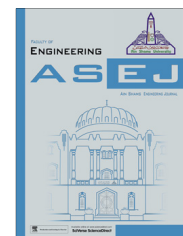




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## ENGINEERING PHYSICS AND MATHEMATICS

# Radiative nanofluid flow and heat transfer over a non-linear permeable sheet with slip conditions and variable magnetic field: Dual solutions

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## KEYWORDS

MHD;  
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Thermal radiation;  
Viscous dissipation

**Abstract Objective:** This paper addresses numerical investigation of steady, magneto-hydrodynamic boundary-layer slip flow of a nanofluid past a permeable stretching/shrinking sheet with thermal radiation using RK45 with shooting technique. The effect of viscous dissipation, suction/injection, Brownian motion, thermophoresis, partial velocity slip and thermal slip is taken into account and controlled by the non-dimensional parameters.

**Results and conclusions:** The dual solutions are obtained for the skin friction, Nusselt number, temperature and nanoparticle volume fraction with pertinent parameters in the domain  $(\chi_c, \infty)$  and  $(s_c, \infty)$ . The study shows that the Nusselt number decreases with an increase in thermophoresis parameter  $Nt$  and thermal slip parameter  $\delta$  but increases with thermal radiation  $R$  and Prandtl number  $Pr$ .

**Practice implications:** The present problem has numerous applications in engineering and petroleum industries such as glass blowing, annealing and thinning of copper wires. The study of radiation heat transfer plays an important role in the industrial applications at high temperature.

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## 1. Introduction

The vast study has been carried out by several researchers in the field of boundary layer flow and convective heat transfer over a stretching/shrinking sheet due to various applications

in the industries and engineering process such as glass blowing, annealing and thinning of copper wires. It is obvious that the desired quality of final sheet strongly depends on the stretching rate and the rate of cooling (heat transfer) in the process of stretching. First analysis on the boundary layer flow over a stretching sheet was studied by Crane [1]. This study is extended by many researchers to examine the various aspects of flow and heat transfer characteristics. Khan and Pop [2] studied the behavior of Nusselt number and Sherwood number for the boundary layer flow of a nanofluid over a linearly stretching sheet under the consideration of two-component model. Instead of linear stretching of sheet, the quality of sheet can also be controlled with nonlinear and exponentially

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**Nomenclature**

$a$	constant	$x, y$	Cartesian coordinates (m)
$B_0$	magnetic field strength (A/m)	$q_r$	radiative heat flux ( $\text{W/m}^2$ )
$C$	nanoparticle volume fraction		
$C_\infty$	ambient volume fraction		
$B(x)$	variable magnetic field ( $\text{A m}^{m-2}$ )	<i>Greek symbol</i>	
$D_B$	Brownian diffusion coefficient ( $\text{m}^2/\text{s}$ )	$\eta$	similarity variable
$D_T$	thermophoretic diffusion coefficient ( $\text{m}^2/\text{s}$ )	$\mu$	dynamic viscosity ( $\text{Ns/m}^2$ )
$Ec$	Eckert number	$\nu$	kinematic viscosity ( $\text{m}^2/\text{s}$ )
$f$	dimensionless stream function	$\phi$	rescaled nanoparticle volume fraction
$k$	thermal conductivity ( $\text{W/m K}$ )	$\theta$	dimensionless temperature
$Sc$	Schmidt number	$\chi$	stretching/shrinking parameter
$L$	velocity slip factor (m)	$\sigma$	electric conductivity of base fluid (S/m)
$m$	power index	$(\rho c)_f$	heat capacity of base fluid (J/K)
$M$	dimensionless magnetic field	$(\rho c)_p$	effective heat capacity of nanoparticle material (J/K)
$N$	thermal slip factor (m)	$\sigma^*$	Stefan–Boltzmann constant ( $\text{W m}^{-2} \text{K}^{-4}$ )
$Nb$	Brownian motion parameter	$\beta$	power-law parameter
$Nt$	thermophoresis parameter	$\tau_w$	shear stress at surface ( $\text{N/m}^2$ )
$Pr$	Prandtl number	$\delta$	thermal slip parameter
$R$	dimensionless thermal radiation		
$s$	mass transfer parameter	<i>Subscript</i>	
$T$	nanofluid temperature (K)	$\infty$	ambient condition
$T_w$	nanofluid temperature at sheet (K)	$w$	condition on surface
$T_\infty$	ambient temperature (K)	$r$	radiation
$u, v$	velocity components along $x$ - and $y$ -axis (m/s)	$f$	base fluid
$u_w$	velocity of sheet (m/s)	$s$	slip condition
$v_w$	mass transfer velocity (m/s)		

stretching along with consideration of heat and mass transfer characteristics. Motivated by this concept, Cortell [3] has discussed viscous flow and heat transfer over a nonlinearly stretching sheet. Rana and Bhargava [4] have extended the idea to nanofluids and employed finite element method for the numerical computation of flow and heat transfer characteristic over a nonlinearly stretching sheet. Moreover, analytical solution of the boundary layer flow over an exponential stretching sheet has been investigated (Nadeem and Lee [5]) using homotopy analysis method.

Since last few years many researchers are attracted towards nanofluid due to its enhanced thermal conductivity as compared to base fluids that are responsible for heat transfer. Nanofluid, which was first introduced by Choi [6], is dilute suspension of nanometer sized solid particle (Cu, Al, Ag, etc.) in base fluid such as water, oil and ethylene glycol. The novel characteristics of nanofluids can be utilized to develop stable suspensions with improved heat transfer. Many researchers have tried to develop the convective transport models for nanofluid. In 2006, Buongiorno [7] has presented non-homogeneous model to understand the convective transport phenomena in nanofluid and studied seven-slip mechanisms. Among these mechanisms only Brownian diffusion and thermophoresis diffusion are found most important. These two slip mechanisms are also incorporated in the study of natural convective boundary layer flow of a nanofluid over a vertical plate by Kuznetsov and Nield [8].

The study of magnetohydrodynamic has numerous applications in engineering, agriculture and petroleum industries. The problem of natural convection under the effect of a magnetic field has also applications in geophysics and astrophysics [9].

Due to this many studies were performed with the effect of magnetic field. Fang and Zhang [10] have given exact solution for MHD flow equation of fluid over a shrinking sheet. They have reported two solution branches for  $M \in (0, 1)$  but for  $M = 1$  single solution branch is obtained only in case of suction and when  $M > 1$  there is also single branch of solution for both suction and injection. In 2011, Hamad [11] investigated the analytical solution of electrical conducting nanofluid flow over a linearly stretching sheet under the influence of magnetic field. He found that momentum boundary layer thickness decreases but thermal boundary thickness increases with magnetic field. Rana et al. [12] presented unsteady MHD transport phenomena over a stretching sheet in a rotating nanofluid. Numerical investigation of the MHD flow and heat transfer of nanofluid between two horizontal plates in rotating system using Cu, Ag,  $\text{Al}_2\text{O}_3$  and  $\text{TiO}_2$  nanoparticles in water has been computed by Sheikholeslami et al. [13] and it is noticed that heat transfer is the highest for  $\text{TiO}_2$  nanoparticles. Currently, much attention has been devoted to work in the presence of magnetic field [14–18].

Several engineering processes occur due to high temperature; therefore, the study of radiation heat transfer plays an important role in the field of equipment designing [19]. Cortell [20] analyzed the boundary layer flow and heat transfer of fluid under the consideration of thermal radiation and viscous dissipation over a nonlinear stretched sheet. This work is extended by Hady et al. [21] in nanofluid and investigated the effect of thermal radiation, viscous dissipation and nanoparticle volume fraction on velocity, temperature and the rate of heat transfer at the surface. They noticed that an increase in thermal radiation decreases temperature of nanofluid which leads

to increment in rate of heat transfer whereas temperature increases with viscous dissipation which gives sudden fall in rate of heat transfer. Motsumi and Makinde [22] have studied the boundary layer flow over a permeable moving flat plate under the effect of viscous dissipation and thermal radiation by considering Cu-water and Al<sub>2</sub>O<sub>3</sub>-water nanofluids. Furthermore, Pal et al. [23] have studied the heat transfer over non-linear stretching and shrinking sheets under the influence of magnetic field, thermal radiation and viscous dissipation by considering copper (Cu), alumina (Al<sub>2</sub>O<sub>3</sub>), and titanium oxide (TiO<sub>2</sub>) nanoparticles. Recently, Nandy and Pop [24] extended the work of Khan and Pop [2] by examining the study of MHD boundary layer stagnation flow and heat transfer over a shrinking sheet incorporating the two component model under the effect of radiation. Very recently, Sheikholeslami et al. [25] studied the combined effect of magnetic field and thermal radiation for nanofluid flow and heat transfer between two horizontal parallel plates by considering two-component model. Rashidi et al. [26] have also investigated the combined effect of magnetic field and thermal radiation over a vertical stretching sheet for two dimensional water based nanofluid flow. They observed that velocity decreases and temperature increases in the presence of magnetic field and skin friction increases with magnetic field and thermal radiation.

Most of the studies are carried out without slip condition, i.e. it is assumed that fluid particles have zero velocity relative to solid boundary. But literature shows that the characteristics are different in case of micro- and nano-scale fluid flow. Thus, the importance of slip boundary condition was first discussed by Navier [27], which states that fluid slip is proportional to shear stress. In 2002, Wang [28] has given the exact solution of Navier–Stokes equations for the flow over a stretching sheet by taking into account partial slip. Fang et al. [29] also investigated the analytical solution for slip effect over a shrinking sheet considering magnetic field effect and noticed the multiple, single and no solution exist for  $0 < M < 1$ ,  $M = 1$ , and  $M > 1$ , respectively. Recently, Das [30,31] investigated the partial slip flow and convective heat transfer of nanofluids over a linear and nonlinear stretching sheet. Moreover, Ibrahim and Shankar [32] incorporated the effect of velocity, thermal and solutal slip boundary condition over a stretching sheet to study the MHD boundary layer flow and heat transfer of a nanofluid. Currently, Uddin et al. [33] have studied hydromagnetic boundary layer slip flow of bio-nanofluid which is significant to the synthesis of bio-magnetic nanofluids of potential interest in skin repair, wound treatments and coatings for biological devices. Multiple solutions for fluid flow and heat transfer are also a point of attraction of various researchers. The survey of recent literatures shows the existence of more than one solution for boundary layer flow over stretching/shrinking sheet [34–38].

The main concern of current study is to investigate the dual solution for the combined effects of thermal radiation, magnetic field, mass suction transfer, and viscous dissipation for steady boundary layer nanofluid flow over a power-law stretching/shrinking sheet in the presence of partial slip by using Nield and Kuznetsov revised nanofluid model [8]. As authors knowledge no efforts are devoted for this kind of problem. Motivated by this fact, present study analyzes the variation of skin friction, Nusselt number, temperature and nanoparticle concentration in the presence of abovementioned parameters numerically by using shooting method

[39] with RKF45 method and presented graphically in this paper.

## 2. Nanofluid transport model

We consider a steady, laminar, two dimensional boundary layer flow of incompressible and electrically conducting nanofluid along a horizontal nonlinear stretching/shrinking sheet under the effect of viscous dissipation and thermal radiation. The coordinate system is considered as,  $x$ -axis is taken along the sheet and  $y$ -axis perpendicular to the sheet (see Fig. 1). The fluid is moving due to nonlinear stretching/shrinking of the sheet caused by two parallel forces act in opposite direction along the  $x$ -axis. The sheet is stretched/shrunk with velocity  $u_w(x) = ax^m$ , where  $a$  is a constant,  $m$  is a power index and wall mass suction/injection velocity is  $v_w = v_w(x)$ , by keeping the origin ‘O’ fixed. The variable magnetic field  $B(x)$  is assumed to be applied along  $y$ -axis. The radiative heat flux  $q_r$  is also taken perpendicular ( $y$ -axis) to the sheet. The temperature at sheet  $T_w$  is assumed to be constant and the ambient temperature is  $T_\infty$ , as  $y \rightarrow \infty$  where  $T_\infty < T_w$ . The nanoparticle volume fraction is assumed to be controlled passively on the sheet by the temperature gradient. The ambient nanoparticle volume fraction is  $C_\infty$ . The external forces and pressure gradient are assumed to be zero. Under these hypotheses, the steady conservation equations for proposed nanofluid model are presented in Cartesian coordinates  $x, y$  as (see [7,8,21,31,40])

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0 \tag{1}$$

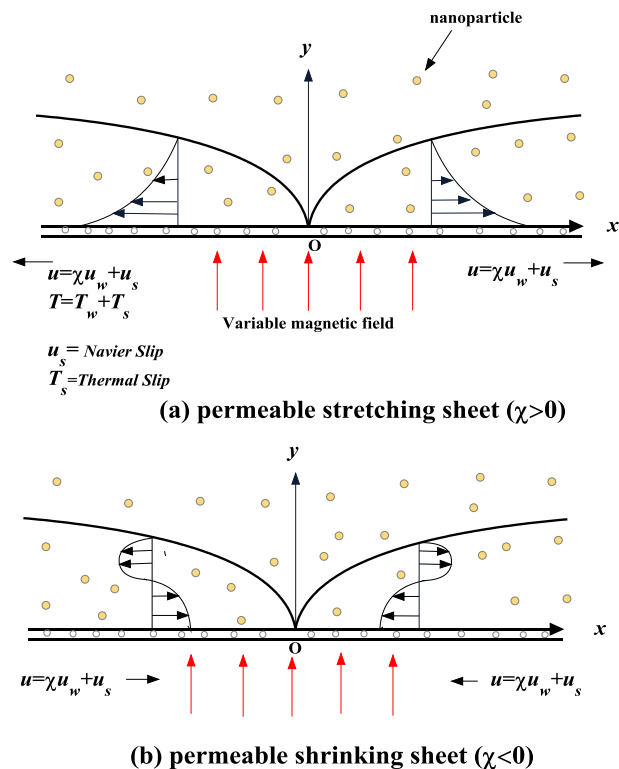


Figure 1 Physical model and the coordinate system.

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} = \nu \frac{\partial^2 u}{\partial y^2} - \frac{\sigma B^2}{\rho} u \tag{2}$$

$$(\rho c)_f \left( u \frac{\partial T}{\partial x} + v \frac{\partial T}{\partial y} \right) = k \frac{\partial^2 T}{\partial y^2} - \frac{\partial q_r}{\partial y} + (\rho c)_p \left( D_B \left( \frac{\partial C}{\partial y} \right) \left( \frac{\partial T}{\partial y} \right) + \frac{D_T}{T_\infty} \left( \frac{\partial T}{\partial y} \right)^2 \right) + \mu \left[ \frac{\partial u}{\partial y} \right]^2 \tag{3}$$

$$u \frac{\partial C}{\partial x} + v \frac{\partial C}{\partial y} = D_B \frac{\partial^2 C}{\partial y^2} + \frac{D_T}{T_\infty} \frac{\partial^2 T}{\partial y^2} \tag{4}$$

In Eq. (2), we have ignored the induced magnetic field because of small magnetic Reynolds number for fluid motion. The external electric field and electric field due to polarization of charges are also neglected and the magnetic field is of the form [41]:

$$B(x) = B_0 x^{(m-1)/2} \tag{5}$$

where  $m$  is power index.

Here  $u$  and  $v$  are the velocity components along the  $x$ - and  $y$ -axis, respectively,  $\rho_f$  and  $\rho_p$  are the base fluid and nanoparticle densities respectively,  $\mu$  is the dynamic viscosity,  $\nu$  is the kinematic viscosity,  $\sigma$  is the electrical conductivity of the base fluid,  $T$  is the temperature,  $c_f$  and  $c_p$  are the specific heat of base fluid and nanoparticle at fixed pressure, respectively and  $k$  is the thermal conductivity.  $C$  is concentration of nanoparticles,  $D_B$  is Brownian motion and  $D_T$  is thermophoretic diffusion coefficient. The boundary conditions are as follows (see [8,32,38]):

$$u = \chi u_w(x) + u_s, \quad v = v_w(x), \quad T = T_w + T_s, \\ D_B \frac{\partial C}{\partial y} + \frac{D_T}{T_\infty} \frac{\partial T}{\partial y} = 0 \quad \text{at } y = 0 \tag{6a}$$

$$u = 0, \quad v = 0, \quad T = T_\infty, \quad C = C_\infty \quad \text{as } y \rightarrow \infty \tag{6b}$$

where  $\chi$  is stretching (for positive)/shrinking (for negative) parameter,  $u_s$  is slip velocity which is assumed equal to  $L \frac{\partial u}{\partial y}$  and  $T_s$  is thermal slip equal to  $N \frac{\partial T}{\partial y}$ .

$q_r$  is considered insignificant in  $x$ -direction and defined by applying Rosseland approximation for optically thick media, as (see [21,42,43]):

$$q_r = \frac{-4}{3k^*} \text{grad}(e_b) \tag{7}$$

where  $k^*$  is the Rosseland mean spectral absorption coefficient and  $e_b$  is the blackbody emission power, defined by the Stefan-Boltzmann radiation law  $e_b = \sigma^* T^4$ . Hence

$$q_r = \frac{-4\sigma^*}{3k^*} \frac{\partial T^4}{\partial y} \tag{8}$$

The temperature difference inside the flow is assumed to be very small so  $T^4$  can be expressed as a linear function of temperature, by applying Taylor series expansion about  $T_\infty$  such that

$$T^4 = T_\infty^4 + 4T_\infty^3(T - T_\infty) + 6T_\infty^2(T - T_\infty)^2 + \dots \tag{9}$$

higher order terms of  $(T - T_\infty)$  in above Eq. (9) are neglected, then we get

$$T^4 \approx 4T_\infty^3 T - 3T_\infty^4 \tag{10}$$

Using Eq. (10) in Eq. (8), we obtain

$$q_r = -\frac{4\sigma^*}{3k^*} \frac{\partial}{\partial y} (4T_\infty^3 T - 3T_\infty^4) = -\frac{16\sigma^* T_\infty^3}{3k^*} \frac{\partial T}{\partial y} \tag{11}$$

and

$$\frac{\partial q_r}{\partial y} = -\frac{16\sigma^* T_\infty^3}{3k^*} \frac{\partial^2 T}{\partial y^2} \tag{12}$$

Now we introduce the following similarity variables for Eqs. (1)–(4) with boundary conditions (6):

$$\psi = \sqrt{\frac{2\nu a}{m+1}} x^{\frac{m+1}{2}} f(\eta), \quad \eta = y \sqrt{\frac{a(m+1)}{2\nu}} x^{\frac{m-1}{2}}, \\ \theta(\eta) = \frac{T - T_\infty}{T_w - T_\infty}, \quad \phi(\eta) = \frac{C - C_\infty}{C_\infty},$$

where  $\psi$  is the stream function, which is defined as  $u = \frac{\partial \psi}{\partial y}$  and  $v = -\frac{\partial \psi}{\partial x}$ . Thus, we have

$$u = ax^m f'(\eta), \quad v = -\sqrt{\frac{av(m+1)}{2}} x^{\frac{m-1}{2}} \left[ f(\eta) + \frac{m-1}{m+1} \eta f'(\eta) \right] \tag{13}$$

Hence using similarity variables the governing Eqs. (2)–(4) transform to

$$f''' + ff'' - \beta f'^2 - M^2 f' = 0 \tag{14}$$

$$\left( 1 + \frac{4R}{3} \right) \theta'' + Nb \theta' \phi' + Nt \theta'^2 + Pr(f\theta' + Ec f'^2) = 0 \tag{15}$$

$$\phi'' + Sc f \phi' + \frac{Nt}{Nb} \theta'' = 0 \tag{16}$$

and boundary conditions become

$$\text{at } \eta = 0, \quad f = s, \quad f' = \chi + \lambda f'', \quad \theta = 1 + \delta \theta', \quad Nb \phi' + Nt \theta' = 0,$$

$$\text{as } \eta \rightarrow \infty, \quad f' = 0, \quad \theta = 0, \quad \phi = 0, \tag{17}$$

where prime denotes the differentiation with respect to  $\eta$  only

and  $\beta = \frac{2m}{m+1}$  power-law parameter,  $M = \sqrt{\frac{2\sigma B_0^2}{a\rho_f(m+1)}}$  is Hartman number or magnetic field parameter,  $Pr = \frac{(\rho c)_p \nu}{k}$  is Prandtl number,  $Sc = \frac{\nu}{D_B}$  is Schmidt number,  $Ec = \frac{u_w^2}{c_f(T_w - T_\infty)}$  is Eckert number,  $R = \frac{4\sigma^* T_\infty^3}{k^* k}$  is radiation parameter,  $Nb = \frac{(\rho c)_p D_B C_\infty}{(\rho c)_f \alpha}$  is Brownian motion parameter,  $Nt = \frac{(\rho c)_p D_T (T_w - T_\infty)}{(\rho c)_f \alpha T_\infty}$  is thermophoresis parameter,  $s = -\frac{v_w}{\sqrt{\frac{av(m+1)}{2}} x^{\frac{m-1}{2}}}$  is mass transfer parameter, i.e. suction for ( $v_w < 0$ ) and injection for ( $v_w > 0$ ),  $\lambda = L \sqrt{\frac{a(m+1)}{2\nu}} x^{\frac{m-1}{2}}$  is the velocity slip parameter, and  $\delta = N \sqrt{\frac{a(m+1)}{2\nu}} x^{\frac{m-1}{2}}$  is the thermal slip parameter.

The important physical quantities in this study are the skin friction coefficient and the local Nusselt number which are defined as

$$C_f = \frac{\tau_w}{\rho u_w^2}, \quad Nu_x = \frac{x q_w}{k(T_w - T_\infty)}, \tag{18}$$

where  $\tau_w$  is shear stress at wall and  $q_w$  is the wall heat flux which are given below:

$$\tau_w = \mu \left( \frac{\partial u}{\partial y} \right)_{y=0}, \quad q_w = - \left( k + \frac{16\sigma^* T_\infty^3}{3k^*} \right) \left( \frac{\partial T}{\partial y} \right)_{y=0}. \quad (19)$$

Using Eqs. (13) and (19) in Eq. (18), we get

$$C_f Re^{1/2} = f''(0) \quad \text{and} \quad \frac{Nu_x}{Re^{1/2}} = - \left( 1 + \frac{4}{3} R \right) \theta'(0),$$

where  $Re = \frac{a(m+1)}{2v} x^{m+1}$  is Local Reynolds number and Reduced Nusselt number is given by

$$Nur = - \left( 1 + \frac{4}{3} R \right) \theta'(0). \quad (20)$$

A closed analytical solution for MHD slip flow  $f''' + ff'' - f^2 - M^2 f' = 0$  over a shrinking sheet has been obtained by Fang et al. [29], which is given as

$$f(\eta) = s - \frac{1}{\zeta + \lambda\zeta^2} + \frac{1}{\zeta + \lambda\zeta^2} e^{-\zeta\eta}, \quad (21)$$

and

$$f'(\eta) = - \frac{1}{1 + \lambda\zeta} e^{-\zeta\eta}, \quad f''(0) = \frac{\zeta}{1 + \lambda\zeta}, \quad (22)$$

where  $s$  is mass transfer parameter,  $\lambda$  is velocity slip parameter and  $\zeta$  is root of the Eq.  $\lambda\zeta^3 + (1 - s\lambda)\zeta^2 - (s + \lambda M^2)\zeta + 1 - M^2 = 0$ . Only positive real roots of  $\zeta$  are physically feasible solutions. There may be either three real roots or one real and two complex conjugate roots or one simple real and two two-fold real roots or one threefold real roots depending on the values of  $M, s$  and  $\lambda$ . For  $M < 1$  multiple solutions are observed for all values of  $\lambda$  and the domain of multiple solutions is changed with  $\lambda$ . For  $M = 1$ , only one solution branch exists and when  $M > 1$ , there is one solution for both mass suction and injection [29].

### 3. Stability analysis

The stability of the solutions is investigated by considering unsteady flow of present nanofluid model which is given as

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0, \quad (23)$$

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} = v \frac{\partial^2 u}{\partial y^2} - \frac{\sigma B^2}{\rho} u, \quad (24)$$

$$\begin{aligned} &(\rho c)_f \left( \frac{\partial T}{\partial t} + u \frac{\partial T}{\partial x} + v \frac{\partial T}{\partial y} \right) \\ &= k \frac{\partial^2 T}{\partial y^2} - \frac{\partial q_r}{\partial y} + (\rho c)_p \left[ D_B \frac{\partial C}{\partial y} \frac{\partial T}{\partial y} + \frac{D_T}{T_\infty} \left( \frac{\partial T}{\partial y} \right)^2 \right] + \mu \left( \frac{\partial u}{\partial y} \right)^2, \end{aligned} \quad (25)$$

$$\frac{\partial C}{\partial t} + u \frac{\partial C}{\partial x} + v \frac{\partial C}{\partial y} = D_B \frac{\partial^2 C}{\partial y^2} + \frac{D_T}{T_\infty} \frac{\partial^2 T}{\partial y^2}, \quad (26)$$

and new similarity transformations are

$$\begin{aligned} \psi &= \sqrt{\frac{2va}{m+1}} x^{\frac{m+1}{2}} f(\eta, \tau), \quad \eta = y \sqrt{\frac{a(m+1)}{2v}} x^{\frac{m-1}{2}}, \\ \tau &= \frac{a(m+1)}{2} x^{m-1} t, \quad \theta(\eta, \tau) = \frac{T - T_\infty}{T_w - T_\infty}, \quad \phi(\eta, \tau) = \frac{C - C_\infty}{C_\infty}. \end{aligned} \quad (27)$$

Using Eq. (27) into Eqs. (24)–(26) we obtain,

$$\frac{\partial^3 f}{\partial \eta^3} + f \frac{\partial^2 f}{\partial \eta^2} - \beta \left( \frac{\partial f}{\partial \eta} \right)^2 - M^2 \frac{\partial f}{\partial \eta} - \frac{\partial^2 f}{\partial \tau \partial \eta} = 0, \quad (28)$$

$$\begin{aligned} &\left( 1 + \frac{4R}{3} \right) \frac{\partial^2 \theta}{\partial \eta^2} + Nb \frac{\partial \theta}{\partial \eta} \frac{\partial \phi}{\partial \eta} + Nt \left( \frac{\partial \theta}{\partial \eta} \right)^2 \\ &+ Pr \left[ Ec \left( \frac{\partial^2 f}{\partial \eta^2} \right)^2 + f \frac{\partial \theta}{\partial \eta} - \frac{\partial \theta}{\partial \tau} \right] = 0, \end{aligned} \quad (29)$$

$$\frac{\partial^2 \phi}{\partial \eta^2} + Scf \frac{\partial \phi}{\partial \eta} + \frac{Nt}{Nb} \frac{\partial^2 \theta}{\partial \eta^2} - \frac{\partial \phi}{\partial \tau} = 0, \quad (30)$$

along with boundary conditions

$$\begin{aligned} f(0, \tau) &= s, \quad \frac{\partial f}{\partial \eta}(0, \tau) = \chi + \lambda \frac{\partial^2 f}{\partial \eta^2}(0, \tau), \\ \theta(0, \tau) &= 1 + \delta \frac{\partial \theta}{\partial \eta}(0, \tau), \quad Nb \frac{\partial \phi}{\partial \eta}(0, \tau) + Nt \frac{\partial \theta}{\partial \eta}(0, \tau) = 0, \\ \text{as } \eta \rightarrow \infty, \quad &\frac{\partial f}{\partial \eta}(\eta, \tau) = 0, \quad \theta(\eta, \tau) = 0, \quad \phi(\eta, \tau) = 0. \end{aligned} \quad (31)$$

As suggested by Merkin [44], and Harris et al. [45], the stability of the steady flow solution  $f(\eta) = f_0(\eta)$ ,  $\theta(\eta) = \theta_0(\eta)$  and  $\phi(\eta) = \phi_0(\eta)$  which satisfies the boundary value problem (14)–(17), can be investigated by considering eigenvalue parameter  $\alpha$  with the following relations:

$$\begin{aligned} f(\eta, \tau) &= f_0(\eta) + e^{-\alpha\tau} F(\eta, \tau), \\ \theta(\eta, \tau) &= \theta_0(\eta) + e^{-\alpha\tau} G(\eta, \tau), \\ \phi(\eta, \tau) &= \phi_0(\eta) + e^{-\alpha\tau} H(\eta, \tau), \end{aligned} \quad (32)$$

where  $F(\eta, \tau), G(\eta, \tau)$  and  $H(\eta, \tau)$  are small relative to  $f_0(\eta), \theta_0(\eta)$  and  $\phi_0(\eta)$ , respectively.

Using relations (32) into Eqs. (28)–(31) we get the following linear system:

$$\frac{\partial^3 F}{\partial \eta^3} + \frac{\partial^2 f_0}{\partial \eta^2} F + f_0 \frac{\partial^2 F}{\partial \eta^2} - 2\beta \frac{\partial f_0}{\partial \eta} \frac{\partial F}{\partial \eta} - M^2 \frac{\partial F}{\partial \eta} - \frac{\partial^2 F}{\partial \tau \partial \eta} + \alpha \frac{\partial F}{\partial \eta} = 0, \quad (33)$$

$$\begin{aligned} &\left( 1 + \frac{4R}{3} \right) \frac{\partial^2 G}{\partial \eta^2} + Nb \left( \frac{\partial \phi_0}{\partial \eta} \frac{\partial G}{\partial \eta} + \frac{\partial \theta_0}{\partial \eta} \frac{\partial H}{\partial \eta} \right) + 2Nt \frac{\partial \theta_0}{\partial \eta} \frac{\partial G}{\partial \eta} + \frac{\partial \theta_0}{\partial \eta} F \\ &+ Pr \left( f_0 \frac{\partial G}{\partial \eta} + 2Ec \frac{\partial^2 f_0}{\partial \eta^2} \frac{\partial^2 F}{\partial \eta^2} - \frac{\partial G}{\partial \tau} + \alpha G \right) = 0, \end{aligned} \quad (34)$$

$$\frac{\partial^2 H}{\partial \eta^2} + Sc \left( f_0 \frac{\partial H}{\partial \eta} + \frac{\partial \phi_0}{\partial \eta} \right) + \frac{Nt}{Nb} \frac{\partial^2 G}{\partial \eta^2} - \frac{\partial H}{\partial \tau} + \alpha H = 0, \quad (35)$$

$$F(0, \tau) = s, \quad \frac{\partial F}{\partial \eta}(0, \tau) = \lambda \frac{\partial^2 F}{\partial \eta^2}(0, \tau), \quad G(0, \tau) = \delta \frac{\partial G}{\partial \eta}(0, \tau),$$

$$Nb \frac{\partial H}{\partial \eta}(0, \tau) + Nt \frac{\partial G}{\partial \eta}(0, \tau) = 0,$$

$$\text{as } \eta \rightarrow \infty, \quad \frac{\partial F}{\partial \eta}(\eta, \tau) = 0, \quad G(\eta, \tau) = 0, \quad H(\eta, \tau) = 0. \quad (36)$$

Now the stability of the solutions  $f(\eta) = f_0(\eta), \theta(\eta) = \theta_0(\eta)$  and  $\phi(\eta) = \phi_0(\eta)$  of steady problem (14)–(17) can be discussed by putting  $\tau = 0$  and then we obtain

$$F''_0 + f''_0 F_0 + f_0 F'' - 2\beta f'_0 F'_0 - M^2 F'_0 + \alpha F_0 = 0, \quad (37)$$



$$\left(1 + \frac{4R}{3}\right)G_0'' + Nb(\phi_0'G_0' + \theta_0'H_0') + 2Nt\theta_0'G_0' + Pr(f_0'G_0' + \theta_0'F + 2Ec f_0''F_0' + \alpha G_0) = 0, \tag{38}$$

$$H_0'' + Sc(\phi_0'F_0 + f_0'H_0') + \frac{Nt}{Nb}G_0'' + \alpha H_0 = 0, \tag{39}$$

along with boundary conditions

$$F_0(0) = 0, \quad F_0'(0) = \lambda F_0''(0), \quad G_0(0) = \delta G_0'(0), \quad NbH_0'(0) + NtG_0'(0) = 0, \tag{40}$$

as  $\eta \rightarrow \infty, F_0(\eta) = 0, G_0(\eta) = 0, H_0(\eta) = 0,$

where  $F = F_0(\eta), G = G_0(\eta)$  and  $H = H_0(\eta)$  characterize the initial growth and decay of the solution (32). To solve the linear eigenvalue problem (37)–(39) with boundary conditions (40), we relax the condition  $F_0'(\eta) \rightarrow 0$  as  $\eta \rightarrow \infty$  and use new boundary condition  $F_0''(0) = 1$ , [45].

#### 4. Numerical solution and validation

The nonlinear ordinary differential Eqs. (14)–(16) along with boundary conditions (17) are solved numerically using shooting technique by converting into initial value problem (IVP). We have placed Eqs. (14)–(16) as first order differential equations by assuming  $(f, f', f'', \theta, \theta', \phi, \phi') = (U_1, U_2, U_3, U_4, U_5, U_6, U_7) = U$ , as given below:

$$\begin{pmatrix} U_1' \\ U_2' \\ U_3' \\ U_4' \\ U_5' \\ U_6' \\ U_7' \end{pmatrix} = \begin{pmatrix} U_2 \\ U_3 \\ -U_1U_3 + \beta U_2^2 + M^2U_2 \\ U_5 \\ -\frac{1}{1+4\beta} [Pr(U_1U_5 + EcU_3^2) + NbU_5U_7 + NtU_5^2] \\ U_7 \\ -(ScU_1U_7 + \frac{Nt}{Nb}U_5') \end{pmatrix}, \tag{41}$$

with the initial conditions

$$U^T = \left( s, \chi + \lambda U_3, U_3, 1 + \delta U_5, U_5, U_6, -\frac{Nt}{Nb}U_5 \right)^T. \tag{42}$$

Here it is noticed that without knowing the values of  $U_3, U_5$  and  $U_6$ , i.e.  $f''(0), \theta'(0)$  and  $\phi(0)$ , we are not able to solve above system of Eq. (41) with initial conditions (42), which are unknown in this problem; therefore, the most important step of this technique is to pick the suitable values of these unknowns. For this we choose initial values for  $f''(0), \theta'(0)$  and  $\phi(0)$ , such that far field conditions, i.e.  $f'(\infty) = 0, \theta(\infty) = 0, \phi(\infty) = 0$ , are satisfied with appropriate domain length  $\eta_\infty$  and improve chosen values iteratively by Newton-Raphson method. After getting all the initial conditions, we solve the initial value problem using MATLAB code for RKF45 method. An iterative process is assumed to give a convergent solution when the following condition is satisfied:

$$\sum_i |\Omega_i^n - \Omega_i^{n-1}| \leq 10^{-6}.$$

We have compared the  $\{-\theta'(0)\}$  and  $\{-\phi'(0)\}$  with earlier published results by [46,2] in Tables 1 and 2 respectively, to validate the accuracy of present numerical results. Skin friction

is also compared with exact solution for without slip condition in Table 3. The graphical validation for velocity profile  $f'(\eta)$  between exact and numerical solution demonstrated by Fang et al. [29], is shown in Fig. 2. The outstanding agreement is reported for all the results.

#### 5. Results and discussion

The analysis of the present problem has been done numerically. Numerical results of skin friction  $f''(0)$ , Nusselt Number, temperature  $\theta(\eta)$  and nanoparticle concentration  $\phi(\eta)$  are presented graphically for different values of governing parameters in Figs. 3–12. We have fixed default values for governing parameters as  $R = 0.1, \beta = 1.5, M = 0.1, Ec = 0.1, s = 3.0, Pr = 6.8, Sc = 10, Nb = 0.5, Nt = 0.5, \lambda = 0.1$  and  $\delta = 0.1$

**Table 1** Comparison of results for  $-\theta'(0)$  and  $-\phi'(0)$  when  $M = s = R = Ec = 0, Pr = 10 = Sc$ , and  $\delta = 0$  for different values of  $Nb, Nt$  and  $\lambda$  for linear stretching sheet  $\chi = 1$ .

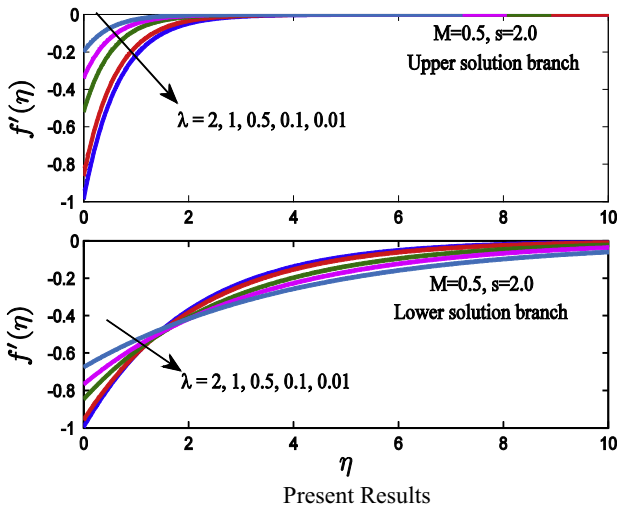
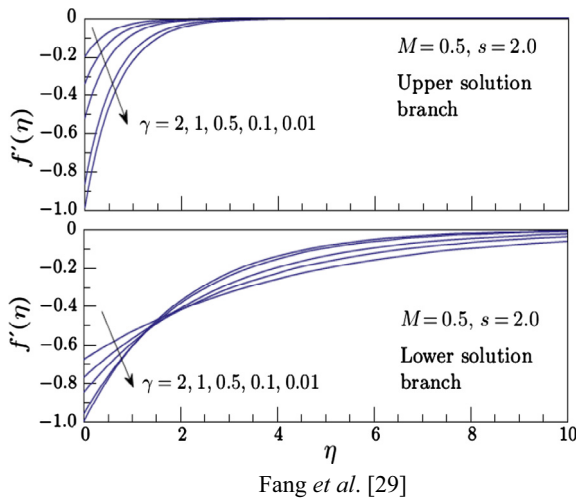
$Nb$	$Nt$	$\lambda = 0$		$\lambda = 1$	
		Noghrehabadi et al. [46]	Present results	Noghrehabadi et al. [46]	Present results
$-\theta'(0)$					
0.1	0.1	0.952377	0.952377	0.718928	0.718928
	0.3	0.520079	0.520079	0.392596	0.392596
	0.5	0.321054	0.321054	0.242357	0.242357
0.3	0.1	0.252156	0.252155	0.190347	0.190346
	0.3	0.135514	0.135514	0.102297	0.102296
	0.5	0.083298	0.083298	0.062880	0.062880
$-\phi'(0)$					
0.1	0.1	2.129394	2.129395	1.607430	1.607431
	0.3	2.528638	2.528639	1.908809	1.908810
	0.5	3.035142	3.035144	2.291156	2.291157
0.3	0.1	2.410019	2.410019	1.819268	1.819269
	0.3	2.608819	2.608820	1.969337	1.969338
	0.5	2.751875	2.751877	2.077327	2.077328

**Table 2** Comparison of  $\{-\theta'(0)\}$  and  $\{-\phi'(0)\}$  for different values of  $Nt$  and  $Nb$  with fixed nanoparticle concentration and no slip condition on the surface, when  $Pr = 10 = Sc, Ec = 0 = M = s = R$  for linear stretching sheet  $\chi = 1$ .

$Nt$	$Nb$	$-\theta'(0)$		$-\phi'(0)$	
		Khan and Pop [2]	Present	Khan and Pop [2]	Present
0.1	0.1	0.9524	0.952376	2.1294	2.129388
	0.3	0.2522	0.252155	2.4100	2.410015
	0.5	0.0543	0.054253	2.3836	2.383567
0.3	0.1	0.5201	0.520079	2.5286	2.528625
	0.3	0.1355	0.135514	2.6088	2.608812
	0.5	0.0291	0.029135	2.4984	2.498367
0.5	0.1	0.3211	0.321054	3.0351	3.035120
	0.3	0.0833	0.083298	2.7519	2.751866
	0.5	0.0179	0.017922	2.5731	2.573099

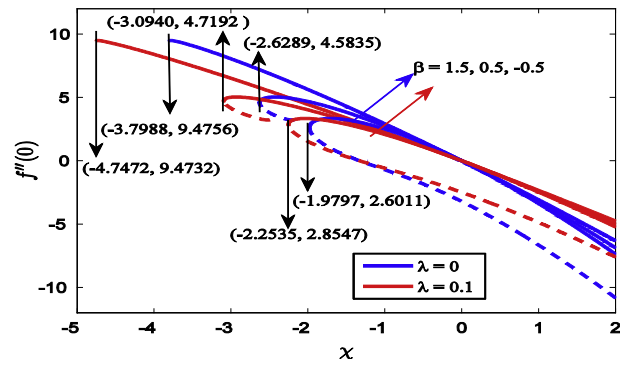
**Table 3** Comparison of skin friction at the wall  $f''(0)$  with exact solution in case of shrinking sheet  $\chi = -1$  for no slip flow ( $\lambda = 0, \delta = 0$ ).

$s$	$M$	Exact solution [10]		Present result	
		First	Second	First	Second
3.0	0.1	2.622497	0.377503	2.622498	0.377503
	0.3	2.657584	0.342416	2.657584	0.342416
	0.5	2.724745	0.275255	2.724745	0.275255
4.0	0.1	3.734935	0.265065	3.734935	0.265065
	0.3	3.757840	0.242160	3.757840	0.242160
	0.5	3.802776	0.197224	3.802776	0.197224

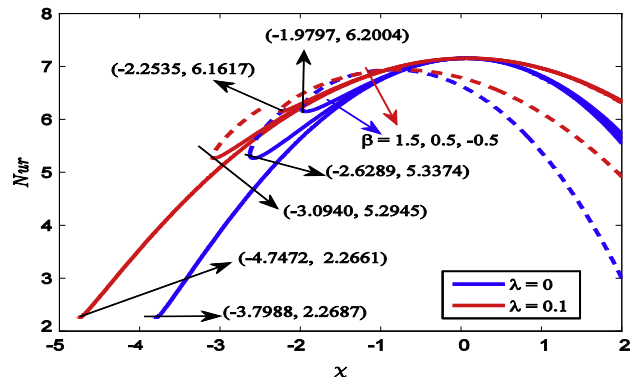


**Figure 2** The graphical comparison with exact solution of velocity profile given by Fang et al. [29] at magnetic field  $M = 0.5$  and mass transfer parameter  $s = 2.0$  for different values of velocity slip parameter  $\lambda$  for shrinking sheet  $\chi = -1$ .

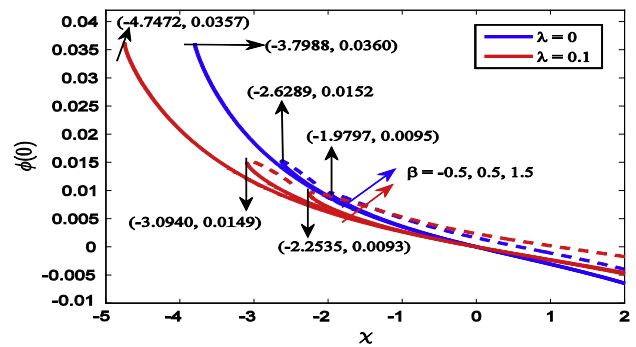
throughout the computations. First and second solutions are displayed with solid and dotted lines respectively. Since the study considers the dual solutions for the present problem, the physical existence of both first and second solutions is



**Figure 3** Skin friction  $f''(0)$  with stretching parameter  $\chi$  for different values of power-law parameter  $\beta$ .

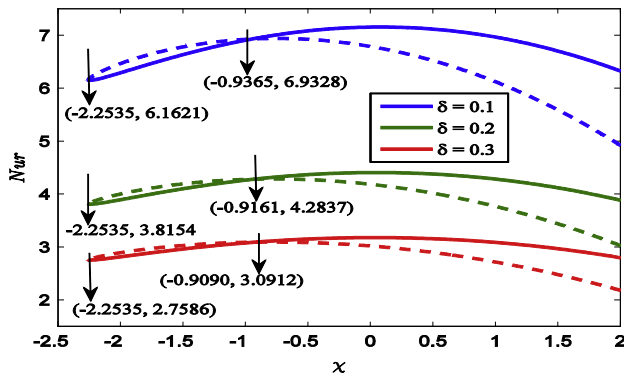


**Figure 4** The Nusselt number at the surface with stretching parameter  $\chi$  for different values of power-law parameter  $\beta$ .

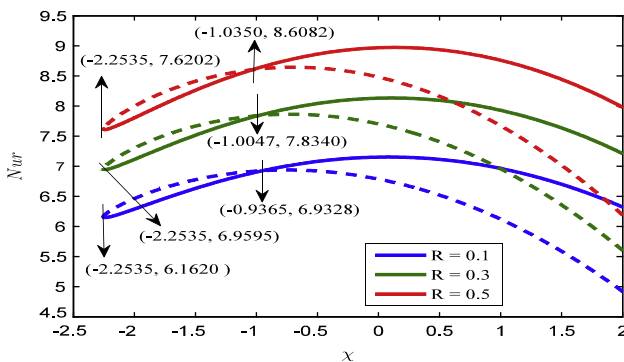


**Figure 5** The nanoparticle volume fraction at the surface with stretching parameter  $\chi$  for different values of power-law parameter  $\beta$ .

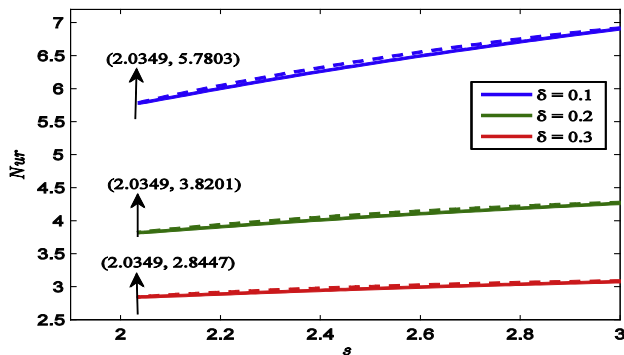
investigated by performing stability analysis. We have found the smallest eigenvalues  $\alpha$  for some values of involving parameters and results are shown in Table 4. It can be seen that the smallest eigenvalues are positive and negative for the first and second solutions, respectively. The positive eigenvalue corresponds to physically stable solution whereas negative to unstable [44,45]. Hence the first solution is physically stable and second is unstable. Numerical results of  $\{-\theta'(0)\}$  have been shown in Table 5 for different values of governing parameters.



**Figure 6** The Nusselt number at surface with stretching parameter  $\chi$  for different values of thermal slip parameter  $\delta$ .



**Figure 7** The Nusselt number at surface with stretching parameter  $\chi$  for different values of thermal radiation parameter  $R$ .



**Figure 8** The Nusselt number with mass transfer parameter  $s$  for different values of thermal slip parameter  $\delta$ .

Figs. 3–5 present the influences of power-law parameter  $\beta$  and velocity slip parameter  $\lambda$ , on the skin friction  $f''(0)$ , Nusselt number and nanoparticle volume fraction  $\phi(0)$  for different values of stretching parameter  $\chi$ . The dual solutions are obtained for  $\beta > 0$  while only single solution is obtained when  $\beta$  goes to negative and these solutions are terminated by critical value  $\chi_c$ . It can also be seen that beyond  $\chi_c$  ( $\chi < \chi_c$ ), no solution exists and this critical value shifts on left side with  $\beta$  and  $\lambda$ . It is observed that for skin friction, both the solutions are decreasing with an increase in  $\beta$  but opposite behavior is

observed for increasing value of  $\lambda$ . The Nusselt number increases with  $\lambda$  and attains maximum value near  $\chi = 0$  (static) after that it goes down to the Nusselt number at critical value  $\chi_c$ . The Nusselt number at the surface enhances as an increase in power-law parameter. Nanoparticle volume fraction increases as power-law parameter increases whereas decreases with increasing value of velocity slip parameter.

The effects of thermal slip parameter  $\delta$  and thermal radiation  $R$  on the Nusselt number are shown in Figs. 6 and 7. It can be seen that the solution does not exist beyond the critical value  $\chi_c = -2.2535$  and the first and second both the solutions are decreasing with increasing values of thermal slip parameter  $\delta$  and increasing with thermal radiation  $R$ . Here it can also be noted that for particular value of  $\chi$  near to  $-1$  the Nusselt number has unique value and first and second solutions have opposite behavior on left and right of this particular value. For  $\delta = 0.1, 0.2$  and  $0.3$ , the particular value  $\chi_{pv}$  is  $-0.9365, -0.9161$  and  $-0.9090$  respectively. Similarly, for  $R = 0.1, 0.3$  and  $0.5$ ,  $\chi_{pv}$  is  $-0.9365, -1.0047$  and  $-1.0350$  respectively.

Further, the effect of mass transfer parameter  $s$  on the Nusselt number for different values of thermal slip parameter  $\delta$  is investigated (see Fig. 8) and observed that the Nusselt number is decreasing with  $\delta$  and  $s$ . The critical value  $s_c$  remains unchanged with  $\delta$  such that no solution exists for  $s < s_c$  and first solution is found lower than second solution.

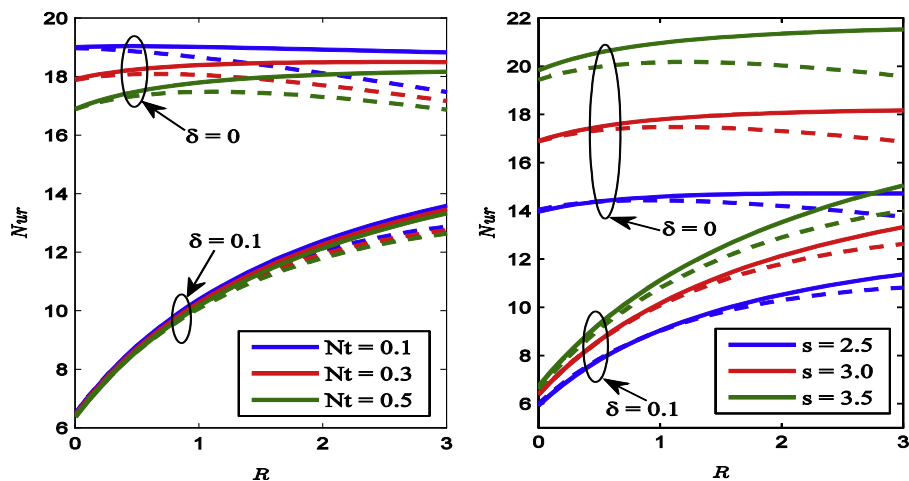
The variation of the Nusselt number with  $R$  for various values of  $Nt$  and  $s$  is shown in Fig. 9 in the presence and absence of thermal slip parameter  $\delta$ . The Dual solutions are captured such that first solution is always higher than second solution. As Nusselt number is ratio of convective and conductive heat transfer so for large Nusselt number, heat convection rises. The Nusselt number is decreasing with  $Nt$  and  $\delta$  but increasing with thermal radiation  $R$  and mass transfer parameter  $s$ .

Fig. 10 gives the effect of viscous dissipation parameter  $Ec$  (Eckert number, which controls the fluid flow), on the local Nusselt number for several values of Prandtl number  $Pr$  and Schmidt number  $Sc$ . It is observed that for both solutions, the local Nusselt number is decreasing, with  $Ec$  and  $Sc$  but increasing with  $Pr$ . Here it is interesting to see that the first solution is higher than second solution in the absence of viscous dissipation ( $Ec = 0$ ) while opposite trend is observed in the presence of viscous dissipation ( $Ec = 0.1, 0.2$ ).

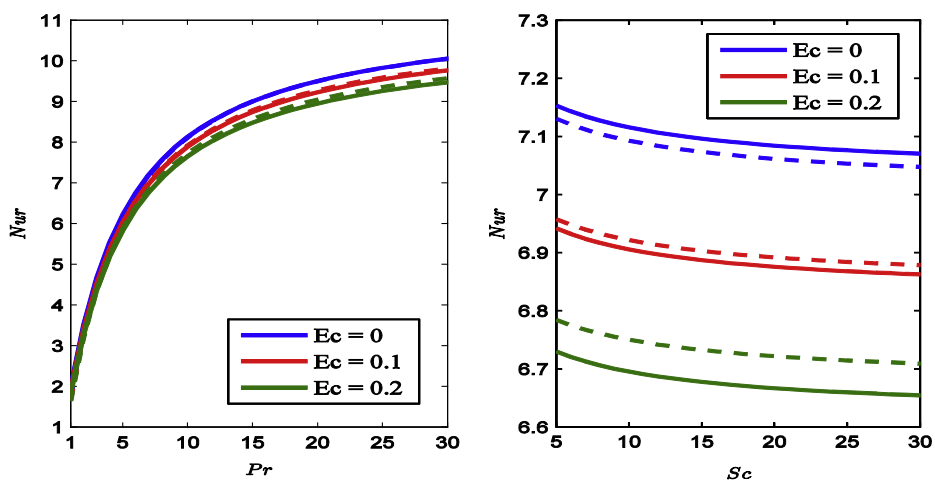
The influence of thermal radiation on temperature  $\theta(\eta)$  and nanoparticle volume fraction  $\phi(\eta)$  is displayed in Fig. 11. As the value of thermal radiation  $R$  increases, temperature and nanoparticle volume fraction increase. Moreover, temperature gradient and thermal boundary layer thickness decrease.

Further, the effect of nanofluid parameters (Brownian motion parameter  $Nb$  and thermophoresis parameter  $Nt$ ) on nanoparticle volume fraction has been investigated. The gradient of nanoparticle concentration at the surface is controlled passively by the product of temperature gradient and  $(-Nt/Nb)$  therefore nanoparticle concentration gradient increases with  $Nt$  and decreases with  $Nb$  for fixed temperature gradient. From Fig. 12 it can be observed that nanoparticle volume fraction is increasing with  $Nt$ , which is due to the fact that thermophoretic force takes away the fluid from the surface quickly, which leads to an increase in the concentration boundary layer thickness. On the other hand nanoparticle volume fraction decreases with an increasing value of  $Nb$  and concentration boundary layer thickness reduces.

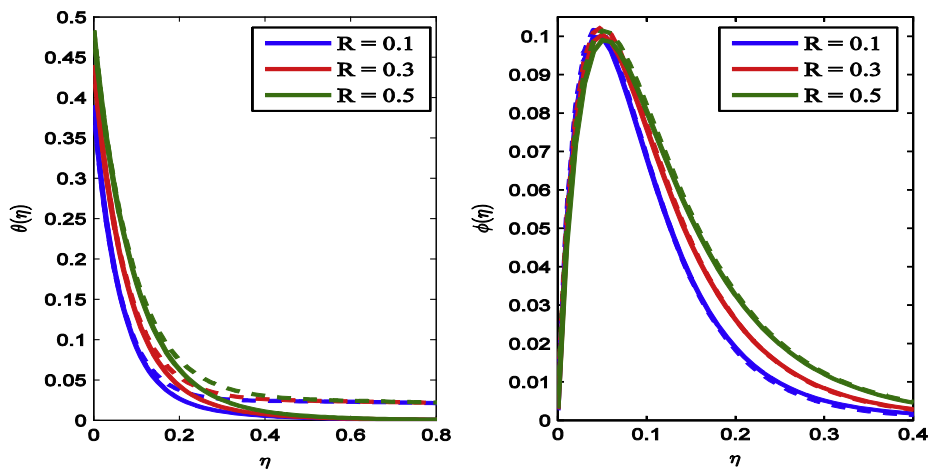




**Figure 9** The effect of thermophoresis parameter  $Nt$  and mass transfer parameter  $s$  on the Nusselt number with thermal radiation  $R$  for different values of thermal slip parameter  $\delta$ .



**Figure 10** The influence of Eckert number  $Ec$  on Nusselt number for different values of Prandtl number  $Pr$  and Schmidt number  $Sc$ .



**Figure 11** The effect of thermal radiation  $R$  on temperature  $\theta(\eta)$  and nanoparticle volume fraction  $\phi(\eta)$ .

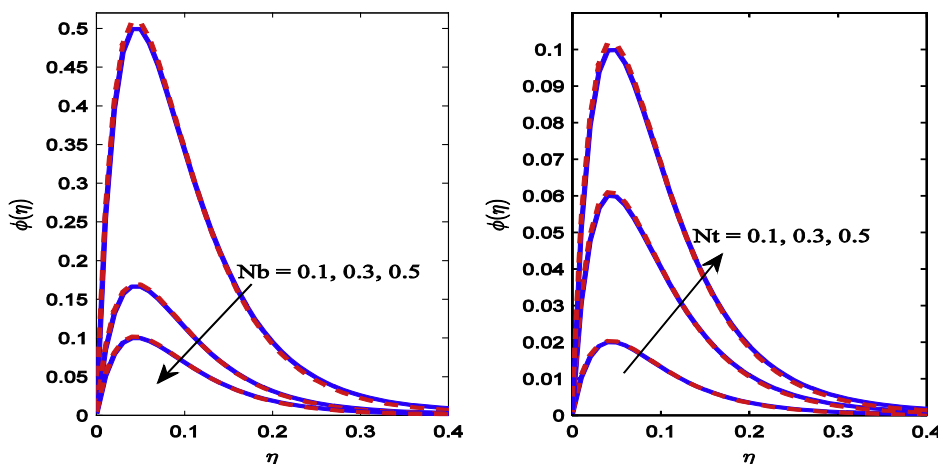


Figure 12 The effect of nanofluid parameters ( $Nb$  and  $Nt$ ) on nanoparticle concentration  $\phi(\eta)$ .

Table 4 The smallest eigenvalues  $\alpha$  for first and second solutions with different values of  $s, \chi, \lambda$  and  $\beta$ , while other parameters are fixed.

$s$	$\lambda = 0$		$s$	$\lambda = 0.1$			
	First solution	Second solution		First solution	Second solution		
2.2	0.4131	-0.3887	2.05	0.1808	-0.1766		
2.14	0.1635	-0.1602	2.04	0.1013	-0.1001		
2.13	0.0630	-0.0629	2.038	0.0759	-0.0757		
$\chi$	$\beta = 0.5$		$\chi$	$\beta = 1.5$			
	-3.07	0.2023		-0.1853	-2.15	0.6793	-0.6510
	-3.08	0.1522		-0.1430	-2.20	0.4890	-0.4758
	-3.085	0.1203		-0.1148	-2.22	-0.3783	-0.3780

Table 5 Numerical values of first and second solution (given in brackets) of  $\{-\theta'(0)\}$  for different values of  $M, \lambda, \delta, R$  and  $Nt$  for power-law shrinking sheet  $\chi = -1$  when other parameters are fixed.

$M$	$R$	$(\lambda, \delta)$	$Nt$		
			0.1	0.3	0.5
0.2	0.1	(0.1, 0.1)	6.189207	6.141767	6.092976
			(6.195208)	(6.149257)	(6.102025)
		(0.1, 0.2)	3.782973	3.771844	3.760436
			(3.779945)	(3.780431)	(3.769725)
(0.2, 0.1)	6.253965	6.206668	6.158027		
	(6.188265)	(6.142379)	(6.095217)		
0.2	0.1	(0.1, 0.1)	6.189207	6.141767	6.092976
			(6.195208)	(6.149257)	(6.102025)
		0.3	5.696319	5.647115	5.596775
			(5.691942)	(5.644108)	(5.595198)
0.5	5.274784	5.225663	5.175644		
	(5.259762)	(5.211896)	(5.163182)		
0	0.1	(0.1, 0.1)	6.189786	6.142357	6.093578
(6.202492)			(6.156475)	(6.109174)	
0.2	0.1	(0.1, 0.1)	6.189207	6.141767	6.092976
(6.195208)			(6.149257)	(6.102025)	
0.5	0.1	(0.1, 0.1)	6.186358	6.138862	6.090012
			(6.146766)	(6.101274)	(6.054522)

## 6. Conclusion

The numerical investigation has been carried out in this study to analyze the influence of governing over a stretching/shrinking sheet under the slip flow of nanofluid. The governing partial differential equations are formulated into nonlinear ordinary differential equations of non-dimensional parameters by using similarity variables and being solved numerically by RKF45 method with shooting technique. We have acquired interesting observations graphically for these pertinent parameters which are summarized below:

- The critical values ( $\chi_c$  and  $s_c$ ) are found for the existence of both first and second solutions.
- At the surface, Skin friction decreases whereas Nusselt number and nanoparticle volume fraction increase with increasing value of power-law parameter. Skin friction increases as velocity slip parameter increases.
- The Nusselt number decreases with an increase of thermophoresis parameter, thermal slip parameter, viscous dissipation and Schmidt number but increases with thermal radiation, mass transfer parameter and Prandtl number.
- It is observed that temperature and nanoparticle volume fraction enhance with thermal radiation. Moreover, nanoparticle volume fraction increases with thermophoresis parameter and decreases with Brownian motion parameter.

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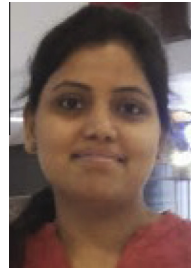
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