# Covariance Adjustments in Discrimination of Mixed Discrete and Continuous Variables 

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#### Abstract

Sufficient conditions are given to ensure a better performance of the plug-in version of the covariates adjusted location linear discriminant function in an asymptotic comparison of the overall expected error rate. Our findings generalize several earlier results on discriminant function with covariance. © 1999 Academic Press AMS 1991 subject classifications: $62 \mathrm{H} 10,62 \mathrm{H} 30$. Key words and phrases: plug-in location linear discriminant function; covariance adjustment; asymptotic expansion; overall expected error rate.


## 1. INTRODUCTION

Treatment of covariates or concomitant variables arises in many statistical investigations. In classification, covariates are often handled by using the residual vector of regression of the discriminators on the covariates in the discriminant function. See Cochran and Bliss [3]. Without much analytic investigation, Cochran [2] claims that the discriminators subject to the suggested treatment generally improve the performance of the discriminant function since internal correlations have been incorporated in the procedure. Memon and Okamoto [8] re-examines the same problem and reaches similar conclusions. In Memon and Okamoto [8], only continuous discriminators are considered in a two-population problem under homogeneous dispersion matrices for both populations with a zero threshold. Their conclusion draws criticism since the argument is based on an asymptotic expansion in Okamoto [9] which is invalid for a nonzero threshold with unknown Mahalanobis distance.

In this article, we consider a similar problem with mixed discrete and continuous variables. Classification of mixed discrete and continuous variables is prevalent in many situations. See Daudin [4], Krzanowski [5], and Vlachonikolis and Marriott [13] for instance. Specifically, we consider discrimination between two populations say, $\Pi_{1}$ and $\Pi_{2}$ with mixed covariates amongst the discrete and continuous variables. Under conditional homogeneity of discrete values specific dispersion matrices for
both populations, an asymptotic overall expected error rate for the plug-in covariates adjusted discriminant function is derived. The result is compared to the corresponding error rate for the discriminant function without the adjustments. Sufficient conditions are obtained in support of the covariates adjusted discriminant function. Explicit statements are given in two special cases. One of our results generalizes Memon and Okamoto [8] and provides further theoretical justification of Cochran [2].

## 2. THE PROCEDURE

Existing procedures for classification between two populations say $\Pi_{1}$ and $\Pi_{2}$ using mixed discrete and continuous variables are based on the location probability model of Olkin and Tate [10]. To simplify the discussion, we adopt the formulation in Krzanowski [5]. Suppose that a vector measurement $u^{\prime}=\left(y^{\prime}, z^{\prime}\right)$ is observed on an individual where $z^{\prime}=\left(z_{1}, \ldots, z_{r}\right)$ is a multinomial variable with $r$ discrete states and $y^{\prime}=\left(y_{1}, \ldots, y_{p+q}\right)$ is a vector of $p+q$ continuous variables. The vector $z$ has only one nonzero entry equal to one which is the incidence for the corresponding state.

The continuous variables consist of $p$ discriminators and $q$ covariates. To simplify the discussion, suppose that the first $p$ variables are the discriminators while the remaining $q$ variables are covariates. Partition $y^{\prime}=\left(y^{(1)^{\prime}}, y^{(2)^{\prime}}\right)$; where $y^{(1)^{\prime}}=\left(y_{1}, \ldots, y_{p}\right) ; y^{(2)^{\prime}}=\left(y_{p+1}, \ldots, y_{p+q}\right)$. Similarly, let $z^{\prime}=\left(z^{(1)^{\prime}}, z^{(2)^{\prime}}\right)$; where $z^{(1)^{\prime}}=\left(z_{1}, \ldots, z_{r_{1}}\right)$ consists of $r_{1}$ discrete discriminators and $z^{(2)^{\prime}}=\left(z_{r_{1}+1}, \ldots, z_{r}\right)$ denotes the discrete covariates $\left(0<r_{1} \leqslant r\right)$. Furthermore, it is assumed that for $i=1,2, Z \mid \Pi_{i} \sim \operatorname{Multinomial}\left(1, p_{i}^{(1)}, p^{(2)}\right)$; $p_{i}^{(1)^{\prime}}=\left(p_{1 i}, \ldots, p_{r_{1} i}\right) ; \quad p^{(2)}=\left(p_{r_{1}+1}, \ldots, p_{r}\right) ; \sum_{m=1}^{r_{1}} p_{m i}+\sum_{l=r_{1}+1}^{r} p_{l}=1 \quad$ and for $i=1,2 ; m=1, \ldots, r ; Y \mid Z_{m}=1, \Pi_{i} \sim N_{p+q}\left(v_{m i}, \Sigma^{(m)}\right)$ where $v_{m i}$ is a $p+q$ vector with the first $p$ entries forming a $p$ vector equal to $\mu_{m i}=E\left(Y^{(1)} \mid Z_{m}=1, \Pi_{i}\right)$ and the last $q$ entries forming a $q$ vector equal to $\lambda_{m}=E\left(Y^{(2)} \mid Z_{m}=1, \Pi_{i}\right)$.

Let $\Sigma^{(m)}$ be partitioned as

$$
\Sigma^{(m)}=\left[\begin{array}{ll}
\Sigma_{11}^{(m)} & \Sigma_{12}^{(m)} \\
\Sigma_{21}^{(m)} & \Sigma_{21}^{(m)}
\end{array}\right]
$$

and $\beta_{m}=\Sigma_{12}^{(m)} \Sigma_{22}^{(m)^{-1}}$; where $\Sigma_{i j}^{(m)}=\operatorname{Cov}\left(Y^{(i)}, Y^{(j)}\right), i, j=1,2 ; m=1, \ldots, r$. Notice that the role of $Z^{(2)}$ assumes that for $i=1,2 ; E\left(Z^{(2)} \mid \Pi_{i}\right)=p^{(2)}$ is known. Similarly, the role of $Y^{(2)}$ assumes that the state specific mean $\lambda_{m}$ common to both $\Pi_{1}$ and $\Pi_{2}$ in state $m, m=r_{1}+1, \ldots, r$ is known.

To briefly state the problem, let $\lambda_{m}=0$ for $m=1, \ldots, r$ in the sequel. With complete knowledge of the parameters, the Bayes rule is given by the location linear discriminant function. Specifically, for an object with
measurement $\left(Y^{\prime}, Z^{\prime}\right)^{\prime}$ with $Z_{m}=1, m=1, \ldots, r$, the rule with threshold $t \in(-\infty, \infty)$ assigns the object to $\Pi_{1}$ if and only if $U_{m}>t$, where

$$
U_{m}= \begin{cases}D_{m}-\log \left(p_{m 2} / p_{m 1}\right), & \text { for } m=1, \ldots, r_{1} \\ D_{m}, & \text { for } m=r_{1}+1, \ldots, r\end{cases}
$$

with $D_{m}=\left[Y^{(1)}-\beta_{m} Y^{(2)}-\frac{1}{2}\left(\mu_{m 1}+\mu_{m 2}\right)\right]^{\prime} \Sigma_{1.2}^{(m)^{-1}}\left(\mu_{m 1}-\mu_{m 2}\right)$ and $\Sigma_{1.2}^{(m)}=$ $\Sigma_{11}^{(m)}-\beta_{m} \Sigma_{22}^{(m)} \beta_{m}^{\prime}$. Notice that $D_{m}$ is the Fisher linear discriminant function adjusted for the continuous covariates $Y^{(2)}$ for state $m, m=1, \ldots, r$ when all the parameters are known. See Memon and Okamoto [8].

The threshold $t=0$ is a common choice and $\Sigma^{(1)}=\cdots=\Sigma^{(r)}$ is usually assumed. See Krzanowski [5]. In practice, an approximate sample based rule rather than the Bayes rule is used due to lack of knowledge of the parameters. Suppose that random training samples of sizes $n_{1}$ and $n_{2}$ respectively from $\Pi_{1}$ and $\Pi_{2}$ are available. Let $n_{m i}$ observations from $\Pi_{i}$ fall in state m, with $Y_{m j i}^{\prime}=\left(Y_{m j i}^{(1)^{\prime}}, Y_{m j i}^{(2)}\right)$ denoting continuous measurements on the jth sample in state m from $\Pi_{i}, j=1, \ldots, n_{m i} ; m=1, \ldots, r ; i=1,2$. Let $n(m)=n_{m 1}+n_{m 2}-2, m=1, \ldots, r$. Unbiased continuous covariates adjusted estimates specific to state m are

$$
\begin{aligned}
\hat{\beta}_{m} & =S_{12}^{(m)} S_{22}^{(m)^{-1}} ; \\
\hat{\Sigma}_{1.2}^{(m)} & =(n(m)-q)^{-1}\left(S_{11}^{(m)}-S_{12}^{(m)} S_{22}^{(m)^{-1}} S_{21}^{(m)}\right) ; \quad \hat{\mu}_{m i}=\bar{Y}_{m i}^{(1)}-\hat{\beta}_{m} \bar{Y}_{m i}^{(2)},
\end{aligned}
$$

where

$$
\bar{Y}_{m i}^{\prime}=\left(\bar{Y}_{m i}^{(1)^{\prime}} ; \bar{Y}_{m i}^{\left.(2)^{\prime}\right)}\right) ; \quad \bar{Y}_{m i}^{(v)}=n_{m i}^{-1} \sum_{j=1}^{n_{m i}} Y_{m i}^{(v)} ; \quad v=1,2 ; \quad m=1, \ldots, r,
$$

and

$$
\sum_{i=1}^{2} \sum_{j=1}^{n_{m i}}\left(Y_{m j i}-\bar{Y}_{m i}\right)\left(Y_{m j i}-\bar{Y}_{m i}\right)^{\prime}=\mathrm{S}^{(m)}=\left[\begin{array}{cc}
S_{11}^{(m)} & S_{12}^{(m)} \\
S_{21}^{(m)} & S_{22}^{(m)}
\end{array}\right]
$$

is similarly partitioned as $\Sigma^{(m)}$ for $m=1, \ldots, r$.
From Kshirsagar [6, p. 20, Eq. (4.12)],

$$
\begin{aligned}
& E\left(n_{m i} \mid \Pi_{i}, n_{r_{1}+1 i}, \ldots, n_{r i}\right) \\
& \quad=\left(n_{i}-n_{r_{1}+1}-\cdots-n_{r i}\right) p_{m i}\left(1-p_{r_{1}+1}-\cdots-p_{r}\right)^{-1} .
\end{aligned}
$$

Unbiased estimates of the state probabilities are obtained by adjusting the known state probabilities in the last $r-r_{1}$ multinomial cells for each of the two discrete samples and are as follows: $\hat{p}_{m i}=\tilde{p}_{m i}\left(1-p_{r_{1}+1}-\cdots-p_{r}\right)$ $\times\left(1-\tilde{p}_{r_{1}+1}^{(i)}-\cdots-\tilde{p}_{r}^{(i)}\right)^{-1}$; where $\tilde{p}_{m i}$ and $\tilde{p}_{l}^{(i)}$ are the sample proportions
of the $m$ th and $l$ th multinomial cells from the $i$ th sample for $m=1, \ldots, r_{1}$; $l=r_{1}+1, \ldots, r$ and $i=1,2$. A popular sample based approximation to $U_{m}$ is the plug-in version of $U_{m}$ using above estimates due to its simplicity. In the next section, an asymptotic expansion of the overall expected error rate of the plug-in rule is given. The expansion provides an index of the long term performance of the procedure.

## 3. THE EXPECTED ERROR RATE

For $-\infty<t<\infty$, given $Z_{m}=1, m=1, \ldots, r ; i=1,2$, the probability of misclassification is $e_{i m}(t)=\operatorname{Pr}\left\{(-1)^{i} \hat{U}_{m}>(-1)^{i} t \mid \Pi_{\mathrm{i}}\right\}$. With equal prior for $\Pi_{1}$ and $\Pi_{2}$, the overall expected error rate is given by $\bar{e}(t)=$ $\frac{1}{2} \sum_{i=1}^{2} \sum_{m=1}^{r} p_{m i} e_{i m}(t)$ which admits an asymptotic expansion given below. Details of the derivation are given in the appendix. To facilitate the derivation, the following results are needed.

Lemma 3.1. Under the formulation in section 2, with $\Sigma^{(1)}=\cdots=\Sigma^{(r)}=$ $I_{p+q}, a(p+q) \times(p+q)$ identity matrix, if $Z_{m}=1, \mu_{m 1}=0, \mu_{m 2}=-\delta_{m}$, $\delta_{m}^{\prime}=\left(\Delta_{m}, \ldots, 0\right), \quad 0<\Delta_{m}=\left[\left(\mu_{m 1}-\mu_{m 2}\right)^{\prime} \Sigma_{1.2}^{(m)^{-1}}\left(\mu_{m 1}-\mu_{m 2}\right)\right]^{1 / 2}$, then for given $n_{m 1}$ and $n_{m 2}, m=1, \ldots, r$, the following hold.
(i) $E_{2 m}\left(\hat{\mu}_{m 1}\right)=0$;
(ii) $E_{2 m}\left(\hat{\mu}_{m 1}-\hat{\mu}_{m 2}\right)=\delta_{m}$;
(iii) $E_{2 m}\left(\hat{\beta}_{m}\right)=0$;
(iv) $E_{2 m}\left(\hat{\beta}_{m} \hat{\beta}_{m}^{\prime}\right)=b_{m} I_{p}, b_{m}=q(n(m)-q-1)^{-1}$;
(v) $E_{2 m}\left(\Sigma_{1.2}^{(m)}\right)=I_{p}$;
(vi) $E_{2 m}\left(\hat{\mu}_{m 1} \hat{\mu}_{m 1}^{\prime}\right)=n_{m 1}^{-1}\left(1+b_{m}\right) I_{p}$;
(vii) $\quad E_{2 m}\left(\left(\hat{\mu}_{m 1}-\hat{\mu}_{m 2}-\delta_{m}\right)\left(\hat{\mu}_{m 1}-\hat{\mu}_{m 2}-\delta_{m}\right)^{\prime}\right)=\left(n_{m 1}^{-1}+n_{m 2}^{-1}\right)\left(1+b_{m}\right) I_{p}$;
(viii) $\left.E_{2 m}\left(\left(\hat{\mu}_{m 1}-\hat{\mu}_{m 2}-\delta_{m}\right) \hat{\mu}_{m 1}^{\prime}\right)\right)=n_{m 1}^{-1}\left(1+b_{m}\right) I_{p}$;
(ix) $E_{2 m}\left(\delta_{m}^{\prime}\left(\Sigma_{1.2}^{(m)}-I_{p}\right) \delta_{m}\right)=(n(m))^{-1}(p+1) \Delta_{m}^{2}$;
(x) $\quad E_{2 m}\left(\left(\delta_{m}^{\prime}\left(\Sigma_{1.2}^{(m)}-I_{p}\right) \delta_{m}\right)^{2}\right)=2(n(m))^{-1} \Delta_{m}^{4}$;
(xi) $\quad E_{2 m}\left(\left(\delta_{m}^{\prime}\left(\hat{\beta}_{m} \hat{\beta}_{m}^{\prime}-b_{m} I_{p}\right) \delta_{m}\right)^{2}\right)=2 d_{m} \Delta_{m}^{4}, \quad d_{m}=q[(n(m)-1)(n(m)$ $\left.-q)^{-1}(n(m)-q-1)^{-1}(n(m)-q-3)^{-1}+(n(m)-2)^{-2}(n(m)-4)^{-1}\right]$.

Proof. Part (i) follows from the fact that given $n_{m 1}$ and $n_{m 2}$ and $Z_{m}=1$, $\bar{Y}_{m i}$ and $\hat{\Sigma}^{(m)}$ are independently distributed with $S_{11}^{(m)}-S_{12}^{(m)} S_{22}^{(m)^{-1}} S_{21}^{(m)} \sim$ $W_{p}\left(I_{p}, n(m)-q\right), \hat{\beta}_{m} \mid S_{22}^{(m)} \sim N_{p, q}\left(0, I_{p}, S_{22}^{(m)}\right)$ and $S_{22}^{(m)} \sim W_{q}\left(I_{p}, n(m)\right)$.

Part (ii) follows similarly as Part (i).

Part (iii) follows from $E_{2 m}\left(\hat{\beta}_{m}\right)=E_{2 m}\left(E_{2 m, \mathrm{~s}_{22}^{(m)}}\left(\hat{\beta}_{m} \mid S_{22}^{(m)}\right)\right)$, where $E_{2 m,} \mathrm{~s}_{22}^{(m)}($. denotes the conditional expectation with respect to $S_{22}^{(m)}$ for given $n_{m 1}, n_{m 2}$.

Part (iv) follows since given $S_{22}^{(m)}$, the rows of $\hat{\beta}_{m}$ are independent and identically distributed as $N_{q}\left(0, S_{22}^{(m)^{-1}}\right)$ with $E_{2 m}\left(S_{22}^{(m)^{-1}}\right)=(n(m)-q-1)^{-1} I_{p}$. Part (v) follows from the Wishart distribution of $S_{11}^{(m)}-S_{12}^{(m)} S_{22}^{(m)^{-1}} S_{21}^{(m)}$.
Part (vi) follows from $E_{2 m}\left(\hat{\mu}_{m 1} \hat{\mu}_{m 1}^{\prime}\right)=n_{m 1}^{-1} E_{2 m}\left(\left[I_{p}+\hat{\beta}_{m} \hat{\beta}_{m}^{\prime}\right]\right)$.
Parts (vii) and (viii) follow similarly.
Parts (ix) and (x) follow from Anderson [1], Eq. (26) and Eq. (27), p. 969 respectively.

Part (xi) follows from $E_{2 m}\left(\left(\delta_{m}^{\prime}\left(\hat{\beta}_{m} \hat{\beta}_{m}^{\prime}-b_{m} I_{p}\right) \delta_{m}\right)^{2}\right)=E_{1} V_{2}+V_{1} E_{2}$, where $E_{2}$ and $V_{2}$ denote respectively the conditional expectation and variance given $S_{22}^{(m)}$ and $E_{1}$ and $V_{1}$ stand for the expectation and variance with respect to the distribution of $S_{22}^{(m)}$. Using $\hat{\beta}_{m} \delta_{m} \mid S_{22}^{(m)} \sim$ $N_{q}\left(0, \Delta_{m}^{2} S_{22}^{\left.(m)^{-1}\right)}\right.$ ) and Searle [11, Theorem 1, p. 55], $V_{1} E_{2}=2 \Delta_{m}^{4} q(n(m)-2)^{-2}$ $(n(m)-4)^{-1}$. By Searle [11, Corollary 1.2, p. 57] and Srivastava and Khatri [12, problem 3.2(iv) p. 97], $E_{1} V_{2}=2 \Delta_{m}^{4} q(n(m)-1)(n(m)-q)^{-1}$ $(n(m)-q-1)^{-1}(n(m)-q-3)^{-1}$.

Lemma 3.2. Under the assumptions in Section 2, given $Z_{m}=1$,
(i) $\quad E_{1 m}\left(\tilde{p}_{m i}\right)=p_{m i} ; m=1, \ldots, r_{1} ; i=1,2$;
(ii) $\quad E_{1 m}\left(\left(\tilde{p}_{m i}-\tilde{p}_{m i}\right)^{2}\right)=n_{i}^{-1} p_{m i}\left(1-p_{m i}\right) ; m=1, \ldots, r_{1} ; i=1,2$;
(iii) $\quad E_{1 m}\left(\left(\tilde{p}_{l}^{(i)}-p_{l}\right)\left(\tilde{p}_{l^{\prime}}^{(j)}-p_{l^{\prime}}\right)\right)=0 ; l, l^{\prime}=r_{1}+1, \ldots, r ; i \neq j=1,2$;
(iv) $\quad E_{1 m}\left(\left(\tilde{p}_{l}^{(i)}-p_{l}\right)^{2}\right)=n_{i}^{-1} p_{l}\left(1-p_{l}\right) ; l=r_{1}+1, \ldots, r ; i=1,2$;
(v) $E_{1 m}\left(\left(\tilde{p}_{l}^{(i)}-p_{l}\right)\left(\tilde{p}_{l^{\prime}}^{(i)}-p_{l^{\prime}}\right)\right)=-n_{i}^{-1} p_{l} p_{l^{\prime}} ; l \neq l^{\prime}=r_{1}+1, \ldots, r ; i=1,2$;
(vi) $\quad E_{1 m}\left(\left(\tilde{p}_{m i}-p_{m i}\right)\left(\tilde{p}_{l}^{(i)}-p_{l}\right)\right)=-n_{i}^{-1} p_{m i} p_{l} ; m=1, \ldots, r_{1} ; l=r_{1}+1$, $\ldots, r ; i=1,2$.
(vii) $\quad E_{1 m}\left(\left(\tilde{p}_{m i}-p_{m i}\right)\left(\tilde{p}_{l}^{(j)}-p_{l}\right)\right)=0, m=1, \ldots, r_{1} ; i \neq j=1,2$.

Proof. This is obvious.

Lemma 3.3. For the two random training samples, suppose that the following conditions are satisfied.
(C1) $n_{m 2} n_{m 1}^{-1}$ converges in probability to $k_{m}>0, m=1, \ldots, r$ as $n_{1}$ and $n_{2}$ tend to infinity.
(C2) $n_{s 1} n_{m 1}^{-1}$ converges in probability to $k_{s, m}>0, s, m=1, \ldots, r$ as $n_{1}$ and $n_{2}$ tend to infinity. Then given $Z_{m}=1, E_{1 m}\left(\Phi\left(\Delta_{m}^{-1}\left[t+\log \left(\hat{p}_{m 2} / \hat{p}_{m 1}\right)-\right.\right.\right.$ $\left.\left.\left.\Delta_{m}^{2} / 2\right]\right)\right)=\Phi\left(\eta_{1 m t}\right)+n^{-1} \Delta_{m}^{-1} \phi\left(\eta_{1 m t}\right) \zeta\left(p_{m 1}, p_{m 2}\right)+O\left(n^{-2}\right)$; where

$$
\begin{aligned}
\zeta\left(p_{m 1}, p_{m 2}\right)= & \left\{n n_{1}^{-1} p_{m 1}^{-1}\left(1-p_{m 1}\right)+n n_{2}^{-1} \bar{p}(1-\bar{p})^{-1}\right\} \\
& \times\left\{\frac{3}{4}-\Delta_{m}^{-2} / 2\left[t+\log \left(p_{m 2} / p_{m 1}\right]\right\}\right. \\
& -\left\{n n_{2}^{-1} p_{m 2}^{-1}\left(1-p_{m 2}\right)+n n_{1}^{-1} \bar{p}(1-\bar{p})^{-1}\right\} \\
& \times\left\{\frac{1}{4}+\Delta_{m}^{-2} / 2\left[t+\log \left(p_{m 2} / p_{m 1}\right]\right\}\right. \\
& -n\left(n_{1}^{-1}+n_{2}^{-1}\right) \bar{p}(1-\bar{p})^{-1} \\
& \times\left\{\frac{1}{4}-\Delta_{m}^{-2} / 2\left[t+\log \left(p_{m 2} / p_{m 1}\right)\right]\right\}
\end{aligned}
$$

with $\bar{p}=\sum_{l=r_{1}+1}^{r} p_{l}$.
Proof. Given $Z_{m}=1, m=1, \ldots, r_{1}$, the result follows from a Taylor series expansion of $\Phi\left(\Delta_{m}^{-1}\left[t+\log \left(\hat{p}_{m 2} / \hat{p}_{m 1}\right)-\Delta_{m}^{-2} / 2\right]\right)$ about $\tilde{p}_{m i}=p_{m i}$, $\tilde{p}_{l}^{(i)}=p_{l}, l=r_{1}+1, \ldots, r ; i=1,2$. Under (C1) and (C2), the remainder term has order $O\left(n^{-2}\right)$. The result follows from Lemma 3.2.

Remark 3.1. It should be pointed out that Lemma 3.1 and Lemma 3.2 ensure that the expansions in the following theorem have the indicated order of approximation.

Theorem 3.1 (Main Result). Suppose that (C1) and (C2) in Lemma 3.3 are satisfied. Let $n=n_{1}+n_{2}-2 r$. Then
(a) $n(n(m))^{-1}$ converges in probability to $1+k_{m}^{*} \geqslant 0$ as both $n_{1}$ and $n_{2}$ tend to infinity and $\lim _{n_{1}, n_{2} \rightarrow \infty} n_{2} n_{1}^{-1}=k>0$.
(b) for $t \in(-\infty, \infty)$ and given $Z_{m}=1, m=1, \ldots, r_{1}$,

$$
\begin{equation*}
e_{1 m}(t)=\Phi\left(\eta_{1 m t}\right)+n^{-1} \phi\left(\eta_{1 m t}\right)\left(\alpha_{1 m t}+\tau_{1 m t}+\gamma_{1 m t}\right)+O\left(n^{-2}\right) ; \tag{3.1}
\end{equation*}
$$

and for $m^{\prime}=r_{1}+1, \ldots, r$,

$$
\begin{equation*}
e_{1 m^{\prime}}(t)=\Phi\left(\eta_{1 m^{\prime} t}^{*}\right)+n^{-1} \phi\left(\eta_{1 m^{\prime} t}^{*}\right)\left(\tau_{1 m^{\prime} t}^{*}+\gamma_{1 m^{\prime} t}^{*}\right)+O\left(n^{-2}\right) ; \tag{3.2}
\end{equation*}
$$

where

$$
\begin{aligned}
\eta_{1 m t}= & \Delta_{m}^{-1}\left[t+\log \left(p_{m 2} / p_{m 1}\right)-\Delta_{m}^{2} / 2\right] ; \\
\alpha_{1 m t}= & \Delta_{m}^{-1}\left\{(1+k) p_{m 1}^{-1}\left(1-p_{m 1}\right)+\left(1+k^{-1}\right) \bar{p}(1-\bar{p})^{-1}\right\} \\
& \times\left\{\frac{3}{4}-\Delta_{m}^{-2} / 2\left[t+\log \left(p_{m 2} / p_{m 1}\right]\right\}-\Delta_{m}^{-1}\left\{\left(1+k^{-1}\right) p_{m 2}^{-1}\left(1-p_{m 2}\right)\right.\right. \\
& \left.+(1+k) \bar{p}(1-\bar{p}))^{-1}\right\}\left\{\frac{1}{4}+\Delta_{m}^{-2} / 2\left[t+\log \left(p_{m 2} / p_{m 1}\right)\right]\right\} \\
& -\Delta_{m}^{-1}\left(2+k+k^{-1}\right) \bar{p}(1-\bar{p})^{-1}\left\{\frac{1}{4}-\Delta_{m}^{-2} / 2\left[t+\log \left(p_{m 2} / p_{m 1}\right)\right]\right\} ;
\end{aligned}
$$

$$
\begin{aligned}
\bar{p} & =\sum_{l=r_{1}+1}^{r} p_{l} ; \\
\tau_{1 m t} & =-\frac{1}{2} q\left(1+k_{m}^{*}\right) \Delta_{m}^{-1}\left[t+\log \left(p_{m 2} / p_{m 1}\right)-\Delta_{m}^{2} / 2\right] ;
\end{aligned}
$$

and

$$
\begin{aligned}
\gamma_{1 m t}= & \frac{1}{4}(p-1)\left(1+k_{m}^{*}\right) \Delta_{m}+\frac{1}{4}(p-1) \Delta_{m}^{-1} \\
& \times\left\{3(1+k) p_{m 1}^{-1}-\left(1+k^{-1}\right) p_{m 2}^{-1}\right\}-\left[t+\log \left(p_{m 2} / p_{m 1}\right)\right] \\
& \times\left\{\frac{3}{2}(p-1)\left(1+k_{m}^{*}\right) \Delta_{m}^{-1}+\frac{1}{2}(p-3) \Delta_{m}^{-3}\left[(1+k) p_{m 1}^{-1}\right.\right. \\
& \left.\left.+\left(1+k^{-1}\right) p_{m 2}^{-1}\right]\right\}-\Delta_{m}^{-1} / 2\left[t+\log \left(p_{m 2} / p_{m 1}\right)-\Delta_{m}^{2} / 2\right] \\
& \times\left\{\frac{1}{4}\left[(1+k) p_{m 1}^{-1}+\left(1+k^{-1}\right) p_{m 2}^{-1}\right]+\Delta_{m}^{-2}\left[t+\log \left(p_{m 2} / p_{m 1}\right)\right]\right. \\
& \times\left[\left(1+k^{-1}\right) p_{m 2}^{-1}-(1+k) p_{m 1}^{-1}\right]+\Delta_{m}^{-4}\left[t+\log \left(p_{m 2} / p_{m 1}\right)\right]^{2} \\
& \left.\times\left[(1+k) p_{m 1}^{-1}+\left(1+k^{-1}\right) p_{m 2}^{-1}+2\left(1+k_{m}^{*}\right) \Delta_{m}^{2}\right]\right\} .
\end{aligned}
$$

$\eta_{1 m^{\prime} t}^{*}, \tau_{1 m^{\prime} t}^{*}$, and $\gamma_{1 m^{\prime} t}^{*}$ are obtained by putting $p_{m 1}=p_{m 2}=p_{m^{\prime}}$ in $\eta_{1 m t}, \tau_{1 m t}$, and $\gamma_{1 m t}$ respectively in (3.1) for $m^{\prime}=r_{1}+1, \ldots, r$.

In Eq. (3.1) and Eq.(3.2), $\Phi($.$) and \phi($.$) denote respectively the standard$ normal distribution function and the density function.

Proof. The proof is given in the appendix.

Corollary 3.1. For $m=1, \ldots, r_{1}, e_{2 m}(t)$ is obtained by interchanging $m_{1}$ and $m_{2}, k$ and $k^{-1}$ and substituting $-t$ for $t$ throughout Eq.(3.1). For $m^{\prime}=r_{1}+1, \ldots, r, e_{2 m^{\prime}}(t)$ is similarly obtained from Eq. (3.2).

Proof. The result follows from the fact that interchanging $m_{1}$ and $m_{2}$ in $\hat{U}_{m}$ changes $\hat{U}_{m}$ to $-\hat{U}_{m}$.

## 4. ASYMPTOTIC COMPARISON

To investigate the effect of covariate adjustments due to both discrete and continuous variables, we need a similar expression for the overall
expected error rate say $\bar{e}^{\prime}(t)$, where $\bar{e}^{\prime}(t)=\frac{1}{2} \sum_{i=1}^{2}\left(\sum_{m=1}^{r_{1}} p_{m i} e_{i m}^{\prime}(t)+\right.$ $\sum_{m^{\prime}=1}^{r} p_{m^{\prime}} e_{i m^{\prime}}^{\prime}(t)$ ); and for $i=1,2 ; m=1, \ldots, r ; e_{i m}^{\prime}(t)$ is the probability of misclassification when all covariates are considered as discriminators. It follows from Leung [8] that $e_{i m}^{\prime}(t)$ can be obtained by dropping $\tau_{i m t}$, setting $\bar{p}=0$ in $\alpha_{1 m t}$ and replacing $p$ by $p+q$ throughout $\gamma_{1 m t}$ for $m=1, \ldots, r_{1}$ in Eq. (3.1). For $m^{\prime}=r_{1}+1, \ldots, r, e_{1 m^{\prime}}(t)$ can be similarly obtained from $e_{1 m}(t)$ using Eq. (3.2) and deleting $\tau_{1 m t}^{*}, m=1, \ldots, r$. For $m=1, \ldots, r, e_{2 m}^{\prime}(t)$ can be obtained similarly from Corollary 3.1.

Combining the above results, we have an asymptotic expression for the difference $\bar{e}^{\prime}(t)-\bar{e}(t)$ which can be used to assess the effect of covariate adjustments in the plug-in location linear discriminant function. We highlight the assessment in two interesting cases where concrete conclusions can be drawn. The first case is the classical problem of Cochran and Bliss [3]. The second case examines the roles played by discrete covariates in mixed variables discrimination. The results are stated in the following corollaries.

Remark 4.1. It is of practical importance to retain all variables including covariates in classification. Covariates not only provide information on their own but also carry useful correlations to be used in classification. Omitting the covariates amounts to throwing away essential information.

Corolary 4.1. Under the assumptions in Theorem 3.1, for $t=0, r=1$, $p_{11}=p_{12}=1$ and $\Delta_{1}=\Delta>0$,

$$
\bar{e}^{\prime}(0)-\bar{e}(0)=\left[\frac{q n^{-1} \Delta^{-1}\left(3 k^{-1}-k+2\right)}{4}\right] \phi\left(-\frac{\Delta}{2}\right)+O\left(n^{-2}\right) .
$$

Corollary 4.2. For $k=1, \quad \bar{e}^{\prime}(0)-\bar{e}(0)>0 \quad u p \quad$ to the order of approximation in Corollary 4.1.

Remark 4.2. Above result justifies the claim in Cochran [2]. The same conclusion is reached in Memon and Okamoto [8] via efficiency consideration.

Corollary 4.3. Under the assumptions in Theorem 3.1, for $q=0$,

$$
\begin{aligned}
\bar{e}^{\prime}(t)-\bar{e}(t)= & {\left[\frac{n^{-1} \bar{p}(1-\bar{p})^{-1}\left(k-k^{-1}\right)}{4}\right] } \\
& \times\left[\sum_{m=1}^{r_{1}} \Delta_{m}^{-1}\left(p_{m 1} \phi\left(\eta_{1 m t}\right)-p_{m 2} \phi\left(\eta_{2 m t}\right)\right)\right]+O\left(n^{-2}\right)
\end{aligned}
$$

Proof. Observe that

$$
\begin{aligned}
\bar{e}^{\prime}(t)-\bar{e}(t)= & \frac{1}{2} \sum_{i=1}^{2}\left(\sum_{m=1}^{r_{1}} p_{m i}\left[e_{i m}^{\prime}(t)-e_{i m}(t)\right]\right. \\
& \left.+\sum_{m^{\prime}=r_{1}+1}^{r} p_{m^{\prime}}\left[e_{i m^{\prime}}^{\prime}(t)-e_{i m^{\prime}}(t)\right]\right) .
\end{aligned}
$$

From Theorem 3.1 and the arguments before Corollary 4.1, for $q=0$ and $m=1, \ldots, r_{1}$,

$$
e_{1 m}^{\prime}(t)-e_{1 m}(t)=\frac{1}{2}\left[n^{-1} \bar{p}(1-\bar{p})^{-1}\left(k-k^{-1}\right)\right] \Delta_{m}^{-1} \phi\left(\eta_{1 m t}\right)+O\left(n^{-2}\right)
$$

and

$$
e_{2 m}^{\prime}(t)-e_{2 m}(t)=\frac{1}{2}\left[n^{-1} \bar{p}(1-\bar{p})^{-1}\left(k^{-1}-k\right)\right] \Delta_{m}^{-1} \phi\left(\eta_{2 m t}\right)+O\left(n^{-2}\right) ;
$$

and for $m^{\prime}=r_{1}+1, \ldots, r$,

$$
e_{1 m^{\prime}}^{\prime}(t)-e_{1 m^{\prime}}(t)=O\left(n^{-2}\right) ; \quad \text { and } \quad e_{2 m^{\prime}}^{\prime}(t)-e_{2 m^{\prime}}(t)=O\left(n^{-2}\right) .
$$

Hence, the result.
Corollary 4.4. Up to the order of approximation in Corollary 4.3,

1. If $n_{1}=n_{2}$, then $\bar{e}^{\prime}(t)-\bar{e}(t)=O\left(n^{-2}\right)$ for all $t,-\infty<t<\infty$;
2. If $n_{1}>n_{2}$, then $\bar{e}(t)<\bar{e}^{\prime}(t)$, if and only if $\sum_{m=1}^{r_{1}} \Delta_{m}^{-1}\left(p_{m 1} \phi\left(\eta_{1 m t}\right)-\right.$ $\left.p_{m 2} \phi\left(\eta_{2 m t}\right)\right)<0$; and
3. If $n_{1}<n_{2}$, then $\bar{e}(t)<\bar{e}^{\prime}(t)$, if and only if $\sum_{m=1}^{r_{1}} \Delta_{m}^{-1}\left(p_{m 1} \phi\left(\eta_{1 m t}\right)-\right.$ $\left.p_{m 2} \phi\left(\eta_{2 m t}\right)\right)>0$.

Remark 4.3. From Corollary 4.4, adjustment of discrete covariates in discrimination of mixed variables without continuous covariates is essential only if the two training samples are of very different sizes.

## 5. NUMERICAL RESULTS

In this section, selected values of $\bar{e}^{\prime}(t)-\bar{e}(t)$ are computed and reported to pinpoint the implication of Corollary 4.3 in practice. To achieve this and have the results conveniently presented, $\Delta_{1}=\cdots=\Delta_{r_{1}}=\Delta=0.5,1.0,1.5$; $t=-0.5,0,0.5 ; \bar{p}=0.2,0.3$ and $n_{2}=k n_{1} ; k=0.8,1.5 ; n_{1}=50,100,200$ are used throughout the study. Only small values of $r, r-r_{1}$ and $\bar{p}$ are considered because discrete discriminators including covariates are rare in practice. The thresholds $t=-0.5,0$, and $t=0.5$ are chosen so that the
effect of departure from the zero threshold and symmetry of $\bar{e}^{\prime}(t)-\bar{e}(t)$ about zero can be examined. To summarize the results of the computations in a readable form, only the cases where $\left(r_{1}, r\right)=(1,2)$, and $\left(r_{1}, r\right)=(2,4)$ are tabulated. Results for unequal values of $\Delta_{m}, m=1, \ldots, r_{1}$ are unlikely to cause much difference due to the rather large values of $n$. Only positive gains due to the adjustment are reported in Tables I and II. In our study, for each given set of values of $\left(r_{1}, r\right) ; \bar{p}$ and $\left(p_{m 1}, p_{m 2}\right)$; for $m=1, \ldots, r_{1}$; and $i=1,2$, there are 54 cases for all the combinations of $t ; \Delta ; k$; and $n_{1}$. The number of cases showing positive gains, no gains and negative gains are equally divided amongst each set of the 54 cases considered in our study. An examination of Table I and Table II indicates that improvement occurs only at nonzero thresholds. For all the cases considered, positive gains occur at a negative threshold for $n_{1}>n_{2}$. This feature is observed again at a positive threshold for $n_{1}<n_{2}$. To summarize, up to the order of approximation given in Corollary 4.3, we have the following:
(i) A nonzero threshold and a substantial difference in the sizes of the two training samples are crucial to a positive gain due to the adjustment.
(ii) Adjustment is beneficial when either $n_{1}>n_{2}$ and a negative threshold is adopted or $n_{1}<n_{2}$ and a positive threshold is adopted.
(iii) At a zero threshold, there is practically no improvement by adjustment no matter the sizes of the two training samples.
(iv) The gain due to the adjustment is unlikely to be dramatic considering the large sample sizes of the two training samples and the other values of the relevant quantities in $\bar{e}^{\prime}(t)-\bar{e}(t)$.

## TABLE I

Values $^{a}$ of $\bar{e}^{\prime}(t)-\bar{e}(t)$ for $\Delta_{1}=\cdots=\Delta_{r_{1}}=\Delta=0.5,1.0,1.5 ; t=-0.5,0.5 ; \bar{p}=0.2,0.3 ; n_{2}=k n_{1}$, $k=0.8,1.5 ; n_{1}=50,100,200$ and $\left(r_{1}, r\right)=(1,2)$ for Cases Where Improvement Is Observed

|  | $n_{1}=$ | 50 | $k=8 \quad t=-0.5$ |  | 50 | $k=1.5$ <br> 100 | $\begin{gathered} t=0.5 \\ 200 \end{gathered}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | 100 | 200 |  |  |  |
| $\bar{p}=0.3 \quad p_{11}=0.7 \quad p_{12}=0.7$ | $\Delta=0.5$ | 9.30 | 4.54 | 2.25 | 12.24 | 6.02 | 2.99 |
|  | $=1.0$ | 6.16 | 3.01 | 1.49 | 8.11 | 3.99 | 1.98 |
|  | $=1.5$ | 3.77 | 1.84 | 0.91 | 4.96 | 2.44 | 1.21 |
| $\bar{p}=0.2 p_{11}=0.8 \quad p_{12}=0.8$ | $\Delta=0.5$ | 6.20 | 3.03 | 1.50 | 8.16 | 4.01 | 1.99 |
|  | $=1.0$ | 4.11 | 2.01 | 0.99 | 5.41 | 2.66 | 1.32 |
|  | $=1.5$ | 2.51 | 1.23 | 0.61 | 3.30 | 1.63 | 0.81 |

[^0]
## TABLE II

Values of $\bar{e}^{\prime}(t)-\bar{e}(t)$ for $\Delta_{1}=\cdots=\Delta_{r_{1}}=\Delta=0.5,1.0,1.5 ; t=-0.5,0.5 ; \bar{p}=0.2,0.3 ; n_{2}=k n_{1}$, $k=0.8,1.5 ; n_{1}=50,100,200$ and $\left(r_{1}, r\right)=(2,4)$ for Cases Where Improvement Is Observed.


Thus, discrete covariate adjustment is essential for a nonzero threshold and is recommended in situations which are considered appropriate.

## APPENDIX

In this section, we prove Theorem 3.1.
Proof. A simple calculation gives part (a). It remains to derive Eq. (3.1). Given $Z_{m}=1, m=1, \ldots, r_{1}$, define $T_{m}, W_{m}, H_{m}$ and $V_{m}$ as follows

$$
\begin{aligned}
\hat{\mu}_{m 1}-\hat{\mu}_{m 2} & =\delta_{m}+(n(m))^{-1 / 2} T_{m} ; \\
\hat{\mu}_{m 1} & =(n(m))^{-1 / 2} W_{m} ; \\
\hat{\beta}_{m} \hat{\beta}_{m}^{\prime} & =b_{m} I_{p}+(n(m))^{-1 / 2} V_{m} ; \quad b_{m}=q(n(m)-q-1)^{-1} ; \\
\hat{\Sigma}_{1.2}^{(m)} & =I_{p}+(n(m))^{-1 / 2} V_{m} .
\end{aligned}
$$

A conditional argument shows that $e_{1 m}(t)=E_{1 m}\left(E_{2 m}\left(\Phi\left(G_{m}\right)\right)\right)$ where $E_{2 m}($.$) and E_{1 m}($.$) denote respectively the conditional expectation given$ $n_{m 1}$ and $n_{m 2}$ and the expectation with respect to $n_{m 1}$ and $n_{m 2}$ with

$$
\begin{aligned}
G_{m}= & a_{m} \Delta_{m}^{-1}\left[t+\log \left(\hat{p}_{m 2} / \hat{p}_{m 1}\right)-\frac{\Delta_{m}^{2}}{2}\right] \\
& +(n(m))^{-1 / 2} L_{m}+(n(m))^{-1} Q_{m}+r_{1 m} ;
\end{aligned}
$$

where

$$
\begin{aligned}
a_{m}= & {\left[(n(m)-q-1)(n(m)-1)^{-1}\right]^{1 / 2} ; } \\
L_{m}= & a_{m} \Delta_{m}^{-1}\left[\delta_{m}^{\prime} W_{m}-\delta_{m}^{\prime} T_{m}+\frac{\delta_{m}^{\prime} V_{m} \delta_{m}}{2}\right] \\
& -a_{m}^{3} \Delta_{m}^{3}\left[t+\log \left(\hat{p}_{m 2} / \hat{p}_{m 1}\right)-\frac{\Delta_{m}^{2}}{2}\right] \\
& \times\left[a_{m}^{-2}\left(\delta_{m}^{\prime} T_{m}-\delta_{m}^{\prime} V_{m} \delta_{m}\right)-\frac{\delta_{m}^{\prime} H_{m} \delta_{m}}{2}\right] ; \\
Q_{m}= & a_{m} \Delta_{m}^{-1}\left[T_{m}^{\prime} W_{m}-\delta_{m}^{\prime} V_{m} W_{m}+\delta_{m}^{\prime} V_{m} T_{m}-\frac{T_{m}^{\prime} T_{m}}{2}-\frac{\delta_{m}^{\prime} V_{m}^{2} \delta_{m}}{2}\right] \\
& -\left[t+\log \left(\hat{p}_{m 2} / \hat{p}_{m 1}\right)-\frac{\Delta_{m}^{2}}{2}\right] \\
& \times\left[\frac { \Delta _ { m } ^ { - 3 } a _ { m } ^ { 3 } } { 2 } \left\{a_{m}^{-2}\left(T_{m}^{\prime} T_{m}-4 \delta_{m}^{\prime} V_{m} T_{m}+3 \delta_{m}^{\prime} V_{m}^{2} \delta_{m}\right)\right.\right. \\
& \left.+2 \delta_{m}^{\prime} H_{m} T_{m}-3 \delta_{m}^{\prime}\left(H_{m} V_{m}+V_{m} H_{m}\right) \delta_{m}\right\} \\
& \left.-\frac{3 \Delta_{m}^{-5} a_{m}^{5}}{2}\left\{a_{m}^{-2}\left(\delta_{m}^{\prime} T_{m}-\delta_{m}^{\prime} V_{m} \delta_{m}\right)+\frac{\delta_{m}^{\prime} H_{m} \delta_{m}}{2}\right\}^{2}\right] \\
& -a_{m}^{3} \Delta_{m}^{-3}\left[a_{m}^{-2}\left(\delta_{m}^{\prime} T_{m}-\delta_{m}^{\prime} V_{m} \delta_{m}\right)+\frac{\delta_{m}^{\prime} H_{m} \delta_{m}}{2}\right] \\
& \times\left[\delta_{m}^{\prime} W_{m}-\delta_{m}^{\prime} T_{m}+\frac{\delta_{m}^{\prime} V_{m} \delta_{m}}{2}\right] ;
\end{aligned}
$$

and $r_{1 m}$ is a remainder term such that $E_{1 m}\left(E_{2 m}\left(r_{1 m}\right)\right)=O\left(n^{-2}\right)$ under $(\mathrm{C} 1)$ and (C2). It follows from Anderson [1, p. 968, Eq. (21)] that

$$
\begin{align*}
e_{1 m}(t)= & E_{1 m}\left(\Phi\left(a_{m} \Delta_{m}^{-1}\left[t+\log \left(\hat{p}_{m 2} / \hat{p}_{m 1}\right)-\frac{\Delta_{m}^{2}}{2}\right]\right)\right) \\
& +n^{-1} E_{1 m}\left(A_{m}\right)+O\left(n^{-2}\right) \tag{1}
\end{align*}
$$

where

$$
\begin{aligned}
A_{m}= & n \phi\left(a_{m} \Delta_{m}^{-1}\left[t+\log \left(\hat{p}_{m 2} / \hat{p}_{m 1}\right)-\frac{\Delta_{m}^{2}}{2}\right]\right) \\
& \times\left[(n(m))^{-1 / 2} E_{2 m}\left(L_{m}\right)+(n(m))^{-1}\right. \\
& \left.\times\left\{E_{2 m}\left(Q_{m}\right)-\frac{a_{m} \Delta_{m}^{-1}}{2}\left[t+\log \left(\hat{p}_{m 2} / \hat{p}_{m 1}\right)-\frac{\Delta_{m}^{2}}{2}\right] E_{2 m}\left(L_{m}^{2}\right)\right\}\right] .
\end{aligned}
$$

By Lemma 3.1, $E_{2 m}\left(L_{m}\right)=0$. Using the probability limits of $a_{m}, b_{m}$ and $d_{m}$, we have

$$
\begin{equation*}
n^{-1} E_{1 m}\left(A_{m}\right)=n^{-1} \phi\left(\eta_{1 m t}\right) \gamma_{1 m t}+O\left(n^{-2}\right) . \tag{2}
\end{equation*}
$$

An application of Lemma 3.3 with a similar calculation in the expansions of $\Phi\left(a_{m} \Delta_{m}^{-1}\left[t+\log \left(\hat{p}_{m 2} / \hat{p}_{m 1}\right)-\Delta_{m}^{2} / 2\right]\right)$ and $\phi\left(a_{m} \Delta_{m}^{-1}\left[t+\log \left(\hat{p}_{m 2} / \hat{p}_{m 1}\right)-\right.\right.$ $\left.\Delta_{m}^{2} / 2\right]$ ) leads to

$$
\begin{align*}
E_{1 m} & \left(\Phi\left(a_{m} \Delta_{m}^{-1}\left[t+\log \left(\hat{p}_{m 2} / \hat{p}_{m 1}\right)-\frac{\Delta_{m}^{2}}{2}\right]\right)\right) \\
& =\Phi\left(\eta_{1 m t}\right)+n^{-1} \phi\left(\eta_{1 m t}\right)\left(\alpha_{1 m t}+\tau_{1 m t}\right)+O\left({ }^{-2}\right) \tag{3}
\end{align*}
$$

Combining Eq. (2) and Eq. (3) gives Eq. (3.1). This proves part (b).

## ACKNOWLEDGMENTS

The author is grateful to the editor in charge and two referees for many constructive comments that helped improve the revision.

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[^0]:    ${ }^{a}$ Actual figures equal $10^{-5}$ times the tabulated values.

