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# Existence theorems for $n$ th-order discontinuous ordinary differential inclusions 

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#### Abstract

In this work an existence theorem for $n$ th-order ordinary differential inclusions is proved without the continuity of multi-valued functions. Our results are an improvement upon the existence results of Dhage et al. [B.C. Dhage, T.L. Holambe, S.K. Ntouyas, Upper and lower solutions for second order discontinuous differential inclusions, Math. Sci. Res. J. 7 (5) (2003) 206-212] and Agarwal et al. [R.P. Agarwal, B.C. Dhage, D. O'Regan, The method of upper and lower solution for differential inclusions via a lattice fixed point theorem, Dynam. Systems Appl. 12 (2003) 1-7] under weaker conditions.


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## 1. Introduction

Let $\mathbb{R}$ be a real line and let $J=[0, T]$ be a closed and bounded interval in $\mathbb{R}$. Consider the second-order differential inclusion (for short DI)

$$
\left.\begin{array}{l}
x^{(n)}(t) \in F(t, x(t)) \text { a.e. } t \in J  \tag{1.1}\\
x^{(i)}(0)=x_{i} \in \mathbb{R}, \quad i \in\{0,1, \ldots, n-1\}
\end{array}\right\}
$$

where $F: J \times \mathbb{R} \rightarrow \mathcal{P}_{p}(\mathbb{R})$ and $\mathcal{P}_{p}(\mathbb{R})$ is the class of all non-empty subsets of $\mathbb{R}$ with property $p$.
By a solution of the DI (1.1) we mean a function $x \in A C^{(n-1)}(J, \mathbb{R})$ that satisfies $x^{(n)}(t)=v(t)$ for some $v \in L^{1}(J, \mathbb{R})$ satisfying $v(t) \in F(t, x(t))$ a.e. $t \in J$, and $x^{(i)}(0)=x_{i} \in \mathbb{R}, i \in\{0,1, \ldots, n-1\}$ where $A C^{(n-1)}(J, \mathbb{R})$ is the space of real-valued functions whose $(n-1)$ th derivative exists and is absolutely continuous on $J$.

The DI (1.1) has already been studied in the literature as regards existence results under different continuity conditions of $F$. The existence theorem for DI (1.1) for the upper semi-continuous multi-function $F$ is proved in Dhage et al. [7]. Again the existence results for the ordinary second-order differential inclusions

$$
\left.\begin{array}{l}
x^{\prime \prime}(t) \in F(t, x(t)) \text { a.e. } t \in J \\
x^{(i)}(0)=x_{i} \in \mathbb{R}, i=0,1 ; \tag{1.2}
\end{array}\right\}
$$

[^0]have been studied in Benchohra [3] under upper semi-continuity of the multi-valued function between the given lower and upper solutions.

The case of discontinuous multi-valued function $F$ has been treated in Agarwal et al. [1] under monotonic conditions on $F$ and the existence of extremal solutions proved using a multi-valued lattice fixed point theorem of Dhage and O'Regan [8]. Note that the monotonic conditions used in the above papers are of very strong nature and not every Banach space is a complete lattice. These facts motivated us to pursue the study of the present work. In this work we prove existence results for the DI (1.1) under a monotonic condition which is weaker than that presented in Agarwal et al. [1].

## 2. Auxiliary results

We equip the real normed linear space $X=A C(J, \mathbb{R})$ of absolutely continuous real-valued functions on $J$ with the norm $\|\cdot\|$ and the order relation $\leq$ defined by

$$
\|x\|=\sup _{t \in J}|x(t)|
$$

and

$$
x \leq y \Longleftrightarrow x(t) \leq y(t) \forall t \in J
$$

Now we introduce different kinds of order relations in $\mathcal{P}_{p}$ as follows:
Let $A, B \in \mathcal{P}_{p}(X)$. Then by $A \stackrel{i}{\leq} B$ we mean "for every $a \in A$ there exists a $b \in B$ such that $a \leq b$ ". Again $A \stackrel{d}{\leq} B$ means that for each $b \in B$ there exists an $a \in A$ such that $a \leq b$. Further we have $A \stackrel{i d}{\leq} B \Longleftrightarrow A \stackrel{i}{\leq} B$ and $A \leq B$. Finally $A \leq B$ implies that $a \leq b$ for all $a \in A$ and $b \in B$. See Dhage [6] and references therein.

Definition 2.1. A mapping $Q: X \rightarrow \mathcal{P}_{p}(X)$ is called right monotone increasing (resp. left monotone increasing) if $Q x \stackrel{i}{\leq} Q y$ (resp. $Q x \stackrel{d}{\leq} Q y$ ) for all $x, y \in X$ for which $x \leq y$. Similarly $Q$ is called monotone increasing if it is left as well as right monotone increasing on $X$.

We need the following fixed point theorem in the following.
Theorem 2.1 (Dhage [5]). Let $[a, b]$ be an order interval in a subset $Y$ of an ordered Banach space $X$ and let $Q$ : $[a, b] \rightarrow \mathcal{P}_{c p}([a, b])$ be a right monotone increasing multi-valued mapping. If every sequence $\left\{y_{n}\right\} \subset \bigcup Q([a, b])$ defined by $y_{n} \in Q x_{n}, n \in \mathbb{N}$ has a cluster point whenever $\left\{x_{n}\right\}$ is a monotone increasing sequence in $[a, b]$, then $Q$ has a fixed point.

In the following section we prove our main existence results for DI (1.1) under suitable conditions.

## 3. Existence results

We need the following definitions later.
Definition 3.1. A multi-valued map $F: J \rightarrow \mathcal{P}_{c p, c v}\left(\mathbb{R}^{n}\right)$ is said to be measurable if for every $y \in \mathbb{R}^{n}$, the function $t \rightarrow d(y, F(t))=\inf \{\|y-x\|: x \in F(t)\}$ is measurable.

Definition 3.2. A multi-function $F(t, x)$ is called right monotone increasing in $x$ almost everywhere for $t \in J$ if $F(t, x) \stackrel{i}{\leq} F(t, y)$ a.e. for $t \in J$, for all $x, y \in \mathbb{R}$ with $x \leq y$.

Definition 3.3. A multi-valued function $F: J \times \mathbb{R} \rightarrow \mathcal{P}_{c p}(\mathbb{R})$ is called $L^{1}$-Chandrabhan if
(i) $t \mapsto F(t, x)$ is measurable for each $x \in \mathbb{R}$,
(ii) $x \mapsto F(t, x)$ is right monotone increasing almost everywhere for $t \in J$, and
(iii) for each real number $r>0$ there exists a function $h_{r} \in L^{1}(J, \mathbb{R})$ such that

$$
\|F(t, x)\|_{\mathcal{P}}=\sup \{|u|: u \in \beta(t, x)\} \leq h_{r}(t) \text { a.e. } t \in J
$$

for all $x \in \mathbb{R}$ with $|x| \leq r$.
Write

$$
S_{F}^{1}(x)=\left\{v \in L^{1}(J, \mathbb{R}) \mid v(t) \in F(t, x(t)) \text { a.e. } t \in J\right\}
$$

for some $x \in A C(J, \mathbb{R})$. The integral of the multi-function $F$ is defined as

$$
\int_{0}^{t} F(s, x(s)) \mathrm{d} s=\left\{\int_{0}^{t} v(s) \mathrm{d} s: v \in S_{F}^{1}(x)\right\} .
$$

Definition 3.4. A function $a \in A C^{(n-1)}(J, \mathbb{R})$ is called a strict lower solution of the $\mathrm{DI}(1.1)$ if for all $v \in S_{F}^{1}(a)$,

$$
\begin{aligned}
a^{(n)}(t) & \leq v(t) \text { a.e. } t \in J \\
x^{(i)}(0) & \leq x_{i}, i \in\{0,1, \ldots, n-1\} .
\end{aligned}
$$

Similarly a strict upper solution $b$ to DI (1.1) is defined.
We consider the following set of hypotheses below.
$\left(\mathrm{H}_{1}\right) F(t, x)$ is closed and bounded for each $t \in J$ and $x \in \mathbb{R}$.
$\left(\mathrm{H}_{2}\right) S_{F}^{1}(x) \neq \emptyset$ for all $x \in A C(J, \mathbb{R})$.
$\left(\mathrm{H}_{3}\right) F$ is $L^{1}$-Chandrabhan.
$\left(\mathrm{H}_{4}\right) \mathrm{DI}(1.1)$ has a strict lower solution $a$ and a strict upper solution $b$ with $a \leq b$.
Hypotheses $\left(\mathrm{H}_{1}\right)-\left(\mathrm{H}_{2}\right)$ are common in the literature. Some nice sufficient conditions for guaranteeing $\left(\mathrm{H}_{2}\right)$ appear in Aubin and Cellina [2], Deimling [4], and Lasota and Opial [10]. A mild hypothesis of $\left(\mathrm{H}_{4}\right)$ has been used in Halidias and Papageorgiou [9]. Hypothesis $\left(\mathrm{H}_{3}\right)$ is relatively new to the literature, but special forms have appeared in the works of several authors. See Dhage $[5,6]$ and references therein.

Theorem 3.1. Assume that $\left(\mathrm{H}_{1}\right)-\left(\mathrm{H}_{4}\right)$ hold. Then the DI (1.1) has a solution in $[a, b]$.
Proof. Let $X=A C(J, \mathbb{R})$ and define an order interval $[a, b]$ in $X$ which is well defined in view of hypothesis $\left(\mathrm{H}_{4}\right)$. Now the DI (1.1) is equivalent to the integral inclusion

$$
\begin{equation*}
x(t) \in \sum_{i=0}^{n-1} \frac{x_{i} t^{i}}{i!}+\int_{0}^{t} \frac{(t-s)^{n-1}}{(n-1)!} F(s, x(s)) \mathrm{d} s, \quad t \in J . \tag{3.1}
\end{equation*}
$$

See Dhage et al. [7] and the references therein. Define a multi-valued operator $Q:[a, b] \rightarrow \mathcal{P}_{p}(X)$ by

$$
\begin{align*}
Q x & =\left\{u \in X: u(t)=\sum_{i=0}^{n-1} \frac{x_{i} t^{i}}{i!}+\int_{0}^{t} \frac{(t-s)^{n-1}}{(n-1)!} v(s) \mathrm{d} s, v \in S_{F}^{1}(x)\right\}  \tag{3.2}\\
& =\left(\mathcal{L} \circ S_{F}^{1}\right)(x)
\end{align*}
$$

where $\mathcal{L}: L^{1}(J, \mathbb{R}) \rightarrow C(J, \mathbb{R})$ is a continuous operator defined by

$$
\begin{equation*}
\mathcal{L} x(t)=\sum_{i=0}^{n-1} \frac{x_{i} t^{i}}{i!}+\int_{0}^{t} \frac{(t-s)^{n-1}}{(n-1)!} x(s) \mathrm{d} s \tag{3.3}
\end{equation*}
$$

Clearly the operator $Q$ is well defined in view of hypothesis $\left(\mathrm{H}_{2}\right)$. We shall show that $Q$ satisfies all the conditions of Theorem 2.1.

Step I: First, we show that $Q$ has compact values on $[a, b]$. Observe that the operator $Q$ is equivalent to the composition $\mathcal{L} \circ S_{F}^{1}$ of two operators on $L^{1}(J, \mathbb{R})$, where $\mathcal{L}: L^{1}(J, \mathbb{R}) \rightarrow X$ is the continuous operator defined by (3.3). To show $Q$ has compact values, it then suffices to prove that the composition operator $\mathcal{L} \circ S_{F}^{1}$ has compact
values on $[a, b]$. Let $x \in[a, b]$ be arbitrary and let $\left\{v_{n}\right\}$ be a sequence in $S_{F}^{1}(x)$. Then, by the definition of $S_{F}^{1}$, $v_{n}(t) \in F(t, x(t))$ a.e. for $t \in J$. Since $F(t, x(t))$ is compact, there is a convergent subsequence of $v_{n}(t)$ (for simplicity call it $v_{n}(t)$ itself) that converges in measure to some $v(t)$, where $v(t) \in F(t, x(t))$ a.e. for $t \in J$. From the continuity of $\mathcal{L}$, it follows that $\mathcal{L} v_{n}(t) \rightarrow \mathcal{L} v(t)$ pointwise on $J$ as $n \rightarrow \infty$. In order to show that the convergence is uniform, we first show that $\left\{\mathcal{L} v_{n}\right\}$ is an equi-continuous sequence, let $t, \tau \in J$; then

$$
\begin{align*}
\left|\mathcal{L} v_{n}(t)-\mathcal{L} v_{n}(\tau)\right| \leq & \left|\sum_{i=0}^{n-1} \frac{x_{i} t^{i}}{i!}-\sum_{i=0}^{n-1} \frac{x_{i} \tau^{i}}{i!}\right| \\
& +\left|\int_{0}^{t} \frac{(t-s)^{n-1}}{(n-1)!} v_{n}(s) \mathrm{d} s-\int_{0}^{\tau} \frac{(\tau-s)^{n-1}}{(n-1)!} v_{n}(s) \mathrm{d} s\right| \\
\leq & |q(t)-q(\tau)|+\left|\int_{0}^{t} \frac{(t-s)^{n-1}}{(n-1)!} v_{n}(s) \mathrm{d} s-\int_{0}^{t} \frac{(\tau-s)^{n-1}}{(n-1)!} v_{n}(s) \mathrm{d} s\right| \\
& +\left|\int_{0}^{t} \frac{(\tau-s)^{n-1}}{(n-1)!} v_{n}(s) \mathrm{d} s-\int_{0}^{\tau} \frac{(\tau-s)^{n-1}}{(n-1)!} v_{n}(s) \mathrm{d} s\right| \\
\leq & |q(t)-q(\tau)|+\int_{0}^{t}\left|\frac{(t-s)^{n-1}}{(n-1)!}-\frac{(\tau-s)^{n-1}}{(n-1)!}\right|\left|v_{n}(s)\right| \mathrm{d} s \\
& +\left|\int_{t}^{\tau}\right| \frac{(\tau-s)^{n-1}}{(n-1)!}| | v_{n}(s)|\mathrm{d} s|  \tag{3.4}\\
\leq & |q(t)-q(\tau)|+\int_{0}^{T}\left|\frac{(t-s)^{n-1}}{(n-1)!}-\frac{(\tau-s)^{n-1}}{(n-1)!}\right|\left|v_{n}(s)\right| \mathrm{d} s \\
& +\left|\int_{t}^{\tau} \frac{T^{n-1}}{(n-1)!}\right| v_{n}(s)|\mathrm{d} s| \tag{3.5}
\end{align*}
$$

where $q(t)=\sum_{i=0}^{n-1} \frac{x_{i} t^{i}}{i!}$.
Since $v_{n} \in L^{1}(J, \mathbb{R})$, the right hand side of (3.4) tends to 0 as $t \rightarrow \tau$. Hence, $\left\{\mathcal{L} v_{n}\right\}$ is equi-continuous, and an application of the Arzelá-Ascoli theorem implies that there is a uniformly convergent subsequence. We then have $\mathcal{L} v_{n_{j}} \rightarrow \mathcal{L} v \in\left(\mathcal{L} \circ S_{F}^{1}\right)(x)$ as $j \rightarrow \infty$, and so $\left(\mathcal{L} \circ S_{F}^{1}\right)(x)$ is compact-valued. Therefore, $Q$ is a compact-valued multi-valued operator on $[a, b]$.

Step II: Secondly we show that $Q$ is right monotone increasing and maps $[a, b]$ into itself. Let $x, y \in[a, b]$ be such that $x \leq y$. Since $x \mapsto F(t, x)$ is right monotone increasing, one has $F(t, x) \stackrel{i}{\leq} F(t, y)$. As a result we have that $S_{F}^{1}(x) \stackrel{i}{\leq} S_{F}^{1}(y)$. Hence $Q(x) \stackrel{i}{\leq} Q(y)$. From $\left(\mathrm{H}_{3}\right)$ it follows that $a \leq Q a$ and $Q b \leq b$. Now $Q$ is right monotone increasing, so we have

$$
a \leq Q a \stackrel{i}{\leq} Q x \stackrel{i}{\leq} Q b \leq b
$$

for all $x \in[a, b]$. Hence $Q$ defines a multi-valued operator $Q:[a, b] \rightarrow \mathcal{P}_{c p}([a, b])$.
Step III: Finally let $\left\{x_{n}\right\}$ be a monotone increasing sequence in $[a, b]$ and let $\left\{y_{n}\right\}$ be a sequence in $Q([a, b])$ defined by $y_{n} \in Q x_{n}, n \in \mathbb{N}$. We shall show that $\left\{y_{n}\right\}$ has a cluster point. This is achieved by showing that $\left\{y_{n}\right\}$ is a uniformly bounded and equi-continuous sequence.

Case I: First we show that $\left\{y_{n}\right\}$ is a uniformly bounded sequence. By definition of $\left\{y_{n}\right\}$ there is a $v_{n} \in S_{F}^{1}\left(x_{n}\right)$ such that

$$
y_{n}(t)=\sum_{i=0}^{n-1} \frac{x_{i} t^{i}}{i!}+\int_{0}^{t} \frac{(t-s)^{n-1}}{(n-1)!} v_{n}(s) \mathrm{d} s, \quad t \in J
$$

Therefore

$$
\left|y_{n}(t)\right| \leq \sum_{i=0}^{n-1} \frac{x_{i} t^{i}}{i!}+\int_{0}^{t} \frac{(t-s)^{n-1}}{(n-1)!} v_{n}(s) \mathrm{d} s
$$

$$
\begin{aligned}
& \leq \sum_{i=0}^{n-1} \frac{x_{i} t^{i}}{i!}+\int_{0}^{t} \frac{(t-s)^{n-1}}{(n-1)!}\left\|F\left(s, x_{n}(s)\right)\right\|_{\mathcal{P}} \mathrm{d} s \\
& \leq \sum_{i=0}^{n-1} \frac{x_{i} t^{i}}{i!}+\int_{0}^{t} \frac{(t-s)^{n-1}}{(n-1)!} h_{r}(s) \mathrm{d} s \\
& \leq \sum_{i=0}^{n-1} \frac{x_{i} t^{i}}{i!}+\int_{0}^{t} \frac{T^{n-1}}{(n-1)!} h_{r}(s) \mathrm{d} s \\
& \leq \sum_{i=0}^{n-1} \frac{x_{i} T^{i}}{i!}+\frac{T^{n-1}}{(n-1)!}\left\|h_{r}\right\|_{L^{1}}
\end{aligned}
$$

for all $t \in J$, where $r=\|a\|+\|b\|$.
Taking the supremum over $t$,

$$
\left\|y_{n}\right\| \leq \sum_{i=0}^{n-1} \frac{x_{i} T^{i}}{i!}+\frac{T^{n-1}}{(n-1)!}\left\|h_{r}\right\|_{L^{1}}
$$

which shows that $\left\{y_{n}\right\}$ is a uniformly bounded sequence in $Q([a, b])$.
Next we show that $\left\{y_{n}\right\}$ is an equi-continuous sequence in $Q([a, b])$. Let $t, \tau \in J$. Then we have

$$
\begin{aligned}
\left|y_{n}(t)-y_{n}(\tau)\right| \leq & \left|\sum_{i=0}^{n-1} \frac{x_{i} t_{1}^{i}}{i!}-\sum_{i=0}^{n-1} \frac{x_{i} \tau^{i}}{i!}\right| \\
& +\left|\int_{0}^{t} \frac{(t-s)^{n-1}}{(n-1)!} v_{n}(s) \mathrm{d} s-\int_{0}^{\tau} \frac{(\tau-s)^{n-1}}{(n-1)!} v_{n}(s) \mathrm{d} s\right| \\
\leq & |q(t)-q(\tau)|+\left|\int_{0}^{t} \frac{(t-s)^{n-1}}{(n-1)!} v_{n}(s) \mathrm{d} s-\int_{0}^{t} \frac{(\tau-s)^{n-1}}{(n-1)!} v_{n}(s) \mathrm{d} s\right| \\
& +\left|\int_{0}^{t} \frac{(\tau-s)^{n-1}}{(n-1)!} v_{n}(s) \mathrm{d} s-\int_{0}^{\tau} \frac{(\tau-s)^{n-1}}{(n-1)!} v_{n}(s) \mathrm{d} s\right| \\
\leq & |q(t)-q(\tau)|+\int_{0}^{t}\left|\frac{(t-s)^{n-1}}{(n-1)!}-\frac{(\tau-s)^{n-1}}{(n-1)!}\right|\left|v_{n}(s)\right| \mathrm{d} s \\
& +\left|\int_{t}^{\tau}\right| \frac{(\tau-s)^{n-1}}{(n-1)!}| | v_{n}(s)|\mathrm{d} s| \\
\leq & |q(t)-q(\tau)|+\int_{0}^{T}\left|\frac{(t-s)^{n-1}}{(n-1)!}-\frac{(\tau-s)^{n-1}}{(n-1)!}\right| h_{r}(s) \mathrm{d} s \\
& +|p(t)-p(\tau)|
\end{aligned}
$$

where $p(t)=\frac{T^{n-1}}{(n-1)!} \int_{0}^{t} h_{r}(s) \mathrm{d} s$.
From the above inequality it follows that

$$
\left|y_{n}(t)-y_{n}(\tau)\right| \rightarrow 0 \quad \text { as } n \rightarrow \infty .
$$

This shows that $\left\{y_{n}\right\}$ is an equi-continuous sequence in $Q([a, b])$. Now $\left\{y_{n}\right\}$ is uniformly bounded and equicontinuous, so it has a cluster point in view of the Arzelá-Ascoli theorem. Now the desired conclusion follows by an application of Theorem 2.1.

To prove the next result, we need the following definitions.
Definition 3.5. A multi-function $\beta: J \times \mathbb{R} \rightarrow \mathcal{P}_{p}(\mathbb{R})$ is called $L_{X}^{1}$-Chandrabhan if
(i) $t \mapsto \beta(t, x)$ is measurable for each $x \in \mathbb{R}$,
(ii) $\beta(t, x)$ is right monotone increasing in $x$ almost everywhere for $t \in J$, and
(iii) there exists a function $h \in L^{1}(J, \mathbb{R})$ such that

$$
\|\beta(t, x)\|=\sup \{|u|: u \in \beta(t, x)\} \leq h(t) \text { a.e. } t \in J
$$

for all $x \in \mathbb{R}$.
Remark 3.1. Note that if the multi-function $\beta(t, x)$ is $L_{X}^{1}$-Chandrabhan, then it is measurable in $t$ and integrally bounded on $J \times \mathbb{R} \times \mathbb{R}$, and so, by a selection theorem, $S_{\beta}^{1}$ has non-empty values, that is,

$$
S_{\beta}^{1}(x)=\left\{u \in L^{1}(J, \mathbb{R}) \mid u(t) \in \beta(t, x) \text { a.e. } t \in J\right\} \neq \emptyset
$$

for all $x \in \mathbb{R}$. See Deimling [4] and the references therein.
Theorem 3.2. Assume that $\left(\mathrm{H}_{1}\right)$ and
$\left(\mathrm{H}_{5}\right) F$ is $L_{X}^{1}$-Chandrabhan
hold. Then the DI (1.1) has a solution on $J$.
Proof. Obviously the hypotheses $\left(\mathrm{H}_{2}\right)$ and $\left(\mathrm{H}_{3}\right)$ of Theorem 3.1 hold in view of Remark 3.1. Define two functions $a, b: J \rightarrow \mathbb{R}$ by

$$
a(t)=\sum_{i=0}^{n-1} \frac{x_{i} t^{i}}{i!}-\int_{0}^{t} \frac{(t-s)^{n-1}}{(n-1)!} h(s) \mathrm{d} s,
$$

and

$$
b(t)=\sum_{i=0}^{n-1} \frac{x_{i} t^{i}}{i!}+\int_{0}^{t} \frac{(t-s)^{n-1}}{(n-1)!} h(s) \mathrm{d} s .
$$

It is easy to verify that $a$ and $b$ are respectively the strictly lower and upper solutions of the DI (1.1) on $J$ with $a \leq b$. Thus $\left(\mathrm{H}_{4}\right)$ holds and now the desired conclusion follows by an application of Theorem 3.1.

Example 3.3. Let $J=[0,1]$ and define a multi-function $F: J \times \mathbb{R} \rightarrow \mathbb{R}$ by

$$
F(t, x)=\left\{\begin{array}{l}
\{0\} \text { if } x<0,  \tag{3.6}\\
{[0, p(t)[x]] \text { if } x \in[0,2]} \\
\{3\} \text { if } x>2,
\end{array}\right.
$$

for all $t \in J$, where $p \in L^{1}\left(J, \mathbb{R}^{+}\right)$and $[x]$ is a greatest integer not greater than $x$. Now consider the DI

$$
\left.\begin{array}{l}
x^{(n)}(t) \in F(t, x(t)) \text { a.e. } t \in J  \tag{3.7}\\
x^{(i)}(0)=\frac{1}{1+i} \in \mathbb{R}, i \in\{0,1, \ldots, n-1\}
\end{array}\right\} .
$$

Clearly the multi-function $F$ satisfies all the hypotheses of Theorem 3.1 with

$$
a(t)=\sum_{i=0}^{n-1} \frac{t^{i}}{i!(1+i)} \quad \text { and } \quad b(t)=\sum_{i=0}^{n-1} \frac{t^{i}}{i!(1+i)}+3 \frac{T^{n}}{(n-1)!}
$$

for $t \in J$.

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