# Asymptotic Equivalence of Abstract Parabolic Equations with Delays 

L. E. Bobisud<br>Department of Mathematics, University of Idaho, Moscow, Idaho 83843

Submitted by K. L. Cooke

Let $A$ be an elliptic operator without time dependence, let $\tau>0$ be fixed, and consider the parabolic equation with time delay

$$
\begin{equation*}
u^{\prime}(t)=A u(t)+f(t, u(t-\tau)) \tag{1}
\end{equation*}
$$

To render (1) well posed, one must specify boundary conditions and the initial value of $u$ for $-\tau \leqslant t \leqslant 0$; such matters are considered in [8-12]. The concern here is not with questions of existence, uniqueness, and continuous dependence, but rather with the detectability of the term $f$ in (1) for large $t$. That is, we ask under what restrictions on $A$ and $f$ will it be impossible to distinguish between bounded solutions of (1) and bounded solutions of

$$
\begin{equation*}
v^{\prime}(t)=A v(t) \tag{2}
\end{equation*}
$$

for sufficiently large time. Specifically, we seek conditions on $f$ which will guarantee that for any bounded solution $u(t)$ of (1) there exists for large time a solution $v(t)$ of (2) such that

$$
\lim _{t \rightarrow \infty}\|u(t)-v(t)\|=0
$$

for some suitable space-variable norm $\|\cdot\|$, and conversely. Such questions for ordinary differential equations have been considered in $[1,3]$ among others; for systems of ordinary differential equations with delays see the recent paper of Cooke [2] and references therein.

Instead of dealing directly with (1) and (2), where $A$ is a member of a certain class of elliptic differential operators, we prefer to deal with an abstract problem on a Banach space; we shall also consider a more general time delay than that discussed above. Let then $\mathscr{X}$ be a Banach space with norm $\|\cdot\|$ and let $\tau>0$; with no loss of generality we may conveniently consider the time scale so chosen
that $\tau<1$. Let $\mathscr{C}$ be the Banach space of continuous maps from the interval $[-\tau, 0]$ into $\mathscr{X}$ with the norm of $\phi \in \mathscr{C}$ given by

$$
\|\phi\|_{0}=\max _{-\tau \leqslant t \leqslant 0}\|\phi(t)\| .
$$

If $t_{0} \geqslant 0$ is a real number and $x$ a continuous function from $\left[t_{0}-\tau, \infty\right)$ into $\mathscr{X}$, then for each $t \in\left[t_{0}, \infty\right)$ we define the element $x_{t} \in \mathscr{C}$ by

$$
x_{t}(s)=x(t \mid s) \quad(\quad \tau \leqslant s \leqslant 0)
$$

Let $A: \mathscr{X} \supset \mathscr{D}(A) \rightarrow \mathscr{X}$ be closed with dense domain. We shall assume that $A$ generates an analytic semigroup $T_{A}(t)(t \geqslant 0)$. This implies that, for all $x \in \mathscr{X}$, $T_{A}(t) x$ is differentiable for $t>0$ and

$$
(d / d t) T_{A}(t) x=A T_{A}(t) x
$$

and that there is a constant $K$ such that [5-7]

$$
\left\|T_{A}(t)\right\| \leqslant K, \quad\left\|A T_{A}(t)\right\| \leqslant K / t
$$

With $R_{+}=\{t \mid t \geqslant 0\}$, let $f: R_{+} \times \mathscr{C} \rightarrow \mathscr{X}$ and $b: R_{+} \rightarrow \mathscr{X}$. Then our problem can be formulated as: under what conditions on $f$ and $b$ is the equation

$$
\begin{equation*}
u^{\prime}(t)=A u(t)+b(t)+f\left(t, u_{t}\right) \tag{3}
\end{equation*}
$$

asymptotically equivalent to the equation

$$
\begin{equation*}
v^{\prime}(t)=A v(t)+b(t) \tag{4}
\end{equation*}
$$

in the sense that for any bounded solution of (3) there exists a bounded solution of (4) such that

$$
\lim _{t \rightarrow \infty}\|u(t)-v(t)\|=0
$$

and conversely. Here by a solution of (3) on ( $0, T$ ] we mean a function $u:[0, T] \rightarrow \mathscr{X}$ such that $u$ is strongly continuous on $[0, T]$, strongly continuously differentiable on $(0, T], u(t) \in \mathscr{D}(A)$ for $t \in(0, t]$, and $u(t)$ satisfies (3). A similar definition applies to (4).

## The Abstract Theorem

The following technical lemma is well known [5, 7].
Lemma. Let $A$ be a closed operator in $\mathscr{X}$. Let $b \leqslant \infty$, let $c(t)$ be continuous on $[a, b)$ to $\mathscr{X}$ with $c(t) \in \mathscr{D}(A)$ and $A c(t)$ continuous on $[a, b)$. If the improper integrals

$$
\int_{a}^{b} c(t) d t, \quad \int_{a}^{b} A c(t) d t
$$

exist, then $\int_{a}^{b} c(t) d t \in \mathscr{D}(A)$ and

$$
A \int_{a}^{b} c(t) d t=\int_{a}^{b} A c(t) d t
$$

The following, our basic result on the asymptotic equivalence of (3) and (4), is an extension of a classical result for ordinary differential equations [1,3]. Concrete applications to parabolic equations will be given in the last section of the paper.

Theorem 1. Let $A$ generate the analytic semigroup $T_{A}(t)$, and let $P: X \rightarrow X$ be a bounded projection with range in the null space of $A$ and which commutes with $T_{A}(t)$ for $t \geqslant 0(P \equiv 0$ is allowed $)$. Let $b(t)$ be uniformly Hölder continuous, and let $f(t, \phi)$ satisfy the following conditions:
(a) fis continuous on $R_{+} \times \mathscr{C}$.
(b) $\lim _{t \rightarrow \infty}\|f(t, 0)\|=0$ and $\int_{0}^{\infty}\|f(t, 0)\| d t<\infty$.
(c) For each $N>0$ there exists $\gamma(s, N) \equiv \gamma(s)$ such that for $\left\|\phi_{1}\right\| \leqslant N$, $\left\|\phi_{2}\right\| \leqslant N$ we have $\left\|f\left(s, \phi_{1}\right)-f\left(s, \phi_{2}\right)\right\| \leqslant \gamma(s)\left\|\phi_{1}-\phi_{2}\right\|_{0}$, where

$$
\lim _{t \rightarrow \infty} \gamma(t)=0 \quad \text { and } \quad \int_{0}^{\infty} \gamma(t) d t<\infty
$$

(d) $\|f(s, \phi)-f(t, \phi)\| \leqslant \mu\left(t,\|\phi\|_{0}\right)|s-t|^{\beta}$, where $0<\beta \leqslant 1, t+1>$ $s>t>0$, and $\mu$ is increasing in the second argument and continuous in the first. Then there is a one-to-one correspondence between bounded solutions of (3) and bounded solutions of (4). Moreover, if $\lim _{t \rightarrow \infty}\left\|T_{A}(t)(1-P) x\right\|=0$ for each fixed $x \in \mathscr{X}$ and if $u(t)$ is a bounded solution of (3) and $v(t)$ the corresponding solution of (4), then

$$
\lim _{t \rightarrow \infty}\|u(t)-v(t)\|=0
$$

Proof. Let

$$
\Psi_{\alpha}=\max \left(1, \sup _{0<\nu<1} \frac{(\nu+\tau) \ln (\nu+\tau)-\nu \ln \nu-\tau \ln \tau}{\nu^{\alpha}}\right) ;
$$

straightforward application of l'Hôpital's rule shows that $\Psi_{\alpha}<\infty$ for $0<\alpha<1$. Let $y(t):\left[t_{2}-\tau, \infty\right) \rightarrow \mathscr{X}$ for some $t_{2} \geqslant \tau$ satisfy (i) $y_{t} \in \mathscr{C}$ for $t \geqslant t_{2}$,
(ii) $\sup _{t \geqslant t_{2}}\left\|y_{t}\right\|_{0}=\sup _{t \geqslant t_{2}-\tau}\|y(t)\| \leqslant \rho$,
(iii) $\sup _{s>t>t_{2},|s-t|<1}\left\|y_{s}-y_{t}\right\|_{0} /|s-t|^{\alpha} \equiv M<\infty \quad$ for $\quad$ some $\quad \alpha$, $0<\alpha<1$.

Condition (iii) states that $y$ satisfies a sort of local Hölder continuity of exponent $\alpha$ with Hölder coefficient $M$. We have assumed that there is a $K(\geqslant 1)$ such that
\| $T_{A}(t) \| \leqslant K$ for $t \geqslant 0$. Choose $t_{1} \geqslant t_{2}$ so large that the following estimates are valid for $\gamma(t)=\gamma(t, 3 \rho)$ :

$$
\begin{array}{lr}
\Theta=K \int_{t_{1}}^{\alpha} \gamma(t) d t<\min \left(\frac{1}{3}, \frac{M \tau}{72 \rho}\right), & \sup _{t \geqslant t_{1}-\tau} \gamma(t) \leqslant \frac{M}{72 K \rho \Psi_{a}}, \\
K \int_{t_{1}}^{\alpha} \mid f(s, 0) \| d s<\min \left(\rho, \frac{M \tau}{24}\right), & \sup _{t \geqslant t_{1}-\tau}\|f(s, 0)\|<\frac{M}{24 K \Psi_{x}} .
\end{array}
$$

Let $\mathscr{F}_{a}$ be the set of all functions $x:\left[t_{1}-\tau, \infty\right) \rightarrow x$ such that
(i) $x_{t} \in \mathscr{C}$ for $t \geqslant t_{1}$,
(ii) $|x|\} \equiv \sup _{t \geq t_{1}}\left\|x_{t}\right\|_{0}=\sup _{t \geqslant t_{1}-\sigma}\|x(t)\| \leqslant 3 \rho$,
(iii) $\sup _{s>t>t_{1}, s-t<1}\left\|x_{s}-x_{t}\right\|_{0} /|s-t|^{\alpha} \leqslant 2 M$.

Then $\mathscr{S}_{\alpha}$ is a closed subset of the Banach space of continuous functions from $\left[t_{1}-\tau, \infty\right)$ to $\mathscr{X}$ with norm $\| \cdot l:$. To see this, it is necessary only to show that the uniform limit of functions satisfying a local Hölder condition with a fixed bound on the Hölder coefficient is also locally Hölder continuous with the same bound on the Hölder coefficient. Let then $\left\|x_{n}-x\right\| \rightarrow 0$, and let $\epsilon>0, s$, and $t(0<|s-t|<1)$ be given. Choose $n$ so large that $\left\|x_{n}(t)-x(t)\right\|<\epsilon \mid s-t^{\prime \alpha}$, $\left\|x_{n}(s)-x(s)\right\|<\epsilon|s-t|^{\alpha}$. Then

$$
\begin{aligned}
\frac{\|x(s)-x(t)\|}{|s-t|^{\alpha}} & \leqslant \frac{\| x(s)-x_{n}(s)}{|s-t|^{\alpha}}+\frac{\| x_{n}(s)-x_{n}(t)}{|s-t|^{\alpha}}-\frac{\left\|x_{n}(t)-x(t)\right\|}{|s-t|^{\alpha}} \\
& \leqslant 2 \epsilon+2 M,
\end{aligned}
$$

where $\epsilon>0$ is arbitrary. It follows that

$$
\frac{\|x(s)-x(t)\|}{|s-t|^{\alpha}} \leqslant 2 M
$$

whence

$$
\frac{\left\|x_{s}-x_{t}\right\|_{0}}{|s-t|^{\alpha}}=\sup _{-\tau \leqslant \theta<0} \frac{\| x(s+\theta)-x(t+\theta)}{|s-t|^{\alpha}} \leqslant 2 M
$$

and the closedness of $\mathscr{S}_{\alpha}$ follows.
For $x \in \mathscr{S}_{x}$, we now define the operators $\mathscr{T}$ and $\mathscr{P}$ by

$$
\begin{aligned}
(\mathscr{T} x)(t) & =y(t)+(\mathscr{F} x)(t) \\
& =y(t)+\int_{t_{1}}^{t} T_{A}(t-s)(1-P) f\left(s, x_{s}\right) d s-\int_{t}^{\infty} P f\left(s, x_{s}\right) d s \\
& =y(t)-\int_{t_{1}}^{\infty} P f\left(s, x_{s}\right) d s \quad\left(t_{1}-\tau \leqslant t<t_{1}\right) .
\end{aligned}
$$

Our hypotheses guarantee the existence of the integrals. It follows easily that $\mathscr{T} x$ is continuous for $t \geqslant t_{1}-\tau$ and that for $t \geqslant t_{1}$

$$
\begin{aligned}
\|\mathscr{T} x(t)\| \leqslant & \|y(t)\|+K \int_{t_{1}}^{t}\left(\gamma(s)\left\|x_{s}\right\|_{0}+\|f(s, 0)\|\right) d s \\
& +\int_{t}^{\infty}\left(\gamma(s)\left\|x_{s}\right\|_{0}+\|f(s, 0)\|\right) d s \\
\leqslant & \rho+K \sup _{t \geqslant t_{1}-\tau}\|x(t)\| \int_{t_{1}}^{\infty} \gamma(s) d s+K \int_{t_{1}}^{\infty}\|f(s, 0)\| d s \\
\leqslant & \rho+3 \rho \Theta+\rho<3 \rho
\end{aligned}
$$

the final estimate is easily seen to be valid also for $t_{1} \geqslant t \geqslant t_{1}-\tau$. Thus $|||\mathscr{T} x||| \leqslant 3 \rho$.

We must also show that $\mathscr{T} x$ is locally Hölder continuous with exponent $\alpha$ and coefficient $2 M$. Suppose first that $t+1>s>t \geqslant t_{1}+\tau$; then
$\left\|(\mathscr{T} x)_{s}-(\mathscr{T} x)_{t}\right\|_{0}$
$-\sup _{-\tau \leqslant \theta \leqslant 0}\|\mathscr{T} x(s+\theta)-\mathscr{T} x(t+\theta)\|$
$\leqslant\left\|y_{s}-y_{t}\right\|_{0}+\sup _{-\tau \leqslant \theta \leqslant 0}\left\|\int_{t+\theta}^{s+\theta} P f\left(\sigma, x_{\sigma}\right) d \sigma\right\|$
†. $\sup _{-T \leqslant \theta \leqslant 0}\left\|\int_{t+\theta}^{s+\theta} T_{A}(s+\theta-\sigma)(1-P) f\left(\sigma, x_{\sigma}\right) d \sigma\right\|$
$+\sup _{-\tau \leqslant \theta \leqslant 0}\left\|\int_{t_{1}}^{t+\theta}\left[T_{A}(s+\theta-\sigma)-T_{A}(t+0-\sigma)\right](1-P) f\left(\tau, x_{\sigma}\right) d v\right\|$
$=J_{1}+J_{2}+J_{3}+J_{4}$.
For $J_{1}$ we have, of course, $J_{1} \leqslant M|s-t|^{\alpha}$. For $J_{2}$,

$$
\begin{aligned}
J_{2} & \leqslant|s-t| \sup _{\sigma \geqslant t_{1}}\left\|f\left(\sigma, x_{\sigma}\right)\right\| \\
& \leqslant|s-t|\left[\| \| x\left\|\sup _{\sigma \geqslant t_{1}} \gamma(\sigma)+\sup _{\sigma \geqslant t_{1}}\right\| f(\sigma, 0) \mid\right] \\
& <\frac{1}{3} M|s-t| \leqslant \frac{1}{3} M|s-t|^{\alpha}
\end{aligned}
$$

since $K, \rho, \Psi_{\alpha} \geqslant 1$. For $J_{3}$ we have

$$
\begin{aligned}
J_{3} & \leqslant K \sup _{-\tau \leqslant \theta \leqslant 0} \int_{t+\theta}^{s+\theta}\left(\gamma(\sigma)\left\|x_{\sigma}\right\|_{0}+\|f(\sigma, 0)\|\right) d \sigma \\
& \leqslant|s-t|\left[K\|x \mid\| \sup _{\sigma \geqslant t_{1}} \gamma(\sigma)+K \sup _{\sigma \geqslant t_{1}}\|f(\sigma, 0)\|\right] \\
& \leqslant \frac{1}{3} M|s-t|^{\alpha} .
\end{aligned}
$$

$J_{4}$ can be estimated as follows.

$$
\begin{aligned}
J_{4} \leqslant & \sup _{-\tau \leqslant \theta \leqslant 0}\left\|\int_{t}^{t+\theta-\tau}\left[T_{A}(s+\theta-\sigma)-T_{A}(t+\theta-\sigma)\right](1-P) f\left(\sigma, x_{\sigma}\right) d \sigma\right\| \\
& +\sup _{-\tau \leqslant \theta \leqslant 0}\left\|\int_{t+\theta-\tau}^{t+\theta}\left[T_{A}(s+\theta-\sigma)-T_{A}(t+\theta-\sigma)\right](1-P) f\left(\sigma, x_{\sigma}\right) d \sigma\right\| \\
\equiv & I_{1}+I_{2} .
\end{aligned}
$$

Since $A$ generates an analytic semigroup, we have $\left\|A T_{A}(t)\right\| \leqslant K / t$ and $(d / d t) T_{A}(t) x=A T_{A}(t) x$; it follows that for $s>t>0$

$$
\left\|\left[T_{A}(s)-T_{A}(t)\right] x\right\|=\left\|\int_{t}^{s} A T_{A}(\sigma) x d \sigma\right\| \leqslant \frac{K}{t}|s-t|\|x\|
$$

For $I_{1}$ we thus get the estimate

$$
\begin{aligned}
I_{1} & \leqslant \sup _{-\tau \leqslant \theta \leqslant 0} \int_{t_{1}}^{t+\theta-\tau} \frac{K}{\tau}|s-t|\left\|f\left(\sigma, x_{\sigma}\right)\right\| d \sigma \\
& \leqslant|s-t| \frac{K}{\tau}\left[3 \rho \int_{t_{1}}^{\infty} \gamma(\sigma) d \sigma+\int_{t_{1}}^{\infty}\|f(\sigma, 0)\| d \sigma\right] \leqslant \frac{1}{12} M|s-t|
\end{aligned}
$$

For $I_{2}$ we have

$$
\begin{aligned}
I_{2} \leqslant & \sup _{-\tau \leqslant \theta \leqslant 0} \int_{t+\theta-\tau}^{t+\theta} \int_{t+\theta-\sigma}^{s+\theta-\sigma}\left\|A T_{A}(\mu)\right\| d \mu\left\|f\left(\sigma, x_{\sigma}\right)\right\| d \sigma \\
& \leqslant K \sup _{\sigma \geqslant t_{1}-\tau}\left\{\gamma(\sigma)\left\|x_{\sigma}\right\|_{0}+\|f(\sigma, 0)\|\right\} \sup _{-\tau \leqslant \theta \leqslant 0} \int_{t+\theta-\tau}^{t+\theta} \int_{t+\theta-\sigma}^{s+\theta-\sigma} \frac{1}{\mu} d \mu d \sigma \\
\leqslant & K \sup _{\sigma \geqslant t_{1}-\tau}\{3 \rho \gamma(\sigma)+\|f(\sigma, 0)\|\}\{(s-t+\tau) \ln (s-t+\tau) \\
& -(s-t) \ln (s-t)-\tau \ln \tau\} \\
\leqslant & K \Psi_{\alpha}|s-t|^{\alpha}\left\{3 \rho \sup _{\sigma \geqslant t_{1}-\tau} \gamma(\sigma)+\sup _{\sigma \geqslant t_{1}-\tau}\|f(\sigma, 0)\|\right\} \leqslant(M / 12)|s-t|^{\alpha} .
\end{aligned}
$$

We conclude that, for $t+1>s>t \geqslant t_{1}+\tau$,

$$
\left\|(\mathscr{T} x)_{s}-(\mathscr{T} x)_{t}\right\|_{0} \leqslant 2 M|s-t|^{\alpha}
$$

By similar arguments, we can dispose of the easier cases where $t+1>s>$ $t>t_{1}-\tau$ but where $s>t>t_{1}+\tau$ does not hold, to conclude that $\mathscr{T} x$ satisfies the Hölder condition with coefficient $2 M$ if $x$ does. It follows that $\mathscr{T}$ maps $\mathscr{S}_{a}$ into itself.

Note. We have made no use in the above argument of the assumption that $x$ itself is Hölder-continuous. Thus $\mathscr{T}$ actually maps functions satisfying (i), (ii) into $\mathscr{S}_{\alpha}$.

It is easily seen that $\mathscr{T}$ is contracting on $\mathscr{S}_{\alpha}$. Indeed, let $x, \hat{x} \in \mathscr{S}_{\alpha}$; then for $t \geqslant t_{1}$,
$\|(\mathscr{T} x)(t)-(\mathscr{T} \hat{x})(t)\| \leqslant K \int_{t_{1}}^{t}\left\|f\left(s, x_{s}\right)-f\left(s, \hat{x}_{s}\right)\right\| d s+\int_{t}^{\infty}\left\|f\left(s, x_{s}\right)-f\left(s, \hat{x}_{s}\right)\right\| d s$

$$
\leqslant K \int_{t_{1}}^{\infty} \gamma(s)\left\|x_{s}-\hat{x}_{s}\right\| d s \leqslant \Theta\|x-\hat{x}\| \|
$$

For $t_{1}-\tau \leqslant t \leqslant t_{1}$,

$$
\begin{aligned}
\|(T x)(t)-(T \hat{x})(t)\| & <\int_{t_{1}}^{\infty}\left\|f\left(s, x_{s}\right)-f\left(s, \hat{x}_{s}\right)\right\| d s \\
& \leqslant \int_{t_{1}}^{\infty} \gamma(s)\left\|x_{s}-\hat{x}_{s}\right\|_{0} d s \leqslant\|x-\hat{x}\| \int_{t_{1}}^{\infty} \gamma(s) d s \\
& =(\Theta \mid K)\|x-\hat{x}\| \leqslant \Theta\|x-\hat{x}\|
\end{aligned}
$$

Thus $\|\mid \mathscr{T} x-\mathscr{T} \hat{x}\|\|\leqslant\| x-\hat{x}\| \|$.
Now let $y$ be a bounded solution of (4) defined for $t \geqslant t_{1}$. Then for $t>t_{1}$

$$
y(t)=T_{A}\left(t-t_{1}\right) y\left(t_{1}\right)+\int_{t_{1}}^{t} T_{A}(t-s) b(s) d s
$$

is differentiable and

$$
y^{\prime}(t)-A T_{A}\left(t-t_{1}\right) y\left(t_{1}\right)+b(t)+\int_{t_{1}}^{t} A T_{A}(t-s) b(s) d s
$$

[7]. Let $t \geqslant t_{1}+\tau$ and let the Hölder condition for $b$ have the form $\|b(t)-b(s)\| \leqslant \bar{M}|t-s|_{\nu}$. Then

$$
\begin{aligned}
\left\|y^{\prime}(t)\right\| & \frac{K}{\tau}\left\|y\left(t_{1}\right)\right\|+\|b(t)\|+\int_{t_{1}}^{t} \frac{K}{t-s}\|b(s)-b(t)\| d s \\
& +\| \int_{t_{1}}^{t} A T_{A}(t-s) b(t) d s \\
\leqslant & \frac{K}{\tau}\left\|y\left(t_{1}\right)\right\|+(2+K)\|b(t)\|+M K \int_{t_{1}}^{t}(t-s)^{\nu-1} d s
\end{aligned}
$$

since

$$
-\int_{t_{1}}^{t} A T_{A}(t-s) b(t) d s=T_{A}(0) b(t)-T_{A}\left(t-t_{1}\right) b(t)
$$

Thus $\left\|y^{\prime}(t)\right\|$ is bounded uniformly on compact subsets of $\left[t_{1}+\tau, \infty\right)$. From

$$
\|y(s+\theta)-y(t+\theta)\| \leqslant|s-t| \sup _{t \leqslant \sigma \leqslant s} \| y^{\prime}(\sigma+\theta) \mid
$$

it follows that $y$ is locally Hölder continuous for $t>t_{1}+\tau$ for any exponent $\alpha$, $0<\alpha \leqslant 1$.

Define $x$ as the fixed point of $\mathscr{T}$; then $x \in \mathscr{S}_{\alpha}$. We show now that $x \in \mathscr{D}(A)$ for $t \geqslant t_{1}$. Since $y \in \mathscr{D}(A)$ and the range of $P$ is in the null space of $A$, it is enough to show that

$$
\int_{t_{1}}^{t} T_{A}(t-s)(1-P) f\left(s, x_{s}\right) d s \in \mathscr{L}(A)
$$

and by the lemma it suffices to show that the improper integral

$$
\int_{t_{1}}^{t} A T_{A}(t-s)(1-P) f\left(s, x_{s}\right) d s
$$

converges. Since the only difficulty occurs at $s=t$, it is enough to show that

$$
L(c) \equiv \int_{t-\tau}^{t-\epsilon} A T_{A}(t-s)(1-P) f\left(s, x_{s}\right) d s
$$

converges as $\epsilon \rightarrow 0+$. To that end we write

$$
\begin{aligned}
L(\epsilon)= & \int_{t-\tau}^{t-\epsilon} A T_{A}(t-s)(1-P)\left[f\left(s, x_{s}\right)-f\left(s, x_{t}\right)\right] d s \\
& +\int_{t-\tau}^{t-\epsilon} A T_{A}(t-s)(1-P)\left[f\left(s, x_{t}\right)-f\left(t, x_{t}\right)\right] d s \\
& +\int_{t-\tau}^{t-\epsilon} A T_{A}(t-s)(1-P) f\left(t, x_{t}\right) d s=L_{1}(\epsilon)+L_{2}(\epsilon)+L_{3}(\epsilon)
\end{aligned}
$$

for arbitrary $\epsilon>0$. For $L_{1}$ we have

$$
\left\|L_{1}(\epsilon)\right\| \leqslant K \int_{t-\tau}^{t-\epsilon} \frac{1}{t-s} \gamma(s)\left\|x_{s}-x_{t}\right\|_{0} d s
$$

the right-hand side converges as $\epsilon \rightarrow 0+$ because of the Hölder continuity of $x$. Similarly

$$
\left\|L_{2}(\epsilon)\right\| \leqslant K \int_{t-\tau}^{t-\epsilon} \frac{1}{t-s} \mu(s, 3 \rho)|t-s|^{\beta} d s
$$

which also converges as $\epsilon \rightarrow 0+$. Finally,

$$
\begin{aligned}
L_{3}(\epsilon) & =-\int_{t-\tau}^{t-\epsilon} \frac{d}{d s}\left\{T_{A}(t-s)(1-P) f\left(t, x_{t}\right)\right\} d s \\
& =T_{A}(\tau)(1-P) f\left(t, x_{t}\right)-T_{A}(\epsilon)(1-P) f\left(t, x_{t}\right)
\end{aligned}
$$

which certainly converges as $\epsilon \rightarrow 0$. We have thus shown that $\mathscr{T} x \in \mathscr{D}(A)$ and that

$$
(A \mathscr{T} x)(t)=A y(t)+\int_{t_{1}}^{t} A T_{A}(t-s)(1-P) f\left(s, x_{s}\right) d s
$$

for $t \geqslant t_{1}$.
We show now that $x$ is differentiable and satisfies the differential equation (3) for $t>t_{1}$. It suffices to show that $\mathscr{S} x$ is differentiable for $t>t_{1}$. Consider first

$$
\frac{1}{h}\left\{\int_{t+h}^{\infty} P f\left(s, x_{s}\right) d s-\int_{t}^{\infty} P f\left(s, x_{s}\right) d s\right\}=\frac{1}{h} \int_{t}^{t+h} P f\left(s, x_{s}\right) d s
$$

which converges to $\operatorname{Pf}\left(t, x_{t}\right)$ as $h \rightarrow 0$. Also,

$$
\begin{aligned}
& \frac{1}{h}\left\{\int_{t_{1}}^{t+h} T_{A}(t+h-s)(1-P) f\left(s, x_{s}\right) d s-\int_{t_{1}}^{t} T_{A}(t-s)(1-P) f\left(s, x_{s}\right) d s\right\} \\
& \quad=\frac{1}{h}\left\{\int_{t}^{t+h} T_{A}(t+h-s)(1-P) f\left(s, x_{s}\right) d s\right. \\
& \left.\quad+\int_{t_{1}}^{t}\left[T_{A}(t+h-s)-T_{A}(t-s)\right](1-P) f\left(s, x_{s}\right) d s\right\}
\end{aligned}
$$

For the second of these integrals we have

$$
\begin{aligned}
& \frac{1}{h} \int_{t_{1}}^{t} {\left[T_{A}(t+h-s)-T_{A}(t-s)\right](1-P) f\left(s, x_{s}\right) d s } \\
& \quad= \frac{1}{h}\left[T_{A}(h)-I\right] \int_{t_{1}}^{t} T_{A}(t-s)(1-P) f\left(s, x_{s}\right) d s \\
& \rightarrow A \int_{t_{1}}^{t} T_{A}(t-s)(1-P) f\left(s, x_{s}\right) d s \\
& \quad=\int_{t_{1}}^{t} A T_{A}(t-s)(1-P) f\left(s, x_{s}\right) d s
\end{aligned}
$$

as shown above. We show now that the first integral converges to

$$
(1-P) f\left(t, x_{t}\right)=\frac{1}{h} \int_{t}^{t+h}(1-P) f\left(t, x_{t}\right) d s
$$

To prove this, we show that the difference, which can be written as

$$
\begin{aligned}
\frac{1}{h} \int_{t}^{t+h} & T_{A}(t+h-s)(1-P)\left[f\left(s, x_{s}\right)-f\left(s, x_{t}\right)\right] d s \\
& +\frac{1}{h} \int_{t}^{t+h} T_{A}(t+h-s)(1-P)\left[f\left(s, x_{t}\right)-f\left(t, x_{t}\right)\right] d s \\
& +\frac{1}{h} \int_{t}^{t+h}\left[T_{A}(t+h-s)-I\right](1-P) f\left(t, x_{t}\right) d s \\
= & K_{1}+K_{2}+K_{3}
\end{aligned}
$$

converges to zero as $h \rightarrow 0$. For the norm of $K_{1}$, we have the estimate

$$
\left\|K_{1}\right\| \leqslant \frac{K}{h} \int_{t}^{t+h} \gamma(s)\left\|x_{s}-x_{t}\right\|_{0} d s \leqslant \frac{2 M K}{h} \int_{t}^{t+h} \gamma(s)(s-t)^{\alpha} d s
$$

which tends to zero as $h \rightarrow 0$. Similarly, for $K_{2}$ we have the bound

$$
\left\|K_{2}\right\| \leqslant \frac{K}{h} \int_{t}^{t+h} \mu(t, 3 \rho)|s-t|^{\beta} d s
$$

which again tends to zero with $h$. Finally, with the change of variable $z=t+h-s, K_{3}$ can be written as

$$
\frac{1}{h} \int_{0}^{h}\left[T_{A}(z)-I\right](1-P) f\left(t, x_{t}\right) d z
$$

which is well-known to converge to $\left[T_{A}(0)-I\right](1-P) f\left(t, x_{t}\right)=0$.

Putting the results of these computations together, we have shown that $x=y+\mathscr{S} x$ is differentiable and that

$$
\begin{aligned}
\frac{d x}{d t}(t) & =\frac{d y}{d t}(t)+f\left(t, x_{t}\right)+\int_{t_{1}}^{t} A T_{A}(t-s)(1-P) f\left(s, x_{s}\right) d s \\
& =A x(t)+b(t)+f\left(t, x_{t}\right)
\end{aligned}
$$

for $t>t_{1}$, as required.
To show that the map $y \rightarrow x$ defined above is one-to-one and onto, let $x(t)$ be a bounded solution of (3) and define $y$ by $y=x-\mathscr{S} x$. Using the above analysis it is easy to show that $y$ is a bounded solution of (4).

Suppose now that $T_{A}(t)(1-P) x \rightarrow 0$ as $t \rightarrow \infty$ for any $x \in \mathscr{X}$. We must show that

$$
\int_{t_{1}}^{t} T_{A}(t-s)(1-P) f\left(s, x_{s}\right) d s \rightarrow 0 \quad \text { as } \quad t \rightarrow \infty
$$

For any $T>t_{1}$ we have

$$
\int_{t_{1}}^{T} T_{A}(t-s)(1-P) f\left(s, x_{s}\right) d s=T_{A}(t-T)(1-P) \int_{t_{1}}^{T} T_{A}(T-s) f\left(s, x_{s}\right) d s
$$

which converges to zero as $t \rightarrow \infty$; we have here used the commutativity of $T_{A}$ and $P$. Finally,

$$
\begin{aligned}
\left\|\int_{T}^{t} T_{A}(t-s)(1-P) f\left(s, x_{s}\right) d s\right\| & \leqslant K \int_{T}^{t}\left\|f\left(s, x_{s}\right)\right\| d s \\
& \leqslant K \int_{T}^{\infty}\{\gamma(s)\|x\|+\|f(s, 0)\|\} d s
\end{aligned}
$$

which can be made arbitrarily small by choosing $T$ sufficiently large. This completes the proof of the theorem.

Remarks. The hypotheses of the theorem become simpler if $f(t, \phi)$ can be factored as $g(t) h(\phi)$. Three sorts of factoring are possible: $g$ scalar-valued and $h: \mathscr{C} \rightarrow \mathscr{X} ; g:[0, \infty) \rightarrow \mathscr{X}$ and $h$ scalar-valued; or if $\mathscr{X}$ is a Banach algebra, both $g$ and $h$ taking values in $\mathscr{X}$. In any of these cases the following hypotheses imply (a)-(d) of Theorem 1:
(a) $g, h$, are continuous,
(b) $g(t) \rightarrow 0$ as $t \rightarrow \infty$ and $\int_{0}^{\infty}|g(t)| d t<\infty$,
(c) for any $N>0$ and $\phi_{1}, \phi_{2} \in \mathscr{C}$ satisfying $\left\|\phi_{1}\right\| \leqslant N,\left\|\phi_{2}\right\| \leqslant N$, we have

$$
\left|h\left(\phi_{1}\right)-h\left(\phi_{2}\right)\right| \leqslant \text { const. }\left\|\phi_{1}-\phi_{2}\right\|_{\mathbf{0}}
$$

(d) for $|s-t| \leqslant 1$ we have $|g(s)-g(t)| \leqslant \mu(t)|s-t|^{\beta}$ for $\mu$ defined and continuous on $[0, \infty)$ and $0<\beta \leqslant 1$.
Here | | | denotes either $\|\cdot\|$ or $\mid \cdot$, as appropriate. Only (d) of the theorem perhaps requires demonstration; we have

$$
\begin{aligned}
f(s, \phi)-f(t, \phi) \| & \leqslant|g(s)-g(t)|[|h(\phi)-h(0)|-|h(0)|] \\
& \leqslant \mu(t)\left[\text { const. }\|\phi\|_{0}+|h(0)|\right] \mid s-t^{3} .
\end{aligned}
$$

Also, a sum of terms each a product satisfying (a)-(d) above satisfies the hypotheses of Theorem 1 .

We also observe that the last hypothesis of Theorem 1 is satisfied if $A$ has a bounded inverse. Indeed, in this case we have

$$
\begin{aligned}
T_{A}(t)(1-P) x \| & =\left\|T_{A}(t) x\right\|=\| T_{A}(t) A A^{-1} x \\
& \leqslant\left\|A T_{A}(t)\right\|\left\|A^{-1} x\right\| \leqslant(K / t)\left\|A^{\mathbf{1}}\right\|
\end{aligned}
$$

using the fact that $A$ and $P$ commute with $T_{A}(t)$.

## Applications

Here we shall give some applications of Theorem 1, without striving for maximum generality.

1. Let $\Omega$ be a bounded domain of $\mathbb{R}^{n}$ with smooth boundary, let $\mathscr{X}$ be the Hilbert space $\mathscr{L}^{2}(\Omega)$, and take $P \equiv 0$. Let for $x \in \Omega$ the linear differential operator $B(x, D)$ be defined by

$$
B(x, D) u(x)=\sum_{i, j=1}^{n} \frac{\partial}{\partial x_{j}}\left(a_{i j}(x) \frac{\partial u(x)}{\partial x_{i}}\right)-c(x) u(x)
$$

where $c \geqslant 0$; we suppose that $B$ is formally self-adjoint, uniformly strongly elliptic, and has smooth coefficients. Define the operator $A$ by

$$
A u=B(x, D) u
$$

for $u \in \mathscr{L}(A)=H^{2}(\Omega) \cap H_{0}{ }^{1}(\Omega)$ (standard notation). Then $-A$ is a self-adjoint and nonnegative operator, and so generates an analytic semigroup $T_{A}(t)$ [6]. Moreover, by Theorem 1 of [4, Chap. 6],

$$
T_{A}(t) x \|_{L_{2}(\Omega)} \rightarrow 0
$$

as $t \rightarrow \infty$.
The condition $u \in H_{0}^{1}(\Omega)$ is a generalized form of the boundary condition
$\left.u\right|_{\partial \Omega}=0$; cf. [5]. Since we allow nonhomogeneous equations, there is no loss of generality in assuming homogeneous boundary conditions.

Let $b(t, x)$ be in $\mathscr{L}^{2}(\Omega)$ for each $t \geqslant 0$ and be uniformly Hölder continuous in $t$. Let $f(t, x, \phi) \in \mathscr{L}^{2}(\Omega)$ for each $t \geqslant 0$ and $\phi \in \mathscr{C}$, and let $f$ satisfy hypotheses (a)-(d) of Theorem 1. We conclude the following. For every (generalized) solution of

$$
\begin{aligned}
\partial v_{t}(t, x) & =B(x, D) v(t, x) \mid b(t, x), \\
\left.v\right|_{\partial \Omega} & =0
\end{aligned}
$$

which has bounded $\mathscr{L}^{2}(\Omega)$ norm there exists for all sufficiently large $t$ a (generalized) solution $u(t, x)$ of

$$
\begin{aligned}
\frac{\partial}{\partial t} u_{t}(t, x) & =B(x, D) u(t, x)+b(t, x)+f\left(t, x, u_{t}\right) \\
\left.u\right|_{\partial \Omega} & =0
\end{aligned}
$$

such that $\|u-v\|_{\mathscr{L}_{2}(\Omega)} \rightarrow 0$ as $t \rightarrow \infty$, and vice versa.
2. The projection $P$ plays a nontrivial role when $A$ is an elliptic partial differential operator without constant term and $\mathscr{X}$ contains constant functions; for example, the heat equation on a bounded region $\Omega$ in $\mathbb{R}^{n}$ with boundary conditions $\partial u /\left.\partial \nu\right|_{\partial \Omega}=0$, where $\partial / \partial \nu$ denotes the derivative along the normal to the boundary of $\Omega$. Here we give a simpler example of a nontrivial $P$ : the Cauchy problem for the one-dimensional heat equation.

Let $\mathscr{X}_{1}$ be the set of functions $h$ defined and continuous on $(-\infty, \infty)$ and satisfying $\lim _{|x| \rightarrow \infty} h(x)=0$. Let $C$ denote the constant functions on $(-\infty, \infty)$, and let $\mathscr{X}=\mathscr{X}_{1}+C$ with the sup norm. Then $\mathscr{X}$ is a Banach space. Let $A=\partial^{2} / \partial x^{2}$ on $\mathscr{D}(A)=\left\{h \in \mathscr{X}: h^{\prime \prime} \in \mathscr{X}\right\}$. Let $P$ denote projection onto $C$, the null space of $A$. It is well known that $A$ generates the analytic semigroup $T_{A}$ given by

$$
\left[T_{A}(t) h\right](x)=\frac{1}{2(\pi t)^{1 / 2}} \int_{-\infty}^{\infty} e^{-(x-s)^{2} /(4 \pi t)} h(s) d s
$$

An elementary integration shows that $T_{A}(t) 1 \equiv 1$, hence $h \in C$ implies that $T_{A}(t) h \in C$, i.e., $P$ commutes with $T_{A}$. Let now $h$ be in the range of $I-P$, that is, $h \in \mathscr{X}_{1}$. Let $\epsilon>0$ be given, and choose $M$ so large that $s \geqslant M$ or $s \leqslant-M$ implies $|h(s)|<\epsilon / 4$. Then

$$
\left|\frac{1}{2(\pi t)^{1 / 2}} \int_{M}^{\infty} e^{-(x-s)^{2} /(4 \pi t)} h(s) d s\right|,\left|\frac{1}{2(\pi t)^{1 / 2}} \int_{-\infty}^{-M} e^{-(x-s)^{2} /(4 \pi t)} h(s) d s\right|<\frac{\epsilon}{4} .
$$

It follows that for all $t>0$

$$
\begin{aligned}
\left|\left[T_{A}(t) h\right](x)\right| & <\frac{\epsilon}{2}+\frac{1}{2(\pi t)^{1 / 2}} \int_{-M}^{M} e^{-(x-s)^{2} /(4 \pi t)}|h(s)| d s \\
& \leqslant \frac{\epsilon}{2}+\frac{M}{(\pi t)^{1 / 2}} \sup _{s}|h(s)|
\end{aligned}
$$

which can be made less than $\epsilon$ by choosing $t$ sufficiently large. We have thus shown that $\left\|T_{A}(t)(1-P) g\right\| \rightarrow 0$ as $t \rightarrow \infty$ for any $g \in \mathscr{X}$. Theorem 1 can now be applied for any suitable $f$ and $b$.

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