JOURNAL OF MATHEMATICAL ANALYSIS AND APPLICATIONS 145, 17-25 (1990)

# A Note on the Convergence of the Solutions of a Linear Functional Differential Equation\*

T. KRISZTIN

Bolyai Institute, Aradi vértanúk tere 1, 6720 Szeged, Hungary

Submitted by V. Lakshmikantham

Received May 24, 1988

#### 1. INTRODUCTION

Consider the linear, autonomous, scalar differential equation

$$
x'(t) = -\mu_0 x(t) + \int_{-\infty}^0 x(t+s) \, d\mu(s), \tag{1}
$$

where  $\mu_0$  is a real number,  $\mu$ : ( $-\infty$ , 0)  $\rightarrow \mathbf{R}$  is a nondecreasing function, and  $\int_{-\infty}^{0} d\mu < \infty$ .

Equation (1) occurs in certain biological applications (see e.g. [2]).

If  $\mu_0 > \int_{-\infty}^0 d\mu$  then any solution of (1) belonging to a bounded, continuous initial function tends to zero as  $t \to \infty$  (see e.g. [9]).

If  $\mu_0 < \int_{-\infty}^0 d\mu$  then it is easy to see that there are unbounded solutions. More precisely, there is a positive real number  $\lambda_0$  such that  $e^{\lambda_0 t}$  is a solution of  $(1)$  on  $\mathbb{R}$ .

In the critical case  $\mu_0 = \int_{-\infty}^{0} d\mu$  it is shown in [6] that under the condition

$$
\int_{-\infty}^{0} |s| d\mu(s) < \infty \tag{2}
$$

any solution of (1) belonging to a bounded, continuous initial function tends to a constant as  $t \to \infty$ .

The different methods of proving the convergence of solutions of differential equations with infinite delay have the same type of condition for the delay term as  $(2)$  [3-8]. The question arises whether Condition  $(2)$  is

\* Supported in part by the Hungarian National Foundation for Scientific Research with Grant 6032/6319.

## 18 T. KRISZTIN

necessary for the convergence of all solutions of (1) belonging to bounded, continuous initial functions.

The purpose of this paper is to prove that (2) is a sufficient and necessary condition under which all solutions of (1) belonging to bounded, continuous initial functions converge to a finite limit as  $t \to \infty$ .

### 2. PRELIMINARIES

Let **R**,  $\mathbf{R}^-$ ,  $\mathbf{R}^+$  and I be the intervals  $(-\infty, \infty)$ ,  $(-\infty, 0]$ ,  $[0, \infty)$ , and [0, 1], respectively. Let BC denote the set of real-valued bounded, continuous functions on  $\mathbb{R}^-$ . Define IC = { $\varphi \in BC$ :  $\varphi(s) \in I$ }. The function x:  $\mathbb{R} \to \mathbb{R}$  is said to be a solution of (1) on  $\mathbb{R}^+$  through  $(0, \varphi)$ ,  $\varphi \in BC$ , if  $x(s) = \varphi(s)$  for  $s \in \mathbb{R}^-$  and (1) holds on  $\mathbb{R}^+$ . It is easy to see that for any  $\varphi \in BC$  there is a unique solution of (1) through (0,  $\varphi$ ) on **R**<sup>+</sup> [1]. In this paper, by a solution of (1) we always mean a solution through  $(0, \varphi)$  for some  $\varphi \in BC$ , and this solution is denoted by  $x(\varphi)$ .

For a given  $\varphi \in BC$  and  $r \in \mathbb{R}^+$  let us define the set IC<sub>*n*</sub>, by

$$
\mathbf{IC}_{\varphi,r} = \{ \psi \in \mathbf{IC} : \psi(s) = \varphi(s) \text{ for } s \in [-r, 0] \}.
$$

Without loss of generality we may assume that  $\mu$  is normalized such that it is continuous from the left,  $\lim_{s \to -\infty} \mu(s) = 0$ . Then, clearly,  $\int_{-\infty}^{u} d\mu(s) = \mu(u)$  for  $u \le 0$ . Moreover, if (2) holds, then by changing the order of integration we obtain

$$
\int_{-\infty}^{0} |s| d\mu(s) = \int_{-\infty}^{0} \left( \int_{s}^{0} du \right) d\mu(s)
$$
  
= 
$$
\int_{-\infty}^{0} \left( \int_{-\infty}^{u} d\mu(s) \right) du = \int_{-\infty}^{0} \mu(u) du,
$$
 (3)

that is,  $\mu$  is integrable on  $\mathbb{R}^-$ .

#### 3. THE RESULT

The sufficiency of Condition (2) is contained in a more general result in [6]. A different method is used in [5] to obtain the sufficiency of  $(2)$ whenever the initial functions are bounded and uniformly continuous on  $R^-$ . For the sake of completeness, we also give here a proof of the sufficiency of (2) for arbitrary initial functions from BC by using the idea of [S].

**THEOREM.** Assume  $\mu_0 = \int_{-\infty}^0 d\mu$ . Then all solutions of (1) converge to a finite limit as  $t \to \infty$  if and only if (2) holds.

*Proof.* Sufficiency of (2). Let  $\varphi \in BC$  be given and let  $x = x(\varphi)$ . Define  $M=\sup_{s\leq 0}x(s)$  and  $m=\inf_{s\leq 0}x(s)$ . First we show that  $x(t)\in [m, M]$  for  $t \geq 0$ , that is, x is bounded. Let

$$
u(t)=\max_{0\leq s\leq t}\bigl\{x(t),\,M\bigr\}.
$$

If  $x(t) < u(t)$  then  $D^+u(t) \stackrel{\text{def}}{=} \limsup_{h \to 0+} (1/h)(u(t+h)-u(t)) = 0$ . If  $x(t) = u(t)$  then clearly  $D^+u(t) \leq max\{0, x'(t)\}$ . On the other hand,  $x(t) = u(t)$  implies  $x(t) \ge x(t+s)$  for all  $s \le 0$ . Thus, from Eq. (1) we get that  $x'(t) \le 0$ . Therefore  $D^+u(t) \le 0$  for all  $t \ge 0$ . Consequently,  $x(t) \le$  $u(t) \leq M$  for all  $t \geq 0$ . Similarly,  $x(t) \geq m$  for all  $t \geq 0$ , which was stated.

Let  $a = \liminf_{t \to \infty} x(t)$ ,  $b = \limsup_{t \to \infty} x(t)$ . For the existence of  $\lim_{t \to \infty} x(t)$  it suffices to prove that  $a = b$ . Suppose the contrary, i.e.,  $a < b$ . Let  $c \in (a, b)$  and let  $\varepsilon > 0$  be given such that

$$
b+\varepsilon+\tfrac{1}{2}(c-b-\varepsilon)\exp\bigg(-\int_{-\infty}^0\mu(s)\,ds\bigg)< b.
$$

There exists such an  $\epsilon > 0$  by continuity, because the left hand side of the inequality is less than b at  $\varepsilon = 0$ . The function  $\mu$  is integrable on  $R^-$  by (3).

Let  $T_1$  be defined such that  $t \geq T_1$  implies  $x(t) \leq b + \varepsilon$ . Choose  $T_2 \geq T_1$ such that  $x(T_2) = c$  and

$$
(M-m)\int_{T_2}^{\infty}\mu(T_1-u)\,du<\tfrac{1}{2}(b+\varepsilon-c)\exp\bigg(-\int_{-\infty}^0\mu(s)\,ds\bigg).
$$

For  $t \ge T_2$  let

$$
v(t)=\max_{T_2\leq s\leq t}x(s).
$$

Now,  $x(t) < v(t)$  implies  $D^+v(t) = 0$ , and  $x(t) = v(t)$ ,  $x'(t) \le 0$  imply  $D^+v(t) \leq 0$ . Assume that  $x(t) = v(t)$  and  $x'(t) > 0$ . Then  $D^+v(t) \leq x'(t)$  and by using Eq.  $(1)$ 

$$
x'(t) = \left(\int_{-\infty}^{T_1-t} + \int_{T_1-t}^{T_2-t} + \int_{T_2-t}^{0}\right) (x(t+s) - x(t)) d\mu(s)
$$
  
\n
$$
\leq \int_{T_1-t}^{T_2-t} (b + \varepsilon - x(t)) d\mu(s) + (M-m) \int_{-\infty}^{T_1-t} d\mu(s)
$$
  
\n
$$
\leq \int_{-\infty}^{T_2-t} d\mu(s) (b + \varepsilon - x(t)) + (M-m) \int_{-\infty}^{T_1-t} d\mu(s).
$$

## 20 T. KRISZTIN

Since the right-hand side of this inequality is nonnegative for  $t \geq T_1$ , we have

$$
D^{+}v(t)\leqslant \int_{-\infty}^{T_{2}-t}d\mu(s)(b+\varepsilon-v(t))+(M-m)\int_{-\infty}^{T_{1}-t}d\mu(s)
$$

for all  $t \ge T_2$ . Using that  $v(T_2) = c$  and a well-known differential inequality, one obtains for  $t \ge T_2$  that

$$
v(t) \leq b + \varepsilon + (c - b - \varepsilon) \exp\left(-\int_{T_2}^t \int_{-\infty}^{T_2 - u} d\mu(s) du\right)
$$
  
+ 
$$
\int_{T_2}^t (M - m) \int_{-\infty}^{T_1 - u} d\mu(s) \exp\left(-\int_u^t \int_{-\infty}^{T_2 - \tau} d\mu(s) dt\right) du
$$
  

$$
\leq b + \varepsilon + (c - b - \varepsilon)
$$
  

$$
\times \exp\left(-\int_{T_2}^t \mu(T_2 - u) du\right) + \int_{T_2}^t (M - m) \mu(T_1 - u) du
$$
  

$$
\leq b + \varepsilon + \frac{1}{2}(c - b - \varepsilon) \exp\left(-\int_{-\infty}^0 \mu(s) ds\right) < b,
$$

which implies  $\limsup_{t\to\infty} x(t) < b$ , a contradiction. Thus,  $\lim_{t\to\infty} x(t)$ exists.

Necessity of  $(2)$ . First we show the following simple statements.

*Claim* 1. If  $\varphi \in \text{IC}$  then  $0 \leq x(\varphi)(t) \leq 1$  for  $t \geq 0$ .

Proof. This is the same as that of the boundedness in the proof of the sufficiency of  $(2)$ .

*Claim* 2. If  $\varphi \in BC$  and  $\varphi$  has compact support (i.e.,  $\varphi$  is zero outside of a compact subset of  $R^-$ ), then for  $t \ge 0$  we have

$$
x(\varphi)(t) + \int_{-\infty}^{0} \int_{t+s}^{t} x(\varphi)(u) du d\mu(s)
$$
  
=  $\varphi(0) + \int_{-\infty}^{0} \int_{s}^{0} \varphi(u) du d\mu(s).$  (4)

*Proof.* (4) can be obtained from Eq. (1) by integrating it from 0 to t and using the fact that

$$
\int_{-\infty}^{0} (x(\varphi)(t) - x(\varphi)(t+s)) d\mu(s)
$$
  
= 
$$
\int_{-\infty}^{0} \frac{d}{dt} \int_{t+s}^{t} x(\varphi)(u) du d\mu(s)
$$
  
= 
$$
\frac{d}{dt} \int_{-\infty}^{0} \int_{t+s}^{t} x(\varphi)(u) du d\mu(s),
$$

since  $\varphi$  has compact support.

*Claim* 3. If  $\varphi \in \text{IC}$  and  $\varphi$  has compact support, then either  $x(\varphi)(t) \to 0$ or  $x(\varphi)(t)$  does not converge as  $t \to \infty$ . Similarly, if  $\varphi \in IC$  and  $1 - \varphi$  has compact support, then either  $x(\varphi)(t) \to 1$  or  $x(\varphi)(t)$  does not converge as  $t\rightarrow\infty$ .

*Proof.* By Claim 1,  $x(\varphi)(t) \in I$  for  $t \ge 0$ . Suppose the contrary, i.e.,  $x(\varphi)(t)\to\alpha, \ \alpha\in(0, 1]$ . If T is so large that  $x(\varphi)(t)\geq \alpha/2$  for  $t\geq T$ , then for  $t \geqslant T$ 

$$
x(\varphi)(t)+\int_{-\infty}^0\int_{t+s}^t x(\varphi)(u)\,du\,d\mu(s)\geqslant \frac{\alpha}{2}\int_{T-t}^0|s|\,d\mu(s).
$$

Hence and from  $\int_{-\infty}^{0} |s| d\mu(s) = \infty$ , the left-hand side of (4) tends to infinity as  $t \to \infty$ . This is impossible since  $\varphi$  has compact support and thus the right-hand side of (4) is a finite constant. The second part can be shown from the first one by applying it for  $1-\varphi$  and using that  $x(1 - \varphi)(t) = 1 - x(\varphi)(t).$ 

Claim 4. For any  $T > 0$ ,  $\varepsilon > 0$  there exists  $r = r(T, \varepsilon) > 0$  such that for all  $\varphi \in IC$  and  $\psi \in IC_{a}$ ,

$$
|x(\varphi)(t) - x(\psi)(t)| < \varepsilon \ (t \in [0, T]).
$$

*Proof.* Let  $y(t) = x(\varphi)(t) - x(\psi)(t)$  for  $t \in R$ . Then  $y(t) = 0$  for  $t \in [-r, 0]$  and we have

$$
y'(t) = -\mu_0 y(t) + f(r, t) + \int_{-t}^{0} y(t+s) d\mu(s) \qquad (t \ge 0),
$$

where  $f(r, t) = \int_{-\infty}^{-t} \frac{1}{2} r(r + s) d\mu(s)$ . From  $\varphi, \psi \in IC$  it follows that  $f(r, t) \rightarrow 0$  as  $r \rightarrow \infty$  uniformly in t on [0, T]. Let  $\delta > 0$  be given and let r be so large that  $|f(r, t)| < \delta$  for  $t \in [0, T]$ . Define  $z(t) = |y(t)|$ ,  $t \in R$ . It is easy to see that

$$
D^+z(t) \leq -\mu_0 z(t) + \delta + \int_{-t}^0 z(t+s) \, d\mu(s) \qquad (t \in [0, T]).
$$

Multiply this inequality by  $e^{\mu_0 t}$  and define  $v(t) = e^{\mu_0 t} z(t)$ ,  $t \in R$ . Obviously

$$
D^+v(t)\leq e^{\mu_0T}\delta+e^{\mu_0T}\int_{-t}^0v(t+s)\,d\mu(s)\qquad(t\in[0,T]).
$$

By integrating on [0, t],  $0 \le t \le T$ , changing the order of integration, and using  $v(0) = 0$ , we get

$$
v(t) \le e^{\mu_0 T} \delta t + e^{\mu_0 T} \int_0^t \int_{-u}^0 v(u+s) \, d\mu(s) \, du
$$
  
=  $e^{\mu_0 T} \delta t + e^{\mu_0 T} \int_{-t}^0 \int_0^{t+s} v(u) \, du \, d\mu(s)$   
 $\le e^{\mu_0 T} T \delta + \mu_0 e^{\mu_0 T} \int_0^t v(u) \, du \qquad (t \in [0, T]).$ 

Applying Gronwall's inequality, one obtains that

$$
v(t) \leq e^{\mu_0 T} T \exp(\mu_0 T e^{\mu_0 T}) \cdot \delta \quad (t \in [0, T]),
$$

which completes the proof of Claim 4.

Now, we give a function  $\varphi \in IC$  such that  $x(\varphi)(t)$  does not converge as  $t \rightarrow \infty$ . Two cases can be distinguished by Claim 3.

Case 1. There is a function  $\varphi \in IC$  such that either  $\varphi$  or  $1 - \varphi$  has compact support and  $x(\varphi)(t)$  does not converge as  $t \to \infty$ .

Case 2. If  $\varphi \in IC$  and  $\varphi$  has compact support, then  $x(\varphi)(t) \to 0$  as  $t \to \infty$ . If  $\varphi \in IC$  and  $1 - \varphi$  has compact support, then  $x(\varphi)(t) \to 1$ as  $t\rightarrow\infty$ .

If Case 1 holds, there is nothing to prove. Assume that Case 2 is satisfied. Let  $\psi_0$  be given by

$$
\psi_0(s) = \begin{cases} s+1 & \text{if } s \in [-1,0] \\ 0 & \text{if } s < -1 \end{cases}
$$

(see Fig. 1). Then  $x(\psi_0)(t) \to 0$  as  $t \to \infty$ . So there exists  $t_0 > 0$  such that  $x(\psi_0)(t_0) < 1/3$ . Claim 4 implies that there is  $r_0 > 1$  such that for any  $\psi \in IC_{\psi_0, r_0}$  one has  $x(\psi)(t_0) < 1/3$ .

Let  $\psi_1 \in IC_{\psi_0,r_0}$  be defined by

$$
\psi_1(s) = \begin{cases} \psi_0(s) & \text{if } s \in [-r_0, 0] \\ -s - r_0 & \text{if } s \in [-r_0 - 1, -r_0] \\ 1 & \text{if } s < -r_0 - 1 \end{cases}
$$

(see Fig. 1). Then  $1 - \psi_1$  has compact support. Therefore,  $x(\psi_1)(t) \rightarrow 1$  as  $t \to \infty$ . It follows that there is  $t_1 > \max\{1, t_0\}$  such that  $x(\psi_1)(t_1) > 2/3$ . By Claim 4 there exists  $r_1 > r_0 + 1$  such that for all  $\psi \in IC_{\psi_1,r_1}$  one has  $x(\psi)(t_1) > 2/3.$ 

Suppose that  $r_0, r_1, ..., r_{2k-1}, t_0, t_1, ..., t_{2k-1}$  and  $\psi_0, \psi_1, ..., \psi_{2k-1}$  are given,  $k \ge 1$ .

Let us define  $\psi_{2k} \in IC_{\psi_{2k-1},\psi_{2k-1}}$  as

$$
\psi_{2k}(s) = \begin{cases} \psi_{2k-1}(s) & \text{if } s \in [-r_{2k-1}, 0] \\ s + r_{2k-1} + 1 & \text{if } s \in [-r_{2k-1} - 1, -r_{2k-1}] \\ 0 & \text{if } s < -r_{2k-1} - 1 \end{cases}
$$

(see Fig. 1). Then  $x(\psi_{2k})(t) \rightarrow 0$  as  $t \rightarrow \infty$ . Consequently, one can choose  $t_{2k}$  > max { $2k$ ,  $t_{2k-1}$ } such that  $x(\psi_{2k})(t_{2k}) < 1/3$ . From Claim 4 it follows that there exists  $r_{2k} > r_{2k-1} + 1$  such that for all  $\psi \in IC_{\psi_{2k},r_k}$  we have  $x(\psi)(t_{2k}) < 1/3.$ 

Let  $\psi_{2k+1} \in IC_{\psi_{2k},r_{2k}}$  be defined by



## 24 T. KRISZTIN

(see Fig. 1). Now  $x(\psi_{2k+1})(t) \to 1$  as  $t \to \infty$ , since  $1 - \psi_{2k+1}$  has compact support. Then there is  $t_{2k+1} > \max\{2k+1, t_{2k}\}\text{ with } x(\psi_{2k+1})(t_{2k+1}) > 2/3.$ Claim 4 implies that we can find  $r_{2k+1} > r_{2k} + 1$  such that  $x(\psi)(t_{2k+1}) > 2/3$ for all  $\psi \in \mathrm{IC}_{\psi_{2k+1},r_{2k+1}}$ .

This induction defines the sequences  $\{\psi_n\}_{n=0}^{\infty}$ ,  $\{t_n\}_{n=0}^{\infty}$ ,  $\{r_n\}_{n=0}^{\infty}$ . It is easy to see that  $\bigcap_{k=0}^{\infty} IC_{\psi_k,r_k}$  contains a unique function  $\varphi$  given by

$$
\varphi(s) = \begin{cases}\n0 & \text{if } s \in \bigcup_{k=0}^{\infty} [-r_{2k}, -r_{2k-1} - 1] \\
1 & \text{if } s \in \bigcup_{k=0}^{\infty} [-r_{2k+1}, -r_{2k} - 1] \\
s + r_{2k-1} + 1 & \text{if } s \in [-1 - r_{2k-1}, -r_{2k-1}] \ (k = 0, 1, \dots) \\
-s - r_{2k} & \text{if } s \in [-1 - r_{2k}, -r_{2k}] \ (k = 0, 1, \dots),\n\end{cases}
$$

where  $r_{-1} = 0$ .

Since  $\varphi \in \bigcap_{k=0}^{\infty}$  IC<sub>there</sub>, we have

 $x(\varphi)(t_{2k}) < 1/3$  (k = 0, 1, ...)

and

$$
x(\varphi)(t_{2k+1}) > 2/3
$$
  $(k = 0, 1, ...).$ 

Therefore,  $x(\varphi)(t)$  does not converge as  $t \to \infty$ . The proof is complete.

#### **REFERENCES**

- 1. R. D. DRIVER, Existence and stability of solutions of a delay-differential system, Arch. Rational Mech. Anal. 10 (1962), 401-426.
- 2. I. GYGRI, Connections between compartmental systems with pipes and integro-differential equations, Math. Modelling 7 (1986), 1215-1238.
- 3. J. HADDOCK, T. KRISZTIN, AND J. TERJÉKI, Invariance principles for autonomous functional differential equations, J. Integral Equations 10 (1985), 123-136.
- 4. J. HADDOCK, T. KRISZTIN, AND J. TERJÉKI, Comparison theorems and convergence properties for functional differential equations with infinite delay, Acta Sci. Math. (Szeged) 52 (1989), 399-414.
- 5. T. KRISZTIN, On the convergence of solutions of functional differential equations with infinite delay, *J. Math. Anal. Appl.* 109 (1985), 509-521.
- 6. T. KRISZTIN, On the convergence of the solutions of a nonlinear integro-ditferential equation, "Differential Equations: Qualitative Theory" (B. Sz.-Nagy and L. Hatvani, Eds.), pp. 597-614, Colloquia Mathematics Societatis Janos Bolyai, No. 47, North-Holland, Amsterdam, 1987.
- 7. T. KRISZTIN AND J. TERJÉKI, On the rate of convergence of solutions of linear Volterra equations, *Boll. Un. Mat. Ital.* 7 2-B (1988), 427-444.
- 8. LI ZHI-XIAN, Liapunov-Razumikhin functions and the asymptotic properties of the autonomous functional differential equations with infinite delay, Tôhoku Math. J. 38 (1986), 491-499.
- 9. A. T. PLANT, On the asymptotic stability of solutions of Volterra integro-differential equations, J. Differential Equations 39 (1981), 39-51.