# Limit theorem for the statistical solution of Burgers equation 

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#### Abstract

In this work we study limit theorems for the Hopf-Cole solution of the Burgers equation when the initial value is a functional of some Gaussian processes. We use the Gaussian chaos decomposition, and we get "Gaussian scenario" with new normalization factors. © 1999 Elsevier Science B.V. All rights reserved.


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## 1. Introduction

The one-dimensional Burgers equation without force has the form

$$
\begin{equation*}
\partial_{t} u+u \partial_{x} u=\frac{v}{2} \partial_{x x}^{2} u, \quad x \in \mathbb{R}, t>0 . \tag{1}
\end{equation*}
$$

Here $v>0$ is the viscosity and the initial value $u(x, 0)=-\mathrm{d} \xi(x) / \mathrm{d} x$ is given, and satisfies $\xi(x)=\mathrm{o}\left(x^{2}\right)$ as $|x| \rightarrow+\infty$. If we introduce a potential function $\psi$ defined as $u=-\partial_{x} \psi$, then the Hopf-Cole substitution $\psi=v \ln \theta$ shows that $\theta$ satisfies the heat equation $\partial_{t} \theta=(v / 2) \partial_{x x}^{2} \theta$. Using this fact one can write down for the solution $u=u(x, t, v)$ the explicit expression

$$
\begin{equation*}
u(x, t, v)=\frac{I(x, t, v)}{J(x, t, v)}, \tag{2}
\end{equation*}
$$

where

$$
\begin{equation*}
I(x, t, v)=\int_{-\infty}^{\infty} \frac{x-y}{t} g\left(\frac{x-y}{\sqrt{t v}}\right) \exp \left\{\frac{\xi(y)}{v}\right\} \mathrm{d} y \tag{3}
\end{equation*}
$$

[^0]and
\[

$$
\begin{equation*}
J(x, t, v)=\int_{-\infty}^{\infty} g\left(\frac{x-y}{\sqrt{t v}}\right) \exp \left\{\frac{\xi(y)}{v}\right\} \mathrm{d} y \tag{4}
\end{equation*}
$$

\]

The function $g$ is the density of the standard Gaussian random variable $\mathscr{N}(0,1)$.
Many authors have investigated the solution $u(x, t, v)$ on different types of initial conditions which are stationary Gaussian processes. It is well-known (Albeverio et al., 1994; Bulinskii and Molchanov, 1991) that, if $v=1$ and $\xi(x)$ is a stationary zero-mean Gaussian process, with covariance function $B(x)=\mathbb{E}[\xi(x) \xi(0)]$ is assumed to satisfy

$$
\begin{equation*}
\int_{\mathbb{R}}|B(x)| \mathrm{d} x<\infty \tag{5}
\end{equation*}
$$

then the solution $u(x, t, 1)$ obeys the "Gaussian scenario", that is, as $L \rightarrow \infty$,

$$
\begin{equation*}
L^{3 / 2} u\left(L x, L^{2} t, 1\right) \Rightarrow X(x, t) \tag{6}
\end{equation*}
$$

where $X$ is a Gaussian process, and $\Rightarrow$ stands for the weak convergence of the finite-dimensional distributions. In the case where

$$
\begin{align*}
& B(x)=1-\frac{\lambda_{2}}{2} x^{2}+\frac{\lambda_{4}}{4!} x^{4}+\mathrm{o}\left(x^{4}\right) \quad \text { as } \quad x \rightarrow 0 \quad \text { and } \quad B(x)=\mathrm{o}(1 / \ln x) \\
& \quad \text { as } \quad x \rightarrow \infty \tag{7}
\end{align*}
$$

Molchanov et al. (1995) have proved that, as $L \rightarrow+\infty$,

$$
L \sqrt{2 \ln L} u\left(L x, L^{2} \sqrt{2 \ln L} t, 1 / L^{2} \sqrt{2 \ln L}\right) \Rightarrow \frac{x-y_{j(x, t)}}{t}
$$

where $y_{j(x, t)}$ is defined via a Poisson process $\left(y_{j}, u_{j}\right)_{j \in \mathbb{Z}}$ on $\mathbb{R}^{2}$ with the intensity $\mathrm{e}^{-u} \mathrm{~d} y \mathrm{~d} u$, by maximizing the difference

$$
\begin{equation*}
\max _{j}\left[u_{j}-\frac{\left(x-y_{j}\right)^{2}}{2 t}\right]=u_{j(x, t)}-\frac{\left(x-y_{j(x, t)}\right)^{2}}{2 t} \tag{8}
\end{equation*}
$$

On the other hand, Surgailis (1996) has proved that if $B(0):=\lambda_{0}>1$,

$$
\begin{equation*}
B(x)=\lambda_{0}-\frac{\lambda_{2}}{2} x^{2}+\mathrm{o}\left(x^{2}\right) \text { as } x \rightarrow 0 \text { and } B(x)=\mathrm{o}(1 / \ln x) \text { as } x \rightarrow \infty \tag{9}
\end{equation*}
$$

then

$$
L \sqrt{2 \ln L} u\left(L x, L^{2} \sqrt{2 \ln L} t, 1 / \sqrt{2 \ln L}\right) \Rightarrow v(x, t)
$$

where

$$
\begin{aligned}
v(x, t)= & \sum_{i \in \mathbb{Z}} t^{-1}\left(x-y_{i}\right) \exp \left\{\sqrt{\lambda_{0}} u_{i}-\frac{\left(x-y_{i}\right)^{2}}{2 t}\right\} \\
& \times\left\{\sum_{i \in \mathbb{Z}} \exp \left\{\sqrt{\lambda_{0}} u_{i}-\frac{\left(x-y_{i}\right)^{2}}{2 t}\right\}\right\}^{-1}
\end{aligned}
$$

See also Hu and Woyczynski (1995) for other cases. In our work we unify these results and we broaden this list. This is the aim of Section 2 Theorem 2.1. In Section 3 we study the case when $\xi(x)=\int_{\mathbb{R}} f(x, y) \mathrm{d} W(y)-\frac{1}{2} \int_{\mathbb{R}} f^{2}(x, y) \mathrm{d} y$, where $W$ is the Gaussian white noise, and we obtain the "Gaussian scenario".

## 2. General scaling limit behavior

We set, for $L>0$, for positive function $T(L)$, and for functions $A(L), b(L)$,

$$
V(L y, v)=\exp \left\{v^{-1}(\xi(L y)-b(L))\right\}-A(L)
$$

The parameter $L$ may depend on $v$. We suppose that for all $(x, t) \in \mathbb{R} \times \mathbb{R}_{+}, t \neq 0$, there exists scaling $\beta(x, t, L)>0$, such that for any $\varepsilon \in\{0,1\}$, as $L \rightarrow \infty$,

$$
\begin{align*}
& \beta(x, t, L) \int_{\mathbb{R}} V(L y, v) g\left(\frac{L(y-x)}{\sqrt{T(L) t v}}\right)((x-y) / t)^{\varepsilon} \mathrm{d} y \Rightarrow\left(Z^{x, t},((x-y) / t)^{\varepsilon}\right) \\
& \quad:=\int_{\mathbb{R}}((x-y) / t)^{\varepsilon} Z^{x, t}(\mathrm{~d} y) \tag{10}
\end{align*}
$$

where $Z^{x, t}$ is a generalized process.
The following theorem gives a convergence of finite-dimensional distributions of the rescaled solutions of (1).

Theorem 2.1. (i) Suppose that $v=1$, and $T(L)=L^{2}$. If the scaling $\beta(x, t, L):=\beta(L)$ does not depend on $(x, t)$, then $Z^{x, t}(\mathrm{~d} y)=g((y-x) / \sqrt{t}) Z(\mathrm{~d} y)$, where $Z$ is a generalized process. Moreover, if for all $\varphi$ belonging to the Schwartz space $\mathscr{S}(\mathbb{R})$,

$$
\begin{equation*}
\lim _{L \rightarrow \infty} \int_{\mathbb{R}} \varphi(y) \exp \{\xi(L y)-b(L)\} \mathrm{d} y=a \int_{\mathbb{R}} \varphi(y) \mathrm{d} y, \tag{11}
\end{equation*}
$$

then, as $L \rightarrow \infty$, the finite-dimensional distributions of the two parameter random fields,

$$
L \beta(L) u\left(L x, L^{2} t, 1\right), \quad x \in \mathbb{R} \text { and } t>0,
$$

converge to the corresponding finite-dimensional distributions of the random field

$$
a^{-1} \int_{\mathbb{R}} \frac{x-y}{t} g\left(\frac{x-y}{\sqrt{t}}\right) Z(\mathrm{~d} y), \quad x \in \mathbb{R} \text { and } t>0
$$

(ii) If $A(L)=0$, then the finite-dimensional distributions of the two parameter random field,

$$
T(L) L^{-1} u(L x, T(L) t, v), \quad x \in \mathbb{R} \text { and } t>0
$$

converge to the corresponding finite-dimensional distributions of the random field

$$
\frac{\int_{\mathbb{R}}(x-y) /(t) Z^{x, t}(\mathrm{~d} y)}{\int_{\mathbb{R}} Z^{x, t}(\mathrm{~d} y)}, \quad x \in \mathbb{R} \text { and } t>0
$$

Proof. The proof of (i) is similar to the proof of Theorem 2.1 in Funaki et al. (1995), and it is based on the well-known following lemma.

Lemma 2.1. If $\left\{X_{t}, t>0\right\}$ and $\left\{Y_{t}, t>0\right\}$ are families of random variables such that $X_{t} \rightarrow X$ in law and $Y_{t} \rightarrow c$ in probability where $c$ is a real constant, then $X_{t}+Y_{t} \rightarrow$ $X+c, X_{t} Y_{t} \rightarrow c X, X_{t} / Y_{t} \rightarrow X / c($ if $c \neq 0)$, in law as $t \rightarrow+\infty$.

Now we come back to the proof of (ii). In this case $V(L y, v)=\exp \left\{v^{-1}(\xi(L y)-\right.$ $b(L))\}$, and from (2), (3) and (4) we have

$$
I(L x, T(L) t, v)=\frac{L^{2}}{T(L)} \int_{\mathbb{R}} \frac{x-y}{t} V(L y, v) g\left(\frac{L(y-x)}{\sqrt{T(L) t v}}\right) \mathrm{d} y \exp \left(v^{-1} b(L)\right),
$$

and

$$
J(L x, T(L) t, v)=L \int_{\mathbb{R}} V(L y, v) g\left(\frac{L(y-x)}{\sqrt{T(L) t v}}\right) \mathrm{d} y \exp \left(v^{-1} b(L)\right) .
$$

We have for all $\alpha_{i}, \gamma_{i}, x_{i} \in \mathbb{R}, t_{i}>0 ; 1 \leqslant i \leqslant n$,

$$
\begin{aligned}
& {\left[\sum_{i=1}^{n} \alpha_{i} \beta\left(x_{i}, t_{i}, L\right) T(L) L^{-2} I\left(L x_{i}, T(L) t_{i}, v\right)\right.} \\
& \left.\quad+\quad \sum_{i=1}^{n} \gamma_{i} L^{-1} \beta\left(x_{i}, t_{i}, L\right) J\left(L x_{i}, T(L) t_{i}, v\right)\right] \exp \left(-v^{-1} b(L)\right) \\
& =\int_{\mathbb{R}}\left\{\sum_{i=1}^{n}\left(\alpha_{i} \frac{x_{i}-y}{t_{i}}+\gamma_{i}\right) \beta\left(x_{i}, t_{i}, L\right) V(L y, v) g\left(\frac{L\left(y-x_{i}\right)}{\sqrt{T(L) t_{i} v}}\right)\right\} \mathrm{d} y .
\end{aligned}
$$

From (10) the member of the left-hand side converges weakly, as $L \rightarrow \infty$, to

$$
\begin{aligned}
& \int_{\mathbb{R}}\left\{\sum_{i=1}^{n}\left(\alpha_{i} \frac{x_{i}-y}{t_{i}}+\gamma_{i}\right) Z^{x_{i}, t_{i}}(\mathrm{~d} y)\right\} \\
& \quad=\sum_{i=1}^{n} \alpha_{i} \int_{\mathbb{R}} \frac{x_{i}-y}{t_{i}} Z^{x_{i}, t_{i}}(\mathrm{~d} y)+\sum_{i=1}^{n} \gamma_{i} \int_{\mathbb{R}} Z^{x_{i}, t_{i}}(\mathrm{~d} y) .
\end{aligned}
$$

It follows that

$$
T(L) L^{-1} \frac{I(L x, T(L) t, v)}{J(L x, T(L) t, v)}=T(L) L^{-1} u(L x, T(L) t, v) \Rightarrow \frac{\int_{\mathbb{R}}(x-y) /(t) Z^{x, t}(\mathrm{~d} y)}{\int_{\mathbb{R}} Z^{x, t}(\mathrm{~d} y)}
$$

whence the claimed result.
Remark 2.1. If $A(L)=A$, and $\beta(L) \rightarrow \infty$, as $L \rightarrow \infty$, then (11) is satisfied, with $a=A$.

Corollary 2.1. Let $\xi(x)$ be a stationary zero-mean Gaussian process.
(1) If $\xi(x)$ satisfies (5), then part (i) of Theorem 2.1 is satisfied with

$$
b(L)=0, \quad A(L)=0, \quad \beta(L)=\sqrt{L}, \quad a=\exp \left\{\mathbb{E}\left[\xi(0)^{2}\right] / 2\right\},
$$

and $Z(\mathrm{~d} y)=c W(\mathrm{~d} y)$; where $W$ is the Gaussian white noise on $\mathbb{R}$ and $c=a\left(\int_{\mathbb{R}}\left(\mathrm{e}^{B(z)}-\right.\right.$ 1) $\mathrm{d} z)^{1 / 2}$.
(2) If $\xi(x)$ satisfies (9), then part (ii) of Theorem 2.1. is satisfied with
$v=1 / \sqrt{2 \ln L}, \quad T(L)=L^{2} \sqrt{2 \ln L}$,
$b(L)=\sqrt{\lambda_{0}}\left(\sqrt{2 \ln L}+\ln \left[\left(\lambda_{2} / \lambda_{0}\right)^{1 / 2} / 2 \pi\right] / \sqrt{2 \ln L}\right)$
and

$$
\begin{aligned}
& \beta(x, t, L)=\left(\lambda_{2} / 2 \pi \lambda_{0}\right)^{1 / 2} L \sqrt{2 \ln L} \\
& Z^{x, t}(\mathrm{~d} y)=g\left(\frac{x-y}{\sqrt{t}}\right) \sum_{i \in \mathbb{Z}} \pi^{-1 / 2} \exp \left(\sqrt{\lambda_{0}} u_{i}\right) \delta\left(y-y_{i}\right)
\end{aligned}
$$

Here $\sum_{i} \delta_{\left(y_{i}, u_{i}\right)}$ is a random Poisson measure on $\mathbb{R}^{2}$ with intensity $\mathrm{e}^{-u} \mathrm{~d} u \mathrm{~d} y$.
(3) If $\xi(x)$ satisfies (7) then part (ii) of Theorem 2.1 is satisfied with

$$
v=\frac{1}{L^{2} \sqrt{2 \ln L}}, \quad T(L)=L^{2} \sqrt{2 \ln L}, \quad b(L)=\sqrt{2 \ln L}+\ln \left[\left(\lambda_{2}\right)^{1 / 2} / 2 \pi\right] / \sqrt{2 \ln L}
$$

and the normalization $\beta(x, t, L)$ is given by

$$
1 / \beta(x, t, L)=\int_{\Delta_{j(x, t)}(L)} \exp \left(v^{-1}\{\xi(L y)-b(L)\}\right) g\left(\frac{L(x-y)}{\sqrt{t}}\right) \mathrm{d} y
$$

where $\Delta_{j(x, t)}(L)=\left\{y \in \mathbb{R}:\left|y-y_{j(x, t)}\right| \leqslant \frac{1}{L \sqrt{2 \ln L}}\right\}$, and $Z^{x, t}(\mathrm{~d} y)=\delta\left(y-y_{j(x, t)}\right)$. Here $y_{j(x, t)}$ is given by (8).

The proofs of (1), (2), and (3) are due, respectively, to Albeverio et al. (1994), Surgailis (1996) and Molchanov et al. (1995).

## 3. The Gaussian scenario

In the sequel $v=1$, and $T(L)=L^{2}$. The initial value is a functional of the onedimensional Gaussian white noise $W$ with intensity the Lebesgue measure. More precisely, we consider the setting where $\xi(x)$ is such that the random variables $\exp \{\xi(x)\}$ belong to $L^{2}(\mathbb{P})$, the Hilbert space of square integrable functions with respect to $\mathbb{P}$, the measure of the underlying probability space supporting $W$.

We are interested in the asymptotic behavior of the ratio $u\left(L x, L^{2} t, 1\right):=u\left(L x, L^{2} t\right)$ as $L \rightarrow+\infty$. In view to obtain the normalization $\beta(L)$, the centering constants $b(L)$, and $A(L)$, we employ the Gaussian chaos decomposition Itô (1951). The nonlinear stochastic functional $\exp \{\xi(x)\}$ has the chaos decomposition

$$
\begin{equation*}
\exp \{\xi(x)\}=\sum_{k=0}^{\infty} \frac{1}{k!} I_{k}\left(f_{k}(x)\right) \tag{12}
\end{equation*}
$$

where for $k \geqslant 1, I_{k}\left(f_{k}(x)\right)=\int \cdots \int_{\mathbb{R}^{k}} f_{k}\left(x, y_{1}, \ldots, y_{k}\right) \mathrm{d} W\left(y_{1}\right) \ldots \mathrm{d} W\left(y_{k}\right)$ is the stochastic multiple Wiener integral, and for all $x \in \mathbb{R}, f_{k}(x): y=\left(y_{1}, \ldots, y_{k}\right) \rightarrow f_{k}(x, y)$ is a symmetric function belonging to $L^{2}\left(\mathbb{R}^{k}, \mathrm{~d} x^{\otimes k}\right)$. The latter space is endowed with the natural scalar product denoted $\langle\cdot, \cdot\rangle$, and with the norm $\|\cdot\|=\langle\cdot, \cdot\rangle^{1 / 2}$. If $\xi(x)$ is a Gaussian process then (12) is reduced to the Hermite expansion. The Gaussian chaos decomposition has a long history of application to the Burgers, and Navier-Stokes turbulence, both in the mathematical, and in the fluid dynamic communities, for references see e.g. Funaki et al. (1995).

We set for $k \geqslant 0$, and $\varphi$ belonging to the Schwartz space $\mathscr{S}(\mathbb{R})$,

$$
v_{k}(\varphi, L)=\frac{1}{k!} \int_{\mathbb{R}} \varphi(y) I_{k}\left(f_{k}(L y)\right) \mathrm{d} y .
$$

From (12) we get

$$
v(\varphi, L):=\int_{\mathbb{R}} \varphi(y) \exp \{\xi(L y)\} \mathrm{d} y=\sum_{k=0}^{\infty} v_{k}(\varphi, L)
$$

From the well-known formula Itô (1951),

$$
\mathbb{E}\left[I_{k}\left(f_{k}\left(x_{1}\right)\right) I_{j}\left(f_{j}\left(x_{2}\right)\right)\right]=k!\delta_{k}^{j}\left\langle f_{k}\left(x_{1}\right), f_{k}\left(x_{2}\right)\right\rangle,
$$

we have

$$
\mathbb{E}[v(\varphi, L)]=v_{0}(\varphi, L), \quad \text { and } \quad \operatorname{Var}(v(\varphi, L))=\sum_{k=1}^{+\infty} \operatorname{Var}\left(v_{k}(\varphi, L)\right) .
$$

For $k \geqslant 1$, we set $B_{k}\left(x_{1}, x_{2}\right)=\left\langle f_{k}\left(x_{1}\right), f_{k}\left(x_{2}\right)\right\rangle$, and we get

$$
\operatorname{Var}\left(v_{k}(\varphi, L)\right)=\frac{1}{k!} \iint_{\mathbb{R}^{2}} \varphi\left(y_{1}\right) \varphi\left(y_{2}\right) B_{k}\left(L y_{1}, L y_{2}\right) \mathrm{d} y_{1} \mathrm{~d} y_{2} .
$$

Theorem 3.1. Suppose that $\mathbb{E}[\exp \{\xi(x)\}]:=A$, a constant which does not depend on $x$, and there exist a positive measurable function $\beta(L) \rightarrow \infty$, as $L \rightarrow \infty$, a measure $\mu$ belonging to the space of tempered distributions $\mathscr{S}^{\prime}\left(\mathbb{R}^{2}\right)$ such that: for all $G$ belonging to the Schwartz space $\mathscr{S}\left(\mathbb{R}^{2}\right)$, as $L \rightarrow \infty$,

$$
\begin{array}{ll}
{\left[\mathrm{H}_{1}\right]:} & \iint_{\mathbb{R}^{2}} \beta(L)^{2} B_{1}(L x, L y) G(x, y) \mathrm{d} x \mathrm{~d} y \rightarrow \iint_{\mathbb{R}^{2}} G(x, y) \mu(\mathrm{d} x, \mathrm{~d} y), \\
{\left[\mathrm{H}_{2}\right]:} & \beta(L)^{2} \sup _{k \geqslant 2} \iint_{\mathbb{R}^{2}}\left|B_{k}(L x, L y) G(x, y)\right| \mathrm{d} x \mathrm{~d} y \rightarrow 0 .
\end{array}
$$

(1) Then we have for all $\varphi \in \mathscr{S}(\mathbb{R})$, as $L \rightarrow \infty$,

$$
\beta(L) \int_{\mathbb{R}}[\exp \{\xi(L y)\}-A] \varphi(y) \mathrm{d} y=\beta(L)\left(v(\varphi, L)-v_{0}(\varphi, L)\right) \rightarrow \int_{\mathbb{R}} \varphi(y) Z(\mathrm{~d} y)
$$

where $Z$ is a Gaussian field whose covariance function is

$$
\operatorname{cov}\left(\left(Z, \varphi_{1}\right),\left(Z, \varphi_{2}\right)\right)=\iint_{\mathbb{R}^{2}} \varphi_{1}\left(y_{1}\right) \varphi_{2}\left(y_{2}\right) \mu\left(\mathrm{d} y_{1}, \mathrm{~d} y_{2}\right)
$$

(2) It follows that

$$
L \beta(L) u\left(L x, L^{2} t, 1\right) \Rightarrow A^{-1} \int_{\mathbb{R}} \frac{x-y}{t} g\left(\frac{x-y}{\sqrt{t}}\right) Z(\mathrm{~d} y) .
$$

Proof. The proof of part (1) is a consequence of Lemma 2.1. Indeed, thanks to the hypotheses $\left[\mathrm{H}_{1}\right]$ and $\left[\mathrm{H}_{2}\right]$, we have, as $L \rightarrow \infty$, the convergence in law of $\beta(L) v_{1}(\varphi, L)$ to the Gaussian process $\int_{\mathbb{R}} \varphi(y) Z(\mathrm{~d} y)$, and the convergence of $\beta(L)\left(v(\varphi, L)-v_{0}(\varphi, L)-\right.$ $\left.v_{1}(\varphi, L)\right)$ to 0 in $L^{2}(\mathbb{P})$. Hence according to Lemma $2.1 \beta(L)\left(v(\varphi, L)-v_{0}(\varphi, L)\right)$ converges in law to $\int_{\mathbb{R}} \varphi(y) Z(\mathrm{~d} y)$.

The proof of part (2) is a consequence of part (i) of Theorem 2.1, and from Remark 2.1.

Corollary 3.1. Suppose that

$$
\xi(x)=\int_{\mathbb{R}} f(x, y) \mathrm{d} W(y)-\frac{\|f(x, \cdot)\|^{2}}{2}
$$

where $f$ is such that $B_{1}(x, x)=\|f(x, \cdot)\|^{2} \leqslant 1$ for all $x$. If the hypotheses $\left[\mathrm{C}_{1}\right]$ and $\left[\mathrm{C}_{2}\right]$ below are satisfied:
[ $\mathrm{C}_{1}$ ] there exist a positive measurable function $\beta(L) \rightarrow \infty$, as $L \rightarrow \infty$, and two positive measures $\mu_{1}, \mu_{2} \in \mathscr{S}^{\prime}\left(\mathbb{R}^{2}\right)$ such that for any $G \in \mathscr{S}\left(\mathbb{R}^{2}\right)$,

$$
\int_{\mathbb{R}^{2}} \beta(L)^{2} B_{1}^{+}(L x, L y) G(x, y) \mathrm{d} x \mathrm{~d} y \rightarrow \int_{\mathbb{R}^{2}} G(x, y) \mathrm{d} \mu_{1}(x, y)
$$

and

$$
\int_{\mathbb{R}^{2}} \beta(L)^{2} B_{1}^{-}(L x, L y) G(x, y) \mathrm{d} x \mathrm{~d} y \rightarrow \int_{\mathbb{R}^{2}} G(x, y) \mathrm{d} \mu_{2}(x, y),
$$

where $B_{1}^{+}, B_{1}^{-}$are, respectively, the positive and negative parts of $B_{1}$.
$\left[\mathrm{C}_{2}\right]$ For all $\varepsilon>0$, and for all compact set $K$, subset of $\mathbb{R}^{2}$, as $L \rightarrow \infty$,

$$
\beta(L)^{2} \lambda\left(\left\{(x, y) \in K,\left|B_{1}(L x, L y)\right| \geqslant \varepsilon\right\}\right) \rightarrow 0,
$$

where $\lambda$ is the Lebesgue measure.
Then, for all $\varphi \in \mathscr{S}(\mathbb{R})$,

$$
\beta(L) \int_{\mathbb{R}}[\exp (\xi(L y))-1] \varphi(y) \mathrm{d} y
$$

converges in distribution to the random variable

$$
\int_{\mathbb{R}} \varphi(y) Z(\mathrm{~d} y):=(Z, \varphi),
$$

where $Z(\mathrm{~d} y)$ is a Gaussian field whose covariance function is

$$
\operatorname{cov}\left(\left(Z, \varphi_{1}\right),\left(Z, \varphi_{2}\right)\right)=\iint_{\mathbb{R}^{2}} \varphi_{1}\left(y_{1}\right) \varphi_{2}\left(y_{2}\right) \mathrm{d} \mu\left(y_{1}, y_{2}\right),
$$

where $\mu=\mu_{1}-\mu_{2}$.
Proof. For any $x \in \mathbb{R}, \exp (\xi(x))=\sum_{k=0}^{\infty}(1 / k!) I_{k}\left(f(x, \cdot)^{\otimes k}\right)$, hence the constant $A$ of Theorem 3.1 is equal to 1 . The condition [ $\mathrm{C}_{1}$ ] implies the condition $\left[\mathrm{H}_{1}\right]$ of Theorem 3.1. For $k \geqslant 2,\left|B_{k}(x, y)\right|=\left|B_{1}(x, y)\right|^{k} \leqslant B_{2}(x, y) \mathrm{d} x \mathrm{~d} y-a . s$. So, to get the condition $\left[\mathrm{H}_{2}\right]$ of Theorem 3.1 we have to prove that for all $G \in \mathscr{S}\left(\mathbb{R}^{2}\right)$, as $L \rightarrow \infty$,

$$
\iint_{\mathbb{R}^{2}} \beta(L)^{2}\left(B_{1}(L x, L y)\right)^{2} G(x, y) \mathrm{d} x \mathrm{~d} y \rightarrow 0
$$

We have for $\varepsilon>0, \iint_{\mathbb{R}^{2}} \beta(L)^{2}\left(B_{1}(L x, L y)\right)^{2} G(x, y) \mathrm{d} x \mathrm{~d} y=I+J$, where

$$
I=\iint_{\left\{\left|B_{1}(L x, L y)\right|<\varepsilon\right\}} \beta(L)^{2}\left(B_{1}(L x, L y)\right)^{2} G(x, y) \mathrm{d} x \mathrm{~d} y,
$$

and

$$
J=\iint_{\left\{\left|B_{1}(L x, L y)\right| \geqslant \varepsilon\right\}} \beta(L)^{2}\left(B_{1}(L x, L y)\right)^{2} G(x, y) \mathrm{d} x \mathrm{~d} y .
$$

It follows that there exist two constants $c_{1}$ and $c_{2}$ such that $|I| \leqslant \varepsilon c_{1}$ (for $L$ large enough), and

$$
|J| \leqslant c_{2} \iint_{\left\{\left|B_{1}(L x, L y)\right| \geqslant \varepsilon\right\}} \beta(L)^{2}\left|B_{1}(L x, L y) G(x, y)\right| \mathrm{d} x \mathrm{~d} y .
$$

For $L$ sufficiently large there exist $M>0$ such that

$$
\iint_{\left\{x^{2}+y^{2} \geqslant M^{2}\right\}} \beta(L)^{2}\left|B_{1}(L x, L y) G(x, y)\right| \mathrm{d} x \mathrm{~d} y \leqslant \varepsilon
$$

and for $K=\left\{(x, y) \in \mathbb{R}^{2}, x^{2}+y^{2} \leqslant M\right\}$,

$$
\begin{aligned}
& \iint_{\left\{\left|B_{1}(L x, L y)\right| \geqslant \varepsilon\right\}} \beta(L)^{2}\left|B_{1}(L x, L y) G(x, y)\right| \mathrm{d} x \mathrm{~d} y \\
& \quad \leqslant \varepsilon+\iint_{K \cap[|B(L x, L y)| \geqslant \varepsilon]} \beta(L)^{2}\left|B_{1}(L x, L y) G(x, y)\right| \mathrm{d} x \mathrm{~d} y \\
& \quad \leqslant \varepsilon+c \beta(L)^{2} \lambda\left(\left\{(x, y) \in K,\left|B_{1}(L x, L y)\right| \geqslant \varepsilon\right\}\right),
\end{aligned}
$$

where $c>0$ is some constant. From that we have for $L$ large enough,

$$
I+J \leqslant \varepsilon c_{1}+c_{2}\left[\varepsilon+c \beta(L)^{2} \lambda\left(\left\{(x, y) \in K,\left|B_{1}(L x, L y)\right| \geqslant \varepsilon\right\}\right)\right] .
$$

Now taking account of [ $\mathrm{C}_{2}$ ] we get the desired result.
Remark 3.1. The case where the initial value $u(x, 0)$, is the Brownian motion, is out of the scope of Theorem 3.1, and Corollary 3.1.

In this part we study some situations when Corollary 3.1 is satisfied. A measurable function $L:(0,+\infty) \rightarrow(0,+\infty)$ is slowly varying at $+\infty$ if, for each $t>0$, as $x \rightarrow+\infty, L(t x) / L(x)=1$. It is well known (see for example Appendix III in Galambos, 1978; ch. 0 in Bertoin, 1996) that $L$ has the form

$$
\begin{equation*}
L(x)=\exp \left\{u(x)+\int_{1}^{x} \frac{e(z)}{z} \mathrm{~d} z\right\} \tag{13}
\end{equation*}
$$

where $u, e:(0,+\infty) \rightarrow \mathbb{R}$ are bounded measurable functions with $u(x) \rightarrow u^{*} \in \mathbb{R}$, and $e(x) \rightarrow 0$, as $x \rightarrow+\infty$.

Corollary 3.2. Let $f \in L^{2}(\mathbb{R}, \mathrm{~d} x)$, and $\xi(x)=\int_{\mathbb{R}} f(x-y) \mathrm{d} W(y)-\|f\|^{2} / 2$. The process $\xi(x)$ is a stationary Gaussian process with covariance function $B_{1}(x, y)=$ $\int_{\mathbb{R}} f(x-z) f(y-z) \mathrm{d} z:=B(x-y)$. Suppose that $B(x-y)=\left(\Phi(|x-y|) /|x-y|^{\alpha}\right)$, where $0<\alpha<1$, and $\Phi$ is a slowly varying function such that $0<\Phi(|x|) \leqslant|x|^{\alpha}$ for all $x$. Then, for all $\varphi \in \mathscr{S}(\mathbb{R})$,

$$
\frac{L^{\alpha / 2}}{\sqrt{\Phi(L)}} \int_{\mathbb{R}}[\exp (\xi(L y))-1] \varphi(y) \mathrm{d} y
$$

converges in distribution to $\int_{\mathbb{R}} \varphi(y) Z(\mathrm{~d} y):=(Z, \varphi)$, where $Z$ is a Gaussian field whose covariance function is

$$
\operatorname{cov}\left(\left(Z, \varphi_{1}\right),\left(Z, \varphi_{2}\right)\right)=\iint_{\mathbb{R}^{2}} \varphi_{1}\left(y_{1}\right) \varphi_{2}\left(y_{2}\right) \frac{\mathrm{d} y_{1} \mathrm{~d} y_{2}}{\left|y_{1}-y_{2}\right|^{\alpha}}
$$

Proof. This result is well known, it has been considered by Albeverio et al. (1994), and Leonenko and Orsingher (1995). Corollary 3.1 gives a simplified proof. Indeed, in this case $B_{k}(x, y)=\left(\left(\Phi(|x-y|) /|x-y|^{\alpha}\right)\right)^{k}$, and it is easy to see that $\left|B_{k}(x, y)\right| \leqslant\left|B_{2}(x, y)\right|$ for all $k \geqslant 2$. Let us prove the condition $\left[\mathrm{C}_{1}\right]$ with $\beta(L)=\frac{L^{\alpha / 2}}{\sqrt{\Phi(L)}}$ and $\mu=\left(\mathrm{d} x \mathrm{~d} y /|x-y|^{\alpha}\right)$.

We have for all $A>0, \iint_{\mathbb{R}^{2}} \beta(L)^{2} B(L|x-y|) G(x, y) \mathrm{d} x \mathrm{~d} y=I+J$, where

$$
I=\iint_{[L|x-y|>A]} \beta^{2}(L) B(L|x-y|) G(x, y) \mathrm{d} x \mathrm{~d} y
$$

and

$$
J=\iint_{[L|x-y|<A]} \beta^{2}(L) B(L|x-y|) G(x, y) \mathrm{d} x \mathrm{~d} y
$$

Let us prove that $I \rightarrow \iint_{\mathbb{R}^{2}}|x-y|^{-\alpha} G(x, y) \mathrm{d} x \mathrm{~d} y$ as $L \rightarrow \infty$. First we have

$$
\beta^{2}(L) B(L|x-y|)=\Phi(L|x-y|) \Phi(L)^{-1}
$$

Using (13), we have for all $\varepsilon>0$, and for $L$ large enough,

$$
\begin{aligned}
\left|\Phi(L|x-y|) \Phi(L)^{-1}\right| & =\exp \left\{u(L|x-y|)-u(L)+\int_{L}^{L|x-y|} \frac{\mathrm{e}(z)}{z} \mathrm{~d} z\right\} \\
& \leqslant c\left\{|x-y|^{\varepsilon}+|x-y|^{-\varepsilon}\right\}
\end{aligned}
$$

where $c$ is some constant which does not depend on $L$. From the dominated convergence theorem we get

$$
I \rightarrow \iint_{\mathbb{R}^{2}}|x-y|^{-\alpha} G(x, y) \mathrm{d} x \mathrm{~d} y \text { as } L \rightarrow \infty
$$

Now let us prove that $J \rightarrow 0$, as $L \rightarrow \infty$. Since for any $x \in \mathbb{R},|B(x)| \leqslant 1$, and

$$
J=\frac{L^{\alpha}}{\Phi(L)} \iint_{[L|x-y|<A]} B(L|x-y|) G(x, y) \mathrm{d} x \mathrm{~d} y
$$

we have the estimate

$$
\begin{aligned}
|J| & \leqslant \frac{L^{\alpha}}{\Phi(L)} \iint_{[L|x-y|<A]}|G(x, y)| \mathrm{d} x \mathrm{~d} y \\
& \leqslant \Phi^{-1}(L) \iint_{[L|x-y|<A]} A^{\alpha}|x-y|^{-\alpha}|G(x, y)| \mathrm{d} x \mathrm{~d} y .
\end{aligned}
$$

We have for $\varepsilon>0$,

$$
\begin{aligned}
& \Phi^{-1}(L) \iint_{[L|x-y|<A]} A^{\alpha}|x-y|^{-\alpha}|G(x, y)| \mathrm{d} x \mathrm{~d} y \\
& \quad \leqslant L^{-\varepsilon} \Phi^{-1}(L) \iint_{[L|x-y|<A]} A^{\alpha+\varepsilon}|x-y|^{-(\alpha+\varepsilon)}|G(x, y)| \mathrm{d} x \mathrm{~d} y .
\end{aligned}
$$

But $L^{-\varepsilon} \Phi^{-1}(L) \rightarrow 0$, as $L \rightarrow \infty$, and for $\alpha+\varepsilon<1$, the integral $\iint_{\mathbb{R}^{2}} A^{\alpha+\varepsilon} \mid x-$ $\left.y\right|^{-\alpha-\varepsilon}|G(x, y)| \mathrm{d} x \mathrm{~d} y$ is bounded. It follows that $J \rightarrow 0$, as $L \rightarrow \infty$, whence the condition [ $\mathrm{C}_{1}$ ] is satisfied.

Now we prove the condition $\left[\mathrm{C}_{2}\right]$. Since $\left(\Phi(|L|) / L^{\alpha}\right) \rightarrow 0$, as $L \rightarrow \infty$, then for $L$ large enough, and for some constant $A$, which does not depend on $L$, we have

$$
[B(L|x-y|) \geqslant \varepsilon] \subset\left[|x-y| \leqslant A L^{-1}\right] .
$$

It follows that for any compact set $K$ and for some constant $c$,

$$
\begin{aligned}
\beta(L)^{2} \lambda\left(\left\{(x, y) \in K, B_{1}(L x, L y) \geqslant \varepsilon\right\}\right) & \leqslant \beta(L)^{2} \lambda\left(\left\{(x, y) \in K,|x-y| \leqslant A L^{-1}\right\}\right) \\
& \leqslant c \beta(L)^{2} L^{-1} \rightarrow 0
\end{aligned}
$$

as $L \rightarrow \infty$, whence the desired result.

## Remarks.

(1) Theorem 3.1 can be rephrased as a statement that the stochastic process $\{\exp (\xi(y)), y \in \mathbb{R}\}$ has a large-scale Gaussian limit in the sense of Dobrushin (1980, p. 169) with normalization $A, \beta(L)$. It is well known (Dobrushin, 1979; Dobrushin and Major, 1979) that necessarily, $\beta(L)=L^{\kappa} / \sqrt{\Phi(L)}$, for some constant $\kappa \in \mathbb{R}$. The function $\Phi(L)$ is slowly varying, as $L \rightarrow \infty$, and locally bounded. From that we conclude that if $B(x, y) \rightarrow 0$, as $x, y$ go to infinity, and satisfies condition [ $\left.\mathrm{C}_{1}\right]$ of Corollary 3.1 with the normalization $\beta(L)=L^{\kappa} / \sqrt{\Phi(L)}$ with $0<\kappa<\frac{1}{2}$, then condition [ $\mathrm{C}_{2}$ ] holds.
(2) If instead of $\left.B(x)=\left(\Phi(|x|) /|x|^{\alpha}\right), \alpha \in\right] 0,1[$, we suppose only that $B(x) \sim$ $\left(\Phi(|x|) /|x|^{\alpha}\right)$, as $x \rightarrow \infty$, and $B(x) \leqslant 1$ for any $x \in \mathbb{R}$, we can show, essentially in the same way, that the conditions $\left[\mathrm{C}_{1}\right]$ and $\left[\mathrm{C}_{2}\right]$ still hold. Such a situation happens if the function $f$ which defines the covariance function $B$ satisfies the following conditions:
(A1) $\int_{\mathbb{R}} f^{2}(x) \mathrm{d} x<\infty$.
(A2) $|f(x)| \leqslant C x^{H_{0}-3 / 2} \Phi(x)$ for almost all $x>0$, and $1-1 / 2 m<H_{0}<1$ for some integer $m \geqslant 1$. Here $\Phi$ is a slowly varying function at $+\infty$.
(A3) $f(x) \sim x^{H_{0}-3 / 2} \Phi(x)$ as $x \rightarrow \infty$.
(A4) There exists a constant $\gamma$ satisfying $0<\gamma<\min \left\{H_{0}-(1-1 / 2 m), 1-H_{0}\right\}$, such that

$$
\int_{-\infty}^{0}|f(u) f(x y+u)| \mathrm{d} u=\mathrm{o}\left(x^{2 H_{0}-2} \Phi(x)\right) y^{2 H_{0}-2-2 \gamma}
$$

as $x \rightarrow \infty$, uniformly in $y \in(0, t]$, for a given $t>0$. See Taqqu (1979, p. 57, Section 2) for more details.

Corollary 3.3. Let $\xi(x)=\int_{\mathbb{R}} f(x, y) \mathrm{d} W(y)-\|f(x, \cdot)\|^{2} / 2$.
(A) If $f(x, y)=\Phi(|x|)|x|^{-\alpha} h(y), \Phi$ is slowly varying at $\infty ; 0<\alpha<\frac{1}{2}$, and $\|h\|=1$, then, for all $\varphi \in \mathscr{S}(\mathbb{R})$, as $L \rightarrow \infty$,

$$
\frac{L^{\alpha}}{\Phi(L)} \int_{\mathbb{R}}[\exp (\xi(L y))-1] \varphi(y) \mathrm{d} y
$$

converges in distribution to $\int_{\mathbb{R}} \varphi(y) Z(\mathrm{~d} y):=(Z, \varphi)$, where $Z$ is a Gaussian field whose covariance function is

$$
\operatorname{cov}\left(\left(Z, \varphi_{1}\right),\left(Z, \varphi_{2}\right)\right)=\iint_{\mathbb{R}^{2}} \varphi_{1}\left(y_{1}\right) \varphi_{2}\left(y_{2}\right) \frac{\mathrm{d} y_{1} \mathrm{~d} y_{2}}{\left|y_{1}\right|^{\alpha}\left|y_{2}\right|^{\alpha}} .
$$

(B) Suppose that $f(x, \cdot)=f(|x|, \cdot) \geqslant 0, \forall x \in \mathbb{R}$, non-increasing with respect to $x$, and for all $x \neq 0$

$$
\left(\int_{\mathbb{R}} f^{2}(L, z) \mathrm{d} z\right)^{-1 / 2} f(L x, \cdot)
$$

converges in $L^{2}(\mathbb{R})$ to some function $g(x, \cdot)$. We suppose also that the covariance function $B_{1}(x, y):=\langle f(|x|, \cdot), f(|y|, \cdot)\rangle$ is slowly varying at infinity, namely, for all $x \neq 0, y \neq 0$,

$$
\lim _{L \rightarrow \infty} \frac{B_{1}(L x, L y)}{B_{1}(L, L)}=\int_{\mathbb{R}} g(x, z) g(y, z) \mathrm{d} z:=m(x, y)
$$

and that $m(L x, L y)=L^{-\alpha} m(x, y)$, for some $0<\alpha<1$.
Then $B_{1}(L, L)^{-1 / 2} \int_{\mathbb{R}} \varphi(y)[\exp (\xi(L y))-1] \mathrm{d} y$ converges, as $L \rightarrow \infty$, to $(Z, \varphi)$, where $Z$ is a Gaussian field with covariance function $\operatorname{cov}\left(\left(Z, \varphi_{1}\right),\left(Z, \varphi_{2}\right)\right)=$ $\iint_{\mathbb{R}^{2}} \varphi_{1}(x) \varphi_{2}(y) m(x, y) \mathrm{d} x \mathrm{~d} y$.

Proof. We use Corollary 3.1 for the proof. In the assertion (A), we have $B_{k}(x, y)=$ $\left(\Phi(x)^{k} \Phi^{k}(y)\right) /\left(|x|^{k \alpha}|y|^{k \alpha}\right)$, and it is easy to see, for all $k \geqslant 2$, that $\left|B_{k}(x, y)\right| \leqslant\left|B_{2}(x, y)\right|$.

Let us prove the condition [C $\mathrm{C}_{1}$ ] of Corollary 3.1, with $\beta(L)=\left(L^{\alpha} / \Phi(L)\right)$, and $\mu=$ $\left(\mathrm{d} x \mathrm{~d} y /|x|^{\alpha}|y|^{\alpha}\right)$. We split $\iint_{\mathbb{R}^{2}} \beta(L)^{2} B_{1}(L x, L y) G(x, y) \mathrm{d} x \mathrm{~d} y=I+J$, where

$$
I=\iint_{[L(|x|+|y|)>A]} \beta^{2}(L) B_{1}(L x, L y) G(x, y) \mathrm{d} x \mathrm{~d} y
$$

and $J=\iint_{[L(|x|+|y|) \leqslant A]} \beta^{2}(L) B_{1}(L x, L y) G(x, y) \mathrm{d} x \mathrm{~d} y$. Let us prove that $I \rightarrow$ $\iint_{\mathbb{R}^{2}}|x|^{-\alpha}|y|^{-\alpha} G(x, y) \mathrm{d} x \mathrm{~d} y$, as $L \rightarrow \infty$. From (13), we have for all $\varepsilon>0$, and for $L$ large enough,

$$
\left|\Phi(L|x|) \Phi(L)^{-1}\right|=\exp \left\{u(L|x|)-u(L)+\int_{L}^{L|x|} \frac{\mathrm{e}(z)}{z} \mathrm{~d} z\right\} \leqslant c\left\{|x|^{\varepsilon}+|x|^{-\varepsilon}\right\}
$$

where $c$ is constant which does not depend on $L$. From the dominated convergence theorem we get

$$
I \rightarrow \iint_{\mathbb{R}^{2}}|x|^{-\alpha}|y|^{-\alpha} G(x, y) \mathrm{d} x \mathrm{~d} y \quad \text { as } L \rightarrow \infty
$$

Now let us prove that $J \rightarrow 0$ as $L \rightarrow \infty$. Since for any $(x, y) \in \mathbb{R}^{2},\left|B_{1}(x, y)\right| \leqslant 1$, and

$$
J=\frac{L^{2 \alpha}}{\Phi^{2}(L)} \iint_{[L(|x|+|y|)<A]} B_{1}(L x, L y) G(x, y) \mathrm{d} x \mathrm{~d} y
$$

we have the estimate

$$
\begin{aligned}
|J| & \leqslant \frac{L^{2 \alpha}}{\Phi^{2}(L)} \iint_{[L(|x|+|y|)<A]}|G(x, y)| \mathrm{d} x \mathrm{~d} y \\
& \leqslant \Phi^{-2}(L) \iint_{[L(|x|+|y|)<A]} A^{2 \alpha}(|x|+|y|)^{-2 \alpha}|G(x, y)| \mathrm{d} x \mathrm{~d} y
\end{aligned}
$$

We have for $\varepsilon>0$,

$$
\begin{aligned}
& \Phi^{-2}(L) \iint_{[L(|x|+|y|)<A]} A^{2 \alpha}(|x|+|y|)^{-2 \alpha}|G(x, y)| \mathrm{d} x \mathrm{~d} y \\
& \quad \leqslant L^{-\varepsilon} \Phi^{-2}(L) \iint_{[L(|x|+|y|)<A]} A^{2 \alpha+\varepsilon}(|x|+|y|)^{-(2 \alpha+\varepsilon)}|G(x, y)| \mathrm{d} x \mathrm{~d} y
\end{aligned}
$$

If $2 \alpha+\varepsilon<1$, then the integral $\iint_{\mathbb{R}^{2}} A^{\alpha+\varepsilon}(|x|+|y|)^{-(2 \alpha+\varepsilon)}|G(x, y)| \mathrm{d} x \mathrm{~d} y$ is bounded. From that, and from the fact that $L^{-\varepsilon} \Phi^{-2}(L) \rightarrow 0$, as $L \rightarrow \infty$, we have $J \rightarrow 0$ as $L \rightarrow \infty$, whence the condition $\left[\mathrm{C}_{1}\right]$ is satisfied.

Now, we prove the condition [ $\mathrm{C}_{2}$ ]. Since $B_{1}(x, y) \rightarrow 0$, as $|x|+|y| \rightarrow \infty$, then for $L$ large enough, and for some constant $A$, which does not depend on $L$, we have

$$
\left[B_{1}(L x, L y) \geqslant \varepsilon\right] \subset\left[|x|+|y| \leqslant A L^{-1}\right]
$$

It follows that for any compact set $K$, and for some constant $c$,

$$
\begin{aligned}
\beta(L)^{2} \lambda\left(\left\{(x, y) \in K, B_{1}(L x, L y) \geqslant \varepsilon\right\}\right) & \leqslant \beta(L)^{2} \lambda\left(\left\{(x, y) \in K,|x|+|y| \leqslant A L^{-1}\right\}\right) \\
& \leqslant c \beta(L)^{2} L^{-2} \rightarrow 0,
\end{aligned}
$$

as $L \rightarrow \infty$, which yields the desired result.
Now we prove the assertion (B). To prove [C $\mathrm{C}_{1}$ ] it is sufficient to take $G>0$. Let $a>0, b>0$. We split $B_{1}(L, L)^{-1} \iint_{\mathbb{R}^{2}} B_{1}(L x, L y) G(x, y) \mathrm{d} x \mathrm{~d} y=I+J$, where

$$
I=\iint_{[|x|>a,|y|>b]} B_{1}(L, L)^{-1} B_{1}(L x, L y) G(x, y) \mathrm{d} x \mathrm{~d} y
$$

and

$$
J=\iint_{[|x| \leqslant a] \cup[|y| \leqslant b]} B_{1}(L, L)^{-1} B_{1}(L x, L y) G(x, y) \mathrm{d} x \mathrm{~d} y .
$$

From the monotonicity of $B$, and the dominated convergence theorem we have

$$
I \rightarrow \iint_{[|x|>a,|y|>b]} G(x, y) m(x, y) \mathrm{d} x \mathrm{~d} y \quad \text { as } L \rightarrow \infty
$$

Now,

$$
G(x, y) B_{1}(L, L)^{-1} B_{1}(L x, L y) 1_{[0<|x|<|y|]} \leqslant G(x, y) B_{1}(L, L)^{-1} B_{1}(L x, L x) 1_{[0<|x|<|y|]}
$$

and each of these functions converges as $L \rightarrow \infty$. Using the same proof as in Corollary 3.2 we show that the integral of the latter function converges. Combining the fact that $\iint_{[0,1]^{2}} m(x, y) \mathrm{d} x \mathrm{~d} y<\infty$, see Haan and Resnick (1979), with the following variant of Fatou's lemma: if $0 \leqslant h_{n} \leqslant g_{n}$ are real-valued functions on some measure space, and $h_{n} \rightarrow h, g_{n} \rightarrow g$, then $\int h_{n} \rightarrow \int h$ provided $\int g<\infty$, we can show that

$$
J \rightarrow \iint_{[|x| \leqslant a] \cup[|y| \leqslant b]} G(x, y) m(x, y) \mathrm{d} x \mathrm{~d} y
$$

which yields $\left[\mathrm{C}_{1}\right]$. [ $\left.\mathrm{C}_{2}\right]$ follows from the fact that $B_{1}(x, y) \rightarrow 0$ as $x, y \rightarrow \infty$ and from $B_{1}(L, L) \sim L^{-\alpha}$, as $L \rightarrow \infty$.

We finish this work by considering the case where $\left\langle f\left(y_{1}, \cdot\right), f\left(y_{2}, \cdot\right)\right\rangle=0$ for $\left|y_{1}\right|+$ $\left|y_{2}\right| \geqslant 1$. This example is out of the scope of Theorem 3.1. The covariance function $B_{1}$ is positive and vanishing outside the ball $|x|+|y| \leqslant 1$, then the condition [ $\mathrm{C}_{1}$ ] holds with $\beta(L)=L$ but [ $\mathrm{C}_{2}$ ] does not hold. We want to prove the following theorem.

Theorem 3.2. Under the latter hypothesis we have for all $\varphi \in \mathscr{S}(\mathbb{R})$

$$
L \int_{\mathbb{R}} \varphi(y)\left[\exp \left\{\int f(L y, u) \mathrm{d} W(u)-\frac{B_{1}(L y, L y)}{2}\right\}-1\right] \mathrm{d} y \rightarrow \mathscr{N}\left(0, \varphi^{2}(0) c\right)
$$

where $c=\iint_{\mathbb{R}^{2}}\left(\exp \left\{B_{1}(x, y)\right\}-1\right) \mathrm{d} x \mathrm{~d} y$, and

$$
L^{2} u\left(L x, L^{2} t\right) \rightarrow c \frac{x Z}{t}
$$

where $Z$ is a normal random variable.

Proof. We will use the technique of Theorem 1.1 in Hu and Woyczynski (1995). Let us prove that

$$
L \int_{-\infty}^{\infty} \varphi(y)\left[\exp \left\{\int f(L y, u) \mathrm{d} W(u)-\frac{B_{1}(L y, L y)}{2}\right\}-1\right] \mathrm{d} y
$$

converges in distribution to $\mathscr{N}\left(0, \varphi(0)^{2} c\right)$. Let

$$
H(L)=L \int_{-\infty}^{-L} \varphi(y)\left[\exp \left\{\int f(L y, u) \mathrm{d} W(u)-\frac{B_{1}(L y, L y)}{2}\right\}-1\right] \mathrm{d} y .
$$

Then

$$
\mathbb{E}\left[|H(L)|^{2}\right] \leqslant k L^{2}\left(\int_{-\infty}^{-L} \varphi(y) \mathrm{d} y\right)^{2} .
$$

Using Chebyshev's inequality and since $\varphi \in \mathscr{S}(\mathbb{R})$ we get $H(L) \rightarrow 0$ in probability as $L \rightarrow \infty$. Similarly, we can get as $L \rightarrow \infty$ the convergence in probability to 0 of

$$
L \int_{L}^{\infty} \varphi(y)\left[\exp \left\{\int f(L y, u) \mathrm{d} W(u)-\frac{B_{1}(L y, L y)}{2}\right\}-1\right] \mathrm{d} y .
$$

The remainder term is

$$
\begin{aligned}
& L \int_{-L}^{L} \varphi(y)\left[\exp \left\{\int f(L y, u) \mathrm{d} W(u)-\frac{B_{1}(L y, L y)}{2}\right\}-1\right] \mathrm{d} y \\
& \quad=I+\sum_{-L^{2} \leqslant k \leqslant L^{2}} \eta_{k}(L),
\end{aligned}
$$

where

$$
\eta_{k}(L)=L \int_{k / L}^{(k+1) / L} \varphi(y)\left[\exp \left\{\int f(L y, u) \mathrm{d} W(u)-\frac{B_{1}(L y, L y)}{2}\right\}-1\right] \mathrm{d} y
$$

and $I$ converges in probability to 0 . Since $B\left(L y_{1}, L y_{2}\right)=\int_{\mathbb{R}} f\left(L y_{1}, u\right) f\left(L y_{2}, u\right) \mathrm{d} u=$ 0 for $y_{1} \in[k / L,(k+1) / L], y_{2} \in[j / L,(j+1) / L]$ with $|k-j|>2$, then the sequence $\eta_{k}(L),-L^{2} \leqslant k \leqslant L^{2}$ is 2-dependent sequence. It is useful to recall the following Bulinskii (1987) result: let $X_{j}(t), j \in U(t)$ be an $m(t)$-dependent field on a finite set $U(t) \subset \mathbb{Z}$, and let, for some $s \in(2,3]$ and all $t>0$,

$$
\sup _{j \in U(t)}\left(\mathbb{E}\left[\left|X_{j}(t)\right|^{s}\right]\right)^{1 / s}=\mathrm{C}_{s}(t)<\infty .
$$

Then

$$
\begin{aligned}
\sup _{x \in \mathbb{R}} \mid & \mathbb{P}\left(\delta^{-1}(t) \sum_{j \in U(t)}\left(X_{j}(t)-\mathbb{E}\left[X_{j}(t)\right]\right) \leqslant x\right)-F(x) \mid \\
& \leqslant k_{0}|U(t)| M_{s}^{s}(t) m^{s-1}(t)+M_{s}(t) m(t)+|U(t)|^{1 / 2} M_{s}^{2}(t) m^{2 / s}(t),
\end{aligned}
$$

where $\delta^{2}(t)=\operatorname{Var} \sum_{j \in U(t)} X_{j}(t), k_{0}$ is some constant, $|U(t)|$ is a number of points in $U(t), M_{s}(t)=\delta^{-1}(t) \mathrm{C}_{s}(t)$, and $F(x)$ is the distribution function of $\mathrm{N}(0,1)$.

Now we return to our proof. For $\left(\eta_{k}(L),-L^{2} \leqslant k \leqslant L^{2}\right)$ we get $|U(L)|=2 L^{2}, \mathrm{C}_{3}(L) \leqslant$ $k_{1} L^{-1}, 0<k_{2} \leqslant \delta(L) \leqslant k_{3}, \quad M_{3}(L) \leqslant k_{4} L^{-1}$, and then we have

$$
k_{0}|U(L)| M_{3}^{3}(L) 2^{2}+M_{3}(L) 2+|U(L)|^{1 / 2} M_{3}^{2}(L) 2^{2 / 3} \leqslant k L^{-1},
$$

so that

$$
L \int_{-\infty}^{\infty} \varphi(y)\left[\exp \left\{\int f(L y, u) \mathrm{d} W(u)-\frac{\|f(L y)\|^{2}}{2}\right\}-1\right] \mathrm{d} y \rightarrow \mathscr{N}\left(0, \varphi(0)^{2} c\right)
$$

Now part (i) of Theorem 2.1 combined with Remark 2.1 achieve the proof.

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