



# Construction of the fundamental solution of disturbed parabolic equation

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## Abstract

In present paper the parabolic equation solution is built. The construction is reduced to iterative procedure. And convergence of the latter is proven.

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## Résumé

Dans un travail présenté on a construit la solution d'équation parabolique. Cette construction est réduite à un procédé d'itération. On démontre la convergence de ce dernier.

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## 1. Introduction

In presented work the problem of construction of fundamental solution  $e^{t(L+L_1)}$  of equation

$$\frac{du}{dt} = (L + L_1)u$$

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is considered, where  $L$  and  $L_1$  are elliptic operators, and the properties of evolution operator  $e^{tL}$  of a non-disturbed equation

$$\frac{du}{dt} = Lu$$

are assumed to be known.

If the coefficients  $L$  and  $L_1$  are constant, then

$$e^{t(L+L_1)} = e^{tL} e^{tL_1}. \quad (1)$$

For the non-constant coefficients, satisfying some set of restrictions, we will prove that the right part of (1) under small  $t$  is quite good approximation for the evolution operator in the left part, that is,

$$e^{t(L+L_1)} = e^{tL} e^{tL_1} + A(t), \quad A(0) = 0,$$

and for the construction of family of operators  $A(t)$  the iteration procedure will be proposed. In this work two examples of parabolic equations are considered:

1.  $L$  is the elliptic operator with constant coefficients,

$$Lu = \frac{1}{2} a^{jk} \frac{\partial^2 u}{\partial x^j \partial x^k},$$

the perturbation  $L_1$  has a form

$$L_1 u = \frac{1}{2} b^{jk}(x) \frac{\partial^2 u}{\partial x^j \partial x^k}.$$

2.  $L = \frac{1}{2}\Delta$ , where  $\Delta$  is Laplace–Beltrami operator on complete simply connected Riemann manifold  $M$  of non-positive curvature with dimension  $n$ , and metrics tensor  $g_{jk}(x)$ , distance  $\rho$  and volume  $\sigma$ , that is

$$Lu(x) = \frac{1}{2} \operatorname{div} \operatorname{grad} u(x),$$

and perturbation has a form

$$L_1 u(x) = \frac{1}{2} \operatorname{div} b(x) \operatorname{grad} u(x).$$

In the both examples

$$(e^{tL} f)(x) = \int f(y) p_0(t, x, y) dy,$$

where  $p_0$  is a fundamental solution of non-disturbed equation. The aim of presented paper is to propose and to ground well a constructing of the function  $p$ , obtained from the equality

$$(e^{t(L+L_1)} f)(x) = \int f(y) p(t, x, y) dy.$$

Above-mentioned function  $p(t, x, y)$  will be searched in the form

$$p(t, x, y) = m(t, x, y) + \int_0^t d\tau \int m(t - \tau, x, z) r(\tau, z, y) dz, \quad (2)$$

where the initial approximation

$$m(t, x, y) = \int p(t, z, y) p_1(t, x, z) \sigma(dz), \quad (3)$$

the function  $p_1$  is an approximation of the kernel of integral operator  $e^{tL_1}$ , and  $r(t, x, y)$  is a function being subject to be obtained.

A procedure of constructing of fundamental solution is analogous to the same procedure in parametrix method, namely: Eq. (2) is reduced to Volterra's integral equation for the function  $r$

$$r(t, x, y) = M(t, x, y) + \int_0^t d\tau \int M(t - \tau, x, z) r(\tau, z, y) dz, \quad (4)$$

where an error  $M(t, x, y) = (L + L_1)m - \frac{\partial m}{\partial t}$ , and solution  $r$  of Eq. (3) has a structure  $r(t, x, y) = \sum_{n=0}^{\infty} r_n(t, x, y)$ , and each iteration is calculated with respect to recurrent formula:

$$\begin{aligned} r_0(t, x, y) &= M(t, x, y), \\ r_{n+1}(t, x, y) &= \int_0^t d\tau \int M(t - \tau, x, z) r_n(\tau, z, y) dz. \end{aligned}$$

Convergence of the last integral and the series  $\sum r_n$  is determined by properties of the error  $M(t, x, y)$ : it must have an integrable with respect to  $t$  singularity. Above-mentioned property holds under some restrictions on coefficients of the operators  $L$  and  $L_1$ .

Since the initial approximation  $m(t, x, y)$  (and hence, the error  $M(t, x, y)$  as well) is defined as an integral, for transforming of the error and its estimating the integration by the parts will be applied:

$$\int \operatorname{div} V(z) \mu(dz) = - \int (\Lambda(z), V(z)) \mu(dz),$$

where the role of the measure  $\mu$  the relation  $p_1(t, x, z) \sigma(dz)$  has:

$$\int \operatorname{div} V(z) p_1(t, x, z) \sigma(dz) = - \int (\Lambda(z), V(z)) p_1(t, x, z) \sigma(dz). \quad (5)$$

Here a logarithmic derivative is  $\Lambda(t, x, z) = \operatorname{grad}_x \ln p_1(t, x, z)$ .

### 1.1. Perturbation of the constant operator

Let's demonstrate the described method in particular case, considering a parabolic equation

$$\frac{\partial u}{\partial t} = \frac{1}{2} \operatorname{tr}(A + B(x)) u'', \quad x \in R^n, \quad (6)$$

where  $A$  is a constant operator in  $R^n$ , and a positive operator  $B(x)$  satisfies the conditions:

(1) a positive operator  $K_0$  exists, such that

$$K(x) = A^{-1/2}B(x)A^{-1/2} \leq K_0 \leq \delta I, \quad \delta < 1;$$

(2)  $\|B(x)B^{-1}(y)\| < \text{Const}$ ;

(3) the first two derivatives of the operator  $B(x)$  are bounded:

$$\begin{aligned} \|B'(x)h\| &\leq c_1\|h\|, \\ \|B''(x)kh\| &\leq c_2\|k\|\cdot\|h\|. \end{aligned}$$

From condition 2 the boundedness of the ratio  $\frac{\det B(x)}{\det B(y)}$  follows.  
The solution of non-disturbed equation is

$$p_0(t, x, y) = \frac{1}{(2\pi t)^{n/2}\sqrt{\det A}} \exp\left\{-\frac{(A^{-1}(x-y), x-y)}{2t}\right\}.$$

Put

$$p_1(t, x, y) = \frac{1}{(2\pi t)^{n/2}\sqrt{\det B(y)}} \exp\left\{-\frac{(B^{-1}(x)(x-y), x-y)}{2t}\right\},$$

then zero approximation is

$$m(t, x, y) = \int_{R^n} p(t, z, y) \frac{1}{(2\pi t)^{n/2}\sqrt{\det B(z)}} \exp\left\{-\frac{(B^{-1}(x)(x-z), x-z)}{2t}\right\} dz.$$

From conditions 1 and 2 an estimate follows:

$$\begin{aligned} m(t, x, y) &< \frac{c}{\sqrt{\det(I + K(x))}} \\ &\times \exp\left\{\frac{1}{2t}(A^{-1/2}K(x)A^{-1/2}(x-y), x-y)\right\} p_0(t, x, y) \\ &< c \exp\left\{\frac{1}{2t}(A^{-1/2}K_0A^{-1/2}(x-y), x-y)\right\} p_0(t, x, y). \end{aligned}$$

Error

$$M(t, x, y) = \frac{1}{2} \operatorname{tr}(A + B(x))m''_{xx} - \frac{\partial m}{\partial t} = I_1 + I_2,$$

where

$$I_1 = \int_{R^n} \left( \frac{1}{2} \operatorname{tr} B(x)p''_1(t, x, z) - \frac{\partial p_1}{\partial t}(t, x, z) \right) p_0(t, z, y) dz,$$

$$I_2 = \int_{R^n} \left( \frac{1}{2} \operatorname{tr} A p''_1(t, x, z) \cdot p(t, z, y) - \frac{\partial p_0}{\partial t}(t, z, y) p_1(t, x, z) \right) dz,$$

and differentiation is done with respect to variable  $x$ . For the next transformations let's reduce  $I_2$  to the form

$$I_2 = \frac{1}{2} \int_{R^n} (\operatorname{tr} A p''_1(t, x, z) p_0(t, z, y) - \operatorname{tr} A p''_{0xx}(t, z, y) p_1(t, x, z)) dz,$$

and integrate the second item twice by the parts, see (5):

$$\begin{aligned}
 & -\frac{1}{2} \int_{R^n} \text{tr}(Ap'_{0x}(t, z, y))'_x p_1(t, x, z) dz \\
 & = -\frac{1}{2} \int_{R^n} \text{div}_x(Ap'_{0x}(t, z, y)) p_1(t, x, z) dz \\
 & = \frac{1}{2} \int_{R^n} (p'_{0x}(t, z, y), A\Lambda(t, x, z)) p_1(t, x, z) dz \\
 & = -\frac{1}{2} \int_{R^n} [(A\Lambda(t, x, z), \Lambda(t, x, z)) + \text{div}_z A\Lambda(t, x, z)] p_0(t, z, y) p_1(t, x, z) dz.
 \end{aligned}$$

**Lemma 1.** *A logarithmic derivative  $\Lambda(t, x, z)$  of the measure  $p_1(t, x, z) dz$  is defined by the equality:*

$$(\Lambda(t, x, z), h) = -\frac{1}{2} \text{tr} B'(z) h B^{-1}(z) + \frac{1}{t} (B^{-1}(x)(x - z), h).$$

**Proof.** From definition

$$(\Lambda(t, x, z), h) = -\frac{1}{2} d_h \ln \det B(z) + \frac{1}{t} (B^{-1}(x)(x - z), h),$$

where  $d_h$  is a differential of function along vector  $h$  with respect to variable  $z$ .

Differentiating of the equality implies

$$\ln \det B(z) = \text{tr} \int_0^1 (B(z) - I) (I + \tau(B(z) - I))^{-1} d\tau,$$

and we get

$$d_h \ln \det B(z) = \text{tr} B'(z) h (B(z) - I)^{-1} \int_0^1 (B(z) - I) (I + \tau(B(z) - I))^{-2} d\tau,$$

thus, the statement of the lemma follows from the fact that the relation under integral sign equals

$$-\frac{d}{d\tau} (I + \tau(B(z) - I))^{-1}. \quad \square$$

**Corollary.**

$$\begin{aligned}
 I_2 &= \frac{1}{2} \int_{R^n} \left[ \frac{\text{tr} Ap''_1(t, x, z)}{p_1(t, x, z)} - (A\Lambda(t, x, z), \Lambda(t, x, z)) - \text{div}_x A\Lambda(t, x, z) \right] \\
 &\quad \times p_0(t, z, y) p_1(t, x, z) dz.
 \end{aligned}$$

**Lemma 2.** Error  $M(t, x, y)$  satisfies the following estimate:

$$|M(t, x, y)| \leq \frac{c}{\sqrt{t}} \int_{R^n} \left( 1 + \frac{\|x - z\|^4}{t^2} \right) p_0(t, z, y) p_1(t, x, z) dz.$$

**Proof.** Differentiating  $p_1$ , we reduce  $I_1$  to the form ( $\{e_k\}$  is an orthogonal basis in  $R^n$ ):

$$\begin{aligned} I_1 = & \frac{1}{2} \int_{R^n} \sum_k \left[ \frac{1}{4t^2} ((B^{-1})' e_k(x - z), x - z) ((B^{-1})' B e_k(x - z), x - z) \right. \\ & + \frac{1}{2t^2} ((B^{-1})' e_k(x - z), x - z) (x - z, e_k) \\ & + \frac{1}{2t^2} ((B^{-1})' B e_k(x - z), x - z) (B^{-1}(x - z), e_k) \\ & - \frac{1}{2t} ((B^{-1})'' e_k B e_k(x - z), x - z) - \frac{1}{t} ((B^{-1})' e_k(x - z), B e_k) \\ & \left. - \frac{1}{t} ((B^{-1})' B e_k(x - z), e_k) \right] p_0(t, z, y) p_1(t, x, z) dz. \end{aligned}$$

From lemma's conditions the relation in brackets satisfies the estimate:

$$c \left( \frac{\|x - z\|^4 + \|x - z\|^3}{t^2} + \frac{\|x - z\|}{t} \right) < \frac{c}{\sqrt{t}} \left( 1 + \frac{\|x - z\|^4}{t^2} \right),$$

that is,

$$I_1 < \frac{c}{\sqrt{t}} \int_{R^n} \left( 1 + \frac{\|x - z\|^4}{t^2} \right) p_0(t, z, y) p_1(t, x, z) dz.$$

For estimating  $I_2$  (see corollary to Lemma 1) we note that

$$\begin{aligned} \operatorname{div}_z A \Lambda(t, x, z) &= \operatorname{tr} A \Lambda'_z(t, x, z) \\ &= \operatorname{tr} A \left[ -\frac{1}{2} \operatorname{tr} B''(z)(\cdot) B^{-1}(z) \right. \\ &\quad \left. + \frac{1}{2} \operatorname{tr} B'(z)(\cdot) B^{-1}(z) B'(z)(\cdot) B^{-1}(z) - \frac{1}{t} B^{-1}(x) \right] \\ &= -\frac{1}{t} \operatorname{tr} A B^{-1}(x) + \phi(z), \end{aligned}$$

where the item  $\phi$  is bounded in lemma's statement. The relation under integral sign in  $I_2(A \Lambda(t, x, z), \Lambda(t, x, z))$  allows a presentation:

$$(A \Lambda(t, x, z), \Lambda(t, x, z)) = \frac{1}{t^2} (B^{-1}(x) A B^{-1}(x)(x - z), x - z) + \psi(t, x, z),$$

where

$$|\psi(t, x, z)| < \frac{c}{\sqrt{t}} \int_{R^n} \left( 1 + \frac{|x - z|}{\sqrt{t}} \right).$$

Calculating  $Ap_1''(t, x, z)$ , we see that under integral sign in  $I_2$  the relation satisfying desired estimate, remains.  $\square$

**Lemma 3.** *For error  $M(t, x, y)$  the following estimate holds:*

$$|M(t, x, y)| < \frac{c}{\sqrt{t}} \exp \left\{ \frac{1}{2t} (A^{-1/2} K_0 A^{-1/2}(x - y), x - y) \right\} p_0(t, x, y).$$

**Proof.** Let's use the equality

$$p_0(t, x, y) = \phi(t, z, x, y) p(t, x, y),$$

where

$$\begin{aligned} \phi(t, z, x, y) &= \exp \left\{ \frac{1}{t} (A^{-1}(y - x), z - x) \right\} \exp \left\{ -\frac{1}{2t} (A^{-1}(z - x), z - x) \right\} \\ &= \phi_1(t, x, y, z) \phi_2(t, x, z). \end{aligned}$$

From Lemma 2 the inequality follows:

$$\begin{aligned} |M(t, x, y)| &< \frac{c}{\sqrt{t}} p_0(t, x, y) \int_{R^n} \left( 1 + \frac{\|x - z\|^4}{t^2} \right) \\ &\quad \times \phi_2(t, x, z) \phi_1(t, x, y, z) p_1(t, x, z) dz, \end{aligned}$$

and from boundedness of the product  $\frac{\|x - z\|^4}{t^2} \phi_2(t, x, z)$  the estimate for error gets the form

$$|M(t, x, y)| < \frac{c}{\sqrt{t}} p_0(t, x, y) \int_{R^n} \exp \left\{ \frac{1}{t} (A^{-1}(z - x), y - x) \right\} p_1(t, x, z) dz.$$

Substituting  $z \rightarrow u$ ,  $u = \frac{1}{\sqrt{t}} B^{-1/2}(x)(z - x)$ ,  $z = x + \sqrt{t} B^{1/2}(x)u$ , we get an inequality

$$\begin{aligned} |M(t, x, y)| &< \frac{c}{\sqrt{t}} p_0(t, x, y) \\ &\quad \times \int_{R^n} \exp \left\{ \left( u, \frac{1}{\sqrt{t}} B^{1/2}(x) A^{-1}(y - x) \right) \right\} \sqrt{\frac{\det B(x)}{\det B(z)}} \mu(du), \end{aligned}$$

where  $\mu$  is a canonical Gaussian measure in  $R^n$ .

Calculation of the last integral (after estimating of the ratio of determinants) leads to an inequality

$$M(t, x, y) < \frac{c}{\sqrt{t}} p_0(t, x, y) \exp \left\{ \frac{1}{2t} (A^{-1} B(x) A^{-1}(y - x), y - x) \right\},$$

and the statement of lemma follows.  $\square$

**Theorem 1.** *Fundamental solution  $p(t, x, y)$  of disturbed equation (6) for  $t \in (0, T]$  satisfies an inequality*

$$p(t, x, y) < c \exp \left\{ \frac{(A^{-1/2} K_0 A^{-1/2}(x - y), x - y)}{2t} \right\} p_0(t, x, y).$$

**Proof.** Let us construct  $p_0(t, x, y)$  as a solution of integral equation (2). Estimating an iteration  $r_1(t, x, y)$  of Eq. (4):

$$\begin{aligned} |r_1(t, x, y)| &< \int_0^t d\tau \int_{R^n} |M(\tau, z, y)M(t - \tau, x, z)| dz \\ &< c^2 \int_0^t \frac{d\tau}{\sqrt{\tau(t - \tau)}} \int_{R^n} \exp \left\{ \frac{(A^{-1/2}K_0 A^{-1/2}(z - y), z - y)}{2\tau} \right. \\ &\quad \left. + \frac{(A^{-1/2}K_0 A^{-1/2}(z - x), z - x)}{2(t - \tau)} \right\} p_0(\tau, z, y) p_0(t - \tau, x, z) dz. \end{aligned}$$

We substitute

$$A^{-1/2} \left( z \sqrt{\frac{t}{\tau(t - \tau)}} - x \sqrt{\frac{\tau}{t(t - \tau)}} - y \sqrt{\frac{t - \tau}{t\tau}} \right) = u,$$

and hence relations

$$\begin{aligned} \frac{z - x}{\sqrt{t - \tau}} &= \sqrt{\frac{\tau}{t}} A^{1/2} u + \frac{\sqrt{t - \tau}}{t} (y - x), \\ \frac{z - y}{\sqrt{\tau}} &= \sqrt{\frac{t - \tau}{t}} A^{1/2} u + \frac{\sqrt{\tau}}{t} (x - y), \end{aligned} \tag{7}$$

transform a space integral in form

$$\begin{aligned} p_0(t, x, y) \exp \left\{ \frac{(A^{-1/2}K_0 A^{-1/2}(z - y), z - y)}{2t} \right\} \int_{R^n} \exp \left\{ \frac{(K_0 u, u)}{2} \right\} \mu(du) \\ = \frac{1}{\sqrt{\det(I - K_0)}} p_0(t, x, y) \exp \left\{ \frac{(A^{-1/2}K_0 A^{-1/2}(z - y), z - y)}{2t} \right\}, \end{aligned}$$

and from this

$$|r_1(t, x, y)| < c^2 c_1 \pi p_0(t, x, y) \exp \left\{ \frac{(A^{-1/2}K_0 A^{-1/2}(z - y), z - y)}{2t} \right\},$$

where  $c_1 = 1/\sqrt{\det(I - K_0)}$ .

It's easy to get by induction that the following estimate is true:

$$\begin{aligned} |r_n(t, x, y)| &< \int_0^t d\tau \int_{R^n} |r_{n-1}(\tau, z, y)M(t - \tau, x, z)| dz \\ &< c^{n+1} c_1^n \frac{\pi(n+1)/2}{\Gamma((n+1)/2)} \exp \left\{ \frac{(A^{-1/2}K_0 A^{-1/2}(x - y), x - y)}{2t} \right\} p_0(t, x, y), \end{aligned}$$

$c$  is a new constant, therefore

$$\begin{aligned} |r(t, x, y)| &< \sum_{n=0}^{\infty} |r_n(t, x, y)| \\ &< \frac{c}{\sqrt{t}} e^{ct} \exp \left\{ \frac{(A^{-1/2} K_0 A^{-1/2}(z-y), x-y)}{2t} \right\} p_0(t, x, y). \end{aligned}$$

Estimating an integral in (2) by means plugging in (6), we get

$$q(t, x, y) < c(1 + \sqrt{t}) \exp \left\{ \frac{(A^{-1/2} K_0 A^{-1/2}(x-y), x-y)}{2t} \right\} p_0(t, x, y),$$

and the statement of theorem follows.  $\square$

**Notation 1.** In this example the well-known explicit form of solution  $p_0(t, x, y)$  of non-disturbed equation was used for:

- 1) calculating of the function  $\phi$  in relation  $p_0(t, z, y) = \phi(t, x, z, y) p_0(t, x, y);$
- 2) solving and then estimating the integrals by means substitution (7).

Under disturbing the equation with variable coefficients (on manifold) an explicit form of  $p_0(t, x, y)$  is unknown, but the estimate of the function  $\phi$  will be obtained and the analogous substitution (7) will be presented.

## 2. Scalar perturbation of variable operator

Let  $p_0(t, x, y)$  be a fundamental solution (heat kernel) of parabolic equation

$$\frac{\partial u}{\partial t} = \frac{1}{2} \Delta u,$$

where  $\Delta$  is Laplace–Beltrami operator on complete simply connected Riemann manifold of non-positive curvature  $M$ ,  $\dim M = n$ . Denote as  $\gamma(s)$  geodezical, parametrized by natural parameter (as a rule,  $\gamma(0) = y$ ,  $\gamma(\rho(x, y)) = x$ ), and put  $e(x, y) = -\dot{\gamma}(x)$ .

The equation on the Riemann manifold is studied in many papers, some of them are [5,6].

Assume, that curvature tensor satisfies the following conditions:

2.1. For arbitrary  $x \in M$ ,  $U, V \in T_x M$ :

$$\sum_k |(R(x)(U, e_k)V, \phi_k)| < c \sqrt{\text{Ric}(x)(U, U) \text{Ric}(V, V)},$$

where

$$\text{Ric}(x)(U, U) = \sum_k (R(x)(U, e_k)V, e_k),$$

$\{e_k\}, \{\phi_k\}$  are arbitrary orthogonal basises in  $T_x M$ , and the constant  $c$  doesn't depend on  $x$ .

2.2. Along any geodezical the scalar curvature  $r(x) = \text{tr Ric}(x)$  decreases quite fast, that is:  $\int_0^\infty s r(\gamma(s)) ds < c$ , where  $c$  doesn't depend on  $y$ .

### 2.3. Co-variant derivative of the curvature tensor satisfies estimates

$$\begin{aligned} & \|(\nabla_{X(s)} R)(\gamma(s))(Y(s), \dot{\gamma}(x))Z(s)\| \\ & \leq f_1(\gamma(s))\|X(s)\|\|Y(s)\|\|Z(s)\|; \\ & \|(\nabla_{U(s)} \nabla_{X(s)} R)(\gamma(s))(Y(s), \dot{\gamma}(x))Z(s)\| \\ & \leq f_2(\gamma(s))\|X(s)\|\|Y(s)\|\|Z(s)\|\|U(s)\|, \end{aligned}$$

where  $f_1$  and  $f_2$  are such functions, that along any geodesical  $\gamma: \int_0^\infty s^2 f_k(\gamma(s)) ds < c$ ,  $c$  doesn't depend on  $\gamma$ .

Let us define along  $\gamma(s)$  an operator  $D$  on  $T_{\gamma(s)} M$

$$D(\gamma(s))U = \nabla_U \rho(y, \gamma(s))\dot{\gamma}(x), \quad \dot{\gamma}(x) = y,$$

and functions

$$\begin{aligned} a(x, y) &= \text{tr}(D(x) - I), \\ q(t, x, y) &= (2\pi t)^{n/2} \exp\left\{-\frac{\rho^2(x, y)}{2t}\right\}. \end{aligned} \tag{8}$$

As it was shown in [1–4], under satisfaction conditions 1–3, the following results hold:

1) heat kernel  $p_0(t, x, y)$  satisfies two-sided estimate

$$\exp\{-\phi(x, y) - kt\} \leq \frac{p_0(t, x, y)}{q(t, x, y)} \leq 1,$$

where

$$\phi(x, y) = \frac{1}{2} \int_0^{\rho(x, y)} (\rho(x, y) - \tau) \text{Ric}(\gamma(\tau))(\dot{\gamma}(\tau), \dot{\gamma}(\tau)) d\tau,$$

$k$  is some constant.

2) the relation holds:

$$\text{grad}_x \ln p_0(t, x, y) = \frac{\rho(x, y)}{t} e(x, y) + w(t, x, y),$$

where  $\|w(t, x, y)\| < c$ ,  $x, y \in M$ ,  $0 < t \leq T$ .

3) the function  $a(x, y)$  satisfies the estimate

$$0 \leq a(x, y) \leq \int_0^{\rho(x, y)} s \text{Ric}(\gamma(s))(\dot{\gamma}(s), \dot{\gamma}(s)) ds,$$

$\text{grad}_x a(x, y) < c$ ,  $|\Delta_x(x, y)| < c$ .

As a consequence of the relation for logarithmic gradient (condition 2) we have

**Lemma 4.** *The following inequality is true:*

$$p_0(t, z, y) \leq p_0(t, x, y) \phi_1(t, x, y, z) \phi_2(t, x, z),$$

where

$$\begin{aligned}\phi_1 &= \exp\{\rho(x, y)\rho(x, y)(e(x, y), e(x, z))\}, \\ \phi_2 &= \exp\left\{-\frac{\rho^2(x, z)}{2t} + c\rho(x, z)\right\}.\end{aligned}$$

**Proof.** Let  $\sigma(s)$  be geodezicals, connecting  $z$  and  $x$ ,  $\sigma(0) = x$ ,  $\sigma(\rho(x, z)) = z$ . Integrating equality (2), we have

$$\begin{aligned}p_0(t, z, y) &= p_0(t, x, y) \left\{ \frac{1}{t} \int_0^{\rho(x, z)} \rho(y, \sigma(s))(e(\sigma(s), y), \dot{\sigma}(s)) ds \right. \\ &\quad \left. + \int_0^{\rho(x, z)} (w(t, \sigma(s)), \dot{\sigma}(s)) ds \right\}.\end{aligned}$$

Notice that

$$\rho(y, \sigma(s))(e(\sigma(s), y), \dot{\sigma}(s)) = -\frac{1}{2} \frac{d}{ds} \rho^2(y, \sigma(s)),$$

and, thus, we have an inequality

$$p_0(t, z, y) \leq p_0(t, x, y) \exp\left\{ \frac{\rho^2(x, y) - \rho^2(z, y)}{2t} + c\rho(x, z) \right\}.$$

We can make stronger, using cosines theorem for manifold of non-positive curvature  $\rho^2(y, z) \geq \rho^2(x, y) + \rho^2(x, z) - 2\rho(x, z)\rho(x, y)(e(x, y), e(x, z))$ , and this leads to desired result.  $\square$

Let us consider a perturbation

$$L_1 u = \frac{1}{2} \operatorname{div} b(x) \operatorname{grad} u,$$

where a scalar function  $b(x)$  satisfies conditions:

- 1)  $0 < b_1 \leq b(x) \leq b_2 < 1$ ;
- 2)  $\|\operatorname{grad} b(x)\| < c$ ,  $\nabla_U \operatorname{grad} b(x) < c \|U\|$ .

Put

$$p_1(t, x, y) = (2\pi t b(x))^{-n/2} \exp\left\{ \frac{\rho^2(x, z)}{2tb(x)} \right\},$$

and define function  $m(t, x, y)$  via equality (3). Then error of disturbed equation be

$$M(t, x, y) = \frac{1}{2} \operatorname{div}(1 + b(x)) \operatorname{grad} m(t, x, y) - \frac{\partial}{\partial t} m(t, x, y) = I_1 + I_2, \quad (9)$$

where

$$I_1 = \int_M \left( \frac{1}{2} \operatorname{div}_x b(x) \operatorname{grad}_x p_1(t, x, z) - \frac{\partial p_1(t, x, z)}{\partial t} \right) p_0,$$

and the item  $I_2$  after applying of formula (5) and integrating by the parts has a form

$$\begin{aligned} I_2 = & \int_M (\Delta_x p_1(t, x, z) - \|\Lambda(t, x, z)\|^2 p_1(t, x, z) \\ & - \operatorname{div}_z \Lambda(t, x, z) p_1(t, x, z)) p_0(t, z, y) \sigma(dz). \end{aligned}$$

**Lemma 5.** Functions  $m(t, x, y)$  and  $I_1$  are bounded by values

$$c \exp\left\{\frac{b(x)\rho^2(x, y)}{2t}\right\} p_0(t, x, y) \quad \text{and} \quad \frac{c}{\sqrt{t}} \exp\left\{\frac{b(x)\rho^2(x, y)}{2t}\right\} p_0(t, x, y)$$

correspondingly.

**Proof.** From the statement of Lemma 4 (since  $\phi_2$  is negative) an estimate follows

$$\begin{aligned} m(t, x, y) &< c p(t, x, y) \int_M (2\pi t b(x))^{-n/2} \\ &\quad \times \exp\left\{\frac{\rho(x, y)\rho(x, z)(e(x, y), e(x, z))}{t} - \frac{\rho^2(x, z)}{2tb(x)}\right\} \sigma(dz) \\ &= c \exp\left\{\frac{b(x)\rho^2(x, y)}{2t}\right\} p(t, x, y) \int_M (2\pi t b(z))^{n/2} \\ &\quad \times \exp\left\{-\frac{\|\rho(x, z)e(x, z) - b(x)\rho(x, y)e(x, y)\|}{2tb(x)}\right\} \sigma(dz). \end{aligned}$$

A substitution

$$U = \frac{\rho(x, z)e(x, z) - b(x)\rho(x, y)e(x, y)}{\sqrt{tb(x)}},$$

$$z(U) = \operatorname{Exp}_x \{ \sqrt{tb(x)} U + b(x)\rho(x, y)e(x, y) \}$$

transforms the last integral to

$$\int_{T_x M} \left( \frac{b(x)}{b(z(U))} \right)^{n/2} J(z(U)) \mu_x(dU),$$

where  $\mu_x$  is canonical measure on  $T_x M$ , and boundedness of Jacobian  $J$  is proved in [6]. Thus, the estimate of  $m(t, x, y)$  is obtained.  $\square$

For estimating of  $I_1$  we transform the function under integral sign.

$$\begin{aligned} \frac{\partial p_1}{\partial t}(t, x, z) &= \left( -\frac{n}{2t} + \frac{\rho^2(x, z)}{2t^2 b(x)} \right) p_1(t, x, z); \\ \operatorname{grad}_x p_1(t, x, z) &= \frac{1}{t} \left( \frac{\rho^2(x, z) \operatorname{grad} b(x)}{2b^2(x)} - \frac{\rho^2(x, z) \dot{\gamma}(\rho(x, y))}{b(x)} \right) p_1(t, x, z); \\ (\nabla_U b(x) \operatorname{grad}_x p_1(t, x, z), U) &= p_1(t, x, z) \left[ \frac{1}{t^2 b(x)} \left( \rho^2(x, z) (\dot{\gamma}(\rho), U)^2 - \frac{\rho^3(x, z) (\operatorname{grad} b(x), U) (\dot{\gamma}(\rho), U)}{b(x)} \right) \right. \\ &\quad \left. - \frac{\rho^2(x, z) \dot{\gamma}(\rho) (\operatorname{grad} b(x), U)}{t b(x)} \right] \end{aligned}$$

$$\begin{aligned} & + \frac{\rho^4(x, z)}{4b^2(x)} (\text{grad } b(x), U)^2 \Big) + \frac{1}{t} \left( \frac{(\nabla_U \rho^2(x, z) \text{grad } b(x), U)}{2b(x)} \right. \\ & \left. - \frac{\rho^2(x, z) (\text{grad } b(x), U)^2}{2b^2(x)} - D(x)U \right). \end{aligned}$$

A summation with respect to orthogonal basis  $\{e_k\}$  in  $T_x M$  ( $e_1 = \dot{\gamma}(\rho)$ ) gives:

$$\begin{aligned} & \frac{1}{2} \text{div } b(x) \text{grad } p_1(t, x, z) - \frac{\partial}{\partial t} p_1(t, x, z) \\ & = \left( \frac{\rho(x, z) (\text{grad } b(x), \dot{\gamma})}{2t^2 b^2(x)} + s \frac{\rho^4(x, z) \|\text{grad } b(x)\|^2}{8t^2 b^3(x)} - \frac{1}{2t} \text{tr}(D(x) - I) \right. \\ & \quad + \frac{\rho(x, z)}{2tb(x)} (\text{grad } b(x), \dot{\gamma}(\rho)) - \frac{\rho^2(x, z)}{4tb^2(x)} \|\text{grad } b(x)\|^2 \\ & \quad \left. + \frac{\rho(x, z)}{4tb(x)} \Delta b(x) \right) p_1(t, x, z). \end{aligned}$$

Obtained relation we estimate by the value  $\frac{c}{\sqrt{t}} (1 + \frac{\rho^4(x, z)}{t^2}) p_1(t, x, z)$ , and as  $(\frac{\rho(x, z)}{\sqrt{t}})^k \varphi_2(t, x, z)$  is bounded, then

$$(I_2) < \frac{c}{\sqrt{t}} p_0(t, x, y) \int_M \varphi_1(t, x, y, z) p_1(t, x, z) \sigma(dz).$$

The second statement of lemma follows.

We are coming to estimating of the item  $I_2$ , containing a logarithmic derivative

$$\Lambda(t, x, z) = -\frac{n}{2} \frac{\text{grad } b(z)}{b(z)} - \frac{\rho(x, z) \dot{\gamma}(\rho(x, z))}{tb(x)} \in T_x M.$$

**Lemma 6.** *The following estimate is true:*

$$|I_2| \leq \frac{c}{\sqrt{t}} \exp \left\{ \frac{\rho^2(x, y) b(x)}{2t} \right\} p_0(t, x, y).$$

**Proof.** Note, that

$$\begin{aligned} & \|\Lambda(t, x, z)\|^2 + \text{div}_z \Lambda(t, x, z) \\ & = \left( \frac{n}{2} + \frac{n^2}{4} \right) \frac{\|\text{grad } b(x)\|^2}{b^2(x)} + \frac{\rho^2(x, z)}{t^2 b^2(x)} \\ & \quad + \frac{n}{tb(x)b(z)} \rho(x, z) (\dot{\gamma}(\rho(x, z), \text{grad } b(z))) - \frac{n \Delta b(z)}{2b(z)} - \frac{\text{tr } D(z)}{tb(x)}. \end{aligned}$$

The second item under integral sign

$$\begin{aligned} \Delta_x p_1(t, x, z) & = \left[ \frac{1}{t^2} \left( \frac{\rho^4(x, z) \|\text{grad } b(x)\|^2}{4b^4(x)} \right. \right. \\ & \quad \left. \left. - \frac{\rho^3(x, z) (\text{grad } b(x), \dot{\gamma}(\rho))}{b^3(x)} + \frac{\rho^2(x, z)}{b^2(x)} \right) \right. \end{aligned}$$

$$+ \frac{1}{t} \left( \frac{2\rho(x, z)(\text{grad } b(x), \dot{\gamma}(\rho))}{b^2(x)} + \frac{\rho^2(x, z)}{2b^2(x)} \Delta b(x) \right. \\ \left. - \frac{\rho^2(x, z)}{b^3(x)} \|\text{grad } b(x)\|^2 - \frac{1}{b(x)} \text{tr } D(x) \right) p_1(t, x, z),$$

and difference

$$\Delta_x p_1(t, x, z) - p_1(t, x, z) (\|\Lambda(t, x, z)\|^2 + \text{div}_z \Lambda(t, x, z))$$

is estimated by the value

$$\frac{c}{\sqrt{t}} \left( 1 + \frac{\rho^4(x, z)}{t^2} \right) p_1(t, x, z),$$

which has integrable with respect to  $t$  singularity. Desired statement is proved by the same way like in Lemma 5.  $\square$

**Corollary 2.** Error  $M(t, x, y)$ , defined by (9), satisfies an estimate

$$M(t, x, y) < \frac{c}{\sqrt{t}} \exp \left\{ \frac{b(x)\rho^2(x, y)}{2t} \right\} p_0(t, x, y).$$

**Notation 3.** Since the inequalities

$$b(x) \leq b_2 < 1 \quad \text{and} \quad p < q$$

hold, the function  $\exp \left\{ \frac{b(x)\rho^2(x, y)}{2t} \right\}$  is integrable with respect to measure  $p_0(t, x, y) \sigma(dy)$ .

**Theorem 2.** Fundamental solution  $p(t, x, y)$  of disturbed equation

$$\frac{\partial u}{\partial t} = \frac{1}{2} \text{div}(1 + b(x)) \text{grad } u$$

satisfies the estimate:

$$p(t, x, y) < c \exp \left\{ \frac{b_2 \rho^2(x, y)}{2t} \right\} q(t, x, y) \\ \leq c \exp \left\{ \frac{b_2 \rho^2(x, y)}{2t} + \varphi(x, y) + kt \right\} p_0(t, x, y),$$

where functions  $q(t, x, y)$  and  $\varphi(x, y)$  are determined by formulas (8) and (9) correspondingly.

**Proof.** We will prove a convergence of  $\sum_{n=0}^{\infty} r_n$  under solution of Volterra's equation, estimating the items of series. From corollary of Lemmas 5 and 6 and the inequality  $p \leq q$  an estimate follows:

$$|r_1(t, x, y)| = \left| \int_0^t d\tau \int_M M(t - \tau, x, z) M(\tau, z, y) \sigma(dz) \right|$$

$$< c^2 \int_0^t \frac{d\tau}{\sqrt{\tau(t-\tau)}} \int_M (4\pi^2 \tau(t-\tau))^{-n/2} \\ \times \exp \left\{ -\frac{(1-b_2)}{2} \left( \frac{\rho^2(y, x)}{\tau} + \frac{\rho^2(x, z)}{t-\tau} \right) \right\} \sigma(dz).$$

Let us transform the inner integral by means substitution

$$u = \left( \sqrt{\frac{t}{\tau(t-\tau)}} \rho(x, z) e(x, z) - \sqrt{\frac{t-\tau}{t\tau}} \rho(x, y) e(x, y) \right) \sqrt{1-b_2}, \\ z(u) = \text{Exp}_x \left( \sqrt{\frac{\tau(t-\tau)}{t(1-b_2)}} u + \frac{t-\tau}{t} \rho(x, y) e(x, y) \right). \quad (10)$$

The argument of exponent equals here

$$-\frac{1}{2} \|u\|^2 - \frac{\rho^2(x, y)}{2t} (1-b_2) - \frac{(1-b_2)}{\tau} (\rho^2(y, z) - \rho^2(x, y) - \rho^2(x, z) \\ + 2\rho(x, y)\rho(x, z)(e(x, y), e(x, z))),$$

and the relation in brackets is non-negative because of curvature non-positivity. Thus,

$$\int_M (4\pi^2 \tau(t-\tau))^{-n/2} \exp \left\{ -\frac{(1-b_2)}{2} \left( \frac{\rho^2(y, z)}{\tau} + \frac{\rho^2(x, z)}{t-\tau} \right) \right\} \sigma(dz) \\ \leq (1-b_2)^{-n/2} \exp \left\{ \frac{b_2 \rho^2(x, y)}{2t} \right\} q(t, x, y) \int_{T_x M} J(z(u)) \mu_x(du).$$

So, we have

$$|r_1(t, x, y)| < c^2 c_1 \pi \exp \left\{ \frac{b_2 \rho^2(x, y)}{2t} \right\} q(t, x, y),$$

where  $c_1 = (1-b_2)^{-n/2} \sup_{z \in M} J(z)$ .

It's easy to obtain an estimate

$$|r_n(t, x, y)| < \frac{c^{n+1} c_1^n \pi^{(n+1)/2} t^{(n-1)/2}}{\Gamma((n+1)/2)} \exp \left\{ \frac{b_2 \rho^2(x, y)}{2t} \right\} q(t, x, y),$$

providing with absolute convergence of series  $\sum_{n=0}^{\infty} r_n(t, x, y)$ ,  $0 < t \leq T$  and for the sum of series

$$|r(t, x, y)| < \frac{c}{\sqrt{t}} \exp \left\{ \frac{b_2 \rho^2(x, y)}{2t} \right\} q(t, x, y).$$

Then

$$\begin{aligned}
 p(t, x, y) &= m(t, x, y) + \int_0^t d\tau \int_M m(t - \tau, x, z) r(\tau, z, y) \sigma(dz) \\
 &< c \exp\left\{\frac{b_2 \rho^2(x, y)}{2t}\right\} q(t, x, y) (1 + \sqrt{t}),
 \end{aligned}$$

and this implies, finally, the statement of theorem.  $\square$

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