

# Small amplitude limit cycles for the polynomial Liénard system ${ }^{\text {* }}$ 

Maciej Borodzik, Henryk Żołądek*<br>Institute of Mathematics, University of Warsaw, ul. Banacha 2, 02-097 Warsaw, Poland

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A R T I C L E I N F O
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## Article history:

Received 1 October 2007
Revised 2 April 2008
Available online 15 August 2008

## MSC:

primary 45C05
secondary 37G15

## Keywords:

Liénard system
Limit cycles


#### Abstract

We estimate for the maximal number of limit cycles bifurcating from a focus for the Liénard equation $\ddot{x}+f(x) \dot{x}+g(x)=0$, where $f$ and $g$ are polynomials of degree $m$ and $n$ respectively. These estimates are quadratic in $m$ and $n$ and improve the existing bounds. In the proof we use methods of complex algebraic geometry to bound the number of double points of a rational affine curve.


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## 1. The results

Consider the Liénard vector field

$$
\begin{equation*}
\dot{x}=y-F(x), \quad \dot{y}=-G^{\prime}(x), \tag{1.1}
\end{equation*}
$$

where $F$ and $G$ are polynomials of degree $m+1$ and $n+1$ respectively. It is related with the second order Liénard equation via the formulas $f(x)=F^{\prime}(x), g(x)=G^{\prime}(x)$. The principal problem concerning the system (1.1) is to find a maximal number $H(m, n)$ of its limit cycles (a special case of the Hilbert's 16 th problem). In this paper we study a weaker problem, we ask about the number of small limit cycles.

[^0]We assume that the origin $x=y=0$ is a singular point of the center or focus type. Therefore

$$
\begin{equation*}
F(x)=a_{1} x+\cdots+a_{m+1} x^{m+1}, \quad G(x)=b_{2} x^{2}+\cdots+b_{n+1} x^{n+1} \tag{1.2}
\end{equation*}
$$

where $a_{1}^{2}<8 b_{2}$. We can also assume that

$$
\begin{equation*}
b_{2}=1 \tag{1.3}
\end{equation*}
$$

When we introduce the local analytic variable

$$
u=\sqrt{G(x)}=x+\cdots,
$$

then the system (1.1) becomes orbitally equivalent to

$$
\begin{equation*}
\dot{u}=y-\Phi(u), \quad \dot{y}=-2 u, \quad \Phi=c_{1} u+c_{2} u^{2}+\cdots \tag{1.4}
\end{equation*}
$$

Here the series

$$
\begin{equation*}
X=c_{1} Y^{1 / 2}+c_{2} Y+c_{3} Y^{3 / 2}+\cdots \tag{1.5}
\end{equation*}
$$

is the Puiseux expansion at the point $X=Y=0$ of the curve

$$
\begin{equation*}
C: \quad X=F(x), \quad Y=G(x) . \tag{1.6}
\end{equation*}
$$

It is well known, see [3], that the system (1.1) (equivalently, the system (1.4)) has center at the origin if and only if $c_{1}=c_{3}=\cdots=0$, i.e. $\Phi(u)=\widetilde{\Phi}\left(u^{2}\right)$ is an even function. From the algebraic point of view this means that the curve (1.6) is multiply covered (or non-primitive). By the Lüroth theorem (see [7]) we have $F(x)=\widetilde{F} \circ \omega(x), G(x)=\widetilde{G} \circ \omega(x)$ for a polynomial $\omega(x)=x^{2}+\cdots$. From the dynamical point of view this means that the system (1.4) is time-reversible and the system (1.1) is rationally reversible, i.e. it can be pushed forward via the map $(x, y) \rightarrow(\omega(x), y)$.

The coefficients $c_{1}, c_{3}, c_{5}, \ldots$ are called the essential Puiseux quantities of the singularity $X=Y=0$ of the curve $C$ (see [1]). They are related with the Poincaré-Lyapunov quantities $g_{1}, g_{3}, \ldots$, which appear in the Taylor expansion of the Poincaré return map

$$
\begin{equation*}
r \rightarrow P(r)=r+g_{1} r(1+\cdots)+g_{3} r^{3}(1+\cdots)+\cdots, \quad r \rightarrow 0^{+} \tag{1.7}
\end{equation*}
$$

from the section $\{(x, y)=(r, 0): r \geqslant 0)\}$ to itself. Namely, $g_{j}$ are proportional to $c_{j}$ with coefficients depending only on $j$. We refer the reader to [5] for details.

Since the fixed points of the map (1.7) correspond to the limit cycles of the Liénard vector field, the essential Puiseux quantities of the curve $C$ become responsible for the small amplitude limit cycles of the system (1.1).

The quantities $c_{j}$ and $g_{j}$ depend on the coefficients $a_{k}$ and $b_{l}$ in the polynomials $F$ and $G$ (see (1.2)). In fact, they are polynomials in $a=\left(a_{1}, \ldots, a_{m+1}\right)$ and $b=\left(b_{3}, \ldots, b_{n+1}\right)$, e.g. for $b_{2}=1$. So the expansion (1.6) varies with varying ( $a, b$ ). This variation results in bifurcation of fixed points of the map $P(r)$ from the point $r=0$ (the generalized Hopf bifurcation). For instance, when $g_{2 v+1} \neq 0$ and the coefficients $g_{1}, g_{3}, \ldots, g_{2 v-1}$ vary independently, then they can be chosen such that either

$$
\begin{align*}
& 0<g_{1} \ll-g_{3} \ll g_{5} \ll \cdots \ll g_{2 v+1}, \quad \text { or } \\
& 0<-g_{1} \ll g_{3} \ll-g_{5} \ll \cdots<g_{2 v+1} . \tag{1.8}
\end{align*}
$$

Thus one finds exactly $\nu$ limit cycles of small amplitude.

Since $g_{j}(a, b)$ are real polynomials, one cannot ensure free choice of signs, like in (1.8) (although the functions $g_{j}$ may be independent).
C. Christopher and S. Lynch in [5] introduced the following quantities:
$\widehat{H}(m, n)$-the maximal number of limit cycles which can bifurcate from the origin;
$H^{*}(m, n)$-the maximal cyclicity of the focus at $x=y=0$, i.e. $\max \left\{v: c_{1}=c_{3}=\cdots=c_{2 v-1}=0 \neq\right.$ $\left.c_{2 v+1}\right\} ;$
$\widehat{H}_{\mathbb{C}}(m, n)$-the maximal number of limit cycles bifurcating from the origin in the complex sense, i.e. $\frac{1}{2} \times$ maximal number of zeroes $r_{i} \neq 0$ of the function $P(r)-r$ for $r \in(\mathbb{C}, 0)$ (counted with multiplicities);
$H_{\mathbb{C}}^{*}(m, n)$-the maximal cyclicity of $x=y=0$ in the complex sense.
In the definitions of $\widehat{H}_{\mathbb{C}}(m, n)$ and $H_{\mathbb{C}}^{*}(m, n)$ one assumes complex coefficients $a_{i}, b_{j}$ and considers the complex foliation defined by $(1.1)$ in $\left(\mathbb{C}^{2},(0,0)\right)$.

We have the following simple relations

$$
\begin{equation*}
\widehat{H}(m, n) \leqslant H^{*}(m, n) \leqslant H_{\mathbb{C}}^{*}(m, n)=\widehat{H}_{\mathbb{C}}(m, n) . \tag{1.9}
\end{equation*}
$$

In [4] Cristopher and Lloyd proved the general inequality

$$
\begin{equation*}
H_{\mathbb{C}}^{*}(m, n) \leqslant \frac{1}{2} m n . \tag{1.10}
\end{equation*}
$$

In the proof they used the Bezout theorem for estimating the number of finite solutions of the following system

$$
\begin{equation*}
\frac{F(x)-F\left(x^{\prime}\right)}{x-x^{\prime}}=\frac{G(x)-G\left(x^{\prime}\right)}{x-x^{\prime}}=0 . \tag{1.11}
\end{equation*}
$$

In [5] Christopher and Lynch stated several conjectures concerning the above quantities. To formulate them we introduce the space $\mathcal{X}$ of curves of the form (1.6) with $F, G$ like in (1.2), thus $\mathcal{X} \simeq \mathbb{C}^{m+n+1}$. This space is acted on by a group $\mathcal{G}$ of equivalences of curves, generated by:

- rescalings $x \rightarrow \alpha x, X \rightarrow \beta X, Y \rightarrow \gamma Y$;
- elementary Cremona transformations $X \rightarrow X+$ const $\cdot Y^{j}, 1 \leqslant j \leqslant[(m+1) /(n+1)]$, if $n \leqslant m$; or of the form $Y \rightarrow Y+$ const $\cdot X^{j}$ if $m<n$.

These changes have no influence on the property of vanishing of successive coefficients $c_{2 j-1}$. Therefore the equations $c_{1}=c_{3}=\cdots=c_{2 v-1}=0$ can be regarded as equations on the quotient space $\mathcal{X} / \mathcal{G}$. They define varieties in $\mathcal{X}$ composed of whole orbits of the action of $\mathcal{G}$ on $\mathcal{X}$.

If $n \leqslant m$ and $\frac{m+1}{n+1} \notin \mathbb{Z}$ then there exists one (exceptional) orbit, which contains the quasihomogeneous curve $F(x)=x^{m+1}, G(x)=x^{n+1}$, of dimension $2+\left[\frac{m+1}{n+1}\right]$; other orbits have dimension $3+\left[\frac{m+1}{n+1}\right]$. If $(m+1)=k(n+1)$ then the orbit of the curve $F(x)=x^{m+1}, G(x)=x^{n+1}$ has dimension $1+k$ and other orbits have dimension $3+k$. Also for $m<n$ there is such division.

Since we assume $b_{2} \neq 0$, the first case for $n \leqslant m$ (i.e. with quasi-homogeneous curve) occurs when $n=1$ (and $G(x)=x^{2}$ ). But here $c_{j}=a_{j}$ and the problem is elementary: we have $\widehat{H}(m, 1)=$ $\widehat{H}_{\mathbb{C}}(m, n)=\left[\frac{m}{2}\right]$, where [•] denotes the integer part. When $m, n \geqslant 2$ we have the following

Conjecture 1. (See [5].)

1. $\widehat{H}_{\mathbb{C}}(m, n)=\widehat{H}_{\mathbb{C}}(n, m)=m+n-2-\left[\frac{m+1}{n+1}\right]$ for $2 \leqslant n \leqslant m$;
2. $\widehat{H}(m, n)=\widehat{H}(n, m)$;
3. $H^{*}(m, n)=H^{*}(n, m)$.

Remark 1. In [5] one finds the following conjectured bounds $\widehat{H}_{\mathbb{C}}(m, n)=\left[\frac{n(m+2)}{n+1}\right]+n-3$ for $2 \leqslant n<m$ (which agrees with the above) and $\widehat{H}_{\mathbb{C}}(n, n)=2 n-4+\left[\frac{2}{n}\right]$ (which is stronger than above).

Christopher and Lynch proved the formula $\widehat{H}(m, 2)=\left[\frac{2 m+1}{3}\right]=m-\left[\frac{m+1}{3}\right]$, using some Petrov's [15] ideas. They also proved that $\widehat{H}(m, 3)=2\left[\frac{2(m+2)}{8}\right]$ when $3 \leqslant m \leqslant 50$ and $\widehat{H}_{\mathbb{C}}(m, 3)=\left[\frac{3(m+2)}{4}\right]$ when $6 \leqslant m \leqslant 50$. They found examples where $\widehat{H}_{\mathbb{C}}(m, 3)>\widehat{H}(m, 3)$ (e.g. $\widehat{H}_{\mathbb{C}}(7,3)=7$ and $\left.\widehat{H}(7,3)=6\right)$.

Also other computer calculations confirm the above conjecture.
We do not prove the Christopher-Lynch conjecture in this paper (although initially we aimed at $i t)$. We are able to show the following quadratic bounds for $H_{\mathbb{C}}^{*}(m, n)$. Introduce the number

$$
\begin{equation*}
\delta_{\max }=\delta_{\max }(m, n)=\frac{1}{2}(m n-\operatorname{gcd}(m+1, n+1)+1) ; \tag{1.12}
\end{equation*}
$$

in the next section we interpret $\delta_{\max }$ as the maximal number of double points of a curve of the form (1.6). The following result slightly improves the Christopher-Lloyd bound and is proved in the next section.

Theorem 1. If $m, n \geqslant 2$ then $H_{\mathbb{C}}^{*} \leqslant \delta_{\max }-1$.
In the next result we replace the factor $\frac{1}{2}$ in (1.10) and (1.12) with $\frac{1}{4}$. We prove it in Section 3 .
Theorem 2. If $m, n \geqslant 2$ and the curve $C$ has one-branch singularity at $X=Y=0$ then

$$
H_{\mathbb{C}}^{*} \leqslant \frac{1}{4}(m n+3 m+3 n+1)
$$

Remark 2. The bound from Theorem 2 still holds true when more than one branches of $C$ go through $X=Y=0$. However the proof is more involved. Namely, the proof of Lemma 7 below becomes much more technical.

## 2. Double points of a curve via a Hamiltonian vector field

If $A \subset\left(\mathbb{C}^{2}, 0\right)$ is a germ of holomorphic curve defined by $H(X, Y)=0$ then the (complex) Hamiltonian vector field

$$
V_{H}=H_{Y}^{\prime} \partial_{X}-H_{X}^{\prime} \partial_{Y}
$$

is tangent to $A$. Below we shall regard $V_{H}$ as a real vector field in $\mathbb{R}^{4}$ (i.e. with real time). One can check that the real field $V_{H}$ is also Hamiltonian with $\operatorname{Re} H$ as the Hamilton function, but with respect to the symplectic structure given by $d \operatorname{Re} X \wedge d \operatorname{Re} Y-d \operatorname{Im} X \wedge d \operatorname{Im} Y$.

We denote $W:=\left.V_{H}\right|_{A}$. If 0 is an isolated singular point of $A$, then we consider the normalization $N: \widetilde{A} \rightarrow A$; thus each topological component $\widetilde{A}_{j}, j=1, \ldots, r$ of $\widetilde{A}$ (preimage of an analytic component $A_{j}$ of $A$ ) is a disc. The pull-back $\widetilde{W}:=N^{*} W=\left(N_{*}\right)^{-1} W \circ N$ of the vector field $W$ is a vector field on the smooth manifold $\widetilde{A}$ with isolated equilibrium points $p_{j} \in N^{-1}(0), j=1, \ldots, r$. Thus one can define the indices $i_{p_{j}} \widetilde{W}$.

We call the quantity

$$
\begin{equation*}
\delta_{0}=\delta_{0}(A):=\frac{1}{2} \sum_{j} i_{p_{j}} \widetilde{W} \tag{2.1}
\end{equation*}
$$

the number of double points of A hidden at 0 . In the literature $\delta_{0}$ is sometimes called the $\delta$-invariant of the singularity or the virtual number of double points. The next lemma justifies this definition.

Lemma 1. The number $\delta_{0}$ equals to the number of simple double points of a typical perturbation $N^{\prime}$ of the normalization map $N: \widetilde{A}_{1} \sqcup \cdots \sqcup \widetilde{A}_{r} \rightarrow \mathbb{C}^{2}$.

Proof. If, after perturbation, in the disc $\widetilde{A_{j}}$ there remain only preimages of simple double points then the number of such preimages equals to the sum of indices of the vector field $\widetilde{W}^{\prime}\left|\widetilde{A}_{j}=\left(N^{\prime}\right)^{*} V_{H^{\prime}}\right| \widetilde{A}_{j}$, where $H^{\prime}$ defines the perturbed curve. But this is exactly the index of the field $\widetilde{W}^{\prime}$ along $\partial A_{j}$. The latter index equals the index of the field $\left.\widetilde{W}\right|_{\tilde{A}_{j}}$ at $p_{j}$.

Summing-up all this over $j$ we get twice the number of double points of the perturbation.
Lemma 2. We have

$$
\begin{equation*}
\delta_{0}(A)=\sum_{j} \delta_{0}\left(A_{j}\right)+\sum_{i<j}\left(A_{i} \cdot A_{j}\right)_{0} \tag{2.2}
\end{equation*}
$$

where $\left(A_{i} \cdot A_{j}\right)_{0}$ is the intersection number at 0 of the components $A_{i}$ and $A_{j}$. In particular,

$$
\begin{equation*}
\delta_{0}(A) \geqslant \frac{1}{2} r(r-1) \geqslant r-1 . \tag{2.3}
\end{equation*}
$$

Proof. Let $N:(\mathbb{C}, 0) \rightarrow\left(A_{j}, 0\right), z \rightarrow(X(z), Y(z))$ be the local parametrization (normalization) of $A_{j}$. Assume also that the coordinates $X, \underset{\sim}{Y}$ are such that $A_{j}$ does not lie in the line $X=0$. Then we get $\dot{z}=\left.(d X / d z)^{-1}(\partial H / \partial Y)\right|_{A_{j}}$ and $i_{p_{j}} \widetilde{W}=\left.\operatorname{ord}_{z=0}(d X / d z)^{-1}(\partial H / \partial Y)\right|_{A_{j}}$. If $H=H_{1} \cdots H_{r}$, where $H_{j}$ defines $A_{j}$, then $\left.\operatorname{ord}_{z=0}(d X / d z)^{-1}(\partial H / \partial Y)\right|_{A_{j}}$ equals

$$
\left.\operatorname{ord}_{z=0}(d X / d z)^{-1}\left(\partial H_{j} / \partial Y\right)\right|_{A_{j}}+\left.\sum_{i \neq j} \operatorname{ord}_{z=0} H_{i}\right|_{A_{j}}=2 \delta_{0}\left(A_{j}\right)+\sum_{i \neq j}\left(A_{i} \cdot A_{j}\right)_{0}
$$

This gives Eq. (2.2).
Consider now the curve $C$ of the form (1.6), where we assume that $a_{m+1} b_{2} b_{n+1} \neq 0$.
Lemma 3. The quantity $v$ for the curve (1.6) such that $c_{1}=c_{3}=\cdots=c_{2 v-1}=0 \neq c_{2 v+1}$ (i.e. the codimension of the singularity $x=0$ of a parametrized curve) equals $\delta_{0}$, the number of double points at the singularity $X=Y=0$ of $C$ (which is of the type $\mathbf{A}_{2 v}$ ).

Proof. The $\mathbf{A}_{2 \nu}$ singular curve $H=X^{2}-Y^{2 v+1}$ admits parametrization $X=z^{2 v+1}, Y=z^{2}$. Then the Hamiltonian vector field restricted to this curve takes the form $\dot{z}=-H_{X}^{\prime} / 2 z=-z^{2 \nu}$.

Remark 3. In $[1,10,11]$ it is proved that the number $2 \delta_{0}$ for a cuspidal singularity, i.e. with only one branch ( $r=1$ ), equals the Milnor number of this singularity.

Denote by $\xi=(F, G): \mathbb{C} \rightarrow C$ the parametrization of the curve $C$ and let $H(X, Y)=0$ be the equation for $C$. The extension of the map $\xi$ to a map from $\mathbb{C P}^{1}$ is the normalization of the closure $\bar{C}=C \cup p_{\infty} \subset \mathbb{C P}^{2}$ of the curve $C$. We define a (real) vector field $W$ on $\bar{C}$, or $\widetilde{W}$ on $\mathbb{C P}^{1}$, by the formula

$$
\widetilde{W}(x)=\chi(x) \cdot\left(\xi^{*} V_{H}\right)(x), \quad x \in \mathbb{C P}^{1} \backslash \infty .
$$

Here $\chi(x)>0$ is a smooth function tending to 0 as $x \rightarrow \infty$ in a way that $\widetilde{W}$ becomes smooth at $\infty$. Namely, in the variable $z=1 / x$ the pull-back vector field $\xi^{*} V_{H}$ usually has pole, $\xi^{*} V_{H}=$ $z^{-\alpha}(c+\cdots) \frac{d}{d z}$ for $c \neq 0$. Then we put $\chi(x)=|z|^{2 \alpha}$ near $z=0$. We find that

$$
\begin{equation*}
i_{\infty} \widetilde{Y}=-\alpha \tag{2.4}
\end{equation*}
$$

Lemma 4. If C has only simple double points as singularities, then their number equals

$$
\delta:=1-\frac{1}{2} i_{\infty} \widetilde{W}
$$

For general curve $C$ the number $\delta=1-\frac{1}{2} i_{\infty} \widetilde{W}$ equals the sum of the numbers of double points hidden at the (finite) singular points of $C$.

Proof. It follows from the Poincaré-Hopf formula, Eq. (2.4) and $\chi\left(\mathbb{C P}^{1}\right)=2$.
Let us calculate the number $i_{\infty} \widetilde{W}$ in terms of the Puiseux expansion of the curve $C$ at infinity:

$$
\begin{align*}
Y & =X^{\frac{u_{1}}{p_{1}}}\left(d_{1}+\cdots\right)+X^{\frac{u_{2}}{p_{1} p_{2}}}\left(d_{1}+\cdots\right)+\cdots+X^{\frac{u_{r}}{p_{1} \cdots p_{r}}}\left(d_{1}+\cdots\right) \\
& =X^{\frac{v_{1}}{m+1}}\left(d_{1}+\cdots\right)+X^{\frac{v_{2}}{m+1}}\left(d_{2}+\cdots\right)+\cdots+X^{\frac{v_{r}}{m+1}}\left(d_{r}+\cdots\right) . \tag{2.5}
\end{align*}
$$

Here $p_{j}>1$ for $j \geqslant 2$, $\operatorname{deg} F=m+1=p_{1} \cdots p_{r}, \operatorname{gcd}\left(u_{j}, p_{j}\right)=1$ and $v_{1}>v_{2}>\cdots>v_{r}$. The coefficients $d_{j} \neq 0$ and the dots denote power series in $X^{1 / p_{1} \cdots p_{j}}$ in the $j$ th summand. Moreover, $v_{1}=\operatorname{deg} G=n+1$. The pairs $\left(p_{1}, u_{1}\right),\left(p_{2}, u_{2}\right), \ldots,\left(p_{r}, u_{r}\right)$ are often called the characteristic pairs (at infinity). We call the expansion (2.5) the topologically arranged Puiseux expansion.

Lemma 5. The number $i_{\infty} \widetilde{W}$ equals

$$
2-\left\{\left(v_{1}-1\right)\left(p_{1}-1\right) p_{2} \cdots p_{r}+\left(v_{2}-1\right)\left(p_{2}-1\right) p_{3} \cdots p_{r}+\cdots+\left(v_{r}-1\right)\left(p_{r}-1\right)\right\} .
$$

In particular, the number of double points of $C$ equals

$$
\begin{equation*}
\delta=\frac{1}{2} \sum\left(v_{j}-1\right)\left(p_{j}-1\right) p_{j+1} \cdots p_{r} . \tag{2.6}
\end{equation*}
$$

Proof. Formula (2.6) is well known in the literature. It is the same formula as the formula for the Milnor number of a cuspidal singularity via the characteristic pars given in [11]. Using the Hamiltonian differential equation on $C$, i.e. $\dot{X}=H_{Y}^{\prime}$, it can be proved as follows.

In the local variable $z=1 / x$ we get $\dot{z}=z^{-m} H_{Y}^{\prime}(c+\cdots)$ for some constant $c \neq 0$. So we have to calculate the order of $H_{Y}^{\prime} \mid c$ at $z=0$.

Formula (2.5) gives one branch $Y=f_{\zeta^{*}}(x)$ of the multi-valued solution to the equation $H(X, Y)=0$. All branches $Y=f_{\zeta}(X)$ of this solution take the form

$$
\zeta_{1}\left\{d_{1} X^{\frac{v_{1}}{m+1}}+\cdots+\zeta_{r}\left\{d_{r} X^{\frac{v_{1}}{m+1}}+\cdots\right\} \cdots\right\},
$$

where the coefficient $\zeta_{1}$ takes $p_{1}$ values, $\zeta_{2}$ takes $p_{2}$ values, etc. We have $\zeta^{*}=(1, \ldots, 1)$.
The polynomial $H$ can be represented in the form $H=\prod_{\zeta}\left(Y-f_{\zeta}(X)\right)$ near infinity and $\left.H_{Y}^{\prime}\right|_{C}=$ $\prod_{\zeta \neq \zeta^{*}}\left(Y-f_{\zeta}(X)\right)$. In the latter product we have $\left(p_{1}-1\right) p_{2} \cdots p_{r}$ factors with $\zeta_{1} \neq 1$ and of order $X^{\frac{v_{1}}{m+1}} \sim z^{-v_{1}}$ each, we have $\left(p_{2}-1\right) p_{3} \cdots p_{r}$ factors of order $z^{-v_{2}}$, etc. We find $\operatorname{ord}_{z=0} H_{Y}^{\prime}=$ $-\sum v_{j}\left(p_{j}-1\right) p_{j+1} \cdots p_{r}$.

Together with $(m+1)-1=\sum\left(p_{j}-1\right) p_{j+1} \cdots p_{r}$, this gives the thesis of the lemma.
Note that when $m+1=l(n+1)$, then $p_{1}=1, v_{1}=l$ and the first term in the sum in (2.6) gives zero contribution to $\delta$.

Lemma 6. The number $\delta$ is maximal when either:
(i) $m+1$ and $n+1$ are relatively prime (here $\delta=\delta_{\max }=\frac{1}{2} m n$ ), or
(ii) when there are exactly two essential terms in the expansion (2.5): $d_{1} X^{(n+1) /(m+1)}+d_{2} X^{n /(m+1)}$ (here $\delta_{\max }=\frac{1}{2}\left(m n-p_{2}+1\right)$ where $\left.p_{2}=\operatorname{gcd}(m+1, n+1)\right)$.

These numbers agree with (1.12). We obtain the following bound, which is weaker than in Theorem 1.

Corollary 1. $H_{\mathbb{C}}^{*}(m, n) \leqslant \delta_{\max }$.

Remark 4. The latter bound can be obtained also by estimating the number of finite solutions to the system (1.11) using the Bezout theorem and taking into account solutions at infinity.

In order to improve this estimate we use the following theorem of M. Zaidenberg and V. Lin.

Theorem 3. (See [17].) If an algebraic curve of the form (1.6) has only one singular point which is cuspidal then it is equivalent to a quasi-homogeneous curve.

Proof of Theorem 1. If the curve $C$ is not equivalent to a quasi-homogeneous curve then the Zaidenberg-Lin theorem says that it must have another double point (simple or hidden at another singularity). Hence the number of double points hidden at the point $X=Y=0$ does not exceed $\delta_{\text {max }}-1$.

So it remains to consider the possibilities when $C$ could be reduced to a quasi-homogeneous curve using Cremona transformations, like $X \rightarrow X+a Y^{j}$.

This cannot occur when none of the ratios $\frac{m+1}{n+1}$ and $\frac{n+1}{m+1}$ is integer and $m, n \geqslant 1$. Indeed, by the condition $b_{2} \neq 0$ the curve should be equivalent to $X=x^{2 v+1}, Y=x^{2}$. So the Cremona transformations should result in decreasing the bi-degree $(m+1, n+1)$. Our assumption about the ratios forbids it.

Suppose, for instance, that $(m+1)=k(n+1)$ and a change $X \rightarrow X+a X^{k}$ gives a curve with $X=F_{1}(x), \operatorname{deg} F_{1}=m_{1}+1<m+1$. Then like in Lemma 6 one checks that $\delta_{\max }\left(m_{1}, n\right) \leqslant \delta_{\max }(m, n)=$ $\frac{1}{2} k n(n+1)$ and the equality takes place only when $m_{1}=m-1$. In the latter case the curve cannot be reduced to a quasi-homogeneous one.

## 3. The Bogomolov-Miyaoka-Yau inequality

This section could be not easy for specialists in ODEs. It uses methods of complex geometry of open algebraic surfaces. This theory was developed mainly by Japanese geometers (see [6]) and one of its main results is the Bogomolov-Miyaoka-Yau (BMY) inequality which we present below. We will apply it using as few algebro-geometric language as possible.

Recall that a divisor on a smooth compact complex 2-dimensional manifold $V$ is a linear combination of closed complex curves with integer coefficients. Such a divisor (modulo some equivalence) can be viewed either as an element in $H^{2}(V, \mathbb{Z})$ or as an element in the homology group $H_{2}(V, \mathbb{Z})$. The latter point of view allows to define intersection product of divisors.

If we have a line bundle (i.e. with the fiber $\mathbb{C}$ ) over $V$ then we can associate with it a divisor of zeroes and poles of a meromorphic section of this bundle, the corresponding element in $H_{2}(V, \mathbb{Z})$ is dual to the first Chern class of the bundle. Conversely with any divisor we can associate a line bundle whose first Chern class equals this divisor. A special case of such a bundle is the canonical bundle $K=K_{V}$ associated with the sheaf $\Omega_{V}^{2}$ of holomorphic 2-forms on $V$. The corresponding (class of) divisor is called the canonical divisor. We refer the reader to [7] and [8] for more informations on divisors and Chern classes.

Let $V$ be a complex projective surface, $K$ its canonical divisor and $D$ a divisor of the form $D=$ $\sum D_{i}$, where $D_{i}$ are smooth projective curves on $V$ and each $D_{i}$ intersects other $D_{j}$ 's transversally. We say that $D$ is a normal crossings divisor.

Definition 1. We say that the logarithmic Kodaira dimension of $(V, D)$ equals $-\infty$ if none of the line bundles associated with the divisors $n(K+D), n=1,2, \ldots$, has a nontrivial holomorphic section. ${ }^{1}$

Definition 2. We say that the pair $(V, D)$ is relatively minimal if none of the components $D_{i}$ can be blown down. In other words, either $D_{i}^{2} \neq-1$, or $D_{i}$ is rational with $D_{i}^{2}=-1$ but $D_{i}$ intersects the divisor $D-D_{i}$ in at least three points.

Theorem 4. (BMY inequality, ${ }^{2}$ see [9].) Let $V$ be a complex projective surface, $K$ its canonical divisor and $D=\sum D_{i}$ is a normal crossings divisor in $V$. Assume moreover that the logarithmic Kodaira dimension of $(V, D)$ is not $-\infty$ and the pair $(V, D)$ is relatively minimal.

Then

$$
\begin{equation*}
(K+D)^{2} \leqslant 3 \chi(V \backslash D), \tag{3.1}
\end{equation*}
$$

where $\chi$ denotes the classical, topological Euler characteristic.
Let us consider the curve $C$ from Section 1 in $\mathbb{C P}^{2}$. More precisely, we consider the closure of this curve, which we still denote by $C$. Recall that $C: X=F(x), Y=G(x)$, where $F$ and $G$ are polynomials of degree $m+1$ and $n+1$ respectively. Recall also that $C$ has $\mathbf{A}_{2 v}$ type singularity at $X=Y=0$.
$C$ is a singular rational curve. Let $z_{1}, \ldots, z_{k}$ be singular points of $C$ with $z_{1}=(0,0)$ and $z_{k}$ the only point at infinity (when it is singular). Let $r_{i}$ be the number of branches of $C$ around the singular point $z_{i}$.

Then, as $C$ is rational, its Euler characteristics is equal to

$$
\chi(C)=2-\sum_{i=1}^{k}\left(r_{i}-1\right) .
$$

In fact, $C$ is topologically a sphere with sets of $r_{i}$-tuples of points (for $i=1, \ldots, k$ ) glued together. We denote

$$
\begin{equation*}
R=\sum_{i=1}^{k}\left(r_{i}-1\right) . \tag{3.2}
\end{equation*}
$$

Let us resolve the singularities of $C$. This means that we construct a map

$$
(V, \tilde{C}) \stackrel{\pi}{\mapsto}\left(\mathbb{C P}^{2}, C\right)
$$

such that $\tilde{C}$ is smooth, $\pi$ is a composition of blow-downs and $\pi^{-1}(C)=\tilde{C}+\sum a_{i} E_{i}$ as divisors, where $\sum_{i} a_{i} E_{i}$ is the sum of exceptional divisors. Assume that the resolution is minimal in the sense that there is no other triple $\left(V^{\prime}, \tilde{C}^{\prime}, \pi^{\prime}\right)$ sharing the same properties as $(V, \tilde{C}, \pi)$ such that $\pi^{\prime}$ is a composition of fewer blow-downs than $\pi$.

Define

$$
D=\tilde{C}+\sum E_{i},
$$

which from the algebro-geometric point of view can be regarded as taking a reduced inverse image of $C$. Here $\tilde{C}=\pi^{*}(C)$ is the strict transform of $C$.

[^1]Lemma 7. If the curve $C$ has a self-intersection, i.e. $R \geqslant 1$ in (3.2), then the logarithmic Kodaira dimension of $(V, D)$ is not $-\infty$ and the pair $(V, D)$ is relatively minimal.

Proof. The first statement, i.e. about the logarithmic Kodaira dimension, follows from a theorem of I. Wakabayashi [16].

In order to show the relative minimality of the pair $(V, D)$ we have to show that no component of $D$ is a rational curve $D_{i}$ such that $D_{i}^{2}=-1$ and $D_{i}\left(D-D_{i}\right) \leqslant 2$ (see [2,6] and Definition 2). The components of $D$ are the exceptional divisors $E_{i}$ and the strict transform $\tilde{C}$ itself. By the minimality of resolution for each $E_{i}$ either $E_{i}^{2}<-1$ or $E_{i}\left(D-E_{i}\right) \geqslant 3$; otherwise we could contract the curve $E_{i}$ and obtain a resolution with smaller number of blowing ups. On the other hand, if $R \geqslant 1$ the strict transform $\tilde{C}$ intersects other components of $D$ in at least three points.

Recall that by the Zaidenberg-Lin Theorem 3 and by the proof of Theorem 1 the curve $C$ without self-intersections can be reduced to a quasi-homogeneous curve via Cremona transformations which reduce the bi-degree of $C$. It is easy to show that in this case the $\delta$-invariant $\delta_{1} \leqslant \frac{1}{2} \max (m+1, n+1)$. So in the sequel we assume that $C$ is not simply connected and we can use the BMY inequality (3.1).

In order to make use of the BMY inequality we have to identify both of its sides. Let us begin with the right-hand side.

Observe that by definition $V \backslash D$ is isomorphic to $\mathbb{C P}^{2} \backslash C$. In particular, the Euler characteristics of both spaces coincide. Therefore

$$
\begin{equation*}
\chi(V \backslash D)=\chi\left(\mathbb{C P}^{2} \backslash C\right)=1+R \tag{3.3}
\end{equation*}
$$

The latter equality results from the additivity of the Euler characteristics.
Let us now deal with the left-hand side of (3.1). We will explain how this is done in this particular case. The general case is done in [2].

Let $W_{l}$ be the subspace of $H_{2}(V, \mathbb{Q})$ spanned by components of $\pi^{-1}\left(z_{l}\right)$. Let $W_{0}$ be the subspace of $H_{2}(V, \mathbb{Q})$ spanned by the class $H$ of a strict transform of a line in $\mathbb{C P}^{2}$ not passing by any of the points $z_{j}$.

Lemma 8. (See [13].) We have the orthogonal ( with respect to the intersection form) decomposition

$$
H_{2}(V, \mathbb{Q})=\bigoplus_{i=0}^{k} W_{i}
$$

We denote by $K_{i}$ and $D_{i}$ the orthogonal projections of $K$ and $D$ onto the space $W_{i}$ respectively. We have then

$$
\begin{align*}
(K+D)^{2}= & D(K+D)+K_{0}\left(K_{0}+D_{0}\right)+K_{1}\left(K_{1}+D_{1}\right) \\
& +\sum_{i=2}^{k-1} K_{i}\left(K_{i}+D_{i}\right)+K_{k}\left(K_{k}+D_{k}\right) . \tag{3.4}
\end{align*}
$$

It is easy to identify the first term in the right-hand side of Eq. (3.4). By the genus formula (see [7]) we have

$$
\begin{equation*}
D(K+D)=2 g_{a}-2, \tag{3.5}
\end{equation*}
$$

where $g_{a}$ is the arithmetic genus of the reducible curve $D .^{3}$

[^2]Lemma 9. The arithmetic genus $g_{a}(D)$ is equal to $R$ defined in (3.2).
Proof. The curve $C$ is rational. Thus its geometric genus is zero. Now each $r_{i}$-tuple point increases the arithmetic genus by $r_{i}-1$.

Also it is rather easy to deal with the term $K_{0}\left(K_{0}+D_{0}\right)$.
Lemma 10. $K_{0}\left(K_{0}+D_{0}\right)=-3 \operatorname{deg} C+9$.
Proof. Assume $n \leqslant m$; then the degree of $C$ is equal to $m+1$. Therefore $C$ intersects a generic line $H$ in $\mathbb{C P}^{2}$ at $m+1$ points. If these points differ from $z_{0}, \ldots, z_{k}$ the strict transform of $H$ intersects $D$ still at $m+1$ points. Thus $D_{0}=(m+1) \mathrm{H}$. Now the canonical divisor on $\mathbb{C P}^{2}$ can be represented as the class $-3 H$ in $H_{2}\left(\mathbb{C P}^{2}, \mathbb{Z}\right)$ (see [7]). By similar arguments as above we get $K_{0}=-3 H$. The lemma follows from the fact that $H \cdot H=1$.

Now we pass to the other parts of Eq. (3.4). We have to interpret and estimate each intersection number $K_{i}\left(K_{i}+D_{i}\right)$ associated with a singular point $z_{i}$ of the curve $C$.

Probably S. Orevkov [12] was the first who interpreted it as the codimension of the singularity in the cuspidal case, i.e. when $r_{i}=1$; he calls it the rough $M$-number. If, in some local analytic coordinates $x, y$ near $z_{i}$, we have the topologically arranged Puiseux expansion

$$
\begin{equation*}
x=\tau^{p}, \quad y=x^{\frac{q_{1}}{p_{1}}}\left(d_{1}+\cdots\right)+\cdots+x^{\frac{q_{s}}{p_{1} \cdots p_{s}}}\left(d_{s}+\cdots\right) \tag{3.6}
\end{equation*}
$$

(compare Eq. (2.5)) with the multiplicity $p=p_{1} \cdots p_{s}$ and $1<\frac{q_{1}}{p_{1}}<\cdots<\frac{q_{1}}{p_{1} \cdots p_{s}}$ then the codimension of this singularity equals $p-2$ plus the number of vanishing essential terms in this Puiseux expansion. Explicitly we have

$$
\begin{equation*}
K_{i}\left(K_{i}+D_{i}\right)=(p-2)+\sum_{j=1}^{s}\left(q_{j}-1-\left[\frac{q_{j}-1}{p_{j}}\right]\right) \tag{3.7}
\end{equation*}
$$

Here $p-2$ is the number of conditions that $d^{i} x / d \tau^{i}=0, i=1, \ldots, p-1$, at some point, $q_{1}-1-$ $\left[\left(q_{1}-1\right) / p_{1}\right]$ is the number of terms $x^{j / p_{1}}, j / p_{1}$ not integer, which are absent in (3.6), etc.

The proof uses a subtle analysis of the dual graph of the singularity which encodes the intersection matrix in the space $W_{i}$ from Lemma 8 . We refer the reader to the papers [13] and [14] by Orevkov and Zaidenberg. In [2] we generalize the interpretation of $K_{i}\left(K_{i}+D_{i}\right)$ as a codimension of singularity to the non-cuspidal case.

In particular, formula (35) of [14] directly implies the following
Lemma 11. For $1 \leqslant i \leqslant k-1$ the intersection number $K_{i}\left(K_{i}+D_{i}\right)$ is non-negative. For $i=1$, where the singularity at $z_{1}$ is of type $\mathbf{A}_{2 v}$, it is equal to $v$.

For the rough M-number $K_{k}\left(K_{k}+D_{k}\right)$ associated with the cuspidal singularity at infinity we have a more subtle bound.

[^3]Lemma 12. For $n<m$ we have

$$
K_{k}\left(K_{k}+D_{k}\right) \geqslant(m-n-1)+m-\left[\frac{m}{m-n}\right]
$$

Proof. The singularity at infinity of the curve $C$ can be locally parametrized by $s=1 / x$ as follows: $Y / X=s^{m-n}+\cdots, 1 / X=s^{m+1}+\cdots$. Then the first two terms in the right-hand side of Eq. (3.7) give our inequality. On the other hand, this inequality follows directly from Proposition 3 in [14] (see also [2]).

From Theorem 4, Eqs. (3.3), (3.4) and (3.5) and Lemmas 9, 10, 11 and 12 we get that

$$
v+2 R-m-n-\left[\frac{m}{m-n}\right]+3 \leqslant(K+D)^{2}, \quad n<m .
$$

Thus BMY inequality implies that

$$
v \leqslant m+n+\left[\frac{m}{m-n}\right]+R .
$$

To make the inequality more transparent, we bound $\left[\frac{m}{m-n}\right]$ by $\frac{1}{2}(m+n)$, getting finally

$$
\begin{equation*}
v \leqslant \frac{3}{2}(m+n)+R+\frac{1}{2} . \tag{3.8}
\end{equation*}
$$

In case $m<n$ we have to switch from $\frac{m}{m-n}$ to $\frac{n}{n-m}$. In case $m=n$ we apply a Cremona change $Y \rightarrow Y+$ const $\cdot X$, so $n$ becomes smaller. Anyway, in all cases inequality (3.8) still holds true.

We need another inequality relating $R$ and $v$. That one will be the consequence of computing the indices of the Hamiltonian vector field introduced in Section 2. Namely, observe that by Lemma 6 (in Section 2) we get $v+\sum_{i=2}^{k-1} \delta_{k} \leqslant \delta_{\text {max }}$, where $\delta_{\max }=\frac{1}{2}(m n-\operatorname{gcd}(n+1, m+1)+1)$ and $\delta_{i}$ is the $\delta$-invariant of the $i$ th singular point. For the sake of transparency we estimate $\operatorname{gcd}(n+1, m+1)$ by 1 .

Now by Lemma 3 (see (2.3)) $\delta_{i} \geqslant r_{i}-1$. So the above inequalities yield

$$
R \leqslant \frac{1}{2} m n-v
$$

Then substituting $R$ into (3.8) yields

$$
v \leqslant \frac{1}{2}(m n+3 n+3 m+1)-v .
$$

This concludes the proof of Theorem 2.
Remark 5. This proof allows some improvement at the cost of legibility. We can consider the resolution not of the curve $C$ but the curve $C+$ (line at infinity) and study carefully the cases when the line at infinity becomes a ( -1 )-curve. We can show that $(K+D)^{2} \geqslant v+2 R-n-m+\left[\frac{m+1}{n+1}\right]+1$ (if $m<n$ ). The whole procedure is explained in [2] and is technically quite complicated. Anyway, the bounds we obtain have the same leading term (i.e. $v \leqslant \sim \frac{1}{4} m n$ ) as the one we have written here.

## Acknowledgments

We would like to thank the referee of JDE for pointing out the reference [4] and for convincing us to give the algebro-geometric proof of the $\frac{1}{4} m n$ bound.

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[^0]:    2 Supported by Polish KBN Grant No. 1 P03A 01529.

    * Corresponding author.

    E-mail addresses: mcboro@mimuw.edu.pl (M. Borodzik), zoladek@mimuw.edu.pl (H. Żołądek).

[^1]:    1 The logarithmic Kodaira dimension is defined via growth of dimensions of the spaces $H^{0}(V, n(K+D))$ as $n \rightarrow \infty$ (see [6]).
    2 The BMY inequality for compact complex surfaces states that $c_{1}^{2} \leqslant 3 c_{2}$ where $c_{1}$ and $c_{2}$ are the Chern classes of the surface. Here $c_{2}$ is the Euler class and its integral equals the Euler characteristic.

[^2]:    ${ }^{3}$ The arithmetic genus $g_{a}$ (or $p_{a}$ ) of an algebraic curve $D$ on an algebraic surface $V$ is defined as $\frac{1}{2} \chi\left(\mathcal{O}_{D}\right)+1=\frac{1}{2}\left(h^{0}\left(\mathcal{O}_{D}\right)-\right.$ $\left.h^{1}\left(\mathcal{O}_{D}\right)\right)+1$ and equals $\frac{1}{2} D\left(K_{V}+D\right)+1$. If $D$ is smooth then $K_{D}=K_{V}+D$ restricted to $D$ (it is the adjunction formula or

[^3]:    an algebro-geometric variant of the Gelfand-Leray form) and $D\left(K_{V}+D\right)$ is the degree of $K_{D}$. If $\tilde{D}$ is the normalization of $D$ then $g_{a}(D)=g_{a}(\tilde{D})+\sum \delta_{z}$, where $\delta_{z}$ are the numbers of double points of $D$ at the singular points $z$. In particular, if $D$ is a connected union of $m$ rational curves with $r$ simple double points as the only singularities (of $D$ ) then $g_{a}(D)=1-m+r$. All this can be found in the Hartshorne's book [8].

