

## SHRINKING WITHOUT LENGTHENING

R. H. BING

*With great sadness and a profound sense of loss we must relate that shortly after submission of this manuscript to *Topology* Professor Bing passed away. The journal is grateful to his wife Mary Bing and to his colleague and admirer Bob Edwards for their help with final editorial details.*

IT WAS shown in [2] that the union of two solid Alexander horned balls sewed together along their boundaries with the identity map is homeomorphic to a 3-sphere. (The Alexander horned ball is the closed *exterior* complement in  $S^3$  of the strangely embedded 2-sphere described by Alexander; see Fig. 1.) This led to the conclusion that there is a homeomorphism of period two (an involution) of a 3-sphere onto itself having as its fixed point set a wild 2-sphere—one simply swaps the two halves of the above union. Such an involution is not equivalent to any PL or differential homeomorphism and is considered wild. (Two homeomorphisms  $h_1, h_2$  are equivalent if there is a homeomorphism  $h$  such that  $h_1 = h^{-1} h_2 h$ .) Later it was discovered [1, 3, 5] that there are uncountably many mutually inequivalent wild involutions and indeed there are wild periodic homeomorphisms of  $S^3$  onto itself of all periods.

The original description in [2] of the union of the Alexander horned balls considered each to appear as shown in Fig. 1. It was noted that this Alexander horned ball is the decomposition space of a 3-cell  $I^3$  as shown in Fig. 2 where the nondegenerate elements of the decomposition are tame arcs. Each of these arcs is the intersection of a decreasing sequence of folded solid cylinders  $C, C_i, C_{ij}, \dots$  with bases on the base of  $I^3$  as shown in Fig. 3, but each arc has just one end on the base of  $I^3$  and each horizontal cross section of each arc is just one point.

It is easier to visualize the union of two copies of  $I^3$  with their associated decompositions than it is to picture the union of two Alexander horned balls. The union of the decomposition spaces would be a decomposition of  $I_1^3 \cup I_2^3 = S^3$  whose nondegenerate

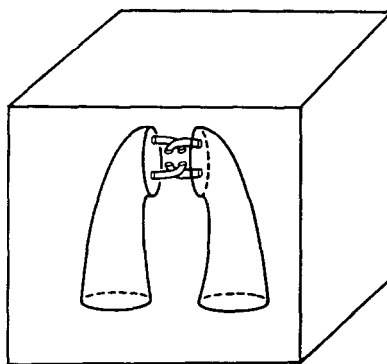


Fig. 1.

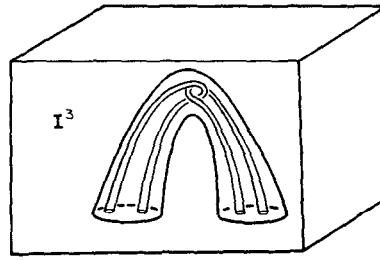


Fig. 2.

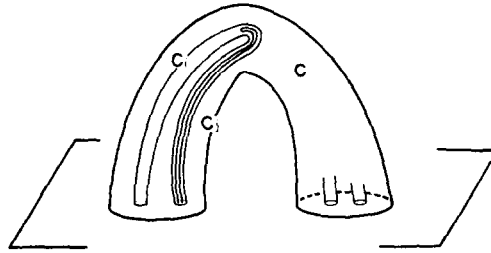


Fig. 3.

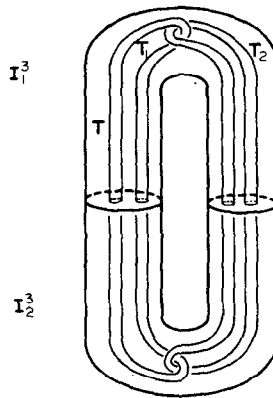


Fig. 4.

elements are tame arcs each of which is the intersection of solid tori  $T, T_i, T_{ij}, \dots$  as shown in Fig. 4. We say that  $T, T_i, T_{ij}, \dots$  are tori at the 0th, 1st, 2nd,  $\dots$  stages respectively.

It was shown in [2] that the decomposition space for Fig. 4 is a 3-sphere by showing that for each  $\epsilon_1 > 0$ , there is an integer  $n_1$  such that there is a homeomorphism  $h_1$  of  $S^3$  onto itself fixed outside  $T$  such that the images of the solid tori at the  $n_1$ th stage have diameters less than  $\epsilon_1$ . (See Theorem 1 below.) Similarly one can construct a homeomorphism  $h_2$  that agrees with  $h_1$  outside the solid tori at the  $n_1$ th stage but shrinks solid tori at some  $n_2$ th stage to images with diameters less than  $\epsilon_2 = \epsilon_1/2$ . Iterating the procedure gives a decomposition map  $(\lim h_1, h_2, \dots)$  showing that the decomposition space is a 3-sphere and indeed, the union of two Alexander horned balls sewed together on their boundaries with the identity map is a 3-sphere.

In getting the homeomorphism  $h_1$  to shrink the tori at the  $n_1$ th stage, no effort was made to decrease the lengths of their centerlines. Let us consider the case where  $T$  is long and thin

(so that we can ignore vertical distances) and the length of the centerline of  $T$  is  $2\epsilon$ , so that the horizontal size of  $T$  as in Fig. 5 is approximately  $\epsilon$ . Suppose we want to get a homeomorphism  $h$  that is fixed on  $BdT$  and takes the inside  $T$ 's at some future stage to images with diameters less than  $\epsilon/4$ . Let us consider several ways to proceed.

One such way might be to move  $T_1$  and  $T_2$  about as shown in Fig. 5 so that the new  $T_i$ 's have diameters less than  $\epsilon/2$ . This method is sometimes called the "standard mistake" because there is no way to move the new  $T_{i1}$  and  $T_{i2}$  about in the new  $T_i$  to significantly reduce their diameters.

To avoid this apparent trap a different procedure was followed in [2]. Rather than get new  $T_i$ 's at the first step with diameters less than  $\epsilon/2$ , we contented ourselves to get them with diameter less than  $3\epsilon/4$  as shown in Fig. 6.

A vertically enlarged copy of the new  $T_i$  appears in Fig. 7 with the way that the new  $T_{i1}$  and  $T_{i2}$  might appear in it. Each of the new  $T_{i1}$  and  $T_{i2}$  has a diameter approximately  $\epsilon/2$  (even though the length of the centerline of  $T_{i1}$  is more than  $2\epsilon$ ). It is an easy task to place a new  $T_{i21}$  and a new  $T_{i22}$  in the new  $T_{i2}$  (using the "standard mistake") to make them have diameters approximately  $\epsilon/4$  and Fig. 8 shows how a new  $T_{i11}$  and  $T_{i12}$  could be placed in the new  $T_{i1}$  to make them have diameters approximately  $\epsilon/4$ . (We hesitate to show all of  $T_{i11}$  since it is so long.)

By using an arbitrary number  $n$  in place of 4 and following a similar procedure we can get new  $T$ 's so that for  $m=1, 2, \dots, n-1$  the new  $T$ 's at the  $m$ th stage have diameters less than  $(1 - (m/n))\epsilon$ . Hence, we have the following result from [2].



Fig. 5.

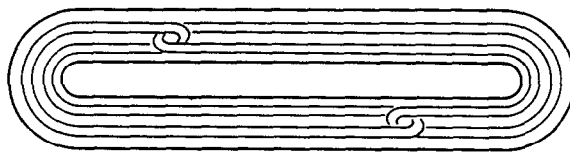


Fig. 6.

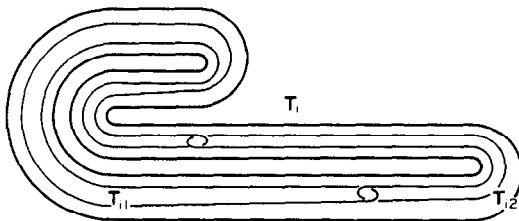


Fig. 7.

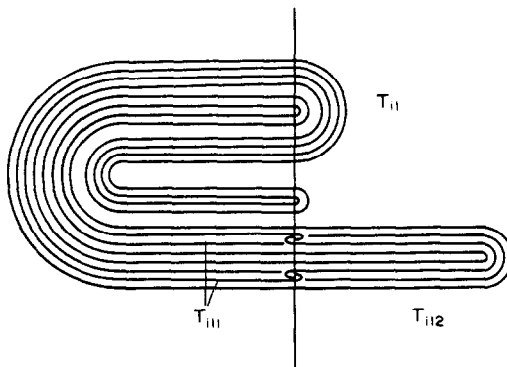


Fig. 8.

**THEOREM 1.** *Suppose the length of the centerline  $T \leq 2\epsilon$  and  $n$  is a positive integer. Then there is a homeomorphism  $h$  of  $T$  onto itself that is fixed on  $BdT$  such that for each  $T_{ij\dots k}$  at the  $(n-1)$ st stage*

$$\text{diameter } h(T_{ij\dots k}) < \epsilon/n.$$

A homeomorphism  $h$  such as we have described to prove Theorem 1 would have increased the lengths of the images of centerlines of some of the  $T_{1ij\dots k}$ 's drastically. Michael Freedman asked if there is a homeomorphism  $h$  that does not. We give an affirmative answer in Theorem 2 in the case where  $n$  is of form  $2^m$ . Theorem 2 has had applications in [4].

**THEOREM 2.** *Suppose the length of the centerline of  $T \leq 2\epsilon$  and  $n$  is a nonnegative integer. Then there is a homeomorphism  $h$  of  $T$  onto itself that is fixed on  $BdT$  and such that for each integer  $m$  with  $0 \leq m \leq n$  and for each  $T_{ij\dots k}$  at the  $2^m$ th stage*

$$\begin{aligned} \text{diameter of } h(T_{ij\dots k}) &< \epsilon/2^m \text{ and} \\ \text{length of centerline of } h(T_{ij\dots k}) &< 2\epsilon. \end{aligned}$$

*Description of  $h$ .* By reselecting the centerline of  $T$  we can suppose that the reselected centerline  $S$  has length less than  $2\epsilon$ . Each of the centerlines  $S_1, S_2$  of the adjusted  $T_1, T_2$  runs parallel to one half of  $S$ , makes a turn, then runs back parallel to the same half, and finally makes a turn to connect to the start. We say that  $S_1$  and  $S_2$  "hook elbows" at the turns. The lengths of the turns are so short that they will be ignored. We suppose that the halves of  $S_1$  and  $S_2$  are so close and parallel to halves of  $S$  that the length of each  $S_i$  is about twice the length of one half of  $S$ . By cutting corners we could make the lengths of  $S_1$  and  $S_2$  less than the length of  $S$  but shall not concern ourselves with this. We note that  $S_1$  and  $S_2$  are each so close to one half of  $S$  that their diameters are less than  $\epsilon$ . Hence, we suppose that the diameters of the new  $T_i$ 's at the 1st stage are less than  $\epsilon = \epsilon/2^0$  where  $2^0 = 1$ . We remark that, unlike in the proof of Theorem 1, the two first stage tori  $T_i$  in this proof are not rotated, simply so that the  $2^m$ th stages rather than the  $(2^m - 1)$ st stages are the most interesting ones in the subsequent discussion.

Centerlines  $S_{ij\dots k}$  of each new  $T_{ij\dots k}$  will zig-zag along  $S$  and be so close and parallel to  $S$  that we ignore the lengths at the turns and estimate the length of  $S_{ij\dots k}$  by the sum of the lengths of the projections of its pieces on  $S$ . The bends in the zig-zagging of  $S_{ij\dots k}$  are determined by two kinds of turns—those that occur at "linking elbows" and those forced by the fact that the centerlines lie in zig-zagging tubes. These interior turns in the zig-zagging

tubes were created by “hooking elbow” turns at previous stages. A “hooking elbow” turn at one stage (as well as an interior turn at that stage) causes an interior turn at the next.

Our goal is to describe new  $T_{ij\dots k}$ 's (which for convenience we continue to call  $T_{ij\dots k}$ 's) so that for each integer  $m$  with  $0 \leq m \leq n$ , the diameters of the  $T_{ij\dots k}$ 's at the  $2^m$ th stage are less than  $\epsilon/2^m$ .

Each  $S_{ij\dots k}$  will be the union of two arcs joined at their ends and which otherwise run parallel to each other and to the same zig-zagging arc  $P_{ij\dots k}$ . We regard the length of  $S_{ij\dots k}$  to be about twice the length of  $P_{ij\dots k}$  and the diameter of  $T_{ij\dots k}$  to be about the same as the diameter of  $P_{ij\dots k}$ . If  $P_{ij\dots k}$  is of length less than  $\epsilon$  and it bends precisely at all the points that divide it into  $2^m$  equal pieces, we suppose that the diameter of  $P_{ij\dots k}$  (and hence that the diameter of  $T_{ij\dots k}$ ) is less than  $\epsilon/2^m$ .

We use Fig. 9 to show how  $S_{i1}$  and  $S_{i2}$  lie in  $T_i$ . Note that we have used the “standard mistake” but we are only at the  $2^1$ th stage and only require that diameters be less than  $\epsilon/2^1$ .

We draw  $P_{ij\dots k}$  as straight or curved depending on which is convenient. We place circles on  $P_{ij\dots k}$  to show where it bends. Figure 10a shows  $P_i$  straight (with no circle on it and  $P_{ij}$  with one bend (and one circle) and  $P_{ijk}$  with two bends (and two circles). Figure 10b shows  $P_{ijk}$  with two circles and  $P_{ijks}$  with three. Note that the bend points of  $P_{ijk}$  are at the quarter and three-quarter marks but there is none at its center. The diameter of  $P_{ijk}$  is about the same as that of  $P_{ij}$  but that of  $P_{ijks}$  is only about half as much.

All of the  $P_{ij\dots k}$ 's at any stage have their bends at similar places. We denote a typical  $P_{ij\dots k}$  at the  $m$ th stage by  $Q_m$  and show it straight but with circles at the bends. Figure 11 shows  $Q_1, Q_2, \dots, Q_8$ . It is to be noticed that if the length of  $Q_1$  is less than  $\epsilon$ , the length of the pieces between turns of  $Q_1, Q_2, Q_4, Q_8$  are less than  $\epsilon, \epsilon/2, \epsilon/4, \epsilon/8$  respectively so the diameter of the  $T$ 's at the 1st, 2nd, 4th, and 8th stages have diameter less than  $\epsilon/2^0, \epsilon/2^1, \epsilon/2^2, \epsilon/2^3$ .

We now make certain observations about the  $Q$ 's that will help us define other  $Q$ 's and make similar observations about them. Each of the  $Q$ 's is symmetric about its center, as is each of the halves of a  $Q$ . (For considering a half, we ignore any circle at an end of the half.) In general, we will define  $Q$ 's so that if they are broken into  $2^i$  equal pieces, each of these pieces is alike and is a shrunken version of a previously defined  $Q$ . If  $m$  is odd,  $Q_m$  does not have a circle

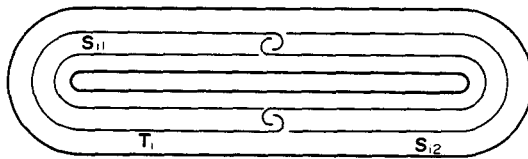


Fig. 9.

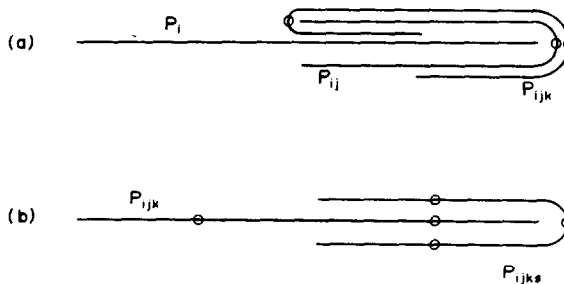


Fig. 10.

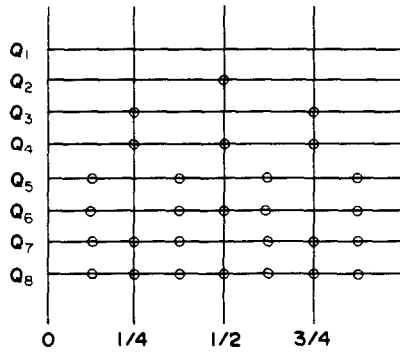


Fig. 11.

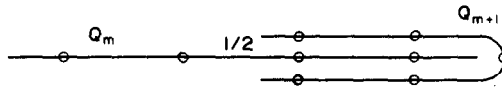


Fig. 12.

at its center and  $Q_{m+1}$  is formed from  $Q_m$  by placing a circle on  $Q_m$  at  $1/2$ . If  $m$  is even,  $Q_{m+1}$  does not have a circle at its center and each half of it looks like a one-half multiple of  $Q_r$ , where  $r = (m + 2)/2$ . Once we have obtained  $Q_i$ 's ( $i = 1, 2, \dots, m$ ) satisfying these observations, these observations produce a unique  $Q_{m+1}$  satisfying them.

Finally, we show how we can slide the  $T_i$ 's at the  $(m + 1)$ st stage about in those at the  $m$ th to get  $Q$ 's as we have described. Figure 12 shows how to do this if  $m$  is odd and  $Q_m$  has no circle at its center. The extra circle at the center of  $Q_{m+1}$  is where  $Q_{m+1}$  goes around the end. We considered each  $T_i$  at the  $m$ th stage and rotated the inner part of it containing the  $T_i$ 's at the  $(m + 1)$ st stage in it through  $\pi/2$  radians. We note that each half of  $Q_{m+1}$  (as does each half of  $Q_m$ ) looks like a reduced copy of  $Q_r$  for  $r = (m + 1)/2$ .

Figure 13 shows how the slide should be done if  $m$  is even. The "hooking elbows" occur at  $1/2^t$  and  $1 - 1/2^t$  where  $1/2^t$  is the largest of the numbers  $1/2, 1/4, 1/8, \dots$  denoting a point where  $Q_m$  is not circled. Rotation of an  $(m + 1)$ st stage  $T_i$  in an  $m$ th stage  $T_i$  is through  $\pi/2^t$ .

Actually, if  $1/2$  is uncircled,  $m$  is odd and we are at the preceding case. If  $1/2^t$  is the first such uncircled point of  $Q_m$ , then all points of the forms  $s/2^t$  are uncircled for  $s$  odd and circled for  $s$  even. The symmetry and equivalences of the pieces of  $Q_m$  of size  $1/2^t$  shows  $Q_{m+1}$  has circles at the required points.

A few philosophical comments seem appropriate now that Theorem 2 is complete. Figure 11 appears simple but it was not easy to discover. It was actually found by working backwards. If in eight steps one had  $Q_8$ , what would  $Q_7$  look like? There was only one possibility. The big gap would have to be in the middle. Once  $Q_7$  were found, what would  $Q_6$  look like? Where would the big gaps be? Actually, more complicated  $Q$ 's like  $Q_{32}, Q_{128}, Q_{2^m}$  were being considered at the time, but  $Q_8$  illustrates the principle just as well and it is easier to work back to  $Q_1$  from  $Q_8$  than from  $Q_{128}$ . This suggests several adages.

*Learning to understand a complicated situation may be aided by considering an easier one. [ $Q_8$  is easier than  $Q_{2^m}$ .]*

*In trying to find the steps of a proof it is sometimes useful to work backwards and get the last steps first. [Count 8, 7, 6, ... rather than 1, 2, 3, ...]*

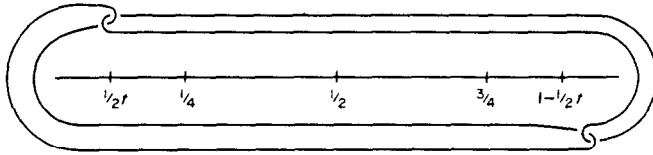


Fig. 13.

*In trying to solve a difficult problem, do not overlook the possibility of rephrasing it and looking at the problem from a different point of view. [Decompositions were used to study unions.]*

#### REFERENCES

1. W. R. ALFORD: Uncountably many different involutions of  $S^3$ , *Proc. Am. math. Soc.* **17** (1966), 186–196.
2. R. H. BING: A homeomorphism between the 3-sphere and the sum of two solid horned spheres, *Ann. Math.* **56** (1952), 354–362.
3. R. H. BING: Inequivalent families of periodic homeomorphisms of  $E^3$ , *Ann. Math.* **80** (1964), 78–93.
4. M. H. FREEDMAN and R. SKORA: Strange actions of groups on spheres, preprint.
5. D. MONTGOMERY and L. ZIPPIN: Examples of transformation groups, *Proc. Am. math. Soc.* **5** (1954), 460–465.

*Department of Mathematics  
The University of Texas at Austin  
Austin, TX 78712  
U.S.A*