LINEAR ALGEBRA
AND ITS
APPLICATIONS

# Approximating the inverse of a symmetric positive definite matrix 

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#### Abstract

It is shown for an $n \times n$ symmetric positive definite matrix $T=\left(t_{i, j}\right)$ with negative offdiagonal elements, positive row sums and satisfying certain bounding conditions that its inverse is well approximated, uniformly to order $1 / n^{2}$. by a matrix $S=\left(s_{i, l}\right)$, where $s_{i, j}=i_{i, i} / t_{i, t}+1 / t \ldots \delta_{i, j}$ being the Kronecker delta function, and $t$.. being the sum of the elements of $T$. An explicit bound on the approximation error is provided. (c) 1998 Elsevier Science Inc. All rights reserved.


## 1. Introduction

We are concerned here with $n \times n$ symmetric matrices $T=\left(t_{i, i}\right)$ which have negative off-diagonal elements and positive row (and column) sums, i.e.,

$$
t_{i, j}=t_{j, i}, t_{i, j}<0 \quad \text { for } i \neq j \text { and } \sum_{k=1}^{n} t_{i, k}>0 \quad \text { for } i, j=1, \ldots, n .
$$

Such matrices must be positive definite and hence fall into the class of $M$-matrices. (See, e.g., [1] for the definition and properties of $M$-matrices.)

It is convenient to introduce an array $\left\{u_{i, j}\right\}_{i, j=1}^{n}$ of positive numbers defined in terms of $T$ as follows:

[^0]$$
u_{i, j}=-t_{i, j} \quad \text { for } \quad i \neq j \quad \text { and } \quad u_{i, i}=\sum_{k=1}^{n} t_{i, k}, \quad i, j=1, \ldots, n
$$

Then we have

$$
\begin{align*}
& u_{i, j}>0, u_{i, j}=u_{j, i}, \quad t_{i, j}=-u_{i, j} \quad \text { for } i \neq j, \quad \text { and } \\
& t_{i, i}=\sum_{k=1}^{n} u_{i, k}, \quad i, j=1, \ldots, n . \tag{1}
\end{align*}
$$

Moreover, it is convenient :o introduce the notation

$$
\begin{equation*}
m=\min _{i, j} u_{i, j}, \quad M=\max _{i, j} u_{i, j}, \quad t . .=\sum_{i, j=1}^{n} t_{i, j}=\sum_{k=x^{\prime}}^{n} u_{k, k}>0 \tag{2}
\end{equation*}
$$

$\|A\|=\max _{i, j}\left|a_{i, j}\right|$ for a general matrix $A=\left(a_{i, j}\right)$, and the $n \times n$ symmetric positive definite matrix $S=\left(s_{i, j}\right)$, with

$$
s_{i, j}=\frac{\delta_{i, j}}{t_{i, i}}+\frac{1}{t . .}
$$

where $\delta_{i, j}$ denotes the Kronecker delta function.

## Theorem.

$$
\left\|T^{-1}-S\right\| \leqslant \frac{C(m, M)}{n^{2}}
$$

where

$$
C(m, M)=\left(1+\frac{M}{m}\right) \frac{M}{m^{2}}
$$

The authors [2] use this theorem while establishing the asymptotic normality of a vector-valued estimator arising in a study of the Bradley-Terry model for paired comparisons. Depending on $n$, which goes to infinity in the asymptotic limit, we need to consider the inverse $T^{-1}$ of a matrix $T$ satisfying Eq. (1) with $m$ and $M$ being bounded away from 0 and infinity. Since it is impossible to obtain this inverse explicitly, except for a few special cases, we show that the approximate inverse $S$ is a workable substitute, with the attendant errors going to zero at the rate $1 / n^{2}$ as $n \rightarrow \infty$.

Computing and estimating the inverse of a matrix has been extensively studied and described in the literature. See [3-5] and references therein. In [4], the characterization of inverses of symmetric tridiagonal and block tridiagonal matrices is discussed, which gives rise to stable algorithms for computing their inverses. [3] and [5] derive, among other things, upper and lower bounds for the elements of the inverse of a symmetric positive definite matrix. In particular, for a symmetric positive definite matrix $A=\left(a_{i, j}\right)$ of dimension
$n$, the following bounds on the diagonal elements of $A^{-1}$ are given in [3] and [5]:

$$
\frac{1}{\alpha}+\frac{\left(\alpha-a_{i, i}\right)^{2}}{\alpha\left(\alpha a_{i, i}-\sum_{k=1}^{n} a_{i, k}^{2}\right)} \leqslant\left(A^{-1}\right)_{i, i} \leqslant \frac{1}{\beta}-\frac{\left(a_{i, i}-\beta\right)^{2}}{\beta\left(\sum_{k=1}^{n} a_{i, k}^{2}-\beta a_{1, i}\right)},
$$

where $\alpha \geqslant \lambda_{n}$ and $0<\beta \leqslant \lambda_{1}, \lambda_{1}$ and $\lambda_{n}$ being the smallest and largest eigenvalues of $A$, respectively.

The next section contains the proof of the theorem, and some remarks are given in Section 3.

## 2. Proof of the theorem

Note that

$$
T^{-1}-S=\left(T^{-1}-S\right)\left(I_{n}-T S\right)+S\left(I_{n}-T S\right)
$$

where $I_{n}$ is the $n \times n$ identity matrix. Letting $V=I_{n}-T S$ and $W=S V$, we have

$$
T^{-1}-S=\left(T^{-1}-S\right) V+W
$$

Thus the task is to show that $\|F\| \leqslant C(m, M)$, where the matrices $F=n^{2}\left(T^{-1}-S\right)$ and $G=n^{2} W$ satisfy the recursion

$$
\begin{equation*}
F=F V+G . \tag{3}
\end{equation*}
$$

By the definitions of $S, V=\left(v_{i, j}\right)$ and $W=\left(w_{i, j}\right)$, it follows from Eqs. (1) and (2) that

$$
\begin{align*}
v_{i, j} & =\delta_{i, j}-\sum_{k=1}^{n} t_{i, k} s_{k . j} \\
& =\delta_{i, j}-\sum_{k=1}^{n} t_{i, k}\left(\frac{\delta_{k, j}}{t_{i, j}}+\frac{1}{t . .}\right)  \tag{4}\\
& =\delta_{i, j}-\frac{t_{i, j}}{t_{j, j}}-\frac{u_{i, i}}{t . .} \\
& =\left(1-\delta_{i, j}\right) \frac{u_{i, j}}{t_{j, j}}-\frac{u_{i, i}}{t . .}
\end{align*}
$$

and

$$
\begin{align*}
w_{i, j} & =\sum_{k=1}^{n} s_{i, k} v_{k, j}=\sum_{k=1}^{n}\left(\frac{\delta_{i . k}}{t_{i, i}}+\frac{1}{t . .}\right)\left(\left(1-\delta_{k, j} \frac{u_{k, j}}{t_{j, j}}-\frac{u_{k . k}}{t . .}\right)\right. \\
& =\sum_{k=1}^{n} \frac{\delta_{i, k}}{t_{i, i}}\left(\left(1-\delta_{k, j}\right) \frac{u_{k, j}}{t_{j, j}}-\frac{u_{k . k}}{t . .}\right)+\sum_{k=1}^{n} \frac{1}{t . .}\left(\left(1-\delta_{k, j}\right) \frac{u_{k, j}}{t_{j, j}}-\frac{u_{k . k}}{t . .}\right)  \tag{5}\\
& =\frac{\left(1-\delta_{i, j}\right) u_{i, j}}{t_{i, i} t_{j, j}}-\frac{u_{i, i}}{t_{i, i} t . .}-\frac{u_{j, j}}{t_{j, j} t . .}
\end{align*}
$$

Again by Eqs. (1) and (2), we have

$$
0<\frac{u_{i, j}}{t_{i, i} t_{j, j}} \leqslant \frac{M}{m^{2} n^{2}}, \quad 0<\frac{u_{i, i}}{t_{i, i} t . .} \leqslant \frac{M}{m^{2} n^{2}},
$$

so that

$$
\left|w_{i, j}\right| \leqslant \frac{a}{n^{2}} \text { and }\left|w_{i, j}-w_{i, k}\right| \leqslant \frac{a}{n^{2}} \quad \text { for } i, j, k=1, \ldots, n,
$$

where $a=2 \mathrm{M} / \mathrm{m}^{2}$. Equivalently, in terms of the elements of $G=\left(g_{i, j}\right)$ :

$$
\begin{equation*}
\left|g_{i, j}\right| \leqslant a \text { and }\left|g_{i, j}-g_{i, k}\right| \leqslant a, \quad i, j, k=1, \ldots, n \tag{6}
\end{equation*}
$$

We now turn our attention to Eq. (3), expressed in terms of the matrix elements $f_{i, j}$ and $g_{i, j}$ in $F$ and $G$, respectively, and the formula for $v_{i, j}$ in Eq. (4):

$$
\begin{equation*}
f_{i, j}=\sum_{k=1}^{n} f_{i, k}\left(1-\delta_{k, j}\right) \frac{u_{k, j}}{t_{j, j}}-\sum_{k=1}^{n} f_{i, k} \frac{u_{k, k}}{t . .}+g_{i, j}, \quad i, j=1, \ldots, n . \tag{7}
\end{equation*}
$$

The task is to show $\left|f_{i, j}\right| \leqslant C(m, M)$ for all $i$ and $j$.
Two things are readily apparent in Eq. (7). To begin with, apart from the factor $\left(1-\delta_{k, j}\right)$ in the first sum, which equals one except when $k=j$, the first and second sums are weighted averages of $f_{i, k}, k=1, \ldots, n$; the positive weights $u_{k, j} / t_{j, i}$ and $u_{k, k} / t$.. each add to unity in the index $k$. Secondly, the index $i$ plays no essential role in the relationship; it can be viewed as fixed. If we take $i$ to be fixed and notationally suppress it in Eq. (7), then Eq. (7) assumes the form of $n$ linear equations in the $n$ unknowns $f_{1}, \ldots, f_{n}$ :

$$
\begin{equation*}
f_{j}=\sum_{k=1}^{n} f_{k}\left(1-\delta_{k, j}\right) \frac{u_{k, j}}{t_{j, j}}-\sum_{k=1}^{n} f_{k} \frac{u_{k, k}}{t . .}+g_{j}, \quad j=1, \ldots, n . \tag{8}
\end{equation*}
$$

Instead of solving these equations, we will show that under the bounding conditions

$$
\left|g_{i}\right| \leqslant a, \quad\left|g_{i}-g_{k}\right| \leqslant a, j, k=1, \ldots, n,
$$

(see Eq. (6)) any solution of Eq. (8) must satisfy the inequalities

$$
\begin{equation*}
\left|f_{j}\right| \leqslant \frac{1}{2}\left(1+\frac{M}{m}\right) a, \quad j=1, \ldots, n, \tag{9}
\end{equation*}
$$

so that $\left|f_{j}\right| \leqslant C(m, M), j=1, \ldots, n$, thereby completing the proof.
Let $\alpha$ and $\beta$ be such that $f_{\alpha}=\max _{1 \leqslant k \leqslant n} f_{k}$ and $f_{\beta}=\min _{1 \leqslant k \leqslant n} f_{k}$. With no loss of generality, assume $f_{x} \geqslant\left|f_{\beta}\right|$. (Otherwise, we may reverse the signs of the $f_{k}$ 's and proceed analogously.) There are two cases to consider:

Case I: $f_{\beta} \geqslant 0$. Then

$$
\begin{aligned}
f_{x} & =\sum_{k=1}^{n} f_{k}\left(1-\delta_{k, x}\right) \frac{u_{k, x}}{t_{x, x}}-\sum_{k=1}^{n} f_{k} \frac{u_{k, k}}{t . .}+g_{x} \\
& \leqslant \sum_{k=1}^{n} f_{k} \frac{u_{k, x}}{t_{x, x}}-\sum_{k=1}^{n} f_{k} \frac{u_{k, k}}{t . .}+g_{x} \\
& =\sum_{k=1}^{n} f_{k}\left(\frac{u_{k, x}}{t_{x, x}}-\frac{u_{k, k}}{t . .}\right)+g_{x} \\
& \leqslant f_{x} \sum_{k \in A}\left(\frac{u_{k, x}}{t_{x, x}}-\frac{u_{k, k}}{t . .}\right)+g_{x}
\end{aligned}
$$

where $A=\left\{k: u_{k . x} / t_{x, x}>u_{k, k} / t ..\right\}$. Let $\rho$ denote the cardinality of $A$, and observe that

$$
\begin{equation*}
\sum_{k \in A}\left(\frac{u_{k . x}}{i_{x . x}}-\frac{u_{k . k}}{t . .}\right) \leqslant \frac{M \rho}{M \rho+m(n-\rho)}-\frac{m \rho}{m \rho+M(n-\rho)} \leqslant \frac{M-m}{M+m} \tag{10}
\end{equation*}
$$

the first inequality being an immediate consequence of the constraints $m \leqslant u_{i, j} \leqslant M$ (see Eq. (2)) and the sum formulas in Eqs. (1) and (2), the second inequality taking into account that the middle expression in Eq. (10) is a concave function of $\rho$ (when viewed as a continuous variable between 0 and $n$ ), with its maximum occurring at $\rho=n / 2$. Thus,

$$
f_{x} \leqslant f_{x} \sum_{k \in A}\left(\frac{u_{k, x}}{t_{x, x}}-\frac{u_{k, k}}{t . .}\right)+g_{x} \leqslant f_{x} \frac{M-m}{M+m}+g_{x} \leqslant f_{x} \frac{M-m}{M+m}+a
$$

so that

$$
f_{x} \leqslant \frac{1}{2}\left(1+\frac{M}{m}\right) a=C(m, M)
$$

thereby estab ishing Eq. (9) and completing the proof.
Case II: $f_{\beta}<0$. Let $h_{k}=f_{k}-f_{\beta} \geqslant 0, k=1, \ldots, n$. Then

$$
\begin{aligned}
h_{x} & =f_{x}-f_{\beta} \\
& \leqslant \sum_{k=1}^{n} f_{k} \frac{u_{k, x}}{t_{x, x}}-\sum_{k=1}^{n} f_{k} \frac{u_{k, \beta}}{t_{\beta, \beta}}+g_{\gamma}-g_{\beta} \\
& =\sum_{k=1}^{n} h_{k} \frac{u_{k, x}}{t_{x, x}}-\sum_{k=1}^{n} h_{k} \frac{u_{k, \beta}}{t_{\beta, \beta}}+g_{x}-g_{\beta} \\
& =\sum_{k=1}^{n} h_{k}\left(\frac{u_{k, x}}{t_{x, x}}-\frac{u_{k, \beta}}{t_{\beta, \beta}}\right)+g_{x}-g_{\beta} \\
& \leqslant h_{x} \sum_{k \subseteq A}\left(\frac{u_{k, x}}{t_{x, x}}-\frac{u_{k, \beta}}{t_{\beta, \beta}}\right)+g_{x}-g_{\beta}
\end{aligned}
$$

where $A=\left\{k: u_{k, \alpha} / t_{\alpha, \alpha}>u_{k, \beta} / t_{\beta, \beta}\right\}$. The argument from this point proceeds analogously to that for Case I. Letting $\rho$ denote the cardinality of $A$, one obtains

$$
\sum_{k \in A}\left(\frac{u_{k, x}}{t_{x, \chi}}-\frac{u_{k, \beta}}{t_{\beta, \beta}}\right) \leqslant \frac{M \rho}{M \rho+m(n-\rho)}-\frac{m \rho}{m \rho+M(n-\rho)} \leqslant \frac{M-m}{M+m},
$$

which leads to

$$
h_{x} \leqslant h_{x} \frac{M-m}{M+m}+g_{x}-g_{\beta} \leqslant h_{x} \frac{M-m}{M+m}+a,
$$

so that

$$
f_{x} \leqslant h_{x} \leqslant \frac{1}{2}\left(1+\frac{M}{m}\right) a,
$$

thereby establishing Eq. (9) and completing the proof.

## 3. Remarks

While our proof of the theorem is somewhat long, we do not see how to simplify it by using any of the well-known properties of $M$-matrices.

The bound $C(m, M) / n^{2}$ on the approximation error is a product of two factors, one depending on $m$ and $M$, the other on $n$. For large $n$, with $m$ and $M$ held bounded away from 0 and infinity, the elements of $S$ (and hence of $T^{-1}$ ) are all of order $1 / n$, and the errors (i.e., the elements of $T^{-1}-S$ ) are uniformly $\mathrm{O}\left(1 / n^{2}\right)$ as $n \rightarrow \infty$. This fact is crucially used in Ref. [2].

A particular case of the matrix $T$, described below, shows that the factor $1 / n^{2}$ is best possible in the sense that any bound of the for $\tilde{C}(m, M) / \gamma(n)$ requires $\gamma(n)=\mathrm{O}\left(n^{2}\right)$ as $n \rightarrow \infty$; no faster growth rate than $n^{2}$ is allowed. On the other hand, it is natural to ask whether the factor $C(m, M)$ is best possible. To clarify the issue, for given integer $n$ and given $m$ and $M, 0<m \leqslant M<\infty$, let $Q_{n}(m, M)$ denote the set of $n \times n$ symmetric positive definite matrices satisfying (1) with $m \leqslant u_{i, j} \leqslant M, i, j=1, \ldots, n$, and define

$$
C_{n}(m, M)=\sup \left\{n^{2}\left\|T^{-1}-S\right\|: T \in Q_{n}(m, M), n=1,2, \ldots\right\} .
$$

It follows from the theorem that $C_{o}(m, M) \leqslant C(m, M)=(1+M / m) M / m^{2}$. But for the special matrix $T$ satisfying Eq. (1) with $u_{1,1}=M$ and $u_{i, j}=m$ for all other $(i, j)$, we find that

$$
\left(T^{-1}\right)_{i . j}= \begin{cases}\frac{2}{2 M+(n-1) m} & \text { for } i=j=1, \\ \frac{1}{2 M+(n-1) m} & \text { for } i=1, j \neq 1 \text { or } i \neq 1, j=1 \\ \frac{3 M+(2 n-1) m}{(n+1) m(2 M+(n-1) m)} & \text { for } i=j \neq 1, \\ \frac{M+n m}{(n+1) m(2 M+(n-1) m)} & \text { for } 1 \neq i \neq j \neq 1\end{cases}
$$

So

$$
\left(T^{-1}-S\right)_{1.1}=\frac{-2 M}{(M+(n-1) m)(2 M+(n-1) m)},
$$

from which it follows that $C_{o}(m, M) \geqslant 2 M / m^{2}$. The same matrix $T$ justifies the constraint on $\gamma(n)$ described above.

The gap between $2 M / m^{2}$ and $(1+M / m) M / m^{2}$ suggests that there might be room for improvement in our bound. Indeed, by computer, we have numerically inverted a very large number of matrices of various dimensions (some as large as $300 \times 300$ ) and found that the inequality $n^{2}\left\|T^{-1}-S\right\| \leqslant 2 M / m^{2}$ holds in all cases. It would therefore be interesting to see whether $C_{o}(m, M)=2 M / m^{2}$.

We finish with one final observation. Surprisingly, it is possible to evaluate the second sum in Eq. (7) explicitly:

$$
\sum_{k=1}^{n} f_{i . k} \frac{u_{k . k}}{t . .}=-n^{2} \frac{u_{i . i}}{t_{i . i} t . .}
$$

which is identical to, and permits a cancellation with, one of the three terms defining $g_{i, j}$ (cf., Eq. (5)). To obtain this, one multiplies both sides of Eq. (7) by $t_{i, j}$, adds over $j(j=1, \ldots, n)$, and carries out the suggested algebra. While we have not found much use for this identity, it does show that $f_{\beta}$, appearing in the proof of the theorem, is strictly negative. Since, as it turns out, $f_{x}$ can be positive or negative, neither case described in the proof is superfluous.

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