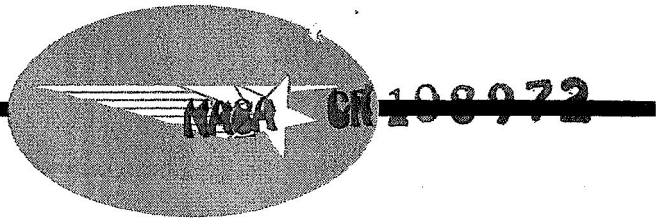


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PROPELLANT SLOSH
COUPLING WITH BENDING

INTERIM REPORT

June 1969

Lockheed

MISSILES & SPACE COMPANY

A GROUP DIVISION OF LOCKHEED AIRCRAFT CORPORATION

SUNNYVALE, CALIFORNIA

LOCKHEED MISSILES & SPACE COMPANY
HUNTSVILLE RESEARCH & ENGINEERING CENTER
HUNTSVILLE RESEARCH PARK
4800 BRADFORD BLVD., HUNTSVILLE, ALABAMA

PROPELLANT SLOSH
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Contract NAS8-21485

by

G. C. Feng
M. L. Pearson

CASE FILE
COPY

APPROVED BY:

A. M. Ellison

A. M. Ellison, Supervisor
Structural Engineering Section

Donald M. McDonald

D. McDonald, Manager
Structures & Mechanics Dept.

J. S. Farrior

J. S. Farrior
Resident Director

FOREWORD

This document presents an interim report of a research program performed by the Lockheed Missiles & Space Company, Huntsville Research & Engineering Center (Lockheed/Huntsville), while under contract to the National Aeronautics & Space Administration, Marshall Space Flight Center (MSFC), Contract NAS8-21485. This report summarizes the derivation and computational procedures of a new method for studying the vibrational characteristics of a large liquid-propellant space vehicle.

Technical coordinator of the contract was Mr. Harry J. Buchanan, Aero-Astroynamics Laboratory, NASA/MSFC.

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SUMMARY

A new approach is used to study the vibrational characteristics of a large liquid-propellant space vehicle. This approach permits taking the higher slosh modes into account and using the dynamic behavior of liquid propellant contained in a tank as determined experimentally. The developed program will provide a set of system bending modes including the effect of liquid propellant in the vehicle. Lateral force distribution coefficients due to the dynamics of the liquid propellant can be computed.

Lagrange's equation is employed to formulate a coupled elastic and fluid problem. The vehicle is modeled as a series of non-uniform beams interconnected by elastic interstages. The engines of each stage may be represented as branch beams attached to the lower ends of the beams. Generalized coordinates of the system are beam end displacements, coefficients of beam deflection functions, branch beam deflection angles and coefficients of slosh modes. The kinetic and potential energies associated with the hardware of a vehicle are computed by summation along its longitudinal axis. The energies associated with liquid propellant are obtained by performing volume integration over the tank volumes occupied by the propellant.

In this study, a program called SLOSH was developed. This program computes the mass and stiffness matrices of the system associated with the liquid propellant and provides the lateral force distribution coefficients due to the dynamics of the propellant. A Lockheed/Huntsville-developed bending program (Ref. 1) was modified to a two-dimensional case in order to accommodate the additional slosh modes used in the present model. This program computes the mass and stiffness matrices of the system associated with the hardware of a vehicle. After a combination of the two sets of matrices, the bending program will solve the constructed eigenvalue problem.

A study of the vibrational characteristics of Saturn V during its first-stage flight is included as an example of the new method. A user's guide of the developed digital SLOSH program is also provided.

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NOMENCLATURE

\underline{A}	mass matrix of a system
a_k	k^{th} tank radius at the liquid propellant surface (m)
\underline{B}	stiffness matrix of a system
c_{km}^n	eigenvectors of the n^{th} slosh mode associated with the k^{th} tank (dimensionless)
d_{lk}	distance between lower beam end and tank coordinate system of the k^{th} tank (m)
G_{3k}	distance between beam end and center of mass of the k^{th} tank (m)
$J_1(j_{km} R)$	Bessel-function of the first kind associated with the k^{th} tank
j_{km}	m^{th} root of equation $J_1'(j_k) = 0$
L_i	length of the i^{th} beam (m)
l_k	distance between propellant surface and center of mass of the k^{th} tank (m)
M_{mk}	propellant mass in the first m layers of the k^{th} tank (kg)
N_i	number of fundamental deflection functions of the i^{th} beam
N_k	number of slosh modes of the k^{th} tank
P	potential energy of a system ($\text{kg}\cdot\text{m}^2/\text{sec}^2$)
P_k	potential energy of the propellant contained in the k^{th} tank ($\text{kg}\cdot\text{m}^2/\text{sec}^2$)
\underline{Q}	generalized coordinate vector
\underline{Q}^T	transposed matrix of \underline{Q}

NOMENCLATURE (Continued)

q_i	i^{th} generalized coordinate
T	kinetic energy of a system ($\text{kg}\cdot\text{m}^2/\text{sec}^2$)
T_k	kinetic energy of the propellant contained in the k^{th} tank ($\text{kg}\cdot\text{m}^2/\text{sec}^2$)
u_i^{ℓ}	lower end displacement of the i^{th} beam (m)
u_i^r	upper end displacement of the i^{th} beam (m)
\underline{X}	eigenvector of a system
Y_{ij}	j^{th} fundamental deflector function of the i^{th} beam (dimensionless)

Symbols

α_{2i}	lateral acceleration of the i^{th} beam (m/sec^2)
α_3	longitudinal acceleration of a vehicle (m/sec^2)
η	wave height of liquid propellant (m)
λ_{kn}	eigenvalues of a fluid system (dimensionless)
ω	natural frequencies of a system (rad/sec)
ϕ_k	velocity potential of the propellant contained in the k^{th} tank (m^2/sec^2)
ϕ_{kn}	eigenfunctions of a fluid system (dimensionless)
$\ddot{\psi}_i$	angular acceleration of the i^{th} beam (rad/sec^2)
ρ_k	mass density of the propellant contained in the k^{th} tank (kg/m^3)
ξ_{kn}	n^{th} slosh coefficient of the k^{th} tank (m)
ζ_{ij}	j^{th} beam deflection coefficient of the i^{th} beam (m)

Section 1 INTRODUCTION

To ensure a successful flight of a liquid-propellant space vehicle, the fundamental frequencies of the control system, liquid propellant and the hardware of the vehicle should be designed such that they are fairly widely separated. Hence, the oscillations of a vehicle will not be excited by the function of the control system. In case the vehicle is excited by a forcing function, interaction between propellant sloshing and bending must not present any large amplitude dynamic response.

In order to simulate the dynamic response of a vehicle, it has been traditional to model the vehicle as a non-uniform beam (Ref. 2). Liquid propellant contained in each tank is replaced by a mass-spring-dashpot system attached to the beam. Due to the limitations of computation time on a digital computer and the capacity of a hybrid computer (Ref. 3), only the first slosh modes for some of the propellant tanks can be taken into account. The above assumptions provide a good mathematical model of a vehicle during its early portion of flight. However, when the propellant level becomes relatively low or in case of a shallow tank, the dynamic behavior of liquid propellant cannot be adequately represented by its first mode alone. Therefore, a new mathematical model is needed which includes higher slosh modes and can be computed within the capabilities of a computer.

A new approach for studying the interaction between vehicle bending and propellant sloshing is introduced in this report. Lagrange's equation is used to formulate the problem. A digital computer program which solves a maximum of 60 degrees of freedom was developed. The mass and stiffness matrices of the coupled elastic and fluid system can be accurately calculated. System bending modes with the presence of liquid propellant of a vehicle will

be provided. If a mathematical model for atmospheric flight simulation is needed, the model can be properly defined by taking into account only the first few of these modes. In general, this approach will lead to a smaller set of differential equations than the conventional approach. Consequently, the objectives of the study are to define an accurate model for analyzing the coupling between vehicle bending and propellant sloshing and to present a set of system bending modes for flight simulation.

Section 2
MATHEMATICAL MODEL

Saturn V is used as a typical vehicle in this study. With minor modifications, the presented method and the developed digital computer program may be applied to analyze other liquid-propellant space vehicles. As shown in Fig. 1b, the vehicle may be modeled as a system of four non-uniform beams interconnected by elastic interstages. The engines of each stage may be modeled as branch beams attached to the lower ends of the beams. The deflection of each beam is represented by a linear combination of four fundamental deflection functions. Dynamic behavior of liquid propellant contained in each tank is described by the first one to three slosh modes. Hence, the generalized coordinates of the system are beam end displacements, engine deflection angles, coefficients of beam deflection functions and coefficients of slosh modes.

The hardware mass of the vehicle is distributed along the longitudinal axis of the vehicle. Tank configurations are approximated by simple functions such that volume integrals can be readily performed (see Figs. 2 to 5).

Suppose that \underline{A} , \underline{B} and \underline{Q} are the mass matrix, stiffness matrix and the generalized coordinates vector of the system, respectively. The kinetic energy of the system may be expressed as

$$T = 1/2 \dot{\underline{Q}}^T \underline{A} \dot{\underline{Q}} \quad (2.1)$$

where $\dot{\underline{Q}}^T$ is the transposed matrix of $\dot{\underline{Q}}$ and $\dot{\underline{Q}} \equiv \frac{d\underline{Q}}{dt}$. The potential energy of the system is

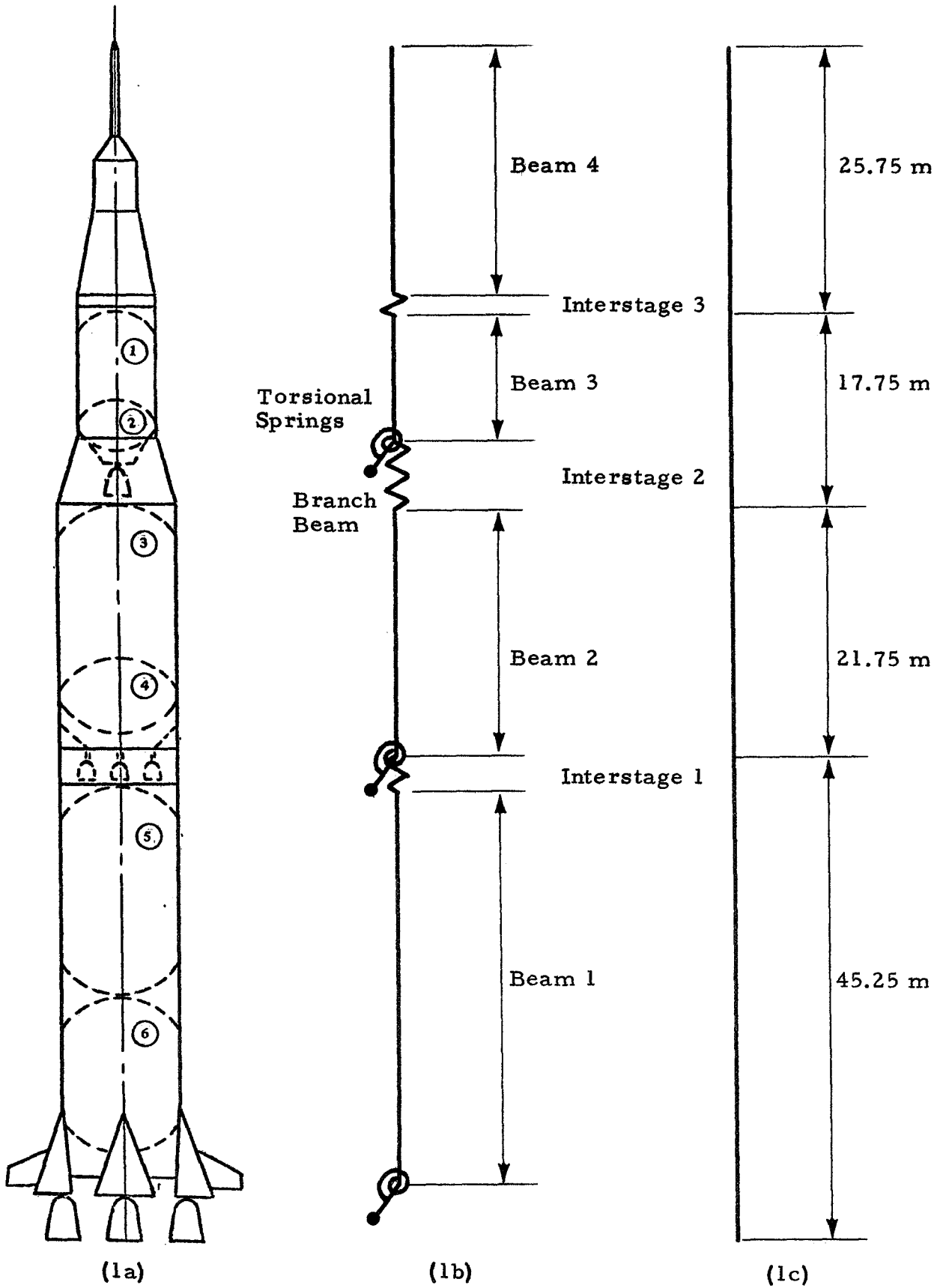


Fig. 1 - Saturn V Vehicle Configuration

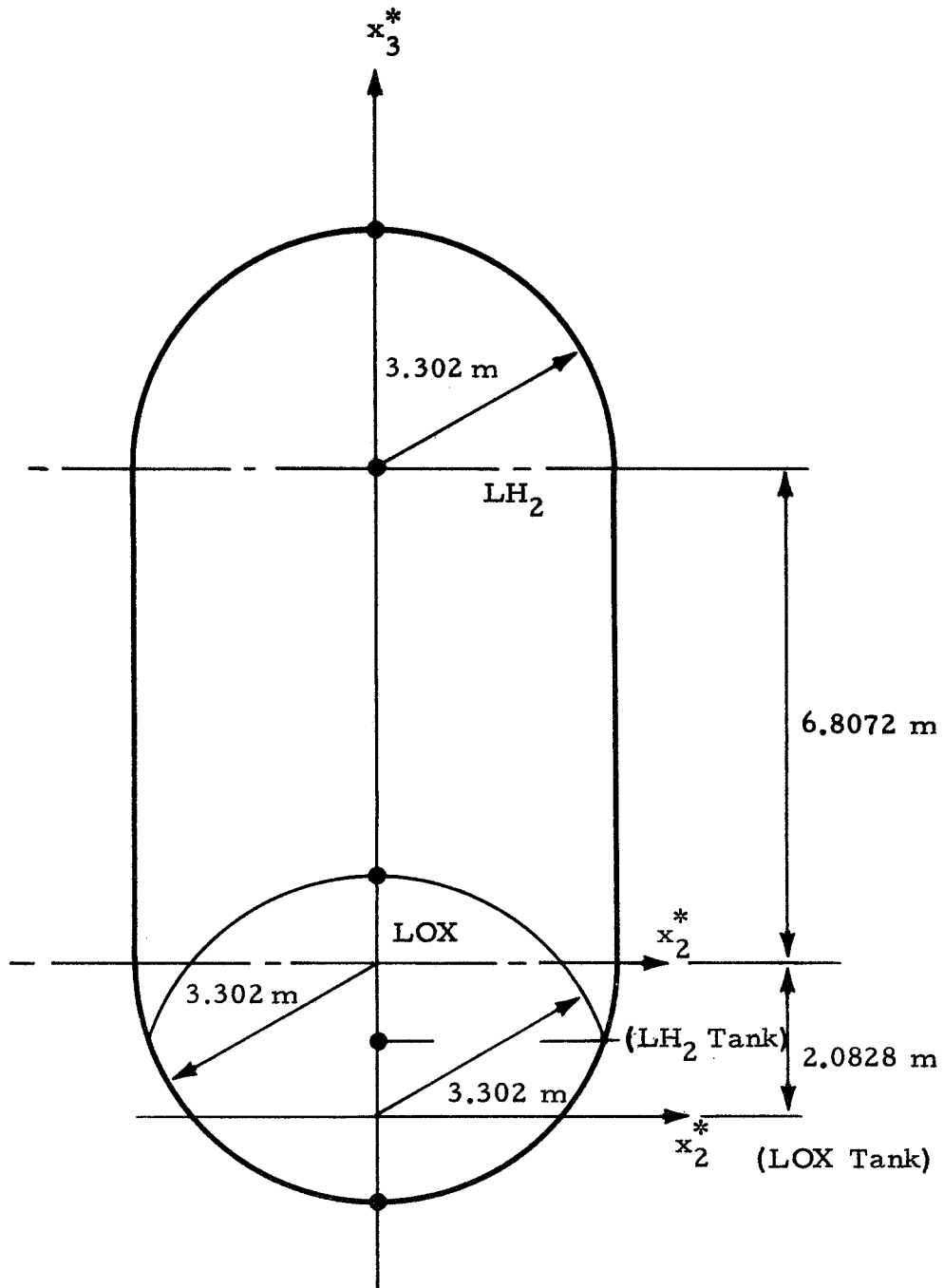


Fig. 2 - S-IVB Tank Configuration

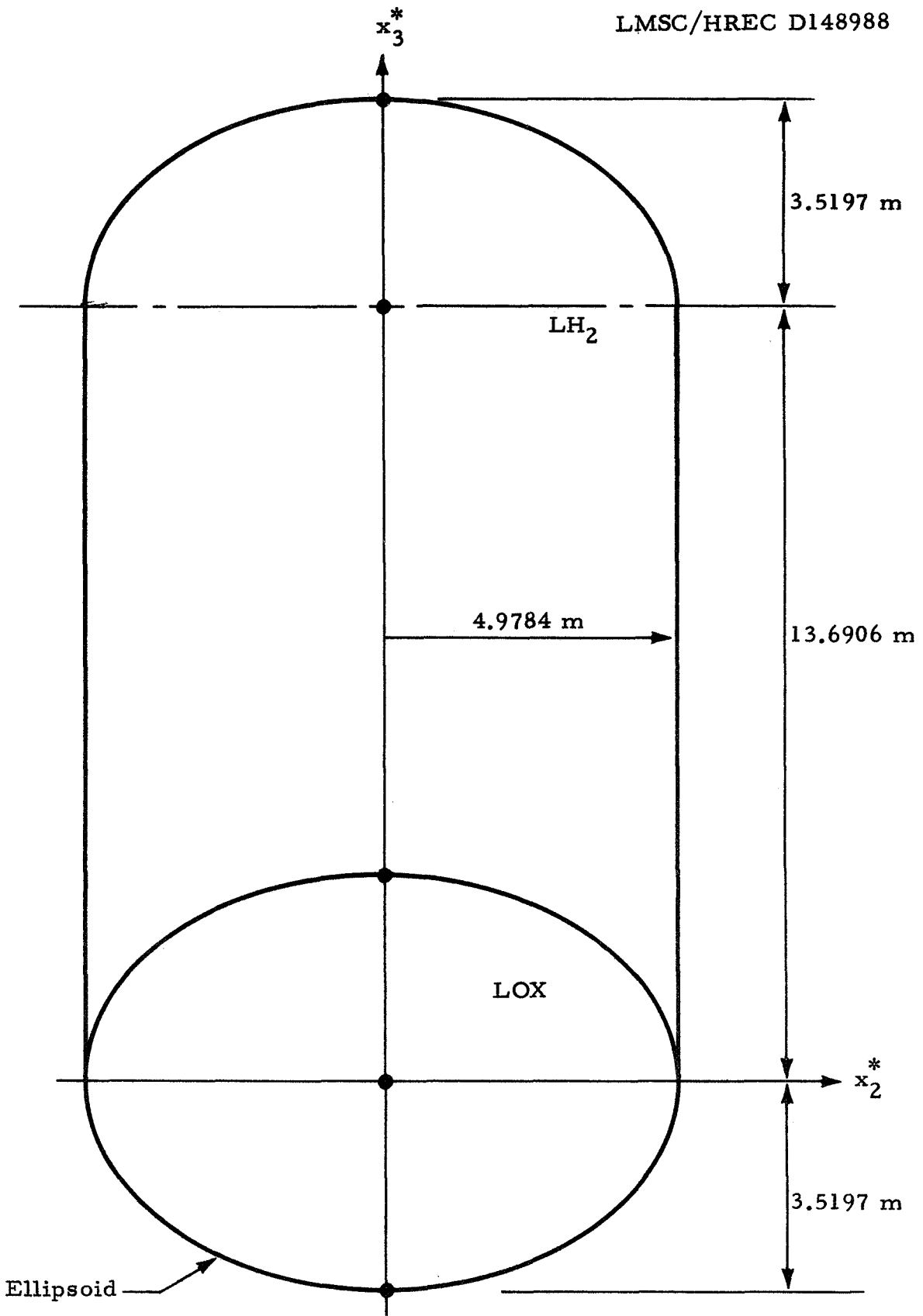


Fig. 3 - S-II Tank Configuration

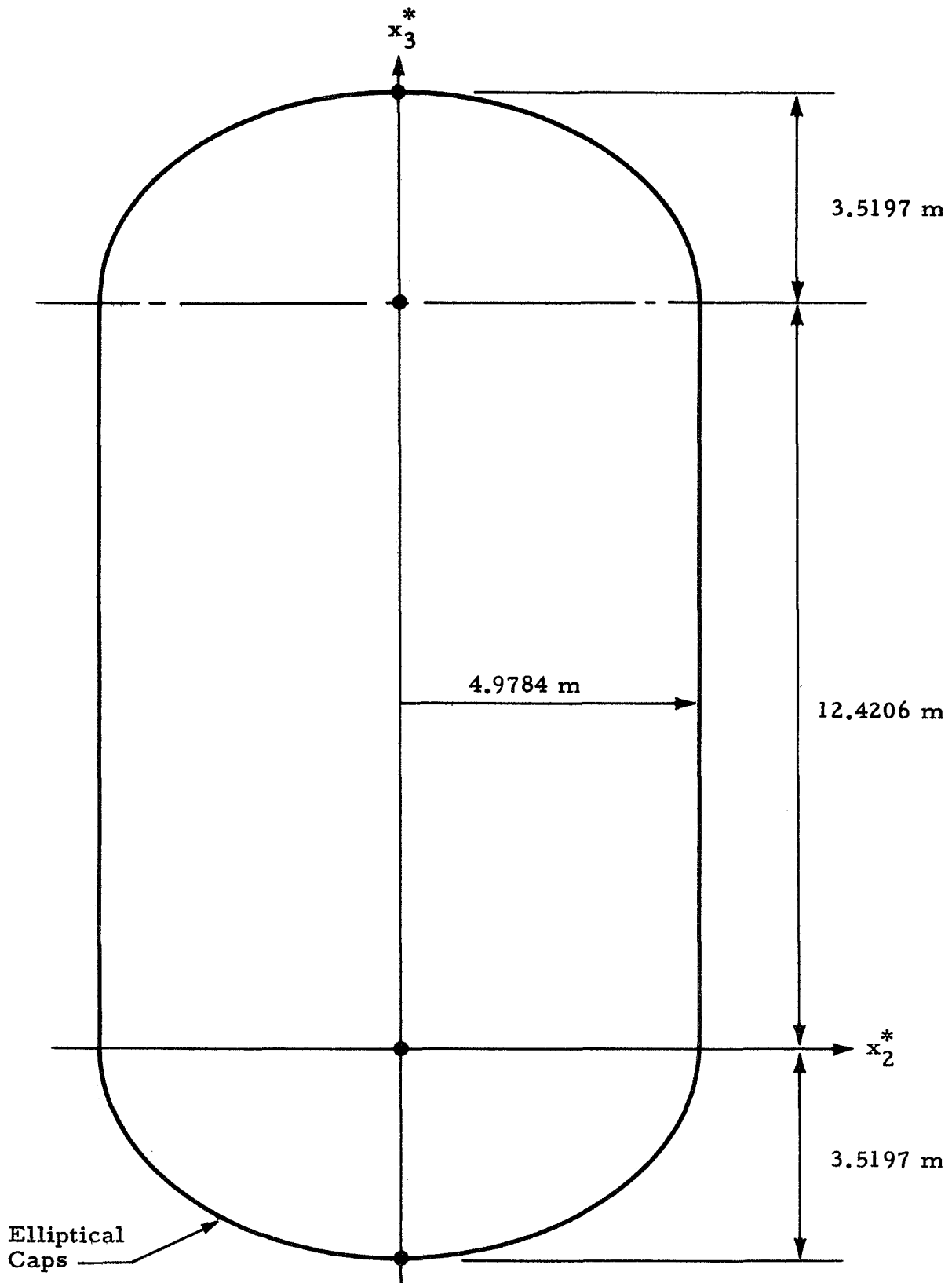


Fig. 4 - S-IC LOX Tank Configuration

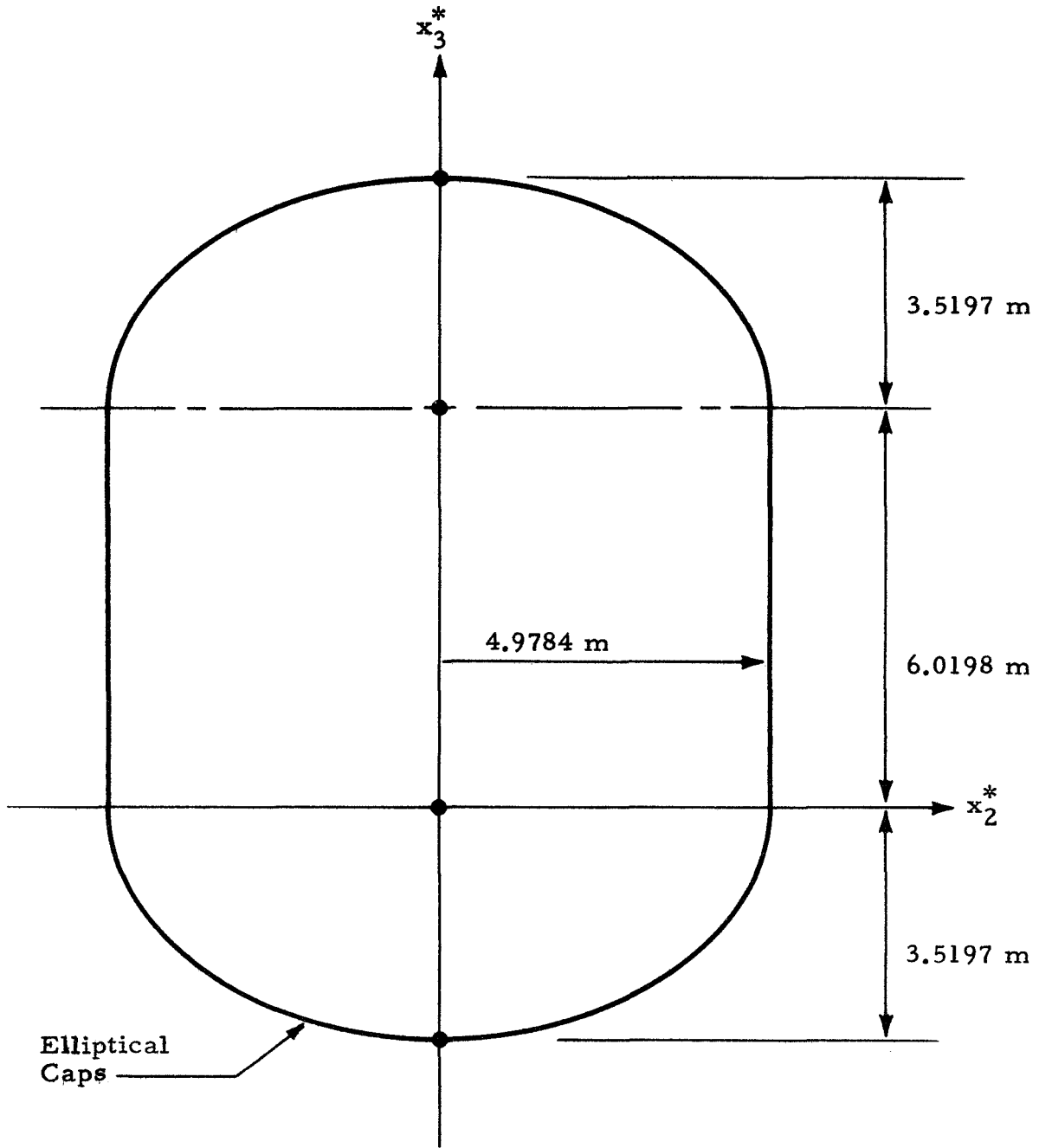


Fig. 5 - S-IC Fuel Tank Configuration

$$\underline{P} = 1/2 \underline{Q}^T \underline{B} \underline{Q} \quad (2.2)$$

For a conservative system, Lagrange's equation is

$$\frac{d}{dt} \left(\frac{\partial T}{\partial \dot{q}_i} \right) + \frac{\partial P}{\partial q_i} = 0 \quad i = 1, 2, \dots, n \quad (2.3)$$

where q_i is the i^{th} element of \underline{Q} . If Eqs. (2.1) and (2.2) are used, Eq. (2.3) becomes

$$\underline{A} \ddot{\underline{Q}} + \underline{B} \underline{Q} = 0 \quad (2.4)$$

The solution of the above equation may be taken as

$$\underline{Q} = \underline{X} \sin \omega t \quad (2.5)$$

where \underline{X} and ω are the eigenvectors and the natural frequencies of a system, respectively. Substituting Eq. (2.5) into Eq. (2.4), one finds

$$(\omega^2 \underline{A} - \underline{B}) \underline{X} = 0 \quad (2.6)$$

Detailed derivations of matrices \underline{A} and \underline{B} are given in Section 3 and the Appendix. Subprograms which compute these matrices are discussed in Section 4. Routines which solve the system of Eq. (2.6) are described in Ref. 1.

Section 3 DERIVATION

Lagrange's equation is used to define a mathematical model for studying the vibrational characteristics of Saturn V. The structure of the vehicle is considered as a series of elastic non-uniform beams interconnected by elastic interstages. The engines of each stage may be represented by a mass which is attached to the beam through a rigid rod and a torsional spring (see Fig. 1b). The vehicle is assumed to be axisymmetric and restricted to plane motion. Liquid propellants contained in the tanks of Saturn V are considered incompressible, inviscid fluids. Furthermore, small oscillations and irrotational flow are assumed.

The kinetic and potential energies of a vehicle are computed in the following manner. Energies associated with the hardware are obtained by integrating along the longitudinal axis of the vehicle. Energies associated with the liquid propellant are computed by performing volume integration over the tank volumes occupied by the propellant. The total energy of a vehicle is represented by the sum of these energies. The kinetic and potential energies of the hardware of a vehicle are defined in Ref. 1. Except that a few notations may differ from those used in this report, the reader will not have any communication difficulty.

As shown in Fig. 6, the kinetic energy of the propellant contained in the k^{th} tank can be expressed as a volume integral

$$T_k = 1/2 \rho_k \int_V \left[v_r^2 + v_\theta^2 + v_z^2 \right] dV \quad (3.1)$$

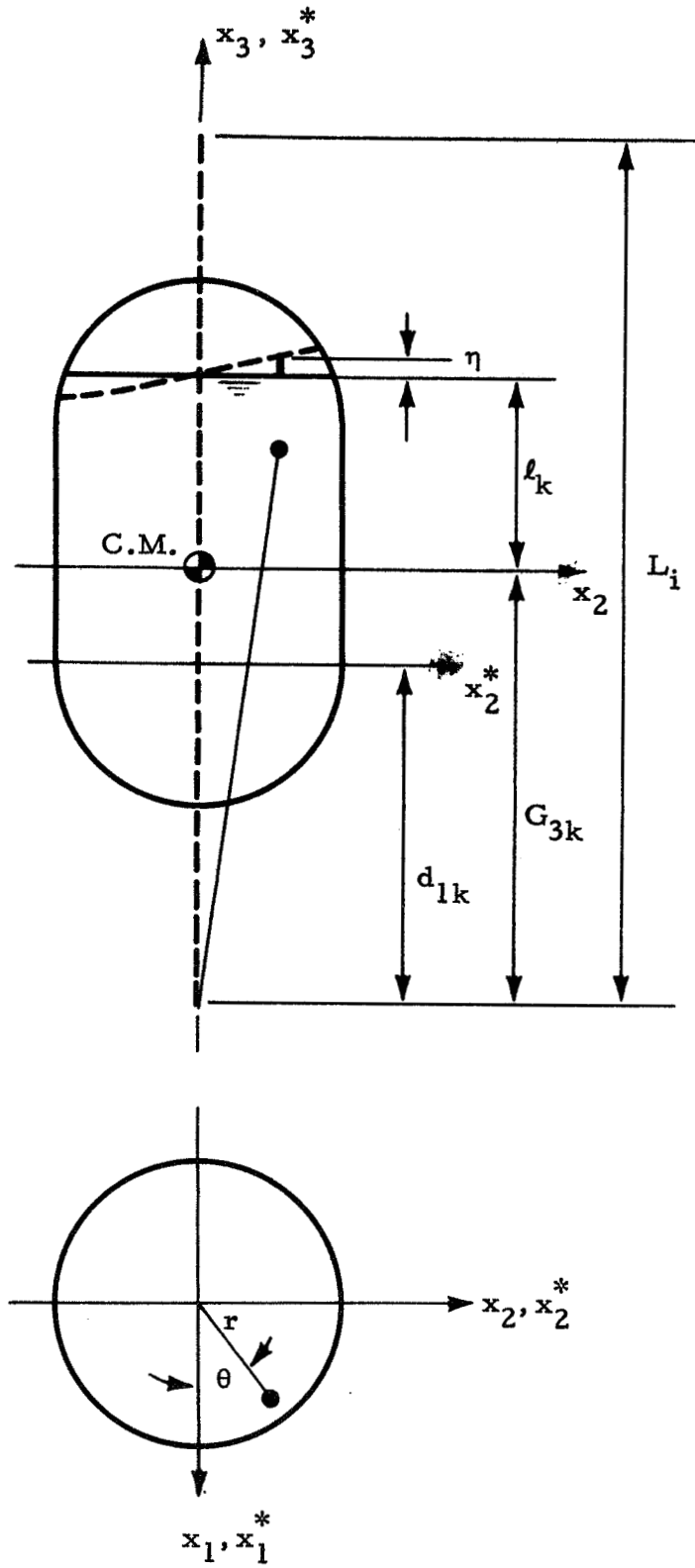


Fig. 6 - Coordinate Systems of k^{th} Tank

where

$$\left\{ \begin{aligned} v_r &= \left[\dot{u}_i^l + \frac{\dot{u}_i^r - \dot{u}_i^l}{L_i} (d_{1k} + x_3^*) + \sum_{j=1}^{N_i} \zeta_{ij} Y_{ij} \right] \sin\theta - \frac{\partial}{\partial r} \int \phi_k dt \\ v_\theta &= \left[\dot{u}_i^l + \frac{\dot{u}_i^r - \dot{u}_i^l}{L_i} (d_{1k} + x_3^*) + \sum_{j=1}^{N_i} \zeta_{ij} Y_{ij} \right] \cos\theta - \frac{1}{r} \frac{\partial}{\partial \theta} \int \phi_k dt \\ v_z &= - \frac{\dot{u}_i^r - \dot{u}_i^l}{L_i} x_2 - \frac{\partial}{\partial x_3} \int \phi_k dt \end{aligned} \right. \quad (3.2)$$

and

$$\phi_k = - \sin\theta \sum_{n=1}^{N_k} \frac{a_k}{\lambda_{kn}} \ddot{\xi}_{kn} \phi_{kn} \quad (3.3)$$

Notations used in the above equations are defined below:

- ρ_k mass density of the propellant contained in the k^{th} tank
- u_i^l lower end displacement of the i^{th} beam
- u_i^r upper end displacement of the i^{th} beam
- L_i length of the i^{th} beam
- d_{1k} distance between lower beam end and tank coordinate system of the k^{th} tank
- N_i number of fundamental deflection functions of the i^{th} beam
- ζ_{ij} j^{th} beam deflection coefficient of the i^{th} beam

- Y_{ij} j^{th} fundamental deflection function of the i^{th} beam
- ϕ_k velocity potential of the propellant contained in the k^{th} tank
- N_k number of slosh modes of the k^{th} tank
- a_k k^{th} tank radius at the liquid propellant surface
- λ_{kn} eigenvalues of a fluid system
- ξ_{kn} n^{th} slosh coefficient of the k^{th} tank
- ϕ_{kn} eigenfunctions of a fluid system

The eigenfunctions ϕ_{kn} of Eq. (3.3) can be chosen in the following form

$$\phi_{kn} = \sum_{m=1}^5 c_{km}^n \left(\frac{r}{a_k}\right)^{2m-1} + \sum_{m=6}^{10} c_{km}^n J_1(j_{km} \frac{r}{a_k}) e^{j_{km} \left(\frac{x_3}{a_k} - \frac{\ell_k}{a_k}\right)} \quad (3.4)$$

where c_{km}^n and $J_1(j_{km} \frac{r}{a_k})$ are the eigenvectors of the n^{th} slosh mode and Bessel function of the first kind associated with the k^{th} tank, respectively. The notation ℓ_k is the distance between propellant surface and center of mass of the k^{th} tank and j_{km} is the m^{th} root of the equation

$$J_1'(j_k) = 0 \quad (3.5)$$

The superscript "prime" of J_1 denotes a differentiation with respect to its argument. The functions of Eq. (3.4) give an excellent solution for liquid contained in an axisymmetric tank with arbitrary height. Substituting Eqs. (3.2) - (3.4) into Eq. (3.1), the kinetic energy T_k may be written in terms of the generalized coordinates u_i^l , u_i^r , ζ_{ij} and ξ_{kn} .

$$\begin{aligned}
 T_k = & - \pi a_k^3 \rho_k \left\{ V_k^{pp} (\dot{u}_i^\ell)^2 + V_k^{pq} \dot{u}_i^\ell \dot{u}_i^r + V_k^{qq} (\dot{u}_i^r)^2 \right. \\
 & + \sum_{j=1}^{N_i} (ULB)_{ij} \dot{u}_i^\ell \dot{\zeta}_{ij} + \sum_{j=1}^{N_i} (URB)_{ij} \dot{u}_i^r \dot{\zeta}_{ij} \\
 & + \sum_{j=1}^{N_i} \sum_{m=1}^{N_i} (BB)_{ijm} \dot{\zeta}_{ij} \dot{\zeta}_{im} + \sum_{n=1}^{N_k} \frac{1}{\lambda_{kn}} s_{kn}^p \dot{u}_i^\ell \dot{\xi}_{kn} \\
 & + \sum_{n=1}^{N_k} \frac{1}{\lambda_{kn}} s_{kn}^q \dot{u}_i^r \dot{\xi}_{kn} + \sum_{j=1}^{N_i} \sum_{n=1}^{N_k} \frac{1}{\lambda_{kn}} (BS)_{kjn} \dot{\zeta}_{ij} \dot{\xi}_{kn} \\
 & \left. + \frac{1}{2} \sum_{n=1}^{N_k} \sum_{m=1}^{N_k} \frac{1}{\lambda_{kn} \lambda_{km}} s_{knm} \dot{\xi}_{kn} \dot{\xi}_{km} \right\} \quad (3.6)
 \end{aligned}$$

Detailed derivations and expressions of V_k^{pp} , V_k^{pq} , V_k^{qq} , $(ULB)_{ij}$, $(URB)_{ij}$, $(BB)_{ijm}$, s_{kn}^p , s_{kn}^q , $(BS)_{kjn}$ and s_{knm} are given in the Appendix.

The potential energy of the propellant contained in the k^{th} tank is expressed as a surface integral integrated over the static free surface of the propellant (Ref. 4).

$$P_k = \frac{1}{2} \rho_k \alpha_3 \int_S \eta^2 r \, d\theta \, dr \quad (3.7)$$

where

$$\eta = \sin\theta \sum_{n=1}^{N_k} \xi_{kn} \phi_{kn}$$

is the wave height of liquid propellant (see Fig. 6) and α_3 is the longitudinal acceleration of a vehicle. Similarly, Eq. (3.7) can be written in terms of the generalized coordinates of the system.

$$P_k = \frac{\pi}{2} \rho_k \alpha_3 a_k^2 \sum_{n=1}^{N_k} \sum_{m=1}^{N_k} p_{knm} \xi_{kn} \xi_{km} \quad (3.8)$$

The quantities p_{knm} and the intermediate steps which lead to Eq. (3.8) are given in the Appendix.

If Eqs. (3.6) and (3.8) are substituted into Eq. (2.3) and differentiated with respect to the appropriate coordinates, the elements of the mass and stiffness matrices associated with the propellant will be found. After a combination with the corresponding matrices associated with the hardware, a matrix equation which governs the vibrational characteristics of a system (Eq. (2.6)) will be obtained. The method of solving this equation is given in Ref. 1.

Lateral force distribution coefficients due to the dynamics of the liquid propellant are computed in the same fashion as in Ref. 4. However, a maximum of three slosh modes per tank can now be included. It can be shown that the lateral force exerted on the k^{th} tank wall due to the motion of the first m layers of the propellant (measured from the tank bottom) is

$$\left({}_m^F \right)_k = \left({}_m^A \right)_k \alpha_{2i} + \left({}_m^B \right)_k \ddot{\psi}_i + \sum_{n=1}^{N_k} \left({}_m^C \right)_k \xi_{kn} \alpha_3 \quad (3.9)$$

where

$$({}_m^A \alpha)_k = -M_{mk} + \pi a_k^2 \rho_k \sum_{n=1}^{N_k} \ell_k b_n \left(\sum_{j=1}^{10} c_{kj}^n I_{kj} \right) \quad (3.10)$$

$$\begin{aligned} ({}_m^B \psi)_k &= -G_{3k} M_{mk} - \pi a_k^4 \rho_k \oint Z^2 R dR \\ &\quad - \pi a_k^2 \ell_k^2 \rho_k \sum_{j=1}^9 q_j \int_{m^A} \left(\frac{\partial f_j}{\partial R} + \frac{f_j}{R} \right) R dR dZ \\ &\quad + \pi a_k^2 \rho_k \sum_{n=1}^{N_k} \ell_k \left[G_{3k} b_n - \ell_k (b_n - h_n) \right] \left(\sum_{j=1}^{10} c_{kj}^n I_{kj} \right) \end{aligned} \quad (3.11)$$

$$({}_m^C \xi)_{kn} = \pi a_k^2 \rho_k \sum_{j=1}^{10} c_{kj}^n I_{kj} \quad (3.12)$$

$$I_{kj} = \int_{m^A} \left(\frac{\partial \phi_{kn}}{\partial R} + \frac{\phi_{kn}}{R} \right) R dR dZ \quad (3.13)$$

$$R \equiv \frac{r}{a_k}$$

$$Z \equiv \frac{x_3}{a_k}$$

and $\int_m A$ denotes an integration over the first m layers of the propellant in a tank. Notations α_{2i} and $\ddot{\psi}_i$ are the lateral and angular accelerations of the i^{th} beam, respectively. G_{3k} and M_{mk} are the distance between center of mass and beam end and the propellant mass in the first m layers of the k^{th} tank, respectively. Definitions of b_m , q_j , k_m and f_j which are all related to the k^{th} tank can be found in Ref. 4. Consequently, the lateral force in the m^{th} layer of the k^{th} tank is calculated by subtracting $({}_{m-1}F'_2)_k$ from $({}_mF'_2)_k$ or

$$({}_mF_2^*)_k = ({}_{m-1}F'_2)_k - ({}_mF'_2)_k \quad (3.14)$$

Section 4
DIGITAL COMPUTER PROGRAM

4.1 PROGRAM ORGANIZATION

A program called SLOSH was developed in this study. Detailed discussions are presented in Section 4.2. This program computes the lateral dynamic force distribution coefficients due to the propellant of a vehicle, and provides the information with regard to the dynamic behavior of the liquid propellant contained in a rigid tank. If the SLOSH program is used as a subprogram of a modified Lockheed/Huntsville bending program (Ref. 1), it will compute the mass and stiffness matrices associated with the liquid propellant of a vehicle. With these matrices, the bending program will solve the constructed eigenvalue program and provide the free vibrational characteristics of a vehicle.

The overlay configuration of the modified bending program is shown in Fig. 7. The functions of the principal subroutines are briefly outlined below:

<u>Deck Name</u>	<u>Function</u>
MAINX	Directs logic flow to other routines
BDAT	Sets up control information
C56Y	Generates fundamental beam deflection functions
C56D	Computes integral terms associated with the hardware
NPUT	Reads in data and sets up problem definition
C56A	Computes mass and stiffness arrays associated with the hardware
SLOSH	Computes mass and stiffness arrays associated with the liquid propellant and the lateral force distribution coefficients due to the dynamics of propellant

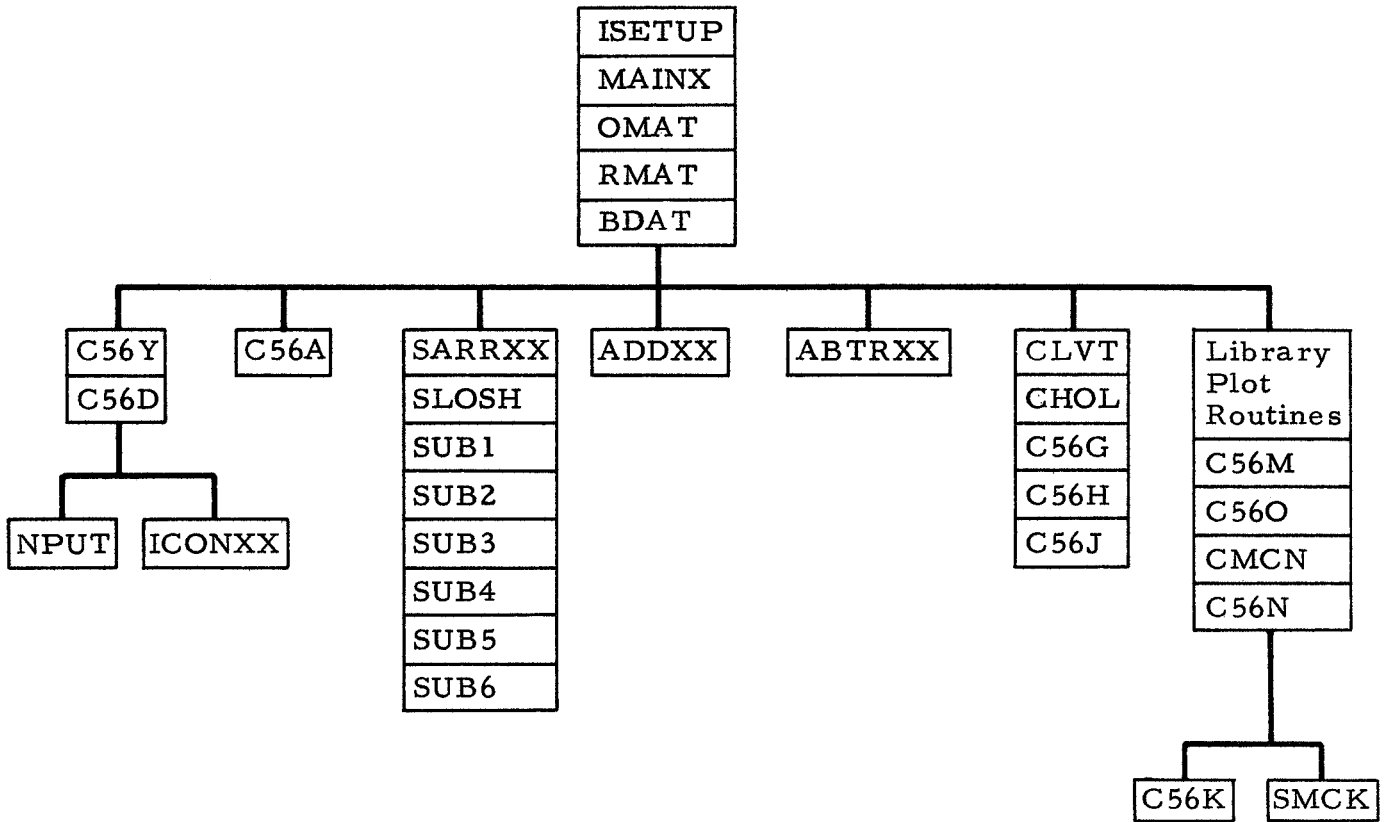


Fig. 7 - Program Overlay Configuration

<u>Deck Name</u>	<u>Function</u>
SUB2	Generates slosh normal modes
SUB3	Performs line integrals associated with the propellant
SUB4	Describes tank configurations
CLVT	Solves the constructed eigenvalue problem
C56K	Plots beam properties, displacement functions and mode shapes.

4.2 THE SLOSH PROGRAM

The SLOSH program serves the following purposes:

1. To read in certain output and intermediate data of Lomen's program (Ref. 4) such that the computation time of the modified bending program can be greatly reduced. In the future, if the SHARE simultaneous equation package (SOLVE) and the SHARE eigenvalue routine (RWEQ2F), which are in the MAP symbolic language, of Lomen's program could be coded in the Fortran IV language or substituted by other standard routines, the function of Lomen's program may be readily replaced by the SLOSH program. It is expected that the SLOSH program will take less computer time than the Lomen program.
2. To compute the mass and stiffness matrices associated with the liquid propellant of a vehicle.
3. To provide the lateral force distribution coefficients due to the propellant dynamics.

Input data which are now furnished by the Lomen program are listed on the following page.

<u>Variable Name</u> (Lomen program)	<u>Variable Name</u> (SLOSH program)	<u>Description</u>
TEMP(2)	DBTBCM(I)	Distance between tank bottom and center of mass
VALP	PEV(I, J)	Eigenvalues of a fluid system
CNK(J, K)	C(I, J, K)	Eigenvectors of a fluid system
HN(J)	HN(I, J)	see p. 3 - 9 of Ref. 4
ARG2	TTFCB(I, J)	$\pi a_k^2 \ell_k^2 \sum_{j=1}^9 q_j \int_{m^A} \left(\frac{\partial f_j}{\partial R} + \frac{f_j}{R} \right)$ RdRdZ (see second term of Eq. (3.11))

Note that the Lomen program has some errors in the computation of the lateral force distribution coefficients. His program has also been slightly modified in order to obtain the above variables.

Unfortunately, due to the complexity of the bending program, it will not be able to evaluate the integrals of Eq. (A-4) in the bending program for the moment. Currently, the fundamental deflection functions which are generated from subroutine C56Y are approximated by straight-line segments in order to perform the integrations of Eq. (A-4) in the SLOSH program. Each deflection function associated with a tank is represented by three straight-line segments. The ordinates of the terminals of the straight lines are shown by the dots along the x_3^* axes in Figs. 2 through 5. In general, these segments should be chosen to give the best approximation of the portion of a deflection curve where the integration over the propellant volume is actually taking place.

The tank configurations of Saturn V are specified by simple curves (Figs. 2 through 5). Bessel functions which are represented by series form (Ref. 5) are included as a subroutine of the SLOSH program. Finally, the line integrals of Eqs. (A-3) through (A-6) are evaluated by the Gauss mechanical quadrature formula (Ref. 6).

4.3 PROGRAM LIMITATIONS

The present IBM 7094 version of the modified bending program is designed for a four-beam model, see Fig. 1-C and Section 5. The DIMENSION statements which are used in the SLOSH program require the following limitations to be observed:

<u>Variable Name</u>	<u>Description</u>	<u>Maximum Capacity</u>
NSMODE	Number of slosh modes per tank	3
NPT(I)	Number of partitions per tank	32
NCOR	Total number of degrees of freedom	60

4.4 USER'S GUIDE FOR THE FOUR-BEAM MODEL

4.4.1 Input

The sequence and format of an input data deck for a particular flight time are shown below:

<u>Data Set</u>	<u>No. of Cards</u>	<u>Format</u>	<u>Description</u>		
1	1	12A6	Title Card		
2	1	12I6	<u>Column</u>	<u>Value</u>	
			1-6	1	Rotary inertia is included.
				0	Rotary inertia is not included.
			7-12	1	Fundamental deflection functions are printed.
				0	Fundamental deflection functions are not printed.
			13-18	1	Shear deflections are included.
	0	Shear deflections are not included.			

<u>Data Set</u>	<u>No. of Cards</u>	<u>Format</u>	<u>Column</u>	<u>Value</u>	<u>Description</u>
2	1	12I6	19-24	0	Only problem definition data printed.
				1	Integral terms are printed.
				2	Mass and stiffness arrays are printed.
				3	Intermediate eigenproblem array and all accuracy check arrays are printed.
					Not operational
				N	N modes are plotted.
					Not operational
					Not operational
					Not operational
				1	Output tape in Stodola format is generated.
				0	Tape is not generated.
					Not operational
					0
	3	Slosh coordinates are included.			
3	Variable	4E18.8			Mass distribution of a vehicle
4	Variable	7E11.7			Mass distribution of the hardware of a vehicle
5	1	8I10	1-10	N	N th stage of flight
			11-20	N	N cases
			21-30	N	N slosh modes per tank
			31-40	0	Propellant mass is included in the bending program.

<u>Data Set</u>	<u>No. of Cards</u>	<u>Format</u>	<u>Description</u>		
5	1	8I10	<u>Column</u>	<u>Value</u>	
				1	Otherwise
			41-50	0	No lateral force distribution coefficients printout
				1	Otherwise
			51-60	0	Zero length interstage
				1	Otherwise
			61-70	0	No normalized slosh normal modes printout
				1	Otherwise
6	1	8E10.6	<u>Column</u>		
			1-10	Flight time	
			11-20	Longitudinal acceleration of a vehicle	
			21-80	Propellant levels	
7	1	8E10.6	Propellant mass densities		
8	1	8E10.6	Distance between tank bottom and center of mass for all tanks		
9	1	8E10.6	Beam lengths		
10	1	8E10.6	Distance between tank coordinate system and beam end for all tanks		
11	Variable	8E10.6	First three eigenvalues of a fluid system for all tanks		
12	Variable	10E8.4	First three eigenvectors of a fluid system for all tanks		
13	Variable	8E10.6	Abscissas of approximate fundamental deflection functions		
14	Variable	8E10.6	Ordinates of approximate fundamental deflection functions		
15	1	8I10	Number of partitions of each tank		

<u>Data Set</u>	<u>No. of Cards</u>	<u>Format</u>	<u>Column</u>
16	1	8E10.6	Partition heights of all tanks
17	Variable	8E10.6	HN(I, J), see Section 4.2
18	Variable	8E10.6	TTF CB(I, J), see Section 4.2

In case of multiple runs, input data decks for different flight times may be stacked together. In addition, the Stodola tape is used to generate the fundamental deflection functions. As an example, the data deck for Saturn V at flight time $t = 0$ is given on the following pages.

4.1.2 Output

All of the input information will be provided. By taking the proper options in the input data cards, the following output may be obtained:

1. Mass and stiffness properties of a vehicle
2. Frequencies, mode shapes and generalized mass printout and plots
3. Lateral force distribution coefficients due to the propellant dynamics
4. Other pertinent intermediate computations.

```

$DATA
SA-503 4-BEAM MODEL T = 0.0
1 0 1 13
0.23626649E 04 0.23573295E 04 0.27036256E 04 0.31628707E 04 3
0.33285230E 04 0.34410596E 04 0.36767982E 04 0.39405403E 04
0.42356412E 04 0.45399702E 04 0.48011578E 04 0.50480263E 04
0.53577202E 04 0.56919917E 04 0.61586480E 04 0.66828657E 04
0.77538636E 04 0.90879822E 04 0.11009531E 05 0.13229081E 05
0.18052180E 05 0.23924706E 05 0.29495270E 05 0.32815892E 05
0.21687931E 05 0.11980989E 05 0.12246694E 05 0.12512399E 05
0.12673966E 05 0.12834600E 05 0.11839444E 05 0.10833241E 05
0.10083304E 05 0.93333669E 04 0.94514519E 04 0.15194759E 05
0.21486629E 05 0.26989582E 05 0.33300475E 05 0.39198215E 05
0.44646836E 05 0.49588704E 05 0.53733486E 05 0.57266059E 05
0.60288021E 05 0.62788426E 05 0.64890358E 05 0.66530950E 05
0.66973726E 05 0.66521650E 05 0.66191993E 05 0.66122411E 05
0.66091067E 05 0.66095638E 05 0.66103289E 05 0.66114230E 05
0.66146886E 05 0.66205900E 05 0.66233432E 05 0.66217429E 05
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0.65973279E 05 0.66089760E 05 0.66166635E 05 0.66160175E 05
0.66151226E 05 0.66136185E 05 0.66123054E 05 0.66115715E 05
0.66174439E 05 0.66472948E 05 0.66426489E 05 0.65664463E 05
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0.62322824E 05 0.69070327E 05 0.74929092E 05 0.79899129E 05
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 0.56188857E 03
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 0.25514547E 03
 0.75184672E 03

2362664+04 2357329+04 2703625+04 3162870+04 3328523+04 3441059+04 3676798+04
 3940540+04 4253641+04 4539970+04 4801157+04 5048026+04 5357720+04 5691991+04
 6158648+04 6682865+04 7753863+04 9087982+04 1100953+05 1322908+05 1805218+05
 2392470+05 2949527+05 3281589+05 2168793+05 1198098+05 1224669+05 1251239+05
 1267396+05 1283460+05 1183944+05 1083324+05 1008330+05 9333366+04 9451451+04
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 4421236+04 4086905+04 3843915+04 3681305+04 3722174+04 3903649+04 3489253+04
 2755130+04 2425473+04 2355891+04 2324547+04 2329117+04 2336769+04 2347711+04
 2380366+04 2439381+04 2466912+04 2450909+04 2403453+04 2304134+04 2229292+04
 2193359+04 2206759+04 2323240+04 2400114+04 2393655+04 2384705+04 2369664+04
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1684166+04	1877846+04	1457171+04	1009263+04	9842645+03	9650124+03	1056061+04
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2112179+04	1672755+04	1330493+04	1322814+04	1250193+04	7508472+03	2974077+03
1793266+03	7585993+02	6276253+02	5034544+02	5195878+02	5357213+02	9826811+02
1455621+03	3401584+03	6575494+03	6580254+03	6063984+03	5814081+03	5650295+03
5608367+03	5608367+03	5611183+03	5615138+03	5622081+03	5630430+03	5627674+03
5618885+03	5310164+03	4814475+03	4327175+03	3836908+03	3010722+03	2184536+03
1890077+03	2551454+03	3593000+03	5292847+03	6692024+03	7518467+03	5096431+03
1337765+03	4268478+02					
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70.8016	1143.3979	70.8016	1143.3979	1143.3979	799.3213	
5.436664	2.15754	8.683117	3.140649	8.833208	5.96866	
45.25	21.75	17.75				
7.9714	5.8892	4.68	4.67968	26.1197	12.22968	
2.2925	5.6755	8.8979	2.5206	5.8236	9.0631	2.0642
8.7901	2.0947	5.635	8.8779	1.8842	5.388	8.6083
5.5301	8.764					2.0329
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-6518-02	-2353-01	4346-01	-3072-01	74	-02	-4334-01
4218-02	9576-02	-1421-01	1028-01	-2739-02	9889-02	-757 -01
						1
						+01
						1275+00
						-5035-01
						2848-01
						-185 -01
						+01
						1345+00
						-6384-01
						4028-01
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						1429+00
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 -2649-01-2267-01 421 -01-2798-01 58 -02-3501-01 1 +01 1929+00-8158-01 4701-01
 1515-01-361 -02 1501-01-7955-02 11 -02-396 -03-102 +00 1 +01 2141+00-9559-01
 148 -01-3301-01 9027-01-9992-01 3644-01 1 +01 7743-01-3942-01 2714-01-1685-01
 -1002-01 159 -01-5267-01 5974-01-2195-01-2196-01 1 +01 9263-01-476 -01 3183-01
 6845-02-1003-01 3483-01-3827-01 1371-01 3311-02-5231-01 1 +01 1005+00-5164-01
 1218+00-588 -01 153 +00-2013+00 762 -01 1 +01 1243+00-5412-01 2932-01-1888-01
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 2207-01 1785-01-1007-01-6117-02 6377-02-2456-01-6294-01 1 +01 1393+00-6944-01
 4516-02-2398-01 7 -01-7858-01 2993-01 1 +01 1733-01-1083-01 7282-02-5712-02
 -1852-02 2223-02-7058-02 6448-02-1759-02-5345-02 1 +01 2467-01-1432-01 1042-01
 1474-02-2025-02 6347-02-5581-02 1485-02 1015-02-146 -01 1 +01 2861-01-1603-01
 2035-01-4811-01 1393+00-1569+00 5804-01 1 +01 6951-01-3625-01 2209-01-1559-01
 -1251-01 2698-01-8906-01 1017+00-3816-01-1503-01 1 +01 8333-01-4317-01 2916-01
 8858-02-1909-01 6385-01-7114-01 2634-01-3696-03-4613-01 1 +01 9012-01-4682-01
 -0.9652 -0.988 -0.63 0.0 0.0 -0.8773 -0.9929 -0.8 0.0
 1.0 0.96 0.53 0.0 0.0 -0.9983 -0.8202 -0.2344 0.0
 -0.8089 -0.9652 -0.988 -0.63 -0.6378 -0.8773 -0.9929 -0.8
 0.7339 1.0 0.96 0.58 -0.92 -0.9983 -0.8202 -0.2344
 -0.74 -1.0 -0.7 0.0 -0.5071 -0.8284 -0.95 0.0
 0.9 1.0 0.63 0.0 0.0 -1.0 -0.98 -0.2898 0.0
 -0.1967 -0.74 -1.0 -0.75 -0.1186 -0.5071 -0.8284 -1.0
 0.2222 0.9 1.0 0.66 -0.3 -1.0 -0.98 -0.2898
 -0.9677 -0.9991 -0.72 -0.3502 0.9902 0.9894 0.66 0.2294
 0.7673 0.9361 0.94 0.3001 -0.9862 -0.9915 -0.66 -0.2276
 -0.4264 -0.6037 -0.87 -0.9566 0.4935 0.69 0.94 0.9849
 0.1316 0.2295 0.5079 0.7375 -0.4751 -0.6686 -0.92 -0.9796
 -1.2214 1.2786 6.7786 9.7786 -1.3892 0.8608 3.3608 8.8608
 -0.18 3.57 13.57 17.07 -3.68 -0.18 3.57 13.57
 -3.6197 0.13 12.38 15.88 -3.73 0.02 6.02 9.77
 20 20 20 21 22 28 28 28
 0.5 0.2 0.75 0.25 0.6 0.4
 0.93105 -0.19023 0.089381 0.91715 -0.24938 0.1116 1.133 -0.24506
 0.12149 0.85781 -0.39294 0.21894 1.1765 -0.2354 0.12069 1.2356
 -0.3057 0.15845
 658953+02 141898+03 218344+03 288758+03 349232+03 398517+03 43591 +03 460371+03
 47081 +03 466415+03 446915+03 412695+03 364752+03 304518+03 23363 +03 157396+03
 927739+02 432502+02 106483+02 828505-05

245042+01 529698+01 825329+01 110622+02 135234+02 155011+02 16919 +02 17745 +02
 179549+02 175535+02 165604+02 150034+02 129386+02 104702+02 776504+01 505881+01
 264904+01 868492+00 327218-01 294694-05 190812+04 213262+04 228939+04 237614+04
 424226+03 866266+03 126976+04 161906+04 173983+04 141068+04 102577+04 612205+03
 239135+04 233438+04 220553+04 200636+04 486374-03 838783+02 925297+02 983975+02
 29562 +03 102769+03 17328 +02-103933-01 727003+02 758617+02 644455+02 520009+02
 140977+02 293034+02 447096+02 594357+02 85673 +02 376999-05 291676+04 318317+04
 101375+03 10147 +03 987661+02 934213+02 131242+01 260438+04 363977+04 350168+04
 392098+02 268438+02 15757 +02 689365+01 224911+04 372814+04 129438+04 874142+03
 488752+03 968504+03 142603+04 185476+04 376578+04 212004+04 172008+04 129438+04 874142+03
 340128+04 356944+04 368653+04 375201+04 212004+04 172008+04 129438+04 874142+03
 331516+04 308178+04 280337+04 248202+04 709305+03 825171+03 92623 +03 10113 +04
 496566+03 201406+03 28799 +02 696182-04 117106+04 114794+04 110686+04 104839+04
 14122 +03 290307+03 439039+03 580035+03 535686+03 411094+03 291931+03 184559+03
 107941+04 112984+04 116207+04 117583+04 973274+03 882393+03 776822+03 659537+03
 955375+02 318436+02 137338+01 89407 -06

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Section 5
EXAMPLE

Vibrational characteristics of Saturn V first stage flight are studied in this section. The vehicle is modeled as a series of four beams rigidly connected to each other (see Fig. 1c). Two cases of one slosh mode per tank and three slosh modes per tank are investigated. The longitudinal acceleration of Saturn V is shown in Fig. 8 and the first three slosh frequencies of the tanks of the vehicle are shown in Figs. 9 through 11. Most of the slosh modes, it was found, came before the vehicle bending modes. In the latter portion of the flight, however, some of the slosh modes (mainly higher modes) will mingle with the vehicle bending modes. Further observations will be made in the second phase of the present contract. It is to use the system bending modes obtained from this program to develop a hybrid simulation program for Saturn V atmospheric flight.

The first 25 modes of the case having three slosh modes per tank at flight time $t = 0$ are shown in Figs. 12 through 36. The corresponding frequency and generalized mass of each mode are given on the top of each plot. The first three vehicle bending modes of this case are also indicated in these figures. Similarly, the first 13 modes of the case having only one slosh mode per tank are presented in Figs. 37 through 49. Mass and stiffness properties of the vehicle for the above cases are provided in Figs. 50 through 53. For comparison, the mass distribution and vehicle bending modes of the vehicle at flight time $t = 40$ are shown in Figs. 54 through 57.

The lateral force distribution coefficients due to the liquid propellant of Saturn V are computed. It is found that the influence of higher slosh modes to the coefficients ${}_m A_\alpha$ and ${}_m B_\psi$ is small and diminishes rapidly for layers away from the propellant-free surface. These coefficients which take the first three slosh modes into account and the coefficients $({}_m C_\xi)_i$, $i = 1, 2, 3$, are shown in Figs. 58 through 67.

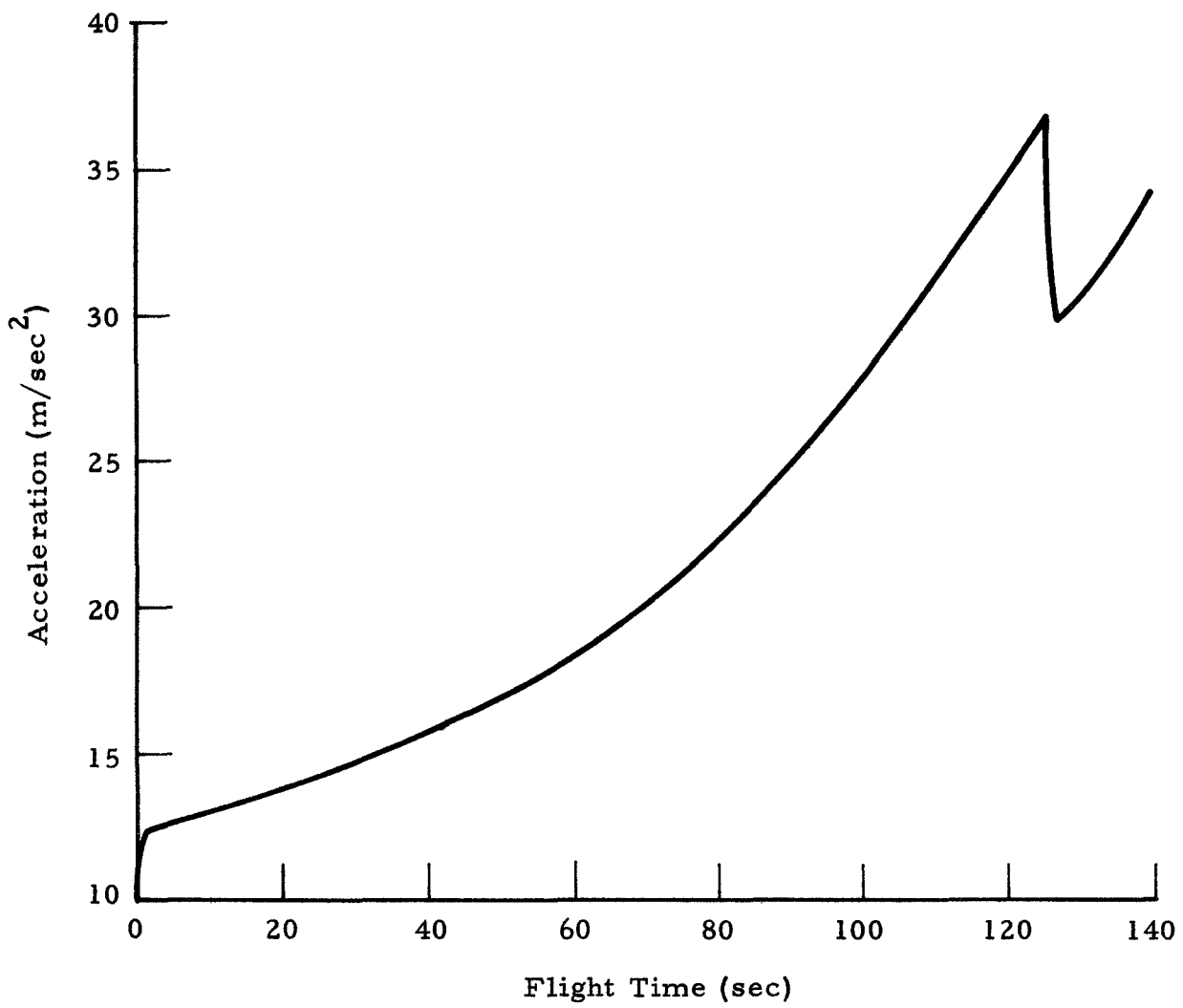


Fig. 8 - Longitudinal Acceleration of Saturn V

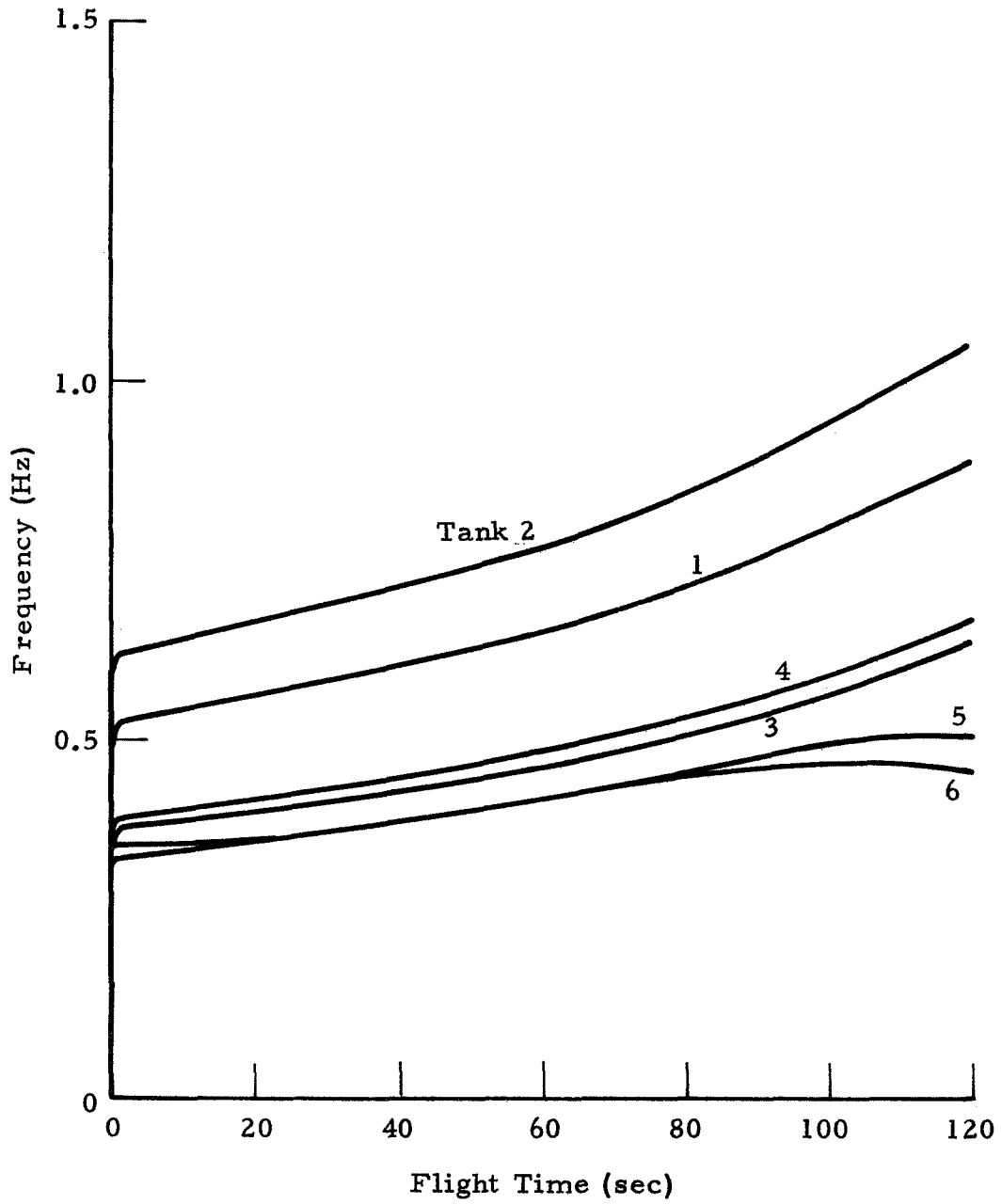


Fig. 9 - First Mode Slosh Frequencies of the Tanks of Saturn V

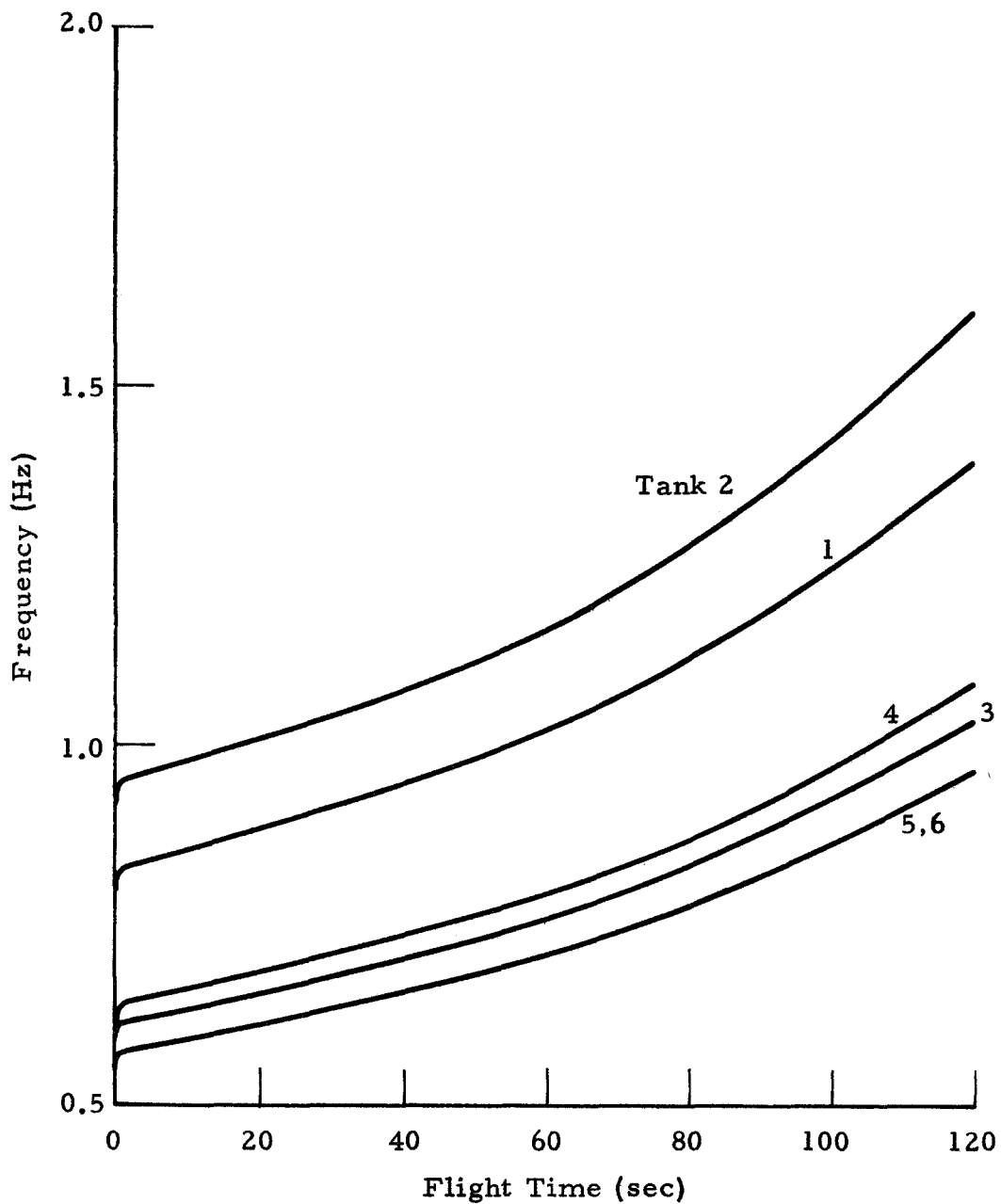


Fig. 10 - Second Mode Slosh Frequencies of the Tanks of Saturn V

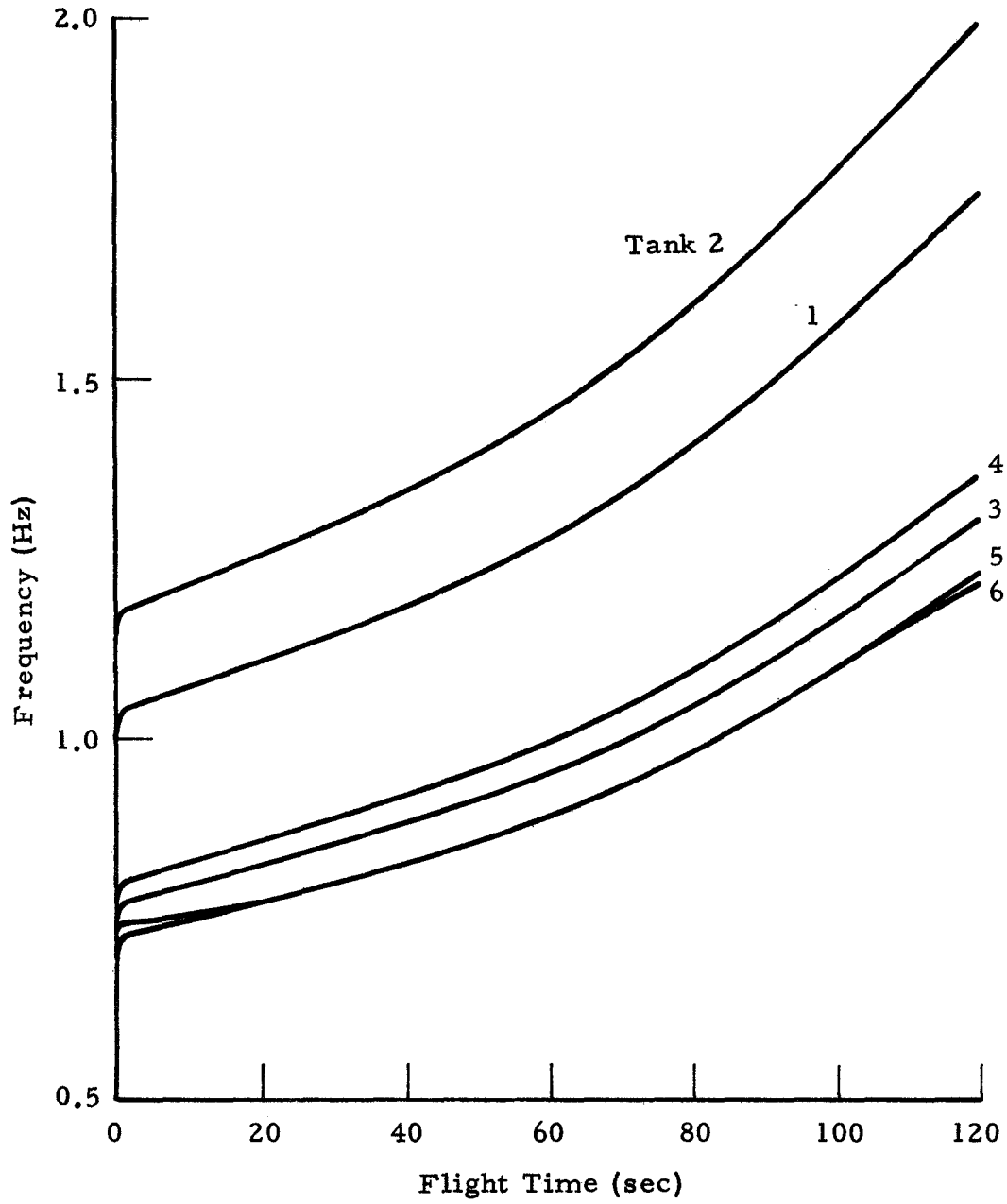


Fig. 11 - Third Mode Slosh Frequencies of the Tanks of Saturn V

SA-503 4-BEAM MODEL T = 0.0

5/08/69

MODE (1)

FREQUENCY = 0.000

GEN. MASS = 2.613X10⁺⁰⁵

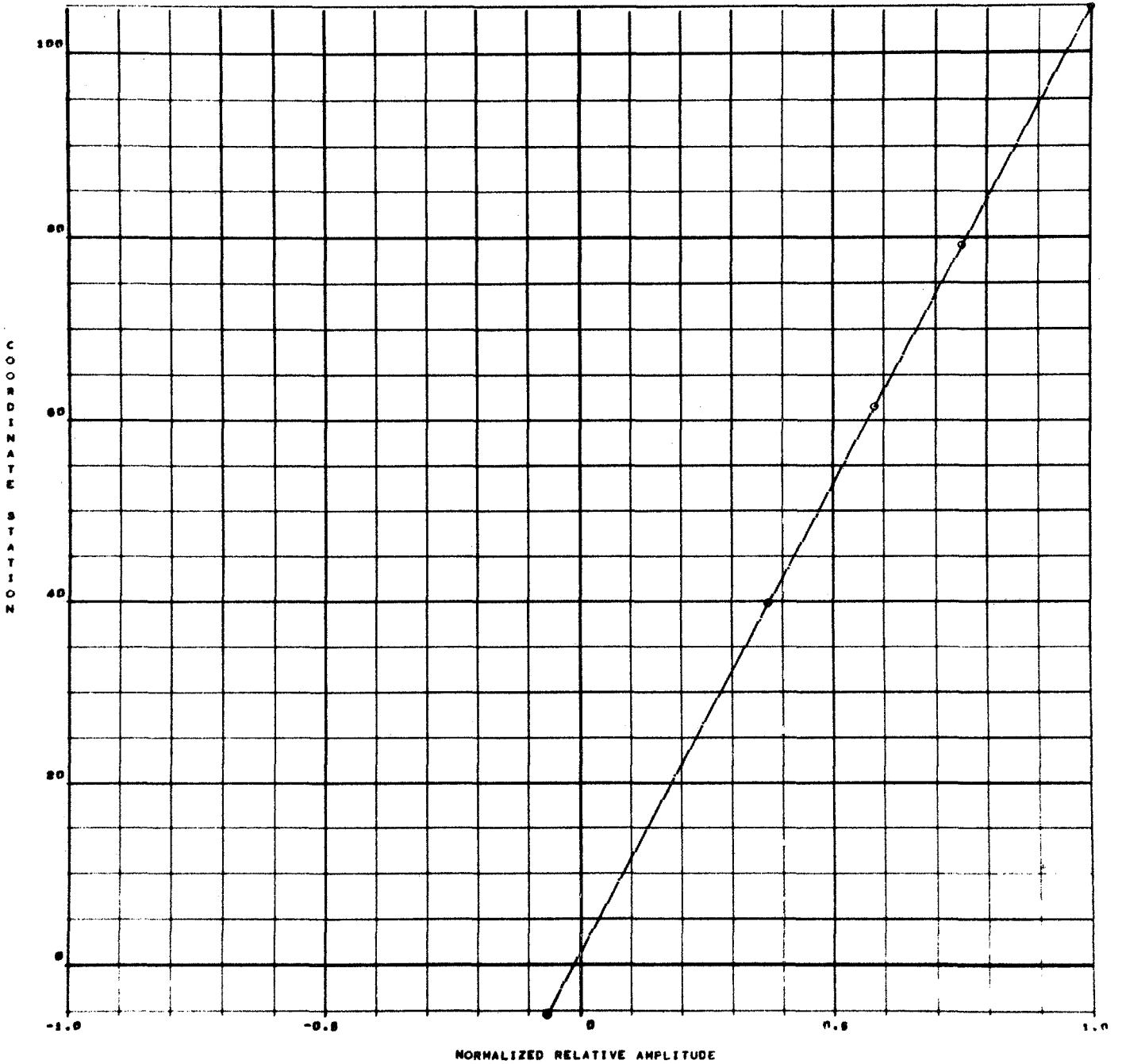


Fig. 12 - 1st Mode Shape (three slosh modes per tank)

SA-503 4-BEAM MODEL T = 0.0

5/08/69

MODE (2)

FREQUENCY = 0.000

GEN. MASS = 3.065X10⁺⁰⁵

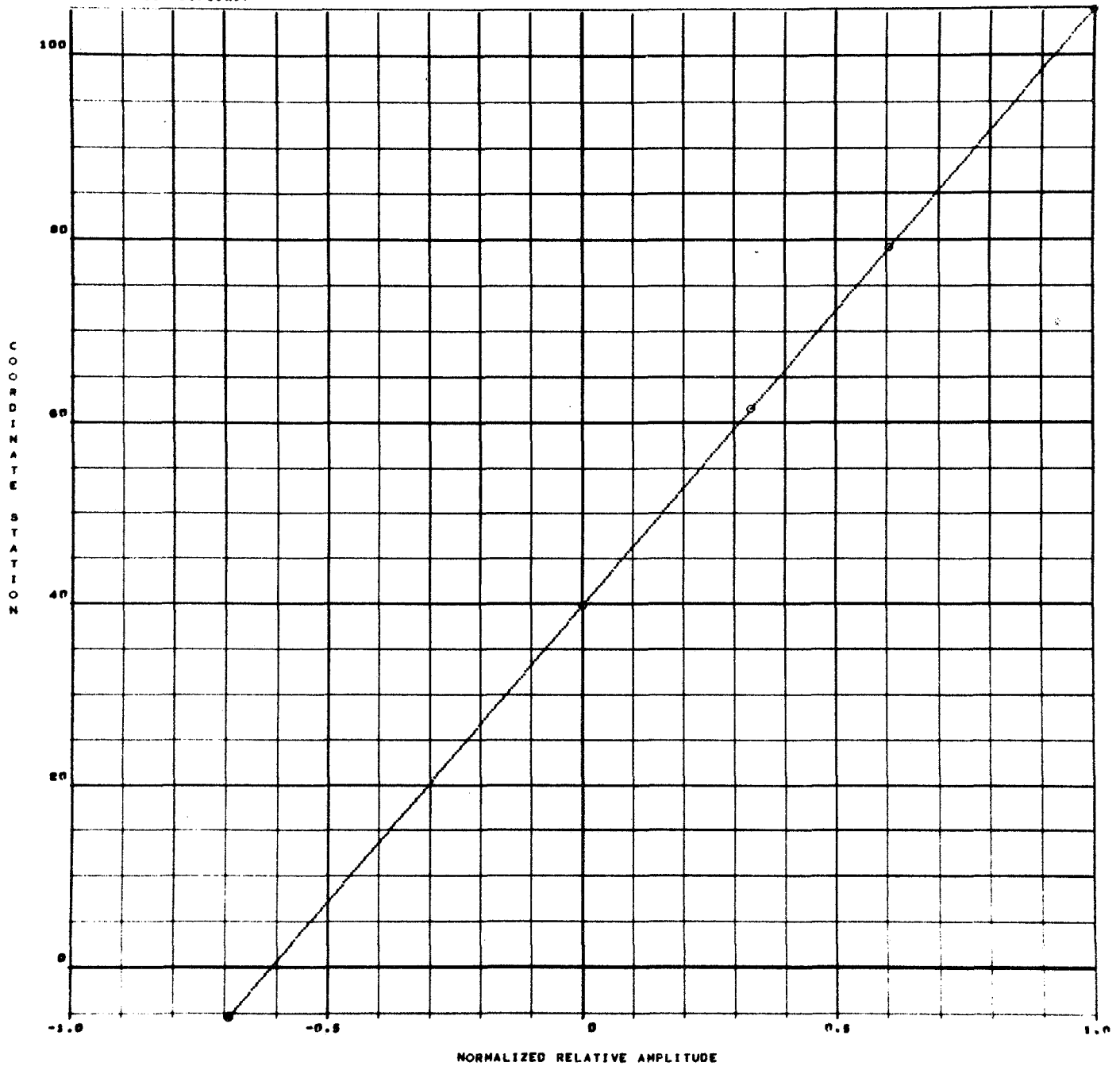


Fig. 13 - 2nd Mode Shape (three slosh modes per tank)

SA-503 4-BEAM MODEL T = 0.0

5/08/69

MODE(3)

FREQUENCY = 0.339

GEN. MASS = 1.355x10⁺⁰⁷

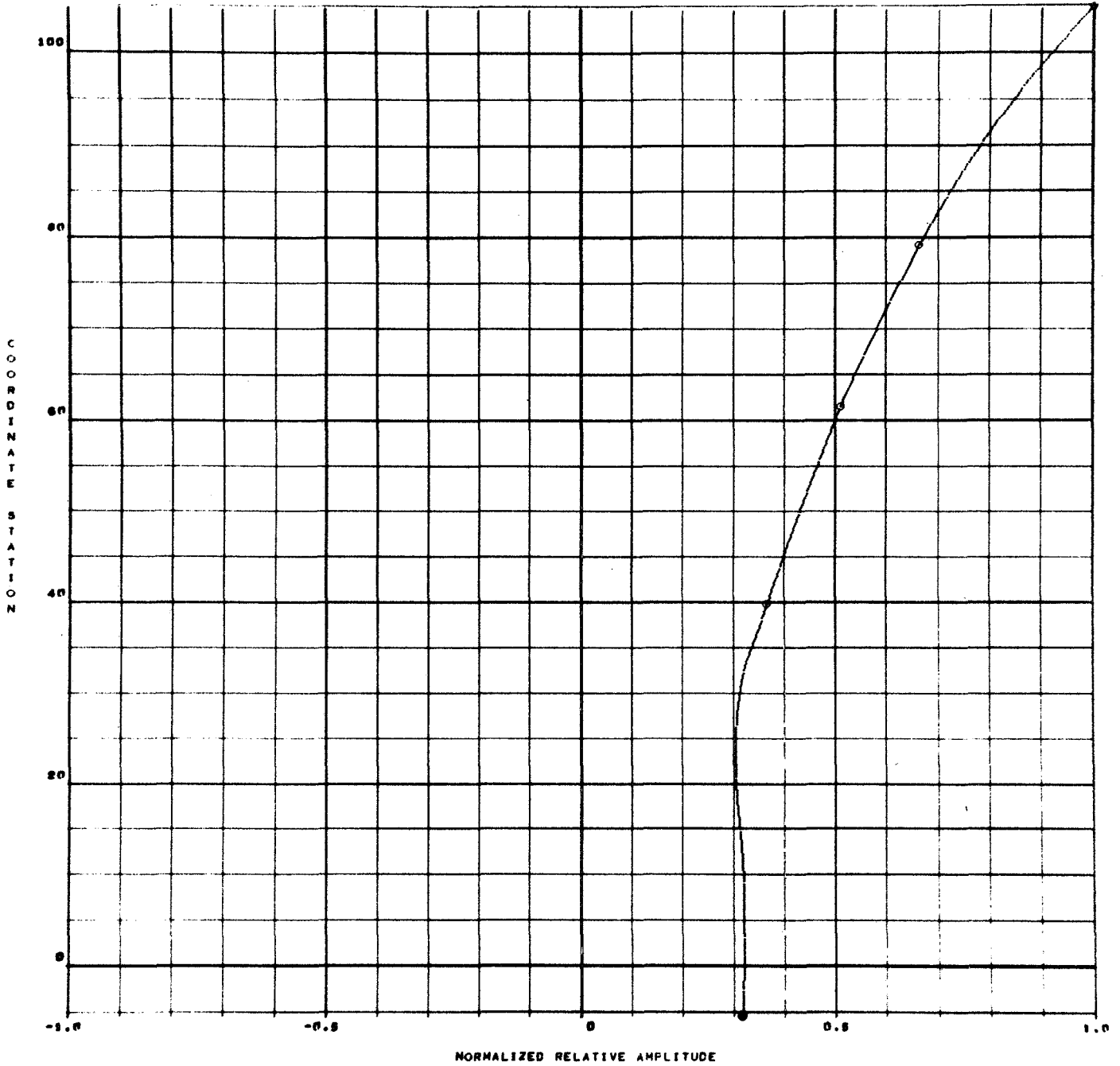


Fig. 14 - 3rd Mode Shape (three slosh modes per tank)

SA-503 4-BEAM MODEL T = 0.0

5/08/69

MODE (4)

FREQUENCY = 0.363

GEN. MASS = 4.722x10⁺⁰⁷

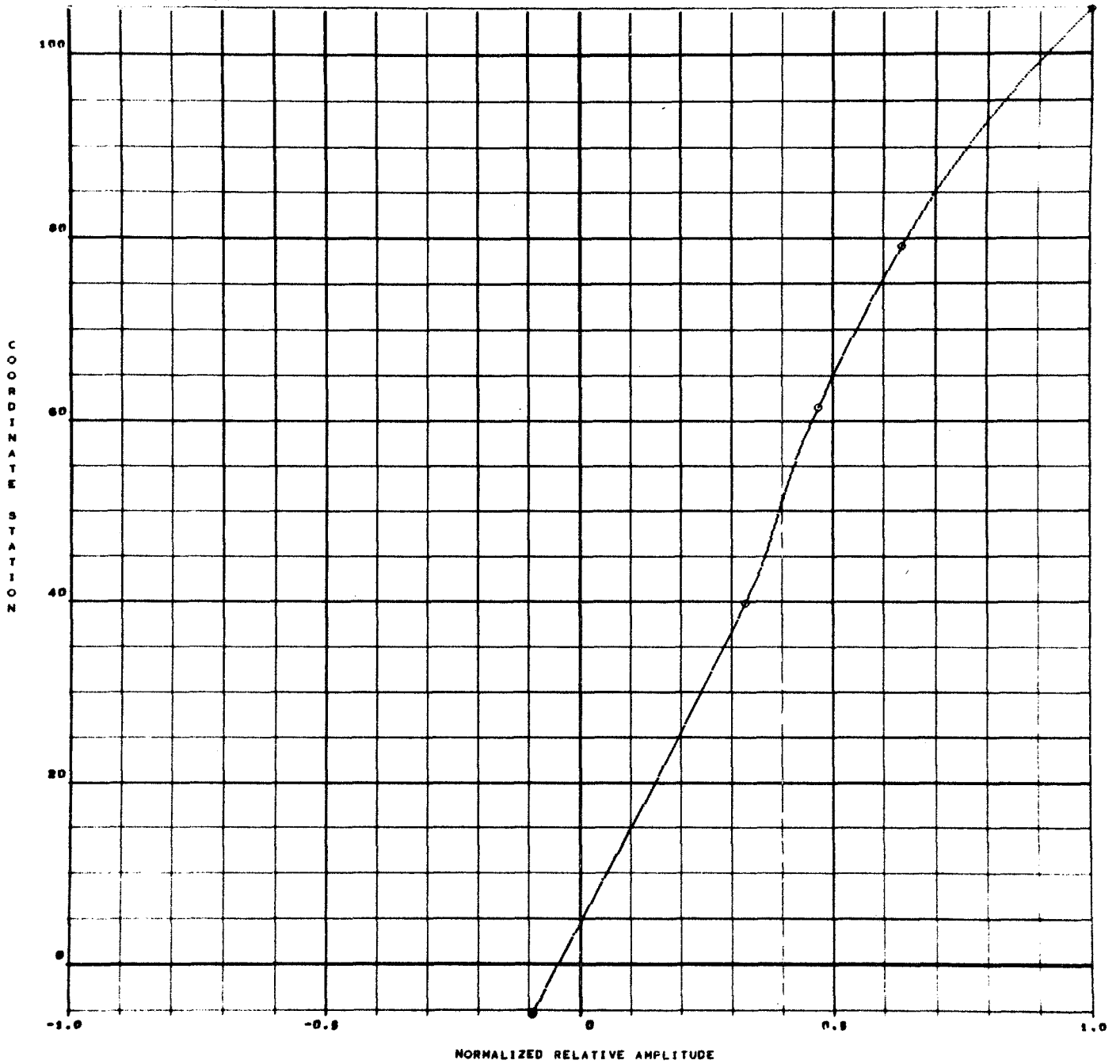


Fig. 15 - 4th Mode Shape (three slosh modes per tank)

SA-503 4-BEAM MODEL T = 0.0

5/08/69

MODE (5)

FREQUENCY = 0.376

GEN. MASS = 1.761X10⁰⁶

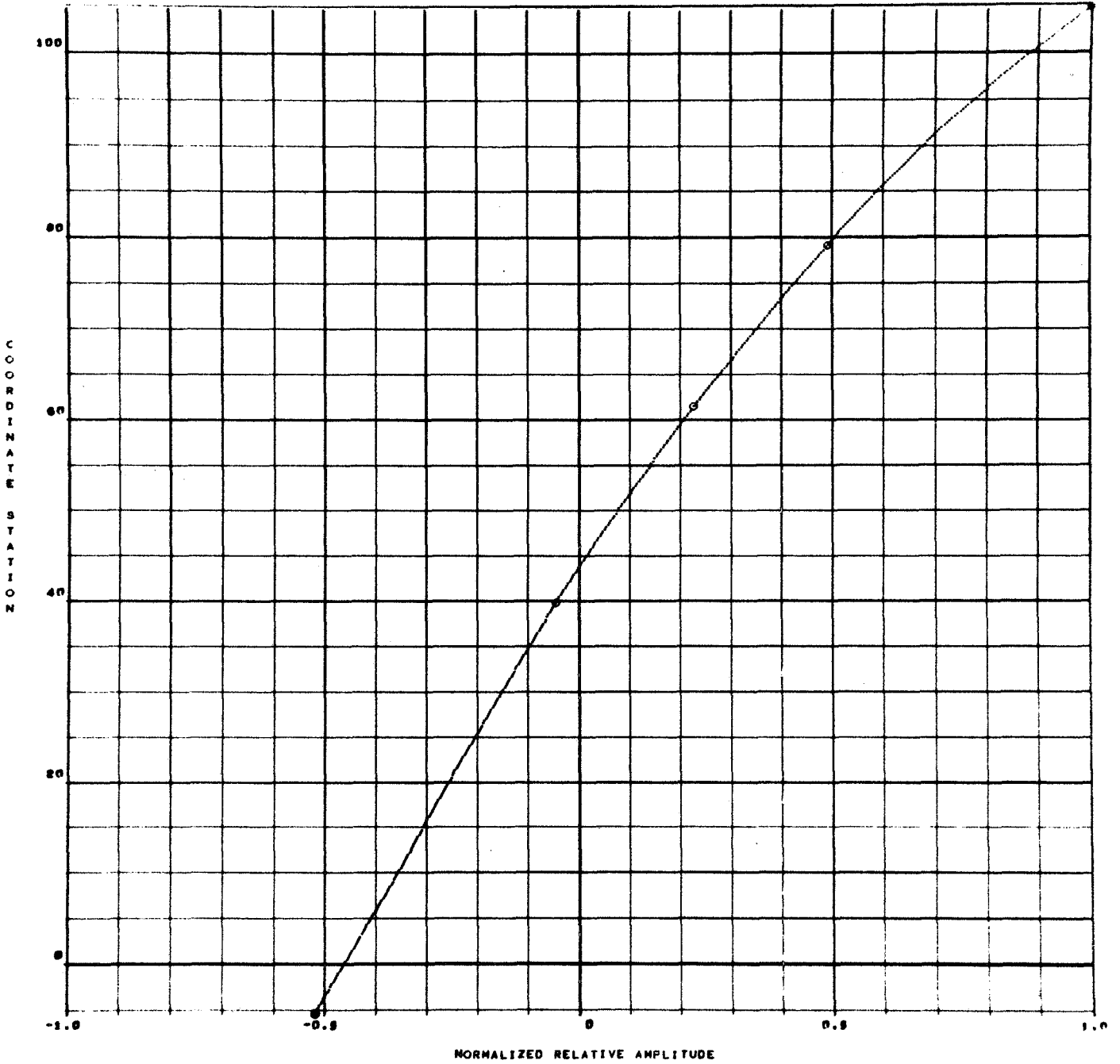


Fig. 16 - 5th Mode Shape (three slosh modes per tank)

SA-503 4-BEAM MODEL T = 0.0

5/08/69

MODE(6)

FREQUENCY = 0.398

GEN. MASS = 1.481X10⁺⁰⁶

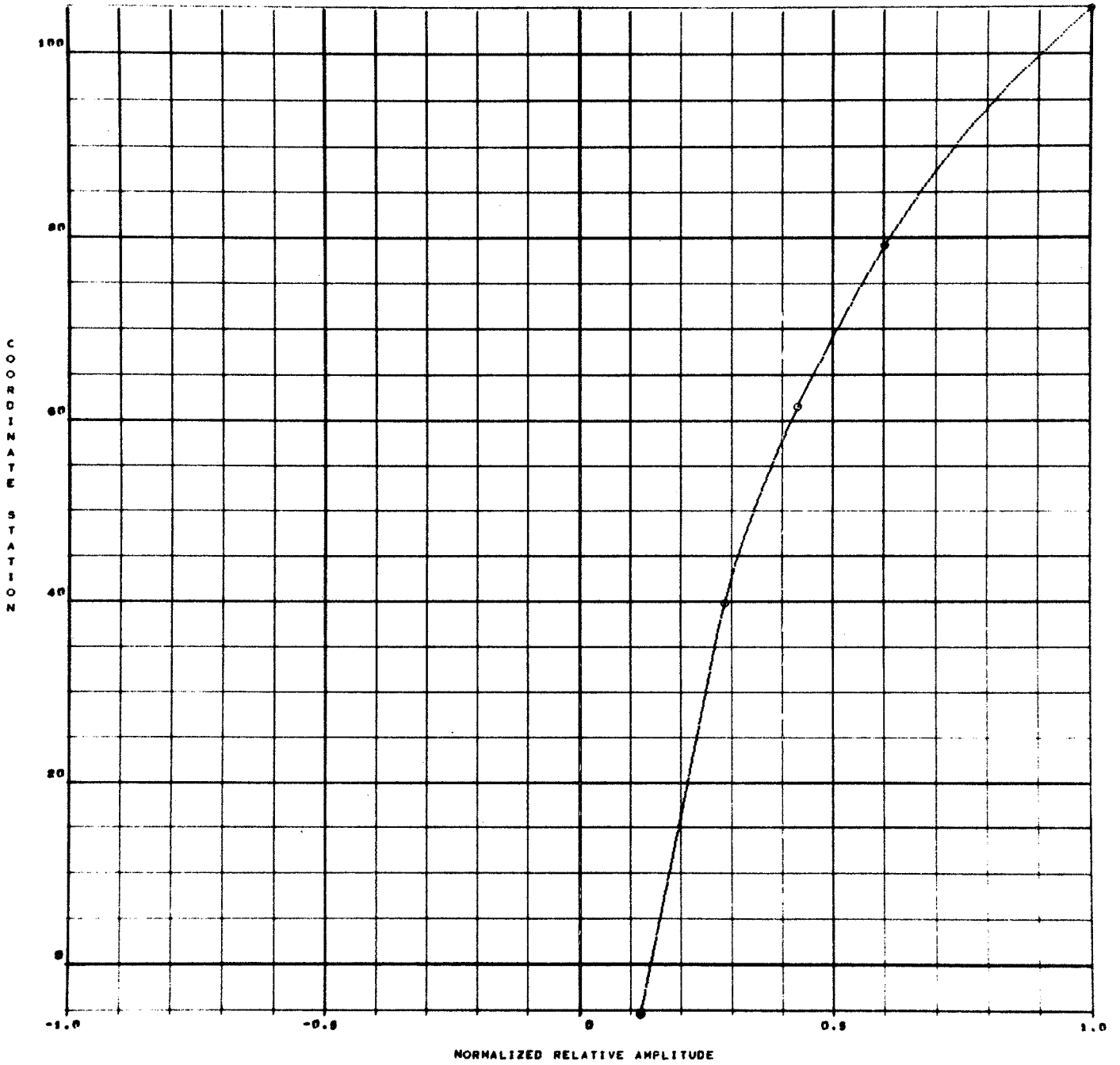


Fig. 17 - 6th Mode Shape (three slosh modes per tank)

SA-303 4-BEAM MODEL T = 0.0

5/00/69

MODE(7)

FREQUENCY = 0.511

GEN. MASS = 1.973x10⁺⁰⁷

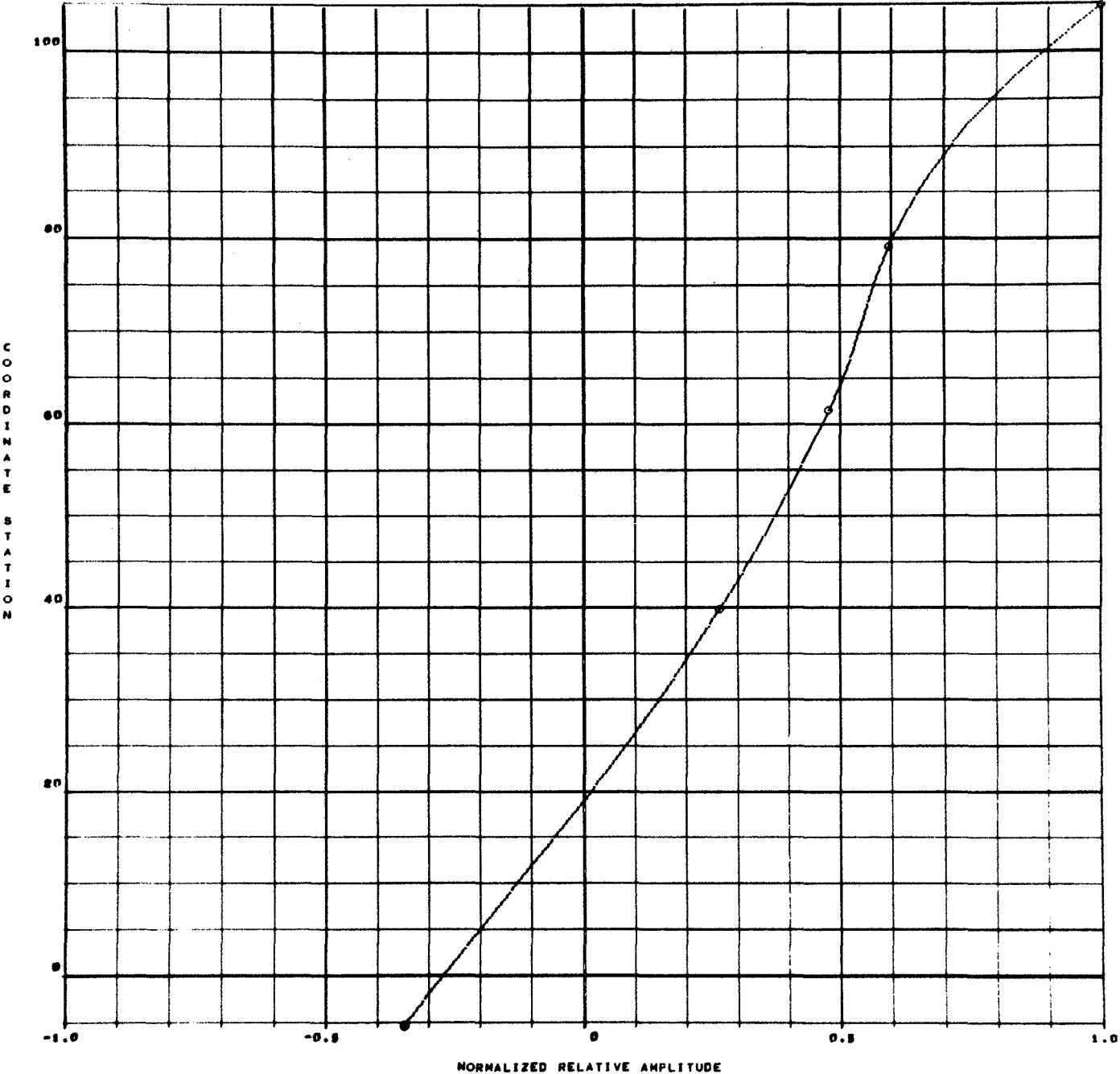


Fig. 18 - 7th Mode Shape (three slosh modes per tank)

SA-503 4-BEAM MODEL T = 0.0

5/08/69

MODE (8)

FREQUENCY = 0.563

GEN. MASS = 4.422x10⁰⁷

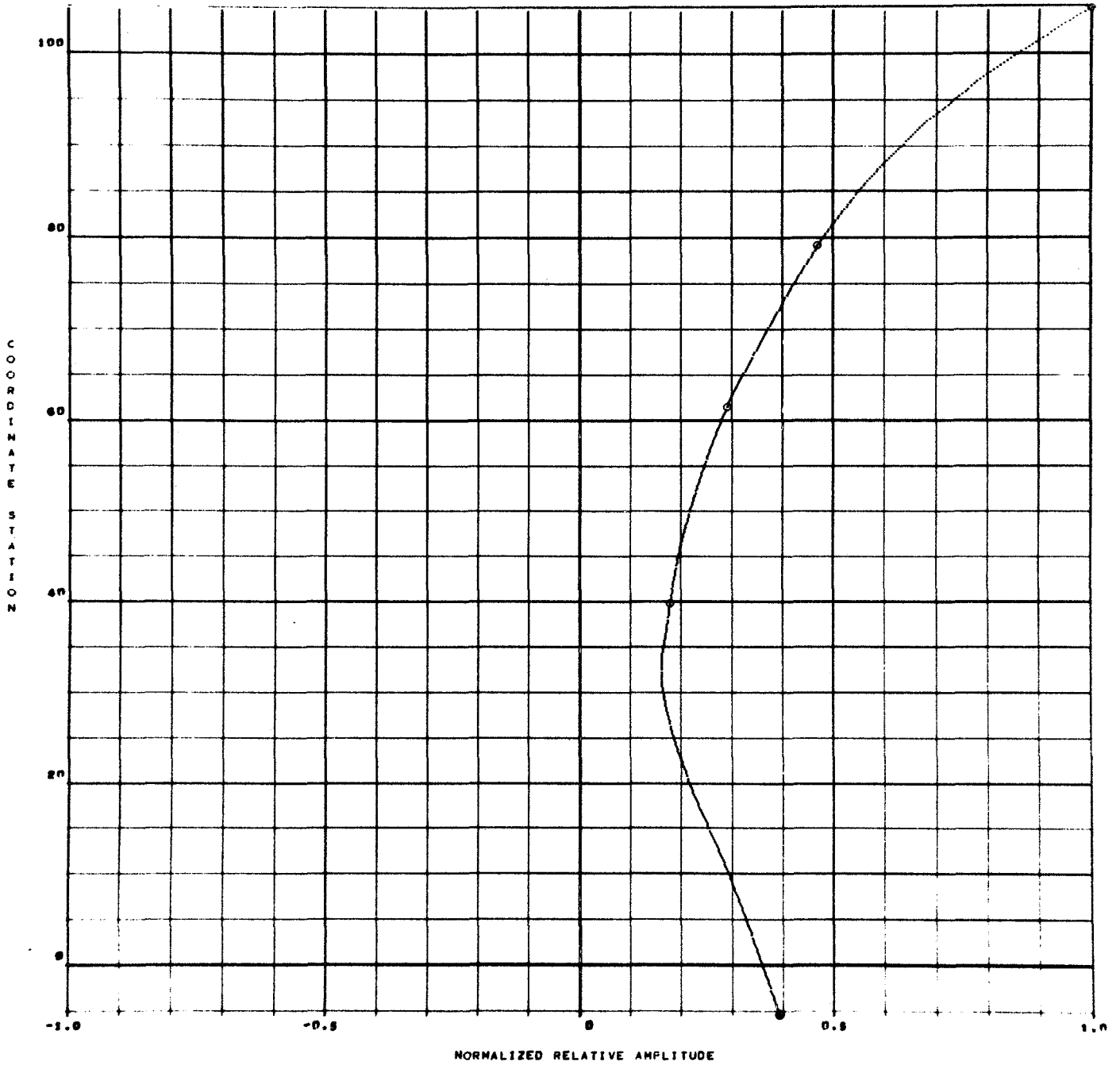


Fig. 19 - 8th Mode Shape (three slosh modes per tank)

SA-503 4-BEAM MODEL T = 0.0

5/08/69

MODE (9)

FREQUENCY = 0.590

GEN. MASS = 3.633x10⁺⁰⁷

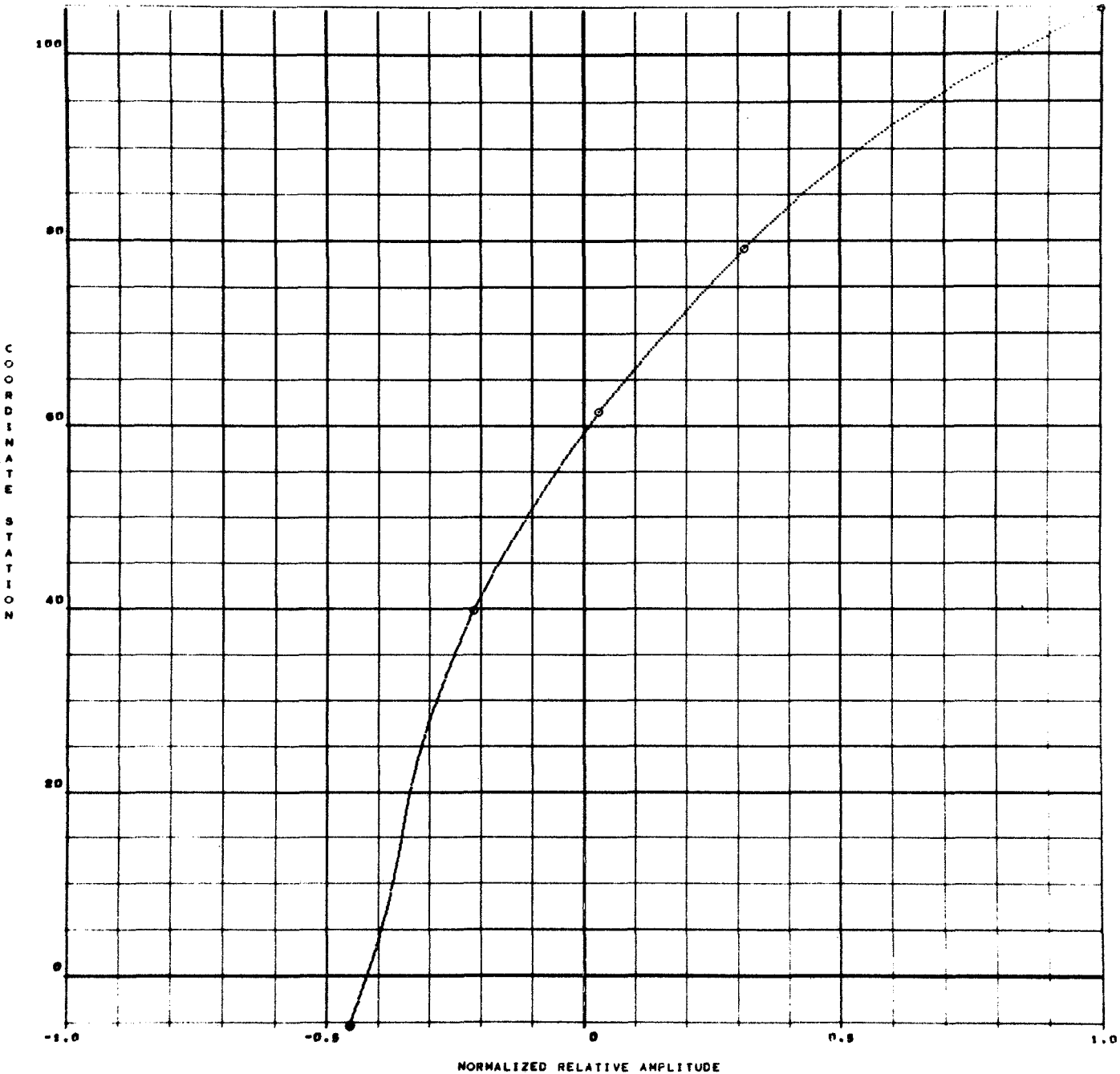


Fig. 20 - 9th Mode Shape (three slosh modes per tank)

SA-503 4-BEAM MODEL T = 0.0

5/08/69

MODE(10)

FREQUENCY = 0.594

GEN. MASS = 2.073x10⁺⁰⁸

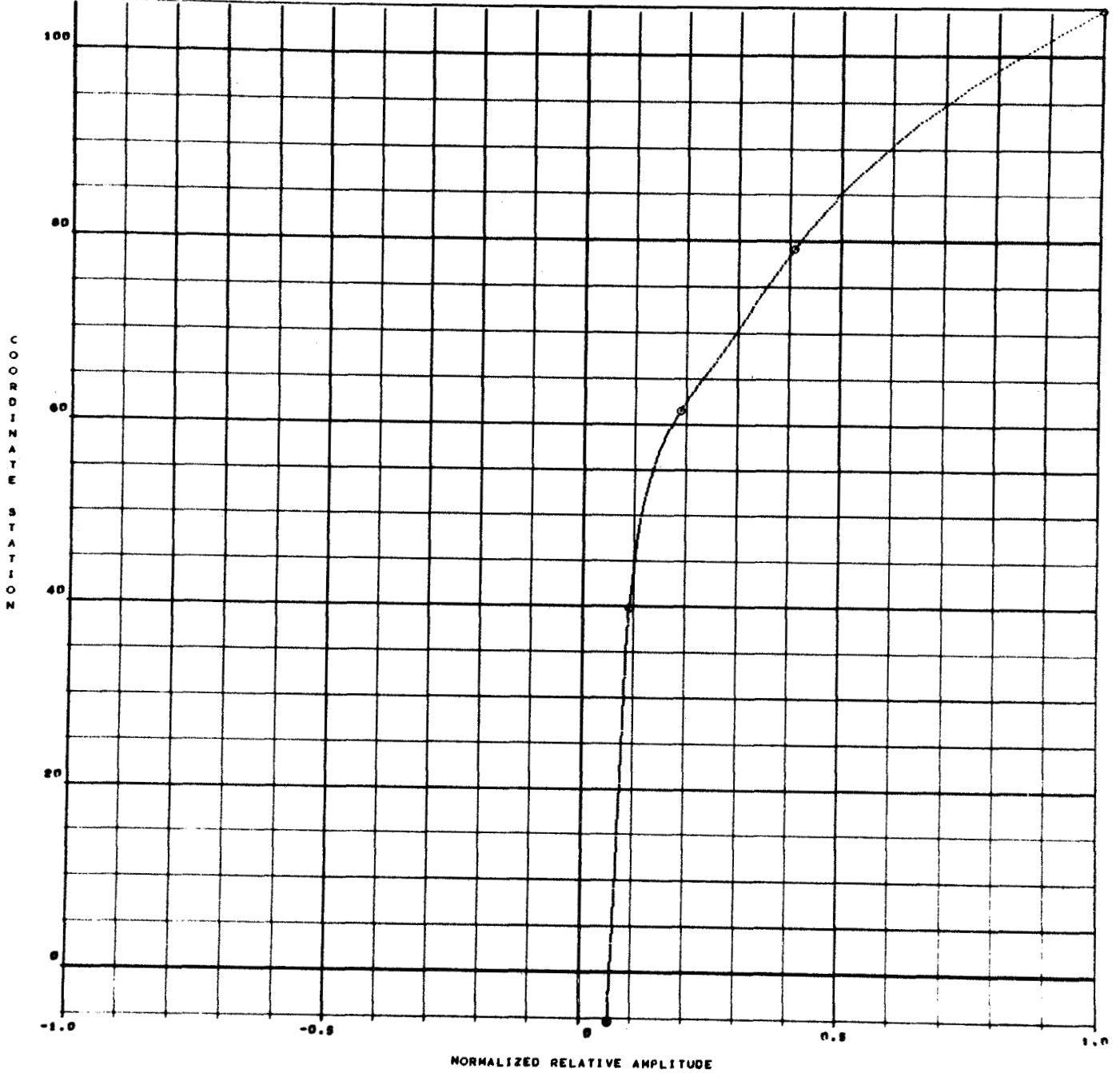


Fig. 21 - 10th Mode Shape (three slosh modes per tank)

SA-503 4-BEAM MODEL T = 0.0

5/08/69

MODE(11)

FREQUENCY = 0.612

GEN. MASS = 2.351X10¹⁰6

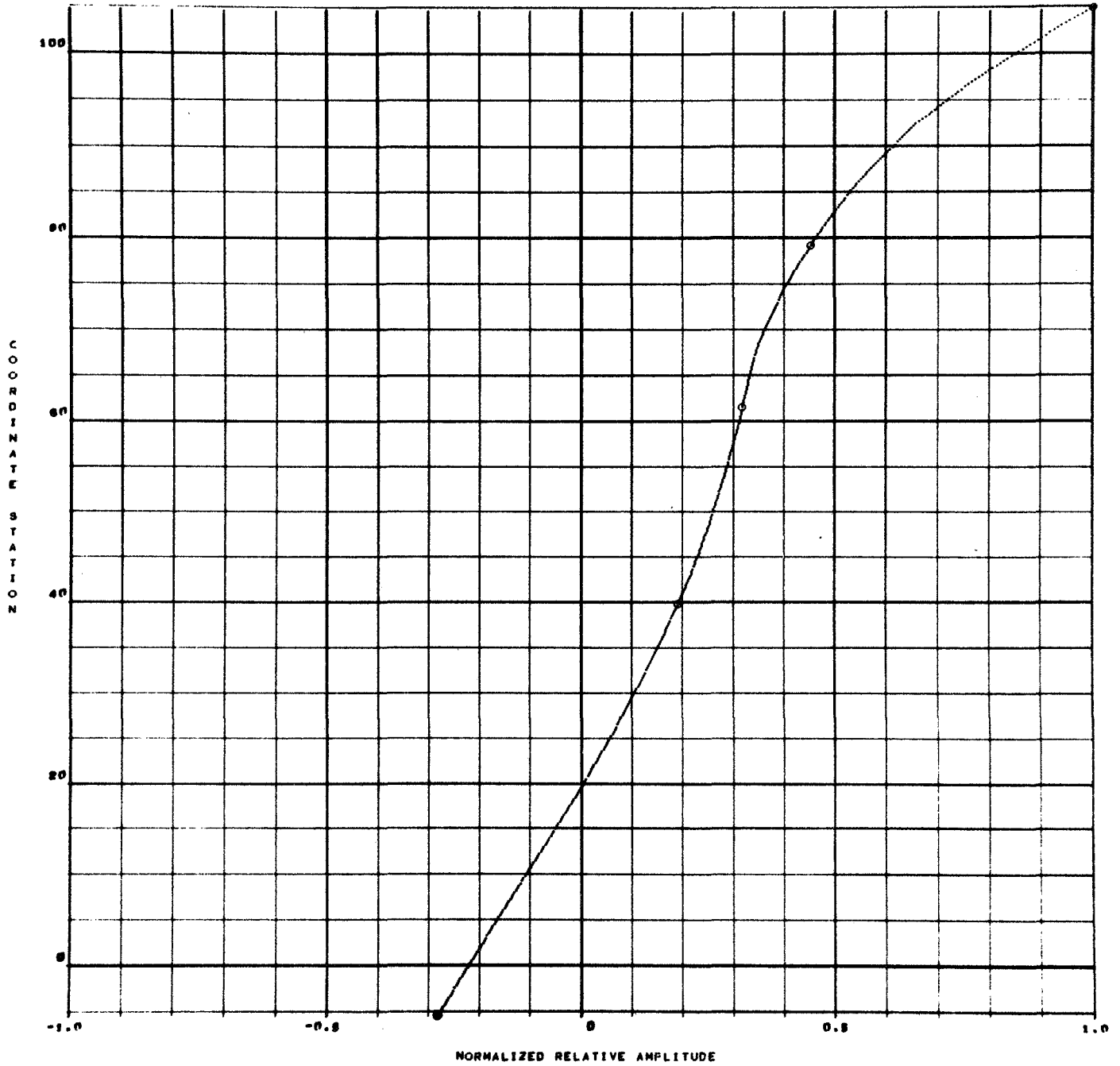


Fig. 22 - 11th Mode Shape (three slosh modes per tank)

SA-503 4-BEAM MODEL T = 0.0

5/08/69

MODE (12)

FREQUENCY = 0.626

GEN. MASS = 1.402x10⁰⁶

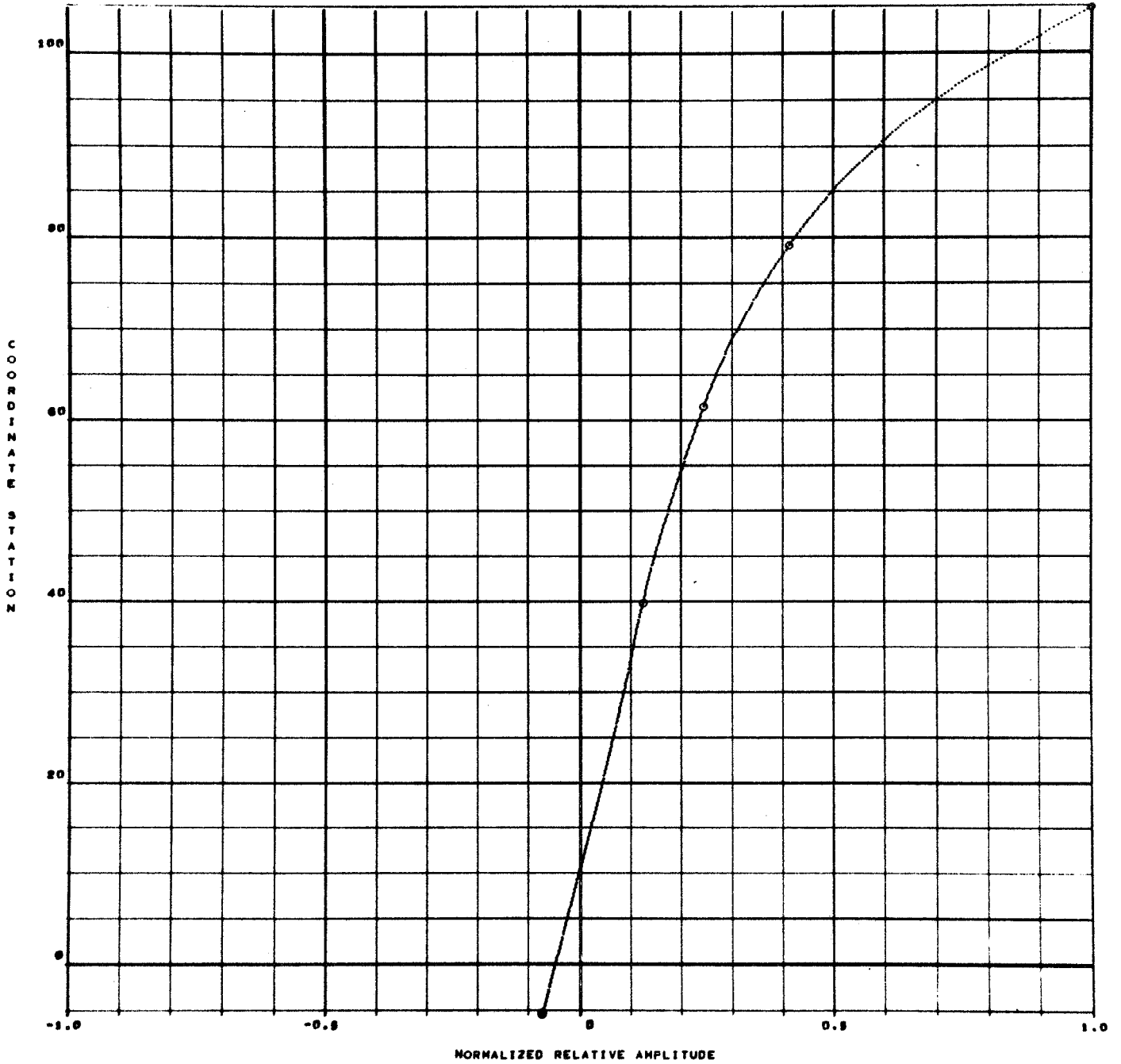


Fig. 23 - 12th Mode Shape (three slosh modes per tank)

SA-503 4-BEAM MODEL T = 0.0

5/08/69

MODE(13)

FREQUENCY = 0.711

GEN. MASS = 2.445X10⁺⁰⁷

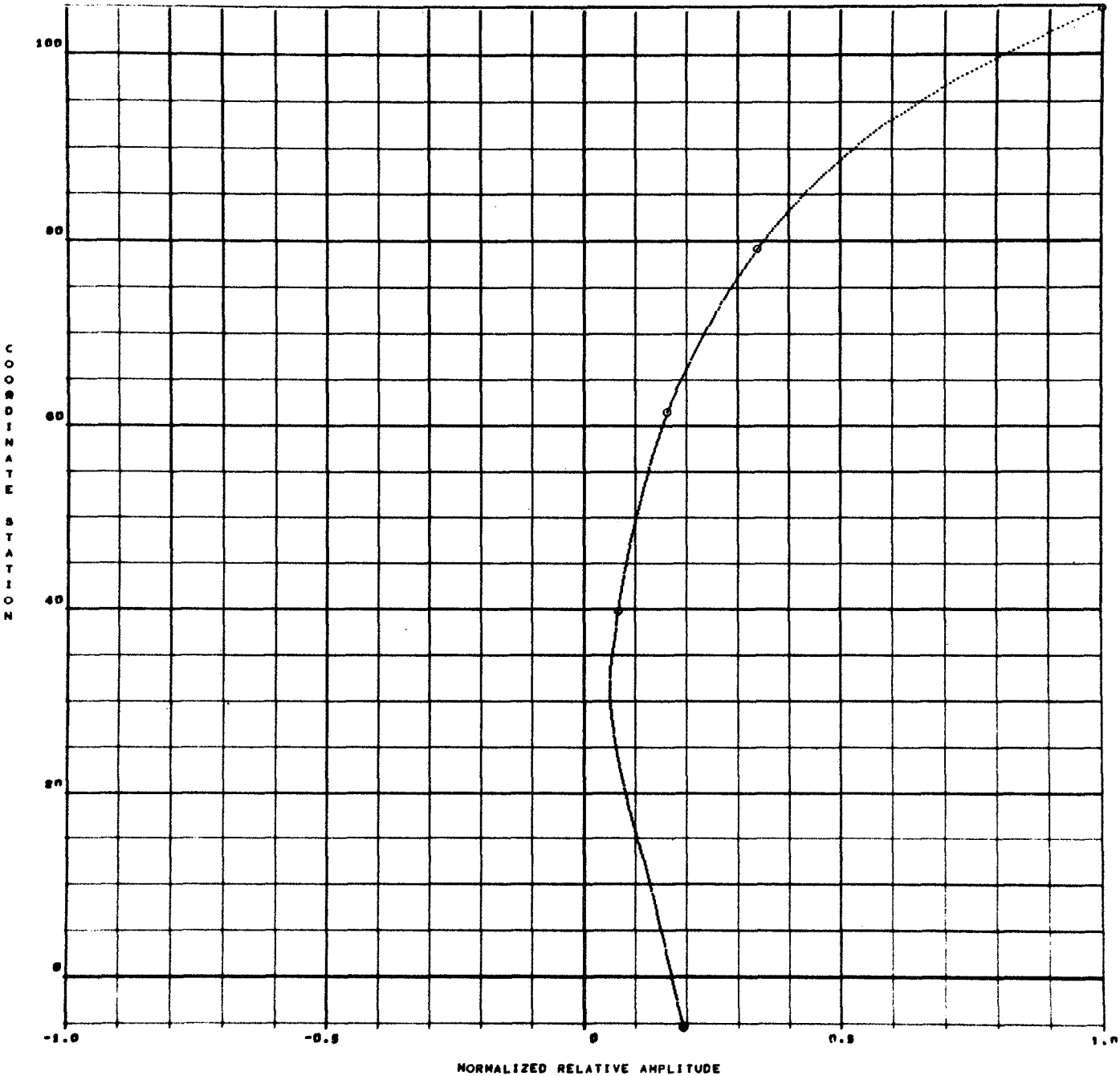


Fig. 24 - 13th Mode Shape (three slosh modes per tank)

SA-303 4-BEAM MODEL T = 0.0

5/06/69

MODE (14)

FREQUENCY = 0.741

GEN. MASS = 2.220x10⁺⁰⁷

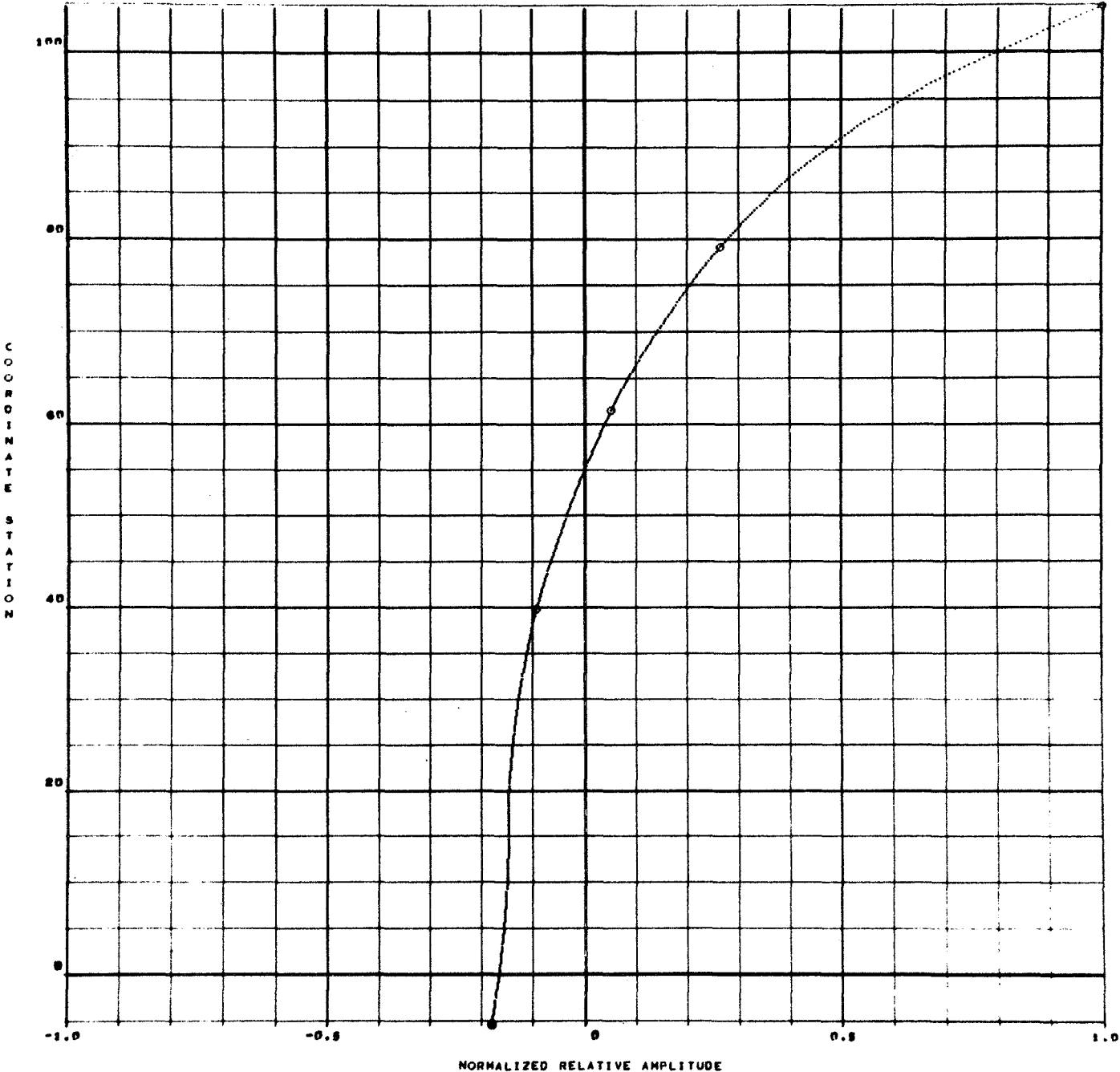


Fig. 25 - 14th Mode Shape (three slosh modes per tank)

SA-503 4-BEAM MODEL T = 0.0

5/08/69

MODE (15)

FREQUENCY = 0.747

GEN. MASS = 5.155x10⁺⁰⁷

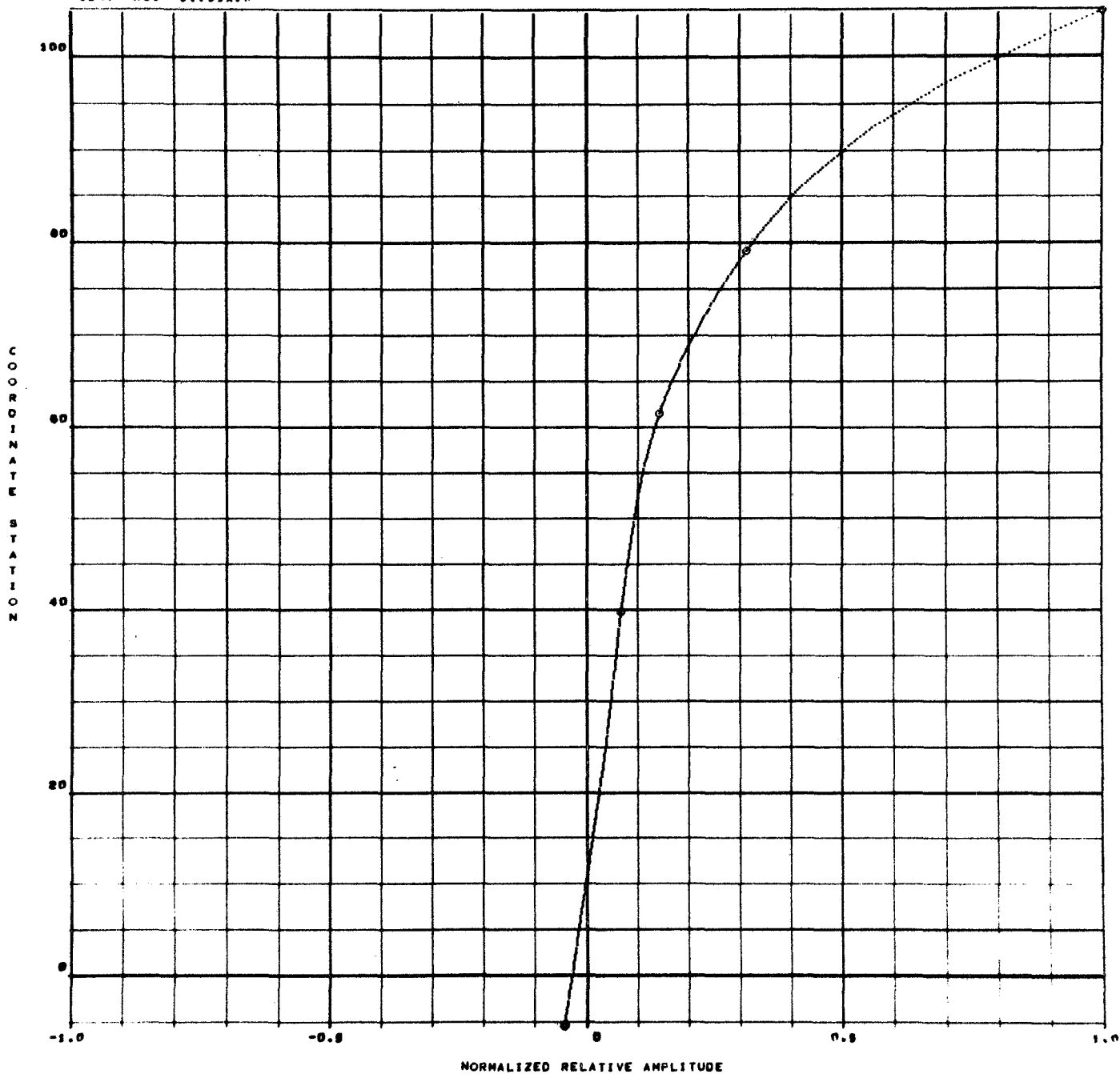


Fig. 26 - 15th Mode Shape (three slosh modes per tank)

SA-503 4-BEAM MODEL T = 0.0

5/08/69

MODE(16)

FREQUENCY = 0.782

GEN. MASS = 3.127x10⁺⁰⁶

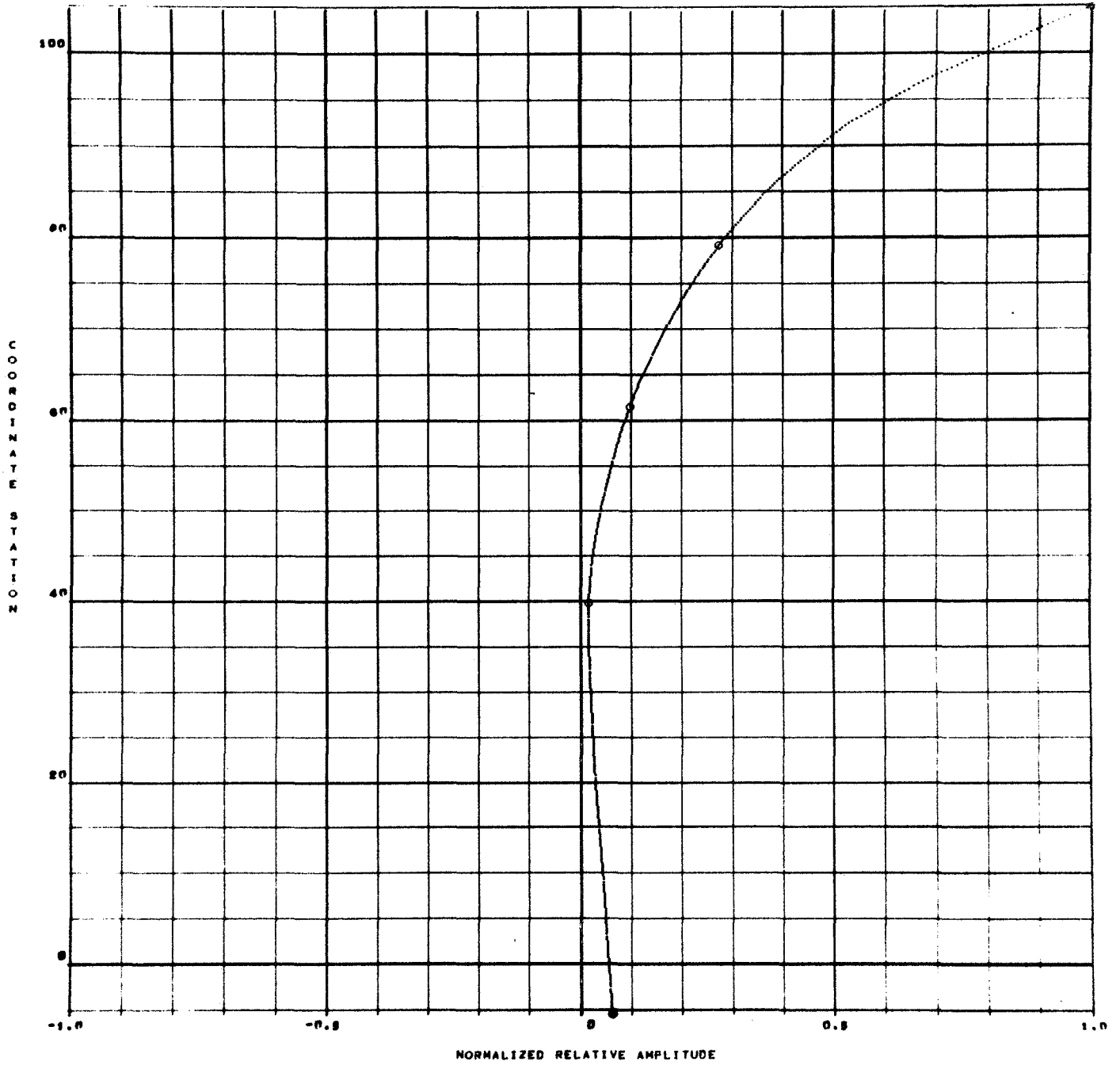


Fig. 27 - 16th Mode Shape (three slosh modes per tank)

SA-503 4-BEAM MODEL T = 0.0

5/08/69

MODE(17)

FREQUENCY = 0.002

GEN. MASS = 3.992X10⁺⁰⁸

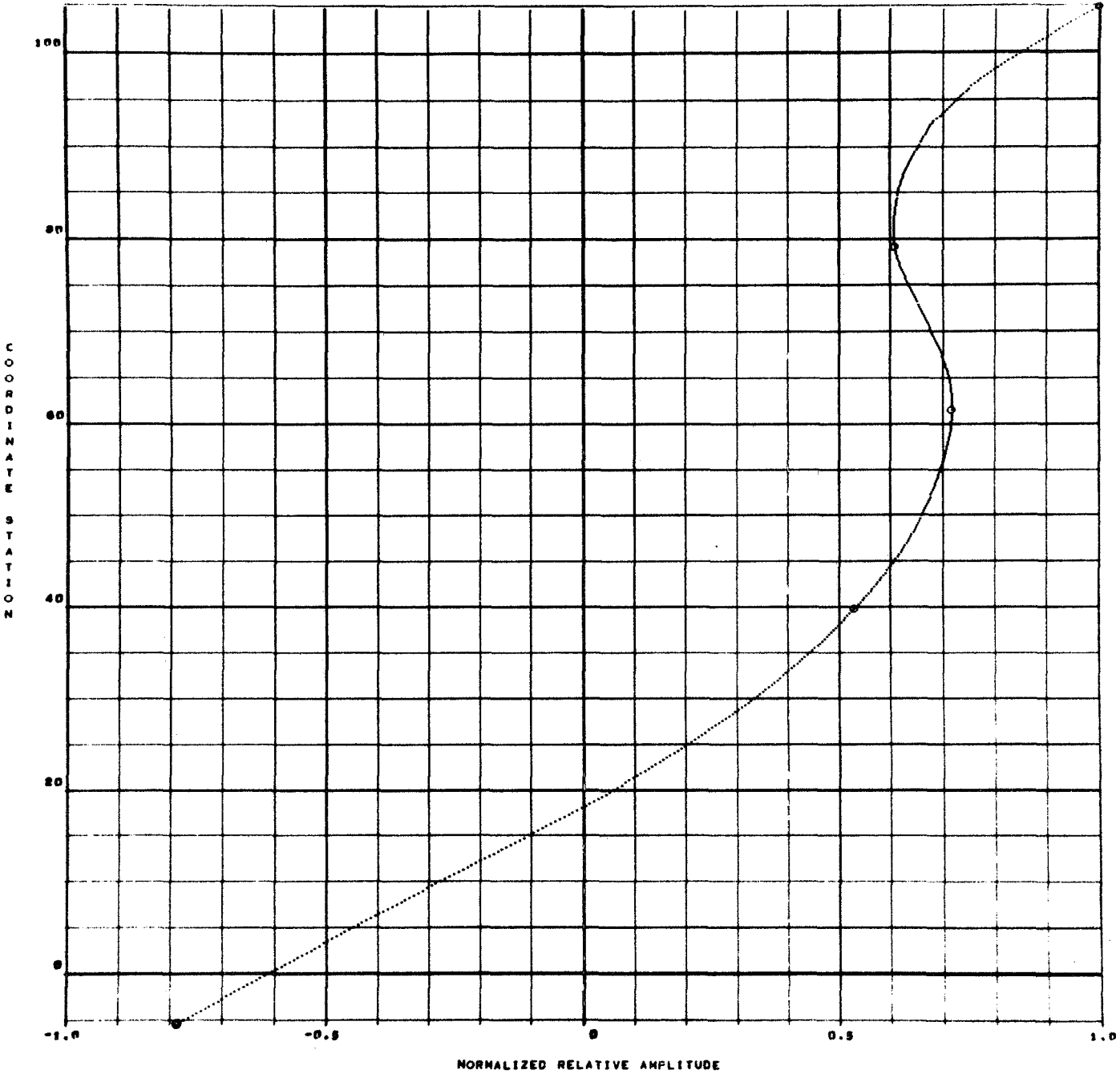


Fig. 28 - 17th Mode Shape (three slosh modes per tank)

SA-503 4-BEAM MODEL T = 0.0

5/08/69

MODE(18)

FREQUENCY = 0.917

GEN. MASS = 6.231X10⁺⁰⁶

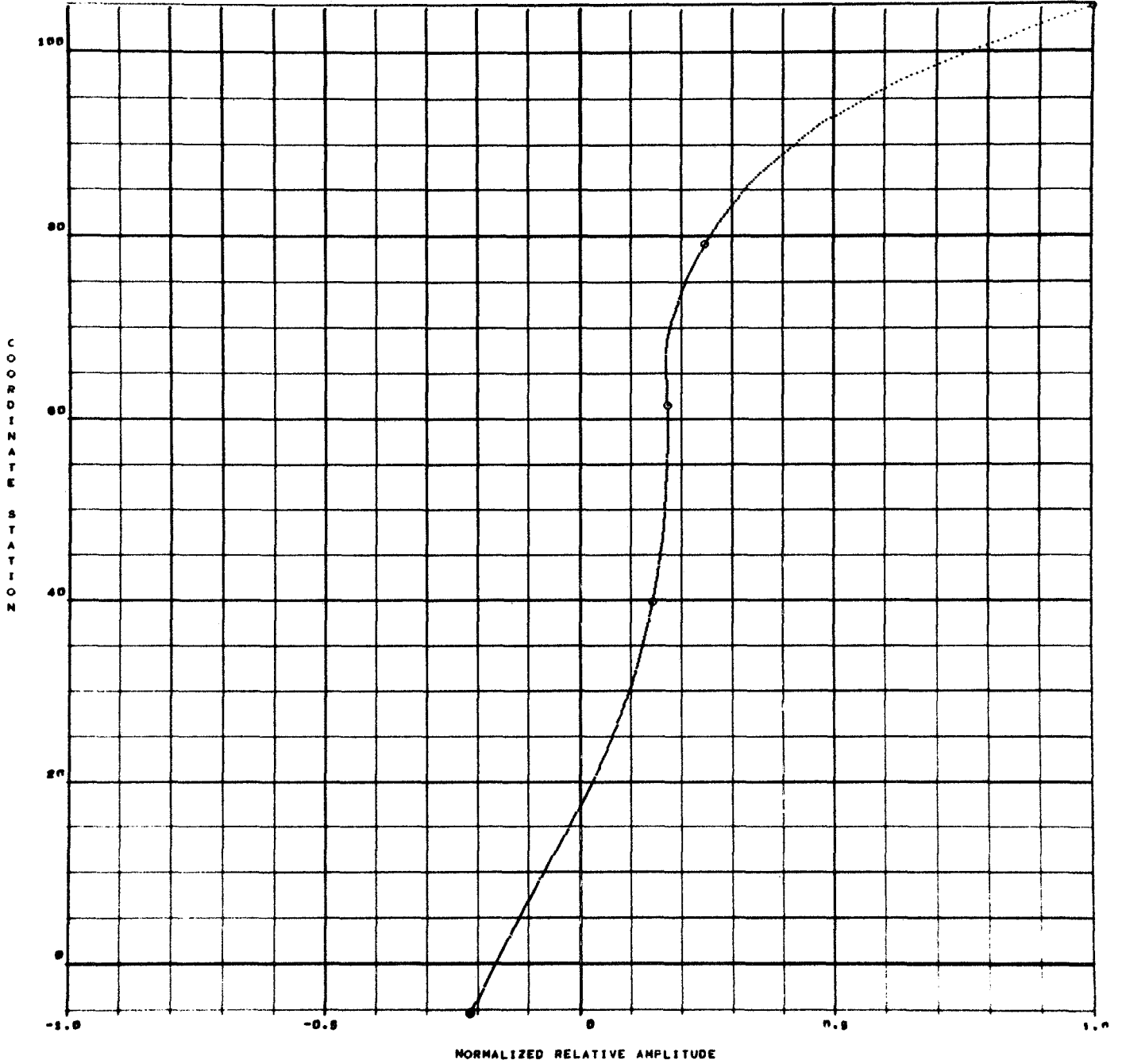


Fig. 29 - 18th Mode Shape (three slosh modes per tank)

SA-503 4-BEAM MODEL T = 0.0

5/08/69

MODE(19)

FREQUENCY = 1.003

GEN. MASS = 5.275X10⁰⁵

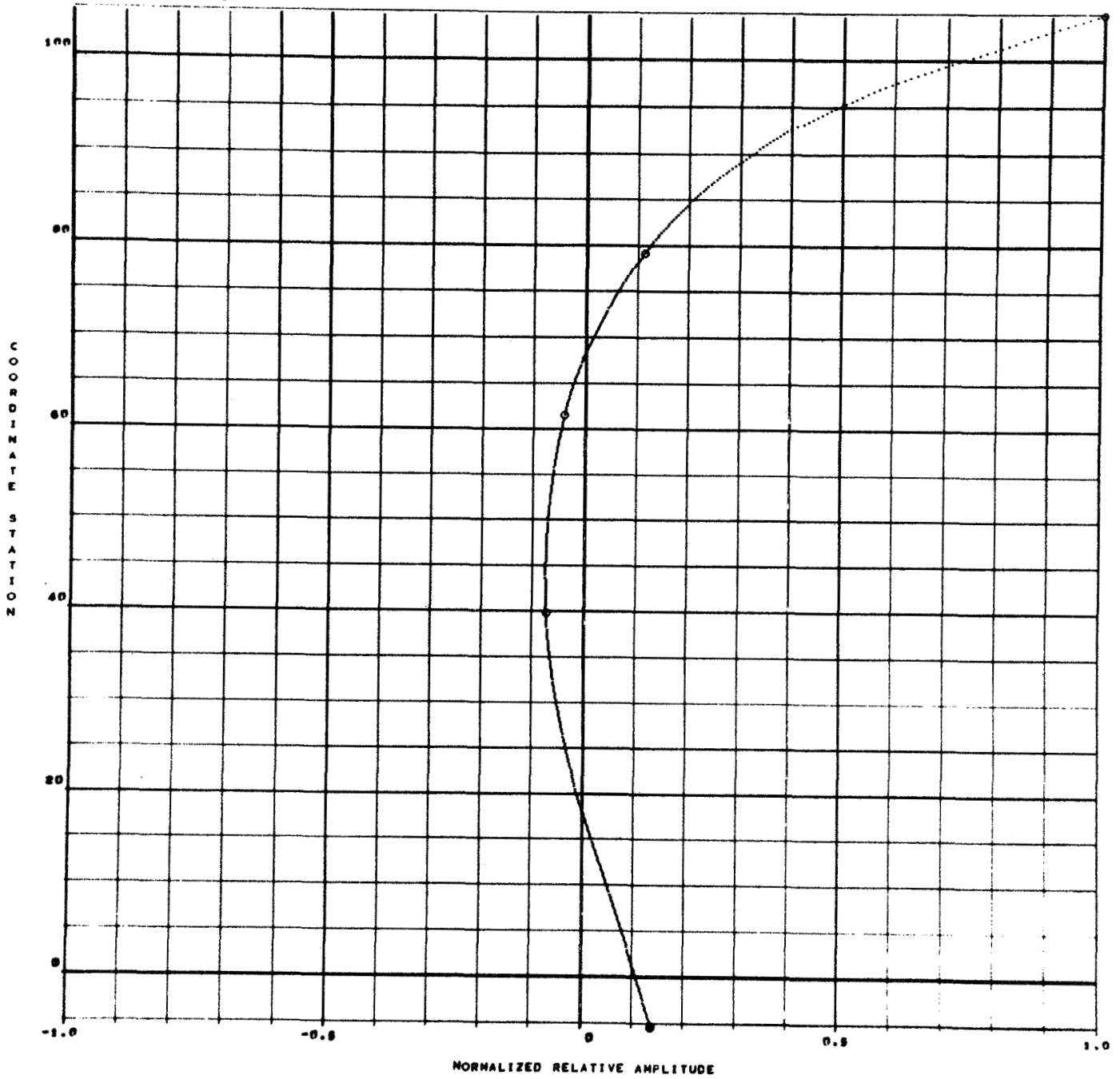


Fig. 30 - 19th Mode Shape (three slosh modes per tank)

SA-503 4-BEAM MODEL T = 0.0

5/08/69

MODE(20)

FREQUENCY = 1.018

GEN. MASS = 1.119X10⁺⁰⁴

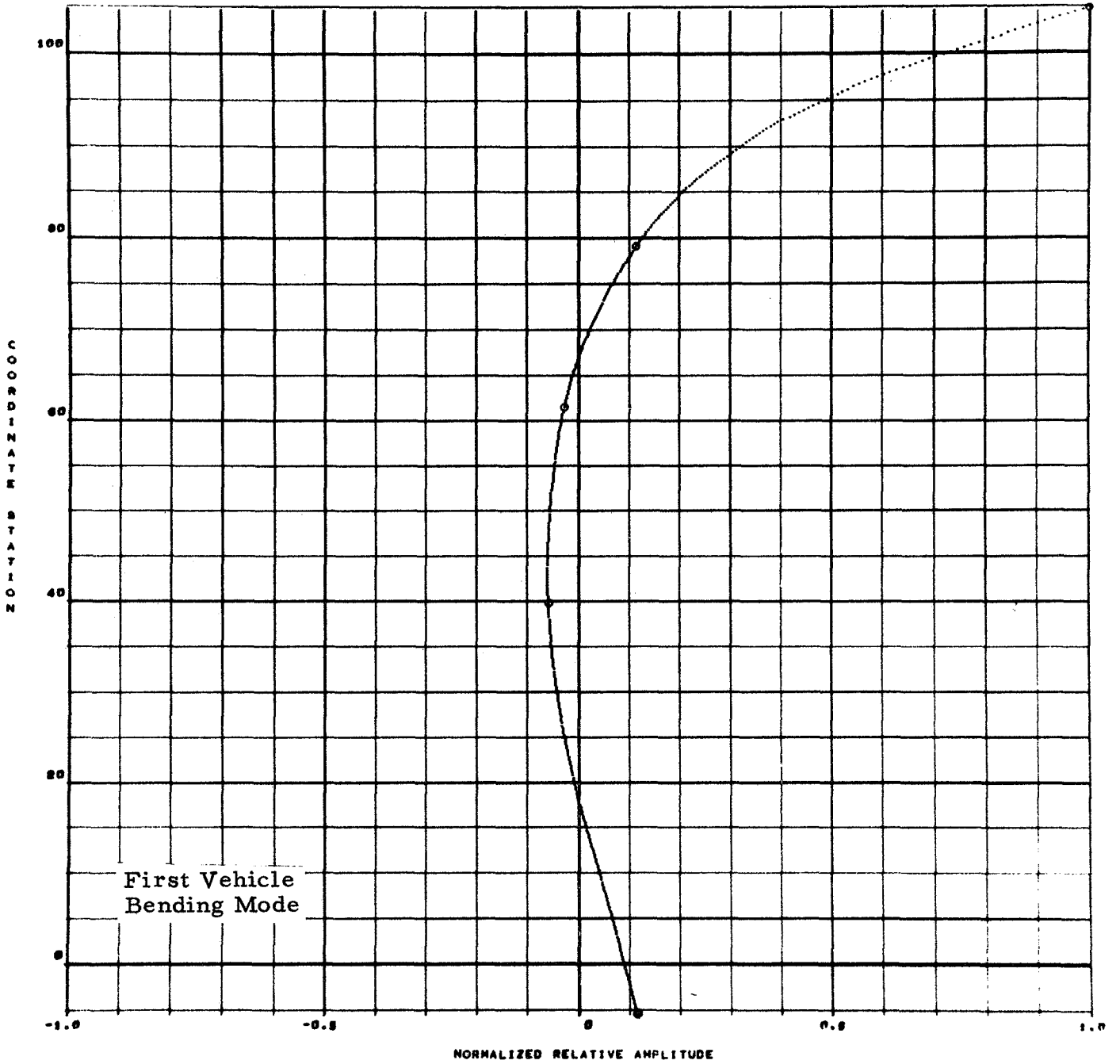


Fig. 31 - 20th Mode Shape (three slosh modes per tank)

SA-503 4-BEAM MODEL T = 0.0

5/18/69

MODE (21)

FREQUENCY = 1.142

GEN. MASS = 4.308x10⁺⁰⁶

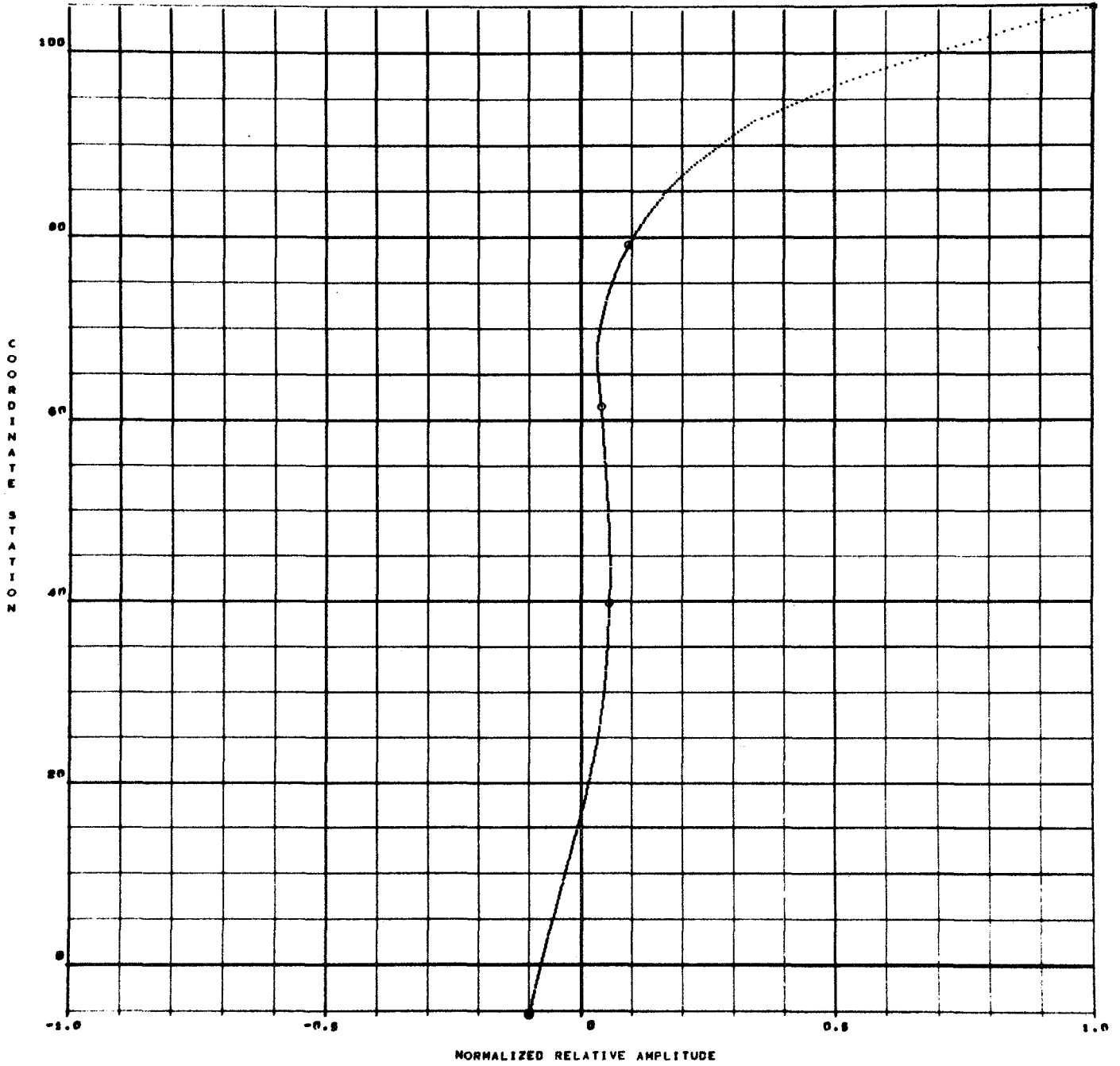


Fig. 32 - 21st Mode Shape (three slosh modes per tank)

SA-503 4-BEAM MODEL T = 0.0

5/08/69

MODE(22)

FREQUENCY = 1.744

GEN. MASS = 3.822x10⁺⁰³

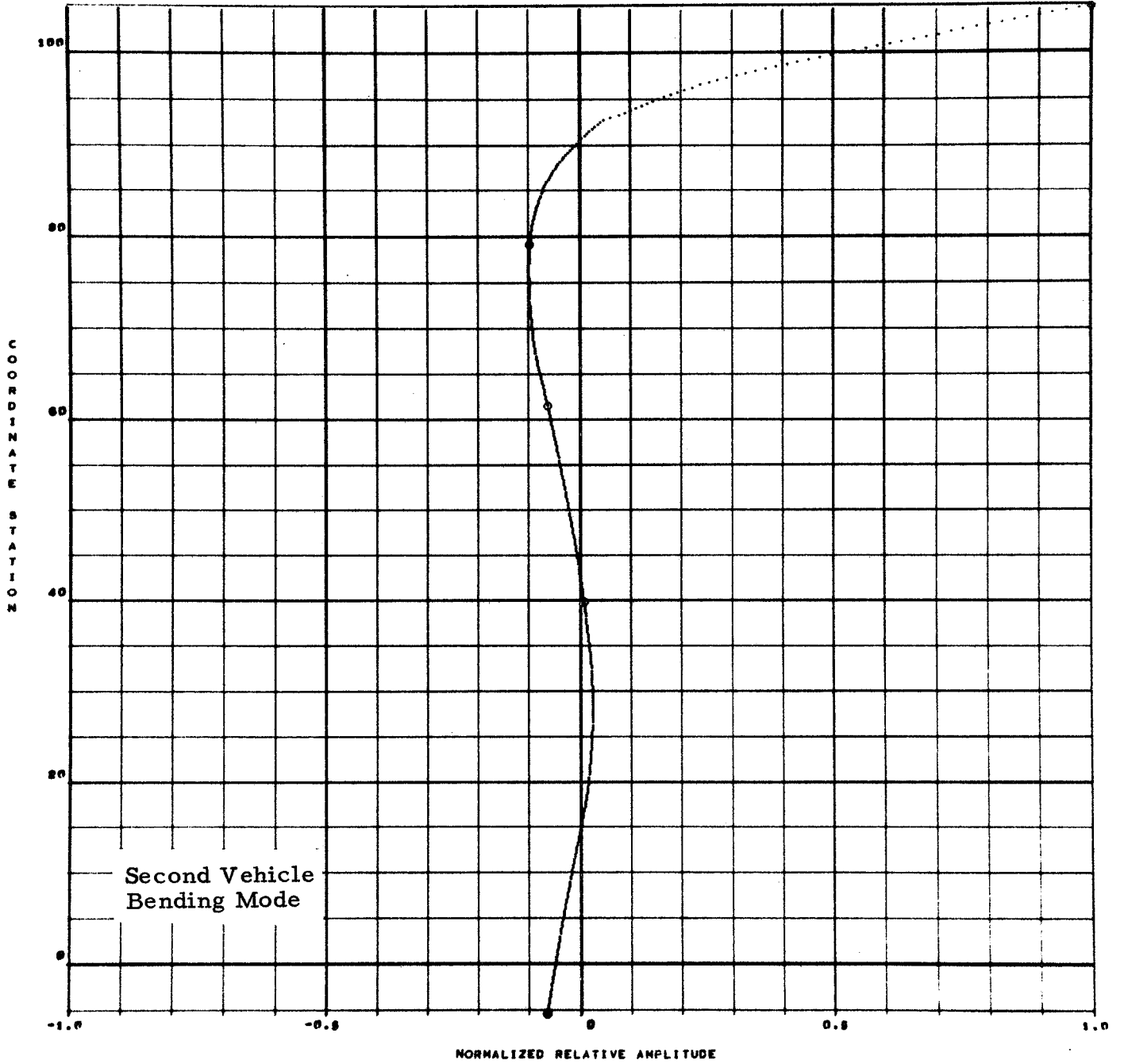


Fig. 33 - 22nd Mode Shape (three slosh modes per tank)

8A-503 4-BEAM MODEL T = 0.0

5/08/69

MODE(23)
FREQUENCY = 2.521
GEN. MASS = 3.078X10⁺⁰³

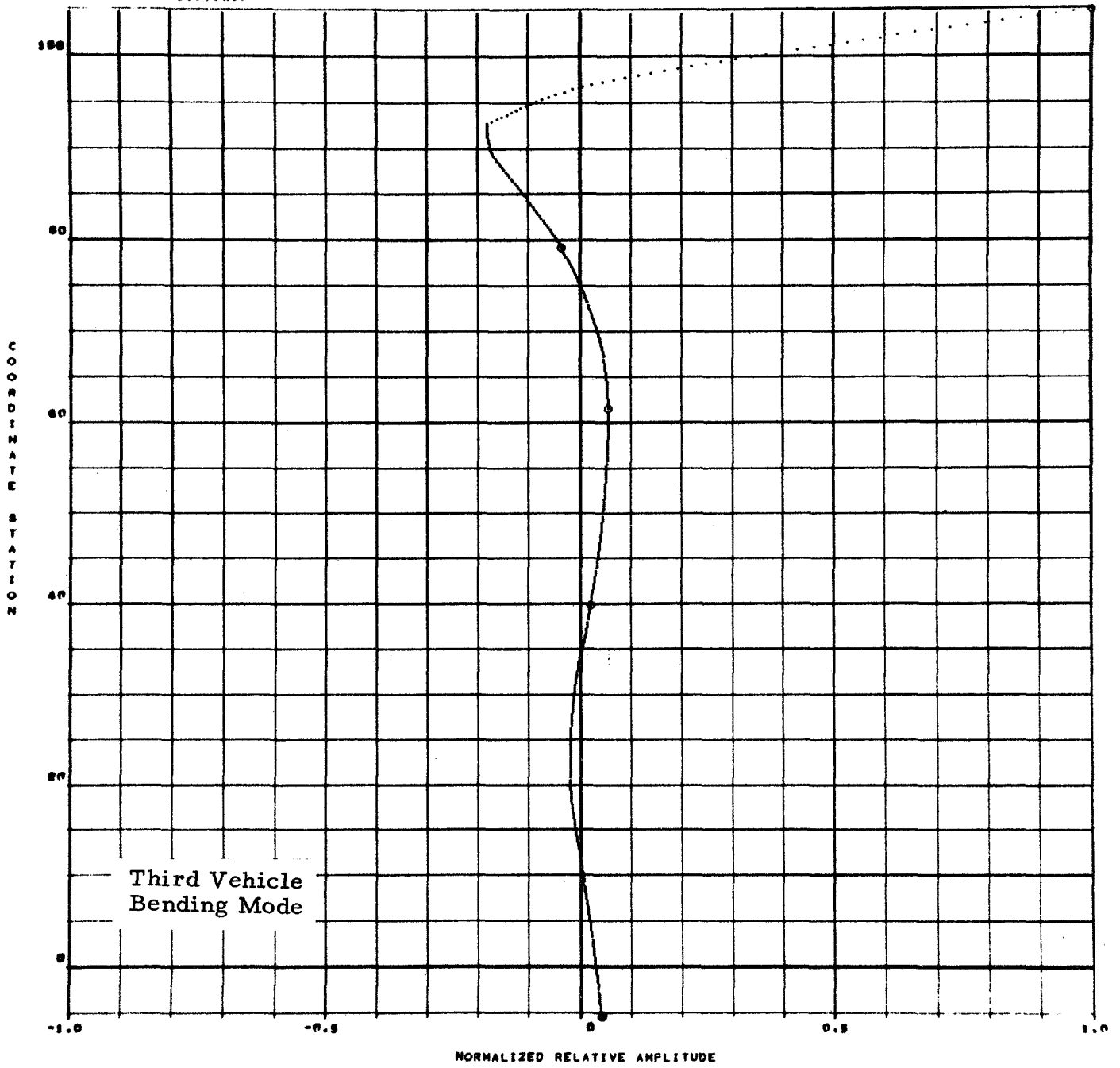


Fig. 34 - 23rd Mode Shape (three slosh modes per tank)

SA-503 4-BEAM MODEL T = 0.0

5/08/69

MODE (24)

FREQUENCY = 3.756

GEN. MASS = 1.690X10⁰⁴

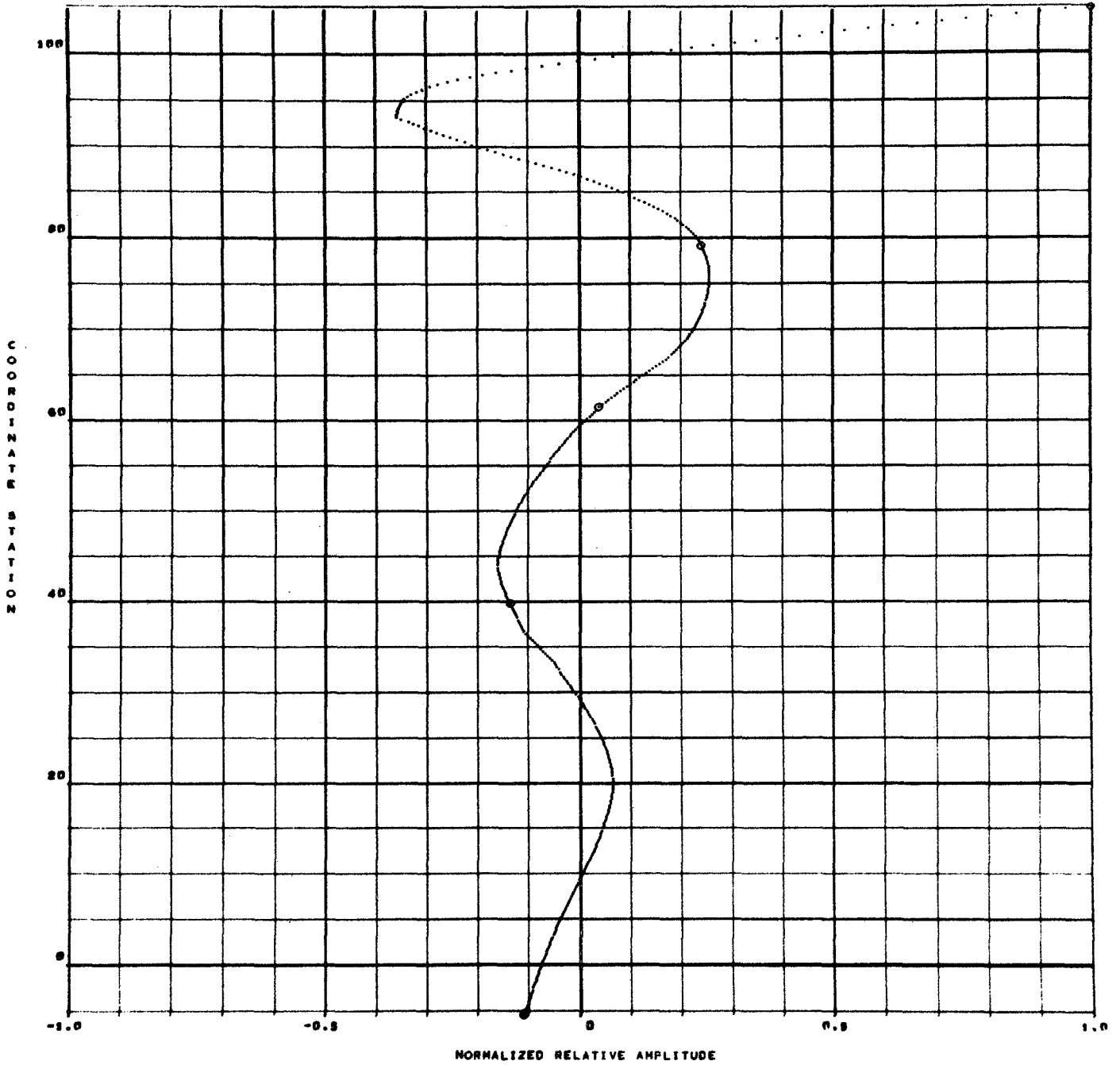


Fig. 35 - 24th Mode Shape (three slosh modes per tank)

SA-503 4-BEAM MODEL T = 0.0

5/08/69

MODE(25)

FREQUENCY = 6.541

GEN. MASS = 2.321 x 10⁺⁰⁴

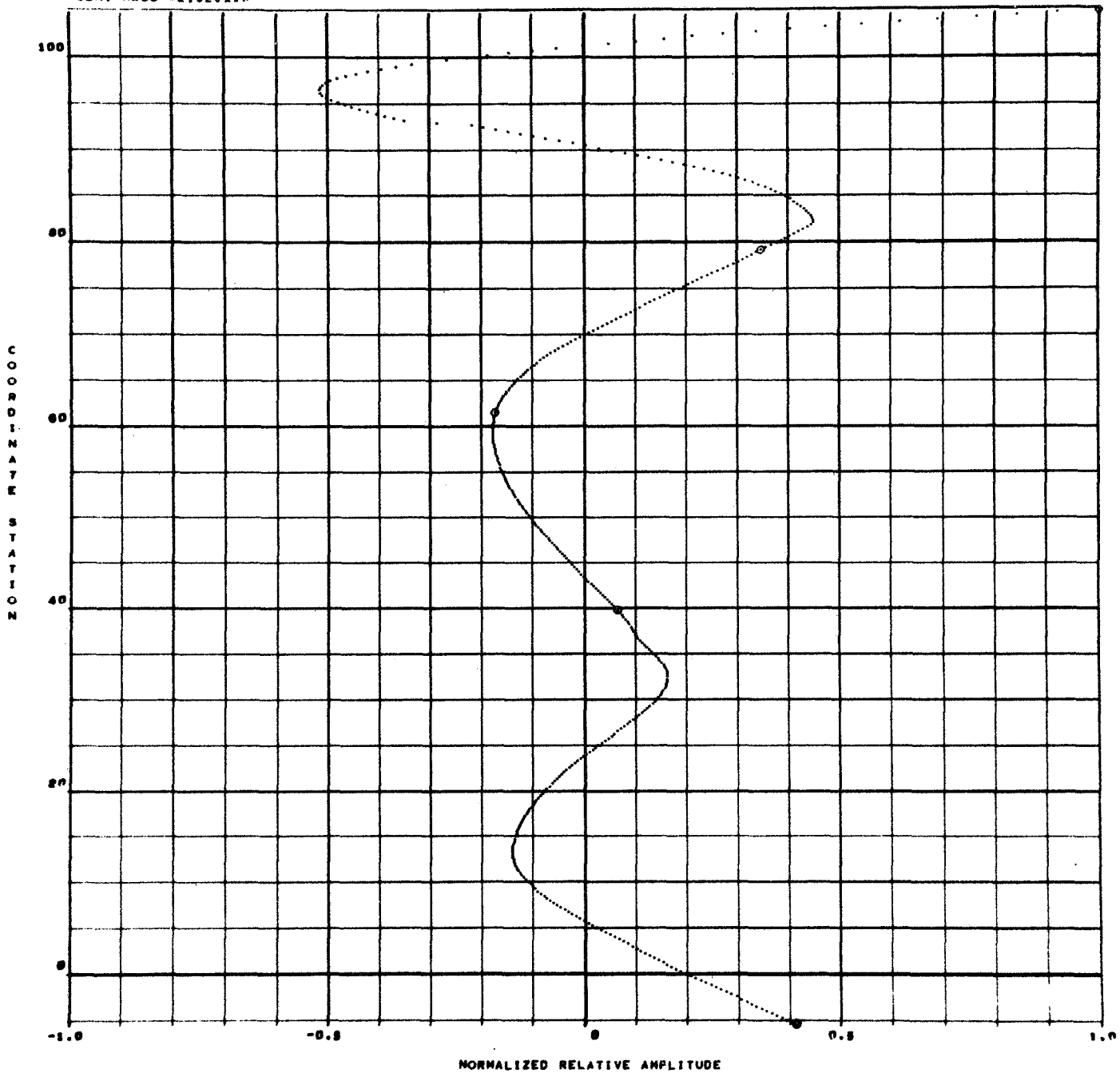


Fig. 36 - 25th Mode Shape (three slosh modes per tank)

SA-303 4-BEAM MODEL T = 0.0
MODE (1)
FREQUENCY = 0.000
GEN. MASS = 2.613 X 10⁰⁵

5/08/69

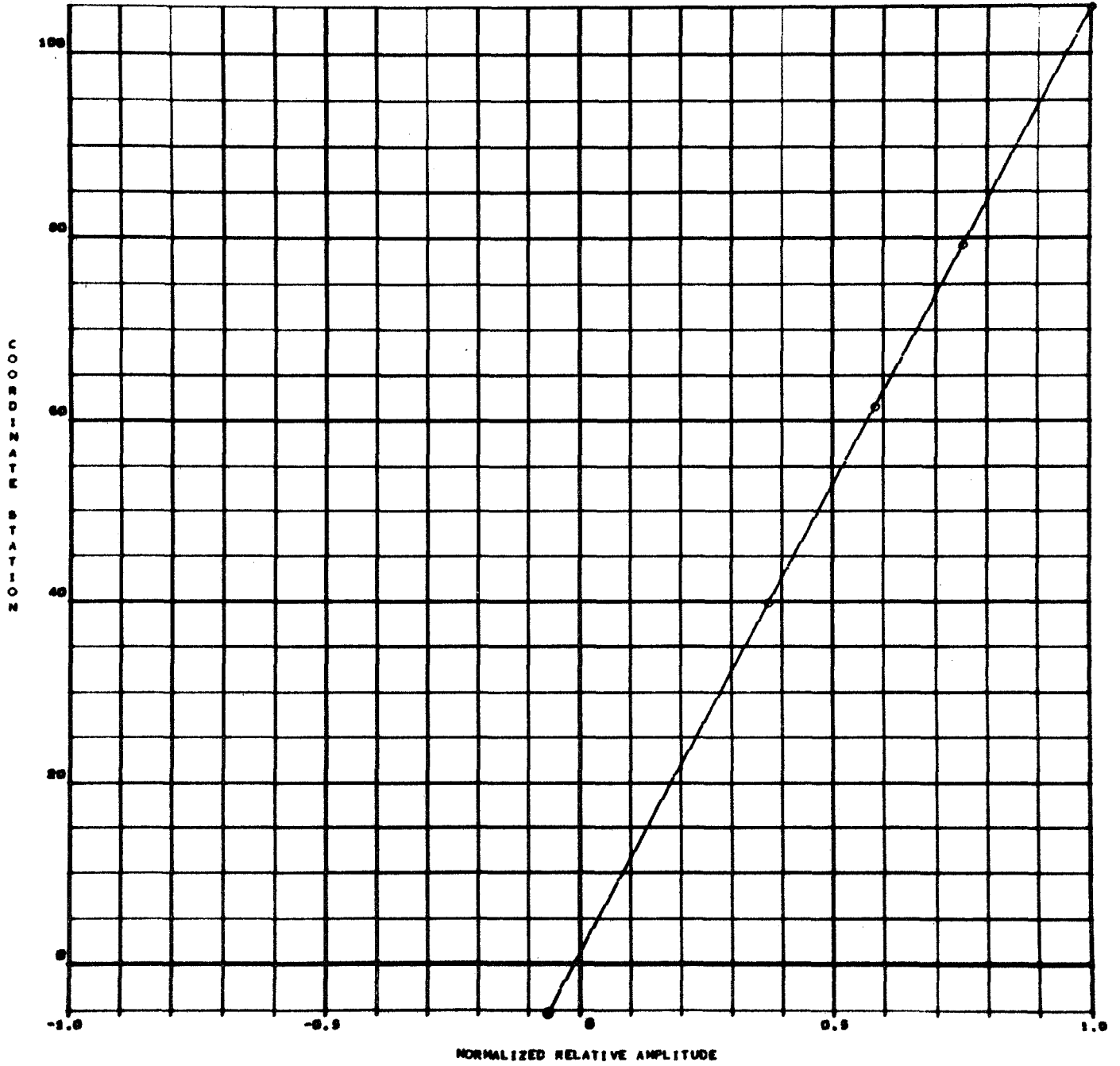


Fig. 37 - 1st Mode Shape (one slosh mode per tank)

SA-503 4-BEAM MODEL T = 0.0

5/08/69

MODE(2)

FREQUENCY = 0.000

GEN. MASS = 3.065x10⁰⁵

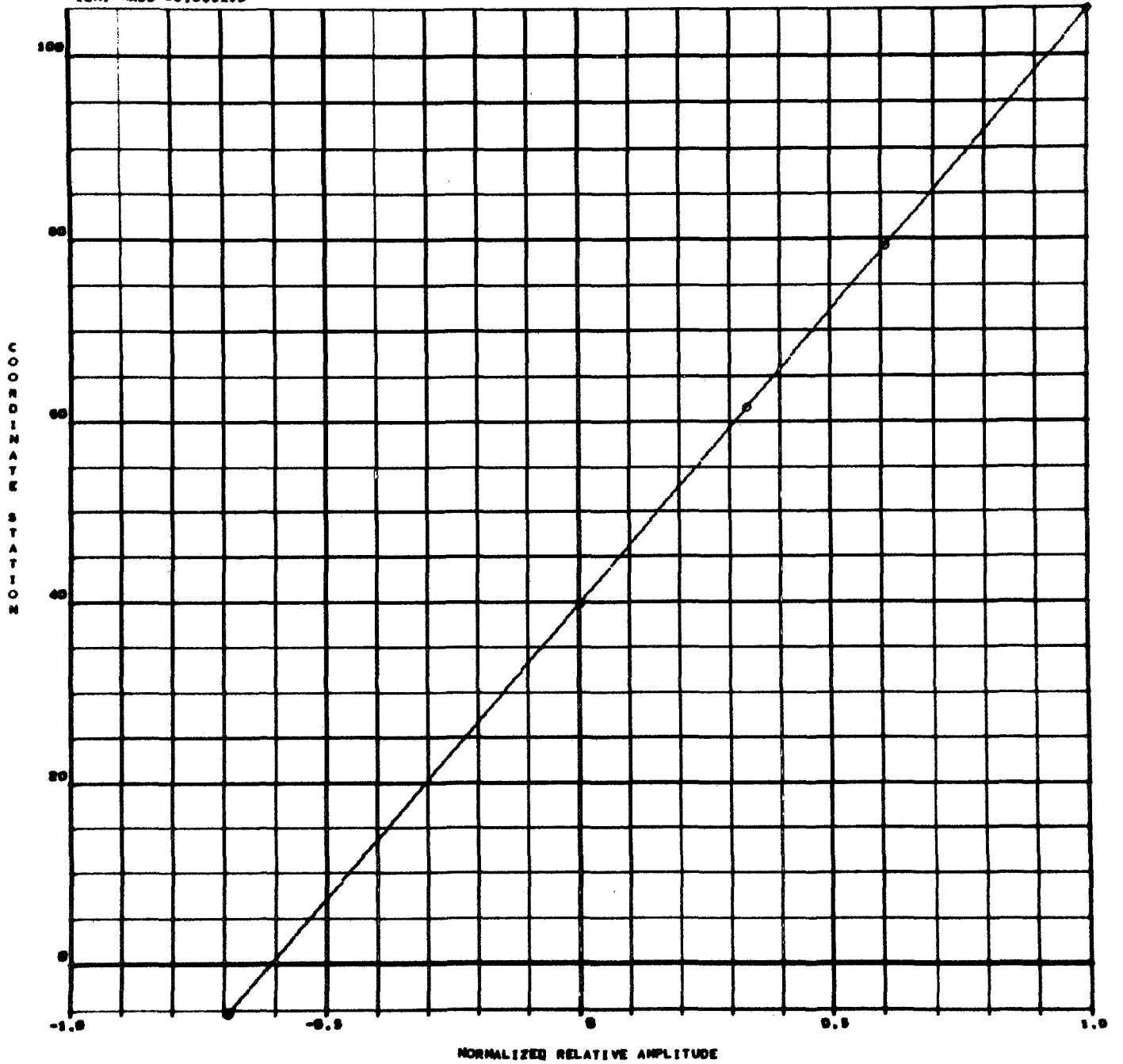


Fig. 38 - 2nd Mode Shape (one slosh mode per tank)

SA-503 4-BEAM MODEL T = 0.0
MODE (3)
FREQUENCY = 0.339
GEN. MASS = 1.344X10⁰⁷

5/06/69

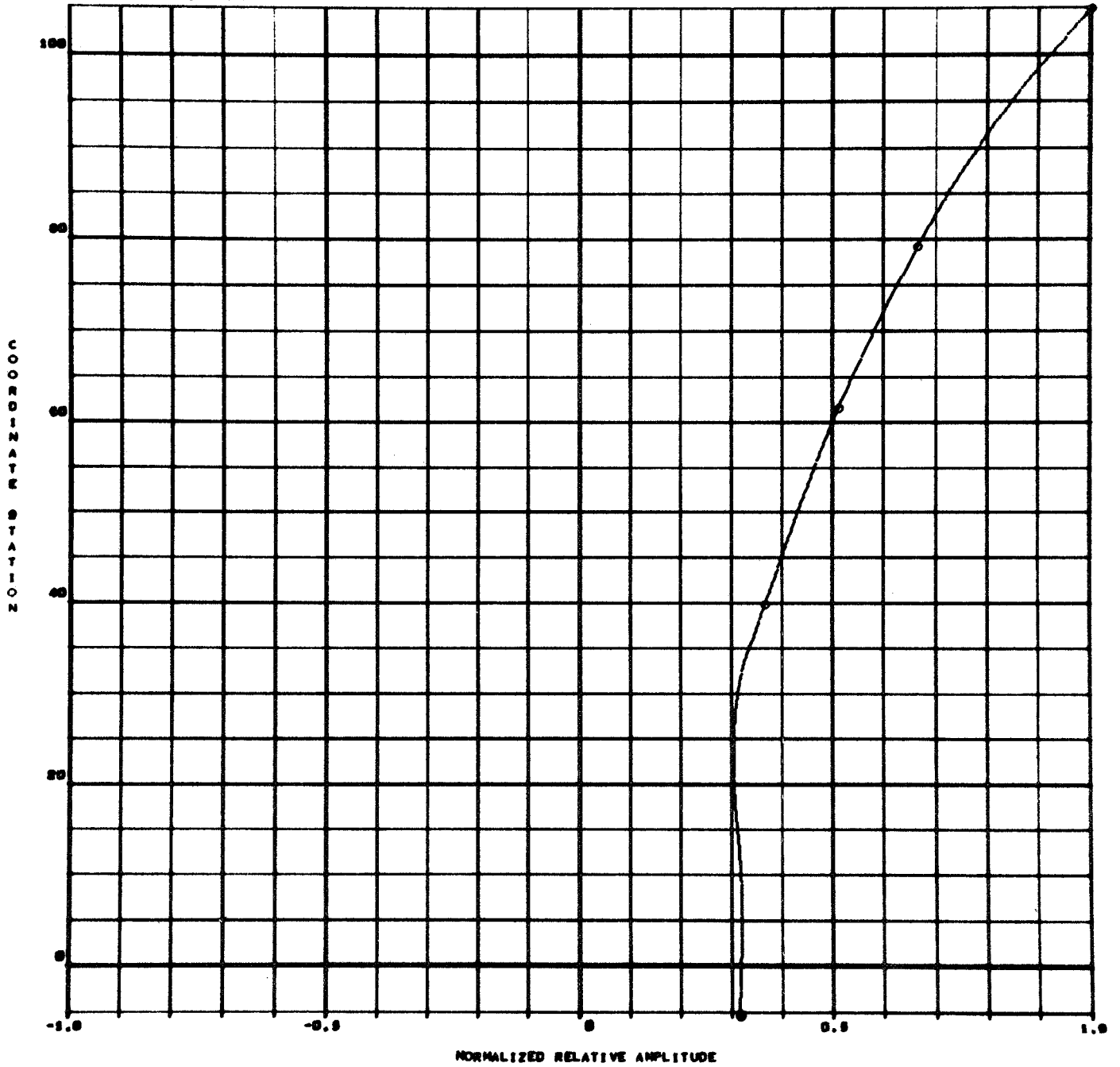


Fig. 39 - 3rd Mode Shape (one slosh mode per tank)

SA-303 4-BEAM MODEL T = 0.0
MODE(4)
FREQUENCY = 0.363
GEN. MASS = 4.000X10⁺⁰⁷

5/08/69

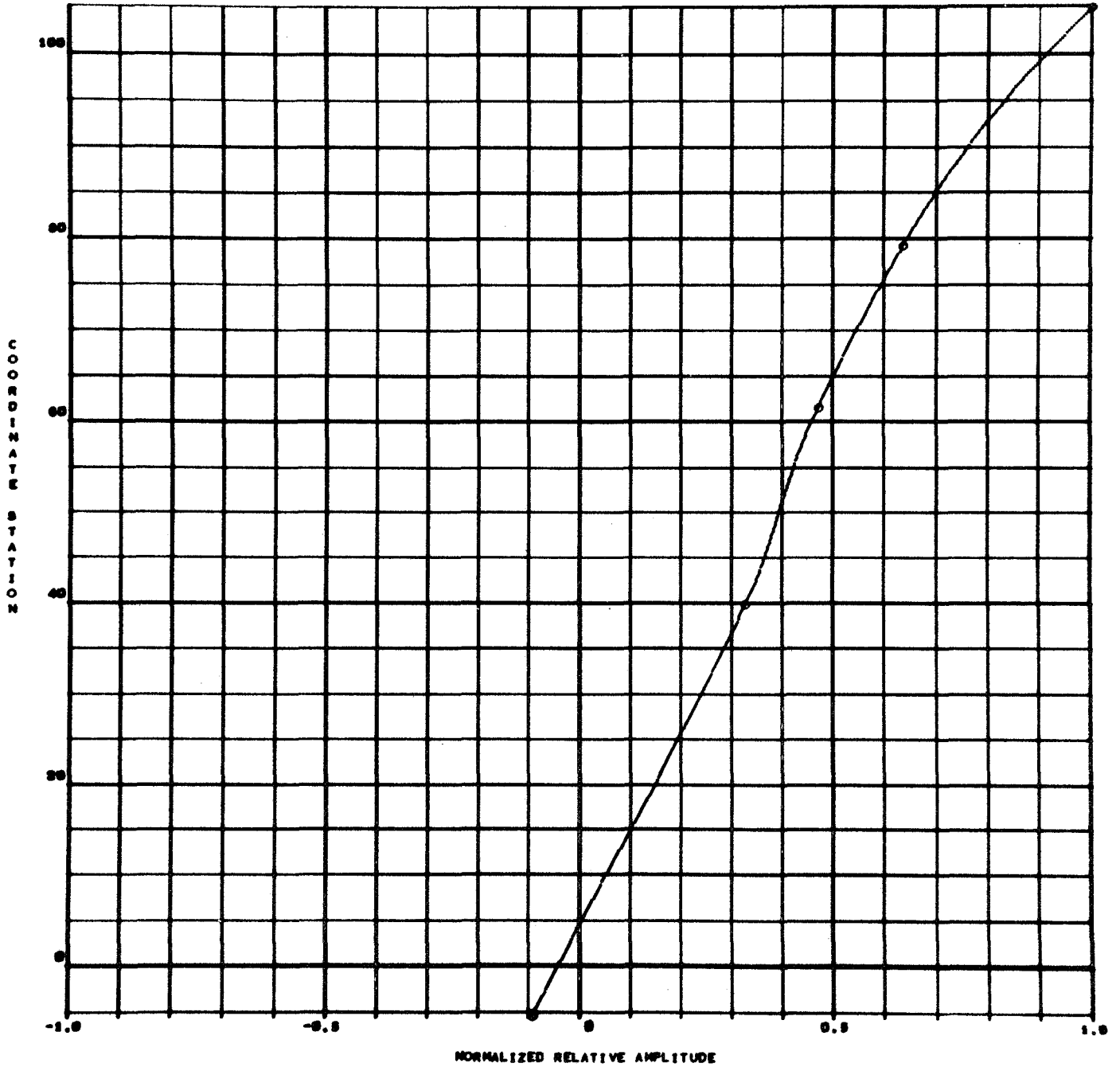


Fig. 40 - 4th Mode Shape (one slosh mode per tank)

SA-903 4-BEAM MODEL T = 0.0

5/08/89

MODE (5)

FREQUENCY = 0.376

GEN. MASS = 1.741X10⁺⁰⁶

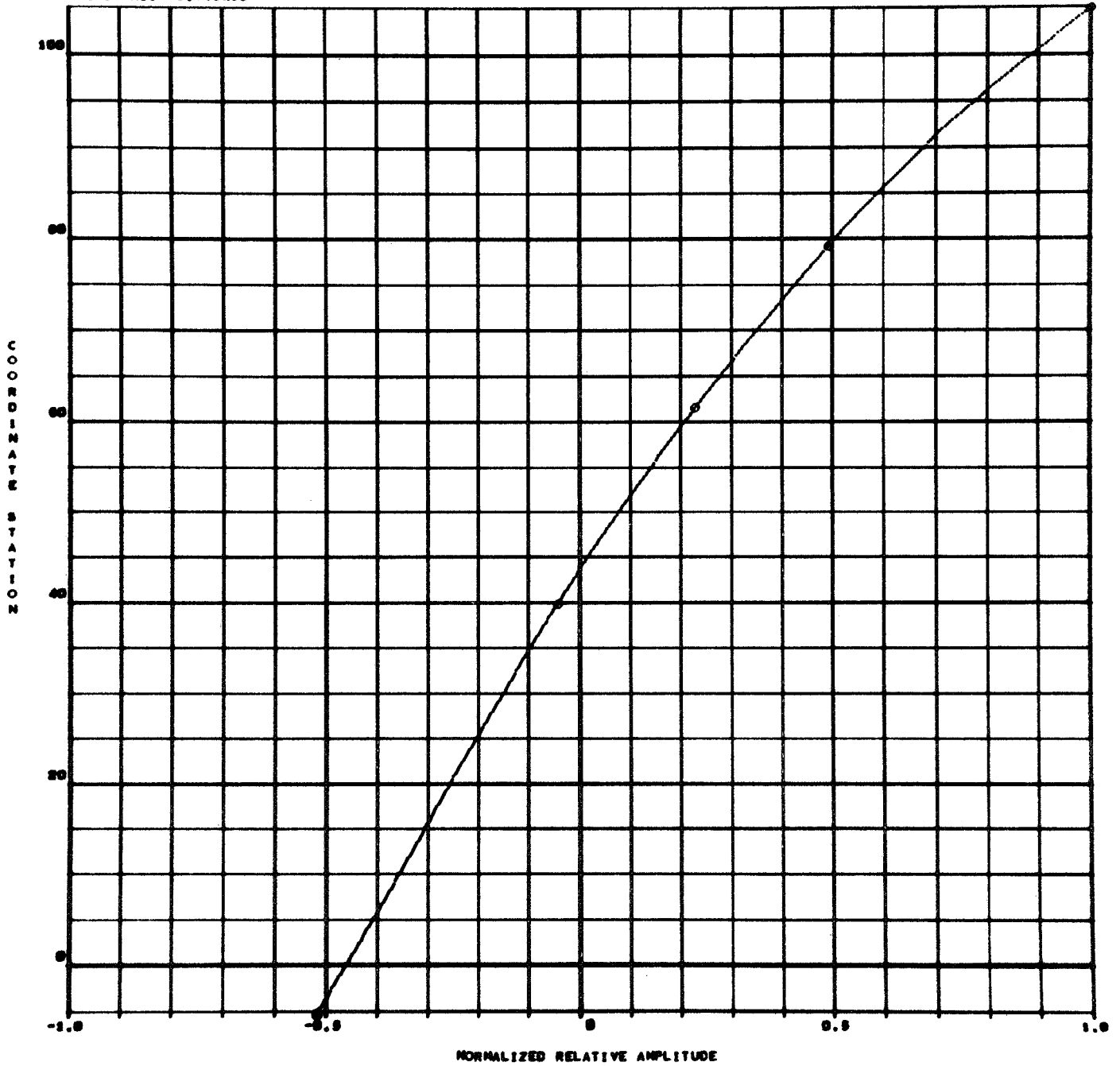


Fig.41 - 5th Mode Shape (one slosh mode per tank)

SA-303 4-BEAM MODEL T = 0.0

5/08/68

MODE (6)

FREQUENCY = 0.398

GEN. MASS = 1.460X10⁺⁰⁶

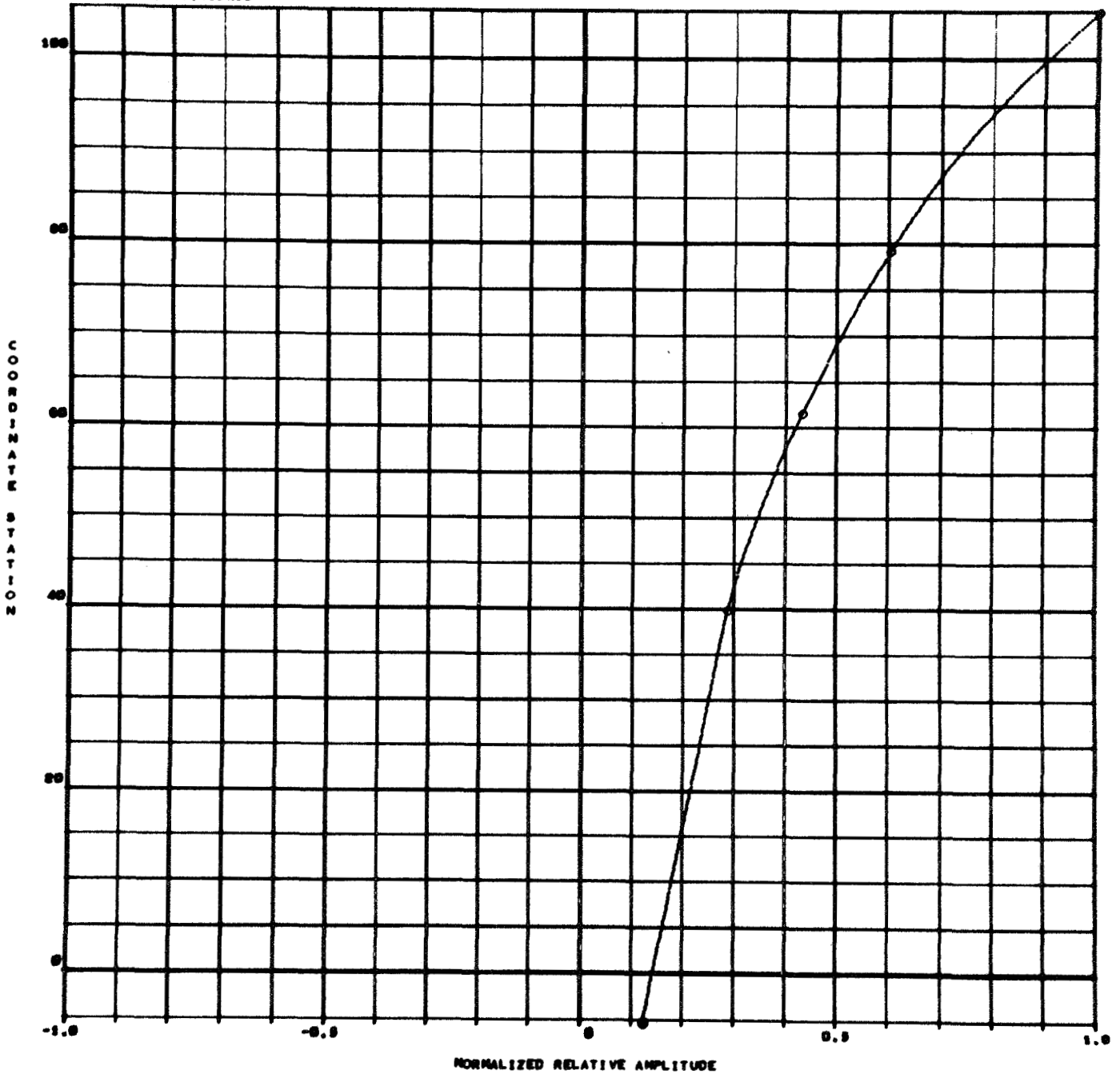


Fig. 42 - 6th Mode Shape (one slosh mode per tank)

SA-503 4-BEAM MODEL T = 0.0

5/08/69

MODE (7)

FREQUENCY = 0.511

GEN. MASS = 1.799X10⁰⁷

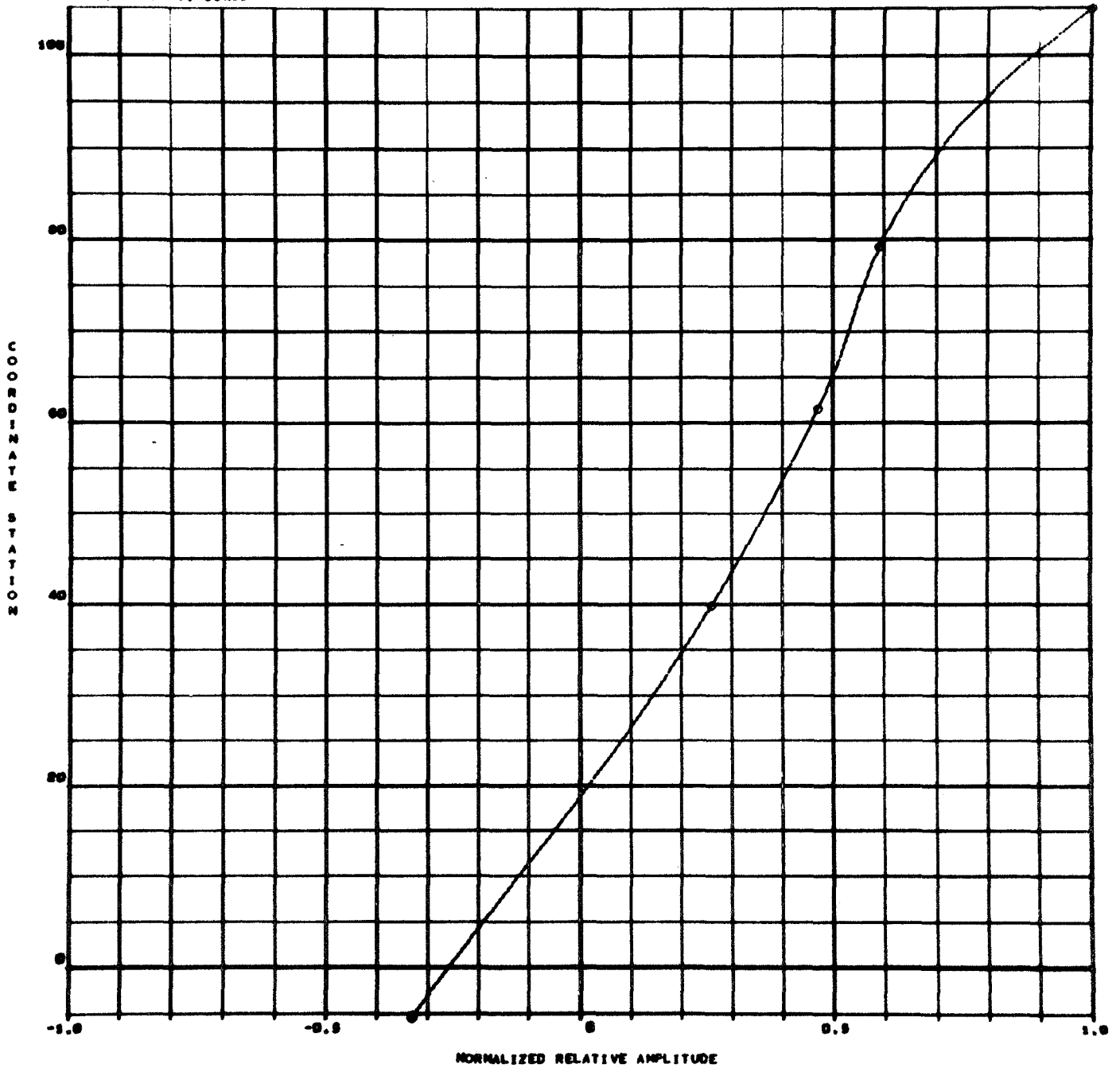


Fig. 43 - 7th Mode Shape (one slosh mode per tank)

9A-503 4-BEAM MODEL T = 0.0

5/08/69

MODE (8)

FREQUENCY = 0.614

GEN. MASS = 1.220X10⁰⁶

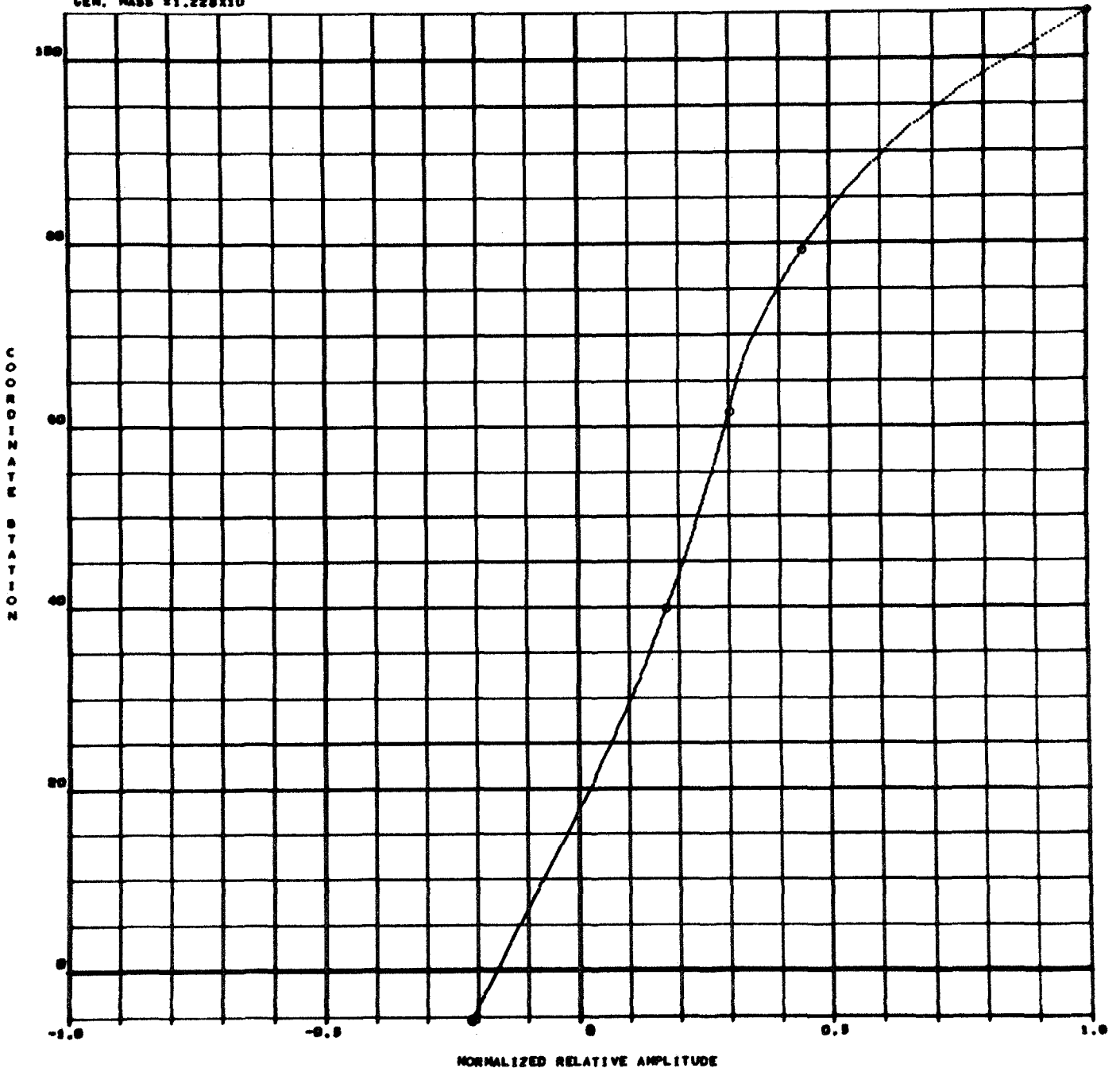


Fig. 44 - 8th Mode Shape (one slosh mode per tank)

SA-303 4-BEAM MODEL T = 0.0

5/06/69

MODE (9)

FREQUENCY = 1.011

GEN. MASS = 1.101 x 10⁰⁴

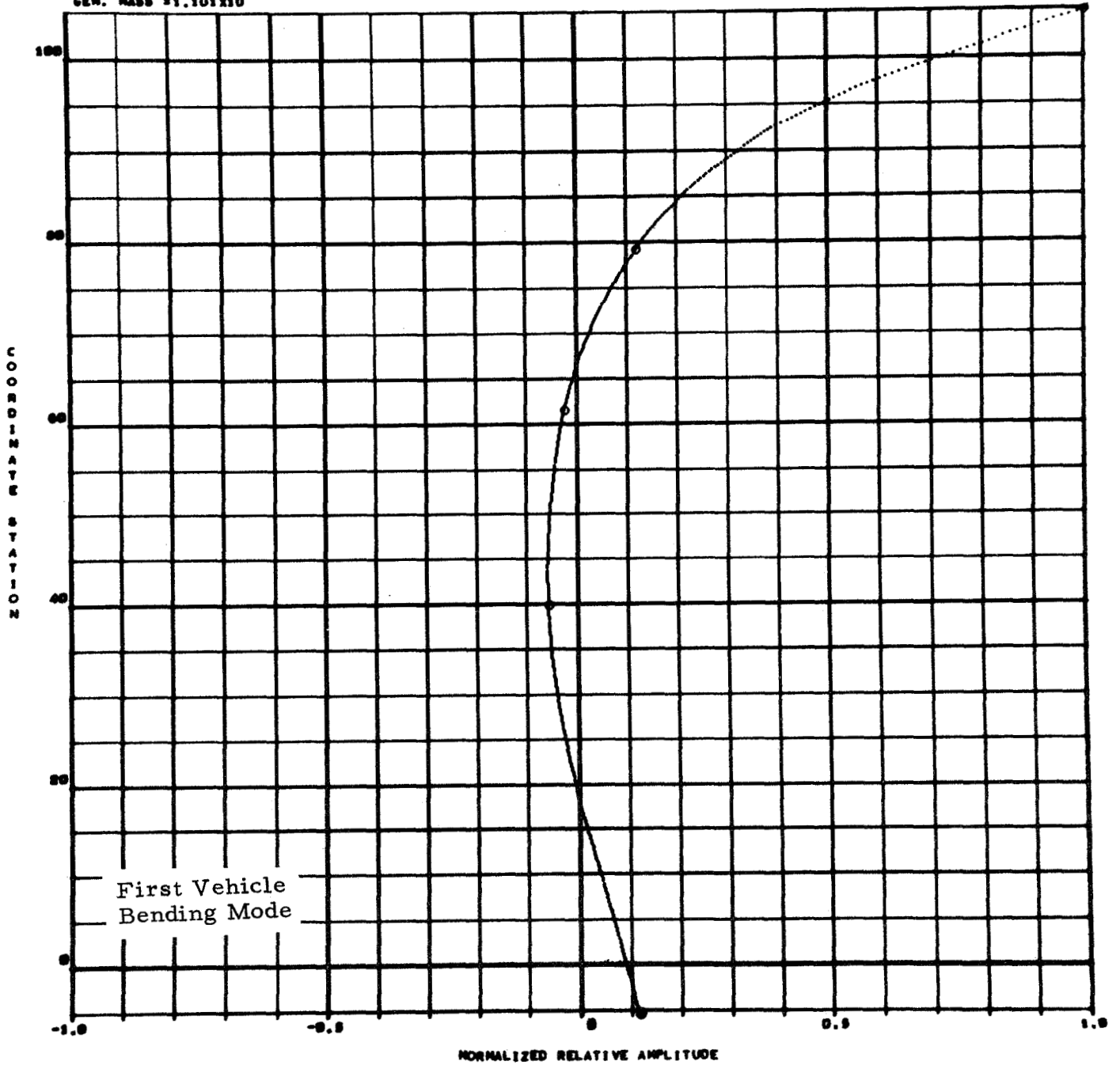


Fig. 45 - 9th Mode Shape (one slosh mode per tank)

SA-303 4-BEAM MODEL T = 0.0

5/08/69

MODE (10)

FREQUENCY = 1.735

GEN. MASS = 3.867x10⁰³

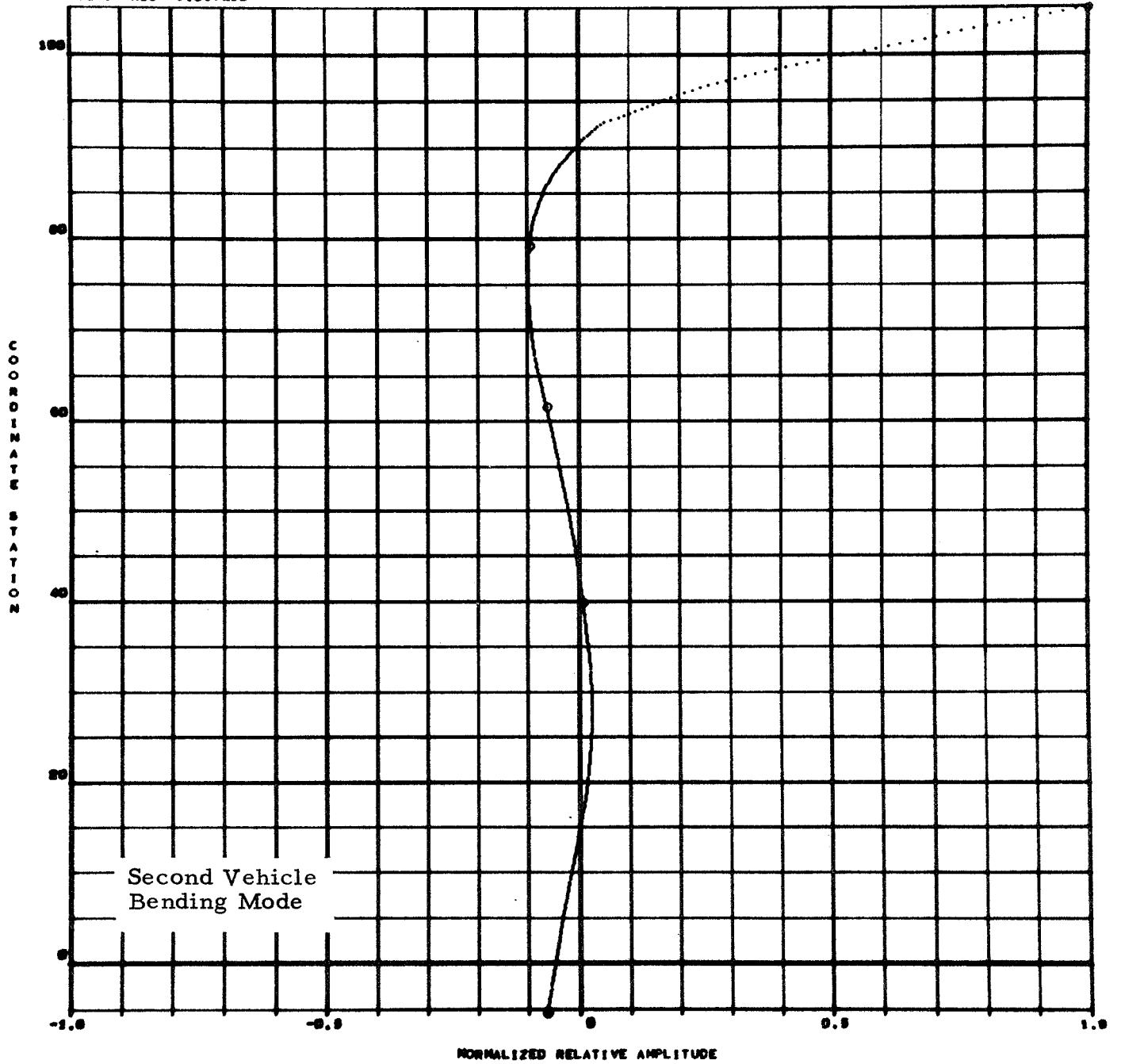


Fig. 46 - 10th Mode Shape (one slosh mode per tank)

SA-503 4-BEAN MODEL T = 0.0

5/08/69

MODE(11)

FREQUENCY = 2.911

GEN. MASS = 3.061 X 10⁰³

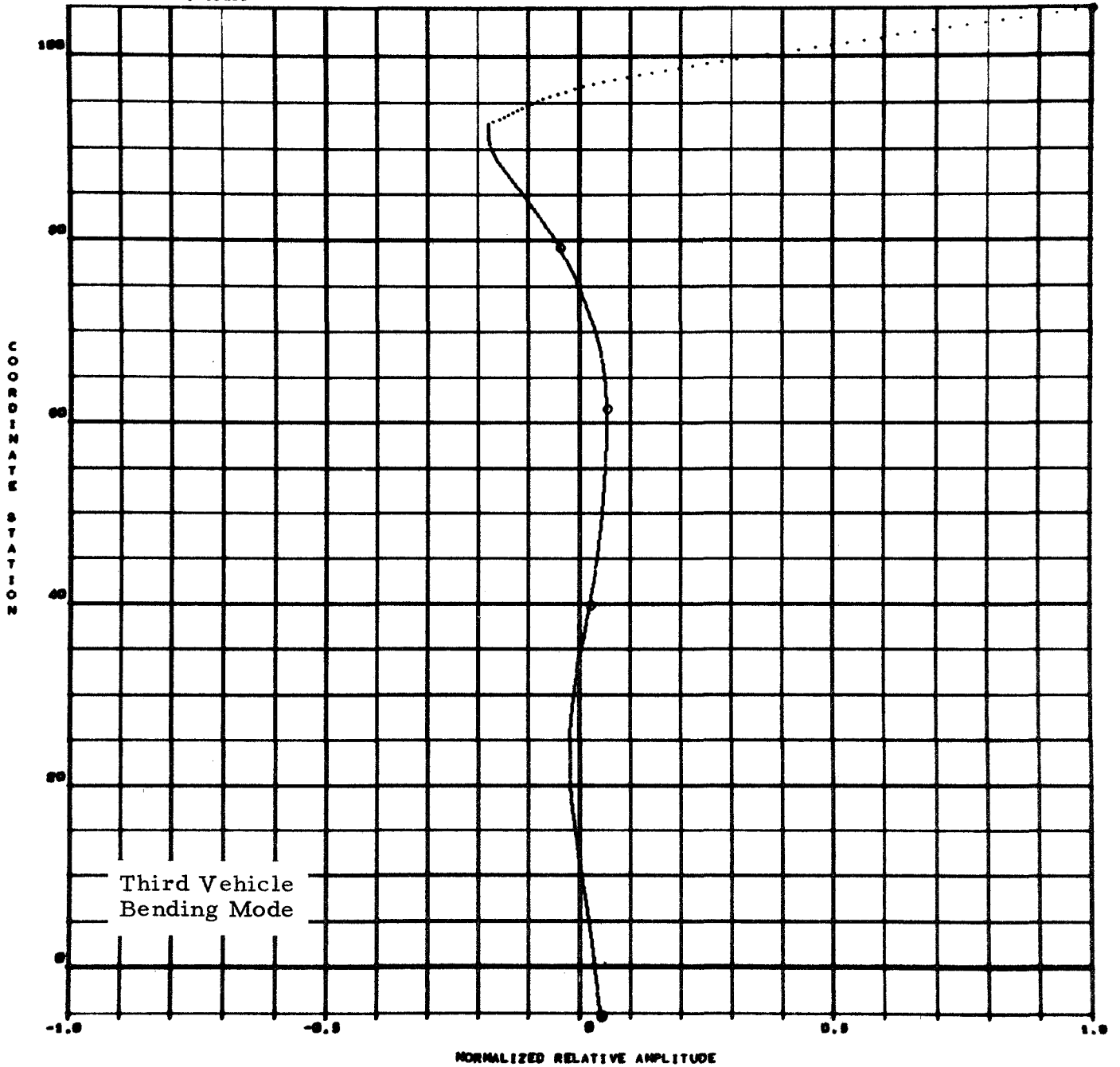


Fig. 47 - 11th Mode Shape (one slosh mode per tank)

SA-303 4-BEAM MODEL T = 0.0

5/08/69

MODE (12)

FREQUENCY = 3.702

GEN. MASS = 1.636x10⁰⁴

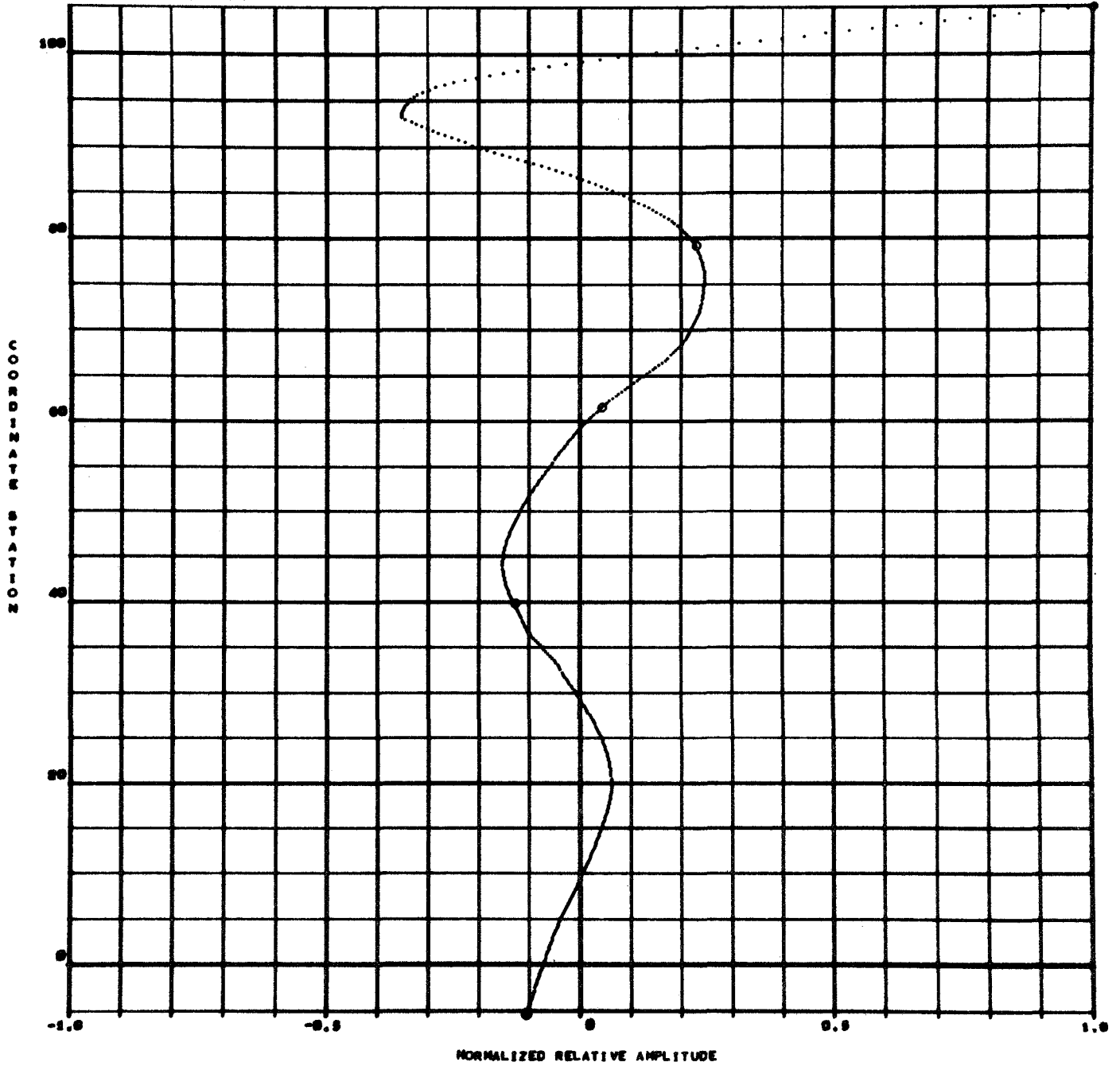


Fig. 48 - 12th Mode Shape (one slosh mode per tank)

SA-503 4-BEAM MODEL T = 0.0

5/08/69

MODE (13)

FREQUENCY = 6.463

GEN. MASS = 2.675×10^{10}

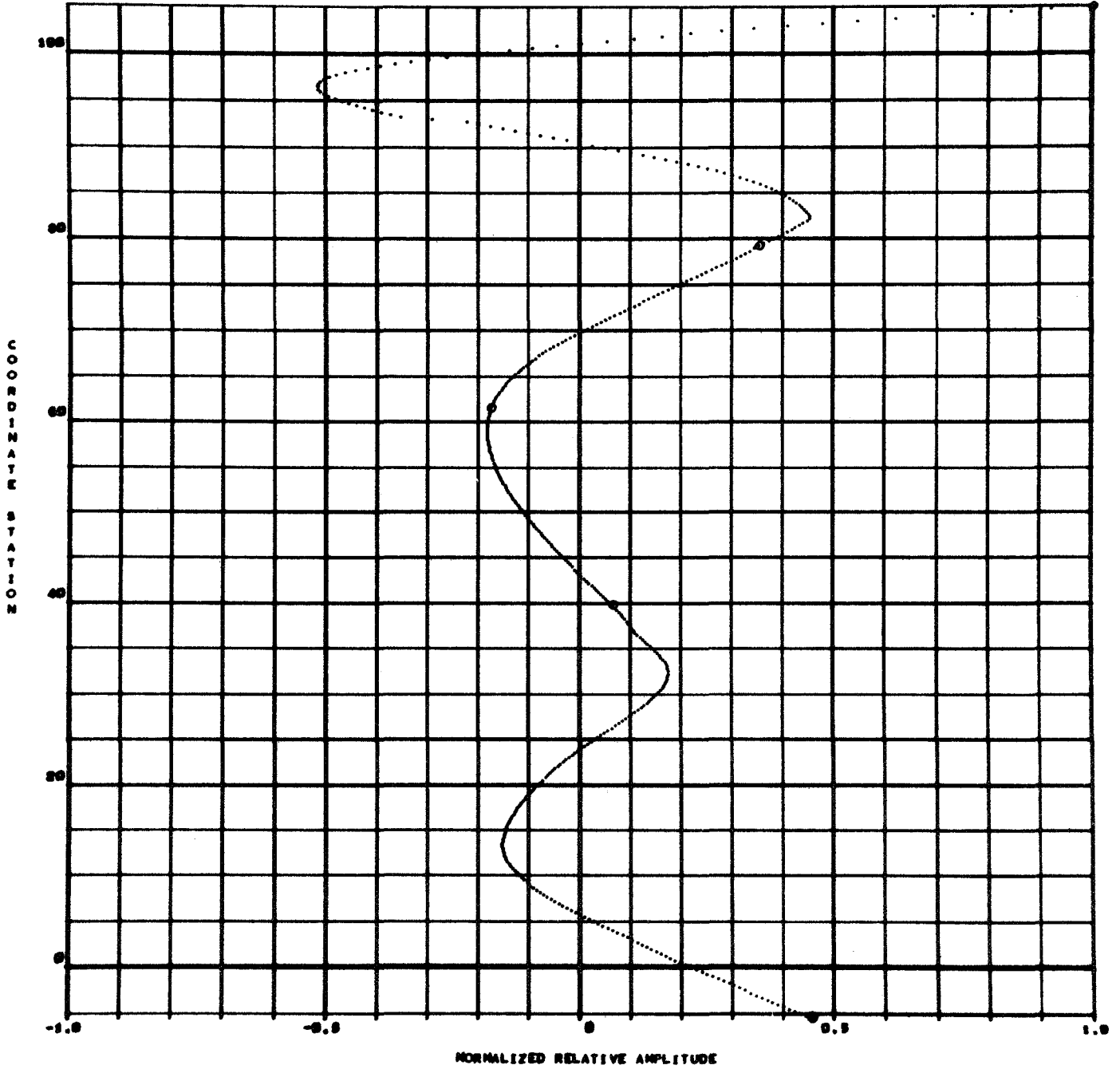
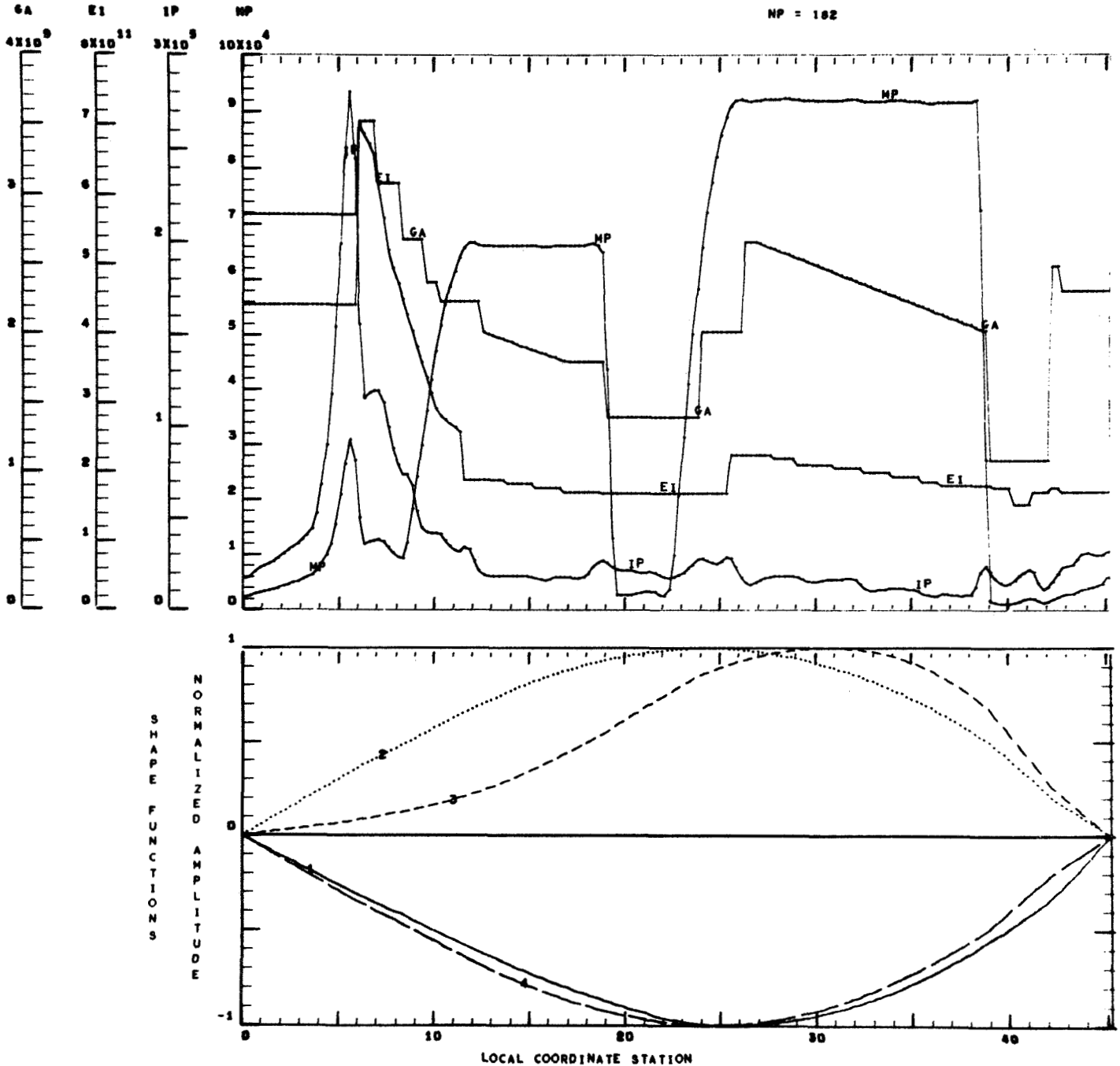


Fig. 49 - 13th Mode Shape (one slosh mode per tank)

SA-303 4-BEAM MODEL T = 0.0

5/08/69

BEAM (1)
 LENGTH = 45.25
 NP = 182



VEHICLE REFERENCE
 STATION = - 9.50

Fig. 50 - Fundamental Deflection Functions, Mass and Stiffness Properties of Beam 1

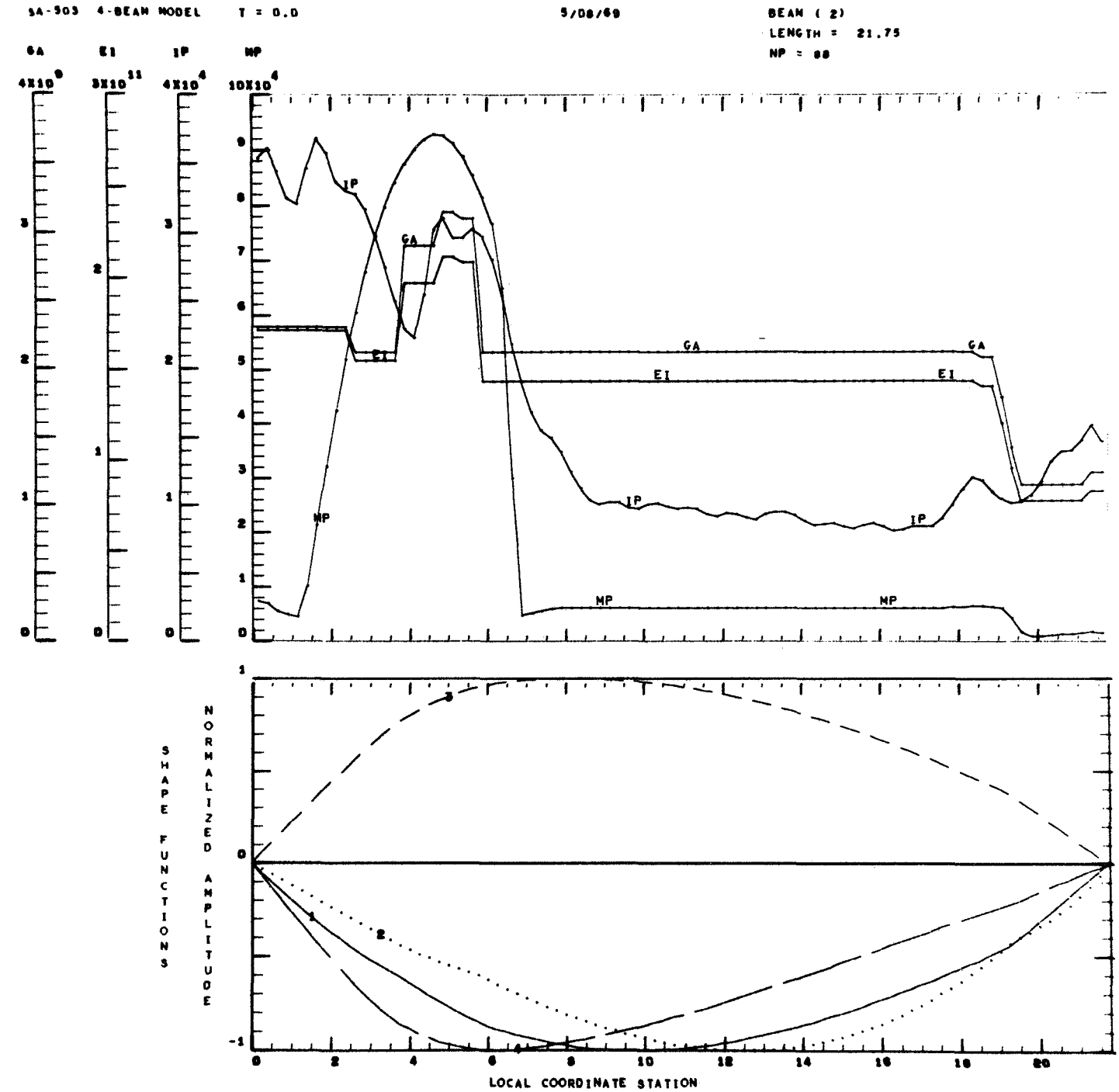
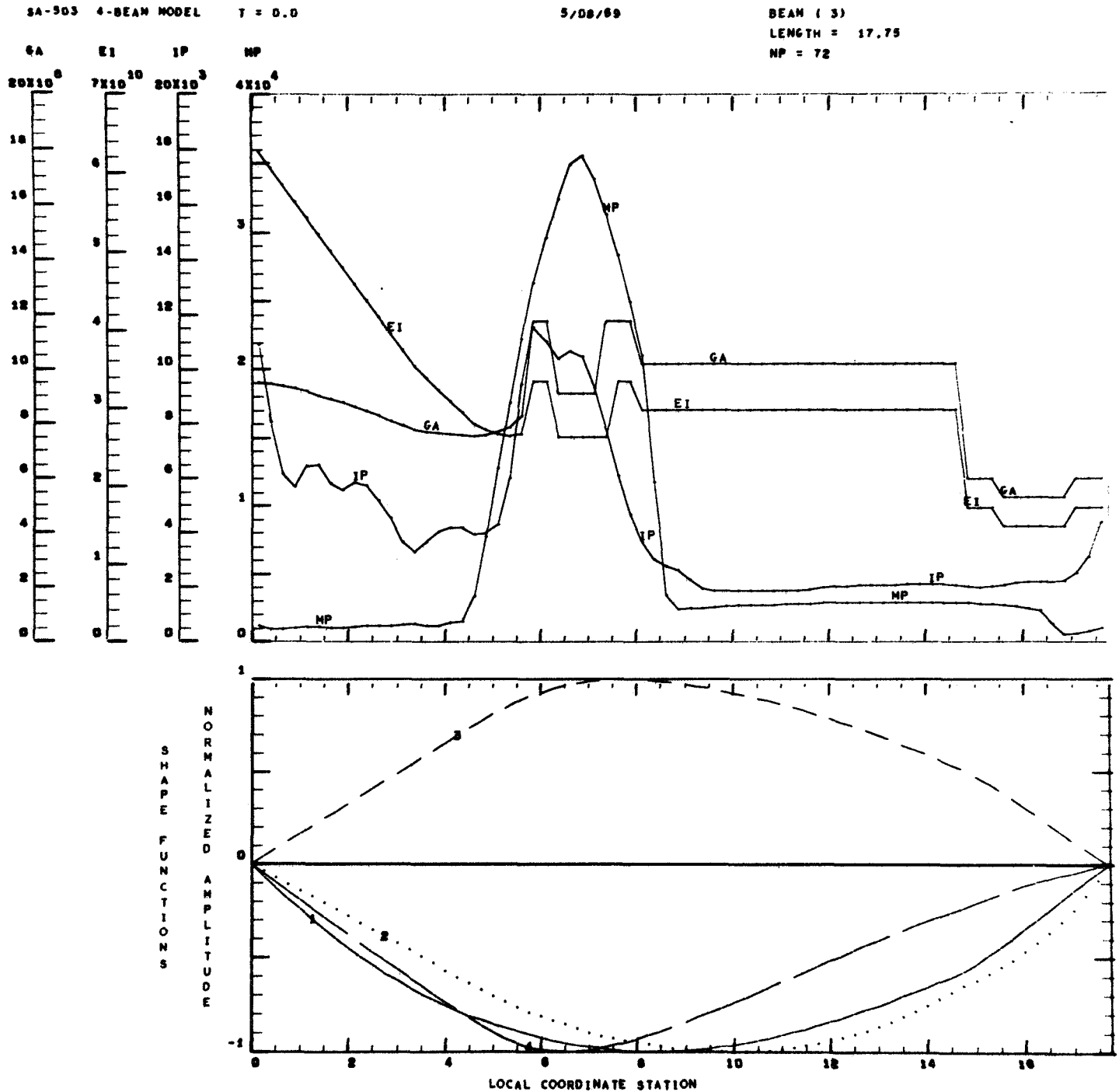


Fig. 51 - Fundamental Deflection Functions, Mass and Stiffness Properties of Beam 2



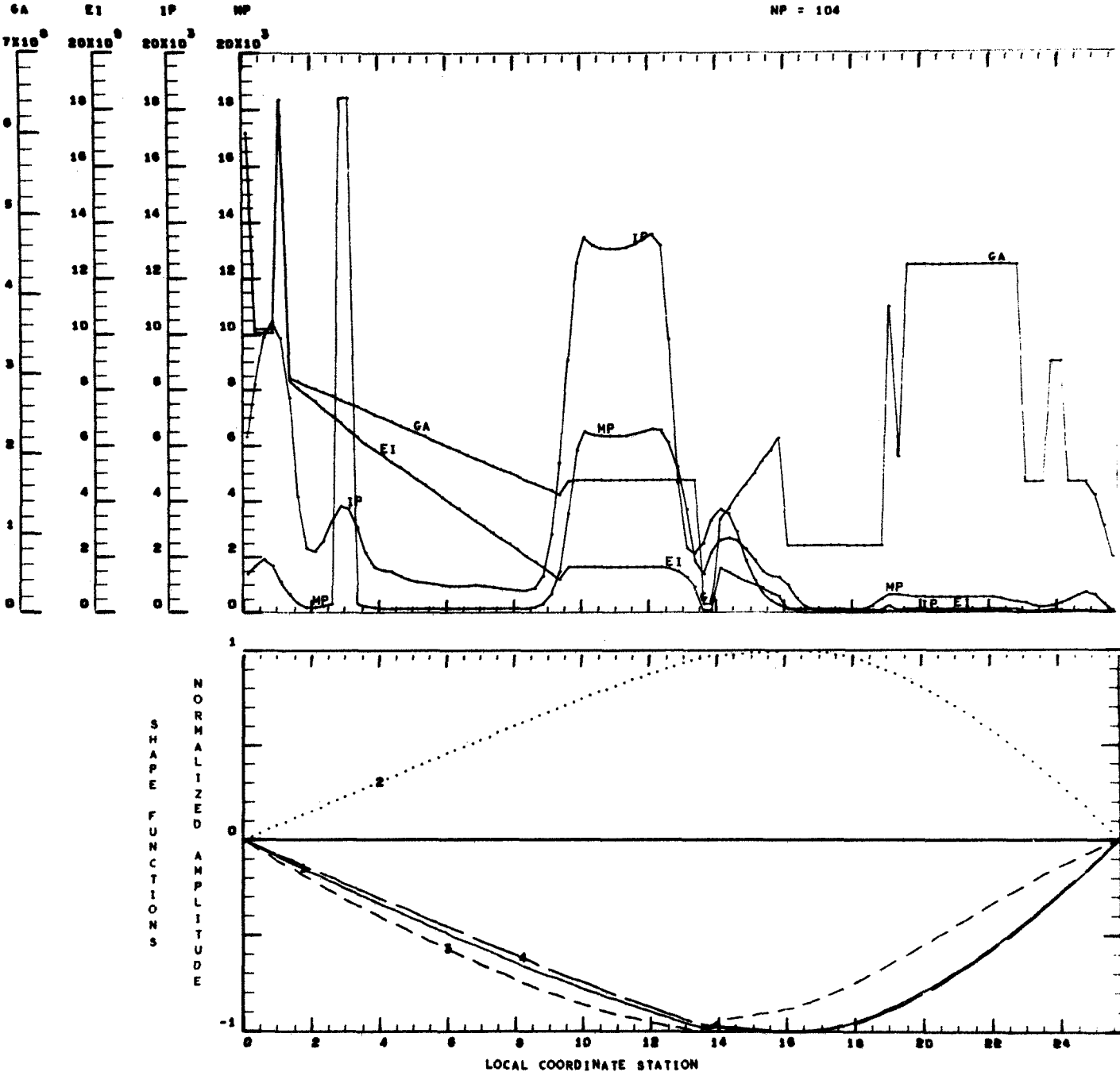
VEHICLE REFERENCE
 STATION = 61.50

Fig. 52 - Fundamental Deflection Functions, Mass and Stiffness Properties of Beam 3

SA-303 4-BEAM MODEL T = 0.0

5/08/69

BEAM (4)
 LENGTH = 25.75
 NP = 104



VEHICLE REFERENCE
 STATION = 79.25

Fig. 53 - Fundamental Deflection Functions, Mass and Stiffness Properties of Beam 4

SA-503 4-BEAM MODEL T = 40.0
MODE (19)
FREQUENCY = 1.090
GEN. MASS = 1.449X10⁺⁰⁴

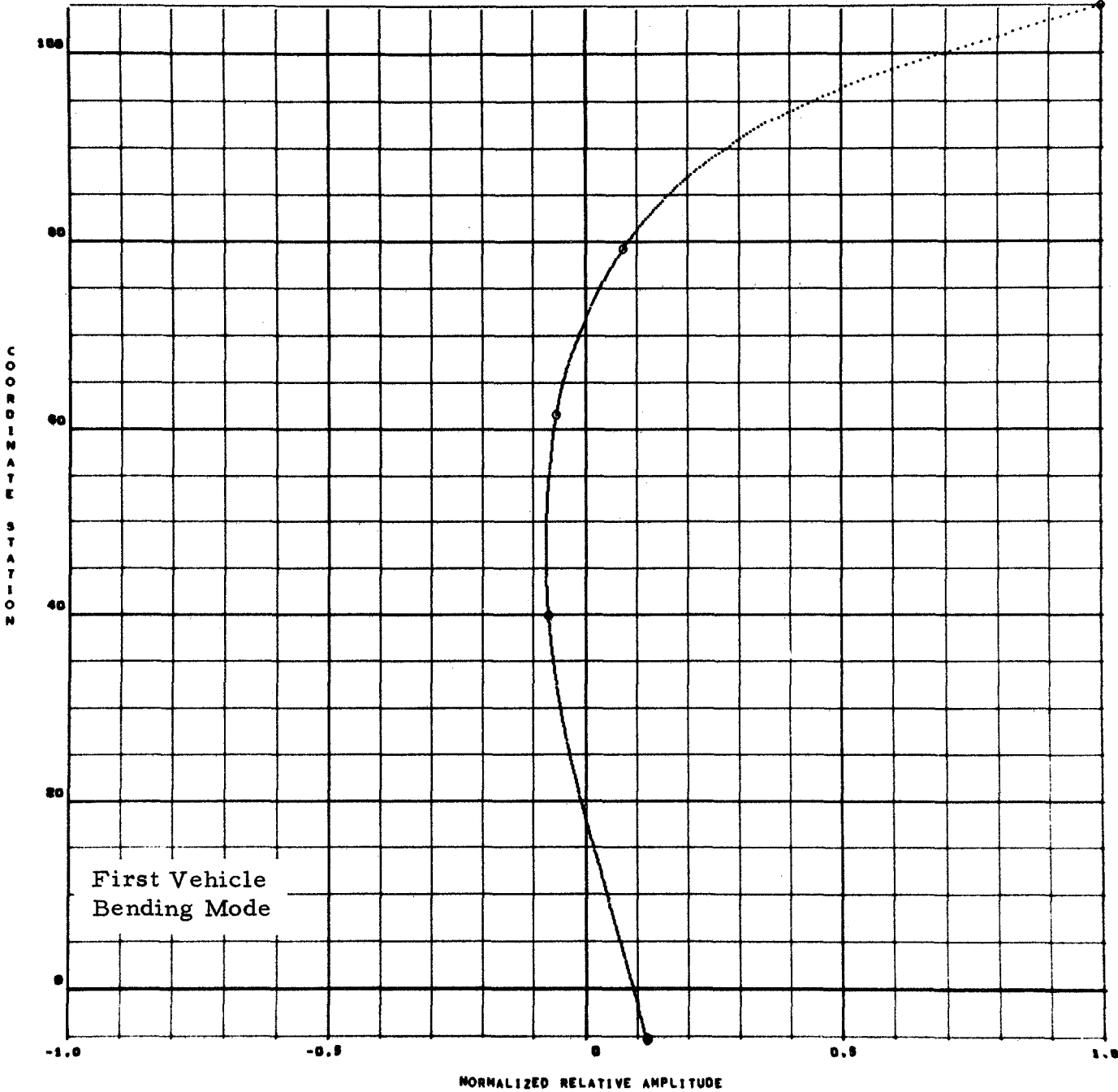


Fig. 54 - 19th Mode Shape (three slosh modes per tank)

SA-503 4-BEAM MODEL T = 40.0

MODE (22)

FREQUENCY = 1.851

GEN. MASS = 3.912X10⁺⁰³

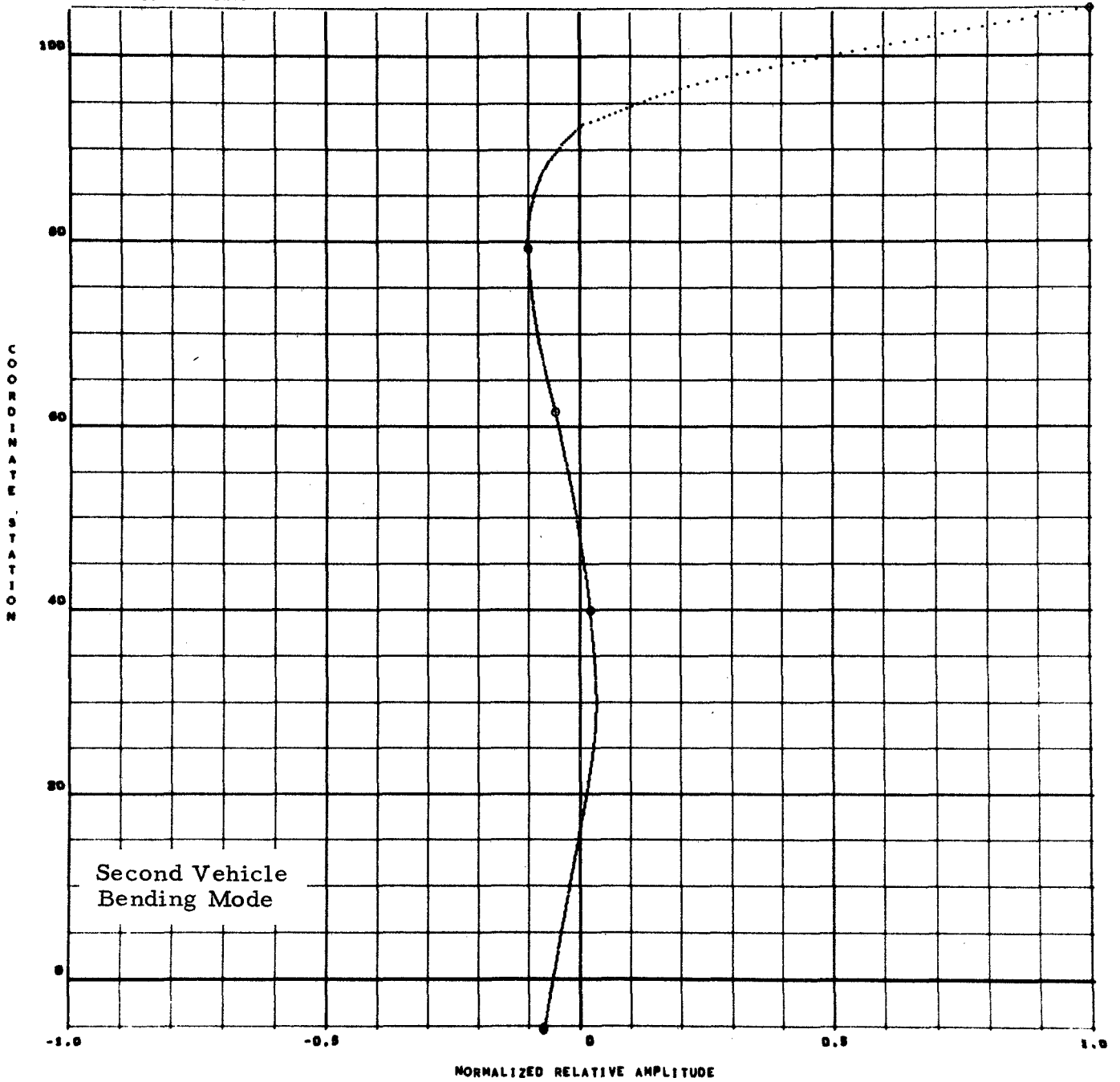


Fig. 55 - 22nd Mode Shape (three slosh modes per tank)

SA-503 4-BEAM MODEL T = 40.0

MODE (23)

FREQUENCY = 2.594

GEN. MASS = 3.451E10⁺⁰³

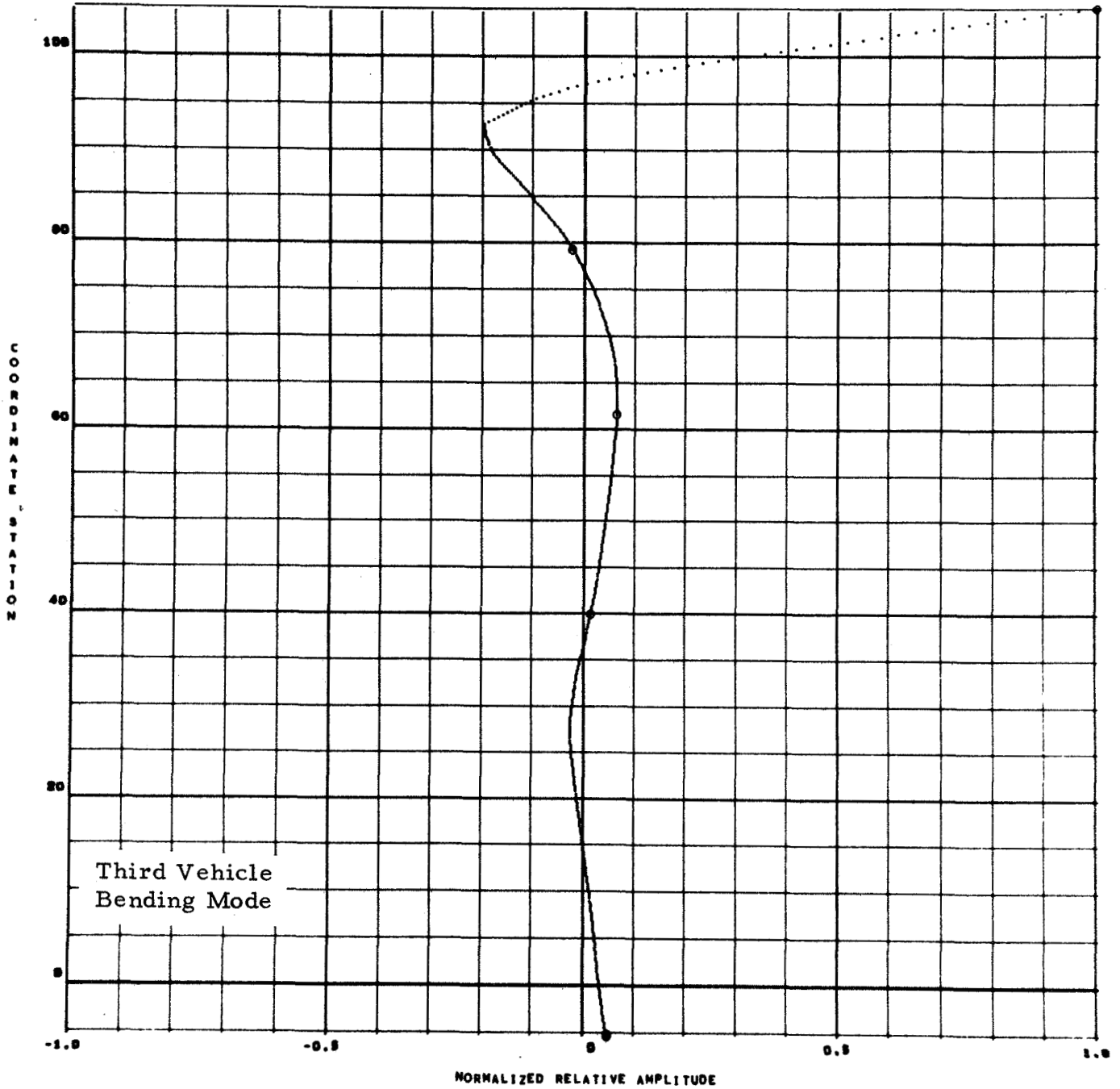
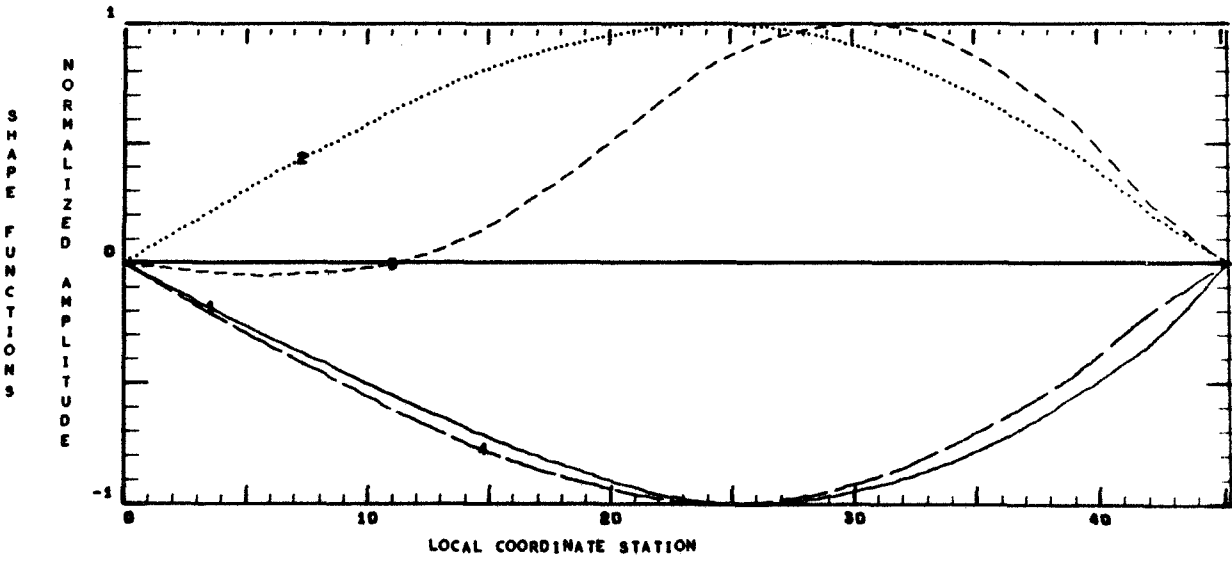
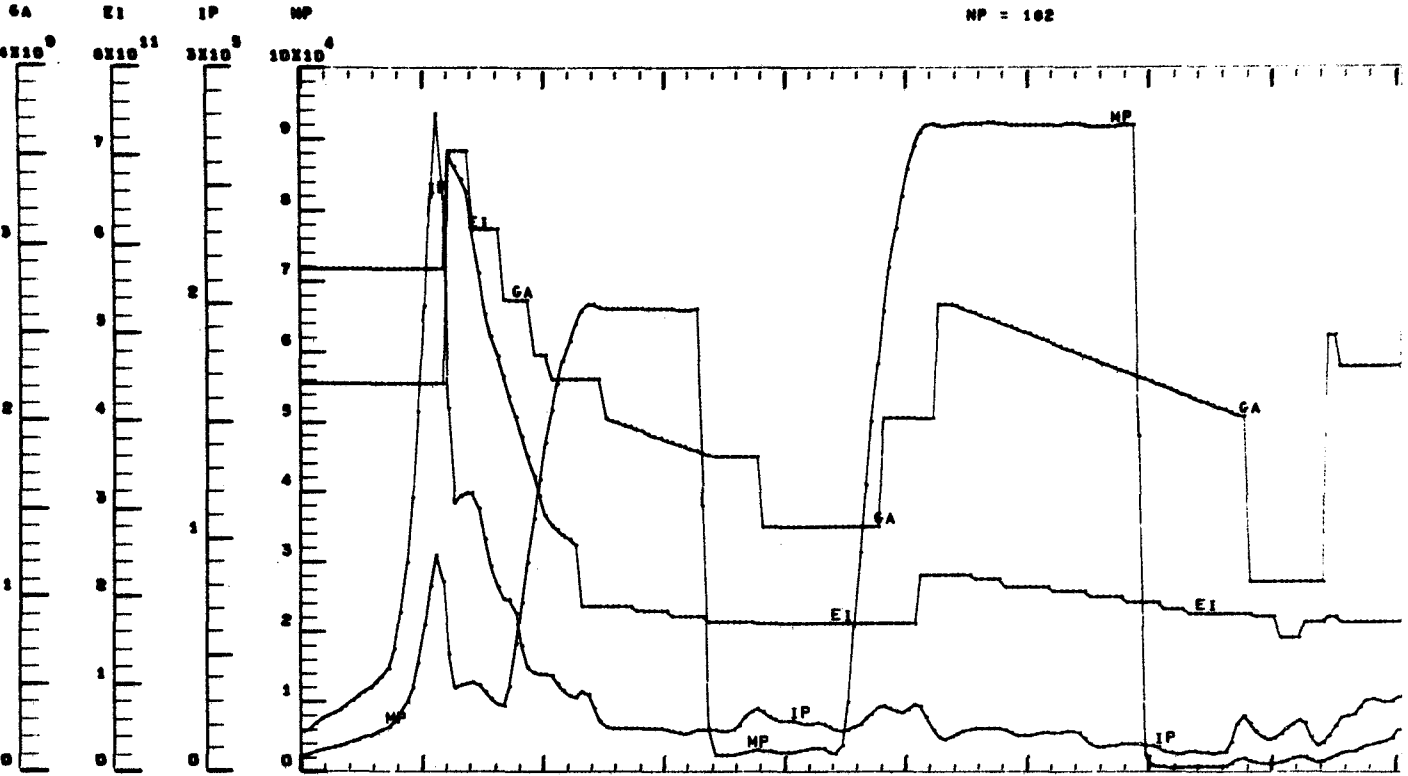


Fig. 56 - 23rd Mode Shape (three slosh modes per tank)

9A-903 4-BEAM MODEL T = 40.0

BEAM (1)
LENGTH = 45.25
NP = 102



VEHICLE REFERENCE
STATION = - 5.50

Fig. 57 - Fundamental Deflection Functions, Mass and Stiffness Properties

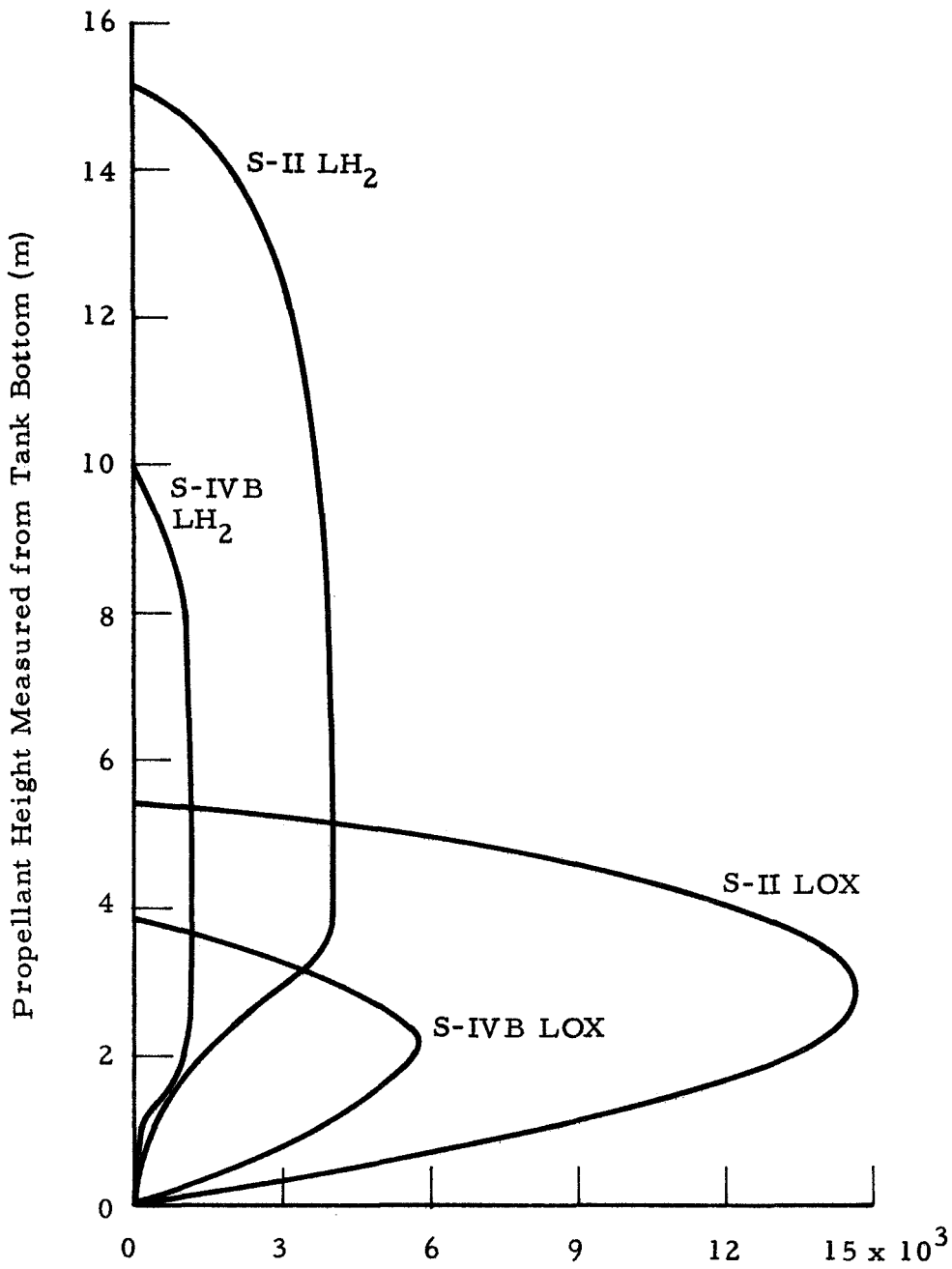


Fig. 58 - Lateral Force Distribution Coefficients m_{α}^A (kg) for Second- and Third-Stage Tanks

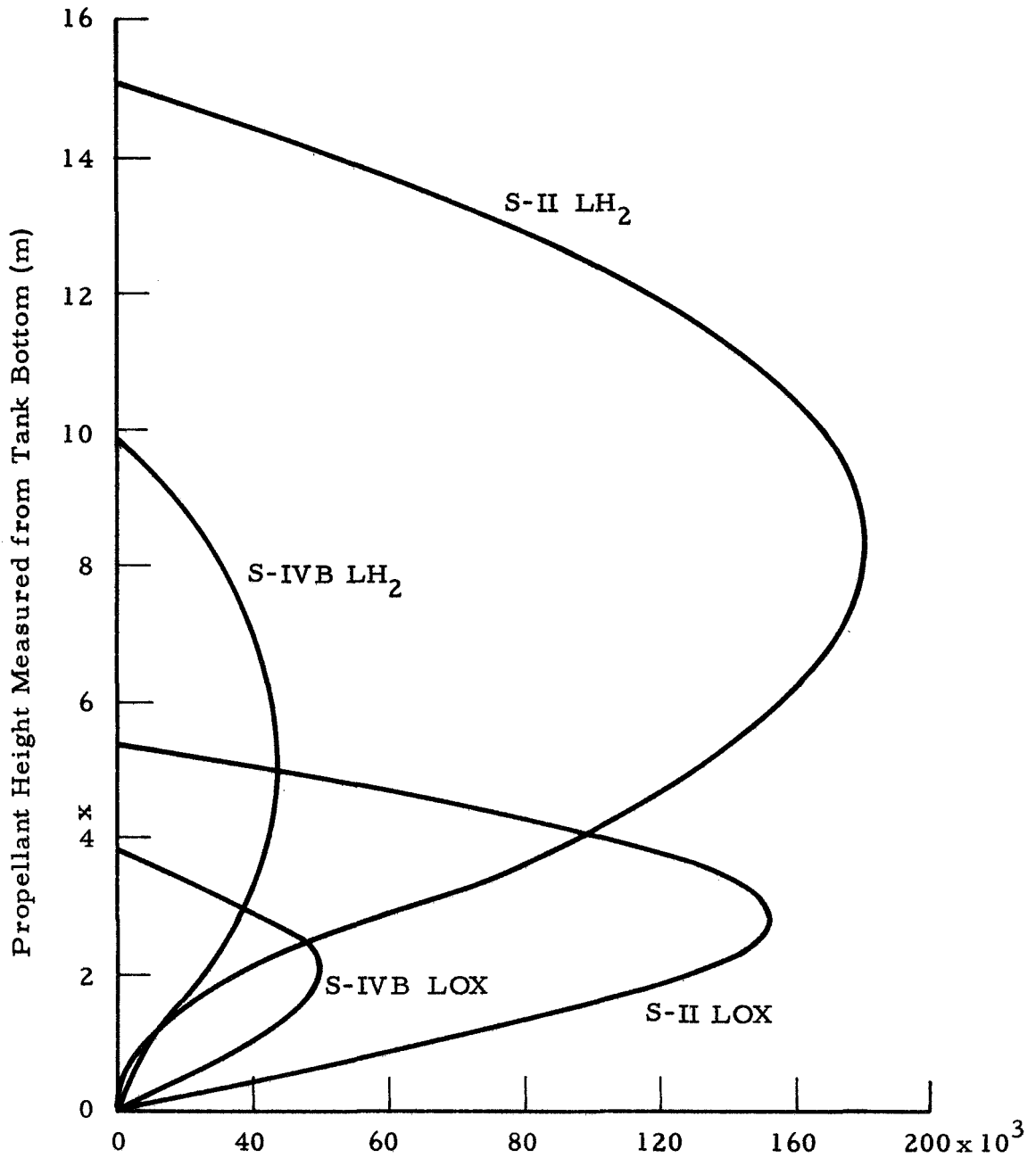


Fig. 59 - Lateral Force Distribution Coefficients $m B_\psi$ (kg/m) for Second- and Third-Stage Tanks

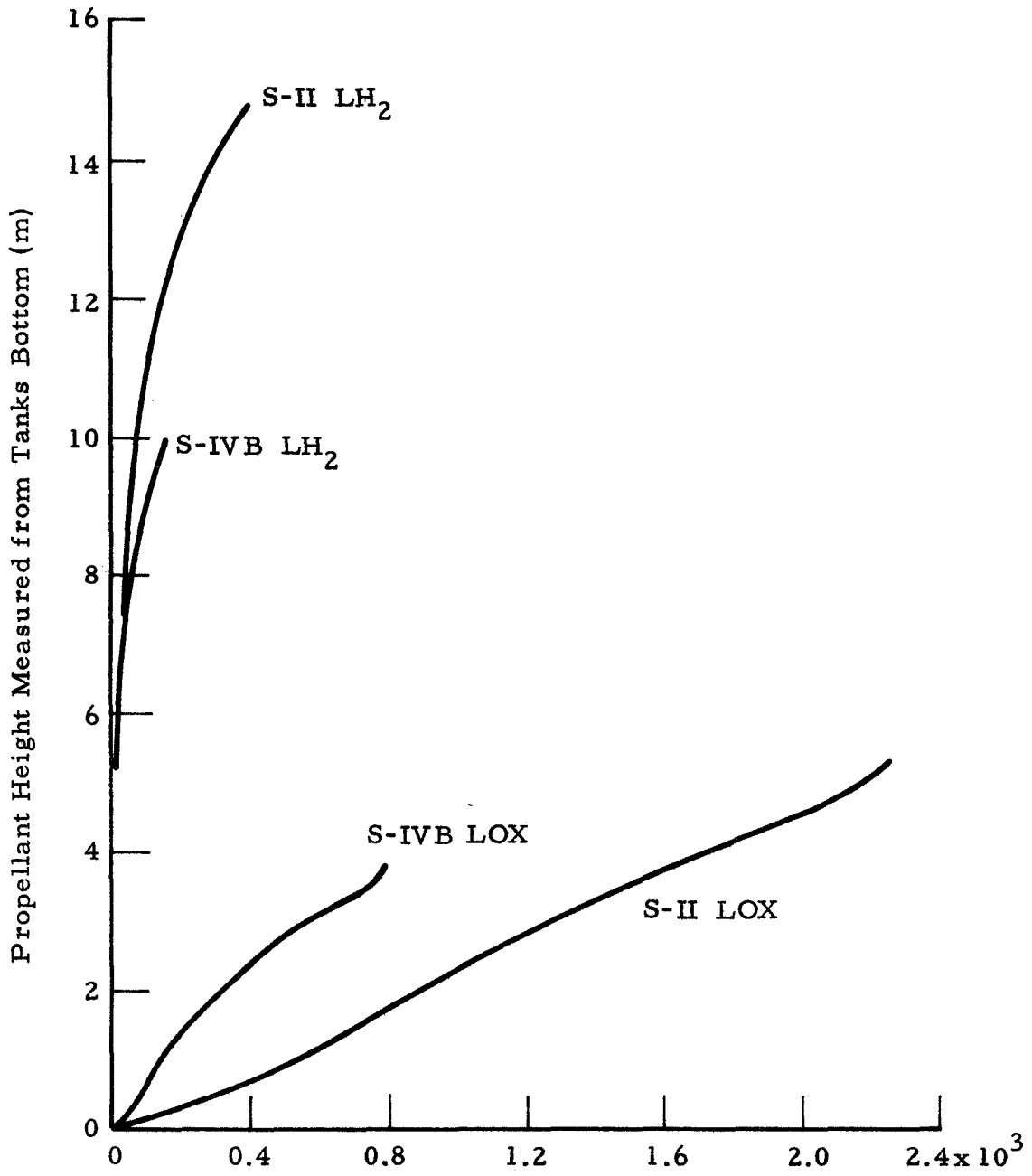


Fig. 60 - Lateral Force Distribution Coefficients $(m C_{\xi})_1 / \alpha_3$ (kg/m) for Second- and Third-Stage Tanks

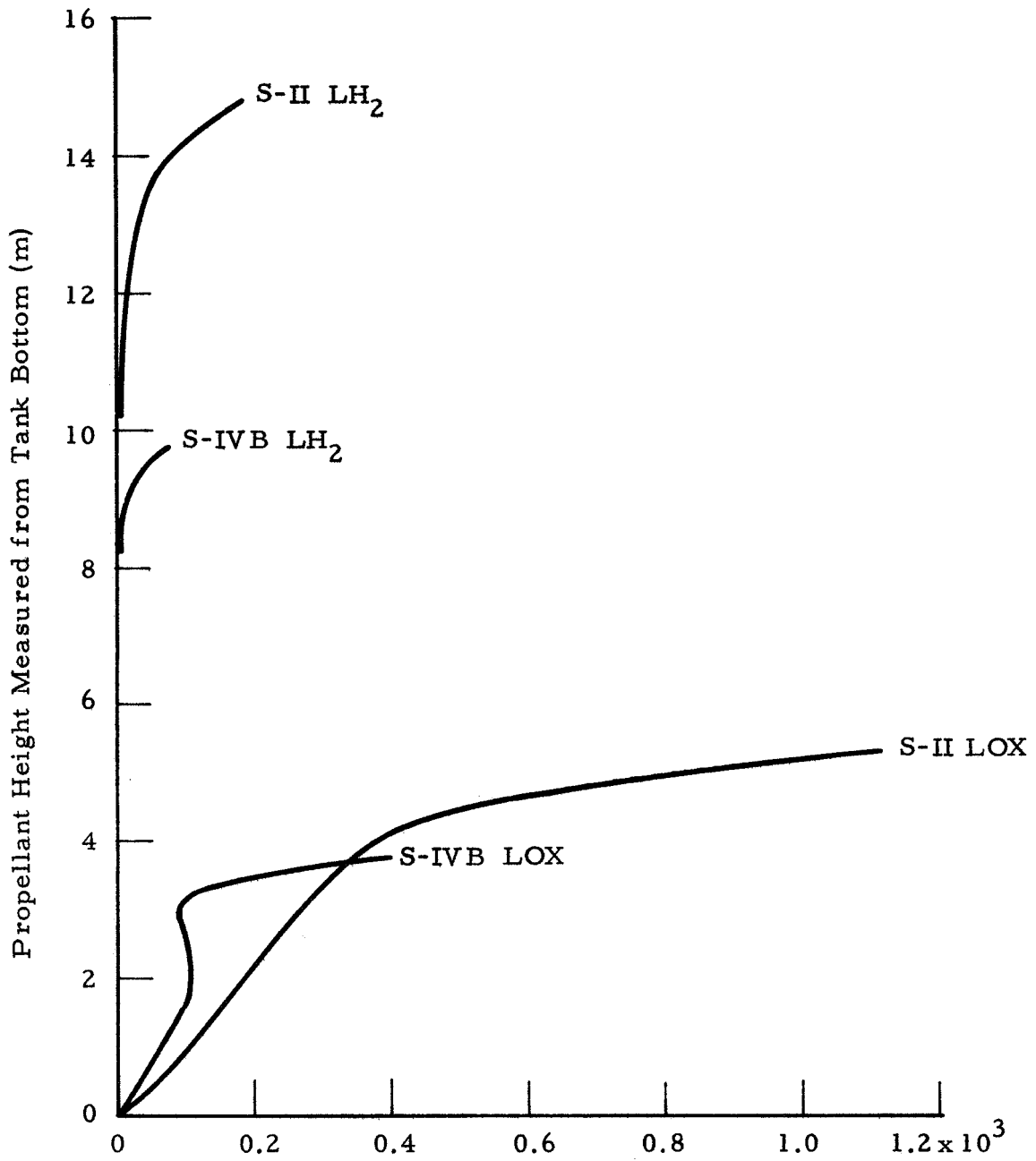


Fig. 61 - Lateral Force Distribution Coefficients $(m C_{\xi})_2 / \alpha_3$ (kg/m) for Second- and Third-Stage Tanks

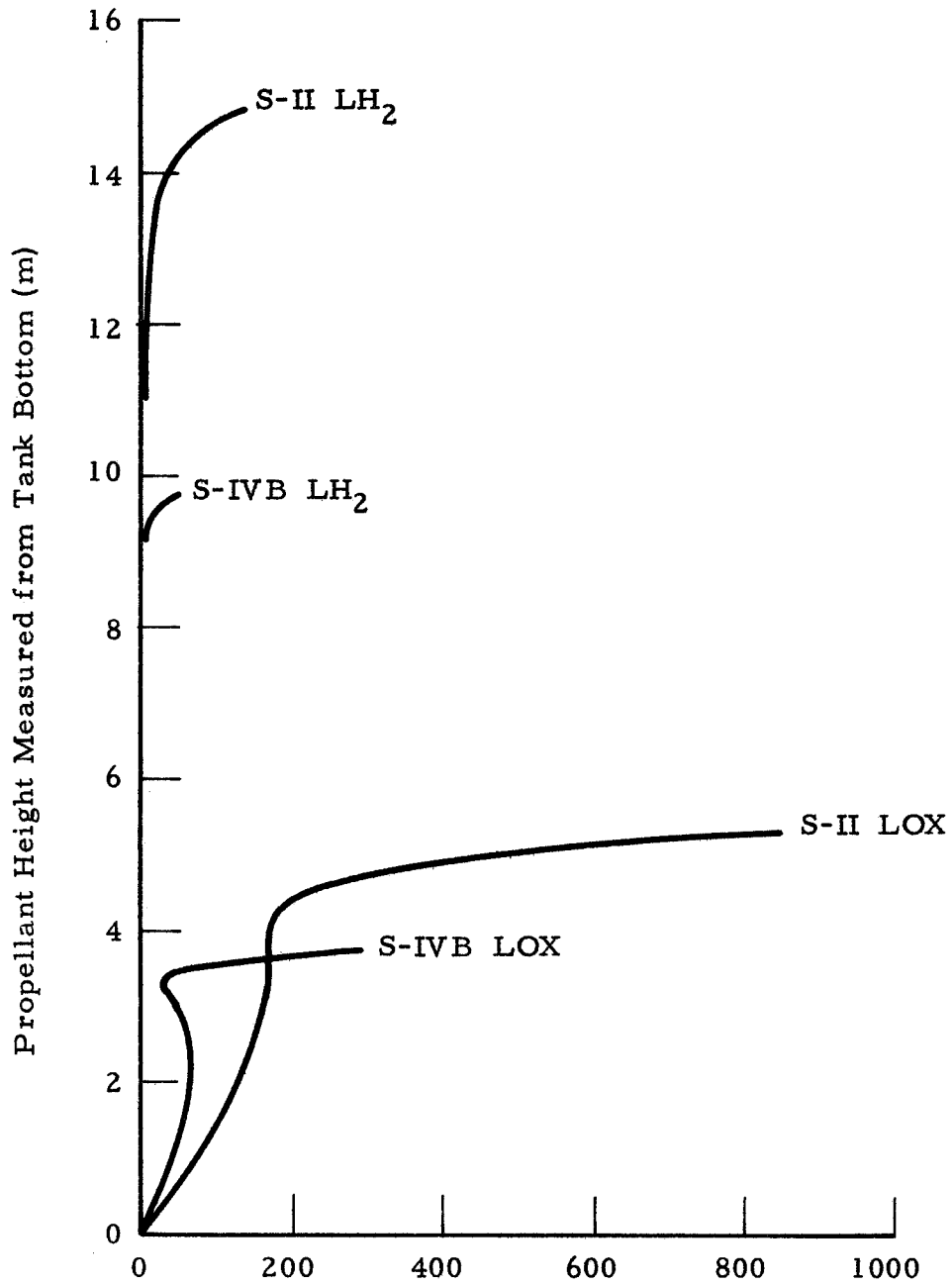


Fig. 62 - Lateral Force Distribution Coefficients $(m C_{\xi})_3 / \alpha_3$ (kg/m) for Second- and Third-Stage Tanks

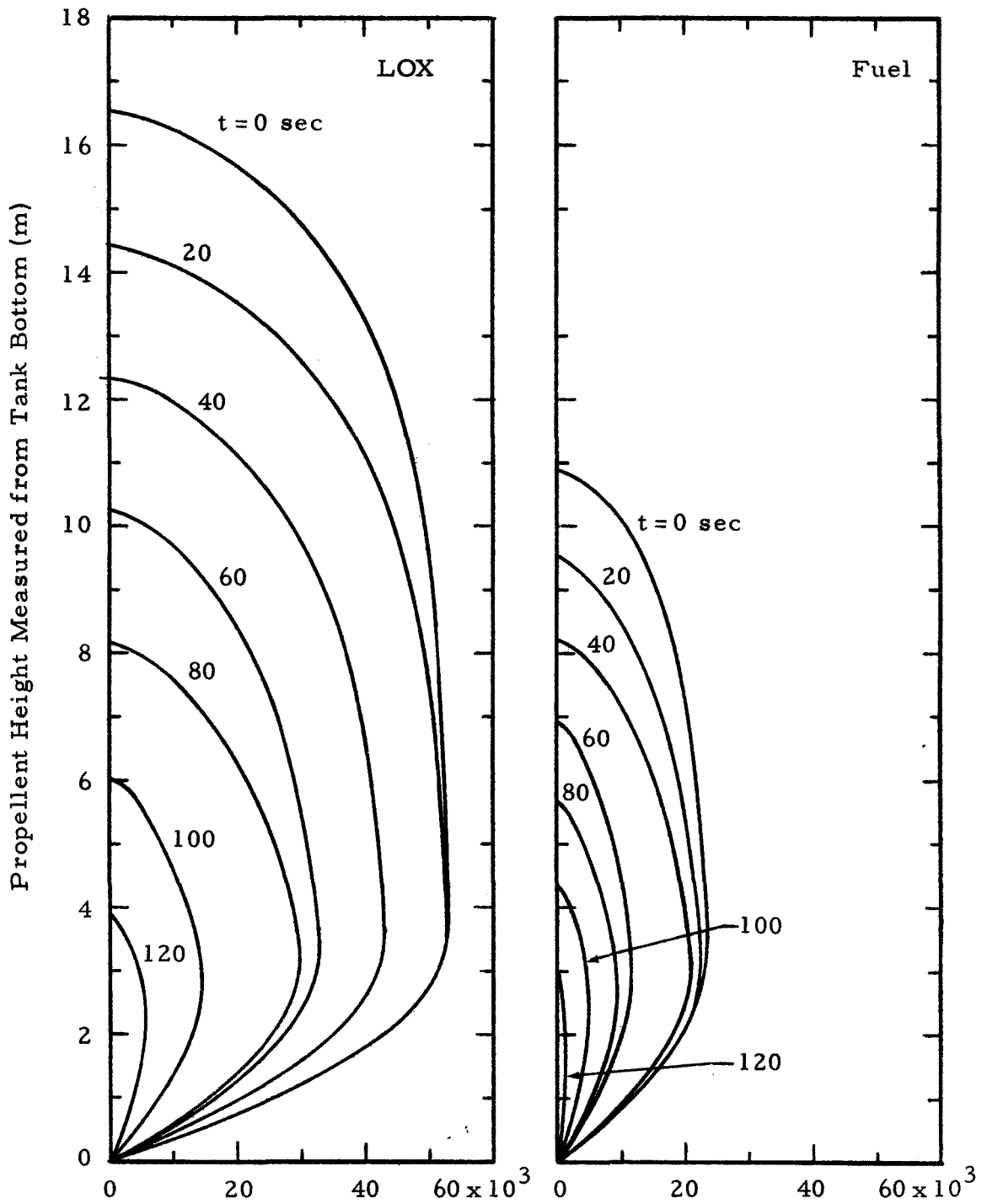


Fig. 63 - Lateral Force Distribution Coefficients $m A_{\alpha}$ (kg) for S-IC Tanks

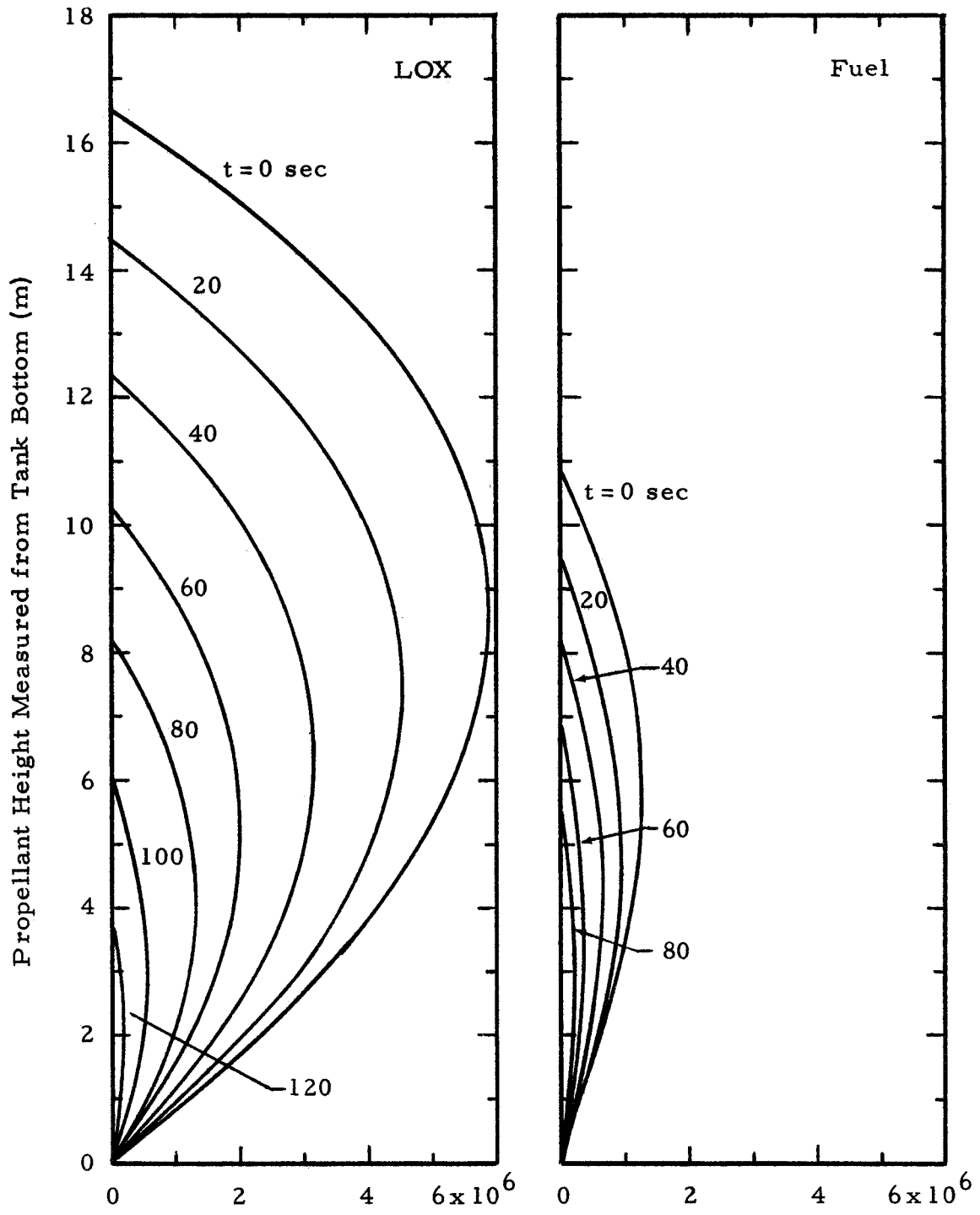


Fig. 64 - Lateral Force Distribution Coefficients $m B_{\psi}$ (kg/m) for S-IC Tanks

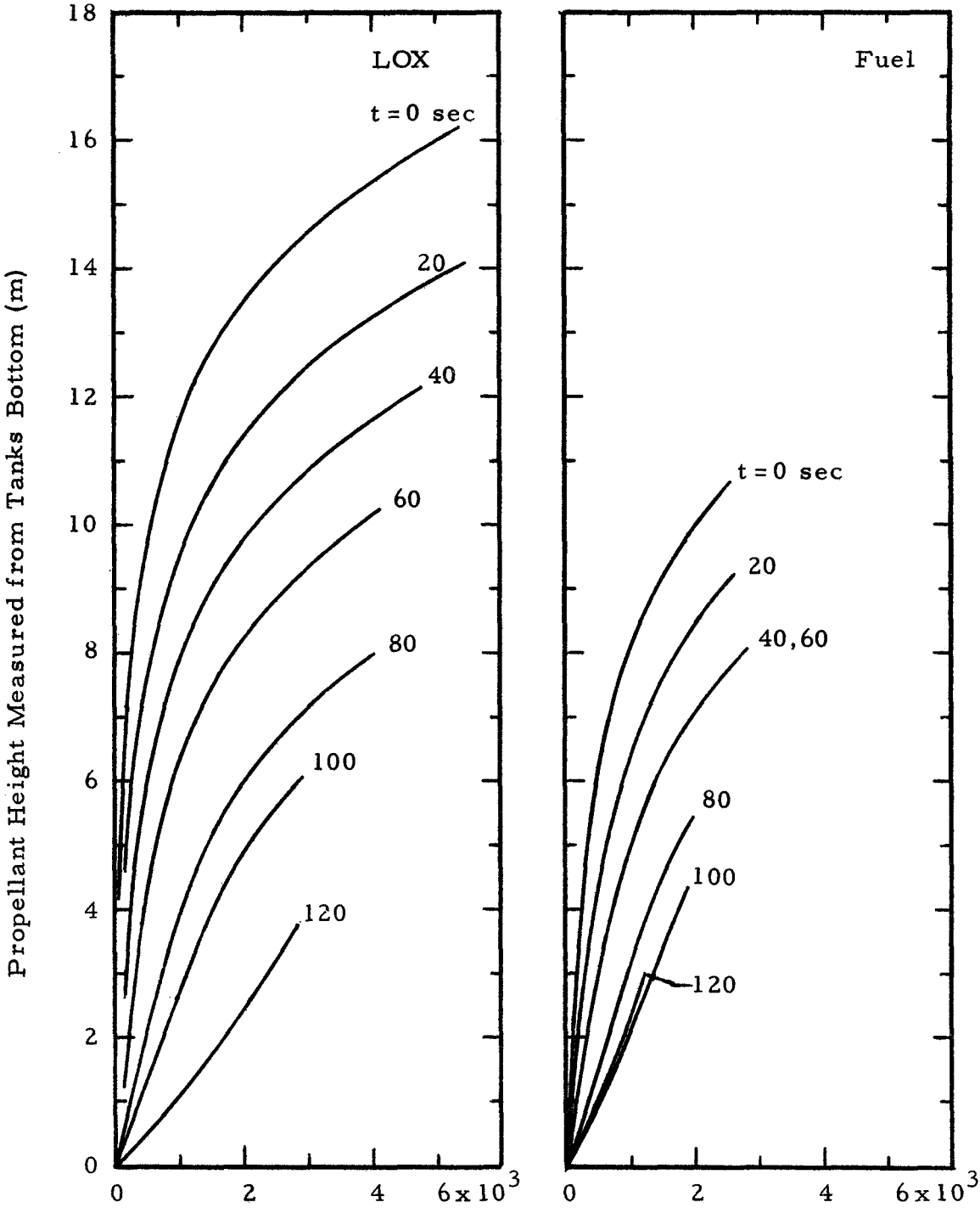


Fig. 65 - Lateral Force Distribution Coefficients $(\frac{m C_{\xi}}{\alpha_3})_1$ (kg/m) for S-IC Tanks

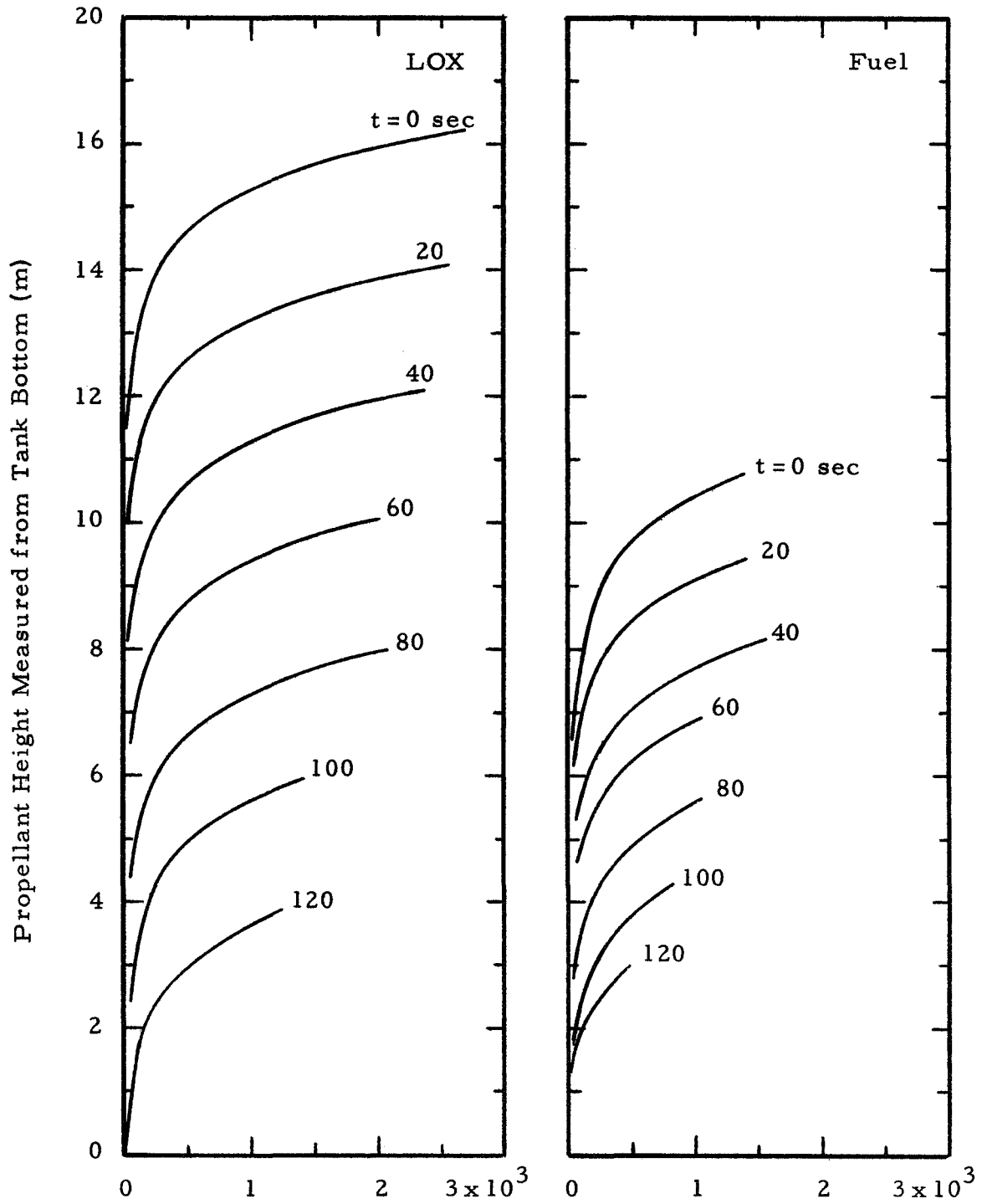


Fig. 66 - Lateral Force Distribution Coefficients $(m C_{\xi})_2 / \alpha_3$ (kg/m) for S-IC Tanks

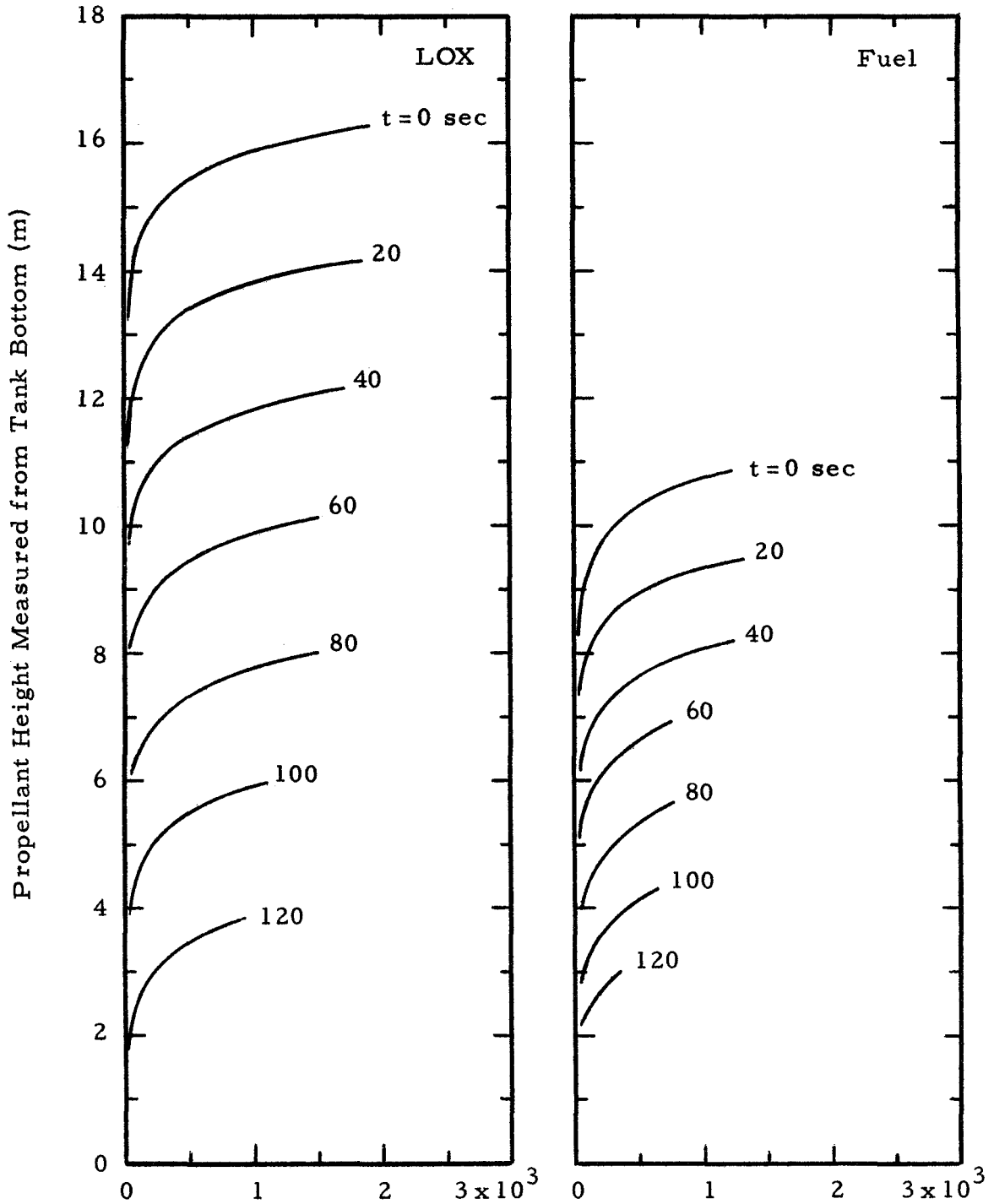


Fig. 67 - Lateral Force Distribution Coefficients $(\frac{m C_{\xi}}{\alpha_3})_3$ (kg/m) for S-IC Tanks

Section 6

CONCLUSION AND RECOMMENDATION

A new method was derived to study the vibrational characteristics of a coupled elastic and fluid system idealized from a liquid-propellant space vehicle. This method presents a consistent formulation for the physical problem and has less restrictions in application than the conventional mechanical model approach. In addition, the method provides a possibility that just a few system modes which are influencing the vehicle dynamics will be needed to define a mathematical model for flight simulation of a space vehicle. Consequently, it will not only lead to a simple and reliable model but also meet the limitations of a computer. For instance, the limited capacity of a hybrid computer and excessive computation time required on a digital computer are the problems which are commonly encountered in flight simulation.

Due to the complexity of the computer program, certain possible improvements of the program are not able to be made in this contract. Specific areas are simplification of the input data deck, possible savings of computer time and to evaluate the integrals of Eq. (A.4) in a better manner. However, the method was demonstrated in this preliminary study that it is a logical approach to solve the coupled bending and sloshing problem of a large-liquid propellant space vehicle.

For an axisymmetric tank, the velocity field of the fluid can be expressed by Eqs. (3.2), (3.3) and (3.4). The eigenvectors c_{km}^n and slosh frequencies λ_{kn} can be obtained from Ref. 4. In case of an arbitrary tank which does not possess a nice geometric symmetry, seeking an analytic expression of the velocity potential of the fluid is almost impossible. Perhaps, to define an empirical equation based on experiment is the only solution to the problem. Once the velocity potential of a fluid system is given in an explicit form, the

kinetic and potential energy terms associated with a tank can be readily computed. Hence, the presented method may be used to study non-beamlike vehicles whose propellant tanks do not have symmetric properties. Furthermore, utilization of the current capability of the developed program, the Saturn V vehicle may be modeled more accurately than the present four-beam model.

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Appendix A

DETAILED DERIVATIONS OF SECTION 3

Appendix

Substituting Eqs. (3.2) and (3.3) into Eq. (3.1), the kinetic energy of the k^{th} tank can be expressed as

$$\begin{aligned}
 T_k = & \frac{1}{2} \rho_k \int_v \left\{ (\dot{u}_i^\ell)^2 + 2 \dot{u}_i^\ell \frac{\dot{u}_i^r - \dot{u}_i^\ell}{L_i} (d_{1k} + x_3^*) + \left(\frac{\dot{u}_i^r - \dot{u}_i^\ell}{L_i} \right)^2 (d_{1k} + x_3^*)^2 \right. \\
 & + 2 \dot{u}_i^\ell \sum_{j=1}^{N_i} \dot{\zeta}_{ij} Y_{ij} + 2 \frac{\dot{u}_i^r - \dot{u}_i^\ell}{L_i} (d_{1k} + x_3^*) \sum_{j=1}^{N_i} \dot{\zeta}_{ij} Y_{ij} + \sum_{j=1}^{N_i} \sum_{m=1}^{N_i} \dot{\zeta}_{ij} \dot{\zeta}_{im} Y_{ij} Y_{im} \\
 & + 2 \left[\dot{u}_i^\ell + \frac{\dot{u}_i^r - \dot{u}_i^\ell}{L_i} (d_{1k} + x_3^*) + \sum_{j=1}^{N_i} \dot{\zeta}_{ij} Y_{ij} \right] \left[\sum_{n=1}^{N_k} \frac{1}{\lambda_{kn}} \dot{\xi}_{kn} (\sin^2 \theta \frac{\partial \phi_{kn}}{\partial R} \right. \\
 & \left. + \cos^2 \theta \frac{\phi_{kn}}{R}) \right] \\
 & + \sum_{n=1}^{N_k} \sum_{m=1}^{N_k} \dot{\xi}_{kn} \dot{\xi}_{km} \left[\sin^2 \theta \frac{\partial \phi_{kn}}{\partial R} \frac{\partial \phi_{km}}{\partial R} + \cos^2 \theta \frac{\phi_{kn}}{R} \frac{\phi_{km}}{R} \right. \\
 & \left. + \sin^2 \theta \frac{\partial \phi_{kn}}{\partial Z} \frac{\partial \phi_{km}}{\partial Z} \right] \\
 & \left. + \left(\frac{\dot{u}_i^r - \dot{u}_i^\ell}{L_i} r \sin \theta \right)^2 - 2 \frac{\dot{u}_i^r - \dot{u}_i^\ell}{L_i} r \sin^2 \theta \sum_{n=1}^{N_k} \frac{1}{\lambda_{kn}} \dot{\xi}_{kn} \frac{\partial \phi_{kn}}{\partial Z} \right\} a_k^3 R d\theta dR dZ
 \end{aligned}$$

$$\begin{aligned}
 &= \pi a_k^3 \rho_k \int_S \left\{ (\dot{u}_i^\ell)^2 \left[1 - 2 \frac{d_{1k}}{L_i} - 2 \frac{a_k}{L_i} Z^* + \left(\frac{d_{1k}}{L_i} \right)^2 + 2 \frac{d_{1k}}{L_i} \frac{a_k}{L_i} Z^* \right. \right. \\
 &+ \left. \left. \left(\frac{a_k}{L_i} Z^* \right)^2 + \frac{1}{2} \left(\frac{a_k}{L_i} R \right)^2 \right] \right. \\
 &+ (\dot{u}_i^r)^2 \left[\left(\frac{d_{1k}}{L_i} \right)^2 + 2 \frac{d_{1k}}{L_i} \frac{a_k}{L_i} Z^* + \left(\frac{a_k}{L_i} Z^* \right)^2 + \frac{1}{2} \left(\frac{a_k}{L_i} R \right)^2 \right] \\
 &+ 2 \dot{u}_i^\ell \dot{u}_i^r \left[\frac{d_{1k}}{L_i} + \frac{a_k}{L_i} Z^* - \left(\frac{d_{1k}}{L_i} \right)^2 - 2 \frac{d_{1k}}{L_i} \frac{a_k}{L_i} Z^* - \left(\frac{a_k}{L_i} Z^* \right)^2 - \frac{1}{2} \left(\frac{a_k}{L_i} R \right)^2 \right] \\
 &+ 2 \dot{u}_i^\ell \sum_{j=1}^{N_i} \dot{\zeta}_{ij} \left[1 - \frac{d_{1k}}{L_i} - \frac{a_k}{L_i} Z^* \right] Y_{ij} + 2 \dot{u}_i^r \sum_{j=1}^{N_i} \dot{\zeta}_{ij} \left[\frac{d_{1k}}{L_i} + \frac{a_k}{L_i} Z^* \right] Y_{ij} \\
 &+ \sum_{j=1}^{N_i} \sum_{m=1}^{N_i} \dot{\zeta}_{ij} \dot{\zeta}_{im} Y_{ij} Y_{im} \\
 &+ \dot{u}_i^\ell \sum_{n=1}^{N_k} \frac{1}{\lambda_{kn}} \dot{\xi}_{kn} \left[\left(\frac{\partial \phi_{kn}}{\partial R} + \frac{\phi_{kn}}{R} \right) \left(1 - \frac{d_{1k}}{L_i} - \frac{a_k}{L_i} Z^* \right) + \frac{a_k}{L_i} R \frac{\partial \phi_{kn}}{\partial Z} \right] \\
 &+ \dot{u}_i^r \sum_{n=1}^{N_k} \frac{1}{\lambda_{kn}} \dot{\xi}_{kn} \left[\left(\frac{\partial \phi_{kn}}{\partial R} + \frac{\phi_{kn}}{R} \right) \left(\frac{d_{1k}}{L_i} + \frac{a_k}{L_i} Z^* \right) - \frac{a_k}{L_i} R \frac{\partial \phi_{kn}}{\partial Z} \right]
 \end{aligned}$$

$$\begin{aligned}
 & + \sum_{j=1}^{N_i} \sum_{n=1}^{N_k} \frac{1}{\lambda_{kn}} \dot{\zeta}_{ij} \dot{\xi}_{kn} \left(\frac{\partial \phi_{kn}}{\partial R} + \frac{\phi_{kn}}{R} \right) Y_{ij} \\
 & + \frac{1}{2} \sum_{n=1}^{N_k} \sum_{m=1}^{N_k} \frac{1}{\lambda_{kn} \lambda_{km}} \dot{\xi}_{kn} \dot{\xi}_{km} \left[\frac{\partial \phi_{kn}}{\partial R} \frac{\partial \phi_{km}}{\partial R} + \frac{\phi_{kn}}{R} \frac{\phi_{km}}{R} \right. \\
 & \left. + \frac{\partial \phi_{kn}}{\partial Z} \frac{\partial \phi_{km}}{\partial Z} \right] \Bigg\} R dR dZ \tag{A.1}
 \end{aligned}$$

where

$$Z^* = \frac{G_{3k} - d_{1k}}{a_k} + Z \quad \text{and} \quad dZ^* = dZ.$$

If Eq. (3.4) is used and integrations with respect to Z are performed (Ref. 6), Eq. (A-1) may be further reduced to the following form.

$$\begin{aligned}
 T_k = & -\pi a_k^3 \rho_k \left\{ V_k^{pp} (\dot{u}_i^\ell)^2 + V_k^{pq} \dot{u}_i^\ell \dot{u}_i^r + V_k^{qq} (\dot{u}_i^r)^2 \right. \\
 & + \dot{u}_i^\ell \sum_{j=1}^{N_i} (ULB)_{ij} \dot{\zeta}_{ij} + \dot{u}_i^r \sum_{j=1}^{N_i} (URB)_{ij} \dot{\zeta}_{ij} \\
 & \left. + \sum_{j=1}^{N_i} \sum_{m=1}^{N_i} (BB)_{ijm} \dot{\zeta}_{ij} \dot{\zeta}_{im} + \dot{u}_i^\ell \sum_{n=1}^{N_k} \frac{1}{\lambda_{kn}} S_{kn}^p \dot{\xi}_{kn} \right\}
 \end{aligned}$$

$$\begin{aligned}
 & + \dot{u}_i^r \sum_{n=1}^{N_k} \frac{1}{\lambda_{kn}} S_{kn}^q \dot{\xi}_{kn} + \sum_{j=1}^{N_i} \sum_{n=1}^{N_k} \frac{1}{\lambda_{kn}} (BS)_{kijn} \dot{\xi}_{ij} \dot{\xi}_{kn} \\
 & + \left. \frac{1}{2} \sum_{n=1}^{N_k} \sum_{m=1}^{N_k} \frac{1}{\lambda_{kn} \lambda_{km}} S_{kmn} \dot{\xi}_{kn} \dot{\xi}_{km} \right\} \quad (A.2)
 \end{aligned}$$

where

$$\left\{ \begin{aligned}
 V_k^{pp} &= V_k^{qq} + \oint \left[1 - 2 \frac{d_{1k}}{L_i} - \frac{a_k}{L_i} Z^* \right] Z^* R dR \\
 V_k^{pq} &= -2 V_k^{qq} + \oint \left[2 \frac{d_{1k}}{L_i} + \frac{a_k}{L_i} Z^* \right] Z^* R dR \\
 V_k^{qq} &= \oint \left[\left(\frac{d_{1k}}{L_i} \right)^2 + \frac{1}{2} \left(\frac{a_k}{L_i} R \right)^2 + \frac{d_{1k}}{L_i} \frac{a_k}{L_i} Z^* + \frac{1}{3} \left(\frac{a_k}{L_i} Z^* \right)^2 \right] Z^* R dR \quad (A.3)
 \end{aligned} \right.$$

$$\left\{ \begin{aligned}
 (ULB)_{ij} &= -2 \int_S Y_{ij} R dR dZ - (URB)_{ij} \\
 (URB)_{ij} &= -2 \int_S \left[\frac{d_{1k}}{L_i} + \frac{a_k}{L_i} Z^* \right] Y_{ij} R dR dZ \\
 (BB)_{ijm} &= - \int_S Y_{ij} Y_{im} R dR dZ^* \\
 (BS)_{kijn} &= - \int_S \left[\frac{\partial \phi_{kn}}{\partial R} + \frac{\phi_{kn}}{R} \right] Y_{ij} R dR dZ \quad (A.4)
 \end{aligned} \right.$$

$$\left\{ \begin{aligned}
 S_{kn}^p &= - S_{kn}^q + \sum_{j=1}^5 c_{kj}^n \left\{ 2j \oint R^{2j-1} Z^* dR \right\} \\
 &+ \sum_{j=6}^{10} c_{kj}^n \left\{ \oint \left[(R J_1'(i_{kj}R) + \frac{1}{j_{kj}} J_1(j_{kj}R)) \right] e^{j_{kj}(Z - \frac{\ell_k}{a_k})} dR \right\} \\
 S_{kn}^q &= \sum_{j=1}^5 c_{kj}^n \left\{ 2j \oint \left[\frac{d_{1k}}{L_i} + \frac{1}{2} \frac{a_k}{L_i} Z^* \right] Z^* R^{2j-1} dR \right\} \\
 &+ \sum_{j=6}^{10} c_{kj}^n \left\{ \oint \left[(R J_1'(j_{kj}R) + \frac{1}{j_{kj}} J_1(j_{kj}R)) \left(\frac{d_{1k}}{L_i} - \frac{a_k}{L_i} \frac{1}{j_{kj}} + \frac{a_k}{L_i} Z^* \right) \right. \right. \\
 &\left. \left. - \frac{a_k}{L_i} R^2 J_1(j_{kj}R) \right] e^{j_{kj}(Z - \frac{\ell_k}{a_k})} dR \right\} \tag{A.5}
 \end{aligned} \right.$$

and

$$\begin{aligned}
 S_{knm} &= \sum_{j=1}^5 \sum_{i=1}^5 c_{kj}^n c_{ki}^n (4_{ji} - 2j - 2i + 2) \oint R^{2j+2i-3} Z^* dR \\
 &+ \sum_{j=1}^5 \sum_{i=6}^{10} (c_{kj}^n c_{ki}^m + c_{kj}^m c_{ki}^n) \oint \left[(2j-1) J_1'(j_{ki}R) + \frac{1}{j_{ki}R} J_1(j_{ki}R) \right] \\
 &\cdot R^{2j-1} e^{j_{ki}(Z - \frac{\ell_k}{a_k})} dR
 \end{aligned}$$

$$\begin{aligned}
 & + \sum_{j=6}^{10} \sum_{i=6}^{10} c_{kj}^n c_{ki}^m \oint \left[j_{kj} j_{ki} R J_1'(i_{kj} R) J_1'(j_{ki} R) \right. \\
 & \left. + (j_{kj} j_{ki} R + \frac{1}{R}) J_1(i_{ki} R) J_1(j_{ki} R) \right] \frac{1}{j_{kj} + j_{ki}} \cdot \\
 & \cdot e^{(j_{kj} + j_{ki})(Z - \frac{l_k}{a_k})} dR \tag{A.6}
 \end{aligned}$$

The potential energy of the k^{th} tank (Eq. (3.7)) can be written in the following form

$$\begin{aligned}
 P_k & = \frac{1}{2} \rho_k \alpha_3 a_k^2 \int_{FS} \left[\sum_{n=1}^{N_k} \sum_{m=1}^{N_k} \xi_{kn} \xi_{km} \phi_{kn} \phi_{km} \right] \sin^2 \theta R dR d\theta \\
 & = \frac{\pi}{2} \rho_k \alpha_3 a_k^2 \sum_{n=1}^{N_k} \sum_{m=1}^{N_k} P_{knm} \xi_{kn} \xi_{km} \tag{A.7}
 \end{aligned}$$

where

$$P_{knm} = \int_0^l R \phi_{kn} \phi_{km} dR$$

Substituting Eq. (3.4) into the above equation, one finds

$$P_{knm} = \sum_{j=1}^5 \sum_{i=1}^5 c_{kj}^n c_{ki}^n \int_0^l R^{2j+2i-1} dR$$

$$\begin{aligned}
 & + \sum_{j=1}^5 \sum_{i=6}^{10} (c_{kj}^n c_{ki}^m + c_{kj}^m c_{ki}^n) \int_0^1 R^{2j} J_1(j_{ki} R) dR \\
 & + \sum_{j=6}^{10} \sum_{i=6}^{10} c_{kj}^n c_{ki}^m \int_0^1 R J_1(j_{kj} R) J_1(j_{ki} R) dR \\
 & = \sum_{j=1}^5 \sum_{i=1}^5 c_{kj}^n c_{ki}^m \frac{1}{2(i+j)} \\
 & + \sum_{j=1}^5 \sum_{i=6}^{10} (c_{kj}^n c_{ki}^m + c_{kj}^m c_{ki}^n) \int_0^1 R^{2j} J_1(j_{ki} R) dR \\
 & + \sum_{j=6}^{10} c_{kj}^n c_{kj}^m \frac{1}{2j_{ki}} (j_{kj}^2 - 1) \left[J_1(j_{kj}) \right]^2 \tag{A.8}
 \end{aligned}$$

Appendix B
SLOSH PROGRAM LISTINGS

```

$IBFTC SLOSH DECK
SUBROUTINE SLOSH(AIJ,BIJ,NCOR,NTANK,NSMODE)
C
C
C *** THIS PROGRAM PROVIDES PRELIMINARY INFORMATION ON THE DYNAMIC ***
C BEHAVIOR OF LIQUID PROPELLANT AND THE COEFFICIENTS OF
C LATERAL FORCE DISTRIBUTION (SATURN-V SPACE VEHICLE)
C
C AALPN(I,N) = COEFFICIENTS A-ALPHA-N ASSOCIATED WITH I-TH TANK
C ACCL = ACCELERATION LEVEL
C ALL(I) = LIQUID LEVEL IN I-TH TANK
C AIJ(I,J) = ELEMENTS OF MASS MATRIX
C BIJ(I,J) = ELEMENTS OF STIFFNESS MATRIX
C BL(I) = LENGTH OF I-TH BEAM
C BTHEN(I,N) = COEFFICIENTS B-THETA-N ASSOCIATED WITH I-TH TANK
C C(1,J,K) = PRELIMINARY EIGENVECTORS ASSOCIATED WITH S-IVB LH2 TANK
C C(2,J,K) = PRELIMINARY EIGENVECTORS ASSOCIATED WITH S-IVB LOX TANK
C C(3,J,K) = PRELIMINARY EIGENVECTORS ASSOCIATED WITH S-II LH2 TANK
C C(4,J,K) = PRELIMINARY EIGENVECTORS ASSOCIATED WITH S-II LOX TANK
C C(5,J,K) = PRELIMINARY EIGENVECTORS ASSOCIATED WITH S-IC LOX TANK
C C(6,J,K) = PRELIMINARY EIGENVECTORS ASSOCIATED WITH S-IC FUEL TANK
C CXIN(I,J,N) = COEFFICIENTS C-XI-N ASSOCIATED WITH THE J-TH SLOSH MODE
C OF I-TH TANK
C DBTBCM(I)= DISTANCE BETWEEN TANK BOTTOM AND CENTER OF MASS ASSOCIATED
C WITH I-TH TANK
C DTB(I) = DISTANCE BETWEEN TANK COORDINATE SYSTEM AND LOWER BEAM END
C ASSOCIATED WITH I-TH TANK
C ETA(I,J,K) = J-TH NORMAL MODE ASSOCIATED WITH I-TH TANK
C FTIME = FLIGHT TIME
C HN(I,N) = COEFFICIENTS HN ASSOCIATED WITH I-TANK
C INDX1 = 0, IF MASS OF LIQUID HAS ALREADY BEEN INCLUDED IN THE
C BENDING PROGRAM, OTHERWISE 1
C INDX2 = 0, NO LATERAL FORCE DISTRIBUTION COEFFICIENTS PRINT-OUT,
C OTHERWISE 1
C INDX3 = 0, ZERO LENGTH INTERSTAGES, OTHERWISE 1
C INDX4 = 0, NO NORMALIZED SLOSH NORMAL MODES PRINT-OUT, OTHERWISE 1
C INDX5 = 0, NO INTERMEDIATE COMPUTATION PRINT-OUT, OTHERWISE 1
C NCASE = NUMBER OF CASES

```

```

C NCOR = TOTAL NUMBER OF DEGREES OF FREEDOM OF BEAM END DISPLANCE-
C MENTS AND BEAM DEFLECTION FUNCTIONS
C NPT(I) = NUMBER OF PARTITIONS OF THE I-TH TANK
C NSFLIG = STAGE OF FLIGHT
C NSMODE = NUMBER OF SLOSH MODES CONSIDERED
C NTANK = NUMBER OF TANKS
C PEV(I,J) = J-TH PRELIMINARY EIGENVALUE ASSOCIATED WITH I-TH TANK
C RHO(I) = MASS DENSITY ASSOCIATED WITH I-TH TANK
C TTFCB(I,N) = THIRD TERM OF COEFFICIENT B-THETA-N ASSOC WITH I-TH TANK
C ZINC(I) = PARTITION HEIGHT OF I-TH TANK
C
C DIMENSION C(6,3,11), ETA(6,4,24), ETAMAX(6,3), PEV(6,3)
C DIMENSION DBLSCM(6), DBTBCM(6), P(6,3,3), RHO(6), S(6,3,3),
C 1 SP(6,3), SQ(6,3), PPVOL(6)
C DIMENSION YBDFL(6,4,8), ZBDFL(6,4)
C DIMENSION ELEMA(24,24), ELEM(24,24), AIJ(60,60), BIJ(60,60)
C DIMENSION BS(6,4,24)
C DIMENSION AALPN(6,32), BN(6,3), BTHEN(6,32), CXIN(6,3,32),
C 1 FASUM(3), GAMMA(6,3), HN(6,3), NPT(6), PIRALS(6),
C 2 TTFCB(6,32), ZINC(6), OMEGA(6,3)
C COMMON /CL2/DL(6), PHI(10), Z(6)
C COMMON /CL3/BL(3), DTB(6), SPU(10), SQU(10), U(10,10), V(10,10),
C 1 VPP(6), VPQ(6), VQG(6), VOL, G3(6), RADIUS
C COMMON /CL7/ NBDLF , INDF, UF(10), IND2, VF, VN, RALS(6),
C 1 ALL(6)
C COMMON /CL8/ BB(6,4,4), BFORDS(4,3), BFSLPS(4,3), ULB(6,4),
C 1 URB(6,4)
C EQUIVALENCE (ETA(1,1,1),ELEMA(1,1),AALPN(1,1)),
C 1 (ELEM(1,1),BS(1,1,1),CXIN(1,1,1)), (GAMMA(1,1),SP(1,1)),
C 2 (ETAMAX(1,1),BN(1,1)), (YBDFL(1,1,1),BTHEN(1,1)),
C 3 (C(1,1,1),TTFCB(1,1))
C READ(5,2) NSFLIG, NCASE, NSMODE, INDX1, INDX2, INDX3, INDX4, INDX5
C 2 FORMAT(8I10)
C NBEAM = 4 - NSFLIG
C NTANK = 8 - 2*NSFLIG
C NBDLF = 4
C READ(5,6) FTIME, ACCL, (ALL(I),I=1,NTANK)
C 6 FORMAT(8E10,6)

```

```

READ(5,6) (RHO(I),I=1,NTANK)
READ(5,6) (DBTBCM(I),I=1,NTANK)
READ(5,6) (BL(I),I=1,NBEAM)
READ(5,6) (DTB(I),I=1,NTANK)
READ(5,6) ((PEV(I,J),J=1,3),I=1,NTANK)
READ(5,10) (((C(I,J,K),K=1,10),J=1,3),I=1,NTANK)
READ(5,6) (((YBDLF(K,J,I),I=1,4),J=1,NBDF),K=1,NTANK)
READ(5,6) ((ZBDF(K,I),I=1,4),K=1,NTANK)
READ(5,2) (NPT(I),I=1,NTANK)
READ(5,6) (ZINC(I),I=1,NTANK)
READ(5,6) ((HN(I,J),J=1,3),I=1,NTANK)
10 FORMAT(10E8.4)

C
C COMPUTATION OF DISTANCE BETWEEN LIQUID SURFACE AND C.M. AND TANK
C RADIUS AT LIQUID SURFACE
C
DO 11 I=1,NTANK
PLEVEL = ALL(I)
CALL CONTR(PLEVEL,ORLS,I)
RALS(I) = ORLS
11 DBLSCM(I) = ALL(I) - DBTBCM(I)
G3(1) = 6.8 + DBTBCM(1)
G3(2) = 4.54 + DBTBCM(2)
G3(3) = 4.68 + DBTBCM(3)
G3(4) = 1.16 + DBTBCM(4)
G3(5) = 22.6 + DBTBCM(5)
G3(6) = 8.71 + DBTBCM(6)
IF(INDX3.EQ.0) GO TO 13
BL(1) = 36.6
BL(3) = 12.09
DTB(1) = 2.1814
DTB(2) = 0.0992
DTB(5) = 20.6197
DTL(6) = 6.72968
G3(1) = 1.14 + DBTBCM(1)
G3(2) = -1.12 + DBTBCM(2)
G3(5) = 17.1 + DBTBCM(5)
G3(6) = 3.21 + DBTBCM(6)

```

```

13 MCASE = 0
    MCASE = MCASE + 1
    WRITE(6,14) NSFLIG, NCASE, NSMODE, NTANK
14 FORMAT(1H1, 30X, 48H PROPELLANT BEHAVIOR IN SATURN-V SPACE VEHICLE
    1 // // 19H STAGE OF FLIGHT = , 12 // 19H NUMBER OF CASES = , 12 //
    2 25H NUMBER OF SLOSH MODES = , 12 // 19H NUMBER OF TANKS = , 12)
    WRITE(6,18) MCASE, FTIME, ACCL
18 FORMAT( 1H0, 5HCASE , 12 // 15H FLIGHT TIME = , F8.2, 5H SEC //
    1 22H ACCELERATION LEVEL = , E16.8, 8H M/S**2 )
    WRITE(6,20) INDX1, INDX2, INDX3, INDX4, INDX5
20 FORMAT(1H0, 7HINDX1 =, 12, 8H INDX2 =, 12, 8H INDX3 =, 12,
    1 8H INDX4 =, 12, 8H INDX5 =, 12)
    WRITE(6,22) (ALL(I),I=1,NTANK)
22 FORMAT( 1H0, 32X, 92H
    1 TANK 4 TANK 5 TANK 6 //22H PROPELLANT L
    2EVEL(M) , 11X, 6E16.8)
    WRITE(6,26) (RHO(I),I=1,NTANK)
26 FORMAT( 1H0,23H MASS DENSITY(KG/M**3) , 9X, 6E16.8)
    WRITE(6,30) (RALS(I),I=1,NTANK)
30 FORMAT( 1H0, 32H RADIUS AT LIQUID SURFACE(M) , 6E16.8)
    WRITE(6,34) (DBTBCM(I),I=1,NTANK)
34 FORMAT( 1H0, 32H DISTANCE BETWEEN TB AND CM(M) , 6E16.8)
    DO 43 J=1,NSMODE
    IF(J.NE. 1) GO TO 39
    WRITE(6,38) (PEV(I,J),I=1,NTANK)
38 FORMAT( 1H0, 25H PRELIMINARY EIGENVALUES , 7X, 6E16.8)
    GO TO 43
39 WRITE(6,42) (PEV(I,J),I=1,NTANK)
42 FORMAT( 1H0, 32X, 6E16.8)
43 CONTINUE
    WRITE(6,44) (DTB(I),I=1,NTANK)
44 FORMAT( 1H0, 66H DISTANCE BETWEEN LOWER BEAM END AND TANK COORD. S
    1 SYSTEM ORIGIN(M) // 33X, 6E16.8)
    WRITE(6,45) (BL(I),I=1,NBEAM)
45 FORMAT( 1H0, 16H BEAM LENGTH(M) // 3E20.8)
    WRITE(6,46) ((C(1,J,K),K=1,10),J=1,NSMODE)
46 FORMAT( 1H0, 15X, 57H PRELIMINARY EIGENVECTORS ASSOCIATED WITH S-I
    1VB LH2 TANK // (10E13.4))

```

```

WRITE(6,50) ((C(2,J,K),K=1,10),J=1,NSMODE)
50 FORMAT( 1H0, 15X, 57H PRELIMINARY EIGENVECTORS ASSOCIATED WITH S-I
1VB LOX TANK // (10E13.4))
IF(NTANK .EQ. 2) GO TO 67
WRITE(6,54) ((C(3,J,K),K=1,10),J=1,NSMODE)
54 FORMAT( 1H0, 15X, 57H PRELIMINARY EIGENVECTORS ASSOCIATED WITH S-I
1I LH2 TANK // (10E13.4))
WRITE(6,58) ((C(4,J,K),K=1,10),J=1,NSMODE)
58 FORMAT( 1H0, 15X, 57H PRELIMINARY EIGENVECTORS ASSOCIATED WITH S-I
1I LOX TANK // (10E13.4))
IF(NTANK .EQ. 4) GO TO 67
WRITE(6,62) ((C(5,J,K),K=1,10),J=1,NSMODE)
62 FORMAT( 1H0, 15X, 57H PRELIMINARY EIGENVECTORS ASSOCIATED WITH S-I
1C LOX TANK // (10E13.4))
WRITE(6,66) ((C(6,J,K),K=1,10),J=1,NSMODE)
66 FORMAT( 1H0, 15X, 57H PRELIMINARY EIGENVECTORS ASSOCIATED WITH S-I
1C FUEL TANK // (10E13.4))
67 CONTINUE
DO 70 K=1,NTANK
K1 = K
WRITE(6,68) K1, (ZBDLF(K1,I),I=1,4), (ZBDLF(K1,I),I=1,4),
1 ((YBDF(K1,J,I),I=1,4),J=1,2)
68 FORMAT( 1H0, 30H BENDING DEFLECTION FUNCTIONS // 6H TANK , 12, 4X,
1 4E14.6, 4X, 4E14.6 / 12X, 4E14.6, 4X, 4E14.6)
WRITE(6,69) (ZBDLF(K1,I),I=1,4), (ZBDLF(K1,I),I=1,4),
1 ((YBDF(K1,J,I),I=1,4),J=3,4)
69 FORMAT( 1H0, 11X, 4E14.6, 4X, 4E14.6/ 12X, 4E14.6, 4X, 4E14.6)
70 CONTINUE
IF(INDX4 .EQ. 0) GO TO 107
C
C COMPUTATION OF SLOSH NORMAL MODES
C
DO 81 I=1,NTANK
DL(I) = DBLSCM(I)/RALS(I)
Z(I) = DBLSCM(I)/RALS(I)
DO 79 J=1,NSMODE
R = 0.0
DO 75 K=1,21

```

```

CALL PSMODE(I,R,PHI)
ETA(I,J,K) = 0.0
DO 71 L=1,10
71 ETA(I,J,K) = ETA(I,J,K) + C(I,J,L)*PHI(L)
75 R = R + 0.05
79 CONTINUE
81 CONTINUE
INDEX = 0
IF(INDEX .EQ. 0) GO TO 103
WRITE(6,82) ((ETA(1,J,K),K=1,21),J=1,NSMODE)
82 FORMAT( 1H0, 10X, 54H PRELIMINARY SLOSH MODES(THE INCREMENT OF R I
1S 0.05) // 21H FOR S-IVB LH2 TANK // (7E18.5))
85 WRITE(6,86) ((ETA(2,J,K),K=1,21),J=1,NSMODE)
86 FORMAT( 1H0, 21H FOR S-IVB LOX TANK // (7E18.5))
IF(NTANK .EQ. 2) GO TO 103
WRITE(6,90) ((ETA(3,J,K),K=1,21),J=1,NSMODE)
90 FORMAT( 1H0, 20H FOR S-II LH2 TANK // (7E18.5))
WRITE(6,94) ((ETA(4,J,K),K=1,21),J=1,NSMODE)
94 FORMAT( 1H0, 20H FOR S-II LOX TANK // (7E18.5))
IF(NTANK .EQ. 4) GO TO 103
WRITE(6,98) ((ETA(5,J,K),K=1,21),J=1,NSMODE)
98 FORMAT( 1H0, 20H FOR S-IC LOX TANK // (7E18.5))
WRITE(6,102) ((ETA(6,J,K),K=1,21),J=1,NSMODE)
102 FORMAT( 1H0, 21H FOR S-IC FUEL TANK // (7E18.5))
103 IF(INDEX .EQ. 1) GO TO 107
DO 105 I = 1,NTANK
DO 105 J=1,NSMODE
ETAMAX(I,J) = ABS(ETA(I,J,21))
DO 105 K=1,21
105 ETA(I,J,K) = ETA(I,J,K)/ETAMAX(I,J)
WRITE(6,106) ((ETA(1,J,K),K=1,21),J=1,NSMODE)
106 FORMAT( 1H0, 10X, 68H PRELIMINARY SLOSH MODES(THE INCREMENT OF R I
1S 0.05) --- NORMALIZED // 21H FOR S-IVB LH2 TANK // (7E18.5))
INDEX = INDEX + 1
GO TO 85

```

C
C COMPUTATION OF COEFFICIENTS OF KINETIC AND POTENTIAL ENERGY TERMS
C ASSOCIATED WITH PROPELLANT SLOSHING

```

C 107 INDF = 2
  PI = 3.1415927
  DO 113 K=1,NTANK
    PLEVEL = ALL(K)
    CALL CINTL(K, PLEVEL)
    PIRALS(K) = PI*RALS(K)**2
    PPVOL(K) = VOL
  DO 113 N=1,NSMODE
    SUM1 = 0.0
    SUM2 = 0.0
    OMEGA(K,N) = SQRT(ACCL*PEV(K,N)/RALS(K))
    DO 111 I=1,10
      DO 109 J=1,10
        109 SUM2 = SUM2 + C(K,N,I)*C(K,N,J)*V ( I,J)
        111 SUM1 = SUM1 + C(K,N,I)*V ( 1,I)
      GAMMA(K,N) = PIRALS(K)*DBLSCM(K)*SUM2/PPVOL(K)
      113 BN(K,N) = PIRALS(K)*RALS(K)*SUM1/(PPVOL(K)*GAMMA(K,N))
    INDF = 0
  DO 165 K=1,NTANK
    PLEVEL = ALL(K)
    CALL CINTL(K, PLEVEL)
  DO 139 M=1,NSMODE
  DO 135 N=M,NSMODE
    SUM1 = 0.0
    SUM2 = 0.0
    DO 115 I=1,10
      DO 115 J=1,10
        SUM1 = SUM1 + C(K,M,I)*C(K,N,J)*U(I,J)
        115 SUM2 = SUM2 + C(K,M,I)*C(K,N,J)*V(I,J)
      S(K,M,N) = SUM1
      135 P(K,M,N) = SUM2
      SUM1 = 0.0
      SUM2 = 0.0
    DO 137 I=1,10
      SUM1 = SUM1 + C(K,M,I)*SPU(I)
      137 SUM2 = SUM2 + C(K,M,I)*SQU(I)
    SP(K,M) = SUM1

```



```

SQ(K,M) = SUM2
139 CONTINUE
DO 141 M=2,NSMODE
M1 = M - 1
DO 141 N=1,M1
S(K,M,N) = S(K,N,M)
141 P(K,M,N) = P(K,N,M)
IF(INDX5.EQ. 0) GO TO 165
WRITE(6,142) K, ((S(K,M,N),N=1,NSMODE),M=1,NSMODE)
142 FORMAT(1H0, 96H COEFFICIENTS OF KINETIC AND POTENTIAL ENERGY TERMS
1 ASSOCIATED WITH PROPELLANT SLOSHING OF TANK , I2 // 15X, 22H COEF
2FICIENTS S(M,N) // (5E24.8))
WRITE(6,144) ((P(K,M,N),N=1,NSMODE),M=1,NSMODE)
144 FORMAT(1H0, 15X, 22H COEFFICIENTS P(M,N) // (5E24.8))
WRITE(6,150) K, (SP(K,M),M=1,NSMODE)
150 FORMAT(1H0, 30H COEFFICIENTS SP(K,M) OF TANK , I2 // 5E24.8)
WRITE(6,154) K, (SQ(K,M),M=1,NSMODE)
154 FORMAT(1H0, 30H COEFFICIENTS SQ(K,M) OF TANK , I2 // 5E24.8)
C
C COMPUTATION OF VOLUME AND MASS OF LIQUID PROPELLANT
C
AMASS = RHO(K)*VOL
WRITE(6,158) K, VOL, AMASS
158 FORMAT(1H0, 56H VOLUME AND MASS OF LIQUID PROPELLANT CONTAINED IN
1TANK , I2 , 5H ARE , E14.6, 10H M**3 AND, E14.6, 20H KG, RESPECTI
2VELY. )
165 CONTINUE
C
C COMPUTATION OF THE ELEMENTS OF THE MASS AND STIFFNESS MATRICES
C ASSOCIATED WITH PROPELLANT SLOSHING
C
DO 173 K=1,NTANK
TEMPC = - PIRALS(K)*RHO(K)*RALS(K)
VPP(K) = TEMPC*VPP(K)
VPQ(K) = TEMPC*VPQ(K)
VQQ(K) = TEMPC*VQQ(K)
DO 169 N=1,NSMODE
TEMPC1 = TEMPC/PEV(K,N)

```

```

SP(K,N) = TEMPC1*SP(K,N)
SQ(K,N) = TEMPC1*SQ(K,N)
169 TEMPC2 = 0.5*PIRALS(K)*RHO(K)*ACCL
DO 171 M=1,NSMODE
DO 171 N=1,NSMODE
TEMPC1 = 0.5*TEMPC/(PEV(K,M)*PEV(K,N))
S(K,M,N) = TEMPC1*S(K,M,N)
171 P(K,M,N) = TEMPC2*P(K,M,N)
173 CONTINUE
IF(INDX5.EQ.0) GO TO 175
WRITE(6,178) (VPP(K),K=1,NTANK) // 6E20.8)
178 FORMAT(1H0, 25H COEFFICIENTS VPP(NTANK) // 6E20.8)
WRITE(6,180) (VPQ(K),K=1,NTANK)
180 FORMAT(1H0, 25H COEFFICIENTS VPQ(NTANK) // 6E20.8)
WRITE(6,182) (VQQ(K),K=1,NTANK)
182 FORMAT(1H0, 25H COEFFICIENTS VQQ(NTANK) // 6E20.8)
175 CONTINUE
DO 177 I=1,24
DO 177 J=1,24
ELEMA(I,J) = 0.0
177 ELEM B(I,J) = 0.0
ELEMA(1,1) = 2.0*(VPP(5) + VPP(6))
ELEMA(1,2) = VPQ(5) + VPQ(6)
ELEMA(2,2) = 2.0*(VQQ(5) + VQQ(6))
ELEMA(3,3) = 2.0*(VPP(3) + VPP(4))
ELEMA(3,4) = VPQ(3) + VPQ(4)
ELEMA(4,4) = 2.0*(VQQ(3) + VQQ(4))
ELEMA(5,5) = 2.0*(VPP(1) + VPP(2))
ELEMA(5,6) = VPQ(1) + VPQ(2)
ELEMA(6,6) = 2.0*(VQQ(1) + VQQ(2))
K = 10 + 4*(NSMODE - 1)
IF(INDX3.NE.0) GO TO 179
ELEMA(2,2) = ELEMA(2,2) + ELEMA(3,3)
ELEMA(2,3) = ELEMA(3,4)
ELEMA(3,3) = ELEMA(4,4) + ELEMA(5,5)
ELEMA(3,4) = ELEMA(5,6)
ELEMA(4,4) = ELEMA(6,6)
ELEMA(5,5) = 0.0

```

```

ELEMA(5,6) = 0.0
ELEMA(6,6) = 0.0
K = 8 + 4*(NSMODE - 1)
179 I6 = NTANK - 1
DO 185 I=1,I6,2
N = I
L = 6 - I
IF(I .EQ. 3) K = 8 + 2*(NSMODE - 1)
IF(I .EQ. 5) K=6
IF(INDX3 .NE. 0) GO TO 183
IF(I .EQ. 1) GO TO 183
K = 6 + 2*(NSMODE - 1)
N = I - 1
IF(I .EQ. 3) GO TO 183
K = 4
N = I - 2
183 N1 = N + 1
DO 185 M=1,2
DO 184 J=1,NSMODE
K = K + 1
ELEMA(N,K) = SP(L,J)
184 ELEMA(N1,K) = SQ(L,J)
185 L = L + 1
NRBD = NBEAM + 1
IF(INDX3 .NE. 0) NRBD = 2*NBEAM
NTKSM = NTANK*NSMODE
I = 0
L = 0
K5 = 5
IF(INDX3 .NE. 0 ) K5=7
K6 = NTKSM + NRBD
DO 193 K=K5,K6
IF(I .EQ. 0) L = L + 1
I = I + 1
GO TO (186,187,188), I
186 K2 = NSMODE
GO TO 189
187 K2 = NSMODE - 1

```

```

GO TO 189
188 K2 = 1
189 J = I - 1
N = 0
DO 191 K1=1,K2
M = K + N
N = N + 1
J = J + 1
ELEMA(K,M) = 2.0*S(L,I,J)
191 ELEM(K,M) = 2.0*P(L,I,J)
IF(I .EQ. NSMODE) I = 0
193 CONTINUE
DO 197 I=2,K6
I1 = I - 1
DO 197 J=1,I1
ELEMA(I,J) = ELEMA(J,I)
197 ELEM(I,J) = ELEM(J,I)
I1 = NCOR + 1
I2 = NCOR + NTKSM
M1 = 1
IF(NBEAM .EQ. 3) GO TO 200
GO TO (198,199), NBEAM
198 M1 = 3
IF(INDX3 .NE. 0) M1=5
GO TO 200
199 M1 = 2
IF(INDX3 .NE. 0) M1=3
200 DO 201 I=1,I2
DO 201 J=1,I2
AIJ(I,J) = 0.0
201 BIJ(I,J) = 0.0
IF(INDX1 .EQ. 0) GO TO 207
N1 = M1
DO 205 I=1,NRBD
N2 = M1
DO 203 J=1,NRBD
AIJ(I,J) = ELEMA(N1,N2)
203 N2 = N2 + 1

```

```

205 N1 = N1 + 1
207 N1 = M1
DO 211 I=1, NRBD
  K1 = 5
  IF(INDX3 .NE. 0) K1=7
DO 209 J=I1, I2
  AIJ(I, J) = ELEMA(N1, K1)
  AIJ(J, I) = AIJ(I, J)
209 K1 = K1 + 1
211 N1 = N1 + 1
  K1 = 5
  IF(INDX3 .NE. 0) K1=7
DO 215 I=I1, I2
  K2 = 5
  IF(INDX3 .NE. 0) K2=7
DO 213 J=I1, I2
  AIJ(I, J) = ELEMA(K1, K2)
  BIJ(I, J) = ELEM(B(K1, K2)
213 K2 = K2 + 1
215 K1 = K1 + 1
C
C COMPUTATION OF BENDING-BENDING, BENDING-RIGID AND BENDING-SLOSH
C TERM
C
  INDF = 11
DO 603 K=1, NTANK
DO 603 I=1, 4
603 ZBDLF(K, I) = ZBDLF(K, I)/RALS(K)
DO 641 K=1, NTANK
  PLEVEL = ALL(K)
DO 611 J=1, NBDLF
DO 611 I=1, 3
  L = I + 1
  BFSLPS(J, I) = (ZBDLF(K, I) - ZBDLF(K, L))/(YBDLF(K, J, I) -
1 YBDLF(K, J, L))
611 BFORDS(J, I) = ZBDLF(K, I) - BFSLPS(J, I)*YBDLF(K, J, I)
  CALL CINTL(K, PLEVEL)
DO 631 J=1, NBDLF

```

```

DO 631 N=1,NSMODE
SUM1 = 0.0
DO 621 I=1,10
621 SUM1 = SUM1 + C(K,N,I)*U(J,I)
631 BS(K,J,N) = SUM1
641 CONTINUE
DO 671 K=1,NTANK
PIA3RH = PI*RHO(K)*RALS(K)**3
DO 671 J=1,NBDLF
ULB(K,J) = PIA3RH*ULB(K,J)
URB(K,J) = PIA3RH*URB(K,J)
DO 651 I=1,NBDLF
651 BB(K,J,I) = PIA3RH*BB(K,J,I)
DO 661 N=1,NSMODE
661 BS(K,J,N) = PIA3RH*BS(K,J,N)/PEV(K,N)
671 CONTINUE
K1 = 6
K2 = 5
IF(INDX3 .NE. 0) GO TO 701
J = NBEAM + 3
DO 691 I=1,NBEAM
I1 = I + 1
DO 681 L=1,NBDLF
AIJ(I,J) = ULB(K1,L) + ULB(K2,L)
AIJ(J,I) = AIJ(I,J)
AIJ(I1,J) = URB(K1,L) + URB(K2,L)
AIJ(J,I1) = AIJ(I1,J)
681 J = J + 1
K1 = K1 - 2
691 K2 = K2 - 2
GO TO 731
701 J = 2*NBEAM + 3
DO 721 I=1,NBEAM
I1 = 2*I - 1
I2 = 2*I
DO 711 L=1,NBDLF
AIJ(I1,J) = ULB(K1,L) + ULB(K2,L)
AIJ(J,I1) = AIJ(I1,J)

```

```

AIJ(I2,J) = URB(K1,L) + URB(K2,L)
AIJ(J,I2) = AIJ(I2,J)
711 J = J + 1
    K1 = K1 - 2
721 K2 = K2 - 2
731 I1 = NCOR - 15
    K1 = 6
    K2 = 5
DO 761 K=1,NBEAM
DO 751 L=1,NBDLF
  J = I1
DO 741 M=L,NBDLF
  AIJ(I1,J) = 2.0*(BB(K1,L,M) + BB(K2,L,M))
  IF(I1 .NE. J) AIJ(J,I1) = AIJ(I1,J)
741 J = J + 1
751 I1 = I1 + 1
    K1 = K1 - 2
761 K2 = K2 - 2
    I1 = NCOR - 7
    J1 = NCOR + 1
DO 791 K=1,NTANK
DO 781 L=1,NSMODE
  I2 = I1
DO 771 M=1,NBDLF
  AIJ(I2,J1) = BS(K,M,L)
  AIJ(J1,I2) = AIJ(I2,J1)
771 I2 = I2 + 1
781 J1 = J1 + 1
  IF(K .EQ. 2) I1 = I1 - NBDLF
  IF(K .EQ. 4) I1 = I1 - NBDLF
791 CONTINUE
  IF(INDX5 .EQ. 0) GO TO 239
  I2 = NCOR + NTKSM
  WRITE(6,220) ((AIJ(I,J),J=1,I2), I=1,I2)
220 FORMAT(1H0, 44H ELEMENTS OF A-MATRIX ASSOCIATED WITH SLOSH //
1 (10E13.4))
  WRITE(6,222) ((BIJ(I,J),J=1,I2), I=1,I2)
222 FORMAT(1H0, 44H ELEMENTS OF B-MATRIX ASSOCIATED WITH SLOSH //

```

```

1 (10E13.4)
C
C COMPUTATION OF LATERAL FORCE DISTRIBUTION COEFFICIENTS
C
239 IF(INDX2 .EQ. 0) GO TO 281
   INDF = 1
   NPTMAX = NPT(1)
DO 253 K=2,NTANK
   IF(NPT(K) .GT. NPTMAX) NPTMAX=NPT(K)
253 CONTINUE
   IF(NPTMAX .GT. 50) NPTMAX = 50
DO 257 K=1,NTANK
DO 257 I=1,NPTMAX
   AALPN(K,I) = 0.0
   BTHEN(K,I) = 0.0
DO 257 J=1,NSMODE
257 CXIN(K,J,I) = 0.0
DO 279 KDK=1,NTANK
   K = KDK
261 PLEVEL = ALL(K)
   KK = NPT(K)
   IF(KK .GT. 50) KK = NPTMAX
DO 275 I=1,KK
   CALL CONTR(PLEVEL,ORLS,K)
   RADIUS = ORLS
   IF(I .EQ. 1) RALS(K) = ORLS
   CALL CINTL(K, PLEVEL)
   PLEVEL = PLEVEL - ZINC(K)
DO 267 N=1,NSMODE
   SUM3 = 0.0
DO 263 J=1,10
263 SUM3 = SUM3 + C(K,N,J)*UF(J)
   CXIN(K,N,I) = PIRALS(K)*RHO(K)*SUM3
267 FASUM(N) = SUM3
   SUM1 = 0.0
   SUM2 = 0.0
DO 271 N=1,NSMODE
   SUM1 = SUM1 + BN(K,N)*FASUM(N)

```



```

271 SUM2 = SUM2 + (G3(K)*BN(K,N) - DBLSCM(K)*(BN(K,N) - HN(K,N)))*
1 FASUM(N)
AALPN(K,I) = -RHO(K)*VN + PIRALS(K)*RHO(K)*DBLSCM(K)*SUM1
275 BTHEN(K,I) = - RHO(K)*VF*PIRALS(K)**2/PI - G3(K)*RHO(K)*VN
1 + PIRALS(K)*RHO(K)*DBLSCM(K)*SUM2
279 CONTINUE
281 CONTINUE
DO 9 I=1,NTANK
II = NPT(I)
IF(II .GT. 50) II = 50
9 READ(5,6) (TTFCB(I,J),J=1,II)
IF(INDX2 .EQ. 0) RETURN
DO 283 K=1,NTANK
II = NPTMAX - 1
DO 283 I=1,II
II = I + 1
AALPN(K,I) = AALPN(K,I) - AALPN(K,II)
BTHEN(K,I) = BTHEN(K,I) - BTHEN(K,II) - RHO(K)*TTFCB(K,I)
DO 283 J=1,NSMODE
283 CXIN(K,J,I) = CXIN(K,J,I) - CXIN(K,J,II)
WRITE(6,288) (NPT(I),I=1,NTANK)
288 FORMAT(1H1, 15X, 45H COEFFICIENTS OF LATERAL FORCE DISTRIBUTION
1 // 32X, 92H TANK 1 TANK 2 TANK 3
2 TANK 4 TANK 5 TANK 6 // 25H NUMBER OF PARTITION
35 , 6I16)
WRITE(6,290) (ZINC(I),I=1,NTANK)
290 FORMAT(1H0, 21H PARTITION HEIGHT(M) , 11X, 6E16.8)
DO 297 J=1,NSMODE
IF(J .NE. 1) GO TO 295
WRITE(6,292) (HN(I,J),I=1,NTANK)
292 FORMAT(1H0, 26H COEFFICIENTS HN(DIM-LESS), 6X, 6E16.8)
GO TO 297
295 WRITE(6,296) (HN(I,J),I=1,NTANK)
296 FORMAT(1H0, 32X,6E16.8)
297 CONTINUE
DO 303 J=1,NPTMAX
IF(J .NE. 1) GO TO 301
WRITE(6,300) (TTFCB(I,J),I=1,NTANK)

```

```

300 FORMAT(1H0, 47H THIRD TERM OF FORCE COEFFICIENT B-THETA(KG-M) //
1 32X, 6E16.8)
GO TO 303
301 WRITE(6,302) (TTFCB(I,J), I=1,NTANK)
302 FORMAT(32X, 6E16.8)
303 CONTINUE
DO 307 J=1,NSMODE
IF(J.NE. 1) GO TO 305
WRITE(6,304) (OMEGA(I,J), I=1,NTANK)
304 FORMAT(1H0, 32H NATURAL FREQUENCIES(RAD/SEC) , 6E16.8)
GO TO 307
305 WRITE(6,302) (OMEGA(I,J), I=1,NTANK)
307 CONTINUE
DO 311 I=1,NPTMAX
IF(I.NE. 1) GO TO 309
WRITE(6,308) (AALPN(K,I), K=1,NTANK)
308 FORMAT(1H0, 32H COEFFICIENTS A-ALPHA-N(KG) , 6E16.8)
GO TO 311
309 WRITE(6,302) (AALPN(K,I), K=1,NTANK)
311 CONTINUE
DO 317 I=1,NPTMAX
IF(I.NE. 1) GO TO 315
WRITE(6,314) (BTHEN(K,I), K=1,NTANK)
314 FORMAT(1H0, 32H COEFFICIENTS B-THETA-N(KG-M) , 6E16.8)
GO TO 317
315 WRITE(6,302) (BTHEN(K,I), K=1,NTANK)
317 CONTINUE
DO 323 J=1,NSMODE
DO 323 I=1,NPTMAX
IF(I.NE. 1) GO TO 321
WRITE(6,320) J, (CXIN(K,J,I), K=1,NTANK)
320 FORMAT(1H0, 54H COEFFICIENTS C-XI-N ASSOCIATED WITH SLOSH MODE(KG/
1M) , 12 // 32X, 6E16.8)
GO TO 323
321 WRITE(6,302) (CXIN(K,J,I), K=1,NTANK)
323 CONTINUE
5991 CONTINUE
RETURN

```

```

END
$IBFTC SUB1 DECK
BLOCK DATA
COMMON /BLK1/A(7),B(7),O(7)
COMMON /BLK2/G(16),X(16)
COMMON /BLK3/RJ1P(5)
DATA (A(M),M=1,7)/0.5,-0.56249985,0.21093573,-0.03954289,
1 0.00443319,-0.00031761,0.00001109/, (B(M),M=1,7)/0.79788456,
2 0.00000156,0.01659667,0.00017105,-0.00249511,0.00113653,
3 -0.00020033/, (O(M),M=1,7)/-2.3561945,0.12499612,0.00005650,
4 -0.00637879,0.00074348,0.00079824,-0.00029166/
DATA (G(I),I=1,16)/0.18945061,0.18260342,0.16915652,0.14959599,
1 0.12462897,0.09515851,0.06225352,0.02715246,0.02715246,
2 0.06225352,0.09515851,0.12462897,0.14959599,0.16915652,
3 0.18260342,0.18945061/, (X(I),I=1,16)/0.09501251,0.28160355,
4 0.45801678,0.61787624,0.75540441,0.86563120,0.94457502,
5 0.98940094,-0.98940094,-0.94457502,-0.86563120,-0.75540441,
6 -0.61787624,-0.45801678,-0.28160355,-0.09501251/
DATA (RJ1P(M),M=1,5)/1.8411837,5.3314427,8.5363163,11.706004,
1 14.863588/
END

```

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$IBFTC SUB2 DECK
SUBROUTINE PSMODE(I,R,PHI)
C
C THIS SUBROUTINE PROVIDES THE EIGENFUNCTIONS FOR THE COMPUTATION OF
C SLOSH NORMAL MODES
C
COMMON /BLK1/A(7),B(7),O(7)
COMMON /BLK3/RJ1P(5)
COMMON /CL2/DL(6), PHI(10), Z(6)
DO 6001 L=1,5
6001 PHI(L) = R**(2*L - 1)
DO 6017 L=1,5
M = L + 5
AJNR = RJ1P(L)*R
IF(AJNR .GT. 3.0) GO TO 6009
T = AJNR/3.0
SUM = 0.5

```

```

DO 6005 N=2,7
6005 SUM = SUM + A(N)*T**(2*N - 2)
BJ1 = AJNR*SUM
PHI(M) = BJ1/EXP(RJIP(L))*ABS(DL(I) - Z(I))
GO TO 6017
6009 T = 3.0/AJNR
SUM1 = 0.0
SUM2 = AJNR
DO 6013 N=1,7
SUM1 = SUM1 + B(N)*T**(N - 1)
SUM2 = SUM2 + O(N)*T**(N - 1)
6013 SUM2 = SUM2 + O(N)*T**(N - 1)
BJ1 = (1.0/AJNR**0.5)*SUM1*COS(SUM2)
PHI(M) = BJ1/EXP(RJIP(L))*ABS(DL(I) - Z(I))
6017 CONTINUE
RETURN
END
$IBFTC SUB3 DECK
SUBROUTINE CINTL(K, PLEVEL)
C GAUSSIAN QUADATURE FORMULA IS USED IN THIS SUBROUTINE TO EVALUATE LINE
C INTEGRALS WITH ARBITRARY LIMITS (P,Q).
C
COMMON /BLK2/G(16),X(16)
COMMON /BLK3/RJIP(5)
COMMON /CL3/BL(3), DTB(6), SPU(10), SQU(10), U(10,10), V(10,10),
1 VPP(6), VPG(6), VQG(6), VQQ(6), VOL, G3(6), RADIUS
COMMON /CL4/BJ1(4,5,16), BJ1A(5,21), BJIP(4,5,16), EPS
COMMON /CL5/PL(4), QL(4), QMP(4), VZ(4,16)
COMMON /CL6/VR(4,16)
COMMON /CL7/ NBDLF , INDF, UF(10), INDX2, VF, VN, RALS(6),
1 ALL(6)
COMMON /CL8/ BB(6,4,4), BFORDS(4,3), BFSLPS(4,3), ULB(6,4),
1 URB(6,4)
COMMON /CL9/ IDXB, RORALS
COMMON /TEMP/BJIPA(5,21), BJOA(5,21)
BOA = 0.70698979
AORS = (4.9784/RALS(K))*2
RIOVRP = 1.0
IF(INDF .EQ. 1) RIOVRP = RADIUS/RALS(K)

```

```

PL(1) = 0.0
PL(2) = RIOVRP
QL(2) = 0.0
PL(3) = RIOVRP
QL(3) = 0.0
EPS = 0.0
IF(INDF .EQ. 1) GO TO 6097
GO TO (6085,6085,6089,6089,6089,6093,6093), K
6085 DTBBL = DTB(K)/BL(3)
RALSBL = RALS(K)/BL(3)
GO TO 6097
6089 DTBBL = DTB(K)/BL(2)
RALSBL = RALS(K)/BL(2)
GO TO 6097
6093 DTBBL = DTB(K)/BL(1)
RALSBL = RALS(K)/BL(1)
6097 IF(INDF .EQ. 11) GO TO 9061
6099 GO TO (6101,6141,6147,6155,6161,6161), K
6101 IF(PLEVEL .GT. 2.2606) GO TO 6105
PL(1) = SQRT(10.903204 - (PLEVEL + 1.0414)**2)/RALS(K)
QL(1) = 3.1334786/RALS(K)
PL(2) = QL(1)
QL(2) = RIOVRP
QL(3) = PL(1)
EPS = PL(1)
GO TO 6109
6105 IF(PLEVEL .GT. 7.8486) GO TO 6107
QL(1) = 3.1334786/RALS(K)
PL(2) = QL(1)
QL(2) = RIOVRP
GO TO 6109
6107 QL(1) = 3.1334786/RALS(K)
PL(2) = QL(1)
QL(2) = 3.302/RALS(K)
PL(3) = QL(2)
QL(3) = RIOVRP
PL(4) = RIOVRP
QL(4) = 0.0

```

```

NII = 4
GO TO 6111
6109 NII = 3
6111 CALL TKCONF(NII,PL,QL,QMP,VR,VZ,CMH,BOA,AORS,PLEVEL,K)
CALL BESSEL(VR,BJ1,BJ1A,BJ1P,NII)
IF(INDF .EQ. 1) GO TO 6177
IF(INDF .EQ. 2) GO TO 6140
DO 6117 I=1,5
DO 6114 J=1,5
SUM1 = 0.0
DO 6113 L=1,NII
DO 6113 LL=1,16
6113 SUM1 = SUM1 + QMP(L)*G(LL)*VZ(L,LL)*VR(L,LL)**(2*I + 2*J - 3)
U(I,J) = FLOAT(4*I*J - 2*I - 2*J + 2)*SUM1
V(I,J) = 0.5/FLOAT(I + J)
IF(J .EQ. 1) GO TO 6114
U(J,I) = U(I,J)
V(J,I) = V(I,J)
6114 CONTINUE
SUM2 = 0.0
SUM3 = 0.0
DO 6115 L=1,NII
DO 6115 LL=1,16
SUM2 = SUM2 + QMP(L)*G(LL)*(DTBBL*VZ(L,LL) + 0.5*RALSBL*VZ(L,LL)**
1 2)*VR(L,LL)**(2*I-1)
6115 SUM3 = SUM3 + QMP(L)*G(LL)*VZ(L,LL)*VR(L,LL)**(2*I-1)
SQU(I) = FLOAT(2*I)*SUM2
6117 SPU(I) = FLOAT(2*I)*SUM3 - SQU(I)
DO 6125 I=1,5
DO 6125 J=6,10
JJ = J - 5
SUM1 = 0.0
SUM2 = 0.5*BJ1A(JJ,21)
DO 6119 L=1,NII
DO 6119 LL=1,16
6119 SUM1 = SUM1 + QMP(L)*G(LL)*(FLOAT(2*I-1)*BJ1P(L,JJ,LL)*VR(L,LL)**(
1 2*I-1) + BJ1(L,JJ,LL)*VR(L,LL)**(2*I-2)/RJ1P(JJ))*EXP(RJ1P(JJ))*
2 (VZ(L,LL) + CMH))
R = 0.0

```

```

DELR = (1.0 - EPS)/20.0
DO 6123 L=1,20
SUM2 = SUM2 + BJ1A(JJ,L)*R**(2*I)
6123 R = R + DELR
U(I,J) = SUM1
U(J,I) = U(I,J)
V(I,J) = SUM2*DELR
6125 V(J,I) = V(I,J)
DO 6137 I=6,10
II = I - 5
DO 6133 J=I,10
JJ = J - 5
SUM1 = 0.0
DO 6129 L=1,NII
DO 6129 LL=1,16
6129 SUM1 = SUM1 + QMP(L)*G(LL)*(RJIP(II)*RJIP(JJ)*VR(L,LL)*BJIP(L,II,
1 LL)*BJIP(L,JJ,LL) + (1.0/VR(L,LL) + RJIP(II)*RJIP(JJ)*VR(L,LL))*
2 BJ1(L,II,LL)*BJ1(L,JJ,LL))*(1.0/(RJIP(II) + RJIP(JJ))*EXP((RJIP
3 (II) + RJIP(JJ))*(VZ(L,LL) + CMH))
U(I,J) = SUM1
IF(J.EQ. I) GO TO 6133
U(J,I) = U(I,J)
V(I,J) = 0.0
V(J,I) = 0.0
6133 CONTINUE
SUM2 = 0.0
SUM3 = 0.0
DO 6135 L=1,NII
DO 6135 LL=1,16
SUM2 = SUM2 + QMP(L)*G(LL)*(DTBBL*(VR(L,LL)*BJIP(L,II,LL) + BJ1(L,
1 II,LL)/RJIP(II)) - RALSBL*BJ1(L,II,LL)*VR(L,LL)**2 + RALSBL*(
2 VZ(L,LL) - 1.0/RJIP(II))*(VR(L,LL)*BJIP(L,II,LL) + BJ1(L,II,LL)/
3 RJIP(II))*EXP(RJIP(II))*(VZ(L,LL) + CMH))
6135 SUM3 = SUM3 + QMP(L)*G(LL)*(VR(L,LL)*BJIP(L,II,LL) + BJ1(L,II,LL)/
1 RJIP(II))*EXP(RJIP(II))*(VZ(L,LL) + CMH))
SQU(I) = SUM2
SPU(I) = SUM3 - SQU(I)
6137 V(I,I) = 0.5*(1.0 - 1.0/RJIP(II)**2)*BJ1A(II,21)**2

```

```

SUM1 = 0.0
SUM2 = 0.0
SUM3 = 0.0
SUM4 = 0.0
DO 6139 L=1,NII
DO 6139 LL=1,16
SUM1 = SUM1 + QMP(L)*G(LL)*VR(L,LL)*VZ(L,LL)*RALS(K)**3
SUM2 = SUM2 + QMP(L)*G(LL)*(VZ(L,LL)*DTBBL**2 + RALSBL*DTBBL*VZ(L,
1 LL)**2 + (RALSBL**2)*(0.33333333*VZ(L,LL)**3 + 0.5*VZ(L,LL)*VR(
2 L,LL)**2))*VR(L,LL)
SUM3 = SUM3 + QMP(L)*G(LL)*((1.0 - 2.0*DTBBL)*VZ(L,LL) - RALSBL*
1 VZ(L,LL)**2)*VR(L,LL)
SUM4 = SUM4 + QMP(L)*G(LL)*(2.0*DTBBL*VZ(L,LL)
1 + RALSBL*VZ(L,LL)**2)*VR(L,LL)
VQQ(K) = SUM2
VPP(K) = SUM3 + VQQ(K)
VPQ(K) = SUM4 - 2.0*VQQ(K)
VOL = -6.2831853*SUM1
RETURN
C
C COMPUTATION OF COEFFICIENTS BMN(1,M,N)
C
6140 CONTINUE
DO 6175 I=1,10
DO 6175 J=1,10
IF(I .GT. 5) GO TO 6171
IF(J .GT. 5) GO TO 6167
V ( I,J) = (1.0 - EPS**(2*(I+J)))/FLOAT(2*(I+J))
GO TO 6173
6167 JJ = J - 5
IF(I .NE. 1) GO TO 6169
V ( I,J) = (BJ1A(JJ,21) - EPS*BJ1A(JJ,1) + RJ1P(JJ)*BJ1PA(JJ,1)
1 *EPS**2)/RJ1P(JJ)**2
GO TO 6173
6169 II = I - 1
V ( I,J) = (FLOAT(2*I-1)*BJ1A(JJ,21) - (FLOAT(2*I-1)*BJ1A(JJ,1)
1 - RJ1P(JJ)*EPS*BJ1PA(JJ,1))*EPS**(2*I-1) - FLOAT(4*I*(I-1))*
2 V( II,J))/RJ1P(JJ)**2
GO TO 6173

```



```

6171 II = I - 5
JJ = J - 5
IF(J .GT. I) GO TO 6172
V ( I,J) = 0.5*((RJIP(JJ)**2 - 1.0)*BJ1A(JJ,21)**2 - (RJIP(JJ)
1 *EPS*BJ1PA(JJ,1)**2 - ((RJIP(JJ)*EPS)**2 - 1.0)*BJ1A(JJ,1)**2)
2 /RJIP(JJ)**2
GO TO 6175
6172 V ( I,J) = (RJIP(II)*EPS*BJ1A(JJ,1)*BJ1PA(II,1) - RJIP(JJ)*EPS
1 *BJ1A(II,1)*BJ1PA(JJ,1))/(RJIP(II)**2 - RJIP(JJ)**2)
6173 IF(J .EQ. I) GO TO 6175
V(J,I) = V(I,J)
6175 CONTINUE
SUM1 = 0.0
DO 6176 L=1,NII
DO 6176 LL=1,16
6176 SUM1 = SUM1 + QMP(L)*G(LL)*VR(L,LL)*VZ(L,LL)*RALS(K)**3
VOL = -6.2831853*SUM1
RETURN
6177 DO 6185 I=1,10
SUM1 = 0.0
IF(I .GT. 5) GO TO 6181
DO 6179 L=1,NII
DO 6179 LL=1,16
6179 SUM1 = SUM1 + QMP(L)*G(LL)*VZ(L,LL)*VR(L,LL)**(2*I - 1)
UF(I) = -FLOAT(2*I)*SUM1
GO TO 6185
6181 II = I - 5
DO 6183 L=1,NII
DO 6183 LL=1,16
6183 SUM1 = SUM1 + QMP(L)*G(LL)*(VR(L,LL)*BJ1P(L,II,LL) + BJ1(L,II,LL)
1 /RJIP(II))*EXP(RJIP(II))*(VZ(L,LL) + CMH)
UF(I) = - SUM1
6185 CONTINUE
SUM1 = 0.0
SUM2 = 0.0
VF = 0.0
VFC = 2.0*(G3(K) - DTB(K))/RALS(K)
DO 6187 L=1,NII

```

```

DO 6187 LL=1,16
VF = VF + QMP(L)*G(LL)*VR(L,LL)*(VZ(L,LL)**2 - VFC*VZ(L,LL))
SUM2 = SUM2 + QMP(L)*G(LL)*VR(L,LL)*VZ(L,LL)**2
6187 SUM1 = SUM1 + QMP(L)*G(LL)*VR(L,LL)*VZ(L,LL)
VN = -6.2831853*SUM1*RALS(K)**3

C
C COMPUTATION OF C.M. MEASURED FROM THE ORIGIN OF THE TANK
C COORDINATE SYSTEM
C
ZBAR = 0.5*RALS(K)*SUM2/SUM1
RETURN
6141 IF(PLEVEL .GT. 2.2606) GO TO 6143
QL(1) = RIOVRP
NII = 2
GO TO 6111
6143 QL(1) = 3.1334786/RALS(K)
PL(2) = QL(1)
QL(2) = RIOVRP
GO TO 6109
6147 IF(PLEVEL .GT. 3.519678) GO TO 6149
PL(1) = 1.4144475*SQRT(12.388133 - PLEVEL**2)/RALS(K)
QL(1) = RIOVRP
QL(2) = PL(1)
NII = 2
EPS = PL(1)
GO TO 6111
6149 IF(PLEVEL .GT. 13.6906) GO TO 6151
QL(1) = RIOVRP
NII = 2
GO TO 6111
6151 QL(1) = 4.9784/RALS(K)
PL(2) = QL(1)
QL(2) = RIOVRP
GO TO 6109
6155 IF(PLEVEL .GT. 3.519678) GO TO 6157
QL(1) = RIOVRP
NII = 2
GO TO 6111
6157 QL(1) = 4.9784/RALS(K)

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        PL(2) = QL(1)
        QL(2) = RIOVRP
        GO TO 6109
6161 IF(PLEVEL .GT. 15.940278) GO TO 6163
        IF(K .EQ. 6 .AND. PLEVEL .GT. 9.539478) GO TO 6163
        QL(1) = RIOVRP
        NII = 2
        GO TO 6111
6163 QL(1) = 4.9784/RALS(K)
        PL(2) = QL(1)
        QL(2) = RIOVRP
        GO TO 6109
9061 CONTINUE
        ROROLD = 0.1
        NII = 1
        IDXB = INDF
        DO 9067 J=1,NBDLF
            URB(K,J) = 0.0
            ULB(K,J) = 0.0
        DO 9063 I=1,NBDLF
            BB(K,J,I) = 0.0
        DO 9065 I=1,10
            U(J,I) = 0.0
9067 CONTINUE
        DELPLV = 0.02*PLEVEL
        DELZ = DELPLV/RALS(K)
        PLEVEL = PLEVEL - 0.5*DELPLV
        GO TO (9071,9073,9075,9077,9077,9077), K
9071 CMH = (1.0414 - PLEVEL)/RALS(K)
        GO TO 9081
9073 CMH = (1.2192 - PLEVEL)/RALS(K)
        GO TO 9081
9075 CMH = -PLEVEL/RALS(K)
        GO TO 9081
9077 CMH = (3.519678 - PLEVEL)/RALS(K)
9081 CONTINUE
        CALL CONTR(PEVEL,ORLS,K)
        RORALS = ORLS/RALS(K)

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1 + 1.0414)**2)/RALS(K)
IF(K.EQ. 3 .AND. PLEVEL.LE. 3.519678) EPS=1.414475*SQRT(12.3881
1 - PLEVEL**2)/RALS(K)
IF(ABS(RORALS - ROROLD) .GT. 0.0001) CALL BESSEL(VR,BJ1,BJ1A,BJ1P,
1 NII)
ROROLD = RORALS
ISEG = 1
GO TO (9111,9111,9131,9131,9151,9151), K
9111 Z = (PLEVEL - 1.0414)/RALS(K)
IF(K.EQ. 2) Z=(PLEVEL - 1.2192)/RALS(K)
IF(PLEVEL.LE. 2.2606) GO TO 9181
ISEG = 2
IF(PLEVEL.LE. 7.8486) GO TO 9181
ISEG = 3
GO TO 9181
9131 Z = PLEVEL/RALS(K)
IF(K.EQ. 4) Z=(PLEVEL - 3.519678)/RALS(K)
IF(PLEVEL.LE. 3.519678) GO TO 9181
ISEG = 2
IF(PLEVEL.LE. 13.6906) GO TO 9181
ISEG = 3
GO TO 9181
9151 Z = (PLEVEL - 3.519678)/RALS(K)
IF(PLEVEL.LE. 3.519678) GO TO 9181
ISEG = 2
IF(K.EQ. 6 .AND. PLEVEL.LE. 9.539478) GO TO 9181
IF(K.EQ. 5 .AND. PLEVEL.LE. 15.940278) GO TO 9181
ISEG = 3
9181 CONTINUE
R = EPS
DELR = (RORALS - EPS)/20.0
RINC = R + DELR
RSUM1 = 0.0
DO 9201 L=1,20
RSUM1 = RSUM1 + R + RINC
R = R + DELR
9201 RINC = RINC + DELR

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DO 9221 J=1,NBDF
YJ = (Z - BFORDS(J,ISEG))/BFSLPS(J,ISEG)
URB(K,J) = URB(K,J) + DELR*RSUM1*(DTBBL + RALSBL*Z)*YJ*DELZ
ULB(K,J) = ULB(K,J) + DELR*RSUM1*YJ*DELZ
DO 9211 I=J,NBDF
YI = (Z - BFORDS(I,ISEG))/BFSLPS(I,ISEG)
BB(K,J,I) = BB(K,J,I) + 0.5*DELR*RSUM1*YJ*YI*DELZ
9211 IF(I .NE. J) BB(K,I,J) = BB(K,J,I)
9221 CONTINUE
DO 9261 I=1,10
R = EPS
RINC = R + DELR
SPU(I) = 0.0
IF(I .GE. 6) GO TO 9241
DO 9231 L=1,20
SPU(I) = SPU(I) + R**(2*I - 1) + RINC**(2*I - 1)
R = R + DELR
9231 RINC = RINC + DELR
GO TO 9261
9241 II = I - 5
DO 9251 L=1,20
N = L + 1
SPU(I) = SPU(I) + RJIP(II)*R*BJ1PA(II,L) + BJ1A(II,L)
1 + RJIP(II)*RINC*BJ1PA(II,N) + BJ1A(II,N)
R = R + DELR
9251 RINC = RINC + DELR
9261 CONTINUE
DO 9291 J=1,NBDF
YJ = (Z - BFORDS(J,ISEG))/BFSLPS(J,ISEG)
DO 9281 I=1,10
IF(I .GE. 6) GO TO 9271
U(J,I) = U(J,I) + FLOAT(I)*DELR*SPU(I)*YJ*DELZ
GO TO 9281
9271 II = I - 5
U(J,I) = U(J,I) + 0.5*DELR*SPU(I)*YJ*DELZ*EXP(RJ1P(II)*(Z + CMH))
9281 CONTINUE
9291 CONTINUE
PLEVEL = PLEVEL - DELPLV

```

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      ALLLEVEL . . . . .
GO TO 9081
9295 CONTINUE
DO 9299 J=1,NBDLF
9299 ULB(K,J) = ULB(K,J) - URB(K,J)
RETURN
END
$IBFTC SUB4 DECK
SUBROUTINE TKCONF(NII,PL,QL,QMP,VR,VZ,CMH,BOA,AORS,PLEVEL,K)
C THIS SUBROUTINE DESCRIBES THE CONTOURS OF SATURN V TANKS IN THE THETA-
C PLANE.
C
C DIMENSION QPP(4)
COMMON /BLK2/G(16),X(16)
COMMON /CL5/PL(4), QL(4), QMP(4), VZ(4,16)
COMMON /CL6/VR(4,16)
COMMON /CL7/ NBDLF , INDF, UF(10), INDX2, VF, VN, RALS(6),
1 ALL(6)
DO 6201 I=1,NII
QMP(I) = 0.5*(QL(I) - PL(I))
6201 QPP(I) = 0.5*(QL(I) + PL(I))
DO 6205 I=1,NII
DO 6205 J=1,16
6205 VR(I,J) = QMP(I)*X(J) + QPP(I)
GO TO (6209,6217,6225,6233,6241,6241), K
6209 DO 6213 I=1,16
VZ(1,I) = - 2.0828/RALS(K) + SQRT((3.302/RALS(K))**2 - VR(1,I)**2)
VZ(2,I) = - SQRT((3.302/RALS(K))**2 - VR(2,I)**2)
IF(NII .EQ. 3) VZ(3,I) = (PLEVEL - 1.0414)/RALS(K)
IF(NII .EQ. 3) GO TO 6213
VZ(3,I) = 6.8072/RALS(K) + SQRT((3.302/RALS(K))**2 - VR(3,I)**2)
VZ(4,I) = (PLEVEL - 1.0414)/RALS(K)
6213 CONTINUE
CMH = (1.0414 - ALL(K))/RALS(K)
RETURN
6217 DO 6221 I=1,16
VZ(1,I) = 2.0828/RALS(K) - SQRT((3.302/RALS(K))**2 - VR(1,I)**2)

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IF(N11 .EQ. 2) GO TO 6221
VZ(2,I) = SQRT((3.302/RALS(K))**2 - VR(2,I)**2)
VZ(3,I) = (PLEVEL - 1.2192)/RALS(K)
6221 CONTINUE
CMH = (1.2192 - ALL(K))/RALS(K)
RETURN
6225 DO 6229 I=1,16
VZ(1,I) = BOA*SQRT(AORS - VR(1,I)**2)
IF(N11 .EQ. 2) VZ(2,I) = PLEVEL/RALS(K)
IF(N11 .EQ. 2) GO TO 6229
VZ(2,I) = 13.6906/RALS(K) + BOA*SQRT(AORS - VR(2,I)**2)
VZ(3,I) = PLEVEL/RALS(K)
6229 CONTINUE
CMH = - ALL(K)/RALS(K)
RETURN
6233 DO 6237 I=1,16
VZ(1,I) = - BOA*SQRT(AORS - VR(1,I)**2)
IF(N11 .EQ. 2) VZ(2,I) = (PLEVEL - 3.519678)/RALS(K)
IF(N11 .EQ. 2) GO TO 6237
VZ(2,I) = BOA*SQRT(AORS - VR(2,I)**2)
VZ(3,I) = (PLEVEL - 3.519678)/RALS(K)
6237 CONTINUE
CMH = (3.519678 - ALL(K))/RALS(K)
RETURN
6241 DO 6249 I=1,16
VZ(1,I) = - BOA*SQRT(AORS - VR(1,I)**2)
IF(N11 .EQ. 2) VZ(2,I) = (PLEVEL - 3.519678)/RALS(K)
IF(N11 .EQ. 2) GO TO 6249
IF(K .EQ. 5) GO TO 6243
VZ(2,I) = 6.0198/RALS(K) + BOA*SQRT(AORS - VR(2,I)**2)
GO TO 6245
6243 VZ(2,I) = 12.4206/RALS(K) + BOA*SQRT(AORS - VR(2,I)**2)
6245 VZ(3,I) = (PLEVEL - 3.519678)/RALS(K)
6249 CONTINUE
CMH = (3.519678 - ALL(K))/RALS(K)
RETURN
END

```

```

PROGRAM SUBS DECK
SUBROUTINE BESSEL(VR,BJ1,BJ1A,BJ1P,NII)
C THIS SUBROUTINE EVALUATES ALL OF THE BESSEL FUNCTIONS WHICH ARE NEEDED
C FOR SUBSEQUENT COMPUTATION
C
DIMENSION D(7), E(7), F(7)
COMMON /BLK1/A(7),B(7),O(7)
COMMON /BLK3/RJ1P(5)
COMMON /CL4/BJ1(4,5,16), BJ1A(5,21), BJ1P(4,5,16), EPS
COMMON /CL6/VR(4,16)
COMMON /CL9/ IDXB, RORALS
COMMON /TEMP/BJ1PA(5,21), BJOA(5,21)
DATA (D(I),I=1,7)/1.0,-2.2499997,1.2656208,-0.3163866,0.0444479,
1 -0.0039444,0.0002100/, (E(I),I=1,7)/0.79788456,-0.00000077,
2 -0.0055274,-0.00009512,0.00137237,-0.00072805,0.00014476/,
3 (F(I),I=1,7)/-0.78539816,-0.04166397,-0.00003954,0.00262573,
4 -0.00054125,-0.00029333,0.00013558/
DO 6329 I=1,NII
DO 6329 J=1,5
LB = 16
IF(IDXB .EQ. 11) LB = 1
DO 6329 L=1,LB
IF(IDXB .EQ. 11) GO TO 6313
AJNR = RJ1P(J)*VR(I,L)
IF(AJNR .GT. 3.0) GO TO 6305
T = AJNR/3.0
SUM1 = 0.0
SUM2 = 0.0
DO 6301 LL=1,7
SUM1 = SUM1 + A(LL)*T**(2*LL - 2)
6301 SUM2 = SUM2 + D(LL)*T**(2*LL - 2)
BJ1(I,J,L) = AJNR*SUM1
BJ1P(I,J,L) = SUM2 - SUM1
GO TO 6313
6305 T = 3.0/AJNR
SUM1 = 0.0
SUM2 = AJNR

```



```

SUM3 = 0.0
SUM4 = AJNR
DO 6309 LL=1,7
SUM1 = SUM1 + B(LL)*T**(LL - 1)
SUM2 = SUM2 + O(LL)*T**(LL - 1)
SUM3 = SUM3 + E(LL)*T**(LL - 1)
SUM4 = SUM4 + F(LL)*T**(LL - 1)
6309 CAJNR = 1.0/AJNR**0.5
      BJ1(I,J,L) = CAJNR*SUM1*COS(SUM2)
      BJ1P(I,J,L) = CAJNR*SUM3*COS(SUM4) - BJ1(I,J,L)/AJNR
6313 IF(.NOT.(I .EQ. 1 .AND. L .EQ. 1)) GO TO 6329
R = EPS
RBORA = 1.0
IF(IDXB .EQ. 11) RBORA = RORALS
DELR = (RBORA - EPS)/20.0
DO 6327 M=1,21
AJNR = RJ1P(J)*R
IF(AJNR .GT. 3.0) GO TO 6321
T = AJNR/3.0
SUM1 = 0.5
SUM2 = 1.0
DO 6317 LL=2,7
SUM2 = SUM2 + D(LL)*T**(2*LL - 2)
6317 SUM1 = SUM1 + A(LL)*T**(2*LL - 2)
      BJ1A(J,M) = AJNR*SUM1
      BJ1PA(J,M) = SUM2 - SUM1
      BJ0A(J,M) = SUM2
GO TO 6326
6321 T = 3.0/AJNR
SUM1 = 0.0
SUM2 = AJNR
SUM3 = 0.0
SUM4 = AJNR
DO 6325 LL=1,7
SUM1 = SUM1 + B(LL)*T**(LL - 1)
SUM3 = SUM3 + E(LL)*T**(LL - 1)
SUM4 = SUM4 + F(LL)*T**(LL - 1)
6325 SUM2 = SUM2 + O(LL)*T**(LL - 1)

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BJ1A(J,M) = (1.0/AJNR**0.5)*SUM1*COS(SUM2)
BJ1PA(J,M) = (1.0/AJNR**0.5)*SUM3*COS(SUM4) - BJ1A(J,M)/AJNR
BJ0A(J,M) = (1.0/AJNR**0.5)*SUM3*COS(SUM4)
6326 R = R + DELR
6327 CONTINUE
6329 CONTINUE
      RETURN
      END
$IBFTC SUB6   DECK
SUBROUTINE CONTR(PLEVEL,ORLS,K)
C THIS SUBROUTINE PROVIDES THE RADIUS OF THE LIQUID SURFACE
C
      C1 = 10.903204
      C2 = 4.9784
      C3 = 3.519678
      GO TO (6411,6421,6431,6445,6451,6461), K
6411 IF(PLEVEL .GT. 7.8486) KI=1
      IF(PLEVEL .LE. 7.8486 .AND. PLEVEL .GE. 1.0414) KI=2
      IF(PLEVEL .LT. 1.0414) KI=3
      GO TO (6413,6415,6417), KI
6413 ORLS = SQRT(C1 - (PLEVEL - 7.8486)**2)
      RETURN
6415 ORLS = 3.302
      RETURN
6417 ORLS = SQRT(C1 - (1.0414 - PLEVEL)**2)
      RETURN
6421 IF(PLEVEL .GE. 2.2606) KI=1
      IF(PLEVEL .LT. 2.2606) KI=2
      GO TO (6423,6425), KI
6423 ORLS = SQRT(C1 - (PLEVEL - 1.2192)**2)
      RETURN
6425 ORLS = SQRT(C1 - (3.302 - PLEVEL)**2)
      RETURN
6431 IF(PLEVEL .GT. 13.6906) KI=1
      IF(PLEVEL .LE. 13.6906) KI=2
      GO TO (6433,6435), KI
6433 ORLS = C2*SQRT(1.0 - ((PLEVEL - 13.6906)/C3)**2)

```

```
RETURN
6435 ORLS = C2
RETURN
6445 ORLS = C2*SQRT(1.0 - (1.0 - PLEVEL/C3)**2)
RETURN
6451 IF(PLEVEL .GT. 15.940278) KI=1
IF(PLEVEL .LE. 15.940278 .AND. PLEVEL .GE. C3) KI=2
IF(PLEVEL .LT. C3) KI=3
GO TO (6453,6435,6445), KI
6453 ORLS = C2*SQRT(1.0 - ((PLEVEL - 15.940278)/C3)**2)
RETURN
6461 IF(PLEVEL .GT. 9.539478) KI=1
IF(PLEVEL .LE. 9.539478 .AND. PLEVEL .GE. C3) KI=2
IF(PLEVEL .LT. C3) KI=3
GO TO (6463,6435,6445), KI
6463 ORLS = C2*SQRT(1.0 - ((PLEVEL - 9.539478)/C3)**2)
RETURN
END
```