# Monotone method for a system of nonlinear mixed type implicit impulsive integro-differential equations in Banach spaces ${ }^{\text {T}}$ 

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#### Abstract

In this paper, by using a monotone iterative technique in the presence of lower and upper solutions, we discuss the existence of solutions for a new system of nonlinear mixed type implicit impulsive integro-differential equations in Banach spaces. Under wide monotonicity conditions and the noncompactness measure conditions, we also obtain the existence of extremal solutions and a unique solution between lower and upper solutions.


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## 1. Introduction

It is well known that the theory of impulsive differential equations is a new and important branch of differential equation theory, which has an extensive physical, chemical, biological, engineering background and realistic mathematical model, and hence has been emerging as an important area of investigation in the last few decades, see [1-9]. Correspondingly, applications of the theory of impulsive differential equations to different areas were considered by many authors and some basic results on impulsive differential equations have been obtained (see, for example, [10-22], and the references therein). Furthermore, the existence of solutions to impulsive differential equations or impulsive integro-differential equations in Banach spaces has also been studied by many authors, see [1, 7,23-40,50,51].

Recently, He and He [51] investigated the existence of minimal and maximal solutions of impulsive integrodifferential equations with periodic boundary conditions by establishing a comparison result and using the method of upper and lower solutions and the monotone iterative technique. Ahmad and Sivasundaram [7] developed the

[^0]monotone method for impulsive hybrid set integro-differential equations in all its generality. Very recently, Li and Liu [27] pointed out "the monotone iterative technique in the presence of lower and upper solutions is an important method for seeking solutions of differential equations in abstract spaces". Further, Li and Liu used a monotone iterative technique in the presence of lower and upper solutions to discuss the existence of solutions for the initial value problem of the impulsive integro-differential equation of Volterra type in a Banach space E:
\[

\left\{$$
\begin{array}{l}
u^{\prime}(t)=f(t, u(t), T u(t)), \quad t \in J, t \neq t_{k}, \\
\left.\triangle u\right|_{t=t_{k}}=I_{k}\left(u\left(t_{k}\right)\right), \quad(i=1,2, \ldots, m) \\
u(0)=x_{0}
\end{array}
$$\right.
\]

where $f \in C(J \times E \times E, E), J=[0, a], 0<t_{1}<t_{2}<\cdots<t_{m}<a$ and $I_{k} \in C(E, E), k=1,2, \ldots, m$. Under wide monotonicity conditions and the noncompactness measure condition of nonlinearity $f$, the authors also obtained the existence of extremal solutions and a unique solution between lower and upper solutions. On the other hand, Sun and Ma [34] used a monotone iterative technique in the presence of lower and upper solutions to discuss the existence of solutions for the following initial value problem of the impulsive integro-differential equation of Volterra type in a Banach space:

$$
\left\{\begin{array}{l}
u^{\prime \prime}(t)-f(x, u, u)=\theta, \quad x \in J, x \neq x_{i}, \\
\left.\Delta u\right|_{x=x_{i}}=I_{i}\left(u\left(x_{i}\right)\right), \quad(i=1,2, \ldots, m) \\
\left.\Delta u^{\prime}\right|_{x=x_{i}}=\bar{I}_{i}\left(u\left(x_{i}\right)\right), \quad(i=1,2, \ldots, m) \\
u(0)=w_{0}, \quad u^{\prime}(0)=w_{1}
\end{array}\right.
$$

For more details of the monotone iterative methods, the readers can refer to [7,33,34,43-51] and the references therein.
In this paper, we study the following system of nonlinear mixed type implicit impulsive integro-differential equation problem in Banach spaces $E_{1}$ and $E_{2}$ : Find $(x, y): J \times J \rightarrow E_{1} \times E_{2}$ such that

$$
\left\{\begin{array}{l}
x^{\prime}(t)=f(t, x(t), y(t), \lambda S x(t)), \quad t \neq t_{k},  \tag{1.1}\\
y^{\prime}(t)=g(t, y(t), x(t), \mu T y(t)), \quad t \neq t_{k}, \\
\left.\Delta x\right|_{t=t_{k}}=I_{k}\left(x\left(t_{k}\right)\right), \quad(k=1,2, \ldots, m), \\
\left.\Delta y\right|_{t=t_{k}}=\hat{I}_{k}\left(y\left(t_{k}\right)\right), \quad(k=1,2, \ldots, m), \\
x\left(t_{0}\right)=x_{0}, \quad y\left(t_{0}\right)=y_{0},
\end{array}\right.
$$

where $J=\left[t_{0}, t_{0}+a\right] \subset R=(-\infty,+\infty)$ is a compact interval, $t_{0}<t_{1}<\cdots<t_{m}<t_{0}+a<+\infty$, $f: J \times E_{1} \times E_{2} \times E_{1} \rightarrow E_{1}$ and $g: J \times E_{2} \times E_{1} \times E_{2} \rightarrow E_{2}$ are continuous, $\lambda, \mu \geq 0$ are two constants, $x_{0} \in E_{1}$, $y_{0} \in E_{2}$,

$$
S x(t)=\int_{t_{0}}^{t} h(t, s) x(s) \mathrm{d} s
$$

is a Volterra integral operator with integral kernel $h(t, s) \in C\left(D, \mathbb{R}^{+}\right), D=\{(t, s) \mid s, t \in J, t \geq s\}, \mathbb{R}^{+}=[0,+\infty)$,

$$
T y(t)=\int_{t_{0}}^{t} \kappa(t, s) y(s) \mathrm{d} s
$$

is a Fredholm integral operator with integral kernel $\kappa(t, s) \in C\left(D_{0}, \mathbb{R}^{+}\right), D_{0}=\{(t, s) \mid s, t \in J\}$, and for $k=1,2, \ldots, m, I_{k} \in C\left[E_{1}, E_{1}\right], \hat{I}_{k} \in C\left[E_{2}, E_{2}\right],\left.\Delta x\right|_{t=t_{k}}$ denotes the jump of $x(t)$ at $t=t_{k}$, i.e., $\left.\Delta x\right|_{t=t_{k}}=$ $x\left(t_{k}^{+}\right)-x\left(t_{k}^{-}\right), x\left(t_{k}^{-}\right)$and $x\left(t_{k}^{+}\right)$represent the left and right limits of $x(t)$ at $t=t_{k}$, respectively.

If $\lambda=0$ and $\mu=0$, then problem (1.1) reduces to finding $(x, y): J \times J \rightarrow E_{1} \times E_{2}$ such that

$$
\left\{\begin{array}{l}
x^{\prime}(t)=f(t, x(t), y(t)), \quad t \neq t_{k},  \tag{1.2}\\
y^{\prime}(t)=g(t, y(t), x(t)), \quad t \neq t_{k}, \\
\left.\Delta x\right|_{t=t_{k}}=I_{k}\left(x\left(t_{k}\right)\right), \quad(k=1,2, \ldots, m), \\
\left.\Delta y\right|_{t=t_{k}}=\hat{I}_{k}\left(y\left(t_{k}\right)\right), \quad(k=1,2, \ldots, m), \\
x\left(t_{0}\right)=x_{0}, \quad y\left(t_{0}\right)=y_{0}
\end{array}\right.
$$

If $f=g, x=y, E_{1}=E_{2}=E$ and for $k=1,2, \ldots, m, I_{k}=\hat{I}_{k}$, then problem (1.2) further simplifies to finding $x: J \rightarrow E$ such that

$$
\left\{\begin{array}{l}
x^{\prime}(t)=f(t, x(t), x(t)), \quad t \neq t_{k},  \tag{1.3}\\
\left.\Delta x\right|_{t=t_{k}}=I_{k}\left(x\left(t_{k}\right)\right), \quad(k=1,2, \ldots, m), \\
x\left(t_{0}\right)=x_{0} .
\end{array}\right.
$$

Problem (1.3) was studied by some authors when $f(t, x, y) \equiv p(t, x)$ for all $t \in J$ and $x, y \in E$, see, for example, [1, 22,28].

Remark 1.1. For appropriate and suitable choices of $f, g, \lambda, \mu, S, T, I_{k}, \hat{I}_{k}$ and $E_{i}$ for $i=1,2$, it is easy to see that problem (1.1) includes a number (systems) of differential equations, impulsive differential equations, (impulsive) integro-differential equations studied by many authors as special cases, see, for example, [1-40,43,44,48-50] and the references therein.

The purpose of this paper is to discuss the existence of solutions for the new system of nonlinear mixed type implicit impulsive integro-differential equation (1.1) in Banach spaces by using a monotone iterative technique in the presence of lower and upper solutions. Further, under wide monotonicity conditions and the noncompactness measure conditions, we obtain the existence of extremal solutions and a unique solution between lower and upper solutions. The new and useful results obtained in this paper improve and extend some relevant results in abstract differential equations.

## 2. Preliminaries

Let $E$ be an ordered Banach space with the norm $\|\cdot\|$ and partial order $\leq$, whose positive cone $P=\{x \in E \mid x \geq 0\}$ is normal with normal constant $N$. Let $J=\left[t_{0}, t_{0}+a\right]$ (where $a>0$ ), $t_{0}<t_{1}<\cdots<t_{m}<t_{0}+a<+\infty$, $J_{0}=\left[t_{0}, t_{1}\right], J_{1}=\left(t_{1}, t_{2}\right], \ldots, J_{k}=\left(t_{k}, t_{k+1}\right], \ldots, J_{m}=\left(t_{m}, t_{0}+a\right]$ and

$$
\begin{aligned}
P C(J, E)= & \left\{x: J \rightarrow E \mid x(t) \text { is continuous at } t \neq t_{k},\right. \text { and left } \\
& \text { continuous at } \left.t=t_{k}, \text { and } x\left(t_{k}^{+}\right) \text {exists, } k=1,2, \ldots, m\right\} .
\end{aligned}
$$

Evidently, $P C(J, E)$ is a Banach space with norm $\|x\|_{P C}=\sup _{t \in J} x(t)$. Let $J^{\prime}=J \backslash\left\{t_{1}, t_{2}, \ldots, t_{m}\right\}$. An abstract function $(x, y) \in P C\left(J, E_{1}\right) \cap C^{1}\left(J^{\prime}, E_{1}\right) \cap P C\left(J, E_{2}\right) \cap C^{1}\left(J^{\prime}, E_{2}\right)$ is called a solution of problem (1.1) if $(x(t), y(t))$ satisfies all the equalities of (1.1).

Let

$$
P C^{1}(J, E)=\left\{x \in P C(J, E) \cap C^{1}\left(J^{\prime}, E\right) \mid x^{\prime}\left(t_{k}^{+}\right), x^{\prime}\left(t_{k}^{-}\right) \text {exist, } k=1,2, \ldots, m\right\}
$$

where $x^{\prime}\left(t_{k}^{+}\right)$and $x^{\prime}\left(t_{k}^{-}\right)$represent the right and left derivatives of $x(t)$ at $t=t_{k}$, respectively. For $x \in P C^{1}(J, E)$, by virtue of the mean value theorem

$$
x\left(t_{k}\right)-x\left(t_{k}-h\right) \in h \overline{c o}\left\{x^{\prime}(t): t_{k}-h<t<t_{k}\right\} \quad(h>0),
$$

it is easy to see that the left derivative $x_{-}^{\prime}\left(t_{k}\right)$ exists and

$$
x_{-}^{\prime}\left(t_{k}\right)=\lim _{h \rightarrow 0^{+}} h^{-1}\left[x\left(t_{k}\right)-x\left(t_{k}-h\right)\right]=x^{\prime}\left(t_{k}^{-}\right),
$$

where $\overline{c o}\left\{x^{\prime}(t): t_{k}-h<t<t_{k}\right\}$ denotes the smallest closed convex subset containing $\left\{x^{\prime}(t): t_{k}-h<t<t_{k}\right\}$ in $P C^{1}(J, E)$, and $\operatorname{co}(K)=\left\{x \mid x=\sum_{y \in K} \lambda_{y} y, \lambda_{y} \in[0,1]\right.$, there exist finite numbers $\lambda_{y} \neq 0$ and $\left.\sum_{y \in K} \lambda_{y}=1\right\}$ for $K \subset P C^{1}(J, E)$. In what follows, $x^{\prime}\left(t_{k}\right)$ is understood as $x_{-}^{\prime}\left(t_{k}\right)$, hence $x^{\prime} \in P C(J, E)$. Evidently, $P C^{1}(J, E)$ is a Banach space with norm $\|x\|_{P C^{1}}=\max \left\{\sup _{t \in J}\|x(t)\|, \sup _{t \in J}\left\|x^{\prime}(t)\right\|\right\}$.

If $(x, y) \in P C\left(J, E_{1}\right) \cap C^{1}\left(J^{\prime}, E_{1}\right) \cap P C\left(J, E_{2}\right) \cap C^{1}\left(J^{\prime}, E_{2}\right)$ is a solution of problem (1.1), then by the continuity of $f, g,(x, y) \in P C^{1}\left(J, E_{1}\right) \cap P C^{1}\left(J, E_{2}\right)$.

A mapping $F: J \rightarrow E$ is differentiable at $t \in J$ if there exists a $F^{\prime}(t) \in E$ such that the limits

$$
\lim _{h \rightarrow 0^{+}} \frac{F(t+h)-F(t)}{h}
$$

and

$$
\lim _{h \rightarrow 0^{+}} \frac{F(t)-F(t-h)}{h}
$$

exist and are equal to $F^{\prime}(t)$. Here the limits are taken in $E$. At the endpoints of $J$, we consider the one-sided derivatives.
Let $C(J, E)$ denote the Banach space of all continuous $E$-value functions on interval $J$ with norm $\|x\|_{C}=$ $\max _{t \in J}\|x(t)\|$. Let $\alpha(\cdot)$ denote the Kuratowski measure of noncompactness of the bounded set. For the details of the definition and properties of the measure of noncompactness, see [38]. For any $B \subset C(J, E)$ and $t \in J$, set $B(t)=\{x(t) \mid x \in B\} \subset E$. If $B$ is bounded in $C(J, E)$, then $B(t)$ is bounded in $E$, and $\alpha(B(t)) \leq \alpha(B)$.

Now, we first give the following lemmas in order to prove our main results.
Lemma 2.1 ([39]). Let $B \subset C(J, E)$ be bounded and equicontinuous. $\alpha(B(t))$ is continuous on $J$, and

$$
\alpha\left(\left\{\int_{J} x(t) \mathrm{d} t \mid x \in B\right\}\right) \leq \int_{J} \alpha(B(t)) \mathrm{d} t .
$$

Lemma 2.2 ([40]). Let $B=\left\{x_{n}\right\} \subset P C(J, E)$ be a bounded and countable set. $\alpha(B(t))$ is a Lebesque integral on $J$, and

$$
\alpha\left(\left\{\int_{J} x_{n}(t) \mathrm{d} t\right\}\right) \leq 2 \int_{J} \alpha(B(t)) \mathrm{d} t .
$$

Lemma 2.3 ([27]). For any $p \in P C^{1}(J, \mathbb{B}), v \in \mathbb{B}$ and $\omega_{k} \in \mathbb{B}, k=1,2, \ldots, m$, the line initial value problem

$$
\left\{\begin{array}{l}
u^{\prime}(t)+M u(t)=p(t), \quad t \neq t_{k},  \tag{2.1}\\
\left.\Delta u\right|_{t=t_{k}}=\omega_{k}, \quad(k=1,2, \ldots, m), \\
u\left(t_{0}\right)=v,
\end{array}\right.
$$

has a unique solution $u \in P C^{1}(J, \mathbb{B})$ given by

$$
u(t)=v \mathrm{e}^{-M\left(t-t_{0}\right)}+\int_{t_{0}}^{t} \mathrm{e}^{-M(t-s)} p(s) \mathrm{d} s+\sum_{t_{0}<t_{k}<t} \mathrm{e}^{-M\left(t-t_{k}\right)} \omega_{k},
$$

where $M \geq 0$ is a constant.

## 3. Main results

In this section, we are in a position to prove our main results concerning the solutions of the nonlinear mixed type implicit impulsive integro-differential equation system (1.1) in Banach spaces.

If a function $(v, \omega) \in P C^{1}\left(J, E_{1}\right) \times P C^{1}\left(J, E_{2}\right)$ satisfies

$$
\left\{\begin{array}{l}
v^{\prime}(t) \leq f(t, x(t), y(t), \lambda S x(t)), \quad t \neq t_{k},  \tag{3.1}\\
\omega^{\prime}(t) \leq g(t, y(t), x(t), \mu T y(t)), \quad t \neq t_{k}, \\
\left.\Delta v\right|_{t=t_{k}} \leq I_{k}\left(x\left(t_{k}\right)\right), \quad(k=1,2, \ldots, m), \\
\left.\Delta \omega\right|_{t=t_{k}} \leq \hat{I}_{k}\left(y\left(t_{k}\right)\right), \quad(k=1,2, \ldots, m), \\
v\left(t_{0}\right) \leq x_{0}, \quad \omega\left(t_{0}\right) \leq y_{0},
\end{array}\right.
$$

we call it a lower solution of problem (1.1); if all the inequalities of (3.1) are inverse, we call it an upper solution of problem (1.1).
Lemma 3.1. $(x, y) \in P C^{1}\left(J, E_{1}\right) \times P C^{1}\left(J, E_{2}\right)$ is a solution of problem (1.1) if and only if $x \in P C^{1}\left(J, E_{1}\right)$ and $y \in P C^{1}\left(J, E_{2}\right)$ satisfy the following impulsive integral equations

$$
\left\{\begin{array}{l}
x(t)=x_{0} \mathrm{e}^{-M_{1}\left(t-t_{0}\right)}+\int_{t_{0}}^{t} \mathrm{e}^{-M_{1}(t-s)}\left[f(s, x(s), y(s), \lambda S x(s))+M_{1} x(s)\right] \mathrm{d} s+\sum_{t_{0}<t_{k}<t} \mathrm{e}^{-M_{1}\left(t-t_{k}\right)} I_{k}\left(x\left(t_{k}\right)\right), \\
y(t)=y_{0} \mathrm{e}^{-M_{2}\left(t-t_{0}\right)}+\int_{t_{0}}^{t} \mathrm{e}^{-M_{2}(t-s)}\left[g(s, y(s), x(s), \mu T y(s))+M_{2} y(s)\right] \mathrm{d} s+\sum_{t_{0}<t_{k}<t} \mathrm{e}^{-M_{2}\left(t-t_{k}\right)} \hat{I}_{k}\left(y\left(t_{k}\right)\right),
\end{array}\right.
$$

where $M_{i}>0(i=1,2)$ is a constant.
Proof. The proof directly follows from Lemma 2.1 in [26] and it is omitted.
Now, let us first list the following assumptions for convenience:
$\left(\mathrm{H}_{1}\right)$ There exist $u_{0}, v_{0} \in P C^{1}\left[J, E_{1}\right], v_{0}, \omega_{0} \in P C^{1}\left[J, E_{2}\right]$ and constants $M_{1}, M_{2}>0$ such that for all $t \in J$, $v_{0}(t) \leq u_{0}(t), \omega_{0}(t) \leq v_{0}(t),\left(v_{0}, \omega_{0}\right) \in P C^{1}\left(J, E_{1}\right) \times P C^{1}\left(J, E_{2}\right)$ and $\left(u_{0}, v_{0}\right) \in P C^{1}\left(J, E_{1}\right) \times P C^{1}\left(J, E_{2}\right)$ are lower and upper solutions of problem (1.1), respectively, and

$$
f\left(t, x_{2}, y_{2}, z_{2}\right)-f\left(t, x_{1}, y_{1}, z_{1}\right) \geq-M_{1}\left(x_{2}-x_{1}\right)
$$

for all $t \in J$ and $v_{0}(t) \leq x_{1} \leq x_{2} \leq u_{0}(t), \omega_{0}(t) \leq y_{1} \leq y_{2} \leq \nu_{0}(t)$ and $\lambda S v_{0}(t) \leq z_{1} \leq z_{2} \leq \lambda S u_{0}(t)$, and

$$
g\left(t, y_{2}, x_{2}, \xi_{2}\right)-g\left(t, y_{1}, x_{1}, \xi_{1}\right) \geq-M_{2}\left(y_{2}-y_{1}\right)
$$

for all $t \in J$ and $v_{0}(t) \leq x_{1} \leq x_{2} \leq u_{0}(t), \omega_{0}(t) \leq y_{1} \leq y_{2} \leq v_{0}(t)$ and $\mu T \omega_{0}(t) \leq \xi_{1} \leq \xi_{2} \leq \mu T v_{0}(t)$.
$\left(\mathrm{H}_{2}\right) I_{k}(x)$ and $\hat{I}_{k}(y)$ are increasing on intervals $\left[v_{0}(t), u_{0}(t)\right]$ and $\left[\omega_{0}(t), v_{0}(t)\right]$ for $t \in J, k=1,2, \ldots, m$, respectively, where $\left[v_{0}(t), u_{0}(t)\right]=\left\{x \in P C^{1}\left[J, E_{1}\right] \mid v_{0}(t) \leq x(t) \leq u_{0}(t), t \in J\right\}$ and $\left[\omega_{0}(t), v_{0}(t)\right]=$ $\left\{x \in P C^{1}\left[J, E_{2}\right] \mid \omega_{0}(t) \leq x(t) \leq \nu_{0}(t), t \in J\right\}$.
$\left(\mathrm{H}_{3}\right)$ There exists $L_{i}>0(i=1,2)$ such that

$$
\begin{aligned}
& \alpha\left(\left\{f\left(t, x_{n}(t), y_{n}(t), z_{n}(t)\right)\right\}\right) \leq L_{1}\left[\alpha\left(\left\{x_{n}(t)\right\}\right)+\alpha\left(\left\{z_{n}(t)\right\}\right)\right] \\
& \alpha\left(\left\{g\left(t, y_{n}(t), x_{n}(t), \xi_{n}(t)\right)\right\}\right) \leq L_{2}\left[\alpha\left(\left\{y_{n}(t)\right\}\right)+\alpha\left(\left\{\xi_{n}(t)\right\}\right)\right]
\end{aligned}
$$

for all $t \in J$ and increasing or decreasing monotonic sequences $\left\{x_{n}\right\} \subset\left[v_{0}(t), u_{0}(t)\right],\left\{y_{n}\right\} \subset\left[\omega_{0}(t), v_{0}(t)\right]$, $\left\{z_{n}\right\} \subset\left[\lambda S v_{0}(t), \lambda S u_{0}(t)\right]$ and $\left\{\xi_{n}\right\} \subset\left[\mu T \omega_{0}(t), \mu T v_{0}(t)\right]$.
In what follows, we prove the following main result of this paper.
Theorem 3.1. Let $E_{1}$ and $E_{2}$ be two ordered Banach spaces, whose positive cone $P_{i}(i=1,2)$ is normal, $f \in C\left(J \times E_{1} \times E_{2} \times E_{1}, E_{1}\right), g \in C\left(J \times E_{2} \times E_{1} \times E_{2}, E_{2}\right)$, and $I_{k} \in C\left(E_{1}, E_{1}\right), \hat{I}_{k} \in C\left(E_{2}, E_{2}\right)$, $k=1,2, \ldots, m$. Suppose that the conditions $\left(\mathrm{H}_{1}\right)-\left(\mathrm{H}_{3}\right)$ hold. Then problem (1.1) has minimal and maximal solutions between $\left(v_{0}, \omega_{0}\right)$ and $\left(u_{0}, v_{0}\right)$, which can be obtained by a monotone iterative procedure starting from $\left(v_{0}, \omega_{0}\right)$ and ( $u_{0}, \nu_{0}$ ), respectively.
Proof. For any $(x, y) \in P C^{1}\left(J, E_{1}\right) \times P C^{1}\left(J, E_{2}\right)$, define $(P x, Q y)$ on $J \times J$ by the equation

$$
\left\{\begin{array}{l}
(P x)(t)=x_{0} \mathrm{e}^{-M_{1}\left(t-t_{0}\right)}+\int_{t_{0}}^{t} \mathrm{e}^{-M_{1}(t-s)}\left[f(s, x(s), y(s), \lambda S x(s))+M_{1} x(s)\right] \mathrm{d} s  \tag{3.2}\\
\quad+\sum_{t_{0}<t_{k}<t} \mathrm{e}^{-M_{1}\left(t-t_{k}\right)} I_{k}\left(x\left(t_{k}\right)\right) \\
(Q y)(t)=y_{0} \mathrm{e}^{-M_{2}\left(t-t_{0}\right)}+\int_{t_{0}}^{t} \mathrm{e}^{-M_{2}(t-s)}\left[g(s, y(s), x(s), \mu T y(s))+M_{2} y(s)\right] \mathrm{d} s \\
\quad+\sum_{t_{0}<t_{k}<t} \mathrm{e}^{-M_{2}\left(t-t_{k}\right)} \hat{I}_{k}\left(y\left(t_{k}\right)\right)
\end{array}\right.
$$

Now define $\|\cdot\|_{*}$ on $P C^{1}\left(J, E_{1}\right) \times P C^{1}\left(J, E_{2}\right)$ by

$$
\|(x, y)\|_{*}=\|x\|+\|y\|, \quad \forall(x, y) \in P C^{1}\left(J, E_{1}\right) \times P C^{1}\left(J, E_{2}\right)
$$

It is easy to see that $\left(P C^{1}\left(J, E_{1}\right) \times P C^{1}\left(J, E_{2}\right),\|\cdot\|_{*}\right)$ is a Banach space (see [41]). Thus, for any given $(x, y) \in P C^{1}\left(J, E_{1}\right) \times P C^{1}\left(J, E_{2}\right)$, it follows from (3.2) that

$$
\left\{\begin{array}{l}
(P x)^{\prime}(t)=-M_{1} P(x(t))+M_{1} x(t)+f(t, x(t), y(t), \lambda S x(t)) \\
(Q y)^{\prime}(t)=-M_{2} Q(x(t))+M_{2} y(t)+g(t, y(t), x(t), \mu T y(t))
\end{array}\right.
$$

and so $F(x, y):=(P x, Q y) \in P C^{1}\left(J, E_{1}\right) \times P C^{1}\left(J, E_{2}\right)$ is a continuous mapping from $P C^{1}\left(J, E_{1}\right) \times P C^{1}\left(J, E_{2}\right)$ into $P C^{1}\left(J, E_{1}\right) \times P C^{1}\left(J, E_{2}\right)$. By Lemma 3.1, the solution of problem (1.1) is equivalent to the fixed point of $F$. By assumptions $\left(\mathrm{H}_{1}\right)$ and $\left(\mathrm{H}_{2}\right), F$ is increasing in $\left[v_{0}, u_{0}\right] \times\left[\omega_{0}, v_{0}\right]$, and maps any bounded set in $\left[v_{0}, u_{0}\right] \times\left[\omega_{0}, v_{0}\right]$ into a bounded set.

Firstly, we show that $v_{0} \leq P v_{0}, P u_{0} \leq u_{0}, \omega_{0} \leq Q \omega_{0}$ and $Q v_{0} \leq \nu_{0}$. In fact, let $p(t)=v_{0}^{\prime}(t)+M_{1} v_{0}(t)$, by the definition of lower solution, $p \in P C^{1}\left(J, E_{1}\right)$ and $p(t) \leq f\left(t, v_{0}(t), \omega_{0}(t), \lambda S v_{0}(t)\right)+M_{1} v_{0}(t)$ for $t \in J^{\prime}$. Because $v_{0}(t)$ is a solution of problem (2.1) for $v=v_{0}\left(t_{0}\right)$ and $\omega_{k}=\left.\Delta v_{0}\right|_{t=t_{k}}(k=1,2, \ldots, m)$, it follows from Lemma 2.3 that for all $t \in J$,

$$
\begin{aligned}
v_{0}(t) & =\mathrm{e}^{-M_{1}\left(t-t_{0}\right)} v_{0}\left(t_{0}\right)+\int_{t_{0}}^{t} \mathrm{e}^{-M_{1}(t-s)} p(s) \mathrm{d} s+\left.\sum_{t_{0}<t_{k}<t} \mathrm{e}^{-M_{1}\left(t-t_{k}\right)} \Delta v_{0}\right|_{t=t_{k}} \\
& \leq \mathrm{e}^{-M_{1}\left(t-t_{0}\right)} v_{0}+\int_{t_{0}}^{t} \mathrm{e}^{-M_{1}(t-s)} p(s) \mathrm{d} s+\sum_{t_{0}<t_{k}<t} \mathrm{e}^{-M_{1}\left(t-t_{k}\right)} \Delta I_{k}\left(v\left(t_{k}\right)\right) \\
& \leq P v_{0}(t),
\end{aligned}
$$

i.e., $v_{0} \leq P v_{0}$. Similarly, it can be shown that $P u_{0} \leq u_{0}, \omega_{0} \leq Q \omega_{0}$ and $Q \nu_{0} \leq \nu_{0}$. Combining these facts and the increasing property of $F$ in $\left[v_{0}, u_{0}\right] \times\left[\omega_{0}, \nu_{0}\right]$, we see that $F$ maps $\left[v_{0}, u_{0}\right] \times\left[\omega_{0}, \nu_{0}\right]$ into itself and $F$ is a continuously increasing operator.

Next, we define two sequences $\left\{\left(v_{n}, \omega_{n}\right)\right\}$ and $\left\{\left(u_{n}, v_{n}\right)\right\}$ in $\left[v_{0}, u_{0}\right] \times\left[\omega_{0}, \nu_{0}\right]$ by the iterative scheme

$$
\begin{equation*}
v_{n}=P v_{n-1}, \quad u_{n}=P u_{n-1}, \quad \omega_{n}=Q \omega_{n-1}, \quad v_{n}=Q v_{n-1}, \quad n=1,2, \ldots \tag{3.3}
\end{equation*}
$$

Then by the monotonicity of $F$, we obtain

$$
\begin{align*}
& v_{0} \leq v_{1} \leq \cdots \leq v_{n} \leq \cdots \leq u_{n} \leq \cdots \leq u_{1} \leq u_{0}  \tag{3.4}\\
& \omega_{0} \leq \omega_{1} \leq \cdots \leq \omega_{n} \leq \cdots \leq v_{n} \leq \cdots \leq v_{1} \leq \nu_{0}
\end{align*}
$$

We shall prove that $\left\{v_{n}\right\}$ and $\left\{u_{n}\right\}$ are uniformly convergent in $J$, and $\left\{\omega_{n}\right\}$ and $\left\{v_{n}\right\}$ are uniformly convergent in $J$.
For convenience, let $B=\left\{v_{n} \mid n \in \mathbb{N}\right\}, V=\left\{\omega_{n} \mid n \in \mathbb{N}\right\}$ and $B_{0}=\left\{v_{n-1} \mid n \in \mathbb{N}\right\}, V_{0}=\left\{\omega_{n-1} \mid n \in \mathbb{N}\right\}$. Since $B=P\left(B_{0}\right), V=Q\left(V_{0}\right)$, by (3.2) and the boundedness of $B_{0}$ and $V_{0}$, we easily see that $B$ and $V$ are equicontinuous in every interval $J_{k}^{\prime}$, where $J_{1}^{\prime}=\left[t_{0}, t_{1}\right]$ and $J_{k}^{\prime}=\left(t_{k-1}, t_{k}\right], k=2,3, \ldots, m$. From $B_{0}=B \cup\left\{v_{0}\right\}$ and $V_{0}=V \cup\left\{\omega_{0}\right\}$, it follows that $\alpha\left(B_{0}(t)\right)=\alpha(B(t))$ and $\alpha\left(V_{0}(t)\right)=\alpha(V(t))$ for $t \in J$. Letting

$$
\phi(t)=(\alpha(B(t)), \alpha(V(t)))=\left(\alpha\left(B_{0}(t)\right), \alpha\left(V_{0}(t)\right)\right), \quad t \in J,
$$

by Lemma 2.1, we know that $\phi \in P C\left(J, \mathbb{R}^{+}\right) \times P C\left(J, \mathbb{R}^{+}\right)$. Going from $J_{1}^{\prime}$ to $J_{m+1}^{\prime}$ interval-by-interval, we show that $\phi(t) \equiv 0$ in $J$.

Indeed, for $t \in J$, there exists a $J_{k}^{\prime}$ such that $t \in J_{k}^{\prime}$. By Lemma 2.1, we have that

$$
\begin{aligned}
\alpha\left(S\left(B_{0}\right)(t)\right) & =\alpha\left(\left\{\int_{t_{0}}^{t} h(t, s) v_{n-1}(s) \mathrm{d} s \mid n \in \mathbb{N}\right\}\right) \\
& \leq \sum_{j=1}^{k-1} \alpha\left(\left\{\int_{t_{j-1}}^{t_{j}} h(t, s) v_{n-1}(s) \mathrm{d} s \mid n \in \mathbb{N}\right\}\right)+\alpha\left(\left\{\int_{t_{k-1}}^{t} h(t, s) v_{n-1}(s) \mathrm{d} s \mid n \in \mathbb{N}\right\}\right) \\
& \leq h_{0} \sum_{j=1}^{k-1} \int_{t_{j-1}}^{t_{j}} \alpha\left(B_{0}(s)\right) \mathrm{d} s+h_{0} \int_{t_{k-1}}^{t} \alpha\left(B_{0}(s)\right) \mathrm{d} s \\
& =h_{0} \int_{t_{0}}^{t} \alpha\left(B_{0}(s)\right) \mathrm{d} s
\end{aligned}
$$

and

$$
\begin{aligned}
\alpha\left(T\left(V_{0}\right)(t)\right) & =\alpha\left(\left\{\int_{t_{0}}^{t} \kappa(t, s) \omega_{n-1}(s) \mathrm{d} s \mid n \in \mathbb{N}\right\}\right) \\
& \leq \sum_{j=1}^{k-1} \alpha\left(\left\{\int_{t_{j-1}}^{t_{j}} \kappa(t, s) \omega_{n-1}(s) \mathrm{d} s \mid n \in \mathbb{N}\right\}\right)+\alpha\left(\left\{\int_{t_{k-1}}^{t} \kappa(t, s) \omega_{n-1}(s) \mathrm{d} s \mid n \in \mathbb{N}\right\}\right)
\end{aligned}
$$

$$
\begin{aligned}
& \leq \kappa_{0} \sum_{j=1}^{k-1} \int_{t_{j-1}}^{t_{j}} \alpha\left(V_{0}(s)\right) \mathrm{d} s+\kappa_{0} \int_{t_{k-1}}^{t} \alpha\left(V_{0}(s)\right) \mathrm{d} s \\
& =\kappa_{0} \int_{t_{0}}^{t} \alpha\left(V_{0}(s)\right) \mathrm{d} s
\end{aligned}
$$

where $h_{0}=\max \{|h(t, s)|:(t, s) \in D\}$ and $\kappa_{0}=\max \left\{|\kappa(t, s)|:(t, s) \in D_{0}\right\}$. Thus,

$$
\begin{equation*}
\int_{t_{0}}^{t} \alpha\left(S\left(B_{0}\right)(s)\right) \mathrm{d} s \leq a h_{0} \int_{t_{0}}^{t} \alpha\left(B_{0}(s)\right) \mathrm{d} s, \quad \int_{t_{0}}^{t} \alpha\left(T\left(V_{0}\right)(s)\right) \mathrm{d} s \leq a \kappa_{0} \int_{t_{0}}^{t} \alpha\left(V_{0}(s)\right) \mathrm{d} s \tag{3.5}
\end{equation*}
$$

For $t \in J_{1}^{\prime}$, from (3.2), using Lemma 2.2, assumption $\left(\mathrm{H}_{3}\right)$ and (3.5), we have

$$
\begin{aligned}
\alpha(B(t)) & =\alpha\left(P\left(B_{0}\right)(t)\right) \\
& =\alpha\left(\left\{\int_{t_{0}}^{t} \mathrm{e}^{-M_{1}(t-s)}\left(f\left(s, v_{n-1}(s), \omega_{n-1}(s), \lambda S v_{n-1}(s)\right)+M_{1} v_{n-1}(s)\right) \mathrm{d} s\right\}\right) \\
& \leq 2 \int_{t_{0}}^{t} \mathrm{e}^{-M_{1}(t-s)} \alpha\left(\left\{\left(f\left(s, v_{n-1}(s), \omega_{n-1}(s), \lambda S v_{n-1}(s)\right)+M_{1} v_{n-1}(s)\right)\right\}\right) \mathrm{d} s \\
& \leq 2 \int_{t_{0}}^{t}\left(L_{1}\left(\alpha\left(B_{0}(s)\right)+\lambda \alpha\left(S\left(B_{0}\right)(s)\right)\right)+M_{1} \alpha\left(B_{0}(s)\right)\right) \mathrm{d} s \\
& \leq 2\left(L_{1}+M_{1}\right) \int_{t_{0}}^{t} \alpha\left(B_{0}(s)\right) \mathrm{d} s+2 L_{1} \lambda \int_{t_{0}}^{t} \alpha\left(S\left(B_{0}\right)(s)\right) \mathrm{d} s \\
& \leq 2\left(L_{1}+M_{1}+a h_{0} L_{1} \lambda\right) \int_{t_{0}}^{t} \alpha\left(B_{0}(s)\right) \mathrm{d} s \\
\alpha(V(t)) & =\alpha\left(Q\left(V_{0}\right)(t)\right) \\
& =\alpha\left(\left\{\int_{t_{0}}^{t} \mathrm{e}^{-M_{2}(t-s)}\left(f\left(s, \omega_{n-1}(s), v_{n-1}(s), \mu T \omega_{n-1}(s)\right)+M_{2} \omega_{n-1}(s)\right) \mathrm{d} s\right\}\right) \\
& \leq 2 \int_{t_{0}}^{t} \mathrm{e}^{-M_{2}(t-s)} \alpha\left(\left\{\left(f\left(s, \omega_{n-1}(s), v_{n-1}(s), \mu T \omega_{n-1}(s)\right)+M_{2} \omega_{n-1}(s)\right)\right\}\right) \mathrm{d} s \\
& \leq 2 \int_{t_{0}}^{t}\left(L_{2}\left(\alpha\left(V_{0}(s)\right)+\mu \alpha\left(T\left(V_{0}\right)(s)\right)\right)+M_{2} \alpha\left(V_{0}(s)\right)\right) \mathrm{d} s \\
& \leq 2\left(L_{2}+M_{2}\right) \int_{t_{0}}^{t} \alpha\left(V_{0}(s)\right) \mathrm{d} s+2 L_{2} \mu \int_{t_{0}}^{t} \alpha\left(T\left(V_{0}\right)(s)\right) \mathrm{d} s \\
& \leq 2\left(L_{2}+M_{2}+a \kappa_{0} L_{2} \mu\right) \int_{t_{0}}^{t} \alpha\left(V_{0}(s)\right) \mathrm{d} s
\end{aligned}
$$

and so

$$
\begin{aligned}
\phi(t) & =(\alpha(B(t)), \alpha(V(t))) \\
& \leq\left(2\left(L_{1}+M_{1}+a h_{0} L_{1} \lambda\right) \int_{t_{0}}^{t} \alpha\left(B_{0}(s)\right) \mathrm{d} s, 2\left(L_{2}+M_{2}+a \kappa_{0} L_{2} \mu\right) \int_{t_{0}}^{t} \alpha\left(V_{0}(s)\right) \mathrm{d} s\right) \\
& =\Gamma \int_{t_{0}}^{t}\left(\alpha\left(B_{0}(s)\right), \alpha\left(V_{0}(s)\right)\right) \mathrm{d} s \\
& =\Gamma \int_{t_{0}}^{t} \phi(s) \mathrm{d} s
\end{aligned}
$$

where $\Gamma=\max \left\{2\left(L_{1}+M_{1}+a h_{0} L_{1} \lambda\right), 2\left(L_{2}+M_{2}+a \kappa_{0} L_{2} \mu\right)\right\}$. Hence, by the Bellman inequality, we know that $\phi(t) \equiv 0$ in $J_{1}^{\prime}$. In particular, $\left(\alpha\left(B\left(t_{1}\right)\right), \alpha\left(V\left(t_{1}\right)\right)\right)=\left(\alpha\left(B_{0}\left(t_{1}\right)\right), \alpha\left(V_{0}\left(t_{1}\right)\right)\right)=\phi\left(t_{1}\right)=0$, this means that $B\left(t_{1}\right), B_{0}\left(t_{1}\right)$ and $V\left(t_{1}\right), V_{0}\left(t_{1}\right)$ are precompact in $E_{1}$ and $E_{2}$, respectively. Therefore, $I_{1}\left(B_{0}\left(t_{1}\right)\right)$ and $\hat{I}_{1}\left(V_{0}\left(t_{1}\right)\right)$ are precompact in $E_{1}$ and $E_{2}$, respectively. This implies that

$$
\alpha\left(I_{1}\left(B_{0}\left(t_{1}\right)\right)\right)=0 \quad \text { and } \quad \alpha\left(\hat{I}_{1}\left(V_{0}\left(t_{1}\right)\right)\right)=0
$$

Now, for $t \in J_{2}^{\prime}$, by (3.2) and the above argument for $J_{1}^{\prime}$, we have

$$
\begin{aligned}
\phi(t)= & (\alpha(B(t)), \alpha(V(t))) \\
\leq & \left(2\left(L_{1}+M_{1}+a h_{0} L_{1} \lambda\right) \int_{t_{0}}^{t} \alpha\left(B_{0}(s)\right) \mathrm{d} s+\alpha\left(I_{1}\left(v_{n-1}\left(t_{1}\right)\right)\right),\right. \\
& \left.2\left(L_{2}+M_{2}+a \kappa_{0} L_{2} \mu\right) \int_{t_{0}}^{t} \alpha\left(V_{0}(s)\right) \mathrm{d} s+\alpha\left(\hat{I}_{1}\left(\omega_{n-1}\left(t_{1}\right)\right)\right)\right) \\
= & \Gamma \int_{t_{0}}^{t}\left(\alpha\left(B_{0}(s)\right), \alpha\left(V_{0}(s)\right)\right) \mathrm{d} s \\
= & \Gamma \int_{t_{0}}^{t} \phi(s) \mathrm{d} s .
\end{aligned}
$$

Again by the Bellman inequality, we know that $\phi(t) \equiv 0$ in $J_{2}^{\prime}$, from which we obtain that $\alpha\left(B_{0}\left(t_{2}\right)\right)=\alpha\left(V_{0}\left(t_{2}\right)\right)=0$ and $\alpha\left(I_{2}\left(B_{0}\left(t_{2}\right)\right)\right)=\alpha\left(\hat{I}_{2}\left(V_{0}\left(t_{2}\right)\right)\right)=0$.

Continuing such a process interval-by-interval up to $J_{m+1}^{\prime}$, we can prove that $\phi(t) \equiv 0$ in every $J_{k}^{\prime}, k=$ $1,2, \ldots, m+1$.

For any $J_{k}$, if for all $n \in \mathbb{N}$, we modify the value of $v_{n}$ and $\omega_{n}$ at $t=t_{k-1}$ via $v_{n}\left(t_{k-1}\right)=v_{n}\left(t_{k-1}^{+}\right)$and $\omega_{n}\left(t_{k-1}\right)=$ $\omega_{n}\left(t_{k-1}^{+}\right)$, respectively, then $\left\{v_{n}\right\} \subset C\left(J_{k}, E_{1}\right),\left\{\omega_{n}\right\} \subset C\left(J_{k}, E_{2}\right)$ and they are equicontinuous. Since $\alpha\left(\left\{v_{n}(t)\right\}\right) \equiv 0$ and $\alpha\left(\left\{\omega_{n}(t)\right\}\right) \equiv 0,\left\{v_{n}(t)\right\}$ and $\left\{\omega_{n}(t)\right\}$ are precompact in $E_{1}$ and $E_{2}$ for every $t \in J_{k}$, respectively. By the Arzela-Ascoli theorem, we know that $\left\{v_{n}\right\}$ and $\left\{\omega_{n}(t)\right\}$ are precompact in $C\left(J_{k}, E_{1}\right)$ and $C\left(J_{k}, E_{2}\right)$, respectively. Hence, $\left\{v_{n}\right\}$ and $\left\{\omega_{n}\right\}$ have convergent subsequences in $C\left(J_{k}, E_{1}\right)$ and $C\left(J_{k}, E_{2}\right)$, respectively. Combining this with the monotonicity (3.4), we easily prove that $\left\{v_{n}\right\}$ itself is convergent in $C\left(J_{k}, E_{1}\right)$ and $\left\{\omega_{n}\right\}$ itself is convergent in $C\left(J_{k}, E_{2}\right)$. In particular, $\left\{v_{n}(t)\right\}$ and $\left\{\omega_{n}(t)\right\}$ are uniformly convergent in $J_{k}^{\prime}$. Consequently, $\left\{v_{n}(t)\right\}$ and $\left\{\omega_{n}(t)\right\}$ are uniformly convergent over the whole of $J$.

Using an argument similar to that for $\left\{v_{n}(t)\right\}$ and $\left\{\omega_{n}(t)\right\}$, we can prove that $\left\{u_{n}(t)\right\}$ and $\left\{v_{n}(t)\right\}$ are also uniformly convergent in $J$. Hence, $\left\{v_{n}(t)\right\}$ and $\left\{u_{n}(t)\right\}$ are convergent in $P C^{1}\left(J, E_{1}\right)$, and $\left\{\omega_{n}(t)\right\}$ and $\left\{v_{n}(t)\right\}$ are convergent in $P C^{1}\left(J, E_{2}\right)$. Set

$$
\begin{array}{lll}
\underline{x}=\lim _{n \rightarrow \infty} v_{n}, & \bar{x}=\lim _{n \rightarrow \infty} u_{n} & \text { in } P C^{1}\left(J, E_{1}\right), \\
\underline{y}=\lim _{n \rightarrow \infty} \omega_{n}, & \bar{y}=\lim _{n \rightarrow \infty} v_{n} & \text { in } P C^{1}\left(J, E_{2}\right) . \tag{3.7}
\end{array}
$$

Letting $n \rightarrow \infty$ in (3.3) and (3.4), we see that $v_{0} \leq \underline{x} \leq \bar{x} \leq u_{0}, \omega_{0} \leq \underline{y} \leq \bar{y} \leq \nu_{0}$ and

$$
\underline{x}=P \underline{x}, \quad \underline{y}=Q \underline{y} \quad \text { and } \quad \bar{x}=P \bar{x}, \quad \bar{y}=Q \bar{y},
$$

i.e.,

$$
\begin{equation*}
(\underline{x}, \underline{y})=F(\underline{x}, \underline{y}), \quad(\bar{x}, \bar{y})=F(\bar{x}, \bar{y}) . \tag{3.8}
\end{equation*}
$$

By the monotonicity of $F$, it is easy to see that $(\underline{x}, \underline{y})$ and $(\bar{x}, \bar{y})$ are the minimal and maximal fixed points of $F$ in $\left[v_{0}, u_{0}\right] \times\left[\omega_{0}, v_{0}\right]$. That is, they are the minimal and maximal solutions of problem (1.1) between ( $v_{0}, \omega_{0}$ ) and ( $u_{0}, v_{0}$ ), respectively. This completes the proof.

Remark 3.1. The conditions for an impulsive argument are dropped in Theorem 3.1, i.e., we do not need the following restrictions:

$$
\alpha\left(I_{k}\left(x_{k}\right)\right) \leq M_{k} \alpha\left(x_{k}\right), \quad \alpha\left(\bar{I}_{k}\left(y_{k}\right)\right) \leq N_{k} \alpha\left(y_{k}\right), \quad k=1,2, \ldots, m .
$$

Further, the results do not rely on the Hausdorff measure of noncompactness, but use the Kuratowski measure of noncompactness. Therefore, Theorem 3.1 greatly improves the corresponding results in [39].

In Theorem 3.1, if $E_{1}$ and $E_{2}$ are weakly sequentially complete, the condition $\left(\mathrm{H}_{3}\right)$ holds automatically. In fact, by Theorem 2.2 of [42], any monotonic and order-bounded sequence is precompact. Let $\left\{x_{n}\right\}$ and $\left\{z_{n}\right\},\left\{y_{n}\right\}$ and $\left\{\xi_{n}\right\}$ be two increasing or decreasing sequences obeying condition $\left(\mathrm{H}_{3}\right)$, respectively, then by condition $\left(\mathrm{H}_{1}\right)$,
$\left\{f\left(t, x_{n}, y_{n}, z_{n}\right)+M_{1} x_{n}\right\}$ and $\left\{g\left(t, x_{n}, y_{n}, \xi_{n}\right)+M_{2} y_{n}\right\}$ are monotonic and order-bounded sequences. By the property of measure of noncompactness, we have

$$
\begin{aligned}
& \alpha\left(\left\{f\left(t, x_{n}, y_{n}, z_{n}\right)+M_{1} x_{n}\right\}\right) \leq \alpha\left(\left\{f\left(t, x_{n}, y_{n}, z_{n}\right)+M_{1} x_{n}\right\}\right)+M_{1} \alpha\left(\left\{x_{n}\right\}\right)=0 . \\
& \alpha\left(\left\{g\left(t, x_{n}, y_{n}, \xi_{n}\right)+M_{2} y_{n}\right\}\right) \leq \alpha\left(\left\{g\left(t, x_{n}, y_{n}, \xi_{n}\right)+M_{2} y_{n}\right\}\right)+M_{2} \alpha\left(\left\{y_{n}\right\}\right)=0 .
\end{aligned}
$$

Hence, condition $\left(\mathrm{H}_{3}\right)$ holds. From Theorem 3.1, we obtain the following result.
Corollary 3.1. Let $E_{1}$ and $E_{2}$ be ordered and weakly sequentially complete Banach spaces, whose positive cone $P_{1}$ and $P_{2}$ are normal, respectively, $f \in C\left(J \times E_{1} \times E_{2} \times E_{1}, E_{1}\right), g \in C\left(J \times E_{2} \times E_{1} \times E_{2}, E_{2}\right)$ and $I_{k} \in C\left(E_{1}, E_{1}\right)$, $\hat{I}_{k} \in C\left(E_{2}, E_{2}\right), k=1,2, \ldots, m$. If conditions $\left(\mathrm{H}_{1}\right)$ and $\left(\mathrm{H}_{2}\right)$ are satisfied, then problem (1.1) has minimal and maximal solutions between $\left(v_{0}, \omega_{0}\right)$ and ( $u_{0}, \nu_{0}$ ), which can be obtained by a monotone iterative procedure starting from $\left(v_{0}, \omega_{0}\right)$ and $\left(u_{0}, \nu_{0}\right)$, respectively.

Moreover, we shall discuss the uniqueness of the solution to problem (1.1) in $\left[v_{0}, u_{0}\right] \times\left[\omega_{0}, \nu_{0}\right]$. If we replace assumption $\left(\mathrm{H}_{3}\right)$ by the following assumption:
$\left(\mathrm{H}_{4}\right)$ There exist positive constants $C_{i}(i=1,2,3,4)$ such that

$$
\begin{aligned}
& f\left(t, x_{2}, y_{2}, z_{2}\right)-f\left(t, x_{1}, y_{1}, z_{1}\right) \leq C_{1}\left(x_{2}-x_{1}\right)+C_{2}\left(z_{2}-z_{1}\right), \\
& g\left(t, y_{2}, x_{2}, \xi_{2}\right)-g\left(t, y_{1}, x_{1}, \xi_{1}\right) \leq C_{3}\left(y_{2}-y_{1}\right)+C_{4}\left(\xi_{2}-\xi_{1}\right)
\end{aligned}
$$

for all $t \in J, v_{0}(t) \leq x_{1} \leq x_{2} \leq u_{0}(t), \omega_{0}(t) \leq y_{1} \leq y_{2} \leq \nu_{0}(t), \lambda S v_{0}(t) \leq z_{1} \leq z_{2} \leq \lambda S u_{0}(t)$, $\mu T \omega_{0}(t) \leq \xi_{1} \leq \xi_{2} \leq \mu T \nu_{0}(t)$, then we have the following unique existence result.

Theorem 3.2. Let $E_{i}$ be an ordered Banach space, whose positive cone $P_{i}$ is normal for $i=1,2, f \in C(J \times$ $\left.E_{1} \times E_{2} \times E_{1}, E_{1}\right), g \in C\left(J \times E_{2} \times E_{1} \times E_{2}, E_{2}\right)$ and $I_{k} \in C\left(E_{1}, E_{1}\right), \hat{I}_{k} \in C\left(E_{2}, E_{2}\right), k=1,2, \ldots, m$. If conditions $\left(\mathrm{H}_{1}\right),\left(\mathrm{H}_{2}\right)$ and $\left(\mathrm{H}_{4}\right)$ hold, then problem (1.1) has a unique solution between $\left(v_{0}, \omega_{0}\right)$ and $\left(u_{0}, v_{0}\right)$, which can be obtained by a monotone iterative procedure starting from $\left(v_{0}, \omega_{0}\right)$ or $\left(u_{0}, \nu_{0}\right)$.
Proof. We first prove that $\left(\mathrm{H}_{1}\right)$ and $\left(\mathrm{H}_{4}\right)$ imply $\left(\mathrm{H}_{3}\right)$. In fact, for $t \in J$, let $\left\{x_{n}\right\} \subset\left[v_{0}, u_{0}\right],\left\{y_{n}\right\} \subset\left[\omega_{0}, \nu_{0}\right]$, $\left\{z_{n}\right\} \subset\left[\lambda S v_{0}(t), \lambda S u_{0}(t)\right]$ and $\left\{\xi_{n}\right\} \subset\left[\mu T \omega_{0}(t), \mu T \nu_{0}(t)\right]$ be increasing sequences. For $m, n \in \mathbb{N}$ with $m>n$, by $\left(\mathrm{H}_{1}\right)$ and $\left(\mathrm{H}_{4}\right)$,

$$
\begin{aligned}
\theta & \leq\left(f\left(t, x_{m}, y_{m}, z_{m}\right)-f\left(t, x_{n}, y_{n}, z_{n}\right)\right)+M_{1}\left(x_{m}-x_{n}\right) \\
& \leq\left(C_{1}+M_{1}\right)\left(x_{m}-x_{n}\right)+C_{2}\left(z_{m}-z_{n}\right) . \\
\theta & \leq\left(g\left(t, y_{m}, x_{m}, \xi_{m}\right)-g\left(t, y_{n}, x_{n}, \xi_{n}\right)\right)+M_{2}\left(y_{m}-y_{n}\right) \\
& \leq\left(C_{3}+M_{1}\right)\left(y_{m}-y_{n}\right)+C_{4}\left(\xi_{m}-\xi_{n}\right) .
\end{aligned}
$$

By these and the normality of cone $P_{i}(i=1,2)$, we have

$$
\begin{aligned}
& \left\|f\left(t, x_{m}, y_{m}, z_{m}\right)-f\left(t, x_{n}, y_{n}, z_{n}\right)\right\| \\
& \quad \leq N_{1}\left\|\left(C_{1}+M_{1}\right)\left(x_{m}-x_{n}\right)+C_{2}\left(z_{m}-z_{n}\right)\right\|+M_{1}\left\|x_{m}-x_{n}\right\| \\
& \quad \leq\left(M_{1}+M_{1} N_{1}+N_{1} C_{1}\right)\left\|x_{m}-x_{n}\right\|+N_{1} C_{2}\left\|z_{m}-z_{n}\right\|
\end{aligned}
$$

and

$$
\begin{aligned}
& \left\|g\left(t, y_{m}, x_{m}, \xi_{m}\right)-g\left(t, y_{n}, x_{n}, \xi_{n}\right)\right\| \\
& \quad \leq N_{2}\left\|\left(C_{3}+M_{2}\right)\left(y_{m}-y_{n}\right)+C_{4}\left(\xi_{m}-\xi_{n}\right)\right\|+M_{2}\left\|y_{m}-y_{n}\right\| \\
& \quad \leq\left(M_{2}+M_{2} N_{2}+N_{2} C_{3}\right)\left\|y_{m}-y_{n}\right\|+N_{2} C_{4}\left\|\xi_{m}-\xi_{n}\right\| .
\end{aligned}
$$

From these inequalities and the definition of the measure of noncompactness, it follows that

$$
\begin{aligned}
\alpha\left(\left\{f\left(t, x_{n}, y_{n}, z_{n}\right)\right\}\right) & \leq\left(M_{1}+M_{1} N_{1}+N_{1} C_{1}\right) \alpha\left(\left\{x_{n}\right\}\right)+N_{1} C_{2} \alpha\left(\left\{z_{n}\right\}\right) \\
& \leq L_{3}\left(\alpha\left(\left\{x_{n}\right\}\right)+\alpha\left(\left\{z_{n}\right\}\right)\right), \\
\alpha\left(\left\{g\left(t, y_{n}, x_{n}, \xi_{n}\right)\right\}\right) & \leq\left(M_{2}+M_{2} N_{2}+N_{2} C_{3}\right) \alpha\left(\left\{y_{n}\right\}\right)+N_{2} C_{4} \alpha\left(\left\{\xi_{n}\right\}\right) \\
& \leq L_{4}\left(\alpha\left(\left\{y_{n}\right\}\right)+\alpha\left(\left\{\xi_{n}\right\}\right)\right),
\end{aligned}
$$

where $L_{3}=\max \left\{M_{1}+M_{1} N_{1}+N_{1} C_{1}, N_{1} C_{2}\right\}$ and $L_{4}=\max \left\{M_{2}+M_{2} N_{2}+N_{2} C_{3}, N_{2} C_{4}\right\}$. If $\left\{x_{n}\right\},\left\{y_{n}\right\},\left\{z_{n}\right\}$ and $\left\{\xi_{n}\right\}$ are two decreasing sequences, the above inequalities are also valid. Hence $\left(\mathrm{H}_{3}\right)$ holds.

Therefore, by Theorem 3.1, problem (1.1) has minimal solution ( $\underline{x}, \underline{y}$ ) and maximal solution $(\bar{x}, \bar{y})$ in $\left[v_{0}, u_{0}\right] \times$ [ $\omega_{0}, \nu_{0}$ ]. By the proof of Theorem 3.1, (3.3), (3.4), (3.6) and (3.7) are valid. Going from $J_{1}^{\prime}$ to $J_{m+1}^{\prime}$ interval-byinterval, we show that $(\underline{x}, \underline{y}) \equiv(\bar{x}, \bar{y})$ in every $J_{k}^{\prime}, k=1,2, \ldots, m+1$.

Indeed, for $t \in J_{1}^{\prime}$, by (3.6), (3.7) and (3.2) and assumption ( $\mathrm{H}_{4}$ ), we have

$$
\begin{align*}
\theta \leq \bar{x}(t)-\underline{x}(t) & =P \bar{x}(t)-P \underline{x}(t) \\
& =\int_{t_{0}}^{t} \mathrm{e}^{M_{1}(t-s)}\left(f(s, \bar{x}(s), \bar{y}(s), \lambda S \bar{x}(s))-f(s, \underline{x}(s), \underline{y}(s), \lambda S \underline{x}(s))+M_{1}(\bar{x}(s)-\underline{x}(s))\right) \mathrm{d} s \\
& \leq \int_{t_{0}}^{t} \mathrm{e}^{M_{1}(t-s)}\left(\left(M_{1}+C_{1}\right)(\bar{x}(s)-\underline{x}(s))+\lambda C_{2}(S \bar{x}(s)-S \underline{x}(s))\right) \mathrm{d} s \\
& \leq \int_{t_{0}}^{t}\left(\left(M_{1}+C_{1}\right)(\bar{x}(s)-\underline{x}(s))+\lambda C_{2}(S \bar{x}(s)-S \underline{x}(s))\right) \mathrm{d} s \\
& \leq\left(M_{1}+C_{1}\right) \int_{t_{0}}^{t}(\bar{x}(s)-\underline{x}(s)) \mathrm{d} s+\lambda C_{2} h_{0} \int_{t_{0}}^{t} \int_{t_{0}}^{s}(\bar{x}(t)-\underline{x}(t)) \mathrm{d} t \mathrm{~d} s \\
& \leq\left(M_{1}+C_{1}+a \lambda C_{2} h_{0}\right) \int_{t_{0}}^{t}(\bar{x}(s)-\underline{x}(s)) \mathrm{d} s \tag{3.9}
\end{align*}
$$

and

$$
\begin{align*}
\theta & \leq \bar{y}(t)-\underline{y}(t) \\
& \leq\left(M_{2}+C_{3}+a \lambda C_{4} \kappa_{0}\right) \int_{t_{0}}^{t}(\bar{y}(s)-\underline{y}(s)) \mathrm{d} s . \tag{3.10}
\end{align*}
$$

It follows from (3.9) and (3.10) and the normality of cone $P_{i}(i=1,2)$ that

$$
\begin{aligned}
& \|\bar{x}(t)-\underline{x}(t)\| \leq N_{1}\left(M_{1}+C_{1}+a \lambda C_{2} h_{0}\right) \int_{t_{0}}^{t}\|\bar{x}(s)-\underline{x}(s)\| \mathrm{d} s, \\
& \|\bar{y}(t)-\underline{y}(t)\| \leq N_{2}\left(M_{2}+C_{3}+a \lambda C_{4} \kappa_{0}\right) \int_{t_{0}}^{t}\|\bar{y}(s)-\underline{y}(s)\| \mathrm{d} s .
\end{aligned}
$$

By the Bellman inequality, these imply that $(\underline{x}(t), \underline{y}(t)) \equiv(\bar{x}(t), \bar{y}(t))$ in $J_{1}^{\prime}$.
For $t \in J_{2}^{\prime}$, since $I_{1}\left(\bar{x}\left(t_{1}\right)\right)=I_{1}\left(\underline{x}\left(t_{1}\right)\right)$ and $\hat{I}_{1}\left(\bar{y}\left(t_{1}\right)\right)=\hat{I}_{1}\left(\underline{y}\left(t_{1}\right)\right)$, using (3.2) and completely the same argument as above for $t \in J_{1}^{\prime}$, we can prove that

$$
\begin{aligned}
\|\bar{x}(t)-\underline{x}(t)\| & \leq N_{1}\left(M_{1}+C_{1}+a \lambda C_{2} h_{0}\right) \int_{t_{0}}^{t}\|\bar{x}(s)-\underline{x}(s)\| \mathrm{d} s \\
& =N_{1}\left(M_{1}+C_{1}+a \lambda C_{2} h_{0}\right) \int_{t_{1}}^{t}\|\bar{x}(s)-\underline{x}(s)\| \mathrm{d} s \\
\|\bar{y}(t)-\underline{y}(t)\| & \leq N_{2}\left(M_{2}+C_{3}+a \lambda C_{4} \kappa_{0}\right) \int_{t_{0}}^{t}\|\bar{y}(s)-\underline{y}(s)\| \mathrm{d} s \\
& =N_{2}\left(M_{2}+C_{3}+a \lambda C_{4} \kappa_{0}\right) \int_{t_{1}}^{t}\|\bar{y}(s)-\underline{y}(s)\| \mathrm{d} s
\end{aligned}
$$

Again, by the Bellman inequality, we obtain that $(\underline{x}(t), \underline{y}(t)) \equiv(\bar{x}(t), \bar{y}(t))$ in $J_{2}^{\prime}$.
Continuing such a process interval-by-interval up to $J_{m+1}^{\prime}$, we see that $(\underline{x}(t), \underline{y}(t)) \equiv(\bar{x}(t), \bar{y}(t))$ over the whole of $J$. Hence, $\left(x^{*}, y^{*}\right):=(\underline{x}(t), \underline{y}(t))=(\bar{x}(t), \bar{y}(t))$ is the unique solution of problem (1.1) in $\left[v_{0}, u_{0}\right] \times\left[\omega_{0}, v_{0}\right]$, which can be obtained by the monotone iterative procedure (3.3) starting from ( $v_{0}, \omega_{0}$ ) or ( $\omega_{0}, \nu_{0}$ ). This completes the proof.

Remark 3.2. Using the same approach as in Theorems 3.1 and 3.2, we can consider initial value problems (1.2) and (1.3) and obtain analogous conclusions, respectively.

Remark 3.3. Using the above argument method interval-by-interval from $J_{1}^{\prime}$ to $J_{m+1}^{\prime}$, we can also improve the main results in [29] and [34], and delete some restrictive conditions there.

## 4. An example

Example 1. Consider the following system of nonlinear mixed type implicit impulsive integro-differential equations in Banach spaces $E_{1}$ and $E_{2}$ : Find $(x, y): J \times J \rightarrow E_{1} \times E_{2}$ such that

$$
\left\{\begin{array}{l}
x_{n}^{\prime}(t)=\frac{1}{20}\left\{\frac{\mathrm{e}^{-6 t}}{3 n}\left[x_{n+1}^{4}+\left(t-y_{n}\right)^{3}\right]+\lambda \int_{0}^{t} \mathrm{e}^{-(6 t+s)} x_{n}(s) \mathrm{d} s\right\}, \quad \forall 0 \leq t \leq 1, t \neq \frac{1}{2}  \tag{4.1}\\
y_{n}^{\prime}(t)=\frac{1}{9 n}\left[y_{n+1}^{4}+\left(t-x_{n}\right)^{3}\right]+\frac{\mu}{2 n}\left[\int_{0}^{1} \mathrm{e}^{t s} y_{n+2}(s) \mathrm{d} s\right]^{3}, \quad \forall 0 \leq t \leq 1, t \neq \frac{1}{2} \\
\left.\Delta x_{n}\right|_{t=1 / 2}=-\frac{2}{5} x_{n}\left(\frac{1}{2}\right), \\
\left.\Delta y_{n}\right|_{t=1 / 2}=4 y_{n}\left(\frac{1}{2}\right), \\
x_{n}(0)=y_{n}(0)=0 \quad(n=1,2, \ldots,)
\end{array}\right.
$$

Evidently, $\left(x_{n}(t), y_{n}(t)\right) \equiv(0,0)(n=1,2, \ldots)$ is a trivial solution of problem (4.1).
Theorem 4.1. Problem (4.1) admits minimal and maximal solutions $(v(t), \omega(t))$ and $(u(t), \nu(t))$ which are continuously differentiable on $J \times J$ and satisfy

$$
\begin{aligned}
& 0 \leq v(t), u(t) \leq\left\{\begin{array}{ll}
\frac{t}{n}, & \forall 0 \leq t \leq \frac{1}{2} \\
\frac{t}{n}-\frac{1}{5 n}, & \forall \frac{1}{2}<t \leq 1,
\end{array}(n=1,2, \ldots),\right. \\
& 0 \leq \omega(t), \nu(t) \leq\left\{\begin{array}{ll}
\frac{t}{n}, & \forall 0 \leq t \leq \frac{1}{2} \\
\frac{t}{n}+\frac{1}{8 n}, & \forall \frac{1}{2}<t \leq 1,
\end{array}(n=1,2, \ldots),\right.
\end{aligned}
$$

where $J=\left[0, \frac{1}{2}\right] \cup\left(\frac{1}{2}, 1\right]$.
Proof. Let $t_{0}=0, a=1, E_{1}=E_{2}=C_{0}=\left\{x=\left(x_{1}, x_{2}, \ldots, x_{n}, \ldots\right): x_{n} \rightarrow 0\right\}$ with norm $\|x\|=\sup _{n}\left|x_{n}\right|$ and $P_{1}=P_{2}=\left\{x=\left(x_{1}, x_{2}, \ldots, x_{n}, \ldots\right) \in C_{0}: x_{n} \geq 0, n=1,2, \ldots\right\}$. Then $P_{1}$ and $P_{2}$ are normal cones in $E_{1}$ and $E_{2}$, respectively, and problem (4.1) can be regarded to be of the form (1.1) in $E_{1} \times E_{2}$. In this situation, $x_{0}=y_{0}=(0,0, \ldots, 0, \ldots)=\theta, J=[0,1], h(t, s)=\mathrm{e}^{-(6 t+s)}, \kappa(t, s)=\mathrm{e}^{t s}, x=\left(x_{1}, x_{2}, \ldots, x_{n}, \ldots\right)$, $y=\left(y_{1}, y_{2}, \ldots, y_{n}, \ldots\right), z=\left(z_{1}, z_{2}, \ldots, z_{n}, \ldots\right), f=\left(f_{1}, f_{2}, \ldots, f_{n}, \ldots\right)$ and $g=\left(g_{1}, g_{2}, \ldots, g_{n}, \ldots\right)$ in which

$$
\begin{aligned}
& f_{n}(t, x, y, z)=\frac{1}{20}\left\{\frac{\mathrm{e}^{-6 t}}{3 n}\left[\left(t-y_{n}\right)^{3}+x_{n+1}^{4}\right]+\lambda z_{n}\right\}, \\
& g_{n}(t, x, y, z)=\frac{1}{9 n}\left[\left(t-x_{n}\right)^{3}+y_{n+1}^{4}\right]+\frac{\mu}{2 n} z_{n}^{3}
\end{aligned}
$$

$m=1, t_{1}=\frac{1}{2}$ and

$$
\begin{aligned}
& I_{1}(x)=-\frac{2}{5} x, \quad \forall x \in E_{1}=C_{0} \\
& \hat{I}_{1}(y)=4 y, \quad \forall y \in E_{2}=C_{0}
\end{aligned}
$$

Obviously, $f \in C\left[J \times E_{1} \times E_{2} \times E_{1}, E_{1}\right], g \in C\left[J \times E_{2} \times E_{1} \times E_{2}, E_{2}\right], I_{1} \in C\left[E_{1}, E_{1}\right]$ and $\hat{I}_{1} \in C\left[E_{2}\right.$, E 2$]$. Let

$$
\begin{aligned}
& v_{0}(t)=\omega_{0}(t)=(0,0, \ldots, 0, \ldots), \quad \forall 0 \leq t \leq 1 \\
& u_{0}(t)= \begin{cases}\left(t, \frac{t}{2} \ldots, \frac{t}{n}, \ldots\right), & \forall 0 \leq t \leq \frac{1}{2} \\
\left(t-\frac{1}{5}, t-\frac{1}{10}, \ldots, \frac{t}{n}-\frac{1}{5 n}, \ldots\right), & \forall \frac{1}{2}<t \leq 1\end{cases} \\
& v_{0}(t)= \begin{cases}\left(t, \frac{t}{2}, \ldots, \frac{t}{n}, \ldots\right), & \forall 0 \leq t \leq \frac{1}{2} \\
\left(t+\frac{1}{8}, t+\frac{1}{16}, \ldots, \frac{t}{n}+\frac{1}{8 n}, \ldots\right), & \forall \frac{1}{2}<t \leq 1\end{cases}
\end{aligned}
$$

It is not difficult to verify that conditions $\left(\mathrm{H}_{1}\right)-\left(\mathrm{H}_{3}\right)$ hold. Hence, our conclusion follows from Theorem 3.1.

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