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Cartan subalgebras of root-reductive Lie algebras *

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Abstract

Root-reductive Lie algebras are direct limits of finite-dimensional reductive Lie algebras under injections which preserve the root spaces. It is known that a root-reductive Lie algebra is a split extension of an abelian Lie algebra by a direct sum of copies of finite-dimensional simple Lie algebras as well as copies of the three simple infinite-dimensional root-reductive Lie algebras \mathfrak{sl}_{∞} , \mathfrak{so}_{∞} , and \mathfrak{sp}_{∞} . As part of a structure theory program for root-reductive Lie algebras, Cartan subalgebras of the Lie algebra \mathfrak{gl}_{∞} were introduced and studied in [K.-H. Neeb, I. Penkov, Cartan subalgebras of \mathfrak{gl}_{∞} , Canad. Math. Bull. 46 (2003) 597–616].

In the present paper we refine and extend the results of [K.-H. Neeb, I. Penkov, Cartan subalgebras of \mathfrak{gl}_{∞} , Canad. Math. Bull. 46 (2003) 597–616] to the case of a general root-reductive Lie algebra \mathfrak{g} . We prove that the Cartan subalgebras of \mathfrak{g} are the centralizers of maximal toral subalgebras and that they are nilpotent and self-normalizing. We also give an explicit description of all Cartan subalgebras of the simple Lie algebra \mathfrak{sl}_{∞} , \mathfrak{so}_{∞} , and \mathfrak{sp}_{∞} .

We conclude the paper with a characterization of the set of conjugacy classes of Cartan subalgebras of the Lie algebras \mathfrak{gl}_{∞} , \mathfrak{sl}_{∞} , \mathfrak{so}_{∞} , and \mathfrak{sp}_{∞} with respect to the group of automorphisms of the natural representation which preserve the Lie algebra.

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1. Introduction

In this paper we continue the study of Cartan subalgebras of infinite-dimensional root-reductive Lie algebras initiated in [NP]. We refine and extend the description of Cartan subalgebras of \mathfrak{gl}_{∞} given in [NP] to the case of a general root-reductive Lie algebra. We also solve the problem of describing the set of conjugacy classes of Cartan subalgebras of the three simple root-reductive Lie algebras \mathfrak{sl}_{∞} , \mathfrak{so}_{∞} , \mathfrak{sp}_{∞} , as well as of \mathfrak{gl}_{∞} , under the group of automorphisms of the natural representation which preserve the Lie algebra. Root-reductive Lie algebras are a specific class of locally finite Lie algebras, and as background literature on locally finite Lie algebras we recommend [BB,BS,B1,B2,BZ,DP].

Here is a description of the contents of the paper. Its first main part, Sections 3 and 4, is concerned with the definition and description of Cartan subalgebras. According to [NP], a Cartan subalgebra of \mathfrak{gl}_{∞} can be defined as a locally nilpotent subalgebra which is the centralizer of the set of all semisimple parts of its own elements. We accept this definition for any locally reductive Lie algebra \mathfrak{g} and prove that similarly to the case of \mathfrak{gl}_{∞} , Cartan subalgebras are nothing but centralizers of arbitrary maximal toral subalgebras. In particular, a Cartan subalgebra is always self-normalizing. We then prove that a Cartan subalgebra can be characterized equivalently as a subalgebra $\mathfrak{h} \subseteq \mathfrak{g}$ which coincides with the set of $\mathfrak{h}_{\text{fin}}$ -locally nilpotent vectors in \mathfrak{g} , where $\mathfrak{h}_{\text{fin}}$ runs over all finite-dimensional subalgebras of \mathfrak{h} . In addition, we show that if \mathfrak{g} is a root-reductive Lie algebra, any Cartan subalgebra \mathfrak{h} is nilpotent and coincides with the set of all \mathfrak{h} -locally nilpotent vectors in \mathfrak{g} . The main new phenomenon in the case of a general root-reductive Lie algebra versus the case of \mathfrak{gl}_{∞} is that Cartan subalgebras are no longer necessarily commutative and that the adjoint action of a Cartan subalgebra \mathfrak{h} on itself no longer has to be locally finite.

We treat in detail the simple Lie algebras \mathfrak{sl}_{∞} , \mathfrak{so}_{∞} , and \mathfrak{sp}_{∞} . The case of \mathfrak{sl}_{∞} is very similar to the case of \mathfrak{gl}_{∞} considered in [NP]. The main new result in the other two cases is that maximal toral subalgebras are in one-to-one correspondence with maximal orthogonal or symplectic self-dual systems of 1-dimensional subspaces in the natural representation. Similarly to the case of \mathfrak{gl}_{∞} , such maximal self-dual systems do not have to span the natural representation, a phenomenon that gives rise to nonsplitting maximal toral subalgebras. In the case of \mathfrak{so}_{∞} , the centralizer of a maximal toral subalgebra is in general nilpotent of depth no greater than 2 but not necessarily commutative. Remarkably enough, the ideal of nilpotent elements of a Cartan subalgebra of \mathfrak{so}_{∞} is itself a nilpotent orthogonal Lie algebra of a vector space with a degenerate symmetric form, and all such nilpotent degenerate algebras occur inside Cartan subalgebras of \mathfrak{so}_{∞} . In the case of \mathfrak{sl}_{∞} , the analogous nilpotent degenerate subalgebras do not occur inside Cartan subalgebras of \mathfrak{sl}_{∞} , and for \mathfrak{gl}_{∞} and \mathfrak{sp}_{∞} , there are no analogous nilpotent nonabelian subalgebras, which is consistent with the fact that \mathfrak{gl}_{∞} , \mathfrak{sl}_{∞} , and \mathfrak{sp}_{∞} admit only abelian Cartan subalgebras.

In Section 5 we address the conjugacy problem for Cartan subalgebras posed in [NP]. More precisely, in the case of \mathfrak{gl}_{∞} it was established that certain standard discrete invariants of Cartan subalgebras are not sufficient to characterize the conjugacy classes of Cartan subalgebras of \mathfrak{gl}_{∞} with respect to the group of automorphisms of the natural representation which preserve \mathfrak{gl}_{∞} . In this paper we describe the missing continuous invariants in terms of a linear algebraic structure which we call a complement datum. Our main theorem in the second part, Theorem 5.9, solves the conjugacy problem in terms of the combinatorics of complement data. It turns out that for a generic set of fixed standard invariants, there are uncountably many conjugacy classes of Cartan subalgebras. In all remaining cases, there are only finitely many conjugacy classes, and

in fact at most 2. We give criteria to distinguish the uncountable and finite cases and provide representatives in each finite case.

2. Preliminaries

All vector spaces and Lie algebras are defined over the field of complex numbers \mathbb{C} .

A Lie algebra \mathfrak{g} is *locally finite* (respectively *locally nilpotent*) if every finite subset of \mathfrak{g} is contained in a finite-dimensional (respectively nilpotent) subalgebra. If \mathfrak{g} is at most countable dimensional, then being locally finite is equivalent to being isomorphic to a union $\bigcup_{i \in \mathbb{Z}_{>0}} \mathfrak{g}_i$ of nested finite-dimensional Lie subalgebras $\mathfrak{g}_i \subseteq \mathfrak{g}_{i+1}$. A \mathfrak{g} -module M is *locally finite* if each element $m \in M$ is contained in a finite-dimensional submodule, and M is *locally nilpotent* if for any $m \in M$ there exists an $i \in \mathbb{Z}_{>0}$ with $\mathfrak{g}^i \cdot m = 0$. Furthermore, we say that a \mathfrak{g} -module M is a *generalized weight module* if $M = \bigoplus_{\lambda \in \mathfrak{g}^*} M^{\lambda}(\mathfrak{g})$, where

$$M^{\lambda}(\mathfrak{g}) := \{ m \in M \colon \exists i \in \mathbb{Z}_{>0} \text{ s.t. } \forall x \in \mathfrak{g}, \ \left(x - \lambda(x) 1 \right)^{l} \cdot m = 0 \}.$$

We define a generalized weight module M to be a weight module if in addition,

$$M^{\wedge}(\mathfrak{g}) = \left\{ m \in M \colon \forall x \in \mathfrak{g}, \ x \cdot m = \lambda(x)m \right\}$$

for each $\lambda \in \mathfrak{g}^*$. The *support* in \mathfrak{g}^* of a module *M* is the set

$$\operatorname{supp} M := \{ \alpha \in \mathfrak{g}^* \colon M^{\alpha}(\mathfrak{g}) \neq 0 \}.$$

For an arbitrary Lie subalgebra $\mathfrak{h} \subseteq \mathfrak{g}$, we set $\overline{\mathfrak{g}^0(\mathfrak{h})} = \bigcap_i \mathfrak{g}^0(\mathfrak{h}_i)$ where $\bigcup_i \mathfrak{h}_i = \mathfrak{h}$ is any exhaustion of \mathfrak{h} by finite-dimensional subalgebras \mathfrak{h}_i . In other words, $\overline{\mathfrak{g}^0(\mathfrak{h})}$ is the subalgebra of all $\mathfrak{h}_{\text{fin}}$ -locally nilpotent vectors in \mathfrak{g} , where $\mathfrak{h}_{\text{fin}}$ runs over all finite-dimensional subalgebras of \mathfrak{g} .

We call a Lie algebra *locally reductive* if it is the union $\bigcup_{i \in \mathbb{Z}_{>0}} \mathfrak{g}_i$ of nested finite-dimensional reductive Lie algebras \mathfrak{g}_i such that \mathfrak{g}_i is reductive in \mathfrak{g}_{i+1} . Recall that for finite-dimensional Lie algebras we have a notion of a Jordan decomposition, and in particular of semisimple elements and nilpotent elements. Since these notions are preserved under injections $\mathfrak{g}_i \hookrightarrow \mathfrak{g}_{i+1}$ where \mathfrak{g}_i is reductive in \mathfrak{g}_{i+1} , for any locally reductive Lie algebra we can talk about a *Jordan decomposition* of an element. In addition, note that any nilpotent element x of a locally reductive Lie algebra \mathfrak{g} lies in $[\mathfrak{g}, \mathfrak{g}]$. Indeed, $x \in \mathfrak{g}_i$ for some *i*, and thus $x \in [\mathfrak{g}_i, \mathfrak{g}_i] \subseteq [\mathfrak{g}, \mathfrak{g}]$.

We call a subalgebra \mathfrak{k} of a locally reductive Lie algebra \mathfrak{g} *splittable* if for every $k \in \mathfrak{k}$, both the semisimple and nilpotent Jordan components k_{ss} and k_{nil} of k belong to \mathfrak{k} . A subalgebra $\mathfrak{t} \subseteq \mathfrak{g}$ is *toral* if every element is semisimple. Every toral subalgebra is abelian: the standard proof of this fact extends from the case of a reductive Lie algebra to a locally reductive Lie algebra, cf. [NP]. By definition, a toral subalgebra $\mathfrak{t} \subseteq \mathfrak{g}$ is *splitting* if \mathfrak{g} is a weight module with respect to the adjoint action of \mathfrak{t} on \mathfrak{g} .

For any subset $\mathfrak{a} \subseteq \mathfrak{g}$ and any subalgebra $\mathfrak{k} \subseteq \mathfrak{g}$, we define the centralizer of \mathfrak{a} in \mathfrak{k} , denoted $\mathfrak{z}_{\mathfrak{k}}(\mathfrak{a})$, to be the set of elements of \mathfrak{k} which commute in \mathfrak{g} with all elements of \mathfrak{a} . The center of \mathfrak{g} is denoted $\mathfrak{z}(\mathfrak{g})$.

Let V and V_* be vector spaces of countable dimension with a nondegenerate pairing $\langle \cdot, \cdot \rangle : V \times V_* \to \mathbb{C}$. We define the Lie algebra $\mathfrak{gl}(V, V_*)$ to be the Lie algebra associated to the associative algebra $V \otimes V_*$ ($V \otimes V_*$ is an associative algebra whose multiplication satisfies $(v \otimes w) \cdot (v' \otimes w') = \langle v', w \rangle v \otimes w'$ for $v, v' \in V, w, w' \in V_*$). The derived subalgebra of

 $\mathfrak{gl}(V, V_*)$ has codimension 1 and is denoted $\mathfrak{sl}(V, V_*)$. If *V* is endowed with a nondegenerate symmetric (respectively antisymmetric) bilinear form, then one can choose $V_* = V$ and denote by $\mathfrak{so}(V)$ (respectively $\mathfrak{sp}(V)$) the Lie subalgebra $\bigwedge^2 V$ (respectively $\operatorname{Sym}^2(V)$) of the Lie algebra associated to the associative algebra $V \otimes V$.

A result of Mackey [M, p. 171] implies that all associative algebras $V \otimes V_*$ are isomorphic, as long as dim $V = \dim V_* = \aleph_0$ and the pairing $V \times V_* \to \mathbb{C}$ is nondegenerate. Hence, up to isomorphism, the Lie algebras $\mathfrak{gl}(V, V_*)$, $\mathfrak{sl}(V, V_*)$, $\mathfrak{sl}(V)$, and $\mathfrak{sp}(V)$ do not depend on V, and the usual representatives of these isomorphism classes are denoted \mathfrak{gl}_{∞} , \mathfrak{sl}_{∞} , \mathfrak{so}_{∞} , and \mathfrak{sp}_{∞} , respectively. Clearly the Lie algebras \mathfrak{gl}_{∞} , \mathfrak{sl}_{∞} , \mathfrak{so}_{∞} , and \mathfrak{sp}_{∞} are locally reductive, as one can also choose exhaustions $V = \bigcup_{i \in Z_{>0}} V_i$ and $V_* = \bigcup_{i \in Z_{>0}} W_i$ (where $V_i = W_i$ for $V = V_*$) such that the pairings $V_i \times W_i \to \mathbb{C}$ are nondegenerate.

3. Cartan subalgebras of locally reductive Lie algebras

Let \mathfrak{g} be a locally reductive Lie algebra. If \mathfrak{h} is a subalgebra of \mathfrak{g} , let \mathfrak{h}_{ss} denote the set of semisimple Jordan components of the elements of \mathfrak{h} . Following [NP], we say that a subalgebra \mathfrak{h} of \mathfrak{g} is a *Cartan subalgebra* if \mathfrak{h} is locally nilpotent and $\mathfrak{h} = \mathfrak{z}_{\mathfrak{g}}(\mathfrak{h}_{ss})$.

We start with the following proposition which generalizes a result of [NP].

Proposition 3.1. Let \mathfrak{h} be a locally nilpotent subalgebra of a locally reductive Lie algebra \mathfrak{g} . Then the following assertions hold:

(1) $\mathfrak{h} \subseteq \mathfrak{z}_{\mathfrak{g}}(\mathfrak{h}_{ss});$

- (2) \mathfrak{h}_{ss} is a toral subalgebra of \mathfrak{g} ;
- (3) $\mathfrak{z}_{\mathfrak{g}}(\mathfrak{h}_{ss})$ is a self-normalizing subalgebra of \mathfrak{g} .

Proof. Let $h, h' \in \mathfrak{h}$. The local nilpotence of \mathfrak{h} implies that $(ad h)^n(h') = 0$ for some n. Since $ad h_{ss}$ is a polynomial with no constant term in ad h, it follows that $(ad h_{ss})(ad h)^{n-1}(h') = 0$. Because an element commutes with its semisimple part, $(ad h)^{n-1}(ad h_{ss})(h') = 0$, and it follows by induction that $(ad h_{ss})^n(h') = 0$. Hence $(ad h_{ss})(h') = 0$. Thus $\mathfrak{h} \subseteq \mathfrak{z}_{\mathfrak{g}}(\mathfrak{h}_{ss})$.

Furthermore, by the same argument, $(ad h')(h_{ss}) = 0$ implies that $(ad h'_{ss})(h_{ss}) = 0$. Therefore any two elements of \mathfrak{h}_{ss} commute. Since the sum of any two commuting semisimple elements is semisimple, \mathfrak{h}_{ss} is a subalgebra.

Finally, suppose x is in the normalizer of $\mathfrak{z}_{\mathfrak{g}}(\mathfrak{h}_{ss})$. For any $y \in \mathfrak{h}_{ss}$, we have that $[x, y] \in \mathfrak{z}_{\mathfrak{g}}(\mathfrak{h}_{ss})$. Thus [[x, y], y] = 0, and as y is semisimple it follows that [x, y] = 0. Hence $x \in \mathfrak{z}_{\mathfrak{g}}(\mathfrak{h}_{ss})$, i.e. $\mathfrak{z}_{\mathfrak{g}}(\mathfrak{h}_{ss})$ is self-normalizing. \Box

The following theorem is our main general result characterizing Cartan subalgebras of locally reductive Lie algebras. It generalizes a well-known result for finite-dimensional reductive algebras (cf. [B, Chapitre VII, §4]), as well as a result from [NP].

Theorem 3.2. Let \mathfrak{g} be a locally reductive Lie algebra and \mathfrak{h} a subalgebra of \mathfrak{g} . The following conditions on \mathfrak{h} are equivalent:

- (1) h is a Cartan subalgebra;
- (2) $\mathfrak{h} = \mathfrak{z}_{\mathfrak{g}}(\mathfrak{h}_{ss})$ and \mathfrak{h}_{ss} is a subalgebra;

- (3) $\mathfrak{h} = \mathfrak{z}_{\mathfrak{g}}(\mathfrak{t})$ for some maximal toral subalgebra $\mathfrak{t} \subseteq \mathfrak{g}$;
- (4) $\mathfrak{h} = \mathfrak{g}^0(\mathfrak{h}).$

In addition, any Cartan subalgebra \mathfrak{h} is splittable and self-normalizing.

We first prove a short lemma.

Lemma 3.3. If \mathfrak{h} is locally nilpotent and splittable, then $\overline{\mathfrak{g}^0(\mathfrak{h})} = \mathfrak{z}_{\mathfrak{g}}(\mathfrak{h}_{ss})$.

Proof. By [B, Chapitre VII, §5, Proposition 5] $\mathfrak{h} = \mathfrak{h}_{ss} \oplus \mathfrak{h}_{nil}$, with \mathfrak{h}_{nil} being the subalgebra of all nilpotent elements in \mathfrak{h} . It follows that $\overline{\mathfrak{g}^0(\mathfrak{h})} = \overline{\mathfrak{g}^0(\mathfrak{h}_{ss})} \cap \overline{\mathfrak{g}^0(\mathfrak{h}_{nil})}$. Since elements of \mathfrak{h}_{ss} are semisimple, $\overline{\mathfrak{g}^0(\mathfrak{h}_{ss})} = \mathfrak{z}_{\mathfrak{g}}(\mathfrak{h}_{ss})$. Clearly $\overline{\mathfrak{g}^0(\mathfrak{h}_{nil})} = \mathfrak{g}$. Hence $\overline{\mathfrak{g}^0(\mathfrak{h})} = \mathfrak{z}_{\mathfrak{g}}(\mathfrak{h}_{ss})$. \Box

Proof of Theorem 3.2. Fix an exhaustion $\mathfrak{g} = \bigcup_{i \in \mathbb{Z}_{>0}} \mathfrak{g}_i$, where \mathfrak{g}_i is a finite-dimensional reductive Lie algebra with \mathfrak{g}_i reductive in \mathfrak{g}_{i+1} .

Clearly (1) implies (2), by Proposition 3.1(2). To show that (2) implies (1), we first prove that (2) implies that \mathfrak{h} is splittable. Suppose that \mathfrak{h} satisfies (2). For any $i \in \mathbb{Z}_{>0}$ note that

$$\mathfrak{h} \cap \mathfrak{g}_i = \mathfrak{z}_\mathfrak{g}(\mathfrak{h}_{ss}) \cap \mathfrak{g}_i = \bigcap_{k \ge i} (\mathfrak{z}_{\mathfrak{g}_k}(\mathfrak{h}_{ss} \cap \mathfrak{g}_k) \cap \mathfrak{g}_i).$$

Since dim $\mathfrak{g}_i < \infty$, we have $\mathfrak{h} \cap \mathfrak{g}_i = \mathfrak{z}_{\mathfrak{g}_j}(\mathfrak{h}_{ss} \cap \mathfrak{g}_j) \cap \mathfrak{g}_i$ for some sufficiently large $j \ge i$. Since $\mathfrak{h}_{ss} \cap \mathfrak{g}_j$ is a subalgebra of \mathfrak{g}_j , we know from [B, Chapitre VII, §5, Proposition 3, Corollaire 1] that $\mathfrak{z}_{\mathfrak{g}_j}(\mathfrak{h}_{ss} \cap \mathfrak{g}_j)$ is a splittable subalgebra of \mathfrak{g}_j . The reductive Lie algebra \mathfrak{g}_i is also splittable, by [B, Chapitre VII, §5, Proposition 2]. Then the intersection $\mathfrak{z}_{\mathfrak{g}_j}(\mathfrak{h}_{ss} \cap \mathfrak{g}_j) \cap \mathfrak{g}_i$ is splittable, too. Being a union of splittable algebras, \mathfrak{h} is splittable.

To show the local nilpotence of \mathfrak{h} , notice that the equality $\mathfrak{h} = \mathfrak{zg}(\mathfrak{h}_{ss})$ implies that every element of \mathfrak{h}_{ss} is in the center of \mathfrak{h} . Now consider a general element $h = h_{ss} + h_{nil} \in \mathfrak{h}$. Choose k such that $(ad h_{nil})^k = 0$. For any $x \in \mathfrak{h}$,

$$(ad h)^{k}(x) = (ad(h_{ss} + h_{nil}))^{k}(x) = (ad h_{nil})^{k}(x) = 0.$$

Hence \mathfrak{h} is locally nilpotent, i.e. (2) implies (1).

Next, it is clear that (2) implies (3). The equality $\mathfrak{h} = \mathfrak{zg}(\mathfrak{h}_{ss})$ shows that any semisimple element of \mathfrak{g} which centralizes \mathfrak{h}_{ss} is already in \mathfrak{h}_{ss} . Thus \mathfrak{h}_{ss} is a maximal toral subalgebra and (3) holds.

Let \mathfrak{h} satisfy (3). The same argument as above shows that \mathfrak{h} is splittable, whence $\mathfrak{h}_{ss} \subseteq \mathfrak{h}$. Then clearly $\mathfrak{t} \subseteq \mathfrak{h}_{ss}$. If $\mathfrak{t} \neq \mathfrak{h}_{ss}$, the existence of a semisimple element $h \in \mathfrak{h} \setminus \mathfrak{t}$ contradicts the maximality of \mathfrak{t} . Therefore $\mathfrak{t} = \mathfrak{h}_{ss}$, and (3) implies (2).

Note that (1) implies (4). Indeed, let \mathfrak{h} be a Cartan subalgebra. We know \mathfrak{h} is splittable and locally nilpotent, so by Lemma 3.3, $\mathfrak{h} = \mathfrak{z}_{\mathfrak{g}}(\mathfrak{h}_{ss}) = \overline{\mathfrak{g}^0}(\mathfrak{h})$.

To show that (4) implies (1), assume that $\mathfrak{h} = \mathfrak{g}^0(\mathfrak{h})$. Then clearly \mathfrak{h} is locally nilpotent. An argument similar to that above shows that \mathfrak{h} is also splittable. Indeed, for any $i \in \mathbb{Z}_{>0}$ we have

$$\overline{\mathfrak{g}^0(\mathfrak{h})} \cap \mathfrak{g}_i = \bigcap_{k \geqslant i} \bigl(\mathfrak{g}_k^0(\mathfrak{h} \cap \mathfrak{g}_k) \cap \mathfrak{g}_i \bigr).$$

The finite dimensionality of \mathfrak{g}_i yields $\overline{\mathfrak{g}^0(\mathfrak{h})} \cap \mathfrak{g}_i = \mathfrak{g}_j^0(\mathfrak{h} \cap \mathfrak{g}_j) \cap \mathfrak{g}_i$ for some sufficiently large $j \ge i$. It is well known that $\mathfrak{g}_j^0(\mathfrak{h} \cap \mathfrak{g}_j)$ is a splittable subalgebra of \mathfrak{g}_j , see [B, Chapitre VII, §1, Proposition 11]. Since \mathfrak{g}_i is also splittable, the intersection $\mathfrak{g}_j^0(\mathfrak{h} \cap \mathfrak{g}_j) \cap \mathfrak{g}_i$ is splittable, too. Hence $\mathfrak{g}^0(\mathfrak{h}) \cap \mathfrak{g}_i$ is splittable. Being a union of splittable algebras, \mathfrak{h} is splittable. Therefore Lemma 3.3 implies that $\mathfrak{h} = \overline{\mathfrak{g}^0(\mathfrak{h})} = \mathfrak{z}_\mathfrak{g}(\mathfrak{h}_{ss})$.

In addition, by Proposition 3.1(3), a subalgebra \mathfrak{h} satisfying (1) is self-normalizing. As we have already seen that a Cartan subalgebra is splittable, the proof of Theorem 3.2 is complete. \Box

The most common characterization of a Cartan subalgebra of a finite-dimensional Lie algebra is as a nilpotent self-normalizing subalgebra. According to Theorem 3.2, any Cartan subalgebra of a locally reductive Lie algebra is self-normalizing. Any Cartan subalgebra of a root-reductive Lie algebra is in addition nilpotent. In fact, we show in Theorem 4.12 that it is nilpotent of depth at most 2. In contrast with the case of \mathfrak{gl}_{∞} or \mathfrak{sl}_{∞} , where all Cartan subalgebras are abelian and hence act locally finitely on themselves for a trivial reason (cf. [NP]), the Cartan subalgebras of \mathfrak{so}_{∞} do not necessarily act locally finitely on themselves, as discussed at the end of Section 4.2 below. We do not know whether all nilpotent self-normalizing subalgebras of a root-reductive Lie algebra are Cartan subalgebras. We also do not know whether a Cartan subalgebra of a general locally reductive Lie algebra is necessarily nilpotent.

In what follows we call a Cartan subalgebra \mathfrak{h} splitting if \mathfrak{h}_{ss} is a splitting toral subalgebra of \mathfrak{g} .

4. Cartan subalgebras of root-reductive Lie algebras

This section begins with some brief introductory material on root-reductive Lie algebras. We then consider separately the cases of a root-reductive Lie algebra \mathfrak{g} containing a simple component of type \mathfrak{sl}_{∞} , \mathfrak{so}_{∞} , and \mathfrak{sp}_{∞} . In particular, we describe all Cartan subalgebras of the simple Lie algebras \mathfrak{sl}_{∞} , \mathfrak{so}_{∞} , and \mathfrak{sp}_{∞} . The section concludes with a general theorem about the Cartan subalgebras of an arbitrary root-reductive Lie algebra and with examples.

4.1. Root-reductive Lie algebras

An inclusion of finite-dimensional reductive Lie algebras $\mathfrak{l} \subseteq \mathfrak{m}$ is a *root inclusion* if, for some Cartan subalgebra $\mathfrak{h}_{\mathfrak{m}}$ of \mathfrak{m} , the subalgebra $\mathfrak{l} \cap \mathfrak{h}_{\mathfrak{m}}$ is a Cartan subalgebra of \mathfrak{l} and each $\mathfrak{l} \cap \mathfrak{h}_{\mathfrak{m}}$ -root space \mathfrak{l}^{α} is also a root space of \mathfrak{m} . Informally, root spaces of \mathfrak{l} are root spaces of \mathfrak{m} . A Lie algebra \mathfrak{g} is called *root-reductive* if it is isomorphic to a union $\bigcup_{i \in \mathbb{Z}_{>0}} \mathfrak{g}_i$ of nested reductive Lie algebras with respect to root inclusions for a fixed choice of nested Cartan subalgebras $\mathfrak{h}_i \subseteq \mathfrak{g}_i$ with $\mathfrak{h}_{i-1} = \mathfrak{h}_i \cap \mathfrak{g}_{i-1}$.

Finite-dimensional reductive Lie algebras are root-reductive, as are $\mathfrak{gl}_{\infty}, \mathfrak{sl}_{\infty}, \mathfrak{so}_{\infty}$, and \mathfrak{sp}_{∞} . The following theorem is a slightly more general version of a result in [DP].

Theorem 4.1. *Let* g *be a locally reductive Lie algebra.*

(1) There is a split exact sequence of Lie algebras

 $0 \to [\mathfrak{g}, \mathfrak{g}] \to \mathfrak{g} \to \mathfrak{g}/[\mathfrak{g}, \mathfrak{g}] =: \mathfrak{a} \to 0,$

i.e. $\mathfrak{g} \simeq [\mathfrak{g}, \mathfrak{g}] \oplus \mathfrak{a}$, where \mathfrak{a} is abelian.

(2) If g is root-reductive, the Lie algebra [g, g] is isomorphic to a direct sum of finite-dimensional simple Lie algebras, as well as of copies of sl_∞, so_∞, and sp_∞, with at most countable multiplicities.

Proof. (1) Fix an exhaustion $\mathfrak{g} = \bigcup_i \mathfrak{g}_i$, where \mathfrak{g}_i is finite dimensional and reductive. Let $\mathfrak{h}_i \subseteq \mathfrak{g}_i$ be a family of Cartan subalgebras such that $\mathfrak{h}_i \cap \mathfrak{g}_{i-1} = \mathfrak{h}_{i-1}$. Define $\mathfrak{h} := \bigcup_i \mathfrak{h}_i$. Then $\mathfrak{g} = [\mathfrak{g}, \mathfrak{g}] + \mathfrak{h}$. Since \mathfrak{h} is abelian, there is an abelian Lie algebra $\mathfrak{a} \subseteq \mathfrak{h}$ such that $\mathfrak{h} = \mathfrak{h} \cap [\mathfrak{g}, \mathfrak{g}] \oplus \mathfrak{a}$. One may check that $\mathfrak{g} \simeq [\mathfrak{g}, \mathfrak{g}] \in \mathfrak{a}$.

(2) For the proof see [DP, Theorem 1]. \Box

We will apply the following proposition only in the case of root-reductive Lie algebras, but we prove it in more generality for locally reductive Lie algebras.

Proposition 4.2. Let $\mathfrak{g} = \bigcup_i \mathfrak{g}_i$ be a locally reductive Lie algebra, with \mathfrak{g}_i finite dimensional and reductive, and \mathfrak{g}_i reductive in \mathfrak{g}_{i+1} . Let W be a $[\mathfrak{g},\mathfrak{g}]$ -module which is a direct limit of injections of simple $[\mathfrak{g}_i,\mathfrak{g}_i]$ -modules W_i . Then the $[\mathfrak{g},\mathfrak{g}]$ -module structure on W can be extended to a \mathfrak{g} -module structure.

Proof. For each *i*, choose an abelian Lie algebra $\mathfrak{a}_i \subseteq \mathfrak{z}(\mathfrak{g}_i)$ such that $\mathfrak{g}_i = (\mathfrak{g}_i \cap [\mathfrak{g}, \mathfrak{g}]) \oplus \mathfrak{a}_i$. Let $\pi_1 : \mathfrak{g}_i \to \mathfrak{g}_i \cap [\mathfrak{g}, \mathfrak{g}]$ and $\pi_2 : \mathfrak{g}_i \to \mathfrak{a}_i$ be the corresponding projections. Consider the inclusion $\varphi : \mathfrak{g}_i \hookrightarrow \mathfrak{g}_{i+1}$, and note that $\pi_2 \circ \varphi|_{\mathfrak{a}_i} : \mathfrak{a}_i \to \mathfrak{a}_{i+1}$ is injective. Let \mathfrak{b}_{i+1} be a vector space complement of $\pi_2 \circ \varphi(\mathfrak{a}_i)$ in \mathfrak{a}_{i+1} .

Given an action of \mathfrak{a}_i on W_i by scalar endomorphisms, we define an action of \mathfrak{a}_{i+1} on W_{i+1} by scalars as follows. Let $a \in \mathfrak{a}_i$ be arbitrary, and let α denote the scalar by which a acts on W_i . Observe that the image of $\pi_1 \circ \varphi(a)$ in End W must commute with the image of $[\mathfrak{g}_i, \mathfrak{g}_i]$. Hence the image of $\pi_1 \circ \varphi(a)$ in End W is the direct sum of a scalar endomorphism of W_i and an endomorphism of a vector space complement of W_i . Let β denote the scalar by which $\pi_1 \circ \varphi(a)$ acts on W_i . Define the action of $\pi_2 \circ \varphi(a)$ on W_{i+1} to be by the scalar $\alpha - \beta$. Since $\pi_2 \circ \varphi|_{\mathfrak{a}_i}$ is injective, this procedure defines an action of $\pi_2 \circ \varphi(\mathfrak{a}_i)$ on W_{i+1} . Define the action of \mathfrak{b}_{i+1} on W_{i+1} to be trivial.

We are now ready to define an action of \mathfrak{g} on W. If $x \in \mathfrak{g}$ and $w \in W$, then for some *i* we have $x \in \mathfrak{g}_i$ and $w \in W_i$. Set $x \cdot w := \pi_1(x) \cdot w + \pi_2(x) \cdot w$, where the second action on the right-hand side comes from the preceding paragraph. One must check that this is well-defined, i.e. compatible with the inclusions $\mathfrak{g}_i \hookrightarrow \mathfrak{g}_{i+1}$ and $W_i \hookrightarrow W_{i+1}$. Explicitly, the composition $\mathfrak{g}_i \to \mathfrak{g}_{i+1} \to \operatorname{Hom}(W_{i+1}, W) \to \operatorname{Hom}(W_i, W)$ coincides with the map $\mathfrak{g}_i \to \operatorname{Hom}(W_i, W)$. Since elements of \mathfrak{a}_i act as scalars on W_i , W is a well-defined \mathfrak{g} -module. \Box

In what follows g will always denote a root-reductive Lie algebra.

4.2. The case where \mathfrak{so}_{∞} is a direct summand of $[\mathfrak{g}, \mathfrak{g}]$

In this subsection $\mathfrak{so}(V) = \bigwedge^2 V$ is a direct summand of $[\mathfrak{g}, \mathfrak{g}]$, and t is a maximal toral subalgebra of \mathfrak{g} . We consider V as a $[\mathfrak{g}, \mathfrak{g}]$ -module in which all direct summands other than $\mathfrak{so}(V)$ act trivially. By Proposition 4.2, V may be endowed with the structure of a \mathfrak{g} -module. We write V' (and more generally A') for the maximal locally finite t-submodule of V (respectively of a t-module A). The key fact about maximal locally finite submodules is that if A and B are two

t-modules then $(A \otimes B)' = A' \otimes B'$. This is a special case of a result of Dimitrov and Zuckerman appearing in [NP, Appendix, Proposition A]. Thus $\mathfrak{so}(V)' = (V' \otimes V') \cap \bigwedge^2 V = \bigwedge^2 V'$.

Recall that for any Lie subalgebra $\mathfrak{k} \subseteq \mathfrak{g}$, $\bigoplus_{\alpha \in \text{supp } V \subseteq \mathfrak{k}^*} V^{\alpha}$ is a generalized weight \mathfrak{k} -submodule of V. If $\mathfrak{k} = \mathfrak{t}$, it is easy to verify that $\bigoplus_{\alpha \in \text{supp } V \subseteq \mathfrak{k}^*} V^{\alpha}$ coincides with the maximal locally finite \mathfrak{t} -submodule $V' \subseteq V$. Therefore

$$\mathfrak{so}(V)' = \sum_{\alpha, \beta \in \mathrm{supp}\, V} V^{\alpha} \wedge V^{\beta},$$

and $\mathfrak{z}_{\mathfrak{so}(V)}(\mathfrak{t})$ is the 0-weight space of this weight decomposition of $\mathfrak{so}(V)'$. Thus

$$\mathfrak{z}_{\mathfrak{so}(V)}(\mathfrak{t}) = \bigwedge^2 V^0 \oplus \bigoplus_{\alpha \in I} V^{\alpha} \wedge V^{-\alpha},$$

where $I \sqcup -I = \operatorname{supp} V \cap -\operatorname{supp} V \setminus \{0\}$.

Theorem 4.3. Let \mathfrak{g} be a root-reductive Lie algebra for which $\mathfrak{so}(V)$ is a direct summand of $[\mathfrak{g},\mathfrak{g}]$. The following statements hold for any maximal toral subalgebra $\mathfrak{t} \subseteq \mathfrak{g}$:

- (1) If $\langle V^{\alpha}, V^{\beta} \rangle \neq 0$, then $\beta = -\alpha$. If furthermore $\alpha \neq 0$, then dim $V^{\alpha} = \dim V^{-\alpha} = 1$;
- (2) If $\langle \cdot, \cdot \rangle|_{V^{\alpha} \times V^{-\alpha}} = 0$ then $V^{\alpha} \wedge V^{-\alpha} \subseteq \mathfrak{z}(\mathfrak{z}_{\mathfrak{so}(V)}(\mathfrak{t}));$
- (3) $\langle \cdot, \cdot \rangle |_{V^0 \times V^0}$ has rank 0 or 1, and $(\bigwedge^2 V^0) \cap \mathfrak{t} = 0;$
- (4) $\mathfrak{z}_{\mathfrak{so}(V)}(\mathfrak{t})$ is nilpotent of depth at most 2.

If $\mathfrak{g} = \mathfrak{so}(V)$, a subalgebra $\mathfrak{t} \subseteq \mathfrak{g}$ is maximal toral if and only if (3), (5) and (6) hold, where

- (5) supp V = supp V and dim $V^{\alpha} = 1$ for any $\alpha \in$ supp $V \setminus \{0\}$;
- (6) $\mathfrak{t} = \bigoplus_{\alpha \in I} V^{\alpha} \wedge V^{-\alpha}$, where $I \sqcup -I = \operatorname{supp} V \setminus \{0\}$.

Proof. (1) Let $v \in V^{\alpha}$ and $w \in V^{\beta}$ be such that $\langle v, w \rangle \neq 0$. If $t \in \mathfrak{t}$, then the g-invariance of $\langle \cdot, \cdot \rangle$ yields $\langle tv, w \rangle + \langle v, tw \rangle = 0$. Thus $(\alpha(t) + \beta(t)) \langle v, w \rangle = 0$. Since $\langle v, w \rangle \neq 0$, it follows that $\beta = -\alpha$. In particular, if $\alpha \neq 0$, then $\langle V^{\alpha}, V^{\alpha} \rangle = 0$.

Suppose $\alpha \neq 0$ and without loss of generality that $\langle v, w \rangle = 1$. Each of $v \otimes w$ and $w \otimes v$ satisfies the equation $x^2 = x$ and therefore is semisimple. Furthermore, $[v \otimes w, w \otimes v] = \langle w, w \rangle v \otimes v - \langle v, v \rangle w \otimes w = 0$. Hence $v \wedge w = v \otimes w - w \otimes v$ is semisimple. Since $v \wedge w \in \mathfrak{zg}(\mathfrak{t})$, $t := v \wedge w$ is contained in t by maximality. Then $\alpha(t)v = t \cdot v = v$ implies $\alpha(t) = 1$. For $v' \in V^{\alpha}$, we calculate $v' = \alpha(t)v' = t \cdot v' = \langle v', w \rangle v$. Therefore V^{α} is 1-dimensional.

(2) In view of part (1), V^{α} and $V^{-\alpha}$ are in the radical of the form $\langle \cdot, \cdot \rangle|_{V' \times V'}$ and hence all elements of $\mathfrak{so}(V)'$ centralize $V^{\alpha} \wedge V^{-\alpha}$.

(3) Suppose, for the sake of a contradiction, that the form $\langle \cdot, \cdot \rangle|_{V^0 \times V^0}$ has rank greater than 1. Then there exist $v, w \in V^0$ with pairings given by the matrix $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$. As in part (1), we see that $v \wedge w$ is semisimple and hence lies in t. Since w is in the 0-weight space of t, we calculate $0 = (v \wedge w) \cdot w = v$, which contradicts the choice of v. Therefore the form $\langle \cdot, \cdot \rangle|_{V^0 \times V^0}$ has rank 0 or 1.

To prove that $(\bigwedge^2 V^0) \cap \mathfrak{t} = 0$, it is enough to show that elements of $\bigwedge^2 V^0$ are nilpotent as endomorphisms of V. Let $\sum v_i \wedge w_i \in \bigwedge^2 V^0$ be arbitrary. If the form $\langle \cdot, \cdot \rangle|_{V^0 \times V^0}$ has rank 0,

one may compute that $(\sum v_i \wedge w_i)^2 = 0$. If the form $\langle \cdot, \cdot \rangle|_{V^0 \times V^0}$ has rank 1, one may compute that $(\sum v_i \wedge w_i)^3 = 0$.

(4) We have $\mathfrak{z}_{\mathfrak{so}(V)}(\mathfrak{t}) = \bigwedge^2 V^0 \oplus \bigoplus_{\alpha \in I} V^\alpha \wedge V^{-\alpha}$, and since $\bigoplus_{\alpha \in I} V^\alpha \wedge V^{-\alpha}$ is central in $\mathfrak{z}_{\mathfrak{so}(V)}(\mathfrak{t})$, it is enough to show that $\bigwedge^2 V^0$ is nilpotent of depth at most 2.

If $\langle \cdot, \cdot \rangle|_{V^0 \times V^0} = 0$, then $\bigwedge^2 V^0$ is abelian. Now suppose that $\langle \cdot, \cdot \rangle|_{V^0 \times V^0}$ has rank 1. Let *K* be the radical of the form $\langle \cdot, \cdot \rangle|_{V^0 \times V^0}$. Let *v* be any vector in $V^0 \setminus K$, and we may as well assume that $\langle v, v \rangle = 1$. We have $V^0 = K \oplus \mathbb{C}v$. To show that $\bigwedge^2 V^0$ is nilpotent of depth at most 2, it is enough to show that $[K \wedge v, K \wedge v] \subseteq \bigwedge^2 K$, since $\bigwedge^2 K$ is central. For arbitrary $a, b \in K$, we compute

$$[a \wedge v, b \wedge v] = [a \otimes v - v \otimes a, b \otimes v - v \otimes b]$$

= $(a \otimes v - v \otimes a) \cdot (b \otimes v - v \otimes b) - (b \otimes v - v \otimes b) \cdot (a \otimes v - v \otimes a)$
= $-a \otimes b + b \otimes a$
= $b \wedge a \in \bigwedge^2 K$.

(5) For the first equality, let us compute $\mathfrak{t} \cdot V'$ in two different ways. On the one hand, by definition, $\mathfrak{t} \cdot V' = \bigoplus_{0 \neq \alpha \in \operatorname{supp} V} V^{\alpha}$. On the other hand, the assumption $\mathfrak{g} = \bigwedge^2 V$ yields $\mathfrak{t} \subseteq \bigwedge^2 V^0 \bigoplus \sum_{\alpha \in \operatorname{supp} V \cap -\operatorname{supp} V} V^{\alpha} \wedge V^{-\alpha}$, and since $\langle V^{\alpha}, V^{\beta} \rangle = \{0\}$ for $\beta \neq -\alpha$, we obtain $\mathfrak{t} \cdot V' \subseteq \bigoplus_{\alpha \in \operatorname{supp} V \cap -\operatorname{supp} V} V^{\alpha}$. This implies $\operatorname{supp} V \subseteq \operatorname{supp} V \cap -\operatorname{supp} V$, and hence $\operatorname{supp} V = -\operatorname{supp} V$.

Now consider the fact that $\mathfrak{t} \cdot V^{\alpha} \neq \{0\}$ for $\alpha \neq 0$. It follows that $\langle V^{\alpha}, V^{-\alpha} \rangle \neq \{0\}$. Part (1) gives dim $V^{\alpha} = 1$ for any $\alpha \in \text{supp } V \setminus \{0\}$.

(6) By the proof of part (1), we have $V^{\alpha} \wedge V^{-\alpha} \subseteq \mathfrak{t}$ for $0 \neq \alpha \in \operatorname{supp} V$. This gives the inclusions

$$\bigoplus_{\alpha \in I} V^{\alpha} \wedge V^{-\alpha} \subseteq \mathfrak{t} \subseteq \bigwedge^2 V^0 \oplus \bigoplus_{\alpha \in I} V^{\alpha} \wedge V^{-\alpha}.$$

In part (3) we showed that $(\bigwedge^2 V^0) \cap \mathfrak{t} = 0$. Hence $\mathfrak{t} = \bigoplus_{\alpha \in I} V^{\alpha} \wedge V^{-\alpha}$.

Conversely, assume that conditions (3), (5), and (6) are satisfied. Since $\langle V^{\alpha}, V^{\beta} \rangle = 0$ for $\alpha \neq -\beta$, the subalgebra t is a direct sum of 1-dimensional Lie subalgebras, hence abelian. If $\alpha \neq 0$, we have $t \cdot V^{\alpha} \neq 0$, hence $\langle V^{\alpha}, V^{-\alpha} \rangle \neq 0$. Thus t is spanned by elements of the form $v \wedge w$ where $v \in V^{\alpha}$, $w \in V^{-\alpha}$, $\alpha \neq 0$, and $\langle v, w \rangle = 1$. These elements are semisimple as in part (1). Hence t is a toral subalgebra of $\mathfrak{g} = \bigwedge^2 V$. The centralizer of t in \mathfrak{g} is contained in \mathfrak{g}' and coincides with $\mathfrak{t} \oplus \bigwedge^2 V^0$. Condition (3) implies that each element in $\bigwedge^2 V^0$ is nilpotent, so t is maximal toral. \Box

Corollary 4.4. For any maximal toral subalgebra $\mathfrak{t} \subseteq \mathfrak{so}(V)$, we have

$$\mathfrak{z}_{\mathfrak{so}(V)}(\mathfrak{t}) = \mathfrak{t} \oplus {\bigwedge}^2 V^0,$$

which is a Lie algebra nilpotent of depth at most 2.

The result from Theorem 4.3(3) that $\langle \cdot, \cdot \rangle|_{V^0 \times V^0}$ has rank 0 or 1 enables us to make the following definition. A maximal toral subalgebra of \mathfrak{so}_{∞} is *even* if the rank of $\langle \cdot, \cdot \rangle|_{V^0 \times V^0}$ is 0, and *odd* if the rank is 1. Likewise, a Cartan subalgebra \mathfrak{h} is *even* if \mathfrak{h}_{ss} is an even maximal toral subalgebra, and \mathfrak{h} is *odd* if \mathfrak{h}_{ss} is odd.

There are two types of exhaustions of \mathfrak{so}_{∞} via root inclusions: as $\bigcup_i \mathfrak{so}_{2i}$ and as $\bigcup_i \mathfrak{so}_{2i+1}$. A union of Cartan subalgebras of \mathfrak{so}_{2i} yields an even splitting Cartan subalgebra of \mathfrak{so}_{∞} , and a union of Cartan subalgebras of \mathfrak{so}_{2i+1} yields an odd splitting Cartan subalgebra of \mathfrak{so}_{∞} . It is easy to see that any splitting Cartan subalgebra of \mathfrak{so}_{∞} arises in one of these two ways and is necessarily abelian.

Notice that $\bigwedge^2 V^0$ is the degenerate orthogonal Lie algebra $\mathfrak{so}(V^0)$. For a degenerate symmetric form on a vector space W, the Lie algebra $\mathfrak{so}(W)$ is nilpotent precisely when the form has rank 0 or 1. Explicitly, the Lie algebra $\mathfrak{so}(W)$ is nilpotent and nonabelian exactly when the form has rank 1 and dim $W \ge 3$. Hence any nonabelian Cartan subalgebra of $\mathfrak{so}(V)$ must be odd and must have dim $V^0 \ge 3$.

Here is an example of a nonabelian Cartan subalgebra of $\mathfrak{so}(V)$. Let $\{e_i\}_{i\in\mathbb{Z}}$ be a basis for V with $\langle e_i, e_j \rangle = \delta_{i,-j}$. Let

$$\mathfrak{t} := \bigoplus_{i \ge 3} \mathbb{C}(e_i + e_1) \wedge (e_{-i} + e_{-2}).$$

Observe that $\mathfrak{t} \subseteq \mathfrak{so}(V)$ is a maximal toral subalgebra, and we have

$$\mathfrak{z}_{\mathfrak{so}(V)}(\mathfrak{t}) = \mathfrak{t} \oplus \bigwedge^2 \operatorname{Span}\{e_0, e_{-2}, e_1\}.$$

We see that the Cartan subalgebra $\mathfrak{z}_{\mathfrak{so}(V)}(\mathfrak{t})$ is not abelian as $[e_1 \wedge e_0, e_{-2} \wedge e_0] = e_{-2} \wedge e_1$.

It is easy to check that the centralizer of any even maximal toral subalgebra acts locally finitely on itself, whereas the centralizer of an odd maximal toral subalgebra acts locally finitely on itself if and only if V^0 is finite dimensional.

4.3. The case where \mathfrak{sp}_{∞} is a direct summand of $[\mathfrak{g}, \mathfrak{g}]$

Let $\mathfrak{sp}(V) = \operatorname{Sym}^2(V)$ be a direct summand of $[\mathfrak{g}, \mathfrak{g}]$, and \mathfrak{t} a maximal toral subalgebra of \mathfrak{g} . The following results are proved in the same way as the analogous statements for $\mathfrak{so}(V)$.

We will write $A \& B := \{a \otimes b + b \otimes a : a \in A, b \in B\} \subseteq A \otimes B \oplus B \otimes A$ for the symmetrizer of vector spaces A and B. Set also $a \& b := a \otimes b + b \otimes a \in A \& B$ for $a \in A, b \in B$.

We consider V as a $[\mathfrak{g}, \mathfrak{g}]$ -module in which all direct summands other than $\mathfrak{sp}(V)$ act trivially, and by Proposition 4.2, V may be endowed with the structure of a \mathfrak{g} -module. We have the equality $\mathfrak{sp}(V)' = \operatorname{Sym}^2(V')$ and the weight decomposition

$$\mathfrak{sp}(V)' = \sum_{\alpha,\beta \in \mathrm{supp}\,V} V^{\alpha} \& V^{\beta}.$$

Observe that

$$\mathfrak{z}_{\mathfrak{sp}(V)}(\mathfrak{t}) = \operatorname{Sym}^2(V^0) \oplus \bigoplus_{\alpha \in I} V^{\alpha} \& V^{-\alpha},$$

where $I \sqcup -I = \operatorname{supp} V \cap -\operatorname{supp} V \setminus \{0\}$.

Theorem 4.5. Let \mathfrak{g} be a root-reductive Lie algebra for which $\mathfrak{sp}(V)$ is a direct summand of $[\mathfrak{g},\mathfrak{g}]$. The following statements hold for any maximal toral subalgebra $\mathfrak{t} \subseteq \mathfrak{g}$:

(1) If $\langle V^{\alpha}, V^{\beta} \rangle \neq 0$, then $\beta = -\alpha$. If furthermore $\alpha \neq 0$, then dim $V^{\alpha} = \dim V^{-\alpha} = 1$; (2) If $\langle \cdot, \cdot \rangle|_{V^{\alpha} \times V^{-\alpha}} = 0$ then $V^{\alpha} \& V^{-\alpha} \subseteq \mathfrak{z}(\mathfrak{zp}(V)(\mathfrak{t}))$; (3) $\langle \cdot, \cdot \rangle|_{V^{0} \times V^{0}} = 0$, and $(\operatorname{Sym}^{2}(V^{0})) \cap \mathfrak{t} = 0$;

(4) $\mathfrak{z}_{\mathfrak{sp}(V)}(\mathfrak{t})$ is abelian.

If $\mathfrak{g} = \mathfrak{sp}(V)$, a subalgebra $\mathfrak{t} \subseteq \mathfrak{g} = \mathfrak{sp}(V)$ is maximal toral if and only if (3), (5), and (6) hold, where

(5) supp V = - supp V and dim $V^{\alpha} = 1$ for any $\alpha \in$ supp $V \setminus \{0\}$; (6) $\mathfrak{t} = \bigoplus_{\alpha \in I} V^{\alpha} \& V^{-\alpha}$, where $I \sqcup -I =$ supp $V \setminus \{0\}$.

Corollary 4.6. For any maximal toral subalgebra $\mathfrak{t} \subseteq \mathfrak{sp}(V)$, we have

$$\mathfrak{z}_{\mathfrak{sp}(V)}(\mathfrak{t}) = \mathfrak{t} \oplus \operatorname{Sym}^2(V^0),$$

which is an abelian Lie algebra.

4.4. The case where \mathfrak{sl}_{∞} is a direct summand of $[\mathfrak{g}, \mathfrak{g}]$

In this subsection we generalize a theorem from [NP], which we first recall.

Theorem 4.7. [NP] A subalgebra $\mathfrak{t} \subseteq \mathfrak{g} = \mathfrak{gl}(V, V_*)$ is maximal toral if and only if the following conditions are satisfied:

- (1) $(\operatorname{supp} V) \setminus \{0\} = -(\operatorname{supp} V_*) \setminus \{0\}$ and $\dim V^{\alpha} = \dim V_*^{-\alpha} = 1$ for any $\alpha \in \operatorname{supp} V \setminus \{0\}$; (2) $\langle \cdot, \cdot \rangle|_{V^0 \times V^0_*} = 0$, and $(V^0 \otimes V^0_*) \cap \mathfrak{t} = 0$;
- (3) $\mathfrak{t} = \bigoplus_{0 \neq \alpha \in \operatorname{supp} V} V^{\alpha} \otimes V_*^{-\alpha}$.

Thus, for any maximal toral subalgebra $\mathfrak{t} \subseteq \mathfrak{gl}(V, V_*)$, we have

$$\mathfrak{z}_{\mathfrak{gl}(V,V_*)}(\mathfrak{t}) = \mathfrak{t} \oplus (V^0 \otimes V^0_*),$$

which is an abelian Lie algebra.

Assume that $\mathfrak{sl}(V, V_*)$ is a direct summand of $[\mathfrak{g}, \mathfrak{g}]$, and let \mathfrak{t} be a maximal toral subalgebra of \mathfrak{g} . We consider V and V_* as $[\mathfrak{g}, \mathfrak{g}]$ -modules in which all direct summands other than $\mathfrak{sl}(V, V_*)$ act trivially, and by Proposition 4.2, V and V_* may be endowed with the structure of \mathfrak{g} -modules. We have the equality $\mathfrak{sl}(V, V_*)' = \mathfrak{sl}(V', V_*')$ and the weight decomposition

$$\mathfrak{sl}(V, V_*)' = \mathfrak{sl}(V, V_*) \cap \bigoplus_{\alpha \in \mathrm{supp } V, \beta \in \mathrm{supp } V_*} V^{\alpha} \otimes V_*^{\beta}.$$

Observe that

$$\mathfrak{z}_{\mathfrak{sl}(V,V_*)}(\mathfrak{t}) = \mathfrak{sl}(V,V_*) \cap \bigoplus_{\alpha \in \mathrm{supp}\, V} V^{\alpha} \otimes V_*^{-\alpha}.$$

Theorem 4.8. Let \mathfrak{g} be a root-reductive Lie algebra for which $\mathfrak{sl}(V, V_*)$ is a direct summand of $[\mathfrak{g}, \mathfrak{g}]$. The following statements hold for any maximal toral subalgebra $\mathfrak{t} \subseteq \mathfrak{g}$:

- (1) If $\langle V^{\alpha}, V_*^{\beta} \rangle \neq 0$, then $\beta = -\alpha$. If furthermore the rank of $\langle \cdot, \cdot \rangle|_{V' \times V'_*}$ is at least 2, then $\dim V^{\alpha} = \dim V_*^{-\alpha} = 1$;
- (2) If $\langle \cdot, \cdot \rangle |_{V^{\alpha} \times V_{*}^{-\alpha}} = 0$ then $V^{\alpha} \otimes V_{*}^{-\alpha} \subseteq \mathfrak{z}(\mathfrak{z}_{\mathfrak{sl}(V,V_{*})}(\mathfrak{t}));$
- (3) If the rank of $\langle \cdot, \cdot \rangle|_{V' \times V'_*}$ is at least 2, then $\langle \cdot, \cdot \rangle|_{V^0 \times V^0_*} = 0$. Hence $\langle \cdot, \cdot \rangle|_{V^0 \times V^0_*}$ has rank 0 or 1. Also, $(V^0 \otimes V^0_*) \cap \mathfrak{t} = 0$;
- (4) $\mathfrak{z}_{\mathfrak{sl}(V,V_*)}(\mathfrak{t})$ is nilpotent of depth at most 2.

If $\mathfrak{g} = \mathfrak{sl}(V, V_*)$, a subalgebra $\mathfrak{t} \subseteq \mathfrak{g}$ is maximal toral if and only if (3'), (5), and (6) hold, where

- (3') $\langle \cdot, \cdot \rangle |_{V^0 \times V^0_*} = 0$, and $(V^0 \otimes V^0_*) \cap \mathfrak{t} = 0$;
- (5) $(\operatorname{supp} V) \setminus \{0\} = -(\operatorname{supp} V_*) \setminus \{0\}$ and $\dim V^{\alpha} = \dim V_*^{-\alpha} = 1$ for any $\alpha \in \operatorname{supp} V \setminus \{0\}$;
- (6) $\mathfrak{t} = \mathfrak{sl}(V, V_*) \cap \bigoplus_{0 \neq \alpha \in \mathrm{supp } V} V^{\alpha} \otimes V_*^{-\alpha}.$

Proof. (1) Suppose $\langle V^{\alpha}, V_*^{-\alpha} \rangle \neq 0$ and that the rank of $\langle \cdot, \cdot \rangle|_{V' \times V'_*}$ is at least 2. Then let $v \in V^{\alpha}$ and $w \in V_*^{-\alpha}$ be such that $\langle v, w \rangle = 1$. Since the rank of $\langle \cdot, \cdot \rangle|_{V' \times V'_*}$ is at least 2, there exist $v' \in V^{\beta}$ and $w' \in V_*^{-\beta}$ such that $\langle v', w' \rangle = 1$ and $\langle v, w' \rangle = \langle v', w \rangle = 0$. We have $t := v \otimes w - v' \otimes w' \in \mathfrak{t}$, by an argument similar to the \mathfrak{so}_{∞} case. Then $t \cdot v = v$ implies $\alpha(t) = 1$.

First assume $\alpha \neq \beta$. Let $v'' \in V^{\alpha}$, and compute $v'' = t \cdot v'' = (v \otimes w - v' \otimes w') \cdot v'' = \langle v'', w \rangle v$. This implies that V^{α} is 1-dimensional. A similar argument shows that $V_*^{-\alpha}$ is also 1-dimensional.

Second assume, for the sake of a contradiction, that $\alpha = \beta$. Then compute $t \cdot v' = -v'$, which implies $\alpha(t) = -1$, contradicting $\alpha(t) = 1$.

(2) The argument from the \mathfrak{so}_{∞} case works; see Theorem 4.3.

(3) If the rank of $\langle \cdot, \cdot \rangle|_{V' \times V'_*}$ is at least 2, and if $\langle V^{\alpha}, V_*^{-\alpha} \rangle \neq 0$, then as in part (1) there exists $t \in \mathfrak{t}$ with $\alpha(t) = 1$. Hence $\langle V^0, V_*^0 \rangle = 0$. The proof of the last statement is similar to that in Theorem 4.3.

(4) We have $\mathfrak{z}_{\mathfrak{sl}(V,V_*)}(\mathfrak{t}) = \mathfrak{sl}(V, V_*) \cap \bigoplus_{\alpha} V^{\alpha} \otimes V_*^{-\alpha}$. If the rank of $\langle \cdot, \cdot \rangle|_{V' \times V'_*}$ is not 1, then one may check that $\mathfrak{z}_{\mathfrak{sl}(V,V_*)}(\mathfrak{t})$ is abelian. Suppose the rank of $\langle \cdot, \cdot \rangle|_{V' \times V'_*}$ is 1. Let β be the weight for which $\langle \cdot, \cdot \rangle|_{V^{\beta} \times V_*^{-\beta}}$ has rank 1. Then $\bigoplus_{\alpha \neq \beta} V^{\alpha} \otimes V_*^{-\alpha}$ is central in $\mathfrak{z}_{\mathfrak{sl}(V,V_*)}(\mathfrak{t})$. Therefore it suffices to show that $\mathfrak{sl}(V^{\beta}, V_*^{-\beta})$ is nilpotent of depth at most 2. It is an easy computation to check that if either V^{β} or $V_*^{-\beta}$ has dimension 1, then $\mathfrak{sl}(V^{\beta}, V_*^{-\beta})$ is abelian, and that otherwise it is nilpotent of depth 2.

If the rank of $\langle \cdot, \cdot \rangle|_{V' \times V'_*}$ is 0 or 1, then $\mathfrak{t} \cap \mathfrak{sl}(V, V_*) = 0$. Thus for any maximal toral subalgebra $\mathfrak{t} \subseteq \mathfrak{sl}(V, V_*)$, we have that $\langle \cdot, \cdot \rangle|_{V^0 \times V^0_*}$ has rank 0, which yields (3'). One can modify the proofs from Theorem 4.3 to obtain (5) and (6), as well as the reverse implication. \Box

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Corollary 4.9. For any maximal toral subalgebra $\mathfrak{t} \subseteq \mathfrak{sl}(V, V_*)$, we have

$$\mathfrak{z}_{\mathfrak{sl}(V,V_*)}(\mathfrak{t}) = \mathfrak{t} \oplus (V^0 \otimes V^0_*),$$

which is an abelian Lie algebra.

Note that the degenerate Lie algebra $\mathfrak{sl}(W, W_*)$ is nilpotent if and only if the form $\langle \cdot, \cdot \rangle : W \times W_* \to \mathbb{C}$ has rank 0 or 1. In the rank 1 case, the algebra is again nilpotent of depth at most 2. This phenomenon does not occur for \mathfrak{gl}_{∞} or \mathfrak{sp}_{∞} , since in these cases any nilpotent degenerate algebra must be fully degenerate.

4.5. Unified description of Cartan subalgebras of \mathfrak{gl}_{∞} , \mathfrak{sl}_{∞} , \mathfrak{so}_{∞} , and \mathfrak{sp}_{∞}

Definition 4.10.

- (1) A dual system for $\mathfrak{gl}(V, V_*)$ or for $\mathfrak{sl}(V, V_*)$ is a set of 1-dimensional vector subspaces $L_i \subseteq V$ and $L^i \subseteq V_*$ for $i \in I$ such that $\langle L_i, L^j \rangle = \delta_{ij} \mathbb{C}$. Here I is a finite set or $Z_{>0}$.
- (2) A self-dual system for $\mathfrak{so}(V)$ or for $\mathfrak{sp}(V)$ is a set of 1-dimensional vector subspaces $L_i \subseteq V$ for $i \in I$ such that $\langle L_i, L_j \rangle = \delta_{i,-j} \mathbb{C}$. Here I is a finite subset of $\mathbb{Z}_{\neq 0}$ with -I = I, or $I = \mathbb{Z}_{\neq 0}$.

The following is a corollary to Theorems 4.3, 4.5, 4.7, and 4.8.

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Corollary 4.11. Cartan subalgebras of \mathfrak{gl}_{∞} (respectively of \mathfrak{sl}_{∞} , \mathfrak{so}_{∞} , or \mathfrak{sp}_{∞}) are in one-to-one correspondence with maximal (self-)dual systems for \mathfrak{gl}_{∞} (respectively for \mathfrak{sl}_{∞} , \mathfrak{so}_{∞} , or \mathfrak{sp}_{∞}).

Proof. A (self-)dual system yields a toral subalgebra by the formulas in Fig. 1. In the case of \mathfrak{gl}_{∞} , since $\langle L_i, L^j \rangle = 0$ for $i \neq j$, the subalgebra t is a direct sum of 1-dimensional Lie subalgebras, hence abelian. Since $\langle L_i, L^i \rangle \neq 0$, t is spanned by elements of the form $v \otimes w$, where $v \in L_i$, $w \in L^i$, and $\langle v, w \rangle = 1$. These elements are semisimple since they satisfy the equation $x^2 = x$. Hence t is a toral subalgebra. A similar argument shows that self-dual systems also yield toral subalgebras.

Consider the map which sends a (self-)dual system to the toral subalgebra according to the formulas in Fig. 1. This map is injective (except in the case of \mathfrak{gl}_{∞} , where one must not allow dual systems to have |I| = 1). To see injectivity in the case of \mathfrak{gl}_{∞} , suppose $\{L_i, L^i\}$ and $\{M_j, M^j\}$ are dual systems with $\bigoplus_i L_i \otimes L^i = \mathfrak{t} = \bigoplus_j M_j \otimes M^j$. Then $L_i = \mathfrak{t} \cdot L_i = (\bigoplus_j M_j \otimes M^j) \cdot L_i$. Hence for some *j* we have $M_j = L_i$. This argument can be adapted to work for self-dual systems. Moreover, this map preserves containment, and its image includes all maximal toral subalgebras

g	ť	ħ
\mathfrak{gl}_∞	$\bigoplus_i L_i \otimes L^i$	$\mathfrak{t} \oplus ((\bigoplus_i L^i)^{\perp} \otimes (\bigoplus_j L_j)^{\perp})$
\mathfrak{sl}_∞	$\mathfrak{sl}_{\infty} \cap (\bigoplus_i L_i \otimes L^i)$	$\mathfrak{t} \oplus ((\bigoplus_i L^i)^\perp \otimes (\bigoplus_j L_j)^\perp)$
\mathfrak{so}_∞	$\bigoplus_{i>0} L_i \wedge L_{-i}$	$\mathfrak{t} \oplus \bigwedge^2 ((\bigoplus_i L_i)^{\perp})$
\mathfrak{sp}_∞	$\bigoplus_{i>0} L_i \& L_{-i}$	$\mathfrak{t} \oplus \operatorname{Sym}^2((\bigoplus_i L_i)^{\perp})$

Fig. 1. Maximal toral subalgebra t and Cartan subalgebra h associated to a maximal (self-)dual system.

by Theorems 4.3, 4.5, 4.7, and 4.8. Therefore maximal toral subalgebras correspond to maximal (self-)dual systems. \Box

Explicitly, the maximal toral subalgebra t and the Cartan subalgebra \mathfrak{h} in \mathfrak{g} associated to a maximal (self-)dual system for \mathfrak{g} are given in Fig. 1. Note that a maximal toral subalgebra $\mathfrak{t} \subseteq \mathfrak{g}$ is splitting if and only if V = V' and $V_* = V'_*$. In that case necessarily $(\bigoplus_i L_i)^{\perp} = 0$ and $(\bigoplus_i L^i)^{\perp} = 0$ for \mathfrak{gl}_{∞} or \mathfrak{sl}_{∞} , $(\bigoplus_i L_i)^{\perp} = 0$ for \mathfrak{sp}_{∞} , and for \mathfrak{so}_{∞} $(\bigoplus_i L_i)^{\perp}$ is 0 or 1-dimensional. In fact, these conditions are equivalent to being splitting.

4.6. The case of a general \mathfrak{g}

The following theorem is our main result on Cartan subalgebras of general root-reductive Lie algebras and strengthens Theorem 3.2 in this case.

Theorem 4.12. Let \mathfrak{g} be a root-reductive Lie algebra and $\mathfrak{h} \subseteq \mathfrak{g}$ a Cartan subalgebra. Then \mathfrak{h} is nilpotent of depth at most 2, and $\mathfrak{h} = \mathfrak{g}^0(\mathfrak{h})$.

Proof. Let $\mathfrak{t} := \mathfrak{h}_{ss}$, so $\mathfrak{h} = \mathfrak{zg}(\mathfrak{t})$. We first show that $\mathfrak{zg},\mathfrak{g}(\mathfrak{t})$ is nilpotent of depth at most 2. Recalling the decomposition of $[\mathfrak{g},\mathfrak{g}]$ in Theorem 4.1(2), let \mathfrak{g}_{fd} be the direct sum of all finite-dimensional simple direct summands of $[\mathfrak{g},\mathfrak{g}]$, and \mathfrak{g}_{id} the direct sum of all infinite-dimensional simple direct summands of $[\mathfrak{g},\mathfrak{g}]$. As there are no nontrivial extensions of an abelian Lie algebra by a finite-dimensional reductive Lie algebra, we get the decomposition

$$\mathfrak{g} = \mathfrak{g}_{\mathrm{fd}} \oplus (\mathfrak{g}_{\mathrm{id}} \oplus \mathfrak{a}),$$

where a is abelian. Then $\mathfrak{t} = \mathfrak{t}_1 \oplus \mathfrak{t}_2$ where \mathfrak{t}_1 is a maximal toral subalgebra of $\mathfrak{g}_{\mathrm{fd}}$ and \mathfrak{t}_2 is a maximal toral subalgebra of $\mathfrak{g}_{\mathrm{id}} \oplus \mathfrak{a}$. So $\mathfrak{z}_{[\mathfrak{g},\mathfrak{g}]}(\mathfrak{t}) = \mathfrak{z}_{\mathfrak{g}_{\mathrm{fd}}}(\mathfrak{t}_1) \oplus \mathfrak{z}_{\mathfrak{g}_{\mathrm{id}}}(\mathfrak{t}_2)$. As \mathfrak{t}_1 is self-centralizing in $\mathfrak{g}_{\mathrm{fd}}$, it remains to show that $\mathfrak{z}_{\mathfrak{g}_{\mathrm{id}}}(\mathfrak{t}_2)$ is nilpotent of depth at most 2. Let $\mathfrak{g}_{\mathrm{id}} = \bigoplus_j \mathfrak{s}_j$ be the decomposition of $\mathfrak{g}_{\mathrm{id}}$ into simple direct summands. Since $[\mathfrak{s}_i, \mathfrak{g}] \subseteq \mathfrak{s}_i$, we have

$$\mathfrak{z}_{(\bigoplus_j \mathfrak{s}_j)}(\mathfrak{t}_2) = \bigoplus_j \mathfrak{z}_{\mathfrak{s}_j}(\mathfrak{t}_2)$$

Theorems 4.3(4), 4.5(4), and 4.8(4) imply that $\mathfrak{z}_{\mathfrak{g}_{id}}(\mathfrak{t}_2)$ is nilpotent of depth at most 2. Thus $\mathfrak{z}_{\mathfrak{g},\mathfrak{g}}(\mathfrak{t})$ is a Lie algebra nilpotent of depth at most 2.

Recall from Theorem 3.2 that $\mathfrak{z}_{\mathfrak{g}}(\mathfrak{t})$ is splittable. If $h = h_{ss} + h_{nil} \in \mathfrak{z}_{\mathfrak{g}}(\mathfrak{t})$, then h_{ss} , $h_{nil} \in \mathfrak{z}_{\mathfrak{g}}(\mathfrak{t})$. By definition $h_{ss} \in \mathfrak{t}$, and $h_{nil} \in [\mathfrak{g}, \mathfrak{g}]$ as h_{nil} is nilpotent. Thus $\mathfrak{z}_{\mathfrak{g}}(\mathfrak{t}) = \mathfrak{t} + \mathfrak{z}_{[\mathfrak{g},\mathfrak{g}]}(\mathfrak{t})$. Since \mathfrak{t} is central in $\mathfrak{z}_{\mathfrak{g}}(\mathfrak{t})$, it follows that $\mathfrak{z}_{\mathfrak{g}}(\mathfrak{t})$ is nilpotent of depth no greater than 2.

Finally, the nilpotence of \mathfrak{h} implies $\mathfrak{h} \subseteq \mathfrak{g}^0(\mathfrak{h})$. Therefore the condition $\mathfrak{h} = \overline{\mathfrak{g}^0(\mathfrak{h})}$ together with the inclusions $\mathfrak{h} \subseteq \mathfrak{g}^0(\mathfrak{h}) \subseteq \overline{\mathfrak{g}^0(\mathfrak{h})}$ yields $\mathfrak{h} = \mathfrak{g}^0(\mathfrak{h})$. \Box

In the case of $\mathfrak{g} = \mathfrak{gl}_{\infty}$, any maximal toral subalgebra of \mathfrak{g} surjects onto $\mathfrak{g}/[\mathfrak{g},\mathfrak{g}]$ [NP]. In general, the map $\mathfrak{t} \to \mathfrak{g}/[\mathfrak{g},\mathfrak{g}]$ does not have to be surjective. For example, consider the Lie algebra \mathfrak{g} defined as the direct limit of the inclusions

$$\mathfrak{gl}_{2n} \hookrightarrow \mathfrak{gl}_{2n+2},$$
$$A \mapsto \begin{bmatrix} \frac{\operatorname{Tr}(A)}{n} & & \\ & & 0 \end{bmatrix}.$$

Clearly we have the exact sequence

$$0 \to \mathfrak{sl}_{\infty} = [\mathfrak{g}, \mathfrak{g}] \to \mathfrak{g} \to \mathbb{C} \to 0.$$

Let $B_{2n} \in \mathfrak{gl}_{2n}$ denote the matrix

$$\begin{bmatrix} I_n & 0_n \\ 0_n & 0_n \end{bmatrix},$$

and let *B* denote the element of \mathfrak{g} defined by the sequence (B_{2n}) . Then as a vector space \mathfrak{g} is isomorphic to $\mathfrak{sl}_{\infty} \oplus \mathbb{C}B$. We will exhibit a Cartan subalgebra of \mathfrak{g} whose image in \mathbb{C} is trivial.

For $n \in \mathbb{Z}_{>0}$, let $C_n \in \mathfrak{sl}_{2n}$ be the matrix whose only nonzero entry is a 1 in the upper right corner, and let $C_{-n} \in \mathfrak{sl}_{2n}$ be the matrix whose only nonzero entry is a 1 in the lower left corner. Then $\mathfrak{t} := \operatorname{Span}_{n>0} \{C_n + C_{-n}\}$ is a toral subalgebra of \mathfrak{g} . We will show that $\mathfrak{z}_{\mathfrak{g}}(\mathfrak{t}) \subseteq \mathfrak{sl}_{\infty}$. A general element of \mathfrak{g} lies in \mathfrak{gl}_{2n} for some n > 0, and hence it may be expressed as M + aB for some $M \in \mathfrak{sl}_{2n}$ and $a \in \mathbb{C}$. The computation $[M + aB, C_{n+1} + C_{-(n+1)}] = a(C_{n+1} - C_{-(n+1)})$ implies that if M + aB centralizes \mathfrak{t} , then a = 0. Let \mathfrak{h} be a Cartan subalgebra which is the centralizer of any maximal toral subalgebra containing \mathfrak{t} . The containments $\mathfrak{h} \subseteq \mathfrak{z}_{\mathfrak{g}}(\mathfrak{t}) \subseteq \mathfrak{sl}_{\infty}$ imply that \mathfrak{h} maps trivially in \mathbb{C} .

Theorem 4.12 also leaves open the question whether the intersection $\mathfrak{t} \cap [\mathfrak{g}, \mathfrak{g}]$ is in general a maximal toral subalgebra of $[\mathfrak{g}, \mathfrak{g}]$. Clearly in the case of \mathfrak{gl}_{∞} the intersection of a maximal toral subalgebra with \mathfrak{sl}_{∞} is maximal. As the following example shows, the intersection is not in general maximal, and it can even be trivial.

Let $\{e_i: i \in \mathbb{Z}_{>0}\}$ be a basis of V, and let $V_j := \text{Span}\{e_1, \dots, e_j\}$. Define constants c_{ij} for $i, j \in \mathbb{Z}_{>0}$ by

$$c_{ij} := \begin{cases} 1 & j \equiv i \pmod{2^{i-1}}, \\ 0 & \text{otherwise.} \end{cases}$$

Let $f_j := \sum_{i \in \mathbb{Z}_{>0}} c_{ij}e_i$, and notice that f_j is a well-defined vector in V_j as $c_{ij} = 0$ for i > j. Observe also that $\{f_1, \ldots, f_j\}$ is a basis of V_j . We construct a root-reductive Lie algebra \mathfrak{g} with $[\mathfrak{g}, \mathfrak{g}] = \mathfrak{sl}(V, V_*)$ and $\mathfrak{g}/[\mathfrak{g}, \mathfrak{g}]$ countable dimensional. We consider the maximal toral subalgebra in \mathfrak{g} consisting of all elements of \mathfrak{g} which have all the f_j 's as eigenvectors. No nontrivial element of $\mathfrak{sl}(V, V_*)$ has this property.

By construction, $f_j - e_j = f_i$ for some unique i < j. Let $p: \mathbb{Z}_{\geq 2} \to \mathbb{Z}_{\geq 1}$ be defined by $f_j - e_j = f_{p(j)}$. In addition, define inductively positive integers d_k^l for $k, l \in \mathbb{Z}_{>0}$ by

$$d_k^l := \begin{cases} k, & 1 \leq k \leq l, \\ d_{p(k)}^l, & k > l. \end{cases}$$

Let $\mathfrak{g}_i := \mathfrak{sl}(V_i, V_i^*) \oplus \mathbb{C}^i$, and let \mathfrak{g} be the root-reductive Lie algebra defined as the direct limit of the inclusions

$$\mathfrak{g}_{i} \hookrightarrow \mathfrak{g}_{i+1},$$

$$(A,0) \mapsto \left(\begin{bmatrix} A \\ 0 \end{bmatrix}, 0 \right),$$

$$\left(0, \frac{\sum_{k=1}^{i} d_{k}^{l}}{i} x_{l} \right) \mapsto \left(\begin{bmatrix} -\frac{\gamma_{i}^{l}}{i} I_{i} \\ \gamma_{i}^{l} \end{bmatrix}, \frac{\sum_{k=1}^{i+1} d_{k}^{l}}{i+1} x_{l} \right),$$

where $\{x_l: 1 \leq l \leq i\}$ is a basis of \mathbb{C}^i , I_i is the identity matrix in $\mathfrak{gl}(V_i, V_i^*)$, and $\gamma_i^l := (i \cdot d_{i+1}^l - \sum_{k=1}^i d_k^l)/(i+1)$. Clearly $[\mathfrak{g}, \mathfrak{g}] = \mathfrak{sl}(V, V_*)$, where $V_* := \bigcup_i V_i^*$.

For $l \in \mathbb{Z}_{>0}$, define the element $t_l \in \mathfrak{g}_l$ by

$$t_l := \left((c_{ij})_{1 \leqslant i, j \leqslant l} \left(\begin{bmatrix} 1 & & \\ & \ddots & \\ & & l \end{bmatrix} - \frac{l+1}{2} I_l \right) (c_{ij})_{1 \leqslant i, j \leqslant l}^{-1}, \frac{l+1}{2} x_l \right).$$

Since t_l is the sum of a central element and the conjugate of a diagonal element of $\mathfrak{sl}(V_l, V_l^*), t_l$ is semisimple. Because t_l and t_m have the same set of eigenvectors, they commute. Explicitly, if $m \ge l$, the image of t_l in \mathfrak{g}_m is

$$\left((c_{ij})_{1\leqslant i,j\leqslant m}\left(\begin{bmatrix}d_1^l&\\&\ddots\\&&\\&&d_m^l\end{bmatrix}-\frac{\sum_{k=1}^m d_k^l}{m}I_m\right)(c_{ij})_{1\leqslant i,j\leqslant m}^{-1},\frac{\sum_{k=1}^m d_k^l}{m}x_l\right),$$

i.e. f_1, \ldots, f_m are eigenvectors of the image of t_l in \mathfrak{g}_m . Let \mathfrak{t} be the toral subalgebra of \mathfrak{g} generated by the elements t_l . We will show that no nontrivial element of $\mathfrak{sl}(V, V_*)$ centralizes \mathfrak{t} .

Suppose $C \in \mathfrak{sl}(V, V_*)$ centralizes t. Since $C \in \mathfrak{sl}(V_j, V_j^*)$ for some *j*, we may consider *C* as $\begin{pmatrix} C & 0 \\ 0 & 0 \end{bmatrix}, 0 \in \mathfrak{g}_l$ for any l > j. In the same block notation, write $t_l = \begin{pmatrix} s_l \\ 0 \\ s \end{pmatrix}, *$. Then

$$0 = \left[\left(\begin{bmatrix} C & 0 \\ 0 & 0 \end{bmatrix}, 0 \right), \left(\begin{bmatrix} * & S_l \\ 0 & * \end{bmatrix}, * \right) \right] = \left(\begin{bmatrix} * & CS_l \\ 0 & 0 \end{bmatrix}, 0 \right).$$

The *k*th column of S_l is $(j + k - p(j + k)) \sum_{i=1}^{j} c_{i,j+k} e_i$. Let *l* be sufficiently large that the vectors $\{\sum_{i=1}^{j} c_{i,j+k} e_i: 1 \le k \le l-j\}$ span V_j . Since the columns of S_l span V_j , it follows that C = 0. Hence no maximal toral subalgebra containing t intersects $\mathfrak{sl}(V, V_*)$ nontrivially.

5. Conjugacy of Cartan subalgebras of simple root-reductive Lie algebras

We define a toral subalgebra t of \mathfrak{g} , where \mathfrak{g} is one of $\mathfrak{gl}_{\infty}, \mathfrak{sl}_{\infty}, \mathfrak{so}_{\infty}$, or \mathfrak{sp}_{∞} , to be *submaximal* if t is associated to a not necessarily maximal (self-)dual system via the formulas in Fig. 1. Any nonzero submaximal toral subalgebra is associated to a unique (self-)dual system. Clearly not every toral subalgebra of \mathfrak{g} is submaximal, but any maximal toral subalgebra of \mathfrak{g} is submaximal, as seen in Corollary 4.11.

Let $GL(V, V_*)$ be the subgroup of GL(V) consisting of those elements which induce isomorphisms on $V_* \subseteq V^*$. In terms of dual bases for V and V_* , elements of $GL(V, V_*)$ are invertible matrices with finitely many nonzero entries in each row and each column, whose inverse matrices also have finitely many nonzero entries in each row and column. Observe that $\mathfrak{gl}(V, V_*) = V \otimes V_*$

is a representation of $GL(V, V_*)$, as is $\mathfrak{sl}(V, V_*)$. Similary, each of $\mathfrak{so}(V)$ and $\mathfrak{sp}(V)$ is a representation of the corresponding subgroup of GL(V, V) preserving the bilinear form. Accordingly, the subgroup GL(V, V) is denoted SO(V) or SP(V). In what follows we describe submaximal toral subalgebras of $\mathfrak{gl}(V, V_*)$ (respectively of $\mathfrak{so}(V)$ or $\mathfrak{sp}(V)$) up to conjugation by the group $GL(V, V_*)$ (respectively of $\mathfrak{SO}(V)$ or $\mathfrak{SP}(V)$).

Proposition 5.1. Let \mathfrak{g} be one of \mathfrak{gl}_{∞} , \mathfrak{sl}_{∞} , \mathfrak{so}_{∞} , or \mathfrak{sp}_{∞} , and G its corresponding group defined above. Two finite-dimensional submaximal toral subalgebras of \mathfrak{g} are conjugate by an element of G if and only if they have the same dimension.

Proof. Let \mathfrak{t}_1 and \mathfrak{t}_2 be finite-dimensional submaximal toral subalgebras of \mathfrak{g} of the same dimension. Then $\mathfrak{t}_1, \mathfrak{t}_2 \subseteq \mathfrak{g}_i$ for some i, where $\mathfrak{g} = \bigcup_i \mathfrak{g}_i$ is an exhaustion by finite-dimensional reductive Lie algebras under root inclusions $\mathfrak{g}_i \subseteq \mathfrak{g}_{i+1}$. It is clear that \mathfrak{t}_1 and \mathfrak{t}_2 , being submaximal, are conjugate in \mathfrak{g}_i by an element of the classical algebraic group G_i associated to \mathfrak{g}_i . Hence they are conjugate in \mathfrak{g} , since there is an obvious injective homomorphism of G_i into G. \Box

In what follows, we assume that all (self-)dual systems we consider are infinite. Their corresponding submaximal toral subalgebras will be infinite dimensional. Clearly all maximal (self-)dual systems are infinite.

Definition 5.2.

- (1) A dual system $\{L_i, L^i\}$ for $\mathfrak{gl}(V, V_*)$ (respectively for $\mathfrak{sl}(V, V_*)$) with $\langle \cdot, \cdot \rangle : V \times V_* \to \mathbb{C}$ and a dual system $\{M_i, M^i\}$ for $\mathfrak{gl}(W, W_*)$ (respectively for $\mathfrak{sl}(W, W_*)$) with $\langle \cdot, \cdot \rangle' : W \times W_* \to \mathbb{C}$ are *equivalent* if there exist isomorphisms $\varphi : V \to W$ and $\varphi : V_* \to W_*$ and a bijection $\sigma : \mathbb{Z}_{>0} \to \mathbb{Z}_{>0}$ such that $\langle \cdot, \cdot \rangle = \varphi^* \langle \cdot, \cdot \rangle', \varphi(L_i) = M_{\sigma(i)}$, and $\varphi(L^i) = M^{\sigma(i)}$.
- (2) A self-dual system $\{L_i\}$ for $\mathfrak{so}(V)$ (respectively for $\mathfrak{sp}(V)$) with $\langle \cdot, \cdot \rangle : V \times V \to \mathbb{C}$ and a self-dual system $\{M_i\}$ for $\mathfrak{so}(W)$ (respectively for $\mathfrak{sp}(W)$) with $\langle \cdot, \cdot \rangle' : W \times W \to \mathbb{C}$ are *equivalent* if there exist an isomorphism $\varphi : V \to W$ and a bijection $\sigma : \mathbb{Z}_{\neq 0} \to \mathbb{Z}_{\neq 0}$ such that $\langle \cdot, \cdot \rangle = \varphi^* \langle \cdot, \cdot \rangle'$ and $\varphi(L_i) = M_{\sigma(i)}$.

It is clear that equivalent (self-)dual systems for the same algebra are precisely those which are conjugate.

Lemma 5.3. Any dual system $\{M_i, M^i\}$ for $\mathfrak{gl}(W, W_*)$ is equivalent to a dual system for $\mathfrak{gl}(V, V_*)$. Similarly, any self-dual system $\{M_i\}$ for $\mathfrak{so}(W)$ (respectively for $\mathfrak{sp}(W)$) is equivalent to a self-dual system for $\mathfrak{so}(V)$ (respectively for $\mathfrak{sp}(V)$).

Proof. The first statement follows directly from Mackey's result [M, p. 171], which implies the existence of isomorphisms $W \to V$ and $W_* \to V_*$ which send $\langle \cdot, \cdot \rangle'$ to $\langle \cdot, \cdot \rangle$. Under these isomorphisms, the dual system $\{M_i, M^i\}$ maps to an equivalent dual system. Similarly, any nondegenerate (symmetric or antisymmetric) form on a countable-dimensional vector space can be diagonalized, hence there exists an isomorphism $W \to V$ which sends $\langle \cdot, \cdot \rangle'$ to $\langle \cdot, \cdot \rangle$. This isomorphism sends $\{M_i\}$ to an equivalent self-dual system. \Box

Given a dual system $\{L_i, L^i\}$ for $\mathfrak{gl}(V, V_*)$, consider the following construction. Let X be a vector space complement in V of $\bigoplus_i L_i$, and Y a vector space complement in V_* of $\bigoplus_i L^i$.

Choose for each $i \in \mathbb{Z}_{>0}$ a generator $v_i \in L_i$, and let $v^i \in L^i$ be the vector such that $\langle v_i, v^i \rangle = 1$. Forgetting the dual system, we can consider the bilinear form $\langle \cdot, \cdot \rangle$ restricted to $X \times Y$, together with the linear functionals $\lambda_i := \langle \cdot, v^i \rangle : X \to \mathbb{C}$ and $\mu_i := \langle v_i, \cdot \rangle : Y \to \mathbb{C}$. This information encodes the entire structure of the dual system, together with V, V_* , and $\langle \cdot, \cdot \rangle$, up to isomorphism. Hence we suggest the following as a useful concept.

Definition 5.4.

- (1) A complement datum for \mathfrak{gl}_{∞} or \mathfrak{sl}_{∞} is a pair of at most countable-dimensional vector spaces X and Y, a bilinear map $\omega: X \times Y \to \mathbb{C}$, a sequence of linear functionals (λ_i) on X, and a sequence of linear functionals (μ_i) on Y, for $i \in \mathbb{Z}_{>0}$.
- (2) A complement datum for so_∞ (respectively for sp_∞) is an at most countable-dimensional vector space X together with a symmetric (respectively antisymmetric) bilinear form ω on X and a sequence of linear functionals (λ_i) on X, for i ∈ Z_{≠0}.

From a dual system for $\mathfrak{gl}(V, V_*)$ and choices of v_i , v^i , X and Y as described above, we can produce a complement datum for \mathfrak{gl}_{∞} . Such a dual system and complement datum are said to be *compatible*. Similarly, a dual system for $\mathfrak{sl}(V, V_*)$ and a complement datum for \mathfrak{sl}_{∞} obtained from it by the same procedure are said to be *compatible*. We will think of compatibility as a relation.

The notion of compatibility between a self-dual system and a complement datum for \mathfrak{so}_{∞} or \mathfrak{sp}_{∞} is similar. Fix a self-dual system $\{L_i\}$ for $\mathfrak{so}(V)$ or $\mathfrak{sp}(V)$, and we construct a complement datum as follows. Let X be a vector space complement of $\bigoplus_i L_i$ in V, and choose a nonzero $v_i \in L_i$ for i > 0, and let $v_{-i} \in L_{-i}$ be determined by $\langle v_i, v_{-i} \rangle = 1$. Consider the restriction of $\langle \cdot, \cdot \rangle$ to $X \times X$ together with the linear functionals on X given by $\lambda_i := \langle \cdot, v_i \rangle \colon X \to \mathbb{C}$. Again, the self-dual system and any complement datum obtained from it in this way are said to be *compatible*.

We will say that two sequences a_i and b_i are *almost equal*, and write $(a_i) \approx (b_i)$, if $a_i = b_i$ for all but finitely many *i*. Let X_0 be the set of $x \in X$ such that $(\lambda_i(x)) \approx 0$. In the case of \mathfrak{gl}_{∞} or \mathfrak{sl}_{∞} , let Y_0 be the set of $y \in Y$ such that $(\mu_i(y)) \approx 0$.

For a fixed (self-)dual system, one might choose a compatible complement datum in such a way that X would actually contain the set of $x \in V$ such that $\lambda_i(x) = 0$ for all *i*. In this case, X_0 would be this orthogonal complement. The examples we give will all have this property. We do not require this property in general because it is not necessary and complicates the statements and proofs.

Given a complement datum $(X, Y, \omega, (\lambda_i), (\mu_i))$ for \mathfrak{gl}_{∞} or \mathfrak{sl}_{∞} , consider the formal sum

$$\tilde{\omega} := \omega - \sum_{i \in \mathbb{Z}_{>0}} \lambda_i \otimes \mu_i,$$

where in what follows we consider ω as a linear map $X \otimes Y \to \mathbb{C}$. Note that $\tilde{\omega}$ is a well-defined linear map when restricted to $X_0 \otimes Y$ or $X \otimes Y_0$.

Given a complement datum $(X, \omega, (\lambda_i))$ for \mathfrak{so}_{∞} , we define analogously

$$\tilde{\omega} := \omega - \sum_{i \in \mathbb{Z}_{>0}} \lambda_i \& \lambda_{-i}.$$

In the case of \mathfrak{sp}_{∞} , we define

$$ilde{\omega} := \omega - \sum_{i \in \mathbb{Z}_{>0}} \lambda_i \wedge \lambda_{-i}$$

Observe that $\tilde{\omega}$ is a linear map when restricted to $X_0 \otimes X$ or $X \otimes X_0$. Moreover, we see that $\tilde{\omega}$ retains from ω the property of symmetry or antisymmetry.

Definition 5.5.

- A complement datum (X, Y, ω, (λ_i), (μ_i)) for gl_∞ or sl_∞ is *nondegenerate* if for any nonzero x₀ ∈ X₀ there exists y ∈ Y such that ω̃(x₀, y) ≠ 0, and for any nonzero y₀ ∈ Y₀ there exists x ∈ X such that ω̃(x, y₀) ≠ 0. Moreover (X, Y, ω, (λ_i), (μ_i)) is *maximal* if ω̃ restricted to X₀ ⊗ Y₀ is trivial.
- (2) A complement datum $(X, \omega, (\lambda_i))$ for \mathfrak{so}_{∞} is *nondegenerate* if for any nonzero $x_0 \in X_0$ there exists $x \in X$ such that $\tilde{\omega}(x_0, x) \neq 0$. Moreover $(X, \omega, (\lambda_i))$ is *maximal* if $\tilde{\omega}$ restricted to $X_0 \otimes X_0$ has rank 0 or 1.
- (3) A complement datum (X, ω, (λ_i)) for sp_∞ is *nondegenerate* if for any nonzero x₀ ∈ X₀ there exists x ∈ X such that ω̃(x₀, x) ≠ 0. Moreover (X, ω, (λ_i)) is *maximal* if ω̃ restricted to X₀ ⊗ X₀ is trivial.

Proposition 5.6. Any complement datum which is compatible with a (self-)dual system is nondegenerate. For any compatible pair, the complement datum is maximal if and only if the (self-)dual system is maximal.

Proof. We prove the proposition in the case of \mathfrak{gl}_{∞} , and the other cases are similar.

Suppose $(X, Y, \omega, (\lambda_i), (\mu_i))$ is a complement datum compatible with a dual system for $\mathfrak{gl}(V, V_*)$. Take a nonzero vector $x_0 \in X_0$. Since $(\lambda_i(x_0)) \approx 0$, we see that $x_0 - \sum \lambda_i(x_0)v_i$ is a well-defined nonzero vector in V. Hence, by the nondegeneracy of $\langle \cdot, \cdot \rangle$, there exists $w \in V_*$ such that $\langle x_0 - \sum \lambda_i(x_0)v_i, w \rangle \neq 0$. Let $w = y + \sum b_j v^j$, with $y \in Y$. We compute:

$$0 \neq \left\langle x_0 - \sum \lambda_i(x_0)v_i, y + \sum b_j v^j \right\rangle = \omega(x_0, y) - \sum \lambda_i(x_0)\mu_i(y)$$
$$= \tilde{\omega}(x_0, y).$$

Similarly, if $y_0 \in Y_0$ the analogous calculation shows that there exists $x \in X$ such that $\tilde{\omega}(x, y_0) \neq 0$.

We turn to maximality. Suppose that the dual system $\{\mathbb{C}v_i, \mathbb{C}v^i\}$ for $\mathfrak{gl}(V, V_*)$ is not maximal. Then there exist vectors $v_0 \in V$ and $v^0 \in V_*$ such that $\langle v_i, v^j \rangle = \delta_{ij}$. Let $v_0 = x + \sum a_j v_j$ and $v^0 = y + \sum b_k v^k$ for $x \in X$ and $y \in Y$. Note $(a_j) \approx 0$ and $(b_j) \approx 0$. We calculate $\lambda_i(x) = \langle x, v^i \rangle = -a_i$, and $\mu_i(y) = -b_i$. Hence $(\lambda_i(x)) \approx 0$ and $(\mu_i(y)) \approx 0$, so $x \in X_0$ and $y \in Y_0$. Now,

$$1 = \langle v_0, v^0 \rangle = \langle x, y \rangle + \sum b_k \lambda_k(x) + \sum a_j \mu_j(y) + \sum a_\ell b_\ell$$
$$= \omega(x, y) - \sum \lambda_k(x) \mu_k(y) = \tilde{\omega}(x, y).$$

In the other direction, let $(X, Y, \omega, (\lambda_i), (\mu_i))$ be a nonmaximal complement datum compatible with a dual system for $\mathfrak{gl}(V, V_*)$. Fix $x \in X_0$ and $y \in Y_0$ such that $\tilde{\omega}(x, y) = 1$. Let $v_0 := x - \sum \lambda_j(x)v_j$ and $v^0 := y - \sum \mu_k(y)v^k$. We calculate $\langle v_0, v^i \rangle = \lambda_i(x) - \lambda_i(x) = 0$ for i > 0. Similarly, $\langle v^i, v_0 \rangle = 0$ for i > 0. Finally, $\langle v_0, v^0 \rangle = \tilde{\omega}(x, y) = 1$. \Box

Lemma 5.7. Any nondegenerate complement datum is compatible with some (self-)dual system.

Proof. Let $(X, Y, \omega, (\lambda_i), (\mu_i))$ be a nondegenerate complement datum for \mathfrak{gl}_{∞} or \mathfrak{sl}_{∞} . Define $V := X \bigoplus \bigoplus_i \mathbb{C} v_i$ and $V_* := Y \bigoplus \bigoplus_i \mathbb{C} v^i$. We define a bilinear map $\langle \cdot, \cdot \rangle$ on $V \times V_*$ by extending ω via $\langle x, v^i \rangle := \lambda_i(x)$ for $x \in X$, and $\langle v_i, y \rangle := \mu_i(y)$ for $y \in Y$, and $\langle v_i, v^j \rangle := \delta_{ij}$.

Consider a nonzero element $v = x + \sum_{i} a_i v_i \in V$. We see that $\langle v, v^j \rangle$ is nonzero for some j, unless $x \in X_0$ and a certain condition on a_i is satisfied, namely that $a_i = -\lambda_i(x)$. But if $v = x - \sum_i \lambda_i(x)v_i$ is nonzero, then x must be nonzero, and there exists $y \in Y$ such that $0 \neq \tilde{\omega}(x, y) = \omega(x, y) - \sum_i \lambda_i(x)\mu_i(y) = \langle x, y \rangle - \sum_i \lambda_i(x)\langle v_i, y \rangle = \langle v, y \rangle$. Similarly, any nonzero element in V_* pairs nontrivially with an element of V. Hence $\langle \cdot, \cdot \rangle$ is a nondegenerate pairing between V and V_* . So { $\mathbb{C}v_i, \mathbb{C}v^i$ } is a dual system for $\mathfrak{gl}(V, V_*)$ or for $\mathfrak{sl}(V, V_*)$ which is compatible with the given complement datum.

Now suppose we are given a nondegenerate complement datum $(X, \omega, (\lambda_i))$ for \mathfrak{so}_{∞} or \mathfrak{sp}_{∞} . Define $V := X \oplus \bigoplus_i \mathbb{C}v_i$. We define a bilinear form $\langle \cdot, \cdot \rangle$ on V by extending ω appropriately (i.e. symmetrically or antisymmetrically) via $\langle x, v_i \rangle := \lambda_i(x)$ for $x \in X$, and $\langle v_i, v_j \rangle := 0$ for $i \neq -j$, and $\langle v_i, v_{-i} \rangle := 1$ for i > 0.

Consider a nonzero element $v = x + \sum_{i} a_i v_i \in V$. We see that $\langle v, v_j \rangle$ is nonzero for some j, unless $x \in X_0$ and the coefficients a_i satisfy some condition. In the \mathfrak{so}_{∞} case, the condition is $a_i = -\lambda_{-i}(x)$. But if $v = x - \sum_i \lambda_{-i}(x)v_i$, then x is nonzero, and there exists $y \in X$ such that $0 \neq \tilde{\omega}(x, y) = \omega(x, y) - \sum_i \lambda_{-i}(x)\lambda_i(y) = \langle x, y \rangle - \sum_i \lambda_{-i}(x)\langle v_i, y \rangle = \langle v, y \rangle$.

In the \mathfrak{sp}_{∞} case, the condition is $a_i = -\operatorname{sgn}(i)\lambda_{-i}(x)$. But if $v = x - \sum_i \operatorname{sgn}(i)\lambda_{-i}(x)v_i$, then x is nonzero, and there exists $y \in X$ such that $0 \neq \tilde{\omega}(x, y) = \omega(x, y) + \sum_i \operatorname{sgn}(i)\lambda_{-i}(x)\lambda_i(y) = \langle x, y \rangle - \sum_i \operatorname{sgn}(i)\lambda_{-i}(x)\langle v_i, y \rangle = \langle v, y \rangle$.

Thus, in either case, $\langle \cdot, \cdot \rangle$ is a nondegenerate bilinear form. So $\{\mathbb{C}v_i\}$ is a self-dual system for $\mathfrak{so}(V)$ or $\mathfrak{sp}(V)$ which is compatible with the given complement datum. \Box

Definition 5.8.

- (1) Two complement data $(X, Y, \omega, (\lambda_i), (\mu_i))$ and $(X', Y', \omega', (\lambda'_i), (\mu'_i))$ for \mathfrak{gl}_{∞} or \mathfrak{sl}_{∞} are *equivalent* if there exist a bijection $\sigma : \mathbb{Z}_{>0} \to \mathbb{Z}_{>0}$, isomorphisms $\pi : X \to X'$ and $\pi : Y \to Y'$, and nonzero constants α_i , such that $(\lambda_i(x)) \approx (\alpha_i \lambda'_{\sigma(i)} \circ \pi(x))$ for all $x \in X$, $(\mu_i(y)) \approx (\alpha_i^{-1} \mu'_{\sigma(i)} \circ \pi(y))$ for all $y \in Y$, and $\tilde{\omega} \pi^*(\tilde{\omega}') = 0$ on $X \otimes Y$.
- (2) Two complement data $(X, \omega, (\lambda_i))$ and $(X', \omega', (\lambda'_i))$ for \mathfrak{so}_{∞} are *equivalent* if there exist a bijection $\sigma : \mathbb{Z}_{\neq 0} \to \mathbb{Z}_{\neq 0}$ such that $\sigma(-i) = -\sigma(i)$, an isomorphism $\pi : X \to X'$, and nonzero constants α_i with $\alpha_{-i} = \alpha_i^{-1}$, such that $(\lambda_i(x)) \approx (\alpha_i \lambda'_{\sigma(i)} \circ \pi(x))$ for all $x \in X$ and $\tilde{\omega} \pi^*(\tilde{\omega}') = 0$ on $X \otimes X$.
- (3) Two complement data $(X, \omega, (\lambda_i))$ and $(X', \omega', (\lambda'_i))$ for \mathfrak{sp}_{∞} are *equivalent* if there exist a bijection $\sigma : \mathbb{Z}_{\neq 0} \to \mathbb{Z}_{\neq 0}$ such that $\sigma(-i) = -\sigma(i)$, an isomorphism $\pi : X \to X'$, and nonzero constants α_i with $\alpha_{-i} = \alpha_i^{-1} \operatorname{sgn}(i) \operatorname{sgn}(\sigma(i))$, such that $(\lambda_i(x)) \approx (\alpha_i \lambda'_{\sigma(i)} \circ \pi(x))$ for all $x \in X$ and $\tilde{\omega} \pi^*(\tilde{\omega}') = 0$ on $X \otimes X$.

Note that the left-hand side of the equation $\tilde{\omega} - \pi^*(\tilde{\omega}') = 0$ in (1) above is in fact a finite sum when applied to any $x \otimes y \in X \otimes Y$. Likewise, $\tilde{\omega} - \pi^*(\tilde{\omega}')$ in (2) and (3) is a finite sum when applied to any $x \otimes x' \in X \otimes X$.

The following theorem is our main result in Section 5.

Theorem 5.9. Let \mathfrak{g} be one of $\mathfrak{gl}(V, V_*)$, $\mathfrak{sl}(V, V_*)$, $\mathfrak{so}(V)$, and $\mathfrak{sp}(V)$. The compatibility relation between (self-)dual systems and complement data induces a bijection between conjugacy classes of submaximal toral subalgebras of \mathfrak{g} and equivalence classes of nondegenerate complement data. Under this bijection, conjugacy classes of maximal toral subalgebras of \mathfrak{g} correspond to equivalence classes of nondegenerate maximal complement data.

Proof. We will prove the proposition in the case of $\mathfrak{g} = \mathfrak{gl}(V, V_*)$, and the other cases are similar.

There is a bijection between conjugacy classes of submaximal toral subalgebras of \mathfrak{g} and conjugacy classes of dual systems for \mathfrak{g} , which comes from the bijection of submaximal toral subalgebras of \mathfrak{g} and dual systems for \mathfrak{g} . There is also a bijection between conjugacy classes of dual systems for \mathfrak{g} and equivalence classes of dual systems, by Lemma 5.3. We will show that compatibility induces a bijection between equivalence classes of dual systems and equivalence classes of nondegenerate complement data. The second statement then follows immediately from Proposition 5.6, which says that compatibility preserves maximality.

We first prove that compatibility induces a well-defined map from equivalence classes of dual systems to equivalence classes of complement data. Let $\{L_i, L^i\}$ be a dual system for $\mathfrak{gl}(V, V_*)$, and $\{M_i, M^i\}$ an equivalent dual system for $\mathfrak{gl}(W, W_*)$. Choose complement data $(X, Y, \omega, (\lambda_i), (\mu_i))$ and $(X', Y', \omega', (\lambda'_i), (\mu'_i))$ compatible with these dual systems. We have implicitly chosen generators $v_i \in L_i$, $v^i \in L^i$, $w_i \in M_i$, and $w^i \in M^i$. We have isomorphisms $\varphi: V \to W$ and $\varphi: V_* \to W_*$ and a bijection $\sigma: \mathbb{Z}_{>0} \to \mathbb{Z}_{>0}$ such that $\langle \cdot, \cdot \rangle = \varphi^* \langle \cdot, \cdot \rangle', \varphi(L_i) = M_{\sigma(i)}$, and $\varphi(L^i) = M^{\sigma(i)}$. Let $\alpha_i \in \mathbb{C}$ be the nonzero constant such that $\varphi(v^i) = \alpha_i w^{\sigma(i)}$ (and hence $\varphi(v_i) = \alpha_i^{-1} w_{\sigma(i)}$).

The map

$$\varphi|_X : X \to X' \oplus \operatorname{Span}_i\{M_i\},$$

 $x \mapsto \left(\pi(x), \sum \nu_i(x)w_i\right)$

defines a map $\pi: X \to X'$ and linear functionals $v_i: X \to \mathbb{C}$. Notice that $(v_i(x)) \approx 0$ for all $x \in X$. Clearly π is an isomorphism. Similarly,

$$\varphi|_{Y}: Y \to Y' \oplus \operatorname{Span}_{i} \{M^{i}\},$$
$$y \mapsto \left(\pi(y), \sum \eta_{i}(y)w^{i}\right)$$

defines $\pi: Y \to Y'$ and $\eta_i: Y \to \mathbb{C}$. Again, $(\eta_i(y)) \approx 0$ for all $y \in Y$. Compute

$$\lambda_i(x) = \langle x, v^i \rangle = \langle \varphi(x), \varphi(v^i) \rangle'$$

= $\langle \pi(x) + \sum v_j(x) w_j, \alpha_i w^{\sigma(i)} \rangle' = \alpha_i \lambda'_{\sigma(i)}(\pi(x)) + \alpha_i v_{\sigma(i)}(x).$

Hence for any $x \in X$ we have $(\lambda_i(x)) \approx (\alpha_i \lambda'_{\sigma(i)} \circ \pi(x))$. The analogous calculation shows $(\mu_i(y)) \approx (\alpha_i^{-1} \mu'_{\sigma(i)} \circ \pi(y))$ for all $y \in Y$. Then compute

$$\begin{split} \omega(x, y) &= \langle x, y \rangle = \langle \varphi(x), \varphi(y) \rangle' \\ &= \left\langle \pi(x) + \sum \nu_j(x) w_j, \pi(y) + \sum \eta_k(y) w^k \right\rangle' \\ &= \omega' \big(\pi(x), \pi(y) \big) - \sum \lambda'_k \big(\pi(x) \big) \mu'_k \big(\pi(y) \big) + \sum \lambda_l(x) \mu_l(y), \end{split}$$

i.e. $\tilde{\omega} - \pi^* \tilde{\omega}' = 0$ on $X \otimes Y$. This shows that the two complement data $(X, Y, \omega, (\lambda_i), (\mu_i))$ and $(X', Y', \omega', (\lambda'_i), (\mu'_i))$ are equivalent. Hence the compatibility relation induces a map from equivalence classes of dual systems to equivalence classes of nondegenerate complement data, where nondegeneracy follows from Proposition 5.6.

The surjectivity of this map follows from Lemma 5.7. For injectivity we will show that if two dual systems are compatible with equivalent complement data, then the two dual systems are equivalent.

Suppose that the dual systems $\{\mathbb{C}v_i, \mathbb{C}v^i\}$ for $\mathfrak{gl}(V, V_*)$ and $\{\mathbb{C}w_i, \mathbb{C}w^i\}$ for $\mathfrak{gl}(W, W_*)$ are compatible with complement data $(X, Y, \omega, (\lambda_i), (\mu_i))$ and $(X', Y', \omega', (\lambda'_i), (\mu'_i))$, respectively, and that these complement data are equivalent. There exist isomorphisms $\pi : X \to X'$ and $\pi : Y \to Y'$, nonzero constants α_i together with a bijection $\sigma : Z_{>0} \to Z_{>0}$ such that $(\lambda_i(x)) \approx (\alpha_i \lambda'_{\sigma(i)} \circ \pi(x))$ for all $x \in X$ and $(\mu_i(y)) \approx (\alpha_i^{-1} \mu'_{\sigma(i)} \circ \pi(y))$ for all $y \in Y$, and $\tilde{\omega} - \pi^* \tilde{\omega}' = 0$ on $X \otimes Y$. Define linear functionals v_i on X and η_i on Y by

$$\nu_i: X \to \mathbb{C}, \quad x \mapsto \lambda_i(x) - \alpha_i \lambda'_{\sigma(i)}(\pi(x))$$

and

$$\eta_i: Y \to \mathbb{C}, \quad y \mapsto \mu_i(y) - \alpha_i^{-1} \mu'_{\sigma(i)}(\pi(y)).$$

Then $(v_i(x)) \approx 0$ for all $x \in X$ and $(\eta_i(y)) \approx 0$ for all $y \in Y$. We have $V = X \oplus \bigoplus_i \mathbb{C}v_i$ and $V_* = Y \oplus \bigoplus_i \mathbb{C}v^i$. Similarly, $W = X' \oplus \bigoplus_i \mathbb{C}w_i$ and $W_* = Y' \oplus \bigoplus_i \mathbb{C}w^i$. We define

$$\varphi: V \to W,$$

$$x + \sum a_i v_i \mapsto \pi(x) + \sum (v_i(x) + a_i) \alpha_i^{-1} w_{\sigma(i)}$$

and

$$\varphi: V_* \to W_*,$$

$$y + \sum a_i v^i \mapsto \pi(y) + \sum (\eta_i(y) + a_i) \alpha_i w^{\sigma(i)}.$$

These isomorphisms establish the equivalence of dual systems. \Box

We are ready now to draw some corollaries from Theorem 5.9.

In the spirit of [NP], we introduce the five *standard invariants* of an infinite dual system (and hence of an infinite-dimensional submaximal toral subalgebra or a Cartan subalgebra of \mathfrak{gl}_{∞} or \mathfrak{sl}_{∞}):

$$(\operatorname{rank}\langle\cdot,\cdot\rangle|_{T^{\perp}\times S^{\perp}}, \dim T^{\perp}, \dim S^{\perp}, \operatorname{codim}(T^{\perp}\oplus S), \operatorname{codim}(S^{\perp}\oplus T)),$$

where $S := \bigoplus_i L_i$ and $T := \bigoplus_i L^i$. The invariants take values in $\mathbb{Z}_{\geq 0} \cup \{\aleph_0\}$. If a dual system for $\mathfrak{gl}(V, V_*)$ or $\mathfrak{sl}(V, V_*)$ is compatible with the complement datum $(X, Y, \omega, (\lambda_i), (\mu_i))$, then one may check that the five standard invariants are

$$(\operatorname{rank} \tilde{\omega}|_{X_0 \times Y_0}, \dim X_0, \dim Y_0, \dim X/X_0, \dim Y/Y_0).$$

Similarly, there are three *standard invariants* of an infinite self-dual system (and hence of an infinite-dimensional submaximal toral subalgebra or a Cartan subalgebra of \mathfrak{so}_{∞} or \mathfrak{sp}_{∞}):

 $(\operatorname{rank}\langle\cdot,\cdot\rangle|_{S^{\perp}\times S^{\perp}}, \dim S^{\perp}, \operatorname{codim}(S^{\perp}\oplus S)),$

where $S := \bigoplus_i L_i$. If a self-dual system for $\mathfrak{so}(V)$ or $\mathfrak{sp}(V)$ is compatible with the complement datum $(X, \omega, (\lambda_i))$, then the three standard invariants are

$$(\operatorname{rank} \tilde{\omega}|_{X_0 \times X_0}, \dim X_0, \dim X/X_0).$$

Corollary 5.10.

- (1) There exists a submaximal toral subalgebra of \mathfrak{gl}_{∞} or \mathfrak{sl}_{∞} with standard invariants (d, p, q, m, n) precisely when $0 \leq p d \leq n$ and $0 \leq q d \leq m$.
- (2) There exists a submaximal toral subalgebra of so_∞ with standard invariants (d, p, m) precisely when 0 ≤ p − d ≤ m.
- (3) There exists a submaximal toral subalgebra of sp_∞ with standard invariants (d, p, m) precisely when 0 ≤ p − d ≤ m and d is even when it is finite.

Proof. We will give proofs which assume that the invariants are all finite, and we leave it to the reader to make the necessary modifications for the cases when the invariants are allowed to equal \aleph_0 .

(1) From the definition of a nondegenerate complement datum, $\tilde{\omega}$ yields surjections $X/X_0 \rightarrow (\operatorname{right} \ker \tilde{\omega}|_{X_0 \times Y_0})^*$ and $Y/Y_0 \rightarrow (\operatorname{left} \ker \tilde{\omega}|_{X_0 \times Y_0})^*$. Thus $\dim X/X_0 \ge \dim Y_0 - \operatorname{rank} \tilde{\omega}|_{X_0 \times Y_0} \ge 0$ and $\dim Y/Y_0 \ge \dim X_0 - \operatorname{rank} \tilde{\omega}|_{X_0 \times Y_0} \ge 0$.

Given $0 \le p-d \le n$ and $0 \le q-d \le m$, we construct a nondegenerate complement datum for \mathfrak{gl}_{∞} or \mathfrak{sl}_{∞} with standard invariants (d, p, q, m, n) as follows. Let X be a vector space with basis $\{x_{-p}, \ldots, x_{-1}, x_1, \ldots, x_m\}$, and let Y be a vector space with basis $\{y_{-q}, \ldots, y_{-1}, y_1, \ldots, y_n\}$. Define $\omega: X \times Y \to \mathbb{C}$ by setting $\omega(x_{-p+j}, y_{-q+j}) := 1$ for $j = 0, \ldots, d-1$, and setting $\omega(x_{-j}, y_j) := 1$ for $j = 1, \ldots, p-d$, and setting $\omega(x_j, y_{-j}) := 1$ for $j = 1, \ldots, q-d$ and letting all other pairings in this basis be trivial. For $\iota \in \mathbb{Z}_{>0}$ define $\lambda_{\iota} := x_{\iota}^*$ where $\overline{\iota} \in \{1, \ldots, m\}$ and $\overline{\iota} \equiv \iota \pmod{m}$, and $\mu_{\iota} := y_{\iota}^*$ where $\overline{\iota} \in \{1, \ldots, n\}$ and $\overline{\iota} \equiv \iota \pmod{m}$. Then X_0 has basis $\{x_{-p}, \ldots, x_{-1}\}$, and Y_0 has basis $\{y_{-q}, \ldots, y_{-1}\}$, and $\widetilde{\omega}|_{X_0 \times Y_0}$ has rank d. This complement datum is nondegenerate, hence it gives rise to a submaximal toral subalgebra of \mathfrak{gl}_{∞} or \mathfrak{sl}_{∞} with standard invariants (d, p, q, m, n).

(2) From the definition of a nondegenerate complement datum, $\tilde{\omega}$ yields a surjection $X/X_0 \rightarrow (\operatorname{rad} \tilde{\omega}|_{X_0 \times X_0})^*$. Thus dim $X/X_0 \ge \dim X_0 - \operatorname{rank} \tilde{\omega}|_{X_0 \times X_0} \ge 0$.

Given any $0 \le p - d \le m$, we construct a nondegenerate complement datum for \mathfrak{so}_{∞} with standard invariants (d, p, m) as follows. Let X be a vector space with basis $\{x_{-p}, \ldots, x_{-1}, x_1, \ldots, x_m\}$. We define $\omega: X \times X \to \mathbb{C}$ by setting $\omega(x_{-p+j}, x_{-p+j}) := 1$ for $j = 0, \ldots, d - 1$ and setting $\omega(x_{-j}, x_j) := 1$ for $j = 1, \ldots, p - d$. For $\iota \in \mathbb{Z}_{\neq 0}$ define $\lambda_{\iota} := x_{\overline{\iota}}^*$ where $\overline{\iota} \in \{1, \ldots, m\}$ and $\overline{\iota} \equiv \iota \pmod{m}$. Then X_0 has basis $\{x_{-p}, \ldots, x_{-1}\}$, and the rank of $\tilde{\omega}|_{X_0 \times X_0}$ is d. This complement datum is nondegenerate, hence it gives rise to a submaximal toral subalgebra with standard invariants (d, p, m).

(3) The proof of the inequality is the same as for \mathfrak{so}_{∞} . We see that d, being the rank of an antisymmetric bilinear form, is even if it is finite.

Given any $0 \le p - d \le m$ and d even, we construct a nondegenerate complement datum for \mathfrak{sp}_{∞} with standard invariants (d, p, m) as follows. Let X be a vector space with basis $\{x_{-p}, \ldots, x_{-1}, x_1, \ldots, x_m\}$. We define $\omega : X \times X \to \mathbb{C}$ by setting $\omega(x_{-p+2j}, x_{-p+2j+1}) := 1$ for $j = 0, \ldots, d/2 - 1$ and setting $\omega(x_{-j}, x_j) := 1$ for $j = 1, \ldots, p - d$. For $\iota \in \mathbb{Z}_{\neq 0}$ define $\lambda_{\iota} := x_{\iota}^*$ where $\overline{\iota} \in \{1, \ldots, m\}$ and $\overline{\iota} \equiv \iota \pmod{m}$. Then X_0 has basis $\{x_{-p}, \ldots, x_{-1}\}$, and the rank of $\widetilde{\omega}|_{X_0 \times X_0}$ is d. This complement datum is nondegenerate, hence it gives rise to a submaximal toral subalgebra with standard invariants (d, p, m). \Box

A submaximal toral subalgebra of \mathfrak{gl}_{∞} , \mathfrak{sl}_{∞} , or \mathfrak{sp}_{∞} is maximal if and only if its first standard invariant is 0. A submaximal toral subalgebra of \mathfrak{so}_{∞} is maximal if and only if its first standard invariant is 0 or 1. Hence we immediately conclude the following corollary.

Corollary 5.11.

- (1) There exists a Cartan subalgebra of \mathfrak{gl}_{∞} or \mathfrak{sl}_{∞} with standard invariants (d, p, q, m, n) precisely when d = 0 and $p \leq n$ and $q \leq m$.
- (2) There exists a Cartan subalgebra of \mathfrak{so}_{∞} with standard invariants (d, p, m) precisely when d = 0, 1 and $d \leq p \leq m + d$.
- (3) There exists a Cartan subalgebra of \mathfrak{sp}_{∞} with standard invariants (d, p, m) precisely when d = 0 and $p \leq m$.

Corollary 5.12.

- The cardinality of the set of conjugacy classes of Cartan subalgebras of gl_∞ or sl_∞ with given standard invariants is 0, 1, 2, or continuum. One conjugacy class occurs precisely for standard invariants (0,0,0,0,0). Two conjugacy classes occur precisely for standard invariants (0,0,0,0,0,1), (0,1,0,0,1), and (0,0,1,1,0).
- (2) The cardinality of the set of conjugacy classes of Cartan subalgebras of so_∞ with given standard invariants is 0, 1, or continuum. One conjugacy class occurs precisely for standard invariants (0,0,0) and (1,1,0).
- (3) The cardinality of the set of conjugacy classes of Cartan subalgebras of \mathfrak{sp}_{∞} with given standard invariants is 0, 1, or continuum. One conjugacy class occurs precisely for standard invariants (0, 0, 0).

Proof. (1) Let $(X, Y, \omega, (\lambda_i), (\mu_i))$ be a complement datum for \mathfrak{gl}_{∞} or \mathfrak{sl}_{∞} with standard invariants (0, p, q, m, n). After possibly interchanging the role of X and Y, we may assume that

 $m \ge n$. First we consider each of the special cases for \mathfrak{gl}_{∞} , and then prove that in all other non-trivial cases the set of conjugacy classes has cardinality continuum. Let $\{e_i\}$ and $\{e^i\}$ be dual bases of V and V_* , indexed by $\mathbb{Z}_{>0}$.

(0, 0, 0, 0, 0): Here both X and Y have dimension 0, so there is exactly one linear functional on each space and exactly one pairing between them. Thus there is exactly one complement datum, and it is nondegenerate and maximal. Up to equivalence there is still exactly one complement datum. A dual system in this class is $\{L_i = \mathbb{C}e_i, L^i = \mathbb{C}e^i: i \in \mathbb{Z}_{>0}\}$.

(0, 0, 0, 1, 0): We see that X is 1-dimensional and Y is 0-dimensional. By setting

$$(\lambda_i, \mu_i) := \begin{cases} (1, 0), & i \in \mathbb{Z}_{>0}, \\ (\bar{i}, 0), & i \in \mathbb{Z}_{>0}, \end{cases}$$

where $\bar{i} \equiv i \pmod{2}$ and $\omega = 0$, we define two complement data. These are inequivalent because whether λ_i is zero infinitely often or finitely often is an invariant.

Notice that in the case under consideration $\mu_i = 0$ and $\omega = 0$ for an arbitrary nondegenerate maximal complement datum $(X, Y, \omega, (\lambda_i), (\mu_i))$. Up to equivalence, we may assume that $\lambda_i \in \{0, 1\}$, where $\lambda_i = 1$ must occur infinitely often since $X_0 = 0$. Therefore, up to equivalence, there are just two possibilities: $\lambda_i = 0$ occurs infinitely often or finitely often. These equivalence classes are represented by the above complement data. A dual system in the first class is $\{L_i = \mathbb{C}(e_i - e_{i+1}), L^i = \mathbb{C}(\sum_{k=1}^i e^k): i \in \mathbb{Z}_{>0}\}$, and a dual system in the second class is $\{L_i = \mathbb{C}(e_i - \overline{i}e_{i+2}), L^i = \mathbb{C}(e^i + \overline{i}\sum_{k=1}^{(i-1)/2} e^{2k-1}): i \in \mathbb{Z}_{>0}\}$, where $\overline{i} \in \{0, 1\}$ and $\overline{i} \equiv i \pmod{2}$.

(0, 0, 1, 1, 0): We see that X is 1-dimensional and $Y = Y_0$ is 1-dimensional. We define two complement data by setting

$$(\lambda_i, \mu_i) := \begin{cases} (1, 0), & i \in \mathbb{Z}_{>0}, \\ (\bar{i}, 0), & i \in \mathbb{Z}_{>0}, \end{cases}$$

where $\bar{i} \equiv i \pmod{2}$ and $\omega = 1$. These are inequivalent because whether or not $\lambda_i = 0$ occurs infinitely often is an invariant.

Since $Y = Y_0$, $(\mu_i) \approx 0$, so every complement datum is equivalent to one with $\mu_i = 0$ for all *i*. Fix $x \in X$, and we may assume $\lambda_i(x) \in \{0, 1\}$ for all *i*. Since $X_0 = 0$, we must have $\lambda_i(x) = 1$ for infinitely many *i*. Now $\tilde{\omega} = \omega$ is nonzero by nondegeneracy, so we may fix $y \in Y$ such that $\tilde{\omega}(x, y) = 1$. Up to equivalence, there are just two possibilities: $\lambda_i(x) = 0$ occurs infinitely often or finitely often. A dual system in the first class is $\{L_i = \mathbb{C}(e_{i+1}), L^i = \mathbb{C}(e^1 + e^{i+1}): i \in \mathbb{Z}_{>0}\}$, and a representative of the second class is $\{L_i = \mathbb{C}(e_{i+1}), L^i = \mathbb{C}(\bar{i}e^1 + e^{i+1}): i \in \mathbb{Z}_{>0}\}$, where $\bar{i} \in \{0, 1\}$ and $\bar{i} \equiv i \pmod{2}$.

Now suppose that $p \le n$ and $q \le m$ and that we are not in one of the above cases. Thus either m = n = 1 or $m \ge 2$. Since the cardinality of the set of all complement data for X and Y is at most continuum, it is enough to show that the cardinality of equivalence classes in each of these cases is at least continuum.

m = n = 1: We will construct a family of complement data which represents continuum many equivalence classes. The space $(X/X_0)^* \otimes (Y/Y_0)^*$ is a vector space of dimension 1 which we identify with \mathbb{C} . For any $z \in \mathbb{C} \setminus \{0, 1\}$ we define a complement datum D_z as follows. Choose λ_i and μ_i to vanish on X_0 and Y_0 , respectively, such that $\lambda_i \otimes \mu_i$ is 1 or z and each of these

two values occurs infinitely often. Choose ω to give surjections $X/X_0 \rightarrow Y_0^*$ and $Y/Y_0 \rightarrow X_0^*$. Since $\tilde{\omega}$ coincides with ω when restricted to $X \otimes Y_0$ or $X_0 \otimes Y$, such a complement datum D_z is nondegenerate and maximal for any z.

For D_z and $D_{z'}$ to be equivalent, there must be an element $\pi \in GL(\mathbb{C})$ and a permutation σ such that $(\pi(\lambda_i \otimes \mu_i)) \approx (\lambda'_{\sigma(i)} \otimes \mu'_{\sigma(i)})$. Thus there must be an element of \mathbb{C}^{\times} sending $\{1, z\}$ to $\{1, z'\}$. Hence the only other element from this family in the equivalence class of D_z is $D_{1/z}$. Therefore there are continuum many equivalence classes.

 $m \ge 2$: Consider the projective space $P = \mathbb{P}((X/X_0)^*)$, and let $S \subset P$ be an at most countable subset. We define a complement datum D_S as follows. Choose $0 \ne \lambda_i \in X^*$ such that for each $s \in S$, λ_i lies on the line *s* for infinitely many *i*. Choose $\mu_i \in Y^*$ such that $(\mu_i(y)) \approx 0$ implies $y \in Y_0$. Finally, choose ω to give surjections $X/X_0 \twoheadrightarrow Y_0^*$ and $Y/Y_0 \twoheadrightarrow X_0^*$. Since $\tilde{\omega}$ coincides with ω when restricted to $X \otimes Y_0$ or $X_0 \otimes Y$, such a complement datum D_S is nondegenerate and maximal for any *S*. Clearly if D_S and $D_{S'}$ are equivalent, then there must be an element $\pi \in GL(X)$, a bijection σ , and nonzero constants α_i such that $(\lambda_i) \approx (\alpha_i \lambda'_{\sigma(i)} \circ \pi)$. Thus there must be an element of Aut(*P*) mapping *S* to *S'*. Hence it is enough to show that there are uncountably many equivalence classes under Aut(*P*) of at most countable subsets of *P*.

Suppose that *m* is finite. Fix a set of m + 1 points in general position in *P*. For each $z \in P$ in general position, let S_z be the union of the fixed set and $\{z\}$. Since Aut(\mathbb{P}^{m-1}) acts with finite stabilizers on sets of m + 1 points in \mathbb{P}^{m-1} , each S_z is equivalent to at most a finite number of other such $S_{z'}$. Thus there are at least continuum many equivalence classes.

Suppose that m > 1, where we allow $m = \aleph_0$. The following argument was suggested by Scott Carnahan and Anton Geraschenko. Choose countably many distinct lines $\ell_1, \ell_2, ...$ in P, which is possible since m > 1. Fix a subset T of $\mathbb{Z}_{>2}$. Let t_i be the *i*th smallest element of T. On ℓ_1 choose t_1 distinct points. On ℓ_2 choose t_2 distinct points. On ℓ_3 choose t_3 distinct points each of which is not collinear with any pair of the chosen points on ℓ_1 and ℓ_2 . This is possible because there are only finitely many lines going through two of the previously chosen points. Continue choosing points to get a set S_T in P satisfying the property that exactly one subset of t_i points lie on the same line in P, and such that t_i points lie on ℓ_i . Since linear transformations preserve collinearity, we see that S_T is equivalent to $S_{T'}$ if and only if T = T'. Since there are continuum many subsets of $\mathbb{Z}_{>2}$, we have constructed representatives of continuum many equivalence classes.

(2) Let $(X, \omega, (\lambda_i))$ be a complement datum for \mathfrak{so}_{∞} with standard invariants (d, p, m). There are two special cases for \mathfrak{so}_{∞} , and then we prove that in all other nontrivial cases, there are continuum many conjugacy classes.

(0, 0, 0): In this case $X_0 = X = 0$, hence there is exactly one equivalence class of complement data. A Cartan subalgebra with these invariants arises naturally from the realization of \mathfrak{so}_{∞} as $\bigcup \mathfrak{so}_{2n}$.

(1, 1, 0): In this case $X_0 = X$ is 1-dimensional and $\tilde{\omega}$ is nontrivial. Since $(\lambda_i) \approx 0$, there is exactly one equivalence class of complement data. A Cartan subalgebra with these invariants arises naturally from the realization of \mathfrak{so}_{∞} as $\bigcup \mathfrak{so}_{2n+1}$.

 $m \ge 1$: Consider the vector space $U = (X/X_0)^* \otimes (X/X_0)^*$. Consider an at most countable set $S \subset U$. We define a complement datum D_S as follows. Choose λ_i to vanish on X_0 such that $\lambda_i \otimes \lambda_{-i} \in S$ and each element of S occurs for infinitely many i. Choose ω to have rank d on X_0 and to give a surjection $X/X_0 \rightarrow (\operatorname{rad} \omega|_{X_0 \times X_0})^*$. Since $\tilde{\omega}$ coincides with ω when restricted to $X_0 \otimes X$, such a complement datum D_S is nondegenerate and maximal for any S. Clearly if D_S and $D_{S'}$ are equivalent, then there must be an element $\pi \in GL(X)$ and a bijection σ such that $(\lambda_i \otimes \lambda_{-i}) \approx (\lambda'_{\sigma(i)} \circ \pi \otimes \lambda'_{-\sigma(i)} \circ \pi)$. Thus there must be an element of Aut(U) mapping S to S'. Hence it is enough to show that there are uncountably many equivalence classes under Aut(U) of at most countable subsets of U.

Now we can use the same two arguments from the analogous case for \mathfrak{gl}_{∞} . If *m* is finite, we can choose $m^2 + 1$ points in general position and proceed as before. If m > 1, including $m = \aleph_0$, then we can choose points on lines in *U* satisfying certain collinearity properties as before.

(3) Let $(X, \omega, (\lambda_i))$ be a complement datum for \mathfrak{sp}_{∞} with standard invariants (0, p, m). There is one special case for \mathfrak{sp}_{∞} .

(0, 0, 0): In this case $X_0 = X = 0$, thus there is exactly one conjugacy class of Cartan subalgebras, and they arise naturally from the realization of \mathfrak{sp}_{∞} as $\bigcup \mathfrak{sp}_{2n}$.

 $m \ge 1$: Repeat the proof of the $m \ge 1$ case for \mathfrak{so}_{∞} , choosing λ_i such that $\operatorname{sgn}(i)\lambda_i \otimes \lambda_{-i} \in S$. \Box

In particular, for \mathfrak{so}_{∞} and \mathfrak{sp}_{∞} , if there are finitely many conjugacy classes of Cartan subalgebras with given standard invariants, then the Cartan subalgebras with these standard invariants are splitting.

We conclude the paper with a description of a case with uncountably many equivalence classes. Let $\{e_i\}$ and $\{e^i\}$ be dual bases of V and V_* , indexed by $\mathbb{Z}_{>0}$. Consider for any pair of sequences (a_i) and (b_i) the dual system for $\mathfrak{gl}(V, V_*)$ given by $\{L_i = \mathbb{C}(b_i e_1 + e_{i+2}), L^i = \mathbb{C}(a_i e^2 + e^{i+2}): i \in \mathbb{Z}_{>0}\}$. This dual system has invariants (0, 1, 1, 1, 1) if and only if the sequences (a_i) and (b_i) are not almost equal to 0. The following are three binary invariants of these dual systems: whether for infinitely many i, a_i is nonzero; whether for infinitely many i, a_i is nonzero; whether for infinitely many i, $both a_i$ and b_i are zero.

We define a *multiset* on a set *S* as a map $m: S \to \mathbb{Z}_{\geq 0} \cup \{\aleph_0\}$ such that *m* vanishes outside a countable subset of *S*. We say m(x) is the *multiplicity* of *x*. Suppose the group \mathbb{C}^{\times} acts on *S*. Two multisets *m*, *m'* on *S* are *almost proportional* if there exists $c \in C^{\times}$ such that for all $x \in S$, $|m(x) - m'(cx)| < \infty$, and m(x) = m'(cx) for all but finitely many $x \in S$. A sequence $(\alpha_i \in S)$ gives rise to a multiset $m: S \to \mathbb{Z}_{\geq 0} \cup \{\aleph_0\}$ by setting $m(x) := |\{i: \alpha_i = x\}|$. Two sequences are *almost proportional* if the multisets arising from them are almost proportional. Consequently, two sequences (α_i) and (β_i) are almost proportional if and only if there exists $c \in \mathbb{C}^{\times}$ and a permutation σ such that $(\alpha_i) \approx (c\beta_{\sigma(i)})$.

Proposition 5.13. Every dual system with standard invariants (0, 1, 1, 1, 1) is equivalent to one of the form $\{L_i = \mathbb{C}(b_ie_1 + e_{i+2}), L^i = \mathbb{C}(a_ie^2 + e^{i+2}): i \in \mathbb{Z}_{>0}\}$. Two such dual systems are conjugate if and only if their three binary invariants agree and the sequence (a_ib_i) is almost proportional to the sequence $(a'_ib'_i)$.

Proof. Fix a dual system with standard invariants (0, 1, 1, 1, 1), and choose a compatible complement datum $(X', Y', \omega', (\lambda'_i), (\mu'_i))$ which satisfies the further condition that the λ'_i vanish on X'_0 and the μ'_i vanish on Y'_0 . Choose nonzero vectors $x_0 \in X'_0$ and $y_0 \in Y'_0$. Since the complement datum is nondegenerate, we can choose vectors $x \in X'$ and $y \in Y'$ such that $\omega'(x, y_0) = \omega'(x_0, y) = 1$. As the complement datum is maximal, we have $\omega'(x_0, y_0) = 0$. After

possibly replacing x with $x + \beta x_0$, we may assume without loss of generality that $\omega'(x, y) = 0$. Let $a_i := \lambda'_i(x)$ and $b_i := \mu'_i(y)$.

Consider the dual system $\{L_i = \mathbb{C}v_i, L^i = \mathbb{C}v^i: i \in \mathbb{Z}_{>0}\}$, where $v_i := b_i e_1 + e_{i+2}$ and $v^i := a_i e^2 + e^{i+2}$. Let $X := \text{Span}\{e_1, e_2\}$ and $Y := \text{Span}\{e^1, e^2\}$. Define a map $\pi : X' \to X$ by $x_0 \mapsto e_1$, $x \mapsto e_2$, and define $\pi : Y' \to Y$ by $y_0 \mapsto e^2$, $y \mapsto e^1$. It is clear that π is an equivalence of dual systems. Thus every equivalence class of dual systems has a representative of the required form.

It remains to show that two such dual systems are equivalent precisely when they have the same binary invariants and the sequences (a_ib_i) and $(a'_ib'_i)$ are almost proportional. Suppose two dual systems, given by sequences (a_i) , (b_i) , (a'_i) , and (b'_i) , are equivalent. There exist a bijection $\sigma : \mathbb{Z}_{>0} \to \mathbb{Z}_{>0}$, isomorphisms $\pi : X \to X$ and $\pi : Y \to Y$, and nonzero constants α_i , such that $(\lambda_i) \approx (\alpha_i \lambda'_{\sigma(i)} \circ \pi)$ and $(\mu_i) \approx (\alpha_i^{-1} \mu'_{\sigma(i)} \circ \pi)$. We adopt the notation $x_0 := e_1, x := e_2, y_0 := e^2$, and $y := e^1$. Suppose $\pi : X \to X$ is given by $x_0 \mapsto ax_0 + bx$, $x \mapsto cx_0 + dx$. Then $(\lambda_i(x_0)) \approx (\alpha_i \lambda'_{\sigma(i)}(ax_0 + bx))$ implies $0 \approx (b\alpha_i a'_i)$, hence b = 0. Since π is an isomorphism, it follows that a and d are nonzero. We also have $(\lambda_i(x)) \approx (\alpha_i \lambda'_{\sigma(i)}(cx_0 + dx))$, thus $(a_i) \approx (\alpha_i da'_{\sigma(i)})$. Similarly, there is a nonzero δ such that $(b_i) \approx (\alpha_i^{-1} \delta b'_{\sigma(i)})$. Therefore the binary invariants agree. Moreover $(a_i b_i) \approx (d\delta a'_{\sigma(i)} b'_{\sigma(i)})$, so the sequences $(a_i b_i)$ and $(a'_i b'_i)$ are almost proportional.

Conversely, suppose that $(a_i b_i) \approx (ca'_{\sigma(i)} b'_{\sigma(i)})$ with *c* nonzero and that the binary invariants agree. Choose nonzero constants α_i such that $(a_i) \approx (\alpha_i ca'_{\sigma(i)})$ and $(b_i) \approx (\alpha_i^{-1} b'_{\sigma(i)})$. This will be possible precisely because the sequences' binary invariants agree. Let γ be the constant $\gamma := c^{-1} \sum (ca'_{\sigma(i)} b'_{\sigma(i)} - a_i b_i)$. Define $\pi : X \to X$ by $x_0 \mapsto x_0$ and $x \mapsto cx$, and define $\pi : Y \to Y$ by $y_0 \mapsto c^{-1}y_0$ and $y \mapsto \gamma y_0 + y$. One calculates that $(\lambda_i) \approx (\alpha_i \lambda'_{\sigma(i)} \circ \pi), (\mu_i) \approx (\alpha_i^{-1} \mu'_{\sigma(i)} \circ \pi),$ and $\tilde{\omega} - \pi^*(\tilde{\omega}') = 0$. \Box

We can visualize the preceding proposition as follows. Cartan subalgebras of \mathfrak{gl}_{∞} with standard invariants (0, 1, 1, 1, 1) are in bijection with certain "admissible" multisets on the parameter space depicted in Fig. 2, modulo almost proportionality. More precisely, the parameter space is $(\mathbb{C} \times \mathbb{C})/\mathbb{C}^{\times}$, where the action of \mathbb{C}^{\times} on $\mathbb{C} \times \mathbb{C}$ is $c \cdot (x, y) = (cx, c^{-1}y)$. A multiset is admissible if infinitely many points lie on each of the two lines. The action of \mathbb{C}^{\times} on the parameter space is $c \cdot [(x, y)] = [(cx, cy)] = [(c^2x, y)]$, and hence elements of \mathbb{C}^{\times} simply rescale the line.

A similar analysis holds more generally. Let *S* be the quotient $((X/X_0)^* \times (Y/Y_0)^*)/\mathbb{C}^\times$, where \mathbb{C}^\times acts on $(X/X_0)^* \times (Y/Y_0)^*$ by $c \cdot (x, y) = (cx, c^{-1}y)$. There is a residual diagonal action of \mathbb{C}^\times on *S*, which enables us to define almost proportional multisets on *S*. If two complement data are equivalent, then the images of (λ_i, μ_i) and (λ'_i, μ'_i) in *S* must be almost proportional. However, the converse does not hold, as different choices of ω often yield inequivalent dual systems. It is difficult to clarify this dependence in general; nonetheless, in practice one should be able to distinguish nonconjugate dual systems. For example, consider complement data with standard invariants (0, 0, 0, 1, 1) and a fixed sequence (λ_i, μ_i) of *S* with no unusual symmetries. It is easy to see that any two choices of ω yield inequivalent dual systems.

Fig. 2. Parameter space for (a_i, b_i) .

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