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STRESS WAVES IN SANDWICH PLATES

bу

R. Kinslow, Tennessee Technological University



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# EXPERIMENTAL STRESS ANALYSIS

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#### SESA PAPER NO. 1653

#### STRESS WAVES IN SANDWICH PLATES\*

bу

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COOKEVILLE, TENNESSEE

OCTOBER, 1970

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#### ABSTRACT

A mathematical stress wave model is formulated for use in predicting the effects of various material combinations and geometry in the design of sandwich plates that may be subjected to high velocity impact. In the experimental investigations the bounding layers were of a birefringent material and stresses were determined by means of a dynamic polariscope utilizing a high-speed framing camera. A comparison is made of the theoretical and experimental results.

# CONTENTS

	Page						
	ABSTRACT ii						
	NOMENCLATURE						
I.	INTRODUCTION						
II.	THEORETICAL ANALYSIS						
III.	EXPERIMENTAL INVESTIGATION						
IV.	A QUASI-THEORETICAL SOLUTION						
V.	CONCLUSION						
	REFERENCES						
	ILLUSTRATIONS						
Figure							
1.	Target Dimensions and Coordinates						
2.	Reflected and Transmitted Stress Waves in Laminated Targets						
3.	Stress Amplitude-Impedance Mismatch Relations						
4.	Polariscope, Camera, and Controls						
5.	Fringe Locations at Various Times						
6.	Stress Wave Photographs and Computed Results						
7.	Fringe Number-Distance-Time Relations						
8.	Displacement-Distance-Time Relations						
9.	Strain-Distance-Time Relations						

- 10. Stress-Distance-Time Relations
- 11. Stress Waves Through 1/8-Inch Aluminum Laminate
- 12. Stress Waves Through 1-Inch Aluminum Laminate
- 13. Fringe Order and Computed Results-Aluminum Laminates
- 14. Comparison of Stresses in Homogeneous and Laminated Targets
- 15. Forcing Function to Simulate Experimental Impulse
- 16. Matching Theoretical Stress Wave with Experimental Stress Wave
- 17. Theoretical Stress-Distance-Time Relations
- 18. Stress Wave Attenuation
- 19. Distance-Time Relation of Stress Waves in Laminated Targets
- 20. Superposition of Transmitted Stress Waves in Laminated Targets
- 21. Comparison of Theoretical Stresses in Homogeneous and Laminated Targets
- 22. Comparison of Experimental and Theoretical Results

#### **TABLES**

- I. Material Properties
- II. Impedance Mismatch for Various Combinations of Materials

## NOMENCLATURE

С	wave velocity
E	Young's modulus
f	photoelastic constant
h	model thickness
k	constants
K	impedance mismatch
N	fringe order
0	point of impact
P <sub>0</sub>	pressure at cavity surface
P	pulse amplitude
S	a point
r	radius vector
r <sub>0</sub>	cavity radius
t	time
T	lamination thickness
u	particle displacement
V	particle velocity
У	distance from free surface of target
Y	target thickness
α	decay constant
ε r	radial strain

# NOMENCLATURE, Continued

ε θ	tangential strain
λ,μ	Lame constants
ν	Poisson's ratio
φ	scalar displacement potential
ρ	material density
o r	radial stress
r o 0	tangential stress
т	shear stress

#### SECTION I

#### INTRODUCTION

Meteoroids and other debris in outer space pose potential hazards to astronauts, spacecraft, and missiles. Although the impacted body may have sufficient strength and thickness to resist actual puncture, damage may be caused by strong shock waves resulting from the impact. When such a stress wave encounters a free surface, it is reflected, generally as a tensile wave. If the amplitude of this reflected wave is equal to or greater than the strength of the "target" material, fracture will occur. Such fractures may appear as cracks near the surface, weakening the structure; as rear surface bulges which could jam mechanisms or block flow in pipes; or as a complete detachment of target material, creating a shrapnel effect, endangering equipment or personnel.

It has been demonstrated that damage caused by stress waves produced by hypervelocity impact can, in many cases, be reduced by employing laminated targets (Reference 1). The results of such experiments have served to alert the design engineer to the possibility of reducing the probability of damage or of using a thinner or lighter material as the outer skin or hull of spacecraft. It is perhaps more important to realize that the use of laminates does not necessarily reduce the probability of damage, but may, in some cases, actually result in increased damage to the structure (Reference 2).

This study is an attempt to formulate a mathematical model that can be utilized to predict the action of laminates in affecting the stress waves induced by impact. Such a model should include all parameters that may affect the ability of structures to resist fracture caused by hypervelocity collisions before it can be used with confidence.

This study is limited to an investigation of elastic waves in sandwich plates or targets of only three layers, the two bounding layers being of one material and the center layer, or core, being of a different material. It deals only with stress amplitudes and not with material strengths and fracture criteria.

A brief theoretical analysis of the propagation of spherical stress waves is first made, followed by an experimental investigation of the stresses developed in both homogeneous and laminated targets.

A theoretical model is next formulated that duplicates the experimentally determined stresses in a homogeneous target as closely as possible. This is called a "quasi-theoretical" method (Reference 3). By using this theoretical model, the effects of the core are calculated and compared with those determined experimentally.

#### SECTION II

#### THEORETICAL ANALYSIS

Spherical dilatational wave propagation in homogeneous, isotropic material can be specified by the equation

$$\frac{\partial^2 \phi}{\partial t^2} = c^2 \left( \frac{\partial^2 \phi}{\partial r^2} + \frac{2}{r} \frac{\partial \phi}{\partial r} \right)$$

where  $\phi$  is a scalar displacement potential, c is the wave velocity, and t is time. Particle displacement (u) and velocity (v) are specified by the relations

$$u = \frac{\partial \phi}{\partial r}$$
 and  $v = \frac{\partial u}{\partial t}$ 

where r denotes the radius vector from the point of projectile impact. The radial and tangential stresses are given by the relations

$$\sigma_{r} = (\lambda + 2\mu) \left( \frac{\partial u}{\partial r} \right) + 2\lambda \left( \frac{u}{r} \right)$$

and

$$\sigma_{\theta} = \lambda \left( \frac{\partial u}{\partial r} \right) + 2(\lambda + \mu) \left( \frac{u}{r} \right)$$

where  $\lambda$  and  $\mu$  are the Lame constants and are related to Young's modulus (E)

and Poisson's ratio (v) as follows

$$\lambda = \frac{E}{(1 + v) (1 - 2v)}$$

$$\mu = \frac{E}{2(1 + v)}$$

The mathematical model used in this investigation for generating spherical elastic waves is that described in References 4 and 5. It is assumed that there is a hollow hemispherical cavity in the target with its center at the point of impact and that a time-varying pressure or forcing function is applied to the cavity surface, generating stress waves in the target. The pressure  $(p_0)$  applied to the cavity surface is an impulse that may be described by the relation

$$p_0 = k_1 e^{-\alpha_1 t} + k_2 e^{-\alpha_2 t} + k_3 e^{-\alpha_3 t} + \dots$$

where  $\alpha_1$ ,  $\alpha_2$ , . . . are decay constants, t is elapsed time, and  $k_1$ ,  $k_2$ , . . . are constants. By the proper choice of values of k and  $\alpha$ , various wave forms can be generated.

The solution of the wave equation based upon Blake's work and described in Reference 5 is employed in this study.

The wave velocity is given by the relation

$$c = \left[ \frac{E(1 - v)}{\rho(1 + v) (1 - 2v)} \right]^{1/2}$$

Figure 1 shows the target being considered. Its thickness is denoted by Y, and the distance of a point (S) from the origin (O) is denoted by r. Only stresses developed along the axis passing through O and normal to the target's rear surface have been considered.

## Laminated Targets

An abrupt change in the physical properties of a material will result in the modification of a pressure pulse as it encounters this change. In general, a portion of the pulse will be transmitted, and a portion will be reflected. The relations which describe the modification of a pulse are based upon the boundary conditions of continuity of pressure and continuity of particle velocity across the interface between two materials. These relations depend upon the value of  $\rho c$ , called the "characteristic impedance," of the two materials. If  $\rho_0 c_0$  is for the first, and  $\rho_0 c_0$  is for the second laminate, and  $\rho_0 c_0$  is the pulse amplitude in the first, the amplitude of the transmitted component is

$$P_{t} = \begin{bmatrix} \frac{2\rho c}{t t} \\ \frac{\rho c}{t t} + \rho_{0}c_{0} \end{bmatrix} P_{0}$$

and the reflected component is

$$P_{r} = \begin{bmatrix} \rho_{t}^{c} - \rho_{0}^{c} \\ \frac{\rho_{t}^{c} + \rho_{0}^{c}}{\rho_{t}^{c} + \rho_{0}^{c}} \end{bmatrix} P_{0}$$

These relations are somewhat simplified by letting

$$K = \frac{\int_{\rho_0 c_0}^{\rho_0 c} t t}{\int_{\rho_0 c_0}^{\rho_0 c} t}$$

giving

$$P_{t} = \left[ \frac{2K}{K+1} \right] P_{0}$$

and

$$P_{r} = \left[\frac{K-1}{K+1}\right] P_{0}$$

The sandwich structure under consideration is shown in Figure 2. Its total thickness is Y, the thicknesses of the first and last layers of material are  $T_0$  and  $T_2$ , respectively. The characteristic impedance of

both is  $\rho_0c_0$ . The middle lamination has a thickness of  $T_1$  and a characteristic impedance of  $\rho_1c_1$ . This figure shows the distance-time relation of the wave fronts. Starting at time zero at point  $r_0$ , the wave moves with a velocity of  $c_0$  through the first layer. Upon reaching the first interface, the amplitude of the transmitted component is  $\left[\frac{2K}{K+1}\right]P_0$  which moves through the core at a velocity of  $c_1$ . As this pulse reaches the second interface, a portion will again be transmitted, and a part will be reflected. However, the value of the impedance mismatch at this interface is not K, but has a value of 1/K. The amplitude of the pulse transmitted is, therefore,

$$\left[\frac{2K}{K+1}\right]\left[\frac{2/K}{(1/K)+1}\right]P_0 = \left[\frac{2K}{K+1}\right]\left[\frac{2}{K+1}\right]P_0 = \left[\frac{4K}{(K+1)^2}\right]P_0$$

and is denoted by P . As only the stress developed in the last layer of the target is under consideration, it can be assumed that the target is composed of this material only, and that the initial pulse has an amplitude of  $\left[\frac{4K}{(K+1)^2}\right]$  P<sub>0</sub> instead of P<sub>0</sub>. The time required, however, for this pulse to reach any point is not the same as for a homogeneous target due to the change in velocity through the core. It must be adjusted by the amount

$$t_{1-0-0} = \left[\frac{c_0 - c_1}{c_0 c_1}\right] T_1$$

The component of the pulse reflected from the second interface is  $\left[\frac{K-1}{K+1}\right]P_0$ , which, upon again reaching the first interface, will be reflected with an amplitude of  $\left[\frac{K-1}{K+1}\right]^2P_0$ . A portion will then be transmitted through the second interface, this being

$$P_{2-0-0} = \left[ \frac{K-1}{K+1} \right]^2 \left[ \frac{4K}{(K+1)^2} \right] P_0 = \left[ \frac{4K(1-K)^2}{(1+K)^4} \right] P_0$$

If the transmitted pulse amplitudes in this layer are denoted by  $P_{A-B-C}$ , the other pulses  $P_{A-0-0}$  may be specified as

$$P_{A-0-0} = \frac{\frac{2(A-1)}{4K(1-K)}}{2A}$$
(1 + K)

These pulse amplitudes,  $P_{1-0-0}$ ,  $P_{2-0-0}$ ,  $P_{3-0-0}$  . . . form a rapidly converging series, the sum of which approaches the value of  $P_0$ . This is to be expected, because pulse attenuation and energy losses have been neglected up to this time. The time adjustments for these waves are given by the relation

$$t_{A-0-0} = \frac{(2A - 1)c_0 - c_1}{c_0 c_1} T_1$$

Figure 3 gives the amplitudes of  $P_{A-0-0}$  as functions of the impedance mismatch, K.

Although the distance-time relations of all the wave fronts indicated by  $P_{A-B-C}$  are shown in Figure 2, only the amplitudes of  $P_{A-0-0}$  are considered in this paper as the other waves do not enter into the specific problem being investigated. Derivations of the other wave amplitudes and their contribution to the total stress in other targets are given in Reference 6. An analysis of stress waves in targets consisting of a large number of laminates may be found in Reference 7.

#### SECTION III

#### EXPERIMENTAL INVESTIGATION

In the experimental investigation described in this report, a

Beckman and Whitley Model 201 synchronous framing camera was used to

record the dynamic fringe pattern generated in the model. The camera

is a rotating mirror type, making twelve 0.7 X 0.9-inch photographs on

a 4 X 5-inch film at speeds up to one million frames per second. Exposure

time for each photograph at this speed is approximately 0.6 microsecond.

Figure 4 is a diagram of the camera and related equipment.

The two pulse generators deliver 100 Joules each at 5 KV. One was used to provide energy for the light source. After much experimentation with exploding wires and other devices, it was found that a Buss type AGC-1 safety fuse was an ideal light source. This fuse, when exploded, provides an intense light with a sufficiently long duration for satisfactory exposure of all twelve frames.

The other pulse generator was used as the energy source for generating stress waves in the model as a simulation of hypervelocity impact. After experimenting with many kinds of model materials, PSM-1, a clear polyester sheet manufactured by Photolastic, Inc., was selected as the basic material to be used in this study. Its manufacturer claims that it has the highest photoelastic sensitivity of any model material available and has a wave velocity of about 60,000 inches per second, sufficiently low to be photographed without apparent wave movement during exposure. Another important

factor is that it is practically free of creep and edge effects. This plastic can be easily machined, polished, and cemented to other materials. The most consistent stress waves were generated by exploding a fine wire in contact with one edge of the model. The amplitudes of these waves, however, were not sufficiently great for accurate comparison of waves having only slight differences in amplitude. A stronger shock, giving a greater number of fringes, resulted when a small amount of explosive was added. Urea nitrate was the explosive used in this investigation.

Separation of the stresses is possible without additional experimental data since the waves in this case propagate without rotation.

Stresses are developed both along and perpendicular to the direction of wave propagation. Displacement occurs, however, only in the direction of wave motion. The displacements are specified by:

$$u_r = f(r)$$
 ,  $u_\theta = 0$ 

and the strain-displacement relations by

$$\varepsilon_{r} = \frac{du_{r}}{dr}$$
,  $\varepsilon_{\theta} = \frac{u_{r}}{r}$ 

The stress-strain equations are

$$\sigma_{r} = \frac{E}{1 - v^{2}} \left[ \varepsilon_{r} + v \varepsilon_{\theta} \right] , \quad \sigma_{\theta} = \frac{E}{1 - v^{2}} \left[ \varepsilon_{\theta} + v \varepsilon_{r} \right]$$

and the shear stress has the value

$$\tau = \pm \frac{\sigma_{\theta} - \sigma_{r}}{2}$$

where E is Young's modulus and v is Poisson's ratio.

From these relations

$$2\tau = \sigma_{\theta} - \sigma_{r} = \frac{E}{1 + \nu} \left[ \varepsilon_{\theta} - \varepsilon_{r} \right] = \frac{E}{1 + \nu} \left[ \frac{u_{r}}{r} - \frac{du_{r}}{dr} \right]$$

but

$$\frac{d}{dr}\left(\frac{u_r}{r}\right) = \frac{1}{r}\left[\frac{du_r}{dr} - \frac{u_r}{r}\right]$$

So
$$\sigma_{\theta} - \sigma_{r} = -\frac{E}{(1+\nu)} \left[ r \frac{d}{dr} \left( \frac{u_{r}}{r} \right) \right]$$

$$\frac{d}{dr} \left( \frac{u_{r}}{r} \right) = -\frac{(1+\nu)}{E} \left( \frac{\sigma_{\theta} - \sigma_{r}}{r} \right)$$

$$\frac{u_{r}}{r} = -\frac{(1+\nu)}{E} \int \frac{\sigma_{\theta} - \sigma_{r}}{r} dr$$

$$\varepsilon_{\theta} = \frac{u_{r}}{r} = -\frac{2(1+\nu)}{E} \int \frac{\tau}{r} dr$$

$$\varepsilon_{\theta} = \varepsilon_{\theta} - \frac{2(1+\nu)}{E} \tau = -\frac{2(1+\nu)}{E} \int \tau + \int \frac{\tau}{r} dr$$

The radial and tangential stresses are, therefore,

$$\sigma_{\mathbf{r}} = -\left(\frac{2}{1-\nu}\right) \left[\tau + (1+\nu)\int_{\mathbf{r}}^{\tau} d\mathbf{r}\right]$$

$$\sigma_{\theta} = -\left(\frac{2}{1-\nu}\right) \left[\nu\tau + (1+\nu)\int_{\mathbf{r}}^{\tau} d\mathbf{r}\right]$$

This derivation is essentially the same as that described in Reference 8. The stress-optic relation is

$$\tau = \frac{Nf}{2h}$$

where N is the fringe order, f is the photoelastic constant of the material, and h is the model thickness.

These relations may be stated in terms of the model material properties and the fringe order

$$u_{r} = -\frac{(1+v)f}{Eh} \left[ r \int_{r}^{N} dr \right] = r \epsilon_{\theta}$$

$$\epsilon_{r} = -\frac{(1+v)f}{Eh} \left[ N + \int_{r}^{N} dr \right] = \frac{du_{r}}{dr}$$

$$\epsilon_{\theta} = -\frac{(1+v)f}{Eh} \left[ \int_{r}^{N} dr \right]$$

$$\sigma_{r} = -\frac{f}{h(1-v)} \left[ N + (1+v) \int_{r}^{N} dr \right]$$

$$\sigma_{\theta} = -\frac{f}{h(1-v)} \left[ vN + (1+v) \int_{r}^{N} dr \right]$$

Values of displacement, strain, and stress may now be determined by numerical integration.

As the objective of the present research is to compare the stresses developed in a laminated target with those produced in a homogeneous target under the same dynamic impulse, the properties of the material, such as the dynamic modulus of elasticity and photoelastic constant, have not been determined. Resulting strains, displacements, and stresses are, therefore, relative values only and are designated by  $k_1 \varepsilon$ ,  $k_1 u$ , and  $k_2 \sigma$  where  $k_1 = E/f$  and  $k_2 = 1/f$ . Values of other properties for the target material, PSM-1, are: Poisson's ratio (v) = 0.38, density  $(\rho) = 20$  grams per cubic inch, thickness (h) = 0.25 inch, and wave velocity (c) = 60,500 inches per second. The characteristic impedance values of this and some other materials are given in Table I.

It was found that a light field polariscope utilizing circular polaroids, and a dark red filter gave the most satisfactory photographs

of the stress pattern. Figure 5 was prepared from three sets of photographs, shots 175, 176, and 177, and show fringe locations for each frame. Frame 12 of shot 175 was identical with frame 1 of shot 176, but there was a slight gap between the last frame of shot 176 and the first frame of shot 177. In the last frame of 176 the wave front is approaching the rear edge of the model and in 177 the wave is being reflected. The zero fringe (wave front) cannot be seen in these photographs because of the light field being used, so this fringe was determined by extrapolation from the other fringes. The broken line shows the approximate location of the reflected wave front.

Displacements, strains, and stresses were computed from values of r and N read from this figure. Figure 6 shows the photographs and computed results. Shots 175 and 176 were considered continuous with the frame numbers indicated as being from 1 to 23. Shot 177 was not included in the computations as this report does not deal with the waves reflected from a free surface.

A plot of fringe order versus distance for various times is shown in Figure 7. Computed displacements are shown in Figure 8; strains in Figure 9; and stresses in Figure 10. The different scales for the radial and tangential strain and stress should be noted.

Two targets were next prepared having cores of aluminum cemented to the PSM-1 with Eastman 910 epoxy. Referring to Table II, which gives impedance mismatch values for various combinations of materials, it is seen that the impedance mismatch between PSM-1 and aluminum is about nine.

In the first target, the core thickness was only 1/8 inch. Figure 11 shows ten frames of this shot (No. 240). The second target had a core

thickness of 1.0 inch. Figure 12 shows photographs of this shot (No. 226). Plots of the fringe order at a time of 68 microseconds and the computed stresses are shown in Figure 13. Only fringes 0.5 and 1.5 were developed in the latter, and as fringe number 1.5 was barely distinguishable, it was the maximum point on this curve.

The time of 68 microseconds corresponded to Frame 14 of the homogeneous geneous target. A comparison of the stress waves in the homogeneous target and the two sandwich plates is made in Figure 14. The distances traveled are, of course, not the same, as the wave velocity in the aluminum was about four times as great as in the plastic.

#### SECTION IV

### A QUASI-THEORETICAL SOLUTION

It was shown in Section II of this report that forcing functions can be selected that will closely simulate explosive impulses or hypervelocity impact. Therefore, it was desired to formulate a function that would approximately duplicate the experimentally determined pressure waves. Without going into the details of the procedure, it was found that the function

shown in Figure 15 will, when multiplied by the proper constant and applied to a 2-inch spherical cavity, create a wave at a time of 68 microseconds that approximates the experimental wave as shown in Figure 16. The time of the theoretical wave has been adjusted by 32.6 microseconds, the time required for the wave to travel two inches, the assumed cavity radius. By employing a greater number of terms in the equation representing the forcing function, the theoretical wave could have been made to coincide with the experimental wave as closely as desired. Values of radial and tangential stresses at other times were computed and are shown in Figure 17. By comparing Figures 10 and 17 it is seen that the waves have the same amplitudes at a time of 68 microseconds but that the stress amplitudes do not attenuate at the

same rate. This is to be expected. The theoretical solution is for spherical waves which decay at a rate proportional to  $r^{-1}$ , but the experimental ones would be expected to be cylindrical waves in a thin plate. Theoretically, cylindrical waves attenuate at a rate proportional to  $r^{-0.5}$ . The expected attenuation of both spherical and cylindrical waves are compared with the experimental results in Figure 18. This shows that in reality, the experimental results are in closer agreement with the spherical than with the cylindrical wave attenuation.

Distance-time plots of the waves in the targets having 1/8- and 1.0- inch aluminum cores are given in Figure 19. It is seen that because of the geometry of the targets, only the waves  $P_{A-0-0}$  contribute to the stress in the third layer at the time under consideration.

The same forcing function applied to the homogeneous target was also applied to the sandwich plates. The radial stress-distance relations at the time of 68 microseconds were computed. The results are shown in Figure 20. This figure also shows each of the transmitted components,  $P_{A-0-0}$ , as well as their resultants. A comparison of these theoretical stresses in homogeneous and laminated targets is given in Figure 21.

#### SECTION V

#### CONCLUSION

The experimental and theoretical results given in Figures 14 and 21 are shown in Figure 22 with values normalized for comparison of maximum stresses. These may be summarized as follows:

	Maximum Stress Compared With Homogeneous Target				
Table to the state of the state	1/8" Core	1.0" Core			
Experimental	0.72	0.41			
Theoretical	0.86	0.42			

There is practically no difference between the experimental and theoretical results in the case of the target with the one-inch core. In fact, one would expect the experimental error to be greater than the small difference that can be detected.

In the case of the 1/8-inch core, however, the agreement between theory and experiment is not as good. The experimental study indicated that the amplitude of the stress wave after passing through the core would be 72 percent of its amplitude in a homogeneous material. The theoretical analysis gives an amplitude of 86 percent.

There are several possible explanations of discrepancies between theoretical and experimental values. Some of these will be discussed briefly

so that they may be taken into consideration in future studies and may lead to more accurate and dependable results.

- The experimental waves were generated and analyzed in 0.25-inch sheets, but the theoretical results were computed for spherical waves in semi-infinite targets.
   Close agreement would not be expected. Three-dimensional experiments employing an imbedded polariscope are being planned.
- 2. Explosives that generated the stress waves probably varied somewhat from shot to shot. More consistent results were obtained when wires were exploded without the use of chemical explosives. A more powerful energy source is needed so that a wire alone can be used and a greater number of fringes will be generated. Reference to Figure 13 will show that more fringes are needed to accurately define the amplitude of the stress wave that had passed through the 1/8-inch core. Although only the 0.5 and 1.5 fringes were created in the target having the 1.0-inch core, the peak of the wave was more accurately determined because the 1.5 fringe was barely visible in that frame.
- 3. It has been assumed that the cemented joints have no effect upon the transmitted and reflected waves. Two sheets of PSM-1 were cemented together and a stress wave photographed as it passed through the joint. No attenuation of the wave could be detected. As long as the effect

of the joint is small it will not materially affect the results in the case of a relatively thick core. With a one-inch laminate only two transmitted waves contributed to the maximum stress (Figure 20). The situation is much different when the core is thin. In the instance of the 1/8-inch core the resultant stress was dependent upon at least nine transmitted components. In this case there were ten waves transmitted through and sixteen reflections from the cemented joints. It is apparent that although an attenuation of stress may not be detected at a single joint it can be quite significant when there is a large number of reflections and transmissions. As previously stated, Eastman 910 cement was used in the construction of the models used in this study. More attention should probably be given to selecting a cement having a characteristic impedance equal to that of the model material. Any voids in the cemented joint will, of course, have a large effect on the experimental results.

4. It has been assumed that the wave velocity remains constant in any given material. Only the first component  $(P_{1-0-0})$  passes through undisturbed material. The reflected waves may traverse the core material many times. The material density and elastic constants will probably be changed slightly, perhaps due

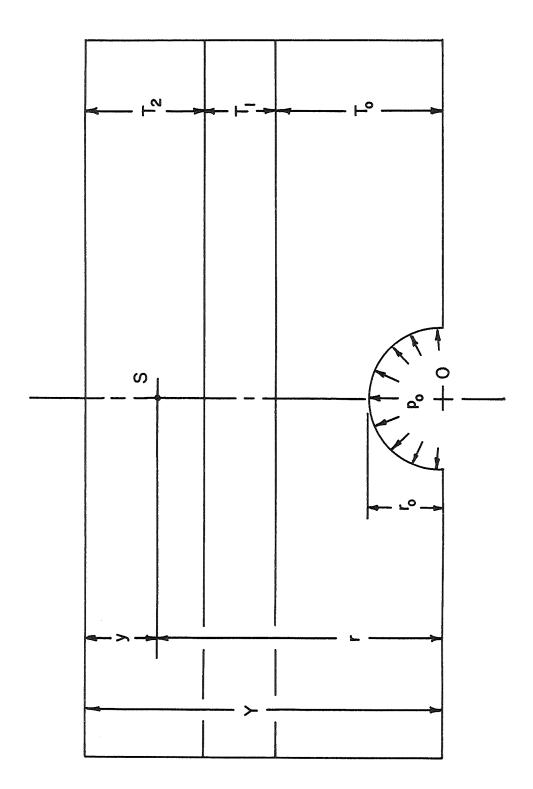
to heating of the material. This will cause some change in the wave velocity and in the characteristic impedance ( $\rho c$ ) of the material. (It has been shown that the velocity of a reflected wave in Lucite is about 80 percent of that of the incident wave [Reference 2]).

5. Energy losses have been neglected. This is obviously not a valid assumption although these losses may be small.

As it is impossible to experimentally test even a small percentage of all possible material combinations of which sandwich plates may be constructed, a dependable theoretical method of analysis is needed. It is believed that the semi-empirical method developed in this study may be used to predict the effects of various material combinations and be of value in the design of sandwich plates that may be subjected to high velocity impact. It is shown that the multiple reflections within the structure must be taken into consideration.

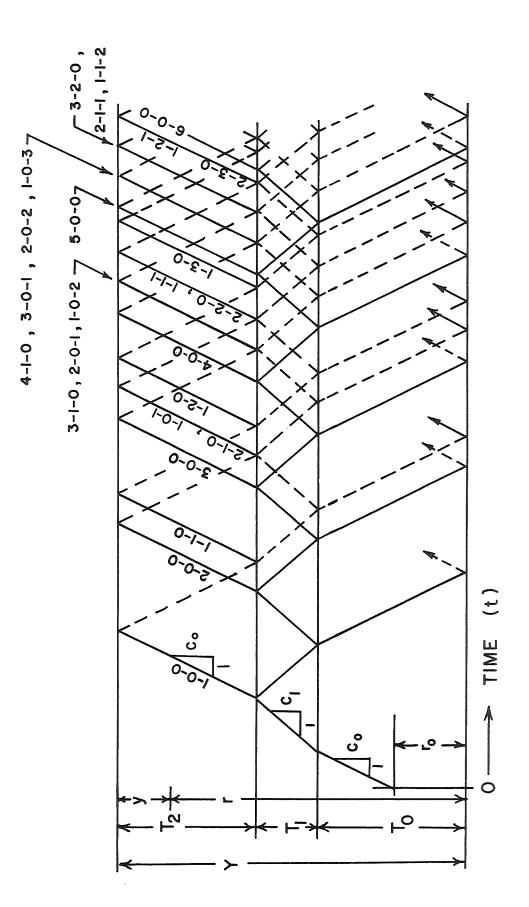
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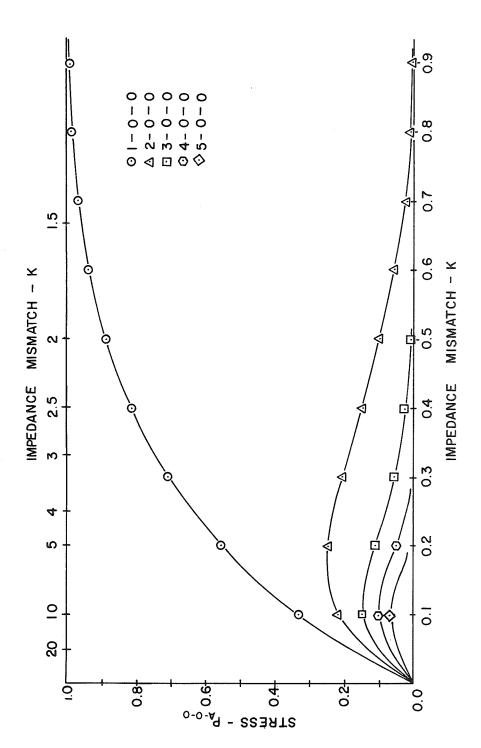


TARGET DIMENSIONS AND COORDINATES

FIGURE



REFLECTED AND TRANSMITTED STRESS WAVES IN LAMINATED TARGETS



STRESS AMPLITUDE - IMPEDANCE MISMATCH RELATIONS

FIGURE 3

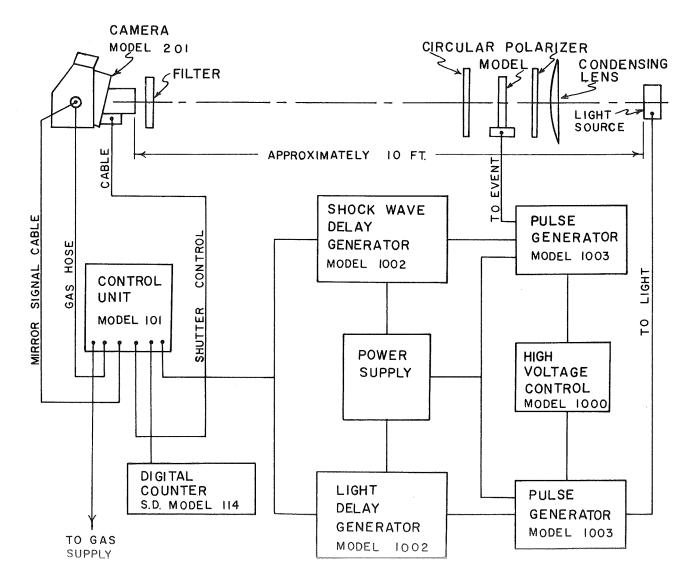
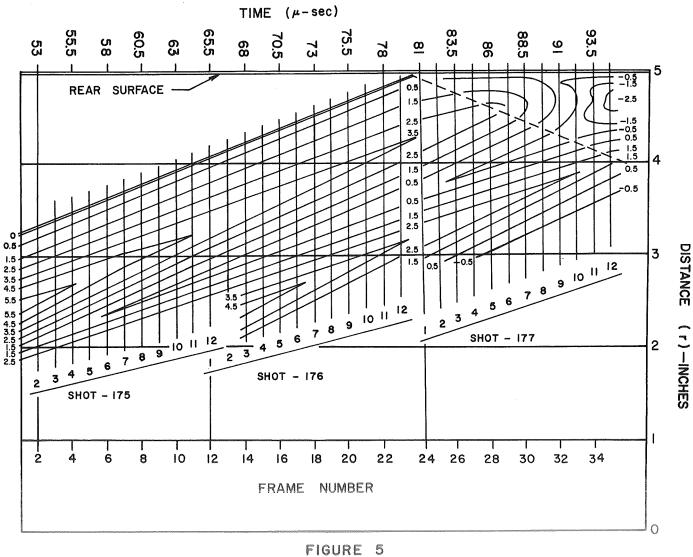
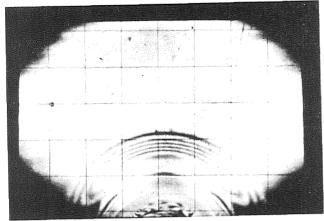


FIGURE 4
POLARISCOPE, CAMERA, AND CONTROLS



FRINGE LOCATIONS AT VARIOUS TIMES

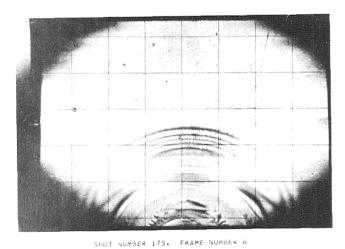


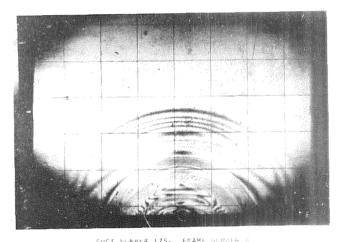
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	SHUE NUMBE	ER 175. FKAMF	SERVING 6	

		SHU1	NUMBER 175	. PHAME	NUMBER 2		
	14	К	UK	t: I	FK	SIGNA K	SIGHA THETA
1234507870	0.0 0.000 2.000 3.000 3.000 4.000 5.000 4.000	3.293 5.203 3.050 2.960 2.850 2.760 2.480 2.380 2.380	0.0 0.124 0.717 2.191 3.814 6.092 3.324 14.626 15.979	0.0 0.039 0.767 0.715 1.398 2.226 3.589 4.727 0.001 7.007	0.0 -7.121 -1.113 -13.045 -11.372 -22.614 -20.671 -23.433 -10.179 -12.313 -6.201	0.0 -3.163 -9.182 *14.976 -20.406 -25.442 -27.534 -17.256 -11.280 -3.677	U.0 -1.103 -3.142 -4.976 -5.406 -7.442 -7.534 -5.537 -1.236 2.720 5.123
11 12 13 14	2.990 1.990 1.290 1.900	2.20b 2.113 2.173 2.073	10.716 10.930 10.931 10.851	7.,777 7.792 H.199 B.347	-0.128 -0.128 1.941 0.067	3.149 5.427 5.750	4.149 10.227 4.736

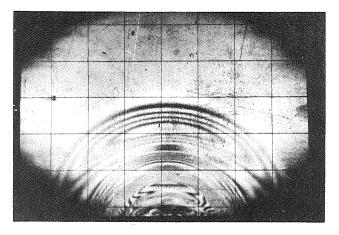
			101 011 111				
	r <sub>k</sub>	ν,	und.		5.5	31 MY -	-11934
i	0.6	1.950	J.C	0.0	0.43		+ + W
k Z	3.500	3.300	0.124	3.03/	- 1 . l. t	- 1.15	
3	1.500	3.610	0.357	3.25	-3,000	9.747.39	5.522.5
	2-960	1.080	2.713	v + 6 / 1	-15,000	-   4 , 4   1	~~~~119
1	3.900	2.750	4.530	1.408	×17.957	474 a 24 A	4 4 4
>		2 = 090	6.570	2.3.1	224 - 34	- 150 (45)	
	4.500		10.010	3.700	1200158	4 1 G 5 J.	
7	9.900	2.700	10.477	3.001	H21 V 134	-17-5-1	
*	5.500	2.040		4.171	14 8 8 8 1 B	- 12219	- 5 4 - 3 6
4	4.000	2.000	17.470		1111111	11. 11	
J	J.500	2.410	10.000	7. 151	~ / . s, >		
ì	Z.360	2.395	17.47:	0.10			Law.
ć.	1.000	7.300	15,500	11. 547	-1-1-6		24554
3	0.800	2.210	10,741	7.147	2 - 1 / 3	1 - 21 -	
4	1.300	2.150	19.795	1-11	40.20	a - 1	

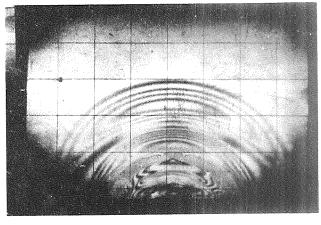




		513G 1 P	DUDEN TO	, ,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,			
	14	К	UR	1.3	ER	SIGMA R	SIGMA THETA
1 2 3 4 5 6 7 8 9 11 12	6.0 0.300 1.300 2.500 4.500 4.500 4.500 2.500 1.500 0.700 1.500	3.599 3.510 3.520 3.220 3.090 2.980 2.790 2.570 2.570 2.470 2.370 2.370	0.0 0.110 0.925 2.408 4.427 6.666 11.143 13.237 14.365 14.842 14.870 14.848	0.0 0.031 0.275 0.748 1.453 2.235 3.990 4.959 5.589 6.029 6.4274 6.484	0.0 -2.729 -8.005 -13.052 -17.887 -22.605 -20.850 -14.361 -5.211 -2.255 2.410 -1.796	0.0 -3.17> -9.233 -14.923 -20.270 -25.427 -22.596 -14.583 -7.11> 0.040 5.603 0.780	0.0 -1.175 -3.233 -4.923 -6.270 -7.427 -4.576 -0.583 2.885 6.040 8.403 6.780

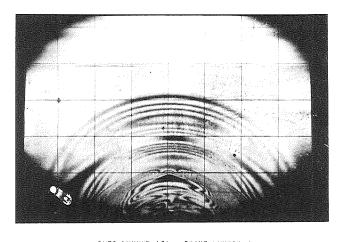
	PHOTE MORBER 1134 ROMAGE MONOGE (C.							
	``	4	UR	٤١	1 %	5 1 15 8 A 1 K	SIGNA INETA	
1	Ç.u	3.750	0.0	U • U	0.5	0.0	0.0	
2	0.500	3.670	0.110	0.030	-2.730	-3-177	-1.177	
4	1.500	3.515	0.979	0.279	-5.001	-3.227	-3.227	
4	2.500	3 - 373	2-463	0.731	-11.009	-14.950	-4,950	
5	3.500	3.239	4.631	1.436	-17.884	-26.264	-0.264	
6	4.500	3.09-3	7.470	2.418	-22.422	-25.131	-7-153	
7	4.500	2.,80	9.996	3.393	-21.487	-23.624	-5.074	
	3.560	2.840	12.536	4.413	-14.907	-15.463	-1.463	
t	2.500	2.750	13.590	4.945	-9.855	-8.154	1.846	
.7		2.640	14.238	5.393	-7.887	-0.979	5.0.1	
10	1.500		14.237	5.033	2.623	5.779	7.179	
1.1	0.500	2.350			2.867	5.849	7.849	
12	0.560	2.510	14.123	5.027	4 * 0 0 *	2 8 0 19 9	1 1 17 1 7	

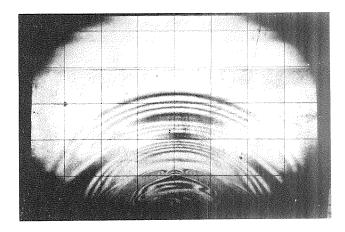




SHUT NUMBER 175, FRAME NUMBER 10							
	A	К	UR	i. I	EŘ	SIGMA R	SIGMA THETA
1	C.U	3.880	0.0	0.0	0.0	0.0	6.0
2	0.500	3.810	0.097	0.025	-2.135	-3.185	-1.135
3	1.500	3.060	0.913	0.249	-8.031	-9.275	-3.275
4	2.500	3.210	2.500	0.714	-13.086	-14.979	-4.778
5	3.500	3.300	4.830	1.440	-17.880	-20.25c	-6.258
6	4.500	3.190	8.254	2.531	-22.243	-24.954	-6.854
7	4.500	3.150	9.164	2.909	-21.731	-24.340	-0.340
8	3.500	3.010	11.771	3.711	-15.409	-16.273	-2.273
y	2.500	2.920	12.883	4.412	-9.388	-9.013	0.987
13	1.500	2.610	13.054	4.334	-3.446	-1.88J	4-120
11	0.560	2.700	13.642	5.052	2.292	4.423	6.923
12	0.350	2.013	13.560	5.079	3-147	5.933	7.333
1.4	0.500	2. 551.	13.539	5136	2.336	4.994	6.914

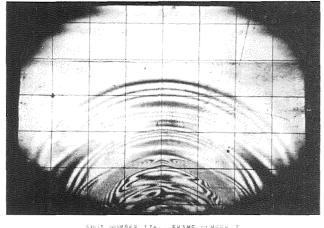
	SHOT NUMBER 175, FRAME NUMBER 12							
	N <sub>e</sub>	к	ુવ	LI	6.4	210ay h	SIGMA	
ı	C.L	4.04.	0.0	0.0	0.0	0.0	Ú = 1)	
2	0.500	3.170	0.037	0.024	= 2 * I 3 (1	-3.187	-1.157	
3	1.500	3.81)	0.957	0.254	-8-026	-9.268	-3.258	
4	2.500	3.060	2.56€	0.730	-11-100	-15.001	-5,001	
5	3.560	3.500	5.050	1.443	-17.877	-20.293	-6.254	
6	3.500	3.200	10.867	3.317	-15.923	-17.102	-1.102	
7	2.500	3.090	12.280	3.)74	-9.626	-9.711	0.281	
8	1.900	2.980	13.030	4.373	-3.767	-2.625	1.375	
g	6.566	2.870	13.140	4.218	1.818	4.157	6.159	
1.6	0.200	2.830	13.035	4.005	3.501	6.137	6.438	
11	0.500	2.780	12.839	4.645	1.880	4.258	0 - 2 - 3	



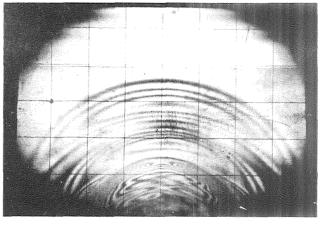


		SHCI	NUMBER	176, FRAME	NUMBER	3	
	N	к	UR	ŧ1	£К	SIGMA R	STGMA THE TA
i	C • U	4.2Cu	0.0	0.0	0.0	0.0	0.0
2	0.000	4.130	0.037	0.023	-2.737	-3.188	-1.188
3	1.500	3.976	0.960	0.244	-8.C36	-9.284	-3.284
4	2.500	3.800	2.77:	0.730	~13.070	-14.952	-4.952
5	3.500	3.640	5.25	1.445	-17.875	-20.250	-6.250
6	3.500	3.390	10.060	2.168	-16.352	-17.794	-3.794
7	2.500	3.280	11.521	3.513	-10.287	-10.464	-0.404
8	1.500	3-140	12.534	3.992	-4.288	-3.23+	2.761
9	0.500	3.020	12.648	4.205	1.445	3.556	5.556
10	0.200	2.970	12.583	4.237	3.133	5.543	6.343
11	0.500	2.920	12.400	4.270	1.510	3.661	5.661

SHOT NUMBER 176, FRAME NUMBER 5								
	N	К	UR	Εſ	ŧΚ	SIGMA R	SIGMA THETA	
1	0.0	4.350	0.0	0.0	0.0	0.0	0.0	
2	0.500	4.280	0.097	0.023	-2.737	-3-189	-1.189	
3	1.500	4.120	0.968	0.235	-6.045	-9.299	-3.248	
4	2.500	3.940	2.880	0.731	-13.069	-14.950	~4.950	
5	3.500	3.770	5.521	1.464	-17.856	-20.219	-6-219	
6	3.500	3.560	9.465	2.659	-16.661	-18.292	-4,272	
7	2.500	3.420	11.350	3.321	-10.479	-10.773	-0.773	
8	1.500	3.300	12.255	3.714	~4.506	-3.688	2-312	
4	0.500	3.170	12.464	3.933	1.173	3.118	5.118	
10	0.160	3.120	12.354	3.960	3.408	5.741	6.141	
11	0.500	3.070	12.23d	3.986	1.226	3.204	5.204	

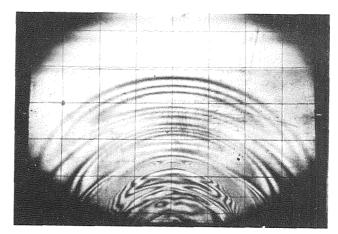






SHUT NUMBER 176. FRAME NUMBER 7									
	ŕγ	К	UR	£t	ЯB	SIGMA R	SIGMA THETA		
1	0.0	4.520	0.0	0.0	0.0	0.0	0.0		
2	0.500	4.440	0.110	0.025	-2.735	-3.185	-1.136		
3	1.500	4.260	1.089	0.256	-8.624	-9.265	-3.205		
4	2.500	4.080	2.994	0.735	-13.005	-14.943	-4.943		
5	3.500	3-910	5.640	1.443	-17.877	-20.254	-6.254		
6	3.500	3.740	8.701	2.350	-16.970	-18.790	-4.790		
7	2.500	3.610	10.594	2. +35	-10.865	-11.396	-1.396		
8	1.500	3.470	11.692	3.304	-4.911	-4.243	1.757		
9	0.500	3.350	11.934	3.002	0.802	2.519	4.519		
10	0.0	3.280	11.77s	3.591	3.591	5.792	5.792		
i i	0.500	3.210	11.623	3.621	0.861	2.614	4.614		

	SHOT NUMBER 176. FRAME NUMBER -								
	fχ	Ιζ	uК	êΓ	4, 4	SIGMA R	SIGMA THETA		
ì	0.0	4.570	0.0	0.0	0.0	0.0	0 = 0		
2	0.500	4.590	0.11.	0.324	-2.738	-1.187	-1.107		
3	1.500	4.420	1.030	0.234	-8.046	-9.291	-3.279		
14	2.560	4.220	3.150	0.749	-13.051	-16.921	-6.921		
5	3-500	4.050	5 <b>.</b> KUU	1.432	-17.088	-20.271	-0.271		
6.	3.500	3.930	7.977	2.230	-17.290	-17.307	-2.3.7		
7	2-540	3.773	10.239	2.716	-11,084	-11.748	-1.74A		
8	1.500	3.620	11.447	3.102	-5.118	-4.577	1.423		
9	0.500	3.520	11.671	3.316	0.556	2.122	4.172		
10	-6.050	3.433	11.491	3.347	3.023	5.72L	5.521		
11	0.500	3.350	11.313	3.177	0.017	2.221	4.281		

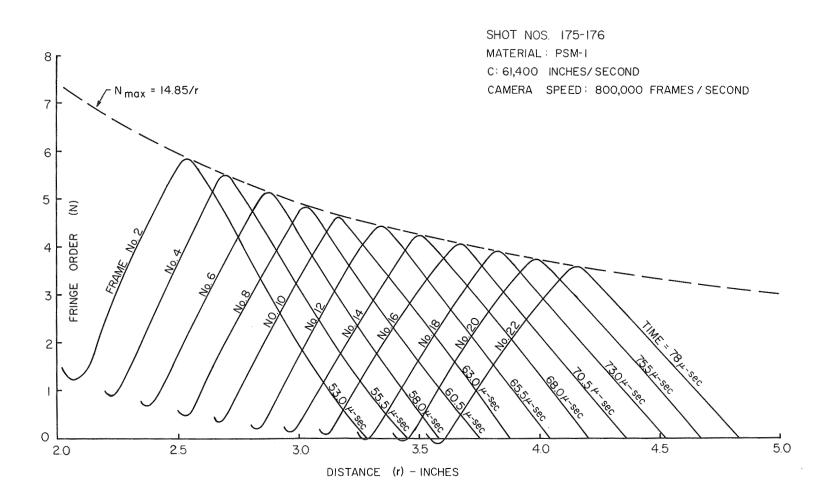


SHOT NUMBER 176, FRAME NUMBER 11

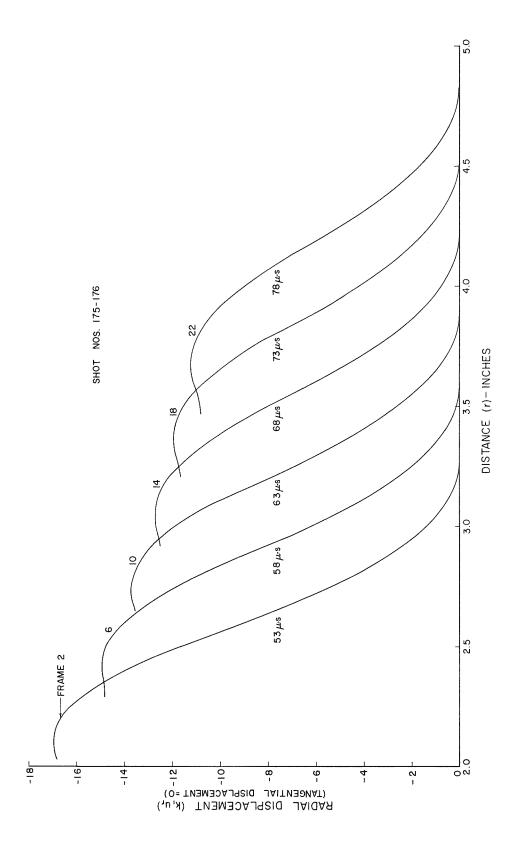
R R LR EI ER SIGMA R THETA

1 C.O 4.830 C.C 0.0 0.0 0.0 0.0
2 C.500 4.740 0.124 0.026 -2.734 -3.184 -1.184
3 1.500 4.560 1.104 0.242 -8.038 -9.287 -3.287
4 2.500 4.370 3.122 0.715 -13.085 -14.977 -4.977
5 3.500 4.190 5.924 1.414 -17.906 -20.300 -6.300
6 3.500 4.120 7.175 1.742 -17.578 -19.772 -5.772
7 2.500 3.950 9.627 2.417 -11.363 -12.198 -2.198
8 1.500 3.800 10.878 2.863 -5.417 -5.060 0.940
9 0.500 3.670 11.205 3.053 0.293 1.698 3.698
10 -0.100 3.570 11.006 3.083 3.635 5.618 5.218
11 0.500 3.470 10.809 3.115 0.355 1.798 3.798

FIGURE 6 CONCLUDED



FRINGE NUMBER - DISTANCE - TIME RELATIONS



DISPLACEMENT - DISTANCE - TIME RELATIONS

FIGURE

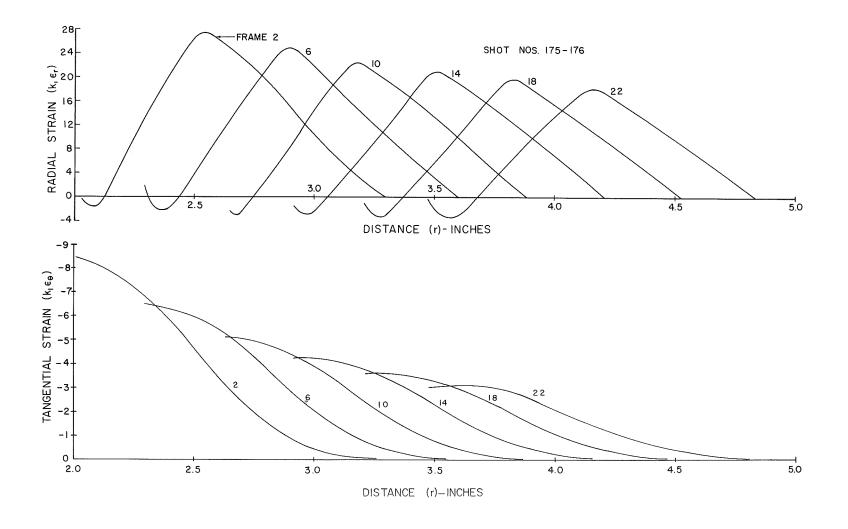
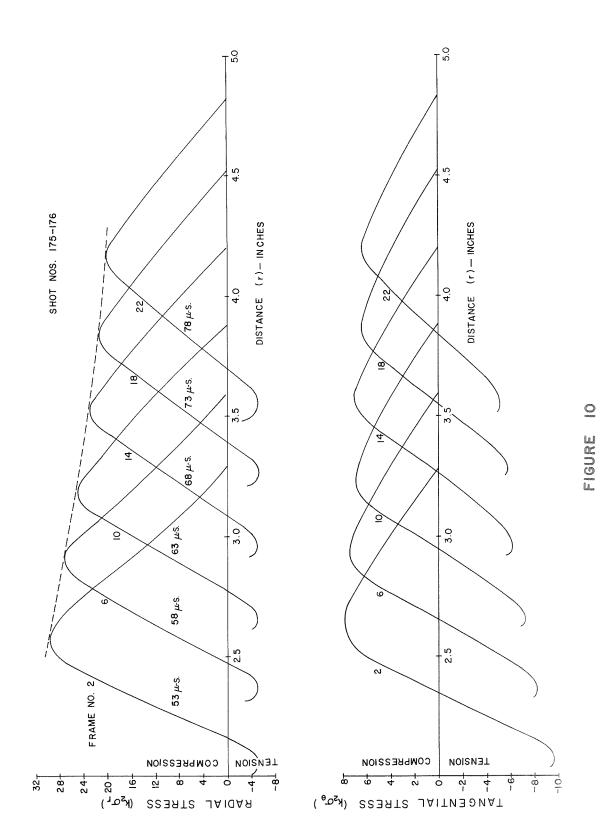
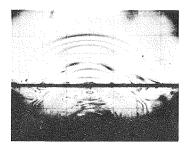


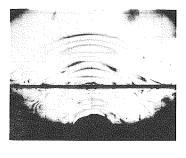
FIGURE 9
STRAIN-DISTANCE-TIME RELATIONS

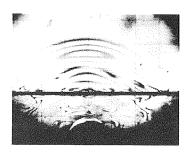


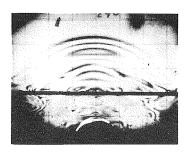
STRESS-DISTANCE-TIME RELATIONS

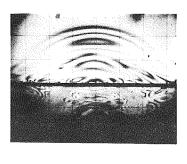
## $\frac{1}{8}$ " ALUMINUM LAMINATE (SHOT 240)











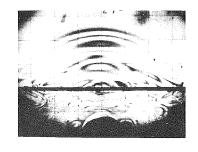
FRAME I

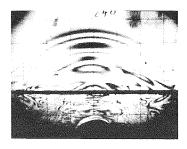
FRAME 2

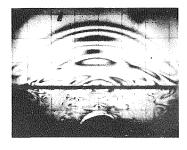
FRAME 3

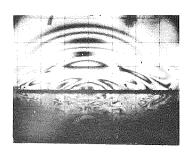
FRAME 4

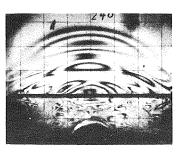
FRAME 5











FRAME 6

FRAME 7

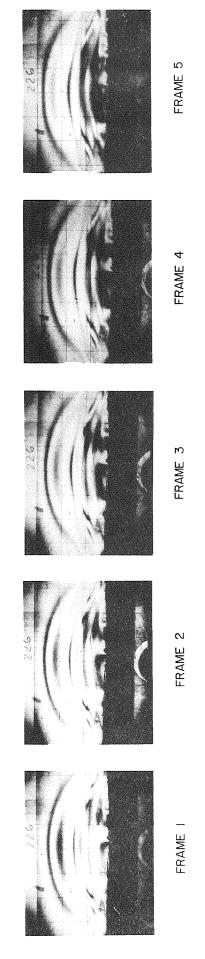
FRAME 8

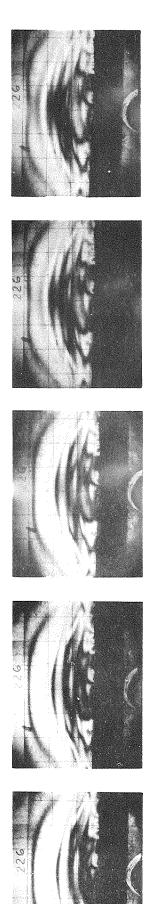
FRAME 9

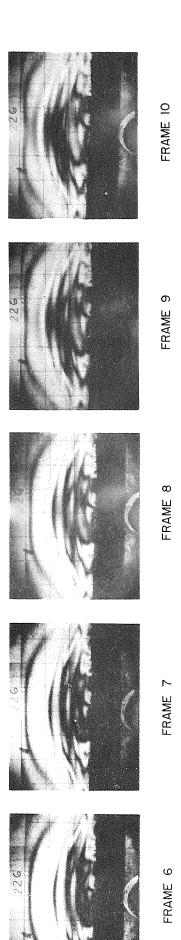
FRAME 10

FIGURE II

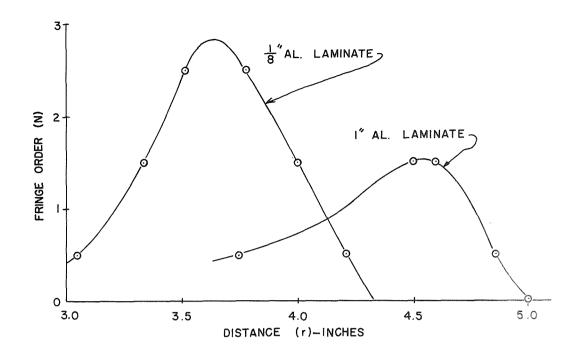
STRESS WAVES THROUGH  $\frac{1}{8}$  INCH ALUMINUM LAMINATE







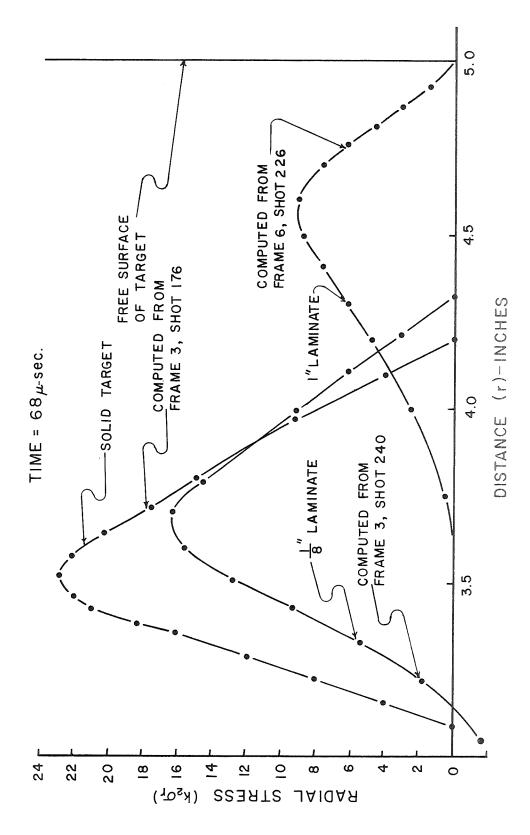
STRESS WAVES THROUGH I INCH ALUMINUM LAMINATE 



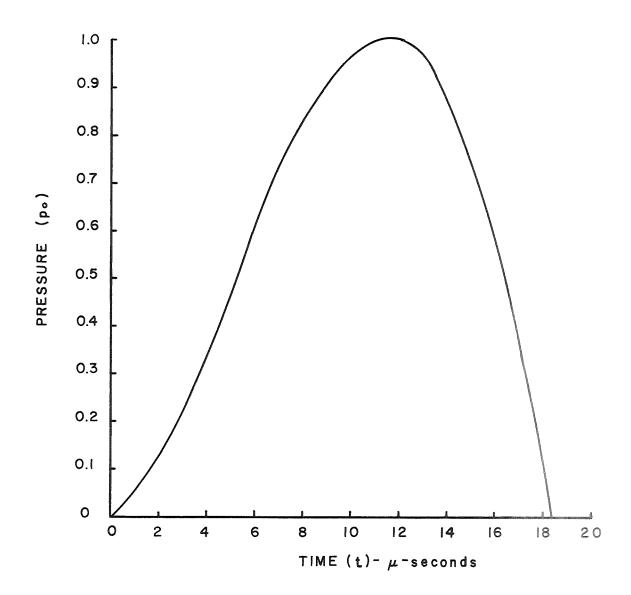
1 INCH LAMINATE											
	N	R	UR	Ł۱	ŁR	SIGMA R	SIGMA THETA				
1	C.O	4.330	0.0	0.0	0.0	C.C	0.0				
2	C.500	4.210	0.160	0.039	-2.721	-3.162	-1.162				
3	1.500	4.CCU	1.30∠	0.326	-7.954	-9.152	-3.152				
4	2.500	3.78U	3.604	0.955	-12.845	-14.589	-4.589				
5	2.85C	3.700	4.702	1.271	-14.461	-16.337	-4.937				
6	2.850	3.600	6.127	1.702	-14.030	-15.642	-4.242				
7	2.500	3.510	7.285	2.076	-11.724	-12.781	-2.701				
8	1.500	3.330	د 8 8 8 8	2.653	-5.627	-5.398	0.602				
9	1.000	3.220	9.287	2.884	-2.636	-1.800	2.200				
10	0.500	3.050	9.470	3.107	0.347	1.785	3.185				

I INCH LAMINATE										
	N	К	UR	ΕT	ĖΡ	SIGMA R	SIGMA	THET/		
1	C.C	5.000	0.0	0.0	0.0	0.0	0.0			
2	C • 500	4.860	0.193	0.040	-2.720	-3.162	-1.162			
3	1.000	4.760	0.600	0.126	-5.394	-6.248	-2.248			
4	1.500	4.600	1.669	0.363	-7.917	-9.092	-3.092			
5	1.500	4.500	2.452	0.545	-7.735	-8.799	-2.799			
6	1.200	4.300	3.797	0.883	-5.741	-6.318	-1.518			
7	1.000	4.200	4.308	1.026	-4.494	-4.797	-0.797			
8	C.700	4.000	5.015	1.254	-2.610	-2.494	0.306			
9	0.500	3.750	5.499	1.466	-1.294	-0.861	1.137			

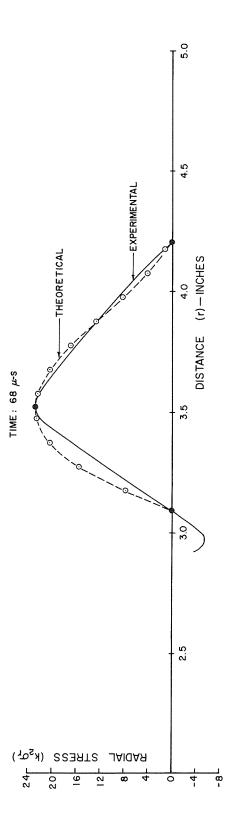
FRINGE ORDER AND COMPUTED RESULTS - ALUMINUM LAMINATES



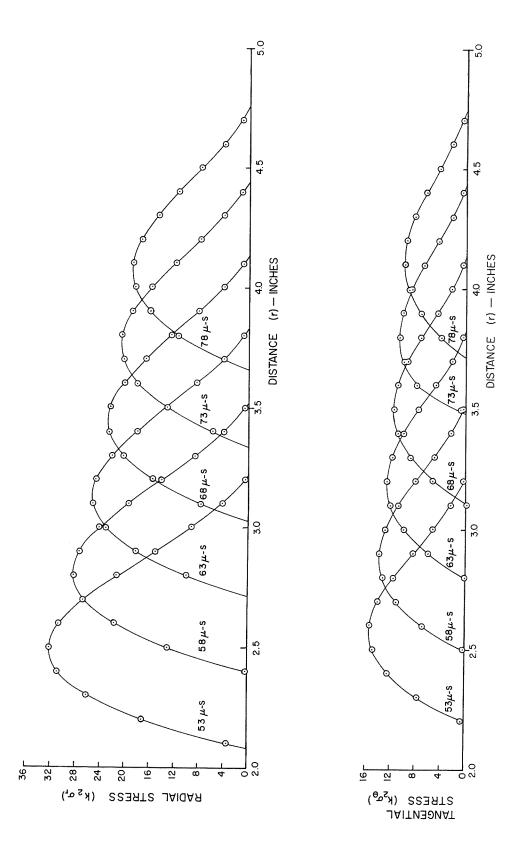
TARGETS AND LAMINATED IN HOMOGENEOUS STRESSES COMPARISON OF



FORCING FUNCTION TO SIMULATE EXPERIMENTAL IMPULSE



EXPERIMENTAL STRESS WAVE MATCHING THEORETICAL STRESS WAVE WITH



THEORETICAL STRESS-DISTANCE-TIME RELATIONS

FIGURE 17

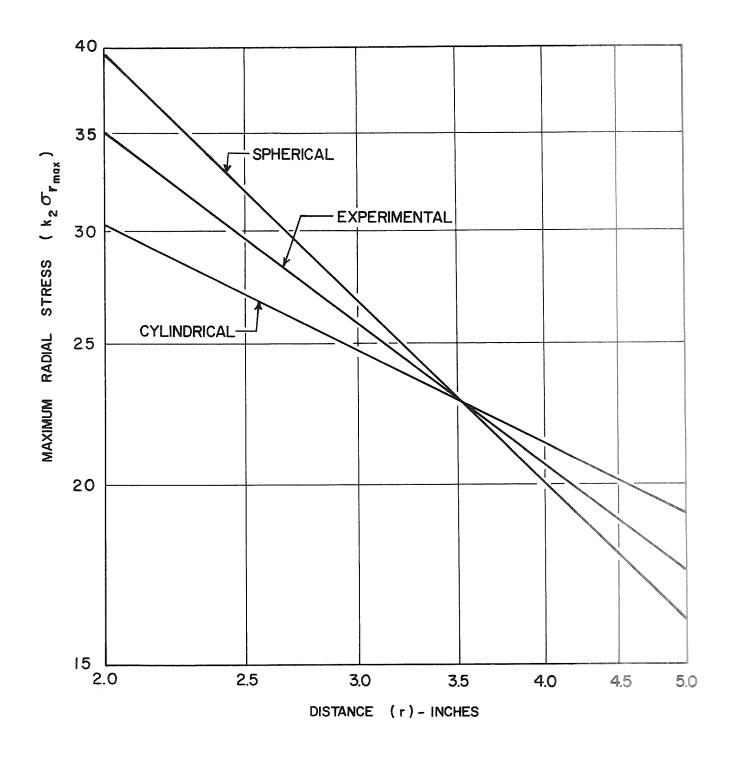
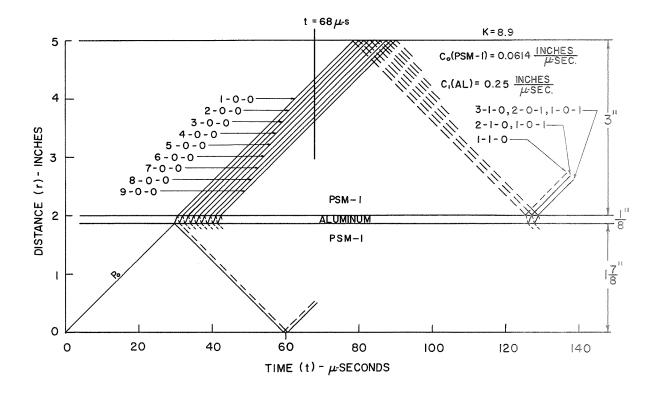


FIGURE 18
STRESS WAVE ATTENUATION



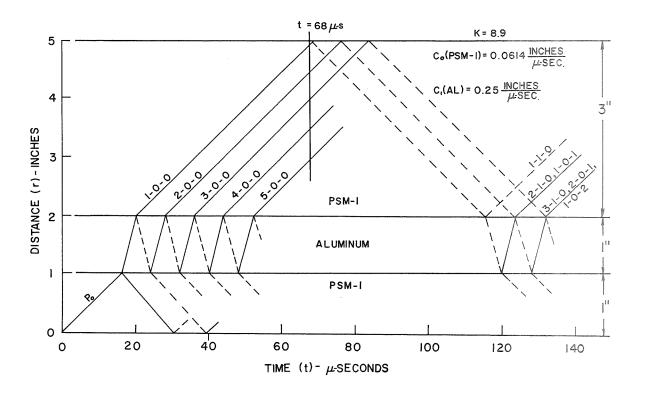
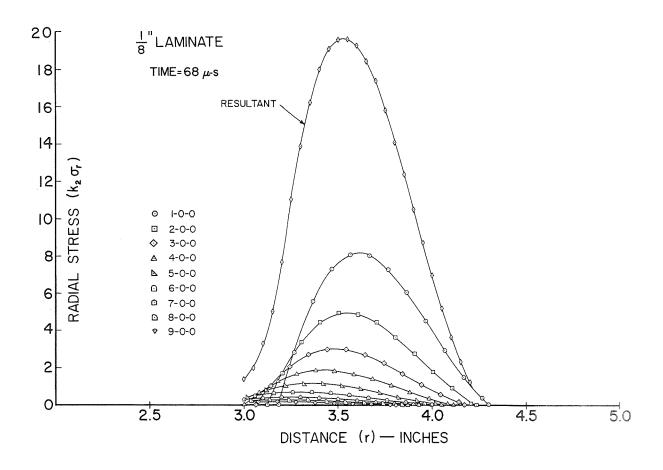


FIGURE 19

DISTANCE-TIME RELATION OF STRESS WAVES IN LAMINATED TARGETS



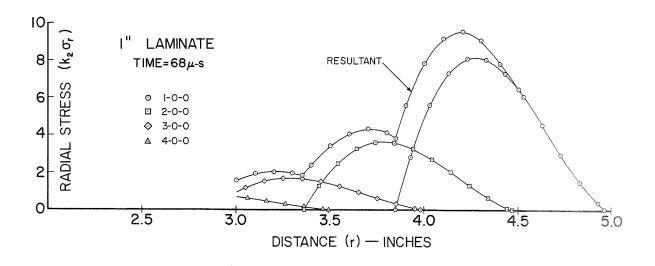
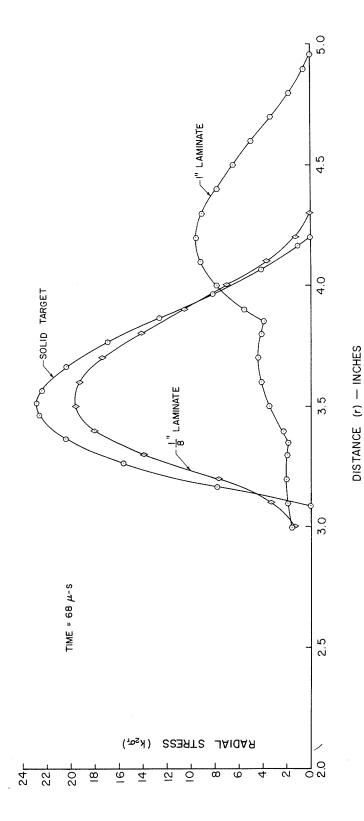
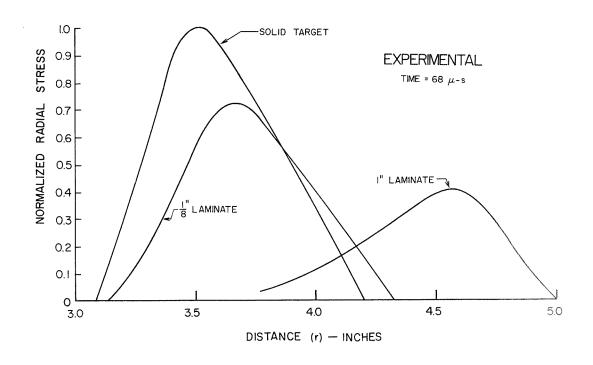


FIGURE 20
SUPERPOSITION OF TRANSMITTED STRESS WAVES IN LAMINATED TARGETS



TARGETS OF THEORETICAL STRESSES IN HOMOGENEOUS AND LAMINATED COMPARISON

FIGURE 2



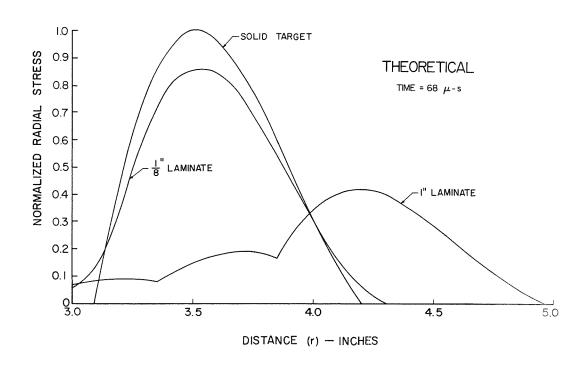


FIGURE 22

COMPARISON OF EXPERIMENTAL AND THEORETICAL RESULTS