The Solution of the One-Dimensional Nonlinear Poisson's Equations by the Decomposition Method

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Abstract—The decomposition method is a nonnumerical method for solving strongly nonlinear differential equations. In this paper, the method is adapted for the solution of the one-dimensional nonlinear Poisson's equations governing the linearly graded p-n junctions in semiconductor devices, and the error analysis for the approximate analytic solutions obtained by the decomposition method is carried out. The simulation results show that the solutions obtained by the method are accurate and reliable, and that the quantitative analysis of the linearly graded p-n junctions can be conducted. This work indicates that the decomposition method has some advantages, which opens up a new way for the numerical analysis of semiconductor devices. © 2003 Elsevier Ltd. All rights reserved.

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1. INTRODUCTION

The numerical analysis for semiconductor devices consists of obtaining the solution of a set of differential equations under appropriate boundary and initial conditions. The equations are nonlinear, and the nonlinearity involved is of an exponential type, which deviates strongly from a linear relation [1]. For the linearly graded p-n junction, when considered under a non-significant current, we only need to solve nonlinear Poisson's equation of one dimension [1]. Morgan and Smits [2] analyzed the linearly graded p-n junction by the explicit numerical-integration method.

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However, the numerical integration tends to diverge unless the electric-field magnitude at the junction point is given in an extraordinary accuracy, for example, to 30 digits. Even so, the solution obtained is restricted to a very small region around the junction point. Kurata [1] used the implicit method, where the matrix equation resulting from the difference approximation must be solved many times according to Newton's iteration principle. The method is complicated and time-consuming. It is obvious that both these methods are numerical methods. We must assume the extent of the depletion layer of the junction before the application of them, but the reasonable choice of this parameter in advance is very difficult.

Since the beginning of the 80s, Adomian [3–5] has originated a method, named the decomposition method, which has advantages in solving nonlinear differential equations. The method is based on the decomposition of unknown function into an infinite sum of functions defined by a recurrent relation. The nonlinearity is also expressed in terms of an infinite sum of special polynomials called Adomian’s polynomials. The method is well suited to physical problems since it needs neither the linearization and perturbation nor other restrictive assumptions which may change, sometimes seriously, the problem being solved. Recently, Wazwaz [6] proposed a powerful modification of Adomian decomposition method that can accelerate the rapid convergence of the series solution.

In this paper, the one-dimensional nonlinear Poisson’s equation is solved by adapting the modification of the decomposition method [6], and the error analysis for the approximate solutions obtained by the decomposition method is carried out. In order to solve the one-dimensional nonlinear Poisson’s equations efficiently, we use the symbolic software such as MATHEMATICA to implement the whole solution procedure. Some simulated results are given, which are in good agreement with the qualitative conclusions in [1, 2]. The error analysis results indicate that the approximate analytic solution determined by the decomposition method is accurate and reliable and that it can be used to analyze quantitatively the linearly graded p–n junctions.

2. BASIC EQUATIONS AND THE BOUNDARY CONDITIONS

According to the semiconductor device principle, the basic equation for every semiconductor device is a set of nonlinear differential equations with appropriate boundary and initial conditions. However, under the nonsignificant-current assumption, the basic equation for the linearly graded p–n junction in the one-dimensional case can be expressed as nonlinear Poisson’s equation, with appropriate boundary conditions. Poisson’s equation in the one-dimensional case is written as [1]

$$\frac{d^2 \psi}{dx^2} = -\frac{q}{\epsilon} [N(x) + p - n],$$

where $\psi$ stands for the potential, $x$ the distance, $N(x)$ the net impurity concentration, $q$ the electronic charge, $\epsilon$ the dielectric constant, $p$ the hole density, and $n$ the electron density. For the linearly graded junction,

$$N(x) = mx. \quad (2)$$

The nonsignificant-current assumption allows the free carrier densities $p$ and $n$ to be written approximately as functions of a single-variable, namely $\psi$. The electron and hole densities in the depletion layer are written as [1]

$$n = n_i e^{\theta \psi}, \quad p = n_i e^{\theta (v - \psi)}, \quad (3)$$

where $\theta = q/KT$, $K$ stands for the Boltzmann constant, $T$ the temperature, $n_i$ the intrinsic free electron density, and $v$ the applied voltage. The quotient $\theta$ is called the Boltzmann factor. Substituting (2) and (3) into (1) yields

$$\frac{d^2 \psi}{dx^2} = -\frac{q}{\epsilon} \left[ mx + n_i e^{\theta (v - \psi)} - n_i e^{\theta \psi} \right]. \quad (4)$$
Boundary conditions for $\psi$ can be expressed as [1]

$$
\psi(-a) = \frac{1}{\theta} \ln \left[ \sqrt{\left( \frac{ma}{2n_i} \right)^2} + 1 - \frac{ma}{2n_i} \right] + v, \tag{5}
$$

$$
\psi(a) = \frac{1}{\theta} \ln \left[ \sqrt{\left( \frac{ma}{2n_i} \right)^2} + 1 + \frac{ma}{2n_i} \right],
$$

where $a$ is a parameter concerning the extent of the depletion layer. Outside the depletion layer, the space-charge neutrality holds. In view of the structural symmetry of the junction, the extent of the depletion layer of the junction is $2a$. Notice that the applied voltage $v$ should not take the positive value; since in that case a significant current flows, making the solution physically meaningless. Therefore, $v$ must be nonpositive.

In the two-point boundary-value problem (4) and (5), $\epsilon$, $q$, $\theta$, and $n_i$ are all physical constants. $m$ and $v$ are parameters given in advance, while $a$ is an unknown quantity. The condition for determining $a$ value is that the electric-field values in positions $\pm a$ are 0, which can be written as

$$
\frac{d\psi}{dx} \Bigg|_{x=\pm a} = 0. \tag{6}
$$

Until now, we have established the analysis model (4)-(6). In the next section, we first solve problem (4) and (5) by the decomposition method to obtain the analytic approximate solution with $a$ as a parameter, then we solve equation (6) to find a value. The accurate determination of the extent of the depletion layer by this technique is one of the great advantages of our method, which other numerical methods are difficult to accomplish.

3. COMPUTATIONAL PROCEDURE

The decomposition method is a general method for solving nonlinear problems. Its general principle is referred to [3-5]. Here, we take the boundary-value problem (4) and (5) as an example to illustrate the solution procedure of the decomposition method and our improvement on the iteration scheme of the method.

Let $L = \frac{d^2}{dx^2}$ and $f(\psi) = (\psi_n/e)[e^{\theta(x)} - e^{\theta(x)}]$. Then equation (4) can be written as

$$
L\psi = -\frac{qm}{\varepsilon} x - f(\psi). \tag{7}
$$

Solving for $L\psi$ and operating with $L^{-1}$, the two-fold indefinite integral operator, we have

$$
\psi = \Phi - L^{-1} \left( \frac{qm}{\varepsilon} x \right) - L^{-1} f(\psi), \tag{8}
$$

where $\Phi$ satisfies $L\Phi = 0$. $\Phi = c_0 + c_1 x$, where $c_0$ and $c_1$ are integration constants. By using the double decomposition strategy [7], we now decompose the solution $\psi$ as well as the integration constant term $\Phi$. Let $\psi = \sum_{m=0}^{\infty} \tilde{\psi}_m$, $\Phi = \sum_{m=0}^{\infty} (c_{0,m} + c_{1,m} x)$. The nonlinear term $f(\psi)$ will be equated to $\sum_{m=0}^{\infty} A_m$, where $A_m$ are polynomials of $\psi_0, \psi_1, \ldots, \psi_m$ called Adomian’s polynomials and are calculated by the formulae

$$
A_m = \frac{1}{m!} \frac{d^m}{d\lambda^m} f(\tilde{\psi}(\lambda)) \bigg|_{\lambda=0}, \quad m = 0, 1, 2, \ldots, \tag{9}
$$

where $\tilde{\psi}(\lambda) = \sum_{m=0}^{\infty} \tilde{\psi}_m \lambda^m$. Putting these relations into (8) gives

$$
\sum_{m=0}^{\infty} \psi_m = \sum_{m=0}^{\infty} (c_{0,m} + c_{1,m} x) - \frac{qm}{6\varepsilon} x^3 - L^{-1} \sum_{m=0}^{\infty} A_m. \tag{10}
$$
The basic iteration scheme of the decomposition method can be expressed as

\begin{align}
\psi_0 &= c_{0,0} + c_{1,0}x - \frac{qm}{6\varepsilon}x^3, \\
\psi_m &= c_{0,m} + c_{1,m}x - L^{-1}A_{m-1}, \quad m \geq 1.
\end{align}

In order to avoid the difficult integrations and to express the integration results with elementary functions, we use the modification of the decomposition method [6] to improve the iteration scheme. By divide the function \( g(z) = c_{0,0} + c_{1,0}z - \frac{qm}{6\varepsilon}z^3 \) into two parts, namely \( g_1(x) = c_{0,0} + c_{1,0}x \) and \( g_2(x) = -\frac{qm}{6\varepsilon}x^3 \), we formulate the modified recurrent relation as follows:

\begin{align}
\psi_0 &= c_{0,0} + c_{1,0}x, \\
\psi_1 &= c_{0,1} + c_{1,1}x - \frac{qm}{6\varepsilon}x^3 - L^{-1}A_0, \\
\psi_m &= c_{0,m} + c_{1,m}x - L^{-1}A_{m-1}, \quad m \geq 2.
\end{align}

Let

\[ \psi_m = \psi_0 + \psi_1 + \cdots + \psi_{m-1}, \tag{13} \]

then \( c_{0,m} \) and \( c_{1,m} \) are determined by satisfying the boundary conditions (5) with \( r_{m+1} \). Let

\begin{align}
\beta_1(a) &= \frac{1}{2} \ln \left[ \sqrt{\left( \frac{ma}{2n_i} \right)^2 + 1 - \frac{ma}{2n_i}} \right] + v, \\
\beta_2(a) &= \frac{1}{2} \ln \left[ \sqrt{\left( \frac{ma}{2n_i} \right)^2 + 1 + \frac{ma}{2n_i}} \right].
\end{align}

Then the boundary conditions (5) become

\[ \psi(-a) = \beta_1(a) \quad \text{and} \quad \psi(a) = \beta_2(a). \tag{15} \]

Matching \( r_1 = \psi_0 \) to the boundary conditions (15), we determine \( c_{0,0} \) and \( c_{1,0} \) by two linear equations, and

\begin{align}
c_{0,0} &= \frac{\beta_1(a) + \beta_2(a)}{2}, \\
c_{1,0} &= \frac{\beta_2(a) - \beta_1(a)}{2a}.
\end{align}

So, we get \( r_1 = \psi_0 \). From (9), we have \( A_0 = f(\psi_0) \). Then

\[ \psi_1 = c_{0,1} + c_{1,1}x - \frac{qm}{6\varepsilon}x^3 - L^{-1}A_0. \tag{17} \]

Matching \( r_2 = \psi_0 + \psi_1 \) to the boundary conditions (15), we require \( \psi_1(-a) = \psi_1(a) = 0 \). By solving two linear equations, we have

\begin{align}
c_{0,1} &= \frac{L^{-1}A_0(-a) + L^{-1}A_0(a)}{2}, \\
c_{1,1} &= \frac{qm}{6\varepsilon}a^2 + \frac{L^{-1}A_0(a) - L^{-1}A_0(-a)}{2a}.
\end{align}

So, we get \( \psi_1 \) and \( r_2 - \psi_0 + \psi_1 \). From (9), \( A_1 \) can be determined by \( \psi_0 \) and \( \psi_1 \). Generally, if \( \psi_0, \psi_1, \ldots, \psi_{m-1} \) have been found for \( m \geq 2 \), \( A_{m-1} \) can be determined by \( \psi_0, \psi_1, \ldots, \psi_{m-1} \).
Decomposition Method

and (9). Matching $r_{m+1} = \psi_0 + \cdots + \psi_{m-1} + \psi_m$ to the boundary conditions (15), we require $\psi_m(-a) = \psi_m(a) = 0$. By solving two linear equations, we have

$$c_{0,m} = \frac{L^{-1}A_{m-1}(-a) + L^{-1}A_{m-1}(a)}{2},$$

$$c_{1,m} = \frac{L^{-1}A_{m-1}(a) - L^{-1}A_{m-1}(-a)}{2a}.$$  \hspace{1cm} (19)

So, we get $\psi_m$ and $r_{m+1} = \psi_0 + \psi_1 + \cdots + \psi_m$.

From the above-mentioned procedure, we arrive at an approximate analytic solution $r(x, a)$ for the boundary-value problem (4) and (5). By solving equation

$$\frac{dr(x,a)}{dx} \bigg|_{x=1} = 0,$$  \hspace{1cm} (20)

we can obtain the value $a$ and the extent of the depletion layer $2a$.

4. COMPUTER IMPLEMENTATION AND ERROR ANALYSIS

The decomposition method is a general method that is well suited to solving many nonlinear problems. However, the artificial derivation of its computational procedure for the solution of complex nonlinear equations is cumbersome as well as time-consuming, and the complex approximate solutions with high accuracy are hard to calculate. Computers and new softwares can be of a great help for the computations. It is necessary to implement the decomposition method for the solution of complex nonlinear equations by the symbolic software such as MAPLE and MATHEMATICA. Now we state the concrete computational steps briefly.

- Compute $c_{0,0}$ and $c_{1,0}$ with boundary conditions, then obtain $\psi_0$.
- According to the recurrent scheme, derive $A_{m-1}, c_{0,m}, c_{1,m}$, and $\psi_m (m = 1, 2, \ldots)$ successively.
- Adding these $\psi_m$s, we obtain the approximate analytic solution $r(x, a)$. By solving equation (20), find the parameter $a$. Simplify the approximant $r(x, a)$.
- Carry out, by using the technique described below, the error analysis for the approximate solution obtained by the decomposition method.
- Quantitatively analyze the potential $r$ and the electric field $-\frac{\partial r}{\partial x}$, and reveal the objective laws governing the linearly graded $p-n$ junctions.

With the computational procedure and MATHEMATICA software, we have studied the boundary-value problem (4) and (5) carefully. Considering the concise expression of the approximate solution and the limited microcomputer memory, the two-term approximation to the solution is given by

$$r_2(x,a) = \psi_0 + \psi_1 = \frac{\beta_1(a) + \beta_2(a)}{2}$$

$$-\frac{2qa^2n_i}{[\beta_2(a) - \beta_1(a)]^2\epsilon \theta^2} \left\{ e^{\beta_1(a)\theta} + e^{\beta_2(a)\theta} - e^{\theta[\psi_1(a)]} - e^{\theta[\psi_2(a)]} \right\}$$

$$+ \frac{2qa_n}{[\beta_2(a) - \beta_1(a)]^2\epsilon \theta^2} \left\{ e^{\beta_1(a)\theta} - e^{\beta_2(a)\theta} - e^{\theta[\psi_1(a)]} + e^{\theta[\psi_2(a)]} \right\} x$$

$$+ \frac{\beta_2(a) - \beta_1(a)}{2a} x + \frac{qm a^2}{6\epsilon} x - \frac{qm}{6\epsilon} x^3 + \frac{4qa^2n_i}{[\beta_2(a) - \beta_1(a)]^2\epsilon \theta^2}$$

$$\left\{ e^{\frac{\theta[\psi_1(a)]}{2} + \frac{\theta[\psi_2(a)]}{2}} + e^{\frac{\theta[\psi_1(a)] - \psi_2(a)]}{2}} x - e^{\frac{\theta[\psi_2(a)]}{2} + \frac{\theta[\psi_1(a)]}{2}} - e^{\frac{\theta[\psi_1(a)] - \psi_2(a)]}{2}} x \right\}.$$
The parameter \( a \) can be determined easily by solving equation \( \frac{d^2 y}{dx^2} \big|_{x=\pm a} = 0 \) with a symbolic program such as MATHEMATICA.

The method’s convergence has been studied by Cherruault [8,9] by using the fixed-point theorem [8] and the properties of the substituted series [9], but problems still remain with differential equations. Nelson [10] proposed a counterexample to the convergence assertion of the decomposition method. Because there is no theoretical proof that is entirely satisfactory, we must verify the validity of the approximate solution obtained with a symbolic program such as MATHEMATICA.

It is obvious that \( r_2 \) satisfies the boundary conditions (5). We need to verify that \( r_2 \) satisfies equation (4). For this purpose, we define the following absolute error and relative error functions:

\[
AE(x) = \frac{d^2 y}{dx^2} + \frac{q}{\epsilon} \left[ mx + f(r_2) \right],
\]
\[
RE(x) = 2 \times \frac{AE(x)}{\left\{ \frac{d^2 y}{dx^2} - \frac{q}{\epsilon} [mx + f(r_2)] \right\}},
\]

and the criterion whether these two functions are close to 0 in \([-a,a]\) can be used to test the degree of accuracy of the approximate solution \( r_2 \).

5. SIMULATED RESULTS

Let us now discuss some examples. At this stage, the following numerical data are given for physical constants: \( q = 1.6 \times 10^{-19} \) Coul, \( \epsilon = 1.064 \times 10^{-16} \) F/\( \mu m \), \( \theta = 38.5 \text{ V}^{-1} \), \( n_i = 1.4 \times 10^{-2} \) (\( \mu m \))^{-3}. By using the mathematics-mechanization method, four cases with \( v = 0 \) V, \( m = 10^4 \) (\( \mu m \))^{-4}; \( v = -5 \) V, \( m = 10^4 \) (\( \mu m \))^{-4}; \( v = -10 \) V, \( m = 10^4 \) (\( \mu m \))^{-4} and \( v = -100 \) V, \( m = 10^3 \) (\( \mu m \))^{-4} are simulated, and the corresponding \( a \) values are 0.4377 \( \mu m \), 0.8355 \( \mu m \), 1.026 \( \mu m \), and 4.65 \( \mu m \), respectively. The potential, electric field, absolute error and relative error distributions in the depletion layers for these four cases are shown in Figures 1-16. The computational results are in good agreement with the qualitative conclusions given in [1,2]. The error analysis results show that the approximate analytic solutions obtained are accurate and reliable, especially when the absolute values of \( v \) are large. Also, our technique can be used to find the accurate extent of the depletion layer for the linearly graded \( p-n \) junctions and to analyze quantitatively their various electric performance indices, such as the potential distribution and the electric field distribution.

![Potential distribution with \( v = 0 \) V and \( m = 10^4 \) (\( \mu m \))^{-4}.](image-url)
Figure 2. Electric field distribution with $v = 0 \text{ V}$ and $m = 10^4 \text{ (}\mu\text{m})^{-4}$.

Figure 3. Absolute error distribution with $v = 0 \text{ V}$ and $m = 10^4 \text{ (}\mu\text{m})^{-4}$.

Figure 4. Relative error distribution with $v = 0 \text{ V}$ and $m = 10^4 \text{ (}\mu\text{m})^{-4}$.
Figure 5. Potential distribution with $v = -5$ V and $m = 10^4$ ($\mu$m)$^{-4}$.

Figure 6. Electric field distribution with $v = -5$ V and $m = 10^4$ ($\mu$m)$^{-4}$.

Figure 7. Absolute error distribution with $v = -5$ V and $m = 10^4$ ($\mu$m)$^{-4}$.
Figure 8. Relative error distribution with $v = -5 \text{ V}$ and $m = 10^4 \text{ (pm)}^{-4}$.

Figure 9. Potential distribution with $v = -10 \text{ V}$ and $m = 10^4 \text{ (pm)}^{-4}$.

Figure 10. Electric field distribution with $v = -10 \text{ V}$ and $m = 10^4 \text{ (pm)}^{-4}$. 
Figure 11. Absolute error distribution with $v = -10 \text{V}$ and $m = 10^4 (\mu\text{m})^{-4}$.

Figure 12. Relative error distribution with $v = -10 \text{V}$ and $m = 10^4 (\mu\text{m})^{-4}$.

Figure 13. Potential distribution with $v = -100 \text{V}$ and $m = 10^3 (\mu\text{m})^{-4}$.
Figure 14. Electric field distribution with $v = -100$ V and $m = 10^3$ $(\mu m)^{-4}$.

Figure 15. Absolute error distribution with $v = -100$ V and $m = 10^3$ $(\mu m)^{-4}$.

Figure 16. Relative error distribution with $v = -100$ V and $m = 10^3$ $(\mu m)^{-4}$. 
6. CONCLUSIONS

The application of the decomposition method to the solution of the one-dimensional Poisson's equation has been studied, and the approximate analytic solution for this strongly nonlinear equation has been found, by using MATHEMATICA software. Also, the technique for determining the extent of the depletion layer has been presented, and the error analysis for the obtained approximate solutions has been carried out. Our research work indicates that the approximate analytic solution determined by the decomposition method is accurate and reliable, and that it can be used to analyze quantitatively the linearly graded $p-n$ junctions.

The decomposition method is an efficient method that can solve many nonlinear equations. For the first time, its efficiency has been proved with the quantitative analysis of the linearly graded $p-n$ junctions. The method has some quite significant advantages over numerical methods such as finite element method and finite difference method, and it gives much more information. Although the linearly graded $p-n$ junction just has been analyzed quantitatively, maybe the decomposition method will open up a new way for the numerical analysis of semiconductor devices. The approximate solution determined by the decomposition method can be viewed as usual functions, which can be used to solve very interesting problems such as quantitative analysis and optimization design.

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