Contents lists available at ScienceDirect

# **Applied Mathematics Letters**

journal homepage: www.elsevier.com/locate/aml

# Fréchet approach in second-order optimization

# Dušan Bednařík<sup>a</sup>, Karel Pastor<sup>b,\*</sup>

<sup>a</sup> Department of Mathematics, University of Hradec Králové, Rokitanského 62, 500 03 Hradec Králové, Czech Republic <sup>b</sup> Department of Mathematical Analysis and Applications of Mathematics, Faculty of Science, Palacký University, Tř. Svobody 26, 771 46 Olomouc, Czech Republic

### ARTICLE INFO

Article history: Received 12 March 2007 Received in revised form 19 November 2008 Accepted 6 January 2009

Keywords: Generalized derivative Second-order optimality conditions Isolated minimizer of order 2 C<sup>1,1</sup> function  $\ell$ -stability

## ABSTRACT

We state a certain second-order sufficient optimality condition for functions defined in infinite-dimensional spaces by means of generalized Fréchet's approach to second-order differentiability. Moreover, we show that this condition generalizes a certain second-order condition obtained in finite-dimensional spaces.

© 2009 Elsevier Ltd. All rights reserved.

Applied Mathematics

ELECTRON

Letters

# 1. Introduction and preliminary facts

Second-order sufficient optimality conditions play a very important role in optimization theory, see e.g. [1–29] and the references therein.

Various generalized second-order sufficient optimality conditions have been introduced since 80s of the last century. In our previous articles [14,15], we established the generalized second-order sufficient optimality condition by means of a certain second-order derivative of the Peano type for the so-called  $\ell$ -stable functions (see Theorem 1).

Let us give a short survey of notions concerning  $\ell$ -stability. Unless stated otherwise, we assume that X is a normed linear space,  $S_X$  is the unit sphere of X and for  $x \in X$  and  $\delta > 0$ ,  $B(x, \delta)$  denotes the set  $\{y \in X; \|y - x\| < \delta\}$ .

For a function  $f : X \to \mathbb{R}$ ,  $x, h \in X$ , we denote

$$f^{\ell}(x; h) = \liminf_{t \downarrow 0} \frac{f(x+th) - f(x)}{t}$$

**Lemma 1** ([14, Lemma 4]). Let  $f : X \to \mathbb{R}$  be a continuous function, and let  $a, b \in X$ . Then there exist  $\xi_1, \xi_2 \in (a, b)$  such that

$$f^{\ell}(\xi_1; b-a) \leq f(b) - f(a) \leq f^{\ell}(\xi_2; b-a).$$

We say that  $f : X \to \mathbb{R}$  is  $\ell$ -stable at  $x \in X$  if there exist a neighbourhood U of x and K > 0 such that

 $|f^{\ell}(y;h) - f^{\ell}(x;h)| \le K ||y-x||, \quad \forall y \in U, \forall h \in S_X.$ 

\* Corresponding author.



E-mail addresses: dbednarik@seznam.cz (D. Bednařík), pastor@inf.upol.cz (K. Pastor).

<sup>0893-9659/\$ –</sup> see front matter 0 2009 Elsevier Ltd. All rights reserved. doi:10.1016/j.aml.2009.01.019

We notice that the property to be an  $\ell$ -stable function at some point requires weaker assumptions than the property to be a  $C^{1,1}$  function near this point. Recall that  $f : X \to \mathbb{R}$  is a  $C^{1,1}$  function near  $x \in X$  if it is differentiable on some neighbourhood of x and its derivative  $f'(\cdot)$  is Lipschitz here.  $C^{1,1}$  functions appear in, e.g., the augmented Lagrange method, the penalty function method and the proximal point method. In [14, Example 6] an example of the function  $f : \mathbb{R} \to \mathbb{R}$ which is  $\ell$ -stable at 0 but which is not differentiable on any neighbourhood of 0 was given.

As was shown in [14,15],  $\ell$ -stability at *x* implies for a continuous function defined on a finite-dimensional space the Lipschitzness on a neighbourhood of *x* and also the strict differentiability at *x*. The differentiability properties of the functions which are  $\ell$ -stable at some point and which are defined on an arbitrary normed space were studied in [16].

**Theorem 1** ([14,15]). Let a function  $f : \mathbb{R}^N \to \mathbb{R}$  be  $\ell$ -stable at  $x \in \mathbb{R}^N$ . If  $f^{\ell}(x; h) = 0$  for every  $h \in S_{\mathbb{R}^N}$ , and

$$\underline{f}_{-P}^{\prime\ell}(x;h) := \liminf_{t\downarrow 0} \frac{f(x+th) - f(x) - tf^{\ell}(x;h)}{t^2/2} > 0, \quad \forall h \in S_{\mathbb{R}^N},$$

then x is an isolated minimizer of order 2 for f.

Recall that  $x \in X$  is an *isolated minimizer of order*  $k (k \in \mathbb{N})$  for a function  $f : X \to \mathbb{R}$  if there are neighbourhood U of x and A > 0 satisfying  $f(y) \ge f(x) + A ||y - x||^k$  for every  $y \in U$ . It is easy to verify that each isolated minimizer is a strict local minimizer.

By means of Theorem 1 we generalized the previous results given in [17, Theorem 3.2], [2, Proposition 5.2], [18, Theorem 3.2], and [19, Theorem 2] as was shown in [14]. Theorem 1 also generalizes the unconstrained and scalar case of results presented in [24, Theorem 5] and [25, Theorem 4.2] as it follows from the remarks given in [25].

In the paper [14] we also compared Theorem 1 with the one presented in [20, Theorem 2.9] by L.R. Hung and K.F. Ng. We recall that it was shown in [20, page 388] that Theorem 1 of Chaney in [21] is a weak form of the result of L.R. Hung and K.F. Ng mentioned before.

We would like to recall that Ginchev in [26] (see also [19]) stated the following sufficient and necessary optimality condition for an isolated minimizer of second order using the derivatives of Hadamard type, i.e.

$$f'_{-}(x; h) = \liminf_{u \to h, t \downarrow 0} \frac{f(x + tu) - f(x)}{t}$$

and

$$f''_{-}(x;h) = \liminf_{u \to h, t \downarrow 0} \frac{f(x+tu) - f(x) - tf'_{-}(x;h)}{t^2/2}$$

**Theorem 2.** Let  $f : \mathbb{R}^N \to \mathbb{R}$  be an arbitrary function, and let  $x \in \mathbb{R}^N$ . If for each  $h \in S_{\mathbb{R}^N}$  one of the following two conditions hold:

(i)  $f'_{-}(x; h) > 0$ (ii)  $f'_{-}(x; h) = 0$  and  $f''_{-}(x; h) > 0$ ,

then x is an isolated minimizer of order 2 for f. Conversely, each isolated minimizer of order 2 satisfies these sufficient conditions.

The derivative  $f''_{-}(x; h)$  does not coincide with the classical ones even in the case of  $C^2$  functions in general in contrast to  $f''_{-P}(x; h)$ . For more details about this "complementary principle" in nonsmooth analysis, see [19]. We also recall that in [19] the problem for what class of functions  $f : \mathbb{R}^N \to \mathbb{R}$  we can replace the Hadamard derivatives by the respective Dini derivatives in Theorem 2 was presented.

Theorem 1 presented recently answered this question for  $\ell$ -stable at some point functions. Nevertheless, our first goal of this paper is to show that Theorem 1 is a special case of Theorem 2.

**Lemma 2.** Let a function  $f : \mathbb{R}^N \to \mathbb{R}$  be  $\ell$ -stable at  $x \in \mathbb{R}^N$  and  $h \in S_{\mathbb{R}^N}$ . Then

$$f^{\ell}(x; h) = f'_{-}(x; h).$$

**Proof.** Since the inequality  $f^{\ell}(x; h) \ge f'_{-}(x; h)$  is evident, it suffices to show that

$$f^{\ell}(x;h) \leq f'_{-}(x;h).$$

Let  $\{t_n\}_{n=1}^{+\infty}$ ,  $\{h_n\}_{n=1}^{+\infty}$  be such sequences that

$$\lim_{n\to+\infty}h_n=h,\qquad \lim_{n\to+\infty}t_n=0,$$

 $t_n > 0$  for every  $n \in \mathbb{N}$ , and

$$\lim_{n \to +\infty} \frac{f(x+t_nh_n) - f(x)}{t_n} = f'_-(x;h).$$

By [14, Proposition 1] f is Lipschitz near x and thus there exists K > 0 satisfying

$$\frac{F(x+t_nh) - f(x)}{t_n} - \frac{f(x+t_nh_n) - f(x)}{t_n} \bigg| = \bigg| \frac{f(x+t_nh) - f(x+t_nh_n)}{t_n} \bigg| \le K \|h - h_n\|,$$

for every sufficiently large  $n \in \mathbb{N}$ . Then

$$\frac{f(x+t_nh) - f(x)}{t_n} \le \frac{f(x+t_nh_n) - f(x)}{t_n} + K \|h - h_n\|$$

for every sufficiently large  $n \in \mathbb{N}$ . Hence

$$f^{\ell}(x;h) \leq \lim_{n \to +\infty} \left( \frac{f(x+t_nh_n) - f(x)}{t_n} + K \|h - h_n\| \right)$$
$$= f'_-(x;h). \quad \Box$$

**Lemma 3.** Let a function  $f : \mathbb{R}^N \to \mathbb{R}$  be  $\ell$ -stable at  $x \in \mathbb{R}^N$  and let  $f^{\ell}(x; h) = 0$  for every  $h \in S_{\mathbb{R}^N}$ . Then

$$f_{p}^{\prime\ell}(x;h) = f_{-}^{\prime\prime}(x;h),$$

for every  $h \in S_{\mathbb{R}^N}$ .

**Proof.** We take an arbitrary  $h \in S_{\mathbb{R}^N}$  and notice that  $f'_-(x; h) = 0$  by Lemma 2. Since the inequality

$$f_{P}^{\prime\ell}(x;h) \ge f_{-}^{\prime\prime}(x;h)$$

is evident, it suffices to show that  $f_{-p}^{\prime\ell}(x;h) \leq f_{-}^{\prime\prime}(x;h)$ . Let  $\{t_n\}_{n=1}^{+\infty}$ ,  $\{h_n\}_{n=1}^{+\infty}$  be such sequences that

$$\lim_{n\to+\infty}h_n=h,\qquad \lim_{n\to+\infty}t_n=0,$$

 $t_n > 0$  for every  $n \in \mathbb{N}$ , and

$$\lim_{n \to +\infty} \frac{2}{t_n^2} (f(x + t_n h_n) - f(x)) = f''_-(x; h).$$

Due to Lemma 1 and the property of  $\ell$ -stability, for every sufficiently large  $n \in \mathbb{N}$  we can find  $\xi_n \in (x+t_nh, x+t_nh_n)$  such that

$$\begin{aligned} \left| \frac{2}{t_n^2} (f(x+t_nh) - f(x)) - \frac{2}{t_n^2} (f(x+t_nh_n) - f(x)) \right| &= \left| \frac{2}{t_n^2} (f(x+t_nh) - f(x+t_nh_n)) \right| \\ &\leq \frac{2}{t_n^2} f^{\ell} (\xi_n; t_n(h-h_n)) \\ &= \frac{2}{t_n} (f^{\ell} (\xi_n; h-h_n) - f^{\ell} (x; h-h_n)) \\ &\leq \frac{2}{t_n} K \|\xi_n - x\| \|h - h_n\|. \end{aligned}$$
(1)

Since  $\xi_n \in (x + t_n h, x + t_n h_n)$ , for every  $n \in \mathbb{N}$  there exists  $\alpha_n \in (0, 1)$  satisfying

$$\frac{2}{t_n} K \|\xi_n - x\| \|h - h_n\| = \frac{2}{t_n} K t_n \|\alpha_n h + (1 - \alpha_n) h_n\| \|h - h_n\| \\ = 2K \|\alpha_n h + (1 - \alpha_n) h_n\| \|h - h_n\|.$$
(2)

Using formulas (1) and (2), we have that for every sufficiently large  $n \in \mathbb{N}$  it holds

$$\frac{2}{t_n^2}(f(x+t_nh)-f(x)) \le \frac{2}{t_n^2}(f(x+t_nh_n)-f(x)) + 2K\|\alpha_nh + (1-\alpha_n)h_n\|\|h-h_n\|.$$

Hence

$$\begin{split} f_{-p}^{\prime\ell}(x;h) &\leq \liminf_{n \to +\infty} \frac{2}{t_n^2} (f(x+t_n h) - f(x)) \\ &\leq \lim_{n \to +\infty} \left( \frac{2}{t_n^2} (f(x+t_n h_n) - f(x)) + 2K \|\alpha_n h + (1-\alpha_n)h_n\| \|h-h_n\| \right) \\ &= f_{-}^{\prime\prime}(x;h), \end{split}$$

because  $\lim_{n \to +\infty} \|h - h_n\| = 0$ .  $\Box$ 

Now, using Lemmas 2 and 3, Theorem 2 implies Theorem 1.

All the previously mentioned results were stated for the functions which are defined on finite-dimensional spaces. In fact, there are not many unconstrained second-order sufficient optimality conditions established in terms of generalized second-order derivatives for infinite dimension. So, maybe now it is time to generalize Theorem 1 with respect to infinite dimension. In this way we will show that  $\int_{-p}^{\ell} (x; h)$  has a certain Fréchet property which is the main aim of our paper.

### 2. Fréchet approach

We will start this section with a definition concerning the Fréchet differentiability and we establish second-order sufficient optimality condition in infinite dimension.

**Definition 1.** Let  $f : X \to \mathbb{R}$  be a function, and let  $x \in X$ . We say that  $f_{p}^{\ell}(x; \cdot)$  is Fréchet if for every  $\varepsilon > 0$  there exists  $\delta > 0$  such that for every  $h \in S_X$  and for every  $0 < t < \delta$  there holds

 $\begin{array}{l} 1. \ f_{\underline{\ell}}^{\prime\ell}(x;h) - \frac{2}{t^2}(f(x+th) - f(x) - tf^\ell(x;h)) < \varepsilon, \ \mathrm{if} \ f_{\underline{\ell}}^{\prime\ell}(x;h) < +\infty. \\ 2. \ \frac{2}{t^2}(f(x+th) - f(x) - tf^\ell(x;h)) > \frac{1}{\varepsilon}, \ \mathrm{if} \ f_{\underline{\ell}}^{\prime\ell}(x;h) = +\infty. \end{array}$ 

It was shown e.g. in [22, page 484] that if f is  $C^2$  with (classical) second-order Fréchet derivative f''(x), then

$$f_{p}^{\prime\ell}(x;h) = f^{\prime\prime}(x;h,h), \quad \forall h \in X.$$

Therefore  $f_p^{\ell}(x; h) < +\infty$  for every  $h \in S_X$  and condition 1 from Definition 1 is satisfied in this case.

**Theorem 3.** Let  $f: X \to \mathbb{R}$  be a function,  $x \in X$ , and let c > 0. If  $f^{\ell}(x; h) = 0$  for every  $h \in S_X$ ,  $f'^{\ell}_p(x; \cdot)$  is Fréchet, and

 $f_{P}^{\prime\ell}(x;h) \geq c, \quad \forall h \in S_X,$ 

then x is an isolated minimum of second order for f.

**Proof.** We put  $\varepsilon = \min\{\frac{c}{2}, 1\}$ . There exists  $\delta > 0$  such that for every  $h \in S_X$  and for every  $0 < t < \delta$ , we have

$$\frac{2}{t^2}(f(x+th)-f(x)-tf^{\ell}(x;h)) > \varepsilon.$$

Since  $f^{\ell}(x; h) = 0$  for every  $h \in S_X$ , the previous inequality implies

$$f(x+th) - f(x) > \frac{\varepsilon}{2}t^2, \quad \forall h \in S_X, \forall 0 < t < \delta.$$

Thus, *x* is an isolated minimizer of second order for *f*.  $\Box$ 

A series of the following lemmas yields to the properties of  $f_{-P}^{\prime \ell}(x; \cdot)$  for an  $\ell$ -stable function which are presented in Proposition 1.

**Lemma 4** ([23, Lemma 2.1]). Let  $f : X \to \mathbb{R}$  be Lipschitz near  $x \in X$ . Then the function  $h \mapsto f^{\ell}(x; h)$  is continuous on X.

**Lemma 5** ([23, Lemma 2.2]). Let  $f : \mathbb{R}^N \to \mathbb{R}$  be Lipschitz near  $x \in \mathbb{R}^N$ . Then for every  $\varepsilon > 0$  there exists  $\delta > 0$  such that for every  $h \in S_{\mathbb{R}^N}$ 

$$0 < t < \delta \Longrightarrow f^{\ell}(x;h) - \varepsilon < \frac{f(x+th) - f(x)}{t}.$$

**Lemma 6.** Let  $f : X \to \mathbb{R}$  be a function which is continuous near  $x \in X$  and  $\ell$ -stable at x. If  $f^{\ell}(x; h) = 0$  for every  $h \in S_X$ , then the function  $g : X \to \mathbb{R}$  defined by

$$g(y) = \begin{cases} \frac{f(y) - f(x)}{\|y - x\|}, & \text{if } y \neq x, \\ 0, & \text{if } y = x, \end{cases}$$

is Lipschitz near x.

**Proof.** Step 1. We can suppose without any loss of generality that x = 0 and f(0) = 0. We have to prove that the following function  $g : X \to \mathbb{R}$ ,

$$g(y) = \begin{cases} \frac{f(y)}{\|y\|}, & \text{if } y \neq 0, \\ 0, & \text{if } y = 0, \end{cases}$$

is Lipschitz near 0.

If *f* is  $\ell$ -stable at 0, there are K > 0 and  $\delta > 0$  such that

$$|f^{\ell}(y;h) - f^{\ell}(0;h)| \le K ||y||, \quad \forall y \in B(0,\delta), \forall h \in S_X$$

Now, let us choose arbitrary  $y, z \in B(0, \delta)$  such that  $y \neq z$ .

Step 2. If ||y|| = ||z||, due to Lemma 1 there is  $\xi \in (z, y)$  such that

$$\begin{split} \|g(z) - g(y)\| &= \frac{|f(z) - f(y)|}{\|z\|} \le \frac{|f^{\ell}(\xi; z - y)|}{\|z\|} \\ &= \frac{|f^{\ell}(\xi; z - y) - f^{\ell}(0; z - y)|}{\|z\|} \le \frac{K \|\xi\| \|z - y\|}{\|z\|}. \end{split}$$

Since  $\|\xi\| < \|z\|$ , the previous calculation implies

$$||g(z) - g(y)|| \le K ||z - y||.$$

Step 3. In the next special case  $-y = 0, z \neq 0$  – due to Lemma 1 we can find  $\xi \in (0, z)$  such that

$$\begin{aligned} \|g(z) - g(y)\| &= \frac{|f(z) - f(y)|}{\|z\|} \le \frac{|f^{\ell}(\xi; z) - f^{\ell}(0; z)|}{\|z\|} \\ &\le \frac{K \|\xi\| \|z\|}{\|z\|} = K \|\xi\| \le K \|z - y\|. \end{aligned}$$

Step 4. Now, we suppose that there exists t > 0 with the property z = y + ty. Using Lemma 1, we can find  $\xi_1 \in (y, y + ty)$  and  $\xi_2 \in (0, y)$  satisfying

$$\begin{split} \|g(z) - g(y)\| &= \left| \frac{f(y+ty)}{\|y+ty\|} - \frac{f(y)}{\|y\|} \right| = \left| \frac{f(y+ty) - f(y)(1+t)}{\|y\|(1+t)} \right| \\ &= \frac{1}{1+t} \left| \frac{f(y+ty) - f(y) - t(f(y) - f(0))}{\|y\|} \right| \\ &\leq \frac{1}{1+t} \left| \frac{f(y+ty) - f(y)}{\|y\|} \right| + \frac{t}{1+t} \left| \frac{f(y) - f(0)}{\|y\|} \right| \\ &\leq \frac{t}{1+t} \left( \left| f^{\ell} \left( \xi_{1}; \frac{y}{\|y\|} \right) - f^{\ell} \left( 0; \frac{y}{\|y\|} \right) \right| + \left| f^{\ell} \left( \xi_{2}; \frac{y}{\|y\|} \right) - f^{\ell} \left( 0; \frac{y}{\|y\|} \right) \right| \right) \\ &\leq \frac{t}{1+t} K(\|\xi_{1}\| + \|\xi_{2}\|) \leq \frac{Kt}{1+t} (\|y+ty\| + \|y\|) \\ &= \frac{2+t}{1+t} Kt \|y\| \leq 2Kt \|y\| = 2K \|z-y\|. \end{split}$$

Since the case y = z is clear and because of Step 3, the Lipschitzness of function g will be proved when we show that for arbitrary  $y, z \in B(0, \delta), y \neq 0, z \neq 0, y \neq z$ , we have

$$\|g(z) - g(y)\| \le 5K \|z - y\|.$$
(3)

We can suppose that  $||z|| \ge ||y||$ . We put

$$s = ||z|| - ||y||, \qquad z_1 = z - \frac{s}{2} \frac{z}{||z||}, \qquad y_1 = y + \frac{s}{2} \frac{y}{||y||}$$

Then  $||z_1|| = ||y_1||$  and Steps 2 and 4 imply

$$||g(z) - g(y)|| \le ||g(z) - g(z_1)|| + ||g(z_1) - g(y_1)|| + ||g(y_1) - g(y)|| \le 2K||z - z_1|| + K||z_1 - y_1|| + 2K||y_1 - y||.$$
(4)

Using elementary geometry, we can obtain that

$$||z - z_1|| \le ||z - y||$$
,  $||z_1 - y_1|| \le ||z - y||$  and  $||y_1 - y|| \le ||z - y||$ .

Thus formula (4) implies the considered inequality (3).  $\Box$ 

**Proposition 1.** Let  $f : X \to \mathbb{R}$  be a function which is continuous near  $x \in X$  and  $\ell$ -stable at x. If  $f^{\ell}(x; h) = 0$  for every  $h \in S_X$ , the function  $h \mapsto \int_{-p}^{\ell} (x; h)$  is continuous on X.

Moreover, if  $X = \mathbb{R}^N$ , then  $f_P^{\prime \ell}(x; \cdot)$  is Fréchet.



**Fig. 1.** Function  $\varphi$ .

**Proof.** Let us consider the function  $g : X \to \mathbb{R}$  such that

$$g(y) = \begin{cases} \frac{2(f(y) - f(x))}{\|y - x\|}, & \text{for } y \neq x, \\ 0, & \text{for } y = x. \end{cases}$$

Then

$$g^{\ell}(x;h) = \liminf_{t \downarrow 0} \frac{g(x+th) - g(x)}{t} = \liminf_{t \downarrow 0} \frac{2^{\frac{f(x+th) - f(x)}{\|th\|}} - 0}{t}$$
$$= \liminf_{t \downarrow 0} \frac{f(x+th) - f(x) - tf^{\ell}(x;h)}{t^{2}/2} = \frac{f^{\ell}(x;h)}{t},$$
(5)

for every  $h \in S_X$ . Due to Lemmas 4 and 6, the function  $h \mapsto f_p^{\prime \ell}(x; h)$  is continuous on *X*. The second part of theorem follows from formula (5) and Lemmas 5 and 6.  $\Box$ 

Using Proposition 1 together with the fact that an  $\ell$ -stable function at some point defined on a finite-dimensional space is continuous near this point [15], the compactness of  $S_{\mathbb{R}^N}$  implies the following consequence.

**Corollary 1.** Let  $f : \mathbb{R}^N \to \mathbb{R}$  be a function which is  $\ell$ -stable at  $x \in \mathbb{R}^N$ . If  $f^{\ell}(x; h) = 0$  for every  $h \in S_{\mathbb{R}^N}$  and

$$f_{\mathcal{P}}^{\prime\ell}(x;h) > 0, \quad \forall h \in S_{\mathbb{R}^N},$$

then there exists c > 0 satisfying

$$\underline{f}_{P}^{\prime\ell}(x;h) \geq c, \quad \forall h \in S_{\mathbb{R}^{N}}.$$

Now, by Proposition 1 and Corollary 1, Theorem 1 is a special case of Theorem 3.

Finishing the paper, we show an example of nonconvex and noncontinuous function for which we can use Theorem 3. We use some ideas from [14, Example 2]

**Example 1.** Consider a sequence  $a_n = 1/n$ , n = 1, 2, ... Then

$$\lim_{n\to\infty}\frac{a_{n+1}+a_n^2}{a_{n+1}+a_n}=\frac{1}{2}>0.$$

Let us define a function  $\varphi : [0, \infty) \to \mathbb{R}$  as follows (see Fig. 1 for the construction of  $\varphi$ ).

$$\varphi(u) = \begin{cases} a_1, & \text{if } u > a_1, \\ \frac{a_n^2 - a_{n+1}}{a_n - a_{n+1}} (u - a_{n+1}) + a_{n+1}, & \text{if } u \in (a_{n+1}, a_n], \\ 0, & \text{if } u = 0. \end{cases}$$

Next, we will define a function  $f : \mathbb{R} \to \mathbb{R}$  via the Riemann integral :

$$f(x) := \int_0^{|x|} \varphi(u) \mathrm{d} u, \ x \in \mathbb{R}.$$

Since  $\varphi$  is a piecewise affine function, the integral exists.

It is easy to show that f is differentiable at 0 with derivative equal to 0. Now we claim that  $f_{p}^{\ell}(0; \pm 1) > 0$ . So it suffices to show that

$$\liminf_{t\downarrow 0}\frac{f(t)}{t^2/2}>0.$$

Note that there is  $\epsilon > 0$  such that for each  $n \in \mathbb{N}$  it holds:

$$\frac{a_{n+1}+a_n^2}{a_{n+1}+a_n}\geq\epsilon>0.$$

Now consider  $t \in [a_{j+1}, a_j)$  for some  $j \in \mathbb{N}$  and fix  $k \in \mathbb{N}$ ,  $k \ge j + 2$ . Let  $S_n$  denote an area of a trapezoid over the interval  $(a_{n+1}, a_n)$ , n = j + 1, ..., k, bounded by a graph of  $\varphi$ . Let R denote an area of a trapezoid over the interval  $(a_{j+1}, t)$  bounded by the graph of  $\varphi$ . Now we can write down the formula for the integral:

$$\int_{a_k}^t \varphi(u) \mathrm{d}u = \left(\sum_{n=j+1}^k S_n\right) + R.$$

Further  $\tilde{S}_n$  stands for an area of a trapezoid over the interval  $(a_{n+1}, a_n)$ , n = j + 1, ..., k bounded by the linear function y = x, and  $\tilde{R}$  stands for an area of a trapezoid over the interval  $(a_{j+1}, t)$  bounded also by the function y = x. Now it can be shown that

$$\int_{a_k}^t \varphi(u) du = \left(\sum_{n=j+1}^k S_n\right) + R \ge \epsilon \sum_{n=j+1}^k \tilde{S}_n + \epsilon \tilde{R}$$
$$= \epsilon \left(\sum_{n=j+1}^k \tilde{S}_n + \tilde{R}\right).$$

Letting  $k \to +\infty$ , we will get:

$$f(t) = \int_0^t \varphi(u) dt \ge \epsilon \left( \sum_{n=j+1}^\infty \tilde{S}_n + \tilde{R} \right)$$
$$= \epsilon \frac{t^2}{2}.$$

Hence  $2f(t)/t^2 \ge \epsilon > 0$ , where  $t \in [a_{j+1}, a_j)$ . Since this holds for almost any  $j \in \mathbb{N}$  and for all  $t \in [a_{j+1}, a_j)$ , we have for any  $\delta > 0$  sufficiently small,

$$\inf\left\{2\frac{f(t)}{t^2}:t\in(0,\delta)\right\}\geq\epsilon>0.$$

Hence  $\liminf_{t\downarrow 0} 2f(t)/t^2 \ge \epsilon > 0$ .

Now, let us suppose that X is an arbitrary infinite-dimensional space,  $A_n$  is a nonempty subset of  $S_X$  for every  $n \in \mathbb{N}$ , and

$$\bigcup_{n=1}^{+\infty} A_n = S_X$$

Let us define the function  $g : X \to \mathbb{R}$  by the following way.

$$g(th) = nf(t), \quad \forall n \in \mathbb{N}, \forall h \in A_n, \forall t \in \mathbb{R}.$$

It follows immediately from the construction of f that

 $g^{\ell}(0; h) = f^{\ell}(0; 1) = 0, \quad \forall h \in S_X,$ 

and for every  $h \in A_n$ ,  $n \in \mathbb{N}$ , we have

$$g_{p}^{\prime\ell}(0;h) \geq n\varepsilon \geq \varepsilon.$$

Moreover, since g is defined by means of f in every direction, we have that  $\underline{g}_{p}^{\ell}(0; h)$  is Fréchet. Therefore, using Theorem 3, we obtain that 0 is an isolated minimizer for g.

We notice that it follows from the construction of  $\varphi$  and definition of f and g that the function g is not convex. Further, considering arbitrary  $h_1 \in A_1$ , we have

$$g(th_1)>0, \quad \forall t>0,$$

and

$$g(th_n) = ng(th_1),$$

for every  $h_n \in A_n$ ,  $n \in \mathbb{N}$ . Thus, the function g is not continuous.

#### Acknowledgement

The second author was supported by the Council of Czech Government (MSM 6198959214).

### References

- [1] A. Ben-Tal, J. Zowe, Necessary and sufficient optimality conditions for a class of nonsmooth minimization problems, Math. Program. 24 (1982) 70-91.
- [2] R. Cominetti, R. Correa. A generalized second-order derivative in nonsmooth optimization. SIAM J. Control Optim. 28 (1990) 789-809.
- [3] W.L. Chan, L.R. Huang, K.F. Ng, On generalized second-order derivatives and Taylor expansions in nonsmooth optimization, SIAM J. Control Optim. 32 (1994) 591-611.
- [4] P.G. Georgiev, N.P. Zlateva, Second-order subdifferentials of C<sup>1,1</sup> functions and optimality conditions, Set-Valued Anal. 4 (1996) 101–117
- J.B. Hiriart–Urruty, J.J. Strodiot, V.H. Nguyen, Generalized Hessian matrix and second-order optimality conditions for problems with C<sup>1,1</sup> data, Appl. [5] Math. Optim. 11 (1984) 43–56.
- [6] H. Kawasaki, An envelope-like effect of infinite many inequality constraints on second-order necessary conditions for minimization problems, Math. Program. 41 (1988) 73-96.
- [7] D. Klatte, Upper Lipschitz behavior of solutions to perturbed C<sup>1,1</sup> programs, Math. Program. (Ser. B) 88 (2000) 285–311.
   [8] L. Qi, Superlinearly convergent approximate Newton methods for LC<sup>1</sup> optimization problem, Math. Program. 64 (1994) 277–294.
- [9] R.T. Rockafellar, Second-order optimality conditions in nonlinear programming obtained by way of epi-derivatives, Math. Oper. Res. 14 (1989) 462-484
- [10] R.T. Rockafellar, J.B. Wets, Variational Analysis, Springer-Verlag, New York, 1998.
- [11] D.L. Torre, M. Rocca, Remarks on second order generalized derivatives for differentiable functions with Lipschitzian jacobian, Appl. Math. E-Notes 3 (2003) 130-137.
- [12] X.Q. Yang, On second-order directional derivatives, Nonlinear Anal. 26 (1996) 55–66.
- [13] X.Q. Yang, On relations and applications of generalized second-order directional derivatives, Nonlinear Anal. 36 (1999) 595-614.
- 14] D. Bednařík, K. Pastor, On second-order conditions in unconstrained optimization, Math. Program. 113 (2008) 283–298.
- [15] D. Bednařík, K. Pastor,  $\ell$ -stable functions are continuous, Nonlinear Anal. 70 (2009) 2317–2324.
- 16] D. Bednařík, K. Pastor, Differentiability properties of functions that are  $\ell$ -stable at a point, Nonlinear Anal. 69 (2008) 3128–3135.
- [17] A. Ben-Tal, J. Zowe, Directional derivatives in nonsmooth optimization, J. Optim. Theory Appl. 47 (1985) 483-490.
- [18] D. Bednařík, K. Pastor, Elimination of strict convergence in optimization, SIAM J. Control Optim. 43 (3) (2004) 1063-1077.
- [19] I. Ginchev, A. Guerraggio, M. Rocca, From scalar to vector optimization, Appl. Math. 51 (2006) 5–36.
- [20] L.R. Huang, K.F. Ng, Second-order necessary and sufficient conditions in nonsmooth optimization, Math. Program. 66 (1994) 379-402.
- [21] R.W. Chaney, Second-order sufficient conditions in nonsmooth optimization, Math. Oper. Res. 13 (1988) 660-673.
- [22] A. Ben-Tal, J. Zowe, Directional derivatives in nonsmooth optimization, J. Optim. Theory Appl. 47 (1985) 483-490.
- [23] K. Pastor, Fréchet approach to generalized second-order differentiability, Studia Sci. Math. Hungar. 45 (3) (2008) 333-352.
- [24] I. Ginchev, A. Guerraggio, M. Rocca, Second order conditions for C<sup>1,1</sup> constrained vector optimization, Math. Program. (Ser. B) 104 (2005) 389–405.
   [25] P.Q. Khanh, N.D. Tuan, Optimality conditions for nonsmooth multiobjective optimization using Hadamard directional derivatives, J. Optim. Theory Appl. 133 (2007) 341-357.
- [26] I. Ginchev, Higher order optimality conditions in nonsmooth optimization, Optimization 51 (1) (2002) 47–72.
- [27] B. Jiménez, V. Novo, First order optimality conditions in vector optimization involving stable functions, Optimization 57 (2008) 449-471.
- [28] V. Jevakumar, D.T. Luc, Nonsmooth Vector Functions and Continuous Optimization, Springer, Berlin, 2008.
- [29] B.S. Mordukhovich, Variational Analysis and Generalized Differentiation I: Basic Theory II: Applications, Springer, Berlin, 2006.