



Sums of residues on algebraic surfaces and application to coding theory

Alain Couvreur

Institut de Mathématiques de Toulouse, UMR 5219, Université Paul Sabatier, 118 route de Narbonne, 31062 Toulouse, France

ARTICLE INFO

Article history:

Received 17 June 2008

Received in revised form 6 January 2009

Available online 1 May 2009

Communicated by J. Walker

MSC:

14J99

14J20

14G50

94B27

ABSTRACT

In this paper, we study residues of differential 2-forms on a smooth algebraic surface over an arbitrary field and give several statements about sums of residues. Afterwards, using these results, we construct algebraic–geometric codes which are an extension to surfaces of the well-known differential codes on curves. We also study some properties of these codes and extend to them some known properties for codes on curves.

© 2009 Elsevier B.V. All rights reserved.

0. Introduction

The present paper is divided in two parts. The first part is a theoretical study of residues of differential 2-forms on algebraic surfaces over an arbitrary field. The second part uses results of the first part to construct differential codes on algebraic surfaces and to study some of their properties. The reader especially interested in coding theory is encouraged to read briefly the definitions and the results of the first part and then to jump to the second part.

About residues

If the notion of residue is well known for differential forms on curves, there is no unified definition in higher dimension. On complex varieties, one can distinguish two objects called residues in the literature. The first one appears for instance in the book by Griffiths and Harris ([1] chapter V). In this book, given an n -dimensional variety X , the residue of a meromorphic n -form ω at a point P is a complex number obtained by computing an integral on a real n -cycle. This object depends on some n -uplet of divisors whose sum contains the poles of ω in a neighborhood of P . Another definition is given in *Compact complex surfaces* by Barth, Hulek, Peters and Van De Ven ([2] II.4). In this book, given an n -dimensional variety X and a 1-codimensional subvariety Y of X , the residue along Y of a q -form on X having a simple pole along Y is a $(q-1)$ -form on Y . The computation of this residue can be obtained by a combinatorial way, or by computing an integral on a real subvariety ([2] II.4).

In algebraic geometry over an arbitrary field, several references deal with *residues*, for instance Hartshorne [3] or Lipman [4]. Actually their main objective is to establish duality theorems generalizing Serre's one. Thus, their first intention is not to define residues of differential forms on higher-dimensional varieties over an arbitrary field.

The goal of the first part of this paper is to generalize to surfaces over an arbitrary field, the definitions of residues given for complex varieties in [2] and in [1]. Then, we will establish results of independence on the choice of local coordinates, and focus on summation properties. Notice that Hartshorne, in [3] III.9, introduces a *Grothendieck residue symbol* having slightly the same properties as the residue defined in Griffiths and Harris's book. Moreover, Lipman (in [4] Section 12) states a summation residue formula which is closed to [Theorem 6.8](#) in the present paper. Finally, most of the results of this first part can be considered as consequences of several statements lying in [3] or [4]. Nevertheless, both references are long and

E-mail address: couvreur@math.univ-toulouse.fr.

contain an important functorial machinery which is not necessary to define residues on surfaces, to study their properties and to obtain summation formulas. That is why we decided to present a self-contained paper for which references [3,4] are not prerequisites.

Notice that we chose to work only on surfaces. At least two main reasons justify this choice. First, working on n -dimensional varieties would have given too heavy notations. Second, the most difficult step in algebraic–geometric coding theory lies between curves and higher-dimensional varieties.

About algebraic–geometric codes

In coding theory, two main problems are frequently studied. The first one is: *how to find a lower bound for its minimal distance of a given code*. The second one is: *how to find algorithms correcting a suitable number of errors in a reasonable time*. Given an arbitrary code defined by a generator or a parity-check matrix, both problems are very difficult. A good way to solve them is to get a geometric (or arithmetic) *realization* of the code. Then, one or both problems may be translated into geometric (or arithmetic) problems. This is, for instance, successful for the study of Reed–Müller codes. Consequently, geometric constructions of codes are often interesting.

Codes on curves

In 1981, Goppa introduced a construction of error-correcting codes using algebraic curves (see [5]). Their study has been a fruitful topic of research during the last thirty years. Hundreds of papers are devoted to this subject. One of the main reasons why these codes have been so intensively studied is that some families of such codes have excellent asymptotic parameters. In particular, Tsfasman, Vlăduț and Zink proved in [6] that some families of algebraic–geometric codes beat the Gilbert–Varshamov bound. Most of the basic results about codes on curves are summarized in [7], in [8] chapter II and in [9].

Codes on higher-dimensional varieties

In higher dimension, the topic has not been as extensively explored. The first general construction of algebraic–geometric codes from a variety of arbitrary dimension was given by Manin in the paper with Vlăduț [10]. Subsequently, codes coming from some particular varieties have been studied. Among others, in [11], Aubry dealt with codes on quadric varieties. His results have been improved in dimension 2 and 3 by Edoukou in [12] and [13]. Codes on Grassmannians have been discussed by Nogin in [14], then by Ghorpade and Lachaud in [15]. Codes on Hermitian varieties have been treated by Chakravarti in [16], then by Hirschfeld, Tsfasman and Vlăduț in [17], afterwards by Sørensen in his PhD thesis [18] and by Edoukou in [19]. In [20], Rodier presented a unified point of view for some of the above-cited examples regarding these varieties as flag-varieties and gave some more examples of codes. Zarzar studied in [21] the parameters of codes on surfaces having a small Picard number. The author also proposed a decoding algorithm for such codes in a joint work with Voloch [22]. General bounds on the parameters of codes on algebraic varieties of arbitrary dimension have been given by Lachaud in [23] and by Søren Have Hansen in [24]. Finally, a survey paper [25] by Little summarizing most of the known works on codes on higher-dimensional varieties appeared recently.

Notice that almost all the above cited references deal with the question of bounding or evaluating the parameters of some error-correcting codes. This will not be the purpose of the present paper whose objective is to give general theoretical statements extending some known results for codes on curves.

Different construction of codes on curves

In the theory of algebraic–geometric codes on curves, one can distinguish two different constructions. *Functional codes* are obtained by evaluating elements of a Riemann–Roch space at some set of rational points on a curve. *Differential codes* are obtained by evaluating residues of some rational differential forms at these points. For higher-dimensional varieties, only the functional construction has been extended and studied (see references below). The differential one does not seem to have a natural generalization and this question has never been treated before.

Motivations

There are at least three motivations for an extension to surfaces of the differential construction. The first one is historical. Indeed, the first construction of algebraic–geometric codes given by Goppa in [5] used differentials. This construction generalized that of classical Goppa codes which can be regarded as differential codes on the projective line. The second one is that the orthogonal of a functional code on a curve is a differential one. Moreover, this statement is used in almost all known algebraic decoding algorithms (see [26]). The third motivation is that, as said before, it is always interesting to have a geometric realization of a code. To finish with motivations, notice that the introduction of the above cited survey paper [25] of Little contains the following sentences.

“In a sense, the first major difference between higher dimensional varieties and curves is that points on X of dimension ≥ 2 are subvarieties of codimension ≥ 2 , not divisors. This means that many familiar tools used for Goppa codes (e.g. Riemann–Roch theorems, the theory of differentials and residues etc.) do not apply exactly in the same way.”

Thus, finding another way of applying residues and differentials for codes on surfaces must be interesting. This is the purpose of the second part of this paper, which starts with the presentation of a construction of codes using residues of differential 2-forms on surfaces. Then, connections between these codes and the functional ones are studied. We

proves that any differential code is included in the orthogonal of a functional one but that the reverse inclusion is false, which is an important difference with the theory of codes on curves. Notice that Voloch and Zarzar suggested the existence of such a difference in [22] Section 3 without proving it. Finally, we prove that, as for codes on curves, a differential code can always be regarded as a functional one associated with some parameters depending on a canonical divisor.

Contents

The first part contains Sections 1–6. In Section 1, we recall the definition of 1-codimensional residues along a curve C of a differential 2-form ω having C as a simple pole. Then, we define naturally the 2-codimensional residue of ω along C at a smooth point $P \in C$ to be the residue at P of the 1-codimensional residue. In Section 2 we study Laurent series expansions in two variables, in order to have a combinatorial definition for residues, which will be more convenient for computations. In Section 3, we introduce new definitions of 1- and 2-codimensional residues holding for any rational 2-form. Then, we prove that the 2-codimensional residue at a point P along a curve $C \ni P$ of a rational 2-form does not depend on a choice of local coordinates. In Section 4, we study some properties of 1- and 2-codimensional residues. In Section 5, we define 2-codimensional residues along a curve at a singular point of it. Finally, Section 6 contains three statements about summations of residues.

The second part contains Sections 7–10. Section 7 is a quick review of the theory of codes on curves. In Section 8, after a brief overview of functional codes on higher-dimensional varieties, we define differential codes on surfaces. Then, properties of these codes and their relations with functional ones are studied in Section 9. In particular, we prove that a differential code is contained in the orthogonal of a functional one. Finally, Section 10 proves that the reverse inclusion may be false by treating the elementary example of the surface $\mathbf{P}^1 \times \mathbf{P}^1$.

Part 1. Residues of a rational 2-form on a smooth surface

Notations

For any irreducible variety X over a field k , we denote by $k(X)$ its function field. If Y is a closed irreducible subvariety of X , then the local ring (resp. its maximal ideal) of regular functions in a neighborhood of Y , that is functions which are regular in at least one point of Y , is denoted by $\mathcal{O}_{X,Y}$ (resp. $\mathfrak{m}_{X,Y}$). The $\mathfrak{m}_{X,Y}$ -adic completion of the ring $\mathcal{O}_{X,Y}$ is denoted by $\widehat{\mathcal{O}}_{X,Y}$ and its maximal ideal $\widehat{\mathfrak{m}}_{X,Y}$. For any function $u \in \mathcal{O}_{X,Y}$, we denote by \bar{u} its restriction to Y . Recall that, if Y has codimension 1 in X and is not contained in the singular locus of X , then $\mathcal{O}_{X,Y}$ is a discrete valuation ring with residue field $k(Y)$. In this situation, the valuation along Y is denoted by val_Y . Finally, we denote by $\Omega_{k(X)/k}^i$ the space of k -rational differential i -forms on X .

1. About 1- and 2-codimensional residues

Context

In this section, k denotes an arbitrary field of arbitrary characteristic and S a smooth geometrically integral quasi-projective surface over k . Moreover, C denotes an irreducible geometrically reduced curve embedded in S and P a smooth rational point of C .

1.1. First definitions for residues

Given a 2-form $\omega \in \Omega_{k(S)/k}^2$, one can construct two objects called *residues* in the literature. The first one is a rational 1-form on a curve embedded in S and the second one is an element of k (or of some finite extension of it). Their definitions will be the respective purposes of Definitions 1.3 and 1.4. We first need the next proposition, asserting the well-definition of 1-codimensional residues (Definition 1.3).

Proposition 1.1. *Let v be a uniformizing parameter of $\mathcal{O}_{S,C}$ and ω be a rational 2-form on S having $\mathfrak{m}_{S,C}$ -valuation greater than or equal to -1 . Then, there exists $\eta_1 \in \Omega_{k(S)/k}^1$ and $\eta_2 \in \Omega_{k(S)/k}^2$, both regular in a neighborhood of C and such that*

$$\omega = \eta_1 \wedge \frac{dv}{v} + \eta_2. \tag{1}$$

Moreover, the differential form $\eta_{1|C} \in \Omega_{k(C)/k}^1$ is unique and depends neither on the choice of v nor on that of the decomposition (1).

Proof. We first prove the existence of a decomposition (1). Recall that

$$\dim_{k(S)} \Omega_{k(S)/k}^1 = 2 \quad \text{and} \quad \dim_{k(S)} \Omega_{k(S)/k}^2 = 1, \tag{2}$$

(see [27] thm III.5.4.3). Consequently, there exists a rational 1-form μ , which is non- $k(S)$ -colinear with $\frac{dv}{v}$. Thus, $\mu \wedge \frac{dv}{v} \neq 0$. From (2), there also exists a unique function $f \in k(S)$ satisfying

$$\omega = f\mu \wedge \frac{dv}{v}.$$

Since $\text{val}_C(\omega) \geq -1$, the 1-form $f\mu$ has no pole along C . We obtain a decomposition (1) by setting $\eta_1 := f\mu$ and $\eta_2 := 0$.

Obviously, this decomposition is far from being unique. Only $\eta_{1|C}$ is unique. To prove the uniqueness and independence of $\eta_{1|C}$ under the choice of v , see [2] II.4. Even if this book only deals with complex surfaces, the very same proof holds for surfaces over an arbitrary field. \square

Remark 1.2. Another proof of Proposition 1.1 will be given in Section 3 in a more general context (see Lemma 3.9).

Definition 1.3. Under the assumptions of Proposition 1.1 and given a decomposition of the form (1) for ω , the 1-form $\eta_{1|C} \in \Omega_{k(C)/k}^1$ is called the 1-codimensional residue (or the 1-residue) of ω along C and is denoted by

$$\text{res}_C^1(\omega) := \eta_{1|C}.$$

Definition 1.4. Under the assumptions of Proposition 1.1, let P be a k -rational point of C . The 2-codimensional residue (or the 2-residue) of ω at P along C is the residue at P of the 1-residue of ω along C . That is,

$$\text{res}_{C,P}^2(\omega) := \text{res}_P(\text{res}_C^1(\omega)).$$

Notice that to define residues in this way, ω needs to have valuation greater than or equal to -1 along C . However, 2-codimensional residues can actually be defined for any rational differential form even if it has a multiple pole along C . This will be the purpose of Sections 2–4.

Remark 1.5. It would have been natural to define 2-residues at a closed point P of C . Nevertheless, we decided to keep a more geometric point of view, even if the base field is not supposed to be algebraically closed. Notice that any geometric point of S (i.e. a closed point of $S \times_k \bar{k}$) is a rational point of $S \times_k L$ for a suitable finite scalar extension L/k . Consequently, if we define residues at rational points of S , it is easy to extend this definition to geometric points using such a scalar extension. The only arithmetic statement we will need in the second part of the present paper is that, if C is defined over k and $P \in C(k)$, then the 2-residue along C at P of a k -rational 2-form is in k . That is why we keep considering non-algebraically closed fields in Sections 1–3 and 5.

However, in Sections 4 and 6, when we deal with properties of residues and particularly with summations of them, we work over an algebraically closed field.

2. Laurent series in two variables

As is well known, the residue at a point P on a curve C of a 1-form can be computed using Laurent series expansions. The residue of a differential form at a point P is the coefficient of degree -1 of its Laurent series expansion. We look for a similar definition in the two-dimensional case. For this purpose we introduce Laurent series in two variables.

Context. The context of this section is exactly that of Section 1.

2.1. Laurent series expansion, the first construction

Recall that C is assumed to be a geometrically reduced irreducible curve over k embedded in S and P a smooth rational point of C .

Definition 2.1. A pair $(u, v) \in \mathcal{O}_{S,P}^2$ is said to be a strong (P, C) -pair if the following conditions are satisfied.

- (1) (u, v) is a system of local parameters at P .
- (2) v is a uniformizing parameter of $\mathcal{O}_{S,C}$.

Lemma 2.2. Let (u, v) be a strong (P, C) -pair, then there exists a morphism $\phi : k(S) \hookrightarrow k((u))(v)$ sending $\mathcal{O}_{S,P}$ into $k[[u, v]]$ and $\mathcal{O}_{S,C}$ into $k((u))[[v]]$.

Proof. We will prove the existence of $\phi_0 : \mathcal{O}_{S,C} \hookrightarrow k((u))[[v]]$ entailing that of ϕ , thanks to the universal property of fraction fields. From [27] II.2, any element of $\mathcal{O}_{S,P}$ has a unique Taylor series expansion in the variables u, v . Then, notice that $\mathcal{O}_{S,C}$

and $\mathcal{O}_{S,P(v)}$ are isomorphic and consider the following diagram.

$$\begin{array}{ccccc}
 \mathcal{O}_{S,P} & \xrightarrow{\text{loc}} & \mathcal{O}_{S,C} & \xrightarrow{\text{comp}} & \widehat{\mathcal{O}}_{S,C} \\
 \downarrow & & \downarrow \exists! & & \downarrow \exists! \\
 k[[u, v]] & \xrightarrow{\text{loc}} & k[[u, v]]_{(v)} & \xrightarrow{\text{comp}} & \widehat{k[[u, v]]}_{(v)}
 \end{array}$$

The horizontal arrows in the left-hand square correspond to localizations and the ones in the right-hand square correspond to (v) -adic completions. Vertical arrows are obtained by applying respectively universal properties of localization and completion. We now have to prove that $\widehat{k[[u, v]]}_{(v)}$ is isomorphic to $k((u))[[v]]$, which is a consequence of Cohen’s structure theorem (see [28] thm 7.7 or [29] thm 9 for an historical reference). \square

2.2. Laurent series, the second construction

Let (u, v) be a strong (P, C) -pair. Cohen’s structure theorem asserts that $\widehat{\mathcal{O}}_{S,C}$ is isomorphic to $k(C)[[v]]$. Unfortunately, this isomorphism is not always unique. Indeed, [29] thm 10(c) asserts that, if $\text{Char}(k) > 0$, then there are infinitely many subfields of $\widehat{\mathcal{O}}_{S,C}$ which are isomorphic to the residue field $k(C)$. Therefore, to use this isomorphism for Laurent series expansions, we have to choose a representant of $k(C)$ which is, in some sense, related to u .

Proposition 2.3 (The Field \mathcal{K}_u). *Let $u \in \mathcal{O}_{S,C}$ whose restriction \bar{u} to C is a separating element (see [8] p. 127 for a definition) of $k(C)/k$. Then, there exists a unique subfield $\mathcal{K}_u \subset \widehat{\mathcal{O}}_{S,C}$ containing $k(u)$ and isomorphic to $k(C)$ under the morphism $\widehat{\mathcal{O}}_{S,C} \rightarrow \widehat{\mathcal{O}}_{S,C}/\widehat{\mathfrak{m}}_{S,C}$. Furthermore, this field is generated over $k(u)$ by an element $y \in \widehat{\mathcal{O}}_{S,C}$.*

Proof. The extension $k(C)/k(\bar{u})$ is finite and separable. Thus, from the primitive element theorem, there exists a function $\bar{y} \in k(C)$ generating $k(C)$ over $k(\bar{u})$. From Hensel’s lemma, \bar{y} lifts to an element $y \in \widehat{\mathcal{O}}_{S,C}$ and the subring $\mathcal{K}_u := k(u)[y] \subset \widehat{\mathcal{O}}_{S,C}$ is the expected copy of $k(C)$. The uniqueness of \mathcal{K}_u is a consequence of the uniqueness of the Hensel lift y of \bar{y} . \square

Corollary 2.4. *Under the assumptions of Proposition 2.3, any element $f \in \widehat{\mathcal{O}}_{S,C}$ has a unique expansion in $\mathcal{K}_u[[v]]$.*

Proof. Existence. Let f be an element of $\widehat{\mathcal{O}}_{S,C}$ and f_0 be the Hensel lift in \mathcal{K}_u of $f \bmod \widehat{\mathfrak{m}}_{S,C}$. The $\widehat{\mathfrak{m}}_{S,C}$ -adic valuation of $f - f_0$ is greater than or equal to one. By induction, using the same reasoning on $v^{-1}(f - f_0)$ we obtain an expansion $f = f_0 + f_1v + \dots$ for f .

Uniqueness. Assume that f has two distinct expansions $\sum_j f_j v^j$ and $\sum_j \tilde{f}_j v^j$ in $\mathcal{K}_u[[v]]$. Let j_0 be the smallest integer such that $f_{j_0} \neq \tilde{f}_{j_0}$. From Proposition 2.3, a nonzero element of $\mathcal{K}_u \subset \widehat{\mathcal{O}}_{S,C}$ has $\widehat{\mathfrak{m}}_{S,C}$ -adic valuation zero. Consequently, 0 has $\widehat{\mathfrak{m}}_{S,C}$ -adic valuation j_0 , which is absurd. \square

The second Laurent series expansion using Cohen’s structure theorem needs weaker conditions on the pair (u, v) . Thus, before we define it, we give a new definition.

Definition 2.5. A pair $(u, v) \in \mathcal{O}_{S,C}^2$ is said to be a weak (P, C) -pair if \bar{u} is a uniformizing parameter of $\mathcal{O}_{C,P}$ and v is a uniformizing parameter of $\mathcal{O}_{S,C}$.

Remark 2.6. Obviously, a strong (P, C) -pair is weak, but the converse statement is false (see next example).

Example 2.7. Assume that S is the affine plane over \mathbf{C} , the curve C is the line of equation $y = 0$ and P is the origin. Set $u := \frac{(x+y)(x-y)}{x}$ and $v := xy$. Then, (u, v) is a weak (P, C) -pair which is not strong.

Now, we can define the second way of Laurent series expansion.

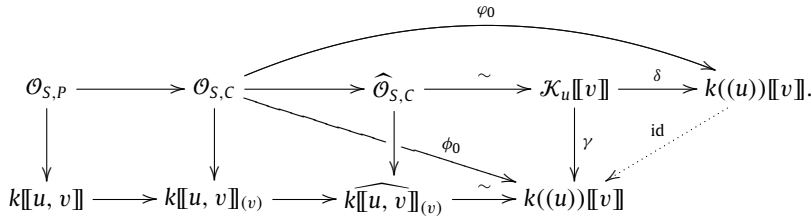
Lemma 2.8. *Given a weak (P, C) -pair (u, v) , there is an injection $\varphi : k(S) \hookrightarrow k((u))(v)$ sending $\mathcal{O}_{S,C}$ in $k((u))[[v]]$.*

Proof. As in the proof of Lemma 2.2, we just have to prove the existence of a morphism $\varphi_0 : \mathcal{O}_{S,C} \hookrightarrow k((u))[[v]]$. The curve C is assumed to be geometrically reduced; thus from [30] prop II.4.4 (i), the extension $k(C)/k$ is separable and hence has a separable transcendence basis. Moreover, the function \bar{u} is a uniformizing parameter of $\mathcal{O}_{C,P}$; thus its differential $d\bar{u}$ is nonzero and, from [31] thm V.16.7.5, it is a separating element of $k(C)/k$. From Proposition 2.3, there is an injection $\mathcal{O}_{S,C} \hookrightarrow \mathcal{K}_u[[v]]$. Furthermore, there is a natural extension $\mathcal{K}_u \hookrightarrow k((u))$, coming from the (\bar{u}) -adic completion of $k(C) \cong \mathcal{K}_u$. Applying this extension coefficientwise on $\mathcal{K}_u[[v]]$ we obtain the morphism φ_0 . \square

The next proposition links both Laurent series expansions.

Proposition 2.9. *If (u, v) is a strong (P, C) -pair, then the Laurent series expansions of Lemmas 2.2 and 2.8 are the same. That is, $\phi = \varphi$.*

Proof. Consider again the diagram in 2.1 including the new expansion



Maps γ and δ correspond respectively to the first and the second expansion. We have to prove that $\phi_0 = \varphi_0$, which is equivalent to $\gamma = \delta$.

Recall that, from Proposition 2.3, the field \mathcal{K}_u is generated over $k(u)$ by an element $y \in \widehat{\mathcal{O}}_{S,C}$. Thus, a local morphism $\mathcal{K}_u[[v]] \rightarrow k((u))[[v]]$ is entirely determined by the images of u, v and y . Obviously, δ sends u and v respectively on themselves, and from the commutativity of the left part of the diagram, so does γ . The only nonobvious part is to prove that γ sends y on $\psi(u)$, where $\psi(\bar{u})$ denotes the (\bar{u}) -adic expansion of \bar{y} .

Let $F \in k(\bar{u})[T]$ be the minimal polynomial of \bar{y} over $k(\bar{u})$. The formal function y is the unique root of F in $\widehat{\mathcal{O}}_{S,C}$ whose class in the residue field $k(C)$ is \bar{y} . Therefore, the morphism γ must send y on the unique root of F in $k((u))[[v]]$ which is congruent to $\psi(u)$ modulo (v) . Moreover, $\psi(\bar{u}) = \bar{y}$, then $F(\bar{u}, \psi(\bar{u})) = 0$; thus the formal series $F(X, \psi(X)) \in k[[X]]$ is zero. Consequently, $F(u, \psi(u))$ is zero in $k((u))$ and hence is zero in $k((u))[[v]]$. Then, $\psi(u)$ is a root of $F(u, T) \in k((u))[[v]][T]$ whose class in the residue field $k((u))$ equals $\psi(u)$. Such a root is unique. Thus, $\gamma(y) = \psi(u)$. \square

2.3. Change of coordinates

In this subsection, we define 1- and 2-residues of any differential 2-form ω using weak (P, C) -pairs. These definitions hold even if C is a multiple pole of ω . Afterwards, we prove that the new definition of 2-residue does not depend on the choice of a weak (P, C) -pair. For that, we must describe changes of weak (P, C) -pairs.

Lemma 2.10. Let (u, v) and (x, y) be two weak (P, C) -pairs; then the Laurent series expansions of u and v in $k((x))[[y]]$ are of the form

$$\begin{cases} u = f(x, y) & \text{with } f(x, 0) \in xk[[x]] \setminus x^2k[[x]] \\ v = g(x, y) & \text{with } g \in yk((x))[[y]] \setminus y^2k((x))[[y]] \end{cases} \tag{CV}$$

Proof. Functions \bar{u} and \bar{x} are both uniformizing parameters in $\mathcal{O}_{C,P}$; thus $\bar{u} = f(\bar{x}, 0) \in \bar{x}k[[\bar{x}]] \setminus \bar{x}^2k[[\bar{x}]]$. Both functions v and y are uniformizing parameters of $\mathcal{O}_{S,C}$; then v/y is invertible in $\mathcal{O}_{S,C}$, that is $v/y \in k((x))[[y]]^\times$. \square

3. General definition of 2-codimensional residues

Laurent series have been introduced in Section 2 because they are useful for computations. Using them, one can define 1- and 2-residues in a more general context.

Context

The context of this section is exactly that of Section 1.

Definition 3.1. Let $\omega \in \Omega_{k(S)/k}^2$ and (u, v) be a weak (P, C) -pair. Then, there exists a unique function $h \in k(S)$, such that $\omega = hdu \wedge dv$ and h has a Laurent series expansion $h = \sum_j h_j(u)v^j$.

(1) The (u, v) -1-residue of ω along C in a neighborhood of P is defined by

$$(u, v)\text{res}_{C,P}^1(\omega) := h_{-1}(\bar{u})d\bar{u} \in \Omega_{k(C)/k}^1.$$

(2) The (u, v) -2-residue of ω at P along C is defined by

$$(u, v)\text{res}_{C,P}^2(\omega) := \text{res}_P((u, v)\text{res}_{C,P}^1(\omega)) = h_{-1,-1} \in k.$$

Remark 3.2. Proposition 2.9 asserts that $(u, v)\text{res}_{C,P}^1(\omega)$ is a rational differential form and not a formal one. This is the reason why we introduced this second way of Laurent series expansion.

Remark 3.3. Obviously, if $\text{val}_C(\omega) \geq -1$, Definition 3.1 coincides with Definitions 1.3 and 1.4.

Remark 3.4. In this definition of 1-codimensional residues, we specify the point P . This 1-form is supposed to give us information about ω only in a neighborhood of P . However, we will see in Section 4.2 that this 1-codimensional residue is actually a global object on C and hence independent of P .

Now we will prove the following statements.

- (1) The 1-codimensional residues do not depend on the choice of v .
- (2) The 2-codimensional residues do not depend on the choice of u and v .

Caution. In what follows, we sometimes deal with formal differential forms, that is objects of the form $fdu \wedge dv$, where $f \in k((u))((v))$. Using such a general point of view is necessary in some parts of the next proofs (for instance those of Theorem 3.6 and Proposition 4.6). Definitions of 1- and 2-codimensional residues extend naturally to formal forms.

Lemma 3.5. *The morphism $k((u))((v)) \rightarrow k((x))((y))$ given by a change of variables (CV) in Lemma 2.10 is well defined and sends series (resp. formal forms) with (v) -adic valuation $n \in \mathbb{Z}$ on series (resp. formal forms) with (y) -adic valuation n .*

Proof. See Appendix A. \square

Theorem 3.6 (Invariance of 2-Residues Under (CV)). *Let $\omega = h(u, v)du \wedge dv$ be a formal 2-form and $(x, y) \in k((u))((v))^2$ connected with (u, v) by a change of variables of the form (CV). Then,*

$$(u, v)\text{res}_{C,P}^2(\omega) = (x, y)\text{res}_{C,P}^2(\omega).$$

The proof of this proposition will use forthcoming Lemmas 3.7 and 3.9. First, notice that the change of coordinates (CV) in Lemma 2.10 can be applied in two steps. First, from (u, v) to (u, y) , then from (u, y) to (x, y) . That is,

$$\text{first (CV1)} \begin{cases} u = u \\ v = \gamma(u, y) \end{cases}, \quad \text{then (CV2)} \begin{cases} u = f(x, y) \\ y = y \end{cases},$$

where γ is a series in $yk((u))[[y]] \setminus y^2k((u))[[y]]$ satisfying $g(x, y) = \gamma(f(x, y), y)$. We will prove successively that 2-residues are invariant under (CV1) and (CV2).

Lemma 3.7 (Invariance of 1-Residues Under (CV1)). *Let ω be a formal 2-form. For all y linked to (u, v) by a change of variables (CV1): $v = \gamma(u, y)$, we have*

$$(u, v)\text{res}_{C,P}^1(\omega) = (u, y)\text{res}_{C,P}^1(\omega).$$

Proof. The 2-form ω is of the form $\omega = hdu \wedge dv$ for some $h \in k((u))((v))$. After applying (CV1) we get

$$\omega = h(u, \gamma(u, y)) \frac{\partial \gamma}{\partial y} du \wedge dy.$$

The field $k((u))((v))$ is the (v) -adic completion of the $k((u))(v)$ regarded as a function field over $k((u))$. From [8] IV.2.9, the coefficient of v^{-1} in $h(u, v)$ equals that of y^{-1} in $h(u, \gamma(u, y))\partial\gamma/\partial y$. \square

Remark 3.8. Notice that, in the whole chapter IV of [8], the base field is assumed to be perfect, which is not true for $k((u))$ if $\text{Char}(k) > 0$. However, the proof of IV.2.9 is purely formal and holds for non-perfect base fields.

Operation (CV2) might change 1-residues. Nevertheless, we will see that it preserves 2-residues.

Lemma 3.9. *Let ω be a formal 2-form, $\omega = h(u, v)du \wedge dv$ with $h \in k((u))((v))$ such that $\text{val}_{(y)}(h) \geq -1$. Then, for any pair $(x, y) \in k((u))((v))^2$ related to (u, v) by a change of variables (CV) of Lemma 2.10, we have*

$$(u, v)\text{res}_{C,P}^1(\omega) = (x, y)\text{res}_{C,P}^1(\omega).$$

Remark 3.10. Notice that the proof of Proposition 1.1 is a direct consequence of Lemma 3.9.

Proof. From Lemma 3.7, $(u, v)\text{res}_{C,P}^1(\omega) = (u, y)\text{res}_{C,P}^1(\omega)$. Thus, we only study the behavior of residues under (CV2). Decompose ω by isolating its degree -1 term,

$$\omega = \frac{h_{-1}(u)}{y} du \wedge dy + \left(\sum_{j \geq 0} h_j(u)y^j \right) du \wedge dy = \omega_{-1} + \omega_+.$$

The formal form ω_+ has positive (y) -adic valuation. From Lemma 3.5, the change of variables (CV2) does not change this valuation. Consequently, the (x, y) -1-residue of ω is that of ω_{-1} , and after applying (CV2), we have

$$\omega_{-1} = \frac{h_{-1}(f(x, y))}{y} \frac{\partial f}{\partial x} dx \wedge dy.$$

From Lemma 3.5, $h_{-1}(f(x, y))$ has (y) -adic valuation zero. Thus,

$$(x, y) \operatorname{res}_{C, p}^1(\omega) = h_{-1}(f_0(\bar{x})) f_0'(\bar{x}) d\bar{x} = h_{-1}(f_0(\bar{x})) d(f_0(\bar{x})),$$

where $f_0(x) := f(x, 0)$. This formal 1-form equals $(u, y) \operatorname{res}_{C, p}^1(\omega) = h_{-1}(\bar{u}) d\bar{u}$, using the change of variables $\bar{u} = f(\bar{x}, 0)$. \square

For the proof of Theorem 3.6, we need also the following lemma.

Lemma 3.11. *Let $A, B \in k((u))((v))$; then for all pair of series (x, y) associated with (u, v) by a change of variables (CV), we have*

$$(x, y) \operatorname{res}_{C, p}^2(dA \wedge dB) = 0.$$

Proof. See Appendix B. \square

Proof of Theorem 3.6 if $\operatorname{Char}(k) = 0$. From Lemma 3.7 we already know that 1-residues are invariant under (CV1). Thus, we will only study their behavior under (CV2). Consider any formal 2-form

$$\omega = \sum_{j=-1}^{-2} h_j(u) y^j du \wedge dy + \sum_{j \geq -1} h_j(u) y^j du \wedge dy = \omega_- + \omega_{\text{inv}}.$$

From Lemma 3.9, the formal form ω_{inv} has an invariant 1-residue under (CV); thus so is its 2-residue. We now have to study ω_- . Since extraction of (x, y) -1- and -2-residues are k -linear operations, we may only consider 2-forms of the form

$$\omega = \phi(u) du \wedge \frac{dy}{y^n} \quad \text{with } \phi \in k((u)) \quad \text{and } n \geq 2.$$

The formal 2-form ω has a zero (u, y) -2-residue because its (u, y) -1-residue is also zero. Then, we have to prove that its (x, y) -2-residue is zero too. Before applying (CV2), we will work a little bit more on ω . First, isolate the term in u^{-1} of the Laurent series ϕ .

$$\phi(u) = \tilde{\phi}(u) + \frac{\phi_{-1}}{u}, \quad \text{where } \tilde{\phi}_i = \begin{cases} \phi_i & \text{if } i \neq -1 \\ 0 & \text{if } i = -1 \end{cases}.$$

The series $\tilde{\phi}$ has a formal primitive $\tilde{\Phi}$. Set $s := \frac{1}{(1-n)y^{n-1}}$, which is a primitive of $1/y^n$ (this makes sense because $\operatorname{Char}(k)$ is assumed to be zero). Then, we have

$$\omega = d\tilde{\Phi} \wedge ds + \phi_{-1} \frac{du}{u} \wedge ds = \omega_r + \phi_{-1} \omega_{-1}.$$

From Lemma 3.11, the form ω_r has a zero 2-residue for all pairs $(x, y) \in k((u))((v))^2$ connected to (u, v) by a change of variables (CV). Now consider $\omega_{-1} = \frac{du}{u} \wedge \frac{dy}{y^n}$ and apply (CV2),

$$\omega_{-1} = \frac{df(x, y)}{f(x, y)} \wedge \frac{dy}{y^n}.$$

Recall that f is of the form $\sum_{j \geq 0} f_j(x) y^j$ with

$$f_0(x) = f_{1,0}x + f_{2,0}x^2 + \dots \quad \text{and } f_{1,0} \neq 0.$$

Thus, one can factorize f_0 in

$$f_0(x) = f_{1,0}x \left(1 + \frac{f_{2,0}}{f_{1,0}}x + \dots \right).$$

Set

$$r(x) := \frac{f_{2,0}}{f_{1,0}}x + \frac{f_{3,0}}{f_{1,0}}x^2 + \dots \in k[[x]]$$

$$\text{and } \mu(x, y) := \frac{f_1(x)}{f_0(x)}y + \frac{f_2(x)}{f_0(x)}y^2 + \dots \in k((x))[[y]].$$

The series f has the following factorization:

$$f(x, y) = f_{1,0}x(1 + r(x))(1 + \mu(x, y)). \tag{3}$$

Moreover, for every series S in $xk[[x]]$ (resp. in $yk((x))[[y]]$) we define the formal logarithm of $1 + S$ to be

$$\log(1 + S) := \sum_{k=0}^{+\infty} (-1)^{k+1} \frac{S^k}{k}.$$

This makes sense because $\text{Char}(k) = 0$ and this series converges for the (x) -adic (resp. (y) -adic) valuation. Furthermore, $\frac{d(1+S)}{(1+S)} = d \log(1 + S)$. Using factorization (3), we obtain

$$\omega_{-1} = \frac{dx}{x} \wedge \frac{dy}{y^n} + d \log(1 + r) \wedge ds + d \log(1 + \mu) \wedge ds.$$

From Lemma 3.11, the second and third term of the sum have zero (x, y) -2-residues and the first one has zero (x, y) -1-residue and hence a zero (x, y) -2-residue. \square

Proof of Theorem 3.6 in positive characteristic. The idea is basically the same as in the proof of invariance of residues of 1-forms on curves (cf. [8] IV.2.9 or [32] prop II.7.5). One proves that the (x, y) -2-residue of ω is a polynomial expression in a finite family of coefficients of f . This polynomial has integer coefficients and depends neither on f nor on the base field k . Thus, using the result of the proof in characteristic zero and the principle of prolongation of algebraic identities ([31] prop IV.3.9), we conclude that this polynomial is zero. For more details see Appendix C. \square

Consequently, from now on, when we deal with 2-residues at P along C we will not have to specify the (P, C) -pair.

4. Properties of residues

Context

In this section, k is an **algebraically closed** field and S a smooth geometrically integral quasi-projective surface over k . Moreover, C denotes an irreducible absolutely reduced curve embedded in S and P a smooth point of C .

4.1. About 2-residues

The next lemma gives a necessary condition on ω to have nonzero 2-residues at P along C .

Lemma 4.1. *Let $\omega \in \Omega_{k(S)/k}^2$ having the curve C as a pole. Let $P \in C$ such that C is the only one pole of ω in a neighborhood of P . Then, $\text{res}_{C,P}^2(\omega) = 0$.*

Proof. Let (u, v) be a strong (P, C) -pair and $n := -\text{val}_C(\omega)$. There exists a function $h \in \mathcal{O}_{S,C}$ such that

$$\omega = hdu \wedge \frac{dv}{v^n}.$$

Furthermore, since ω has no pole but C in a neighborhood of P , the function h is in $\mathcal{O}_{S,P}$. Consequently, h has a Taylor expansion $\sum_{i \geq 0} h_i(u)v^i$, where $h_i \in k[[u]]$ for all i . Then, $(u, v)\text{res}_C^1(\omega) = h_{n-1}(\bar{u})d\bar{u}$, which is regular at P and hence has zero residue at this point. \square

4.2. About 1-residues

We will give a new definition for 1-codimensional residues generalizing the previous one. The goal is, as said in Remark 3.4, to define 1-residues as global objects on the curve C .

Proposition 4.2. *Let u, v be elements of $\mathcal{O}_{S,C}$ such that \bar{u} is a separating element of $k(C)/k$ and v is a uniformizing parameter of $\mathcal{O}_{S,C}$. Then, any 2-form $\omega \in \Omega_{k(S)/k}^2$ can be expanded as*

$$\omega = \sum_{j \geq -1} f_j v^j du \wedge dv, \tag{4}$$

where the f_j 's are elements of the Hensel lift \mathcal{K}_u of $k(C)$ over $k(u)$ in $\widehat{\mathcal{O}}_{S,C}$ (see Proposition 2.3). Furthermore, the 1-form $\bar{f}_{-1}d\bar{u}$ is rational on C and does not depend on the choice of the uniformizing parameter v of $\mathcal{O}_{S,C}$.

Proof. Recall that, from [27] thm III.5.4.3, the space $\Omega_{k(S)/k}^2$ has dimension 1 over $k(S)$. Thus, there exists a unique function $f \in k(S)$ such that $\omega = fdu \wedge dv$. From Corollary 2.4, one can expand f in $\mathcal{K}_u((v))$, which gives expansion (4). From the

construction of \mathcal{K}_u (see Proposition 2.3), \bar{f}_{-1} may be identified to a rational function on C . Thus, the 1-form $\bar{f}_{-1}d\bar{u}$ is rational on C . To prove its independence on the choice of v , the reasoning is exactly the same as in the proof of Lemma 3.7. \square

Definition 4.3. Under the assumptions of Proposition 4.2, we call (u) -1-residue of ω along C and denote by $(u)\text{res}_C^1(\omega)$ the rational 1-form $\bar{f}_{-1}d\bar{u} \in \Omega_{k(C)/k}^1$.

Remark 4.4. Using Lemma 3.9, one can prove that, if $\text{val}_C(\omega) \geq -1$, then this 1-form is also independent of the choice of u .

Remark 4.5. Let $\omega \in \Omega_{k(S)/k}^2$ and $u \in \widehat{\mathcal{O}}_{S,C}$ such that \bar{u} is a separating element of $k(C)/k$. Set

$$\mu := (u)\text{res}_C^1(\omega) \in \Omega_{k(C)/k}^1.$$

Then, at each smooth point P of C where \bar{u} is a local parameter, we have

$$(u, v)\text{res}_{C,P}^1(\omega) = \mu \quad \text{and} \quad \text{res}_{C,P}^2(\omega) = \text{res}_P(\mu). \tag{♠}$$

This remark asserts that Definition 4.3 generalizes the notion 1-codimensional residue (Definition 3.1). The next proposition extends (♠) to any smooth point of C .

Proposition 4.6. Let $\omega \in \Omega_{k(S)/k}^2$ and $u \in \mathcal{O}_{S,C}$ such that \bar{u} is a separating element of $k(C)/k$; then at each smooth point Q of C , we have

$$\text{res}_{C,Q}^2(\omega) = \text{res}_Q((u)\text{res}_C^1(\omega)).$$

Remark 4.7. In Section 5, we generalize the definition of 2-residue at P along C when C may be singular at P . Using this definition, the assumption “ C is smooth at Q ” in Remark 4.5 and Proposition 4.6 can be cancelled (see Remark 5.3).

Proof of Proposition 4.6. Set $\mu := (u)\text{res}_C^1(\omega) = \bar{f}_{-1}d\bar{u}$.

Step 1. Let $Q \in C$ at which \bar{u} is regular and $(u - \bar{u}(Q), v)$ is a weak (Q, C) -pair. Set $u_0 := u - \bar{u}(Q)$. The function \bar{u} is a local parameter of $\mathcal{O}_{C,Q}$. Moreover, $\mathcal{K}_u = \mathcal{K}_{u_0}$ and $du = du_0$. Consequently, $(u_0, v)\text{res}_{C,Q}^1(\omega) = \bar{f}_{-1}d\bar{u}_0 = \mu$ and $\text{res}_{C,Q}^2(\omega) = \text{res}_Q(\mu)$.

Step 2. Let $Q \in C$ at which \bar{u} is regular but $\bar{u} - \bar{u}(Q)$ is not a local parameter of $\mathcal{O}_{C,Q}$. Set $u_0 := u - \bar{u}(Q)$. We have $\omega = \sum_j f_j v^j du_0 \wedge dv$, but (u_0, v) is not a weak (Q, C) -pair. Let (x, v) be a weak (Q, C) -pair. The function \bar{x} is a local parameter of $\mathcal{O}_{C,Q}$, and for some $\phi \in k[[T]]$, we have

$$\bar{u}_0 = \phi(\bar{x}) \quad \text{in } k(C).$$

Let σ be the Hensel lift of \bar{x} in \mathcal{K}_u ; the last relation lifts in \mathcal{K}_u and gives $u_0 = \phi(\sigma)$. Consequently, we get a new formal expression for ω ,

$$\omega = \sum_{j \geq -l} f_j v^j \phi'(\sigma) d\sigma \wedge dv. \tag{♣}$$

Notice that $\sigma \in \widehat{\mathcal{O}}_{S,C}$ and is congruent to x modulo (v) . Therefore, σ expands in $k((x))[[v]]$ as

$$\sigma = x + \sigma_1(x)v + \sigma_2(x)v^2 + \dots$$

Thus, the pair (σ, v) is associated with (x, v) by a change of variables (CV). Using (♣) and Theorem 3.6, we conclude that

$$\text{res}_{C,Q}^2(\omega) = \text{res}_P(\bar{f}_{-1}\phi'(\sigma)d\sigma) = \text{res}_P(\bar{f}_{-1}\phi'(\bar{x})d\bar{x}) = \text{res}_P(\mu).$$

Step 3. Let $Q \in C$ at which \bar{u} is not regular. Set $t := 1/u$ and notice that

$$u = 1/t \Rightarrow k(u) = k(t) \Rightarrow \mathcal{K}_u = \mathcal{K}_t.$$

Thus, expansion of ω is of the form

$$\omega = \sum_{j \geq -l} f_j v^j \left(-\frac{dt}{t^2} \right) \wedge dv,$$

for some v , and

$$(t)\text{res}_C^1(\omega) = -\bar{f}_{-1} \frac{d\bar{t}}{\bar{t}^2} = \mu.$$

Applying the arguments of the previous steps, we conclude the proof. \square

Summary.

- (1) A 2-residue depends only on a curve and a point. Consequently, from now on, we will deal with $\text{res}_{C,P}^2$ and not $(u, v)\text{res}_{C,P}^2$ (Definition 3.1).
- (2) A 1-residue depends only on the curve and the choice of some element u of $\widehat{\mathcal{O}}_{S,C}$ whose restriction to C is a separating element of $k(C)/k$. Moreover, this object gives a global information on C and in a neighborhood of a point. From now on, we will deal with $(u)\text{res}_C^1$ (Definition 4.3) and not with $(u, v)\text{res}_{C,P}^1$ (Definition 3.1). We will also keep using map res_C^1 for 2-forms having $\mathfrak{m}_{S,C}$ -adic valuation greater than or equal to -1 .

Corollary 4.8. *Let u be a function in $\mathcal{O}_{S,C}$ whose restriction \bar{u} to C is a separating element of $k(C)/k$. Let $\pi : \widetilde{S} \rightarrow S$ be the blowup of S at P and \widetilde{C} be the strict transform of C by π . Then,*

$$(\pi^*u)\text{res}_{\widetilde{C}}^1(\pi^*\omega) = \pi_{|\widetilde{C}}^*((u)\text{res}_C^1(\omega)).$$

Proof. Surfaces $\widetilde{S} \setminus E$ and $S \setminus \{P\}$ are isomorphic under π . Furthermore, recall that P is assumed to be a smooth point of C ; thus π induces an isomorphism between \widetilde{C} and C . The 1-forms $(\pi^*u)\text{res}_{\widetilde{C}}^1(\pi^*\omega)$ and $(u)\text{res}_C^1(\omega)$ are pullbacks of each other by $\pi_{|\widetilde{C}}$ and its inverse. \square

Corollary 4.9. *Let (u, v) be a weak (P, C) -pair and $\pi : \widetilde{S} \rightarrow S$ be the blowup of S at P . Denote by \widetilde{C} the strict transform of C by π and by Q the intersection point between \widetilde{C} and the exceptional divisor. Then,*

$$\text{res}_{\widetilde{C},Q}^2(\pi^*\omega) = \text{res}_{C,P}^2(\omega).$$

5. Residues along a singular curve

Context

The context of this section is that of Sections 1–3 with only one difference: the curve C may be singular at P .

Proposition 5.1. *Let $\pi : \widetilde{S} \rightarrow S$ be a morphism obtained by a finite sequence of blowups of S and such that the strict transform \widetilde{C} of C by π is a desingularization of C at P . Then, the sum*

$$\sum_{Q \in \pi^{-1}(\{P\})} \text{res}_{C,Q}^2(\pi^*\omega)$$

does not depend on the choice of the desingularization $\pi : \widetilde{S} \rightarrow S$.

Proof. Let $\pi_1 : \widetilde{S}_1 \rightarrow S$ and $\pi_2 : \widetilde{S}_2 \rightarrow S$ be two morphisms as in the wording of the proposition. Denote by \widetilde{C}_1 and \widetilde{C}_2 the respective strict transforms of C by these two morphisms. Since both maps π_1 and π_2 induce desingularizations of C at P , the point P has the same number of preimages by π_1 and by π_2 . These preimages are respectively denoted by $P_{1,1}, \dots, P_{1,n}$ and $P_{2,1}, \dots, P_{2,n}$. By construction of π_1 and π_2 , there exists an open set $U_1 \subseteq \widetilde{C}_1$ (resp. $U_2 \subseteq \widetilde{C}_2$) containing $P_{1,1}, \dots, P_{1,n}$ (resp. $P_{2,1}, \dots, P_{2,n}$) and an isomorphism $\varphi : U_1 \rightarrow U_2$ such that $\pi_{1|U_1} = \pi_{2|U_2} \circ \varphi$. Moreover, for a suitable ordering of indexes, φ sends $P_{1,i}$ on $P_{2,i}$ for all i .

Let u be an element of $\mathcal{O}_{S,C}$ whose restriction to C is a separating element of $k(C)/k$. From Corollary 4.8, the 1-forms $(\pi_1^*u)\text{res}_{\widetilde{C}_1}^1(\pi_1^*\omega)$ and $(\pi_2^*u)\text{res}_{\widetilde{C}_2}^1(\pi_2^*\omega)$ are pullbacks of each other by φ and φ^{-1} . Consequently,

$$\forall i \in \{1, \dots, n\}, \quad \text{res}_{\widetilde{C}_1, P_{1,i}}^2(\pi_1^*\omega) = \text{res}_{\widetilde{C}_2, P_{2,i}}^2(\pi_2^*\omega).$$

We conclude by adding the last equalities for all i . \square

Definition 5.2. Under the assumptions of Proposition 5.1, the 2-residue of a 2-form $\omega \in \Omega_{k(S)/k}^2$ at P along C is defined by

$$\text{res}_{C,P}^2(\omega) = \sum_{Q \in \pi_C^{-1}(\{P\})} \text{res}_{C,Q}^2(\pi^*\omega).$$

Remark 5.3. As said in Remark 4.7, using Definition 5.2, the statement of Proposition 4.6 holds for singular points of C . To prove this, apply the same arguments as in the proof of Proposition 4.6 on a surface \widetilde{S} such that there exists a map $\pi : \widetilde{S} \rightarrow S$ inducing a normalization of C .

6. Residue formulas

We look for an analogous definition of the residue formula on curves ([32] lem II.12.3 or [8] IV 3.3) in the two-dimensional case. We will give three statements about summations of 2-residues.

Context

In this section, k is an **algebraically closed** field and S a smooth geometrically integral **projective** surface over k .

Theorem 6.1 (First Residue Formula). *Let C be a reduced irreducible projective curve embedded in S . Then,*

$$\forall \omega \in \Omega_{k(S)/k}^2, \sum_{P \in C} \text{res}_{C,P}^2(\omega) = 0.$$

Proof. Let u be an element of $\mathcal{O}_{S,C}$ whose restriction \bar{u} to C is a separating element of $k(C)/k$. If C is smooth, then apply Proposition 4.6 and the classical residue formula on curves to $(u)\text{res}_C^1(\omega)$. Else, use Definition 5.2 and apply the same arguments to a morphism $\phi : \tilde{S} \rightarrow S$ inducing a normalization of C . \square

Remark 6.2. If $\text{val}_C(\omega) \geq -1$, then from Proposition 1.1 and Definition 1.3, the 2-form ω has a 1-residue along C denoted by $\text{res}_C^1(\omega)$. Thus, in this particular situation, the last theorem is an easy consequence of the classical residue formula on curves applied to the 1-form $\text{res}_C^1(\omega)$. The nonobvious part of this proposition is that the statement holds even if $\text{val}_C(\omega) < -1$.

Theorem 6.3 (Second Residue Formula). *Let $\mathcal{C}_{S,P}$ be the set of germs of irreducible reduced curves embedded in S and containing P . Then,*

$$\forall \omega \in \Omega_{k(S)/k}^2, \sum_{C \in \mathcal{C}_{S,P}} \text{res}_{C,P}^2(\omega) = 0.$$

Remark 6.4. Notice that this sum is actually finite because almost all $C \in \mathcal{C}_{S,P}$ is not a pole of ω ; thus the 2-residue at P along this curve is zero.

Proof. Let $\omega \in \Omega_{k(S)/k}^2$ and $C_1, \dots, C_n \in \mathcal{C}_{S,P}$ be the set of its poles in a neighborhood of P . We will prove the theorem by induction on n .

Step 1. Assume that, for each pair of curves C_i, C_j with $i \neq j$, their intersection multiplicity at P is one.

If $n = 1$. From Lemma 4.1 the sum is obviously zero.

If $n = 2$. Let u_1, u_2 be respectively local equations of C_1 and C_2 . Then, (u_1, u_2) is a strong (P, C_2) -pair and (u_2, u_1) a strong (P, C_1) -pair, because C_1 and C_2 are assumed to have a normal crossing at P . Thus, for some $h \in \mathcal{O}_{S,P}$ and some positive integers n_1 and n_2 , we have

$$\omega = h \frac{du_1}{u_1^{n_1}} \wedge \frac{du_2}{u_2^{n_2}}.$$

Expand h in Taylor series $h = \sum h_{ij} u_1^i u_2^j$. Using the anticommutativity of the external product, a brief computation gives $\text{res}_{C_2,P}^2(\omega) = -\text{res}_{C_1,P}^2(\omega) = h_{n_1-1, n_2-1}$.

If $n \geq 2$. Consider $\pi : \tilde{S} \rightarrow S$ the blowup of S at P . Denote by E the exceptional divisor, by \tilde{C}_i the strict transform of C_i and by Q_i the intersection point between E and \tilde{C}_i . Points Q_i 's are all distinct and curves E and \tilde{C}_i have normal crossing at Q_i . The curve E is projective and the \tilde{C}_i 's are the only poles of $\pi^*\omega$ which cross E . Furthermore, the previous case entails $\text{res}_{\tilde{C}_i, Q_i}^2(\pi^*\omega) = -\text{res}_{E, Q_i}^2(\pi^*\omega)$ for all i . Consequently, from Corollary 4.9, we have

$$\sum_{i=1}^n \text{res}_{C_i,P}^2(\omega) = \sum_{i=1}^n \text{res}_{\tilde{C}_i, Q_i}^2(\pi^*\omega) = - \sum_{i=1}^n \text{res}_{E, Q_i}^2(\pi^*\omega)$$

and the last sum is zero from Theorem 6.1.

Step 2. In the general case, a curve C_i might be singular at P or intersect the other C_j 's with higher multiplicity. After a finite number of blowups, using Definition 5.2 and applying same arguments to the resolution tree, we get the expected result. \square

Remark 6.5. Notice that the valuation of $\pi^*\omega$ along the exceptional divisor E is not always greater than or equal to -1 . This valuation is given by the formula

$$\text{val}_E(\pi^*\omega) = 1 + \sum_{C \in \mathcal{C}_{S,P}} \text{val}_C(\omega),$$

where the set $\mathcal{C}_{S,P}$ is that of Theorem 6.3. For a proof of this formula see [33] prop V.3.3 and V.3.6. Therefore, Theorem 6.1 is necessary to conclude in the first step of the last proof.

To state the third residue formula we need to extend the definition of 2-residues at a point along a curve to 2-residues at a point along a divisor.

Definition 6.6. Let $D = n_1C_1 + \dots + n_pC_p$ be a divisor on S and $\omega \in \Omega_{k(S)/k}^2$. We define the 2-residue of ω at P to be

$$\text{res}_{D,P}^2(\omega) := \sum_{i=1}^n \text{res}_{C_i,P}^2(\omega).$$

N.B. By convention, if $P \notin C$, then the map $\text{res}_{C,P}^2$ is zero on $\Omega_{k(S)/k}^2$.

Remark 6.7. Notice that the coefficients n_i 's of D are not involved in this definition. Actually, $\text{res}_{D,P}^2$ depends only on the support of the D . The most logic notation would have been “ $\text{res}_{\text{Supp}(D)}^2$ ”, which is too heavy.

Theorem 6.8 (Third Residue Formula). Let D_a, D_b be two divisors such that the set $\text{Supp}(D_a) \cap \text{Supp}(D_b)$ is finite. Let Δ be the zero-cycle given by the set-theoretic intersection $\Delta := D_a \cap D_b$. Set $D := D_a + D_b$. Then,

$$\forall \omega \in \Omega^2(-D), \quad \sum_{P \in \text{Supp}\Delta} \text{res}_{D_a,P}^2(\omega) = \sum_{P \in S} \text{res}_{D_a,P}^2(\omega) = 0.$$

Proof. From Theorem 6.1, for each irreducible component C_i of the support of D_a , we have $\sum_{P \in C_i} \text{res}_{C_i,P}^2(\omega) = 0$. From Theorem 6.3, if a point P is out of the support of Δ , then $\text{res}_{D_a,P}^2(\omega) = 0$. A combination of both claims concludes the proof. \square

Remark 6.9. From Theorem 6.3 and under the assumptions of Theorem 6.8, for all P in S , we have

$$\text{res}_{D_a,P}^2(\omega) = -\text{res}_{D_b,P}^2(\omega).$$

Consequently, the statement in Theorem 6.8 holds replacing D_a by D_b .

Part 2. Application to coding theory

Notations

Let X be a variety defined over finite a field k . We denote by $\text{Div}_k(X)$ the group of rational Weil divisors on X , that is, the free Abelian group spanned by irreducible 1-codimensional closed subvarieties of X . If $G \in \text{Div}_k(X)$, then we use the following notations.

- (1) G^+ denotes the effective part of G .
- (2) $L(G)$ denotes the Riemann–Roch space of rational functions

$$L(G) := \{f \in k(X), (f) + G \geq 0\} \cup \{0\}.$$

- (3) $\Omega^2(G)$ denotes the Riemann–Roch space of rational 2-forms

$$\Omega^2(G) := \{\omega \in \Omega_{k(X)/k}^2, (\omega) - G \geq 0\} \cup \{0\}.$$

- (4) If $G' \in \text{Div}_k(X)$ such that the supports of G and G' have no common component in a neighborhood of P , we denote by $m_P(G, G') \in \mathbf{Z}$ the intersection multiplicity of these divisors at P .

7. About codes from curves, classical constructions

In this section, C is a smooth projective absolutely irreducible curve over a finite field \mathbf{F}_q . Let G be a rational divisor on C and P_1, \dots, P_n be a family of rational points of C avoiding the support of G . Set $D := P_1 + \dots + P_n \in \text{Div}_{\mathbf{F}_q}(C)$ and

$$\text{ev}_D : \begin{cases} L(G) \rightarrow \mathbf{F}_q^n \\ f \mapsto (f(P_i))_{i=1\dots n} \end{cases}, \quad \text{res}_D : \begin{cases} \Omega^1(G - D) \rightarrow \mathbf{F}_q^n \\ \omega \mapsto (\text{res}_{P_i}(\omega))_{i=1\dots n} \end{cases}.$$

We define the codes $C_L(D, G) := \text{Im}(\text{ev}_D)$ and $C_\Omega(D, G) := \text{Im}(\text{res}_D)$, called respectively functional code and differential code.

Both constructions are linked by the following properties.

(OR): $C_\Omega(D, G) = C_L(D, G)^\perp$.

(LΩ): For some canonical divisor K , we have $C_\Omega(D, G) = C_L(D, K - G + D)$.

See [7,8] or [9] for the proofs of these statements. Relation (OR) is a consequence of the residue formula for inclusion “ \subseteq ” and of Riemann–Roch’s theorem for the reverse one. This relation is used in almost all algebraic decoding algorithms (see [26]). Relation (LΩ) is a consequence of the weak approximation theorem ([8] thm I.3.1). It allows one to restrict the study of algebraic–geometric codes to only one class, for example functional codes, which seems to be easier to study. The goal of this second part is to extend some of these statements to surfaces.

8. Algebraic–geometric codes on surfaces

From now on, S denotes a smooth geometrically integral projective surface over \mathbf{F}_q and $\bar{S} := S \times_{\mathbf{F}_q} \bar{\mathbf{F}}_q$. Moreover, G denotes a rational divisor on S and P_1, \dots, P_n a set of rational points of S avoiding the support of G . Set $\Delta := P_1 + \dots + P_n$. Notice that Δ is not a divisor but a 0-cycle. Most of the difficulties we will meet come from this difference of dimension between G and Δ .

8.1. Functional codes

As said in the introduction, the functional construction of codes extends to higher-dimensional varieties (see [10] I.3.1). Define the map

$$\text{ev}_\Delta : \begin{cases} L(G) \rightarrow \mathbf{F}_q^n \\ f \rightarrow (f(P_1), \dots, f(P_n)) \end{cases}$$

The functional code is $C_L(\Delta, G) := \text{Im}(\text{ev}_\Delta)$. The study of such codes is really more complicated than that of codes on curves. Particularly, finding a minoration of the minimal distance becomes a very difficult problem. For more details about this topic, see the references cited in the introduction.

8.2. Differential codes

To define differential codes, we need more than G and Δ . We want to evaluate 2-residues of some rational differential forms with prescribed poles. Unfortunately, 2-residues depend not only on a point but on a flag $P \in C \subset S$. Thus, we have to input another divisor.

Definition 8.1. Let $D \in \text{Div}_{\mathbf{F}_q}(S)$ and assume that D is the sum of two divisors D_a, D_b whose supports have no common irreducible component. Then, one can define the map

$$\text{res}_{D_a, \Delta}^2 : \begin{cases} \Omega^2(G - D) \rightarrow \mathbf{F}_q^n \\ \omega \mapsto (\text{res}_{D_a, P_1}^2(\omega), \dots, \text{res}_{D_a, P_n}^2(\omega)) \end{cases}$$

The differential code is defined by $C_\Omega(\Delta, D_a, D_b, G) := \text{Im}(\text{res}_{D_a, \Delta}^2)$.

Remark 8.2. We can also define a map $\text{res}_{D_b, \Delta}^2$, but, from Theorem 6.3, we have $\text{res}_{D_b, \Delta}^2 = -\text{res}_{D_a, \Delta}^2$. Thus, both maps have the same image and

$$C_\Omega(\Delta, D_a, D_b, G) = C_\Omega(\Delta, D_b, D_a, G).$$

8.3. Δ -convenience

Actually, if one chooses an arbitrary divisor D , the last definition is not very convenient. Recall that, from Lemma 4.1 and Theorem 6.3, $\text{res}_{D_a, P_i}^2(\omega)$ is nonzero only if the supports of D_a^+ and D_b^+ intersect at P_i . Therefore, if we want to have a code which is linked to the functional code $C_L(\Delta, G)$, the divisor D must be itself related to the 0-cycle Δ . We will first define the notion of a Δ -convenient pair of divisors. Afterwards, we will give a criterion of Δ -convenience. Although this criterion may look ugly, it is actually easy to handle.

Let D_a, D_b be a pair of \mathbf{F}_q -rational divisors on S whose supports have no common component and set $D := D_a + D_b$. From now on, \mathcal{F} denotes the sheaf on \bar{S} defined by

$$\mathcal{F}(U) = \left\{ \omega \in \Omega_{\bar{\mathbf{F}}_q}^2(\bar{S})/\bar{\mathbf{F}}_q, (\omega|_U) \geq -D|_U \right\}.$$

Moreover, for all points $P \in \bar{S}$, the stalk of \mathcal{F} at P is denoted by \mathcal{F}_P (see [33] II.1 p. 62 for the definition of “stalk”). Notice that $H^0(\bar{S}, \mathcal{F}) = \Omega^2(-D) \otimes_{\mathbf{F}_q} \bar{\mathbf{F}}_q$.

Definition 8.3. The pair (D_a, D_b) is said to be Δ -convenient if it satisfies the following conditions.

- (i) Supports of D_a and D_b have no common irreducible components.
- (ii) For all points $P \in \bar{S}$, the map $\text{res}_{D_a, P}^2 : \mathcal{F}_P \rightarrow \bar{\mathbf{F}}_q$ is $\mathcal{O}_{\bar{S}, P}$ -linear.
- (iii) This map is surjective for all $P \in \text{Supp}(\Delta)$ and zero elsewhere.

Remark 8.4. The $\mathcal{O}_{\bar{S}, P}$ -module structure of $\bar{\mathbf{F}}_q$ is induced by the morphism $f \rightarrow f(P)$. Thus, if the map $\text{res}_{D_a, P}^2$ satisfies (ii), then it vanishes on $\mathfrak{m}_{\bar{S}, P} \mathcal{F}_P$.

Remark 8.5. Let $P \in \bar{S}$ and $\omega \in \mathcal{F}_P$. From Remark 6.9, we have

$$\text{res}_{D_a, P}^2(\omega) = -\text{res}_{D_b, P}^2(\omega).$$

Consequently, if at a point $P \in \bar{S}$ the map $\text{res}_{D_b, P}^2$ is $\mathcal{O}_{S, P}$ -linear and satisfies (ii) and (iii); then so does $\text{res}_{D_a, P}^2$.

Proposition 8.6 (Criterion for Δ -Convenience). Let (D_a, D_b) be a pair of \mathbf{F}_q -rational divisors having no common irreducible component on S and set $D := D_a + D_b$. If (D_a, D_b) satisfies the following conditions, then it is a Δ -convenient pair.

- (1) For each $P \in \text{Supp}(\Delta)$, there exists an irreducible curve C smooth at P such that, in a neighborhood U_P of P , either $(D_a^+)|_{U_P}$ or $(D_b^+)|_{U_P}$ equals $C|_{U_P}$ and $m_P(C, D - C) = 1$.
- (2) For each $P \in \bar{S} \setminus \text{Supp}(\Delta)$, either $D_* = D_a$ or $D_* = D_b$ satisfies the following conditions. For each $\bar{\mathbf{F}}_q$ -irreducible component \bar{C} of D_*^+ containing P ,
 - (a) the curve \bar{C} is smooth at P ;
 - (b) this curve \bar{C} appears in D_* with coefficient 1;
 - (c) $m_P(\bar{C}, D - \bar{C}) \leq 0$.

Remark 8.7. In condition (2) of this criterion, the divisor D_* may be zero in a neighborhood of P (actually, that is what happens at almost all P). In this situation, conditions (2a), (2b) and (2c) are obviously satisfied.

For the proof of this proposition we need the next lemma and its corollary.

Lemma 8.8. Let \bar{C} be an irreducible curve over $\bar{\mathbf{F}}_q$ embedded in \bar{S} and P be a smooth point of \bar{C} . Let $\omega \in \Omega_{\bar{\mathbf{F}}_q(\bar{S})/\bar{\mathbf{F}}_q}^2$ having a simple pole along \bar{C} . Then

$$\text{val}_P(\text{res}_{\bar{C}}^1(\omega)) = m_P(\bar{C}, (\omega) + \bar{C}),$$

where val_P denotes the valuation at the point P on $\Omega_{\bar{\mathbf{F}}_q(\bar{C})/\bar{\mathbf{F}}_q}^1$.

Proof. Let φ, ψ and v be respective local equations of $((\omega) + \bar{C})^+$, $((\omega) + \bar{C})^-$ and \bar{C} in a neighborhood of P . Let $u \in \bar{\mathbf{F}}_q(\bar{S})$ such that (u, v) is a strong (P, \bar{C}) -pair; then for some $h \in \mathcal{O}_{\bar{S}, P}^\times$, we have

$$\omega = h \frac{\varphi}{\psi} du \wedge \frac{dv}{v}.$$

Thus, $\text{res}_{\bar{C}}^1(\omega) = \bar{h}\bar{\varphi}\bar{\psi}^{-1}d\bar{u}$ and, since $\bar{h} \in \mathcal{O}_{\bar{C}, P}^\times$, we have $\text{val}_P(\bar{h}d\bar{u}) = 0$. Consequently,

$$\text{val}_P(\text{res}_{\bar{C}}^1(\omega)) = \text{val}_P(\bar{\varphi}) - \text{val}_P(\bar{\psi}).$$

Furthermore,

$$\begin{aligned} m_P(\bar{C}, (\omega) + \bar{C}) &= m_P(\bar{C}, ((\omega) + \bar{C})^+) - m_P(\bar{C}, ((\omega) + \bar{C})^-) \\ &= \dim_{\bar{\mathbf{F}}_q} \mathcal{O}_{\bar{S}, P}/(\varphi, v) - \dim_{\bar{\mathbf{F}}_q} \mathcal{O}_{\bar{S}, P}/(\psi, v) \\ &= \dim_{\bar{\mathbf{F}}_q} \mathcal{O}_{\bar{C}, P}/(\bar{\varphi}) - \dim_{\bar{\mathbf{F}}_q} \mathcal{O}_{\bar{C}, P}/(\bar{\psi}) \\ &= \text{val}_P(\bar{\varphi}) - \text{val}_P(\bar{\psi}). \quad \square \end{aligned}$$

Corollary 8.9. Let \bar{C} be an irreducible curve embedded in \bar{S} and P be a smooth point of \bar{C} . Let $\omega \in \Omega_{\bar{\mathbf{F}}_q(\bar{S})/\bar{\mathbf{F}}_q}^2$ such that $\text{val}_{\bar{C}}(\omega) \geq -1$ and $m_P(\bar{C}, (\omega) + \bar{C}) \geq -1$. Then,

$$\forall f \in \mathcal{O}_{\bar{S}, P}, \quad \text{res}_{\bar{C}, P}^2(f\omega) = f(P)\text{res}_{\bar{C}, P}^2(\omega).$$

Proof. Let (u, v) be a strong (P, \bar{C}) -pair and f be an element of $\mathcal{O}_{\bar{S}, P}$. Since $\text{val}_{\bar{C}}(\omega) \geq -1$, there exists $\psi \in \mathcal{O}_{\bar{S}, \bar{C}}$ such that

$$\omega = \psi du \wedge \frac{dv}{v}.$$

Set $\mu := \text{res}_{\bar{C}}^1(\omega) = \bar{\psi}d\bar{u}$. The condition $\text{val}_{\bar{C}}(\omega) \geq -1$ also entails

$$\text{res}_{\bar{C}}^1(f\omega) = \bar{f}\bar{\psi}d\bar{u} = \bar{f}\mu.$$

From Lemma 8.8, we have $\text{val}_P(\mu) = m_P(\bar{C}, (\omega) + \bar{C}) \geq -1$. Thus,

$$\text{res}_{\bar{C}, P}^2(f\omega) = \text{res}_P(\bar{f}\mu) = \bar{f}(P)\text{res}_P(\mu) = f(P)\text{res}_{\bar{C}, P}^2(\omega). \quad \square$$

Proof of Proposition 8.6. Let (D_a, D_b) be a pair of divisors satisfying the conditions of Proposition 8.6. Condition (i) of Definition 8.3 is obviously satisfied, because supports of D_a and D_b are assumed to have no common irreducible component. Now, we prove that (ii) and (iii) are satisfied. First, recall that \mathcal{F} denotes the sheaf of rational 2-forms ω on \bar{S} satisfying locally $(\omega) \geq -D = -D_a - D_b$.

Condition (ii). Let $P \in \text{Supp}(\Delta)$ and $\omega \in \mathcal{F}_P$, where \mathcal{F}_P denotes the stalk of the sheaf \mathcal{F} at P . From (1), there is an irreducible curve C , smooth at P such that either D_a^+ or D_b^+ equals C in a neighborhood of P . Using Remark 8.5, we may assume that $D_a^+ = C$ without loss of generality. Thus, C is the only one irreducible component of $\text{Supp}(D_a^+)$ in a neighborhood of P . Therefore, $\text{res}_{D_a, P}^2(\omega) = \text{res}_{C, P}^2(\omega)$. Consequently, $\text{val}_C(\omega) \geq -1$ and Corollary 8.9 asserts that $\text{res}_{C, P}^2$ (and hence $\text{res}_{D_a, P}^2$) is $\mathcal{O}_{S, P}$ -linear.

Condition (iii). Let $P \in \bar{S}$ be a point out of the support of Δ . From Remark 8.5, we may assume without loss of generality that condition (2) in Proposition 8.6 is satisfied by D_a (i.e. $D_* = D_a$ at P). Let \bar{C} be an $\bar{\mathbf{F}}_q$ -irreducible component of $\text{Supp}(D_a^+)$ and $\omega \in \mathcal{F}_P$. From (2b), $\text{val}_{\bar{C}}(\omega) \geq -1$ and, from Lemma 8.8 and (2c), we have $\text{val}_P(\text{res}_{\bar{C}}^1(\omega)) \geq 0$. Consequently, $\text{res}_{\bar{C}, P}^2(\omega) = 0$, which concludes the proof. \square

Example 8.10. Let $S = \mathbf{P}^2$ and let Δ be the sum of the rational points of an affine chart U . Let x, y be affine coordinates on U . For all $\alpha, \beta \in \mathbf{F}_q$, set $D_{a, \alpha}$ the line $\{x = \alpha\}$ and $D_{b, \beta} := \{y = \beta\}$. Now, set $D_a := \sum_{\alpha \in \mathbf{F}_q} D_{a, \alpha}$ and $D_b := \sum_{\beta} D_{b, \beta}$. The pair (D_a, D_b) satisfies the criterion of Proposition 8.6 and hence is Δ -convenient. Notice that the components of D_a (resp. D_b) intersect themselves at a point lying on the line at infinity, which does not represent any contradiction with the definition of Δ -convenience.

Notice that, in the definition, neither D_a nor D_b are assumed to be effective. In some situations, it is necessary to use noneffective divisors. This happens in next example.

Example 8.11. Consider again $S = \mathbf{P}^2$ and assume that the base field is \mathbf{F}_q with q odd. Set $\Delta = P_1 + P_2 + P_3$ with $P_1 = (0 : 0 : 1)$, $P_2 = (1 : 0 : 1)$ and $P_3 = (0 : 1 : 1)$. The pair (D_a, D_b) , defined by $D_a = \{Y = 0\} + \{Y = 1\}$ and $D_b = \{X = 0\} + \{X = 1\} - \{X + Y - 2 = 0\}$, is Δ -convenient. However, in this situation, there does not exist any Δ -convenient pair of effective divisors. The proof of the last claim is left to the reader.

9. Properties of differential codes

9.1. Orthogonality

Theorem 9.1. Let (D_a, D_b) be a Δ -convenient pair and set $D := D_a + D_b$; then

$$C_\Omega(\Delta, D_a, D_b, G) \subseteq C_L(\Delta, G)^\perp.$$

Proof. Let $\omega \in \Omega^2(G - D)$ and $f \in L(G)$; then $f\omega \in \Omega^2(-D)$, and from the definition of Δ -convenient pairs,

$$\forall P \in \bar{S}, \quad \text{res}_{D_a, P}^2(f\omega) = \begin{cases} 0 & \text{if } P \notin \text{Supp}(\Delta) \\ f(P)\text{res}_{D_a, P}^2(\omega) & \text{if } P \in \text{Supp}(\Delta) \end{cases}$$

Thus,

$$\langle \text{ev}_\Delta(f), \text{res}_{D_a, \Delta}^2(\omega) \rangle = \sum_{P \in \text{Supp}(\Delta)} f(P)\text{res}_{D_a, P}^2(\omega) = \sum_{P \in \text{Supp}(\Delta)} \text{res}_{D_a, P}^2(f\omega).$$

And the last sum is zero from Theorem 6.8. \square

In Section 10, we prove that, in some situations, the reverse inclusion is false for any choice of a Δ -convenient pair of divisors. Thus, in general, we do not have equality. An interpretation of this statement is that, even if a pair of Δ -convenient divisors is linked to Δ , it is not involved in the functional construction. This lack of canonicity in the choice of (D_a, D_b) might be the reason of this non-equality. In a forthcoming paper we will study how to get the whole orthogonal of a functional code, using differentials.

9.2. A differential code is functional

Recall that, in Section 7, we discussed two relations denoted by **(OR)** and **(L Ω)**. We just said that it is not possible to extend perfectly the orthogonality relation **(OR)**. Nevertheless, the next proposition asserts that relation **(L Ω)** holds on surfaces: a differential code is always a functional one associated with some canonical divisor. Recall that the proof of **(L Ω)** for curves is a consequence of the weak approximation theorem. Here is the required statement for surfaces.

Proposition 9.2. Let P_1, \dots, P_m and Q_1, \dots, Q_n be two families of closed points of S and C be an irreducible curve embedded in S . Suppose that the P_i 's are contained in C and the Q_j 's are out of it. Then, there exists a function $u \in \mathbf{F}_q(S)$ satisfying the following conditions.

- (i) $\forall i \in \{1, \dots, m\}$, u is a local equation of C in a neighborhood of P_i .
- (ii) $\forall j \in \{1, \dots, n\}$, $Q_j \notin \text{Supp}(u)$, i.e. $u \in \mathcal{O}_{S, Q_j}^\times$.

Proof. Choose u_0 , a uniformizing parameter of $\mathcal{O}_{S, C}$. Then $(u_0) = C + D$, where $D \in \text{Div}_{\mathbf{F}_q}(S)$, whose support does not contain C . From the moving lemma ([27] thm III.1.3.1), there exists a divisor D' linearly equivalent to D and whose support avoids $P_1, \dots, P_m, Q_1, \dots, Q_n$. Thus, for some function $f \in \mathbf{F}_q(S)$, we have $D' = D + (f)$, and $u := fu_0$ is a solution of the problem. \square

N.B. In the whole book of Shafarevich [27], the base field is assumed to be algebraically closed. Nevertheless the very same proof holds over an arbitrary field.

Corollary 9.3. Let (D_a, D_b) be a Δ -convenient pair and set $D := D_a + D_b$; then there exists a differential $\omega_0 \in \Omega_{k(S)/k}^2$ satisfying the following conditions.

- (1) For some open set U containing $\text{Supp}(\Delta)$, we have $(\omega_0|_U) = -D|_U$.
- (2) $\forall P \in \text{Supp}(\Delta)$, $\text{res}_{D_a, P}^2(\omega_0) = 1$.
- (3) $\forall P \in \text{Supp}(\Delta)$, $\forall f \in \mathcal{O}_{S, P}$, $\text{res}_{D_a, P}^2(f\omega_0) = f(P)\text{res}_{D_a, P}^2(\omega_0)$.

Proof. Let X_1, \dots, X_r and Y_1, \dots, Y_s be respectively the irreducible components of $\text{Supp}(D_a)$ and $\text{Supp}(D_b)$. That is, $D_a = m_1X_1 + \dots + m_rX_r$ and $D_b = n_1Y_1 + \dots + n_sY_s$ for some integers m_i 's and n_j 's. From Proposition 9.2 there exists an open subset U of S containing the support of Δ and functions $u_1, \dots, u_r, v_1, \dots, v_s$ such that u_i (resp v_j) is an equation of X_i (resp Y_j) in U . Set $u := \prod_i u_i^{m_i}$ and $v := \prod_j v_j^{n_j}$.

Let μ be a rational 2-form on S having neither zeros nor poles in a neighborhood of the support of Δ , and set

$$\omega_0 := \frac{\mu}{uv}.$$

Replacing U by a smaller open set containing $\text{Supp}(\Delta)$, we may assume that μ has neither zeros nor poles in U . Thus, statements (1) and (3) are satisfied by ω_0 . Moreover, from the Definition 8.3 of Δ -convenience, we have

$$\forall P \in \text{Supp}(\Delta), \quad \text{res}_{D_a, P}^2(\omega_0) = a_P \neq 0.$$

Choose $g \in \bigcap_{P \in \text{Supp}(\Delta)} \mathcal{O}_{S, P}^\times$ such that $g(P) = a_P^{-1}$ for all $P \in \text{Supp}(\Delta)$. Then, replacing U by a smaller open set containing $\text{Supp}(\Delta)$ and ω_0 by $g\omega_0$, the three conditions are satisfied. \square

Theorem 9.4. Let $D = D_a + D_b$ such that (D_a, D_b) is Δ -convenient. There exists a canonical divisor K such that

$$C_\Omega(\Delta, D_a, D_b, G) = C_L(\Delta, K - G + D).$$

Proof. From Corollary 9.3, there exists a 2-form ω_0 satisfying (1), (2) and (3). Set $K := (\omega_0)$; this divisor is of the form $K = -D + R$, where the support of R avoids that of Δ . Let $\omega \in \Omega^2(G - D)$; then, for some function $f \in L(K - G + D)$, we have $\omega = f\omega_0$. Notice that $K - G + D = -G + R$; then any function $f \in L(K - G + D)$ is regular in a neighborhood of each $P \in \text{Supp}(\Delta)$. Consequently, from condition (3) in Corollary 9.3, we have

$$\text{res}_{D_a, \Delta}^2(\omega) = \text{res}_{D_a, \Delta}^2(f\omega_0) = ev_\Delta(f). \quad \square$$

Any differential code is actually a functional one. Notice that, if the converse statement is trivial for codes on curves, it is less easy in our situation. Indeed, to prove that a functional code is differential, we have to build a Δ -convenient pair of divisors.

9.3. Converse statement, a functional code is differential

Lemma 9.5. Let Q_1, \dots, Q_m be rational points of S and set $\Gamma := Q_1 + \dots + Q_m$. Then, there exists a Γ -convenient pair (D_a, D_b) .

Proof. Step 1: Construction of D_a . Choose a curve C (which may be reducible) containing the whole support of Γ and regular at each point of it and set $D_a := \sum_k C_k$ where the C_k 's are the irreducible components of C . Finding such a curve is an interpolation problem with infinitely many solutions.

Step 2: Construction of D_b . Choose another effective divisor D' interpolating all the points of $\text{Supp}(\Gamma)$ and having no common component with D_a . Let Λ be the 0-cycle given by the scheme-theoretic intersection $D_a \cap D'$. Unfortunately, the support of Λ might be bigger than that of Γ . Thus, we have $\Lambda = \Gamma + \Gamma'$, where Γ' is an effective 0-cycle. Now choose an effective divisor D'' such that $D'' \cap D_a = \Gamma' + \Gamma''$, where Γ'' and Γ have disjoint supports. Set $D_b := D' - D''$. The pair (D_a, D_b) satisfies the criterion of Proposition 8.6, which concludes the proof. \square

Theorem 9.6. *Let G be a rational divisor on S ; then for some canonical divisor K and some divisor $D := D_a + D_b$ such that (D_a, D_b) is Δ -convenient, we have*

$$C_L(\Delta, G) = C_{\Omega}(\Delta, D_a, D_b, K - G + D).$$

Proof. Lemma 9.5 asserts the existence of a Δ -convenient pair (D_a, D_b) . Then, construct a 2-form ω_0 using Corollary 9.3. Set $K := (\omega_0)$. Now the result is an easy consequence of Theorem 9.4. \square

10. The reverse inclusion is false

As said in Section 9.1, if a differential code is included in the orthogonal of a functional one, the reverse inclusion is in general false. The study of the following example will prove this.

In this section, the surface S is the product of two projective lines $S := \mathbf{P}^1 \times \mathbf{P}^1$. Let U be an affine chart of S with affine coordinates x, y . The complement of U in S is a union of two lines E and F . The Picard group of S is generated by the classes of E and F . Thus, without loss of generality, one can choose for G the divisor $G_{n,m} := mE + nF$, with $m, n \in \mathbf{Z}$. Finally, Δ is defined as the formal sum of all rational points of U .

10.1. Functional codes on $\mathbf{P}^1 \times \mathbf{P}^1$

On U , the vector space $L(G_{m,n})$ may be identified with $\mathbf{F}_q[x]_{\leq m} \otimes_{\mathbf{F}_q} \mathbf{F}_q[y]_{\leq n}$, where $\mathbf{F}_q[t]_{\leq d}$ denotes the space of polynomials in t with degree less than or equal to d . Furthermore, the functional code $C_L(\Delta, G_{m,n})$ may be identified with a tensor product of two codes on the projective line, which are Reed–Solomon codes. Thus,

$$C_L(\Delta, G_{m,n}) = RS_q(m + 1) \otimes_{\mathbf{F}_q} RS_q(n + 1), \tag{\diamond}$$

where $RS_q(k)$ denotes the Reed–Solomon code over \mathbf{F}_q of length q and dimension k .

10.2. Orthogonal of functional codes on $\mathbf{P}^1 \times \mathbf{P}^1$

In this subsection, we prove that the orthogonal of some functional code on $\mathbf{P}^1 \times \mathbf{P}^1$ cannot be differential.

Proposition 10.1. *Let m, n be two integers such that $0 \leq n, m < q - 2$; then, for all Δ -convenient pair of divisors (D_a, D_b) , we have*

$$C_{\Omega}(\Delta, D_a, D_b, G_{m,n}) \subsetneq C_L(\Delta, G_{m,n})^{\perp}.$$

Proof. From (\diamond) and Lemma D.1 in Appendix D, we have

$$C_L(\Delta, G_{m,n})^{\perp} = RS_q(m + 1)^{\perp} \otimes_{\mathbf{F}_q} \mathbf{F}_q^q + \mathbf{F}_q^q \otimes_{\mathbf{F}_q} RS_q(n + 1)^{\perp}.$$

Suppose that, for some Δ -convenient pair (D_a, D_b) , we had

$$C_{\Omega}(\Delta, D_a, D_b, G_{m,n}) = C_L(\Delta, G_{m,n})^{\perp}.$$

From Theorem 9.4, the code $C_{\Omega}(\Delta, D_a, D_b, G_{m,n})$ is functional. Thus, from (\diamond) , it is a tensor product of two Reed–Solomon codes. But $C_L(\Delta, G_{m,n})^{\perp}$ is of the form $A \otimes \mathbf{F}_q^q + \mathbf{F}_q^q \otimes B$ with A, B nonzero and strictly contained in \mathbf{F}_q^q . This contradicts Lemma D.2 in Appendix D. \square

Remark 10.2. The condition $0 \leq m, n < q - 2$ asserts that, in the tensor product representation

$$C_L(\Delta, G_{m,n}) = RS_q(m + 1) \otimes RS_q(n + 1),$$

none of the terms of the tensor product is zero or \mathbf{F}_q^q .

A solution to avoid this lack of reverse inclusion is to try to construct the orthogonal as a sum of differential codes. The purpose of the next subsection is the realization of $C_L(\Delta, G_{m,n})^{\perp}$ as a sum of two differential codes associated with two distinct Δ -convenient pairs.

10.3. A construction of the orthogonal code

For each $\alpha \in \mathbf{F}_q$, consider the lines $D_{1,\alpha} := \{x = \alpha\}$, $D_{2,\alpha} := \{y = \alpha\}$ and $D_{3,\alpha} := \{x - y = \alpha\}$. Now set

$$D_1 := \sum_{\alpha \in \mathbf{F}_q} D_{1,\alpha}, \quad D_2 := \sum_{\alpha \in \mathbf{F}_q} D_{2,\alpha} \quad \text{and} \quad D_3 := \sum_{\alpha \in \mathbf{F}_q} D_{3,\alpha}.$$

Pairs (D_1, D_3) and (D_2, D_3) are Δ -convenient. Using them, one can realize the orthogonal of $C_L(\Delta, G_{m,n})$ as a sum of two differential codes.

Proposition 10.3. *The three following relations are satisfied.*

- (i) $C_\Omega(\Delta, D_1, D_3, G_{m,n}) = \mathbf{F}_q^q \otimes RS_q(q - 2 - n).$
- (ii) $C_\Omega(\Delta, D_2, D_3, G_{m,n}) = RS_q(q - 2 - m) \otimes \mathbf{F}_q^q.$
- (iii) $C_L(\Delta, G_{m,n})^\perp = C_\Omega(\Delta, D_1, D_3, G_{m,n}) + C_\Omega(\Delta, D_2, D_3, G_{m,n}).$

Proof. As said in last proof, relation (\heartsuit) and Lemma D.1 entail

$$C_L(\Delta, G_{m,n})^\perp = RS_q(m + 1)^\perp \otimes \mathbf{F}_q^q + \mathbf{F}_q^q \otimes RS_q(n + 1)^\perp.$$

Consequently, (i) + (ii) \Rightarrow (iii). Furthermore, by symmetry, (i) \Leftrightarrow (ii). Thus, we only have prove (i). Set

$$v := \frac{dy}{\prod_{\beta \in \mathbf{F}_q} (x - \beta)} \wedge \frac{dx}{\prod_{\alpha \in \mathbf{F}_q} (x - y - \alpha)}.$$

This form satisfies conditions (1), (2) and (3) in Corollary 9.3. Compute the divisor of v . On U , we have $(v|_U) = -D_{3|U} - D_{1|U}$. Moreover, $D_1 \sim qE$ and $D_3 \sim q(E + F)$. Since the canonical class on $\mathbf{P}^1 \times \mathbf{P}^1$ equals that of $-2(E + F)$, we have

$$(v) = (2q - 2)E + (q - 2)F - D_1 - D_3$$

and

$$\begin{aligned} C_\Omega(\Delta, D_1, D_3, mE + nF) &= C_L(\Delta, (2q - 2 - m)E + (q - 2 - n)F) \\ &= RS_q(2q - 2 - m) \otimes RS_q(q - 2 - n). \end{aligned}$$

To conclude, notice that, if $m \leq q - 1$, then $2q - 2 - m \geq q - 1$ and $RS_q(2q - 2 - m)$ equals \mathbf{F}_q^q . \square

11. Conclusion

This new construction of codes generalizes the differential construction of codes on curves. The main difference is that it is not always possible to realize the orthogonal of a functional code as a differential (or equivalently functional) one. A natural question comes from the study of last example.

Question 11.1. *Is the orthogonal of a functional code a sum of differential codes? If yes, is there an upper bound on the number of differential codes involved in this sum?*

Moreover, we now know that the orthogonal of a functional code might be non-functional. Consequently, the study of such codes might be interesting.

Note added in proof

Recently, Oleg Osipov of the Steklov Mathematical Institute informed the author of the existence of the paper [34] of Paršin which deals with residues on surfaces. In Paršin’s article, the first and second residue formulas (Theorems 6.1 and 6.3 of the present paper) are proved using nearly the same proof.

Acknowledgments

I would like to thank Gerhard Frey for his explanations about valuations, Emmanuel Hallouin for his fruitful advice on commutative and local algebra, and the anonymous referee for his conscientious work. Moreover, I am also very grateful to my advisor, Marc Perret, for all his very constructive comments about this paper.

Appendix A. Proof of Lemma 3.5

If we prove the well-definition of the morphism $k((u))[[v]] \rightarrow k((x))[[y]]$, then we conclude about that of the morphism $k((u))(v) \rightarrow k((x))(y)$, using the universal property of fraction fields. First, we have to define a topology on $k((u))[[v]]$ (resp. $k((x))[[y]]$). Recall that

$$k((u))[[v]] = \varprojlim k((u))[v]/(v^n).$$

Afterwards, using the (u) -adic topology of $k((u))$, one can define a topology of projective limit on $k((u))[[v]]$. For this topology, a sequence $(s^{(n)})_{n \in \mathbf{N}}$ defined for all n by $s^{(n)} = \sum_{j \in \mathbf{N}} s_j^{(n)}(u)v^j$ converges to zero if and only if

$$\forall j \in \mathbf{N}, \lim_{n \rightarrow +\infty} s_j^{(n)}(u) = 0, \text{ for the } (u)\text{-adic topology.}$$

Afterwards, using a Cauchy criterion, one proves that, for this topology, a series of elements of $k((u))[[v]]$ converges if and only if its general term converges to zero.

Remark A.1. Notice that this topology on $k((u))[[v]]$ is weaker than the (v) -adic one (for which the subset $k((u))$ is discrete). Thus, if a sequence (resp. a series) converges for the (v) -adic topology, it hence converges for the projective limit topology.

Proof of Lemma 3.5. *Step 1.* Recall that f is of the form $f = f_0(x) + f_1(x)v + \dots$ and such that f_0 has (x) -adic valuation 1. We will prove that the sequence $(f^n)_{n \in \mathbf{N}}$ converges to zero. Let i be a nonnegative integer; for n large enough, the coefficient of y^i in f^n is of the form $f_0^n P_i(f_0, \dots, f_i)$, where P_i is a polynomial which does not depend on n . Thus, for the (x) -adic topology, this coefficient tends to zero. Consequently, for all Laurent series $\phi(u) \in k((u))$, the series $\phi(f(x, y))$ converges in $k((x))[[y]]$.

Step 2. The series g has (y) -adic valuation 1; thus the sequence $(g^n)_{n \in \mathbf{N}}$ converges to zero for the (y) -adic topology and hence for the projective limit topology (see Remark A.1). Using step 1, we conclude that, for every series $\psi(u, v) \in k((u))[[v]]$, the series $\psi(f, g)$ converges in $k((x))[[y]]$. Moreover, its (y) -adic valuation equals the (v) -adic one of ψ .

Step 3. If ω is a formal form $\omega = h(u, v)du \wedge dv$ with (v) -adic valuation $n \in \mathbf{Z}$, then we have to prove that the (y) -adic valuation of $h(f, g)df \wedge dg$ is n too. If we prove that the (y) -adic valuation of $df \wedge dg$ is zero, then we can conclude using step 2. For that, consider the expression

$$df \wedge dg = \left(\underbrace{\frac{\partial f}{\partial x} \frac{\partial g}{\partial y}}_{\text{val}_{(y)}=0} - \underbrace{\frac{\partial f}{\partial y} \frac{\partial g}{\partial x}}_{\text{val}_{(y)} \geq 1} \right) dx \wedge dy.$$

This concludes the proof. \square

Appendix B. Proof of Lemma 3.11

If $\omega = dA \wedge dB$ for some series $A, B \in k((u))((v))$, after a change of coordinates (CV), $\omega = dF \wedge dG$ for some other series $F, G \in k((x))((y))$. Then, in order to prove the lemma we only have to prove that the (u, v) -2-residue of $\omega = dA \wedge dB$ is zero.

We first introduce some notations. Let ρ and Jac be the maps

$$\rho : \left\{ \begin{array}{l} k((x))((y)) \rightarrow k((x)) \\ \sum_{i \geq -n} h_j(u)v^j \mapsto h_{-1}(u) \end{array} \right., \quad \text{Jac} : \left\{ \begin{array}{l} k((x))((y))^2 \rightarrow k((x))((y)) \\ (A, B) \mapsto \frac{\partial A}{\partial u} \frac{\partial B}{\partial v} - \frac{\partial A}{\partial v} \frac{\partial B}{\partial u} \end{array} \right.$$

Thus, $\omega = dA \wedge dB = \text{Jac}(A, B)du \wedge dv$. We will prove the following lemma.

Lemma B.1. For all $A, B \in k((u))((v))$, we have $\rho(\text{Jac}(A, B)) = \phi'(u)$ for some $\phi \in k((u))$, where ϕ' denotes the formal derivative of ϕ .

Proof. Maps Jac and ρ are respectively k -bilinear antisymmetric and k -linear. Then, we can restrict the proof to the three following situations and extend it by linearity.

- (1) $A, B \in k((u))[[v]]$.
- (2) $A \in k((u))[[v]]$ and $B = \frac{b(u)}{v^n}$ with $n \in \mathbf{N}^*$ and $b \in k((u))$.
- (3) $A = \frac{a(u)}{v^m}$ and $B = \frac{b(u)}{v^n}$ with $m, n \in \mathbf{N}^*$ and $a, b \in k((u))$.

Let us consider these three situations.

- (1) The series A and B do not have terms with negative powers of v , thus neither do their partial derivatives. Therefore, $\rho \circ \text{Jac}(A, B) = 0$.
- (2) The series A is of the form $A = \sum_{j \geq 0} a_j(u)v^j$. Then,

$$\rho(\text{Jac}(A, B)) = -n(a'_n(u)b(u) + a_n(u)b'(u)) = (-na_n(u)b(u))'.$$

- (3) In this situation we have

$$\text{Jac}(A, B) = \left(-n \frac{a'(u)b(u)}{v^{m+n+1}} - (-m) \frac{a(u)b'(u)}{v^{m+n+1}} \right).$$

Integers m and n are positive. Therefore, there is no term in v^{-1} and thus $\rho(\text{Jac}(A, B)) = 0$. \square

Conclusion. Using Lemma B.1, we get $(u, v)\text{res}_{C,P}^1(\omega) = \phi'(\bar{u})d\bar{u}$ and the coefficient of u^{-1} in ϕ' is zero, because it is a derivative.

Appendix C. Proof of Theorem 3.6 when k has a positive characteristic

We only have to work on the points of the proof of Theorem 3.6 in which we used specific properties of characteristic zero. Thus, we will study the behavior under (CV2) of differentials of the form

$$\omega = \phi(u)du \wedge \frac{dy}{y^{n+1}}, \quad \text{where } \phi \in k((u)) \text{ and } n \geq 1.$$

Let N be a nonnegative integer. In what follows, we consider a change of variables of the form (CV2):

$$u = f(x, y), \quad \text{with } f = \sum_{j \geq 0} f_j(x)y^j \text{ and } f_0 \in xk[[x]] \setminus x^2k[[x]],$$

such that $\min_{k=1 \dots n} \{val_{(x)}(f_k)\} = -N$, where $val_{(x)}$ denotes the (x) -adic valuation of an element of $k((x))$.

Step 1. Assume that $\omega = u^m du \wedge \frac{dy}{y^{n+1}}$ with $m \in \mathbf{N}$. Then,

$$\omega = (f'_0(x) + f'_1(x)y + \dots)(f_0(x) + f_1(x)y + \dots)^m dx \wedge \frac{dy}{y^{n+1}}.$$

The (x, y) -1-residue of ω is the coefficient in y^n of the series $f^m \partial f / \partial x$. This residue is of the form

$$(x, y) \text{res}_{C,p}^1(\omega) = P_{m,n}(f_0, \dots, f_n, f'_0, \dots, f'_n) d\bar{x},$$

where $P_{m,n} \in \mathbf{Z}[X_0, \dots, X_n, Y_0, \dots, Y_n]$ depends neither on the field k nor on f . Actually, $P_{m,n}$ depends only on m and n . By the same way, its coefficient of x^{-1} is a polynomial expression Q in the $f_{i,j}$'s with $0 \leq j \leq n$ and $-N \leq i \leq N + 1$, such that Q has coefficients in \mathbf{Z} and depends neither on k nor on f . Furthermore, if k has characteristic zero, we know from Section 3 that Q vanishes on the set $\{f_{1,0} \neq 0\}$, hence is the zero polynomial.

Step 2. Assume that $\omega = \phi(u)du \wedge \frac{dy}{y^{n+1}}$, with $\phi = \sum_{m \geq 0} \phi_m u^m \in k[[u]]$. From step 1, we have

$$(x, y) \text{res}_{C,p}^1(\omega) = \sum_{m \geq 0} \phi_m P_{m,n}(f_0, \dots, f_n, f'_0, \dots, f'_n) d\bar{x}, \tag{5}$$

where the $P_{m,n}$'s denote the polynomials involved in Step 1. The (x, y) -1-residue of ω is well defined. Thus, the series in (5) converges in $k((x))$. Consequently, the (x) -adic valuation of its terms is positive for each m greater than or equal to some positive integer M and

$$(x, y) \text{res}_{C,p}^1(\omega) = \sum_{m=0}^M \phi_m P_{m,n} d\bar{x} + \sum_{m > M} \phi_m P_{m,n} d\bar{x}.$$

The right term has nonnegative (x) -adic valuation; thus its residue is zero. The left one has zero residue zero because of step 1 extended by linearity.

Step 3. Assume that $\omega = \frac{du}{u^m} \wedge \frac{dy}{y^{n+1}}$, with $m \in \mathbf{N}$. Then, $\omega = \frac{1}{f^m} \frac{\partial f}{\partial x} dx \wedge \frac{dy}{y^{n+1}}$. We have to study the fraction $\frac{1}{f^m} \frac{\partial f}{\partial x}$. First, compute its coefficient of y^n corresponding to the (x, y) -1-residue. We have

$$\frac{1}{f^m} = \frac{1}{f_0^m} \left(1 + \frac{R_{m,1}(f_0, f_1)}{f_0} y + \dots + \frac{R_{m,p}(f_0, \dots, f_p)}{f_0^p} + \dots \right), \tag{6}$$

for some homogeneous polynomials $R_{m,i} \in \mathbf{Z}[X_0, \dots, X_p]$ of degree p and depending only on m . Thus, the coefficient of y^n in $\frac{1}{f^m} \frac{\partial f}{\partial x}$ is

$$C(x) := \frac{1}{f_0^m} \left(f'_n + f'_{n-1} \frac{R_{m,1}(f_0, f_1)}{f_0} + \dots + f'_0 \frac{R_{m,n}(f_0, \dots, f_n)}{f_0^n} \right).$$

For all $k \in \{1, \dots, n\}$, set $S_{m,n,k}(f_0, \dots, f_k) := f_0^{n-k} R_{m,k}(f_0, \dots, f_k)$ and $S_{m,n,0}(f_0) := f_0^n$. The $S_{m,n,k}$'s are homogeneous of degree n and

$$C(x) := \underbrace{\frac{1}{f_0^{m+n}}}_{A(x)} \underbrace{\sum_{k=0}^n f'_{n-k} S_{m,n,k}(f_0, \dots, f_k)}_{B(x)}. \tag{7}$$

Recall that $f_0 \in xk[[x]]$, that is $f_0 := f_{1,0}x + f_{2,0}x^2 + \dots$; then

$$A(x) = \frac{1}{(f_{1,0}x)^{m+n}} \left(1 + \frac{R_{m,1}(f_{1,0}, f_{2,0})}{f_{1,0}} x + \dots + \frac{R_{m,p-1}(f_{1,0}, f_{2,0}, \dots, f_{p,0})}{f_{1,0}^{p-1}} x^{p-1} + \dots \right),$$

for polynomials $R_{m,k}$ as in (6). Finally, we want to express the coefficient C_{-1} of x^{-1} in $C(x)$. Recall that, for all p , the degree of $S_{m,n,p}$ is n . Therefore, there exists an integer M and a polynomial $V \in \mathbf{Z}[X_{i,j}]$ with $-N \leq i \leq \max(m+n, (n+1)N+1)$ and $0 \leq j \leq n$, depending only on m, n and N , and such that

$$C_{-1} = \frac{1}{f_{1,0}^M} V(f_{i,j}).$$

Over a field of characteristic zero, V vanishes on the set $\{f_{1,0} \neq 0\}$ and hence is the zero polynomial.

Remark C.1. Notice that, in the whole proof, we deal with the value N such that $-N$ is the minimal valuation of the f_i 's, for $0 \leq i \leq n$. Then, we have proved that the 2-residue is invariant under a change of variables $u = f(x, y)$ such that the f_i 's have valuation minored by $-N$. But we proved it for all N , which concludes the proof.

Appendix D. About tensor products

Statements in this appendix are quite elementary results of linear algebra. We prove them because of a lack of references.

Lemma D.1. *Let (E, \langle, \rangle_E) and (F, \langle, \rangle_F) be two finite-dimensional vector spaces over an arbitrary field k with respective non-degenerate bilinear forms \langle, \rangle_E and \langle, \rangle_F . Let A and B be subspaces respectively of E and F ; then for the bilinear form $\langle, \rangle_{E \otimes F} := \langle, \rangle_E \otimes \langle, \rangle_F$ on $E \otimes_k F$, we have*

$$(A \otimes_k B)^\perp = A^\perp \otimes_k F + E \otimes_k B^\perp.$$

Proof. Inclusion “ \supseteq ” is obvious. For the reverse one, we will prove that both spaces have the same dimension. First, we have to prove that

$$A^\perp \otimes_k F \cap E \otimes_k B^\perp = A^\perp \otimes B^\perp. \tag{8}$$

Here again, inclusion “ \supseteq ” is obvious. For the reverse one, consider bases $(e_i)_{i \in I_0}$ and $(f_j)_{j \in J_0}$ respectively of A^\perp and B^\perp and complete them as bases $(e_i)_{i \in I}$ and $(f_j)_{j \in J}$ of E and F . Then, for all $s = \sum_{i,j} s_{ij} e_i \otimes f_j \in E \otimes F$, we have

$$s \in A^\perp \otimes_k F \cap E \otimes_k B^\perp \implies (\forall (i, j) \in (I \setminus I_0) \times (J \setminus J_0), s_{ij} = 0).$$

Thus, (8) is proved and entails

$$\dim(A^\perp \otimes F + E \otimes B^\perp) = \dim(A^\perp \otimes F) + \dim(E \otimes B^\perp) - \dim(A^\perp \otimes B^\perp).$$

After an easy computation, we prove that spaces $(A \otimes B)^\perp$ and $(A^\perp \otimes F + E \otimes B^\perp)$ have the same dimension, which concludes the proof. \square

Lemma D.2. *Let E and F be two vector spaces over an arbitrary field k . Let A (resp. B) be a strict nonzero subspace of E (resp. F). Then, the subspace $A \otimes_k F + E \otimes_k B$ of $E \otimes_k F$ cannot be written as an elementary tensor product $U \otimes V$.*

Proof. Assume that $A \otimes F + E \otimes B = U \otimes V$ for some subspace U (resp. V) of E (resp. F). Let $(e_i)_{i \in I_0}$ (resp. $(f_j)_{j \in J_0}$) be a basis of A (resp. B) completed in a basis $(e_i)_{i \in I}$ of E (resp. $(f_j)_{j \in J}$ of F). Assume that $U \not\subseteq A$ and choose $u \in U$ such that $u \notin A$. Then, for all $v \in V$, the vector $u \otimes v$ is of the form

$$u \otimes v = \sum_{i,j} u_i v_j e_i \otimes f_j.$$

From the assumption $A \otimes F + E \otimes B = U \otimes V$, the product $u_i v_j$ is zero for all couples $(i, j) \in I \setminus I_0 \times J \setminus J_0$. Since $u \notin A$, there exists at least one index $i_1 \in I \setminus I_0$ such that $u_{i_1} \neq 0$. Thus, for all $j \in J \setminus J_0$, we have $u_{i_1} v_j = 0$ which entails that $v \in B$. This statement works for all $v \in V$; hence $U \otimes V \subseteq E \otimes B$. Now choose $f \in F$ such that $f \notin B$ and $a \in A \setminus \{0\}$. Then, $a \otimes f \notin E \otimes B$; thus $a \otimes f \notin U \otimes V$, which contradicts $A \otimes F + E \otimes B = U \otimes V$.

If $U \subseteq A$, use the same argument replacing U, A, E by V, B, F . \square

References

[1] P. Griffiths, J. Harris, Principles of Algebraic Geometry, in: Pure and Applied Mathematics, Wiley-Interscience [John Wiley & Sons], New York, 1978.
 [2] W.P. Barth, K. Hulek, C.A.M. Peters, A. Van de Ven, Compact complex surfaces, Second ed., in: Ergebnisse der Mathematik und ihrer Grenzgebiete, Springer-Verlag, Berlin, 2004.
 [3] R. Hartshorne, Residues and Duality, in: Lecture Notes in Mathematics, Springer-Verlag, Berlin, 1966.
 [4] J. Lipman, Dualizing sheaves, differentials and residues on algebraic varieties, Astérisque 117 (1984) ii+138.
 [5] V.D. Goppa, Codes on algebraic curves, Dokl. Akad. Nauk SSSR 259 (6) (1981) 1289–1290.
 [6] M.A. Tsfasman, S.G. Vlăduț, T. Zink, Modular curves, Shimura curves, and Goppa codes, better than Varshamov-Gilbert bound, Math. Nachr. 109 (1982) 21–28.
 [7] S.A. Stepanov, Codes on algebraic curves, Kluwer Academic/Plenum Publishers, New York, 1999.

- [8] H. Stichtenoth, Algebraic function fields and codes, in: Universitext, Springer-Verlag, Berlin, 1993.
- [9] M.A. Tsfasman, S.G. Vlăduț, Algebraic-geometric codes, in: Mathematics and its Applications (Soviet Series), Kluwer Academic Publishers Group, Dordrecht, 1991.
- [10] S.G. Vlăduț, Y.I. Manin, Linear codes and modular curves, in: Current Problems in Mathematics, in: Itogi Nauki i Tekhniki, vol. 25, Akad. Nauk SSSR Vsesoyuz. Inst. Nauchn. i Tekhn. Inform., Moscow, 1984, pp. 209–257.
- [11] Y. Aubry, Reed–Müller codes associated to projective algebraic varieties, in: Coding Theory and Algebraic Geometry (Luminy, 1991), in: Lecture Notes in Math., 1518, Springer, Berlin, 1992, pp. 4–17.
- [12] F.A.B. Edoukou, Codes defined by forms of degree 2 on quadric surfaces, IEEE Trans. Inform. Theory 54 (2) (2008) 860–864.
- [13] F.A.B. Edoukou, Codes defined by forms of degree 2 on quadrics in $\mathbb{P}^4(\mathbb{F}_q)$, in: Arithmetic, Geometry, Cryptography and Coding Theory (AGCT 2007), in: Contemporary Mathematics, vol. 487, American Mathematical Society, Providence, RI, 2009.
- [14] D.Y. Nogin, Codes associated to Grassmannians, in: Arithmetic, Geometry and Coding Theory (Luminy, 1993), de Gruyter, Berlin, 1996, pp. 145–154.
- [15] S.R. Ghorpade, G. Lachaud, Higher weights of Grassmann codes, in: Coding Theory, Cryptography and Related Areas (Guanajuato, 1998), Springer, Berlin, 2000, pp. 122–131.
- [16] I.M. Chakravarti, Geometric construction of some families of two-class and three-class association schemes and codes from nondegenerate and degenerate Hermitian varieties, Discrete Math. 111 (1–3) (1993) 95–103. Graph theory and combinatorics (Marseille-Luminy, 1990).
- [17] J.W.P. Hirschfeld, M. Tsfasman, S. Vlăduț, The weight hierarchy of higher dimensional hermitian codes, IEEE Trans. Inform. Theory 40 (1) (1994) 275–278.
- [18] A.B. Sørensen, Rational points on algebraic surfaces, Reed–Müller codes and algebraic–geometric codes, Ph.D. Thesis, Aarhus, Denmark, 1991.
- [19] F.A.B. Edoukou, Codes defined by forms of degree 2 on Hermitian surfaces and Sørensen’s conjecture, Finite Fields Appl. 13 (3) (2007) 616–627.
- [20] F. Rodier, Codes from flag varieties over a finite field, J. Pure Appl. Algebra 178 (2) (2003) 203–214.
- [21] M. Zarzar, Error-correcting codes on low rank surfaces, Finite Fields Appl. 13 (4) (2007) 727–737.
- [22] J.F. Voloch, M. Zarzar, Algebraic geometric codes on surfaces, in: Arithmetic, Geometry and Coding Theory (AGCT 2005), in: Séminaires et congrès, vol. 21, Société mathématique de France (in press). <http://www.ma.utexas.edu/users/voloch/Preprints/luminy.pdf>.
- [23] G. Lachaud, Number of points of plane sections and linear codes defined on algebraic varieties, in: Arithmetic, Geometry and Coding Theory (Luminy, 1993), de Gruyter, Berlin, 1996, pp. 77–104.
- [24] S.H. Hansen, Error-correcting codes from higher-dimensional varieties, Finite Fields Appl. 7 (4) (2001) 531–552.
- [25] J.B. Little, Algebraic geometry codes from higher dimensional varieties, (2008) Preprint [arXiv:math/0802.2349v1](https://arxiv.org/abs/math/0802.2349v1).
- [26] T. Høholdt, R. Pellikaan, On the decoding of algebraic–geometric codes, IEEE Trans. Inform. Theory 41 (6, part 1) (1995) 1589–1614.
- [27] I.R. Shafarevich, Basic Algebraic Geometry. 1, Second ed., Springer-Verlag, Berlin, 1994.
- [28] D. Eisenbud, Commutative algebra, in: Graduate Texts in Mathematics, volume 150, Springer-Verlag, New York, 1995.
- [29] I.S. Cohen, On the structure and ideal theory of complete local rings, Trans. Amer. Math. Soc. 59 (1946) 54–106.
- [30] D. Mumford, The Red Book of Varieties and Schemes, Second ed., in: Lecture Notes in Mathematics, volume 1358, Springer-Verlag, Berlin, 1999, Includes the Michigan lectures (1974) on curves and their Jacobians, With contributions by Enrico Arbarello.
- [31] N. Bourbaki, Algèbre, Hermann, Paris, 1959.
- [32] J.-P. Serre, Groupes algébriques et corps de classes, Publications de l’institut de mathématique de l’université de Nancago, VII. Hermann, Paris, 1959.
- [33] R. Hartshorne, Algebraic Geometry, in: Graduate Texts in Mathematics, volume 52, Springer-Verlag, New York, 1977.
- [34] A.N. Paršin, On the arithmetic of two-dimensional schemes. I. Distributions and residues, Izv. Akad. Nauk SSSR Ser. Mat. 40 (4) (1976) 736–773. 949.