# Continuation and Surjectivity Theorems for Uniform Limits of A-proper Mappings with Applications 

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## Introduction

In [19] the authors established several continuation theorems and studied the approximation-solvability of operator equations involving multivalued $A$-proper mappings. In this paper we continue our study of the solvability of equations involving the uniform limits of multivalued $A$-proper mappings and their perturbations.

In Section 1 we state the basic definitions and some of the preliminaries to be used in subsequent sections. For more details the reader should consult [20].

In Section 2 we establish two continuation theorems and some surjectivity results for uniform limits of $A$-proper mappings under various growth conditions. The proofs of some theorems in this section are based on our results in [19]. All the results of this section except Theorem 2.4 and a version of Theorem 2.6 are new also in the single-valued case.

Section 3 deals with some special classes of uniform limits of $A$-proper mappings. In the first part of this section we introduce various classes of multivalued $A$-proper mappings involving quasi- $K$-monotone, generalized pseudo-$K$-monotone, and $K$-semibounded mappings. In the second part of this section we use the theorems of Section 2 to deduce various surjectivity results for the above mentioned mappings and their perturbations. As special cases we deduce from our results (for separable spaces) certain surjectivity results of Browder, Browder and Hess, Hess, Fitzpatrick, Petryshyn, Petryshyn and Fitzpatrick, Rockafellar, Wille, and others.

In Section 4 we apply some of our results (Theorems 2.4, 2.6, and 3.5) to the variational solvability of elliptic boundary value problems involving completely continuous perturbations of operators with semibounded variation. Our surjectivity results extend some of those obtained earlier by Browder, Dubinsky and others (see Sects. 3 and 4 for detailed historical comments). As our second

[^0]application we treat a boundary value problem involving nonlinear ordinary differential operators of order $m>1$ satisfying general homogeneous boundary conditions. The interesting feature of this example is that it involves mappings acting between two different spaces and thus surjectivity results of the other authors are not directly applicable in this case. Furthermore our growth conditions are weaker than those used by other authors for operators acting from a Banach space to its dual space.

## 1. Basic Definitions and Preliminaries

Let $\left\{E_{n}\right\}$ and $\left\{F_{n}\right\}$ be two sequences of oriented finite-dimensional spaces and let $\left\{V_{n}\right\}$ and $\left\{W_{n}\right\}$ be two sequences of continuous linear mappings with $V_{n}$ mapping $E_{n}$ into $X$ and $W_{n}$ mapping $Y$ onto $F_{n}$, where $X$ and $Y$ are real normed linear spaces.

Remark 1.1. For the sake of notational simplicity we use the same symbol $\left\|\|\right.$ to denote the norm in the respective space $X, Y, E_{n}$, and $F_{n}$, and from the context it will be clear which norm is meant. We also use the symbols " $\rightarrow$ " and"-"" to denote strong and weak convergence, respectively.

Definition 1.1. A quadruple of sequences $\Gamma=\left\{E_{n}, V_{n} ; F_{n}, W_{n}\right\}$ is said to be an admissible scheme for $(X, Y)$ if $\operatorname{dim} E_{n}=\operatorname{dim} F_{n}$ for each $n, V_{n}$ is injective, $\operatorname{dist}\left(x, V_{n} E_{n}\right) \rightarrow 0$ as $n \rightarrow \infty$ for each $x$ in $X$, and $\left\{W_{n}\right\}$ is uniformly bounded.

Note that in Definition 1.1 we do not require that $E_{n}$ and $F_{n}$ be subspaces of $X$ and $Y$, respectively, nor that $V_{n}$ and $W_{n}$ be linear projections. The following examples of admissible shcemes (for others see [21]), which we subscript for further references, will be used in this paper. For the present we shall assume that $\left\{X_{n}\right\}$ is a sequence of oriented finite-dimensional subspaces of $X$ such that $\operatorname{dist}\left(x, X_{n}\right) \rightarrow 0$ as $n \rightarrow \infty$ for each $x$ in $X$, and let $V_{n}$ be an inclusion map of $X_{n}$ into $X$.
(a) Let $\left\{Y_{n}\right\}$ be a sequence of finite-dimensional oriented subspaces of $Y$ such that $\operatorname{dim} Y_{n}=\operatorname{dim} X_{n}$ and let $Q_{n}$ be a continuous linear map of $Y$ onto $Y_{n}$ such that $\left\|Q_{n}\right\| \leqslant M$ for all $n$ and some $M>0$. Then $\Gamma_{a}=\left\{X_{n}, V_{n} ; Y_{n}, Q_{n}\right\}$ is admissible for $(X, Y)$.
(b) If $Y=X, Y_{n}=X_{n}$ and $W_{n}=P_{n}$, where $P_{n}$ is a projection of $X$ onto $X_{n}$ such that $P_{n}(x) \rightarrow x$ for each $x$ in $X$ and $\left\|P_{n}\right\| \leqslant M$ for all $n$, then $\Gamma_{b}=\left\{X_{n}, V_{n} ; X_{n}, P_{n}\right\}$ is an admissible projection scheme for ( $X, X$ ). Note that when $X$ is complete, then the assumption that $\left\|P_{n}\right\| \leqslant M$ is superfluous.
(c) If $Y=X^{*}, Y_{n}=X^{*}$ and $W_{n}=V_{n}^{*}$, then $\Gamma_{r}=\left\{X_{n}, V_{n} ; X_{n}^{*}\right.$, $\left.V^{*}{ }_{n}\right\}$ is an admissible injective shceme for $\left(X, X^{*}\right)$.

We add that $\Gamma_{c}$ always exists when $X$ is separable. Let $D$ be a given set in $X$, $D_{n} \equiv V_{n}^{-1}(D), T: D \rightarrow 2^{Y}$ and $\left.T_{n} \equiv W_{n} T V_{n}\right|_{D_{n}}: D_{n} \rightarrow 2^{F_{n}}$. For what follows we shall need the following basic definition.

Definition 1.2. A multivalued mapping $T: D \subset X \rightarrow 2^{Y}$ is said to be $A$-proper w.r.t. $\Gamma=\left\{E_{n}, V_{n} ; F_{n}, W_{n}\right\}$ if $T_{n}: D_{n} \rightarrow 2^{F_{n}}$ is upper semicontinuous for each $n$ and if for any sequence $\left\{u_{n_{j}} \mid u_{n_{j}} \in D_{n_{j}}\right\}$ such that $\left\{V_{n_{j}}^{\prime}\left(u_{n_{j}}\right)\right\}$ is bounded in $X$ and $\left\|W_{n_{j}}\left(y_{n_{j}}\right)-W_{n_{j}}(y)\right\| \rightarrow 0$ as $j \rightarrow \infty$ for some $y_{n_{j}} \in T V_{n_{j}}\left(u_{n_{j}}\right)$ and $y \in Y$, there exist a subsequence $\left\{u_{n_{j(k)}}\right\}$ and $x_{0} \in D$ such that $V_{n_{j(k)}}\left(u_{n_{j(k)}}\right) \rightarrow x_{0}$ and $y \in T\left(x_{0}\right)$.

Remark 1.2. The class of single-valued $A$-proper mappings, whose study was initiated by Petryshyn, has been investigated by many authors (see [20] for the survey). The theory of $A$-proper mappings proved to be useful in the constructive solvability for abstract and differential equations. It provided the unification and the extension of various results from the theory of operators of monotone, condensing, and $P$-compact type. Multivalued $A$-proper mappings have been first studied extensively by Milojević [17, 18] and subsequently by Milojevic and Petryshyn [19]. For various examples of $A$-proper single-valued and multivalued $A$-proper mappings see [20, 17, 19].

The purpose of this paper is to continue the study initiated by the authors in [19]. Our particular interest is the study of the solvability of equations involving operators which are uniform limits of $A$-proper mappings. The theory presented here unifies and extends a number of results obtained by other authors for various special classes of mappings such as mappings of monotone type, condensing, $P$-compact and others.

In what follows $K(X), B K(X)$, and $C K(X)$ will denote the families of nonempty closed and convex, nonempty bounded closed and convex, and nonempty compact and convex subsets of $X$, respectively.

## 2. Continuation and Surjectivity Results

In this section we shall consider the solvability of a larger class of operator equations than that considered in the paper [19]. Namely, for a given $T_{t}: X \rightarrow 2^{Y}$, $t \in[0,1]$, we shall consider the solvability of equations of type $f \in T_{1}(x)$, where $T_{t}$ is not $A$-proper for $t \in[0,1]$, but is the uniform limit of multivalued $A$-proper mappings, i.e., $T_{t}$ is such that $T_{t, \mu}=T_{t}+\mu G$ is $A$-proper for each $\mu>0$ and $t \in[0,1]$ and some given multivalued mapping $G$. We then apply these results to the solvability of equations of the form $f \in T(x)$ with $T$ being a uniform limit of $A$-proper mappings. Examples of such mappings will be given in Section 3. The solvability of the perturbed equations, i.e., of $f \in T(x)+A(x)$ is also considered. Unlike the results of [19], those obtained here will be only of the existence type.

In what follows we shall say that a mapping $T: Y \rightarrow 2^{Y}$ satisfies condition $(+)$ if $\left\{x_{n}\right\}$ is any sequence and $u_{n} \rightarrow g$ in $Y$ for some $u_{n} \in T\left(x_{n}\right)$, then $\left\{x_{n}\right\}$ is bounded. $T$ is said to satisfy condition $(++)$ if $\left\{x_{n}\right\} \subset X$ is any bounded sequence such that whenever $u_{n} \rightarrow g$ in $Y$ for some $u_{n} \in T\left(x_{n}\right)$ then there exists $x \in X$ such that $g \in T(x)$.

Theorem 2.1. Let $X$ and $Y$ be normed spaces with an admissible scheme $\Gamma$ and let $T_{t}(\cdot) \equiv T(t, \cdot) \operatorname{map}[0,1] \times X \rightarrow 2^{Y}$ with $W_{n} T_{t}(x) \in C K\left(F_{n}\right)$. Suppose there exists a bounded mapping $G: X \rightarrow 2^{Y}$ with $W_{n} G(x) \in C K\left(F_{n}\right)$ for each $x \in X$ and that $T_{t}+\mu G$ is $A$-proper w.r.t. $\Gamma$ for each $t \in[0,1], \mu>0$. Suppose that for each $f \in Y$ there exists $r_{f}>0$ such that the following hypotheses hold:
(H1) There exists $\gamma>0$ such that $\|f-y\|>\gamma$ for all $y \in T_{t}(x)$ with $x \in \partial B\left(0, r_{f}\right)$ and $t \in[0,1]$.
(H2) $\|s f-y\|>\gamma$ for all $y \in T_{0}(x)$ with $x \in \partial B\left(0, r_{f}\right)$ and $s \in[0,1]$.
(H3) If for some $\mu>0, t_{n} \in[0,1]$ and $u_{n} \in \partial B_{n}\left(0, r_{f}\right)=\partial V_{n}^{-1}\left(B\left(0, r_{f}\right)\right)$ we have $W_{n}(f) \in W_{n} T_{t_{n}} V_{n}\left(u_{n}\right)+\mu W_{n} G V_{n}\left(u_{n}\right)$, then there exists a subsequence $\left\{t_{n_{k}}\right\}$ converging to $t$ such that $\left\|W_{n_{k}}(f)-W_{n_{k}}\left(y_{n_{k}}\right)-\mu W_{n_{k}}\left(z_{n_{k}}\right)\right\| \rightarrow 0$ as $k \rightarrow \infty$ for some $y_{n_{k}} \in T_{t} V_{n_{k}}\left(u_{n_{k}}\right)$ and $z_{n_{k}} \in G V_{n_{k}}\left(u_{n_{k}}\right)$.
(H4) There exists $n_{0} \geqslant 1$ such that for each $n \geqslant n_{0}, \mu>0$, $\operatorname{deg}\left(L_{n} W_{n} T_{0} V_{n}+\mu L_{n} W_{n} G V_{n}, B_{n}\left(0, r_{f}\right), 0\right\} \neq 0$, where $L_{n}$ is some linear isomorphism between $F_{n}$ and $E_{n}$.

Then, if $T_{1}$ satisfies condition $(++)$, the equation $f \in T_{1}(x)$ is solvable for each $f \in Y$.

Proof. Let $f \in Y$ be fixed. Since $G$ is bounded, there exists $\mu_{0}>0$ such that for each $\mu \in\left(0, \mu_{0}\right)$ we have

$$
\|f-y-\mu z\|>\gamma / 2 \quad \text { for all } y \in T_{t}(x), \quad z \in G(x)
$$

with

$$
x \in \partial B\left(0, r_{f}\right), \quad t \in[0,1]
$$

and

$$
\|s f-y-\mu z\|>\gamma / 2 \quad \text { for all } y \subset T_{0}(x), \quad z \subset G(x)
$$

with

$$
\begin{equation*}
x \in \partial B\left(0, r_{f}\right) \quad \text { and } \quad s \in[0,1] \tag{2.2}
\end{equation*}
$$

Let $\mu \in\left(0, \mu_{0}\right)$ be fixed. Then we claim now that there exists $n_{1}$ such that

$$
\begin{gather*}
W_{n}(f) \notin W_{n} T_{t} V_{n}(u)+\mu W_{n} G V_{n}(u) \quad \text { for all } n \geqslant n_{1},  \tag{2.3}\\
t \in[0,1] \quad \text { and } \quad u \in \partial B_{n}\left(0, r_{f}\right) .
\end{gather*}
$$

If not, then there exist $t_{n} \in[0,1]$ and $u_{n} \in \partial B_{n}\left(0, r_{f}\right)$ such that $W_{n}(f) \in$ $W_{n} T_{t_{n}} V_{n}\left(u_{n}\right)+\mu W_{n} G V_{n}\left(u_{n}\right)$ for infinitely many $n$. By hypothesis (H3), there
exists $\left\{t_{n_{k}}\right\}$ converging to $t$ with $\left\|W_{n_{k}}(f)-W_{n_{k}}\left(y_{n_{k}}\right)-\mu W_{n_{k}}\left(z_{n_{k}}\right)\right\| \rightarrow 0$ as $k \rightarrow \infty$ for some $y_{n_{k}} \in T_{t} V_{n_{k}}\left(u_{n_{k}}\right)$ and $z_{n_{k}} \in G V_{n_{k}}\left(u_{n_{k}}\right)$. By the $A$-properness of $T_{t}+\mu G$ w.r.t. $\Gamma$, there exists $\left\{u_{n_{k(i)}}\right\}$ such that $V_{n_{k(i)}}\left(u_{n_{k(i)}}\right) \rightarrow x \in X$ and $f \in T_{t}(x)+\mu G(x)$ with $\|x\|=r_{f}$, in contradiction to (2.1). Thus, there exists $n_{1}$ such that (2.3) holds for each $n \geqslant n_{1}$.

Next, there exists an $n_{2} \geqslant 1$ such that for each $n \geqslant n_{2}$
$s W_{n}(f) \notin W_{n} T_{0} V_{n}(u)+\mu W_{n} G V_{n}(u) \quad$ for all $s \in[0,1] \quad$ and $\quad u \in \partial B_{n}\left(0, r_{f}\right)$.

If not, there exist $s_{n} \in[0,1]$ and $u_{n} \in \partial B_{n}\left(0, r_{f}\right)$ such that $s_{n} W_{n}(f) \in$ $W_{n} T_{0} V_{n}\left(u_{n}\right)+\mu W_{n} G V_{n}\left(u_{n}\right)$ for infinitely many $n$. Let $y_{n} \in T_{0} V_{n}\left(u_{n}\right)$ and $z_{n} \in G V_{n}\left(u_{n}\right)$ be such that $s_{n} W_{n}(f)=W_{n}\left(y_{n}\right)+\mu W_{n}\left(z_{n}\right)$. We may assume that $s_{n} \rightarrow s$. Then

$$
\begin{aligned}
& \left\|W_{n}\left(y_{n}\right)+\mu W_{n}\left(z_{n}\right)-W_{n}(s f)\right\| \\
& \quad=\left\|W_{n}\left(s_{n} f\right)-W_{n}(s f)\right\| \leqslant\left\|W_{n}\right\| \cdot\|f\| \cdot\left|s_{n}-s\right| \rightarrow 0
\end{aligned}
$$

as $n \rightarrow \infty$ by the uniform boundedness of $\left\{W_{n}\right\}$. Consequently, by the $A$-properness of $T_{0}+\mu G$, there exists $\left\{u_{n_{k(i)}}\right\}$ such that $V_{n_{k(i)}}\left(u_{n_{k(i)}}\right) \rightarrow x \in X$ with $s f \in T_{0}(x)+\mu G(x)$, with $\|x\|=r_{f}$, in contradiction to (2.2). Thus, (2.4) holds. Let $N_{f}=\max \left\{n_{0}, n_{1}, n_{2}\right\}$. Then, for each $n \geqslant N_{f}$ relations (2.3), (2.4), and hypothesis (H4) hold. Hence, by Theorem 1.2 in [19], for each $\mu \in\left(0, \mu_{0}\right)$ there exists $x_{\mu} \in B\left(0, r_{f}\right)$ such that $f \in T_{1}(x)+\mu G(x)$. Let $\mu_{n} \in\left(0, \mu_{0}\right)$ be such that $\mu_{n} \rightarrow 0$ as $n \rightarrow \infty$ and let $x_{\mu_{n}} \equiv x_{n} \in X$ be such that $f \in T_{1}\left(x_{n}\right)+\mu_{n} G\left(x_{n}\right)$, or $f=y_{n}+\mu_{n} z_{n}$ for some $y_{n} \in T_{1}\left(x_{n}\right)$ and $z_{n} \in G\left(x_{n}\right)$. By the boundedness of $G$, $y_{n}=f-\mu_{n} z_{n} \rightarrow f$ which by condition $(++)$ implies the existence of $x \in X$ such that $f \in T_{1}(x)$.
Q.E.D.

The following lemma gives some conditions which imply (H1)-(H3).
Lemma 2.1. Suppose that $T_{t}(x)$ is bounded and closed for all $t \in[0,1]$, $x \in X$ and that
(1) $f \notin \overline{T_{t}\left(\partial B\left(0, r_{f}\right)\right)}$ for all $t \in[0,1]$,
(2) $\left.s f \notin \overline{T_{0}\left(\partial B\left(0, r_{f}\right)\right.}\right)$ for all $s \in[0,1]$.

Then, if $\alpha\left(T_{t_{n}}(x), T_{t}(x)\right)=\sup _{\nu \in T_{t_{n}}(x)} d\left(y, T_{t}(x)\right) \rightarrow 0$ uniformly with respect to $x$ in bounded sets when $t_{n} \rightarrow t$, hypotheses ( H 1 ), ( H 2 ) hold. If, additionally, $W_{n} T_{t}(x)$ is compact for all $n, t \in[0,1]$ and $x \in X$, then hypothesis (H3) also holds.

Proof. Let $t_{0} \in[0,1]$ be fixed. Then there exists $\gamma\left(t_{0}\right)>0$ such that $\|f-y\|>\gamma\left(t_{0}\right)$ for all $y \in T_{t_{0}}(x), x \in \partial B\left(0, r_{f}\right)$. Let $\Delta\left(t_{0}\right)$ be an interval around $t_{0}$ such that for $t \in \Delta\left(t_{0}\right), \alpha\left(T_{t}(x), T_{t_{0}}(x)\right) \leqslant \gamma\left(t_{0}\right) / 3$. For each $x \in \partial B\left(0, r_{f}\right)$ and $y \in T_{t}(x), t \in \Delta\left(t_{0}\right)$, let $y_{0} \in T_{t_{0}}(x)$ be such that $\left\|y-y_{0}\right\| \leqslant 2 \gamma\left(t_{0}\right) / 3$. Then $\|f-y\| \geqslant\left\|f-y_{0}\right\|-\left\|y-y_{0}\right\| \geqslant \gamma\left(t_{0}\right) / 3$. Since [0, 1] can be covered by a
finite number of such intervals, we have that there exists $\gamma_{1}>0$ such that $\|f-y\| \geqslant \gamma_{1}$ for all $y \in T_{t}(x)$ with $\|x\|=r_{f}$ and $t \in[0,1]$.

Now define $A=\{s f \mid s \in[0,1]\}$ and $B=\overline{T_{0}\left(\partial B\left(0, r_{f}\right)\right)}$. Since $A$ is compact, $B$ closed and $A \cap B=\phi$, it follows that there exists $\gamma_{2}>0$ such that sf-y\|> $\gamma_{2}$ for all $s \in[0,1]$ and $y \in T_{0}\left(\partial B\left(0, r_{f}\right)\right)$. Then $\gamma==\min \left\{\gamma_{1}, \gamma_{2}\right\}$ is such that hypotheses (H1) and (H2) hold.

Suppose now that for some $\mu>0, t_{n} \in[0,1]$ and $u_{n} \in \partial B_{n}\left(0, r_{f}\right), W_{n}(f) \in$ $W_{n} T_{t_{n}} V_{n}\left(u_{n}\right)+\mu W_{n} G V_{n}\left(u_{n}\right)$. Then for some subsequence we have $t_{n_{k}} \geqslant t$. By the compactness of $W_{n} T_{t}(x)$, for each $z_{n_{k}} \in T_{t_{n_{k}}} V_{n_{k}}\left(u_{n_{k}}\right)$, there exists $y_{n_{k}} \in T_{t} V_{n_{k}}\left(u_{n_{k}}\right)$ such that

$$
W_{n_{k}}\left(z_{n_{k}}\right)-W_{n_{k}}\left(y_{n_{k}}\right)!=d\left(W_{n_{k}}\left(z_{n_{k}}\right), W_{n_{k}} T_{t} V_{n_{k}}\left(u_{n_{k}}\right)\right)
$$

This implies that

$$
\begin{aligned}
& W_{n_{k}}\left(z_{n_{k}}\right)-W_{n_{k}}\left(y_{n_{k}}\right) \\
& \quad \leqslant \alpha\left(W_{n_{k}} T_{t_{n_{k}}} V_{n_{k}}\left(u_{n_{k}}\right), W_{n_{k}} T_{t} V_{n_{k}}\left(u_{n_{k}}\right)\right) \\
& \quad \leqslant\left\|W_{n_{k}}\right\| \alpha\left(T_{t_{n_{k}}} V_{n_{k}}\left(u_{n_{k}}\right), T_{t} V_{n_{k}}\left(u_{n_{k}}\right)\right) \rightarrow 0 \quad \text { as } \quad k \rightarrow \infty
\end{aligned}
$$

Since $W_{n_{k}}(f)=W_{n_{k}}\left(z_{n_{k}}\right)+\mu W_{n_{k}}\left(\bar{z}_{n_{k}}\right)$ for some $z_{n_{k}} \in T_{t_{n_{k}}} V_{n_{k}}\left(u_{n_{k}}\right)$ and $\bar{z}_{n_{k}} \in$ $G V_{n_{k}}\left(u_{n_{k}}\right)$, it follows for $\left\{y_{n_{k}}\right\}$ above chosen with respect to $\left\{z_{n_{k}}\right\}$ that

$$
\left\|W_{n_{k}}(f)-W_{n_{k}}\left(y_{n_{k}}\right)-\mu W_{n_{k}}\left(\bar{z}_{n_{k}}\right)\right\|=\left\|W_{n}\left(z_{n_{k}}\right)-W_{n_{k}}\left(y_{n_{k}}\right)\right\| \rightarrow 0
$$

$$
\text { as } \quad k \rightarrow \infty
$$

Thus hypothesis (H3) holds.
Q.E.D.

Remark 2.1. It is easy to see that hypotheses (H1) and (H2) hold if $T_{t}$ satisfies condition $(+)$ uniformly with respect to $t \in[0,1]$.

Analyzing the proof of Theorem 2.1 we see that all we need for the solvability of $f \in T_{1}(x)$ is that relations (2.3) and (2.4) and hypothesis (H4) hold. So we have the following more general form of Theorem 2.1.

Theorem 2.2. Let $X, Y$ be normed spaces with an admissible scheme $\Gamma$, $T:[0,1] \times X \rightarrow 2^{Y}$ with $T_{n}:[0,1] \times E_{n} \rightarrow C K\left(F_{n}\right)$ u.s.c. and $G: X \rightarrow 2^{Y}$ a bounded mapping with $W_{n} T_{t}(x), W_{n} G(x) \in C K\left(F_{n}\right)$ and that for $\mu>0, T_{1}+\mu G$ is A-proper w.r.t. $\Gamma$. Suppose that for each $f \in Y$ there exist $r_{f}>0$ and $n_{0} \geqslant 1$ such that for each $n \geqslant n_{0}$ and $\mu \in\left(0, \mu_{0}\right)$ for some $\mu_{0}>0$ we have
$\left(\mathrm{H} 1^{\prime}\right) \quad W_{n}(f) \notin W_{n} T_{t} V_{n}(u)+\mu W_{n} G V_{n}(u)$ for $t \in[0,1], u \in \partial B_{n}\left(0, r_{f}\right)$
$\left(\mathrm{H} 2^{\prime}\right) \quad s W_{n}(f) \notin W_{n} T_{0} V_{n}(u)+\mu W_{n} G V_{n}(u)$ for $s \in[0,1], u \in \hat{c} B_{n}\left(0, r_{f}\right)$.
and hypothesis (H4) holds.

Then, if $T_{1}$ satisfies condition $(++)$, the equation $f \in T_{1}(x)$ is solvable for each $f \in Y$.

For the solvability of the equation $f \in T_{1}(x)+A(x)$ we have the following:

Theorem 2.3. Let $X$ and $Y$ be normed spaces with an admissible scheme $\Gamma$ and $T_{t}(\cdot)=T(t, \cdot) \operatorname{map}[0,1] \times X \rightarrow 2^{Y}$ with $W_{n} T_{t}(x) \in C K\left(F_{n}\right)$ for all $(t, x) \in[0,1] \times X$. Suppose that $T_{t}(x)$ is $\alpha$-continuous in $t$ uniformly with respect to $x$ in bounded subsets of $X$. Suppose that $A, G: X \rightarrow 2^{F}$ with $W_{n} A(x), W_{n} G(x) \in$ $C K\left(F_{n}\right), G$ is bounded, and that for each $\mu>0, T_{t}+A+\mu G$ is $A$-proper w.r.t. $\Gamma$ for each $t \in[0,1]$. Suppose also that either for each $f \in Y$ there exists $r_{f}>0$ such that:
(1) $f \notin \overline{\left(T_{t}+A\right)\left(\partial B\left(0, r_{f}\right)\right)}$ for all $t \in[0,1]$
(2) $s f \notin \overline{\left(T_{0}+A\right)\left(\partial B\left(0, r_{f}\right)\right)}$ for $s \in[0,1]$
or that $T_{t}$ satisfies condition $(+)$ uniformly w.r.t. $t \in[0,1]$.
(3) There exists $n_{0} \geqslant 1$ such that for each $n \geqslant n_{0}, \mu>0, \operatorname{deg}\left(L_{n} W_{n} T_{0} V_{n}+\right.$ $\left.L_{n} W_{n} A V_{n}+\mu L_{n} W_{n} G V_{n}, B_{n}\left(0, r_{f}\right), 0\right) \neq 0$, where $L_{n}$ is some linear isomorphism between $F_{n}$ and $E_{\eta}$.

Then, if $T_{1}+A$ satisfies condition $(++)$, the equation $f \in T_{1}(x)+A(x)$ is solvable for each $f \in Y$.

Proof. Let $f \in Y$ be fixed. Since $\alpha\left(T_{t}(x)+A(x), T_{t_{0}}(x)+A(x)\right) \leqslant \alpha\left(T_{t}(x)\right.$, $T_{t_{0}}(x)$ ), it follows that $T_{t}(x)+A(x)$ is $\alpha$-continuous in $t$ uniformly with respect to $x$ in bounded subsets of $X$, i.e., whenever $t_{n} \rightarrow t$, then $\alpha\left(T_{t_{n}}(x)+A(x)\right.$, $\left.T_{t}(x)+A(x)\right) \rightarrow 0$ as $n \rightarrow \infty$ uniformly for $x$ in bounded subsets of $X$. By Lemma 2.1, we see that hypotheses (H1), (H2), and (H3) of Theorem 2.1 hold for $T_{t}+A, T_{0}+A$, and $T_{t}+A+\mu G$, respectively. In view of this and our assumption (3), there exists $\mu_{0}>0$ such that for each $\mu \in\left(0, \mu_{0}\right)$, the equation, $f \in T_{1}(x)+A(x)+\mu G(x)$ is solvable in $\bar{B}\left(0, r_{f}\right)$. Since $T_{1}+A$ satisfies condition $(++)$ and $G$ is bounded, we have that, as in Theorem 2.1, the equation $f \in T_{1}(x)+A(x)$ is solvable for each $f \in Y$.
Q.E.D.

Let us now discuss conditions that imply hypothesis (H4). It is clear that if $T_{0}$ and $G$ and $T_{0}, A$ and $G$ in Theorems 2.1 and 2.3 , respectively, are odd, then hypothesis (H4) and condition (3) hold, respectively. Moreover, if $K, K_{n}$, and $M_{n}$ satisfy conditions of Proposition 1.2 in [19], $G$ and $K$, and $T_{0}$ and $K$ satisfy condition (C3) of that proposition, then one can show that hypothesis ( H 4 ) holds. Similarly, one imposes conditions on $T_{0}, A$ and $G$ in Theorem 2.3 which imply the validity of its condition (3).

Remark 2.2 We add in passing that condition $(+)$ is implied by any one of the following conditions which have been used by many authors (see [19]) in
their study of the equation $f \in T(x)$ with $T$ either single-valued or multivalued mapping of monotone, ball-condensing and $A$-proper type:

Condition $(1+) . \quad(y, v) /\|v\| \rightarrow \infty$ as $\|x\| \rightarrow \infty$ for all $y \in T(x)$ and $v \in K(x)$ (i.e., $T$ is $K$-coercive).

Condition $(2+)$. For each unbounded sequence $\left\{x_{n}\right\} \subset X,\left|y_{n}\right| \rightarrow \infty$ as $n \rightarrow \infty$ for all $y_{n} \in T\left(x_{n}\right)$ (i.e., $T$ is norm-coercive).

Condition $(3+)$. For each $y_{n} \in T\left(x_{n}\right)$ and $z_{n} \in K\left(x_{n}\right), \quad y_{n}$ $\left(\left(y_{n}, v_{n}\right) /\left\|v_{n}\right\|\right) \rightarrow \infty$ as $\left\|x_{n}\right\| \rightarrow \infty$.

Condition $(4+) . \quad 0 \notin \overline{T(\partial B(0, r))}$ and $T(t x)=t^{\alpha} T(x)$ for all $\|x\| \geq r, t>1$ and some $\alpha>0$.

The following result on the solvability of $f \in T(x)$, where $T$ is a uniform limit of $A$-proper mappings, i.e., $T$ is such that $T+\mu G$ is $A$-proper for each $\mu>0$ and some mapping $G$, can be obtained either from Theorem 2.3 or Theorems 6.4 and 7.2 in [17]. We shall prove it by applying Theorems 6.4 and 7.2 in [17] since the argument is shorter.

Theorem 2.4. Let $X, Y$ be normed spaces with an admissible scheme $\Gamma$. Suppose that $T: X \rightarrow 2^{Y}$ satisfies conditions $(+)$ and $(++)$ with $W_{n} T V_{n}: E_{n} \rightarrow$ $C K\left(F_{n}\right)$ u.s.c. for each $n$ and that $G: X \rightarrow 2^{Y}$ is bounded, $W_{n} G(x) \in C K\left(F_{n}\right)$ and $T_{u}=T+\mu G$ is $A$-proper w.r.t. $\Gamma$ for each $\mu>0$.

Suppose further that either one of the following conditions holds:
(i) There is $r_{0}>0$ such that $T$ and $G$ are odd on $X \backslash B\left(0, r_{0}\right)$.
(ii) There exist $K: X \rightarrow 2^{Y^{*}}, K_{n}: E_{n} \rightarrow 2^{F_{n}{ }^{*}}$, and a linear isomorphism $M_{n}$ of $E_{n}$ onto $F_{n}$ such that $0 \in K(x)$ implies $x=0$ and that
(C1) for each $n$ and $u \in E_{n}, v \in K V_{n}(u)$ there exists $w \in K_{n}(u)$ such that $(g, v)=\left(W_{n} g, w\right)$ for all $g \in Y$;
(C2) for each $n,\left(M_{n} u, w\right)>0$ for all $w \in K_{n}(u)$ and $u \neq 0$ in $E_{n}$;
(C3) there exists $r_{0}>0$ such that $(u, v) \geqslant 0$ and $(w, v) \geqslant 0$ for all $u \in T(x), w \in G(x)$ and $v \in K(x)$ with $\|x\| \geqslant r_{0}$.

Then the equation $f \in T(x)$ is solvable for each $f \in Y$.
Proof. Let $f \in Y$ be fixed. We have noted in Remark 2.1 that condition ( + ) implies the existence of $r \geqslant r_{0}$ and $\gamma>0$ such that $\|u-t f\| \geqslant \gamma$ for all $t \in[0,1]$ and $u \in T(x)$ with $\|x\|=r$. This and the boundedness of $G$ imply that there exists $\mu_{0}>0$ such that $\|v-t f\| \geqslant \gamma / 2$ for $t \in[0,1], v \in T_{\mu}(x)$ with $\|x\|=r$ and $\mu \in\left(0, \mu_{0}\right)$. In view of Theorems 6.4 and 7.2 in [17], the equation $f \in T_{\mu}(x)=T(x)+\mu G(x)$ is solvable in $B(0, r)$ for each $\mu \in\left(0, \mu_{0}\right)$. Now, let $\mu_{k} \in\left(0, \mu_{0}\right)$ be such that $\mu_{k} \rightarrow 0$ as $k \rightarrow \infty$ and let $x_{k} \in B(0, r)$ be the corresponding solution of $f \in T_{u_{k}}(x)$. Since $\left\{G\left(x_{k}\right)\right\}$ is bounded, we have that $u_{k}=$
$f-\mu_{k} v_{k} \rightarrow f$ as $k \rightarrow \infty$ for some $u_{k} \in T\left(x_{k}\right)$ and $v_{k} \in G\left(x_{k}\right)$. This and condition $(++)$ imply that there exists an $x \in X$ such that $f \in T(x)$.: Q.E.D.

Remarks 2.3. Theorem 2.4 remains valid if condition $(+)$ is replaced by any one of the conditions of Remark 2.2. We also add that condition $(++)$ holds if $T(\bar{B}(0, r))$ is closed in $Y$ for each $r>0$.

Remark 2.4. When all mappings involved are single-valued, Theorem 2.4 and Theorems 6.4 and 7.2 in [17] were proven by Petryshyn [21].

Remark 2.5. Instead of condition ( + ) in Theorem 2.4 it is enough to require that for each $f \in Y$ there exists $r_{f} \geqslant r_{0}$ such that $\|u-t f\| \geqslant \gamma$ for all $t \in[0,1]$ and $u \in T(x)$ with $\|x\|=r_{f}$ and some $\gamma>0$.

Remark 2.6. The following are few choices of $K, M_{n}, G$ and $K_{n}$ in Theorem 2.4. If $Y=X^{*}$ with $X$ separable and reflexive, we choose $\Gamma=\Gamma_{c}=\left\{X_{n}, V_{n}\right.$; $\left.X^{*}{ }_{n}, V^{*}{ }_{n}\right\}, K=I, K_{n}=V_{n}, G=J$ a duality mapping and define $M_{n}: X_{n} \rightarrow X_{n}^{*}$ by $M_{n}(x)=\sum_{j=1}^{n}\left(f_{j}, x\right) f_{j}$, where $\left\{\psi_{1}, \ldots, \psi_{n}\right\}$ is a basis in $X_{n}$ and $\left\{f_{1}, \ldots, f_{n}\right\}$ is the corresponding biorthogonal basis in $X^{*}{ }_{n}$. If $Y=X$ and $\Gamma=\Gamma_{b}=\left\{X_{n}, V_{n} ; X_{n}, P_{n}\right\}$ is a projectionally complete scheme for ( $X, X$ ), we choose $K=J, K_{n}=P{ }_{n} J, M_{n}=I_{n}$ and $G=I$, where $I_{n}$ and $I$ are the identity mappings in $X_{n}$ and $X$, respectively.

When condition ( + ) is replaced by condition (C4) below, we have the following useful result.

Theorem 2.5. Let $X, Y, K, K_{n}$ and $M_{n}$ be as in Theorem 2.4. Suppose that $T: X \rightarrow 2^{Y}$ satisfies condition $(++)$ with $W_{n} T V_{n}: E_{n} \rightarrow C K\left(F_{n}\right)$ u.s.c. for each $n$. Suppose also that there exists a bounded mapping $G: X \rightarrow 2^{Y}$ such that $T_{\mu}=T+\mu G$ is A-proper w.r.t. $\Gamma$ for each $\mu>0$ and $W_{n} G(x) \in C K\left(F_{n}\right)$ for all $x \in V_{n}\left(E_{n}\right)$.

Moreover, suppose that for each $f \in Y$ there exists an $r_{f}>0$ such that
(C4) $(u-f, v) \geqslant 0$ and $(w, v) \geqslant 0$ for all $u \in T(x), w \in G(x)$ and $v \in K(x)$ with $\|x\|=r_{f}$.

Then $T$ is surjective, i.e., $T(X)=Y$.
Proof. Let $f \in Y$ be fixed. Then, for each $\mu>0$ we have $(u+\mu w-f, v)=$ $(u-f, v)+\mu(w, v) \geqslant 0$ for all $u \in T(x), w \in G(x), v \in K(x)$ with $\|x\|=r_{f}$.

It follows from Theorem 6.4 in [17] that the equation $f \in T_{\mu}(x)=T(x)+$ $\mu G(x)$ is solvable in $B\left(0, r_{f}\right)$ for each $\mu>0$. Proceeding as in Theorem 2.4, we obtain that the equation $f \in T(x)$ is solvable. Thus, $T(X)=Y$.
Q.E.D.

Finally, the following new result will prove to be useful.
Theorem 2.6. Let $X, Y, K, K_{n}$, and $M_{n}$ be as in Theorem 2.4. Let T: $X \rightarrow 2^{Y}$ satisfy condition $(++)$ with $W_{n} T V_{n}: E_{n} \rightarrow C K\left(F_{n}\right)$ u.s.c. for each $n$ and let
$G: X \rightarrow 2^{Y}$ be bounded with $W_{n} G V_{n}(x) \in C K\left(F_{n}\right)$ and $T_{u}=T+\mu G$ be A-proper w.r.t. $\Gamma$ for each $\mu>0$. Suppose that the following conditions hold:
(1) $(u, v) \geqslant\|x\|^{\alpha}\|v\|$ for all $u \in G(x), v \in K(x)$ with $x \in X$ and some $\alpha>0$.
(2) There exists $c>0$ such that $(u, v) \geqslant-c \mid v$ for all $u \in T(x), v \in K(x)$ with $x \in \mathrm{X}$.
(3) To each fin $Y$ there corresponds $c_{f}>0$ such that if $f \in T\left(x_{k}\right) \not \mu_{k} G\left(x_{k}\right)$ for some $x_{k} \in X$ with $\mu_{k} \rightarrow 0$, then $\left\|x_{k}\right\| \leqslant c_{f}$ for all $k$.

Then the equation $f \in T(x)$ is solvable for each $f$ in $Y$.
Proof. Let $\mu_{k}>0$ with $\mu_{k} \rightarrow 0$. By (1) and (2) we get that for each $k$ and $x$ in $X$
$\left(u+\mu_{k} w, v\right) \geqslant\left(\mu_{k}\|x\|^{\alpha}-c\right)\|v\| \quad$ for all $u \in T(x), \quad w \in G(x), \quad v \in K(x)$.
This means that $T_{\mu_{k}}$ is $K$-coercive and $A$-proper and consequently, by Theorem 6.4 [17], the equation $f \in T(x)+\mu_{k} G(x)$ is solvable for each $f$ in $Y$ and each $k$. Moreover, for each $f$ in $Y$ the set of solutions is bounded by (3) and thus, by condition $(++)$, there exists $x$ in $X$ such that $f \in T(x)$.
Q.E.D.

Remark 2.7. (a) Condition (3) in Theorem 2.6 is satisfied if $T$ satisfies condition ( $2+$ ) (i.e., if $\left\|x_{n}\right\| \rightarrow \infty$ then $\left\|u_{n}\right\| \rightarrow \infty$ for each $u_{n} \in T\left(x_{n}\right)$ ) provided (1) and (2) hold and $G$ is $\alpha$-positively homogeneous (i.e., $G(t x)=t^{\alpha} G(x)$ for $x \in X$ and $t>0$ ). Indeed, let $f \in T\left(x_{k}\right)+\mu G\left(x_{k}\right)$ with $\mu_{k} \rightarrow 0$. Then $f=u_{k}-\mu_{k} w_{k}$ for some $u_{k} \in T\left(x_{k}\right)$ and $w_{k} \in G\left(x_{k}\right)$ and for $v_{k} \in K\left(x_{k}\right)$, $\left(f, v_{k}\right)=\left(u_{k}, v_{k}\right)+\mu_{k}\left(w_{k}, v_{k}\right) \geqslant\left(\mu_{k}\left\|x_{k}\right\| x-c\right)\left\|v_{k}\right\|$. For $v_{k} \neq 0$ we have by the Schwartz-Buniakovsky inequality that $\mu_{k}\left\|x_{k}\right\|^{\alpha}=c+\left(f, v_{k}\right) \cdot\left\|v_{k}\right\|^{-1} \leqslant$ $c+\|f\|$. Since $G$ is bounded and $\mu_{k} G\left(x_{k}\right)=G\left(\mu_{k}^{1 / \alpha} x_{k}\right)$, we have that $\left\{u_{k}\right\}==$ $\left\{f-\mu_{k} w_{k}\right\}$ is bounded which, by ( $2+$ ), implies that $\left\{x_{k}\right\}$ is bounded.

The second author used the conditions and the method described in (a) to obtain a surjectivity theorem for the more general class of uniform limits of pseudo-A-proper maps (e.g. see 'Theorem 5.3A in [20]).
(b) Condition (3) of Theorem 2.6 holds if $T$ satisfies condition ( $3+$ ), i.e., (3-) \| $u_{n}\left\|+\left(u_{n}, v_{n}\right)\right\| v_{n} \| \rightarrow \infty$ as $\left\|x_{n}\right\| \rightarrow \infty$ for each $u_{n} \in T\left(x_{n}\right)$, $v_{n} \in K\left(x_{n}\right), 1$ and $(w, v)=\|w\| \cdot\|v\|$ for all $w \in G(x), v \in K(x)$ and $x \in X$.

To show this, let $f \in T\left(x_{k}\right)+\mu_{k} G\left(x_{k}\right)$ with $\mu_{k} \rightarrow 0$. Then $f=u_{k}+\mu_{k} z_{k}$ for some $u_{k} \in T\left(x_{k}\right)$ and $w_{k} \in G\left(x_{k}\right)$ and for $v_{k} \in K\left(x_{k}\right)$,

$$
\begin{aligned}
\left\|u_{k}\right\| & =\frac{\left(u_{k}, v_{k}\right)}{\left\|v_{k}\right\|} \\
& =\left\|f-\mu_{k} w_{k}\right\|+\frac{\left(f-\mu_{k} w_{k}, v_{k}\right)}{\| v_{k}!} \leqslant 2\|f\|+\mu_{k}\left\|w_{k}\right\|-\mu_{k} \frac{\left(w_{k}, v_{k}\right)}{\| v_{k}!} \\
& =2\|f\| \quad \text { for each } k .
\end{aligned}
$$

Hence, by ( $3+$ ), $\left\{x_{k}\right\}$ is bounded.
(c) Analyzing the proof of Theorem 2.6, we see that instead of (1) and (2) it is enough to assume that for all $\mu \in\left(0, \mu_{0}\right)\left(\mu_{0}>0\right)$ and some $r_{0}>0$, $(u+\mu w, v) \geqslant 0$ for all $u \in T(x), w \in G(x), v \in K(x)$ and $\|x\| \geqslant r_{0}$ and $T+\mu G$ satisfies condition ( + ) or that $T$ and $G$ are odd on $X \backslash B\left(0, r_{0}\right)$ and $T+\mu G$ satisfies ( $t$ ).

Remark 2.8. It is easy to see that condition (3+) implies condition $(2+)$. However, if condition (2) of Theorem 2.6 holds, then conditions ( $2+$ ) and (3+) are equivalent.

## 3. Surjectivity Resulits for Multivalued Mappings of Monotone and Ball-Contractive Type and Their Perturbations

In the first part of this section we introduce several new classes of multivalued $A$-proper mappings involving quasi- $K$-monotone, generalized pseudo- $K$ monotone and $K$-semibounded type of mappings. In the second part of this section we use the results of Section 2 in establishing various surjectivity type results for these classes of mappings and their perturbations. Ceratin surjectivity results for some perturbations of $k$-ball-contractive mappings are also proved. As special cases of our results, we deduce some results of Browder, Browder and Hess, Hess, Fitzpatrick, Petryshyn, Petryshyn and Fitzpatrick, Rockafellar, Wille, and others.

We begin this section by introducing some classes of multivalued mappings to be studied in the sequel.

Definition 3.1. (1) Let $K: X \rightarrow 2^{Y *}$. Then a mapping $T: X \rightarrow 2^{Y}$ is said to be quasi-K-monotone if
(a) The set $T(x)$ is nonempty, bounded, closed and convex in $Y$ for each $x \in X$;
(b) $T$ is upper semicontinuous from each finite dimensional subspace $F$ of $X$ to the weak topology on $Y$;
(c) $x_{n} \rightharpoonup x$ in $X$ implies that for each $u_{n} \in T\left(x_{n}\right)$ and $f_{n} \in K\left(x_{n}-x\right)$, $\lim \sup \left(u_{n}, f_{n}\right) \geqslant 0$.
(2) $T$ is said to be of type (KS) if (a) and (b) of (1) hold and if $x_{n} \rightharpoonup x$ in $X$ and $\left(u_{n}, f_{n}\right) \rightarrow 0$ for some $u_{n} \in T\left(x_{n}\right)$ and $f_{n} \in K\left(x_{n}-x\right)$ imply that $x_{n} \rightarrow x$ in $X$.
(3) $T$ is said to be of type ( $K S_{+}$) if (a) and (b) of (1) hold and if $x_{n} \rightharpoonup x$ in $X$ and $\lim \sup \left(u_{n}, f_{n}\right) \leqslant 0$ for some $u_{n} \in T\left(x_{n}\right)$ and $f_{n} \in K\left(x_{n}-x\right)$ imply that $x_{n} \rightarrow x$ in $X$.
(4) $T$ is said to be pseudo-K-monotone if conditions (a) and (b) of (1) hold and (d): if $x_{n} \rightharpoonup x$ in $X$ and if $u_{n} \in T\left(x_{n}\right)$ and $f_{n} \in K\left(x_{n}-x\right)$ are such that
$\lim \sup \left(u_{n}, f_{n}\right) \leqslant 0$, then to each element $v \in X$ there exist $u(v) \in T(x)$, $g \in K(x-v)$, and $g_{n} \in K\left(x_{n}-v\right)$ such that

$$
\lim \inf \left(u_{n}, g_{n}\right) \geqslant(u(v), g)
$$

(5) $T$ is said to be generalized pseudo-K-monotone if (a) and (b) of (1) hold and (e): if $x_{n} \rightarrow x$ in $X$ and $u_{n} \in T\left(x_{n}\right), f_{n} \in K\left(x_{n}-x\right)$ with $u_{n} \rightharpoonup u$ in $Y$ and lim sup $\left(u_{n}, f_{n}\right) \leqslant 0$ imply that $u \in T(x)$ and $\left(u_{n}, f_{n}\right) \rightarrow 0$.

Let us add that the single-valued pseudomonotone mappings ( $K=I$, $Y=X^{*}$ ) were introduced (in a somewhat different way) by Brézis [2] and that multivalued pseudomonotone and generalized pseudomonotone mappings were introduced by Browder and Hess [9]. Single-valued mappings of type ( $S$ ) and ( $S_{+}$) from $X$ into $X^{*}(K=I)$ were introduced and studied by Browder [5] and $I$-quasimonotone by Hess [13] and Calvert and Webb [10]. The singlevalued mappings given by Definition 3.1 were studied by Petryshyn in a series of papers (see [20]).

To introduce our first class of multivalued $A$-proper mappings we need the following:

Lemma 3.1. Let $X, Y$ be normed spaces, $T: X \rightarrow 2^{Y}$ a quasi-K-monotone mapping and $G: X \rightarrow 2^{Y}$ bounded and of type $\left(K S_{+}\right)$. Then $T+\alpha G$ is of type $\left(K S_{+}\right)$for each $\alpha>0$, except that in general $T(x)+\alpha G(x)$ may not be closed for all $x \in X$. In particular, if either $T$ is pseudo-K-monotone with $K$ being single-valued, and $K(0)=0$ or $T$ is a bounded generalized pseudo-K-monotone map with $Y$ reflexive, then $T+\alpha G$ is of type $\left(K S_{+}\right)$for each $\alpha>0$ except that in general $T(x)+\alpha G(x)$ may not be closed for each $x \in X$.
Proof. Let $\alpha>0$ be fixed and suppose that $x_{n} \rightarrow x_{0}$ in $X$ and let $\lim \sup \left(u_{n}+\alpha v_{n}, f_{n}\right) \leqslant 0$ for some $u_{n} \in T\left(x_{n}\right), v_{n} \in G\left(x_{n}\right)$, and $f_{n} \in K\left(x_{n}-x_{0}\right)$. Since $T$ is quasi- $K$-monotone and $G$ is bounded, it follows that $\lim \sup \left(v_{n}, f_{n}\right)$ $\leqslant 0$. Hence, by the ( $K S_{+}$) property of $G, x_{n} \rightarrow x$.
For the second part of the lemma we need only show that either a generalized pseudo- $K$-monotone or a pseudo- $K$-monotone mapping $T$ is quasi $-K$-monotone. Suppose first that $T$ is generalized pseudo- $K$-monotone. If $T$ is not quasi- $K$ monotone, then for some $u_{n} \in T\left(x_{n}\right), f_{n} \in K\left(x_{n}-x_{0}\right)$, where $x_{n} \rightharpoonup x_{0}$ in $X$, we have that $\lim \sup \left(u_{n}, f_{n}\right)<0$. Since $Y$ is reflexive and $T$ is bounded, we may assume that $u_{n} \rightarrow u_{0}$ in $Y$. By the generalized pseudo- $K$-monotonicity of $T$, it follows that $\lim \left(u_{n}, f_{n}\right)=0$, a contradiction. Thus $T$ is quasi- $K$-monotone.
Assume now that $T$ is pseudo- $K$-monotone. Again, supposing that it is not quasi- $K$-monotone, we obtain that $\lim \sup \left(u_{n}, K\left(x_{n}-x_{0}\right)\right)<0$ for some $u_{n} \in T\left(x_{n}\right)$, with $x_{n} \rightharpoonup x_{0}$ in $X$. By the pseudo- $K$-monotonicity we have that for each $v \in X$ there exists $u(x) \in T\left(x_{0}\right)$ with

$$
\lim \inf \left(u_{n}, K\left(x_{n}-v\right) \geqslant\left(u(v), K\left(x_{0}-v\right)\right) .\right.
$$

In particular, taking $v=x_{0}$ in the last inequality, we obtain

$$
\liminf \left(u_{n}, K\left(x_{n}-x_{0}\right)\right) \geqslant 0>\lim \sup \left(u_{n}, K\left(x_{n}-x_{0}\right)\right),
$$

a contradiction. Thus, $T$ is quasi- $K$-monotone.
Q.E.D.

Definition 3.2. We say that a mapping $T: D \subset X \rightarrow 2^{Y}$ is $K$-quasi-bounded if, for any bounded sequence $\left\{x_{n}\right\} \subset D,\left(y_{n}, f_{n}\right) \leqslant c\left\|x_{n}\right\|$ for each $n$ and some $y_{n} \in T\left(x_{n}\right), f_{n} \in K\left(x_{n}\right), c>0$, implies that $\left\{y_{n}\right\}$ is bounded in $Y$.
$T$ is said to be demiclosed if $x_{n} \rightarrow x$ in $X$ and $y_{n} \rightharpoonup y$ for some $y_{n} \in T\left(x_{n}\right)$, then $y \in T(x)$.

In view of Proposition 2.2 in [19] and Lemma 3.1 we have the following:
Proposition 3.1. Let $X$ and $Y$ be reflexive Banach spaces with an admissible scheme $\Gamma_{a}=\left\{X_{n}, V_{n} ; Y_{n}, Q_{n}\right\}$ and $K: X \rightarrow Y^{*}$ a bounded mapping such that
( $\mathrm{a}_{1}$ ) $K(x)=0$ implies $x=0, K$ is $\alpha$-positively homogeneous (i.e., $K(t x)=$ $t^{\alpha} K(x)$ for each $t>0, x$ in $X$ and some $\alpha>0$ ), and the range of $K$ is dense in $Y^{*}$.
( $\mathrm{a}_{2}$ ) For each $x \in X_{n}$ and $g \in Y$, we have that $\left(Q_{n}(g), K(x)\right)=(g, K(x))$;
$\left(\mathrm{a}_{3}\right) K$ is weakly continuous at 0 and is uniformly continuous on closed balls in $X$.

Let $T: X \rightarrow 2^{Y}$ be a $K$-quasi-bounded demiclosed and quasi-K-monotone mapping and $G: X \rightarrow 2^{Y}$ a bounded, demiclosed and of type $\left(K S_{+}\right)$. Then $T+\alpha G$ is $A$-proper w.r.t. $\Gamma_{a}$ for each $\alpha>0$.

Remark 3.1. In the single-valued case Proposition 3.1 was established in Petryshyn [21], while the first part of Lemma 3.1 was proved by Hess [13] and Calvert and Webb [10] for $Y=X^{*}, K=I$ and $G=J$ a single-valued duality mapping and by Petryshyn [21] for general $K$ and $G$. That a single-valued pseudomonotone mapping $T: X \rightarrow X^{*}$ is quasi-monotone ( $K=I$ ) was proved by Fitzpatrick [12].

The following result will be needed for the next proposition and for establishing the surjectivity results of mappings involved. First we introduce the following:

Definition 3.3. We say that a multivalued mapping $T: X \rightarrow 2^{r}$ is hemicontinuous at $x \in X$, if $x \in X, t_{n}>0, t_{n} \rightarrow 0$ and $y_{n} \in T\left(x+t_{n} v\right)$ imply that some subsequences $y_{n_{k}} \rightarrow y \in T(x)$. It is demicontinuous if $x_{n} \rightarrow x_{0}$ in $X$ and $y_{n} \in T\left(x_{n}\right)$ imply that some subsequence $y_{n_{k}} \rightharpoonup y_{0} \in T\left(x_{0}\right)$.

Definition 3.4. Let $X$ and $Y$ be Banach spaces and $K: X \rightarrow 2^{Y *}$. Then a mapping $T$ from $X$ into $2^{r}$ is said to be $K$-monotone, if for all $x, y$ in $X$ there exists $f \in K(x-y)$ such that $(u-v, f) \geqslant 0$ for all $u \in T(x), v \in T(y) . T$ is maximal $K$-monotone if it is $K$-monotone and maximal in the sense of inclusions of graphs in the family of $K$-monotone mappings from $X$ into $2^{r}$.

Monotone mappings ( $K=I, Y=X^{*}$ ) were introduced independently by Vainberg, Kachuvorsky and Zarantonello and further studied by Minty, Browder, Kachuvorsky, Rockafellar, and others (see [5, 14] for references). The study of $J$-monotone mappings ( $J$ a duality mapping) was initiated by Browder, while those of $K$-monotone type were initiated by Kato and Petryshyn.

Proposition 3.2. Let $X$ and $Y$ be Banach spaces with an admissible scheme $\Gamma_{1,}$ and $X$ reflexive. Let $K: X \rightarrow Y^{*}$ be weakly continuous, $\alpha$-homogeneous with $\alpha \geqslant 1$ and $R(K)=Y^{*}$. Let $D$ be an open convex subset of $X$ and $T: \bar{D} \rightarrow 2^{X}$ eihter hemicontinuous and $K$-monotone or pseudo-K-monotone. Then, if $G$ is a bounded closed and convex subset of $D, T(G)$ is closed in $Y$.

Proof. Let $u_{k} \in T(G)$ be such that $u_{k} \rightarrow u$ in $Y$ as $k \rightarrow \infty$ and let $x_{k} \in G$ be such that $u_{k} \subset T\left(x_{k}\right)$ for each $k$. By the reflexivity of $X$ we may assume that $x_{k} \rightarrow x_{0} \in G$.

Then, if $T$ is $K$-monotone, $\left(u_{k}-y, K\left(x_{k}-v\right)\right) \geqslant 0$ for all $v \in D, y \in T(v)$ and all $k$. The passage to the limit in the latter inequality yields

$$
\begin{equation*}
\left(u, K\left(x_{0}-v\right)\right) \geqslant\left(y, K\left(x_{0}-v\right)\right) \quad \text { for all } y \in T(v) \quad \text { and } \quad v \in D . \tag{3.1}
\end{equation*}
$$

If $T$ is pseudo- $K$-monotone, then

$$
\lim \sup \left(u_{k}, K\left(x_{k}-x_{\mathbf{0}}\right)\right)=\lim \left(u_{k}, K\left(x_{k}-x_{0}\right)\right)=0
$$

and consequently, for each $v \in D$ there exists $y(v) \in T\left(x_{0}\right)$ such that

$$
\lim \inf \left(u_{k}, K\left(x_{k}-v\right)\right) \geqslant\left(y(v), K\left(x_{0}-v\right)\right) .
$$

Passing to the limit, we obtain

$$
\begin{equation*}
\left(u, K\left(x_{0}-v\right)\right) \geqslant\left(y(v), K\left(x_{0}-v\right)\right) \quad \text { for all } \tau \in D . \tag{3.2}
\end{equation*}
$$

Now, each one of the inequalities (3.1), (3.2) implies that $u \in T\left(x_{0}\right)$. Consider (3.1) and suppose that $u \notin T\left(x_{0}\right)$. Since $T\left(x_{0}\right)$ is closed and convex and $R(K)=Y^{*}$, there exists $z_{0} \in X$ such that

$$
\begin{equation*}
\left(u, K\left(z_{0}\right)\right)<\inf _{y \in T\left(x_{0}\right)}\left(y, K\left(z_{0}\right)\right) . \tag{3.3}
\end{equation*}
$$

Since $D$ is open and $x_{0} \in D$, for sufficiently small $t>0$, we have that $v_{t}=x_{0}-t z_{0} \in D$. Choosing $x_{0}-t z_{0}$ for $v$ in (3.1), we obtain

$$
\left(u, K\left(t z_{0}\right)\right) \geqslant\left(y(t), K\left(t z_{0}\right)\right), \quad y(t) \in T\left(x_{0}-t z_{0}\right)
$$

or $\left(u, K\left(z_{0}\right)\right) \geqslant\left(y(t), K\left(z_{0}\right)\right)$. Since $T$ is hemicontinuous, passing to the limit when $t \rightarrow 0$, we get

$$
\left(u, K\left(z_{0}\right)\right) \geqslant\left(y, K\left(z_{0}\right)\right) \quad \text { for } y \in T\left(x_{0}\right),
$$

in contradiction to (3.3).

Assuming now that the inequality (3.2) holds, we get in a similar fashion that for $t>0$ small

$$
\left(u, K\left(z_{0}\right)\right) \geqslant\left(z(t), K\left(z_{0}\right)\right) \quad \text { with } \quad z(t) \in T\left(x_{0}\right)
$$

which contradicts (3.3).
Q.E.D.

Now we are in a position to prove the following.
Proposition 3.3. Let $X, Y, \Gamma_{a}$, and $K$ be as in Proposition 3.1 with $K$ weakly continuous on $X$ and $K(0)=0$. If $T: X \rightarrow 2^{Y}$ is quasi-K-bounded, pseudo- $K$ monotone and either demiclosed or $K$ is onto, and if $G: X \rightarrow 2^{r}$ is a bounded demiclosed mapping of type $\left(K S_{+}\right)$, then $T+\alpha G$ is $A$-proper w.r.t. $\Gamma_{a}$ for each $\alpha>0$.

Proof. Let $\alpha>0$ be fixed. Then by Lemma 3.1, $T+\alpha G$ is of type $\left(K S_{+}\right)$. Since $T+\alpha G$ is $K$-quasi-bounded, by Proposition 2.2 in [19], it is sufficient to show that $T+\alpha G$ is demiclosed. So, let $x_{n} \rightarrow x$ in $X$ and let $y_{n}=u_{n}+\alpha v_{n} \in T\left(x_{n}\right)+\alpha G\left(x_{n}\right)$ be such that $y_{n} \rightharpoonup y$ in $Y$. Since $G$ is demiclosed and bounded, we have for some subsequence that $v_{n_{j}} \rightharpoonup v \in G(x)$, and consequently, $u_{n_{j}} \rightharpoonup y-\alpha v$. Hence, if $T$ is demiclosed, we see that so is $T+\alpha G$. Next, let $K$ be onto. By the continuity of $K,\left(u_{n_{j}}, K\left(x_{n_{j}}-x\right)\right) \rightarrow 0$. Now, continuing in the same fashion as in Proposition 3.2, we obtain that $y-\alpha v \in T(x)$, or $y \in T(x)+\alpha G(x)$.
Q.E.D.

Remark 3.2. If $K$ is linear, then it can be shown that a maximal $K$-monotone mapping $T$ is pseudo- $K$-monotone and that, if $K$ is also onto, pseudo- $K$-monotone mapping is generalized pseudo- $K$-monotone (see Browder and Hess [9] for the case $Y=X^{*}$ and $K=I$ ).

For $K$-quasi-bounded generalized pseudo-K-monotone mappings we have the following:

Proposition 3.4. Let $X, Y, \Gamma_{a}$ and $K$ be as in Proposition 3.1. If $T$ is a $K$-quasibounded and generalized pseudo-K-monotone mapping of $X$ into $2^{r}$ and if $G$ is a bounded demiclosed mapping of type $\left(K S_{+}\right)$from $X$ into $2^{r}$, then $T_{\mu}=T+\mu G$ is $A$-proper w.r.t. $\Gamma_{a}$ for each $\mu>0$.

Proof. Let $\mu>0$ be fixed and let $\left\{x_{n_{j}} \mid x_{n_{j}} \in X_{n_{j}}\right\}$ be a bounded sequence such that for some $g \in Y, u_{n_{j}} \in T\left(x_{n_{j}}\right)$, and $v_{n_{j}} \in G\left(x_{n_{j}}\right), Q_{n_{j}}\left(u_{n_{j}}\right)+\mu Q_{n_{j}}\left(v_{n_{j}}\right)-$ $Q_{n_{j}}(g) \rightarrow 0$ as $j \rightarrow \infty$. Then, as in Proposition 2.2 of [19], we obtain that $\left(u_{n_{j}}+\mu v_{n_{j}}, K\left(x_{n_{j}}-x_{0}\right)\right) \rightarrow 0$ as $j \rightarrow \infty$ and $\left\{u_{n_{j}}\right\}$ is bounded, where $x_{n_{j}} \rightarrow x_{0}$.

Now by the reflexivity of $Y$, we may assume that $u_{n_{j}} \rightharpoonup u_{0}$ and that $v_{n_{j}} \rightharpoonup v_{0}$ in $Y$. Moreover, we claim that $\lim \sup \left(\mu v_{n_{i}}, K\left(x_{n_{j}}-x_{0}\right)\right) \leqslant 0$. If not, then $\lim \sup \left(\mu v_{n_{j}}, K\left(x_{n_{3}}-x_{0}\right)\right)>0$ and by passing to a subsequence, we may assume that $\lim \left(\mu v_{n_{j}}, K\left(x_{n_{j}}-x_{0}\right)\right)>0$. Thus, $\lim \sup \left(u_{n_{j}}, K\left(x_{n_{j}}-x_{0}\right)\right)=$ $\lim \sup \left(u_{n_{j}}+\mu v_{n_{j}}, K\left(x_{n_{j}}-x_{0}\right)\right)-\lim \left(\mu v_{n_{j}}, K\left(x_{n_{j}}-x_{0}\right)\right)<0$. Since $T$ is generalized pseudo- $K$-monotone, it follows that $u_{0} \in T\left(x_{0}\right)$ and ( $u_{n,}$, $\left.K\left(x_{n_{j}}-x_{0}\right)\right) \rightarrow 0$ as $j \rightarrow \infty$, in contradiction to $\lim \left(u_{n_{j}}, K\left(x_{n_{j}}-x_{0}\right)\right)<0$.

Consequently, $\lim \sup \left(v_{n_{j}}, K\left(x_{n_{j}}-x_{0}\right)\right) \leqslant 0$ which, by the $\left(K S_{+}\right)$property of $G$, implies that $x_{n_{j}} \rightarrow x_{0}$.

Now, let $y \in X$ be arbitrary and let $y_{n} \in X_{n}$ be such that $y_{n} \rightarrow y$. Then, by $\left(a_{2}\right), \quad\left(u_{0}+\mu v_{0}-g, K y\right)=\lim \left(u_{n_{j}}+\mu v_{n_{j}}-g, K\left(y_{n_{j}}\right)\right)=\lim \left(Q_{n_{j}}\left(u_{n_{j}}\right)+\right.$ $\mu Q_{n_{j}}\left(v_{n_{j}}\right)-Q_{n_{j}}(g), K\left(y_{n_{j}}\right)=(0, K(y))=0$. Hence, since $R(K)$ is dense in $Y^{*}$ and $\left(u_{0}+\mu v_{0}-g, w\right)=0$ for all $w \in R(K)$, it follows that $g=u_{0}+\mu v_{0}$. Moreover, that $u_{0}+\mu v_{0} \in T\left(x_{0}\right)+\mu G\left(x_{0}\right)$ follows from the demiclosedness of $G$ and the generalized pseudo-K-monotonicity of $T$ since $\left(u_{n_{j}}, K\left(x_{n_{j}}-x_{0}\right)\right) \rightarrow 0$ as $j \rightarrow \infty$.
Q.E.D.

In treating perturbation results, the following result will be useful.
Lemma 3.2. Let $X$ and $Y$ be reflexive Banach spaces, $K: X \rightarrow Y^{*}$ continuous and linear and $T_{1}$ and $T_{2}$ two generalized pseudo- $K$-monotone mappings from $X$ into $2^{Y}$. Suppose that $T_{1}$ is $K$-quasibounded and that there exists a continuous function $\psi: R^{+} \rightarrow R$ such that for all $(x, y) \in G\left(T_{2}\right),(y, K(x)) \geqslant-\psi(\|x\|)\|x\|$. Then $T_{1}-T_{2}$ is generalized pseudo-K-monotone. In particular, if $T_{2}$ is maximal $K$-monotone with $0 \in T_{2}(0)$, then $T_{1}+T_{2}$ is generalized pseudo- $K$-monotone.

Proof. For $K=I$ and $Y=X^{*}$, Lemma 3.2 was proved by Browder and Hess [9]. Simple checking shows that the same arguments carry over to this more general setting.
Q.E.D.

Finally, let us introduce another important class of multivalued mappings that contains $K$-monotone mappings as a proper subclass.

Definition 3.5. Let $K: X \rightarrow Y^{*}$ and $T: X \rightarrow 2^{Y}$. Then $T$ is called an operator with semibounded variation if $T(x)$ is nonempty, closed and convex for each $x$ in $X$ and for any $x$ and $y$ in $X$ such that $\|x\| \leqslant R,\|y\| \leqslant R$ we have the inequality

$$
(u-r, K(x-y)) \geqslant-c\left(R,\|x-y\|^{\prime}\right) \quad \text { for all } u \in T(x), \quad v \in T(y)
$$

where $\|$ is a norm on $X$ which is compact relative to the norm $\|\cdot\|$ and $c(R, \rho) \geqslant 0$ is a continuous function in $R$ and $\rho$ such that $c(R, t \rho) / t \rightarrow 0$ as $t \rightarrow 0$ for any fixed $R$ and $\rho$.

Nonlinear operators $T: X \rightarrow X^{*}$ with semibounded variation have been studied by many authors (see, for example [11, 3, 25] and the literature cired there).

Using Lemma 1.1 of Fitzpatrick [12], we first prove the following result.
Lemma 3.3. Let $T: X \rightarrow 2^{Y}$ be an operator with semibounded variation and $K: X \rightarrow Y^{*}$ linear continuous and onto. Then
(a) $T$ is locally bounded (i.e., if $x_{n} \rightarrow x$ in $X$ and $u_{n} \in T\left(x_{n}\right)$, then $\left\{u_{n}\right\}$ is bounded in $Y$ );
(b) if $Y$ is reflexive and $T$ is hemicontinuous, $T$ is demicontinuous and strongly demiclosed (i.e., if $x_{n} \rightharpoonup x_{0}$ in $X$ and $u_{n_{k}} \in T\left(x_{n_{k}}\right)$ with $u_{n_{k}} \rightarrow$ fin $Y$, then $f \in T\left(x_{0}\right)$ );
(c) $T$ is $K$-quasi-bounded provided $K$ is one-to-one.

Proof. (a) Suppose that $T$ is not locally bounded. Then there exists a sequence $\left\{x_{n}\right\} \subset X$ such that $x_{n} \rightarrow x_{0}$ and for some $u_{n} \in T\left(x_{n}\right),\left\{u_{n}\right\}$ is unbounded. Since $y_{n}=K\left(x_{n}\right) \rightarrow K\left(x_{0}\right)=y_{0}$ and $\left\{u_{n}\right\} \subset Y \subset Y^{* *}$ with $\left\|u_{n}\right\| \rightarrow \infty$, by Lemma 1.1 in [12] we may choose a subsequence (if necessary) and $\tilde{z}_{0}$ in $Y^{*}$ such that $\lim _{n}\left(u_{n}, y_{n}-y_{0}-\tilde{z}_{0}\right)=-\infty$. Moreover, since $R(K)=Y^{*}$, there exists $x_{0}$ in $X$ such that $K\left(\tilde{x}_{0}\right)=\tilde{z}_{0}$ and for each $n$ and fixed $v_{0} \in T\left(x_{0}+\tilde{x}_{0}\right)$ we have

$$
\begin{align*}
& \left(u_{n}, K\left(x_{n}\right)-K\left(x_{0}+\tilde{x}_{0}\right)\right)  \tag{3.4}\\
& \quad \geqslant\left(v_{0}, K\left(x_{n}\right)-K\left(x_{0}+\tilde{x}_{0}\right)\right)-c\left(R,\left\|x_{n}-x_{0}-\tilde{x}_{0}\right\|^{\prime}\right)
\end{align*}
$$

where $R>0$ is such that $\left\|x_{0}+\tilde{x}_{0}\right\| \leqslant R$ and $\left\|x_{n}\right\| \leqslant R$ for all $n$. Set $t_{n}=\left\|x_{n}-x_{0}-\tilde{x}_{0}\right\|, t_{0}=\left\|-\tilde{x}_{0}\right\|$ and note that $c\left(R, t_{n}\right) \rightarrow c\left(R, t_{0}\right)$ as $n \rightarrow \infty$. Hence, for a given $\epsilon>0$, there exists $n_{0} \geqslant 1$ such that $\left|c\left(R, t_{n}\right)-c\left(R, t_{0}\right)\right|<\epsilon$ for $n \geqslant n_{0}$. Consequently, $-c\left(R, t_{n}\right)>-c\left(R, t_{0}\right)-\epsilon$ for $n \geqslant n_{0}$, and therefore the right-hand side of (3.4) is bounded from below. This contradiction leads to the validity of (a).
(b) Let $x_{n} \rightarrow x_{0}$ in $X$ and $u_{n} \in T\left(x_{n}\right)$. By (a), $\left\{u_{n}\right\}$ is bounded in $Y$ and consequently there exists a subsequence $\left\{u_{n_{n}}\right\}$ such that $u_{n_{j}} \rightharpoonup u$ in $Y$. Let $r>0$ be such that $\left\{x_{n}\right\} \subset B\left(x_{0}, r\right) \subset X$ and $x \in B\left(x_{0}, r\right)$. Then for each $v \in T(x)$ and some $R>0$ we have

$$
\left(u_{n_{k}}-v, K\left(x_{n_{k}}-x\right)\right) \geqslant-c\left(R,\left\|x_{n_{k}}-x\right\|^{\prime}\right) .
$$

Taking the limit in the above inequality as $n \rightarrow \infty$, we get $\left(u-v, K\left(x_{0}-x\right)\right.$ ) $\geqslant-c\left(R,\left\|x_{0}-x\right\|^{\prime}\right)$ for each $v \in T(x)$, or

$$
\begin{align*}
&\left(u, K\left(x_{0}-x\right)\right) \geqslant\left(v, K\left(x_{0}-x\right)\right)-c\left(R,\left\|x_{0}-x\right\|^{\prime}\right) \quad \text { for all } v \in T(x), \\
& x \in B\left(x_{0}, r\right) . \tag{3.5}
\end{align*}
$$

This inequality implies that $u \in T\left(x_{0}\right)$. If not, then since $T\left(x_{0}\right)$ is closed and convex and $R(K)=Y^{*}$, there exists $z_{0} \in X$ such that

$$
\begin{equation*}
\left(u, K\left(z_{0}\right)\right)<\inf _{y \in T\left(x_{0}\right)}\left(y, K\left(z_{0}\right)\right) \tag{3.6}
\end{equation*}
$$

Let $t_{n}>0$ be such that $t_{n} \rightarrow 0$ and $x_{0}-t_{n} z_{0} \in B\left(x_{0}, r\right)$. Choosing $x_{0}-t_{n} z_{0}$ as $x$ in (3.5), we obtain $\left(u, K\left(t_{n} z_{0}\right)\right) \geqslant\left(v\left(t_{n}\right), K\left(t_{n} z_{0}\right)\right)-c\left(R, t_{n}\left\|z_{0}\right\|^{\prime}\right), v\left(t_{n}\right) \in$
$T\left(x_{0}-t_{n} z_{0}\right)$, or $\left(u, K\left(z_{0}\right)\right) \geqslant\left(v\left(t_{n}\right), K\left(z_{0}\right)\right)-c\left(R, t_{n}\left\|z_{0}\right\|^{\prime}\right) / t_{n}$. Since $T$ is hemicontinuous, passing to the limit as $n \rightarrow \infty$ we obtain

$$
\left(u, K\left(z_{0}\right)\right) \geqslant\left(v, K\left(z_{0}\right)\right) \quad \text { for some } v \in T\left(x_{0}\right)
$$

which contradicts (3.6). Thus, $u \in T\left(x_{0}\right)$.
The strong demiclosedness of $T$ follows in the same fashion.
(c) Let $\left\{x_{n}\right\} \subset X$ be bounded and $\left(u_{n}, K\left(x_{n}\right)\right) \leqslant c_{0}\left\|x_{n}\right\|$ for some $u_{n} \in T\left(x_{n}\right)$ and all $n$. Let $R>0$ be such that $\left\{x_{n}\right\} \subset B(0, R)$ and observe that for each $x \in B(0, R)$ and $u \in T(x)$ we have

$$
\left(u_{n}-u, K\left(x_{n}-x\right)\right) \geqslant-c\left(R,\left\|x_{n}-x\right\|^{\prime}\right)
$$

Since $T$ is locally bounded, there exists $\epsilon>0$ such that $\| \leqslant c_{1}$ for all $u \in T(x)$ with $\|x\| \leqslant \epsilon$. We may assume that $\epsilon<R$ and then for each $u \in T(x)$ with $\|x\| \leqslant \epsilon$ from the above inequality we obtain

$$
\left(u_{n}, K(x)\right)\left|\leqslant\left|\left(u_{n}, K\left(x_{n}\right)\right)\right|+\left|\left(u, K\left(x_{n}-x\right)\right)\right|+c\left(R,\left.\left|x_{n}-x\right|\right|^{\prime}\right) .\right.
$$

Now, since $\left(X,\|\cdot\|^{\prime}\right)$ is compactly embedded into $\left(X, \| \cdot{ }^{\prime}\right)$, there exists $c_{2}>0$ such that $\|x\|^{\prime} \leqslant c_{2}\|x\|$ for all $x \in B(0,2 R)$ and consequently, $\left\|x_{n}-x\right\|^{\prime} \leqslant$ $c_{2}(R+\epsilon)$. By the continuity of $c(R, \rho)$ we have that $c\left(R,\left\|x_{n}-x\right\|^{\prime}\right) \leqslant c_{3}$ for all $n$ and some $c_{3}>0$. Thus, for all $u \in T(x)$ with $\|x\| \leqslant \epsilon, \mid\left(u_{n}, K(x)\right) \leqslant$ $c_{0}+c_{1}\left\|K\left(x_{n}-x\right)\right\|+c_{3} \leqslant M$ for all $n$ and some $M>0$ and since $K$ is injective and $Y$ reflexive, we have for $0<\epsilon_{0} \leqslant \epsilon$ with $\epsilon_{0}\|y\| \leqslant \epsilon$ for $y \in A=$ $K^{-1}(B(0,1))$ that

$$
\epsilon_{0}\left\|u_{n}\right\|=\epsilon_{0} \sup _{y \in A}\left|\left(u_{n}, K(y)\right)\right|=\sup _{y \in A}\left|\left(u_{n}, K\left(\epsilon_{0} y\right)\right)\right| \leqslant M,
$$

i.e., $\left|u_{n}\right| \leqslant M / \epsilon_{0}$ for all $n$.
Q.E.D.

The relationship of mappings with semibounded variation to pseudo $K$-monotone ones is given by the following:

Proposition 3.5. Let $Y$ be reflexive, $K: X \rightarrow Y^{*}$ linear, continuous and surjective and $T: X \rightarrow K(Y)$ hemicontinuous with semibounded variation. Then $T$ is pseudo-K-monotone.

Proof. By Lemma 3.3(b), all we need show is part (d) of Definition 3.1. Suppose that $x_{n} \longrightarrow x_{0}$ in $X$ and $u_{n} \in T\left(x_{n}\right)$ with $\lim \sup \left(u_{n}, K\left(x_{n}-x_{0}\right)\right) \leqslant 0$. Then for a fixed $u_{0} \in T\left(x_{0}\right)$ and some $R>0$ we have $\left(u_{0}, K\left(x_{n}-x_{0}\right)\right) \leqslant$ $\left(u_{n}, K\left(x_{n}-x_{0}\right)\right)+c\left(R,\left\|x_{n}-x_{0}\right\|^{\prime}\right) \quad$ and so $\lim \inf \left(u_{n}, K\left(x_{n}-x_{0}\right)\right) \geqslant 0$. Hence, $\left(u_{n}, K\left(x_{n}-x_{0}\right)\right) \rightarrow 0$ as $n>\infty$. This implies that for each $x$ in $X$, $\liminf \left(u_{n}, K\left(x_{n}-x\right)\right)=\lim \left(u_{n}, K\left(x_{n}-x_{0}\right)\right)+\lim \inf \left(u_{n}, K\left(x_{0}-x\right)\right)=$ $\liminf \left(u_{n}, K\left(x_{0}-x\right)\right)$. Now for $v \in T(x)$,

$$
\left(v, K\left(x_{n}-x\right)\right) \leqslant\left(u_{n}, K\left(x_{n}-x\right)\right)+c\left(R,\left\|x_{n}-x\right\|^{\prime}\right)
$$

and passing to the limit we obtain
$\left(v, K\left(x_{0}-x\right)\right) \leqslant \liminf \left(u_{n}, K\left(x_{0}-x\right)\right) \quad$ for all $v \in T(x), \quad x \in X$.
Let $v_{0}$ in $X$ be fixed and define $x_{t}=x_{0}+t\left(v_{0}-x_{0}\right)$ for $t>0$ with $t \rightarrow 0$. Then for any $v_{t} \in T\left(x_{t}\right)$ we get from (3.7) that

$$
\left(v_{t}, K\left(x_{0}-v_{0}\right)\right) \leqslant \liminf _{n}\left(u_{n}, K\left(x_{0}-v_{0}\right)\right)
$$

Since $T$ is locally bounded and hemicontinuous, we may assume that $v_{t} \rightarrow v \in T\left(x_{0}\right)$ as $t \rightarrow 0$. Consequently, passing to the limit as $t \rightarrow 0$ in the last inequality, we get

$$
\left(v, K\left(x_{0}-v_{0}\right)\right) \leqslant \liminf _{n}\left(u_{n}, K\left(x_{0}-v_{0}\right)\right)=\liminf _{n}\left(u_{n}, K\left(x_{n}-v_{0}\right)\right) .
$$

Q.E.D.

Let us now discuss some special cases of our results and their relationship to some results of other authors. Our first result in that direction is the following:

Theorem 3.1. Let $X, Y, \Gamma_{a}$ and $K$ be as in Proposition 3.1 with $K$ linear and let, $T:[0,1] \times X \rightarrow 2^{Y}, A: X \rightarrow B K(Y)$ and $G: X \rightarrow K(Y)$ be bounded, demiclosed and of type $\left(K S_{+}\right)$. Suppose that
(1) $T_{t}=T(t, \cdot)$ is $\alpha$-continuous in $t$ uniformly for $x$ in bounded subsets of $X$.
(2) For each $f$ in $Y$ there exists $r_{f}>0$ such that $f \notin \overline{\left(T_{t}+\bar{A}\right)\left(\partial B\left(0, r_{f}\right)\right)}$ for all $t \in[0,1]$.
(3) $s f \not \ddagger \overline{\left.\left(T_{0}+\overline{A)(\partial \overline{B( }}, r_{f}\right)\right)}$ for all $s \in[0,1]$;
(4) There exists $n_{f} \geqslant 1$ such that for each $n \geqslant n_{f}$ and $\mu>0, \operatorname{deg}\left(L_{n} Q_{n} T_{0}+\right.$ $\left.L_{n} Q_{n} A+\mu L_{n} Q_{n} G, B_{n}\left(0, r_{f}\right), 0\right) \neq 0$, where $L_{n}$ is some linear isomorphism from $Y_{n}$ onto $X_{n}$.

Moreover, suppose that either $T_{t}$ is quasi-K-monotone and $K$-quasi-bounded for each $t \in[0,1]$ and $A$ is maximal $K$-monotone, or $T_{t}$ is generalized pseudo- $K$ monotone and $K$-quasi-bounded for each $t \in[0,1]$ and $A$ is generalized pseudo- $K$ monotone and $K$-quasi-bounded such that $(u, K(x)) \geqslant-\psi(\|x\|)\|x\|$ whenever $(x, u) \in G(A)$, where $\psi: R^{+} \rightarrow R$ is a continuous function. Then the equation $f \in T_{1}(x)+A(x)$ is solvable for each $f$ in $Y$ provided $T_{1}$ satisfies condition $(++)$.

Proof. We first observe that for each $t \in[0,1], T_{t}+A$ is quasi- $K$-monotone in the first case, and generalized pseudo- $K$-monotone in the second case (Lemma 3.2 , with possibly not closed images). Moreover, $T_{t}+A$ is $K$-quasi-bounded if $A$ is maximal $K$-monotone. Next, suppose that $A$ is generalized pseudo- $K$ monotone and that for some bounded $\left\{x_{n}\right\} \subset X$ we have that ( $t \in[0,1]$ fixed)
$\left(u_{n}+v_{n}, K\left(x_{n}\right)\right) \leqslant c\left\|x_{n}\right\|$ for some $u_{n} \in T_{t}\left(x_{n}\right), v_{n} \in A\left(x_{n}\right)$ and some $c>0$. Then

$$
\left(u_{n}, K\left(x_{n}\right)\right) \leqslant c\left\|x_{n}\right\|+\psi\left(\left\|x_{n}\right\|\right)\left\|x_{n}\right\| \leqslant c_{1}\left\|x_{n}\right\|
$$

for some $c_{1}>0$. By the $K$-quasi-boundedness of $T_{t},\left\{u_{n}\right\}$ is bounded. Since $\left(v_{n}, K\left(x_{n}\right)\right) \leqslant c\left\|x_{n}\right\|+\left|\left(u_{n}, K\left(x_{n}\right)\right)\right| \leqslant c_{2}\left\|x_{n}\right\|$, we have that $\left\{v_{n}\right\}$ is also bounded. Hence, $\left\{u_{n}+v_{n}\right\}$ is bounded, proving the $K$-quasi-boundedness of $T_{t}+A$. It remains to observe that since $T_{t}+A+\mu G$ is $A$-proper w.r.t. $\Gamma_{a}$ for each $t \in[0,1]$ and $\mu>0$, the conclusion of our theorem follows from Theorem 2.3.
Q.E.D.

Remark 3.3. If in Theorem 3.1 we assume that $(u, K(x)) \geqslant-c(t,\|x\|) x$ for all $u \in T_{t}(x), t \in[0,1]$, instead of $K$-quasi-boundedness of $T_{t}$, where $c:[0,1] \times R^{+} \rightarrow R$ is continuous, then one can easily see that the conclusion of Theorem 3.1 is still valid since $T_{t} \vdash A$ is also $K$-quasi-bounded in this case.

Remark 3.4. When $Y=X^{*}, K=I$ and $T_{0}$ and $A$ are odd on the boundary of a symmetric about 0 set $D$ in $X$ with $A$ maximal monotone, $T_{1}$ pseudomonotone, $T_{t}$ single-valued quasi-monotone for $t \in[0,1]$, and $0 \notin \overline{\left(T_{t}+\bar{A}\right)(\partial D)}$ instead of (2) and (3), the conclusion of Theorem 3.1 for $f=0$ was proved by Hess [13].

As a consequence of our results of Section 2, we have the following surjectivity result for perturbations of quasi- $K$-monotone or generalized pseudo- $K$ monotone mappings.

Theorem 3.2. Let $X, Y, \Gamma_{a}$, and $K$ be as in Proposition 3.1, $T: X \rightarrow 2^{Y}$ $K$-quasi-bounded and either demiclosed and quasi-K-monotone or generalized pseudo-K-monotone, and $G: X \rightarrow K(Y)$ bounded, demiclosed and of type $\left(K S_{+}\right)$. Suppose that $C: X \rightarrow 2^{Y}$ is such that $T+C+\mu G$ is A-proper w.r.t. $\Gamma_{a}$ for $\mu>0$ and $Q_{n} C: X_{n} \rightarrow C K\left(Y_{n}\right)$ u.s.c. Moreover, suppose that either one of the following three conditions holds:
(i) $T+C$ satisfies condition ( + ) and $T, G$, and $C$ are odd on $X \backslash B(0, r)$ for some $r>0$;
(ii) $T+C$ satisfies condition $(+)$, the mappings $K, K_{n}=Q^{*} K$ and $M_{n}$ satisfy conditions $\left(\mathrm{a}_{1}\right)-\left(\mathrm{a}_{3}\right)$ of Proposition 3.1, condition $(\mathrm{C} 2)$, and $(u, K(x)) \geqslant 0$, $(v, K x) \geqslant 0,(w, K(x)) \geqslant 0$ for all $u \in T(x), v \in G(x)$, and $w \in C(x)$ with $\|x\| \geqslant r$;
(iii) $K, K_{n}$, and $M_{n}$ are as in (ii) and for each $f$ in $Y$ there exists $r_{f}>0$ such that $(u-f, K(x)) \geqslant 0,(v, K(x)) \geqslant 0$, and $(w, K(x)) \geqslant 0$ for all $u \in T(x)$, $v \in G(x)$, and $w \in C(x)$ with $\|x\|=r_{f}$.

Then, if $T+C$ satisfies condition $(++)$, the equation $f \in T(x)+C(x)$ is solvable for each $f$ in $Y$.

Remark 3.4. For $C=0$ and $T$ quasi- $K$-monotone, Theorem 3.2, parts (i) and (ii), was proved by Petryshyn [21] in the single-valued case and it extends
some results of Browder [4], Calvert and Webb [10], Fitzpatrick [12], Rockafellar [24], and others (see [21] for more details) when $Y=X^{*}, K=I$ and $T$ is quasi-monotone or maximal monotone. In the case when $T$ is a maximal monotone mapping from $X$ into $2^{x^{*}}$ and $C$ is a single-valued completely continuous mapping, the conclusion of our theorem was proved by Fitzpatrick [12] under either (i) or (ii).

Remark 3.5. As $C$ in our Theorem one can choose a completely continuous (multivalued) mapping or a $K$-quasi-bounded generalized pseudo- $K$-monotone mapping with $K$ linear such that $(u, K(x)) \geqslant-\psi(\|x\|)\|x\|$ for all $u \in C(x)$ with $\psi: R^{+} \rightarrow R$ a continuous function or a sum of two such mappings.

We say that $T: X \rightarrow 2^{Y}$ is completely continuous if $x_{n} \longrightarrow x_{0}$ in $X$ and $y_{n} \in T\left(x_{n}\right)$ imply that some subsequence $y_{n_{k}} \rightarrow y_{0} \in T\left(x_{0}\right)$.

As an application of Theorem 2.6 and Remark 2.7(c) we have the following result:

Theorem 3.3. Let $X$ be a reflexive separable Banach space, $T: X \rightarrow 2^{X^{*}} a$ quasi-bounded generalized pseudomonotone mapping and $C: X \rightarrow C K\left(X^{*}\right)$ completely continuous and such that

$$
\begin{equation*}
\|u+v\|+\frac{(u+v, x)}{\|x\|} \rightarrow \infty \quad \text { as } \quad\|x\| \rightarrow \infty \tag{+}
\end{equation*}
$$

for all $u \in T(x)$ and $v \in C(x)$ and condition $\left(^{*}\right)$ below holds for some $\psi$ (which is so if, e.g., for some $R>0$, either $T$ is bounded on $X \backslash B(0, R)$ or $(u, x) \geqslant-c\|x\|$ for $u \in T(x),\|x\| \geqslant R$ and some $c$ ).

Then the equation $f \in(T+C)(x)$ is solvable for each $f$ in $X^{*}$.
Proof. Since for each $f$ in $X^{*}, T-f$ and $C$ satisfy the same conditions that $T$ and $C$ do, it is sufficient to show that $0 \in(T+C)(x)$ is solvable. Moreover, by the results of Asplund [1], we may assume that $X$ and $X^{*}$ are locally uniformly convex since the "monotonicity" and continuity properties of a mapping are not affected by renorming its domain and range space. Moreover, ( $3^{+}$) holds in these renormed spaces.

Now by condition ( $3^{+}$), if for some $r>0,\|u+v\|+((u+v, x)\|x\|) \leqslant r$ for $u \in T(x)$ and $v \in C(x)$, then $\|x\| \leqslant R$ for some $R>0$. Let $\psi: R^{+} \rightarrow R^{+}$be a continuous increasing function such that $\psi(t)=0$ for $t \leqslant R$ and for $u \in T(x), v \in C(x)$

$$
\begin{equation*}
\lim _{\|x\| \rightarrow \infty}\left(\psi(\|x\|)-\frac{|(u+v, x)|}{\|x\|}\right)=\infty \tag{*}
\end{equation*}
$$

Let $J_{0}$ be a duality mapping corresponding to this $\psi$. Then the mapping $T+C+J_{0}$ is coercise since for $u \in T(x), v \in C(x)$ and $w \in J_{0}(x)$ we have that

$$
\frac{(u+v+w, x)}{\|x\|} \geqslant \psi(\|x\|)-\frac{|(u+v, x)|}{\|x\|} \rightarrow \infty \quad \text { as } \quad\|x\| \rightarrow \infty
$$

Let $J$ be the normalized duality mapping. Then, since $T+J_{0}$ is generalized pseudomonotone (see Lemma 3.2) and quasi-bounded and $J$ is of type ( $S_{+}$), the mapping $T+J_{0}+\mu J$ is $A$-proper for each $\mu>0$ w.r.t. the injective scheme $\Gamma_{I}=\left\{X_{n}, V_{n} ; X_{n}^{*}, V_{n}^{*}\right\}$. Consequently, $T+J_{0}+C+\mu J$ is $A$-proper w.r.t. $\Gamma_{l}, \mu>0$.

Now, from the above discussion we see that the mappings $T+C+J_{0}$ and $J$ satisfy all the assumptions of Theorem 2.6 (see Remark 2.7(b, c)). Hence, there exists $x_{0} \in X$ such that $0 \in\left(T+C+J_{0}\right)\left(x_{0}\right)$. If $x_{0}=0$, then clearly $0 \in(T+C)\left(x_{0}\right)$. Suppose that $x_{0} \neq 0$. Then $u+v+w=0$ for some $u \in T\left(x_{0}\right)$, $\boldsymbol{v} \in C\left(x_{0}\right)$ and $w \in J_{0}\left(x_{0}\right)$. This implies that $\psi\left(\left\|x_{0}\right\|\right)=\|w:=\| u-w^{\prime}$ and $\left|x_{0}\right| \leqslant R$ since

$$
0=\frac{\left(u+v+w, x_{0}\right)}{\left\|x_{0}\right\|}=\psi\left(\left|x_{0}\right|\right)+\frac{\left(u+v, x_{0}\right)}{\left\|x_{0}\right\|} .
$$

By the definition of $\psi$, we have $\|u+v\|=\psi\left(\left\|x_{0}\right\|\right)=0$, i.e., $0 \in(T+C)\left(x_{0}\right)$. Q.E.D.

Remark 3.6. If $T$ is of semibounded variation in Theorem 3.3, then its conclusion is valid if $T$ is bounded, since it is bounded and generalized pseudomonotone mapping (see Lemma 3.3 and Proposition 3.5). Moreover, if $T$ is maximal monotone defined on all of $X$, then our condition $\left(3^{+}\right)$is equivalent to

$$
\|u+v\|+\frac{(v, x)}{\|x\|} \rightarrow \infty \quad \text { as } \quad\|x\| \rightarrow \infty \quad \text { for all } u \in T(x), \quad v \in C(x)
$$

Thus, our Theorem 3.3 includes a result of Wille [27] with $T$ maximal monotone. For $C=0$ and $T$ single-valued bounded and generalized-pseudomonotone with $(T x, x) \geqslant-k\|x\|$, see Browder [8].

In the next two theorems we extend the corresponding results of [19] to the case of noninjective and nonlinear perturbations of condensing like mappings as defined below.

For a bounded subset $A$ of a Banach space $X$ we define the ball-measure of noncompactness as $\chi(A)=\inf \{r>0 \mid A$ can be covered by a finite number of balls of radius less than $r$ with centers in $X\}$. A mapping $T: D \subset X \rightarrow C K(Y)$ is said to be $k$-ball-contractive if for each bounded subset $Q \subset D, \chi(T(Q))$ $k \chi(Q)$; it is ball-condensing if for each $Q \subset D$ with $\chi(Q) \neq 0, \chi(T(Q))<\chi(Q)$.

Theorem 3.4. Let $X$ and $Y$ be Banach spaces, $\Gamma_{b}=\left\{X_{n}, V_{n} ; X_{n}, P_{n}\right\}$ a projectionally complete scheme for $(X, X)$ with $\left\|P_{n}\right\|=1$ and $M$ a continuous linear mapping of $X$ onto $Y$ which satisfies the following condition:
(1) there exists a constant $c>0$ such that $\chi(M(Q)) \geqslant c \chi(Q)$ for any bounded set $Q \subset X$.

Suppose that $T: X \rightarrow C K(Y)$ is bounded u.s.c. and such that
(2) $\quad \chi(T(Q)) \leqslant c \chi(Q)$ for each bounded $Q \subset X$.

Moreover, suppose that there exists $r>0$ such that $T$ is odd on $X \backslash B(0, r)$ and that $(T-M)^{-1}$ maps relatively compact sets of $Y$ into bounded sets of $X$.

Then, if $T-M$ satisfies condition $(++), T-M$ maps $X$ onto $Y$.
Proof. Let $f_{0} \in Y$ be fixed and define

$$
\begin{aligned}
F(t, y) & =M^{-1}\left(T(y)-t f_{0}\right) \\
& =\left\{x \in X \mid M(x) \in T(y)-t f_{0}\right\} \quad \text { for all }(t, y) \in[0,1] \times X
\end{aligned}
$$

It is clear that the equation $f_{0} \in T(y)-M(y)$ is equivalent to the equation $y \in F(1, y)$.

We shall prove now that $F(t, y)$ satisfies all the assumptions of Theorem 2.1. First we prove that $F(t, y)$ is u.s.c. on $[0,1] \times X$. If $F$ were not u.s.c. at some point $\left(t_{0}, y_{0}\right)$, then there would exist a neighborhood $U$ of $F\left(t_{0}, y_{0}\right)$ and sequences $y_{n} \rightarrow y_{0}, t_{n} \rightarrow t_{0}$ and $x_{n} \in F\left(t_{n}, y_{n}\right) \backslash U$ for all $n$. Then we would have $M\left(x_{n}\right)=$ $u_{n}-t_{n} f_{0}$ for some $u_{n} \in T\left(y_{n}\right)$. By the u.s.c. of $T$ we may assume that $u_{n} \rightarrow u_{0} \in T\left(y_{0}\right)$, which implies that $\chi\left(\left\{M\left(x_{n}\right)\right\}\right)=0$. By (1), $\chi\left(\left\{x_{n}\right\}\right)=0$ and consequently, $x_{n_{k}} \rightarrow x_{0}$ for some subsequence $\left\{x_{n_{k}}\right\}$ with $x_{0} \notin U$. Since $M$ is continuous, we have that $M\left(x_{0}\right) \in T\left(y_{0}\right)-t_{0} f_{0}$, i.e., $x_{0} \in F\left(t_{0}, y_{0}\right) \subset U$, a contradiction. Using similar arguments, we obtain that $M^{-1}$ is also u.s.c. on $Y$. Since $M$ is continuous and linear with $R(M)=Y$, the Open Mapping Theorem implies that $M$ maps open sets of $X$ into open sets of $Y$ and consequently, $M^{-1}$ is lower semicontinuous.

Next we prove that for each $t \in[0,1], F_{t}=F(t, \cdot)$ is 1-ball-contractive. Indeed, for each bounded subset $Q \subset X$ we have

$$
M(F([0,1] \times Q)) \subset\left\{T(y)-t f_{0} \mid y \in Q, t \in[0,1]\right\}
$$

and consequently, for cach $t \in[0,1], \chi\left(M\left(F_{t}(Q)\right)\right) \leqslant \chi(T(Q)) \leqslant c \chi(Q)$.
Assumption (1) implies that $F_{t}(Q)$ is bounded and $c \chi\left(F_{t}(Q)\right) \leqslant \chi\left(M\left(F_{t}(Q)\right)\right) \leqslant$ $c \chi(Q)$, i.e., $\chi\left(F_{t}(Q)\right) \leqslant \chi(Q)$ for each $t \in[0,1]$. Then, as shown in [17], we have that $\mu I+I-F_{t}$ is $A$-proper with respect to $\Gamma_{b}$ for each $t \in[0,1]$ and $\mu>0$.

Now we claim that $I-F_{t}$ satisfies condition ( + ) uniformly for $t \in[0,1]$. Let $g_{n} \equiv x_{n}-u_{n} \rightarrow g$ for some $u_{n} \in F\left(t_{n}, x_{n}\right)$. Then $M\left(u_{n}\right)=v_{n}-t_{n} f_{0}$ for some $v_{n} \in T\left(x_{n}\right)$ and $M\left(x_{n}\right)-v_{n}=M\left(g_{n}\right)+M\left(u_{n}\right)-v_{n}=M\left(g_{n}\right)-t_{n} f_{0}$, or $x_{n} \in(M-T)^{-1}\left(M\left(g_{n}\right)-t_{n} f_{0}\right)$. By the relative compactness of $\left\{M\left(g_{n}\right)-t_{n} f_{0}\right\}$ we obtain that $\left\{x_{n}\right\}$ is bounded. This implies that there exist $r_{0} \geqslant r$ and $\gamma>0$ such that $\|y-u\| \geqslant \gamma$ for all $u \in F_{t}(y)$ with $\|y\|=r_{0}$ and $t \in[0,1]$. If not, then there would exist $\left\{t_{n}\right\} \subset[0,1]$ and $\left\{y_{n}\right\} \subset X$ with $t_{n} \rightarrow t$ and $\left\|y_{n}\right\| \rightarrow \infty$ and for some $u_{n} \in F_{t_{n}}\left(y_{n}\right),\left\|y_{n}-u_{n}\right\| \rightarrow 0$, in contradiction to condition $(+)$ for $I-F_{t}$. Thus such $r_{0}>0$ and $\gamma>0$ exist.

Set $H_{t}=I-F_{t}$ for each $t \in[0,1]$. Since $T$ and $M$ are odd on $X\left(B\left(0, r_{0}\right)\right.$, we have that $H_{0}(-y)=-H_{0}(y)$ for all $y \notin B\left(0, r_{0}\right)$. From this and our discussion above it follows that $H_{t}$ satisfies all the hypotheses of 'I'heorem 2.1 with $G=I$ and $f=0$ except (H3) and condition $(++)$. The rest of the proof will be devoted to establishing the validity of $(\mathrm{H} 3)$ for $H_{t}$. Thus, let for some $\mu>0$, $t_{n} \in[0,1]$, and $x_{n} \in \partial B_{n}\left(0, r_{0}\right)$, we have $0 \in P_{n} H\left(t_{n}, x_{n}\right)+\mu x_{n}=(\mu-1) x_{n}-$ $P_{n} M^{-1}\left(T\left(x_{n}\right)-t_{n} f_{0}\right)$ or $(\mu+1) x_{n}=P_{n}\left(y_{n}\right)$ for some $y_{n} \in M^{-1}\left(T\left(x_{n}\right)-t_{n} f_{0}\right)$. Then $M\left(y_{n}\right) \in T\left(x_{n}\right)-t_{n} f_{0} \quad$ and consequently, $c \chi\left(\left\{y_{n}\right\}\right) \leqslant \chi\left(\left\{M\left(y_{n}\right)\right\}\right) \leqslant$ $\chi\left(\left\{T\left(x_{n}\right)\right\}\right) \leqslant c_{\chi}\left(\left\{x_{n}\right\}\right)$. Hence,

$$
\chi\left(\left\{(\mu+1) x_{n}\right\}\right)=\chi\left(\left\{P_{n}\left(y_{n}\right)\right\}\right) \leqslant \chi\left(\left\{y_{n}\right\}\right) \leqslant \chi\left(\left\{x_{n}\right\}\right),
$$

a contradiction unless $\left\{x_{n}\right\}$ is precompact. It follows that we can choose subsequences $\left\{t_{n_{k}}\right\}$ and $\left\{x_{n_{k}}\right\}$ such that $t_{n_{k}} \rightarrow t_{0}$ and $x_{n_{k}} \rightarrow x_{0}$. Let $u_{n_{k}} \in T\left(x_{n_{k}}\right)-$ $t_{n_{k}} f_{0}$ be such that $y_{n_{k}} \in M^{-1}\left(u_{n_{k}}\right)$. By the u.s.c. of $T, u_{m} \rightarrow u_{0} \in T\left(x_{0}\right)-t_{0} f_{0}$ for some subsequence $\left\{u_{m}\right\} \subset\left\{u_{n_{k}}\right\}$. By the u.s.c. of $M^{-1}, y_{m_{i}} \rightarrow y_{0} \in M^{-1}\left(u_{0}\right)$ for some subsequence $\left\{y_{m_{i}}\right\} \subset\left\{y_{m}\right\}$. Then, $P_{m_{i}}\left(y_{m_{i}}\right) \rightarrow y_{0}=(1+\mu) x_{0}$. Since $M^{-1}$ is lower semicontinuous and $u_{m}=v_{m}-t_{m} f_{0}$ for some $v_{m} \in T\left(x_{m}\right)$ with $v_{m} \rightarrow v_{0} \in T\left(x_{0}\right)$, we have that for $y_{0} \in M^{-1}\left(u_{0}\right)$ there exists $z_{m_{i}} \in M^{-1}\left(T\left(x_{m_{i}}\right)-\right.$ $t_{0} f_{0}$ ) such that $z_{m_{i}} \rightarrow y_{0}$. Whence, $(1+\mu) x_{m_{i}}-P_{m_{i}}\left(z_{m_{i}}\right) \rightarrow 0$ as $i \rightarrow \infty$, which shows that (H3) holds. Now, as in Theorem 2.1, we obtain an $\mu_{0}>0$ such that for each $\mu \in\left(0, \mu_{0}\right)$ there exists $y_{u} \in X$ with $0 \in \mu y_{\mu}+H_{1}\left(y_{\mu}\right)=-$ $(\mu+1) y_{\mu}-M^{-1}\left(T\left(y_{\mu}\right)-f_{0}\right)$, or $f_{0} \in(\mu+1) M\left(y_{u}\right)-T\left(y_{\mu}\right)$. Lct $\mu_{k} \in\left(0, \mu_{0}\right)$ with $\mu_{k} \rightarrow 0$. Then, by condition $(++)$ for $M-T$, there exists $y \in X$ such that $f_{0} \in M(y)-T(y)$. Since $f_{0} \in Y$ was arbitrary, we have that $M-T$ maps $X$ onto $Y$.
Q.E.D.

Remark 3.7. It is easy to check that if $K: X \rightarrow Y^{*}$ with $|K x| \rightarrow \infty$ as $\|x\| \rightarrow \infty$ and if

$$
(T x, K x) \geqslant c_{1}\|K x\|^{2}, \quad(M x, K x) \leqslant c_{2} \| x x{ }^{2}+\phi(K x \|)
$$

with $c_{1}-c_{2}>0$ and $\phi(r) / r \rightarrow 0$ as $r \rightarrow \infty$, then $T-M$ is $K$-coercive and, in particular, satisfies condition $(t)$.

Next we shall consider the case of nonlinear $M$. For such $M$ we have the following:

Theorem 3.5. Let $X$ and $Y$ be Banach spaces, $\Gamma_{b}=\left\{Y_{n}, V_{n} ; Y_{n}, Q_{n}\right\} a$ projectionally complete scheme for $(Y, Y)$ with $\left\|Q_{n}\right\|=1$, M a mapping of $D \subset X$ onto $Y$ with $M^{-1}$ u.s.c. and bounded, and $T: D \rightarrow C K(Y)$ u.s.c. and bounded. Suppose that $M-T$ satisfies conditions $(+)$ and $(1+)$ and that $T M^{-1}$ : $Y \rightarrow C K(Y)$ is 1-ball contractive.

Moreover, suppose that either one of the following conditions holds:
(i) $M$ and $T$ are odd on the symmetric w.r.t. 0 set $D$.
(ii) There exists $R>0$ such that whenever $0 \in t T(x)-M(x)$ holds for any $x \in D$ and $t \in(0,1]$, then $\|x\| \leqslant R$.

Then $T-M$ maps $D$ onto $Y$.
Proof. Let $f_{0} \in Y$ be fixed and consider the equation $f_{0} \in M(x)-T(x)$. Set $y=M(x)$. Then it is easy to see that the last equation is equivalent to the equation $f_{0} \in y-T M^{-1}(y)$.

Let us now prove that $I-T M^{-1}$ satisfies conditions $(+)$ and $(++)$. Let $\left\{y_{n}\right\} \subset Y$ be such that $y_{n}-u_{n} \rightarrow g$ for some $u_{n} \in T M^{-1}\left(y_{n}\right)$. Then $u_{n} \in T\left(x_{n}\right)$ with $x_{n} \in M^{-1}\left(y_{n}\right)$ and consequently, $M\left(x_{n}\right)-u_{n}=y_{n}-u_{n} \rightarrow g$. Since $M-T$ satisfies condition $(+),\left\{x_{n}\right\}$ is bounded and by the boundedness of $T$, $\left\|y_{n}\right\|=\left\|M\left(x_{n}\right)\right\| \leqslant\left\|M\left(x_{n}\right)-u_{n}\right\|+\left\|u_{n}\right\| \leqslant K$ for all $n$ and some $K>0$. Next, let $\left\{y_{n}\right\}$ be bounded and such that $y_{n}-u_{n} \rightarrow g$ for some $u_{n} \in T M^{-1}\left(y_{n}\right)$. Then for some $x_{n} \in M^{-1}\left(y_{n}\right), u_{n} \in T\left(x_{n}\right)$ and $M\left(x_{n}\right)-u_{n}=y_{n}-u_{n} \rightarrow g$. Since $M-T$ satisfies condition $(++)$, there exists $x \in X$ such that $g \in M(x)-$ $T(x)$ or $g \in y-T M^{-1}(y)$ with $y=M(x)$. Hence $I-T M^{-1}$ satisfies conditions $(+)$ and $(++)$.

Now we claim that there exist $\gamma>0$ and $r_{f_{0}}>c(c>0$ given $)$ such that for all $t \in[-1,1]$ and $y \in \partial B\left(0, r_{f_{0}}\right)$

$$
\begin{equation*}
\left\|y-u-t f_{0}\right\| \geqslant \gamma \quad \text { for all } u \in T M^{-1}(y) \tag{3.8}
\end{equation*}
$$

If not, then there exist $\left\{t_{n}\right\} \subset[-1,1]$ and $\left\{y_{n}\right\} \subset Y$ with $t_{n} \rightarrow t_{0}$ and $\left\|y_{n}\right\| \rightarrow \infty$ and $\left\|y_{n}-u_{n}-t_{n} f_{0}\right\| \rightarrow 0$ for some $u_{n} \in T M^{-1}\left(y_{n}\right)$. Thus, $y_{n}-u_{n} \rightarrow t_{0} f_{0}$ with $\left\{y_{n}\right\}$ unbounded, in contradiction to condition $(+)$ for $I-T M^{-1}$.

Case (1). Assume that $T$ and $M$ are odd. We claim that $H_{t}=I-$ $T M^{-1}-t f_{0}$ satisfies hypothesis (H3) of Theorem 2.1 for $f=0$ with $G=I$ i.e., if for some $\mu>0, t_{n} \in[0,1]$, and $y_{n} \in \partial B_{n}\left(0, r_{f_{0}}\right)$ we have that

$$
\begin{equation*}
0 \in(1+\mu) y_{n}-Q_{n} T M^{-1}\left(y_{n}\right)-t_{n} Q_{n}\left(f_{0}\right) \tag{3.9}
\end{equation*}
$$

then there exists $\left\{t_{n_{k}}\right\}$ such that $t_{n_{k}} \rightarrow t_{0}$ and $t_{0} Q_{n_{k}}\left(f_{0}\right)-(1+\mu) y_{n_{k}}+Q_{n_{k}}\left(v_{n_{k}}\right)$ $\rightarrow 0$ for some $v_{n_{k}} \in T M^{-1}\left(y_{n_{k}}\right)$. Indeed, from (3.9) we get that for some $v_{n_{k}} \in T M^{-1}\left(y_{n_{k}}\right), 0=(1+\mu) y_{n_{k}}-Q_{n_{k}}\left(v_{n_{k}}\right)-t_{n_{k}} Q_{n_{k}}\left(f_{0}\right)$, which implies that
$t_{0} Q_{n_{k}}\left(f_{0}\right)-(1+\mu) y_{n_{k}}+Q_{n_{k}}\left(v_{n_{k}}\right)=\left(t_{0}-t_{n_{k}}\right) Q_{n_{k}}\left(f_{0}\right) \rightarrow 0 \quad$ as $\quad k \rightarrow \infty$.
Now since $T$ and $M$ are odd, we have that $H_{0}+\mu I=(1+\mu) I-T M^{-1}$ is odd and hence hypothesis ( H 4 ) of Theorem 2.1 holds. Consequently, by Theorem 2.1 there exists $y \in Y$ such that $0 \in H_{1}(y)=y-T M^{-1}(y)-f_{0}$.

Case (2). Suppose that condition (ii) holds. We claim that there exists a constant $C$ such that $\lambda y \notin T M^{-1}(y)$ for $\|y\| \geqslant C$ and $\lambda \geqslant 1$. Indeed, if such a $C$ did not exist, then we could find sequences $\left\{y_{n}\right\} \subset Y$ and $\left\{\lambda_{n} \mid \lambda_{n} \geqslant 1\right\}$ with
$\left\|y_{n}\right\| \rightarrow \infty$ and $\lambda_{n} y_{n} \in T M^{-1}\left(y_{n}\right)$. Then $\lambda_{n} y_{n}=v_{n}$ for some $v_{n} \in T\left(u_{n}\right)$ and $u_{n} \in M^{-1}\left(y_{n}\right)$. Consequently, $y_{n}-\left(1 / \lambda_{n}\right) v_{n}=M\left(u_{n}\right)-\left(1 / \lambda_{n}\right) v_{n}=0$, which by (ii) implies that $\left\{u_{n}\right\}$ is bounded. Since $T$ is bounded and $\left\{1 / \lambda_{n}\right\} \subset(0,1]$, we have that the sequence $\left\{y_{n}\right\}=\left\{\left(1 / \lambda_{n}\right) v_{n}\right\}$ is bounded, in contradiction to our assumption on $\left\{y_{n}\right\}$. It is clear now that for each $\mu \geqslant 0, \lambda(1+\mu) y \notin T M^{-1}(y)$ for all $\|y\| \geqslant C$ and $\lambda \geqslant 1$. It follows from (3.8) that there exists $\mu_{0} \in(0,1)$ such that $\left\|(1+\mu) y-u-t f_{0}\right\| \geqslant \gamma / 2$ for $t \in[-1,1], \mu \in\left(0, \mu_{0}\right), u \in T M^{-1}(y)$ with $\|y\|=r_{f_{0}}$. In view of this, a slight modification of Proposition 1.4 in [19] applied to $T M^{-1}$ and $(1+\mu) I, \mu \in\left(0, \mu_{0}\right)$, implies the existence of $y \in B\left(0, r_{f_{0}}\right)$ such that $f_{0} \in(1+\mu) y_{\mu}-T M^{-1}\left(y_{\mu}\right)$ with $\mu \in\left(0, \mu_{0}\right)$. Let $\mu_{k} \in\left(0, \mu_{0}\right)$ be such that $\mu_{k} \rightarrow 0$ and $y_{k} \in B\left(0, r_{f_{0}}\right)$ with $f_{0} \in\left(1+\mu_{k}\right) y_{k}-T M^{-1}\left(y_{k}\right)$. Let $u_{k} \in T M^{-1}\left(y_{k}\right)$ be such that $f_{\mathbf{0}}=\left(1+\mu_{k}\right) y_{k}-u_{k}$. Then $y_{k}-u_{k}=-\mu_{k} y_{k}+$ $f_{0} \rightarrow f_{0}$ as $k \rightarrow \infty$ and consequently, since $I-T M^{-1}$ satisfies condition $(++)$, there exists $y \in Y$ such that $f_{0} \in y-T M^{-1}(y)$, or $f_{0} \in M(x)-T(x)$ for some $x \in M^{-1}(y)$. Since $f_{0}$ was arbitraty, $M-T$ maps $D$ onto $Y$. Q.E.D.

When $M$ is bijective and $T$ single-valued, Theorem 3.5 was obtained by Petryshyn and Fitzpatrick [22]. We note that conditions (1) and (2) of Theorem 3.4 imply that $M^{-1}$ is u.s.c. and bounded and $T M^{-1}$ is u.s.c. and 1 -ball-contractive. If $T$ is a convex mapping (i.e., $X$ is partially ordered by $" \leqslant "$ and $T(\alpha x+(1-\alpha) y) \leqslant \alpha T(x)+(1-\alpha) T y$ for all $x, y \in X$ and $\alpha \in(0,1)$ ) and $M$ is either linear or $K$-monotone with $K$ linear, then $T M^{-1}(y)$ is convex for each $y$ in $Y$. For M and $T$ single-valued with $M^{-1}(y)$ convex for each $y$ in $V$ and $M^{-1} T$ ball-condensing, the ontoness of $M-T$ was established by Webb [26] under either (i) or (ii).

## 4. Elliptic Boundary Value Problems Involving Semibounded Operators with Completely Continuous Perturbations

In the first part of this section we use Theorems 2.4 and 3.3 to establish the existence of weak solutions for boundary value problems for quasilinear elliptic operators in divergence form which involve completely continuous perturbations of operators with semibounded variation acting in $W_{p}{ }^{m}(Q)$. The latter class of elliptic operator equations was first studied by Browder [3] and Dubinsky [11] and later by Pohodjayev [23], Skrypnik [25], and others (see [5, 25]). For the above-mentioned class of elliptic operator equations our existence results extend those of $[3,11]$.

In the second part of this section we apply Theorems 2.4 and 2.6 to establish the existence of strong solutions (i.e., functions lying in a closed subspace $V$ of $W_{2}{ }^{m}$ ) for nonlinear ordinary differential equations of order $m$ involving completely continuous perturbations $B: V \rightarrow L_{2}$ of operators $A: V \rightarrow L_{2}$ with semibounded variation. Rather than obtaining the most general results, our
aim is to show how one can choose the operators $K, K_{n}, G, M_{n}$ and a suitable admissible scheme so that Theorems 2.4 and 2.6 are applicable.

Let $Q$ be a bounded domain in $R^{n}$ with a sufficiently smooth boundary $\partial Q$ so that the Sobolev Imbedding Theorem holds on $Q$ (see [7, 16]). For fixed $p \in(1, \infty)$, let $L_{p} \equiv L_{p}(Q)$ denote the real Banach space of functions $u(x)$ on $Q$ with norm $\|u\|_{p}$. If $\alpha=\left(\alpha_{1}, \ldots, \alpha_{n}\right)$ is a multiindex of nonnegative integers, we denote by $D^{\alpha}=\partial^{\alpha_{1}} / \partial x_{n}^{\alpha_{1}} \cdots \partial^{\alpha_{n}} / \partial x_{n}^{\alpha_{n}}$ a differential operator of order $|\alpha|=$ $\alpha_{1}+\cdots+\alpha_{n}$. If $m$ is a nonnegative integer, $W_{p}{ }^{m} \equiv W_{p}{ }^{m}(Q)$ denotes the real Sobolev space of all $u \in L_{p}$ whose generalized derivatives $D^{\alpha} u,|\alpha| \leqslant m$, also lie in $L_{y} . W_{p}{ }^{m}$ is a separable uniformly convex Banach space with respect to the norm $\|\left. u\right|_{h n, p}=\left(\sum_{|\alpha| \leqslant m}\left\|D^{x} u\right\|_{p}^{p}\right)^{1 / p}$. In case $p=2$, we get the Hilbert space $W_{2}{ }^{m}$ with the corresponding inner product $(\cdot, \cdot)_{m}$. Let $C_{c}{ }^{\infty}(Q)$ be the family of infinitely differentiable functions with compact support in $Q$ considered as a subset of $W_{p}{ }^{m}$ and let $W_{p}{ }^{m}$ be the completion in $W_{p}{ }^{m}$ of $C_{c}{ }^{\infty}(Q)$. Let $\langle u, v\rangle=$ $\int_{Q} u v d x$ denote the natural pairing between $u \in L_{p}$ and $v \in L_{a}$ with $q=p(p-1)^{-1}$ and let $R^{S_{m}}$ be the vector space whose elements are $\xi=\left\{\xi_{\alpha}| | \alpha \mid \leqslant m\right\}$.

Let $V$ be a closed subspace of $W_{p}{ }^{m}$ such that $W_{p}{ }^{n} \subseteq V \subseteq W_{p}{ }^{m}$. For a given $f \in L_{q}$, the $B V$ problem corresponding to $V$ is the problem of finding a generalized solution $u \in V$ of the equation

$$
\begin{equation*}
\sum_{|\alpha| \leqslant m}(-1)^{|\alpha|} D^{\alpha} A_{\alpha}\left(x, u, \ldots, D^{m} u\right)+\sum_{|\beta| \leqslant m-1}(-1)^{|\beta|} D^{\beta} B_{8}\left(x, u, \ldots, D^{m-1} u\right)=f(x) \tag{4.1}
\end{equation*}
$$

such that for all $v$ in $V$ the following identity holds:

$$
\begin{equation*}
\sum_{|\alpha| \leqslant m}\left\langle A_{\alpha}\left(x, u, \ldots, D^{m} u\right), D^{\alpha} v\right\rangle+\sum_{|\beta| \leqslant m-1}\left\langle B_{p}\left(x, u, \ldots, D^{m-1} u\right), D^{\beta} v\right\rangle=\langle f, v\rangle . \tag{4.2}
\end{equation*}
$$

The choices $V=\dot{W}_{p}{ }^{m}$ and $V=W_{p}^{m}$ lead to the generalized Dirichlet and Neumann $B V$ problems for (4.1), respectively.

To formulate the $B V P$ with respect to $V$ as an equivalent operator equation involving mappings from $V$ to $V^{*}$ to which Theorems 2.4 and 3.3 are applicable, we impose the following conditions on the nonlinear functions $A_{\alpha}(x, \xi)$ : $Q \times R^{s_{m}} \rightarrow R^{1}$ and $B_{\beta}(x, \eta): Q \times R^{s_{m-1}} \rightarrow R^{1}$.
(A1) For each $|\alpha| \leqslant m, A_{\alpha}(x, \xi)$ satisfies the Carathéodory conditions, i.e., it is measurable in $x \in Q$ for fixed $\xi \in R^{S_{m}}$ and continuous in $\xi \in R^{S_{m}}$ for almost all $x \in Q$, and there exists a constant $c_{0}>0$ such that

$$
\left|A_{\alpha}(x, \xi)\right| \leqslant c_{0}\left\{1+\sum_{|\gamma| \leqslant m}\left|\xi_{\alpha}\right|^{p_{\gamma \alpha}}\right\}
$$

with $p_{\gamma \alpha} \leqslant 1$ for $|\alpha|=|\gamma|=m$, while in the lower order cases the exponents may have larger upper bounds (see [8]).
(A2) For any given ball $B(0, R) \subset V$ and $u, v \in B(0, R)$ we have

$$
\sum_{|\alpha| \leqslant m}\left\langle A_{\alpha}\left(x, u, \ldots, D^{m} u\right)-A_{\alpha}\left(x, v, \ldots, D^{m} v\right), D^{\alpha}(u-v)\right\rangle \geqslant-c\left(R,\|u-v\|_{m-1, p}\right),
$$

where $c(R, \rho) \geqslant 0$ is continuous in $R$ and $\rho$ and such that $c(R, t \rho) / t \rightarrow 0$ as $t \rightarrow 0^{+}$ for any fixed $R$ and $\rho$.
(B1) For each $|\beta| \leqslant m-1$ and each $u$ in $W_{p}^{m-1}$ the mapping $u \rightarrow C_{p}(u) \equiv$ $B_{B}\left(x, u, D u, \ldots, D^{m-1} u\right)$ yields a continuous and bounded mapping of $W_{p}^{m_{2}-1}$ into $L_{q}, q=p(p-1)^{-1}$.

Let us add in passing that it is not hard to show that condition (B1) holds if, for example, $B_{\alpha}: R^{S_{m-1}} \rightarrow R^{1}$ satisfies the Carathéodory conditions and there exist constants $b_{\alpha} \geqslant 0$ and a function $b(x) \in L_{q}$ such that for each $|\beta| \leqslant m-1$

$$
\begin{equation*}
\left|B_{\beta}(x, \eta)\right| \leqslant \sum_{|\alpha| \leqslant m-1} b_{\alpha}\left|\eta_{\alpha}\right|^{p-1}+b(x) \quad\left(\eta \in R^{S_{n-1}}, x \in \underset{\sim}{O}(\text { a.e. })\right) . \tag{4.3}
\end{equation*}
$$

Now it follows from assumptions (A1) and (B1) and the standard results on Nemytsky operators (e.g., [16]) that the generalized forms

$$
\begin{array}{ll}
a(u, v)=\sum_{|\alpha| \leqslant m}\left\langle A_{\alpha}\left(x, u, \ldots, D^{m} u\right), D^{\alpha} v\right\rangle & \left(u, v \in W_{p}^{m}\right), \\
\left.b(u, v)=\sum_{\{\beta \mid \leqslant m-1}\left\langle B_{8}\left(x, u, \ldots, D^{m-1} u\right), D^{\alpha} v\right\rangle\right\rangle & \left(u, v \in \in W_{p}^{m}\right) \tag{4.5}
\end{array}
$$

are well defined on $W_{p}{ }^{m}$ and that for a given closed subspace $V$ of $W_{p}{ }^{m}$ with $\mathscr{W}_{p}{ }^{m} \subseteq V$ one can associate with $a(u, v)$ and $b(u, v)$ in a unique way bounded continuous mappings $A$ and $B$ of $V$ into $V^{*}$ such that

$$
\begin{equation*}
a(u, v)=(A u, v), \quad b(u, v)=(B u, v) \quad(u, v \in V) \tag{4.6}
\end{equation*}
$$

where $(A u, v)$ and $(B u, v)$ denote the values of the functionals $A u$ and $B u$ in $V^{*}$ at $v$ in $V$. Similarly, for each $f$ in $L_{q}$ there exists a unique $w_{f}$ in $V^{*}$ such that $\langle f, v\rangle=\left(w_{f}, v\right)$ for all $v$ in $V$. Consequently, in view of (4.6), Eq. (4.2) is equivalent to the operator equation

$$
\begin{equation*}
T u \equiv A u+B u=w_{f} \quad(u \in V) \tag{4.7}
\end{equation*}
$$

for a given $w_{f} \in V^{*}$ and the mapping $T=A+B: V \rightarrow V^{*}$.
In order to apply Theorems 2.4 and 3.3 to Eq. (4.7) or Eq. (4.2) we must first select our admissible approximation shceme $\Gamma$ for the pair ( $V, V^{*}$ ). Since $V$ is a separable uniformly convex Banach space, we may find a sequence of finite-dimensional subspaces $\left\{X_{n}\right\} \subset V$ such that $\operatorname{dist}\left(u, X_{n}\right)=\inf _{x \in X_{n}}\|u-x\|$ $\rightarrow 0$ for each $u$ in $V$ as $n \rightarrow \infty$ and so the scheme $\Gamma=\left\{X_{n}, V_{n} ; X^{*}{ }_{n}, V^{*}{ }_{n}\right\}$ is admissible for $\left(V, V^{*}\right)$, where $V_{n}: X_{n} \rightarrow V$ is the inclusion map and $V_{n}^{*}$ : $V^{*} \rightarrow X^{*}{ }_{n}$.

We are now in a position to apply our theorems to obtain the existence of solutions of elliptic boundary value problems of form (4.1) involving operators with semibounded variation.

Theorem 4.1. Suppose $Q \subset R^{n}$ is a bounded domain for which the Sobolev Imbedding Theorem is valid, $V$ is a closed subspace of $W_{p}{ }^{m}$ with $W_{p}{ }^{m} \subseteq V$ for which the hypothesis (A2) holds, and assumptions (A1) and (B1) are satisfied. Then Eq. (4.7) is solvable for each $w_{f}$ in $V^{*}$ provided that any one of the following conditions holds:
(D1) $A$ and $C$ are odd on $V \backslash B(0, r)$ for some $r>0$ and $T=A+B$ satisfies condition $(+)$ on $V$;
(D2) $a(u, u)+b(u, u) \geqslant 0$ on $V \backslash B(0, r)$ for some $r>0$ and $T=A+B$ satisfies condition $(+)$ on $V$;
(D3) $\|T u\|+\{a(u, u)+b(u, u)\} /\|u\|_{m, p} \rightarrow \infty$ as $\|u\|_{m, p} \rightarrow \infty$ for $u$ in $V$.
Proof. First, it follows from (A1) and (A2) that $A: V \rightarrow V^{*}$ is a bounded continuous mapping with semibounded variation. Hence, by Propositions 3.4 and 3.5 and Lemma 3.3 with $K=I$ and $G=J, A$ is strongly demiclosed and $A+\mu J$ is $A$-proper with respect to $\Gamma_{I}$ for each $\mu>0$. Now it follows from assumption (B1) that $B: V \rightarrow V^{*}$ is completely continuous. Indeed, if $\left\{u_{n}\right\}$ is a sequence in $V\left(C W_{p}{ }^{m}\right)$ such that $u_{n} \rightharpoonup u$ in $V$, then by the Sobolev Imbedding Theorem, $u_{n} \rightarrow u$ in $W_{p}^{m-1}$ and thus, by (B1), $C_{\beta}\left(u_{n}\right) \rightarrow C_{\beta}(u)$ in $L_{q}$ for each $|\beta| \leqslant m-1$. Since

$$
\left(B u_{n}-B u, v\right)=\sum_{|\beta| \leqslant m-1}\left\langle B_{\beta}\left(x, u_{n}, \ldots, D^{m-1} u_{n}\right)-B_{\beta}\left(x, u, \ldots, D^{m-1} u\right), D^{\beta} v\right\rangle
$$

for each $v$ in $V$, it follows by Hölder's inequality that

$$
\begin{aligned}
\left\|B u_{n}-B u\right\| & =\sup \left\{\left|\left(B u_{n}-B u, v\right)\right| \mid\|v\|_{W_{v}{ }^{m}}=1\right\} \\
& \leqslant \sum_{|\beta| \leqslant m-1}\left(\int\left|C_{B}\left(u_{n}\right)-C_{B}(u)\right|^{q} d x\right)^{1 / q} \rightarrow 0 \quad \text { as } \quad n \rightarrow \infty
\end{aligned}
$$

Consequently, $B$ is completely continuous. Now, since $A$ is strongly demiclosed and $B$ is completely continuous, $A+B$ satisfies condition ( ++ ). Indeed, let $\left\{u_{n}\right\}$ be any bounded sequence such that $A u_{n}+B u_{n} \rightarrow f$ in $V^{*}$ for some $f$ in $V^{*}$. Since $V$ is reflexive, there exists a subsequence $\left\{u_{n_{j}}\right\}$ of $\left\{u_{n}\right\}$ such that $u_{n_{j}} \longrightarrow u_{0}$ for some $u_{0}$ in $V$ as $j \rightarrow \infty$. Then $B u_{n j} \rightarrow B u_{0}$ and $A u_{n j} \rightarrow f-B u_{0}$ in $V^{*}$ as $j \rightarrow \infty$. This and the strong demiclosedness of $A$ imply that $A u_{0}+B u_{0}=f$, i.e., $A+B$ satisfies condition $(++)$. Finally, since $V$ is reflexive and $B$ is completely continuous, $B$ is compact. Thus, $A+B+\mu J: V \rightarrow V^{*}$ is $A$-proper w.r.t. $\Gamma_{I}$ for each $\mu>0$.

Consequently, if condition (D1) or (D2) holds, then the assertion of Theorem
4.1 follows from Theorem 2.4, while if condition (D3) holds, then the assertion of Theorem 4.1 follows from Theorem 3.3 in view of Proposition 3.5 .
Q.E.D.

Remark 4.1. In case $B \equiv 0$ and $T=A$ is coercive (in which case (D3) obviously holds), Theorem 4.1 was first proved by Browder [3] and Dubinsky [11]. Coercive elliptic operators of pseudomonotone type were first studied by Leray and Lions [15]. The study of elliptic equations involving odd operators was initiated by Pohodjayev [23] and continued by Browder [7, 8], Hess [13], and others (see $[8,16]$ ). In [8] Browder studied the solvability of elliptic equations involving operators of pseudomonotone type satisfying the growth condition (D3) under the additional condition that $(T u, u) \geqslant-k \|$ for all $u \in X$ and some constant $k$.

As our second application we consider the following $B V P$ for the nonlinear ordinary differential equation of order $m>1$ of the form

$$
\begin{align*}
\tilde{A}\left(x, u, u^{(1)}, \ldots, u^{(m)}\right)+\tilde{B}\left(x, u, u^{(1)}, \ldots, u^{(m-1)}\right)=h & \left(h \in L_{2}\right),  \tag{4.8}\\
W_{i}(u) \equiv \sum_{j=0}^{m-1}\left[\alpha_{i j} u^{(j)}(a)+\beta_{i j} u^{(j)}(b)\right]=0 & (0 \leqslant i \leqslant m), \tag{4.9}
\end{align*}
$$

where $\alpha_{i j}, \beta_{i j}$ are constants and the functions $\tilde{A}(x, \xi):[a, b] \times R^{m+1} \rightarrow R^{1}$ and $\tilde{B}(x, \eta):[a, b] \times R^{m} \rightarrow R^{1}$ satisfy the Caratheodory conditions and are such that
(a1) For each $u \in W_{2}^{m} \equiv W_{2}{ }^{m}([a, b])$, the map $u \rightarrow A(u) \equiv \tilde{A}(x, u(x), \ldots$, $\left.u^{m}(x)\right)$ yields a bounded continuous mapping of $W_{2}{ }^{m}$ into $L_{2}[a, b]$.
(a2) For each $u \in W_{2}^{m-1} \equiv W_{2}^{m-1}([a, b])$ the map $u \rightarrow B(u) \equiv \tilde{B}(x, u, \ldots$, $\left.u^{(m-1)}\right)$ yields a bounded continuous mapping of $W_{2}^{m-1}$ into $L_{2}$.

Let $V$ be a closed subspace of $W_{g^{m}}$ given by

$$
V=\left\{u \in W_{2}^{m} ; W_{i}(u)=0 \text { for } i=0,1, \ldots, m\right\} .
$$

Suppose further that $\widetilde{A}(x, \xi)$ satisfies the following condition:
(a3) For any given ball $B(0, R) \subset V$ and $u, v$ in $B(0, R)$ the function $\tilde{A}(x, \xi)$ satisfies the condition:
$\int_{a}^{b}\left[\tilde{A}\left(x, u, \ldots, D^{m} u\right)-\tilde{A}\left(x, v, \ldots, D^{m} v\right)\right] D^{m}(u-v) d x \geqslant-c\left(R,\|u-v\|_{w_{2}^{m-1}}\right)$,
where $c(R, \rho) \geqslant 0$ is continuous in $R$ and $\rho$ and such that $c(R, t \rho) / t \rightarrow 0$ as $t \rightarrow 0^{+}$ for fixed $R$ and $\rho$.

Suppose that the homogeneous equation $\boldsymbol{u}^{(m)}=0$ has only the trivial solution $u(x)=0$ satisfying (4.9). Then, as is well known, the linear mapping $K$ defined
on $V$ by $K u=u^{(m)}(x)$ is a homeomorphism of $V$ onto $L_{2}$. Thus, if $\left\{X_{n}\right\} \subset V$ is a sequence of finite-dimensional subspaces such that $\operatorname{dist}\left(v, X_{n}\right)=$ $\inf _{x \in X_{n}}\|v-x\|_{W_{2}^{m}} \rightarrow 0$ for each $v \in V$, the sequence $\left\{Y_{n}\right\}=\left\{K X_{n}\right\} \subset L_{2}$ has also the property that $\operatorname{dist}\left(f, Y_{n}\right)=\inf _{y \in Y_{n}}\|f-y\|_{L_{2}} \rightarrow 0$ as $n \rightarrow \infty$ for each $f$ in $L_{2}$. Let $P_{n}: V \rightarrow X_{n}$ and $Q_{n}: L_{2} \rightarrow Y_{n}$ be the orthogonal projections. Then $\Gamma_{0}=\left\{X_{n}, P_{n} ; Q_{n}, Y_{n}\right\}$ is projectionally complete for $\left(V, L_{2}\right)$.

Now, it follows from conditions (a1), (a2), and (a3), that $A: V \rightarrow L_{2}$ and $B: V \rightarrow L_{2}$ are well-defined, continuous and bounded; moreover, $A$ has a semibounded variation as a map of $V$ into $L_{2}$ since (a3) implies that

$$
\begin{equation*}
(A(u)-A(v), K(u-v))_{L_{2}} \geqslant-c\left(R,\|u-v\|_{W_{2}^{m-1}}\right) \tag{4.10}
\end{equation*}
$$

whenever $u, v \in B(0, R) \subset V$.
In view of the above discussion and Theorems 2.4 and 2.6 we have the following existence theorem for Eq. (4.8).

Theorem 4.2. Suppose that the functions $A(x, \xi)$ and $B(x, \eta)$ satisfy conditions (a1), (a2), and (a3). Then for each $h \in L_{2}$, the BV problem (4.8)-(4.9) has a solution $u \in V$ provided that any one of the following conditions holds:
(d1) $A(x,-\xi)=-A(x, \xi)$ for $\xi \in R^{m+1}$ and $B(x,-\eta)=-B(x, \eta)$ for $\eta \in R^{m}$ and $T \equiv A+B: V \rightarrow L_{2}$ satisfies condition $(+)$, i.e., if $\left\{u_{n}\right\} \subset V$ is a sequence that $A\left(u_{n}\right)+B\left(u_{n}\right) \rightarrow$ for some $f$ in $L_{2}$, then $\left\{u_{n}\right\}$ is bounded in $V$.
(d2) $(T u, K u) \geqslant 0$ for all $u$ in $V$ and $T=A+B: V \rightarrow L_{2}$ satisfies condition ( + ).
(d3) $\|T u\|_{L_{2}}+\left((T u, K(u) /\|K u\|) \rightarrow \infty\right.$ as $\|u\|_{W_{2} m} \rightarrow \infty$ for $u \in V$, and $(T u, K u) \geqslant-c\|K u\|$ for all $u \in V$ and some $c$.

Proof. It follows from (4.10) that for each $\mu>0$ and $u, v \in B(0, R)$ we have the inequality

$$
\begin{aligned}
& ((A+\mu K) u-(A+\mu K) v, K(u-v)) \\
& \quad \geqslant \mu\|K(u-v)\|_{L_{2}}^{2}-c\left(R,\|u-v\|_{W_{2}^{m-1}}\right)
\end{aligned}
$$

Since the imbedding of $W_{2}{ }^{m}$ into $W_{2}^{m-1}$ is compact and the norm in $W_{2}{ }^{m}$ is equivalent to the norm given by $\|u\|_{0}=\|K u\|_{L_{2}}$ for $u \in V$, it follows from the above inequality that $A+\mu K: V \rightarrow L_{2}$ is $A$-proper with respect to $\Gamma_{0}$. Moreover, since $B: V \rightarrow L_{2}$ is completely continuous and thus compact because $V$ and $L_{2}$ are reflexive, the operator $A+B+\mu K: V \rightarrow L_{2}$ is $A$-proper with respect to $\Gamma_{0}$.

It is obvious that if in Theorem 2.4 we take $X=V, Y=L_{2}, G=K$, and $K_{n}=M_{n}=\left.K\right|_{X_{n}}: X_{n} \rightarrow Y_{n}$, then all the assumptions of Theorem 2.4 are satisfied. Thus, if either (d1) or (d2) holds, the conclusion of Theorem 4.2
follows from Theorem 2.4. If, on the other hand, condition (d3) holds, then, in view of Lemma 3.3, the conclusion of Theorem 4.2 follows from Theorem 2.6 and Remark 2.7(b).
Q.E.D.

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