

STABLY TAME AUTOMORPHISMS*

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Certain automorphisms of polynomial rings are shown to be stably tame.

In [1], Bass raised the question of whether a certain automorphism of a polynomial ring in three variables is stably tame — i.e., can be expressed as a product of automorphisms of certain special types if one adjoins an additional variable. In this note we show that this is indeed the case.

Let $k[x_1, \dots, x_n]$ denote the polynomial ring over the field k in commuting indeterminates x_1, \dots, x_n . An automorphism σ of $k[x_1, \dots, x_n]$ such that for each i , $\sigma(x_i) - x_i \in k[x_{i+1}, \dots, x_n]$ is called *triangular* (with respect to the given ordered set of indeterminates). An automorphism σ such that each σx_i is a linear combination of x_1, \dots, x_n is called *linear*. An automorphism σ is *tame* if it is in the subgroup generated by the triangular and linear automorphisms. It is *stably tame* if for some choice of additional indeterminates x_{n+1}, \dots, x_m , the extension of σ to $k[x_1, \dots, x_m]$ which fixes x_{n+1}, \dots, x_m is tame. The concepts of triangular, linear, tame, and stably tame are defined analogously for automorphisms of free algebras (see [3]) or rings of generic matrices (see [2]).

For $n = 2$, all automorphisms are tame (see, e.g. [4] or [5]). For $n \geq 3$, it seems likely that nontame automorphisms exist. Thus the question of stable tameness becomes of interest. The first example known to the author of a stably tame automorphism which is not known to be tame is the following unpublished example of David Anick's for a free algebra.

Let $R = k\{x, y, u, v\}$ be the free algebra in noncommuting indeterminates x, y, u, v . Define $\sigma \in \text{Aut}_k R$ by

$$\begin{aligned}\sigma(x) &= x - (ux + yv)v, & \sigma(y) &= y + u(ux + yv), \\ \sigma(u) &= u, & \sigma(v) &= v.\end{aligned}$$

Note that $w = ux + yv$ is fixed by σ . Introduce a new variable t and let τ be the automorphism of $R\{t\}$ fixing x, y, u, v and sending t to $t + w$. Extend σ to $R\{t\}$ by

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setting $\sigma(t) = t$. Then $\tau \circ \sigma$ fixes $x + tv$, $y - ut$, u , and v and sends t to $t + w = t + u(x + tv) + (y - ut)v$. Thus $\tau \circ \sigma$ is triangular with respect to the list of indeterminates $t, x + tv, y - ut, u, v$. Since this list can be obtained from x, y, u, v, t by a triangular (with respect to x, y, u, v, t) automorphism followed by a linear one, it follows easily that $\tau \circ \sigma$ is the conjugate of a triangular (with respect to x, y, u, v, t) automorphism by a tame one, hence is tame. Since τ is tame, this implies σ (extended to $R\{t\}$) is tame.

Abelianizing Anick’s example gives a stably tame automorphism of the commutative polynomial ring.

Now consider the automorphism discussed by Bass (first mentioned by Nagata). Here, $R = k[x, y, z]$ and the automorphism σ is determined by

$$\begin{aligned} \sigma(x) &= x - 2(xz + y^2)y - (xz + y^2)^2z, \\ \sigma(y) &= y + (xz + y^2)z, \\ \sigma(z) &= z. \end{aligned}$$

Notice that both the abelianized Anick example and the Bass–Nagata example are ‘exponential automorphisms’, i.e., have the form $\sigma(r) = (\exp \Delta)(r) = \sum (1/i!) \Delta^i(r)$ where Δ is some locally nilpotent derivation of R (i.e., for each $r \in R$, there is an integer m with $\Delta^m(r) = 0$). Moreover, in both cases, $\Delta = wD$ for some ‘triangular’ derivation D and some $w \in \ker D$. Specifically, for Anick’s example, $w = ux + yv$ and

$$Dx = -v, \quad Dy = u, \quad Du = Dv = 0.$$

For the Bass–Nagata example, $w = xz + y^2$ and

$$Dx = -2y, \quad Dy = z, \quad Dz = 0.$$

(Note that in general, if D is locally nilpotent and $w \in \ker D$, then wD is also locally nilpotent.) The idea of Anick’s example goes over to all automorphisms of this form as follows. Call a derivation D of $R = k[x_1, \dots, x_n]$ *triangular* if for each i , $Dx_i \in k[x_{i+1}, \dots, x_n]$.

Proposition. *Let D be a locally nilpotent derivation of $R = k[x_1, \dots, x_n]$. Let $w \in \ker D$. Extend D to $R[t]$ by setting $Dt = 0$. (Note that tD is locally nilpotent.) Define $\tau \in \text{Aut}_k R[t]$ by $\tau(x_i) = x_i$, $i = 1, \dots, n$ and $\tau(t) = t + w$. Then*

$$\exp(wD) = \tau^{-1} \exp(-tD) \tau \exp(tD).$$

Corollary. *Let D, w be as above. If D is conjugate by a tame automorphism to a triangular derivation, then $\exp(wD)$ is stably tame.*

Proof of Corollary. Let γ be a tame automorphism of R with $\gamma^{-1}D\gamma = E$ a triangular derivation of R . Extend γ, D , and E to $R[t]$ by setting $\gamma t = t, Dt = Et = 0$. The extended γ is still tame and $\gamma^{-1}tD\gamma = tE$ is triangular, so $\exp(tD) = \gamma \exp(tE) \gamma^{-1}$

and $\exp(tE)$ is triangular. Since τ is tame, the proposition implies that $\exp(wD)$ is tame in $R[t]$. \square

Proof of Proposition. Since wD and tD commute, $\exp(wD) \circ \exp(-tD) = \exp((w-t)D)$. Since $DR \subseteq R$ and τ fixes R ,

$$\begin{aligned} \tau \circ \exp[(w-t)D](x_i) &= \tau \left(\sum_j \frac{(w-t)^j}{j!} D^j(x_i) \right) \\ &= \sum_j \frac{(-t)^j}{j!} D^j(x_i) = \exp(-tD)x_i. \end{aligned}$$

Since $Dt = 0$,

$$\tau \circ \exp[(w-t)D](t) = \tau(t) = t + w.$$

Thus

$$\exp(tD) \circ \tau \circ \exp[(w-t)D] = \tau,$$

from which the desired result follows by simple algebraic manipulation. \square

Remarks. (1) The proposition, corollary, and their proofs go over unchanged to other ‘relatively free’ algebras provided w commutes with the new generator t . In particular, consider the ring $R_n = k\langle x_1, \dots, x_n \rangle_d$ of n generic $d \times d$ matrices. In [2], Bergman gave examples of nontame automorphisms $\eta_{m,f}$ of R_n . These are defined by

$$\eta_{m,f} = \begin{cases} x_i, & i \neq m, \\ x_i + f, & i = m, \end{cases}$$

where f is a suitable central element of r_n . Thus $\eta_{m,f} = \exp(fD_m)$, where $D_m x_i = \delta_{im}$. Since the center of R_n is contained in the center of R_{n+1} [6, p. 172], computations as above show that Bergman’s examples are stably tame.

(2) It is natural to consider the ‘non-linear K -group’ $KA_1(k) = G/H$, where $G = \bigcup_n \text{Aut } k[x_1, \dots, x_n]$ is the stable group of automorphisms of polynomial rings over k and H is its commutator subgroup. Let D_i be the derivation of $k[x_1, \dots, x_n]$ sending x_j to δ_{ij} . Then the proposition implies that every automorphism of the form $\exp(wD_i)$, where $w \in k[x_1, \dots, \hat{x}_i, \dots, x_n]$, is in H . Since every triangular automorphism is a product of automorphisms of this form, all triangular automorphisms are in H . It follows that to prove the existence of automorphisms which are not stably tame, it suffices to show $KA_1(k)$ is larger than $K_1(k)$.

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Added in proof. David L. Wright [unpublished] has also shown that the Nagata–Bass automorphism is stably tame.