Available at
WWw.MATHEMATICSwE.ORG
powered by science @direct.
J. Math. Anal. Appl. 281 (2003) 633-640

Yournal of MATHEMATICAL ANALYSIS AND APPLICATIONS

# Existence results for some fourth-order nonlinear elliptic problems of local superlinearity and sublinearity ${ }^{\pi}$ 

Guixiang Xu and Jihui Zhang*<br>Department of Mathematics, Nanjing Normal University, Nanjing 210097, Jiangsu, People’s Republic of China<br>Received 6 June 2002<br>Submitted by N.S. Trudinger

## Abstract

In this paper we study the existence of positive solutions for the problem

$$
\begin{cases}\Delta^{2} u+c \Delta u=f(x, u) & \text { in } \Omega,  \tag{0.1}\\ u \geqslant 0, \quad u \neq 0 & \text { in } \Omega, \\ u=\Delta u=0 & \text { on } \partial \Omega,\end{cases}
$$

where $c<\lambda_{1}(\Omega)$ and $f(x, u)$ satisfies the local superlinearity and sublinearity condition. © 2003 Elsevier Science (USA). All rights reserved.

Keywords: Variational method; Biharmonic operator; Superlinear; Sublinear; Positive solutions; Suspension bridge

## 1. Introduction

This paper is concerned with the study of existence of positive solutions for the problem

$$
\begin{cases}\Delta^{2} u+c \Delta u=f(x, u) & \text { in } \Omega  \tag{1.1}\\ u \geqslant 0, \quad u \neq 0 & \text { in } \Omega \\ u=\Delta u=0 & \text { on } \partial \Omega\end{cases}
$$

[^0]0022-247X/03/\$ - see front matter © 2003 Elsevier Science (USA). All rights reserved.
doi:10.1016/S0022-247X(03)00170-7
where $\Delta^{2}$ denotes the biharmonic operator, $c \in R, \Omega$ is a bounded domain in $R^{N}$ and $f: \Omega \times R^{+} \rightarrow R$ is a Carathéodory function.

These fourth-order problems have been studied by many authors. In [1] there is a survey of results obtained in this direction. At the same time, in [1] it has been point out that this type of nonlinearity can furnish a model to study travelling waves in suspension bridges.

There are many results about (1.1) when $c<\lambda_{1}(\Omega)$ (where $\left(\lambda_{k}(\Omega)\right)_{k} \geqslant 1$ is the sequence of the eigenvalues of $-\Delta$ in $\left.H_{0}^{1}(\Omega)\right)$ and $f(x, u)=b\left[(u+1)^{+}-1\right]$. In [2] Tarantello found a negative solution when $b \geqslant \lambda_{1}(\Omega) *\left(\lambda_{1}(\Omega)-c\right)$ by a degree argument. Lazer and McKenna in [3] proved the existence of $2 k-1$ solutions when $\Omega \subset R$ is an interval and $b>\lambda_{k}(\Omega) *\left(\lambda_{k}(\Omega)-c\right)$ by the global bifurcation method. Micheletti and Pistoia in [4] proved that there exist two solutions when $b>\lambda_{1}(\Omega) *\left(\lambda_{1}(\Omega)-c\right)$ and three solutions when $b$ is close to $\lambda_{k}(\Omega) *\left(\lambda_{k}(\Omega)-c\right)$ for a more general nonlinearity $g$ by variational method.

In this paper we use the following terminologies. Problem (1.1) is said to be sublinear (superlinear) at 0 if there exist $\alpha>\lambda_{1}(\Omega) *\left(\lambda_{1}(\Omega)-c\right)$ and $s_{0}>0$ such that

$$
\begin{equation*}
f(x, s) \geqslant(\leqslant) \alpha s \quad \text { for a.e. } x \in \Omega \text { and all } 0 \leqslant s \leqslant s_{0} \tag{1.2}
\end{equation*}
$$

here $\lambda_{1}(\Omega)$ denotes the first eigenvalue of $-\Delta$ on $H_{0}^{1}(\Omega)$. Problem (1.1) is said to be superlinear (or sublinear) at $\infty$ if there exist $\beta>\lambda_{1}(\Omega) *\left(\lambda_{1}(\Omega)-c\right)$ and $s_{1}>0$ such that

$$
\begin{equation*}
f(x, s) \geqslant(\leqslant) \beta s \quad \text { for a.e. } x \in \Omega \text { and all } s \geqslant s_{1} . \tag{1.3}
\end{equation*}
$$

Zhang in [5] proved the existence of weak solutions when $f(x, u)$ is sublinear at $\infty$ by variational method.

It is the purpose to study the problem (1.1) when $f$ satisfies the local superlinearity and sublinearity by variational methods. Our method is similar to De Figueiredo's method in [6].

A good example to which our results apply is

$$
\begin{cases}\Delta^{2} u+c \Delta u=\lambda a(x) u^{q}+b(x) u^{p} & \text { in } \Omega,  \tag{1.4}\\ u \geqslant 0, \quad u \not \equiv 0 & \text { in } \Omega \\ u=\Delta u=0 & \text { on } \partial \Omega\end{cases}
$$

where $\lambda>0$ is a parameter and the exponents $p$ and $q$ satisfy $0 \leqslant q<1<p$ with $p \leqslant$ $2^{*}-1$ if $N \geqslant 3, p<+\infty$ if $N=1$ or 2 . Here $2^{*}=2 N /(N-2)$.

## 2. Main results

We will always assume $N \geqslant 3, c<\lambda_{1}(\Omega)$, denote by $\sigma^{\prime}$ the Hölder conjugate of $\sigma$, by $\lambda_{1}(\Omega)$ the first eigenvalue of $-\Delta$ on $H_{0}^{1}(\Omega)$ and by $\lambda_{1}\left(\Omega_{1}\right)$ the first eigenvalue of $-\Delta$ on $H_{0}^{1}\left(\Omega_{1}\right)$.

Given a bounded domain $\Omega \subset R^{N}$, let $V$ denote the Hilbert space $H^{2}(\Omega) \cap H_{0}^{1}(\Omega)$. Denote the $L^{p}(\Omega)$ norm by $\|u\|_{p}$, the norm on $H_{0}^{1}(\Omega)$ is given by $\|u\|_{0,1}=\left(\int_{\Omega}|\nabla u|^{2} d x\right)^{1 / 2}$, the norm on $V$ is given by

$$
\|u\|_{V}=\left(\int_{\Omega}\left[(\Delta u)^{2}-c|\nabla u|^{2}\right] d x\right)^{1 / 2} .
$$

Note that $\|u\|_{V}^{2} \geqslant\left(\lambda_{1}(\Omega)-c\right)\|u\|_{0,1}^{2}$ for all $u \in V$, that is, the norm $\|u\|_{V}$ is stronger than the norm $\|u\|_{0,1}$.

Let $f: \Omega \times R^{+} \rightarrow R$ be a Carathéodory function and satisfy the following conditions:
(H1) $f(x, 0) \geqslant 0$ for a.e. $x \in \Omega$;
(H2) There exist $1 \leqslant \sigma<2^{*}, d_{1} \in L^{\sigma^{\prime}}(\Omega), d_{2}>0$ such that

$$
|f(x, s)| \leqslant d_{1}(x)+d_{2}|s|^{\sigma-1}
$$

for a.e. $x \in \Omega$ and all $s>0$;
(H3) There exist $\Theta>2,1 \leqslant r<2, d \in L^{\left(2^{*} / r\right)^{\prime}}(\Omega)$, with $d \geqslant 0$ a.e. in $\Omega, s_{0} \geqslant 0$, such that

$$
\Theta F(x, s) \leqslant s f(x, s)+d(x) s^{r}
$$

for a.e. $x \in \Omega$ and all $s>s_{0}$, where $F(x, s)=\int_{0}^{s} f(x, t) d t$;
(H4) There exist $0 \leqslant q<1<p<2^{*}-1, a_{0} \in L^{\sigma_{q}}(\Omega)$, with $\sigma_{q}=\left(2^{*} /(q+1)\right)^{\prime}$ and $a_{0} \geqslant 0$ a.e. in $\Omega, b_{0} \in L^{\sigma_{p}}(\Omega)$, with $\sigma_{p}=\left(2^{*} /(p+1)\right)^{\prime}$ and $b_{0} \geqslant 0$ a.e. in $\Omega$, such that

$$
f(x, s) \leqslant a_{0} s^{q}+b_{0} s^{p}
$$

for a.e. $x \in \Omega$ and all $s \geqslant 0$;
(H5) There exist a nonempty subdomain $\Omega_{1} \subset \Omega, \Theta_{1}>\lambda_{1}\left(\Omega_{1}\right) *\left(\lambda_{1}\left(\Omega_{1}\right)-c\right), s_{1}>0$, such that

$$
F(x, s) \geqslant \Theta_{1} \frac{s^{2}}{2}
$$

for a.e. $x \in \Omega_{1}$ and all $0 \leqslant s \leqslant s_{1}$;
(H6) There exist a nonempty open subset $\Omega_{2} \subset \Omega, \Theta_{2}>0, s_{2} \geqslant 0$, such that

$$
F(x, s) \geqslant \Theta_{2} s^{2}
$$

for a.e. $x \in \Omega_{2}$ and all $s \geqslant s_{2}$, with the additional requirement that the function $d(x)$ appearing in (H3) is bounded on $\Omega_{2}$.

There are some comments on the conditions (H2), (H3), (H4), (H5), (H6) in [6], so we omit them. Here we comment the hypothesis (H1) again. When assuming (H1), we will always understand that $f(x, s)$ has been extended for $s<0$ by putting $f(x, s)=f(x, 0)$ for a.e. $x \in \Omega$ and all $s<0$. The extension technology had been used in [8,9] too. Doing so, any solution $u \in V$ of

$$
\begin{cases}\Delta^{2} u+c \Delta u=f(x, u) & \text { in } \Omega,  \tag{2.1}\\ u=\Delta u=0 & \text { on } \partial \Omega\end{cases}
$$

is automatically $\geqslant 0$ in $\Omega$.
Indeed, if $u$ is the solution of Eq. (2.1), then $-u^{-}$(where $u^{-}=\max \{-u, 0\}$ ) satisfies the system

$$
\begin{cases}\Delta u^{-}+c u^{-}=-v & \text { in } \Omega,  \tag{2.2}\\ \Delta v=f\left(x,-u^{-}\right) & \text {in } \Omega, \\ u^{-}=v=0 & \text { on } \partial \Omega .\end{cases}
$$

Note that the function $v=0$ on $\partial \Omega$. Hence, the weak maximum principle applied to the second equation of (2.2) show that

$$
v(x) \leqslant 0 \quad \text { for } x \in \Omega
$$

Thus, the right-hand side of the first equation of (2.2) is positive in $\Omega$. Because $u^{-}=0$ on $\partial \Omega$ and $c<\lambda_{1}(\Omega)$, the weak maximum principle applied to the first equation of (2.2) in turn implies that $u^{-}(x) \leqslant 0$ for all $x \in \Omega$, but $u^{-}(x) \geqslant 0$ for all $x \in \Omega$, so $u^{-}(x)=0$ for all $x \in \Omega$.

Solving (1.1) reduces to look for nontrivial solutions of (2.1) where $f$ has been extended as above.

In addition (H5) and (H6) imply $a_{0} \not \equiv 0$ and $b_{0} \not \equiv 0$ in (H4).
The main results of this paper are the following theorems.
Theorem 2.1. Under conditions (H1)-(H6) there exists $\eta=\eta(p, q, N)>0$ such that problem (1.1) has at least two solutions for $a_{0}, b_{0}$ :

$$
\left\|a_{0}\right\|_{\sigma_{q}}^{p-1}\left\|b_{0}\right\|_{\sigma_{p}}^{1-q}<\eta
$$

One of them, call it $v$, satisfies $\Phi(v)>0$, while the other, call it $w$, satisfies $\Phi(w)<0$, where $\Phi$ denotes the associated energy:

$$
\Phi(u):=\frac{1}{2} \int_{\Omega}\left[(\Delta u)^{2}-c|\nabla u|^{2}\right] d x-\int_{\Omega} F(x, u) d x .
$$

In addition, if $f$ varies in such a way that the coefficients in $(\mathrm{H} 4)$ satisfy
$a_{0} \rightarrow 0 \quad$ in $L^{\sigma_{q}}(\Omega) \quad$ and $\quad b_{0}$ is bounded in $L^{\sigma_{p}}(\Omega)$,
then the solution $w=w_{f}$ can be constructed such that $w_{f} \rightarrow 0$ in $V$.
Applying this theorem to Eq. (1.4), we have
Corollary 2.1. Assume in (1.4) $\lambda>0,0 \leqslant q<1<p<2^{*}-1, a \in L^{\tau_{q}}(\Omega)$ with $\tau_{q}<\sigma_{q}$, $b \in L^{\tau_{p}}(\Omega)$ with $\tau_{p}<\sigma_{p}$, and, in addition, $a(x) \geqslant 0$ a.e. in $\Omega$ in case $q=0$. Suppose
(I1) there exists a nonempty open subset $\Omega_{1} \subset \Omega$ such that, on $\Omega_{1}, a(x) \geqslant \epsilon_{1}$ for some $\epsilon_{1}>0$ and $b(x)$ is bounded from below;
(I2) there exists a nonempty open subset $\Omega_{2} \subset \Omega$ such that, on $\Omega_{2}, b(x) \geqslant \epsilon_{2}$ for some $\epsilon_{2}>0$ and $a(x)$ is bounded from above and from below.

Then there exists $\tilde{\eta}=\tilde{\eta}(p, q, N)>0$ such that if

$$
\lambda<\frac{\tilde{\eta}}{\left\|a^{+}\right\|_{\sigma_{q}}\left\|b^{+}\right\|_{\sigma_{p}}^{(1-q)(p-1)}},
$$

then problem (1.4) has at least two solutions $v$ and $w$ such that $\Psi(v)>0$ and $\Psi(w)<0$, where $\Psi$ denotes the energy functional associated to (1.4). Moreover, if $\lambda \rightarrow 0$, the solution $w=w_{f}$ can be constructed such that $w_{f} \rightarrow 0$ in $V$.

## 3. Proofs

Lemma 3.1. Assume (H1)-(H3). Then $\Phi$ satisfies the (PS) condition on $V$.
Proof. As already observed in connection with (H1), $f$ is extended on all $\Omega \times R$ by putting $f(x, s)=f(x, 0)$ for a.e. $x \in \Omega$ and all $s<0$. It is then clear that (H2) implies that $\Phi$ is a $C^{1}$ functional on $V$.

To see that $\Phi$ satisfies (PS) condition, first note that by (H2) the map $s \rightarrow f(\cdot, s)$ takes bounded set in $L^{\sigma}(\Omega)$ into bounded sets in $L^{\sigma /(\sigma-1)}(\Omega) \subset H^{-1}(\Omega)$. So, and since for $\sigma<2^{*}$, by Rellich's theorem the space $H_{0}^{1}(\Omega)$ embeds into $L^{\sigma}(\Omega)$ compactly, the map $K: H_{0}^{1}(\Omega) \rightarrow H^{-1}(\Omega)$, given by $K(s)=f(\cdot, s)$, is compact. Now $D \Phi(s)=\Delta^{2} s+c \Delta s-$ $f(\cdot, s)$, and hence by Proposition 2.2.2 of [7] it suffices to show that any (PS)-sequence $\left(u_{n}\right)$ for $\Phi$ is bounded in $V$.

Let $\left(u_{n}\right)$ be a (PS) sequence, i.e., $\Phi\left(u_{n}\right)$ is bounded and $\Phi^{\prime}\left(u_{n}\right) \rightarrow 0$. So, for $\Theta$ as in (H3) and for some $\varepsilon_{n} \rightarrow 0$ and some constant $C$,

$$
\Theta \Phi\left(u_{n}\right)-\Phi^{\prime}\left(u_{n}\right) u_{n} \leqslant C+\varepsilon_{n}\left\|u_{n}\right\|_{V},
$$

where $\|\cdot\|_{V}$ denotes the norm on $V$. So we have

$$
\left(\frac{\Theta}{2}-1\right)\left\|u_{n}\right\|_{V}^{2}-\int_{\Omega}\left(\Theta F\left(x, u_{n}\right)-u_{n} f\left(x, u_{n}\right)\right) \leqslant C+\varepsilon_{n}\left\|u_{n}\right\|_{V}
$$

By (H3),

$$
\left(\frac{\Theta}{2}-1\right)\left\|u_{n}\right\|_{V}^{2} \leqslant c^{\prime}+\int_{\Omega} d(x)\left(u_{n}^{+}\right)^{r} d x+\varepsilon_{n}\left\|u_{n}\right\|_{V}
$$

where $c^{\prime}$ is another constant. Since $r<2$, we deduces that $\left\|u_{n}\right\|_{V}$ remains bounded. This completes the proof of Lemma 3.1.

Lemma 3.2. Let $0 \leqslant q<1<p, A>0, B>0$, and consider the function

$$
\Psi_{A, B}(t)=t^{2}-A t^{q+1}-B t^{p+1}
$$

for $t \geqslant 0$. Then $\max \left\{\Psi_{A, B}(t): t \geqslant 0\right\}>0$ if and only if

$$
A^{p-1} B^{q-1}<\frac{(p-1)^{p-1}(1-q)^{1-q}}{(p-q)^{p-q}}:=\eta_{1}(p, q) .
$$

Moreover, for

$$
t=t_{B}:=\left[\frac{1-q}{B(p-q)}\right]^{1 /(p-1)}
$$

one has

$$
\begin{equation*}
\Psi_{A, B}\left(t_{B}\right)=t_{B}^{2}\left[\frac{p-1}{p-q}-A B^{(1-q) /(p-1)}\left(\frac{p-q}{1-q}\right)^{(1-q) /(p-1)}\right] \tag{3.1}
\end{equation*}
$$

For the proof see Lemma 3.2 of [6].
Proof of Theorem 2.1. First, we will get the first solution by the classical mountain pass theorem. We observe that $\Phi(0)=0$. By (H4), Hölder inequality, and Sobolev inequality, we have

$$
\begin{align*}
\Phi(u) & \geqslant \frac{1}{2}\|u\|_{V}^{2}-\int_{\Omega}\left[\frac{a_{0}\left(u^{+}\right)^{q+1}}{q+1}+\frac{b_{0}\left(u^{+}\right)^{p+1}}{p+1}\right] d x \\
& \geqslant \frac{1}{2}\|u\|_{V}^{2}-m_{1}\left\|a_{0}\right\|_{\sigma_{q}}\|u\|_{0,1}^{q+1}-m_{2}\left\|b_{0}\right\|_{\sigma_{p}}\|u\|_{0,1}^{p+1} \\
& \geqslant \frac{1}{2}\|u\|_{V}^{2}-c_{1}\left\|a_{0}\right\|_{\sigma_{q}}\|u\|_{V}^{q+1}-c_{2}\left\|b_{0}\right\|_{\sigma_{p}}\|u\|_{V}^{p+1} \tag{3.2}
\end{align*}
$$

for all $u \in V$, where $m_{1}=(q+1)^{-1} S^{-(q+1) / 2}, m_{2}=(p+1)^{-1} S^{-(p+1) / 2}, c_{1}=m_{1} \times$ $\left(\lambda_{1}(\Omega)-c\right)^{-(q+1) / 2}, c_{2}=m_{2}\left(\lambda_{1}(\Omega)-c\right)^{-(p+1) / 2}$, and

$$
S:=\inf \left\{\int_{\Omega}|\nabla u|^{2} d x: u \in H_{0}^{1}(\Omega) \text { and } \int_{\Omega}|u|^{2^{*}} d x=1\right\}
$$

We now apply to (3.2) Lemma 3.2 with $A=2 c_{1}\left\|a_{0}\right\|_{\sigma_{q}}$ and $B=2 c_{2}\left\|b_{0}\right\|_{\sigma_{p}}$. This gives that for all $u \in V$ with $\|u\|_{V}=t_{B}$, we have

$$
\Phi(u) \geqslant \frac{1}{2} \Psi_{A, B}\left(t_{B}\right)>0
$$

provided that $A^{p-1} B^{q-1}<\eta_{1}(p, q)$, i.e., provided that

$$
\begin{equation*}
\left\|a_{0}\right\|_{\sigma_{q}}^{p-1}\left\|b_{0}\right\|_{\sigma_{p}}^{1-q}<\frac{\eta_{1}(p, q)}{\left(2 c_{1}\right)^{p-1}\left(2 c_{2}\right)^{1-q}}:=\eta(p, q, N) \tag{3.3}
\end{equation*}
$$

So we have obtained, under (3.3), a "range of mountains" around 0 .
Now we will look for some $u_{2} \in V$ such that $\Phi\left(t u_{2}\right) \rightarrow-\infty$ as $t \rightarrow+\infty$ by condition (H6). Let us choose $s_{3}$ sufficiently large so that $s_{3}>s_{0}$ (from (H3)) and, for some $\Theta_{3}>0, F(x, s) \geqslant \Theta_{3} s^{2}+1$ for a.e. $x \in \Omega_{2}$ and all $s \geqslant s_{3}$, which is clearly possible by (H6). For $x \in \Omega_{2}$ and $s \geqslant s_{3}$, we then divide the inequality of (H3) by $s F(x, s)$, integrate from $s_{3}$ to $s$ and take the exponential to get

$$
F(x, s) \geqslant F\left(x, s_{3}\right)\left(\frac{s}{s_{3}}\right)^{\Theta} \exp \left(-d(x) \int_{s_{3}}^{s} \frac{t^{r-1}}{F(x, t)} d t\right)
$$

So, by (H6),

$$
\begin{equation*}
F(x, s) \geqslant c s^{\Theta} \tag{3.4}
\end{equation*}
$$

for a.e. $x \in \Omega_{2}$ and all $s \geqslant s_{3}$, where $c>0$ is a constant. We now take a function $u_{2} \in$ $V \cap H^{\Theta}(\Omega)$ with support in $\Omega_{2}$ and $u_{2} \geqslant 0, u_{2} \not \equiv 0$, and consider $t u_{2}$ with $t \geqslant t_{2}$, where $t_{2}$ is such that measure of $\left\{x \in \Omega_{2}: t u_{2}(x) \geqslant s_{3}\right\}$ is $>0$. We have

$$
\Phi\left(t u_{2}\right)=\frac{t^{2}}{2}\left\|u_{2}\right\|_{V}^{2}-\int_{\Omega_{2}} F\left(x, t u_{2}\right) d x
$$

and, consequently, splitting the integral over $\Omega_{2}$ into an integral over $\left\{x \in \Omega_{2}: t u_{2}(x)<s_{3}\right\}$ and an integral over $\left\{x \in \Omega_{2}: t u_{2}(x) \geqslant s_{3}\right\}$, and applying (3.4) to the latter, we get, for some constants $c^{\prime}, c^{\prime \prime}$ with $c^{\prime \prime}>0$,

$$
\Phi\left(t u_{2}\right) \leqslant \frac{t^{2}}{2}\left\|u_{2}\right\|_{V}^{2}+c^{\prime}-c t^{\Theta} \int_{\left\{x \in \Omega_{2}: t u_{2}(x) \geqslant s_{3}\right\}}\left(u_{2}\right)^{\Theta} d x \leqslant \frac{t^{2}}{2}\left\|u_{2}\right\|_{V}^{2}+c^{\prime}-c^{\prime \prime} t^{\Theta}
$$

Since $\Theta>2$, this latter relation implies that $\Phi\left(t u_{2}\right) \rightarrow-\infty$ as $t \rightarrow+\infty$.
Under (3.3), we apply the mountain pass theorem, which yields a critical point $v$ of $\Phi$ with

$$
\begin{equation*}
\Phi(v) \geqslant \frac{1}{2} \Psi_{A, B}\left(t_{B}\right)>0 . \tag{3.5}
\end{equation*}
$$

This function $v$ is a nontrivial solution of (2.2), so we get the first solution $v$.
Next, we will get the second solution by local minimization. We will show that there exists $u_{1} \in V$ such that

$$
\begin{equation*}
\Phi\left(t u_{1}\right)<0 \tag{3.6}
\end{equation*}
$$

for all $t>0$ sufficiently small by condition (H5). Take for $u_{1}$ the positive eigenfunction associated to the principle eigenvalue of $-\Delta$ on $H_{0}^{1}\left(\Omega_{1}\right)$. It is known that $u_{1} \in L^{\infty}\left(\Omega_{1}\right)$. By (H5), we have, for $t>0$ sufficiently small (in fact $t \leqslant s_{1} /\left\|u_{1}\right\|_{\infty}$, so $0 \leqslant t u_{1} \leqslant s_{1}$ ),

$$
\Phi\left(t u_{1}\right)=\frac{t^{2}}{2}\left\|u_{1}\right\|_{V}^{2}-\int_{\Omega_{1}} F\left(x, t u_{1}\right) d x \leqslant \frac{t^{2}}{2}\left(\left\|u_{1}\right\|_{V}^{2}-\Theta_{1} \int_{\Omega_{1}}\left(u_{1}\right)^{2} d x\right)
$$

The term in parentheses is $<0$ since $\Theta_{1}>\lambda_{1}\left(\Omega_{1}\right) *\left(\lambda_{1}\left(\Omega_{1}\right)-c\right)$. So we have (3.6).
It follows from (3.6) that the minimum of the (weakly lower semicontinuous) functional $\Phi$ on the closed ball in $V$ with center 0 and radius $t_{B}$ is achieved in the corresponding open ball and thus yields a nontrivial solution $w$ of (2.2) with

$$
\begin{equation*}
\Phi(w)<0 \quad \text { and } \quad\|w\|_{V}<t_{B} \tag{3.7}
\end{equation*}
$$

So, we get the second solution.
This completes the proof of the existence of at least two solutions in Theorem 2.1.
We now turn to the study of the asymptotic behavior of one of these two solutions. When $f$ varies in such a way that $a_{0} \rightarrow 0$ in $L^{\sigma_{q}}(\Omega)$ and $b_{0}$ remains bounded in $L^{\sigma_{p}}(\Omega)$, we fix $\alpha \in] 0,1 /(1-q)\left[\right.$ and observe that for $t_{B}=\left\|a_{0}\right\|_{\sigma_{q}}^{\alpha}$ and for all $u$ with $\|u\|_{V}=t_{B}$, $t_{B} \rightarrow 0$. By (3.2), we have

$$
\begin{aligned}
\Phi(u) & \geqslant \frac{1}{2}\left\|a_{0}\right\|_{\sigma_{q}}^{2 \alpha}-c_{1}\left\|a_{0}\right\|_{\sigma_{q}}^{1+\alpha(q+1)}-c_{2}\left\|b_{0}\right\|_{\sigma_{p}}\left\|a_{0}\right\|_{\sigma_{q}}^{\alpha(p+1)} \\
& =\left\|a_{0}\right\|_{\sigma_{q}}^{2 \alpha}\left(\frac{1}{2}-c_{1}\left\|a_{0}\right\|_{\sigma_{q}}^{1-\alpha(1-q)}-c_{2}\left\|b_{0}\right\|_{\sigma_{p}}\left\|a_{0}\right\|_{\sigma_{q}}^{\alpha(p-1)}\right) .
\end{aligned}
$$

Since $1-\alpha(1-q)>0$, the expression is positive for $\left\|a_{0}\right\|_{\sigma_{q}}$ sufficiently small, so we have

$$
\Phi(u) \geqslant \frac{1}{2} \Psi_{A, B}\left(t_{B}\right)>0 \quad \text { for all } u \text { with }\|u\|_{V}=\left\|a_{0}\right\|_{\sigma_{q}}^{\alpha}=t_{B}
$$

By (3.7), the corresponding solution $w$ will converge to 0 in $V$. This complete the proof of Theorem 2.1.

Proof of Corollary 2.1. It is easy to verify that for each $\lambda>0$, conditions (H1)-(H6) of Theorem 2.1 hold.

## Acknowledgments

We would like to express our gratitude to Professor D.G. De Figueiredo, Professor J.P. Gossez, and Professor Guo Dajun for their helps.

## References

[1] A.C. Lazer, P.J. McKenna, Large-amplitude periodic oscillations in suspension bridges: Some new connections with nonlinear analysis, SIAM Rev. 32 (1990) 537-578.
[2] G. Tarantello, A note on a semilinear elliptic problem, Differential Integral Equations 5 (1992) 561-565.
[3] A.C. Lazer, P.J. McKenna, Global bifurcation and a theorem of Tarantello, J. Math. Anal. Appl. 181 (1994) 648-655.
[4] A.M. Micheletti, A. Pistoia, Multiplicity results for a fourth-order semilinear elliptic problem, Nonlinear Anal. 31 (1998) 895-903.
[5] J. Zhang, Existence results for some fourth-order nonlinear elliptic problems, Nonlinear Anal. 45 (2001) 29-36.
[6] D.G. De Figueiredo, J.P. Gossez, P. Ubilla, Local superlinearity and sublinearity for indefinite semilinear elliptic problem, http://www.ulb.ac.be/sciences/ulbmath/travaux/preprints2000-2001.html.
[7] M. Struwe, Variational Methods, Applications to Nonlinear Partial Differential Equations and Hamiltonian Systems, Springer, 1990.
[8] N. Castaneda, R. Ma, Positive solutions to a second order three-point boundary value problem, Appl. Anal. 76 (2000) 231-239.
[9] G. Xu, J. Zhang, Positive solutions to a second order $m$-point boundary value problem, submitted.


[^0]:    ${ }^{4}$ Project supported by CNSF and NSF of Education Committee of Jiangsu Province (No. 01kjd110003).

    * Corresponding author.

    E-mail addresses: xu_gui_xiang@sina.com (G. Xu), jihuiz@jlonline.com (J. Zhang).

