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Paraholomorphic B-manifold and its properties [☆]

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Abstract

This paper is concerned with problem of the geometry of B-manifolds. We give some properties of Riemannian curvature tensors of paraholomorphic B-manifolds. Finally, we consider some examples of paraholomorphic B-manifolds.

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1. Introduction

Let M_n be a Riemannian manifold with metric g , which is not necessarily positive definite. We denote by $\mathfrak{S}_q^p(M_n)$ the set of all tensor fields of type (p, q) on M_n . Manifolds, tensor fields and connections are always assumed to be differentiable and of class C^∞ .

An almost paracomplex manifold is an almost product manifold (M_n, φ) , $\varphi^2 = \text{id}$, such that the two eigenbundles T^+M_n and T^-M_n associated to the two eigenvalues $+1$ and -1 of φ , respectively, have the same rank. Note that the dimension of an almost paracomplex manifold is necessarily even. Considering the paracomplex structure φ , we obtain the following set of affinors on M_n : $\{\text{id}, \varphi\}$, $\varphi^2 = \text{id}$, which form a bases of a representation of the algebra of order 2 over the field of real numbers R , which is called the algebra of paracomplex (or double) numbers and is denoted by $R(j) = \{a_0 + a_1j \mid j^2 = 1; a_0, a_1 \in R\}$. Obviously, it is associative, commutative and it admits principal unit 1. The canonical bases of this algebra has the form $\{1, j\}$. Structural constants of an algebra are defined by the multiplication law of the base units of this algebra: $e_i e_j = C_{ij}^k e_k$. The components of C_{ij}^k are given by $C_{11}^1 = C_{12}^2 = C_{21}^2 = C_{22}^1 = 1$, all the others being zero, with respect to the canonical bases of $R(j)$.

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Consider $R(j)$ endowed with the usual topology of R^2 and a domain U of $R(j)$. Let

$$X = x^1 + jx^2$$

be a variable in $R(j)$, where x^i are real coordinates of a point of a certain domain U for $i = 1, 2$. Using two real-valued functions $f^i(x^1, x^2)$, $i = 1, 2$, we introduce a paracomplex function

$$F = f^1 + jf^2$$

of variable X . It is said to be paraholomorphic if we have

$$dF = F'(X) dX$$

for the differentials $dX = dx^1 + j dx^2$, $dF = df^1 + j df^2$ and the derivative $F'(X)$. The paraholomorphy of the function $F = f^1 + jf^2$ in the variable $X = x^1 + jx^2$ is equivalent to the fact that the Jacobian matrix $D = (\partial_k f^i)$ commutes with the matrix

$$C_2 = (C_{2j}^k) = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

(see [10, p. 87]). It follows that F is paraholomorphic if and only if f^1 and f^2 satisfy the para-Cauchy–Riemann equations:

$$\frac{\partial f^1}{\partial x^1} = \frac{\partial f^2}{\partial x^2}, \quad \frac{\partial f^1}{\partial x^2} = \frac{\partial f^2}{\partial x^1}.$$

For almost paracomplex structure the integrability is equivalent to the vanishing of the Nijenhuis tensor

$$N_\varphi(X, Y) = [\varphi X, \varphi Y] - \varphi[\varphi X, Y] - \varphi[X, \varphi Y] + [X, Y].$$

On the other hand, in order that an almost paracomplex structure be integrable, it is necessary and sufficient that we can introduce a torsion free linear connection such that $\nabla\varphi = 0$. A paracomplex manifold is an almost paracomplex manifold (M_{2k}, φ) such that the G-structure defined by the affinor field φ is integrable. We can give another-equivalent-definition of paracomplex manifold in terms of local homeomorphisms in the space $R^k(j) = \{(X^1, \dots, X^k) \mid X^i \in R(j), i = 1, \dots, k\}$ and paraholomorphic changes of charts in a way similar to [3] (for more details see [10] or [4]), i.e. a manifold M_{2k} with an integrable paracomplex structure φ is a real realization of the paraholomorphic manifold $M_k(R(j))$ over the algebra $R(j)$. Let $\overset{*}{t}$ be a paracomplex tensor field on $M_k(R(j))$. The real model of such a tensor field is a tensor field on M_{2k} of the same order that is independent of whether its vector or covector arguments is subject to the action of the affinor structure φ . Such tensor fields are said to be pure with respect to φ . They were studied by many authors (see, e.g., [5,8–10,12]). In particular, being applied to a $(0, q)$ -tensor field ω , the purity means that for any $X_1, \dots, X_q \in \mathfrak{S}_0^1(M_{2k})$, the following conditions should hold:

$$\omega(\varphi X_1, X_2, \dots, X_q) = \omega(X_1, \varphi X_2, \dots, X_q) = \dots = \omega(X_1, X_2, \dots, \varphi X_q).$$

We define an operator

$$\phi_\varphi : \mathfrak{S}_q^0(M_{2k}) \rightarrow \mathfrak{S}_{q+1}^0(M_{2k})$$

applied to the pure tensor field ω by [12]

$$(\phi_\varphi\omega)(X, Y_1, Y_2, \dots, Y_q) = (\varphi X)(\omega(Y_1, Y_2, \dots, Y_q)) - X(\omega(\varphi Y_1, Y_2, \dots, Y_q)) + \omega((L_{Y_1}\varphi)X, Y_2, \dots, Y_q) + \dots + \omega(Y_1, Y_2, \dots, (L_{Y_q}\varphi)X), \tag{1.1}$$

where L_Y denotes the Lie differentiation with respect to Y .

When φ is a paracomplex structure on M_{2k} and the tensor field $\phi_\varphi\omega$ vanishes, the paracomplex tensor field $\overset{*}{\omega}$ on $M_k(R(j))$ is said to be paraholomorphic [5]. Thus a paraholomorphic tensor field $\overset{*}{\omega}$ on $M_k(R(j))$ is realized on M_{2k} in the form of a pure tensor field ω , such that

$$(\phi_\varphi\omega)(X, Y_1, Y_2, \dots, Y_q) = 0 \tag{1.2}$$

for any $X, Y_1, \dots, Y_q \in \mathfrak{S}_0^1(M_n)$. Therefore such a tensor field ω on M_{2k} is also called paraholomorphic tensor field.

The main results of the present paper are the following ones: Almost paracomplex manifolds endowed with a paraholomorphic Riemannian metric g are the manifolds where the Levi-Civita connection of the metric parallelizes the almost paracomplex structure (Theorem 2). In that case, the Levi-Civita connection is also the Levi-Civita connection of the metric G given by $G(X, Y) = g(\varphi X, Y)$ (Theorem 5). Moreover, in such a manifold, the Riemannian curvature tensor is pure (Theorem 6).

2. Paraholomorphic B-manifold

A pure metric with respect to the almost paracomplex structure is a Riemannian metric g such that

$$g(\varphi X, Y) = g(X, \varphi Y) \tag{2.1}$$

for any $X, Y \in \mathfrak{S}_0^1(M_n)$. Such Riemannian metrics were studied in [11], where they were said to be *B-metrics*, since the metric tensor g with respect to the structure φ is B-tensor according to the terminology accepted in [10]. If (M_{2k}, φ) is an almost paracomplex manifold with B-metric, we say that (M_{2k}, φ, g) is an *almost B-manifold*. If φ is integrable, we say that (M_{2k}, φ, g) is an *B-manifold*.

In a B-manifold a B-metric is called a *paraholomorphic* if

$$(\phi_\varphi g)(X, Y, Z) = 0.$$

If (M_{2k}, φ, g) is a B-manifold with paraholomorphic B-metric, we say that (M_{2k}, φ, g) is a *paraholomorphic B-manifold* (in some papers, (almost) B-manifolds are simply (almost) paracomplex manifolds, as in [4]). Now we establish a formula for the B-metric for an almost B-manifold.

Theorem 1. *Let g be a B-metric of almost B-manifold. Then*

$$g(Z, (\nabla_Y \varphi)(X)) = g((\nabla_Y \varphi)(Z), X),$$

where ∇ denotes the operator of the Riemannian covariant derivative with respect to g .

Proof. By virtue of (2.1) and

$$Yg(Z, X) = g(\nabla_Y Z, X) + g(Z, \nabla_Y X),$$

from $Yg(\varphi Z, X) = Yg(Z, \varphi X)$, we have

$$g(\nabla_Y \varphi Z, X) + g(\varphi Z, \nabla_Y X) = g(\nabla_Y Z, \varphi X) + g(Z, \nabla_Y \varphi X)$$

or

$$g(\varphi Z, \nabla_Y X) - g(Z, \nabla_Y \varphi X) = g(\nabla_Y Z, \varphi X) - g(\nabla_Y \varphi Z, X)$$

and consequently

$$g(Z, \varphi(\nabla_Y X) - \nabla_Y \varphi X) = g(\varphi(\nabla_Y Z) - \nabla_Y \varphi Z, X)$$

from which by virtue of formula

$$(\nabla_Y \varphi)X = (\nabla \varphi)(X, Y) = \nabla_Y \varphi X - \varphi(\nabla_Y X) \tag{2.2}$$

we see that the proof is completed. \square

In some aspects, paraholomorphic B-manifolds are similar to Kahler manifolds. The following theorem is analogue to the next known result: An almost Hermitian manifold is Kahler if and only if the almost complex structure is parallel with respect to the Levi-Civita connection.

Theorem 2. *An almost B-manifold is paraholomorphic B-manifold if and only if the almost paracomplex structure is parallel with respect to the Levi-Civita connection ∇ .*

Proof. Putting $(g \circ \varphi)(X, Y) = g(\varphi X, Y)$, we get from (1.1)

$$\begin{aligned}
 (\phi_\varphi g)(X, Z_1, Z_2) &= (L_{\varphi X} g - L_X(g \circ \varphi))(Z_1, Z_2) + g(Z_1, \varphi L_X Z_2) - g(\varphi Z_1, L_X Z_2) \\
 &= (\varphi X)g(Z_1, Z_2) - g(\nabla_{\varphi X} Z_1 - \nabla_{Z_1} \varphi X, Z_2) - g(Z_1, \nabla_{\varphi X} Z_2 - \nabla_{Z_2} \varphi X) \\
 &\quad - Xg(\varphi Z_1, Z_2) + (g \circ \varphi)(\nabla_X Z_1 - \nabla_{Z_1} X, Z_2) - (g \circ \varphi)(Z_1, \nabla_X Z_2 - \nabla_{Z_2} X) \\
 &\quad + g(Z_1, \varphi(\nabla_X Z_2 - \nabla_{Z_2} X)) - g(\varphi Z_1, \nabla_X Z_2 - \nabla_{Z_2} X) \\
 &= (\varphi X)g(Z_1, Z_2) - Xg(\varphi Z_1, Z_2) - g(\nabla_{\varphi X} Z_1, Z_2) + g(\nabla_{Z_1} \varphi X, Z_2) \\
 &\quad - g(Z_1, \nabla_{\varphi X} Z_2) + g(Z_1, \nabla_{Z_2} \varphi X) + g(\varphi(\nabla_X Z_1), Z_2) - g(\varphi(\nabla_{Z_1} X), Z_2) \\
 &\quad + g(\varphi Z_1, \nabla_X Z_2) - g(\varphi Z_1, \nabla_{Z_2} X) + g(Z_1, \varphi(\nabla_X Z_2)) - g(Z_1, \varphi(\nabla_{Z_2} X)) \\
 &\quad - g(\varphi Z_1, \nabla_X Z_2) + g(\varphi Z_1, \nabla_{Z_2} X) \\
 &= (\varphi X)g(Z_1, Z_2) - Xg(\varphi Z_1, Z_2) - g(\nabla_{\varphi X} Z_1, Z_2) + g(\nabla_{Z_1} \varphi X, Z_2) \\
 &\quad - g(Z_1, \nabla_{\varphi X} Z_2) + g(Z_1, \nabla_{Z_2} \varphi X) + g(\varphi(\nabla_X Z_1), Z_2) - g(\varphi(\nabla_{Z_1} X), Z_2) \\
 &\quad + g(\varphi Z_1, \nabla_X Z_2) - g(Z_1, \varphi(\nabla_{Z_2} X)). \tag{2.3}
 \end{aligned}$$

Taking account of (2.2), we find

$$\begin{aligned}
 &g(\nabla_{Z_1} \varphi X, Z_2) - g(\varphi(\nabla_{Z_1} X), Z_2) + g(Z_1, \nabla_{Z_2} \varphi X) - g(Z_1, \varphi(\nabla_{Z_2} X)) \\
 &= g((\nabla \varphi)(X, Z_1), Z_2) + g(Z_1, (\nabla \varphi)(X, Z_2)). \tag{2.4}
 \end{aligned}$$

Substitution (2.4) into (2.3), (2.3) may be written as

$$\begin{aligned}
 (\phi_\varphi g)(X, Z_1, Z_2) &= (\varphi X)g(Z_1, Z_2) - Xg(\varphi Z_1, Z_2) + g((\nabla \varphi)(X, Z_1), Z_2) \\
 &\quad + g(Z_1, (\nabla \varphi)(X, Z_2)) - g(\nabla_{\varphi X} Z_1, Z_2) - g(Z_1, \nabla_{\varphi X} Z_2) \\
 &\quad + g(\varphi(\nabla_X Z_1), Z_2) + g(\varphi Z_1, \nabla_X Z_2). \tag{2.5}
 \end{aligned}$$

On the other hand, with respect to the Levi-Civita connection ∇ , we have

$$(\varphi X)g(Z_1, Z_2) - g(\nabla_{\varphi X} Z_1, Z_2) - g(Z_1, \nabla_{\varphi X} Z_2) = (\nabla_{\varphi X} g)(Z_1, Z_2) = 0 \tag{2.6}$$

and

$$\begin{aligned}
 &-Xg(\varphi Z_1, Z_2) + g(\varphi(\nabla_X Z_1), Z_2) + g(\varphi Z_1, \nabla_X Z_2) \\
 &= -Xg(\varphi Z_1, Z_2) + g((\nabla_X \varphi Z_1), Z_2) + g(\varphi Z_1, \nabla_X Z_2) - g((\nabla_X \varphi)Z_1, Z_2) \\
 &= -(\nabla_X g)(\varphi Z_1, Z_2) - g((\nabla_X \varphi)Z_1, Z_2) = -g((\nabla_X \varphi)Z_1, Z_2). \tag{2.7}
 \end{aligned}$$

By virtue of (2.6) and (2.7), (2.5) reduces to

$$(\phi_\varphi g)(X, Z_1, Z_2) = -g((\nabla_X \varphi)Z_1, Z_2) + g((\nabla_{Z_1} \varphi)X, Z_2) + g(Z_1, (\nabla_{Z_2} \varphi)X). \tag{2.8}$$

Similarly, we have

$$(\phi_\varphi g)(Z_2, Z_1, X) = -g((\nabla_{Z_2} \varphi)Z_1, X) + g((\nabla_{Z_1} \varphi)Z_2, X) + g(Z_1, (\nabla_X \varphi)Z_2). \tag{2.9}$$

The sufficiency follows easily from (2.8) (or (2.9)).

By virtue of Theorem 1 we find

$$(\phi_\varphi g)(X, Z_1, Z_2) + (\phi_\varphi g)(Z_2, Z_1, X) = 2g(X, (\nabla_{Z_2} \varphi)Z_2). \tag{2.10}$$

Now, putting $\phi_\varphi g = 0$ in (2.10), we find $\nabla \varphi = 0$ from which the necessity follows. Thus Theorem 2 is proved. \square

Corollary. *The almost paracomplex structure φ on almost B-manifold is integrable if $\phi_\varphi g = 0$.*

Remark. The leaves of the foliations defined by the paracomplex structure of a paraholomorphic B-manifold are totally geodesic submanifolds (see [6] or the book K. Yano and M. Kon [14, p. 420]). In the paper of A.M. Naveira [6] Riemannian almost product manifolds were classified.

Let (M_{2k}, φ, g) be an almost B-manifold. The associated B-metric of almost B-manifold is defined by

$$G(X, Y) = (g \circ \varphi)(X, Y) \tag{2.11}$$

for all vector fields X and Y on M_{2k} . One can easily prove that G is a metric, which is also called the twin metric of g (see [2]) and it plays a role similar to the Kahler form in Hermitian Geometry. We shall now apply the Tachibana operator to the pure Riemannian metric G

$$\begin{aligned} (\phi_\varphi G)(X, Y, Z) &= (L_{\varphi X}G - L_X(G \circ \varphi))(Y, Z) + G(Y, \varphi L_X Z) - G(\varphi Y, L_X Z) \\ &= (L_{\varphi X}(g \circ \varphi) - L_X((g \circ \varphi) \circ \varphi))(Y, Z) + (g \circ \varphi)(Y, \varphi L_X Z) - (g \circ \varphi)(\varphi Y, L_X Z) \\ &= ((L_{\varphi X}g) \circ \varphi + g \circ L_{\varphi X}\varphi - L_X(g \circ \varphi) \circ \varphi - (g \circ \varphi)L_X\varphi)(Y, Z) \\ &\quad + (g \circ \varphi)(Y, \varphi L_X Z) - (g \circ \varphi)(\varphi Y, L_X Z) \\ &= (L_{\varphi X}g - L_X(g \circ \varphi))(\varphi Y, Z) + g(\varphi Y, \varphi L_X Z) \\ &\quad - g(\varphi(\varphi Y), L_X Z) + (g \circ L_{\varphi X}\varphi - (g \circ \varphi)L_X\varphi)(Y, Z) \\ &= (\phi_\varphi g)(X, \varphi Y, Z) + g((L_{\varphi X}\varphi)Y, Z) - g(\varphi((L_X\varphi)Y), Z) \\ &= (\phi_\varphi g)(X, \varphi Y, Z) + g([\varphi X, \varphi Y] - \varphi[\varphi X, Y], Z) - g(\varphi[X, \varphi Y] - \varphi^2[X, Y], Z) \\ &= (\phi_\varphi g)(X, \varphi Y, Z) + g([\varphi X, \varphi Y] - \varphi[\varphi X, Y] - \varphi[X, \varphi Y] + \varphi^2[X, Y], Z) \\ &= (\phi_\varphi g)(X, \varphi Y, Z) + g(N_\varphi(X, Y), Z). \end{aligned} \tag{2.12}$$

Thus (2.12) implies the following:

Theorem 3. *In an almost B-manifold, we have*

$$\phi_\varphi G = (\phi_\varphi g) \circ \varphi + g \circ (N_\varphi).$$

From Theorems 2 and 3 we have

Theorem 4. *Almost B-manifold with condition $\phi_\varphi G = 0, N_\varphi \neq 0$ i.e. analogues of the almost Kahler manifolds, does not exist.*

Corollary. *The following conditions are equivalent:*

- (a) $\phi_\varphi g = 0;$
- (b) $\phi_\varphi G = 0.$

We denote by ∇_g the covariant differentiation of Levi-Civita connection of B-metric g . Then, we have

$$\nabla_g G = (\nabla_g g) \circ \varphi + g \circ (\nabla_g \varphi) = g \circ (\nabla_g \varphi)$$

which implies $\nabla_g G = 0$ by virtue of Theorem 2. Therefore we have

Theorem 5. *Let (M_{2k}, φ, g) be a paraholomorphic B-manifold. Then the Levi-Civita connection of B-metric g coincides with the Levi-Civita connection of associated B-metric G .*

3. Curvature tensors in a paraholomorphic B-manifold

Let R and S be the curvature tensors formed by g and G respectively, then for the paraholomorphic B-manifold we have $R = S$ by means of the Theorem 5.

Applying the Ricci’s identity to φ , we get

$$\varphi(R(X, Y)Z) = R(X, Y)\varphi Z \tag{3.1}$$

by virtue of $\nabla\varphi = 0$. Hence $R(X_1, X_2, X_3, X_4) = g(R(X_1, X_2)X_3, X_4)$ is pure with respect to X_3 and X_4 and also pure with respect to X_1 and X_2 :

$$\begin{aligned}
 R(X_1, X_2, \varphi X_3, X_4) &= g(R(X_1, X_2)\varphi X_3, X_4) \\
 &= g(\varphi(R(X_1, X_2)X_3), X_4) \\
 &= g(R(X_1, X_2)X_3, \varphi X_4) \\
 &= R(X_1, X_2, X_3, \varphi X_4).
 \end{aligned}$$

On the other hand, S being the curvature tensor formed by associated B-metric G , if we put $S(X_1, X_2, X_3, X_4) = G(S(X_1, X_2)X_3, X_4)$, then we have

$$S(X_1, X_2, X_3, X_4) = S(X_3, X_4, X_1, X_2). \tag{3.2}$$

Taking account of (1.1), (2.11), (3.1) and $R = S$, we find that

$$\begin{aligned}
 S(X_1, X_2, X_3, X_4) &= G(S(X_1, X_2)X_3, X_4) \\
 &= g(\varphi(S(X_1, X_2)X_3), X_4) \\
 &= g(S(X_1, X_2)X_3, \varphi X_4) \\
 &= g(R(X_1, X_2)X_3, \varphi X_4) \\
 &= R(X_1, X_2, X_3, \varphi X_4)
 \end{aligned}$$

and

$$\begin{aligned}
 S(X_3, X_4, X_1, X_2) &= G(S(X_3, X_4)X_1, X_2) \\
 &= g(\varphi(S(X_3, X_4)X_1), X_2) \\
 &= g(S(X_3, X_4)X_1, \varphi X_2) \\
 &= g(R(X_3, X_4)X_1, \varphi X_2) \\
 &= R(X_3, X_4, X_1, \varphi X_2) \\
 &= R(X_1, \varphi X_2, X_3, X_4).
 \end{aligned}$$

Thus Eq. (3.2) becomes

$$R(X_1, X_2, X_3, \varphi X_4) = R(X_1, \varphi X_2, X_3, X_4),$$

which shows that $R(X_1, X_2, X_3, X_4)$ is pure with respect to X_2 and X_4 . Therefore $R(X_1, X_2, X_3, X_4)$ is pure.

Thus we get

Theorem 6. *In a paraholomorphic B-manifold, the Riemannian curvature tensor of B-metric is pure.*

Since the Riemannian curvature tensor R is pure, we can apply the ϕ -operator to R . By similar devices (see proof of Theorem 2), we can prove that

$$(\phi_\varphi R)(X, Y_1, Y_2, Y_3, Y_4) = (\nabla_{\varphi X} R)(Y_1, Y_2, Y_3, Y_4) - (\nabla_X R)(\varphi Y_1, Y_2, Y_3, Y_4). \tag{3.3}$$

Using (3.1) and applying the Bianchi’s 2nd identity to (3.3), we get

$$\begin{aligned}
 (\phi_\varphi R)(X, Y_1, Y_2, Y_3, Y_4) &= g((\nabla_{\varphi X} R)(Y_1, Y_2, Y_3) - (\nabla_X R)(\varphi Y_1, Y_2, Y_3), Y_4) \\
 &= g((\nabla_{\varphi X} R)(Y_1, Y_2, Y_3) - \varphi((\nabla_X R)(Y_1, Y_2, Y_3)), Y_4) \\
 &= g(-(\nabla_{Y_1} R)(Y_2, \varphi X, Y_3) - (\nabla_{Y_2} R)(\varphi X, Y_1, Y_3) \\
 &\quad - \varphi((\nabla_X R)(Y_1, Y_2, Y_3)), Y_4).
 \end{aligned} \tag{3.4}$$

On the other hand, using $\nabla\varphi = 0$, we find

$$\begin{aligned}
 (\nabla_{Y_2} R)(\varphi X, Y_1, Y_3) &= \nabla_{Y_2}(R(\varphi X, Y_1, Y_3)) - R(\nabla_{Y_2}(\varphi X), Y_1, Y_3) - R(\varphi X, \nabla_{Y_2} Y_1, Y_3) - R(\varphi X, Y_1, \nabla_{Y_2} Y_3) \\
 &= (\nabla_{Y_2} \varphi)(R(X, Y_1, Y_3)) + \varphi(\nabla_{Y_2} R(X, Y_1, Y_3)) \\
 &\quad - R((\nabla_{Y_2} \varphi)X + \varphi(\nabla_{Y_2} X), Y_1, Y_3) - R(\varphi X, \nabla_{Y_2} Y_1, Y_3) - R(\varphi X, Y_1, \nabla_{Y_2} Y_3) \\
 &= \varphi(\nabla_{Y_2} R(X, Y_1, Y_3)) - \varphi(R(\nabla_{Y_2} X, Y_1, Y_3)) \\
 &\quad - \varphi(R(X, \nabla_{Y_2} Y_1, Y_3)) - \varphi(R(X, Y_1, \nabla_{Y_2} Y_3)) \\
 &= \varphi((\nabla_{Y_2} R)(X, Y_1, Y_3)).
 \end{aligned}
 \tag{3.5}$$

Similarly

$$(\nabla_{Y_1} R)(Y_2, \varphi X, Y_3) = \varphi((\nabla_{Y_1} R)(Y_2, X, Y_3)).
 \tag{3.6}$$

Substituting (3.5) and (3.6) in (3.4) and using again the Bianchi’s 2nd identity, we obtain

$$\begin{aligned}
 (\phi_\varphi R)(X, Y_1, Y_2, Y_3, Y_4) &= g(-\varphi((\nabla_{Y_1} R)(Y_2, X, Y_3)) - \varphi((\nabla_{Y_2} R)(X, Y_1, Y_3)) - \varphi((\nabla_X R)(Y_1, Y_2, Y_3)), Y_4) \\
 &= -g(\varphi(\sigma\{(\nabla_X R)(Y_1, Y_2\}, Y_3)), Y_4) \\
 &= 0,
 \end{aligned}$$

where σ denotes the cyclic sum with respect to X, Y_1 and Y_2 . Therefore we have

Theorem 7. *In a paraholomorphic B-manifold, the Riemannian curvature tensor field is paraholomorphic tensor field.*

4. Examples

Examples 1. We suppose that the manifold M_{2n} is the tangent bundle $\pi : T(V_n) \rightarrow V_n$ of a Riemannian manifold V_n . If x^i are local coordinates on V_n , then x^i together with the fibre coordinates $x^{\bar{i}} = y^i, \bar{i} = n + 1, \dots, 2n$, form local coordinates on $T(V_n)$.

A tensor field of type $(0, q)$ on $T(V_n)$ completely determined by its action on all vector fields $\tilde{X}_i, i = 1, 2, \dots, q$, which are of the form ${}^V X$ (vertical lift) or ${}^H X$ (horizontal lift) [13, p. 101]:

$${}^V X = X^i \frac{\partial}{\partial x^i}, \quad {}^H X = X^i \frac{\partial}{\partial x^i} - y^s \Gamma_{sh}^i X^h \frac{\partial}{\partial x^{\bar{i}}}.$$

Therefore, we define the Sasakian metric ${}^S g$ on $T(V_n)$ by

$$\begin{cases}
 {}^S g({}^H X, {}^H Y) = {}^V(g(X, Y)), \\
 {}^S g({}^V X, {}^V Y) = {}^V(g(X, Y)), \\
 {}^S g({}^V X, {}^H Y) = 0,
 \end{cases}
 \tag{4.1}$$

for any $X, Y \in \mathfrak{S}_0^1(V_n)$. ${}^S g$ has local components

$${}^S g = \begin{pmatrix} g_{ji} + g_{ts} y^k y^l \Gamma_{kj}^t \Gamma_{li}^s & y^k \Gamma_{kj}^s g_{si} \\ y^k \Gamma_{ki}^s g_{js} & g_{ji} \end{pmatrix}$$

with respect to the induced coordinates $(x^i, x^{\bar{i}})$ in $T(V_n)$, where Γ_{ij}^k are components of Levi-Civita connection ∇_g in V_n .

The diagonal lift ${}^D \varphi$ in $T(V_n)$ is defined by

$$\begin{cases}
 {}^D \varphi {}^H X = {}^H(\varphi X), \\
 {}^D \varphi {}^V X = -{}^V(\varphi X),
 \end{cases}
 \tag{4.2}$$

for any $X \in \mathfrak{S}_0^1(V_n)$ and $\varphi \in \mathfrak{S}_1^1(M_n)$. The diagonal lift ${}^D I$ of the identity tensor field $I \in \mathfrak{S}_1^1(M_n)$ has the components

$${}^D I = \begin{pmatrix} \delta_i^j & 0 \\ -2y^t \Gamma_{ti}^j & -\delta_i^j \end{pmatrix}$$

with respect to the induced coordinates and satisfies $(DI)^2 = I_{T(V_n)}$. Thus DI is an almost paracomplex structure determining the horizontal distribution and the distribution consisting of the tangent planes to fibres.

We put

$$A(\tilde{X}, \tilde{Y}) = {}^Sg(DI\tilde{X}, \tilde{Y}) - {}^Sg(\tilde{X}, DI\tilde{Y}).$$

If $A(\tilde{X}, \tilde{Y}) = 0$ for all vector fields \tilde{X} and \tilde{Y} which are of the form ${}^VX, {}^VY$ or ${}^HX, {}^HY$, then $A = 0$. We have by virtue of $DI{}^VX = -{}^VX, DI{}^HX = {}^HX$ (4.1) and (4.2)

$$\begin{aligned} A({}^VX, {}^VY) &= {}^Sg(-{}^VX, {}^VY) - {}^Sg({}^VX, -{}^VY) = 0, \\ A({}^VX, {}^HY) &= {}^Sg(-{}^VX, {}^HY) - {}^Sg({}^VX, {}^HY) = 0, \\ A({}^HX, {}^VY) &= {}^Sg({}^HX, {}^VY) - {}^Sg({}^HX, -{}^VY) = 0, \\ A({}^HX, {}^HY) &= {}^Sg({}^HX, {}^HY) - {}^Sg({}^HX, {}^HY) = 0, \end{aligned}$$

i.e. Sg is B-metric with respect to DI .

We hence have:

Theorem 8. $(T(V_n), DI, {}^Sg)$ is an almost B-manifold.

Using the properties of ${}^VX, {}^HX$ and $\gamma R(X, Y) = y^s R^k_{ijs} X^i Y^j \frac{\partial}{\partial x^k}$, we have

$$\begin{aligned} (\phi_{DI} {}^Sg)({}^VX, {}^HY, {}^HZ) &= -2({}^Sg^V(\nabla_Y X), {}^HZ) + {}^Sg({}^HY, {}^V(\nabla_Z X)) = 0, \\ (\phi_{DI} {}^Sg)({}^VX, {}^HY, {}^VZ) &= -2{}^Sg({}^HY, [{}^VZ, {}^VX]) = 0, \\ (\phi_{DI} {}^Sg)({}^VX, {}^VY, {}^HZ) &= -2{}^Sg([{}^VY, {}^VX], {}^HZ) = 0, \\ (\phi_{DI} {}^Sg)({}^VX, {}^VY, {}^VZ) &= 0, \\ (\phi_{DI} {}^Sg)({}^HX, {}^HY, {}^HZ) &= 0, \\ (\phi_{DI} {}^Sg)({}^HX, {}^VY, {}^VZ) &= 2^V((\nabla_X g)(Y, Z)) = 0, \\ (\phi_{DI} {}^Sg)({}^HX, {}^HY, {}^VZ) &= -2{}^Sg(\gamma R(Y, X), {}^VZ), \\ (\phi_{DI} {}^Sg)({}^HX, {}^VY, {}^HZ) &= -2{}^Sg({}^VY, \gamma R(Z, X)). \end{aligned}$$

Therefore we have

Theorem 9. The almost B-manifold $(T(V_n), DI, {}^Sg)$ is paraholomorphic if and only if V_n is locally Euclidean.

Examples 2. Let now M_n be the locally product Riemannian manifold with integrable almost product structure

$$\varphi = \begin{pmatrix} \delta^i_j & 0 \\ 0 & -\delta^{\bar{i}}_{\bar{j}} \end{pmatrix}, \quad i, j = 1, \dots, k, \bar{i}, \bar{j} = k + 1, \dots, n,$$

and let $n = 2k$. Then the paracomplex manifold M_{2k} , admit a structure of B-manifold:

$$g = \begin{pmatrix} g_{ij} & 0 \\ 0 & g_{\bar{i}\bar{j}} \end{pmatrix}, \quad g_{ij} = g_{ij}(x^t, x^{\bar{t}}), \quad g_{\bar{i}\bar{j}} = g_{\bar{i}\bar{j}}(x^t, x^{\bar{t}}).$$

Suppose that the metric of the locally product Riemannian manifold M_{2k} has the form

$$ds^2 = g_{ij}(x^t) dx^i dx^j + g_{\bar{i}\bar{j}}(x^{\bar{t}}) dx^{\bar{i}} dx^{\bar{j}}, \quad i, j, t = 1, \dots, k, \bar{i}, \bar{j}, \bar{t} = k + 1, \dots, 2k,$$

that is $g_{ij}(x)$ are functions of x^t only, $g_{\bar{i}\bar{j}} = 0$, and $g_{\bar{i}\bar{j}}(x)$ are functions of $x^{\bar{t}}$ only, then we call the manifold a locally decomposable Riemannian manifold. A necessary and sufficient condition for a locally product Riemannian manifold to be a locally decomposable Riemannian manifold is that $\nabla_g \varphi = 0$ [14, p. 420]. Then from Theorem 2 we have

Theorem 10. A locally decomposable Riemannian manifold M_{2k} is a paraholomorphic B-manifold.

Examples 3. Let (M_{2k}, ω) be a symplectic manifold and let D be a Lagrangian distribution, which is a k -dimensional distribution having $\omega/D = 0$. Then, M may be endowed with an almost B-structure.

First of all, we shall prove that there exist a transversal Lagrangian distribution. Taking into account that (M, ω) is an almost symplectic manifold one can find (see [1] or [7]) an almost Hermitian structure (J, G) on M such that $\omega(X, Y) = G(JX, Y)$. Let D^\perp the G -orthogonal distribution to D . Then one has:

- (1) If $X, Y \in D$, then $G(JX, Y) = \omega(X, Y) = 0$, thus proving that $J(D) = D^\perp$.
- (2) D^\perp is a Lagrangian distribution, because $\omega(JX, JY) = \omega(X, Y)$, for all $X, Y \in \mathfrak{S}_0^1(M_n)$.

Let F be the almost product structure defined by D and D^\perp , i.e., $F^+ = D$ and $F^- = D^\perp$. Then, one easily check that $J \circ F = -F \circ J$. Moreover, one can prove that (M, F, G) is a Riemannian almost product manifold:

If $X \in \mathfrak{S}_0^1(M_n)$, then $X = X_1 + X_2$, where $X_1 \in F^+ = D$ and $X_2 \in F^- = D^\perp = J(D)$, and one can write $X_2 = J(X_3)$, with $X_3 \in F^+$. Using this notation we obtain:

$$G(X, Y) = G(X_1 + JX_3, Y_1 + JY_3) = G(X_1, Y_1) + G(JX_3, JY_3) = G(X_1, Y_1) + G(X_3, Y_3)$$

and

$$G(FX, FY) = G(X_1 - JX_3, Y_1 - JY_3) = G(X_1, Y_1) + G(JX_3, JY_3) = G(X_1, Y_1) + G(X_3, Y_3)$$

thus proving $G(X, Y) = G(FX, FY)$.

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