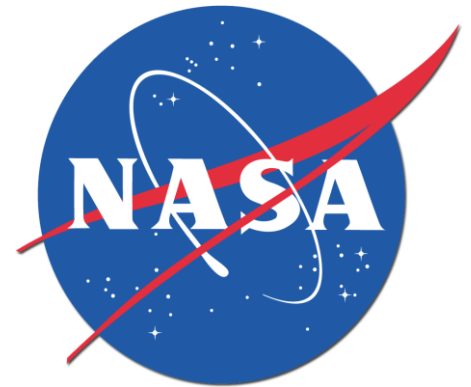


# Enabling Airspace Integration for High Density On-Demand Mobility Operations

Eric Mueller

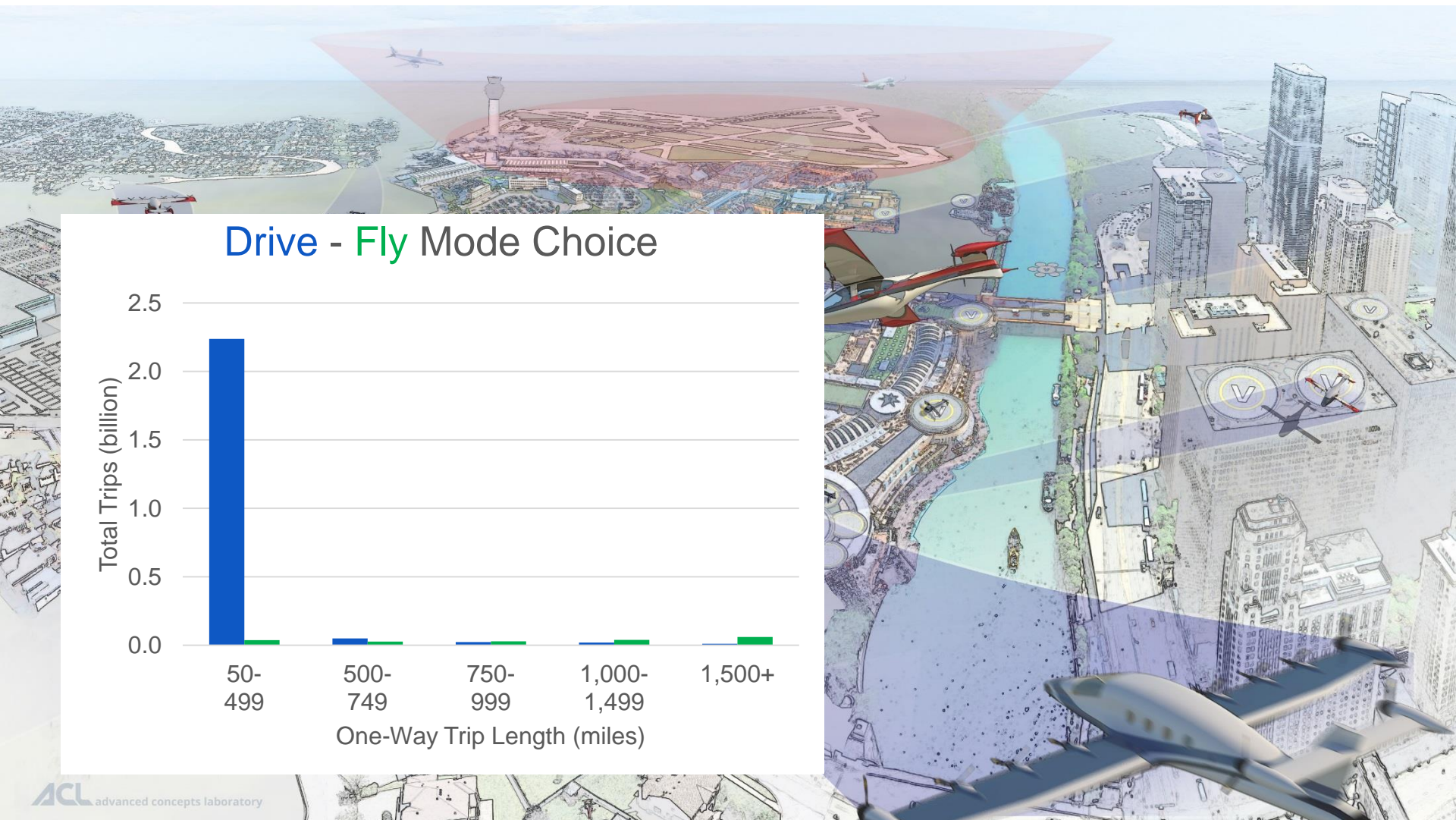
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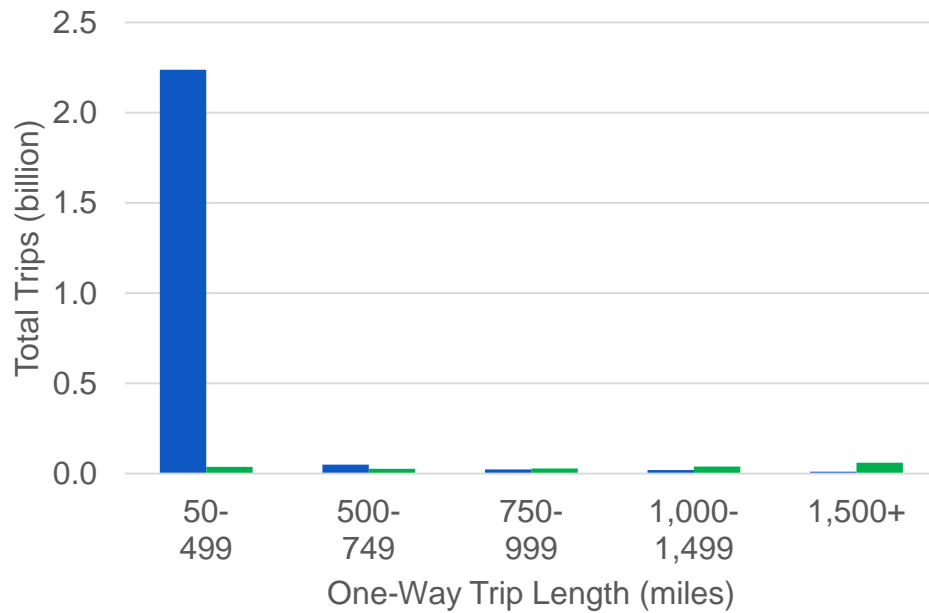


- Barriers
  - The airspace integration problem
- Opportunities
  - Integrating new airspace users
  - Review of selected capabilities
- Research approach

**An incremental approach to airspace integration  
can achieve high-density on-demand mobility**



## Drive - Fly Mode Choice



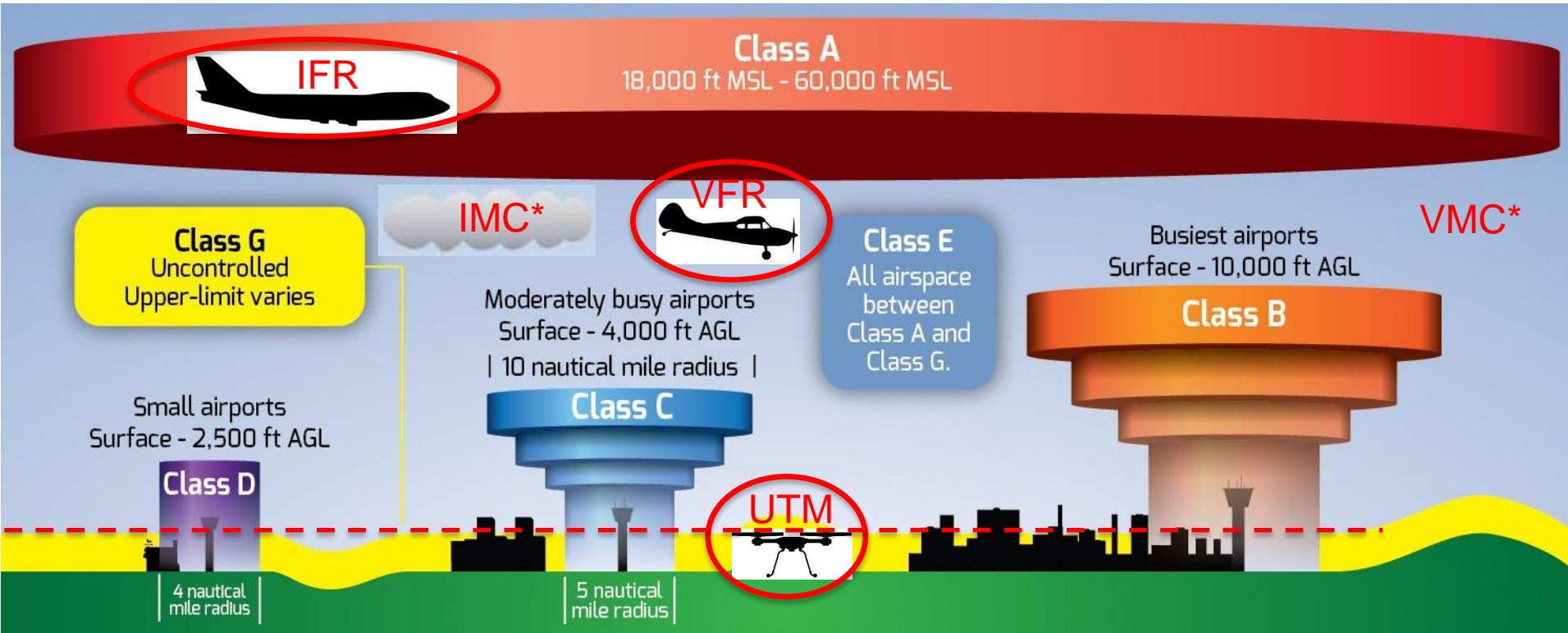


Operating safely and efficiently  
in a given volume without unreasonably burdening  
existing airspace users or air traffic control

# Airspace Integration Options

- IFR (Instrument Flight Rules): under the supervision of air traffic control (ATC)
- VFR (Visual Flight Rules): used largely by general aviation, not commercial operators
- UTM (UAS Traffic Management): parallel ATC system for small, low altitude UAS

## Simplified National Airspace System (NAS)



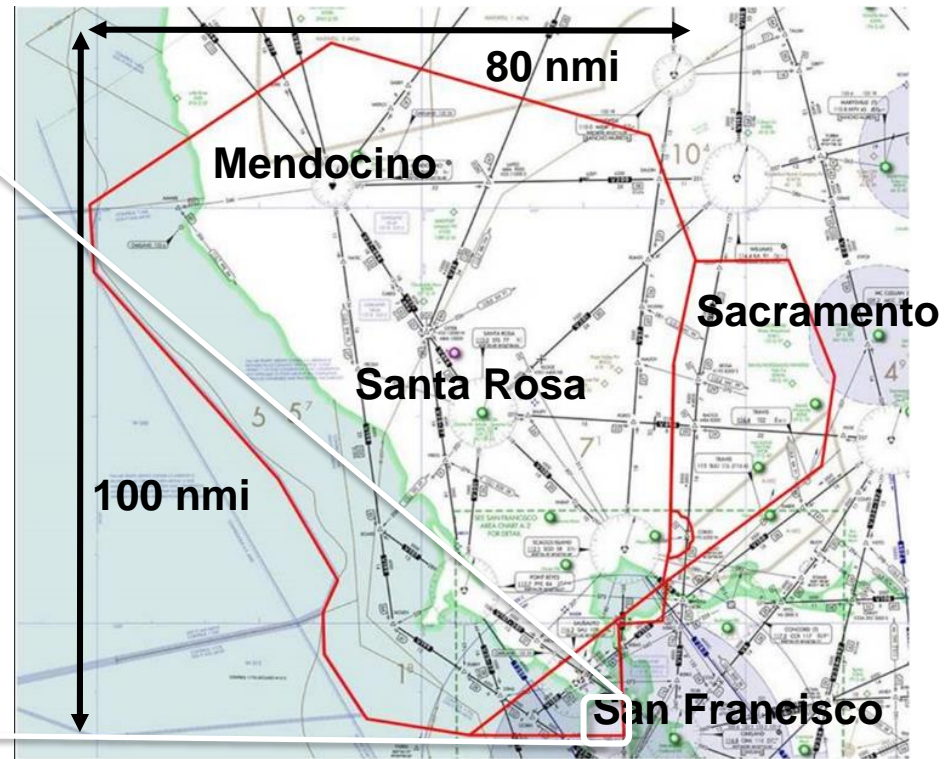
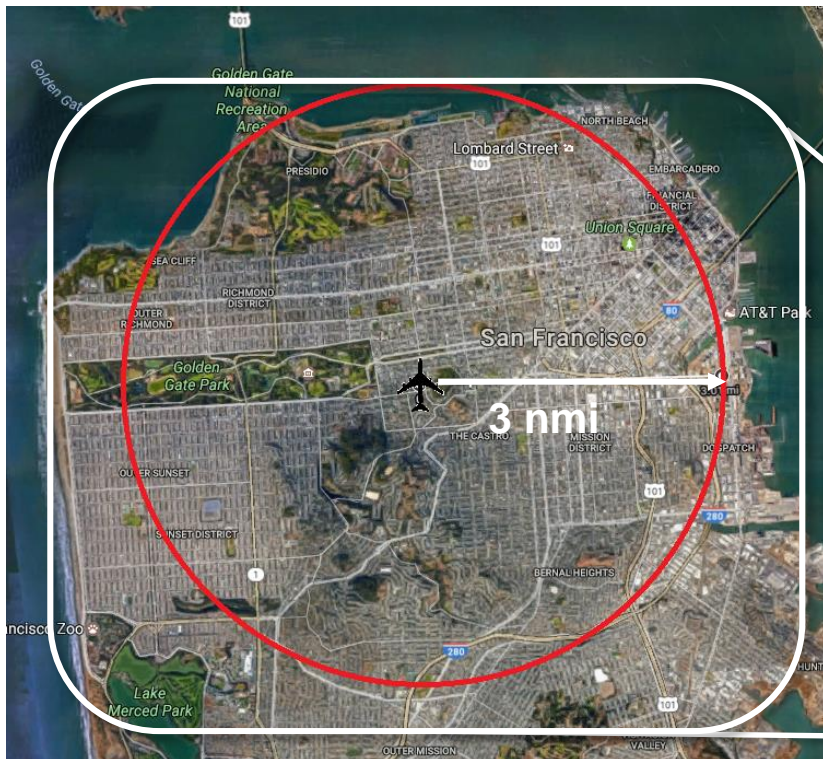
\*VMC/IMC = Visual/Instrument Meteorological Conditions



# The IFR Airspace Integration Problem



- High-density reference mission in a single metropolitan area (30x40 nmi)
  - 1200 aircraft, 150,000 passengers per day, more operations than the entire NAS
  - Approximately one on-demand mobility aircraft per square mile



**On-demand mobility density is ~400 times higher than the allowable IFR density**



# Airspace Integration for New Users

# Airspace Integration Principles



1. Does not require additional air traffic control (ATC) infrastructure
2. Does not impose additional workload on human controllers (i.e. ATC)
3. Does not restrict operations of traditional airspace users
4. Will meet appropriate safety thresholds and requirements
5. Will prioritize operational scalability to reach high aircraft densities
6. Allows flexibility where possible and imposes structure where necessary



# Airspace Integration Approaches



Start where you are with what you have...

Approach	Advantages	Disadvantages	Prognosis for urban mob.
<b>IFR</b>	Air traffic services allow operation anywhere, anytime	Not scalable	Operationally incompatible, automated technologies and services may extend to urban mobility
<b>VFR</b>	Maximum autonomy from ATC for manned aircraft	Must provide own ATC services, no IMC ops, not scalable	Allows autonomy from ATC, but safety, scalability, and efficiency are too low
<b>UTM</b>	ATC ecosystem for small UAS provides all relevant services	Quality and availability of services for small UAS require extensions for manned aviation	Supplies most services necessary for high density urban mobility, but tech. and procedures still in research phase



...make something of it and never be satisfied

1. Start by operating VFR according to today's rules
2. Incrementally develop and certify aircraft-centric technologies to relieve operational constraints
3. Adopt UTM services as replacements for aircraft-centric technologies and VFR requirements

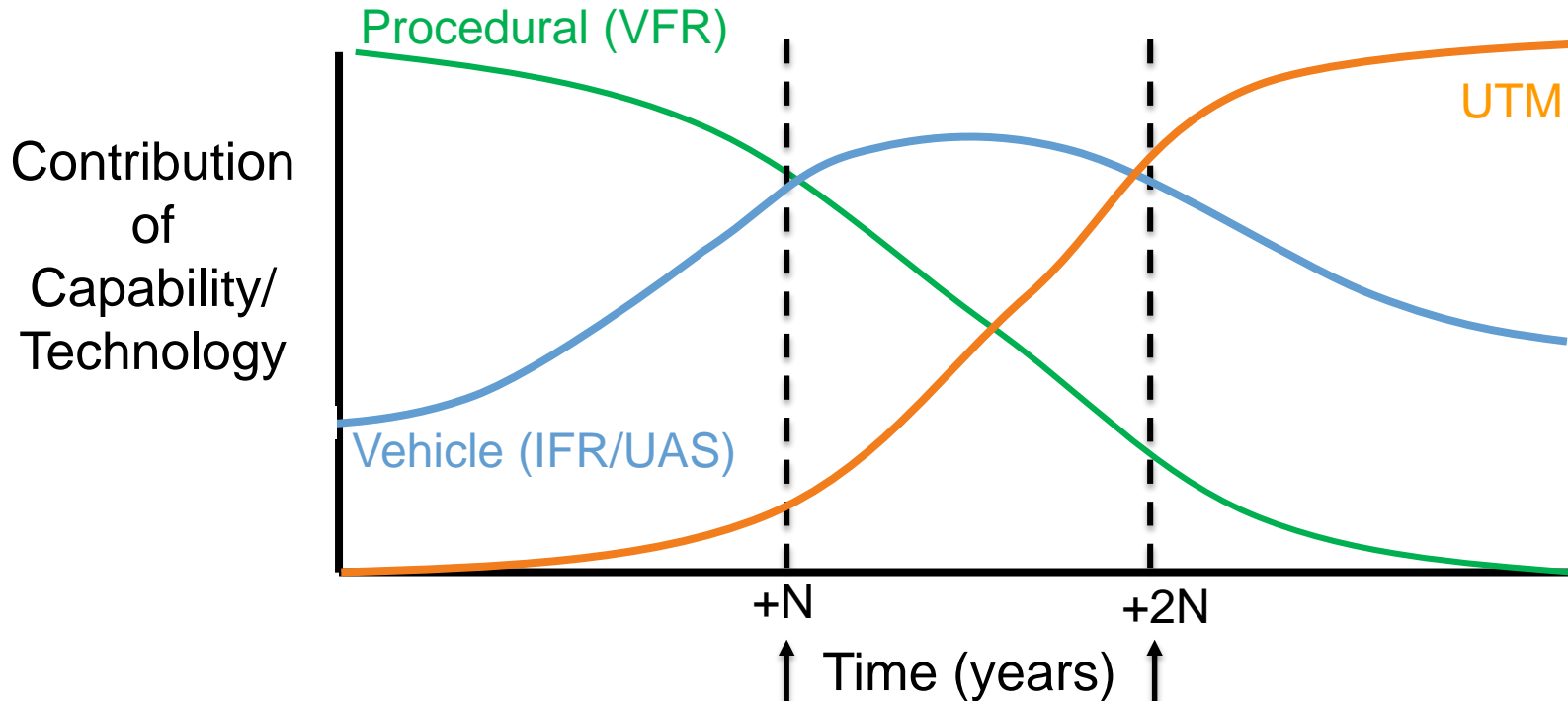
# Approaches to Developing Capabilities



**Low Density**  
VFR-dominated  
operations, new  
procedures

**Medium Density**  
Advanced VFR with  
adapted UAS,  
IFR technologies

**High Density**  
Autonomous  
ops. with UTM  
services



- See and avoid unsafe
- Sequencing and spacing inefficient
- IMC constraints

- Aircraft tech. too costly,
- Centralized coordination may be more efficient
- Pilot needs to be remote

# Capabilities Required for Airspace Integration



- Communications
- Navigation
- Surveillance
- Weather/Met. Data
- Security
- Airspace routes
- Airspace constructs
- Airspace classes
- Geofencing
- Take-off and landing areas
- Demand-capacity balancing
- Separation
  - aircraft, obstacles, terrain
- Scheduling, sequencing and spacing
  - to take-off and landing areas, corridors, ops. areas
- Trajectory planning
- Wake avoidance
- All-weather and night-time operations
- Contingency management
- Community impact (noise)

# Capabilities Required for Airspace Integration



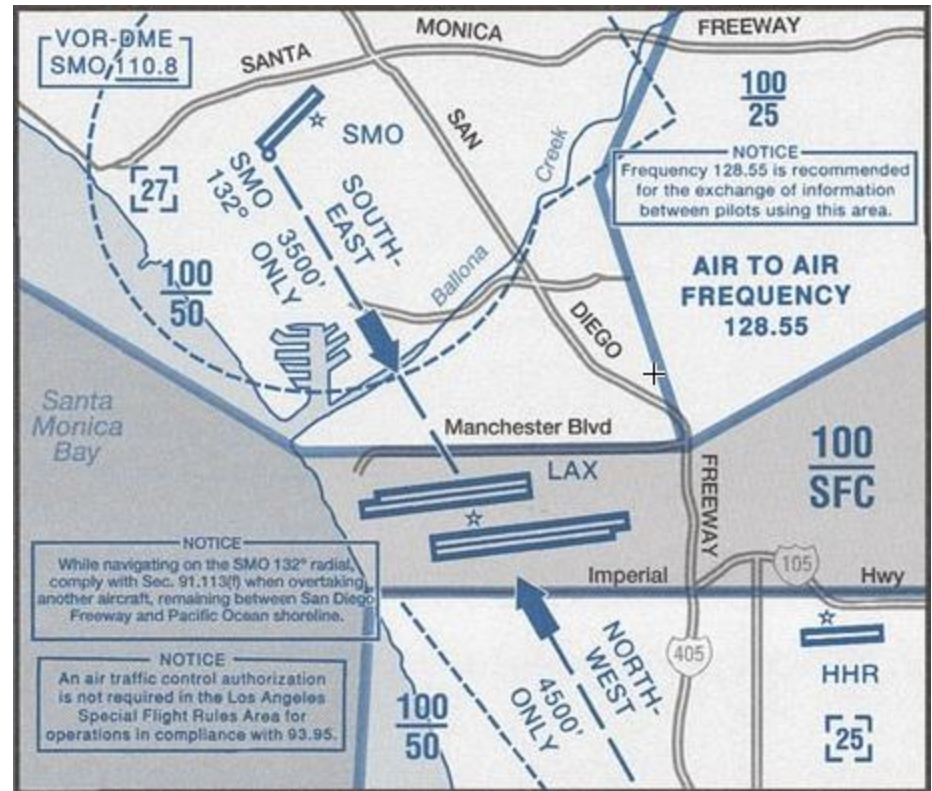
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- Community impact (noise)



# Airspace Constructs (AC)



- Today, AC consist of procedures and rules that enhance safety or efficiency
  - Los Angeles special flight rules area (SFRA)
  - Mode-C veil, with ADS-B (i.e. satellite-based surveillance)
- For on-demand mobility, airspace constructs will compensate for technological limitations
- UTM will provide more efficient airspace access than AC
  - May allow dynamic ACs



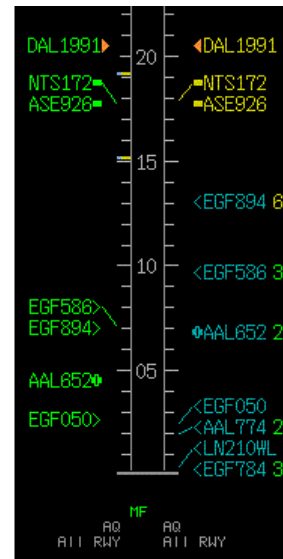
**UTM would relieve the need to impose airspace constructs**

# Sequencing, Scheduling, Spacing (SSS)

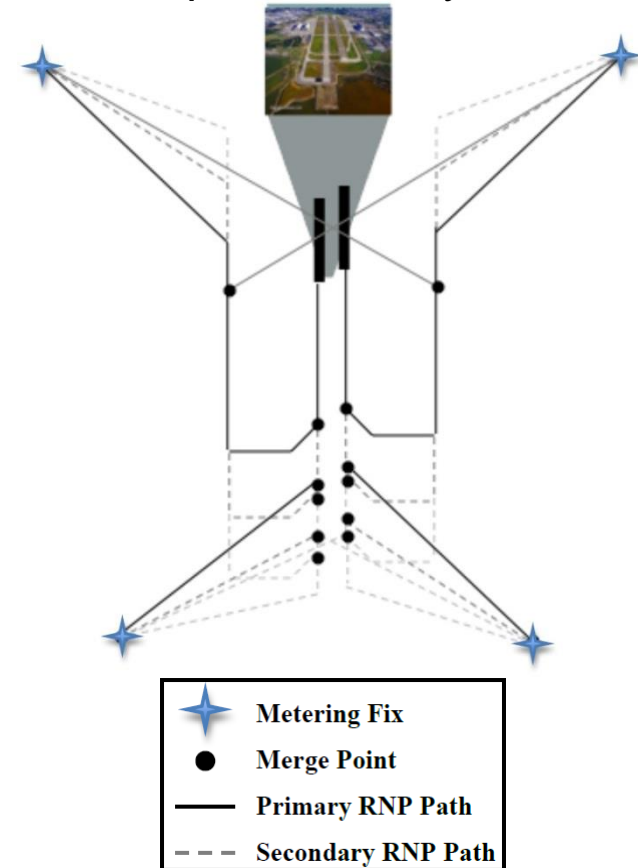


- Today, SSS is used to regulate the flow of traffic into constrained airspace
  - Airport (terminal) areas
    - VFR aircraft follow procedures and use vision
    - IFR aircraft sequenced far from the airport and merged by humans using advisory tools
  - Weather-impacted enroute sectors
- On-demand mobility will require an automated or distributed SSS capability for VTOLs
- UTM surveillance and trajectory prediction capabilities will directly support SSS functions

## Traffic Management Advisor



## Typical arrival pattern today



**UTM does not require SSS, but the services it provides could be extended to this capability**

# Separation Services



- Today, different aircraft types separate differently
  - VFR aircraft separate visually
  - IFR aircraft separated by ATC, but require visual and electronic collision avoidance
  - Right-of-way rules for aircraft classes
- On-demand mobility aircraft will assume responsibility for separation to avoid IFR capacity limitations
  - UAS detect-and-avoid (DAA) systems
  - Vehicle-to-vehicle (V2V) technologies
- UTM will provide surveillance and separation services, but tailored for small UAS



**UTM provides separation services, need to reduce risk to apply them to human-carrying aircraft**

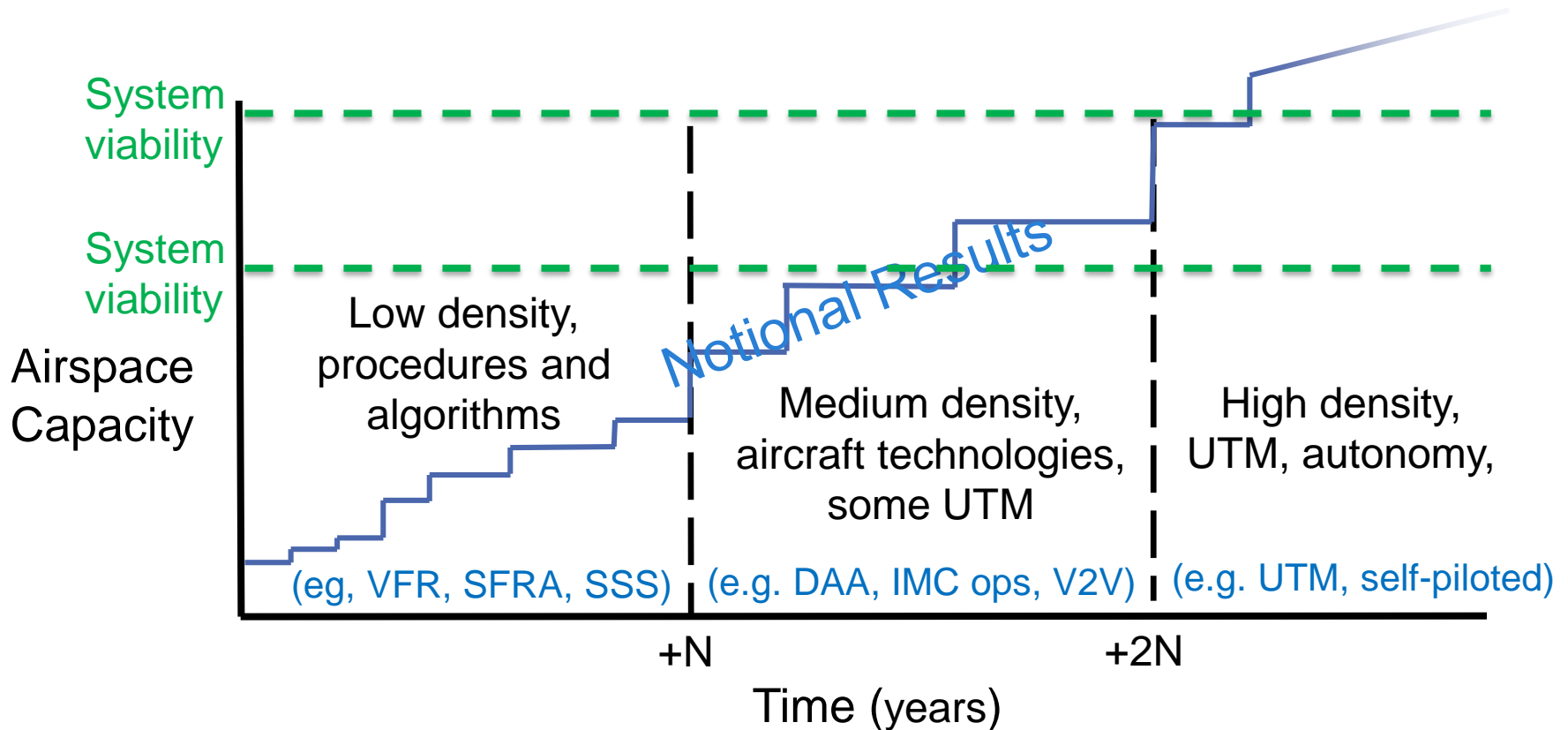


# Research Approach for Airspace Integration

# Airspace Capacity Enablers



What capabilities will increase the capacity of the airspace?



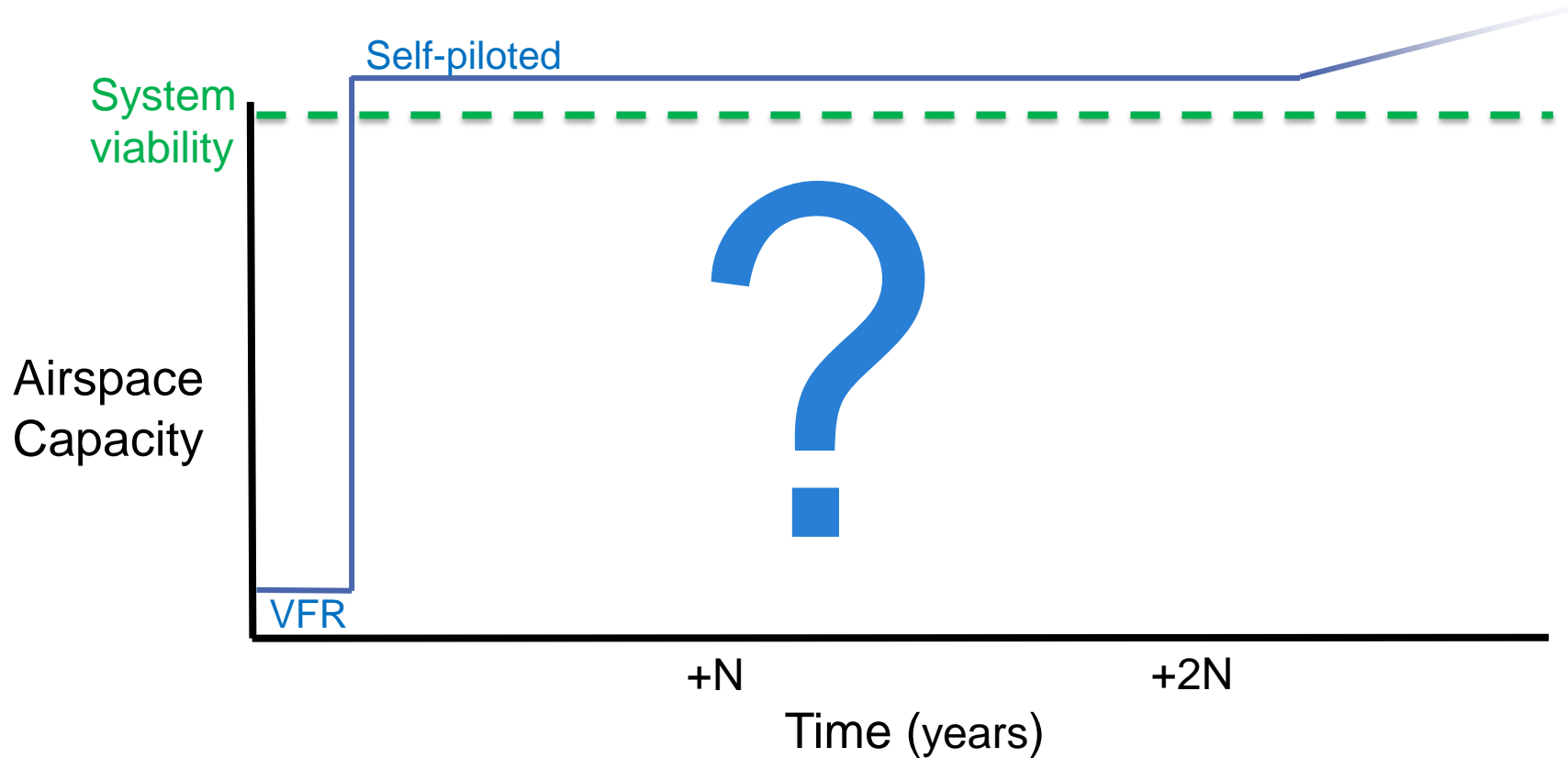
Deliver validated data on the cumulative benefits and costs of these capabilities



# Airspace Capacity Enablers



What capabilities will increase the capacity of the airspace?



Deliver validated data on the cumulative benefits and costs of these capabilities

1. Organize a community of interest for airspace integration
2. Develop a roadmap of airspace integration solutions by density level
3. Develop required airspace services, whether aircraft-centric or in UTM
4. Create analysis, modeling, simulation, flight test infrastructure
5. Verify scalability of airspace solutions through simulations
6. Validate deployability of solutions through flight tests

**An incremental approach to airspace integration  
can achieve high-density on-demand mobility**

Eric.Mueller@nasa.gov

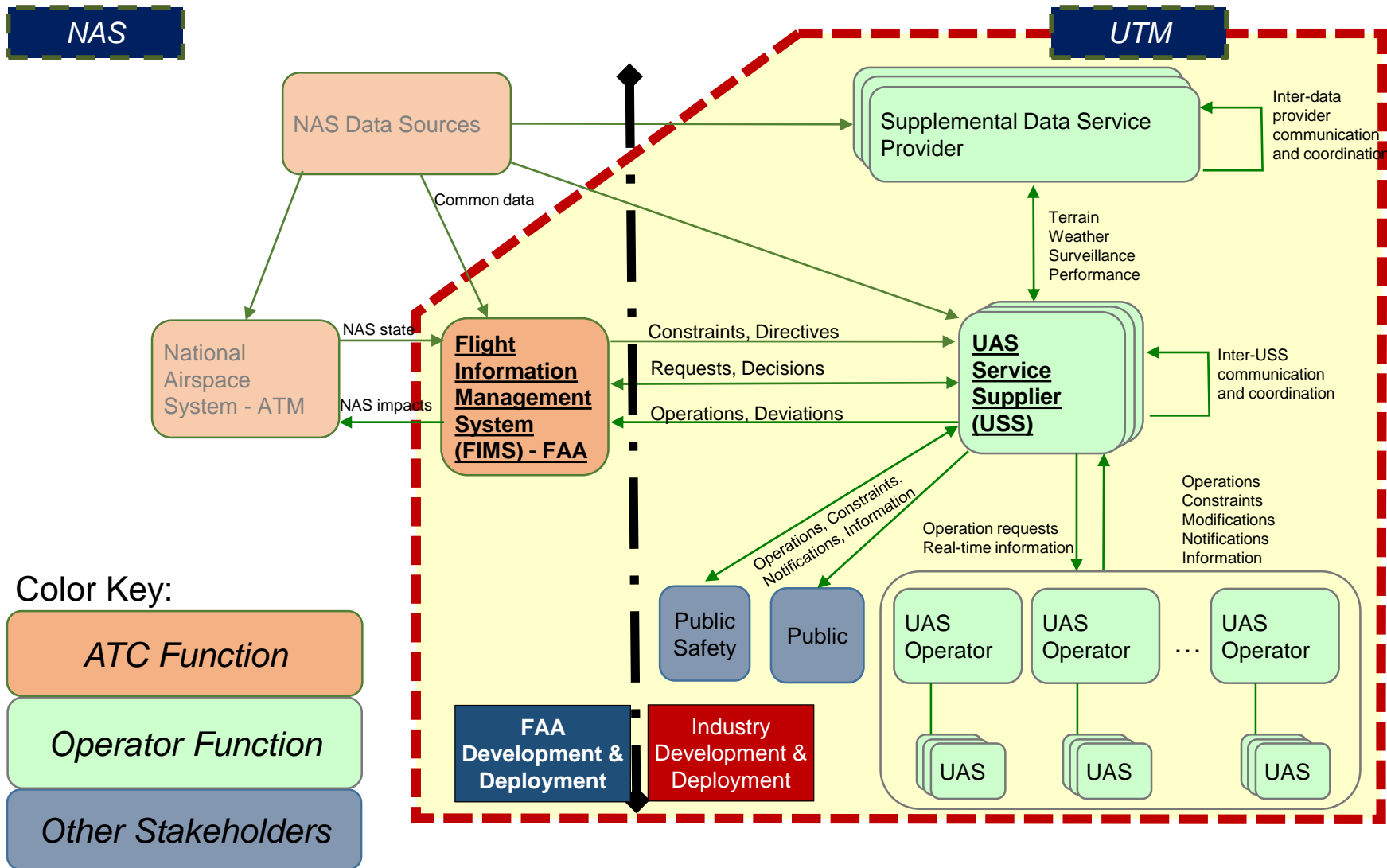


# Backup

# UTM Architecture



# UTM Architecture





# Airspace Integration Research Approach



## Technology and Procedure Candidates

**NASA**  
National Aeronautics and Space Administration  
Ames Research Center  
Moffett Field, CA 94035-8277

**Unmanned Aircraft Systems (UAS) Integration in the National Airspace System (NAS) Project**

CON-ARC51-001

Release: Initial Draft  
Date: September 30, 2012  
Prepared By: [Name]  
By: [Name]

Reviewed By: [Name]  
[Name]  
[Name]  
[Name]

Concepts for the Integration of UAS in the National Airspace System

UAM Concepts

<p><b>UAM Corridors</b></p>	<p><b>Aircraft</b></p>	<p><b>UTM</b></p>	<p><b>V2V/DSRC</b></p>	<p><b>Separation</b></p>
<p><b>DAA systems</b></p>	<p><b>IMC</b></p>	<p><b>Automation</b></p>	<p><b>SSS</b></p>	

High-maturity (TRL) capabilities

Low-maturity capabilities

Deployability

Scalability

HitL Evaluation

NAS-wide Simulation

Technology Integration

Flight Test





- Provide concepts, technologies and procedures that enable orders of magnitude increases in the capacity of the airspace for novel vehicle types and operations through cooperative airspace traffic management that does not require additional ATM infrastructure
- Flight test demonstration of integrated system *deployability* at successively higher traffic densities
- Simulation demonstration of concept *scalability* with novel capabilities at successively higher densities

# Mapping Approaches to Capabilities

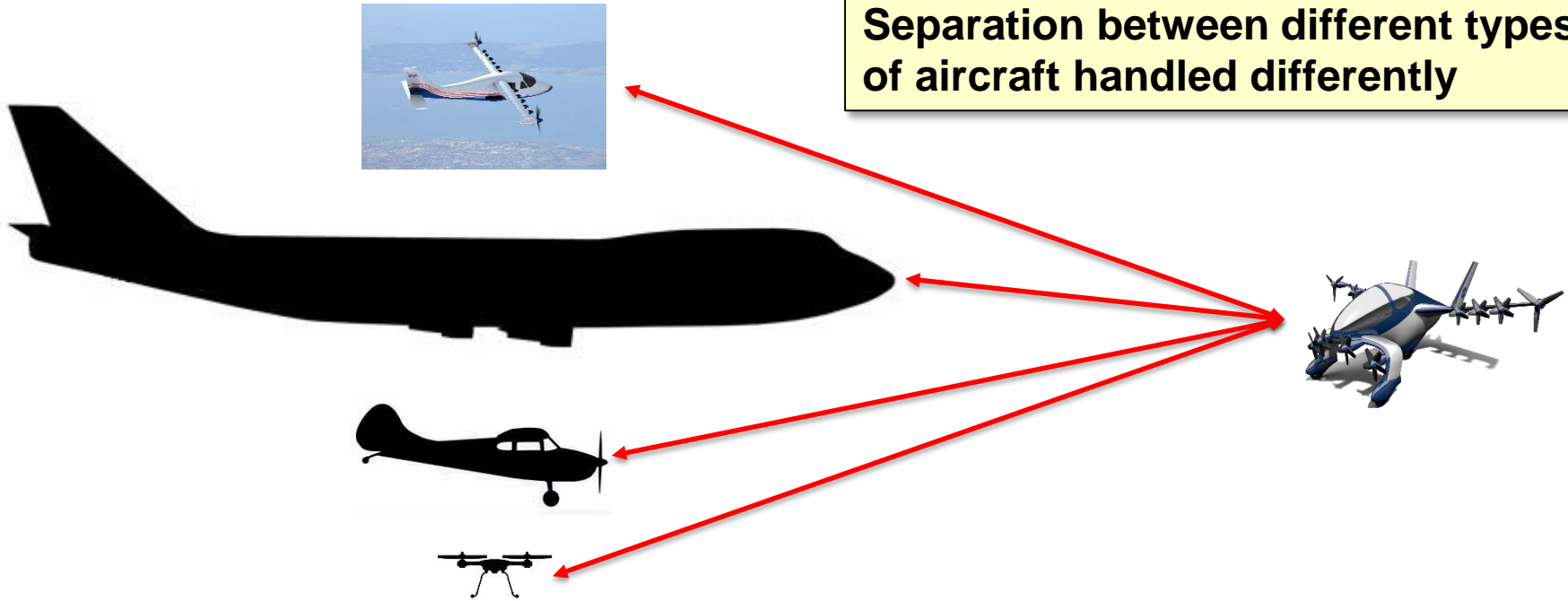


Barrier	Procedural	Vehicle	UTM
<b>Information gathering and exchange</b>	Chartered routes, GPS & radio beacons, pilot SAA & ADS-B, FIS, VHF	V2V state & intent exchange, 802.11p, aGPS + WAAS, DAA, VDL, cell net.	UTM-aggregated data, V2V backup, limited DAA, aGPS + GBAS, cell net., sat. comm.
<b>Airspace design</b>	UAM corridors in terminal airspace, public helipads	High density corridors enroute, reserved airspace, municipality TOLAs	No UAM structure, some traditional users excluded, neighborhood TOLAs
<b>Airspace Services</b>	Pilot SAA, traditional flight planning	DAA for separation & SSS, AR wake avoidance	UTM-provided services & traj. planning, backup DAA
<b>Resilience, scalability</b>	NOTAMs, scripted contingency ops, daytime only, VMC	V2V-coordinated contingency ops, IMC, night-time	FIMS, dynamic contingency ops, all weather, all times

# UAM Separation Services



**Separation between different types of aircraft handled differently**



Aircraft pairs	Low Density	Medium Density	High Density
<b>UAM-UAM</b>	SAA, AC, ADS-B	DAA, V2V, AC	UTM, V2V, DAA
<b>UAM-IFR</b>	Segregation, SAA, ADS-B	DAA, ADS-B	UTM, DAA
<b>UAM-VFR</b>	SAA, ADS-B	DAA, ADS-B	UTM, DAA
<b>UAM-sUAS</b>	Segregation	V2V, DAA	UTM, V2V, DAA

# UTM Architecture and Services



Flexibility where possible, structure where necessary

