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### ANALOGIES BETWEEN EM AND ACOUSTIC WAVES\*

By

H. S. Hayre and G. Vroulis

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#### Department of Electrical Engineering Wave Propagation Laboratories

UNIVERSITY OF HOUSTON Cullen College of Engineering 3801 Cullen Boulevard Houston, Texas 77004

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#### Introduction

The purpose of this report is to summarize the results of a considerable amount of work in the field of acoustic simulation of radar return so that the reader may be readily confident about the validity of this inexpensive laboratory tool.

Acoustic simulation readily permits experimental verification of scatter theories which would otherwise be costly and time consuming.

#### Wave Equations

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Flectromagnetic	Acoustic
$\nabla \mathbf{x} \mathbf{E} = -\mu \frac{\partial \mathbf{H}}{\partial \mathbf{t}}$	$\nabla P = -\beta_1 \frac{\partial u}{\partial t} ,$
$\nabla x H = \epsilon \frac{\partial E}{\partial t}$	$\nabla \cdot \mathbf{u} = -\mathbf{K}_{l} \frac{\partial \mathbf{P}}{\partial t}$

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for plane sinusoidal waves in the x-direction:

$\frac{dEy}{dx} = -i\omega\mu Hz$	1	$\frac{dP}{dx} = -i\omega Qun$	
$\frac{dHz}{dx} = -i\omega_{\rm F}Ey$	1	$\frac{\mathrm{d}\mathbf{u}_{\mathbf{X}}}{\mathrm{d}\mathbf{x}} = -\mathrm{i}\omega K_{l} P$	

taking the divergence of (1) and the substitution of (2)

$\nabla^2_{\rm E} = \mu \in \frac{\partial^2_{\rm E}}{\partial t^2}$	$\nabla^2 \mathbf{P} = \rho_l \kappa_l \frac{\partial^2 \mathbf{P}}{\partial t^2}$
$\nabla^2_{\rm H} = \hbar \epsilon \frac{\partial^2_{\rm H}}{\partial t^2}$	$\nabla^2_{u} = \rho_t \kappa_t \frac{\partial^2_{u}}{\partial t^2}$

where

E = electric field vector	P = pressure field scalar
H = magnetic field vector	u = particle velocity vector
$\epsilon$ = dielectric constant	$\rho_t$ = density of the medium
$\mu$ = permeability	K <sub>t</sub> = compressibility of medium
Simulation of electromagnetic wa	ves using acoustic waves is always
feasible when their respective b	oundary conditions are nearly the

same.

BOUNDARY C	ONDITIONS
Electromagnetic $\overline{2}$ $\overline{4}$ $\overline{6}$	Acoustic $n$ $P_1, P_2, P_3$ $P_2, P_3, P_4$ $P_2, P_3, P_4$ $P_2, P_3, P_4$
Most General Form	Most General Form
$   \vec{n} \times (\vec{E}_1 - \vec{E}_2) = 2 $ (1) $   \vec{n} \times (\vec{H}_1 - \vec{H}_2) = 3 $ (2)	$P_{1} = P_{2} $ (1) $\bar{n} \cdot (\bar{U}_{1} - \bar{U}_{2}) = 0 $ (2)
When:	<u>When</u> :
$M_1/M_2$ = Dielectric/Dielectric Q = 0 $J_s = 0$	$M_1/M_2 = \text{Liquid/Liquid} \qquad P_1 = P_2$ $\vec{n} \cdot (\vec{v}_1 - \vec{v}_2) = 0$
$M_{1}/M_{2} = \text{Dielectric/Perf. Cond. } Q \neq 0$ $6 = co  \tilde{E}_{2} = \tilde{H}_{2} = 0 \qquad J_{s} = 0$	$M_{1}/M_{2} = \underset{\text{Rigid}}{\text{Liquid/Solid}} P_{1} = P_{2} = 0$ $\overline{n} \cdot (\overline{U}_{1} - \overline{U}_{2}) = 0$
$M_1/M_2 = Dielectric/Imp. Cond. Q \neq 0$ $\delta = finite$ $J_2 = 0$	$M_1/M_2$ = Liquid/Semielastic $P_1 = P_2 = 0$ Solid $U_{total} = U_t = 2U_{incident}$
Perfect $M_1/M_2 = Conductor/Imp. Cond.  Q \neq 0$ $\overline{E}_1 = \overline{H}_2 = 0$ $J_s \neq 0$	$M_{1}/M_{2} = \begin{array}{c} \text{Solid/Elastic} & P_{1} = P_{2} = 0\\ \text{Rigid Solid} & \\ \overline{n} \cdot (\overline{U}_{1} - \overline{U}_{2}) = 0 \end{array}$
Conductors	Solid Surfaces
Perfect Conductor: o .> co	Rigid Surface: $\mu \Rightarrow \infty$
Imperfect Conductor: $\sigma = finite$	Elastic Surface: $\mu$ = finite
Insulator: $\sigma = 0$	Liquid Surface: $\int t = 0$

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For the EM and, Acoustic field  $\overline{n}$  is a unit vector normal to the surface. The equations state that the tangential components of  $\overline{E}$  and  $\overline{H}$  are continuous across the boundary as are the pressure P and the normal component of the particle velocity  $\overline{}$ .

Boundary conditions at a perfect conductor require the tangential electric field to be zero and the tangential magnetic field to be two times the incident field. On the other hand at a perfectly elastic wall (pressure release surface) the dynamic pressure is zero and the normal component of the total particle velocity is twice the normal component of the incident particle velocity. In each of these situations there is no wave propagation beyond the interface.

When a plane electromagnetic wave is normally incident on a perfectly conducting plane surface, the field components are both parallel to the surface and the electric field component can be made equivalent to either the pressure of the particle velocity in the acoustic wave using a perfectly elastic boundary in the first case and a perfectly rigid boundary in the second.







For nearly smooth surfaces, the surface characteristic constant 1 B = 0, and (3.15) gives the scattering coefficient. This result compares very closely with published results [Nielson, 1960] for new ice as shown in table 2

For rough (not *namely* smooth) surfaces, (3.14) describes the relationship of the scattering coefficient  $\sigma_0$  and other variables such as the angle of incidence  $\theta$  wavelength  $\lambda$ , standard deviation  $\sigma$  and surface covariance constant B, etc. Two curves of the scat-tering coefficient  $\sigma_0$  versus  $\theta$  for each of the three values of  $\lambda/B$ , 0.1, 0.5, and 1.0 for  $\sigma/\lambda$  equal to 0.05, and 0.1 are shown in figure 4. It may be noticed that as the surface becomes rougher, or as  $\lambda/B$ increases for a specified  $\lambda$ , the scattering coefficient curve becomes flatter, showing the relative importance of the contribution of the power return from the surface at angles other than those near zero. As expected, when the surface becomes smoother or  $1_1B$  decreases, the received power seems to come primarily from near-zero angles. These curves are quite similar to those recently published [Campbell, 1959; Dye. 1959; Edison, 1960] The experimental data [Nielson, 1960] on desert and new ice also seems to follow the pattern of these theoretical curves described above.

The scattering coefficient  $(\sigma_n)$  for nearly smooth surfaces is inversely proportional to the wavelength, but varies directly with  $(\sigma^2)$ ,  $(\theta \cot^{\dagger} \theta)$  and 1/B, where  $\sigma$ ,  $\theta$ , B are standard deviation, angle of incidence, and the terrain characteristic constant respectively. For rough surfaces it has a negative exponential  $\sigma^2 \cos^2 \theta$ 

factor, where the exponent is made up of  $\frac{\sigma^2 \cos^2 \theta}{\lambda^2}$ 

times a constant. The surface characteristic constants B and  $\sigma$  can be calculated from the radar return data. Although approximate, the theoretical results agree well with the experimental data; and therefore, suggest the usefulness of the approach. The application of these results may be extended to the moon-echo data, with proper corrections for Faraday and liberation effects, etc. This investigation has established that for near-vertical incidence, the normalized autocovariance for the terrain elevation is more often of the exponential form exp (-|r|/B) rather than the Gaussian form, exp  $(-r^2/B)$ . The former may well be more appropriate for finer extrain irregularities than those considered in this



FIGURE 4. Southering coefficient vorum the angle of uncidence.

Comparison of theoretical versus experimental scattering coefficient

(Normalized)							
<del>6</del> 0	on Theoretical	🐢 Experimental					
30 -40 50 60 70	1 000 - 0 291 - 0 381 - 0 29 - 0 98 - 0 9	1 000 0.308 089 .464 . 609					

H S HAYRE & R.K. HOORE. Theoretical Scattering Coeffor <u>hear Vertical Incidence From Contour Maps</u>, Journal of Research Vol. B5D, Sept-1961 pp 431.

The distinction between beam width

and pulse-length limiting of the illuminated area is a function of altitude and is given by

$$1 + \frac{v \cdot r}{2h} = \sec \theta_{0} \tag{6-1}$$

where

Relative Mean Pressure Amplitude

V is the velocity of propagation,

7 is the pulse width,

h is the altitude, and

Og is the effective half-angle of the antenna pattern.



Signal ve Altitide over Smooth Surface (EDISON, 1961)



Mean Scatter-Power Signal



Lighter de Mary e





Angle of incidence





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Angle of Incidence, 0

(EDISON, 1961)

Terrain	Target Base	Sand Particle size, wavelengths	Distance Between Particles, Wavelengths
Woods	Plywood	1-2	0 - 1/2
Parmland	à	1-2	1 - 5
Desert	•		* * * * * *
Cities	" (buildings) <sup>®</sup>	$\frac{1}{7}$	1 - 5
Water (smooth)	galv. steel		3 - 5
Water (rough)	• •	$\frac{1}{2}$	1 - 2
Mountains	" " (shaped)	$\frac{1}{2}$	1 - 2

TARGET RECOMMENDATIONS (EDISON 1961)

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<sup>a</sup>Buildings are pine blocks cut to size.

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<sup>b</sup>Steel can be formed into appropriate contours.

It should be observed that the slope of the radar backscattering cross section curves is important in modeling practice. The absolute level of the curves can be increased or decreased by proper scaling.



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Median scattering curves for a relatively smooth surface on the Salton Sea in California. The air over the target was quite calm at the time of the flights. (EDISON, 59)







(EDISON, 1959)



buildings were built of brick, flat roofed, and several stories tall. (EDISON, 1959)



(LOISON (59)



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A COUSTIC SCATTERING FRON THE SEA



Geophysical Research, Vol. 70, No. 16, (August, 1965), pp. 3831-3839.

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Acoustics (Lig/Solid)	EMW (General)
$c^2 \qquad \frac{\lambda + 2\mu}{3}$	$\frac{1}{\varepsilon \omega}$
<pre>C = Velocity of Propagation     (longitudinal)</pre>	
$b^2 = (shear) \mu/f$	
$v^{2} + k^{2} = 0$	$\overline{\nabla^2 E} + k^2 E = 0$
$\overrightarrow{V} = \nabla \phi + \nabla X \Psi$	$\vec{E} = -\nabla\phi + \frac{\partial A}{\partial t}$
SNELL'S LAW	
$k_1 \sin \phi_1 = k_1 \sin \phi_{11} =$	$k_1 \sin \phi = k_{11} \sin \phi_{11} = k_2 \sin \phi_2$
K <sub>2</sub> siny <sub>2</sub>	
$Z_i = fc \sec \phi_i  i = 1$	$\sqrt{\frac{\mu}{\varepsilon}} \sec \phi \qquad \text{Vertical} \\ \text{Polarization}$
$z_{sh} = z_t$ fb sec y	$\sqrt{\frac{\mu}{\varepsilon}} \cos \phi \qquad \text{Horizontal} \\ \text{Polarization}$
Reflection Coefficient (longitudinal) $V = \frac{Z_{tot} - Z_{i}}{Z_{tot} + Z_{i}}$ i = 2	$R = \frac{z_2 - z_1}{z_2 + z_1}$
Transmission Coefficient W = $\frac{1}{2} \frac{2(Z_1 \cos 2\gamma_2)}{Z_{tot} + Z_1}$ (longitudinal)	$T = \frac{2Z_2}{Z_1 + Z_2}$
i = 2	
Transmission Coefficient = $\int_{1}^{2} \frac{2(Z_{t}\cos\gamma_{2})}{Z_{tot} + Z_{i}}$ i (shear)	L = 2
$z_{tot} = z_1 \cos^2 2\gamma_2 + z_t s$	$\sin^2 2\gamma_2$
$z_i = f_i C_i / \cos \theta_i$ , $z_t = f_i$	2 <sup>b</sup> 2/cosy2

#### COMPARISON OF REFLECTION TRANSMISSION COEFFICIENTS

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 $\mu$ ,  $\lambda$  are Lame constants

## AFPROXIMATE COUNT OF RCS MCS PEAKS ( 1-1121 N. NO-PAT SCAT PACILITY PRODUCT (1013)

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