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Six signed Petersen graphs, and their automorphisms

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ABSTRACT

Up to switching isomorphism, there are six ways to put signs on the edges of the Petersen graph. We prove this by computing switching invariants, especially frustration indices and frustration numbers, switching automorphism groups, chromatic numbers, and numbers of proper 1-colorations, thereby illustrating some of the ideas and methods of signed graph theory. We also calculate automorphism groups and clusterability indices, which are not invariant under switching. In the process, we develop new properties of signed graphs, especially of their switching automorphism groups.

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1. Introduction

The Petersen graph P is a famous example and counterexample in graph theory, making it an appropriate subject for a book (see [11]). With signed edges, it makes a fascinating example of many aspects of signed graph theory as well. There are 2^{15} ways to put signs on the edges of P , but in many respects only six of them are essentially different. We show how and why that is true as we develop basic properties of these six signed Petersens.

The fundamental property of signed graphs is balance. A signed graph is *balanced* if all its circles (circuits, cycles, polygons) have positive sign product. Harary introduced signed graphs and balance [9] (though they were implicit in [12, Section X.3]). Cartwright and Harary used them to model social stress in small groups of people in social psychology [6]. Subsequently, signed graphs have turned out to be valuable in many other areas, some of which we shall allude to in what follows.

The opposite of balance is frustration. Most signatures of a graph are unbalanced; but they can be made balanced by deleting (or, equivalently, negating) edges. The smallest number of edges whose deletion makes the graph balanced is the *frustration index*, a number which is implicated in certain questions of social psychology [1,10] and spin-glass physics [16,3]. We find the frustration indices of all signed Petersen graphs (Theorem 7.2).

The second basic property of signed graphs is switching equivalence. Switching is a way of turning one signature of a graph into another, without changing circle signs. Many properties of signed graphs are unaltered by switching, the frustration index being a notable example. The first of our main theorems is that there are exactly six equivalence classes of signatures of P under the combination of switching and isomorphism (Theorem 5.1). Fig. 1.2 shows a representative of each switching isomorphism class. In each representative, the negative edges form a smallest set whose deletion makes the signed Petersen balanced. Hence, we call them *minimal signatures* of P (see Theorem 7.2). Because there are only six switching isomorphism classes of signatures, the frustration index of every signature of P can be found from those of the minimal signatures.

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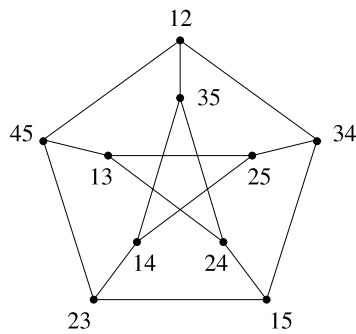


Fig. 1.1. P , the Petersen graph.

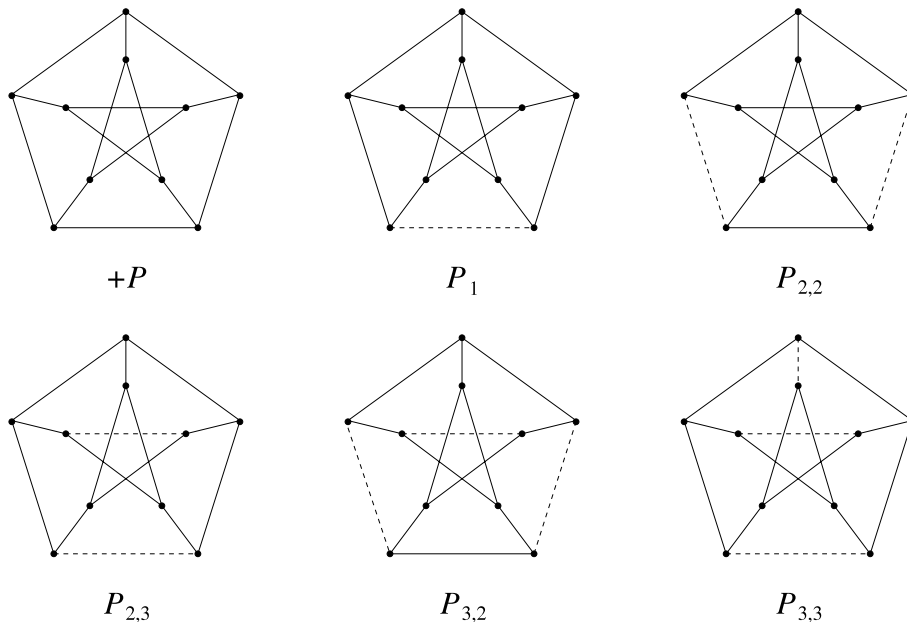


Fig. 1.2. The six switching isomorphism types of signed Petersen graph. Solid lines are positive; dashed lines are negative.

The second main theorem, which occupies the bulk of this paper, is a computation of the automorphism and switching automorphism groups of the six minimal signatures (Theorem 8.12). An automorphism has the obvious definition: it is a graph automorphism that preserves edge signs. This group is not invariant under switching. It is not even truly signed-graphic, since in what concerns automorphisms a signed graph is merely an edge 2-colored graph. The proper question for signed graphs regards the combination of switching with an automorphism of the underlying graph. The group of switching automorphisms of a signed graph is, by its definition, invariant under switching, so just six groups are needed to know them all. Some of the groups are trivial, but one is so complicated that it takes pages to describe it thoroughly.

Isomorphic minimal signatures may not be equivalent under the action of the switching group. The number of switching-inequivalent signatures of a given minimal isomorphism type is deducible from the order of the switching automorphism group (Section 8.3).

Two further properties are treated more concisely. First, a signed graph can be colored by signed colors. This leads to two chromatic numbers, depending on whether or not the intrinsically signless color 0 is accepted. The chromatic numbers are invariant under switching (and isomorphism); thus they help to distinguish the six minimal signatures by showing their inequivalence under switching isomorphism (Theorem 9.2). The two chromatic numbers are aspects of two chromatic polynomials, but we make no attempt to compute those polynomials, as they have degree 10.

Finally, we take a brief excursion into a natural generalization of balance called *clusterability* (Section 10). This, like the automorphism group, is not switching invariant, but it has attracted considerable interest, most recently in connection with the organization of data (see [2]), and has complex properties that have been but lightly explored.

Signed graphs, signed Petersen graphs in particular, have other intriguing aspects that we do not treat. Two are mentioned in the concluding section, but they hardly exhaust the possibilities.

2. Graphs and signs

We write V and E for the vertex and edge sets of a graph Γ or signed graph Σ , except when they may be confused with the same sets of another graph. The complement of $X \subseteq V$ is $X^c := V \setminus X$. The (open) neighborhood of a vertex v is $N(v)$; the closed neighborhood is $N[v] = N(v) \cup \{v\}$. A *cut* in a graph is a non-empty set $\nabla X := \{uv \in E : u \in X \text{ and } v \notin X\}$, where $X \subseteq V$. We call two or more substructures of a graph, such as edge sets or vertex sets, *automorphic* if there are graph automorphisms under which any one is carried to any other.

A *signed graph* is a pair $\Sigma := (\Gamma, \sigma)$, where $\Gamma = (V, E)$ is a graph and $\sigma : E \rightarrow \{+, -\}$ is a *signature* that labels each edge positive or negative. Hence, a *signed Petersen graph* is (P, σ) . Two examples are $+P := (P, +)$, where every edge is positive, and $-P := (P, -)$, where every edge is negative. The *underlying graph* of Σ is Σ without the signs, denoted by $|\Sigma|$. We say that Σ is *homogeneous* if it is all positive or all negative, and *heterogeneous* otherwise; so $+P$ and $-P$ are the homogeneous signed Petersens. The set of positive edges of Σ is E^+ , and that of negative edges is E^- ; Σ^+ and Σ^- are the corresponding (unsigned) graphs (V, E^+) and (V, E^-) . The *negation* of Σ is $-\Sigma = (\Gamma, -\sigma)$, the same graph with all signs reversed. A compact notation for a signed Petersen graph with negative edge set S is P_S .

The sign of a circle (i.e., a cycle, circuit, or polygon) C is $\sigma(C) :=$ the product of the signs of the edges in C . The most essential fact about a signed graph usually is not, as one might think, the edge sign function itself, but only the set $\mathcal{C}^+(\Sigma)$ of circles that have positive sign. If this set consists of all circles, we call the signed graph *balanced*. Such a signed graph is equivalent to its unsigned underlying graph in most ways. We call Σ *antibalanced* if $-\Sigma$ is balanced.

Proposition 2.1 (Harary [9]). Σ is balanced if and only if V can be divided into two sets so that all positive edges are within a set and all negative edges are between the sets.

We say ‘divided’ rather than ‘partitioned’ because one set may be empty. If that is so, the signature is all positive.

3. Petersen structure

The Petersen graph P is the complement of the line graph of K_5 : $P = \overline{L(K_5)}$. Thus, its vertices v_{ij} are in one-to-one correspondence with the 10 unordered pairs from the set $\{1, 2, 3, 4, 5\}$ and its 15 edges are all the pairs $v_{ij}v_{kl}$ such that $\{i, j\} \cap \{k, l\} = \emptyset$. (For readability, in subscripts we often omit the v of vertex names.) We usually write V and E for $V(P)$ and $E(P)$ when discussing the Petersen graph, as there can be no confusion with the vertex and edge sets of a general graph.

For use later, we want structural information about P .

As P has edge connectivity 3, the smallest cut has three edges.

The automorphism group $\text{Aut } P$ is well known to be the symmetric group \mathfrak{S}_5 with action on V induced by the permutations of the set $\{1, 2, 3, 4, 5\}$. Writing \mathfrak{S}_T for the group of permutations of the set T , we identify $\text{Aut } P$ with $\mathfrak{S}_{\{1,2,3,4,5\}}$. We use the same symbol for a permutation of $\{1, 2, 3, 4, 5\}$ and the corresponding automorphism of P , as there is little danger of confusion. $\text{Aut } P$ carries any oriented path of length 3 to any other; hence it is also transitive on pairs of adjacent edges (distance 1) and on pairs of edges at distance 2. (For these properties, see, e.g., [8, Section 4.4].) Furthermore, $\text{Aut } P$ carries any non-adjacent vertex pair to any other.

The maximum size of a set of independent vertices in P is 4. Each maximum independent vertex set has the form $X_m := \{v_{im} : i \in \{1, 2, 3, 4, 5\} \setminus m\}$, and any three vertices in X_m determine m . For any $m, n \in \{1, 2, 3, 4, 5\}$, X_m and X_n are automorphic. An independent set of three vertices is either the neighborhood of a vertex, or a subset of a maximum independent set X_m . Deleting an independent vertex set leaves a connected graph, except that $P \setminus N(v) = C_6 \cup K_1$ and $P \setminus X_m$ is a 3-edge matching. If $|W| = 3$ and $W \subset X_m$, then $P \setminus W$ is a tree consisting of three paths of length 2 with one endpoint in common.

3.1. Hexagons

Each hexagon is $E(P \setminus N[v])$ for a vertex v . Thus there is a one-to-one correspondence between vertices and hexagons; we write $H_v = H_{lm}$ for the hexagon that corresponds to $v = v_{lm}$. The stabilizer of H_{lm} is $\mathfrak{S}_{\{l,m\}} \times \mathfrak{S}_{\{1,2,3,4,5\} \setminus \{l,m\}}$. A hexagon is determined by any two of its edges that have distance 2. Furthermore, any two hexagons are automorphic.

3.2. Matchings

We need to know all automorphism types of a matching in P . Let M_k denote a matching of k edges.

Matchings of one edge are obviously all automorphic.

Let $M_{2,d}$ denote a pair of edges at distance $d = 2$ or 3 . Any 2-edge matching is an $M_{2,2}$ or $M_{2,3}$. All $M_{2,2}$ matchings are automorphic because $\text{Aut } P$ is transitive on paths of length 3. All $M_{2,3}$ matchings are automorphic; for the proof see the treatment of $M_{3,3}$.

An M_5 can only be a cut between two pentagons, since $P \setminus M_5$ is a 2-factor and P is non-Hamiltonian. All are clearly automorphic.

A matching of four edges leaves two vertices unmatched. If they are adjacent, $M_4 = M_5 \setminus \text{edge}$; all such matchings are automorphic. If they are non-adjacent, say they are v_{ik} and v_{jk} in Fig. 3.1. Then M_4 consists of a and one of the two $M_{3,2}$'s

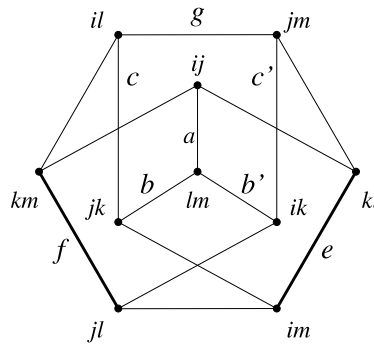


Fig. 3.1. The four kinds of 3-edge matching in P .

in H_{lm} . Call this type of matching M'_4 . Interpreting M'_4 as one of the matchings in H_{lm} together with one of the edges incident with v_{lm} , it is easy to see that all matchings of type M'_4 are automorphic. Consequently, there are two automorphism classes of 4-edge matchings.

There are four non-automorphic kinds of 3-edge matching M_3 . First we describe them; then we prove there are no other kinds.

By $M_{3,3}$ we mean a set of three edges, each pair having the same distance 3. Each $M_{3,3}$ has the form

$$M_{3(m)} := E(P \setminus X_m) = \{v_{ij}v_{kl} : \{i, j, k, l\} = \{1, 2, 3, 4, 5\} \setminus m\}.$$

There are five such edge sets, one for each $m \in \{1, 2, 3, 4, 5\}$; they partition $E(P)$. Obviously, all the $M_{3(m)}$'s are automorphic. An $M_{2,3}$ lies in a unique $M_{3,3}$, since the $M_{2,3}$ determines the value of m . This implies that there are 15 different $M_{2,3}$'s. Permuting $\{1, 2, 3, 4, 5\} \setminus m$ permutes the edges of $M_{3(m)}$; it follows that any $M_{2,3}$ is automorphic to any other.

We define $M_{3,2}$ to consist of alternate edges of a hexagon, say H_{lm} , which we call the *principal hexagon* of the three edges. There are two such sets for each hexagon, hence 20 $M_{3,2}$'s in all, and they are all automorphic to each other. The notation $M_{3,2}$ reflects the fact that the edges in the matching all have distance 2 from each other. Each $M_{2,2}$ is contained in a unique hexagon, and hence in a unique $M_{3,2}$; thus, there are 60 $M_{2,2}$'s.

There is another way to form a matching of three edges at distance 2 from one another. In a pentagon $v_{ij}v_{kl}v_{mi}v_{jk}v_{lm}v_{ij}$, take the edges $e = v_{kl}v_{im}$ and $f = v_{ij}v_{km}$ and the edge $a = v_{ij}v_{lm}$. We call this type M'_3 . Another view of M'_3 is as $M_3 \setminus$ two edges. All matchings of type M'_3 are automorphic, but they are not automorphic to any $M_{3,2}$ because e, f, a do not lie in a hexagon.

A fourth type of 3-edge matching, call it $M_{3,2/3}$, consists of e, f , and $b = v_{jk}v_{im}$. The distances of these edges are 2, except that b and f have distance 3. All $M_{3,2/3}$'s are automorphic, but the distance pattern proves that an $M_{3,2/3}$ is not automorphic to any other type.

Lemma 3.1. Every 3-edge matching in P is an $M_{3,3}$, an $M_{3,2}$, an M'_3 , or an $M_{3,2/3}$.

Proof. Let M_3 be a 3-edge matching. If its edges are all at distance 3 from each other, then M_3 can only be $M_{3,3}$, as two edges at distance 3 have a unique edge at the same distance from both.

If M_3 contains edges e, f at distance 2, there are four potential third edges up to the symmetry that interchanges e and f (see Fig. 3.1). Choosing g for M_3 , the hexagon H_{lm} contains M_3 , so we have $M_{3,2}$. Choosing a for M_3 , the pentagon $v_{ij}v_{kl}v_{mi}v_{jk}v_{lm}v_{ij}$ shows we have M'_3 . Choosing b , we have $M_{3,2/3}$. Choosing c , we have M'_3 again with the pentagon $v_{im}v_{jk}v_{il}v_{km}v_{jl}v_{im}$. \square

4. Switching

Two signed graphs, $\Sigma_1 = (\Gamma_1, \sigma_1)$ and $\Sigma_2 = (\Gamma_2, \sigma_2)$, are *switching equivalent* (written $\Sigma_1 \sim \Sigma_2$) if $\Gamma_1 = \Gamma_2$ and there is a function $\zeta : V_1 \rightarrow \{+, -\}$ (a *switching function*) such that $\sigma_2(vw) = \zeta(v)\sigma_1(vw)\zeta(w)$ for every edge vw . We write $\sigma_2 = \sigma_1^\zeta$ and $\Sigma_2 = \Sigma_1^\zeta$; that is, we write the switched signature or graph as if we were conjugating in a group—and indeed switching is a graphical generalization of conjugation. Another way to define switching is to switch a vertex set $X \subseteq V$ (the connection is that $X = \zeta^{-1}(-)$); that means negating the sign of every edge in the cut ∇X . Then we write $\Sigma^X = (\Gamma, \sigma^X)$ for the switched graph. The switching function ζ_X is defined by $\zeta_X(v) := +$ if $v \notin X$ and $-$ if $v \in X$.

Switching functions multiply pointwise: $(\zeta\eta)(v) = \zeta(v)\eta(v)$. Multiplication corresponds to set sum (symmetric difference) of switching sets: $\zeta_X\zeta_Y = \zeta_{X \oplus Y}$. The group of switching functions is $\{+, -\}^V$. We write ε for its identity element, the all-positive switching function. Certain switching functions have no effect on Σ ; that is, the action of $\{+, -\}^V$ on a signature has a kernel,

$$\mathfrak{K}_\Gamma := \{\zeta : \Sigma^\zeta = \Sigma\} = \{\zeta : \zeta \text{ is constant on each component of } \Gamma\}.$$

The kernel is independent of the signature, in fact, of everything except the partition of V into vertex sets of connected components of Γ . The quotient group is the *switching group* of Γ , written

$$\text{Sw } \Gamma := \{+, -\}^V / \mathfrak{K}_\Gamma.$$

The element of this group that corresponds to a switching function ζ is $\bar{\zeta}$, but for simplicity of notation we often use the same symbol ζ without the bar when it should not cause confusion.

We say Σ_1 and Σ_2 are *isomorphic* (written $\Sigma_1 \cong \Sigma_2$) if there is a graph isomorphism $\psi : \Gamma_1 \rightarrow \Gamma_2$ that preserves edge signs, i.e., $\sigma_2((vw)^\psi) = \sigma_1(vw)$ for every edge. (As we are restricting ourselves to simple graphs, ψ can be treated as a bijection $V_1 \rightarrow V_2$ and $(vw)^\psi = v^\psi w^\psi$.) They are *switching isomorphic* (written $\Sigma_1 \simeq \Sigma_2$) if Σ_2 is isomorphic to a switching of Σ_1 ; that is, there are a graph isomorphism $\psi : \Gamma_1 \rightarrow \Gamma_2$ and a switching function $\zeta : V_1 \rightarrow \{+, -\}$ such that $\sigma_2((vw)^\psi) = \sigma_1^\zeta(vw)$ for every edge.

Lemma 4.1 ([15,17]). *Switching preserves circle signs. Conversely, if two signatures of Γ have the same circle signs, then one is a switching of the other.*

For instance, Σ is balanced if and only if it is switching equivalent to the all-positive signature. Because of this lemma, switching-equivalent signed graphs are in most ways the same.

Lemma 4.1 shows that switching isomorphism is a true isomorphism: not of graphs or signed graphs, but of the structure on signed graphs consisting of the underlying graph and the class of positive circles, i.e., of the pair $(|\Sigma|, \mathcal{C}^+(\Sigma))$ (which constitutes a type of ‘biased graph’ [21]).

Switching equivalence and switching isomorphism are equivalence relations on signed graphs. An equivalence class under switching equivalence is a *switching equivalence class* of signed graphs. An equivalence class under switching isomorphism is a *switching isomorphism class*. (Many writers say ‘switching equivalence’ when they mean ‘switching isomorphism’, but I find it better to separate the two concepts.)

5. Switching isomorphism types

The most patently obvious signatures of the Petersen graph are $+P$ and $-P$. Two more are P_1 , which has only one negative edge, and its negative $-P_1$, with only one positive edge. Two more signatures are $P_{2,d}$ where $d = 2, 3$, which have two negative edges at distance d ; and the last two that mainly concern us are $P_{3,d}$ for $d = 2, 3$, which have three negative edges, all at distance d ; in $P_{3,2}$ the negative edges must be alternate edges of a hexagon. In terms of our classification of matchings, $P_{k,d} := P_{M_{k,d}}$; that is, $E^-(P_{k,d}) = M_{k,d}$. These signed graphs are illustrated in Fig. 1.2.

Theorem 5.1. *There are exactly six signed Petersen graphs up to switching isomorphism. They are $+P \simeq -P_{3,3}$, $P_1 \simeq -P_{2,3}$, $P_{2,2} \simeq -P_{2,2}$, $P_{2,3} \simeq -P_1$, $P_{3,2} \simeq -P_{3,2}$, and $P_{3,3} \simeq -P$.*

Proof. The first step is to establish the switching isomorphisms stated in the theorem. To switch $-P$ to $P_{3,3}$, switch an independent set $X = X_m$ of four vertices; this negates ∇X , leaving three negative edges, which have distance 3. If we begin with $-P_1$ with positive edge uv , by choosing X to contain neither u nor v we get $uv \notin \nabla X$, so, after switching, uv retains its sign; therefore $(-P_1)^X = P_{2,3}$. To switch $-P_{3,2}$, where the positive edges belong to a hexagon H_v , switch $N[v]$. This negates all edges except those of H_v , giving $P_{3,2}$, whose negative edges are the originally negative edges of the hexagon. To switch $-P_{2,2}$, note that the two positive edges e and f , having distance 2, lie in a unique pentagon J . Switch the three vertices of J that are not incident to e and the two vertices outside J that are adjacent to e . The result is $P_{2,2}$.

For the rest of the theorem we need two more steps. First, we must prove that every signed Petersen graph belongs to the switching isomorphism class of one of the six types $+P$, P_1 , $P_{k,d}$ listed in the theorem. This is implied by Theorem 7.2. Second, we must show that none of the six types is switching isomorphic to any other. The second step follows from the calculation of *invariants* of the six switching isomorphism classes, by which we mean numbers or other objects that are the same for every element of a switching isomorphism class. Relevant invariants are the numbers c_5^- and c_6^- of negative circles of lengths 5 and 6 (Theorem 6.1), the frustration index l (Theorem 7.2) and frustration number l_0 (Theorem 7.7), the switching automorphism groups (Theorem 8.12), and some chromatic invariants (Section 9). The six classes must be distinct because no two have all the same invariants. In fact, c_5^- and c_6^- suffice to distinguish them; and so do the numbers of proper 3-colorations (Theorem 9.4). \square

6. Circle signs

Lemma 4.1 leads to an effective method of distinguishing switching isomorphism classes, by comparing the numbers of negative circles of each length.

Theorem 6.1. *The numbers of negative pentagons and hexagons in each of the six signed Petersen graphs of Theorem 5.1 are those listed in Table 6.1.*

Proof. The Petersen graph has $c_5 = 12$ pentagons and $c_6 = 10$ hexagons. The number of cases to consider is lessened if we notice that negating (P, σ) leaves the number $c_6^-(P, \sigma)$ of negative hexagons the same but complements the number $c_5^-(P, \sigma)$ of negative pentagons to $c_5^-(P, -\sigma) = 12 - c_5^-(P, \sigma)$.

Table 6.1
The numbers of negative pentagons and hexagons in each switching isomorphism type.

(P, σ)	$+P$	P_1	$P_{2,2}$	$P_{2,3} \simeq -P_1$	$P_{3,2}$	$P_{3,3} \simeq -P$
Negative C_5 's	0	4	6	8	6	12
Negative C_6 's	0	4	6	4	10	0

For $+P$ both numbers are 0, and the values for $-P$ follow.

In P_1 there are as many negative pentagons, or hexagons, as the number of each that lie on a fixed edge e . There are four ways to add an edge at each end of e to get a path of length 3, and each such path completes uniquely to a pentagon or hexagon. Thus, $c_5^-(P_1) = c_6^-(P_1) = 4$. The numbers for $-P_1$ are immediate.

If we also negate an edge f at distance 2 from e , the number of negative k -gons equals $2(c_k^-(P_1) - d_k)$ where d_k is the number of k -gons that contain both e and f . It is easy to see that $d_5 = d_6 = 1$. (Use the 3-path transitivity of P , by which under the symmetries of P there is only one orbit of pairs of edges at distance 2.) It follows that $c_5^-(P_{2,2}) = c_6^-(P_{2,2}) = 6$.

For an f at distance 3 from e there is a similar calculation. However, f cannot lie in a common pentagon with e , so now $d_5 = 0$. The value of d_6 is not quite obvious. There are four ways to form a path of length 3 by extending e at each end. Inspection reveals that two of these paths cannot be completed to a hexagon on f , but the other two can be completed uniquely. Thus, $d_6 = 2$. We conclude that $c_5^-(P_{2,3}) = 8$ and $c_6^-(P_{2,3}) = 4$. \square

7. Frustration

The proofs of Theorems 5.1 and 9.4 make use of the measurement of imbalance by edges or vertices. The *frustration index* $l(\Sigma) :=$ the smallest number of edges whose deletion leaves a balanced signed graph. It is equivalent to finding the largest number of edges in a balanced subgraph of Σ , which is the signed-graph equivalent of the maximum cut problem in an unsigned graph; in fact, $l(-\Gamma) =$ the smallest number of edges whose complement is bipartite. The *frustration number* (or *vertex frustration number*) $l_0(\Sigma)$ is the smallest number of vertices whose deletion leaves a balanced signed graph. Its complement, $|V| - l_0$, is the largest order of a balanced induced subgraph. For an all-negative graph, $l_0(-\Gamma)$ is the smallest number of vertices whose deletion leaves a bipartite graph.

7.1. Frustration index

The frustration index is the most significant way to measure how unbalanced a signed graph is. For instance, in social psychology, $l(\Sigma)$ is the minimum number of relations that must change to achieve balance. In the non-ferromagnetic Ising model of spin-glass theory, the frustration index determines the ground-state energy of the spin glass. (The frustration index was called ‘complexity’ by Abelson and Rosenberg [1], who introduced the idea, and ‘line index of balance’ by Harary; my name for it was inspired by the picturesque terminology of Toulouse [16].)

Harary [10] proved that $l(\Sigma) =$ the smallest number of edges whose negation or deletion makes the signed graph balanced. (Negating an edge is equivalent to deleting it, so one can delete or negate the edges in any combination.) An edge set whose deletion leaves a balanced graph is called a *balancing set* (of edges); thus, $l(\Sigma) =$ the size of a minimum balancing set.

Lemma 7.1 (Implicit in [3]). *Switching does not change $l(\Sigma)$. Indeed, $l(\Sigma) = \min_{\zeta} |E^-(\Sigma^\zeta)|$, the minimum number of negative edges in a switching of Σ .*

That is, a signed graph has the smallest number of negative edges in its switching equivalence class if and only if $|E^-(\Sigma)| = l(\Sigma)$. Let us call Σ *minimal* if it satisfies this equation.

By Lemma 7.1, we can distinguish switching isomorphism classes by their having different frustration indices. This helps to prove the six signed P 's are not switching isomorphic.

Theorem 7.2. *There are precisely the following six isomorphism types of minimal signed Petersen graph: $+P, P_1, P_{2,2}, P_{3,2}, P_{2,3}$, and $P_{3,3}$. Each is the unique minimal isomorphism type in its switching isomorphism class. The frustration indices of the six types are as stated in Table 7.1.*

To find the frustration index of any signature of P , switch it to be minimal and consult the table. As frustration index is an NP-complete problem (its restriction to all-negative signatures is equivalent to the well known NP-complete maximum-cut problem) that may not be so easy, but in small examples like the Petersen graph Lemma 7.3 is a great help.

Proof. First we show that every signature of P switches to one of the six.

Lemma 7.3. *If every cut in Σ has at least as many positive as negative edges, then $l(\Sigma) = |E^-|$. If some cut has more negative than positive edges, then $l(\Sigma) < |E^-|$.*

Table 7.1
The frustration index of each switching isomorphism type.

(P, σ)	$+P$	P_1	$P_{2,2}$	$P_{2,3}$	$P_{3,2}$	$P_{3,3}$
$l(P, \sigma)$	0	1	2	2	3	3

Proof. If $|E^-(X, X^c)| > |E^+(X, X^c)|$, then switching X reduces the number of negative edges. If $|E^-(X, X^c)| \leq |E^+(X, X^c)|$ for every X , then no switching can reduce the number of negative edges; so $l(\Sigma) = |E^-|$ by Lemma 7.1. \square

Lemma 7.3 has a pleasing effect on a cubic graph.

Corollary 7.4. *In any minimal signature of a cubic graph, the negative edges are a matching.*

Thus, we need only examine all the automorphism types of matchings in P from Section 3. Let $E^- = M_k$, where $0 \leq k \leq 5$. Matchings of 0 or 1 edge are trivial: Σ is minimal. When $k = 2$, $E^- = M_{2,2}$ or $M_{2,3}$, so we have $P_{2,2}$ or $P_{2,3}$.

When $E^- = M_5$, switching the vertices of one of the pentagons separated by E^- makes all edges positive, which is $+P$. When $E^- = M_5 \setminus \text{edge}$ or $E^- = M'_3 = M_5 \setminus 2 \text{ edges}$, the same switching gives P_1 or $P_{2,2}$, respectively.

For $E^- = M'_4$, switch $\{v_{kl}, v_{ij}, v_{km}, v_{jl}\}$. This also results in $P_{2,2}$.

The last case is $E^- = M_{3,2/3}$. Here, we switch $\{v_{jk}, v_{jl}, v_{im}\}$, getting $P_{2,3}$.

This proves that every signature is switching isomorphic to one of the six basic types.

It remains to show that each of the six types is actually minimal. We have shown that a signature in which E^- is a matching is not minimal if it is not one of the six. Thus, if no two of the six are switching isomorphic, each must be the unique minimal element of its switching isomorphism class. The switching invariants c_5^- and c_6^- are enough to prove that none of the six can switch to any other. Thus, the theorem is proved. \square

Corollary 7.5. *In each switching equivalence class, and in each switching isomorphism class of signed Petersen graphs, there is exactly one minimal isomorphism type.*

The corollary cannot say that there is a unique minimal signature in each switching equivalence class, because that is false. In the switching equivalence class of $-P$ the unique minimal isomorphism type is $P_{3,3}$, but the exact choice of the three negative edges is not unique. The number of minimal graphs in that switching equivalence class equals the number of sets of three edges all at distance 3, which is 5.

It is a remarkable fact that not just some but every switching equivalence class, and every switching isomorphism class, of signed Petersens has only one minimal signature up to isomorphism. It is not surprising that some switching equivalence classes have this property, but that all do is. By way of contrast, K_n (with $n \geq 4$) has some switching equivalence classes with unique minimal elements, either absolutely or only up to isomorphism, and some with multiple minimal members. In the class of the signature $K_n(e)$, which has exactly one negative edge e , clearly the only minimal signed graph is $K_n(e)$. In the class of $-K_n$, the minimal elements are all the signatures of K_n where the positive edges form a cut of maximum size, i.e., where $V(K_n)$ is partitioned into two sets whose sizes differ by at most 1 [14]. There are many such signatures and all are switching equivalent to $-K_n$; but they are all isomorphic. Now, assume that $n = 2r + 1 \geq 5$ and consider one more signature, where the negative edges are e_{1i} for $i = 2, 3, \dots, r + 1$ and $e_{2,3}$. Here, E^- is a connected subgraph. This signature is minimal in its switching equivalence class, by Lemma 7.3. Switching v_1 , the negative edges are e_{1i} for $i = r + 2, r + 3, \dots, 2r + 1$ and $e_{2,3}$. The number of negative edges is unchanged, but they now form a disconnected subgraph. Thus, this switching equivalence class contains (at least) two minimal graphs that are not isomorphic. We see that for K_n there are switching equivalence classes whose minimal graph is unique, those in which the minimal graph is unique only up to isomorphism, and those with non-isomorphic minimal members.

Thus, the behavior of the Petersen signatures is not totally ordinary. I suspect it is unusual, but the truth is that no one knows whether, in regard to the uniqueness of either minimal signatures or isomorphism types of minimal signatures in either their switching equivalence or isomorphism class, most graphs resemble K_n or P .

7.2. Frustration number

The (vertex) frustration number has been less deeply explored than the frustration index, perhaps because it seems less suitable to the social psychology model and is certainly less relevant to spin-glass theory. Besides, it appears to be less subtle in distinguishing between different signatures of a graph, because most graphs have fewer vertices than edges. Nevertheless, we find a use for it in counting colorations in Section 9.

Lemma 7.6. *Switching does not change $l_0(\Sigma)$. Moreover, $l_0(\Sigma) \leq l(\Sigma)$ in every signed graph.*

Proof. The first part is obvious from Lemma 4.1, because imbalance depends only on the set of negative circles. The second part follows from the fact that, if we delete one endpoint from each edge of a minimum balancing edge set, we get a balanced subgraph by deleting at most l vertices. \square

Table 7.2
The frustration number of each switching isomorphism type.

(P, σ)	$+P$	P_1	$P_{2,2}$	$P_{2,3}$	$P_{3,2}$	$P_{3,3}$
$l_0(P, \sigma)$	0	1	2	2	3	3

Theorem 7.7. *The frustration numbers of signed Petersen graphs are given in Table 7.2. All have frustration number equal to the frustration index.*

Proof. Consult Fig. 1.2. The values for $+P$ and P_1 are obvious.

A signature that has two vertex-disjoint negative pentagons cannot have $l_0 < 2$; if the frustration index is 2, as in $P_{2,2}$ and $P_{2,3}$, that must be l_0 .

In $P_{3,2}$ the negative pentagons are the inner star and all pentagons with two outer edges. To achieve balance we must delete an inner vertex. Deleting one such vertex v gives $P_{3,2} \setminus v$, which is a subdivision of K_4 in which the paths corresponding to two opposite edges in K_4 are negative and the paths that correspond to other edges in K_4 are positive. Every circle in $P_{3,2} \setminus v$ that corresponds to a triangle of K_4 is negative. It is impossible to make this graph balanced by deleting only one vertex; hence $l_0(P_{3,2}) = 3$.

Because $P_{3,3}$ is antibalanced, every pentagon is negative. This means that a vertex set whose deletion makes for balance must cover all the pentagons. No two vertices can do that, as one can verify by inspecting adjacent and non-adjacent pairs; but any vertex neighborhood $N(v)$ does. Hence, $l_0(-P) = 3$.

Comparing Tables 7.1 and 7.2 shows that $l_0 = l$ in every case. \square

One can easily see that $l_0 = l$ is not true in general. However, I verified that equality holds for every signature of K_4 or $K_{3,3}$. I offer the following proposal.

Conjecture 7.1. *For every signed cubic graph Σ , $l_0(\Sigma) = l(\Sigma)$.*

8. Automorphisms and orbits

In this section, we develop a general theory of switching automorphism groups of signed graphs. Then we compute the automorphism and, more importantly, switching automorphism groups of the six basic signed Petersen graphs and their negatives. Lastly, we apply that information to find the number of isomorphic but switching-inequivalent copies of each of the six basic signatures.

We regard an automorphism of Γ as a permutation of V , and we write actions as superscripts, so products are read from left to right.

8.1. Automorphisms and switching automorphisms of signed graphs

An automorphism of a signed graph is an isomorphism with itself; that is, it is an automorphism of the underlying graph that preserves edge signs. A *switching automorphism* of a signed graph is a switching isomorphism with itself. (As with switching isomorphisms, cf. near Lemma 4.1, switching automorphisms really are automorphisms: of the biased graph $(|\Sigma|, \mathcal{C}^+(\Sigma))$.) The group of automorphisms is $\text{Aut}(\Sigma)$ and that of switching automorphisms is $\text{SwAut}(\Sigma)$.

8.1.1. Automorphisms

As concerns automorphisms, a signed graph is just a graph whose edges are colored with two colors; an automorphism is a color-preserving graph automorphism. There is not much to say except the following elementary observations.

Proposition 8.1. *For a signed graph $\Sigma = (\Gamma, \sigma)$,*

$$\text{Aut } \Sigma = \text{Aut } \Gamma \cap \text{Aut } \Sigma^+ = \text{Aut } \Gamma \cap \text{Aut } \Sigma^- = \text{Aut } \Sigma^+ \cap \text{Aut } \Sigma^-.$$

8.1.2. Switching permutations and switching automorphisms

Switching automorphisms are more complicated; to treat them we need precise definitions and notation. We begin with the action of automorphisms of Γ upon signatures:

$$\sigma^\alpha(v^\alpha w^\alpha) := \sigma(vw),$$

and $\Sigma^\alpha := (\Gamma, \sigma^\alpha)$. The action of an automorphism on a switching function is similar:

$$\zeta^\alpha(v^\alpha) := \zeta(v).$$

This leads to the commutation law

$$\zeta\alpha = \alpha\zeta^\alpha, \tag{8.1}$$

because

$$\sigma^{\zeta^\alpha}(v^\alpha w^\alpha) = (\sigma^\zeta)^\alpha(v^\alpha w^\alpha) = \sigma^\zeta(vw) = \zeta(v)\sigma(vw)\zeta(w),$$

while

$$\sigma^{\alpha\zeta^\alpha}(v^\alpha w^\alpha) = (\sigma^\alpha)^{\zeta^\alpha}(v^\alpha w^\alpha) = \zeta^\alpha(v^\alpha)\sigma^\alpha(v^\alpha w^\alpha)\zeta^\alpha(w^\alpha) = \zeta(v)\sigma(vw)\zeta(w).$$

Rewriting (8.1) as $\alpha^{-1}\zeta\alpha = \zeta^\alpha$, we see that the action of α is that of conjugation, as the notation suggests. Rewriting it in terms of ζ_X , we obtain the important equation

$$(\zeta_X)^\alpha = \zeta_{X^\alpha}, \tag{8.2}$$

since $\zeta_X^\alpha(v^\alpha) = \zeta_X(v) = \zeta_{X^\alpha}(v^\alpha)$.

Now, we can define a preliminary group to the switching automorphism group. The ground set is $\{+, -\}^V \times \text{Aut } \Gamma$, whose elements we call, for lack of a better name, *switching permutations of Γ* , because when they act on a signature of Γ they switch signs and permute the vertices. A *switching permutation of Σ* is any $\zeta\gamma \in \{+, -\}^V \times \text{Aut } \Gamma$ such that $\Sigma^{\zeta\gamma} = \Sigma$. The multiplication rule is

$$(\zeta, \alpha)(\eta, \beta) = (\zeta\eta^{\alpha^{-1}}, \alpha\beta).$$

Because $\{+, -\}^V$ and $\text{Aut } \Gamma$ embed naturally into $\{+, -\}^V \times \text{Aut } \Gamma$ as $\{+, -\}^V \times \{\text{id}\}$ and $\{\varepsilon\} \times \text{Aut } \Gamma$, we regard them as subgroups of $\{+, -\}^V \times \text{Aut } \Gamma$, and we write the element (ζ, α) as a product, $\zeta\alpha$. The equation of multiplication is given by the next lemma.

Lemma 8.2. *The product of switching permutations $\zeta_X\gamma$ and $\zeta_Y\xi$, where $\zeta_X, \zeta_Y \in \{+, -\}^V$ and $\gamma, \xi \in \text{Aut } \Gamma$, is given by*

$$\zeta_X\gamma \cdot \zeta_Y\xi = \zeta_X\zeta_{\gamma^{-1}} \cdot \gamma\xi. \tag{8.3}$$

The inverse of a switching permutation is

$$(\zeta_X\gamma)^{-1} = \zeta_{X^\gamma}\gamma^{-1}. \tag{8.4}$$

Proof. The product formula is a restatement of the previous equations. We verify the inversion formula with a short calculation:

$$\zeta_{X^\gamma}\gamma^{-1} \cdot \zeta_X\gamma = \zeta_{X^\gamma}\zeta_{X^\gamma} \cdot \gamma^{-1}\gamma = \zeta_{X^\gamma \oplus X^\gamma} \text{id} = \varepsilon \text{id},$$

by (8.2). \square

The commutation laws (8.1) and (8.2) imply that the conjugate of a switching function by an automorphism is another switching function. Consequently, $\{+, -\}^V$ is a normal subgroup. This makes the group of switching permutations a semidirect product of $\{+, -\}^V$ and $\text{Aut } \Gamma$, so we write it as $\{+, -\}^V \rtimes \text{Aut } \Gamma$. We write p_A for the projection onto $\text{Aut } \Gamma$.

The action of $\{+, -\}^V \rtimes \text{Aut } \Gamma$ on signed graphs (Γ, σ) has kernel $\mathfrak{K}_\Gamma \times \{\text{id}\}$. The quotient group is the *switching automorphism group of Γ* ,

$$\text{SwAut } \Gamma := (\{+, -\}^V \rtimes \text{Aut } \Gamma) / (\mathfrak{K}_\Gamma \times \{\text{id}\}).$$

Since $\text{Sw } \Gamma$ can be identified with the normal subgroup $\text{Sw } \Gamma \times \{\text{id}\}$, \mathfrak{K}_Γ with $\mathfrak{K}_\Gamma \times \{\text{id}\}$, and $\text{Aut } \Gamma$ with the subgroup $\{\varepsilon\} \times \text{Aut } \Gamma$, the switching automorphism group of Γ is a semidirect product,

$$\text{SwAut } \Gamma = \text{Sw } \Gamma \rtimes \text{Aut } \Gamma,$$

which projects onto $\text{Aut } \Gamma$ by a mapping \bar{p}_A . We refer to elements of $\text{SwAut } \Gamma$ as *switching automorphisms of Γ* . (This is a slight abuse of terminology, since they do not actually switch Γ ; they switch signatures of Γ .)

A switching automorphism of Γ can be written in several equivalent ways. As a member of $(\{+, -\}^V \rtimes \text{Aut } \Gamma) / (\mathfrak{K}_\Gamma \times \{\text{id}\})$, it is $(\bar{\zeta}, \bar{\alpha}) = \bar{\zeta}\bar{\alpha}$. As a member of $\text{Sw } \Gamma \rtimes \text{Aut } \Gamma$, it is $(\bar{\zeta}, \alpha) = \bar{\zeta}\alpha$. By the natural embeddings, $\bar{\zeta}\text{id} = \bar{\zeta}\text{id} = \bar{\zeta}$ and $\bar{\varepsilon}\alpha = \bar{\varepsilon}\alpha = \alpha$. In particular, the identity element of $\text{SwAut } \Gamma$ is $\bar{\varepsilon}\text{id} = \bar{\varepsilon}\text{id} = \text{id}$. Lemma 8.2 applies in $\text{SwAut } \Gamma$ simply by putting a bar over the switching functions. (Sometimes we omit the bar, as it is obvious which element of $\text{SwAut } \Gamma$ is meant by $\zeta\alpha$.)

The switching automorphism group of Γ contains the switching automorphism group of each signed graph $\Sigma = (\Gamma, \sigma)$. The latter group is

$$\text{SwAut } \Sigma := \{\bar{\zeta}\alpha : \alpha \in \text{Aut } \Gamma \text{ and } \alpha : \Sigma^\zeta \cong \Sigma\}.$$

That is, α must be an isomorphism from the switched signed graph to the original signed graph. This group projects into $\text{Aut } \Gamma$ by the mapping $\bar{p}_A|_{\text{SwAut } \Sigma}$, which for simplicity we also write as \bar{p}_A . We identify $\text{Aut } \Sigma$ with the subgroup $\{\bar{\varepsilon}\alpha \in \text{SwAut } \Gamma : \alpha \in \text{Aut } \Sigma\}$. Note that a switching permutation of Σ is any switching permutation of Γ such that $\zeta\gamma \in \text{SwAut } \Sigma$.

8.1.3. Automorphisms and switching automorphisms

Now, we can state relationships amongst the automorphisms and switching automorphisms of Σ and the automorphisms of Γ .

Proposition 8.3. *As a function from $\text{SwAut } \Sigma$ to $\text{Aut } \Gamma$, \bar{p}_A is a monomorphism. The groups satisfy $\text{Aut } \Sigma \leq \bar{p}_A(\text{SwAut } \Sigma) \leq \text{Aut } \Gamma$.*

Proof. It is obvious that \bar{p}_A is a homomorphism. To prove it is injective, we examine a switching function ζ such that $\zeta \text{ id}$ is a switching automorphism. This means that $\Sigma^\zeta = \Sigma$; in other words, $\zeta \in \mathfrak{R}_\Gamma$. But that means that the only element of the form $\bar{\zeta} \text{ id}$ in $\text{SwAut } \Sigma$ is the trivial one, $\bar{\varepsilon} \text{ id}$. Hence, \bar{p}_A is injective.

The relationships of the groups are now obvious. \square

Another relationship makes an obvious but valuable lemma.

Lemma 8.4. *The automorphisms of Σ are the automorphisms of $|\Sigma|$ that stabilize Σ^+ , or equivalently Σ^- .*

Switching automorphisms of homogeneously signed graphs are not very interesting in themselves.

Proposition 8.5. *The automorphisms and the switching automorphisms of a homogeneous signature, $+\Gamma$ or $-\Gamma$, are the automorphisms of the underlying graph.*

Proof. This follows at once from Lemma 8.4. \square

A heterogeneously signed graph, in contrast, is likely to have switching automorphisms that are not automorphisms of the signed graph. We see this in most, though not all, of the heterogeneous signatures of P .

Switching can change the automorphism group drastically. Fortunately, the isomorphism type of the switching automorphism group is invariant under switching. In addition, negations need not be considered separately.

Proposition 8.6. *$\text{Aut}(-\Sigma) = \text{Aut}(\Sigma)$ and $\text{SwAut}(-\Sigma) = \text{SwAut}(\Sigma)$. Also, $\text{SwAut}(\Sigma^\zeta) \cong \text{SwAut}(\Sigma)$ by the mapping $\bar{\eta}\gamma \mapsto \bar{\zeta}\bar{\eta}\gamma$.*

Proof. The first statement is immediate from Lemma 8.4.

The second follows from considering how a switching automorphism acts. (ζ, α) is a switching automorphism of Σ if and only if $\Sigma^\zeta \cong \Sigma$, the isomorphism being via α . This means that the same graph automorphism is an isomorphism both of $(\Sigma^\zeta)^+ \cong \Sigma^+$ and of $(\Sigma^\zeta)^- \cong \Sigma^-$. It follows that $\zeta\alpha$ is a switching automorphism of $-\Sigma$ under exactly the same conditions as it is a switching automorphism of Σ .

For the third statement, we simply write down the action of $\bar{\eta}\gamma$: it converts Σ^ζ to $(\Sigma^\zeta)^{\eta\gamma} = \Sigma^{\bar{\zeta}\bar{\eta}\gamma}$. \square

Corollary 8.7. *Switching Σ does not change the automorphisms in the switching automorphism group: $p_A(\text{SwAut } \Sigma^\zeta) = p_A(\text{SwAut } \Sigma)$ for any switching function ζ .*

Proof. Examine the mapping in Proposition 8.6. \square

Suppose that $\zeta\alpha$ is a switching automorphism. Since $(\Sigma^\zeta)^- \cong \Sigma^-$, the switching cannot change the number of negative edges. As switching means negating the signs of edges in a cut, the cut must have equally many positive and negative edges. Thus we have a necessary condition for a switching automorphism.

Proposition 8.8. *If $\zeta_X\alpha$ is a switching automorphism of Σ , then ∇X has equally many edges of each sign.* \square

8.1.4. Coset representation

We treat multiplication in a switching automorphism group $\text{SwAut } \Sigma$ through the left cosets of $\text{Aut } \Sigma$. Choose a system \bar{R} of representatives of the cosets and a system R of representatives $\zeta_X\gamma_X \in \{+, -\}^V \rtimes \text{Aut } \Gamma$ of the elements $\bar{\zeta}_X\gamma_X \in \bar{R}$. Then $\text{SwAut } \Sigma$ is the disjoint union of the left \bar{R} -cosets of $\text{Aut } \Sigma$:

$$\text{SwAut } \Sigma = \bigcup_{\bar{\zeta}_X\gamma_X \in \bar{R}} \bar{\zeta}_X\gamma_X \text{Aut } \Sigma. \tag{8.5}$$

Thus we have two levels of representation: a switching automorphism $\bar{\zeta}_X\gamma_X$ representing each coset, and a switching permutation $\zeta_X\gamma_X$ to represent each $\bar{\zeta}_X\gamma_X \in \bar{R}$. Note that ζ_X and $\zeta_{X^c} = -\zeta_X$ are equally valid representatives of $\bar{\zeta}_X$; thus we can choose X so that $|X| \leq \frac{1}{2}|V|$.

Proposition 8.9. *The following three statements about two switching automorphisms, $\bar{\zeta}_X\gamma$ and $\bar{\zeta}_Y\xi \in \text{SwAut } \Sigma$, are equivalent.*

- (i) *They belong to the same coset of $\text{Aut } \Sigma$ in $\text{SwAut } \Sigma$.*
- (ii) *They have the same switching operation, $\bar{\zeta}_X = \bar{\zeta}_Y$.*
- (iii) *γ and ξ belong to the same coset of $\text{Aut } \Sigma$ in $\text{Aut } \Gamma$.*

Proof. The switching automorphisms are in the same coset \iff there is an $\alpha \in \text{Aut } \Sigma$ such that $\bar{\zeta}_X \gamma = \bar{\zeta}_Y \xi \alpha$. Because $\text{SwAut } \Sigma \subseteq \text{SwAut } \Gamma$ and \bar{p}_A is a monomorphism, this implies (iii), $\gamma = \xi \alpha \in \xi \text{Aut } \Sigma$, and (ii), $\bar{\zeta}_X = \bar{\zeta}_Y$.

Now suppose that (ii) holds, i.e., there are cosets $\bar{\zeta}_X \gamma \text{Aut } \Sigma$ and $\bar{\zeta}_X \xi \text{Aut } \Sigma$ with the same switched set X . Then $(\bar{\zeta}_X \gamma)^{-1}(\bar{\zeta}_X \xi) \in \text{Aut } \Sigma$. Simplifying, $(\bar{\zeta}_X \gamma)^{-1}(\bar{\zeta}_X \xi) = \gamma^{-1} \bar{\zeta}_X^{-1} \bar{\zeta}_X \xi = \gamma^{-1} \xi$. Thus, $\gamma^{-1} \xi \in \text{Aut } \Sigma$, which implies (iii).

Finally, suppose that (iii) holds, i.e., $\xi = \gamma \alpha$. Then $\bar{\zeta}_X \gamma = \bar{\zeta}_Y \gamma \alpha$. As in the first part of the proof, this implies (ii), $\bar{\zeta}_X = \bar{\zeta}_Y$, and consequently $\bar{\zeta}_Y \xi = \bar{\zeta}_X \gamma \alpha \in \bar{\zeta}_X \gamma \text{Aut } \Sigma$, which is (i). \square

Corollary 8.10. Each left coset representative $\bar{\zeta}_X \gamma_X \in \bar{R}$ has a different switching function $\bar{\zeta}_X$.

By Corollary 8.10, X determines γ_X ; thus, we define

$$\rho_X := \bar{\zeta}_X \gamma_X := \text{the unique element of } R \text{ that has switching set } X.$$

Also, define $\rho_{X^c} = \bar{\zeta}_{X^c} \gamma_{X^c}$. Then $\bar{\rho}_X = \bar{\rho}_{X^c}$, because $\bar{\zeta}_X = -\bar{\zeta}_{X^c} = \bar{\zeta}_{X^c}$. Thus, assuming that Σ is connected, each $\bar{\rho} \in \bar{R}$ has associated switching sets X and X^c , each of which serves equally well to represent $\bar{\rho}$. (There are only two if Γ is connected, because then $\bar{K}_\Gamma = \{\pm \varepsilon\}$.)

The task now is to express the product of switching automorphisms in terms of coset representatives. In the next subsection, we do that for the more complicated signed Petersen examples by setting up multiplication tables for R , which combine with a general formula to give all products. Here, we explain the format of such tables and obtain the general product formula.

The product of representatives, $\bar{\zeta}_X \gamma_X \cdot \bar{\zeta}_Y \gamma_Y$, has the form $(\zeta_U \gamma_U) \nu$, where $\zeta_U \gamma_U \in R$ and the permutation $\nu \in \text{Aut } \Sigma$ is a correction due to the fact that the product of representatives need not be a representative itself. We need formulas for U and ν in terms of R . (The application to \bar{R} consists merely of placing bars over the switching functions.) For simplicity, we assume that Σ is connected, to ensure that $\bar{\zeta}_U$ is represented only by ζ_U or $\zeta_{U^c} = -\zeta_U$.

Proposition 8.11. Assume that $\Sigma = (\Gamma, \sigma)$ is connected. For switching automorphisms $(\bar{\zeta}_X \gamma_X) \alpha$ and $(\bar{\zeta}_Y \gamma_Y) \beta$, where $\bar{\zeta}_X \gamma_X, \bar{\zeta}_Y \gamma_Y \in R$ and $\alpha, \beta \in \text{Aut } \Sigma$, there is the multiplication formula

$$(\bar{\zeta}_X \gamma_X) \alpha \cdot (\bar{\zeta}_Y \gamma_Y) \beta = (\pm \zeta_U \gamma_U) \nu \cdot \alpha \beta, \tag{8.6}$$

where $U = X \oplus Y^{\alpha^{-1} \gamma_X^{-1}}$, γ_U and the sign are determined by $\pm \zeta_U \gamma_U \in R$, and $\nu = \gamma_U^{-1} \gamma_X \gamma_Y^{\alpha^{-1}} \in \text{Aut } \Sigma$.

Proof. Most of the proof is a calculation:

$$\begin{aligned} (\bar{\zeta}_X \gamma_X) \alpha \cdot (\bar{\zeta}_Y \gamma_Y) \beta &= (\zeta_X \gamma_X) (\zeta_Y^{\alpha^{-1}} \gamma_Y^{\alpha^{-1}}) \cdot \alpha \beta \\ &= (\zeta_X \gamma_X) (\zeta_{Y^{\alpha^{-1} \gamma_X^{-1}}} \gamma_Y^{\alpha^{-1}}) \cdot \alpha \beta \\ &= (\zeta_X \zeta_{Y^{\alpha^{-1} \gamma_X^{-1}}}^{\gamma_X^{-1}}) (\gamma_X \gamma_Y^{\alpha^{-1}}) \cdot \alpha \beta \\ &= (\zeta_X \zeta_{Y^{\alpha^{-1} \gamma_X^{-1}}}^{\gamma_X^{-1}}) (\gamma_X \gamma_Y^{\alpha^{-1}}) \cdot \alpha \beta \\ &= \zeta_{X \oplus Y^{\alpha^{-1} \gamma_X^{-1}}} (\gamma_X \gamma_Y^{\alpha^{-1}}) \cdot \alpha \beta. \end{aligned}$$

By Corollary 8.10, $\bar{\zeta}_U$ determines $\gamma_U \in \text{Aut } \Gamma$ such that $\bar{\zeta}_U \gamma_U \in \bar{R}$; consequently,

$$(\bar{\zeta}_X \gamma_X) \alpha \cdot (\bar{\zeta}_Y \gamma_Y) \beta = (\pm \zeta_U \gamma_U) (\gamma_U^{-1} \gamma_X \gamma_Y^{\alpha^{-1}}) \cdot \alpha \beta.$$

The sign is determined by whether $U := X \oplus Y^{\alpha^{-1} \gamma_X^{-1}}$ or its complement is the set U' switched by the representative $\zeta_{U'} \gamma_{U'} \in R$. In the former case, $U' = U$ and the sign is $+$, while, in the latter case, $U' = U^c$, which introduces the minus sign. U' must be one or the other, because switching any other set will give some edge in a spanning tree a different sign.

The reason that $\nu \in \text{Aut } \Sigma$ is that, by the definition of U , $(\bar{\zeta}_X \gamma_X) \alpha \cdot (\bar{\zeta}_Y \gamma_Y) \beta \in \bar{\zeta}_U \gamma_U \text{Aut } \Sigma$. Thus, $\nu \cdot \alpha \beta \in \text{Aut } \Sigma$, which entails that $\nu \in \text{Aut } \Sigma$. \square

Ideally, to use Eq. (8.6) in conjunction with the multiplication table of R , one first finds $Y' := Y^{\alpha^{-1}}$, then looks up the product $(\pm \rho_U) \nu = \rho_X \rho_{Y'}$ in the table and combines it with $\alpha \beta$. (It is not necessary to find $Y^{\alpha^{-1} \gamma_X^{-1}}$ or U .) For this method to work, R should be closed under conjugation by $\text{Aut } \Sigma$. With $\Sigma = P_{3,2}$ and $P_{3,3}$, one can choose R suitably; that is, so it is a union of orbits of $\text{Aut } \Sigma$ acting on $\text{SwAut } \Sigma$. However, it may not always be possible to choose such an ideal system of representatives.

Question 8.1. Does a system of representatives \bar{R} , or R , that is closed under conjugation by $\text{Aut } \Sigma$ exist for every signed graph?

A necessary condition for such a system is that, if $(\zeta_X \gamma_X)^\alpha$ is in the same coset as $\zeta_X \gamma_X$, then it must equal $\zeta_X \gamma_X$. Thus γ_X should commute with every automorphism α of Σ for which $\bar{\zeta}_{X^\alpha} = \bar{\zeta}_X$ (equivalently when Σ is connected, $X^\alpha = X$ or X^c).

Table 8.1

The automorphism and switching automorphism groups of the minimal signed Petersens and their negatives. $\mathfrak{S}_k, \mathfrak{A}_k, \mathfrak{D}_k,$ and \mathfrak{Z}_k are the symmetric and alternating groups on k letters, the dihedral group of a k -gon, and the cyclic group of order k . \mathfrak{V}_4 is the Klein four-group.

(P, σ)	$\text{Aut}(P, \sigma)$	$\text{SwAut}(P, \sigma)$
$+P, -P$	\mathfrak{S}_5	\mathfrak{S}_5
$P_1, -P_1$	\mathfrak{D}_4	\mathfrak{D}_4
$P_{2,2}, -P_{2,2}$	\mathfrak{Z}_2	\mathfrak{V}_4
$P_{2,3}, -P_{2,3}$	\mathfrak{D}_4	\mathfrak{D}_4
$P_{3,2}, -P_{3,2}$	\mathfrak{S}_3	\mathfrak{A}_5
$P_{3,3}, -P_{3,3}$	\mathfrak{S}_4	\mathfrak{S}_5

Table 8.2

The exact groups corresponding to specific negative edge sets. i, j, k, l, m are the five elements of $\{1, 2, 3, 4, 5\}$, in any order. For $\mathfrak{E} \leq \mathfrak{S}_n, \mathfrak{E}^+$ denotes the set of even permutations in \mathfrak{E} . ζ_X is the switching function that switches $X \subseteq V$ (with ij denoting vertex v_{ij} for readability).

(P, σ)	$\text{Aut}(P, \sigma)$	$\text{SwAut}(P, \sigma)$
$+P, -P$	$\mathfrak{S}_{\{1,2,3,4,5\}}$	$\{\bar{\varepsilon}\} \times \mathfrak{S}_{\{1,2,3,4,5\}}$
$P_1, -P_1$ with $E^- = \{v_{ij}v_{kl}\}$	$\langle (ij), (ikjl) \rangle$	$\{\bar{\varepsilon}\} \times \langle (ij), (ikjl) \rangle$
$P_{2,2}, -P_{2,2}$ with $E^- = \{v_{il}v_{jm}, v_{kl}v_{im}\}$	$\langle (jk)(lm) \rangle$	$\langle \bar{\varepsilon}(jk)(lm), \zeta_{\{jm,kl\}}(jl)(km) \rangle$
$P_{2,3}, -P_{2,3}$ with $E^- = \{v_{ik}v_{jl}, v_{il}v_{jk}\}$	$\langle (ij), (ikjl) \rangle$	$\{\bar{\varepsilon}\} \times \langle (ij), (ikjl) \rangle$
$P_{3,2}, -P_{3,2}$ with $E^- = \{v_{il}v_{jm}, v_{kl}v_{im}, v_{ij}v_{km}\}$	$\langle \mathfrak{S}_{\{i,j,k\}} \times \mathfrak{S}_{\{l,m\}} \rangle^+$	See Eq. (8.11)
$P_{3,3}, -P_{3,3}$ with $E^- = \{v_{ij}v_{kl}, v_{ik}v_{jl}, v_{il}v_{jk}\}$	$\mathfrak{S}_{\{i,j,k,l\}}$	See Eq. (8.9)

8.2. Petersen automorphisms and switching automorphisms

Here, we find the automorphism and switching automorphism groups of the six minimal signed Petersen graphs and their negatives. Between them, they have six automorphism groups and six switching automorphism groups, but only four abstract types of switching automorphism group. By Proposition 8.6, the negative signature, $(P, -\sigma)$, has exactly the same groups as does (P, σ) , and furthermore $\text{SwAut}(P_{3,3}) \cong \text{SwAut}(-P)$ and $\text{SwAut}(P_{2,3}) \cong \text{SwAut}(-P_1)$. By Propositions 8.5 and 8.5, both groups of $+P$ and $-P$ equal $\text{Aut}(P) = \mathfrak{S}_5$. Thus, as abstract groups, we have five automorphism groups and three switching automorphism groups to discover; but there are five switching automorphism groups to find as explicit subgroups of $\text{SwAut } P$.

Theorem 8.12. *The abstract automorphism and switching automorphism groups of the minimal signed Petersen graphs and their negatives are as shown in Table 8.1. As subgroups of $\text{SwAut } P$, they are shown in Table 8.2.*

We preface the proof with a structural lemma.

Lemma 8.13. *Let (P, σ) be a minimal signature of P . Suppose that ∇X is a cut that contains equally many edges of each sign, as when X is switched in a switching automorphism. Then*

- (a) $|\nabla X| = 4, X = V(e_0)$ for some edge e_0 , and $(P, \sigma) = P_{k,2}$ for $k = 2$ or 3 , or
- (b) $|\nabla X| = 6, X = V(Q)$ for a path Q of order 4, and $(P, \sigma) = P_{3,2}$, or
- (c) $|\nabla X| = 6, X = N[v]$ for some vertex v , and $(P, \sigma) = P_{3,3}$.

Note that Lemma 8.13 does not apply to a switching automorphism in which there is no switching.

Proof. Suppose that the subgraph $P:X$ induced on X , with edge set $E:X$, is disconnected; then ∇X is the disjoint union of two or more cuts, hence it has at least six edges. As (P, σ) is minimal, there are no more than three negative edges; hence $|\nabla X| = 6$, and X consists of two non-adjacent vertices. Then ∇X does not contain three independent edges; by Corollary 7.4 this case is impossible.

Therefore $P:X$ is connected, so $|\nabla X| = 3|X| - 2|E:X|$. As $|\nabla X|$ is even, this implies that $|X|$ is even, so we may assume that $|X| \leq 4$. Then $P:X$ is acyclic; being connected, it is a tree. Consequently, $|E:X| = |X| - 1$, and we deduce that $|\nabla X| = |X| + 2$.

If the cut has four edges, $|X| = 2$; so $X = V(e_0)$ for some edge e_0 and ∇X consists of the four edges adjacent to e_0 . Amongst them the largest distance is 2. It follows that $(P, \sigma) = P_{k,2}$ as in (a).

If the cut has six edges, $|X| = 4$. $P:X$ is a tree which may be either a path Q of length 3 or a vertex star. If it is a path Q , then $X = V(Q)$, and the six edges of ∇X contain no three edges at distance 3 from one another. Hence, $d = 2$, and we have (b). If $P:X$ is a vertex star, $X = N[v]$ for some $v \in V$. In this case, $d = 3$, since it is not possible to choose three edges in ∇X whose distances are all 2. Thus, we are in case (c). \square

Proof of Theorem 8.12. In the course of the proof, we establish many important facts about the groups, in particular multiplication tables for the most complicated ones, $\text{SwAut } P_{2,3}$ and $\text{SwAut } P_{3,3}$. The proofs of these facts could not easily be separated from that of the main theorem, so it seemed best, though unconventional, to incorporate them all, including their formal statements, into one large proof. In order to keep the reader (and the author) from getting lost, the proof is divided into subsections treating different aspects.

The groups of $+P$ follow from Proposition 8.5. We take up the others in turn.

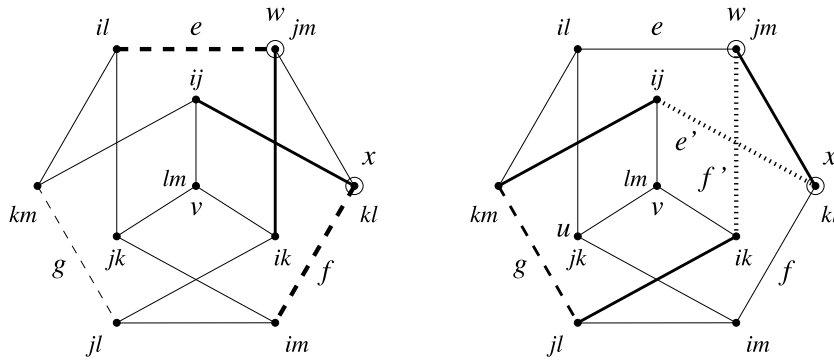


Fig. 8.1. Switching two positively adjacent vertices (circled) on the principal hexagon in $P_{3,2}$ for Case (a). Left: $P_{\{e,f,g\}}$, before switching. The principal hexagon H_v is the outer hexagon. Heavy lines indicate the cut ∇X . Right: $P_{\{e,f,g\}}^X$, after switching $X = \{v_{jm}, v_{kl}\}$. Heavy lines indicate the new principal hexagon H_u and dotted lines mark the two new negative edges.

8.2.1. Signatures of type P_1 .

The automorphism group of P_1 is the stabilizer of an edge in $\text{Aut } P$. Suppose P_1 to have negative edge $e = v_{ij}v_{kl}$; i.e., it is $P_{\{e\}}$. An automorphism α can preserve the vertices; then it is in the four-element group generated by (ij) and (kl) . Or, it can exchange the vertices; this is done, for instance, by a permutation $(ikjl)$. The group $\langle (ij), (kl), (ikjl) \rangle$ is the dihedral group of a square with corners labelled, in circular order, i, k, j, l ; it is generated by (ij) and $(ikjl)$.

Due to Proposition 8.8 and the fact that no cut in P has fewer than three edges, there are no switching automorphisms of P_1 other than its automorphisms.

8.2.2. Signatures of type $P_{2,d}$.

We write $P_{\{e,f\}}$ for $P_{2,d}$ with negative edges e and f . An automorphism of $P_{\{e,f\}}$ preserves $\{e, f\}$.

In $P_{2,3}$, there is a unique third edge g at distance 3 from e and f forming a matching $M_{3(m)}$. As any edge in $M_{3(m)}$ determines the whole matching, an automorphism of P that stabilizes $\{e, f\}$ must fix g , and vice versa. Thus, $\text{Aut } P_{\{e,f\}} = \text{Aut } P_{\{g\}}$.

In $P_{2,2} = P_{\{e,f\}}$, e and f are at distance 2 in a hexagon H_{lm} . The hexagon is uniquely determined by $\{e, f\}$. There is a unique edge g at distance 2 from e and f in H . Let $e = v_{il}v_{jm}, f = v_{kl}v_{im}$, and $g = v_{jl}v_{km}$. Since an automorphism α of $P_{\{e,f\}}$ preserves distance, the adjacent vertices v_{jm}, v_{kl} of E^- are either fixed or interchanged, and the remaining vertices v_{il}, v_{im} are also fixed or interchanged. This implies that i is fixed under α , so α , if not the identity, transposes l and m , and consequently $\alpha = \text{id}$ or $(jk)(lm)$. Hence, $\text{Aut } P_{\{e,f\}} = \langle (jk)(lm) \rangle \cong \mathbb{Z}_2$, the cyclic group of order 2.

Now, let us examine possible switching automorphisms $\zeta_X \gamma$ of $P_{\{e,f\}} = P_{2,d}$ for $d = 2, 3$. By Lemma 8.13, $|\nabla X| = 4$ and $P_{\{e,f\}} = P_{2,2}$. It follows that a non-trivial switching of $P_{2,3}$ cannot be isomorphic to $P_{2,3}$, so $\text{SwAut } P_{2,3} = \{\bar{\epsilon}\} \times \text{Aut } P_{2,3}$. There is a non-trivial switching of $P_{2,2}$ by $X = \{v_{jm}, v_{kl}\}$ forming new negative edges $e' = v_{jm}v_{ik}$ and $f' = v_{kl}v_{im}$, so γ must fix i and transpose either j, l and k, m or else j, m and k, l . Thus, $\gamma = (jl)(km)$ or $(jm)(kl)$. We conclude that

$$\text{SwAut } P_{\{e,f\}} = \{\bar{\epsilon} \text{ id}, \bar{\epsilon} (jk)(lm), \zeta_{\{jm,kl\}}(jl)(km), \zeta_{\{jm,kl\}}(jm)(kl)\}.$$

8.2.3. Signatures of type $P_{3,d}$.

The next groups are those of $P_{3,d} = P_{\{e,f,g\}}$ for $d = 2, 3$. For each distance d , choose the same negative edges e, f, g as in the previous analyses of $P_{2,d}$. In $P_{3,2}$, the negative edges lie in the hexagon $H = H_{lm} = P \setminus N[v_{lm}]$. In $P_{3,3}$, the negative edges are $e = v_{ij}v_{kl}, f = v_{ik}v_{jl}, g = v_{il}v_{jk}$, so $E^- = M_{3(m)}$.

We begin with the automorphism groups.

To determine $\text{Aut } P_{3,2}$, note that the hexagon containing e, f, g is $H_v = P \setminus N[v]$ for $v = v_{lm}$. An automorphism α of $P_{\{e,f,g\}}$ must fix v and thus must fix or exchange l and m . It can also permute the other indices i, j, k . Suppose that α fixes l and m . As the vertices of H_v , in order, are $v_{li}, v_{mk}, v_{lj}, v_{im}, v_{lk}, v_{jm}$, with vertex indices alternating between l and m , and as α must preserve the set $\{e, f, g\}$, it must rotate H_v by a multiple of one-third of a full rotation. This means that it permutes i, j, k cyclically, so it is a power of (ijk) . Now, suppose that α exchanges l with m . Then it reverses the direction of H_v , so in order to leave $\{e, f, g\}$ invariant it must fix one of e, f, g and one of i, j, k ; thus, $\alpha = (ij)(lm), (ik)(lm)$, or $(jk)(lm)$. The conclusion is that α is an even permutation of $\{1, 2, 3, 4, 5\}$ and is an element of $\mathfrak{S}_{\{l,m\}} \times \mathfrak{S}_{\{i,j,k\}}$. Thus, $\text{Aut } P_{\{e,f,g\}} = (\mathfrak{S}_{\{l,m\}} \times \mathfrak{S}_{\{i,j,k\}})^+$, the superscript $+$ denoting even permutations only. As the factor (lm) is predictable by evenness given the $\mathfrak{S}_{\{i,j,k\}}$ part of an automorphism, $\text{Aut } P_{3,2} \cong \mathfrak{S}_3$.

The automorphism group of $P_{3,3}$ is determined by the fact that the negative edge set $\{e, f, g\} = M_{3(m)}$. An automorphism permutes e, f, g , whence it permutes i, j, k, l arbitrarily and fixes m . Thus, $\text{Aut } P_{\{e,f,g\}} = \mathfrak{S}_{\{i,j,k,l\}} \cong \mathfrak{S}_4$.

Now, we examine the switching automorphism groups. We assume that $P_{3,d} = P_{\{e,f,g\}}$ switches by X to $P_{\{e',f',g'\}}$. Lemma 8.13 presents three cases to consider.

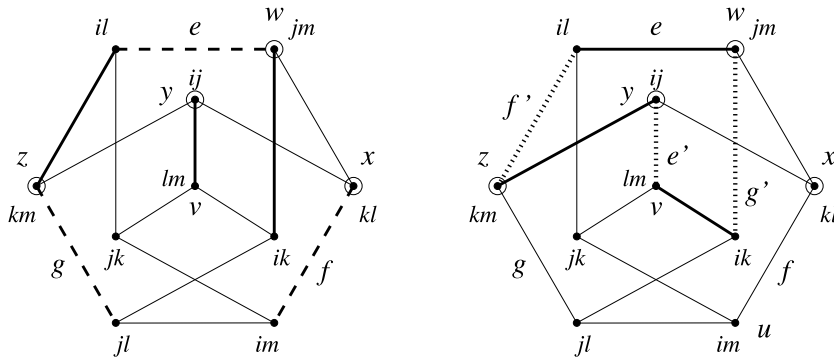


Fig. 8.2. Switching the four vertices of a path in $P_{3,2}$ for Case (b). Left: $P_{\{e,f,g\}}$, before switching $X = \{w, x, y, z\}$. The principal hexagon H_v is the outer hexagon. Heavy lines indicate the cut ∇X . Right: $P_{\{e,f,g\}}^X$, after switching. Heavy lines indicate the new principal hexagon H_u and dotted lines mark the new negative edges.

In Case (a), $d = 2$, so the three negative edges lie in the hexagon H_v (Fig. 8.1). As switching changes two edges from negative to positive, this resembles the case of $P_{2,2}$, but now there are three possible switching sets X , namely $X = \{w, x\}$ for each positive edge wx in H_v . Switching X gives a $P_{3,2}$ with negative edge set $\{e', f', g'\} \subseteq H_u$. The vertex u can be described in terms of the 3-edge path in H_v centered upon wx : there is a unique pentagon containing this path, and u is its only vertex not in H_v . It follows that each different edge wx yields a different principal hexagon after switching. Now, suppose that $X = \{v_{jm}, v_{kl}\}$; then $u = v_{jk}$ and $P_{\{e,f,g\}}^X$ is isomorphic to $P_{\{e,f,g\}}$ by the even permutation $\gamma_X := (jm)(kl)$. Similarly, each of the other two switching sets X gives $P_{\{e,f,g\}}^X$, which is isomorphic to $P_{\{e,f,g\}}$ by an even permutation. It follows from Proposition 8.9 that each different $\zeta_X \gamma_X$ belongs to a different left coset of $\text{Aut } P_{\{e,f,g\}}$ in $\text{SwAut } P_{\{e,f,g\}}$. Thus we have three cosets besides $\text{Aut } P_{\{e,f,g\}}$ itself.

The three coset representatives are a single orbit of the action of $\text{Aut } P_{\{e,f,g\}}$ on $\text{SwAut } P_{\{e,f,g\}}$. To prove this, we may point to symmetry or we may compute the action on a coset representative $\zeta_X \gamma_X$, or rather on the switching permutation $\zeta_X \gamma_X$. The argument from symmetry is that each switching automorphism is obtained from one of them, say $\zeta_{jm,kl}(jm)(kl)$, by rotating Fig. 8.1 through 120° once or twice. The rotation is carried out by the permutation (kji) . As for a double transposition, say $(jk)(lm) \in \text{Aut } P_{\{e,f,g\}}$, applying it reflects the figure across a line parallel to $v_{jk}v_{lm}$, and therefore does not change the switching automorphism $\zeta_{jm,kl}(jm)(kl)$; the other double transpositions similarly fix the other switching automorphisms. For the computational proof, first, we note the action of powers of (ijk) :

$$\begin{aligned} [\zeta_{jm,kl}(jm)(kl)]^{(ijk)} &= \zeta_{km,il}(km)(il), \\ [\zeta_{jm,kl}(jm)(kl)]^{(kji)} &= \zeta_{im,jl}(im)(jl). \end{aligned} \tag{8.7}$$

This shows the chosen representatives are in one orbit. Next, we show the action of $(jk)(lm)$:

$$[\zeta_{jm,kl}(jm)(kl)]^{(jk)(lm)} = \zeta_{jm,kl}(jm)(kl).$$

As $\text{Aut } P_{\{e,f,g\}} = \langle (ijk) \rangle \cup (jk)(lm) \langle (ijk) \rangle$, this proves there are no other switching permutations in the orbit. Thus, the computational proof gives the slightly stronger result that these switching permutations, not only the switching automorphisms, are a whole orbit of $\text{Aut } P_{\{e,f,g\}}$.

In Case (b), $d = 2$ and $P:X$ is a path $wxyz$. Again e, f, g are alternating edges on H_v (Fig. 8.2).

Given H_v , we need to know which sets $X = \{w, x, y, z\}$ can be. To determine that, we reverse the question; we fix X and ask which hexagons H_v can be. (There are 60 paths of length 3, but, as $\text{Aut } P$ is transitive on them, there is only one type.) Since $e, f, g \in \nabla X$, it must be true that $|H_v \cap \nabla X| = 3$. One finds by checking every vertex of P that only two hexagons H_v have this property; the vertices v are the neighbors of x and y in X^c . By choice of notation, we may assume that v is adjacent to y .

Now we can describe the relationship between the path $wxyz$ and $P_{\{e,f,g\}}$. The path begins with the positive edge wx of H_v , which is followed by $y \notin V(H_v)$, and then ends at z in H_v . The original negative edges e, f, g are the alternating triple in H_v that excludes wx . The vertex y is the neighbor of x along H_v . Thus, there are six possible paths for $wxyz$. Once we choose w and x , the rest is determined.

After switching $X = \{w, x, y, z\}$, we again have three negative edges on a hexagon; this hexagon is H_u , where u is the neighbor of x along H_v . $H_v \cap H_u$ is the 2-edge path from w to z in H_v ; the first edge is one of e, f, g and hence is positive (after switching), while the next, call it e' , is negative. The negative edge set of $P_{\{e,f,g\}}^X$ consists of e' and the edges f', g' at distance 2 from it along H_u . Thus, $P_{\{e,f,g\}}$ switches to $P_{\{e',f',g'\}}$.

To find a permutation α by which $P_{\{e,f,g\}}^X$ is isomorphic to $P_{\{e,f,g\}}$, we need only examine one case, because each path $wxyz$ maps to any other, $w'x'y'z'$, by the unique automorphism of $P_{\{e,f,g\}}$ which carries (w, x) to (w', x') . Let $e = v_{il}v_{jm}$, $f = v_{kl}v_{im}$, and $g = v_{jl}v_{km}$, so $v = v_{lm}$, and let the path $wxyz = v_{jm}v_{kl}v_{ij}v_{km}$. Then $u = v_{im}$. The even permutation (ilm) is one choice for

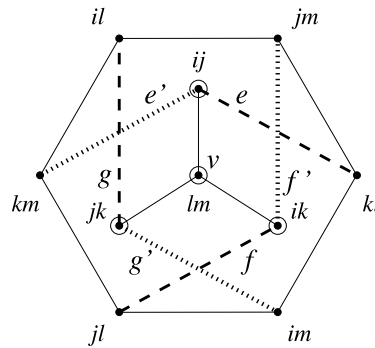


Fig. 8.3. Switching the closed neighborhood $X = N[v]$ of a totally positive vertex in $P_{3,3}$ for Case (c). The original negative edges e, f, g are dashed; the new ones after switching, e', f', g' , are dotted. The heavy lines show the cut ΔX .

the desired isomorphism. The switching automorphism of $P_{\{e,f,g\}}$ is $\bar{\zeta}_{\{jm,kl,ij,mk\}}(ilm)$. (In the notation of Section 8.1.4, this is $\bar{\rho}_{\{jm,kl,ij,mk\}}$.)

These six switching automorphisms are another orbit of $\text{Aut } P_{\{e,f,g\}}$ acting on $\text{SwAut } P_{\{e,f,g\}}$. The proof by symmetry is contained in the observation that the six paths are automorphic under the automorphism group. We show the computational proof in order to demonstrate that the switching permutations are also a single orbit of $\text{Aut } P_{\{e,f,g\}}$. We compute the non-trivial actions on one of the switching permutations:

$$\begin{aligned}
 [\zeta_{\{jm,kl,ij,mk\}}(ilm)]^{(ijk)} &= \zeta_{\{km,il,jk,mi\}}(jlm), \\
 [\zeta_{\{jm,kl,ij,mk\}}(ilm)]^{(kji)} &= \zeta_{\{im,jl,ki,mj\}}(klm), \\
 [\zeta_{\{jm,kl,ij,mk\}}(ilm)]^{(jk)(lm)} &= \zeta_{\{kl,jm,ik,lj\}}(mli), \\
 [\zeta_{\{jm,kl,ij,mk\}}(ilm)]^{(ij)(lm)} &= \zeta_{\{il,km,ji,lk\}}(mlj), \\
 [\zeta_{\{jm,kl,ij,mk\}}(ilm)]^{(ik)(lm)} &= \zeta_{\{jl,im,kj,li\}}(mlk).
 \end{aligned}
 \tag{8.8}$$

This displays all six switching permutations of $P_{\{e,f,g\}}$.

In Case (c), $X = N[v]$, $\{e, f, g\} = M_{3(m)} := \{v_{ij}v_{kl} : \{i, j, k, l\} = \{1, 2, 3, 4, 5\} \setminus m\}$, and $\text{Aut } P_{\{e,f,g\}} = \mathfrak{S}_{\{1,2,3,4,5\} \setminus m}$. The complement of $V(M_{3(m)})$ is X_m . Any vertex in X_m can be taken as v ; choosing $v = v_{lm}$, $\zeta_{N[v_{lm}]}(ilm)$ is a switching automorphism of $P_{3,3}$ (Fig. 8.3). This is the only way to switch $P_{\{e,f,g\}}$ for a switching automorphism, so

$$\text{SwAut } P_{3,3} = \mathfrak{S}_{\{1,2,3,4,5\} \setminus m} \cup \bigcup_{i \in \{1,2,3,4,5\} \setminus m} \zeta_{N[v_{im}]}(im) \mathfrak{S}_{\{1,2,3,4,5\} \setminus m}.
 \tag{8.9}$$

We may rewrite Eq. (8.9) as

$$\text{SwAut } P_{3,3} = \mathfrak{S}_{\{1,2,3,4,5\} \setminus m} \cup \bigcup_{\alpha \in \mathfrak{S}_{\{1,2,3,4,5\} \setminus m}} [\zeta_{N[v_{im}]}(im)]^\alpha \mathfrak{S}_{\{1,2,3,4,5\} \setminus m}$$

(where $i \neq m$ is fixed).

Thus, as with $P_{3,2}$, the switching permutations and switching automorphisms of $P_{3,3}$ are unions of whole orbits of the actions of $\text{Aut } P_{\{e,f,g\}}$ acting on switching permutations and switching automorphisms of P . This is obvious both pictorially, as $\text{Aut } P_{\{e,f,g\}}$ permutes $\{1, 2, 3, 4, 5\} \setminus \{m\}$ and therefore X_m , and computationally, as $N[v_{im}]^\alpha = N[v_{i^\alpha m}]$, so $[\zeta_{N[v_{im}]}(im)]^\alpha = \zeta_{N[v_{i^\alpha m}]}(i^\alpha m)$ (Fig. 8.3).

8.2.4. The structure of $\text{SwAut } P_{3,2}$.

A switching automorphism of $P_{3,2}$, if not an automorphism, falls under Case (a) or Case (b). Thus,

$$\text{SwAut } P_{3,2} = \text{Aut } P_{3,2} \cup \bigcup_{\lambda \in \langle (ijk) \rangle} [\zeta_{\{jm,kl\}}(jm)(kl)]^\lambda \text{Aut } P_{3,2} \cup \bigcup_{\mu \in \text{Aut } P_{3,2}} [\zeta_{\{jm,kl,ij,mk\}}(il)(jk)]^\mu \text{Aut } P_{3,2}.
 \tag{8.10}$$

This tells us the set $\text{SwAut } P_{3,2}$, but to know the group we need the rules for multiplication and for how to determine, for each permutation in $p_A(\text{SwAut } P_{3,2})$, which switching must be done before the permutation to get a switching automorphism.

The description is simplified if we fix the $P_{3,2}$ by choosing a specific negative edge set. Our choice for E^- is $\{e = v_{14}v_{25}, f = v_{34}v_{15}, g = v_{24}v_{35}\} \subseteq H_{45}$. (That is, we are setting $i, j, k = 1, 2, 3$ and $l, m = 4, 5$.)

To describe the group we fix two switching sets,

$$W := \{v_{15}, v_{24}\} \quad \text{and} \quad Z := \{v_{34}, v_{25}, v_{13}, v_{24}\},$$

and corresponding switching permutations,

$$\omega_W := \zeta_W(15)(24) \quad \text{and} \quad \omega_Z := \zeta_Z(145).$$

Table 8.3

The transforms W^μ and Z^μ and associated switching automorphisms, for $\mu \in \text{Aut } P_{3,2}$. Recall that $\nu_W^\mu = \nu_{W^\mu}$ and $\omega_Z^\mu = \omega_{Z^\mu}$.

λ	W^μ	ν_{W^μ}	Z^μ	ω_{Z^μ}
id	$W = \{v_{15}, v_{24}\}$	$\zeta_W(15)(24)$	$Z = \{v_{34}, v_{25}, v_{13}, v_{24}\}$	$\zeta_Z(145)$
(123)	$\{v_{25}, v_{34}\}$	$\zeta_W^{(123)}(25)(34)$	$\{v_{14}, v_{35}, v_{12}, v_{34}\}$	$\zeta_Z^{(123)}(245)$
(321)	$\{v_{35}, v_{14}\}$	$\zeta_W^{(321)}(35)(14)$	$\{v_{24}, v_{15}, v_{23}, v_{14}\}$	$\zeta_Z^{(321)}(345)$
(12)(45)	$\{v_{15}, v_{24}\}$	ν_W	$\{v_{35}, v_{14}, v_{23}, v_{15}\}$	$\zeta_Z^{(12)(45)}(542)$
(23)(45)	$\{v_{14}, v_{35}\}$	$\nu_W^{(321)}$	$\{v_{25}, v_{34}, v_{12}, v_{35}\}$	$\zeta_Z^{(23)(45)}(541)$
(13)(45)	$\{v_{34}, v_{25}\}$	$\nu_W^{(123)}$	$\{v_{15}, v_{24}, v_{13}, v_{25}\}$	$\zeta_Z^{(13)(45)}(543)$

Table 8.4

The multiplication table of elements of $\{+, -\} \times \text{Aut } P$ that represent coset representatives of the second kind times the second and third kinds in $\text{SwAut } P_{3,2}$.

\cdot	ν_W	$\nu_W^{(123)}$	$\nu_W^{(321)}$	ω_Z	$\omega_Z^{(123)}$	$\omega_Z^{(321)}$	$\omega_Z^{(12)(45)}$	$\omega_Z^{(23)(45)}$	$\omega_Z^{(13)(45)}$
ν_W	$\bar{\varepsilon} \text{ id}$	$\omega_Z^{(12)(45)}(321)$	$\omega_Z^{(13)(45)}(321)$	$\bar{\varepsilon} \text{ id}$	$\omega_Z^{(123)}$	$\omega_Z^{(321)}$	$\omega_Z^{(12)(45)}$	$\omega_Z^{(23)(45)}$	$\omega_Z^{(13)(45)}$
$\nu_W^{(123)}$	$\omega_Z^{(12)(45)}(321)$	$\bar{\varepsilon} \text{ id}$	$\omega_Z^{(13)(45)}(321)$	$\omega_Z^{(123)}$	$\bar{\varepsilon} \text{ id}$	$\omega_Z^{(123)}$	$\omega_Z^{(12)(45)}$	$\omega_Z^{(23)(45)}$	$\omega_Z^{(13)(45)}$
$\nu_W^{(321)}$	$\omega_Z^{(123)}$	$\omega_Z^{(13)(45)}(321)$	$\bar{\varepsilon} \text{ id}$	$\omega_Z^{(123)}$	$\omega_Z^{(321)}$	$\bar{\varepsilon} \text{ id}$	$\omega_Z^{(12)(45)}$	$\omega_Z^{(23)(45)}$	$\omega_Z^{(13)(45)}$
ω_Z	$\omega_Z^{(12)(45)}$	$\omega_Z^{(123)}(12)(45)$	$\omega_Z^{(13)(45)}(23)(45)$	ω_Z	$\omega_Z^{(123)}$	$\omega_Z^{(321)}$	$\omega_Z^{(12)(45)}$	$\omega_Z^{(23)(45)}$	$\omega_Z^{(13)(45)}$
$\nu_W^{(123)}$	$\omega_Z^{(12)(45)}$	$\omega_Z^{(123)}(12)(45)$	$\omega_Z^{(13)(45)}(23)(45)$	ω_Z	$\omega_Z^{(123)}$	$\omega_Z^{(321)}$	$\omega_Z^{(12)(45)}$	$\omega_Z^{(23)(45)}$	$\omega_Z^{(13)(45)}$
$\nu_W^{(321)}$	$\omega_Z^{(123)}$	$\omega_Z^{(13)(45)}(23)(45)$	$\omega_Z^{(123)}$	ω_Z	$\omega_Z^{(123)}$	$\omega_Z^{(321)}$	$\omega_Z^{(12)(45)}$	$\omega_Z^{(23)(45)}$	$\omega_Z^{(13)(45)}$
ω_Z	$\omega_Z^{(12)(45)}$	$\omega_Z^{(123)}(12)(45)$	$\omega_Z^{(13)(45)}(23)(45)$	ω_Z	$\omega_Z^{(123)}$	$\omega_Z^{(321)}$	$\omega_Z^{(12)(45)}$	$\omega_Z^{(23)(45)}$	$\omega_Z^{(13)(45)}$

(W is the $X = \{v_{im}, v_{jl}\}$ of Case (a) and Z is the $X = \{v_{jm}, v_{kl}, v_{ij}, v_{km}\}$ of Case (b). The permutation part is what was called γ_W and γ_Z ; as before, it is partly arbitrary, since it is determined only up to right multiplication by elements of $\text{Aut } P_{3,2}$.) For the systems of representatives in Proposition 8.11 we choose

$$R := \{\varepsilon \text{ id}\} \cup \{\nu_W^\lambda : \lambda \in \langle (123) \rangle\} \cup \{\omega_Z^\mu : \mu \in \text{Aut } P_{3,2}\},$$

which we may do because the coset representatives constitute three orbits of $\text{Aut } P_{3,2}$ acting on $\{+, -\}^V \times \text{Aut } P_{3,2}$, as shown in Section 8.2.3, and $\bar{R} := \{\zeta_X \gamma_X : \zeta_X \gamma_X \in R\}$. As in Cases (a) and (b), $W^{(12)(45)} = W$ and $\rho_X^\mu = \rho_{X^\mu}$ for any $\rho_X = \zeta_X \gamma_X \in R$ and $\mu \in \text{Aut } P_{3,2}$, so R is closed under the action of $\text{Aut } P_{3,2}$. The sets W^μ and Z^μ are found in Table 8.3.

The switching set X associated with $\bar{\rho} \in \bar{R}$ is uniquely determined if we insist that $|X| \leq 4$. (That is how we chose R .) Thus, we are representing $\text{SwAut } P_{3,2}$ as the disjoint union of the left \bar{R} -cosets of $\text{Aut } P_{3,2}$:

$$\text{SwAut } P_{3,2} = \bigcup_{\zeta_X \gamma_X \in R} \bar{\zeta}_X \gamma_X \text{Aut } P_{3,2}. \tag{8.11}$$

Note again that ζ_X and $-\zeta_X = \zeta_{X^c}$ are equally valid representatives of $\bar{\zeta}_X$; this fact helps to calculate and interpret the multiplication tables we provide for $\text{SwAut } P_{3,2}$.

The product $(\bar{\zeta}_X \gamma_X) \alpha \cdot (\bar{\zeta}_Y \gamma_Y) \beta$ of any two switching automorphisms is completely specified by Proposition 8.11. To find the product follow this procedure.

- (1) Set $Y' = Y^{\alpha^{-1}}$ and $\zeta_{Y'} = \zeta_Y^{\alpha^{-1}}$. Then $\zeta_{Y'} \gamma_{Y'}$ is an element of R , because R is closed under the action of $\text{Aut } P_{3,2}$.
- (2) Calculate $U = X \oplus Y'$ or $(X \oplus Y')^c$, the former if $|X \oplus Y'| \leq 4$ and the latter otherwise.
- (3) Find $\zeta_U \gamma_U \in R$ to determine γ_U .
- (4) The product is $(\bar{\zeta}_U \gamma_U)(\gamma_U^{-1} \gamma_X \gamma_{Y'}) \cdot \alpha \beta$, which lies in the coset $(\bar{\zeta}_U \gamma_U) \text{Aut } P_{3,2}$.
- (5) The product $(\zeta_X \gamma_X) \alpha \cdot (\zeta_Y \gamma_Y) \beta$ in $\{+, -\} \times \text{Aut } P$, if desired, is $\pm(\zeta_U \gamma_U)(\gamma_U^{-1} \gamma_X \gamma_{Y'}) \cdot \alpha \beta$, with the positive sign if $|X \oplus Y'| \leq 4$ and the negative sign if not.

Steps (2) and (3) can be combined by using Tables 8.4–8.6, which give the products of elements $\zeta_X \gamma_X, \zeta_{Y'} \gamma_{Y'} \in R$.

To illustrate the calculations involved in preparing the multiplication tables for $P_{3,2}$, we solve three representative cases.

Example 8.1. For the first two examples, we compute the product of ω_Z times two other switching permutations in R . First,

$$\begin{aligned} \omega_Z \omega_Z &= \zeta_{\{34,25,13,24\}}(145) \cdot \zeta_{\{34,25,13,24\}}(145) \\ &= \zeta_{\{34,25,13,24\}} \zeta_{\{34,25,13,24\}^{(145)^{-1}}}(145)(145) \\ &= \zeta_{\{34,25,13,24\}} \zeta_{\{31,24,53,21\}}(541) = \zeta_{\{34,25,13,24\} \oplus \{31,24,53,21\}}(541) \\ &= \zeta_{\{34,25,53,21\}}(541) = \zeta_{Z^{(23)(45)}}(541) = \omega_Z^{(23)(45)}. \end{aligned}$$

Table 8.5

The multiplication table of elements of $\{+, -\} \times \text{Aut } P$ that represent coset representatives of the third kind times the second kind in $\text{SwAut } P_{3,2}$.

\cdot	ν_W	$\nu_W^{(123)}$	$\nu_W^{(321)}$
ω_Z	$-\omega_Z^{(12)(45)}(12)(45)$	$\nu_W^{(123)}(321)$	$\omega_Z^{(13)(45)}$
$\omega_Z^{(123)}$	$\omega_Z^{(23)(45)}$	$-\omega_Z^{(13)(45)}(23)(45)$	$\nu_W^{(321)}(321)$
$\omega_Z^{(321)}$	$\nu_W(321)$	$\omega_Z^{(12)(45)}$	$-\omega_Z^{(23)(45)}(13)(45)$
$\omega_Z^{(12)(45)}$	$-\omega_Z(12)(45)$	$\omega_Z^{(321)}$	$\nu_W^{(321)}(123)$
$\omega_Z^{(23)(45)}$	$\omega_Z^{(123)}$	$\nu_W^{(123)}(123)$	$-\omega_Z^{(321)}(13)(45)$
$\omega_Z^{(13)(45)}$	$\nu_W(123)$	$-\omega_Z^{(123)}(23)(45)$	ω_Z

Table 8.6

The multiplication table of elements of $\{+, -\} \times \text{Aut } P$ that represent coset representatives of the third kind in $\text{SwAut } P_{3,2}$.

\cdot	ω_Z	$\omega_Z^{(123)}$	$\omega_Z^{(321)}$
ω_Z	$\omega_Z^{(23)(45)}$	ν_W	$-\nu_W^{(321)}(13)(45)$
$\omega_Z^{(123)}$	$-\nu_W(12)(45)$	$\omega_Z^{(12)(45)}$	$\nu_W^{(123)}$
$\omega_Z^{(321)}$	$\nu_W^{(321)}$	$-\nu_W^{(123)}(23)(45)$	$\omega_Z^{(13)(45)}$
$\omega_Z^{(12)(45)}$	$-\omega_Z^{(23)(45)}(12)(45)$	$\bar{\epsilon} \text{ id}$	$-\omega_Z^{(13)(45)}(23)(45)$
$\omega_Z^{(23)(45)}$	$\bar{\epsilon} \text{ id}$	$\omega_Z^{(12)(45)}(12)(45)$	$\omega_Z^{(13)(45)}(13)(45)$
$\omega_Z^{(13)(45)}$	$-\omega_Z^{(23)(45)}(13)(45)$	$-\omega_Z^{(12)(45)}(23)(45)$	$\bar{\epsilon} \text{ id}$
\cdot	$\omega_Z^{(12)(45)}$	$\omega_Z^{(23)(45)}$	$\omega_Z^{(13)(45)}$
ω_Z	$-\omega_Z^{(123)}(12)(45)$	$\bar{\epsilon} \text{ id}$	$-\omega_Z^{(321)}(13)(45)$
$\omega_Z^{(123)}$	$\bar{\epsilon} \text{ id}$	$-\omega_Z(12)(45)$	$-\omega_Z^{(321)}(23)(45)$
$\omega_Z^{(321)}$	$-\omega_Z^{(123)}(23)(45)$	$-\omega_Z(23)(45)$	$\bar{\epsilon} \text{ id}$
$\omega_Z^{(12)(45)}$	$\omega_Z^{(123)}$	$\nu_W^{(12)(45)}$	$-\nu_W^{(13)(45)}(23)(45)$
$\omega_Z^{(23)(45)}$	$-\nu_W^{(12)(45)}(12)(45)$	ω_Z	$\nu_W^{(13)(45)}$
$\omega_Z^{(13)(45)}$	$\nu_W^{(12)(45)}$	$-\nu_W^{(23)(45)}(13)(45)$	$\omega_Z^{(321)}$

Next, we give a more complicated example involving complementation of the switching set and a residual permutation that is an automorphism of $P_{3,2}$.

$$\begin{aligned}
 \omega_Z \omega_Z^{(321)} &= \zeta_{\{34,25,13,24\}}(145) \cdot \zeta_{\{24,15,23,14\}}(345) \\
 &= \zeta_{\{34,25,13,24\}} \zeta_{\{24,15,23,14\}}^{(145)^{-1}}(145)(345) \\
 &= \zeta_{\{34,25,13,24\}} \zeta_{\{21,54,23,51\}}(15)(34) = \zeta_{\{34,25,13,24\} \oplus \{12,45,23,15\}}(15)(34) \\
 &= -\zeta_{\{14,35\}}(15)(34) = [-\zeta_{\{14,35\}}(14)(35)] \cdot [(14)(35)]^{-1}(15)(34) \\
 &= -\nu_{\{14,35\}} \cdot (35)(14)(15)(34) = -\nu_W^{(321)}(13)(45).
 \end{aligned}$$

Example 8.2. We use Example 8.1 to compute left multiplication by a transform of ω_Z .

$$\omega_Z^{(321)} \omega_Z^{(123)} = [\omega_Z \omega_Z^{(123)(321)^{-1}}]^{(321)} = [\omega_Z \omega_Z]^{(321)},$$

which, by Example 8.1,

$$= [-\nu_W^{(321)}(13)(45)]^{(321)} = -\nu_W^{(123)}(32)(45).$$

By explicitly inverting the isomorphism $\bar{p}_A : \text{SwAut } P_{3,2} \rightarrow \mathfrak{A}_5 : \bar{\zeta} \xi \mapsto \xi$, we can say, for any $\xi \in \mathfrak{A}_5$, exactly which switching function $\zeta_X \gamma_X$ should be associated with it.

Table 8.7

The multiplication table of $\text{SwAut } P_{3,3}$ with negative edge set $M_{3(5)} = \{v_{12}v_{34}, v_{13}v_{24}, v_{14}v_{23}\}$. $i, j \in \{1, 2, 3, 4\}$ and $\alpha, \beta \in \mathfrak{S}_{\{1,2,3,4\}}$.

Left · Top	β	$\bar{\zeta}_{N[j5]}(j5)\beta$
α	$\alpha\beta$	$\bar{\zeta}_{N[j^{\alpha-1}5]}(j^{\alpha-1}5)\alpha\beta$
$\bar{\zeta}_{N[i5]}(i5)\alpha$	$\bar{\zeta}_{N[i5]}(i5)\alpha\beta$	$\begin{cases} \alpha\beta & \text{if } j = i^\alpha \\ \bar{\zeta}_{N[j^{\alpha-1}5]}(j^{\alpha-1}5)\alpha\beta & \text{if } j \neq i^\alpha \end{cases}$

Proposition 8.14. For a permutation $\xi \in \mathfrak{A}_5$, the corresponding switching automorphism of $P_{3,2}$ is $\bar{\zeta}_X \xi = \bar{\zeta}_X \gamma_X \alpha \in \bar{\zeta}_X \gamma_X \text{Aut } P_{3,2}$, where $\zeta_X \gamma_X \in R$ is given by

$$\zeta_X \gamma_X = \begin{cases} \zeta_\emptyset \text{id} = \varepsilon \text{id} & \text{if } \{4, 5\}^{\xi^{-1}} = \{4, 5\}, \\ \zeta_{\{34,25,13,24\}^\lambda}(i45) & \text{if } \{4, 5\}^{\xi^{-1}} = \{i, 4\}, \text{ where } \lambda = (123)^{i-1}, \\ \zeta_{\{25,34,12,35\}^\lambda}(54i) & \text{if } \{4, 5\}^{\xi^{-1}} = \{i, 5\}, \text{ where } \lambda = (123)^{i-1}, \\ \zeta_{\{i5,j4\}}(i5)(j4) & \text{if } \{4, 5\}^{\xi^{-1}} = \{i, j\} \subset \{1, 2, 3\}, \text{ where } j = i^{(123)}, \end{cases}$$

and $\alpha = \gamma_X^{-1} \xi \in \text{Aut } P_{3,2}$.

Proof. The question is to find the vertex set X such that γ_X , of $\zeta_X \gamma_X \in R$, satisfies $\xi \in \gamma_X \text{Aut } P_{3,2}$; in other words, $\gamma_X^{-1} \xi = \alpha \in \text{Aut } P_{3,2}$. By this definition of α , $\{4, 5\}^{\xi^{-1}} = \{4, 5\}^{\alpha^{-1} \gamma_X^{-1}}$. But $\{4, 5\}$ is invariant under $\text{Aut } P_{3,2}$. Therefore, $\{4, 5\}^{\xi^{-1}} = \{4, 5\}^{\gamma_X^{-1}}$, which depends only on the coset of $\text{Aut } P_{3,2}$ to which ξ belongs. In other words, we need only consider the case $\alpha = \text{id}$, which means that we examine only all $\xi = \gamma_X$. Now, the proposition follows easily, by inspection of the ten cases of γ_X .

A better method is to show that the proposition for one X implies it for X^λ , for every $\lambda = (123)^p$. Replacing X by X^λ ,

$$\{4, 5\}^{(\gamma_X^\lambda)^{-1}} = \{4, 5\}^{(\gamma_X^{-1})^\lambda} = \{4, 5\}^{\lambda^{-1}(\gamma_X)^{-1}\lambda} = (\{4, 5\}^{(\gamma_X)^{-1}})^\lambda.$$

Supposing that $\{4, 5\}^{\gamma_X^{-1}} = \{4, 5\}, \{i, 4\}, \{i, 5\}$, or $\{i, i^{(123)}\}$, we deduce that $\{4, 5\}^{(\gamma_X^\lambda)^{-1}} = \{4, 5\}, \{i^\lambda, 4\}, \{i^\lambda, 5\}$, or $\{i^\lambda, (i^\lambda)^{(123)}\}$, respectively. This proves the claim for $\lambda = (123)^p$. Thus, we need only check the proposition's validity for $X = \emptyset, Z, Z^{(12)(45)}$, and W , which is easier than checking all ten X 's. \square

A natural question is whether $\text{SwAut } P_{3,2}$ can be written as a product of subgroups, $\mathfrak{H} \cdot \text{Aut } P_{3,2}$, where $\mathfrak{H} \cap \text{Aut } P_{3,2} = \{\text{id}\}$, or in other words whether there exists a system of left coset representatives that is a subgroup. There does not, for it is known that no subgroup of \mathfrak{A}_5 of order 6 has such a complementary subgroup.

8.2.5. The structure of $\text{SwAut } P_{3,3}$.

We know the set $\text{SwAut } P_{3,3}$, but for a full description we need the rule of multiplication and the rule for inverting the projection p_A . It is easier to do this if we fix m , so we assume that $m = 5$. Then $E^- = M_{3(5)}, \text{Aut } P_{3,3} = \mathfrak{S}_{\{1,2,3,4\}}$, and

$$\text{SwAut } P_{3,3} = \mathfrak{S}_{\{1,2,3,4\}} \cup \bigcup_{j=1}^4 \bar{\zeta}_{N[j5]}(j5) \mathfrak{S}_{\{1,2,3,4\}}. \tag{8.12}$$

An element of the group has the form β or $\bar{\zeta}_{N[j5]}(j5)\beta$ for $\beta \in \mathfrak{S}_{\{1,2,3,4\}}$ and $j \in \{1, 2, 3, 4\}$. To compute a product, refer to Table 8.7.

The second product column in Table 8.7 requires proof, for which the main step is this computation (done for a switching permutation $\zeta \alpha$ and consequently the same for the switching automorphism $\bar{\zeta} \alpha$):

$$\alpha \cdot \zeta_{N[j5]}(j5) = \zeta_{N[j^{\alpha-1}5]} \alpha(j5) = \zeta_{N[j^{\alpha-1}5]}(j^{\alpha-1}5) \cdot \alpha.$$

This gives the first product. For the second, we continue the calculation; first, when $j = i^\alpha$:

$$\zeta_{N[i5]}(i5) \alpha \cdot \zeta_{N[i^\alpha 5]}(i^\alpha 5) = \zeta_{N[i5]}(i5) \zeta_{N[i5]}(i5) \alpha = \zeta_{N[i5]} \zeta_{N[i5]}(i5)(i5) \alpha = \alpha;$$

second, when $j \neq i^\alpha$:

$$\begin{aligned} \zeta_{N[i5]}(i5) \alpha \cdot \zeta_{N[j5]}(j5) &= \zeta_{N[i5]}(i5) \zeta_{N[j^{\alpha-1}5]}(j^{\alpha-1}5) \alpha \\ &= \zeta_{N[i5]} \zeta_{N[j^{\alpha-1}i]}(i5)(j^{\alpha-1}5) \alpha = -\zeta_{N[j^{\alpha-1}5]}(j^{\alpha-1}5) \alpha, \end{aligned}$$

because $N[pq] \oplus N[qr] = N[pr]^c$, whence $\zeta_{N[pq]} \zeta_{N[qr]} = \zeta_{N[pr]^c} = -\zeta_{N[pr]}$.

Table 8.8

The number of different signatures of P that are isomorphic to each minimal signed Petersen graph and its negative ('copies'); and the number of switching equivalence classes of such signatures ('[copies]').

(P, σ)	$+P, -P$	$P_1, -P_1$	$P_{2,2}, -P_{2,2}$	$P_{2,3}, -P_{2,3}$	$P_{3,2}, -P_{3,2}$	$P_{3,3}, -P_{3,3}$
# copies	1	15	60	15	20	5
# [copies]	1	15	30	15	2	1

Every permutation $\xi \in \mathfrak{S}_{\{1,2,3,4,5\}}$ is the projection of a unique element $\bar{\zeta}_X \gamma_X \cdot \alpha \in \text{SwAut } P_{3,3}$ belonging to the coset $\bar{\zeta}_X \gamma_X \text{Aut } P_{3,3}$. The following formulas give ζ_X, γ_X , and α in terms of ξ , thereby inverting p_A . Let $\zeta_X \gamma_X \alpha := p_A^{-1}(\xi)$. Then $\zeta_X \gamma_X$ identifies the coset of $\mathfrak{S}_{\{1,2,3,4\}}$, and α identifies the element of $\mathfrak{S}_{\{1,2,3,4\}}$ that gives ξ .

$$(\zeta_X, \gamma_X, \alpha) = \begin{cases} (\varepsilon, \text{id}, \xi) & \text{if 5 is fixed by } \xi, \\ (\zeta_{N[5^{\xi^{-1}5}], (5^{\xi^{-1}5}), (5^{\xi^{-1}5})\xi) & \text{if 5 is not fixed.} \end{cases} \tag{8.13}$$

(Note that $(5^{\xi^{-1}5})\xi$ in cycle form is ξ with 5 deleted from whichever cycle it is in. Also note that, if we interpret $N[kk]$ as the empty set, so $\zeta_{N[kk]}$ is ε , and (55) as the trivial cycle (5) , then the first line is subsumed in the second line.)

8.2.6. *The end of the proof*

This concludes the proof of **Theorem 8.12**. \square

8.3. *Orbits and copies*

There are two ways signed graphs Σ and Σ' based on the same graph Γ can be isomorphic. They may have the same set of positive circles, which (by **Lemma 4.1**) is the same as saying they are switching equivalent; then for many purposes they are essentially the same. The other possibility is that they belong to different switching equivalence classes; in other words, their positive circles are not the same ones even though they correspond under an automorphism of Γ . From the automorphism and switching automorphism groups we can deduce the number of signatures of Γ that are isomorphic to Σ and also the number that are switching inequivalent to Σ and to each other, i.e., the number of switching equivalence classes of signatures isomorphic to Σ .

There is a nice bonus to this: we get an interpretation of the part of $\text{Aut } \Gamma$ that does not belong to $\bar{p}_A(\text{SwAut } \Sigma)$. Apply any automorphism $\gamma \in \text{Aut } \Gamma$ to Σ . Then $\Sigma^\gamma \sim \Sigma$ if and only if $\gamma \in \bar{p}_A(\text{SwAut } \Sigma)$. This means that Σ^γ for $\gamma \notin \bar{p}_A(\text{SwAut } \Sigma)$, while isomorphic to Σ , belongs to a different switching equivalence class.

A fine example is $\text{SwAut } P_{3,2}$, whose projection is the alternating group \mathfrak{A}_5 . Any single transposition changes $(P, \sigma) \cong P_{3,2}$ to an inequivalent (P, σ') , but there is one that is simplest. In the notation of **Table 8.2**, it is (lm) . This permutation preserves the hexagon H_{lm} that contains E^- while reversing the signs of the hexagon's edges. Whether there are such distinguished permutations to change one switching automorphism class of $P_1, P_{2,2}$, or $P_{2,3}$ to another is not known.

The number of different isomorphic (but possibly switching-equivalent) copies of a particular signature Σ is the number of orbits of $\text{Aut } \Sigma$, which equals $|\text{Aut } \Gamma|/|\text{Aut } \Sigma|$. The number of different copies that are not switching equivalent, i.e., the number of switching equivalence classes of signatures isomorphic to Σ , is $|\text{Aut } \Gamma|/|\text{SwAut } \Sigma|$, the number of orbits of $\text{Aut } \Gamma$ acting on $\text{SwAut } \Sigma$. For instance, $|\text{Aut } P_1| = |\text{SwAut } P_1| = |\mathfrak{D}_4| = 8$; $|\text{Aut } P|/|\text{Aut } P_1| = |\text{Aut } P|/|\text{SwAut } P_1| = 5!/8 = 15$; and (obviously) there are $|E| = 15$ ways to have one negative edge, none of which is switching equivalent to any other. See **Table 8.8** for the numbers.

9. Coloring

A *coloration* (in full, *proper k-coloration*, where $k \geq 0$) of a signed graph is a function $\kappa : V \rightarrow \{0, \pm 1, \pm 2, \dots, \pm k\}$ such that, if vw is an edge, then $\kappa(w) \neq \sigma(vw)\kappa(v)$. The *chromatic number* $\chi(\Sigma)$ is the smallest k such that there is a proper k -coloration of Σ . A signed graph has a second chromatic number, the *zero-free chromatic number* $\chi^*(\Sigma)$; it is the smallest k such that there is a proper k -coloration of Σ that does not use the color 0. As the color 0 can be replaced by $+(k + 1)$ to turn a coloration into a zero-free coloration, $\chi^*(\Sigma) = \chi(\Sigma) + 0$ or 1.

The chromatic numbers pair with chromatic polynomials. The *chromatic polynomial* of Σ is the function $\chi_\Sigma(2k + 1) :=$ the number of proper k -colorations, and the *zero-free chromatic polynomial* is $\chi^*_\Sigma(2k) :=$ the number that are zero free. (One can prove that these functions are monic polynomials of degree $|V|$ by any method that establishes the chromatic polynomial $\chi_\Gamma(y)$ of an ordinary graph; see [19]. There is another connection: $\chi_\Gamma(y) = \chi_{+\Gamma}(y) = \chi^*_{+\Gamma}(y)$.)

Proposition 9.1. *The chromatic numbers and the chromatic polynomials of a signed graph are invariant under switching and isomorphism.*

Table 9.1
The chromatic numbers of signed Petersen graphs.

(P, σ)	$+P$	P_1	$P_{2,2}$	$P_{2,3}$	$P_{3,2}$	$P_{3,3}$
$\chi(P, \sigma)$	1	1	1	1	1	1
$\chi^*(P, \sigma)$	2	2	2	2	2	1

Proof. Isomorphism invariance is obvious. For switching invariance, consider a proper coloration κ . A switching function ζ acts on κ by transforming it to $\kappa^\zeta(v) := \kappa(v)\zeta(v)$. The condition for a coloration to be proper, $\kappa(w) \neq \kappa(v)\sigma(vw)$, when multiplied by $\zeta(w)$, takes the form

$$\kappa^\zeta(w) = \kappa(w)\zeta(w) \neq \kappa(v)\sigma(vw)\zeta(w) = [\kappa(v)\zeta(v)][\zeta(v)\sigma(vw)\zeta(w)] = \kappa^\zeta(v)\sigma^\zeta(vw).$$

Thus, κ^ζ is a proper coloration of Σ^ζ if and only if κ is a proper coloration of Σ . This establishes a bijection between proper colorations of Σ and of Σ^ζ , and hence the proposition. \square

9.1. Chromatic numbers

The chromatic numbers are weak invariants; they are nearly the same for all signatures of P .

Theorem 9.2. *The chromatic and zero-free chromatic numbers of signed Petersen graphs are as in Table 9.1.*

To find the chromatic numbers of any (P, σ) , switch it into one of the minimal forms and look it up in Table 9.1. Note that $+P \simeq -P_{3,3}, P_1 \simeq -P_{2,3}, P_{2,2} \simeq -P_{2,2}, P_{2,3} \simeq -P_1, P_{3,2} \simeq -P_{3,2}$, and $P_{3,3} \simeq -P$.

We prepare for the proof of Theorem 9.2 with definitions and a lemma.

By a *signed color* we mean 0 or $+i$ or $-i$ for $i > 0$. For consistency with the definition of chromatic numbers, when coloring a signed graph we call ± 1 a single *unsigned color* and we do not count 0 as an unsigned color. Thus, the counting of unsigned colors on signed graphs is very different from that on unsigned graphs. We can color an unsigned graph with signed colors, but each has to be counted separately; for example, 0, $+1$, -1 are three colors when coloring an unsigned graph.

Note that the endpoints of a negative edge may have the same signed color as long as that color is not 0.

Contracting a graph Γ by an edge set S means one shrinks each connected component of the spanning subgraph (V, S) to a vertex. The contracted graph is written Γ/S . (Technically, a vertex W of Γ/S is a subset of V consisting of the vertices of one component of (V, S) ; they are the vertices that are coalesced into one by the shrinking.) The edges of S are deleted. Another edge becomes a loop if its endpoints belong to the same component of (V, S) . We say that an original vertex that is a component of (V, S) remains a vertex of Γ/S . Any other vertex of Γ/S results from coalescing two or more original vertices; we say it *results from contraction* to distinguish it from remaining original vertices.

Lemma 9.3. *Let Σ be a signed graph, and let $m \geq 1$.*

- (a) *Suppose that $\chi(|\Sigma|/E^-(\Sigma)) \leq 2m$. Then $\chi(\Sigma) \leq \chi^*(\Sigma) \leq m$.*
- (b) *Suppose that $|\Sigma|/E^-(\Sigma)$ can be colored with the colors $0, \pm 1, \dots, \pm m$ in such a way that no vertex resulting from contraction gets the color 0. Then $\chi(\Sigma) \leq m$ and $\chi^*(\Sigma) \leq m + 1$.*
- (c) *If $\chi(|\Sigma|/E^-(\Sigma)) \leq 2$ and Σ has at least one edge, then $\chi(\Sigma) = \chi^*(\Sigma) = 1$.*
- (d) *If $\chi(|\Sigma|/E^-(\Sigma)) = 3$, then $\chi^*(\Sigma) = 2$.*

Proof. (a) Color $|\Sigma|/E^-$ with the colors $\pm 1, \dots, \pm m$. This coloration can be pulled back to Σ , because the vertices that are contracted into W can all be given the signed color of W . Thereby we see that Σ needs at most m unsigned colors, without using the color 0.

(b) Color $|\Sigma|/E^-(\Sigma)$ as specified. This coloration can be pulled back to Σ , because the vertices that are contracted into W can all be given the signed color of W . Thereby we see that Σ needs at most m unsigned colors if 0 is permitted, but it may need $m + 1$ if 0 is excluded.

(c) When the contraction is bipartite, assign color $+1$ to one color class and -1 to the other. Pulling this coloration back to Σ yields a zero-free coloration, from which the chromatic numbers follow—as long as there is at least one edge in Σ so one cannot color every vertex 0.

(d) From (a), we conclude that $\chi^*(\Sigma) \leq 2$. Trying to color Σ using only ± 1 , the endpoints of a negative edge must have the same signed color; therefore, such a coloration of Σ can only be a pullback of a 2-coloration of $|\Sigma|/E^-$, which does not exist. Hence, there is no coloration of Σ using only one unsigned color without 0, and therefore $\chi^*(\Sigma) = 2$. \square

Proof of Theorem 9.2. The chromatic number of P itself is 3 [11]. Thus, $+P$ needs exactly three signed colors, which may be 0, $+1$, -1 if 0 is used and otherwise must be, for example, $+1$, -1 , $+2$.

The only bipartite contraction is $P/E^-(P_{3,3})$; it can be colored with $+1$, -1 , so $P_{3,3}$ can be colored using ± 1 . (One can more easily see this by coloring the switching-isomorphic graph $-P$.) The other contractions need three or four signed colors.

$P/E^-(P_{2,d})$ ($d = 2, 3$) has chromatic number 3, and since there are just two contracted vertices they can get non-zero signed colors; it follows that $P_{2,d}$ is colorable with signed colors $\pm 1, 0$, no contraction vertex being colored 0. Therefore, $\chi(P_{2,d}) = 1$ and $\chi^*(P_{2,d}) = 2$. The same reasoning holds for P_1 , where there is one contracted vertex.

The most complicated contraction is $P/E^-(P_{3,2})$. It has a triangle composed of contracted vertices, so its chromatic number is 3, but there does not exist a coloration with colors $\pm 1, 0$ in which no contracted vertex has color 0. However, one can color $P_{3,2}$ directly using $\pm 1, 0$. The hexagon that contains all negative edges should be colored alternately $+1$ and 0 . The vertices adjacent to the hexagon get color -1 and the remaining vertex is colored 0 or $+1$. Thus, $\chi(P_{3,2}) = 1$ and $\chi^*(P_{3,2}) = 2$. \square

9.2. Coloration counts

A more refined coloring invariant, the chromatic polynomial, does differ for different signatures of P , and most likely the zero-free chromatic polynomials differ as well. Since the polynomials have degree 10, computing them is too large a project for us. ($\chi_P(y)$ is known; perhaps it is possible to imitate the technique for calculating it in [5, Additional Result 12c].) I propose that the number of proper k -colorations for any $k \geq 1$, and also the number of zero-free proper k -colorations for any $k \geq 2$, is a distinguishing invariant. We prove this for proper 1-colorations.

Theorem 9.4. *The six minimal signatures of the Petersen graph have different chromatic polynomials, and in particular they have different numbers $\chi_{(P,\sigma)}(3)$ of proper 1-colorations.*

Conjecture 9.1. (a) *Any two signed Petersen graphs that are not switching isomorphic have different zero-free chromatic polynomials; in particular, they have different numbers $\chi_{(P,\sigma)}^*(4)$ of zero-free proper 2-colorations.* (b) *For any $\mu \geq 2$, the six values $\chi_{(P,\sigma)}(2\mu + 1)$ are different for the six switching isomorphism classes of signature, and so are the six values $\chi_{(P,\sigma)}^*(2\mu)$.*

We will establish Theorem 9.4 by investigating $\chi_{(P,\sigma)}(3) - \chi_{+P}(3)$ with the aid of several general lemmas and formulas. Calculating the difference give the actual value, because

$$\chi_{+P}(3) = \chi_P(3) = 120.$$

A proof depends on the fact that every 3-coloration of P has the same form as every other, under graph automorphisms and permutations of the colors. In a coloration, define a *head vertex* to be a vertex whose neighbors have only one color. Each proper 3-coloration of P has a unique head vertex; and there are 12 such colorations for each head vertex. (To prove this, examine the two ways to 3-color $N[v]$ where v is the head vertex. We omit the details.) To color with a given head vertex, one chooses its color, then chooses the neighborhood color, then colors the uncolored hexagon with the two non-neighborhood colors. One concludes that $\chi_P(3) = 120$.

We begin preparing for the proof of Theorem 9.4 with the balanced expansion formula of [18, Theorem 1.1], which states that, for any signed graph $\Sigma = (\Gamma, \sigma)$,

$$\chi_\Sigma(2\mu + 1) = \sum_{\substack{W \subseteq V: \\ W \text{ independent}}} \chi_{\Sigma \setminus W}^*(2\mu). \tag{9.1}$$

(The proof is easy, by counting colorations according to the set W with color 0.) Applying this to the difference of Σ and $+\Gamma$,

$$\chi_\Sigma(2\mu + 1) - \chi_{+\Gamma}(2\mu + 1) = \sum_{\substack{W \subseteq V: \\ W \text{ independent}}} \chi_{\Sigma \setminus W}^*(2\mu) - \chi_{+\Gamma \setminus W}^*(2\mu).$$

The term of W disappears if $\Sigma \setminus W$ is balanced; thus,

$$\chi_\Sigma(2\mu + 1) - \chi_\Gamma(2\mu + 1) = \sum_{\substack{W \subseteq V: \\ W \text{ independent,} \\ \Sigma \setminus W \text{ unbalanced}}} \chi_{\Sigma \setminus W}^*(2\mu) - \chi_{\Gamma \setminus W}^*(2\mu), \tag{9.2}$$

since $\chi_{+\Gamma}^*(y) = \chi_\Gamma(y)$.

Observe that

$$\chi_\Sigma^*(2) = \begin{cases} 2^{c(\Sigma)} & \text{if } \Sigma \text{ is antibalanced,} \\ 0 & \text{if it is not.} \end{cases} \tag{9.3}$$

To prove this, suppose that a zero-free, proper 1-coloration exists. Since there are only the two signed colors $+1$ and -1 , a negative edge must have the same color at both ends, and a positive edge must have oppositely signed colors at its ends. Taking the bipartition of V into sets of vertices with the same sign, that means that a positive edge in $-\Sigma$ has both ends in the same part and a negative edge has ends in opposite parts. Hence, $-\Sigma$ is balanced and Σ is antibalanced. If Σ is antibalanced, there are two choices of color in each component.

Table 9.2
The numbers necessary to prove Theorem 9.4.

(P, σ)	$+P$	P_1	$P_{2,2}$	$P_{2,3} \simeq -P_1$	$P_{3,2}$	$P_{3,3} \simeq -P$
$\alpha_0(P, \sigma)$	1	0	0	0	0	0
$\alpha_1(P, \sigma)$	10	2	0	0	0	0
$\alpha_2(P, \sigma)$	30	14	6	4	0	0
$c_6^-(P, \sigma)$	0	4	6	4	10	0
$\chi_{(P,\sigma)}(3) - \chi_{+P}(3)$	0	-8	-12	16	-40	82
$\chi_{(P,\sigma)}(3)$	120	112	108	136	80	202

Lemma 9.5. *If Σ has two of the properties of balance, antibalance, and bipartiteness, then it has the third property as well.*

Proof. Balance means every circle is positive. Antibalance means every even circle is positive and every odd circle is negative. In a bipartite signed graph, balance and antibalance are equivalent. In any signed graph, the conjunction of balance and antibalance implies that there are no odd circles. \square

Now, we can further simplify Eq. (9.2) when $\mu = 1$. By Lemma 9.5, there are three possibilities: $\Gamma \setminus W$ may be bipartite with $\Sigma \setminus W$ not antibalanced, $\Sigma \setminus W$ may be antibalanced but non-bipartite, or it may be non-bipartite and not antibalanced. Then, by Eq. (9.3),

$$\chi_\Sigma(3) - \chi_\Gamma(3) = \sum_{\substack{W \subseteq V: \\ W \text{ independent,} \\ \Sigma \setminus W \text{ antibalanced and not bipartite}}} 2^{c(\Gamma \setminus W)} - \sum_{\substack{W \subseteq V: \\ W \text{ independent,} \\ \Sigma \setminus W \text{ bipartite and not antibalanced}}} 2^{c(\Gamma \setminus W)}. \tag{9.4}$$

Proof of Theorem 9.4. We use a formula deduced from Eq. (9.4). For $k = 0, 1, 2$, let

$$\alpha_k(\Sigma) := \text{the number of independent sets } X \subseteq V \text{ such that } \Sigma \setminus X \text{ is balanced.}$$

Lemma 9.6. *For a signed Petersen graph,*

$$\chi_{(P,\sigma)}(3) - \chi_{+P}(3) = 2\alpha_0(-P, \sigma) + 2\alpha_1(-P, \sigma) + 2\alpha_2(-P, \sigma) - 4c_6^-(P, \sigma). \tag{9.5}$$

Proof. By Section 3, either $|W| \leq 1$, W is a pair of non-adjacent vertices, or $W = N(v)$ for some vertex v . In the former cases, $P \setminus W$ is connected and non-bipartite. In the last case, it is bipartite.

Suppose that $(P, \sigma) \setminus W$ is antibalanced and not bipartite. Because $P \setminus W$ is not bipartite, $|W| \leq 2$. Therefore, $P \setminus W$ is connected, and the term of W contributes 2 to the first summation if $(P, \sigma) \setminus W$ is antibalanced, and 0 otherwise. The respective contributions of W of size 0, 1, 2 are $2\alpha_0(-P, \sigma)$, $2\alpha_1(-P, \sigma)$, and $2\alpha_2(-P, \sigma)$.

Suppose that $P \setminus W$ is bipartite and not antibalanced. Here, $W = N(v)$, so $P \setminus W = H_v \cup K_1$. Because $(P, \sigma) \setminus W$ is not antibalanced, the term of W contributes 4 to the second summation. Each hexagon lies in $P \setminus W$ for a unique $W = N(v)$. Since the contribution of each negative hexagon to (9.5) is -4 , the total contribution of all negative hexagons is $4c_6^-(P, \sigma)$. \square

It remains to evaluate the α_k , as c_6^- is given by Table 6.1. The results are in Table 9.2, along with the values of $\chi_{(P,\sigma)}(3) - \chi_{+P}(3)$ and $\chi_{(P,\sigma)}(3)$.

Some of the values α_k are not obvious. For $P_{3,2}$ and $-P$, all $\alpha_k = 0$ because $l_0 > 2$ (Theorem 7.7). $\alpha_1(P_1) = 2$, because any edge is the intersection of two pentagons, hence only by deleting an endpoint of the negative edge can we balance P_1 . $\alpha_1(P_{2,2}) = \alpha_1(P_{2,3}) = 0$, because each graph has $l_0 > 1$. That leaves α_2 of $P_{2,2}$, P_1 , and $-P_1 \simeq P_{2,3}$.

Consider deleting a non-adjacent vertex pair from $P_{2,2} \simeq -P_{2,2}$. Suppose that the negative edges are $v_{15}v_{34}$ and $v_{23}v_{45}$ (see Fig. 1.1). We get balance by deleting one endpoint of each edge, ignoring $\{v_{15}, v_{23}\}$ because those vertices are adjacent; that is, three vertex pairs. If we switch v_{15} and v_{23} first so the negative edges are $v_{15}v_{24}$ and $v_{23}v_{14}$, we find three more ways to get balance. Thus, the obvious approach gives six balancing sets. These are all. To prove that, we list four negative pentagons forming two vertex-disjoint pairs:

$$A := v_{24}v_{15}v_{34}v_{12}v_{35} \quad \text{and} \quad A' := v_{14}v_{23}v_{45}v_{13}v_{25},$$

and

$$B := v_{14}v_{23}v_{45}v_{12}v_{35} \quad \text{and} \quad B' := v_{34}v_{15}v_{24}v_{13}v_{25}.$$

We need one vertex from each pair, which means (Case 1) one from $A \cap B = \{v_{12}, v_{35}\}$ and one from $A' \cap B' = \{v_{13}, v_{25}\}$, or else (Case 2) one from $A \cap B' = \{v_{24}, v_{15}, v_{34}\}$ and one from $A' \cap B = \{v_{14}, v_{23}, v_{45}\}$. The two other negative pentagons are

$$C := v_{15}v_{23}v_{45}v_{13}v_{24} \quad \text{and} \quad D := v_{34}v_{15}v_{23}v_{14}v_{25}.$$

Case 1 cannot cover both of these. In Case 2, we can take any pair except $v_{24}v_{45}$, $v_{34}v_{14}$, or (because they are adjacent) $v_{15}v_{23}$. Therefore, $\alpha_2(P_{2,2}) = 6$.

Next, consider P_1 with negative edge $v_{15}v_{23}$. The obvious pairs are v_{15} and any non-neighbor, and v_{23} and any of its non-neighbors; that is, 12 pairs. Two pairs that are less obvious are $\{v_{24}, v_{34}\}$ and $\{v_{14}, v_{54}\}$, which eliminate all circles on v_{15} and v_{23} , respectively. To show there are no other possible pairs we list the negative pentagons:

$$D, \quad C, \quad v_{12}v_{34}v_{15}v_{23}v_{45}, \quad v_{14}v_{35}v_{24}v_{13}v_{25}.$$

If a pair excludes v_{15} and v_{23} , it needs one vertex from each of the following triples:

$$v_{12}v_{34}v_{45}, \quad v_{45}v_{13}v_{24}, \quad v_{14}v_{35}v_{24}, \quad v_{14}v_{25}v_{34},$$

in which non-consecutive sets are disjoint. The possible pairs then are $v_{45}v_{14}$ and $v_{24}v_{34}$. Thus, $\alpha_2(P_1) = 14$.

Finally, consider $-P_1 \sim P_{2,3}$ with (after switching X_4) negative edges $e := v_{12}v_{35}$ and $f := v_{13}v_{25}$. The obvious pairs are one from e and one from f . They are the only ones possible. As with $P_{2,2}$, A, A', B, B' are negative, and we have two cases. Case 1 gives the four obvious vertex pairs. Case 2 is impossible, because it fails to cover every negative pentagon, which is every pentagon that does not contain the edge $v_{15}v_{23}$. Hence, $\alpha_2(P_{2,3}) = 4$.

The values of $\chi_{(P,\sigma)}(3) - \chi_{+P}(3)$ and $\chi_{(P,\sigma)}(3)$ follow from Lemma 9.6. (I also calculated $\chi_{P_1}(3)$ and $\chi_{-P}(3)$ directly, confirming the values 112 and 202.) They are different for each switching isomorphism type; that proves the theorem. \square

Theorem 9.4 suggests a problem.

Question 9.1. Is it possible for two switching non-isomorphic signatures of the same graph to have the same chromatic polynomial? Can they have the same zero-free chromatic polynomial?

It is not possible for a 2-regular graph.

Proposition 9.7. Two different, switching non-isomorphic signatures of the same 2-regular graph have different chromatic polynomials and different zero-free chromatic polynomials.

Proof. It suffices to consider a circle C_l with two signatures, σ_0 in which it is positive and σ_1 in which it is negative. It is well known that $\chi_{C_l}(y) = (y - 1)[(y - 1)^{l-1} - (-1)^{l-1}]$; thus,

$$\chi_{(C_l,\sigma_0)}(y) = \chi_{(C_l,\sigma_0)}^*(y) = (y - 1)[(y - 1)^{l-1} - (-1)^{l-1}].$$

To calculate the polynomials of $\Sigma_1 := (C_l, \sigma_1)$, we apply the matroid theory of [20,19]. By [20, Theorem 5.1], the matroid $G(\Sigma_1)$ is the free matroid F_l on l points, whose characteristic polynomial is $\sum_A (-1)^{|A|} y^{|A|}$, summed over all flats, i.e., all subsets of E ; thus it equals $(y - 1)^l$. By [19, Theorem 2.4], $\chi_{\Sigma_1}(y)$ equals the characteristic polynomial of F_l . For $\chi_{\Sigma_1}^*(y)$, we sum only over balanced sets A ; since the only unbalanced flat is E , $\chi_{\Sigma_1}^*(y) = (y - 1)^l - (-1)^l$. \square

A possible approach to Question 9.1 may be through the geometrical interpretation of signed-graph coloring in [4, Section 5].

10. Clusterability

A signed graph Σ is called *clusterable* if its vertices can be partitioned into sets, called clusters, so that each edge within a cluster is positive and each edge between two clusters is negative. Such a partition is a *clustering* of Σ . By Proposition 2.1, balance is clusterability with at most two clusters. Clusterability is the other property we discuss, besides the automorphism group, that is not invariant under switching. Davis proposed it as a possibly more realistic alternative to balance as an ideal state of a social group [7], and he proved the following criterion.

Proposition 10.1. A signed graph is clusterable if and only if no circle has exactly one negative edge.

Clusterability of signed graphs has recently taken on new life in the field of knowledge and document classification under the name ‘correlation clustering’ [2].

There are (at least) two ways to measure clusterability. When Σ is clusterable, the smallest possible number of clusters is the *cluster number* $\text{clu}(\Sigma)$. Even if a signed graph is inclusterable, it becomes clusterable when enough edges are deleted; the smallest such number is the *inclusterability index* $Q(\Sigma)$.

Theorem 10.2. The cluster number of a signed graph is $\text{clu}(\Sigma) = \chi(|\Sigma|/E^+(\Sigma))$. Σ is clusterable if and only if $|\Sigma|/E^+(\Sigma)$ has no loops.

Thus, an all-positive signed graph is a cluster by itself: $\text{clu}(+\Gamma) = 1$. For an all-negative signed graph, $\text{clu}(-\Gamma) = \chi(\Gamma)$.

Table 10.1

The clusterability measures of the minimal signed Petersen graphs and their negatives. A dash denotes an inclusterable signature.

(P, σ)	$+P$	$-P$	P_1	$-P_1$	$P_{2,2}$	$-P_{2,2}$	$P_{2,3}$	$-P_{2,3}$	$P_{3,2}$	$-P_{3,2}$	$P_{3,3}$	$-P_{3,3}$
$\text{clu}(P, \sigma)$	1	3	–	3	–	3	–	3	–	4	–	2
$Q(P, \sigma)$	0	0	1	0	2	0	2	0	3	0	3	0

Proof. In the contraction $\Gamma' := |\Sigma|/E^+$, let $[v] \in V'$ denote the vertex corresponding to $v \in V$.

Suppose that Σ has a clustering $\pi = \{V_1, \dots, V_k\}$ into k parts (with each V_i non-empty). This means, first, that all positive edges are contained within V_i 's, so each $[v]$ is contained within a set V_i . Furthermore, two vertices $[u], [v] \in V'$ that lie within the same V_i are non-adjacent, since $E' = E^-$ and no negative edges are within V_i . Therefore, the function $\kappa : V \rightarrow \{1, 2, \dots, k\}$ defined by $\kappa(v) = i$ if $[v] \subseteq V_i$ is a (proper) coloration of Γ' , and furthermore every color is used at one or more vertices. (κ is determined by π only up to permutations of the colors.)

Conversely, if κ' is a (proper) coloration of Γ' using exactly k colors, say with color set $\{1, 2, \dots, k\}$, let $V_i := \{v \in V : \kappa'([v]) = i\}$. This implies that Γ' has no loops and that every color is applied to a vertex, so no V_i is empty. Then, in Σ , no negative edge can lie within a set V_i and, because every positive edge of Σ is within a set $[v]$, it lies inside a V_i . Hence, $\pi = \{V_1, \dots, V_k\}$ is a clustering of Σ into k clusters.

Consequently, k -clusterings of Σ coincide (modulo permuting the colors) with k -colorations of Γ' that use all k colors, for any k . The theorem follows immediately. \square

Observe that $|\Sigma|/E^+(\Sigma) = |\Sigma|/E^-(-\Sigma)$. Thus, the contraction used here in connection with Σ is the same one used in Theorem 9.2 in connection with $-\Sigma$.

To supplement Davis's criterion for clusterability—that is, for zero inclusterability index—we state a criterion for unit index. The proof is a simple check.

Proposition 10.3. $Q(\Sigma) = 1$ if and only if there is a circle with exactly one negative edge and there is an edge common to all such circles.

Theorem 10.4. The clusterabilities of the minimal signed Petersen graphs and their negatives are as stated in Table 10.1.

Proof. The cluster numbers are obvious for $+P$, which is balanced, and $P_1, P_{2,2}, P_{2,3}, P_{3,2}, P_{3,3}$, all of which violate Davis's criterion for clusterability. The negatives of these graphs are clusterable; their cluster numbers follow from Theorem 10.2. Specifically, we have the following observations.

The contraction $P/E^+(-P_{2,2})$ has a triangle and is easy to color in three colors; thus, $\text{clu}(-P_{2,2}) = 3$.

The more complex graph $P/E^+(-P_{3,2})$ consists of three triangles overlapping at vertices—which require three colors arranged so that the three divalent vertices have different colors—and one more vertex adjacent to the divalent vertices; therefore, the chromatic number is 4. This gives $\text{clu}(-P_{3,2}) = 4$.

The contraction $P/E^+(-P_{3,3}) = K_{3,4}$. Thus, $\text{clu}(-P_{3,3}) = 2$.

The contraction $P/E^+(-P_{2,3})$ is $K_{3,4}$ with one vertex split, forming a C_5 . As the contraction is non-bipartite, $\text{clu}(-P_{2,3}) > 2$, but, as only one vertex was split, only one more color is needed.

The fact that clusterability is equivalent to having inclusterability index 0 leaves five signatures with positive inclusterability index. Clearly, $Q(\Sigma) \leq |E^-|$. This implies that $Q(P_1) = 1$. Proposition 10.3 implies that the other inclusterability indices are at least 2, since in each $P_{k,d}$ there are two edge-disjoint circles containing exactly one negative edge each. Consequently, $Q(P_{2,2}) = Q(P_{2,3}) = 2$.

In each of $P_{3,2}$ and $P_{3,3}$, all the pentagons with one edge on the outer pentagon in Fig. 10.1 have exactly one negative edge. Call them the sharp pentagons. To make the signed graph clusterable we must eliminate (at least) all sharp pentagons; thus, we have to remove at least an edge from each one. Any two sharp pentagons have just one edge in common, and no three of them have a common edge. Therefore, to eliminate sharp pentagons one has to delete at least three edges. It follows that $Q(P_{3,2}) = Q(P_{3,3}) = 3$. \square

As clusterability is not a switching invariant, the data in Table 10.1 are not sufficient to describe all signatures of the Petersen graph. The number of inequivalent clustering problems equals the number of non-isomorphic edge 2-colorations of P , which is large. This makes it interesting to ask about the maximum inclusterability of P , defined as the maximum inclusterability index of any signature.

Theorem 10.5. The largest inclusterability index of any signed Petersen graph is 3.

Proof. Several of the signatures in Table 10.1 attain inclusterability 3, so the problem is to prove no higher value is possible.

We begin with two general observations. First, every signed graph satisfies

$$\Sigma' \subseteq \Sigma \implies Q(\Sigma') \leq Q(\Sigma). \tag{10.1}$$

Second, here are properties of general graphs and cubic graphs.

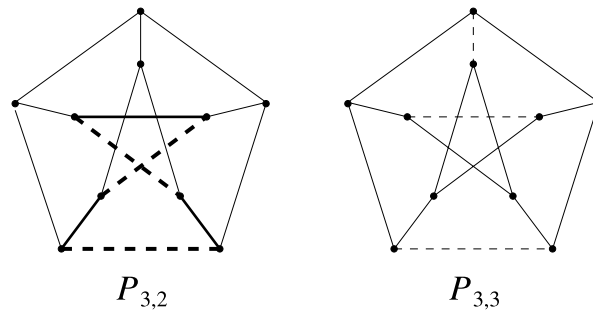


Fig. 10.1. Signed Petersen graphs with three negative edges. Each sharp pentagon has one negative edge.

Lemma 10.6. *If the underlying graph of a signed graph Σ has a cut with more negative than positive edges, then $Q(\Sigma) < |E^-|$.*

Proof. If there is a cut ∇X with more negative than positive edges, delete the positive edges of ∇X and any negative edges outside ∇X . In the remaining graph $(P, \sigma) \setminus S$, the negative edges form a cut, so $(P, \sigma) \setminus S$ is clusterable; but, as the number of edges that were deleted is less than $|E^-|$, $Q(P, \sigma) < |E^-|$. \square

Proposition 10.7. *Let Γ be a graph whose maximum degree is at most 3. The maximum inclusterability index of any signature is attained only by signatures in which the negative edge set is a matching.*

Proof. This follows from Lemma 10.6 by examining the vertex cuts $\nabla\{v\}$ in a signature that maximizes inclusterability. \square

Proof of Theorem 10.5, continued. We may assume that (P, σ) is a signed Petersen that has maximum inclusterability and that E^- is a matching. A matching in P has at most five edges. The matchings were classified in Section 3.2.

If $|E^-|$ has five edges, it separates two pentagons. Since $(P, \sigma) \setminus E^-$ is all positive, (P, σ) is clusterable with two clusters that are the vertex sets of the pentagons of $P \setminus E^-$.

Suppose, then, that E^- is a matching with four edges.

Lemma 10.6 applies when $E^- = M_5 \setminus \text{edge}$, with $X = V(C)$, where C is one of the pentagons separated by M_5 .

If the matching is M'_4 , there is a hexagon H_{lm} with three negative edges and the fourth negative edge d is incident with v_{lm} (Fig. 3.1). The two negative edges at distance 2 from d , together with d , are part of an M_5 that is a 5-edge cut with three negative edges.

It follows that $Q(P, \sigma) < 4$ when E^- is a 4-edge matching, so the theorem is proved. \square

11. Other aspects

The signed Petersen graphs have other properties that we intend to treat elsewhere.

For instance, we can establish the smallest surface in which each (P, σ) can be embedded so that a circle is orientable if and only if it is positive (this is called *orientation embedding*). This embeddability, by its definition, is a property of switching isomorphism classes, so there are just six cases. The only signature that embeds in the projective plane is $P_{2,3}$; as P is non-planar, every other signature of P embeds only in a higher non-orientable surface (if not balanced) or in the torus (if balanced).

Another aspect is the relationship between (P, σ) and its signed covering graph (the ‘derived graph’ of [5, Section 9]), in which each vertex of P splits into a pair, $+v$ and $-v$, and edges double as well, with positive edges connecting vertices of the same sign and negative edges connecting vertices of opposite sign. The switching automorphisms of the signed graph are closely related to the fibered automorphisms of the signed covering.

As $\text{Aut } \Sigma$ is not invariant under switching, there is a very large number of possible automorphism groups of signed Petersen graphs: as many as there are non-isomorphic sets of signatures with Σ and $-\Sigma$ paired together. (We should pair $\text{Aut}(\Sigma)$ with $\text{Aut}(-\Sigma)$ because they have the same automorphisms, by Proposition 8.6.) That is equivalent to finding the automorphism groups of all edge 2-colored Petersen graphs. The number of non-automorphic ways to edge 2-color P is given by [13, Eq. (24)]. The number of automorphism groups of such colorations is unknown to me.

Switching and the switching automorphism group generalize from the sign group to any group \mathfrak{G} . A *gain graph* is a graph whose edges are labelled invertibly by elements of \mathfrak{G} ; this means that, if $\varphi(e)$ is the gain of oriented edge e and e^{-1} is e in the opposite orientation, then $\varphi(e^{-1}) = \varphi(e)^{-1}$. Gain graphs and switching over arbitrary groups were introduced in [21]. Many of the basic properties of switching automorphisms should extend to the general case, though some, such as the simple description of the switching kernel \mathfrak{K} , may depend on having an abelian group, and some (those that depend upon the property that the gain is independent of direction) require a group of exponent 2. This brief description is just an outline; a complete theory of switching automorphisms over an arbitrary gain group, and its application to examples, are open problems.

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