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AN APPLICATION OF THE "REQUIREMENT VS CAPABILITY" ANALYSIS TO ESTIMATING DESIGN RELIABILITY OF SOLID ROCKET MOTORS

by C. R. Herrmann, G. E. Ingram, and E. L. Welker

Prepared by GENERAL ELECTRIC COMPANY Santa Barbara, Calif. for

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ABSTRACT

This report describes the results of the research work of G.E./ TEMPO on the continuing studies of the reliability of large solid rocket motors. The basic concepts of the study methodology were presented in G. E./TEMPO document number 66TMP-90, 1 March 1967 prepared for NASA/OART under contract number NAS 7-383. The present report is devoted primarily to a description of the application of this methodology to an existing solid rocket motor system. A hypothetical example serves to explain the basic concepts and to illustrate both hand and computerized computational procedures. The solid rocket motor example demonstrates the practicality of the methodology in a realistic case, showing that the data and design relationships can be obtained and that the computational work load is not unreasonable.

Briefly, the reliability analysis methodology can be described as follows. For each significant failure mode, transfer functions are derived to express the requirements (or stresses) which will be imposed on the motor and the capability (or strength) of the motor to withstand these requirements. (The words "requirements" and "capabilities" are used in preference to "stresses" and "strength" to avoid the incorrect implication that the method is restricted to structures.) Using the initials, the method is called the $R \parallel C$ analysis technique. All input and output parameters are treated probabilistically to provide proper realism. Simultaneous consideration of analyses for the various modes yields the system reliability estimate. TEMPO elected to use the General Electric time sharing computer system for performing the computations. It provides speed, convenience, and flexibility sufficient to permit design engineers or their analysts to apply $R \| C$ analysis themselves, thus allowing the technique to serve as an effective design tool.

The main body of the report contains (1) a brief description of the concepts associated with the $R \| C$ approach, (2) an application of the technique using the engineering information and data supplied by the Aerojet General Corporation (AGC), and (3) conclusions and recommendations resulting from the study. The appendices contain (1) data on input parameters supplied by AGC, (2) a discussion of the detailed analysis

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which was performed in the course of the study, (3) some computer printouts resulting from an $R \| C$ analysis of failure modes for which data was available, (4) a brief description of the computational technique used for combining random variables and the computer procedures used to implement the technique, and (5) a mathematical discussion of a portion of the theory of the $R \| C$ analysis technique.

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1. SUMMARY AND INTRODUCTION

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For some time, the Office of Advanced Research and Technology of NASA Headquarters, NASA/OART, has been concerned about the problems associated with designing highly reliable large solid rocket motor systems. Specifically, they would like to be able to estimate the reliability potential of a candidate system design in advance of production in sufficient detail to identify and quantify the sources of unreliability. Of course such an estimation method could also be used to evaluate the reliability of a rocket motor system after fabrication. The familiar "piece part" approach which has proved to be so useful in the evaluations of the reliability of electronic systems is not suitable for solid rocket motors for two critical reasons. In the first place, a solid rocket motor is largely fabricated as a single integrated system from raw materials rather than piece parts. In the second place, system testing in large samples is not feasible since test firings are destructive and large motors are very expensive. Phases I and II of this study program were devoted primarily to examinations of past experience on completed and continuing solid rocket motor developments. These examinations attempted to discover criteria for extrapolating reliability growth experience from past programs to current ones. As a result of these studies, the need for the analytical approach of Phase III was quite clearly established. The present report summarizes the results of this Phase III research work by G. E. /TEMPO*, all phases being performed under the sponsorship of NASA /OART.

In the initial phases of this research, TEMPO explored the possibility of extrapolating test experience from other solid rocket motor programs. This was partially successful for the purposes of reliability estimation and of clarification of the elements of the overall problem. However, the approach was clearly deficient in identifying and quantifying sources of unreliability to assist the design engineer in his efforts to meet desired reliability goals. It became apparent to the study team that the most promising technique would involve analytical studies of the solid rocket motor system to gain an appropriate insight into the physics of the failure phenomena which could occur. This report presents a brief description of the methodology of this approach, including some of the basic theory involved, a simple hypothetical example, and an application of the

^{*} Contributions to this research by Aerojet General Corporation and TRW Systems are described elsewhere in the report.

technique to a number of the failure modes for a realistic solid propellant rocket motor, the 260 inch motor manufactured by AGC.

The main body of the report, of which this section is a part, introduces the reader to the background leading up to this study, states the objectives of the study in terms of the contract work statement, briefly summarizes the fundamental concepts of the methodology, presents general comments on the transfer functions and parameter data used in the study, summarizes the results obtained from applying the methodology to a large solid rocket motor, discusses the results, and presents conclusions and recommendations for future work.

The appendices contain a complete summary of the input data and transfer functions provided by AGC, the details of the application of $R \| C$ analysis to a large solid rocket motor, and the computer printouts resulting from this application. They also include a detailed discussion of the approach concepts, computational techniques, and computer procedures used in the study, and a mathematical discussion of a portion of the theory of the $R \| C$ analysis technique.

This study had two prime objectives: (1) development of analytical techniques that will enable the design engineer to estimate the reliability of the system (e.g. a large solid rocket motor), and (2) the application of these techniques to a large solid rocket motor system. The results of the study indicate that the techniques are feasible and tractable and provide the designer an efficient and economical analysis tool. For example, using the unmodified data as it was furnished by AGC for the parameters associated with the burn-through failure mode, the $R \parallel C$ analysis for this failure mode indicated that in one region of the motor the probability of burning through to the case wall could be as high as 0.137 depending upon the data used to define the burn-through parameters. The important point here is that this could not have been realized by the designer without describing these parameters probabilistically.

Another failure mode which helped to illustrate the importance of the $R \| C$ analysis was that of case rupture in both the cylindrical and spherical portions of the case. The welds are the most critical elements of the case with respect to rupture and it was necessary to consider them in detail, distinguishing between those that were made by machine and those that required hand techniques. All welding was initially done by

machine. According to AGC inspection experience, approximately 10 percent of the total weld length was defective and was reworked by hand welding techniques. Test data derived from representative weld specimens showed that on the average, the hand welds were weaker and their strengths had a larger variability than did the machine welds. Results of the R||C analysis indicated that the failure probabilities associated with this failure mode were relatively small when based only on the machine weld strengths (90% of all welds) but increased many orders of magnitude when the hand weld strengths (10% of all welds) were included. This quantitative result is not immediately obvious to the designer until he considers the probabilistic description of the design parameters in an R||C analysis.

Relatively low probabilities of failure were also obtained from the $R \| C$ analysis for the other failure modes when using the standard set of unadjusted AGC data. In many cases, however, further $R \| C$ analysis indicated that the probability of failure associated with a particular failure mode could be increased many orders of magnitude by simply changing the mean value and/or the variance of certain of the parameters. On the other hand there was little effect upon the probability of failure resulting from changes in the mean values and/or variances of certain other parameters. Studies based on such changes of the means and/or variances of input parameters are referred to as sensitivity analyses in the text.

The recommendations evolving from this study address themselves primarily to four areas--(1) further analysis of the large solid rocket motor to include those subsystems that have not yet been analyzed by the $R \parallel C$ approach (e.g. ignitor system, nozzle, etc.), (2) a more detailed study in certain areas where the sensitivity analysis indicated a criticality of certain parameters (e.g. maraged steel versus HY series steel), (3) a consideration of system interdependence and engineering trade-offs (e.g. developing criteria for prorating unreliability of total system to individual failure modes), and (4) extending the $R \parallel C$ analysis to other types of motor systems (e.g. smaller solid propellant rocket motors, liquid propellant rocket engines, hybrid motors, etc.).

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2. OBJECTIVES OF THE PHASE III STUDY PROGRAM

The TEMPO Phase III study effort was directed toward the accomplishment of two basic tasks. The first task consisted of the development of a methodology for using a physics of failure approach in evaluating the reliability of a large solid propellant rocket motor system. The second task was actually composed of two subtasks. One of these was to apply this methodology to an actual system—the 260 inch motor system was selected for this purpose. The other subtask consisted of the development of computational procedures which were sufficiently simple to constitute a demonstration of the practicality of the analysis methodology. The TEMPO tasks were detailed in the most recent contract work statement as follows.

"Statement of Work

TEMPO shall work toward development of a technique for the assessment of reliability of large solid propellant motors, which relies on an engineering analysis and a description of the motor. Work to include:

Task I

In cooperation of Aerojet General Corporation (AGC), identify and list available failure modes of the Propellant Grain Subsystem and establish priorities for the application of the $R \| C$ analysis of these failure modes.

Task II

Define in coordination with AGC the ballistic and hardware performance and reliability requirements of the Propellant Grain Subsystem.

Task III

Identify in coordination with AGC measurable characteristics which characterize the Propellant Grain Subsystem's capability.

Task IV

Define, in coordination with AGC, relationships between requirements and capabilities.

Task V

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Identify data format and needs to be submitted by AGC to G.E. for $R \| C$ analysis.

Task VI

Apply $\mathbb{R} \| \mathbb{C}$ analysis technique. This will involve setting up a computer program to handle the typical comparisons to be made.

Task VII

Preliminary ground work will be defined as it is associated with the other motor subsystems, such as the case, to insure proper lead time to application of the complete $\mathbb{R} \| \mathbb{C}$ analysis in the next period of this study.

Task VIII

In cooperation with Aerojet-General Corporation (AGC), identify and list failure modes associated with the Case-Liner-Insulation-Propellant Subsystems and establish priorities for the application of the $R \| C$ analysis to these failure modes. In consultation with AGC and TRW, and with the approval of NASA, the following failure modes have been tentatively selected for analysis:

- 1. Case Rupture due to Overpressurization and Flight Loads parent metal.
- 2. Case Rupture due to Overpressurization and Flight Loads welds.
- 3. Skirt Failure due to Flight Loads forgings and plate.
- 4. Forward Cap Failure bolt failure.
- 5. Forward Cap Failure joint flexure.
- 6. Insulation/Case Bond Failure.

Task IX

Define, in coordination with AGC, a set of the more significant "Requirements" (i.e., to be used in the R||C analysis) that will be placed on the Case-Liner-Insulation-Propellant Subsystems.

Task X

Identify, in coordination with AGC, measurable properties which characterize the Case-Liner-Insulation-Propellant Subsystems' "Capabilities" (i.e., to be used in the $R \parallel C$ analysis) to satisfy the "Requirements" defined in Task IX.

Task XI

Define, in coordination with AGC, relationships between the "Requirements" and "Capabilities" identified in Task IX and Task X.

Task XII

Identify data format and needs to be submitted by AGC to G.E. for the $R \| C$ analysis.

Task XIII

Apply $R \| C$ analysis technique in line with Tasks VIII thru XII. (This will include any necessary computer programming.)"

Only the first seven of these tasks were listed in the original contract. Tasks eight through thirteen were added later by contract modification as an appropriate follow on or extension of the initial phases of this research.

The basic methodology was developed in the TEMPO Phase IIIA study effort, the results of which are described in the report "The Analytical Approach and Physics-of-Failure Technique for Large Solid Rocket Reliability", C. R. Herrmann and G. E. Ingram, TEMPO Report 66TMP-90, 1 March 1967, (Reference 1). The Phase IIIB study program had as its objective the development of computer methods for performing this analysis, using the propellant subsystem of the 260 inch solid rocket motor, thus initiating the work on the application of the methodology to an actual system. An interim report was prepared on this Phase IIIB work. It was given only limited distribution since it was viewed essentially as a progress report.

The objective of the present report is to describe the results of the entire Phase III effort. Since the Phase IIIA report explained the concepts of the methodology in some detail, we are including only a summary of the methodology herein.

3. THE FUNDAMENTAL CONCEPTS OF THE METHODOLOGY

System failure occurs when the capability or strength of the system is insufficient to withstand the requirements or stresses which are imposed upon it. The reliability of the system is of course the probability that the requirements do not exceed the capabilities for each and every failure mode.* We immediately recognize this as the traditional stress vs strength approach so commonly associated with analysis of structures. TEMPO has chosen to replace the terms "stress and strength" by "requirements and capability" respectively to avoid the incorrect implication that the method is restricted to structures— it applies equally to any system type. Using the initials, we identify the method as the $R \parallel C$ analysis technique. The significant aspect of the TEMPO research is the development of the ways and means for performing $R \parallel C$ analysis the derivations of formulas, the collection of the necessary data from design group such as AGC, and the actual performance of the required computations.

The details of the $\mathbb{R} \| \mathbb{C}$ analysis methodology are briefly as follows. A list of failure modes must be prepared. For each mode, a pair of transfer functions are derived from the basic design equations. One transfer function expresses the requirement, R, placed on the system by the stresses it will see and the other expresses the capability, C, of the system to withstand these stresses. Each transfer function involves design variables or parameters which must be treated probabilistically if we are to obtain realistic and thus meaningful results from the analysis, meaning that R and C are also treated probabilistically. It will be helpful to describe this process in the symbolism and language of mathematics.

Consider a single failure mode and denote its two transfer functions as follows.

Requirement: $R = f_R(x_1, x_2, \dots, x_m)$ Capability: $C = f_C(y_1, y_2, \dots, y_n)$.

* For brevity, we will usually not make reference to the modifiers in the more precise definition of reliability which cover the system mission, the time span, the definition of satisfactory performance and the conditions of operation. However, these elements are included in the analysis.

When we say that the x's, y's, R, and C are treated probabilistically. we mean each of them is described in terms of its probability density function. In the language of probability, the terms random variable and stochastic variable are used to refer to a variable which has an associated density function and we shall use these terms in this sense herein. Thus, we can say that the probabilistic treatment of input variables, x's and y's, and output variables, R and C, contrasts with less realistic design approaches in which only single values are used for inputs and hence for outputs and the detail of the arithmetic reflects this distinction. The combination of the density functions of the input variables to generate the densities of the outputs for R and for C according to their respective transfer functions is a significantly larger task than the substitution of single (such as an average or worst case) values as will be illustrated. However, we will show how currently available computer systems perform such computations easily, quickly, and cheaply for most functions and hence make this $R \| C$ analysis methodology quite tractable. The probability of system failure by this mode is obtained by computing the probability that C is less than R. This is obtained by deriving the density of the difference, (C - R), and then computing the probability that (C - R) is negative.*

The derivation of the probability density of (C - R) must be completed for each failure mode. The system failure probability is then determined by computing the probability of the occurrence of at least one mode of failure. Obviously there can and perhaps commonly will be dependencies between input random variables in C and R functions for the various failure modes. Therefore it is necessary to treat dependent functions simultaneously to provide proper consideration of the conditional probabilities involved.

Discrete vs Continuous Densities for Input Data and R C Analysis Output Functions

The density functions of the input random variables—the input data of the $R \| C$ analysis—can be presented in one of two forms: (1) discrete variable relative frequency distributions, usually a summarization of test results, sometimes called "batch" data, and (2) a closed form representation—a formula form of the density function. Of course we must be able to carry out an $R \| C$ analysis when input densities are in either of these forms or when they are in a combination of them. If

^{*} The parenthesis in the symbol (C - R) is used to denote that we are treating the difference as a single random variable.

one or more input densities are in the discrete form, then the output density is necessarily discrete. Curve fitting procedures could then be used to obtain a continuous approximation and a formula representation. It is always possible to use discrete densities as approximations for continuous ones, and the computer programs which TEMPO has used in its $R \| C$ analyses require that this approach be used.

We are especially interested in the case in which all input densities are defined in closed form-a functional representation. In this case, the output densities can be expressed as integrals involving the input densities, but it is not always possible to perform the integration to derive a closed form functional representation for the output, R, C, or (C - R). Of course numerical integration techniques are available to handle such complex integrals. It should be noted that the functional form of an output density is often quite different from those of the inputs. The importance of this point lies in the fact that significant inaccuracy arises when one erroneously assumes an incorrect form of an output density. The most commonly encountered error in this connection is the false belief that Gaussian inputs generate Gaussian outputs. Appendix VI of this report contains a number of examples of closed form solutions to illustrate the intergration procedures and to show this transformation of functional forms. Fortunately, the R C analysis method does not require us to know in advance what form the output will take-the technique is able to generate the appropriate form automatically.

Data Sources

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Since the input parameters in the transfer functions are often material properties, it is important to note that data sources need not be restricted to the project's own test programs. For example, data on properties of maraged steel can be obtained from manufacturer's tests or from tests in any program in which maraged steel is used. The application of such data to the system being analyzed is determined by the transfer function from the designer's equations and not from a requirement that the data be generated in tests of the actual system hardware. Thus, one of the great strengths of the R $\|C$ technique is its ability to expand the data base through the use of data from other programs which share in materials being used even though the system hardware is entirely different. In fact, the data base is not only extended in this fashion, but it is an appropriate information source which is in existence in advance of the production of any hardware of the system being analyzed by the R $\|C$ methodology.

4. GENERAL COMMENTS ON DATA AND TRANSFER FUNCTIONS USED IN THIS STUDY

At the outset of this research program, it was recognized that the derivation of R and C transfer functions and the collection of necessary input data were major tasks. Aerojet General was charged with the responsibility for performing these tasks in their contract with NASA/OART. AGC not only supplied TEMPO with the data and the transfer functions, but they also provided information on data adjustment procedures and on special interpretations of the information which they felt to be appropriate and useful in the subsequent $R \parallel C$ analysis. Comments about specific data and transfer function characteristics are included in the application section of this report. In the present section, we will confine our attention to the general nature of the information supplied by AGC.

Since information unavailability is often alleged, it is extremely important to note that AGC was able to obtain transfer functions and data in spite of the problems involved. Of course, they found it necessary to use some approximations and thus to introduce a degree of uncertainty in the analyses of some failure modes—this is essentially the ever present problem of data shortage coupled with uncertainty about such things as physics of failure and environmental stress profiles. A slight degree of uncertainty was also introduced when AGC was forced to use a design criterion instead of a true physics of failure relationship for one transfer function. It was expected that this would probably lead to an underestimate of reliability since design criteria frequently contain an unquantified degree of conservatism.

On a number of occasions, AGC expressed concern about the small sample sizes which they were sometimes forced to use to generate input densities. They indicated their belief that such data problems should be handled by assuming that input densities should be Gaussian, that sample data tended to give reasonably good estimates of mean values, and that from other information, AGC could obtain good estimates of coefficients of variation. Accepting these assumptions by AGC, TEMPO was required to use Gaussian inputs in all of the $R \| C$ analyses reported on herein.

It must be pointed out that TEMPO has some reservations about this widespread use of the Gaussian curve, and AGC recognizes that it is open to question in some cases. For example, a parameter which can never be negative can certainly not have a Gaussian density. One can visualize many parameters which have finite bounds on both sides web thickness is greater than zero and it surely will never be infinite! In the next phases of this research, it is hoped that data can be obtained in a form which does not force the use of the Gaussian assumption, especially where it is clearly quite inappropriate.

The limited data base which could be developed within the restrictions of time and funding was responsible for one disappointment in this study. It had been hoped that for a few cases, comparative $\mathbb{R} \| \mathbb{C}$ analyses could be performed, one using raw or batch data and the other using the fitted Gaussian functions. Unfortunately, there was no case in which suitable batch data was available, so this comparative analysis was not possible.

5. APPLICATION OF THE METHODOLOGY TO A LARGE SOLID ROCKET MOTOR

A complete reliability study of a system would require the application of the $\mathbb{R} \| \mathbb{C}$ analysis technique for each failure mode by itself, that is, independently of all others, and then an application of the methodology to all failure modes simultaneously, bringing into the analysis all of the interdependencies which exist. Independent analysis of a particular failure mode would tend to focus attention on specific reliability problems in terms of design characteristics as related to that individual mode. However, the study of all failure modes together is essential to arrive at suitable estimates of system reliability. course, the combined failure mode treatment can be derived from the separate analyses of individual failure modes if the associated transfer functions are independent. The analysis can often be simplified by neglecting some failure modes, the criterion for the selection of these modes being that their individual and collective contributions to unreliability must be insignificant, assuming an appropriate determination of what we should mean by insignificant in the light of the seriousness of failure. The limited research effort provided by the present contract precluded the simultaneous consideration of failure modes so this report covers only the analysis of individual modes by themselves.

In conference with representatives of NASA, AGC, TRW Systems and TEMPO, the following 14 failure modes were selected for study of the 260/SIV-B Motor System:

- 1. Hoop Stress Case Rupture
- 2. Insulation Burn Through
- 3. Failure of the Forward Motor Skirt Forging in Combined Compression, Shear, and Bending
- 4. Meridonal Stress Case Rupture
- 5. Rupture of the Nozzle Joint Bolts
- 6. Separation of the Motor Chamber and Nozzle Flange
- 7. Propellant Maximum Inner Bore Hoop Strain Storage Condition
- 8. Propellant/Liner Interface Maximum Radial Bond Stress Failure Mode, Storage Condition
- 9. Propellant Maximum Combined Stress (Principal Stress), Shear and Tension Storage Condition

10. Propellant/Liner Interface Maximum Shear Stress Flight Condition

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- 11. Propellant Maximum Inner Bore Hoop Strain Flight Condition
- 12. Insulation/Motor Case Interface Bond Maximum Shear Stress Flight Condition
- 13. Propellant Auto Ignition Due to Static Discharge
- 14. Propellant Auto Ignition Due to Self Heating

These failure modes are those selected consistent with contract statements of Tasks I through XIII listed under Sudy Objectives. The first six failure modes are in general those itemized under Task VIII. However, some trade-offs were made by AGC to cover the aft closure and bolt failure modes instead of the forward areas because better design data was available. In order to gain further insight into the rocket motor failure problems, special analyses were made for a few significant subdivisions of some of the 14 listed failure modes.

Details of the analysis for each of the above listed 14 failure modes is given in Appendix II of this report. In this section, we have included a brief description of the basic nature of each of the failure modes, a table summarizing the transfer function equations for each, a table listing all of the parameters and giving values of means and standard deviations, a table which summarizes the reliabilities associated with each mode, and finally, a table summarizing the sensitivity analyses for failure mode.1. These tabular summaries are followed by a few comments on these study results. The discussion of computational procedure is included in the appendices. Again it should be noted that AGC asked TEMPO to base their analysis on the assumption that all input parameters are Gaussian, recognizing that this is not entirely realistic.

Failure Mode 1. - Hoop Stress Case Rupture

This failure mode is identified as a failure of the longitudinal weld. Past experience by AGC shows that about 10 percent of the machine welds have flaws detectable in inspection. For these, the welds are reworked by hand techniques and experience indicates that hand welds are weaker on the average and they have greater variability in strength than do machine welds. Hence, the failure probability for this mode is computed on the assumption that 90 percent of the welds are by machine and 10 percent are by hand. It is believed by AGC that 40" aft of motor station 2 (Fig. 1) is the critical station for this mode, so this failure mode probability for the motor is based on an analysis for this station.

Failure Mode 2. - Insulation Burn Through

For this mode, AGC defined failure as burning all of the propellant and burning through the insulation, meaning burning to but not necessarily through the case. Obviously, the burn through probability varies by motor station. AGC suggested that TEMPO consider stations 1, 2, 4, 5, 6, 7 and 12 as identified in Figure 1. At stations 1 and 12, there is no propellant so the transfer function relationship had to be appropriately modified.

Failure Mode 3. - The Failure of the Forward Motor Skirt Forging in Combined Compression, Shear, and Bending

For this mode, failure consists of inelastic deformation and buckling resulting from the joint action of axial compression, transverse shear and bending forces acting on the forward motor skirt forging. The AGC engineers felt that it would be better to use a modification of the usual transfer function approach when considering this mode of failure. Rather than attempting to express requirements in terms of the compressive, shear, and bending forces and the capability in terms of the design and materials parameters, AGC chose to use a design criteria relationship. This emperical relationship combines the ratio of the requirement of each type of load to the corresponding allowable in an interaction formula such that if the sum of the ratios is greater than unity, failure is assumed to occur.

Failure Mode 4. - Meridional Stress Case Rupture Failure Mode

The major failure risk for this mode is the rupture of forward head circumferential welds due to meridional stress. All welds are initially made by machine but inspection shows that about 10 percent are defective. These must be reworked by hand techniques. It will be noted that hand welds on the average have less strength than machine welds and their strength is more variable. The failure probability for this mode is computed as a weighted average using 90 percent machine welds and 10 percent hand welds.



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Failure Mode 5. - Rupture of the Nozzle Joint Bolts

For this mode, failure is the rupture of the nozzle joint bolts due to combined loads of pressure ejection and TVC bending moments. The requirement function involves the tension due to pretorquing, a portion of the ejection load due to internal and external pressure and inertia, and the added tension effect due to the thrust vector control moment.

Failure Mode 6. - Separation of the Motor Chamber and Nozzle Flange

This mode involves the same forces as failure mode 5. However, in the case of failure mode 6, we are concerned with the occurrence of leakage due to separation which is a consequence of deformation of the bolts short of rupture.

Failure Modes 7 through 12

Five failure modes, 7 thru 12 inclusive, are related to propellant stress problems. These will be discussed collectively because of their close relationship. The failure modes are as follows.

Failure Mode 7. - Propellant Maximum Inner Bore Hoop Strain Failure Mode, Storage Condition

Inner bore grain Failure in hoop stress due to cool down and storage (undetected), critical station - center region of motor.

Failure Mode 8. - Propellant/Liner Interface Maximum Radial Bond Stress Failure Mode, Storage Condition

Propellant/Liner interface bond fails radially during cool down and storage (undetected), critical station-aft end of motor.

Failure Mode 9. - Propellant Maximum Combined Stress (Principal Stress), Shear and Tension Failure Mode, Storage Condition

Failure of propellant due to combined shear and tension stress during cool down and storage (undetected), critical station - aft end of motor.

Failure Mode 10. - Propellant/Liner Interface Maximum Shear Stress Failure Mode, Flight Condition

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Propellant/Liner interface bond fails due to shear stress during cool down and storage (undetected), critical station forward end of motor.

Failure Mode 11. - Propellant Maximum Inner Bore Hoop Strain Failure Mode, Flight Condition

Inner bore grain failure in hoop stress due to pressurization and flight acceleration, critical station - aft end of motor.

Failure Mode 12. - Insulation/Motor Case Interface Bond Maximum Shear Stress Failure Mode, Flight Condition

Insulation/Motor Case Interface bond fails in shear for 2g maximum launch acceleration.

Failure modes 7, 9, and 11 relate to propellant cracking while modes 8, 10 and 12 are concerned with separation between the propellant and the case. The names identify the stresses. These various propellant stress relationships are perhaps the most complex and least understood of all solid rocket motor failure modes. AGC ran a rather complex computer program to obtain some feel for the severity of these failure modes using a set of randomly selected inputs for each run of the computer program. Within the constraints of their analysis and relatively few runs made (because of the cost aspect), the outputs they generated were in the form of R and C functions. AGC also said that these output R and C density functions were Gaussian. Hence we were able to use a closed form solution, Gaussian in this case.

Failure Modes 13. - Propellant Auto Ignition Due to Static Discharge

Failure of motor due to propellant self ignition from static electrical discharges.

Failure Mode 14. - Propellant Auto Ignition Due to Self Heating

Failure of motor due to propellant self ignition from endothermal self heating within the propellant, caused by internal reactions.

These two failure modes, 13 and 14, are similar in that they both involve ignition of the propellant. The causes of ignition do of course differentiate them and the brief descriptions adequately identify these causes.

Discussion and Results - $R \parallel C$ Analysis of Failure Mode 1 - 14

Table 1 shows the Requirement (R) function and the associated Capability (C) function for each of the first six of these failure modes. The parameters involved in these functions are defined in Table 2, "Summary of Parameters". A detailed discussion of this information is given in Appendix II.

It should be noted that the units are not necessarily the same for each of the R functions (Obviously, the units must be the same for an R function and its associated C function.). The units depend upon the type of failure modes being considered and very frequently the preference of the engineer who derives the associated transfer functions. For example, one engineer may prefer to express the requirement on a structural member in terms of a load per unit of area (e.g. pounds per square inch) while another engineer may prefer to express the requirement as the total load (e.g. pounds).

As noted above, Table 1 contains the R and C functions for the first six failure modes. For failure modes 1, 4, 5, and 6 and the R and C functions are engineering relationships which describe an imposed stress or load on the system (R) and the ability of the system to withstand that particular stress or load (C). For failure mode 3, however, the R function is a somewhat different type of relationship. It is a design criterion used to decide on the adequacy of the design of the forward motor skirt under combined compression shear and bending when considering inelastic deformation and/or buckling of the skirt. If the value (which is dimensionless) resulting from this calculation is less than 1.0 then the forward motor skirt is judged to be adequate. For failure mode 2 the R and C functions are gross time relationships. However, in the absence of a more refined description of the time that burning takes place in the motor and the time it will take to burn through to the case wall in terms of the physics and chemistry of the propellant and the insulation, these relationships are very useful for estimating the probability of failure for this failure mode. A few of the parameters in the R and C functions for the first six failure modes are treated as constants rather than as random variabiles because they have essentially zero variances. A discussion and description of how the random variable are combined, via the appropriate R or C function, to determine the probability of failure is given in Appendix IV.



Table 1. Summary of $R \| C$ functions.

** See discussion of FM 3 on page 14 regarding special characteristics of R and C for this failure mode.

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Table 2. Summary of Parameters.

Description, mean values, standard deviations, applicable failure modes

Parameter symbol	Description of Parameter	Location, Motor Station	Average X	Std. Dev. Ø	Applicable Failure Modes
A _{ti}	Initial Throat Area in ²	Nozzle Throat	6,235	0	5,6
A _{ei}	Initial Exit Area, in ²	Nozzle Exit	56,116	0	6
A _t	Average Throat Area, in ²	Nozzle Throat	6,355	20.9	1,4,5,6
A ₁₈₀	Area at Nozzle Joint, in ²		25; 477	0	6
Ъ	Propellant Web, in.	sta 4	87.5	.175	2
Ъ	"	" 5	85.0	.17	1, 2, 4, 5, 6
Ъ		" 6	71.85	.1437	2
Ъ	"	" 7	70.57	. 1411	2
с ₇	Propellant inner bore hoop strain storage in/in	Center Motor	. 242	.0392	7
c ₈	Propellant/liner radial bond stress,storage, psi	Áft end Motor	18.3	2.84	8
С9	Propellant principle stress, storage, psi	Aft end Motor	18.3	2.84	9
с ₁₀	Propellant/Liner shear stress, flight, psi	Fwd end Motor	418	39.2	10
с ₁₁	Propellant inner bore hoop strain, flight, in/in	Aft end Motor	. 441	.0674	11
c ₁₂	Insul. / case bond shear strength psi		375	64.13	12
с ₁₃	Propellant Ignition threshold jowles	Total Propellant	12.8	.188	13

Parameter symbol	Description of Parameter	Location, Motor Station	Average x	Std. Dev. g	Applicable Failure Modes
с ₁₄	Propellant auto-igni- tion temp, °F	Total Propellant	586	5.5	14
с _w	Mass flow coefficient, sec ⁻¹		. 0062477	.000019	1,4,5,6
đ	dist. TVC port & joint, in.	TVC port	178.84	0	5
D _j	dia. of Nozzle joint, in.	TVC joint	180	0	5
Eo	Propellant	Total Propellant			7-14
Es	Motor Case Modulus of Elasticity, psi		27, 500, 000	54,725	3
e r	Insulation erosion rate, in/sec	1,2	. 003	.000489	2
e r		5,6	. 005	.002586	2
e _r	i1	7	. 006	. 000979	2
e r	н	12	.0168	.00274	2
F _{by}	Min. Tensile Load per bolt, lb	Nozzle flange	213,310	0	5
К _{ве}	Bending/discontinuity factor (ND) ⁽³⁾	cylinder	.95845	. 00693	1,4

Parameter symbol	Description of Parameter	Location, Motor Station	Average x	Std. Dev. o	Applicable Failure Modes
K _{bx}	Biaxial gain factor, (ND)	spheric al ends	1.106	.0312	1
K m/a	Ratio of Avg to Peak chamber press. (ND)	chambe r	1.18	.008968	1,4,5,6
к _с	Ratio of Axial Com- pressive strength to E. (ND)	Fwd Skirt	.0036	.000685	3
к _ь	Ratio of pure bending strength to E. (ND)	11	. 005	.000968	3
к _s	Ratio of transverse shear to E. (ND)	11	.00288	.00334	3
К Р	Fraction of bolt min. yield, to which bolt is pretorqued (ND)	Nozzle flange	.60	.077	5,6
L _c	Axial compressive load, lb.	Fwd Skirt	2,200,000	0	3
^L ь	Pure bending load, lb.	"	94,000,000	0	3
L s	Transverse Shear load, lb.	"	60,000	0	3
^M 180	Mach Number of gas stream at joint dia. (ND)	Aft chamber	.0576	ο	6
M _e	Mach Number of gas stream at exit plane (ND)	Nozzle Exit	3.205	o	6
n	Nozzle flange bolts, number.	Nozzle flange	220	-	5,6

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Parameter symbol	Description of Parameter	Location, Motor Station	Average T	Std. Dev. σ	Applicable Failure Modes
P	Max Chamber Pres- sure, psi.	Fow'd End	(1)		1,4,5,6
Pa	Ambient Atmospheric pressure,psi	Nozzle Flange	14, 696	.0735	5,6
Р у	Nozzle attach bolt Load capability, lb/bolt	Nozzle	245,307	1987	5
R ₇	Propellant Rqm ¹ t. corresponding to C ₇ through C14.	Center, motor	.037	. 0374	7
R ₈	"	Aft end, motor	2.47	.282	8
R ₉	11		5.51	.604	9
R ₁₀	11	Fwd. Equa- tor of motor	30.62	9.52	10
R ₁₁	11	Aft end, motor	.0749	.0489	11
R12	н		30.62	9.52	12
R ₁₃	11	Total Propellant	.015 (max)	0	13
R ₁₄	11	Total Propellant	100.1 (max)	0	14
Ro	Outside radius, motor in.	Cyl.portion of case.	130,631	.0261	1
R _o	11	Spherical protion of case.	130.428	.0456	4

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Parameter symbol	Description of Parameter	Location, Motor Statior	Average X	Std. Dev. Ø	Applicable Failure Modes
r _b	Propellant burn rate in/sec.	2, 5, 6, 7,	.606	. 00361 ⁽²⁾	1, 2, 4,
r _b	11	aft	.606	.00818	5,6
r _b	11	4	.590	. 00351 ⁽²⁾	1,2,4,
R _i	Radius to inner sur- face of nozzle skirt, in.	Nozzle skirt	129.903	.0203	3
R _c	Ratio of axial com- pressive load rqm't. to material capability (ND)	Fwd s kirt	(1)	—	3
^R ь	Ratio of transverse shear load reqm't to material capability (ND)	"	(1)		3
R _s	Ratio of pure bending load requirement to material capability (ND)	11			3
Sumw	Ultimate machine weld strength, psi	case welds	232,000	2,516.6	1,4
$^{\rm S}{}_{ m uhw}$	Ultimate hand weld strength, psi	case welds	199, 333	8,641	1,4
t. i	Insulation thickness, in	1,2	1.125	.01667	2
t _.	"	5	.110	.0033	2
t i	"	6	.250	.01667	2
t _i	"	7	.43	.01667	2
t _i	"	12	3.6	.01667	2

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Parameter symbol	Description of Parameter	Location, Motor Station	Average x	Std. Dev. σ	Applicable Failure Modes
t _c	Motor case thickness,in	Cyl.	. 6392	. 0095	1
t _c		Spherical	.428	.0108	4
t s	Motor skirt thickness, in.	Fwd Skirt	.728	. 0093	3
w _p	Propellant Weight, lb.	Motor	3,400,000	6,120	1,4,5,6
w _{ni}	Initial Nozzle Weight, lb.	Nozzle	58, 428	0	6
w _{vi}	Initial Launch Weight of vehicle less first stage propellant, lb.		726,466	0	6
^π k	Temperature sensitiv- ity coef. %/°F.	Propellant	.16	.00676	1,4,5,6
α	T.V.C. angle, degree	Nozzle	3.6	0	5
Y	Ratio of specific heats (ND)	Propellant	1.2	0	6
	l				

- Notes: (1) These terms are functions of many parameters, and density functions can be generated for these for a given set of input data.
 - (2) AGC selected these input parameter values. Their selection criteria are briefly discussed in Appendix I.
 - (3) (ND), Non Dimentional

For failure modes 7 through 14, AGC did not submit transfer functions and input parameter densities. Rather, they gave us means and standard deviations for capability and requirement densities which they said were all Gaussian. Hence for all of these modes, we could write a closed form solution since the difference of two Gaussian variables is also Gaussian. The notation is as follows.

			Standard	
	Variable	Mean	Deviation	
Capability	С	T	σ _C	-
Requirement	R	R	σ _R	
Capability minus Requirement	(C-R)	$\overline{C-R}$	$\sigma_{(C-R)} = \sqrt{\sigma_C^2 + \sigma_R^2}$	

The probability of failure is obtained from tables of the normal function as the area in one tail of the normal curve with zero mean and unit variance beyond the point $\overline{C} - \overline{R}$

$$\sqrt{\sigma_{\rm C}^2 + \sigma_{\rm R}^2}$$

The basic data supplied by AGC is shown in Table 2. As noted earlier, this data was treated in two ways. First, an $\mathbb{R} \| \mathbb{C}$ analysis was made for each failure mode using the input data with no modification -these were called standard analyses. This was followed by analyses which used a series of data modifications, usually increases or decreases in the input standard deviation and less often by shifts in the value of the mean. These so-called sensitivity analyses were made to establish the criticality of the parameters with respect to the failure probabilities. A listing of the results of all of the standard analyses is shown in the body of Table 3. The footnotes illustrate the kinds of answers obtained in the sensitivity analyses for failure mode 2, these being quite completely described in Appendix II. Table 4 illustrates a more complete sensitivity analysis which was made for failure mode 1.

The case insulation burn through failure mode (FM 2) provides a very good illustration of the value of $\mathbb{R} \| \mathbb{C}$ analysis in terms of the

Failure Mode	Description	Motor Station	P[S] for Standard Run
FM 1	Hoop stress, case rupture	Forward	>. 999999
FM 2	Case insulation burn through	1, 2	>.999999
	0 0 U U	5	.983907 (1)
11	0 0 0 0	6	. 862888 (2)
11	11 11 11 11	7	.988810(3)
"	11 11 11 11	12	.953370 (4)
FM 3	Failure of forward motor, skirt forging in combined compression; shear and bending	Forward Skirt	> . 9 99999
FM 4	Meridional stress, case rupture forward head	Forward Head	>. 999999
FM 5	Rupture of nozzle joint bolts	Nozzle Flange	>. 999999
FM 6	Separation of Motor Chamber and nozzle flange	Nozzle Flange	. 999998
FM 7	Propellant max. inner bore hoop strain—storage	Center of Motor	. 999999
FM 8	Propellant liner interface max. radial bond stress—storage	Aft end, Motor	>. 999999
FM 9	Propellant maximum combined stress in shear and tension—storage	Aft end, Motor	. 999989

Forward

Aft end

Motor

Bond

Total

Surface Total

Propellant

Propellant

end Motor

>.999999

>.999999

>.999999

>.999999

>.999999

Table 3. Summary of failure modes $R \parallel C$ analysis.

NOTES:

FM 10

FM 11

FM 12

FM 13

FM 14

(1) For double insulation, P[S] = .999988

Propellant/Liner interface max.

Propellant max Inner bore hoop

Insulation/Motor interface bond.

Propellant autoignition due to

Propellant autoignition due to

shear stress-flight

strain-flight

Max shear-flight

static discharge

self heating.

(2) For double insulation, P[S] = >.999999

(3) 50% increase in insulation, P[S] = .999999

(4) 50% increase in insulation, P[S] = >.999999

Run	Parameter	Variability Factor V _f	σ	ν _f σ	P[S]
Standard	*	1	*	*	>.999999
1	Sumw Suhw	4 2	2516.6 8641.	10066.4 17282.	.999772
2	Sumw Suhw	8 4	2516.6 8641.	20132.8 34564.	.994983
3	r _b	4	.00361	.01444	.999781
4	К _{. be}	5	.00693	.03465	. 999995
5	K be	1.0	.00693	.0693	.999832
6	K _{m/a}	5	.00897	.04485	. 999999
7	$\frac{K}{m/a}$	10	.00897	.0897	.999885

Table 4. Summary of sensitivity analyses for failure mode 1.

NOTE:

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*The standard run used the unadjusted data supplied by AGC for all parameters and, consequently, the variability factor is unity. For other runs, unadjusted data was used for all parameters except for those noted in the column labeled "Parameter."
standard data and also of the sensitivity analysis. The reliability of .862888 at station 6, standard data, is entirely too low to be acceptable, a fact which would not have been easily recognized and quantified without $R \parallel C$ analysis. The significance of insulation thickness is shown in the sensitivity analysis, footnote 2, in which a doubling of the insulation thickness at this station raises the reliability above .999999. At stations 7 and 12, an increase of 50% in insulation thickness is ample to provide a reliability increase to the level of .999999 at each of these stations.

The hoop stress failure mode, FM l, also provides an interesting illustration of the value of $R \| C$ analysis, especially with respect to a study of the sensitivity of the failure probabilities to changes in the data inputs. The numerical results of eight runs are summarized in Table 4. The unadjusted AGC data is used in the standard run which yielded an estimated reliability in excess of . 999999. The other runs, identified as runs 1 through 7 in Table 4, were based on modifications of the unadjusted standard deviation. The modification consisted merely of multiplying the unadjusted standard deviation, σ , by a variability factor, V_f , as shown in the table. The variability factors should be selected to cover some realistic range for the particular parameter under consideration. Runs l and 2 involved modifications in weld strength standard deviations for both machine and hand welds. Each of the other runs involved only one variability factor associated with the indicated parameter. As expected, increases in input standard deviations lowered the reliability estimates, the lowest value being .994983 for run 2. The details of this analysis are given in Appendix II.

In summary, Table 3 indicates that there are a few problem areas in the case insulation burn through, but that for most failure modes, reliabilities are close to the range of .999999 and above. Furthermore, the sensitivity analyses identify those parameters which are most critical in causing the unreliabilities and indeed it measures the extent of the influence of each on the related failure probabilities. Thus, the sensitivity analyses demonstrate the way in which the $R \parallel C$ technique serves as a valuable design tool, quantifying the effect of a proposed modification on reliability in advance of its implementation. In other words, it permits the designer to make more nearly optimum tradeoffs in solving his design problems as they arise.

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Consideration of System Interactions In Determining the Probability of One or More Failure Modes

To determine the probability of the occurrence of one or more failure modes (i.e. the probability of system failure) or, if one wishes, the probability of no failure mode occurrences (i.e. the probability of system success-or reliability) the correlation between parameters which interact to define the various failure modes must be properly considered. If, for example, no correlation exists (i.e. all failure modes, and consequently all parameters, are statistically independent of one another) then the probability that no failure mode will occur in the system is simply the product of the probability of the non-occurrence of each single failure mode. When correlation exists between failure modes, however, the correlated failure modes must be treated simultaneously to determine the probability of the occurrence of one or more of the modes (It should be noted that this probability will be greater than the probability of the occurrence of any single failure mode.). A detailed discussion of this process is given in Appendix IV, entitled "Computations When There Is Dependence Between Two or More Transfer Functions."

General Comments on the Motor Example

Up to this point the report has provided a brief survey of the background upon which the current work is based, a summary of the current state of development of the $R \| C$ methodology, and a description of the application of the method to the reliability analysis of the 260 inch solid rocket motor which has been performed to date. In this discussion of the motor example, we would like to synthesize all of this information into a logical presentation of the current status of this research program and an interpretation of this status in terms of the objectives which we believe we have accomplished and the objectives which should serve to guide future efforts.

Throughout the sequence of studies on the reliability of solid rocket motors, it has been clear that the purpose has been two-fold: (1) provide information which can be used to enhance the reliability assessment of the large solid rocket, or any system, and (2) develop techniques which will help us assess the level of reliability throughout the development of these systems. We have been concerned primarily with the use of the 260 inch motor system as an example with all the problems attendant an expensive item which will have only limited production and naturally very limited development test firing. These characteristics have necessarily lead us to emphasis on analytical techniques. We feel very strongly that this emphasis on analytical methods has not in any way sidetracked this work from the two practical objectives listed above—we are certainly attempting to provide the design engineer with information which will assist him in his design effort and methods whereby he can assess his progress toward assigned reliability goals.

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The application of $\mathbb{R} \| \mathbb{C}$ methodology to the motor example led to several observations. It is felt that the feasibility of performing $R \| C$ analyses on real systems has been definitely established. Even though we may not be able to analyze every failure mode, we can cover a large number of them, perhaps the most critical, thus reducing the area of uncertainty. In establishing this feasibility, it is clear that this method is a useful design tool, especially in the performance of design trade-off studies in advance of testing. The limited examination of closed form solutions in Appendix VI illustrates what really is involved in the basic theory. Of course it points out the complexity of the mathematics involved and thus it serves to reemphasize the versatility and economy of a time sharing computer system. The adaptation of the GE time sharing computer for example, to the problem of combining random variables quickly and cheaply, has been one of the most significant outputs of this research effort. We have seen how it can combine probability densities without resort to Monte Carlo methods-it in effect generates discrete approximations to closed form solutions with the capability of reducing approximation errors to any required low level. The examples which have been worked out also demonstrate that, as far as the method is concerned, it is quite unnecessary to attempt to prejudge the form of the input densities. The method works equally well with density equations, with tables of discrete data, or with any combination the reof.

In summary, then, it seems appropriate to say that the numerical results obtained in this phase of the study are encouraging to the extent that they do validate the $R \| C$ method. With respect to methodology, results seem to be quite close to expectation. The major problems involved in combining random variables have been solved but future research can provide even faster and cheaper techniques through proper revision and improvements of the computer programs.

6. CONCLUSIONS

The goals of this study, namely to demonstrate the $\mathbb{R} \| \mathbb{C}$ analyses of certain failure modes on a large solid rocket motor, have been met to a degree that demonstrates the soundness of the technique. The research effort associated with these goals, and described herein covers a) reliability analysis of the large solid rocket motor, and b) technique development. Hence it is appropriate to present the conclusions (and in Section 7 the recommendations) in the two corresponding categories.

- 1. Conclusions Concerning Estimates of Reliability of the Large Solid Rocket Motor System.
- 1.1 Failure Modes 1 and 4 cover hoop and meridional stresses of the case welds. The analysis shows that the weld strength parameters of hand welds are by far the most critical—they are used in the rework of defective machine welds. Although only 10% of all welds were done by hand, they greatly predominated the failure probability by many orders of magnitude.
- 1.2 The insulation burn-though failure mode was found to be critical at four motor stations, 5, 6, 7, and 12. These had undesirable reliability estimates of .984, .863, .989 and .953 respectively. The sensitivity analysis indicated two things: first that these reliabilities could be raised to satisfactory values if the insulation were increased by varying amounts at the critical stations, or if the standard deviation of the insulation erosion rate could be decreased; second, that the insulation erosion rate variability was the most sensitive parameter by far. Some parameters showed little effect on the estimate of reliability even when they were increased an order of magnitude or more (e.g. propellant effective web thickness could be reduced 10 inches and still not affect burnthrough significantly).
- 1.3 Analysis of the forward motor skirt forging in combined compression, shear and bending indicated very low probability of failure.
- 1.4 Results indicated that the probability of rupture of the nozzle joint bolts was very low.
- 1.5 Separation of the motor chamber and nozzle flange failure mode showed a reliability of .999 998. However, further attention should be given to the parameters associated with this failure mode because the sensitivity analysis showed that values of about .98 were possible.

- 1.6 The two propellant failure modes 7 and 9 dealing with inner bore hoop strain-storage, and principle stress-storage, appeared to be marginal in terms of their reliability and warrant further study.
- 1.7 The three propellant failure modes 8, 10 and 11, which involve propellant/liner interface radial bond stess—storage, propellant/ liner interface shear stress—flight, and propellant inner bore hoop stress—flight, showed relatively low probabilities of failure.
- 1.8 The insulation/motor case interface bond failure mode showed a relatively high reliability.
- 1.9 The auto-ignition failure mode appears to have an insignificant probability of occurrence on the basis of the data and other information currently avaiblable from AGC. They reported it to be much less than 10^{-6} .
- 1.10 Study results were distinctly encouraging in that the feasibility of application of the R||C method seemed to be clearly established. Given approviate support, and necessary input data and transfer functions from AGC, then, GE time sharing (or possibly other computer techniques) has the capacity and flexibility ideally suited for such analyses.
- 2. Conclusions Relating to the Results of Technique Research.
- 2.1 A methodology has been developed that can be used directly by the design engineer. The techniques used to implement this methodology have proven to be tractable and economical.
- 2.2 Very satisfactory progress has been made in the development of computation methods using time sharing computer techniques. For example, the computer programs provided rapid and economical processing of input data when the inputs were assumed to be Gaussian as well as when raw data was used.
- 2.3 It should be emphasized that the computer technique permits the accomplishment of $\mathbb{R} \| C$ analysis, no matter what the forms of the input densities, through the use of discrete approximations to continuous densities.

- 2.4 Numerical accuracy is dependent on the accuracy of the input data and on the way in which the continuous density is approximated by the discrete one. Of course, the discrete approximation can be as good as required by forming a sufficiently large number of intervals with sufficiently small widths.
- 2.5 The data, in general, was available but some searching of the files by AGC was necessary.
- 2.6 The discussion of closed form solutions presented in Appendix VI pointed out the fact that input densities of a specified type do not regularly lead to output densities of the same type. Indeed, it is neither easy nor necessary to attempt to guess the form of the output density. The method will generate it without any guess by the analyst.

7. RECOMMENDATIONS FOR FUTURE WORK

Future efforts should be continued in the reliability analysis and technique development categories for solid rocket motor examples. Technique development, which included the mathematics and computer methods for handling the $\mathbb{R} \| C$ analysis, is further advanced in the present phase of work than is the reliability analysis of the failure modes. It is therefore recommended that greater stress be placed upon the reliability analysis category; however, certain important improvements of the techniques are strongly advised.

- 1. Recommendations Relating to Reliability Analysis
- 1.1 The weld strengths were found to be the critical element of failure mode 1. This will require a detailed analysis of the elements that make up weld strengths and their associated variabilities:
 - a) Fracture toughness, critical crack length, location, size, etc.
 - b) Comparison of an alternative material such HY-160 steels.

Further study of welds that require hand processing should be made because of the predominant effect on reliability of their reduced strengths.

- 1.2 It is recommended that additional factors associated with the burn-through failure mode, such as the presence of cracks, voids, laps and folds, be considered in the future work. Further analysis of the variability of the insulation erosion rates should be made, since this was found to be a critical element of the analysis of failure mode 2. The time to burn through the case could be considered and its effect upon system failure could also be evaluated.
- 1.3 The current status of data generated and engineering analysis made by AGC of the bond and tensile stress failure modes associated with the grain was inadequate for a proper $\mathbb{R} \| C$ analysis. Within the limitations of the data, however, the failure modes appeared to require further analysis because of their relatively low reliability:

- a) the propellant maximum inner bore hoop strain (storage condition), and
- b) the propellant maximum combined stress in shear and tension (storage condition)

It is suggested that further effort be made by AGC to generate additional data and transfer functions required for this analysis.

- 2. Recommendations Relating to Technique Research.
- 2.1 The theory for handling dependence between failure modes which is merely correlation between transfer functions has been presented. However, the computational techniques for this situation need further refinement and this should be included in future phases of the research program.
- 2.2 Further study should be made of those subsystems that have not yet been analyzed by the R||C technique (e.g. ignition system, nozzle, etc.)
- 2.3 Consideration should be given to the problem of appropriately apportioning the reliability required for the total system to each of the individual failure modes.
- 2.4 The $\mathbb{R} \| \mathbb{C}$ approach is general in its applicability and should be applied to other systems, as well as the large solid motor, such as the small motors, both liquids and solids, the hybrids, other liquid systems, etc.
- 2.5 Future research should be devoted to further refinement of the computational procedures and to additional study of closed form solutions for more realistic transfer functions.
- 2.6 Computer program refinements which were made during the course of this study indicate the feasibility of even more significant improvements, specifically in a reduction in the time which must be spent by an engineer in performing an R||C analysis. Research in this area should be pursued.

APPENDIX I

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SUMMARY OF INPUT DATA, RATIONALE AND DESIGN EQUATIONS OBTAINED FROM AGC

Introduction

This appendix contains the input data received from AGC in the form of data packages and progress reports. This information consists of engineering equations, rationale, and density function data describing the means and variability of the parameters. These data are in general unmodified, with only minor changes and editing done in the interest of conformity to the report format or to prepare the form of the material for R||C analysis. The use of these data and transfer functions in R||C form are discussed in Appendix II, and summarized in Section 5 of the body of the report.

The AGC progress reports and data packages are listed in the references in this report. AGC has also prepared a final report covering these data (Reference 5).

Since it is not the intent to modify any data or comments, much of the following data is only briefly presented and explained. Certain sources referred to in their data packages were deleted. For more details, the reader is referred to the AGC progress reports, work packages, and final report as listed in the references. Failure Mode 1. Failure of Cylindrical Section Longitudinal Weld in Hoop Stress (Location 40" Aft of Forward Equator)

The basic engineering data for this failure mode is covered by AGC Data Pack II-1.

Table I. 1 summarizes the AGC parameter averages, standard deviations, and coefficients of variations for this failure mode.

Table I.2 consists of the AGC support data, the "batch" data, from which is made up the summary data of Table I.1. The rationale and engineering discussion in support of these data as supplied by AGC is as follows.

1. Capability Rationale. The formula used is the basic hoop stress formula modified to allow for a reduction due to local bending and discontinuities and for an increase due to biaxial gain. Ultimate, rather than yield parameters are used. The capability is calculated at the exterior surface which theoretically will experience greater stress than the interior. A location 40" aft of the forward equator* was chosen to eliminate the effects of discontinuity stresses associated with the transition from the cylindrical section to the forward head.

During the fabrication of the first two 260-inch diameter short length motors, it was found that manual repair welds had a lower strength than the normal machine welds. It is estimated by AGC that 10% of the total weld length of the 260/S IV-B motor would consist of manual welds. Therefore, the capability distribution should be constructed as the probabilistic sum of both a manual and a machine weld distribution, with the latter encompassing 90% of the total welds and the former 10%. All parameters used in the formula are assumed to be independently and normally distributed. The coefficient of variation, $\frac{10}{x}$, is assumed to be constant for varying values of \overline{x} .

Machine and Hand Weld Ultimate Tensile Strength. Data were available for a limited number of sample machine weld and hand weld coupons that were maraged in representative locations on both 260-SL chambers. A variety of weld wire heats are represented since it is this parameter rather than parent metal strength that governs weld strength. As can be

^{*} This region occurs at about motor station 3.

Table I. 1 Summary of Capability Distribution Parameters: Averages, Standard Deviations and Coefficient of Variations for Failure Mode 1: Motor Case Hoop Stress Failure.

Parameter	Avg. or Nominal x	Standard Deviation (Est, of Pop Deviation) o	Coef. of Variation, σ / \bar{x} Non dim.	Sour of Va	Ce alues
Machine Weld UTS, S psi umw, psi	232, 000	2516.6	. 01 0847	x, σ:	260-SL-1 and 260-SL-2 Maraged weld coupons*
Hand Weld UTS, S _{uh w} , ^{psi}	199,333	8641.0	.043350	x,σ:	260-SL-1 and 260-SL-2 Maraged weld coupons*
Plate Thickness, t c	.63922	. 0095	.0149	. σ:	Design nominal 18 plates from 18 heats used in 260-SL-1 and 260-SL-2*
Radius (exterior), R in.	130.631	. 0261	.0002	x: σ:	Design nominal Tolerance on radius plus plate thickness variability*
Bending/Discontinuity Reduction Factor, K	.95845	. 00693	. 007231	x, σ:	Est from 260-SL-1 and SL-2 hydrotest strain gage data*
Biaxial Gain, K _{bx} Factor	1.1105	. 03 12	. 0282	x: σ:	Two PETV subscale hydroburst tests* Nine D6AC 7.25 in dia test vessels*
Web Thickness, b, in.	85.0	. 170	. 002	x: σ:	Design nominal 260-SL-1 vs. 260-SL-2 (AGC Report NAS 7-572 PR-2, Figure 3)
Propellant Weight, W _p , lb	3,400,000	6120	.0018	x: σ:	Design nominal 260-SL-1 vs. 260-SL-2 **
Burning Rate, r _b				_	
at (80°F), in/sec	.606	.00818	.0135	χ: σ:	Design nominal 260-SL-1 vs. 260-SL-2 plus Scaleup Factor*
Temperature Sensiti- vity, ¶ _k ,%/°F	. 16	. 00666	. 0416	π.: σ:	Design nominal NASA Variability Study, Report 0815-*F, Figure 11
Max Temperature Difference, ∆t, [°] F (Assumes max value)	20	_	_	x :	Extreme (100°F) Minus Nominal (80°F)
Ratio of Peak to Avg. Pressure, K _{m/a}	1.18	.008968	. 0076	х: σ:	Design nominal Avg. of 4 Motor Programs *
Mass Flow Coefficient, C _w , sec ⁻¹	.0062477	.0000190	. 003 05	x: σ:	Design nominal Nine 52-india Motors*
Avg. Throat Area, A _* , in ²	6355	20.9	. 00332		Design nominal 260-SL-1 vs. 260-SL-2*

* AGC routinely used the fotation \overline{x} for mean and σ for standard deviation for all parameters in their data presentations even though other letters were used in the equations.

** See Table I.2

Maraged Weld	Coupon Ultimate Ten	sile Strength
l) Machine Welds, Sumw	,	
Weld Wire	UTS	Maraged with
Heat No.	$\frac{1b}{in^2}$	Motor No.
63343	231,000	260-SL-1
8436	235,000	11 11
9035	231,000	11 11
8950	233,000	11 11
9620	228,000	11 11
9624	235,000	260-SL-2
9994	231,000	11 11
	$\bar{\mathbf{x}} = 232, 000; \sigma = 2$	516.6
	$cv = \frac{\sigma}{x} = .01084^{\circ}$	7
Maraged Weld	Coupon Ultimate Ten	sile Strength
2) Hand Welds, Suhw		
63343	189,000	260-SL-1
63343	195,000	11 11
63343	197,000	11 11
9624	214,000	260-SL-2
9624	197,000	11 11
9620	204,000	11 11
	$\bar{x} = 199,333; \sigma = 86$	541
	$cv = \frac{\sigma}{\bar{x}} = .04335$	

Table I.2 List of AGC Batch Data for Parameters Summarized in Table I.1.

	· · · · · · · · · · · · · · · · · · ·			
3) Plate Thickn	$\frac{ess}{c}$, t_c		· ·	
	Plate	· · · · · · · · · · · · · · · · · · ·		
	Thickness, in.	Within	Motor	
Heat No.	(Avg of 15 Readings)	Plate Std Deviation*	No.	
50265	. 651	. 0060	260-SL-2	
50264 B1	. 637	.0052	11	
50338 B2	.640	. 0033	11	
50210-3	.647	. 0057	260-SL-1	
24997-1A	. 631	.0060	11	
24999-1A	. 639	.0080	11	
3951218-A	. 631	.0060	11	
25126-1	. 638	.0070	11	
3951215 B	. 653	.0097	260-SL-2	
3960819	.635	.0078	260-SL-1	
3960832 A	.640	.0080	11	
25098-i	. 643	. 0034	11	
25007-1	.642	.0020	0	
24998-1	. 630	.0026	11	
3960829 B	. 636	. 0092	260-SL-1	
3960870 B	. 625	. 0051	260-SL-2	
24996-1A	. 642	. 0049	11	
50234	. 646	. 0086	11	
	$\bar{\mathbf{x}} = .63922$ σ_{wit}	hin plate = .0060 (avg)		
a a a a a a a a a a a a a a a a a a a	- 0074	ann prate		
plate	to plate = .0074			
$\sqrt{\frac{2}{2}}$				
Total variability = $V \sigma_{pp} + v_{pp}$; $\sigma_t = .0095$				
(any location)	** *	°t _	- 0149	
1		x	0177	
·				

* Estimated by range method. AGC used this method routinely for estimating standard deviations from small samples.



) <u>Bending/D</u> <u>Motor</u>	<u>iscontinuity</u> Location	Net Tensile Stress psi	duction Factor, Bending Stress, psi	K _{be} <u>1-(Bending Stress</u>)
260-SL-1	16	151,200	+ 4,850	. 9679
260-SL-2	43 44	149,400 148,200	$\frac{+}{+}$ 7,350 $\frac{+}{+}$ 6,400	.9559 .9515 .9585
<u> </u>				x = .95845
				$\sigma = .00693$ $cv = \frac{\sigma}{\bar{x}} = .007231$

6) <u>Bi</u> a	iaxial Gain Factor, K _{bx}				
(1)	<u>x</u> from 36	" Dia Subscale H	lydroburst Tests (18%)	Ni Maraged Steel)	
	Test	Weld Coupon Uniaxial UTS, KSI	Burst Strength, KSI (PR/t)	Biaxial Gain Factor	
	PETV-1	216	240	1.111	
	PETV-2	217	241	1.110	
		·····		$\bar{x} = 1.1105$	
(2)	σfrom 7.	25" Dia Subscale	e Hydroburst Tests (La	dish D6AC Steel)	
	Test	Uniaxial UTS, KSI	Burst Strength, KSI (PR/t)	Biaxial Gain Factor	
		222	250	1 1 07	
	1	235	258	1.107	
	3	2.2.2	252	1.144	
	4	230	257	1.117	
	5	235	256	1.089	
	6	241	263	1.091	
	7	241	263	1.091	
	8	234	252	1.077	
	9	230	246	1.070	
-				$\bar{x} = 1.106$	
				$\sigma = .0312$	
				$cv = \frac{\sigma}{\bar{x}} = .0282$	

Table I.2 Cont

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. . . .

8)	8) <u>Propellant Burning Rate</u> , r _b					
	Motor	Web Duration sec			Batch Mix Liquid Strand Burning Rate in/sec	
	260-SL-1	113.7			. 444	
	260-SL-2	114.0	- ,		. 441	
			Range	=	.003 in/sec	
			σ	=	.00265*	
			cv	=	.006	
г	Thus for 260/S W-B:	$\left(\frac{\sigma}{\overline{\mathbf{x}}}\right)$ (2.2	255) ** =	. 0	06 (2.255) = .0135	
		and $\sigma = (.$	0135) (. 6	606)	= .00818	

* Using the range method

** Special AGC scaleup factor, see text, page I.12

Table I.2 Cont

-

9) Ratio of Avg. to Peak Press	sure, K _{m/a}	.: •
Program	Average Ratio x	Motor to Motor Coefficient of Variation
Minuteman Wing VI	1.17	. 0050
Minuteman Wing I	1.08	.0082
Alcor	1.27	. 0081
Algol	1.08	. 0091
	$\vec{x} = 1.18^*$	$\overline{Cv} = \frac{\sigma}{\sigma} = .0076^{**}$
For 260/S IV-B: $\sigma = 1.1$	8 (. 0076) = . 00896	9
10) Mass Flow Coefficient, C.,		
· · · · · · · · · · · · · · · · · · ·		
52-india		C /sec
Motor no.		w
1		00624583
2		00628364
3		00624590
5	•	00622264
6	÷	00626091
7	•	00624864
10	•	00622428
RCD-1		00625999
	x = .	00624774
	$\sigma = .$	00001904
	$cv = \frac{\sigma}{x} = .$	003 04 8

* This reported value was used in this study. (It should be 1.15)
** Average for 4 motor programs (see text).

- --

11) <u>Avg</u>	. Throat Area, A _t		
-	Motor No.	Avg. T	hroat Area, in
	260-SL-1		3991
	260-SL-2		3979
		Range =	12 in ²
		σ =	10.65 (Based on range)
		$cv = \frac{\sigma}{\overline{x}} =$.00332
F	or 260/S IV-B, $\sigma = 6355$ (.003	32) = 20.9 in^2	
NOTE:	This observed $\frac{\sigma}{\overline{\mathbf{x}}}$ value is the	same as that o	btained when based
	upon dimensional tolerances variability.	and observed li	near erosion rate

seen in Table I.2, items 1 and 2, the hand weld strength averaged 86% of the machine weld and it had a coefficient of variation of .04335 compared to the .0108 for the machine weld. The .04335 figure is probably excessive and indicates an area in which additional data is required. *

Plate Thickness. These data came from 18 plates of material that were used in 260-SL-1 and 260-SL-2, shown in Table I.2, item 3. In addition to the plate-to-plate variability, a within-plate component of variance was included to properly estimate the range of thickness possible at any given location. To save computational time, the withinplate component of variance was estimated for each sheet by taking a stratified sample of 15 readings of the 200 or more vidigage measurements actually made, and the average of these 18 within-plate standard deviations was squared and combined with the plate-to-plate variance to obtain an estimate of the total thickness variability.

Exterior Radius Variability. The exterior radius variability was estimated as the sum of two components of variance: the tolerance on the inside diameter and the variability of the plate thickness. As shown on Table I. 2, item 4, the coefficient of variation derived from this combination of these two sources is an almost negligible .0002.

Bending/Discontinuity Strength Reduction Factor. While it is well known that local contour deviations and material discontinuities can result in bending stresses above that normally predicted, data as to the magnitude and variability of the amount of reduced strength that can be expected is extremely limited. The best data that can be obtained was derived from strain gage measurements taken during the hydrotest of the two 260-inch diameter motors. Table I.2, item 5, shows the bending stress estimated at four locations in the two motors. The locations were in the middle of the plates in the cylindrical section and were chosen as control gages to compare with readings at other locations where the effects of thin material, inclusions, and known contour deviations were being assessed. The strength reduction factor, calculated as one minus the ratio of bending stress to net tensile stress, was calculated for each of the four locations. The computed coefficient of variation, .0072, was assumed to represent the variability to be encountered.

Biaxial Gain Factor. The average level of biaxial gain in the cylindrical section was estimated at 1.1105 based upon the results obtained in two burst tests of 18% maraging steel 36-inch-diameter chambers. The coefficient of variation was determined to be .0282 for nine 7.5-inchdiameter Ladish D6aC test chambers. It is not known whether this value

^{*} This is especially true since sensitivity analysis indicates that this parameter's variability is the critical element of this failure mode.

reflects heat-to-heat variability or whether the welds or parent metal coupons were used in the uniaxial tests. (Table I.2, item 6)

2. Requirement Data Rationale. The requirement distribution is that of the maximum chamber pressure expected when operating at the upper specified pre-firing propellant temperature limit of 100° F.

Propellant Weight. The standard deviation of the first two 260-inchdiameter motors was estimated by dividing the observed difference by a factor of 1.128.* The resulting coefficient of variation of .0018 agreed well with a figure of .0021 calculated by estimating the grain weight variability from the variability of an equivalent cylindrical grain whose density, length, inside diameter and outside diameter variabilities can be estimated. (Table I.2, item 7)

Propellant Burning Rate. The motor-to-motor variability of average propellant liquid strand burning rate was estimated from the average batch mix liquid strand burning rate cast in 260-SL-1 and SL-2 motors. The standard deviation estimated by the range method was .00265 in/sec, from which we obtained the coefficient variation, .00265/.4425 = .006 . While the two motors were actually targeted for slightly different averages, the difference between the two for batch mix propellant was felt to be a conservative estimate of what could be attained if motors were actually targeted for the same averages.

Experience in a variety of programs has shown that the variability of tweb action time is significantly greater than can be accounted for by liquid strand burning rate variability. As a result, an adjustment or scale up factor is used to account for this discrepancy. An average adjustment factor of 2.255 was determined from eight different motor designs and it was used to compensate between liquid strand burning rate data and the 260/S IV-B motor estimate of burning rate. Multiplying this factor times .006 yields a value of .0135 for $\frac{\sigma}{x}$. (Table I.2, item 8).

* Aerojet prefers to use the more conservative range method for estimating standard deviations when the sample size is extremely small (i.e., 2, 3, etc.). For a sample of two, this will result in a standard deviation 25.3% higher than that estimated by the conventional method. Reference: (1) Bennet & Franklin, Statistical Analysis in Chemistry

and the Chemical Industry, 1954. Table 5.5, Page 165.

 (2) Grant, E. L., Statistical Quality Control, 1952, Table 3, Page 512, Factors for Estimating O' from R. Ratio of Average to Peak Pressure. This factor is included to reflect the effects of additonal burning surface variability due to separations, voids and manufacturing deviations. The average value is the design ratio of maximum to average pressure for a nominal 80°F firing. The variability was estimated as the average coefficient of variation measured in four motor programs. (Table I. 2, item 9)

<u>Mass Flow Coefficient</u>. The most accurate measurement of C variability was obtained in a 52-inch-diameter motor program where the most advanced computer data reduction techniques were employed. The estimated motor-to-motor $\frac{\sigma}{x}$ for these motors was found to be .00305. (Table I. 2, item 10) \bar{x}

<u>Average Throat Area</u>. A $\frac{\sigma}{\overline{x}}$ of .00332 was estimated by the range method using the average of prefire and postfire throat areas in the first two 260-inch-diameter motor firings. (Table I.2, item 11)

3. AGC Design Equations^{*} for FM l Requirement. The formula for instantaneous chamber pressure P_C is derived from the steady state mass balance equation

$$P_{c} = \frac{r_{b}A_{p}}{C_{w}A_{t}}$$
(1)

where

$$r_b = propellant burning rate at nominal temperature, in/sec.
 $A_p = burning surface, in.^2$$$

$$\rho$$
 = propellant density, 1b/in.³

 $A_{t} = average throat area, in.²$

This formula was judged not to be an optimum one for use in estimating the distribution of maximum pressures since the variability of burning surface at time of maximum pressure cannot be measured. The following

^{*} These data are found in Data Package II-1, reference 4.

formula, which substitutes propellant weight and web thickness for the density and surface area terms, was used to gain a better evaluation:

$$P_{c \max} = \frac{W_{p} r_{b} K_{m/a}}{b C_{w} A_{t}}$$
(2)

where

$$W_p$$
 = propellant weight, lb.
 $K_{m/a}$ = ratio of peak to average web pressure, (ND)
 C_w = propellant mass flow coefficient, sec. -1
 A_t = average throat area, in.²
b = propellant web thickness, in.
 π_k = temperature sensitivity coefficient of pressure, %/°F

Capability. The ultimate burst pressure, ${\bf P}_{m{\bf w}}$, due to machine welding may be expressed by

$$P_{mw} = \frac{S_{umw} t_c K_{be} K_{bx}}{R_o}$$
(3)

where

$$P_{mw}$$
 = ultimate burst pressure machine welds, psi.
 S_{umw} = machine weld ultimate tensile strength, psi.
 t_c = case plate thickness, in.
 R_o = radius (to exterior), in.
 K_{be} = bending/discontinuity strength reduction factor (ND)
 K_{bx} = biaxial gain factor (ND)

Ten percent of the time the weld strength will be reduced due to the necessity to make local repairs by hand welding. The same formula applies with S hand weld ultimate tensile strength, substituted for S unw.

Failure Mode 2. Data, Motor Case Insulation Burn-Through

Data used for this failure mode supplied by AGC is covered in Reference 3. Failure was defined as the occurrence of erosion through the insulation to any part of the case prior to the end of action time. Although additional time would be required to burn through the steel and cause the chamber to rupture, this extra margin was not considered.

<u>Capability</u>. It was defined then that the capability at any section of the motor is

$$T_{bt} = \frac{b}{r_b} + \frac{t_i}{e_r}$$
(4)

where

T _{bt}	=	time to burn through insulation, second
Ъ	=	propellant web thickness, in.
r _b	=	propellant burning rate, in. per second
t _i	=	insulation thickness, in.
e _r	=	erosion rate, in. per second

This failure mode involves both the insulation and propellant bubsystems and is an excellent example of why failure rates cannot be calculated separately for the propellant or insulation subsystems of solid rocket motors.

Requirement for this failure mode is total action time, or the maximum time of burning. This is derived by the formula

$$T_{a} = \frac{b'}{r'_{b}}$$
(5)

where

- T₂ = total action time (maximum time of burning), second
- b' = propellant web thickness, where the maximum T_a occurs (generally where propellant web is a maximum), in.
- r' = average burning rate for maximum action time, in. per second

The maximum web thickness for the 260/S IV-B motor occurs in the forward part of the cylindrical section (Station 4) where the nominal value for b' is 87.5 inches. Although the design nominal propellant burning rate is 0.606 inches per second, the average burning rate for the maximum web thickness section is less than this because the section nearest the sidewall burns during the tail-off period when the motor pressure is decreasing rapidly. Since the design nominal total action time is 148.5 seconds, the nominal average burning rate for maximum web thickness is 0.590 inches per second, and occurs at motor station 4.

The nominal thickness and burning rate for the insulation and propellant at other sections of the motor are tabulated in Table I.3. The assumed nominal maximum erosion rates, based upon the estimated maximum Mach number of the gas stream at that section are also shown in the table.

Estimation of Parameter Variability

Propellant Burning Rate, r_b. The variability of the propellant burn-

ing rate was assumed to be the same as the variability of the 12-pot increments for motors 260-SL-1 and 260-SL-2. As discussed earlier, the increment-to-increment variability was used because a certain amount of mixing of propellant occurs in successive pots as the motor is cast. Table I. 4 summarizes the burning rate data for both motors and shows the distribution of individual values and the distribution of the 12-pot averages. Because different target values were used for the nominals of these first 260-inch motors, the data was rationalized to provide coincidental average values.

The value of $\frac{\sigma}{\bar{x}}$, (12-pot increment to 12-pot increment) was found to be .0067 for Motor SL-1 and .0052 for Motor SL-2. The combined average of .00595 was selected for this study.

Lo	cation Station	Web Thickness (b) in	Propellant Burning rate (r _b)	Insulation* Thickness (t _.)	Insulation Erosion rate (e _r)
~					
<u>/1</u>	Igniter Boss	0	-	1.125	.003
Â	Fwd Head (Igniter Boss to Equator)	24.5	. 606	1.125	.003
3.	35'' Aft of Fwd Equator	86.7	. 606	1.125	. 003
<u>A</u>	120" Aft of Fwd Equator	87.5	. 590	. 1 1	.003
ß	274" Fwd of Aft Equator	85.0	.606	. 11	.005
	47" Fwd of Aft Equator	71.85	. 606	. 250	.005
${\mathbb A}$	Aft Equator	70.57	. 606	. 430	.006
8.	12.5 in. Aft of Aft Equator	70.57	.606	. 470	.00625
9.	Aft Head at 240'' Dia	52.5	. 606	. 750	.00725
10.	Aft Head at 220'' Dia	31.9	.606	1.10	.00825
11.	Aft Head at 200" Dia	15.5	.606	1.80	.0105
♪	Aft Head at Nozzle Joint	0	-	3.60	.0168

Table I. 3260/SIVB Design Parameters, Mean (Nominal)Values for Insulation Burn Thru Failure Mode.

* V44 Silica Asbestos

 \bigwedge These seven station have been used in the R||C analysis for this failure mode. (See Figure 1 of this report for motor schematic)

Propellant Burn Rate In/Sec for 260-SL-1Motor	Propellant Burn Rate In/Sec for 260-SL-2 Motor			
$\begin{array}{c} 260-SL-1Motor\\ 0.4369\\ 0.4391\\ 0.4426\\ 0.4426\\ 0.44401\\ 0.4446\\ 0.4427\\ 0.4443\\ 0.4447\\ 0.4461\\ 0.4443\\ 0.4477\\ 0.4460\\ 0.4477\\ 0.4460\\ 0.4477\\ 0.4459\\ 0.4440\end{array}$	$\begin{array}{c} 0.4408\\ 0.4435\\ 0.4423\\ 0.4395\\ 0.4377\\ 0.4426\\ 0.4425\\ 0.4425\\ 0.4422\\ 0.4388\\ 0.4417\\ 0.4431\\ 0.4388\\ 0.4365\\ 0.4402\\ 0.4450\end{array}$			
$\bar{x}_1 = 0.4438$	$\bar{x}_2 = 0.4410$			
$\sigma_1 = 0.00299 \text{ in/sec}$ $cv_1 = \frac{\sigma_1}{\bar{x}_1} = 0.0067$	$\sigma_2 = 0.00229 \text{ in/sec}$ $cv_2 = \frac{\sigma_2}{\bar{x}_2} = 0.0052$			
$c\dot{v}_{260/SIVB} \simeq \left(\frac{cv_1 + cv_2}{2}\right)^{**} = 0.00595$				

Table I.4 Distribution Data* for Design Parameter r Propellant Burning Rate.

- LSBR-BATCH MIX DATA from 260-SL-1 and 260-SL-2 motors, based on 12 pot averages.
- *** See comments in Appendix II, page II.2 which discuss the averaging of two coefficients of variation.

Propellant Web Thickness. The formula for web thickness for the cylindrical grain was assumed to be given by the formula

$$b = \frac{(D_c - D_b)}{2}$$

where

b = web thickness

 D_c = inside diameter of the insulated case

 $D_{\rm b}$ = bore diameter

A value of .002 was obtained for $\frac{\sigma_b}{\overline{x}}$ for the propellant web thickness, based on 260-SL-1 and 260-SL-2 motor data. From these data and nominar web thickness for the 260/S IV-B motor, the standard deviation is equal to .002(85) = 0.170.

Insulation Thickness. The standard deviation of insulation thickness was estimated from drawing tolerances. Assuming that the difference between the upper and lower limits equals six standard deviations, a value of 0.0033 in. was adopted for the cylindrical section (0.100/0.120 in. - thick stock) and 0.0167 in. for the varying thickness sections of the forward and aft ends.

Insulation Erosion Rate. The variability of the erosion rate was estimated from the maximum erosion distance observed at four circumferential locations for four longitudinal stations in a sample of 24 Polaris A3 motors as shown in Table I.5. The coefficient of variation ranged from .12026 at the nozzle base to .1890 at the equator, with a high value of .23914. The average of the eleven stations was .1631 which was chosen for use in the study since data for other motors indicated no consistent trend for higher $\frac{\sigma}{\overline{x}}$ variability at one station as opposed to another. The maximum value of the four circumferential locations was used rather than the average since the design nominal thickness was based on nominal maximum erosion rates and not on the average.

Table I. 6 shows the distribution of sidewall erosion data for 20 Minuteman Wing II motors. This data results in a considerably higher figure for the coefficient of variation, .51714 instead of .1631 for Polaris data.

		Total E	Total Erosion, Inches			
Station No.	Read 1	Read 2	Read 3	Read 4	X max from Read 1	
26 (Nozzle Base)	.17 .34 .36 .31 .33 .30 .42 .37 .39 .40 .36 .42 .36 .25 .29 .34 .24 .30 .40 .27 .20 .29	. 36 . 28 . 28 . 29 . 33 . 30 . 38 . 35 . 27 . 37 . 30 . 28 . 37 . 30 . 28 . 38 . 27 . 35 . 28 . 34 . 35 . 25 . 17 . 42 . 28 . 24 . 27	. 27 . 26 . 29 . 37 . 35 . 32 . 35 . 34 . 30 . 39 . 27 . 34 . 35 . 36 . 29 . 25 . 24 . 37 . 41 . 38 . 40 . 31 . 23 . 32	. 29 . 28 . 26 . 37 . 40 . 30 . 42 . 28 . 26 . 39 . 38 . 31 . 25 . 25 . 35 . 26 . 31 . 40 . 26 . 23 . 43 . 30 . 23 . 37	. 36 . 34 . 36 . 37 . 40 . 32 . 42 . 35 . 42 . 39 . 39 . 40 . 38 . 42 . 36 . 28 . 34 . 40 . 41 . 38 . 43 . 31 . 24 . 37	
27	. 22 . 37 . 33 . 27 . 30 . 34 . 31 . 41 . 32 . 41 . 34 . 35 . 43	. 40 . 33 . 29 . 33 . 29 . 27 . 29 . 34 . 28 . 30 . 32 . 33 . 37 . 29	. 27 . 35 . 28 . 36 . 39 . 33 . 25 . 23 . 29 . 40 . 28 . 32 . 35 . 40	. 30 . 28 . 36 . 36 . 33 . 43 . 35 . 29 . 37 . 35 . 31 . 25 . 25	. 40 . 37 . 33 . 36 . 39 . 33 . 43 . 35 . 41 . 40 . 41 . 34 . 37 . 43	

Table I.5Distribution, Polaris Insulation Erosion Data
from 24 Motors, Readings at Four Stations
90° Apart (V52 Silica Asbestos Insulation).

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I —

		Total Erosion, Inches				
Station No.	Read 1	Read 2	Read 3	Read 4	X max from Read $1 \longrightarrow 4$	
27 (Cont)	.30	. 36	. 32	. 37	. 37	
	. 24	. 29	. 26	. 26	. 29	
	. 27	. 32	. 22	. 40	.40	
	. 32	. 37	. 34	. 38	. 38	
	. 30	. 21	.38	. 29	.38	
	. 28	. 17	. 33	. 21	.33	
	. 42	.43	. 40	. 39	.43	
	. 26	. 25	. 29	. 26	. 29	
	. 18	. 26	. 28	. 21	.28	
	. 26	. 32	. 25	.30	32	
	. =0		. 23			
28	.17	.41	. 24	. 27	.41	
	. 28	. 33	. 36	. 25	. 36	
	. 34	. 29	. 27	. 25	. 34	
	. 26	.34	.30	. 35	. 35	
	. 37	. 32	. 37	. 36	. 37	
	. 27	. 25	.31	. 30	.30	
	. 34	. 25	. 21	. 36	.36	
	. 30	. 33	. 21	. 32	. 33	
	.38	. 28	. 27	. 27	.38	
	. 25	. 27	. 31	. 33	.33	
	. 33	. 28	.31	. 30	.33	
i	. 34	. 33	. 31	. 34	.34	
	. 33	.31	. 36	. 29	.36	
	. 39	. 24	. 38	. 29	. 39	
	. 26	. 35	. 32	. 37	. 37	
	. 23	. 28	. 21	. 25	. 28	
	. 24	. 28	. 22	. 36	.36	
	.31	. 33	.32	. 39	.39	
	.31	. 24	. 32	. 27	. 32	
	. 21	.12	. 28	.18	.28	
	. 42	.40	.39	. 39	.42	
	. 24	.24	. 27	. 24	.27	
	. 20	. 23	. 27	.14	.27	
	. 23	. 29	.18	. 24	. 29	
29	. 21	.41	.34	. 25	.41	
	. 32	. 30	. 28	. 23	. 32	

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ſ	Total Erosion, Inches				
Station No.	Read 1	Read 2	Read 3	Read 4	X max from Read 1—4
29 (Cont)	. 30 . 22 . 37 . 25 . 31 . 28 . 40 . 25 . 28 . 34 . 27 . 34 . 27 . 34 . 27 . 21 . 20 . 28 . 21 . 28 . 36 . 22 . 19 . 17	. 24 . 31 . 29 . 24 . 19 . 30 . 24 . 28 . 27 . 33 . 27 . 33 . 27 . 19 . 37 . 24 . 26 . 27 . 21 . 12 . 37 . 27 . 22 . 26	. 25 . 31 . 34 . 28 . 18 . 20 . 29 . 26 . 29 . 29 . 29 . 31 . 40 . 29 . 31 . 29 . 31 . 29 . 31 . 29 . 31 . 29 . 33 . 30 . 28 . 16	. 23 . 30 . 34 . 28 . 36 . 37 . 31 . 28 . 29 . 33 . 23 . 23 . 23 . 23 . 37 . 19 . 33 . 42 . 29 . 21 . 35 . 20 . 16 . 24	. 30 . 31 . 37 . 28 . 36 . 37 . 40 . 28 . 29 . 34 . 31 . 40 . 37 . 24 . 33 . 42 . 29 . 29 . 29 . 37 . 30 . 28 . 26
30	. 17 . 25 . 25 . 18 . 27 . 24 . 32 . 27 . 37 . 23 . 30 . 29 . 29 . 33 . 25 . 16	. 36 . 25 . 24 . 30 . 28 . 23 . 21 . 28 . 21 . 28 . 21 . 25 . 31 . 30 . 25 . 17 . 36 . 25	. 30 . 24 . 23 . 27 . 36 . 24 . 16 . 25 . 31 . 25 . 26 . 28 . 32 . 39 . 29 . 17	. 27 . 23 . 25 . 28 . 36 . 30 . 35 . 18 . 29 . 33 . 29 . 35 . 24 . 24 . 24 . 36 . 18	. 36 . 25 . 25 . 30 . 36 . 30 . 35 . 28 . 37 . 33 . 31 . 35 . 32 . 39 . 36 . 25

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Station No.	Total Erosion, Inches				
	Read 1	Read 2	Read 3	Read 4	X max from Read 1————————————————————————————————————
30 (Cont)	.11 .25 .19 .32 .36 .24 .18 .16	. 24 . 24 . 19 . 15 . 34 . 24 . 24 . 26	.38 .27 .35 .29 .29 .40 .24 .18	.32 .38 .36 .21 .42 .19 .18 .23	. 38 . 38 . 36 . 32 . 42 . 40 . 24 . 26
31	. 16 . 23 . 20 . 16 . 27 . 26 . 29 . 25 . 32 . 18 . 30 . 26 . 29 . 30 . 26 . 15 . 14 . 20 . 19 . 29 . 29 . 29 . 20 . 17 . 11	. 31 . 20 . 24 . 28 . 28 . 20 . 23 . 28 . 19 . 28 . 31 . 29 . 25 . 15 . 33 . 24 . 21 . 23 . 15 . 20 . 32 . 26 . 27 . 27	. 27 . 23 . 22 . 24 . 36 . 25 . 16 . 25 . 31 . 23 . 25 . 31 . 23 . 25 . 31 . 25 . 36 . 36 . 29 . 19 . 37 . 25 . 34 . 31 . 25 . 34 . 31 . 25 . 34 . 31 . 25 . 39 . 24 . 39 . 24	. 24 . 27 . 23 . 27 . 33 . 29 . 38 . 20 . 28 . 31 . 25 . 30 . 25 . 25 . 31 . 19 . 29 . 38 . 35 . 18 . 37 . 21 . 18 . 24	. 31 . 27 . 24 . 28 . 36 . 29 . 38 . 28 . 32 . 31 . 31 . 30 . 36 . 36 . 33 . 24 . 37 . 38 . 35 . 31 . 37 . 39 . 27 . 27
32	.17 .25 .18 .12	. 28 . 14 . 20 . 24	. 24 . 27 . 22 . 24	.20 .29 .21 .25	. 28 . 29 . 22 . 25

Table I.5 Cont

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	.	Total Erosion, Inches				
Station No.	Read 1	Read 2	Read 3	Read 4	X max from Read 1	
32 (Cont)	. 27	. 25	. 31	. 27	. 31	
	. 19	. 22	. 23	. 27	.27	
	. 29	. 28	.17	. 31	. 31	
	. 26	. 27	. 24	. 16	. 27	
	. 25	. 17	.30	. 30	. 30	
	. 16	. 26	. 19	. 26	. 26	
	. 27	. 29	. 20	. 21	. 29	
	. 24	. 27	. 24	. 25	. 27	
	. 27	. 29	. 35	. 22	. 35	
	. 29	. 15	. 32	. 22	. 32	
	. 28	. 28	. 25	. 36	. 36	
	. 21	. 21	. 21	. 20	. 21	
	.17	. 13	. 30	. 27	.30	
	. 20	. 23	. 25	. 34	. 34	
	. 19	. 16	. 29	. 31	. 31	
	. 25	. 17	. 30	. 16	. 30	
	. 19	. 29	. 25	. 25	. 29	
	. 20	. 23	. 32	. 20	. 32	
	. 15	. 23	. 20	.13	. 23	
	.12	. 25	. 20	. 22	.25	
33	. 17	. 26	. 21	. 18	. 26	
	. 22	. 15	. 23	. 27	. 27	
	. 20	.16	. 24	.17	. 24	
	.11	. 21	. 22	. 24	. 24	
	. 25	. 16	. 24	. 23	. 25	
	. 23	. 21	. 20	. 21	. 23	
	. 28	. 29	.17	. 22	. 29	
	. 29	. 23	. 25	.18	. 29	
	.13	.17	. 27	. 29	. 29	
	.12	. 27	.16	. 21	. 27	
	. 24	. 20	.19	.13	. 24	
	. 26	. 27	. 24	. 24	. 27	
	. 22	. 27	.32	. 23	. 32	
	. 24	.13	. 28	. 23	. 28	
	. 25	. 27	.21	. 37	. 37	
	. 24	. 19	.16	.16	. 24	
	. 15	.09	. 25	. 28	. 28	
	. 21	. 25	. 23	. 45	. 45	

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	Total Erosion, Inches					
Station No.	Read 1	Read 2	Read 3	Read 4	X max from Read 1	
33 (Cont)	.23 .25 .15 .14 .10 .11	. 13 . 16 . 22 . 19 . 16 . 25	. 26 . 22 . 24 . 31 . 09 . 16	. 25 . 15 . 18 . 15 . 12 . 15	. 26 . 25 . 24 . 31 . 16 . 25	
34	. 12 . 20 . 21 . 15 . 18 . 19 . 25 . 25 . 11 . 07 . 21 . 21 . 17 . 22 . 13 . 21 . 16 . 22 . 19 . 25 . 06 . 12 . 10 . 12	. 21 . 16 . 19 . 18 . 17 . 21 . 25 . 23 . 14 . 28 . 21 . 28 . 24 . 14 . 24 . 21 . 09 . 32 . 12 . 12 . 12 . 12 . 18 . 14 . 12 . 24	. 13 . 22 . 22 . 23 . 18 . 21 . 16 . 21 . 23 . 16 . 19 . 22 . 39 . 26 . 16 . 15 . 23 . 24 . 19 . 20 . 21 . 29 . 05 . 13	20 19 18 24 22 16 21 17 25 17 11 27 25 25 26 17 25 26 17 25 39 24 15 16 18 13 18	. 21 . 22 . 22 . 24 . 22 . 21 . 25 . 25 . 25 . 25 . 25 . 28 . 21 . 28 . 39 . 26 . 26 . 21 . 25 . 39 . 26 . 21 . 25 . 39 . 24 . 25 . 21 . 25 . 21 . 25 . 21 . 28 . 21 . 28 . 21 . 26 . 26 . 26 . 26 . 21 . 25 . 25 . 25 . 25 . 25 . 25 . 25 . 25	
35	.11 .15 .20 .13 .18 .13	. 22 . 14 . 17 . 17 . 13 . 13	. 11 . 20 . 21 . 21 . 13 . 15	. 20 . 13 . 15 . 23 . 21 . 17	. 22 . 20 . 21 . 23 . 21 . 17	

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<u> </u>	Total Erosion, Inches					
Station No.	Read 1	Read 2	Read 3	Read 4	X max from Read 1	
35 (Cont)	. 21	. 19	. 17	. 18	. 21	
	.18	. 20	.17	. 20	. 20	
	.14	. 12	. 21	. 19	. 21	
	.08	. 21	. 15	. 16	. 21	
	. 23	. 19	. 16	. 15	. 23	
	.16	. 20	. 16	. 18	. 20	
	.18	. 19	. 24	. 18	. 24	
	. 20	. 12	. 24	. 18	. 24	
	.18	. 19.	.12	. 20	. 20	
	.13	. 18	. 15	. 16	.18	
	. 17	. 10	.15	. 21	.21	
	. 19	. 34	.17	. 35	. 35	
	. 15	.11	. 15	. 15	. 15	
	. 17	. 19	.14	. 16	. 19	
	. 06	.13	.07	.14	.14	
	.13	.11	. 37	. 15	. 37	
	. 13	. 08	.08	.15	. 15	
	.18	. 23	.09	.16	. 23	
36 (Equator)	. 10	. 20	11	16	20	
(.12	. 11	. 20	.15	20	
	. 15	.17	. 15	. 08	17	
	.12	. 12	.17	.21	. 21	
	. 15	. 10	. 08	. 20	. 20	
	.12	. 12	.13	.17	. 17	
	. 15	. 20	.14	. 16	. 20	
	.16	.17	.18	.18	.18	
	.10	.11	.14	.15	. 15	
	.06	. 23	.16	.19	. 23	
	. 23	.18	.13	.16	. 23	
	.17	. 21	.14	.12	. 21	
	.17	. 15	. 23	.20	. 23	
	.14	.12	. 21	. 20	.21	
	.10	.18	. 09	. 15	.18	
	.15	.14	.11	. 19	.19	
	.19	. 15	. 15	. 14	.19	
	.17	. 27	.16	. 32	. 32	
	. 09	. 06	.13	. 14	.14	
	.13	. 22	. 16	. 16	. 22	

Station No.	Total Erosion, Inches				
	Read 1	Read 2	Read 3	Read 4	X max from Read 1————————————————————————————————————
36 (Equator) (Cont)	.09 .15 .16 .16	.08 .14 .08 .12	.10 .22 .13 .08	. 15 . 11 . 17 . 15	.15 .22 .17 .16

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Maximum Sidewall [*] Erosion, Inches	Number of Samples
0.05 - 0.06	2
	1
. 010 011	1
. 011 012	3
.012013	1
.015016	5
.017018	1
. 030 031	3
	Total 20
Calculations for MM Wing II day	ta:
$\bar{x} = .01465$	
σ = .00738	
σ cv = = .51714	

Table I.6Distribution of Sidewall Erosion Data 20 MinutemanWing II Motors (V44 Silica Asbestos).

 $cv = \frac{1}{x}$

^{*} These data are maximum values obtained in the cylindrical region of the motor, from a population sample of 20 motors. They were used to compute σ and $\frac{\sigma}{\mathbf{x}}$ for the cylindrical region of the 260/SIVB motor (stations 4 and 5).

The validity of using this data is questionable because: (1) it is more difficult to measure sidewall than aft head erosion, (2) it was derived from motors using a bi-propellant grain that might have had more variability in burning rate than a mono-propellant grain, (3) sidewall erosion is mainly a function of tailoff time, which is usually more variable than the web burning time that primarily governs the fore and aft head insulation erosion rates.

These factors make the applicability of the .51714 value doubtful for $\frac{\sigma}{x}$ and indicate that the variability of the V-44 erosion rate in sidewall locations should be given additional study. (However, for purposes of preliminary analysis this value was used for stations 4 and 5 in the motor.)

Failure Mode 3. Failure of the Forward Skirt Forging in Combined Compression, Shear, and Bending Loads.

Requirement versus Capability Relationship. When combined loads are present, as in the case of the forward skirt which is subjected to combined compressive, shear, and bending forces, it is the opinion of AGC that the correct estimation of failure cannot be obtained by separately comparing the requirement and capability of each type of loading and then combining the total failure. The non-validity of such an approach, they feel, is due to the fact that the combination of different types of loads interact to reduce the material capabilities to levels below that which they exhibit for single types of loads. As a consequence, stress engineers have derived empirical relationships to account for the amount of interaction between various types of combined loads. In these relationships, the ratios of the requirement of each type of load to their corresponding allowables are combined in an interaction formula such that if the sum of the ratios is greater than unity, failure is assumed to occur. The transfer function used for the combined compression, shear and bending in the skirts of solid rocket motors is

$$R_{c} + (R_{b}^{3} + R_{s}^{3})^{1/3}$$
 (6)

where

- R_s = the ratio of transverse shear load requirement to material capability
- R = the ratio of pure bending load requirement to material capability

This function can be used in the $\mathbb{R} \| \mathbb{C}$ analysis to describe the requirement, or more specifically the requirement ratio. The capability distribution is assumed to be the single value of 1.000, with no variability.

Expanding the interaction formula to account for the geometry of the 260/S IV-B vehicle, we obtain:

Requirement Ratio =
$$\frac{L_c}{2\pi R_i t_s K_c E_s} + \sqrt{\frac{L_b}{\pi R_i^2 t_s K_b E_s}}^3 + \left(\frac{L_s}{\pi R_i t_s K_s E_s}\right)^3$$

These parameters are defined in Table I.7, and a summary of the mean values and standard deviations are also given.

Engineering Data for Failure Mode 3. Failure of the forward motor skirt forging in combined compression, shear and bending, is discussed and the rationale and data used in this study follow.

L_c, L_b, L_s; Axial Compression, Pure Bending, Transverse Shear Loads.

The axial compression, pure bending, and transverse shear loads are single limit values with zero variability.

Assumptions: The loads used in this analysis were specified by the launch vehicle systems designer, Douglas Missile and Space Systems Division. In actuality, the maximum axial compression load occurred at 116 sec while the maximum shear and bending moment occurred at 59 sec. However, lacking data for shear and bending at 116 sec, the 59 sec values were used instead since this produced a conservative estimate. The values used are maximum requirements based in part on a 95% probability quasisteady state winds, plus associated wind shears, wind speed changes and gusts. In addition, the TVC portion of the loads also reflected a root-sumsquare combination of the maximum expected variability of thrust misalignment, motor thrust, and vehicle weight. The probability of failure calculated from these loads is therefore a maximum one in the same sense that the hoop stress failure rate was evaluated at the maximum temperature requirement. To obtain the skirt failure probability for normal use would require the vehicle designer to furnish variability estimates for these loads.

	Nominal Value X	Standard Deviation Units O	Coefficient of Variation <u>T</u>	Source of Data
Maximum Axial Compressive Load, L _c , lb.	2,200,000	0	0	Figure 4-17, <u>Saturn IB Improvement</u> <u>Study</u> , Douglas Missile & Space Systems Div., 3/30/66 (Douglas Rpt SM-51896, Vol. II) Contract NAS8-20242.
Maximum Pure Bending Load, L _b , inlb.	94, 000, 000	0	0	Fig. 4-15, Same report as above.
Maximum Transverse Shear Load, L _s , 1b.	60,000	0	0	Fig. 4-15, Same report as above .
Skirt Radius (interior), R _i , in.	129, 903	.0208	.00016	\overline{X} : Design nominal σ : Assuming design tolerance = 6 sigma.
Modulus of Elasticity, E _s , psi	27,500,000	54, 725	.00199	 X: Design nominal σ: Est. from plate-to-plate variability of material composition.
Ratio of Axial Compression Strength to Mod. of Elasticity, K _c	.0036	.000685	.190	X, σ: Development of design curves for stability of thin pressurized and unpres- surized circular cylinders, Report AZS- 27.275, 3/8/59, Convair Astronautics Div., General Dynamics Corp.
Ratio of Pure Bending Strength to Mod. of Elasticity, K _b	.0050	.000968	.193	Χ,σ: """.
Ratio of Transverse Shear Strength to Mod. of Elasticity, K _s	.00288	.000334	.116	Χ,σ: """.
Skirt Thickness, t _s , in.	. 728	. 0093	.0128	X: Design Nominal σ : Assuming design tolerance = 6 sigma.

Table I.7. Summary of Parameter Average and Standard Deviations.

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 R_{i} , Skirt Radius Distribution

- 1. The tolerance on the interior skirt radius = 0.125
- 2. Assuming the tolerance equals 6σ , $\sigma = 0.0208$

$$3. \ \frac{\sigma}{\bar{\mathbf{x}}} = \frac{0.0208}{129.903} = 0.00016$$

4. The population is assumed to be normally distributed.

Assumptions: Engineering judgment supports the statement that such tolerances could be held in production motors.

Experience with similar manufacturing parameters in smaller motors indicate a normal distribution.

 t_s , Skirt Thickness Distribution

- 1. The tolerance on the skirt thickness is 0.056 inches.
- 2. Assuming the tolerance equals 6σ , $\sigma = 0.0093$

3.
$$\frac{\sigma}{\overline{x}} = \frac{0.0093}{0.728} = 0.0128$$

4. The population is assumed to be normally distributed.

Assumptions: Engineering judgment supports the statement that such tolerances could be held in production motors.

Experience with similar manufacturing parameters in smaller motors indicate a normal distribution.

E_s, Modulus of Elasticity Distribution

Table I.8 lists the data for E_s . Twenty-four heat number values are shown.

Assumptions: No data were available for the plate-to-plate variability of modulus of elasticity. However, the chemical composition data available for each plate made possible an estimate of the modulus of elasticity.

Table I.8. E_s, Modulus of Elasticity Distribution

Heat No.	Estimated Modulus of Elasticity lb/in ² x 10 ⁻⁶
50265	29,138
50264	29.087
50338	29.138
50210	29.189
24997	29.248
24999	29.138
3951218A	29.036
25126	29.146
3951215	29.240
3960819	29.138
3920781	29.129
2500	29.189
392077	29.078
25064	29.104
3960832	29.104
25098	29.180
25007	29.163
24998	29.129
3960829	29.036
50187	29.180
3960870	29.061
25050	29.036
24996	29.155
50234	29.138
	$\bar{x} = 29.132 \times 10^6$
	$\sigma = 0.058 \times 10^6$
cv	$= \frac{\sigma}{\overline{\mathbf{x}}} = 0.00199$

This was done by obtaining handbook values for modulus of elasticity of each of the ingredients and obtaining a weighted average estimate of the modulus of each plate. While the true modulus of elasticity is probably affected by other factors than composition, this method is felt to be sufficiently accurate for variability estimating purposes. The average value obtained by this method was 29, 132, 000 which is within 5% of the design nominal value of 27, 500, 000.

The assumptions of a normal distribution and the constancy of the coefficient of variation apply to this parameter.

Ratio of Strengths to Modulus of Elasticity Distribution. The variability of axial compressive strength, pure bending strength and transverse shear strength was obtained from a study performed by Convair Astronautics Division, wherein data from unstiffened circular cylinders in compression, bending and shear from numerous studies were analyzed and summarized. The results were calculated for various radius/thickness relationships as well as length/radius relationships. In addition to showing average values, results were portrayed for 90% probability with 95% confidence levels which made possible direct estimation of standard deviation. The results are summarized as follows:

Assumptions:

Radius/Thicknuss = 129.903/728 = 180

Length/Radius = 30/129.903 = 0.23

	Ratio of S Modulus of	trength to Elasticity	(No. of σ between x & 90% prob. 95%	Standard	of varia- tion
Function	Avg. Value	90%Prob. 95%C.L.	C.L. based on sample size)	Deviation σ	σ x
Axial Compressive Strength, K	.0036	. 0026	1.459	.000685	.190
Pure Bending Strength, K _b	.0050	.0035	1.548	.000968	. 193
Transverse Shear (1.25 x torsion), K _s	.00288	.00238	1.497	.000334	.116

Coef.

The data in the Convair study were shown only in summary form and it was assumed that populations are normally distributed. It is interesting to note that coefficients of variation obtained, which ranged from .116 to .193 are considerably larger than the .025 obtained for the tensile strength of the plates maraged in 260-SL-1 and 260-SL-2. This is to be expected, since the initiation of buckling failures is more susceptible to local discontinuities and contour deviation than is the case of simple tensile tests. As such, this data can be considered to include the bending/discontinuity factor that was evaluated separately in the hoop stress failure mode.

Failure Mode 4. Data, Failure of Forward Head Circumferential Weld in Meridional Stress (Location: Weld Between Igniter Boss Forging and Upper Gore, 35" from Center Line)*

Capability Distribution:

90% of time weld strength is

$$P_{mw} = \frac{\frac{2S_{umw} t_c (K_{be})}{R_o}}{R_o}$$
(8)

where

P_mw = Ultimate burst pressure of machine welds, psi, S_umw # Ultimate tensile strength of machine welds, psi, t_c = Plate thickness, in., R_o = Radius (to exterior surface), in., K_{be} = Bending/discontinuity strength reduction factor, ND.

10% of time weld strength is reduced due to the necessity of making local hand weld repairs. The same formula applies except S_{uhw} is substituted for S_{umw} .

S_{ubw} = Ultimate tensile strength of hand welds, psi.

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Motor Station 3

As shown in Table I. 9, the same values for average and standard deviations for cylindrical welds as was used for FM 1 apply to the forward head welds with the exception of plate thickness and radius.

Requirement Distribution. The requirement distribution of maximum chamber pressure for this failure mode is the same as for the failure of longitudinal welds^{*} in hoop stress. Tables I.10 and I.11 support the plate thickness and exterior radius variabilities.

Failure Mode 5. ** Data, Rupture of the Nozzle Joint Bolts

Failure of nozzle joint bolts in tension due to combined loads of pressure ejection, and TVC bending moments.

Requirement Distribution. The requirement distribution is the sum of three distributions: the tension due to pretorqueing, a portion of the ejection load due to internal and external pressure and inertia, and the added tension effect due to the thrust vector control moment.

The portion of the total ejection load that is felt as tension in the bolt can be approximated by the ratio of the cross sectional area of a bolt to the area of flange per bolt. Since this results in a load that is less than .1% of the pretorque load for the 260/S IV-B design, the ejection load effects were not considered in this failure mode. The resulting requirement transfer function is then that the Bolt Tensile Load = Pretorque Load + Thrust Vector Control Load.

The thrust vector control load results from the side force load of the liquid injection TVC system. It acts at right angles to the longitudinal axis at the TVC ports in the exit cone and results in a bending stress at the nozzle joint. The basic formula for the load/bolt at the joint is:

$$P_{b} = \frac{(F_{max}) (\tan \alpha) (d)}{\frac{n}{2} \left(\frac{D_{j}}{2}\right)}$$
(9)

* Ref. Data Package II-1 and equation (2) of this Appendix.

^{**} Ref. 4, Data Package II-4.

		<u>.</u>		
Parameter	Parameter Average Value, X	Parameter Standard Deviation in Units, σ	$\begin{array}{c} \text{Coefficient} \\ \text{of} \\ \text{Variation} \\ \frac{\sigma}{\overline{X}} \end{array}$	Source of Values
Machine Weld UTS, S _{umw} , psi	232 , 000	2,516	.0109	\overline{X} , σ : 260-SL-1 and 260-SL-2 Maraged weld coupons (see Data Package II-1, Table 2).
Hand Weld UTS, S _{uhw} , psi	199, 333	8,641	.0433	Χ ,σ: """ .
Plate Thick- ness, t in. c	. 428	.0108	.0250	\overline{X} : Design nominal. σ : 18 plates from 18 heat used in 260- SL-1 and SL-2
Radius (exter- ior), R _o , in.	130.428	.0456	.00035	\overline{X} : Design nominal. σ : Tolerance on radi- us r plate thickness variable
Bending/Dis- continuity Reduction Factor, K be (ND)	. 9585	.00693	. 72	X, 0: Est. from 260-SL-1 and SL-2, Hydrotest strain gauge data. See Data Package II-1 Table 5.

Table I.9. Summary of Parameter Averages and Standard Deviations, FM-4.

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Table I.10. Plate Thickness Variability

		·····	
Heat No	Plate Thickness Average of 15 Readings	Within-Plate Standard Deviation	Used In Motor Number
IIEat NO.	Readings	Deviation	Motor Number
3920778-B	.414	.0089	260-SL-1
25000-6A	.429	.0050	250-SL-1
25064-1	. 434	.0069	260-SL-1
25050-1	. 435	.0023	260-SL-1
3960870-C	436	.0023	260-SL-2
50187-2T	443	0032	260-51-2
50101-21	. 115	.0052	200-01-2
24996-1	. 446	.0059	260-SL-2
50187-2B	.441	.0065	260-SL-2
t _c avg. ≖	. 434		
⁰ plate to = plate	.0095 σ _ν	vithin = .0051 (avg plate	g.)
σ = Est	imated Total V (any location)	ariability = $\sqrt{\sigma_{\rm F}^2}$	$r^2 + \sigma^2_{wp}$
		$\sigma = .0108$	3
	CV	= σ	
		$\frac{-1}{-1} = .0250$	υ
		x	

Table I.11. Estimation of Exterior Radius Variability.

(1)	Tolerance on interior radius		=	. 26
(2)	Assuming tolerance = 6σ ,	σ	=	.0433
(3)	Variability of plate Table 1.10	r t	=	.0108
(4)	Combining plate and radius variability by RSS,	τ	=	.0456
(5)	Coefficient of variation			
	$\frac{\sigma}{\frac{\pi}{x}} = \frac{.0456}{130.428}$		=	.00035

where:

 P_{L} load per bolt, lb. = maximum longitudinal thrust, 1b. F_{max} = TVC side force deflection angle, degrees. α = \mathbf{d} longitudinal distance between TVC port and joint, in. = number of bolts = n diameter at nozzle joint, in. D_i =

However, the maximum longitudinal thrust can be expressed in terms of maximum chamber pressure which is the requirement parameter for other failure modes. The relationship is:

$$F_{max} = P_{sn} A_{ti} C_{f vac} K_{f} + (P_{e} - P_{a}) A_{ti}$$
 (10)

where:

P_{sn} = chamber stagnation pressure, psi. Р = atmospheric pressure, psi. initial throat area, in² Ati $C_{f vac} =$ nozzle thrust coefficient in vacuum, (ND) ĸ nozzle efficiency factor, (ND) = e nozzle expansion ratio, (ND) = Pe z nozzle exit pressure, psi

Constant values for α , $C_{f vac}$, K_{f} , and ϵ , are used in the following formula for the bolt tensile load:

$$Q_{BT} = K_{p}F_{by} + \frac{\left(\tan \alpha\right)(d)(.8538 P_{cmax})(A_{ti})\left(1.66642 - \frac{11.0 P_{a}}{.8538 P_{cmax}}\right)}{\left(\frac{n}{2}\right)\left(\frac{D_{j}}{2}\right)}$$

(11)

where:

Q _{BT}	=	total tensile load per bolt, lb.
к р	=	fraction of bolt minimum yield strength to which bolt is pretorqued, $\%/100$.
F _{by}	=	minimum tensile load per bolt, 1b.
α	z	3.6° (TVC side force deflection angle)
d	=	longitudinal distance between TVC port and joint, in.
P _{cmax}	=	maximum chamber pressure, psi
Pa	=	atmosphere pressure, psi
A _{ti}	=	initial nozzle throat area, in ²
n	z	number of bolts, 220
D _j	=	diameter at nozzle joint, in.

<u>Capability Distribution</u>. The load capability parameter, P_y is based on the tensile strength of the nozzle attachment bolts. The nominal value for bolt load capability is estimated at 15% greater than the specified minimum of 213, 310 lbs per bolt, or 245, 307 lb/bolt. The coefficient of variation is .0081 as shown in Table I. 12 thus $\sigma = (cv) P_y = 1987$ psi.

A summary of the averages and standard deviations characterizing these parameters, is presented in Table I.12. Table I.13 shows distribution data and rationale for the parameters shown in Table I.9.

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Symbol	Parameter	Nominal Value x	Standard Deviation Units 	Coefficient of Variation σ/\bar{x}	Source of Data
K p	Pretorque fraction of minimum yield strength, $\frac{4}{100}$. 60	. 077	. 128	 x: design nominal o: measured variability for tensile strength for six 1¹/₄ -india EWB bolts all pretorqued to same 1000 ft. lb. load. See Table 1.13
Fby	Bolt minimum yield strength, lb/bolt	213,310	0	0	$\overline{\mathbf{x}}$: design nominal σ : included in pretorque data
d	Distance between TVC port and nozzle joint, in.	178.84	0	0	$\overline{\mathbf{x}}$: design nominal σ : no data available
P cmax	Maximum chamber pressure, psi	-	-	-	A parameter expressed as a function of other parameters. (See equation $(I.2)$)
Pa	Atmospheric pressure, psi	14.696	. 0735	. 0049	$\overline{\mathbf{x}}$ and σ : Handbook of Geophysics for Air Force Design. Data is for sea level. 30°N latitude.
A _{ti}	Initial nozzle 2 throat area, in	6235	0	0	 x: design, nominal σ: negligible (one sigma equals .045%, assuming dia. dwg. tolerance equal to 6 sigma (see Table I.13)
n	Number of bolts	220	-	-	$\overline{\mathbf{x}}$: design nominal
D _j	Diameter of nozzle joint, in.	180	0	0	 x: design nominal σ: negligible (.001% assuming dwg. tolerance equal to 6 sigma. See Table I.13
Р у	Bolt Load Capability lbs/bolt.	245,307	1987	.0081	

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Table I.13. Distribution Data for FM-5.

Pretorque Distribution

Pretorque design nominal is set at 60% of minimum bolt tensile strength; the pretorque variability is estimated from 6 tests performed on 1.25 in. dia. EWB bolts similar to LWB used in 260-in. /SIVB design were torqued to 1000 ft-lbs (lubricated). The imposed tensile loads were measured as follows:

Test	<u>Tensile load, psi</u>
1	124,000
2	133,000
3	147,000
4	153,000
5	167,000
6	174,000
	Avg. 149,667
	σ = 19,210
	$\mathbf{cv} = \frac{\sigma}{\overline{\mathbf{x}}} = 0.128$

<u>Assumptions</u>: It was assumed that the $\frac{\sigma}{x}$ observed in these tests would apply to 260/SIVB bolts when torqued to 60% of their minimum yield. It was also assumed that the pretorque variability represented both the variability of the inherent tensile strength and the variability resulting from pretorquing itself.

Initial Throat Area

This parameter is assumed to be normally distributed with the tolerance on initial throat area equal to 6 standard deviations. The 0.060 inches total tolerance on the 89.1 inch diameter becomes the equivalent of 0.045% for one sigma of initial throat area. This small magnitude can be neglected.

TABLE L13 continued

Diameter of Nozzle Joint

This parameter is assumed to be normally distributed with the tolerance on the joint diameter equal to 6 standard deviations. Thus, the 0.015 inches total tolerance on the 180 in. diameter of the bolt circle becomes 0.00139%. This small magnitude can be neglected.

Summary of Bolt Tensile Strength Data

Only summarized data were available. The following were obtained from AGC reports, reflecting strength measured in Aerojet acceptance tests:

Type of Bolt	Material	Average Ultimate Tensile Strength, psi	Standard Deviation psi	Coefficients of Variation σ/\bar{x}
-	8735	190,950	1667	0.00873
-	8740	181,600	1718	0.00946
NAS626 H4	-	214,900	1310	0.00610
			cv Avg	.= 0.00810

<u>Assumptions</u>: The average of the coefficients of variation, σ/\bar{x} was used as the best estimate of the population coefficient of variation. The assumption is also made that yield strength σ/\bar{x} is the same as ultimate tensile strength σ/\bar{x} .

Failure Mode 6. Data, Separation of Motor Chamber and Nozzle Flange

1. Relationship of Requirement and Capability.

The longitudinal compression of the flange due to pretorque can be described by the formula:

$$\epsilon_{c} = \frac{Q_{pt}}{A_{F} E_{F}}$$

where:

 ϵ_{c} = fractional compression (ND) Q_{pt} = pretorque load per bolt, lb/bolt A_{F} = `area of flange/bolt, in.² E_{F} = modulus of elasticity of flange, psi.

Similarly, the longitudinal elongation of the flange due to the ejection load can be described by the formula:

$$\epsilon_{e} = \frac{Q_{ej}}{A_{F} E_{F}}$$

where:

*

€e

= fractional elongation (ND)

Q = ejection load per bolt due to internal pressure, external pressure, and inertia, lb/bolt

The joint will separate when the elongation due to ejection load exceeds the compression due to pretorque. This occurs when: $\epsilon_{c} = \epsilon_{c}$ or:

Ref. AGC Data Package II-4,5

$$\frac{Q_{\text{pt}}}{A_{\text{F}}E_{\text{F}}} = \frac{Q_{\text{ej}}}{A_{\text{F}}E_{\text{F}}}$$

This reduces to $Q_{pt} = Q_{ej}$ at time of failure. Thus the ejection load becomes the requirement and the pretorque load the capability.

Requirement distribution. The ejection load on the nozzle in flight is made up of three components:

a. The force on the entrance to the nozzle minus the reacting forces in the exit cone:

$$P_{180}A_{180} (1 + \gamma M_{180}^2) - P_e A_{ei} (1 + \gamma M_e^2)$$

where:

P 180	=	pressure at 180" joint diameter, psi,
A ₁₈₀	=	area at 180" joint diameter, in ² ,
γ	=	ratio of propellant specific heats (ND),
^M 180	=	Mach number of gas stream at joint diameter, (ND),
Pe	=	gas pressure at exit diameter, psi,
A _{ei}	=	initial exit area, in ² ,
M _e	=	Mach number at exit plane, (ND).

b. The drag on the exterior surface of the nozzle due to ambient air pressure:

$$P_{a} (A_{ei} - A_{180})$$

where:

 $P_a = atmospheric air pressure.$

c. The inertial load on the nozzle:

$$\frac{\texttt{W}_{ni} \texttt{W}_{veh}}{\texttt{F}}$$

where:

W_ni = initial weight of the nozzle, lb, W_veh = total weight of the launch vehicle, lb, F = thrust, lb.

As in the case of the failure mode due to bolt pretorque and TVC loads the thrust term has been replaced by chamber pressure, throat area and other parameters. The final formula for the ejection load per bolt is then:

$$R_{6} = Q_{ej} = \left[\left(.9981 P_{cmax} A_{180} (1 + \gamma M_{180}^{2}) - .014092 P_{cmax} A_{ei} (1 + \gamma M_{e}^{2}) \right) + \left(\frac{W_{ni} (W_{p} + W_{vi})}{(.8538P_{cmax} A_{ti} \left(1.66642 - \frac{11P_{a}}{.8538P_{cmax}} \right) \right) \right] \frac{1}{n}$$
(12)

where:

$$Q_{ej}$$
 = ejection load ber bolt, lb/bolt,
 P_{max} = maximum chamber pressure, psi (see Equation II. 22,
Appendix II),
 γ = ratio of propellant specific heats, (ND),
 M_{180} = Mach number of gas streem at joint diameter, (ND),
 M_e = Mach number of gas stream at exit plane, (ND),
 P_a = atmospheric pressure, psi,

A _{ei}	=	initial exit area, in. ² ,
A ₁₈₀	=	area at nozzle joint, in. ² ,
W _{ni}	=	initial weight of nozzle, 1b,
w _p	=	propellant weight (first stage), 1b,
W_{vi}	=	initial weight of launch vehicle (less first stage propellant), lb,
A _{ti}	Ξ	initial throat area, in. ² ,
n	=	number of bolts.

A preliminary evaluation indicates that load Q or the requirement, will be at a maximum immediately after ignition.

Capability Distribution. The formula for the pretorque load/bolt is:

$$C_6 = Q_{pt} = K_p F_{by}$$
(13)

where:

Q_{pt} = pretorque load on bolt, lb, K_p = fraction of bolt minimum yield strength to which bolt is pretorqued, %/100, F_{bv} = bolt minimum load capability based on yield strength, lb.

Table I. 14 presents the FM 6 parameters giving estimates of the means, standard deviations, coefficient of variations, and data sources. Table I. 15 summarizes the rationale for those parameters assumed to have $\sigma = 0$.

Table I. 14. Summary of Parameter Data FM-6.

_	Nominal Value X	Standard Deviation	Coefficient of Variation	Surger of Data
Parameter				Source of Data
Ratio of propellant specific heats, γ (ND)	1.2	0	0	x: design nominal 0: is negligible .00167% per Report 0815-81F "Survey of Existing Solid Propellant Ballistic Data", Contract NAS8-11033, 4-29-64.
Mach number at joint diameter, M ₁₈₀ (ND)	0.0576	0	0	 design nominal regligible. (A one sigma change in A_{ti} produces only .04% change in M₁₈₀. See Table II).
Mach number at exit plane, M _e (ND)	3.205	0	0	 design norminal negligible (one sigma equals . 0039% based on . 04% for A i and . 01796% for A i. See Table II0.
Atmospheric Pressure, psi P a	14.696	. 0735	. 0049	x:and 𝔄. Handbook of Physics for Air Force Design. Data is for sea level, 20°N latitude.
Initial Exit Area, A _{ei} in ²	56,116	0	0	 x: design nominal c: negligible (one sigma equals . 01796% based on assumption that exit dia tolerance is 6 sigma. See Table II).
Area at Nozzle Joint, A ₁₈₀ in ²	25,447	0	0	 x: design nominal c: negligible (one sigma equals .00343% based on assumption that joint dia. tolerance equals 6 sigma. See Table II).
Initial Nozzle Weight, W lb ni	58, 428	0	. 0134	$\overline{\mathbf{x}}$: design nominal σ : same source as for sigma of γ .
Propellant Weight, 3 Wp lb (1st Stage)	,400,000	6120	. 18	See Data Package II-1, AGC
Initial Launch Vehicle Weight, W _{vi} lb (Less First Stage Propellant)	726,466	4085	. 70	 x: design nominal c: Saturn 1B Improvement Study, Douglas Missile and Space Systems Division. (Douglas Report SM-51896 Vol. II, 3-30-66).
Initial Throat Area, A _{ti} in ²	6,235	0	0	 x: design nominal o: negligible (sigma equals .045% based on assumption that dwg. tolerance equals 6 sigma. See Table II).
Number of Bolts, n	220	-	-	
Fraction of Bolt Min. Yield Strength to Which Bolt is pretorqued, K _p	0.6	. 077	. 1283	

Symbol	Requirement Formula Parameter	Related Primary Parameter	Equation for Requirement Formula Parameter	Variability of Related Parameters	Corresponding Formula Parameter Variability	Assumption
м ₁₈₀	Mach number at throat diameter	^A ti	Complex	.045% (σA _{ti})	. 04%	Negligible effect on requirement variability
M _e	Mach number at exit diameter	A _{ti} and A _{ei}	Complex	.045% (ơA _{ei}) .01796% (ơA _{ei})	. 0039%	
A _{ei}	Exit Area	Exit Area Radius	^{2π R} ei ^{σR} ei	$.012\left(\sigma_{R180}=\frac{tol}{6}\right)$. 01796%	11
A ₁₈₀	Nozzle Joint Area	Nozzle Joint Dia	^{2π R} 180 ^σ R180	$.00125\left(\sigma_{R180}=\frac{tol}{6}\right)$. 00343%	п
A _{ti}	Throat Area	Throat Radius	^{2π R} ti ^σ Rti	$010 \left(\sigma_{\mathrm{Rti}} = \frac{\mathrm{tol}}{6}\right)$. 045%	п

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Table I.15. Summary for Parameters Assumed Without Variance FM-6.

DATA FOR PROPELLANT STRESS FAILURE MODES, * FM7-11 INCLUSIVE

These five failure modes are a representative group related to propellant stress problems. They will be discussed together because only a small amount of input data applicable for $R \| C$ analysis was made available. However, this data collection effort represented a sizeable computer and study program on the part of AGC. It did, however, show that $R \| C$ analysis can still be a valuable tool when data supply is marginal. The five failure modes are as follows.

Failure Mode 7.	Propellant Max, Inner Bore
	Hoop Strain Failure Mode,
	Storage Condition

Innerbore grain failure in hoop stress due to cool down and storage (undetected) critical station-center region of motor.

Failure Mode 8.	Propellant/Liner Interface Maximum
	Radial Bond Stress Failure Mode,
	Storage Condition

Propellant/Liner interface bond fails radially during cool down and storage (undetected), critical station-aft end of motor.

Failure Mode 9.	Propellant Maximum Combined
	Stress (Principal Stress), Shear
	and Tension Failure Mode, Storage
	Condition

Failure of propellant due to combined shear and tension stress during cool down and storage (undetected), critical station-aft end of motor.

Failure Mode 10. Propellant/Liner Interface Maximum Shear Stress Failure Mode, Flight Condition

Propellant/Liner interface bond fails due to shear stress during cool down and storage (undetected), critical station-forward end of motor.

^{*} Data covered by AGC Progress Report No. 6, NAS 7-572. (Phase I study).

Failure Mode 11. Propellant Maximum Inner Bore Hoop Strain Failure Mode, Flight Condition

Inner bore grain failure in hoop stress due to pressurization and flight acceleration, critical station-aft end of motor.

Requirement Distribution. Data received from AGC and used for the $R \| C$ analysis for the failure modes 7 through 11 was given in the form of output R and C density parameters. AGC said that these functions were Gaussian and therefore TEMPO used closed formed solutions.

Detailed input and output data from the computer grain stress analysis performed by AGC are covered here. Input variables for the eight storage and eight flight simulations were used in the AGC analysis. Only the storage modulus of elasticity, the coefficients of thermal expansion, and the case wall thickness were varied, however, for the simulation storage conditions. For the flight simulations, the flight modulus was substituted for storage modulus and the propellant density and initial chamber pressure were added to the parameters varied in each run. A sample run is shown in Table I. 16.

The corresponding output data which are the grain stress and strain requirements are presented in a sample run, Table I. 17, which is the result of one of the eight simulation runs made by AGC. No Requirements are shown for inner bore strain in the forward part of the motor since it is non-axisymmetric, and would require special analytical treatment. The assumption was made that the grain design in this forward end could be so modified as to ensure that the maximum bore strain requirements would occur in the cylindrical section. AGC 260/S IV-B Propellant success criteria is as follows:

SATISFACTORY PERFORMANCE OF PROPELLANT/ LINER SUBSYSTEM

- Grain does not auto-ignite prior to planned ignition.
- Propellant burns without producing overpressure, burnthrough, or structural damage. (Does not include performance failure wherein structure remains intact, but delivered thrust, ignition delay, tail off, etc., are out of specification.)

TIME PERIOD

• From start of countdown to end of motor total action time.

Table I.16

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Sample^{*} AGC Run #2, Input Variables for Propellant Stress Failure Modes.

Section	Propo Modu <u>Elastic</u> Storage	ellant lus of ity, psi Flight	Coef. Therr <u>Exp.</u> , Prop. (X10 ⁵)	of nal %/°F Case (X10 ⁶)	Case Wall Thickness, Inches	Prop. Density, <u>lb/in³</u>	Initial Chamber Pressure, psi
	Diorage	<u>r iigiit</u>	(1110)	(1110)			
1-3	55	857	5.3996	5.594	. 425	.06328	528.1
4	63	1084	5.4003		11	.06332	539.8
5	54	838	5.3995		11	.06331	549.8
6	63	1071	5.4005	5.590	.433	. 06331	547.8
7	58	954	5.4000	5.605	.641	.06330	561.6
8	63	1095	5.4019	11	**	.06327	567.4
9	64	1121	5.4008	5.595	.650	.06329	591.3
10	62	1053	5.3992	5.514	.625	.06330	586.8
11	60	990	5.3988	5.606	.637	.06332	588.0
12	62	1049	5.4007	11	11	.06332	601.0
13	62	1063	5.4001	11	11	.06331	596.5
14	57	923	5.3992	5.618	.618	.06328	608.6
15	70	1269	5.4018	11	11	.06328	613.4
16	61	1028	5.3984	11	11	.06330	615.4
17	62	1049	5.4014	5.594	.641	.06334	608.1
18	60	1003	5.3992	11	11	.06329	612.4
19	53	817	5.3980	If	11	.06332	621.9
20	64	1097	5.4001	5.589	.621	.06331	619.2
21	57	929	5.4002	!!	* 1	.06330	619.8
22	62	1063	5.3993	11	11	.06331	628.0
23	57	923	5.4007	11	11	.06330	644.6
24	58	956	5.3985	5.600	.648	.06329	639.6
25	60	993	5.3987	11	11	.06333	659.4
26	50	734	5.3974	11	11	.06329	647.3
27	58	948	5.3984	5.584	.647	.06331	635.9
28	60	993	5.3998	11	11	.06329	646.1
29	64	1109	5.3996	11	11	.06330	659.5
30	61	1014	5.4003	5.585	.645	.06331	658.1
31	54	823	5.3983	11	11	.06328	653.8
32	60	1165	5.3987	11	11	.06330	672.1
33-37	58	946	5.3991	5.619	.637	.06330	679.0
38-39	66	1154	5.4015	11	11	.06330	661.0
40-41	54	829	5.4010			.06329	683.7
42-43	57	920	5.4002	5.602	.432	.06331	689.1
44	67	1185	5.3989	5.598	.432	.06329	690.3
45	57	913	5.3997	5.597	. 426	. 06332	701.8

* 8 Simulation computer runs were made by AGC.

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Table I.17

17 Sample* AGC Run #2, Output (Requirements) for Propellant Stress Failure Modes.

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	Flig	ht	Storage			
Section	Inner Bore Strain, %	Bond Shear Stress, lb/in ²	Inner Bore Strain, %	Radial Bond Stress, lb/in ²	Prop. Principle Stress, lb/in ²	
	2 7/		1 90		E 2/44	
1-5	2.70	11.1	1.80	2.25**	5.20**	
4	3.15	4.9	1.75	1.03	1.88	
5	5.50	8.1	1.13	.40	.91	
6	5.00	7.9	2.10	1.05	1.61	
7	5.79	9.1	2.60	. 93	1.44	
8	6.08	11.7	2.99	1.41	1.95	
9	7.70**	14.3	3.53	1.42	1.93	
10	7.23	16.0	3.48	1.79	2.28	
11	6.58	14.8	3.44	1.41	1.88	
12	6.29	12.3	3.45	1.77	2.25	
13	6.32	17.2	3.47	1.54	2.03	
14	6.26	12.4	3.38	1.78	2.23	
15	6.20	18.2	3.32	1.51	2.04	
16	6.15	15.1	3.38	1.82	2.30	
17	5.91	15.6	3.44	1.49	1.97	
18	6.11	20.7	3.54**	1.78	2.25	
19	6.32	13.5	3.54**	1.52	1.94	
20	5.95	16.7	3.44	1.69	2.18	
21	5.65	15.9	3.40	1.51	1.96	
22	5,96	18.5	3.38	1.64	2.13	
23	6.42	17.3	3.38	1.48	1.93	
24	6.66	27.1	3.36	1.57	2.04	
25	6.92	16.7	3.38	1.36	1.85	
26	6.70	13.0	3.43	1.55	1.98	
27	5.84	16.6	3.31	1.25	1.74	
28	5.53	18.3	3.09	1.38	1.90	
29	5.58	21.8	2.91	1.11	1.72	
30	5.51	24.4	2.84	1.22	1.85	
31	5,77	20.8	2.86	. 92	1.53	
32	NA	28.4**	NA	. 76	1.44	
33-37	11	20.5	11	. 81	1.46	
38-39	11	24.4	11	. 53	1.23	
40-41	11	15.1	11	. 35	. 85	
42-43	11	9.0	T t	. 47	. 73	
44	11	10.4		. 46	. 69	
45	11	17.3	11	.56	1,09	
-					•	

* 8 simulation computer runs were made by AGC.

** Maximum Value

PRE COUNTDOWN ENVIRONMENTAL CONDITIONS

- Post cast cool down from 140° to 60° F.
- Horizontal storage 3 years prior to use.
- Handling and shipping maximum, 1.3 g's longitudinal, 3.0 g's lateral.
- Countdown and launch at ETR, 2 g's axial load maximum.

EXCLUSIONS*

- Grain cracks and flaws, slump, deformation, and propellant/ liner separations that can be visually detected prior to countdown.
- All failures originating due to human error in manufacturing, inspection, assembly, transport, etc., that result in material strength or capability far below that normally considered in design.
- Failures resulting from the inability of quality control tests run on samples of case, liner, insulation and propellant to accurately reflect motor conditions.

Data for the input parameters used by AGC in the grain stress analysis, is given in Table I. 18. Table I. 19 summarizes the results of the AGC computer runs, which, although inadequate for a high confidence^{**} in the results, do show a relatively small variability for so few runs.

** Note that these data which represent maximum stress strain data, have standard deviations of from 10% to about 30% of the means. Only because the capability is so much greater does this data appear reasonable. From the few runs made, even if the data is representative of one of the "tails" of a distribution curve, our estimate is that R C analysis would still yield useful results.

 ^{*} It should be pointed out that some of the performance irregularities of the last 260 inch SL-3 motor firing might include failure modes associated with some of these exclusions.

Table I. 18Propellant Stress Datafor Failure Modes 7 through 11.

1

Requirement Parameter	Capability Parameter	Average Value	Coefficient of Variation $\frac{\sigma}{x}$	Standard Deviation, σ
Inner Bore Strain, in/in	Critical Storage Strain	. 242	.153	. 037
Radial Bond Stress, psi	Tensile Strength	18.3	.097	.018
Propellant Principle Stress, psi	Tensile Strength	18.3	.097	. 018

Table I. 19. Summary of AGC Computer Output, Showing Maximum Stress and Strain Requirements For Eight Flight and Eight Storage Simulation Runs

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. · · · · · <u> </u>	P1	opellant Fligh	t Conditi	lons
	Max Inner Bor	Max B	ond Shear Stress	
Run No.	in/in Section	Location	lb/in ²	Section Location
1	0747	31	24 5	32
2	0770*	9	28.4*	32
3	. 0746	<i>,</i> 9	34.0	32
4	. 0743	9	25.3	36
5	.0746	9	24.7	30
6	.0667	26	31.8	36
7	. 0731	9	29.7	37
8	.0845	9	52.8	39
	$\overline{x} = .0749$ (=)	R ₁₁)**	$\overline{\mathbf{x}} = 3$	0.62 (= R ₁₂)**
	σ = .00489 in	/in	σ =	9.52 lbs/in ²
	$\frac{\sigma}{\bar{x}} = .065$		$\frac{\sigma}{x} =$. 311
	Pr	opellant Storag	ge Conditi	ons
	Max Inner Bore Hoop Strain	Max Rad Bond Stre	ial ess	Max Propellant Principle Stress
Run No.	in/in Section Loc.	lb/in ² Sect	ion Loc.	lb/in ² Section Loc.
1	0354 18	2 26	2	5 16 2
2	0.0594 = 10 0.354* 18 + 19	2.35*	2	5 26* 2
3	0356 13	2.34	2	5, 29 2
4	. 0353 21	2.14	2	4.93 2
5	.0361 16	2.89	2	6.25 2
6	.0362 14	2.34	2	5.24 2
7	.0363 17	2.58	2	5.67 2
8	.0457 14	2.88	2	6.26 2
	$\overline{x} = .0370(=R_7)^{**}$	x = 2.47(=	R ₈) **	$\overline{x} = 5.51(= R_9) **$
	$\sigma = .00374$	$\sigma = 0.282$	lbs/in ²	$\sigma = 0.604 \mathrm{lbs/in}^2$
	$\frac{\sigma}{\pi}$ = .101	$\frac{\sigma}{\overline{x}} = .114$		$\frac{\sigma}{\overline{x}} = .091$

* Note max values in sample Table I.17.

** The \overline{x} values are also the requirement average values.

It should also be pointed out that, the \bar{x} values are also the Requirements: R_7 , R_8 , R_9 , R_{10} , and R_{11} . The following list the relationship for R and C parameters, as given by AGC:

Measurement of Requirement Parameters for Storage Condition:	Measurement of Corresponding Capability Parameters for Storage Conditions:
• Inner-bore Hoop Strain, in/in	• Measured Critical Storage Strain, in/in
• Radial Bond Stress, lbs/in ²	• Measured Tensile Strength, lb/in ²
 Propellant Principal Stress, lbs/in² 	• Measured Tensile Strength, lb/in ²
Measurement of Requirement for Firing and Flight Conditions:	Measurement of Corresponding Capability Parameters for Firing and Flight Conditons:
• Bond Shear Stress, lbs/in ²	 Measured Shear Stress Under Pressure, 1b/in²
• Inner-bore Hoop Strain, in/in	• Measured Critical Firing Strain, in/in

Capability Distribution. Data relative to propellant capability is given in Figures I. 1 and I. 2, and those relating propellant modulus to critical firing strain and shear strength are used in determining the capability for flight failure modes for each section of the motor. No such correlation is assumed to exist for storage failure modes. Therefore, the capability to resist storage inner bore strain, radial bond stress, and propellant principle stress is considered normally distributed in accordance with the parameter distribution data shown in Table I. 20.

A summary of AGC capability data is shown in Table I.21. These data are obtained from Figures I.3 through I.6. Appendix II discusses how this data is used.







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Constant Strain Data For ANB-3105 and ANB-3254 Propellant Figure 1.3



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Figure 1.4



Modulus of Elasticity vs Shear Strength for ANB-3254 Propellant Tested under 1000 psig Pressure.

Figure 1.5

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Figure 1.6

Storage Conditions	Average Value, x	Source of Average Value	Standard Deviation	Coefficient of Variation $\frac{\sigma}{\overline{x}}$	Source of Standard Deviation
Critical storage strain, (C ₇) in/in.	. 242	Extrapolated strain at which 50% of ANB-3254 samples from 260-SL-3 would fail. (Figure I. 3)	.0392	. 162	σ assumed to be same as 260-SL-1 data (Figure I. 3)
Tensile strength, (C ₈ , C ₉) psi	18.3	Value corresponds to modulus of 60 extrapolated from tensile stress vs modulus data for 28 batches of ANB -3254 from 260-SL -3 (Figure I. 4)	2.84	. 155	^C / _x from same 260- SL-3 and data used in Figure I.4.
Firing Conditions					
Inter-face shear strength, (C ₁₀) psi	418	Value corresponding to modulus of 1000 lb/in ² from graph of shear strength vs modulus based on on batch of ANB-3254 (Figure I. 5)	39.2 e	. 094	Sey from correlation between modulus and shear strength for one batch of ANB- 3254 (Figure I. 5)
Critical firing strain, (C ₁₁) in/in. * eg: .0392 = (.24 2) (.162)	. 44	Value corresponding to modulus of 1000 lb/in ² from graph of strain vs modulus single batch of ANB- 3254 (Figure I. 6)	.06 74	. 153	Sey from correlation between modulus and maximum strain for one batch of ANB- 3254

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Parameter	x	σ	σ / x
Propellant Modulus-Storage, psi (3 year relaxation 60°to 100°F)	60	4.67	.078
Propellant Modulus-Storage, psi (Initial)	1000	59.3	. 138
Propellant Density, lb/in. ³	0.06330	0.0000147	.000231
Propellant Linear Coefficient of Thermal Expansion in/in °F	5.4 $\times 10^{-5}$	0.00132×10^{-5}	.00231
Case Coefficient of Thermal Expansion	5.6x10 ⁻⁶	0.014×10^{-6}	.0025
Case Modulus of Elasticity, E _c (200 grade marage steel), psi	27,500,000		_
Case Thickness-Fwd and Aft Heads, in.	0.428	0.00482	.0115
Case Thickness-Cyl Section, in.	0.631	0.0118	.0187
Initial Chamber Pressure- Fwd End* psi.	700	10	.0143
Initial Chamber Pressure- Aft End* psi.	530	7.6	.0143

Table I.21. Propellant and Case Input Parameters Varied by AGC in Grain Design Computer Simulation Runs.

* Varies Linearly between fwd and aft end

Failure Mode 12. Data, Insulation/Motor Case Interface Bond Maximum Shear Stress, Flight Condition

The requirement distribution is the calculated maximum shear stress at the chamber wall for a 2.0 g maximum launch acceleration. It was assumed that the Insulation/Motor case interface maximum bond shear stress can be conservatively approximated by the maximum bond shear stress of the propellant. Thus from the 8 computer simulation runs made (as discussed in FM's 7-11), from Table I. 19, the mean value for the bond shear stress is 30.62 psi and the standard deviation is 9.52 psi. Although the sample size is small, the standard deviation based upon this sample data is probably conservatively high—the 52.8 psi obtained in the 8th run appears to be abnormally large.

For the Capability distribution, no data was available for the distribution of the shear strength of V44/Epon 948/Steel Bond. However, engineering judgment indicates that the data given in Table I.22 for shear strength of V45/SC 48:68 Epoxy Anhydride/Glass could be used as a conservative estimate.

Failure Modes 13 and 14. Data, Propellant Auto Ignition due to Static Discharge; and Auto Ignition due to Self Heating.

The data for these failure modes is discussed in AGC report NAS 7-572, Progress Report 6. Because of the extremely low probability of failure based on the limitations of data, the following AGC summary is given:

PROPELLANT AUTOIGNITION DUE TO STATIC DISCHARGE

Summary for distribution, R and C. Autoignition of a 260-in. -diameter motor propellant grain because of a static electrical discharge is considered to be unlikely because of the normally followed safety precautions and the large amount of energy required to ignite the grain. The requirement (in Joules) is assumed to be the single point value fixed by the U.S. Bureau of Mines as being "a reasonable value under not too extreme conditions." The capability distribution of the propellant is derived from ignition threshold tests.

The AGC report yielded the following data: $R_{13} = .013$ Joules charge energy, with $\sigma_{R_{13}} \simeq 0$ and $\overline{C}_{13} = 12.8$ Joules charge energy, with $\sigma_{C_{13}} = .188$ Joules.

Table I.22. Distribution of Bond Strength of
V45/SC 58:68 Epoxy-Anhydride/Glass
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	Bond Shear				
Specimen	Strength, @ 77°F, psi				
9	373				
10	356				
11	490				
12	402				
13	316				
14	435				
15	328				
16	303				
	$\bar{x} = 375$				
	$\sigma = 64.13$				
	$\frac{\sigma}{x} = .170$				

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PROPELLANT AUTOIGNITION DUE TO AMBIENT AIR TEMPERATURE

<u>Requirement Distribution</u>. The requirement is established as a single maximum value specified by the procuring activity. In the case of the 260-in.-diameter motor, this has been set at 100° F for the ambient air at the surface of the propellant grain. With some propellants, the temperature at the interior of the grain may be more than this because of propellant self-heating. For ANB-3105 in an 87.5-in. web, the estimated temperature rise is of a 0. 1° F order of magnitude and can be overlooked.

Capability Distribution. The capability of ANB-3105 to resist autoignition is determined by heating small propellant samples until they ignite. A value of 480° F was established for the ANB-3105 propellant. As is ordinarily the case where the capability is far in excess of the requirement, there is usually little effort made to determine a variability for the capability parameter. A limited amount of data for a similar propellant (ANB-3066) indicated a $\frac{\sigma}{\overline{x}}$ value of .0094. Since this represented only a single batch of propellant, it is recommended that a $\frac{\sigma}{\overline{x}}$ value of .02 be used instead. This assumption is based on engineering judgment and reflects experience with the batch-to-batch variability of other propellant parameters.

The AGC report yielded the following data:

$$R_{14_{max}} = 100.1^{\circ} F$$
, with $\sigma_{R_{14}} \approx 0$

and

$$C_{14} = 586^{\circ} F$$
, with $\sigma_{C_{14}} = 5.5^{\circ} F$.

APPENDIX II

I

DETAILS OF APPLICATION OF LARGE SOLID ROCKET MOTOR

Introduction

This appendix contains the details of the analysis and results that were summarized in Section 5 of this report. It is based upon the ground rules, data and rationale set up by AGC as given in Appendix I of this report. Computer programs and sample printouts are shown in the appendices which follow. A description of variability and sensitivity is also given in this appendix. This is followed by a discussion of the $R \mid \mid C$ analyses for the fourteen failure modes.

Discussion of Variability and Sensitivity Analysis

Standard Deviations, σ

It is appropriate to include a brief comment on the manner in which variances are computed and used in this report. The basic formulas are as follows. Consider a set of n observation of a variable, say x_1, x_2, \ldots, x_n . (These n values are in effect what we have called "batch data"). The sample mean is i=n

$$\overline{\mathbf{x}} = \frac{1}{n} \sum_{i=1}^{n} \mathbf{x}_{i}$$
(1)

and the sample variance is

$$s^{2} = \frac{1}{n} \sum_{i=1}^{n} (x_{i} - \overline{x})^{2}$$
 (2)

The sample standard deviation is s, the positive square root of the variance. Denote the unknown population variance by σ^2 , σ being the population standard deviation. An unbiased estimate of σ^2 , denoted by $\hat{\sigma}^2$, computed from the sample is

$$\hat{\sigma}^2 = \frac{1}{n-1} \sum_{i=n}^{n-1} (x_i - \overline{x})^2$$
(3)

Coefficient of Variation, cv

2

The coefficient of variation* is defined as the ratio of the standard deviation to the mean. In this case, we can speak of two such ratios based on computations from the n observations, namely

$$\frac{s}{\bar{x}}$$
 and $\frac{\sigma}{\bar{x}}$

We can describe s/\overline{x} as the coefficient of variation of the sample and $\hat{\sigma}/\bar{x}$ as an estimate of the coefficient of variation of the population.

Following a regrettably all too common practice, both TEMPO and AGC have used an inexact notation—we have used σ to mean s sometimes and to mean $\hat{\sigma}$ at others. This means that throughout this report, σ represents our estimate of the population standard deviation which may be either s or $\hat{\sigma}$. Of course there is little difference between s and $\hat{\sigma}$ for large n and we have regularly used the preferred one, $\hat{\sigma}$, where n is small. In the subsequent discussion, we will use this σ notation.

AGC has indicated that their data and their engineering analysis leads them to believe that the coefficient of variation is a key parameter and that it tends to remain constant over a rather wide range of designs. In other words, they can extrapolate coefficients of variation without adjustment—the scaling factor is nearly unity. This is an engineering property and not a statistical characteristic of σ/\overline{x} so at this point we can make no comment as to the validity of the AGC belief.

It often happens that various data sources yield a variety of estimates of σ/x . As an example, one might observe a design characteristic for each of a number of different motors. AGC has chosen to combine these estimates of σ/x by computing their arithmetic mean. Perhaps they consider that this is an appropriate method in view of their belief in the constancy of the coefficient of variation. We are not prepared to take issue with this method on theoretical statistical grounds. It should be noted, however, that it is an unusual procedure.

$$\sigma \simeq \overline{x}_{std} cv$$
 (4)

AGC frequently obtains an estimate of a standard deviation for a new parameter of interest, by multiplying estimates of the mean value of the parameter of interest (e.g., 260/S IV.B), by the coefficient of variation based on similar systems data. Thus

Variability Factor, V_f

The factor V_f is used to test the sensitivities of the failure probabilities to the values of the standard deviations of the input parameters. This was accomplished by multiplying the unadjusted standard deviation of the parameter, σ , by a variability factor V_f

$$\sigma = \mathbf{V}_{\mathbf{f}} \sigma_{\mathbf{std}}$$
(5)

where

 $v_f > 0.$

If $V_f > 1$, we are analyzing the effect of increased parameter variability on the failure probability—an increase is expected. If $V_f < 1$, we would anticipate a decrease in the failure probability. Sensitivity analysis thus provides an indication of the motor characteristics which can be adjusted through design changes or modifications in production methods to effect desired changes in reliability.

Detailed Analysis of the Failure Modes

The fourteen failure modes discussed herein were selected for analysis according to the provisions of the contract work statement given in Section 2, Study Objectives. The first six failure modes are in general those itemized under Task VIII, with some changes as suggested by AGC. They wished to cover the aft closure and bolt failure modes (numbers 5 and 6) instead of the forward areas because better design data was available.

Failure modes 7 through 11 were propellant stress failure modes. Failure mode 12 covered the interface bond stress of case and insulation, and the final two, 13 and 14, dealt with auto ignition failures.

In order to gain further insight into the rocket motor failures, special analyses were made in some cases of the fourteen listed failure modes. Parameter variability is based upon the AGC data and rationale shown in Appendix I. AGC has determined that as a good preliminary approximation, for this study, all parameters will be assumed normally distributed. The reader is reminded, however, that the R | | C analysis works equally well if the data is used as any other closed form or if discrete sets of data are used. A discussion of the failure modes follows.

Failure Mode 1. Hoop Stress Case Rupture Failure Mode

- 1a) Rupture with 90% of welds by machine 40" Fwd of equator, station 3.
- 1b) Rupture with 10% of welds by hand. 40" Fwd of equator, station 3.

For purposes of this analysis, motor station 3, Figure 1, Section 5, was selected by AGC as being the critical one to consider. Since the analysis is made before fabrication it is not known exactly where hand welds will occur and hence AGC had to provide this selection. Past experience by AGC shows, however, that about 10% of the welds will have detectable flaws that must be reworked by hand welding. AGC data shows that the hand welds tend to be weaker and have more strength variability then those done by machine. For this analysis, we assumed that 90% of the welds would be by machine and the 10% remaining by hand. It was further assumed that these proportions would hold throughout the motor case. The critical region of the motor case, section 3, is a logical choice since it is where the transformation of a thin walled spherical region joins the thicker walled cylindrical section of the motor.

1. Requirement Function. The basic engineering equation was described in Appendix I. To fit the R | | C analysis format better, both sides of the requirement equation are multiplied by R_0/t_c , giving

$$R_{1} = \frac{P_{cmax}R_{o}}{t_{c}} = \frac{W_{p}r_{b}R_{o}K_{m/a}e^{\pi_{k}\Delta t}}{C_{w}A_{t}bt_{c}}$$
(6)

where

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- $\pi_k = propellant temperature sensitivity coefficient, <math>\frac{\pi}{\sqrt{\rho_F}}$
- ∆t = ambient temperature difference between nominal and an upper specified limit prior to motor firing, ^oF.

W_p = propellant weight, lb. b = nominal web thickness, in. K_{m/a} = the ratio of peak to average web time pressure. (ND)

^πk^{∆t}

The factor e \uparrow was put in to allow for estimating the maximum chamber pressure at the specified upper limit. π_k is a random variable but Δt is a single valued or fixed (maximum) design limit.

The factor $K_{m/a}$ is the ratio of the design maximum pressure to the design average web pressure. The variability of this factor, observed from data on other motor programs, was used to reflect the effects of burning surface variability due to non-homogeneous burning, propellant linear separations, voids, etc. AGC values are tabulated in Table II. 1.

2. Capability Function. The capability of the case to withstand the stresses imposed can be divided into two parts. The first part consists of those stresses that are the result of the machine welds, which is assumed to constitute 90% of all the case welds. The second part consists of the remaining 10% which are hand welds. To fit the R || C analysis format, both sides of the equation are multiplied by R_0/t_c and the resulting capability equations become

$$C_{lm} = \frac{P_{mw} R_o}{t_c} = S_{umw} K_{be} K_{bx}$$
(7)

for the machine welds and

$$C_{lh} = S_{uhw} K_{be} K_{bx}$$
(8)

for the hand welds. *

The R | | C equation for failure mode 1, for the probability of failure is

$$\mathbf{P}[\mathbf{F}]_{1} = \mathbf{P}\{(\mathbf{C}_{1} - \mathbf{R}_{1}) \le 0\}$$
(9)

The subscript designation is m for machine and h for hand welds.

which becomes, for 90% welds:

$$P_{m}[F]_{1m} = P\{C_{1m} - R_{1}\} \le 0\};$$
 (10)

and for 10% of the welds:

$$P_h[F]_{1h} = P\{(C_{1h} - R_1) \le 0\};$$
 (11)

and for 100% of the welds:

$$P[F]_{1} = .9P_{m}[F]_{1m} + .1P_{h}[F]_{1h}$$
(12)

πΛ

Finally, using Equations 6 through 12, we obtain

$$P[F]_{1} = .9\{P_{m}[K_{be}K_{bx}S_{umw} - \frac{W_{p}r_{b}R_{o}K_{m/a}e}{C_{w}A_{t}bt_{c}}] \le 0\} + .1\{P_{h}[K_{be}K_{bx}S_{uhw} - \frac{W_{p}r_{b}R_{o}K_{m/a}e}{C_{w}A_{t}bt_{c}}] \le 0\}$$
(13)

The machine and hand weld portions shown in Equation 13 were calculated in separate computer runs.

The program used for failure mode one, RELFMl, is given as an example in Appendix V. Sample runs are shown for FMl_m for the standard case ($V_f = 1$ for all parameters), and for FMlh for case 2 ($V_f = 4$ for the standard deviation of the parameter S_{uhw}). Over 30 computer runs were made for this failure mode to cover the standard case and the sensitivity analysis.

Table II. 2 summarizes the results of the solution to Equations 10 and 11. Based on the data supplied by AGC, the standard computer runs were made for the 90% and 10% cases. For the 90% case, only when the value for one standard deviation for S_{umw} is increased from 2516.6 psi to 20, 132.8 psi ($V_f = 8$) does the probability of failure increase from virtually zero to .00007567 ($V_f = 1$ for all other parameters). From the table, the critical ranking of the parameters was obtained, and is: S_{uhw} , S_{unw} , r_b , K_b and K_m . The remaining parameters are relatively insensitive to increases in variability. If more detailed sets of computer runs were to be made such as using other weld ratios (namely, 80/20 or 95/05 etc.) the remaining insensitive parameters A_t ,

Table II.1. Summary Data for Failure Mode-1

Γ

Symbol	Parameter Description	$\frac{\text{Mean Value}}{\overline{x}}$	Parameter Standard Deviation
S _{umw} S _{uhw}	Ultimate weld strength, psi. — Machine weld — Hand weld	232,000 199,000	2516.6 8641
K be	Bending/discontinuity factor, (ND)	.95845	.00693
K _{bx}	Biaxial Gain Factor, (ND)	1.106	.0312
wp	Propellant weight, lb.	3,400,000	6120
с _w	Mass flow coefficient sec ⁻¹ .	.0062477	.0000190
^г ь	Propellant burn rate, in/sec.	. 606	.00818
A _t	Average Throat area, in. ²	6355	20.9
K _{m/a}	Ratio of Avg to peak chamber pressure (ND)	1.18	.008968
b	Web thickness propel- lant, in.	85	.17
R ₀	External motor radius, in.	130.631	.0261
t _c	Case wall thickness, in.	.6392	. 0095
^π k	Temperature sensi- tivity, %/°F.	.16	.00676
Δt	Maximum temperature difference, ^O F .	20	

RUN	Variable	x	$\overline{\mathbf{x}}$ $\mathbf{V_f}$ $\sigma \mathbf{V_f}$		P[F] _{lm,lh}		
		FOR MAC	HINE W	ELDS (90%)			
Std.	*	*	*	*	<<. 000 000 01		
1	Sumw	232,000	4	10,066.4	<. 000 000 01		
2	Sumw	232,000	8	20,132.8	.000 075 67		
3	rb	. 606	4	. 03272	<<. 000 000 01		
4	$\mathbf{r}_{\mathbf{b}}$.606	8	.06544	.000 009 47		
5	Kbe	.95845	~5	. 03	<<. 000 000 01		
6	Kbe	.95845	~10	. 06	.000 000 13		
7	$K_{m/a}$	1.18	5	. 04485	<<.000 000 01		
8	K _{m/a}	1.18	~10	.1	.000 000 04		
9	At	6355	~5	100	<<.000 000 01		
10	tc	.6392	~2	. 01	<<.000 000 01		
11	C_w	.0062477	5	.000095	<<.000 000 01		
12	WP	3,400,000	3	18,360	<<.000 000 01		
13	R ₀	130.631	~5	.125	<<.000 000 01		
14	π _k	.16	~3	. 0002	<<.000 000 01		
15	Ъ	85	~50	8.5	<<.000 000 01		
		FOR HAI	ND WEL	DS (10%)			
Std.	*	*	*	*	.000 000 81		
1	S_{uhw}	199,333	2	17,282	.002 283 40		
2	S_{uhw}	199,333	4	34, 564	.049 484 70		
3	r_{b}	.606	2	.01636	.000 012 04		
4	r_{b}	.606	4	.03272	.000 219 25		
5	К _{be}	.95845	5	.03465	.000 050 83		
6	К _{be}	.95845	~10	.06	.001 684 02		
7	K _{m/a}	1.18	5	. 04485	.000 006 19		
8	K _{m/a}	1.18	~10	.1	.001 145 91		

Table II.2. Summary of Results of Computer Runs for Failure Mode-1

* V_f , the variability factor, is varied for one parameter at a time. For the standard run, $V_f = 1$ for all parameters.

Parameter	Variability Factor V _f	σ	ν _f σ	P[S]**
Standard run*	1	*	*	>.999999
S _{umw}	4	2516.6	10,066.4	000772
Suhw	2	8641.	17,282.	. 999772
Sumw	8	2616.6	20,132.8	004000
Suhw	4	8641.	34,564.	. 994983
r _b	4	. 00361	.01444	. 999781
K _{be}	5	. 00693	.03465	. 999995
K. be	10	. 00693	.0693	. 999832
K _{m/a}	5	. 00897	. 04485	. 999999
K _{m/a}	10	. 00897	.0897	. 999885

Table II. 3. Summary of R | | C Analyses for Failure Mode-1

* The standard run uses the unajusted data supplied by AGC for all parameters and, consequently, the variability factor is unity.

**

The P[S] is obtained by combining the data of Table II. 2 for 90% and 10% welds, using Equation 13; and noting that P[S] = 1 - P[F].

t, C, W, R, π_k and b could be treated as constants to greatly reduce computer time, and determine the sensitivity of ratio of machine welds to hand welds.

It can be seen from Table II. 2 and II. 3 that, as the variability factor (V_f) increases, the probability of failure increases significantly. The most significant of these increases in probability of failure are a result of the welds made by hand techniques.

Table II. 3 summarizes the results of some of the combinations of the Table II. 2 run results for 90% machine and 10% hand welds. We note that for the standard run ($V_f = 1$ for all parameters) the reliability is in excess of .999999. An illustration of a somewhat critical case for the present design of the 260/S IV B welds arises if the V_f is as great as 8 for machine welds and 4 for hand welds. This is shown by the third calculation in Table II. 3 with a value of P[S] equal to .994983. The table considers variability factors for one parameter at a time except for the second and third calculations. The "90/10" ratio of welds should be investigated further and also the variability of S_{uhw} , S_{umw} , r_b . Possibly K_{be} and K_m/a should also be investigated to check if these in fact have significant influence for realistic values of V_f 's.

Failure Mode 2. Motor Case Insulation Burn Through Failure Mode

- 2a) Burn-through of the insulation to case wall at stations with propellant.
- 2b) Burn-through of the insulation to case wall at stations that have no propellant.

Many motor stations are being considered in studying this failure mode since it is not obvious which is critical—for purposes of this analysis, AGC suggested that we examine stations 1, 2, 4, 5, 6, 7 and 12 as are shown in Figure 1, Section 5.

<u>Transfer Function</u>. Four basic parameters enter in the transfer functions for this failure mode. These four parameters are as follows.

b = nominal propellant web thickness, in.

r = propellant burning rates, in. per second.

t_i = insulation thickness, in.

$$e_r = insulation erosion rate, in. per second.$$

The capability transfer function, C, is $(b/r_b + t_i/e_r)$. This function represents the total time it takes to burn through the propellant and insulation at any motor station.

The requirement transfer function, R, is b'/r_b' . This function represents the time it takes to burn through the propellant to the insulation at that motor station, where the propellant web thickness, b', divided by the propellant burning rate, r_b' , is greatest. The resulting transfer function for FM2 becomes

$$(C - R)_2 = (b/r_b + t_i/e_r) - b'/r_b'$$
 (14)

The requirement term involving primed parameters occurs at station 4-it is compared to the capability function at each motor station using the equation

$$\mathbf{P}[\mathbf{S}]_{2} = \mathbf{1} - \mathbf{P}\left[\left(\frac{\mathbf{b}}{\mathbf{r}_{\mathbf{b}}} + \frac{\mathbf{t}_{\mathbf{i}}}{\mathbf{e}_{\mathbf{r}}} - \frac{\mathbf{b}'}{\mathbf{r}_{\mathbf{b}}'}\right) \leq 0\right]$$
(15)

Parameter Variability. The analysis for FM2, follows.

<u>Propellant Burning Rate</u>, r_b . The burning rate variability is estimated from the coefficient of variation based on LSBR batch mix data for 260-SL-1 and 260-SL-2 motors. Table II. 4 lists the burning rate data from which the coefficient of variation for the propellant burning rate is estimated at 0.00595 for the 260/S IV-B motor. Using the propellant burning rate as 0.606 in/sec at motor stations 2, 5, 6 and 7, and 0.590 in/sec at motor station 4, we can estimate the respective standard deviations for the propellant burning rates as follows:

```
At Motor stations 2, 5, 6 and 7

\sigma_{std} = 0.00595 (0.606) = 0.00361

At motor station 4
```

$$\sigma_{\rm std} = 0.00595 (0.590) = 0.00351$$

<u>Propellant Web Thickness, b.</u> AGC assumed the coefficient of variation is .002 and constant throughout the propellant. This then resulted in the values for one standard deviation* at the various motor stations and summarized in Table II.4.

Insulation Thickness, t_i . The insulation thickness variability is estimated by AGC to be \pm 0.010 inches for \pm 3₀ in the thin section of the motor (stations 4 and 5, where $t_i = 0.110$ inches), and \pm 0.050 inches for \pm 3₀ in the remainder of the motor.

At motor stations 4 and 5

 $\sigma_{std} = \frac{0.01}{3} = 0.0033$

At motor stations 1, 2, 6, 7 and 12

$$\sigma_{\rm std} = \frac{0.05}{3} = 0.01667$$

Table II. 5 shows this data as it will be used in the $R \mid \mid C$ analysis. For the first set of data, standard runs will use the above data with the nominal design values for t_i . The second set of values are used in the sensitivity analysis, where insulation thicknesses were doubled in the thin sections (stations 4 and 5) and increased by a factor that was less than double in the thicker sections. The results of this analysis are discussed in Section 5 of the report.

Insulation Erosion Rate, e_r . The insulation erosion rate variability is estimated from the coefficient of variations based on Polaris and Minuteman (MM) data since these also use V-44 type Silica Asbestos insulation on the motor case. AGC suggested that the MM data may be used in the cylindrical sections of the motor as a preliminary estimate, but they feel that the high variability of the data may lead to an over conservative analysis. Polaris data is to be used in the remaining sections of the motor. Table II. 5 of Appendix I lists distribution data for 11 Polaris motor stations and are assumed by AGC to be comparable to the hemispherical ends of the 260/S IV-B motor. Table II. 6 lists the MM data estimated by AGC as conservatively comparable to the thin wall section of the 260/S IV-B, at motor station 5.

The assumption of a normal distribution for the propellant web thickness, b, is based upon a homogeneous propellant not having voids, cracks, laps, folds, etc. This assumption appears to be less realistic than some others. A more reasonable one would consider a skewed distribution.

Table II.4. Variability Data for Propellant Web Thickness, Parameter b

PY 7

Motor Station	$\sigma_{ m std}$
2	0.049
4	0.175
5	0.170
6	0.1437
7	0.1411
1	(no propellant)
2	(no propellant)

Notes: Based on AGC judgment it is assumed that the coefficient of variation , $\sigma/\bar{x} = 0.002$, is constant for the entire propellant grain. (AGC report 0815-81F on 260 SLl and 260 SL2 motors.)

Motor	Sta	ndard Ru	ns	Ser	sitivity R	sitivity Runs		
Station	t. i	σ_{std}	Run No.	t _. i	$^{\sigma}$ std	Run No.		
1	1.125	0.01667	1	(not r	equired)			
2	1.125	0.01667	2	(not r	equired)			
4	0.110	0.00333	$(all)^*$	(not a	pply) ⁽¹⁾			
5	0.110	0.00333	3,5	0.220	0.005	4		
6	0.250	0.01667	6	${0.375 \\ 0.500}$	0.025 0.025	7 8		
7	0.430	0.01667	9	∫0.516 0.645	0.025 0.025	10 11		
12	3.60	0.01667	12	${4.32 \\ 5.4}$	0.025 0.025	13 14		

Table II.5. Variability Data for Insulation Thickness Parameter, t_i

* Station 4 is the station by which the requirement is generated.

Thus, from the Polaris data, the coefficient of variation is estimated as being the "average" * of the 11 station maximums. Using a computer program to compute the means, standard deviations, and coefficient of variations for "batch" data, values obtained for \overline{x} and cv are calculated and summarized in Table II.6. Thus:

*

 $cv_{POL} = 0.16310 \approx cv_{260/S IV-B}$; at stations 1, 2, 6, 7 and 12.

 $\overline{\mathbf{a}}$

Station	Mean, x	<u>cv, 🕱</u>
26	. 368333	.123837
27	. 366250	.120264
28	. 341667	.123079
29	. 328750	. 151663
30	. 328750	.157890
31	.318750	.140394
32	. 283333	.143245
33	. 272917	.194025
34	. 248333	.214555
35	.214583	. 239135
36	. 197083	.184974

Table II.6. Summary of Polaris Data

$$cv_{POL} = 0.16310$$

Similarly, for Minuteman data based on 20 motor firings and shown in Table I.6 of Appendix I the coefficient of variation was calculated, to be

$$cv_{MM} = 0.51714$$

and this was used as the cv for stations 4 and 5. Thus, the estimates of the standard deviations for the insulation erosion to be used in this analysis for 260/S IV-B are as follows.

This is an engineering judgement rather than a statistical one. See beginning of this appendix for comments on coefficients of variations. (If the total population of $264 \overline{x}$ maximum values were averaged, the total mean would have been .297159 and $cv_{264} = .245477$).

At motor stations 1 and 2 (cv = .16310)

 $\sigma_{std} = cv_{POL} \overline{e}_{r} = 0.16310 (0.003) = 0.0004893$

1

At motor station 5 (cv = 0.51714)

$$\sigma_{std} = cv_{MM} e_{r} = 0.51714 (0.005) = 0.002586$$

At motor station 6 (cv = 0.16310)

$$\sigma_{\text{std}} = cv_{\text{POL}} \bar{e}_{r} = 0.16310 (0.005) = 0.000816$$

At motor station 7 (cv = 0.16310)

$$\sigma_{\text{std}} = cv_{\text{POL}} = 0.16310 (0.006) = 0.000979$$

At motor station 12 (cv = 0.16310)

$$\sigma_{\text{std}} = cv_{\text{POL}} \overline{e}_{r} = 0.16310 (0.0168) = 0.002740$$

Results of Failure Mode 2 Analysis. The parameters, standard deviations and summary of results are tabulated in Table II. 7. Fourteen computer runs were made, including six standard runs for the six motor stations. This resulted in critical values of .862888 at station 6; .953370 at station 12; .983907 at station 5; and .988810 at station 7. The sensitivity analysis showed that by increasing the insulation thickness at these stations reliability values greater than . 999999 resulted, except for station 5 where even for an increase of from . 110 to . 220 inches (cylindrical region) the P[S] was only .999988. This represents the conservative AGC estimate based on MM variability data for the erosion rate of the insulation. It was noted that if Polaris variability data were used instead of the MM data in the cylindrical region of the motor, this would effectively amount to a V_f value of . 316 on the standard deviation. Thus, for the thin wall region; $t_i = .110$, and this would have increased P[S] at station 6 from .86288 to .998. This is still too low, but coupled with increased insulation thickness, the P[S]will exceed . 999999 at this critical station. A major effort may be required to accomplish this gain. If further analysis indicates that the MM data is in fact about the "best estimate" of σ , then the only course open is to increase the insulation thickness about 120% at station 5.

[CAPABILITY ⁽¹⁾					(2) REQUIREMENT [Station 4]							
	; 		Web, b, ins		Burn H (ins/s	Rate, r _b ec)	Ins. T t _i	hick., ins_	Eros. (in/sec	Rate, e _r c.)	Web, ins	b,	Burr (in/s	n Rate, r _b sec.)	
Computer Run	Motor Station	Variability Sensitivity	x	σ	x	σ	x	σ	x	σ	x	σ	x	σ	P[S] ₂
1	1	Standard Run	No	Propella	ant		1.125	.1667	.003	.000489	87.5	.175	.59	.00351	>.999 999
2	2	Standard Run	24.5	.049	.606	.00361	"			0		11	11	п	> .999 999
3	5	Standard Run	85	.170	n	11	0.110	.0033	.005	.002586	ч. –	,	1	1	.983 907
4	5	Double Insulation	н	' 11	н	l	0.220	.005	"		"	n		н	.999 988
5	5	Decr. $V_{f}^{(3)}$ for e_{r}	11	''	11	(n	0.110	.0033		.000816		11		11	.998 001
6	6	Standard Run	71.85	.1437	. 11	: 	0.25	.01667	"	н		н	"	11	.862 888
7	6	50% Incr. Insul.		† (н ,	1 1		0.375	.025	n	. 11	11	11	11		.993 235
8	6	Double Insul.	п	н	1	11 }	0.50	.025		้ ท	н -	11		11	> .999 999
9	7	Standard Run	70.57	.1411	¹ n	t ''	0.43	.01667	. 006	.000979	11	п		11	.988 810
10.	7	Incr. Insul. 20%	"		i		0.516	.025	11	п		0		"	.995 213
11	7	Incr. Insul. 50%	п		U.		0.645	.025			11	11	н	н	> .999 999
12	12	Standard Run	No	Propella	ant]	3.6	.01667	.0168	.00274	р ¹		11	11	.953 370
13	12	Incr.Insul 50%	No	Propella	ant	:	4.32	.025	0		":	н		н	.983 565
14	12	Incr. Insul 50%	No	Propella	nt		5.4		11	п		11	11		> .999 999
· ·]			·				İ				

Table II.7. Summary for Failure Mode FM-2; Motor Insulation Burn-Through.

(1) $C = (b/r_b + t_i/e_r)$.

(2) $R = b^{i}/r_{b}^{i}$.

(3) $V_f \simeq 1/3$; POLARIS Standard deviation used at this station instead of MM standard deviation.

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Failure Mode 3. Failure of the Forward Motor Skirt Forging in Combined Compression, Shear, and Bending.

This failure mode involves consideration of the interaction ratios of axial compression, transverse shear and pure bending load requirements to their respective material capabilities. The mode is associated with only one region of the motor case, namely the forward motor skirt forging. The engineering data and rationale to be used for analysis will be found in Appendix I.

The transfer function for this failure mode was given in Equation 6 of Appendix I. It was transformed into R | | C form as follows.

$$\mathbf{P[F]}_{3} = \mathbf{P} \left[(\mathbf{R}_{c} + \sqrt[3]{\mathbf{R}_{b}^{3} + \mathbf{R}_{s}^{3}}) \ge 1.000 \right].$$
(16)

By expanding the interaction transfer function, and by substitution we have for the 260/SIV-B motor, in $R \mid |C$ form, the following:

$$P[F]_{3} = P\left\{ \left[\frac{L_{c}}{2\pi r_{i} t_{s} k_{c} E_{s}} + \sqrt{\frac{L_{b}}{\pi R_{i}^{2} t_{s} K_{b} E_{s}}} + \left(\frac{L_{s}}{\pi R_{i} t_{s} K_{b} E_{s}}\right) + \left(\frac{L_{s}}{\pi R_{i} t_{s} K_{s} E_{s}}\right) \right] \\ \geq 1.000 \right\}. \quad (17)$$

where

$$L_c = Axial compressure load, lb.$$

 $L_b = Pure bending load, lb.$
 $L_s = Transverse shear load, lb.$
 $R_i = Radius to inner surface of skirt, in.$
 $t_s = Thickness of skirt, in.$
 $E_s = Modules of elasticity, psi$
 $K_c = Ratio of axial compressure strength to Modulus of Elasticity.$

- K = Ratio of pure bending strength to Modulus of Elasticity.
- K = Ratio of transverse shear strength to Modulus of Elasticity.

A summary of the averages and standard deviations characterizing the distribution of these parameters is shown in Table I. 7 of Appendix I. Based on this data, the computations indicated that the probability of failure was very remote. Hence, with $P[S]_3 > .999999$ no sensitivity analysis was made for this failure mode.

Failure Mode 4. Meridional Stress Case

Rupture Failure Mode:

- 4a) Rupture with 90% of welds machine welded, Fwd head circumferential weld, Meridional stress, spherical section.
- 4b) Rupture with 10% of welds, hand welded. Fwd head circumferential weld, Meridional stress, spherical section.

The general analysis for this failure mode is similar to Failure Mode 1. However, because of the spherical shape in the forward region of the motor, the pressure capacity it twice as great for the same thickness of material. In practice, the hemispherical motor ends are made thicker than half that of the cylindrical sections; hence, this region tends to be much less critical, all things being equal (weld strengths, etc.).

The Requirement is the same, so Equation 3 is used. Hence,

 $R_3 = R_1$

The Capability, again as with FM-1, is assumed to have 90% of welds machine welded, and 10% hand welded. Because of the spherical shape, there is no $K_{\rm bx}$, biaxial gain factor. Hence the capability for 90% of the welds becomes

$$C_{4m} = \frac{P_{mw} R_0}{2t_c} = S_{umw} K_{be}$$
 (19)

and for 10% of the welds

$$C_{4h} = \frac{P_{hw}R_0}{2t_c} = S_{uhw}K_{be}$$
(20)

In similar fashion to FM-1, these reduce to

$$P[F]_{4} = .9 \left\{ P_{m} \left[K_{be} S_{umw} - \frac{W_{p} r_{b} K_{m/a} e^{\pi_{k} \Delta t}}{2C_{w} A_{t} b t_{c}} \right] \leq 0 \right\} +$$

$$.1 \left\{ P_{h} \left[K_{be} S_{uhw} - \frac{W_{p} r_{b} K_{m/a} e^{\pi_{k} \Delta t}}{2C_{w} A_{t} b t_{c}} \right] \leq 0 \right\}.$$

$$(21)$$

Computations for machine and hand welds were made separately. Data and rationale appear in Appendix I for FM-4. Table I.9 of Appendix I summarizes the data for the runs which were made. The plate thickness parameter, t_c , uses the thinner plate (mean of .428) together with its associated standard deviation. The standard runs yielded the following results.

 $P[S]_4 = 1 - [.9(<.000\ 001) + .1\ (<.000001)] = >.999\ 999.$

Since this failure mode has a considerably lower criticality than FM-l, no sensitivity analysis was made.

Failure Mode 5. Rupture of the Nozzle Joint Bolts

The requirement Equation 11 was given in Appendix I. The term P_{cmax} is contained within that expression, but P_{cmax} is also a function of several other variables, which also appear in FM-1 as:

$$P_{cmax} = \frac{W_{p}r_{b}K_{m/a}e^{\pi k\Delta t}}{C_{w}A_{t}b}$$
(22)

Substituting (22) in the R_5 function and using Equation 23

$$\mathbf{P[F]}_{5} = \mathbf{P[C}_{5} - \mathbf{R}_{5} \leq \mathbf{0}]$$
(23)

we can write the probability of failure for this failure mode as

—

$$P[F]_{5} = P\left\{P_{y} - \left[K_{p}F_{by} + \frac{5.6912(\tan\alpha)A_{ti}W_{p}r_{b}K_{m/a}e^{\pi_{k}\Delta t}}{n D_{j}C_{w}A_{t}b} - \frac{51.534(\tan\alpha)dA_{ti}P_{a}}{n D_{j}}\right] \leq 0\right\}$$

$$(24)$$

Equation 24 could have been simplified by factoring, so that the P_{cmax} terms transfer function would match those of FM-1. This would be better if we were considering correlated parameters of different failure modes and if all the terms were variables. In this analysis, however, since many of the variables are constants, Equation 24 was reduced to the following:

$$P[F]_{5} = P\left\{P_{y} - \left[213\ 310\ K_{p} + \frac{10.\ 08146\ W_{p}r_{b}K_{m/a}e}{C_{w}A_{t}b} - \frac{20\pi_{k}}{C_{w}A_{t}b} - \frac{2$$

Table II.8 lists the variables and their deviations, the last six being constants in this example. Equation 25 was used in the computer run and the results showed a very low probability of failure. The sensitivity analysis used variability factors to approach a low limit of reliability.

Four of the variables that showed some sensitivity, namely, W_p , r_b , A_t and K_m/a , were varied together by using factors, V_f , which ranged from 2 to 10. Resulting probabilities of failure were still much less than .000001. Reliability for this failure mode is estimated as $P[S]_5 > .999999$.

The numerical constants appearing in the Equations 11 and 24 are the result of various computations performed by AGC—they were not described in their reports.

Table 1	II. 8.	Summary	for	FM- 5
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		Standard	Sensitivity		
Parameter	X	^σ std	v _f	$\sigma \mathbf{v_f}$	
Wp	3,400,000	6120	4	24,480	
C _w	.0062477	. 000019	1	. 000019	
r _b	. 606	. 00818	2	.01636	
A _t	.6355	20.9	4	83.6	
K _{m/a}	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$		10	. 0897	
b			1	.17	
π_{k}			1	. 00676	
Pa			1	10735	
K p			1	. 077	
P y	245, 307	1987	1	1987	
F _{by}	213, 310	0	1	0	
α	3.1	0	1	0	
d	d 178.84 A _{ti} 6235		1	0 0	
A _{ti}			1		
n	220	-	-	-	
Dj	180	0	1	0	
P[F]5	=	<.0000001	<. 0000001		

Note: only 10 of the 15 paramaters had a distribution, and of these all

but three are correlated with FM-l

_ _ _ II**-**22

Failure Mode 6. Separation of Motor Chamber and Nozzle Flange.

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This failure mode deals with the separation of the motor chamber from the nozzle flange caused by the ejection load per bolt exceeding the pretorque load per bolt.

Requirement Analysis. The requirement Equation 12 given in Appendix I, may be rewritten as:

$$R_{6} = P_{cmax} \left[.9981 A_{180}^{i} (1 + \gamma M_{180}^{2}) - .014092 A_{ei}^{i} (1 + \gamma M_{e}^{2}) \right] \frac{1}{n} + P_{a} \left[A_{ei}^{i} - A_{180}^{i} \right] \frac{1}{n} + \left[\frac{W_{ni}^{i} (W_{p} + W_{vi})}{1.42279 A_{ti}^{i} P_{cmax}^{i} - 11 A_{ti}^{i} P_{a}^{i}} \right] \frac{1}{n}$$
(26)

Then, by substituting Equation 22 for P_c ; we obtain the equation in terms of all of the variables:

$$R_{6} = \frac{W_{p}r_{b}K_{m/a}e^{\pi_{k}\Delta t}}{C_{w}A_{t}b} \left[\cdot 9981 A_{180}^{*1+\gamma M_{180}^{2}} - \cdot 014092 A_{ei}^{(1+\gamma M_{e}^{2})} \right] \frac{1}{n} + P_{a} \left[A_{ei}^{-A_{180}} \right] \frac{1}{n} + \left[\frac{W_{ni}^{(W_{p} + W_{vi})}}{\frac{1.42279A_{ti}W_{p}r_{b}K_{m/a}e^{\pi_{k}\Delta t}}{C_{w}A_{t}b} - 11A_{ti}P_{a}^{-11A_{ti}P_{a}} \right] \frac{1}{n}$$
(27)

Since for this study many variables appearing in the above equation are constants ($\sigma = 0$), Equation 27 was reduced to the following:

$$R_{6} = \left(\frac{68.0064 W_{p} r_{b} K_{m/a}}{C_{w} A_{t}^{b}}\right) + 139.405 P_{a} + \frac{59428 (W_{p} + 726 466)}{\frac{59428 (W_{p} + 726 466)}{r_{k} \Delta t}} + \frac{1,951,640 W_{p} r_{b} K_{m/a}}{C_{w} A_{t}^{b}}\right) - 15,088,700 P_{a}$$
(28)

Capability Analysis. The capability is the pretorque load per bolt. This may be expressed simply as

$$C_6 = K_p F_{by}$$

where

*

- $C_6 =$ the capability of one bolt to withstand the flange separation, lb.
- K = the fraction of bolt minimum yield strength to which the bolt is pretorqued, (ND)

F_{bv} = the minimum tensile load per bolt, 1b/bolt.

$$\frac{Failure, \text{ then is}}{P[F]_{6} = P\left\{\left[\begin{matrix} K_{p}F_{by} \\ [K_{p}F_{by} \end{matrix}] - \left[\begin{matrix} \frac{68.0064 W_{p}r_{b}K_{m/a}e}{C_{w}A_{t}b} + 139.405 P_{a} \\ \frac{59,428 (W_{p} + 726,466)}{(W_{p} + 726,466)} + \frac{139.405 P_{a}}{C_{w}A_{t}b} \\ \frac{(1,951,640 W_{p}r_{b}K_{m/a}e}{C_{w}A_{t}b} - 15,088,700 P_{a} \\ \end{bmatrix} \le 0 \right\}$$
(30)

A program was written for Equation 30 in which the last ratio, to be denoted by "B", before the inequality sign was treated as a constant. This was done after a sensitivity analysis showed that the effect of the last term, B, was negligible. It was found that even if the standard deviation of the parameter of the last term were chosen at the values of + 3 $_{\sigma}$ that would cause the term to be a maximum (B_{max} = 228,653), the effect on P[F] was negligible. Had this not been so, a more complicated program would have to have been written to account for the correlation of the parameters. * Table II. 9 contains the data and results. Note the effect of the B term when comparing two sets of identical runs. Standard runs 1 and 2 yielded a reliability of . 999 998 for both B = 0, and B = 228.653. Runs 6 and 7 were also unaffected in the 6th place. The variability of K_p , the pretorque factor, is somewhat sensitive. Perhaps a 100% increase in variability is unreasonable (which produces a joint reliability of . 983 695); but for a 20% increase in variability, reliability is . 999 949. This analysis has about the same effect as Run 8,

(29)

This is an example of parameter correlation within a failure mode. The sensitivity analysis also showed that there was no need to overcomplicate the problem with a more exact treatment, since the results would have been nearly the same for all runs.

		Standard Deviation	Sensitivity Runs ⁽²⁾ , for Values of Vf.							
Parameter	<u> </u>	std	1	2	3	4	5	6	7	8
w _p	3,400,000	6,120	1	1	1	1	1	1	1	2
Cw	.0062477	.000019	1	1	1	1	4	4	4	4
rb	.606	.00818	1	1	1	1	1	1	1	10
A _t	.6355	20.9	1	1	1	1	1	2	2	2
K _{m/a}	1.18	.00897	1	1	1	1	1	2	2	2
b	85	.17	1	1	1	1	1	1	1	10
π _k	.16 ´	.00676	1	1	1	1	1	1	1	1
Pa	14.696	.0735	1	1	1	1	1	1	1	1
к _р	0.6	.077	1	1	2	1.2	1	1	1	1
A ₁₈₀	25,477	0	0	0	0	0	0	0	0	0
A _{ei}	56,116	0	0	0	0	0	0	0	0	0
A _{ti}	6,235	0	0	0	0	0	0	0	0	0
γ	1.2	0	0	0	0	0	0	0	0	0
M ₁₈₀	.0576	0	0	0	0	0	0	0	0	0
Me	3.205	0	0	0	0	0	0	0	0	0
n	220	0	0	0	0	0	0	0	0	0
W _{ni}	58,428	0	0	0	0	0	0	0	0	0
W _{vi}	726, 466	0	0	0	0	0	0	0	0	0
в ⁽¹⁾	B ⁽¹⁾		0	228	0	0	0	0	228	0
$\mathbf{P[S]}_{6} = 1 - \mathbf{P[F]}_{6} =$. 999998	. 98 36 95	. 999949	. 999998	. 999993	. 999993	. 999951

Table II. 9. Summary for FM-6.

(1) $B = Maximum value, within \pm 3 \sigma$, for all variables in the last term of Equation 30. When max, B = 228.653; when the term is ignored, B = 0. (This term should not be confused with the general notation of \tilde{X} for mean value of a parameter).

(2) Eight runs were made. Values in the table are V_f values ($\sigma = V_f \sigma_{std}$); zero values of V_f or σ have no variance, or their estimates are assumed near zero.

where the combined variabilities of propellant weight, mass flow coefficient, burning rate, throat area, maximum to average peak pressure ratio, and propellant web thickness, produces about the same reliability, namely .999951.

Failure Modes 7 through 11 inclusive. Propellant Stress Failure Modes

The propellant stress relationships are perhaps the most complex and least understood of all the solid rocket motor failure modes. For the requirement function, AGC ran a rather complex computer program on a limited propellant stress analysis, using sets of randomly selected input parameter values for each computer run to gain some feel for $R \mid \mid C$ variability, for those seven failure modes. Within the constraints of the analysis made (see Appendix I for success criteria), and the relatively few computer runs made by AGC (high computer run costs), their outputs gave reasonable preliminary estimates for the mean values of the requirement functions, \overline{R} , for Failure Modes 7 through 11.

For the capability functions, AGC used values based on their curves (see Appendix I) from which \tilde{C} estimates were made. These data for R and \tilde{C} are summarized in Table II.10 together with the estimates for standard deviations, σ . For R, the estimate of σ was obtained from the variability of the 8 computer runs. For \tilde{C} , the rationale is given in Table I.20 of Appendix I.

AGC did not supply the transfer function equations and input parameter densities. Rather, they gave the R and C output means and standard deviations, stating that R and C had Gaussian densities. Closed form solutions were used to solve for the probability of success for these failure modes. The difference of two Gaussian random variables, C - R, is also Gaussian. Thus, the probability of failure is obtained from tables of the normal function as the area in one tail of the normal curve with zero mean and unit variance beyond the point $\frac{\overline{C} - \overline{R}}{\sqrt{\sigma_{C}^{2} + \sigma_{R}^{2}}}$. Table II. 10 also summarizes these calculations, and $\sqrt{\sigma_{C}^{2} + \sigma_{R}^{2}}$ the last column gives the P[S]. A sensitivity analysis was made on two of the failure modes that yielded low estimates of P[S], FM-9 and FM-11. Note that when the principle stress storage condition has its

FM-11. Note that when the principle stress, storage condition, has its standard deviation doubled, P[S] is markedly reduced to .972. Certainly FMs 9 and 11 deserve closer inspection of the input data and the rationale used herein.

FM	FM Description	R	ô		ô	$\frac{\overline{C} - \overline{R}}{\sqrt{\sigma_C^2 + \sigma_R^2}}$	P[S]
7	Inner bore hoop strain, storage.in/in	. 037	.00374	. 242	.0392	5.20595	.999999
8	Prop/Liner radial bond stress, storage.#/in ²	2.47	. 282	18.3	2.84	7.61397	>. 999999
9a	Principle stress, stor- age, #/in ²	5.51	.604	18.3	2.84	4.405	. 999989
9Ъ	Principle stress, stor- age, #/in ²	5.51	1.208 ⁽¹⁾	18.3	5.68 ⁽¹⁾	2.2025	(. 972360) ⁽¹⁾
10	Prop/liner interface shear stress, flight #/in ²	30.62	9.52 ⁽²⁾	418	39.2	9.60301	>. 999999
lla	Inner bore hoop strain, flight, in/in.	. 0749	.00489	. 441	.0674	5.41751	>. 999999
11ъ	Inner bore hoop strain,	7.49	. 978 ⁽³⁾	44.1	8.9 ⁽³⁾	4.08887	(.999956) ⁽³⁾

Table II. 10 Summary of Propellant Stress/Strain Failure Modes in Storage and Flight Conditions

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(1) $V_f = 2 \text{ for } \sigma_R \text{ and } \sigma_C$.

(2) At less than -3σ value of R becomes negative, truncation required.

(3) $V_f = 2 \operatorname{for} \sigma_R$, and $\sim 1.3 \operatorname{for} \sigma_C$.

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Failure Mode 12. Insulation/Motor Case Interface Bond Max. Shear Stress Failure Mode, Flight Condition

Insulation/Motor Case interface bond fails in shear for a 2g maximum launch acceleration.

The failure mode requirement is that the shear stress at the chamber wall of the motor for a 2g maximum launch acceleration will also be a maximum. From the 8 grain stress computer runs that were made by AGC, a mean value for R_{12} of 30.62 psi maximum shear stress with a standard deviation of 9.52 psi was obtained (see Table I.19 of Appendix I).

No data was available from AGC on the capability distribution of shear strength for V44/Epon 948/steel bond. AGC did report, however, that the shear strength of V45/SC 58:68 epoxy-anhydride/glass could be used as a conservative estimate. From Appendix I, Table I. 22, the mean bond shear strength is given as 375 psi, with a value of 64.13 psi for one standard deviation.

Since R and C are assumed Gaussian, the probability of success is obtained from the closed form Gaussian solution. Thus, for FM-12 $\frac{\overline{C} - \overline{R}}{\sqrt{\sigma_{C}^{2} + \sigma_{R}^{2}}}$ is 5.31182; and for this value, the table of the normal

function yields $P[S]_{12} < .999$ 999. Because of the relatively small value of the failure probability, a sensitivity analysis was made. It showed that if $V_f = 2$ for σ_{C12} and σ_{R12} , then P[S] < .99. Again, this failure mode data and rationale should be more closely analyzed.

Failure Mode 13. Propellant Auto Ignition Due to Static Discharge.

Premature ignition of the motor due to propellant self-ignition from static electrical discharges, and

Failure Mode 14. Propellant Auto Ignition Due to Self-Heating.

Premature ignition of the motor due to propellant self-ignition from endothermal self-heating within the propellant, caused by propellant internal reactions.

These two failure modes are somewhat similar in that they involve premature ignition of the propellant from other than a normal ignition sequence. From the data of Appendix I, and again the assumption of Gaussian distributions for C and R for both FM13 and FM14, solution for P[S] indicates an extremely high probability of success. Thus:

$$P[S]_{13} > .999 999$$

and

-

 $P[S]_{14} > .9999999$.
APPENDIX III

COMPUTER PRINTOUTS

Introduction

This appendix contains copies of a sample of computer runs for failure modes 1 through 6. (Modes 7 through 14 were handled as closed form solutions as discussed in Section 5 of this report.) Each run contains a heading which identifies the failure mode. This is followed by the computer run output in a three-column tabular format. The first column, FROM, lists the lower bound of the (C-R) interval; the second column, TO, lists the upper bound of the interval; and the third column, PROB, shows the probability that (C-R) falls within the interval. The probability of failure by this mode is shown below the three column table, identified by the symbol P[F]. This probability is computed by linear interpolation as the probability that (C-R) is less than zero. Computer running time is shown just below the failure probability. Note that some of the times are listed as fractions, the charge unit being one-sixth of a second. Running times on time sharing computer are of course longer than batch computers but time sharing costs are much less. Data is given at the bottom of the runs. This first number in each line is the mean and the second number is the standard deviation. Recall that a Gaussian assumption is made throughout these runs on all input parameters. The remaining numbers in each line are included for purposes of the program operation.

For failure mode 2, runs using unadjusted data are referred to in the headings as nominal or standard runs. Sensitivity runs were made in runs 4, 5, 7, 8, 10, 11, 13 and 14. Eight runs are shown for FM6, and results are tabulated in table II.9. Two types of sensitivity runs were made. Runs 2 and 6 were made with B = 228.653 (see page II.24 for explanation). Table II.9 shows the variability factors used for the various runs, for the second type of sensitivity analysis.

RELFM1 13:20 SB WED 03/20/68

HOOP STRESS FAIL MODE FWD CYL SECT, FM-1, MOTOR CASE 9/10 OF TIME STANDARD RUN

7

FROM	TO	PROB
*****	*****	******
<-397.334	-397•334	0
-397+334	8961+05	3.40275 E-34
8961.05	18319•4	1.36223 E-23
18319•4	27677.8	3.21347 E-17
27677•8	37036•2	2.37702 E-12
37036.2	4639 4• 6	1•21983 E-8
46394~6	55753.	4.02486 E-6
55753.	65111•4	4.41090 E-4
65111.4	74469•8	1.26742 E-2
74469 • 8	83828 • 2	• 12379 1
83828+2	93186-6	• 368 43 Å
93186•6	102545.	• 358 558
102545.	111903 -	• 12009
111903-	121262.	1.50104 E-2
121262-	130620-	9•82185 E-4
130620.	139979•	1•49434 E-5
139979 •	149337.	5-48731 E-8
149337.	158695.	3.23650 E-11
î 58 69 5 •	168054.	1•95549 E-15
168054.	177412.	6•70829 E-21
177412.	186770.	1•20673 E-27
186770-	> 186770.	0

P[F]= 1.44472 E-35

```
TIME: 1 MINS. 33 SECS.

LISTNH5000

5010 DATA 232000,2516.6,1258.3,10

5020 DATA .95845,.00693,.003465,10

5030 DATA 1.106,.0312,.0156,10

5040 DATA 3.4E6,6120,3060,10

5050 DATA 6.2477E-3,1.9E-5,9.5E-6,10

5060 DATA .606,.00818,.00409,10

5070 DATA 6355,20.9,10.45,10

5080 DATA 1.18,.00897.004485,10

5090 DATA 85,.17,.085,10

5100 DATA 130.631,.0261,.01305,10

5110 DATA .6392,.0095,.00475,10

5120 DATA .0016,6.676E-5,3.38E-5,10
```

RELFMX 15:50 SB WED 03/20/68

——

HOOP STRESS FAIL MODE FWD CYL SECT, FM-1, MOTOR CASE 1/10 OF TIME RUN 2 1.

FROM	TO	PROB
*****	*****	********
<-169692.	-169692 •	0
-169692.	-143875.	7.02443 E-17
-143875.	-118057.	1.20510 E-6
-118057.	-92240-1	2.08646 E-5
-92240.1	-66422.9	2.39351 E-4
-66422.9	- 40605-6	2.36905 E-3
-40605.6	-14788 • 4	1.51561 E-2
-14788+4	11028.8	.055338
11028.8	36846.1	• 1 59 1 63
36846-1	62663.3	.295196
62663.3	88480.6	• 259 41
88480+6	114298 -	• 127791
114298 •	140115-	6-36229 E-2
140115.	165932.	1.80443 E-2
165932.	191750.	3.27235 E-3
191750-	217567.	3-60149 E-4
217567.	243384.	1.48032 E-5
243384	269201 .	3.16083 E-7
269201.	29 50 18 .	3.91324 E-9
29 50 18 .	320836.	4-28898 E-12
320836.	346653.	4.02567 E-19
346653.	> 346653.	0

P[F]= 4.94847 E-2

TIME: 1 MINS. 31 SECS. LI STNH5000 5010 DATA 199333, 34564, 17282, 10 5020 DATA .95845, .00693, .003465, 10 5030 DATA 1.106, .0312, .0156, 10 5040 DATA 3.4E6, 6120, 3060, 10 5050 DATA 6.2477E-3, 1.9E-5, 9.5E-6, 10 5060 DATA .606, .00818, .00409, 10 5070 DATA 6355, 20.9, 10.45, 10 5080 DATA 1.18, .00897, .004485, 10 5090 DATA 85, .17, .085, 10 5100 DATA 130.631, .0261, .01305, 10 5110 DATA .6392, .0095, .00475, 10 5120 DATA .0016, 6.676E-5, 3.38E-5, 10

RELF2 17:38 SB THU 04/11/68

INSUL BURN THRU FM-2, MOTOR CASE NOMINAL RUN STA 1 1.

FROM	ТО	PROB
*****	*****	******
< 36.9237	36.9237	0
36.9237	136.809	3.48628 E-2
136.809	236.694	•561804
236.694	336.579	.338034
336.579	436.464	4.85317 E-2
436.464	536.349	1.48401 E-2
536.349	636.234	8.68104 E-4
636.234	736.12	8.56160 E-4
736.12	836.005	1.64879 E-4
836.005	935.89	1.14193 E-5
935.89	1035.78	5.16168 E-7
1035.78	1135.66	2.33383 E-5
1135.66	1235.55	4.83562 E-9
1235.55	1335.43	0
1335.43	1435.32	3.06095 E-9
1435.32	1535.2	2.11915 E-6
1535.2	1635.09	3.92546 E-7
1635.09	1734.97	0
1734.97	1834.86	0
1834.86	1934.74	0
1934.74	2034.63	0
2034.63	> 2034.63	0

1

P[F]= 0

RAN 179/6 SEC LISTNH5000

5020 DATA 1.125,.01667,.008335,10 5030 DATA .003,.000489,.0002445,10 5040 DATA 87.5,.175,.0875,10 5050 DATA .59,.00351,.001755,10

RELFN2 17:32 SB WED 04/10/68

F

INSULATION BURN THRU FAILURE MODE-2, MOTOR CASE NOMINAL CASE STA 2 1.

FROM	TO	PROB
******	******	********
• 75•7907	75•7907	0
75-7907	175-837	3.48628 E-2
175-837	275-883	• 561804
275-883	375-929	• 338034
375.929	475+975	4-85317 E-2
475-975	576-021	1.48401 E-2
-576-021	676-067	8.68104 E-4
676.067	776+114	8.56160 E-4
776-114	876-16	1.64879 E-4
876-16	976-206	1.14193 E-5
976-206	1076-25	5-16168 E-7
1076-25	1176-3	2.33383 E-5
1176-3	1276-34	4.83562 E-9
1276-34	1376-39	0
1376-39	1476+44	3.06095 E-9
1476-44	1576-48	2.11915 E-6
1576-48	1676.53	3.92546 E-7
1676-53	1776-57	0
1776-57	1876.62	õ
1876-62	1976+67	õ
1976-67	2076+71	õ
2076 • 71	> 2076.71	õ

P[F] = 0

RAN 278/6 SEC LISTNH 5000

5000 DATA 24.5, 049, 0245, 10 5010 DATA .606, 00361, 001805, 10 5020 DATA 1.125, 01667, 008335, 10 5030 DATA .003, 000489, 0002445, 10 5040 DATA 87.5, 175, 0875, 10 5050 DATA .59, 00351, 001755, 10 RELFM2 17:50 SB WED 04/10/68

1.

INSULATION BURN THRU FAILURE MODE-2, MOTOR CASE NOMINAL CASE STA 5 7

FROM	TO	PROB
**********	******	*******
-		_
<-14.0866	-14.0866	0
-14-0866	-9.98349	5+46581 E-12
-9+98349	- 5• 88037	4.57727 E-7
-5.88037	-1.7725	7.17910 E-4
-1,77725	2+32587	3.54963 E-2
2.32587	6• 4 2899	•147657
6. 42899	10-5321	• 199825
10.5321	14.6352	• 187377
14-6352	18 • 7383	• 156787
18.7383	22 • 8 41 5	8.24432 E-2
22-8415	26-9446	4.30062 E-2
26-9446	31-0477	6.70429 E-2
31.0477	35-1508	6-32103 E-3
35-1508	39 • 2539	• 037 41
39 • 2539	43 • 3571	3.27667 E-2
43.3571	47•4602	3.13296 E-3
47.4602	51 • 5633	1•73846 E-5
51 • 5633	55+6664	1 • 578 49 E-9
55+6664	59 • 7 69 5	0
59 • 769 5	63•8726	0
63-8726	67 • 9758	0
67 • 97 58	67.9758	Ó

P[F]= 1.60934 E-2

RAN 270/6 SEC LISTNH5000

5000 DATA 85, 170, 085, 10 5010 DATA .606, 00361, 001805, 10 5020 DATA .11, 0033, 00165, 10 5030 DATA .005, 002586, 00076, 4 5040 DATA 87.5, 175, 0875, 10 5050 DATA .59, 00351, 001755, 10

RELFM2 10:46 SB THU 04/11/68

-

INSULATION BURN THRU FAILURE MODE-2,MOTOR CASE INCREASED INSULATION THICKNESS STA 5 1.

ТО	PROB
****	*******
-8.17169	0
-1.34136	4.34000 E-8
5.48898	5.98296 E-5
12.3193	6.69687 E-3
19.1496	8.15602 E-2
25.98	.201266
32.8103	.207558
39.6406	.171833
46.471	8.64536 E-2
53.3013	6.38087 E-2
60.1316	7.46558 E-3
66.962	9.27011 E-2
73.7923	2.19805 E-3
80.6226	2.44819 E-3
87.453	3.28294 E-2
94.2833	4.01691 E-2
101.114	2.95299 E-3
107.944	1.37432 E-7
114.774	0
121.605	0
128.435	0
> 128.435	0
	T0 ************************************

P[F]= 1.17929 E-5

RAN 276/6 SEC LISTNH5000

5000 DATA 85,.17,.085,10 5010 DATA .606,.00361,.001805,10 5020 DATA .22,.005,.0025,10 5030 DATA .005,.002586,.00076,4 5040 DATA 87.5,.175,.0875,10 5050 DATA .59,.00351,.001755,10

RELFM2 10:55 SB THU 04/11/68

INSULATION BURN THRU FAILURE MODE-2.MOTOR CASE POL DATA FOR EROS RATE AT 5030 STA 5 1. 7

FR *****	OM	7 0	PR08
-9 -9 -1 1 22 3 3 4 5 6 6 7 8 8 9 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	•23797 •23797 •72932 •77932 •7966 8:3053 5:8139 3:3226 0.8312 8:3398 5:8485 3:3571 0:8658 8:3744 5:8831 03:392 10.9 18:409 25:918 33:426 40:935	-9.23797 -1.72932 5.77932 13.288 20.7966 28.3053 35.8139 43.3226 50.8312 58.3398 65.8485 73.3571 80.8658 88.3744 95.8831 103.392 110.9 118.409 125.918 133.426 140.935 > 140.935	0 1.98411 E-5 8.59162 E-3 .219643 .589701 .16963 1.16532 E-2 5.71658 E-4 1.60487 E-4 3.35618 E-6 1.96193 E-5 3.72613 E-6 3.04620 E-9 2.60923 E-7 1.63801 E-6 6.05777 E-7 7.65812 E-9 0 0 0 0
P[F]= 1	•99858 E-3		

RAN 281/6 SEC LISTNH5000

5000 DATA 85,.17,.085,10 5010 DATA .606,.00361,.001805,10 5020 DATA .11,.0033,.00165,10 5030 DATA .005,.000816,.000408,10 5040 DATA 87.5,.175,.0875,10 5050 DATA .59,.00351,.001755,10

RELFM2 10:04 SB THU 04/11/68

INSULATION BURN THRU FAILURE MODE-2, MOTOR, CASE <u>STA 6</u> 1.

.....

FROM	ТО	PROB
*****	*****	*****
<-22.0431	-22.0431	0
-22.0431	-3.78184	1.41237 E-2
-3.78184	14.4794	.59387
14.4794	32.7407	.343887
32.7407	51.002	4.27197 E-2
51.002	69.2633	4.46839 E-3
69.2633	87.5245	7.34970 E-4
87.5245	105.786	1.43720 E-4
105.786	124.047	3.41082 E-5
124.047	142.308	1.30332 E-5
142.308	160.57	3.64074 E-6
160.57	178.831	4.75038 E-7
178-831	197.092	8.65461 E-7
197.092	215.353	1.09449 E-6
215.353	233.615	1.48392 E-7
233.615	251.876	1.39853 E-8
251.876	270.137	5.09671 E-10
270.137	288.399	0
288.399	306.66	0
306.66	324.921	0
324.921	343.182	0
343.182	> 343.182	0

P[F]= .137112

281/6 SEC RAN LISTNH5000

5000 DATA 71.85,.1437,.07185,10 5010 DATA .606,.00361,.001805,10 5020 DATA .25,.01667,.008335,10 5030 DATA .005,.000816,.000408,10 5040 DATA 87.5,.175,.0875,10 5050 DATA .59,.00351,.001755,10

RELFM2 11:28 SB THU 04/11/68

INSULATION BURN THRU FAILURE MODE-2, MOTOR CASE INCREASED INSULATION RUN STA 6

1.

FROM	TO	PROB
*****	****	*****
<-12.8636	-12,8636	0
-12.8636	13.9958	1.41251 E-2
13.9958	40.8551	•593872
40.8551	67.7145	•343883
67.7145	94.5739	4.27197 E-2
94.5739	121.433	4.46839 E-3
121.433	148.293	7.34970 E-4
148.293	175.152	1.43720 E-4
175.152	202.011	3.41082 E-5
202.011	228.871	1.30332 E-5
228.871	255.73	3.64074 E-6
255.73	282.589	4.75038 E-7
282.589	309.449	8.65461 E-7
309.449	336.308	1.09449 E-6
336.308	363.168	1.48392 E-7
363.168	390.027	1.39853 E-8
390.027	416.886	5.09671 E-10
416.886	443.746	0
443.746	470.605	0
470.605	497.464	0
497.464	524.324	0
524.324	> 524.324	0

P[F]= 6.76484 E-3

RAN 284/6 SEC LISTNH5000

5000 DATA 71.85,.1437,.07185,10 5010 DATA .606,.00361,.001805,10 5020 DATA .375,.025,.0125,10 5030 DATA .005,.000816,.000408,10 5040 DATA 87.5,.175,.0875,10 5050 DATA .59,.00351,.001755,10

RELFM2 11:06 SB THU 04/11/68

INS<u>ULATION BURN THRU FAILURE MODE-2,MOTOR CASE</u> INCREASED INSULATION RUN STA 6 1.

FROM PROB TO ************** < .902925 .902925 0 .020274 .902925 33.8674 33.8674 .581951 66.832 .344343 66.832 99.7965 99.7965 132.761 .046933 5.34132 E-3 132.761 165.726 165.726 198.69 9.36390 E-4 1.40368 E-4 5.43655 E-5 198.69 231.655 264.619 297.584 231.655 1.16281 E-5 264.619 1.14136 E-5 297.584 330.548 330.548 363.513 5.29968 E-7 396.477 3.78680 E-7 363.513 396.477 429.442 1.35102 E-6 429.442 462.406 7.16786 E-7 5,38941 E-8 462.406 495.371 495.371 528.335 5.09671 E-10 528.335 561.3 0 594.264 561.3 0 594.264 627.229 0 Õ 627.229 660.193 660.193 > 660.193 0

P[F] = 0

RAN 279/6 SEC

*** OFF AT 11:20 ELAPSED TERMINAL TIME = 87 MIN.

R'UN

. . . .

F----

INSULATION BURN THRU FAILURE MODE-2, MOTOR CASE NOMINAL CASE <u>STA 7</u> 1.

-1

FROM	ТО	PROB
*****	*****	******
<-10.6096	-10.6096	0
-10.6096	12.0817	2.39327 E-2
12.0817	34.773	•574877
34.773	57.4643	.341176
57.4643	80.1556	5.17988 E-2
80.1556	102.847	6.92150 E-3
102.847	125.538	1.02544 E-3
125.538	148.23	1.53648 E+4
148.23	170.921	8.79634 E-5
170.921	193.612	3.90992 E-6
193.612	216.303	1.85895 E-5
216.303	238.995	1.54487 E-6
238,995	261.686	5.49667 E-8
261.686	284.377	7.16786 E-7
284.377	307.069	1.58068 E-6
307.069	329.76	1.59826 E-7
329.76	352.451	3.06095 E-9
352.451	375.143	0
375.143	397.834	Ō
397.834	420.525	0
420.525	443.216	0
443.216	> 443.216	0

P[F]= .01119

RAN 286/6 SEC LISTNH 5000

5000 DATA 70.57,.1411,.07055,10 5010 DATA .606,.00361,.001805,10 5020 DATA .43,.01667,.008335,10 5030 DATA .006,.000979,.0004895,10 5040 DATA 87.5,.175,.0875,10 5050 DATA .59,.00351,.001755,10

RELFM2 10:36 SB THU 04/11/68

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INSULATION BURN THRU FAILURE MODE-2,MOTOR CASE INCREASED INSULATION THICKNESS STA 7 1.

то

-6.5389

21.7249

49.9887 78.2525 .344271 4.70051 E-2 78.2525 106.516 106.516 5.24869 E-3 134.78 1.02904 E-3 134.78 163.044 1.40368 E-4 163.044 191.308 5.43655 E-5 191.308 219.571 1.16281 E-5 219.571 247.835 247.835 276.099 1.14136 E-5 5.29968 E-7 276.099 304.363 3.78680 E-7 332.626 304.363 1.35102 E-6 332.626 360.89 389.154 7.16786 E-7 360.89 417.418 5.38941 E-8 389.154 5.09671 E-10 417.418 445.682 473.945 445.682 0 473.945 502.209 0 0 502.209 530.473 530.473 558.737 > 558.737 0 558.737 0

PROB

o

2.06893 E-2

.581536

P[F]= 4.78651 E-3

FROM

<-6.5389

-6.5389

21.7249

RAN 285/6 SEC LISTNH 5000

5000 DATA 70.57,.1411,.07055,10 5010 DATA .606,.00361,.001805,10 5020 DATA .516,.025,.0125,10 5030 DATA .006,.000979,.0004895,10 5040 DATA 87.5,.175,.0875,10 5050 DATA .59,.00351,.001755,10

RELFM2 10:30 SB THU 04/11/68

.

INSULATION BURN THRU FAILURE MODE-2, MOTOR CASE INCREASED INSULATION THICKNESS STA 7 1. -1

FROM	то	PROB
*****	*****	******
< 5.3014	5.3014	0
5.3014	38.8103	2.39327 E-2
38.8103	72.3191	•574877
72.3191	105.828	.341176
105-828	139.337	5.17988 E-2
139.337	172.846	6.92150 E-3
172.846	206.355	1.02544 E-3
206.355	239.864	1.53648 E-4
239.864	273.372	8.79634 E-5
273.372	306-881	3.90992 E-6
306-881	340-39	1.85895 E-5
340.39	373.899	1.54487 E-6
373.899	407.408	5.49667 E-8
A07. A08	440-917	7.16786 E-7
440.917	474.426	1-58068 E-6
474-426	507.934	1.59826 F-7
507.934	541.443	3-06096 F-9
541 443	574.952	0
574 052	508 A61	õ
509 A61	641 07	0
641 67	675 470	õ
641.97	012.419	0
672.479	> 012.419	U

P[F]= 0

RAN 277/6 SEC LISTNH5000

5000 DATA 70.57,.1411,.07055,10 5010 DATA .606,.00361,.001805,10 5020 DATA .645,.025,.0125,10 5030 DATA .006,.000979,.0004895,10 5040 DATA 87.5,.175,.0875,10 5050 DATA .59..00351,.001755,10

RELF2 11:41 SB THU 04/11/68

-

INSUL BURN THRU FM-2,MOTOR CASE STANDARD CASE STA 12 1.

FROM PROB ΤO *********** <-39.0822 -39.0822 0 .06472 -39.0822 15.1613 .465459 15.1613 69.4049 69.4049 123.648 .405049 4.31387 E-2 177.892 123.648 1.58754 E-2 177.892 232.135 4.54125 E-3 232.135 286.379 286.379 340.622 1.01452 E-3 2.14589 E-7 1.76083 E-4 340.622 394.866 394.866 449.109 449.109 503.353 0 557.597 2.33432 E-5 503.353 5.16170 E-7 557.597 611.84 n 611.84 666.084 720.327 666.084 0 720.327 774.571 0 774.571 828.814 2.51475 E-6 828.814 883.058 0 883.058 937.301 0 937.301 991.545 0 0 991.545 1045.79 1045.79 > 1045.79 0

.

P[F]= 4.66304 E-2

RAN 178/6 SEC LISTNH 5000

5020 DATA 3.6,.01667,.008335,10 5030 DATA .0168,2.7401E-3,1.37005E-3,10 5040 DATA 87.5,.175,.0875,10 5050 DATA .59,.00351,.001755,10

READY .

RUN

_

RELF2 11:47 SB THU 04/11/68

INSUL BURN THRU FM-2, MOTOR CASE INCREASED INSUL. RUN STA 12 1.

FROM	ТО	PROB
*****	*****	*****
< 18.5677	18.5677	ο
18.5677	99.6375	.06472
99.6375	180.707	465459
180.707	261.777	.405049
261.777	342.847	4.31387 E-2
342.847	423.917	1.58754 E-2
423-917	504.987	4.54125 E-3
504.987	586.057	1.01452 E-3
586.057	667.126	2.14589 E-7
667.126	748,196	1.76083 E-4
748-196	829-266	0
829-266	910.336	2.33432 E-5
910-336	991-406	5.16171 E-7
991.406	1072-48	0
1072.48	1153.55	õ
1153.55	1234-62	ă
1234.62	1315.69	2.51475 E-6
1315.69	1396.76	0
1396.76	1477-83	õ
1477.83	1558.89	ŏ
1558.80	1639.96	ň
1630.06	> 1639.96	õ
1003430	- 1003030	v

1

P[F]= 0

RAN 178/6 SEC

RELF2 11:51 SB THU 04/11/68

INSUL BURN THRU FM-2,MOTOR CASE INCREASED INSUL. RUN STA 12 1.

TO PROB FROM ******* <-16.8416 -15.8416 0 6.38392 E-2 -16.8416 48.5766 .49545 48.5766 113.995 .375939 113.995 179.413 179.413 244.831 4.31391 E-2 1.61639 E-2 244.831 310.249 375.667 310.249 4.25228 E-3 375.667 441.085 1.01452 E-3 441.085 506,504 1.14192 E-5 506.504 571.922 1.64879 E-4 571**.**922 637.34 0 702.758 2.37218 E-5 637.34 1.37526 E-7 702.758 768.176 833.594 768.176 0 833.594 899.012 0 899.012 964.431 0 2.51475 E-6 964.431 1029.85 1029.85 1095.27 0 1095.27 0 1160.69 1160.69 1226.1 0 1226.1 1291.52 0 0 > 1291.52 1291.52

P[F]= 1.64351 E-2

RAN 178/6 SEC LISTNH5000

5020 DATA 4.32,.025,.0125,10 5030 DATA .0168,2.7401E-3,1.37005E-3,10 5040 DATA 87.5,.175,.0875,10 5050 DATA .59,.00351,.001755,10

.

RELFM3 14:34 SB FRI 03/08/68

COMBINED STRESSES FWD SKIRT FM-3, MOTOR CASE.

1.

. .

FROM TO P		PROB		
**********	*********	********	***********	******
< 2.62092	E-2 2.62092	E-2	0	
2 • 62092	E-2 9.63239	E-2	• 99 2 3 6 1	
9 - 63239	E-2 .166439	•	7 • 60727	E-3
• 166439	•236553		2 • 6 4 5 2 8	E-5
•236553	• 306665		2.64137	E-6
• 306668	-376783		1.23014	E-7
• 37 6783	• 446898		2.39640	E-6
• 446898	• 517012		1.03689	E-8
• 517012	• 587127		2-34673	E-11
• 58 71 27	• 657242		9 - 02 49 2	E-13
• 6572 42	• 727356		0	
• 727356	•797471		0	
• 79 7 47 1	•867586		0	
•867586	·937701		0	
•937701	1.00782		0	
1.00782	1.07793		G	
1.07793	1 • 1 480 4		0	
͕14604	1.21816		0	
1.21816	1.26827		G	
1 • 28827	1 - 35839		0	
i • 35839	1 - 4285		0	
1 • 428 5	> i•4285		0	

-!

P(F) = 0

TIME: 50 SECS.

LISTNH 5000

5000 DATA 129.903.0208.0104.10 5010 DATA 728.0093.00465.10 5020 DATA 2.75E7.54725.27362.5.10 5030 DATA 005.000968.000484.10 5040 DATA 00288.000334.000167.10 5050 DATA 0036.000685.3.425E-4.10

RELFMY 17:55 SB THU 04/11/68

FOWD HEAD CIRF WELD MERIOD STRESS FM-4, SPHER SECT MOTOR 1/10 OF TIME STANDARD RUN

1.

.____

FROM	то	PROB
****	****	******
<-16252.9	-16252.9	0
-16252-9	110,936	1.46022 E-25
110,936	16474.8	2.56260 E-18
16474.8	32838.6	8.58624 E-13
32838.6	49202.4	3.63771 E-9
49202.4	65566.2	9.97860 E-7
65566.2	81930.	6.15112 E-5
81930.	98293.8	1.47640 E-3
98293.8	114658	1.57795 E-2
114658.	131021.	8.60684 E-2
131021.	147385.	.243795
147385.	163749.	.343434
163749	180113.	.225681
180113.	196477.	7.11609 E-2
196477.	212841	1.16288 E-2
212841	229204	8.79079 E-4
229204.	245568	3.29577 E-5
245568 .	261932.	4.76476 E-7
261932.	278296	3.62146 E-10
278296.	294660.	9.69555 E-15
294660	311023.	8.39386 E-22
311023.	> 311023.	0

P[F]= 1.45032 E-25

RAN 497/6 SEC LISTNH 5000

5010 DATA 199300,8600,4300,10 5020 DATA .95845,.00693,.003465,10 5040 DATA 3.4E6,6120,3060,10 5050 DATA 6.2477E-3,1.9E-5,9.5E-6,10 5050 DATA 606,.00818,.00409,10 5070 DATA 6355,20.9,10.45,10 5080 DATA 1.18,.00897,.004485,10 5090 DATA 85,.17,.085,10 5100 DATA 130.428,.0456,.0228,10 5110 DATA .428,.0108,.0054,10 5120 DATA .0016,6.676E-5,3.38E-5,10 RUN .

18:11 SB THU 04/11/68 RELFM5

FAILURE OF NOZ BOLTS JNT IN TENSION DUE TO COMBD LOADS: PRETORQUE, PRESS EJECT, AND TVC MOMENT. FM 5. STANDARD RUN 1.

-;

FROM	TO PROB		
*****	*****	******	
< 17575.8	17575.8	Q	
17575.8	26907.	1.44950 E-8	
26907.	36238.3	3.00193 E-6	
36238.3	45569.6	3.47479 E-5	
45569.6	54900-8	3.23236 E-4	
54900-8	64232.1	2.25055 E-3	
64232.1	73563.4	1.10885 E-2	
73563.4	82894.6	3.78618 E-2	
82894.6	92225.9	.090463	
92225.9	101557.	.156003	
101557.	110888	.201972	
110888	120220	201972	
120220.	129551	.156003	
129551	138882.	.090463	
138882	148213.	3.78618 E-2	
148213.	157545.	1.10885 E-2	
157545.	166876.	2.25055 E-3	
166876.	176207.	3.23236 E-4	
176207.	1'85539	3.47479 E-5	
185539	194870.	3.00193 E-6	
194870-	204201	1.44950 E-8	
204201.	> 204201.	0	

P[F] = 0

RAN 455/6 SEC LISTNH 5000 5040 DATA 3.4E6,6120,3060,10 5050 DATA 6.2477E-3,1.9E-5,9.5E-6,10 5060 DATA .606,.00818,.00409,10 5070 DATA 6355,2C.9,10.45,10 5070 DATA (35),2009,10043,10 5080 DATA 1.18,.00897,.004485,10 5090 DATA 85,.17,.085,10 5120 DATA .0016,6.676E-5,3.38E-5,10 5130 DATA 14.696,.0735,.03675,10 5140 DATA .6,.077,.0385,10 5150 DATA 245307,1987,993.5,10

RELFM5 18:30 SB THU 04/11/68

FAILURE OF NOZ BOLTS JNT IN TENSION DUE TO COMBD LOADS: FRETORQUE, PRESS EJECT, AND TVC MOMENT MAX CASE RUN

1.

FROM	ТО	PROB
*****	*****	******
- 10007 0	10007 0	0
< 12927.2	12921.2	0
12927.2	22632.4	1.77511 E-10
22632.4	32337.6	1.22580 E-7
32337.6	42042.8	8.59278 E-6
42042.8	51748.	1.73523 E-4
51748.	61453.2	1.87640 E-3
61453.2	71158.4	1.08657 E-2
71158.4	80863.6	3.82026 E-2
80863.6	90568.8	9.08202 E-2
90568.8	100274.	.156075
100274.	109979.	.201978
109979.	119684.	.201973
119684.	129390.	.156003
129390.	139095.	•090463
139095.	148800.	3.78622 E-2
148800.	158505.	1.10897 E-2
158505.	168210.	2.25107 E-3
168210.	177915.	3.22902 E-4
177915.	187621.	3.36304 E-5
187621.	197326.	2.32468 E-6
197326.	207031.	1.06864 E-8
207031.	> 207031.	0

P[F]= 0

RAN 473/6 SEC LISTNH 01 PRINT"FAILURE OF NOZ BOLTS JNT IN TENSION DUE TO COMBD LOADS:" 02 PRINT"PRETORQUE I STOP. READY. LISTNH5000 5040 DATA 3.4E6,24480,12240,10 5050 DATA 6.2477E-3,1.9E-5,9.5E-6,10 5060 DATA 6.01636,.00818,10 5070 JATA 6355,83.6,41.8,10 5080 DATA 1.18,.0897,.04485,10 5080 DATA 1.18,.0897,.04485,10 5120 DATA 0016,6.676E-5,3.38E-5,10 5130 DATA 14.696,.0735,.03675,10 5140 DATA 245307,1987,993.5,10 RELFM6 19:12 SB 1HU 04/04/68

NOZ SEP DUE TO EJECT LOAD EXCEEDING PRETOURQUE LOAD. FM-6 AT LINES 2070, 3070, B=228.653 FOR MAX SENSITIVITY.MIN, B=0. STANDARD RUN B=0 1.

FRUM IU PR0B			
*********************	******		
- 150 46+ 7	0		
- 6303•04	1.52915 E-10		
2240•62	2 • 5 38 08 E-6		
11234+3	2.62024 E-5		
20327•9	2.63887 E-4		
29371•6	2•31861 E-3		
38415+3	1.33029 E-2		
47458•9	• 0439 46		
56502+6	9•48111 E-2		
65546+2	• 151854		
74539•9	• 19 3464		
83633+6	• 19 3349		
92677•2	• 15065°		
101721.	9.18133 E-2		
110765.	• 044045		
119808•	1.57835 E-2		
128852.	3•79693 E-3		
137896•	5.21572 E-4		
146939 •	4.35434 E-5		
155983.	2.88369 E-6		
165027.	2.26736 E-9		
> 165027.	0		
	IU - 15d 46.7 - 63 03.04 2240.62 1128 4.3 20327.9 29371.6 38 415.3 47 458.9 56502.6 65546.2 74589.9 33633.6 92677.2 101721. 110765. 128852. 137896. 146939. 155983. 165027. > 165027.		

P[F]= 1.90941 E+6

5040 DATA 3.4E6,6120,3060,10 5050 DATA 6.2477E-3,1.9E-5,9.5E-6,10 5060 DATA .606,.00818,.00409,10 5070 DATA 6355,20.9,10.45,10 5080 DATA 1.18,.00897,.004485,10 5090 DATA 85,.17,.085,10 5120 DATA .0016,6.676E-5,3.38E-5,10 5130 DATA 14.696,.0735,.03675,10 5140 DATA .6,.077,.0385,10

RELFM6 19:00 SB TUE 06/11/68

NOZ SEP DUE TO EJECT LOAD EXCEEDING PRETOURQUE LOAD. FM-6 AT LINES 2070,3070, =228.653 FOR MAX SENSITIVITY.MIN, B=0. B= 228.653

-1-

то	PROB
******	*****
-15750.5	0
-6715+09	1.71905 E-10
2320.37	2.54173 E-6
11355+8	2.65306 E-5
20391.3	2.74594 E-4
29 426•7	2•45044 E-3
38 462 • 2	1.36361 E-2
47 49 7 • 7	4.41442 E-2
56533+1	9•41164 E-2
65568•6	• 151874
74604.	• 193468
83639•5	• 193351
92675.	• 1 50 6 6 2
101710.	• 09 188 1
110746 •	4.40582 E-2
119781 •	1•58269 E-2
128817.	3•68919 E-3
137852 •	4-94189 E-4
146888 •	4.08014 E-5
155923 •	2.89023 E-6
164959•	2.34895 E-9
> 164959.	0
	TO -15750.5 -6715.09 2320.37 11355.8 20391.3 29426.7 38462.2 47497.7 56533.1 65568.6 74604. 83639.5 92675. 101710. 110746. 119781. 128817. 137852. 146888. 155923. 164959. > 164959.

P[F]= 1.88917 E-6

RAN 415/6 SEC

5040 DATA 3.4E6,6120,3060,10 5050 DATA 6.2477E-3,.000019,.0000085,10 5060 DATA 606,.00818,.00409,10 5070 DATA 6355,20.9,10.45,10 5080 DATA 1.18,.00897.004485,10 5090 DATA 85,.17,.085,10 5120 DATA .0016,6.676E-5,3.38E-5,10 5130 DATA 14.696,.0735,.03675,10 5140 DATA .6,.077,.0385,10

RUN

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RELFM6 17:58 SB TUE 06/11/68

NOZ SEP DUE TO EJECT LOAD EXCEEDING PRETOURQUE LOAD. FM-6 AT LINES 2070, 3070, B=228.653 FOR MAX SENSITIVITY.MIN, B=0. B=01.

-

FROM	TO	PROB
*****	*****	*****
<-97742•4	-97742•4	0
-97742.4	-80486-3	1.60919 E-6
-80486.3	-63230.2	2.20507 E-5
-63230.2	- 459 7 4 • 1	1•76269 E-4
- 459 7 4 • 1	-28718.	1.01635 E-3
-28718.	-11461.9	4.54755 E-3
-11461.9	5794.17	• 01 58 7
579 4-17	23050.3	4-31387 E-2
23050.3	40306 • 4	9.13246 E-2
40306 • 4	57562.5	• 150569
57562.5	74818•6	• 193334
74818.6	92074.6	• 193334
92074.6	109331.	• 150569
109331.	126587.	9.13246 E-2
126587.	143843.	4.31387 E-2
143843.	161099 •	1.58698 E-2
161099 •	178355.	4.54684 E-3
178355.	195611 •	1.01464 E-3
195611.	212867.	1.76445 E-4
212867.	230123.	2.37744 E-5
230123.	247380.	2.27938 E-6
247380.	> 247380.	0

P[F]= 1.63051 E-2

RAN 432/6 SEC LISTNH5000

5040 DATA 3.4E6,6120,3060,10 5050 DATA 6.2477E-3,1.9E-5,9.5E-6,10 5060 DATA 606,00818,00409,10 5070 DATA 6355,20.9,10.45,10 5080 DATA 1.18,00897,004485,10 5090 DATA 85,17,085,10 5120 DATA 0016,6.676E-5,3.38E-5,10 5130 DATA 14.696,0735,03675,10 5140 DATA 6,.154,077,10

19:09 SB TUE 06/11/68 REL FM 6

:

NOZ SEP DUE TO EJECT LOAD EXCEEDING PRETOURQUE LOAD. FM-6 AT LINES 2070, 3070, 8=228.653 FOR MAX SENSITIVITY.MIN, 5=0. E=228 . 653

1.

FROM TO PROB			
***********	******	*****	
	- 20175 4	0	
<-321/5+4	-321/3•4		
-32175+4	-21497.5	2.86101 E-9	
-21497.5	-10819-5	2.87709 E-6	
-10819.5	-141 • 58 1	4.10444 E~5	
-141-581	10536+4	5.01678 E-4	
10536+4	21214.3	3.71607 E-3	
21214.3	31892+3	1.58131 E-2	
31892.3	42570.2	4.40146 E-2	
42570.2	53248+1	9.19224 E-2	
53248 • 1	63926+1	• 1 506 49	
63926 • 1	74604.	• 193339	
74604.	85282.	• 193334	
85282 •	9 59 59 • 9	• 1 50 57 5	
9 59 59 • 9	106638•	9.13674 E-2	
106638.	117316+	4+33325 E-2	
117316.	127994.	1.60796 E-2	
12799 4.	138672.	4.43709 E-3	
138672.	1 49 3 50 •	7.89641 E-4	
149350+	160028 •	7•97663 E-5	
160028.	170706.	4.81893 E-6	
170706.	181383.	3.98219 E-8	
181383.	> 181383.	0	

P[F]= 5.05762 E-5

RAN

410/6 SEC LISTNH5000 5040 DATA 3.4E6,6120,3060,10 5050 DATA 6.2477E-3, 000019, 0000085, 10 5060 DATA .606,.00818,.00409,10 5070 DATA 6355, 20.9, 10.45, 10 5080 DATA 1.18, 00897, 004485, 10 5090 DATA 85+ .17+ .085+10

5120 DATA .0016, 6.676E-5, 3.38E-5, 10 5130 DATA 14.696, 0735, 03675, 10

5140 DATA .6+ .0924+ .0462+10

RUN

L

RELFM6 18:47 SB TUE 06/11/68

NOZ SEF	DUE TO	EJECT	LOAD	EXCI	EEDIN	NG PI	RETOURQU	E LOAD.	FM-6
AT LINE	S 2070,	3070,	=228 -	653	FOR	MAX	SENSITI	VI TY . MI	N, =0.
_B =0									
1.									

FROM TO PROB *************** <-18502+2 -18502-2 0 -18502-2 -9222.17 2.33536 E-13 -9222.17 57 • 8 4 5 2.50965 E-6 57.845 9337+86 2.39383 E-5 9337.86 18617.9 1.84368 E-4 18617.9 27897.9 1+22233 E-3 27897.9 37177.9 7.86086 E-3 3.61686 E-2 37177.9 46457.9 46457.9 55737.9 9.85807 E-2 55737.9 65017.9 -159057 65017.9 74298. -196492 74298. 83578. -193796 83578. 92858 -151247 9 28 58 🖷 .102138 • 9-26404 E-2 102138. 111418. 4.46199 E-2 111418. 120698. 1.48513 E-2 120698 • 129978 • 2.91586 E-3 129978 • 139258 • 3.06028 E-4 139258 -148538. 2.79834 E-5 1 48 538 🗸 157818. 2.56517 E-6 1.25330 E-10 157818. 167098 . 167098+ > 167098. 0

P[F]= 2.49401 E-6

RAN 430/6 SEC LISTNH5000 5040 DATA 3-4E6,6120,3060,10 5050 DATA 6.2477E-3,000076,000038,10 5060 DATA 606,00818,00409,10 5070 DATA 6355,20.9,10.45,10 5080 DATA 1-18,-00897,-004485,10 5090 DATA 85,-17,085,10 5120 DATA 0016,6.876E-5,3.38E-5,10 5130 DATA 14.696,0735,03675,10 5140 DATA -6,-077,-0385,10

RELFM6 18:28 SB TUE 06/11/68

NOZ SEP DUE TO EJECT LOAD EXCEEDING PRETOURQUE LOAD. FM-6 AT LINES 2070, 3070, B=228.653 FOR MAX SENSITIVITY.MIN, B=0. B=0 1.

FROM TO		PROB		
******	*********	*********		
<-22108+2	-22108.2	0		
-22108.2	-12546.9	7.08590 E-17		
-12546+9	-2985.64	1.09311 E-6		
-2985.64	6575+62	2.03307 E-5		
6575+62	16136.9	1-77198 E-4		
16136-9	25698+1	1.02517 E-3		
25698 • 1	35259 • 4	4+81516 E-3		
35259 • 4	44820.7	2.10748 E-2		
44820.7	54381.9	7.73554 E-2		
54381+9	639 43 • 2	• 1709 55		
639 43 - 2	73504.5	• 220067		
73504+5	83065•7	• 197828		
83065•7	92627.	• 1 5 2 1 6 1		
92627.	i02188.	9.52269 E-2		
102188.	111750 •	•044557		
111750.	121311.	•012575		
121311.	130872.	1-93422 E-3		
130872.	140433.	1.99803 E-4		
140433+	1 49 9 9 5 •	2.41170 E-5		
1 4999 5 •	159556.	2.47208 E-6		
1 59 5 56 •	169117.	6-93164 E-1'		
169117.	> 169117.	0		

P[F]= 7.44166 E-6

 RAN
 422/6
 SEC

 LISTNH5000
 5040
 DATA
 3.4E6,6120,3060,10

 5050
 DATA
 6.2477E-3,000076,000038,10

 5060
 DATA
 606,00818,00409,10

 5070
 DATA
 6355,41.8,20.9,10

 5080
 DATA
 1.18,01794,00897,10

 5090
 DATA
 85,17,085,10

 5120
 DATA
 14.696,0735,03675,10

 5140
 DATA
 6,077,0385,10

. –

RELFM6 18:36 SB TUE 06/11/68

NOZ SEP DUE TO EJECT LOAD EXCEEDING PRETOURQUE LOAD. FM-6 AT LINES 2070, 3070, B=228.653 FOR MAX SENSITIVITY.MIN, B=0. B=228.653 .

1.

FROM	то	PROB
******	******	******
<-21879.5	-21879.5	0
-21879.5	-12318.3	7.08590 E-17
-12318.3	-2756.99	1.09311 E-6
-2756.99	6804+27	2.03307 E-5
6804.27	16365.5	1+77198 E-4
16365•5	25926.8	1.02517 E-3
25926•8	35488 • 1	4.81516 E-3
35488 • 1	45049•3	2.10748 E-2
45049 - 3	54610.6	7.73554 E-2
54610.6	64171+9	• 1709 55
64171.9	73733•1	• 220067
73733 • 1	83294.4	• 19 78 28
83294+4	92855•6	• 1 52 1 6 1
92855+6	102417.	9.52269 E-2
102417.	111978 •	•044557
111978 •	121539 •	•012575
121539 •	131101.	1.93422 E-3
131101.	140662.	1.99803 E-4
140662.	150223.	2.41170 E-5
150223.	159785.	2.47208 E-6
1 59 78 5 •	169346.	6.93164 E-13
169346-	> 169346.	0

P[F]= 6.95546 E-6

 RAN
 413/6
 SEC

 LISTNH5000
 5040
 DATA
 3.4E6,6120,3060,10

 5050
 DATA
 6.2477E-3,000076,000038,10

 5060
 DATA
 606,00818,00409,10

 5070
 DATA
 635,41.8,20.9,10

 5080
 DATA
 1.18,01794,00897,10

 5090
 DATA
 65,017,085,10

 5120
 DATA
 0016,6.676E-5,3.38E-5,10

 5130
 DATA
 14.696,0735,03675,10

 5140
 DATA
 6,077,0385,10

RELFM6 18:14 SB TUE 06/11/68

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4

NOZ SEP D	UE TO EJE	CT LOAD	EXCEEDI	NG PI	RETOURQUE	LOAD. F	M-6
AT LINES	2070, 3070	B=228	• 653 · FOR	MAX	SENSITIV	ITY .MIN,	B =0
B=0							

.

. • FROM TO PROB *************** <-70769.2 -70769.2 0 -70769.2 - 57 451 . 4 2.03471 E-21 -57451+4 -44133-5 6-10704 E-15 -44133-5 -30815+6 3.72071 E-10 -30815-6 -17497.8 1.62339 E-7 -17497.8 -4179.92 6.60487 E-6 -4179.92 9137.95 1.33906 E-4 9137.95 22455+8 1.63698 E-3 35773•7 22455+8 1.21776 E-2 5.75501 E-2 35773.7 49091.5 49091.5 62409 • 4 ·161236 62409 • 4 75727.3 .267306 75727.3 89045+1 .279736 89045+1 102363. •15964 115681 • 102363. 4.94763 E-2 115681. 128999. 9.94846 E-3 128999 . 142317. 1.09352 E-3 142317. 155634+ 5.63756 E-5 168952. 182270. 1.68257 E-6 155634. 168952+ 9.18616 E-9 182270: 195588• 6.63242 E-11 > 195588+ 195588+ 0

P[F]= 4.87950 E-5

RAN 428/6 SEC LISTNH5000 5040 DATA 3.4E6,12240,6120,10

S050 DATA 6.2477E-3,000076,000038,10 S060 DATA .606,0818,0409,10 S070 DATA 6355,41.8,20.9,10 S080 DATA 1.18,01794,00897,10 S090 DATA 85,1-7,85,10 S120 DATA .0016,6.676E-5,3.38E-5,10 S130 DATA 14.696;0735,03675,10 S140 DATA .6,077,0385,10

APPENDIX IV

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APPROACH CONCEPTS AND COMPUTATION TECHNIQUE

Introduction

The $\mathbb{R} \| \mathbb{C}$ analysis concept has been described in the previous phase III-A report (66TMP-90) and in Section 3 of the body of this report but it is desirable for purposes of this study to review briefly the mechanics of the process using a simple hypothetical example.

Let us consider a system having only one failure mode which is assumed to be time independent^{*}. Let us assume that the requirement, R, is a function of the parameters X and Y, and that the capability, C, is a function of the parameters U and V. Specifically, let us assume that R = X/Y, and $C = U \cdot V$. The problem, then, is to determine the probabilistic descriptions of R and C given the probabilistic descriptions of X, Y, U, and V. The probability that C is greater than R (i.e., in this case, the probability of success, or reliability) can be computed by using the formula

prob. $\{C > R\}$ = prob. $\{(C - R) > 0\}$ = prob. $\{(U \cdot V - X/Y) > 0\}$

To evaluate this probability the density function for $(U \cdot V - X/Y)$ will be generated and the area under the function in the positive region will then be the probability value of interest.

Think of this computation as an illustration of the general approach which is a straightforward technique of using discrete approximations of continuous functions, considering all possible combinations of values, computing the probability of each combination of values, operating on the set of values appropriately to generate the output value, grouping similar output values and then computing the probability of each group. The area under each input density function was allocated to a selected set of intervals so that the combination of values referred to above are combinations of intervals of values and not combinations of discrete values—the latter is, of course, an acceptable alternate method. The density functions are combined pair-wise to reduce the total number of combinations required in the process.

As noted earlier, the capability, C, is defined by the function $(U \cdot V)$ and the requirement, R, by the function (X/Y) and the transfer function of interest by $\{(C-R) = U \cdot V - X/Y\}$. Variables U, V, X and Y each have probability density functions as shown in Figure IV.1. The figures

^{*} The assumption of independence is not a restriction on the technique but is made, merely, to simplify the illustration.

should be interpreted as follows. Looking first at the probability density function of U —the probability that the value lies between 3 and 4 is 0.1; between 4 and 5 is 0.5; and between 5 and 6 is 0.4. The probability density functions on V, X, and Y are interpreted in the same way as those for U. The widths of the intervals are not the same for all parameters and they need not be. Any appropriate widths of intervals which adequately approximate the true density functions may be used.

Figure IV. 2 illustrates the combination of the first pair of parameters, $U \cdot V$. Consider first the interval 3-4 on U and the interval 5-6 on V. All values of $U \cdot V$ resulting from these intervals will lie in a new interval having as a lower value $3 \cdot 5 = 15$, and an upper value $4 \cdot 6 = 24$. The probability associated with this new interval is $0.1 \cdot 0.1 = 0.01$, which is simply the probability that the value of U lies between 3 and 4 and the value of V lies between 5 and 6. The output of this combination of intervals is shown in Row 1 of the table. Columns 1 and 2 show the lower and upper limits of the new interval generated by combining the first interval of U with the first interval of V. Column 3 shows the probability that the new value $U \cdot V$ lies in the new interval. Columns 4, 5, and 6 show the intervals into which the outputs of the transfer of $U \cdot V$ are grouped. The probability shown in column 3 that is associated with the interval indicated by columns 1 and 2 is appropriately prorated into columns 4, 5, and 6. This process is repeated for each combination of intervals. Because U has three intervals and V has three intervals, there are nine combinations of intervals to be considered. (The numbers of intervals need not be the same.) The intervals into which the outputs of the transfer of $U \cdot V$ are to be grouped have been arbitrarily designated as 15-26, 26-37, and 37-48.

The new interval generated by the first combination of intervals is 15-24 with an associated probability of 0.01 (this is shown in the first three columns— row 1 of the table). Because this interval is wholly contained by the first interval of the output density function, the entire 0.01 is put into the 15-26 interval.

The rest of the computations for generating the output probability density function on (C - R), when (C - R) has been defined by (C-R) = $U \cdot V - X/Y$ (shown in Figures IV.3 and IV.4), are accomplished in basically the same manner as we have shown here. Figure IV.5 represents the total process. First operate on U and V according to the transfer function to produce the output $U \cdot V$. Then operate on X and Y according to the transfer function to produce X/Y. Finally, operate on $(U \cdot V)$ and (X/Y) according to the transfer function to produce $\{(C - R) = U \cdot V - X/Y\}$.

It was noted earlier that discrete densities could be presented in the form of probabilities associated with discrete values of the random variables rather than the use of intervals of values. A common method is to associate the probability with the value of the variable at the interval midpoint. For example, the density of U was given with intervals as.

U	Probability
3 - 4	0.1
4 - 5	0.5
5 - 6	0.4

Using midpoints as discrete values, we could have presented it as

U	Probability
3.5	0.1
4.5	0.5
5.5	0.4

Either of these forms is acceptable for suitable accuracy can be obtained with either one by increasing the number of classes and taking smaller intervals (smaller difference between midpoints.) We have used both techniques in our $R \| C$ analyses.

The use of continuous variable density functions in generating densities of combinations of random variables is naturally a preferred approach, but it is not always possible to carry out the complex integrations which are quite often encountered. Appendix VI gives a discussion of the process and it includes a number of examples for which integrations could be performed and thus closed form solutions obtained. It also includes a few cases for which integrations were too complicated to be carried out. It is instructive to observe that the discrete example presented here does provide a guideline for understanding the continuous cases because the mathematical techniques are the same in essential characteristics even though the steps do appear very different.

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Figure IV-1, Combination of random variables.



Figure IV-2. Combination of random variables.



Figure IV-3. Combination of random variables.

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Figure IV-4. Combination of random variables.

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Figure IV-5. Combination of random variables.
The examples discussed thus far in this section involved independence of input parameters and transfer functions. The extension to a dependent situation is not difficult conceptually, but it does involve some computational complications. Hence, we are including a discussion of the treatment of dependency in the following section. Computations When There is Dependence Between Two or More Transfer Functions

Suppose we have two transfer functions,

 $U = T_1(x_1, x_2, ..., x_m)$ and $v = T_2(y_1, y_2, ..., y_n)$

and suppose that there exists some type of correlation between the input variables, implying therefore a correlation between the outputs, U and v. Such correlation may arise from the fact that one or more x variables are identical with y variables. On the other hand, it might arise in the form of statistical correlation rather than from matching variables.

We wish to determine a computational procedure which permits us to handle any of these cases, and we will also show simplified methods for the independent and the identical variable cases. The initial step will consist of a description of the process in a functional format. This will be followed by some simple discrete examples to illustrate the mathematics involved. Expressing this in terms of only two functions is no real restriction—the extension to more is elementary.

For simplicity of presentation, we will let m = 3 and n = 4. Thus, the two transfer functions are

 $u = T_1(x_1, x_2, x_3)$ and $v = T_2(y_1, y_2, y_3, y_4)$.

We will describe what must be computed, not being concerned at this point with the time sequence in which the various tasks are performed. It will be convenient to phrase the description entirely in terms of discrete variables—the extension to the continuous case is obvious.

Select a specific set of values of the input parameters. For this set, compute the associated u and v values by substituting in the transfer functions $T_1(x_1, x_2, x_3)$ and $T_2(y_1, y_2, y_3, y_4)$. From the joint density of the x's and y's compute the probability of the occurrence of the selected combination of x and y values. Using the standard probability notation, this probability computation is expressed by the equation

$$p(x_{1}, x_{2}, x_{3}, y_{1}, y_{2}, y_{3}, y_{4}) = p(x_{1})p(x_{2}|x_{1})p(x_{3}|x_{1}, x_{2})p(y_{1}|x_{1}, x_{2}, x_{3})p(y_{2}|x_{1}, x_{2}, x_{3}, y_{1})$$
$$p(y_{3}|x_{1}, x_{2}, x_{3}, y_{1}, y_{2})p(y_{4}|x_{1}, x_{2}, x_{3}, y_{1}, y_{2}, y_{3}) .$$

Repeat these computations for every possible combination of input parameters. Find the probability of a selected u and v pair by adding together the probabilities for every combination of parameters which yield the u, v pair under consideration. Do this same thing for every possible u, v pair, thus generating the joint density of u and v.

Of course this description includes the case of independence in which the indicated conditional probabilities are in reality equal to the unconditional ones. Let us express this in basic probability language. Take as an example the probability

$$p(y_1|x_1, x_2, x_3)$$
.

If y_1 is correlated with one or more of the x's, then the density of y_1 is modified if x_1 , x_2 and x_3 are fixed. This modification of the y_1 density is a reflection of the dependence. However, if y_1 is independent of x_1 , x_2 , and x_3 , then its density is not modified and we would have

$$p(y_1) = p(y_1 | x_1, x_2, x_3).$$

Thus we see that the computational task is one of adjusting densities after the determination of each parameter value. It is clear that this description does indeed cover dependence whether or not it is generated by the occurrence of the same variables in the two transfer functions. The extension to more than two functions is quite clearly indicated by the above presentation.

Examples to Show the Mathematics Involved in Treating Dependency Between Transfer Functions with Discrete Input Parameters

Let us express these examples in terms of capability vs requirement in reliability analysis, C and R respectively. We will illustrate independence as well as the two kinds of dependence—one resulting from the occurrence of identically the same variable in C and R and the other resulting from a correlation without variable identity. This treatment should be viewed as a display of the computational task and not as a description of an optimal computation methodology.

Suppose the transfer functions are

Capability:	С	Ξ	×1 a	and
Requirement:	R	=	×2 +	z.

We have chosen to use a notation common to capability vs requirement analysis instead of the more general functional notation described earlier. This should not create any real confusion. The variables x_1 and x_2 will be treated under three different assumptions corresponding to the three cases identified above. In each of the cases, the variable densities will be as follows.

×1	p(x1)	×2	p(x ₂)	у	p(y)	z	p(z)	
1	. 3	1	. 3	1	.1	1	. 2	
2	.5	2	.5	2	.4	2	. 2	
3	. 2	3	. 2	3	. 3	3	.6	
				4	.2			

The general probability symbolism is needed later in the discussion so we used it here instead of the general function notation. We chose $p(x_1)$ to be the same as $p(x_2)$ in order to fit them into the dependency case involving identical variables.

With respect to x_1 and x_2 , the basic input probabilities needed in this analysis can be expressed as the four densities

$$p(x_1)$$
, $p(x_2)$, $p(x_1, x_2)$ and $p(x_2|x_1)$

shown in Table IV.6.

The basic formula for each of the three cases is

$$p(x_1, x_2) = p(x_1) p(x_2 | x_1)$$
.

However, in the first case in which x_1 and x_2 are independent, the joint density reduces to the product of the single parameter densities since

$$p(x_2 | x_1) = p(x_2)$$
,

giving

$$p(x_1, x_2) = p(x_1) p(x_2)$$
.

For example, take $x_1 = 2$ and $x_2 = 3$. Then we have

$$p(x_1 = 2, x_2 = 3) = p(x_1 = 2)p(x_2 = 3)$$
$$= (.5)(.2)$$
$$= .10$$
and
$$p(x_2 = 3 | x_1 = 2) = p(x_2 = 3) = .2.$$

In the second case, we have x_1 and x_2 identically the same which means that

$$p(x_2|x_1) = 1$$
 if $x_2 = x_1$
= 0 if $x_2 \neq x_1$.

Case Identification]	Conditional Probabilities				Joint Density				
		$p(x_2 x_1)$					p(x ₁ , x ₂)			
	*2	1	*1 2	3	p(x ₂)	*2	1	*1 2	3	p(x ₂)
Independent	1	.3	.3	.3	. 3	1	.09	.15	. 06	. 3
	2	. 5	.5	.5	.5	2	.15	. 25	.10	. 5
	3	. 2	. 2	. 2	. 2	3	.06	.10	.04	. 2
	p(x ₁)	.3	.5	. 2		p(x ₁)	.3	. 5	. 2	
		p(x	2 ^x 1)			p(x ₁	, x ₂)		
Dependent	*2	1	*1 2	3	p(x ₂)	*2	1	x 1 2	3	p(x ₂)
$x_1 \equiv x_2$	1	1	0	0	.3	1	. 3	0	0	. 3
	2	0	1	0	.5	2	0	.5	0	.5
	3	0	0	1	. 2	3	0	0	. 2	. 2
	p(x ₁)	. 3	.5	. 2		p(x ₁)	. 3	. 5	. 2	
		p(x	$2^{ x_1 }$)			p(x ₁	, x ₂)		
Dependent	*2	1	*1 2	3	p(x ₂)	*2	1	*1 2	3	p(x ₂)
x_1 and x_2	1	.5	. 2	. 25	.3	1	.15	.10	. 05	.3
correlated	2	.5	.5	.50	. 5	2	.15	. 25	.10	.5
but $x_1 \neq x_2$	3	0	. 3	. 25	. 2	3	0	.15	.05	. 2
	p(x ₁)	.3	.5	. 2		p(x ₁)	. 3	.5	. 2	

Table IV.6. Probabilities involving x_1 and x_2 .

.

Therefore we have

$$p(x_1, x_2) = p(x_1)$$
 if $x_2 = x_1$
= 0 if $x_2 \neq x_1$

For the third case in which x_1 and x_2 are correlated but are not identical, we merely use the general formula

$$p(x_1, x_2) = p(x_1)p(x_2|x_1)$$
.

Regardless of the relationship between x_1 and x_2 , in our example it is always true that y and z are uncorrelated. Hence, we can form the joint density, p(y,z), for each case. The density, p(y,z), is

z y	1	2	3	4	p(z)
1 2 3	.02 .02 .06	.08 .08 .24	.06 .06 .18	.04 .04 .12	.2 .2 .6
p(y)	.1	.4	. 3	. 2	

We can express the $p(x_1, x_2, y, z)$ density in the format of the p(y, z) density, three rows and four columns, in which each element is a three by three matrix formed as the product of the single p(y, z) probability and the entire three by three $p(x_1, x_2)$ density. For each column, there corresponds a particular pair of x_1 and y values and for each row, there is a particular pair of x_2 and z values. Therefore, we can identify a C value for each column and an R value for each row as shown in the three $p(x_1, x_2, y, z)$ densities which follow. The row and column x_1 and x_2 values, 1, 2, and 3, increase from left to right and top to bottom respectively.

y	1	2	3	4		R
1	.0018 .0030 .0012	.0072 .0120 .0048	.0054 .0090 .0036	.0036 .0060 .0024	.0600	2
	.0030 .0050 .0020	.0120 .0200 .0080	.0090 .0150 .0060	.0060 .0100 .0040	.1000	3
	.0012 .0020 .0008	.0048 .0080 .0032	.0036 .0060 .0024	.0024 .0040 .0016	.0400	4
2	.0018 .0030 .0012	.0072 .0120 .0048	.0054 .0090 .0036	.0036 .0060 .0024	.0600	3
	.0030 .0050 .0020	.0120 .0200 .0080	.0090 .0150 .0060	.0060 .0100 .0040	.1000	4
	.0012 .0020 .0008	.0048 .0080 .0032	.0036 .0060 .0024	.0024 .0040 .0016	.0400	5
3	.0054 .0090 .0036	.0216 .0360 .0144	.0162 .0270 .0108	.0108 .0180 .0072	.1800	4
	.0090 .0150 .0060	.0360 .0600 .0240	.0270 .0450 .0180	.0180 .0300 .0120	.3000	5
	.0036 .0060 .0024	.0144 .0240 .0096	.0108 .0180 .0072	.0072 .0120 .0048	.1200	6
	.0300 .0500 .0200	.1200 .2000 .0800	.0900 .1500 .0600	.0600 .1000 .0400		
с	1 2 3	2 4 6	3 6 9	4 8 12		

Table IV. 7. Independent case. Values of $p(x_1, x_2, y, z)$, C, and R for every possible combination of variables.

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Table IV.8. Independent case. Worksheet to generate joint density of C and R.

R	1	2	3	4	6	8	9	12	Sum
2	.0018	,0030 .0072	.0012 .0054	.0120 .0036	.0048 .0090	.0060	.0036	.0024	
Sum C-R	.0018 -1	.0102 0	.0066 1	.0156 2	.0138 4	.0060 6	.0036 7	.0024 10	.0600
3	.0030 .0018	.0050 .0030 .0120 .0072	.0020 .0012 .0090 .0054	.0200 .0120 .0060 .0036	.0080 .0048 .0150 .0090	.0100 .0060	.0060 .0036	.0040 .0024	
Sum C-R	.0048 ⊒2	.0272 -1	•0176 0	.0416 1	.0368 3	.0160 5	.0096	.0064 9	.1600
4	.0012 .0030 .0054	.0020 .0050 .0090 .0048 .0120 .0216	.0008 .0020 .0036 .0036 .0090 .0172	.0080 .0200 .0360 .0024 .0060 .0108	.0032 .0080 .0144 .0060 .0150 .0270	.0040 .0100 .0180	.0024 .0060 .0108	.0016 .0040 .0072	
Sum C-R	•0096 - 3	.0544 -2	.0352 -1	.0832 0	.0736 2	.0320 4	.0192 5	.0128 8	3200
5	.0012 •0090	.0020 .0150 .0048 .0360	.0008 .0060 .0036 .0270	.0080 .0600 .0024 .0180	.0032 .0240 .0060 .0450	.0040 .0300	-0024 -0180	.0016 .0120	
Sum C-R	•0102 -4	•0578 -3	.0374 -2	•0884 -1	•0782 1	•0340 3	•0204 4	•0136 7	3400
6	.0036	.0060 .0144	.0024 .0108	.0240 .0072	.0096 .0180	.0120	.0072	.0048	
Sum C-R	,0036 -5	.0204 -4	.0132 -3	.0312 -2	.0276 0	.0120 2	.0072	.0048 6	1200
Sum	.0300	.1700	-1100	-2600	. 2300	.1000	.0600	.0400	

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C-R						Sum
-5					.0036	.0036
-4				. 0102	.0204	. 0306
- 3			. 0096	.0578	.0132	.0806
-2		.0048	.0544	.0374	.0312	.1278
-1	.0018	. 0272	. 0352	. 0884		.1526
0	.0102	.0176	. 0832		.0276	.1386
1	.0066	.0416		.0782		.1264
2	.0156		.0736		.0120	.1012
3		. 0368		.0340	.0072	.0780
4	. 0138		.0320	.0204		.0662
5		.0160	.0192			. 0352
6	. 0060	. 0096			.0048	.0204
7	. 0036			.0136		.0172
8			.0128			.0128
9		.0064				.0064
10	. 0024					.0024

Table IV.9. Independent case. Computation of C-R density.

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yz	1	2	3	4	Sum	R
1	.006	.024	. 018	. 012	. 060	2
	.010	.040	. 030	. 020	. 100	3
	.004	.016	. 012	. 008	. 040	4
2	.006	. 024	.018	.012	.060	3
	.010	. 040	.030	.020	.100	4
	.004	. 016	.012	.008	.040	5
3	.018	.072	.054	.036	.180	4
	.030	.120	.090	.060	.300	5
	.012	.048	.036	.024	.120	6
Sum	.030 .050 .020	.120 .200 .080	.090 .150 .060	.060 .100 .040		
С	1 2 3	2 4 6	3 6 9	4 8 12		

Table IV.10. Identical variable case. Values of $p(x_1, x_2, y, z)$, C, and R for every possible combination of variables.

Table IV.11. Identical variable case. Worksheet to generate joint density of C and R.

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CR	1	2	3	4	6	8	9	12	Sum
2	. 006	.024	.018	.012					
Sum C-R	.006 -1	.024 0	.018	.012 2					.060
3	. 006	.010	.018	.040 .012	.030	.020			
Sum C-R	. 006 -2	.034 -1	.018	.052 1	.030	.020			.160
4	.018	.010	.004	.040 .036	.016	.020	.012	.008	
Sum C-R	.018 -3	.082 -2	.058 -1	.076 0	.046 2	.020 4	.012	.008 8	. 320
5		.030	.004	.120	.016	.060	.012	. 008	
Sum C-R		.030 -3	.004 -2	.120 -1	.106 1	.060 3	.012 4	.008 7	.340
6			.012		.048		.036	.024	
Sum C-R			.012 -3		.048		.036 3	. 024	.120
Sum	. 030	.170	.110	. 260	. 230	.100	. 060	. 040	

Table IV.12.	Identical variable case.	Computation of
	C-R density.	

C-R						Sum
-3			.018	.030	.012	.060
-2		.006	.082	.004		.092
-1	.006	.034	.058	.120		.218
0	.024	.018	.076		.048	.166
1	.018	.052		.106		.176
2	.012		.046			.058
3		.030		.060	.036	.126
4			.020	.012		.032
5		.020	.012			.032
6					.024	.024
7				.008		.008
8			.008			.008

Sum

1.000

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y z		1			2			3			4		Sum	R
1	. 003	.002	.001	.012	.008	.004	. 009	.006	.003	.006	.004	.002	.060	2
	. 003	.005	.002	.012	.020	.008	. 009	.015	.006	.006	.010	.004	.100	3
	0	.003	.001	0	.012	.004	0	.009	.003	0	.006	.002	.040	4
2	.003	.002	.001	.012	.008	.004	.009	.006	.003	.006	.004	.002	.060	3
	.003	.005	.002	.012	.020	.008	.009	.015	.006	.006	.010	.004	.100	4
	0	.003	.001	0	.012	.004	0	.009	.003	0	.006	.002	.040	5
3	.009	.006	.003	.036	.024	.012	.027	.018	.009	.018	.012	.006	.180	4
	.009	.015	.006	.036	.060	.024	.027	.045	.018	.018	.030	.012	.300	5
	0	.009	.003	0	.036	.012	0	.027	.009	0	.018	.006	.120	6
Sum	.030	.050	.020	.120	. 200	.080	.090	.150	.060	.060	.100	.040		
С	1	2	3	2	4	6	3	6	9	4	8	12		

Table IV.13. Correlated variable case, $x \neq x$. Values of $p(x_1, x_2, y, z)$, C, and R for every possible combination of variables.

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∇c	1	2	3	4	6	0		1.2	I C.
R		-	5	т	0	0	9	. 12	Sum
2	. 003	. 002	. 001	. 008	004	004	003	002	+
		.012	. 009	. 006	.006	.004	.005	. 002	ł
Sum	.003	.014	.010	.014	.010	.004	.003	. 002	. 060
C-R	-1	0	1	2	4	6	7	10	
3	.003	.005	.002	. 020	. 008	. 010	. 006	.004	
	.003	.002	.001	.008	.004	.004	.003	.002	
1		.012	.009	.006	.015				
		.012	.009	.006	.006				
Sum	. 006	.031	.021	.040	.033	.014	. 009	.006	. 160
C-R	-2	-1	0	1	3	5	6	9	
4	.003	.003	.001	.012	.004	. 006	.003	. 002	1
	.009	.005	.002	.020	.008	.010	.006	.004	
		.006	.003	.024	.012	.012	.009	. 006	1
		.012	.009	.006	.009				
		.036	.027	.018	.015				
					.018				
Sum	.012	.062	.042	.080	. 0 6 6	.028	.018	.012	. 320
C-R	-3	- 2	-1	0	2	4	5	8	
5	.009	.003	. 001	. 012	. 004	. 006	. 003	002	
		.015	.006	.060	.024	. 030	. 018	. 012	
		.036	.027	.018	.009				
					.045				
Sum	.009	.054	.034	.090	.082	. 036	.021	.014	. 340
C-R	-4	- 3	-2	-1	1	3	4	7	
6		.009	. 003	. 036	. 012	. 018	. 009	. 006	
		·			. 027		,		
Sum		.009	.003	.036	.039	. 018	. 009	. 006	.120
C-R	-5	-4	-3	-2	0	2	3	6	
Sum	.030	.170	.110	.260	.230	.100	.060	.040	
ł									l

Table IV.14. Correlated variable case, $x_1 \neq x_2$. Worksheet to generate joint density of C and R.

Table I	IV.15.	Corre Comp	elated v utation	variable of C-I	e case, x ₁ R density.	, ≢ × ₂ .
C-R						Sum
-4				.009	.009	.018
- 3			.012	.054	.003	.069
-2		.006	.062	.034	.036	.138
-1	.003	.031	.042	.090		.166
0	.014	.021	.080		.039	.154
1	.010	.040		.082		.132
2	.014		.066		.018	.098
3		.033		.036	.009	.078
4	.010		.028	.021		.059
5		.014	.018			.032
6	.004	.009			.006	.019
7	.003			.014		.017
8			.012			.012
9		.006				.006
10	.002					.002
Sum						1.000

IV-21

Simplified Computational Procedures

Comol: 1:4---

The preceding discussion has presented a general computational method. For the independent and the identical variable cases, we can simplify the arithmetic because of the special relationships existing for these two cases.

Independent Case

When the capability, C, and the requirement, R, are independent, we can compute their densities separately and then obtain the density of the difference, C-R, thus eliminating the need to derive the four variable density used in the general approach. The arithmetic is summarized as follows. First consider the computation for C and R.

	Capab	ility		Requirement					
	C =	×1 ^y		$R = x_2 + z$					
y x1	1,.3	2,.5	3,.2	z x 2	1,.3	2,.5	3,.2		
1,.1 2,.4 3,.3 4,.2	1,.03 2,.12 3,.09 4,.06	2,.05 4,.20 6,.15 8,.10	3,.02 6,.08 9,.06 12,.04	1,.2 2,.2 3,.6	2,.06 3,.06 4,.18	3,.10 4,.10 5,.30	4,.04 5,.04 6,.12		

Each tabular entry consists of a pair of numbers, the first one being the value of the input parameter or the output capability or requirement as the case may be, and the second number being the associated probability. This "pair" notation will be used throughout this section. The function densities are obtained by collecting terms.

С	= x ₁	y Proba	ability	R	$= x_2^{+2}$	z Probability		
	Val	ue			Valu	ıe		
	1	.03			2	.06	=	.06
	2	.12 + .05	= .17		3	.10 + .06	=	.16
	3	.09 + .02	= .11		4	.04 + .10 + .18	=	. 32
	4	.06 + .20	= .26		5	.04 + .30	=	.34
	6	.15 + .08	= .23		6	.12	=	.12
	8	.10	= .10					
	9	.06	= .06					
	12	.04	= .04					

The C-R density is computed in the following tables, again using the paired notation in which the first number is the value and the second is the probability.

We will compute the density of C-R for the identical variable case in two ways. Since $x_1 \equiv x_2$, we can drop the subscripts. The problem is to take each value of x and compute all corresponding values of xy and x + z with associated probabilities, keeping proper identification. This is accomplished in the following table. The columns of blocks are identified by an x value and the rows of blocks by a y value. Within the blocks we have a sequence of values and associated probabilities corresponding to

xy, x + z for z = 1, x + z for z = 2, and x + z for z = 3.

C	R	2	.06	3	.16	4	. 32	5	. 34	6	. 12	Probability Sum
1	.03	-1	.0018	-2	.0048	- 3	. 0096	-4	. 0102	-5	. 0036	. 0300
2	.17	0	.0102	-1	. 0272	-2	.0544	- 3	.0578	-4	.0204	.1700
3	.11	1	.0066	0	.0176	- 1	.0352	-2	.0374	- 3	.0132	.1100
4	. 26	Z	.0156	1	.0416	0	.0832	-1	.0884	-2	.0312	. 2600
6	. 23	4	.0138	3	.0368	z	.0736	1	.0782	0	.0276	.2300
8	.10	6	.0060	5	.0160	4	.0320	3	.0340	2	.0120	.1000
9	.06	7	.0036	6	.0096	5	.0192	4	.0204	3	.0072	.0600
12	.04	10	.0024	9	.0064	8	.0128	7	.0136	6	.0048	.0400
Proba Sum	bility		.0600		.1600		. 3200		.3400		.1200	1.0000

-

C-R		Probability
-5	. 0036 =	. 0036
-4	. 0102 + . 0204 =	. 0306
- 3	.0096 + .0578 + .0132 =	. 0806
-2	.0048 + .0544 + .0374 + .0312 =	.1278
- 1	.0018 + .0272 + .0352 + .0884 =	. 1526
0	. 0102 + . 0176 + . 0832 + . 0276 =	.1386
1	.0066 + .0416 + .0782 =	. 1264
2	.0156 + .0736 + .0120 =	. 1012
3	.0368 + .0340 + .0072 =	.0780
4	. 0138 + . 0320 + . 0204 =	. 0622
5	. 0160 + . 0192 =	.0352
6	.0060 + .0096 + .0048 =	. 0204
7	. 0036 + . 0136 =	.0172
8	. 0128 =	. 0128
9	. 0064 =	.0064
10	. 0024 =	. 0024
Sum		1.0000

y	•		Value	Probability	Value	Probability	Value	Probability
Value	Probability	x:	1	.3	2	.5	3	. 2
		·						
1	.1	xy	1	. 03	2	. 05	3	. 02
		x+z	2	. 006	3	.010	4	. 004
		x+z	3	.006	4	.010	5	.004
		x+z	4	.018	5	.030	6	. 012
2	. 4	xy	2	.12	4	. 20	6	. 08
		x+z	2	. 024	3	.040	4	.016
		x+z	3	.024	4	.040	5	. 016
		x+z	4	.072	5	.120	6	.048
						······	<u> </u>	
3	. 3	xy	3	. 09	6	.15	9	. 06
		x+z	2	. 018	3	. 030	4	. 012
		$\mathbf{x} + \mathbf{z}$	3	.018	4	.030	5	. 012
		x+z	4	. 054	5	.090	6	.036
			·····					
4	. 2	xy	4	. 06	8	.10	12	.04
		x+z	2	.012	3	. 020	4	.008
		x+z	3	.012	4	.020	5	.008
		x+z	4	.036	5	.060	6	. 024

Associated R and C values and their respective probabilities can now be collected together as shown below, and this leads immediately to the density of C-R which is also shown.

		1					C =		
	C ≈	{	$\mathbf{R} = \mathbf{x}$	+ z			xy		
	xy	2	3	4	5	6	Sum		
	1	. 006	. 006	. 018			. 03		
	2		. 010	.010	. 030	_			
		. 024	. 024	.072					
	Sum	.024	.034	. 082	.030		. 17		
	3			. 004	. 004	. 012	-		
		.018	.018	. 054					
	Sum	. 018	.018	. 058	.004	.012	. 11		
	4		. 040	. 040	. 120		-		
		.012	.012	. 036					
	Sum	. 012	.052	. 076	.120		. 26		
	6		•	. 016	. 016	. 048	-		
			.030	.030	. 090				
	Sum		.030	.046	.106	.048	. 23		
	8		. 020	. 020	. 060		. 10		
	9			. 012	. 012	. 036	. 06		
	12			. 008	.008	. 024	. 04		
				······			-		
Sum:	R=x+z	.060	.160	. 320	. 340	.120	1.00		
С-	R = xy	- (x+z)							Probability
								_	,
		- 3	.018 +	030 +	+.012			=	. 060
		-2	.006 +	.082 +	⊦.004			=	. 092
		-1	.006 +	034 +	+.058 +	.120		~	. 218
		0	.024 +	. 018 +	+.076 +	.048		=	.166
		1	.018 +	.052 +	106			=	.176
		2	.012 +	046				=	.058
		3	.030 +	.060 +	+.036			=	. 126
		4	.020 +	. 012				=	. 032

5 .020 + .012

6.024

7.008

. 008

8

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. 032

.024

. 008

.008

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=

=

=

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Consider now a direct computation of the density of C-R by first generating a formula for this difference, namely

$$C-R = xy - (x+z)$$

= $x(y-1)-z$.

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We can now compute all possible values of C - R together with their associated probabilities. This is shown below as a three step process in which we determine

- (1) values of x(y-1) and associated probabilities,
- (2) values of x(y-1)-z and associated probabilities,
- (3) density of C-R = x(y-1)-z by combining values computed in (2).

						X		
			Value	Probability	Value	Probability	Value	Probability
y	y-1	p(y-1)	1	. 3	2	. 5	3	. 2
1	0	. 1	0	. 03	0	. 05	0	. 02
2	1	. 4		. 12	2	. 20	3	. 08
3	2	. 3	2	.09	4	.15	6	. 06
4	3	. 2	3	. 06	6	.10	9	. 04

z

		Value	Probability	Value	Probability	Value	Probability
x(y-1)	Probability	1	. 2	2	. 2	3	. 6
0	. 10	-1	. 020	-2	. 020	-3	.060
1	.12	0	.024	-1	. 024	-2	. 072
2	. 29	1	. 058	0	.058	-1	.174
3	.14	2	. 028	1	. 028	0	.084
4	.15	3	.030	2	.030	1	.090
6	. 16	5	. 032	4	. 0,32	3	.096
9	. 04	8	. 008	7	. 008	6	.024

_x(y-1)-z	Probability
-3	. 060
-2	. 092
-1	. 218
0	. 166
1	.176
2	.058
3	.126
4	.032
5	. 032
6	. 024
7	.008
8	. 008

APPENDIX V

COMPUTER PROCEDURES

.

Introduction

Even a very simple $R \| C$ analysis example can involve a rather heavy computational load so it was natural to try to develop computer procedures to handle such problems. Indeed, recognition of the burdensome arithmetic has been a strong deterrent to the use of this reliability analysis procedure even though the validity of the basic theory has been accepted for a long time. Furthermore, there has been a decided hesitation to use computers even when they were available, largely because of the apparent loss of control when the design engineer or analyst turned the work over to a programmer who then turned it over to the computer operator. This lack of control was reflected in an inability to react to problems as they arose and also to provide prompt reaction to or use of study results as they were developed by the computer.

These problems associated with computer usage have been largely solved by the introduction of time sharing computer systems. It was natural, therefore, for TEMPO to make use of the General Electric Time Sharing Computer System in achieving one of the major study objectives—showing that some system does exist for carrying out $R \parallel C$ analysis with the expenditure of a reasonable computational effort. Since the General Electric system turned out to be so well suited to this task and since we were not required to find more than one suitable system, no attempt was made to find others. It must be recognized, however, that even though other systems might be adaptable to this problem, the programs which we have included and the running times and costs which we have discussed in this report apply only to the General Electric system. We do not know how these items would have to be modified if one wished to adapt them to another time sharing computer system.

Some of the desirable characteristics of time sharing computer systems have been implied in the preceding discussion. It would perhaps be useful to identify them more precisely to provide an adequate back-ground for understanding and appreciating the time sharing computer system in the $R \| C$ analysis application. Since the computer is operated from a remote access teletype console, the design engineer or analyst can operate the computer from a convenient location in his own office or work area. Not only is the operating console handy,

but it is also easy to use. It is operated much like a standard typewriter which has been tied in with a telephone. The modern compiler languages have been so simplified that programming proficiency can be achieved in a very short time. This means that the design engineer, his analyst, or any other member of the staff can learn the technique and operate the computer himself or he can participate in performing a computerized $R \parallel C$ analysis. Thus control of the process is not lost by going through the programmer—operator cycle required on "batch" computers. The analyst maintains complete control and he receives his answers promptly so he can debug his program with ease in a very timely fashion. The rapidity with which the answers are generated and displayed makes it easy to perform parametric studies which realistically reflect the effects of design changes. Finally, because of its high speed, flexibility of operation, and its ability to serve many operators simultaneously, the computer costs are held to extremely low levels.

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Earlier discussion noted that the computer uses discrete densities, with the random variable expressed either in interval form or as separate distinct values. Data can be fed into the computer in one of these discrete density forms or in the form of a density function formula from which the computer will derive a discrete density approximation according to instructions programmed in by the operator. Of course it is possible to combine these different forms in a single $R \| C$ analysis.

The computer programs now available have the capability of combining random variables by a mix of any appropriate mathematical operations. In an $\mathbb{R} \| \mathbb{C}$ analysis, random variables are combined two at a time, a succession of such pair-wise combinations being used to derive the density resulting from the combination of more than two random variables.

The listings of two typical computer programs that were used in this study are included at the end of this section. The program named "F 260" is written in the Time-Sharing Fortran compiler language and it is the program that was used to illustrate a computer run as discussed in the example on the following pages. The program named "RELFMI" is written in the Time-Sharing Extended Basic compiler language and it is the program that was used to obtain the results that are shown in the discussions of the motor example in Section 5 and Appendix II. It should be noted that this particular program listing contains the instructions for doing the computations associated with the first failure mode. The only difference in the instructions for the first failure mode and those for the other failure modes occur in line number 2000 and above.

The hypothetical example that was used in Appendix IV to illustrate the process of combining random variables was also solved on the desk side computer using the program described above. The sequence of computer operations differed slightly from that used in the hand computation of the example illustrated by Figures IV.1 through IV.5. Copies of the output of the computer, Figure V.1, have been marked to show the correspondence to the results shown in Figures IV.2, IV.3 and IV.4.

Recalling that the transfer function used in the example was $\{(C - R) = U \cdot V - X/Y\}$, the computer performed the following sequence of operations:

- (1) Generate density function for (X/Y).
- (2) Save (X/Y) density function for later call-up.
- (3) Generate density function for $(U \cdot V)$.
- (4) Call back (X/Y) density function and subtract it from $(U \cdot V)$ density function thus generating the density function for (C - R).

It will be observed that notations are made on the computer output sheets to point out which of the values are inputs to the computer and which ones are outputs of the computer. The print-outs that occur before the final density function print-out (i.e., for C-R) are optional. They have been included here in order to show the sequence of computer operations.

Figure V.1 Illustration of Computer Run

USER NUMBER --8888888 **(Each user is assigned a number)** ------(Fortran compiler language) SYSTEM--FOR <---(Program is stored in computer memory) NEW OR OLD--OLD OLD PROBLEM NAME -- F260 (Name of program to be brought from WAIT. memory) ------ (Computer has found program and is READY <---ready to act) RUN <----(User's command for computer to compile program) F260 15:14 SB FRI 10/31/67 (Computer is compiling the three IN F260A Jprogram sections) IN F260B PROGRAM TO COMBINE RANDOM VARIABLES WANT TO SEE CODE, YES OR NO+(First option of program-to print-? NO out various combining operations) NUMBER, POINTS FOR FIRST DENSITY ? 4, 24, 32, 40, 48) (Description of first density function PROBABILITIES וייציי∫ ? .2..7..1 READ OPERATION CODE (1-15) (Tells computer - operation is to divide two random variables) NEXT DENSITY FROM STORAGE, YES OR NO - (At this point no den-? NO sity function has been stored) NUMBER, POINTS FOR NEXT DENSITY ? 4, 2, 4, 6, 8) (Description of second density func-PROBABILITES ftion. "Y") ? . 2, . 5, . 3 NEW OUTPUT POINTS. YES OR NO ? YES (Description of output grid for X/Y) NUMBER, OUTPOINT POINTS ? 4, 3, 10, 17, 24 WANT TO SEE DISTRIBUTION, YES OR NO ? YES

Figure V.1 Illustration of Computer Run (continued)

```
****RESULTING PROBABILITES*****
                     STOP
                                  PROBABILITY
     START
        3.00
                    10.00
                                       .8206
                                               ן (Density function for
       10.00
                    17.00
                                        .1344
                                               \int X/Y; see Fig. IV. 3
       17.00
                    24.00
                                        . 045
CHECKSUM = 1.000000
MOMENTS = 8.070917E+00 1.293864E+01 2.250325E+00 7.142340E+00
READ OPERATION CODE (1-15)
                                      -(Tells computer to save X/Y
? 11
                                        density function for later use)
READ OPERATION CODE (1-15) ←
                                      - (Tells computer-there is a new
? 15
                                        set of random variables on which
                                       to operate)
 NUMBER, POINTS FOR FIRST DENSITY
? 4, 3, 4, 5, 6
                               (Description of first density function,
 PROBABILITIES
                               (יידדיי)
? .1,.5,.4
READ OPERATION CODE (1-15)
                                       (Tells computer - operation is
? 3 ←
                                       to multiply two random variables)
NEXT DENSITY FROM STORAGE, YES OR NO←(Next density function not
? NO
                                              to be taken from storage)
 NUMBER, POINTS FOR NEXT DENSITY
? 4, 5, 6, 7, 8
                                 (Description of second density function
 PROBABILITIES
                                (113711)
? .1,.3,.6
 NEW OUTPUT POINTS, YES OR NO
? YES
                                (Description of output grid for U \cdot V)
 NUMBER, OUTPOINT POINTS
? 4, 15, 26, 37, 48
WANT TO SEE DISTRIBUTION, YES OR NO
? YES
```

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Figure V.1 Illustration of Computer Run (continued) ****RESULTING PROBABILITIES**** PROBABILITY START STOP 15.00 26.00 .1222) (Density function for 26.00 37.00 .5497 $\int U \cdot V$; see Fig. IV.2 37.00 . 3281 48.00 CHECKSUM = 1.000000MOMENTS = 3.376485E+01 4.935178E+01 -2.102505E-01 2.343323E+00READ OPERATION CODE(1-15) (Tells computer - operation is to subtract ? 2 ← a random variable from $U \cdot V$ which is now in computer) NEXT DENSITY FROM STORAGE, YES OR NO - (Tells computer that the ? YES random variable to subtract from U.V is stored) NEW OUTPUT POINTS, YES OR NO ? YES $\left. \right\}$ (Description of output grid for U·V-X/Y) NUMBER, OUTPOINT POINTS ? 7, -9, 0, 9, 18, 27, 36, 45 WANT TO SEE DISTRIBUTION, YES OR NO ? YES *****RESULTING PROBABILITIES***** STOP START PROBABILITY .00 .0046 -9.00 9.00 .0429 .00 ן (Density function for 9.00 18.00 .1601 $\int U \cdot V - X/Y$; see Fig. IV. 4 18.00 27.00 .3176 27.00 36.00 .3354 36.00 45.00 .1395 CHECKSUM = 1.000000MOMENTS = 2.569393E+01 9.235007E+01 - 3.561212E-01 2.709346E+00

....

READ OPERATION CODE(1-15) (Tells computer that there are no more calculations to make)

F260

Γ

```
00000C*****PROG FINDS PROB OF COMB *****
00005 $FILE F260D1/F260D2
            COMMON X(100),Y(200),Z(100),P(200),PP(200),RP(100),S(100)
00010
20
        COMMONZX(100), RPX(100), NX
       1000 FORMAT(//" PROGRAM TO COMBINE RANDOM VARIABLES")
00030
       1002 FORMAT(//" OPERATION CODE")
00040
00050, 1004 FORMAT(" ADD, 1"/" SUBTRACT, 2"/" MULTIPLY, 3"/
           +" DIVIDE, 4"/" C*X, 5"/" X**C, 6"/" SIN(X), 7"/
00060
           +" COS(X), 8"/" LOG(X), 9"/" EXP(X), 10"/
00070
           +" SAVE DISTRIBUTION, 11"/
00080
           +" HALVE INTERVALS BOTH/FIRST/SECOND, 12/13/14"/
00090
           +" RESTART, 15 OR GREATER")
00100
00110
      1006 FORMAT(//"READ OPERATION CODE(1-15)")
00120
       1010 FORMAT(///" NUMBER, POINTS FOR FIRST DENSITY")
00130
       1015 FORMAT(" PROBABILITIES")
       1030 FORMAT(" NUMBER, POINTS FOR NEXT DENSITY")
00140
       1040 FORMAT(/" NEXT DENSITY FROM STORAGE, YES OR NO")
00150
       1060 FORMAT(//"****RESULTING PROBABILITIES*****")
00160
       1070 FORMAT("CHECK SUM =", F10.6)
00170
       1080 FORMAT(//5X,"START",10X,"STOP",6X,"PROBABILITY")
00180
       2000 FORMAT(" NUMBER, OUTPOINT POINTS")
00190
       2020 FORMAT(" NEW OUTPUT POINTS, YES OR NO")
00200
       2040 FORMAT(/"(",14,") AND (",14,") POINTS")
00210
       2060 FORMAT(/"MAX CUMULATIVE PROB DIFFERENCE =", 1PE14.6)
00220
       2080 FORMAT(/"WANT TO SEE DISTRIBUTION, YES OR NO")
00230
00240
       3000 FORMAT("MOMENTS =",4(1PE14.6))
       3020 FORMAT(/" WANT TO SEE CODE, YES OR NO")
00250
00255
        3040 FORMAT(A3)
            IYES=/ 702562
00260
00270
            PRINT 1000
            PRINT 3020
00280
            READ(1), IY
00290
291 PRINT3040, IY
            IF(IY-IYES)10, 5, 10
00300
          5 PRINT 1002
00310
            PRINT 1004
00320
       10 PRINT 1010
330
00340
            LSD=0
00350
            READ(1), M, (Z(K), K=1, M)
            PRINT 1015
00360
00370
            JM1 = M - 1
00380
            READ(1), (RP(1), I=1, JM1)
         15 PRINT 1006
00390
00400
            READ(1), ICODE
401 PRINT, ICODE
405 IF(ICODE-999)16, STOP, 16; STOP: STOP; 16: CONTINUE
00410
            IF(ICODE-14)17,17,10
00420
         17 IF(ICODE-11)30,30,20
00430
         20 LQ = ICODE - 11
00440
            GO TO (22,22,25),LQ
```

```
00450
         22 CALL HALF(N1,X)
00460
             CALL PHALF(N1M1,P)
             GO TO (25,28,25),LQ
00470
00480
          25 CALL HALF(N2,Y)
             CALL PHALF(N2M1, PP)
00490
         28 PRINT 2040,N1,N2
00500
00510
            LSD=ICODE
00520
             ICODE=LCODE
00530
             GO TO 100
00540
         00550
         31 DO 38 I=1, JM1
00560
         38 P(I)=RP(I)
00570
            DO 40 I=1.M
00580
         40 X(I)=Z(I)
00590
            LSD=0
00600
            N1 = JM1 + 1
00610
            N1M1=N1-1
            GO TO (41,41,41,41,49,49,49,49,49,49,49), ICODE
00620
         41 PRINT 1040
00630
00640
            READ(1), IY
641 PRINT 3040, IY
00650
             IF(IY-IYES)48,42,48
00660
         42 DO 43 I=1,NX
00670
         43 Y(I)=ZX(I)
00680
            N2M1 = NX - 1
00690
            N2=NX
            DO 44 I=1,N2M1
00700
00710
         44 PP(I)=RPX(I)
00720
            GO TO 49
         48 PRINT 1030
00730
00740
            READ(1), N2, (Y(I), I=1, N2)
            PRINT 1015
00750
00760
            N2M1=N2-1
00770
            READ(1), (PP(I), I=1, N2M1)
         49 PRINT 2020
00780
00790
            READ(1), IY
791 PRINT3040, IY
00800
            IF(IYES-IY)100,50,100
00810
         50 PRINT 2000
            READ(1),M, (Z(I), I=1,M)
00820
        100 CALL ADDER (N1M1, N2M1, M, ICODE)
00830
            LCODE=ICODE
00840
00850
            MT = M
00860
        155 MT=MT-1
00870
            IF(RP(MT))156,156,157
        156 IF(MT-1)157,157,155
00880
00890
        157 JM1=MT
00900
            T=R=CM=0.
00910
            IF(LSD-12)130,120,120
        120 DO 125 I=1, JM1
00920
```

F260 CONTINUED

00930		T=T+RP(I)
00940		R=R+S(I)
00950		S(I)=RP(I)
00960		D=ABSF(T-R)
00970		IF(D-CM)125,125,122
00980	122	CM=D
00990	125	CONTINUE
01000		PRINT 2060,CM
01010	130	PRINT 2080
01020		READ(1), IY
1021 PRI	NT 3	3040, IY
01030		IF(IYES-IY)135,137,135
01040	135	LX=5
01050		GO TO 140
01060	137	PRINT 1060
01070		PRINT 1080
01080		L X=1
01090	140	T=T1=T2=T3=T4=0.
01100		DO 200 I=1, JM1
01110		PQ=RP(I)
01120		XQ = Z(I) + (Z(I+1) - Z(I))/2.
01130		T=T+PQ
01140		S(I)=PQ
01150		T1 = T1 + XQ * PQ
01160		T2=T2+PQ*XQ**2
01170		T3=T3+PQ*XQ**3
01180		T4=T4+PQ*XQ**4
01190		GO TO (160,200),LX
1200	160	PRINT, Z(I), Z(I+1), RP(I)
01210	200	CONTINUE
01220		PRINT 1070,T
01230		C2=T2-T1*T1
01240		C3=T3-3•*T2*T1+2•*T1**3
01250		C4=T4-4.*T3*T1+6.*T2*T1**2-3.*T1**4
01260		C3N=C3/C2**1.5
01270		C4N=C4/C2**2
01280		PRINT 3000, T1, C2, C3N, C4N
01290		GO TO 15
01300		END
1310 \$US	SE F2	260A

.

F260A

```
00000C*****PR0B5 SEGMENT****
00010
             SUBROUTINE LOAD(TPR, ZL, ZH, M, Z, RP)
00020
             COMMON X(100),Y(200),Z(100),P(200),PP(200),RP(100),S(100)
             COMMON ZX(100), RPX(100), NX
00030
             SP=ZH-ZL
00040
             IF(SP)20,80,20
00050
00060
          20 D0 30 JL=2,M
             IF(Z(JL)-ZL)30,30,25
00070
00080
          25 ZLOW=ZL
00090
             JTEMP=JL
             GO TO 40
00100
          30 CONTINUE
00110
00120
          40 CONTINUE
             DO 60 J=JTEMP,M
00130
00140
             IF(Z(J)-ZH)50,45,45
00150
          45 JSAVE=J
00160
             ZHIGH=ZH
00170
             GO TO 70
00180
          50 ZHIGH=Z(J)
             RP(J-1)=RP(J-1)+((ZHIGH-ZLOW)/SP)*TPR
00190
             ZLOW=Z(J)
00200
          60 CONTINUE
00210
          70 RP(JSAVE-1)=RP(JSAVE-1)+((ZHIGH-ZLOW)/SP)*TPR
00220
00230
             GO TO 100
00240
          80 D0 90 J=2,M
00250
             IF(2L-Z(J-1))85,82,85
          82 RP(J-1)=RP(J-1)+TPR
00260
00270
             JSAVE=J
00580
             GO TO 100
          85 IF(ZL-Z(J))82,90,90
00290
00300
          90 CONTINUE
00310
             RP(M-1) = RP(M-1) + TPR
00350
             JSAVE=M
330 100 CONTINUE
        200 RETURN
00340
00350
             END
             SUBROUTINE HALF(N,A)
00360
00370
             DIMENSION A(1)
00380
             LX=2*N-1
             LY=N
00390
00400
             DO 20 I=1,N
             A(LX)=A(LY)
00410
             LX=LX-2
00420
00430
             LY=LY-1
00440
         20 CONTINUE
00450
             LIM=2*N-3
             DO 30 I=1,LIM,2
00460
00470
          30 A(I+1)=A(I)+(A(I+2)-A(I))/2.
00480
             N = 2 \times N - 1
00490
             RETURN
```

[---

00500		END
00510		SUBROUTINE PHALF(N,A)
00520		DIMENSION A(1)
00530		DO 20 I=1.N
00540		A(I)=A(I)/2.
00550	50	A(I+N)=A(I)
00560		N=2*N
00570		RETURN
00580		END
590 \$USE	F26	50B

```
00000C*****PR0B6 SEGMENT*****
             SUBROUTINE ADDER(N1M1,N2M1,M,ICODE)
00010
             COMMON X(100),Y(200),Z(100),P(200),PP(200),RP(100),S(100)
00050
             COMMON ZX(100), RPX(100), NX
00030
             GO TO (1,1,1,1,1,1,1,1,1,1,220), ICODE
00040
00050
           1 DO 5 I=1,M
           5 RP(I-1)=0.
00060
00070
             DO 48 K=1,N1M1
             DO 48 I=1,N2M1
00080
             GO TO (8,8,8,8,800,800,800,800,800,800), ICODE
00090
00100
           8 CONTINUE
00110
             GO TO (10,20,30,40), ICODE
00120
          10 \ O1 = X(K) + Y(I)
00130
             Q2 = X(K+1) + Y(I+1)
             Q3 = X(K) + Y(I+1)
00140
             Q4 = X(K+1) + Y(I)
00150
             GO TO 45
00160
          20 \quad Q1 = X(K) - Y(I)
00170
00180
             Q2=X(K+1)-Y(I+1)
00190
             Q3=X(K)-Y(I+1)
00200
             Q4 = X(K+1) - Y(I)
             GO TO 45
00210
00550
          30 Q1=X(K)*Y(I)
00230
             Q2=X(K+1)*Y(I+1)
00240
             Q3 = X(K) * Y(I+1)
00250
             Q4=X(K+1)*Y(I)
             GO TO 45
00260
00270
          40 Q1=X(K)/Y(I)
             Q2=X(K+1)/Y(I+1)
00280
             Q3=X(K)/Y(I+1)
00290
00300
             Q4 = X(K+1)/Y(I)
00310
          45 ZL=MIN1F(Q1,Q2,Q3,Q4)
             ZH=MAX1F(Q1,Q2,Q3,Q4)
00320
00330
             TPR=P(K)*PP(I)
00340
             CALL LOAD(TPR, ZL, ZH, M, Z, RP)
00350
          48 CONTINUE
00360
             RETURN
00370
         800 CONTINUE
             GO TO (49,49,49,49,500,500,49,49,49,49,49),ICODE
00380
00390
         500 PRINT 5000
       5000 FORMAT(/" READ CONSTANT")
00400
410
       READ(1),C;PRINT,C
          49 DO 200 I=1,N1M1
00420
             GO TO (200,200,200,200,50,60,70,80,90,100), ICODE
00430
00440
          50 Q1=C * X(I)
             Q2=C*X(I+1)
00450
00460
             GO TO 150
00470
         60 Q1=X(I)**C
00480
             Q2=X(I+1)**C
00490
             GO TO 150
```

- 1
F260B CONTINUED

1----

70	Q1=SINF(X(I))
	Q2=SINF(X(I+1))
	GO TO 150
80	Q1=COSF(X(I))
	Q2=COSF(X(I+1))
	GO TO 150
90	Q1=LOGF(X(I))
	Q2=LOGF(X(I+1))
100	Q1 = EXPF(X(I))
	Q2=EXPF(X(I+1))
150	ZL=MIN1F(Q1, Q2)
	ZH=MAX1F(Q1,Q2)
	TPR=P(I)
	CALL LOAD(TPR, ZL, ZH, M, Z, RP)
200	CONTINUE
	RETURN
220	DO 230 I=1.M
S30	ZX(I)=Z(I)
JM 1 =	=M-1
	DO 240 I=1.JM1
240	RPX(I)=RP(I)
NX=N	1
	RETURN
	END
	70 80 90 100 150 200 220 230 JM1= 240 NX=N

REL FM 1

PRINT "HOOP STRESS FAIL MODE FWD CYL SECT, FM-1, MOTOR CASE" 01 02 PRINT"9/10 ØF TIME" 03 PRINT"STANDARD RUN" 04 REM THIS IS BASIC PROG :EDI WEAVE KEL AND FM1, AND IS BASIC 05 REM PROGMS FOR RELFM1, RELFMX, RELFM4, RELFMY 10 DIM A(2,22), B(2,22), C(2,22), S(2,22) 20 H = 130 READ M1#READ S1#READ W1#READ N1 35 P=0 40 A(1,1)=M1-N1*W1 50 FØR I=2 10 21 60 A(1, I) = A(1, I - 1) + W1 70 A=(.3989423/S1)*W1 $30 A_1 = (-((A(1,I) - (W_1/2) - M_1) + 2)/(2*(S_1+2)))$ 90 $A(2, 1-1) = A \times EXP(A1)$ 95 P=P+A(2,I-1)100 NEXT I 101 FØR I=1 TØ 20 102 A(2,I) = A(2,I)/P103 NEXT I 110 READ M2#READ S2#READ W2#READ N2 115 P=0 120 B(1,1)=M2-N2*W2 130 FØR I=2 TØ 21 140 B(1,I) = B(1,I-1) + W2150 B= (• 3989 423/S2) * W2 160 B1=(-((B(1,1)-(W2/2)-M2)+2)/(2*(S2+2))) 170 $B(2,I-1) = B \times EXP(B1)$ 175 P=P+B(2,I-1) 180 NEXT I 181 FØR I=1 TØ 20 182 B(2, I)=B(2, I)/P 183 NEXT I 190 N 3= 20 200 GØ SUB 3000 220 W=(U-L)/N3 230 C(1,1)=L 240 FUR I=2 TO N3+1 250 C(1,I)=C(1,I-1)+W 255 C(2, I-1) = 0260 NEXT- L 270 FØR J=2 TØ 21 280 FØR K=2 TØ 21 290 GØ SUB 2000 300 NEXT K 310 NEXT J 315 GØ SUB 2005 320 GØ TØ (330, 390, 500) G 330 FØR I=1 TØ N3+1 340 A(1,I) = C(1,I)

```
350 A(2,I)=C(2,I)
360 NEXT I
370 IF F=0 THEN 445
375 IF F<0 THEN 4000
380 H=H+1
385 GØ TØ 110
390 FØR I=1 TØ N3+1
400 S(1, I) = C(1, I)
410 S(2, I) = C(2, I)
420 NEXT I
430 H=H+1
440 GØ TØ 30
445 FØR I=1 TØ N3+1
450 B(1,I) = S(1,I)
460 B(2,I) = S(2,I)
470 NEXT I
480 H = H + 1
490 GØ TØ 190
500 P=0
510 FOR I=1 TO N3
520 P=P+C(2,I)
530 NEXT I
540 PRINT P
545 FØR I=1 TØ 5
550 PRINT#PRINT#PRINT
555 NEXT I
560 S1=5#S2=20#S3=45
570 PRINT TAB(S1);"FRØM"; TAB(S2);"TØ"; TAB(S3);"PRØB"
580 FØR I=1 TØ 60 STEP 3
590 PRINT TAB(I); "***";
600 NEXT I
610 PRINT " "#PRINT
620 S4=5#S5=20#S6=45
625 PRINT TAB (S4-1);"<";C(1,1);TAB(S5);C(1,1);TAB(S6);C(2,0)
630 FØR I=1 TØ N3
640 PRINT TAB(S4);C(1,I);TAB(S5);C(1,I+1);IAB(S6);C(2,I)
650 NEXT I
652 PRINT TAB(S4); C(1,N3+1); TAB(S5-1); "> "; C(1,N3+1); TAB(S6); C(2,N3+1)
655 PRINT#PRINT#PRINT
660 P=0
670 I=1
680 IF C(1, I) <0 THEN 700
690 GØ TØ 760
700 IF C(1,I+1)<0 THEN 730
710 P=P+(-C(1,I)/(C(1,I+1)-C(1,I)))*C(2,I)
720 GØ TØ 760
730 P=P+C(2,1)
740 I=I+1
750 GØ TØ 630
760 PRINT "P(F)=";P
```

```
770 END
1000 N = (N3/2) + 1
1010 IF Z<C(1,N) THEN 1040
1020 N=N+5
1030 GØ TØ 1060
1040 N=N-5
1050 GØ TØ 1110
1060 FØR I=1 TØ ((N3/10)-1)
1070 IF Z<C(1,N) THEN 1160
1080 N=N+5
1090 NEXT I
1100 GØ TØ 1160
1110 FØR I=1 TØ ((N3/10)-1)
1120 IF Z>C(1,N) THEN 1180
1130 N = N - 5
1140 NEXT I
1145 IF Z<C(1,N) THEN 1230
1150 GØ TØ 1180
1160 N = N - 4
1170 GØ TØ 1190
1180 N=N+1
1190 FØR I=1 TØ 5
1200 IF Z<C(1,N) THEN 1230
1210 N=N+1
1220 NEXT I
1230 C(2, N-1) = C(2, N-1) + A(2, J-1) + B(2, K-1)
1240 RETURN
2000 GØ TØ (2010,2010,2050,2010,2050,2010,2050,2010,2050,2010,2210) H
2010 Z=(A(1, J-1)+A(1, J))*(B(1, K-1)+B(1, K))/4
2015 60 10 1000
2020 G=1#F=1
2025 RETURN
2040 G=2#F=1
2045 RETURN
2050 Z=(A(1,J-1)+A(1,J))/(B(1,K-1)+B(1,K))
2055 GØ TØ 1000
2180 G = 1 \# F = -1
2135 RETURN
2200 G=1#F=0
2205 RETURN
2210 \ Z = (-A(1, J-1) - A(1, J) + B(1, K-1) + B(1, K))/2
2215 GØ TØ 1000
2220 G=3
2225 RETURN
3000 GØ TØ (3010,3010,3050,3010,3050,3010,3050,3010,3050,3010,3210) H
3010 L=A(1,1)*B(1,1)#U=A(1,21)*B(1,21)
3020 RETURN
3050 L = A(1, 1) / B(1, 21) # U = A(1, 21) / B(1, 1)
3060 RETURN
```

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V.16
```

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RELFM1 CUNTINUED

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```
3210 L=-A(1,21)+B(1,1)#U=-A(1,1)+B(1,21)
3220 RETURN
4000 READ M2#READ S2#READ W2#READ N2
4010 B(1,1)=M2-N2*W2
4020 FØR I=2 TØ 2*N2+1
4030 B(1,I) = B(1,I-1) + w_2
4040 B=(.3989423/S2)*W2
4050 B1=(-((B(1,I)-(W2/2)-M2)+2)/(2*(S2+2)))
4060 B(2, I-1) = B \times EXP(B1)
4070 NEXT I
4090 C=20
4100 FUR I=1 TO 2*N2+1
4110 B(1,I) = EXP(B(1,I)*C)
4120 NEXT I
4130 H=H+1#60 TO 190
5010 DATA 232000, 2516.6, 1258.3, 10
5020 DATA • 95845, • 00693, • 003465, 10
5030 DATA 1.106, 0312, 0156, 10
5040 DATA 3.4E6,6120,3060,10
5050 DATA 6.2477E-3,1.9E-5,9.5E-6,10
5060 DATA • 606, • 00313, • 00409, 10
5070 DATA 6355, 20, 9, 10, 45, 10
5080 DATA 1.18, 00897, 004485, 10
5090 DATA 85, 17, 085, 10
5100 DATA 130.631.0261.01305.10
5110 DATA • 6392, • 0095, • 00475, 10
5120 DATA .0016, 6.676E-5, 3.38E-5, 10
```

APPENDIX VI

THE NATURE OF THE MATHEMATICS INVOLVED IN ANALYTICAL MODELING USING TRANSFORMATIONS OF STOCHASTIC VARIABLES

Introduction

The mathematical theory involved in the analytical modeling of system characteristics is essentially described by the title "transformations of stochastic variables". Of course these transformations are identical to those involved in the determination of volumes by integration, an obvious fact when it is recalled that probabilities are themselves integrals of density functions. We will first describe the process in the general language of the calculus and then translate it into the transfer function terminology of modeling analysis. Proofs will be omitted since they are available in standard mathematics books. We will write the relationships in terms of three variables the extension to more (or less) than three is obvious.

Consider the volume differential of a function of three variables,

f(x, y, z) dx dy dz.

Let the variables u, v, and w be related to x, y, and z by the transformation functions

We wish to transform the volume differential into the form

h(u, v, w) du dv dw.

The transformation is given by the expression

h(u, v, w) du dv dw
= f(
$$g_x(u, v, w), g_y(u, v, w), g_z(u, v, w)$$
) |J| du dv dw

where

$$J = \begin{bmatrix} \frac{\partial n}{\partial x} & \frac{\partial v}{\partial x} & \frac{\partial w}{\partial x} \\ \frac{\partial n}{\partial x} & \frac{\partial v}{\partial x} & \frac{\partial w}{\partial x} \end{bmatrix}$$

Note that we take the absolute value of the determinant J, the Jacobian or functional determinant of the transformation of x, y, z into u, v, w. Naturally we will wish to express the determinant in terms of the new variables, u, v, and w. In some cases, we may find it simpler to compute J from the relationship

$$J^{-1} = \begin{bmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} & \frac{\partial u}{\partial z} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} & \frac{\partial v}{\partial z} \\ \frac{\partial w}{\partial x} & \frac{\partial w}{\partial y} & \frac{\partial w}{\partial z} \end{bmatrix}$$

We shall consider only transformations for which $J \neq 0$ -we exclude the case of singular transformations for which J does vanish.

Let us now express this theory in the language of modeling analysis. We shall call the analytical representation of the model by the common engineering term "transfer function". Let the stochastic variables x, y, and z be the input parameters of the transfer function of interest, and, as before, denote the joint density of these parameters by f(x, y, z). Let the transfer function itself be denoted by $T_1(x, y, z)$ and define the new variables u, v, and w by the relationships

u =
$$T_1(x, y, z)$$

v = $T_2(x, y, z)$
w = $T_3(x, y, z)$

where T_2 and T_3 are essentially arbitrary, except for the condition that the Jacobian of the transformation be non-zero. We often set v and w equal to two of the original variables for this reduces the Jacobian to a simple partial derivative with respect to the other original variable. Solve these three equations for x, y, and z, giving the transformation in the form

 $x = g_{x}(u, v, w),$ $y = g_{y}(u, v, w),$ $z = g_{z}(u, v, w).$

The joint density of u, v, and w in differential form is then given by the previously indicated relationship

h(u, v, w) du dv dw $= f(g_x(u, v, w), g_y(u, v, w), g_z(u, v, w)) |J| du dv dw.$

Now we are actually interested only in the density of u, the variables v and w entering merely to permit us to define the complete transformation and we eliminate the two variables by intergration. The density of u is then obtained by carrying out this integration and by dropping du, giving

 $\begin{array}{ccc} w_2 & v_2 \\ \int & \int & h(u, v, w) \, dv \, dw \\ w_1 & v_1 \end{array}$

The integration limits are chosen in the usual way as described in the calculus. This theory will be clarified by applying it to some specific examples in which we consider a number of different transfer and density function combinations.

It should be observed that there are other mathematical procedures for deriving densities of the transformations of stochastic variables. For example, a number of such transformations are accomplished through the use of Mellin transforms in a very fine report by M. D. Springer and W. E. Thompson, G. M. Defense Research Laboratories, TR 64-46, August 1964 entitled "The Distribution of Products of Independent Random Variables". However, it was decided to restrict our discussion to cases for which we could apply the simple methods described above. Where this is not possible, we can rely on the work of Springer and Thompson as will be noted.

Some Examples of Transformations of Discrete Stochastic Variables.

Let x and y be two stochastic variables with probability density functions p(x) and p(y) respectively as indicated below*.

x	p(x)	у	р(у)
1	.3	1	.3
2	.5	2	.4
3	.2	3	.2
	-	4	.1

Densities of the reciprocal and the square of each variable are obtained merely by performing the variable transformations and leaving the probabilities unchanged. This gives the following four densities.

$\frac{1}{x}$	x ²	$p(\frac{1}{x}) = p(x^2)$	$\frac{1}{y}$	y ²	$p(\frac{1}{y}) = p(y^2)$
1 1/2 1/3	1 4 9	.3 .5 .2	1 1/2 1/3 1/4	1 4 9 16	.3 .4 .2 .1

We will now derive densities of four functions of the two variables to illustrate how we combine the variables and compute the associated probabilities. The selected functions are x + y, x - y, xy, and x/y. The detailed computations are shown below and it should be noted that these four suffice to illustrate how one could handle any other function of the two variables and also how we could extend the technique to more variables. It should be mentioned that we are assuming independence of x and y. The extension to the dependent case will be commented upon later. The basic computations are summarized in Table 6.1.

* The density function notation as used here is really the usual probability symbolism. Thus, p(x) is the probability associated with the event identified by the value of the variable x. We can think in terms of all possible x values or of a specific value the meaning is always clear in context. Hence, the use of p(x)and p(y) in our discussion does not imply identity of the densities.

Table VI.I.	le VI.1.
-------------	----------

у	р(у)	x p(x)	1 .3	2 .5	3 .2
1	. 3	p(x, y) x+y x-y xy x/y	.09 2 0 1 1	.15 3 1 2 2	.06 4 2 3 3
2	.4	p(x, y) x+y x-y xy x/y	.12 3 -1 2 1/2	.20 4 0 4 1	.08 5 1 6 3/2
3	.2	p(x, y) x+y x-y xy x/y	.06 4 -2 3 1/3	.10 5 -1 6 2/3	.04 6 0 9 1
4	.1	p(x, y) x+y x-y xy x/y	.03 5 -3 4 1/4	.05 6 -2 8 1/2	.02 7 -1 12 3/4

For each possible pair of x and y values, Table VI.1 shows the values of five different items:

- The probability of the x, y pair which, by virtue of their independence, is merely the product of their respective probabilities,
- (2) x + y,
- (3) x y,

- (4) xy, and
- (5) x/y.

For example, let x = 3 and y = 2. We have

$$p(x=3, y=2) = p(x=3) p(y=2)$$

= (.2)(.4) = .08
$$x + y = 3 + 2 = 5$$

$$x - y = 3 - 2 = 1$$

$$xy = (3)(2) = 6$$

$$x/y = 3/2.$$

Now to find the density functions of interest, we must add probabilities associated with all of the ways of obtaining each function value. For example,

> p(x - y = 1) = p(x = 2, y = 1) + p(x = 3, y = 2)= .15 + .08 = .23

All such additions are shown in Table VI.2, the values being read directly from Table VI.1.

It is obvious that the case of dependence between variables x and y can be handled quite easily. The computational procedure requires the calculation of the joint probability of each possible x, y pair, this probability then being associated with the corresponding value of the function of the pair—the x + y, x - y, or whatever it might be. Thus, we would use the conditional probability formula

$$p(x, y) = p(x) p(y | x)$$

which expresses the probability of the joint occurrence of x and y as the product of the probability of x and the probability of y, given the occurrence of x.

Table VI.2.

· · - -

x + y	Density	
2 3 4 5 6 7	.09 .15 + .12 .06 + .20 + .06 .08 + .10 + .03 .04 + .05 .02	= .09 = .27 = .32 = .21 = .09 = .02
x - y	Density	
- 3 - 2 - 1 0 1 2	.03 .06 + .05 .12 + .10 + .02 .09 + .20 + .04 .15 + .08 .06	$= .03 \\ = .11 \\ = .24 \\ = .33 \\ = .23 \\ = .06$
xy	Density	
1 2 3 4 6 8 9 12	.09 .15 + .12 .06 + .06 .20 + .03 .08 + .10 .05 .04 .02	= .09 = .27 = .12 = .23 = .18 = .05 = .04 = .02
x/y	Density	
1/4 1/3 1/2 2/3 3/4 1 3/2 2 3	.03 .06 .12 + .05 .10 .02 .09 + .20 + .04 .08 .15 .06	$\begin{array}{rcrr} = & . & 03 \\ = & . & 06 \\ = & . & 17 \\ = & . & 10 \\ = & . & 02 \\ = & . & 33 \\ = & . & 08 \\ = & . & 15 \\ = & . & 06 \end{array}$

Continuous Stochastic Variable.

Transformations and Functions to be Considered

We will consider in some detail six transformations of input stochastic variables which are described by four different density function types. These transformations and functions are as follows:

Transformations

Applied to a single variable:

Reciprocal Power

Applied to a pair of variables

Sum Difference Product Quotient

Density Functions of Input Variables

Rectangular Gaussian Gamma Cauchy

In discussing transformations of pairs of variables we will restrict our treatment to the case in which the same density type applies to each variable of the pair. We will further restrict ourselves to the case in which the variables of the pair are independent.

The expressions for these four density function types are as follows, the function parameters being subject to the usual restrictions.

Table VI.3.

Name	Density Function f(x)	Range of Variable x
Rectangular	1/a 0	0≤x≤a x<0,x>a
Gaussian	$\frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\overline{x})^2}{2\sigma^2}}$	-∞ <x<∞< td=""></x<∞<>
Gamma	$\frac{1}{\Gamma(\alpha+1)\beta^{\alpha+1}} x^{\alpha} e^{-x/\beta}$	x ≥ 0
	0	x < 0
Cauchy	$\frac{a}{\pi(a^2+x^2)}$	-∞ <x<∞< td=""></x<∞<>

Note: For simplicity and consistent with the usage of many authors, we have adopted the functional symbol, f(x), as a general identification of the density function of an input stochastic variable. It will be seen that this is a convenient symbolism and that it will cause no problem—the meaning of f(x) will be clear in context. When treating more than one density in a particular derivation, appropriate modification of the symbol will be made.

Transformations Involving Only One Stochastic Variable

Consider the stochastic variable, x, with density f(x) and the transformation of the variable defined by

$$T(x) = x^n$$

We are especially interested in two values of the exponent: n = -1 which gives the reciprocal and n = 2 which gives the square.

Denote the new variable by un. Then

$$u_n = x^n$$
 or $x = u_n^{1/n}$.

The Jacobian reduces to a single derivative in the one variable case. It is

$$J = \frac{dx}{du_n} = \frac{1}{n} \frac{1-n}{n}$$

Therefore the differential form of the density of u_n is

$$f(u_n^{1/n}) \mid \frac{1}{n} \quad u_n^{\frac{1-n}{n}} \mid du_n$$

The density function is obtained here by merely dropping the differential since there are no variables to eliminate by integration.

For the two cases of interest we will use the following notation. For the reciprocal, n = -1, we will replace u_{-1} by y and we will denote the density of y by g(y). Then

$$g(y) = f(y^{-1}) | -y^{-2} |$$
$$= y^{-2} f(y^{-1}) .$$

For the square, we will replace u_2 by z and we will represent the density of z by h(z). Then

h(z) = f(z^{1/2})
$$\left| \frac{1}{2} z^{-1/2} \right|$$

= $\frac{1}{2} z^{-1/2} f(z^{1/2})$.

A warning is appropriate at this point. Care must be exercised in the use of these formulas to take proper account of signs and variable ranges. This is of course a repetition of our experience in the calculus when these same problems were encountered. We can expect them to occur again in the **treatment** of transformations involving two variables where we will also have the problems associated with determining limits of integration. The specific derivations to be included herein will illustrate how we handle these complications.

The Density of the Reciprocal of a Stochastic Variable for the Four Functions. Using the formulas derived above, we can immediately write the density of the reciprocal of the stochastic variable for each of the four functions. They are as follows.

Rectangular:

$$g(y) = \frac{1}{ay^2} , \frac{1}{a} \le y < \infty$$
$$= 0 \qquad y < \frac{1}{a}$$

Gaussian:

$$g(y) = y^{-2} (\sqrt{2\pi} \sigma)^{-1} e^{\frac{-(y^{-1} - \overline{x})^2}{2\sigma^2}}, -\infty < y < \infty$$

Gamma:

g(y) =
$$\frac{1}{\Gamma(\alpha+1)\beta^{\alpha+1}} y^{-2-\alpha} e^{-1/\beta y}$$
, $0 \le y < \infty$

Cauchy:

$$g(y) = \frac{a y^{-2}}{\pi(a^2 + y^{-2})}$$
$$= \frac{a}{\pi(a^2 y^2 + 1)} , -\infty < y < \infty.$$

Certain aspects of the variable ranges should be noted. Of course y decreases as x increases, thus generating an inversion and the negative and positive portions of the x range required separate treatement. The following range relationships apply.

x	ra	inge	Co	orre (1	esponding y range not reversed)
0	to	a	8	to	1/a
-∞	to	0	0	to	 α
0	to	œ	8	to	0

Note the two transforms of the limit where x = 0. As we go to zero through negative values of x, y approaches $-\infty$ while on the positive x side, y approaches $+\infty$. The first of the three listed intervals applies to the rectangular density, the second and third combine to give the ranges for the Gaussian and the Cauchy densities, and the third one by itself applies to the Gamma density.

The discussion of the four reciprocal densities will be delayed until later. However, we do wish to make one observation. In the Cauchy density, if we set a = 1, it turns out that the density of y is exactly the same as the density of x, a rather interesting relationship which has implications on the densities of products and quotients of Cauchy variables as we will see.

The Density of the Square of a Stochastic Variable For the Four Functions. The transformation formulas for the square of the stochastic variable x, with density f(x), as derived above are

$$z = x^{2}$$
, $x = z^{1/2}$
 $h(z) = \frac{1}{2} z^{-1/2} f(z^{1/2})$.

However, we must take heed of the warning which followed the derivation of the function h(z) regarding the correct procedure for handling ranges over which x is negative. The method is, of course, to modify the above equations by using the absolute value of x. Thus, let

$$|\mathbf{x}| = \mathbf{z}^{1/2}$$

which merely says

$$-x = z^{1/2} \text{ for } -\infty < x \le 0,$$
$$x = z^{1/2} \text{ for } 0 \le x < \infty$$

In practice, it is usually convenient to apply the sign change on x over the negative range to modify the density f(x) before applying the square transformation, thus eliminating all negative x values. This will be illustrated in the examples given below.

First, let us look at a very simple density not discussed previously as an illustration of the sign change method.

Let $f(x) = \frac{1}{8}(x+1)$, $-1 \le x \le 3$. This is the triangular density in Figure VI.1.



Figure VI.1

Transforming the portion for the negative values of x gives

$$f(-x) = \frac{1}{8}(-x+1)$$

with new range $0 \le x \le 1$. Hence, for this range, we have

$$\frac{1}{8}(-x+1) + \frac{1}{8}(x+1) = \frac{1}{4}, \quad 0 \le x \le 1$$

and for the remaining range, we have

$$\frac{1}{8}(x+1), 1 \le x \le 3$$
.

The graph of this transformed x density is shown in Figure VI.2, the added increment being the shaded portion



Figure VI.2

We can now write the density of h(z) by applying the previously derived transformation formulas. Thus, we have

$$h(z) = \frac{1}{8} z^{-1/2}, \quad 0 \le z \le 1,$$

$$h(z) = \frac{1}{16} \frac{z^{1/2} + 1}{z^{1/2}} = \frac{1}{16} (1 + z^{-1/2}), \quad 1 \le z \le 9.$$

The range computations are quite direct. As x goes from 0 to 1, so also does z and as x goes from 1 to 3, $z = x^2$ goes from 1 to 9.

For the rectangular density, we expressed the function over a positive range on x as

$$f(x) = \frac{1}{a}, 0 \le x \le a$$
.

Hence we can write the square transformation immediately as

$$h(z) = \frac{1}{2a} z^{-1/2}, \quad 0 \le z \le a^2$$

We again encounter the negative x problem in deriving the density of the square where x has a Gaussian distribution. This is handled again by the transformation of the f(x) density for the negative range on x. Thus, for

$$f(\mathbf{x}) = \frac{1}{\sqrt{2\pi\sigma}} e^{\frac{(\mathbf{x} - \overline{\mathbf{x}})^2}{2\sigma^2}}$$

over the range $-\infty < x < 0$, we will replace x by -x, giving

$$\int_{\frac{1}{\sqrt{2\pi}\sigma}}^{\frac{1}{2\sigma^2}} e^{-\frac{(x+\overline{x})^2}{2\sigma^2}}$$

where x now ranges from 0 to $+\infty$. We replaced $(-x - \overline{x})^2$ by its equivalent, $(x + \overline{x})^2$ to simplify the exponent. It is now possible to express the complete density by adding this transform to the original density over the positive x range, giving the function

$$f^{*}(\mathbf{x}) = \sqrt{\frac{1}{2\pi\sigma}} \begin{bmatrix} e^{\frac{-(\mathbf{x} + \overline{\mathbf{x}})^{2}}{2\sigma^{2}}} & -\frac{(\mathbf{x} - \overline{\mathbf{x}})^{2}}{2\sigma^{2}} \\ e^{\frac{-(\mathbf{x} - \overline{\mathbf{x}})^{2}}{2\sigma^{2}}} \end{bmatrix}, \quad 0 \le \mathbf{x} < \infty$$

We can now apply the $z = x^2$ transformation directly to this new function, giving, for the Gaussian case,

$$h(z) = \frac{1}{2\sqrt{2\pi}\sigma} z^{-1/2} \begin{bmatrix} e^{\frac{1/2}{2\sigma^2}} & -\frac{(z^{1/2} - \overline{x})^2}{2\sigma^2} \\ e^{\frac{2\sigma^2}{2\sigma^2}} & + e^{\frac{2\sigma^2}{2\sigma^2}} \end{bmatrix}, \ 0 \le z < \infty.$$

It is interesting to note the simplification which occurs if $\overline{x} = 0$. Then we have

h(z) =
$$\sqrt{\frac{1}{2\pi\sigma}} z^{-1/2} e^{-z/2\sigma^2}$$
, $0 \le z < \infty$.

This case of the zero mean illustrates the situation in which f(x) is symmetrical about the origin and the transform on the negative x range merely changes

$$f(x)$$
, $-\infty < x < \infty$

into

Naturally, if the original range had been finite, say -c to +c, then the transformed x density would have been defined over the positive portion $0 \le x \le c$. We will encounter another symmetrical case when we treat the Cauchy distribution.

It is useful to observe that the distribution of x for the symmetrical Gaussian density is actually the well-known χ^2 density,

$$\frac{1}{2^{n/2} \Gamma(\frac{n}{2})} e^{-\chi^2/2} (\chi^2)^{\frac{n-2}{2}} d\chi^2$$

where n = 1. We wrote the differential form of the density to permit us to transform from the variable χ^2 to the variable z to establish the equivalence of these functions. Thus, let n = 1 and let

$$\chi^2 = z/\sigma^2$$
.

This gives

$$d\chi^2 = \frac{1}{\sigma^2} dz$$

Substituting in the χ^2 density, we have

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$$\frac{1}{2^{1/2} \Gamma(\frac{1}{2})} e^{-z/2\sigma^2} (\frac{z}{\sigma^2})^{-1/2} \frac{1}{\sigma^2} dz$$
$$= \frac{1}{\sqrt{2\pi}\sigma} z^{-1/2} e^{-z/2\sigma^2} dz,$$

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thereby checking the relationship stated above.

The Gamma density was defined for $x \ge 0$ so the density of $z = x^2$ can be written immediately. It is

h(z) =
$$\frac{1}{2\Gamma(\alpha+1)\beta^{\alpha+1}} \frac{\frac{\alpha-1}{2}}{z} e^{\frac{-z^{1/2}}{\beta}}, 0 \le z \le \infty$$
.

For the Cauchy distribution, we merely double the density on the positive portion of the x range to reflect the symmetrical negative portion, giving

$$f^{*}(x) = \frac{2 a}{\pi(a^{2} + x^{2})}$$
, $0 \le x < \infty$.

The density of $z = x^2$ is then given as

h(z) =
$$\frac{a}{\pi z^{1/2}(a^2 + z)}$$
, $0 \le z < \infty$

Densities of Sums and Differences of Stochastic Variables

For these transformations we can restrict the discussion to only two variables since this is immediately extendible to more than two by adding variables one at a time. Furthermore, subtraction need not be discussed separately since every difference can be expressed as a sum: i.e., x - y = x + (-y).

We will use the following notation. Let x and y be the two variables with densities $f_1(x)$ and $f_2(y)$ respectively. Let w = x + yand let f(w) denote the density* of w. The basic formula is

^{*}Since we are using subscripts on the symbols for the densities of x and y, the symbol f(w) is available for the density of the sum, w = x + y. Repetitive use of a symbol when properly described should be acceptable.

$$f(w) = \int_{x_1}^{x_2} f_1(x) f_2(w - x) dx$$

where the limits of integration are the bounds on x for fixed w. The determination of these limits will be illustrated in the examples included herein. This is the same as the transformation

$$w = x + y$$
, $v = x$

which has a Jacobian equal to unity. We chose here not to replace x by v, a common practice in such simple cases.

In deriving the density function of the sum of two variables each of which has a uniform or rectangular density, we encounter a good illustration of the complexities which sometimes arise from finite variable ranges. Let the two input densities be

$$f_1(x) = \frac{1}{a}, \ 0 \le x \le a,$$

 $f_2(y) = \frac{1}{b}, \ 0 \le y \le b.$

Without loss of generality, we can let a > b. (Later we will treat the case a = b.) The density of w = x+y is given by

$$f(w) = \int_{x_1}^{x_2} \frac{1}{ab} dx = \frac{1}{ab} (x_2 - x_1)$$

but there are complications in computing x_1 and x_2 . We can explain them by reference to Figure VI.3.



Figure VI.3

The w range is broken into three intervals

$$0 \le w \le b$$
, $b \le w \le z$, and $a \le w \le a + b$.

For fixed w, x + y = w is a straight line of slope negative one. The solid lines w = b and w = a separate the three areas of interest. The dotted lines are used to determine the x_1 and x_2 values in these ranges. It is apparent from the figure just why we must treat the intervals separately. Substituting the limits in the formula

$$f(w) = \frac{1}{ab} (x_2 - x_1)$$

gives

$$f(w) = \frac{1}{ab} w, \quad 0 \le w \le b$$
$$= \frac{1}{ab} b = \frac{1}{a}, \quad b \le w \le a$$
$$= \frac{1}{ab} (a + b - w), \quad a \le w \le a + b.$$

The graph of f(w) is quite interesting. As the functional representation shows, it consists of three segments which are plotted in Figure VI.4.



Figure VI.4

Obviously, if a = b,

$$f(w) = \frac{w}{a^2} \qquad 0 \le w \le a$$
$$= \frac{2a - w}{a^2} \qquad a \le w \le 2a$$

and the graph is triangular, the $f(w) = \frac{1}{a}$ segment vanishing.

Consider next the case of two normal distributions, denoting means by \overline{x} and \overline{y} and standard deviations by σ_x and σ_y for x and y respectively. The formula for f(w) is

$$f(w) = \int_{-\infty}^{\infty} \frac{1}{2\pi\sigma_x \sigma_y} e^{-\frac{(x-\overline{x})^2}{2\sigma_x^2} - \frac{(w-x-\overline{y})^2}{2\sigma_y^2}} dx .$$

In this case, the limits are determined by observing that x can range from $-\infty$ to $+\infty$ for any fixed w. We will not bother to perform the simple integration required to obtain the well known result

$$f(w) = \frac{1}{\sqrt{2\pi(\sigma_x^2 + \sigma_y^2)}} \frac{\frac{-(w - \overline{x} - \overline{y})^2}{2(\sigma_x^2 + \sigma_y^2)}}$$

Next consider the case of two gamma densities

$$f_{1}(\mathbf{x}) = \frac{1}{\alpha! \beta^{\alpha+1}} \mathbf{x}^{\alpha} e^{-\mathbf{x}/\beta}, \quad 0 \le \mathbf{x} < \infty$$
$$f_{2}(\mathbf{y}) = \frac{1}{a! \beta^{a+1}} \mathbf{y}^{a} e^{-\mathbf{y}/\beta}, \quad 0 \le \mathbf{y} < \infty$$

In this derivation we have chosen to use the factorial notation, α ! and a!. in place of $\Gamma(\alpha+1)$ and $\Gamma(a+1)$ to simplify typing. Note also that the parameter β is common to the two densities, an assumption needed

to get a simple answer. We can express f(w) as

$$f(w) = \int_{0}^{w} \frac{e^{-\frac{w}{\beta}}}{\alpha! a! \beta^{\alpha+a+2}} x^{\alpha} (w-x)^{a} dx .$$

To evaluate this integral, we will transform it into a beta function form by letting x = wt. Then dx = w dt and the integral becomes

$$f(w) = \int_{0}^{1} \frac{e^{-\frac{w}{\beta}}}{\alpha! a! \beta^{\alpha+a+2}} w^{\alpha+a+1} t^{\alpha} (1-t)^{a} dt$$

The beta density is commonly written as

$$\beta(\mathbf{x}) = \frac{(\alpha+\beta+1)!}{\alpha! \beta!} \mathbf{x}^{\alpha} (1-\mathbf{x})^{\beta}, \quad 0 \leq \mathbf{x} \leq 1.$$

Hence,

$$\int_{0}^{1} t^{\alpha} (1-t)^{a} dt = \frac{\alpha! a!}{(\alpha+a+1)!}$$

Then we have

$$f(w) = \frac{1}{\alpha! a! \beta^{\alpha+a+2}} e^{\frac{w}{\beta}} w^{\alpha+a+1} \frac{\alpha! a!}{(\alpha+a+1)!}$$
$$= \frac{1}{(\alpha+a+1)! \beta^{\alpha+a+2}} w^{\alpha+a+1} e^{\frac{w}{\beta}}$$

also a gamma density.

The Density of the Sum of Two Stochastic Variables Having Identical Cauchy Densities. Let us now derive the density function of the sum of two stochastic variables having identical Cauchy densities. Thus, let

$$f_1(x) = \frac{a}{\pi(a^2+x^2)}, f_2(y) = \frac{a}{\pi(a^2+y^2)} - \infty < x, y < \infty$$

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Letting w = x + y, we have

$$f(w) = \int_{-\infty}^{\infty} \frac{a^2}{\pi^2 (a^2 + x^2) [a^2 + (w - x)^2]} dx$$

In order to perform this integration, we will express the integrand in the form

$$\frac{a^2}{\pi^2} \left[\frac{A + Bx}{a^2 + x^2} + \frac{C + Dx}{a^2 + (w - x)^2} \right]$$

where A, B, C, and D are functions of w which is considered to be constant for this integration. It is not difficult to verify that they are

A =
$$\frac{1}{4a^2 + w^2}$$
, B = $\frac{2}{w(4a^2 + w^2)}$, C = $\frac{3}{4a^2 + w^2}$, D = $\frac{-2}{w(4a^2 + w^2)}$

Therefore the integral can be written as

$$\frac{a^2}{\pi^2(4a^2+w^2)} \int_{-\infty}^{\infty} \left[\frac{1+2w^{-1}x}{a^2+x^2} + \frac{3-2w^{-1}x}{a^2+(w-x)^2}\right] dx$$

We now modify the expression to be

$$\frac{a^{2}}{\pi^{2}(4a^{2}+w^{2})} \int_{-\infty}^{\infty} \left[\frac{1}{a^{2}+w^{2}} + \frac{2w^{-1}x}{a^{2}+x^{2}} + \frac{1}{a^{2}+(w-x)^{2}} - \frac{w^{-1}(-2w+2x)}{a^{2}+(w-x)^{2}} \right] dx$$

$$= \frac{a^{2}}{\pi^{2}(4a^{2}+w^{2})} \left[\frac{1}{a} \arctan \frac{x}{a} + w^{-1}\ln(a^{2}+x^{2}) - \frac{1}{a}\arctan \frac{(w-x)}{a} - w^{-1}\ln\{a^{2}+(w-x)^{2}\}\right]_{-\infty}^{\infty}$$

$$= \frac{a}{\pi^{2}(4a^{2}+w^{2})} (2\pi)$$

$$= \frac{2a}{\pi(4a^{2}+w^{2})} \cdot$$

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It is interesting to modify this density by the variable transformation

$$2z = w$$
, $2dz = dw$.

Then we have for the density of z,

$$\frac{a}{\pi(a^2+z^2)}$$

exactly the same density as for \mathbf{x} and \mathbf{y} .

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The Density of the Product of Two Stochastic Variables

Let the two variables be x and y with densities

$$f_1(x)$$
 and $f_2(y)$.

Let

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$$u = xy and v = x$$
.

Solve for x and y, giving

$$x = v$$
 and $y = uv^{-1}$

The Jacobian of the transformation is

$$J = v^{-1}$$

and the transformed density in differential form is

$$f_1(v) f_2(uv^{-1})v^{-1} dv du$$
.

As noted in the derivation of the sums of stochastic variables, it is common to omit the substitution x = v, which in this case gives

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$$f_1(x) f_2(ux^{-1}) x^{-1} dx du$$

Then the density of u, P(u), is derived by integration as

$$P(u) = \int_{x_1}^{x_1} f_1(x) f_2(ux^{-1}) x^{-1} dx,$$

the limits being determined in the usual way.

The Density of the Product of Two Stochastic Variables, Each having a Rectangular Density. Let

$$f_1(x) = \frac{1}{a}$$
, $0 \le x \le a$ and
 $f_2(y) = \frac{1}{b}$, $0 \le y \le b$.

Then the density of the product, u = xy, is

$$P(u) = \int_{\frac{u}{b}}^{a} \frac{1}{ab} x^{-1} dx$$
$$= \frac{1}{ab} \ln x \int_{\frac{u}{b}}^{a}$$
$$= \frac{1}{ab} \left[\ln a - \ln \frac{u}{b} \right]$$

 \mathbf{or}

$$P(u) = \frac{1}{ab} \ln \frac{ab}{u} , \quad 0 \le u \le ab$$

The Density of the Product of Two Stochastic Variables, Each Having A Gaussian or a Gamma Density. For these two cases, the simple methodology which we have adopted leads to integrals which are too complicated to handle. For derivations using more sophisticated methods, refer to the paper by Springer and Thompson which was mentioned earlier. This paper includes a table of ordinates for the Gaussian case and these were used to plot the curve to be presented later. For the gamma product, we used numerical techniques and a GE time sharing computer to derive the table of ordinates.

The Density of the Product of Two Stochastic Variables Each Having a Cauchy Density. Let us consider two stochastic variables with Cauchy densities.

$$f_1(x) = \frac{a}{\pi(x^2 + a^2)}$$
, $-\infty < x < \infty$ and

$$f_2(y) = \frac{b}{\pi(y^2 + b^2)}$$
, $-\infty < y < \infty$.

The density of the product u = xy, P(u), is obtained as follows. The joint density of x and y in differential form is

$$\frac{a b}{\pi^2 (x^2 + a^2) (y^2 + b^2)} dx dy.$$

Transform this into the differential form of the joint density of x and u by the expressions used before,

$$y = ux^{-1}$$
, $dy = x^{-1} du$,

giving

$$\frac{a b}{\pi^2 (x^2 + a^2) (u^2 x^{-2} + b^2)} x^{-1} dx du .$$

The density of u can be obtained by integrating on x. To do this, make the substitution $z = x^2$ and the accompanying differential change, dz = 2x dx. Multiply by 2 to overlap the negative and positive ranges, giving

$$P(u) = \int_{0}^{\infty} \frac{ab}{\pi^{2}(z+a^{2})(u^{2}+b^{2}z)} dz,$$

the limits on z corresponding to $-\infty$ to ∞ for x. By using partial fractions, we can express this as

$$P(u) = \frac{a b}{\pi^{2}(u^{2} - a^{2}b^{2})} \int_{0}^{\infty} \left(\frac{1}{z + a^{2}} - \frac{b^{2}}{u^{2} + b^{2}z}\right) dz$$

$$= \left[\frac{a b}{\pi^{2}(u^{2} - a^{2}b^{2})} \ln \frac{z + a^{2}}{u^{2} + b^{2}z}\right]_{0}^{\infty}$$

$$= \frac{a b}{\pi^{2}(u^{2} - a^{2}b^{2})} \left[\ln \frac{1}{b^{2}} - \ln \frac{a^{2}}{u^{2}}\right]$$

$$= \frac{a b}{\pi^{2}(u^{2} - a^{2}b^{2})} \ln \frac{u^{2}}{a^{2}b^{2}}, \quad -\infty < u < \infty.$$

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Consider the case in which the densities of x and y are identical, obtained by letting a = b. Then we have

P(u) =
$$\frac{a^2}{\pi^2(u^2 - a^4)}$$
 ln $\frac{u^2}{a^4}$, $-\infty < u < \infty$.

If we further simplify this by a unit change in which we set $\dot{a} = 1$, we find that

P(u) =
$$\frac{1}{\pi^2(u^2-1)}$$
 ln u^2 , $-\infty < u < \infty$.

The Density of the Quotient of Two Stochastic Variables

The notation which will be used in this case is similar to that used for the product. The variables are x and y with densities

$$f_1(x)$$
 and $f_2(y)$.

Let

$$v = x/y$$
 and $u = y$

Solve for x and y, giving

$$x = uv$$
 and $y = v$.

The Jacobian is v and the joint density in differential form changes from

$$f_1(x) f_2(y) d x d y$$

into

$$f_1(uv) f_2(v) |v| dudv$$
.

It is common not to replace y by v. Thus, we have the joint density differential in the form

$$f_1(y v) f_2(y) |y| dy dv$$
.

The density of v, Q(v), is obtained by evaluating the integral

$$Q(v) = \int_{y_1}^{y_2} f_1(y v) f_2(y) |y| dy,$$

the limits y_1 and y_2 being determined in the usual way.

Density of the Quotient of Two Stochastic Variables with Rectangular Densities. Let

$$f_1(x) = \frac{1}{a}$$
, $0 \le x \le a$ and
 $f_2(y) = \frac{1}{b}$, $0 \le y \le b$.

Using the transformation formulas derived above, the density of the quotient, v = x/y, is

$$Q(\mathbf{v}) = \int_{0}^{y_1} \frac{1}{ab} y \, dy$$
$$= \frac{1}{2ab} y_1^2$$

where the values of y_1 can be determined as follows. For fixed v, the graph of yv = x is a straight line through the origin. Reference to Figure VI.5 shows how y_1 is determined in two ranges.



We can see that

$$y_1 = b$$
 for $v < \frac{a}{b}$, and
 $y_1 = a/v$ for $v > \frac{a}{b}$

Therefore

$$Q(v) = \frac{b}{2a} \text{ for } v < \frac{a}{b} \text{ or } 0 \le v \le \frac{a}{b}$$
$$= \frac{a}{2bv^2} \text{ for } v > \frac{a}{b} \text{ or } \frac{a}{b} \le v < \infty .$$

Density of the Quotient of Two Stochastic Variables Having Identical Gaussian Distribution with Zero Means. Because of mathematical complexities in the more general case, we will restrict ourselves to the derivation of the density of the quotient of two stochastic variables having identical Gaussian densities with zero means. Thus, let

$$f_1(x) = \frac{1}{\sqrt{2\pi\sigma}} e^{-\frac{x^2}{2\sigma^2}} \text{ and } f_2(y) = \frac{1}{\sqrt{2\pi\sigma}} e^{-\frac{y^2}{2\sigma^2}}, -\infty < x, y < \infty.$$

The joint density of x and y in differential form is

$$\frac{-x^2 - y^2}{2\sigma^2}$$

$$\frac{1}{2\pi\sigma^2} e^{2\sigma^2} dx dy$$

As before, use the substitution x = yv, dx = |y| dv to obtain the joint density of y and v in differential form as

$$\frac{-y^2v^2-y^2}{2\sigma^2}$$

$$\frac{1}{2\pi\sigma^2} e^{2\sigma^2} |y| dy dv$$

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The density of v, Q(v), is obtained by the following integration.

$$Q(v) = \int_{-\infty}^{\infty} \frac{1}{2\pi\sigma^2} e^{\frac{-(v^2+1)}{2\sigma^2}y^2} |y| dy$$

$$= \frac{1}{\pi\sigma^2} \int_0^{\infty} e^{\frac{-(v^2+1)}{2\sigma^2} y^2} y \, dy$$

$$= \frac{1}{\pi\sigma^{2}} \left[\frac{-\sigma^{2}}{v^{2}+1} e^{\frac{-(v^{2}+1)}{2\sigma^{2}} y^{2}} \right]_{0}^{\infty}$$
$$= \frac{1}{\pi(v^{2}+1)} .$$

Thus, the ratio of two variables with identical Gaussian densities and having zero means turns out to be the Cauchy distribution.

Density of the Quotient of Two Stochastic Variables Having Gamma Densities. In this case, we will denote the densities of the stochastic variables, x and y, by the two gamma functions

$$f_1(x) = \frac{1}{\Gamma(\alpha+1)\beta^{\alpha+1}} x^{\alpha} e^{-\frac{x}{\beta}}$$
 and $0 \le x \le \infty$

$$f_2(y) = \frac{1}{\prod(a+1)b^{a+1}} y^a e^{-\frac{y}{b}} \qquad 0 \le y < \infty$$

VI.31

To obtain the joint density, we again form the product which will be transformed by the substitution x = vy, dx = v dy, giving in differential the joint density of y and v,

$$\frac{1}{\Gamma(\alpha+1) \Gamma(a+1) \beta^{\alpha+1} b^{a+1}} (vy)^{\alpha} y^{a} e^{-\frac{vy}{\beta} - \frac{y}{b}} v dy dv .$$

The density of v is obtained by integrating on y. Omitting factors not containing y, we have the integral

$$\int_{0}^{\infty} y^{\alpha+a+1} e^{-\left(\frac{v}{\beta} + \frac{1}{b}\right)y} dy$$

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By reference to the gamma function in integral form, we can see that the value of this integral is

$$\Gamma (\alpha + a + 2) \left(\frac{v}{\beta} + \frac{1}{b} \right)^{-(\alpha + a + 2)}$$

Therefore the density of v is

$$Q(v) = \frac{\Gamma(\alpha + a + 2)}{\Gamma(\alpha + 1)\Gamma(a + 1)\beta^{\alpha + 1}b^{a + 1}} v^{\alpha} \left(\frac{v}{\beta} + \frac{1}{b}\right)^{-(\alpha + a + 2)}$$

If x and y have identical densities, that is, if $a = \alpha$ and $b = \beta$, then

$$Q(\mathbf{v}) = \frac{\Gamma(2\alpha+2)}{\left[\Gamma(\alpha+1)\right]^2 \beta^{2\alpha+2}} \mathbf{v}^{\alpha} \left(\frac{\mathbf{v}}{\beta} + \frac{1}{\beta}\right)^{-(2\alpha+2)}$$
$$= \frac{\Gamma(2\alpha+2)}{\left[\Gamma(\alpha+1)\right]^2} \mathbf{v}^{\alpha} (\mathbf{v}+1)^{-(2\alpha+2)}$$

VI.32

The Density of the Quotient of Two Stochastic Variables Each Having a Cauchy Density. Again we will consider two stochastic variables with Cauchy densities

$$f_1(x) = \frac{a}{\pi(x^2 + a^2)}, \quad -\infty < x < \infty \text{ and}$$

$$f_2(x) = \frac{b}{\pi(y^2 + b^2)}, \quad -\infty < y < \infty.$$

Using the previously discussed transformation,

$$x = vy$$
, $dx = |y| dv$,

in the product of the two densities, we have the joint density of y and v in differential form as

$$\frac{ab}{\pi^2 (v^2 y^2 + a^2) (y^2 + b^2)} |y| dy dv.$$

Transforming to a positive range for y, thereby multiplying by 2, we have the density of v, Q(v), as

$$Q(v) = \int_{0}^{\infty} \frac{2ab}{\pi^{2}(v^{2}y^{2} + a^{2})(y^{2} + b^{2})} \quad y \, dy \, .$$

We can easily verify that

$$\frac{1}{(v^2y^2 + a^2)(y^2 + b^2)} = \frac{1}{b^2v^2 - a^2} \left(\frac{v^2}{v^2y^2 + a^2} - \frac{1}{y^2 + b^2}\right)$$

which, when substituted in the integral, gives

$$Q(v) = \frac{ab}{\pi^2(b^2v^2 - a^2)} \int_0^{\infty} \left[\frac{v^2}{v^2y^2 + a^2} - \frac{1}{y^2 + b^2}\right]^2 y \, dy \, .$$

Integrating, we have

$$Q(v) = \frac{ab}{\pi^{2}(b^{2}v^{2} - a^{2})} \left[\ln \frac{v^{2}y^{2} + a^{2}}{y^{2} + b^{2}} \right]_{0}^{\infty}$$
$$= \frac{ab}{\pi^{2}(b^{2}v^{2} - a^{2})} \left[\ln v^{2} - \ln \frac{a^{2}}{b^{2}} \right]$$
$$= \frac{ab}{\pi^{2}(b^{2}v^{2} - a^{2})} \ln \frac{b^{2}v^{2}}{a^{2}}, \quad -\infty < v < \infty$$

It is interesting to write the density of the quotient of stochastic variables with identical Cauchy densities. Thus let a = b, giving

Q(v) =
$$\frac{1}{\pi^2(v^2 - 1)} \ln v^2$$
, $-\infty < v < \infty$.

Note that "a" does not enter in the expression for Q(v), a natural consequence of the fact that the ratio of x to y is dimensionless in this case. Note further that the quotient is density is the same as the product for a = 1, an obvious result in view of the fact that the reciprocal of a Cauchy variables has the same Cauchy density as the variable if a = 1.

A Special Example - The Generation					
of the Rayleigh Density as a Transform	nation				
of a Pair of Gaussian Densities					

An interesting example of the transformation of a pair of Gaussian densities is provided by the following problem. Suppose we have a pair of independent forces, x and y, acting at right angles and having identical Gaussian densities with a mean of zero and a standard deviation of σ . The problem is to derive the density of the resultant force, r. The relationships of the force vectors is diagramed in the traditional way with x and y shown as the sides of a rectangle and r as the diagonal.



The zero mean merely implies that the forces are equally likely to act in either direction, positive or negative.

The densities of x and y are

$$-\frac{\frac{x^2}{2\sigma^2}}{\sqrt{2\pi}\sigma} \quad e^{-\frac{y^2}{2\sigma^2}}$$
 and $\frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{y^2}{2\sigma^2}}$

and the joint density in differential form is



VI.35

Since $r = \sqrt{x^2 + y^2}$, we can solve this problem by transforming to polar coordinates, r and θ , and integrating on θ . The differential product is replaced by

The integration is

$$\sum_{0}^{2\pi} \frac{1}{2\pi\sigma^{2}} e^{\frac{r^{2}}{2\sigma^{2}}} r d\theta dr$$
$$= \frac{1}{\sigma^{2}} e^{\frac{r^{2}}{2\sigma^{2}}} r dr, r \leq 0$$

which is the Rayleigh density. It is perhaps more common to modify the constant by the substitution

$$r_0 = 2\sigma^2$$

giving the function in the form

$$\frac{2r}{r_{0}} = \frac{r^{2}}{r_{0}} dr, r \ge 0.$$

Here again we have illustrated with a rather typical engineering example that a transformation of Gaussian densities can indeed lead to non-Gaussian outputs.

Implications of the Discussion of Transformations of Stochastic Variables

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In drawing conclusions from this discussion of transformations of stochastic variables, we will restrict our coverage to include only a few transformation properties. We will concentrate on those properties which seem to be at odds with intuition or, in other words, properties which at times seem to be misunderstood, thereby resulting in certain erroneous analyses. It is perhaps worth noting here that these problems arise because of a frequently observed characteristic of probability. It is unsafe to trust intuition by guessing or anticipating answers to problems in probability for it is so easy to guess wrong—probability problem solutions often provide interesting surprises.

Perhaps the most significant observation is that transformations of stochastic variables tend to change the density types. Stated in another way, even if all the input variables in a transfer function have the same kind of density, we cannot expect the output to be the same. For example, the ratio of two Gaussian (normal) variables is definitely not normal—in the case which was used herein, a Cauchy distribution was obtained. Of course, the density form is sometimes preserved the sum of Gaussian variables is still Gaussian.

Although we did not bother to cover this point in the derivations, it is nevertheless true that moments of transformed variables are not in general equal to the corresponding transformation of the moments of the input stochastic variables. As a simple illustration and one which is really obvious, for any density with zero mean, the reciprocal of the variable can have a density with a finite mean. Indeed, if the density of the variable is symmetrical about zero, then the density of the reciprocal is also and hence it will have a zero mean. Thus, it is necessary to derive the proper relationships on moments and it will not be wise to guess at such relationships.

The discussion did point out the difference between the density of the square of a variable and the density of the product of two independent variables having identical densities. The square of a variable represents the case of complete dependence or perfect correlation if you will. The product is the opposite extreme—complete independence with absolutely no correlation. It is interesting to look also at the case of a variable divided by itself as contrasted with the ratio of two independent variables having identical distributions. The variable divided by itself is the trivial case in which the quotient must be unity and the associated probability is also unity. The quotient of two independent variables is of course nontrivial—the density may exhibit quite unusual characteristics as compared with the common density of the input variables. For example, one can verify that for the uniform density example used herein, the quotient has an infinite mean value—a somewhat striking characteristic.

In deriving the closed form solutions presented herein, it was observed that finite limits on the input variables tend to be more difficult to handle than infinite limits. In actual engineering applications, it is likely that many variables will have finite bounds, perhaps arising by truncation of a Gaussian or Gamma or some other density form. This will have no impact on a computer analysis based on discrete approximations, but it would be significant if one choses to derive closed form solutions.

Summary of Closed Form Solutions

The discussion of closed form solutions is summarized by the formulas and graphs in Figure VI.6. This figure shows graphs of the densities of the variable, its reciprocal and its square and densities of the sum, product and quotient of two variables for the uniform, Gaussian, Gamma, and Cauchy distributions. Formulas for the closed form solutions were derived and are shown for all but two cases—the products of two Gaussian and two Gamma variables. These cases involve derivations which are much more complicated than the others in the figure. As noted earlier, an excellent treatment of some of this theory is included in the publication "The Distribution of Products of Independent Random Variables" by M. D. Springer and W. E. Thompson, G. M. Defense Research Laboratories, TR 64-46, August 1964 as noted in the discussion. In this paper, Springer and Thompson used Mellin transforms to derive many closed form relationships and some in infinite series form. Springer and Thompson provided us with a table of ordinates for the density of the product of two Gaussian variables to permit plotting this curve in the figure. We developed the ordinates for the case of the product of two gamma's by using the GE time sharing computer. Curves for the uniform density and sum were plotted from their simple equations but all other curves were plotted from coordinates generated on the G.E. time sharing computer. The tabular values generated by these computer runs are included after Figure VI.6. It is of interest to note that the computer output was formated on 8-1/2 by 11 inch sheets immediately ready for reproduction without retyping. It is also interesting to know that all of these computations required less than one minute of computer time-each page took only a few seconds.



Figure VI.6

VI.40

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Figure VI.6 (continued)

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VARIABLE	RECIPROCAL	OUD LENT	VARIABLE	SUUARE	ド トブレししょ
• 5	4	2	• 05	2.23607	2. 77573
1	1	• 5	•.1	1.58114	2.30259
1.5	• 444444	• 222222	•15	1.29099	1.87712
2	• 25	• 125	• 2	1.11803	1.60944
2.5	• 16	• 03	• 25	1	1 • 33629
3	• 1 1 1 1 1 1	055556	• 3	• 912371	1.20397
3•5	• 651633	.040816	• 35	• 0 45154	1.04732
4 j	. 0625	.03125	• 4	• 790569	• 916291
4.5	• 049363	•024671	• 45	• 745356	• 173508
5	• 04	• 02	• 5	• 707107	• (73147
5.5	• 033058	• 016527	• 55	. 6742	. 597837
6	• 027773	• 013389	• 6	• 645497	• 510826
6+ 5	• 023669	• 011634	• 65	.620174	• 430753
7	·020408	·010204	• 7	. 597614	· 356615
1.5	• 01 ////15	•004837	• 75	• 57735	• 23 1632
ن	· 015625	• 007813	• đ	· 559017	.223144
3•5	• 013341	· UU 69 8	• 0 5	• 542326	· 16251)
9	• 012346	• 00 61 73	• 7	. 527046	• 105361
6.5	• 01103	• 00554	• 9 5	• 512939	• 051293
10	• 61	.005	1	• 5	0

CAUSSIAN DISIRIBUILIN

VANIABLE.	DENSIIY	RÉCIPRUÉAL	LGUANE	VALIABLE	504
• 1	• 396752	0	1.20004	3.2	.279288
• 2	· 371042	.000037	• 807171	3. 4	.271034
• 3	• 301300	• 017136	• 62691	3• 6	.257815
• 4	. 36827	.107552	• 516441	3•3	.240386
• 5	• 352065	·215964	• 439391	4	• 219696
• 6	• 333224	• 276325	• 381545	4• 2	• 176811
• 7	• 312254	• 293465	· 336014	4. 4	.172317
• 0	• 289 69 1	• 23 5339	• 579383	4• 6	• 145747
• 9	• 266035	• 26567	·268137	4 • d	• 125492
1	.241971	.241971	.241971	5	.103777
1 • 1	·217652	210104	·219456	5.2	·03412
1.2	• 134136	•175772	• 1998 63	5• 4	• 066636
1.3	.171365	•175604	• 182661	5.6	.052052
1 • 4	• 147721	.157712	·167432	5•3	 • 03≠735
1.5	• 129513	• 141977	•153d <i>é</i> é	e	.027733
1.6	.110921	• 128188	• 141714	6.2	.021307
1. /	• 07 40 47	• 116111	•130778	. 6 • 4	• Ú15678
د ۱۰	• 07695	• 105522	•120895	6. 6.	• 011043
1•7	065616	• 09 62 1 7	• 111932	6•3	· C07631
2	053991	• 000016	 103777 	7	 005167
2•1	• U43934	·0a0767	• 09 6337	7•2	• 603429
2.2	• 035475	•074336	·U37531	7•4	• 002231
2•3	023327	.063613	• 083293	7.6	· U(1422
2• 4	• 055342	• 063502	• 077562	1.0	• UUU347
2.5	.017523	• 054923	· U72289	8	 000545
8.6	·013583	• Ü 5 43 Ü 3	•067423	ð• 2	· UUU327
2.1	•010421	.051097	• 062741	d • 4	.000135
2.3	• 007915	. 041142	. 053792	8.6	.000111
2.9	•üú5¥53	•044677	·054752	3 • 3	 000063
3	• 004432	•041931	• 051393	7	 000035

VI.42

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CAMA DISIRIBUILUN-LENSITE

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	****************		ALPHA ***	********	
VALIABLE	0	1	2	3	4
•2	. 513731	.163746	.016375	• 001032	.000055
• 4	· 67032	• 266126	· Ú53626	.00715	.000715
• 6	- 548d 12	• 329237	• 073786	• 019757	.002964
• 8	. 447329	.359463	.143785	.038343	.007667
1	. 367879	• 367379	• 18394	.061313	.015326
1.2	• 301194	• 361433	• 21 66 6	• 086744	• 654053
1.4	.246597	• 345236	.241665	• 112777	• 039 472
1.6	• 201677	• 323034	• 258 428	• 137428	• 655131
1.3	• 165299	• 29 7538	•267784	• 160671	• 072302
2	. 135335	·270671	• 270671	.180447	.090224
2.2	• 110803	.243767	·260144	• 19 6639	108151
2. 4	• 090718	·21772 3	• 261263	.209014	·125408
2.6	.074274	• 193111	.251045	.217572	.141422
2.8	• 06081	 170268 	·238375	· 222434	• 155739
3	• 049 78 7	• 149361	• 224042	• 224042	• 168031
3.2	.040762	• 130439	.203702	.222616	. 170073
3.4	• 033373	• 113469	• 192533	•218617	• 1d 5d 25
3.6	• 02732 4	• 098365	• 1 7 7058	.212469	•131553
3.8	.022371	• 08 5009	• 161517	• 204568	• 19 4357
4	•018316	•073263	• 146525	• 195367	• 175367
4.2	•014776	• 062981	• 132261	135165	• 19 4424
4. A	.012277	.05402	.118845	.174305	• 171736
4.6	.010052	•046238	• 106340	·163068	• 107520
4.3	.00823	• 039 503	• 07 4807	• 151691	• 195023
5	·006738	.03369	.034224	.140374	.175467
5.2	.005517	• 023636	• 07458 4	·129279	 16d063
5.4	.004517	.02439	• 065652	•118533	•16002
5.6	• 003698	• 020708	• 057983	.108234	.151520
5.8	• 003028	• 01756	.050923	• 098 452	•142755
6	• 002473	• 01 46 73	• 044618	.089235	•133653
		r			

GAMMA DISTRIBUTION-RECTANOCAL

	*****************		ALPHA ***	********	
VARIABLE	0	1	2	3	4
• 2	• 165 449	. 342243	2-10561	3.50935	4.38668
- 4	• 513031	1.28258	1.60322	1.33602	•835012
• 6	.524654	. 874424	• 728 68 7	· 404826	• 168677
• ð	. 447664	• 55958	. 349 737	. 45724	· U45539
1	• 367879	• 367879	• 18 39 4	.061313	•015328
1.2	• 301804	-251504	• 104793	• 029107	.004064
1.4	.249766	.176404	.063716	.01517	.002709
1 - 6	.209086	.130679	·040837	• 003 503	.001329
1.8	• 177084	• 09838	• 027328	.005061	• 000703
5	.151633	.075816	.018954	.003159	.000395
2.2	.131144	059611	013548	• 002053	• 600233
2.4	- 114451	·047655	• 009935	• 00138	.000144
2.6	• 100697	.03873	.007443	:000955	.000092
2.8	.089244	·031873	• 005692	·000678	• 00006
3	.079615	• 026538	• 004423	• 000 49 1	.000041
3.2	.071447	.022327	.003489	.000363	• 000023
3-4	.064463	• 01896	• 002788	• 000273	• 00002
3.6	• 058 446	• 01 6235	• 002255	• 000209	• 000014
3.5	• 053229	· UI 4005	.001343	.000162	• 000011
4	• 043675	• 015163	.001521	.000127	• 000004
4.2	• 044678	• 010638	.001266	-000101	• 000004
4. 4	041152	.009353	.001063	• 00003 1	• 000005
4.6	• 038025	• 003266	• 000899	• UÜGÜ 65	.000004
4.8	• 03524	• 007342	• 000765	• 000053	• 000003
5	.032749	• 60655	.000455	.000044	• 000005
5.2	• 030512	• 005468	.000564	.000036	· 000002
5.4	• 025 49 6	+005277	• 000489	• 00003	• 000001
5.6	• 026673	.004763	- 000425	-000025	• 00000
5.6	.025017	.004314	.000372	• 000021	• 000001
6	023213	· 0G3919	• 000327	• 000013	• 000001

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GAAMA DISIRIBUIIJN-SOUARE

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	*********		ALPHA	*****************	
VARIABLE	0	1	2	3	4
• 2	• 714372	.319704	.07148	3 .010657	.001191
• 4	420014	265643	- 08 40 D	4 .(11771	.0024
• 6	. 297503	.230445	.04725	023044	+ 004463
• ở	- 223547	.204421	.07142	. (127256	• 006095
1	· 16374	.16394	. 09 197	.030657	.007664
1.2	• 152624	• 167195	.09157	.033439	.007158
1.4	- 129 432	• 153146	• 090602	.035734	.01057
1.6	• 111575	•141132	.08926	.037635	.011901
1.8	.097424	• 130703	.037682	• 039212	.013152
2	• 08 59 55	- 121558	• 08 59 55	.040519	• 014326
2.2	•076485	• 113451	• 08 41 3 T	• 041599	.015425
2•4	• 068553	.10621	• 03227	• 042484	.016454
2+6	• 061831	• 099699	• 08 038	• 643203	+017416
2.8	.056063	.093312	.075486	• 043779	018314
3	.051073	038461	.076609	• 04423	.019152
3.2	.04672	.083576	• 074752	• 044574	• 019934
3.4	042897	.079099	• 07292 <i>6</i>	.044823	• 020662
3.6	039519	.074332	• 071134	• 044939	.02134
3• 8	+030516	• 071183	• 06935	• 045032	• 02197
4	• 033334	• 067668	.067868	• 045112	.022556
4.2	031427	• 064407	• 065997	• 045085	.023099
4. 4	•029259	• 061374	.06437	.045008	• 023602
4.6	• 027298	• 053543	.062736	+044887	· U24663
4.8	• 025517	• 05 59 09	• 061245	•044727	.024473
5	• 023899	• 053439	• 057747	.044532	• 024894
5•.2	· 022419	• 051124	.058291	• 044308	.025259
5.4	021065	.046951	•056376	.044056	.025594
5+6	• 019822	• 046907	• 055502	04378	• 025901
5.8	•016678	.044933	.054167	.043464	.026181
6	•017624	• 043169	• 052371	• 043169	.026435

CA4MA DISTRIBUTION-584

	*******	* * * * * * * * * * * * * * * *	ALMA +++	*******	*******
ANIABLE	Û	ì	5	3	4
• 3	Û	Û	.000001	0	0
• 6	Ó	Ū.	• 000036	0	0
• 9	0	Û	• 0003	0	Û
1.2	G	C	.001247	G	0
1.5	ō	Ō	+00353	Ú	0
1.8	ō	ō	• 00 78 09	Ŭ	Ō
2.1	0	0	•014587	0	o
2.4	ō	õ	.024078	0	ú
2.7	õ	Ŭ	• 036162	ō	Ū
3	0	0	.050407	0	υ
3.3	Ğ	ů.	.066158	0	0
3.6	õ	õ	.032608	ō	ō
3.9	ō	n	.093925	0	o
4.2	ō.	n	.114321	0	0
4.5	õ	ŭ	.12612	ō	ō
4.3	o	o	• 1 39 798	0	o
5.1	ō	ō	.149	0	0
5 4	ō	õ	.155539	Ō	Ō
5.7	0	0	• 159382	0	0
6	ō	ñ	• 160623	ō	0
6.3	õ	õ	• 157461	ō	ō
6.6	Q	0	• 15 € 1 6 €	0	0
6+9	ō	ō	•151053	0	0
7.2	ō	õ	144458	ō	Ō
7.5	ú	0	• 136718	U	0
7.8	ō	ō	• 123156	0	Û
d•1	ō	õ	• 119067	Ō	0
8.4	0	0	• 109716	O	0
3. 7	0	0	.100328	0	U
0 • /					

Gamma Products

$\alpha = 0, 1, 2, 3, 4.$

(From runs of F260 Program)

Ordinate at midpoint between "START" and "STOP" is five times the probability. Curves were drawn by plotting the probability and changing the vertical scale.

Gamma Product $\alpha = 0$

START	STOP	PROBABILITY
• 00	• 20	• 338 4
• 20	- 40	• 1557
• 40	• 60	• 099
• 60	+80	• 0703
.80	1.00	• 0527
1.00	1.20	• 0414
1.20	1 • 40	• 033
1.40	1 • 60	• 027
1.60	1.80	• 0222
1.80	2.00	• 0188
2.00	2.20	• 01 6
2.20	2.40	• 0136
2.40	2.60	• 0117
2.60	2.80	• 0102
2.80	3.00	• 0088
3.00	3.20	• 0079
3•20	3•40	• 00 68
3, 40	3• 60	• 00 6 1
3• 60	3.80	• 0053
3.80	4+ 00	• 00 48
4.00	4.20	• 00 43
4.20	4. 40	• 0039
4. 40	4. 60	• 0034
4. 60	4.80	• 0032
4.80	5.00	• 0028
5.00	5.20	• 0026
5.20	5.40	• 0023
5.40	5.60	• 0021
5+ 60	5+80	• 0019
5.80	6.00	• 0017
6+ 00	6.20	• 0016
6+20	6• 4 0	• 0015
6 • 40	6.60	• 0013
6- 60	6+8 0	• 0012
6.80	7.00	• 0011
7.00	7.20	- 0011
7.20	7•40	9•43681E-04
7•40	7• 60	8•94820E-04
7.60	7.80	8.23562E-04
7•80	8.00	7• 55059 E- 04
8.00	8.20	7.01411E-04
8+20	8 • 40	6. 62229E-04
8 • 40	8 • 60	5•93497E-04
8 • 60	8.80	5.68472E-04
8.80	9.00	5-22160E-04
9.00	9.20	4-82370E-04
9.20	9 • 40	4. 52413E-04
9.40	9.60	4.29304E-04
9.60	9.80	3-83981E-04
9.80	10.00	3+ 70714E-04
10.00	20.00	• 0055

VI.45

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Gamma Product $\alpha = 1$

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Gamma Product $\alpha = 2$

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START	STO P	PROBABILITY	START	STOP	PROBABILITY
• 00	• 2 <u>0</u>	• 0321	• 00	• 20	• 0012
• 20	• 40	• 0423	• 20	• 40	• 0033
- 4 U	• 60	• 0467	• 40	• 60	• 0059
• 60	•80	• 0473	• 60	•80	• 0084
• 80	1.00	• 0461	• 80	1 • 00	• 0105
1.00	1 • 20	• 0442	1.00	1.20	• 0122
1.20	1 - 40	• 0419	1 • 20	1 • 40	• 0137
1.40	1 • 60	• 0395	1• 40	1-60	• 01 48
1• 60	1.80	• 0371	1 • 60	1.80	• 0158
1.80	2.00	• 0349	1.80	2.00	• 01 6 6
2.00	2.20	• 0328	2.00	2.20	• 01 72
2.20	2• 40	• 0306	2•20	2•40	• 0176
2.40	2• 60	• 028 7	2.40	2.60	• 018
2. 60	2.80	• 027	2.60	2.80	• 0182
2.80	3•00	• 0251	2.80	3.00	•0183
3.00	3•20	• 02 38	3• 00	3•20	• 0184
3•20	3• 40	• 0221	3•20	3•40	• 0183
3.40	3• 60	• 021	3• 40	3• 60	• 0183
3. 60	3.80	• 0194	3- 60	3.80	• 0181
3.80	4• 00	•0185	3•80	4• OC	• 018
4.00	4.20	• 0173	4• 00	4.20	• 0177
4.20	4• 40	• 0163	4• 20	4• 40	• 0175
4.40	4• 60	• 0152	4.40	4• 60	• 0172
4. 60	4•80	• 0146	4• 60	4.80	• 017
4.80	5+00	• 0134	4.80	5.00	• 0166
5.00	5+20	• 0129	5+00	5•20	• 0164
5.20	5• 40	• 0121	5•20	5•40	•016
5.40	5+ 60	• 0114	5• 40	5. 60	•0157
5. 60	5+80	• 0108	5• 60	5.80	• 0154
5.80	6- 00	• 0101	5+80	6.00	• 015
6.00	6 •`20	• 0097	6• 00	6-20	• 01 47
6.20	6 • 4 0	• 00 9 1	6•20	6-40	• 01 43
6.40	6• 60	• 008 6	6+ 4 0	6 • 6 0	•014
6. 60	6.80	• 0082	6• 60	6.80	• 0137
6.80	7.00	• 0077	6-8 0	7•00	• 0133
7.00	7•20	• 0074	7.00	7.20	• 0131
7.20	7•40	• 00 68	7.20	7•40	•0126
7•40	7.60	• 00 6 6	7• 40	7.60	•0124
7• 60	7.80	•0063	7• 60	7.80	• 012
7.80	8.00	• 0059	7-80	8.00	• 0117
8.00	8 • 20	• 0056	8.00	8 • 20	•0114
8.20	8 • 40	• 0054	8•20	8 • 40	•0112
8 • 40	8 • 60	• 005	8 • 40	8 • 60	• 0107
8 • 60	8.80	• 00 49	8 • 60	8-80	• 0106
8.80	9+00	• 0046	8.80	9.00	• 0102
9.00	9+20	• 00 43	9.00	9.20	• 0099
9.20	9•40	• 00 42	9 • 20	9 • 40	• 0097
9 • 40	9 • 60	• 004	9•40	9 • 60	• 0095
9 • 60	9+80	• 0037	9.60	9.80	• 009 1
9.80	10+00	• 0036	9.80	10.00	• 0089
10.00	20.00	•0704	10+00	20.00	• 2352

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Gamma Product

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Gamma Product $\alpha = 4$

α = 3

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START	STOP	PROBABILITY	START	STOP	PROBABILITY
• 00	• 20	2-85197E-05	• 00	• 20	4.93797E-07
• 20	• 40	1.26807E-04	• 20	• 40	3.01330E-06
. 40	• 60	3+55770E-04	• 40	• 60	1.26716E-05
• 60	• 80	6.82424E-04	• 60	•80	3-26122E-05
.80	1.00	+ 0011	.80	1.00	6.57359E-05
1.00	1+20	• 0015	1.00	1.20	1.09647E-04
1.20	1 - 40	• 002	1.20	1+40	1.70719E-04
1 • 40	1+60	• 0025	1.40	1 • 60	2. 43246E-04
1 - 60	1.80	• 003	1.60	1.80	3.33558E-04
1.80	2.00	• 0035	1.80	2.00	4.32614E-04
2+00	2.20	• 004	2.00	2.20	5. 41872E-04
2.20	2.40	• 0045	2.20	2.40	6. 67298E-04
2.40	2.60	• 005	2.40	2.60	8.05899E-04
2.60	2.80	• 0055	2.60	2.80	9.42595E-04
2.80	3.00	• 00 6	2.80	3.00	• 0011
3.00	3•20	• 00 63	3.00	3.20	.0012
3.20	3 • 40	• 00 48	3.20	3.40	• 0014
3.40	3• 60	• 0071	3.40	3.60	• 0016
3• 60	3.80	• 0075	3. 60	3.80	• 0018
3.80	4•00	• 0078	3.80	4+00	• 0019
4.00	4.20	• 008 1	4.00	4.20	• 0021
4.20	4.40	• 008 4	4.20	4.40	• 0023
4.40	4• 60	.• 0087	4.40	4• 60	• 0025
4. 60	4.80	• 0088	4. 60	4.80	.0026
4.80	5.00	• 009 1	4.80	5.00	• 0028
5.00	5+20	• 009 3	5.00	5.20	• 003
5.20	5 • 40	• 0095	5.20	5+ 40	• 0032
5.40	5.60	• 009 6	5- 40	5+ 60	• 0033
5+ 60	5.80	• 009 7	5+ 60	5+80	• 0035
5.80	6+ 00	• 0099	5.80	6.00	• 0037
6.00	6-20	• 01	6• 00	6.20	• 0038
6•20	6• 40	• 0101	6.20	6• 40	• 00 4
6• 40	6- 60	• 0101	6- 40	6+ 60	• 00 42
6. 60	6.80	• 01 02	6+ 60	6.80	• 0043
6.80	7.00	• 0102	6.80	7.00	• 0045
7•00	7.20	• 0103	7.00	7•20	• 0046
7.20	7•40	• 0103	7.20	7• 40	• 00 48
7•40	7•60	• 0103	7.40	7• 60	• 00 49
7• 60	7.80	• 0103	7• 60	7-80	• 005
7.80	8.00	• 0103	7.80	8.00	• 0051
8.00	8.20	• 0103	8+00	8 • 20	• 0053
8.20	8 • 40	• 0103	8 • 20	8 • 40	• 0054
8•,40	8 • 60	• 0102	8+40	8 • 60	• 0055
8 • 60	8.80	• 0102	5 • 6 0	8.80	• 0056
8.80	9.00	• 0101	8.80	9.00	• 0057
9•00	9.20	• 0101	9+00	9.20	• 0058
9•20	9+40	• 01	9•20	9•40	• QO 59
9•40	9 • 60	• 01	9•40	9 • 60	• 006
9 • 60	9.80	• 0099	9• 60	9.80	• 00 6 1
9.80	10.00	• 0098	9.80	10.00	- 0061
10-00	20.00	• 3629	10.00	20.00	• 33

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CANNA DISTRIBUTION-QUDTIENT

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	******	*********	ALPHA ***	********	
ARIABLE	0	1	5	3	4
• 2	• 69 4 4 4 4	.578704	• 40187ō	.260476	• 162798
• 4	.510204	• 62474	• 637489	· 607133	• 557571
• 6	• 370625	• 549316	- 64373	. 70 408	• 7 42 58 4
• ð	• 308 6 42	• 457247	• 564503	• 650456°	• 722723
1	• 25	• 375	• 46375	• 546875	• 615234
1•2	• 206612	• 307356	• 38102	• 4403 49	• 49 1357
1-4	• 173611	• 253183	• 3076dd	• 345797	• 381716
1 . 6	• 147729	·210077	• 246611	.2746	• 292474
1.8	• 127551	• 175708	.201706	•216113	• 22328
5	• 111111	- 146 146	• 164609	• 170706	• 170706
2•2	• 097656	•125835	•135223	•13558	• 131079
2.4	• 03 6 5 0 5	• 107757	• 111859	•108375	• 10125
2•6	• 07716	• 09 28 78	• 093165	• 08 7222	• Ú78742
2.8	• 069252	·08057	.078115	 070€3€ 	• 061679
3	• 0625	•070313	•065918	·057678	•048666
3.2	• 056639	• 061703	+ 055966	· 047379	.033677
3.4	+051653	• 054428	• 047793	• 037169	• 030955
3•6	• 047259	•043242	•041037	• 032582	• 024944
3•3	• 043403	• 0 4 2 9 5 1	• 035419	• 027261	• 020233
4	• 0.4	• U36 4	 03072 	022933	· C16515
4.2	• 036782	•0344ff	.026767	019402	• 013561
4.4	• 034294	•031045	.023424	016494	•0112
4.6	 031656 	·028064	• 020583	• 01409	• 0073
4.3	• 029 727	• 02545	•018157	.01209	• 007763
5	• 027778	023148	• 016075	• 010419	.006512
5.2	026015	.021115	·014232	.009016	+ 005488
5•4	• 02 441 4	.019312	• 01273	• 007832	.004646
5. 6	• 022957	• 017708	•011382	• 006829	• 003951
5• చ	.021626	• 01 62 76	• 010208	• 005975	.003373
6	• 020405	014994	• 00913	· 005246	00289

CAUCHY DISTRIBUTION

VARIABLE	DENSLIY	SUUARE	51-1	VALIABLE	1.430001
• 1	• 315158	• 457536	• 158758	• 3	.268106
• 2	.306067	• 27 65 68	• 157579	• 6	• 161742
•'3	• 29 2026	• 22352	• 155653	• 9	• 112371
• 4	.274405	• 179747	• 153034	1.2	· 033763
• 5	• 254646	•150053	.149793	1.5	• 065732
• 6	-234051	• 123418	• 146014	1.3	• 053174
• 7	• 213631	• 111898	• 141736	2.1	•04407
• 3	• 19 409 1	•07d856	•137203	2-4	.03727
• 9	• 175362	·089533	·132353	2.7	• 031999
1	•159155	·079578	.127324	3	• 027828
1 • 1	• 144032	•072261	 122192 	3.3	.024463
1.2	• 130455	• 06604	• 117026	3•6	• 021703
1.3	• 118331	• 060691	• 111884	3•9	·017403
1 • 4	• 107537	.056046	• 106815	4.2	•017477
1.5	.097942	• 05198	• 101859	4.5	·015333
1.6	• 039 41 3	• 0 48 39 3	• 09 70 46	4.8	.014422
1.7	 061828 	• 04521	• 092396	5•1	• 013201
1.8	• 075073	• 042367	• 08 79 31	5.4	•01213 6
1.9	• 067048	• 039815	·083656	5.7	.0115
2	• 063662	• 037513	•079578	6	• 010374
2+1	• 05å837	035428	• 075693	6• 3	• 00964
5•5	• 054505	• 033532	·072016	6+ 6	·005755
2+3	 050606 	•031801	.063527	6+ 9	• 008398
2+4	•047037	030216	·065227	7•2	• 0078 43
2.5	• 043905	02876	• 062109	7.5	• 00739
2.6	• 041019	.027415	 059165 	7+3	• 006956
2.7	• 038397	026178	• 056388	8.1	.006561
2.3	• 036008	• 02 50 3	.053769	8.4	·0062
2.7	•033827	•023964	051299	3.7	• 005869
3	• 031831	• 0229 72	• 0 4 8 9 7 1	4	+ 005566

DI SCAL

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20 FUR K=1 TO 8
30 PRINTNPRINTNPRINTNPRINTNPRINTNPRINTNPRINTNPRINTNPRINT
40 IF K>5.5 THEN 110
50 GU TO (500,600,700,800,900,1000,1100,1200) K
60 PRINT
80 PRINT TAB(2);"VARIABLE"; TAB(17);"O"; TAB(29);"1"; TAB(41);"2";
90 PRINT TAB(53);"3"; TAB(65);"4"
100 GO TO 120
110 GJ TJ (500,600,700,800,900,1000,1100,1200) K
120<sup>1</sup> PRINT
130 I=0
140 IF K>7.5 THEN 170
150 N = 3
160 GD TO 180
170 N=2
180 FOR X= . 1 TO N STEP . 1
190 I=I+1
200 GU TU (530,630,730,830,930,1030,1130,1230) K
210 GJ SUB 400
220 PRINT TAB(T(0)); V(0); TAB(12+1(1)); V(1); TAB(24+T(2)); V(2);
230 PRINT TAB(36+1(3)); v(3); 1AB(48+1(4)); v(4); 1AB(60+1(5)); v(5)
250 IF I<2.5 1HEN 280
260 PRINT
270 1=0
280 NEXT X
290 IF K>7.5 THEN 320
300 PRINTNPRINTNPRINTNPRINTNPRINTNPRINTNPRINTNPRINTNPRINTNPRINTNPRINT
310 GO TO 330
320 PRINTNPRINTNPRINTNPRINTNPRINTNPRINTNPRINTNPRINTNPRINTNPRINTNPRINT
321 PRINTNPRINTNPRINTNPRINTNPRINTNPRINTNPRINTNPRINTNPRINTNPRINTNPRINT
322 PRINTNPRINTNPRINT
340 NEKT K
350 END
400 FOR J=0 TO 5
410 V(J)=1NI(V(J)*1E6+•5001)/1E6
420 T=0
430 FOR Z=2 TO 0 STEP -1
440 IF ABS(V(J)+.0001)>=10+Z 1HEN 470
450 T=T+1
460 NEXT Z
465 IF V(J) <> 0 THEN 470
466 1=2
470 T(J)=T
480 NEX1 J
490 RETURN
500 PRINT TAB(23);"GAMMA DISTRIBUTION-DENSITY"
510 GO TO 60
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1040 V(1)=C*EXP(-.5*(X+2))
1045 V(2)=(C/(X+2))*EXP(-.5/(X+2))
1050 V(3)=(C/SQR(X))*EXP(-.5*X)
1055 V(4) = 3 + (2 + V(0))
1060 V(5)=.282095*EXP(-((V(4)-3)+2)/4)
1065 GO TO 210
1100 PRINT TAB(27); "CAUCHY DISTRIBUTION"
1105 PRINTNPRINT
1110 PRINT TAB(2); "VARIABLE"; TAB(16); "DENSITY"; TAB(28); "SQUARE";
1115 PRINT TAB(40);"SUM"; TAB(50);"VARIABLE"; TAB(64); "PRODUCT"
1120 GJ TJ 120
1130 D= . 31831
1135 V(0)=X
1140 V(1)=D/(1+(X+2))
1145 V(2)=D/(2*SQR(X)*(1+X))
1150 V(3)=2*D/(4+(X+2))
1155 V(4) = 3 \times V(0)
1160 V(5)=(D+2)*(1/((V(4)+2)-1))*LOG(V(4)+2)
1165 GO TO 210
1200 PRINT TAB(26); "UNIFORM DISTRIBUTION"
1205 PRINTNPRINT
1210 PRINT TAB(2); "VARIABLE"; TAB(15); "RECIPROCAL"; TAB(27); "QUO LIENT";
1215 PRINT TAB(38); "VARIABLE"; TAB(51); "SQUARE"; TAB(63); "PRODUCT"
1220 60 10 120
1230 v(0)=5*X
1235 V(1)=1/(V(0)+2)
1240 V(2)=V(1)/2
1245 V(3)=X/2
1250 v(4) = 1/(2*SQR(v(3)))
1255 V(5)=L0G(1/V(3))
1260 GO TO 210
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530 V(0)=2*X
540 V(1)=EXP(-V(0))
550 v(2) = v(1) * v(0)
560 V(3)=V(2)*V(0)/2
570 V(4) = V(3) * V(0) / 3
580 V(5) = V(4) + V(0)/4
590 GO TO 210
600 PRINT TAB(22); "GAMMA DISTRIBUTION-RECIPROCAL"
610 GO TO 60
630 V(0)=2*X
640 V(1)=EXP(-1/V(0))/(V(0)+2)
650 V(2)=V(1)/V(0)
660 V(3)=V(2)/(2*V(0))
670 V(4)=V(3)/(3+V(0))
680 V(5)=V(4)/(4+V(0))
690 GO TU 210
700 PRINT TAB(24); "GAMMA DISTRIBUTION-SQUARE"
710 GU TU 60
730 V(0)=2*X
740 V(1)=EXP(-SQR(V(0)))/(2*SQR(V(0)))
750 V(2)=V(1)*SQR(V(0))
760 V(3)=V(2)*SQR(V(0))/2
770 V(4)=V(3)*SQR(V(0))/3
780 V(5)=V(4)*SQR(V(0))/4
790 GO TU 210
800 PRINT TAB(25); "GAMMA DISTRIBUTION-SUM"
810 GO TO 60
830 V(0)=3*X
840 V(1)=0
850 V(2)=0
860 V(3)=EXP(-V(0))*(V(0)+6)/720
870 V(4)=0
880 V(5)=0
890 GU TU 210
900 PRINT TAB(23);"GAMMA DISTRIBUTION- QUD TIENT"
910 GO TO 60
930 V(0)=2*X
940 V(1)=1/((V(0)+1)+2)
950 V(2)=(V(1)+2)+6+V(0)
960 V(3)=V(2)*V(1)*5*V(0)
970 V(4)=V(3)*V(1)*(14/3)*V(0)
980 V(5)=V(4)+V(1)+(9/2)+V(0)
990 GO TO 210
1000 PRINT TAB(26); "GAUSSIAN DISTRIBUTION"
1005 PRINTNPRINT
1010 PRIN1 TAB(2); "VARIABLE"; TAB(16); "DENSITY"; TAB(27); "RECIPRUCAL";
1015 PRINT TAB( 39); "SQUARE"; TAB( 50); "VARIABLE"; TAB( 64); "SUM"
1020 @ 10 120
1030 C= . 398942
1035 V(0)=X
```

REFERENCES

1. General Electric, TEMPO, Reports

Engineering Evaluation Planning Study for Large Solid Propellant Stages: Phase I, RM62TMP-64, by C. R. Herrmann, Dec. 1962 (Confidential)

Engineering Evaluation Planning Study for Large Solid Propellant Stages: Phase II, RM64TMP-31, 3 volumes, Volume III (Secret), by C. R. Herrmann, P. M. Carrick, R. G. Herrmann, April 65.

The Analytical Approach and Physics-of-Failure Technique for Large Solid Rocket Reliability. TEMPO Report 66TMP-90, 1 March 1967. C. R. Herrmann and G. E. Ingram.

An Application of the "Requirement vs Capability" Approach to Estimating the Reliability of Large Solid Rocket Motors: Interim Report, 67TMP-116, by C. R. Herrmann, G. E. Ingram, E. L. Welker. 2 Jan 1968.

- Phase I Progress Report, 260 Inch Motor Reliability Study, Aerojet General Corporation. 17 April through 15 Oct 1967. Report NAS 7-572 PR-6.
- 3. AGC Data Packets supplied between June 2, 1967 and Oct. 20, 1967 are in general contained in the above report (Reference 2). These packets include:

Some preliminary data on LSBR and insulation erosion rates for 260 SL-1, 260SL-2, Polaris and Minuteman;

LSBR distribution data for 260SL-1, SL-2, and propellant modules distribution data for 260SL-3;

260 inch diameter motor, Saturn 1 B Improvement Insulation Design, DLNA;

260/SIV-B Data for Burn Through Failure Mode Design Parameters;

Polaris Motor Insulation Erosion Data;

Requirement/Capability Data for Inner Bore Hoop Strain and Interface Shear Stress (Firing and Flight Conditions);

Propellant Grain Requirement and Capability Data for Storage Conditions; and

Propellant Grain Requirement and Capability Data for 260/SIV-B Booster Motor.

- 4. AGC Data Packages II-1 through II-6, supplied between Jan 26, 1968 and April 3, 1968 which include the following:
 - (II-1) Failure of Longitudinal Weld in Hoop Stress;
 - (II-2) Failure of Forward Head Circumferential Weld in Meridional Stress;
 - (II-3) Failure of Forward Skirt Forging in Combined Compression, Shear, and Bending;
 - (II-4) Failure of Nozzle Joint Bolts in Tension Due to Combined Pretorque Load, Pressure Ejection Load, and TVC Moment;
 - (II-5) Separation of Nozzle and Chamber Flange Due to Ejection Load per Bolt Exceeding Pretorque Load per bolt;

(II-6) Failure of Insulation/Case Bond in Shear Stress.

5. Phase II Report, 260-inch Motor Reliability Study, Aerojet General Corporation. 16 October 1967 through 17 May 1968. Report NAS 7-572 PR-12.