# Monomlal Patterns in the Sequence $\boldsymbol{A}^{\boldsymbol{k}} \boldsymbol{b}$ 

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#### Abstract

We consider the pattern of zero and nonzero elements in the sequence $A^{k} b$, where $A$ is an $n \times n$ nonnegative matrix and $b$ is an $n \times 1$ nonnegative column vector. We establish a tight bound of $k<n$ for the first occurrence of a given monomial pattern, and we give a graph theoretic characterization of triples ( $A, b, i$ ) such that there exists a $k, k \geqslant n$, for which $A^{k} b$ is an $i$-monomial. The appearance of monomial patterns with a single nonzero entry is linked to controllability of discrete $n$-dimensional linear dynamic systems with positivity constraints on the state and control.


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## 1. INTRODUCTION

In the course of investigating a control theoretic question, Coxson and Shapiro [1] showed that, for a nonnegative matrix $A$ with a positive diagonal and for a nonnegative vector $b$, an $i$-monomial pattern consisting of a single nonzero entry in the $i$ th position will appear in $A^{k} b$ for some $k<n$, or it will not appear at all. They conjectured that the result holds even without restriction on the diagonals of $A$.

It is the main purpose of this paper to prove the conjecture of Coxson and Shapiro: see Theorem 1 in Section 2. We call a triple ( $A, b, i$ ) for which there exists a $k, k \geqslant n$, such that $A^{k} b$ is $i$-monomial a monophil triple. In Section 3 we describe some graph theoretic properties of monophil triples, and we determine, in Lemma 5 , the set of $k$ such that $A^{k} b$ is $i$-monomial. From these properties, we derive a graph theoretic characterization of monophil triples in Theorem 2, Section 4, and we pursue some of its consequences. In Section 5 we show that for monophil triples the bound $k<n$ for the least $k$ such that $A^{k} b$ is $i$-monomial is tight, and we display matrices and vectors for which the first $i$-monomial power is $n-1$. A final Section 6 explains the control theoretic background.

Our proofs proceed by means of a translation of combinatorial matrix properties into graph theoretic terms. We have structured our paper so as to derive Theorem 1 as early as possible. An alternative approach would be first to prove the characterization of monophil triples contained in Theorem 2 and then to derive Theorem 1.

The investigation of the combinatorial properties of the powers of a nonnegative matrix $A$ is classical and of importance in applications to areas such as the theory of Markov chains. It is known that there exist a positive $c$ and a nonnegative $K_{0}$ such that $A^{k+c}$ has the same pattern as $A^{k}$ for all $k \geqslant K_{0}$. Many papers derive bounds for the least such $c$ and the corresponding least $K_{0}$; see, for example, [2]-[10]. We do not use these results directly, though our paper is in the same spirit and contains theorems of a similar type.

## 2. THE MAIN RESULT

A matrix or vector $M$ is nonnegative, denoted $M \geqslant 0$, if all of its entries are nonnegative real numbers. A nonnegative vector $x$ will be called a monomial column if it has precisely one nonzero entry. If the nonzero entry of a monomial column is in the $i$ th position, we will refer to it as an i-monomial. The following theorem is the focus of this paper.

Theorem 1. Let $A$ be an $n \times n$ nonnegative matrix and $b$ be an $n \times 1$ nonnegative column vector. If there is an i-monomial in the sequence $\left\{A^{k} b: k=n, n+1, n+2, \ldots\right\}$, then there is an i-monomial in the sequence $\left\{A^{k} b: k=0,1,2, \ldots, n-1\right\}$.

Of course, Theorem 1 implies the conjecture of Coxson and Shapiro [1] which is stated in the first paragraph of the introduction.

Our proof of this result is based on graph theoretic considerations. The (directed) graph of an $n \times n$ nonnegative matrix $A$, denoted $G(A)$, is the graph with $n$ nodes having a directed arc from node $i$ to node $j$ if and only if the ( $i, j$ ) entry of $A$ is positive. For our purpose, it will be much more convenient to think in terms of the graph $G^{-}(A):=G\left(A^{T}\right)$, in which the direction of each are is reversed.

A (directed) path of $G^{-}(A)$ is simple if it has no repeated nodes. Let $S$ be a subset of $\{1, \ldots, n\}$. A path of $G^{-}(A)$ that starts at a node of $S$ is called an S-path. If $i$ is a node of $G^{-}(A)$, then an $\{i\}$-path is called an $i$-path. An $S$-path that ends at a node $i$ is called an ( $\mathrm{S}, i$ )-path. By cycle we shall always mean a cycle without repeated nodes, except for the first and last. Two cycles with the same arc set are identified. An $i$-path that is a cycle is called an $i$-cycle. By the previous remark, an $i$-cycle is also a $j$-cycle for every node $j$ on the cycle.

For an $n \times n$ nonnegative matrix $A$ and an $n \times 1$ nonnegative column vector $b$, the product $A^{k} b$ has the following interpretation in terms of $G^{-}(A)$. Let $S=\left\{s_{1}, s_{2}, \ldots, s_{V}\right\}$ denote the positions of all the nonzero entries of $b$. We call $S$ the support of $b$, and we write $S=\operatorname{supp}(b)$. We identify the set $S$ with the corresponding subset of the nodes of $G^{-}(A)$. Then the $j$ th entry of $A^{k} b$ is nonzero if and only if there is an ( $S, j$ )-path of length $k$ in $G^{-}(A)$. Thus we obtain the following key proposition which allows us to restate Theorem 1 in graph theoretic terms. It will be used many times in our proofs, often without further reference.

Proposition 1. Let A be a nonnegative matrix, $b$ a nonnegative vector, and $i$ a node of $G^{-}(A)$. Let $S=\operatorname{supp}(b)$. Then $A^{k} b$ is $i$-monomial if and only if there is at least one ( $\mathrm{S}, \mathrm{i}$ )-path of length $k$ in $G^{-}(\mathrm{A})$ and every S -path of length $k$ ends at $i$.

We can now state Theorem 1 in the following equivalent form.

Theorem 1G. Let A be an $n \times n$ nonnegative matrix, and $S$ a subset of nodes of $G^{-}(A)$. For some $k, k \geqslant n$, suppose there is an S-path of length $k$, and suppose that every S-path of length $k$ terminates at the $i$ th node of
$G^{-}(A)$. Then there is $a j<n$ such that all S-paths of length $j$ also terminate at node $i$.

Let $A$ be an $n \times n$ nonnegative matrix, $b$ a nonnegative vector, and $i$ a positive integer, $l \leqslant i \leqslant n$. We call the triple $(A, b, i)$ monophil if there exists an integer $k, k \geqslant n$, such that $A^{k} b$ is $i$-monomial.

Lemma 1. Let the triple $(A, b, i)$ be monophil, and let $S=\operatorname{supp}(b)$. Then no S-path can meet a cycle which is not an i-cycle.

Proof. Suppose $A^{k} b$ is $i$-monomial, $k \geqslant n$, If the $S$-path $P$ meets a cycle which is not an $i$-cycle, then there is a path of length $k$ which ends on that cycle, contrary to Proposition 1.

A path augmented (reduced) by a cycle is a path with the same beginning and end but covering one more (less) cycle than the original path. A path of length 0 is identified with a node.

Proof of Theorem 1G. By assumption there is a $k, k \geqslant n$, such that all S-paths of length $k$ end at node $i$, and such that there is at least one S-path $P$ of length $k$ which ends at $i$. Then, by Lemma 1 , all cycles that can be reached from $S$ must be $i$-cycles. Since the length of $P$ is greater than $n-1$, the path $P$ includes a cycle $C$. Let $c$ denote the length of $C$. Then $c \leqslant n \leqslant k$. We claim that every $S$-path of length $k-c$ either ends at node $i$ or is disjoint from $C$, for if it contains a node of $C$ it can be augmented to a path of length $k$.

Now suppose that $k, k \geqslant n$, is the minimal integer such that all $S$-paths of that length end at $i$. Then there is an S-path $R$ of length $k-c$ with endpoint other than $i$. By the above argument, the nodes of $C$ and $R$ are disjoint. In particular, $i$ is not a node of $R$. Hence, by Lemma $1, R$ contains no cycle and therefore has $k-c+1$ nodes. Since $C$ has $c$ nodes, it follows that $k+\mathrm{l}=(k-c+1)+c \leqslant n$, a contradiction.

The proof of Theorem 1G above does not explicitly contain the insights into the structure of $S$-paths in $G^{-}(A)$ which originally led us to a proof. Those insights are detailed next in our discussion of the graph theoretic properties of monophil triples. We found Lemma 3 and Figure 1 to be especially helpful in understanding the result.

## 3. PROPERTIES OF MONOPHIL TRIPLES $(A, b, i)$

Lemma 2 follows immediately from Proposition 1 and the definition of a monophil triple.

Lemma 2. Let the triple $(A, b, i)$ be monophil, and let $S=\operatorname{supp}(b)$. Then there is an S-path which contains a cycle.

Let the triple ( $A, b, i$ ) be monophil. By $k_{0}=k_{0}(A, b, i)$ we shall always denote the least integer $k$ for which $A^{k} b$ is $i$-monomial. If $S=\operatorname{supp}(b)$, then $p_{\text {max }}$ will denote the length of the longest $S$-path which does not meet a cycle. If there is no such path, we put $p_{\max }=-1$. The result of Theorem 1 may now be stated as $k_{0} \leqslant n-1$. In fact, we have proved more, namely, $k_{0} \leqslant p_{\text {max }}+c$, where $c$ is the length of a cycle contained in some $S$-path. In view of the next lemma, this result is of some interest.

Lemma 3. If $(A, b, i)$ is monophil, then every simple cycle through the node $i$ must have the same length $c$.

Proof. Let $A^{k} b$ be $i$-monomial, $k \geqslant n$. Suppose there are two cycles containing node $i$ of lengths $c_{1}$ and $c_{2}$, with $c_{1}<c_{2}$. By Lemma 1 , both cycles are $i$-cycles. All S-paths of length $k$ terminate at node $i$. Select $s$ in $S$ such that there exists a path of length $k$ originating at node $s$ of $G^{-}(A)$. Consider the following two paths:

Path 1: Begin at node $s$ in $S$. At the first occurrence of node $i$ (say after $p$ steps), follow the cycle of length $c_{1}$ until the first return to node $i$. Then follow along the longer cycle until a path of length $k$ has been determined.

Path 2: Begin at node $s$, and take the same route as path 1 to reach node $i$ for the first time. Now follow the cycle of length $c_{2}$ and continue to cycle until the path has length $k$.
At the $\left(p+c_{1}\right)$ th step, path 1 reaches node $i$ and path 2 arrives at a node which is a distance $c_{1}$ beyond node $i$ on the cycle of length $c_{2}$. From this point on, paths 1 and 2 are always a distance $c_{1}$ apart on the cycle of length $c_{2}$. In particular, they cannot both terminate at node $i$ as required. Thus, all cycles must have the same length, as claimed.

By $c$ we shall denote the common length of all $i$-cycles if $(A, b, i)$ is monophil. We now immediately have the following corollary to Theorem IG.

Corollary 1. Let $(A, b, i)$ be monophil. Then

$$
\begin{equation*}
k_{0} \leqslant p_{\max }+c \leqslant n-1 . \tag{3.1}
\end{equation*}
$$

We shall investigate the cases of equality in (3.1) in Section 5.

Lemma 4. Let $(A, b, i)$ be monophil, and let $P$ be a simple $(i, j)$-path of length $d$. Then $d<c$.

Proof. If $j$ lies on an $i$-cycle, then $d<c$, since the path is simple. Suppose $j$ does not lie on an $i$-cycle, and suppose that $d \geqslant c$. Since the path is simple, the subpath $P^{\prime}$ of $P$ of length $c$ which also starts at $i$ ends at a node $j^{\prime}$ with $j^{\prime} \neq i$. Let $Q$ be an $(S, i)$-path of length $k, k \geqslant n$. Reduce $Q$ by an $i$-cycle, and then continue the reduced path by adjoining $P^{\prime}$. We obtain an $S$-path of length $k$ which does not end at $i$, contrary to assumption.

Lemma 5. Let the triple $(A, b, i)$ be monophil. Then the vector $A^{k} b$ is i-monomial if and only if $k=k_{0}+m c$, where $m$ is a nonnegative integer.

Proof. Suppose $A^{k} b$ is $i$-monomial. Since by Lemmas 2 and 3 there exists an $i$-cycle of length $c$, and by Lemma 4 the only $i$-paths of length $c$ are $i$-cycles, it follows immediately that $A^{k+c} b$ is $i$-monomial. Hence, by induction, $A^{k} b$ is $i$-monomial if $k=k_{0}+m c$, where $m$ is a nonnegative integer.

Conversely, suppose that $A^{k} b$ is $i$-monomial and that $0<d<c$. By Lemmas 1 and 3 there exists an $i$-path of length $d$ along an $i$-cycle which does not end at $i$. It follows that $A^{k+d} b$ is not $i$-monomial. The result follows.

Corollary 2. Let $A$ be an $n \times n$ nonnegative matrix, $b$ an $n \times 1$ nonnegative column vector, and $i$ a node of $G^{-}(A)$. Then either all integers $k$ such that $A^{k} b$ is i-monomial satisfy $k<n$, or else there are an infinity of integers $k$ such that $A^{k} b$ is i-monomial.

Proof. If there exists a $k \geqslant n$ such that $A^{k} b$ is $i$-monomial, then $(A, b, i)$ is monophil, and the corollary follows from Lemma 5.

In the next section, we use these results to specify necessary and sufficient conditions for a triple to be monophil.

## 4. GRAPH THEORETIC CHARACTERIZATION OF MONOPHIL TRIPLES

Theorem 2. Let A be an $n \times n$ nonnegative matrix, let be a nonnegative vector, and let $i$ be a node of $G^{-}(A)$. Then ( $\left.A, b, i\right)$ is monophil if and only if the following conditions hold for $G^{-}(A)$ :
(a) There exists a cycle which lies on an S-path, where $S=\operatorname{supp}(b)$.
(b) Every cycle that can be reached from $S$ is an i-cycle.
(c) Every i-cycle has the same length $c$.
(d) Every simple i-path has length less than $c$.
(e) If $P$ and $Q$ are two simple ( $S, i$ )-paths of lengths $p$ and $q$ respectively, then $p \equiv q(\bmod c)$.

Proof. Suppose $A^{k} b$ is $i$-monomial, where $k \geqslant n$. Conditions (a), (b), (c) and (d) are Lemmas 2, 1, 3, and 4, respectively. For (e), note that by (c) and Lemma 5 there must exist $m$ and $m^{\prime}$ such that $p+m c=q+m^{\prime} c=k$.

Conversely, suppose that (a)-(e) are satisfied. By (a) and (b) there exists a simple ( $S, i$ )-path $P$. Let $p$ be its length, and let $m$ be an integer such that $k=p+m c \geqslant n$. By (c), we can augment $P$ by adjoining $m i$-cycles to obtain a path of length $p+m c=k$. Thus conditions (a), (b) and (c) imply that there is an ( $S, i$ ) path of length $k$. Now suppose that $R$ is an $S$-path of length $k$ which is not an ( $S, i$ )-path. Since $R$ contains a cycle, by (b) it contains an $i$-cycle and all of its cycles are $i$-cycles. Thus $R$ is obtained from a simple ( $S, i$ )-path $Q$, repeatedly augmenting $Q$ by an $i$-cycle, and then adjoining a simple $i$-path $D$ not ending at $i$. Denote the lengths of $Q$ and $D$ by $q$ and $d$, respectively. By (c) we have $p+m c=k=q+m^{\prime} c+d$, for some positive integer $m^{\prime}$, so that $p \equiv q+d(\bmod c)$. Using the congruence in (e), we conclude $0 \equiv d(\bmod c)$. But, since $D$ is nonempty, we have $d>0$, and from (d) we know $d<c$, a contradiction. Hence the path $R$ is an ( $S, i$ )-path, and, in view of Proposition 1, the theorem is proved.

From Theorem 2, we see that an S-path $Q$ for monophil ( $A, b, i$ ) has very simple structure, as illustrated in Figure 1. It first traces a route of length $p$, which does not meet any cycle. (For consistency, we define $p$ to be -1 if the initial node of $Q$ is on a cycle.) Then it moves around the various cycles through $i$, all of length $c$. After the last occurrence of node $i$, it follows an $i$-path $D$ of length $d<c$.

Corollary 3. If $(A, b, i)$ is monophil, then ( $A, e_{i}, i$ ) is monophil, where $e_{i}$ is the $i$ th canonical unit vector.


$$
\text { cycle length }=\mathrm{c}
$$

Fig. 1.

Proof. If ( $A, b, i$ ) is monophil, then conditions (a)-(e) of Theorem 2 hold. Note that (c) and (d) are independent of the vector $b$. Conditions (a) and (b) for ( $A, e_{i}, i$ ) follow from (a) and (b) for ( $A, b, i$ ). Condition (e) also holds for $S=\{i\}$, since the only simple $i$-path which ends at $i$ is empty and has length 0 . Hence the result follows from the converse direction of Theorem 2.

In view of an application in Section 6, it is of interest to determine whether all $i$-monomials appear among the columns $\left\{A^{k} b_{j}: j=1, \ldots, m\right.$; $k=0,1, \ldots\}$. By Theorem 1 , it is sufficient to consider $k \leqslant n-1$. If an $i$-monomial appears in $\left\{A^{k} b: k=0, \ldots, n-1\right\}$ we shall say that the triple ( $A, b, i$ ) is submonophil. Every monophil triple is submonophil (Theorem 1), but the converse is false. Theorem 3 characterizes the graphs $G^{-}(A)$ and corresponding vectors $b$ such that ( $A, b, i$ ) is submonophil for all nodes $i$ (here $m=1$ ).

Theorem 3. Let $A$ be an $n \times n$ nonnegative matrix, and let $b$ be $a$ nonnegative vector. Then the following are equivalent:
(a) $(A, b, i)$ is submonophil for each $i, i=1, \ldots, n$.
(b) After a permutation of $(1, \ldots, n), \operatorname{supp}(b)=\{1\}$ and the set of arcs of $G^{-}(A)$ is the union of $\{(1,2),(2,3), \ldots,(n-1, n)\}$ and an arbitrary subset of $\{(n, n),(n, n-1), \ldots,(n, 1)\}$ (Figure 2).


Fig. 2.

Proof. Suppose $b$ and $G^{-}(A)$ satisfy condition (b). Then $A^{i-1} b$ is $i$-monomial, $i=1, \ldots, n$, so that condition (a) holds.

Conversely, suppose that $A$ and $b$ satisfy condition (a). Since $k_{0}(A, b, i)$ $<n$ for each $i$, it follows that (after permutation of indices) $A^{i-1} b$ is $i$-monomial, $i=1, \ldots, n$. In particular, $\operatorname{supp}(b)=\{1\}$. Since $A b$ is 2 -monomial, we see that $(1,2)$ is the only arc beginning at node 1 . The result follows by a repetition of this argument.

Corollary 4. Let A be an $n \times n$ nonnegative matrix. Then the following conditions are equivalent:
(a) For every node $i$ of $G^{-}(A)$ there is a nonnegative vector $b_{i}$ such that ( $A, b_{i}, i$ ) is monophil.
(b) $G^{-}(A)$ consists of a union of disjoint cycles which cover all nodes, and $b_{i}$ is a monomial vector whose support is a node on the cycle containing node $i$.

Proof. Suppose condition (b) holds. Let $d_{i}$ denote the distance from $\operatorname{supp}\left(b_{i}\right)$ to node $i$, and let $c_{i}$ denote the length of the cycle containing node $i$. Then $A^{k} b_{i}$ is $i$-monomial for all $k \equiv d_{i} \bmod c_{i}$ and thus $\left(A, b_{i}, i\right)$ is monophil.

For the converse, assume condition (a). From Theorem 2(a) and 2(b), it follows that every node of $G^{-}(A)$ is on a cycle. Suppose nodes $i$ and $j$ are on the same cycle. Then any $i$-cycle can be reached from any $j$-cycle, so Theorem 2(b) implies that the cycle through $i$ (and $j$ ) is unique and the only simple ( $i, j$ )-path is the path along this cycle. Now suppose nodes $i^{\prime}$ and $j^{\prime}$ lie on different cycles. An are ( $i^{\prime}, j^{\prime}$ ) would join the $i^{\prime}$-cycle to the $j^{\prime}$-cycle, violating Theorem 2(b) for ( $A, b_{i^{\prime}}, i^{\prime}$ ). The result follows.

Evidently, if $G^{-}(A)$ is the union of $m$ disjoint cycles, the minimum number of distinct $b_{i}$ such that ( $A, b_{i}, i$ ) is monophil for every node $i$ of $G^{-}(A)$ is $m$. In particular, we have the following corollary.

Corollary 5. Let A be a nonnegative matrix. Then there is a nonnegative vector $b$ such that $(A, b, i)$ is monophil for each if and only if $G^{-}(A)$ consists of a single full cycle.

## 5. THE BOUND IS SHARP

The bound $k_{0} \leqslant p_{\text {max }}+c \leqslant n-1$ is best possible, as illustrated in Figure 3 , where $k_{0}=3=n-1$.
$A=\left(\begin{array}{llll}0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1\end{array}\right) \quad b=\left(\begin{array}{l}1 \\ 0 \\ 1 \\ 0\end{array}\right)$


$$
\left\{A^{k} b\right\}_{k=0}^{3}=\left\{\left(\begin{array}{l}
1 \\
0 \\
1 \\
0
\end{array}\right),\left(\begin{array}{l}
0 \\
1 \\
0 \\
1
\end{array}\right),\left(\begin{array}{l}
0 \\
0 \\
1 \\
1
\end{array}\right),\left(\begin{array}{l}
0 \\
0 \\
0 \\
1
\end{array}\right)\right\}
$$

Fig. 3.

The general structure of a monophil ( $A, b, i$ ), $i=n$, having $k_{0}=n-1$ is illustrated in Figure 4 for the case $n=10, p_{\max }=6, c=3$. The graph $G^{-}(A)$ has precisely one cycle of length $c$ and precisely one cycle free S-path of length $p_{\text {max }}$ which does not meet the cycle. The nodes are numbered consecutively, beginning with the initial node 1 of the cycle free path and ending with $i=n$ on the cycle. In the matrices $A$ and $h, 1$ 's denote positions which must have nonzero character. The X character denotes positions which may be chosen to be zero or nonzero. The \# character denotes positions which may be nonzero, but may be forced to be zero if certain X's


Fig. 4.


Fig. 5.
are nonzero. For example, if $a_{87} \neq 0$, then all positions marked \# are zero. Note that the X's of $A$ all lie on subdiagonals separated by the distance $c$. If all of the X's in the last three rows of A are zero-indicating that the cycle and the cycle free path are disjoint-then the single entry marked * in $b$ must be nonzero.

We note that it is easy to construct an example for which the first monomial column (of any kind) in the sequence $\left\{A^{k} b: k=0,1,2, \ldots\right\}$ occurs when $k=n-1$. For example, let $G^{-}(A)$ be given in Figure 5, and let $\operatorname{supp}(b)=\{1,2\}$.

## 6. MONOMIAL PATTERNS AND POSITIVE REACHABILITY OF LINEAR SYSTEMS

A discrete single input linear dynamic system is given by

$$
\begin{gather*}
x(k+1)=A x(k)+B u(k), \quad x(0)=x_{0}  \tag{6.1}\\
x(k) \text { in } \mathbf{R}^{n} \quad \text { and } \quad u(k) \text { in } \mathbf{R}^{m}
\end{gather*}
$$

where $A$ is an $n \times n$ real matrix and $B$ is an $n \times m$ real matrix. $x(k)$ is a real $n \times 1$ column vector, called the state vector, for each $k=0,1,2, \ldots$, and $u(k)$ is a real $m$-dimensional input to the system. For a given initial state $x(0)=x_{0}$, the solution of (6.1) is given by

$$
x(k)=A^{k} x_{0}+\sum_{j=0}^{k-1} A^{j} B u(k-1-j)
$$

We will be interested in the states $x$ in $\mathbf{R}^{n}$ which can be reached from $x_{0}=0$. This set of reachable states is clearly the subspace of $\mathbf{R}^{n}$ spanned by the column vectors of $\left\{A^{j} B\right\}$. For each $j \geqslant n$, the Cayley-Hamilton theorem provides that $A^{j} B$ can be expressed as a linear combination of $\left\{A^{i} B: i=\right.$ $0,1, \ldots, n-1\}$. Thus, any state which can be reached in a finite number of
steps can also be reached within $n$ steps with an appropriate choice of inputs $u(i)$. The reachable set is all of $\mathbf{R}^{\boldsymbol{n}}$ if and only if $\mathbf{R}^{n}$ is spanned by $\left\{A^{j} B: j=0,1, \ldots, n-1\right\}$.

Next consider a positive discrete linear system,

$$
\begin{gathered}
x(k+1)=A x(k)+B u(k), \quad x(0)=x_{0} \\
x(k) \text { in } \mathbf{R}_{+}^{n} \quad \text { and } \quad u(k) \text { in } \mathbf{R}_{+}^{m}
\end{gathered}
$$

with $A, B, x_{0}$, and $u(j)$ constrained to be nonnegative. Under these conditions, $x(k)$ will be nonnegative for all $k \geqslant 0$. Such nonnegativity constraints are an essential feature of a wide range of applications, including chemical reaction systems, where the underlying states are masses of chemicals which can never be negative.

Due to the nonnegativity of $\left\{A^{k} B\right\}$ and the input $u(k)$, the reachable set of the positive system is contained in the nonnegative orthant $\mathbf{R}_{+}^{n}$. This set is denoted by $\mathbf{R}_{\infty}$. The subset $\mathbf{R}_{k}$ of states which can be reached within $k$ steps is the polyhedral cone generated by the nonnegative columns of $\left\{A^{j} B\right.$ : $j=0, \ldots, k-1\}$. The Cayley-Hamilton theorem again guarantees that $A^{k} B$ can be expressed as a linear combination of $\left\{A^{j} B: j=0,1, \ldots, n-1\right\}$. But the coefficients are not necessarily nonnegative, so we cannot conclude, as in the unconstrained case, that $\mathbf{R}_{\infty}=\mathbf{R}_{n}$.
$\mathbf{R}_{k}=\mathbf{R}_{+}^{n}$ if and only if each of the $n$ independent $i$-monomials of $\mathbf{R}_{+}^{n}$ is an element of $\mathbf{R}_{k}$. We let $e_{i}$ denote the $i$-monomial with a 1 in the $i$ th position. Since $e_{i}$ is extremal in $\mathbf{R}_{+}^{n}$, it is possible to obtain

$$
e_{i}=\sum_{j=0}^{k-1} A^{j} B u(k-1-j)
$$

with $u(j) \geqslant 0, j=0, \ldots, k-1$, if and only if $A^{j} B$ has an $i$-monomial column for some nonnegative integer $j$. If $A^{j} B$ has an $i$-monomial column, then $e_{i}$ can be reached in $j+1$ steps.

Thus Theorem 1 applied to each column $b$ of $B$ implies that $\mathbf{R}_{\infty}=\mathbf{R}_{+}^{n}$ if and only if $\mathbf{R}_{n}=\mathbf{R}_{+}^{n}$; that is, if all nonnegative states are reachable, then they are reachable within $n$ steps $\left(\mathbf{R}_{\infty}=\mathbf{R}_{n}\right)$. Note, however, that if $\mathbf{R}_{\infty} \neq \mathbf{R}_{+}^{n}$, then it is possible that $\mathbf{R}_{\infty} \neq \mathbf{R}_{n}$. For example,

$$
\text { if } A=\left(\begin{array}{ll}
1 & 1 \\
0 & 1
\end{array}\right) \text { and } b=\binom{0}{1}, \quad \text { then } \quad A^{k} b=\binom{k}{1}
$$

and $\mathbf{R}_{k}$ is strictly contained in $\mathbf{R}_{k+1}$ for each $k$.

If $\mathbf{R}_{\infty}=\mathbf{R}_{+}^{n}$, then for each node $i$ of $G^{-}(A)$ there is a column $b$ of $B$ such that ( $A, b, i$ ) is submonophil. For the single input system ( $B=b$, a column vector), a characterization of $A$ and $b$ such that $\mathbf{R}_{\infty}=\mathbf{R}_{+}^{n}$ is given in Theorem 3. If ( $A, b, i$ ) is monophil, then $i$-monomials can be reached repeatedly over time. If ( $A, b, i$ ) is submonophil but not monophil, then $i$-monomials can be reached only in the initial $n$ steps following an input (see Corollary 2). A detailed discussion of the reachability problem and related control issues for positive systems can be found in Coxson and Shapiro [1].

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