# An optimal lower bound for the Frobenius problem 

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#### Abstract

Given $N \geqslant 2$ positive integers $a_{1}, a_{2}, \ldots, a_{N}$ with $\operatorname{GCD}\left(a_{1}, \ldots, a_{N}\right)=1$, let $f_{N}$ denote the largest natural number which is not a positive integer combination of $a_{1}, \ldots, a_{N}$. This paper gives an optimal lower bound for $f_{N}$ in terms of the absolute inhomogeneous minimum of the standard ( $N-1$ )-simplex. © 2006 Elsevier Inc. All rights reserved.


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## 1. Introduction and statement of results

Given $N \geqslant 2$ positive integers $a_{1}, a_{2}, \ldots, a_{N}$ with $\operatorname{GCD}\left(a_{1}, \ldots, a_{N}\right)=1$, the Frobenius problem asks for the largest natural number $g_{N}=g_{N}\left(a_{1}, \ldots, a_{N}\right)$ (called the Frobenius number) such that $g_{N}$ has no representation as a non-negative integer combination of $a_{1}, \ldots, a_{N}$. In this paper, without loss of generality, we assume that $a_{1}<a_{2}<\cdots<a_{N}$. The simple statement of the Frobenius problem makes it attractive and the relevant bibliography is very large (see [14] and [11, Problem C7]). We will mention just few main results.

For $N=2$, the Frobenius number is given by an explicit formula due to W.J. Curran Sharp [3]:

$$
g_{2}\left(a_{1}, a_{2}\right)=\left(a_{1}-1\right)\left(a_{2}-1\right)-1 .
$$

[^0]The case $N=3$ was solved explicitly by Selmer and Beyer [20], using a continued fraction algorithm. Their result was simplified by Rödseth [15] and later by Greenberg [8]. No general formulas are known for $N \geqslant 4$. Upper bounds, among many others, include classical results by Erdős and Graham [5]

$$
g_{N} \leqslant 2 a_{N}\left[\frac{a_{1}}{N}\right]-a_{1}
$$

by Selmer [19]

$$
g_{N} \leqslant 2 a_{N-1}\left[\frac{a_{N}}{N}\right]-a_{N}
$$

and by Vitek [21]

$$
g_{N} \leqslant\left[\frac{\left(a_{2}-1\right)\left(a_{N}-2\right)}{2}\right]-1
$$

as well as more recent results by Beck, Diaz and Robins [2]

$$
g_{N} \leqslant \frac{1}{2}\left(\sqrt{a_{1} a_{2} a_{3}\left(a_{1}+a_{2}+a_{3}\right)}-a_{1}-a_{2}-a_{3}\right)
$$

and by Fukshansky and Robins [7], who produced an upper bound in terms of the covering radius of a lattice related to the integers $a_{1}, \ldots, a_{N}$.

For $N=3$, Davison [4] has found a sharp lower bound

$$
g_{3} \geqslant \sqrt{3 a_{1} a_{2} a_{3}}-a_{1}-a_{2}-a_{3},
$$

where the constant $\sqrt{3}$ cannot be replaced by any smaller constant. Rödseth [15] proved in the general case that

$$
g_{N} \geqslant\left((N-1)!a_{1} \cdots a_{N}\right)^{1 /(N-1)}-\sum_{i=1}^{N} a_{i}
$$

The present paper gives a sharp lower bound for the function

$$
f_{N}\left(a_{1}, \ldots, a_{N}\right)=g_{N}\left(a_{1}, \ldots, a_{N}\right)+\sum_{i=1}^{N} a_{i}
$$

(and thus for $g_{N}$ ) in terms of geometric characteristics of the standard ( $N-1$ )-simplex. Clearly, $f_{N}=f_{N}\left(a_{1}, \ldots, a_{N}\right)$ is the largest integer which is not a positive integer combination of $a_{1}, \ldots, a_{N}$.

Following the geometric approach developed in [12,13], we will make use of tools from the geometry of numbers. Recall that a family of sets in $\mathbb{R}^{N-1}$ is a covering if their union equals $\mathbb{R}^{N-1}$. Given a set $S$ and a lattice $L$, we say that $L$ is a covering lattice for $S$ if the family
$\{S+\boldsymbol{l}: \boldsymbol{l} \in L\}$ is a covering. Recall also that the inhomogeneous minimum of the set $S$ with respect to the lattice $L$ is the quantity

$$
\mu(S, L)=\inf \{\sigma>0: L \text { is a covering lattice of } \sigma S\}
$$

and the quantity

$$
\mu_{0}(S)=\inf \{\mu(S, L): \operatorname{det} L=1\}
$$

is called the absolute inhomogeneous minimum of $S$. If $S$ is bounded and has inner points, then $\mu_{0}(S)$ does not vanish and is finite (see [10, Chapter 3]).

Let $S_{N-1}$ be the standard simplex given by

$$
S_{N-1}=\left\{\left(x_{1}, \ldots, x_{N-1}\right): x_{i} \geqslant 0 \text { reals and } \sum_{i=1}^{N-1} x_{i} \leqslant 1\right\} .
$$

The main result of the paper shows that the constant $\mu_{0}\left(S_{N-1}\right)$ is a sharp lower bound for (suitably normalized) Frobenius number and integers with relatively small $f_{N}$ are, roughly speaking, dense in $\mathbb{R}^{N-1}$.

## Theorem 1.1.

(i) For $N \geqslant 3$ the inequality

$$
\begin{equation*}
\mu_{0}\left(S_{N-1}\right) \leqslant \frac{f_{N}\left(a_{1}, \ldots, a_{N}\right)}{\left(a_{1} \cdots a_{N}\right)^{1 /(N-1)}} \tag{1}
\end{equation*}
$$

holds.
(ii) For any $\epsilon>0$ and for any point $\boldsymbol{\alpha}=\left(\alpha_{1}, \ldots, \alpha_{N-1}\right)$ in $\mathbb{R}^{N-1}$ there exist $N$ integers $0<$ $a_{1}<a_{2}<\cdots<a_{N}$ with $\operatorname{GCD}\left(a_{1}, \ldots, a_{N}\right)=1$ such that

$$
\begin{gather*}
\left|\alpha_{i}-\frac{a_{i}}{a_{N}}\right|<\epsilon, \quad i=1,2, \ldots, N-1, \quad \text { and }  \tag{2}\\
\frac{f_{N}\left(a_{1}, \ldots, a_{N}\right)}{\left(a_{1} \cdots a_{N}\right)^{1 /(N-1)}}<\mu_{0}\left(S_{N-1}\right)+\epsilon . \tag{3}
\end{gather*}
$$

Remark 1.1. Prof. J.L. Davison kindly informed the authors that the part (i) of Theorem 1.1 was proved by Rödseth in [16] without using geometry of numbers.

The quantity $\mu_{0}(S)$ is closely related to the covering constant $\Gamma(S)$ of the set $S$, where

$$
\begin{equation*}
\Gamma(S)=\sup \{\operatorname{det}(L): L \text { a covering lattice of } S\} . \tag{4}
\end{equation*}
$$

By [10, Theorem 1, Chapter 3, Section 21] (see also [1]) for each Lebesgue measurable set $S$

$$
\begin{equation*}
\Gamma(S) \leqslant \operatorname{vol}(S) \tag{5}
\end{equation*}
$$

and by Theorem 2 ibid.

$$
\begin{equation*}
\mu_{0}(S)=\frac{1}{\Gamma(S)^{1 /(N-1)}} \tag{6}
\end{equation*}
$$

The proof of Theorem 1 of [10, Chapter 3, Section 21] easily implies that the equality in (5) is attained only if $S$ is a space-filler. Further, by [17, Theorem 6.3], packings of simplices cannot be very dense and, consequently, $S_{N-1}$ is not a space-filler. Therefore, by (5) and (6),

$$
\begin{equation*}
\mu_{0}\left(S_{N-1}\right)>\frac{1}{\left(\operatorname{vol}\left(S_{N-1}\right)\right)^{1 /(N-1)}}=((N-1)!)^{1 /(N-1)} \tag{7}
\end{equation*}
$$

and we get the following result.
Corollary 1.1. For $N \geqslant 3$ the inequality

$$
\begin{equation*}
f_{N}\left(a_{1}, \ldots, a_{N}\right)>\left((N-1)!a_{1} \cdots a_{N}\right)^{1 /(N-1)} \tag{8}
\end{equation*}
$$

holds.
Inequality (8) with nonstrict sign was proved in [16]. The only known value of $\mu_{0}\left(S_{N-1}\right)$ is $\mu_{0}\left(S_{2}\right)=\sqrt{3}$ (see, e.g., [6]). In the latter case we get the following slight generalization of Theorems 2.2 and 2.3 of [4].

Corollary 1.2. For $N=3$ the inequality

$$
f_{3}\left(a_{1}, a_{2}, a_{3}\right) \geqslant\left(3 a_{1} a_{2} a_{3}\right)^{1 / 2}
$$

holds. Moreover, for any $\epsilon>0$ and for any point $\boldsymbol{\alpha}=\left(\alpha_{1}, \alpha_{2}\right)$ in $\mathbb{R}^{2}$ there exist integers $0<a_{1}<$ $a_{2}<a_{3}$ with $\operatorname{GCD}\left(a_{1}, a_{2}, a_{3}\right)=1$ such that

$$
\begin{gathered}
\left|\alpha_{i}-\frac{a_{i}}{a_{3}}\right|<\epsilon, \quad i=1,2, \quad \text { and } \\
f_{3}\left(a_{1}, a_{2}, a_{3}\right)<\left((3+\epsilon) a_{1} a_{2} a_{3}\right)^{1 / 2}
\end{gathered}
$$

Let us consider a lattice $M$ in $\mathbb{R}^{N-1}$ generated by the vectors

$$
\begin{equation*}
\frac{1}{N-1} \boldsymbol{e}_{1}, \ldots, \frac{1}{N-1} \boldsymbol{e}_{N-1} \tag{9}
\end{equation*}
$$

where $\boldsymbol{e}_{j}$ are the standard basis vectors. Since the fundamental cell of $M$ w.r.t. the basis (9) belongs to $S_{N-1}$, the lattice $M$ is a covering lattice for the simplex $S_{N-1}$. Therefore, by (4) and (6),

$$
\mu_{0}\left(S_{N-1}\right) \leqslant \frac{1}{(\operatorname{det} M)^{1 /(N-1)}}=N-1 .
$$

This implies the following result.

Corollary 1.3. For any $\epsilon>0$ and for any point $\boldsymbol{\alpha}=\left(\alpha_{1}, \ldots, \alpha_{N-1}\right)$ in $\mathbb{R}^{N-1}$ there exist $N$ integers $0<a_{1}<a_{2}<\cdots<a_{N}$ with $\operatorname{GCD}\left(a_{1}, \ldots, a_{N}\right)=1$ such that

$$
\begin{gathered}
\left|\alpha_{i}-\frac{a_{i}}{a_{N}}\right|<\epsilon, \quad i=1,2, \ldots, N-1, \quad \text { and } \\
\frac{f_{N}\left(a_{1}, \ldots, a_{N}\right)}{\left(a_{1} \cdots a_{N}\right)^{1 /(N-1)}}<N-1+\epsilon
\end{gathered}
$$

Remark 1.2. Note that inequality (7) and Stirling's formula imply that

$$
\liminf _{N \rightarrow \infty} \frac{\mu_{0}\left(S_{N-1}\right)}{N-1} \geqslant e^{-1}
$$

Thus, we know the asymptotic behavior of the optimal constant $\mu_{0}\left(S_{N-1}\right)$ up to the multiple $e$.
For $\boldsymbol{a}=\left(a_{1}, a_{2}, \ldots, a_{N}\right)$, define a lattice $L_{\boldsymbol{a}}$ by

$$
L_{\boldsymbol{a}}=\left\{\left(x_{1}, \ldots, x_{N-1}\right): x_{i} \text { integers and } \sum_{i=1}^{N-1} a_{i} x_{i} \equiv 0 \bmod a_{N}\right\} .
$$

The main tool for the proof of the part (ii) of Theorem 1.1 is the following result implicit in [18].
Theorem 1.2. For any lattice $L$ with basis $\boldsymbol{b}_{1}, \ldots, \boldsymbol{b}_{N-1}, \boldsymbol{b}_{i} \in \mathbb{Q}^{N-1}, i=1, \ldots, N-1$, and for all rationals $\alpha_{1}, \ldots, \alpha_{N-1}$ with $0<\alpha_{1} \leqslant \alpha_{2} \leqslant \cdots \leqslant \alpha_{N-1} \leqslant 1$, there exists an infinite arithmetic progression $\mathcal{P}$ and a sequence

$$
\boldsymbol{a}(t)=\left(a_{1}(t), \ldots, a_{N-1}(t), a_{N}(t)\right) \in \mathbb{Z}^{N}, \quad t \in \mathcal{P}
$$

such that $\operatorname{GCD}\left(a_{1}(t), \ldots, a_{N-1}(t), a_{N}(t)\right)=1$ and the lattice $L_{a(t)}$ has a basis

$$
\begin{gather*}
\boldsymbol{b}_{1}(t), \ldots, \boldsymbol{b}_{N-1}(t) \quad \text { with } \\
\frac{b_{i j}(t)}{d t}=b_{i j}+O\left(\frac{1}{t}\right), \quad i, j=1, \ldots, N-1, \tag{10}
\end{gather*}
$$

where $d \in \mathbb{N}$ is such that $d b_{i j}, d \alpha_{j} b_{i j} \in \mathbb{Z}$ for all $i, j=1, \ldots, N-1$. Moreover,

$$
\begin{gather*}
a_{N}(t)=\operatorname{det}(L) d^{N-1} t^{N-1}+O\left(t^{N-2}\right) \quad \text { and }  \tag{11}\\
\alpha_{i}(t):=\frac{a_{i}(t)}{a_{N}(t)}=\alpha_{i}+O\left(\frac{1}{t}\right) \tag{12}
\end{gather*}
$$

For completeness, we give a proof of Theorem 1.2 in Section 4.

## 2. Proof of Theorem 1.1(i)

Recall that $\boldsymbol{a}=\left(a_{1}, a_{2}, \ldots, a_{N}\right)$ and put

$$
\alpha_{1}=\frac{a_{1}}{a_{N}}, \quad \ldots, \quad \alpha_{N-1}=\frac{a_{N-1}}{a_{N}}
$$

Define a simplex $S_{a}$ by

$$
S_{\boldsymbol{a}}=\left\{\left(x_{1}, \ldots, x_{N-1}\right): x_{i} \geqslant 0 \text { reals and } \sum_{i=1}^{N-1} a_{i} x_{i} \leqslant 1\right\} .
$$

Theorem 2.5 of [12] states that

$$
\begin{equation*}
f_{N}\left(a_{1}, \ldots, a_{N}\right)=\mu\left(S_{\boldsymbol{a}}, L_{\boldsymbol{a}}\right) \tag{13}
\end{equation*}
$$

Observe that the inhomogeneous minimum $\mu(S, L)$ satisfies

$$
\mu(S, t L)=t \mu(S, L), \quad \mu(t S, L)=t^{-1} \mu(S, L)
$$

Thus, if we define

$$
\begin{aligned}
& S_{\boldsymbol{\alpha}}=a_{N} S_{\boldsymbol{a}}=\left\{\left(x_{1}, \ldots, x_{N-1}\right): x_{i} \geqslant 0 \text { reals and } \sum_{i=1}^{N-1} \alpha_{i} x_{i} \leqslant 1\right\}, \\
& L_{u}=a_{N}^{-1 /(N-1)} L_{\boldsymbol{a}}
\end{aligned}
$$

then

$$
\begin{equation*}
\mu\left(S_{\boldsymbol{a}}, L_{\boldsymbol{a}}\right)=a_{N}^{1+1 /(N-1)} \mu\left(S_{\boldsymbol{\alpha}}, L_{u}\right) \tag{14}
\end{equation*}
$$

Note that det $L_{\boldsymbol{a}}=a_{N}$. Thus the lattice $L_{u}$ has determinant 1 and we have

$$
\begin{equation*}
\mu_{0}\left(S_{\alpha}\right) \leqslant \mu\left(S_{\alpha}, L_{u}\right) \tag{15}
\end{equation*}
$$

The simplices $\left(\alpha_{1} \cdots \alpha_{N-1}\right)^{1 /(N-1)} S_{\alpha}$ and $S_{N-1}$ are equivalent up to a linear transformation of determinant 1. Therefore

$$
\begin{equation*}
\mu_{0}\left(S_{N-1}\right)=\frac{\mu_{0}\left(S_{\alpha}\right)}{\left(\alpha_{1} \cdots \alpha_{N-1}\right)^{1 /(N-1)}}, \tag{16}
\end{equation*}
$$

and by (15), (14) and (13) we have

$$
\mu_{0}\left(S_{N-1}\right) \leqslant \frac{\mu\left(S_{\alpha}, L_{u}\right)}{\left(\alpha_{1} \cdots \alpha_{N-1}\right)^{1 /(N-1)}}=\frac{\mu\left(S_{\boldsymbol{a}}, L_{\boldsymbol{a}}\right)}{a_{N}^{1+1 /(N-1)}\left(\alpha_{1} \cdots \alpha_{N-1}\right)^{1 /(N-1)}}=\frac{f_{N}\left(a_{1}, \ldots, a_{N}\right)}{\left(a_{1} \cdots a_{N}\right)^{1 /(N-1)}}
$$

## 3. Proof of Theorem 1.1(ii)

The proof is based on Theorem 1.2 and the following continuity property of the inhomogeneous minima. We say that a sequence $S_{t}$ of star bodies in $\mathbb{R}^{N-1}$ converges to a star body $S$ if the sequence of distance functions of $S_{t}$ converges uniformly on the unit ball in $\mathbb{R}^{N-1}$ to the distance function of $S$. For the notion of convergence of a sequence of lattices to a given lattice we refer the reader to [10, Definition 4, p. 178].

Lemma 3.1. Let $S_{t}$ be a sequence of star bodies in $\mathbb{R}^{N-1}$ which converges to a bounded star body $S$ and let $L_{t}$ be a sequence of lattices in $\mathbb{R}^{N-1}$ convergent to a lattice $L$. Then

$$
\lim _{t \rightarrow \infty} \mu\left(S_{t}, L_{t}\right)=\mu(S, L)
$$

Proof. The result follows from a much more general result of [9, Satz 1].
W.l.o.g., we may assume that $\boldsymbol{\alpha} \in \mathbb{Q}^{N-1}$ and

$$
\begin{equation*}
0<\alpha_{1}<\alpha_{2}<\cdots<\alpha_{N-1}<1 \tag{17}
\end{equation*}
$$

For $\epsilon>0$ we can choose a lattice $L_{\epsilon}$ of determinant 1 with

$$
\begin{equation*}
\mu\left(S_{\alpha}, L_{\epsilon}\right)<\mu_{0}\left(S_{\alpha}\right)+\frac{\epsilon\left(\alpha_{1} \cdots \alpha_{N-1}\right)^{1 /(N-1)}}{2} \tag{18}
\end{equation*}
$$

The inhomogeneous minimum is independent of translation and rational lattices are dense in the space of all lattices. Thus, by Lemma 3.1, we may assume that $L_{\epsilon} \subset \mathbb{Q}^{N-1}$. Applying Theorem 1.2 to the lattice $L_{\epsilon}$ and the numbers $\alpha_{1}, \ldots, \alpha_{N-1}$, we get a sequence $\boldsymbol{a}(t)$, satisfying (10)-(12). Note also that, by (17),

$$
0<a_{1}(t)<a_{2}(t)<\cdots<a_{N}(t)
$$

for sufficiently large $t$.
Observe that identity (12) implies (2) with $a_{i}=a_{i}(t), i=1, \ldots, N$, for $t$ large enough. Let us show that, for sufficiently large $t$, the inequality (3) also holds. Define a simplex $S_{\boldsymbol{\alpha}(t)}$ and a lattice $L_{t}$ by

$$
\begin{aligned}
& S_{\boldsymbol{\alpha}(t)}=a_{N}(t) S_{\boldsymbol{a}(t)}=\left\{\left(x_{1}, \ldots, x_{N-1}\right): x_{i} \geqslant 0 \text { reals and } \sum_{i=1}^{N-1} \alpha_{i}(t) x_{i} \leqslant 1\right\}, \\
& L_{t}=a_{N}(t)^{-1 /(N-1)} L_{\boldsymbol{a}(t)} .
\end{aligned}
$$

By (10) and (11), the sequence $L_{t}$ converges to the lattice $L_{\epsilon}$. Next, the point $\boldsymbol{p}=$ $(1 /(2 N), \ldots, 1 /(2 N))$ is an inner point of the simplex $S_{\alpha}$ and all the simplices $S_{\alpha(t)}$ for sufficiently large $t$. By (12) and Lemma 3.1, the sequence $\mu\left(S_{\boldsymbol{\alpha}(t)}-\boldsymbol{p}, L_{t}\right)$ converges to $\mu\left(S_{\boldsymbol{\alpha}}-\boldsymbol{p}, L_{\epsilon}\right)$. Here we consider the sequence $\mu\left(S_{\boldsymbol{\alpha}(t)}-\boldsymbol{p}, L_{t}\right)$ instead of $\mu\left(S_{\boldsymbol{\alpha}(t)}, L_{t}\right)$ because
the distance functions of the family of star bodies in Lemma 3.1 need to converge on the unit ball. Now, since the inhomogeneous minimum is independent of translation, the sequence $\mu\left(S_{\alpha(t)}, L_{t}\right)$ converges to $\mu\left(S_{\alpha}, L_{\epsilon}\right)$. Consequently, by (12),

$$
\frac{\mu\left(S_{\alpha(t)}, L_{t}\right)}{\left(\alpha_{1}(t) \cdots \alpha_{N-1}(t)\right)^{1 /(N-1)}} \rightarrow \frac{\mu\left(S_{\alpha}, L_{\epsilon}\right)}{\left(\alpha_{1} \cdots \alpha_{N-1}\right)^{1 /(N-1)}}, \quad \text { as } t \rightarrow \infty
$$

and, by (13), (18) and (16),

$$
\frac{f_{N}\left(a_{1}(t), \ldots, a_{N}(t)\right)}{\left(a_{1}(t) \cdots a_{N}(t)\right)^{1 /(N-1)}}=\frac{\mu\left(S_{\alpha(t)}, L_{t}\right)}{\left(\alpha_{1}(t) \cdots \alpha_{N-1}(t)\right)^{1 /(N-1)}}<\mu_{0}\left(S_{N-1}\right)+\epsilon
$$

for sufficiently large $t$.

## 4. Proof of Theorem 1.2

Let us consider the matrices

$$
\left.\begin{array}{c}
B=\left(\begin{array}{ccccc}
b_{11} & b_{12} & \ldots & b_{1 N-1} & \sum_{i=1}^{N-1} \alpha_{i} b_{1 i} \\
b_{21} & b_{22} & \ldots & b_{2 N-1} & \sum_{i=1}^{N-1} \alpha_{i} b_{2 i} \\
\vdots & \vdots & & \vdots & \vdots \\
b_{N-11} & b_{N-12} & \ldots & b_{N-1 N-1} & \sum_{i=1}^{N-1} \alpha_{i} b_{N-1 i}
\end{array}\right) \text { and } \\
M
\end{array}=M\left(t, t_{1}, \ldots, t_{N-1}\right) \quad \begin{array}{ccccc}
d b_{11} t+t_{1} & d b_{12} t & \ldots & d b_{1 N-1} t & d \sum_{i=1}^{N-1} \alpha_{i} b_{1 i} t \\
d b_{21} t & d b_{22} t+t_{2} & \ldots & d b_{2 N-1} t & d \sum_{i=1}^{N-1} \alpha_{i} b_{2 i} t \\
\vdots & \vdots & & \vdots & \vdots \\
d b_{N-11} t & d b_{N-12} t & \ldots & d b_{N-1 N-1} t+t_{N-1} & d \sum_{i=1}^{N-1} \alpha_{i} b_{N-1 i} t
\end{array}\right) .
$$

Denote by $M_{i}=M_{i}\left(t, t_{1}, \ldots, t_{N-1}\right)$ and $B_{i}$ the minors obtained by omitting the $i$ th column in $M$ or in $B$, respectively. Following the proof of Theorem 2 in [18], we observe that

$$
\begin{align*}
& \left|B_{N}\right|=\left|\operatorname{det}\left(b_{i j}\right)\right|=\operatorname{det} L  \tag{19}\\
& \left|B_{i}\right|=\alpha_{i}\left|B_{N}\right|,  \tag{20}\\
& M_{i}=d^{N-1} B_{i} t^{N-1}+\begin{array}{l}
\text { polynomial of degree less than } N-1 \text { in } t \\
\text { whose coefficients are functions of } t_{1}, \ldots, t_{N-1}
\end{array}, \tag{21}
\end{align*}
$$

and $M_{1}, \ldots, M_{N}$ have no nonconstant common factor.
By $\left[18\right.$, Theorem 1] applied with $m=1, F=1$, and $F_{1 v}=M_{v}\left(t, t_{1}, \ldots, t_{N-1}\right), v=1, \ldots, N$, there exist integers $t_{1}^{*}, \ldots, t_{N-1}^{*}$ and an infinite arithmetic progression $\mathcal{P}$ such that for $t \in \mathcal{P}$

$$
\operatorname{GCD}\left(M_{1}\left(t, t_{1}^{*}, \ldots, t_{N-1}^{*}\right), \ldots, M_{N}\left(t, t_{1}^{*}, \ldots, t_{N-1}^{*}\right)\right)=1
$$

Put

$$
\boldsymbol{a}(t)=\left(M_{1}\left(t, t_{1}^{*}, \ldots, t_{N-1}^{*}\right), \ldots,(-1)^{N-1} M_{N}\left(t, t_{1}^{*}, \ldots, t_{N-1}^{*}\right)\right), \quad t \in \mathcal{P} .
$$

Then the basis $\boldsymbol{b}_{1}(t), \ldots, \boldsymbol{b}_{N-1}(t)$ for $L_{\boldsymbol{a}(t)}$ satisfying the statement of Theorem 1.2 is given by the rows of the matrix obtained by omitting the $N$ th column in the matrix $M\left(t, t_{1}^{*}, \ldots, t_{N-1}^{*}\right)$. The properties (19)-(21) of minors $M_{i}, B_{i}$ imply the properties (10)-(12) of the sequence $\boldsymbol{a}(t)$, $t \in \mathcal{P}$.

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