

NORTH-HOLLAND

On Perturbation Bounds for the QR Factorization

Ji-guang Sun*

Institute of Information Processing University of Umeå S-901 87 Umeå, Sweden

Submitted by Hans Schneider

ABSTRACT

Certain new perturbation bounds of the orthogonal factor in the QR factorization of a real matrix are derived. The bounds of this note improve the known bounds in the literature.

1. INTRODUCTION

Let A be a real $m \times n$ matrix $(A \in \mathbb{R}^{m \times n})$ with rank A = n. The QR factorization of A is a decomposition of the form A = QR, in which $R \in \mathbb{R}^{n \times n}$ is an upper triangular matrix with positive diagonal elements, and the matrix $Q \in \mathbb{R}^{m \times n}$ satisfies $Q^T Q = I$, the identity matrix. Here Q^T is the transpose of Q. The matrix Q is referred to as the orthogonal factor, and R the triangular factor in the QR factorization of A. It is well known that the QR factorization of a full-columnrank matrix is unique, and the QR factorization is one of the most important decompositions of a matrix (see [3]).

Let $E \in \mathbb{R}^{m \times n}$ with rank(A + E) = n, and let A + E = (Q + W)(R + F) be the QR factorization of A + E. A number of upper bounds on ||F||/||R|| and ||W|| in terms of ||E|| for a certain norm || || have been derived by Stewart [6] and Sun [8]. Recently, Stewart [7] gave asymptotic perturbation bounds on ||F||/||R|| and ||W||, and Bhatia and Mukherjea [2] presented a new bound on ||W||. Besides, Sun [9] gives componentwise perturbation bounds of |F| and |W|, where the matrix |F| is defined by $|F| = (|f_{ij}|)$ for $F = (f_{ij})$. It is worthwhile to point out that the bounds of ||W|| (or |W|) given by [6–9] are derived from certain known bounds of ||F||

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(or |F|) and the relation

$$W = [E - (Q + W)F]R^{-1}.$$

In this note we derive several new bounds of ||W|| directly. Roughly speaking, the new bounds of [2] and this note improve the results of [7] and [8] by a factor $1 + 1/\sqrt{2}$:

$$\begin{split} \|W\|_{\rm F} &\lesssim (1+\sqrt{2}) \|A^{\dagger}\|_2 \|E\|_{\rm F} \quad \text{(by the results of [7, 8]),} \\ \|W\|_{\rm F} &\lesssim \sqrt{2} \|A^{\dagger}\|_2 \|E\|_{\rm F} \quad \text{(by the new bounds),} \end{split}$$

where A^{\dagger} denotes the Moore-Penrose inverse of A, and $|| ||_2$ and $|| ||_F$ stand for the spectral norm and the Frobenius norm, respectively.

Note that the methods and results of this note are different from those of [2]. Bhatia and Mukherjea [2] apply calculus on manifold and matrix Lie groups to consider complex square matrices. The following inequality was proved in [2]:

$$\|\widetilde{Q}-Q\|_{\mathrm{F}} \leq \max_{0\leq t\leq 1} \|A(t)^{-1}\|_{2} \|E\|_{\mathrm{F}},$$

where A(t) = A + tE, $0 \le t \le 1$. Remark that the quantity $\max_{0 \le t \le 1} ||A(t)^{-1}||_2$ is not convenient to calculate. In this note we apply fixed-point theory and elementary calculus to consider real rectangular matrices. The upper bounds of $||\tilde{Q} - Q||_F$ obtained in this note are computable.

We shall use $I^{(n)}$ to denote the identity matrix of order *n*, and 0 the null matrix. $P_A = AA^{\dagger}$ denotes the orthogonal projection onto the column space of *A*. The symbol $\lambda()$ denotes the set of the eigenvalues of a matrix or an operator. $U^{n \times n}$ is the set of real $n \times n$ upper triangular matrices, and $U_s^{m \times n}$, $\mathcal{L}_s^{m \times n}$, $\mathcal{D}^{m \times n}$ are sets defined by

$$\begin{aligned} \mathcal{U}_{\mathrm{s}}^{m \times n} &= \left\{ A = (\alpha_{ij}) \in \mathcal{R}^{m \times n} : \alpha_{ij} = 0 \; \forall i \geq j \right\}, \\ \mathcal{L}_{\mathrm{s}}^{m \times n} &= \left\{ A = (\alpha_{ij}) \in \mathcal{R}^{m \times n} : \alpha_{ij} = 0 \; \forall i \leq j \right\}, \\ \mathcal{D}^{m \times n} &= \left\{ A = (\alpha_{ij}) \in \mathcal{R}^{m \times n} : \alpha_{ij} = 0 \; \forall i \neq j \right\}. \end{aligned}$$

Obviously, an $X \in \mathcal{R}^{m \times n}$ can be split uniquely as

$$X = X_L + X_D + X_U, \qquad X_L \in \mathcal{L}_s^{m \times n}, \quad X_D \in \mathcal{D}^{m \times n}, \quad X_U \in \mathcal{U}_s^{m \times n}.$$
(1.1)

The matrices X_L , X_D , X_U of (1.1) will be denoted by

$$X_L = \log(X), \qquad X_D = \operatorname{diag}(X), \qquad X_U = \operatorname{up}(X). \tag{1.2}$$

The relation (1.2) gives the definitions of the operators low(), diag(), and up() defined on $\mathcal{R}^{m \times n}$ (Reference [4]).

In Section 2 we derive perturbation equations. In Section 3 we discuss some basic properties of the operator L [defined below by (2.8)] and the function l(R) [defined below by (3.8)], which are important for studying perturbation bounds for the orthogonal factor in the QR factorization. In Sections 4 and 5 we apply fixed-point theory and elementary calculus to derive perturbation bounds of the orthogonal factor, respectively, and in Section 6 we give a numerical example.

2. PERTURBATION EQUATIONS

Let $A \in \mathcal{R}^{m \times n}$ with rank A = n, and let $\widetilde{A} = A + E$, where $E \in \mathcal{R}^{m \times n}$ satisfies

$$\epsilon_2 \equiv \|A^{\dagger}\|_2 \|E\|_2 < 1.$$
 (2.1)

Then obviously rank $\tilde{A} = n$. Let $A = QR, \tilde{A} = \tilde{Q}\tilde{R}$ be the QR factorizations of A, \tilde{A} , respectively, and let

$$E = \widetilde{A} - A, \qquad W = \widetilde{Q} - Q, \qquad F = \widetilde{R} - R.$$
 (2.2)

Then it is easy to verify that the perturbation matrices W, F satisfy the equation

$$E = WR + \tilde{Q}F. \tag{2.3}$$

Take a matrix $\tilde{P} \in \mathcal{R}^{m \times (m-n)}$ such that $\tilde{U} = (\tilde{Q}, \tilde{P})$ is an orthogonal matrix, and let

$$\widetilde{E} = \widetilde{U}^{\mathsf{T}} E, \qquad X = \widetilde{U}^{\mathsf{T}} W = \begin{pmatrix} X^{(1)} \\ X^{(2)} \end{pmatrix}, \quad X^{(1)} \in \mathcal{R}^{n \times n}.$$
 (2.4)

Then from (2.3)

$$XR + \binom{F}{0} = \widetilde{E}.$$
 (2.5)

Moreover, from the relations $Q^{T}Q = I$ and

$$\binom{I}{0} - X = \widetilde{U}^{\mathsf{T}} \mathcal{Q}$$

we get

$$X^{(1)} + X^{(1)^{\mathrm{T}}} = X^{\mathrm{T}}X.$$
 (2.6)

Let X be a solution to the equations (2.5)–(2.6). Define the matrices X_L , X_D , X_U by (1.1)–(1.2). Then from (2.5) and low(XR) = low(X_LR) it follows that

$$\log(X_L R) = \log(\tilde{E}). \tag{2.7}$$

Define the operator $\mathbf{L}: \mathcal{L}_s^{m \times n} \to \mathcal{L}_s^{m \times n}$ by

$$\mathbf{L}X_L = \log(X_L R), \qquad X_L \in \mathcal{L}_s^{m \times n}.$$
(2.8)

Then the equation (2.7) can be rewritten as

$$\mathbf{L}X_L = \log(\widetilde{E}). \tag{2.9}$$

Moreover, from (2.6)

$$X_D = \begin{pmatrix} \frac{1}{2} \operatorname{diag}(X^T X) \\ 0 \end{pmatrix}, \qquad X_U = \begin{pmatrix} \operatorname{up}(X^T X) - X_L^{(1)'} \\ 0 \end{pmatrix}, \qquad (2.10)$$

where $X_L^{(1)} = \log(X^{(1)})$.

In Section 4 we shall prove that there is a unique solution X to the equations (2.9)–(2.10) in the case of small $||E||_{\rm F}$, and derive upper bounds of $||X||_{\rm F}$ for the solution X.

3. THE OPERATOR L AND FUNCTION l(R)

Before we go on to derive perturbation bounds of $||X||_F$ from the equations (2.9)–(2.10), it will be necessary to discuss the basic properties of the operator L defined by (2.8).

We first consider the relation

$$Y = XR, \tag{3.1}$$

where $X, Y \in \mathbb{R}^{m \times n}, R = (r_{ij}) \in \mathcal{U}^{n \times n}$. Let

$$X = (x_1, ..., x_n) = (\xi_{ij}), \quad Y = (y_1, ..., y_n) = (\eta_{ij}), x = (x_1^{\mathrm{T}}, ..., x_n^{\mathrm{T}})^{\mathrm{T}}, \qquad y = (y_1^{\mathrm{T}}, ..., y_n^{\mathrm{T}})^{\mathrm{T}}.$$

The relation (3.1) can be rewritten as

$$y=\big(R^{\mathrm{T}}\otimes I^{(m)}\big)x,$$

where $A \otimes B \equiv (\alpha_{ij}B)$ is a Kronecker product. Write

$$L \equiv R^{\mathrm{T}} \otimes I^{(m)} = (L_{ij}), \qquad L_{ij} \in \mathcal{R}^{m \times m}, \quad i, j = 1, \dots, n; \qquad (3.2)$$

we have

$$L_{ij} = \begin{cases} 0, & i < j, \\ r_{ii}I^{(m)}, & i = j, \\ r_{ji}I^{(m)}, & i > j. \end{cases}$$
(3.3)

Let

$$Y_L = \mathbf{L} X_L \equiv \log(X_L R). \tag{3.4}$$

Define $x_j^{(L)}, y_j^{(L)}, x^{(L)}, y^{(L)}$ by

$$\begin{aligned} x_{j}^{(L)} &= \begin{pmatrix} \xi_{j+1,j} \\ \vdots \\ \xi_{mj} \end{pmatrix}, \quad y_{j}^{(L)} = \begin{pmatrix} \eta_{j+1,j} \\ \vdots \\ \eta_{mj} \end{pmatrix}, \quad j = 1, 2, ..., n_{1}, \\ x^{(L)} &= (x_{1}^{(L)^{\mathsf{T}}}, ..., x_{n_{1}}^{(L)^{\mathsf{T}}})^{\mathsf{T}}, y^{(L)} = (y_{1}^{(L)^{\mathsf{T}}}, ..., y_{n_{1}}^{(L)^{\mathsf{T}}})^{\mathsf{T}}, \end{aligned}$$

where

$$n_1 = \begin{cases} n & \text{if } m > n, \\ n-1 & \text{if } m = n. \end{cases}$$
(3.5)

The relation (3.4) can be rewritten as

$$y^{(L)} = L^{(L)} x^{(L)}, (3.6)$$

where

$$L^{(L)} = (L^{(L)}_{ij}), \qquad L^{(L)}_{ij} = L_{ij} \begin{pmatrix} i+1, i+2, \dots, m \\ j+1, j+2, \dots, m \end{pmatrix},$$

$$i, j = 1, 2, \dots, n_1,$$
(3.7)

in which n_1 is defined by (3.5), and

$$L_{ij}$$
 $\begin{pmatrix} i+1, i+2, ..., m \\ j+1, j+2, ..., m \end{pmatrix}$

denotes the submatrix of L_{ij} consisting of rows i + 1, i + 2, ..., m and columns j + 1, j + 2, ..., m. Combining (3.7) with (3.3), we see that

$$\lambda(L^{(L)}) = \bigcup_{j=1}^{n_1} \lambda(L_{jj}^{(L)}) = \bigcup_{j=1}^{n_1} \underbrace{\{r_{jj}, \ldots, r_{jj}\}}_{m-j},$$

where n_1 is defined by (3.5). Since (3.6) is equivalent to (3.4), we have the following

THEOREM 3.1. Let $R = (r_{ij}) \in U^{n \times n}$, and let L be the operator defined by (2.8). Then the eigenvalues of L are

$$\underbrace{r_{11},\ldots,r_{11}}_{m-1},\underbrace{r_{22},\ldots,r_{22}}_{m-2},\ldots,\underbrace{r_{nn},\ldots,r_{nn}}_{m-n}$$

Let L be the operator defined by (2.8). Now we define the function l(R) by

$$l(R) = \inf_{\substack{X_L \in \mathcal{L}_s^{m \times n} \\ \|X_L\|_F = 1}} \|\mathbf{L}X_L\|_F.$$
(3.8)

It is easy to verify that

$$l(R) = \begin{cases} \|\mathbf{L}^{-1}\|^{-1}, & 0 \notin \lambda(\mathbf{L}), \\ 0, & 0 \in \lambda(\mathbf{L}), \end{cases}$$
(3.9)

where $\|\mathbf{L}^{-1}\|$ is the subordinate operator norm defined by

$$\|\mathbf{L}^{-1}\| = \max_{\substack{Y_L \in \mathcal{L}_s^{m \times n} \\ \|Y_L\|_{\mathbf{F}} = 1}} \|\mathbf{L}^{-1} Y_L\|_{\mathbf{F}}.$$
 (3.10)

Therefore, from Theorem 3.1 we get the following

COROLLARY 3.2. Let l(R) be the function defined by (3.8). If R is nonsingular, then

$$0 < l(R) \leq \min_{1 \leq i \leq n_1} |r_{ii}|,$$

where n_1 is defined by (3.5).

The following result gives a relation between l(R) and $1/||A^{\dagger}||_2$.

THEOREM 3.3. Let $A \in \mathbb{R}^{m \times n}$ with rank A = n, A = QR be the QR factorization of A, and let L, l(R) be defined by (2.8), (3.8), respectively. Then

$$l(R) \ge \frac{1}{\|A^{\dagger}\|_{2}}.$$
(3.11)

PROOF. By (3.9) and $||A^{\dagger}||_2 = ||R^{-1}||_2$, the inequality (3.11) is equivalent to

$$\|\mathbf{L}^{-1}\| \le \|\mathbf{R}^{-1}\|_2. \tag{3.12}$$

Now we are going to prove (3.12).

Let $X = (x_1, x_2, \ldots, x_n) \in \mathcal{R}^{m \times n}$, where

$$x_j = \begin{pmatrix} x_j^{(U)} \\ x_j^{(L)} \end{pmatrix}, \quad x_j^{(U)} = \begin{pmatrix} \xi_{1j} \\ \vdots \\ \xi_{jj} \end{pmatrix}, \quad x_j^{(L)} = \begin{pmatrix} \xi_{j+1,j} \\ \vdots \\ \xi_{mj} \end{pmatrix}, \quad j = 1, \dots, n_1,$$

where n_1 is defined by (3.5), and $x_n^{(U)} = x_n$ if m = n. By (1.1)-(1.2) $X_L = (x_1^{(0)}, \ldots, x_n^{(0)}) \in \mathbb{R}^{m \times n}$, where

$$x_j^{(0)} = \begin{pmatrix} 0 \\ x_j^{(L)} \end{pmatrix}, \quad j = 1, ..., n_1, \qquad x_n^{(0)} = 0 \quad \text{if } m = n.$$

Let $x = (x_1^T, \ldots, x_n^T)^T$, and let

$$x^{(L)} = \left(x_1^{(L)^{\mathsf{T}}}, \ldots, x_n^{(L)^{\mathsf{T}}}\right)^{\mathsf{T}}, \qquad x^{(U)} = \left(x_1^{(U)^{\mathsf{T}}}, \ldots, x_n^{(U)^{\mathsf{T}}}\right)^{\mathsf{T}}.$$

Moreover, we use the vectors $y \in \mathcal{R}^{mn}$, $y^{(L)} \in \mathcal{R}^{mn_1-n_1(n_1+1)/2}$, $y^{(U)} \in \mathcal{R}^{n(n+1)/2}$ to correspond to $Y \in \mathcal{R}^{m \times n}$. Then the relations

$$Y = XR,$$
 $Y_L = \mathbf{L}X_L \equiv \log(X_LR)$

are equivalent to

$$y = Lx, \qquad y^{(L)} = L^{(L)}x^{(L)},$$
 (3.13)

respectively, when L and $L^{(L)}$ are expressed by (3.2)–(3.3) and (3.7). From the first relation of (3.13)

$$\frac{\partial y_k}{\partial x_j} = \begin{cases} 0, & k < j, \\ \begin{pmatrix} r_{jj}I^{(j)} & 0 \\ 0 & r_{jj}I^{(m-j)} \end{pmatrix}, & k = j, \\ \begin{pmatrix} * & * \\ 0 & * \end{pmatrix}, & k > j. \end{cases}$$

Thus, we have $\partial y_k^{(L)} / \partial x_j^{(U)} = 0 \ \forall k, j$, and

$$\begin{pmatrix} y^{(L)} \\ y^{(U)} \end{pmatrix} = \begin{pmatrix} L^{(L)} & 0 \\ * & * \end{pmatrix} \begin{pmatrix} x^{(L)} \\ x^{(U)} \end{pmatrix}.$$

This means that there is a permutation matrix P such that

$$P(R^{\mathsf{T}} \otimes I^{(m)})P^{\mathsf{T}} = \begin{pmatrix} L^{(L)} & 0 \\ * & * \end{pmatrix},$$

i.e.,

$$P\left(R^{\mathrm{T}} \otimes I^{(m)}\right)^{-1} P^{\mathrm{T}} = \begin{pmatrix} L^{(L)^{-1}} & 0\\ * & * \end{pmatrix}.$$
 (3.14)

Observe that from the second relation of (3.13) $x^{(L)} = L^{(L)^{-1}} y^{(L)}$; hence by the definition (3.10) and (3.14) we have

$$\|\mathbf{L}^{-1}\| = \|L^{(L)^{-1}}\|_{2} \le \|(\mathbf{R}^{\mathrm{T}} \otimes \mathbf{I}^{(m)})^{-1}\|_{2} = \|\mathbf{R}^{-1}\|_{2}.$$

The inequality (3.12) is proved.

The following result shows that the function l(R) is insensitive to perturbations of R.

THEOREM 3.4. Let $R, M \in U^{n \times n}$. Then

$$l(R) - \|M\|_2 \le l(R+M) \le l(R) + \|M\|_2.$$
(3.15)

PROOF. By the definition (3.8), we have

$$l(R) = \min \left\{ \|\log (X_L R)\|_{\rm F} : X_L \in \mathcal{L}_{\rm s}^{m \times n}, \|X_L\|_{\rm F} = 1 \right\} \\ = \|\log (X_L^* R)\|_{\rm F}, \qquad X_L^* \in \mathcal{L}_{\rm s}^{m \times n}, \quad \|X_L^*\|_{\rm F} = 1,$$

and

$$l(R + M) = \min \{ \| \log (X_L(R + M)) \|_F : X_L \in \mathcal{L}_s^{m \times n}, \| X_L \|_F = 1 \}$$

$$\leq \| \log (X_L^*(R + M)) \|_F$$

$$\leq \| \log (X_L^*R) \|_F + \| \log (X_L^*M) \|_F$$

$$\leq l(R) + \| M \|_2.$$

Similarly, we can prove the first inequality of (3.15).

Let

$$X = \begin{pmatrix} X^{(1)} \\ X^{(2)} \end{pmatrix} \in \mathcal{R}^{m \times n}$$
 with rank $X = n$,

where $X^{(1)} \in \mathcal{R}^{n \times n}$. Define the operator $\mathbf{L}_1 : \mathcal{L}_s^{n \times n} \to \mathcal{L}_s^{n \times n}$ by

$$\mathbf{L}_1 X_L^{(1)} = \log\left(X_L^{(1)} R\right), \qquad X_L^{(1)} \in \mathcal{L}_s^{n \times n}, \tag{3.16}$$

and define the function $l_1(R)$ by

$$l_{1}(R) = \inf_{\substack{X_{L}^{(1)} \in \mathcal{L}_{n}^{n \times n} \\ ||X_{L}^{(1)}||_{F} = 1}} \|\mathbf{L}_{1}X_{L}^{(1)}\|_{F}.$$
(3.17)

Observe that L_1 is just L for the case m = n; hence the operator L_1 and the function $l_1(R)$ have the same properties as L and l(R) stated by Theorem 3.1, Corollary 3.2, and Theorems 3.3-3.4.

4. PERTURBATION THEOREMS (I)

Now we are going to discuss the solution X to the equations (2.9)–(2.10) under the assumption that all the diagonal elements of R are positive.

By the assumption and Theorem 3.1, the operators L and L_1 defined by (2.8) and (3.16) are nonsingular. Moreover, from (2.4)–(2.5)

$$X_L^{(1)} = \mathbf{L}_1^{-1} \big[\operatorname{low}(\widetilde{Q}^T E) \big].$$

Thus, the equations (2.9)–(2.10) can be rewritten as a continuous mapping $\Phi: \mathcal{R}^{m \times n} \to \mathcal{R}^{m \times n}$ expressed by

$$X_L = \mathbf{L}^{-1}[\operatorname{low}(\widetilde{E})],$$

$$X_D = \begin{pmatrix} \frac{1}{2}\operatorname{diag}(X^TX) \\ 0 \end{pmatrix},$$

$$X_U = \begin{pmatrix} \operatorname{up}(X^TX) - \mathbf{L}_1^{-1}[\operatorname{low}(\widetilde{Q}^TE)] \\ 0 \end{pmatrix},$$

or simply

$$X = \phi(X) + G, \tag{4.1}$$

where

$$\phi(X) = \begin{pmatrix} \frac{1}{2} \operatorname{diag}(X^{\mathrm{T}}X) + \operatorname{up}(X^{\mathrm{T}}X) \\ 0 \end{pmatrix},$$

$$G = \mathbf{L}^{-1}[\operatorname{low}(\widetilde{E})] - \begin{pmatrix} (\mathbf{L}_{1}^{-1}[\operatorname{low}(\widetilde{Q}^{\mathrm{T}}E)])^{\mathrm{T}} \\ 0 \end{pmatrix}.$$
(4.2)

Let

$$\eta = \frac{\sqrt{5}}{2}, \qquad \gamma = \sqrt{\left(\frac{\|E\|_{\rm F}}{l(R)}\right)^2 + \left(\frac{\|P_{\widetilde{A}}E\|_{\rm F}}{l_1(R)}\right)^2}, \tag{4.3}$$

where l(R) and $l_1(R)$ are the functions defined by (3.8) and (3.17), respectively. One can verify the following inequalities:

(1) $\|\phi(X)\|_{F} \leq \eta \|X\|_{F}^{2}$, (2) $\|\phi(X) - \phi(Y)\|_{F} \leq 2\eta \max \{\|X\|_{F}, \|Y\|_{F}\} \|X - Y\|_{F}$, (3) $\|G\|_{F} \leq \gamma$.

Hence, by Stewart [5, Theorem 3.1], if $4\gamma\eta < 1$, then the mapping Φ expressed by (4.1)–(4.2) has a unique fixed point X in the neighborhood

$$\mathcal{S}(0; 2\gamma) \equiv \left\{ X \in \mathcal{R}^{m \times n} : \|X\|_{\mathrm{F}} < 2\gamma \right\}$$

of the origin $\mathcal{R}^{m \times n}$, and

$$\|X\|_{\rm F} \leq \frac{2\gamma}{1+\sqrt{1-4\gamma\eta}}$$

Let

$$\epsilon_{l, l_1} \equiv \frac{\gamma}{\sqrt{2}} = \sqrt{\frac{1}{2} \left[\left(\frac{\|E\|_{\mathrm{F}}}{l(R)} \right)^2 + \left(\frac{\|P_{\widetilde{A}}E\|_{\mathrm{F}}}{l_1(R)} \right)^2 \right]}.$$
(4.4)

Then the condition $4\gamma\eta < 1$ can be rewritten as

$$2\sqrt{10}\epsilon_{l,\,l_1} < 1. \tag{4.5}$$

Observe that from (2.4) and (2.2)

$$||X||_{\rm F} = ||W||_{\rm F} = ||\widetilde{Q} - Q||_{\rm F}$$

Hence, we get the following perturbation theorem.

THEOREM 4.1. Let $A \in \mathbb{R}^{m \times n}$ with rank A = n, A = QR be the QR factorization of A, and A = A + E, and let ϵ_2 and ϵ_{l, l_1} be defined by (2.1) and (4.4), respectively. If $\epsilon_2 < 1$ and ϵ_{l, l_1} satisfies the condition (4.5), then rank $\widetilde{A} = n$ and the OR factorization $\widetilde{A} = \widetilde{QR}$ satisfies

$$\|\widetilde{Q} - Q\|_{\mathrm{F}} \leq \frac{2\sqrt{2}\epsilon_{l,\,l_{1}}}{1 + \sqrt{1 - 2\sqrt{10}\epsilon_{l,\,l_{1}}}} \equiv b\left(\epsilon_{l,\,l_{1}}\right)$$
$$= \sqrt{2}\epsilon_{l,\,l_{1}} + \sqrt{5}\epsilon_{l,\,l_{1}}^{3} + 5\sqrt{2}\epsilon_{l,\,l_{1}}^{3} + O\left(\epsilon_{l,\,l_{1}}^{4}\right).$$
(4.6)

By Theorem 3.3

$$\epsilon_{l, l_1} \leq \|A^{\dagger}\|_2 \sqrt{\frac{\|E\|_F^2 + \|P_{\widetilde{A}}E\|_F^2}{2}} \equiv \widetilde{\epsilon}.$$

$$(4.7)$$

Moreover, we have

$$2\sqrt{10}\tilde{\epsilon} \ge 2\sqrt{5}\|A^{\dagger}\|_{2}\|E\|_{\mathrm{F}} \ge \|A^{\dagger}\|_{2}\|E\|_{2} = \epsilon_{2}.$$

Hence, Theorem 4.1 gives the following

COROLLARY 4.2. Let A, Q, \tilde{A} , E be as in Theorem 4.1, and let $\tilde{\epsilon}$ be defined by (4.7). If

$$2\sqrt{10\tilde{\epsilon}} < 1,$$

then rank $\widetilde{A} = n$, and the QR factorization $\widetilde{A} = \widetilde{Q}\widetilde{R}$ satisfies

$$\|\widetilde{Q} - Q\|_{\mathrm{F}} \leq \frac{2\sqrt{2}\widetilde{\epsilon}}{1 + \sqrt{1 - 2\sqrt{10}\widetilde{\epsilon}}} \equiv b(\widetilde{\epsilon}) \\ = \sqrt{2}\widetilde{\epsilon} + \sqrt{5}\widetilde{\epsilon}^{2} + 5\sqrt{2}\widetilde{\epsilon}^{3} + O(\widetilde{\epsilon}^{4}).$$
(4.8)

5. PERTURBATION THEOREMS (II)

Let $A \in \mathbb{R}^{m \times n}$ with rank (A) = n, A = QR be the QR factorization of A, A(t) = A + tE, $0 \le t \le 1$, $\tilde{A} = A(1)$, and let ϵ_2 be defined by (2.1). It is known that if $\epsilon_2 < 1$, then rank A(t) = n, and A(t) has the unique QR factorization

$$A(t) = Q(t)R(t) \tag{5.1}$$

for each $t \in [0, 1]$, where $R(t) \in \mathbb{R}^{n \times n}$ is a upper triangular matrix with positive diagonal elements, and $Q(t) \in \mathbb{R}^{m \times n}$ satisfy

$$Q(t)^{\mathrm{T}}Q(t) = I.$$
(5.2)

In this section we shall apply elementary calculus [1, 8] to derive perturbation bounds of the orthogonal factor in the QR factorization of A. Differentiating (5.1) and (5.2), we get

$$E dt = dQ(t) R(t) + Q(t) dR(t)$$
(5.3)

and

$$dQ(t)^{T} Q(t) + Q(t)^{T} dQ(t) = 0.$$
(5.4)

Take $P(t) \in \mathcal{R}^{m \times (m-n)}$ so that U(t) = (Q(t), P(t)) is orthogonal, and let

$$\delta A(t) = U(t)^{\mathrm{T}} E \,\mathrm{d}t, \qquad \delta X(t) = U(t)^{\mathrm{T}} \,\mathrm{d}Q(t) = \begin{pmatrix} \delta X^{(1)}(t) \\ \delta X^{(2)}(t) \end{pmatrix},$$
$$\delta X^{(1)}(t) \in \mathcal{R}^{n \times n}. \tag{5.5}$$

Then (5.3) and (5.4) can be rewritten as

$$\delta X(t) = \delta A(t) R(t)^{-1} - \begin{pmatrix} dR(t) R(t)^{-1} \\ 0 \end{pmatrix}$$
(5.6)

and

$$\delta X^{(1)}(t)^{\mathrm{T}} + \delta X^{(1)}(t) = 0.$$
(5.7)

By (1.1)–(1.2), the matrix $\delta X(t)$ can be split uniquely as

$$\delta X(t) = \delta X(t)_L + \delta X(t)_D + \delta X(t)_U.$$

Thus, the relation (5.7) implies $\delta X(t)_D = 0$. Moreover, from (5.5)–(5.7) we get

$$\delta X(t)_L = \log \left(\delta A(t) R(t)^{-1} \right)$$

and

$$\delta X(t)_U = \begin{pmatrix} \delta X^{(1)}(t)_U \\ 0 \end{pmatrix} = \begin{pmatrix} -[\delta X^{(1)}(t)_L]^T \\ 0 \end{pmatrix}$$
$$= \begin{pmatrix} -[\operatorname{low}(Q(t)^T E R(t)^{-1})]^T dt \\ 0 \end{pmatrix}.$$
(5.8)

Hence,

$$\|dQ(t)\|_{\rm F} = \|\delta X(t)\|_{\rm F} = \sqrt{\|\delta X(t)_L\|_{\rm F}^2 + \|\delta X(t)_U\|_{\rm F}^2} \\ \leq \sqrt{2}\|E\|_{\rm F}\|R(t)^{-1}\|_2 \, {\rm d}t = \sqrt{2}\|E\|_{\rm F}\|A(t)^{\dagger}\|_2 \, {\rm d}t.$$
(5.9)

Consequently,

$$\|\widetilde{Q} - Q\|_{\mathrm{F}} = \left\| \int_{0}^{1} \mathrm{d}Q(t) \right\|_{\mathrm{F}} \leq \int_{0}^{1} \|\mathrm{d}Q(t)\|_{\mathrm{F}}$$

$$\leq \sqrt{2} \|E\|_{\mathrm{F}} \int_{0}^{1} \|A(t)^{\dagger}\|_{2} \, \mathrm{d}t = \sqrt{2} \|E\|_{\mathrm{F}} \int_{0}^{1} \frac{\mathrm{d}t}{\sigma_{n}(t)}, \quad (5.10)$$

where $\sigma_n(t)$ is the smallest singular value of the matrix A(t). Let σ_n be the smallest singular value of A. Combining (5.10) with the well-known relation $\sigma_n(t) \ge \sigma_n - ||E||_2 t$, we get

$$\begin{split} \|\widetilde{Q} - Q\|_{F} &\leq \sqrt{2} \|E\|_{F} \int_{0}^{1} \frac{dt}{\sigma_{n} - \|E\|_{2}t} \\ &= \frac{\sqrt{2} \|E\|_{F}}{\|E\|_{2}} \ln \frac{1}{1 - \|A^{\dagger}\|_{2} \|E\|_{2}} \\ &= \sqrt{2} \omega(\epsilon_{2}) \epsilon_{f}, \end{split}$$

where ϵ_2 is defined by (2.1), and

$$\epsilon_f = \|A^{\dagger}\|_2 \|E\|_{\mathrm{F}}, \qquad \omega(\epsilon) = \frac{1}{\epsilon} \ln \frac{1}{1-\epsilon}, \quad 0 < \epsilon < 1.$$
 (5.11)

Hence, we have proved the following result.

THEOREM 5.1. Let A, Q, \tilde{A}, E be as in Theorem 4.1, and let ϵ_2 , ϵ_f , and $\omega(\epsilon)$ be defined by (2.1) and (5.11), respectively. If $\epsilon_2 < 1$, then rank A = n, and the QR factorization $\tilde{A} = \tilde{Q}\tilde{R}$ satisfies

$$\begin{split} \|\widetilde{Q} - Q\|_{\mathsf{F}} &\leq \sqrt{2}\omega(\epsilon_2)\epsilon_f \equiv b_1(\epsilon_2, \epsilon_f) \\ &= \sqrt{2}\epsilon_f + \frac{\sqrt{2}}{2}\epsilon_2\epsilon_f + \frac{\sqrt{2}}{3}\epsilon_2^2\epsilon_f + O\left(\epsilon_f^4\right). \\ &\leq \frac{\sqrt{2}\epsilon_f}{\sqrt{1 - \epsilon_2}} \equiv b_2(\epsilon, \epsilon_f) \\ &= \sqrt{2}\epsilon_f + \sqrt{2}\epsilon_2\epsilon_f + \sqrt{2}\epsilon_2^2\epsilon_f + O\left(\epsilon_f^4\right). \end{split}$$
(5.12)

We note that the perturbation bound (5.12) can be improved by observing that from (5.8)

$$\begin{aligned} \|\delta X(t)_{U}\|_{F} &\leq \|Q(t)^{T} E R(t)^{-1} dt\|_{F} \leq \|R(t)^{-1}\|_{2} \|Q(t)^{T} E\|_{F} dt \\ &= \|A(t)^{\dagger}\|_{2} \left\| \left(\int_{0}^{t} dQ(\tau) + Q \right)^{T} E \right\|_{F} dt \\ &\leq \|A(t)^{\dagger}\|_{2} \left(\|E\|_{2} \int_{0}^{t} \|dQ(\tau)\|_{F} + \|P_{A} E\|_{F} \right) dt. \end{aligned}$$

Combining it with

$$\int_0^t \| \mathrm{d} Q(\tau) \|_{\mathrm{F}} \le \int_0^1 \| \mathrm{d} Q(\tau) \|_{\mathrm{F}} \le \sqrt{2} \omega(\epsilon_2) \epsilon_f \qquad \text{[see (5.10)-(5.12)]},$$

we get

$$\|\delta X(t)_U\|_{\mathbf{F}} \leq \|A(t)^{\dagger}\|_2 [\sqrt{2}\|E\|_2 \omega(\epsilon_2)\epsilon_f + \|P_A E\|_{\mathbf{F}}] \mathrm{d}t.$$

Substituting it into (5.9), we obtain

$$\begin{aligned} \| \mathrm{d}Q(t) \|_{\mathrm{F}} &\leq \| |A(t)^{\dagger} \|_{2} \sqrt{\| E \|_{\mathrm{F}}^{2} + (\sqrt{2} \| E \|_{2} \omega(\epsilon_{2}) \epsilon_{f} + \| P_{A} E \|_{\mathrm{F}})^{2}} \, \mathrm{d}t \\ &\leq \| |A(t)^{\dagger} \|_{2} \left(\sqrt{\| E \|_{\mathrm{F}}^{2} + \| P_{A} E \|_{\mathrm{F}}^{2}} + \sqrt{2} \| E \|_{2} \omega(\epsilon_{2}) \epsilon_{f} \right) \, \mathrm{d}t \\ &= \sqrt{2} \| |A(t)^{\dagger} \|_{2} \left[\| A^{\dagger} \|_{2}^{-1} \epsilon + \| E \|_{2} \omega(\epsilon_{2}) \epsilon_{f} \right] \, \mathrm{d}t, \end{aligned}$$

where

$$\epsilon \equiv \|A^{\dagger}\|_{2} \frac{\sqrt{\|E\|_{F}^{2} + \|P_{A}E\|_{F}^{2}}}{2}$$
(5.13)

Hence,

$$\begin{split} \|\widetilde{Q} - Q\|_{\mathrm{F}} &\leq \int_{0}^{1} \|\mathrm{d}Q(t)\|_{\mathrm{F}} \\ &\leq \sqrt{2} \left[\|A^{\dagger}\|_{2}^{-1} \epsilon + \|E\|_{2} \omega(\epsilon_{2}) \epsilon_{f} \right] \int_{0}^{1} \|A(t)^{\dagger}\|_{2} \, \mathrm{d}t \\ &\leq \sqrt{2} \omega(\epsilon_{2}) \left[\epsilon + \omega(\epsilon_{2}) \epsilon_{2} \epsilon_{f} \right]. \end{split}$$

Thus, we have proved the following

THEOREM 5.2. Let A, Q, \widetilde{A}, E be as in Theorem 4.1, and let $\epsilon_2, \epsilon_f, \omega(\epsilon), \epsilon$ be defined by (2.1), (5.11), (5.13). If $\epsilon_2 < 1$, then rank $\widetilde{A} = n$, and the QR factorization $\widetilde{A} = \widetilde{QR}$ satisfies

$$\|\widetilde{Q} - Q\|_{\mathrm{F}} \leq \sqrt{2}\omega(\epsilon_2) \left[\epsilon + \omega(\epsilon_2)\epsilon_2\epsilon_f\right] \equiv b_0(\epsilon, \epsilon_2, \epsilon_f)$$
$$= \sqrt{2}\epsilon + \frac{\sqrt{2}}{2}\epsilon_2(\epsilon + 2\epsilon_f) + \frac{\sqrt{2}}{3}\epsilon_2^2(\epsilon + 3\epsilon_f) + O\left(\epsilon_f^4\right). \quad (5.14)$$

6. AN EXAMPLE

The following result has been proved in [8]: Let A, Q, R, \tilde{A}, E be as in Theorem 4.1, and let ϵ_2, ϵ_f be defined by (2.1), (5.11). If $\epsilon_2 < 1$, then there is a unique QR

factorization $\widetilde{A} = \widetilde{Q}\widetilde{R}$, and

$$\|\widetilde{Q} - Q\|_{\mathsf{F}} \leq (1 + \sqrt{2})\omega(\epsilon_2)\epsilon_f \equiv \beta_1(\epsilon_2, \epsilon_f)$$

$$\leq \frac{(1 + \sqrt{2})\epsilon_f}{1 - \epsilon_2} \equiv \beta_2(\epsilon_2, \epsilon_f). \tag{6.1}$$

It is easy to verify that there are the following relations between the upper bounds $b(\epsilon_{l,l_1}), b(\tilde{\epsilon}), b_1(\epsilon_2, \epsilon_f)$, and $\beta_1(\epsilon_2, \epsilon_f)$:

$$b\left(\epsilon_{l,l_1}\right) \leq b(\widetilde{\epsilon}), \qquad b_1\left(\epsilon_2,\epsilon_f\right) \leq \beta_1\left(\epsilon_2,\epsilon_f\right).$$

Moreover, the bound $b_0(\epsilon, \epsilon_2, \epsilon_f)$ expressed by (5.14) is better than $b_1(\epsilon_2, \epsilon_f)$ for very small perturbations of A, and by the author's numerical tests the bound $b(\epsilon_{l, l_1})$ is better than all the others.

Now we give a numerical example.

EXAMPLE 6.1. Let

$$A = \begin{pmatrix} R \\ 0 \end{pmatrix}, \qquad R = \begin{pmatrix} 1 & -2 & 1 & 2 & 3 \\ 0 & 2 & 4 & 1 & -5 \\ 0 & 0 & 3 & -1 & 2 \\ 0 & 0 & 0 & 4 & 1 \\ 0 & 0 & 0 & 0 & 5 \end{pmatrix},$$

and let $\widetilde{A} = A + E$, $E = \tau E_0$ with $\tau > 0$, and

$$E_0 = \begin{pmatrix} 0.2 & -0.5 & 0.3 & 0.1 & 0.4 \\ -0.1 & 0.4 & 0.1 & -0.3 & 0.2 \\ 0.5 & 0.7 & -0.2 & 0.1 & 0.6 \\ 0.3 & -0.6 & 0.1 & -0.1 & 0.2 \\ 0.2 & 0.1 & 0.7 & 0.3 & -0.4 \\ 0.4 & 0.8 & -0.2 & 0.1 & 0.3 \\ 0.6 & -0.1 & -0.5 & 0.1 & -0.2 \\ 0.1 & -0.3 & 0.2 & 0.6 & 0.7 \end{pmatrix}$$

τ	1.000000e-01	1.000000e-02	1.000000e-05	1.000000e-08
$\ E\ _{\mathrm{F}}$	2.431049e-01	2.431049e-02	2.431049e-05	2.431049e-08
$ Q - Q _{\mathrm{F}}$	3.355805e-01	3.162668e-02	3.138194e-05	3.138170e-08
$b(\epsilon_{l,l_1})$		9.834899e-02	8.765590e-05	8.764743e-08
$b(\widetilde{\epsilon})$		1.037806e-01	9.189167e-05	9.188238e-08
$b_0(\epsilon,\epsilon_2,\epsilon_f)$	2.104630e+00	9.913509e-02	9.188933e-05	9.188238e-08
$b_1(\epsilon_2,\epsilon_f)$	1.397628e+00	1.065221e-01	1.040365e-04	1.040340e-07
$b_2(\epsilon_2,\epsilon_f)$	1.939075e+00	1.090902e-01	1.040389e-04	1.040341e-07
$\beta_1(\epsilon_2,\epsilon_f)$	2.385901e+00	1.818447e-01	1.776013e-04	1.775972e-07
$\beta_2(\epsilon_2,\epsilon_f)$	3.310208e+00	1.862287e-01	1.776055e-04	1.775972e-07

TABLE 1.

Obviously, A has the QR factorization A = QR with

$$Q = \begin{pmatrix} I \\ 0 \end{pmatrix} \in \mathcal{R}^{8 \times 5}.$$

By MATLAB we get the QR factorization $\widetilde{A} = \widetilde{QR}$ of \widetilde{A} for small τ . Some numerical results by using MATLAB are listed in Table 1, where the scalars $\epsilon_2, \epsilon_{l,l_1}, \widetilde{\epsilon}, \epsilon_f, \epsilon$ are defined by (2.1), (4.4), (4.7), (5.11), (5.13), and the bounds $b(\epsilon_{l,l_1}), b(\widetilde{\epsilon}), b_i(\epsilon_2, \epsilon_f)$ (i = 1, 2), $b_0(\epsilon, \epsilon_2, \epsilon_f), \beta_i(\epsilon_2, \epsilon_f)$ (i = 1, 2) are defined by (4.6), (4.8), (5.12), (5.14), (6.1), respectively.

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