



Hybrid shrinking projection method for a generalized equilibrium problem, a maximal monotone operator and a countable family of relatively nonexpansive mappings

Lu-Chuan Ceng^{a,b}, Sy-Ming Guu^{c,*}, H.-Y. Hu^d, Jen-Chih Yao^e

^a Department of Mathematics, Shanghai Normal University, Shanghai 200234, China

^b Scientific Computing Key Laboratory of Shanghai Universities, China

^c College of Management, Yuan-Ze University, Chung-Li City, Taoyuan Hsien, 33026, Taiwan

^d Department of Mathematics, Shanghai Normal University, Shanghai 200234, China

^e Center for General Education, Kaohsiung Medical University, Kaohsiung, 807, Taiwan

ARTICLE INFO

Article history:

Received 18 February 2011

Accepted 18 February 2011

Keywords:

Generalized equilibrium problem

Relatively nonexpansive mapping

Maximal monotone operator

Hybrid shrinking projection method

Strong convergence

Uniformly smooth and uniformly convex Banach space

ABSTRACT

The purpose of this paper is to introduce and consider a hybrid shrinking projection method for finding a common element of the set EP of solutions of a generalized equilibrium problem, the set $\bigcap_{n=0}^{\infty} F(S_n)$ of common fixed points of a countable family of relatively nonexpansive mappings $\{S_n\}_{n=0}^{\infty}$ and the set $T^{-1}0$ of zeros of a maximal monotone operator T in a uniformly smooth and uniformly convex Banach space. It is proven that under appropriate conditions, the sequence generated by the hybrid shrinking projection method, converges strongly to some point in $EP \cap T^{-1}0 \cap (\bigcap_{n=0}^{\infty} F(S_n))$. This new result represents the improvement, complement and development of the previously known ones in the literature.

© 2011 Elsevier Ltd. All rights reserved.

1. Introduction

Let E be a real Banach space with the dual E^* and C be a nonempty closed convex subset of E . We denote by \mathcal{N} and \mathcal{R} the sets of nonnegative integers and real numbers, respectively. Also, we denote by J the normalized duality mapping from E to 2^{E^*} defined by

$$Jx = \{x^* \in E^* : \langle x, x^* \rangle = \|x\|^2 = \|x^*\|^2\}, \quad \forall x \in E,$$

where $\langle \cdot, \cdot \rangle$ denotes the generalized duality pairing. Recall that if E is smooth then J is single-valued and norm-to-weak* continuous, and that if E is uniformly smooth, then J is uniformly norm-to-norm continuous on bounded subsets of E . We shall still denote by J the single-valued duality mapping. Let $A : C \rightarrow E^*$ be a nonlinear mapping and $f : C \times C \rightarrow \mathcal{R}$ be a bifunction. Then, consider the following generalized equilibrium problem:

$$\text{Find } u \in C \text{ such that } f(u, y) + \langle Au, y - u \rangle \geq 0, \quad \forall y \in C. \quad (1.1)$$

The set of solutions of (1.1) is denoted by EP , i.e.,

$$EP = \{u \in C : f(u, y) + \langle Au, y - u \rangle \geq 0, \quad \forall y \in C\}.$$

Whenever $E = H$ a Hilbert space, problem (1.1) was introduced and studied by Takahashi and Takahashi [1].

* Corresponding author. Tel.: +886 3 463-8800x2250; fax: +886 3 435 4604.

E-mail addresses: zenglc@hotmail.com (L.-C. Ceng), iesmguu@saturn.yzu.edu.tw, iesmguu@gmail.com (S.-M. Guu), yaojc@kmu.edu.tw (J.-C. Yao).

Whenever $A \equiv 0$, problem (1.1) is equivalent to finding $u \in C$ such that

$$f(u, y) \geq 0, \quad \forall y \in C,$$

which is called the equilibrium problem. The set of its solutions is denoted by $EP(f)$.

Whenever $f \equiv 0$, problem (1.1) is equivalent to finding $u \in C$ such that

$$\langle Au, y - u \rangle \geq 0, \quad \forall y \in C,$$

which is called the variational inequality of Browder type. The set of its solutions is denoted by $VI(C, A)$.

Problem (1.1) is very general in the sense that it includes, as special cases, optimization problems, variational inequalities, minimax problems, the Nash equilibrium problem in noncooperative games and others; see, e.g., [2,3]. A mapping $S : C \rightarrow E$ is called nonexpansive if $\|Sx - Sy\| \leq \|x - y\|$ for all $x, y \in C$. Denote by $F(S)$ the set of fixed points of S , that is, $F(S) = \{x \in C : Sx = x\}$. A mapping $A : C \rightarrow E^*$ is called α -inverse-strongly monotone, if there exists an $\alpha > 0$ such that

$$\langle Ax - Ay, x - y \rangle \geq \alpha \|Ax - Ay\|^2, \quad \forall x, y \in C.$$

It is easy to see that if $A : C \rightarrow E^*$ is an α -inverse-strongly monotone mapping, then it is $1/\alpha$ -Lipschitzian.

Very recently, motivated by Takahashi and Zembayashi [4], Chang [5] has been proved the following strong convergence theorem for finding a common element of the set of solutions to the generalized equilibrium problem (1.1) and the set of common fixed points of a pair of relatively nonexpansive mappings in a Banach space.

Theorem SSC (See [5, Theorem 3.1]). *Let E be a uniformly smooth and uniformly convex Banach space, and C be a nonempty closed convex subset of E . Let $A : C \rightarrow E^*$ be an α -inverse-strongly monotone mapping and $f : C \times C \rightarrow \mathcal{R}$ be a bifunction satisfying the following conditions (A1)–(A4):*

- (A1) $f(x, x) = 0$ for all $x \in C$,
- (A2) f is monotone, i.e., $f(x, y) + f(y, x) \leq 0$, for all $x, y \in C$,
- (A3) for all $x, y, z \in C$, $\limsup_{t \downarrow 0} f(tz + (1-t)x, y) \leq f(x, y)$,
- (A4) for all $x \in C$, $f(x, \cdot)$ is convex and lower semicontinuous.

Let $S, \tilde{S} : C \rightarrow C$ be two relatively nonexpansive mappings such that $F(S) \cap F(\tilde{S}) \cap EP \neq \emptyset$. Let $\{x_n\}$ be the sequence generated by

$$\begin{cases} x_0 \in C, & C_0 = C; \\ z_n = J^{-1}(\alpha_n x_n + (1 - \alpha_n)JSx_n), \\ y_n = J^{-1}(\beta_n x_n + (1 - \beta_n)J\tilde{S}z_n), \\ u_n \in C \text{ such that } f(u_n, y) + \langle Au_n, y - u_n \rangle + \frac{1}{r_n}(y - u_n, Ju_n - Jy_n) \geq 0, \quad \forall y \in C, \\ C_{n+1} = \{v \in C_n : \phi(v, u_n) \leq \beta_n \phi(v, x_n) + (1 - \beta_n)\phi(v, z_n) \leq \phi(v, x_n)\}; \\ x_{n+1} = \Pi_{C_{n+1}} x_0, \quad \forall n \geq 0, \end{cases} \tag{1.2}$$

where $\phi(x, y) = \|x\|^2 - 2\langle x, Jy \rangle + \|y\|^2$, $\forall x, y \in E$, $\Pi_C : E \rightarrow C$ is the generalized projection operator, $J : E \rightarrow E^*$ is the single-valued normalized duality mapping, $\{\alpha_n\}$ and $\{\beta_n\}$ are sequences in $[0, 1]$ and $\{r_n\} \subset [a, \infty)$ for some $a > 0$. If the following conditions are satisfied:

- (i) $\liminf_{n \rightarrow \infty} \alpha_n(1 - \alpha_n) > 0$,
- (ii) $\liminf_{n \rightarrow \infty} \beta_n(1 - \beta_n) > 0$,

then $\{x_n\}$ converges strongly to $\Pi_{F(S) \cap F(\tilde{S}) \cap EP} x_0$, where $\Pi_{F(S) \cap F(\tilde{S}) \cap EP}$ is the generalized projection of E onto $F(S) \cap F(\tilde{S}) \cap EP$.

Let E be a real Banach space with the dual E^* . A multivalued operator $T : E \rightarrow 2^{E^*}$ with domain $D(T) = \{z \in E : Tz \neq \emptyset\}$ is called monotone if $\langle x_1 - x_2, y_1 - y_2 \rangle \geq 0$ for each $x_i \in D(T)$ and $y_i \in Tx_i$, $i = 1, 2$. A monotone operator T is called maximal if its graph $G(T) = \{(x, y) : y \in Tx\}$ is not properly contained in the graph of any other monotone operator. A method for solving the inclusion $0 \in Tx$ is the proximal point algorithm. Denote by I the identity operator on $E = H$ a Hilbert space. The proximal point algorithm generates, for any initial point $x_0 = x \in H$, a sequence $\{x_n\}$ in H , by the iterative scheme

$$x_{n+1} = (I + r_n T)^{-1} x_n, \quad n = 0, 1, 2, \dots,$$

where $\{r_n\}$ is a sequence in the interval $(0, \infty)$. Note that this iteration is equivalent to

$$0 \in Tx_{n+1} + \frac{1}{r_n}(x_{n+1} - x_n), \quad n = 0, 1, 2, \dots$$

This algorithm was first introduced by Martinet [2] and generally studied by Rockafellar [6] in the framework of a Hilbert space. Later many authors studied its convergence in a Hilbert space or a Banach space. See for instance, [7–12] and the references therein. Kamimura and Takahashi [13] have been recently introduced and studied the proximal-type algorithm

for finding an element of $T^{-1}0$ in a uniformly smooth and uniformly convex Banach space E , which is an extension of Solodov and Svaiter’s proximal-type algorithm. They derived a strong convergence theorem which extends and improves Solodov and Svaiter’s result [14].

Recently, utilizing Nakajo and Takahashi’s idea [15], Qin and Su [16] have been introduced one iterative algorithm (i.e., modified Ishikawa iteration) for a relatively nonexpansive mapping $S : C \rightarrow C$, with C a closed convex subset of a uniformly smooth and uniformly convex Banach space E

$$\begin{cases} x_0 \in C \text{ arbitrarily chosen,} \\ z_n = J^{-1}(\beta_n Jx_n + (1 - \beta_n)JSx_n), \\ y_n = J^{-1}(\alpha_n Jx_n + (1 - \alpha_n)JSz_n), \\ C_n = \{v \in C : \phi(v, y_n) \leq \alpha_n \phi(v, x_n) + (1 - \alpha_n)\phi(v, z_n)\}, \\ Q_n = \{v \in C : \langle x_n - v, Jx_0 - Jx_n \rangle \geq 0\}, \\ x_{n+1} = \Pi_{C_n \cap Q_n} x_0. \end{cases} \tag{1.3}$$

They proved that under appropriate conditions the sequence $\{x_n\}$ generated by algorithm (1.3), converges strongly to $\Pi_{F(S)}x_0$.

Let E be a real Banach space with the dual E^* . Assume that $T : E \rightarrow 2^{E^*}$ is a maximal monotone operator and $S : E \rightarrow E$ is a relatively nonexpansive mapping. Very recently, by combining Kamimura and Takahashi’s idea [13] with Qin and Su [16], Ceng et al. [17] have been introduced a hybrid proximal-type algorithm for finding an element of $F(S) \cap T^{-1}0$ in a uniformly smooth and uniformly convex Banach space E . The authors proved that under appropriate conditions the sequence $\{x_n\}$ generated by the algorithm, converges strongly to $\Pi_{F(S) \cap T^{-1}0}x_0$.

Let E be a reflexive, strictly convex, and smooth Banach space with the dual E^* and C be a nonempty closed convex subset of E . Let $T : E \rightarrow 2^{E^*}$ be a maximal monotone operator, and $\{S_n\}_{n=0}^\infty$ be a countable family of relatively nonexpansive self-mappings on C . Let $A : C \rightarrow E^*$ be an α -inverse-strongly monotone mapping and $f : C \times C \rightarrow \mathcal{R}$ be a bifunction satisfying (A1)–(A4). The purpose of this paper is to introduce and investigate a hybrid shrinking projection method for finding an element of $EP \cap T^{-1} \cap (\bigcap_{n=0}^\infty F(S_n))$, i.e., the following iterative algorithm

$$\begin{cases} x_0 \in C_0 \text{ arbitrarily chosen,} \\ z_n = J^{-1}(\alpha_n Jx_n + (1 - \alpha_n)JS_n x_n), \\ y_n = J^{-1}(\beta_n Jx_n + (1 - \beta_n)Jr_n z_n), \\ u_n \in C \text{ such that } f(u_n, y) + \langle Au_n, y - u_n \rangle + \frac{1}{r_n} \langle y - u_n, Ju_n - Jy_n \rangle \geq 0, \quad \forall y \in C, \\ C_{n+1} = \{v \in C_n : \phi(v, u_n) \leq \beta_n \phi(v, x_n) + (1 - \beta_n)\phi(v, z_n) \leq \phi(v, x_n)\}, \\ x_{n+1} = \Pi_{C_{n+1}} x_0, \quad n = 0, 1, 2, \dots, \end{cases} \tag{1.4}$$

where $C_0 = C, J_{r_n} = (J + r_n T)^{-1}J, \forall n \geq 0, \{r_n\}_{n=0}^\infty$ is a sequence in $(0, \infty)$ and $\{\alpha_n\}_{n=0}^\infty, \{\beta_n\}_{n=0}^\infty$ are sequences in $[0, 1]$.

In this paper, a strong convergence result for our hybrid shrinking projection method is established in a uniformly smooth and uniformly convex Banach space; that is, under appropriate conditions, the sequence $\{x_n\}$ generated by algorithm (1.4), converges strongly to $\Pi_{EP \cap T^{-1}0 \cap (\bigcap_{n=0}^\infty F(S_n))}x_0$. Our result improves and extends some well-known results in [5,13,14,16,17].

Throughout this paper, the symbol \rightharpoonup stands for weak convergence and \rightarrow for strong convergence.

2. Preliminaries

Let E be a real Banach space with the dual E^* . We denote by J the normalized duality mapping from E to 2^{E^*} defined by

$$Jx = \{x^* \in E^* : \langle x, x^* \rangle = \|x\|^2 = \|x^*\|^2\}, \quad \forall x \in X,$$

where $\langle \cdot, \cdot \rangle$ denotes the generalized duality pairing. A Banach space E is called strictly convex if $\|\frac{x+y}{2}\| < 1$ for all $x, y \in E$ with $\|x\| = \|y\| = 1$ and $x \neq y$. It is said to be uniformly convex if $x_n - y_n \rightarrow 0$ for any two sequences $\{x_n\}, \{y_n\} \subset E$ such that $\|x_n\| = \|y_n\| = 1$ and $\lim_{n \rightarrow \infty} \|\frac{x_n + y_n}{2}\| = 1$. Let $U = \{x \in E : \|x\| = 1\}$ be a unit sphere of E . Then the Banach space E is called smooth if

$$\lim_{t \rightarrow 0} \frac{\|x + ty\| - \|x\|}{t}$$

exists for each $x, y \in U$. If E is smooth then J is single-valued. We shall still denote the single-valued duality mapping by J .

It is also said to be uniformly smooth if the limit is attained uniformly for $x, y \in U$. Recall also that if E is uniformly smooth, then J is uniformly norm-to-norm continuous on bounded subsets of E . A Banach space E is said to have the Kadec–Klee property if for any sequence $\{x_n\} \subset E$, whenever $x_n \rightarrow x \in E$ and $\|x_n\| \rightarrow \|x\|$, we have $x_n \rightarrow x$. It is known that if E is uniformly convex, then E has the Kadec–Klee property; see [18,19] for more details.

Let C be a nonempty closed convex subset of a real Hilbert space H and $P_C : H \rightarrow C$ be the metric projection of H onto C . Then P_C is nonexpansive. This fact actually characterizes Hilbert spaces and hence, it is not available in more general Banach spaces. Nevertheless, Alber [20] has been recently introduced a generalized projection operator Π_C in a Banach space E which is an analogue of the metric projection in Hilbert spaces.

Next, we assume that E is a smooth Banach space. Consider the functional defined as in [20,21] by

$$\phi(x, y) = \|x\|^2 - 2\langle x, Jy \rangle + \|y\|^2, \quad \forall x, y \in E. \tag{2.1}$$

It is clear that in a Hilbert space H , (2.1) reduces to $\phi(x, y) = \|x - y\|^2, \forall x, y \in H$.

The generalized projection $\Pi_C : E \rightarrow C$ is a mapping that assigns to an arbitrary point $x \in E$ the minimum point of the functional $\phi(y, x)$; that is, $\Pi_C x = \bar{x}$, where \bar{x} is the solution to the minimization problem

$$\phi(\bar{x}, x) = \min_{y \in C} \phi(y, x). \tag{2.2}$$

The existence and uniqueness of the operator Π_C follows from the properties of the functional $\phi(x, y)$ and strict monotonicity of the mapping J (see, e.g., [22]). In a Hilbert space $H, \Pi_C = P_C$. From [2], in uniformly smooth and uniformly convex Banach spaces, we have

$$(\|x\| - \|y\|)^2 \leq \phi(x, y) \leq (\|x\| + \|y\|)^2, \quad \forall x, y \in E. \tag{2.3}$$

Let C be a nonempty closed convex subset of E , and let S be a mapping from C into itself. A point $p \in C$ is called an asymptotically fixed point of S [23] if C contains a sequence $\{x_n\}$ which converges weakly to p such that $Sx_n - x_n \rightarrow 0$. The set of asymptotical fixed points of S will be denoted by $\widehat{F}(S)$. A mapping S from C into itself is called relatively nonexpansive [24–26] if $F(S) = F(S)$ and $\phi(p, Sx) \leq \phi(p, x)$ for all $x \in C$ and $p \in F(S)$.

We remark that if E is a reflexive, strictly convex and smooth Banach space, then for any $x, y \in E, \phi(x, y) = 0$ if and only if $x = y$. It is sufficient to show that if $\phi(x, y) = 0$ then $x = y$. From (2.3), we have $\|x\| = \|y\|$. This implies that $\langle x, Jy \rangle = \|x\|^2 = \|y\|^2$. From the definition of J , we have $Jx = Jy$. Therefore, we have $x = y$; see [18,19] for more details.

We need the following lemmas for the proof of our main results.

Lemma 2.1 (See [13]). *Let E be a smooth and uniformly convex Banach space and let $\{x_n\}$ and $\{y_n\}$ be two sequences of E . If $\phi(x_n, y_n) \rightarrow 0$ and either $\{x_n\}$ or $\{y_n\}$ is bounded, then $x_n - y_n \rightarrow 0$.*

Lemma 2.2 (See [13,20]). *Let C be a nonempty closed convex subset of a smooth, strictly convex and reflexive Banach space E , let $x \in E$ and let $z \in C$. Then*

$$z = \Pi_C x \Leftrightarrow \langle y - z, Jx - Jz \rangle \leq 0, \quad \forall y \in C.$$

Lemma 2.3 (See [13,20]). *Let C be a nonempty closed convex subset of a smooth, strictly convex and reflexive Banach space E . Then*

$$\phi(x, \Pi_C y) + \phi(\Pi_C y, y) \leq \phi(x, y), \quad \forall x \in C \text{ and } y \in E.$$

Lemma 2.4 (See [27]). *Let C be a nonempty closed convex subset of a reflexive, strictly convex and smooth Banach space E , and let $S : C \rightarrow C$ be a relatively nonexpansive mapping. Then $F(S)$ is closed and convex.*

The following result is due to Blum and Oettli [28].

Lemma 2.5 (See [28]). *Let C be a nonempty closed convex subset of a smooth, strictly convex and reflexive Banach space E , let f be a bifunction from $C \times C$ to \mathcal{R} satisfying (A1)–(A4). Then*

$$f(z, y) + \frac{1}{r} \langle y - z, Jz - Jx \rangle \geq 0, \quad \text{for all } y \in C.$$

Motivated by Combettes and Hirstoaga [29] in a Hilbert space, Takahashi and Zembayashi [11] established the following lemma.

Lemma 2.6 (See [4]). *Let C be a nonempty closed convex subset of a uniformly smooth, strictly convex and reflexive Banach space E , and let f be a bifunction from $C \times C$ to \mathcal{R} satisfying (A1)–(A4). For $r > 0$ and $x \in E$, define a mapping $T_r : E \rightarrow C$ as follows:*

$$T_r(x) = \left\{ z \in C : f(z, y) + \frac{1}{r} \langle y - z, Jz - Jx \rangle \geq 0, \text{ for all } y \in C \right\}$$

for all $x \in E$. Then, the following statements hold.

- (i) T_r is single-valued.
- (ii) T_r is a firmly nonexpansive-type mapping, i.e., for all $x, y \in E$,

$$\langle T_r x - T_r y, JT_r x - JT_r y \rangle \leq \langle T_r x - T_r y, Jx - Jy \rangle.$$

- (iii) $F(T_r) = \widehat{F}(T_r) = EP(f)$.
- (iv) $EP(f)$ is closed and convex.

Using Lemma 2.6, one has the following result.

Lemma 2.7 (See [4]). Let C be a nonempty closed convex subset of a smooth, strictly convex and reflexive Banach space E , let f be a bifunction from $C \times C$ to \mathcal{R} satisfying (A1)–(A4), and let $r > 0$. Then, for $x \in E$ and $q \in F(T_r)$,

$$\phi(q, T_r x) + \phi(T_r x, x) \leq \phi(q, x).$$

Utilizing Lemmas 2.5–2.7 as above, Chang [5] derived the following result.

Proposition 2.1 (See [5, Lemma 2.5]). Let E be a smooth, strictly convex and reflexive Banach space and C be a nonempty closed convex subset of E . Let $A : C \rightarrow E^*$ be an α -inverse-strongly monotone mapping, let f be a bifunction from $C \times C$ to \mathcal{R} satisfying (A1)–(A4), and let $r > 0$. Then the following statements hold.

(I) for $x \in E$, there exists $u \in C$ such that

$$f(u, y) + \langle Au, y - u \rangle + \frac{1}{r} \langle y - u, Ju - Jx \rangle \geq 0, \quad \forall y \in C;$$

(II) if E is additionally uniformly smooth and $K_r : E \rightarrow C$ is defined as

$$K_r(x) = \left\{ u \in C : f(u, y) + \langle Au, y - u \rangle + \frac{1}{r} \langle y - u, Ju - Jx \rangle \geq 0, \forall y \in C \right\}, \quad \forall x \in E, \quad (2.4)$$

then the mapping K_r has the following properties.

- (i) K_r is single-valued,
- (ii) K_r is a firmly nonexpansive-type mapping, i.e.,

$$\langle K_r x - K_r y, JK_r x - JK_r y \rangle \leq \langle K_r x - K_r y, Jx - Jy \rangle, \quad \forall x, y \in E,$$

(iii) $F(K_r) = \widehat{F}(K_r) = EP$,

(iv) EP is a closed convex subset of C ,

(v) $\phi(p, K_r x) + \phi(K_r x, x) \leq \phi(p, x)$, $\forall p \in F(K_r)$.

Proof. Define a bifunction $F : C \times C \rightarrow \mathcal{R}$ as follows:

$$F(x, y) = f(x, y) + \langle Ax, y - x \rangle, \quad \forall x, y \in C.$$

Then it is easy to verify that F satisfies conditions (A1)–(A4). Therefore, statements (I) and (II) of Proposition 2.1 follow immediately from Lemmas 2.5–2.7. \square

Let $T : E \rightarrow 2^{E^*}$ be a maximal monotone operator in a smooth Banach space E . We denote the resolvent of T by $J_r := (J + rT)^{-1}J$ for each $r > 0$. Then $J_r : E \rightarrow D(T)$ is a single-valued mapping. Also, $T^{-1}0 = F(J_r)$ for each $r > 0$, where $F(J_r)$ is the set of fixed points of J_r . For each $r > 0$, the Yosida approximation of T is defined by $A_r = (J - J_r)/r$. It is known that

$$A_r x \in T(J_r x), \quad \text{for each } r > 0 \text{ and } x \in E. \quad (2.5)$$

Lemma 2.8 (Rockafellar [30]). Let E be a reflexive, strictly convex, and smooth Banach space and let $T : E \rightarrow 2^{E^*}$ be a multivalued operator. Then the following statements hold.

- (i) $T^{-1}0$ is closed and convex if T is maximal monotone such that $T^{-1}0 \neq \emptyset$.
- (ii) T is maximal monotone if and only if T is monotone with $R(J + rT) = E^*$ for all $r > 0$.

Lemma 2.9. Let E be a reflexive, strictly convex, and smooth Banach space, and let $T : E \rightarrow 2^{E^*}$ be a maximal monotone operator with $T^{-1}0 \neq \emptyset$. Then the following statements hold.

- (i) (see [3]) $\phi(z, J_r x) + \phi(J_r x, x) \leq \phi(z, x)$ for all $r > 0$, $z \in T^{-1}0$ and $x \in E$.
- (ii) (see [5]) $J_r : E \rightarrow D(T)$ is a relatively nonexpansive mapping.

3. Main results

Throughout this section, unless otherwise stated, we assume that $\{S_n\}_{n=0}^{\infty}$ is a countable family of relatively nonexpansive self-mappings on C , $T : E \rightarrow 2^{E^*}$ is a maximal monotone operator, $A : C \rightarrow E^*$ is an α -inverse-strongly monotone mapping and $f : C \times C \rightarrow \mathcal{R}$ is a bifunction satisfying (A1)–(A4), where C is a nonempty closed convex subset of a reflexive, strictly

convex, and smooth Banach space E . Let $EP \cap T^{-1}0 \cap (\bigcap_{n=0}^{\infty} F(S_n)) \neq \emptyset$. In this section, we study the following algorithm for finding an element of $EP \cap T^{-1}0 \cap (\bigcap_{n=0}^{\infty} F(S_n))$.

$$\begin{cases} x_0 \in C_0 \text{ arbitrarily chosen,} \\ z_n = J^{-1}(\alpha_n Jx_n + (1 - \alpha_n)JS_n x_n), \\ y_n = J^{-1}(\beta_n Jx_n + (1 - \beta_n)Jr_n z_n), \\ u_n \in C \text{ such that } f(u_n, y) + \langle Au_n, y - u_n \rangle + \frac{1}{r_n}(y - u_n, Ju_n - Jy_n) \geq 0, \quad \forall y \in C, \\ C_{n+1} = \{v \in C_n : \phi(v, u_n) \leq \beta_n \phi(v, x_n) + (1 - \beta_n)\phi(v, z_n) \leq \phi(v, x_n)\}, \\ x_{n+1} = \Pi_{C_{n+1}} x_0, \quad n = 0, 1, 2, \dots, \end{cases} \tag{3.1}$$

where $C_0 = C$, $\{r_n\}_{n=0}^{\infty}$ is a sequence in $(0, \infty)$ and $\{\alpha_n\}_{n=0}^{\infty}, \{\beta_n\}_{n=0}^{\infty}$ are sequences in $[0, 1]$.

First we investigate the condition under which algorithm (3.1) is well defined.

Lemma 3.1. *Let E be a reflexive, strictly convex, and smooth Banach space. If $EP \cap T^{-1}0 \cap (\bigcap_{n=0}^{\infty} F(S_n)) \neq \emptyset$, then the sequence $\{x_n\}$ generated by algorithm (3.1) is well defined.*

Proof. First, let us show that C_n is a closed and convex subset of C for all $n \geq 0$. Indeed, observe that

$$\begin{aligned} \phi(v, u_n) &\leq \beta_n \phi(v, x_n) + (1 - \beta_n)\phi(v, z_n) \\ \Leftrightarrow 2\langle v, (1 - \beta_n)Jz_n + \beta_n Jx_n - Ju_n \rangle &\leq (1 - \beta_n)\|z_n\|^2 - \|u_n\|^2 + \beta_n \|x_n\|^2 \end{aligned}$$

and

$$\begin{aligned} \beta_n \phi(v, x_n) + (1 - \beta_n)\phi(v, z_n) &\leq \phi(v, x_n) \\ \Leftrightarrow \phi(v, z_n) &\leq \phi(v, x_n) \\ \Leftrightarrow 2\langle v, Jx_n - Jz_n \rangle &\leq \|x_n\|^2 - \|z_n\|^2. \end{aligned}$$

Hence C_n is closed and convex for each $n \geq 0$.

Second, let us show that $EP \cap T^{-1}0 \cap (\bigcap_{n=0}^{\infty} F(S_n)) \subset C_n$ for each $n \geq 0$.

Indeed, it is clear that $EP \cap T^{-1}0 \cap (\bigcap_{n=0}^{\infty} F(S_n)) \subset C_0 = C$. Suppose that $EP \cap T^{-1}0 \cap (\bigcap_{n=0}^{\infty} F(S_n)) \subset C_n$ for some $n \in \mathcal{N}$. Let $w \in EP \cap T^{-1}0 \cap (\bigcap_{n=0}^{\infty} F(S_n))$ be arbitrarily chosen. Then $w \in EP$, $w \in T^{-1}0$ and $w \in \bigcap_{n=0}^{\infty} F(S_n)$. Since $u_n = K_{r_n} y_n$, utilizing (3.1) and Proposition 2.1 we have

$$\begin{aligned} \phi(w, u_n) &= \phi(w, K_{r_n} y_n) \leq \phi(w, y_n) \\ &= \phi(w, J^{-1}(\beta_n Jx_n + (1 - \beta_n)Jr_n z_n)) \\ &= \|w\|^2 - 2\langle w, \beta_n Jx_n + (1 - \beta_n)Jr_n z_n \rangle + \|\beta_n Jx_n + (1 - \beta_n)Jr_n z_n\|^2 \\ &\leq \|w\|^2 - 2\beta_n \langle w, Jx_n \rangle - 2(1 - \beta_n)\langle w, Jr_n z_n \rangle + \beta_n \|x_n\|^2 + (1 - \beta_n)\|Jr_n z_n\|^2 \\ &= \beta_n \phi(w, x_n) + (1 - \beta_n)\phi(w, Jr_n z_n) \\ &\leq \beta_n \phi(w, x_n) + (1 - \beta_n)\phi(w, z_n) \quad (\text{using Lemma 2.9}) \\ &= \beta_n \phi(w, x_n) + (1 - \beta_n)\phi(w, J^{-1}(\alpha_n Jx_n + (1 - \alpha_n)JS_n x_n)) \\ &= \beta_n \phi(w, x_n) + (1 - \beta_n)[\|w\|^2 - 2\langle w, \alpha_n Jx_n + (1 - \alpha_n)JS_n x_n \rangle + \|\alpha_n Jx_n + (1 - \alpha_n)JS_n x_n\|^2] \\ &\leq \beta_n \phi(w, x_n) + (1 - \beta_n)[\|w\|^2 - 2\alpha_n \langle w, Jx_n \rangle - 2(1 - \alpha_n)\langle w, JS_n x_n \rangle + \alpha_n \|x_n\|^2 + (1 - \alpha_n)\|S_n x_n\|^2] \\ &= \beta_n \phi(w, x_n) + (1 - \beta_n)[\alpha_n \phi(w, x_n) + (1 - \alpha_n)\phi(w, S_n x_n)] \\ &\leq \beta_n \phi(w, x_n) + (1 - \beta_n)[\alpha_n \phi(w, x_n) + (1 - \alpha_n)\phi(w, x_n)] \\ &= \phi(w, x_n). \end{aligned}$$

This implies that $w \in C_{n+1}$. This shows that $EP \cap T^{-1}0 \cap (\bigcap_{n=0}^{\infty} F(S_n)) \subset C_n$ for all $n \geq 0$. Therefore $x_{n+1} = \Pi_{C_{n+1}} x_0$ is well defined. Then, by induction, the sequence $\{x_n\}$ generated by (3.1) is well defined for each integer $n \geq 0$. \square

Remark 3.1. From the above proof, we obtain that

$$EP \cap T^{-1}0 \cap \left(\bigcap_{n=0}^{\infty} F(S_n) \right) \subset C_n$$

for each integer $n \geq 0$.

We are now in a position to prove the main theorem.

Theorem 3.1. *Let E be a uniformly smooth and uniformly convex Banach space. Let $\{r_n\}_{n=0}^{\infty}$ be a sequence in $(0, \infty)$ and $\{\alpha_n\}_{n=0}^{\infty}, \{\beta_n\}_{n=0}^{\infty}$ be sequences in $[0, 1]$ such that*

$$\liminf_{n \rightarrow \infty} r_n > 0, \quad \limsup_{n \rightarrow \infty} \alpha_n < 1 \quad \text{and} \quad \limsup_{n \rightarrow \infty} \beta_n < 1. \tag{3.2}$$

Let $EP \cap T^{-1}0 \cap (\bigcap_{n=0}^{\infty} F(S_n)) \neq \emptyset$. If for each integer $m \geq 0$,

$$\lim_{n \rightarrow \infty} \|S_n x_n - S_m x_n\| = 0, \tag{UARC}$$

then the sequence $\{x_n\}$ generated by algorithm (3.1) converges strongly to $\Pi_{EP \cap T^{-1}0 \cap (\bigcap_{n=0}^{\infty} F(S_n))} x_0$.

Proof. We divide the proof into several steps.

Step 1. We claim that $\{x_n\}$ is bounded, and $\phi(x_{n+1}, x_n) \rightarrow 0$.

Indeed, by the definition of C_n , we have $x_n = \Pi_{C_n} x_0, \forall n \geq 0$. Hence from Lemma 2.3 it follows that for each $u \in EP \cap T^{-1}0 \cap (\bigcap_{n=0}^{\infty} F(S_n))$ and each $n \geq 0$,

$$\phi(x_n, x_0) = \phi(\Pi_{C_n} x_0, x_0) \leq \phi(u, x_0) - \phi(u, \Pi_{C_n} x_0) \leq \phi(u, x_0).$$

This implies that $\{\phi(x_n, x_0)\}$ is bounded, and so $\{x_n\}, \{S_n x_n\}, \{J_{r_n} x_n\}$ all are bounded. Furthermore, noticing that $x_n = \Pi_{C_n} x_0$ and $x_{n+1} = \Pi_{C_{n+1}} x_0 \in C_{n+1} \subset C_n$, we have

$$\phi(x_n, x_0) \leq \phi(x_{n+1}, x_0), \quad \forall n \geq 0.$$

Thus, $\{\phi(x_n, x_0)\}$ is nondecreasing, and so the limit $\lim_{n \rightarrow \infty} \phi(x_n, x_0)$ exists. From Lemma 2.3 we have

$$\begin{aligned} \phi(x_{n+1}, x_n) &= \phi(x_{n+1}, \Pi_{C_n} x_0) \leq \phi(x_{n+1}, x_0) - \phi(\Pi_{C_n} x_0, x_0) \\ &= \phi(x_{n+1}, x_0) - \phi(x_n, x_0), \quad \forall n \geq 0, \end{aligned}$$

which leads to $\lim_{n \rightarrow \infty} \phi(x_{n+1}, x_n) = 0$. So from Lemma 2.1 it follows that $\|x_{n+1} - x_n\| \rightarrow 0$.

Step 2. We claim that $\|z_n - J_{r_n} z_n\| \rightarrow 0$ and $\|x_n - S_m x_n\| \rightarrow 0$ for each integer $m \geq 0$.

Indeed, since $x_{n+1} = \Pi_{C_{n+1}} x_0 \in C_{n+1} \subset C_n$, from the definition of C_{n+1} we have

$$\phi(x_{n+1}, u_n) \leq \phi(x_{n+1}, x_n), \quad \forall n \geq 0,$$

and

$$\phi(x_{n+1}, z_n) \leq \phi(x_{n+1}, x_n), \quad \forall n \geq 0.$$

Hence from $\phi(x_{n+1}, x_n) \rightarrow 0$ it follows that $\phi(x_{n+1}, u_n) \rightarrow 0$ and $\phi(x_{n+1}, z_n) \rightarrow 0$. Utilizing Lemma 2.1, we conclude that

$$\lim_{n \rightarrow \infty} \|x_{n+1} - x_n\| = \lim_{n \rightarrow \infty} \|x_{n+1} - u_n\| = \lim_{n \rightarrow \infty} \|x_{n+1} - z_n\| = 0, \tag{3.3}$$

and so

$$\lim_{n \rightarrow \infty} \|x_n - u_n\| = \lim_{n \rightarrow \infty} \|x_n - z_n\| = \lim_{n \rightarrow \infty} \|u_n - z_n\| = 0. \tag{3.4}$$

Again since $u_n = K_{r_n} y_n$, as in the proof of Lemma 3.1 we can deduce that

$$\phi(w, u_n) \leq \phi(w, y_n) \leq \phi(w, x_n), \quad \forall w \in EP \cap T^{-1}0 \cap \left(\bigcap_{n=0}^{\infty} F(S_n)\right). \tag{3.5}$$

Now observe that

$$\begin{aligned} \phi(u_n, y_n) &= \phi(K_{r_n} y_n, y_n) \leq \phi(w, y_n) - \phi(w, K_{r_n} y_n) \quad (\text{using Proposition 2.1}) \\ &\leq \phi(w, x_n) - \phi(w, K_{r_n} y_n) \\ &= \phi(w, x_n) - \phi(w, u_n) \\ &= \|x_n\|^2 - \|u_n\|^2 - 2\langle w, Jx_n - Ju_n \rangle \\ &\leq \|x_n - u_n\|(\|x_n\| + \|u_n\|) + 2\|w\| \|Jx_n - Ju_n\|. \end{aligned}$$

Since $\|x_n - u_n\| \rightarrow 0$ and J is uniformly norm-to-norm continuous on bounded subsets of E , it follows that $\|Jx_n - Ju_n\| \rightarrow 0$ and so $\phi(u_n, y_n) \rightarrow 0$. Since E is smooth and uniformly convex, from Lemma 2.1 and (3.4), we have

$$\|u_n - y_n\| \rightarrow 0, \quad \text{and so } \|x_n - y_n\| \rightarrow 0. \tag{3.6}$$

Note that E is uniformly smooth and uniformly convex. Thus J and J^{-1} are uniformly norm-to-norm continuous on bounded subsets of E and E^* , respectively. Hence from (3.1) and (3.6) we have

$$(1 - \beta_n) \|J_{r_n} z_n - Jx_n\| = \|Jy_n - Jx_n\| \rightarrow 0,$$

and so $\|J_{r_n} z_n - x_n\| \rightarrow 0$. This together with $\|x_n - z_n\| \rightarrow 0$ yields

$$\lim_{n \rightarrow \infty} \|z_n - J_{r_n} z_n\| = \lim_{n \rightarrow \infty} \|Jz_n - J_{r_n} z_n\| = 0. \tag{3.7}$$

Again from (3.1) and (3.4) we have

$$(1 - \alpha_n)\|J S_n x_n - J x_n\| = \|J z_n - J x_n\| \rightarrow 0.$$

This implies that $\|J S_n x_n - J x_n\| \rightarrow 0$, and so

$$\lim_{n \rightarrow \infty} \|x_n - S_n x_n\| = 0. \tag{3.8}$$

Note that for each integer $m \geq 0$,

$$\|x_n - S_m x_n\| \leq \|x_n - S_n x_n\| + \|S_n x_n - S_m x_n\|. \tag{3.9}$$

Thus, from (3.8) and condition (UARC) we infer that for each integer $m \geq 0$,

$$\lim_{n \rightarrow \infty} \|x_n - S_m x_n\| = 0. \tag{3.10}$$

Step 3. We claim that $\omega_w(\{x_n\}) \subset EP \cap T^{-1}0 \cap (\bigcap_{n=0}^{\infty} F(S_n))$, where

$$\omega_w(\{x_n\}) := \{\hat{x} \in C : x_{n_k} \rightarrow \hat{x} \text{ for some subsequence } \{n_k\} \subset \{n\} \text{ with } n_k \uparrow \infty\}.$$

Indeed, for any $\hat{x} \in \omega_w(\{x_n\})$, there exists a subsequence $\{x_{n_k}\} \subset \{x_n\}$ such that $x_{n_k} \rightarrow \hat{x}$. Since S_m is relatively nonexpansive for each integer $m \geq 0$, from (3.10) and $x_{n_k} \rightarrow \hat{x}$ we have

$$\hat{x} \in \widehat{F}(S_m) = F(S_m).$$

Now let us show that $\hat{x} \in T^{-1}0$. Since $x_{n_k} \rightarrow \hat{x}$, from (3.4) and (3.7) it follows that $z_{n_k} \rightarrow \hat{x}$ and $J_{r_{n_k}} z_{n_k} \rightarrow \hat{x}$. Also, from (3.7) and $\liminf_{n \rightarrow \infty} r_n > 0$ we derive

$$\lim_{n \rightarrow \infty} \|A_{r_n} z_n\| = \lim_{n \rightarrow \infty} \frac{1}{r_n} \|J z_n - J_{r_n} z_n\| = 0.$$

If $z^* \in Tz$, then it follows from (2.5) and the monotonicity of the operator T that for all integers $k \geq 0$

$$\langle z - J_{r_{n_k}} z_{n_k}, z^* - A_{r_{n_k}} z_{n_k} \rangle \geq 0.$$

Letting $k \rightarrow \infty$, we obtain $\langle z - \hat{x}, z^* \rangle \geq 0$. Then the maximality of the operator T yields $\hat{x} \in T^{-1}0$.

Next, let us show that $\hat{x} \in EP$. Since $x_{n_k} \rightarrow \hat{x}$, from (3.4) and (3.6) it follows that $u_{n_k} \rightarrow \hat{x}$ and $y_{n_k} \rightarrow \hat{x}$. Since J is uniformly norm-to-norm continuous on bounded subsets of E , from (3.6) we have $\lim_{n \rightarrow \infty} \|J u_n - J y_n\| = 0$. From $\liminf_{n \rightarrow \infty} r_n > 0$, it follows that

$$\lim_{n \rightarrow \infty} \frac{\|J u_n - J y_n\|}{r_n} = 0. \tag{3.11}$$

By the definition of $u_n := K_{r_n} y_n$, we have

$$F(u_n, y) + \frac{1}{r_n} \langle y - u_n, J u_n - J y_n \rangle \geq 0, \quad \forall y \in C,$$

where

$$F(u_n, y) = f(u_n, y) + \langle A u_n, y - u_n \rangle.$$

Replacing n by n_k , we have from (A2) that

$$\frac{1}{r_{n_k}} \langle y - u_{n_k}, J u_{n_k} - J y_{n_k} \rangle \geq -F(u_{n_k}, y) \geq F(y, u_{n_k}), \quad \forall y \in C.$$

Since $y \mapsto f(x, y) + \langle Ax, y - x \rangle$ is convex and lower semicontinuous, it is also weakly lower semicontinuous. Letting $n_k \rightarrow \infty$ in the last inequality, from (3.11) and (A4) we have

$$F(y, \hat{x}) \leq 0, \quad \forall y \in C.$$

For t , with $0 < t \leq 1$, and $y \in C$, let $y_t = ty + (1 - t)\hat{x}$. Since $y \in C$ and $\hat{x} \in C$, then $y_t \in C$ and hence $F(y_t, \hat{x}) \leq 0$. So, from (A1) we have

$$0 = F(y_t, y_t) \leq tF(y_t, y) + (1 - t)F(y_t, \hat{x}) \leq tF(y_t, y).$$

Dividing by t , we have

$$F(y_t, y) \geq 0, \quad \forall y \in C.$$

Letting $t \downarrow 0$, from (A3) it follows that

$$F(\hat{x}, y) \geq 0, \quad \forall y \in C.$$

So, $\hat{x} \in EP$. Therefore, we obtain that $\omega_w(\{x_n\}) \subset EP \cap T^{-1}0 \cap (\bigcap_{n=0}^{\infty} F(S_n))$ by the arbitrariness of \hat{x} .

Step 4. We claim that $\omega_w(\{x_n\}) = \{\Pi_{EP \cap T^{-1}0 \cap (\bigcap_{n=0}^{\infty} F(S_n))} x_0\}$ and $x_n \rightarrow \Pi_{EP \cap T^{-1}0 \cap (\bigcap_{n=0}^{\infty} F(S_n))} x_0$.

Indeed, put $\bar{x} = \Pi_{EP \cap T^{-1}0 \cap (\bigcap_{n=0}^{\infty} F(S_n))} x_0$. From $x_{n+1} = \Pi_{C_{n+1}} x_0$ and $\bar{x} \in EP \cap T^{-1}0 \cap (\bigcap_{n=0}^{\infty} F(S_n)) \subset C_{n+1}$, we have $\phi(x_{n+1}, x_0) \leq \phi(\bar{x}, x_0)$. Now from weakly lower semicontinuity of the norm, we derive for each $\hat{x} \in \omega_w(\{x_n\})$

$$\begin{aligned} \phi(\hat{x}, x_0) &= \|\hat{x}\|^2 - 2\langle \hat{x}, Jx_0 \rangle + \|x_0\|^2 \\ &\leq \liminf_{k \rightarrow \infty} (\|x_{n_k}\|^2 - 2\langle x_{n_k}, Jx_0 \rangle + \|x_0\|^2) \\ &= \liminf_{k \rightarrow \infty} \phi(x_{n_k}, x_0) \\ &\leq \limsup_{k \rightarrow \infty} \phi(x_{n_k}, x_0) \\ &\leq \phi(\bar{x}, x_0). \end{aligned}$$

It follows from the definition of $\Pi_{EP \cap T^{-1}0 \cap (\bigcap_{n=0}^{\infty} F(S_n))} x_0$ that $\hat{x} = \bar{x}$ and hence

$$\lim_{k \rightarrow \infty} \phi(x_{n_k}, x_0) = \phi(\bar{x}, x_0).$$

So we have $\lim_{k \rightarrow \infty} \|x_{n_k}\| = \|\bar{x}\|$. Utilizing the Kadec–Klee property of E , we conclude that $\{x_{n_k}\}$ converges strongly to $\Pi_{EP \cap T^{-1}0 \cap (\bigcap_{n=0}^{\infty} F(S_n))} x_0$. Since $\{x_{n_k}\}$ is an arbitrary weakly convergent subsequence of $\{x_n\}$, we know that $\{x_n\}$ converges strongly to $\Pi_{EP \cap T^{-1}0 \cap (\bigcap_{n=0}^{\infty} F(S_n))} x_0$. This completes the proof. \square

The following corollaries can be obtained from Theorem 3.1 immediately.

Corollary 3.1. Let E and C be the same as in Theorem 3.1. Let $T : E \rightarrow 2^{E^*}$ be a maximal monotone operator, $f : C \times C \rightarrow \mathcal{R}$ be a bifunction satisfying (A1)–(A4), and $\{S_n\}_{n=0}^{\infty}$ be a countable family of relatively nonexpansive self-mappings on C . Let $EP(f) \cap T^{-1}0 \cap (\bigcap_{n=0}^{\infty} F(S_n)) \neq \emptyset$. Let $\{x_n\}$ be the sequence generated by

$$\begin{cases} x_0 \in C, & C_0 = C, \\ z_n = J^{-1}(\alpha_n Jx_n + (1 - \alpha_n)JS_n x_n), \\ y_n = J^{-1}(\beta_n Jx_n + (1 - \beta_n)Jr_n z_n), \\ u_n \in C \text{ such that } f(u_n, y) + \frac{1}{r_n} \langle y - u_n, Ju_n - Jy_n \rangle \geq 0, \quad \forall y \in C, \\ C_{n+1} = \{v \in C_n : \phi(v, u_n) \leq \beta_n \phi(v, x_n) + (1 - \beta_n)\phi(v, z_n) \leq \phi(v, x_n)\}, \\ x_{n+1} = \Pi_{C_{n+1}} x_0, \quad n = 0, 1, 2, \dots, \end{cases} \tag{3.12}$$

where $\{r_n\} \subset (0, \infty)$ and $\{\alpha_n\}, \{\beta_n\} \subset [0, 1]$ satisfy (3.2). If the condition (UARC) is satisfied, then $\{x_n\}$ converges strongly to $\Pi_{EP(f) \cap T^{-1}0 \cap (\bigcap_{n=0}^{\infty} F(S_n))} x_0$.

Proof. Put $A \equiv 0$ in Theorem 3.1. Then $EP = EP(f)$. Hence from Theorem 3.1 we immediately obtain the desired conclusion. \square

Corollary 3.2. Let E and C be the same as in Theorem 3.1. Let $T : E \rightarrow 2^{E^*}$ be a maximal monotone operator, $A : C \rightarrow E^*$ be an α -inverse-strongly monotone mapping, and $\{S_n\}_{n=0}^{\infty}$ be a countable family of relatively nonexpansive self-mappings on C . Let $VI(C, A) \cap T^{-1}0 \cap (\bigcap_{n=0}^{\infty} F(S_n)) \neq \emptyset$. Let $\{x_n\}$ be the sequence generated by

$$\begin{cases} x_0 \in C, & C_0 = C, \\ z_n = J^{-1}(\alpha_n Jx_n + (1 - \alpha_n)JS_n x_n), \\ y_n = J^{-1}(\beta_n Jx_n + (1 - \beta_n)Jr_n z_n), \\ u_n \in C \text{ such that } \langle Au_n, y - u_n \rangle + \frac{1}{r_n} \langle y - u_n, Ju_n - Jy_n \rangle \geq 0, \quad \forall y \in C, \\ C_{n+1} = \{v \in C_n : \phi(v, u_n) \leq \beta_n \phi(v, x_n) + (1 - \beta_n)\phi(v, z_n) \leq \phi(v, x_n)\}, \\ x_{n+1} = \Pi_{C_{n+1}} x_0, \quad n = 0, 1, 2, \dots, \end{cases} \tag{3.13}$$

where $\{r_n\} \subset (0, \infty)$ and $\{\alpha_n\}, \{\beta_n\} \subset [0, 1]$ satisfy (3.2). If the condition (UARC) is satisfied, then $\{x_n\}$ converges strongly to $\Pi_{VI(C, A) \cap T^{-1}0 \cap (\bigcap_{n=0}^{\infty} F(S_n))} x_0$.

Proof. Put $f \equiv 0$ in Theorem 3.1. Then $EP = VI(C, A)$. Hence from Theorem 3.1 we immediately obtain the desired conclusion. \square

Corollary 3.3. Let E and C be the same as in Theorem 3.1. Let $A : C \rightarrow E^*$ be an α -inverse-strongly monotone mapping, $f : C \times C \rightarrow \mathcal{R}$ be a bifunction satisfying (A1)–(A4), and $\{S_n\}_{n=0}^\infty$ be a countable family of relatively nonexpansive self-mappings on C . Let $EP \cap (\bigcap_{n=0}^\infty F(S_n)) \neq \emptyset$. Let $\{x_n\}$ be the sequence generated by

$$\begin{cases} x_0 \in C, & C_0 = C, \\ z_n = J^{-1}(\alpha_n x_n + (1 - \alpha_n) S_n x_n), \\ y_n = J^{-1}(\beta_n x_n + (1 - \beta_n) J z_n), \\ u_n \in C \text{ such that } f(u_n, y) + \langle Au_n, y - u_n \rangle + \frac{1}{r_n} \langle y - u_n, Ju_n - Jy_n \rangle \geq 0, \quad \forall y \in C, \\ C_{n+1} = \{v \in C_n : \phi(v, u_n) \leq \beta_n \phi(v, x_n) + (1 - \beta_n) \phi(v, z_n) \leq \phi(v, x_n)\}, \\ x_{n+1} = \Pi_{C_{n+1}} x_0, \quad n = 0, 1, 2, \dots, \end{cases} \quad (3.14)$$

where $\{r_n\} \subset (0, \infty)$ and $\{\alpha_n\}, \{\beta_n\} \subset [0, 1]$ satisfy (3.2). If the condition (UARC) is satisfied, then $\{x_n\}$ converges strongly to $\Pi_{EP \cap (\bigcap_{n=0}^\infty F(S_n))} x_0$.

Proof. Put $T \equiv 0$ in Theorem 3.1. Then $EP \cap T^{-1}0 \cap (\bigcap_{n=0}^\infty F(S_n)) = EP \cap (\bigcap_{n=0}^\infty F(S_n))$ and $J_r = (J + rT)^{-1}J = I$. Hence from Theorem 3.1 we immediately obtain the desired conclusion. \square

Corollary 3.4. Let E and C be the same as in Theorem 3.1. Let $T : E \rightarrow 2^{E^*}$ be a maximal monotone operator, and $\{S_n\}_{n=0}^\infty$ be a countable family of relatively nonexpansive self-mappings on C such that $T^{-1}0 \cap (\bigcap_{n=0}^\infty F(S_n)) \neq \emptyset$. Let $\{x_n\}$ be the sequence generated by

$$\begin{cases} x_0 \in C, & C_0 = C, \\ z_n = J^{-1}(\alpha_n x_n + (1 - \alpha_n) S_n x_n), \\ y_n = J^{-1}(\beta_n x_n + (1 - \beta_n) J r_n z_n), \\ u_n = \Pi_C y_n, \\ C_{n+1} = \{v \in C_n : \phi(v, u_n) \leq \beta_n \phi(v, x_n) + (1 - \beta_n) \phi(v, z_n) \leq \phi(v, x_n)\}, \\ x_{n+1} = \Pi_{C_{n+1}} x_0, \quad n = 0, 1, 2, \dots, \end{cases} \quad (3.15)$$

where $\{r_n\} \subset (0, \infty)$ and $\{\alpha_n\}, \{\beta_n\} \subset [0, 1]$ satisfy (3.2). If the condition (UARC) is satisfied, then $\{x_n\}$ converges strongly to $\Pi_{T^{-1}0 \cap (\bigcap_{n=0}^\infty F(S_n))} x_0$.

Proof. Put $A \equiv 0$ and $f \equiv 0$ in Theorem 3.1. Then $u_n = \Pi_C y_n, \forall n \geq 0$. Hence from Theorem 3.1 we immediately obtain the desired conclusion. \square

4. Applications

Let E be a reflexive, strictly convex, and smooth Banach space. Let $\tilde{T}, \tilde{T} : E \rightarrow 2^{E^*}$ be two maximal monotone operators. For $r > 0$, define the resolvent of T and \tilde{T} by $J_r = (J + rT)^{-1}J$ and $\tilde{J}_r = (J + r\tilde{T})^{-1}J$, respectively. Then, J_r (resp. \tilde{J}_r) is a single-valued mapping from E to $D(T)$ (resp. from E to $D(\tilde{T})$). Also, for $r > 0$,

$$T^{-1}0 = F(J_r) \quad (\text{resp. } \tilde{T}^{-1}0 = F(\tilde{J}_r)), \quad (4.1)$$

where $F(J_r)$ (resp. $F(\tilde{J}_r)$) is the set of fixed points of J_r (resp. \tilde{J}_r). We can define, for $r > 0$, the Yosida approximation of T (resp. \tilde{T}) by $A_r = (J - J_r)/r$ (resp. $\tilde{A}_r = (J - \tilde{J}_r)/r$). For $r > 0$ and $x \in E$, we know that $A_r x \in T r x$ and $\tilde{A}_r x \in \tilde{T} r x$.

We are now in a position to apply Theorem 3.1 to prove the following result.

Theorem 4.1. Let E be a uniformly smooth and uniformly convex Banach space, $r > 0$ be a positive constant, $A : E \rightarrow E^*$ be an α -inverse-strongly monotone mapping, and $f : E \times E \rightarrow \mathcal{R}$ be a bifunction satisfying (A1)–(A4). Let $T, \tilde{T} : E \rightarrow 2^{E^*}$ be two maximal monotone operators such that $EP \cap T^{-1}0 \cap \tilde{T}^{-1}0 \neq \emptyset$. Let $\{x_n\}$ be the sequence generated by

$$\begin{cases} x_0 \in E, & C_0 = E, \\ z_n = J^{-1}(\alpha_n x_n + (1 - \alpha_n) \tilde{J}_r x_n), \\ y_n = J^{-1}(\beta_n x_n + (1 - \beta_n) J r_n z_n), \\ u_n \in E \text{ such that } f(u_n, y) + \langle Au_n, y - u_n \rangle + \frac{1}{r_n} \langle y - u_n, Ju_n - Jy_n \rangle \geq 0, \quad \forall y \in E, \\ C_{n+1} = \{v \in C_n : \phi(v, u_n) \leq \beta_n \phi(v, x_n) + (1 - \beta_n) \phi(v, z_n) \leq \phi(v, x_n)\}, \\ x_{n+1} = \Pi_{C_{n+1}} x_0, \quad n = 0, 1, 2, \dots, \end{cases} \quad (4.2)$$

where $\{r_n\} \subset (0, \infty)$ and $\{\alpha_n\}, \{\beta_n\} \subset [0, 1]$ satisfy (3.2). Then $\{x_n\}$ converges strongly to $\Pi_{EP \cap T^{-1}0 \cap \tilde{T}^{-1}0} x_0$.

Proof. From (4.1) and Lemma 2.9 it follows that $\tilde{J}_r : E \rightarrow D(\tilde{T})$ is a relatively nonexpansive mapping and $\tilde{T}^{-1}0 = F(\tilde{J}_r)$. Now, in Theorem 3.1, put $S_n = \tilde{J}_r$ for each integer $n \geq 0$. Then it is easy to see that for all $m \geq 0$,

$$\lim_{n \rightarrow \infty} \|S_n x_n - S_m x_n\| = \lim_{n \rightarrow \infty} \|\tilde{J}_r x_n - \tilde{J}_r x_n\| = 0,$$

that is, the condition (UARC) is satisfied. Then from Theorem 3.1 we immediately obtain the desired conclusion. \square

From Theorem 4.1, we can derive the following corollaries.

Corollary 4.1. Let E and $r > 0$ be the same as in Theorem 4.1. Let $A : E \rightarrow E^*$ be an α -inverse-strongly monotone mapping and $T, \tilde{T} : E \rightarrow 2^{E^*}$ be two maximal monotone operators such that $VI(E, A) \cap T^{-1}0 \cap \tilde{T}^{-1}0 \neq \emptyset$. Let $\{x_n\}$ be the sequence generated by

$$\begin{cases} x_0 \in E, & C_0 = E, \\ z_n = J^{-1}(\alpha_n Jx_n + (1 - \alpha_n) \tilde{J}r_n x_n), \\ y_n = J^{-1}(\beta_n Jx_n + (1 - \beta_n) \tilde{J}r_n z_n), \\ u_n \in E \text{ such that } \langle Au_n, y - u_n \rangle + \frac{1}{r_n} \langle y - u_n, Ju_n - Jy_n \rangle \geq 0, \quad \forall y \in E, \\ C_{n+1} = \{v \in C_n : \phi(v, u_n) \leq \beta_n \phi(v, x_n) + (1 - \beta_n) \phi(v, z_n) \leq \phi(v, x_n)\}, \\ x_{n+1} = \Pi_{C_{n+1}} x_0, \quad n = 0, 1, 2, \dots, \end{cases} \quad (4.3)$$

where $\{r_n\} \subset (0, \infty)$ and $\{\alpha_n\}, \{\beta_n\} \subset [0, 1]$ satisfy (3.2). Then $\{x_n\}$ converges strongly to $\Pi_{VI(E, A) \cap T^{-1}0 \cap \tilde{T}^{-1}0} x_0$.

Proof. Put $f \equiv 0$ in Theorem 4.1. Then from Theorem 4.1 we immediately obtain the desired conclusion. \square

Corollary 4.2. Let E and $r > 0$ be the same as in Theorem 4.1. Let $f : E \times E \rightarrow \mathcal{R}$ be a bifunction satisfying (A1)–(A4) and $T, \tilde{T} : E \rightarrow 2^{E^*}$ be two maximal monotone operators such that $EP(f) \cap T^{-1}0 \cap \tilde{T}^{-1}0 \neq \emptyset$. Let $\{x_n\}$ be the sequence generated by

$$\begin{cases} x_0 \in E, & C_0 = E, \\ z_n = J^{-1}(\alpha_n Jx_n + (1 - \alpha_n) \tilde{J}r_n x_n), \\ y_n = J^{-1}(\beta_n Jx_n + (1 - \beta_n) \tilde{J}r_n z_n), \\ u_n \in E \text{ such that } f(u_n, y) + \frac{1}{r_n} \langle y - u_n, Ju_n - Jy_n \rangle \geq 0, \quad \forall y \in E, \\ C_{n+1} = \{v \in C_n : \phi(v, u_n) \leq \beta_n \phi(v, x_n) + (1 - \beta_n) \phi(v, z_n) \leq \phi(v, x_n)\}, \\ x_{n+1} = \Pi_{C_{n+1}} x_0, \quad n = 0, 1, 2, \dots, \end{cases} \quad (4.4)$$

where $\{r_n\} \subset (0, \infty)$ and $\{\alpha_n\}, \{\beta_n\} \subset [0, 1]$ satisfy (3.2). Then $\{x_n\}$ converges strongly to $\Pi_{EP(f) \cap T^{-1}0 \cap \tilde{T}^{-1}0} x_0$.

Proof. Put $A \equiv 0$ in Theorem 4.1. Then from Theorem 4.1 we immediately obtain the desired conclusion. \square

Acknowledgements

The first author's research was partially supported by the National Science Foundation of China (10771141), Ph.D. Program Foundation of Ministry of Education of China (20070270004), Science and Technology Commission of Shanghai Municipality grant (075105118), and Shanghai Leading Academic Discipline Project (S30405). The second author's research was partially supported by the Grant NSC 97-2221-E-155-041-MY3. The fourth author's research was partially supported by the Grant NSC 99-2115-M-110-004-MY3.

References

- [1] S. Takahashi, W. Takahashi, Strong convergence theorem for a generalized equilibrium problem and a nonexpansive mapping in a Hilbert space, *Nonlinear Anal.* 69 (2008) 1025–1033.
- [2] B. Martinet, Regularisation d'inéquations variationnelles par approximations successives, *Rev. Fr. Autom. Inform. Rech. Oper.* 4 (1970) 154–159.
- [3] F. Kohsaka, W. Takahashi, Strong convergence of an iterative sequence for maximal monotone operators in a Banach space, *Abstr. Appl. Anal.* 3 (2004) 239–249.
- [4] W. Takahashi, K. Zembayashi, Strong and weak convergence theorems for equilibrium problems and relatively nonexpansive mappings in Banach spaces, *Nonlinear Anal.* 70 (1) (2009) 45–57.
- [5] S.S. Chang, Shrinking projection method for solving generalized equilibrium problem, variational inequality and common fixed point in Banach spaces with applications, *Sci. China* (in press).
- [6] R.T. Rockafellar, Monotone operators and the proximal point algorithm, *SIAM J. Control Optim.* 14 (1976) 877–898.
- [7] L.C. Ceng, T.C. Lai, J.C. Yao, Approximate proximal algorithms for generalized variational inequalities with paramonotonicity and pseudomonotonicity, *Comput. Math. Appl.* 55 (6) (2008) 1262–1269.
- [8] L.C. Ceng, S.Y. Wu, J.C. Yao, New accuracy criteria for modified approximate proximal point algorithms in Hilbert spaces, *Taiwan. J. Math.* 12 (6) (2008) 1691–1705.
- [9] O. Güler, On the convergence of the proximal point algorithm for convex minimization, *SIAM J. Control Optim.* 29 (1991) 403–419.
- [10] L.C. Ceng, J.C. Yao, Generalized implicit hybrid projection-proximal point algorithm for maximal monotone operators in Hilbert space, *Taiwan. J. Math.* 12 (3) (2008) 753–766.
- [11] L.C. Zeng, J.C. Yao, An inexact proximal-type algorithm in Banach spaces, *J. Optim. Theory Appl.* 135 (1) (2007) 145–161.
- [12] L.C. Ceng, J.C. Yao, Approximate proximal algorithms for generalized variational inequalities with pseudomonotone multifunctions, *J. Comput. Appl. Math.* 213 (2) (2008) 423–438.
- [13] S. Kamimura, W. Takahashi, Strong convergence of a proximal-type algorithm in a Banach space, *SIAM J. Optim.* 13 (2003) 938–945.
- [14] M.V. Solodov, B.F. Svaiter, Forcing strong convergence of proximal point iterations in a Hilbert space, *Math. Program.* 87 (2000) 189–202.
- [15] K. Nakajo, W. Takahashi, Strong convergence theorems for nonexpansive mappings and nonexpansive semigroups, *J. Math. Anal. Appl.* 279 (2003) 372–379.
- [16] X.L. Qin, Y.F. Su, Strong convergence theorems for relatively nonexpansive mappings in a Banach space, *Nonlinear Anal.* 67 (2007) 1958–1965.
- [17] L.C. Ceng, A. Petrusel, S.Y. Wu, On hybrid proximal-type algorithms in Banach spaces, *Taiwan. J. Math.* 12 (8) (2008) 2009–2029.
- [18] I. Cioranescu, *Geometry of Banach Spaces, Duality Mappings and Nonlinear Problems*, Kluwer, Dordrecht, 1990.
- [19] W. Takahashi, *Nonlinear Functional Analysis*, Yokohama-Publishers, 2000.

- [20] Ya. I. Alber, Metric and generalized projection operators in Banach spaces: properties and applications, in: A.G. Kartsatos (Ed.), *Theory and Applications of Nonlinear Operators of Monotonic and Accretive Type*, Marcel Dekker, New York, 1996, pp. 15–50.
- [21] Ya. I. Alber, S. Reich, An iterative method for solving a class of nonlinear operator equations in Banach spaces, *Panamer. Math. J.* 4 (2) (1994) 39–54.
- [22] Ya. I. Alber, S. Guerre-Delabriere, On the projection methods for fixed point problems, *Analysis (Munich)* 21 (2001) 17–39.
- [23] S. Reich, A weak convergence theorem for the alternating method with Bergman distance, in: A.G. Kartsatos (Ed.), *Theory and Applications of Nonlinear Operators of Accretive and Monotone Type*, Marcel Dekker, New York, 1996, pp. 313–318.
- [24] D. Butnariu, S. Reich, A.J. Zaslavski, Asymptotic behavior of relatively nonexpansive operators in Banach spaces, *J. Appl. Anal.* 7 (2001) 151–174.
- [25] D. Butnariu, S. Reich, A.J. Zaslavski, Weak convergence of orbits of nonlinear operators in reflexive Banach spaces, *Numer. Funct. Anal. Optim.* 24 (2003) 489–508.
- [26] Y. Censor, S. Reich, Iterations of paracontractions and firmly nonexpansive operators with applications to feasibility and optimization, *Optimization* 37 (1996) 323–339.
- [27] S. Matsushita, W. Takahashi, A strong convergence theorem for relatively nonexpansive mappings in a Banach space, *J. Approx. Theory* 134 (2005) 257–266.
- [28] E. Blum, W. Oettli, From optimization and variational inequalities to equilibrium problems, *Math. Stud.* 63 (1994) 123–145.
- [29] P.L. Combettes, S.A. Hirstoaga, Equilibrium programming in Hilbert spaces, *J. Nonlinear Convex Anal.* 6 (2005) 117–136.
- [30] R.T. Rockafellar, On the maximality of sums of nonlinear monotone operators, *Trans. Amer. Math. Soc.* 149 (1970) 75–88.