Effective Utilization of a Microcontroller Port for Optimisation of Hardware

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Abstract

In embedded systems microcontrollers play a very important role because modern day’s microcontrollers have in-built program as well as data memory of enough length to implement any embedded application without need of any external memory. But it has limited number of IO port pins to interface IO peripherals and better utilization of these IO port pins becomes extremely challenging.

1. Introduction

Now a days Liquid Crystal Displays (LCDs) are becoming very popular output devices and are rapidly replacing seven segment displays. There are varieties of alphanumeric LCDs readily available in the market ranging from 16X1 up to 40X4. In fact, it is a basic output device used along with 4X4 matrix keyboard in many embedded applications.

If we interface these input and output peripherals on separate IO ports of a microcontroller, then very limited number of IO pins will remain available to interface other input and output devices like ADC, DAC, relays, I2C devices (DS1307/SHT71), etc. If we use LCD in 8-Bit mode then at least 13 IO pins will be required to interface it, but to minimize the IO pin count, generally, we use LCD in its 4-Bit mode operation. Thus at least 7 Pins will be required for the LCD. Apart from that, 4X4 matrix keyboard will require 8 more IO pins of a microcontroller. Thus both LCD and 4X4 matrix keyboard will consume 15 IO port pins of a microcontroller [1]. This is definitely poor utilization of microcontroller port pins to interface basic IO devices. To improve the utilization of port pins of a microcontroller we should interface
LCD and 4X4 matrix keyboard at the same port. This technique will work without fail if both devices have Tri-state IO buffers, which otherwise will fail due to bus contention.

Both the devices are using same port of a microcontroller in time division multiplexing mode. Here, one may raise a point that if a microcontroller is communicating with LCD and at the same time user has pressed a key, then it will not be read by a microcontroller and any vital data fed from user may be lost by a microcontroller. But there are two basic assumptions, first is that, this port is available almost all the time for matrix keyboard, as LCDs are operating at very high rate and will take very less time to communicate with a microcontroller and second is that, 4X4 matrix keyboard is operated by human beings who are very slow in operation. Between any two key strokes, generally, minimum time gap of 500ms is observed and this time gap is quite sufficient for LCD communication if at all it is to be taken place. So with this basic assumption, interfacing of LCD and 4X4 matrix keyboard to the same port of a microcontroller will work without fail.

2. Interfacing of LCD & Keyboard

In this section, interfacing of a LCD and 4X4 matrix keyboard to a common port of MCS-51 family microcontroller is explained. As a case study author has chosen 89C52 microcontroller along with MM74C922 a keyboard controller. As 4X4 matrix keyboard does not have capability of tri-stating its output line, so MM74C922 keyboard controller IC is used to fulfil this task. Another advantage of using keyboard controller is that, microcontroller is fully relieved from keyboard polling, as MM74C922 generates interrupt upon a key press and generates corresponding key code in its output buffer to be read by a microcontroller. Second advantage is that de-bouncing of a pressed key is done by the keyboard controller itself. Thus vital 20ms de-bouncing delay time of a microcontroller is saved. Using this controller, 4X4 matrix keyboard is interfaced with the microcontroller at the expense of 6 IO pins instead of 8 IO pins, out of which 4 IO pins are common data lines with the LCD. That means, exclusively 2 IO pins are required for 4X4 matrix keyboard and 3 IO pins are required exclusively to control the LCD. Thus total number of IO pin count to interface basic IO devices will be limited to 9 instead of 15, which is less by 6, if both the devices would have been interfaced separately to the microcontroller.

In this case study, 8-Bits of Port 0 are used to interface both LCD and 4X4 matrix keyboard. Here LCD is used in its 4-Bit mode operation, 4 data lines of the LCD D7 to D4 are connected to P0.7 to P0.4 pins respectively [2] and to the same data lines, keyboard data lines D to A are connected respectively. Control lines EN of the LCD and OE” (OE BAR) of MM74C922 are connected to P0.2 and P0.3 pins respectively. Data Available (DA) is an interrupt of keyboard controller and is connected to P3.2 pin which is alternatively used as INT0 [3]. The circuit diagram is shown in fig. 1. This figure is a Proteus VSM 7 simulation run output. Microcontroller asserts only that control line of the device with whom it wants to communicate. For example, if it is going to read the output buffer of keyboard controller then EN of the LCD is de-asserted and OE” of MM74C922 is asserted.

3. Software Design

To illustrate proper working of LCD and 4X4 matrix keyboard both connected to a common port, author has also interfaced Real Time Clock (DS1307) to the microcontroller [4]. To initialize DS1307 at the time of power-on, user is asked to give choice to continue with old time or change to new time. This message is displayed on LCD as shown in fig.1. During this communication with the LCD, output buffer of the keyboard controller is tri-stated by de-asserting OE”. Microcontroller communicates with the LCD via different subroutines like put_nibbles, put_string, lcd_ready, etc. During execution of any subroutine of the LCD, OE” signal of keyboard controller is de-asserted. The longest execution time is required for
put_string subroutine and its rough estimate is 630 μs, provided that crystal frequency is 12MHz. Some of the subroutines used to communicate with LCD and keyboard are shown in the table 1.

If user presses key ‘A’, then he/she will be asked to input all timing parameters starting from current seconds up to current year. As user presses any key to enter tens of seconds, microcontroller is interrupted by the keyboard controller. Then microcontroller executes Interrupt Service Routine to read output buffer of the keyboard controller and the pressed key is echoed back to the user as shown fig. 2. During execution of this ISR EN signal of LCD is de-asserted so as to tri-state IO buffer of the LCD. Execution time for this ISR is 10 μs fixed.

Table 1 Different subroutines used to communicate with LCD and keyboard

<table>
<thead>
<tr>
<th>Subroutine to transfer nibbles to LCD:</th>
<th>Subroutine to check LCD Ready:</th>
</tr>
</thead>
<tbody>
<tr>
<td>void put_nibbles(void)</td>
<td>void lcd_ready(void)</td>
</tr>
<tr>
<td>{</td>
<td>{</td>
</tr>
<tr>
<td>lcd_ready();</td>
<td>kbd_en=1; //tri-state output buffer of 74C922</td>
</tr>
<tr>
<td>kbd_en=1; //tri-state output buffer of 74C922</td>
<td>busy=1; //set MSB as input bit</td>
</tr>
<tr>
<td>lcd_buff1=lcd_buff;</td>
<td>rw=1;</td>
</tr>
<tr>
<td>rw=0;</td>
<td>rs=0;</td>
</tr>
<tr>
<td>rs=lcd_rs;</td>
<td>lcd_busy:</td>
</tr>
<tr>
<td>rd_buff1=lcdport;</td>
<td>lcd_en=1;</td>
</tr>
<tr>
<td>rd_buff1=rd_buff1&amp;0x0f;</td>
<td>rd_buff1=lcdport;</td>
</tr>
<tr>
<td>lcd_buff=lcd_buff</td>
<td>rd_buff1;</td>
</tr>
<tr>
<td>lcdport=lcdbuf;</td>
<td>rd_buff2=lcdport;</td>
</tr>
<tr>
<td>lcd_en=1; //Enable LCD to write HI-NIB. into</td>
<td>lcd_en=1;</td>
</tr>
<tr>
<td>it</td>
<td>if(rd_buff1==0x80)//if busy is still HI</td>
</tr>
<tr>
<td>lcd_en=0; //Disable it</td>
<td>goto lcd_busy; //then do not return</td>
</tr>
<tr>
<td>lcd_buff1=lcd_buff1&lt;&lt;4;</td>
<td>}</td>
</tr>
<tr>
<td>lcd_buff1=lcd_buff</td>
<td>rd_buff1;</td>
</tr>
<tr>
<td>lcdport=lcdbuf;</td>
<td>void put_string(unsigned char _string[16])</td>
</tr>
<tr>
<td>lcd_en=1; //Enable LCD to write HI-NIB. into</td>
<td>{</td>
</tr>
<tr>
<td>it</td>
<td>lcd_rs=1;</td>
</tr>
<tr>
<td>lcd_en=0; //Disable it</td>
<td>for(i=0;i&lt;16;i++)</td>
</tr>
<tr>
<td></td>
<td>{</td>
</tr>
<tr>
<td></td>
<td>if(_string[i]==0x24) goto exit;</td>
</tr>
<tr>
<td></td>
<td>lcd_buf</td>
</tr>
<tr>
<td></td>
<td>put_nibbles();</td>
</tr>
<tr>
<td></td>
<td>exit;;</td>
</tr>
<tr>
<td>}</td>
<td>}</td>
</tr>
</tbody>
</table>
Fig. 1 Interfacing of LCD and keyboard to PORT0 of 89C52 microcontroller

Fig. 2 Status of display when user presses key 5 to enter tens of second
As soon as initialization process of RTC DS1307 is finished, it generates square wave of 1Hz continuously on its SOUT pin. This signal is connected to P3.3 pin of the microcontroller which has alternate function of INT1. During execution of ISR for Interrupt-1 every after 1 second, microcontroller reads current time, day and date from DS1307 and displays it on the LCD, as shown in fig. 3.

4. Conclusion

In this work, it is observed that a systematic design approach for interfacing LCD and 4X4 matrix keyboard to a single PORT of a micro-controller is quite possible so as to improve the hardware utilization factor of the system. 4-Bit interface mode of LCD is used to reduce number of IO pins required to interface it with a micro-controller. Tri-stating of 4X4 matrix keyboard is achieved by using MM74C922 keyboard controller. For complex embedded system applications where number of IO peripherals in the system is more, generally Hi-end microcontrollers like ARM7 are chosen where number IO port pins are in abundant, but it results in increased complexity, size and cost of the circuit. But by using the effective interfacing technique for basic IO devices like LCD and matrix keyboard, as illustrated above, one can still build complex embedded system using Low-end microcontrollers like 8051/PIC16FXXX. Applications of this technique are many, like public telephone booth, fuel (petrol/diesel) filling machine, automation of green-house, AC & DC drives, etc. Any embedded system which consists of 4X4 matrix keyboard and LCD can be built using this novel technique. The same technique can be used for those devices which have internal buffers that can be Tri-stated by enable control signal.

References

4. www.8051projects.net/