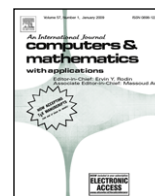


Contents lists available at [SciVerse ScienceDirect](http://SciVerse.ScienceDirect.com)

## Computers and Mathematics with Applications

journal homepage: [www.elsevier.com/locate/camwa](http://www.elsevier.com/locate/camwa)

# Chebyshev wavelets approach for nonlinear systems of Volterra integral equations

J. Biazar\*, H. Ebrahimi

Department of Applied Mathematics, Faculty of Mathematical Science, University of Guilan, P. O. Box. 41635-19141, P. C. 4193833697, Rasht, Iran

## ARTICLE INFO

## Article history:

Received 19 April 2011

Received in revised form 22 September 2011

2011

Accepted 23 September 2011

## Keywords:

Chebyshev wavelets method

Mother wavelet

Operational matrix

Systems of Volterra integral equations

## ABSTRACT

In this paper, a new approach for solving nonlinear systems of Volterra integral equations has been proposed. The method is based on Chebyshev wavelets approximations. The method is described and after that the error is analyzed. At the end, some examples are presented to illustrate the ability and simplify of the method and the results reveal the effectiveness of the technique.

© 2011 Elsevier Ltd. All rights reserved.

## 1. Introduction

Orthogonal functions and polynomials have been used by many authors for solving various functional equations. The main idea of using an orthogonal basis is that the problem under study reduces to a system of linear or nonlinear algebraic equations. This can be done by truncated series of orthogonal basis functions for the solution of problem and using the operational matrices. In this paper, Chebyshev wavelets basis, on the interval  $[0, 1]$ , have been used. There are many applications of the Chebyshev wavelet method in the literature [1–3]. An extension of Chebyshev wavelets method for solving nonlinear systems of Volterra integral equations [4–6], is the novelty of this paper.

Mathematical modeling of many phenomena in different disciplines leads to a system of Volterra integral equations. So the solutions of these systems are of great interest for mathematicians and engineers. Systems of Volterra integral equations have been solved by some methods, the Adomian decomposition method [7,8], Homotopy perturbation method [9,10], Variational iteration method [11], Adomian–Pade technique [12], Runge–Kutta method [13], radial basis function networks [14] and block by block method [15]. The general form of these systems can be presented as follows

(a) The first kind

$$\sum_{j=1}^m \int_0^x k_{i,j}(x, t) G_{ij}(u_1(t), u_2(t), \dots, u_n(t)) dt = f_i(x), \quad 0 \leq x \leq 1, \quad i = 1, 2, \dots, n, \quad m = 1, 2, \dots \quad (1)$$

(b) The second kind

$$u_i(x) = f_i(x) + \sum_{j=1}^m \int_0^x k_{ij}(x, t) G_{ij}(u_1(t), u_2(t), \dots, u_n(t)) dt, \quad 0 \leq x \leq 1, \quad i = 1, 2, \dots, n, \quad m = 1, 2, \dots \quad (2)$$

\* Corresponding author. Tel.: +98 131 3233509; fax: +98 131 3233509.

E-mail addresses: [biazar@guilan.ac.ir](mailto:biazar@guilan.ac.ir) (J. Biazar), [ebrahimi.hamideh@gmail.com](mailto:ebrahimi.hamideh@gmail.com) (H. Ebrahimi).

where  $k_{ij}(x, t) \in L^2([0, 1] \times [0, 1])$  are the kernels,  $f_i(x)$ ,  $i = 1, 2, \dots, n$ , are known functions,  $G_{ij}$  are linear or non-linear vector functions of  $n$  unknown real functions  $u_1(t), \dots, u_n(t)$ .

## 2. Wavelets and Chebyshev wavelets

Wavelets constitute a family of functions constructed from dilation and translation of a single function called the mother wavelet, [16–18]. When the dilation parameter,  $a$  and the translation parameter,  $b$ , vary continuously we have the following family of continuous wavelets as

$$\psi_{a,b}(x) = |a|^{-\frac{1}{2}} \psi\left(\frac{x-b}{a}\right), \quad a, b \in \mathbb{R}, a \neq 0. \tag{3}$$

If we take the dilation and translation parameters  $a^{-k}$ , and  $nba^{-k}$ , respectively where  $a > 1$ ,  $b > 0$ ,  $n$ , and  $k$  are positive integers, then we have the following family of discrete wavelets

$$\psi_{k,n}(x) = |a|^{\frac{k}{2}} \psi(a^k x - nb). \tag{4}$$

These functions are a wavelet basis for  $L^2(\mathbb{R})$  and in special case  $a = 2$ , and  $b = 1$ , the functions  $\psi_{k,n}(x)$  are an orthonormal basis.

Chebyshev wavelets  $\psi_{n,m}(x) = \psi(k, n, m, x)$  have four arguments,  $n = 1, 2, \dots, 2^{k-1}$ ,  $k$  is an arbitrary positive integer and  $m$  is the order of Chebyshev polynomials of the first kind. They are defined on the interval  $[0, 1]$ , as follows:

$$\psi_{nm}(x) = \psi(k, n, m, x) = \begin{cases} 2^{\frac{k}{2}} \tilde{T}_m(2^k x - 2n + 1), & \frac{n-1}{2^{k-1}} \leq x < \frac{n}{2^{k-1}}, \\ 0, & \text{otherwise} \end{cases} \tag{5}$$

where

$$\tilde{T}_m(x) = \begin{cases} \frac{1}{\sqrt{\pi}}, & m = 0, \\ \sqrt{\frac{2}{\pi}} T_m(x), & m > 0. \end{cases} \tag{6}$$

and  $m = 0, 1, \dots, M-1$  and  $n = 1, 2, \dots, 2^{k-1}$ .  $T_m(x)$  are the famous Chebyshev polynomials of the first kind of degree  $m$ , which are orthogonal with respect to the weight function  $W(x) = \frac{1}{\sqrt{1-x^2}}$ , on the interval  $[-1, 1]$ , and satisfy the following recursive formula:

$$\begin{cases} T_0(x) = 1, \\ T_1(x) = x, \\ T_{m+1}(x) = 2xT_m(x) - T_{m-1}(x), \quad m = 1, 2, \dots \end{cases} \tag{7}$$

The set of Chebyshev wavelets is an orthogonal set with respect to the weight function  $W_n(x) = W(2^k x - 2n + 1)$ . A function  $f(x)$  defined on the interval  $[0, 1]$  may be presented as

$$f(x) = \sum_{n=1}^{\infty} \sum_{m=0}^{\infty} c_{nm} \psi_{nm}(x). \tag{8}$$

The series representation of  $f(x)$  in (7) is called a wavelet series and the wavelet coefficients  $c_{nm}$  are given by  $c_{nm} = (f(x), \psi_{nm}(x))_{W_n(x)}$ . The convergence of the series (8), in  $L^2[0, 1]$ , means that

$$\lim_{s_1, s_2 \rightarrow \infty} \|f(x) - \sum_{n=1}^{s_1} \sum_{m=0}^{s_2} c_{nm} \psi_{nm}(x)\| = 0. \tag{9}$$

Therefore one can consider the following truncated series for series (8)

$$f(x) \simeq \sum_{n=1}^{2^{k-1}} \sum_{m=0}^{M-1} c_{nm} \psi_{nm}(x) = C^T \psi(x), \tag{10}$$

where  $C$  and  $\psi(x)$  are  $2^{k-1}M \times 1$  matrices given by

$$\begin{aligned} C &= [c_{10}, c_{11}, \dots, c_{1M-1}, c_{20}, c_{21}, \dots, c_{2M-1}, \dots, c_{2^{k-1}0}, \dots, c_{2^{k-1}M-1}]^T \\ &= [c_1, c_2, \dots, c_M, c_{M+1}, \dots, c_{2^{k-1}M}]^T, \end{aligned} \tag{11}$$

and

$$\begin{aligned} \psi(x) &= [\psi_{10}(x), \psi_{11}(x), \dots, \psi_{1,M-1}(x), \psi_{20}(x), \psi_{21}(x), \\ &= \dots, \psi_{2,M-1}(x), \dots, \psi_{2^{k-1}0}(x), \dots, \psi_{2^{k-1},M-1}(x)]^T \\ &= [\psi_1(x), \psi_2(x), \dots, \psi_M(x), \psi_{M+1}(x), \dots, \psi_{2^{k-1}M}(x)]^T. \end{aligned} \tag{12}$$

The integration of the product of two Chebyshev wavelets vector functions with respect to the weight function  $W_n(x)$ , is derived as

$$\int_0^1 W_n(x) \psi(x) \psi^T(x) dx = I, \tag{13}$$

where  $I$  is an identity matrix.

A function  $f(x, y)$  defined on  $[0, 1] \times [0, 1]$  can be approximated as the following

$$f(x, y) \simeq \psi^T(x) K \psi(y). \tag{14}$$

Here the entries of matrix  $K = [k_{ij}]_{2^{k-1}M \times 2^{k-1}M}$  will be obtain by

$$k_{i,j} = (\psi_i(x), (f(x, y), \psi_j(y))_{W_n(y)}_{W_n(x)}), \quad i, j = 1, 2, \dots, 2^{k-1}M. \tag{15}$$

The integration of the vector  $\psi(x)$ , defined in (12), can be achieved as

$$\int_0^x \psi(t) dt = P \psi(x) \tag{16}$$

where  $P$  is the  $2^{k-1}M \times 2^{k-1}M$  operational matrix of integration [1,2]. This matrix is determined as follows.

$$P = \frac{1}{2^k} \begin{bmatrix} L & F & F & \dots & F \\ O & L & F & \ddots & \vdots \\ O & O & L & \ddots & F \\ \vdots & \ddots & \ddots & \ddots & F \\ O & \dots & O & O & L \end{bmatrix}, \tag{17}$$

where  $L, F$  and  $O$  are  $M \times M$  matrices given by

$$L = \begin{bmatrix} 1 & \frac{1}{\sqrt{2}} & 0 & 0 & 0 & \dots & 0 \\ -\frac{\sqrt{2}}{4} & 0 & \frac{1}{4} & 0 & 0 & \dots & 0 \\ -\frac{\sqrt{2}}{3} & -\frac{1}{2} & 0 & \frac{1}{6} & 0 & \dots & 0 \\ \vdots & \ddots & \ddots & \ddots & \ddots & \ddots & \vdots \\ \frac{\sqrt{2}}{2}(-1)^r \left( \frac{1}{r-2} - \frac{1}{r} \right) & \dots & -\frac{1}{2(r-2)} & 0 & \frac{1}{2r} & \dots & 0 \\ \vdots & & \ddots & \ddots & \ddots & & \vdots \\ \frac{\sqrt{2}}{2}(-1)^M \left( \frac{1}{M-2} - \frac{1}{M} \right) & 0 & 0 & 0 & \dots & -\frac{1}{2(M-2)} & 0 \end{bmatrix}, \tag{18}$$

$$F = \begin{bmatrix} 2 & 0 & \dots & 0 \\ 0 & 0 & \dots & 0 \\ -\frac{2\sqrt{2}}{3} & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\sqrt{2}}{2} \left( \frac{1 - (-1)^r}{r} - \frac{1 - (-1)^{r-2}}{r-2} \right) & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\sqrt{2}}{2} \left( \frac{1 - (-1)^M}{M} - \frac{1 - (-1)^{M-2}}{M-2} \right) & 0 & \dots & 0 \end{bmatrix}, \tag{19}$$

$$O = \begin{bmatrix} 0 & 0 & \dots & 0 \\ 0 & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 0 \end{bmatrix}. \tag{20}$$

The property of the product of two Chebyshev wavelets vector functions will be as follows

$$\psi(x)\psi^T(x)Y \simeq \tilde{Y}\psi(x), \tag{21}$$

where  $Y$  is a given vector and  $\tilde{Y}$  is a  $2^{k-1}M \times 2^{k-1}M$  matrix. This matrix is called the operational matrix of product.

### 3. Solution of systems of Volterra integral equations via Chebyshev wavelets method

Consider the systems of Volterra integral equations (1) and (2). Let's consider the following approximations for unknown functions  $u_i, (x), i = 1, 2, \dots, n$ .

$$u_i(x) \simeq C_i^T \psi(x), \quad i = 1, 2, \dots, n \tag{22}$$

where  $C_i, i = 1, 2, \dots, n$  are  $2^{k-1}M \times 1$  matrices given by

$$\begin{aligned} C_i &= \left[ c_{10}^i, c_{11}^i, \dots, c_{1M-1}^i, c_{20}^i, c_{21}^i, \dots, c_{2M-1}^i, \dots, c_{2^{k-1}0}^i, \dots, c_{2^{k-1}M-1}^i \right]^T \\ &= \left[ c_{i,1}, c_{i,2}, \dots, c_{i,M}, c_{i,M+1}, \dots, c_{i,2^{k-1}M} \right]^T, \end{aligned} \tag{23}$$

and  $\psi(x)$  is defined in (12). Also consider the following approximations

$$\begin{aligned} f_i(x) &\simeq F_i^T \psi(x), \quad G_{i,j}(u_1(t), u_2(t), \dots, u_n(t)) \simeq Y_{ij}^T \psi(t), \\ k_{ij}(x, t) &\simeq \psi^T(x)K_{ij}\psi(t), \quad i = 1, 2, \dots, n, \quad j = 1, 2, \dots, m. \end{aligned} \tag{24}$$

where  $K_{ij}$  are the  $2^{k-1}M \times 2^{k-1}M$  matrices,  $F_i$  are the  $2^{k-1}M \times 1$  matrices, and  $Y_{ij}$  are column vectors with the entries of the vectors  $C_i$  for  $i = 1, 2, \dots, n, j = 1, 2, \dots, m$ .

Substitution of approximations (22) and (24) into the systems (1) and (2), will be resulted to:

$$\begin{aligned} F_i^T \psi(x) &= \sum_{j=1}^m \int_0^x \psi^T(x)K_{ij}\psi(t)\psi^T(t)Y_{ij} dt, \\ &= \sum_{j=1}^m \psi^T(x)K_{ij} \left( \int_0^x \psi(t)\psi^T(t)Y_{ij} dt \right), \\ &= \sum_{j=1}^m \psi^T(x)K_{ij}\tilde{Y}_{i,j}P\psi(x), \quad i = 1, 2, \dots, n, \quad m = 1, 2, \dots \end{aligned} \tag{25}$$

and

$$\begin{aligned} C_i^T \psi(x) &= F_i^T \psi(x) + \sum_{j=1}^m \int_0^x \psi^T(x)K_{ij}\psi(t)\psi^T(t)Y_{ij} dt, \\ &= F_i^T \psi(x) + \sum_{j=1}^m \psi^T(x)K_{ij} \left( \int_0^x \psi(t)\psi^T(t)Y_{ij} dt \right), \\ &= F_i^T \psi(x) + \sum_{j=1}^m \psi^T(x)K_{ij}\tilde{Y}_{i,j}P\psi(x), \quad i = 1, 2, \dots, n, \quad m = 1, 2, \dots \end{aligned} \tag{26}$$

where  $\tilde{Y}_{ij}$  are  $2^{k-1}M \times 2^{k-1}M$  operational matrices for production and  $P$  is the  $2^{k-1}M \times 2^{k-1}M$  operational matrix of integration [1-3].

According to the Galerkin method by multiplying  $W_n(x)\psi^T(x)$ , in both sides of the systems (25) and (26) and then applying  $\int_0^1(\cdot)dx$ , linear or non-linear systems in terms of the entries of  $C_i, i = 1, 2, \dots, n$ , will be obtained. The elements of vector functions  $C_i, i = 1, 2, \dots, n$  can be computed by solving these systems.

**4. Error analysis**

**Theorem 1.** Assume  $P$  be the number of vanishing moments for a wavelet  $\psi_{nm}(x)$  and let  $f(x) \in C^P[0, 1]$ . Then the wavelet coefficient,  $c_{nm}$ , decays as follows

$$|c_{nm}| \leq C_p 2^{-n(P+\frac{1}{2})} \text{Max}_{\xi \in [0,1]} |f^{(P)}(\xi)|, \tag{27}$$

where  $C_p$  is an independent constant from  $n, m$  and  $f(x)$ .

The above theorem implies that wavelet coefficients are exponentially decayed with respect to  $P$  and by increasing  $P$  the decay increases.

Since the truncated Chebyshev wavelets series is approximate solution of a system, so one has an error function error ( $f(x)$ ) for  $f(x)$  as follows

$$\text{error}(f(x)) = \left| f(x) - \sum_{n=1}^{2^{k-1}} \sum_{m=0}^{M-1} c_{nm} \psi_{nm}(x) \right| \tag{28}$$

where setting  $x = x_j, x_j \in [0, 1]$ , the absolute error value of  $x_j$  can be obtained.

The error bound of the approximate solution by using Chebyshev wavelets series is given by the following theorem.

**Theorem 2.** Suppose  $f(x) \in C^P[0, 1]$  and  $C^T \psi(x) = \sum_{n=1}^{2^{k-1}} \sum_{m=0}^{M-1} c_{nm} \psi_{nm}(x)$  is the approximate solution using Chebyshev wavelets method. Then the error bound would be obtained as follows

$$\| \text{error}(f(x)) \| \leq \frac{1}{P! 2^{P(k-1)}} \text{Max}_{\xi \in [0,1]} |f^{(P)}(\xi)|. \tag{29}$$

**Proof.** Using the definition of norm in the inner product space, we have

$$\| \text{error}(f(x)) \|^2 = \| f(x) - C^T \psi(x) \|^2 = \int_0^1 W(x) (f(x) - C^T \psi(x))^2 dx. \tag{30}$$

Because the interval  $[0, 1]$  is divided into  $2^{k-1}$  subintervals  $I_n = \left[ \frac{n-1}{2^{k-1}}, \frac{n}{2^{k-1}} \right]$  that the function  $f(x)$  is approximated on them by using Chebyshev wavelets method as a polynomial of the  $P$ th degree at most with the least-square property, therefore would be as

$$\begin{aligned} \| \text{error}(f(x)) \|^2 &= \int_0^1 W(x) (f(x) - C^T \psi(x))^2 dx = \sum_{n=1}^{2^{k-1}} \int_{\frac{n-1}{2^{k-1}}}^{\frac{n}{2^{k-1}}} W_n(x) (f(x) - C^T \psi(x))^2 dx \\ &\leq \sum_{n=1}^{2^{k-1}} \int_{\frac{n-1}{2^{k-1}}}^{\frac{n}{2^{k-1}}} W_n(x) (f(x) - S_p(x))^2 dx, \end{aligned}$$

where  $S_p(x)$  is any polynomial of degree  $P$  that interpolates  $f(x)$  on  $I_n$  with the following error bound for interpolating

$$|f(x) - S_p(x)| \leq \frac{1}{P! 2^{P(k-1)}} \text{Max}_{\xi_n \in I_n} |f^{(P)}(\xi_n)|. \tag{31}$$

Therefore, using (31) would be obtained

$$\begin{aligned} \| \text{error}(f(x)) \|^2 &\leq \sum_{n=1}^{2^{k-1}} \int_{\frac{n-1}{2^{k-1}}}^{\frac{n}{2^{k-1}}} W_n(x) \left( \frac{1}{P! 2^{P(k-1)}} \text{Max}_{\xi_n \in I_n} |f^{(P)}(\xi_n)| \right)^2 dx \\ &\leq \sum_{n=1}^{2^{k-1}} \int_{\frac{n-1}{2^{k-1}}}^{\frac{n}{2^{k-1}}} W_n(x) \left( \frac{1}{P! 2^{P(k-1)}} \text{Max}_{\xi \in [0,1]} |f^{(P)}(\xi)| \right)^2 dx \\ &= \int_0^1 \left( \frac{1}{P! 2^{P(k-1)}} \text{Max}_{\xi \in [0,1]} |f^{(P)}(\xi)| \right)^2 dx \\ &= \left\| \frac{1}{P! 2^{P(k-1)}} \text{Max}_{\xi \in [0,1]} |f^{(P)}(\xi)| \right\|^2. \quad \square \end{aligned}$$

**5. Numerical examples**

In this section, some examples of systems of Volterra integral equations are considered and will be solved by introduced method. These examples are solved for  $k = 1$  and  $M = 6$ .

**Table 1**  
Numerical results of Example 1.

$x$	$u(\text{exact})$	$u(\text{CWM})$	$\text{error}(u(x))$	$v(\text{exact})$	$v(\text{CWM})$	$\text{error}(v(x))$
0	0	-0.0000260703 5437	0.00002607035 437	0	0.0002222967327	0.0002222967327
0.2	0.04	0.03998703593	0.00001296407437	0.2	0.1999646030	0.0000353966836
0.4	0.16	0.1599826154	0.00001738456777	0.4	0.4000415581	0.0000415581197
0.6	0.36	0.3600478974	0.00004789734703	0.6	0.5999773361	0.0000226638703
0.8	0.64	0.6399664612	0.00003353875937	0.8	0.7999977346	0.0000022653373
1	1	1.000185856	0.0001858557196	1	0.999922349	0.0000776850473

**Example 1.** Consider the following nonlinear system of Volterra integral equations of the first kind with the exact solutions  $u(x) = x^2$  and  $v(x) = x$  [7,14].

$$\begin{cases} \int_0^x (1 - x^2 + t^2)(u(t) + v^3(t))dt = -\frac{1}{12}x^6 - \frac{2}{15}x^5 + \frac{1}{4}x^4 + \frac{1}{3}x^3, \\ \int_0^x (5 + x - t)(u^3(t) - v(t))dt = \frac{1}{56}x^8 + \frac{5}{7}x^7 - \frac{1}{6}x^3 - \frac{5}{2}x^2, \quad 0 \leq x \leq 1. \end{cases} \tag{32}$$

Let's

$$\begin{aligned} u(x) &\simeq C_1^T \psi(x), & v(x) &\simeq C_2^T \psi(x), \\ u^3(x) &\simeq Y_1^T \psi(x), & v^3(x) &\simeq Y_2^T \psi(x), \\ -\frac{1}{12}x^6 - \frac{2}{15}x^5 + \frac{1}{4}x^4 + \frac{1}{3}x^3 &\simeq F_1^T \psi(x), \\ \frac{1}{56}x^8 + \frac{5}{7}x^7 - \frac{1}{6}x^3 - \frac{5}{2}x^2 &\simeq F_2^T \psi(x), \\ (1 - x^2 + t^2) &\simeq \psi^T(x)K_1 \psi(t), \\ (5 + x - t) &\simeq \psi^T(x)K_2 \psi(t). \end{aligned}$$

Substitution into the system (29), leads to the following system

$$\begin{cases} F_1^T \psi(x) = \psi^T(x)K_1 \int_0^x \psi(t)\psi^T(t)(C_1 + Y_2)dt = \psi^T(x)K_1 \tilde{Y}_1 P \psi(x), \\ F_2^T \psi(x) = \psi^T(x)K_2 \int_0^x \psi(t)\psi^T(t)(Y_1 - C_2)dt = \psi^T(x)K_2 \tilde{Y}_2 P \psi(x). \end{cases} \tag{33}$$

Multiply  $W_n(x)\psi^T(x)$ , on both sides of the system (33), apply  $\int_0^1 (\cdot)dx$ , and then solve the system. The elements of vector functions  $C_1$  and  $C_2$  can be obtained as follows

$$\begin{aligned} C_1 &= [0.4700121513, 0.4431403268, 0.1108030029, 0.00002342689770, \\ &\quad 0.00003248339560, 0.00004361621557]^T, \\ C_2 &= [0.6266750242, 0.4430699839, 0.00002475338584, -0.00003950954832, \\ &\quad 0.00002662956111, -0.00004993764185]^T. \end{aligned}$$

Therefore, the following solutions will result.

$$\begin{aligned} u(x) &\simeq C_1^T \psi(x) = 0.02519840204x^5 - 0.05830434600x^4 + 0.04658408778x^3 + 0.9851318713x^2 \\ &\quad + 0.001601910954x - 0.00002607035437 \\ v(x) &\simeq C_2^T \psi(x) = -0.02885048049x^5 + 0.07597237616x^4 - 0.07222939205x^3 + 0.02971053030x^2 \\ &\quad + 0.9950969843x + 0.0002222967327. \end{aligned}$$

Table 1 shows some values of the solutions and absolute errors at some  $x$ 's and plots of the exact and approximate solutions are shown in Fig. 1. Comparison between the obtained solutions by the Adomian decomposition method in [7] and the results of this paper show that the absolute error of the Chebyshev wavelets method is less than the absolute error of the Adomian decomposition method.

**Example 2.** Consider the following nonlinear system of Volterra integral equations of the second kind

$$\begin{cases} u(x) = \sin x - x + \int_0^x (u^2(t) + v^2(t)) dt, \\ v(x) = \cos x - \frac{1}{2} \sin^2 x + \int_0^x u(t)v(t)dt, \quad 0 \leq x \leq 1. \end{cases} \tag{34}$$

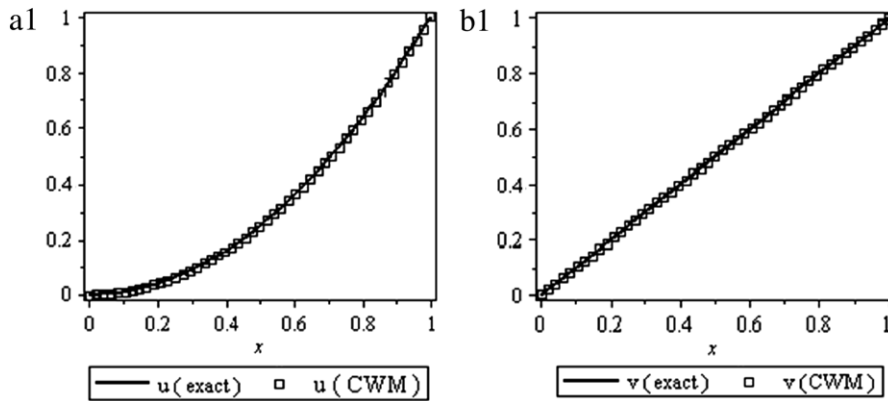


Fig. 1. (a1) and (b1) comparison of the exact and approximate solutions of Example 1.

Table 2  
Numerical results of Example 2.

$x$	$u(\text{exact})$	$u(\text{CWM})$	$\text{error}(u(x))$	$v(\text{exact})$	$v(\text{CWM})$	$\text{error}(v(x))$
0	0	-0.000001403 703684	0.000001403703 684	1	1.000000319	0.000000319
0.2	0.1986693308	0.1986696393	0.0000003085	0.9800665778	0.9800669460	0.0000003682
0.4	0.3894183423	0.3894165787	0.00000017636	0.9210609940	0.9210604974	0.0000004966
0.6	0.5646424734	0.5646433964	0.0000000923	0.8253356149	0.8253349025	0.0000007124
0.8	0.7173560909	0.7173557641	0.0000003268	0.6967067093	0.6967067839	0.0000000746
1	0.84144709848	0.8414719842	0.0000009994	0.5403023059	0.5403020838	0.0000002221

With the exact solutions  $u(x) = \sin x$  and  $v(x) = \cos x$  [10,15].

The vectors  $C_1$  and  $C_2$  are computed by solving the system of nonlinear equations for six unknowns, via the Maple package, as follows

$$C_1 = [0.5638986783, 0.3768420409, -0.02600615260, -0.003987867721, 0.0001365184253, 0.00001401577453]^T$$

$$C_2 = [1.032209955, -0.2058701368, -0.04760382879, 0.002178573519, 0.0002499015756, -0.6913472440 \times 10^{-5}]^T.$$

Therefore, we have the following approximate solutions

$$u(x) = 0.008097427401x^5 - 0.0005258577420x^4 - 0.1657167707x^3 - 0.0004456850651x^2 + 1.000064274x - 0.1403703684 \times 10^{-5}$$

$$v(x) = -0.003994087527x^5 + 0.04607914088x^4 - 0.002260687350x^3 - 0.4994799014x^2 - 0.00004269977464 + 1.000000319.$$

Table 2 shows some values of the solutions and absolute errors at some  $x$ 's and plots of the exact and approximate solutions are shown in Fig. 2.

Example 3. Consider

$$\begin{cases} \int_0^x (5+x-t)u(t) + \left(\frac{x^2}{2} + t\right)v(t)w(t) dt = \frac{1}{48}x^6 + \frac{19}{270}x^5 + \frac{19}{72}x^4 + \frac{7}{6}x^3 + x^2 + 5x, \\ \int_0^x \left(\frac{x^2}{2} + t\right)u(t) + (3+x-t)v(t) + \frac{1}{4}(x^2 - t^2)w(t) dt = \frac{1}{24}x^5 + \frac{35}{288}x^4 + \frac{17}{18}x^3 + \frac{5}{4}x^2 + \frac{9}{2}x, \\ \int_0^x (tu(t)v(t) - xt v^2(t) - 5w(t)) dt = -\frac{1}{54}x^7 + \frac{1}{72}x^6 - \frac{1}{4}x^5 + \frac{17}{96}x^4 - \frac{9}{8}x^3 - \frac{1}{2}x^2 - \frac{10}{3}x, \quad 0 \leq x \leq 1. \end{cases} \quad (35)$$

With the exact solution  $u(x) = \frac{1}{4}x^2 + 1$ ,  $v(x) = \frac{1}{3}x^2 + \frac{3}{2}$ , and  $w(x) = \frac{1}{2}x + \frac{2}{3}$ , [9].

By applying the Chebyshev wavelets method and solving the resulted nonlinear system, the following results would be achieved.

$$C_1 = [1.370909608, 0.1107744910, 0.02796071583, -0.3904883363 \times 10^{-5}, -0.3849125038 \times 10^{-5}, -0.2901199063 \times 10^{-5}]^T,$$

**Table 3**  
Numerical results of Example 3.

$x$	$u(\text{exact})$	$u(\text{CWM})$	$\text{error}(u(x))$	$v(\text{exact})$	$v(\text{CWM})$	$\text{error}(v(x))$	$w(\text{exact})$	$w(\text{CWM})$	$\text{error}(w(x))$
0	1	1.0000 1158	0.000001158	1.5	1.49999 9358	0.000000642	0.66666 66667	0.66665 69385	0.0000097282
0.2	1.01	1.01000 096	0.0000009599 7788	1.51333 3333	1.51333 2873	0.0000004605 47730	0.76666 66667	0.76665 8447	0.0000008219 52071
0.4	1.04	1.03999 9975	0.0000000249 5013	1.55333 3333	1.55333 3413	0.0000000792 8579	0.86666 66667	0.86666 36607	0.0000030059 964
0.6	1.09	1.08999 7698	0.0000023016 2855	1.62	1.62000 1073	0.0000010726 5340	0.96666 66667	0.96667 3803	0.0000071362 43
0.8	1.16	1.16000 4458	0.0000044583 5934	1.71333 3333	1.71333 0858	0.0000024753 2844	1.06666 6667	1.06665 8534	0.0000081324 58
1	1.25	1.24997 7054	0.0000229459 3658	1.83333 3333	1.83346 595	0.0000132612 6583	1.16666 6667	1.16671 0616	0.0000439496 41

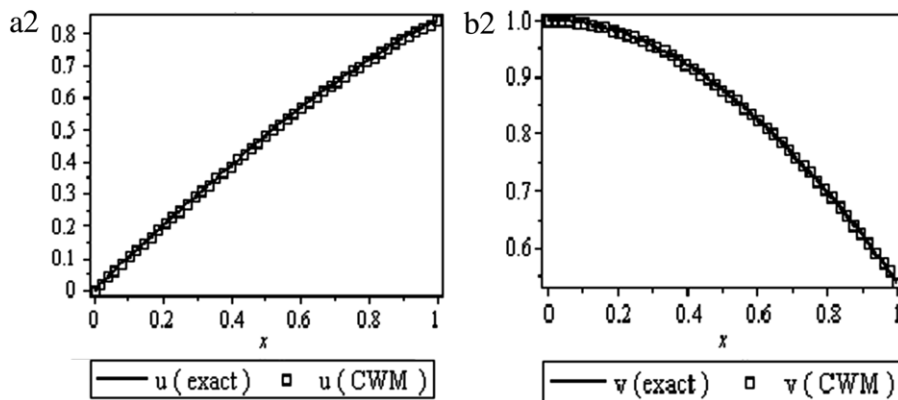


Fig. 2. (a2) and (b2) comparison of the exact and approximate solutions of Example 2.

$$C_2 = [2.036637098, 0.1477068045, 0.03692842611, 0.2315201546 \times 10^{-5}, 0.2139368296 \times 10^{-5}, 0.1528559747 \times 10^{-5}]^T,$$

$$C_3 = [1.148875490, 0.2215642788, 0.5944442817 \times 10^{-5}, 0.7599016308 \times 10^{-5}, 0.6251581812 \times 10^{-5}, 0.8638907550 \times 10^{-5}]^T.$$

Therefore, we have the following approximate solutions

$$u(x) \simeq C_1^T \psi(x) = -0.001676110122x^5 + 0.003634336424x^4 - 0.002695611180x^3 + 0.2507910494x^2 - 0.00007776845858x + 1.000001158,$$

$$v(x) \simeq C_2^T \psi(x) = 0.0008830950267x^5 - 0.001898743184x^4 + 0.001397379211x^3 + 0.3329250622x^2 + 0.00004044331183x + 1.499999358,$$

$$w(x) \simeq C_3^T \psi(x) = 0.004990957212x^5 - 0.01157446124x^4 + 0.009386241600x^3 - 0.003128439331x^2 + 0.5003793796x + 0.6666569385.$$

Some values of exact, approximate solutions and absolute errors are presented in Table 3 and the plots of exact and approximate solutions are shown in Fig. 3.

### 6. Conclusion

The aim of this paper is to develop Chebyshev wavelets method for obtaining the solutions of nonlinear systems of Volterra integral equations. Illustrative examples are included to demonstrate that the method is a very effective and useful technique for finding approximate solutions of these systems. In [9,10], examples (2) and (3) were solved by the Homotopy perturbations method and comparison between the obtained absolute error values in [9,10] and this paper shows that the absolute error values of the Chebyshev wavelets method are less than the absolute error values of the Homotopy perturbations method. Research for finding more applications of this method and other orthogonal basis functions is one of the goals of our research group. Here, the computations associated with these examples are performed by the package Maple 13.



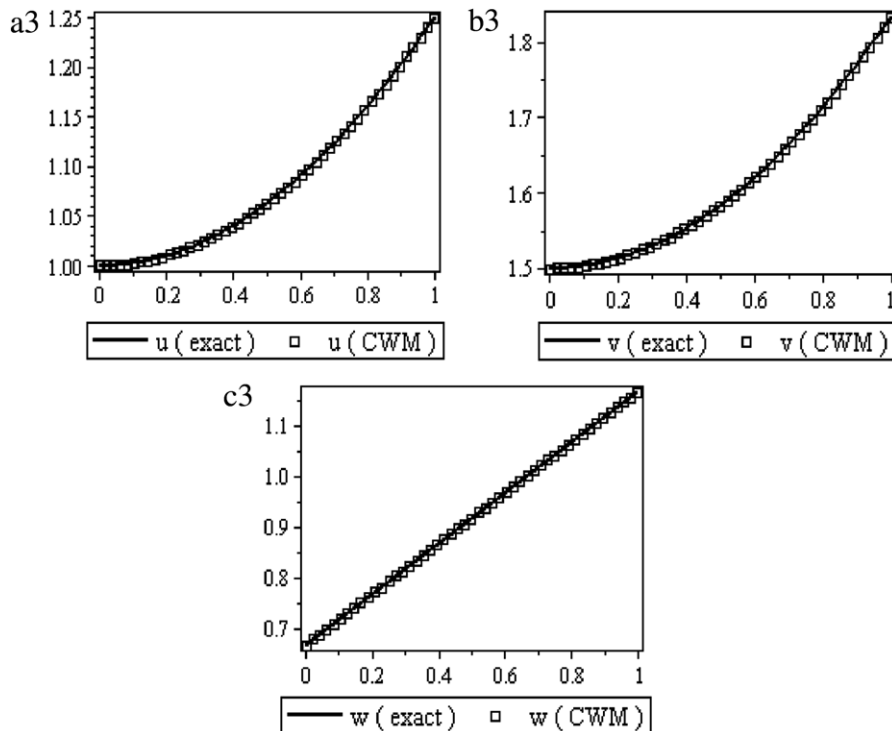


Fig. 3. (a3), (b3) and (c3) comparison of the exact and approximate solutions of Example 3.

## References

- [1] E. Babolian, F. Fattahzadeh, Numerical computation method in solving integral equations by using Chebyshev wavelet operational matrix of integration, *Applied Mathematics and Computations* 188 (2007) 1016–1022.
- [2] E. Babolian, F. Fattahzadeh, Numerical solution of differential equations by using Chebyshev wavelet operational matrix of integration, *Applied Mathematics and Computations* 188 (2007) 417–426.
- [3] Y. Li, Solving a nonlinear fractional differential equation using Chebyshev wavelets, *Communications in Nonlinear Science and Numerical Simulation* 15 (2010) 2284–2292.
- [4] L.M. Delves, J.L. Mohamed, *Computational Methods for Integral Equations*, Cambridge University, 1988.
- [5] A.J. Jerri, *Introduction to Integral Equation with Applications*, 2nd ed., John Wiley and Sons, Inc., New York, 1999.
- [6] P. Linz, *Analytical and Numerical Methods for Volterra Equations*, SIAM, Philadelphia, PA, 1985.
- [7] J. Biazar, E. Babolian, R. Islam, Solution of a system of Volterra integral equations of the first kind by Adomian method, *Applied Mathematics and Computation* 139 (2003) 249–258.
- [8] E. Babolian, J. Biazar, A.R. Vahidi, On the decomposition method for system of linear equations and system of linear Volterra integral equation, *Applied Mathematics and Computation* 147 (2004) 19–27.
- [9] J. Biazar, M. Eslami, H. Aminikhah, Application of homotopy perturbation method for systems of Volterra integral equations of the first kind, *Chaos, Solitons and Fractals* 42 (2009) 3020–3026.
- [10] J. Biazar, H. Ghazvini, He's homotopy perturbation method for solving systems of Volterra integral equations of the second kind, *Chaos, Solitons and Fractals* 39 (2009) 770–777.
- [11] J. Biazar, H. Ebrahimi, Existence and uniqueness of the solution of non-linear systems of Volterra integral equations of the second kind, *Journal of Advanced Research in Applied Mathematics* 2 (4) (2010) 39–51.
- [12] M. Dehghan, M. Shakourifar, A. Hamidi, The solution of linear and nonlinear systems of Volterra functional equations using Adomian–Pade technique, *Chaos, Solitons and Fractals* 39 (2009) 2509–2521.
- [13] K. Maleknejad, M. Shahrezaee, Using Runge–Kutta method for numerical solution of the system of Volterra integral equation, *Applied Mathematics and Computation* 149 (2004) 399–410.
- [14] A. Golbabai, M. Mammadov, S. Seifollahi, Solving a system of nonlinear integral equations by an RBF network, *Computers and Mathematics with Applications* 57 (2009) 1651–1658.
- [15] R. Katani, S. Shahmorad, Block by block method for the systems of nonlinear Volterra integral equations, *Applied Mathematical Modelling* 34 (2010) 400–406.
- [16] I. Daubechies, *Ten lectures on wavelets*, CBMS-NSF, 1992.
- [17] Ole Christensen, Khadjia L. Christensen, *Approximation Theory: from Taylor Polynomial to Wavelets*, Birkhauser, Boston, 2004.
- [18] D. Gottlieb, S.A. Orszag, *Numerical Analysis of Spectral Methods*, SIAM, Philadelphia, PA, 1997.