# Ideals of quasi-symmetric functions and super-covariant polynomials for $\mathcal{S}_{n}$ 

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#### Abstract

The aim of this work is to study the quotient ring $\mathbf{R}_{n}$ of the ring $\mathbb{Q}\left[x_{1}, \ldots, x_{n}\right]$ over the ideal $\mathcal{J}_{n}$ generated by non-constant homogeneous quasi-symmetric functions. This article is a sequel of Aval and Bergeron (Proc. Amer. Math. Soc., to appear), in which we investigated the case of infinitely many variables. We prove here that the dimension of $\mathbf{R}_{n}$ is given by $C_{n}$, the $n$th Catalan number. This is also the dimension of the space $\mathbf{S H}_{n}$ of super-covariant polynomials, defined as the orthogonal complement of $\mathcal{J}_{n}$ with respect to a given scalar product. We construct a basis for $\mathbf{R}_{n}$ whose elements are naturally indexed by Dyck paths. This allows us to understand the Hilbert series of $\mathbf{S H}_{n}$ in terms of number of Dyck paths with a given number of factors.


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## 1. Introduction

We study, in this paper, a natural analog of the space $\mathbf{H}_{n}$ of covariant polynomials of $\mathcal{S}_{n}$. Let $X$ denote the $n$ variables $x_{1}, \ldots, x_{n}$ and $\mathbb{Q}[X]$ denote the ring of polynomials in the variables $X$. Let $\mathcal{I}_{n}$ denote the ideal of $\mathbb{Q}[X]$ generated by all

[^0]symmetric polynomials with no constant term. That is
$$
\mathcal{I}_{n}=\left\langle h_{k}(X), k>0\right\rangle,
$$
where $h_{k}(X)$ is the $k$ th homogeneous symmetric polynomials in the variables $X$ (cf. $[12])$. We consider the following scalar product on $\mathbb{Q}[X]$ :
\[

$$
\begin{equation*}
\langle P, Q\rangle=\left.P(\partial X) Q(X)\right|_{X=0}, \tag{1.1}
\end{equation*}
$$

\]

where $\partial X$ stands for $\partial x_{1}, \ldots, \partial x_{n}$ and in the same spirit $X=0$ stands for $x_{1}=\cdots=$ $x_{n}=0$. The space $\mathbf{H}_{n}$ is defined as the orthogonal complement, denoted by $\mathcal{I}_{n}^{\perp}$, of the ideal $\mathcal{I}_{n}$ in $\mathbb{Q}[X]$.

Equivalently (cf. [6, Proposition I.2.3]), covariant polynomials (also known as $\mathcal{S}_{n}$ harmonic polynomials) can be defined as polynomials $P$ such that $Q(\partial X) P=0$, for any symmetric polynomial $Q$ with no constant term. Since elements of $\mathbf{H}_{n}$ satisfy the Laplace equation

$$
\left(\partial x_{1}^{2}+\cdots+\partial x_{n}^{2}\right) P=\Delta P=0
$$

every covariant polynomial is also harmonic.
Classical results $[1,16]$ state that the space $\mathbf{H}_{n}$ affords a graded $\mathcal{S}_{n}$-module structure and is isomorphic (as a representation of $\mathcal{S}_{n}$ ) to the left regular representation. Furthermore, as a graded $\mathcal{S}_{n}$-module, $\mathbf{H}_{n}$ is isomorphic to the quotient

$$
Q_{n}=\mathbb{Q}[X] / \mathcal{I}_{n} .
$$

The space $Q_{n}$ appears naturally in other contexts; for instance, as the cohomology ring of the variety of complete flags [5]. The discussion above implies that

$$
\begin{equation*}
\operatorname{dim} \mathbf{H}_{n}=n!. \tag{1.2}
\end{equation*}
$$

Part of the interesting results surrounding the study of $\mathbf{H}_{n}$ involve the fact that it can also be described as the linear span of all partial derivatives of the Vandermonde determinant. This is a special case of a general result for finite groups generated by reflections [16].

By analogy, we consider here the space $\mathbf{S H}_{n}=\mathcal{J}_{n}^{\perp}$ of super-covariant polynomials, where $\mathcal{J}_{n}$ is the idea generated by quasi-symmetric polynomials with no constant term. Since the ring of symmetric polynomials is a subring of the ring of quasisymmetric polynomials, we have $\mathcal{I}_{n} \subseteq \mathcal{J}_{n}$ hence $\mathcal{J}_{n}^{\perp} \subseteq \mathcal{I}_{n}^{\perp}$, thus

$$
\mathbf{S H}_{n} \subseteq \mathbf{H}_{n},
$$

which justifies the terminology. Quasi-symmetric polynomials were introduced by Gessel in 1984 [8] and have since appeared as a crucial tool in many interesting algebraico-combinatorial contexts (cf. [4,7,13-15]).

As in the corresponding symmetric setup, we have a graded isomorphism

$$
\begin{equation*}
\mathbf{S H}_{n} \simeq \mathbf{R}_{n}=\mathbb{Q}[X] / \mathcal{J}_{n} \tag{1.3}
\end{equation*}
$$

and the approach used in the following work concentrates on this alternate description. We construct a basis of $\mathbf{R}_{n}$ by giving an explicit set of monomial representatives. This set is naturally indexed by Dyck paths of length $n$, hence we obtain the following main theorem.

Theorem 1.1. The dimension of $\mathbf{S H}_{n}$ is given $y$ the well-known Catalan numbers:

$$
\begin{equation*}
\operatorname{dim} \mathbf{S H}_{n}=\operatorname{dim} \mathbf{R}_{n}=C_{n}=\frac{1}{n+1}\binom{2 n}{n} \tag{1.4}
\end{equation*}
$$

In fact, taking into account the grading (with respect to degree), we have the Hilbert series

$$
\begin{equation*}
\sum_{k=0}^{n-1} \operatorname{dim} \mathbf{S} \mathbf{H}_{n}^{(k)} t^{k}=\sum_{k=0}^{n-1} \frac{n-k}{n+k}\binom{n+k}{k} t^{k} \tag{1.5}
\end{equation*}
$$

The article contains five section. In Section 2 we recall useful definitions and basic properties. In Section 3 we construct a family $\mathcal{G}$ of generators for the ideal $\mathcal{J}_{n}$ and state useful properties of this set. Section 4 is devoted to the proof of the first part of Theorem 1.1. We construct an explicit basis for $\mathbf{R}_{n}$ which allows us in Section 5 to obtain the Hilbert series of $\mathbf{S H}_{n}$.

Before we begin, let us remark that Hivert [9] has developed an action of the Hecke algebra on $\mathbb{Q}[X]$ for which a polynomial is invariant if and only if it is quasisymmetric. One way to reformulate his result is to consider the generators $e_{i}=\frac{q-T_{i}}{(1+q)}$ of the Hecke algebra, where $T_{i}$ are the standard generators and $q$ is an arbitrary parameter. Then

$$
\begin{equation*}
e_{i} e_{i \pm 1} e_{i}-\frac{q}{(1+q)^{2}} e_{i} \tag{1.6}
\end{equation*}
$$

acts, via Hivert's action, as zero on the polynomial ring and generates the kernel of this action. Hence, the Temperley-Lieb algebra $T L_{n}(q)$ (cf. [10]) classically defined as the quotient of the Hecke algebra by relation (1.6), faithfully acts on polynomials. The algebra $T L_{n}(q)$ is known to have dimension equal to $C_{n}$ and at $q=1$ this is a quotient of the symmetric group algebra. The quasi-symmetric polynomials are thus identified as the polynomial invariants $\mathbb{Q}[X]^{T L_{n}}$ of the algebra $T L_{n}=T L_{n}(1)$.

The action of Hivert is not compatible with multiplication and does not preserve the ideal $\mathcal{J}_{n}$, yet there are some striking facts related to $T L_{n}$-invariants. The quasisymmetric functions are closed under multiplication [14], in particular they form a
subring of $\mathbb{Q}[X]$. Moreover, if we let $n$ go to infinity, there is a graded Hopf algebra structure on quasi-symmetric functions [8] that is free and cofree with cogenerators in every degree [13]. That is, the graded dual is isomorphic to a free noncommutative Hopf algebra $\mathbb{Q}\left\langle h_{1}, h_{2}, \ldots\right\rangle$ where $\operatorname{deg}\left(h_{k}\right)=k$. Moreover, in this paper, we show that the space $R_{n}$ of $T L_{n}$-covariants has dimension equal to $C_{n}=$ $\operatorname{dim}\left(T L_{n}\right)$.

These facts are very similar to the classical theory of group invariants [16]. Unfortunately the analogy is incomplete as Hivert's action does not induce an action on $R_{n}$. This raises new open questions for future investigation: how can we explain that $\operatorname{dim}\left(R_{n}\right)=\operatorname{dim}\left(T L_{n}\right)$ ?

## 2. Basic definitions

A composition $\alpha=\left(\alpha_{1}, \alpha_{2}, \ldots, \alpha_{k}\right)$ of a positive integer $d$ is an ordered list of positive integers $(>0)$ whose sum is $d$. We denote this by $\alpha \models d$ and also say that $\alpha$ is a composition of size $d$ and denote this by $|\alpha|$. The integers $\alpha_{i}$ are the parts of $\alpha$, and the length $\ell(\alpha)$ is set to be the number of parts of $\alpha$. We denote by 0 the unique empty composition of size $d=0$.

There is a natural one-to-one correspondence between compositions of $d$ and subsets of $\{1,2, \ldots, d-1\}$. Let $S=\left\{a_{1}, a_{2}, \ldots, a_{k}\right\}$ be such a subset, with $a_{1}<\cdots<a_{k}$, then the composition associated to $S$ is $\alpha_{d}(S)=\left(a_{1}-a_{0}, a_{2}-\right.$ $\left.a_{1}, \ldots, a_{k+1}-a_{k}\right)$, where we set $a_{0}:=0$ and $a_{k+1}:=d$. We denote by $D(\alpha)$ the set associated to $\alpha$ through this correspondence. For compositions $\alpha$ and $\beta$, we say that $\beta$ is a refinement of $\alpha$, if $D(\alpha) \subset D(\beta)$, and denote this by $\beta \succcurlyeq \alpha$.

We use vector notation for monomials. More precisely, for $v=\left(v_{1}, \ldots, v_{n}\right) \in \mathbb{N}^{n}$, we denote $X^{v}$ the monomial

$$
\begin{equation*}
x_{1}^{v_{1}} x_{2}^{v_{2}} \cdots x_{n}^{v_{n}} \tag{2.1}
\end{equation*}
$$

For a polynomial $P \in \mathbb{Q}[X]$, we further denote $\left[X^{\nu}\right] P(X)$ as the coefficient of the monomial $X^{v}$ in $P(X)$.

For a vector $v \in \mathbb{N}^{n}$, let $c(v)$ represent the composition obtained by erasing zero (if any) in $v$. A polynomial $P \in \mathbb{Q}[X]$ is said to be quasi-symmetric if and only if, for any $v$ and $\mu$ in $\mathbb{N}^{n}$, we have

$$
\left[X^{v}\right] P(X)=\left[X^{\mu}\right] P(X)
$$

whenever $c(v)=c(\mu)$. The space of quasi-symmetric polynomials in $n$ variables is denoted by $Q s y m_{n}$. The space $Q s y m_{n}^{(d)}$ of homogeneous quasi-symmetric polynomials of degree $d$ admits as linear basis the set of monomial quasi-symmetric polynomials indexed by compositions of $d$. More precisely, for each composition $\alpha$
of $d$ with at most $n$ parts, we set

$$
\begin{equation*}
M_{\alpha}=\sum_{c(v)=\alpha} X^{v} . \tag{2.2}
\end{equation*}
$$

For the 0 composition, we set $M_{0}=1$. Another important linear basis is that of the fundamental quasi-symmetric polynomials (cf. [8]):

$$
\begin{equation*}
F_{\alpha}=\sum_{\beta \succcurlyeq \alpha} M_{\beta} \tag{2.3}
\end{equation*}
$$

with $\alpha \models n$ and $\ell(\alpha) \leqslant n$. For example, with $n=4$,

$$
\begin{aligned}
F_{21}\left(x_{1}, x_{2}, x_{3}, x_{4}\right)= & M_{21}\left(x_{1}, x_{2}, x_{3}, x_{4}\right)+M_{111}\left(x_{1}, x_{2}, x_{3}, x_{4}\right) \\
= & x_{1}^{2} x_{2}+x_{1}^{2} x_{3}+x_{1}^{2} x_{4}+x_{2}^{2} x_{3}+x_{2}^{2} x_{4}+x_{3}^{2} x_{4} \\
& +x_{1} x_{2} x_{3}+x_{1} x_{2} x_{4}+x_{1} x_{3} x_{4}+x_{2} x_{3} x_{4} .
\end{aligned}
$$

Part of the interest of fundamental quasi-symmetric functions comes from the following properties. The first is trivial, but very useful and the second comes from the theory of $P$-partitions [14,15].

Proposition 2.1. For $\alpha=\left(\alpha_{1}, \alpha_{2}, \ldots, \alpha_{k}\right) \models d$,

$$
F_{\alpha}(X)= \begin{cases}x_{1} F_{\left(\alpha_{1}-1, \alpha_{2}, \ldots, \alpha_{k}\right)}(X)+F_{\alpha}\left(x_{2}, \ldots, x_{n}\right) & \text { if } \alpha_{1}>1  \tag{2.4}\\ x_{1} F_{\left(\alpha_{2}, \alpha_{3}, \ldots, \alpha_{k}\right)}\left(x_{2}, \ldots, x_{n}\right)+F_{\alpha}\left(x_{2}, \ldots, x_{n}\right) & \text { if } \alpha_{1}=1\end{cases}
$$

Let $u=u_{1} \cdots u_{l} \in \mathcal{S}_{\ell}$ and $v=v_{1} \cdots v_{m} \in \mathcal{S}_{[\ell+1, \ell+m]}$. Let $u w v$ denote the set of shuffles of the words $u$ and $v$, i.e. $u w v$ is the set of all permutations $w$ of $\ell+m$ such that $u$ and $v$ are subwords of $w$. In particular $u w v$ contains $\binom{\ell+m}{m}$ permutations. Let $\mathcal{D}(u)=$ $\left\{i, u_{i}>u_{i+1}\right\}$ denote the descent set of $u$. If $\beta$ and $\gamma$ are the two compositions such that $D(\beta)=\mathcal{D}(u)$ and $D(\gamma)=D(v)$, then

Proposition 2.2 (Stanley [15, Exercise 7.93]).

$$
\begin{equation*}
F_{\beta} F_{\gamma}=\sum_{w \in w_{w}} F_{\alpha_{\ell+m}(\mathcal{D}(w))} . \tag{2.5}
\end{equation*}
$$

In (2.1), the monomials are in correspondence with vectors $v \in \mathbb{N}^{n}$. Just as for compositions, the size $v_{1}+\cdots+v_{n}$ of $v$ is denoted by $|v|$. It is also convenient to denote by $\ell(v)$ the position of its last non-zero component. As usual, $v+\mu$ is the componentwise addition of vectors.

For ease of reading, we reserve the use of $\alpha, \beta$ and $\gamma$ to represent compositions, and the other Greek letters to represent vectors. We use the same symbol $\alpha$ for both the composition $\left(\alpha_{1}, \ldots, \alpha_{\ell}\right)$ and the word $\alpha_{1} \cdots \alpha_{\ell}$, likewise for vectors. In general, the length of vectors (or number of variables) is fixed and equal to $n$. If $w$ is a word of integers (that is an element of $\mathbb{N}^{k}$ for $0 \leqslant k \leqslant n$ ) we denote by $w 0^{*}=w 0^{n-k}$ the vector whose first $k$ parts are the letters of $w$, to which are added $n-k$ zeros at the end. If $u=u_{1} \cdots u_{k}$ and $v=v_{1} \cdots v_{m}$ are words of integers, the word

$$
u v:=u_{1} \cdots u_{k} v_{1} \cdots v_{m}
$$

is the concatenation of $u$ and $v$.
We next associate to any vector $v$ a path $\pi(v)$ in the $\mathbb{N} \times \mathbb{N}$ plane with steps going north or east as follows. If $v=\left(v_{1}, \ldots, v_{n}\right)$, the path $\pi(v)$ is

$$
\begin{aligned}
(0,0) & \rightarrow\left(v_{1}, 0\right) \rightarrow\left(v_{1}, 1\right) \rightarrow\left(v_{1}+v_{2}, 1\right) \rightarrow\left(v_{1}+v_{2}, 2\right) \rightarrow \cdots \\
& \rightarrow\left(v_{1}+\cdots+v_{n}, n-1\right) \rightarrow\left(v_{1}+\cdots+v_{n}, n\right)
\end{aligned}
$$

For example the path associated to $v=(2,1,0,3,0,1)$ is


Observe that the height of the path is always $n$, whereas its width is $|v|$.
We distinguish two kinds of paths, thus two kinds of vectors, with respect to their "behavior" with respect to the diagonal $y=x$. If the path remains above the diagonal, we call it a Dyck path, and say that the corresponding vector is Dyck. If not, we say that the path (or equivalently the associated vector) is transdiagonal. For example $\eta=(0,0,1,2,0,1)$ is Dyck and $\varepsilon=(0,2,1,0,2,2)$ is transdiagonal.


Observe that $v=v_{1} \cdots v_{n}$ is transdiagonal if and only if there exists $1 \leqslant m \leqslant n$ such that

$$
\begin{equation*}
m<v_{1}+\cdots+v_{m} \tag{2.6}
\end{equation*}
$$

Recall that the classical lexicographic order, on monomials of same degree, is

$$
\begin{equation*}
X^{v} \geqslant_{\text {lex }} X^{\mu} \quad \text { iff } \quad v \geqslant_{\text {lex }} \mu \tag{2.7}
\end{equation*}
$$

where we say that $v$ is lexicographically larger than $\mu, v>_{\text {lex }} \mu$, if the first non-zero part of the vector $v-\mu$ is positive. For example

$$
x_{1}^{3}>_{\operatorname{lex}} x_{1}^{2} x_{2}>_{\operatorname{lex}} x_{1} x_{2}^{2}>_{\operatorname{lex}} x_{2}^{3} \quad \text { since } \quad(3,0)>_{\operatorname{lex}}(2,1)>_{\operatorname{lex}}(1,2)>_{\operatorname{lex}}(0,3)
$$

## 3. The $\mathcal{G}$ basis

Following [2], we exploit relations (2.4) to construct a family

$$
\mathcal{G}=\left\{G_{\varepsilon}\right\} \subset \mathcal{J}_{n}
$$

indexed by vectors that are transdiagonal. For $\alpha$ any composition of $k \leqslant n$, the polynomial $G_{\varepsilon}$, with $\varepsilon:=\alpha 0^{*}$, is defined to be

$$
\begin{equation*}
G_{\varepsilon}:=F_{\alpha} . \tag{3.1}
\end{equation*}
$$

When $\alpha \neq 0$, the vector $\varepsilon=\alpha 0^{*}$ is clearly transdiagonal. For a general vector $\varepsilon$ (not of the form $\alpha 0^{*}$ ), the polynomial $G_{\varepsilon}$ is defined recursively in the following way. Let $\varepsilon=w 0 a \beta 0^{*}$ be the unique factorization of $\varepsilon$ such that $w$ is a word of $k-1$ nonnegative integers, $a>0$ is a positive integer, and $\beta$ is a composition (parts $>0$ ). Then we set

$$
\begin{equation*}
G_{\varepsilon}=G_{w a \beta 0^{*}}-x_{k} G_{w(a-1) \beta 0^{*}} \tag{3.2}
\end{equation*}
$$

By induction on the length of the indexing vectors, both terms on the right of (3.2) are well defined, and we have

- $\ell\left(w a \beta 0^{*}\right)=\ell\left(w(a-1) \beta 0^{*}\right)=\ell(\varepsilon)-1$;
- wa $\beta 0^{*}$ and $w(a-1) \beta 0^{*}$ are transdiagonal as soon as $\varepsilon$ is transdiagonal.

In fact, let $m$ be the first ordinate where $\pi(\varepsilon)$ crosses the diagonal, this is to say the smallest integer such that $m<\varepsilon_{1}+\cdots+\varepsilon_{m}$. Then the second assertion follows from

$$
\varphi_{1}+\cdots+\varphi_{m}>\psi_{1}+\cdots+\psi_{m}=\varepsilon_{1}+\cdots+\varepsilon_{m}-1>m-1,
$$

where $\varphi=w a \beta 0^{*}$ and $\psi=w(a-1) \beta 0^{*}$.
For example,

$$
\begin{aligned}
G_{1020}= & G_{1200}-x_{2} G_{1100} \\
= & F_{12}\left(x_{1}, x_{2}, x_{3}, x_{4}\right)-x_{2} F_{11}\left(x_{1}, x_{2}, x_{3}, x_{4}\right) \\
= & x_{1} x_{2}^{2}+x_{1} x_{3}^{2}+x_{1} x_{4}^{2}+x_{2} x_{3}^{2}+x_{2} x_{4}^{2}+x_{3} x_{4}^{2}+x_{1} x_{2} x_{3}+x_{1} x_{2} x_{4} \\
& +x_{1} x_{3} x_{4}+x_{2} x_{3} x_{4}-x_{2}\left(x_{1} x_{2}+x_{1} x_{3}+x_{1} x_{4}+x_{2} x_{3}+x_{2} x_{4}+x_{3} x_{4}\right) \\
= & x_{1} x_{3}^{2}+x_{1} x_{3} x_{4}+x_{1} x_{4}^{2}-x_{2}^{2} x_{3}-x_{2}^{2} x_{4}+x_{2} x_{3}^{2}+x_{2} x_{4}^{2}+x_{3} x_{4}^{2} .
\end{aligned}
$$

We observe in this example that the leading monomial (in lex order) of $G_{1020}$ is $X^{1020}=x_{1}^{1} x_{2}^{0} x_{3}^{2} x_{4}^{0}$. This holds in general for the $\mathcal{G}$ family as stated in the following proposition, for which all technical details can be found in [2].

Proposition 3.1 (Aval and Bergeron [2, Corollary 3.4]). The leading monomial $L M\left(G_{\varepsilon}\right)$ of $G_{\varepsilon}$ is $X^{\varepsilon}$.

## 4. Proof of the main theorem

We now give an explicit basis for the space $\mathbf{R}_{n}$ naturally indexed by Dyck paths. This proves the first part of Theorem 1.1.

Theorem 4.1. The set of monomials

$$
\begin{equation*}
\mathcal{B}_{n}=\left\{X^{\eta} \mid \pi(\eta) \text { is a Dyck path }\right\} \tag{4.1}
\end{equation*}
$$

is a basis of the space $\mathbf{R}_{n}$.
The proof is achieved in a few steps. We start with the following lemma.
Lemma 4.2. Any $\mathcal{P}(X) \in \mathbb{Q}[X]$ is in the linear span of $\mathcal{B}_{n}$ modulo $\mathcal{J}_{n}$. That is

$$
\begin{equation*}
P(X) \equiv \sum_{X^{n} \in \mathcal{B}_{n}} c_{\eta} X^{\eta}\left(\bmod \mathcal{J}_{n}\right) . \tag{4.2}
\end{equation*}
$$

Proof. It clearly suffices to show that (4.2) holds for any monomial $X^{v}$, with $v$ transdiagonal. We assume that there exists $X^{v}$ not reducible of the form (4.2) and we choose $X^{\varepsilon}$ to be the smallest amongst them with respect to the lexicographic order. Let us write

$$
\begin{aligned}
X^{\varepsilon} & =L M\left(G_{\varepsilon}\right) \\
& =\left(X^{\varepsilon}-G_{\varepsilon}\right)+G_{\varepsilon} \\
& \equiv X^{\varepsilon}-G_{\varepsilon}\left(\bmod \mathcal{J}_{n}\right) .
\end{aligned}
$$

All monomials in $\left(X^{\varepsilon}-G_{\varepsilon}\right)$ are lexicographically smaller than $X^{\varepsilon}$, thus they are reducible. This contradicts our assumption on $X^{\varepsilon}$ and completes our proof.

Thus $\mathcal{B}_{n}$ spans the space $\mathbf{R}_{n}$. We now prove its linear independence. This is equivalent to showing that the set $\mathcal{G}$ is a Gröbner basis of the ideal $\mathcal{J}_{n}$. A crucial lemma is the following one, which is the quasi-symmetric analogue of a classical result is the case of symmetric polynomials ([6, Theorem II.2.2]).

Lemma 4.3. If we denote by $\mathcal{L}[S]$ the linear span of a set $S$, then

$$
\begin{equation*}
\mathbb{Q}[X]=\mathcal{L}\left[X^{\eta} F_{\alpha} \mid X^{\eta} \in \mathcal{B}_{n}, \quad \alpha \models r \geqslant 0\right] . \tag{4.3}
\end{equation*}
$$

Proof. We have already obtained the following reduction for any monomial $X^{\varepsilon}$ in $\mathbb{Q}[X]$.

$$
X^{\varepsilon} \equiv \sum_{X^{\eta} \in \mathcal{B}_{n}} c_{\eta} X^{\eta}\left(\bmod \mathcal{J}_{n}\right),
$$

which is equivalent to

$$
\begin{equation*}
X^{\varepsilon}=\sum_{X^{\eta} \in \mathcal{B}_{n}} c_{\eta} X^{\eta}+\sum_{\alpha \nLeftarrow r \geqslant 1} Q_{\alpha} F_{\alpha} . \tag{4.4}
\end{equation*}
$$

We then apply reduction (4.4) to each monomial of the $Q_{\alpha}$ 's and use Proposition 2.2 to reduce products of fundamental quasi-symmetric functions. We obtain (4.3) in a finite number of operations since degrees strictly decrease at each operation, because $\alpha \models r \geqslant 1$ implies $\operatorname{deg} Q_{\alpha}<|\varepsilon|$.

The next lemma is the final step in our proof of Theorem 4.1.
Lemma 4.4. The set $\mathcal{G}$ is a linear basis of the ideal $\mathcal{J}_{n}$, i.e.

$$
\begin{equation*}
\mathcal{J}_{n}=\mathcal{L}\left[G_{\varepsilon} \mid \varepsilon \text { transdiagonal }\right] . \tag{4.5}
\end{equation*}
$$

Proof. Let us denote by $\mathcal{A}_{n}$ the set

$$
\begin{equation*}
\mathcal{A}_{n}=\left\{X^{\xi} \mid x_{1}^{\xi_{n}} x_{2}^{\xi_{n-1}} \cdots x_{n}^{\xi_{1}} \in \mathcal{B}_{n}\right\} \tag{4.6}
\end{equation*}
$$

Now the algebra endomorphism of $\mathbb{Q}[X]$ that reverses the variables,

$$
x_{i} \mapsto x_{n-i+1},
$$

clearly fixes the subalgebra $Q s y m$. In fact it maps $F_{\alpha}$ to $F_{\alpha^{\prime}}$, where $\alpha^{\prime}$ is the reverse composition.

It follows from Lemma 4.3 and the endomorphism above that

$$
\begin{equation*}
\mathbb{Q}[X]=\mathcal{L}\left[X^{\zeta} F_{\alpha} \mid X^{\zeta} \in \mathcal{A}_{n}, \quad \alpha \models r \geqslant 0\right] . \tag{4.7}
\end{equation*}
$$

Now to prove Lemma 4.4, we reduce the problem as follows. We first use (4.7) and Proposition 2.2 to write

$$
\begin{aligned}
\mathcal{J}_{n} & =\left\langle F_{\alpha}, \alpha \models s \geqslant 0\right\rangle_{\mathbb{Q}[X]}=\mathcal{L}\left[X^{\xi} F_{\alpha} F_{\beta} \mid X^{\xi} \in \mathcal{A}_{n}, \alpha \models s \geqslant 0, \beta \models t \geqslant 1\right] \\
& =\mathcal{L}\left[X^{\xi} F_{\gamma} \mid X^{\xi} \in \mathcal{A}_{n}, \gamma \models r \geqslant 1\right] .
\end{aligned}
$$

It is now sufficient to prove that for all $X^{\xi} \in \mathcal{A}_{n}$ and all $\gamma \models r \geqslant 1$

$$
\begin{equation*}
X^{\xi} F_{\alpha} \in \mathcal{L}\left[G_{\varepsilon} \mid \varepsilon \text { transdiagonal }\right] . \tag{4.8}
\end{equation*}
$$

But Lemma 4.2 implies that any monomial of degree greater than $n$ is in $\mathcal{J}_{n}$. Hence to prove (4.8), we need only show it for $\xi$ and $\gamma$ such that $|\xi|+|\gamma| \leqslant n$. To do that, we reduce the product

$$
\begin{equation*}
x_{n}^{\xi_{n}}\left(x_{n-1}^{\xi_{n-1}}\left(\cdots\left(x_{2}^{\xi_{2}}\left(x_{1}^{\xi_{1}} F_{\alpha}\right)\right)\right)\right) \tag{4.9}
\end{equation*}
$$

recursively, using

$$
\begin{equation*}
x_{k} G_{w b \beta 0^{*}}=G_{w(b+1) \beta 0^{*}}-G_{w 0(b+1) \beta 0^{*}} \tag{4.10}
\end{equation*}
$$

or

$$
\begin{equation*}
x_{k} G_{w 0^{*} 00^{*}}=G_{w 0^{*} 10^{*}}-G_{w 0^{*} 010^{*}} . \tag{4.11}
\end{equation*}
$$

Relations (4.10) and (4.11) are immediate consequences of the definition of the $\mathcal{G}$ basis (relation (3.2)).

We have to show that the vectors $\varepsilon$ generated in this process are all transdiagonal and that the length $\ell(\varepsilon)$ always remains at most equal to $n$. Let us first check that the transdiagonal part. This is obvious in the case of relation (4.11). In the other case (relation (4.10)), for $\varphi=w b \beta 0^{*}$, it is sufficient to observe that if $m$ is such that

$$
\varphi_{1}+\cdots+\varphi_{m}>m
$$

with $m>\ell(w)$ (if not, it is evident), then

$$
\varphi_{1}^{\prime}+\cdots+\varphi_{m}^{\prime}>m+1>m \quad \text { and } \quad \varphi_{1}^{\prime \prime}+\cdots+\varphi_{m+1}^{\prime \prime}>m+1,
$$

where $\varphi^{\prime}=w(b+1) \beta 0^{*}$, and $\varphi^{\prime \prime}=w 0(b+1) \beta 0^{*}$. We shall now prove that the length of the $\varepsilon$ 's always remains at most equal to $n$. For this we need to keep track of the term $\varepsilon_{\ell(\varepsilon)}$. Two cases have to be considered.

- First case: $\varepsilon_{\ell(\varepsilon)}$ comes from $\alpha_{\ell(\alpha)}$ that has shifted to the right by relation (4.10). It could move at most $|\xi|$ steps to the right, whence

$$
\ell(\varepsilon) \leqslant \ell(\alpha)+|\xi| \leqslant|\alpha|+|\xi| \leqslant n .
$$

- Second case: $\varepsilon_{\ell(\varepsilon)}$ is a " 1 " generated by relation (4.11) that has shifted to the right. If it is generated by a multiplication by $x_{k}$, then we consider the vector

$$
\eta=\xi_{n} \xi_{n-1} \cdots \xi_{k} 0^{*}
$$

Since $X^{\xi} \in \mathcal{A}_{n}$ implies $\pi(\eta)$ is a Dyck path, we have

$$
|\eta|<\ell(\eta)=n-k+1
$$

hence the generated " 1 " can shift at most to position

$$
k+|\eta| \leqslant k+n-k=n .
$$

The recursive process used to reduce a product of form (4.9) is illustrated in the following example, where $n=5$.

$$
\begin{aligned}
x_{1} x_{3} F_{21} & =x_{3}\left(x_{1} F_{21}\right) \\
& =x_{3}\left(G_{31000}-G_{03100}\right)
\end{aligned}
$$

$$
\begin{aligned}
& =x_{3} G_{31000}-x_{3} G_{03100} \\
& =G_{31100}-G_{31010}-G_{03200}+G_{03020} .
\end{aligned}
$$

End of proof of Theorem 4.1: By Lemma 4.2, the set $\mathcal{B}_{n}$ spans the quotient $\mathbf{R}_{n}$. Assume we have a linear dependence relation modulo $\mathcal{J}_{n}$, i.e. there exists $P$

$$
P=\sum_{X^{\xi} \in \mathcal{B}_{n}} a_{\xi} X^{\xi} \in \mathcal{I}_{n} .
$$

By Lemma $4.4, \mathcal{J}_{n}$ is linearly spanned by the $G_{\varepsilon}$ 's, thus

$$
P=\sum_{\varepsilon \text { transdiagonal }} b_{\varepsilon} G_{\varepsilon}
$$

This implies $L M(P)=X^{\varepsilon}$, with $\varepsilon$ transdiagonal, which is absurd.
A consequence of Lemma 4.4 and Theorem 4.1 is that the set $\mathcal{G}$ is a Gröbner basis of $\mathcal{J}_{n}$ with respect to the lex order. From this we see below that a minimal Gröbner basis of $\mathcal{J}_{n}$ is obtained from $\mathcal{G}$ if we select the $G_{\varepsilon} \in \mathcal{G}$ such that $\pi(\varepsilon)$ has exactly one step under the line $y=x$ and no other horizontal steps after that.

Corollary 4.5. A minimal Gröbner basis for $\mathcal{J}_{n}$ is given by

$$
\begin{equation*}
\left\{G_{\varepsilon} \in \mathcal{G}\left|\varepsilon=w 0^{*}, \ell(w)=|w|+1, w_{1}+\cdots+w_{s} \leqslant s, \text { for } s<\ell(w)\right\} .\right. \tag{4.12}
\end{equation*}
$$

Proof. Theorem 4.1 implies that the monomial ideal $\operatorname{LT}\left(\mathcal{J}_{n}\right)$ of leading terms of $\mathcal{J}_{n}$ is generated by all monomials $X^{\eta}$ where $\pi(\eta)$ is transdiagonal. For any such $\eta$ let $m$ be the smallest integer such that $m<\eta_{1}+\cdots+\eta_{m}$ and let $\varepsilon=\eta_{1} \cdots \eta_{m-1} a 0^{*}$ where $a=m-1-\eta_{1}-\cdots-\eta_{m-1}$. The monomial $X^{\varepsilon}$ divides $X^{\eta}$ which shows that $L T\left(\mathcal{J}_{n}\right)$ is generated by the leading monomial of the $G_{\varepsilon}$ in (4.12). This gives that (4.12) is a Gröbner basis. To show minimality, consider $X^{\xi}$ a monomial that strictly divides the leading monomial of a $G_{\varepsilon}$ in (4.12). Since $\pi(\varepsilon)$ has exactly one step under the line $y=x$, we have that $\pi(\xi)$ is not transdiagonal and $X^{\xi} \notin L T\left(\mathcal{J}_{n}\right)$. Hence the leading monomials of the $G_{\varepsilon}$ in (4.12) is a minimal set of generators for $\operatorname{LT}\left(\mathcal{J}_{n}\right)$.

## 5. Hilbert series

Since Theorem 4.1 gives us an explicit basis for the quotient $\mathbf{R}_{n}$, which is isomorphic to $\mathbf{S H}_{n}$ as a graded vector space, we are able to refine relation (1.4) by giving the Hilbert series of the space of super-covariant polynomials. For $k \in \mathbb{N}$, let
$\mathbf{S H}_{n}^{(k)}$ and $\mathbf{R}_{n}^{(k)}$ denote the projections

$$
\begin{equation*}
\mathbf{S H}_{n}^{(k)}=\mathbf{S H}_{n} \cap \mathbb{Q}^{(k)}[X] \simeq \mathbf{R}_{n} \cap \mathbb{Q}^{(k)}[X]=\mathbf{R}_{n}^{(k)}, \tag{5.1}
\end{equation*}
$$

where $\mathbb{Q}^{(k)}[X]$ is the vector space of homogeneous polynomials of degree $k$ together with zero. Here, we represent Dyck paths horizontally, with $n$ rising steps $(1,1)$ and $n$ falling steps $(1,-1)$. Let us denote by $D_{n}^{(k)}$ the number of Dyck paths of length $2 n$ ending by exactly $k$ falling steps and by $C_{n}^{(k)}$ the number of Dyck paths of length $2 n$ which have exactly $k$ factors, i.e. $k+1$ points on the axis. The next figure gives an example of a Dyck path of length 28, ending with four falling steps and made of three factors.


It is well known that

$$
\begin{equation*}
D_{n}^{(k)}=C_{n}^{(k)}=\frac{k(2 n-k-1)!}{n!(n-k)!} \tag{5.2}
\end{equation*}
$$

where the first equality is classical (cf. [17] for example for a bijective proof), and the second corresponds to [11, formula (7)].

Let us denote by $F_{n}(t)$ the Hilbert series of $\mathbf{S H}_{n}$, i.e.

$$
\begin{equation*}
F_{n}(t)=\sum_{k \geqslant 0} \operatorname{dim} \mathbf{S} \mathbf{H}_{n}^{(k)} t^{k} . \tag{5.3}
\end{equation*}
$$

Theorem 5.1. For $0 \leqslant k \leqslant n-1$, the dimension of $\mathbf{S H}_{n}^{(k)}$ is given by

$$
\begin{equation*}
\operatorname{dim} \mathbf{S H}_{n}^{(k)}=\operatorname{dim} \mathbf{R}_{n}^{(k)}=D_{n}^{(n-k)}=C_{n}^{(n-k)}=\frac{n-k}{n+k}\binom{n+k}{k} . \tag{5.4}
\end{equation*}
$$

For $k \geqslant n$ the dimension of $\mathbf{S H}_{n}^{(k)}$ is 0 .
Proof. By Theorem 4.1, we know that the set

$$
\mathcal{B}_{n}=\left\{X^{\eta} \mid \pi(\eta) \text { is a Dyck path }\right\}
$$

is a basis for $\mathbf{R}_{n}$. It is then sufficient to observe that the path $\pi(\eta)$ associated to $\eta$ ends by exactly $n-|\eta|$ falling steps.

For example, we have:

| $n$ | $F_{n}(t)$ |
| :--- | :--- |
| 1 | 1 |
| 2 | $1+t$ |
| 3 | $1+2 t+2 t^{2}$ |
| 4 | $1+3 t+5 t^{2}+5 t^{3}$ |
| 5 | $1+4 t+9 t^{2}+14 t^{3}+14 t^{4}$ |
| 6 | $1+5 t+14 t^{2}+28 t^{3}+42 t^{4}+42 t^{5}$ |
| 7 | $1+6 t+20 t^{2}+48 t^{3}+90 t^{4}+132 t^{5}+132 t^{6}$ |

This gives

$$
\begin{equation*}
F_{n}(t)=\sum_{k=0}^{n-1} \frac{n-k}{n+k}\binom{n+k}{k} t^{k} \tag{5.5}
\end{equation*}
$$

from which one easily deduces that the generating series for the $F_{n}(t)$ 's is

$$
\begin{equation*}
\sum_{n} F_{n}(t) x^{n}=\frac{1-\sqrt{1-4 t x}-2 x}{2(t+x-1)} \tag{5.6}
\end{equation*}
$$

Remark 5.2. The study of various filtrations of the space $\mathbb{Q}[X]$, with respect to family of ideals of quasi-symmetric polynomials, will be the object of a forthcoming paper [3].

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