# Optimal Error Bounds for Quadratic Spline Interpolation\*

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Four types of quadratic spline interpolants are considered for which we obtain error bounds of the form

$$\|(f-s)^{(k)}\|_{\infty} \le C_k h^{3-k} \|f^{(3)}\|_{\infty} \qquad (k=0,1,2).$$

Moreover, the optimality of the constant  $C_0$  is proved. © 1996 Academic Press, Inc.

### 1. INTRODUCTION

In [1] and [4] error bounds were derived for cubic spline interpolation over arbitrary partitions, and in [5] the optimality of these bounds was investigated. In [3] the results were extended to the periodic case. The purpose of this paper is to obtain error bounds for four types of quadratic spline interpolation problems using a technique similar to the technique developed in [1, 4, 5, and 3]. Bounds for periodic cubic and quadratic splines are also presented in [8] for uniform partition.

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Throughout this paper we use the following notation. Let  $N \geq 2$  and

$$\Delta$$
:  $a = x_0 < x_1 < \cdots < x_i < \cdots < x_{N-1} < x_N = b$ 

be any partition of the interval [a, b]. A function s is said to be a spline of degree n over  $\Delta$  if s is a polynomial of degree at most n on each interval  $[x_{i-1}, x_i]$  and  $s \in C^{n-1}([a, b], \mathbb{R})$ . It is said to be periodic if  $s^{(k)}(a) = s^{(k)}(b)$  for  $k = 0, \ldots, n-1$ . Let

$$h = \max\{h_i = x_i - x_{i-1} \mid i = 1, ..., N\}$$

be the mesh size of the partition and

$$\beta = h/\min\{h_i \mid i = 1, \dots, n\}$$

be the mesh ratio of the partition. Finally, let us consider the following function spaces

$$L^{1}([a,b];\mathbb{R}) = \left\{ f: [a,b] \to \mathbb{R} \mid \int_{a}^{b} |f(x)| dx < \infty \right\},\,$$

$$L^{\infty}([a,b];\mathbb{R}) = \{f: [a,b] \to \mathbb{R} \mid ||f||_{\infty} = \operatorname{ess sup}\{|f(x)|: x \in [a,b]\} < \infty\},$$

and

$$AC^{n+1}([a,b];\mathbb{R}) = \left\{ f \in C^{n}([a,b];\mathbb{R}) \middle| \begin{array}{l} (\mathbf{i}) & f^{(n+1)} \in L^{\infty}([a,b];\mathbb{R}) \\ (\mathbf{ii}) & f^{(n)}(x) \middle|_{a}^{b} = \int_{a}^{b} f^{(n+1)}(x) dx \end{array} \right\}.$$

A function  $f \in AC^{n+1}([a, b]; \mathbb{R})$  is said to be periodic if  $f^{(k)}(a) = f^{(k)}(b)$  for k = 0, ..., n.

# 2. QUADRATIC SPLINE INTERPOLANT

Let  $\Delta'$  be the partition of [a, b] such that

$$\Delta'$$
:  $a = z_0 < z_1 < \cdots < z_{i-1} < z_i < z_{i+1} < \cdots < z_N < z_{N+1} = b$ 

where  $z_i = (x_{i-1} + x_i)/2$  (i = 1, ..., N). Given any function  $f \in AC^3([a, b]; \mathbb{R})$ , we consider the following four types of quadratic spline interpolant s of f defined on  $\Delta$ :

Type I (Marsden [7]). f and s are periodic and

$$s(z_i) = f(z_i)$$
  $(i = 1,...,N),$  (2.1a)

$$s^{(k)}(a) = s^{(k)}(b)$$
  $(k = 0, 1).$  (2.1b)

Type II (Demko [2], Kammerer et al. [6], and Xie [10]).

$$s(z_i) = f(z_i)$$
  $(i = 0, ..., N + 1).$  (2.2)

Type III (Xie [10]).

$$s(z_i) = f(z_i)$$
 (i = 1,..., N), (2.3a)

$$s^{(1)}(z_i) = f^{(1)}(z_i)$$
  $(i = 0, N + 1).$  (2.3b)

Type IV (Xie [10]).

$$s(z_i) = f(z_i)$$
  $(i = 2, ..., N-1),$  (2.4a)

$$s^{(k)}(z_i) = f^{(k)}(z_i)$$
  $(i = 0, N + 1; k = 0, 1).$  (2.4b)

The existence and uniqueness results are presented in the references given here. Our goal is to obtain, for each type of interpolant, error bounds of the form

$$||f^{(k)} - s^{(k)}||_{\infty} \le C_k h^{3-k} M$$

for k = 0, 1, 2, where  $M = ||f^{(3)}||_{\infty}$ .

## 3. FUNDAMENTAL SPLINES

Let v and w be two quadratic splines defined on  $\Delta'$  and such that

$$v(x_i) = 0 = w(x_i)$$
  $(i = 0, ..., N)$  (3.1)

and for

Types I and II 
$$\begin{cases} v^{(1)}(a) = 0 = w^{(1)}(b); \\ v^{(2)}(a) = 1 = (-1)^N w^{(2)}(b). \end{cases}$$
(3.2)

Type III 
$$\begin{cases} v^{(1)}(a) = 1 = (-1)^N w^{(1)}(b); \\ v^{(2)}(a) = 0 = w^{(2)}(b). \end{cases}$$
(3.3)

Type IV 
$$\begin{cases} v(z_1) = 1 = (-1)^N w(z_N); \\ v^{(2)} \text{ is continuous at } z_1; \\ w^{(2)} \text{ is continuous at } z_N. \end{cases}$$
 (3.4)

There is no difficulty to show that v and w are well defined by the given conditions. Some of the properties of v and w are stated in the next lemmas.

LEMMA 1. The splines v and w have the following sign properties:

$$v^{(1)}(x_i) = (-1)^i |v^{(1)}(x_i)| \qquad (i = 0, ..., N), \tag{3.5a}$$

$$v^{(2)}(x_i) = (-1)^i |v^{(2)}(x_i)| \qquad (i = 1, ..., N);$$
 (3.5b)

$$w^{(1)}(x_i) = (-1)^{i+1} |w^{(1)}(x_i)| \qquad (i = 0, ..., N),$$
 (3.6a)

$$w^{(2)}(x_i) = (-1)^i |w^{(2)}(x_i)|$$
  $(i = 0..., N-1).$  (3.6b)

The splines v and w satisfy the following identities:

$$\left| v^{(1)}(x_i) \right| = 3 \left| v^{(1)}(x_{i-1}) \right| + \left| v^{(2)}(x_{i-1}) \right| h_i, \tag{3.7a}$$

$$\left| v^{(2)}(x_i) \right| h_i = 8 \left| v^{(1)}(x_{i-1}) \right| + 3 \left| v^{(2)}(x_{i-1}) \right| h_i; \tag{3.7b}$$

$$|w^{(1)}(x_{i-1})| = 3|w^{(1)}(x_i)| + |w^{(2)}(x_i)|h_i,$$
 (3.8a)

$$\left| w^{(2)}(x_{i-1}) \right| h_i = 8 \left| w^{(1)}(x_i) \right| + 3 \left| w^{(2)}(x_i) \right| h_i; \tag{3.8b}$$

for i = 1, ..., N for types I, II, and III, and for type IV (3.7) holds for i = 2, ..., N and (3.8) holds for i = 1, ..., N - 1.

Furthermore, v and w have no zeros in each interval  $(x_{i-1}, x_i)$ , and

$$v(x) = (-1)^{i-1} |v(x)|$$
 and  $w(x) = (-1)^{i} |w(x)|$  (3.9)

for i = 1, ..., N.

*Proof.* We prove only these results for v since the proofs for w are similar. We use the following representation of v on  $[x_{i-1}, x_i]$ 

$$v(x) = \sum_{j=1}^{2} v^{(j)}(x_{i-1}) \frac{(x - x_{i-1})^{j}}{j!} + J \frac{(x - z_{i})_{+}^{2}}{2!}$$

where  $J = v^{(2)}(z_i^+) - v^{(2)}(z_i^-)$ . If we evaluate  $v^{(1)}(x_i)$  and  $v^{(2)}(x_i)$ , we obtain

$$-v^{(1)}(x_i) = 3v^{(1)}(x_{i-1}) + v^{(2)}(x_{i-1})h_i$$
 (3.10a)

$$-v^{(2)}(x_i)h_i = 8v^{(1)}(x_{i-1}) + 3v^{(2)}(x_{i-1})h_i.$$
 (3.10b)

For v of type I, II, or III, we have from the definition that  $v^{(1)}(a)$  and  $v^{(2)}(a)$  are nonnegative. Therefore we obtain (3.5) form (3.10) in these cases. If v is of type IV then v is a polynomial on  $[a, x_1]$  such that  $v^{(1)}(a) = 4/h_1$  and  $v^{(2)}(a) = -4/h_1^2$ . It follows from (3.10) that  $-v^{(1)}(x_1)$  and  $-v^{(2)}(x_1)$  are nonnegative and (3.5) follows. As a direct consequence of (3.5) and (3.10) we obtain (3.7). Since v is a spline with a single knot at

 $z_i$  on  $(x_{i-1}, x_i)$ , it follows from the Budan-Fourier Theorem for polynomial splines [9, Theorem 4.58] that v has no zeros in  $(x_{i-1}, x_i)$ . Therefore (3.9) is a consequence of (3.5).

LEMMA 2. The quadratic spline v has the properties

$$\int_{x_{i-1}}^{x_i} |v(x)| dx = (-1)^i \left(v^{(1)}(x_i) - v^{(1)}(x_{i-1})\right) \frac{h_i^2}{12}, \quad (3.11a)$$

$$\int_{a}^{x_{i}} |v(x)| dx \le \frac{h^{2}}{6} |v^{(1)}(x_{i})|, \tag{3.11b}$$

$$\int_{x_{i-1}}^{x_i} |v(x)| dx = (-1)^i \left(v^{(2)}(x_i) + v^{(2)}(x_{i-1})\right) \frac{h_i^3}{24}, \quad (3.11c)$$

$$\int_{a}^{x_{i}} |v(x)| dx \le \frac{h^{3}}{24} \left( (-1)^{i} v^{(2)}(x_{i}) - v^{(2)}(a) \right), \tag{3.11d}$$

for i = 1, ..., N. Moreover, if the partition is uniform then (d) is an equality.

*Proof.* Let  $\omega(u) = u(u - \frac{1}{2})(u - 1)/6$  and define  $\Omega(x) = h_i^3 \omega((x - x_{i-1})/h_i)$  for  $x \in [x_{i-1}, x_i]$ . Then  $\Omega^{(3)}(x) = 1$  and, from (3.9), we have

$$(-1)^{i-1} \int_{x_{i-1}}^{x_i} |v(x)| dx = \int_{x_{i-1}}^{x_i} v(x) \Omega^{(3)}(x) dx.$$

Integrating by parts, using (3.1) and the continuity of  $v^{(2)}(x)\Omega(x)$ , we obtain

$$\int_{x_{i-1}}^{x_i} v(x) \Omega^{(3)}(x) dx = -\left(v^{(1)}(x_i) - v^{(1)}(x_{i-1})\right) \frac{h_i^2}{12}$$

and (3.11a) follows. To obtain (3.11b) we have from (3.11a)

$$\int_{a}^{x_{i}} |v(x)| dx = \sum_{j=1}^{i} (-1)^{j} (v^{(1)}(x_{j}) - v^{(1)}(x_{j-1})) \frac{h_{j}^{2}}{12}$$

and, using (3.5a), we obtain

$$\int_{a}^{x_{i}} |v(x)| dx \leq \frac{h^{2}}{12} \left\{ \left| v^{(1)}(x_{i}) \right| + 2 \sum_{j=1}^{i-1} \left| v^{(1)}(x_{j}) \right| + \left| v^{(1)}(a) \right| \right\}.$$

But from (3.7a) we have  $|v^{(1)}(x_i)| \ge 3|v^{(1)}(x_{i-1})|$  (for type IV we have  $v^{(1)}(x_1) = -v^{(1)}(x_0)$ ). It follows that

$$\int_{a}^{x_{i}} |v(x)| dx \leq \frac{h^{2}}{12} |v^{(1)}(x_{i})| \left\{ 1 + 2 \sum_{j=1}^{i-1} \frac{1}{3^{j}} + \frac{1}{3^{i-1}} \right\}$$

$$\leq \frac{h^{2}}{6} |v^{(1)}(x_{i})|.$$

If we observe that

$$v^{(1)}(x_i) - v^{(1)}(x_{i-1}) = v^{(1)}(x_i) - v^{(1)}(z_i) + v^{(1)}(z_i) - v^{(1)}(x_{i-1})$$
$$= \left(v^{(2)}(x_i) + v^{(2)}(x_{i-1})\right) \frac{h_i}{2}$$

then (3.11a) becomes (3.11c). Also,

$$\int_{a}^{x_{i}} |v(x)| dx = \sum_{j=1}^{i} \int_{x_{j-1}}^{x_{j}} |v(x)| dx$$

$$\leq \frac{h^{3}}{24} \sum_{j=1}^{i} (-1)^{j} (v^{(2)}(x_{j}) + v^{(2)}(x_{j-1}))$$

$$\leq \frac{h^{3}}{24} \{ (-1)^{i} v^{(2)}(x_{i}) - v^{(2)}(a) \}$$

and we get (3.11d).

From (3.11d) and (3.5b) we obtain

$$\int_{a}^{x_{i}} |v(x)| dx \le \frac{h^{3}}{24} \begin{cases} \left|v^{(2)}(x_{i})\right| - \left|v^{(2)}(a)\right| & \text{for types I and II,} \\ \left|v^{(2)}(x_{i})\right| & \text{for type III,} \\ \left|v^{(2)}(x_{i})\right| + \left|v^{(2)}(a)\right| & \text{for type IV.} \end{cases}$$

Using the same method we obtain the following result for w.

LEMMA 3. The quadratic spline w has the properties

$$\int_{x_{i}}^{x_{i+1}} |w(x)| dx = (-1)^{i+1} \left( w^{(1)}(x_{i}) - w^{(1)}(x_{i+1}) \right) \frac{h_{i+1}^{2}}{12}, \quad (3.12a)$$

$$\int_{x}^{b} |w(x)| dx \le \frac{h^{2}}{6} |w^{(1)}(x_{i})|, \quad (3.12b)$$

$$\int_{x_{i}}^{x_{i+1}} |w(x)| dx = (-1)^{i} \left( w^{(2)}(x_{i}) + w^{(2)}(x_{i+1}) \right) \frac{h_{i+1}^{3}}{24}, \quad (3.12c)$$

$$\int_{x_{i}}^{b} |w(x)| dx \le \frac{h^{3}}{24} \left( (-1)^{i} w^{(2)}(x_{i}) - (-1)^{N} w^{(2)}(b) \right), \quad (3.12d)$$

for i = 0, ..., N - 1. Moreover, if the partition is uniform then (3.12d) is an equality.

From (3.12d) and (3.6b) we get

$$\int_{x_{i}}^{b} |w(x)| dx \le \frac{h^{3}}{24} \begin{cases} \left| w^{(2)}(x_{i}) \right| - \left| w^{(2)}(b) \right| & \text{for types I and II,} \\ \left| w^{(2)}(x_{i}) \right| & \text{for type III,} \\ \left| w^{(2)}(x_{i}) \right| + \left| w^{(2)}(b) \right| & \text{for type IV.} \end{cases}$$

## 4. KERNELS

For the quadratic spline interpolant s of  $f \in AC^3([a,b];\mathbb{R})$  we define the error e(x) = f(x) - s(x). Let us observe that for the four types of interpolant considered here we have

$$e(z_i)=0 \qquad (i=2,\ldots,N-1),$$
 
$$e^{(1)} \text{ and } e^{(2)} \text{ are continuous at } z_i \qquad (i=1,\ldots,N).$$

Moreover v,  $v^{(1)}$ , w, and  $w^{(1)}$  are continuous at  $z_i$  (i = 0, ..., N + 1), and  $v(x_i) = 0 = w(x_i)$  (i = 0, ..., N). Using these properties we obtain

$$\int_{a}^{x_{i}} v(x)e^{(3)}(x) dx = v^{(1)}(a)e^{(1)}(a) - v^{(1)}(x_{i})e^{(1)}(x_{i})$$

$$+ v^{(2)}(x_{i})e(x_{i}) - v^{(2)}(a)e(a)$$

$$+ \left[v^{(2)}(z_{1}^{-}) - v^{(2)}(z_{1}^{+})\right]e(z_{1})$$

$$+ \delta_{iN}\left[v^{(2)}(z_{N}^{-}) - v^{(2)}(z_{N}^{+})\right]e(z_{N}). \tag{4.1}$$

Similarly, for w we have

$$\int_{x_{i}}^{b} w(x)e^{(3)}(x) dx = w^{(1)}(x_{i})e^{(1)}(x_{i}) - w^{(1)}(b)e^{(1)}(b)$$

$$+ w^{(2)}(b)e(b) - w^{(2)}(x_{i})e(x_{i})$$

$$+ \left[w^{(2)}(z_{N}^{-}) - w^{(2)}(z_{N}^{+})\right]e(z_{N})$$

$$+ \delta_{i0}\left[w^{(2)}(z_{1}^{-}) - w^{(2)}(z_{1}^{+})\right]e(z_{1}). \quad (4.2)$$

Using the supplementary conditions for each type of interpolant we obtain the following results.

Type I. From (2.1) and (3.2) we have

$$\int_{a}^{b} v(x)e^{(3)}(x) dx = \left(v^{(2)}(b) - v^{(2)}(a)\right)e(a) - v^{(1)}(b)e^{(1)}(a),$$

$$\int_{a}^{b} w(x)e^{(3)}(x) dx = \left(w^{(2)}(b) - w^{(2)}(a)\right)e(a) + w^{(1)}(a)e^{(1)}(a).$$

It is a linear system for e(a) and  $e^{(1)}(a)$  for which the determinant of the coefficient matrix is

$$D(a,b) = w^{(1)}(a)(v^{(2)}(b) - v^{(2)}(a)) + v^{(1)}(b)(w^{(2)}(b) - w^{(2)}(a)).$$

But from (3.11d), (3.12d), (3.5), and (3.6), we have

$$\operatorname{sgn}(v^{(2)}(b) - v^{(2)}(a)) = \operatorname{sgn}(v^{(2)}(b)) = (-1)^{N},$$
  
$$\operatorname{sgn}(w^{(2)}(b) - w^{(2)}(a)) = -\operatorname{sgn}(w^{(2)}(a)) = -1.$$

Hence.

$$D(a,b) = [|w^{(1)}(a)||v^{(2)}(b) - v^{(2)}(a)| + |v^{(1)}(b)||w^{(2)}(b) - w^{(2)}(a)|](-1)^{N+1}.$$

It follows that

$$e^{(k)}(a) = \int_a^b K_k(x)e^{(3)}(x) dx$$

where  $e^{(3)}(x) = f^{(3)}(x)$ , and

$$K_0(x) = \left[ w^{(1)}(a)v(x) + v^{(1)}(b)w(x) \right] / D(a,b),$$

$$K_1(x) = \left[ \left( v^{(2)}(b) - v^{(2)}(a) \right) w(x) - \left( w^{(2)}(b) - w^{(2)}(a) \right) v(x) \right] / D(a,b).$$

Therefore, using Lemmas 2 and 3 we have

$$||K_0||_1 \le \frac{h^3}{24}$$
 and  $||K_1||_1 \le \frac{h^2}{6}$ .

Finally, using the periodicity, and considering any interval of the form  $[x_i, x_i + b - a]$ , we obtain

$$\max\{|e^{(k)}(x_i)|: i = 0, ..., N\} \le ||K_k||_1 M$$

for k = 0, 1.

Type II. From (2.2) and (3.2) we have

$$\int_{a}^{x_{i}} v(x)e^{(3)}(x) dx = v^{(2)}(x_{i})e(x_{i}) - v^{(1)}(x_{i})e^{(1)}(x_{i}),$$

$$\int_{x_{i}}^{b} w(x)e^{(3)}(x) dx = -w^{(2)}(x_{i})e(x_{i}) + w^{(1)}(x_{i})e^{(1)}(x_{i}),$$

for  $i = 0, \ldots, N$ .

Type III. From (2.3) and (3.3) we have

$$\int_{a}^{x_{i}} v(x)e^{(3)}(x) dx = v^{(2)}(x_{i})e(x_{i}) - v^{(1)}(x_{i})e^{(1)}(x_{i}),$$

$$\int_{x_{i}}^{b} w(x)e^{(3)}(x) dx = -w^{(2)}(x_{i})e(x_{i}) + w^{(1)}(x_{i})e^{(1)}(x_{i}),$$

for i = 0, ..., N.

Type IV. From (2.4) and (3.4) we have

$$\int_{a}^{x_{i}} v(x)e^{(3)}(x) dx = v^{(2)}(x_{i})e(x_{i}) - v^{(1)}(x_{i})e^{(1)}(x_{i}),$$

$$\int_{x_{i}}^{b} w(x)e^{(3)}(x) dx = -w^{(2)}(x_{i})e(x_{i}) + w^{(1)}(x_{i})e^{(1)}(x_{i}),$$

for i = 1, ..., N - 1.

For these three cases we have to solve a linear system for  $e(x_i)$  and  $e^{(1)}(x_i)$  for which the determinant of the coefficient matrix is

$$D(x_i) = v^{(2)}(x_i)w^{(1)}(x_i) - v^{(1)}(x_i)w^{(2)}(x_i).$$

Using (3.5) and (3.6) we have

$$D(x_i) = -\{ |v^{(2)}(x_i)| |w^{(1)}(x_i)| + |v^{(1)}(x_i)| |w^{(2)}(x_i)| \} \neq \mathbf{0}$$

for all i (depending on the type of the interpolant).

Solving for  $e(x_i)$  and  $e^{(1)}(x_i)$ , we have

$$e^{(k)}(x_i) = \int_a^b K_k(x_i; x) e^{(3)}(x) dx$$

where

$$K_{k}(x_{i};x) = \begin{cases} \frac{w^{(k+1)}(x_{i})v(x)}{D(x_{i})} & a \leq x \leq x_{i}; \\ \frac{v^{(k+1)}(x_{i})w(x)}{D(x_{i})} & x_{i} < x \leq b, \end{cases}$$

for k = 0, 1. It follows from Lemmas 2 and 3 that

$$\|K_0\|_1 \le \begin{cases} h^3/24 & \text{for types II and III,} \\ h^3/12 & \text{for type IV,} \end{cases}$$

and  $||K_1||_1 \le h^2/6$ . Finally,

$$\max\{|e^{(k)}(x_i)|: i = 0, ..., N\} \le ||K_k||_1 M$$

for k = 0, 1. In summary we have the following result.

PROPOSITION 4. Let  $f \in AC^3([a, b]; \mathbb{R})$  and s be the quadratic spline interpolant of type I, II, III, or IV. Then for e(x) = f(x) - s(x) we have

$$\max\{|e^{(k)}(x_i)|: i = 0, ..., N\} \le ||K_k||_1 M$$

for k = 0, 1, where

$$||K_0||_1 \le \begin{cases} h^3/24 & \text{for types I, II, and III,} \\ h^3/12 & \text{for type IV,} \end{cases}$$
$$||K_1||_1 \le h^2/6,$$

and  $M = ||f^{(3)}||_{\infty}$ .

# 5. DERIVATION OF ERROR BOUNDS

For any interval  $[x_{i-1}, x_i]$  on which we have the condition  $f(z_i) = s(z_i)$  we consider the Lagrange interpolating polynomial p(x) of degree 2 such that

$$p(x_{i-1}) = f(x_{i-1}), p(z_i) = f(z_i), p(x_i) = f(x_i).$$

Then

$$|f(x) - p(x)| \le |(1+t)t(1-t)| \frac{h_i^3}{48}M$$
 (5.1)

for  $x = z_i + (h_i/2)t$  and  $-1 \le t \le 1$ . The difference p - s is then the Lagrange interpolant of e = f - s on  $[x_{i-1}, x_i]$ , and

$$|p(x) - s(x)| \le |t| \max\{|e(x_{i-1})|, |e(x_i)|\}.$$
 (5.2)

Hence, from (5.1), (5.2), and Proposition 4, it follows that

$$\max_{x \in [x_{i-1}, x_i]} |f(x) - s(x)| \le \frac{h^3}{24} M$$

for types I, II, and III, and

$$\max_{x \in [x_{i-1}, x_i]} |f(x) - s(x)| \le \frac{h^3}{12} M$$

for type IV.

For type IV it remains to consider the interval  $[x_0, x_1]$  where  $f^{(1)}(z_0) = s^{(1)}(z_0)$  (and similarly the interval  $[x_{N-1}, x_N]$  where  $f^{(1)}(z_{N+1}) = s^{(1)}(z_{N+1})$ ). In this case we consider the Hermite interpolating polynomial p(x) of degree 2 such that

$$p(x_0) = f(x_0), p^{(1)}(x_0) = f^{(1)}(x_0), p(x_1) = f(x_1).$$

Then

$$|f(x) - p(x)| \le |(1+t)^2 (1-t)| \frac{h_1^3}{48} M.$$
 (5.3)

Also, p - s is the Hermite interpolant of e = f - s on  $[x_0, x_1]$ , and

$$|p(x) - s(x)| \le \frac{(1+t)^2}{4} |e(x_1)|.$$
 (5.4)

Hence, from (5.3), (5.4), and Proposition 4, we have

$$\max_{x \in [x_0, x_1]} |f(x) - s(x)| \le \frac{h^3}{12} M.$$

To obtain the error bounds for  $e^{(1)}(x)$  and  $e^{(2)}(x)$  we use the following lemma about linear interpolation.

LEMMA 5. Let  $\phi \in AC^2([a, b]; \mathbb{R})$ , then

$$\|\phi\|_{\infty} \leq \max\{|\phi(a)|, |\phi(b)|\} + \frac{(b-a)^2}{8} \|\phi^{(2)}\|_{\infty}$$

and

$$\|\phi^{(1)}\|_{\infty} \leq \frac{2}{b-a} \max\{|\phi(a)|, |\phi(b)|\} + \frac{b-a}{2} \|\phi^{(2)}\|_{\infty}.$$

Using this lemma, if  $\phi(x) = e^{(1)}(x)$  then

$$\|e^{(1)}\|_{\infty} \leq \max\{|e^{(1)}(x_i)|: i = 0, ..., N\} + \frac{h^2}{8}M$$

and

$$\|e^{(2)}\|_{\infty} \leq \max \left\{ \frac{h}{3h_i} + \frac{h_i}{2h} : i = 1, ..., N \right\} hM.$$

Finally we have the following result.

Theorem 6. Let s be a type I, II, III, or IV interpolant of  $f \in AC^3([a,b];\mathbb{R})$ . Then

$$||(f-s)^{(k)}||_{\infty} \le C_k h^{3-k} ||f^{(3)}||_{\infty} \qquad (k=0,1,2)$$

where

$$C_0 = \begin{cases} \frac{1}{24} & \textit{for types I, II, and III,} \\ \frac{1}{12} & \textit{for type IV,} \end{cases}$$

$$C_1=\frac{7}{24},$$

$$C_2 = egin{cases} rac{5}{6} & ext{if } 1 \leq eta \leq 3/2, \\ rac{eta}{2} + rac{1}{2\,eta} & eta \geq 3/2. \end{cases}$$

Moreover,  $C_0$  is optimal in the sense that

$$C_0 = \sup_{f, \Delta} \frac{\|f - s\|_{\infty}}{h^3 \|f^{(3)}\|_{\infty}}$$

where the supremum is taken over all partitions  $\Delta$  of [a,b] and all  $f \in AC^3([a,b];\mathbb{R})$  such that  $||f^{(3)}||_{\infty} \neq 0$  (for type I, f is assumed to be periodic).

*Proof.* It remains to prove the optimality of  $C_0$ . We only have to show that for any  $\varepsilon > 0$  there exists an index i and a function  $f \in AC^3([a, b]; \mathbb{R})$  for which

$$|e(x_i)| > (1 - \epsilon) ||f^{(3)}||_{\infty} \begin{cases} \frac{1}{24} & \text{for types I, II, and III,} \\ \frac{1}{12} & \text{for type IV.} \end{cases}$$

We consider the following three situations.

Type I. From (3.5a), (3.5b), (3.8a), and (3.8b) we have

$$K_0(x) = \frac{(-1)^i}{D(a,b)} \Big[ |w^{(1)}(a)| |v(x)| + (-1)^N |v^{(1)}(b)| |w(x)| \Big]$$

for any  $x \in (x_{i-1}, x_i)$  and i = 1, ..., N. Hence for N even

$$\int_{a}^{b} |K_{0}(x)| dx = \frac{1}{|D(a,b)|} \left[ |w^{(1)}(a)| \int_{a}^{b} |v(x)| dx + |v^{(1)}(b)| \int_{a}^{b} |w(x)| dx \right].$$

But from (3.11d) and (3.12d) for a uniform partition, we obtain

$$\int_{a}^{b} |K_{0}(x)| dx = \frac{h^{3}}{24}.$$

Finally, let  $f \in AC^3([a, b]; \mathbb{R})$  be a periodic function such that  $f^{(3)}(x) = \operatorname{sgn}(K_0(x)) = (-1)^{i-1}$  for  $x \in (x_{i-1}, x_i)$ , then

$$e(a) = \int_{a}^{b} K_{0}(x)e^{(3)}(x) dx = \int_{a}^{b} K_{0}(x)f^{(3)}(x) dx$$
$$= \int_{a}^{b} |K_{0}(x)| ||f^{(3)}||_{\infty} dx = \frac{h^{3}}{24} ||f^{(3)}||_{\infty}.$$

Types II and III. From (3.7b) and (3.8b) we have

$$|v^{(2)}(x_i)| \ge 3^i |v^{(2)}(a)|$$
 and  $|w^{(2)}(x_i)| \ge 3^{N-i} |w^{(2)}(b)|$ .

Hence, for a uniform partition, we obtain from (3.11d) and (3.12d)

$$\int_{a}^{x_{i}} |v(x)| dx \ge \left(1 - \frac{1}{3^{i}}\right) \frac{h^{3}}{24} |v^{(2)}(x_{i})|$$
$$\int_{x}^{b} |w(x)| dx \ge \left(1 - \frac{1}{3^{N-i}}\right) \frac{h^{3}}{24} |w^{(2)}(x_{i})|$$

then

$$\int_{a}^{b} |K(x_{i}; x)| dx \ge \left(1 - \frac{1}{3^{\alpha N}}\right) \frac{h^{3}}{24}$$

for all  $\alpha N < i < (1 - \alpha)N$  where  $\alpha \in (0, \frac{1}{2})$ . It follows that

$$\lim_{N\to\infty}\int_a^b \left|K(x_i;x)\right| dx = \frac{h^3}{24}.$$

Finally, let  $f \in AC^3([a, b]; \mathbb{R})$  be such that

$$f^{(3)}(x) = \text{sgn}(K_0(x_i; x)).$$

Then

$$e(x_i) = \int_a^b K_0(x_i; x) e^{(3)}(x) dx$$

$$= \int_a^b |K_0(x_i; x)| dx ||f^{(3)}||_{\infty}$$

$$> (1 - \epsilon) \frac{h^3}{24} ||f^{(3)}||_{\infty}$$

for  $\alpha N < i < (1 - \alpha)N$  and N such that  $1/3^{\alpha N} < \epsilon$ .

*Type* IV. Let N=2 and  $\Delta$  be the uniform partition of [a,b]. In this case  $v^{(2)}(a)=-|v^{(2)}(x_1)|$  and  $w^{(2)}(b)=-|w^{(2)}(x_1)|$ . We obtain from (3.11d) and (3.12d)

$$\int_{a}^{x_{1}} |v(x)| dx = \frac{h^{3}}{12} |v^{(2)}(x_{1})| \quad \text{and} \quad \int_{x_{1}}^{b} |w(x)| dx = \frac{h^{3}}{12} |w^{(2)}(x_{1})|.$$

Then

$$\int_{a}^{b} |K_{0}(x_{1};x)| dx = \frac{h^{3}}{12}.$$

Finally, let  $f \in AC^3([a, b]; \mathbb{R})$  be such that  $f^{(3)}(x) = \operatorname{sgn}(K_0(x_1; x))$  for all  $x \in [a, b]$ . Then

$$e(x_1) = \int_a^b K_0(x_1; x) f^{(3)}(x) dx$$

$$= \int_a^b |K_0(x_1; x)| dx ||f^{(3)}||_{\infty}$$

$$= \frac{h^3}{12} ||f^{(3)}||_{\infty}. \quad \blacksquare$$

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