## A NOTE ON DIELECTRIC LENSES

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In the following we consider dielectric lenses with spherical or cylindrical symmetry, in which the index of refraction N is a function of the distance r from the center of the sphere or from the axis of the cylinder. Only the geometrical properties of optical ray paths are investigated; amplitude, phase and polarization of the electromagnetic wave are neglected. In the spherical case, the problem always reduces to the consideration of ray paths in a plane passing through the center of the sphere; in the cylindrical case, we shall limit ourselves to the case of rays lying in a plane perpendicular to the cylinder axis.

The following assumptions are made:

1) the radius of the sphere, or of the cylinder, is equal to unity;
2) the index of refraction $N(r)$ of the dielectric material relative to the surrounding medium is finite, except possibly at $r=0$, and $N(1)=1$;
3) $\mathcal{N}(r)$ is continuous with its first derivative in $1 / r \cdots 1$.

The geometry of the problem is the same for both spherical and cylindrical lenses, and is illustrated in Fig. 1. An optical ray enters the lens at $P_{1}$ with an angle of incidence $\alpha$, it is smoothly deviated along the path $P_{1} P_{2}$, and leaves the lens a: $\mathrm{P}_{2}$. Let us indicate by R the optical length of the path $\mathrm{P}_{1} \mathrm{P}_{2}$, by $\theta$ its angular extension as seen from the center $r=0$, and by $\delta$ the deviation of the ray at $P_{2}$ from the direction of incidence; it is:

$$
\begin{equation*}
\delta=\theta+2 \alpha-\pi . \tag{i}
\end{equation*}
$$



Following the usual procedure (see e.g. Toraldo di Francia, 1957 and Huynen, 1958), we set

$$
\begin{equation*}
r^{2} N^{2}=1-\xi^{2}, \tag{2}
\end{equation*}
$$

and introduce a new function $f(\xi)$ satisfying the relation:

$$
\begin{equation*}
2 \mathrm{~N}^{2} \mathrm{r} \mathrm{dr}=-\mathrm{f}(\xi) \mathrm{d} \xi . \tag{3}
\end{equation*}
$$

Then it is:

$$
\begin{align*}
& R=\int_{0}^{\cos \alpha} \frac{\mathrm{f}(\xi) \mathrm{d} \xi}{\sqrt{\cos ^{2} \alpha-\xi^{2}}},  \tag{4}\\
& \theta=\sin \alpha \int_{0}^{\cos \alpha} \frac{\mathrm{f}(\xi) \mathrm{d} \xi}{\left(1-\xi^{2}\right) \sqrt{\cos ^{2} \alpha-\xi^{2}}},  \tag{5}\\
& \ln r=-\frac{1}{2} \int_{0}^{\xi} \frac{\mathrm{f}(\eta) \mathrm{d} \eta}{1-\eta^{2}} \tag{6}
\end{align*}
$$

Relations (2) and (6) give $N$ as a function of $r$, in parametric form.
Formulas (4), (5) and (6) have been employed by various authors. Huynen (1958) has discussed the case in which

$$
\begin{equation*}
f(\xi)=a_{0}+a_{i} \xi \tag{7}
\end{equation*}
$$

where $a_{0}$ and $a_{1}$ are constants.
In this note, the expressions for $R, \theta$ and $\ln r$ are derived for the case in which $f(\xi)$ is an analytic function of $\xi$ in a neighborhood of $\xi=0$. It is then pointed out that restrictions have to be placed on the coefficients of the power series representing $f(\xi)$, if one wants to have solutions with physical significance. In particular, the limitations on $a_{o}$ and $a_{1}$ for the simple case ( 7 ) are investigated in detail.


Let us split $\mathrm{f}(\xi)$ into its even and odd components:

$$
\begin{equation*}
f(\xi)=\mathbf{f}_{\mathbf{e}}(\xi)+\mathbf{f}_{\mathbf{o}}(\xi) \tag{8}
\end{equation*}
$$

where:

$$
\begin{equation*}
\mathrm{f}_{\mathrm{e}}(\xi)=\frac{\mathrm{f}(\xi)+\mathrm{f}(-\xi)}{2}, \quad f_{0}(\xi)=\frac{\mathrm{f}(\xi)-\mathrm{f}(-\xi)}{2}, \tag{9}
\end{equation*}
$$

Assume that for the range of values of $\xi$ of interest to us, $f_{e}$ and $f_{0}$ may be represented by the uniformly convergent power series:

$$
\begin{equation*}
f_{e}(\xi)=\sum_{m=0}^{\infty} a_{2 m^{2}} \xi^{2 m}, \quad f_{o}(\xi)=\sum_{m=0}^{\infty} a_{2 m+1} \xi^{2 m+1} \tag{10}
\end{equation*}
$$

where $a_{2 m}$ and $a_{2 m+1}$ are constants.
Substituting expansions (10) into relations (4), (5) and (6) and integrating term by term, it is found that

$$
\begin{align*}
& R=\frac{\pi}{2}\left\{a_{0}+\sum_{m=1}^{\infty} \frac{(2 m-1)!!}{m!2^{m}} a_{2 m}(\cos \alpha)^{2 m}\right\}+ \\
& +\sum_{m=0}^{\infty} a_{2 m+1}(\cos \alpha)^{2 m+1} \sum_{h=0}^{m} \frac{1(-1)^{h}}{2 h+1}\binom{m}{h},  \tag{1i}\\
& \theta=\frac{\pi}{2} a_{0}+\left(\frac{\pi}{2}-\alpha\right) a_{1}+\frac{\pi}{2} \sum_{m=1}^{\infty} \frac{a_{2 m}(\cos \alpha)^{2 m}}{\sum_{k=0}^{m}\left(\sum_{k}^{m}\right)\left(-\sin ^{2} \alpha\right)^{k}}\left\{1+\frac{1}{(m-1)!2^{m-1} \sin \alpha} x\right. \\
& \left.x \sum_{h=0}^{m-1}(2 h-1)!!(2 m-2 h-3)!!\sum_{\ell=1}^{m-h}\left(\frac{m}{h+\ell}\right)\left(-\sin ^{2} \alpha\right)^{\ell}\right\}+
\end{align*}
$$

$$
\begin{align*}
&+\sum_{m=1}^{\infty} a_{2 m+1}(\cos \alpha)^{2 m}\left\{\left(\frac{\pi}{2}-\alpha\right) \sum_{h=0}^{m}\binom{m}{h}(\tan \alpha)^{2 m-2 h}-\right. \\
&\left.-\sum_{h=0}^{m-1} \sum_{l=1}^{m-h}\binom{m}{h} \frac{(-1)^{m-h-l}}{2(m-h-l)+1}(\tan \alpha)^{2 l-1}\right\},  \tag{12}\\
& \ln r^{4}=a_{o} \ln \left|\frac{1-\xi}{1+\xi}\right|+a_{1} \ln \left(1-\xi^{2}\right)+\sum_{m=1}^{\infty} a_{2 m}\left\{\ln \left|\frac{1-\xi}{1+\xi}\right|+2 \sum_{h=1}^{m} \frac{\xi^{2 h-1}}{2 h-1}\right\}+ \\
&+\sum_{m=1}^{\infty} a_{2 m+1}\left\{\ln \left(1-\xi^{2}\right)+2 \sum_{h=1}^{m} \frac{\xi^{2 h}}{2 h}\right\}, \tag{13}
\end{align*}
$$

where

$$
(2 h-1)!!=1 \times 3 \times 5 x \ldots x(2 h-1)
$$

is the semi-factorial of ( $2 \mathrm{~h}-1$ ) (in particular $(-1):!=1$ ).
Huynen (1958) derived an expression equivalent to (13), for the case in which $f(\xi)$ is a polynomial of degree $n$ in $\xi$; he also gave the first few terms of expansions (11) and (12).

The coefficients $\mathrm{a}_{2 \mathrm{~m}}$ and $\mathrm{a}_{2 \mathrm{~m}+1}$ cannot be arbitrarily chosen; in fact, the angle $\theta$ must obviously be positive for the entire range $0 \leqslant \alpha<\frac{\pi}{2}$. Suppose that $f(\xi)$ is a polynomial of degree $n$ in $\xi$, then the fundamental limitation on the choice of the coefficients is:

$$
\begin{equation*}
\theta\left(a_{0}, a_{1}, \ldots, a_{n} ; \boldsymbol{\alpha}\right)>0, \text { for all } 0 \leqslant a<\frac{\pi}{2}, \tag{14}
\end{equation*}
$$

i. e. the representative point ( $a_{0}, a_{1}, \ldots, a_{n}$ ) must belong to a certain region of the ( $n+1$ )-dimensional space ( $a_{0}, a_{1}, \ldots, a_{n}$ ).

From formulas (2) and (3) it is seen that the relationship between $N$ and $r$ remains unchanged when both $\xi$ and $f(\xi)$ change sign, i.e. when $\xi$ and all the coefficients $\mathrm{a}_{2 \mathrm{~m}}$ change sign (see also formula (13)). The ambiguity that thus arises in the choice of the representative point ( $a_{0}, a_{1}, \ldots$ ) for a given lens $\mathrm{N}=\mathrm{N}(\mathrm{r})$ is eliminated by requiring that inequality (14) be satisfied.

In order to elucidate this concept, let us examine in detail the case of formula (7), for which relation (12) reduces to

$$
\begin{equation*}
\theta=\frac{\pi}{2} \mathrm{a}_{\mathrm{o}}+\left(\frac{\pi}{2}-\alpha\right) \mathrm{a}_{1} \tag{15}
\end{equation*}
$$

then relation (14) gives:

$$
\begin{equation*}
a_{0}+a_{1}>0, \quad a_{0} \geq 0 \tag{16}
\end{equation*}
$$

and therefore the representative point ( $a_{0}, a_{1}$ ) must belong to the shaded region of Fig. 2.

If we also require that $N(0)$ be finite and non-zero and that $(d N / d r)_{r=0}=0$, then the representative point must belong either to the straight line DGF for which

$$
\begin{equation*}
a_{0}+a_{1}=2, \quad N(0)=4^{a_{0} / 4}, \tag{17}
\end{equation*}
$$

or to the straight line DS for which

$$
\begin{equation*}
a_{1}-a_{o}=2, N(0)=4^{-a_{0} / 4} \tag{18}
\end{equation*}
$$

In Fig. 2, the point $D(0,2)$ corresponds to the free space lens $(N=1, \delta=0)$, the point $G(1,1)$ to the Luneberg lens ( $N=\sqrt{2-\mathrm{r}^{2}}$; Luneberg, 1944) and the point $F(2,0)$ to Maxwell's fish eye ( $\mathrm{N}=2 /\left(1+\mathrm{r}^{2}\right)$ ), while the point $\mathrm{H}(2,2)$ represents
the isotropic lens $(N=\sqrt{(2-\mathrm{r}) / \mathrm{r}}, \delta=\pi$; see e.g. Eaton, 1953) .
Let us now impose the further restriction that the optical rays make less than one complete turn around the origin, i.e. that $\theta<2 \pi$; then the representative points $\left(a_{0}, a_{1}\right)$ cannot be chosen outside the rhomboid $0 A B_{0} C$ of Fig. 3. The permissable points of Fig. 2, which are external to the rhomboid $0 \mathrm{AB}_{0} \mathrm{C}$ of Fig. 3 correspond to the so-called higher-order lenses, which were first considered by Stettler (1955).

If we require that all incident rays make at least $\boldsymbol{l}$, but less than $(\boldsymbol{\ell}+1)$, complete turns around the origin before leaving the lens ( $\boldsymbol{\ell}$ is any positive integer), then $2 \pi \boldsymbol{l} \leqslant \theta<2 \pi(\boldsymbol{l}+1)$, and therefore the representative point ( $\mathrm{a}_{\mathrm{o}}, \mathrm{a}_{1}$ ) must belong to the rhomboid ${ }^{B} \ell-1^{A} \boldsymbol{l}^{\mathrm{B}} \boldsymbol{l}^{\mathrm{C}} \boldsymbol{\ell}$, which is obtained by shifting $0 \mathrm{AB} \mathrm{O}_{0}$, an amount $4 \ell$ along the positive a ${ }_{0}$ axis (see Fig. 3).

That portion of the permissible region of Fig. 2 which is not covered by the rhomboids of Fig. 3 represents lenses for which the number of complete turns of the optical ray around the origin may be changed by varying the angle $\alpha$ of incidence.

The investigation that, we developed for the simple case of formula (7) could be repeated for the more complicated cases in which $f(\xi)$ is a polynomial of degree $n=2,3$, etc. In the çase $n \square 2$, the angle $\theta$ is given by the relation:

$$
\begin{equation*}
\theta=\frac{\pi}{2} a_{0}+\left(\frac{\pi}{2}-\alpha\right) a_{1}+\frac{\pi}{2}(1-\sin \alpha) a_{2} \tag{19}
\end{equation*}
$$

which follows from (12).

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## Captions for Figures

> 1 Geometry for the Optical Ray Path
> 2 The Permissible Domain in the ( $a_{0}, a_{1}$ ) Plane
> $3 \quad$ Fundamental Lenses (shaded area) and Higher-Order Lenses




