# Entire solutions to the Monge-Ampère equation 

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#### Abstract

We consider the Monge-Ampère equation $\operatorname{det}\left(D^{2} u\right)=\Psi(x, u, D u)$ in $\mathbb{R}^{n}, n \geqslant 3$, where $\Psi$ is a positive function in $C^{2}\left(\mathbb{R}^{n} \times \mathbb{R} \times \mathbb{R}^{n}\right)$. We prove the existence of convex solutions, provided there exist a subsolution of the form $\underline{u}=a|x|^{2}$ and a superharmonic bounded positive function $\varphi$ satisfying: $\Psi>\left(2 a+\frac{\Delta \varphi}{n}\right)^{n}$.


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## 1. Introduction

In this paper we study the existence of convex solutions to the Monge-Ampère equation

$$
\begin{equation*}
\operatorname{det}\left(D^{2} u\right)=\Psi(x, u, D u) \quad \text { in } \mathbb{R}^{n} \tag{1}
\end{equation*}
$$

where $\Psi(x, z, p)$ is a positive function in $C^{2}\left(\mathbb{R}^{n} \times \mathbb{R} \times \mathbb{R}^{n}\right), D u=\left(u_{1}, \ldots, u_{n}\right)$ denotes the gradient of $u$ and $D^{2} u=\left\{u_{i j}\right\}$ denotes the hessian of $u\left(u_{i}=\frac{\partial u}{\partial x_{i}}, u_{i j}=\frac{\partial^{2} u}{\partial x_{i} \partial x_{j}}\right)$.

The Monge-Ampère equation on bounded domains has been studied by many authors (see for instance $[1-5,8,9,11]$ ) but very little is known when the domain is unbounded (see for instance [2,6,7]). When $\Psi$ depends only on $x$, the problem was solved by K.S. Chou and X.J. Wang [6]. Here we generalize the latter work and prove an existence result of entire convex solutions provided there exist a subsolution of the form $\underline{u}=a|x|^{2}$ and a superharmonic bounded positive function $\varphi$ satisfying: $\Psi>\left(2 a+\frac{\Delta \varphi}{n}\right)^{n}$. Since no entire bounded positive superharmonic function exists for $n \leqslant 2$ (see [12]), we assume that $n \geqslant 3$ in all this note. For $n \geqslant 4, \varphi(x)=\frac{1}{1+|x|^{n-2}}$ is an example of superharmonic bounded positive function given in [10]. So let

$$
\psi^{\frac{1}{n}}=e^{\frac{2}{\Pi} \frac{\Delta \varphi}{n} \operatorname{arctg}\left(u^{2}+|p|^{2}\right)},
$$

then we can easily verify that the assumptions above on $\psi$ are all satisfied with $a=1$.

[^0]
## 2. Main result

Using the $C^{2}$ estimates of the solution up to the boundary (see [1,7]) we prove the following theorem.
Theorem 2.1. Suppose that the function $\underline{u}=a|x|^{2}$ is a subsolution of (1), that is

$$
\begin{equation*}
\operatorname{det} D^{2} \underline{u} \geqslant \Psi(x, \underline{u}, D \underline{u}) \tag{2}
\end{equation*}
$$

with a a positive large constant, and assume that $\Psi$ is a $C^{2}$ function satisfying:

$$
\begin{equation*}
\Psi>\left(2 a+\frac{\Delta \varphi}{n}\right)^{n}, \quad \Psi_{u} \geqslant 0, \quad \frac{|D \Psi|+\left|D^{2} \Psi\right|}{\Psi}<\infty \tag{3}
\end{equation*}
$$

where $\varphi$ is a superharmonic bounded positive function. Then Eq. (1) admits at least one convex solution $u$ satisfying:

$$
\begin{equation*}
a|x|^{2} \leqslant u \leqslant a|x|^{2}+\varphi, \quad u \in C^{2, \alpha}(K) ; \forall K \Subset \mathbb{R}^{n}, \forall 0<\alpha<1 . \tag{4}
\end{equation*}
$$

To prove Theorem 2.1 we shall proceed as follows. Suppose there exists a subsolution $\underline{u}=a|x|^{2}$. For $k \geqslant 1$, denote by $B_{n}(0, k)$ the ball in $\mathbb{R}^{n}$ of center the origin and radius $k$. We know that (see [1,4]), for any $k \geqslant 0$, the Dirichlet problem:

$$
\begin{cases}\operatorname{det}\left(D^{2} u^{k}\right)=\Psi\left(x, u^{k}, D u^{k}\right) & \text { in } B_{n}(0, k)  \tag{5}\\ u^{k}=\underline{u} & \text { on } \partial B_{n}(0, k)\end{cases}
$$

has a unique solution $u^{k} \in C^{2, \alpha}\left(B_{n}(0, k)\right), \forall 0<\alpha<1$. Using the barrier constructions (see [1,7]) for estimating the second tangential and mixed derivatives at the boundary, we prove that bounds of the second derivatives of $u^{k}$ are independent of $k$ in all compact set of $\mathbb{R}^{n}$. Finally, standard Calabi's interior estimates for the third derivatives (see [4]) yield local uniform bounds of $D^{3} u^{k}$. Using a diagonal sequence argument, we get a subsequence $\left\{u^{k_{i}}\right\}_{i \geqslant 1}$, that converges locally in $C^{2, \alpha}$ norm to a strictly convex solution of our original problem.

In Section 3 we shall give some technical lemmas. In Section 4, we give the proof of Theorem 2.1.

## 3. Some technical lemmas

To prove uniform bound of the second derivative of $u$ we shall return to work of L.A. Caffarelli, L. Niremberg and J. Spruck in [4], Bo Guan in [1], F. Finster and O.C. Schnürer in [7] and adapt to the situation of the theorem above that we prove in the next paragraph. By $c$ we denote a constant independent of $k$ which may change its value from line to line throughout the text.

Lemma 3.1. Let $k \geqslant 1$. For any $x \in \partial B_{n}(0, k)$, set $v_{k}(x)$ the inner unit normal to $\partial B_{n}(0, k)$ at $x$ and write any $y \in \mathbb{R}^{n}$ as

$$
y-x=y_{v} v_{k}(x)+y^{\prime}, \quad\left(y_{v}, y^{\prime}\right) \in \mathbb{R} \times v_{k}(x)^{\perp}
$$

then $\partial B_{n}(0, k) \cap B_{n}\left(x, \frac{1}{2}\right)$ is given explicitly by an equation of the type

$$
\begin{equation*}
y_{v}=\rho_{k}\left(y^{\prime}\right) \tag{6}
\end{equation*}
$$

where $\rho_{k} \in C^{\infty}\left(B_{n}\left(0, \frac{1}{2}\right) \cap v_{k}(x)^{\perp}\right)$ and satisfies

$$
\begin{equation*}
\rho_{k}(0)=0, \quad D \rho_{k}(0)=0, \quad\left|D^{2} \rho_{k}(0)\right| \leqslant \frac{c}{k}, \quad\left|D^{3} \rho_{k}\right|_{0,1, B_{n-1}\left(0, \frac{1}{2}\right)} \leqslant \frac{c}{k^{2}} \tag{7}
\end{equation*}
$$

with $c$ a positive constant independent of $k$.
Proof. Let $x \in \partial B_{n}(0, k)$. Without loss of generality we may suppose that $x=(0, \ldots, 0,-k)$ and then $v_{k}(x)=-\frac{x}{|x|}=e_{n}=$ $(0, \ldots, 0,1)$, and $v_{k}(x)^{\perp}=\mathbb{R}^{n-1}$. We write any $y \in \mathbb{R}^{n}$ as

$$
y-x=y_{n, k} e_{n}+y^{\prime}
$$

Set

$$
\rho\left(y^{\prime}\right)=1-\sqrt{1-\left|y^{\prime}\right|^{2}}, \quad y^{\prime} \in B_{n-1}(0,1)
$$

and

$$
\rho_{k}\left(y^{\prime}\right)=k \rho\left(\frac{y^{\prime}}{k}\right)
$$

where $B_{n-1}(0,1)$ is the unit open ball of $\mathbb{R}^{n-1}$. For $k \geqslant 1$, we have $B_{n}\left(x, \frac{1}{2}\right) \cap \partial B_{n}(0, k)$ is given by

$$
y_{n, k}=\rho_{k}\left(y^{\prime}\right), \quad y^{\prime} \in B_{n}\left(0, \frac{1}{2}\right) \cap \mathbb{R}^{n-1}=B_{n-1}\left(0, \frac{1}{2}\right) .
$$

We have

$$
\rho_{k}(0)=0, \quad D \rho_{k}(0)=0, \quad D^{2} \rho_{k}(0)=\left\{\frac{\delta_{i j}}{k}\right\}
$$

and since

$$
D^{i} \rho_{k}\left(y^{\prime}\right)=\frac{1}{k^{i-1}} D^{i} \rho\left(\frac{y^{\prime}}{k}\right), \quad \forall i \geqslant 1,
$$

it follows that

$$
\left|D^{2} \rho_{k}(0)\right| \leqslant \frac{c}{k}, \quad\left|D^{3} \rho_{k}\right|_{0,1, B_{n-1}\left(0, \frac{1}{2}\right)} \leqslant \frac{c}{k^{2}}
$$

with $c$ is uniform in $k$. This completes the proof of Lemma 3.2.
We shall use, in addition, the following lemmas. Let $u^{k}$ be a solution of the Dirichlet problem (5).
Lemma 3.2 (Estimation of $u^{k}$ ). Set $\bar{u}(x)=a|x|^{2}+\varphi$. As $k \rightarrow \infty$, the function $u^{k}$ converges locally uniformly to a convex function $u$. Moreover,

$$
\underline{u} \leqslant u^{k} \leqslant \bar{u} \quad \text { in } B_{n}(0, k), \forall k \geqslant 1 .
$$

Proof. Applying the arithmetic-geometric mean to the convex function $u^{k}$ we deduce that

$$
\Delta u^{k} \geqslant n \Psi^{\frac{1}{n}}>\Delta \bar{u}
$$

and then using the maximum principle we obtain

$$
\underline{u} \leqslant u^{k} \leqslant \bar{u} \quad \text { in } B_{n}(0, k)
$$

Hence for $k_{1}<k_{2}$,

$$
u^{k_{1}} \leqslant u^{k_{2}} \quad \text { on } \partial B_{n}\left(0, k_{1}\right)
$$

and again from the maximum principle,

$$
u^{k_{1}} \leqslant u^{k_{2}} \quad \text { in } B_{n}\left(0, k_{1}\right)
$$

We conclude that the sequence $\left\{u^{k}\right\}_{k \geqslant 1}$ is monotone. Its pointwise limit is convex and thus continuous. So it converges locally uniformly according to Dini's theorem.

From now on we omit the index $k$ and assume that $u$ is a solution of (5).
Lemma 3.3 (Estimation of $D u^{k}$ in $\left.\overline{B_{n}(0, k)}\right)$. Let $u \in C^{2}\left(\overline{B_{n}(0, k)}\right)$ be a locally convex solution to the Dirichlet problem (5). Then

$$
\begin{equation*}
|D u|_{0, \overline{B_{n}(0, k)}} \leqslant c k, \tag{8}
\end{equation*}
$$

with $c$ is uniform in $k$, and in all compact subset $K$ of $\mathbb{R}^{n}$, we have $|D u|_{0, K}$ is uniformly bounded in $k$ for $k$ sufficiently large.
Moreover, for $k^{2}-\frac{1}{4} \leqslant|x|^{2} \leqslant k^{2}$, let $v=\frac{x}{|x|}$ and $\tau$ be a unit vector orthogonal to $x$ then

$$
\begin{align*}
& \left|u_{\nu}(x)-\underline{u}_{\nu}(x)\right| \leqslant c,  \tag{9}\\
& \left|u_{\tau}(x)\right| \leqslant c . \tag{10}
\end{align*}
$$

Proof. Since $u$ is locally strictly convex, $|D u|$ takes its maximum on the boundary. It suffices then to estimate $|D u|$ at the boundary. Tangential derivatives vanish there in view of Dirichlet boundary conditions. It suffices then to estimate $u_{v}$ the exterior normal derivative of $u$ on $\partial B_{n}(0, k)$. Letting $x \in \partial B_{n}(0, k)$ we have

$$
u_{\nu}(x)=\lim _{t \rightarrow 0^{-}} \frac{u(x+t v)-u(x)}{t}
$$

As $u(x)=\underline{u}(x)$, we have

$$
\forall t<0, \quad \frac{u(x+t v)-u(x)}{t} \leqslant \frac{\underline{u}(x+t v)-\underline{u}(x)}{t}
$$

Then

$$
\begin{equation*}
u_{v}(x) \leqslant \underline{u}_{\nu}(x) \quad \text { on } \partial B_{n}(0, k) . \tag{11}
\end{equation*}
$$

To estimate $u_{\nu}(x)$ from below we simply make use of the convexity of $u$. The exterior unit normal to $\partial B_{n}(0, k)$ at $x$ being $\nu=\frac{x}{|x|}$. Using the convexity of $u$ as well as the fact that $\underline{u}$ lies below $u$ and $\underline{u}(x=k \nu)=u(x=k \nu), \underline{u}(y=-k v)=u(y=-k \nu)$ we obtain

$$
-\underline{u}_{-v}(y) \leqslant-u_{-v}(y)=u_{v}(y) \leqslant u_{v}(x) \leqslant \underline{u}_{v}(x),
$$

we deduce that

$$
\left|u_{v}(x)\right| \leqslant 2 a k
$$

Now, for $\theta>0$, denote

$$
\tilde{U}_{\theta}=\{x / \bar{u}(x)<\theta\}, \quad U_{\theta}=\{x / u(x)<\theta\}, \quad \underline{U}_{\theta}=\{x / \underline{u}(x)<\theta\} .
$$

These domains are all open, bounded and $U_{\theta}, \underline{U}_{\theta}$ are convex subsets of $\mathbb{R}^{n}$. Moreover, according to the $C^{0}$ estimates in Lemma 3.2, there exists a sufficiently large $k$ forthwith they satisfy

$$
\tilde{U}_{\theta} \subset U_{\theta} \subset \underline{U}_{\theta} \subset B_{n}(0, k)
$$

Let $K$ be a compact subset of $\mathbb{R}^{n}$. We can find $\theta>0$ and $k \geqslant 1$ such that $K \subset \tilde{U}_{\theta}$ and $\underline{U}_{2 \theta} \subset B_{n}(0, k)$. As

$$
\tilde{U}_{\theta} \subset U_{\theta} \Subset \underline{U}_{2 \theta},
$$

and $u$ is convex, it is not difficult to deduce, using $C^{0}$ estimates in Lemma 3.2, that

$$
\max _{K}|D u| \leqslant \max _{\partial U_{\theta}}|D u| \leqslant \max _{\partial \underline{U}_{2 \theta}} \frac{u-\theta}{d\left(\partial \underline{U}_{\theta}, \partial \underline{U}_{2 \theta}\right)} \leqslant c .
$$

Now, let $k^{2}-\frac{1}{4} \leqslant|x|^{2} \leqslant k^{2}$ and $v=\frac{x}{|x|}$. Using the convexity of $u$ we have

$$
\begin{aligned}
\left(u(x)-a|x|^{2}\right)-\left(u((|x|-1) v)-a|(|x|-1) \nu|^{2}\right) & \leqslant u_{v}(x)-2 a|x|+a \\
& =u_{v}(x)-\underline{u}_{v}(x)+a \\
& \leqslant \underline{u}_{v}(k v)-2 a\left(k-\frac{1}{2}\right)+a=2 a
\end{aligned}
$$

The $C^{0}$ estimates of Lemma 3.2 imply that $\left.|u(y)-a| y\right|^{2}\left|<|\varphi|_{0}\right.$ in $\overline{B_{n}(0, k)}$ and then

$$
\left|u_{\nu}(x)-\underline{u}_{v}(x)\right| \leqslant 2 a+|\varphi|_{0}
$$

In order to derive (10), we consider $u$ along the line segment $x+\lambda \tau$ parametrized by $\lambda \in\left[-\lambda_{0}, \lambda_{0}\right], \lambda_{0}=\sqrt{k^{2}-|x|^{2}}$. The boundary values of $u$ are $u\left( \pm \lambda_{0}\right)=\underline{u}\left( \pm \lambda_{0}\right)$. Thus using that $u$ lies above $\underline{u}$ and is convex, we obtain the estimate

$$
\underline{u}^{\prime}\left(-\lambda_{0}\right) \leqslant u^{\prime}\left(-\lambda_{0}\right) \leqslant u^{\prime}(\lambda=0) \leqslant u^{\prime}\left(\lambda_{0}\right) \leqslant \underline{u}^{\prime}\left(\lambda_{0}\right),
$$

and thus

$$
\left|u_{\tau}(x)\right|=\left|u^{\prime}(\lambda=0)\right| \leqslant \max \left\{\left|\underline{u}^{\prime}\left(-\lambda_{0}\right)\right|,\left|\underline{u}^{\prime}\left(\lambda_{0}\right)\right|\right\} .
$$

As $\lambda_{0}=\sqrt{k^{2}-|x|^{2}} \leqslant \frac{1}{2}$ we obtain

$$
\left|\underline{u}^{\prime}\left( \pm \lambda_{0}\right)\right|=\left|2\left(x \pm \lambda_{0} \tau\right) \cdot \tau\right|=2 \lambda_{0} \leqslant 1
$$

and the proof of Lemma 3.3 is complete.
Let $x$ be a point on $\partial B_{n}(0, k)$, set $\nu_{k}(x)$ the inner unit normal to $\partial B_{n}(0, k)$ at $x$ and write any $y \in \mathbb{R}^{n}$ as

$$
y-x=y_{\nu} v_{k}(x)+y^{\prime}, \quad\left(y_{v}, y^{\prime}\right) \in \mathbb{R} \times v_{k}(x)^{\perp}
$$

Using Lemma 3.1, choosing $\left(\tau_{1}, \ldots, \tau_{n-1}\right)$ an orthonormal basis in $\nu_{k}(x)^{\perp}$ and writing $y^{\prime}=\sum_{\alpha=1}^{n-1} y_{\alpha} \tau_{\alpha}$, we get that $\partial B_{n}(0, k) \cap B_{n}\left(x, \frac{1}{2}\right)$ is given explicitly by an equation of the type

$$
\begin{equation*}
y_{\nu}=\rho_{k}\left(y^{\prime}\right)=\frac{1}{2} \sum_{1 \leqslant \alpha, \beta \leqslant n-1} B_{\alpha \beta} y_{\alpha} y_{\beta}+\text { cubic of } y^{\prime}+O\left(\left|y^{\prime}\right|^{4}\right) \tag{12}
\end{equation*}
$$

where $O\left(\left|y^{\prime}\right|^{4}\right) \leqslant \frac{c}{k^{3}}$ with $c$ uniform in $k$.
Lemma 3.4 (Tangential strict convexity of $u^{k}$ ). Let $u \in C^{2}\left(\overline{B_{n}(0, k)}\right)$ be a locally convex solution to (5). Then for $k$ sufficiently large we have

$$
\begin{equation*}
c_{0} \leqslant \sum_{\alpha, \beta=1}^{n-1} u_{\alpha \beta}(x) \xi_{\alpha} \xi_{\beta} \leqslant c \tag{13}
\end{equation*}
$$

for any unit vector $\xi=\left(\xi_{1}, \ldots, \xi_{n-1}\right) \in \mathbb{R}^{n-1}$. Where $c_{0}$ and $c$ are positive constants uniform in $k$.
Proof. Since $u=\underline{u}$ on $\partial B_{n}(0, k)$ we have for $1 \leqslant \alpha, \beta \leqslant n-1$ :

$$
\begin{equation*}
u_{\alpha \beta}(x)=\underline{u}_{\alpha \beta}(x)+\left(\underline{u}_{\nu}-u_{\nu}\right)(x) \rho_{\alpha \beta}(x) . \tag{14}
\end{equation*}
$$

Using Lemma 3.1, (9) in Lemma 3.3 and $\left|D^{2} \underline{u}\right|=\left|2 a\left\{\delta_{i j}\right\}\right| \leqslant c$, we obtain $\left|u_{\alpha \beta}(x)\right| \leqslant c$ with $c$ a positive constant uniform in $k$.

Next we shall establish:

$$
\sum_{\alpha, \beta<n} u_{\alpha \beta}(x) \xi_{\alpha} \xi_{\beta} \geqslant c_{0}
$$

for any unit vector $\xi=\left(\xi_{1}, \ldots, \xi_{n-1}\right) \in \mathbb{R}^{n-1}$. Since

$$
(u-\underline{u})_{\alpha \beta}(x)+(u-\underline{u})_{\nu}(x) \rho_{\alpha \beta}(x)=0,
$$

and according to (9) as well as

$$
D^{2} \underline{u}=2 a\left\{\delta_{i j}\right\}, \quad \rho_{\alpha \beta}(x)=\frac{\delta_{\alpha \beta}}{k}
$$

we obtain for $k$ sufficiently large

$$
\sum_{\alpha, \beta<n} u_{\alpha \beta}(x) \xi_{\alpha} \xi_{\beta} \geqslant 2 a-\frac{c}{k} \geqslant 2 a-1,
$$

for any unit vector $\xi=\left(\xi_{1}, \ldots, \xi_{n-1}\right) \in \mathbb{R}^{n-1}$. The proof of Lemma 3.4 is then complete.
Lemma 3.5 (Estimates of the mixed second derivatives of $u^{k}$ on $\partial B_{n}(0, k)$ ). If $u \in C^{2}\left(\overline{B_{n}(0, k)}\right)$ is the locally strictly convex solution of (5), then for $x \in \partial B_{n}(0, k)$,

$$
\left|u_{\alpha \nu}(x)\right| \leqslant c, \quad 1 \leqslant \alpha \leqslant n-1
$$

where the constant $c$ is uniform in $k$.
Proof. Rewrite Eq. (1) in the form

$$
\log \operatorname{det}\left(D^{2} u\right)=\log \Psi(y, u, D u) \equiv f(y, u, D u)
$$

and let $\mathcal{L}$ denote the linear operator defined by

$$
\mathcal{L} \omega=u^{i j} \omega_{i j}-f_{p_{i}}(y, u, D u) \omega_{i} \quad \text { for } \omega \in C^{2}\left(\overline{B_{n}(0, k)}\right)
$$

where $\left\{u^{i j}\right\}$ is the inverse matrix of $\left\{u_{i j}\right\}$ and $f_{p_{i}}(y, z, p)=\frac{\partial f}{\partial p_{i}}(y, z, p)$. For a fixed $\alpha<n$, consider the differential operator

$$
T=\partial_{\alpha}+\sum_{\beta<n} B_{\alpha \beta}\left(y_{\beta} \partial_{\nu}-y_{\nu} \partial_{\beta}\right)
$$

On $\partial B_{n}(0, k) \cap B_{n}(x, \sigma), \sigma<k-\sqrt{k^{2}-\frac{1}{4}}$, we have

$$
|T(u-\underline{u})| \leqslant\left|(u-\underline{u})_{\alpha}+\left(\sum_{\beta<n} B_{\alpha \beta} y_{\beta}\right)(u-\underline{u})_{v}\right|+\left|y_{v} \sum_{\beta<n} B_{\alpha \beta}(u-\underline{u})_{\beta}\right| .
$$

To estimate the first term of the last inequality we use

$$
(u-\underline{u})_{\alpha}+\left(\sum_{\beta<n} B_{\alpha \beta} y_{\beta}\right)(u-\underline{u})_{\nu}=(u-\underline{u})_{\alpha}+\rho_{\alpha}\left(y^{\prime}\right)(u-\underline{u})_{v}+O\left(\left|y^{\prime}\right|^{2}\right)(u-\underline{u})_{v}
$$

where, by (7), $O\left(\left|y^{\prime}\right|^{2}\right) \leqslant \frac{c}{k^{2}}\left|y^{\prime}\right|^{2}$.
Since $(u-\underline{u})_{\alpha}+\rho_{\alpha}\left(y^{\prime}\right)(u-\underline{u})_{\nu}=0$ on $\partial B_{n}(0, k) \cap B_{n}(x, \sigma)$, and according to (9), (10) it follows

$$
\left|(u-\underline{u})_{\alpha}+\left(\sum_{\beta<n} B_{\alpha \beta} y_{\beta}\right)(u-\underline{u})_{v}\right| \leqslant \frac{c}{k}\left|y^{\prime}\right|^{2} .
$$

By Lemma 3.3, the second term verifies

$$
\left|y_{v} \sum_{\beta<n} B_{\alpha \beta}(u-\underline{u})_{\beta}\right|=\left|\rho\left(y^{\prime}\right) \sum_{\beta<n} B_{\alpha \beta}(u-\underline{u})_{\beta}\right| \leqslant c\left|y^{\prime}\right|^{2} .
$$

Consequently, we have

$$
|T(u-\underline{u})| \leqslant c|y|^{2} \quad \text { on } \partial B_{n}(0, k) \cap B_{n}(x, \sigma) .
$$

Following [4], we shall prove that

$$
|\mathcal{L} T(u-\underline{u})| \leqslant c\left(1+\sum u^{i i}\right) \quad \text { in } \overline{B_{n}(0, k) \cap B_{n}(x, \sigma)} .
$$

Let $\left(\xi_{1}, \ldots, \xi_{n-1}, \xi_{n}=v\right)$ be an orthonormal basis in $\mathbb{R}^{n}$, then we have, using Einstein summation convention

$$
\begin{aligned}
\mathcal{L}(T u)= & u^{i j}(T u)_{i j}-f_{p_{i}}(T u)_{i} \\
= & T\left[\log \operatorname{det}\left(D^{2} u\right)\right]-f_{p_{i}}\left[u_{\alpha i}+\sum_{\beta<n} B_{\alpha \beta}\left(\delta_{\beta i} u_{\nu}+y_{\beta} u_{\nu i}-\delta_{i \nu} u_{\beta}-y_{\nu} u_{\beta i}\right)\right] \\
= & T[f(y, u, D u)]-\left[f_{p_{i}} u_{\alpha i}+\sum_{\beta<n} B_{\alpha \beta}\left(y_{\beta} f_{p_{i}} u_{\nu i}-y_{\nu} f_{p_{i}} u_{\beta i}\right)\right] \\
& +\delta_{i \nu} f_{p_{i}} \sum_{\beta<n} B_{\alpha \beta} u_{\beta}-u_{\nu} f_{p_{i}} \sum_{\beta<n} B_{\alpha \beta} \delta_{\beta i} \\
= & f_{\alpha}+\sum_{\beta<n} B_{\alpha \beta}\left(y_{\beta} f_{v}-y_{\nu} f_{\beta}\right)+f_{z} u_{\alpha}+\sum_{\beta<n} B_{\alpha \beta}\left(y_{\beta} f_{z} u_{\nu}-y_{\nu} f_{z} u_{\beta}\right) \\
& +f_{p_{n}} \sum_{\beta<n} B_{\alpha \beta} u_{\beta}-u_{\nu} \sum_{1 \leqslant i<n} B_{\alpha i} f_{p_{i}} .
\end{aligned}
$$

As

$$
\left|u_{\nu}\right| \leqslant c k, \quad B_{\alpha \beta}=\frac{\delta_{\alpha \beta}}{k}, \quad|y-x|=y_{\nu}^{2}+\sum_{\alpha=1}^{n-1} y_{\alpha}^{2}<\frac{1}{2}
$$

and using (9), (10) we obtain

$$
|\mathcal{L}(T u)| \leqslant c .
$$

In another hand, we have

$$
|\mathcal{L} T(u-\underline{u})| \leqslant|\mathcal{L} T u|+|\mathcal{L} T \underline{u}| \leqslant c+|\mathcal{L} T \underline{u}| .
$$

Since $T \underline{u}=\underline{u}_{\alpha}=2 a y_{\alpha}$,
$\mathcal{L T} \underline{u}=-2 a f_{p_{\alpha}}$.

Thus
$|\mathcal{L T} \underline{u}| \leqslant c$.
So,

$$
|\mathcal{L} T(u-\underline{u})| \leqslant c \quad \text { in } \overline{B_{n}(0, k) \cap B_{n}(x, \sigma)} .
$$

We shall employ a barrier function of the form

$$
v=(u-\underline{u})+t d-N d^{2},
$$

where $d$ is the distance function to $\partial B_{n}(0, k)$, and $t, N$ are positive constants to be determined. We have $d(y)=k-|y|$ is $C^{\infty}$ smooth in $B_{n}(0, k) \cap B_{n}(x, \sigma)$.

The key ingredient is the following:
Lemma 3.6. For $N$ sufficiently large and $t$ sufficiently small,

$$
\begin{align*}
& \mathcal{L} v \leqslant-\frac{a}{2}\left(1+\sum u^{i i}\right) \quad \text { in } B_{n}(0, k) \cap B_{n}(x, \sigma), \\
& v \geqslant 0 \quad \text { on } \partial\left(B_{n}(0, k) \cap B_{n}(x, \sigma)\right) . \tag{15}
\end{align*}
$$

Proof. We have

$$
u^{i j}\left(u_{i j}-\underline{u}_{i j}\right)=\operatorname{tr}\left(\left\{\delta_{i j}\right\}\right)-2 a u^{i j} \delta_{i j}=n-2 a \sum_{i=1}^{n} u^{i i} .
$$

Using (9), (10) it follows that

$$
\mathcal{L}(u-\underline{u})=u^{i j}\left(u_{i j}-\underline{u}_{i j}\right)-f_{p_{i}}(x, u, D u)\left(u_{i}-\underline{u}_{i}\right) \leqslant c-2 a \sum u^{i i},
$$

where $c$ is uniform in $k$.
Moreover it is easy to see that

$$
|\mathcal{L}(d)| \leqslant c\left(1+\sum u^{i i}\right)
$$

for some $c>0$ uniform in $k$. Thus

$$
\mathcal{L} v \leqslant c+t c+(t c-2 a) \sum u^{i i}-N\left(\mathcal{L} d^{2}\right) \quad \text { in } B_{n}(0, k) \cap B_{n}(x, \sigma)
$$

Since

$$
\mathcal{L} d^{2}=2 d \mathcal{L} d+2 u^{i j} d_{i} d_{j}
$$

it follows, in $B_{n}(0, k) \cap B_{n}(x, \sigma)$

$$
\begin{equation*}
\mathcal{L} v \leqslant c+t c+(t c-2 a) \sum u^{i i}-2 N\left(d \mathcal{L} d+u^{i j} d_{i} d_{j}\right) \tag{16}
\end{equation*}
$$

Furthermore, since $\left\{u^{i j}\right\}$ is positive definite,

$$
\begin{aligned}
u^{i j} d_{i} d_{j} & =\sum_{i=1}^{n} u^{i i} d_{i}^{2}+2 \sum_{i<j} u^{i j} d_{i} d_{j} \\
& =u^{n n} d_{n}^{2}+2 \sum_{\beta<n} u^{n \beta} d_{n} d_{\beta}+\sum_{1 \leqslant i \leqslant n-1} u^{i j} d_{i} d_{j} \\
& \geqslant u^{n n} d_{n}^{2}+2 \sum_{\beta<n} u^{n \beta} d_{n} d_{\beta}
\end{aligned}
$$

Since $d_{\nu}(x)=1, d_{\beta}(x)=0$ for all $\beta<n$, we can find, for any $\delta>0$ a sufficiently small $\sigma<\delta$ such that $1+\frac{1}{\sqrt{2}} \geqslant d_{\nu}(y) \geqslant \frac{1}{\sqrt{2}}$ and $\left|d_{\beta}(y)\right|<\frac{\delta}{\sqrt{2}}, \forall y \in B_{n}(0, k) \cap B_{n}(x, \sigma)$. Then

$$
\left|\sum_{\beta<n} u^{n \beta} d_{n} d_{\beta}\right| \leqslant \frac{\delta}{\sqrt{2}} \sum u^{i i},
$$

and

$$
u^{i j} d_{i} d_{j} \geqslant u^{n n} d_{n}^{2}+2 \sum_{\beta<n} u^{n \beta} d_{n} d_{\beta} \geqslant \frac{u^{n n}}{2}-c \delta \sum u^{i i} \quad \text { in } B_{n}(0, k) \cap B_{n}(x, \sigma)
$$

with $c$ is uniform in $k$.
Now, letting $\lambda_{1} \leqslant \cdots \leqslant \lambda_{n}$ be the eigenvalues of $\left\{u^{i j}\right\}$ we have $\sum u^{i i}=\sum \lambda_{i}^{-1}, u^{n n} \geqslant \lambda_{n}^{-1}$, and, by arithmetic-geometric mean,

$$
\begin{aligned}
\frac{a}{2} \sum u^{i i}+N u^{n n} & \geqslant \frac{a}{2}\left(\sum_{i=1}^{n-1} \lambda_{i}^{-1}+N \lambda_{n}^{-1}\right) \\
& \geqslant \frac{n a}{2}\left(N \lambda_{1}^{-1} \cdots \lambda_{n}^{-1}\right)^{\frac{1}{n}} \\
& \geqslant \frac{n a}{2\left(|\Psi|_{0, \mathbb{R}^{n}}^{\frac{1}{n}}\right)} N^{\frac{1}{n}} \equiv c_{1} N^{\frac{1}{n}}
\end{aligned}
$$

Now, we fix $t>0$ sufficiently small so that the constant $t c$ in (16) satisfies: $t c \leqslant \frac{a}{2}$ and fix $N$ so that $c_{1} N^{\frac{1}{n}} \geqslant c+2 a$. We obtain

$$
\begin{aligned}
\mathcal{L} v & \leqslant c+\frac{a}{2}-\frac{a}{2} \sum u^{i i}-N u^{n n}+2 N(c \delta+d c) \sum u^{i i}+2 N d c-a \sum u^{i i} \\
& \leqslant c+\frac{a}{2}-c_{1} N^{\frac{1}{n}}+2 N(c \delta+d c) \sum u^{i i}+2 N d c-a \sum u^{i i} \\
& \leqslant-\frac{3 a}{2}-a \sum u^{i i}+4 N \delta c \sum u^{i i}+2 N \delta c
\end{aligned}
$$

if we require $\delta$ to satisfy $4 N c \delta \leqslant \frac{a}{2}$, we get

$$
\mathcal{L} v \leqslant-\frac{a}{2}\left(1+\sum u^{i i}\right) \quad \text { in } B_{n}(0, k) \cap B_{n}(x, \sigma)
$$

It remains to examine the value of $v$ on $\partial\left(B_{n}(0, k) \cap B_{n}(x, \sigma)\right)$.
On $\partial B_{n}(0, k) \cap B_{n}(x, \sigma)$ we have $v=0$. If we require, in addition, $N \sigma \leqslant t$, we get

$$
v \geqslant t d-N d^{2} \geqslant(t-N \sigma) d \geqslant 0 \quad \text { on } B_{n}(0, k) \cap \partial B_{n}(x, \sigma) .
$$

Now we fix $\sigma$ sufficiently small and the proof of Lemma 3.6 is complete.
We can now complete the proof of Lemma 3.5. Using Lemma 3.6, we have

$$
\begin{aligned}
\mathcal{L}\left(A v+B|y|^{2} \pm T(u-\underline{u})\right) & =A \mathcal{L}(v)+2 B \sum u^{i i}-2 f_{p_{i}} y_{i} \pm \mathcal{L}(T(u-\underline{u})) \\
& \leqslant-\frac{a}{2} A+c-2 f_{p_{i}} y_{i}+\left(-\frac{a}{2} A+2 B\right) \sum u^{i i}
\end{aligned}
$$

Consequently,

$$
\mathcal{L}\left(A v+B|y|^{2} \pm T(u-\underline{u})\right) \leqslant 0 \quad \text { in } B_{n}(0, k) \cap B_{n}(x, \sigma),
$$

for $A$ sufficiently large (depending on $c, B, \frac{|\Psi|_{1}}{\Psi_{0}}$ ).
Since $v \geqslant 0$ on $\partial\left(B_{n}(0, k) \cap B_{n}(x, \sigma)\right)$ and

$$
|T(u-\underline{u})| \leqslant c|y|^{2} \quad \text { on } \partial\left(B_{n}(0, k) \cap B_{n}(x, \sigma)\right)
$$

we can choose $A \gg B \gg 1$ so that

$$
A v+B|x|^{2} \pm T(u-\underline{u}) \geqslant 0 \quad \text { on } \partial\left(B_{n}(0, k) \cap B_{n}(x, \sigma)\right) .
$$

It follows from the maximum principle that

$$
|T(u-\underline{u})| \leqslant A v+B|y|^{2} \quad \text { in } B_{n}(0, k) \cap B_{n}(x, \sigma),
$$

and according to (9)

$$
\left|\partial_{\nu} T(u-\underline{u})(x)\right| \leqslant \partial_{v}\left(A v+B|y|^{2}\right)(x)=A \partial_{\nu} v(x)=A(u-\underline{u})_{\nu}(x)+t A d_{v}(x) \leqslant A c,
$$

with $c$ is uniform in $k$. But

$$
\partial_{\nu} T(u-\underline{u})(x)=u_{\nu \alpha}(x)-\underline{u}_{\nu \alpha}(x) .
$$

So,

$$
\left|u_{\alpha \nu}(x)\right| \leqslant c .
$$

This completes the proof of Lemma 3.5.
Lemma 3.7 (Estimation of $u_{\nu \nu}^{k}$ on $\partial B_{n}(0, k)$ ). Let $x \in \partial B_{n}(0, k)$ and $\nu=-\frac{x}{|x|}$. We have

$$
u_{\nu v}(x)<c .
$$

Proof. We choose an orthonormal basis such that the submatrix $\left\{u_{\alpha \beta}\right\}$ is diagonal. We expand the determinant,

$$
\begin{aligned}
\Psi(x, u, D u) & =\operatorname{det}\left(D^{2} u(x)\right)=u_{\nu \nu}(x) \prod_{1 \leqslant \alpha \leqslant n-1} u_{\alpha \alpha}(x)-\sum_{1 \leqslant \gamma \leqslant n-1} u_{\gamma \nu}^{2}(x) \prod_{\alpha \neq \gamma<n} u_{\alpha \alpha}(x) \\
& =\prod_{1 \leqslant \alpha \leqslant n-1} u_{\alpha \alpha}(x)\left(u_{\nu \nu}(x)-\sum_{1 \leqslant \gamma \leqslant n-1} u_{\gamma \nu}^{2}(x) \frac{1}{u_{\gamma \gamma}(x)}\right) .
\end{aligned}
$$

Now we substitute in the estimates of Lemmas 3.4 and 3.5 to obtain

$$
0 \leqslant u_{\nu \nu}(x) \leqslant \frac{1}{\prod_{1 \leqslant \alpha \leqslant n-1} u_{\alpha \alpha}}\left(\Psi(x, u, D u)+\sum_{1 \leqslant \gamma \leqslant n-1} \frac{u_{\gamma \nu}^{2}(x)}{u_{\gamma \gamma}(x)}\right) \leqslant c .
$$

## 4. Proof of Theorem 2.1

For each $k \geqslant 1$, we consider the Dirichlet problem (5). Using the fact that $\underline{u}$ is a locally strictly convex subsolution of (5), the $C^{\infty}$ smoothness of boundary data in (5) allows us to deduce the existence of a unique solution to (5) satisfying

$$
\left.u_{k} \in C^{2, \alpha}\left(\overline{B_{n}(0, k)}\right) \quad \forall \alpha \in\right] 0,1[
$$

(see [1]). Furthermore, using Lemmas 3.2, 3.3, 3.4, 3.5 and 3.7 we deduce that:

$$
\begin{equation*}
\forall k \geqslant 1, \quad\left|D^{2} u_{k}\right|_{0, \overline{B_{n}(0, k)}} \leqslant c \tag{17}
\end{equation*}
$$

with $c$ a positive constant independent of $k$.
Using Calabi's interior estimates for the third derivatives (see [4]) we deduce that

$$
\left|D^{3} u_{k}\right| \leqslant \frac{\tilde{c}}{d(x, \partial B(0, k))}, \quad k \geqslant 1, \text { in } B(0, k)
$$

where $\tilde{c}$ is a positive constant depending only on the constant $c$ given by (17).

Step 1. In $B_{n}(0,1)$ we have

$$
\left|D^{3} u_{k}\right| \leqslant \frac{\tilde{c}}{d\left(\partial B_{n}(0,1), \partial B_{n}(0,2)\right)}, \quad \forall k \geqslant 2
$$

where $\tilde{c}$ is a positive constant independent of $k$.
Then, according to the $C^{0}$ and $C^{1}$ estimates of $u$ in Lemmas 3.2 and 3.3 and using Lemma 6.36 in [8] we deduce that there exist a subsequent $\left(u_{\eta_{1}(k)}\right)_{k \geqslant 1}$ of $\left(u_{k}\right)_{k \geqslant 1}$ and $v_{1} \in C^{2, \alpha}\left(\overline{B_{n}(0,1)}\right)$ such that:

$$
\lim _{k \rightarrow+\infty}\left|u_{\eta_{1}(k)}-v_{1}\right|_{2, \alpha, \overline{B_{n}(0,1)}}=0
$$

Step 2. As previously, from the sequence $\left(u_{\left.\eta_{1}(k)\right)_{k} \geqslant 1}\right.$ we can extract a subsequent $\left(u_{\eta_{2}(k)}\right)_{k \geqslant 1}$ such that $u_{\eta_{2}(k)}$ converges to $v_{2}$ in $C^{2, \alpha}\left(\overline{B_{n}(0,2)}\right)$.

By uniqueness of the limit we have

$$
v_{1}=v_{2} \quad \text { in } \overline{B_{n}(0,1)}
$$

So we construct iteratively a sequence $\left(u_{\eta_{s}(k)}\right)_{k \geqslant 1}$ for all $s \geqslant 1$ such that

$$
u_{\eta_{s}(k)} \rightarrow v_{s} \quad \text { in } C^{2, \alpha}\left(\overline{B_{n}(0, s)}\right)
$$

and

$$
\forall s \geqslant 1, \quad v_{s}=v_{k}, \quad \forall 1 \leqslant k \leqslant s, \text { in } \overline{B_{n}(0, k)}
$$

We consider the sequence $\left(u_{\eta_{k}(k)}\right)_{k \geqslant 1}$ obtained from $\left(u_{\eta_{s}(k)}\right)_{s, k \geqslant 1}$ by the diagonal process. $\left(u_{\eta_{k}(k)}\right)_{k \geqslant 1}$ is a subsequent of $\left(u_{\eta_{s}(k)}\right)_{k \geqslant 1}$ for all $s \geqslant 1$. Therefore,

$$
\begin{equation*}
u_{\eta_{k}(k)} \rightarrow v_{s} \quad \text { when } k \rightarrow \infty, \text { in } C^{2, \alpha}\left(\overline{B_{n}(0, s)}\right), \forall s \geqslant 1 \tag{18}
\end{equation*}
$$

Thus $u_{\eta_{k}(k)}$ converges locally to $u$ in $C^{2, \alpha}$ norm, with $u=v_{s}$ in $\overline{B_{n}(0, s)}$ for $s \geqslant 1$. Since $\Psi$, det are continuous then when passing to the limit we obtain $u$ satisfies

$$
\begin{equation*}
\operatorname{det}\left(D^{2} u\right)=\Psi(x, u, D u) \quad \text { in } \mathbb{R}^{n} \tag{19}
\end{equation*}
$$

that is $u$ is a solution in $\mathbb{R}^{n}$ of (1). Moreover, from the fact that $D^{2} u_{\eta_{k}(k)}$ is positive on $\overline{B_{n}(0, s)}, \forall k \geqslant s$, when passing to the limit we deduce that $D^{2} u=D^{2} v_{s}$ is nonnegative in $\overline{B_{n}(0, s)}, \forall s \geqslant 1$. Using (19) and $\Psi>0$ we conclude that $D^{2} u$ is positive in $\mathbb{R}^{n}$. Thus $u$ is strictly convex in $\mathbb{R}^{n}$. In another hand, since $\forall s \geqslant 1, \forall k \geqslant s, \bar{u} \geqslant u_{\eta_{k}(k)} \geqslant \underline{u}$ on $\overline{B_{n}(0, s)}$, we deduce

$$
\begin{equation*}
\bar{u} \geqslant u \geqslant \underline{u} \quad \text { in } \mathbb{R}^{n} \tag{20}
\end{equation*}
$$

That completes the proof of Theorem 2.1.

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