# DECIDABILITY OF A TEMPORAL LOGIC PROBLEM FOR PETRI NETS 

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#### Abstract

The paper solves an open problem from [4] by showing a decision algorithm for a temporal logic language $L\left(Q^{\prime}, G F\right)$. It implies the decidability oi the problem of the existence of an infinite weakly fair occurrence sequence for a given Petri net; thereby an open problem from [2] is soived.


## 1. Introduction

Real parallel systems should always satisfy some conditions of fairness; it means that the behaviour of a (global) system should be fair with respect to (local) components (processes). Therefore it is desirable to search for an exact expression of fairness in theoretical models and so also in Petri nets. Throughout the paper, we consider the "classical" place/transition Petri nets.

If we try to define a fair behaviour (execution) of a Petri net independently on a modelled problem, the following notions seem to be natural: an infinite uccurrence sequence $\sigma$ is (strongly) fair with respect to a transition $t$ if $t$ occurs infinitely many times or is enabled only finitely many times in $\sigma ; \sigma$ is weakly fair (or $\sigma$ has the finite delay property) with respect to $t$ if $t$ occurs infinitely many times or is disabled infinitely many times in $\sigma$.

Carstensen uses more general notions in [2]; he considers fairness with respect to sets of transitions (where the above-mentioned fairness with respect to single transitions is a special case).

He proves that it is undecidable for a given Petri net and some sets of its transitions whether an infinite occurrence sequence being (strongly) fair with respect to the given sets of transitions exists; the same even holds in case of one given (single) transition (and in case of all (single) transitions as well).

On the other hand, [2] shows that it is decidable for a given Petri net and one set of its transitions whether an infinite occurrence sequence being weakly fair with respect to the given set exists. The idea of the proof cannot be generalized and the general problem (weak fairness with respect to several sets of transitions) is left open in [2]. The problem is also open in the later published paper [4] which provides a nice survey of complexities of similar problems for various definitions of fairness; [4] also defines a simple temporal logic language $L\left(Q^{\prime}, G F\right)$, in which the problem can be expressed.

This paper shows that there is a decision algorithm for formulas of $L\left(Q^{\prime}, G F\right)$, by which Carstensen's open problem is also solved.

Section 2 contains preliminaries, Section 3 shows the structure of the proof in an informal way, and Section 4 reduces our problem to the "key" problem which is to be solved. Sections 5 and 6 contain some auxiliary results-a decidable generalizing of the reachability problem and an application of a result from [3] on occurrence sequences. The main proof (of the decidability of the "key" problem) is given in Section 7.

## 2. Basic definitions and results

We use usual logical and set theoretical symbols $\neg, \&, v, \Rightarrow, \Leftrightarrow, \exists, \downarrow, \epsilon, \subseteq, \cap$, $\cup$; the quantifier $\exists_{x}$ means "there are infinitely many".
$A \backslash B$ denotes the set difference of sets $A, B, A \times B$ their cartesian product. $|A|$ denotes the cardinality of a set $A, f \upharpoonleft A$ the restriction of a function $f$ to a domain $A$.
$\mathbb{N}, \mathbb{N}_{+}, \mathbb{Z}$ denote the sets of nonnegative, positive and all integers, respectively. $\mathbb{Q}_{+}$denotes the set of nonnegative rational numbers.

Sometimes we implicitly regard a function $f \in \mathbb{Z}^{s}(f: S \rightarrow \mathbb{Z}), S$ being a finite set, as a vector from $\mathbb{Z}^{r}$ for $r=|S|$. The bold symbol 0 stands for the null vector ( $0,0, \ldots, 0$ ); the dimension will be clear from the context.
$A^{*}$ denotes the set of finite sequences of elements of $A ; \varepsilon$ denotes the empty sequence. For $u \in A^{*}, k \in \mathbb{N},(u)^{k}$ stands for $u u \ldots u, u$ being written $k$-times, $(u)^{\omega}$ stands for uuu. . . .

The Petri net notation is taken mainly from [1].
A quadruple $\Sigma=\left(S, T, W, M_{0}\right)$ is called a Petri net if $S$ and $T$ are finite disjoint sets of places and transitions, respectively, $W:(S \times T) \cup(T \times S) \rightarrow \mathbb{N}$ is a weight function (for $W(s, t)>0$, there is an arc from $s$ to $t$ with the multiplicity $W(s, t)$; similarly for $W(t, s)>0$ ) and $M_{0}$ is an initial marking, where a marking $M$ of $\Sigma$ is a function $M: S \rightarrow \mathbb{N}$.

A transition $t$ is enabled by $M, M[t\rangle$, if $M(s) \geqslant W(s, t)$ for every $s \in S$. If $t$ is enabled by $M$, it can "occur" yielding a new marking $M^{\prime}, M[t) M^{\prime}$, where $M^{\prime}(s)=$ $M(s)-W(s, t)+W(t, s)$ for every $s \in S$. In a natural way, the definitions can be extended for the case $M[u\rangle, M[u\rangle M^{\prime}$, where $u \in T^{*}$. By $M\left[>M^{\prime}\right.$ we mean that there is some $u \in T^{*}$ such that $M[u\rangle M^{\prime}$.

Remark. Notice the trivial fact that $M \leqslant M^{\prime} \& M[u\rangle$ implies $M^{\prime}[u\rangle$; we often use it implicitly.

The effect of $u \in T^{*}$ (on markings), denoted by $\Delta(u)$, is given by the following: $\Delta: T^{*} \rightarrow \mathbb{Z}^{\text {s }}$, where $\Delta(\varepsilon)=0$,

$$
(\Delta(t))(s)=-W(s, t)+W(t, s), \quad \Delta\left(t u_{i}\right)=\Delta(t)+\Delta(u) .
$$

For a Petri net, a sequence $\sigma=M_{M_{0}} t_{1} M_{1} t_{2 M_{2}} \ldots t_{M_{n}}$ is a (finite) occurrence sequence if $M_{i-1}\left[i_{i}\right\rangle A A_{i}$ for all $i$; similarly for an infinite occurrence sequence $\sigma=$ $M_{0} t_{1} M_{1} t_{2} M_{2} \ldots$. The whole information in $\sigma$ is given by the sequence of transitions; we write $\sigma_{T}=t_{1} t_{2} \ldots$

Describing an occurrence sequence, we often write only some "passed through" markings explicitly (e.g. we write $\sigma=M_{M_{0}} u_{1 M_{1}} u_{2 M_{2}} \ldots$ for $u_{i} \in T^{*}$ ).

We define weak fairness (finite delay property) as in [2].
Definition 2.1. Let a Petri net $\Sigma=\left(S, T, W, M_{0}\right)$ and some sets of transitions $T_{1}, T_{2}, \ldots, T_{k} \subseteq T$ be given. An infinite occurrence sequence $\sigma=M_{M_{0}} t_{1} M_{1} t_{2} M_{2} \ldots$ is weakly fair, or has the finite delay property (has the fdp), with respect to $T_{1}, T_{2}, \ldots, T_{k}$ if $\left(\exists_{x} i\right)\left(t_{i} \in T_{j}\right)$ or $\left(\exists_{x} i\right)\left(M_{i} \nmid \Gamma_{j}\right)$ ) for every $T_{j}(1 \leqslant j \leqslant k)$, where the expression $\left.M_{i} \nmid T_{j}\right\rangle$ means that all $t \in T_{j}$ are disabled (i.e. not enabled; by $M_{i}$.

We are interested in the following problem $\mathbb{P}_{\mathrm{fdp}}$.
Definition 2.2. Problem $\mathbb{P}_{\mathrm{fdp}}$ is specified in the following way:
Instance: A Petri net $\Sigma=\left(S, T, W, M_{0}\right)$ and some sets $T_{1}, T_{2}, \ldots, T_{k} \subseteq T$.
Question: Is there an infinite occurrence sequence $\sigma$ of $\Sigma$ which has the fdp with respect to $T_{1}, T_{2}, \ldots, T_{k}$ ?

We need the well-known resuit on the decidability of the reachability problem $\mathbb{P P}$ :
Definition 2.3. Problem $\mathbb{R P}$ is specified in the following way:
Instance: A Petri net $\Sigma=\left(S, T, W, M_{0}\right)$, a set $S^{\prime} \subseteq S$ and a function (submarking) $M^{\prime}: S^{\prime} \rightarrow \mathbb{N}$.

Question: Is there a marking $M$ such that $M_{0}\left[>M \& M \upharpoonright S^{\prime}=M^{\prime}\right.$ ?
Theorem 2.4. Problem $\mathbb{R P}$ is decidable.

Preof. In [6] or [8].
It is known from [7] that $\mathbb{R P}$ is exp-space-hard, but the known upper bound is not primitive recursive.

We know the following facts from [2].
Theorem 2.5. (1) $\mathbb{P}_{\mathrm{fdp}}$ is exp-space-hard.
(2) In case of one given set ( $k=1$ in Definition 2.2.), $\|_{\mathbb{P}_{\mathrm{fdp}}}$ is decidable.

Proof. In [2]; (1) by the construction from [7], (2) by a reduction to Rip.
The above results are shown more precisely in [4].
Theorem 2.6. (1) $\mathbb{P P P} \leqslant_{\mathrm{PTIME}} \mathbb{P}_{\mathrm{fdp}}\left(\mathbb{P}_{\mathrm{fdp}}\right.$ is at least as hard as $\left.\mathbb{R} \mathbb{P}\right)$.
(2) In case of one given set, $\mathbb{R P} \equiv$ ptime $\mathbb{P}_{\text {rdp }}$.

Proof. In [4].
In [4], a simple temporal language $L\left(Q^{\prime}, G F\right)$ is defined.
Defimition 2.7. Ist a Petri net $\Sigma=\left(S, T, W, M_{0}\right)$ be given. The language $\left.L^{\prime} \mathbf{n}^{\prime}, \mathrm{GF}\right)$ is defined in the following way:
(a) atomic formulas (predicaies) are ge( $s, c$ ), fi(t), where $s \in S, t \in T, c \in \mathbb{N}$, with the following interpretation: for any infinite occurrence seguence $\sigma=\mathrm{m}_{1,}, \mathrm{i}_{1}, \mathrm{~m}_{1} \boldsymbol{I}_{2} \varepsilon_{2} \ldots$ and for any $n \in \mathbb{N}$.

$$
\begin{aligned}
& \langle\Sigma, \sigma, n\rangle=\operatorname{ge}(s, c) \Leftrightarrow M_{d r}(s) \geqslant c, \\
& \langle\Sigma, \sigma, n\rangle \vDash \operatorname{fi}(1) \Leftrightarrow t_{n+1}=1,
\end{aligned}
$$

(b) formulas are either literals, i.e. atomic formulas or their negations (ge( $s, c$ ),
 formulas. GF/ (it is always true that / will hold in future) can be defined as follows:

The rest of the interpretation is natural.
For technical reasons, we will also use literals eq( $s, c$, where

$$
(\Sigma, \sigma, n)=e q(s, c) \Leftrightarrow M_{m}(s)=c
$$

The decidability of the next problem $\mathbb{P}_{\text {aswo }}$ was open in $[4]$.
Definition 28. Problem Premp is specified in the following way:
Instance: A Petri net $\Sigma$, formula ( $\mathcal{L}\left(Q^{\prime}, G F\right)$.
Question: Is there an infinite occurrence sequence of of $\Sigma$ such that $\langle\Sigma, 0,0)=A$ ?
If is easy to verify that the finite delay property can be expressed i y a formula from $L\left(Q^{\prime}, G F\right)$; it means that $P_{\text {sia }}$ is seducible to $P$ acmp. (lit can be done in $P T I M E$;


The main aim of this paper is to prove the decidability of Peemg. In fact, the proof shows an exponential reduction to PP.

A crucial point of the proof is to show the decidability of the following problem $p_{\text {her }}$

Delinition 2.9. Problem $P_{\text {key }}$ is specified in the following way:


$$
\left(S_{i}, f,\right),\left(S_{2}, f_{2}\right), \ldots,\left(S_{n}, \text { for }\right) \text { where } S_{i} \leq S \quad f_{p}: S_{i} \rightarrow \mathbb{N}
$$

Question: Is there a solution of the mey $^{\text {-instance, i.e. an infinite occurrence sequence }}$ $\sigma=M_{M_{1}} t_{1} M_{1} t_{2} M_{2} \ldots$ such that

$$
(\forall j, 1 \leqslant j \leqslant n)(\exists \underset{r}{ } i)\left(M_{i} \mid S_{i}=f_{i}\right) ?
$$

## 3. Informal outline of the proof

Carstensen's proof of (2) in Theorem 2.5 depends on the fact that the existence of $\sigma$ which has the fdp with respect to $T_{1}$ implies the existence of a "periodic" $\sigma$ " ( $\sigma_{?}^{\prime}$ is in the form $\left.u(w)^{\omega}\right)$ which has the fdp with respect to $T_{1}$ as well.

Figure 1 (also given in [2]) shows that this idea cannot be extended. The occurrence sequence

$$
\begin{aligned}
& \cdots\left(0,2^{2}, 11\right)\left(t_{1}\right)^{2^{2}}{ }_{(2,0,0,1}\left(t_{2}\right)^{2^{2}}{ }_{\left(0,2^{2+1}, 11\right.} \ldots
\end{aligned}
$$

has the fdp with respect to $\left\{t_{3}\right\},\left\{t_{4}\right\}$ (also with respect to $\left\{t_{1}\right\},\left\{t_{2}\right\}$ ) but there is not any periodic $\sigma^{*}$ with this property.

Notice that the $P_{\text {sfo }}$ instance $\Sigma,\left\{t_{3}\right\},\left\{t_{d}\right\}$ can be reduced to searching for an infinite occurrence sequence in which $s_{1}, s_{2}$ are empty infinitely many times, i.e. to a $P_{k c y}$-instance.


Fig. 1.

It is not difficult to show that $\mathbb{P}_{\text {temp }}$ (and so $\mathbb{P}_{\text {fdp }}$ also) is reducible to $\mathbb{P}_{\text {key }}$ (see Sedion 4).

We shall outline the proof of the decidability of $\mathbb{P}_{\text {key }}$. First notice that the described $\sigma$ is regular in a certain way: if we denote $M_{1}^{i}=\left(0,2^{i}, 1\right), M_{2}^{i}=\left(2^{i}, 0,1\right)$ then (1) holds for all $i$.

$$
\begin{equation*}
(\forall j, 1 \leqslant j \leqslant 2) \quad\left(\exists k_{j} \in \mathbb{N}_{+}\right) \quad\left(M_{i}^{i+2}-M_{j}^{i+1}=k_{j}\left(M_{j}^{i+1}-M_{j}^{i}\right)\right) \tag{1}
\end{equation*}
$$

It is important that a "regular beginning" (a finite sequence in which (i) hoids for $i=0$; cf. Definition 7.8.) can be lengthened to infinity in a "regular" way.
$\mathbb{P}_{\text {kes }}$-solutions will be characterized as so-called $\omega$-good sequences satisfying a certain condition INSERT; it will be done using the results from Section 6.

Within a (finite) $f(n|S|)$-good INSERT sequence, where $f$ is a certain exponential function of the "size" of the relevant $\mathbb{P}_{\text {key }}$-instance, a series of modifications can be performed so that a regular sequence (i.e. a regular beginning) arises; it is the most technically difficult part of the proot.

Unfortunately, neither the existence of a regular sequence nor the existence of an $f(n|S|)$-good INSERT sequence can be reduced to the reachability problem in a straightforward way.

We shall use the fact that the infinite regular lengthening of a regular sequence yields an $\omega$-good sequence $u$ hich satisfies INSERT in a STRICT way.

The existence of an $f(n|S|) \cdot \operatorname{good}$ STRICT INSERT sequence is reducible to the reachability problem using the results from Section 5.

Figure 2 shows the structure of the proof.


Fig. 2.

## 4. Reduction of $\mathbb{P}_{\text {temp }}$ to $\mathbb{P}_{\text {key }}$

Let us say that a formula $f \in L\left(Q^{\prime}, \mathrm{GF}\right)$ is "simple" if $f$ can be written $f \equiv$ $\&_{j \in J} \mathrm{GF} \not_{j}, J$ being a finite index set and $f_{j}$ being finite conjunctions of literals of the type eq( $s, c)$.

A $\mathbb{P}_{\text {temp }}$-instance $\Sigma$, $f$, where $f$ is simple, can be rewritten into a $\mathbb{P}_{\text {key }}$-insiance in an obvious way.

In what follows we show how to reduce any (general) $\mathbb{P}_{\text {temp }}$-instance to finitely many $\mathbb{P}_{\text {temp }}$-instances with simple formulas only.

Convention 4.1. Further we will implicitly assume that all literals $\neg \mathrm{ge}(s, c)$ are replaced by eq $(s, 0) \vee \operatorname{eq}(s, 1) \vee \cdots \vee \mathrm{eq}(s, c-1)$ and so we will not consider them.

Let us define a natural equivalence on the set of formulas.
Definition 4.2 (of the equivalence $\cong$ ). Let a Petri net $\Sigma$ be given. For any $f_{1}, f_{2} \in$ $L\left(Q^{\prime}, \mathrm{GF}\right), f_{1} \cong f_{2}$ iff $\langle\Sigma, \sigma, 0\rangle \vDash f_{1} \Leftrightarrow\langle\Sigma, \sigma, 0\rangle \vDash f_{2}$ for all $\sigma$.

Lemma 4.3. Any $\mathbb{P}_{\text {temp }}$-instance $\Sigma=\left(S, T, W, M_{0}\right), \notin$ can be reduced to finitely many $\mathbb{P}_{\text {temp }}$-instances where the formulas are in the form $\&_{j \epsilon J} G F f_{j}, f_{j}$ being conjunctions of literals.

Proof. Using the distributive laws for $v, \&$ and obvious cquivalences

$$
\begin{aligned}
& \mathrm{GF}(\mathrm{GF} f) \cong \mathrm{GF} f_{1}, \\
& \mathrm{GF}\left(f_{1} \vee f_{2}\right) \cong \mathrm{GF} f_{1} \vee \mathrm{GF} f_{2}, \\
& \mathrm{GF}\left(\mathrm{GF} f_{1} \& f_{2}\right) \cong \mathrm{GF} f_{1} \& G F f_{2},
\end{aligned}
$$

it is clear that $f$ can be written as a finite disjunction of formulas of the type $f^{\prime} \equiv \boldsymbol{\&}_{j \in J} g_{j}$ where $g_{j}$ are either literals or in the form $\mathrm{GFg}, g$ being a conjunction of literals.

Answering all instances $\Sigma, f^{\prime}$, where $f^{\prime}$ is a member of the disjunction, we obtain the answer for $\Sigma, f$ easily.

Hence it suffices to get rid of literals in the conjunction $\ell^{\prime} \equiv \boldsymbol{\&}_{j \in J} \mathscr{g}_{j}$.
(i) If none of $g_{j}$ is a literal, we are done.
(ii) In the following four points we show how $\Sigma^{\prime}, f^{\prime \prime}$ can be constructed so that the answer for $\Sigma^{\prime}, f$ " is the same as for $\Sigma, f^{\prime}$ and $f^{\prime \prime}$ is "more simple" than $f^{\prime}$.

It will be clear that Case (i) will be achieved by finitely many steps.

$$
\begin{equation*}
f^{\prime} \equiv \operatorname{ge}(s, c) \& \&_{j \in J^{\prime}} \boldsymbol{g}_{j} \tag{1}
\end{equation*}
$$

If $M_{0}(s)<c$ then the answer for $\Sigma, \ell^{\prime}$ is NO, if $M_{0}(s) \geqslant c$ then put $\Sigma^{\prime}=\Sigma$ and $f^{\prime \prime} \equiv \boldsymbol{\&}_{j \in J^{\prime}} g_{j}$.
(2) $f^{\prime} \equiv \mathrm{eq}(s, c) \& \&_{j \in J^{\prime}} g_{j}$.

It is similar to (1).

$$
\begin{equation*}
f^{\prime} \equiv \mathrm{f}\left(t^{\prime}\right) \& \&_{j \in J} g_{j} \tag{3}
\end{equation*}
$$

To obtain $\Sigma^{\prime}$, do the following changes in $\Sigma$ (cf. Fig. 3):

- add new places $s_{1}, s_{2}$ and put $W\left(s_{1}, t^{\prime}\right)=W\left(t^{\prime}, s_{1}\right)=1, W\left(s_{2}, t\right)=W\left(t, s_{2}\right)=1$ for all $t \in T \backslash\left\{t^{\prime}\right\}\left(s_{1}\right.$ is a "run-place" for $t^{\prime}, s_{2}$ for $T \backslash\left\{t^{\prime}\right\}$ ) and still $W\left(t^{\prime}, s_{2}\right)=1$ (the other values of $\boldsymbol{W}$ are 0 ).
- put $M_{0}\left(s_{1}\right)=1, M_{0}\left(s_{2}\right)=0$. Finally put $\ell^{\prime \prime} \equiv \boldsymbol{\&}_{j c \cdot} g_{j}$.

$$
\begin{equation*}
f^{\prime} \equiv \operatorname{fi}^{\prime}\left(i^{\prime}\right) \& \&_{j \in J} g_{j} . \tag{4}
\end{equation*}
$$

We can proceed as in (3) $\left(W\left(t, s_{1}\right)=1\right.$ for all $t \in T \backslash\left\{t^{\prime}\right\}, M_{0}\left(s_{1}\right)=0$ and $M_{0}\left(s_{2}\right)=1$ in this case).


Fig. 3.


Fig. 4.

Lemma 4.4. Any $\mathbb{P}_{\text {temp }}$-instance $\Sigma=\left(S, T, W, M_{0}\right), f_{,}$where $f \equiv \boldsymbol{\&}_{j \in J} G F f_{j}, f_{j}$ being conjunctions of literals, can be reduced to another $\mathbb{P}_{\text {temp-instance }} \Sigma^{\prime}$, $f^{\prime}$, where $f^{\prime} \equiv$ $\&_{j \in J} G F f_{j}^{\prime}, f_{j}^{\prime}$ being conjunctions of literals of the type eq $(s, c)$.

Proof. Again, it suffices to show how $\Sigma^{\prime}, f^{\prime}$ with "more simple" $f^{\prime}$ can be constructed.
(1) $\mathrm{fi}\left(t^{\prime}\right)$ or $\neg \mathrm{fi}\left(t^{\prime}\right)$ occurs in $f$. (We will slightly modify the construction from (3) in the proof of Lemma 4.3.)
To obtain $\Sigma^{\prime}$, do the following changes in $\Sigma$ (cf. Fig. 4):

- add places $s_{0}, s_{1}, s_{2}$ and put $W\left(s_{1}, t^{\prime}\right)=1, W\left(s_{2}, t\right)=1$ for all $t \in T \backslash\left\{t^{\prime}\right\}$ and $W\left(t, s_{0}\right)=1$ for all $t \in T$.
- add transitions $t_{1}, t_{2}$ and put $W\left(s_{0}, t_{1}\right)=W\left(s_{0}, t_{2}\right)=1, W\left(t_{1}, s_{1}\right)=1, W\left(t_{2}, s_{2}\right)=1$ (the other values of $W$ are 0 ).
- put $M_{0}\left(s_{0}\right)=1, M_{0}\left(s_{1}\right)=M_{0}\left(s_{2}\right)=0$. (First $t_{1}$ or $t_{2}$ occurs by which it is decided whether $t$ ' or some $t \in T \backslash\left\{t\right.$ '\} can occur next. Any $t \in T$ puts "a token" to $s_{0}$, then again $t_{1}$ or $t_{2}$ occurs, etc.)

To obtain $f^{\prime}$, replace the occurrences of $f\left(t^{\prime}\right)$ by eq $\left(s_{1}, 1\right)$ and the occurrences of $\neg \mathrm{fi}\left(t^{\prime}\right)$ by eq $\left(s_{2}, 1\right)$ in $f$.
In (2), we can suppose only literals ge $(s, c)$, eq $(s, c)$ occurring in $\not \subset$.
(2) $\operatorname{ge}(s, c)$ occurs in $f$. To obtain $\Sigma^{\prime}$, do the following changes in $\Sigma$. Add places $s_{1}, s_{2}, s_{3}, M_{0}\left(s_{1}\right)=1, M_{0}\left(s_{2}\right)=M_{0}\left(s_{3}\right)=0$, and transitions $t_{1}, t_{2}, t_{3}$ as in Fig. 5 ( $W\left(s_{3}, t\right)=W\left(t, s_{1}\right)=1$ for all $\left.t \in T\right)$. To obtain $f^{\prime}$, replace the occurtences of ge $(s, c)$ by eq $(s, c)$ in $f$.


Fig. 5.

Proposition 4.5. If $\mathbb{P}_{\mathrm{key}}$ is decidable then $\mathbb{D}_{\mathrm{tunp}}$ is decidable.
Proof. It follows from Lemmas 4.3. and 4.4. and from the considerations at the beginning of this section.

## 5. A decidable extension of the reachability problem

Look at the proposition of Lemma 5.2. If $f^{\prime}(M)$ is a finite conjunction of conditions $M(s)=s, s \in S, c \in \mathbb{N}$, then the problem under discussion is, in fact, $\mathbb{R P}$ and the proposition follows from Theorem 2.4. But we need formulas from $L_{\Sigma}$, which are more generai.

Definition 5.1. Let a Petri net $\Sigma=\left(S, T, W, M_{0}\right)$ be given. The ianguage $L_{\Sigma}$ is the set of the formulas which are defined as follows:
(1) there is one variable $\mathscr{M}$ for elements of $\mathbb{N}^{s}$;
(2) a term is either atomic, $\mathcal{M}(s)$ or $c$, where $s \in S, c \in \mathbb{N}$, or of the form $t_{1}+t_{2}$, where $t_{1}, t_{2}$ are terms;
(3) a formula is either atomic, $t_{1}<t_{2}$ or $t_{1} \leqslant t_{2}$, where $t_{1}, t_{2}$ are terms, or of the form $f_{1} \& f_{2}$, where $f_{1}, f_{2}$ are formulas.

The semantics is natural.

We also use $t_{1}=t_{2}$ by which $t_{1} \leqslant t_{2} \& t_{2} \leqslant t_{1}$ is abbreviated. For a concrete marking $M, f(M)$ denotes the instance of $f$ in which $M$ is substituted for $\mathbb{M}$.

Lemma 5.2. There is an algorithm with the following specification:
Input: A Petri net $\Sigma=\left(S, T, W, M_{0}\right)$ and a formula $f \in I_{\Sigma}$.
Output: YES if there is a marking $M$ such that $M_{0}[>M$ and $f(M)$ is true, NO otherwise.

Proof. (i) The case with $f$ as described before Definition $5.1, f$ is "simpie", is obvious.
(ii) In the general case, we shall show how $\Sigma^{\prime}$ and $f^{\prime} \in L_{\Sigma^{\prime}}$ can be constructed so that the output for $\Sigma$ ', $f$ ' is the same as for $\Sigma, f$ and $f$ ' is "more simp!.e" than $f$.

The way of constructing $\Sigma^{\prime}, f^{\prime}$ is shown in the following five points; it will be clear that Case (i) will be achieved by finiteiy many steps.
(1) Some $c \in \mathbb{N}$ occurs in $f$ : add a new isolated place $s_{N}$ with $M_{0}\left(s_{N}\right)=c$ and replace an occurrence of $c$ by $\mathscr{M}\left(s_{N}\right)$ in $f$.
(2) Some $s \in S$ occurs in $f$ several times: add a new place $\hat{s}$ to $\Sigma$ and put $M_{0}(\hat{s})=M_{0}(s)$ and $W(\hat{s}, t)=W(s, t), W(t, \hat{s})=W(t, s)$ for every $t \in T(\hat{s}$ is a duplicate of $s)$; in $f$, replace an occurrence of $\mathcal{M}(s)$ by $\mathcal{M}(\hat{s})$.

Thus we can suppose in the following points that no $c \in \mathbb{N}$ occurs in $f$ and that every $s \in S$ occurs in $f$ at most once.
(3) A term $t \equiv \mathscr{M}\left(s_{1}\right)+\mathscr{M}\left(s_{2}\right)$ occurs in $f: \check{z}^{\prime \prime}$ is shown in Fig. 6; in $f$, replace the occurrence of $t$ by $\mathscr{M}\left(s_{N}\right)$ and add the conjunction $\mathcal{M}\left(s_{1}\right)=0 \& \mathscr{M}\left(s_{2}\right)=0$.
(4) a formula $g \equiv \mathcal{M}\left(s_{1}\right)<\mathcal{M}\left(s_{2}\right)$, or $g^{\prime} \equiv \mathcal{M}\left(s_{1}\right) \leqslant \mathcal{M}\left(s_{2}\right)$, occurs in $f: \Sigma^{\prime}$ is shown in Fig. 7 ; in $f$, replace $g$ by $\mathcal{M}\left(s_{1}\right)=0 \& \mathcal{M}\left(s_{2}\right)=1$ or $g^{\prime}$ by $\mathcal{M}\left(s_{1}\right)=$ $0 \& \mathscr{M}\left(s_{2}\right)=0$.


Fig. 6.


Fig. 7.

We shall still generalize the result by putting some conditions on "passed through" markings.

Definition 5.3. Let a Petri nct $\Sigma=\left(S, T, W, M_{0}\right)$ be given. For $k \in \mathbb{N}_{+}$, the language $L_{\Sigma}^{k}$ is defined in the same way as $L_{\Sigma}$, but it contains $k$ variables $\mathcal{M}_{1}, \mathcal{M}_{2}, \ldots, \mathcal{M}_{k}$ ( $\mathcal{M}_{i}(s)$ is a term for $\left.i=1,2, \ldots, k\right)$.

Theorem 5.4. There is an algorithm specified as follows:
Input: a Petri net $\Sigma=\left(S, T, W, M_{0}\right)$ and a formula $f \in L_{\Sigma}^{k}$ (for any $k \in \mathbb{N}_{+}$).
Output: YES if there are markings $M_{1}, M_{2}, \ldots, M_{k}$ such that $M_{0}\left[>M_{1}\left[>M_{2} \ldots\left[>M_{k}\right.\right.\right.$ and $f\left(M_{1}, M_{2}, \ldots, M_{k}\right)$ is true, $N O$ ctherwise.

Proof. The case $f \in L_{\Sigma}^{1}$ is clear from Lemma 5.2.
The case $\Sigma, f \in L_{\Sigma}^{k+1}$ will be reduced to the case $\Sigma^{\prime}, f^{\prime} \in L_{\Sigma^{\prime}}^{k}$ with the same output in the following way:

- Add a duplicate $\hat{s}$ for every $s \in S$ (as in (2) in the proof of Lemma 5.2.) and denote $\bar{S}=\{\hat{s} \mid s \in S\}$.
- For every $t \in T$, add a new transition $\bar{t}$ and put $W(s, \bar{t})=W(\bar{t}, s)=0, W(\hat{s}, \bar{t})=$ $W(s, t), W(\bar{t}, \hat{s})=W(t, s)$ for every $s \in S$. Denote $\bar{T}=\{\bar{t} \mid t \in T\}$. (The transitions from (original) $T$ work both on original and on duplicate places, the transitions from $\bar{T}$ work on duplicate places only.)
- Now add a place $s_{\mathrm{R}}$ putting $M_{0}\left(s_{\mathrm{R}}\right)=1, W\left(s_{\mathrm{R}}, t\right)=W\left(t, s_{\mathrm{R}}\right)=\alpha$, where $\alpha$ is 1 for $t \in T$ and 0 for $t \in \bar{T}$, and a place $s_{\mathrm{R}}^{\prime}$ putting $M_{0}\left(s_{\mathrm{R}}^{\prime}\right)=0, W\left(s_{\mathrm{R}}^{\prime}, t\right)=W\left(t, s_{\mathrm{R}}^{\prime}\right)=\beta$, where $\beta$ is 0 for $t \in T$ and 1 for $t \in \bar{T}$. ( $s_{R}$ is a "run-place" for $T, s_{R}^{\prime}$ a "run-place" for $\bar{T}$ ).
- Finally add $t_{\mathrm{R}}$ as shown in Fig. 8; thereby the construction of $\Sigma^{\prime}$ is completed. To obtain $f^{\prime} \in L_{\Sigma^{\prime}}^{k}$, do the following changes in $\notin$ :
- add the conjunction

$$
\mathcal{M}_{1}\left(s_{R}\right)=1 \& \mathscr{M}_{2}\left(s_{R}\right)=1 \& \cdots \& \mathscr{M}_{k-1}\left(s_{R}\right)=1 \& \mathcal{M}_{k}\left(s_{R}\right)=0
$$

- replace every occurrence of $\mathcal{M}_{k+1}(s)$ by $\mathscr{M}_{k}(\hat{s})$.


Fig. 8.

## 6. A special ordering of occurrence sequences

Recall the following well-known proposition.

Proposition 6.1. Every infinite sequence of elements of $\mathbb{N}^{r}\left(r \in \mathbb{N}_{+}\right)$has an infinite ascending subsequence ( $\leqslant$ being considered componentwise).

Proof. By induction on $r$.

We shall use a nontrivial generalization for quasi-crdered sets (in such a set, $a \leqslant a$ and $a \leqslant b \& b \leqslant c \Rightarrow a \leqslant c$ hold for all $a, b, c$ ).

Definition 6.2. A quasi-ordered set $(A, \leqslant)$ has the finite basis property, the $f b p$, if every infinite sequence of elements of $A$ has an infinite ascending subsequence.

For a quasi-ordered set $(A, \leqslant)$, let $A^{*}$ be quasi-ordered in the following way: for $u, v \in A^{*}, \quad u=a_{1} a_{2} \ldots a_{m}\left(a_{i} \in A\right), u \leqslant v$ holds iff $v$ can be written $v=$ $v_{1} b_{1} v_{2} b_{2} v_{3} \ldots b_{m} v_{m+1}$ so that $b_{i} \in A$ and $a_{i} \leqslant b_{i}$ for $i=1,2, \ldots, m$.

Proposition 6.3. If $(A, \leqslant)$ has the fbp then $\left(A^{*}, \leqslant\right)$ also has the fhp.
Proof. In [3] as a corollary of a more general theorem.
For a Petri net, we shall show a quasi-order with the fbp on the set of couples ( $M, u$ ), where $M$ enables $u$.

Definition 6.4. Let a Petri net be given. Let us define the following relation $\leqslant$ : for any markings $M_{1}, M_{2}$ and any finite sequences of transitions $u_{1}, u_{2}$ such that $M_{1}\left[u_{1}\right\rangle$, $M_{2}\left[u_{2}\right\rangle,\left(M_{1}, u_{1}\right) \leqslant\left(M_{2}, u_{2}\right)$ iff, for $u_{1}=t_{1} t_{2} \ldots t_{m}$ ( $t_{i}$ being transitions), $u_{2}$ can be written $: t_{2}=w_{1} t_{1} w_{2} t_{2} w_{3} \ldots t_{m} w_{m+1}$, where $M_{2}-M_{1}+\Delta\left(w_{1} w_{2} \ldots w_{c}\right) \geqslant 0$ for $c=$ $0,1,2, \ldots, m+1$.

Thus $\left(M_{1}, u_{1}\right) \leqslant\left(M_{2}, u_{2}\right)$ means that $M_{1} \leqslant M_{2}, M_{1}+\Delta\left(u_{1}\right) \leqslant M_{2}+\Delta\left(u_{2}\right)$ and $M_{1}+$ $\Delta\left(t_{1} t_{2} \ldots t_{c}\right) \leqslant M_{2}+\Delta\left(w_{1} t_{1} w_{2} t_{2} \ldots w_{c} t_{c}\right)$ for $c=1,2, \ldots, m$. It is easy to verify that $\leqslant$ is a quasi-order.

The next theorem gives the main result of this section.
Theorem 6.5. For any Peiri net $\Sigma=\left(S, T, W, M_{0}\right)$, the set $\mathbb{M}=\{(M, u) \mid M[u\rangle\}$ has the $f b p$ in $\leqslant$.

Proof. First notice that $\left(\mathbb{N}^{r}\right)^{*}, r \in \mathbb{N}_{+}$, has the fbp (cf. Propositions 6.1 and 6.3).
We can define a one-to-one map EMS of $\mathbb{M}$ into $\left(\mathbb{N}^{r}\right)^{*}$, where $r=|S|+|T|+2$, in the following way:

- take the marking sequence corresponding to ( $M, u$ );
- extend each element of this sequence by $|T|$ components; the component corresponding to the transition just occurred will be equal to 1 , the others will be equal to 0;
- add a special end-element which contains the last marking but all "the transition components" are equal to 0 ;
- extend each element by another iwo components, one indicating the begin-element and the other indicating the end-element.
An example makes it clear:
$\operatorname{EMS}\left[\left(M, t_{1} t_{2}\right)\right]$
$\quad=[M, 0, \ldots, 0,1,0]\left[M+\Delta\left(t_{1}\right), 0, \ldots, 0,1,0, \ldots, 0,0,0\right]$
$\uparrow$
Begin


The following equivalence is easy to verify:

$$
\left(M_{1}, u_{1}\right) \leqslant\left(M_{2}, u_{2}\right) \text { iff } \operatorname{EMS}\left[\left(M_{1}, u_{1}\right)\right] \leqslant \operatorname{EMS}\left[\left(M_{2}, u_{2}\right)\right]
$$

Hence the theorcm is obvious.
Later we shall use Lemma 6.7 for which Lemma 6.6 is needed.
Lemma 6.6. Suppose $(M, u) \leqslant\left(M^{\prime}, u^{\prime}\right)$ for a given Petri net. For any "partition" $u=u_{1} u_{2} \ldots u_{m}$ of $u, u^{\prime}$ can be written $u^{\prime}=v_{1} v_{2} \ldots v_{m}$ where $M+\Delta\left(u_{1} u_{2} \ldots u_{c}\right) \leqslant$ $M^{\prime}+\Delta\left(v_{1} v_{2} \ldots v_{c}\right)$ for $c=0,1,2, \ldots, m$.

Proof. It follows from the definition of $\leqslant$ in an obvious way.
Lemma 6.7. Let a Petri net $\Sigma=\left(S, T, W, M_{0}\right)$ be given. Suppose $\left(M_{1}, u_{1}\right) \leqslant\left(M_{2}, u_{2}\right) \leqslant$ $\left(M_{3}, u_{3}\right)$ and $M_{i}\left[u_{i}\right\rangle M_{i}^{\prime}$ for $i=1,2,3$. Then there is $v \in T^{*}$ such that $M_{3}+\left(M_{2}-M_{1}\right)$ $[v\rangle M_{3}^{\prime}+\left(M_{2}^{\prime}-M_{1}^{\prime}\right)$ and $\left(M_{3}, u_{3}\right) \leqslant\left(M_{3}+\left(M_{2}-M_{1}\right), v\right)$.

Proof. Suppose $u_{1}=t_{1} t_{2} \ldots t_{m}, u_{2}=w_{1} t_{1} w_{2} t_{2} w_{3} \ldots t_{m} w_{m+1}$ where $M_{2}-M_{1}+$ $د\left(w_{1} w_{2} \ldots w_{c}\right) \geqslant 0$ for $c=0,1, \ldots, m+1$. Due to the previous lemma, we can write $u_{3}=v_{1} v_{2} \ldots v_{m+1}$ where $M_{2}+\Delta\left(w_{1} t_{1} w_{2} t_{2} \ldots w_{c} t_{c}\right) \leqslant M_{3}+\Delta\left(v_{1} v_{2} \ldots v_{c}\right)$ for $c=$ $0,1, \ldots, m$. It can be easily verified that $v=w_{1} v_{1} w_{2} v_{2} \ldots w_{m+1} v_{m+1}$ proves the lemma.

## 7. Decidability of $\mathbb{P}_{\text {key }}$

We use the following technical convention in this section.
Convention 7.1. We will assume implicitly that every Petri net $\Sigma=\left(S, T, W, M_{0}\right)$ has a special step counter place, denoted by $s_{\mathrm{cnt}}$, where $M_{0}\left(s_{\mathrm{cnt}}\right)=0$ and $W\left(s_{\mathrm{cnt}}, t\right)=0$, $W\left(t, s_{\mathrm{cnt}}\right)=1$ for every $t \in T$.

We can immediately establish a result corresponding to Carstensen's resuit 2.5. (2).
Proposition 7.2. $\mathbb{P}_{\text {key }}$ is decidable in case $n=1$ (there is one $\left(S_{1}, f_{1}\right)$ only).
Proof. In such a case, a solution $\sigma$ exists iff there is a finite sequence $\sigma^{\prime}={ }_{M_{0}} u_{1 M_{1}} u_{2 M_{2}}$ such that

$$
\left[M_{1}\left|S_{1}=f_{1} \& M_{2}\right| S_{1}=f_{1}\right] \&\left[M_{1} \leqslant M_{2} \& M_{1}\left(s_{\mathrm{cnt}}\right)<M_{2}\left(s_{\mathrm{cnt}}\right)\right]
$$

( $\sigma$ implies $\sigma^{\prime}$ due to Proposition 6.1, $\sigma^{\prime}$ implies a solution $\sigma_{T}=u_{1}\left(u_{2}\right)^{\omega}$.)
The existence of such $\sigma^{\prime}$ is decidable due to Theorem 5.4.
In what follows we implicitly assume $n \geqslant 2$ in $\mathbb{P}_{\text {key }}$-instances. Now we show a more detailed structure of $\mathbb{P}_{\text {key }}$-solutions.

Definition 7.3. Let $\Sigma=\left(S, T, W, M_{0}\right),\left(S_{1}, f_{1}\right), \ldots,\left(S_{n}, f_{n}\right)$ be a $\mathbb{P}_{\text {key }}$-instance. A (finite) occurrence sequence $\sigma$ in the form

$$
\sigma=M_{0} u_{0} M_{0}^{1} U_{M_{n}^{1}}^{1} w^{1} M_{0}^{2} U_{M_{n}^{2}}^{2} w^{2} M_{0}^{3} \cdots M_{0}^{\text {i }} U_{M_{n}^{k}}^{k} w_{M_{0}^{k+1}}
$$

where every subsequence $\boldsymbol{m}_{0}^{\prime} \boldsymbol{u}_{M_{n}^{\prime}}$ can be written in more detail $M_{0}^{i} u_{1 M_{i}}^{i} u_{2 M_{2}^{\prime}}^{i} \ldots u_{n M_{n}^{\prime}}^{i}$, is $\boldsymbol{k}$-good if the following conditions hold for all (relevant) $i, j$ :
(1) $M_{j}^{i} \backslash S_{j}=\tilde{f}_{j}$ (i.e. $\left.M_{j}^{1}\right\rceil S_{j}=M_{j}^{2} \backslash S_{j}=\cdots=M_{j}^{k} \backslash S_{j}=f_{j}$ for $1 \leqslant j \leqslant n$ ) and $M_{0}^{i} \backslash S_{n}=$ $f_{n}$;
(2) $\Delta\left(u^{i}\right) \geqslant 0, \Delta\left(w^{i}\right) \geqslant 0$ (i.e. $M_{0}^{1} \leqslant M_{n}^{1} \leqslant M_{0}^{i} \leqslant M_{n}^{2} \leqslant \cdots \leqslant M_{0}^{k} \leqslant M_{n}^{k} \leqslant M_{0}^{k+1}$ );
(3) $M_{j}^{i-1} \leqslant M_{j}^{i}$ (i.e. $M_{j}^{1} \leqslant M_{j}^{2} \leqslant M_{j}^{3} \leqslant \cdots \leqslant M_{j}^{k}$ also for $1 \leqslant j \leqslant n-1$ ) and $M_{j}^{i-1}\left(s_{\mathrm{cnt}}\right)<M_{j}^{i}\left(s_{\mathrm{cnt}}\right)$ (the "sector from $M_{i}^{i-1}$ to $M_{j}^{i "}$ is not empty).

We will say that a $k$-good sequence $\sigma$ satisfies INSERT, $\sigma$ is a $k$-good INSERT sequence, if in addition $\left(M_{j-1}^{i}, u_{j}^{i}\right) \nsucceq\left(M_{j-1}^{i+1}, u_{j}^{i / 1}\right)$ for $i=1,2, \ldots, k-1, j=1,2, \ldots, n$.

In a natural way, the definition can be extended for the case $k=\omega$ yielding the notions of an $\omega$-good sequence and an $\omega$-good INSERT sequence.

Notation 7.4. For technical convenience, we write $\operatorname{sect}(i, j)$ for $u^{i}+u_{i+2}^{i-1} \ldots$ $u_{i=}^{i-1} w^{i-1} u_{i}^{i} u_{2}^{i} \ldots u_{j}^{i}$ (i.e. for "sector from $M_{j}^{i-1}$ to $M_{j}^{i ")}$ ). Condition (3) in Definition 7.3. means that $\Delta[\sec i(i, j)] \geqslant 0$ and $\Delta[\operatorname{sect}(i, j)]\left(s_{\mathrm{cnt}}\right)>0$.

Remark 7.5. We will often suppose $w^{i}=\varepsilon$ for all $i\left(M_{n}^{i}=M_{0}^{i+1}\right.$ in such a case). Considering a $k$-good ( $\omega$-good) sequence, we can always sbain the case $w^{i}=\varepsilon$ by the notation change $\left(u_{1}^{i+1}\right)_{\text {NEW }}=\left(w^{i} u_{1}^{i+1}\right)_{\text {OLD }}$; of course, the condition INSERT may be affected thereby. Doing a netation change $\left(w^{i}\right)_{\text {NEW }}=\left(w^{i} u^{i+1} w^{i+1}\right)_{\text {oLD }}$ for some $i$, we obtain a $(k-1)$-good sequence (another form of an $\omega$-good sequence, respectively).

Lemma 7.6. Any $\omega$-good sequence can be rewritten into a form of an $\omega$-good INSERT sequence.

Proof. Because of Theorem 6.5, any infinite sequence of elements of the set $\{(M, u) \mid M[u\rangle\}$ has an infinite subsequence ascending in $\swarrow$. The lemma can be proved by applying this fact $n$-times (and using the last notation change in the previous remark).

Proposition 7.7. Let a $\mathbb{P}_{\text {key }}$-instance $\Sigma=\left(S, T, W, M_{0}\right),\left(S_{1}, f_{1}\right), \ldots,\left(S_{n}, f_{n}\right)$ be given. The solutions of the $\mathbb{P}_{\text {key }}$-instance are exactly the $\omega$-good INSERT sequences.

Proof. It is obvious that an $\omega$-good sequence is a solution.
(*) Now let $\sigma=M_{0} t_{1} M_{1} t_{2} M_{2} \ldots$ be a solution of the $\mathbb{P}_{k e y}$-instance. Due to the previous lemma it suffices to show that $\sigma$ can be written in a form of an $\omega$-good sequence.

Take any $j, 1 \leqslant j \leqslant n$. From Proposition 6.1. it is clear that there is an infinite subsequence $\varphi_{j}$ of the sequence $M_{0}, M_{1}, M_{2}, \ldots$, where $M \upharpoonright S_{j}=f_{j}$ for every member $M$ of $\varphi_{j}$ and $\varphi_{j}$ is ascending (in the component $s_{\mathrm{cnt}}$ strictly ascending).

It is easy to establish ( $*$ ) using sequences $\varphi_{1}, \varphi_{2}, \ldots, \varphi_{n}$.
A special 3-good sequence will be called regular.
Definition 7.8. Let a $\mathbb{P}_{\text {key }}$-instance $\Sigma=\left(S, T, W, M_{0}\right),\left(S_{1}, f_{1}\right), \ldots,\left(S_{n}, f_{n}\right)$ be given. A 3-good sequence $\sigma$ in the form

$$
\sigma=M_{M_{0}} u_{0 M_{1}^{1}} u_{1 M_{1}^{1}}^{1} \ldots u_{n M_{n}^{1}}^{1} u_{1 M_{1}^{2}}^{2} \ldots u_{n M_{n}^{2}}^{2} u_{1}^{3} M_{i}^{1} \ldots u_{n M_{n}^{2}}^{3}
$$

( $w^{i}=\varepsilon$ for $i=1,2,3$ ) will be called a regular sequence if

$$
(\forall j, 1 \leqslant j \leqslant n)\left(\exists k_{j} \in \mathbb{N}_{+}\right) \quad\left[M_{j}^{3}-M_{i}^{2}=k_{i}\left(M_{j}^{2}-M_{j}^{\prime}\right)\right] .
$$

Our next aim will be to prove that the existence of a $k$-good INSERT sequence, for sufficiently large $k$, implies the existence of a regular sequence. It is the most tecinnical part of the whole proof.

First we define technical notions $R_{j}^{i}$ and $\operatorname{MUL}(i, j)$.
Definition 7.9. Consider a $\boldsymbol{k}$-good sequence $\sigma$ as in Definition 7.3 (we can suppose $\boldsymbol{w}^{i}=\varepsilon$ for all $i$ ).
(1) The functions (vectors) $R_{j}^{i} \in\left(\mathbb{Q}_{+}\right)^{S}(2 \leqslant i \leqslant k, 1 \leqslant j \leqslant n)$ will be defined in the following way: for any $s \in S$,

$$
R_{j}^{i}(s)=\frac{\left[M_{j}^{i}-M_{j}^{i-1}\right](s)}{\left[M_{j}^{i}-M_{j}^{i-1}\right]\left(s_{\mathrm{cnt}}\right)}=\frac{[\Delta(\operatorname{sect}(i, j))](s)}{[\Delta(\operatorname{sect}(i, j))]\left(s_{\mathrm{cnt}}\right)} .
$$

(2) The predicate $\operatorname{MUL}(i, j)(3 \leqslant i \leqslant k, 1 \leqslant j \leqslant n)$ will be defined in the following way:

$$
\operatorname{MUL}(i, j) \underset{\mathrm{df}}{\Leftrightarrow}\left(\exists p \in \mathbb{N}_{+}\right)\left\{\left(M_{j}^{i}-M_{j}^{i-1}\right)\left(s_{\mathrm{cnt}}\right)=p\left[\left(M_{j}^{i-1}-M_{j}^{i-2}\right)\left(s_{\mathrm{cnt}}\right)\right]\right\}
$$

Remark 7.10. Notice that a 3 -good sequence with $w^{i}=\varepsilon$ is regular iff MUL( $3, j$ ) and $R_{j}^{2}=R_{j}^{3}$ for $j=1,2, \ldots, n$.

We will use certain special $\boldsymbol{k}$-good sequences (called "relatives"); for them, we will show certain modifications which keep the special $k$-goodness conditions and change $R_{j}^{i}$ (and are able to establish $\operatorname{MUL}(i, j)$ ). We need the next two lemmas.

Notation 7.11. Let $\boldsymbol{\sigma}$ be a $\boldsymbol{k}$-good sequence as in Definition 7.3. For any (relevant) $i, j$ and any $r_{1}, r_{2}, \ldots, r_{i-1} \in \mathbb{N}, M_{j}^{i}\left(r_{1}, r_{2}, \ldots, r_{i-1}\right)$ stands for $M_{j}^{i}+r_{1}\left(M_{j}^{2}-M_{j}^{1}\right)+$ $r_{2}\left(M_{j}^{3}-M_{j}^{2}\right)+\cdots+r_{i-1}\left(M_{j}^{i}-M_{j}^{i-1}\right)$.

Lemma 7.12. Let $\sigma$ be a $k$-good INSERT sequence as in Definition 7.3. For any $i, j$, $1 \leqslant i \leqslant k, \quad 0 \leqslant j \leqslant n-1$ and any $r_{1}, r_{2}, \ldots, r_{i-1} \in \mathbb{N}$, there is $u \in T^{*}$ such that $M_{j}^{i}\left(r_{1}, r_{2}, \ldots, r_{i-1}\right)[u\rangle M_{j+1}^{i}\left(r_{1}, r_{2}, \ldots, r_{i-1}\right)$.

Proof. We show in addition that $u$ can be chosen so that $\left(M_{j}^{i}, u_{j+1}^{i}\right) \leqslant$ ( $M_{j}^{i}\left(r_{1}, r_{2}, \ldots, r_{i-1}\right), u$ ). The proof is made by induction on the sum $c=\sum_{p=1}^{i-1} r_{r}$ (assuming fixed $i, j$ ).
(i) In case of $c=0$, put $u=u_{j+1}^{i}$.
(ii) In the induction step, denote

$$
M=M_{j}^{i}\left(r_{1}, r_{2}, \ldots, r_{i-1}\right), \quad M^{\prime}=M_{j+1}^{i}\left(r_{1}, r_{2}, \ldots, r_{i-1}\right)
$$

and suppose

$$
\begin{equation*}
M[u\rangle M^{\prime},\left(M_{j}^{i}, u_{j+1}^{i}\right) \leqslant(M, u) \tag{2}
\end{equation*}
$$

The proposition will be shown for

$$
M_{j}^{i}\left(r_{1}, \ldots, r_{d-1}, 1+r_{d}, r_{d+1}, \ldots, r_{i-1}\right)=M+\left(M_{j}^{d+1}-M_{j}^{d}\right),
$$

where $1 \leqslant d \leqslant i-1$.

We have $\left(M_{j}^{d}, u_{j+1}^{d}\right) \leqslant\left(M_{j}^{d+1}, u_{j+1}^{d+1}\right) \leqslant(M, u)$ due to : NSERT and (2). Because of Lemma 6.7, there is $v \in T^{*}$ such that

$$
M+\left(M_{j}^{d+1}-M_{j}^{d}\right)[v\rangle M^{\prime}+\left(M_{j+1}^{d+1}-M_{j+1}^{d}\right)
$$

and

$$
(M, u) \leqslant\left(M+\left(M_{j}^{d+1}-M_{j}^{d}\right), v\right) .
$$

Hence

$$
\begin{aligned}
& M_{j}^{i}\left(r_{1}, \ldots, r_{d-1}, 1+r_{d}, r_{d+1}, \ldots, r_{i-1}\right)[v\rangle \\
& \quad\rangle M_{j+1}^{i}\left(r_{1}, \ldots, r_{d-1}, 1+r_{d}, r_{d+1}, \ldots, r_{i-1}\right)
\end{aligned}
$$

and

$$
\left(M_{j}^{i}, u_{j+1}^{i}\right) \leqslant\left[M_{j}^{i}\left(r_{1}, \ldots, r_{d-1}, 1+r_{d}, r_{d+1}, \ldots, r_{i-1}\right), v\right]
$$

by which the proof is finished.

The next lemma adds the case $j=n$ to the previous one (we do not need INSERT in this case).

Lemma 7.13. Let $\sigma$ be a $k$-good sequence as in Definition 7.3. For any $i, 1 \leqslant i \leqslant k$, and any $r_{1}, r_{2}, \ldots, r_{i-1} \in \mathbb{N}$, there is $w \in T^{*}$ such that

$$
M_{n}^{i}\left(r_{1}, r_{2}, \ldots, r_{i-1}\right)[w\rangle M_{0}^{i+1}\left(r_{1}^{\prime}, r_{2}^{\prime}, \ldots, r_{i-1}^{\prime}, r_{i}^{\prime}\right)
$$

where $r_{p} \leqslant r_{p}^{\prime}$ for $p=1,2, \ldots, i-1$.

Proof. (i) The case $\sum_{p=1}^{i-1} r_{p}=0$ is clear (put $w=w^{i}$ ).
(ii) Suppose $M_{n}^{i}\left(r_{1}, r_{2}, \ldots, r_{i-1}\right)[w\rangle M_{0}^{i+1}\left(r_{1}^{\prime}, r_{2}^{\prime}, \ldots, r_{i-1}^{\prime}, r_{i}^{\prime}\right)$. It is easy to verify that

$$
M_{n}^{i}\left(r_{1}, r_{2}, \ldots, r_{i-1}\right)+\left(M_{n}^{d+1}-M_{n}^{d}\right)\left[w u^{d} w^{d+1}\right\rangle M
$$

where

$$
\begin{aligned}
M & =M_{0}^{i+1}\left(r_{1}^{\prime}, r_{2}^{\prime}, \ldots, r_{i-1}^{\prime}, r_{i}^{\prime}\right)+M_{n}^{d+1}-M_{n}^{d}+M_{n}^{d}-M_{0}^{d}+M_{0}^{d+2}-M_{n}^{d+1} \\
& =M_{0}^{i+1}\left(r_{1}^{\prime}, \ldots, r_{d-1}^{\prime}, 1+r_{d}^{\prime}, 1+r_{d+1}^{\prime}, r_{d+2}^{\prime}, \ldots, r_{i-1}^{\prime}\right) .
\end{aligned}
$$

Now we define the notion of a "relative"; it is a $k$-good sequence which does not need to satisfy INSERT but which is closely related to some $k$-good INSERT sequence.

Definition 7.14. Let $\sigma$ be a $k$-good INSERT sequence exactly as in Definition 7.3. Let $v$ be an occurrence sequence in the form

$$
\boldsymbol{\sigma}^{\prime}={ }_{N u_{0}} u_{0} M_{0}^{1} \boldsymbol{u}_{M_{n}^{1}}^{1} \underline{u}_{\mathbf{u}_{n}^{2}}^{2} \underline{u}^{3} \underline{M}_{n}^{3} \ldots \underline{u}_{\underline{M}_{n}^{k}}^{k},
$$

where every subsequence $M_{i} \underline{u}^{i} \underline{w}_{i}^{\prime}$ can be written in more detail

$$
\underline{M}_{0}^{i} \underline{u}_{1}^{i} \underline{M}_{1}^{i} \underline{u}_{2 M_{2}^{i}}^{i} \ldots \underline{u}_{n}^{i} \underline{M}_{n}^{\prime} .
$$

(Hence $\sigma^{\prime}$ has the same prefix as $\sigma$; of course, $M_{n}^{1}=\underline{M}_{n}^{1}$ ).
$\sigma^{\prime}$ is a relative of $\sigma$ if the following conditions hold:
(1) for all $i, j, 1 \leqslant i \leqslant k, 1 \leqslant j \leqslant n$, there are parameters $r_{1}, r_{2}, \ldots, r_{i-1}$ such that $M_{j}^{i}=M_{j}^{i}\left(r_{1}, r_{2}, \ldots, r_{i-1}\right)$,
(2) the parameters in (1) can be chosen so that if ( $\left.i<i^{\prime}\right) \vee\left(i=i^{\prime} \& j<j^{\prime}\right)$ then $r_{p} \leqslant r_{p}^{\prime}$ for $p=1,2, \ldots, i-1$ ( $r_{p}$ being the parameters belonging to $i, j, r_{p}^{\prime}$ to $\left.i^{\prime}, j^{\prime}\right)$.

Remark 7.15. It is easy to verify that a relative of $\sigma$ is also a $k$-good sequence (where INSERT is not necessary and $w^{i}=\varepsilon$ for all $i$ ). Notice that any $k$-good INSERT sequence can be rewritten into a form of its relative by the notation change $\left(u_{1}^{i}\right)_{\text {NEW }}=\left(w^{i-1} u_{1}^{i}\right)_{\text {OLD }}$ for all $i \geqslant 2$.

Now we are ready to define the modifications mentioned before Notation 7.11. They use linear combinations of the "previous relevant sectors" in order to change $\boldsymbol{R}_{j}^{i}$ (and establish $\operatorname{MUL}(i, j)$ ).

Definition 7.16. Let $\sigma$ and its relative $\sigma^{\prime}$ be exactly as in Definition 7.14. An $i, j$-modification of $\sigma^{\prime}(2 \leqslant i \leqslant k, 1 \leqslant j \leqslant n)$ consists of two steps:
(1) replacing $\underline{u}_{j}^{i}$ by

$$
u_{j}^{i}=\underline{u}_{j}^{i}[\operatorname{sect}(2, j)]^{k_{2}}[\operatorname{sect}(3, j)]^{k_{2}} \ldots[\operatorname{sect}(i, j)]^{k_{1}}
$$

for some $k_{2}, k_{3}, \ldots, k_{i} \in \mathbb{N}$ (the sectors from $\sigma^{\prime}$ are meant; $\boldsymbol{M}_{j}^{i}$ changes appropriately, but conditions from Definition 7.14. remain holding for it).
(2) a successive replacing of

$$
\underline{u}_{j+1}^{i}, \underline{u}_{j+2}^{i}, \ldots, \underline{u}_{n}^{i}, \underline{u}_{1}^{i+1}, \underline{u}_{2}^{i+1}, \ldots, \underline{u}_{n}^{i+1}, \ldots, \underline{u}_{1}^{k}, \underline{u}_{2}^{k}, \ldots, \underline{u}_{n}^{k}
$$

(and the appropriate changing of $\underline{M}_{j+1}^{i}, \ldots, M_{n}^{k}$ ) in such a way that the new sequence is also a relative of $\sigma$.

Lemma 7.17. For any $i, j, 2 \leqslant i \leqslant k, 1 \leqslant j \leqslant n$, and any $k_{2}, k_{3}, \ldots, k_{i} \in \mathbb{N}$, there is the $i, j$-modification described above.

Proof. The correctness of Step (1) follows from the $k$-good sequence properties (a relative is $k$-good); the "new" $M_{j}^{i}$ (i.e. $M_{j}^{i}$ ) is obviously equal to $M_{j}^{i}\left(r_{1}, r_{2}, \ldots, r_{i-1}\right)$ for some parameters which are equal or greater than the "old" ones.

For Step (2), we can use Lemmas 7.12 and 7.13. If, during the successive replacing, we are to replace some $\underline{u}_{j}^{i}$, where $2 \leqslant j \leqslant n$, we use $u$ ensured by Lemma 7.12. If we are to replace some $\underline{u}_{1}^{\prime \prime}$, we use $w u$, where $w$ is ensured by Lemma 7.13. and $u$ by Lemma 7.12.

By such a successive replacing "from left to right", we really get another elative $\sigma^{\prime \prime}$ of (the original) $\sigma$.

Remark 7.18. In fact, only $i, j$-modifications with at most two $k_{p}$ not equal to zero will be used. Notice that any $i, j$-modification does not affect the prefix before $\underline{u}_{j}$ ( $\underline{u}_{j}^{i}$ is changed in the defined way; as regards the suffix, we need only the correctness).

Now we show how MUL(i,j) can be achieved without affecting $R_{j}^{i}$.

Lemma 7.19. Let a relative $\sigma$ (of a $k$-good INSERT sequence) be given. For any fixed $i, j$, there is an $i, j$-modification after which $\operatorname{MUL}(i, j)$ holds and $R_{;}^{i}$ remains unchanged.

Proof. It suffices to perform an $i, j$-modification which starts by replacing $u_{j}^{i}$ by $u_{j}^{i}[\operatorname{sect}(i, j)]^{r}$ where $r=\left[M_{j}^{i-1}-M_{j}^{i-2}\right]\left(s_{\mathrm{cnt}}\right)-1$.

A crucial point in changing $R_{j}^{i}$ is Lemma 7.21; we need the following simple fact.

Lemma 7.20. For any $m_{1}, m_{2} \in \mathbb{N}, n_{1}, n_{2} \in \mathbb{N}_{+}, q \in \mathbb{Q}_{+}$, where $m_{1} / n_{1}<q<m_{2} / n_{2}$, there are $x_{1}, x_{2} \in \mathbb{N}_{+}$such that $\left(m_{1} x_{1}+m_{2} x_{2}\right) /\left(n_{1} x_{1}+n_{2} x_{2}\right)=q$.

Proof. Let $q=c_{1} / c_{2}$ for $c_{1}, c_{2} \in \mathbb{N}_{+}$. We want to solve the equation $c_{2} m_{1} x_{1}+c_{2} m_{2} x_{2}=$ $c_{1} n_{1} r_{1}+c_{1} n_{2} x_{2}$, i.e. $\left(c_{2} m_{2}-c_{1} n_{2}\right) x_{2}=\left(c_{1} n_{1}-c_{2} m_{1}\right) x_{1}$. Due to $c_{2} m_{1}<c_{1} n_{1}, c_{1} n_{2}<$ $c_{2} m_{2}$, a positive solution is clear.

Lemma 7.21. Let a relative $\sigma$ (of a $k$-good INSERT sequence) be given. Let $S^{\prime} \subseteq S$, $s^{\prime} \in S \backslash S^{\prime}, 2 \leqslant i^{\prime}<i^{\prime \prime}<i \leqslant k, 1 \leqslant j \leqslant n$ and

$$
\begin{equation*}
R_{j}^{i^{\prime}} \backslash S^{\prime}=R_{j}^{i^{\prime \prime}} \backslash S^{\prime}=R_{j}^{i} \mid S^{\prime} \tag{3}
\end{equation*}
$$

In addition, let $q \in \mathbb{Q}_{+}$be strictly between $R_{j}^{i^{\prime}}\left(s^{\prime}\right)$ and $R_{j}^{i^{\prime \prime}}\left(s^{\prime}\right)$. Then it can be achieved by an $i, j$-modification that $R_{j}^{i}\left(s^{\prime}\right)=q$ and $R_{j}^{i} \dagger S^{\prime}$ remains the same.

Proof. If $R_{j}^{i}\left(s^{\prime}\right) \neq q$ then $q$ is strictly between $R_{j}^{i^{\prime}}\left(s^{\prime}\right)$ and $R_{j}^{i}\left(s^{\prime}\right)$ or strictly between $R_{j}^{i^{\prime \prime}}\left(s^{\prime}\right)$ and $R_{j}^{i}\left(s^{\prime}\right)$; suppose the first alternative (the second being similar).
Due to the previous lemma there are $x_{1}, x_{2}$ such that the following holds: performing an $i, j$-modification which starts by replacing $u_{j}^{i}$ by $u_{j}^{i}\left[\operatorname{seci}\left(i^{\prime}, j\right)\right]^{x_{1}}[\operatorname{sect}(i, j)]^{x_{2}-1}$, we obtain $R_{j}^{i}\left(s^{\prime}\right)=q$ and $R_{j}^{i}\left\lceil S^{\prime}\right.$ remains the same due to (3).

Now we can reach the aim defined after Definition 7.8.
Proposition 7.22. Leł $a \mathbb{P}_{\text {key }}$-instance $\Sigma=\left(S, T, W, M_{0}\right),\left(S_{1}, f_{1}\right), \ldots,\left(S_{n}, f_{n}\right)$ be given. If there is a $k$-good INSERT sequence for $k=1+2^{c}$, where $c=n|S|+1$, then there is also a regular sequence.

Proof. Let $\sigma$ be a $k$-good INSERT sequence. Change the notation as in Remark 7.15 to obtain $\sigma$ in a form of its relative. It suffices to show a series of modiaications which will ensure that

$$
\begin{equation*}
(\exists m, 1 \leqslant m \leqslant k-2) \quad(\forall j, 1 \leqslant J \leqslant n) \quad\left[R_{j}^{m+1}=R_{j}^{m+2} \& \operatorname{MUL}(m+2, j)\right] \tag{4}
\end{equation*}
$$

(cf. Remark 7.10; the exact form of a regular sequence will then be obtained by notation changes).

We shall show the following proposition $\mathrm{P}(r)$ for $r=0,1, \ldots, n|S|$ by induction. $P(n|S|)$ will imply (4) by which the proof will be finished.

Proposition $7.23(\mathrm{P}(r))$. There are

- a relative $\sigma_{r}$ of $\sigma$,
- $m_{r} \in \mathbb{N}_{+}, 1 \leqslant m_{r} \leqslant k-2^{c-r}(c=\imath|S|+1)$,
- two disjoiut scis $M_{r}, N_{r} \subseteq S \times\{1,2, \ldots, n\}$, where $\left|M_{r} \cup N_{r}\right|=r$ and some $q_{i}(s) \in \mathbb{Q}_{+}$ is given for every $(s, j) \in M_{r}$
meeting the following two conditions (we write range ${ }_{r}$ instead of $\left\{m_{r}+1, m_{r}+2, \ldots\right.$, $\left.m_{r}+2^{c-r}\right\}$ ):
(1) suppose any series of any $i, j$-modifications of $\sigma_{r}, i$ moving in range, only, has been performed. Now for every pair $i^{\prime}, j^{\prime}, i^{\prime} \in$ range $_{r}$, we can achieve by several $i^{\prime}$, $j$ '-modifications that

$$
(\forall s \in S) \quad\left[\left(s, j^{\prime}\right) \in M_{r} \Rightarrow R_{j^{\prime}}^{i^{\prime}}(s)=q_{j^{\prime}}(s)\right] .
$$

(2) Again, suppose any series of any $i, j$-modifications of $\sigma_{r}, i$ moving in range $r_{r}$ only, has been performed. For any $i^{\prime}, i^{\prime \prime}, j^{\prime}, i^{\prime}, i^{\prime \prime} \in$ range $_{r}$, if

$$
(\forall s \in S) \quad\left[\left(s, j^{\prime}\right) \in M_{r} \Rightarrow R_{j^{\prime}}^{i^{\prime}}(s)=R_{j^{\prime}}^{i^{\prime \prime}}(s)=q_{j^{\prime}}(s)\right]
$$

holds, then

$$
(\forall s \in S) \quad\left[\left(s, j^{\prime}\right) \in N_{r} \Rightarrow R_{j^{\prime}}^{i^{\prime}}(s)=R_{j}^{\prime^{\prime \prime}}(s)\right]
$$

is also ensured.
$\mathbf{P}(0)$ is obvious: take $\sigma$ in the form of its relative as $\sigma_{0}$ and put $m_{0}=1, M_{0}=N_{0}=\emptyset$.
We shall show $\mathrm{P}(r) \Rightarrow \mathrm{P}(r+1)$ for $r<n|S|$. FH (range ${ }_{r}$ ) will denote the first half of range $e_{r}$, i.e. $\left\{m_{r}+1, m_{r}+2, \ldots, m_{r}+2^{-r-1}\right\}$, $\mathrm{SH}\left(\right.$ range $\left._{r}\right)$ the second half similarly. Take an arbitrary $\left(s^{\prime}, j^{\prime}\right) \notin \boldsymbol{M}_{r} \cup \mathbb{N}_{r}$. There are two possibilities, (a) and (b), only.
(a) After performing any series of any $i, j$-modifications of $\sigma_{r}$, $i$ moving in $F H$ (range $e_{r}$ ) only, the following holds: for any $i^{\prime}, i^{\prime \prime} \in \mathrm{FH}$ (range $e_{r}$ ), if

$$
(\forall s \in S) \quad\left[\left(s_{j}^{\prime}\right) \in j_{r} \Rightarrow R_{j}^{i^{\prime}}(s)=R_{j}^{\prime}(s)=q_{j}(s)\right]
$$

holds then $R_{j}^{i \prime}\left(s^{\prime}\right)=R_{j}^{i^{\prime \prime}}\left(s^{\prime}\right)$ is also ensured. In such a case, we can put $\sigma_{r+1}=\sigma_{r}$, $m_{r+1}=m_{r}, \quad M_{r+1}=M_{r}, \quad \mathbb{N}_{r+1}=\mathbb{N}_{r} \cup\left\{\left(s^{\prime}, j^{\prime}\right)\right\}$ and $\mathbb{P}(r+1)$ is clear (range ${ }_{r+1}=$ FH (range ${ }_{r}$ ), of course).
(b) There is a series $\varphi$ of $i, j$-modifications of $\sigma_{r}$, where $i$ moves in FH (range ${ }_{r}$ ) only, after the performing of which we have for some $i^{\prime}, i^{\prime \prime} \in \mathrm{FH}$ (range ${ }_{r}$ ):

$$
(\forall s \in S) \quad\left[\left(s, j^{\prime}\right) \in M_{r} \Rightarrow R_{j^{\prime}}^{i^{\prime}}(s)=R_{j^{\prime}}^{i^{\prime \prime}}(s)=q_{j}(s)\right]
$$

and $R_{j^{\prime}}^{i^{\prime}}\left(s^{\prime}\right) \neq R_{j^{\prime}}^{i^{\prime \prime}}\left(s^{\prime}\right)$.
In such a case, take $\sigma_{r}$ modified by $\varphi$ as $\sigma_{r+1}$ and put $m_{r+1}=m_{r}+2^{r-r-1}, \mathbb{N}_{r+1}=\mathcal{N}_{r}$, $M_{r+1}=M_{r} \cup\left\{\left(s^{\prime}, j^{\prime}\right)\right\}$ choosing $q_{j^{\prime}}\left(s^{\prime}\right)$ strictly between $R_{j^{\prime}}^{\prime}\left(s^{\prime}\right)$ and $R_{j^{\prime}}^{\prime \prime}\left(s^{\prime}\right)$.
$P(r+1)$ can then be verified by help of $\mathbb{P}(r)$ and Lemma 7.21 (in this case, range $_{r+1}=\mathrm{SH}\left(\right.$ range $\left._{r}\right)$ ).

In the end, we show $\mathrm{P}(n|S|) \Rightarrow(4)$. Take $\sigma_{r}$ and put $m=m_{r}$ for $r=n|S|$ (range, $=$ $\{m+1, m+2\}$ ). The $i^{\prime}, j^{\prime}$-modifications ensured by (1) of $\mathrm{P}(n|S|)$ can be performed successively for

$$
\begin{aligned}
\left(i^{\prime}, j^{\prime}\right)= & (m+1,1),(m+1,2), \ldots,(m+1, n),(m+2,1) \\
& (m+2,2), \ldots,(m+2, n)
\end{aligned}
$$

in case $i^{\prime}=\boldsymbol{m}+2$, we always add the $\left(i^{\prime}, j^{\prime}\right)$-modification ensured by Lemma 7.19. Thereby (4) is established.

Now we will show that a regular sequence can be lengthened to infinity in the "regular" way whereby an $\omega$-good STRICT INSERT sequence arises.

Definition 7.24. Let $\sigma$ be a $k$-good sequence as in Definition 7.3. $\sigma$ will be called a $k$-good STRICT INSERT sequence if
(1) $w^{i}=\varepsilon$ for all $i$, and
(2) for any $i, j, 2 \leqslant i \leqslant k, 1 \leqslant j \leqslant n, u_{j}^{i}=u_{j}^{i-1} v$ for some $v$.

An $\omega$-good STRICT INSERT sequence is defined in the same way.

It is obvious that a $k$-good ( $\omega$-good) STRICT INSERT sequence satisfies INSERT (i.e. the above notion is correct).

Proposition 7.25. Let a $\mathbb{P}_{\text {key }}$-instance be given. If there is a regular sequence then there is also an $\omega$-good STRICT INSERT sequence.

Proof. Suppose $\sigma$ as in Definition 7.8 and take some $x \in \mathbb{N}$ such that $k_{n}+x=c k_{1}$ for some $c \in \mathbb{N}$. Notice that

$$
\Delta\left(u_{1}^{3} u_{2}^{1} u_{3}^{1} \ldots u_{n}^{1}\right)=\left(M_{1}^{3}-M_{n}^{2}\right)+\left(M_{n}^{1}-M_{1}^{1}\right)=-\left(M_{n}^{2}-M_{n}^{1}\right)+\left(M_{1}^{3}-M_{1}^{1}\right)
$$

and recall $M_{n}^{3}=M_{n}^{2}+k_{n}\left(M_{n}^{2}-M_{n}^{1}\right)$.

Now we can easily verify what follows.

$$
\begin{aligned}
& M_{n}^{3}\left[\left(u_{1}^{3} u_{2}^{1} u_{3}^{1} \ldots u_{n}^{1}\right)^{k}\right\rangle M_{n}^{2}+k_{n}\left(M_{1}^{3}-M_{1}^{1}\right)\left[u_{1}^{3}\right\rangle M_{1}^{3}+k_{n}\left(M_{1}^{3}-M_{1}^{1}\right) \\
& \quad \times\left[\left(u_{2}^{1} u_{3}^{1} \ldots u_{n}^{1} u_{1}^{2}\right)^{x}\right\rangle M^{\prime},
\end{aligned}
$$

where

$$
\begin{aligned}
M^{\prime} & =M_{1}^{3}+k_{n}\left(M_{1}^{3}-M_{1}^{2}\right)+k_{n}\left(M_{1}^{2}-M_{1}^{1}\right)+x\left(M_{1}^{2}-M_{1}^{1}\right) \\
& =M_{1}^{2}+k_{n}\left(M_{1}^{3}-M_{1}^{2}\right)+c k_{1}\left(M_{1}^{2}-M_{1}^{1}\right) \\
& =M_{1}^{3}+\left(k_{n}+c\right)\left(M_{1}^{3}-M_{1}^{2}=M_{\mathrm{df}}^{4} .\right.
\end{aligned}
$$

Thus we have lengthened $\sigma$ by a certain $u_{1}^{4}=u_{1}^{3} v$ in the "regular way". This way can be continued to infinity. Then the notation change $\left(u^{i}\right)_{\text {NEW }}=\left(u^{i+2}\right)_{\text {oLD }}$ finishes the proof.

Proposition 7.26. There is an algorithm specified as follows:
Input: $a \mathbb{P}_{\text {key }}$-instance $\Sigma=\left(S, T, W, M_{0}\right),\left(S_{1}, f_{1}\right),\left(S_{2}, f_{2}\right), \ldots,\left(S_{n}, f_{n}\right)$.
Output: YES if there is a $k$-good STRICT INSERT sequence for $k=1+2^{c}$ where $c=n|S|+1$, NO otherwise.

Proof. In a straightforward way, the conditions satisfied by a $\boldsymbol{k}$-good STRICT INSERT sequence can be described with a formula from $L_{\Sigma}^{m}$ (defined in Definition 5.3.) for some $m$ depending on $k$. The only difficulty is to describe the condition $u_{j}^{i}=u_{j}^{i-1} v$ (for some $v$ ); but it suffices to ensure $u_{j}^{i}=u v$ where $\Delta(u)=\Delta\left(u_{j}^{i-1}\right)$; as such $u$ could be immediately replaced by $u_{j}^{i-1}$ (because of $M_{j-1}^{i-1} \leqslant M_{j-1}^{i}$ ).

Thus the existence of the above-specified algorithm follows from Theorem 5.4.

Theorem 7.27. Problem $\mathbb{P}_{\text {key }}$ is decidable.

Proof. It follows from Propositions 7.7, 7.22, 7.25 (cf. Fig. 2) that the algorithm from Proposition 7.26, decides $\mathbb{P}_{\text {key }}$.

Theorem 7.28. Problem $\mathbb{P}_{\text {temp }}$ (including $\mathbb{P}_{\mathrm{fdp}}$ ) is aecidable.

Proof. It follows from Proposition 4.5 and Theorem 7.27.

## Conclusion

Establishing the deciduciaity of $\mathcal{F}_{\text {fdp }}$ and of (more general) $\mathbb{P}_{\text {temp }}$ we have solved an open problem from [2] and [4]. Unfortunately, the presented proof does not imply $\mathbb{P}_{\text {fdp }} \equiv \equiv_{\text {pTime }} \mathbb{R P P}$ (our reduction was exponential); that would answer the relevant question from [4] completely.

## Acknewledgment

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