# Origami fold as algebraic graph rewriting ${ }^{\text {, wh }}$ 站 

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#### Abstract

We formalize paper fold (origami) by graph rewriting. Origami construction is abstractly described by a rewriting system $(\mathbb{O}, \rightarrow)$, where $\mathbb{O}$ is the set of abstract origamis and $\leftrightarrow$ is a binary relation on $\mathbb{O}$, that models fold. An abstract origami is a structure ( $\Pi, \backsim$, $\succ)$, where $\Pi$ is a set of faces constituting an origami, and $\backsim$ and $\succ$ are binary relations on $\Pi$, each representing adjacency and superposition relations between the faces.

We then address representation and transformation of abstract origamis and further reasoning about the construction for computational purposes. We present a labeled hypergraph of origami and define fold as algebraic graph transformation. The algebraic graphtheoretic formalism enables us to reason about origami in two separate domains of discourse, i.e. pure combinatorial domain where symbolic computation plays the main role and geometrical domain $\mathbb{R} \times \mathbb{R}$. We detail the program language for the algebraic graph rewriting and graph rewriting algorithms for the fold, and show how fold is expressed by a set of graph rewrite rules.


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## 1. Introduction

The art of paper folding, known as origami, ${ }^{2}$ provides the methodology of constructing a geometrical object out of a sheet of paper solely by means of folding by hands. Computational

[^0]origami studies the mathematical and computational aspects of origami, including visualization by a computer (Demaine and Demaine, 2002). By the assistance of a computer, we will be able to formalize origami with rigor and capability that are beyond the methods performed by hands.

In this article, we give graph-theoretic formalization of origami. Our motivation of this study is to give more abstract view of fold used in origami. Although origami fold appears to be an easy operation to humans, even a naïve anatomy of origami reveals that it is not the case from computational point of view. There are two distinct operations in paper fold, i.e. division and reflection of origami faces. These operations lend themselves to distinct modes of computations: algebraic and numeric computation on geometrical objects, e.g., finding intersection of lines and checking the overlap of two faces, on one hand, and purely combinatorial computation on discrete objects, e.g., computing transitive closure of the adjacency relation on faces, on the other.

These computations tend to be mixed when origami is analyzed mathematically (Ida et al., 2007). Indeed, the implementation of computational origami system Eos (Ida et al., 2006) relies very much on algorithms which resort to mixtures of algebraic, numeric and symbolic computing. Sometimes, algorithms are hard to describe mathematically because of this complication. There should be clearer separation of computations of discrete and continuous objects in origami. When this has been done, we not only clarify the algorithms developed for the implementation of Eos, but also are in a position to extend the capability of Eos to allow for more complex origami constructions such as of 3D and modular origami, and to reason about their geometrical and algebraic properties.

The rest of the article is organized as follows. In Section 2, we will formalize origami as an abstract origami system, which can be regarded as an abstract rewrite system. In Section 3, we will elaborate the abstract origami system by giving to it more algebraic and geometrical structures, and then we will analyze the structures. Section 4 is a short passage from the abstract description of origami to more algorithmic description of origami. In Sections 5 and 6, we will explain the bases for graph-theoretic modeling of origami. In Section 7, we show fold as a set of graph rewrite rules. In Section 8, we will summarize the results and point out the direction of further research.

## 2. Formalizing origami

### 2.1. Preliminaries

In this subsection, we summarize the basic mathematical notations that we will use throughout this article. Given an arbitrary set $A$, a sequence of elements $a_{1}, \ldots, a_{n} \in A$ is denoted by $\left\langle a_{1}, \ldots, a_{n}\right\rangle$. If $n=1$, the sequence is written as $a_{1}$. In other words, $\langle a\rangle$ and $a$ denote the same mathematical object. If $A$ is an alphabet, the sequence of elements $a_{1}, \ldots, a_{n}(\in A)$ is denoted by the juxtaposition of the elements, i.e. $a_{1} \cdots a_{n}$. The set of all the sequences of the elements in $A$ is denoted by $A^{*}$. We use * in the superscript position in the following ways, too. Namely, $f^{*}$ for a function $f$ is defined as: $f^{*}\left(\left\langle a_{1}, \ldots, a_{n}\right\rangle\right)=\left\langle f\left(a_{1}\right), \ldots, f\left(a_{n}\right)\right\rangle . R^{*}$ for a binary relation $R$ is the reflexive and transitive closure of $R$. The transitive closure of $R$ is denoted by $R^{+}$. A sequence $\left\langle a_{1}, \ldots, a_{n}\right\rangle$ is called an $R$-sequence, if $a_{1} R a_{2} \wedge \cdots \wedge a_{n-1} R a_{n}$. For an irreflexive $R$, an $R$-sequence $\left\langle a_{1}, \ldots, a_{n}\right\rangle$ is called acyclic if $\forall i<j \neg\left(a_{j} R a_{i}\right)$. The cross product of sets $A_{1}, \ldots, A_{n}$ is denoted by $A_{1} \times \cdots \times A_{n}$. The element of $A_{1} \times \ldots \times A_{n}$, i.e. $n$-tuple, is denoted by $\left(a_{1}, \ldots, a_{n}\right)$, where $a_{i} \in A_{i}$ for $i=1, \ldots, n$.

### 2.2. Origami at a glance

We begin an origami construction with a single sheet of paper, and repeat folding the paper until it becomes a desired shape. We can observe that an origami can be modeled as a set of faces. During the construction, some of the faces are divided by a fold line, reflected along the fold line and become above or below the others. The faces form a stack of layers. The stack of layers of faces exhibits a remarkable shape, which may be regarded as a piece of art such as illustrated in Fig. 1.

The left origami in Fig. 1 is the top view of the constructed object. We see the faces in two different colors in the figure. This is because the initial origami has two sides, each colored differently. During the construction, some faces become up and the others become down, resulting in the two colored object. We can imagine that this origami models a cicada. The right is a 3D view of the same origami


Fig. 1. Origami cicada: art piece (left) and stack of face layers (right).
after stretching it vertically and making superposing faces slightly far apart. From the shapes in Fig. 1, we will be able to see that an origami can be formalized as a set of faces together with the relations that express relative positions, horizontally and vertically, among the faces.

### 2.3. Abstract origami rewrite system

An origami can be modeled at several abstraction levels. A most abstract view is to take an origami as an algebra $(A, R)$, where $A$ is a set and $R$ is a binary relation on $A$, where we identify a set of faces that constitute an origami with $A$, and a geometrical relation on the faces with $R$. The origami construction is then a transformation of the algebras viewed as an abstract rewrite system. We begin with this abstract view of origami and gradually make our modeling concrete.

Our first attempt is as follows. We take a finite set $\Pi$ of faces as the object of our study, and introduce two binary relations on $\Pi$, expressing horizontal and vertical arrangements of faces rather than a single binary relation $R$ mentioned above. Then, we have the following definition of an origami.
Definition 1 (Abstract Origami). An abstract origami is a structure ( $\Pi, \backsim, \succ$ ), where $\Pi$ is the finite set of (origami) faces, $\sim$ is a symmetric binary relation on $\Pi$, called adjacency relation, and $\succ$ is a binary relation on $\Pi$, called superposition relation.
An abstract origami is abbreviated to AO, hereafter.
We next present a view that an origami construction is a rewrite sequence of an abstract rewrite system. This view bridges the set theoretic treatment of origami and graph rewriting of origami.
Definition 2 (Abstract Origami System). An abstract origami system is an abstract rewrite system $(\mathbb{O}, \leftrightarrow)$, where $\mathbb{O}$ is the set of AOs, and $\rightarrow$ is a rewrite relation on $\mathbb{O}$, called abstract fold.
When $O, O^{\prime} \in \mathbb{O}$ are related by $\rightarrow$, we write $O \leftrightarrow O^{\prime}$ and say that $O$ is rewritten or abstractly folded to $O^{\prime}$.

An origami construction proceeds as follows. We start with an initial origami and perform folds repeatedly until we obtain a desired shape of the origami. Usually, we begin an origami construction with a square sheet of paper, but the sheet can be in any shape having convexity. This initial sheet of paper is abstracted as a structure having a single distinguished face to be denoted by $f_{0}$. Then, we define the initial AO, denoted by $I$, as follows.
Definition 3 (Initial Abstract Origami). The initial AO I is a structure ( $\left\{f_{0}\right\}, \emptyset, \emptyset$ ).
Suppose that we are at the beginning of step $i$ of the construction, having an origami $O_{i-1}=$ $\left(\Pi_{i-1}, \backsim_{i-1}, \succ_{i-1}\right)$. We perform a fold and obtain the next origami $O_{i}=\left(\Pi_{i}, \backsim_{i}, \succ_{i}\right)$. Thus, we have the following:
Definition 4 (Abstract Origami Construction). An abstract origami construction is a finite sequence of AOs satisfying

$$
O_{0}(=I) \leftrightarrow O_{1} \leftrightarrow \cdots \leftrightarrow O_{n}, \quad \text { where } O_{0}, O_{1}, \ldots, O_{n} \in \mathbb{O} \text {. }
$$



Fig. 2. Abstract folds from the initial AO with geometrical interpretation.
In this article, we decompose an abstract fold into two finer operations in order to make our formalism general enough to model both mathematical origami and art origami. Namely, we decompose a fold into the following operations: (a) making a crease along which the sheet is bended, and then (b) actually bending the sheet. We call the operation (a) crease and operation (b) basic fold.

In mathematical origami, we are primarily interested in constructing points on the origami. Those points form the vertices of the shape that we want to construct. In such cases, we only need creases and points of intersections of the creases and the sides of the initial origami. In art origami, we are interested in artistic shapes that are composed of layers of faces. In art origami, bending the sheets are equally important. Bending outwards is commonly called mountain fold, and inwards valley fold. In summary, we have the relation of the abstract fold as the composition of the relations crease $(\xrightarrow{\boldsymbol{m}})$, and basic fold $(\underset{\rightarrow}{\sim})$. The basic fold is a union of mountain fold $(\underset{\rightarrow}{\sim})$ and valley fold $(\xrightarrow{\sim})$.

In the case of an unfold, no crease operation precedes a valley fold or a mountain fold. In this case, the crease operation is vacuous, i.e. $\xrightarrow[\rightarrow]{\sim}$ is the identity relation. In some mathematical folds, creasing is important and basic folds play no role. In such a case, $\xrightarrow[\rightarrow]{\sim}$ ( or $\xrightarrow{\Omega}$ ) is the identity relation.

Let us consider an example of the abstract origami construction. We are interested in the construction that starts with $O_{0}=I$ and simulates the origami construction by hands.
Example 1 (Construction from the Initial Abstract Origami). We are given the initial AO I. We define $\mathrm{O}_{1}^{\prime}$ and $O_{1}$ as follows: $O_{1}^{\prime}=\left(\Pi_{1}^{\prime}, \sim_{1}^{\prime}, \succ_{1}^{\prime}\right)$, where $\Pi_{1}^{\prime}=\left\{f_{1}, f_{2}\right\}, \sim_{1}^{\prime}=\left\{\left(f_{1}, f_{2}\right)\right\}, \succ_{1}^{\prime}=\emptyset, O_{1}=\left(\Pi_{1}, \sim_{1}, \succ_{1}\right)$, where $\Pi_{1}=\Pi_{1}^{\prime}, \sim_{1}=\sim_{1}^{\prime}, \succ_{1}=\left\{\left(f_{2}, f_{1}\right)\right\}$. Fig. 2 shows the rewrites of the initial AO. $O_{1}$ is the abstraction of the origami resulting from folding the initial origami once. $O_{1}$ is obtained first by creasing $I$, thus constructing $O_{1}^{\prime}$, and then by making a valley fold.

We also allow a fold along the sides of the faces. Then, the fold along one of the four sides of the initial origami is simply turning over the initial origami. I and the abstraction of the upside-down ones of the initial origami are the same. Therefore, we have abstract origami constructions such as:

$$
\begin{aligned}
& I \stackrel{\leftrightarrow}{I} O_{1}(=I), \\
& I \leftrightarrow O_{1},\left(I \xrightarrow{\hookrightarrow} O_{1}^{\prime} \text { and } O_{1}^{\prime} \xrightarrow{\curvearrowleft} O_{1}\right) .
\end{aligned}
$$

Fig. 2 shows that some faces are colored differently from the others. This property is abstracted away during the process of the abstraction that leads to the abstract rewriting system. The property of "sides" appear when we give more geometrical structures in Section 3.


The two faces $f_{1}$ and $f_{2}$ are created by the crease $X Y$. The two faces share the same edge $X Y$.

Fig. 3. Adjacent faces created by crease.


On the left, the two faces $f_{1}$ and $f_{2}$ share the same edge $X Y$. On the right, the faces $f_{1}$ and $f_{2}$ are modeled as two plane surfaces with infinitesimally small vertical distance. The two surfaces have the same edge $X Y$ and are considered to share the same edge.

Fig. 4. Adjacent faces created by fold along crease.

## 3. Geometrical and algebraic structures of origami

The notion of fold is central in origami and in abstract origami systems. The relation of $\rightarrow$ is given a priori in defining the abstract rewrite system. There is no clue in the above formalism as to how an AO is computationally related via $\rightarrow$ to the other. We now give more geometrical structures to the constituents of the abstract origami system to relate AOs computationally.

### 3.1. Geometry of origami

We rely on the following geometrical intuition.
(I1) A face is a plane surface in the sense of Euclid's Elements.
(I2) A face can share the boundary with other faces. See Figs. 3 and 4.
(I3) A face can be above other faces, and all the faces form a stack of face layers. See Fig. 5.
(I4) A point belonging to a face can be overlaid on the other points belonging to other faces. See Fig. 6.
Then, we give more geometrical structures to the notion of a face. We appeal to the readers for the intuition (I1) and define a face as follows.

## Definition 5 (Face). A face is a convex $n$-gon.

Recall that an $n$-gon ( $n \geqslant 3$ ) is a polygon consisting of $n$ edges, none of which intersects each other. We represent an $n$-gon as a sequence $\left\langle P_{1}, \ldots, P_{n}\right\rangle$ of pairwise distinct points, where points $P_{1}, \ldots, P_{n}$ are vertices of the n-gon. Any cyclic permutations of a given sequence could represent the same face, but we choose one particular sequence among them in order to represent a face uniquely. The convexity does not play a role in this article. It is abstracted away in our discussion, but is used crucially in the design of the algorithms for face division and for checking face overlap. When points $P_{1}, \ldots, P_{n}$ are arranged counterclockwise, we say that the face is up, and when clockwise, down. In the figures, we distinguish the sides of the faces by the shading (colored if color print is possible).


The faces $f_{1}, f_{2}, f_{3}$ and $f_{4}$ form a stack of three layers $\left(f_{1}\right),\left(f_{2}\right)$ and ( $f_{3}, f_{4}$ ).

Fig. 5. Stack of face layers.


The point $P$ belonging to the face $f_{1}$ overlays the point $Q$ belonging to the face $f_{3}$.

Fig. 6. Overlay of points.
We can now define the adjacency relation as follows.
Definition 6 (Face Adjacency). Two distinct faces are adjacent if they share an edge.
The adjacency relation is generated between the two faces that have been constructed by the division of a face. Our construction ensures the following properties, and we take them as an axiom of our construction by folds. In describing the axiom, we use the following notation. When a face $f$ is divided by a ray $r$ into ( $f_{1}, f_{2}$ ), where $f_{1}$ is to the left of the ray $r$ and $f_{2}$ is to the right of $r$, we write $f \rightarrow_{r}\left(f_{1}, f_{2}\right)$. Later, we also write $f \rightarrow_{r} f^{\prime}$, where $f^{\prime}$ is one of $f_{1}$ and $f_{2}$, whenever we need only to specify one of the divided faces. The subscript $r$ in $\mapsto_{r}$ may be omitted if intended $r$ is clear from the context. When $f \rightarrow\left(f_{1}, f_{2}\right), f$ is called the immediate ancestor of $f_{1}\left(\right.$ and $\left.f_{2}\right)$. Face $g_{1}$ is called the ancestor of face $g_{k}$ if there exists $g_{2}, \ldots, g_{k}$ such that $g_{j}$ is the immediate ancestor of $g_{j+1}$ for $j=1, \ldots, k-1$.

Axiom 7. Suppose $f \mapsto_{r}\left(f_{1}, f_{2}\right)$. Then, we have the following:
(1) $f_{1} \backsim f_{2}$.
(2) Let $X$ and $Y$ be points of intersection with the ray $r$ and $X Y$ be one of the edges of $f_{1}$ such that $f_{1}=\langle X, Y, \ldots\rangle$. Then, $f_{2}=\langle Y, X, \ldots\rangle$.
(3) The sides of the faces $f, f_{1}$ and $f_{2}$ are the same.

Fig. 7 depicts the adjacency relation between the divided faces.
Note that the $n$-gon $\langle X, Y, \ldots\rangle$ can be denoted by any cyclic permutation of the sequence $\langle X, Y, \ldots\rangle$.However, we fix the denotation as in Axiom 7. The following lemma is an easy consequence of our construction.


The faces $f_{1}=\left\langle X, Y, P_{3}, P_{1}\right\rangle$ and $f_{2}=\left\langle Y, X, P_{2}\right\rangle$ are created by the division of face $f=\left\langle P_{1}, P_{2}, P_{3}\right\rangle$ by the ray $r$.

Fig. 7. Faces and the adjacency relation as determined by Axiom 7.
By $\langle X, Y\rangle$, we denote the set of all the finite sequences that have a subsequence $\langle X, Y\rangle$ and their cyclic permutations.

Lemma 8. For any $0=(\Pi, \backsim, \succ)$ such that $I \rightarrow \sim^{*} 0$,
$\forall f, g \in \Pi \quad(f, g \in\langle X, Y\rangle$ for some points $X$ and $Y \Leftrightarrow f=g)$
Lemma 8 states that a directed edge of a face in a given $\Pi$ uniquely identifies the face. As we have decided the representation of a face, we have the following equivalence.

Proposition 9. For any $O=(\Pi, \backsim, \succ)$ such that $I \leftrightarrow{ }^{*} O, \forall f, g \in \Pi$

$$
f \backsim g \Leftrightarrow \exists \text { points } X \text { and } Y \text { such that } f \in\langle X, Y\rangle \wedge g \in\langle Y, X\rangle \text {. }
$$

Proof. $(\Leftarrow)$ The edge $X Y$ are shared by $f$ and $g$. By definition of the adjacency, $f \backsim g$.
$(\Rightarrow)$ We have either $f \in\langle X, Y\rangle \wedge g \in\langle Y, X\rangle$ for some points $X$ and $Y$, or $f \in\langle X, Y\rangle \wedge g \in\langle X, Y\rangle$ for some points $X$ and $Y$. The latter is impossible by Lemma 8.

Example 2 (Adjacency Relation). We make use of Example 1. The faces of $f_{1}$ and $f_{2}$ in Fig. 2 are adjacent by the following reasoning. We have $f_{1}=\langle E, F, D, A\rangle$ and $f_{2}=\langle F, E, B, C\rangle$. Since $f_{1}$ and $f_{2}$ share the edge $E F$, we can see that $f_{1} \backsim f_{2}$ and $f_{2} \backsim f_{1}$.

The superposition relation gives the vertical arrangement of faces. We first appeal to the readers for intuition about the notion of above and below among faces (cf. Intuition (I3)), where below is the inverse relation of above. Roughly speaking, face $f$ superposes face $g$ iff $f$ is above $g$, and moreover $f$ and $g$ "face" each other. Let us take a look at Fig. 2 again. We consider making a valley fold on the face $f_{0}$. The face $f_{0}$ is divided into ( $f_{1}, f_{2}$ ). The face $f_{2}$ is rotated along the axis $E F$ by an angle $\pi$. The face $f_{2}$ is clearly above $f_{1}$ in $O_{2}$ and $f_{1}$ faces $f_{2}$. Hence, $f_{2}$ superposes $f_{1}$.

We are now ready to formalize the notion of superposition. We proceed as follows. First, we formalize the notion of overlap based on the intuition (I4). Then, we define the relation over on the set of faces. Using the notion of over, we define above and superposition.

Definition 10 (Overlap). Faces $f$ and $g$ overlap, denoted by $f \asymp g$, iff there exist points $P$ and $Q$, each belonging to faces $f$ and $g$, respectively, such that $P$ overlays $Q$ (or vice versa).
Note that we allow a point to be overlaid on itself, Hence, a face can overlap with itself. One might imagine that there is a through-hole that penetrates the points $P$ and $Q$.

To define the relation over, we will use the following notations. Let $\stackrel{\rightharpoonup}{r}_{r}$ be $\mapsto_{r} \cup=$, where $=$ is the equality on faces. The relation $\stackrel{\Xi}{r}_{r}$ is introduced more for convenience; By $f \stackrel{\Xi}{r} f^{\prime}$ we want to describe the situation where $r$ may not divide $f$.

Let $\sim_{\text {on }(r)}$ denote the adjacency relation between two faces that share an edge that lies on the ray $r$ and let $\sim_{\operatorname{on}(r)}=\backsim \backslash \sim_{\mathrm{on}(r)}$. Let $\sim_{\text {left }(r)}$ denote the adjacency relation between two faces that share an edge that is to the left of the ray $r$ and let $\sim$ left $(r)=\backsim \backslash \sim_{\text {left }(r)}$.

To make a crease on an origami, we need to specify the ray $r$ and the set $C$ of faces to which we want to apply the face division and on which we want to make a crease afterwards. The set $C$ is called a candidate set of face division. Origamists give a set $F$ of faces that they want to make a crease. Then, $C$ can be determined as

$$
C=\bigcup_{f \in F}\left\{g \mid g \sim_{\neg \operatorname{left}(r)}^{*} f\right\}
$$

Later, we will discuss how to compute the set $C$. For now, it is sufficient to note that whenever we discuss the fold $\rightarrow$, we assume that $r$ and $C$ are implicitly given.

To make a basic fold $O^{\prime} \xrightarrow{\sim} O^{\prime \prime}$ after $O \xrightarrow[\rightarrow]{\text { m }} O^{\prime}\left(=\left(\Pi^{\prime}, \sim^{\prime}, \succ^{\prime}\right)\right.$ ), we need to determine the set $\Pi_{M}^{\prime}$ of faces that are to be moved and the set $\Pi_{N}^{\prime}$ of faces that are not moved. We define $\Pi_{M}^{\prime}$ and $\Pi_{N}^{\prime}$ as follows:

$$
\Pi_{M}^{\prime}=\bigcup_{f \in D}\left\{g \mid g\left(\sim_{-\operatorname{on}(r)}^{\prime} \cup \succ^{\prime}\right)^{*} f\right\}, \text { and } \Pi_{N}^{\prime}=\Pi^{\prime} \backslash \Pi_{M}^{\prime}
$$

where $D$ is the set of faces that have been divided in $O \xrightarrow{\sim} O^{\prime}$ and are to the right of the ray $r$.
Definition 11 (Over). Let $O=(\Pi, \backsim, \succ)$ be an AO. We define the relation over, denoted by $\gtrdot$, on $\Pi$ inductively on the construction of AOs.

Suppose $I \rightarrow{ }^{*} 0$
$\forall f, g \in \Pi$.

- Base case: $0=I$

$$
\gtrdot=\emptyset .
$$

- Inductive case 1:I $\stackrel{*}{*}_{*} O \xrightarrow{m} O^{\prime}\left(\xrightarrow{\sim} O^{\prime \prime}\right)$ where $O=(\Pi, \backsim, \succ)$, and $\gtrdot$ is defined on $\Pi$. We will define $\gg$ on $\Pi^{\prime}$ as follows.

$$
f^{\prime} \gtrdot^{\prime} g^{\prime} \quad \text { iff } \exists f, g \in \Pi(f \gtrdot g) \wedge\left(f \stackrel{\doteq}{\rightleftharpoons} f^{\prime}\right) \wedge\left(g \stackrel{\Xi}{\rightleftharpoons} g^{\prime}\right) \wedge\left(f^{\prime} \asymp g^{\prime}\right)
$$

- Inductive case 2.1: $I \overbrace{}^{*} O \xrightarrow{\sim} O^{\prime} \xrightarrow{\curvearrowleft} O^{\prime \prime}$ where $O^{\prime}=\left(\Pi^{\prime}, \varpi^{\prime}, \succ^{\prime}\right)$, and $\gtrdot^{\prime}$ is defined on $\Pi^{\prime}$. We will define $\gtrdot^{\prime \prime}$ on $\Pi^{\prime \prime}$ as follows. Note that in both cases 2.1 and 2.2 we have $\Pi^{\prime \prime}=\Pi^{\prime}$ and that $f \asymp g$ is geometrically interpreted for the case that $f, g \in \Pi^{\prime \prime}$.

$$
f \gtrdot^{\prime \prime} g \quad \text { iff } \quad\left(g \gtrdot^{\prime} f \wedge f, g \in \Pi_{M}^{\prime}\right) \vee\left(f \gtrdot^{\prime} g \wedge f, g \in \Pi_{N}^{\prime}\right) \vee\left(f \asymp g \wedge f \in \Pi_{M}^{\prime} \wedge g \in \Pi_{N}^{\prime}\right)
$$

- Inductive case 2.2:I $\rightarrow^{*} O \xrightarrow{m} O^{\prime} \xrightarrow{\curvearrowright} O^{\prime \prime}$ where $O^{\prime}=\left(\Pi^{\prime}, \sim^{\prime}, \succ^{\prime}\right)$, and $>^{\prime}$ is defined on $\Pi^{\prime}$. We will define $\gtrdot$ " on $\Pi^{\prime \prime}$ as follows.

$$
f \gtrdot^{\prime \prime} g \quad \text { iff } \quad\left(g \gtrdot^{\prime} f \wedge f, g \in \Pi_{M}^{\prime}\right) \vee\left(f \gtrdot^{\prime} g \wedge f, g \in \Pi_{N}^{\prime}\right) \vee\left(f \asymp g \wedge g \in \Pi_{M}^{\prime} \wedge f \in \Pi_{N}^{\prime}\right)
$$

Definition 12 (Above). The relation above, denoted by $\gg$, is the transitive closure of $>$.
The notion of below becomes rigorous now, since it is the inverse relation of above. Note that the relation $>$ does not have the transitivity, as the following example shows.
Example 3 (Over and Above). Fig. 8 illustrates the relations over and above. Face $f_{1}$ is over $f_{2}$. Face $f_{2}$ is over $f_{3}$. Hence, face $f_{1}$ is above $f_{2}$ and $f_{3}$, and face $f_{2}$ is above $f_{3}$. However, face $f_{1}$ is not over $f_{3}$ since $f_{1}$ does not overlap with $f_{3}$.

Finally, we define the relation of superposition.
Definition 13 (Superposition). Let $O=(\Pi, \backsim, \succ)$ be an AO such that $I \rightarrow^{*} 0$. We define the relation superposition, denoted by $\succ$, on $\Pi$ as follows.

$$
\forall f, g \in \Pi f \succ g \quad \text { iff } \quad(f \gtrdot g) \wedge\left(\forall h \in \Pi \quad\left(f \gtrdot h \gtrdot \gtrdot^{*} g \Longrightarrow h=g\right)\right)
$$



Fig. 8. Relations: over and above.

### 3.2. Analysis of relations

We will derive basic mathematical properties of the relations defined in Section 3.1. The following propositions are immediate from the definitions of the relations.

Proposition 14 (Asymmetry of $\gtrdot$ ).

$$
\forall 0=(\Pi, \backsim, \succ) \in \mathbb{O} \text { such that } I \gtrdot^{*} 0, \forall f, g \in \Pi f \gtrdot g \Longrightarrow \neg(g \gtrdot f) \text {. }
$$

In the following, all the propositions in this subsection hold for $O$ under the context " $\forall O=(\Pi, \backsim, \succ)$ $\in \mathbb{O}$ such that $I \leftrightarrow_{*}^{*} 0$ ". We omit this context for brevity.

Corollary 15 (Irreflexivity of $\gtrdot$ ).
$\forall f \in \Pi \neg(f \gtrdot f)$.

## Proposition 16.

$$
\forall f, g \in \Pi f \gtrdot g \Longrightarrow f \asymp g
$$

## Proposition 17.

```
>> \supset\succ.
```


## Lemma 18.

$$
\neg\left(\gtrdot \supset \succ^{+}\right)
$$

Proof. There exist faces $f, g$ and $h$ such that $f \succ h$ and $h \succ g$ and $f \nprec g$. By Proposition $16, \neg(f \gtrdot g)$ if $f \nprec g$.

Proposition 19. An $\gtrdot$-sequence is acyclic.
Proof. By induction on the construction of AOs.

- Base case: $0=I$

Immediate, since we have $\neg\left(f_{0} \gtrdot f_{0}\right)$.

- Inductive case: $I \neg^{*} O \leftrightarrow O^{\prime}$ and $O=(\Pi, \backsim, \succ)$

We assume the non-existence of a cyclic $>$-sequence. We prove by contradiction. Suppose, there exists a cyclic $\gtrdot^{\prime}$-sequence. Taking the irreflexivity of $\gtrdot$ ' into account, we can write the sequence as

$$
\left\langle g_{0}^{\prime}\left(=g^{\prime}\right), g_{1}^{\prime}, \ldots, g_{n}^{\prime}, g_{n+1}^{\prime}\left(=g^{\prime}\right)\right\rangle, \quad \text { where } n \geq 1
$$

We distinguish the following three cases:
(1) $I \xrightarrow{*} O \xrightarrow{\text { m }} O^{\prime}\left(\xrightarrow{\sim} O^{\prime \prime}\right)$

By the definition of $\gtrdot^{\prime}$, we have on $O$ the $\gtrdot$-sequence:

$$
\begin{equation*}
\left\langle g_{0}(=g), g_{1}, \ldots, g_{n}, g_{n+1}(=g)\right\rangle, \quad \text { where } n \geq 1 \tag{1}
\end{equation*}
$$

The sequence (1) is cyclic. This contradicts the induction hypothesis.
(2) $I \xrightarrow{*} O \xrightarrow{\sim} O^{\prime} \xrightarrow{n} O^{\prime \prime}$

We further distinguish the following two cases.
(a) $g \in \Pi_{M}^{\prime}$

We show that $g_{i} \in \Pi_{M}^{\prime}$ for all $i \in\{1, \ldots, n\}$. Suppose the contrary, i.e., there exists $i \in\{1, \ldots, n\}$ such that $g_{i} \in \Pi_{N}^{\prime}$. Let $j$ be the maximum index among such i's, i.e.,
$g_{j} \gtrdot^{\prime \prime} g_{j+1}, g_{j} \in \Pi_{N}^{\prime}, g_{j+1} \in \Pi_{M}^{\prime}$.
By the definition of $\gtrdot^{\prime \prime}$, if $g_{j}$ and $g_{j+1}$ overlap, then we have $g_{j+1} \gtrdot{ }^{\prime \prime} g_{j}$, else we have $\neg\left(g_{j+1} \gtrdot^{\prime \prime} g_{j}\right) \wedge \neg\left(g_{j} \gtrdot^{\prime \prime} g_{j+1}\right)$. Using the asymmetry of $\gtrdot^{\prime \prime}$, in both cases, we have
$\neg\left(g_{j} \gtrdot^{\prime \prime} g_{j+1}\right)$, which is contradictory. Therefore, we have for all $i \in\{1, \ldots, n\}, g_{i} \in \Pi_{M}^{\prime}$. This implies that we have the $>$ '-sequence:
$\left\langle g_{n+1}(=g), g_{n}, \ldots, g_{1}, g_{0}(=g)\right\rangle \quad$ where $n \geq 1$.
The sequence (2) is cyclic. This contradicts the induction hypothesis.
(b) $g \in \Pi_{N}^{\prime}$

We can show that $g_{i} \in \Pi_{N}^{\prime}$ for all $i \in\{1, \ldots, n\}$. We take the minimum $j$ instead. We then derive the same contradiction.
(3) $I \xrightarrow{*} O \xrightarrow{\longrightarrow} O^{\prime} \xrightarrow{\hookrightarrow} O^{\prime \prime}$

This case is treated similarly to the previous case.
In summary, we can conclude that $>$ is acyclic.
Noting Proposition 17, we have the following corollaries.
Corollary 20. $A \succ$-sequence is acyclic.
Corollary 21. Relation $\gg$ is asymmetric.
Since a strict partial order is a relation that is asymmetric and transitive, we have the following.
Proposition 22. Relation $\gg$ is a strict partial order.

## Lemma 23.

$$
\forall f, g \in \Pi f \gtrdot g \Longrightarrow \exists h \in \Pi\left(f \succ h \gtrdot^{*} g\right) .
$$

Proof. Let $f$ and $g$ be arbitrary but fixed elements of $\Pi$, satisfying $f \gtrdot g$. Let $K_{f}=\{k \in \Pi \mid f \gtrdot k\}$. $K_{f} \neq \emptyset$, since $g \in K_{f}$. We prove $\exists h \in \Pi \quad\left(f \succ h \gtrdot^{*} g\right)$ by the induction on the cardinality of $K_{f}$.

If the cardinality of $K_{f}$ is 2, i.e. the base case, we are done. Let $H=\left\{h \in K_{f} \mid \forall k \in K_{f} \neg(k \gtrdot h)\right\}$. Obviously, $H \neq \emptyset$.

If $g \in H$, then $f \succ g$ by definition of $\succ$, and we are done.
If $g \notin H$, there exists $h \in K_{f}$ such that $h \gtrdot g$. We consider $K_{f}^{\prime}=\{k \in \Pi \backslash\{g\} \mid f \gtrdot k\}$ and $f \gtrdot h$ for our inductive argument. The cardinality of $K_{f}^{\prime}$ is one less than the cardinality of $K_{f}$. By the induction hypothesis, $\exists h^{\prime} \in \Pi f \succ h^{\prime} \gtrdot^{*} h$. Therefore, we have $f \succ h^{\prime} \gtrdot^{*} h \gtrdot g$, and we are done.

## Proposition 24.

$$
\succ^{+} \supset \gtrdot^{+} .
$$

Proof. Since $\Pi$ is finite and an $>$-sequence is acyclic by Proposition 19, the relation $\gtrdot$ on $\Pi$ is a wellfounded order. We therefore prove the claim by the well-founded induction. Let $f$ and $g$ be arbitrary but fixed elements in $\Pi$ such that $f \gtrdot^{+} g$. By Lemma $23, \exists h \in \Pi f \succ h \gtrdot^{*} g$. If $h=g$, then we are done. This constitutes the base case of the induction.

We next consider the case $f \succ h \gtrdot^{*} g$ and $h \neq g$. Since $\gtrdot \supset \succ, f \succ h \gtrdot \gtrdot^{*} g$ implies $f \gtrdot h \gtrdot^{*} g$. By the induction hypothesis $h \succ^{+} g$. Hence, $f \succ h \succ^{+} g$, and then $f \succ^{+} g$.

## Theorem 25.

```
>> > }\mp@subsup{}{}{+}
```

Proof. By Proposition 24, we have $\succ^{+} \supset \quad \gtrdot^{+}(=\gg)$. The relation $\gtrdot^{+} \supset \succ^{+}$holds by Proposition 17.

Theorem 25 tells the following. Although the relation above, i.e. $\gg$, is defined by $>$, which is less intuitive notion introduced for the sake of formalization and ease of computation, $\gg$ is the right notion on which we base our reasoning about the vertical arrangements of faces. The relation $\succ$ is the finest relation to compose the above relation. Taking Theorem 25 and Corollary 20 together, we
have the following. Given faces $f$ and $g$ in an AO constructed from the initial origami, $f \gg g$ can be expanded by the finite number of faces $g_{1}, \ldots, g_{n}$ such that $g_{1}(=f) \succ g_{2} \succ \cdots \succ g_{n}(=g)$.

## 4. Abstract fold from computational viewpoint

This section is devoted to the algorithmic description of fold. It is a prelude to our argument for the necessity of graph rewriting. When we construct an origami that does not have face overlapping, the operational meaning of folds can be quite simple. The fold is essentially intended to construct a reflection in the fold line. Unfold is similarly understood. In mathematical origami, which is the case in point, some studies have been made in Alperin (2000) and Ida et al. (2008). When an (abstract) origami consists of faces with non-empty superposition relations, the situation is more complex and does not admit a simple algebraic interpretation. Geometrical properties of folds are expounded in Demaine and O'Rourke (2007). However, the fold performed during the construction of an origami, as has been abstracted as an operation on discrete objects, has not been studied systematically. Having this in mind, let us analyze the abstract fold from computational viewpoint.

Computationally, an origami fold is a composite operation consisting of the following operations.
(1) Specify a fold method and the set $F$ of the faces of concern, i.e. the faces on which the origamist wants to make a fold. We can specify the fold method by one of Huzita's axioms (Huzita, 1989) or classical fold methods such as mountain and valley folds with constructed points and lines as arguments.
(2) Compute a fold line and define the associated directed line ray $r$. Through the ray, the notion of left and right of the fold line is made sense of.
(3) Compute the set $C$ of the faces that are the candidates for the face division.
(4) Divide all the faces in $C$ by the ray $r$ and classify the divided and non-divided faces according to the locations relative to $r$.
(5) Obtain the new set $\Pi$ of all the faces that constitutes the new origami.
(6) Compute the adjacency relation $\backsim$ on $\Pi$.
(7) Compute the superposition relation $\succ$ on $\Pi$.
(8) Rotate the relevant faces to the right of $r$ along $r$.
(9) Compute the new superposition relation $\succ^{\prime}$ on $\Pi$ caused by the rotation.
(10) $\left(\Pi, \backsim, \succ^{\prime}\right)$ is the new origami created by the fold.

As we saw in Section 2.3, functionally a fold is decomposed into two operations. Steps (1)- (7) constitute one operation which corresponds to the crease relation, and steps (8) and (9) constitutes the other operation corresponding to the basic fold relation. At the completion of step (7), we have a well-defined origami.

More algorithmic description in a procedural program style is given in Algorithms 2 and 3. In both Algorithms 2 and 3, we use a common algorithm RefTransR. Given a set $A \subset X$ and a binary relation $R$ on $X$, it computes the set $B$ of the elements in $X$ that are related by $R^{*}$ to the elements of the set $A$. In our case, the set $X$ is taken to be $\Pi$.

```
Algorithm 1 RefTransR
Input: \(A, R\)
Output: \(B\)
    \(B \leftarrow A\)
    while \(A \neq \emptyset\) do
        Take \(f \in A\)
        \(W \leftarrow\{g \mid g R f\} \backslash B\)
        \(B \leftarrow B \cup W\)
        \(A \leftarrow(A \backslash\{f\}) \cup W\)
    Return \(B\)
```

```
Algorithm 2 Crease
Input: \((\Pi, \backsim, \succ), F, r\)
Output: \(\left(\Pi^{\prime}, \varkappa^{\prime}, \succ^{\prime}\right)\), \(D\)
    \(C \leftarrow \operatorname{RefTransR}\left(F, \sim_{\sim \text { left }}(r)\right)\)
    \{comment \(C\) is the candidate set of the face division\}
    for all \(f \in C\) do
        Divide \(f\) and classify the divided faces
    \{comment As the result of the divide-and-classify, we obtain the set \(D\) that contains the faces to
    the right of the ray \(r\) \}
    Compute \(\sim^{\prime}\) on \(\Pi^{\prime}\)
    Compute \(\succ^{\prime}\) on \(\Pi^{\prime}\)
    Return ( \(\Pi^{\prime}, \varkappa^{\prime}, \succ^{\prime}\) ) and \(D\)
```

```
Algorithm 3 Basic fold
Input: \((\Pi, \backsim, \succ), D, r, \theta\)
Output: \(\left(\Pi^{\prime}, \varsigma^{\prime}, \succ^{\prime}\right)\)
    \(M \leftarrow \operatorname{RefTransR}\left(D, \sim_{\text {on }(r)} \cup \succ\right)\)
    \{Comment \(M\) is \(\Pi_{M}\) \}
    Rotate the faces in \(M\) by angle \(\theta\) along \(r\)
    Compute \(\succ^{\prime}\)
    Return \(\left(\Pi, \backsim, \succ^{\prime}\right)\)
```


## 5. Graph formalism for origami

The origami fold as explained in the previous sections shows that the fold is a complex operation. We need to compute the relations $\backsim$ and $\succ$. Furthermore, we need geometrical information that is abstracted away in the formulation of the abstract origami system. One of the promising approach for compromising abstraction and concretization towards the understanding of the geometrical structures of an origami and its implementation is to use graph-theoretic formalism (Ehrig et al., 2006; Schneider, 2008). In particular, we see that a labeled hypergraph is applicable to model our origami.

### 5.1. Hypergraph

Definition 26 (Hypergraph). A hypergraph is a quadruple ( $V, E, s, t$ ), where

- $V$ is the set of nodes,
- $E$ is the set of hyperedges, and
- $s, t: E \rightarrow V^{*}$ are source and target functions.

Let $\mathscr{L}_{V}$ and $\mathscr{L}_{E}$ be the label alphabets for $V$ and $E$, respectively, and $\mathbb{L}$ be the set of all the regular expressions over $\mathscr{L}_{V}$.
Definition 27 (Labeled Hypergraph). Given a pair $\mathscr{L}=\left(\mathscr{L}_{V}, \mathscr{L}_{E}\right)$ of label alphabets together with label constraints $\tau_{s}, \tau_{t}: \mathscr{L}_{E} \rightarrow \mathbb{L}$ that constrain labeling of the source and the target nodes of the hypergraph, respectively, an $\mathcal{L}$-labeled hypergraph is a 6 -tuple $\left(V, E, s, t, l_{V}, l_{E}\right)$, where

- ( $V, E, s, t$ ) is a hypergraph and
- $l_{V}: V \rightarrow \mathscr{L}_{V}$ and $l_{E}: E \rightarrow \mathscr{L}_{E}$ are labeling functions that satisfy the following labeling constraint:

$$
\begin{equation*}
\forall e \in E \quad l_{V}^{*}(s(e)) \in \tau_{s}\left(l_{E}(e)\right) \wedge l_{V}^{*}(t(e)) \in \tau_{t}\left(l_{E}(e)\right) . \tag{3}
\end{equation*}
$$

Condition (3) ensures the consistency of labeling. To see how it works, let us consider the following simple example.


Fig. 9. Hypergraph of an origami created by face division.
Example 4 (Simple Labeled Hypergraph). Let $c$ be a label of a hyperedge $e$ and $\tau_{s}(c)=c_{1} c_{2}$. Suppose that $s(e)=\left\langle v_{1}, v_{2}\right\rangle$. Then, we must have $l_{V}\left(v_{1}\right)=c_{1}$ and $l_{V}\left(v_{2}\right)=c_{2}$. We can only assign to the nodes $v_{1}$ and $v_{2}$ a label that satisfies the condition (3).

With another $\tau_{s}(c)=\left(c_{1} \mid d\right) c_{2}$, for $l_{E}\left(e^{\prime}\right)=c$ and $s\left(e^{\prime}\right)=\left\langle v_{1}^{\prime}, v_{2}^{\prime}\right\rangle$, the labeling function $l_{V}$ may be such that $l_{V}\left(v_{1}^{\prime}\right)=d$ and $l_{V}\left(v_{2}^{\prime}\right)=c_{2}$. Note that $\left(c_{1} \mid d\right) c_{2}$ as well as $c_{1} c_{2}$ are regular expressions denoting the set $\left\{c_{1} c_{2}, d c_{2}\right\}$ and the set $\left\{c_{1} c_{2}\right\}$, respectively.
Example 5 (Labeled Hypergraph of the Initial AO). We are given the label alphabets together with label constraints $\tau_{s}$ and $\tau_{t}$ as follows:

$$
\mathrm{F} \in \mathscr{L}_{V}, \mathrm{~A} \in \mathscr{L}_{E}, \tau_{s}=\left\{\mathrm{A} \mapsto \mathrm{~F}^{*}\right\}, \tau_{t}=\{\mathrm{A} \mapsto \mathrm{~F}\} .
$$

We define a graph $G$ of the initial AO $I$ as an $\mathscr{L}$-labeled graph ( $V, E, s, t, l_{V}, l_{E}$ ), where

$$
V=\left\{f_{0}\right\}, E=\{e\}, s=\left\{e \mapsto f_{0}\right\}, t=\left\{e \mapsto f_{0}\right\}, l_{E}=\{e \mapsto \mathrm{~A}\}, l_{V}=\left\{f_{0} \mapsto \mathrm{~F}\right\} .
$$

Example 6 (Graph Immediately after Face Division). We are given the label alphabets and the label constraints $\tau_{s}, \tau_{t}$ as follows:

$$
\begin{aligned}
& \mathscr{L}_{V}=\{\mathrm{F}\}, \mathscr{L}_{E}=\{\mathrm{A}, \mathrm{R}, \mathrm{~L}\} \\
& \tau_{s}=\left\{\mathrm{A} \mapsto \mathrm{~F}^{*}, \mathrm{R} \mapsto \mathrm{~F}, \mathrm{~L} \mapsto \mathrm{~F}\right\}, \tau_{t}=\{\mathrm{A} \mapsto \mathrm{~F}, \mathrm{R} \mapsto \mathrm{~F}, \mathrm{~L} \mapsto \mathrm{~F}\} .
\end{aligned}
$$

We have an $\mathcal{L}$-labeled graph $G=\left(V, E, s, t, l_{V}, l_{E}\right)$, where

$$
\begin{aligned}
& V=\left\{f_{0}, f_{1}, f_{2}\right\} \\
& E=\left\{e_{1}, e_{2}, e_{3}, e_{4}\right\} \\
& s=\left\{e_{1} \mapsto f_{0}, e_{2} \mapsto f_{0}, e_{3} \mapsto\left\langle f_{1}, f_{2}\right\rangle, e_{4} \mapsto\left\langle f_{2}, f_{1}\right\rangle\right\} \\
& t=\left\{e_{1} \mapsto f_{1}, e_{2} \mapsto f_{2}, e_{3} \mapsto f_{1}, e_{4} \mapsto f_{2}\right\} \\
& l_{E}=\left\{e_{1} \mapsto \mathrm{~L}, e_{2} \mapsto \mathrm{R}, e_{3} \mapsto \mathrm{~A}, e_{4} \mapsto \mathrm{~A}\right\} \\
& l_{V}=\left\{f_{0} \mapsto \mathrm{~F}, f_{1} \mapsto \mathrm{~F}, f_{2} \mapsto \mathrm{~F}\right\} .
\end{aligned}
$$

The hyperedge $e_{3}$ forms a cycle from $f_{1}$ to $f_{1}$, visiting the node $f_{2}$ on the way. The hyperedge $e_{4}$ also forms a cycle. The graph $G$ is shown in Fig. 9. The graph represents AO $O_{1}^{\prime}$ in Fig. 2. In the graph, the circles, rectangles and symbols after colons denote nodes, hyperedges and labels, respectively.

### 5.2. Graph term

Often graphs are drawn using diagrams. The diagrammatic representation of graphs helps perceive many of properties of graphs, and is indeed effective as long as they are fit into a manageably small space. Graphs for origami become complicated as the construction of an origami proceeds and they do not lend themselves to easy-to-understand drawing in general. Since we are interested in
graph rewriting，in addition to the diagrammatic representation that we have just seen，we need a good symbolic representation of graphs for reasoning about the graph transformation，and efficiently manipulating graphs by programs．Thus，we are guided to the following symbolic representation of nodes and edges．
Definition 28 （Edge Term of a Hyperedge）．Let $e$ be a hyperedge with $s(e)=\left\{v_{1}, \ldots, v_{m}\right\}, t(e)=$ $\left\langle w_{1}, \ldots, w_{n}\right\rangle$ ，and $l_{E}(e)=c$ ．The edge term representation of $e$ ，denoted by $\widehat{e}$ ，is a term $c\left[v_{1}, \ldots, v_{m}, w_{1}, \ldots, w_{n}\right]$ ．

Definition 29 （Node Term of a Node）．Let $v$ be a node with $l_{V}(v)=c$ ．The node term representation of $v$ ，denoted by $\widehat{v}$ ，is a term $c[v]$ ．
The edge term and node term are called graph terms，g－terms for short．We will later extend the definition of graph term to allow variables and sequence variables to occur as subterms．
Definition 30 （Graph Term of a Hypergraph）．Given an $\mathcal{L}$－labeled hypergraph $G=\left(V, E, s, t, l_{V}, l_{E}\right)$ ， graph term representation $\widehat{G}$ of $G$ is a multi－set

$$
\{\widehat{e} \mid e \in E\} \cup\{\widehat{v} \mid v \in V\} .
$$

Note that $\{\widehat{e} \mid e \in E\}$ is a multi－set and hence $\cup$ is the multi－set union；For different $e$ and $e^{\prime}$ with $s(e)=s\left(e^{\prime}\right)$ and $t(e)=t\left(e^{\prime}\right)$ ，the representations $\widehat{e}$ and $\widehat{e^{\prime}}$ are the same when their labels are the same．

Example 7 （G－Term Representation of a Hypergraph）．Let $G$ be a hypergraph given in Example 6．The g－term representation $\widehat{G}$ is

$$
\widehat{G}=\left\{\mathrm{L}\left[f_{0}, f_{1}\right], \mathrm{R}\left[f_{0}, f_{2}\right], \mathrm{A}\left[f_{1}, f_{2}, f_{1}\right], \mathrm{A}\left[f_{2}, f_{1}, f_{2}\right], \mathrm{F}\left[f_{0}\right], \mathrm{F}\left[f_{1}\right], \mathrm{F}\left[f_{2}\right]\right\} .
$$

In our application，$V$ is implicitly given，and $\mathscr{L}_{V}$ is a singleton．In such a case，we describe $\widehat{G}$ simply as $\{\widehat{e} \mid e \in E\}$ ，since the affected node terms can be inferred from the edge terms．

## 6．Graph rewriting

In this section，we present a graph rewriting system for origami．We first introduce a language $g$ for graph rewriting informally．Language $g$ is embedded in the host language of $g$ ，on which we rely for controlling the application of graph rewrite rules as well as for evaluating host functional expressions during the graph rewriting．${ }^{3}$ The syntax of the host expression is of the form $f\left[t_{1}, \ldots, t_{n}\right]$ ，and we use this syntax throughout in $g .{ }^{4}$ A basic expression $t$ in $g$ ，called term，is defined by the following grammar together with the auxiliary notion of an atomic term $a$ ：

```
\(t::=a \mid\langle\) g-term〉 | 〈host expr〉
\(a::=v|x| \underline{x}\)
\(\langle\) host expr〉::=f[t,..,t].
```

Here，$x$ denotes a variable，$\underline{x}$ a sequence variable and $v$ a graph node．In this article，we do not give any syntactic specification of $v$ apart from the fact that $v$ denotes a node of a graph．A sequence variable is used for a g－pattern（see below for the definition）such as $c[\underline{x}]$ ．〈host expr〉 means an expression of the host language．It is used during the application of graph rewrite rules，and gives fine control over pattern matching．

A g－term is extended to have variables and sequence variables as subterms，i．e．

$$
\langle\mathrm{g} \text {-term }\rangle::=c[a, \ldots, a] .
$$

A g－pattern $c[x]$ matches a g－term $c\left[s_{1}, \ldots, s_{n}\right]$ of arbitrary $n(\geqslant 0)$ arguments．Sequence variables are indispensable constituents in our language since the constructor symbol $c$ in $g$－term $c\left[s_{1}, \ldots, s_{n}\right]$ ， representing a hyperedge whose label is $c$ visiting $n$ nodes，has a flexible arity．

[^1]A g-pattern is a g-term possibly with a condition written after ";".
$\langle\mathrm{g}$-pattern $\rangle::=\langle$ g-term $\rangle\langle$ g-term $\rangle / ;\langle$ host expr $\rangle$.
The expression of the form $s / ; t$ is a conditional $g$-pattern. The conditional g-pattern is used in the context graph part of a graph rewrite rule. During pattern matching with a subgraph by a substitution $\theta$, if $t \theta$ is evaluated by the evaluator of the host language to true, $(s / ; t) \theta$ reduces to $s \theta$, and otherwise it reduces to $\perp$. We use $u$ to denote a g-pattern.

Finally, a graph in $g$ is a multi-set of g-terms subjected to the conditions for defining a graph.
Definition 31 (Graph Rewrite Rule). A graph rewrite rule (rewrite rule for short) is a triplet ( $C, L, R$ ) of multi-sets of $g$-terms, written as

$$
L /: C \rightarrow R
$$

where

- $C:=\left\{u_{1}, \ldots, u_{m}\right\}$ is a graph called a context graph,
- $L$ is a subset of $\left\{\widetilde{u_{1}}, \ldots, \widetilde{u_{m}}\right\}$, where $\widetilde{u_{i}}=s_{i}$, if $u_{i}=s_{i} / ; t_{i}$, otherwise $\widetilde{u_{i}}=u_{i}$. $L$ is called the left-hand side of the rewrite rule, and
- $R:=\left\{t_{1}, \ldots, t_{n}\right\}$ is a subgraph called the right-hand side of the rewrite rule.

In order to identify the same g-terms in $L$ and $C$, we can give a name to a g-term. For example, a name $n$ is given to the g-term $t$ in $C$ by writing $n: t$ in $C$ and refer to it as $n$ in $L$ :

$$
\{n\} /:\{g[x], n: f[x], h[x]\} \rightarrow\{f[x], f[x]\} .
$$

The occurrence of $n$ in the left-hand side of the rewrite rule refers to $f[x]$ of the context graph of the rewrite rule.
Definition 32 (Graph Rewriting). A graph $\widehat{G}$ is rewritten to $\widehat{G^{\prime}}$ by a rewrite rule $r:=L /: C \rightarrow R$, denoted by

$$
\widehat{G} \Rightarrow_{r} \widehat{G}^{\prime}
$$

if there exist $g$-terms $s_{1}, \ldots, s_{m}$, and a substitution $\theta$ such that $\left\{s_{1}, \ldots, s_{m}\right\} \subseteq \widehat{G}, C \theta=\left\{s_{1}, \ldots, s_{m}\right\}$ after the evaluation of the conditions, if any, and $\widehat{G}^{\prime}=(\widehat{G} \backslash L \theta) \cup R \theta$. The set-related notations are taken to be those for multi-sets.

The graph rewriting can be formalized as the double push out using graph production

$$
\langle C \leftarrow(C \backslash L) \rightarrow(C \backslash L) \cup R\rangle,
$$

where $C \backslash L$ is an interface, as in Ehrig et al. (2006). However, we prefer our definition of the rewrite rule from the programming language point of view. Thanks to $g$-terms, it makes clear the parts of the graph involved for rewriting and the graph rewriting becomes a simple multi-set rewriting.

Rewrite rules are combined using the following combinators (i.e. alternative, non-strict sequencing, strict sequencing and repeat) to form a composite rewrite rule. The combinators control the application of the rewrite rules. Hereafter, rewrite rule and composite rewrite rule are collectively called rewrite rules.

Rewrite rule $\rho$ is defined by the following grammar.

$$
\rho::=r\left|\rho_{1}\right| \rho_{2}\left|\rho_{1} ; \rho_{2}\right| \rho_{1} * \rho_{2} \mid\left(\text { Cond } \rho_{1} \rho_{2} \rho_{3}\right) \mid(\text { Repeat } \rho)
$$

- $r$ is a basic rewrite rule as defined in Definition 31.
- $\rho_{1} \mid \rho_{2}$ is an alternative.
- $\rho_{1} ; \rho_{2}$ is a non-strict sequencing.
- $\rho_{1} * \rho_{2}$ is a strict sequencing.
- (Cond $\rho_{1} \rho_{2} \rho_{3}$ ) is a conditional.
- (Repeat $\rho$ ) is a repetition.

We apply a rewrite rule $\rho$ to a graph $\widehat{G}$ to obtain a new graph $\widehat{G}^{\prime}$. The graph $\widehat{G}^{\prime}$ is the result of one of the following operations.
(1) The rewrite rule $\rho$ is applicable to some subgraph of $\widehat{G}$, which then is rewritten by $\rho$, and returns the new graph $\widehat{G}^{\prime}$. We denote the new graph $\widehat{G}^{\prime}$ by $\rho[\widehat{G}]$. We call this case successful rewrite.
(2) The rewrite rule $\rho$ is applicable to no subgraph of $\widehat{G}$, and it returns the new graph $\widehat{G}^{\prime}=\widehat{G}$. We call this case unsuccessful rewrite.
To describe the semantics of the graph rewriting, we need to distinguish the above two cases since by mere observation of the resulting graph we cannot tell whether the graph rewriting has been successful or not. We, therefore, adopt continuation passing style of semantic treatment. We use two continuations as the parameters to the graph rewriting: continuation $v$ to be obeyed when the rewrite is successful and the continuation $\kappa$ to be obeyed when the rewrite is unsuccessful.

Then, we have the following semantic equations to describe the graph rewriting.

$$
\begin{align*}
& r G \kappa v= \begin{cases}v(r[G]) & \text { if the rewrite is successful } \\
\kappa G & \text { if the rewrite is unsuccessful }\end{cases}  \tag{4}\\
& \left(\rho_{1} \mid \rho_{2}\right) G \kappa v=\rho_{1} G\left(\lambda G^{\prime} . \rho_{2} G \kappa v\right) v  \tag{5}\\
& \left(\rho_{1} ; \rho_{2}\right) G \kappa v=\rho_{1} G \kappa\left(\lambda G^{\prime} . \rho_{2} G^{\prime}\left(\lambda G^{\prime} . \kappa G\right) v\right)  \tag{6}\\
& \left(\rho_{1} * \rho_{2}\right) G \kappa v=\rho_{1} G\left(\lambda G^{\prime} . \rho_{2} G \kappa v\right)\left(\lambda G . \rho_{2} G v v\right)  \tag{7}\\
& \text { (Cond } \left.\rho_{1} \rho_{2} \rho_{3}\right) G \kappa v=\rho_{1} G\left(\lambda G^{\prime} . \rho_{3} G \kappa v\right)\left(\lambda G^{\prime} . \rho_{2} G \kappa v\right)  \tag{8}\\
& \text { (Repeat } \rho) G \kappa v=\rho G \kappa(\lambda G . \text { (Repeat } \rho) G v v) . \tag{9}
\end{align*}
$$

The semantic equation (5) for the alternative states the following. We first apply rule $\rho_{1}$ to $\widehat{G}$. If the rewrite is successful, the continuation $v$ is applied to the result $\rho_{1}[\widehat{G}]$ of rewriting of $G$ by $\rho_{1}$. If the rewrite is unsuccessful, we apply rule $\rho_{2}$ to $\widehat{G}$ with the continuations $\kappa$ and $\nu$. The semantic equations (6) and (7) for the sequencing rules show that the applications of the rules $\rho_{1}$ and $\rho_{2}$ are performed sequentially from left to right. In the non-strict sequencing, $\rho_{2}$ is not applied if the rewrite by $\rho_{1}$ is unsuccessful, and it immediately completes the rewrite unsuccessfully. In the strict sequencing, even if the rewrite by $\rho_{1}$ is unsuccessful, the rewrites continue with $\widehat{G}$, and the rewrite of $\widehat{G}$ by $\rho_{2}$ is performed. The rewrite of $\widehat{G}$ by $\rho_{1} * \rho_{2}$ completes successfully either (including both) of rewrites by $\rho_{1}$ and $\rho_{2}$ are successful. Otherwise, the rewrite is unsuccessful. Thus, $\left(r_{1} * r_{2}\right) \widehat{G} \kappa v$ evaluates to one of the following: $v\left(r_{2}\left[r_{1}[\widehat{G}]\right]\right), v\left(r_{2}[\widehat{G}]\right), v\left(r_{1}[\widehat{G}]\right)$ and $\kappa \widehat{G}$, whereas $\left(r_{1} ; r_{2}\right) \widehat{G} \kappa v$ evaluates to one of the following: $v\left(r_{2}\left[r_{1}[\widehat{G}]\right]\right)$ and $\kappa \widehat{G}$. The semantic equation (8) states that if $\rho_{1}$ rewrites $\widehat{G}$ successfully then the resulting graph is $\rho_{2}[\widehat{G}]$, else it is $\rho_{3}[\widehat{G}]$. The semantic equation (9) states the following: (Repeat $\rho$ ) rewrites $\widehat{G}$ successfully if there exists an $n \geqslant 1$ such that $\rho^{n}$ rewrites $\widehat{\widehat{G}}$ successfully and $\rho^{n+1}$ rewrites $\widehat{G}$ unsuccessfully, where $\rho^{n}$ denotes $\underbrace{\rho ; \ldots ; \rho}_{n}$. (Repeat $\rho$ ) rewrites $\widehat{\widehat{G}}$ unsuccessfully if $\rho$ rewrites $\widehat{G}$ unsuccessfully.

## 7. Fold as graph rewriting

We are now ready to describe the fold explained in Section 4 in graph rewriting framework. We follow closely Algorithms Crease (Algorithm 2) and Basic fold (Algorithm 3) and describe how the graph representing an origami is transformed. In the following, Section 7.1 explains step 4 , Section 7.2 step 6, and Section 7.3 step 7 of Algorithm Crease. Section 7.4 explains steps 3 and 4 of Algorithm Basic fold.

### 7.1. Face division

We consider face division $f \rightarrow_{r}\left(f_{1}, f_{2}\right)$. An example of the graph obtained by the face division was given in Fig. 9. We will discuss the face division in general cases. Suppose that face $f$ is surrounded by faces $v_{1}, \ldots, v_{n}$ in this order, and that ray $r$ divides the faces $v_{1}, f$ and $v_{i}$. We transform the graph as follows.
(1) Construct nodes $f_{1}$ and $f_{2}$.


Fig. 10. Node changes after face divisions.
(2) Construct the hyperedge $e_{1}$ that connects $f$ with $f_{1}$ and $e_{2}$ that connects $f$ with $f_{2}$. We label the hyperedge $e_{1}$ by L ( L for Left) and $e_{2}$ by R ( R for Right).
(3) Construct the hyperedges $e_{3}$ and $e_{4}$ starting from $f_{1}$ and from $f_{2}$, respectively. We have $s\left(e_{3}\right)=$ $\left\langle f_{1}, v_{1}, \ldots, v_{i}, f_{2}\right\rangle, t\left(e_{3}\right)=f_{1}, s\left(e_{4}\right)=\left\langle f_{2}, v_{i}, \ldots, v_{n}, v_{1}, f_{1}\right\rangle$ and $t\left(e_{4}\right)=f_{2}$. We label those hyperedges A (A for Adjacency).
Let $\widehat{G}$ be the g-term of a graph before the division of the face $f$. The g-term $\widehat{G^{\prime}}$ of the graph after the division is

$$
\left\{\mathrm{L}\left[f, f_{1}\right], \mathrm{R}\left[f, f_{2}\right], \mathrm{A}\left[f_{1}, v_{1}, \ldots, v_{i}, f_{2}, f_{1}\right], \mathrm{A}\left[f_{2}, v_{i}, \ldots, v_{n}, v_{1}, f_{1}, f_{2}\right], \mathrm{F}\left[f_{1}\right], \mathrm{F}\left[f_{2}\right]\right\} \cup \widehat{\mathrm{G}}
$$

The label A in $\mathrm{A}\left[x_{1}, \ldots, x_{n}\right]$ is the realization of the adjacency relation. The intended meaning of $\mathrm{A}\left[x_{1}, \ldots, x_{n}\right]$ is that $x_{1} \backsim x_{2}, \ldots, x_{1} \backsim x_{n-1}$. But at this point, the relations is transient since some of the faces in $\left\{x_{2}, \ldots, x_{n-1}\right\}$ may be divided later during the face division. We will discuss about this in the next subsection. The label R in $\mathrm{R}\left[x_{1}, x_{2}\right]$ indicates the relation that $x_{1}$ is the right (w.r.t. $r$ ) part sub-face of $x_{2}$. This relation is introduced temporarily during the graph rewriting, and the R-labeled hyperedges will be deleted (garbage collected) after the graph construction of each step of the origami construction is completed. The label L is used similarly.

We have two special cases that we need to consider besides the above. The first case is that either $f_{1}$ or $f_{2}$ is empty. In this case, the node corresponding to the empty face is not constructed. For example, if $f_{1}$ is empty, we have $f_{2}=f$ and the hyperedge $e_{2}$ only with $s\left(e_{2}\right)=t\left(e_{2}\right)=f$. The other case is that the ray passes through the vertex (vertices) of the face $f$. In both cases, the construction of $\widehat{G^{\prime}}$ is straightforward.

### 7.2. Computation of adjacency relation

In order to complete the computation of the adjacency relation, the subgraph constructed at the face division step has to be traversed again to update the nodes on the hyperedges. Some of the other faces have been divided later during the face division. The constructed hyperedges still connect to those nodes of the previous non-divided faces. We need to update those hyperedges by the traversal of the graph using the following rewrite rules:

$$
\begin{align*}
& \rho_{1}:=\{n\} /:\left\{\mathrm{L}\left[f, f_{1}\right], n: \mathrm{A}\left[f_{1}, \underline{x}\right], \mathrm{L}\left[g, g_{1}\right] / ;\left(g \neq g_{1} \wedge g \in\{\underline{x}\}\right)\right\} \mapsto \mathrm{A}\left[f_{1}, \underline{x}\right]\left\{g \mapsto g_{1}\right\}  \tag{10}\\
& \rho_{2}:=\{n\} /:\left\{\operatorname{R}\left[f, f_{1}\right], n: \operatorname{A}\left[f_{1}, \underline{x}\right], \mathrm{R}\left[g, g_{1}\right] / ;\left(g \neq g_{1} \wedge g \in\{\underline{x}\}\right)\right\} \mapsto \mathrm{A}\left[f_{1}, \underline{x}\right]\left\{g \mapsto g_{1}\right\}  \tag{11}\\
& \rho:=\left(\text { Repeat } \rho_{1}\right) *\left(\text { Repeat } \rho_{2}\right) .
\end{align*}
$$

The term $\mathrm{A}\left[f_{1}, \underline{x}\right]\left\{g \mapsto g_{1}\right\}$ is the application of the substitution $\left\{g \mapsto g_{1}\right\}$ to a term $\mathrm{A}\left[f_{1}, \underline{\chi}\right]$. Note that we omit the g-terms for the nodes in all the subgraphs involved.
Example 8 (Update of Hyperedges After Face Division). Suppose, we have a face $b$ surrounded by the faces $a_{1}, a_{2}, a_{3}$ as shown in Fig. 10(left). The face division $b \mapsto_{r}\left(b_{1}, b_{2}\right)$ is shown in Fig. 10(right).

At the time of the face division, we have $\mathrm{A}\left[b_{1}, a_{3}, a_{1}, b_{2}, b_{1}\right]$ and $\mathrm{A}\left[b_{2}, a_{1}, a_{2}, a_{3}, b_{1}, b_{2}\right]$ that represent the hyperedges $e_{1}$ and $e_{2}$ satisfying $s\left(e_{1}\right)=\left\langle b_{1}, a_{3}, a_{1}, b_{2}\right\rangle, t\left(e_{1}\right)=b_{1}$, and $s\left(e_{2}\right)=$ $\left\langle b_{2}, a_{1}, a_{2}, a_{3}, b_{1}\right\rangle, t\left(e_{2}\right)=b_{2}$. Later, we have $a_{1} \rightarrow\left(a_{11}, a_{12}\right)$ and $a_{3} \rightarrow\left(a_{31}, a_{32}\right)$. The update of the hyperedges is achieved by rewriting the g-terms $\mathrm{A}\left[b_{1}, a_{3}, a_{1}, b_{2}, b_{1}\right]$ and $\mathrm{A}\left[b_{2}, a_{1}, a_{2}, a_{3}, b_{1}, b_{2}\right]$, to $\mathrm{A}\left[b_{1}, a_{31}, a_{11}, b_{2}, b_{1}\right]$ and $\mathrm{A}\left[b_{2}, a_{12}, a_{2}, a_{32}, b_{1}, b_{2}\right]$, respectively.

The instantiated rule from rule (10), i.e. the rule after applying the substitution formed during the pattern matching of the rewrite rule with the graph,

$$
\{n\} /:\left\{\mathrm{L}\left[b, b_{1}\right], n: \mathrm{A}\left[b_{1}, a_{3}, a_{1}, b_{2}, b_{1}\right], \mathrm{L}\left[a_{3}, a_{31}\right]\right\} \rightarrow\left\{\mathrm{A}\left[b_{1}, a_{31}, a_{1}, b_{2}, b_{1}\right]\right\}
$$

is used to update the g-term $\mathrm{A}\left[b_{1}, a_{3}, a_{1}, b_{2}, b_{1}\right]$ to $\mathrm{A}\left[b_{1}, a_{31}, a_{11}, b_{2}, b_{1}\right]$. Similarly, $\mathrm{A}\left[b_{2}, a_{1}, a_{2}, a_{3}, b_{1}\right.$, $\left.b_{2}\right]$ is rewritten to $\mathrm{A}\left[b_{2}, a_{12}, a_{2}, a_{32}, b_{1}, b_{2}\right]$ by the rewrite rule (11).

### 7.3. Computation of superposition relation

The superposition relation is computed twice during the fold operation: one induced by the face division and the other by the face rotation. Although both computations may appear different, they are based on the same algorithmic pattern. Namely, in both computations the basic operations are the insertion of a new face to the peaks (to be defined shortly) of the graph and the transitive reduction of the graph.

In order to describe fully these operations, we use the following definitions and notations. Let $V$ be a set and $R$ be a binary relation on $V$. A pair $(V, R)$ is identified as a directed graph. ${ }^{5}$ Let us further stipulate that $G=(V, R)$ is a directed acyclic graph. A graph $G^{T}=\left(V, R^{+}\right)$is called a transitive closure of the graph $G$. Let $G^{-}$be a directed acyclic graph with a minimum number of edges satisfying $G^{T}=\left(G^{-}\right)^{T}$. The graph $G^{-}$is called a transitive reduction of the graph $G$. In the following, we consider $G=(\Pi, \gtrdot)$. It is easy to see that $G^{T}=(\Pi, \gg)$ and $G^{-}=(\Pi, \succ)$ and is unique. We call a node $f$ in $\Pi$ of $G$ a peak iff there exists no node $g$ in $\Pi$ such that $g>f$. The set of peaks of a graph $G$ is denoted by $\mathcal{K}_{G}$.

From a given $O_{i}=\left(\Pi_{i}, \varkappa_{i}, \succ_{i}\right)$ of an AO construction $I ๑^{*} O_{i}$, we can define a graph $\left(\Pi_{i}, \gtrdot_{i}\right)$. As $\gtrdot$ is defined inductively on the construction of AOs, we can construct $\gtrdot_{i+1}$ from $\gtrdot_{i}$. Then, we take the transitive reduction of $\left(\Pi_{i+1},>_{i+1}\right)$ and finally we extract $\succ_{i+1}$ from the transitive reduction. The known algorithm for the transitive reduction of a directed acyclic graph $G=(V, R)$ can be as low as $O\left(n^{3}\right)$, where $n$ is the cardinality of $V$ (Gries et al., 1989). Actually, it suffices to construct a graph ( $\Pi_{i+1}, R$ ) with a relation $R$ such that $\succ_{i+1} \subset R \subset \gtrdot_{i+1}$. The crucial observation here is that if $f \gtrdot g$, then for any $h$ such that $g \gtrdot^{+} h$, we have $\neg(f \succ h)$. Therefore, once the edge representing $f \gtrdot g$ is established, we do not have to consider the possible edges representing $f \gtrdot h$ because those edges would be unnecessary to construct the transitive reduction.

We define the above algorithm with the set of graph rewrite rules in the following way. Suppose we have a unique g-term NewNode[ $f]$ in $\widehat{G}$. We define the graph rewrite rule:

$$
\operatorname{AddS}(h):=\{ \} /:\{\operatorname{NewNode}[f] / ; f \asymp h\} \rightarrow\{\mathrm{S}[f, h]\} .
$$

The rewrite rule states that we can create an S-labeled edge from $f$ to $h$ when $f \asymp h$. Note, however, that some of the S-labeled edges thus constructed may be deleted during the subsequent transitive reduction. The remaining ones after the transitive reduction are the edges representing the superposition relation. The node $f$ is to be added to the peaks of $G$. To find the node to which we construct an edge from $f$ is a simple graph traversal. For this purpose, we incorporated the graph traversal strategy Trav in our language $\mathcal{g}$. The semantics of Trav can be described by the following semantic equation.

Trav $\rho\} G \kappa v=\nu G$
Trav $\rho(\{e\} \cup e s) G \kappa v=\rho e G\left(\lambda G\right.$. Trav $\rho($ Succ $\left.e G) G v^{\prime} v^{\prime}\right) v^{\prime} \quad$ where $v^{\prime}=\lambda G$. Trav $\rho$ es $G v v$ and (Succ $e G$ ) computes the set of nodes $x$ of $G$ such that $e \succ x$.

Note that (Succ eG) finds the set of successor nodes using $\succ$ rather than $>$, since any node connected by $>$ from $e$ can be reached by multiple edges of $\succ$ from $e$ by Proposition 24. Let $\operatorname{Tr}(G)$ be a function

[^2]

Fig. 11. Superposition relation after face division.


Fig. 12. Insertion of a superposition hyperedge.
to compute the transitive reduction of a graph $G$. Then the following program, receiving a graph $G$, returns the desired graph.

Trav AddS $\mathcal{K}_{G} G \kappa \operatorname{Tr}$
Example 9 (Superposition After Making a Crease). We consider $0=(\Pi, \backsim, \succ) \xrightarrow{m} O^{\prime}=\left(\Pi^{\prime}, \varsigma^{\prime}, \succ^{\prime}\right)$ as shown in Fig. 11. We see that $\Pi=\{f, g\}, \backsim=\{f, g\}$ and $\succ=\{f, g\}$. By the face division, we have $f \hookrightarrow\left(f_{1}, f_{2}\right)$ and $g \hookrightarrow\left(g_{1}, g_{2}\right)$. Whether or not $f_{1} \gtrdot^{\prime} g_{1}$ holds in $O^{\prime}$ depends on whether faces $f_{1}$ and $g_{1}$ overlap. In the case of the fold along $r_{1}$, we have $f_{i} \gtrdot^{\prime} g_{i}$ for $i=1,2$, but in the case of the fold along $r_{2}$, neither $f_{1} \gtrdot^{\prime} g_{1}$ or $g_{1} \succ \gtrdot^{\prime} f_{1}$ holds. Let us consider the latter case further. Fig. 12 depicts a subgraph of the graph representing $O^{\prime}$. In $O^{\prime}=\left(\Pi^{\prime}, \curvearrowleft^{\prime}, \succ^{\prime}\right), \Pi^{\prime}=\left\{f_{1}, f_{2}, g_{1}, g_{2}\right\}, \backsim=\left\{\left(f_{1}, f_{2}\right),\left(g_{1}, g_{2}\right),\left(f_{2}, g_{2}\right)\right\}$ and $\succ=\left\{\left(f_{2}, g_{2}\right)\right\}$. The hyperedge $e_{1}$ is labeled $L$ since the $f_{1}$ is to the left of $f$, and the $e_{2}$ labeled R. Similarly, $e_{3}$ and $e_{4}$ are labeled L and R , respectively. The hyperedge $e_{5}$ is labeled S since $f \succ g$. The hyperedge $e_{6}$ is added. This hyperedge is labeled S , since they realize the superposition relation after the face division. In the figure, the other incoming edges of the A-labeled hyperedges are omitted.

### 7.4. Computation of superposition relation induced by the rotation

The final stage of the fold is the rotation of faces. It consists of steps 3 and 4 of Algorithm Basic fold (Algorithm 3). Prior to the face rotation, we check the foldability. Namely, we check whether the fold line passes through the interior of a face. If true, we cannot make a fold. The rotation at step 3 induces the changes in the coordinates of the vertices of the moved faces. This invokes numerical computation of the coordinates, on one hand, and symbolic computation of the reflection relation between the vertices before and after the rotation, on the other. These computations do not change the structure of the graph. We construct S-labeled hyperedges using the rewrite rule Trav explained in Section 7.3 for finding the the pair of faces that should be connected by S-labeled hyperedges. The algorithm is similar to the one for step 7 of Algorithm Crease. Finally, we take the transitive reduction of the constructing graph.


Fig. 13. Origami after crease.


Fig. 14. Origami after basic fold.


Fig. 15. Graph of origami of Fig. 13.
Example 10 (Superposition by Rotation). Fig. 13 shows the origami after making creases. The ray $r$ corresponding to the fold line runs from lower right to upper left. The faces on the base layer of the origami have been divided by the ray $r$ into faces $f$ and $a$. At this step, the origami consists of faces $a, b, c, d, f$ and $g$. We see that the faces $a, b, c$ and $d$ are to the right of $r$, and the faces $f$ and $g$ to the left of $r$. Fig. 14 shows the result of the rotation along $r$. Face $g$ superposes face $f$. Faces $b$ and $c$ superpose $a$. Face $d$ superposes $b$.

Fig. 15 shows the graph of the origami of Fig. 13. The rotation induces the graph transformation from the graph of Fig. 15 to that of Fig. 16. The newly added S-labeled hyperedges are $e_{5}, e_{6}, e_{7}, e_{8}$ and $e_{9}$. For simplicity, we omit the hyperedges of the other labels.

## 8. Conclusions

We have presented an abstract model for origami. Central to the modeling is the abstraction of fold. The abstraction of fold led to graph-theoretic modeling of an origami and transformation of the graph


Fig. 16. Graph of origami of Fig. 14.
representing the origami. By this formalism, we are able to rigorously construct an origami and reason about the process of construction of the origami as well as the geometrical properties of constructed origami. Furthermore, it has been shown that the graph-theoretic formalism has the advantage of separating domains of discourse into pure combinatorial domain and geometrical domain $\mathcal{R} \times \mathcal{R}$.

We have also presented a language of graph rewriting. The language enables us to describe the process of graph transformation algebraically. Our formalism follows closely that of algebraic and categorical graph theories.

The graph contains necessary information to explore other possible methods of origami constructions. We are thus in a position to tackle challenging problems such as of discovering a new construction given an origami shape, and of discovering a new origami method that has certain geometrical properties employing various AI techniques.

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    2 The word ori-gami, meaning ori (fold) and gami (paper), is used in two ways in this article as is customary in Japanese. The former is the art of paper fold (used as an uncountable noun) and the other is a sheet of paper (used as a countable noun).

[^1]:    3 To be more specific，in our implementation we use Mathematica for the host language．
    ${ }^{4}$ We use infix notation for commonly used functions，however．

[^2]:    5 In this subsection, in order to explain the essential idea of the computation of the superposition, we employ an ordinary graph. Actual implementation is done in the labeled hypergraphs that have been discussed so far.

