

## On a Characterization of Directed Divergence\*

P L. KANNAPPAN

*Faculty of Mathematics, University of Waterloo, Waterloo, Ontario*

AND

P. N. RATHIE

*Department of Mathematics, M.R. Engineering College, Jaipur, India*

Shannon's entropy was characterized by many authors by assuming different sets of postulates. One other measure associated with Shannon's entropy is directed divergence or information gain. In this paper, a characterization theorem for the measure directed divergence is given by assuming intuitively reasonable postulates and with the help of functional equations.

### 1. INTRODUCTION

Consider two finite discrete probability distributions

$$P = (p_1, p_2, \dots, p_n), \quad Q = (q_1, q_2, \dots, q_n),$$

with

$$p_i \geq 0, \quad \sum_{i=1}^n p_i = 1 \quad \text{with} \quad q_j \geq 0, \quad 1 = \sum_{j=1}^n q_j,$$

where the correspondence between the elements of the two distributions are given by their suffices. Then a measure of directed divergence (Kullback, 1959) or information gain (Renyi, 1961) is defined as

$$I_n \left( \begin{matrix} p_1, p_2, \dots, p_n \\ q_1, q_2, \dots, q_n \end{matrix} \right) = \sum_{i=1}^n p_i \log \frac{p_i}{q_i}. \quad (1.1)$$

Throughout this paper,  $\sum$  will stand for the sum  $\sum_{i=1}^n$ ; the logarithm will be taken to the base 2. In (1.1), whenever  $q_i = 0$ , the corresponding  $p_i = 0$ ;

\* This work is partially supported by a National Research Council of Canada grant.

and the convention  $0 \cdot \log 0 = 0 = 0 \cdot \log(0/q_i)$  is followed. These conventions are not used in the proof of the characterization theorem in Section 3.

One interpretation for (1.1) may be given as follows. The quantity  $-\log p_i$ , in communication theory is usually known as the "information content" in the event  $E_i$  with probability  $p_i$  or the amount of "self information" associated with the event  $E_i$ . Thus  $\log(p_i/q_i) = \log p_i - \log q_i$  may be taken as the "information gain" in predicting the event  $E_i$ . Therefore (1.1) is the average "information gain". The quantity defined in (1.1) is also interpreted as the mean information for discrimination in favor of hypothesis  $H_1$  against hypothesis  $H_2$  in statistical inference problems (Kullback, 1959). Kerridge (1961) interprets (1.1) as a measure of the error made by the observer in estimating a discrete probability distribution as  $Q$  which is in fact  $P$ . For interpretations of (1.1) in econometric problems see Theil (1967).

Characterizations of (1.1) in arbitrary probability spaces and continuous analogs are given earlier by Campell (1970, 1970A), Kullback and Khairat (1966), Hobson (1969), Rathie and Kannappan (1971) and Reyni (1961).

The object of this paper is to give a characterization theorem for the measure of information defined in (1.1) by assuming reasonable postulates, parallel to that of Shannon's entropy. A method similar to that employed in Kendall (1964) is followed here in arriving at the characterization theorem.

## 2. POSTULATES

In this section we give a set of five postulates which will be used in establishing a characterization theorem for (1.1) in the next section. The postulates are:

### POSTULATE 2.1—Recursivity

$$I_n \left( \begin{matrix} p_1, \dots, p_n \\ q_1, \dots, q_n \end{matrix} \right) = I_{n-1} \left( \begin{matrix} p_1 + p_2, p_3, \dots, p_n \\ q_1 + q_2, q_3, \dots, q_n \end{matrix} \right) \\ + (p_1 + p_2) I_2 \left( \begin{matrix} p_1/(p_1 + p_2), p_2/(p_1 + p_2) \\ q_1/(q_1 + q_2), q_2/(q_1 + q_2) \end{matrix} \right),$$

for  $p_1 + p_2 > 0$ ,  $q_1 + q_2 > 0$  and for all  $n = 3, 4, \dots$

### POSTULATE 2.2—Symmetry

$$I_3 \left( \begin{matrix} p_1, p_2, p_3 \\ q_1, q_2, q_3 \end{matrix} \right) \text{ is symmetric in pairs } \left\{ \begin{matrix} p_i \\ q_i \end{matrix} \right\} \quad i = 1, 2, 3.$$

POSTULATE 2.3—Derivative. *Let*

$$f(p, q) = I_2 \left( \begin{matrix} p, 1-p \\ q, 1-q \end{matrix} \right), \quad \text{for } (p, q) \in J,$$

where  $J = ]0, 1[ \times ]0, 1[ \cup \{(0, y)\} \cup \{(1, y')\}$  with  $y \in [0, 1)$  and  $y' \in ]0, 1]$ . Also the function  $f$  has continuous first partial derivatives with respect to both variables  $p, q \in (0, 1)$ .

POSTULATE 2.4—Normalization

$$I_2 \left( \begin{matrix} \frac{2}{3}, \frac{1}{3} \\ \frac{1}{3}, \frac{2}{3} \end{matrix} \right) = \frac{1}{3}.$$

POSTULATE 2.5—Nullity

$$I_2 \left( \begin{matrix} p, 1-p \\ p, 1-p \end{matrix} \right) = 0, \quad \text{for } p \in (0, 1).$$

Now we discuss the postulates one by one. The Postulate 2.1 suggests the way in which the measures are added up when the union of two mutually exclusive events are considered. In other words, if an event is split into two mutually exclusive events then the measure is a weighted sum with the weights being probabilities as given above. The Postulate 2.2 says that the directed divergence does not depend on the order in which the possible outcomes are labeled. For mathematical purposes the assumption of symmetry for  $n = 3$  is enough to establish the theorem. The Postulate 2.3 is a regularity postulate. The Postulate 2.4 is a normalization postulate which fixes the unit for measurement of the directed divergence. The Postulate 2.5 says that if there is no divergence between the two distributions then the measure vanishes.

### 3. CHARACTERIZATION THEOREM

In this section we prove the following theorem regarding directed divergence (1.1) given by the set of five postulates of the Section 2.

THEOREM. *The function*

$$I_n \left( \begin{matrix} p_1, p_2, \dots, p_n \\ q_1, q_2, \dots, q_n \end{matrix} \right) \quad \text{for } p_i \geq 0, \quad q_i \geq 0,$$

$\sum p_i = 1 = \sum q_i$ , satisfying the postulates 2.1, 2.2, 2.3, 2.4, and 2.5 described in Section 2, is the directed divergence given by

$$I_n \left( \begin{matrix} p_1, p_2, \dots, p_n \\ q_1, q_2, \dots, q_n \end{matrix} \right) = \sum p_i \log \frac{p_i}{q_i}. \tag{1.1}$$

*Proof.* First we will show that  $I_2$  is symmetric. For  $n = 3$ , Postulate 2.1 gives

$$I_3 \left( \begin{matrix} p_1, p_2, p_3 \\ q_1, q_2, q_3 \end{matrix} \right) = I_2 \left( \begin{matrix} p_1 + p_2, p_3 \\ q_1 + q_2, q_3 \end{matrix} \right) + (p_1 + p_2) I_2 \left( \begin{matrix} p_1/(p_1 + p_2), p_2/(p_1 + p_2) \\ q_1/(q_1 + q_2), q_2/(q_1 + q_2) \end{matrix} \right) \tag{3.1}$$

for  $p_1 + p_2 > 0, q_1 + q_2 > 0$ . Also from (3.1) for  $n = 3$ , we have

$$I_3 \left( \begin{matrix} p_2, p_1, p_3 \\ q_2, q_1, q_3 \end{matrix} \right) = I_2 \left( \begin{matrix} p_2 + p_1, p_3 \\ q_2 + q_1, q_3 \end{matrix} \right) + (p_2 + p_1) I_2 \left( \begin{matrix} p_2/(p_2 + p_1), p_1/(p_2 + p_1) \\ q_2/(q_2 + q_1), q_1/(q_2 + q_1) \end{matrix} \right), \tag{3.2}$$

for  $p_2 + p_1 > 0, q_2 + q_1 > 0$ ,

Hence (3.2), (3.1), and Postulate 2.2 give

$$I_2 \left( \begin{matrix} p_1/(p_1 + p_2), p_2/(p_1 + p_2) \\ q_1/(q_1 + q_2), q_2/(q_1 + q_2) \end{matrix} \right) = I_2 \left( \begin{matrix} p_2/(p_1 + p_2), p_1/(p_1 + p_2) \\ q_2/(q_1 + q_2), q_1/(q_1 + q_2) \end{matrix} \right), \tag{3.3}$$

for  $p_1 + p_2 > 0, q_1 + q_2 > 0$ , which shows that  $I_2 \left( \begin{smallmatrix} a_1, a_2 \\ y_1, y_2 \end{smallmatrix} \right)$  is symmetric in pairs  $\{y_i\}, i = 1, 2$ . In particular (3.3) gives

$$f(0, 0) = f(1, 1). \tag{3.4}$$

Next we will obtain an expression for  $f(x, y)$ . The Postulate 2.2 gives

$$I_3 \left( \begin{matrix} p_1, p_2, p_3 \\ q_1, q_2, q_3 \end{matrix} \right) = I_3 \left( \begin{matrix} p_2, p_3, p_1 \\ q_2, q_3, q_1 \end{matrix} \right) = I_3 \left( \begin{matrix} p_3, p_1, p_2 \\ q_3, q_1, q_2 \end{matrix} \right),$$

which on using Postulate 2.1 for  $n = 3$  and the representation in Postulate 2.3 yields the following functional equations,

$$\begin{aligned} & f(p_1 + p_2, q_1 + q_2) + (p_1 + p_2) f \left[ \begin{matrix} p_1/(p_1 + p_2), q_1/(q_1 + q_2) \end{matrix} \right] \\ &= f(p_1, q_1) + (1 - p_1) f \left[ \begin{matrix} p_2/(1 - p_1), q_2/(1 - q_1) \end{matrix} \right] \\ &= f(p_2, q_2) + (1 - p_2) f \left[ \begin{matrix} p_1/(1 - p_2), q_1/(1 - q_2) \end{matrix} \right], \\ & \text{for } p_1, p_2, q_1, q_2 \in [0, 1], p_1 + p_2, q_1 + q_2 \in (0, 1]. \end{aligned} \tag{3.5}$$

Denoting the partial derivative of  $f$  with respect to the first variable by  $f_1$  and differentiating partially with respect to  $p_1$  the equation comprised of the first and third lines of (3.5) we have

$$\begin{aligned} & f_1(p_1 + p_2, q_1 + q_2) + f[p_1/(p_1 + p_2), q_1/(q_1 + q_2)] \\ & \quad + p_2/(p_1 + p_2) f_1[p_1/(p_1 + p_2), q_1/(q_1 + q_2)] \\ & = f_1[p_1/(1 - p_2), q_1/(1 - q_2)], \\ & \quad \text{for } p_1, q_1 \in (0, 1), p_2, q_2 \in [0, 1) \text{ with } p_1 + p_2, q_1 + q_2 \in (0, 1]. \end{aligned} \quad (3.6)$$

Also differentiating partially with respect to  $p_2$  the equation comprised of the first and second lines of (3.5), we have

$$\begin{aligned} & f_1(p_1 + p_2, q_1 + q_2) + f[p_1/(p_1 + p_2), q_1/(q_1 + q_2)] \\ & \quad - p_1/(p_1 + p_2) f_1[p_1/(p_1 + p_2), q_1/(q_1 + q_2)] \\ & = f_1[p_2/(1 - p_1), q_2/(1 - q_1)], \\ & \quad \text{for } p_2, q_2 \in (0, 1), p_1, q_1 \in [0, 1) \text{ with } p_1 + p_2, q_1 + q_2 \in (0, 1]. \end{aligned} \quad (3.7)$$

Hence subtracting (3.7) from (3.6) gives

$$\begin{aligned} & f_1[p_1/(p_1 + p_2), q_1/(q_1 + q_2)] \\ & \quad = f_1[p_1/(1 - p_2), q_1/(1 - q_2)] - f_1[p_2/(1 - p_1), q_2/(1 - q_1)], \\ & \quad \text{for } p_1, p_2, q_1, q_2 \in (0, 1), p_1 + p_2, q_1 + q_2 \in (0, 1]. \end{aligned} \quad (3.8)$$

Taking  $p_1 = xy/(1 + y + xy)$ ,  $p_2 = y/(1 + y + xy)$ ,  $q_1 = uv/(1 + v + uv)$  and  $q_2 = v/(1 + v + uv)$  in (3.8) we get

$$\begin{aligned} & f_1[x/(1 + x), u/(1 + u)] \\ & \quad = f_1[xy/(1 + y + xy), uv/(1 + v + uv)] - f_1[y/(1 + y), v/(1 + v)] \\ & \quad \quad \quad \text{for } x, y, u, v \in (0, \infty). \end{aligned} \quad (3.9)$$

Let

$$F(x, u) = f_1[x/(1 + x), u/(1 + u)], \quad \text{for } x, u \in (0, \infty). \quad (3.10)$$

Then, since  $f_1$  is continuous, so is  $F$ .

Then (3.9) with the help of (3.10) gives

$$F(x, u) + F(y, v) = F(xy, uv), \quad \text{for } x, y, u, v \in (0, \infty). \quad (3.11)$$

Taking  $u = v = 1$  in (3.11), we have

$$F(x, 1) + F(y, 1) = F(xy, 1), \quad \text{for } x, y \in (0, \infty). \quad (3.12)$$

Equation (3.12) is the well known Cauchy equation with the continuous solution given by Aczel (1966),

$$F(x, 1) = a \log x, \quad x \in (0, \infty), \quad (3.13)$$

where  $a$  is an arbitrary real constant.

Similarly, taking  $x = y = 1$  in (3.11), we have

$$F(1, u) = b \log u, \quad u \in (0, \infty) \quad (3.14)$$

where  $b$  is an arbitrary real constant.

Again, taking  $u = 1, y = 1$  in (3.11), we have

$$F(x, v) = F(x, 1) + F(1, v). \quad (3.15)$$

Hence (3.13), (3.14), and (3.15) give

$$F(x, v) = a \log x + b \log v, \quad \text{for } x, v \in (0, \infty), \quad (3.16)$$

where  $a$  and  $b$  are arbitrary real constants.

Thus (3.16) and (3.10) give

$$f_1(x, y) = a \log[x/(1-x)] + b \log[y/(1-y)], \quad \text{for } x, y \in (0, 1), \quad (3.17)$$

which on integration gives

$$f(x, y) = a\{x \log(x/2) + (1-x) \log[(1-x)/2]\} + bx \log[y/(1-y)] + g(y), \quad (3.18)$$

for  $x, y \in (0, 1)$ , where  $g$  is a function of  $y$  alone.

Hence (3.18) and (2.5) give

$$\begin{aligned} g(x) = & -a\{x \log(x/2) + (1-x) \log[(1-x)/2]\} \\ & - bx \log[x/(1-x)], \quad \text{for } x \in (0, 1). \end{aligned} \quad (3.19)$$

Therefore (3.18) and (3.19) yield

$$\begin{aligned} f(x, y) = & a[x \log x + (1-x) \log(1-x) - y \log y - (1-y) \log(1-y)] \\ & + b(x-y) \log[y/(1-y)], \quad \text{for } x, y \in (0, 1). \end{aligned} \quad (3.20)$$

Taking  $x = \frac{2}{3}, y = \frac{1}{3}$  in (3.20) and utilizing (2.4) we get

$$b = -1. \quad (3.21)$$

Again taking  $p_1 = q_1 = \frac{1}{4}$ ,  $p_2 = \frac{2}{3}$ ,  $q_2 = \frac{1}{3}$  in the second and third equation pair of (3.5) for  $f$ , that is,

$$\begin{aligned} f(p_1, q_1) + (1 - p_1)f[p_2/(1 - p_1), q_2/(1 - q_1)] \\ = f(p_2, q_2) + (1 - p_2)f[p_1/(1 - p_2), q_1/(1 - q_2)], \end{aligned} \tag{3.22}$$

for  $p_1, p_2, q_1, q_2 \in [0, 1], p_1 + p_2, q_1 + q_2 \in (0, 1]$ , we have

$$f(\frac{1}{4}, \frac{1}{4}) + \frac{2}{3}f(\frac{2}{3}, \frac{1}{3}) = f(\frac{2}{3}, \frac{1}{3}) + \frac{1}{3}f(\frac{1}{4}, \frac{3}{8}). \tag{3.23}$$

Thus (3.23), (3.21), Postulate 2.5, Postulate 2.4 and (3.20) give

$$a = 1. \tag{3.24}$$

Hence (3.20), (3.21) and (3.24) yield

$$f(x, y) = x \log(x/y) + (1 - x) \log[(1 - x)/(1 - y)], \quad \text{for } x, y \in (0, 1). \tag{3.25}$$

Next we have to determine  $f(0, y)$  and  $f(1, y)$ , where  $y \in (0, 1)$ .

Taking  $p_1 = 0$  in (3.22), we have

$$f(0, q_1) + f[p_2, q_2/(1 - q_1)] = f(p_2, q_2) + (1 - p_2)f[0, q_1/(1 - q_2)], \tag{3.26}$$

for  $p_2, q_2 \in (0, 1), q_1 \in [0, 1], q_1 + q_2 \in (0, 1]$ .

For  $q_1 = \frac{1}{2}, q_2 = \frac{1}{4}$ , (3.26) reduces to

$$f(0, \frac{1}{2}) + f(p_2, \frac{1}{2}) = f(p_2, \frac{1}{4}) + (1 - p_2)f(0, \frac{2}{3}), \quad \text{for } p_2 \in (0, 1). \tag{3.27}$$

The equation (3.27) for  $p_2 = \frac{1}{2}$ , with the help of (2.5) gives

$$f(0, \frac{1}{2}) = f(\frac{1}{2}, \frac{1}{4}) + \frac{1}{2}f(0, \frac{2}{3}). \tag{3.28}$$

Thus (3.28), (3.27) and (3.25) imply

$$f(0, \frac{1}{2}) = 1. \tag{3.29}$$

Taking  $q_2 = 1 - 2q_1$ , in (3.26) and utilizing (3.29) and (3.25), (3.26) gives

$$f(0, q_1) = -\log(1 - q_1), \quad \text{for } q_1 \in (0, \frac{1}{2}). \tag{3.30}$$

Again putting  $q_2 = \frac{1}{2}$  in (3.26) and using (3.25) and (3.30), we get

$$f(0, 2q_1) = -\log(1 - 2q_1), \quad \text{for } 2q_1 \in (0, 1). \tag{3.31}$$

Hence (3.30) and (3.31) yield

$$f(0, q) = -\log(1 - q), \quad \text{for } q \in (0, 1). \quad (3.32)$$

The symmetry of  $I_2$  will imply

$$f(p, q) = f(1 - p, 1 - q), \quad \text{for } p, q \in J, \text{ with } f(0, 0) = f(1, 1) = 0, \quad (3.33)$$

[obtained by putting  $p_1 = 0 = q_1$ , in the last two equations of (3.5)] from which on using (3.32) we get

$$f(1, q) = -\log q, \quad \text{for } q \in (0, 1). \quad (3.34)$$

Hence (3.25), (3.32), (3.34) and  $f(0, 0) = 0 = f(1, 1)$ , imply

$$f(x, y) = x \log(x/y) + (1 - x) \log[(1 - x)/(1 - y)], \quad \text{for } (x, y) \in J. \quad (3.35)$$

Now repeated application of Postulate 2.1 gives

$$I_n \left( \begin{matrix} p_1, \dots, p_n \\ q_1, \dots, q_n \end{matrix} \right) = \sum_{i=2}^n r_i I_2 \left( \begin{matrix} r_{i-1}/r_i, p_i/r_i \\ s_{i-1}/s_i, q_i/s_i \end{matrix} \right), \quad (3.36)$$

where  $r_i = p_1 + \dots + p_i$  and  $s_i = q_1 + \dots + q_i$ ; which on using (3.35) proves the theorem. This completes the proof of this theorem.

RECEIVED: May 15, 1972

#### REFERENCES

- ACZEL, J. (1966), "Lectures on Functional Equations and Their Applications," Academic Press, New York.
- CAMPBELL, L. L. (1970), Equivalence of Gauss's principle and minimum discrimination information estimation by probabilities, *Ann. Math. Statist.* **41**, 1011-1015.
- CAMPBELL, L. L. (1970A), Characterization of Entropy in Arbitrary Probability Spaces, Queen's University Preprint No. 1970-32, Kingston, Ontario, Canada.
- HOBSON, A. (1969), A new theorem of information theory, *J. Statist. Phys.* **1**, 383-391.
- KENDALL, D. G. (1964), Functional equations in information theory, *Z. Wahr. Verw. Geb.* **2**, 225-229.
- KERRIDGE, D. F. (1961), Inaccuracy and inference, *J. Roy. Statist. Soc.* **23**, 184-194.
- KULLBACK, S. (1959), "Information Theory and Statistics," Wiley, New York.
- KULLBACK, S., AND LEIBLER, R. A. (1951), On information and sufficiency, *Ann. Math. Statist.* **22**, 79-86.



- KULLBACK, S., AND KHAIRAT, M. A. (1966), A note on minimum discrimination information, *Ann. Math. Statist.* **37**, 279-280.
- RATHIE, P. N., AND KANNAPPAN, P. L. (1971), On a new characterization of directed-divergence, in "Information Theory," 6th Prague Conference on Information Theory, Statistical Decision Functions and Random Processes, September 19-25, 1971.
- RENYI, A. (1961), On measures of entropy and information, *Proc. Fourth Berkeley Symp. Math. Statist. Probabil.* **1**, 547-561.
- THEIL, H. (1967), "Economics and Information Theory," North-Holland, Amsterdam.