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POLY-SCIENTIFIC DIVISION LITTON PRECISION PRODUCTS, INC.

ENGINEERING DIVISION

DESIGN INVESTIGATION AND DEVELOPMENT OF DESIGN IMPROVEMENTS FOR ST124-M STABILIZED PLATFORM SLIP RING CAPSULES

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1.0 INTRODUCTION

On March 31, 1966, a program was initiated to eliminate and/ or reduce reliability hazards resulting from insulating deposits that form on precious metal contacts. The program was a two-phased study, the first of which consisted of analytical and design studies, material and process reviews, concept development, and fabrication and evaluation of concepts necessary to eliminate or minimize the effects of organic contamination of slip ring capsule assemblies. The second phase was the design, manufacture and evaluation of hardware of minimum organic content based upon the studies of Phase I.

The second phase is now complete. This report briefly reviews the work conducted during the first phase, describes the second phase investigation and contains conclusions and recommendations based upon the program as a whole.

The manufacture of totally inorganic capsules (exclusive of lead insulation) was successfully accomplished, and much was learned about design and methods of substituting inorganic materials in place of more easily used plastics and other organics. Some units have passed all mechanical and electrical tests with the exception of lifetime noise. The method of contact lubrication did not allow the capsules to operate at low levels of noise for long periods of time. Design and process improvements are suggested for future inorganic capsules.

Further investigation is needed in the area of inorganic contact lubricants; however, the fabrication of totally inorganic capsules is definitely feasible and could be done on a production basis.

2.0 REVIEW OF PHASE I

2.1 Summary of Activities

The work conducted during Phase I was organized into four principal areas of investigation:

The fabrication of totally inorganic assemblies; The fabrication of assemblies of reduced organic material;

The fabrication of inorganically lubricated contact surfaces; and

The testing of bearings with inorganic lubricants and low contamination organic lubricants.

In addition, testing was done on prototype capsules of inorganic and low organic materials. One parallel control test series was conducted to evaluate the performance of inorganically lubricated electrodeposited gold

Three concepts were investigated for the fabrication of totally inorganic assemblies. These concepts were:

 <u>Stacked Assembly</u> - Convertible glass ceramics were stacked and fired to form both slip ring rotors and brush assemblies. The glass phase was Fotoform B¹ which converted to a ceramic, Fotoceram², as the

¹Corning Glass Works ²Corning Glass Works

stacked wafers were fused to each other. As the program progressed, the stacked assembly process showed greatest possibilities for further consideration and was selected for the second phase design.

2. <u>Tube and Spline Assembly</u> - The tube and spline concept involved heat shrinking a glass tube over a ceramic or glass spline containing axial leads in the grooves. The ceramic spline was extruded from aluminum oxide and fired; a vitreous frit glass was used to fire the spline onto the centershaft. The glass tube was fitted over the spline and mated to the front face of the flange. The tube was attached to the flange and spline with the use of heat and vacuum.

The brush assembly for use with the spline and tube concept was made from aluminum oxide. It was a composite substrate assembly having the internal leads spaced between thin layers of alumina. Theleads were metallized onto these thin layers and brought to the surface. The individual layers were then fired and fused into a dense composite.

As a result of delays in obtaining exact matches of material properties, only sample quantities of the subassemblies were produced, but the structural concept was proven feasible.

3. <u>Cast and Sintered Assembly</u> - The cast and sintered concept involved the casting of glass "slip" (or slurry) in plaster molds, which was dried and finally sintered to a homogenous glass. The ring subassembly was made by loading the Kovar metal ring and lead assemblies, along with a center shaft, into a plaster mold cavity and filling the cavity with glass slip. After drying, the part was removed and sintered. The same principle of loading a plaster mold with leads was used for the brush subassembly.

There was no success with this concept which would indicate feasibility.

A highly successful method of fabricating a low organic assembly was to drill lead exit holes in the glass tube and load the tube with leads. A specially formulated low expansion plastic was cast into the bore, encapsulating the leads. Other low organic concepts were discarded early in the program because of the success with the drilled glass tube method.

Gas pressure bonding, plasma spraying and electrodeposition were investigated as methods of forming gold-niobium diselenide composites. It was not feasible to form a Au-NbSe₂ composite by plasma spraying of a fine powder blend of contact material. Dense, sound composites of gold and niobium diselenide were formed by gas pressure.

bonding techniques. The powder metallurgy technique was concluded to be a quite satisfactory one if the composites were formed on metal rings which were in turn bonded to the slip ring leads. The bonding of leads directly to pressed composites was not considered to be satisfactory.

An extensive survey of possible inorganic and organic bearing lubricants led to the selection of the following materials for testing:

Inorganic/Organi	c Trade Name (type)	Manufacturer	
Inorganic ³	Hi T (electrodeposited)	General Magnaplate	
Inorganic	CLD 5940 (vapor deposited)	CBS Laboratories	
Inorganic	Everlube 811 (sodium silicate bonded MoS ₂ and graphite)	Haward Corporation	
Organic	Versilube F-50 (silicone fluid)	General Electric	
Organic	Fluorolube S-30 . (fluorinated liquid)	Hooker Chemical	
Organic	Nujol (mineral oil)	Plough Inc.	

The sodium silicate bonded molybdenum disulfide provided the most consistent torque in excess of 500 hours (except under moist conditions) and was selected for use in the

³HiTwas subsequently found to have an organic bonding agent of a phenolic base.

Phase II study. Satisfactory performance could also be expected with mineral oil and fluorinated lubricants of viscosity similar to Nujol and Fluorolube S-30.

2.2 Conclusions of Phase I

Slip ring capsule assemblies can be feasibly manufactured from totally inorganic materials. The most successful process to date for both slip ring and brush assemblies has been the fusion of the glass ceramic disks (or wafers) under pressure.

Slip ring capsules of the low organic type can be feasibly produced in the same size packages as conventional units. Glass barrier slip rings and very low organic content brush blocks would be used.

Manufacture of the contacts with a composite of gold and niobium diselenide self-lubricating surface is feasible for applications where noise levels in the range of 20 to 60 milliohms can be tolerated for periods up to 500 hours.

Sodium silicate bonded molybdenum disulfide and graphite is a satisfactory inorganic bearing lubricant. Nujol and Fluorolube S-30 are satisfactory organic bearing lubricants when applied in prescribed quantities and operated at 50°C.

- 2.3 Recommendations for Phase II units were that Poly-Scientific:
 - Fabricate slip rings and brush blocks from stacked and fused Fotoceram.
 - 2. Electroform rings of 24 K gold and lubricate them with a gold-niobium diselenide electrodeposit.
 - 3. Lubricate bearings with Everlube 811.
 - 4. Seal the entire capsule to the maximum extent possible.

3.0 PHASE II. - PROGRAM AND ACTIVITIES

During Phase II, a total of five units (DP1766) were fabricated by the stacking and firing of Fotoceram brush blocks and slip rings. The contacts were lubricated with electrodeposited niobium diselenide and the bearings with Everlube 811. The capsule housings were designed to close with graphite seals so that the contacts were partially sealed from external contamination. Appendix IV contains detailed engi. neering drawings of the capsules and components. Records of fabrication difficulties and methods of solution were kept during the building of the units. The details of problems in fabrication are discussed later, along with action taken for improvement. Three of the completed capsules were performance tested during vibration, and acceleration and after shock tests; two capsules were life tested for 5000 hours. All units were evaluated after testing in order to determine what improvements could be incorporated in future designs and processes.

4.0 FABRICATION OF INORGANIC CAPSULE

4.1 Concepts

All five slip rings were fabricated by the stacked assembly techniques, and the only organic components used were Tef-

Internal slip ring and brush block conductors were fired in place as the Fotoform was being fused and converted into Fotoceram.

The rings-to-slip ring-lead conductors and the brush-tobrush block conductors were electroplated copper. Silver was painted and used as a ring starting conductor. After the slip ring was plated with approximately 0.5 mil of copper, the silver and copper over the lead ends were picked away so that there would be direct electrical contact between the internal slip ring leads and the copper rings which served as substrates for electroformed 24 karat gold. The electroformed gold was grooved and overplated with a composite of nickel hardened gold and dispersed niobium diselenide. A copper reduction coat allowed the electroforming of copper pads to which brushes could be attached by soldering.

Sauereisen #31¹ was used for potting over the external to

¹Sauereisen Cement Company

1.0

internal slip ring lead joints and for bonding the nameplate to the capsule. A one-piece end cap and housing was fitted to a spring loaded graphite seal.

4.2 Details of Problems and Solutions

There were a number of design and manufacturing problems resulting from using only inorganic materials. One of the first difficulties was that the unfired glass (Fotoform B) was quite fragile and had to be handled with care. We found that glass could be very easily cracked or chipped when a technician was inserting relatively stiff wires through holes in the slip ring wafers or slots in the brush block wafers. The solution to this problem was to preform the conductors so that very little stress would be applied to the Fotoform during the stacking of the unfired assemblies.

Eight units were started for the Phase II program, but three were damaged beyond repair during the firing operation. A redesign of the firing fixture allowed the remaining five units to be completed. Complete wafer-towafer bonding was still not obtained between either the slip ring wafers or between the brush block ones. The wafers were held slightly apart by the internal leads which were present in the assemblies at the firing stages. Good wafer fusion was found away from the leads, but there were some non-bonded areas between leads which later resulted in electrical shorts.

The voids between wafers were first patched with solder glass which unfortunately was attacked by the plating baths We learned that Sauereisen #31 was not damaged by plating electrolytes and it was subsequently used in place of the solder glass. Future units should be designed so that there will be little or no interference between stacked wafers and conductors. Also, attention must be given to applying uniform pressure to all fired surfaces so that the wafers will be uniformly forced together while they are in the plastic state. We have discovered that part of the fusion problem was caused by rough Fotoform wafers. Rough wafers, as were used during Phase II, do not fuse nearly as well as smooth ones. We now require that all Fotoform have a 25 microinch (CLA) finish and the problem of incomplete fusion has been essentially eliminated on the Fotoceram units currently being manufactured at Poly-Scientific.

As a result of this study, we learned that external protrusions or bosses that can be broken or ground away after firing can assist in the stacking of Fotoform wafers. Designers of Fotoform wafers should remember that the photoetch process does not necessitate the use of straight lines, round holes, absence of sharp undercuts, and uniform radii that are so desirable for machined components. For instance, future rotor wafers should be

designed, as shown in Figure 1, so that the tabs can be used for positioning during firing and then ground or broken away after firing is completed. Future designs should not require depth etching of Fotoform. If a depth etch is required, it should not be done on a wafer that is also to be through etched. For example, the DP1766 brush block wafer which contained leads can be designed so that depth etching is not necessary, if breakaway fixturing material is included in the Fotoform design.

Some difficulties in drilling holes to internal leads were encountered. The problem of locating internal leads was intensified by the fact that the shrinkage of the Fotoceram during firing could not be determined accurately beforehand. We now have learned more about the dimensional changes which occur when Fotoform is converted to Fotoceram. However, a test assembly should be fired before positioning fixtures are designed for subsequent grinding and drilling operations, since the dimensional changes upon firing depend on applied load, height of stack, Fotoform surface finish, shape of wafer and method of fixturing.

The P-S E.S. 56 leads oxidized during firing so that unsupported leads were so brittle that they broke when attempts were made to braze external leads to them. (Figure 2). It was therefore necessary to grind ceramic

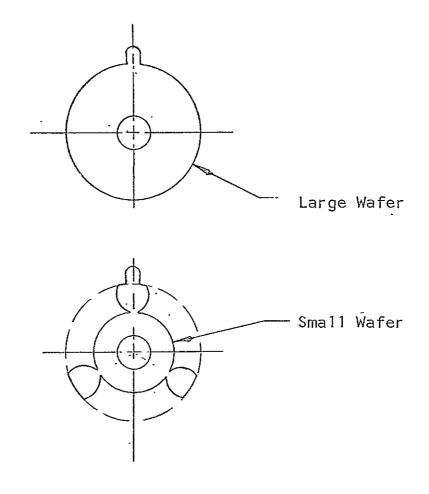


Figure 1

Design of rotor wafers with removal tabs that could be used to assist in positioning wafers during firing operation. away from a remaining part of the leads and soda blast them to remove surface oxidation. The leads were then too confined to allow brazing so it was necessary to solder the external to internal leads together and to insulate over the joints with Sauereisen #31 (Figure 3). Future Fotoceram units which are fired with leads in place should be fired in an inert or slightly reducing atmosphere so that lead oxidation will be reduced to a minimum.

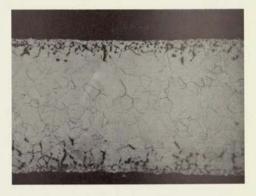


Figure 2

Etched cross section of P-S E.S. 56 internal lead. Note intergranular corrosion caused by approximately 4 hours exposure to air at 1500°F. (285X)

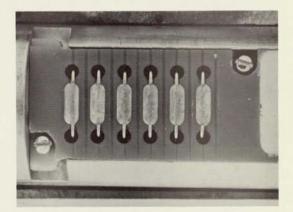


Figure 3

Back of ceramic brush block. White area at the right is Sauereisen #31 which has been potted over internal to external lead joints. (2.5X)

5.0 TESTING OF CAPSULES

5.1 Test Procedures

Three units were tested for d.c. resistance, contact resistance variation (noise), torque, and insulation resistance before and after acceleration, vibration, shock, and load tests. The details of the test procedures are described in Appendix II. Two units were life tested as described in paragraph 4.10 of Appendix LI. The life test units were also tested for d.c. resistance, contact resistance, noise, and insulation resistance as descriged in paragraphs 4.1 through 4.4 of the Test Procedure. The detailed test results are recorded in Appendix III.

5.2 Results

5.2.1 Qualification Test Units (three) - The initial noise levels of all circuits on all three capsules were less than 10 milliohms after acceleration, vibration and shock tests. Two qualification units showed a significant increase in noise after the load test, but noise on the third capsule decreased slightly after load testing. The highest noise on a single circuit after qualification testing was 22 milliohms. The maximum noise experienced during acceleration testing was 7 milliohms and there were no significant changes in d.c. resistances. Noise

reached as high as 50 milliohms during vibration testing, but we believe this was partly because the test drive shaft reached resonant frequency. Maximum noise, exclusive of that probably caused by resonance of the test fixture, was approximately 20 milliohms.

One unit had two high potential shorts and another had five at the beginning of the testing program. The insulation resistances did not change appreciably during acceleration, vibration or shock testing, but dropped by approximately three orders of magnitude after load tests. Not considering the initially shorted circuits, the minimum insulation resistance after load testing was four megohms. DC resistance did not change significantly during any of the qualification tests. Maximum capacitance between circuits was 68 picofarads - maximum capacitance to ground was 37 picofarads.

The initial torque of the qualification units varied appreciably (see Table I). In general, the torque decreased as the units were tested.

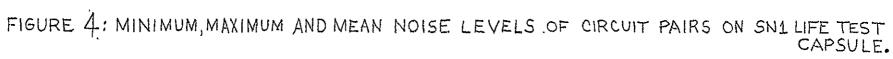
The differences in bearing torques were the dominant reason for the differences in torque needed to turn slip ring capsules. Even though brush formation was checked after brush block assembly, the variation in measured brush force was great.

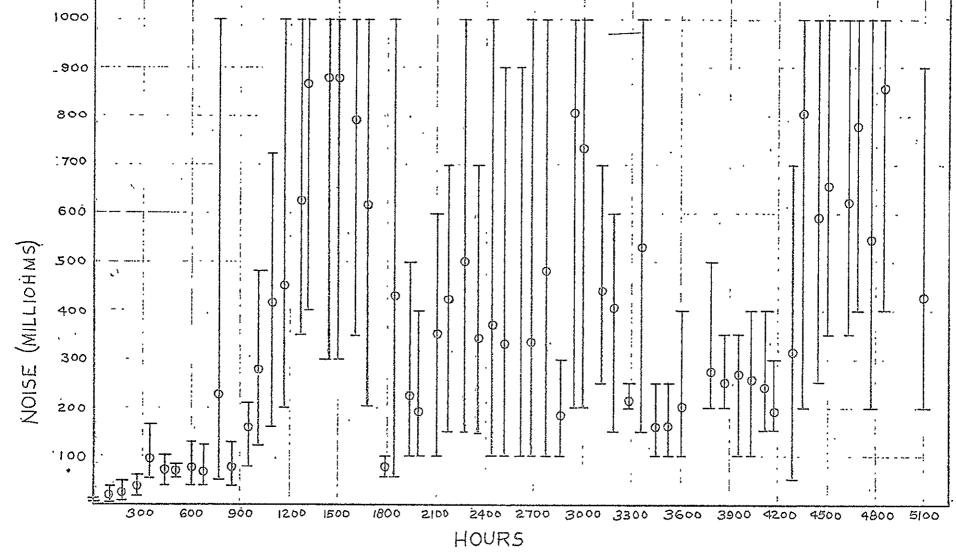
1.8

S/N	Initial Torque (gm-cm)	Torque During Post Test Evaluation (gm.cm)	Bearing Torque After Test	Brush Force After Test (gm.cm) (average)	Brush Force Range
3	35	25	13	3.5	2 -6.5
-4	18	13	9	5.0	4 - 5 - 5
5	45	3'8	29	4.7	2-6.2

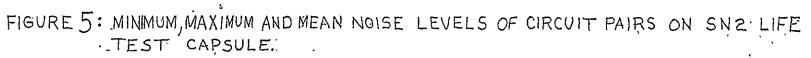
TABLE 1: TORQUE AND BRUSH FORCE DATA FROM QUALIFICATION. UNITS

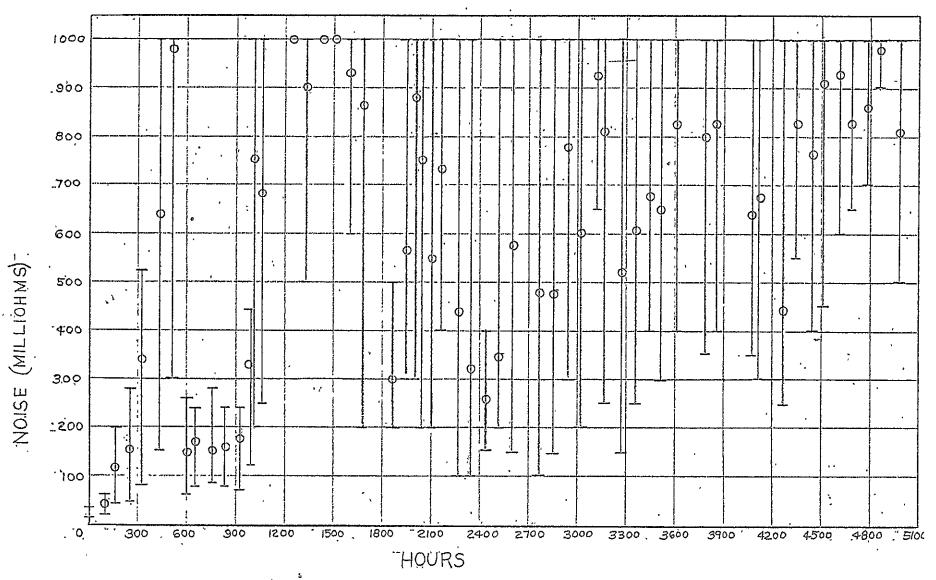
5.2.2 Life Test Units - The initial maximum noise on the two life test units was 13 milliohms and 32 milliohms respectively. At the end of 500 hours, the maximum noise levels were 80 and 1100 milliohms. Figures 4 and 5 indicate the lowest, highest, and median circuit noise levels for capsules S/N 1 and S/N 2. S/N 1 performed similarly to the test capsules that were lubricated with a gold-niobium diselenide composite during Phase I, and were tested for only 500 hours. The second capsule exceeded comparable Phase I noise test results after 168 hours. Sometime after 500 hours, noise on all circuits of both capsules exceeded 1 ohm.





S/N.#1





S/N #2

6.0 EVALUATION OF PARTS

6.1 Structural

The capsules were not structurally or functionally damaged by the acceleration, vibration and shock tests. The Sauereisen used as a nut locking compound on the slip ring front shaft appeared to have been slightly cracked, but the cracking was not sufficient to allow the cement to break from the part. The ceramics were in no way damaged by the mechanical tests and there were no joint failures. The internal to external lead joints were sound even though the internal leads had been oxidized (Figure 6). Some of the plated jumpers between internal leads and rings or brush pads contained large voids (Figure 7). These voids were probably caused by entrapped air during plat-Future units should be vacuum impregnated with ing. plating solution and then the jumpers electrodeposited while the plating bath is being ultrasonically agitated.

There was discoloration of the Fotoceram in areas which adjoined the oxidized P-S E.S. 56 internal leads. The discoloration was probably caused by oxides of the E.S. 56 material and not by the alloy itself. Thus, the firing of the Fotoform internal lead assemblies in an inert or slightly reducing atmosphere may reduce the

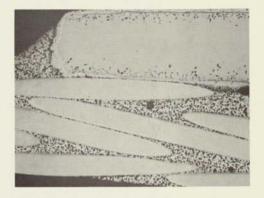


Figure 6

Solder joint between internal and external leads. Note that the residual oxidation of the internal lead did not prevent it being wetted by the solder. (138X)



Figure 7

Cross section of copper jumper plated between internal brush block lead and brush pad. Large void was probably caused by trapped air. (138X) amount of discoloration. The discoloration does not represent a structural problem, but the subassemblies would have a more pleasing appearance if they were uniform in color. There will be some slight differences in color from one wafer to another if the wafers are not flooded (exposed to high intensity light) and otherwise processed in exactly the same manner during the manufacture of the Fotoform.

There was very little wear of the graphite seal (Figure 8). No loose graphite particles were seen and the amount of graphite transferred to the rotor flange surface was slight (Figures 8 and 9).

Brush alignment was quite good (Figure 10).

6.2 Electrical

Dielectric failures which were a result of incomplete wafer fusion (Figure 11) can be corrected by further refinement of Fotoceram firing techniques. We are presently stacking five wafers to form an eight segment switch without problem of high potential shorts between segments, or between segments and ground. An increase in relative humidity is believed to be the cause of the drop in insulation resistance after the load test was performed. The insulation resistance before load testing was on May 1, 1969 (\approx 37% RH). The after load tests were performed on July 14, 1969 (\approx 48% RH). The

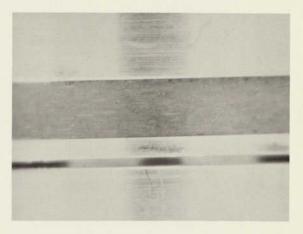


Figure 8 Side view of graphite seal. Note absence of graphitic wear debris. (14X)



Figure 9

The dark area on the slip ring base was caused by burnishing of the graphite seal. There are very few loose particles of graphite. (11X)

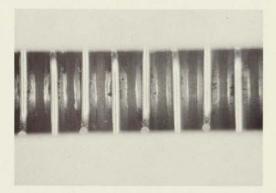


Figure 10

Capsule as viewed through slot in housing after 5000 hour life test. Even though the slip ring is rotated so that the wear debris is at a maximum, there is only a small amount of it on the ring shoulders and barriers. (14X)

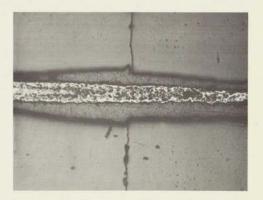


Figure 11

Photomicrograph showing extreme case of voided areas between ceramic wafers in the area of an internal lead. Note also the poor fusion between wafers. (69X)

months of June and July were, in general, humid and probably caused the capsules to adsorb some water.

6.3 Contacts

Initial noise levels were low (e.g., 10 milliohms), but they increased to approximately 1 ohm after about 500 hours of testing. The amount of wear debris appeared to be quite small when one looked through the windows of the life test capsules (Figure 10). Removal of the brush blocks on one of the life tests units revealed the presence of black adherent debris which was concentrated in the area of the wear spots (Figures 12 and 13). The black part of the debris dissolved in a solution of concentrated H2SOL saturated with Cr03. There were a few gold particles (<5 volume percent) in the wear debris which did not dissolve in the H2SO4-CrO3 solution. Most polymers will dissolve in H2S04-Cr03 solutions, and tests at Poly-Scientific showed that NbSe, is not soluble in the acid mixutre. Thus, we feel that the black debris was an organic polymer and that it was probably the cause of the high noise. The source of carbon for the polymer is not certain. The units were tested in a nitrogen atmosphere and the dielectric materials were ceramics. It has been reported that hard gold plates of the type used can co-deposit organic

Munier, G. B. - "A Study of Polymer Co-Deposition with Gold during Electroplating", presented at American Electroplater's Society Meeting, Boston, Massachusetts, February 1969.

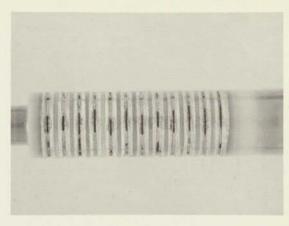


Figure 12

Overall view of rotor after 5000 hours of testing. The areas which contacted the brushes during oscillation are at the top, but as the slip ring was rotated during noise testing, wear debris was transferred and redeposited along the bottom of the slip ring grooves. (7X)

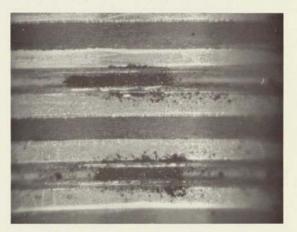


Figure 13

Grooves of slip ring (S/N 1) after 5000 hours of testing at 5 - 6 cps, 6° double amplitude. Note that most of the wear debris remained in the grooves and that it is as high as the bottom of the wear areas on the rings. (20X)

materials. The lower the cathode efficiency of the plating bath, the greater the likelihood of polymeric material being co-deposited with the gold. Cathode efficiency decreases in the acid gold bath 1 from approximately 35% to approximately 27% as the current density is decreased from 7.5 ASF (the current density normally used) to 2.5 ASF (the current density used during deposition of the Au-NbSe, composite). Some organic material could have been in the nitrogen or counter diffused (with respect to the N2 flow) into the test chambers. However, the quantity of debris was on the order of that expected to form on a similar unit with conventional lubrication and organic insulators when tested in air. The black debris was in contrast to the fluffy, loose type polymer found in conventional slip ring capsules in that it was more adherent and appeared to contain "oil". Oil is used as a descriptive term only, for the unit was definitely not lubricated with a liquid material.

The black debris was situated in the grooves in such a manner that we feel sure that it was the cause of the high electrical noise.

There was appreciable wear of both the rings and the brushes (Figures 13, 14, 15 and 16). A typical brush

¹Technic, Inc.

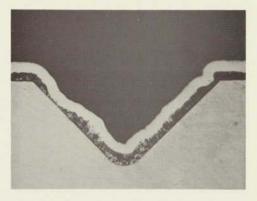


Figure 14

Cross section of slip ring groove in area worn by oscillation. The gold-niobium diselenide composite appears dark because of etching. It was over-plated with nickel to more clearly delineate the wear area which does not extend through the composite to the gold substrate.(285X)

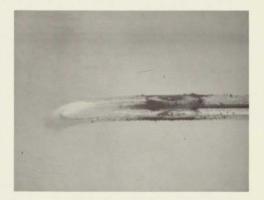


Figure 15

Wear spot on a brush taken from a life test capsule (S/N 1). Note the black wear debris and the absence of prow formation. (40X)

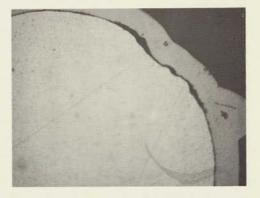
was worn to a maximum depth of 0.0003 inch. The goldniobium diselenide composite plates were in some cases worn approximately two thirds the way to the substrate gold electroform (Figure 14). In no case was the composite worn through to base metal. The wear rate was approximately 10^{-10} in./in. The composite was harder than expected (169 HK₁₀). In comparison, the 24 karat electrodeposit had a hardness of 87 HK₁₀.

We found that even though the brushes were formed cor rectly before assembly, they did not have the correct force after assembly. The differences in force could have been caused, in part, by the fact that only two of the three frame surfaces to which the block was designed to mate could be used. Thus, the brush blocks may have been slightly twisted. The brush block "ears" (shown in Figure 3) were designed to fit snugly in the slot of the frame; however, to obtain correct brush alignment, the ears had to be ground so that they did not contact the inner side of the frame slot. The correct mating can be obtained, on future units, by a slight redesign of the brush block wafers. We will check the brush force of future units immediately after assembly, rather than rely on correct brush formation and torque as measurement indicators of correct brush force.

6.4 Bearings

There were no bearing failures and the wear of the sodium silicate bonded MoS, and graphite (Everlube 811) was slight. There were a few loose particles of lubricant inside the bearings, but none of them appeared outside of the bearing shields. In fact, fewer than six particles were observed on the internal surfaces of four shields removed from two bearings. The quantity of loose particles in these bearings (Figure 17) which were operated for 5000 hours did not appear any greater than the quantity found in the bearings which were tested for 500 hours during Phase I. Both inner and outer races (Figure 18) were uniformly burnished and there was no sign of Brinelling; also, the lubricating film remained continuous and smooth on all surfaces. The balls of the bearing did not appear (30X) to be worn as a result of being operated in an oscillating mode for 5000 hours at 5 - 6 cps (Figure 19). We feel that future inorganic units should contain bearings lubricated with sodium silicate bonded MoS2 and graphite. Also, this lubricant appears to be an excellent candidate for vacuum applications.

We found that running reduced the friction torque of the qualification units. Future bearings lubricated with sodium-silicate bonded molybdenum disulfide and graphite should be run-in so that a smooth burnished finish is obtained before use.



NOT REPRODUCIBLE

Figure 16

Cross section of brush showing wear area. The wear extends approximately 0.0003 inch along a radius from the original circumference of the brush. The black areas are wear debris sandwiched between a nickel overplate and the brush. (550X)

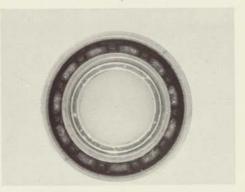


Figure 17

SR155 bearing after 5000 hours of operation at 5 - 6 cps, 6° double amplitude. (7.5X)



Figure 18

Inner bearing race after life test. The lubricating film is burnished, but not chipped, flaked, or worn to the stainless steel. (18X)

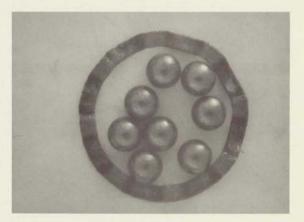


Figure 19

Balls and one retainer ribbon from bearing of a life test unit. Notice that balls are coated with lubricant and that lubricant on the sides of the retainers has been only slightly burnished. (18X)

7.0 CONCLUSIONS OF PROGRAM

The following program conclusions are advanced:

Slip ring assemblies can be feasibly manufactured from totally inorganic materials. The most successful process for both slip ring and brush assemblies has been the glass ceramic disks (or wafers) fused under pressure. To the best of our knowledge, this is the first time that a totally inorganic slip ring capsule has been fabricated.

Sodium silicate bonded molybdenum disulfide and graphite serves as an excellent inorganic bearing lubricant when operated in a N_2 atmosphere at 50°C.

Composite rings are not yet satisfactory sliding electrical contacts for operation in excess of 500 hours at 5 - 6 cps. Noise levels are too high and wear too severe. The composite could be used approximately 200 hours if noise levels in the range of 20 to 60 milliohms could be tolerated. The performance of the electrodeposited gold-NbSe₂ is equivalent to similar rings produced by pressing techniques.

Slip ring capsules of the low organic type can be feasibly produced in the same size packages as conventional units. Glass barrier slip rings and very low organic content brush blocks would be used. Changes would be required for specification GC125355 to permit such a modification.

The experience gained by virtue of this study has allowed Poly-Scientific to manufacture, in production quantities, two types of completely inorganic switches which can be operated at temperatures in excess of those which would destroy conventional organic dielectrics.

More investigation is needed in the area of totally inorganic contact lubricants.

Design and process improvement recommendations for future inorganic units are listed in Appendix I.

The specific technical accomplishments of the program were:

- 1) A technique was applied for fusing Fotoform wafers to build ceramic bodies for electrical integrity.
- 2) A method was developed for introducing electrical conducting elements in the Fotoceramic bodies with continuity and electrical separation.
- A method of applying solid lubricant by co-electrodeposition was developed.
- 4) A satisfactory inorganic bearing lubricant was demonstrated for N_2 environment which probably would be satis factory in vacuum.
- 5) The glass surface slip ring concept was shown to be reducible to practice with the enclosure as conventional slip rings.
- Ultrasonic drilling of ceramic and glass bodies was made practical.

- 7) Plastic formulations were developed with coefficients of thermal expansion so low as to nearly match sodalime glass.
- Techniques were developed for grinding ceramic and glass to good surfaces without breaking.
- 9) Laser welding was proven feasible where permanent mechanical support for the components is designed into the unit.
- O) A spline and tube method of inorganic slip ring manufacture was shown to be feasible for low cost, low precision slip rings.

Poly-Scientific gained considerable general information about various glasses, ceramics and lubricants. This knowledge has already been applied to a number of other programs, and has ben of particular benefit during the design and development of assemblies which are to operate in space environment, or at high temperatures.

APPENDIX I

DESIGN AND PROCESS IMPROVEMENTS RECOMMENDED FOR FUTURE INORGANIC CAPSULES

DESIGN AND PROCESS IMPROVEMENTS RECOMMENDED FOR FUTURE INORGANIC CAPSULES

As a result of this study, we recommend that:

- External bosses and tabs of Fotoform be used to assist in positioning wafers during firing or assembly.
- Depth etched wafers be avoided in preference to through etch ones. A 20 to 1 etch rate should be assumed.
- 3. Fotoform wafers comply with P-S E.S. 344 which requires a smoother surface finish than that on the Phase II wafers.
- 4. Fotoform containing internal leads be fired in an inert or slightly reducing atmosphere.
- 5. Firing fixtures be designed to provide uniform pressure over entire horizonal surfaces of Fotoform.
- Internal to external jumpers be plated via processes of vacuum impregnation of electrolyte and ultrasonic agitation of electrolyte during electrodeposition.
- 7. Brush block Fotoform wafers be slightly redimensioned so that all three brush block aligning surfaces can be used.
- 8. Brush forces be checked immediately after assembly.
- 9. Sodium silicate bonded MoS₂ and graphite lubricated bear ings be run in before brush blocks are placed on the capsule.
- 10. A matrix gold electrodeposit that does not contain polymer (e.g., BDT 200)¹ be used in the formation of gold-niobium diselenide composites.

Sel Rex

11. If there is allowable space, Au-NbSe₂ composite brushes be used in conjunction with hard gold rings.

A.P.P.E.N.D.I.X II

QUALIFICATION TEST PROCEDURE

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FOR

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DP1766 CAPSULE SLIP RING ASSEMBLY

QUALIFICATION TEST PROCEDURE

FOR

DP1766 CAPSULE SLIP RING ASSEMBLY

Procedure No	RLT - 91
Date <u>27 Feb</u>	ruary 1969
Revised	3 ,
Approved <u>/</u>	m.m. milie
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1. SCOPE

This procedure describes the testing required for qualification of the 12 circuit capsule slip ring assembly in accordance with Marshall Space Flight Center Drawing No. GC-125355 Rev. H, dated 2-17-67 and the Military Standards referred to in the drawing.

2. TEST UNITS

Five prototype assemblies shall be used as the qualification units.

3. TEST EQUIPMENT REQUIRED

General Radio Megohmmeter Model 1862C General Radio Precision Decade Resistor, Box type 510-AA in .ULU steps Hewlett Packard Power Supplies, Model 721A Cimron Digital Voltmeter Model 6200A DVM Cimron Preamplifier Model 6801A Sanborn Model 150 Recorder with AC-DC Preamplifier Model 150-1000 Sanborn Low Level Amplifier Model 850-1500A Sanborn Medium Gain Amplifier, 8 Channel, Model 658-3400 with Optical Recorder Model 650. Bruel and Kjaer Exciter Control Preamplifier type 1608 Bruel and Kjaer Accelerometer Bruel and Kjaer Automatic Vibration Exciter Control Model 1018 Unholtz-Dickie Shaker system No. 52 AVCO Shock Machine Model SM-005 Tektronix L-C Meter type 130 Tektronix Oscilloscope Model 533 or equivalent Tektronix Preamplifier type "E" or "1A7" Tektronix Preamplifier type "CA" Waters 0-42 Gram/Centimeter Torque Watch Gauge Radio Frequency Laboratories Variable Frequency Power Supply Model 150 Poly-Scientific Shock, Vibration and Acceleration Test Fixture Poly-Scientific Centrifuge Poly-Scientific Noise Test Drive Fixture Poly-Scientific Current Control System Poly-Scientific Run-In Fixture Poly-Scientific Life Test Fixture

TEST EQUIPMENT REQUIRED (...Continued)

Rotational Drive Motors for Vibration and Acceleration Tests. Wire Wound Resistor.

Assorted Cables, Hardware and Other Required Incidental Hook-Up Equipment

4. OPERATION SEQUENCE

- 4.1 D.C. Resistance
 - 4.1.1 Adjust the power supply and current control system to 10 VDC open circuit voltage with 0.010 ampere current.
 - 4.1.2 Using the digital voltemeter, measure and record each circuit of the capsule assembly.

Contact Resistance Variation (Noise)

- 4.2.1 Install the capsule assembly on the noise test drive fixture.
- 4.2.2 Adjust the power supply to 10 VDC open circuit voltage and the current control to 0.100 ampere.
- 4.2.3 Rotate the capsule assembly rotor at 2 RPM with super- imposed oscillation of 5° $\pm 1^{\circ}$ DA @ 6-8 Hz.
- 4.2.4 Test the capsule assembly and record the noise level of each circuit pair.

4.3 TORQUE

- 4.3.1 Using the torque watch gauge, take six random torque measurements of the capsule slip ring rotor with the housing static.
- 4.3.2 Record both the maximum and the minimum torque readings on the data sheet.

4.3.3 The torque test shall be performed within 15 minutes from completion of the noise test.

4.4 Insulation Resistance

- 4.4.1 Using the 500 volts setting on the megohmmeter, measure and record on the dats sheet each circuit to all other circuits and all circuits to the frame.
- 4.4.2 Apply the voltage to the circuit until the meter has stabilized, then take the reading.
- 4.4.3 Testing shall be performed at 22 ±5° C. with 50% Relative Humidity.

- 4.5 Capacitance
 - 4.5.1 Connect the D-c Meter to Circuits 1-2.
 - 4.5.2 Measure and record the capacity of the circuit pair, then measure and record the capacity of circuit 1 to frame and circuit 2 to frame.
 - 4.5.3 Measure the remaining circuits in the same manner and record each reading on the data sheet.

4.6 Acceleration

- 4.6.1 Install the capsule assembly in the test fixture and attach the fixture to the centrifuge arm.
- 4.6.3 Make the required electrical connections.
- 4.6.4 Adjust the centrifuge speed to attain 20 ±2 G's for 30 minutes in each of the three mutually perpendicular axes.
- 4.6.5 The DC Resistance and Noise shall be monitored during the test.
- 4.6.6 Upon completion of acceleration testing, perform DC Resistance, Noise, Torque and Insulation Resistance tests per Paragraph 4.1, 4.2, 4.3 and 4.4 of this procedure.

4.7 <u>Vibration</u>

- 4.7.1 Install the capsule assembly in the vibration test fixture.
- 4.7.2 Connect the rotational dirve motor to the capsule assembly rotor.
- 4.7.3 Program the vibration exciter control to sweep from 20 to 2000 and return to 20 Hz in 20 minutes.
- 4.7.4 Set the amplitude at 0.06 inches displacement, use 55 Hz as the crossover, and set the acceleration to 15 G's peak
- 4.7.5 Vibrate each of the three mutually perpendicular axes for one hour.
- 4.7.6 The noise level shall be monitored during the vibration.
- 4.7.7 When the vibration testing is completed, perform DC Resistance, Noise, Torque and Insulation Resistance tests per Para. 4.1, 4.2, 4.3 and 4.4 of this procedure.

Page 4 RLT-91

- 4.8 Shock
 - 4.8.1 Install the capsule assembly in the shock test fixture and secure to the shock machine, taking care to secure all lead wire.
 - 4.8.2 Apply 20 G's acceleration with 7 to 11 milliseconds duration half sine pulse, one blow in each direction, to each of the three mutually perpendicular axes.
 - 4.8.3 A total of six blows is required.
 - 4.8.4 Using the oscilloscope, monitor the acceleration level and the pulse duration of each blow.
 - 4.8.5 When the shock testing is completed, perform DC Resistance, Noise, Torque and a visual examination for workmanship, per Para. 4.1, 4.2, 4.3 of this procedure and Para. 3.4.16 of drawing no. GC-125355 Rev. H from MSFC.

4.9 Load Test

- 4.9.1. Connect fifty percent of the circuits is series and apply 115 volts AC @ 400 Hz.
- 4.9.2 Using the wire wound resistor, limit the current through the series circuit to one ampere for 500 continuous hours.
- 4.9.3 At the end of 500 hours, connect the remaining fifty percent of the circuits in series and apply the same voltage and current for an additional 500 hours.
- 4.9.4 When the load test is completed, perform DC Resistance, Noise, Torque and Insulation Resistance per Para. 4.1, 4.2,
 4.3 and 4.4 of this procedure.

4.10 Life

- 4.10.1 Install the capsule assembly in the life test fixture.
- 4.10.2 Adjust the power supply to 10 VDC open circuit voltage and adjust the load applied to 0.010 ampere to all circuits in series.
- 4.10.3 Oscillate the rotor 2 ±1 degrees @ 6-8 Hz.
- 4.10.4 At intervals of 100 -10 hours during the test, the rotor shall be rotated one revolution for noise test of all six circuit pairs simultaneously.
- 4.10.5 With the 8 channel optical recorder, monitor and record : the noise level on the data sheet.

- 4.10.6 When the noise test is completed, return the rotor to the original oscillation position ±1 degree, using the mechanical locator on the fixture.
- 4.10.7 5000 hours is the required duration of the life test.

4.10.8 The entire life test shall be performed in a nitrogen atmosphere.

- 4.11 Final Testing and Examination
 - 4.11.1 Upon completion of the life test, the capsule assembly shall be given the following tests:

DC Resistance Noise Torque Insulation Resistance per Para. 4.1, 4.2, 4.3 and 4.4 of this procedure ... and in addition a thorough visual examination

4.11.2 The visual examination shall include workmanship, contamination and seizure, per para. 3.4.16 and 4.4.4.1c, (1) and (2) of MSFC Drawing No. GC-125355 Rev. H.

A, P P E N D I X III

TEST DATA

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INSULATION RESISTANCE

INITIAL

P/S Part No. DP-1766Serial No. 3Date 2-28-69Test Voltage: 500 UDCSpecification: . Megohms Minimum

Circúit	Megohms
1	50000
2	2000
3	100 000
4	2000
5	100 000
6	20 000
7	ItIPOT SHOR
8	20 000
9	50 000
10	HIPOT SHOPT
1.1	50 000
12	40000

D.C. RESISTANCE

INITIAL

P/S Part No. DP-1766 Serial No. 3 Date 14 APR 69

Specification: .030 Ohms[±].015 Ohms Maximum

Test Current: 10 MA @ 10 VDC

-

Circuit	Ohms
1	. 681
2	.679
• 3	.685
4	.686
5	.678
- 6	.685
7	,699
8	.677
9	.671
10	.683 .
11	.673
12	.675

H. Fruin Technician

NOISE and TORQUE TEST

. INITIAL

P/S Part No. DP-1766	- Se	rial No.	<u>3</u> Date	14 APR 69
Noise Spec: Million	hn.		Torque Spec:	G/C Max.
			-	G/C Min.
Test Current: 100 MA	@ 10 VDC	Rotation:	<u>2 RPM</u> Osci	llation: 6HZ52
	<u> </u>			
	ct. Pairs	Reading		
	3-4	-6		
	<u>5-6</u> 7-8	5		
	<u>9-10</u> 11-12	65		

.

18 Starting Torque: <u>35</u> G/C

H. Juin Technician

CAPACITANCE

INITIAL

P/S Part No. DP-1766 Serial No. 3 Date 14 APR 69

Specification: PFD Maximum

Mounted in handling fixture with readings taken through plugs.

Circuit	Ckt Pair	Ground
1 2	43	2B · 28
3 4	44	27 27
5	42 .	27 27
7 8	. 64	33 · 27
9 10	57	2.8 33
. 11 · 12	42	2-8 2-8

H. Sruin Technician

ACCELERATION

P/S Part No. <u>DP-1766</u> Serial No. <u>3</u> Date <u>15\$16 HPR 69</u> Specification: <u>20 + 2G's for 30 Minutes each a</u>

No. Axes: 3

	DC Resista	nce		•		Noise	· · · ·
Ckt Pair	Axis I	Axis II	Axis III		Axis J	Axis II	Axis III
.1-2	1.3150	1.325.0.	1.305 a	•	5/19-2-	4 11 54	4 1.0
-3-4	1,325	1.335	1.325		7	.5	7
5-6	1320	1.325	1.315		7	4 ·	7
7-8 .	1.345	1.335	1.335		6	5	5.
9-10	1.315	1.305	1.295	•	6	7	7
11-12	1.820	1.300	1.300		6	7	7

REMARKS

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Note: Axis I - Axial direction Axis II - Radial I (Brushes Horizontal) Axis III- Radial II (Brushes Vertical)

H. Grun Technician

D.C. RESISTANCE

POST ACCELERAMON

Serial No. <u>3</u> Date <u>17 APR</u> 69 P/S Part No. DP-1766 .030 Ohms[±].015 Ohms Maximum Specification:

Test Current: 10 MA @ 10 VDC

• •

Circuit	Ohms
1	.685
2	,692
3	,641
4	.692
5	.682
6.	.688
7	.707
8 '	.687
· · 9	,678
10 .	.68-3
]1	,679
12	.680.

H. Truin Technician

NOISE and TORQUE TEST POST ACCELERATION

P/S Part No. D	P-1766 5	Serial No. <u>3</u>		Date 18 APA 69
Noise Spec:	Milliohms		Torque .	Spec: G/C Max.
	•			G/C Min
Test Current:_	100 MA @ 10 VDC	2 notation:	d KYM	Oscillation: $\underline{DH} \ge 5^{\circ} D$
	Ckt. Pairs	Reading		

	CK1. Pairs	Reading
	1-2	5
	3-4	В
	5-6	B
	7-8	6
	9-10	3
-	11-12	G
	Ť	

15 MIN Starting Torque: 19 MAX G/C

H. Grunn Technician

INSULATION RESISTANCE

POST ACCELERATION

P/S Part No. DP-1766 Serial No. 3 Date <u>4-22-69</u>

Test Voltage: <u>Sock DC</u> Specification: <u>Megohms Minimum</u>

Circuit	Megohas
1	70000
2	600
3	30000.
4	600
5	40000
6	5000
7	SHORT
8	10000
9	10000
10	Shopt
11	20000
12	20000

Fred Opens Technician

VIBRATION TEST

P/S Part No. DP-1766	Serial No	3:	Date	23	APR	69
Amplitude Limits: 0.06" Dis	sp. 1563 A	ccel.				
Frequency Limits: 20 to 200	00 Hz	-				
1013E BEGAN Axis I <u>1113E STOPPED</u>						
Maximum Noise: <u>30</u>	Milliohms	@ <u>20-7</u>	<u>50 Hz</u>			
08566 86641V Axis II <u>09566 stopped</u>						
Maximum Noise: 40*	Milliohms	@ <u>700-80</u>	<u>00</u> Hz ·			
0758E BEGAN Axis III <u>0853E STOPPED</u>						
Maximum Noise: 18	Milliohms	e <u>50-</u> 2	Hz			
REMARKS: * CIXTURE SHAFT	RESONANT	AT. THE	CREA A		- 4/	VINSE
REMARKS: * FIXTURE SHAFT		•				WOISE,
DO NOT BELIEVE RESONAN		RE FROM	BRUSHES	<u>ALO</u>	ME.	
	_					

Note: Axis J - Axial Direction Axis II - Radial I (Brushes Horizontal) Axis III - Radial II (Brushes Vertical)

H. Frein Technician

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D.C. RESISTANCE

POST VIBRATION

P/S Part No. <u>DP-1765</u> Serial No. <u>3</u> Date <u>24 APR 69</u> Specification: <u>+.030 Ohms[±].015 Ohms Maximum</u>

Test Current: 10 MA @ 10 VDC

Circuit	Ohms
1	.686
2	.681
• 3 -	.703
4	.681
5	,679
. 6 .	.683
7	.708
8	.681
9	.675
10	,684
11	.678
. 12 .	,677

H. Frenn Technician

NOISE and TOROHE TEST

POST VIBRATION

P/S Part No. DP-1	766 Seri	al No. <u>3</u>	Date	24	APR 69
Noise Spec: Mi	lliohms	Torque	Spec:	<u>.</u>	G/C Max.
			-		G/C Min.
Test Current: 100	0 MA @ 10 VDC	Rotation: 2 RPM	Usci	illati	on: <u>6//2</u> 5°DA.

$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	Ckt. Pairs	Reading
5-6 & 7-8 7 9-10 7	1-2	6
7-8 7 9-10 7	3-4	9
9-10 7	5-6	6
	7 ∸ 8	7
11-12	9-10	7
	11-12	4

Starting Torque: 19 MAX G/C

H. Junn Technician Tech

INSULATION RESISTANCE

POST VIBRATTON

P/S Part No. DP-1766 Serial No. 3 Date 4-25-69

Test Voltage: 500 VDC "pecification: Megohms Minimum

•

Circuit	Megohms
1	40000
2	1000
· 3	60000
4	900
5	90000
6	7000
7	Shert
8	20000
9	30000
10	SACAT
11	10000
12.	40000

<u>Fred</u> Opens Technician .

SHOCK TEST

P/S Part No. DP-1766	Serial No. <u>3</u> Date <u>30 APR 69</u>
Specification: 20 G's	No. Blows: 6 (1 blow each direction on each of 3 axes)
Axis I / 1 Blow	
Axis II l Blow l Blow	
Axis III 1 Blow 1 Blow	
REMARKS 1.35 V @ 9 MS	DUMINI 1/2 SING

Note: Axis I - Axial Direction Axis II - Radial I (Brushes Horizontal) Axis III - Radial II (Brushes Vertical)

N. Truin Technician

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NOISE and TORQUE TEST

POST SHOCK

P/S Part No. DP-1766	Serial No. <u>3</u>	Date	30. APR 69
Noise Spec: Milliohms		Torque Spec:	G/C Max.
		:	G/C Min.

Test Current: 100 MA @ 10 VDC Rotation: 2 RPM Oscillation: 6/25°D.

Ckt. Pairs	Reading
. 1-2	6
. 3-4	10
5-ó	6
7-8	θ
<u>9-10'</u>	10 .
11-12	6

19 MIN Starting Torque: 22 MAX G/C

H Druin Technician

D.C. RESISTANCE

POST SHOCK

Circuit	Ohms
1	. 688
2	.633
3	.642
4	,690
5	16B1
6	.686
. 7	.705
8	:634
9	1076
10	,684
11	.1ETB
12	1679

Julio Téchnician

INSULATION RESISTANCE

POST SHOCK

P/S Part No. DP-1766 Serial No. 3 Date 5-1-69

Test Voltage: 500 VDC Specification: : Megohms Minimum

Circuit	Megohms
1	30000
2 .	950
3	40000
4	850
5	70000
6	8 000
7	SOPAT
8	20000
9	20000
10	Sheet
11	30000
12	30000

<u>Fred</u> <u>Opers</u> Technician

D.C. RESISTANCE

AFTER LOAD TEST

P/S Part No. <u>DP-1766</u> Serial No. <u>3</u> Date <u>8 JUL 69</u> Specification:_______+.030 Ohms[±].015 Ohms Maximum

Test Current: 10 MA @ 10 VDC

Circuit	Ohms
1	.686
. 2	,686
3	.687
4 ·	,691
. 5	.679
·6 ·	,684
- 7	,677
8 ·	,680
9	.672.
10	,678
11	.677
12	.680

H. Fruin Technician

NOISE and TORQUE TEST

AFTER LOAD TEST

P/S Part No. DP-1766 Serial No. 3 Date 8 JUL 69 Torque Spec: G/C Max. Noise Spec: Milliohms G/C Min.

Test Current: 100 MA @ 10 VDC Rotation: 2-RPM Oscillation: 6 H2

Ckt. Pairs	Reading
1-2 .	11
3-4	14
5-6	18
7-8	22
9-10	1.1
11-12	12

Starting Torque: 25 G/C

H. Frinin

INSULATION RESISTANCE

AFTER LOAD TEST

Circuit	' Megohms
1	10
2	10
3 `	50
4	10
5	5
6	5
7	VII-POT SLOR
. 8	5
9	10
10	HI-PUT SHUR
11	10
12	In

Ful Open (23 Technician

INSULATION RESISTANCI

INITIAL

P/S Part No. DP-1766Serial No. 4Date 3-11-69Test Voltage: 500 VOCSpecification: Megohms Minimum

400 100 100 3000 .60
0 000 100 30 000 . 60
100 30000 .60
.60
.60
0 000
2000
100
0000
200
500
400
-000 .

F.L.A. Technician

D.C. RESISTANCE

INITIAL ņ P/S Part No. DP-1766 Serial No. 4 Date 31 MAR 69 Specification:_____+.030 Ohms[±].015 Ohms Maximum

•	
Circuit	Ohms
1	. 698
2	.702
3	. 7//
4	, 698
5	,705
6	.691
7	.695
8	.686
9	,690
10	,690
11	.689
12	.683

H. Junn Technician

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' NOISE and TORQUE TEST

INITIAL

	乌	
P/S Part No. DP-1766	Serial No. 4	Date 14 APR 69
Noise Spec: Milliohms	forq	ue Spec:G/C_Max
		G/C Min.

Test Current: 100 MA @ 10 VDC Rotation: 2RPM Oscillation: 6H2 5°DA

Ckt. Pairs	Reading
1-2	9
3-4	5
5-6	6
7-8	5
9-10	4
11-12	4
-	•

Starting Torque: /8 G/C

14. Suin Technician

CAPACITANCE

INITIAL

P/S Part No. DP-1766 Serial No. 4 : Date 14 APR 69

Specification: - PFD Maximum

Mounted in handling fixture with readings taken through plugs

	-	
Circuit	<u>Ckt Pair</u>	Ground
1 2	. 43 ·	2B 2B
3 4	• 43	27 28
5 6	• 47 • •	27 28
7 8	.45	2B 20
9 . 10	44	27 27
11 12	• 42	28 28

Juin

Technician

ACCELERATION

P/S Part No. <u>DP-1766</u> Serial No. <u>4</u> Date <u>15 \$16 Apr. 69</u>

Specification: 20 + 2G's for 30 Minutes each axis.

No. Axes: 3

DC Resistance					Noise			
Ckt Pair	Axis I	Axis Jŀ	Axis III	-	Axis J	Axis II	Axis	III
.1-2	1.3850	1.345 2	1.355 5.	•	6 112	4. 1150	4-	12.0
3-4 `	1.395	1.355	1.355-9-		5	5	4	•
5-6	1.390	1.340	1.360		6	5	6	·
7~8	1.395	1.345	1.345		5	4	3	7
9-10	1.395	1.345	1,345		5-	4	4	-
11-12	1.385	1.330	1.340		5	5ª=	6	******

- REMARKS

Note: Axis I, - Axial direction Axis II - Radial I (Brushes Horizontal) Axis III- Radial II (Brushes Vertical)

Juni-Technician

D.C. RESISTANCE

POST ACCELERATION

P/S Part No. DP-1766 Serial No. 4 Date 17 APR 69

Specification:

+.030 Ohms +.015 Ohms Maximum

Test Current: 10 MA @ 10 VDC

. Circuit	Ohms
· · 1.	.704
2	.706
3	.717
4	,704
· 5	.708
6	:698
7	1701
8	.673
9	.703
10	. 700
]].	,697
12 .	1690

num

Technician

NOISE and TORQUE TEST POST ACCELERATION

P/S Part No. DP-1766 Se	rial No. 4	Date 19 APR 69
Noise Spec: Milliohms	Torque	Spec:G/C Max.
		G/C Min.
Test Current: 100 MA @ 10 VDC	Rotation: 2281911	Oscillation: 64250
Ckt. Pairs	Reading	

Ckt. Pairs	Reading
1-2	7
3-4	_ۍ
5-6	5
· 7-8 ·	4
9-10	4
11-12	4

13 MM Starting Torque: 22 MAX G/C

.

Juin

Technician

INSULATION RESISTANCE

POST ACCELERATION

•

Circuit	Megohms
1	1000
2	20000
3	450
4	30000
5	400
6	30000
7	4.50
8	10000
9	1000
10	10000
11	2000
12	6000

Fred Obers Technician

VIBRATION TEST

P/S Part No. <u>DP-1766</u> Serial No. <u>4</u> Date <u>23 APR 69</u> Amplitude Limits: <u>0.06" Disp. 1/56's Accel</u>. Frequency Limits: <u>20 to 2000 Hz</u> Axis I <u>1/36 E BEGAN</u> Axis I <u>1/36 E BEGAN</u> Maximum Noise: <u>20 x</u> Milliohms @ <u>650-750</u> Hz Maximum Noise: <u>30 *</u> Milliohms @ <u>650-750</u> Hz Maximum Noise: <u>30 *</u> Milliohms @ <u>650-750</u> Hz Axis III <u>1/5236 STOP/PED</u> Maximum Noise: <u>50 *</u> Milliohms @ <u>650-750</u> Hz REMARKS: <u>x RESONANT SPIKES OCCURRED AT FIXTURE RESONANCE FREQUENCY</u>. <u>AT OTHER FREP. NOISE WAS 18 M.P. PEAK, ALL CIRCUITS IN SERIES WITH</u> <u>100.MA CURRENT</u>

Note: Axis I - Axial Direction - Axis II - Radial I (Brushes Horizontal) Axis III - Radial II (Brushes Vertical)

V. Fruin

D.C. RESISTANCE

POST VIBRATTON

P/S Part No. <u>DP-1766</u> Serial No. <u>4</u> Date <u>14 APR 69</u> Specification: <u>+.030 Ohms[±].015 Ohms Maximum</u>

Circuit	Ohms
1	.705
2	.707
3 :	,719
4	.706
5	. 711
6	. 701
7	. 702
8	1690
9	.697.
10	.689
. 11	.706
12 .	1691
· · ·	÷

Fruin

Tećhnician

QUAL1FICATION NOISE and TORQUE TEST

POST VIBRATION

P/S Part No. DP-1766 Serial No. 4 Date 14 APR 69

Noise Spec: Milliohms

Torque Spec: G/C Max.

G/C Min. Test Current: 100 MA @ 10 VDC Rotation: 2 RPM Oscillation: 6Hz 5° DA

Ckt. Pairs	Reading
1-2	5
3-4	5
5-6	6
7∸8	. 5
9-10	5
11-12	7
	l

Starting Torque: 16 MIN Starting Torque: 22 MAX G/C

H. Junior. Technician

'NSULATION RESISTANCE

POST VIBRATION

P/S Part No. DP-1766 Serial No. 4 . Date 4-25-69

Test_Voltage: 500 VOC Specification: Megohms Minimum

Circuit	Megohins
1	2000
2	20000
3	900
4	40000
5	200
6	50000
7	1000
8	20000
9	1500
1.0	20000
]]	1500
12	7000

<u>Ful Okno</u> Technician

SHOCK TEST

 P/S Part No. <u>DP-1766</u>
 Serial No. <u>4</u>
 Date <u>30 APR 69</u>

 Specification: <u>20 G's</u>
 No. Blows: <u>6</u> (1 blow each direction on each of 3 axes)

 Axis I
 <u>1</u> 1 Blow Down

 <u>1</u> 1 Blow Up

 Axis II
 <u>1</u> 1 Blow Down

 <u>1</u> 1 Blow Up

 Axis II
 <u>1</u> 1 Blow Down

 <u>1</u> 1 Blow Up

 Axis III
 <u>1</u> 1 Blow Down

 <u>1</u> 1 Blow Up

 Axis III
 <u>1</u> 1 Blow Down

 <u>1</u> 1 Blow Up

 REMARKS
 <u>1.35V @ 9MS DURAHON 12 SINE</u>

Note: Axis I - Axial Direction Axis II - Radial I (Brushes Horizontal) Axis III - Radial II (Brushes Vertical)

H. Trum

NOISE and TORQUE TEST

POST SHOCK

P/S Part No. DP-1766	Serial No. <u>4</u>	Date <u>5</u>	DAPR 69
Noise Spec: Milliohms	Tore	que Spec:	G/C Max.
			G/C Min.

Test Current: 100 MA @ 10 VDC Rotation: 2RPM Oscillation: 6/25°DA

Ckt. Pairs	Reading
1-2	5
3-4	4
5-6	5
7-8	4
9-10	6
11-12	7
-	

•

Starting Torque: 19 MAX G/C

1. Druun Technician

D.C. RESISTANCE

POST SHOCK

P/S Part No. <u>DP-1766</u> Serial No. <u>4</u> Date <u>MAY</u> Specification: ______+.030 Ohms[±].015 Ohms Maximum

Circuit	Ohms
1	.705
2	,708
3	.716
4	.706
. 5	.709
6	,696
7	1702
8	. 689
. 9	.696
10	.688
11	1092
12	.689 .

H. Juin

Technician

INSULATION RESISTANCE

POST SHOCK P/S Part No. DP-1766 Serial No. 4 Date 5-1-69

Test Voltage: 500 VDC Specification: Megohms Minimum

Circuit	Megohms
1	1500
2	20000
3	900
4	50000
5	900
6	40000
7	900
8	20000
9	30
1.0	20000
11	50
12	10000

Fred Ohers

D.C. RESISTANCE

AFTER LOAD TEST

P/S Part No. DP-1766	Serial No. 4	Date 8 JUL 69
Specification:	+.030 Ohms [±] .015 (Dhms Maximum

Circuit	Ohms
- 1	,700
2 ·	1.693
3	,714
4	,702
5	,702
6	. 692
7	. 699
8	.686
9	.690
10	,685
11	,689
12	.685

H. Junn Technician

NOISE and TORQUE TEST

AFTER LOAD TEST

 P/S Part No. <u>DP-1766</u>
 Serial No. <u>4</u>
 Date <u>8 JUL 69</u>

 Noise Spec: <u>Milliohms</u>
 Torque Spec: <u>G/C Max.</u>

G/C Min.

Test Current: 100 MA @ 10 VDC Rotation: 2" RPM Uscillation: 6 H>

Ckt. Pairs	Reading
1-2	4
3-4	4
5-6	3
7-8	2
9-10	2

-Starting Torque: 22 G/C

H. Fruin

INSULATION RESISTANCE

AFTER LOAD TEST

P/S Part No. DP-1766Serial No. 4Date 7-14-69Test Voltage: 5001 DC.Specification: Megohms Minimum

.

t	· · · · · · · · · · · · · · · · · · ·
Circuit	Megohms
]	10
2	40
3	5
4	50
- 5	4
6	50
7	5
8	40
9	8
10	20
11	سی
12	40

<u>Ful</u> Okern (23) Technician

NSULATION · RESISTANCE

INITIAL

. .

 P/S Part No. <u>DP-1766</u>
 Serial No. <u>NONE (S/N 5)</u> Date <u>3-31-69</u>

 Test Voltage: <u>500 VDC</u>
 Specification: <u>Megohms Minimum</u>

Circuit	Megohms
1.	2500
. 2	250
3	1500
4.	HIPOT SHORT
5	HIPST SHORT
· 6	500
7	40
8	2000
9	HIPOT SHORT
· 10	5000
11	HIPOT SHORT
12	HIPOT SHORT

<u>F.L.A.</u> Technician

D.C. RESISTANCE

INIIAL

P/S Part No. DP-1766

Serial No. NONE (SIN 5) Date 14 APR 69

Specification:_____

+.030 Ohms[±].015 Ohms Maximum

Circuit	Ohms
1	. 620
· 2	.637
3	.634
4	.768
5	.630
6	.628
7	.632
· 8	.624
9	.629
10	:628
11	.625
12	690

H. Juin Technician

NOISE and TORQUE TES1

INITIAL

P/S Part No. DP-1766 Serial No. NONE (S/115) Date 14 APR.69 Torque Spec: G/C Max. Noise Spec: Milliohms G/C Min. Test Current: 100 MA @ 10 VDC Rotation: 2RPM Oscillation: 6Hz@ 50

Ckt, Pairs	Reading
1-21-4	8
3-42-5	4
5-63-9	9
7-56-11	3
9=108-12	8
11-1-2.7-10	5
	-

35 Starting Torque: 45 G/C

H. Truun Technician

CAPACITANCE

. INITIAL

P/S Part No. DP-1766 Serial No. NONE (S/N5) Date 14 APR 69

Specification: PFD Maximum

.

Mounted in handling fixture with mondings taken through plugs.

		-	
Cir	<u>cuit</u>	<u>Ckt Pair</u>	Ground
1	1 .	- 39 -	27
	2		27
	3	60	2B 37
	4	<i>\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\</i>	
-	5	· 68	37 28
	6		28
	7	.41	27
	8		27
	9	40.	27
1	0	-10	27
1	1 .	-0	27
1		· 58	37

H. Sruin. Technician

ACCELERATION

P/S Part No. <u>DP-J766</u> Serial No. <u>NONE (S/N_5)</u> Date <u>15 & 16 APR 69</u> Specification: <u>20 + 2G's for 30 Minutes each axis</u>.

No. Axes: 3

DC Resistance		Noise					
Ckt Pair	Axis I	Axis II	Axis 111		Axis I	Axis II	Axis JI1
1-4 1-2	1.3355	1,335 s.	1.325.0.	•	6 100	5 M.a.	4 M.S.
3-4	1,1950	1.2152	1.2050		7	4	4
3-9	1.2200	1.210-0-	1.7100		5.	5	6
<i>4</i> -31	1.195 5	1.1955	1.2055		5	4	4
3-13	1.2.45 5	1,245 52	1.2350	•	4	6	5
	1.220.2	1.2055	1.220-52		5	6	6

REMARKS

Note: Axis I - Axial direction Axis II - Radial I (Brushes Horizontal) Axis III- Radial II (Brushes Vertical)

juin

Technician

D.C. RESISTANCE

POST ACCELERATION

P/S Part No. DP-1766 Serial No. NONE (</N5) Date 17 APR 69 Specification:______+.030 Ohms[±].015 Ohms Maximum

Circuit	Ohms
].	.625
2	,641
3	,637
4	.771
5	1645
6	:638
7	. 640
8	1630
9	.633
10	. 640
11	. 428
12 .	. 677

H. Junion Technician

NOISE and TORQUE TEST

POST ACCELERATION

P/S Part No. DP-1766 Serial No. NONE (S/N5) Date 18 APR 69

Torque Spec: G/C Max.

Noise Spec. Milliohms

G/C Min. Test Current: 100 MA @ 10 VDC Rotation: 2 R PM Oscillation: 6.112.5°DA

Ckt. Pairs Reading 1-2 6 ٠ 3 3-4 .5-6 4. 3 7-8 Ð 9-10 3 11-12

Starting Torque: 35 MAX G/C

H. Frunn Technician

INSULATION RESISTANCE

POST ACCELERATION

P/S Part No. DP-1766 Serial No. NONE (S/N 5) Date 4-22 -69

Test Voltage: 500 KDC

Specification: <u>Megohms Minimum</u>

Circuit	Megohms
. 1	2000
• 2	100
3	2000 .
4	Shear :
5	Spear
6	150
• 7	20
8	700
9	Shert
10	800
11	SHERT
12	Sheat

- Lechnician

VIBRATION. TEST

P/S Part No. DP-1766 Serial No. NONE (S/N-5) Date 22 APR 69
Amplitude Limits: 0.06" Disp. 156's Accel.
Frequency Limits: 20 to 2000 Hz
IIISE BEGAN Axis I <u>121SE STOPPED</u>
Maximum Noise: 10-14 Milliohms @ 1000-1250 Hz
12525 BEGAN Axis II <u>1352E STOPPED</u> Maximum Noise: // Milliohms @ 700-1000 H:
1355E BEGAN Axis III <u>1455E STOPPED</u>
Maximum Noise: <u>10</u> Milliohms @ <u>700-800</u> Hz

REMARKS : PA	AK NOISE	DCCURRED	AT RESONANT	FREQ.	OF FIXTURE	DRIVE
SHAFT.						

Note: Axis I - Axial Direction Axis II - Radial I (Brushes Horizontal) Axis III - Radial II (Brushes Vertical)

Turn. Technici

D.C. RESISTANCE

POST VIBRATTON

P/S Part No. DP-1766 Serial No. NONE (S/N 5) Date 24 APR 69

Specification:______ 30 Ohms[±].015 Ohms Maximum

Circuit	Ohms '
1	,620
2	,640
3 :	:636
4	.757
5	.675
6	1632
7	. 10 34
8	.627
9	,628
10	.629
11	1675
12	.675

H. Fruin Technician

NOISE and TORQUE TEST.

POST VIBRATION

P/S Part No. DP-1766 Serial No. NONE (S/N 5) Date 24 APR 69

Noise Spec: Milliohms

Torque Spec: G/C Max.

G/C Min.

Test Current: 100 MA @ 10 VDC Rotation: 2RPM Oscillation: 6/125°DA

*			
Ckt. Pairs	Reading		
1-2-1-4	5		
3	5		
5-63-9	7		
7-8 6-11	· A		
9-107-10			
11-128-12	6		
	· ·		

25 MIN Starting Torque: <u>38 MAX</u> G/C

H. Simin Technician

INSULATION RESISTANCE

POST VIBRATION

P/S Part No. DP-1766 Serial No. NONE (S/N 5) Date 4-25-69

Test Voltage: 500 VDC Specification: Megohms Minimum

Circuit	Megohms
1	7000
2	200
3	5000
4	Short
5	Sheat
6	300
7	40
8	1500
9	Shent
10	2500
]]	Short
12	Short

<u>Fred</u> Okeno Technician

SHOCK TEST

 P/S Part No. <u>DP-1766</u>
 Serial No. <u>NONE (S/H 5)</u> Date <u>30. APR 69</u>

 Specification: 20 G's
 No. Blows: <u>6</u> (1 blow each direction on each of 3 axes)

 Axis I
 $\frac{1}{-1}$ 1 Blow Down

 Axis I1
 $\frac{1}{-1}$ 1 Blow Up

REMARKS 1.351 @ 9 MS DURATION 1/2 SINE.

Note: Axis I - Axial Direction Axis II - Radial I (Brushes Horizontal) Axis III - Radial II (Brushes Vertical)

H. Truir

Technician

NOISE and TORQUE TEST

. POST SHOCK

P/S Part No. DP-1766Serial No. NONE (S/H 5)Date 30 APR 69Noise Spec:MilliohusTorque Spec:G/C Max.

G/C Min.

Test Current: 100 have to vJC Rotation: 2-RPM Oscillation: 6 HZ 5°DA

Ckt. Pairs	Reading
1-21-4.	5-
3-4 2-5	7
5-3-9	9
7-37-10	. 5
-916-11	6
++=18-12	6

19 MIN Starting Torque: <u>38 MAX</u> G/C

H. Truen Technician

D.C. RESISTANCE

POST SHOCK

P/S Part No. DP-1766 Serial No. NONE (S/N5) Date / MAY 69 Specification:_____.030 Ohms[±].015 Ohms Maximum

Test Current: 10 MA @ 10 VDC

.

Circuit	Ohms
· 1	.620
2	.639
3	1:34
4	.76.8
5	lefte
· 6 ·	,630
7	. 634
8	. 630
9	, 1029
10	,631
11	,673
12	,674

H. Schlink Technician

INSULATION RESISTANCE

POST SHOCK

P/S Part No. DP-1766 Serial No. NONE(S/N 5) Date 5-1-69

Test Voltage: <u>500 VDC</u> Specification: <u>Megohms Minimum</u>

Circuit	Megohms
1	4000
2	150
3	4000
<u>4</u> ·	ShORT
5	Shent
6	250
7	30
8	1000
9	Shent
10	2000
]1	SHORT
12	Short

Fred Opens Technician

D.C. RESISTANCE

AFTER LOAD TES P/S Pari No. <u>DP-1766</u> Serial No. <u>NONE (s/N</u>5) Date <u>B JUL 69</u> Specification:______+.030 Ohms[±].015 Ohms Maximum

Test Current: 10 MA @ 10 VDC

	Circuit	Ohms
	1	.620
•	2	.638
	3	.635
	4	,768
~	5	.625
	6	.627
	7	,631
ļ	8	,623
	9	,629
	10	;630
	11	:623
L	12 ·	.670
	•	

H. Fruin

NOISE and TORQUE TEST

AFTER LOAD TEST

P/S Part No. DP-1766 Serial No. NONE (S/N 5) Date 8 JUL 69 Torque Spec: G/C Max. G/C Min. Noise Spec: Milliohms

Test Current: 100 MA @ 10 VDC Rotation: 2 RPM Oscillation: 6 Hz

Ckt. Pairs	Reading
1-21-4	11
3-4 2-5	
5-6 3-9	11
7-8 6-11	6
9-10 7-10	6
11=12 8-12	7
•	-
	•

Starting Torque: 44 G/C

H. Juin Technician

• •

INSULATION RESISTANCE

AFTER LOAD TEST

 P/S Part No. DP-1766
 Serial No. NONE (5/H 5) Date 7.14 - 69

 Test Voltage: 500 V UC
 Specification: Megohms Minimum

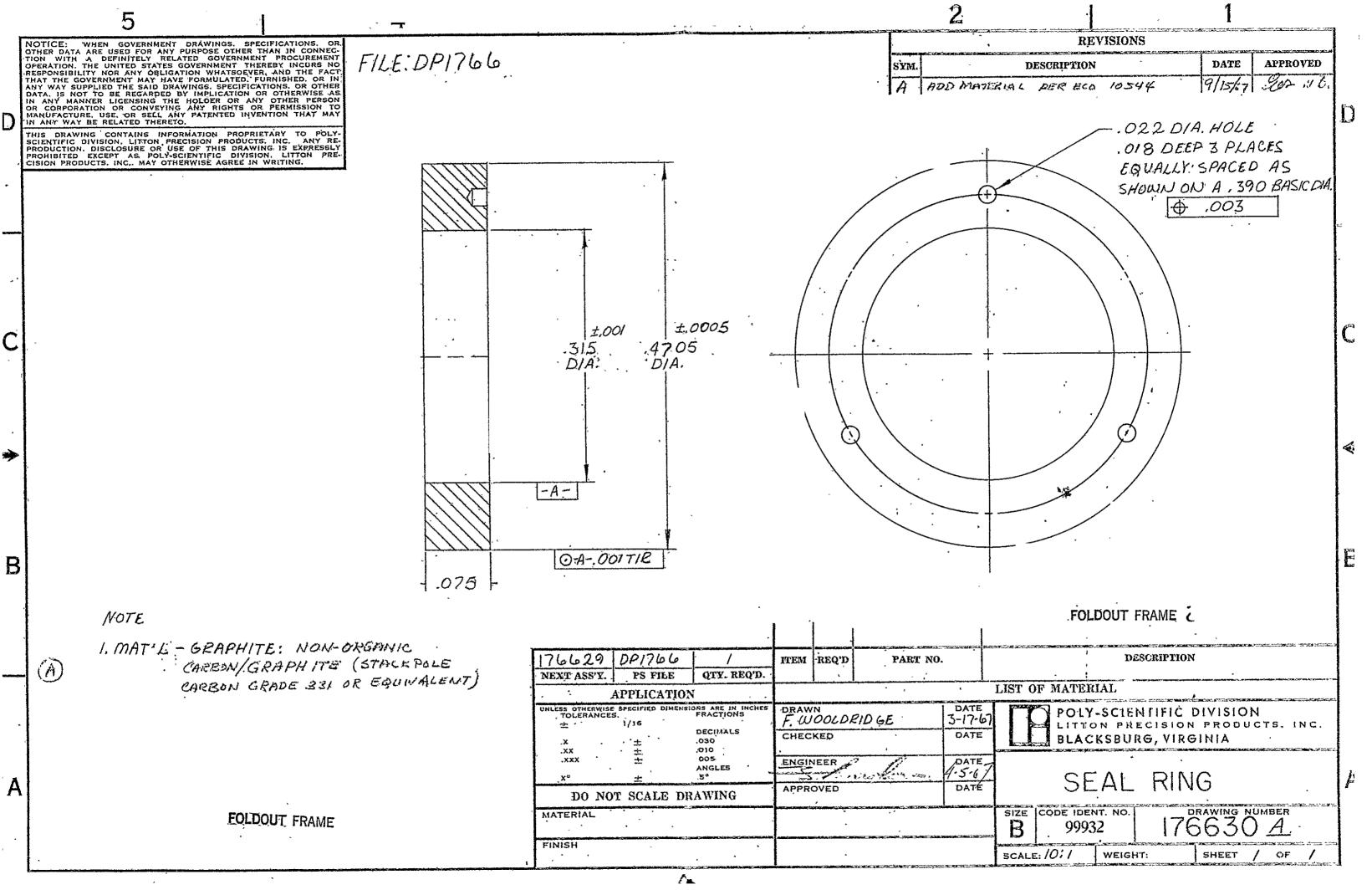
Circuit	Megohms
1	14
2	5
3	Mi-Por Sheri
4	Hi-Pot Shall
5	Hi POT Shift
6	20
7	10
88	20
9	Hi-Pot Short-
10	20
11	VII-POT Shaft
12	HI-POT Speet

Fiel Open (Technician

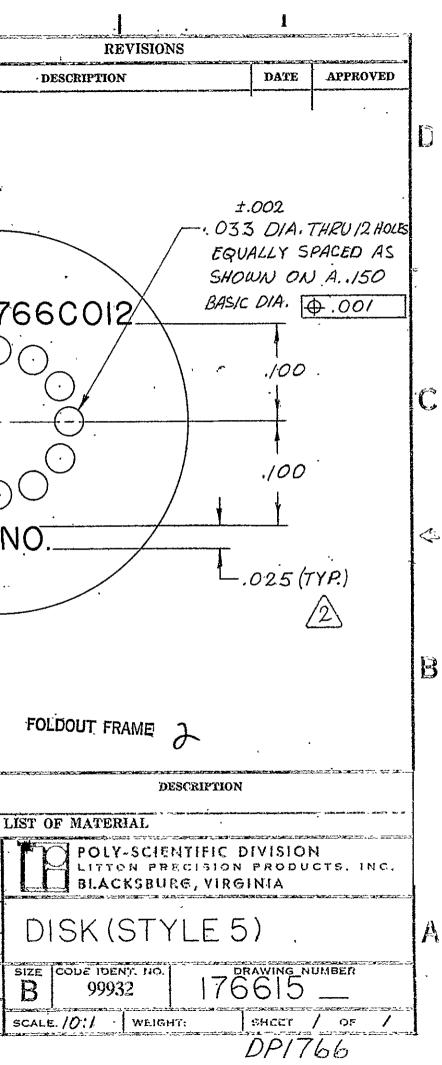
A P P E N D I X IV

ENGINEERING DRAWINGS



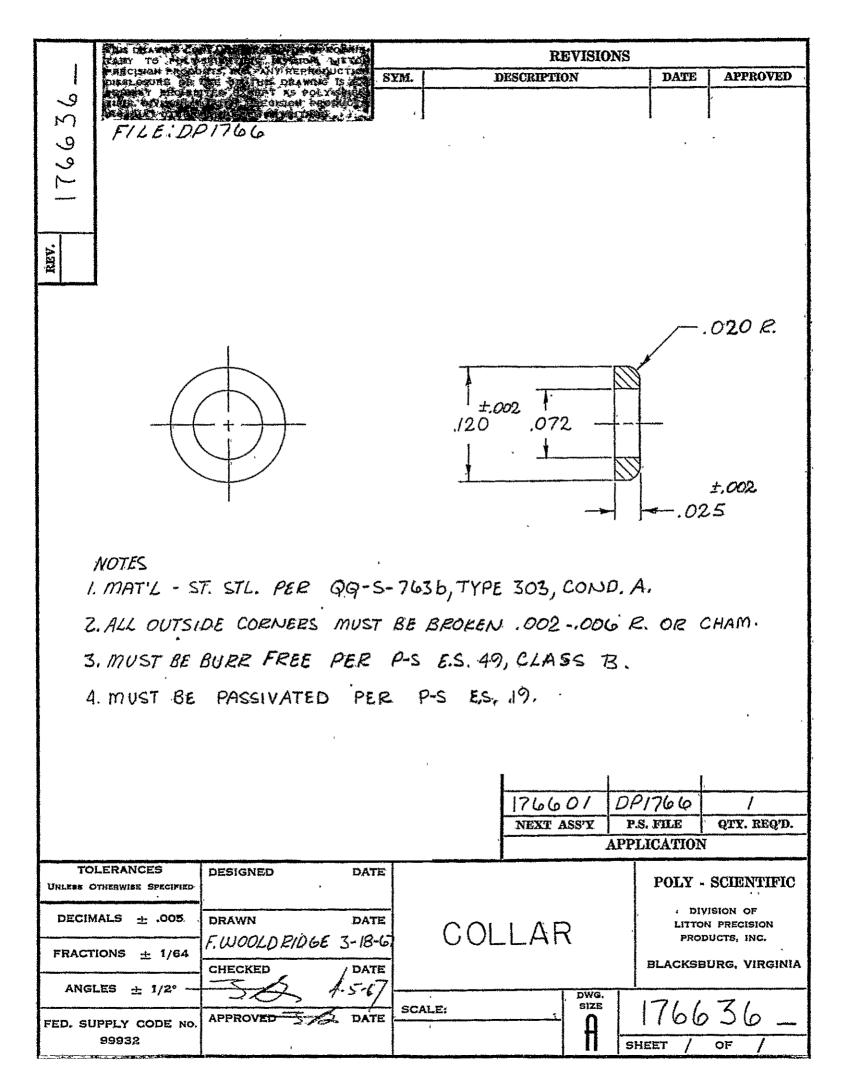


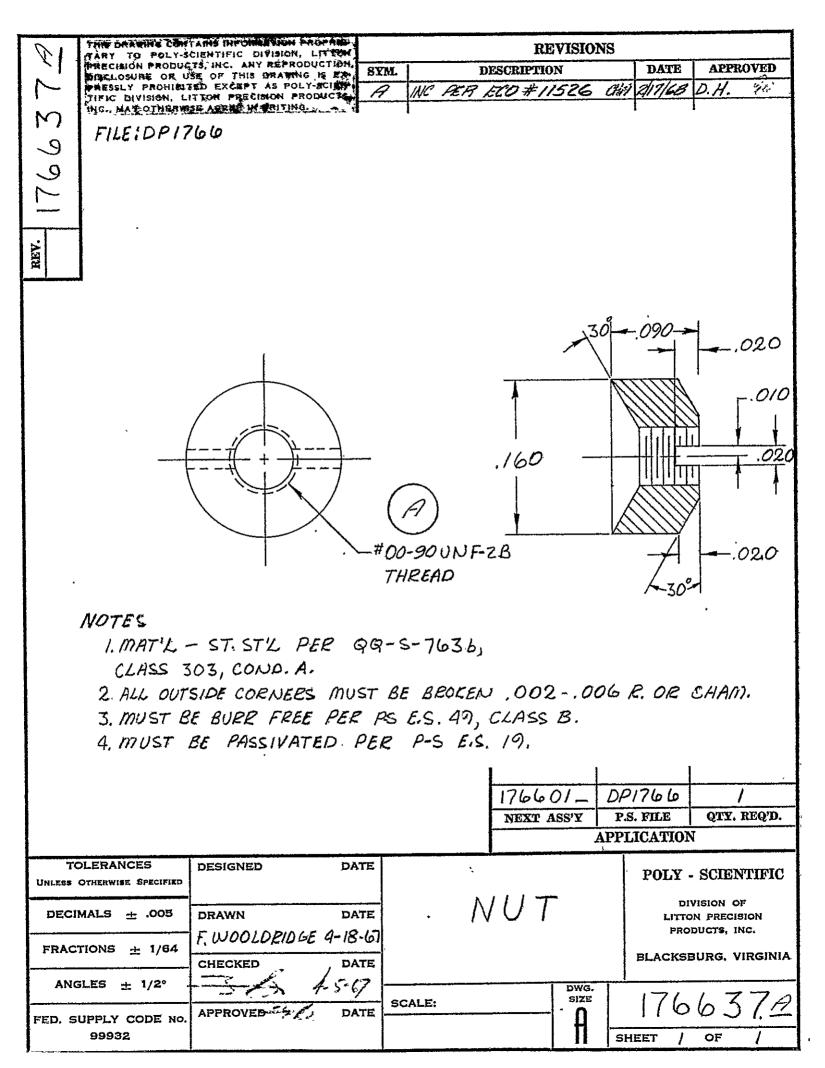
	5	4	₹ 3	
	NOTICE: WHEN GOVERNMENT DRAWINGS. SPEC OTHER DATA ARE USED FOR ANY PURPOSE OTHER T TION WITH A DEFINITELY RELATED GOVERNMEN OPERATION. THE UNITED STATES GOVERNMENT THE RESPONSIBILITY NOR ANY OBLIGATION WHATSOEVER THAT THE GOVERNMENT MAY HAVE FORMULATED FI ANY WAY SUPPLIED THE SAID DRAWINGS. SPECIFICA DATA. IS NOT TO BE REGARDED BY IMPLICATION O IN ANY MANNER LICENSING THE HOLDER OR ANY OR CORPORATION OR CONVEYING ANY RIGHTS OR MANUFACTURE. USE. OR SELL ANY PATENTED INVE IN ANY WAY BE RELATED THERETO. " THIS DRAWING, CONTAINS INFORMATION PROPRIE SCIENTIFIC DIVISION. LITTON PRECISION PRODUCTS PRODUCTION, DISCLOSURE OR USE OF THIS DRAWING PRODUCTION, PRODUCTS, INC., MAY OTHERWISE AGREE IN	TIONS, OR OTHER R OTHERWISE AS Y OTHER PERSON NTION THAT MAY ETARY TO POLY- S. INC. ANY RE- NG IS EXPRESSLY	±.001 	SYM.
			040	PIN DPI7
C			1.003 394 2/A. 12	044
•				SERIAL
B				2
	NOTES: 1. MAT 12 - FO 2. DEPTH OF	TO FORM B. CHARACTERS MUST [*] BE . 010.	176602 DP1766 1 NEXT ASS'Y. PS FILE QTY. REQ'D.	FTEM REQ'D PART NO.
	· ·		APPLICATION UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN INCHES TOLERANCES: FRACTIONS	DRAWN F. WOOLDRIDGE 2-78-67
A	EOLDOUT FRAME		$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	F. WOOLDRIDGE 2-78-67 CHECKED DATE ENGINEER DATE Jon 3-22-67 APPROVED DATE
			MATERIAL	
			FINISH	



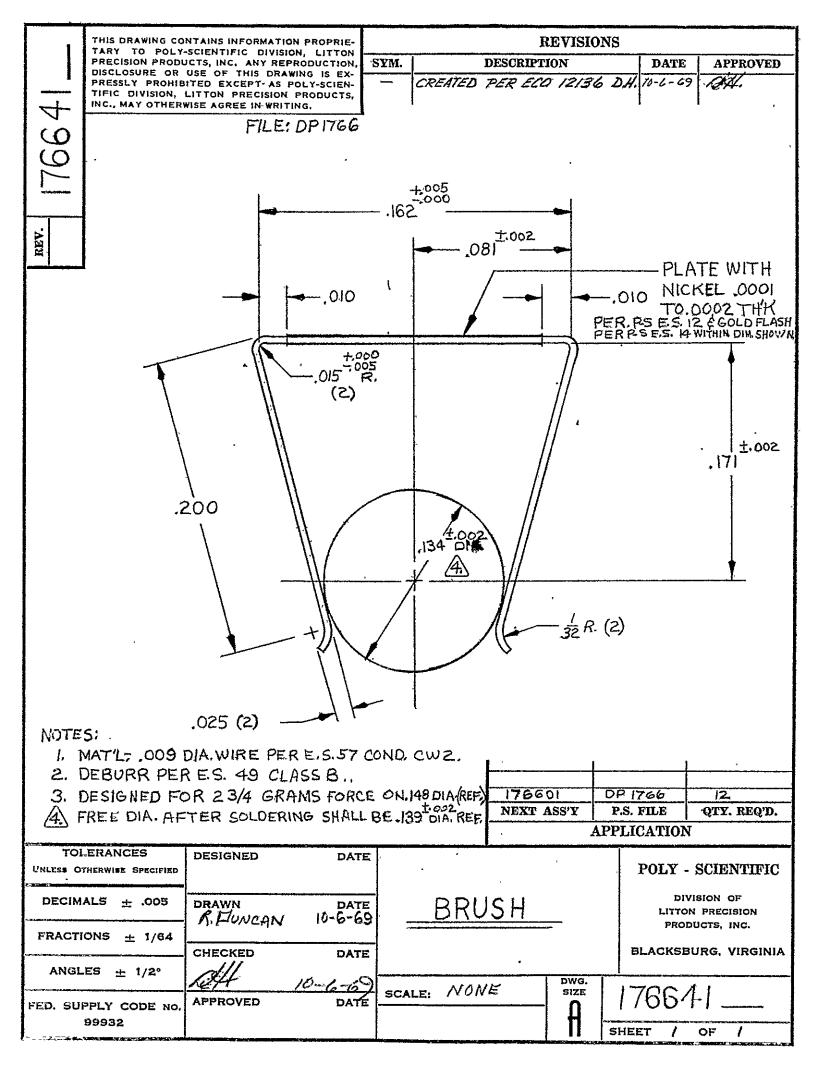
•		LIST	OF DRAWINGS		
ENGR. REF.	PART NUMBE	R QTY.		DESCRIPTION	•
DP 1766	176601 <u>A</u>		CAPSULE ASSY		
l l	176602 🗅	(E) 1 '	SLIP RING A	SSY .	
	176603 _		ŚLIP'RIN	G SUB-ASSY	
	176605 _	2 3	DISK	(STYLE I)	
	176606 <u></u>	1	DISK	(STYLE 2)	
	176607 🦽	2 14	DISK	(STYLE 3)	
	176608 _	2, 2	DISK	(STYLE 4)	
	1	•	III III IIII IIII IIII IIII IIIIIIIIII	t Tress ()	
	176612 <u>B</u>	12		(SLIP RING INTERNAL)	
	176640	_· 1	SHA	F.T : 3	
	176604 _	2 1	SLIP RIN	G BASE	
	176613	24	LEAD (EX	TERNAL)	
	176615		DISK (ST	YLE 5)	
	176616 🖻	(E) 1	BRUSH BLOCK	ASSY (ODD)	
ļ	176617 😤	(E) 1	BRUSH BL	OCK SUB-ASSY (ODD)	
	176619-1	$\frac{\Lambda}{1}$ 1		(ODD)	
	176619-2 176619-31	$\frac{1}{5(6)}$ 1	WAFER WAFER		
	176619 4	$B(\underline{E}) = 1$	WAFER	(ddd)	
	176619-5			(QDD) (ODD)	
	[70019-0				
	176621-1' thru	<u>A</u> 4 ea	LE	AD (B.B. INTERNAL)	1
	176621-3	<u>A</u> .			
	1 1 1 1 C	≣) ∃			
	176624		INSULATO	R	
	176625 🚊	<u>5</u> (E) 1	BRUSH BLOCK	ASSY (EVEN)	
	176626 <u>B</u>	<u>(</u> E) 1	BRUSH BL	OCK SUB-ASSY (EVEN)	
	,	/ = 1			
		(E)			
	176630	1	SEAL RING		
DP 1766	176631	-	SUPPORT RIN	422A 3	4
51 1700		- '	SOFTONT MIN		:
PREPARED LGRAY	DATE 6-12-67		N OCHONYAYO	LIST OF DRAWINGS	
- -			Y-SCIENTIFIC	CAPSULE ASSY	•
UNEUKED	DATE	LITTON PRI	ECISION PRODUCTS, INC.	UMI JULL HJJI	
10000VCD		BLACK	SBURG, VIRGINIA	l	
APPROVED	DATE			LD-DP1766C012	REV.
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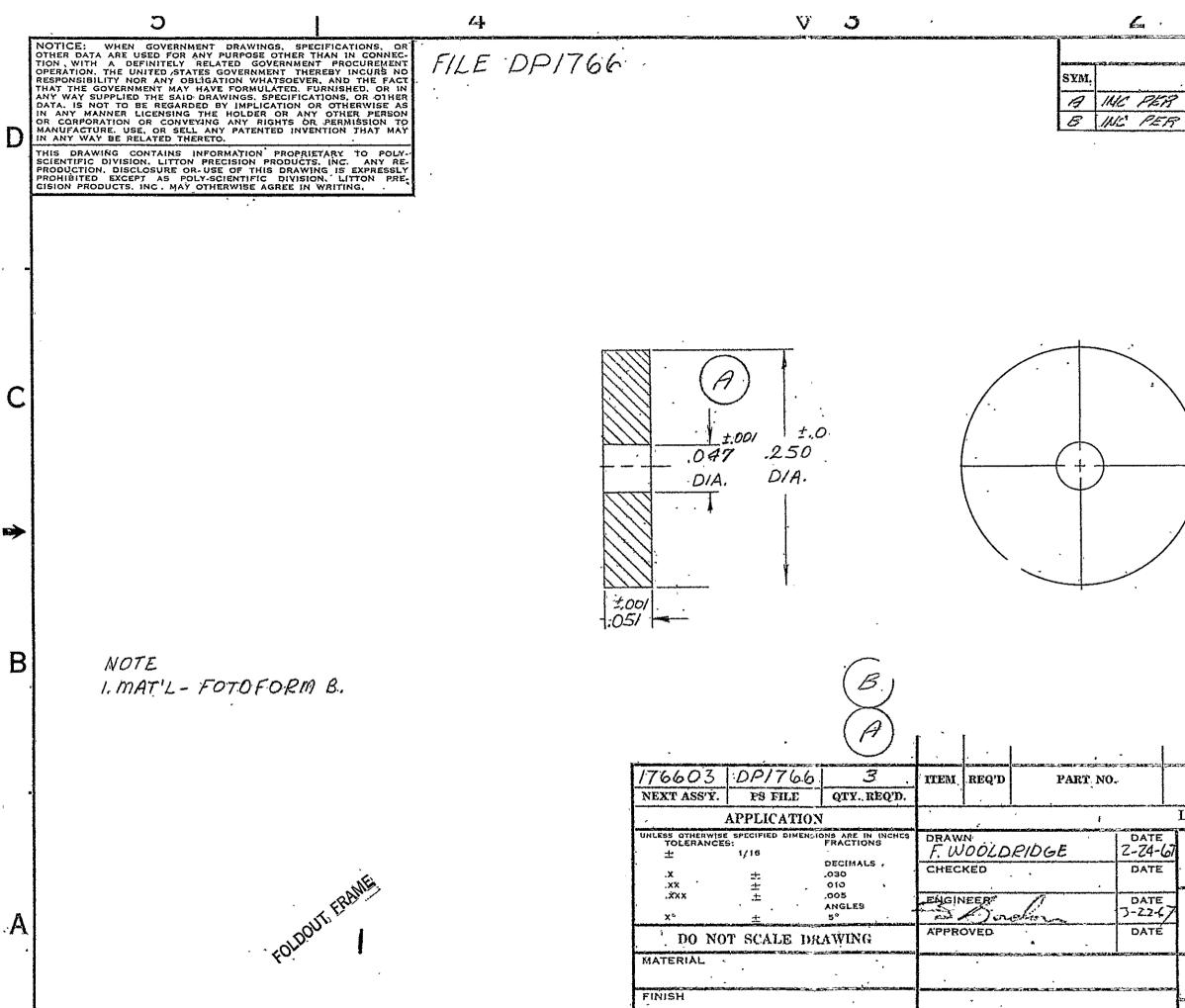
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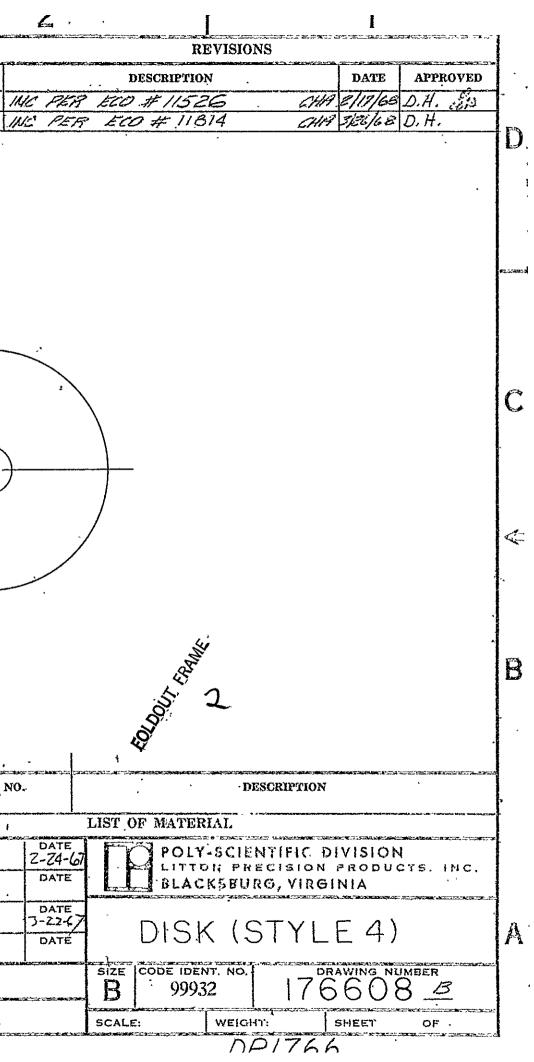


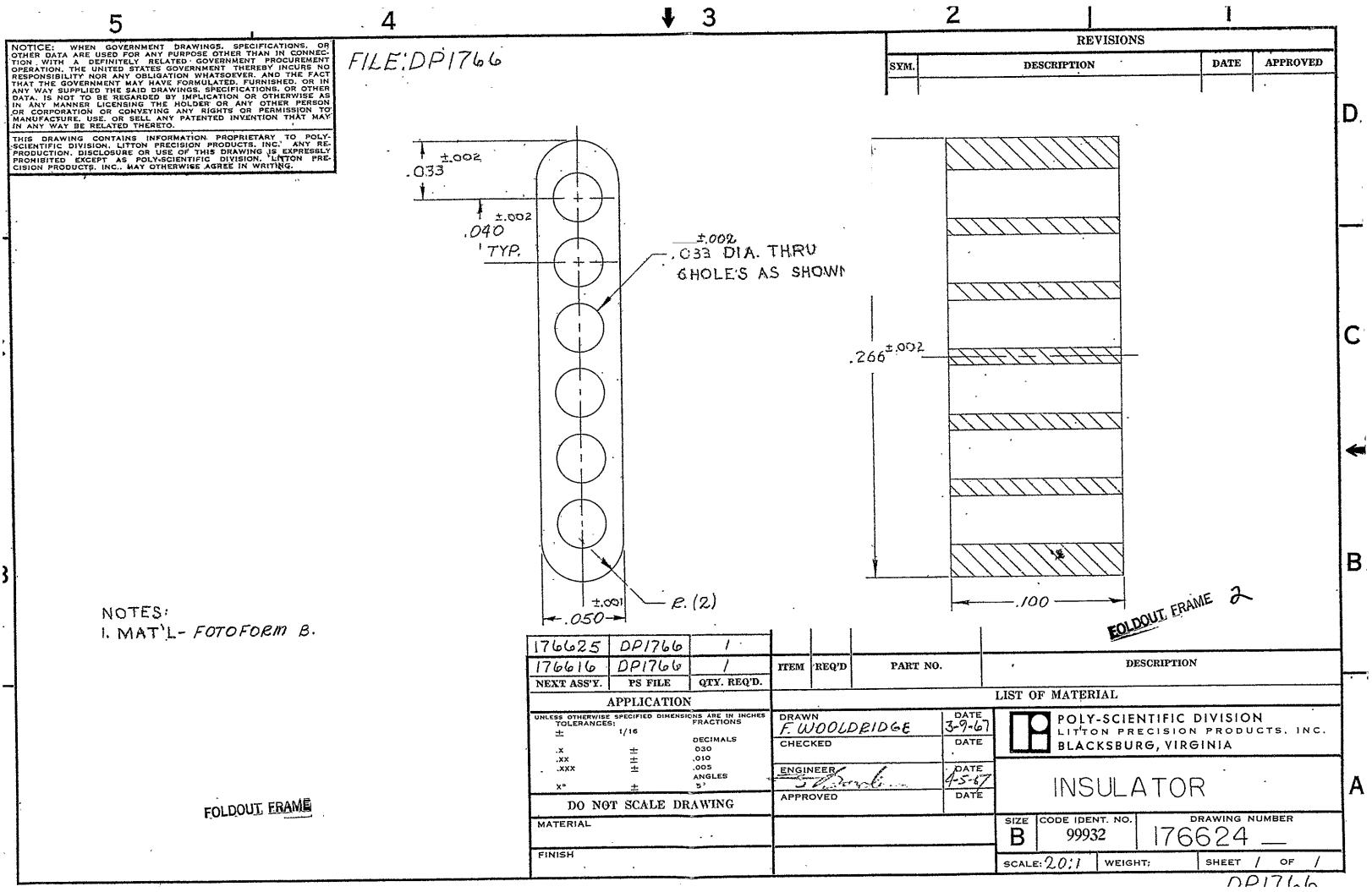


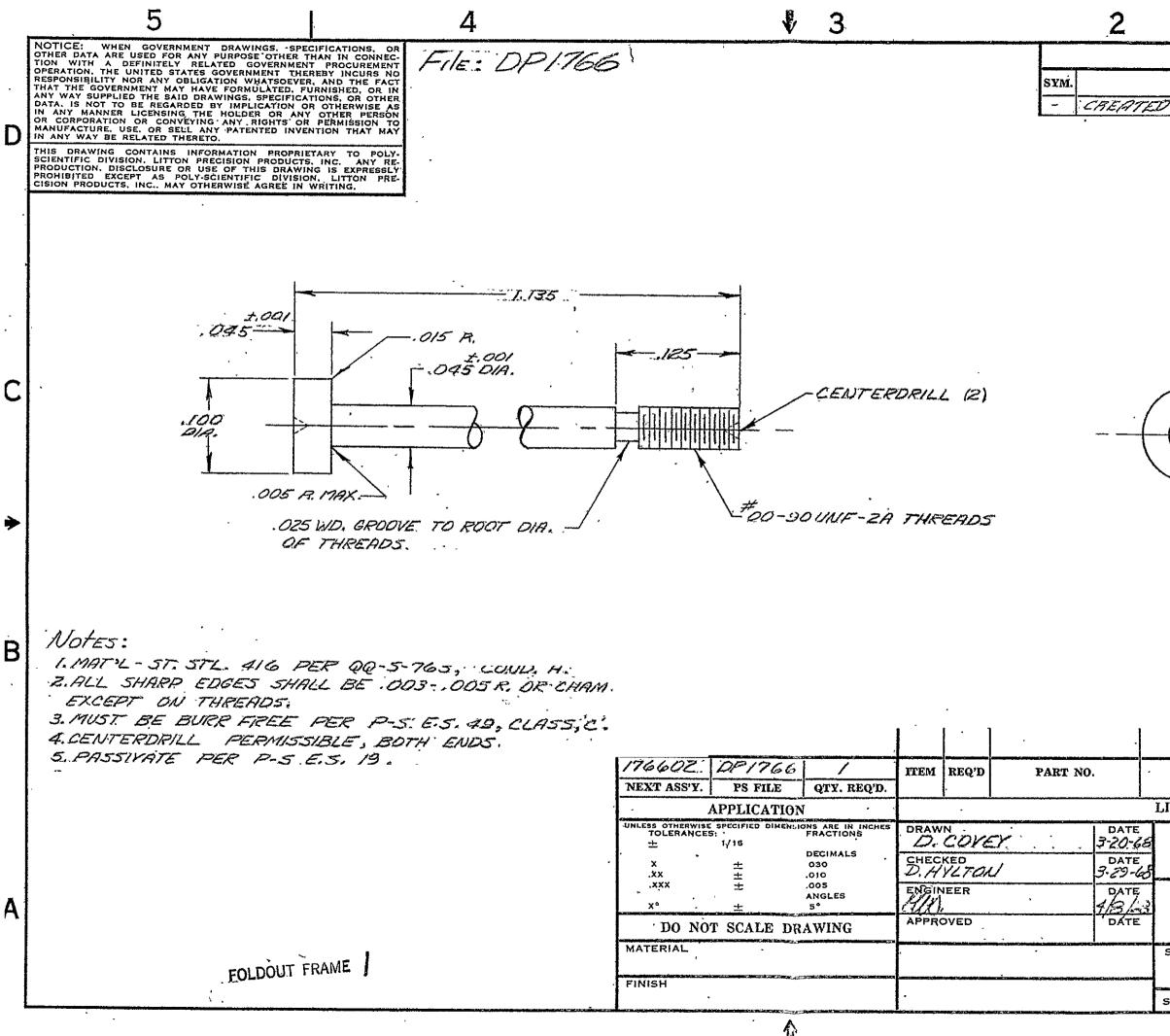
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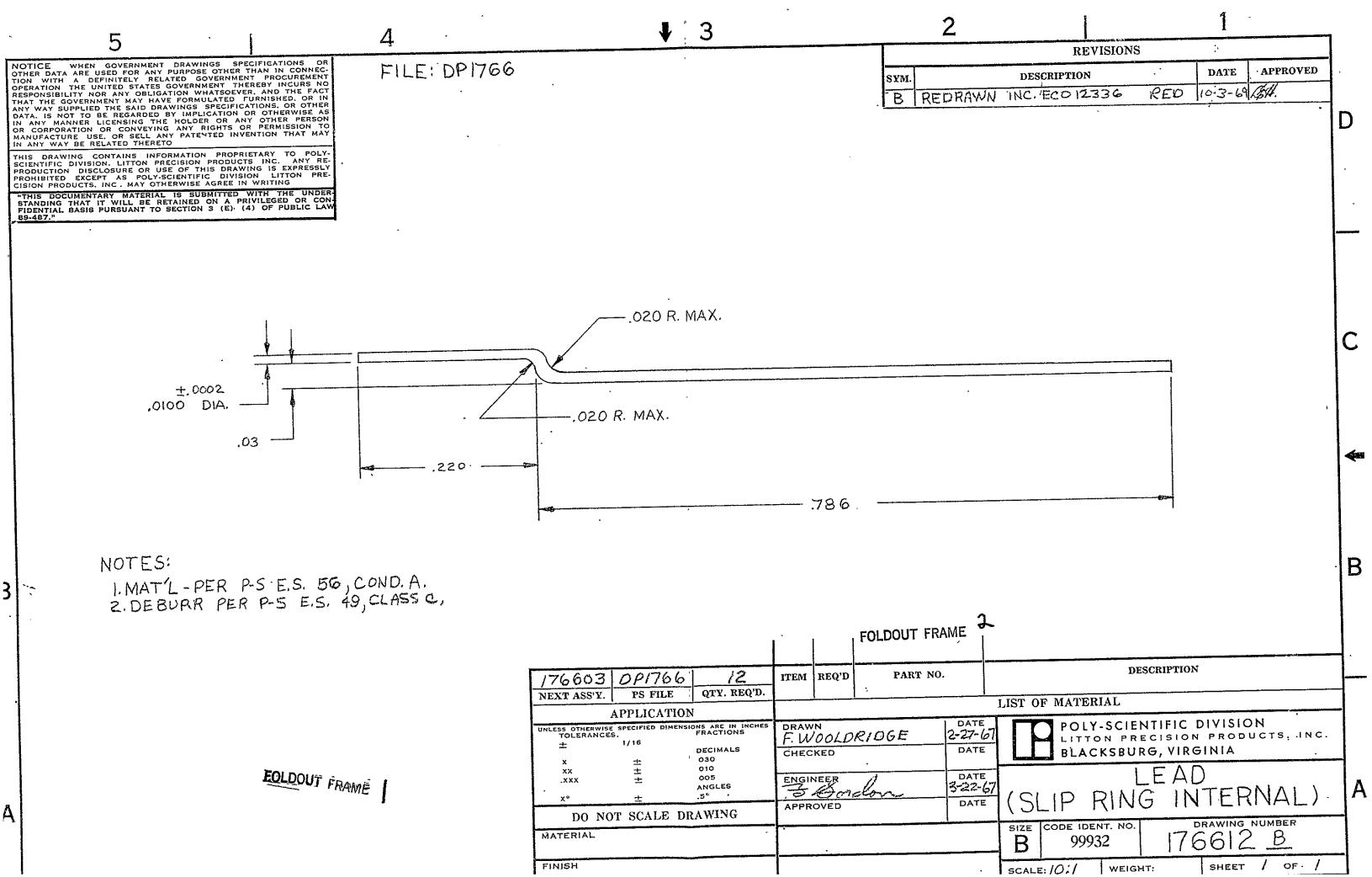


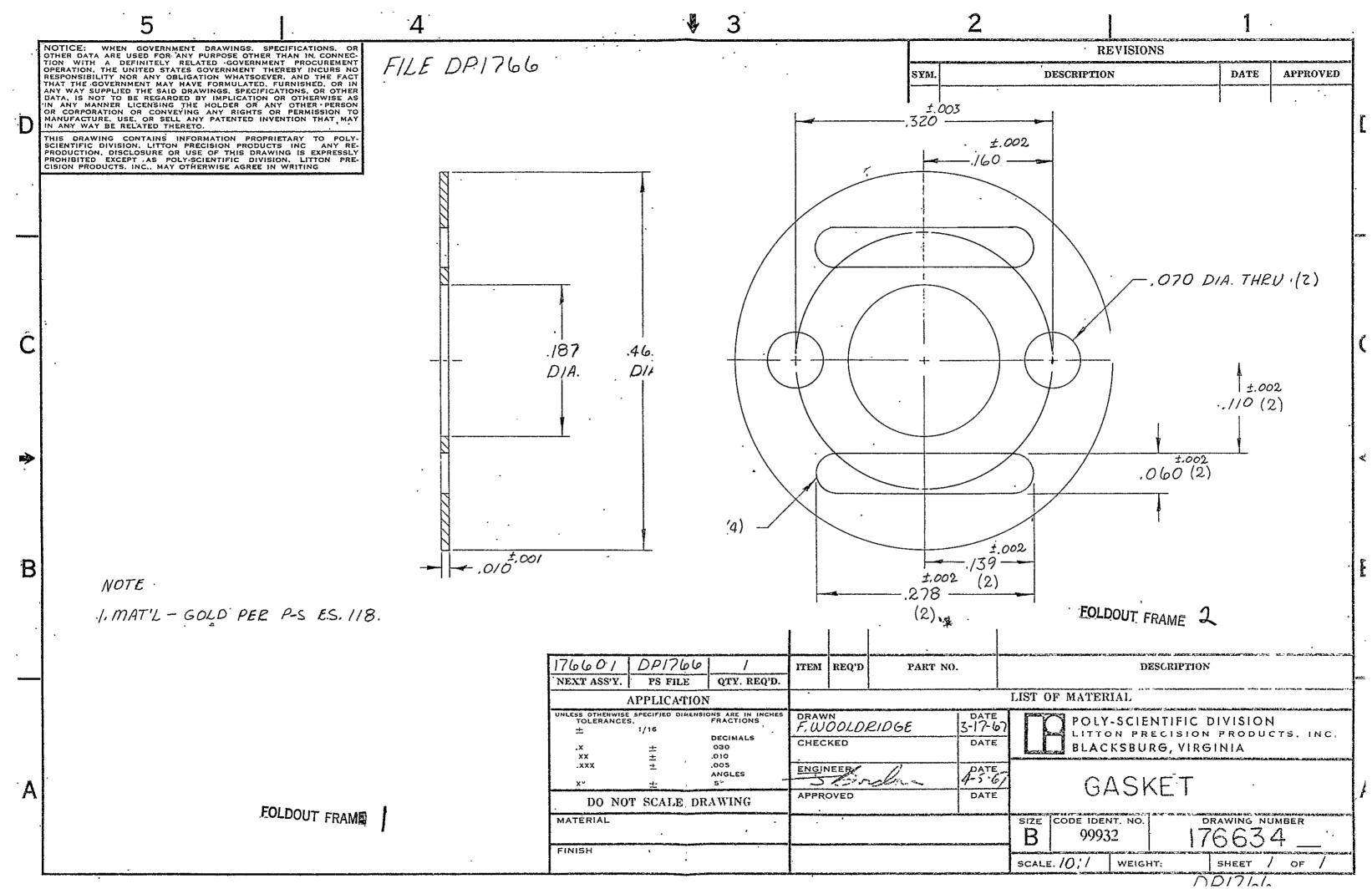


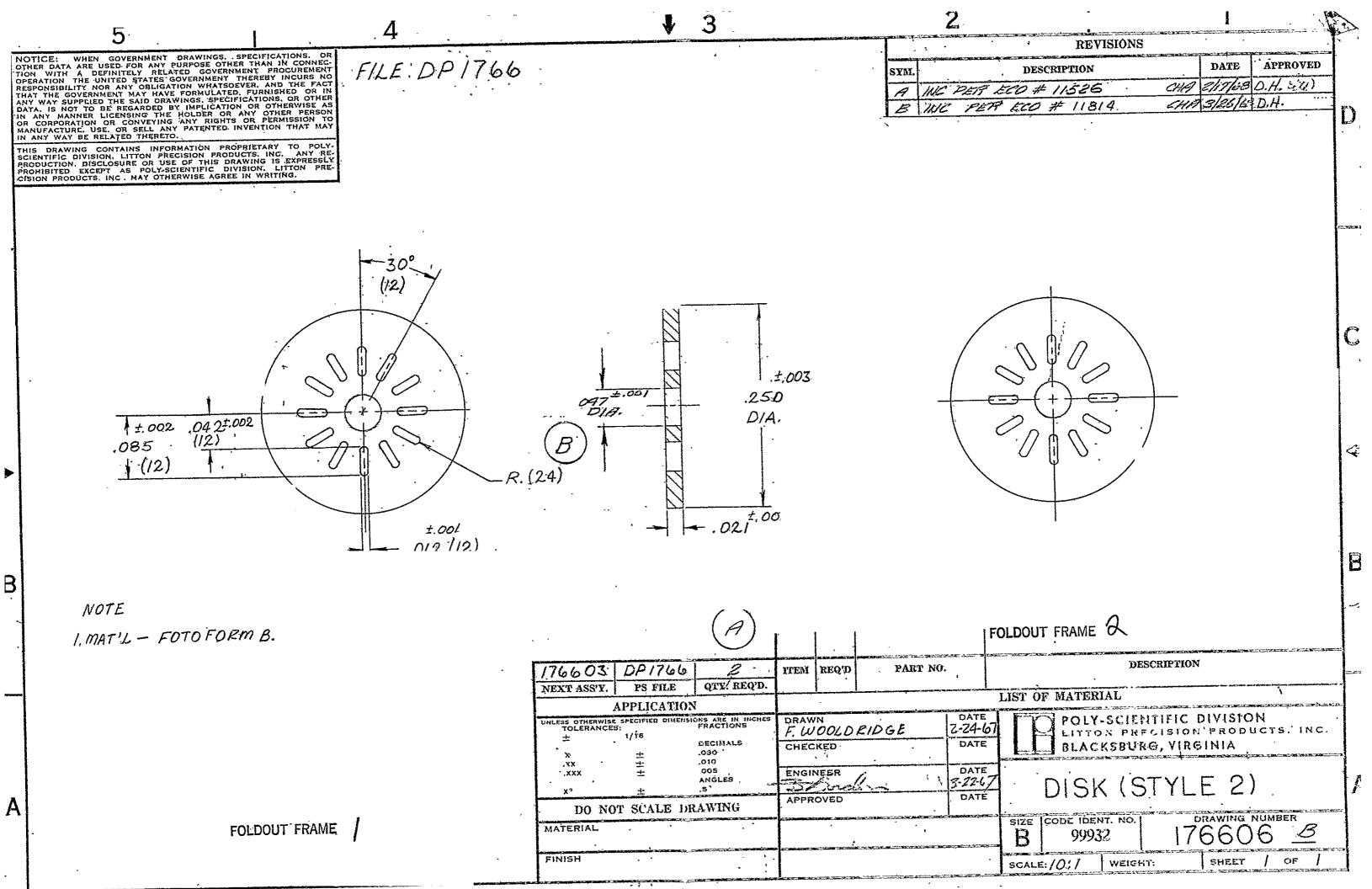


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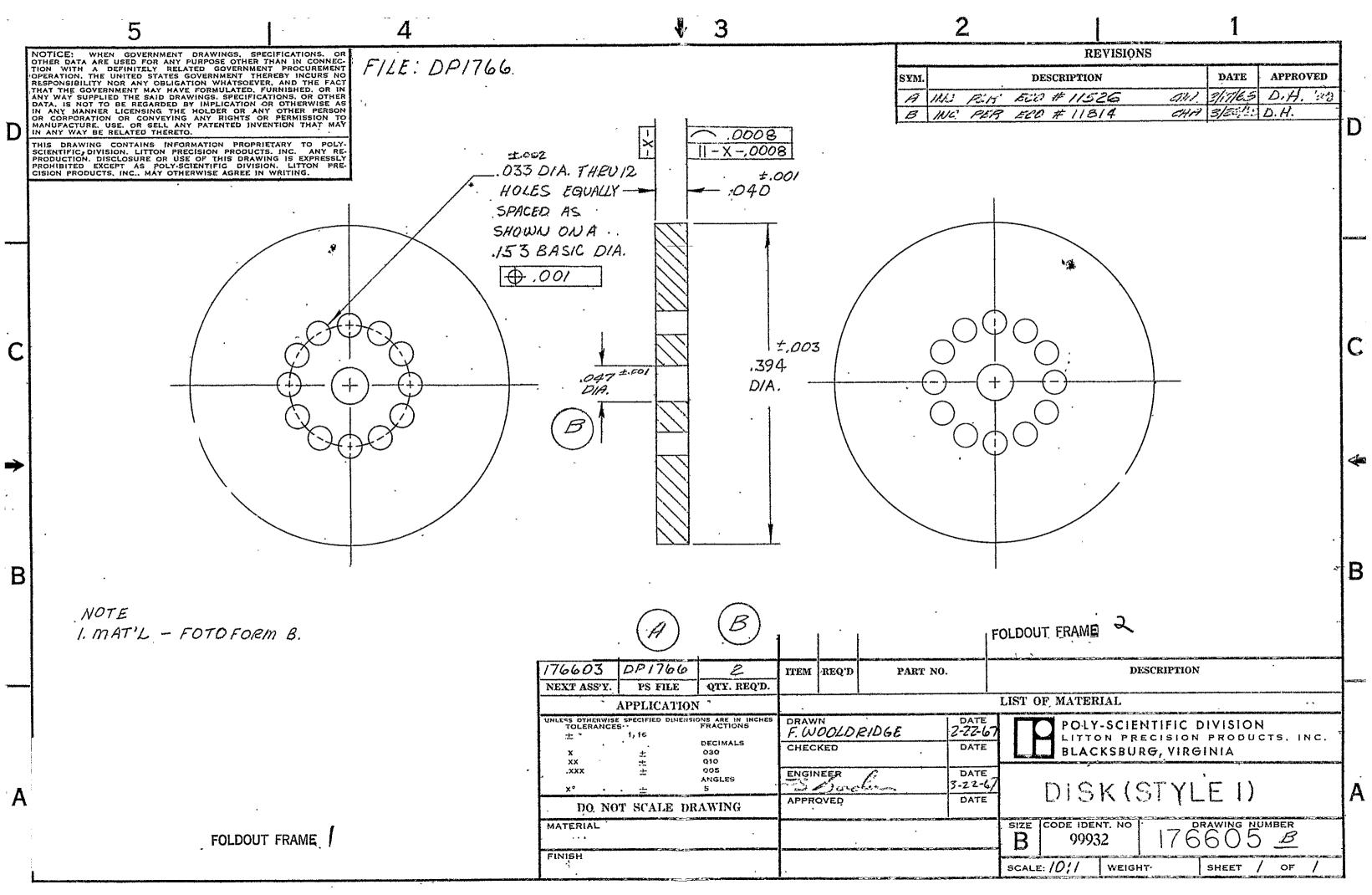
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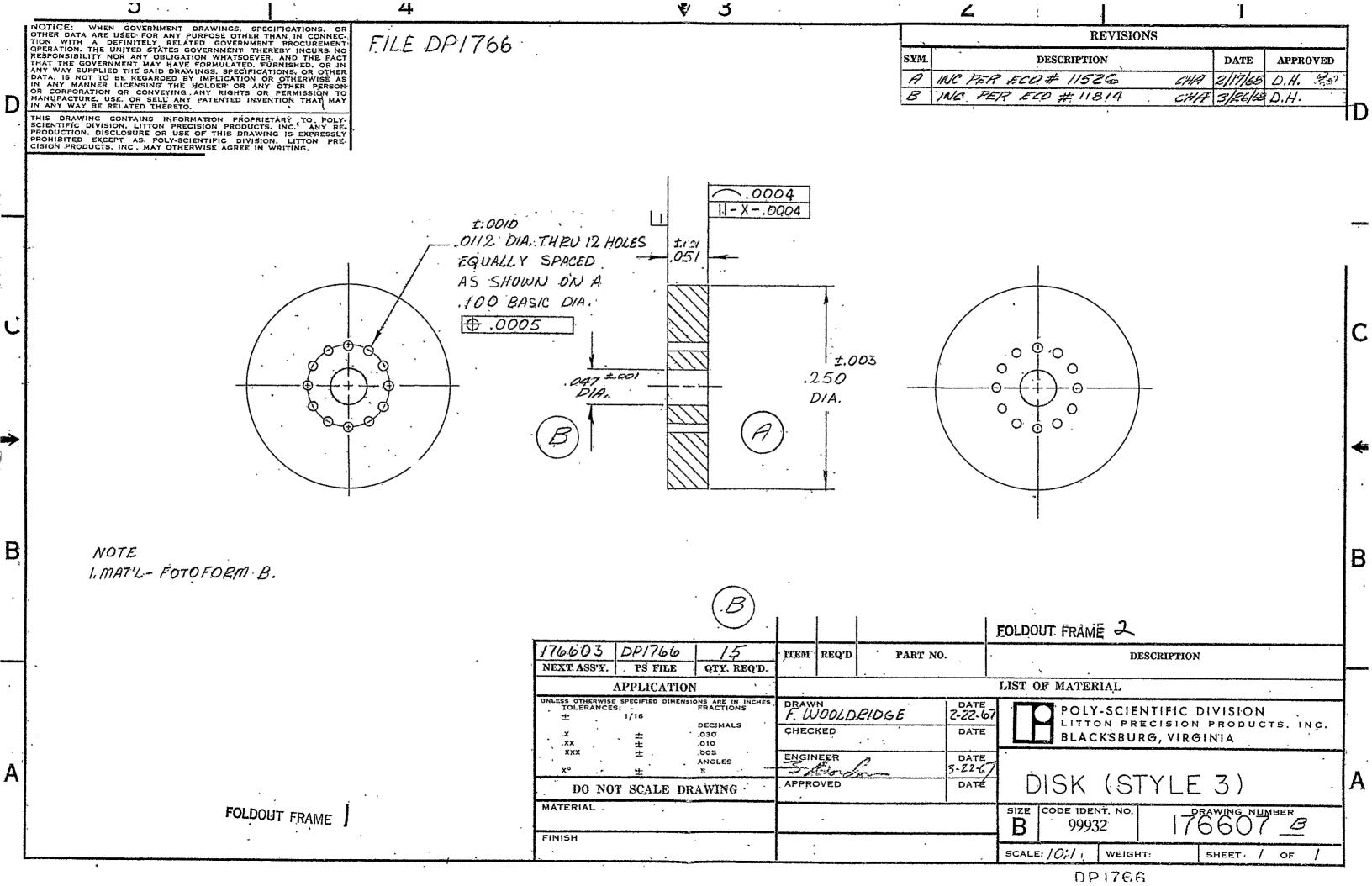






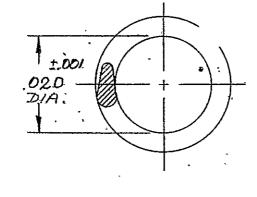
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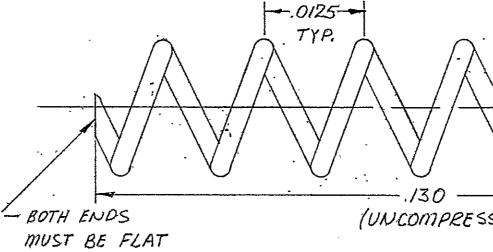




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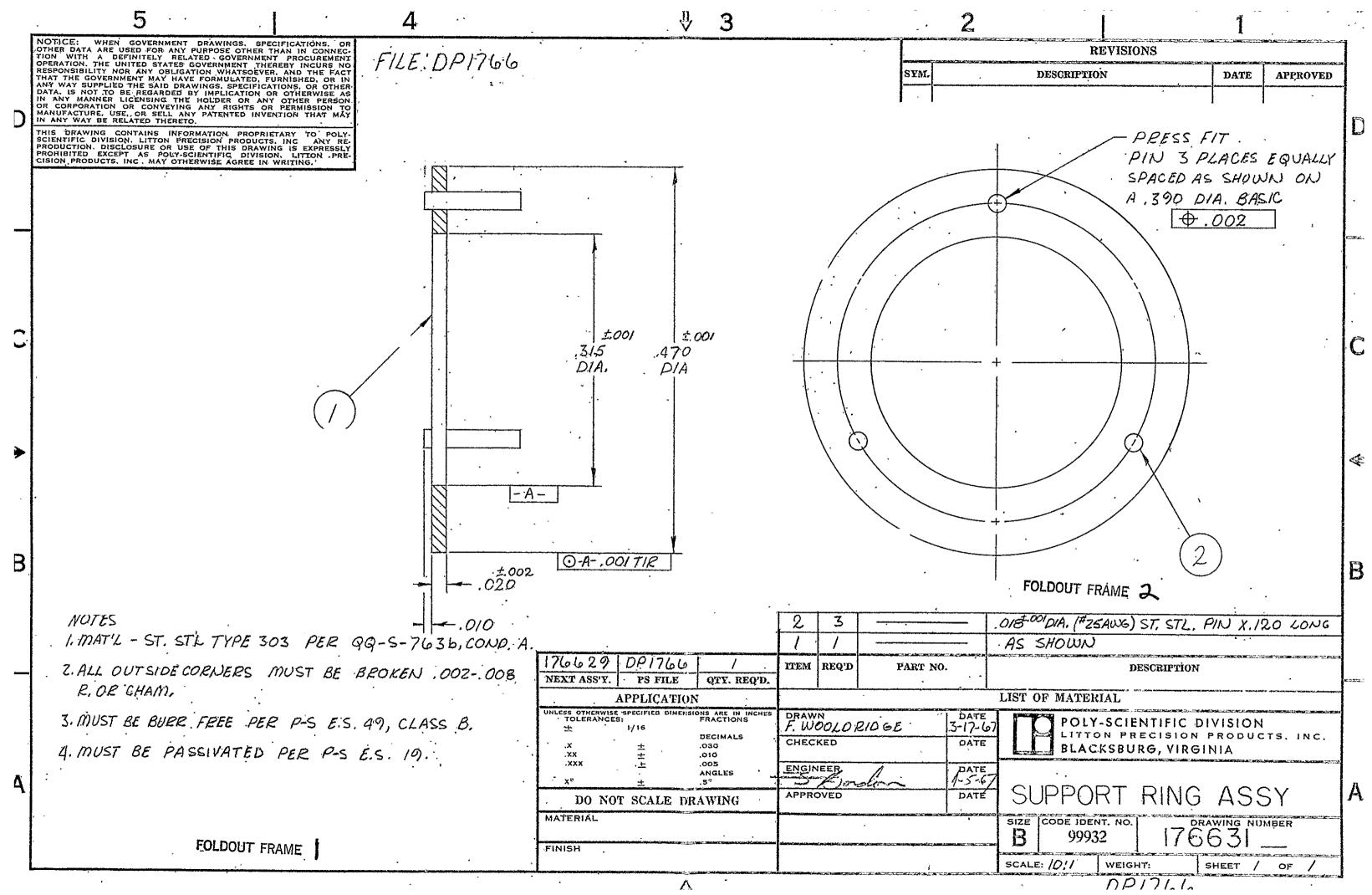
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