



# $q$ -integral representation of the Al-Salam–Carlitz polynomials

Mingjin Wang

Department of Applied Mathematics, Jiangsu Polytechnic University, Changzhou city 213164, Jiangsu province, PR China

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## ABSTRACT

We use the Andrews–Askey integral and the Leibniz rule for the  $q$ -difference operator to give the  $q$ -integral representation of the Al-Salam–Carlitz polynomials, which includes the  $q$ -integral representation of the Rogers–Szegő polynomials and the  $q$ -integral representation of the  $q$ -Hermite polynomials as special cases.

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## 1. Introduction and statement of result

The following are the well-known Rogers–Szegő polynomials:

$$h_n(x|q) = \sum_{k=0}^n \begin{bmatrix} n \\ k \end{bmatrix} x^k. \quad (1.1)$$

Other hypergeometric polynomials related to the Rogers–Szegő polynomials are the  $q$ -Hermite polynomials  $H_n(x|q)$ , which are often defined via the generating function [1]

$$\sum_{n=0}^{\infty} H_n(x|q) \frac{t^n}{(q; q)_n} = \prod_{n=0}^{\infty} \frac{1}{(1 - 2xtq^n + t^2q^{2n})}.$$

The Rogers–Szegő polynomials and the  $q$ -Hermite polynomials have the following relationship:

$$H_n(\cos \theta|q) = e^{in\theta} h_n(e^{2i\theta}|q). \quad (1.2)$$

The Rogers–Szegő polynomials play an important role in the theory of orthogonal polynomials, particularly in the study of the Askey–Wilson integral [2–4]. The Rogers–Szegő polynomials are the  $a = 0$  case of the Al-Salam–Carlitz polynomials  $\varphi_n^{(a)}(x|q)$ , which are defined as [5]

$$\varphi_n^{(a)}(x|q) = \sum_{k=0}^n \begin{bmatrix} n \\ k \end{bmatrix} x^k (a; q)_k. \quad (1.3)$$

E-mail addresses: [wang197913@126.com](mailto:wang197913@126.com), [wmj@jpu.edu.cn](mailto:wmj@jpu.edu.cn).

In [6], some integral representations of hypergeometric polynomials are given. In this work, we give the  $q$ -integral representation of the Al-Salam–Carlitz polynomials, which includes the  $q$ -integral representation of the Rogers–Szegő polynomials and the  $q$ -integral representation of the  $q$ -Hermite polynomials. The main result of the work is the following  $q$ -integral representation of the Al-Salam–Carlitz polynomials:

**Theorem 1.1.** *We have*

$$\varphi_n^{(a)}(x|q) = \frac{(ax, a; q)_\infty}{(1-q)(q, q/x, x; q)_\infty} \int_x^1 \frac{(qt/x, qt; q)_\infty t^n}{(at; q)_\infty} d_q t. \tag{1.4}$$

provided that no zero factors occur in the denominator.

**2. Notation and known results**

Before the proof of the theorem, we recall some definitions, notation and known results in [11,12] which will be used in the proof. Throughout this work, it is supposed that  $0 < |q| < 1$ . The  $q$ -shifted factorials are defined as

$$(a; q)_0 = 1, \quad (a; q)_n = \prod_{k=0}^{n-1} (1 - aq^k), \quad (a; q)_\infty = \prod_{k=0}^{\infty} (1 - aq^k). \tag{2.1}$$

We also adopt the following compact notation for multiple  $q$ -shifted factorials:

$$(a_1, a_2, \dots, a_m; q)_n = (a_1; q)_n (a_2; q)_n \cdots (a_m; q)_n, \tag{2.2}$$

where  $n$  is an integer or  $\infty$ . The  $q$ -binomial coefficient is defined by

$$\begin{bmatrix} n \\ k \end{bmatrix} = \frac{(q; q)_n}{(q; q)_k (q; q)_{n-k}}. \tag{2.3}$$

The  $q$ -difference operator  $D_q$  is defined by [7]

$$D_q\{f(a)\} = \frac{1}{a} [f(a) - f(aq)]. \tag{2.4}$$

The following property of  $D_q$  is straightforward:

$$D_q^n \left\{ \frac{(at; q)_\infty}{(as; q)_\infty} \right\} = s^n (t/s; q)_n \frac{(atq^n; q)_\infty}{(as; q)_\infty}. \tag{2.5}$$

We also have the following Leibniz rule for  $D_q$  [8]:

$$D_q^n \{f(a)g(a)\} = \sum_{k=0}^n q^{k(k-n)} \begin{bmatrix} n \\ k \end{bmatrix} D_q^k \{f(a)\} D_q^{n-k} \{g(q^k a)\}. \tag{2.6}$$

F.H. Jackson defined the  $q$ -integral via [9]

$$\int_0^d f(t) d_q t = d(1-q) \sum_{n=0}^{\infty} f(dq^n) q^n, \tag{2.7}$$

and

$$\int_c^d f(t) d_q t = \int_0^d f(t) d_q t - \int_0^c f(t) d_q t. \tag{2.8}$$

The following is the Andrews–Askey integral [10] which can be derived from Ramanujan’s  ${}_1\psi_1$  summation:

$$\int_c^d \frac{(qt/c, qt/d; q)_\infty}{(at, bt; q)_\infty} d_q t = \frac{d(1-q)(q, dq/c, c/d, abcd; q)_\infty}{(ac, ad, bc, bd; q)_\infty}, \tag{2.9}$$

provided that no zero factors occur in the denominator of the integrals.

**3. The proof of Theorem 1.1**

Using the Andrews–Askey integral and the Leibniz rule for the  $q$ -difference operator, the  $q$ -integral representation of the Al-Salam–Carlitz polynomials can be easily derived. Throughout this section, whenever  $D_q$  is applied, the argument should be viewed as a function of  $a$ .

**Proof.** Applying  $D_q^n$  to both sides of (2.9), using

$$D_q^n \left\{ \int_c^d f(a; t) d_q t \right\} = \int_c^d D_q^n \{f(a; t)\} d_q t \quad (3.1)$$

and

$$D_q^n \left\{ \frac{(qt/c, qt/d; q)_\infty}{(at, bt; q)_\infty} \right\} = \frac{(qt/c, qt/d; q)_\infty t^n}{(at, bt; q)_\infty}, \quad (3.2)$$

we get

$$\begin{aligned} \int_c^d \frac{(qt/c, qt/d; q)_\infty t^n}{(at, bt; q)_\infty} d_q t &= D_q^n \left\{ \frac{d(1-q)(q, dq/c, c/d, abcd; q)_\infty}{(ac, ad, bc, bd; q)_\infty} \right\} \\ &= \frac{d(1-q)(q, dq/c, c/d; q)_\infty}{(bc, bd; q)_\infty} D_q^n \left\{ \frac{(abcd; q)_\infty}{(ac; q)_\infty} \cdot \frac{1}{(ad; q)_\infty} \right\} \\ &= \frac{d(1-q)(q, dq/c, c/d; q)_\infty}{(bc, bd; q)_\infty} \\ &\quad \times \sum_{k=0}^n q^{k(k-n)} \begin{bmatrix} n \\ k \end{bmatrix} D_q^k \left\{ \frac{(abcd; q)_\infty}{(ac; q)_\infty} \right\} D_q^{n-k} \left\{ \frac{1}{(adq^k; q)_\infty} \right\}. \end{aligned} \quad (3.3)$$

Employing (2.5), we finally obtain

$$\int_c^d \frac{(qt/c, qt/d; q)_\infty t^n}{(at, bt; q)_\infty} d_q t = \frac{d(1-q)(q, dq/c, c/d, abcd; q)_\infty}{(ac, ad, bc, bd; q)_\infty} \sum_{k=0}^n \begin{bmatrix} n \\ k \end{bmatrix} \frac{(ad, bd; q)_k}{(abcd; q)_k} c^k d^{n-k}. \quad (3.4)$$

If we let  $b = 0$ ,  $c = x$  and  $d = 1$  in (3.4), we get (1.4).  $\square$

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