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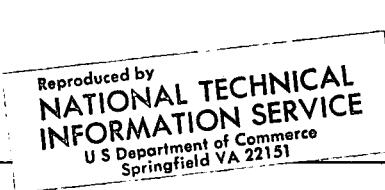
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## Summary Report

# SHUTTLE OPERATIONS SIMULATION MODEL PROGRAMMERS'/USERS' MANUAL

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SIMULATION MODEL PROGRAMMERS'/USERS' MANUAL  
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SUMMARY REPORT  
ASD-ASTN-1533

SHUTTLE OPERATIONS SIMULATION MODEL  
PROGRAMMERS'/USERS' MANUAL

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June 1972

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Contract No. NAS8-21804

**Details of illustrations in  
this document may be better  
studied on microfiche**

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## ABSTRACT

The prospective user of the Shuttle Operations Simulation (SOS) Model is given sufficient information by this document to enable him to perform simulation studies of the Space Shuttle launch-to-launch operations cycle. The procedures used for modifying the SOS Model to meet user requirements are described. The various control card sequences required to execute the SOS Model are given in the text of the report. The report is written for users with varying computer simulation experience.

A description of the components of the SOS Model is included that presents both an explanation of the logic involved in the simulation of the Shuttle operations cycle and a description of the routines used to support the actual simulation.

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## DEFINITION OF SYMBOLS

CA      Cards added

CD      Cards deleted

CPU     Central Processing Unit

GPSS    General Purpose Systems Simulator

LUT     Launch Umbilical Tower

MSFC    Marshall Space Flight Center

SOS     Shuttle Operations Simulation

**Control Card Sequence**--A sequence of UNIVAC 1108 instructions that represents the information required to execute a computer program.

**Insert Card**--A specific card type used to indicate the addition to or the deletion of the statements contained in the computer program.

**Location Number**--The UNIVAC 1108 computer assigned number to each statement of the computer program.

**Mnemonic Inserts**--The GPSS II language commonly uses numeric block identification numbers. The language can accept alphanumerics as block numbers by using specific control card sequences. The alphanumeric block identification numbers are referred to as mnemonic inserts.

**Model**--A representation of a process or concept that permits the manipulation of its parameters as a means of determining how the concept or process behaves in various situations.

**Operational Cycle**--Those functions performed on each Shuttle element after its previous launch in preparation for its succeeding launch.

**Simulation**--Represents the behavior of a physical system by means of a computer and a program. The computer and program serves to demonstrate system behavior under the influence of stimuli and permits system performance analysis.

**Subprogram**--A routine designed to solve a particular problem that becomes applicable to the problem only when appropriate parametric values are supplied.

## **DEFINITION OF SYMBOLS (Concluded)**

**Supplemental Fortran Instructions**--A collection of Fortran routines, both user written and GPSS II language supplied, that implement and support the simulation of the Shuttle turnaround cycle.

**System Model Description**--A sequence of GPSS II language instructions that, upon implementation, simulate the Space Shuttle launch-to-launch operations cycle.

**Turnaround Cycle**--Starting with a Shuttle vehicle at launch, represents those operations performed to prepare the vehicle to the same state of preparedness for its next launch.

## SECTION I. INTRODUCTION

### A. Purpose

A model has been developed that analyzes the major events of the Space Shuttle launch-to-launch operations cycle. The formulation of a model describing the Shuttle operations cycle was initiated by isolating the operational characteristics of the elements involved in the operations cycle. Next, the logical rules governing the interaction of those operational characteristics were identified and formulated into a model describing the entire Shuttle launch-to-launch operations cycle. To further analyze the system, a simulation technique was employed as an effective method of testing and evaluating the proposed real system. The simulation technique employed allows statistical estimates of the operational parameters in the real system. Using the results of the simulation technique only allows comparison of the alternatives to the real system, and does not necessarily generate an optimal solution. The resulting model has been named the Shuttle Operations Simulation (SOS) Model and, as developed, is activity oriented and designed to simulate the major events of the Space Shuttle launch-to-launch operations cycle. The SOS Model serves as a tool for conducting operations and logistical analysis relevant to the definition and design phase of the Space Shuttle program.

The Space Shuttle operational cycle is described by the General Purpose Systems Simulator (GPSS) II computer language which is supported by special purpose Fortran subprograms. As written, the SOS Model is capable of projecting real life activities and functions which will probably occur during the operational phase of the Space Shuttle program. From the results of parametric studies, real life projection and logistical and operational requirements can be determined for the Space Shuttle system.

This document is written to describe the use and operations of the SOS Model. Sufficient data and instructions are given to the potential user of the SOS Model to enable him to modify the model to meet his particular needs. A complete description of the components of the SOS Model is also given within the text of this document.

B. Scope

This report provides instructions for the use and operation of the SOS Model. Supplemental information is given to allow user modifications to the program enabling the user to meet his particular requirements. Section II of this document contains general information relating to the SOS Model operations and a description of the necessary input data required for implementing the SOS Model. Section III describes the two basic components of the SOS Model, the System Model Description, and the Supplemental Fortran Instructions. Included in Section IV are the control card sequences used to execute the SOS Model along with a description of each control card sequence. The Appendices contain data to support the sections of this document.

## SECTION II. SOS MODEL OPERATING INSTRUCTIONS

### A. General Information

The SOS Model is designed for execution by the Marshall Space Flight Center (MSFC) UNIVAC 1108 EXEC VIII Computer System and requires approximately 32,800 words of core storage. The SOS Model consists of two major components: the System Model Description and the Supplemental Fortran Instructions. The System Model Description component consists of a sequence of GPSS II language instructions that describe the launch-to-launch operation cycle of the Space Shuttle flight elements and support hardware. The Supplemental Fortran Instructions are a combination of user-written Fortran subprograms and the standard subprograms supplied as part of the GPSS II language. The GPSS II supplied subprograms are responsible for implementing the instructions contained in the System Model Description.

The SOS Model is maintained as a catalogued drum file by the UNIVAC 1108 computer located at MSFC. The catalogued file contains both the Supplemental Fortran Instructions and the System Model Description which defines a baseline configuration of the operational elements and their time distribution parameters. The System Model Description, as catalogued, defines a specific operational concept for the Space Shuttle launch-to-launch operations cycle. Using the basic configuration, a number of Shuttle flight elements and support facility arrangements are capable of being studied. Therefore, the user must decide the type of analysis to be performed and select the parameters to be varied.

### B. Temporary System Model Modification Procedure

If the catalogued version of the System Model Description of the SOS Model is not entirely satisfactory to the user, temporary modifications to the System Model Description can be accomplished by utilizing the procedure described below. In making temporary model modifications, it will be useful to refer to Appendix A which contains a printout of the System Model Description. This printout is fully documented with each of the GPSS II language system variables used in the System Model Description defined prior to the first GENERATE block. Section IV shows the appropriate placement of the Model modification cards in the control card sequences required to execute the SOS Model.

Each statement of the System Model Description is computer numbered with the number positioned to the extreme left of each statement. Appendix A contains a computer printout of the System Model Description showing the GPSS II statements, block numbers, and computer assigned location numbers. To temporarily modify the System Model Description, such as to change the Booster and Orbiter storage capacities or to change the number of launch pads, the insert card method is used.

The insert card method requires an insert card which contains any of the following: the location number of the statement to be replaced (Example 1), the sequential location numbers of the statements to be modified (Example 2), or the location number of the statement which modifications are to follow (Example 3). All insert cards are punched beginning with a minus sign in column one. The inserted statements must conform with GPSS II block type formats (Reference 2). The following examples illustrate the use of the insert card method for implementing temporary model modifications. The format for these examples is: original GPSS II statements from the System Model Description, solid line, insert cards and new GPSS II statements. A brief discussion follows each example.

Example 1:

000051	2	CAPACITY	2
000052	3	CAPACITY	2
000053	4	CAPACITY	9

---

-51,51			
2	CAPACITY	1	
-53,53			
4	CAPACITY	7	

In Example 1 the storage capacities of both Booster maintenance and Booster storage, identified as location Nos. 51 and 53, respectively, were modified. The storage capacity of Booster maintenance was changed from two to one, and the Booster storage capacity was changed from nine to seven. Notice on each insert card that the location number is listed twice. This example illustrates a one for one replacement of the statement whose location was 53. It should be noted that all statements between the insert card and the succeeding insert card, if any, will replace the statement at location 53. Thus, it is possible to delete the statement at location 53 or to insert a finite number of statements in place of the statement at location 53.

Example 2:

000060	11	CAPACITY	2
000061	12	CAPACITY	2
000062	13	CAPACITY	9

---

-60062			
11	CAPACITY	3	
12	CAPACITY	1	
13	CAPACITY	8	

Example 2 illustrates the modification procedure required when replacing all statements between and including two statement location numbers. The storage capacities of Orbiter maintenance, Orbiter test, and Orbiter storage were changed from two, two, and nine, respectively, to three, one and eight, respectively. The insert card contains the two numbers, inclusive, that identify the program segment to be modified. Using the above example and the discussion at the conclusion of Example 1, it is possible to delete all statements between and including two location numbers or to insert a finite number of statements in place of the statements between and including the indicated location numbers.

Example 3:

---

000080	31	CAPACITY	1
--------	----	----------	---

---

-80			
32	CAPACITY	3	
33	CAPACITY	4	
34	CAPACITY	3	

Example 3 illustrates how a number of statements can be inserted to follow a particular statement. It should be noted that only one location number is required on the insert card with this number preceded by a minus sign.

**Example 4:**

000489	70	QUEUE	21	ALL	71	72
--------	----	-------	----	-----	----	----

---

-489,489	70	QUEUE	21	ALL	71	73
----------	----	-------	----	-----	----	----

Example 4 changes the System Model Description from the use of two launch pads to the use of three launch pads. By using the following QUEUE card, instead of the QUEUE card shown previously in this example, the System Model Description can be modified to limit the number of launch pads to one.

70	QUEUE	21	71
----	-------	----	----

It should be noted that the maximum number of available launch pads is three.

**C. Temporary Supplemental Fortran Instructions  
Modification Procedure**

Temporary modifications to the subprograms contained in the Supplemental Fortran Instructions can be accomplished by utilizing the insert card method outlined in the preceding discussion. Appendix B contains a printout of the Supplemental Fortran Instructions. Like the System Model Description, each statement of the Supplemental Fortran Instructions has a computer assigned location number. These location numbers are used in conjunction with the insert card method previously outlined to perform the temporary modifications required by the user of the SOS Model.

Mention of the modification procedure to the Supplemental Fortran Instructions has been made only for completeness. Thus, no effort has been made to include examples of modifications. Modifications to the Supplemental Fortran Instructions should be attempted by only the most experienced user. Section IV shows the control card sequence required when modifications are made.

**D. Input Data Description**

The data input requirements for the execution of the SOS Model consist of the two card types described below.

Card type one, which is commonly referred to as the comment card, is used by the SOS Model to place a desired comment or heading on the output summary tables resulting from the execution of the SOS Model. All 80 columns of the card may be used to obtain the heading for the output summary tables.

Card type two, which is commonly referred to as the data card, defines the traffic density to be scheduled, the number of Booster and Orbiter elements to be used, the number of active Launch Umbilical Towers (LUT's), the level of significance for the statistics collected by the Confidence Interval Option (Reference 3), and the random number generator seeds for both the Traffic Model Simulator and the Shuttle Operations Simulator. The user has the option of choosing any of the 5 available traffic densities, numbered consecutively from 1 to 5 which represent 20, 35, 45, 55, and 75 launches per year, respectively. The required format for the type two data card is:

Column 1	Traffic Density Required
Columns 2 through 5 (right justified)	Number of Boosters
Columns 6 through 10 (right justified)	Number of Orbiters
Columns 11 through 15 (right justified)	Number of LUT's
Columns 16 through 20 (right justified)	Level of Significance for Confidence Interval Option
Columns 61 through 70	Random Number Seed for the Traffic Model Simulator
Columns 71 through 80	Random Number Seed for the Shuttle Operations Simulator

Sample data cards can be seen in Section IV which contains the control card sequences used to execute the SOS Model.

The Fortran format associated with data card type two in SUBROUTINE HELP is:

```
FORMAT (I1, I4, 3I5, 40X, 2I10) .
```

Following the second data card type, it is necessary to place a card which terminates the computer's execution of the current set of data. This is accomplished by placing (after the data card) a card that has the word END punched in columns seven through nine.

### SECTION III. SOS MODEL DESCRIPTION

#### A. SOS Model Components

The SOS Model consists of two major components: the System Model Description and the Supplemental Fortran Instructions (Figure 1). The model, formed by analyzing the operational elements of the Space Shuttle turnaround cycle, was translated into the GPSS II language. The resulting set of instructions that describe the model are known as the System Model Description. When the System Model Description is implemented, the launch-to-launch operations cycle of the Space Shuttle vehicle and support hardware is simulated. The Supplemental Fortran Instructions of the SOS Model contain the routines which implement the instructions contained in the System Model Description. The routines contained in the Supplemental Fortran Instructions are mostly user written Fortran routines. However, there are several routines supplied by the GPSS II language that are included in the Supplemental Fortran Instructions.

Reference 1 describes the SOS Model. Sections III B and III C give more detailed data relating to the two major components of the SOS Model.

#### B. SOS Model System Description

The System Model Description component of the SOS Model is a sequence of GPSS II language instructions that allows the simulation of the operational facts concerning individual Shuttle processing facilities, LUT's, Orbiters, and Boosters. The necessary instructions are included to simulate the operations involved in the complete launch-to-launch cycle of the Space Shuttle. The operations in the launch-to-launch cycle are expected to have time distributions associated with their performance. In order to reflect this, frequency distribution functions have been estimated that approximate the expected real life time distributions for the performance of each operation. The estimated frequency distribution functions are used in conjunction with the Monte Carlo technique to provide a stochastic simulation of the launch-to-launch operations for the Space Shuttle.

The following is a brief description of the overall logic in the System Model Description. Figure 2 is a detailed flowchart depicting

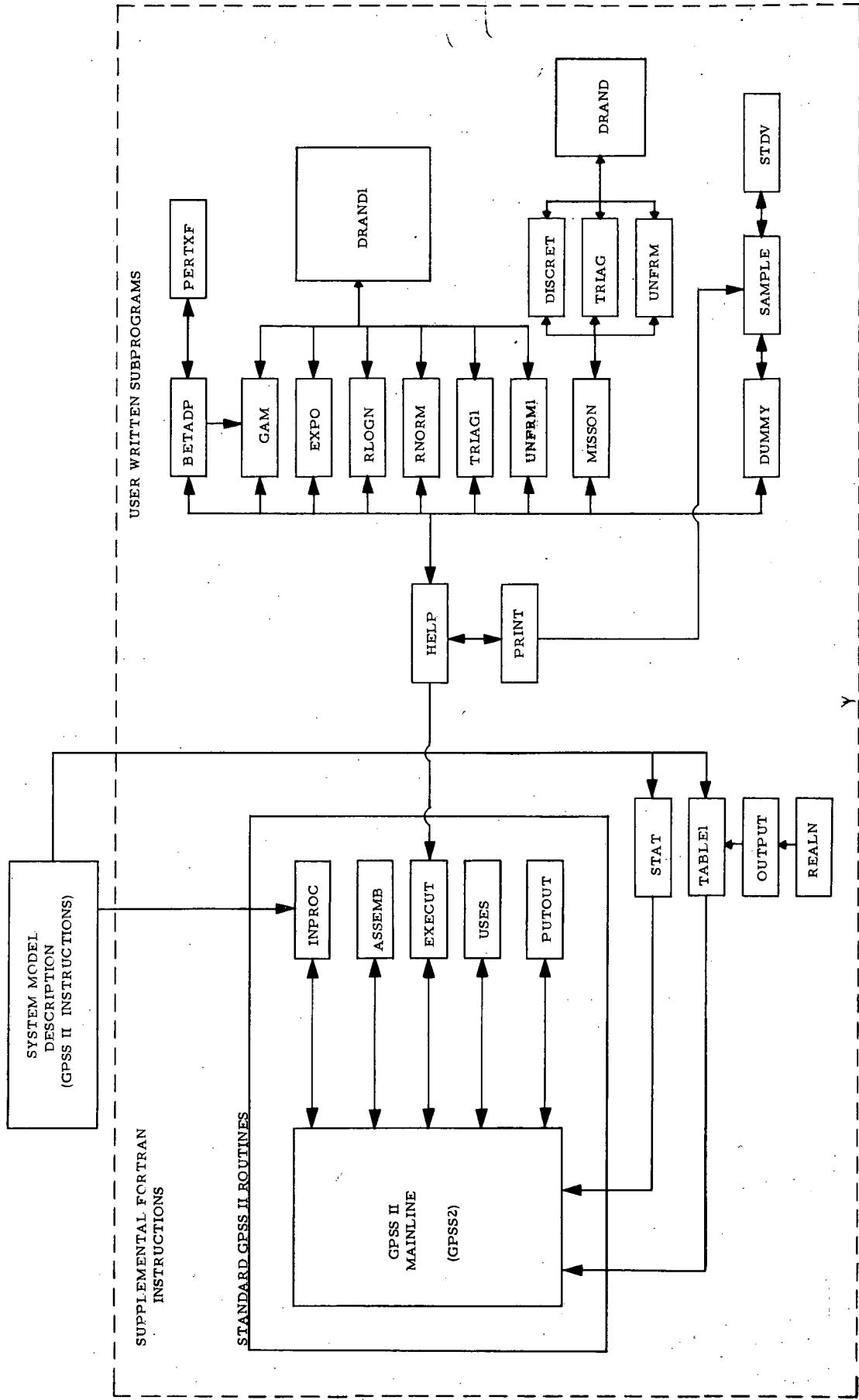


FIGURE 1. SOS MODEL CONFIGURATION

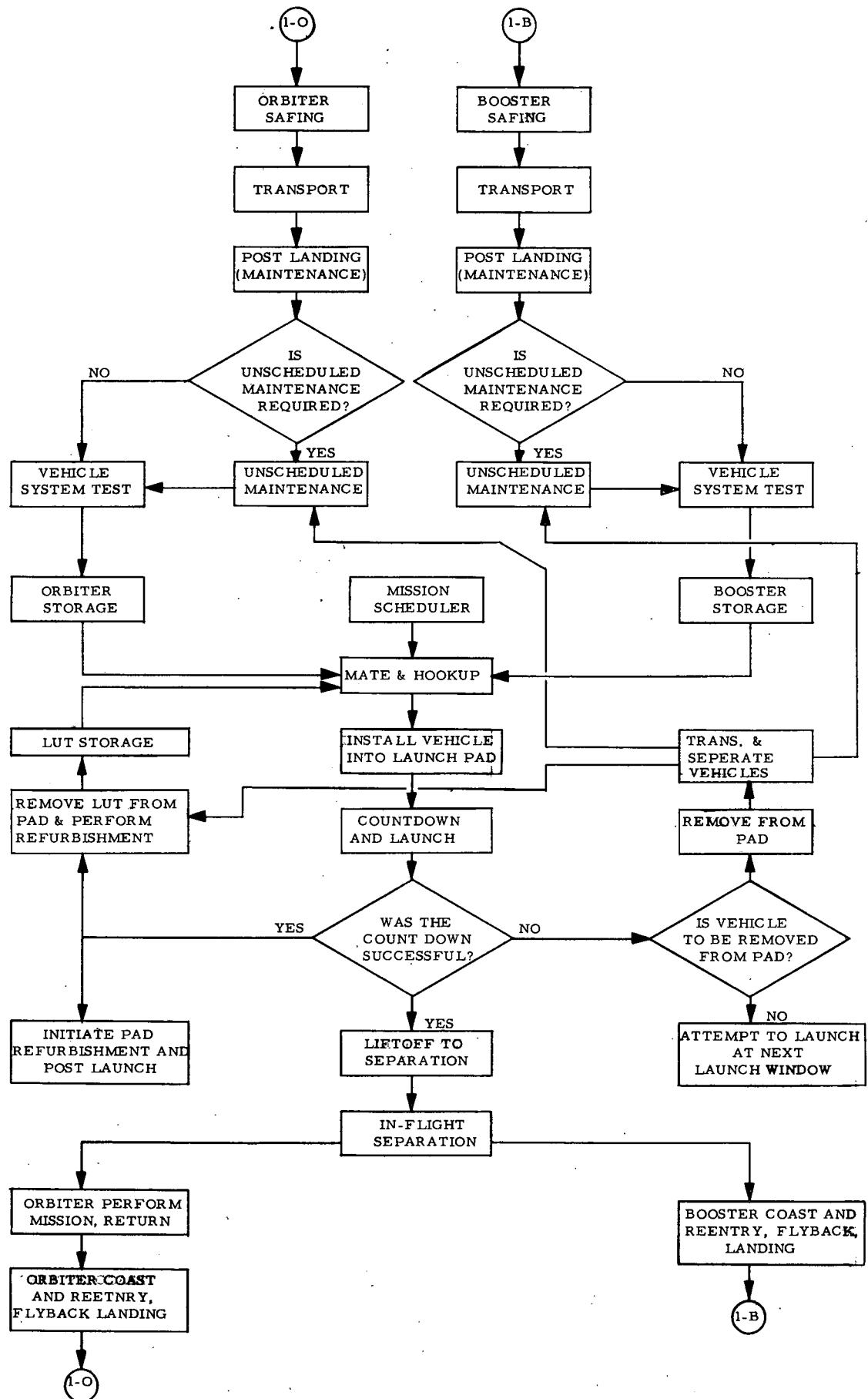


FIGURE 2. SYSTEM MODEL DESCRIPTION FLOWCHART

the functional logic of the Shuttle turnaround cycle. In the ensuing discussion, references are made to GPSS II system variables through the use of parentheses. A brief definition of the commonly used system variables is contained in Table I.

Using a GPSS II HELP block and Fortran SUBROUTINE HELP, a data card is read which contains the number of Boosters, Orbiters, and LUT's. Each of these values is placed in a separate storage location (SAVEX) for use during the simulation.

The simulation proceeds by using a HELP block to determine both a realistic first launch date and the parameters associated with the mission scheduled for that date. The HELP block, through Fortran SUBROUTINE MISSON, also establishes the time between launches. Throughout the simulation, the launch intervals and the parameters for both the current and the succeeding missions are always known.

The earliest feasible storage exit time prior to launch is the maximum processing time required to prepare the vehicle for launch. The request for vehicle elements for the current mission is not made until this time. The ready storage time prior to storage exit is determined by subtracting both the current simulated clock time (C1) and the maximum time required to process the vehicle from mate and hookup initiation to launch (V5) from the launch date of the current mission (X21). At the maximum processing time prior to the scheduled mission, a request is made to determine if there is a Booster, Orbiter, and LUT available in their respective storages. If all three elements are available, their storage departure time is recorded and they are placed in a queue for the mate and hookup operation (Q20).

The time a request may be delayed (V11) because of vehicle element unavailability is the difference between the maximum and minimum time to process the vehicle from mate and hookup initiation to launch. If this time is exceeded, the mission is cancelled and a record of the unavailable elements is kept. When all vehicle elements are available and the maximum time delay has not occurred, the pad availability is checked. The vehicle elements are removed from storage, sent to the mate and hookup waiting line (Q2), and this information is recorded. If a pad will not be available, the mission is cancelled and the pad unavailability is recorded.

When the vehicle elements complete mate and hookup (S20), the vehicle goes to the launch pad waiting line (Q21) where it is

TABLE I. DEFINITION OF COMMONLY USED SYSTEM VARIABLES\*

Scope	Name	Meaning
Equipment	F <sub>n</sub>	Facility status, facility n
	S <sub>n</sub>	Storage occupancy, storage n
Queue	Q <sub>n</sub>	Queue length, queue n
System	V <sub>n</sub>	Defined variable, numbered n
	X <sub>n</sub>	Stored value, cell n
	K <sub>n</sub>	Constant n

\*A more complete description of the available GPSS II system variables can be found in Reference 2.

assigned to the first available pad after the pads have been checked in sequential order. (After a vehicle has been assigned a pad, the pad is unavailable until either the vehicle has been launched and the pad refurbished or until the vehicle is removed from the pad.)

Once a pad has been assigned to a vehicle and a LUT, they are transferred to the pad from the launch pad waiting line (Q21). The vehicle is installed on the pad and precountdown preparations are performed (S22). The countdown time (V6) is compared to the time left to launch (V2) to determine if sufficient time remains to complete countdown. If excess time exists to launch, a built-in variable length hold (V3) is utilized. When insufficient time remains to meet the first launch window, the second launch window is tried.

Should a failure occur while the vehicle is in countdown, a check is made to determine if the failure can be corrected on the pad. If the failure cannot be corrected on the pad, the vehicle and LUT are removed from the pad (S25) and the pad is released for the use of another mission. The Orbiter is separated from the Booster and LUT (S30) and sent to maintenance (S11). The Booster is separated from the LUT (S19) and they are sent to their respective maintenances (S2, S18). If no failure occurs, the vehicle is launched. The LUT is removed from the pad (S17) and sent to maintenance (S18) and the launch pad is refurbished (S27) and released for future launches. The lift-off time, time between lift-off and separation, Booster flight time, and Orbiter flight time are recorded.

After the Booster flies back and lands, it enters the waiting line for Booster safing (Q1) and enters the safing facility (S1) when it becomes available. Upon completion of safing, the Booster enters the maintenance waiting line (Q2) and maintenance is performed. When maintenance is completed, the Booster enters storage and becomes available for future launch requests.

After the Orbiter has performed its mission, flown back to landing site and landed, it enters the waiting line for Orbiter safing (Q10). When the safing facility (S10) becomes available, the Orbiter is safed and transported to the Orbiter maintenance waiting line (Q11). After maintenance is completed on the Orbiter, it is transported to storage for future use.

When the above Shuttle operations cycle logic is simulated, three computer outputs that describe the simulation results are available to the user of the SOS Model. Sample computer outputs resulting from executing the SOS Model can be found in Appendices C, D, and E.

### C. SOS Model Supplemental Fortran Instructions

The Supplemental Fortran Instructions component of the SOS Model is composed of user written Fortran routines and the GPSS II supplied routines. The instructions necessary to simulate the System Model Description of the SOS Model are supplied by the Supplemental Fortran Instructions. Figure 1 denotes the manner in which the System Model Description interfaces with the Supplemental Fortran Instructions.

The GPSS2 routine, as supplied by the GPSS II language, is the nucleus of the SOS Model and, as such, actually performs the operations required to execute the System Model Description which in turn simulates launch-to-launch operations cycle of the Space Shuttle. All of the GPSS II supplied routines are in binary format and cannot be changed, with the exception of the GPSS2 routine. Consequently, the GPSS2 routine is the only GPSS II supplied routine discussed within this document. At the discretion of the user, this routine may be altered through the use of Fortran parameter statements to increase or decrease the size limitations of the System Model Description. However, this should be attempted by only the most experienced of users.

Upon request, the GPSS2 routine calls either of two user written Fortran subroutines: TABLE1 and STAT. Both subroutines are used to read the System Model Description of the SOS Model as data. Both subroutines are described below.

TABLE1 is used to output a table of time distribution parameters for each of the operations simulated by the System Model Description. The output of the time distribution parameters is accomplished by reading each statement of the System Model Description until a comment card is located that has the key symbol IDST in columns 68 through 71, with columns 67 and 72 containing a blank. The program continues reading cards until a HELP card is found which is used to supply the desired information for the time distribution parameters. The program prints the title of the activity found on the comment card and the time distribution parameters found on the HELP card. Appendix C contains an example listing of the TABLE1 output. It should be noted that TABLE1 and its support routines of OUTPUT and REALN are not active during the dynamic simulation of the Space Shuttle operations cycle. Section IV gives the control card sequences required to obtain the TABLE1 output.

STAT is used to read and store headings to be in the output of confidence interval statistics. A detailed description of the use of the Confidence Interval Option is contained in Reference 3. Each statement of the System Model Description is read until a statement with the key symbol CONF in columns 67 through 70 is found. At such time, the heading contained on that statement is stored to be used during the output of the confidence interval statistics. Appendix E contains an example output from the Confidence Interval Options. STAT, like TABLE1, is not active during the dynamic simulation of the operations cycle of the Space Shuttle. A complete description of the use of SUBROUTINE STAT and of the Confidence Interval Option can be found in Reference 3.

The primary user written routine of the Supplemental Fortran Instructions is the HELP routine. The HELP routine enables the GPSS II user to perform operations that are not easily obtainable from using the GPSS II block types. Upon completion of the operations in the HELP routine, the calculated values are transmitted back to the System Model through a specified SAVEX (system variable Xn), which is a core storage location. The user employing the GPSS II HELP block must supply a Fortran subroutine called HELP which has five or less fixed point variables as arguments. These arguments are specified on the GPSS II HELP card in the X, Y, Z, Mean, and Mod field locations.

The launch requirements for the Space Shuttle and the Orbiter on-orbit mission requirements are supplied by SUBROUTINE MISSON which is supported by subprograms UNFRM, DICRET, TRIAG, and DRAND. To gain access to SUBROUTINE MISSON, one must use the HELP block in the GPSS II model as illustrated in the following example:

```
* CALL HELP TO GENERATE ATTRIBUTES OF NEXT LAUNCH
24    HELP      K1      X11     X12     B01H   10      25      X13     X10
```

Upon entering the HELP block, the program calls for SUBROUTINE HELP with its five fixed point variables. The proper form of SUBROUTINE HELP is shown below:

```
SUBROUTINE HELP(K1,K2,K3,K4,K5)
```

The first variable in the call statement, K1, is used by a Fortran computed GO TO statement within SUBROUTINE HELP to determine which Fortran user written routine is to be used to assist the operations of the GPSS II block types. In the above example, the value of K1 is used to call SUBROUTINE MISSON from SUBROUTINE HELP.

SUBROUTINE MISSON calculates the length of the next Orbiter mission, determines the mission type, computes the time until the next launch, and the time between launch opportunities. These values are calculated as different variables in SUBROUTINE MISSON and reset equal to K2, K3, K4, and K5 by SUBROUTINE HELP. The calculated values are then stored in the SAVEX locations of X11, X12, X13, and X15 for use by the GPSS II program.

## SECTION IV. UNIVAC 1108 CONTROL CARD SEQUENCES USED IN THE EXECUTION OF THE SOS MODEL

### A. General Discussion

Execution of the SOS Model can be accomplished by choosing the appropriate control card sequence of those described in this section. Multiple executions of the SOS Model can be accomplished by using the Systems Model Description as catalogued on the UNIVAC 1108 drum files. Two executions, both with and without the Confidence Interval Option and each simulating 500 Shuttle launch requests, can be obtained from one computer run with a resulting Central Processing Unit (CPU) time of approximately 3 minutes.

In selecting the appropriate control card sequence, it is assumed that the user has acquainted himself with the material and techniques presented in this document, and that he has defined his objectives sufficiently to enable an intelligent decision in the choice of control card sequences. The control card deck setups which follow are used in conjunction with the execution of the SOS Model. No effort has been made to enumerate all the possible control card sequences. Instead, only the most commonly used sequences are presented. A description of each individual control card is provided in Appendix F.

### B. Multiple Executions of the SOS Model

The basic control card sequence used for executing the SOS Model, when no modification or additions are made to either the System Model Description or the Supplemental Fortran Instructions, is shown in Figure 3. The sequence (Figure 3) includes two of the options available to the user of the SOS Model. Both options are for the convenience of the user and the inclusion or deletion of either option has no effect on the results of the simulation.

The @SETC 4 control card placed before the @XQT control card generates the TABLE1 output as described previously in this document. In order to produce the output table, it was necessary to place the System Model Description in the execution run stream. This was accomplished by the addition of the one extra @ADD MODEL control card placed immediately after the first @XQT control card.

```
l RUN //T SAMPLE,999999,P0R1ERB1N225,3,150
l ASG,T GPSSE8,F2
l COPY,RSA MASTER*GPSSE8.,GPSSE8.
l ASG,T MODEL,F2
l UDATA FILE2,MODEL
l END
l SETC 4
l XGT GPSSE8.MAPGPS
l ADD MODEL.
l ADD MODEL.
*****COMMENT CARD*****
*****DATA CARD*****
END
l SETC 5
l XGT GPSSE8.MAPGPS
l ADD MODEL.
*****COMMENT CARD*****
*****DATA CARD*****
END
l FIN
l FIN
```

FIGURE 3. MULTIPLE EXECUTION OF THE SOS MODEL  
WITHOUT MODIFICATIONS

The @SETC 3 control card placed before the second @XQT control card eliminates the printout of the model listing but allows the output of the summary results and the standard GPSS II output.

### C. Modifications to the System Model Description

If the catalogued version of the System Model Description is not completely satisfactory to the user of the SOS Model, temporary model changes can be made through the use of the control card sequence shown in Figure 4.

The control card sequence shown in Figure 4 is used for multiple executions of the SOS Model. The sequence also encompasses the use of the TABLE1 output and the use of the @SETC 3 command. If only one execution is desired, the two @FIN cards should follow the first END card.

### D. Modifications to the Supplemental Fortran Instructions

The user written routines of the Supplemental Fortran Instructions can be added to or modified in order to meet the user's requirements by utilizing the control card sequence shown in Figure 5. The use of this control card sequence enables the user to test both a modified user written routine and a newly developed user written routine by utilizing the catalogued drum files. The control card sequence (Figure 5) is an example of only one execution of the SOS Model; but, multiple executions are possible by utilizing the information previously supplied in this section. The procedure for modifying the user written routines entails the use of the insert card method described previously in conjunction with modifications to the System Model Description. More detailed information concerning the user written routines can be found in Appendix B.

### E. Creation of an Update Tape

The control card sequence (Figure 6) is used to create a tape that includes all updates to both the Supplemental Fortran Instructions and the System Model Description. The created tape, which includes all updates, can then be used to update the catalogued drum file of the SOS Model. Great care should be taken when creating a tape to be used for updating the SOS Model. To ensure the proper operation of the updated tape, Figure 7 gives the control card sequence used to test the newly created tape.

```
!RUN//T SAMPLE,999999,P0R1ERB1N225,3,150
!ASG,T GPSSE8,F2
!ASG,I MODEL,F2
!COPY,RSA MASTER*GPSSE8.,GPSSE8.
!DATA FILE2,MODEL
*****MODEL CHANGE CARD*****
*****(IF REQUIRED)*****
!END
!SETL 4
!XQT GPSSE8.MAPGPS
!ADD MODEL.
!ADD MODEL.
*****COMMENT CARD*****
*****DATA CARD*****
      END
!SETL 3
!XQT GPSSE8.MAPGPS
!ADD MODEL.
*****COMMENT CARD*****
*****DATA CARD*****
      END
!FIN
!FIN
```

FIGURE 4. MULTIPLE EXECUTION OF THE SOS MODEL WITH SYSTEM MODEL DESCRIPTION MODIFICATIONS

```
l RUN //T SAMPLE,999999,PURTERBIN225,3,150
l ASG,T GPSSE8,F2
l ASG,T MODEL,F2
l COPY,RSA MASTER*GPSSE8.,GPSSE8.
*** ANY SUPPORTING FORTRAN SUBPROGRAMS WHICH ARE
*** BEING MODIFIED SHOULD BE INSERTED AS FOLLOWS.
*** (REPLACE 'NAME' WITH THE APPROPRIATE SUBPROGRAM NAME)
l FOR,US GPSSE8.NAME,GPSSE8.NAME
*** INSERT THE CHANGES TO SUBPROGRAM 'NAME'.
***
*** ANY SUPPORTING FORTRAN SUBPROGRAMS WHICH ARE
*** BEING ADDED SHOULD BE INSERTED AS FOLLOWS.
*** (REPLACE 'NAME' WITH THE APPROPRIATE SUBPRGRAM NAME)
l FOR,IS GPSSE8.NAME,GPSSE8.NAME
*** INSERT THE ADDED SUBPROGRAM 'NAME'.
l HUG,R (IN THESE SPACES,ANY DESIRED COMMENT)
l PREP GPSSE8.
l MAP,NX GPSSE8.MAP,GPSSE8.MAPGPS
l DATA FILE2,MODEL
*****MODEL CHANGE CARDS*****
***** (IF REQUIRED)*****
l END
l XQT GPSSE8.MAPGPS
l ADD MODEL.
*****COMMENT CARD*****
*****DATA CARD*****
END
l FIN
l FIN
```

FIGURE 5. EXECUTION OF THE SOS MODEL WITH SUPPLEMENTAL FORTRAN INSTRUCTIONS MODIFICATIONS

```

l RUN //T SAMPLE,999999,PURITERBIN225,3,200/5000
l ASG,T TAPENAME,1,SAVEU2
l ASG,T GPSSE8,F2
l ASG,T DUMMYP,F2
l ASG,T MODEL,F2
l COPY,RSA MASTER*GPSSE8.,GPSSE8.
l HUG,P <<<PROGRAM FILE UPDATE NUMBER AAA>>>
***INSERT ALL SUBPROGRAM UPDATES AND INSERTIONS HERE***
l PREP GPSSE8.
l MAP,XS GPSSE8.MAP,GPSSE8.MAPGPS
l HUG,P <<<SOS MODEL UPDATE MSFC VERSION 111-BBB>>>
l DATA,L FILE2,MODEL
-1,1
      .ASSEMBLER
      JOB
***INSERT ALL MODEL MODIFICATIONS HERE***
-XXX,XXX
      END
l END
l SETC 2
l BRKPT PUNCH$/DUMMYP
l XQT GPSSE8.MAPGPS
l ADD MODEL.
l BRKPT PUNCH$
l DATA,L DUMMYP,MODEL
-YYY,YYY
      START      501
l END
l REWIND TAPENAME
l COPOUT GPSSE8,TAPENAME
l COPY,GM MODEL,TAPENAME
l ERS GPSSE8.
l REWIND TAPENAME
l COPIN TAPENAME,IPFS.
l FREE TAPENAME.
l HUG,P <REVISION NUMBER CCC TO THE SYSTEM FILE>
l PRT,T
l XQT,LÄ SYSS*MSFC$.LISTIT
l FIN

```

FIGURE 6. CREATION OF A TAPE FOR UPDATING THE SOS MODEL

A few words of explanation are needed before the user attempts to create a tape containing the inserts and additions to either of the major components of the SOS Model. In the control card sequence (Figure 6), it should be noted that there are two insert cards, one with a location number of XXX and one with a location number of YYY. Before attempting to create the tape, location number XXX needs to be replaced by the location number of the GPSS II START card. At this time in the control card sequence, the System Model Description is assembled with all the statements reassigned new location numbers. The START card has been temporarily replaced by an END card which prohibits the execution of the model and prevents an error occurring during the assembly process. Location number YYY needs to be the new location number of the inserted END card and is determined by knowing the total number of new cards added (CA) and the number of cards deleted (CD) from the current version of the model. The new insert number of the END statement is found by:

$$YYY = XXX + CA - CD$$

At this time in the control card sequence, the START card permanently replaces the END card prior to storing the System Model Description on tape.

The sample control card sequence (Figure 7) is an example of one execution of the SOS Model. Multiple executions are possible by following the procedures outlined previously in this section. The numbers XXXXX on the @ASG, T TAPENAME card should be replaced by the number of the tape to be tested.

#### F. Mnemonic Inserts to the System Model Description

The control card sequence (Figure 8) is used when the modifications to the System Model Description contain mnemonic location references in the GPSS block types. Mnemonic references are helpful during the development of major modifications to the SOS Model when block location numbers are in a constant state of change. The presence of an insert card containing location number XXX should be noted in Figure 8. The number XXX should be changed to the location number of the START card before an attempt is made to execute this control card sequence. This will place an end card immediately after the START card as is required by mnemonic decks.

```

l RUN //T SAMPLE,999999,P01ERBIN225,3,150
l ASG,I TAPENAME,T,XXXXX
l ASG,T GPSSE8,F2
l ASG,I FILE2,F2
l ASG,I MODEL,F2
l REWIND TAPENAME
l COPIN TAPENAME, GPSSE8.
l COPY,G TAPENAME,FILE2
l FREE TAPENAME
l DATA FILE2,MODEL
l END
l XQT GPSSE8.MAPGPS
l ADD MODEL.
*****COMMENT CARD*****
*****DATA CARD*****
    END
l FIN
l FIN

```

FIGURE 7. TEST OF AN UPDATE TAPE

```

l RUN //T SAMPLE,999999,P01ERBIN225,3,150
l ASG,T GPSSE8,F2
l COPY,RSA MASTER*GPSSE8.,GPSSE8.
l ASG,T MODEL,F2
*** INSERT ALL SUBPROGRAM UPDATES OR INSERTIONS HERE ***
l DATA FILE2,MODEL
-1,1
    ASSEMBLER
    J0B
***INSERT ALL MODEL MODIFICATIONS HERE***
-XXX
    END
l END
l XQT GPSSE8.MAPGPS
l ADD MODEL.
*****COMMENT CARD*****
*****DATA CARD*****
l FIN
l FIN

```

FIGURE 8. EXECUTION OF THE SOS MODEL WITH MNEMONIC  
INSERTS TO THE SYSTEM MODEL DESCRIPTION

## G. Example Production Deck and Explanation

Figure 9 is an example of an SOS Model production deck with temporary System Model Description modifications. The System Model portion was modified to change the statements at locations 51, 489, and 513. The modification at location 51 altered the capacity of the Booster maintenance facility and the modification at location 489 changed the number of available launch pads to 3. The modification at location 513 resulted in a mean time for countdown preparations of 2.0 days being associated with block number 80.

Two executions of the SOS Model are required to complete the case study. The @SETC 4 command is used to obtain a listing of the time distribution parameters contained in the Systems Model Description. The @SETC 3 command is used to prevent a listing of the System Model Description for the last execution of the program. An example of the TABLE1 output from the above run is found in Appendix C.

The first requested execution of the SOS Model uses traffic density four with the number of LUT's and launch pads fixed at three and three, respectively. The number of active Boosters and Orbiters for the first study are four and five, respectively. The random number seeds for the entire case study are constant. The random number seed for the Traffic Model Simulator is 3154267131 and the random number seed for the Shuttle Operations Simulator is 4339968911. (Note: Any ten digit odd number with the last digit not ending in five may serve as a random number seed.) The second execution uses the same study conditions as the first execution with the exception of the number of Orbiters being changed to four. Sample output of the summary table and the GPSS II output resulting from the above case study can be found in Appendix D.

```

  l RUN, /P SAMPLE, 999999, PURIEBIN<25,3,15U
  l ASG,I GPSSE8.F2
  l ASG,I MODEL,F<
  l CUPY, RSA MASTER*GPSSE8.,GPSSE8.
  l DATA FILE2,MODEL
  -51,51
    2 CAPACITY   1
  -469,489
    70 GUEUE     <1          ALL    71      73
  -513,513
    79 HELP      <3          K1500 K2000      80
                                         K2500 x10
  l END
  l SETC 4
  l XGT GPSSE8.MAPGRS
  l AUD MODEL.
  l AUD MODEL.
  l DETERMINATION OF FLEET SIZE REQUIREMENTS
    4   4   5   5
    ENL
  l SETC 3
  l XGT GPSSE8.MAPGRS
  l AUD MODEL.
  l DETERMINATION OF FLEET SIZE REQUIREMENTS
    4   4   4   4
    ENL
  l FIN

```

31542671314339968911

FIGURE 9. EXAMPLE PRODUCTION DECK FOR THE EXECUTION OF THE SOS MODEL

## REFERENCES

1. Shuttle Operations Simulation Model Description. S&E-012-001-2H, Rev. A. Marshall Space Flight Center, Huntsville, Alabama, February 15, 1971.
2. Univac General Purpose Systems Simulator II. UP-4129 Reference Manual.
3. Ghiglieri, F.J. and Porter, D.G.: Requirements for the Integration of Confidence Interval Logic into the Shuttle Operations Simulation Model. Interim Report ASD-ASTN-1485, Teledyne Brown Engineering Company, Huntsville, Alabama, March 1972.

**APPENDIX A. SYSTEM MODEL DESCRIPTION LISTING**

PRECEDING PAGE BLANK NOT FILMED

000001	JOB		IIIA 20
000002	*		IIIA 30
000003	* SHUTTLE OPERATIONS SIMULATION MODEL MSFC VERSION III-D MAR. 31 1972		IIID 10
000004			IIIA 50
000005	*		IIIA 60
000006	*		IIIA 70
000007	*		IIIA 80
000008	*		IIIA 90
000009	*		IIIA 100
000010	*	ALL TIMES EXPRESSED IN THIS PROGRAM ARE IN TERMS OF MILLI WORKING DAYS (1/1000 OF A WORKING DAY)	IIIA 110
000011	*	(WORKING DAY = 16 HOURS)	IIIB 10
000012	*		IIIA 120
000013	*		IIIA 130
000014	*		IIIA 140
000015	*	PERFORMANCE TIME DISTRIBUTION CODES	IIIA 150
000016	*	K3 TRIANGULAR	IIIA 160
000017	*	K4 NORMAL	IIIA 170
000018	*	K8 EXPONENTIAL	IIIA 180
000019	*	K9 LOGNORMAL	IIIA 190
000020	*	K1 CONSTANT	IIIA 200
000021	*	K12 UNIFORM	IIIA 210
000022	*	K13 BETA	IIIC 11
000023	*		IIIC 12
000024	*		IIIA 220
000025	*		IIIA 230
000026	*		IIIA 240
000027	*		IIIA 250
000028	*		IIIB 20
000029	*	CURRENT MAXIMUM PROGRAM LIMITS	IIIB 30
000030	*	BLOCKS - 400	IIIB 40
000031	*	FACILITIES - 15	IIIB 50
000032	*	STORAGES - 50	IIIB 60
000033	*	QUEUES - 50	IIIB 70
000034	*	LOGIC SWITCHES - 25	IIIB 80
000035	*	SAVEX LOCATIONS - 50	IIIB 90
000036	*	FUNCTIONS - 10	IIIB 100
000037	*	TABLES AND QTABLES - 30	IIIB 110
000038	*	VARIABLE STATEMENTS - 30	IIIB 120
000039	*	PARAMETERS - 20	IIID 20
000040	*	TRANSACTION NUMBERS - 100	IIIB 140
000041	*		IIIB 150
000042	*		IIIB 160
000043	*		IIIB 170
000044	*		IIIB 180
000045	*		IIIB 190
000046	*		IIIA 260
000047	*		IIIA 270
000048	*		IIIA 280
000049	*	STORAGE CAPACITIES	IIIA 290
000050	*	CAPACITY 1	IIIA 300
000051	*	CAPACITY 2	IIIA 310
000052	*	CAPACITY 2	IIIA 320
000053	*	CAPACITY 9	IIIA 330
000054	*	CAPACITY 5	

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000055	*6		IIIA 340
000056	*7		IIIA 350
000057	*8		IIIA 360
000058	*9		IIIA 370
000059	10	CAPACITY 1	IIIA 380
000060	11	CAPACITY 2	IIIA 390
000061	12	CAPACITY 2	IIIA 400
000062	13	CAPACITY 9	IIIA 410
000063	14	CAPACITY 9	IIIA 420
000064	*15		IIIA 430
000065	16	CAPACITY 10	IIIA 440
000066	17	CAPACITY 2	IIIA 450
000067	18	CAPACITY 2	IIIA 460
000068	19	CAPACITY 1	IIIA 470
000069	20	CAPACITY 1	IIIA 480
000070	*21		IIIA 490
000071	22	CAPACITY 2	IIIA 500
000072	23	CAPACITY 2	IIIA 510
000073	*24		IIIA 520
000074	25	CAPACITY 2	IIIA 530
000075	*26		IIIA 540
000076	27	CAPACITY 2	IIIA 550
000077	28	CAPACITY 2	IIIA 560
000078	29	CAPACITY 1	IIIA 570
000079	30	CAPACITY 1	IIIA 580
000080	31	CAPACITY 1	IIIA 590
000081	*		IIIA 600
000082	*		IIIA 610
000083	*		IIIA 620
000084	*		IIIA 630
000085	*		IIIA 640
000086	*		IIIB 200
000087	*		IIIB 660
000088	*		IIIB 660
000089	*	NOTE - THE DEFINITIONS WHICH ARE FOLLOWED BY THE NOTATION (Q)	IIIB 210
000090	*	ALSO REFER TO A QUEUE WHICH IMMEDIATELY PRECEDES THE	IIIB 220
000091	*	STORAGE. THE DEFINITIONS WHICH ARE NOT FOLLOWED BY THE	IIIB 230
000092	*	NOTATION (Q) HAVE NO QUEUE ASSOCIATED WITH THEM.	IIIB 240
000093	*	1 - BOOSTER SAFING (Q)	IIIB 250
000094	*	2 - BOOSTER MAINTENANCE (Q)	IIIB 260
000095	*	3 - TRANSPORT BOOSTER TO SYSTEMS TEST, TEST, TRANSPORT TO STORAGE (Q)	IIIB 270
000096	*	4 - BOOSTER STORAGE	IIIA 700
000097	*	5	IIIA 710
000098	*	6	IIIA 720
000099	*	7	IIIA 730
000100	*	8	IIIA 740
000101	*	9	IIIA 750
000102	*	10 - ORBITER SAFING (Q)	IIIB 280
000103	*	11 - ORBITER MAINTENANCE (Q)	IIIB 300
000104	*	12 - TRANSPORT ORBITER TO SYSTEMS TEST, TEST, TRANSPORT TO STORAGE (Q)	IIIB 790
000105	*	13 - ORBITER BOOST TO ORBIT, PERFORM MISSION, RETURN	IIIA 800
000106	*	14 - ORBITER BOOST TO ORBIT, PERFORM MISSION, RETURN	IIIA 810
000107	*	15 - LAUNCH UMBILICAL TOWER (LUTS), STORAGE	IIIB 310
000108	*	16 - REMOVE POST LAUNCH LUT FROM PAD	IIIA 830
000109	*	17 - TRANSPORT LUT TO MAINT, REFURBISH/TEST, TRANSPORT TO STORAGE (Q)	IIIB 320
000110	*	18 - SEPARATE BOOSTER FROM LUT, TRANSPORT BOOSTER TO MAINTENANCE	IIIA 850

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000111 \* 20 - MATE AND HOOKUP BOOSTER ORBITER AND LUT (Q)  
 000112 \* 21 - QUEUE IMMEDIATELY PRECEDING THE PAD FACILITIES (NOTE- THERE IS  
 000113 \* NO ASSOCIATED STORAGE )  
 000114 \* 22 - COUNTDOWN PREPARATION  
 000115 \* 23 - COUNTDOWN  
 000116 \* 24 - REMOVE BOOSTER, ORBITER AND LUT FROM PAD  
 000117 \* 25 - REFURBISH LAUNCH PAD  
 000118 \* 26  
 000119 \* 27 - LIFTOFF THROUGH SEPARATION  
 000120 \* 28 - READY, STORAGE FOR NEXT BOOSTER, ORBITER AND LUT (Q)  
 000121 \* 29 - IMMEDIATELY PRIOR TO THE BEGINNING OF THE MATE OPERATION  
 000122 \* 30 - TRANSPORT VEHICLE, SEPARATE ORBITER-TRANSPORT ORBITER TO MAINT.  
 000123 \* 31 - RESTRICTS THE REQUEST FOR VEHICLE ELEMENTS TO ONE MISSION  
 000124 \* AT A TIME. SUCCESSIVE MISSIONS MUST WAIT UNTIL THE MISSION  
 000125 \* IMMEDIATELY IN FRONT OF THEM HAS EITHER SUCCESSFULLY MET ITS  
 000126 \* REQUEST, OR HAS BEEN CANCELLED DUE TO AN EXCESSIVE WAIT FOR  
 000127 \* VEHICLE ELEMENTS. (Q)  
 000128 \*  
 000129 \*  
 000130 \*  
 000131 \*  
 000132 \*  
 000133 \*  
 000134 \*  
 000135 \*  
 000136 \* 1 - IS A CONTINUOUS LINEAR FUNCTION WITH A SLOPE OF 1. ITS END  
 000137 \* POINTS ARE LOCATED AT (0,0) AND (999999,999999). IT IS USED  
 000138 \* TO CONVERT THE INPUT SYSTEM VARIABLE SAVEX 10 (X10) INTO  
 000139 \* FUNCTION 1,(FN1), WHICH CAN BE USED AS A MODIFIER IN AN ADVANCE  
 000140 \* BLOCK. THE FUNCTION IS DESCRIBED SUCH THAT THE CONVERSION  
 000141 \* IS ONE TO ONE (FN1=X10).  
 000142 \*  
 000143 \* 1 FUNCTION X10 C2  
 000144 0 0 999999999999  
 000145 \*  
 000146 \*  
 000147 \*  
 000148 \*  
 000149 \*  
 000150 \*  
 000151 \*  
 000152 \*  
 000153 \*  
 000154 \*  
 000155 \*  
 000156 \*  
 000157 \*  
 000158 \*  
 000159 \*  
 000160 \* 1 - BOOSTER AND ORBITER ARE AVAILABLE  
 000161 \* 2 - BOOSTER AND ORBITER ARE NOT AVAILABLE  
 000162 \* 3 - BOOSTER IS NOT AVAILABLE  
 000163 \* 4 - ORBITER IS NOT AVAILABLE  
 000164 \* 5 - BOOSTER AND/OR ORBITER AND/OR LUT NOT AVAILABLE  
 000165 \* 6 - TOTAL GENERATED LAUNCH REQUESTS  
 000166 \* 7 - ORBITER AND/OR LUT NOT AVAILABLE

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000167 \* 8 - LUT. NOT AVAILABLE WHEN BOOSTER AND ORBITER ARE AVAILABLE  
 000168 \* 9 - THE INPUT VARIABLE TO FUNCTION 1 (SEE NOTE B ABOVE)  
 000169 \* 10 - THE LENGTH OF THE NEXT ORBITER MISSION (SEE NOTE B ABOVE)  
 000170 \* 11 - THE LENGTH OF THE NEXT ORBITER MISSION (SEE NOTE B ABOVE)  
 000171 \* 12 - MISSION TYPE FOR NEXT MISSION (SEE NOTE B ABOVE)  
 000172 \* 13 - TIME UNTIL NEXT LAUNCH  
 000173 \* 14 - TIME BETWEEN LAUNCH OPPORTUNITIES FOR NEXT MISSION  
 000174 \* 15 - LENGTH OF ORBITER MISSION FOR NEXT MISSION  
 000175 \* 16 - MISSION TYPE OF CURRENT MISSION  
 000176 \* 17 - TIME UNTIL CURRENT LAUNCH  
 000177 \* 18 - TIME UNTIL CURRENT LAUNCH  
 000178 \* 19 -  
 000179 \* 20 - TIME BETWEEN LAUNCH OPPORTUNITIES FOR CURRENT MISSION  
 000180 \* 21 - TIME OF FIRST LAUNCH OPPORTUNITY FOR CURRENT MISSION  
 000181 \* 22 - VEHICLES REMOVED FROM PAD (FAILURE ON PAD)  
 000182 \* 23 - VEHICLES REMOVED FROM PAD (CONSTRAINS NEXT LAUNCH)  
 000183 \* 24 - VEHICLES REMOVED FROM PAD (NO SECOND LAUNCH WINDOW)  
 000184 \* 25 - LAUNCHES MISSED DUE TO PAD UNAVAILABILITY  
 000185 \* 26 - THE NUMBER OF VEHICLES LAUNCHED AT AN ALTERNATE LAUNCH WINDOW  
 000186 \* 27 - LAUNCH WINDOW INDICATOR  
 000187 \* 28 - NUMBER OF LAUNCHES AT PRIMARY WINDOW  
 000188 \* 29 - NUMBER OF TIMES A VEHICLE WAS REPAIRED ON THE PAD  
 000189 \* 30 - TOTAL SUCCESSFULLY ACCOMPLISHED LAUNCHES  
 000190 \* 31 -  
 000191 \* 32 -  
 000192 \* 33 -  
 000193 \* 34 -  
 000194 \* 35 - AMOUNT OF TIME AFTER PRIMARY WINDOW AT WHICH LAUNCH OCCURS  
 000195 \*  
 000196 \*  
 000197 \*  
 000198 \*  
 000199 \*  
 000200 \*  
 000201 \*  
 000202 \* 1 - GROUND PROCESSING TIME FOR EACH BOOSTER  
 000203 \* (TIME OUT OF STORAGE)-(FLIGHT TIME)\*(TIME IN STORAGE)  
 000204 \*  
 000205 \* 2 - TIME LEFT BEFORE LAUNCH (USED TO DETERMINE IF SUFFICIENT TIME  
 000206 \* REMAINS BEFORE LAUNCH TO INITIATE AND COMPLETE COUNTDOWN)  
 000207 \* (TIME TO LAUNCH FROM EARLIEST POSSIBLE STORAGE EXIT)-(ELAPSED  
 000208 \* TIME FROM EARLIEST POSSIBLE STORAGE EXIT)  
 000209 \* NOTE- IF FIRST LAUNCH WINDOW IS MISSED V2 WILL BE NEGATIVE.  
 000210 \* THIS IS TAKEN INTO ACCOUNT IN LATER VARIABLES.  
 000211 \* 3 - FLOATING HOLD TIME BETWEEN COMPLETION OF ALL PRECOUNTDOWN  
 000212 \* OPERATIONS AND THE INITIATION OF FINAL COUNTDOWN FOR THE  
 000213 \* FIRST LAUNCH OPPORTUNITY  
 000214 \* (TIME LEFT BEFORE LAUNCH)-(COUNTDOWN TIME)  
 000215 \*  
 000216 \*  
 000217 \* 4 - TIME TO SECOND LAUNCH WINDOW  
 000218 \* (TIME FIRST WINDOW WAS MISSED BY)+(TIME BETWEEN FIRST AND  
 000219 \* SECOND WINDOW)  
 000220 \*  
 000221 \* 5 - MAXIMUM TIME TO PROCESS VEHICLE FROM MATE AND HOOKUP INITIATION  
 000222 \* TO LAUNCH. THIS ALSO REPRESENTS THE EARLIEST POSSIBLE STORAGE

A-5

000223 \* EXIT FOR THE VEHICLE ELEMENTS.  
 000224 \* (ASSIGN CONSTANT = SUM OF MAXIMUM TIMES IN EACH  
 PRELAUNCH OPERATION)  
 000225 \*  
 000226 \*  
 000227 \* 6 - LENGTH OF COUNTDOWN  
 000228 \* (PREASSIGNED CONSTANT)

000229 \* 7 - GROUND PROCESSING TIME FOR EACH ORBITER  
 (TIME OUT OF STORAGE)-(FLIGHT TIME)+(TIME IN STORAGE)

000230 \* 8 - MINIMUM TIME TO PROCESS VEHICLE FROM MATE AND HOOKUP INITIATION  
 TO LAUNCH. THIS ALSO REPRESENTS THE LATEST POSSIBLE STORAGE  
 EXIT FOR THE VEHICLE ELEMENTS IF THE FIRST LAUNCH WINDOW IS  
 TO BE MET.

000231 \* ASSIGN CONSTANT = SUM OF MINIMUM TIMES IN EACH  
 PRELAUNCH OPERATION)

000232 \* 9 - TIME VEHICLES ARE HELD IN READY STORAGE PRIOR TO EARLIEST  
 POSSIBLE INITIATION OF MATE AND HOOKUP RELATIVE TO THEIR MISSION  
 (LAUNCH TIME)-(CURRENT TIME)-(VARIABLE 5)

000233 \* 10 - THE NUMBER OF SIMULATIONS FOR WHICH STATISTICS ARE COLLECTED  
 (ASSIGN CONSTANT = ONE, LESS THAN NUMBER OF SIMULATIONS  
 SPECIFIED ON THE START CARD)

000234 \* 11 - MAXIMUM TIME A REQUEST MAY WAIT FOR ANY VEHICLE ELEMENT  
 AFTER THE EARLIEST POSSIBLE MATE AND HOOKUP INITIATION.  
 (MAXIMUM TIME TO LAUNCH(V5))-(MINIMUM TIME TO LAUNCH(V8))

000235 \* 12 - TIME TO BEGINNING OF FINAL COUNTDOWN FOR THE SECOND WINDOW  
 (TIME TO SECOND LAUNCH WINDOW)-(LENGTH OF COUNT DOWN)

000236 \* 13 - LENGTH OF TIME BETWEEN EVEN AND ODD WINDOWS  
 (23.5 HOURS)-(TIME BETWEEN FIRST AND SECOND WINDOW)

000237 \* 14 - TIME LEFT TO BEGINNING OF FINAL COUNTDOWN FOR LAUNCH AT THE  
 CURRENT WINDOW.  
 (LENGTH OF TIME BETWEEN FIRST WINDOW AND CURRENT WINDOW)+(TIME  
 THE FIRST WINDOW WAS MISSED BY)-(LENGTH OF FINAL COUNTDOWN)

000238 \* 15 - DIVIDE WINDOW NUMBER BY 2 DISCARD QUOTIENT AND RETAIN REMAINDER  
 IF V15=0 THE WINDOW IS EVEN. IF V15=1 THE WINDOW IS ODD

000239 \*  
 000240 \*  
 000241 \*  
 000242 \*  
 000243 \*  
 000244 \*  
 000245 \*  
 000246 \*  
 000247 \*  
 000248 \*  
 000249 \*  
 000250 \*  
 000251 \*  
 000252 \*  
 000253 \*  
 000254 \*  
 000255 \*  
 000256 \*  
 000257 \*  
 000258 \*  
 000259 \*  
 000260 \*  
 000261 \*  
 000262 \*  
 000263 \*  
 000264 \*  
 000265 \*  
 000266 \* 1 VARIABLE MP11-P1+P2  
 000267 \* 2 VARIABLE V5-M1  
 000268 \* 3 VARIABLE V2-V6  
 000269 \* 4 VARIABLE P7+V2  
 000270 \* 5 VARIABLE K5325  
 000271 \* 6 VARIABLE K83  
 000272 \* 7 VARIABLE MP11-P1+P4  
 000273 \* 8 VARIABLE K3925  
 000274 \* 9 VARIABLE X21-C1-V5  
 000275 \* 10 VARIABLE K500  
 000276 \* 11 VARIABLE V5-V8  
 000277 \* 12 VARIABLE V4-V6  
 000278 \* 13 VARIABLE K979-P7

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000279   14 VARIABLE X35+V2-V6          IIIC 280
000280   15 VARIABLE X271K2           IIIC 290
000281   *                                IIIA1890
000282   *                                IIIB1370
000283   *                                IIIB1380
000284   *                                IIIB1390
000285   *                                IIIB1400
000286   *                                IIIB1410
000287   *                                IIIB1420
000288   * 1 - INDEPENDENT TOTAL FLIGHT TIME OF EACH BOOSTER AND ORBITER
000289   * 2 - TIME IN STORAGE FOR THE BOOSTER OF THE CURRENT MISSION
000290   * 3 - LENGTH OF CURRENT ORBITER MISSION
000291   * 4 - MISSION TYPE UNTIL REDEFINED AS TIME IN STORAGE FOR THE ORBITER
000292   * 5 - TIME OF THE CURRENT MISSION
000293   * 6 - TIME TO THE CURRENT LAUNCH
000294   *                                IIIB1470
000295   * 7 - TIME BETWEEN LAUNCH OPPORTUNITIES FOR CURRENT LAUNCH
000296   * 8 - TIME FROM LANDING TO STORAGE ENTRY
000297   * 9 - DEFINES PAD TO BE SEIZED FOR CURRENT MISSION
000298   * 10 - INITIALIZATION OF THE NUMBER OF BOOSTERS, ORBITERS AND LUTS
000299   * 11 - IS MARKED SUCH THAT THE LEAVE STORAGE TO LAUNCH TIME CAN BE
000300   * TABULATED. THE AMOUNT OF TIME EACH BOOSTER AND ORBITER
000301   * SPENDS OUT OF STORAGE IS ALSO TABULATED BY THIS PARAMETER.
000302   *                                IIIB1500
000303   *                                IIIB1510
000304   *                                IIIB1520
000305   * START NEW PROBLEM AND READ IN FLEET SIZE
000306   *                                IIIB1530
000307   *                                IIIB1540
000308   1 GENERATE 0 1                IIIB1550
000309   * 2 BOOSTER ORBITERS          LUT
000310   * 2 HELP K7 X11 X10          X12
000311   *                                IIIB1560
000312   * ENTER X10 NUMBER OF ORBITERS INTO STORAGE 13
000313   *                                IIIB1570
000314   3 ASSIGN 10 X10             4
000315   4 ENTER 13 P10              5
000316   *                                IIIB1580
000317   * ENTER X11 NUMBER OF BOOSTERS INTO STORAGE 4
000318   5 ASSIGN 10 X11             6
000319   6 ENTER 9 P10              7
000320   *                                IIIB1590
000321   * ENTER X12 NUMBER OF LUTS IN STORAGE 16
000322   *                                IIIB1600
000323   7 ASSIGN 10 X12             8
000324   8 ENTER 16 P10              15
000325   *                                IIIB1610
000326   *                                IIIB1620
000327   *                                IIIB1630
000328   *                                IIIB1640
000329   *                                IIIB1650
000330   * GENERATE SUFFICIENT TIME TO MEET THE FIRST MISSION REQUEST
000331   *                                IIIB1660
000332   * INITIALIZE SAVEX 16 THROUGH 21 WITH FIRST TRANSACTION START TIME
000333   *                                IIIB1670
000334   *                                IIIB1680

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000335      9     SAVEX    16    X11    10
000336      10    SAVEX    17    X12    11
000337      11    SAVEX    18    X13    12
000338      12    SAVEX    20    X15    13
000339      *INITIALIZE TIME TO LAUNCH CUMULATOR WITH SIMULATION START TIME
000340      13    SAVEX    21    C1     BOTH 14   15
000341      * DETERMINE IF FIRST LAUNCH REQ • HAS ENOUGH TIME TO MEET ITS LAUNCH
000342      * CALL HELP & DETERMINE A MORE REALISTIC FIRST LAUNCH REQ.
000343      * RETURN AND REINITIALIZE SAVEX 16 THROUGH 21
000344      14    COMPARE   X18   GE    V5    16
000345      * RETURN AND REINITIALIZE SAVEX 16 THROUGH 21
000346      * CALL HELP & DETERMINE A MORE REALISTIC FIRST LAUNCH REQ.
000347      * RETURN AND REINITIALIZE SAVEX 16 THROUGH 21
000348      15    HELP     K1    X11   X12    9     X13   X15
000349      * RETURN AND REINITIALIZE SAVEX 16 THROUGH 21
000350      * RETURN AND REINITIALIZE SAVEX 16 THROUGH 21
000351      * RETURN AND REINITIALIZE SAVEX 16 THROUGH 21
000352      16    LOGIC     R3    17
000353      17    TERMINATE
000354      *
000355      *
000356      *
000357      *
000358      *
000359      *
000360      *
000361      *
000362      *
000363      *
000364      * THE SIMULATION TRANSACTIONS ARE GENERATED FOLLOWING THIS POINT
000365      *
000366      *
000367      *
000368      *
000369      *
000370      *
000371      *
000372      *
000373      *
000374      *
000375      *
000376      *
000377      * GENERATE LAUNCHES BASED ON PROJECTED TRAFFIC REQUIREMENT
000378      *
000379      18    GENERATE   LR3
000380      19    GATE      S?
000381      20    LOGIC     S?
000382      * COUNT THE NUMBER OF LAUNCH REQUESTS
000383      *
000384      21    SAVEX     S+   K1    22
000385      *
000386      * CALL HELP TO GENERATE ATTRIBUTES OF NEXT LAUNCH
000387      *
000388      * CALL HELP TO GENERATE ATTRIBUTES OF NEXT LAUNCH
000389      22    HELP      K1    X11   X12    23
000390      * COUNT THE NUMBER OF LAUNCH REQUESTS

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000391 *-----*
000392 *-----*
000393 *-----*
000394 *-----* ASSIGN ATTRIBUTES OF CURRENT LAUNCH TO TRANSACTION
000395 *-----* 3 - LENGTH OF THE ORBITER MISSION
000396 *-----* 4 - MISSION TYPE
000397 *-----* 5 - TIME UNTIL NEXT LAUNCH
000398 *-----* 7 - TIME BETWEEN LAUNCH OPPORTUNITIES
000399 *-----*
000400 23 ASSIGN 3 X16 24
000401 24 ASSIGN 4 X17 25
000402 25 ASSIGN 5 X18 26
000403 26 ASSIGN 7 X20 27
000404 27 SAVEX 16 X11 28
000405 28 SAVEX 17 X12 29
000406 29 SAVEX 18 X13 30
000407 30 SAVEX 20 X15 31
000408 31 SAVEX 21+ X18 32
000409 32 SPLIT 33 37
000410 33 SAVEX 10 X13 34 FN1
000411 34 ADVANCE 35 1
000412 35 LOGIC R3
000413 36 TERMINATE 36
000414 *-----*
000415 *-----*
000416 *-----*
000417 *-----*
000418 *-----* READY STORAGE QUEUE TIME INCLUDED IN TABLE 2 AND TABLE 22
000419 37 QUEUE 29 38
000420 *-----*
000421 *-----* ADVANCE UNTIL TIME TO MATE THE VEHICLES
000422 *-----*
000423 *-----*
000424 38 ENTER 29 39
000425 39 SAVEX 10 V9 40
000426 40 ADVANCE 41 FN1
000427 41 LEAVE 29 42
000428 42 QUEUE 31 43
000429 43 ENTER 31 44
000430 44 MARK BOTH 45 47
000431 *-----*
000432 *-----*
000433 *-----*
000434 *-----*
000435 *-----* CHECK IF TOO MUCH DELAY HAS OCCURRED TO MEET THE LAUNCH
000436 45 COMPARE M1 G V11 46
000437 46 LEAVE 31 25C
000438 47 GATE SNE4 BOTH 45 48
000439 48 GATE SNE13 BOTH 49
000440 49 GATE SNE16 BOTH 50
000441 *-----*
000442 *-----* CHECK TO SEE IF PAD IS AVAILABLE FOR THIS MISSION.
000443 *-----* IF NOT GO TO MISSED LAUNCH STATISTICS SECTION
000444 *-----*
000445 50 LEAVE 31 259

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000503	77	SEIZE	*9		78			IIIA3850
000504	*							IIIA3860
000505	*							IIIA3880
000506	*							IIIA3890
000507	*							IIIA3900
000508	*	COUNTDOWN PREPARATION					IDST	IIIA3910
000509	*	TRANSFER_LUT AND VEHICLE, INSTALL INTO_PAD, AND COUNTDOWN_PREPS.						IIIA3920
000510	*							IIIA3930
000511	78	ENTER	22		79	MAX		IIIA3940
000512	*	TRIANGULAR	MIN MODE			K3000_X10		IIIA3950
000513	79	HELP	K3	K2000_K2500	80	1 FN1		IIIC_312
000514	80	ADVANCE			81			IIIA3970
000515	81	LEAVE			82			IIIC_320
000516	*							IIIA4000
000517	*							IIIA4010
000518	*							IIIC_330
000519	*	DETERMINE WHICH PATH THROUGH THE LAUNCH LOGIC IS TO BE TAKEN						IIIC_340
000520	*	ESTABLISH TIME LEFT TO FIRST LAUNCH WINDOW						IIIC_350
000521	*	PRIMARY PATH						IIIC_360
000522	82	SAVEX	10	V2	ALL 83	85		IIIC_370
000523	*							IIIC_380
000524	*							IIIC_390
000525	*	IS TIME TO LAUNCH GE LENGTH OF FINAL COUNTDOWN. IF SO GO TO						IIIC_400
000526	*	PRIMARY PATH						IIIC_410
000527	*							IIIC_420
000528	*	PATH ONE						IIIC_430
000529	*	PATH ONE						IIIC_440
000530	83	COMPARE	V2	GE	V6	86		IIIC_450
000531	*	TIME TO LAUNCH IS NOT GE LENGTH OF FINAL COUNTDOWN. IS THERE						IIIC_460
000532	*	ANOTHER LAUNCH WINDOW. IF SO GO TO SECONDARY PATH						IIIC_470
000533	*							IIIC_480
000534	*							IIIC_490
000535	*	PATH TWO						IIIC_500
000536	84	COMPARE	P7	G	K0	105		IIIC_510
000537	*	TIME TO LAUNCH IS NOT GE LENGTH OF FINAL COUNTDOWN. AND THERE						IIIC_520
000538	*	IS NOT ANOTHER LAUNCH WINDOW. COUNT NUMBER OF VEHICLES REMOVED						IIIC_530
000539	*	FROM THE PAD FOR LACK OF ANOTHER LAUNCH WINDOW AND GO TO THE						IIIC_540
000540	*	VEHICLE REMOVAL PATH.						IIIC_550
000541	*							IIIC_560
000542	*	PATH THREE						IIIC_570
000543	*	PATH THREE						IIIC_580
000544	85	SAVEX	24+	K1		210		IIIC_590
000545	*							IIIC_600
000546	*							IIIC_610
000547	*							IIIC_620
000548	*							IIIC_630
000549	*	THIS IS THE PRIMARY PATH THROUGH THE LAUNCH LOGIC.						IIIC_640
000550	*							IIIC_650
000551	*							IIIC_660
000552	*							IIIC_670
000553	*							IIIC_680
000554	*	ESTABLISH LENGTH OF HOLD TO BEGINNING OF FINAL COUNTDOWN						IIIC_690
000555	86	SAVEX	10	V3				IIIC_700
000556	*	TABULATE LENGTH OF HOLD TO BEGINNING OF FINAL COUNTDOWN						IIIC_710
000557	87	TABULATE	4					IIIC_720
000558	*	SET FIRST LAUNCH WINDOW INDICATOR						

88 SAVEX 27 K1  
 ESTABLISH A BASE POINT OF ZERO FOR CALCULATING TIME BETWEEN,  
 FIRST AND SUBSEQUENT WINDOWS IN CASE THIS VEHICLE HAS A FINAL.  
 COUNTDOWN FAILURE AND CAN BE REPAIRED ON THE PAD.  
 IIIC 740

000560 \* \*  
 000561 \* \*  
 000562 \* \*  
 000563 89 SAVEX 35 KC  
 ADVANCE TO BEGINNING OF FINAL COUNTDOWN  
 90 ADVANCE  
 IIIC 750  
 IIIC 760  
 IIIC 770  
 IIIC 780

000564 \* \*  
 000565 90 ADVANCE  
 IIIC 790

000566 \* \*  
 000567 \* \*  
 000568 \* \*  
 000569 \* \*  
 FINAL COUNTDOWN  
 IIIC 800  
 IIIC 810  
 IIIC 820  
 IIIC 830  
 IDST IIIC 840  
 IIIC 850  
 IIIC 860  
 IIIC 870  
 IIIC 880  
 IIIC 890

000570 \* \*  
 000571 \* \*  
 BEGIN FINAL COUNTDOWN  
 IIIC 900  
 IIIC 910  
 IIIC 920  
 IIIC 930  
 IIIC 940  
 IIIC 950  
 IIIC 960  
 IIIC 970  
 IIIC 980  
 IIIC 990

000572 \* \*  
 000573 \* \*  
 000574 91 ENTER 23 92  
 ESTABLISH LENGTH\_OF\_FINAL COUNTDOWN  
 92 HELP K1 K83  
 93 ADVANCE TO END\_OF\_FINAL COUNTDOWN  
 93 ADVANCE  
 94 LEAVE FINAL COUNTDOWN  
 94 LEAVE  
 000580 94 LEAVE 23 .05 95 100  
 000581 \* \*  
 000582 \* \*  
 000583 \* \*  
 000584 \* \*  
 000585 \* \*  
 FAILURE HAS NOT OCCURRED DURING FINAL COUNTDOWN. COLLECT  
 APPROPRIATE STATISTICS AND INITIATE LAUNCH OF VEHICLE.  
 000586 \* \*  
 000587 \* \*  
 000588 \* \*  
 000589 \* \* TABULATE WHICH WINDOW LAUNCH OCCURS AT  
 000590 95 TABULATE 9 BOTH 96 98  
 000591 \* \* DID LAUNCH OCCUR AT PRIMARY WINDOW  
 000592 96 COMPARE X27 E K1  
 000593 \* \* COUNT NUMBER\_OF\_LAUNCHES\_AT THE PRIMARY WINDOW  
 000594 97 SAVEX 28+ K1 118  
 000595 \* \* LAUNCH DID NOT OCCUR AT THE PRIMARY WINDOW  
 000596 \* \* TABULATE AMOUNT\_OF\_TIME\_AFTER\_PRIMARY\_WINDOW\_LAUNCH OCCURRED  
 000597 98 TABULATE 8  
 000598 \* \* COUNT NUMBER\_OF\_LAUNCHES\_AT\_A\_SUBSEQUENT\_WINDOW  
 000599 99 SAVEX 26+ K1 118  
 000600 \* \*  
 000601 \* \*  
 000602 \* \*  
 000603 \* \*  
 000604 \* \* FAILURE HAS OCCURRED DURING FINAL COUNTDOWN (5 PERCENT PROB.)  
 000605 \* \* REMOVE 50 PERCENT OF THESE VEHICLES FROM PAD. ATTEMPT TO LAUNCH  
 000606 \* \* 50 PERCENT AT A LATER WINDOW.  
 000607 100 ADVANCE  
 000608 \* \* COUNT NUMBER\_OF\_VEHICLES REMOVED FROM PAD DUE TO A FINAL  
 000609 \* \* COUNTDOWN FAILURE.  
 000610 101 SAVEX 22+ K1 210  
 000611 \* \* COUNT NUMBER\_OF\_TIMES A VEHICLE WAS REPAIRED ON THE PAD.  
 000612 102 SAVEX 29+ K1 BOTH 103 104  
 000613 \* \* IS THERE ANOTHER LAUNCH OPPORTUNITY  
 000614 103 COMPARE P7 G KO 112

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000615 * THERE IS NOT ANOTHER LAUNCH OPPORTUNITY
000616 * COUNT NUMBER OF VEHICLES REMOVED DUE TO NO FURTHER
000617 * LAUNCH WINDOW. THEN GO TO VEHICLE REMOVAL PATH.
000618 104 SAVEX 24+ K1
000619 * THERE IS ANOTHER LAUNCH OPPORTUNITY
000620 * SET SECOND LAUNCH WINDOW INDICATOR
000621 *
000622 *
000623 *
000624 *
000625 *
000626 *
000627 *
000628 * THIS THE SECONDARY PATH THROUGH THE LAUNCH LOGIC. ONLY VEHICLES
000629 * WHICH CANNOT LAUNCH ON THE PRIMARY WINDOW FLOW THROUGH THIS SECTION
000630 105 SAVEX 27 K2
000631 * TABULATE AMOUNT OF TIME LEFT TO FIRST WINDOW (MAY BE NEGATIVE)
000632 106 TABULATE 7 BOTH 107 III
000633 * IS THERE TIME TO LAUNCH AT THE SECOND WINDOW
000634 107 COMPARE V4 GE V6 108
000635 * THERE IS TIME TO LAUNCH AT THE SECOND WINDOW
000636 * ESTABLISH LENGTH OF HOLD TO BEGINNING OF FINAL COUNTDOWN
000637 * FOR THE SECOND WINDOW
000638 108 SAVEX 10 V12 109
000639 * ESTABLISH LENGTH OF TIME BETWEEN FIRST AND SECOND WINDOW
000640 109 SAVEX 35 P7 110
000641 * TABULATE HOLD TO BEGINNING OF FINAL COUNTDOWN FOR THE
000642 * SECOND WINDOW
000643 110 TABULATE 5 90
000644 *
000645 *
000646 * THERE IS NOT TIME TO LAUNCH AT THE SECOND WINDOW
000647 * ESTABLISH LENGTH OF TIME BETWEEN FIRST AND SECOND WINDOW
000648 111 SAVEX 35 P7 112
000649 * INCREMENT WINDOW INDICATOR TO NEXT WINDOW
000650 112 SAVEX 27+ K1 BOTH 113 115
000651 * DETERMINE IF THE WINDOW BEING TRIED IS EVEN OR ODD
000652 113 COMPARE V15 G KO 114
000653 * THE WINDOW IS ODD*
000654 * ESTABLISH LENGTH OF TIME BETWEEN FIRST AND SUBSEQUENT
000655 * ODD WINDOWS
000656 114 SAVEX 35+ V13 BOTH 116 112
000657 *
000658 *
000659 * THE WINDOW IS EVEN
000660 * ESTABLISH LENGTH OF TIME BETWEEN FIRST AND SUBSEQUENT
000661 * EVEN WINDOWS
000662 115 SAVEX 35+ P7 BOTH 116 112
000663 * IS THERE TIME TO LAUNCH AT THIS WINDOW. IF NOT TRY NEXT WINDOW
000664 116 COMPARE V14 GE KO 117
000665 * THERE IS TIME TO LAUNCH
000666 * ESTABLISH LENGTH OF HOLD TO BEGINNING OF FINAL COUNTDOWN
000667 117 SAVEX 10 V14 110
000668 *
000669 *
000670 *

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\* 000671 \* IIICC630  
 \* 000672 \* IIIA4570  
 \* 000673 \* IIIA580  
 \* 000674 \* IIIA4590  
 \* 000675 \* IIIA900  
 \* 000676 \* IIIA4910  
 \* 000677 \* \* FAILURE HAS NOT OCCURRED DURING TIME ON PAD. INITIATE LAUNCH OF SHUTTLE.  
 \* 000678 \* IIIA4920  
 \* 000679 \* IIIA930  
 \* 000680 \* 118 SPLIT 119 120  
 000681 119 MATCH 128 140  
 000682 120 SPLIT 121 142  
 000683 121 SPLIT 136 122  
 \* 000684 \*  
 000685 \*  
 000686 \*  
 000687 \* LUT REMOVAL AND PAD REFURBISHMENT PATH  
 \* 000688 \* THIS PATH IS SIMULTANEOUS WITH THE FLIGHT AND REFURBISH PATH.  
 \* 000689 \*  
 000690 \*  
 000691 \*  
 \* REMOVE POST LAUNCH LUT FROM PAD  
 000692 122 ENTER 17 123  
 000693 123 HELP K3 K1250 K1500 124 K1750 X10  
 000694 124 ADVANCE 1 1 FN1  
 000695 125 LEAVE 17 126 SPLIT  
 000696 126 MATCH 127 130  
 000697 127 ASSEMBLE 2 128 130  
 000698 128 TERMINATE 119 129  
 000699 129 TERMINATE \*  
 000700 \*  
 000701 \*  
 000702 \*  
 000703 \*  
 000704 \* TRANSPORT LUT TO MAINT.REFURBISH TEST. TRANSPORT TO STORAGE..... IDST  
 \* 000705 \* 130 QUEUE 18 131  
 000706 131 ENTER 18 132  
 000707 132 HELP K3 K2700 K3000 133 K3300 X10  
 000708 133 ADVANCE 1 1 FN1  
 000709 134 LEAVE 18 135  
 000710 135 ENTER 16 K1 129  
 000711 136 ENTER 27 137 MAX  
 000712 \*  
 000713 \*  
 000714 \*  
 000715 \* REFURBISH LAUNCH PAD  
 000716 \*  
 000717 \*  
 000718 136 ENTER 27  
 \* 000719 \* TRIANGULAR MIN MODE  
 000720 137 HELP K3 K950 K1000 138 K1050 X10  
 000721 138 ADVANCE 1 1 FN1  
 000722 139 LEAVE 27 127  
 000723 140 RELEASE \*9 191  
 000724 141 TERMINATE  
 000725 \*  
 000726 \*



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000783 * WAITING LINE FOR BOOSTERS GOING INTO SAFING FACILITY
000784 * WAITING LINE FOR BOOSTERS GOING INTO SAFING FACILITY
000785 * WAITING LINE FOR BOOSTERS GOING INTO SAFING FACILITY
000786 * WAITING LINE FOR BOOSTERS GOING INTO SAFING FACILITY
000787 157 QUEUE 1 158
000788 *
000789 *
000790 *
000791 *
000792 * BOOSTER SAFING
000793 158 ENTER 1 159
000794 * TRIANGULAR MIN MODE
000795 159 HELP K3 K900 K1000 MAX K100 X10
000796 160 ADVANCE K900 K1000 1 FN1
000797 161 LEAVE 1 162
000798 162 HELP K3 K50 K100
000799 * ADVANCE K50 K100
000800 *
000801 * TRANSPORT BOOSTER TO MAINTENANCE
000802 * TRANSPORT BOOSTER TO MAINTENANCE
000803 *
000804 * TRIANGULAR MIN MODE
000805 162 HELP K3 K50 K100 MAX K150 X10
000806 163 ADVANCE K50 K100 1 FN1
000807 *
000808 *
000809 *
000810 * BOOSTER MAINTENANCE
000811 * BOOSTER MAINTENANCE
000812 *
000813 164 QUEUE 2 165
000814 165 ENTER 2 166
000815 * TRIANGULAR MIN MODE
000816 166 HELP K3 K2250 K2500 MAX K2750 X10
000817 167 ADVANCE K2250 K2500 25 170 168 1 FN1
000818 *
000819 * BOOSTER ADDITIONAL MAINTENANCE
000820 *
000821 * EXPONENTIAL MIN MEAN
000822 168 HELP K8 K500 K1000 X10
000823 169 ADVANCE K500 K1000 170 1 FN1
000824 170 LEAVE 2 171
000825 *
000826 *
000827 *
000828 *
000829 * TRANSPORT BOOSTER TO SYSTEMS TEST. TEST. TRANSPORT TO STORAGE
000830 *
000831 171 QUEUE 3 172
000832 172 ENTER 3 173
000833 173 HELP K3 K1900 K2000 K2100 X10
000834 174 ADVANCE K1900 K2000 1 FN1
000835 175 LEAVE 3 176
000836 *
000837 * BOOSTER STORAGE WHEN WAITING FOR ORBITER OR LAUNCH REQUIREMENT
000838 *

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000839	176	ENTER	4	K1	177	IIIIA6500
000840	177	HELP	K5	K1	C1	IIIIA6590
000841	178	TABULATE	3			IIIIA6600
000842	179	TABULATE	1			IIIIA6610
000843	*					IIIIA6620
000844	*					IIIIA6630
000845	*	ORBITER BOOST INTO ORBIT. PERFORM MISSION AND RETURN				IIIIA6640
000846	*					IIIIA6650
000847	180	ENTER	14		181	IIIIA6660
000848	181	SAVE X	10	P3	182	IIIIA6670
000849	182	ASSIGN	1+	FN1		IIIIA6680
000850	183	ADVANCE			183	IIIIA6690
000851	184	LEAVE	14		184	IIIIA6700
000852	*				185	IIIIA6710
000853	*					IIIIA6720
000854	*					IIIIA6730
000855	*	PARAMETER 8 COLLECTS THE TIME FROM LANDING UNTIL ENTRY INTO STORAGE				IIIIA6740
000856	185	MARK	8		186	IIIIA6750
000857	*					IIIIA6760
000858	*					IIIIA6770
000859	*					IIIIA6780
000860	*					IIIIA6790
000861	*	ORBITER SAFING				IIIIA6800
000862	*					IDST IIIIA6810
000863	186	QUEUE	10		187	IIIIA6820
000864	187	ENTER	10		188	IIIIA6830
000865	*	TRIANGULAR	MIN	MODE		IIIIA6840
000866	*	HELP	K3	K900..K2000	MAX	IIIIC1914
000867	188	ADVANCE			K100 X10	IIIIA6860
000868	189	LEAVE	10		1 FN1	IIIIA6870
000869	190	LEAVE			191	IIIIA6880
000870	*					IIIIA6890
000871	*					IIIIA6900
000872	*					IIIIA6910
000873	*	TRANSPORT ORBITER TO MAINTENANCE				IIIIA6920
000874	*					IDST IIIIA6930
000875	*	LOGNORMAL	MEAN	STDDEV		IIIIA6940
000876	*	K3	K50	K100		IIIIA6950
000877	191	HELP			K150 X10	IIIIA6960
000878	192	ADVANCE			1 FN1	IIIIA6970
000879	*					IIIIA6980
000880	*					IIIIA7000
000881	*					IIIIA7010
000882	*					IDST IIIIA7020
000883	*	ORBITER MAINTENANCE				IIIIA7030
000884	*					IIIIA7040
000885	193	QUEUE	11		194	IIIIA7050
000886	194	ENTER	11		195	IIIIC1915
000887	*	TRIANGULAR	MIN	MODE	K2750 X10	IIIIA7070
000888	195	HELP	K3	K2250 K2500	196	IIIIA7080
000889	196	ADVANCE			25 199 197 1 FN1	IIIAT090
000890	*					IDST IIIAT100
000891	*	ORBITER ADDITIONAL MAINTENANCE				IIIAT110
000892	*					IIIIC1916
000893	197	EXPONENTIAL	MIN	MEAN	K1000	IIIAT130
000894	*	HELP	K8	K500	198	X10

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000895	198	ADVANCE				199	1	FN1
000896	199	LEAVE	11			200		IIIA7140
000897	*	-----						IIIA7150
000898	*	-----						IIIA7160
000899	*	-----						IIIA7170
000900	*	-----						IIIA7180
000901	*	TRANSPORT ORBITER TO SYSTEMS TEST, TEST, TRANSPORT TO STORAGE					IDST	IIIA7190
000902	*	ORBITER VEHICLE SYSTEM TEST FACILITY						IIIA7200
000903	*	-----						IIIA7210
000904	200	QUEUE	12			201		IIIA7220
000905	201	ENTER	12			202		IIIA7230
000906	202	HELP	K3	K1900	K2000	203	K2100 X10	IIIA7240
000907	203	ADVANCE				204	1	FN1
000908	204	LEAVE	12			205		IIIA7260
000909	*	-----						IIIA7270
000910	*	ORBITER STORAGE WHEN WAITING FOR BOOSTER OR LAUNCH REQUIREMENT						IIIA7280
000911	*	-----						IIIA7290
000912	205	ENTER	13	K1		206		IIIA7300
000913	206	HELP	K5	K2	C1	207		IIIA7310
000914	207	TABULATE	21			208		IIIA7320
000915	208	TABULATE	23			209		IIIA7330
000916	209	TERMINATE						IIIA7340
000917	*	-----						IIIA7350
000918	*	-----						IIIA7360
000919	*	-----						IIIA7370
000920	*	-----						IIIA7380
000921	*	VEHICLE REMOVAL PATH						IIIC1920
000922	*	ONLY VEHICLES WHICH ARE TO BE REMOVED FROM THE PAD FLOW						IIIC1930
000923	*	THROUGH THIS SECTION.						IIIC1940
000924	*	-----						IIIC1950
000925	*	-----						IIIC1960
000926	*	REMOVE BOOSTER, ORBITER AND LUT FROM THE PAD						IIIC1970
000927	*	-----					IDST	IIIC1980
000928	210	ENTER	25			211		IIIC1990
000929	*	TRIANGULAR	MIN MODE					IIIC2000
000930	211	HELP	K3	K1800	K2000	212	MAX K2200 X10	IIIC2D10
000931	212	ADVANCE				213	1 FN1	IIIC2020
000932	213	LEAVE	25					IIIC2040
000933	214	RELEASE	*9			215		IIIC2050
000934	*	-----						IIIC2060
000935	*	-----						IIIC2070
000936	*	-----						IIIC2080
000937	*	-----						IIIC2090
000938	*	TRANSPORT VEHICLE, SEPARATE ORBITER, TRANSPORT ORBITER TO MAINT IDST						IIIC2100
000939	*	-----						IIIC2110
000940	215	ENTER	30			216	MAX	IIIC2120
000941	*	TRIANGULAR	MIN MODE					IIIC2130
000942	216	HELP	K3	K550	K750	217	K950 X10	IIIC2140
000943	217	ADVANCE				218	1 FN1	IIIC2150
000944	218	LEAVE	30			219		IIIC2160
000945	*	-----						IIIC2170
000946	*	-----						IIIC2180
000947	*	-----						IIIC2190
000948	*	-----						IIIC2200
000949	*	-----						IIIC2210
000950	*	SEPARATE ORBITER FROM BOOSTER/LUT AND SEND ORBITER TO MAINTENANCE						IIIC2220

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000951	*	219	SPLIT		220	237		I1IC2230
000952	*							I1IC2240
000953	*							I1IC2250
000954	*							I1IC2260
000955	*							I1IC2270
000956	*							I1IC2280
000957	*							I1IC2290
000958	*	SEPARATE BOOSTER FROM LUT • TRANSPORT BOOSTER TO MAINTENANCE			IDST	I1IC2300		
000959	220	ENTER	19		221			I1IC2310
000960	221	HELP	K3	K550	K750	222	K950 X10	I1IC2320
000961	222	ADVANCE				223	1 EN1	I1IC2330
000962	223	LEAVE	19			224		I1IC2340
000963	224	SPLIT			225	130		I1IC2350
000964	*	• BOOSTER MAINTENANCE ON RETURN FROM PAD						I1IA7400
000965	225	QUEUE	2		226			I1IA7410
000966	226	ENTER	2		227			I1IA7420
000967	*	EXponential	MIN	MEAN				I1IC2361
000968	*	EXPONENTIAL	K8	K500	K7500	228	X10	I1IA7440
000969	227	HELP				229	1 FN1	I1IA7450
000970	228	ADVANCE			230			I1IA7460
000971	229	LEAVE	2					I1IA7470
000972	*							I1IA7480
000973	*							I1IA7490
000974	*							I1IA7500
000975	*	• BOOSTER VEHICLE SYSTEM TEST FACILITY ON RETURN FROM PAD			IDST	I1IA7510		
000976	230	QUEUE	3		231			I1IA7520
000977	231	ENTER	3	MIN	NOM	232		I1IA7530
000978	*							I1IA7540
000979	*							I1IA7550
000980	232	HELP	K3	K1900	K2000	233	K2100 X10	I1IA7560
000981	233	ADVANCE				234	1 EN1	I1IA7570
000982	234	LEAVE	3			235		I1IA7580
000983	235	ENTER	4	K1		236		I1IA7590
000984	236	HELP	K5	K1	C1	260		I1IA7600
000985	*							I1IA7610
000986	*							I1IA7620
000987	*	• ORBITER MAINTENANCE ON RETURN FROM PAD						I1IA7630
000988	237	QUEUE	11		238			I1IA7640
000989	238	ENTER	11		239			I1IA7650
000990	*	EXponential	MIN	MEAN				I1IA7660
000991	*	EXPONENTIAL	K8	K500	K7500	240	X10	I1IC2362
000992	*	HELP				241	1 FN1	I1IA7680
000993	239	ADVANCE				242		I1IA7690
000994	240	LEAVE	11					I1IA7700
000995	*							I1IA7710
000996	*							I1IA7720
000997	*							I1IA7730
000998	*							I1IA7740
000999	*	• ORBITER VEHICLE SYS TEST FACILITY ON RETURN FROM PAD			IDST	I1IA7750		
001000	242	QUEUE	12		243			I1IA7760
001001	243	ENTER	12		244			I1IA7770
001002	*	MIN NOM						I1IA7780
001003	*							I1IA7790
001004	244	HELP	K3	K1900	K2000	245	K2100 X10	I1IA7800
001005	245	ADVANCE				246	1 FN1	I1IA7810
001006	246	LEAVE	12			247		I1IA7810

001007	247	ENTER	13			248	
001008	248	HELP	K5	K2	C1	249	
001009	249	TERMINATE					
001010	*						
001011	*						
001012	*						
001013	*	COUNT NUMBER OF LAUNCHES MISSED BECAUSE OF UNAVAILABILITY OF A BOOSTER AND/OR ORBITER AND/OR LUT					
001014	*						
001015	*						
001016	*						
001017	250	SAVEX	5+	K1	BOTH	251	255
001018	251	GATE	SE4		BOTH	252	254
001019	252	GATE	SEL3			253	
001020	*	NO BOOSTER OR ORBITER AVAILABLE					
001021	*						
001022	*						
001023	253	SAVEX	2+	K1		260	
001024	*	NO BOOSTER AVAILABLE					
001025	*						
001026	*						
001027	254	SAVEX	3+	K1		260	
001028	*	EITHER NO ORBITER OR NO LUT OR BOTH					
001029	*						
001030	*						
001031	*						
001032	255	SAVEX	7+	K1	BOTH	256	258
001033	256	GATE	SEL3			257	
001034	*	NO ORBITER AVAILABLE					
001035	*						
001036	*						
001037	257	SAVEX	4+	K1		260	
001038	*	NO LUT AVAILABLE WHEN HARDWARE IS AVAILABLE					
001039	*						
001040	*						
001041	*						
001042	*	COUNT NUMBER OF MISSED LAUNCHES PAUL(S) UNAVAILABLE					
001043	*						
001044	258	SAVEX	8+	K1		260	
001045	*						
001046	*						
001047	*						
001048	*	INSERT HELP CARDS IN THIS BLOCK TO REQUEST CONFIDENCE INTERVALS.					
001049	*	THESE ARE THE FIVE DUMMY ADVANCE CARDS USED AS PLACE HOLDERS AND					
001050	*	ARE REPLACED BY HELP CARDS WHEN REQUESTING CONFIDENCE INTERVALS.					
001051	*						
001052	260	ADVANCE				261	
001053	261	ADVANCE				262	
001054	262	ADVANCE				263	
001055	263	ADVANCE				264	
001056	264	ADVANCE				265	
001057	*						
001058	*						
001059	*						
001060	265	COMPARE	N276	LE	V10	BOTH	266
001061	265	COMPARE	V10	E	N276		276
001062	*						

## 001063 \* PRINT OUT SUMMARY TABLE

001064	*	267	HELP	K10		268		TB10	ST14	I11A8230
001065	*	268	HELP	K10	TB1	269	TB2	T822	QX2	I11A8250
001066	*	269	HELP	K10	QX1	270	QX2	QX11	QX1	I11A8260
001067	*	270	HELP	K10	QX3	271	QX20	QX18	I11B1632	I11B1636
001068	*	271	HELP	K10	QX21	272	SP2	SR11	I11A8280	I11A8290
001069	*	272	HELP	K10	SR1	273		I11A8300	I11A8310	I11A8320
001070	*	273	HELP	K10	SR3	274		I11A8310	I11A8320	I11A8330
001071	*	274	HELP	K10	SR20	275	FR3	I11B1640	I11B1650	I11B1660
001072	*	275	HELP	K10	ER1	276		I11B1670	I11B1680	I11B1690
001073	*	276	TERMINATE	R				I11B1700	I11B1710	I11C2380
001074	*	277	TERMINATE	R				I11B1710	I11B1720	I11C2390
001075	*	278	TERMINATE	R				I11B1720	I11B1730	I11C2400
001076	*	279	TERMINATE	R				I11B1730	I11B1740	I11C2410
001077	*	280	TERMINATE	R				I11B1740	I11B1750	I11C2420
001078	*	281	1 - TIME FROM LANDING TO STORAGE ENTRY (BOOSTER)					I11B1750	I11B1760	I11C2430
001080	*	282	2 - STORAGE TIME (BOOSTER)					I11B1760	I11B1770	I11C2440
001081	*	283	3 - GROUND PROCESSING TIME (BOOSTER)					I11B1770	I11B1780	I11C2450
001082	*	284	4 - FLOATING HOLD TIME BETWEEN COMPLETION OF ALL PRECOUNTDOWN OPERATIONS AND THE INITIATION OF FINAL COUNTDOWN FOR THE FIRST WINDOW					I11B1780	I11B1790	I11C2460
001083	*	285	5 - FLOATING HOLD TIME BETWEEN COMPLETION OF ALL PRECOUNTDOWN OPERATIONS AND THE INITIATION OF FINAL COUNTDOWN FOR ALL WINDOWS SUBSEQUENT TO THE FIRST					I11B1790	I11B1800	I11C2470
001084	*	286	6 - THE AMOUNT OF TIME A SUCCESSFUL REQUEST SPENT WAITING FOR VEHICLE ELEMENTS.					I11B1800	I11B1810	I11C2480
001085	*	287	7 - THE AMOUNT OF TIME LEFT TO THE FIRST LAUNCH WINDOW • NEGATIVE VALUES IN THE TABLE INDICATE THE AMOUNT OF TIME PAST THE WINDOW					I11B1810	I11B1820	I11C2490
001086	*	288	8 - THE PROGRAM IS AT					I11B1820	I11B1830	I11C2490
001087	*	289	9 - INDICATES THE NUMBER OF LAUNCHES AT EACH WINDOW					I11B1830	I11B1840	I11C2490
001088	*	290	10 - ELAPSED TIME OF VEHICLE ELEMENTS FROM THEIR STORAGE EXIT TO THEIR LIFTOFF					I11B1840	I11B1850	I11C2490
001089	*	291	THEIR LIFTOFF					I11B1850	I11B1860	I11C2490
001090	*	292	THE PROGRAM IS AT					I11B1860	I11B1870	I11C2490
001091	*	293	8 - AMOUNT OF TIME AFTER PRIMARY WINDOW LAUNCH OCCURRED AT					I11B1870	I11B1880	I11C2490
001092	*	294	9 - INDICATES THE NUMBER OF LAUNCHES AT EACH WINDOW					I11B1880	I11B1890	I11C2490
001093	*	295	10 - ELAPSED TIME OF VEHICLE ELEMENTS FROM THEIR STORAGE EXIT TO THEIR LIFTOFF					I11B1890	I11B1900	I11C2490
001094	*	296	THEIR LIFTOFF					I11B1900	I11B1910	I11C2490
001095	*	297	THEIR LIFTOFF					I11B1910	I11B1920	I11C2490
001096	*	298	THEIR LIFTOFF					I11B1920	I11B1930	I11C2490
001097	*	299	21 - TIME FROM LANDING TO STORAGE ENTRY (ORBITER)					I11B1930	I11B1940	I11C2490
001098	*	300	22 - STORAGE TIME (ORBITER)					I11B1940	I11B1950	I11C2490
001099	*	301	23 - GROUND PROCESSING TIME (ORBITER)					I11B1950	I11B1960	I11C2490
001100	*	302	24 - GROUND PROCESSING TIME (ORBITER)					I11B1960	I11B1970	I11C2490
001101	*	303	25 - GROUND PROCESSING TIME (ORBITER)					I11B1970	I11B1980	I11C2490
001102	*	304	26 - GROUND PROCESSING TIME (ORBITER)					I11B1980	I11B1990	I11C2490
001103	*	305	27 - GROUND PROCESSING TIME (ORBITER)					I11B1990	I11B2000	I11C2490
001104	*	306	28 - GROUND PROCESSING TIME (ORBITER)					I11B2000	I11B2010	I11C2490
001105	*	307	29 - GROUND PROCESSING TIME (ORBITER)					I11B2010	I11B2020	I11C2490
001106	*	308	30 - GROUND PROCESSING TIME (ORBITER)					I11B2020	I11B2030	I11C2490
001107	*	309	31 - GROUND PROCESSING TIME (ORBITER)					I11B2030	I11B2040	I11C2490
001108	*	310	32 - GROUND PROCESSING TIME (ORBITER)					I11B2040	I11B2050	I11C2490
001109	*	311	33 - GROUND PROCESSING TIME (ORBITER)					I11B2050	I11B2060	I11C2490
001110	*	312	34 - GROUND PROCESSING TIME (ORBITER)					I11B2060	I11B2070	I11C2490
001111	1	313	TABLE	MP8	5000	5000	20	I11A8340	I11A8350	I11A8360
001112	2	314	TABLE	X10	500	500	30	I11A8350	I11A8360	I11A8370
001113	3	315	TABLE	V1	9000	500	30	I11A8360	I11A8370	I11C2500
001114	4	316	TABLE	X10	000	100	30	I11A8370	I11C2500	I11C2510
001115	5	317	TABLE	X10	000	100	30	I11C2500	I11C2520	I11C2530
001116	6	318	TABLE	M1	000	100	70	I11C2510	I11C2520	I11C2530
001117	7	319	TABLE	X10	-5000	100	55	I11C2520	I11C2530	I11C2530
001118	8	320	TABLE	X35	000	100	50	I11C2530	I11C2530	I11C2530

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## APPENDIX B. SUPPLEMENTAL FORTRAN INSTRUCTIONS DESCRIPTION AND LISTING

As the SOS Model evolved, it became apparent that additional Fortran subprograms were required to supplement the basic instructions provided by the standard GPSS II language. These subprograms, which are referred to as the user written routines, are utilized during the dynamic simulation of the Shuttle operations cycle by means of the GPSS II HELP block. The subprograms utilized in the SOS Model are listed after the descriptions in this Appendix. The function of the Fortran subprogram HELP is described below:

- HELP serves as the interfacing routine between the GPSS II instructions and the user written subprograms. The HELP subprogram is accessed by a GPSS II HELP block containing a control variable located in the X field. The HELP subprogram serves four general functions in support of the SOS Model: 1. generating random deviates from the available probability distribution; 2. collecting statistics on the time of stage storage; 3. transferring control to other special purpose subprograms; 4. providing scheduling data for each launch. A description of each segment of subprogram HELP is shown in Table B-I. Transfer to the segments from within the HELP subprogram is accomplished by utilizing the control variable in a Fortran computed GO TO statement and selecting the proper HELP segment.

The subprograms described below are responsible for the generation of the random numbers used in the user written subprograms.

- DRAND and DRAND1 serve as two independent random number generators. The random number generation is accomplished by modulo division. The random number seeds for these two subprograms are defined by variables ISEED and ISEED1, respectively. (No support routines called.)

The following subprograms are used in determining deviates from various statistical distributions to be used by the GPSS II instructions to accurately simulate the Shuttle operations cycle.

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TABLE B-I. SUBPROGRAM HELP SEGMENT DESCRIPTION

Segment	Description
1	Generates the attributes of the next launch including mission type, time between launches, Orbiter mission length, and the time between the first and second launch opportunity. (Support routine called: MISSON.)
2	Calls a special purpose subprogram that prepares information obtained from GPSS II system variables for use in the Confidence Interval Option. (Support routine called: DUMMY.)
3	Generates the deviates from a triangular distribution. (Support routine called: TRIAG1.)
4	Generates the deviates from a normal distribution. (Support routine called: RNORM.)
5	Saves the clock time when a stage has completed processing and has entered storage. (No support routine called.)
6	Computes the elapsed time a stage has spent in storage based on a first in first out basis. (No support routines called.)
7	Prepares the model for a new case study by reading the input variables and the comment card title. (No support routines called.)
8	Generates the deviates for a two-parameter exponential distribution. (Support routine called: EXPO.)
9	Generates the deviates for a lognormal distribution. (Support routine called: RLOGN.)
10	Outputs the summary table. Repeated calls are required to complete the entire table. (Support routine called: PRINT.)
11	Generates the deviates for a constant distribution. (No support routines called.)
12	Generates the deviates for a uniform distribution. (Support routine called: UNFRM1.)
13	Generates the deviates for a beta distribution. (Support routines called: BETADP and PERTXF.)

- BETADP generates the deviates for a beta distribution.  
(Support routines called: GAM and PERTXF.)
- DICRET produces deviates from a discrete probability distribution. This subprogram permits the model to generate random values from data that has either a 1/3 or 1/2 probability of selection. (Support routine called: DRAND.)
- EXPO generates the deviates for a two parameter exponential distribution. (Support routine called: DRAND1.)
- GAM generates the deviates for a gamma distribution.  
(Support routine called: DRAND1.)
- PERTXF converts three input parameters, namely the minimum expected time, the most likely expected time and the maximum expected time to the mean and standard deviation of a beta distribution. (No support routines called.)
- RLOGN calculates the deviates for a lognormal distribution by exponentiating the normal deviate. The mean and standard deviation of the lognormal distribution are obtained from the calling subprogram. (Support routine called: RNORM.)
- RNORM calculates the deviates for a normal distribution. The mean and standard deviation of the routine are obtained from the calling subprogram. (Support routine called: DRAND1.)
- TRIAG and TRIAG1 produce the random deviates for a triangular distribution function. These two routines are identical and independent. (Support routines called: DRAND and DRAND1, respectively.)
- UNFRM and UNFRM1 produce random deviates from a uniform distribution. The two routines are identical and independent. (Support routines called: DRAND and DRAND1, respectively.)

It should be noted that subprograms DRAND, TRIAG, and UNFRM are used exclusively by the MISSON subprogram to provide a separate and unique sequence of random numbers.

The subprogram described below is responsible for scheduling the Shuttle launches.

- MISSON is responsible for determining the parameters associated with each Shuttle launch. MISSON is used to

determine a realistic time between launches for the Shuttle system. For each launch, the mission type is defined with the possible types including Shuttle payload placement, space station logistics, tug placement and fuel supplies, Department of Defense, and others, including space rescue. The MISSON subprogram also determines the Orbiter mission length which depends on mission type, the date of the next launch, and the time between the first and second launch opportunity. (Support routines called: DICRET, TRIAG, UNFRM.)

The following subprograms are not active during the dynamic simulation of the Shuttle operations cycle, but were developed for the convenience of the user. These subprograms are used to produce the TABLE1 output which summarizes the activity time distributions defined in the System Model Description of the SOS Model.

- OUTPUT determines the type of distribution for each Shuttle processing event and outputs this information in tabular form. (Support routine called: REALN).
- REALN converts alphanumeric data into the real data used by the OUTPUT routine. (No support routines called.)
- TABLE1 scans the System Model Description for the titles of the various processing operations and for their associated time distributional parameters. (Support routine called: OUTPUT.)

The following subprograms are used when confidence intervals are requested for specific statistics generated during the dynamic simulation of the Shuttle operations cycle. Reference 3 gives detailed information on the Confidence Interval Option.

- DUMMY controls the sampling rate used in obtaining statistical observations for those statistics specified by the Confidence Interval Option. The subprogram also assures the proper collection of the statistics specified by the user. (Support routine called: SAMPLE.)
- SAMPLE makes statistical observations during the simulation on the statistics specified by the user to have confidence intervals calculated for them. At the conclusion of the simulation, a summary table is outputted that contains a descriptive heading and a corresponding confidence interval for each of the statistics specified by the user to be collected. (Support routine called: STDV.)

- STAT is used to read and store descriptive headings to be used in the output of confidence interval statistics. Each card of the System Model Description is scanned for the appropriate headings. This subprogram is not active during the actual simulation. (No support routines called.)
- STDV calculates the sample standard deviation for the statistics specified for confidence interval calculations. (No support routines called.)

The subprogram described below is responsible for a summary output of the statistics collected during the simulation of the Shuttle operations cycle.

- PRINT is a collection of various write statements which print out a summary table of various simulation parameters at the end of each computer run. The values of these parameters are transmitted to the routine through two different transfer methods. The first method transfers the values of certain GPSS II system variables (table means, facility utilization and queue times) to PRINT as arguments of the subroutine. These arguments are defined on the HELP blocks at the end of the model. The other method permits the user to retrieve the output parameters through the values stored in the GPSS II common block variables. These tables are subscripted arrays and are defined in the GPSS II reference manual. The routine is executed by a series of call statements that subsequently execute each statement of the subprogram. (Support routine called: SAMPLE.)

The GPSS II Mainline (GPSS2) routine is the only GPSS II symbolic element deck available for modification by the SOS Model user. It serves as the mainline master control for the complete GPSS II program. The GPSS2 routine is a software package available upon request from the operators of the UNIVAC 1108 EXEC VIII System. The routine is described as follows:

- GPSS2 contains the option to specify the size of the network and its associated variables by means of the Fortran parameter statements contained within the routine. The total program core size is determined by the limits of the model description as defined by the values assigned to the Fortran parameter statements. Complete instructions and other information on making changes is contained in the comments of the routine listing. (Major GPSS II routines USES, BLOCKD, SETERR, INPROC, EXECUT, PUTOFF,

ASSEMB; other support routines called: RCONWN, CSFREQ,  
LETTER, STAT, and TABLE1.)

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1

```
BETADP  
420223*TPFS*  
1      FUNCTION BETADP(J,SMEAN,SVAR)  
2      COMMON /HEPL/ PARA(17,3),LL,ISEED,ISTORE(2,10),IS(2)  
3      A = SMEAN  
4      B = SVAR  
5      X = GAM(A)  
6      BETADP=X*(X+GA(3))  
7      BETADP=BETADP*(PARA(J,3)-PARA(J,2))+PARA(J,2)  
8      RETURN  
9      END
```

GHOS,P DICRET

SPRT,S DICRET  
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420223•TPFS•DCRET DATE 063072 PAGE 1

```
1      FUNCTION DICRET(JP)
2      COMMON /HEPL/PARAM(7,3),LL,ISEED,ISTED1,ISTED2
3      RNUM=DRAND(ISEED)
4      IF (PARAM(JP,2)*5.0+0.15) TO 20
5      IF (RNUM.GE.0.4666160) TO 15
6      IF (RNUM.GE.0.3333) GO TO 10
7      DICRET=PARAM(JP,1)
8      RETURN
9      10 DICRET=PARAM(JP,2)
10     RETURN
11     15 DICRET=PARAM(JP,3)
12     RETURN
13     20 IF (RNUM.LE.0.5) GO TO 30
14     DICRET=PARAM(JP,3)
15     RETURN
16     30 DICRET=PARAM(JP,1)
17     RETURN
18     END
```

END, P DRAND

10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31

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DRAND1

42U223•TPFS•DRAND1

FUNCTION DRAND1(NRI)

2 NRI=NRI•316231

3 IF (NRI)5,5,6

4 5 NRI=NRI+34359738167

6 R=NRI

7 DRAND1RN/343597384•E2

8 RETURN

END

@HDG,P DUMMY

@PRT,S DUMMY

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DUMMY

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420223*TPFS.DUMMY
1      SUBROUTINE DUMMY(K1,K2,K3,K4,K5)
2      COMMON/STAT2/NFLTS
3      COMMON/STAT3/ISN
4      COMMON/EKSES/JEKS(11)
5      COMMON/NODE,JN4L1

6      C      NENTR DETERMINES THE NUMBER OF TERMINATED SIMULATIONS
7      C      NENTR=NTH2U(JN4(276))+2
8      C      DETERMINE IF 100 SIMULATIONS HAVE BEEN COMPLETED
9      C      IF NOT, RETURN
10     C      DETERMINE IF 100 OR MORE FLIGHTS (IN INCREMENTS OF 50 FLIGHTS)
11     C      HAVE OCCURRED
12     C      IF NOT, RETURN
13     C      IF (NENTR>100) RETURN
14     C      DETERMINE IF 100 OR MORE FLIGHTS (IN INCREMENTS OF 50 FLIGHTS)
15     C      HAVE OCCURRED
16     C      IF NOT, RETURN
17     C      IF (NODNNIR>0) RETURN
18     C
19     C
20     C      NFLTS DETERMINES THE NUMBER OF SIMULATIONS THAT HAVE BEEN
21     C      COMPLETED
22     C      NFLTS=JEKS(12)+JEKS(13)+JEKS(14)+JEKS(19)+JEKS(22)+JEKS(23)+JEKS(24)
23
24     1 +JEKS(25)+JEKS(3G)
B      25     C
25     C
26     C      DETERMINE IF THE STATISTICAL IDENTIFICATION NUMBER IS LEGAL
27     C      IF NOT, RETURN
28     C      IF (K2.LT.0.OR.K2.GT.5) RETURN
29
30     C
31     C      IF OPTION 1 HAS BEEN SPECIFIED, IDENTIFY THE MAXIMUM NUMBER
32     C      OF STATISTICS TO BE COLLECTED
33     C      IF (K2.EQ.0).ISNA9
34     C
35     C      DETERMINE THE CONFIDENCE INTERVAL IDENTIFICATION NUMBER
36     C      IF (K2>2)2,1,1
37     C
38     C
39     C      IF OPTION 1 HAS BEEN REQUESTED, COLLECT STATISTICS FOR THE OPERATION
40     C      EVALUATION PARAMETERS
41     2 K2LK2
42     K3TK3
43     K4TK4
44     K5TK5
45     K2L1
46     K3L1
47     K4L1
48     K5L1
49     CALL SAMPLE(K1,K2,K3,K4,K5)
50     C
51     K2=2
52     K4=NFLTS-JEKS(30)
53     CALL SAMPLE(K1,K2,K3,K4,K5)
54     C
55     K2=3

```

```

56      K4=JEKS(26)
57      CALL SAMPLE(K1,K2,K3,K4,K5)          DUMY 560
58      C                                     DUMY 570
59      C                                     DUMY 580
60      K2=B4
61      K4=JEKS(31)
62      C                                     DUMY 590
63      K2=B5
64      K4=JEKS(4)
65      C                                     DUMY 600
66      C                                     DUMY 610
67      K2=B6
68      K4=JEKS(2)
69      CALL SAMPLE(K1,K2,K3,K4,K5)          DUMY 620
70      C                                     DUMY 630
71      K2=B7
72      K4=JEKS(8)
73      CALL SAMPLE(K1,K2,K3,K4,K5)          DUMY 640
74      C                                     DUMY 650
75      K2=B8
76      K4=JEKS(25)
77      CALL SAMPLE(K1,K2,K3,K4,K5)          DUMY 660
78      C                                     DUMY 670
79      K2=B9
80      K4=JEKS(22)+JEKS(23)+JEKS(24)
81      CALL SAMPLE(K1,K2,K3,K4,K5)          DUMY 680
82      C                                     DUMY 690
83      C                                     DUMY 700
84      IF(K2>EQ.0) RETURN
85      C                                     DUMY 710
86      C                                     DUMY 720
87      K2=B10
88      K3=K3T
89      K4=K4T
90      K5=K5T
91      CALL SAMPLE(K1,K2,K3,K4,K5)
92      RETURN
93      C                                     DUMY 730
94      C                                     DUMY 740
95      C                                     DUMY 750
96      K2=B2+9
97      CALL SAMPLE(K1,K2,K3,K4,K5)
98      RETURN
99      END

```

SHDG,P EXPO

BPR,T,S EXPO  
FURPUR/HAI8-06/30-13:31

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```
420225TPFS.EXPO
1      FUNCTION EXP0(J)
2      COMMON /HEPL/ PARAM(7,3) TLL, ISEED1, ISEED2, ISTORE(2,10), IS(2)
3      RNUM=DRAND1(ISEED1)
4      EXP0=PARAM(J,1)-PARAM(J,2)*ALOG(RNUM)
5      RETURN
6      END
```

```
@HUG, P      GAM
```

```
  @PR1,S      GAM
  FURPUR HA18-06/30-13:31
```

```

GAM
420223•TPFS•GAM
      !           FUNCTION GAM(ALPHA)
      2             K = ALPHA
      3             FK = K
      4             GAM = 0.
      5             IELK17A7.B
      6             8   IF(K.GT.20) GO TO 30
      7             PROD = 1.0
      8             DO 10 I=1,K
      9             10   PROD = PROD*DRAND((ISEED))
     10             GAM = -ALOG( PROD )
     11             7   D = ALPHA-FK
     12             IF(D-.015/12.12.11
     13             11   IF(D-.985/13.20.20
     14             20   N = 1.0
     15             15   GO TO 22
     16             13   A = 1.0/9
     17             17   B = 1.0/11.-D
     18             14   X = DRAND((ISEED))**A
     19             19   Y = DRAND((ISEED))**B+X
     20             20   IF(Y-1.0/15.15.14
     21             15   N = X/Y
     22             22   Y = -ALOG(DRAND((ISEED)))
     23             23   GAM = GAM+Y
     24             12   RETURN
     25             30   GAM = ALPHA
     26             26   RETURN
     27             27   END

```

QHDF,P GPSS2

GPRT,S GPSS2  
FURPUR HA18-06/30-13:31

420223\*1PFS.GPSS2

```

1   C   GPSS 11      VERSION F      LEVEL 3
2   C
3   C   THE GENERAL PURPOSE SYSTEMS SIMULATOR 11 FINAL USER MANUAL IS
4   C   UP-4129, AND THE FINAL GPSS 11 CODING FORM IS UP-431, BOTH
5   C   OBTAINABLE FROM HOLYoke, MASS., VIA A SALES HELP REQUISITION
6   C   THROUGH THE LOCAL UNIVAC MANAGER.
7   C
8   C   * * * * * THE FOLLOWING NOTES ARE INTENDED TO SUPPLEMENT OR
9   C   UPDATE INFORMATION PRESENTED IN THE GPSS USER MANUAL. * * * * *
10  C
11  C   1. EACH TIME AN OVERLAY OCCURS, A WARNING TO THIS EFFECT
12  C   IS PRINTED, BUT EXECUTION IS NOT INHIBITED.
13  C   2. IF JOHTAPE AND WRITAP ARE USED THE NUMBER OF TRANS-
14  C   ACTIONS ON TAPE MUST BE AT LEAST ONE GREATER THAN
15  C   THE NUMBER REQUIRED FOR THE EXECUTION OF THE JOB.
16  C   3. EXECUTION USING XQT MAPGP5 RESULTS IN A SEGMENTATION
17  C   OF GPSS 11.
18  C   4. THE STANDARD UPPER LIMITS OF FIELDS GIVEN IN APPENDIX 3
19  C   OF THE GPSS USER MANUAL MAY BE CHANGED. THE METHOD FOR
20  C   MAKING SUCH CHANGES HAS BEEN REVISED. SEE NOTE 7 FOR AN
21  C   EXPLANATION.
22  C   5. THE EXECUTIVE COMMAND, SSETC 2, WILL CAUSE AN ASSEMBLED
23  C   DECK TO BE PUNCHED OUT.
24  C   6. UPON DETECTION OF AN END COMMAND, ALL JOBTAPES WHICH WERE
25  C   REFERENCED BY A WRITE BLOCK WILL HAVE AN END-OF-FILE PLACED
26  C   ON THEM. READING OF THESE TAPES WILL NOT OCCUR.
27  C
28  C   7. THE METHOD USED TO CHANGE TABLE SIZES FOR THIS
29  C   VERSION IS TO CHANGE THE VALUES GIVEN IN THE
30  C   FORTRAN PARAMETER STATEMENTS WHICH FOLLOW. THE
31  C   TABLE TYPE REFERRED TO BY A FORTRAN PARAMETER
32  C   STATEMENT IS GIVEN IN THE LINE PRECEDING THAT
33  C   STATEMENT.
34  C
35  C
36  C   C**HLUCKS      PARAMETER HMAX = 400
37  C
38  C   C**STORAGES    PARAMETER NSMAX = 50
39  C   C**FACILITIES  PARAMETER NMMAX = 15
40  C
41  C
42  C   C**STOREGSES  PARAMETER NSMAX = 50
43  C
44  C   C**QUEUES      PARAMETER NMMAX = 50
45  C
46  C
47  C   C**USER CHAINS  PARAMETER NUCMAX = 1
48  C   C**LOGIC SWITCHES PARAMETER NLSMAX = 25
49  C
50  C   C**USER CHAINS  PARAMETER NSCH = 1
51  C   C**LOGIC SWITCHES PARAMETER NLSMAX = 25
52  C
53  C   C**SAVEX LOCATIONS PARAMETER NSLMAX = 50
54  C
55  C

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56      C
57      C* FUNCTIONS
58      PARAMETER NFMAX = 10
59      C
60      C* TABLES AND QTABLES (COMBINED TOTAL)
61      PARAMETER NQMAX = 30
62      C
63      C* VARIABLE STATEMENTS
64      PARAMETER NVMAX = 30
65      C
66      C* COMMON CORE AREA
67      PARAMETER NCNMAX = 4500
68      C
69      C* TRANSACTIONS IMAXIMUM ALLOWED IN SYSTEM AT ANY GIVEN TIME
70      PARAMETER NTMAX = 100
71      C
72      C* PARAMETERS PER TRANSACTION (MUST BE LESS THAN OR EQUAL TO 30)
73      PARAMETER NPRM=20
74      C******THE FOLLOWING CARDS ARE NOT TO BE DELETED, NOR CHANGED
75      C UNLESS SO NOTED IN COMMENT CARDS.*****.
76      PARAMETER NPRM=(NPRMAX+1)/2*2
77      A      NPX2 = NPRM/2-NPRM/4-NPRM/6-NPRM/10+NPRM/20-NPRM/22-NPRM/26
78      B      -NPRM/14+NPRM/20-NPRM/22-NPRM/26
79      C      +NPRM/28+NPRM/30 ,
80      D      NPX4 = NPRM/4-NPRM/8-NPRM/12-NPRM/20+NPRM/24-NPRM/28 ,
81      E      NPX6 = NPRM/6-NPRM/12-NPRM/18-NPRM/30 ,
82      F      NPX8 = NPRM/8-NPRM/6-NPRM/18-NPRM/30 ,
83      G      NPX10 = NPRM/10-NPRM/20-NPRM/30 ,
84      H      NP2 = NPX*NTMAX +1 -NPX2 ,
85      I      NP4 = NPX*NTMAX +1 -NPX4 ,
86      J      NP6 = NPX6*NTMAX +1 -NPX6 ,
87      K      PARAMETER NP8 = NPX8*NTMAX +1 -NPX8 ,
88      L      NP10 = NP10*NTMAX +1 -NPX10 ,
89      M      NP12 = (NPRM/12-NPRM/4)*NTMAX +1 -(NPRM/12-NPRM/24) ,
90      N      NP14 = (NPRM/14-NPRM/28)*NTMAX +1 -(NPRM/12-NPRM/24) ,
91      O      NP16 = (NPRM/16)*NTMAX +1 -NPRM/16 ,
92      P      NP18 = (NPRM/18)*NTMAX +1 -NPRM/18 ,
93      Q      NP20 = (NPRM/20)*NTMAX +1 -NPRM/20 ,
94      R      NP22 = (NPRM/22)*NTMAX +1 -NPRM/22 ,
95      S      NP24 = (NPRM/24)*NTMAX +1 -NPRM/24 ,
96      T      NP26 = (NPRM/26)*NTMAX +1 -NPRM/26 ,
97      U      NP28 = (NPRM/28)*NTMAX +1 -NPRM/28 ,
98      V      NP30 = (NPRM/30)*NTMAX +1 -NPRM/30
99      COMMON/NODE1/JN1(NBMAX)
100     COMMON/NODE2/JN2(NBMAX)
101     COMMON/NODE3/JN3(NBMAX)
102     COMMON/NODE4/JN4(NBMAX)
103     COMMON/NODE5/JN5(NBMAX)
104     COMMON/EQ1/JF1(NFMAX)
105     COMMON/EQ2/JF2(NFMAX)
106     COMMON/EQ3/JF3(NFMAX)
107     COMMON/EQ4/JF4(NFMAX)
108     COMMON/EQ5/JF5(NFMAX)
109     COMMON/EQ6/JF6(NFMAX)
110     COMMON/EQ7/JF7(NFMAX)
111     COMMON/STOR1/J51(NSMAX)

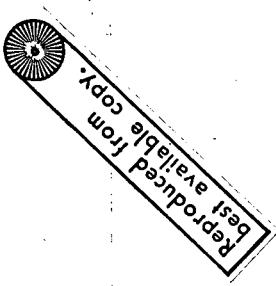
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112 COMMON/STOR2/J$2(N$MAX)
113 COMMON/STOR3/J$3(N$MAX)
114 COMMON/STOR4/J$4(N$MAX)
115 COMMON/STOR5/J$5(N$MAX)
116 COMMON/STOR6/J$6(N$MAX)
117 COMMON/STOR7/J$7(N$MAX)
118 COMMON/QUE1/J$1(N$MAX)
119 COMMON/QUE2/J$2(N$MAX)
120 COMMON/QUE3/J$3(N$MAX)
121 COMMON/QUE4/J$4(N$MAX)
122 COMMON/QUE5/J$5(N$MAX)
123 COMMON/QUE6/J$6(N$MAX)
124 COMMON/LOGIX/J$1(N$MAX)
125 COMMON/ESSES/JEKS(N$MAX)
126 COMMON/FN1/JYLOC$N$NMAX)
127 COMMON/FN2/JYLOC$N$NMAX)
128 COMMON/FN3/JYLOC$N$NMAX)
129 COMMON/TAB1/JYLOC$N$NMAX)
130 COMMON/TAB2/JTMODE(NT$MAX)
131 COMMON/TAB3/JT$MAX)
132 COMMON/TAB4/JTINS(NT$MAX)
133 COMMON/TAB5/JLASTH$MAX)
134 COMMON/TAB6/JTNUM(NT$MAX)
135 COMMON/TAB7/LARG$GEAX)
136 COMMON/TAB8/T$PRINTQMAX)
137 COMMON/TAB9/TWARG(NT$MAX)
138 COMMON/TAB10/T$SOUTGMAX)
139 COMMON/VAS/JVLOC$N$NMAX)
140 COMMON/WORDS/JWORD$INC$MAX)
141 COMMON/UCL/JU1(NUC$MAX)
142 COMMON/UCL2/JU2(NUC$MAX)
143 COMMON/UCL3/JU3(NUC$MAX)
144 COMMON/UCL4/JU4(NUC$MAX)
145 COMMON/UCL5/JU5(NUC$MAX)
146 COMMON/TRANDO/JTSTAT(NT$MAX)
147 COMMON/TRANZ/JDINT$MAX)
148 COMMON/TRAN2/JCHAN(NT$MAX)
149 COMMON/TRAN3/JMOVE(NT$MAX)
150 COMMON/TRAN4/JNWD$N$NMAX)
151 COMMON/TRAN5/JC1(NT$MAX)
152 COMMON/TRAN6/JC2(NT$MAX)
153 COMMON/TRAN7/JC3(NT$MAX)
154 COMMON/TRAN8/JC4(NT$MAX)
155 COMMON/TRAN9/JC5(NT$MAX)
156 COMMON/TRAN10/JC6(NT$MAX)
157 COMMON/TRAN12/JC7(NT$MAX)
158 COMMON/TRAN14/JC8(NT$MAX)
159 COMMON/TRAN16/JC9(NT$MAX)
160 COMMON/TRAN18/JC10(NT$MAX)
161 COMMON/TRAN20/JC11(NT$MAX)
162 COMMON/TRAN22/JC12(NT$MAX)
163 COMMON/TRAN24/JC13(NT$MAX)
164 COMMON/TRAN26/JC14(NT$MAX)
165 COMMON/TRAN28/JC15(NT$MAX)
166 COMMON/TRAN30/JC16(NT$MAX)
167 COMMON K1100)

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168 COMMON LPRT(128),LPRTG(128)  
 169 CURNON ICHAR(7),KTYPE(43),KGATE(112),KCONTR(7),KSV(50),  
 170 1 KCOP(6),KSELEC(7),LX(6)  
 171 COMMON/STAT3/IN  
 172 COMMON/STATS/HEAD  
 173 DIMENSION NHEAD(14,11)  
 174 DIMENSION FWORDS(11)  
 175 EQUIVALENCE (FWORDS(11),FWORDS(11))  
 176 EQUIVALENCE (K(1),KASYN),(K(2),KASYM2),(K(3),KNODES),(K(4),KEQS),  
 177 1 (K(5),KSTORS),(K(6),KQUES),(K(7),KVARS),(K(8),KLOGIX),  
 178 2 (K(9),KESES),(K(10),KENS),(K(11),KTABS),(K(12),KWORDS),  
 179 3 (K(13),KTANS),(K(14),KRAND),(K(15),KASMBL),(K(16),KIT),  
 180 USCH  
 181 EQUIVALENCE (K(17),KOT),(K(86),KUSER1),  
 182 EQUIVALENCE (K(79),KPARAM),(K(71),INDFLU),(K(72),INDEND),  
 183 1 (K(55),IFATAL),  
 184 C\*\*\*THE FOLLOWING NOTES PROVIDES TO THE USER OF THE MSFC-505 MODEL  
 185 C THE NECESSARY INFORMATION CONCERNING @SETC COMMAND CONTROL OPTIONS.  
 186 C 1. A @SETC 3 COMMAND PLACED BEFORE THE @XQT CONTROL CARD WILL  
 187 C ELIMINATE THE PRINTOUT OF THE MODEL LISTING. ONLY SUMMARY  
 188 C RESULTS AND STANDARD GPSS OUTPUT WILL BE PRINTED.  
 189 C 2. A @SETC 4 COMMAND PLACED BEFORE THE @XQT CONTROL CARD WILL  
 190 C GENERATE A TABLE CONTAINING THE DISTRIBUTION TIME PARAMETERS  
 191 C FOR THE DIFFERENT PROCESSING OPERATIONS.  
 192 C NOTE: THAT THE MODEL MUST BE ADDED TO THE RUN STREAM IN ORDER  
 193 C TO PRODUCE THIS OUTPUT TABLE.  
 194 C EXAMPLE DECK SET-UP:  
 195 C @SETC 4  
 196 C @XQT GPSSB.MAPGPS  
 197 C @ADD MODEL.  
 198 C @ADD MODEL.  
 199 C COMMENT CARD FOR CASE 1  
 200 C DATA CARD 1  
 201 C END  
 202 C 3. A @SETC 5 COMMAND PLACED BEFORE THE @XQT CONTROL CARD WILL  
 203 C DETERMINE THE HEADINGS TO BE USED IN THE CONFIDENCE INTERVAL  
 204 C STATISTICS COLLECTED BY THE MODEL. THIS COMMAND IS USED ONLY  
 205 C WHEN CONFIDENCE INTERVAL STATISTICS ARE DESIRED.  
 206 C NOTE: TO COLLECT THE HEADINGS TO BE ASSOCIATED WITH THE  
 207 C STATISTICS COLLECTED, THE MODEL MUST BE ADDED TO THE RUN STREAM.  
 208 C EXAMPLE DECK SET-UP:  
 209 C @XQT GPSSB.MAPGPS  
 210 C @ADD MODEL.  
 211 C COMMENT CARD FOR CASE 1  
 212 C DATA CARD 1  
 213 C END  
 214 C  
 215 DIMENSION ICTLCD(4),JCILCD(4),KCTLCD(4)  
 216 DATA ICTLCD/\*@ASG6\*,JCILCD/\*@ASG6\*,KCTLCD/\*@ASG6\*,  
 217 1 @BRKPT PRINT\$/\*DUMMY\*,@BRKPT PRINT\$/\*DUMMY\*,  
 218 2 @BRKPT PRINT\$/\*DUMMY\*,@BRKPT PRINT\$/\*DUMMY\*,  
 219 CALL RCOND(IMPRT)  
 220 NPRINT=IGETT2(IMPRT)  
 221 IF(NPRINT.EQ.4)CALL TABLE1  
 222 IF(NPRINT.EQ.5)CALL STAT  
 223 IF(NPRINT.NE.3)GO TO 5



```
224      CALL CSFREQ(1CTLCH)
225      CALL CSFREQ(LUCTLCC)
5  CALL USES
226      KPARAM = NPRM
227      KIT = 5
228      NKOT = 6
229      KRND = 1220703125
230      KNODES = NBMAX
231      KEQS = NFMAX
232      KSTORS = NSMAX
233      KQUES = HQMAX
234      KWORDS = NCNMAX
235      KVARS = NYMAX
236      KLLOGIX = NSLMAX
237      KEKSES = NSLMAX
238      KFNS = NFNMAX
239      KTABS = INTOMAX
240      KWORDS = NCNMAX
241      KTRANS = NTIMAX
USCH
242      KUSERS = NUCMAX
243      CALL CLOCKD
244      CALL SETERR
245      CALL JNPROC($20,$30)
10.      CALL JNPROC($20,$30)
20.      IF (INFLD • NE • 0) CALL FLOW
246      20. PERMIT EXECUTION OF A JOB WITH ILLEGAL INPUT CARDS, OR TO
247      C. PERMIT EXECUTION FOLLOWING A RESET OR CLEAR CARD WHERE A GPSS IS
B-19    248      C. ERROR HAS ALREADY OCCURRED, REMOVE THE FOLLOWING CARD
249      C. IF (IFATAL • NE • 0) GO TO 10
250      IF (LINDEN • NE • 0) GO TO 10
251      IF (LINDEN • NE • 0) GO TO 10
252      IF (INPRINT • NE • 3) GO TO 25
253      CALL CSFREQ(KCILCD)
254      CALL LETTER
255      25. CALL EXECUT
256      CALL POUT
257      60 TO 10
258      30. CALL ASSEMB
259      60 TO 10
260      END
```

GHDG,P HELP

@PRT'S HELP  
FURPUR HA18-06/30-13:31

```

4202233TPFS.HELP
      1   SUBROUTINE HELP(K1,K2,K3,K4,K5)           HELP_ 10
      2   COMMON /HEPL/PARAM(7,3),LL,ISED,IS(2)       HELP_ 20
      3   COMMON /HLPRT/IBOOS,NORBL,NLUTS,TITLE(20),NSEED,NSEDI
      4   COMMON /STAT/NCONF
      5   25  GO TO (1,2,3,4,5,6,7,8,9,10,11,12,13),K1    HELP_ 110
      6   C***GENERATE REQUIREMENTS FOR NEXT LAUNCH
      7   C
      8   C
      9   1 CONTINUE  CALL  MISSION(NP1,NP2,NP3,NP4,NP5,MODEL)  HELP_ 140
     10
     11   K2=NP1
     12   K3=NP2
     13   K4=NP3
     14   K5=NPS
     15   RETURN
     16   2 CONTINUE
     17   C***COLLECT STATISTICAL DATA FOR CONFIDENCE INTERVALS
     18
     19   C
     20   CALL DUMMY(K1,K2,K3,K4,K5)
     21   RETURN
     22   C
     23   C***GENERATE DEVIATE FOR TRIANGULAR DISTRIBUTION
     24   C
     25   3 PARAM(1,1)=K2
     26   PARAM(1,2)=K3
     27   PARAM(1,3)=K4
     28   K5=TRIAG(1)
     29   RETURN
     30   C
     31   C***GENERATE DEVIATE FOR NORMAL DISTRIBUTION
     32   C
     33   4 PARAM(1,1)=K2
     34   PARAM(1,2)=K3
     35   K4=RNORM(1)
     36   K5=K4
     37   RETURN
     38   C
     39   C***STORE THE TIME THAT THE BOOSTER (K2=1) OR ORBITER (K2=2) WAS
     40   C***PUT IN STORAGE.
     41   C
     42   5 IS(K2)=IS(K2)+1
     43   K=IS(K2)
     44   ISQRE(K2,K)=K3
     45   RETURN
     46   C
     47   C***COMPUTE THE TIME THAT THE BOOSTER OR ORBITER WAS PUT IN STORAGE
     48   C***BASED ON FIRST-IN-FIRST-OUT.
     49   6 K4=K3-ISSTORE(K2,1)
     50   IS(K2)=IS(K2)-1
     51   K=IS(K2)
     52   IF(K.EQ.0)RETURN
     53   DO 20 I=1,K
     54   20 ISSTORE(K2,I)=ISSTORE(K2,I+1)
     55   RETURN

```

```

56      7 CONTINUE                               HELP 580
57      C                                     HELP 590
58      C***INITIALIZE MISSION SUBROUTINE AND PREPARE FOR NEW CASE   HELP 600
59      C                                     HELP 610
60      LL=0                                 HELP 620
61      C                                     HELP 650
62      - C***READ CASE STUDY COMMENT CARD                               HELP 670
63      C                                     READ(5,101)(TITLE(1),1=1,20)    HELP 700
64      101 FORMAT(20A4)                         HELP 710
65      C                                     HELP 720
66      C***READ THE VERSION CODE OF THE TRAFFIC MODEL TO BE SIMULATED
67      C                                     HELP 740
68      C***READ IN THE NUMBER OF BOOSTERS, ORBITERS & LUTS
69      C***READ IN THE LEVEL OF SIGNIFICANCE
70      C***READ IN THE RANDOM NUMBER SEED FOR MISSION MODEL PROGRAM(ISEED)
71      C***READ IN THE RANDOM NUMBER SEED FOR DISTRIBUTION GENERATORS(ISEED1)
72      C                                     HELP 770
73      READ(L1,103)NBOOS,NORBL,NCONF,NLUTS,NORAL,NLUTS,ISEED,ISEED1   HELP 780
74      103 FORMAT(1I14,3I5,4OX,2I10)          HELP 790
75      I$11=NBOOS                           HELP 800
76      I$121=NORBL                           HELP 820
77      K2=NBOOS                            HELP 830
78      K3=NORBL                            HELP 840
79      K4=NLUTS                            HELP 850
80      NSEED=ISEED                           HELP 860
81      NSEED1=ISEED1                         HELP 870
B-21
82      RETURN                                HELP 880
83      8 CONTINUE                             HELP 890
84      C                                     HELP 900
85      C***GENERATE DEVIATE FOR A TWO PARAMETER EXPONENTIAL DISTRIBUTION   HELP 920
86      C                                     HELP 930
87      PARAM1,1)=K2                           HELP 940
88      NBETA=K3-K2                           HELP 950
89      PARAM1,2)=NBETA                         HELP 960
90      K5=EXP(1)                            HELP 970
91      RETURN                                HELP 980
92      9 CONTINUE                             HELP 990
93      C                                     HELP 1000
94      C***GENERATE DEVIATE FOR THE LOG NORMAL DISTRIBUTION               HELP 1010
95      C                                     HELP 1020
96      F2=FLOAT(K2)/1000.                   HELP 1030
97      F3=FLOAT(K3)/1000.                   HELP 1040
98      PARAM1,1)=SQRT ALOG(F3**2/F2**2+1.0)    HELP 1050
99      PARAM1,1)=ALOG(F2)-5*(PARAM1,2)*2.0     HELP 1060
100     KS=RLOGN(1)*1000                      HELP 1070
101     RETURN                                HELP 1080
102     10 CONTINUE                            HELP 1090
103     C                                     HELP 1100
104     C***PRINT OUT OF SUMMARY TABLE           HELP 1110
105     C                                     NCALL=NCALL+1
106     CALL PRINT(NCALL,K2,K3,K4,K5)           HELP 1120
107     RETURN                                HELP 1130
108     11 CONTINUE                            HELP 1140
109     C                                     THIS FUNCTION PERMITS THE ADVANCE BLOCK TO BE INCREMENTED BY A
110     C                                     HELP 1150
111     C                                     A

```

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```
112 C***CONSTANT
113 C***TRANSFER THE VALUE OF ARGUMENT K2 TO ARGUMENT K5
114 C
115 C GPPS OUTPUT CAN BE OBTAINED FROM EITHER THE K4 OR K5 FIELDS
116 K5=K2
117 K4=K2
118 RETURN
119 12 CONTINUE
120 C
121 C***GENERATE DEVIATE FOR UNIFORM DISTRIBUTION
122 C
123 A = K2
124 B = K3
125 C GPPS OUTPUT CAN BE OBTAINED FROM EITHER THE K4 OR K5 FIELDS
126 K4 = UNFRM1(A,B)
127 K5=K4
128 RETURN
129 13 CONTINUE
130 C
131 C***GENERATE DEVIATE FOR PERTA DISTRIBUTION
132 C
133 PARAM(1,1) = K3
134 PARAM(1,2) = K2
135 PARAM(1,3) = K4
136 CALL PERTF(1,SMEAN,SVAR)
B 137 K5 = BETADP(1,SMEAN,SVAR)
138 RETURN
139 END
HELP1079
```

BHDG,P MAP

SPKT,S MAP

FURPUR HAIB-06/30-13:31

B-22

## 470223•TPFS•MISSION

SUBROUTINE MISSION(IPI,IP2,IP3,IP4,IP5,IK)

C THIS PROGRAM GENERATES TRAFFIC REQUIREMENTS FOR THE SHUTTLE

C OPERATIONAL MISSIONS.

C THE SELECTION OF FLEET SCHEDULED LAUNCH IS BASED ON THE FREQUENCY  
C OF MISSION OCCURRANCE.

C REAL LATITUDE

DIMENSION OPPORT(5,3),TLGTH(5,3)

DIMENSION LCONS(5),LDATE(5),INTERL(5),LFREQ(5,5)

COMMON /HEF/ LPARM(12),LLISEED,LLSTORE(12,10),LS(2)

COMMON /MISSION/ LLTA1,LLTA2,LLTA3,LLTA4,LLTA5

C\*\*\*\*\*VARIABLE K DEFINES THE TRAFFIC MODEL TO BE SIMULATED

K=1 = 20 LAUNCHES/YEAR

K=2 = 35 LAUNCHES/YEAR

K=3 = 45 LAUNCHES/YEAR

K=4 = 55 LAUNCHES/YEAR

K=5 = 75 LAUNCHES/YEAR

C\*\*\*\*\*ARRAY LFREQ CONTAINS THE FREQUENCY REQUIREMENTS FOR THE 5 TRAFFIC  
C MODELS. EACH ROW DEFINES A NEW MODEL.(FLIGHTS/YEAR)

DATA LFREQ/10,8,0,0,2,

A 14,6,2,12,1,  
B 16,8,4,16,1,  
C 20,8,8,19,2,  
D 35,8,6,19,5/

C\*\*\*\*\*DATA ON THE MINIMUM TIME BETWEEN LAUNCH REQUESTS(DAYS)

DATA LCONS/5,3,3,2,1/

DATA OPPORT/8,33,8,33,8,33,8,33,0,,

A 14,0,0,0,14,17,8,33,  
B 24,0,14,17,14,17,24,0,14,17/

C\*\*\*\*\*DATA ON THE RANGE OF TYPICAL ORBITER MISSION LENGTHS(DAYS)

DATA MILGTH/2,1,4,1,1,

A 3,2,5,3,5,  
B 5,3,6,5,20/

C\*\*\*\*\*VARIABLE NTYPES IS THE NUMBER OF DIFFERENT TYPES OF MISSIONS

NTYPES

C\*\*\*\*\*VARIABLE I DEFINES THE MISSION TYPE

I=1 = SHUTTLE PAYLOAD PLACEMENT

I=2 = SPACE STATION LOGISTICS

I=3 = TUG P/L PLACEMENT &amp; FUEL RESUPPLY

I=4 = DEPARTMENT OF DEFENSE

I=5 = SPACE RESCUE &amp; OTHER TYPES

C\*\*\*\*\*GO THRU THIS LEG ON THE FIRST CALL ONLY\*\*\*\*\*

C

I=1,LNE,0) GO TO 2

C\*\*\*\*\*VARIABLE LL IS SET = 1 WHEN EXECUTION PASSES THRU THIS LEG

LL = 1

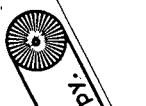
SAVE = 0,0

C\*\*\*\*\*DETERMINE THE FIRST LAUNCH DATE FOR EACH OF THE MISSION TYPES

C\*\*\*\*\*EVERY SPACED LAUNCH DATES HAVE BEEN ASSUMED FOR THE FIRST 5

LAUNCHES.

B-23

  
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```
56      LR=LFREQ(I,K)+LFREQ(I2,K)+LFREQ(3,K)+LFREQ(4,K)+LFREQ(5,K)
```

```
57      FIRST=260/LR
```

```
58      DO 7 I=1,NTYPE
```

```
59      DATE(I)=FIRST*2.
```

```
60      C****IF MISSION TYPE IS NOT DEFINED, SET THE LAUNCH DATE = 99999999
```

```
61      LFREQ(LK),EQ.O)DATE(I)=99999999
```

```
62      C****MISSIONS ARE TO BE SCHEDULED AT THE SAME FREQUENCY WITH 10 PERCENT
```

```
63      C     DEVIATION
```

```
64      INTERL(I)=.50*FLOAT(260/LFREQ(I,K))
```

```
65      IF(L.EQ.1)INTERL(I)=INTERL(I)+INTERL(I+2)
```

```
66      7 CONTINUE
```

```
67      C****
```

```
68      2 CONTINUE
```

```
69      C****CALCULATE THE NEXT LAUNCH TRAFFIC REQUIREMENT
```

```
70      C****
```

```
71      NMINMNO(LDATE(1),LDATE(2),LDATE(3),LDATE(4),LDATE(5))
```

```
72      DO 20 I=1,NTYPE
```

```
73      IF(LDATE(I).EQ.NMINM)GO TO 21
```

```
74      20 CONTINUE
```

```
75      MEROR=1
```

```
76      WRITE(6,100)MEROR
```

```
77      100 FORMAT(IX,6HERROR ,I1)
```

```
78      C****
```

```
79      C****ASSIGN LAUNCH HOUR FOR MISSION ASSIGNMENT
```

```
80      C****
```

```
81      21 NP2=I
```

```
82      TIME=DATE(I)
```

```
83      HOUR = UNFRM(0..24.)
```

```
84      LATINE = TIME + HOUR/24.
```

```
85      NP3=LATINE*1000.-SAVE
```

```
86      NP3=1ABS(NP3)
```

```
87      C****
```

```
88      C****GENERATE THE HISTOGRAM FOR THE TIME BETWEEN LAUNCH REQUESTS
```

```
89      C****
```

```
90      C****INITIALIZE NELTA1=NELTA1+1
```

```
91      IF(NP1.LT.20000.NELTA1=NELTA2+1
```

```
92      IF(NP3.GE.20000.AND.NP3.LT.30000.NELTA2=NELTA3+1
```

```
93      IF(NP3.GE.30000.AND.NP3.LT.50000.NELTA3=NELTA4+1
```

```
94      IF(NP3.GE.50000.AND.NP3.LT.10000.NELTA4=NELTA5+1
```

```
95      IF(NP3.GE.100000.AND.NP3.LT.20000.NELTA5=NELTA5+1
```

```
96      SAVE=LATINE*1000.
```

```
97      NP4=SAVE
```

```
98      C****
```

```
99      C****CALCULATE THE FIRST LAUNCH OPPORTUNITY AFTER THE NOMINAL LAUNCH TIME
```

```
100     C
```

```
101     DO 40 J=1,3
```

```
102     PARAM(I,J)=OPPORT(I,J)
```

```
103     40 CONTINUE
```

```
104     XOPPOR = DISCRET(I)
```

```
105     NPS=XOPPOR/24.*1000.
```

```
106     C****SELECT THE MISSION LENGTH OF THE ORBITER
```

```
107     C****
```

```
108     C
```

```
109     DO 50 J=1,3
```

```
110     PARAM(I,J)=MILGTH(I,J)
```

```
111     50 CONTINUE
```

## MISSION

```

112      NPI=TRIM(1)*1000.
113      C***CALCULATE THE DATE OF THE NEXT LAUNCH
114      C
115      C      NCOUNT=0
116      C      NCOUNT=NCOUNT+1
117      C      GO_CONTINUE
118      C      NCOUNT=NCOUNT+1
119      C      A=INTERL(1)
120      C      B=INTERL(1)
121      C      NVAR=UNFRM(A,B)
122      C      NDAY=LDATE(1)+260/LFREQ(1,K)+NVAR
123      C      DO 65 J=1,NTYPE
124      C
125      C***AFTER SO RESCHEDULES, THE CONSTRAINT MAY BE OVERRIDDEN
126      C
127      IF(INCOUNT.EQ.50)WRITE(6,1071)
128      107 FORMAT(//, * TRAFFIC MODEL VIOLATED MINIMUM TIME BETWEEN LAUNCH
129      REQUESTS CONSTRAINT*, TYPE*,[3])
130      IF(INCOUNT.EQ.50)GO TO 68
131      C
132      C***DETERMINE IF TIME BETWEEN LAUNCH REQUESTS MEETS THE MINIMUM REQ.
133      C      IF NOT - TRY TO SCHEDULE ANOTHER LAUNCH DATE
134      C
135      NIESTANDAY=LDATE(1)
136      IF(IABS(NTEST).LE.LCONS(K))GO TO 60
B-25
137      65 CONTINUE
138      66 CONTINUE
139      LDATE(1)=NDAY
140      RETURN
141      END

```

@Hdg, P      OUTPUT

@PRT,S      OUTPUT  
FURPUR HA18-06/30-13:31

```

420223@TPFS.OUTPUT
      SUBROUTINE OUTPUT (ICOM,LOC,NAME,IX,IY,IZ,ISEL,M,NBA,NBB,MEAN,MOD)
      C
      C   SUBROUTINE TO DETERMINE TYPE OF DISTRIBUTION AND WRITE
      C   CORRESPONDING DATA.
      C
      C   DIMENSION NAME(2),ICOM(11)
      DATA K9/2HK9/,K3/2HK3/,K4/2HK4/,K8/2HK8/
      DATA K11/3HK11/,K12/3HK12/,K13/3HK13/
      C   TEST TO DETERMINE IF DISTRIBUTION IS LOGNORMAL (K9)
      10  C
      11  IF(IY.EQ.K9) GO TO 1
      12  C   TEST TO DETERMINE IF DISTRIBUTION IS TRIANGULAR (K3)
      13  C
      14  IF(IX.EQ..3) GO TO 2
      15  C   TEST TO DETERMINE IF DISTRIBUTION IS NORMAL (K4)
      16  C
      17  IF(IX.EQ.K4) GO TO 3
      18  C   TEST TO DETERMINE IF DISTRIBUTION IS EXPONENTIAL (K8)
      19  C
      20  IF(IX.EQ.K8) GO TO 4
      21  C   TEST TO DETERMINE IF DISTRIBUTION IS CONSTANT(K11)
      22  C
      23  IF(IX.EQ.K11) GO TO 5
      24  C   TEST TO DETERMINE IF DISTRIBUTION IS UNIFORM (K12)
      25  IF(IX.EQ.K12) GO TO 6
      26  C   TEST TO DETERMINE IF DISTRIBUTION IS BETA (K13)
      27  C
      28  IF(IX.EQ.K13) GO TO 7
      29  C
      30  RETURN
      31  I  CONTINUE
      32  C   CALL SUBROUTINE REALN TO CONVERT ALPHANUMERIC NUMBERS TO
      33  C   REAL NUMBERS.
      34  C
      35  CALL REALN (RES1,IY)
      36  CALL REALN (RES2,IZ)
      37  C
      38  RES1 = RES1/1000.0
      39  RES2 = RES2/1000.0
      40  C
      41  C   WRITE RESULTS FOR LOGNORMAL DISTRIBUTION
      42  WRITE (6,90) ICOM,RES1,RES2
      43  WRITE(6,841)
      44  RETURN
      45  C   CONTINUE
      46  C
      47  C   CALL SUBROUTINE REALN TO CONVERT ALPHANUMERIC NUMBERS TO
      48  C   REAL NUMBERS.
      49  CALL REALN (RES1,IY)
      50  CALL REALN (RES2,IZ)
      51  CALL REALN (RES3,MEAN)
      52  C
      53  RES1 = RES1/1000.0
      54  RES2 = RES2/1000.0
      55  RES3 = RES3/1000.0

```

```

56      C
57      C WRITE RESULTS FOR TRIANGULAR DISTRIBUTION
58      WRITE (6,91) ICOM,RES1,RES2,RES3
59      WRITE (6,84)
60      RETURN
61      3... CONTINUE
62      C CALL SUBROUTINE REALN TO CONVERT ALPHANUMERIC NUMBERS TO
63      C REAL NUMBERS.
64      C CALL REALN (RES1,IY)
65      C CALL REALN (RES2,IY)
66      C CALL REALN (RES2,I2)
67      C
68      RES1 = RES1/1000.0
69      RES2 = RES2/1000.0
70      C WRITE RESULTS FOR NORMAL DISTRIBUTION
71      C WRITE (6,92) ICOM,RES1,RES2
72      C
73      C CALL SUBROUTINE REALN TO CONVERT ALPHANUMERIC NUMBERS TO
74      C REAL NUMBERS.
75      4... CONTINUE
76      C
77      C CALL SUBROUTINE REALN TO CONVERT ALPHANUMERIC NUMBERS TO
78      C REAL NUMBERS.
79      C CALL REALN (RES1,IY)
80      C CALL REALN (RES2,I2)
81      C
82      RES1 = RES1/1000.0
83      RES2 = RES2/1000.0
84      C WRITE RESULTS FOR EXPONENTIAL DISTRIBUTION
85      C
86      WRITE (6,93) ICOM,RES1,RES2
87      WRITE (6,84)
88      RETURN
89      5... CONTINUE
90      C
91      C CALL SUBROUTINE REALN TO CONVERT ALPHANUMERIC NUMBERS TO
92      C REAL NUMBERS.
93      C CALL REALN (RES3,IY)
94      C
95      RES3=RES3/1000.0
96      C
97      C WRITE RESULTS FOR CONSTANT DISTRIBUTION
98      C
99      WRITE (6,94) ICOM,RES3
100     C
101     6... CONTINUE
102     C
103     C CALL SUBROUTINE REALN TO CONVERT ALPHANUMERIC NUMBERS TO
104     C REAL NUMBERS.
105     C CALL REALN (RES1,IY)
106     C CALL REALN (RES2,I2)
107     C RES3=(RES1+RES2)/2000.0
108     C RES1=RES1/1000.0
109     C RES2=RES2/1000.0
110     C
111     C WRITE RESULTS FOR UNIFORM DISTRIBUTION

```

```

112      WRITE(6,95) TCOM,REST,RES3,RES5
113      WRITE (6,84)
114      RETURN
115      7 CONTINUE
116
117      C      CALL SUBROUTINE REALN TO CONVERT ALPHANUMERIC NUMBERS TO
118      C      REAL NUMBERS
119      CALL REALN(RES1,IY)
120      CALL REALN(RES2,I2)
121      CALL REALN(RES3,MEAN)
122      RES1=RES1/1000.0
123      RES2=RES2/1000.0
124      RES3=RES3/1000.0
125
126      C      WRITE RESULTS FOR BETA DISTRIBUTION
127      WRITE (6,6) TCOM,RES1,RES2,RES3
128      WRITE (6,84)
129      RETURN
130
131      C      84 FORMAT (I9,IHI,6T7X,IHI,13X,IHI,13X,IHI)
132      C      90 FORMAT(I9,IHI,1X,A5,2A6,8A6,1X,IHI,1X,IHLOGNORMAL,
133      1 IX,IHI,1X,5HMEAN=,F7.4,1X,IHI,1X,BHST,DEV =,F7.4,1X,IHI,13X,IHI)
134
135      C      91 FORMAT(I9,IHI,1X,A5,2A6,8A6,1X,IHI,1X,IHTRIANGULAR ,
136      1 IX,IHI,1X,5HMIN =,F7.4,1X,IHI,1X,BHMODE =,F7.4,
137      2 IX,IHI,1X,4HMAX=,F7.4,1X,IHI)
138
139      C      92 FORMAT(I9,IHI,1X,A5,2A6,8A6,1X,IHI,1X,IHNORMAL ,
140      1 IX,IHI,1X,5HMEAN=,F7.4,1X,IHI,1X,BHST,DEV =,F7.4,1X,IHI,13X,IHI)
141
142      C      93 FORMAT(I9,IHI,1X,A5,2A6,8A6,1X,IHI,1X,IHEXPONENTIAL,
143      1 IX,IHI,1X,5HMIN =,F7.4,1X,IHI,1X,BHMEAN =,F7.4,1X,IHI,13X,IHI)
144
145      C      94 FORMAT(I9,IHI,1X,A5,2A6,8A6,1X,IHI,1X,IHCONSTANT ,
146      1 IX,IHI,1X,5HMEAN =,F7.4,1X,IHI,17X,IHI,13X,IHI)
147
148      C      95 FORMAT(I9,IHI,1X,A5,2A6,8A6,1X,IHI,1X,IHUNIFORM
149      1 IX,IHI,1X,5HMIN =,F7.4,1X,IHI,1X,BHMEAN =,F7.4,
150      2 IX,IHI,1X,4HMAX=,F7.4,1X,IHI)
151
152      C      96 FORMAT(I9,IHI,1X,A5,2A6,8A6,1X,IHI,1X,IHBETA
153      1 IX,IHI,1X,5HMIN =,F7.4,1X,IHI,1X,BHMEAN =,F7.4,
154      2 IX,IHI,1X,4HMAX=,F7.4,1X,IHI)
155      END

```

@HDG,P PERTAF

@PRT,S PERTXE  
FURPUR HA18-06/30-13:31

PERTXF  
420223•TPFS•PERTXF  
1 SUBROUTINE PERTXF(J,SMEAN,SVAR)  
2 COMMON /HEPL/ PARAM(7,3),LL,ISEED,ISEED1,ISTORE(2,10),IS12)  
3 SVAR = (PARAM(J,3)-PARAM(J,2))/2./36.  
4 SMEAN = (PARAM(J,1)\*4. + PARAM(J,2)) \* 6.0  
5 C  
6 C\*\*\* CALCULATE THE MEAN AND VARIANCE FOR THE GIVEN PARAMETERS  
7 C\*\*\*  
8 C\*\*\* PARAM(J,1) CONTAINS THE MODE  
9 C\*\*\* PARAM(J,2) CONTAINS THE LOWER LIMIT  
10 C\*\*\* PARAM(J,3) CONTAINS THE UPPER LIMIT  
11 C\*\*\* SMEAN CONTAINS THE NORMALIZED MEAN OVER THE INTERVAL 10.JPERT 110  
12 C\*\*\* BVAR CONTAINS THE NORMALIZED VARIANCE OVER THE INTERVAL PERT 120  
13 C\*\*\*  
14 C  
15 SMEAN = (SMEAN - PARAM(J,2))/(PARAM(J,3)-PARAM(J,2))  
16 BVAR = SVAR/(PARAM(J,3)-PARAM(J,2))\*2.0  
17 SMEAN = SMEAN\*(BMEAN\*LL-BMEAN)/BVAR-1.0  
18 SVAR = SMEAN\*((1.0-SMEAN)/BMEAN)  
19 RETURN  
20 END

SHUG,P PRINT

BPRINT,  
FURPUR HA18-06/30-13:31

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--420223•TPFS.PRINT      SUBROUTINE PRINTNCALL,K2,K3,K4,KS
1      C
2      C*****THIS ROUTINE PRINTS OUT THE SUMMARY RESULTS TABLE*****
3      C
4      C
5      REAL MHUF,LUTREF
6      INTEGER P
7      INTEGER GLOB
8      COMMON /HUPRT/NB005,NORB1,NLUTS,TITLE(20),NSEED,NSEED1
9      COMMON /MISPR/T/NELTA1,NELTA2,NELTA3,NELTA4,NLTAS
10     COMMON/EQJ/JF2(1)
11     COMMON/SI0R1/J$1(1)
12     COMMON/STOR2/J$2(1)
13     COMMON/QWE5/JQS(1)
14     COMMON/QUE6/JQ6(1)
15     COMMON/ENSES/JEKS(1)
16     COMMON/WAY/P
17     COMMON/STAT3/ISN
18
19     P=6
20     GO TO 110,20,30,50,60,70,80,90,NCALL
21
22     100 FORMAT(1H,30X,*TABLE 11. SUMMARY RESULTS*)
23     100 FORMATT1H,30X,*TABLE 11. SUMMARY RESULTS*)
24     WRITE(P,102)(TITLE(1),15,20)
25     WRITE(P,103)
26     103 FORMAT(1/10X,*INITIAL CONDITIONS*,T60,*BOOSTER*,T70,*ORBITER*)
27     WRITE(P,104)NBOOS ,NORB1
28     104 FORMAT(15X,*NUMBER OF VEHICLE STAGES *,T63,112,T73,12)
29     MSAB=MGTHU(J$2(1))+MGTH2U(J$1(1))
30     PSAO=MGTHU(J$2(10))+MGTH2U(J$1(10))
31     WRITE(P,170)MSAB,PSAO
32     170 FORMAT(15X,*SERVICE CAPACITY OF SAFING AREA*,T63,12,T73,12)
33     MF9=MGTHU(J$2(2))+MGTH2U(J$1(2))
34     MF0=MGTHU(J$2(11))+MGTH2U(J$1(11))
35     WRITE(P,105)
36     105 FORMAT(15X,*SERVICE CAPACITY OF MAINTENANCE FACILITY *,T63,12,
37           1,T73,12)
38     MCOTB=MGTHU(J$2(3))+MGTH2U(J$1(3))
39     MCOTO=MGTHU(J$2(12))+MGTH2U(J$1(12))
40     WRITE(P,176)MCOTB,MCOTO
41     176 FORMAT(15X,*SERVICE CAPACITY OF CHECKOUT & TEST FACILITY *,T63,
42           1,T73,12)
43     MHF =MGTHU(J$2(20))+MGTH2U(J$1(20))
44     WRITE(P,171)MHF
45     171 FORMAT(15X,*SERVICE CAPACITY OF MATE & HOOK-UP FACILITY *,T68,12)
46     LUTRF=MGTHU(J$2(18))+MGTH2U(J$1(18))
47     WRITE(P,172)LUTRF
48     172 FORMAT(15X,*SERVICE CAPACITY OF LUT REFURBISHMENT FACILITY *,T68,
49           1,12)
50     50     WRITE(P,173)NLUTS
51     173 FORMAT(15X,*NUMBER OF LUTS *,T40,12)
52     C*****NPADS=1
53
54     54     IF(JF2(2).GT.0)NPACS=2
55     IF(JF2(3).GT.0)NPDS=3

```

```

5   13 WRITE(P,106)NPAUDS
57 106 FORMAT(15X,'NUMBER OF LAUNCH PADS= ',I40,12)
58   K2=JEKS(30)+JEKS(12)+JEKS(3)+JEKS(4)+JEKS(22)+JEKS(23)+JEKS(24)*
59   1
60   JEKS(25)*JEKS(8)
61   174 FORMAT(15X,'TRAFFIC MODEL STATISTICS::')
62   NFR=260000/FLOAT(JEKS(21))*FLOAT(K2)
63   WRITE(P,157)NFR
64   157 FORMAT(15X,'MISSION MODEL LAUNCH RATE (FLIGHTS/YEAR)= ',I6)
65   NLRNELTA1*NELTA2*NELTA3*NELTA4*NELTA5
66   PELTA1=FLOAT(NELTA1)*100/NLR
67   PELTA2=FLOAT(NELTA2)*100/NLR
68   PELTA3=FLOAT(NELTA3)*100/NLR
69   PELTA4=FLOAT(NELTA4)*100/NLR
70   PELTA5=FLOAT(NELTA5)*100/NLR
71   WRITE(P,158)PELTA1,PELTA2,PELTA3,PELTA4,PELTA5
72   158 FORMAT(15X,'DISTRIBUTION OF TIME BETWEEN LAUNCH REQUESTS--',
73   'A16X,F5.1,* OF LAUNCHES ARE SCHEDULED 1 DAY APART,
74   B/16X,F5.1,* OF LAUNCHES ARE SCHEDULED 2 DAYS APART,
75   C/16X,F5.1,* OF LAUNCHES ARE SCHEDULED 3 DAYS TO 1 WEEK APART,
76   D/16X,F5.1,* OF LAUNCHES ARE SCHEDULED 3 DAYS TO 2 WEEKS APART,
77   E/16X,F5.1,* OF LAUNCHES ARE SCHEDULED 2 WEEKS TO 1 MONTH APART')
78   WRITE(P,107)K2
79   107 FORMAT(15X,'OPERATIONAL EVALUATION PARAMETERS FOR ',I4,' SIMULA-
80   TIONS;')
81   PLR=FLOAT(JEKS(30))*100/K2
82   WRITE(P,152)JEKS(30),PLR
83   152 FORMAT(15X,'THE NUMBER OF SUCCESSFUL LAUNCH REQUESTS ARE ',I4,
84   ' OR ',F5.1,' PERCENT')
85   NMRLR=K2-JEKS(30)
86   NMRLR=FLOAT(NMRLR*100./K2)
87   WRITE(P,108)NMRLR,PMLR
88   108 FORMAT(15X,'THE NUMBER OF UNSUCCESSFUL REQUESTS ARE ',I4,
89   ' OR ',F5.1,' PERCENT')
90   GLOB=FLOAT(JEKS(26))/FLOAT(JEKS(30))*100.
91   GLOB = JEKS(26)
92   WRITE(P,373)GLOB,GLOB
93   373 FORMAT(15X,'THE NUMBER OF VEHICLES LAUNCHED AT A SUBSEQUENT WINDOW
94   1 IS ',I3,', OR ',F5.1,' PERCENT')
95   WRITE(P,596)
96   596 FORMAT(15X,'REASONS FOR REQUEST FAILURES--')
97   NBUNA=JEKS(31)
98   NBUNA=FLOAT(NBUNA*100./K2)
99   WRITE(P,109)NBUNA,PHUNA
100  109 FORMAT(15X,'BOOSTER UNAVAILABILITY ',T50,I4,' TIMES OR ',F5.1,' PERC
101  IENT')
102  JEKS(4)
103  NOUNA=FLOAT(NOUNA)*100./K2
104  WRITE(P,110)NOUNA,POUNA
105  110 FORMAT(15X,'ORBITER UNAVAILABILITY ',T50,I4,' TIMES OR ',F5.1,' PERC
106  IENT')
107  POUNA=FLOAT(JEKS(21))*100./K2
108  WRITE(P,156)JEKS(2),POUNA
109  156 FORMAT(15X,'BOTH STAGES UNAVAILABLE ',T50,I4,' TIMES OR ',F5.1,' PE
110  IRCENT')
111  LEFAIL=JEKS(8)

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168      154 FORMAT(15X,'PERCENT OF VEHICLES DELAYED FOR MAINT.',T62,F5.2,T72,
169          1 F5.2),
170          TMQB=K4/1000.
171          TMQD=5/1000.
172          WRITE(P,116)TMQB,TMQD
173          116 FORMAT(15X,'AVERAGE QUEUE TIME FOR MAINTENANCE(DAYS)',T62,F5.2,T72
174          1,F5.2)
175          RETURN
176          C*****.
177          40 CONTINUE
178          PCHEKB = FLOAT(JQS(13)-JQ6(3))*100./JQS(3)
179          PCHEKO = FLOAT(JQS(112)-JQ6(112))*100./JQS(112)
180          CHECKB = K2/1000.
181          CHECKD = K3/1000.
182          WRITE(P,330)PCHEKB,PCHEKO,CHECKB,CHECKD
183          330 FORMAT(
184          215X,'PERCENT OF VEHICLES DELAYED FOR CHECKOUT&TEST',T62,F5.2,T72,
185          3 F5.2/15X,'AVERAGE QUEUE TIME FOR CHECKOUT & TEST(DAYS)',T62,F5.2
186          42,T72,F5.2)
187          C           WRITE(P,117) DUMMY WRITE STATEMENT
188          C 117 FORMAT(15X,'AVERAGE QUEUE TIME FOR
189          C 1 F5.2)
190          MAHUF = K4/1000.
191          LUTREF = K5/1000.
192          PMAHU = FLOAT(JQS(20)-JQ6(20))*100./JQS(20)
193          PLUT = FLOAT(JQS(18)-JQ6(18))*100./JQS(18)
B-33
194          WRITE(P,301)PMAHU,MAHUF,PLUT,LUTREF
195          301 FORMAT(15X,'PERCENT OF VEHICLES DELAYED FOR M & H',T65,F5.2/15X,
196          1AVERAGE QUEUE TIME FOR MATE & HOOTUP(DAYS)',T65,F5.2/15X,'PERCENT
197          2 OF LUTS DELAYED FOR REFURBISHMENT',T65,F5.2/15X,'AVERAGE QUEUE T
198          3IME FOR LUT REFURBISH FACILITY',T65,F5.2)
199          RETURN
200          C*****.
201          50 CONTINUE
202          PQP=FLOAT(JQS(21)-JQ6(21))*100./JQS(21)
203          WRITE(P,155)PQP
204          155 FORMAT(15X,'PERCENT OF VEHICLES DELAYED FOR PAD ACCESS',T65,F5.2)
205          TQP=K2/1000.
206          WRITE(P,118)TOP
207          118 FORMAT(15X,'AVERAGE QUEUE TIME FOR PAD(DAYS)',T65,F5.2)
208          RETURN
209          C*****.
210          60 CONTINUE
211          SAUB=K2/10.
212          SAUD=K3/10.
213          WRITE(P,119)SAUB,SAUD
214          119 FORMAT(1//10X,'FACILITY UTILIZATION',T60,'BOOSTER',T70,'ORBITER',
215          1 /15X,'SAFING AREA(PERCENT)',T61,F5.2,T71,F5.2)
216          SMUB=K4/10.
217          SMUD=K5/10.
218          WRITE(P,120)SMUB,SMUD
219          120 FORMAT(15X,'MAINTENANCE(PERCENT)',T61,F5.2,T71,F5.2)
220          RETURN
221          C*****.
222          70 CONTINUE
223          COTUB=K2/10.

```

```
224      COTU0=K3/10.
225      WRITE(P,177)COTUB,COTU0
226      177 FORMAT(15X,'CHECKOUT & TEST(PERCENT)',T61,FS=2,T71,FS=2)
227      RETURN
228      C*****.
229      80 CONTINUE
230      PMHUK2/10.
231      WRITE(P,121)PMHU
232      121 FORMAT(15X,'MATE & HOOK-UP (PERCENT)',T45,FS=2)
233      PLRU=K3/10.
234      WRITE(P,122)PLRU
235      122 FORMAT(15X,'PLUT REFURISHMENT (PERCENT)',T45,FS=2)
236      RETURN
237      C*****.
238      90 CONTINUE
239      PDU1=K2/10.
240      WRITE(P,123)PDU1
241      123 FORMAT(15X,'PAO UTILIZATION')
242      1   15X,LAUNCH PAD 1 (PERCENT),T45,FS=2)
243      IF (NPADS=2) 61,62,62
244      62 PDU2=K3/10.
245      WRITE(P,124)PDU2
246      124 FORMAT(15X,'LAUNCH PAD 2 (PERCENT)',T45,FS=2)
247      IF (NPADS=3) 61+1003,1003
248      1003 PDU3=K4/10.
249      WRITE(P,1004) PDU3
250      1004 FORMAT(15X,'LAUNCH PAD 3 (PERCENT)',T45,FS=2)
251      61 CONTINUE
252      C*****.WRITE OUT CASE STUDY COMMENT CARD
253      WRITE(P,199)TITLE(1,1,E1,20)
254      199 ////////////////20A4,/////////////
255      WRITE(P,200)NBOOS,NOBJ
256      200 FORMAT(///,10X,'THE FLEET SIZE IS',I2,' BOOSTERS & I2.,' ORBITERS
257      1')
258      WRITE(P,201)NSEED
259      201 FORMAT(10X,RANDOM NUMBER SEED FOR TRAFFIC MODEL SIMULATOR = *,I10)
260      1 ,/10X, RANDOM NUMBER SEED FOR DISTRIBUTION FUNCTIONS = *,I10
261      C DETERMINE IF TABLE 111 OUTPUT IS REQUIRED
262      C IF (ISN.LT.9) RETURN
263      CALL SAMPLE(K1,K2,K3,K4,K5)
264      C
265      C
266      RETURN
267      C*****.
268      END
B-34
```

```

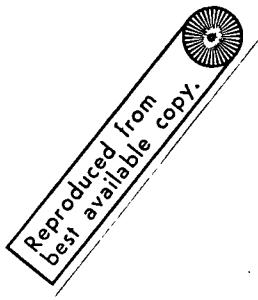
-----42U223•TPFS.REALN-----1
1      SUBROUTINE REALN (RES,IN)
2      C
3      C   SUBROUTINE TO CHANGE ALPHANUMERIC NUMBERS TO REAL NUMBERS
4      C
5      C..... C... SUBSCRIPTED VARIABLE IA WILL CONTAIN L CHARACTER IN EACH P
6      C
7      DIMENSION IA(6)
8      C
9      C
10     C
11     C..... C... FUNCTION FLD IS A LIBRARY FUNCTION WHICH ENABLES USER TO O
12     C..... C... INDIVIDUAL BITS FROM AN ALPHANUMERIC WORD AND STORE
13     C..... C... THEM IN ANOTHER WORD.
14     C
15     C FLD (I1,K,E) I1 = STARTING BIT K = BIT WIDTH E = WORD
16     C
17     C
18     C
19     C IN POSITION 1 OF IA STORE BITS 0 TO 5 OF WORD IN
20     C IA(1) = FLD ( G, 1, E )
21     C
22     C IN POSITION 2 OF IA STORE BITS 6 TO 11 OF WORD IN
23     C IA(2) = FLD ( G, 6, E )
24     C
25     C IN POSITION 3 OF IA STORE BITS 12 TO 17 OF WORD IN
26     C IA(3) = FLD ( G, 12, E )
27     C
28     C IN POSITION 4 OF IA STORE BITS 18 TO 23 OF WORD IN
29     C IA(4) = FLD ( G, 18, E )
30     C
31     C IN POSITION 5 OF IA STORE BITS 24 TO 29 OF WORD IN
32     C IA(5) = FLD ( G, 24, E )
33     C
34     C IN POSITION 6 OF IA STORE BITS 30 TO 35 OF WORD IN
35     C IA(6) = FLD ( G, 30, E )
36     C
37     C TEST TO DETERMINE IF 1ST CHARACTER OF WORD IS A BLANK
38     C..... IF (IA(1).NE.16) GO TO 1
39     C
40     C TEST TO DETERMINE IF 6TH CHARACTER OF WORD IS A BLANK
41     C..... IF (IA(6).NE.5) GO TO 10
42     C
43     C TEST TO DETERMINE IF 5TH CHARACTER OF WORD IS A BLANK
44     C..... IF (IA(5).NE.5) GO TO 11
45     C
46     C TEST TO DETERMINE IF 4TH CHARACTER OF WORD IS A BLANK
47     C..... IF (IA(4).NE.5) GO TO 12
48     C
49     C TEST TO DETERMINE IF 3RD CHARACTER OF WORD IS A BLANK
50     C..... IF (IA(3).NE.5) GO TO 13
51     C
52     C TEST TO DETERMINE IF 2ND CHARACTER OF WORD IS A BLANK
53     C..... IF (IA(2).NE.5) GO TO 14
54     C..... GO TO 1

```

```

56 C
57 C TO CHANGE ALPHANUMERIC NUMBER TO A REAL NUMBER SUBSTRACT 48.
58 C
59 C ALPHANUMERIC ZERO IS REPRESENTED BY CHARACTER 48 WHICH
60 C OCCUPIES 6 BITS IN AN ALPHANUMERIC WORD.
61 C
62 C ALPHANUMERIC ONE IS REPRESENTED BY CHARACTER 49 ETC.
63 C
64 C
65 C
66 C
67 C 10 CONTINUE
68 C
69 C EQUATION TO CHANGE 5 CHARACTER ALPHANUMERIC NUMBER TO 5
70 C CHARACTER INTEGER
71 C IRES = (IA(6)-48) + (IA(5)-48) + (IA(4)-48)*10 + (IA(3)-48)*100
72 C 1 + (IA(3)-48)*1000 + (IA(2)-48)*10000
73 C
74 C EQUATION TO CHANGE INTEGER TO REAL NUMBER FOR TABLE
75 C RES = IRES
76 C RETURN
77 C 11 CONTINUE
78 C
79 C EQUATION TO CHANGE 4 CHARACTER ALPHANUMERIC NUMBER TO 4
80 C CHARACTER INTEGER
81 C IRES = (IA(5)-48) + (IA(4)-48)*10 + (IA(3)-48)*100
82 C 1 + (IA(2)-48)*1000
83 C
84 C EQUATION TO CHANGE INTEGER TO REAL NUMBER FOR TABLE
85 C RES = IRES
86 C RETURN
87 C 12 CONTINUE
88 C
89 C EQUATION TO CHANGE 3 CHARACTER ALPHANUMERIC NUMBER TO 3
90 C CHARACTER INTEGER
91 C IRES = (IA(4)-48) + (IA(3)-48)*10 + (IA(2)-48)*100
92 C
93 C EQUATION TO CHANGE INTEGER TO REAL NUMBER FOR TABLE
94 C RES = IRES
95 C RETURN
96 C 13 CONTINUE
97 C
98 C EQUATION TO CHANGE 2 CHARACTER ALPHANUMERIC NUMBER TO 2
99 C CHARACTER INTEGER
100 C IRES = (IA(3)-48) + (IA(2)-48)*10
101 C
102 C EQUATION TO CHANGE INTEGER TO REAL NUMBER FOR TABLE
103 C RES = IRES
104 C RETURN
105 C 14 CONTINUE
106 C
107 C EQUATION TO CHANGE 1 CHARACTER ALPHANUMERIC NUMBER TO 1
108 C CHARACTER INTEGER
109 C IRES = IA(2)-48
110 C
111 C EQUATION TO CHANGE INTEGER TO REAL NUMBER FOR TABLE

```



REALN

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112	RES = TRES
113	RETURN
114	I CONTINUE
115	C
116	C EQUATION WILL RESULT IN ERROR, PRINTING STARS
117	RES = 999999.9
118	RETURN
119	END
@HDG.P	RLOGN

@PRT.S RLOGN

FURPUR HA1B=06/30-13:31

RLOGN

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```
420223*TPFS.RLOGN
1      FUNCTION RLOGN (J)
2      C
3      C***THE PARAMETERS USED WITH RLOGN ARE THE MEAN AND STANDARD DEVIATION
4      C***OF A NORMAL DISTRIBUTION
5      C
6      VA=RNORM (J)
7      RLOGN=EXP(VA)
8      RETURN
9      END
```

```
      LGNS  IN
      LGNS  LGNS  20
      LGNS  30
      LGNS  40
      LGNS  50
```

```
6HUG,P   RNORM
```

```
RPT,S   RNORM
```

```
FURPUR HAI 06/30 13:31
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```
RNORM
420223•TPFS•RNORM
      1. FUNCTION RNORM (J)
      2. COMMON /HEPL/ PARAM(7,3),LL,ISEED1,ISEED2,ISTORE(12,10),IS(2)
      3.      RA=DRAND(ISEED1)
      4.      RB=DRAND(ISEED1)
      5.      V=(72.0*LOG(RA))**C.5*COS (6.283*RB)
      6.      RNORM = V*PARAM (J,2) + PARAM (J,1)
      7.      RETURN
      8.      END
```

```
NRLS 10
NRLS 80
```

```
NRLS 90
```

```
NRLS 150
```

```
NRLS 160
```

GDG,P

SAMPLE

6PKTS SAMPLE  
FUKPUR HAI8-06/30-13:31

```

420223@PPFS.SAMPLE
1      COMPILER(U DATA=SHORT)
2      SUBROUTINE SAMPLE(K1,K2,K3,K4,K5)
3      COMMON /STAT/ NCONF
4      COMMON/SIA/2/NFLTS
5      COMMON/STATS/NHEAD
6      COMMON/WAY/P
7      COMMON/STAT3/1SN
8      COMMON K(100)
9      EQUIVALENCE /K(28)ANCLK/
10     INTEGER P
11     DIMENSION I(32,2),SAVE(14,6),NHEAD(14,11)
12     C
13     C
14     C THESE ARE VALUES OF THE STUDENT T VARIABLE
15     C
16     DATA(I(J,K),K=1,2),J=1,18)/
17     1.2,704,63,657,
18     2,4,303,9,925,
19     3,3,182,5,841,
20     4,2,776,4,604,
21     5,2,571,4,032,
22     6,2,447,3,707,
23     7,2,365,3,499,
24     8,2,306,3,355,
25     9,2,262,3,250,
26     0,2,228,3,169,
27     1,2,201,3,106,
28     2,2,179,3,055,
29     3,2,160,3,012,
30     4,2,145,2,977,
31     5,2,131,2,947,
32     6,2,120,2,921,
33     7,2,110,2,898,
34     8,2,101,2,878/
35     DATA((I(J,K),K=1,2),J=19,31)/
36     9,2,093,2,861,
37     0,2,086,2,845,
38     1,2,080,2,831,
39     2,2,074,2,819,
40     3,2,069,2,807,
41     4,2,064,2,797,
42     5,2,060,2,787,
43     6,2,056,2,779,
44     7,2,052,2,771,
45     8,2,048,2,763,
46     9,2,045,2,756,
47     0,2,042,2,750,
48     1,1,960,2,576/
49     C
50     C STORE HEADINGS TO BE USED IN PRINTING
51     C
52     C DATA(NHEAD(I,J),J=1,11),I=1,9)/
53
54     C
55     C 162THE PERCENTAGE OF SUCCESSFUL LAUNCH REQUESTS

```

SAMPLE		DATE 063072	PAGE
56	262 THE PERCENTAGE OF UNSUCCESSFUL LAUNCH REQUESTS	SAMP 560	
57	362 THE PERCENTAGE OF VEHICLES LAUNCHED AT A SUBSEQUENT MINDON	SAMP 570	
58	462H BOOSTER UNAVAILABILITY	SAMP 580	
59	562H ORBITER UNAVAILABILITY	SAMP 590	
60	662H BOTH STAGES UNAVAILABLE	SAMP 600	
61	762H LUT UNAVAILABILITY	SAMP 610	
62	862H PAD UNAVAILABILITY	SAMP 620	
63	962H FAILURES AND REMOVAL FROM PAD	/SAMP 630	
64	C	SAMP 640	
65	C	SAMP 650	
66	C FIELD DEFINITIONS	SAMP 660	
67	C	SAMP 670	
68	C K1 IS A DUMMY	SAMP 680	
69	C	SAMP 690	
70	C K2 CORRESPONDS TO THE *Y FIELD ENTRY ON THE HELP CARD AND IS	SAMP 700	
71	C THE IDENTIFICATION NUMBER OF THE STATISTIC BEING COLLECTED.	SAMP 710	
72	C	SAMP 720	
73	C K3 CORRESPONDS TO THE *Z FIELD ENTRY ON THE HELP CARD AND IS	SAMP 730	
74	C THE TYPE OF STATISTIC BEING COLLECTED	SAMP 740	
75	C K3=1 FOR A NUMBER	SAMP 750	
76	C K3=2 FOR PERCENTAGE UTILIZATION	SAMP 760	
77	C K3=3 FOR AVERAGE TIME	SAMP 770	
78	C	SAMP 780	
79	C K4 CORRESPONDS TO THE *MEAN FIELD ENTRY ON THE HELP CARD AND	SAMP 790	
80	C IS THE GPS SYSTEM VARIABLE THAT REPRESENTS	SAMP 800	
81	C 1) NUMBER OF ENTRIES	SAMP 810	
82	C 2) AVERAGE UTILIZATION	SAMP 820	
83	C 3) AVERAGE TIME IN A FACILITY, STORAGE OR QUEUE	SAMP 830	
84	C	SAMP 840	
85	C KS CORRESPONDS TO THE *MOD FIELD ENTRY ON THE HELP CARD AND	SAMP 850	
86	C IS THE GSS SYSTEM VARIABLE WHEN REQUIRED THAT REPRESENTS	SAMP 860	
87	C THE NUMBER OF ENTRIES INTO THE BLOCK TYPE SPECIFIED	SAMP 870	
88	C IN THE *MEAN FIELD	SAMP 880	
89	C	SAMP 890	
90	C	SAMP 900	
91	C ARRAY ELEMENT DEFINITIONS	SAMP 910	
92	C	SAMP 920	
93	C SAVEL(1,1) = PREVIOUS READING	SAMP 930	
94	C SAVEL(1,2) = SUM X <sup>2</sup>	SAMP 940	
95	C SAVEL(1,3) = SUM X SQUARED'S	SAMP 950	
96	C SAVEL(1,4) = K4 READING FOR THE FIRST 100 SIMULATIONS	SAMP 960	
97	C SAVEL(1,5) = 1/2 WIDTH OF THE CONFIDENCE INTERVAL	SAMP 970	
98	C SAVEL(1,6) = PREVIOUS K5 READING	SAMP 980	
99	C	SAMP 990	
100	C	SAMP 1000	
101	C	SAMP 1010	
102	C	SAMP 1020	
103	C CONTINUE WITH STATISTICAL SAMPLING	SAMP 1030	
104	C	SAMP 1040	
105	C DETERMINE IF A REQUEST FOR OUTPUT HAS OCCURRED	SAMP 1050	
106	C IF(P.EQ.6) GO TO 60	SAMP 1060	
107	C	SAMP 1070	
108	C EXECUTE THIS PORTION OF THE PROGRAM ONLY ONCE	SAMP 1080	
109	C IF(LKLT.GE.1) GO TO 90	SAMP 1090	
110	C LKT = 1	SAMP 1100	
111	C NCI=NCONF	SAMP 1110	

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112 C IDENTIFY THE LEVEL OF SIGNIFICANCE
113 C IF(NINC1.EQ.99) NCONF=2
114 C IF(NINC1.EQ.99) NCONF=1
115 C CONTINUE
116 90
117 C CHANGE FIXED POINT VARIABLES K4 AND K5 TO FLOATING POINT
118 C FK4=FLOAT(K4)
119 C FK5=FLOAT(K5)
120
121 C SPECIFY THE KS VALUE BASED ON THE TYPE OF STATISTIC BEING
122 C COLLECTED AS SPECIFIED BY K3
123 C IF(K3.EQ.1) FK5=1.
124 C IF(K3.EQ.2) FK5=FLOAT((CLOCK)/1000.
125
126 C ADJUST THE K4 VALUE BASED ON THE TYPE OF STATISTIC BEING
127 C COLLECTED AS SPECIFIED BY K3
128 C IF(K3.EQ.2) FK4=FK4*FK5/1000.
129
130 C COUNT THE NUMBER OF OBSERVATIONS THAT HAVE BEEN MADE
131 C IF(K2.LE.1) NOR=0 OR 1
132
133 C
134 C COLLECT AND RETAIN THE STATISTICS FROM THE FIRST 100.SIMS
135 C IF(NOB.LT.2) SAVE(K2,'')=FK4
136 C IF(NOB.LT.2) SAVE(K2,6)=FK5
137 C
138 C IF(NOB.EQ.1) RETURN
139
140 C DETERMINE THE CHANGE IN MEAN FROM THE CURRENT OBSERVATION AND THE SAMPLING
141 C 100TH OBSERVATION
142 C XK2=FK4-SAVE(K2,4)
143 C
144 C DETERMINE THE DIFFERENCES IN MEANS BETWEEN THE CURRENT SAMPLING
145 C OBSERVATION AND THE PREVIOUS OBSERVATION TO OBTAIN A *NEW* MEAN
146 C
147 C X1=XK2-SAVE(K2,1)
148 C SAVE(K2,1)=XK2
149 C XK2=X1
150 C
151 C DETERMINE THE INCREMENT IN BLOCK ENTRIES THAT HAVE OCCURRED
152 C SINCE THE PREVIOUS OBSERVATION
153 C BINCRE=FS-SAVE(K2,6)
154 C
155 C RETAIN THE TOTAL NUMBER OF BLOCK ENTRIES
156 C SAVE(K2,6)=FK5
157
158 C ADJUST THE NEW MEAN BASED ON THE TYPE OF STATISTIC BEING
159 C COLLECTED AS SPECIFIED BY K3
160 C IF(K3.EQ.1) XK2 = XK2*2.
161 C IF(K3.EQ.2) XK2 = XK2*100/BINCR
162 C IF(K3.EQ.3) XK2 = XK2/3INCR
163
164 C
165 C
166 C DETERMINE THE 1 STATISTIC VALUE AND THE ESTIMATED
167 C

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## SAMPLE

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169      C      POPULATION STANDARD DEVIATION          SAMP1680
169      C      SAVE(K2,2) = SAVE(K2,2) + XK2           SAMP1690
170      C      SAVE(K2,3) = SAVE(K2,3) + (XK2*XK2)     SAMP1700
171      C
172      C      IF AN INSUFFICIENT NUMBER OF OBSERVATIONS HAS OCCURRED, RETURN    SAMP1710
173      C      N = NOB                                SAMP1720
174      C      IF(N<LE,2) RETURN                         SAMP1730
175      C      DETERMINE THE DEGREES OF FREEDOM FOR THE STUDENT T DISTRIBUTION    SAMP1740
176      C      NDFREE = N-2                           SAMP1750
177      C      NDFREE = T(NDFREE,GT,31) NDFREE = 31      SAMP1760
178      C
179      C      DETERMINE AND RETAIN THE ESTIMATED DEVIATION          SAMP1770
180      C      CALL,STDV(SAVE(K2,2),SAVE(K2,3),N,STDEV)    SAMP1780
181      C      SAVE(K2,5)=T(NDFREE,NCONF)*STDEV        SAMP1790
182      C
183      C
184      C      RETURN                                SAMP1800
185      C
186      C
187      C
188      C
189      C
190      C
191      C
192      C      60  CONTINUE                            SAMP1830
193      C
194      C      BEGIN OUTPUT OF CONFIDENCE INTERVALS      SAMP1840
195      C
196      C
197      C
198      C      198  OUTPUT FOR TABLE III HEADINGS          SAMP1850
199      C
200      C      WRITE(P,100)                            SAMP1860
201      C      WRITE(P,110)                            SAMP1870
202      C      FORMAT(1H1,40X,*TABLE III* STATISTICAL RESULTS***)
203      C      WRITE(P,110)                            SAMP1880
204      C      110  FORMAT(1H1,35X,*CONFIDENCE INTERVALS ON REQUESTED STATISTICS*)  SAMP1890
205      C      WRITE(P,120)                            SAMP1900
206      C      120  FORMAT(1H1,25X,*WARNING - CONFIDENCE INTERVALS WITH LIMITS OF 0 OR 10* SAMP1910
207      C      10 ARE PROBABLY*)
208      C      WRITE(P,130)                            SAMP1920
209      C      130  FORMAT(35X,*NOTE*,13,* PERCENT CONFIDENCE INTERVALS*)    SAMP1930
210      C      WRITE(P,140) N
211      C      140  FORMAT(1H1,STATISTICS BASED ON*,13,* OBSERVATIONS,*//*)  SAMP1940
212      C      WRITE(P,160) NCL
213      C      160  FORMAT(T83,12,* PERCENT CONFIDENCE INTERVALS*)
214      C      1/T79,*LOWER LIMIT*,7X,MEAN*,6X,*UPPER LIMIT*)   SAMP1950
215      C      WRITE(P,150) NFLTS
216      C      150  FORMAT(1H1,5X,*STATISTICAL CONFIDENCE INTERVALS FOR *,14,* SIMULATI SAMP2110
217      C      1ONS*)                                SAMP2150
218      C
219      C
220      C      OUTPUT FOR THE OPERATIONAL EVALUATION PARAMETERS      SAMP2160
221      C
222      C      DO 50 I=1,9
223      C      AVG=SAVE(1,2)/FLOAT(N)                      SAMP2170
                                         SAMP2180
                                         SAMP2190
                                         SAMP2200
                                         SAMP2210

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224      XLOW=AVG+SAVE(1,5)          SAMP2220
225      HIGH=AVG+SAVE(1,5)          SAMP2230
226      IF (HIGH.GE.100.) HIGH=100.   SAMP2240
227      IF (XLOW.LE.0.) XLOW=0.0    SAMP2250
228      WRITE(P,200)(NHEAD(I,J),J=1,11),XLOW,AVG,HIGH
229      200  FORMAT(I0,X,1A6,1B1,F6.2,BX,F6.2,BX,F6.2)  SAMP2260
230      C                               SAMP2270
231      1FL1,NE,3) GO TO 50          SAMP2280
232      WRITE(P,190)                 SAMP2290
233      190  FORMAT(12X,*REASONS FOR REQUEST FAILURES*)  SAMP2300
234      C                               SAMP2310
235      50  CONTINUE                SAMP2320
236      C                               SAMP2330
237      C                               SAMP2340
238      C   DETERMINE IF ANY USER REQUESTED STATISTICS HAVE BEEN REQUESTED
239      IF(L1.N.LE.9) GO TO 500      SAMP2350
240      C                               SAMP2360
241      C   OUTPUT FOR THE USER REQUESTED STATISTICS      SAMP2380
242      C                               SAMP2390
243      C                               SAMP2400
244      WRITE(P,210)                 SAMP2410
245      210  FORMAT(//,15X,*THE FOLLOWING ARE THE USER REQUESTED STATISTICS*)/, SAMP2420
246      DO 52 I=10,15N               SAMP2430
247      AVGSAVE(I,2)/FLOAT(I,N)     SAMP2440
248      XLOW=AVG+SAVE(1,5)          SAMP2450
249      HIGH=AVG+SAVE(1,5)          SAMP2460
250      IF (HIGH.GE.100.) HIGH=100.0  SAMP2470
251      IF (XLOW.LE.0.) XLOW=0.0    SAMP2480
252      WRITE(P,200)(NHEAD(I,J),J=1,11),XLOW,AVG,HIGH
253      52  CONTINUE                SAMP2500
254      C                               SAMP2510
255      500  WRITE(P,999)           SAMP2520
256      999  FORMAT(1H1)            SAMP2530
257      C                               SAMP2540
258      RETURN                      SAMP2550
259      END                          SAMP2560
                                         SAMP2570
```

RDG,P

STAT

OPRT,S STAT  
FURPUR HA18-06/30-13:31

```

420223•TPFS•STAT      SUBROUTINE STAT
1      COMMON/STATS/NHEAD
2      DIMENSION NHEAD(14,11),ICOM(11)
3      COMMON/STAT3/ISN
4      DATA KEY/4HCONF/,JEND/5HSTART /
5
6      C
7      C   BEGIN SEARCH FOR A STATISTICAL REQUEST
8      C   1  CONTINUE
9      C   10  READ(5,100) ICOM,IREM,NUM
10     C   11  100  FORMAT(IX,10A6,A5,A4,A1)
11
12     C
13     C   IS THIS THE LAST CARD
14     C   15  IF THIS IS THE LAST CARD, RETURN
15     C   16  IF (ICOM(2).EQ.JEND) RETURN
16
17     C
18     C   NO, THIS IS NOT THE LAST CARD
19     C   20  IS THIS A STATISTICAL REQUEST
20     C   21  IF NOT, READ ANOTHER CARD
21
22  IF(KEY.NE.IREM) GO TO 1
23
24  C   THIS CARD IS A STATISTICAL REQUEST
25  C   CONVERT THE ALPHANUMERIC INPUT (NUM) TO NUMERIC
26  C
27  NUM=0
28  NUM=FLD(0,6,NUM)
29
30  C   DETERMINE THE STATISTICAL REQUEST IDENTIFICATION NUMBER
31  C   32  NUM=NUM1+48
32
33  C
34  C   DETERMINE IF THE NUMERIC IDENTIFICATION IS LEGAL
35  C   36  IF NOT, GO TO ERROR IDENTIFICATION ROUTINE
36  C   37  IF (NUM.LT.1).OR.NUM.GT.51 GO TO 3
37
38  C
39  C   STORE HEADING FOR FUTURE REFERENCE
40  C   41  15=N+9
41
42  C   43  DO 2 1=1,11
42  C   44  NHEAD((ISN,1)=1COM(11)
44
45  C   46  READ ANOTHER CARD
46  C   47  GO TO 1
47
48  C
49
50
51
52
53  C   ERROR IDENTIFICATION ROUTINE
54  C
55  C   3  J=J+1

```

```

56      IF(J.GT.J) GO TO 4
57      WRITE(6,300)
58      300  FORMAT(1H1)
59      WRITE(6,310)
60      310  FORMAT(1DX,'THE FOLLOWING HEADING(S) ARE DISREGARDED IN THE CONFIDSTAT 600
61  LENCE INTERVAL./5X,*CALCULATIONS DUE TO AN ILLEGAL C. I. IDENTIFICASTAT 610
62      2TION NUMBER')
63      4   WRITE(6,320) (ICOM(L),L=1,11)
64      320  FORMAT(15X,1A6)
65      C
66      C
67      C  READ ANOTHER CARD
68      C  GO TO 1
69      C  END.

```

@HDG,P STDV

BRT,S STDV  
FURPUR MA18-06/30-13;31

```

42022•TPFS•STDV
      1      SUBROUTINE STDV(XSAVE,N,STDEV)
      2      C
      3      C   ELIMINATE THE ONE OBSERVATION COUNTED FOR THE FIRST 100 SIMULATIONSTDV
      4      N = N - 1
      5
      6      C   IF AN INSUFFICIENT NUMBER OF OBSERVATIONS HAS OCCURRED, RETURN
      7      IF(NLT.2) RETURN
      8      C
      9      C   DETERMINE THE ESTIMATE STANDARD DEVIATION
     10      XN = FLOAT(N)
     11      SIDEV = ABS(XSAVE2-XN)/((XN-1))
     12      STDEV = SQRT(SIDEV)
     13      C
     14      C   ADJUST TO CONFORM WITH CONFIDENCE INTERVAL EQUATION
     15      SIDEV = STDEV/SQRT(1/N)
     16      C
     17      RETURN
     18      END

```

## QHDG,P TABLE I

B-47      TABLE I  
FURPUR HA18-06/30-13:31

  
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## 420223-TPFS-TABLEI

## SUBROUTINE TABLEI

```

1      C
2      C
3      C   TABLEI IS A SUBROUTINE DESIGNED TO BE USED IN CONJUNCTION WITH
4      C   A GPSS PROGRAM CARD DECK. THE FUNCTION OF THIS SUBROUTINE IS TO
5      C   READ EACH CARD IN A GPSS DECK AND DETERMINE IF IT IS A COMMENT
6      C   CARD WITH THE KEY WORD IN COLUMNS 68-71. (THE KEY WORD IS IOST)
7      C   AFTER IT HAS FOUND A COMMENT CARD WITH THE PROPER KEY WORD IT THEN
8      C   READS CARDS UNTIL IT FINDS A HELP CARD. AFTER THE HELP CARD IS FOUND
9      C   THE SUBROUTINE OUTPUT IS CALLED TO PRINT OUT THE INFORMATION
10     C   IN TABULAR FORM
11    C
12    DIMENSION NAME(2),ICOM(11)
13    DATA JAST/LH*7,JHELP/4HHELP/,KEY/6H_IOST/,IEND/6H_END/
14    DATA JEND/6HSTART/
15    C
16    WRITE(6,80)
17    WRITE(6,81)
18    WRITE(6,88)
19    WRITE(6,70)
20    WRITE(6,84)
21    WRITE(6,82)
22    WRITE(6,83)
23    WRITE(6,84)
24    WRITE(6,70)
25    WRITE(6,84)
26    WRITE(6,85)
27    WRITE(6,85)
28    C
29    C   BEGIN THE SEARCH FOR THE NEXT COMMENT CARD AT THIS POINT
30    S CONTINUE
31    READ(5,100) LAST,ICOM,IREM
32    100 FORMAT (A11,A5,2A6,9A6)
33    C
34    C   IS THIS THE LAST CARD
35    1E10COM(12).EQ.JEND) GO TO 999
36    C
37    C   NO, THIS IS NOT THE LAST CARD
38    C   IS THIS CARD A COMMENT CARD
39    C   IF (LAST .NE. JAST) GO TO 5
40    C
41    C   YES, THIS CARD IS A COMMENT CARD
42    C   DOES THIS COMMENT CARD HAVE A KEY
43    C   IF (IREM .NE. KEY) GO TO 5
44    C
45    C   YES, THIS COMMENT CARD HAS A KEY
46    10 CONTINUE
47    READ(5,100) LAST,LOC,NAME,IX,IY,IZ,ISELM,NBA,NBB,MEAN,MOD,IREM
48    C   WAS THE CARD JUST READ A HELP CARD
49    C   IF (JHELP .NE. NAME(1)) GO TO 10
50    C
51    C   YES, THE CARD JUST READ WAS A HELP CARD
52    C   CALL OUTPUT AND PRINT APPROPRIATE INFORMATION
53    CALL OUTPUT(LCOM,LOC,NAME,IX,IY,IZ,ISELM,NBA,NBB,MEAN,MOD)
54    GO TO 5
55    C   YES, THIS IS THE LAST CARD

```

B-48

TABLE I  
999 CONTINUE

```

56      WRITE (6,70)
57      WRITE (6,99)
58      C
59      C    7D FORMAT (1X,130H
60      1
61      2-----)
62      2-----)
63      C
64      80 FORMAT (1H1)
65      C
66      81 FORMAT (44X,***TABLE I. OPERATION TIME DATA IN DAYS***)
67      C
68      82 FORMAT (1X,1H1,2X,9HOPERATION,29X,1H1,2X,
69      1.9HDISTRIBUTION,2X,1H1,16X+14HINPUT DATA FOR,16X,1H1)
70      C
71      83 FORMAT (1X,1H1,2BX,11HDESCRIPTION,26X,1H1,2X,9HTION TYPE,2X,
72      1 H1,12X,23HDISTRIBUTION PARAMETERS,11X,1H1)
73      C
74      84 FORMAT (1X,1H1,67X,1H1,13X,1H1,46X,1H1)
75      C
76      85 FORMAT (1X,1H1,67X,1H1,13X,1H1,17X,1H1,13X,1H1)
77      C
78      88 FORMAT (//)
79      C
80      99 FORMAT (1H1)
81      RETURN
82      END
B-49
      GHUG,P   TRIAG
      SPRT,S   TRIAG
      FURPUR HA18-06/30-13:31

```

```

1 FUNCTION TRIAG(JP)
2 COMMON /HEPL/ PARAM(7,3),LL,ISEED,ISTORE(2,10),IS(2)
3 RNUM = DRAND(ISEED)
4 IF (IRNUM-(PARAM(JP,2)-PARAM(JP,1))/(PARAM(JP,3)-PARAM(JP,1))) .LT. 1.2
5 ITRIAG = PARAM(JP,1)+SQRT(LL*PARAM(JP,3)-PARAM(JP,1))
6 I = PARAM(JP,2)-PARAM(JP,1)*RNUM
7 RETURN
8 X = (PARAM(JP,3)-PARAM(JP,2))*2 -(PARAM(JP,2) - PARAM(JP,3))*
9 (PARAM(JP,2) - PARAM(JP,1)-(PARAM(JP,3)-PARAM(JP,1))*RNUM)
10 TRIAG = PARAM(JP,3) - SQRT(X)
11 RETURN
12 END

```

CHDG, P TRIAGI

OPRT,S TRIAGI  
FURPUR HAI 8-06/30-13:31

TRIAGI

```

42023•TPFS•TRIAGI
1      FUNCTION TRIAGI(JP)
2      COMMON /HEPL/PARAM(7,3),LL,ISEED,ISTORE(2,10),IS(2)
3      RNUM = DRAND(ISEED)
4      IF (RNUM-(PARAM(JP,2)-PARAM(JP,1))/(PARAM(JP,3)-PARAM(JP,1))) > 1.2
5      THEN
6          1. TRIAGI = PARAM(LL,1) + SQRT((PARAM(JP,3)-PARAM(JP,1))*
7          1*(PARAM(JP,2)-PARAM(JP,1))*RNUM)
8          RETURN
9          2 X = (PARAM(JP,3)-PARAM(JP,2))*2 *(PARAM(JP,2) - PARAM(JP,3))
10         1 (PARAM(JP,2) - PARAM(JP,1)-(PARAM(JP,3)-PARAM(JP,1))*RNUM)
11         TRIAGI = PARAM(JP,3) - SQRT(X)
12         RETURN
END

```

@HDG,P UNFRM

```

@PRT,S UNFRM
FURPUR HAI8-06/30-13:31

```

UNFRM DATE 063072 PAGE 1

```
42023•TPFS•UNFRM
1      FUNCTION UNFRM (A,B)
2      COMMON /HEPL/ PARAM(7,3),LL,ISEED,ISTORE(2,10),IS(2)
3      RNUM=DRAND(ISEED)
4      UNFRM = A+(B-A)*RNUM
5      RETURN
6      END
```

```
@HDG,P      UNFRM1
```

```
@PRT,S      UNFRM1
FURPUR HA1B-06/30-1331
```

UNIFORM DATE 063072 PAGE 1

```

420223@PF$•UNFRM1
1      FUNCTION UNFRM1(A,B)
2      COMMON /HEPL/ PARAM(7,3)LL,ISEED,1SEED1,1STORE(12,10),IS(2)
3      RNUM=DRAINDL(ISEED1)
4      UNFRM1 = A+(B-A)*RNUM
5      RETURN
6      END

```

**APPENDIX C. EXAMPLE TABLE1 OUTPUT**

TABLE I. OPERATION TIME DATA IN DAYS

PRECEDING PAGE BLANK NOT FILMED

OPERATION DESCRIPTION	DISTRIBU- TION TYPE	INPUT DATA FOR DISTRIBUTION PARAMETERS
HATE BOOSTER, ORBITER AND LUT	TRIANGULAR	MIN = 1.0000 MODE = 2.0000 MAX = 2.2000
COUNTDOWN PREPARATION	TRIANGULAR	MIN = 1.5000 MODE = 2.0000 MAX = 2.5000
FINAL COUNTDOWN	CONSTANT	MEAN = .0830
REMOVE POST LAUNCH LUT FROM PAD	TRIANGULAR	MIN = 1.2500 MODE = 1.5000 MAX = 1.7500
TRANSPORT LUT TO MAINT., REFURBISH/TEST, TRANSPORT TO STORAGE	TRIANGULAR	MIN = 2.7000 MODE = 3.0000 MAX = 3.3000
REFURBISH LAUNCH PAD	TRIANGULAR	MIN = .9500 MODE = 1.0000 MAX = 1.0500
LIFTOFF THROUGH SEPARATION	CONSTANT	MEAN = .0020
BOOSTER COAST, REENTRY, PLYBACK AND LANDING	TRIANGULAR	MIN = .0640 MODE = .0700 MAX = .0740
BOOSTER SAFING	TRIANGULAR	MIN = .9000 MODE = 1.0000 MAX = 1.1000
TRANSPORT BOOSTER TO MAINTENANCE	TRIANGULAR	MIN = .0500 MODE = .1000 MAX = .1500
BOOSTER MAINTENANCE	TRIANGULAR	MIN = 2.0250 MODE = 2.5000 MAX = 2.7500
BOOSTER ADDITIONAL MAINTENANCE	EXPONENTIAL	MIN = .5000 MEAN = 1.0000
TRANSPORT BOOSTER TO SYSTEMS TEST, TEST, TRANSPORT TO STORAGE	TRIANGULAR	MIN = 1.9000 MODE = 2.0000 MAX = 2.1000
ORBITER SAFING	TRIANGULAR	MIN = .9000 MODE = 1.0000 MAX = 1.1000
TRANSPORT ORBITER TO MAINTENANCE	TRIANGULAR	MIN = .0500 MODE = .1000 MAX = .1600
ORBITER MAINTENANCE	TRIANGULAR	MIN = 2.2500 MODE = 2.5000 MAX = 2.7500
ORBITER ADDITIONAL MAINTENANCE	EXPONENTIAL	MIN = .5000 MEAN = 1.0000
TRANSPORT ORBITER TO SYSTEMS TEST, TEST, TRANSPORT TO STORAGE	TRIANGULAR	MIN = 1.9000 MODE = 2.0000 MAX = 2.1000
REMOVE BOOSTER, ORBITER AND LUT FROM THE PAD	TRIANGULAR	MIN = 1.6000 MODE = 2.0000 MAX = 2.2000
TRANSPORT VEHICLE, SEPARATE ORBITER, TRANSPORT ORBITER TO MAINT.	TRIANGULAR	MIN = .5500 MODE = .7500 MAX = .9500
SEPARATE BOOSTER FROM LUT, TRANSPORT BOOSTER TO MAINTENANCE	TRIANGULAR	MIN = .6500 MODE = .7500 MAX = .9500
BOOSTER MAINTENANCE ON RETURN FROM PAD	EXPONENTIAL	MIN = .6000 MEAN = .7500
BOOSTER VEHICLE SYSTEM TEST FACILITY ON RETURN FROM PAD	TRIANGULAR	MIN = 1.9000 MODE = 2.0000 MAX = 2.1000
ORBITER MAINTENANCE ON RETURN FROM PAD	EXPONENTIAL	MIN = .5000 MEAN = 7.5000
ORBITER VEHICLE SYS TEST FACILITY ON RETURN FROM PAD	TRIANGULAR	MIN = 1.9000 MODE = 2.0000 MAX = 2.1000

**APPENDIX D. SAMPLE SOS MODEL OUTPUT**

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•••TABLE II. SUMMARY RESULTS•••

CASE STUDY I DETERMINATION OF FLEET SIZE REQUIREMENTS

INITIAL CONDITIONS	BOOSTER	ORBITER
NUMBER OF VEHICLE STAGES	4	5
SERVICE CAPACITY OF SAFING AREA	1	1
SERVICE CAPACITY OF MAINTENANCE FACILITY	1	2
SERVICE CAPACITY OF CHECKOUT & TEST FACILITY	2	2
SERVICE CAPACITY OF HATE & HOOK-UP FACILITY	1	
SERVICE CAPACITY OF LUT REFURBISHMENT FACILITY	2	
NUMBER OF LUTS <sup>a</sup>	3	
NUMBER OF LAUNCH PADS <sup>b</sup>	2	

TRAFFIC MODEL STATISTICS<sup>c</sup>

MISSION MODEL LAUNCH RATE (FLIGHTS/YEAR) - 53  
DISTRIBUTION OF TIME BETWEEN LAUNCH REQUESTS -

• 8% OF LAUNCHES ARE SCHEDULED 1 DAY APART

14.1% OF LAUNCHES ARE SCHEDULED 2 DAYS APART

48.6% OF LAUNCHES ARE SCHEDULED 3 DAYS TO 1 WEEK APART

35.3% OF LAUNCHES ARE SCHEDULED 1 WEEK TO 2 WEEKS APART

1.2% OF LAUNCHES ARE SCHEDULED 2 WEEKS TO 1 MONTH APART

OPERATIONAL EVALUATION PARAMETERS FOR SO2-SIMULATIONS<sup>d</sup>

THE NUMBER OF SUCCESSFUL LAUNCH REQUESTS ARE 984 OR 96.4 PERCENT

THE NUMBER OF UNSUCCESSFUL REQUESTS ARE 18 OR 3.6 PERCENT

THE NUMBER OF VEHICLES LAUNCHED AT A SUBSEQUENT WINDOW IS 7 OR 1.4 PERCENT  
REASONS FOR REQUEST FAILURES<sup>e</sup>

BOOSTER UNAVAILABILITY 5 TIMES OR 1.0 PERCENT

ORBITER UNAVAILABILITY 0 TIMES OR .0 PERCENT

BOTH STAGES UNAVAILABLE 0 TIMES OR .0 PERCENT

LUT UNAVAILABILITY 1 TIMES OR .2 PERCENT

PAD UNAVAILABILITY 0 TIMES OR .0 PERCENT

FAILURES AND REMOVAL FROM PAD 12 TIMES OR 2.4 PERCENT

AVERAGE PHASE TIMES PER VEHICLE ELEMENTS	BOOSTER	ORBITER
LANDING TO STORAGE(DAYS)	6.12	5.87
STORAGE(DAYS)	7.93	9.67
LEAVE STORAGE TO LAUNCH(DAYS)	5.32	5.32
MEAN ON-ORBIT MISSION TIME(DAYS)	3.42	
TURNAROUND- LAUNCH TO LAUNCH(DAYS)	19.37	24.29

	BOOSTER	ORBITER
PERCENT OF VEHICLES DELAYED FOR SAFING	.00	3.93
AVERAGE QUEUE TIME FOR SAFING(DAYS)	.00	.32
PERCENT OF VEHICLES DELAYED FOR MAINT.	9.48	.61
AVERAGE QUEUE TIME FOR MAINTENANCE(DAYS)	2.69	.16
PERCENT OF VEHICLES DELAYED FOR CHECKOUT & TEST	.00	.00
AVERAGE QUEUE TIME FOR CHECKOUT & TEST(DAYS)	.00	.00
PERCENT OF VEHICLES DELAYED FOR MATE & HOOKUP(DAYS)	.40	.63
AVERAGE QUEUE TIME FOR MATE & HOOKUP(DAYS)	.00	.20
PERCENT OF LUTS DELAYED FOR REFURBISHMENT	.00	.00
AVERAGE QUEUE TIME FOR LUT REFURBISH FACILITY	.00	.00
PERCENT OF VEHICLES DELAYED FOR PAD ACCESS	.00	.00
AVERAGE QUEUE TIME FOR PAD(DAYS)	.00	.00
 FACILITY UTILIZATION:		
SAFING AREA(PERCENT)	19.80	19.90
MAINTENANCE(PERCENT)	57.70	29.90
CHECKOUT & TEST(PERCENT)	20.30	20.30
MATE & HOOK-UP(PERCENT)	40.90	
LUT REFURBISHMENT(PERCENT)	30.50	
 PAD UTILIZATION:		
LAUNCH PAD 1 (PERCENT)	68.70	
LAUNCH PAD 2 (PERCENT)	30.00	

THE FLEET SIZE IS 4 BOOSTERS & 5 ORBITERS  
 RANDOM NUMBER SEED FOR TRAFFIC MODEL SIMULATOR 0  
 RANDOM NUMBER SEED FOR DISTRIBUTION FUNCTIONS 0

CLOCK TIME REL 2426161 ABS 2428181

TRANS COUNTS	BLOCK TRANS, TOTAL					
1	0	2	0	1	5	0
6	1	7	1	6	1	1
11	0	12	0	13	0	1
16	0	17	0	18	1	14
21	0	503	22	503	23	503
26	0	503	27	503	28	503
31	0	503	32	503	33	503
36	0	502	37	503	38	503
41	0	503	42	503	43	503
46	0	497	47	498	48	498
51	0	497	52	497	53	497
56	0	497	57	497	58	497
61	0	497	62	497	63	497
66	0	497	67	497	68	497
71	0	345	72	151	73	0
76	0	77	0	496	78	0
81	0	496	82	0	496	83
86	0	496	87	0	496	88
91	0	504	92	504	93	0
96	0	477	97	0	477	98
101	0	12	102	0	8	103
106	0	0	107	0	0	108
111	0	0	112	0	0	113
116	0	8	117	0	8	118
121	0	484	122	0	484	123
126	0	483	127	1	967	128
131	0	495	132	0	495	133
136	0	484	137	0	484	138
141	0	483	142	0	484	143
146	0	484	147	0	484	148
151	0	484	152	0	484	153
156	0	484	157	0	484	158
161	0	484	162	0	484	163
166	0	484	167	1	484	168
171	0	483	172	0	483	173
176	0	483	177	0	483	178
181	0	484	182	0	484	183
186	0	483	187	0	483	188
191	0	483	192	0	483	193
196	1	483	197	0	483	198
201	0	482	202	0	482	203
206	0	482	207	0	482	208



2	3	.05	496	449	90.52	254.53	2666.09	0	0
3	1	.00	495	495	100.00	.00	.00	0	0
10	1	.00	483	464	96.07	15.54	395.00	0	0
11	1	.00	495	492	99.39	.96	159.00	0	0
12	1	.00	494	494	100.00	.00	.00	0	0
16	1	.00	495	494	99.60	.00	.00	0	0
20	1	.00	497	495	99.60	2.54	631.50	0	0
21	1	.00	496	496	100.00	.00	.00	0	0
29	1	.00	503	503	100.00	.00	.00	0	0
31	1	.00	503	503	100.00	.00	.00	0	0

TABLE NUMBER 1

ENTRIES IN TABLE		MEAN ARGUMENT 6.21.199		STANDARD DEVIATION 1634.808		NON-WEIGHTED	
483		OBSERVED	PERCENT OF TOTAL	CUMULATIVE PERCENTAGE	CUMULATIVE REMAINDER	MULTIPLE OF MEAN	DEVIATION FROM MEAN
		UPPER LIMIT	OBSERVED FREQUENCY	.00	100.0	.817	-.686
5000	0	74	15.32	15.3	89.7	.899	-.380
5500	0	264	54.66	50.0	30.0	.980	-.074
6000	1	63	13.04	83.0	17.0	1.062	.232
6500	1	39	8.07	91.1	8.9	1.144	.538
7000	1	18	3.73	94.8	5.2	1.225	.843
7500	1	10	2.07	96.9	3.1	1.307	1.149
8000	0	0	.00	96.9	3.1	1.389	1.455
8500	0	4	.83	97.7	2.3	1.470	1.761
9000	1	21	2.21	97.9	2.1	1.552	2.067
9500	1	0	.00	97.9	2.1	1.634	2.373
10000	0	0	.00	98.1	1.9	1.715	2.678
10500	1	21	.41	98.6	1.4	1.797	2.984
11000	2	0	.00	98.6	1.4	1.879	3.290
11500	0	0	.00	98.6	1.4	1.960	3.596
12000	1	21	.21	98.8	1.2	2.042	3.902
12500	0	0	.00	98.8	1.2	2.124	4.208
13000	0	0	.00	98.8	1.2	2.205	4.514
13500	0	0	.00	98.8	1.2	2.287	4.819
14000	0	0	.00	98.8	1.2		
OVERFLOW	6	1	.24	100.0	.0		

ENTRIES IN TABLE		MEAN ARGUMENT 7926.986		STANDARD DEVIATION 3142.907		NON-WEIGHTED	
497		OBSERVED	PERCENT OF TOTAL	CUMULATIVE PERCENTAGE	CUMULATIVE REMAINDER	MULTIPLE OF MEAN	DEVIATION FROM MEAN
		UPPER LIMIT	OBSERVED FREQUENCY	.00	100.0	0.000	-.522
500	0	2	.40	.4	.996	0.063	-.363
1000	3	.60	1.00	1.0	.99.0	1.126	.204
1500	6	1.21	2.02	1.21	.97.8	1.169	.045
2000	8	1.61	3.08	1.61	.96.2	1.252	.886
2500	4	.80	1.24	1.24	.95.4	1.315	1.727

3000	8	1.61	6.2	93.8	*378
3500	13	2.62	8.9	91.1	*1.568
4000	6	1.21	10.1	89.9	*1.409
4500	20	4.02	14.1	85.9	*1.249
5000	18	3.62	17.7	82.3	*1.090
5500	25	5.03	22.7	77.3	*568
6000	27	5.43	28.2	71.8	*505
6500	21	4.23	32.4	67.6	*594
7000	27	5.43	37.8	62.2	*631
7500	26	5.23	43.1	56.9	*694
8000	37	7.44	50.5	49.5	*772
8500	25	5.03	55.5	49.5	*613
9000	34	6.84	62.4	47.6	*454
9500	28	5.63	68.0	37.6	*454
10000	32	6.44	74.4	32.0	*295
10500	24	4.83	79.3	25.4	*1.36
11000	25	5.03	84.3	20.7	*0.23
11500	18	3.62	87.9	15.7	*1.82
12000	19	3.82	91.8	12.1	*341
12500	12	2.41	94.2	8.2	*500
13000	5	1.01	95.2	6.8	*500
13500	4	1.21	96.4	5.6	*500
14000	5	1.01	97.4	2.6	*500
OVERTLOW	13	2.62	100.0	0.0	*500

TABLE NUMBER 3  
ENTRIES IN TABLE  
MEAN ARGUMENT  
19392.867  
483

UPPER LIMIT	OBSERVED FREQUENCY	PERCENT OF TOTAL	CUMULATIVE PERCENTAGE	CUMULATIVE REMAINDER	MULTIPLE OF MEAN	DEVIATION FROM MEAN
9000	0	0.00	0.0	100.0	*490	*2.880
9500	0	0.00	0.0	100.0	*516	*2.734
10000	0	0.00	0.0	100.0	*541	*2.588
10500	0	0.00	0.0	100.0	*567	*2.443
11000	0	0.00	0.0	100.0	*593	*2.297
11500	1	0.21	0.2	99.8	*619	*2.152
12000	3	0.62	0.8	99.2	*645	*2.006
12500	2	0.41	1.2	98.8	*670	*1.861
13000	6	1.24	2.5	97.5	*696	*1.715
13500	5	1.04	3.5	96.5	*722	*1.570
14000	8	1.66	5.2	94.8	*748	*1.424
14500	15	3.11	8.3	91.7	*773	*1.279
15000	8	1.66	9.9	90.1	*800	*1.133
15500	15	3.11	13.0	87.0	*825	*0.988
16000	12	2.48	15.5	84.5	*851	*0.842
16500	18	3.73	19.3	80.7	*877	*0.696
17000	22	4.55	23.8	76.2	*902	*0.551
17500	26	5.38	29.2	70.8	*928	*0.405
18000	21	4.35	33.5	66.5	*954	*0.260
18500	20	4.14	37.7	62.3	*980	*0.114
19000	42	6.70	46.4	53.6	*0.031	*0.006
19500	24	4.97	51.3	51.3		

20000	35	7.25	58.6	41.4	1.031	.177
20500	17	3.52	62.1	37.9	1.057	.322
21000	31	6.42	68.5	31.5	0.083	.468
21500	31	6.42	74.9	25.1	1.019	.613
22000	32	6.63	81.6	18.4	1.34	.759
22500	17	3.52	85.1	14.9	1.160	.904
23000	14	2.90	88.0	12.0	1.186	1.050
OVERFLOW	58	12.01	100.0	0.0		

TABLE NUMBER 4

ENTRIES IN TABLE 496

MEAN ARGUMENT  
1207.008STANDARD DEVIATION  
225.094

UPPER LIMIT	OBSERVED FREQUENCY	PERCENT OF TOTAL	CUMULATIVE PERCENTAGE	CUMULATIVE REMAINDER	MULTIPLE OF MEAN	DEVIATION FROM MEAN
0	0	0.00	0.0	100.0	0.000	+5.362
100	0	0.00	0.0	100.0	0.083	-4.918
200	0	0.00	0.0	100.0	0.166	-4.474
300	1	0.20	0.2	99.8	0.249	-4.029
400	0	0.00	0.2	99.8	0.331	-3.585
500	2	0.40	0.6	99.4	0.414	-3.141
600	2	0.40	1.0	99.0	0.497	-2.697
700	5	1.01	2.0	98.0	0.580	-2.252
800	10	2.02	4.0	96.0	0.663	-1.808
900	25	5.04	9.01	90.9	0.746	-1.364
1000	38	7.66	16.7	83.3	0.828	-0.920
1100	58	11.69	28.4	71.6	0.911	-0.475
1200	89	17.94	46.4	53.6	0.994	-0.031
1300	97	19.56	65.9	34.1	1.077	+0.413
1400	80	16.13	82.1	17.9	1.160	+0.857
1500	43	8.67	90.7	9.3	1.243	1.302
1600	30	6.05	96.8	3.2	1.326	1.746
1700	12	2.42	99.2	0.8	1.408	2.190
1800	4	0.81	100.0	0.0	1.491	2.634

REMAINING FREQUENCIES ARE ALL ZERO

D-8

TABLE NUMBER 5

ENTRIES IN TABLE 8

MEAN ARGUMENT  
681.625STANDARD DEVIATION  
246.855

UPPER LIMIT	OBSERVED FREQUENCY	PERCENT OF TOTAL	CUMULATIVE PERCENTAGE	CUMULATIVE REMAINDER	MULTIPLE OF MEAN	DEVIATION FROM MEAN
0	0	0.00	0.0	100.0	0.000	+2.761
100	0	0.00	0.0	100.0	0.147	-2.356
200	0	0.00	0.0	100.0	0.293	-1.951
300	1	12.50	12.5	87.5	0.440	-1.546
400	0	0.00	12.5	87.5	0.587	-1.141
500	0	0.00	12.5	87.5	0.734	-0.736
600	3	37.50	50.0	50.0	0.880	-0.311
700	0	0.00	50.0	50.0	1.027	0.074

800	0	.00	50.0	50.0	1.174	.480
900	0	.00	50.0	50.0	1.320	.885
1000	4	50.00	100.0	100.0	1.467	1.290
REMAINING FREQUENCIES ARE ALL ZERO						

TABLE NUMBER 6  
ENTRIES IN TABLE 997

		MEAN ARGUMENT 9.835	STANDARD DEVIATION 82.668	NON-WEIGHTED	
UPPER LIMIT	OBSERVED FREQUENCY	PERCENT OF TOTAL	CUMULATIVE PERCENTAGE	CUMULATIVE REMAINDER	MULTIPLE OF MEAN
0	489	98.39	98.4	1.6	*0.000
100	0	0.00	98.4	1.6	*0.119
200	0	0.00	98.4	1.6	1.091
300	2	.40	98.6	1.6	2.300
400	0	0.00	98.8	1.2	3.510
500	0	0.00	98.8	1.2	4.720
600	2	.40	99.2	1.2	5.929
700	0	0.00	99.2	0.8	7.139
800	2	.40	99.4	0.8	8.349
900	1	.20	99.6	0.4	9.558
1000	1	.20	100.0	0.0	10.768
REMAINING FREQUENCIES ARE ALL ZERO					11.978

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TABLE NUMBER 8  
ENTRIES IN TABLE 7

		MEAN ARGUMENT 731.000	STANDARD DEVIATION 246.165	NON-WEIGHTED	
UPPER LIMIT	OBSERVED FREQUENCY	PERCENT OF TOTAL	CUMULATIVE PERCENTAGE	CUMULATIVE REMAINDER	MULTIPLE OF MEAN
0	0	0.00	0.0	100.0	*0.000
100	0	0.00	0.0	100.0	*2.970
200	0	0.00	0.0	100.0	*2.563
300	0	0.00	0.0	100.0	*2.167
400	1	1.429	14.3	85.7	*1.751
500	0	0.00	14.3	85.7	*1.345
600	3	42.86	57.1	42.9	*0.938
700	0	0.00	57.1	42.9	*0.532
800	0	0.00	57.1	42.9	*0.126
900	0	0.00	57.1	42.9	*0.280
1000	3	42.86	100.0	0.0	*0.687
REMAINING FREQUENCIES ARE ALL ZERO					1.093

TABLE NUMBER 9  
ENTRIES IN TABLE 484

		MEAN ARGUMENT 1.019	STANDARD DEVIATION 1.019	NON-WEIGHTED	
UPPER LIMIT	OBSERVED FREQUENCY	PERCENT OF TOTAL	CUMULATIVE PERCENTAGE	CUMULATIVE REMAINDER	MULTIPLE OF MEAN
0	0	0.00	0.0	100.0	*0.000
1	1	1.000	1.000	0.0	*1.019
2	0	0.00	0.0	100.0	1.019

UPPER LIMIT	OBSERVED FREQUENCY	PERCENT OF TOTAL	CUMULATIVE PERCENTAGE	CUMULATIVE REMAINDER	MULTIPLE OF MEAN
0	0	0.0	0.0	100.0	-8.497
1	477	90.55	98.6	1.4	-0.121
2	7	1.45	100.0	0.0	0.255
REMAINING FREQUENCIES ARE ALL ZERO					

TABLE NUMBER 10

## ENTRIES IN TABLE

484

MEAN ARGUMENT  
5325.473

UPPER LIMIT	OBSERVED FREQUENCY	PERCENT OF TOTAL	CUMULATIVE PERCENTAGE	CUMULATIVE REMAINDER	MULTIPLE OF MEAN
0	0	0.0	0.0	100.0	-42.514
500	0	0.0	0.0	100.0	-38.522
1000	0	0.0	0.0	100.0	-34.531
1500	0	0.0	0.0	100.0	-30.539
2000	0	0.0	0.0	100.0	-26.548
2500	0	0.0	0.0	100.0	-22.556
3000	0	0.0	0.0	100.0	-18.565
3500	0	0.0	0.0	100.0	-14.573
4000	0	0.0	0.0	100.0	-10.581
4500	1	0.2	0.2	99.8	-6.590
5000	5	1.03	1.2	98.8	-2.598
5500	471	97.31	98.6	1.4	1.393
6000	4	0.83	99.4	0.6	5.385
6500	3	0.62	100.0	0.0	9.376
REMAINING FREQUENCIES ARE ALL ZERO					

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TABLE NUMBER 21

## ENTRIES IN TABLE

482

STANDARD DEVIATION

125.264

NON-WEIGHTED

UPPER LIMIT	OBSERVED FREQUENCY	PERCENT OF TOTAL	CUMULATIVE PERCENTAGE	CUMULATIVE REMAINDER	MULTIPLE OF MEAN
5000	0	0.0	0.0	100.0	-1.752
5500	60	12.45	12.4	87.6	-0.937
6000	294	61.00	73.4	26.6	1.022
6500	73	15.15	88.6	11.4	1.107
7000	35	7.26	95.9	4.1	1.192
7500	12	2.49	98.3	1.7	1.277
8000	5	1.04	99.4	0.6	1.362
8500	3	0.62	100.0	0.0	1.447
REMAINING FREQUENCIES ARE ALL ZERO					

TABLE NUMBER 22

## ENTRIES IN TABLE

STANDARD DEVIATION

498.013

NON-WEIGHTED

UPPER LIMIT	OBSERVED FREQUENCY	PERCENT OF TOTAL	CUMULATIVE PERCENTAGE	CUMULATIVE REMAINDER	MULTIPLE OF MEAN
5000	0	0.0	0.0	100.0	-1.752
5500	60	12.45	12.4	87.6	-0.937
6000	294	61.00	73.4	26.6	1.022
6500	73	15.15	88.6	11.4	1.107
7000	35	7.26	95.9	4.1	1.192
7500	12	2.49	98.3	1.7	1.277
8000	5	1.04	99.4	0.6	1.362
8500	3	0.62	100.0	0.0	1.447
REMAINING FREQUENCIES ARE ALL ZERO					

497

9673.145

3591.861

NON-WEIGHTED

UPPER LIMIT	OBSERVED FREQUENCY	PERCENT OF TOTAL	CUMULATIVE PERCENTAGE	CUMULATIVE REMAINDER	MULTIPLE OF MEAN FROM MEAN
0	1	.20	.2	99.8	+2.693
500	0	.00	.2	99.8	-2.554
1000	0	.00	.2	99.8	-2.415
1500	2	.40	.6	99.4	-2.275
2000	1	.20	.8	99.2	-2.136
2500	4	.80	1.6	98.4	+1.997
3000	7	1.41	3.0	97.0	+1.858
3500	5	1.01	4.0	96.0	+1.719
4000	7	1.41	5.4	94.6	+1.579
4500	9	1.81	7.2	92.8	+1.440
5000	12	2.41	9.7	90.3	+1.301
5500	12	2.41	12.1	87.9	+1.162
6000	17	3.42	15.5	84.5	+1.023
6500	21	4.23	19.7	80.3	+0.883
7000	25	5.03	24.7	75.3	+0.744
7500	14	2.82	27.6	72.4	+0.605
8000	28	5.63	33.2	66.8	+0.466
8500	23	4.63	37.8	62.2	+0.327
9000	26	5.23	43.1	56.9	+0.187
9500	18	3.62	46.7	53.3	+0.048
10000	35	7.04	53.7	46.3	+0.034
10500	29	5.84	59.6	40.4	+0.085
11000	28	5.63	65.2	34.8	+0.137
11500	26	5.23	70.4	29.6	+0.189
12000	22	4.43	74.8	25.2	+0.241
12500	16	3.22	78.1	21.9	+0.292
13000	24	4.83	82.9	17.1	+0.344
13500	14	2.82	85.7	14.3	+0.396
14000	18	3.62	89.3	10.7	+0.447
OVERFLOW	53	10.66	100.0	0.0	+0.205

TABLE NUMBER 23  
ENTRIES IN TABLEMEAN ARGUMENT  
20915.421

3612.657

UPPER LIMIT	OBSERVED FREQUENCY	PERCENT OF TOTAL	CUMULATIVE PERCENTAGE	CUMULATIVE REMAINDER	MULTIPLE OF MEAN FROM MEAN
9000	0	.00	.0	100.0	+3.298
9500	0	.00	.0	100.0	+3.160
10000	0	.00	.0	100.0	+3.021
10500	0	.00	.0	100.0	+2.883
11000	1	.21	.2	99.8	+2.745
11500	0	.00	.2	99.6	+2.606
12000	0	.00	.2	99.4	+2.468
12500	2	.41	.6	99.4	+2.329
13000	3	.62	1.2	98.8	+2.191
13500	4	.83	2.1	97.9	+2.053
14000	4	.83	2.9	97.1	+1.914
14500	6	1.24	4.1	95.9	+1.776

15000	4	.63	5.0	95.0	=1.637
15500	7	1.45	6.4	93.6	=1.499
16000	7	1.45	7.9	92.1	=1.361
16500	14	2.90	10.8	89.2	=1.222
17000	15	3.11	13.9	86.1	=1.084
17500	17	3.53	17.4	82.6	=.945
18000	20	4.15	21.6	78.4	=.807
18500	17	3.53	25.1	74.9	=.669
19000	23	4.77	29.9	70.1	=.530
19500	25	5.19	35.1	64.9	=.392
20000	25	5.19	40.2	59.8	=.253
20500	22	4.56	44.8	55.2	=.115
21000	29	6.02	50.8	49.2	=.023
21500	29	6.02	56.8	43.2	=.162
22000	22	4.56	61.4	38.6	=.300
22500	29	6.02	67.4	32.6	=.439
23000	21	4.36	71.8	28.2	=.100
OVERFLOW	136	28.22	100.0	.0	

FUTURE RANDOM NUMBER SEED IS (OCTAL)

277404621561

**APPENDIX E. SAMPLE CONFIDENCE INTERVAL OPTION OUTPUT**

## TABLE III. STATISTICAL RESULTS

## CONFIDENCE INTERVALS ON REQUESTED STATISTICS

**WARNING - CONFIDENCE INTERVALS WITH LIMITS OF 0 OR 100 ARE PROBABLY NOT 99 PERCENT CONFIDENCE INTERVALS**

**STATISTICS BASED ON 6 OBSERVATIONS.**

## 99 PERCENT CONFIDENCE INTERVALS

LOWER LIMIT

MEAN

UPPER LIMIT

## STATISTICAL CONFIDENCE INTERVALS FOR 500 SIMULATIONS.

THE PERCENTAGE OF SUCCESSFUL LAUNCH REQUESTS

38.06

41.50

44.94

THE PERCENTAGE OF UNSUCCESSFUL LAUNCH REQUESTS

55.91

58.75

61.69

THE PERCENTAGE OF VEHICLES LAUNCHED AT A SUBSEQUENT WINDOW

3.37

7.50

11.63

## REASONS FOR REQUEST FAILURES:

T

BOOSTER UNAVAILABILITY

.00

.00

.00

N

ORBITER UNAVAILABILITY

.00

.00

.00

B

BOTH STAGES UNAVAILABLE

.00

.00

.00

L

LUT UNAVAILABILITY

55.69

57.75

59.81

P

PAD UNAVAILABILITY

.00

.00

.00

F

FAILURES AND REMOVAL FROM PAD

.00

1.00

2.32

## THE FOLLOWING ARE THE USER REQUESTED STATISTICS

TIME FROM LANDING TO STORAGE (BOOSTER)	5.69	5.87	6.05
ORBITER SAFING FACILITY UTILIZATION (PERCENT)	11.28	12.84	14.40
LAUNCH PAD 1 UTILIZATION (PERCENT)	40.33	42.41	44.48
BOOSTER SAFING QUEUE TIME	.00	.00	.00
ORBITER MAINTENANCE QUEUE TIME	.00	.00	.00

## APPENDIX F. EXPLANATION OF INDIVIDUAL CONTROL CARDS

This appendix gives a brief operational description of the various control cards contained in the example deck setups shown in the document. Further information about these control statements is given in the MSFC Program Procedures Manual with the page numbers in parentheses. (Refer to Figure F-1 for the correct column positioning).

### 1. @ADD MODEL.

This card will add the contents of file MODEL to the run stream. This card must follow the @XQT GPSSE8. MAPGPS card for each execution of the GPSS program. (6.3.1-80)

### 2. @ASG, T NAME, F2

This control card assigns a temporary file location called NAME on a magnetic drum unit. The F2 represents the type of drum selected for mass storage. Note that an @ASG card must be used for each file referenced within the run. (6.3.1-29)

### 3. @ASG, T TAPENAME, T, SAVEXX

This card creates a tape called TAPENAME and is maintained in the MSFC tape library for the time specified by the code XX. The code XX represents the following:  
(Technical Bulletin No. 17)

- 02--14 day retention
- 03--30 day retention
- 04--90 day retention
- 05--6 month retention

### 4. @ASG, T TAPENAME, T, 12345

This card assigns the use of a tape drive to the run. In this example, the tape file is called TAPENAME and reel number 12345 is loaded onto the drive unit. (6.3.1-33)

### 5. @BRKPT PUNCH\$

This card causes the current normal punch file to be closed and queued for punching and starts a new normal punch file. (6.3.1-101)

6. @BRKPT PUNCH\$/FN  
This statement causes the current normal punch file to be closed and queued for printing and routes all future output of the normal punch type to a file whose name is FN. The file whose name is FN must be currently assigned to the run. (6.3.1-102)
7. @COPIN TAPENAME, GPSSE8.  
This card causes the transfer of the program instruction from the tape called TAPENAME, to a file name GPSSE8. (6.3.1-147)
8. @COPIN TAPENAME, TPF\$.  
This card causes the transfer of the program instructions from the tape, called TAPENAME, to a temporary program file. (6.3.1-148)
9. @COPOUT GPSSE8, TAPENAME  
This card is a reverse operation of the @COPIN card. The program instructions are transferred from the file GPSSE8 to the tape named TAPENAME. (6.3.1-146)
10. @COPY, G TAPENAME, MODEL.  
This control card causes the transfer of a data file (the GPSS System Model Description) from the tape named TAPENAME to a drum location named MODEL. (6.3.1-144)
11. @COPY, GM MODEL, TAPENAME  
This represents the reverse operation of the @COPY, G TAPENAME, MODEL. command. (6.3.1-144)
12. @COPY, RSA MASTER\*GPSSE8., GPSSE8.  
This control card is used to command execution from a drum file. This card copies from the drum a program called MASTER\*GPSSE8 into temporary location named GPSSE8. (6.3.1-144)
13. @DATA FILE2, MODEL  
This control card permits the updating of the GPSS model network contained on a file named FILE2. The new revision is stored in a file named MODEL (corrections or changes to MODEL follow this control card and FILE2 remains unchanged). (6.3.1-97)
14. @DATA, L DUMMYP, MODEL  
This control allows the revision of the DUMMYP file and creates an updated file named MODEL. The revisions to DUMMYP follow this control card. A listing of the data in MODEL is then generated. (6.3.1-97).

15. @END  
This control card marks the end of the data corrections following the DATA control card. (6.3.1-98)
16. @ERS GPSSE8.  
This control card will erase all contents of the program file named GPSSE8. (This card is used in decks that generate a new program file.) (6.3.1-156)
17. @FIN  
Signifies the end of the control deck. (This is the last card on all deck setups.) (6.3.1-80)
18. @FOR, US GPSSE8.NAME, GPSSE8.NAME  
Control card used to include a new or modified Fortran user written subroutine in the GPSS run stream. The word NAME should be replaced on the control card with the title of the subroutine. The U option allows modification of individual cards in the subroutine. An I option allows the inclusion of an entire subroutine package but not the updating of individual cards (6.3.1-103)
19. @FREE TAPENAME  
Releases the tape called TAPENAME. (In cases where the information on the tape has been copied onto the drums, the tape drive unit is no longer needed and, therefore, released from the run.) (6.3.1-88)
20. @HDG, P CASE STUDY TITLE  
This heading card prints any desired title on the top of each page of the printout. The page number and data are also printed. All columns on the card can be used. In this case, the title CASE STUDY TITLE is printed on top of each page of output. (6.3.1-124)
21. @MAP, LX GPSSE8.MAP, GPSSE8.MAPGPS  
This card causes the collection of all program elements into the program instruction element by the name of MAPGPS. (6.6-4)
22. @MOVE TAPENAME, 2  
This control card is used for positioning the tape called TAPENAME at the beginning of the selected file. (The example indicates the movement of the tape past 2 files from its present position.) (6.3.1-137)
23. @PREP GPSSE8.  
This command is used to prepare a program file on FASTRAND for subsequent referencing as a library by the collector. This card must always be used before a @MAP control card. (6.3.1-153)

24. @PRT, T  
This card produces a table of contents of the temporary program file (TPF\$). (6.3.1-157)
25. @PRT, T GPSSE8.  
This card will generate a table of contents of all elements contained in the program file GPSSE8. (6.3.1-151)
26. @REWIND TAPENAME  
Executive command which causes the rewinding of the tape drive called TAPENAME. Execution of this control causes the tape to be positioned at the starting point of the first tape file. (6.3.1-138)
27. @RUN, //P SAMPLE, 999999, PORTERBIN225, 3, 150  

The run is always the first control card in the 1108 deck setup. This card contains all the information used by the computer for accounting and identification purposes. The three options available on the RUN card are P (production), T (development, and A (maintenance and checkout). SAMPLE1 is the run I.D. code assigned to the particular deck for use by the computer, 999999 is the accounting job number, PORTER is the programmer's name in six characters, and 225 identifies the programmer's BIN location. The 3 is the maximum CPU time (min) for the run. The 150 represents the maximum number of pages of output produced by the program. (Technical Bulletin No. 16)
28. @SETC 2  
Sets the computer condition word to the value of 2 and causes the generation of a punched deck of the absolute GPSS model. (6.3.1-118)
29. @SETC 3  
Sets the computer condition word to the value of 3, thus eliminating the listing of the model network. A separate header page is generated for each case to be executed. (6.3.1-118)
30. @SETC 4  
Sets the computer condition word to the value of 4, thus causing a printout indicating the distributions and their associated parameters from the GPSS model that were defined for each processing operation. (An extra control card, @ADD MODEL, must be inserted into the program deck when this control option is used.) (6.3.1-118)

31. @SETC 5

Sets the computer condition word to the value of 5, thus causing the System Model to be read for headings used in the collection of confidence interval statistics. (An extra control card, @ADD MODEL, must be inserted into the program deck when this control option is used.)

(6.3.1-118)

32. @XQT GPSSE8.MAPGPS

Control card command indicating the execution of the GPSS program instructions called MAPGPS contained on a file named GPSSE8. (6.3.1-108)

33. @XQT, LA SYS\$\*MSFC\$.LISTIT

This card executes a special program that generates a listing of the contents of the temporary program file.

(6.3.1-106)

## GENERAL CARD DESIGN

```

1      @ ADD MODEL .
2      @ ASG , T NAME F2
3      @ ASG , T TAPE NAME , T , SAVEXX
4      @ ASG , T TAPE NAME , T , 12 34 5
5      @ BRKPT PUNCH $
6      @ BRKPT PUNCH$ /EN
7      @ COPIN TAPE NAME , GPSSE8 .
8      @ COPIN TAPE NAME , TPF$ .
9      @ CPOUT GPSSE8 , TAPE NAME
10     @ COPY , G TAPE NAME , MODEL .
11     @ COPY , CM MODE L , TAPE NAME
12     @ COPY , RSA MASTER * GPSSE8 . , GPSSE8 .
13     @ DATA FILE 2 , MODE L
14     @ DATA , L DUMMY F , MODEL
15     @ END
16     @ ERS GPSSE8 .
17     @ FIN
18     @ FOR , US GPSSE8 . NAME , GPSSE8 . NAME
19     @ FREE TAPE NAME
20     @ HDG , F CASE STUDY TITLE
21     @ MAP , LX GPSSE8 . MAP , GPSSE8 . MAP GPS
22     @ MOVE TAPE NAME , 2
23     @ PREP GPSSE8 .
24     @ PR , T
25     @ PR , T GPSSE8 .

```

FIGURE F-1. EXAMPLE CONTROL CARD FORMAT (Sheet 1 of 2)

GENERAL CARD DESIGN	
1	-
2	REWIND TAPENAME
3	RUN, / P SAMPLE, 99999, PORTER BIN 225, 3, 150
4	SETC 2
5	SETC 3
6	SETC 4
7	SETC 5
8	XQT GPSSE 8.MAP GPS
9	XQT, LA SYS\$ *MSFC\$.LISTIT
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FIGURE F-1. EXAMPLE CONTROL CARD FORMAT (Sheet 2 of 2)