# Convolution theory in a space of generalized functions* 

by A. J. E. M. Janssen<br>Dept. of Mathematics, Eindhoven University of Technology

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## INTRODUCTION

This paper presents a convolution theory for the test function space $S$ of smooth functions and the space $S^{*}$ of generalized functions as introduced by De Bruijn (the terminology and notation is the one used in [B], where these spaces are defined). The space $S$ can be regarded as an example of a test function space of the type studied in [GS], Ch. IV (actually, our space $S$ can be identified with the space $S \ddagger$ of [GS], Ch. IV, § 2.3). Since the spaces $S$ and $S^{*}$ are adapted to the needs of Fourier analysis (cf. [B], section 8 and 9, and [GS], Ch. IV, § 6), it was to be expected that it is possible to develop a satisfactory convolution theory for these spaces; it seems however that no such theory has been published thus far.

Let us summarize the contents of this paper. Section 1 gives the main definitions and theorems about the spaces $S$ and $S^{*}$, and some results about continuous linear transformations in these spaces are mentioned. This section is mainly included here for ease of reference.

Section 2 serves as a preparation. The convolution operators introduced here involve smooth functions only, and they are defined as follows. If $g \in S$, then the convolution operator $T_{g}$ of $S$ is defined by

$$
\begin{equation*}
\left(T_{g} f\right)(x)=\int_{-\infty}^{\infty} f(x-t) \overline{g(t)} d t \quad(x \in \mathrm{Q}) \tag{1}
\end{equation*}
$$

[^0]for $f \in S$. Instead of the integral at the right hand side in (1) we can also write ( $T_{x} f, g_{-}$), where $T_{x}$ is the shift operator over distance $x$, and $g_{-}$is the smooth function with values $g_{-}(t)=g(-t)$ for $t \in \mathbf{C}$.

In section 3 we generalize the notion of convolution operator. The $g$ in (1) is replaced by a generalized function: if $G \in S^{*}$, then the convolution operator $T_{G}$ of $S$ is defined by

$$
\begin{equation*}
\left(T_{G} f\right)(x)=\left(T_{x} f, G_{-}\right) \quad(x \in \mathbf{Q}) \tag{2}
\end{equation*}
$$

for $f \in S$. Here $G_{-}$bears a similar relation to $G$ as $g_{-}$does to $g$ in the previous paragraph. Special attention is paid to the case that $T_{G}$ maps $S$ into $S$, and the class of all $G \in S^{*}$ with this property is called the convolution class $\mathscr{C}$. For $G \in \mathscr{C}$ we prove that $T_{G}$ has an adjoint, and that $T_{G}$ can be extended in a natural way to a continuous linear operator of $S^{*}$. We also discuss some alternative descriptions of the class $\mathscr{C}$.

Section 4 presents a link between convolution theory and Fourier analysis. This involves what we call multiplication operators of $S$ and $S^{*}$. If $g \in S$, then the multiplication operator $M_{g}$ of $S$ is defined by $M_{\theta} f=g \cdot f$ for $f \in S$, where the dot denotes pointwise multiplication; this multiplication operator can be extended in a natural way to a continuous linear operator of $S^{*}$. We obtain a useful characterization of the class $\mathscr{C}$ in terms of the Fourier transforms of its elements. Furthermore the convolution theorem is generalized in section 4, and a version of Titchmarsh's theorem is proved. Finally we mention some results about the solutions $F \in S^{*}$ of equations of type $T_{G} F=0$, where $G$ is a fixed element of $\mathscr{C}$.

Section 5 contains some additional material. There we prove that the class of generalized functions of the form $M_{g} G$ with $g \in S, G \in S^{*}$ is a proper subset of $\mathscr{C}$. We make some remarks about convergence in $\mathscr{C}$, and finally we pay some attention to convolution theory for the spaces of smooth and generalized functions of several variables.

## notation

We use Church's lambda calculus notation, but instead of his $\lambda$ we have the symbol $Y$, as suggested by Freudenthal: If $S$ is a set, then putting $Y_{x \in S}$ in front of an expression (usually containing $x$ ) means to indicate the function with domain $S$ and with the function values given by the expression. For example, if $g \in S$ then $T_{g}=Y_{f \in S} T_{g} f$. In case it is clear from the context which set $S$ is meant, we write $Y_{x}$ instead of $Y_{x \in S}$.

## 1. the spaces $S$ and $S^{*}$

1.1. We give a survey of the fundamental notions and theorems of De Bruijn's theory of generalized functions (as far as relevant for this paper). Also, the main theorems of [J], appendix 1 about continuous linear operators of $S$ and $S^{*}$ are given. More details can be found in [B] and [J].

The class $S$ (of smooth functions) is the set of all analytic functions $f$ of one complex variable that satisfy inequalities

$$
|f(t)| \leqslant M \exp \left(-\pi A(\operatorname{Re} t)^{2}+\pi B(\operatorname{Im} t)^{2}\right) \quad(t \in \mathbf{C})
$$

where $M>0, A>0, B>0$ depend on $f$. In $S$ we take the usual inner product, denoted by (, ). Cf. [B], 2.1.
1.2. We consider a semigroup $\left(N_{\alpha}\right)_{\alpha>0}$ of linear operators of $S$ (the smoothing operators); they satisfy $N_{\alpha+\beta}=N_{\alpha} N_{\beta}(\alpha>0, \beta>0)$. These operators are integral operators (integration over $\mathbf{R})$; the kernels $K_{a}(\alpha>0)$ are given by
$K_{a}(z, t)=(\sinh \alpha)^{\frac{1}{2}} \exp \left(\frac{-\pi}{\sinh \alpha}\left(\left(z^{2}+t^{2}\right) \cosh \alpha-2 z t\right)\right) \quad(z \in \mathbf{Q}, t \in \mathbf{Q})$.
Cf. [B], section 4, 5 and 6. The operators $N_{\alpha}(\alpha>0)$ can be defined on the larger space $S^{+}$consisting of all mappings $f: \mathbb{R} \rightarrow \mathbf{C}$ such that

$$
Y_{t \in \mathrm{R}} f(t) \exp \left(-\pi \varepsilon t^{2}\right) \in \mathscr{L}_{1}(\mathbf{R}) \text { for every } \varepsilon>0
$$

We have $N_{\alpha} f \in S$ for $f \in S^{+}, \alpha>0$ (compare [B], section 20, where an equivalent definition of $\mathbb{S}^{+}$is used). Note that $\mathscr{L}_{2}(\mathbf{R}) \subset \mathbb{S}^{+}$.
1.3. We summarize some properties of $N_{\alpha}(\alpha>0)$.
(i) $\left(N_{\alpha} f, g\right)=\left(f, N_{\alpha} g\right)$ for $\alpha>0, f \in S, g \in S$ (cf. [B], 6.5).
(ii) If $f \in S, \alpha>0$, then there is at most one $g \in S$ with $f=N_{a} g$. Also, if $f \in S$, then there exists an $\alpha>0, g \in S$ with $f=N_{\alpha} g$. And if $f \in S$, and the numbers $M>0, A>0, B>0$ are such that

$$
|f(t)| \leqslant M \exp \left(-\pi A(\operatorname{Re} t)^{2}+\pi B(\operatorname{Im} t)^{2}\right) \quad(t \in \mathrm{C})
$$

then we can find an $\alpha>0, M^{\prime}>0, A^{\prime}>0, B^{\prime}>0$, only depending on $A$ and $B$, such that the inequalities

$$
|g(t)| \leqslant M M^{\prime} \exp \left(-\pi A^{\prime}(\operatorname{Re} t)^{2}+\pi B^{\prime}(\operatorname{Im} t)^{2}\right) \quad(t \in \mathbf{Q})
$$

hold for the unique $g \in S$ with $f=N_{\alpha} g$ (cf. [B], 10.1).
1.4. We list some other linear operators of $S$ (cf. [B], section 8 and 11).
(i) The Fourier transform $\mathscr{F}$ and its inverse $\mathscr{F}^{*}$ :

$$
\mathscr{F} f=Y_{z a c} \int_{-\infty}^{\infty} e^{-2 \pi z t} f(t) d t, \mathscr{F} * f=Y_{z e c}(\mathscr{F} f)(-z) \quad(f \in S) .
$$

(ii) The shift operators $T_{a}(a \in \mathrm{Q})$ and $R_{b}(b \in \mathrm{Q})$ :

$$
T_{a} f=Y_{z \in c} f(z+a), R_{b} f=Y_{s \in C} e^{-2 \pi b z} f(z) \quad(f \in S)
$$

(iii) The operators $P$ and $Q$ :

$$
P f=Y_{z \in c} \frac{f^{\prime}(z)}{2 \pi i}, Q f=Y_{z \in C} z f(z) \quad(f \in S) .
$$

1.5. A generalized function $F$ is a mapping $\alpha \in(0, \infty) \rightarrow F_{\alpha} \in S$ such that $N_{\alpha} F_{\beta}=F_{\alpha+\beta}(\alpha>0, \beta>0)$. We also write $F(\alpha)$ or $N_{\alpha} F$ instead of $F_{\alpha}$.

It follows from $1.3(\mathrm{ii})$ that $F=0$ in case $F_{\alpha}=0$ for some $\alpha>0\left(F \in S^{*}\right)$.
If $F \in S^{*}, g \in S$, then the inner product ( $F, g$ ) is defined as follows: write $g=N_{\alpha} h$ with some $\alpha>0, h \in S$ (cf. 1.3(ii)), and put ( $F, g$ ): $=\left(F_{\alpha}, h\right)$ (this number depends only on $F$ and $g$; cf. [B], section 17 and 18). We have $\left(N_{\alpha} F, g\right)=\left(F, N_{\alpha} g\right)$ for $\alpha>0, F \in S^{*}, g \in S$.

We further define $(g, F):=(\overline{F, g})$ for $F \in S^{*}, g \in S$.
1.6. We give some examples of generalized functions.
(i) If $f \in S^{+}$, then the embedding of $f$ (notation: emb $(f)$ ) is defined by $\operatorname{emb}(f):=Y_{\alpha>0} N_{\alpha} f$.

Cf. [B], section 20. We have for $f \in S^{+}, g \in S$

$$
(\operatorname{emb}(f), g)=\int_{-\infty}^{\infty} f(t) \overline{g(t)} d t
$$

It may be proved that $f=0$ (a.e.) if and only if emb $(f)=0$.
(ii) For $b \in \mathbf{Q}$, the "delta function at $b$ " is defined by

$$
\delta_{b}:=Y_{a>0} Y_{t \in \mathcal{C}} K_{\alpha}(t, b) .
$$

Now $\left(g, \delta_{b}\right)=g(\bar{b})$ for $g \in S$ (cf. [B], 17.3 and 27.18).
1.7. We next define convergence in $S$. Let $\left(f_{n}\right)_{n \in \mathbb{N}}$ be a sequence in $S$, and let $f \in S$. We write $t_{n} \xrightarrow{S} 0$ if there are positive numbers $A$ and $B$ such that $f_{n}(t) \exp \left(\pi A(\operatorname{Re} t)^{2}-\pi B(\operatorname{Im} t)^{2}\right) \rightarrow 0$ uniformly in $t \in \mathbf{C}$; we write $f_{n} \xrightarrow{s} f$ if $f_{n}-f \xrightarrow{s} 0$. Similarly we define $f^{(\alpha)} \xrightarrow{s} 0(\alpha \downarrow 0)$ and $f^{(\alpha)} \xrightarrow{s} f$ $(\alpha \downarrow 0)$ if $f^{(\alpha)} \in S(\alpha>0), f \in S$. Cf. [B], section 23.

### 1.8. The following theorem on $S$-convergence is useful.

theorem. Let $\left(f_{n}\right)_{n \in \mathrm{~N}}$ be a sequence in $S$. The three following statements are equivalent.
(i) $f_{n} \xrightarrow{s} 0$.
(ii) There exist $\alpha>0$ and $g_{n} \in S(n \in \mathbb{R})$ such that $f_{n}=N_{\alpha} g_{n}, g_{n} \xrightarrow{s} 0$.
(iii) There exists an $M>0, A>0, B>0$ such that

$$
\left|f_{n}(t)\right| \leqslant M \exp \left(-\pi A(\operatorname{Re} t)^{2}+\pi B(\operatorname{Im} t)^{2}\right) \quad(t \in \mathbf{Q})
$$ and $f_{n} \rightarrow 0$ pointwise.

Proof. Equivalence of (i) and (ii) follows from [B], 23.1, and equivalence of (i) and (iii) follows from [J], appendix 2, theorem 1.
1.9. We proceed by defining convergence in $S^{*}$. Let $\left(F_{n}\right)_{n \in N}$ be a sequence in $S^{*}$, and let $F \in S^{*}$. We write $F_{n} \xrightarrow{S^{*}} 0$ if $N_{\alpha} F_{n} \xrightarrow{S} 0$ for every
$\alpha>0$; we write $F_{n} \xrightarrow{s^{*}} F$ if $F_{n}-F^{s^{*}} 0$. Similarly we define $F^{(\beta)} \xrightarrow{s^{*}} 0(\beta \downarrow 0)$ and $F^{(\beta)} \xrightarrow{S^{*}} F(\beta \downarrow 0)$ if $F^{(\beta)} \in S^{*}(\beta>0), F \in S^{*}$.
[B], 24.2 states: a sequence $\left(F_{n}\right)_{n \in \mathrm{~N}}$ in $S^{*}$ is $S^{*}$-convergent if and only if $\lim _{n \rightarrow \infty}\left(F_{n}, g\right)$ exists for every $g \in S$.

It is not hard to prove from 1.8 that $\left(F_{n}, f_{n}\right) \rightarrow(F, f)$ if $F_{n} \xrightarrow{s^{*}} F, f_{n} \xrightarrow[\rightarrow]{s} f$, where $\left(F_{n}\right)_{n \in \mathrm{~N}}$ is a sequence in $S^{*}$ and $\left(f_{n}\right)_{n \in \mathrm{~N}}$ is a sequence in $S$.
1.10. We are going to study continuous linear transformations of $S$ and $S^{*}$.
definition. A linear functional $L$ of $S$ is called continuous if $L f_{n} \rightarrow 0$ for every sequence $\left(f_{n}\right)_{n \in \mathrm{~N}}$ in $S$ with $f_{n} \xrightarrow{s} 0$. A linear operator $T$ of $S$ is called continuous if $T f_{n} \xrightarrow{s} 0$ for every sequence $\left(f_{n}\right)_{n \in \mathrm{~N}}$ in $S$ with $f_{n} \xrightarrow{S} 0$. The definitions of continuous linear functionals and operators of $S^{*}$ are similar. (We use the word continuous instead of quasi-bounded, cf. [B], 22.2 , and [J], appendix $1,2.2$.)
1.11. definition. A linear operator $T$ of $S$ is said to have an adjoint if for every $g \in S$ there is a $g^{*} \in S$ such that $(T f, g)=\left(f, g^{*}\right)$ for every $f \in S$. Such a $g^{*}$ is unique, and $g^{*}$ depends linearly on $g \in S$. If we define $T^{*} g:=g^{*}$ for $g \in S$, then $T^{*}$ is a linear operator of $S$, called the adjoint of $T$.

Note that if $T$ has an adjoint, then so has $T^{*}$, and $\left(T^{*}\right)^{*}=T$.
1.12. example. We introduce some notation. If $g \in S$, then we define

$$
\bar{g}:=Y_{x \in c} \overline{g(\bar{z})}, g_{-}:=Y_{x \in c} g(-z), \bar{g}_{-}:=Y_{x \in c} \overline{g(-\bar{z})} .
$$

Note that $\bar{g} \in S, g_{-} \in S, \bar{g}_{-} \in S$, and that $(\bar{g})_{-}=\left(\overline{g_{-}}\right)=\bar{g}_{-}$. If $F \in S^{*}$, then we define $\bar{F}:=Y_{\alpha>0} \bar{F}_{a}, F_{-}:=Y_{\alpha>0}\left(F_{\alpha}\right)_{-}, \bar{F}_{-}:=Y_{\alpha>0}\left(\overline{F_{\alpha}}\right)$. Note that (by
 $(\overline{\bar{F}})_{-}=\left(\overline{F_{-}}\right)=\bar{F}_{-}$. We have $(\bar{F}, g)=(\overline{F, \bar{g}}),\left(F_{-}, g\right)=\left(F, g_{-}\right),\left(\bar{F}_{-}, g\right)=\overline{\left(\bar{F}, \bar{g}_{-}\right)}$ for $F \in S^{*}, g \in S$.

If $T$ is a continuous linear operator of $S$, then we define

$$
\bar{T}:=Y_{g \in S} \overline{T \bar{g}}, T_{-}:=Y_{g \in S}\left(T g_{-}\right)-, \bar{T}_{-}:=Y_{g \in S}\left(\overline{T \bar{g}_{-}}\right)_{-}
$$

Now $\bar{T}, T_{-}$and $\bar{T}_{-}$are continuous linear operators of $S$ with $(\bar{T})_{-}=$ $=\left(\overline{T_{-}}\right)=\bar{T}_{-}$, and if $T$ has an adjoint, then so have $\bar{T}, T_{-}$and $\bar{T}_{-}$: $(\bar{T})^{*}=\left(\overline{T^{*}}\right),\left(T_{-}\right)^{*}=\left(T^{*}\right)_{-},\left(\bar{T}_{-}\right)^{*}=\left(\bar{T}^{*}\right)_{-}$.

If $T$ is a continuous linear operator of $S^{*}$, then we define

$$
\bar{T}:=Y_{F \in S} T \bar{F}, T_{--}:=Y_{F \in S^{*}}\left(T F_{-}\right), \bar{T}_{-}:=Y_{F \in S^{*}\left(\bar{T} \overline{F_{-}}\right)-}
$$

Now $\bar{T}, T_{-}$and $\bar{T}_{-}$are continuous linear operators of $S^{*}$ and $(\bar{T})_{-}=$ $=\left(\overline{T_{-}}\right)=\bar{T}_{-}$.
1.13. THEOREM. $L$ is a continuous linear functional of $S$ if and only if there exists an $F \in S^{*}$ such that $L f=(f, F)(f \in S)$. Such an $F$ is unique.

PRoof. Follows easily from [B], 22.2.
1.14. theorem. Let $T$ be a linear operator of $S$. The four following statements are equivalent.
(i) $T$ is continuous.
(ii) $Y_{f \in S}(T f)(x)$ is a continuous linear functional of $S$ for every $x \in \mathbf{Q}$.
(iii) $T N_{\alpha}$ has an adjoint for every $\alpha>0$.
(iv) For every $\alpha>0$ there is a $\beta>0$ and a bounded linear operator $T_{1}$ of $S$ (bounded with respect to inner product norm) such that $T N_{\alpha}=$ $=N_{\beta} T_{1}$.

PROOF. This is proved in [J], appendix 1, 2.2 through 2.10.
remark. A useful alternative formulation of (iv) is: for every $M>0$, $A>0, B>0$ there exists $M_{0}>0, A_{0}>0, B_{0}>0$ such that

$$
|(T f)(t)|<M_{0} \exp \left(-\pi A_{0}(\operatorname{Re} t)^{2}+\pi B_{0}(\operatorname{Im} t)^{2}\right) \quad(t \in \mathbf{Q})
$$

whenever $f \in S$ and

$$
|f(t)|<M \exp \left(-\pi A(\operatorname{Re} t)^{2}+\pi B(\operatorname{Im} t)^{2}\right) \quad(t \in \mathbf{Q})
$$

Equivalence of both conditions easily follows from the equivalence of (i) and (iv), and from [B], 6.3.

The linear operators of 1.4 are continuous.
1.15. THEOREM. If $T$ is a linear operator of $S$ with an adjoint, then it is possible to extend $T$ to a continuous linear operator $\tilde{T}$ of $S^{*}$ such that $\tilde{T}(\mathrm{emb}(f))=\operatorname{emb}(T f)(f \in S),(\tilde{T} F, f)=\left(F, T^{*} f\right)\left(F \in S^{*}, f \in S\right)$. Here emb ( $f$ ) for $f \in S$ is to be read as emb $\left(f_{0}\right)$, where $f_{0}$ is the restriction of $f$ to $\mathbf{R}$ (cf. 1.2).

Proof. This is [J], appendix 1 , theorem 3.2.
We denote the extended operator again by T. For examples, see 1.4.
1.16. We finally devote some attention to (generalized) functions of several variables. The previous definitions and theorems can be given and proved (with the proper modifications) without any restriction for the more dimensional case. For instance, the class $\mathbb{S}^{n}$ (where $n \in \mathbf{R}$ ) is defined as the set of all complex-valued functions $f$ of $n$ complex variables that are analytic in all variables, for which there exist positive numbers $M, A$ and $B$ such that

$$
\left|f\left(t_{1}, \ldots, t_{n}\right)\right|<M \exp \left(\pi \sum_{k=1}^{n}\left(-A\left(\operatorname{Re} t_{k}\right)^{2}+B\left(\operatorname{Im} t_{k}\right)^{2}\right)\right)
$$

for $\left(t_{1}, \ldots, t_{n}\right) \in \mathrm{Q}^{n}$.

As an example of a smooth function of $n$ variables we have

$$
f_{1} \otimes \ldots \otimes f_{n}:=Y\left(t_{1}, \ldots, t_{n}\right) \in c^{n} f_{1}\left(t_{1}\right) \cdot \ldots \cdot f_{n}\left(t_{n}\right),
$$

where $f_{1} \in S, \ldots, f_{n} \in S$.
The classes $S^{n+}$ and $S^{n *}$ (of embeddable and generalized functions respectively) are introduced in a similar way (the smoothing operators $N_{\alpha, n}$ are defined as the $n$-fold tensor products of $N_{\alpha}(\alpha>0)$ ). Cf. [B], section 7 and 21.

As an example of a generalized function of $n$ variables we have

$$
F_{1} \otimes \ldots \otimes F_{n}:=Y_{\alpha>0} N_{\alpha} F_{1} \otimes \ldots \otimes N_{\alpha} F_{n},
$$

where $F_{1} \in S^{*}, \ldots, F_{n} \in S^{*}$.
The notions of convergence and continuity are adapted correspondingly, and theorems $1.13,1.14,1.15$ hold for the present case.
1.17. The following theorem is important (we state it only for the case $n=2$ ).
theorem. If $T_{i}(i=1,2)$ are continuous linear operators of $S$, then the mapping $T_{1} \otimes T_{2}$, defined by

$$
\left(T_{1} \otimes T_{2}\right) f:=Y\left(z_{1}, z_{2}\right) T_{1}\left(Y_{t_{1}}\left(T_{2}\left(Y_{t_{2}} f\left(t_{1}, t_{2}\right)\right)\left(z_{2}\right)\right)\right)\left(z_{1}\right)
$$

for $f \in S^{2}$, is a continuous linear operator of $S^{2}$. If $T_{i}(i=1,2)$ have adjoints, then so has $T_{1} \otimes T_{2}$ (with respect to the inner product in $S^{2}$ ), and $\left(T_{1} \otimes T_{2}\right)^{*}=T_{1}^{*} \otimes T_{2}^{*}$. If furthermore $T_{1}, T_{2}$ and $T_{1} \otimes T_{2}$ are extended to linear operators of $S^{*}, S^{*}$ and $S^{2 *}$ (according to l.15), then we have $\left(T_{1} \otimes T_{2}\right)\left(F_{1} \otimes F_{2}\right)=T_{1} F_{1} \otimes T_{2} F_{2}$ for $F_{1} \in S^{*}, F_{2} \in S^{*}$.
proof. This follows from [J], appendix 1, 2.13 and 3.12.
1.18. An example of an operator of $S^{2}$ (not of the type discussed in 1.17) that can be extended to a continuous linear operator of $S^{2 *}$ is the following one. Define

$$
Z_{v} f:=Y_{\left(t_{1}, t_{2}\right) \in C^{2}} f\left(\frac{t_{1}+t_{2}}{V^{2}}, \frac{t_{1}-t_{2}}{V^{2}}\right) \quad(f \in S)
$$

It is not hard to see that $Z_{U}$ is a continuous linear operator of $S^{2}$ that satisfies $Z_{\boldsymbol{U}}^{*}=\boldsymbol{Z}_{\boldsymbol{v}}$.

## 2. PREPARATION

2.1. We introduce in this section convolution operators defined on $S$ in which only smooth functions appear. Some simple results are derived.
2.2. definition. For $g \in S$ the convolution operator $T_{g}$ is defined by

$$
T_{g} f:=Y_{x \in c} \quad \int_{-\infty}^{\infty} f(x-t) \overline{g(t)} d t \quad(f \in S) .
$$

Note that $T_{g} f$ is the ordinary convolution of $f$ and $Y_{t} \overline{g(t)}$ (it will have some notational convenience in the subsequent sections to take $Y_{t} \overline{g(t)}$ instead of $g$ ).

To avoid confusion with the translation operators $T_{a}(a \in \mathrm{C})$ of $1.4(\mathrm{ii})$, we shall always denote convolution operators by

$$
T_{f}, T_{g}, T_{h}, \ldots, T_{F}, T_{G}, T_{H}, \ldots
$$

where

$$
f \in S, g \in S, h \in S, \ldots, F \in S^{*}, G \in S^{*}, H \in S^{*}, \ldots
$$

whereas translation operators are denoted by $T_{a}, T_{b}, T_{c}, \ldots, T_{x}, T_{y}, T_{z}, \ldots$ with $a \in \mathbf{C}, b \in \mathbf{Q}, c \in \mathbf{Q}, \ldots, x \in \mathbf{Q}, y \in \mathbf{Q}, z \in \mathbf{Q}, \ldots$.
2.3. theorem. If $g \in S$, then we have
(i) $T_{g}$ maps $S$ linearly and continuously into $S$.
(ii) $T_{g}$ has an adjoint, viz. $T_{\boldsymbol{\theta}}^{*}=T_{\bar{\sigma}_{-}}$, and $\bar{T}_{g}=T_{\bar{g}},\left(T_{g}\right)_{-}=T_{g_{-}}$(cf. 1.12).
(iii) If $h \in S$, then $T_{g} T_{h}=T_{h} T_{g}$ and $T_{\bar{\rho}} h=T_{\bar{n} g}$.
(iv) If $h \in S$, then $\mathscr{F}\left(T_{\bar{\sigma}} h\right)=\mathscr{F} g \cdot \mathscr{F} h$ (pointwise multiplication).

Proor. If $f \in S$, then it is easily seen that $T_{g} f$ is an analytic function, and we therefore concentrate on the estimation. Let $M_{1}, A_{1}, B_{1}, M_{2}, A_{2}, B_{2}$ be positive numbers such that

$$
\begin{array}{ll}
|f(x+i y)| \leqslant M_{1} \exp \left(-\pi A_{1} x^{2}+\pi B_{1} y^{2}\right) & (x \in \mathbf{R}, y \in \mathbf{R}), \\
|g(x+i y)| \leqslant M_{2} \exp \left(-\pi A_{2} x^{2}+\pi B_{2} y^{2}\right) & (x \in \mathbf{R}, y \in \mathbf{R}) .
\end{array}
$$

Using the optimal shift technique as displayed in the proof of [B], theorem 8.1, we obtain

$$
\begin{array}{r}
\left|\left(T_{g} f\right)(x+i y)\right| \leqslant \frac{M_{1} M_{2}}{\sqrt{A_{1}+A_{2}}} \exp \left(-\pi \frac{A_{1} A_{2}}{A_{1}+A_{2}} x^{2}+\pi \frac{B_{1} B_{2}}{B_{1}+B_{2}} y^{2}\right) \\
(x \in \mathbf{R}, y \in \mathbf{R})
\end{array}
$$

This proves smoothness of $T_{g} f$, and it also shows continuity of $T_{g}$. It is trivial that $T_{g}$ is linear.

Assertions (ii) and (iii) follow from elementary calculations which we shall omit, and (iv) is the well known convolution theorem for $S$.

## 3. CONVOLUTION OPERATORS AND GENERALIZED FUNCTIONS

3.1. In this section we define convolution operators $T_{F}$ with $F \in S^{*}$. We pay special attention to operators $T_{F}$ that map $S$ into $S$, and it shall be proved that such operators have an adjoint (so that we can extend
them to linear operators of $S^{*}$ according to 1.15). Furthermore we shall derive a number of useful properties of these convolution operators.
3.2. Definition. We define for $F \in S^{*}$ the mapping $T_{F}$ (cf. 1.4 and 1.12) by

$$
T_{F} f:=Y_{x \in \mathrm{C}}\left(T_{x} f, F_{-}\right) \quad(f \in S)
$$

We shall write $T_{f}$ instead of $T_{\text {emb }(f)}$ in case $f \in S^{+}$(cf. 1.2). Note that in case $f \in S$ definition 2.2 and the present one yield the same operator $T_{f}$.
3.3. theorem. If $F \in S^{*}$ and $f \in S$, then $T_{F} f$ is an analytic function.

PRoof. It is sufficient to prove analyticity of the function $Y_{x \in c}\left(T_{x} f, F_{-}\right)$ in a point $x_{0} \in \mathbf{Q}$. It is easy to prove (by using Cauchy's theorem and a continuous version of 1.8 ) that

$$
Y_{x \in c} \frac{f\left(x_{0}+x+h\right)-f\left(x_{0}+x\right)}{h} \stackrel{s}{\rightarrow} Y_{x \in c} f^{\prime}\left(x_{0}+x\right) \quad(h \rightarrow 0) .
$$

Hence, by 1.9,

$$
\lim _{h \rightarrow 0}\left(\frac{T_{x_{0}+h} f-T_{x_{0}} f}{h}, F_{-}\right)=\left(Y_{x \in \mathrm{c}} f^{\prime}\left(x_{0}+x\right), F_{-}\right),
$$

and this shows analyticity of $Y_{x \in c}\left(T_{x} t, F_{-}\right)$in $x_{0}$.
remark. We shall prove in 5.4 that $Y_{\text {sec }} \exp \left(-\pi \varepsilon z^{2}\right)\left(T_{F} f\right)(z) \in S$ for every $\varepsilon>0, F \in S^{*}, f \in S$.
3.4. definition. The class $\mathscr{C}$ is defined as the set of all generalized functions $F$ for which $T_{F}(S) \subset S$.
remark. This definition is somewhat uneasy to handle, but we shall give alternative descriptions of the class $\mathscr{C}$ later on.

### 3.5. EXAMPLES.

(i) If $f \in S$, then $\mathrm{emb}(f) \in \mathscr{C}$.
(ii) If $a \in \mathbf{Q}, F=\delta_{a}$, then $T_{F}=T_{-\bar{a}}$ (cf. 1.4(ii)), so $\delta_{a} \in \mathscr{C}$.
(iii) If $F=P \delta_{0}$, then $T_{F}=P$, so $P \delta_{0} \in \mathscr{C}$ (cf. 1.4(iii)).
(iv) If $f$ is an integrable function defined on $\mathbf{R}$ with a compact support, then emb $(f) \in \mathscr{C}$.
(v) If $P$ is a measure on $\mathbb{R}$, and if there is an $\varepsilon>0$ such that

$$
\int_{|t| \geqslant x} d P(t)=0\left(\exp \left(-\pi \varepsilon x^{2}\right)\right) \quad(x>0),
$$

then $F$, defined by

$$
(F, f):=\int_{-\infty}^{\infty} \overline{f(t)} d P(t) \quad(f \in S)
$$

(cf. 1.13), belongs to $\mathscr{C}$.
3.6. The following lemma turns out to be very useful in this section.

Lemma. If $F \in \mathscr{C}, f \in S$, then $T_{F(\alpha)} f \xrightarrow{s} T_{F} f(\alpha \downarrow 0)$.
PRoof. We first note that $T_{F}$ is a continuous linear operator: if $x \in \mathrm{C}$, then $Y_{f \in S}\left(T_{F} f\right)(x)$ is a continuous linear functional of $S$ (cf. 1.10 and 1.14).

For $\alpha>0, a \in \mathbf{C}$ we have $\left(T_{F(\alpha)} f\right)(a)=\left(N_{a} T_{a} f, F_{-}\right)$and using the formula $N_{\alpha} T_{a}=\exp \left(-\pi a^{2} \cosh \alpha \cdot \sinh \alpha\right) T_{a \cosh \alpha} R_{i a \sinh \alpha} N_{\alpha}$ (that easily follows from [B], (11.11)), we obtain

$$
\begin{aligned}
\left(T_{F(\alpha)} f\right)(a) & =\exp \left(-\pi a^{2} \cosh \alpha \cdot \sinh \alpha\right)\left(T_{a} \cosh \alpha R_{i a \sinh \alpha} N_{\alpha} f, F_{-}\right) \\
& =\exp \left(-\pi a^{2} \cosh \alpha \cdot \sinh \alpha\right)\left(T_{F}\left(R_{i a \sinh \alpha} N_{\alpha} f\right)\right)(a \cosh \alpha) .
\end{aligned}
$$

We are going to estimate $R_{i a \sinh \alpha} N_{a} f$ for $a \in \mathbf{C}, \alpha>0$. It is not hard to prove from smoothness of $f$ that there is an $M>0, A>0, B>0$ such that

$$
\left|\left(N_{\alpha} f\right)(t)\right| \leqslant M \exp \left(-\pi A(\operatorname{Re} t)^{2}+\pi B(\operatorname{Im} t)^{2}\right) \quad(t \in \mathbf{C}, \alpha>0)
$$

(This may be proved by using the optimal shift technique of the proof of [B], 8.1.) Hence, using the inequality

$$
|2 a t| \leqslant|a|^{2}+(\operatorname{Re} t)^{2}+(\operatorname{Im} t)^{2} \quad(a \in \mathbf{C}, t \in \mathbf{C})
$$

$\left|\left(R_{\text {t } a \operatorname{Binh} \alpha} N_{\alpha} f\right)(t)\right|=\left|\exp (2 \pi a t \sinh \alpha)\left(N_{\alpha} f\right)(t)\right| \leqslant$ $<M \exp \left(-\pi(A-\sinh \alpha)(\operatorname{Re} t)^{2}+\pi(B+\sinh \alpha)(\operatorname{Im} t)^{2}\right) \exp \left(\pi|a|^{2} \sinh \alpha\right)$ for every $a \in \mathbf{C}, t \in \mathbf{Q}, \alpha>0$. This shows that for sufficiently small $\alpha>0$
$\left|\left(R_{i a \sinh \alpha} N_{a} f\right)(t)\right|<M \exp \left(-\frac{\pi}{2} A(\operatorname{Re} t)^{2}+2 \pi B(\operatorname{Im} t)^{2}\right) \exp \left(\pi|a|^{2} \sinh \alpha\right)$
for every $a \in \mathbf{Q}, t \in \mathbf{C}$.
Now we use continuity of $T_{F}$. It follows from 1.14, remark that there are numbers $M_{0}>0, A_{0}>0, B_{0}>0$ such that
$\left|\left(T_{F}\left(R_{i a \sinh \alpha} N_{\alpha} f\right)\right)(a \cosh \alpha)\right| \leqslant$ $\leqslant M_{0} \exp \left(-\pi A_{0}(\operatorname{Re} a)^{2} \cosh ^{2} \alpha+\pi B_{0}(\operatorname{Im} a)^{2} \cosh ^{2} \alpha\right) \exp \left(\pi|a|^{2} \sinh \alpha\right)$
for sufficiently small $\alpha>0$ and all $a \in \mathbf{Q}$. Hence
$\left|\left(T_{F(\alpha)} f\right)(a)\right| \leqslant$
$<M_{0} \exp \left(-\pi A_{0}(\operatorname{Re} a)^{2} \cosh ^{2} \alpha+\pi B_{0}(\operatorname{Im} a)^{2} \cosh ^{2} \alpha\right) \times$
$\times \exp \left(2 \pi|a|^{2} \cosh \alpha \sinh \alpha\right)$
for sufficiently small $\alpha>0$ and all $a \in \mathbf{C}$.
It is easy to see now that there exists $\alpha_{1}>0, M_{1}>0, A_{1}>0, B_{1}>0$ such that
$0<\alpha<\alpha_{1} \Rightarrow\left|\left(T_{F(a)} f\right)(a)\right| \leqslant M_{1} \exp \left(-\pi A_{1}(\operatorname{Re} a)^{2}+\pi B_{1}(\operatorname{Im} a)^{2}\right) \quad(a \in \mathbf{Q})$.
Since $T_{F(\alpha)} f \rightarrow T_{F} f$ pointwise we easily conclude from a continuous version of 1.8 that $T_{F(\alpha)} f \stackrel{\stackrel{S}{\rightarrow}}{ } T_{F} f$.
3.7. A lot of properties of the $T_{F}$ 's with $F \in \mathscr{C}$ easily follow now.
theorem. Let $F \in \mathscr{C}$. Then $\bar{F} \in \mathscr{C}, F_{-} \in \mathscr{C}$ and $\bar{F}_{-} \in \mathscr{C}$ (cf. 1.12), and furthermore $T_{\boldsymbol{F}}$ and $T_{\bar{F}_{-}}$are adjoint operators.

Proof. We shall only prove that $\bar{F}_{-} \in \mathscr{C}$ (the other cases can be treated similarly). Let $g \in S$. Using the relation $T_{\bar{n}_{-}} g=\left(T_{h} \overline{\bar{g}_{-}}\right)$- that holds by 2.3(ii) for $h \in S$, we obtain by 3.6

$$
T_{\overline{(F(\alpha))-}} g=\overline{\left(T_{F(\alpha)} \bar{g}_{-}\right)} \xrightarrow{S}{\overline{\left(T_{F} \bar{g}_{-}\right)}-}
$$

if $\alpha \downarrow 0$. Furthermore $T_{\overline{(\bar{F}(\alpha))}} g \rightarrow T_{\bar{F}_{-}} g$ pointwise. So $T_{\overline{\boldsymbol{F}}_{-}} g=\left(\overline{T_{F} \bar{g}_{-}}\right)_{-} \in S$, and hence $\bar{F}_{-} \in \mathscr{C}$.

We further have for $f \in S, g \in S$ by 2.3 (ii) and 3.6

$$
\left(T_{F} f, g\right)=\lim _{\alpha \neq 0}\left(T_{F(\alpha)} f, g\right)=\lim _{\alpha \neq 0}\left(f, T_{\overline{(F(\alpha))}}=g\right)=\left(f, T_{\bar{F}-} g\right),
$$

so $T_{F}$ and $T_{\bar{F}_{-}}$are adjoint operators.
remark 1. According to 1.15 we can extend $T_{F}$ to a linear operator of $S^{*}$ in case $F \in \mathscr{C}$. We denote this extended operator again by $T_{F}$. The following properties are satisfied
(i) $T_{F}(\mathrm{emb}(f))=\mathrm{emb}\left(T_{F} f\right) \quad(f \in S)$,
(ii) $G_{n} \in S^{*}(n \in \mathbb{\Omega}), G_{n} \xrightarrow{s^{*}} 0 \Rightarrow T_{F} G_{n} \xrightarrow{s^{*}} 0$,
(iii) $\left(T_{F} G, g\right)=\left(G, T_{\bar{F}_{-}} g\right) \quad\left(G \in S^{*}, g \in S\right)$.
remark 2. For $F \in \mathscr{C}$ the following relations hold:

$$
\bar{T}_{F}=T_{\bar{F}},\left(T_{F}\right)_{-}=T_{F-},\left(\overline{T_{F}}\right)_{-}=T_{\bar{F}-}
$$

3.8. theorem. Let $F \in \mathscr{C}, G \in \mathscr{C}$. We have $T_{F} T_{G}=T_{G} T_{F}$.

Proof. First assume that $F \in \mathscr{C}, G \in \operatorname{emb}(S)$, and let $f \in S$. We have

$$
T_{F} T_{G} f=\lim _{\alpha \neq 0} T_{F(\alpha)} T_{G} f=\lim _{\alpha \neq 0} T_{G} T_{F(\alpha)} f=T_{G} T_{F} f
$$

(the limits are in $S$-sense by 3.6). The general case is reduced to the above one by noting that

$$
T_{F} T_{G} f=\lim _{\alpha \downarrow 0} T_{F} T_{G(\alpha)} f=\lim _{\alpha \downarrow 0} T_{G(\alpha)} T_{F} f=T_{G} T_{F} f
$$

(the limits are again in $\mathcal{S}$-sense).
3.9. Another theorem of the above type is the following one.
theorem. Let $F \in \mathscr{E}, G \in \mathscr{C}$. We have $T_{\bar{F}} G=T_{\bar{G}} F, T_{T_{\bar{P}}}=T_{F} T_{G}$.
proof. Let us first note that $T_{\bar{p}} G$ and $T_{\bar{\sigma}} F$ are well defined by 3.7, remark 1.

To show $T_{\bar{F}} G=T_{\bar{G}} F$ first assume that $F \in \mathscr{C}, G \in \mathrm{emb}(S)$. Then

$$
T_{\bar{F}} G=\lim _{\alpha+0} T_{\overline{\bar{P}(\alpha)}} G=\lim _{\alpha+0} T_{\bar{G}}(\mathrm{emb}(F(\alpha)))=T_{\bar{G}} \bar{F}
$$

(the limits are in $S^{*}$-sense). Here we used 2.3 (iii) and the fact that emb $(F(\alpha)) \xrightarrow{\mathcal{S}^{*}} F(\alpha \downarrow 0)$. The general case can be reduced to this one by noting that

$$
T_{\bar{F}} G=\lim _{\alpha \neq 0} T_{\bar{F}}(\operatorname{emb}(G(\alpha)))=\lim _{\alpha \neq 0} T_{\overline{G(\alpha)}} F=T_{\bar{G}} F
$$

(the limits are again in $S^{*}$-sense), where the latter equality follows from

$$
\left(T_{\bar{\sigma} \boldsymbol{\alpha}} F, f\right)=\left(F, T_{(G(\alpha))_{-}} f\right) \rightarrow\left(F, T_{G_{-}} f\right)=\left(T_{\bar{\sigma}} F, f\right) \quad(\alpha \downarrow 0)
$$

holding for $f \in S$ (ef. 1.9).
Now we show $T_{T_{\boldsymbol{F}^{G}}}=T_{F} T_{G}$, and we use therefore the relation

$$
T_{a} T_{K}=T_{K} T_{a} \quad(a \in \mathrm{Q}, K \in \mathscr{C}),
$$

that follows at once from the definition of $\boldsymbol{T}_{\boldsymbol{K}}$. We easily see from 3.7, remark 2 that ( $\left.T_{\bar{F}} G\right)_{-}=T_{\bar{F}_{-}} G_{-}$, so

$$
\begin{aligned}
& \left(T_{T_{\bar{F}} G} f\right)(x)=\left(T_{x} f,\left(T_{\bar{F}} G\right)-\right)=\left(T_{x} f, T_{\bar{F}_{-}} G_{-}\right) \\
& =\left(T_{F} T_{x} f, G_{-}\right)=\left(T_{x} T_{F} f, G_{-}\right)=\left(T_{G}\left(T_{F} f\right)\right)(x)
\end{aligned}
$$

for $t \in S, x \in \mathrm{Q}$. Hence $T_{T_{\bar{F}} G}=T_{G} T_{\boldsymbol{F}}$.
remark 1. The preceding theorem states (among other things) that $T_{F}$ maps $\mathscr{C}$ into $\mathscr{C}$ in case $F \in \mathscr{C}$. For if $G \in \mathscr{C}$ then $T_{T_{\boldsymbol{F}}}=T_{\bar{F}} T_{G}$, and $T_{\bar{F}} T_{G}$ maps $S$ into $S$, hence $T_{F} G \in \mathscr{C}$.
remark 2. Let $F \in S^{*}$. We mention the possibility to extend the linear mapping $T_{F}$ (which maps $S$ into the class of all entire functions) to a linear mapping of the space $\mathscr{C}$ into $S^{*}$. This is done by putting $T_{F} f:=T_{i} \bar{F}$ for $f \in \mathscr{C}$. In case $\bar{F} \in \mathscr{C}$ this definition coincides with the one given in 3.7 , remark 1.
remark 3. In 3.7 , remark 1 we have extended the operator $T_{F}$ to a linear operator of $S^{*}$ (in case $F \in \mathscr{C}$ ). If $F \in S$ however, there is a more direct way to define this operator on $S^{*}$, namely by putting $T_{F} G=T_{\bar{G}} \bar{F}$ for $G \in S^{*}$ (this $T_{\bar{\sigma}} \bar{F}$ has been defined in 3.2, and is an entire function). It is not obvious yet that this alternative definition yields the same operator, i.e. that emb ( $T_{\bar{a}} \bar{F}$ ) equals $T_{F} G$ (as it is defined in 3.7, remark 1) for $G \in S^{*}$. The proof is pretty hard, and will be postponed until 5.5.
remari 4. Let $F \in \mathscr{C}, G \in S^{*}$. We can define the convolution $F \star G$ of $F$ and $G$ by putting $F \star G=T_{F} G$. If we restrict ourselves to $F \in \mathscr{C}$, $G \in \mathscr{C}$, then this convolution product has the usual properties. We mention commutativity (follows from the preceding theorem), and associativity:
if $H \in S^{*}$, then $F \star(G \star H)=(F \star G) \star H$, for

$$
\begin{aligned}
& F \star(G \star H)=T_{\bar{P}}(G \star H)=T_{\bar{F}} T_{\bar{G}} H= \\
& =T_{T_{F^{\rho}}} \bar{G} H=T_{\bar{P} \star G} H=(F \star G) \star H .
\end{aligned}
$$

We mention furthermore Titchmarsh's theorem for $\mathscr{C}$ : if $F \in \mathscr{C}, G \in \mathscr{C}$, then $F \star G=0 \Rightarrow F=0 \vee G=0$. This will be proved in the next section.
3.10. We consider an alternative description of the class $\mathscr{C}$ which is related to Weyl correspondence (cf. [B], 26). If $F \in S^{*}$, then we can define for every $g \in S$ the continuous linear functional (cf. 1.10 and 1.18)

$$
Y_{f \in S}\left(f \otimes \bar{g}, Z_{U}(E \otimes \check{F})\right)
$$

of $S$ ( $E$ is the function emb ( $\left.Y_{l} 1\right)$ ). For every $g \in S$ we can find (by l.13) exactly one $K_{F} g \in S^{*}$ such that

$$
\left(f \otimes \bar{g}, Z_{U}(E \otimes \bar{F})\right)=\left(f, K_{F} g\right) \quad(f \in S)
$$

This $K_{F}$ is a linear mapping of $S$ into $S^{*}$.
If $F \in \mathscr{C}, g \in S$, then we can prove that $K_{F} g \in \mathrm{emb}(S)$. It suffices therefore to show that $K_{F} g=\operatorname{emb}\left(T_{G} g\right)$, where $G$ is the element of $S^{*}$ that satisfies $(G, f)=\left(F, Y_{x} / 2 f(x / 2)\right)$ for $f \in S$ (cf. 1.13; note that $G \in \mathscr{C}$ ). This equation holds in case $F \in \mathrm{emb}(S)$, and the gencral case can be handled by using $T_{G(\alpha)} g \xrightarrow{g} T_{G} g, K_{F(\alpha) g} \xrightarrow{\mathcal{S}^{*}} K_{F} g$ if $\alpha \downarrow 0$. The converse of the above statement is also true, i.e. if $K_{F} g \in \operatorname{emb}(S)$ for every $g \in S$, then $F \in \mathscr{C}$. We shall prove this in 5.6.
3.11. One of the main features of the convolution operators is the fact that they commute with the time shifts $T_{a}(a \in \mathbf{C})$. That this fact actually characterizes the convolution operators is expressed in the following theorem.
theorem. Let $T$ be a continuous linear operator of $S$ that satisfies $T T_{a}=T_{a} T$ for every $a \in \mathbf{R}$. Then there is a $G \in \mathscr{C}$ such that $T=T_{G}$.

PRoof. We note that $Y_{f \in S}(T f)(0)$ is a continuous linear functional of $S$. This means that there exists an $H \in S^{*}$ such that

$$
(T f)(0)=(f, H) \quad(f \in S)
$$

Now we have for every $f \in S, x \in \mathbf{Q}$

$$
(T f)(x)=\left(T_{x} T f\right)(0)=\left(T T_{x} f\right)(0)=\left(T_{x} f, H\right)
$$

This proves the theorem with $G=H_{-}$.
corollary. Let $T$ be a continuous linear operator of $S$ that commutes with all time shifts $T_{a}(a \in \mathbf{R})$ and all frequency shifts $R_{b}(b \in \mathbf{Q})$. Then there is a $c \in \mathbf{Q}$ such that $T=c I$. This is proved as follows. We infer from
3.11 that there is an $H \in \mathscr{C}$ such that $(T f)(x)=\left(T_{x} f, H\right)(f \in S, x \in \mathbf{C})$; we have $H=T^{*} \delta_{0}$. Since $T$, and hence $T^{*}$ commutes with all frequency shifts we have $R_{b} T^{*} \delta_{0}=T^{*} R_{b} \delta_{0}=T^{*} \delta_{0}(b \in \mathbf{R})$. So, by a theorem that will be proved in 4.11, remark, $T^{*} \delta_{0}$ is a multiple of $\delta_{0}$. Hence $T$ is a multiple of $I$.

REmARK. Let $T$ be a continuous linear operator of $S$ satisfying $T P=P T$ (cf. 1.4(iii)). It may be proved from 3.11 that there is a $G \in \mathscr{C}$ with $T=T_{G}$.

## 4. FOURIER TRANSFORM AND GENERALIZED OONVOLUTION OPERATORS

4.1. This section is devoted to the Fourier transform in its relation to convolution theory. We shall generalize the convolution theorem, and we shall give a characterization of the class $\mathscr{C}$ in terms of Fourier transforms. Some remarks are made on the equation $T_{f} F=0$ with $f \in \mathscr{C}, F \in S^{*}$.
4.2. Definition. Let $h$ be a mapping of $\mathbf{Q}$ into Q . We define the multiplication operator $M_{\boldsymbol{h}}$ by

$$
M_{h} f:=Y_{z \in c} h(z) f(z) \quad(f \in S)
$$

We also write $h \cdot f$ instead of $M_{h} f$.
4.3. Lemma. If $h: \mathbf{Q} \rightarrow \mathbf{Q}$ satisfies $V_{\in>0}\left[Y_{z \in c} h(z) \exp \left(-\pi \varepsilon z^{2}\right) \in S\right]$, then $M_{h}$ is a continuous linear operator of $S$ with an adjoint, viz. $M_{\bar{n}}$.

PROOF. Almost trivial.
remark. The $M_{h}$ of the above lemma can be extended in the familiar way to a continuous linear operator of $S^{*}$, which is again denoted by $M_{h}$. We shall also write $h \cdot F$ instead of $M_{h} F$ if $F \in S^{*}$.
4.4. definition. Let $\mathscr{M}$ be the class of all generalized functions $F$ for which there exists an analytic $g$ satisfying $\forall_{\leqslant>0}\left[Y_{x \in c} g(z) \exp \left(-\pi \varepsilon z^{2}\right) \in S\right]$ such that $F=\mathrm{emb}(g)$ (cf. 1.6(i)). On $\mathscr{M}$ we define the mapping emb ${ }^{-1}$ by putting $\mathrm{emb}^{-1}(F)=g$ if $F \in \mathscr{M}, F=\mathrm{emb}(g)$, where $g$ satisfies the above description (note that such a $g$ is unique, hence the mapping emb ${ }^{-1}$ is well defined on $\mathscr{M}$ ).
4.5. The following characterization of $\mathscr{C}$ is very useful.

THEOREM. $\quad F \in \mathscr{C} \Leftrightarrow \mathscr{F} F \in \mathscr{M}$.
proof. Let $F \in \mathscr{C}$. We have for every $f \in S$

$$
(\mathscr{F} F)(\alpha) \cdot \mathscr{F} f=(\mathscr{F} F(\alpha)) \cdot \mathscr{F} f=\mathscr{F}\left(T_{\bar{F}(\alpha)} f\right) \xrightarrow{S} \mathscr{F}\left(T_{\bar{F}} f\right)
$$

if $\alpha \downarrow 0$ by [B], Theorem 9.1, 2.3(iv) and lemma 3.6. It easily follows that $g:=Y_{x \in C} \lim _{\alpha+0}((\mathscr{F} F)(\alpha))(z)$ is an analytic function that satisfies

$$
Y_{z \in C} g(z) \exp \left(-\pi \varepsilon z^{2}\right) \in S \text { for } \varepsilon>0
$$

Furthermore $\mathscr{F} F=\mathrm{emb}(g)$ since we have for every $h \in S$

$$
\begin{aligned}
& (\mathscr{F} F, h)=\lim _{\alpha \neq 0}((\mathscr{F} F)(\alpha), h)= \\
& =\lim _{\alpha \neq 0} \int_{-\infty}^{\infty}((\mathscr{F} F)(\alpha))(t) \overline{h(t)} d t=\int_{-\infty}^{\infty} g(t) \overline{h(t)} d t .
\end{aligned}
$$

Hence $\mathscr{F} F \in \mathscr{M}$.
Now assume that $\mathscr{F} F \in \mathscr{M}$. It suffices to show that for every $f \in S$ the function $Y_{z \in \mathrm{C}}\left(T_{z} f, \bar{F}_{-}\right) \in S$. Note therefore that for every $z \in \mathbf{C}$

$$
\lim _{\alpha \neq 0}\left(T_{z} f, \overline{\left.F_{-}(\alpha)\right)}=\left(T_{z} f, \overline{F_{-}}\right),\right.
$$

and that the proof will be complete if we can show that this limit is achieved in $S$-sense.

We have by $2.3(\mathrm{iv})$ for every $\alpha>0$

$$
\mathscr{F}\left(T_{\mathscr{F}(\alpha)} f\right)=(\mathscr{F} F)(\alpha) \cdot \mathscr{F} f .
$$

Now let $M>0, A>0, B>0$ be such that

$$
|(\mathscr{F} f)(x+i y)| \leqslant M \exp \left(-\pi A x^{2}+\pi B y^{2}\right)
$$

for every $x \in \mathbf{R}, y \in \mathbf{R}$. Since $\mathscr{F} F \in \mathscr{M}$, we infer the existence of a $g$ that satisfies $V_{\epsilon>0}\left[Y_{z \in \mathcal{C}} g(z) \exp \left(-\pi \varepsilon z^{2}\right) \in S\right]$ such that $F=\operatorname{emb}(g)$. This means that there exists an $M_{1}>0, B_{1}>0$ such that

$$
|g(x+i y)| \leqslant M_{1} \exp \left(\frac{1}{2} \pi A x^{2}+\pi B_{1} y^{2}\right)
$$

for every $x \in \mathbf{R}, y \in \mathbf{R}$. It is not hard to show that there are numbers $M_{2}>0, B_{2}>0, \alpha_{0}>0$ such that

$$
0<\alpha<\alpha_{0} \Rightarrow\left|\left(N_{\alpha} g\right)(x+i y)\right|<M_{2} \exp \left(\frac{1}{2} \pi A x^{2}+\pi B_{2} y^{2}\right)
$$

for every $x \in \mathbf{R}, y \in \mathbf{R}$. Since $N_{a} g=(\mathscr{F} F)(\alpha)$ for every $\alpha>0$, we see that $(\mathscr{F} F)(\alpha) f \xrightarrow{S} g \cdot f$ if $\alpha \downarrow 0$ (here we have used a continuous version of 1.8 ), so $\mathscr{F}\left(T_{\overline{F(\alpha)}} f\right) \xrightarrow{s} g \cdot \mathscr{F} f$, and hence $T_{\bar{F}(\alpha)} \stackrel{S}{\rightarrow} \mathscr{F}^{*}(g \cdot \mathscr{F} f)$ if $\alpha \downarrow 0$ (cf. 1.4(i)). This shows that $T_{\bar{F}} f=\mathscr{F} *(g \cdot \mathscr{F} f)$, and hence that $T_{F} f \in S$.
corollary. If $F \in \mathscr{C}, f \in S$, then $\mathscr{F}\left(T_{\bar{P}} f\right)=\operatorname{emb}^{-1}(\mathscr{F} F) \cdot \mathscr{F} f$. This follows easily from the second part of the proof of the above theorem.

### 4.6. EXAMPLES

(i) Let $F:=Y_{z \in \mathbb{C}} e^{\pi i \hbar^{2}}$. It is not hard to check that $\mathscr{F} F$ is the embedding of $Y_{z \in C}(-i)^{-\frac{1}{2}} e^{-\pi z^{2}}$ (principal root), and it follows that $F \in \mathscr{C}$.
(ii) Let $h_{\tau}$ be the function defined by $h_{\tau}:=1 / 2 \tau \chi_{(-\tau, \tau)}$. Its Fourier trans-
form is given by

$$
Y_{\lambda} \frac{\sin 2 \pi \lambda \tau}{2 \pi \lambda \tau}
$$

hence emb $\left(h_{\tau}\right) \in \mathscr{C}$.
(iii) Let $\left(d_{n}\right)_{n \in Z}$ be a complex sequence that satisfies $\left|d_{n}\right|=0\left(e^{-\mathrm{m}^{2}}\right)(n \in Z)$ for some $\varepsilon>0$, and let $F:=\sum_{n--\infty}^{\infty} d_{n} \delta_{n}$ (cf. [B], 27.24.2(ii)). Then $\mathscr{F} F$ is the embedding of the analytic function $Y_{z} \sum_{n-\infty}^{\infty} d_{n} e^{-2 \pi n n s}$, and it is not hard to show that $F \in \mathscr{C}$.

## 4.7. тнеовем. If $F \in \mathscr{C}, G \in S^{*}$, then $\mathscr{F}\left(T_{\bar{\jmath}} G\right)=\mathrm{emb}^{-1}(\mathscr{F} F) \cdot \mathscr{F} G$.

proor. The case with $G \in \mathrm{emb}(S)$ follows from 4.5, corollary, and the general case is deduced from this one by noting that

$$
\begin{aligned}
\mathscr{F}\left(T_{\bar{F}} G\right) & =\lim _{\alpha+0} \mathscr{F}\left(T_{\bar{F}} G(\alpha)\right)= \\
& =\lim _{\alpha \neq 0} \mathrm{emb}^{-1}(\mathscr{F} F) \cdot \mathrm{emb}((\mathscr{F} G)(\alpha))=\mathrm{emb}^{-1}(\mathscr{F} F) \cdot \mathscr{F} G,
\end{aligned}
$$

where the limit is achieved in $S^{*}$-sense.
4.8. theorem. If $F \in S^{*}, \mathscr{F} F \in \operatorname{emb}\left(S^{+}\right), Q \in \mathscr{C}$, and if $T_{\bar{G}} F=0$, then $F=0$ or $G=0$.

Proof. By 4.7 we have $\mathrm{emb}^{-1}(\mathscr{F} G) \cdot \mathscr{F} F=0$. Write $g=\mathrm{emb}^{-1}(\mathscr{F} G)$, and let $f \in S^{+}$be such that emb $(f)=\mathscr{F} F$. Then $g \cdot \mathscr{F} F=$ emb $(g \cdot f)$, for we have for $h \in S$

$$
\begin{aligned}
& (g \cdot \mathscr{F} F, h)=(\mathscr{F} F, \bar{g} \cdot h)=(\mathrm{emb}(f), \tilde{g} \cdot h)= \\
& =\int_{-\infty}^{\infty} f(t) \overline{\overline{g(t)} h(t)} d t=\int_{-\infty}^{\infty} g(t) f(t) \overline{h(t)} d t=(\mathrm{emb}(g \cdot f), h) .
\end{aligned}
$$

It follows from 1.6(i) that $g \cdot f=0$ (a.e.). We conclude by analyticity of $g$ that $g=0$ or that $f=0$ (a.e.), and so $G=0$ or $F=0$.
4.9. We enter somewhat further into questions of the type: if $f \in \mathscr{C}$, $F \in S^{*}$ and $T_{f} F=0$, then what can we tell about $F$. As we see from 4.7 such questions can be translated into ( $g=\mathscr{F} f, G=\mathscr{F} F$ ): if $g \in \mathscr{M}, G \in S^{*}$, and if $\mathrm{emb}^{-1}(\mathrm{~g}) \cdot G=0$, then what can we tell about $G$. In [S] these problems have been solved for the space $K^{\prime}$ (dual space of $K$ ), but we cannot use the techniques employed there, since we have (by lack of non-trivial elements of $S$ of compact support) not the occasion to consider the elements of $S^{*}$ locally, as it is done in [S] for the elements of $K^{\prime}$ (cf. [S], Ch. V, § 4).

We shall prove here some simple results in this direction, and we shall mention some further theorems without proof.
4.10. THEOREM. Let $g \in \mathscr{M}$, and assume that $\mathrm{emb}^{-1}(g)$ has no zeros. If $G \in S^{*}$ and $\mathrm{emb}^{-1}(g) \cdot G=0$, then $G=0$.

Proor. Put $h:=\operatorname{emb}^{-1}(g)$. We infer from the fact that

$$
Y_{z} h(z) \exp \left(-\pi \varepsilon z^{2}\right) \in S
$$

for every $\varepsilon>0$, and the fact that $h$ has no zeros, that there are complex numbers $a_{0}, a_{1}$ and $a_{2}$ with $\operatorname{Re}\left(a_{2}\right)<0$ such that

$$
h(z)=\exp \left(a_{0}+a_{1} z+a_{2} z^{2}\right) \quad(z \in \mathbf{C})
$$

If $\alpha>0$ is such that $\operatorname{coth} \alpha>\left|a_{2}\right|$, and if we denote for $t \in \mathbf{C}$

$$
k_{t}:=Y_{s \in \mathrm{C}}(\sinh \alpha)^{\frac{1}{2}} \exp \left(\frac{-\pi}{\sinh \alpha}\left(\left(z^{2}+t^{2}\right) \cosh \alpha-2 z t\right)\right) \overline{h^{-1}(\bar{z})},
$$

then we have $k_{t} \in S, \boldsymbol{h} \cdot k_{t}=\delta_{\alpha}(t)$ (cf. 1.6(ii)). Hence for $t \in \mathbf{Q}$

$$
0=\left(h \cdot G, k_{t}\right)=\left(G, h \cdot k_{t}\right)=\left(G, \delta_{a}(t)\right)=G_{a}(\bar{t})
$$

(cf. [B], 27.18), so $G_{\infty}=0$, and therefore $G=0$ by 1.5.
4.11. theorem. If $G \in S^{*}, Q G=0$ (cf. $\left.1.4(i i)\right)$, then there is a $c \in \mathbb{Q}$ such that $G=c \delta_{0}$. This $c$ is uniquely determined by $G$.
proof. Let $\alpha>0$ be fixed. We infer from [B], (11.9) and (11.11) that $N_{\alpha} Q=\cosh \alpha Q N_{\alpha}+i \sinh \propto P N_{\alpha}$,
so we find

$$
\cosh \propto Q G_{\alpha}+i \sinh \propto P G_{\alpha}=0
$$

The solution of this differential equation is given by

$$
G_{\alpha}=Y_{z \in C} G_{\alpha}(0) \exp \left(-\pi z^{2} \operatorname{coth} \alpha\right)=G_{\alpha}(0)(\sinh \alpha)^{\frac{1}{1}}\left(\delta_{0}\right)_{\alpha} .
$$

Hence, with $c:=G_{\alpha}(0)(\sinh \alpha)^{\frac{1}{2}},\left(G-c \delta_{0}\right)_{\alpha}=G_{\alpha}-c\left(\delta_{0}\right)_{\alpha}=0$. It follows from 1.5 that $G=c \delta_{0}$.

Uniqueness of $c$ is trivial.
remark. It follows easily from the above theorem that an $F \in S^{*}$ that satisfies $T_{a} F=F(a \in \mathbf{R})$ is the embedding of a constant function. For we have $P F=\lim _{h \rightarrow 0} 1 / 2 \pi i h\left(T_{h} F-F\right)=0$ (the limit is in $S^{*}$-sense), hence $Q \mathscr{F} F=\mathscr{F} P F=0$. This means that $\mathscr{F} F=c \delta_{0}$ with some $c \in \mathbf{Q}$, and hence $F=\mathrm{emb}$ ( $Y_{\operatorname{lec}} c$ ). Also, if $F \in S^{*}, R_{b} F=F(b \in \mathbf{R})$, then $F=c \delta_{0}$ for some $c \in \mathbf{G}$.
4.12. Theorem 4.11 can be generalized as follows. Let

$$
n \in \mathbf{\Omega}, a_{1} \in \mathrm{Q}, \ldots, a_{n} \in \mathrm{Q}, v_{1} \in \mathbf{\Omega}, \ldots, v_{n} \in \mathbf{\Omega}
$$

and let $h:=Y_{z \in \mathrm{C}} \prod_{k=1}^{n}\left(z-a_{k}\right)^{y_{k}}$. If $G \in S^{*}$ satisfies $h \cdot G=0$, then there are complex numbers $d_{k l}\left(l=0, \ldots, \nu_{k}-1 ; k=1, \ldots, n\right)$ such that

$$
F=\sum_{k=1}^{n} \sum_{l=0}^{n_{k}-1} d_{k l} P^{l} \delta_{a_{k}}
$$

The numbers $d_{k l}$ are uniquely determined by $F$.
We still can go further. Assume that $h \in \mathrm{emb}^{-1}(\mathscr{M})$, and let $h$ have its zeros in $a_{1}, a_{2}, \ldots$ with multiplicities $\nu_{1}, \nu_{2}, \ldots$ Let $V_{n}$ be the set of all elements $F \in S^{*}$ of the form ( $\star$ ), and let $V$ be the union of all $V_{n}$ 's. We assume that $\sum_{k=1 .\left|a_{k}\right| \neq 0}^{\infty} \nu_{k} /\left|a_{k}\right|^{2}<\infty$. Then every $F \in S^{*}$ that satisfies $h \cdot F=0$ is $S^{*}$-limit of a sequence in $V$, and every $F \in S^{*}$ that is $S^{*}$-limit of elements of $V$ satisfies $h \cdot F=0$.

We note that every element $h$ of $\mathrm{emb}^{-1}(\mathscr{M})$ has order $\leqslant 2$, and this means that the limit exponent of $h$ does not exceed 2 (cf. [Bi], Ch. VI, § 4): if $a_{1}, a_{2}, \ldots$ and $\nu_{1}, \nu_{2}, \ldots$ are as in the above, then $\left.\sum_{k=1,\left|a_{k}\right| \neq 0}^{\infty} \nu_{k}| | a_{k}\right|^{2+s}<\infty$ for every $\varepsilon>0$. In case that the order of $h$ is less than 2, we have $\sum_{k-1 .\left|a_{k}\right| \neq 0}^{\infty} v_{k} /\left|a_{k}\right|^{2}<\infty$, so the above theorem applies to $h$. We do not know how to handle the general case in which functions $h$ like Yzc $Y_{\text {( }} \exp$ $\left(\pi i z^{2}\right)-1$ ) occur (here $\left.\sum_{k=1,\left|a_{k}\right| \neq 0}^{\infty} \nu_{k}| | a_{k}\right|^{2}=\infty$ ).

## 5. SOME FURTHER REMARKS ON CONVOLUTION THEORY

5.1. In this section we give some further theorems and definitions about the class $\mathscr{C}$. We shall also pay attention to convergence in $\mathscr{C}$, and to convolution operators in $\mathbb{S}^{n}(n \in \mathbb{1})$.
5.2. We are going to show that $g \cdot G \in \mathscr{C}$ if $g \in S, G \in S^{*}$. This means that $T_{\bar{j}} F \in \mathscr{M}$ if $f \in S, F \in S^{*}$ (cf. 4.5 and 4.7), and it will turn out that $T_{\bar{f}} F=\mathrm{emb}\left(T_{\bar{F}} f\right.$ ) (in particular $T_{\bar{F}} f \in S^{+}$). The following lemma is useful in the proofs of the above statements.

Lemma. Let $f \in S, g \in \operatorname{emb}^{-1}(\mathscr{M})$, and let $M_{1}>0, A_{1}>0, B_{1}>0, M_{2}>0$, $A_{2} \geqslant 0, B_{2}>0$ be such that

$$
\begin{aligned}
& |f(z)| \leqslant M_{1} \exp \left(-\pi A_{1}(\operatorname{Re} z)^{2}+\pi B_{1}(\operatorname{Im} z)^{2}\right), \\
& |g(z)| \leqslant M_{2} \exp \left(-\pi A_{2}(\operatorname{Re} z)^{2}+\pi B_{2}(\operatorname{Im} z)^{2}\right)
\end{aligned}
$$

for every $z \in \mathbf{C}$. To every $\varepsilon$ with $0<\varepsilon<A_{1}+A_{2}$ there exists a $C>0$ and a $\beta>0$ (only depending on $B_{1}, B_{2}$ and $\varepsilon$ ) such that for every $F \in S^{*}, y \in \mathbf{Q}$ (|| || denotes inner product norm in $S$ )
$\left|\left(g \cdot T_{y} f, F\right)\right| \leqslant M_{1} M_{2} C\|F(\beta)\| \exp \left(-\pi A_{1} \frac{A_{2}-\varepsilon}{A_{1}+A_{2}-\varepsilon}(\operatorname{Re} y)^{2}+2 \pi B_{1}(\operatorname{Im} y)^{2}\right)$.
proof. We have for every $y \in \mathbf{Q}, z \in \mathbf{Q}$

$$
\left|g(z)\left(T_{y} f\right)(z)\right| \leqslant M_{1} M_{2} \exp (\pi P(z, y))
$$

where $P$ is defined by

$$
\begin{aligned}
& P(z, y)=-\left(A_{1}+A_{2}\right)(\operatorname{Re} z)^{2}+\left(B_{1}+B_{2}\right)(\operatorname{Im} z)^{2}+2 A_{1} \mid \operatorname{Re} z \operatorname{Re} y \\
& +2 B_{1}|\operatorname{Im} z \operatorname{Im} y|-A_{1}(\operatorname{Re} y)^{2}+B_{1}(\operatorname{Im} y)^{2} \quad(z \in \mathbf{Q}, y \in \mathbf{Q}) .
\end{aligned}
$$

Let $\varepsilon$ satisfy $0<\varepsilon<A_{1}+A_{2}$. Applying the inequality $2|a b|<\gamma a^{2}+\gamma^{-1} b^{2}$ (valid for $a \in \mathbf{R}, b \in \mathbf{R}, \gamma>0$ ) to $2|\operatorname{Re} z \operatorname{Re} y|$ and $2|\operatorname{Im} z \operatorname{Im} y|$ with $\gamma=1+\left(A_{2}-\varepsilon\right) A_{1}^{-1}$ and $\gamma=1$ respectively, we obtain
$P(z, y) \leqslant-\varepsilon(\operatorname{Re} z)^{2}+\left(2 B_{1}+B_{2}\right)(\operatorname{Im} z)^{2}-A_{1} \frac{A_{2}-\varepsilon}{A_{1}+A_{2}-\varepsilon}(\operatorname{Re} y)^{2}+2 B_{1}(\operatorname{Im} y)^{2}$
for $y \in \mathbf{Q}, z \in \mathbf{Q}$. Now put for every $y \in \mathbf{Q}$

$$
h_{y}:=Y_{z \in \mathrm{C}} g(z)\left(T_{y} f\right)(z) \exp \left(\pi A_{1} \frac{A_{2}-\varepsilon}{A_{1}+A_{2}-\varepsilon}(\operatorname{Re} y)^{2}-2 \pi B_{1}(\operatorname{Im} y)^{2}\right)
$$

Then we have $h_{y} \in S$, and

$$
\left|h_{y}(z)\right| \leqslant M_{1} M_{2} \exp \left(-\pi \varepsilon(\operatorname{Re} z)^{2}+\pi\left(2 B_{1}+B_{2}\right)(\operatorname{Im} z)^{2}\right) \quad(z \in \mathrm{Q}) .
$$

It follows from 1.3 (ii) that we can find a $C>0$ and a $\beta>0$ (only depending on $\varepsilon$ and $2 B_{1}+B_{2}$ ) such that for every $y \in \mathrm{Q}$ there exists an $l_{y} \in S$ with $h_{y}=N_{\beta} l_{y},\left\|l_{y}\right\| \leqslant M_{1} M_{2} C$. So we have for every $y \in \mathrm{C}$
$\left|\left(g \cdot T_{y} f, F\right)\right| \leqslant M_{1} M_{2} C\|F(\beta)\| \exp \left(-\pi A_{1} \frac{A_{2}-\varepsilon}{A_{1}+A_{2}-\varepsilon}(\operatorname{Re} y)^{2}+2 \pi B_{1}(\operatorname{Im} y)^{2}\right)$
if $F \in S^{*}$ (here we apply

$$
\left.\left|\left(h_{y}, F\right)\right|=\left|\left(N_{\beta} l_{y}, F\right)\right|=\left|\left(l_{y}, F(\beta)\right)\right| \leqslant M_{1} M_{2} C\|F(\beta)\|\right)
$$

5.3. theorem. If $g \in S, G \in S^{*}$, then $g \cdot G \in \mathscr{C}$.
proor. Let $f \in S$. Then $T_{g} \cdot G f=Y_{v \in c}\left(\bar{g} \cdot T_{y} f, G_{-}\right)$. Analyticity of $T_{g} \cdot G f$ follows from theorem 3.3, and it follows easily from lemma 5.2 that $T_{g} \cdot a f \in S$.
5.4. theorem. If $f \in S, F \in S^{*}$, then emb $\left(T_{\bar{F}} f\right) \in \mathscr{M}$.

Proor. Take $g=Y_{z \in c} 1$ and $\bar{F}_{-}($instead of $F)$ in 5.2 to conclude that $T_{\bar{F}} \dagger \in S^{+}$. It further follows from lemma 5.2 and theorem 3.3 that $Y_{z \in C} \exp \left(-\pi \varepsilon z^{2}\right)\left(T_{\bar{F}} f\right)(z) \in S$ for every $\varepsilon>0$. Hence emb $\left(T_{\bar{F}} f\right) \in \mathscr{M}$.
5.5. We can prove now the statement in 3.9, remark 3.
theorem. If $F \in S^{*}, f \in S$ then $T_{\bar{j}} F=\mathrm{emb}\left(T_{\bar{F}}\right)$.
Proof. We first prove the formula with $F \in \mathscr{C}$. We have in that case
by theorem 3.9, theorem 3.7 and 3.7, remark 1 for every $g \in S$

$$
\begin{aligned}
& \left(T_{\bar{f}} F, g\right)=\left(T_{\bar{F}}(\mathrm{emb}(f)), g\right)=\left(\mathrm{emb}(f), T_{F_{-}} g\right)= \\
& =\left(f, T_{F_{-}} g\right)=\left(T_{\bar{F}} f, g\right)=\left(\mathrm{emb}\left(T_{\bar{f}} f\right), g\right)
\end{aligned}
$$

hence $T_{\bar{j}} F=\operatorname{emb}\left(T_{\bar{r}} f\right)$ by the uniqueness part of theorem 1.13.
The general case is reduced to the above one as follows. Denote $h_{d}:=Y_{\text {rec }} \exp \left(-\pi \delta z^{2}\right)$, and define $F_{\delta}:=h_{\delta} \cdot F$ for $\delta>0$. Now $F_{d} \in \mathscr{C}$ by 5.3, and we have $T_{\bar{j}} F_{\delta}=\mathrm{emb}\left(T_{\bar{F}_{d}}\right)$ for $\delta>0$. The proof will be complete if we can show that $T_{\bar{f}} F_{\delta} \xrightarrow{s^{*}} T_{\bar{f}} F, \mathrm{emb}\left(T_{\bar{P}_{\delta}} f\right) \xrightarrow{s^{*}}$ emb $\left(T_{\bar{F}} f\right)$ if $\delta \downarrow 0$. We note therefore that $F_{\delta} \xrightarrow{s^{*}} F$ if $\delta \downarrow 0$, so, by 3.7 remark 1, we have $T_{j} F_{o} \xrightarrow{s^{*}} T_{j} F^{\prime}$ if $\delta \downarrow 0$. Furthermore we have $\left(T_{\bar{F}_{\delta}} f\right)(y) \rightarrow\left(T_{\bar{F}} f\right)(y)$ if $\delta \downarrow 0$ for every $y \in \mathbf{Q}$, and it is easily proved now with the aid of lemma 5.2 and 1.9 that $\operatorname{emb}\left(T_{\bar{F}_{\delta}} f\right) \xrightarrow{s^{*}} \operatorname{emb}\left(T_{F} f\right)$ if $\delta \downarrow 0$.
remark. Note that not every element of $\mathscr{C}$ can be obtained as the product of a $g \in S$ and a $G \in S^{*}$ (cf. theorem 5.3), and so not every element of $\mathscr{M}$ can be obtained as $T_{j} F$ with some $f \in S, F \in S^{*}$.

EXAMPLE. $k:=\operatorname{emb}\left(Y_{z \in C} e^{-x^{2}}\right) \in \mathscr{C}$ cannot be of the form $g \cdot G$ with some $g \in S, G \in S^{*}$. For if so, then we consider the sequence $\left(f_{n}\right)_{n \in N}$ defined by $f_{n}:=Y_{z \in C} e^{\pi\left(2^{2}-\pi(z+n)^{2}\right.}(n \in \mathbb{\Omega})$. Now we have $f_{n} \cdot \bar{g} \xrightarrow{s} 0$, but $\left(f_{n} \cdot \bar{g}, G\right)=$ $=\left(f_{n}, g \cdot G\right)=\left(f_{n}, k\right)=1 \quad(n \in \mathbb{R})$.
5.6. We are going to prove the statement at the end of 3.10. With the notation used there we have to show that $F \in \mathscr{C}$ in case $K_{F} g \in \mathrm{emb}(S)$ for every $g \in S$. Let $f \in S, g \in S$. We have $\left(K_{F} g, f\right)=\left(E \otimes \bar{F}, Z_{V}(f \otimes \bar{g})\right.$ ) by definition and 1.18, and it is not hard to see from [B], (21.4) that $\left(E \otimes \bar{F}, Z_{V}(f \otimes \bar{g})\right)=\left(\bar{G}, T_{g_{-}} f\right)$, where $G$ is the generalized function that satisfies $(G, h)=\left(F, Y_{x} / 2 h(x / 2)\right)$ for $h \in S$ (cf. 1.13). Hence, by 3.7, remark 1 and 5.5,

$$
\left(K_{F} g, f\right)=\left(\bar{G}, T_{g_{-}} f\right)=\left(T_{\bar{\jmath}} \bar{G}, f\right)=\left(\operatorname{emb}\left(T_{G} g\right), f\right)
$$

This means that $K_{F} g=\mathrm{emb}\left(T_{G} g\right.$ ), and by analyticity of $T_{G} g$ we conclude that $T_{G} g \in S$. Hence $G \in \mathscr{C}$, and so $F \in \mathscr{C}$.
5.7. We make some remarks on convergence of convolution operators.
definition. Let $f_{n} \in \mathscr{C}(n \in \mathbb{\Omega}), f \in \mathscr{C}$. We write $f_{n} \xrightarrow{g} 0$ if $T_{f_{n}} g \xrightarrow{\boldsymbol{B}} 0$ for every $g \in S$; we write $f_{n} \xrightarrow{c} f$ if $f_{n}-f \xrightarrow{C} 0$.

If $f_{n} \in \mathscr{C}(n \in \mathbb{R})$, then the following statements are equivalent.
(i) $f_{n} \xrightarrow{c} 0$,
(ii) $\hat{f}_{n} \xrightarrow{c} 0$,
(iii) $\left(f_{n}\right) \xrightarrow{c} 0$,
(iv) $\overrightarrow{F G G}\left[T_{f_{n}} F^{S^{*}} 0\right]$,
(v) $V_{g \in S}\left[\mathrm{emb}^{-1}\left(\mathscr{F} f_{n}\right) \cdot g \xrightarrow{s} 0\right]$,
(vi) $V_{F \in S^{*}}\left[\mathrm{emb}^{-1}\left(\mathscr{F} f_{n}\right) \cdot F \xrightarrow{S^{*}} 0\right]$.

The proofs are almost trivial.
5.8. theorem. Let $f_{n} \in \mathscr{C}(n \in \mathbf{N})$. We have

$$
\mathbb{T}_{f \in C}\left[f_{n} \xrightarrow{G} f\right] \Leftrightarrow \forall_{g \in S}\left[\left(T_{f_{n}} g\right)_{n \in \mathrm{~N}} \text { is } S \text {-convergent }\right] .
$$

Proor. If $f \in \mathscr{C}$ is such that $f_{n} \xrightarrow{C} f$, then we have $T_{f_{n}} g-T_{f} g=T_{f_{n}-f} \xrightarrow{S} 0$ for every $g \in S$.

Now assume that ( $\left.T_{f_{n}} g\right)_{n \in \mathrm{~N}}$ is $S$-convergent for every $g \in S$. Denote $T g=\lim _{n \rightarrow \infty} T_{f_{n}} g$ for $g \in S$. It follows from [J], appendix $1,2.12$ that $T$ is a continuous linear operator of $S$, and $T T_{a}=T_{a} T$ for every $a \in \mathbf{R}$. So by 3.11, there is an $f \in \mathscr{C}$ such that $T=T_{f}$. It follows at once that $f_{n} \xrightarrow{C} f$.
5.9. THEOREM. Let $f \in \mathscr{C}, f_{n} \in \mathscr{C}(n \in \mathbb{R}), g \in \mathscr{C}, g_{n} \in \mathscr{C}(n \in \mathbb{R})$, and assume that $f_{n} \xrightarrow{C} f, g_{n} \xrightarrow{C} g$. Then $f_{n} \star g_{n} \xrightarrow{O} f \star g$ (cf. 3.9, remark 4).
proof. Let $u \in S$, and denote

$$
\begin{aligned}
& h_{n}:=\mathrm{emb}^{-1}\left(\mathscr{F} \tilde{f}_{n}\right) \quad(n \in \mathbf{\Omega}), k_{n}:=\mathrm{emb}^{-1}\left(\mathscr{F} \bar{g}_{n}\right) \quad(n \in \mathbb{R}), \\
& h:=\mathrm{emb}^{-1}(\mathscr{F} \tilde{f}), k:=\mathrm{emb}^{-1}(\mathscr{F} \bar{g}), v:=\mathscr{F} u .
\end{aligned}
$$

By $5.7(v)$ it suffices to show that $h_{n} \cdot k_{n} \cdot v \xrightarrow{s} h \cdot k \cdot v$. Therefore we note that $h_{n} \cdot k_{n} \cdot v \xrightarrow{S} h \cdot k \cdot v$ pointwise, and that there is an $M>0, A>0, B>0$ such that

$$
\left|h_{n}(z) k_{n}(z) v(z)\right| \leqslant M \exp \left(-\pi A(\operatorname{Re} z)^{2}+\pi B(\operatorname{Im} z)^{2}\right) \quad(z \in \mathbf{Q}, n \in \mathbf{N})
$$

as one easily sees from the fact that $k_{n} \cdot v \xrightarrow{s} k \cdot v, h_{n} \cdot w \xrightarrow{s} h \cdot w(w \in S)$. So, by $1.8, h_{n} \cdot k_{n} \cdot v \xrightarrow{S} h \cdot k \cdot v$.
remark. The above theorem is a special case of the following one. If $\left(T_{n}\right)_{n \in \mathbb{N}},\left(U_{n}\right)_{n \in \mathrm{~N}}$ are sequences of continuous linear operators of $S$ for which $\left(T_{n} g\right)_{n \in \mathbb{N}},\left(U_{n} g\right)_{n \in \mathbb{N}}$ are $S$-convergent for every $g \in S$, then

$$
T:=Y_{g \in S} \lim _{n \rightarrow \infty} T_{n} g, U:=Y_{g \in S} \lim _{n \rightarrow \infty} U_{n} g
$$

are continuous linear operators of $S$, and we have $T_{n} U_{n} g \xrightarrow{g} T U g$ for every $g \in S$.

### 5.10. examples

(i) If $\left(f_{n}\right)_{n \in N}$ is an $S$-convergent sequence in $S$, then (emb $\left.\left(f_{n}\right)\right)_{n \in N}$ is an $\mathscr{C}$-convergent sequence in $\mathscr{C}$. If $\left(g_{n}\right)_{n \in N}$ is a $\mathscr{C}$-convergent sequence in $\mathscr{C}$, then $\left(g_{n}\right)_{n \in N}$ is an $S^{*}$-convergent sequence in $S^{*}$.
(ii) If $f \in \mathscr{C}$, then $\mathrm{emb}\left(N_{\alpha} f\right) \xrightarrow{C} f$ if $\alpha \downarrow 0$ (we have of course a similar
definition of $\mathscr{C}$-convergence for this case as in 5.7). This is lemma 3.6.
(iii) If $\left(d_{n}\right)_{n \in Z}$ is a complex sequence satisfying $d_{n}=0\left(e^{-\mathrm{sm}^{2}}\right)(n \in Z)$ for some $\varepsilon>0$, then $\sum_{n--\infty}^{\infty} d_{n} \delta_{n}$ is a $\mathscr{C}$-convergent series in the sense that

$$
Y_{x \in \mathrm{C}} \sum_{n--N}^{M} d_{n} g(n+x) \xrightarrow{S} Y_{x \in \mathrm{C}} \sum_{n--\infty}^{\infty} d_{n} g(n+x)
$$

$(N \rightarrow \infty, M \rightarrow \infty)$ for every $g \in S$.
(iv) If $g_{\gamma}:=Y_{\operatorname{vec}} \gamma^{\ddagger} \exp \left(-\pi \gamma z^{2}\right)(\gamma>0)$, then emb $\left(g_{\gamma}\right) \xrightarrow{c} \delta_{0}(\gamma \rightarrow \infty)$. If $h_{\tau}:=1 / 2 \tau \chi_{(-\tau, \tau)}(\tau>0)$, then emb $\left(h_{\tau}\right) \xrightarrow{c} \delta_{0}(\tau \downarrow 0)$. More generally: if $h \in \mathscr{C}$, and $\left(\mathrm{emb}^{-1}(\mathscr{F} h)\right)(0)=1$, then $V_{\lambda} h \xrightarrow{c} \delta_{0}(\lambda \rightarrow \infty)$, where $V_{\lambda} h$ is the generalized function that satisfies

$$
\left(V_{\lambda} h, f\right)=\left(h, Y_{\varepsilon} \in c f(x / \lambda)\right)(f \in S) \text { for } \lambda>0
$$

(cf. 1.13). This may be proved by using $\mathscr{F} V_{\lambda}=\lambda^{-1} V_{\lambda^{-1}} \mathscr{F}(\lambda>0)$, the equivalence of $5.7(\mathrm{i})$ and $5.7(\mathrm{v})$, and 1.8 .
(v) Let $g \in S, g_{n} \in S(n \in \mathbb{R}), G \in S^{*}, G_{n} \in S^{*}(n \in \mathbf{R})$, and assume that $g_{n} \xrightarrow{S} g, G_{n} \xrightarrow{s^{*}} G$. Then $g_{n} \cdot G_{n} \xrightarrow{c} g \cdot G$. For it easily follows from 1.9 that $g_{n} \cdot G_{n} \xrightarrow{s^{*}} g \cdot G$. So if $f \in S$, then we have $T_{g_{n} \cdot G_{n}} f \rightarrow T_{g} \cdot G f$ pointwise, and it may be proved from lemma 5.2 that $T_{g_{n}} \cdot G_{n} f \xrightarrow{S} T_{g} \cdot G f$.

We also have: if $g \in S, G \in S^{*}$, then $g \cdot G(\alpha) \xrightarrow{C} g \cdot G(\alpha \downarrow 0)$.
5.11. We finally make some remarks about convolution theory for (generalized) functions of several variables. It is possible to develop the theory as it is presented here almost entirely for the more dimensional case (an exception should be made for the results of 4.12). We shall restrict ourselves here to the case of functions of two variables.

The definition of $T_{K}$ with $K \in S^{2 *}$ becomes

$$
T_{K} f=Y(x, y) \in \mathrm{C}^{2}\left(T_{x} \otimes T_{y} f, K_{-}\right) \quad(f \in S)
$$

where $K_{-}$is the generalized function $Y_{\alpha>0} Y_{(z, w) \in \mathrm{C}^{2}}\left(N_{\alpha, 2} K\right)(-z,-w)$ (cf. 1.16). In order to prove the two-dimensional version of theorem 3.3, we can use a theorem of Hartogs ([BT], Ch. III, § 4, Satz 15) about the analyticity of functions of several variables.

We introduce the set $\mathscr{C}_{2}^{2}$ as the class of all generalized functions $K$ for which $T_{K}$ maps $S^{2}$ into itself. The crucial lemma 3.6 still holds for the present case, and its proof differs only from that of lemma 3.6 in notational respect. This enables us to prove the two-dimensional versions of the theorems of section 3 and 4. We mention in particular theorems 3.5 and 3.7 (the definition of the class $\mathscr{M}^{2}$ is obvious).

An important example of an element of $\mathscr{C}^{2}$ is the tensor product of two elements of $\mathscr{C}$. Let $g_{1} \in \mathscr{C}, g_{2} \in \mathscr{C}$. We claim that $g_{1} \otimes g_{2} \in \mathscr{C}^{2}$, and that $T_{g_{1} \otimes g_{2}}=T_{g_{1}} \otimes T_{g_{2}}$ (cf. 1.17). To prove this note that

$$
(\mathscr{F} \otimes \mathscr{F})\left(g_{1} \otimes g_{2}\right)=\mathscr{F} g_{1} \otimes \mathscr{F} g_{2} \in \mathscr{M}^{2}
$$

hence, by the two-dimensional version of theorem 3.5, $g_{1} \otimes g_{2} \in \mathscr{C}^{2}$. Furthermore we have

$$
T_{g_{1} \otimes g_{2}}\left(h_{1} \otimes h_{2}\right)=T_{g_{1}} h_{1} \otimes T_{g_{2}} h_{2} \text { for } h_{1} \in S, h_{2} \in S
$$

and the proof can be completed in the style of [J], appendix 1, 2.13.

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