# Existence of steady subsonic Euler flows through infinitely long periodic nozzles 

Chao Chen ${ }^{\mathrm{a}}$, Chunjing Xie ${ }^{\mathrm{b}, *}$<br>${ }^{\text {a }}$ The Institute of Mathematical Sciences and Department of Mathematics, The Chinese University of Hong Kong, Shatin, Hong Kong<br>${ }^{\mathrm{b}}$ Department of Mathematics and Institute of Natural Sciences, Shanghai Jiao Tong University, 800 Dongchuan Road, Shanghai 200240, China

## A R T I C L E I N F O

## Article history:

Received 26 July 2011
Available online 20 January 2012


#### Abstract

In this paper, we study the global existence of steady subsonic Euler flows through infinitely long nozzles which are periodic in $x_{1}$-direction with the period $L$. It is shown that when the variation of Bernoulli function at some given section is small and mass flux is in a suitable regime, there exists a unique global subsonic flow in the nozzle. Furthermore, the flow is also periodic in $x_{1}$-direction with the period $L$. If, in particular, the Bernoulli function is a constant, we also get the existence of subsonic-sonic flows when the mass flux takes the critical value.


© 2012 Elsevier Inc. All rights reserved.

## 1. Introduction and main results

The study on subsonic and transonic flows in nozzles has grown enormously in recent years. Subsonic and subsonic-sonic potential flows in infinitely long nozzles were studied in [20,21,19,15]. For full compressible Euler equations, Xie and Xin in [22] showed the existence of global subsonic flow in an infinitely long nozzle which tends to be flat at far field. The key point in [22] is to transform the system of Euler equations into a second-order equation of stream function. The careful energy estimates give far field behavior and uniqueness of flows. The idea in [22] was generalized to subsonic Euler flows in axially symmetric nozzles [14]. Subsonic and subsonic-sonic potential flows past a body were studied in $[3,4,7]$ and references therein. Subsonic Euler flows with nonzero vorticity in half-space were investigated in [10]. Subsonic flows were also studied as a part of stability of transonic shock problem, see $[8,9,5,6,11,12,17,18,23-26]$ and references therein, where subsonic flows and nozzles are small perturbations of some given background flows and nozzles with simple geometries, respectively.

[^0]In this paper, we study the existence of global steady subsonic Euler flows through periodic nozzles. Consider 2-D steady isentropic Euler equations

$$
\begin{gather*}
(\rho u)_{x_{1}}+(\rho v)_{x_{2}}=0  \tag{1}\\
\left(\rho u^{2}\right)_{x_{1}}+(\rho u v)_{x_{2}}+p_{x_{1}}=0,  \tag{2}\\
(\rho u v)_{x_{1}}+\left(\rho v^{2}\right)_{x_{2}}+p_{x_{2}}=0, \tag{3}
\end{gather*}
$$

where $\rho$, $(u, v)$, and $p=p(\rho)$ denote the density, velocity, and pressure, respectively. In general, it is assumed that $p^{\prime}(\rho)>0$ for $\rho>0$ and $p^{\prime \prime}(\rho) \geqslant 0$, where $c(\rho)=\sqrt{p^{\prime}(\rho)}$ is called the sound speed. The most important examples include polytropic gases and isothermal gases. For polytropic gases, $p=A \rho^{\gamma}$ where $A$ is a constant and $\gamma$ is the adiabatic constant with $\gamma>1$; and for isothermal gases, $p=c^{2} \rho$ with constant sound speed $c$ [13].

We consider flows through an infinitely long periodic nozzle given by

$$
\Omega=\left\{\left(x_{1}, x_{2}\right) \mid f_{1}\left(x_{1}\right)<x_{2}<f_{2}\left(x_{1}\right),-\infty<x_{1}<\infty\right\}
$$

where $f_{i}(i=1,2)$ is $L$-periodic, i.e., $f_{i}\left(x_{1}+L\right)=f_{i}\left(x_{1}\right)$ for $x_{1} \in \mathbb{R}$. Suppose that there exist $\alpha \in(0,1)$ and $C>0$ such that

$$
\begin{equation*}
\left\|f_{i}\right\|_{C^{2, \alpha}(\mathbb{R})} \leqslant C \quad \text { and } \quad \inf _{x_{1} \in[0, L]}\left(f_{2}\left(x_{1}\right)-f_{1}\left(x_{1}\right)\right)>0 \tag{4}
\end{equation*}
$$

Therefore, the domain $\Omega$ satisfies the uniform exterior sphere condition with some uniform radius $r>0$. Without loss of generality, we assume that $f_{1}(0)=0$ and $f_{2}(0)=1$.

Suppose that the nozzle walls are impermeable so that the flow satisfies the no flow boundary condition

$$
\begin{equation*}
(u, v) \cdot \vec{v}=0 \quad \text { on } \partial \Omega, \tag{5}
\end{equation*}
$$

where $\vec{v}$ is the unit outward normal to the nozzle wall. It follows from (1) and (5) that

$$
\begin{equation*}
\int_{l}(\rho u, \rho v) \cdot \vec{n} d l \equiv m \tag{6}
\end{equation*}
$$

holds for some constant $m$, which is called the mass flux, where $l$ is any curve transversal to the $x_{1}$-direction, and $\vec{n}$ is the normal of $l$ in the positive $x_{1}$-axis direction.

Using the continuity equation (1), when the flow is away from the vacuum, the momentum equations (2) and (3) are equivalent to

$$
\begin{align*}
& u u_{x_{1}}+v u_{x_{2}}+h(\rho)_{x_{1}}=0,  \tag{7}\\
& u v_{x_{1}}+v v_{x_{2}}+h(\rho)_{x_{2}}=0, \tag{8}
\end{align*}
$$

where $h(\rho)$ is the enthalpy of the flow satisfying $h^{\prime}(\rho)=p^{\prime}(\rho) / \rho$ and can be determined up to a constant. In this paper, for example, we always choose $h(0)=0$ for polytropic gases and $h(1)=0$ for isothermal gases. After determining this integral constant, we denote $H_{0}=\inf _{\rho>0} h(\rho)$.

It follows from (7) and (8) that

$$
\begin{equation*}
(u, v) \cdot \nabla\left(h(\rho)+\frac{1}{2}\left(u^{2}+v^{2}\right)\right)=0 . \tag{9}
\end{equation*}
$$

This implies that $\frac{u^{2}+v^{2}}{2}+h(\rho)$, which is called Bernoulli's function, is a constant along each streamline. For Euler flows in the nozzle, we assume that at $x_{1}=0$, Bernoulli function is given, i.e.,

$$
\begin{equation*}
\left(\frac{u^{2}+v^{2}}{2}+h(\rho)\right)\left(0, x_{2}\right)=B_{0}\left(x_{2}\right) \tag{10}
\end{equation*}
$$

where $B_{0}\left(x_{2}\right)$ is a function defined on $[0,1]$.
When the Bernoulli function $B$ is a constant, Proposition 3 shows that the flow is irrotational. The existence of periodic potential flows with small mass flux in periodic nozzles was obtained in [19]. In this paper, we first study the subsonic and subsonic-sonic periodic potential flows with relatively large mass flux.

Theorem 1. If $B_{0}\left(x_{2}\right) \equiv \bar{B}>H_{0}$, then

1. there exists an $\hat{m}>0$, such that for any $m \in(0, \hat{m})$ there exists a unique subsonic periodic flow $(\bar{\rho}, \bar{u}, \bar{v})$ which satisfies $\inf _{\bar{\Omega}} \bar{u}>0$;
2. the maximum of Mach numbers of the flows increases as $m$ increases and goes to one as $m \rightarrow \hat{m}$, i.e., the flows approach sonic;
3. there exist a sequence $m_{n} \rightarrow \hat{m}$ such that the associated potential flows $\left(\bar{\rho}_{n}, \bar{u}_{n}, \bar{v}_{n}\right)$ converge to $(\hat{\rho}, \hat{u}, \hat{v})$ almost everywhere, which satisfies

$$
\left\{\begin{array}{l}
\nabla \times(\hat{u}, \hat{v})=0  \tag{11}\\
\operatorname{div}(\hat{\rho} \hat{u}, \hat{\rho} \hat{v})=0
\end{array}\right.
$$

and the boundary condition (5) in the sense of divergence measure field, where $\hat{\rho}$ is determined by $\hat{u}$ and $\hat{v}$ via Bernoulli law.

When $B_{0}$ is not a constant, we have the following results on subsonic Euler flows in periodic nozzles.

Theorem 2. Let the nozzle satisfy (4) and $B_{0}$ in (10) satisfy

$$
\begin{equation*}
B_{0}^{\prime}(0) \geqslant 0, \quad B_{0}^{\prime}(1) \leqslant 0 \tag{12}
\end{equation*}
$$

For any $m \in(0, \hat{m})$, there exists $\epsilon_{0}>0$ such that if $B_{0}\left(x_{2}\right)$ satisfies

$$
\begin{equation*}
\left\|B_{0}-\bar{B}\right\|_{C^{1,1}([0,1])}=\epsilon \leqslant \epsilon_{0} \tag{13}
\end{equation*}
$$

where $\bar{B}$ is the constant in Theorem 1, then

1. (Existence) there exists a periodic flow, i.e.,

$$
\rho\left(x_{1}+L, x_{2}\right)=\rho\left(x_{1}, x_{2}\right), \quad u\left(x_{1}+L, x_{2}\right)=u\left(x_{1}, x_{2}\right), \quad v\left(x_{1}+L, x_{2}\right)=v\left(x_{1}, x_{2}\right)
$$

which satisfies the original Euler equations (1)-(3), the boundary condition (5), mass flux condition (6), and the condition (10);
2. (Subsonic flows and positivity of horizontal velocity) the flow is globally uniformly subsonic and has positive horizontal velocity. More precisely,

$$
\begin{equation*}
\sup _{\bar{\Omega}}\left(u^{2}+v^{2}-c^{2}(\rho)\right)<0 \quad \text { and } \quad \inf _{\bar{\Omega}} u>0 \tag{14}
\end{equation*}
$$

3. (Regularity) the flow satisfies

$$
\|\rho\|_{C^{1, \alpha}(\Omega)},\|u\|_{C^{1, \alpha}(\Omega)},\|v\|_{C^{1, \alpha}(\Omega)} \leqslant C
$$

for some constant $C>0$;
4. (Uniqueness) the flow is unique in the class of the periodic flows satisfying (14).

A remark about Theorem 2 is as follows.
Remark 1. Using the analysis in this paper, it is easy to show that there exists a subsonic full compressible Euler flow in the nozzle, if the entropy is also prescribed at $x_{1}=0$.

The rest of the paper is organized as follows: In Section 2, we introduce the stream function formulation for the Euler equations and give the proof of Theorem 1. In Section 3, a boundary value problem for stream function is analyzed. This is divided into two steps. The existence of solutions for the associated problem is studied in Section 3.1. The uniqueness, periodicity, and positivity of horizontal velocity of the flows are proved in Section 3.2. In Section 4, we use the fixed point theorem to show the existence of Euler flows; the uniqueness of these flows are obtained by the energy method.

## 2. Stream function formulation of the Euler flows and proof of Theorem 1

### 2.1. Bernoulli's law and a new formulation of the Euler equations

We recall that the steady Euler system for subsonic flows is a hyperbolic-elliptic coupled system [22]. Therefore, one has to resolve the hyperbolic mode.

To overcome the difficulties mentioned above, we introduce the stream function for 2-D steady compressible Euler flows so that the Bernoulli function can be reduced to a single-valued function of stream function. This gives an equivalent formulation for Euler flows in terms of stream function.

Proposition 3. For a smooth flow away from vacuum with no stagnation point, i.e., $u^{2}+v^{2}>0$, the Euler system (1)-(3) is equivalent to the system of Eqs. (1), (9), and

$$
\begin{equation*}
\omega=\frac{v \partial_{x_{1}} B-u \partial_{x_{2}} B}{u^{2}+v^{2}}, \tag{15}
\end{equation*}
$$

where $B=\frac{1}{2}\left(u^{2}+v^{2}\right)+h(\rho)$ and $\omega=\partial_{\chi_{1}} v-\partial_{\chi_{2}} u$ are Bernoulli function and vorticity, respectively.
Proof. Let us first show that (1)-(3) imply (15). Differentiating the Bernoulli function with respect to $x_{1}$ and $x_{2}$, respectively, gives

$$
\begin{equation*}
\partial_{1} B=u \partial_{1} u+v \partial_{1} v+\partial_{1} h(\rho), \quad \partial_{2} B=u \partial_{2} u+v \partial_{2} v+\partial_{2} h(\rho) . \tag{16}
\end{equation*}
$$

This, together with (7)-(8), yields

$$
\begin{equation*}
\partial_{1} B=v\left(\partial_{1} v-\partial_{2} u\right)=v \omega, \quad \partial_{2} B=-u\left(\partial_{1} v-\partial_{2} u\right)=-u \omega . \tag{17}
\end{equation*}
$$

Therefore, Eq. (15) holds provided $u^{2}+v^{2}>0$.
Conversely, it follows from straightforward computation that (9) and (15) imply (17). Substituting (17) into (16) gives (7) and (8). Using (1), one has (2) and (3).

This finishes the proof of the proposition.

The continuity equation (1) implies that there exists a stream function $\psi$ such that

$$
\partial_{x_{1}} \psi=-\rho v, \quad \partial_{x_{2}} \psi=\rho u .
$$

Hence, for the flows away from vacuum, (9) is equivalent to

$$
\nabla^{\perp} \psi \cdot \nabla B=0,
$$

where $\nabla^{\perp}=\left(-\partial_{\chi_{2}}, \partial_{\chi_{1}}\right)$. This yields that $B$ and $\psi$ are functionally dependent. Therefore, one may regard $B$ as a function of $\psi$. We denote this function by $B=\mathcal{B}(\psi)$. It follows from the no flow boundary condition (5), that the nozzle walls are streamlines, so $\psi$ is constant on each nozzle wall. Taking (6) into account, one may assume that

$$
\begin{equation*}
\psi=0 \quad \text { on } S_{1}, \quad \text { and } \quad \psi=m \quad \text { on } S_{2}, \tag{18}
\end{equation*}
$$

where $S_{i}=\left\{\left(x_{1}, f_{i}\left(x_{1}\right)\right) \mid x_{1} \in \mathbb{R}\right\}(i=1,2)$.
As in [22], for any given $s>H_{0}$, there exist $\bar{\varrho}=\bar{\varrho}(s), \varrho=\varrho(s)$ and $\Gamma=\Gamma(s)$ such that

$$
h(\varrho(s))=s, \quad h(\varrho(s))+\frac{\Gamma^{2}(s)}{2}=s, \quad \text { and } \quad p^{\prime}(\varrho(s))=\Gamma^{2}(s),
$$

where $\bar{\varrho}(s), \varrho(s)$, and $\Gamma(s)$ are the maximum density, the critical density, and the critical speed, respectively for the states with given Bernoulli constant $s$. Set

$$
\begin{equation*}
\Sigma(s)=\varrho(s) \sqrt{2(s-h(\varrho(s)))} \tag{19}
\end{equation*}
$$

Then the straightforward calculations show that

$$
\frac{d \bar{\varrho}}{d s}>0, \quad \frac{d \varrho}{d s}>0, \quad \text { and } \quad \frac{d \Sigma}{d s}>0 .
$$

Obviously, $\varrho(s)<\bar{\varrho}(s)$, if $s>H_{0}=\inf _{\rho>0} h(\rho)$. Furthermore, there exists a $\bar{\delta}>0$ such that

$$
\begin{equation*}
\bar{\varrho}\left(s_{1}\right)>\varrho\left(s_{2}\right) \quad \text { for any } s_{1}, s_{2} \in(\bar{B}-\bar{\delta}, \bar{B}+\bar{\delta}) . \tag{20}
\end{equation*}
$$

For a fixed $s$, if $\rho$ and $\mathcal{M}$ satisfy

$$
\begin{equation*}
h(\rho)+\frac{\mathcal{M}}{2 \rho^{2}}=s \tag{21}
\end{equation*}
$$

then $\rho$ is a two-valued function of $\mathcal{M}$ for $\mathcal{M} \in\left(0, \Sigma^{2}(s)\right)$ and the subsonic branch satisfies $\rho>\varrho(s)$, see [22]. When $s$ varies, the subsonic branch will be denoted by

$$
\begin{equation*}
\rho=H(\mathcal{M}, s) \quad \text { for }(\mathcal{M}, s) \in\left\{(\mathcal{M}, s) \mid \mathcal{M} \in\left(0, \Sigma^{2}(s)\right), s>H_{0}\right\} . \tag{22}
\end{equation*}
$$

In view of (21), we have

$$
\frac{\partial H}{\partial s}=\frac{H^{3}}{H^{2} c^{2}-\mathcal{M}}>0, \quad \frac{\partial H}{\partial \mathcal{M}}=\frac{H}{2\left(\mathcal{M}-H^{2} c^{2}\right)}<0 .
$$

### 2.2. Potential flows and proof of Theorem 1

If $B_{0}(x) \equiv \bar{B}$, we have $\mathcal{B}(\psi)=\bar{B}$. It follows from (22) that $\rho=H\left(|\nabla \psi|^{2}, \bar{B}\right)$. Furthermore, (15) implies $\omega \equiv 0$ because $B\left(x_{1}, x_{2}\right) \equiv \bar{B}$ in $\Omega$. Therefore, $\psi$ satisfies

$$
\begin{equation*}
\operatorname{div}\left(\frac{\nabla \psi}{H\left(|\nabla \psi|^{2}, \bar{B}\right)}\right)=0 . \tag{23}
\end{equation*}
$$

Let $\left\{M_{n}\right\}$ be a strictly increasing sequence satisfying $\lim _{n \rightarrow \infty} M_{n}=\Sigma^{2}(\bar{B})$. We define $H_{n}(\cdot, \bar{B}) \in$ $C^{\infty}(\mathbb{R})$ satisfying

$$
H_{n}(M, \bar{B})= \begin{cases}H(M, \bar{B}) & \text { if } M \leqslant M_{n},  \tag{24}\\ H\left(M_{n}, \bar{B}\right) & \text { if } M \geqslant \frac{M_{n}+\Sigma^{2}(\bar{B})}{2} .\end{cases}
$$

Combining Lemmas 2.1 and 3.1 in [20] and Lemma 1 in [19] (or Theorem 2 in [2]), there exists a unique periodic solution $\bar{\psi}(\cdot ; t)$ of the problem

$$
\left\{\begin{array}{l}
\operatorname{div}\left(\frac{\nabla \psi}{H_{n}\left(|\nabla \psi|^{2}, \bar{B}\right)}\right)=0, \\
\psi=0 \text { on } S_{1}, \quad \psi=t \quad \text { on } S_{2}
\end{array}\right.
$$

for $t \geqslant 0$. Define $\mathscr{M}_{n}(t)=\sup _{\bar{\Omega}}\left|\nabla \bar{\psi}_{n}(\cdot ; t)\right|^{2}$. Then that $\mathscr{M}_{n}(t)$ is a continuous function of $t$ follows from the same argument in Lemma 4.1 in [20]. Let $m_{n}=\sup \left\{t \mid \mathscr{M}_{n}(t)<M_{n}\right\}$ and $\hat{m}=\sup _{n} m_{n}$. Then as $m \rightarrow \hat{m}$, the maximum of $|\nabla \bar{\psi}|$ of solutions of the problem (23) and (18) tends to $\Sigma(\bar{B})$, i.e., the flows approach the sonic state. Moreover, using the compensated compactness framework in [7, Theorem 2.1] and [20, Theorem 5.1], there exist a sequence $\left\{m_{n}\right\} \uparrow \bar{m}$ such that the associated $\bar{u}_{n}=\frac{\partial_{2} \bar{\psi}_{n}}{H\left(\left|\nabla \bar{\psi}_{n}\right|^{2}, \bar{B}\right)}, \bar{v}_{n}=-\frac{\partial_{1} \bar{\psi}_{n}}{H\left(\left|\nabla \bar{\psi}_{n}\right|^{2}, \bar{B}\right)}$, and $\bar{\rho}_{n}=H\left(|\nabla \bar{\psi}|^{2}, \bar{B}\right)$ satisfy $\bar{u}_{n} \rightarrow \hat{u}, \bar{v}_{n} \rightarrow \hat{v}$, and $\bar{\rho}_{n} \rightarrow \hat{\rho}$ a.e., where $(\hat{u}, \hat{v})$ satisfies $\sup _{\bar{\Omega}} \frac{\hat{u}^{2}+\hat{v}^{2}}{p^{\prime}(\hat{\rho})}=1$, the system (11), and the boundary condition (5) in the sense of divergence measure field [1].

The proof of Theorem 1 finishes after we prove the following lemma on the properties of subsonic potential flows.

Lemma 4. If $m>0$, then the solution $\bar{\psi}$ of the problem (23) and (18) satisfies $\inf _{\bar{\Omega}} \partial_{2} \bar{\psi}>0$. Furthermore, as $m$ increases, $\max _{\bar{\Omega}}|\nabla \bar{\psi}|$ also increases.

Proof. Note that $\bar{\psi}$ satisfies $0 \leqslant \bar{\psi} \leqslant m$, therefore, $\bar{\psi}$ achieves its minimum and maximum on the boundaries $S_{1}$ and $S_{2}$ respectively. It follows from the Hopf lemma [16, Lemma 3.4] that $\partial_{x_{2}} \bar{\psi}>0$ on $\partial \Omega$. Therefore, the continuity of $\partial_{x_{2}} \bar{\psi}$ yields

$$
\inf _{\substack{\left(x_{1}, x_{2}\right) \in \partial \Omega, 0 \leqslant x_{1} \leqslant L}} \partial_{\chi_{2}} \bar{\psi}>0 .
$$

If $\bar{\psi}$ satisfies (23), then $\partial_{x_{2}} \bar{\psi}$ satisfies

$$
\begin{equation*}
\partial_{i}\left(\bar{a}_{i j} \partial_{j}\left(\partial_{x_{2}} \bar{\psi}\right)\right)=0, \quad \text { where } \bar{a}_{i j}=\frac{\left(H^{2} c^{2}-|\nabla \bar{\psi}|^{2}\right) \delta_{i j}+\partial_{i} \bar{\psi} \partial_{j} \bar{\psi}}{H\left(|\nabla \bar{\psi}|^{2}-H^{2} c^{2}\right)} . \tag{25}
\end{equation*}
$$

Here and later on, the repeated index means summation from 1 to 2 . It follows from the strong maximum principle [16, Theorem 3.5] that $\partial_{2} \bar{\psi}>0$ on $\bar{\Omega}$. In fact, if the minimum of $\partial_{x_{2}} \bar{\psi}$ is achieved
at some point $\left(x_{1}^{*}, x_{2}^{*}\right) \in \Omega$, by periodicity, we can always assume $\left|x_{1}^{*}\right| \leqslant L$. Then, it contradicts with the strong maximum principle for Eq. (25) in the domain $\left\{\left(x_{1}, x_{2}\right) \in \Omega:\left|x_{1}\right| \leqslant \frac{3 L}{2}\right\}$.

It follows from Bernstein estimates [16, Theorem 15.1] and periodicity of the solutions that

$$
\begin{equation*}
\max _{\bar{\Omega}}|\nabla \bar{\psi}| \leqslant \max _{\partial \Omega}|\nabla \bar{\psi}| . \tag{26}
\end{equation*}
$$

Thus using comparison principle, Hopf lemma and periodicity, we can show that the maximum of the flow speed increases as $m$ increases (cf. [20, Lemma 4.4]).

### 2.3. Stream function formulation of general Euler flows

For any $m \in(0, \hat{m})$, there exists a unique periodic solution $\bar{\psi}\left(x_{1}, x_{2}\right) \in C^{2, \alpha}(\bar{\Omega})$ for the problem (23) and (18). Furthermore, there exist positive constants $\sigma_{0}$ and $\sigma_{1}$ such that

$$
\begin{equation*}
0<\inf _{\bar{\Omega}} \bar{\psi}_{x_{2}}=\sigma_{0} \leqslant \sigma_{1}=\sup _{\bar{\Omega}}|\nabla \bar{\psi}| . \tag{27}
\end{equation*}
$$

Given $W \in \mathcal{S}$ defined by

$$
\mathcal{S}=\left\{W \in C^{1, \beta}([0,1]), \int_{0}^{1} W(s) d s=m,\left\|W-\bar{\psi}_{x_{2}}(0, \cdot)\right\|_{C^{1, \beta}[0,1]} \leqslant \sigma_{0} / 2\right\}
$$

where $\beta \in(0, \alpha)$, then $W(s)>\sigma_{0} / 2$ for $s \in[0,1]$. Therefore there exists a function $y=\kappa(\psi)$ such that

$$
\begin{equation*}
\psi=\int_{0}^{\kappa(\psi)} W(s) d s \tag{28}
\end{equation*}
$$

Differentiating (28) with respect to $\psi$ yields

$$
\begin{equation*}
\kappa^{\prime}(\psi)=\frac{1}{W(\kappa(\psi))} \tag{29}
\end{equation*}
$$

This shows that $\kappa(\psi) \in C^{2, \beta}([0, m])$. Suppose that the Bernoulli function at $x_{1}=0$ is $B_{0}(\kappa(\psi))$ in terms of $\psi$, since the Bernoulli function is a constant along each stream line, we get the Bernoulli function defined in the whole domain $\Omega$ by $B\left(x_{1}, x_{2}\right)=\mathcal{B}\left(\psi\left(x_{1}, x_{2}\right)\right)=B_{0}\left(\kappa\left(\psi\left(x_{1}, x_{2}\right)\right)\right)$. Define $\mathcal{B}(\psi)=B_{0}(\kappa(\psi))$. Then $\mathcal{B}(\psi) \in C^{2}([0, m])$. Combining (12) and (29) gives

$$
\begin{equation*}
\|\mathcal{B}-\bar{B}\|_{C^{1,1}([0, m])} \leqslant C \epsilon, \quad \mathcal{B}^{\prime}(0) \geqslant 0 \quad \text { and } \quad \mathcal{B}^{\prime}(m) \leqslant 0 \tag{30}
\end{equation*}
$$

Therefore, $\rho=H\left(|\nabla \psi|^{2}, \mathcal{B}(\psi)\right)$ follows from (22) for subsonic flows. Eq. (15) becomes the following second-order equation for the stream function $\psi$,

$$
\begin{equation*}
\operatorname{div}\left(\frac{\nabla \psi}{H\left(|\nabla \psi|^{2}, \mathcal{B}(\psi)\right)}\right)=H\left(|\nabla \psi|^{2}, \mathcal{B}(\psi)\right) \mathcal{B}^{\prime}(\psi) \tag{31}
\end{equation*}
$$

We first solve Eq. (31) with the boundary condition (18). Second, we define a map from $W$ to $\psi_{x_{2}}(0, \cdot)$. The fixed point of this map induces the solution of Euler equations.

## 3. Analysis of the boundary value problem for stream function

### 3.1. Existence of solutions

There are two main difficulties to solve Eq. (31) in $\Omega$. The first difficulty is that Eq. (31) becomes degenerate elliptic at sonic states. In addition, $H$ is not well-defined for arbitrary $\psi$ and $|\nabla \psi|$; neither is $\mathcal{B}$. The second difficulty is that this is a problem in an unbounded domain. Our basic strategy is that we extend the definition of $\mathcal{B}$ appropriately, truncate $|\nabla \psi|$ appeared in $H$ in a suitable way, and use a sequence of problems in bounded domains to approximate the problem (31) and (18).

Set

$$
\tilde{g}(s)= \begin{cases}\mathcal{B}^{\prime}(s), & \text { if } 0 \leqslant s \leqslant m, \\ \mathcal{B}^{\prime}(m)(2 m-s) / m, & \text { if } m \leqslant s \leqslant 2 m, \\ \mathcal{B}^{\prime}(0)(s+m) / m, & \text { if }-m \leqslant s \leqslant 0, \\ 0, & \text { if } s \geqslant 2 m \text { or } s \leqslant-m .\end{cases}
$$

It is obvious that $\tilde{g} \in C^{0,1}(\mathbb{R})$ and

$$
\|\tilde{g}(s)\|_{C^{0,1}\left(\mathbb{R}^{1}\right)} \leqslant\left\|\mathcal{B}^{\prime}(s)\right\|_{C^{0,1}([0, m])} \leqslant 2 \epsilon / \sigma_{0}
$$

Define

$$
\tilde{\mathcal{B}}(s)=\mathcal{B}(0)+\int_{0}^{s} \tilde{g}(t) d t
$$

Then, $\left\|\tilde{\mathcal{B}}^{\prime}\right\|_{C^{0,1}\left(\mathbb{R}^{1}\right)}=\|\tilde{g}\|_{C^{0,1}\left(\mathbb{R}^{1}\right)} \leqslant\left\|\mathcal{B}^{\prime}\right\|_{C^{1}([0, m])} \leqslant C \epsilon$. Therefore,

$$
|\tilde{\mathcal{B}}(\psi)-\bar{B}| \leqslant C \epsilon .
$$

Hence, there exists $\tilde{\epsilon}_{0}>0$ such that if $0<\epsilon<\tilde{\epsilon}_{0}$, then $\tilde{\mathcal{B}}(\psi)>H_{0}=\inf _{s} h(s)$. In view of (30), $\tilde{\mathcal{B}}$ also satisfies

$$
\begin{equation*}
\tilde{\mathcal{B}}^{\prime}(s) \geqslant 0 \quad \text { for } s \leqslant 0 \quad \text { and } \quad \tilde{\mathcal{B}}^{\prime}(s) \leqslant 0 \quad \text { for } s \geqslant m \tag{32}
\end{equation*}
$$

Let $\check{B}=\min _{x \in[0,1]} B_{0}(x)$. Choose $\theta_{0}$ to be a fixed positive constant satisfying

$$
\begin{equation*}
0<\theta_{0} \leqslant \min \left\{\Sigma^{2}(\check{B}) / 2, \Sigma^{2}(\bar{B})-\sigma_{1}^{2}\right\}, \tag{33}
\end{equation*}
$$

where $\sigma_{1}$ is defined in (27). Let $\zeta \in C^{\infty}(\mathbb{R})$ satisfy

$$
\zeta(s)= \begin{cases}s, & \text { if } s<-\theta_{0} / 4 \\ -\theta_{0} / 8, & \text { if } s \geqslant-\theta_{0} / 8\end{cases}
$$

and define $\tilde{\rho}=H\left(\zeta\left(|\nabla \psi|^{2}-\Sigma^{2}(\tilde{\mathcal{B}}(\psi))\right)+\Sigma^{2}(\tilde{\mathcal{B}}(\psi)), \tilde{\mathcal{B}}(\psi)\right)$. Instead of Eq. (31), we begin with investigating the equation

$$
\begin{equation*}
\partial_{1}\left(\frac{\partial_{1} \psi}{\tilde{\rho}}\right)+\partial_{2}\left(\frac{\partial_{2} \psi}{\tilde{\rho}}\right)=\tilde{\rho} \tilde{\mathcal{B}}^{\prime}(\psi) . \tag{34}
\end{equation*}
$$

Eq. (34) can also be written in the following non-divergence form

$$
\begin{equation*}
A_{i j}(\nabla \psi, \psi) \partial_{i j} \psi=\mathcal{F}(\nabla \psi, \psi) \tag{35}
\end{equation*}
$$

where

$$
A_{i j}(\nabla \psi, \psi)=\tilde{\rho} \delta_{i j}+\frac{\zeta^{\prime} \tilde{\rho}}{\left(\tilde{\rho}^{2} \tilde{c}^{2}-\left(\zeta+\Sigma^{2}\right)\right)} \partial_{i} \psi \partial_{j} \psi
$$

and

$$
\mathcal{F}(\nabla \psi, \psi)=\tilde{\mathcal{B}}^{\prime}(\psi)\left(\tilde{\rho}^{3} \frac{\tilde{\rho}^{2} \tilde{c}^{2}-\left(\zeta+\Sigma^{2}\right)+|\nabla \psi|^{2}}{\tilde{\rho}^{2} \tilde{c}^{2}-\left(\zeta+\Sigma^{2}\right)}+\frac{\left(\zeta^{\prime}-1\right) \Sigma \Sigma^{\prime}|\nabla \psi|^{2}}{\tilde{\rho}^{2} \tilde{c}^{2}-\left(\zeta+\Sigma^{2}\right)}\right),
$$

where the variables in $\zeta$ and $\Sigma$ are $|\nabla \psi|^{2}-\tilde{\mathcal{B}}(\psi)$ and $\tilde{\mathcal{B}}(\psi)$, respectively. The direct calculation shows that the eigenvalues $\Lambda$ and $\lambda$ of $\left[A_{i j}\right]_{2 \times 2}$ satisfy $C^{-1} \leqslant|\Lambda / \lambda| \leqslant C$ for some constant $C$ and thus Eq. (35) is uniformly elliptic. However, $\mathcal{F}$ involves a quadratic growth in $|\nabla \psi|$, so it is not easy to apply the classical elliptic theory directly. The strategy is to modify $\mathcal{F}$ by

$$
\begin{equation*}
\tilde{\mathcal{F}}(\nabla \psi, \psi)=\tilde{\mathcal{B}}^{\prime}(\psi) \frac{\tilde{\rho}^{5} \tilde{c}^{2}}{\tilde{\rho}^{2} \tilde{c}^{2}-\left(\zeta+\Sigma^{2}\right)} \tag{36}
\end{equation*}
$$

It is easy to see that $\tilde{\mathcal{F}}=\mathcal{F}$ when $\psi$ satisfies $|\nabla \psi|^{2}-\Sigma^{2}(\tilde{\mathcal{B}}(\psi)) \leqslant-\theta_{0} / 4$.
Proposition 5. There exists a solution $\psi(\cdot ; t) \in C^{2, \alpha}(\bar{\Omega})$ of the problem

$$
\left\{\begin{array}{l}
A_{i j} \partial_{i j} \psi=\tilde{\mathcal{F}},  \tag{37}\\
\psi=0 \quad \text { on } S_{1}, \quad \psi=t \quad \text { on } S_{2}
\end{array}\right.
$$

Furthermore, if $t \leqslant m$, then

$$
\begin{equation*}
0 \leqslant \psi \leqslant m \tag{38}
\end{equation*}
$$

There exist $m_{1}>0$ and $\epsilon_{1}>0$ such that if $0 \leqslant t \leqslant m_{1}$ and $\left\|\mathcal{B}^{\prime}\right\| \leqslant \epsilon_{1}$, then

$$
\begin{equation*}
|\nabla \psi|^{2}-\Sigma^{2}(\mathcal{B}(\psi)) \leqslant-\theta_{0} / 2 \tag{39}
\end{equation*}
$$

Proof. For the unbounded domain $\Omega$, we use a sequence of boundary value problems defined in bounded domains $\tilde{\Omega}_{N}$ to approximate the problem in $\Omega$, where $\tilde{\Omega}_{N} \in C^{2, \alpha}$ satisfies $\Omega_{N} \subset \tilde{\Omega}_{N} \subset \Omega_{2 N}$ with $\Omega_{k}:=\Omega \cap\left\{\left|x_{1}\right| \leqslant k\right\}$. The construction of $\tilde{\Omega}_{N}$ can be found in [20].

We first solve the boundary value problem

$$
\left\{\begin{array}{l}
A_{i j}(\nabla \psi, \psi) \partial_{i j} \psi=\tilde{\mathcal{F}}(\nabla \psi, \psi) \quad \text { in } \tilde{\Omega}_{N}  \tag{40}\\
\psi=\frac{x_{2}-f_{1}\left(x_{1}\right)}{f_{2}\left(x_{1}\right)-f_{1}\left(x_{1}\right)} t \quad \text { on } \partial \tilde{\Omega}_{N}
\end{array}\right.
$$

Similar to the proof of Proposition 3 in [22], there exists a $C^{2, \alpha}$-solution $\psi_{N}$, such that

$$
\left|\psi_{N}\right| \leqslant C\left(t+\left|\frac{\tilde{\mathcal{F}}}{\lambda}\right|_{0}\right), \quad\left\|\psi_{N}\right\|_{2, \alpha ; \tilde{\Omega}_{N}} \leqslant C\left(\Lambda / \lambda,\left|f_{i}\right|_{C^{2, \alpha}}, m,\left|\frac{\tilde{\mathcal{F}}}{\lambda}\right|_{0}\right) .
$$

By Arzela-Ascoli theorem, one can select a subsequence of $\left\{\psi_{N}\right\}$ (we still label it by $\left\{\psi_{N}\right\}$ ), such that

$$
\psi_{N} \rightarrow \psi \quad \text { in } C^{2, \alpha_{1}}(K) \quad \text { with } K \Subset \bar{\Omega}, \alpha_{1}<\alpha .
$$

Obviously, $\psi$ solves (37).
Since $\tilde{\mathcal{B}}$ satisfies (32), then $\tilde{\mathcal{F}}\left(\nabla \psi_{N}, \psi_{N}\right) \geqslant 0$ in the domain $\tilde{\Omega}_{N} \cap\left\{\psi_{N} \geqslant m\right\}$. Thus according to system (40),

$$
A_{i j}\left(\nabla \psi_{N}, \psi_{N}\right) \partial_{i j} \psi_{N} \geqslant 0 \quad \text { in } \tilde{\Omega}_{N} \cap\left\{\psi_{N} \geqslant m\right\}
$$

Since

$$
\psi_{N} \leqslant m \quad \text { on } \partial\left(\tilde{\Omega}_{N} \cap\left\{\psi_{N} \geqslant m\right\}\right)
$$

by the maximum principle [16, Theorem 3.1], one has

$$
\psi_{N} \leqslant \sup _{\partial \tilde{\Omega}_{N}} \psi_{N} \leqslant m \quad \text { in } \tilde{\Omega}_{N} \cap\left\{\psi_{N} \geqslant m\right\} .
$$

Similarly, it is also true that

$$
\psi_{N} \geqslant \inf _{\partial \tilde{\Omega}_{N}} \psi_{N} \geqslant 0 \quad \text { in } \tilde{\Omega}_{N} \cap\left\{\psi_{N} \leqslant 0\right\}
$$

Therefore, one has $0 \leqslant \psi_{N} \leqslant m$. So the limit $\psi$ satisfies (38).
The Hölder estimate for the gradients of elliptic equations of two variables implies that

$$
\left[\psi_{N}\right]_{1, \mu ; \tilde{\Omega}_{N}}=\sup _{x, y \in \tilde{\Omega}_{N}} \frac{\left|\nabla \psi_{N}(x)-\nabla \psi_{N}(y)\right|}{|x-y|^{\mu}} \leqslant C\left(\Lambda / \lambda,\left|f_{i}\right|_{2}\right)\left(1+t+\left|\frac{\tilde{\mathcal{F}}}{\lambda}\right|_{0}\right)
$$

Then, $\psi_{N}$ satisfies the estimate

$$
\left|\nabla \psi_{N}\right|^{2} \leqslant \eta\left(1+t+\left|\frac{\tilde{\mathcal{F}}}{\lambda}\right|_{0}\right)^{2}+C_{\eta}\left(t+\left|\frac{\tilde{\mathcal{F}}}{\lambda}\right|_{0}\right)^{2},
$$

where $C_{\eta}$ is independent of $N$. Note that

$$
\begin{equation*}
|\tilde{\mathcal{F}}| \leqslant C \epsilon \tag{41}
\end{equation*}
$$

There exist $\eta_{1}, m_{1}$ and $\epsilon_{1}$ such that

$$
\begin{equation*}
\eta_{1}\left(1+m_{1}+C \epsilon_{1}\right)^{2} \leqslant \min \left\{\frac{\Sigma^{2}(\check{B})}{4}, \frac{\sigma_{1}^{2}}{2}\right\}, \quad C_{\eta_{1}}\left(m_{1}+C \epsilon_{1}\right)^{2} \leqslant \min \left\{\frac{\Sigma^{2}(\check{B})}{4}, \frac{\sigma_{1}^{2}}{2}\right\} . \tag{42}
\end{equation*}
$$

If $t \leqslant m_{1}, \epsilon \leqslant \epsilon_{1}$, then

$$
\left|\nabla \psi_{N}\right|^{2}-\Sigma^{2}\left(\mathcal{B}\left(\psi_{N}\right)\right) \leqslant-\frac{\Sigma^{2}(\check{B})}{2} \leqslant-\theta_{0}
$$

Thus, the limit $\psi$ satisfies (39) if $\epsilon_{1}$ is suitably small.
This finishes the proof of the proposition.
3.2. Uniqueness, periodicity and positivity of horizontal velocity

In this subsection, we show that the uniformly subsonic solution for the problem (31) with the boundary condition

$$
\begin{equation*}
\psi=0 \quad \text { on } S_{1}, \quad \text { and } \quad \psi=t \quad \text { on } S_{2} \tag{43}
\end{equation*}
$$

is unique.
Proposition 6. There exists a positive constant $\epsilon_{2}<\epsilon_{1}$ such that if $\left\|\mathcal{B}^{\prime}\right\|_{C^{0,1}}=\epsilon \leqslant \epsilon_{2}$, then for $0 \leqslant t \leqslant m$, the solution $\psi$ of (31) and (43) which satisfies

$$
\begin{equation*}
|\nabla \psi|^{2}-\Sigma^{2}(\mathcal{B}(\psi)) \leqslant-\theta_{0} / 4, \quad 0 \leqslant \psi \leqslant m, \tag{44}
\end{equation*}
$$

must be unique.
Proof. Let $\psi_{i}, i=1,2$, both solve (31) and (43). Set $\psi=\psi_{1}-\psi_{2}$. Then $\Psi$ satisfies the following elliptic boundary value problem,

$$
\left\{\begin{array}{l}
\partial_{i}\left(a_{i j} \partial_{j} \Psi\right)+\partial_{i}\left(b_{i} \Psi\right)=c_{i} \partial_{i} \Psi+d \Psi, \quad \text { in } \Omega,  \tag{45}\\
\Psi=0, \quad \text { on } \partial \Omega
\end{array}\right.
$$

where

$$
\begin{gathered}
a_{i j}=\int_{0}^{1} \frac{\left(\tilde{H}^{2} \tilde{c}^{2}-|\nabla \tilde{\Psi}|^{2}\right) \delta_{i j}+\partial_{i} \tilde{\Psi} \partial_{j} \tilde{\Psi}}{\left(|\nabla \tilde{\Psi}|^{2}-\tilde{H}^{2} \tilde{c}^{2}\right) \tilde{H}} d \theta, \quad b_{i}=-\int_{0}^{1} \frac{\partial_{i} \tilde{\Psi} \tilde{H} \mathcal{B}^{\prime}(\tilde{\Psi})}{\tilde{H}^{2} \tilde{c}^{2}-|\nabla \tilde{\Psi}|^{2}} d \theta, \\
c_{i}=\int_{0}^{1} \frac{\tilde{H} \partial_{i} \tilde{\Psi}}{|\nabla \tilde{\Psi}|^{2}-\tilde{H}^{2} \tilde{c}^{2}} \mathcal{B}^{\prime}(\tilde{\Psi}) d \theta, \quad d=\int_{0}^{1} \frac{\tilde{H}^{3}}{\tilde{H}^{2} \tilde{c}^{2}-|\nabla \tilde{\Psi}|^{2}}\left[\mathcal{B}^{\prime}(\tilde{\Psi})\right]^{2}+\tilde{H} \mathcal{B}^{\prime \prime}(\tilde{\Psi}) d \theta,
\end{gathered}
$$

with $\tilde{c}=\sqrt{p^{\prime}(\tilde{H})}, \tilde{H}=H\left(|\nabla \tilde{\Psi}|^{2}, \mathcal{B}(\tilde{\Psi})\right)$, and $\tilde{\Psi}=\theta \psi_{1}+(1-\theta) \psi_{2}$. Since $\left\|\mathcal{B}^{\prime}\right\|_{C^{0,1}} \leqslant C \epsilon$, we have

$$
\left|b_{i}\right|+\left|c_{i}\right|+|d| \leqslant C \epsilon .
$$

Choose a smooth cut-off function $\eta \in C_{0}^{\infty}(\mathbb{R})$ satisfying

$$
\eta=\eta(s)= \begin{cases}0, & |s| \geqslant(N+1) L  \tag{46}\\ 1, & |s| \leqslant N L\end{cases}
$$

Multiplying $\eta^{2}\left(x_{1}\right) \Psi$ on both sides of Eq. (45) and integrating by parts yield that

$$
\begin{aligned}
\iint_{\left\{\left|x_{1}\right| \leqslant N L\right\} \cap \Omega}|\nabla \Psi|^{2} d x_{1} d x_{2} & \leqslant C \iint_{\Omega} \eta^{2}\left(a_{i j} \partial_{i} \Psi \partial_{j} \Psi\right) d x_{1} d x_{2} \\
& \leqslant C \iint_{\Omega}\left(\left|\eta \eta^{\prime} \Psi\right|(|\Psi|+|\nabla \Psi|)+\epsilon \eta^{2}|\Psi|(|\Psi|+|\nabla \Psi|)\right) d x_{1} d x_{2}
\end{aligned}
$$

$$
\begin{aligned}
\leqslant C & \iint_{\left\{N L \leqslant\left|x_{1}\right| \leqslant(N+1) L\right\} \cap \Omega}\left(|\Psi|^{2}+|\nabla \Psi|^{2}\right) d x_{1} d x_{2} \\
& +C \epsilon \underset{\left\{\left|x_{1}\right| \leqslant N L\right\} \cap \Omega}{\iint\left(|\Psi|^{2}+|\nabla \Psi|^{2}\right) d x_{1} d x_{2} .}
\end{aligned}
$$

Since $\Psi=0$ on $\partial \Omega$, by Poincaré's inequality, we have

$$
\iint_{\left\{k L \leqslant\left|x_{1}\right| \leqslant(k+1) L\right\} \cap \Omega}|\Psi|^{2} d x_{1} d x_{2} \leqslant C \quad \iint_{\left\{k L \leqslant\left|x_{1}\right| \leqslant(k+1) L\right\} \cap \Omega}|\nabla \Psi|^{2} d x_{1} d x_{2}
$$

for any $k \in \mathbb{Z}$. When $\epsilon \leqslant \epsilon_{2}$ for some $\epsilon_{2}>0$, we have

$$
\begin{equation*}
\iint_{\left\{\left|x_{1}\right| \leqslant N L\right\} \cap \Omega}|\nabla \Psi|^{2} d x_{1} d x_{2} \leqslant C \quad \iint_{\left\{N L \leqslant\left|x_{1}\right| \leqslant(N+1) L\right\} \cap \Omega}|\nabla \Psi|^{2} d x_{1} d x_{2} \tag{47}
\end{equation*}
$$

Noting that $|\nabla \Psi| \in L^{\infty}(\Omega)$, it yields that $\nabla \Psi \in L^{2}(\Omega)$. Thus

$$
\lim _{N \rightarrow \infty} \iint_{\left\{N L \leqslant\left|x_{1}\right| \leqslant(N+1) L\right\} \cap \Omega}|\nabla \Psi|^{2} d x_{1} d x_{2}=0 .
$$

Therefore, the estimate (47) implies that $\iint_{\Omega}|\nabla \Psi|^{2} \equiv 0$. It follows from $\Psi \equiv 0$ on $\partial \Omega$ that $\Psi \equiv 0$ in $\Omega$. Therefore, the solution of (31) and (43) is unique.

One can check easily that if $\psi\left(x_{1}, x_{2}\right)$ solves the boundary value problem (31) and (18), so does $\psi\left(x_{1}+L, x_{2}\right)$. Then the uniqueness implies the following corollary.

Corollary 7. For any $\theta_{0}>0$, there exists a positive constant $\epsilon_{2}<\epsilon_{1}$ such that if $\left\|\mathcal{B}^{\prime}\right\|_{C^{0,1}}=\epsilon \leqslant \epsilon_{2}$, then for $0 \leqslant t \leqslant m$, the solution $\psi$ of (31) and (43) satisfying (44) must be periodic with respect to $x_{1}$ with period $L$, i.e.,

$$
\psi\left(x_{1}, x_{2}\right)=\psi\left(x_{1}+L, x_{2}\right), \quad \forall\left(x_{1}, x_{2}\right) \in \Omega .
$$

Now we show that $\psi_{x_{2}}(0, \cdot) \in \mathcal{S}$.
Proposition 8. For any $\theta_{0}>0$, there exists a positive constant $\epsilon_{3}<\epsilon_{2}$ such that if $\left\|\mathcal{B}^{\prime}\right\|_{C^{0,1}}=\epsilon \leqslant \epsilon_{3}$ and the solution $\psi$ of (31) and (43) with $t \in(0, m)$ satisfies (44), then $\|\nabla \psi-\nabla \bar{\psi}\|_{C^{1}, \alpha} \leqslant C \epsilon$.

Proof. Set $\psi=\psi-\bar{\psi}$. Subtracting (23) from (31) gives that $\psi$ satisfies

$$
\left\{\begin{array}{l}
\partial_{i}\left(a_{i j} \partial_{j} \psi+b_{i}(\mathcal{B}(\psi)-\bar{B})\right)=H\left(|\nabla \psi|^{2}, \mathcal{B}(\psi)\right) \mathcal{B}^{\prime}(\psi) \text { in } \Omega,  \tag{48}\\
\Psi=0 \text { on } \partial \Omega,
\end{array}\right.
$$

where

$$
a_{i j}=\int_{0}^{1} \frac{\left(\hat{H}^{2} \hat{c}^{2}-|\nabla \hat{\Psi}|^{2}\right) \delta_{i j}+\partial_{i} \hat{\Psi} \partial_{j} \hat{\Psi}}{\hat{H}\left(\hat{H}^{2} \hat{c}^{2}-|\nabla \hat{\Psi}|^{2}\right)} d \theta, \quad b_{i}=-\int_{0}^{1} \frac{\partial_{i} \hat{\Psi} \hat{H}}{\hat{H}^{2} \hat{c}^{2}-|\nabla \hat{\Psi}|^{2}} d \theta,
$$

with $\hat{c}=\sqrt{p^{\prime}(\hat{H})}, \hat{H}=H\left(|\nabla \hat{\Psi}|^{2}, \theta \mathcal{B}(\psi)+(1-\theta) \bar{B}\right), \hat{\Psi}=\theta \psi+(1-\theta) \bar{\psi}$. Since both $\psi$ and $\bar{\psi}$ are periodic, $\Psi$ is also periodic with period $L$. Multiplying the equation in (48) with $\Psi$ and integrating the resulting equation on $\Omega \cap\left\{-2 L \leqslant x_{1} \leqslant 2 L\right\}$, and integration by parts yield

$$
\|\nabla \Psi\|_{L^{2}\left(\Omega \cap\left\{-2 L \leqslant x_{1} \leqslant 2 L\right\}\right)} \leqslant C \epsilon
$$

Applying Moser's iteration [16, Theorems 8.17 and 8.25], we have

$$
\|\Psi\|_{L^{\infty}\left(\Omega \cap\left\{-\frac{L}{2} \leqslant x_{1} \leqslant \frac{3 L}{2}\right\}\right)} \leqslant C \epsilon .
$$

Using the estimate for elliptic equation of two variables [16, Theorem 12.4 and global estimates on p. 304], we have

$$
\|\Psi\|_{C^{1, \alpha}\left(\bar{\Omega} \cap\left\{0 \leqslant x_{1} \leqslant L\right\}\right)} \leqslant C \epsilon .
$$

It follows from Schauder estimate that $\|\Psi\|_{C^{2, \alpha}\left(\Omega_{1}\right)} \leqslant C \epsilon$. Choosing $\epsilon_{3}>0$ sufficiently small shows that $\|\nabla \Psi\|_{C^{1, \alpha}\left(\Omega_{1}\right)} \leqslant \sigma_{0} / 2$ provided $0<\epsilon \leqslant \epsilon_{3}$. This finishes the proof of the proposition.

## 4. Existence and uniqueness of the Euler flows

In this section, we prove the existence and uniqueness of subsonic solutions for Euler equations.

Proposition 9. There exists a positive constant $\epsilon_{5}$ such that if $\left\|B_{0}^{\prime}\right\|_{C^{1}} \leqslant \epsilon_{5}$, then the system (1)-(3) under the conditions (5), mass flux condition (6), and the condition (10) has a subsonic solution with positive horizontal velocity.

Proof. It follows from Proposition 5 that there exists a solution $\psi(\cdot ; t)$ for the problem (37). Set

$$
S(t)=\{\psi(\cdot ; t) \mid \psi(\cdot ; t) \text { solves }(37)\}
$$

and

$$
\Delta(t)=\inf _{\psi \in S(t)} \sup _{\bar{\Omega}}\left\{|\nabla \psi(\cdot ; t)|^{2}-\Sigma^{2}(\tilde{B}(\psi(\cdot ; t)))\right\}
$$

Then $\Delta(t)$ is continuous for $t \in[0, m]$ (cf. [22, Proposition 6]). If $t \leqslant m$, then

$$
\begin{aligned}
& |\nabla \psi(\cdot ; t)|^{2}-\Sigma^{2}(\mathcal{B}(\psi(\cdot ; t))) \\
& \quad=|\nabla \psi(\cdot ; t)|^{2}-|\nabla \bar{\psi}(\cdot ; t)|^{2}+|\nabla \bar{\psi}(\cdot ; t)|^{2}-\Sigma^{2}(\bar{B})+\Sigma^{2}(\bar{B})-\Sigma^{2}(\mathcal{B}(\psi(\cdot ; t))) \\
& \quad \leqslant C \epsilon-\theta_{0}+C \epsilon
\end{aligned}
$$

where we use the property that the maximum of flow speed increases as the mass flux increases in Lemma 4. Thus there exists a positive $\epsilon_{4} \leqslant \epsilon_{3}$ such that $|\nabla \psi(\cdot ; t)|^{2}-\Sigma^{2}(\mathcal{B}(\psi(\cdot ; t))) \leqslant-\theta_{0} / 2$. Thus it implies that for $t=m$ the problem (37) has a unique solution satisfying

$$
|\nabla \psi|^{2}-\Sigma(\mathcal{B}(\psi)) \leqslant-\theta_{0} / 4
$$

Using Proposition 8 , there exists a positive constant $\epsilon_{4}<\epsilon_{3}$ such that $|\nabla \psi-\nabla \bar{\psi}| \leqslant \sigma_{0} / 2$. In particular, $\left|\partial_{x_{2}} \psi(0, \cdot)-\partial_{x_{2}} \bar{\psi}(0, \cdot)\right| \leqslant \sigma_{0} / 2$. Therefore $\partial_{x_{2}} \psi(0, \cdot) \in \mathcal{S}$. Hence, we can define a map $T: \mathcal{S} \rightarrow \mathcal{S}$ by

$$
T(W)=\psi_{x_{2}}(0, \cdot)
$$

By Proposition $8,\left\|\psi_{x_{2}}(0, \cdot)-\bar{\psi}_{x_{2}}(0, \cdot)\right\|_{\mathcal{C}^{1, \alpha}} \leqslant C \epsilon$. Thus $T \mathcal{S}$ is a compact subset of $\mathcal{S}$. It is easy to see that $T$ is a continuous map. Note that $\mathcal{S}$ is a closed convex set in $C^{1, \beta}[0,1]$; the existence of fixed point of $T$ on $\mathcal{S}$ follows from Schauder fixed point theorem [16, Theorem 11.1].

Let $\hat{W}$ be the fixed point of $T$ and $\hat{\kappa}(y)$ satisfy

$$
y=\int_{0}^{\hat{\kappa}(y)} \hat{W}(s) d s .
$$

Define $\hat{\mathcal{B}}(\psi)=B_{0}(\hat{\mathcal{K}}(\psi))$. Then

$$
\left\{\begin{array}{l}
\operatorname{div}\left(\frac{\nabla \psi}{H\left(|\nabla \psi|^{2}, \hat{\mathcal{B}}(\psi)\right)}\right)=H\left(|\nabla \psi|^{2}, \hat{\mathcal{B}}(\psi)\right) \hat{\mathcal{B}}^{\prime}(\psi), \\
\psi=0 \text { on } S_{1} \text { and } \psi=m \text { on } S_{2}
\end{array}\right.
$$

has a solution satisfying $\hat{\psi}_{x_{2}}\left(0, x_{2}\right)=\hat{W}\left(x_{2}\right)$. It is clear that $\rho=H\left(|\nabla \hat{\psi}|^{2}, \hat{\mathcal{B}}(\psi)\right), u=\partial_{x_{2}} \hat{\psi} / \rho$, and $v=-\partial_{x_{2}} \hat{\psi} / \rho$ satisfy the Euler equations and the condition

$$
\left(\frac{u^{2}+v^{2}}{2}+h(\rho)\right)\left(0, x_{2}\right)=\hat{\mathcal{B}}\left(\psi\left(0, x_{2}\right)\right)=B_{0}\left(x_{2}\right) .
$$

Thus we get the existence of solution for Euler system under the conditions (5), mass flux condition (6), and the condition (10). Furthermore, it follows from Proposition 8 that horizontal velocity is positive.

Now we show that the periodic Euler flow is also unique.
Proposition 10. There exists a positive constant $\epsilon_{6}$ such that if $\left\|B_{0}^{\prime}\right\|_{C^{1}} \leqslant \epsilon_{6}$, then the uniformly subsonic solution of the system (1)-(3) under the conditions (5), mass flux condition (6), and the condition (10) is unique.

Proof. Suppose that $\psi_{i}(i=1,2)$ are stream functions of two periodic solutions of the Euler equations with positive velocity. Let $\kappa_{i}(i=1,2)$ be the functions satisfying $\kappa_{i}\left(\psi_{i}\left(0, x_{2}\right)\right)=x_{2}(i=1,2)$. Set $\mathcal{B}_{i}(\psi)=B_{0}\left(\kappa_{i}(\psi)\right)$. Then $\psi_{i}$ satisfies the problem

$$
\left\{\begin{array}{l}
\operatorname{div}\left(\frac{\nabla \psi}{H\left(|\nabla \psi|^{2}, \mathcal{B}_{i}(\psi)\right)}\right)=H\left(|\nabla \psi|^{2}, \mathcal{B}_{i}(\psi)\right) \mathcal{B}_{i}^{\prime}(\psi) \quad \text { in } \Omega, \\
\psi=0 \quad \text { on } S_{1}, \quad \psi=m \text { on } S_{2}
\end{array}\right.
$$

Set $\Psi=\psi_{1}-\psi_{2}$. Then $\Psi$ satisfies the problem

$$
\left\{\begin{array}{l}
\partial_{i}\left(a_{i j} \partial_{j} \Psi\right)+\partial_{i}\left(b_{i} \mathcal{D}\right)=c_{i} \partial_{i} \Psi+d \mathcal{D}+e \mathcal{E} \text { in } \Omega,  \tag{49}\\
\Psi=0 \text { on } \partial \Omega
\end{array}\right.
$$

where

$$
a_{i j}=\int_{0}^{1} \frac{\left(H^{2} c^{2}-|\nabla \tilde{\Psi}|^{2}\right) \delta_{i j}+\partial_{i} \tilde{\Psi} \partial_{j} \tilde{\Psi}}{H\left(H^{2} c^{2}-|\nabla \tilde{\Psi}|^{2}\right)} d \theta, \quad b_{i}=-\int_{0}^{1} \frac{\partial_{i} \tilde{\Psi} H}{H^{2} c^{2}-|\nabla \tilde{\Psi}|^{2}} d \theta,
$$

$$
\begin{gathered}
c_{i}=\int_{0}^{1} \frac{H \partial_{i} \tilde{\Psi}}{|\nabla \tilde{\Psi}|^{2}-H^{2} c^{2}}\left(\theta \mathcal{B}_{1}^{\prime}\left(\psi_{1}\right)+(1-\theta) \mathcal{B}_{2}^{\prime}\left(\psi_{2}\right)\right), \\
d=\int_{0}^{1} \frac{H^{3}}{H^{2} c^{2}-|\nabla \tilde{\Psi}|^{2}}\left(\theta \mathcal{B}_{1}^{\prime}\left(\psi_{1}\right)+(1-\theta) \mathcal{B}_{2}^{\prime}\left(\psi_{2}\right)\right) d \theta, \quad e=\int_{0}^{1} H d \theta,
\end{gathered}
$$

with $\tilde{\Psi}=\theta \psi_{1}+(1-\theta) \psi_{2}, H=H\left(|\nabla \tilde{\Psi}|^{2}, \theta \mathcal{B}_{1}\left(\psi_{1}\right)+(1-\theta) \mathcal{B}_{2}\left(\psi_{2}\right)\right), \mathcal{D}=\mathcal{B}_{1}\left(\psi_{1}\right)-\mathcal{B}_{2}\left(\psi_{2}\right)$ and $\mathcal{E}=$ $\mathcal{B}_{1}^{\prime}\left(\psi_{1}\right)-\mathcal{B}_{2}^{\prime}\left(\psi_{2}\right)$.

We first multiply $\Psi$ on both sides of the equation in (49) and integrate the resulting equation on $\Omega_{1}$. In view of periodicity of the coefficients and $\Psi$ in (49), integration by parts yields

$$
\begin{equation*}
\int_{\Omega_{1}} a_{i j} \partial_{i} \Psi \partial_{j} \Psi d x=\int_{\Omega_{1}}\left(b_{i} \mathcal{D} \partial_{i} \Psi+c_{i} \Psi \partial_{i} \Psi\right)+d \mathcal{D} \Psi+e \mathcal{E} \Psi d x . \tag{50}
\end{equation*}
$$

Thus,

$$
\begin{equation*}
\int_{\Omega_{1}}|\nabla \Psi|^{2} d x \leqslant C \delta \int_{\Omega_{1}}\left(|\Psi|^{2}+|\nabla \Psi|^{2}\right) d x+C(\delta) \int_{\Omega_{1}}\left(|\mathcal{D}|^{2}+|\mathcal{E}|^{2}\right) d x . \tag{51}
\end{equation*}
$$

Since $\Psi \in W^{1, \infty}$, the first term on the right-hand side of (51) is bounded. Noting that $\Psi=0$ on $\partial \Omega \cap \bar{\Omega}_{1}$, Poincaré inequality implies that

$$
\int_{\Omega_{1}}|\Psi|^{2} d x \leqslant C \int_{\Omega_{1}}|\nabla \Psi|^{2} d x
$$

Therefore, after choosing $\delta$ suitably small, the first term on the right-hand side of (51) can be absorbed by the left-hand side.

Now let us estimate the second term on the right-hand side of (51). First,

$$
\begin{aligned}
\int_{\Omega_{1}}|\mathcal{D}|^{2} d x & =\int_{\Omega_{1}}\left|B_{0} \circ \kappa_{1}\left(\psi_{1}\right)-B_{0} \circ \kappa_{2}\left(\psi_{2}\right)\right|^{2} d x \\
& \leqslant 2 \int_{\Omega_{1}}\left|B_{0} \circ \kappa_{1}\left(\psi_{1}\right)-B_{0} \circ \kappa_{1}\left(\psi_{2}\right)\right|^{2} d x+2 \int_{\Omega_{1}}\left|B_{0} \circ \kappa_{1}\left(\psi_{2}\right)-B_{0} \circ \kappa_{2}\left(\psi_{2}\right)\right|^{2} d x \\
& =I_{1}+I_{2} .
\end{aligned}
$$

Using mean value theorem, we have

$$
I_{1} \leqslant C \epsilon \int_{\Omega_{1}}|\Psi|^{2} d x \leqslant C \epsilon \int_{\Omega_{1}}|\nabla \Psi|^{2} d x
$$

Noting that $\psi_{1}\left(0, \kappa_{1}\left(\psi_{2}\right)\right)=\psi_{2}\left(0, \kappa_{2}\left(\psi_{2}\right)\right)$, we have

$$
\int_{0}^{\kappa_{1}\left(\psi_{2}\right)} \partial_{x_{2}} \psi_{1}(0, s)-\partial_{x_{2}} \psi_{2}(0, s) d s=\int_{\kappa_{1}\left(\psi_{2}\right)}^{\kappa_{2}\left(\psi_{2}\right)} \partial_{x_{2}} \psi_{2}(0, s) d s
$$

In view of the fact that $\partial_{x_{2}} \psi_{2} \geqslant \frac{\sigma_{0}}{2}$, we have

$$
\left|\kappa_{1}\left(\psi_{2}\right)-\kappa_{2}\left(\psi_{2}\right)\right| \leqslant C\|\nabla \Psi(0, \cdot)\|_{L^{2}[0,1]}
$$

Thus,

$$
I_{2} \leqslant \int_{\Omega_{1}} C \epsilon\|\nabla \Psi(0, \cdot)\|_{L^{2}[0,1]} d x_{1} d x_{2} \leqslant C \epsilon\|\nabla \Psi\|_{L^{\infty}\left(\Omega_{1}\right)}
$$

Similarly, we can show that $\int_{\Omega_{1}}|\mathcal{E}|^{2} d x_{1} d x_{2} \leqslant C \epsilon\|\nabla \Psi\|_{L^{\infty}\left(\Omega_{1}\right)}$.
This implies that

$$
\|\nabla \Psi\|_{L^{2}\left(\Omega_{1}\right)} \leqslant C \epsilon\|\nabla \Psi\|_{L^{\infty}\left(\Omega_{1}\right)} .
$$

By Nash-Moser's iteration, we have

$$
\|\Psi\|_{L^{\infty}\left(\Omega_{1}\right)} \leqslant C \epsilon\|\nabla \Psi\|_{L^{\infty}\left(\Omega_{1}\right)} .
$$

Using the estimate for elliptic equation of two variables [16, Theorem 12.4 and global estimates on p. 304], we have

$$
\|\Psi\|_{C^{1, \alpha}\left(\Omega_{1}\right)} \leqslant C \epsilon\|\Psi\|_{L^{\infty}\left(\Omega_{1}\right)}=C \epsilon\|\Psi\|_{L^{\infty}\left(\Omega_{1}\right)} .
$$

Therefore $\Psi \equiv 0$ in $\Omega$.
This finishes the proof of the proposition.
Choosing $\epsilon_{0}=\min \left\{\epsilon_{1}, \epsilon_{2}, \epsilon_{3}, \epsilon_{5}, \epsilon_{6}\right\}$, then Theorem 2 follows from Propositions 9 and 10 .

## Acknowledgments

The second author thanks Professor Louis Nirenberg for proposing this problem and helpful discussions. Part of the work was done when the second author was visiting The Institute of Mathematical Sciences, The Chinese University of Hong Kong. He thanks the institute for its hospitality and support. Both of the authors thank Professor Zhouping Xin for helpful discussions.

## References

[1] Gabriele Anzellotti, Pairings between measures and bounded functions and compensated compactness, Ann. Mat. Pura Appl. 135 (1983) 293-318.
[2] M. Bergner, J. Dittrich, A uniqueness and periodicity result for solutions of elliptic equations in unbounded domains, arXiv:0711.3108v1.
[3] L. Bers, Existence and uniqueness of a subsonic flow past a given profile, Comm. Pure Appl. Math. 7 (1954) 441-504.
[4] L. Bers, Mathematical Aspects of Subsonic and Transonic Gas Dynamics, Surv. Appl. Math., vol. 3, John Wiley \& Sons, Inc., New York, 1958.
[5] Gui-Qiang Chen, Jun Chen, Mikhail Feldman, Transonic shocks and free boundary problems for the full Euler equations in infinite nozzles, J. Math. Pures Appl. 88 (2007) 191-218.
[6] Gui-Qiang Chen, Jun Chen, Kyungwoo Song, Transonic nozzle flows and free boundary problems for the full Euler equations, J. Differential Equations 229 (2006) 92-120.
[7] G.Q. Chen, C. Dafermos, M. Slemrod, D.H. Wang, On two-dimensional sonic-subsonic flow, Comm. Math. Phys. 271 (2007) 635-647.
[8] Gui-Qiang Chen, Mikhail Feldman, Multidimensional transonic shocks and free boundary problems for nonlinear equations of mixed type, J. Amer. Math. Soc. 16 (2003) 461-494.
[9] Gui-Qiang Chen, Mikhail Feldman, Steady transonic shocks and free boundary problems for the Euler equations in infinite cylinders, Comm. Pure Appl. Math. 57 (2004) 310-356.
[10] Jun Chen, Subsonic Euler flows in half plane, J. Hyperbolic Differ. Equ. 6 (2009) 207-228.
[11] Shuxing Chen, Transonic shocks in 3-D compressible flow passing a duct with a general section for Euler systems, Trans. Amer. Math. Soc. 360 (2008) 5265-5289.
[12] Shuxing Chen, Hairong Yuan, Transonic shocks in compressible flow passing a duct for three-dimensional Euler systems, Arch. Ration. Mech. Anal. 187 (2008) 523-556.
[13] R. Courant, K.O. Friedrichs, Supersonic Flow and Shock Waves, Interscience Publishers, New York, 1948.
[14] Lili Du, Ben Duan, Global subsonic Euler flows in an infinitely long axisymmetric nozzle, J. Differential Equations 250 (2) (2011) 813-847.
[15] Lili Du, Zhouping Xin, Wei Yan, Subsonic flows in a multi-dimensional nozzle, Arch. Ration. Mech. Anal. 201 (2011) 9651012.
[16] D. Gilbarg, N.S. Trudinger, Elliptic Partial Differential Equations of Second Order, Springer-Verlag, Berlin, 1998.
[17] Jun Li, Zhouping Xin, Huicheng Yin, On transonic shocks in a nozzle with variable end pressures, Comm. Math. Phys. 291 (2009) 111-150.
[18] Jun Li, Zhouping Xin, Huicheng Yin, A free boundary value problem for the Euler system and 2-D transonic shock in a large variable nozzle, Math. Res. Lett. 16 (2009) 777-796.
[19] Li Liu, Global subsonic compressible flows through a two-dimensional periodic duct, Rend. Circ. Mat. Palermo 58 (2009) 407-417.
[20] Chunjing Xie, Zhouping Xin, Global subsonic and subsonic-sonic flows through infinitely long nozzles, Indiana Univ. Math. J. 56 (2007) 2991-3023.
[21] Chunjing Xie, Zhouping Xin, Global subsonic and subsonic-sonic flows through infinitely long axially symmetric nozzles, J. Differential Equations 248 (2010) 2657-2683.
[22] Chunjing Xie, Zhouping Xin, Existence of global steady subsonic Euler flows through infinitely long nozzles, SIAM J. Math. Anal. 42 (2010) 751-784.
[23] Zhouping Xin, Wei Yan, Huicheng Yin, Transonic shock problem for Euler system in a nozzle, Arch. Ration. Mech. Anal. 194 (2009) 1-47.
[24] Zhouping Xin, Huicheng Yin, Transonic shock in a nozzle. I. Two-dimensional case, Comm. Pure Appl. Math. 58 (2005) 999-1050.
[25] Zhouping Xin, Huicheng Yin, Three-dimensional transonic shocks in a nozzle, Pacific J. Math. 236 (2008) 139-193.
[26] Hairong Yuan, On transonic shocks in two-dimensional variable-area ducts for steady Euler system, SIAM J. Math. Anal. 38 (2006) 1343-1370.


[^0]:    * Corresponding author.

    E-mail addresses: cchen@math.cuhk.edu.hk (C. Chen), mathcjxie@gmail.com (C. Xie).

