



ESC 2017
Ottawa, Canada

Bart Forman

- Observation Types
- Objectives
- OSSE
- TAT-C
- Hyperplanes
- Eulerian Grid
- Single Platform Constellation
- Trade-off Space
- Machine Learning
- Emulators
- Variability
- Experiments
- Conclusions

Towards the Development of a Global, Satellite-based, Terrestrial Snow Mission Planning Tool

Co-authors: **Sujay Kumar¹**, **Jacqueline Le Moigne²**, and **Sreeja Nag^{2,3}**

1=NASA GSFC - Hydrological Sciences; 2=NASA GSFC - Software Engineering; 3=Bay Area Environmental Research Institute

Bart Forman

Assistant Professor, University of Maryland
The Deborah J. Goodings Professor of Global Sustainability
Department of Civil and Environmental Engineering

June 7th, 2017



Satellite-derived Snow "Information"

ESC 2017

Ottawa, Canada

Bart Forman

Observation
Types

Objectives

OSSE

TAT-C

Hyperplanes

Eulerian Grid

Single Platform

Constellation

Trade-off Space

Machine Learning

Emulators

Variability

Experiments

Conclusions





Satellite-derived Snow "Information"

ESC 2017
Ottawa, Canada

Bart Forman

Observation
Types

Objectives

OSSE

TAT-C

Hyperplanes

Eulerian Grid

Single Platform

Constellation

Trade-off Space

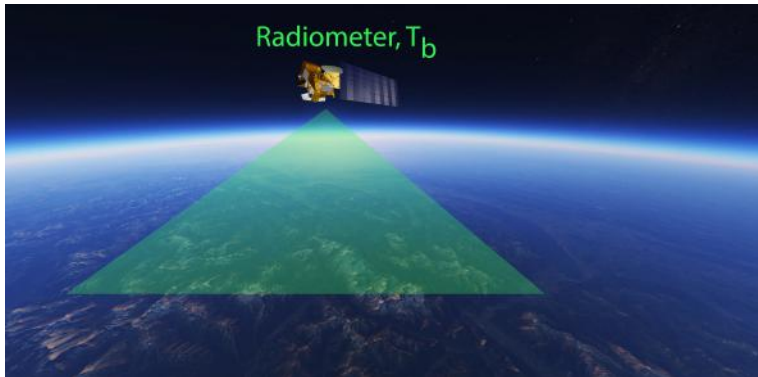
Machine Learning

Emulators

Variability

Experiments

Conclusions





Satellite-derived Snow "Information"

ESC 2017
Ottawa, Canada

Bart Forman

Observation
Types

Objectives

OSSE

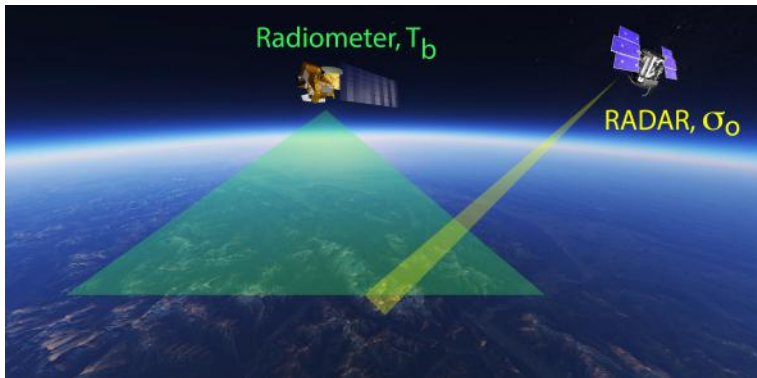
TAT-C

Hyperplanes
Eulerian Grid
Single Platform
Constellation
Trade-off Space

Machine Learning

Emulators
Variability
Experiments

Conclusions





Satellite-derived Snow "Information"

ESC 2017
Ottawa, Canada

Bart Forman

Observation
Types

Objectives

OSSE

TAT-C

Hyperplanes

Eulerian Grid

Single Platform

Constellation

Trade-off Space

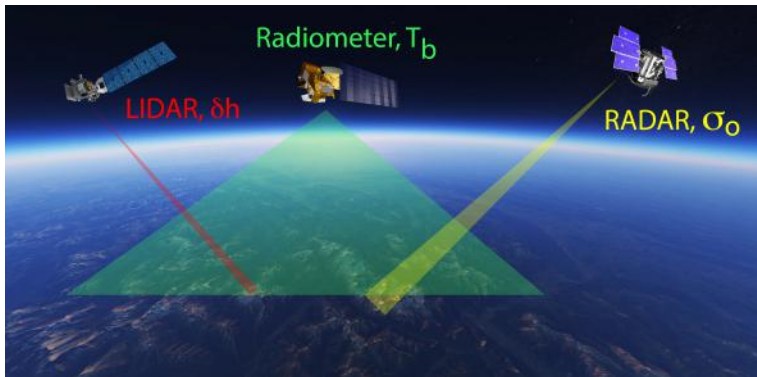
Machine Learning

Emulators

Variability

Experiments

Conclusions





Research Objectives

ESC 2017

Ottawa, Canada

Bart Forman

Observation
Types

Objectives

OSSE

TAT-C

Hyperplanes
Eulerian Grid
Single Platform
Constellation
Trade-off Space

Machine Learning

Emulators
Variability
Experiments

Conclusions

Science and mission planning questions:

- 1 What **observational records** are needed (in space and time) to maximize terrestrial snow experimental utility?
- 2 How might observations be **coordinated** (in space and time) to maximize this utility?
- 3 What is the **additional utility** associated with an additional observation?
- 4 How can future **mission costs be minimized** while ensuring Science requirements are fulfilled?



Research Objectives

ESC 2017

Ottawa, Canada

Bart Forman

Observation
Types

Objectives

OSSE

TAT-C

Hyperplanes
Eulerian Grid
Single Platform
Constellation
Trade-off Space

Machine Learning

Emulators
Variability
Experiments

Conclusions

Science and mission planning questions:

- ① What **observational records** are needed (in space and time) to maximize terrestrial snow experimental utility?
- ② How might observations be **coordinated** (in space and time) to maximize this utility?
- ③ What is the **additional utility** associated with an additional observation?
- ④ How can future **mission costs be minimized** while ensuring Science requirements are fulfilled?



Research Objectives

ESC 2017
Ottawa, Canada

Bart Forman

Observation
Types

Objectives

OSSE

TAT-C

Hyperplanes
Eulerian Grid
Single Platform
Constellation
Trade-off Space

Machine Learning

Emulators
Variability
Experiments

Conclusions

Science and mission planning questions:

- 1 What **observational records** are needed (in space and time) to maximize terrestrial snow experimental utility?
- 2 How might observations be **coordinated** (in space and time) to maximize this utility?
- 3 What is the **additional utility** associated with an additional observation?
- 4 How can future **mission costs be minimized** while ensuring Science requirements are fulfilled?



Research Objectives

ESC 2017

Ottawa, Canada

Bart Forman

Observation
Types

Objectives

OSSE

TAT-C

Hyperplanes
Eulerian Grid
Single Platform
Constellation
Trade-off Space

Machine Learning

Emulators
Variability
Experiments

Conclusions

Science and mission planning questions:

- 1 What **observational records** are needed (in space and time) to maximize terrestrial snow experimental utility?
- 2 How might observations be **coordinated** (in space and time) to maximize this utility?
- 3 What is the **additional utility** associated with an additional observation?
- 4 How can future **mission costs be minimized** while ensuring Science requirements are fulfilled?



Observing System Simulation Experiment

ESC 2017

Ottawa, Canada

Bart Forman

Observation
Types

Objectives

OSSE

TAT-C

Hyperplanes

Eulerian Grid

Single Platform

Constellation

Trade-off Space

Machine Learning

Emulators

Variability

Experiments

Conclusions





Observing System Simulation Experiment

ESC 2017
Ottawa, Canada

Bart Forman

Observation
Types

Objectives

OSSE

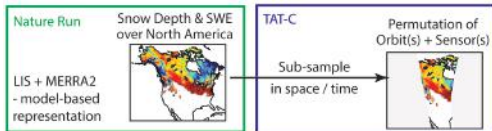
TAT-C

Hyperplanes
Eulerian Grid
Single Platform
Constellation
Trade-off Space

Machine Learning

Emulators
Variability
Experiments

Conclusions





Observing System Simulation Experiment

ESC 2017
Ottawa, Canada

Bart Forman

Observation
Types

Objectives

OSSE

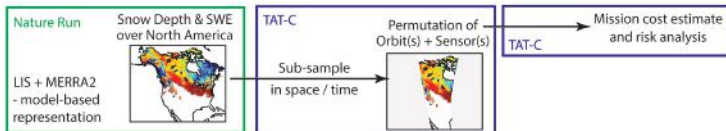
TAT-C

Hyperplanes
Eulerian Grid
Single Platform
Constellation
Trade-off Space

Machine Learning

Emulators
Variability
Experiments

Conclusions





Observing System Simulation Experiment

ESC 2017
Ottawa, Canada

Bart Forman

Observation
Types

Objectives

OSSE

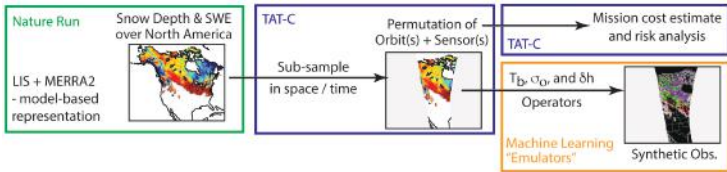
TAT-C

Hyperplanes
Eulerian Grid
Single Platform
Constellation
Trade-off Space

Machine Learning

Emulators
Variability
Experiments

Conclusions





Observing System Simulation Experiment

ESC 2017
Ottawa, Canada

Bart Forman

Observation
Types

Objectives

OSSE

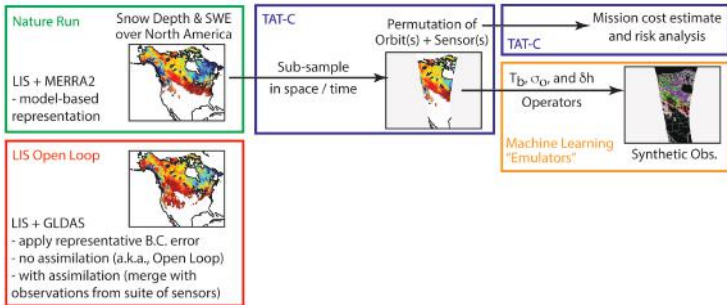
TAT-C

Hyperplanes
Eulerian Grid
Single Platform
Constellation
Trade-off Space

Machine Learning

Emulators
Variability
Experiments

Conclusions





Observing System Simulation Experiment

ESC 2017
Ottawa, Canada

Bart Forman

Observation
Types

Objectives

OSSE

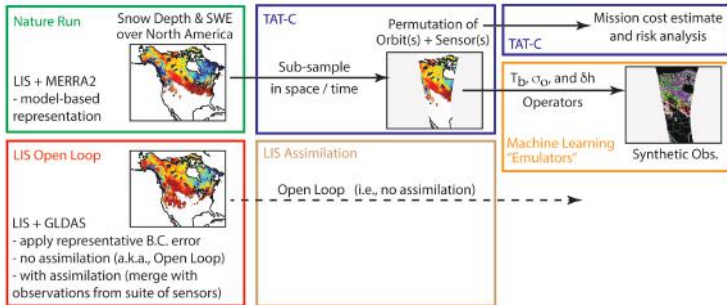
TAT-C

Hyperplanes
Eulerian Grid
Single Platform
Constellation
Trade-off Space

Machine Learning

Emulators
Variability
Experiments

Conclusions





Observing System Simulation Experiment

ESC 2017
Ottawa, Canada

Bart Forman

Observation
Types

Objectives

OSSE

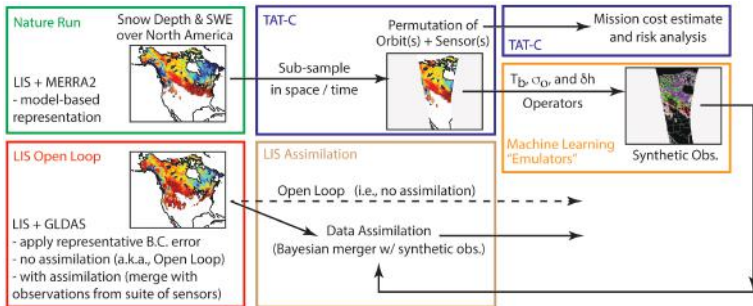
TAT-C

Hyperplanes
Eulerian Grid
Single Platform
Constellation
Trade-off Space

Machine Learning

Emulators
Variability
Experiments

Conclusions





Observing System Simulation Experiment

ESC 2017
Ottawa, Canada

Bart Forman

Observation
Types

Objectives

OSSE

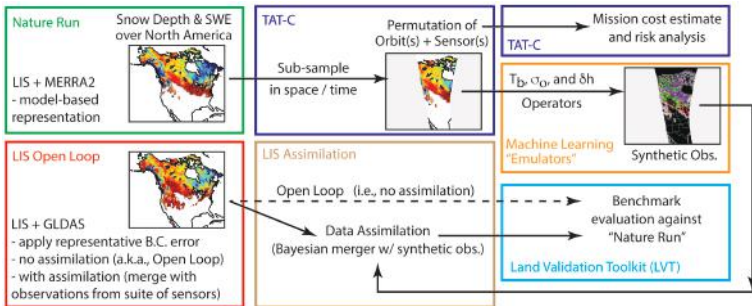
TAT-C

Hyperplanes
Eulerian Grid
Single Platform
Constellation
Trade-off Space

Machine Learning

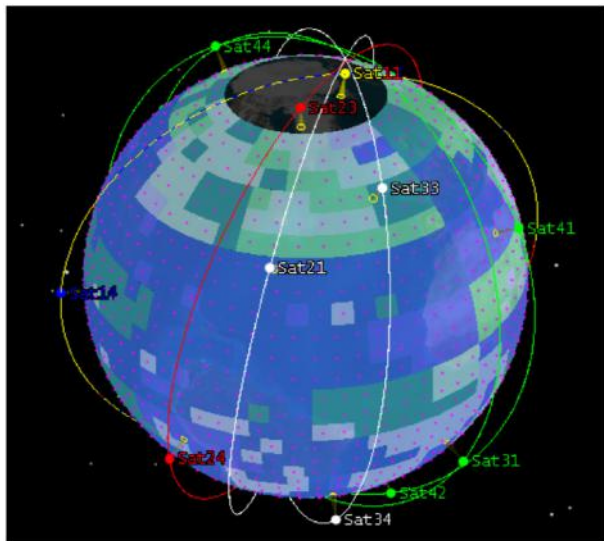
Emulators
Variability
Experiments

Conclusions





TAT-C Orbital Simulator



ESC 2017

Ottawa, Canada

Bart Forman

Observation

Types

Objectives

OSSE

TAT-C

Hyperplanes

Eulerian Grid

Single Platform

Constellation

Trade-off Space

Machine Learning

Emulators

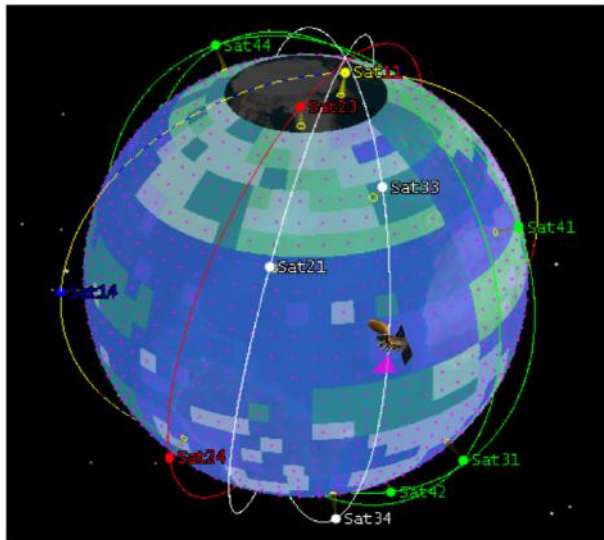
Variability

Experiments

Conclusions



TAT-C Orbital Simulator



ESC 2017

Ottawa, Canada

Bart Forman

Observation

Types

Objectives

OSSE

TAT-C

Hyperplanes

Eulerian Grid

Single Platform

Constellation

Trade-off Space

Machine Learning

Emulators

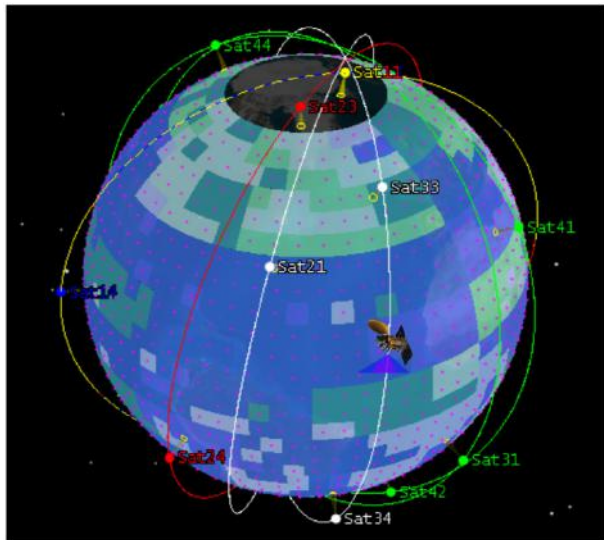
Variability

Experiments

Conclusions



TAT-C Orbital Simulator



ESC 2017

Ottawa, Canada

Bart Forman

Observation
Types

Objectives

OSSE

TAT-C

Hyperplanes

Eulerian Grid

Single Platform

Constellation

Trade-off Space

Machine Learning

Emulators

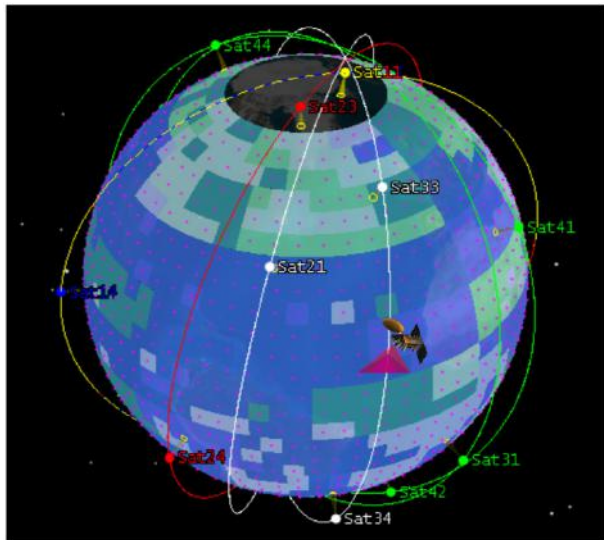
Variability

Experiments

Conclusions



TAT-C Orbital Simulator



ESC 2017

Ottawa, Canada

Bart Forman

Observation

Types

Objectives

OSSE

TAT-C

Hyperplanes

Eulerian Grid

Single Platform

Constellation

Trade-off Space

Machine Learning

Emulators

Variability

Experiments

Conclusions



TAT-C Orbital Simulator

ESC 2017

Ottawa, Canada

Bart Forman

Observation

Types

Objectives

OSSE

TAT-C

Hyperplanes

Eulerian Grid

Single Platform

Constellation

Trade-off Space

Machine Learning

Emulators

Variability

Experiments

Conclusions



“Comb” Viewing \mapsto Single Platform

ESC 2017

Ottawa, Canada

Bart Forman

Observation
Types

Objectives

OSSE

TAT-C

Hyperplanes

Eulerian Grid

Single Platform

Constellation

Trade-off Space

Machine Learning

Emulators

Variability

Experiments

Conclusions



"Comb" Viewing \mapsto Constellation

ESC 2017

Ottawa, Canada

Bart Forman

Observation

Types

Objectives

OSSE

TAT-C

Hyperplanes

Eulerian Grid

Single Platform

Constellation

Trade-off Space

Machine Learning

Emulators

Variability

Experiments

Conclusions



Trade-off Space: Coverage vs. Resolution

ESC 2017
Ottawa, Canada

Bart Forman

Observation
Types

Objectives

OSSE

TAT-C

Hyperplanes

Eulerian Grid

Single Platform

Constellation

Trade-off Space

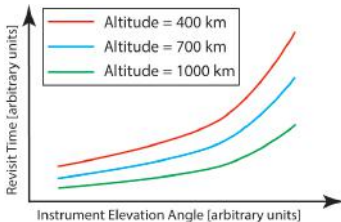
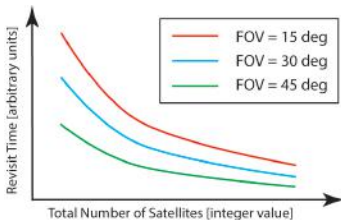
Machine Learning

Emulators

Variability

Experiments

Conclusions



- Explore **trade-off** between engineering and science
 - ▶ Field-of-View (FOV)?
 - ▶ Platform altitude?
 - ▶ Repeat cycle?
 - ▶ Single platform vs. constellation?
 - ▶ Orbital configuration(s)?
- How do we get the most **scientific bang** for our buck?

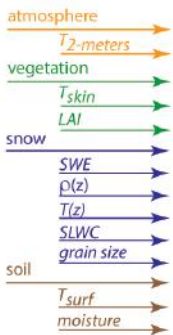


Machine Learning “Emulators”

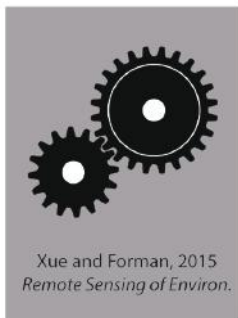
ESC 2017
Ottawa, Canada

Bart Forman

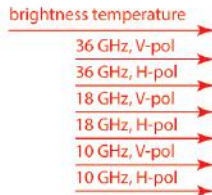
- Observation Types
- Objectives
- OSSE
- TAT-C
- Hyperplanes
- Eulerian Grid
- Single Platform
- Constellation
- Trade-off Space
- Machine Learning
- Emulators**
- Variability
- Experiments
- Conclusions



Physically-based
Land Surface Model(s)



Observation Operator
(Forman et al., 2013;
Forman and Reichle, 2014;
Forman and Xue, 2016)

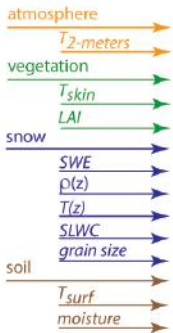


Multi-frequency,
Multi-polarization
Training Targets

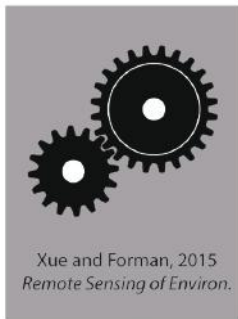


Machine Learning “Emulators”

- ESC 2017
Ottawa, Canada
- Bart Forman
- Observation
Types
- Objectives
- OSSE
- TAT-C
- Hyperplanes
- Eulerian Grid
- Single Platform
- Constellation
- Trade-off Space
- Machine Learning
- Emulators**
- Variability
- Experiments
- Conclusions



Physically-based
Land Surface Model(s)



Observation Operator
(Forman et al., 2013;
Forman and Reichle, 2014;
Forman and Xue, 2016)



Multi-frequency,
Multi-polarization
Training Targets

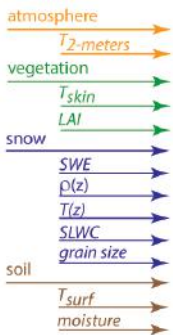


Machine Learning “Emulators”

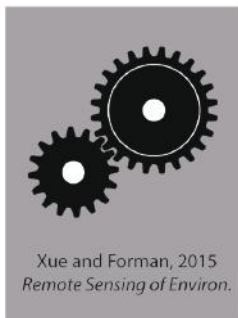
ESC 2017
Ottawa, Canada

Bart Forman

- Observation Types
- Objectives
- OSSE
- TAT-C
- Hyperplanes
- Eulerian Grid
- Single Platform
- Constellation
- Trade-off Space
- Machine Learning
- Emulators**
- Variability
- Experiments
- Conclusions



Physically-based
Land Surface Model(s)



Observation Operator
(Forman et al., 2013;
Forman and Reichle, 2014;
Forman and Xue, 2016)



Multi-frequency,
Multi-polarization
Training Targets

Spatiotemporal Variability

ESC 2017
Ottawa, Canada

Bart Forman

Observation
Types

Objectives

OSSE

TAT-C

Hyperplanes
Eulerian Grid

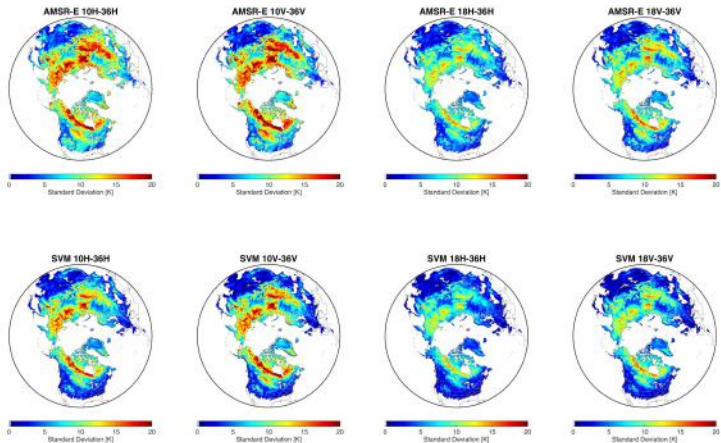
Single Platform
Constellation
Trade-off Space

Machine Learning

Emulators

Variability
Experiments

Conclusions





Spatiotemporal Variability

ESC 2017
Ottawa, Canada

Bart Forman

Observation
Types

Objectives

OSSE

TAT-C

Hyperplanes
Eulerian Grid
Single Platform
Constellation
Trade-off Space

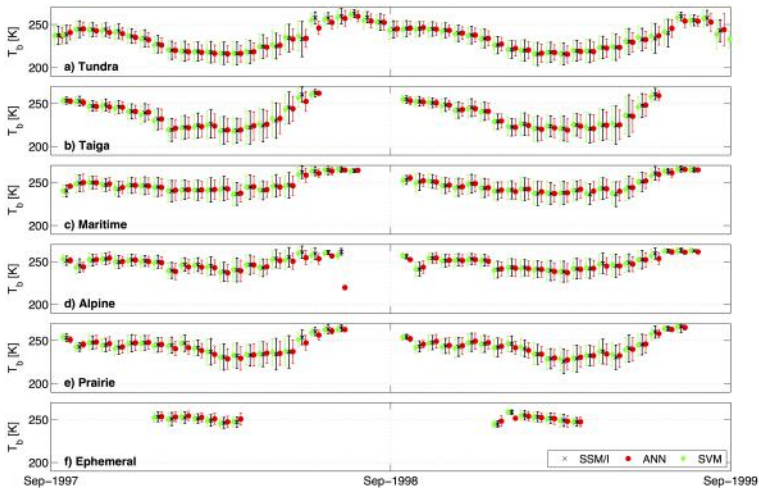
Machine Learning

Emulators

Variability

Experiments

Conclusions





Relevancy Scenarios

ESC 2017

Ottawa, Canada

Bart Forman

Observation
Types

Objectives

OSSE

TAT-C

Hyperplanes
Eulerian Grid
Single Platform
Constellation
Trade-off Space

Machine Learning

Emulators
Variability
Experiments

Conclusions

- **Scenario 1:** Benchmark Analysis
 - ▶ Passive MW Assimilation only
- **Scenario 2:** Comparative Analysis
 - ▶ Passive MW vs. Active MW vs. LIDAR
- **Scenario 3:** Multi-sensor Analysis
 - ▶ single-sensor platform
 - ▶ multi-sensor platform
 - ▶ constellation of sensors



Research Summary

ESC 2017

Ottawa, Canada

Bart Forman

Observation
Types

Objectives

OSSE

TAT-C

Hyperplanes
Eulerian Grid
Single Platform
Constellation
Trade-off Space

Machine Learning

Emulators
Variability
Experiments

Conclusions

- Global snow mission planning will require **evidence of achievable science** via OSSE
- Land Information System (LIS) provides “nature run” plus assimilation framework
- TAT-C provides **spatiotemporal sub-sampling** of observations, including **cost estimates and risk assessments**
- **Machine learning** maps model state(s) into observation space (i.e., T_b and σ_0)
 - ▶ Enables integration of T_b , σ_0 , and δh in geophysical realm (i.e., SWE and snow depth)
 - ▶ **Multiple frequencies/polarizations/observations** allow for flexibility and modularity in DA framework
- Snow **OSSE is on-going** → open to suggestions!



Research Summary

ESC 2017

Ottawa, Canada

Bart Forman

Observation
Types

Objectives

OSSE

TAT-C

Hyperplanes
Eulerian Grid
Single Platform
Constellation
Trade-off Space

Machine Learning

Emulators
Variability
Experiments

Conclusions

- Global snow mission planning will require **evidence of achievable science** via OSSE
- Land Information System (LIS) provides “nature run” plus assimilation framework
- TAT-C provides **spatiotemporal sub-sampling** of observations, including **cost estimates and risk assessments**
- **Machine learning** maps model state(s) into observation space (i.e., T_b and σ_0)
 - ▶ Enables integration of T_b , σ_0 , and δh in geophysical realm (i.e., SWE and snow depth)
 - ▶ **Multiple frequencies/polarizations/observations** allow for flexibility and modularity in DA framework
- Snow **OSSE is on-going** → open to suggestions!



Research Summary

ESC 2017

Ottawa, Canada

Bart Forman

Observation
Types

Objectives

OSSE

TAT-C

Hyperplanes
Eulerian Grid
Single Platform
Constellation
Trade-off Space

Machine Learning

Emulators
Variability
Experiments

Conclusions

- Global snow mission planning will require **evidence of achievable science** via OSSE
- Land Information System (LIS) provides “nature run” plus assimilation framework
- TAT-C provides **spatiotemporal sub-sampling** of observations, including **cost estimates and risk assessments**
- **Machine learning** maps model state(s) into observation space (i.e., T_b and σ_0)
 - ▶ Enables integration of T_b , σ_0 , and δh in geophysical realm (i.e., SWE and snow depth)
 - ▶ Multiple frequencies/polarizations/observations allow for flexibility and modularity in DA framework
- Snow **OSSE is on-going** → open to suggestions!



Research Summary

ESC 2017

Ottawa, Canada

Bart Forman

Observation
Types

Objectives

OSSE

TAT-C

Hyperplanes
Eulerian Grid
Single Platform
Constellation
Trade-off Space

Machine Learning

Emulators
Variability
Experiments

Conclusions

- Global snow mission planning will require **evidence of achievable science** via OSSE
- Land Information System (LIS) provides “nature run” plus assimilation framework
- TAT-C provides **spatiotemporal sub-sampling** of observations, including **cost estimates and risk assessments**
- **Machine learning** maps model state(s) into observation space (i.e., T_b and σ_0)
 - ▶ Enables integration of T_b , σ_0 , and δh in geophysical realm (i.e., SWE and snow depth)
 - ▶ **Multiple frequencies/polarizations/observations** allow for flexibility and modularity in DA framework
- Snow **OSSE is on-going** → open to suggestions!



Research Summary

ESC 2017

Ottawa, Canada

Bart Forman

Observation
Types

Objectives

OSSE

TAT-C

Hyperplanes
Eulerian Grid
Single Platform
Constellation
Trade-off Space

Machine Learning

Emulators
Variability
Experiments

Conclusions

- Global snow mission planning will require **evidence of achievable science** via OSSE
- Land Information System (LIS) provides “nature run” plus assimilation framework
- TAT-C provides **spatiotemporal sub-sampling** of observations, including **cost estimates and risk assessments**
- **Machine learning** maps model state(s) into observation space (i.e., T_b and σ_0)
 - ▶ Enables integration of T_b , σ_0 , and δh in geophysical realm (i.e., SWE and snow depth)
 - ▶ **Multiple frequencies/polarizations/observations** allow for flexibility and modularity in DA framework
- Snow **OSSE is on-going** → open to suggestions!



ESC 2017
Ottawa, Canada

Bart Forman

Observation
Types

Objectives

OSSE

TAT-C

Hyperplanes
Eulerian Grid
Single Platform
Constellation
Trade-off Space

Machine Learning

Emulators
Variability
Experiments

Conclusions

Thank You.

Questions and/or Comments?

Financial support provided by:

NASA **New Investigator Program** (NNX14AI49G)

NASA **GRACE-FO Science Team** (NNX16AF17G)

NASA **High Mountain Asia Science Team** (NNX17AC15G)



High-performance computing support provided by
UMD's Division of Information Technology