# $Q$-operator and factorised separation chain for Jack polynomials 

Dedicated to Tom H. Koornwinder on the occasion of his $60^{\text {th }}$ birthday

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#### Abstract

Applying Baxter's method of the $Q$-operator to the set of Sekiguchi's commuting partial differential operators we show that Jack polynomials $P_{\lambda}^{(1 / g)}\left(x_{1}, \ldots, x_{n}\right)$ are eigenfunctions of a one-parameter family of integral operators $Q_{z}$. The operators $Q_{z}$ are expressed in terms of the Dirichlet-Liouville $n$-dimensional beta integral. From a composition of $n$ operators $Q_{z_{k}}$ we construct an integral operator $\mathcal{S}_{n}$ factorising Jack polynomials into products of hypergeometric polynomials of one variable. The operator $\mathcal{S}_{n}$ admits a factorisation described in terms of restricted Jack polynomials $P_{\lambda}^{(1 / g)}\left(x_{1}, \ldots, x_{k}, 1, \ldots, 1\right)$. Using the operator $Q_{z}$ for $z=0$ we give a simple derivation of a previously known integral representation for Jack polynomials.


## 1. INTRODUCTION

The method of $Q$-operator has been introduced by Rodney Baxter [3,4] who used it to solve the eight-vertex model. Baxter's original $Q$-operator was a finite matrix, which commuted with the transfer-matrix of the model. Later on, Pasquier and Gaudin [31] discovered a connection between the classical Bäcklund transformation and a $Q$-operator for the periodic Toda lattice. Their $Q$-opcrator was a certain integral opcrator with a simple kernel. Rccent developments transformed the method into a unified approach used for solving quan-

[^0]tum integrable systems, with several families having been extensively treated (see, e.g., $[5,23,8,19,32,34]$ ).

Let us take a quantum integrable system defined by $n$ commuting linear partial differential (or difference) operators $H_{i}$ in $n$ variables, whose common eigenfunctions $\Psi_{\lambda}(\mathbf{x}) \equiv \Psi_{\lambda}\left(x_{1}, \ldots, x_{n}\right)$,

$$
\begin{equation*}
H_{i} \Psi_{\lambda}(\mathbf{x})=h_{i}(\lambda) \Psi_{\lambda}(\mathbf{x}) \tag{1.1}
\end{equation*}
$$

form a basis in a Hilbert space $\mathcal{H}$. The multi-index $\lambda=\left(\lambda_{1}, \ldots, \lambda_{n}\right)$ is a set of quantum numbers labelling spectrum $h_{i}(\lambda)$ and eigenfunctions $\Psi_{\lambda}(\mathbf{x})$.

By definition, a $Q$-operator $Q_{z}$ depends on a parameter $z \in \mathbb{C}$ and satisfies two commutativity properties

$$
\begin{align*}
{\left[Q_{z_{1}}, Q_{z_{2}}\right]=0 } & \forall z_{1}, z_{2} \in \mathbb{C}  \tag{1.2}\\
{\left[Q_{z}, H_{i}\right]=0 } & \forall z \in \mathbb{C}, \quad \forall i=1, \ldots, n \tag{1.3}
\end{align*}
$$

which imply that $Q_{z}$ can be diagonalised by the same basis functions $\Psi_{\lambda}(\mathbf{x})$ :

$$
\begin{equation*}
\left[Q_{z} \Psi_{\lambda}\right](\mathbf{y})=q_{\lambda}(z) \Psi_{\lambda}(\mathbf{y}) \tag{1.4}
\end{equation*}
$$

The third and the most important (as well as the characterising) property of a $Q$-operator is that its eigenvalues $q_{\lambda}(z)$ satisfy a linear ordinary differential (or difference) equation with respect to the parameter $z$,

$$
\begin{equation*}
W\left(z, \frac{d}{d z} ;\left\{h_{i}(\lambda)\right\}\right) q_{\lambda}(z)=0 \tag{1.5}
\end{equation*}
$$

whose coefficients, apart from being functions in $z$, depend on the eigenvalues $h_{i}(\lambda)$ of the commuting operators $H_{i}$. Equation (1.5) is called Baxter's equation or, alternatively, the separation equation.

An operator $Q_{z}$ for a quantum integrable system $\left\{H_{i}\right\}$ is a quantization of a Bäcklund transformation for the corresponding classical integrable system. In the quasi-classical limit, its kernel turns into the generating function of the Bäcklund transformation, viewed as a canonical transform [31,23].

A separating operator $\mathcal{S}_{n}$, by definition, factorises the basis functions $\Psi_{\lambda}(\mathbf{x})$ into functions of one variable:

$$
\begin{equation*}
\mathcal{S}_{n}: \Psi_{\lambda}\left(x_{1}, \ldots, x_{n}\right) \mapsto c_{\lambda} \prod_{i=1}^{n} \phi_{\lambda}^{(i)}\left(z_{i}\right) \tag{1.6}
\end{equation*}
$$

$c_{\lambda}$ being some normalization constants. The partial functions $\phi_{\lambda}^{(i)}\left(z_{i}\right)$ are called separated functions and usually satisfy a differential or difference equation like (1.5). Notice that, in the quasi-classical limit, the operator $\mathcal{S}_{n}$ turns into a separating canonical transformation for the corresponding Liouville integrable system.

In [23], two of the authors noticed that any $Q$-operator gives rise to a family of separating operators for an integrable system. Indeed, given a $Q$-operator $Q_{z}$ and an arbitrary linear functional $\rho$ on $\mathcal{H}$, one constructs a product of $n$ such operators

$$
\begin{equation*}
Q_{z}=Q_{z_{1}} \cdots Q_{z_{n}} \tag{1.7}
\end{equation*}
$$

with the kernel $Q_{\mathbf{z}}(\mathbf{y} \mid \mathbf{x})$ as the convolution

$$
\begin{equation*}
Q_{\mathbf{z}}(\mathbf{y} \mid \mathbf{x})=\int d \mathbf{t}_{1} \ldots \int d \mathbf{t}_{n-1} Q_{z_{1}}\left(\mathbf{y} \mid \mathbf{t}_{1}\right) Q_{z_{2}}\left(\mathbf{t}_{1} \mid \mathbf{t}_{2}\right) \ldots Q_{z_{n}}\left(\mathbf{t}_{n-1} \mid \mathbf{x}\right) \tag{1.8}
\end{equation*}
$$

and defines an operator $\mathcal{S}_{n}^{(\rho)}=\rho Q_{z}$ with the kernel

$$
\begin{equation*}
\mathcal{S}_{n}^{(\rho)}(\mathbf{z} \mid \mathbf{x})=\int d \mathbf{y} \rho(\mathbf{y}) Q_{\imath}(\mathbf{y} \mid \mathbf{x}), \tag{1.9}
\end{equation*}
$$

where $\rho(\mathbf{y})$ is the generalised function corresponding to $\rho$. It then follows from (1.4) and (1.6)-(1.9) that $\mathcal{S}_{n}^{(p)}$ is a family of separating operators (parameterised by the functional $\rho$ ) with

$$
\begin{equation*}
\phi_{\lambda}^{(i)}\left(z_{i}\right)=q_{\lambda}\left(z_{i}\right) \quad \text { and } \quad c_{\lambda}=\int d \mathbf{y} \rho(\mathbf{y}) \Psi_{\lambda}(\mathbf{y}) . \tag{1.10}
\end{equation*}
$$

A clever choice of the 'projection function' $\rho(\mathbf{y})$ can, in principle, simplify the structure of the integral operator $\mathcal{S}_{n}^{(\rho)}$. Our main motivation is to study suitable classes of $Q$-operators and functions $\rho(\mathbf{y})$ for a variety of quantum integrable models in order to construct simplest separating operators $\mathcal{S}_{n}(1.6)$, which factorise special functions $\Psi_{\lambda}\left(x_{1}, \ldots, x_{n}\right)$.

In the present paper, we apply the above ideas to the Calogero-Sutherland integrable model. In our case of study $\mathcal{H}$ is an appropriate Hilbert space closure of the space $\mathbb{C}\left[x_{1}, \ldots, x_{n}\right]^{S_{n}}$ of symmetric polynomials in $n$ variables, $\Psi_{\lambda}\left(x_{1}, \ldots, x_{n}\right)$ are Jack polynomials and $\lambda=\left(\lambda_{1}, \ldots, \lambda_{n}\right)$ is a partition.
The problem of separation of variables for the Calogero-Sutherland model and for its $q$-analogue has been addressed by the authors in a series of publications since 1994. Many of the results presented below generalise those obtained from the studies of the few particle cases, $n=2,3,4$, in [33,20,21,18,22,24,26,27].
The paper is organised as follows. Section 2 fixes notation and collects the necessary background information on Jack polynomials. In Section 3 we study the propertics of Dirichlct-Liouville multidimensional beta-integrals, which constitute our main analytical tool. All integral operators that we construct are expressed in terms of these integrals. In Section 4 we introduce a Q-operator $Q_{z}$ for the Calogero-Sutherland model and derive its properties. In particular, we prove that $Q_{z}$ is diagonal in the basis of Jack polynomials. Thus, the eigenvalue problem $Q_{z} \Psi_{\lambda}-q_{\lambda}(z) \Psi_{\lambda}$ can be considered as an integral equation for Jack polynomials. In Section 5 we obtain the eigenvalues $q_{\lambda}(z)$ of $Q_{z}$ and give for them several explicit expressions, including the one in terms of the generalised hypergeometric series. In section 6 we construct the separating operator $\mathcal{S}_{n}^{(\rho)}$ and show that for a special choice of the functional $\rho=\rho_{0}$ it splits into a product of $n$ operators $\mathcal{A}_{i}, i=1, \ldots, n$,

$$
\begin{equation*}
\mathcal{S}_{n}^{\left(\rho_{0}\right)}=\mathcal{A}_{1} \cdots \mathcal{A}_{n}, \tag{1.11}
\end{equation*}
$$

such that each operator $\mathcal{A}_{k}$ acts only on $k$ variables. Such a factorisation is an
example of the factorised separation chain introduced in [17] for integrable models of $s l(2)$ class.
In Section 7 we describe another application of the $Q$-operator $Q_{z}$. Setting $z=0$ we show that the operator $Q_{0}$ leads to an integral relation between Jack polynomials in $n$ and $n-1$ variables $\left\{x_{i}\right\}$. Iterating this relation we produce an integral representation for Jack polynomials, which is equivalent to the integral representation due to Okounkov and Olshanski [28] who found it as a limit from a formula involving shifted Jack polynomials.

## 2. JACK POLYNOMIALS

This section serves an introductory purpose as it fixes notation and collects the necessary background information on Jack polynomials.
Jack polynomials $P_{\lambda}^{(\alpha)}\left(x_{1}, \ldots, x_{n}\right)$ [12,13,14,16,35,25] are orthogonal symmetric polynomials, discovered by Henry Jack in 1970 as a one-parameter extension of the Schur functions $s_{\lambda}\left(x_{1}, \ldots, x_{n}\right)$. In the case $\alpha=2$, they reduce to zonal polynomials constructed by James in 1960 ([15]). We shall use the parameter $g=1 / \alpha$, instead of $\alpha$ as in [25], i.e. use the notation $P_{\lambda}^{(1 / g)}(\mathbf{x}) \equiv P_{\lambda}^{(1 / g)}\left(x_{1}, \ldots, x_{n}\right)$.
Let $\lambda=\left(\lambda_{1}, \lambda_{2}, \ldots, \lambda_{n}\right) \in \mathbb{N}^{n}, \lambda_{1} \geq \lambda_{2} \geq \ldots \geq \lambda_{n} \geq 0$, be a partition of an arbitrary weight $|\lambda|$,

$$
\begin{equation*}
|\lambda|=\sum_{i=1}^{n} \lambda_{i} . \tag{2.1}
\end{equation*}
$$

Hereafter, we shall use the weight notation $|$.$| as in (2.1) for any finite sum of$ indexed variables. The dominance partial ordering $\preceq$ for two partitions $\mu$ and $\lambda$ is defined as follows:

$$
\begin{equation*}
\mu \preceq \lambda \Longleftrightarrow\left\{|\mu|=|\lambda| ; \quad \sum_{j=1}^{k} \mu_{j} \leq \sum_{j=1}^{k} \lambda_{j}, \quad k=1, \ldots, n-1\right\} . \tag{2.2}
\end{equation*}
$$

Usually ( cf [25]), the length $l(\lambda)$ of a partition $\lambda$ is the number of non-zero parts $\lambda_{i}$. We shall consider the partitions $\lambda=\left(\lambda_{1}, \lambda_{2}, \ldots, \lambda_{n}\right)$ that are finite sequences of exact length $n$, including any zero parts. For instance, ( $6,6,2,0$ ) and $(6,0,0,0)$ are both partitions of the length 4 , while $(6,6,2)$ and (6) have lengths 3 and 1 , respectively. The reason for this deviation from the standard definition is because we shall study Jack polynomials with the finite number of variables and characterise them as eigenfunctions of the complete set of $n$ commuting partial differential operators $\left\{H_{i}\right\}$ in $n$ variables. In this picture, the parts $\lambda_{i}$ are the labels that parameterise the spectrum and the eigenfunctions of the operators $\left\{H_{i}\right\}$. The number of parts, therefore, will always be equal to the number of the operators $H_{i}$ (or to the number of the variables $x_{i}$ ).
In the main text, for any partition $\lambda=\left(\lambda_{1}, \ldots, \lambda_{n}\right)$ of the length $n$, we shall often use the notation $\lambda_{i, j}=\lambda_{i}-\lambda_{j}$, in particular $\lambda_{i, i+1}=\lambda_{i}-\lambda_{i+1}, i=1, \ldots, n$, $\lambda_{n+1} \equiv 0$.

In the theory of symmetric polynomials, the number $n$ of the variables $x_{i}$ is often irrelevant because many results have been obtained for the case when this number is assumed to be large enough, for instance $n \geq|\lambda|$, for the stabilised polynomials [35]. In this paper, the number $n$ of the variables $x_{i}$ is a fixed finite number, the partition $\lambda$ is of the length $n$ and has an arbitrary weight $|\lambda|$, which means that we shall mostly deal with the non-stabilised Jack polynomials.

Let $\mathbb{C}(a, b, c, \ldots)$ be the field of rational functions in indeterminates $a, b, c, \ldots$ over the field $\mathbb{C}$ of complex numbers, $\mathbb{C}(a, b, c, \ldots)[x, y, z, \ldots]$ be the ring of polynomials in the variables $x, y, z, \ldots$ with coefficients from $\mathbb{C}(a, b, c, \ldots)$, and $\mathbb{C}\left[x_{1}, \ldots, x_{n}\right]^{S_{n}}$ be the subring of symmetric polynomials.

We need two standard bases in $\mathbb{C}\left[\mathbf{x}^{S_{n}}\right.$ labelled by partitions $\lambda$. For each $\mathbf{a}=$ $\left(a_{1}, \ldots, a_{n}\right) \in \mathbb{N}^{n}$ let us denote by $\mathbf{x}^{\mathbf{a}}$ the monomial

$$
\begin{equation*}
\mathbf{x}^{\mathbf{a}}=x_{1}^{a_{1}} \cdots x_{n}^{a_{n}} \tag{2.3}
\end{equation*}
$$

The monomial symmetric functions $m_{\lambda}(\mathbf{x})$ are defined by

$$
\begin{equation*}
m_{\lambda}(\mathbf{x})=\sum \mathbf{x}^{\nu} \tag{2.4}
\end{equation*}
$$

where the sum is taken over all distinct permutations $\nu$ of $\lambda$. The $m_{\lambda}(\mathbf{x})$ form a basis in $\mathbb{C}[\mathbf{x}]^{S_{n}}$.

For each $r=0, \ldots, n$ the $r$ th elementary symmetric function $e_{r}(\mathbf{x})$ is the sum of all products of $r$ distinct variables $x_{i}$, so that $e_{0}(\mathbf{x})=1$ and

$$
\begin{equation*}
e_{r}(\mathbf{x})=\sum_{1 \leq i_{1}<\ldots<i_{r} \leq n} x_{i_{1}} x_{i_{2}} \cdots x_{i_{r}}=m_{\left(1^{1} 0^{n-r}\right)}(\mathbf{x}) \tag{2.5}
\end{equation*}
$$

for $r=1, \ldots, n$. For each partition $\lambda=\left(\lambda_{1}, \ldots, \lambda_{n}\right)$ define the polynomials $E_{\lambda}(\mathbf{x})$ as

$$
\begin{equation*}
E_{\lambda}(\mathbf{x})=e_{1}^{\lambda_{1}-\lambda_{2}}(\mathbf{x}) e_{2}^{\lambda_{2}-\lambda_{3}}(\mathbf{x}) \cdots e_{n}^{\lambda_{n}}(\mathbf{x}) \tag{2.6}
\end{equation*}
$$

The polynomials $E_{\lambda}(\mathbf{x})$ also form a basis in $\mathbb{C}[\mathbf{x}]^{S_{n}}$ and the transition matrix between $E_{\lambda}$ and $m_{\lambda}$ is triangular with respect to the dominance partial ordering (see [25], Ch. 1, Sec. 2):

$$
\begin{equation*}
E_{\lambda}(\mathbf{x})=\sum_{\mu \leq \lambda} a_{\lambda \mu} m_{\mu}(\mathbf{x}) \tag{2.7}
\end{equation*}
$$

where $a_{\lambda \mu} \in \mathbb{N}$ and $a_{\lambda \lambda}=1$.
Jack polynomials $P_{\lambda}=P_{\lambda}^{(1 / g)}(\mathbf{x}) \in \mathbb{C}(g)[\mathbf{x}]^{S_{n}}$ are homogeneous of degree $|\lambda|$ :

$$
\begin{equation*}
P_{\lambda}^{(1 / g)}\left(x_{1}, \ldots, x_{n}\right)=x_{n}^{|\lambda|} P_{\lambda}^{(1 / g)}\left(x_{1} / x_{n}, \ldots, x_{n-1} / x_{n}, 1\right) \tag{2.8}
\end{equation*}
$$

They form a basis in $\mathbb{C}(g)[\mathbf{x}]^{S_{n}}$. The transition matrix between the bases $P_{\lambda}$ and $m_{\lambda}$ is triangular with respect to the dominance partial ordering:

$$
\begin{equation*}
P_{\lambda}=\sum_{\mu \preceq \lambda} v_{\lambda \mu}(g) m_{\mu}, \quad v_{\lambda \mu}(g) \in \mathbb{C}(g), \quad v_{\lambda \lambda}=1 \tag{2.9}
\end{equation*}
$$

The three bases, $m_{\lambda}, E_{\lambda}$ and $P_{\lambda}$, are thus mutually triangular.

The polynomials $P_{\lambda}^{(1 / g)}(\mathbf{x})$ diagonalise the Sekiguchi partial differential operators [30] given by the generating function $D(u ; g)$ :

$$
\begin{equation*}
D(u ; g)=\frac{(-1)^{n(n-1) / 2}}{\Delta_{n}(\mathbf{x})} \operatorname{det}\left[x_{i}^{n-j}\left(x_{i} \frac{\partial}{\partial x_{i}}+(n-j) g+u\right)\right]_{i, j=1}^{n}, \tag{2.10}
\end{equation*}
$$

$$
\begin{equation*}
D(u ; g) P_{\lambda}^{(1 / g)}(\mathbf{x})=\left[\prod_{i=1}^{n}\left(\lambda_{i}+(n-i) g \mid u\right)\right] P_{\lambda}^{(1 / g)}(\mathbf{x}) \tag{2.11}
\end{equation*}
$$

where

$$
\begin{equation*}
\Delta_{n}(\mathbf{x})=\operatorname{det}\left[x_{j}^{i-1}\right]_{i, j=1}^{n}=\prod_{1 \leq i<j \leq n}\left(x_{j}-x_{i}\right) \tag{2.12}
\end{equation*}
$$

is the Vandermonde determinant. Expansion (2.9) and the fact that $P_{\lambda}$ are the eigenfunctions of the Sekiguchi operators characterise Jack polynomials uniquely.

Generating function $D(u ; g)$ is an operator polynomial in $u$ whose coefficients give $n$ commuting partial differential operators $H_{i}, i=1, \ldots, n$ :

$$
\begin{equation*}
D(u ; g)=u^{n}+\sum_{i=1}^{n} u^{n-i} H_{i}, \quad H_{1}=\frac{n(n-1)}{2} g+\sum_{i=1}^{n} x_{i} \frac{\partial}{\partial x_{i}} \tag{2.13}
\end{equation*}
$$

Define the second order partial differential operator $H$ as

$$
\begin{equation*}
H=\frac{n(n-1)(n-2)}{6} g^{2}+H_{1}\left[H_{1}-(n-1) g\right]-2 H_{2} \tag{2.14}
\end{equation*}
$$

then

$$
\begin{equation*}
H=\sum_{i=1}^{n}\left(x_{i} \frac{\partial}{\partial x_{i}}\right)^{2}+g \sum_{i<j} \frac{x_{i}+x_{j}}{x_{i}-x_{j}}\left(x_{i} \frac{\partial}{\partial x_{i}}-x_{j} \frac{\partial}{\partial x_{j}}\right) \tag{2.15}
\end{equation*}
$$

It follows from (2.11) that

$$
\begin{equation*}
H P_{\lambda}^{(1 / g)}(\mathbf{x})=h(\lambda) P_{\lambda}^{(1 / g)}(\mathbf{x}), \quad h(\lambda)=\sum_{i=1}^{n} \lambda_{i}\left[\lambda_{i}+g(n+1-2 i)\right] . \tag{2.16}
\end{equation*}
$$

Jack polynomials were applied in $[6,36,29]$ to describe the excited states in the Calogero-Sutherland model. Let us briefly remind some facts about this model. It describes a system of $n$ quantum particles on a circle with coordinates $0 \leq q_{i} \leq \pi, i=1, \ldots, n$. The quantum Hamiltonian and the operator of the total momentum are

$$
\begin{equation*}
H_{C S}=-\frac{1}{2} \sum_{i=1}^{n} \frac{\partial^{2}}{\partial q_{i}^{2}}+\sum_{i<j} \frac{g(g-1)}{\sin ^{2}\left(q_{i}-q_{j}\right)}, \quad P_{C S}=-i \sum_{j=1}^{n} \frac{\partial}{\partial q_{j}} \tag{2.17}
\end{equation*}
$$

The space of quantum states of the model is the complex Hilbert space $L^{2}\left(T^{n} / S_{n}\right)$ of functions $\Psi(\mathbf{q})$ on the torus $T^{n}=\mathbb{R}^{n} / \pi \mathbb{Z}^{n} \ni \mathbf{q}$, symmetric with
respect to permutations of the coordinates $q_{i}$. The scalar product in $L^{2}\left(T^{n} / S_{n}\right)$ is defined as follows:

$$
\begin{equation*}
\langle\Psi, \Phi\rangle=\frac{1}{n!} \int_{0}^{\pi} d q_{1} \cdots \int_{0}^{\pi} d q_{n} \overline{\Psi(\mathbf{q})} \Phi(\mathbf{q}) \tag{2.18}
\end{equation*}
$$

The differential operators (2.17) are formally Hermitian with respect to the scalar product (2.18) when the parameter $g$ is real. Most results of the present paper are established, however, for $g>0$, which we shall assume hereafter.

The ground state of the model is given by the function

$$
\begin{equation*}
\omega(\mathbf{q})=\left|\prod_{i<j} \sin \left(q_{i}-q_{j}\right)\right|^{g} \tag{2.19}
\end{equation*}
$$

with the ground state energy $E_{0}=\frac{1}{6} g^{2}\left(n^{3}-n\right)$. The gauge transformation of the Hamiltonian $H_{C S}(2.17)$ with the function $\omega(\mathbf{q})$ gives

$$
\begin{equation*}
\omega^{-1}(\mathbf{q}) \circ H_{C S} \circ \omega(\mathbf{q})=\frac{1}{2} H+E_{0} \tag{2.20}
\end{equation*}
$$

where the operator $H$ is defined by (2.15) and the change of variables from $\mathbf{q}$ to $\mathbf{x}=\varepsilon(\mathbf{q})$ is given by the map

$$
\begin{equation*}
\varepsilon:\left(q_{1}, \ldots, q_{n}\right) \mapsto\left(e^{2 i q_{1}}, \ldots, e^{2 i q_{n}}\right) \tag{2.21}
\end{equation*}
$$

The eigenfunctions of the $H_{C S}$ can therefore be chosen as the product of the ground state function and a Jack polynomial labelled by a partition $\lambda$ :

$$
\begin{equation*}
\Psi_{\lambda}(\mathbf{q})=\omega(\mathbf{q}) P_{\lambda}^{(1 / g)}(\varepsilon(\mathbf{q})) \tag{2.22}
\end{equation*}
$$

The Hermitian form (2.18) corresponds to the following scalar product for any two symmetric polynomials $f(\mathbf{x})$ and $p(\mathbf{x})$ from $\mathbb{C}[\mathbf{x}]^{S_{n}}$ :

$$
\begin{equation*}
\langle f, p\rangle=\int_{T_{\mathbf{v}}} d \mathbf{v}[\omega(\mathbf{v})]^{2} \overline{f(\varepsilon(\mathbf{v}))} p(\varepsilon(\mathbf{v})) \tag{2.23}
\end{equation*}
$$

where the integration domain, by symmetry, is

$$
\begin{equation*}
T_{\mathbf{v}}=\left\{\mathbf{v} \in \mathbb{R}^{n} / \pi \mathbb{Z}^{n} \mid v_{j} \in\left(v_{j-1}, v_{j+1}\right), \quad j+n \equiv j\right\} \tag{2.24}
\end{equation*}
$$

The intervals $\left(v_{j-1}, v_{j+1}\right)$ above are understood as arcs on the circle $\mathbb{R} / \pi \mathbb{Z}$ such that $v_{j-1}$ precedes $v_{j+1}$ with respect to the orientation on $\mathbb{R}$.

For $g>0$, Jack polynomials $P^{(1 / g)}(\mathbf{x})$ are orthogonal with respect to the scalar product (2.23). Note that $\overline{P_{\lambda}^{(1 / g)}(\mathbf{x})}=P_{\lambda}^{(1 / g)}\left(\overline{x_{1}}, \ldots, \overline{x_{n}}\right)$.

## 3. DIRICHLET-LIOUVILLE INTEGRAL AND ITS MODIFICATIONS

The Dirichlet integrals and their extension due to Liouville (see, e.g., [1]) are the most straightforward multidimensional generalisations of the beta-integral. They are used in computing volumes and surface areas of multidimensional ellipsoids. A special form of these integrals serves as the main building tool for our construction of the $Q$-operator for Jack polynomials. In what follows, the
powers $\xi^{\alpha}$ are functions of a positive argument $\xi>0$ and are understood as $\xi^{\alpha}=\exp (\alpha \ln \xi)$, with $\ln \xi \in \mathbb{R}$.

Theorem 3.1. (Dirichlet-Liouville [1]) Define the domain $V_{\xi} \subset \mathbb{R}^{n}$ as

$$
\begin{equation*}
V_{\xi}=\left\{\xi \in \mathbb{R}^{n} \mid \xi_{i}>0, i=1, \ldots, n\right\} \tag{3.1}
\end{equation*}
$$

Then for $\Re \alpha_{i}>0$,

$$
\begin{equation*}
\int_{V_{\xi}} d \xi \delta(|\xi|-1) \xi_{1}^{\alpha_{1}-1} \cdots \xi_{n}^{\alpha_{n}-1}=\frac{\Gamma\left(\alpha_{1}\right) \cdots \Gamma\left(\alpha_{n}\right)}{\Gamma(|\alpha|)} \tag{3.2}
\end{equation*}
$$

where $\alpha=\left(\alpha_{1}, \ldots, \alpha_{n}\right),|\alpha|=\alpha_{1}+\cdots+\alpha_{n}, d \xi=d \xi_{1} \cdots d \xi_{n}$, and $\delta$ is the Dirac delta-function.

The proof can be found in [1]. We use iwo modifications of the integral (3.2) given in Theorems 3.2 and 3.3 below.

Theorem 3.2. Let $\mathbf{y}=\left(y_{1}, \ldots, y_{n}\right)$ be a fixed set of real positive parameters such that

$$
\begin{equation*}
0<y_{1}<y_{2}<\ldots<y_{n}<\infty \tag{3.3}
\end{equation*}
$$

Define the domain $\Omega_{\mathrm{x}} \subset \mathbb{R}^{n}$ by the inequalities

$$
\begin{equation*}
\Omega_{\mathbf{x}}=\left\{\mathbf{x} \in \mathbb{R}^{n} \mid 0<y_{1}<x_{1}<y_{2}<\ldots<x_{n-1}<y_{n}<x_{n}<\infty\right\} . \tag{3.4}
\end{equation*}
$$

Let $\check{x} \equiv e_{n}(\mathbf{x})=x_{1} \cdots x_{n}$ and $\check{y} \equiv e_{n}(\mathbf{y})=y_{1} \cdots y_{n}$. Then for $\Re \alpha_{i}>0$ and $z>1$,

$$
\begin{equation*}
\int_{\Omega_{\mathbf{x}}} d \mathbf{x} \delta(\check{x}-z \check{y}) \Delta_{n}(\mathbf{x}) \prod_{i=1}^{n} \xi_{i}^{\alpha_{i}-1}=(z-1)^{|\alpha|-1} \Delta_{n}(\mathbf{y}) \frac{\prod_{i=1}^{n} y_{i}^{\alpha_{i}}{ }^{1} \Gamma\left(\alpha_{i}\right)}{\Gamma(|\alpha|)} \tag{3.5}
\end{equation*}
$$

where $\Delta_{n}$ is the Vandermonde determinant (2.12) and $\xi_{i}$ are defined as follows:

$$
\begin{equation*}
\xi_{i}=\frac{\prod_{k=1}^{n}\left(x_{k}-y_{i}\right)}{\prod_{k \neq i}\left(y_{k}-y_{i}\right)} \tag{3.6}
\end{equation*}
$$

The other modification of the Dirichlet-Liouville integral is a trigonometric variant of (3.5).

Theorem 3.3. Given a fixed set of real parameters $\mathbf{v}=\left(v_{1}, \ldots, v_{n}\right)$ such that

$$
\begin{equation*}
v_{1}<v_{2}<\ldots<v_{n}<\pi+v_{1} \tag{3.7}
\end{equation*}
$$

define the domain $\Omega_{\mathbf{u}}^{T} \subset \mathbb{R}^{n}$ by the inequalities

$$
\begin{equation*}
\Omega_{\mathbf{u}}^{T}=\left\{\mathbf{u} \in \mathbb{R}^{n} \mid v_{1}<u_{1}<v_{2}<\ldots<u_{n-1}<v_{n}<u_{n}<\pi+v_{1}\right\} \tag{3.8}
\end{equation*}
$$

Then for $\gamma \in(0, \pi)$ and $\Re \alpha_{i}>0$,

$$
\begin{align*}
& \int_{S_{\mathbf{u}}^{T}} d \mathbf{u} \delta(|\mathbf{u}|-|\mathbf{v}|-\gamma)\left[\prod_{i<j} \sin \left(u_{j}-u_{i}\right)\right]\left[\prod_{i=1}^{n}\left(\xi_{i}^{T}\right)^{\alpha_{i}-1}\right] \\
& =(\sin \gamma)^{|\alpha|-1}\left[\prod_{i<j} \sin \left(v_{j}-v_{i}\right)\right] \frac{\prod_{i=1}^{n} \Gamma\left(\alpha_{i}\right)}{\Gamma(|\alpha|)} \tag{3.9}
\end{align*}
$$

where

$$
\begin{equation*}
\xi_{i}^{T}=\frac{\prod_{k=1}^{n} \sin \left(u_{k}-v_{i}\right)}{\prod_{k \neq i} \sin \left(v_{k}-v_{i}\right)} . \tag{3.10}
\end{equation*}
$$

Both Theorems are proved by performing the respective changes of variables, from $\left\{\xi_{i}\right\}$ to $\left\{x_{i}\right\}$ (3.6) and from $\left\{\xi_{i}^{T}\right\}$ to $\left\{u_{i}\right\}$ (3.10), in the integral (3.2).

Proof of Theorem 3.2. The first step is to rescale the variables $\xi_{i} \mapsto \frac{\xi_{i}}{y_{i}(z-1)}$ in the integral (3.2) and to rewrite it in the form

$$
\begin{equation*}
\int_{V_{\xi}} d \xi \delta\left(\sum_{i=1}^{n} \frac{\xi_{i}}{y_{i}}-(z-1)\right) \prod_{i=1}^{n} \xi_{i}^{\alpha_{i}-1}=(z-1)^{|\alpha|-1} \frac{\prod_{i=1}^{n} y_{i}^{\alpha_{i}} \Gamma\left(\alpha_{i}\right)}{\Gamma(|\alpha|)} \tag{3.11}
\end{equation*}
$$

The next step is to prove that the relations (3.6) define a bijection of $V_{\xi}$ onto $\Omega_{\mathbf{x}}$. From the inequalities in (3.4) it follows immediately that $\Omega_{\mathrm{x}}$ is mapped into $V_{\xi}$. To prove the invertibility of this mapping consider the rational function

$$
\begin{equation*}
R(t)=\prod_{i=1}^{n} \frac{t-x_{i}}{t-y_{i}} \tag{3.12}
\end{equation*}
$$

It is easy to see that res ${ }_{t=y_{i}} R(t)=-\xi_{i}$ and $\lim _{t \rightarrow \infty} R(t)=1$, and therefore

$$
\begin{equation*}
R(t)=1-\sum_{i=1}^{n} \frac{\xi_{i}}{t-y_{i}} \tag{3.13}
\end{equation*}
$$

Given a set of positive $\xi_{i}>0$, the function $R(t)$ is restored by the formula (3.13), and the variables $x_{i}$ are then determined uniquely as its zeroes, taken in the increasing order. The standard continuity argument, using $\xi_{i}>0$, shows that all $n$ zeroes $x_{j}$ of $R(t)$ are real and interspersed with the poles $y_{j}$ of $R(t)$ and $+\infty$ or, equivalently, belong to the domain $\Omega_{\mathrm{x}}$.

The bijectivity of the mapping $\xi \longrightarrow \mathbf{x}$ having been thus established, its Jacobian is as follows:

$$
\begin{equation*}
J=\operatorname{det}\left[\frac{\partial \xi_{j}}{\partial x_{i}}\right]_{i, j=1}^{n}=\operatorname{det}\left[\frac{\xi_{j}}{x_{i}-y_{j}}\right]_{i, j=1}^{n}=\frac{\Delta_{n}(\mathbf{x})}{\Delta_{n}(\mathbf{y})}>0 \tag{3.14}
\end{equation*}
$$

which was evaluated with the help of Cauchy's determinantal formula [7]

$$
\begin{equation*}
\operatorname{det}\left[\frac{1}{1-a_{i} b_{j}}\right]_{i, j=1}^{n}=\frac{\Delta_{n}(\mathbf{a}) \Delta_{n}(\mathbf{b})}{\prod_{i, j=1}^{n}\left(1-a_{i} b_{j}\right)} \tag{3.15}
\end{equation*}
$$

Setting $t=0$ in (3.12) and (3.13) we get $1+\sum_{i=1}^{n} \xi_{i} / y_{i}=\prod_{k=1}^{n} x_{k} / y_{k}$, and hence,

$$
\begin{equation*}
\delta\left(\sum_{y_{i}}^{\underline{\xi}_{i}}-(z-1)\right)=\left(\prod^{y_{k}}\right) \delta\left(\prod^{x_{k}-z} \prod^{y_{k}}\right) . \tag{3.16}
\end{equation*}
$$

Using (3.14) and (3.16) we can now fulfil the change of variables $\xi \mapsto \mathbf{x}$ in (3.11) and obtain (3.5).

The proof of Theorem 3.3 is similar to the above, but the structure of the mapping $\xi^{T} \mapsto \mathbf{u}$ (3.10) is, however, more involved compared to the rational case (3.6).

Proposition 3.1. Define the domains $V_{\xi}^{T}, \Phi_{\mathbf{u}}^{ \pm} \subset \mathbb{R}^{n}$ as

$$
\begin{equation*}
V_{\xi}^{T}=\left\{\xi \in \mathbb{R}^{n}| | \xi \mid<1, \xi_{i}>0 ; i=1, \ldots, n\right\} \tag{3.17}
\end{equation*}
$$

and

$$
\begin{equation*}
\Phi_{\mathbf{u}}^{-}=\left\{\mathbf{u} \in \Omega_{\mathbf{u}}^{T}| | \mathbf{u}\left|<|\mathbf{v}|+\frac{\pi}{2}\right\}, \quad \Phi_{\mathbf{u}}^{+}=\left\{\mathbf{u} \in \Omega_{\mathbf{u}}^{T}| | \mathbf{u}\left|>|\mathbf{v}|+\frac{\pi}{2}\right\}\right.\right. \tag{3.18}
\end{equation*}
$$

Then the change of variables $\mathbf{u} \mapsto \xi^{T}$ maps the sets $\Phi_{\mathbf{u}}^{ \pm}$bijectively onto $V_{\xi}^{T}$.
Proof. Consider the function $R(t)$

$$
\begin{equation*}
R(t)=\prod_{i=1}^{n} \frac{\sin \left(t-u_{i}\right)}{\sin \left(t-v_{i}\right)} \tag{3.19}
\end{equation*}
$$

Noting that $\operatorname{res}_{t=v_{i}} R(t)=-\xi_{i}^{T}, R(t)$ can be rewritten in the form

$$
\begin{equation*}
R(t)=c-\sum_{i=1}^{n} \xi_{i}^{T} \cot \left(t \quad v_{i}\right) \tag{3.20}
\end{equation*}
$$

Comparing the limits of the two expressions for $R(t)$ at $t \rightarrow \pm i \infty$ one gets

$$
\begin{equation*}
c=\cos (|\mathbf{u}|-|\mathbf{v}|), \quad\left|\xi^{T}\right|=\sin (|\mathbf{u}|-|\mathbf{v}|) \tag{3.21}
\end{equation*}
$$

Suppose that $\mathbf{u} \in \Omega_{\mathbf{u}}^{T}$, that is either $\mathbf{u} \in \Phi_{\mathbf{u}}^{-}$or $\mathbf{u} \in \Phi_{\mathbf{u}}^{+}$. Then, from the inequalities (3.8) and the expressions (3.10) for $\xi_{i}^{T}$, it follows that $\xi_{i}^{T}>0$. It also follows from (3.21) that $\left|\xi^{T}\right| \in(0,1)$, for $0<|\mathbf{u}|-|\mathbf{v}|<\pi$. Thus, both domains $\Phi_{\mathrm{u}}^{ \pm}$are mapped into $V_{\xi}^{T}$. Conversely, given $\xi^{T} \in V_{\xi}^{T}$, one obtains from the relation $c^{2}+\left|\xi^{T}\right|^{2}=1$ (cf (3.21)) two possible valucs for the constant $c$ in (3.20). The inequalities in (3.17) ensure that $c^{2} \in(0,1)$. Having chosen a solution for $c$, one reconstructs $R(t)$ using the formula (3.20). The continuity argument, based on the positivity of $\xi_{i}^{T}$, shows that the zeroes $u_{i}$ of $R(t)$ belong to the domain $\Omega_{\mathbf{u}}^{T}$. The positive $c \in(0,1)$ correspond to $\mathbf{u} \in \Phi_{\mathbf{u}}^{-}$and the negative $c \in(-1,0)$ to $\mathbf{u} \subset \Phi_{\mathbf{u}}^{+}$.

Proof of Theorem 3.3 starts with rescaling the variables $\xi_{i} \mapsto \frac{\xi_{i}}{\sin \gamma}$ in the integral (3.2) which transforms it into the formula

$$
\begin{equation*}
\int_{V_{\xi}} d \xi \delta(|\xi|-\sin \gamma) \xi_{1}^{\alpha_{1}-1} \cdots \xi_{n}^{\alpha_{n}-1}=(\sin \gamma)^{|\alpha|-1} \frac{\Gamma\left(\alpha_{1}\right) \cdots \Gamma\left(\alpha_{n}\right)}{\Gamma(|\alpha|)} \tag{3.22}
\end{equation*}
$$

By the condition of the Theorem, $\gamma \in(0, \pi)$, so $\sin \gamma \in(0,1)$, and therefore the integration in (3.22) can be restricted to $V_{\xi}^{T}$. The Jacobian of the mapping $\xi^{T} \mapsto \mathbf{u}$,

$$
\begin{equation*}
J^{T}=\operatorname{det}\left[\frac{\partial \xi_{j}^{T}}{\partial u_{i}}\right]_{i, j=1}^{n}=\operatorname{det}\left[\xi_{j}^{T} \cot \left(u_{i}-v_{j}\right)\right]_{i, j=1}^{n} \tag{3.23}
\end{equation*}
$$

can be calculated with the help of a trigonometric limit of the generalized (elliptic) Cauchy determinant (cf $[11,18]$ ),

$$
\begin{equation*}
\operatorname{det}\left[\frac{\sigma\left(x_{i}-y_{j}+\zeta\right)}{\sigma\left(x_{i}-y_{j}\right) \sigma(\zeta)}\right]_{i, j=1}^{n}=\frac{\sigma(\Sigma+\zeta)}{\sigma(\zeta)} \frac{\prod_{k<l} \sigma\left(x_{k}-x_{l}\right) \sigma\left(y_{l}-y_{k}\right)}{\prod_{k, l} \sigma\left(x_{k}-y_{l}\right)}, \tag{3.24}
\end{equation*}
$$

where $\sigma(x)$ is the Weierstrass sigma-function and $\Sigma \equiv \sum_{i}\left(x_{i}-y_{i}\right)$. Take the limit of the infinite imaginary period, $\omega^{\prime} \rightarrow \infty$, choose the real period $\omega=\frac{\pi}{2}$ and put $\zeta=\frac{\pi}{2}$, then $\sigma(x) \rightarrow \exp \left(\frac{1}{6} x^{2}\right) \sin x$ and (3.24) turns into the following trigonometric determinantal formula:

$$
\begin{equation*}
\operatorname{det}\left[\cot \left(x_{i}-y_{j}\right)\right]_{i, j=1}^{n}=\cos (\Sigma) \frac{\prod_{k \leq l} \sin \left(x_{k}-x_{l}\right) \sin \left(y_{l}-y_{k}\right)}{\prod_{k, l} \sin \left(x_{k}-y_{l}\right)} \tag{3.25}
\end{equation*}
$$

Now we can evaluate the Jacobian $J^{T}$ in (3.23):

$$
\begin{equation*}
J^{T}=\cos (|\mathbf{u}|-|\mathbf{v}|) \prod_{i<j} \frac{\sin \left(u_{j}-u_{i}\right)}{\sin \left(v_{j}-v_{i}\right)} \tag{3.26}
\end{equation*}
$$

Notice that $J^{T}$ is positive for $\mathbf{u} \in \Phi_{\mathbf{u}}^{-}$and negative for $\mathbf{u} \in \Phi_{\mathbf{u}}^{+}$.
Using (3.21), one transforms the $\delta$-function in (3.22) as

$$
\begin{equation*}
\delta(|\xi|-\sin \gamma)=\frac{\delta(|\mathbf{u}|-|\mathbf{v}|-\gamma)}{\cos \gamma} \tag{3.27}
\end{equation*}
$$

Finally, combining (3.26) and (3.27) one fulfils the change of variables $\xi^{T} \mapsto \mathbf{u}$ in (3.22) and obtains (3.9). When $\gamma \in(0, \pi / 2)$, the integration in (3.9) can be restricted to $\Phi_{\mathbf{u}}^{-}$, and when $\gamma \in(\pi / 2, \pi)$, the integration is over $\Phi_{\mathbf{u}}^{+}$. Formula (3.9) is valid for any $\gamma \in(0,1)$ by continuity.

## 4. $Q$-OPERATOR $Q_{z}$

In this section we construct a $Q$-operator $Q_{z}$ for the Sekiguchi partial differential operators $\left\{H_{i}\right\}$ (2.13). The operator $Q_{z}$ is described as an integral operator with a kernel expressed in terms of elementary functions and satisfies the defining conditions (1.2)-(1.4), proved in this section, and (1.5), proved in the next section. Thus, the cigenvalue problem $Q_{z} P_{\lambda}^{(1 / g)}=q_{\lambda}(z) P_{\lambda}^{(1 / g)}$ can be considered as an integral equation for Jack polynomials $P_{\lambda}^{(1 / g)}$.

For $g>0, z>1$ and for an ordered set of $n$ real positive parameters $\mathbf{y}=\left(y_{1}, \ldots, y_{n}\right)$,

$$
\begin{equation*}
0<y_{1}<y_{2}<\ldots<y_{n}<\infty \tag{4.1}
\end{equation*}
$$

define the operator $Q_{z}$, acting on symmetric polynomials $p \in \mathbb{C}[\mathbf{x}]^{S_{n}}$, by the integral

$$
\begin{equation*}
\left[Q_{z} p\right](\mathbf{y})=\frac{\Gamma(n g)}{\Gamma(g)^{n}} \frac{(z-1)^{1-n g}}{\Delta_{n}(\mathbf{y}) \prod_{i=1}^{n} y_{l}^{g-1}} \int_{\Omega_{\mathbf{x}}} d \mathbf{x} \delta(\check{x}-z \check{y}) \Delta_{n}(\mathbf{x})\left[\prod_{i=1}^{n} \xi_{i}^{g-1}\right] p(\mathbf{x}) \tag{4.2}
\end{equation*}
$$

using the notation of Theorem 3.2, notably

$$
\begin{equation*}
\xi_{i}=\frac{\prod_{k=1}^{n}\left(x_{k}-y_{i}\right)}{\prod_{k \neq i}\left(y_{k}-y_{i}\right)} . \tag{4.3}
\end{equation*}
$$

By virtue of the modification (3.5) of the Dirichlet-Liouville integral, $Q_{z}$ is normalised such that it sends $p(\mathbf{x}) \equiv 1$ to 1 :

$$
\begin{equation*}
Q_{z}[1]=1 \tag{4.4}
\end{equation*}
$$

The function $\left[Q_{z} p\right](\mathbf{y})$ defined by the above integral for $\forall p \in \mathbb{C}[\mathbf{x}]^{S_{n}}$ as a realvalued function of real arguments $z$ and $\mathbf{y}$ is, in fact, a polynomial in $z$ and a symmetric polynomial in $\mathbf{y}$.

Proposition 4.1. The operator $Q_{z}$ defined by (4.2) sends $\mathbb{C}[\mathbf{x}]^{S_{n}}$ into $\mathbb{C}(g)[\mathbf{y}, z]^{S_{n}^{y}}$.
Proof. Let $\mathbf{k}=\left(k_{1}, \ldots, k_{n}\right) \in \mathbb{N}^{n}$. Extend the domain of $Q_{z}$ from $\mathbb{C}[\mathbf{x}]^{S_{n}}$ to $\mathbb{C}(\mathbf{y})[\mathbf{x}]^{S_{n}}$, assuming that $Q_{z}$ acts trivially on the $\mathbf{y}$-variables. In other words, we can allow $p$ in the formula (4.2) to depend on variables $\mathbf{y}$ in addition to $\mathbf{x}$. In particular, we can set $p=\boldsymbol{\xi}^{\mathbf{k}}$. The integral (3.5) is well suited for calculating the action of $Q_{z}$ on the monomials $\xi^{\mathbf{k}} \equiv \xi_{1}^{k_{1}} \cdots \xi_{n}^{k_{n}} \in \mathbb{C}(\mathbf{y})[\mathbf{x}]^{S_{n}}$. Substituting $p=\xi^{\mathbf{k}}$ into (4.2) and using the integral (3.5) for $\alpha_{i}=g+k_{i}$, we arrive at the following formula:

$$
\begin{equation*}
Q_{z}: \xi^{\mathbf{k}} \mapsto \boldsymbol{y}^{\mathbf{k}} \frac{(z-1)^{|\mathbf{k}|}}{(n g)_{|\mathbf{k}|}} \prod_{i=1}^{n}(g)_{k_{i}} \tag{4.5}
\end{equation*}
$$

where

$$
\begin{equation*}
(\alpha)_{k} \equiv \frac{\Gamma(\alpha+k)}{\Gamma(\alpha)}=\alpha(\alpha+1) \cdots(\alpha+k-1) \quad \forall k \in \mathbb{N} \tag{4.6}
\end{equation*}
$$

is the Pochhammer symbol.
The monomials $\xi^{k}$ form a basis in $\mathbb{C}[\mathbf{x}]^{S_{n}}$. To show this, it is sufficient to express the elementary symmetric functions $e_{i}(\mathbf{x}), i=1, \ldots, n(\operatorname{cf}(2.5))$ in terms of $\xi$, for any symmetric polynomial in $\mathbf{x}$ is uniquely expanded into the powers $E_{\lambda}(\mathbf{x})=e_{1}^{\lambda_{1}-\lambda_{2}}(\mathbf{x}) e_{2}^{\lambda_{2}-\lambda_{3}}(\mathbf{x}) \cdots e_{n}^{\lambda_{n}}(\mathbf{x})$ (see section 2). Introducing the generating function $w_{x}(t)$ for $\left\{e_{i}(\mathbf{x})\right\}$,

$$
\begin{equation*}
w_{x}(t)=\prod_{j=1}^{n}\left(t-x_{j}\right)=t^{n}+\sum_{i=1}^{n}(-1)^{i} t^{n-i} e_{i}(\mathbf{x}) \tag{4.7}
\end{equation*}
$$

and using the formula (3.13) for the rational function $R(t)=w_{x}(t) / w_{y}(t)$, we get

$$
\begin{equation*}
w_{x}(t)=w_{y}(t) R(t)=w_{y}(t)-\sum_{i=1}^{n} \xi_{i} \frac{w_{y}(t)}{t-y_{i}} . \tag{4.8}
\end{equation*}
$$

Expanding (4.8) in powers of $t$, we obtain the expressions for $\left\{e_{i}(\mathbf{x})\right\}$ in terms of $\xi:$

$$
\begin{equation*}
e_{i}(\mathbf{x})=e_{i}(\mathbf{y})+\sum_{j=1}^{n} \xi_{j}\left[e_{i-1}(\mathbf{y})\right]_{y_{j}=0} \tag{4.9}
\end{equation*}
$$

We can give the following algorithm for calculating $\left[Q_{z} p\right](\mathbf{y})$ for an arbitrary symmetric polynomial $p \in \mathbb{C}[\mathbf{x}]^{S_{n}}$ :
(1) express $p(\mathbf{x})$ as a polynomial in $\left\{e_{i}(\mathbf{x})\right\}$,
(2) substitute the expressions (4.9) for $\left\{e_{i}(\mathbf{x})\right\}$ in terms of $\left\{e_{j}(\mathbf{y})\right\}$ and $\xi$,
(3) expand the resulting polynomial in monomials $\xi^{k}$,
(4) replace each monomial $\xi^{\mathbf{k}}$ with the right hand side of (4.5).

The result $\left[Q_{z} p\right](\mathbf{y})$ is obviously a polynomial in $\mathbf{y}$ and $z$ and a rational function in $g$. Any permutation of the $\mathbf{y}$-variables, $\sigma: y_{i} \mapsto y_{\sigma_{i}}$, by (3.6), also sends $\xi_{i}$ to $\xi_{\sigma_{i}}$. The right hand side of the (4.9) is therefore invariant under simultaneous permutations $\sigma: y_{i} \mapsto y_{\sigma_{i}}$ and $\xi_{i} \mapsto \xi_{\sigma_{i}}$. Using (4.5), we conclude that the polynomial $\left[Q_{z} p\right](\mathbf{y})$ is symmetric in $\mathbf{y}$.

Remark 4.1. Let us mention another convenient variant of the above algorithm. After the substitution $\xi_{j}=\eta_{j} y_{j}$, the expression (4.9) for $e_{i}(\mathbf{x})$ becomes homogeneous in $\mathbf{y}$ :

$$
\begin{equation*}
e_{i}(\mathbf{x})=\sum_{1 \leq k_{1}<\ldots<k_{i} \leq n}\left(1+\eta_{k_{1}}+\ldots+\eta_{k_{i}}\right) y_{k_{1}} \cdots y_{k_{i}} . \tag{4.10}
\end{equation*}
$$

We can use (4.10) instead of (4.9) for the step 2 of the algorithm, and then use the substitution

$$
\begin{equation*}
B_{g}: \boldsymbol{\eta}^{\mathbf{k}} \mapsto \frac{(z-1)^{|\mathbf{k}|}}{(n g)_{|\mathbf{k}|}} \prod_{i=1}^{n}(g)_{k_{i}}, \tag{4.11}
\end{equation*}
$$

instead of (4.5), for the step 4.
Remark 4.2. Notice also that the polynomiality of $Q_{z} \xi^{k}$ in $z$ (4.5) ensures that the operator $Q_{z}$, although initially defined for the real values $z>1$, can now be analytically continued to the whole of the complex plane, $z \in \mathbb{C}$.

Formula (4.2) is not the only way to realise $Q_{z}$ as an integral operator. An alternative description of $Q_{z}$ can be obtained from Theorem 3.3.

For $\gamma \in(0, \pi)$ and for an ordered set of real variables $\mathbf{v}=\left(v_{1}, \ldots, v_{n}\right)$ satisfying

$$
v_{1}<v_{2}<\ldots<v_{n}<\pi+v_{1},
$$

we define the operator $\widetilde{Q}_{\gamma}$ acting on a symmetric polynomial $p \in \mathbb{C}[\mathbf{x}]^{S_{n}}$ by the integral

$$
\begin{align*}
& {\left[\widetilde{Q}_{\gamma} p\right](\mathbf{v})=\frac{\Gamma(n g)}{\Gamma(g)^{n}} \frac{(\sin \gamma)^{1-n g}}{\prod_{i<j} \sin \left(v_{j}-v_{i}\right)}}  \tag{4.12}\\
& \times \int_{\Omega_{\mathbf{u}}^{T}} d \mathbf{u} \delta(|\mathbf{u}|-|\mathbf{v}|-\gamma)\left[\prod_{i<k} \sin \left(u_{k}-u_{j}\right)\right]\left[\prod_{j=1}^{n}\left(\xi_{j}^{T}\right)^{g-1}\right] p(\varepsilon(\mathbf{u})),
\end{align*}
$$

using the notation of Theorem 3.3 and the map $\varepsilon$ from (2.21).

Proposition 4.2. Let

$$
\begin{equation*}
\mathbf{x}=\varepsilon(\mathbf{u}), \quad \mathbf{y}=\varepsilon(\mathbf{v}), \quad z=\varepsilon(\gamma) . \tag{4.13}
\end{equation*}
$$

Then $\left[\widetilde{Q}_{\gamma} p\right](\mathbf{y}) \in \mathbb{C}(g)[\mathbf{y}, z]^{S_{n}^{y}}$ and, moreover, $\widetilde{Q}_{\gamma}$ coincides with $Q_{z}$ as operators from $\mathbb{C}[\mathbf{x}]^{S_{n}}$ to $\mathbb{C}[\mathbf{y}]^{S_{n}}$.

Proof. Substituting $p(\varepsilon(\mathbf{u}))=\left(\xi^{T}\right)^{\mathbf{k}}$ into (4.12) and using the integral (3.9), one obtains the action

$$
\begin{equation*}
\widetilde{Q}_{\gamma}:\left(\xi^{T}\right)^{\mathbf{k}} \mapsto \frac{(\sin \gamma)^{|\mathbf{k}|}}{(n g)_{|\mathbf{k}|}} \prod_{i=1}^{n}(g)_{k_{i}}, \tag{4.14}
\end{equation*}
$$

which is similar to (4.5). Comparing expressions (3.6) for $\xi_{i}$ and (3.10) for $\xi_{i}^{T}$ and using substitutions (4.13), we obtain the relation

$$
\begin{equation*}
\xi_{j}=\xi_{j}^{T} \cdot 2 i y_{j} e^{i \gamma} \tag{4.15}
\end{equation*}
$$

which identifies the action (4.5) of $Q_{z}$ on the monomials $\xi^{k}$ and the action (4.14) of $\widetilde{Q}_{\gamma}$ on the monomials $\left(\xi^{T}\right)^{\mathbf{k}}$, and therefore on polynomials $p \in \mathbb{C}[\mathbf{x}]^{S_{n}}$. Hence, $Q_{z}$ and $\widetilde{Q}_{\gamma}$ define two integral realisations of the same operator acting from $\mathbb{C}[\mathbf{x}]^{S_{n}}$ to $\mathbb{C}[\mathbf{y}]^{S_{n}}$.

The integral formula (4.2) will be our main tool when working with the $Q$ operator. The trigonometric representation (4.12) will, however, be required for proving the conjugation properties of $Q_{z}$ (cf Proposition 4.4 below). In what follows, we shall identify the source space $\mathbb{C}[\mathbf{x}]^{S_{n}}$ and the target space $\mathbb{C}[\mathbf{y}]^{S_{n}}$ of $Q_{z}$ and think of $Q_{z}$ as an operator in $\mathbb{C}[\mathbf{x}]^{S_{n}}$.

Proposition 4.3. Let $\hat{e}_{n}$ be the multiplication operator acting in $\mathbb{C}[\mathbf{x}]^{S_{n}}$ as $\hat{e}_{n}: p(\mathbf{x}) \mapsto e_{n}(\mathbf{x}) p(\mathbf{x})$. Then the following operator relation holds:

$$
\begin{equation*}
Q_{z} \hat{e}_{n}=z \hat{e}_{n} Q_{z} \tag{4.16}
\end{equation*}
$$

Proof. For $z>1$, the statement follows from the observation that $Q_{z}$ is realised
as the integral operator (4.2) whose kernel contains $\delta\left(e_{n}(\mathbf{x})-z e_{n}(\mathbf{y})\right)$. Then the result is extended by analyticity to $z \in \mathbb{C}$.

The following Theorem is the main result of this section, because it states the defining properties (1.2)-(1.4) of the introduced $Q$-operator.

Theorem 4.1. Jack polynomials are the eigenfunctions of the operator $Q_{z}$ :

$$
\begin{equation*}
\left[Q_{z} P_{\lambda}^{(1 / g)}\right](\mathbf{x})=q_{\lambda}(z) P_{\lambda}^{(1 / g)}(\mathbf{x}), \quad q_{\lambda}(z) \in \mathbb{C}(g)[z] \tag{4.17}
\end{equation*}
$$

The idea of the proof is to show that the matrix of $Q_{z}$ in the basis of Jack polynomials is both symmetric and triangular, and therefore diagonal. The symmetry is cstablished by Proposition 4.4, the triangularity by Proposition 4.5.

Proposition 4.4. The operator $Q_{z}$ possesses the conjugation property

$$
\begin{equation*}
Q_{z}^{\dagger}=Q_{\bar{z}} \tag{4.18}
\end{equation*}
$$

with respect to the Hermitian form (2.23).

Proof. We shall use the representation of the $Q$-operator as $\widetilde{Q}_{\gamma}$ given by (4.12). To begin with, let us prove that

$$
\begin{equation*}
\left\langle f, \widetilde{Q}_{\gamma} p\right\rangle=\left\langle\widetilde{Q}_{\pi-\gamma} f, p\right\rangle \quad \forall f, p \in \mathbb{C}[\mathbf{x}]^{S_{n}}, \quad \gamma \in(0, \pi) \tag{4.19}
\end{equation*}
$$

For our present purposes it is convenient to think that, similarly to (2.24), the variables $\mathbf{u}, \mathbf{v}$ in (4.12) belong to the torus $T_{n}=\mathbb{R}^{n} / \pi \mathbb{Z}^{n}$ and all functions of $\mathbf{u}, \mathbf{v}$, including delta-function, are $\pi$-periodic. In particular, we can assume that all the sine functions in (4.12) take their arguments in $(0, \pi)$ or, equivalently, replace the sines by their absolute values.

Keeping that in mind and using (2.23) and (4.12) we obtain

$$
\begin{equation*}
\left\langle f, \widetilde{Q}_{\gamma} p\right\rangle=\int_{T_{\mathbf{u}, \mathbf{v}}} d \mathbf{u} d \mathbf{v} \overline{f(\varepsilon(\mathbf{v}))} \mathcal{Q}_{\gamma}(\mathbf{v}, \mathbf{u}) p(\varepsilon(\mathbf{u})) \tag{4.20}
\end{equation*}
$$

where

$$
\begin{equation*}
T_{\mathbf{u}, \mathbf{v}}=\left\{\mathbf{u}, \mathbf{v} \in \mathbb{R}^{n} / \pi \mathbb{Z}^{n} \mid u_{j} \in\left(v_{j}, v_{j+1}\right), \quad v_{j} \in\left(u_{j-1}, u_{j}\right)\right\} \tag{4.21}
\end{equation*}
$$

(using the convention $j+n \equiv j$ ) and

$$
\begin{align*}
\mathcal{Q}_{\gamma}(\mathbf{v}, \mathbf{u})= & (\sin \gamma)^{1-n g} \frac{\Gamma(n g)}{\Gamma(g)^{n}} \delta(|\mathbf{u}|-|\mathbf{v}|-\gamma) \\
& \times \prod_{j<k}\left|\sin \left(v_{k}-v_{j}\right) \sin \left(u_{k}-u_{j}\right)\right| \prod_{j, k}\left|\sin \left(u_{k}-v_{j}\right)\right|^{g-1} . \tag{4.22}
\end{align*}
$$

Performing the following change of variables:

$$
\begin{equation*}
u_{j} \mapsto u_{j}^{\prime}=v_{j+1}, \quad v_{j} \mapsto v_{j}^{\prime}=u_{j} \tag{4.23}
\end{equation*}
$$

and observing that $T_{\mathbf{u}, \mathbf{v}}=T_{\mathbf{u}^{\prime}, \mathbf{v}^{\prime}}$ and $\mathcal{Q}_{\gamma}(\mathbf{v}, \mathbf{u})=\mathcal{Q}_{\pi-\gamma}\left(\mathbf{v}^{\prime}, \mathbf{u}^{\prime}\right)$ we transform (4.20) into ( $\left.\widetilde{Q}_{\pi-x} f, p\right)$.

Having thus proved that $\widetilde{Q}_{\gamma}^{\dagger}=\widetilde{Q}_{\pi-\gamma}$ for $\gamma \in(0, \pi)$, we extend this result by analyticity to $\widetilde{Q}_{\gamma}^{\dagger}=\widetilde{Q}_{\pi-\bar{\gamma}}$ for $\gamma \in \mathbb{C}$. Due to the relation $z=e^{2 i \gamma}(\operatorname{cf}(4.13))$, the involution $\gamma \mapsto \pi-\bar{\gamma}$ corresponds to $z \mapsto \bar{z}$, hence (4.18).

Proposition 4.5. The matrix of the operator $Q_{z}$ between any two of the three bases, $m_{\lambda}(2.4), E_{\lambda}(2.6)$ or $P_{\lambda}^{(1 / g)}$, is triangular with respect to the dominance partial ordering. For example,

$$
\begin{equation*}
Q_{z} E_{\lambda}=\sum_{\mu \leq \lambda} q_{\lambda \mu}(z, g) m_{\mu} \tag{4.24}
\end{equation*}
$$

Proof. Since the three bases, $\left\{m_{\lambda}, E_{\lambda}, P_{\lambda}^{(1 / g)}\right\}$, are mutually triangular, it is sufficient to prove only the expansion (4.24).

According to the algorithm explained in Remark 4.1, in order to calculate $Q_{z} E_{\lambda}$ we have to substitute into (2.6) the expressions (4.10) for $e_{j}$ in terms of $\eta_{j}$ and $y_{j}$, expand the brackets and transform the products of $\eta_{j}$ by the formula (4.11).

It follows from (4.10) that $Q_{z}$ maps $E_{\lambda}$ into a polynomial consisting of the same monomials in $y_{j}$ as $E_{\lambda}$ in $x_{j}$. The only difference is the presence of the variables $\eta_{j}$ in the coefficients producing a nontrivial dependence on $g$. Since the expansion of $E_{\lambda}$ into $m_{\mu}$ is triangular (2.7), so is the expansion of $Q_{z} E_{\lambda}$.

Proof of Theorem 4.1. Let $\mathcal{Q}_{\lambda \mu} \equiv\left(Q_{z} P_{\lambda}^{(1 / g)}, P_{\mu}^{(1 / g)}\right)$. It follows from the triangularity property (Proposition 4.5) that $\mathcal{Q}_{\lambda \mu} \neq 0$ only for $\lambda \succeq \mu$. On the other hand, from the conjugation formula (4.18) and the orthogonality of the basis $P_{\mu}^{(1 / g)}$ it follows that $\left(\mathcal{Q}_{\lambda \mu} \neq 0\right) \Longrightarrow\left(\mathcal{Q}_{\mu \lambda} \neq 0\right)$, therefore $\mu \succeq \lambda$. However, $\lambda \succeq \mu$ and $\mu \succeq \lambda$ implies $\lambda=\mu$, hence (4.17). The eigenvalue $q_{\lambda}(z)$ is a polynomial in $z$ since $\left[Q_{z} P_{\lambda}^{(1 / g)}\right](\mathbf{x}) \in \mathbb{C}(g)[\mathbf{x}, z]^{S_{n}^{x}}$ by Proposition 4.1.

Remark 4.3. In the quasi-classical limit, $g \rightarrow \infty$, the operator $Q_{z}$ turns into the corresponding Bäcklund transformation for the Calogero-Sutherland model (see [23] for details).
5. EIGENVALUES OF $Q_{z}$

Here we study the eigenvalues of the operator $Q_{z}$, that is the polynomials $q_{\lambda}(z) \in \mathbb{C}(g)[z]$ introduced in the previous section (cf (4.17)).

First, we derive a representation for $q_{\lambda}(z)$ as a finite multiple sum by making use of the explicit formula for the action of $Q_{z}$ on a polynomial basis. Then, we convert the obtained expression into another finite multiple sum, which results from a previously known formula (cf [20,22]) for the separated polynomials $q_{\lambda}(z)$ in terms of the hypergeometric function ${ }_{n} F_{n-1}(z)$. Hinally, we write down
the ordinary differential equation of order $n$ for $q_{\lambda}(z)$, which serves as the Baxter equation (1.5) for our $Q$-operator $Q_{z}$.

By Proposition 4.5, the eigenvalue $q_{\lambda}(z)$ can be determined as the diagonal matrix element of $Q_{z}$ in the basis $E_{\lambda}$ :

$$
\begin{equation*}
Q_{z} E_{\lambda}=q_{\lambda}(z) E_{\lambda}+\sum_{\mu<\lambda} b_{\lambda \mu} E_{\mu} \tag{5.1}
\end{equation*}
$$

To calculate $Q_{z} E_{\lambda}$ we shall apply the algorithm described in Remark 4.1. Taking the diagonal element corresponds to replacing $e_{j}(\mathbf{x})$ by formula (4.10) and taking the coefficient at the monomial $\mathbf{y}^{\lambda}$. Introducing the operator $B_{g}$ : $\mathbb{C}[\boldsymbol{\eta}] \mapsto \mathbb{C}(g)$ acting on the monomials $\boldsymbol{\eta}^{\mathbf{k}}$ by the formula (4.11) we arrive at the following expression:

$$
\begin{equation*}
q_{\lambda}(z)=B_{g}\left[\prod_{i=1}^{n}\left(1+\eta_{1}+\ldots+\eta_{i}\right)^{\lambda_{i, i+1}}\right] \tag{5.2}
\end{equation*}
$$

Theorem 5.1. The polynomial $q_{\lambda}(z) \in \mathbb{C}(g)[z]$ is given by the rnultiple sum

$$
\begin{equation*}
q_{\lambda}(z)-z^{\lambda_{n}} \sum_{k_{1}=0}^{\lambda_{1,2}} \cdots \sum_{k_{n-1}=0}^{\lambda_{n-1, n}} \prod_{i=1}^{n-1}(1-z)^{k_{i}} \frac{\left(-\lambda_{i, i+1}\right)_{k_{i}}}{k_{i}!} \frac{(i g)_{k_{1}+\ldots+k_{i}}}{((i+1) g)_{k_{1}+\ldots+k_{i}}} \tag{5.3}
\end{equation*}
$$

Proof. Expanding the product in (5.2) we obtain

$$
\begin{equation*}
q_{\lambda}(z)=\sum_{k_{1}=0}^{\lambda_{1,2}} \cdots \sum_{k_{n}=0}^{\lambda_{n, n+1}}\left[\prod_{j=1}^{n}\binom{\lambda_{j, j \mid 1}}{k_{j}}\right] \frac{(z-1)^{|\mathbf{k}|}}{(n g)_{|\mathbf{k}|}} c_{\mathbf{k}} \tag{5.4}
\end{equation*}
$$

with

$$
\begin{align*}
c_{\mathbf{k}} & =\frac{(n g)_{|\mathbf{k}|}}{(z-1)^{|\mathbf{k}|}} B_{g}\left[\prod_{j=1}^{n}\left(\eta_{1}+\ldots+\eta_{j}\right)^{k_{j}}\right]  \tag{5.5}\\
& =\left(D_{1} \otimes \cdots \otimes D_{n}\right)\left[\prod_{j=1}^{n}\left(\eta_{1}+\ldots+\eta_{j}\right)^{k_{j}}\right]
\end{align*}
$$

where the operators $D_{j}: \mathbb{C}\left[\eta_{j}\right]_{\mapsto}(g)$ are defined as follows $D_{j}: \eta_{j}^{k_{j}} \mapsto(g)_{k_{j}}$.
Lemma 5.1. The coefficients $c_{\mathbf{k}}$ (5.5) are

$$
\begin{equation*}
c_{\mathbf{k}}=\prod_{j=1}^{n}\left(j g+k_{1}+\ldots+k_{j-1}\right)_{k_{j}}=(n g)_{|\mathbf{k}|} \prod_{j=1}^{n-1} \frac{(j g)_{k_{1}+\ldots+k_{j}}}{((j+1) g)_{k_{1}+\ldots+k_{j}}} \tag{5.6}
\end{equation*}
$$

The formula (5.3) is then obtained by substituting (5.6) into (5.4) and evaluating the sum over $k_{n}$.

Proof of Lemma 5.1. is given by induction in $n$. When $n=1$ formulae (5.5) and
(5.6) give the same value $(g)_{k_{1}}$ for $c_{k_{1}}$. It is sufficient to show that $c_{k_{1}, \ldots, k_{n}}$ given by (5.5) satisfies the recurrence relation

$$
\begin{equation*}
c_{k_{1}, \ldots, k_{n}}=c_{k_{1}, \ldots, k_{n-1}} \cdot\left(n g+k_{1}+\ldots+k_{n-1}\right)_{k_{n}} \tag{5.7}
\end{equation*}
$$

Expanding the factor $\left(\left(\eta_{1}+\ldots+\eta_{n-1}\right)+\eta_{n}\right)^{k_{n}}$ in (5.5) we get

$$
\begin{align*}
c_{k_{1}, \ldots, k_{n}}= & \left(D_{1} \otimes \cdots \otimes D_{n}\right)\left[\left(\prod_{j=1}^{n-1}\left(\eta_{1}+\ldots+\eta_{j}\right)^{k_{j}}\right)\left(\eta_{1}+\ldots+\eta_{n}\right)^{k_{n}}\right] \\
= & \sum_{m=0}^{k_{n}}\binom{k_{n}}{m}\left(D_{1} \otimes \cdots \otimes D_{n-1}\right)\left[\left(\eta_{1}+\ldots+\eta_{n-1}\right)^{k_{n-1}+m}\right. \\
& \left.\times \prod_{j=1}^{n-2}\left(\eta_{1}+\ldots+\eta_{j}\right)^{k_{j}}\right] \cdot D_{n}\left[\eta_{n}^{k_{n}-m}\right]  \tag{5.8}\\
= & \sum_{m=0}^{k_{n}}\binom{k_{n}}{m} c_{k_{1}, \ldots, k_{n-2}, k_{n-1}+m}(g)_{k_{n}-m} \\
= & c_{k_{1}, \ldots, k_{n-1}} \sum_{m=0}^{k_{n}}\binom{k_{n}}{m}\left((n-1) g+k_{1}+\ldots+k_{n-1}\right)_{m}(g)_{k_{n}-m}
\end{align*}
$$

To obtain (5.7) it remains to use the summation formula

$$
\begin{equation*}
\sum_{m=0}^{k}\binom{k}{m}(s)_{m}(g)_{k-m}=(s+g)_{k} \tag{5.9}
\end{equation*}
$$

for $k=k_{n}$ and $s=(n-1) g+k_{1}+\ldots+k_{n-1}$ which is easily proved by comparing the coefficients with powers of $t$ in the identity $(1-t)^{-s}(1-t)^{-g}=$ $(1-t)^{-s-g}$.

In [20] (see also [22]) it was conjectured, and then proved for $n=2,3,4$ (cf $[20,22,26,27])$, that Jack polynomials $P_{\lambda}^{(1 / g)}\left(x_{1}, \ldots, x_{n}\right)$ can be factorised into a product of the separated polynomials $f_{\lambda}(z)$ defined in terms of the hypergeometric function ${ }_{n} F_{n-1}(z)$ as follows:

$$
\begin{align*}
& f_{\lambda}(z)=z^{\lambda_{n}}(1-z)^{1-n g}{ }_{n} F_{n-1}\binom{a_{1}, a_{2}, \ldots, a_{n}}{b_{1}, \ldots, b_{n-1}},  \tag{5.10}\\
& a_{i}=\lambda_{n, i}+1-(n-i+1) g, \quad b_{i}=a_{i}+g . \tag{5.11}
\end{align*}
$$

Theorem 5.2. The function $f_{\lambda}(z)$ is a polynomial given by the multiple sum

$$
\begin{align*}
f_{\lambda}(z)= & z^{\lambda_{n}} \sum_{k_{1}=0}^{\lambda_{1,2}} \cdots \sum_{k_{n-1}=0}^{\lambda_{n-1} n} \prod_{i=1}^{n-1}(1-z)^{\lambda_{i, i 11}}\left(\frac{z}{z-1}\right)^{k_{i}} \frac{\left(-\lambda_{i, i+1}\right)_{k_{i}}}{k_{i}!}  \tag{5.12}\\
& \times \frac{\left(1-(n-i+1) g-\lambda_{i, n}\right)_{k_{i}+\ldots+k_{n-1}}}{\left(1-(n-i) g-\lambda_{i, n}\right)_{k_{i}+\ldots+k_{n-1}}} .
\end{align*}
$$

Proof. Representation (5.12) for the separated polynomial $f_{\lambda}(z)$ follows from
the observation made in [22] that an explicit finite multiple sum for the polynomial given by (5.10) can be obtained by iterating Fox's formula [10],

$$
\begin{align*}
& { }_{p} F_{p-1}\left(\begin{array}{c}
a_{1} \ldots, a_{p-1}, b_{p-1}+m \\
h_{1}, \ldots, b_{p 1}
\end{array} ; z\right)=\sum_{j=0}^{m}(-z)^{j} \frac{(-m)_{j}}{j!} \\
& \times\left[\prod_{i=1}^{p-1} \frac{\left(a_{i}\right)_{j}}{\left(b_{i}\right)_{j}}\right]{ }_{p-1} F_{p-2}\left(\begin{array}{l}
a_{1}+j, \ldots, a_{p-1}+j \\
b_{1}+j, \ldots, b_{p-2}+j
\end{array} ; z\right), \tag{5.13}
\end{align*}
$$

which expresses the hypergeometric function ${ }_{p} F_{p-1}$ on the left, for any nonnegative integer $m$, as a finite sum of lower series.

Noticing that $a_{i+1}=b_{i}+\lambda_{i, i+1}$ for $i=1, \ldots, n-1$ in (5.11) and using the binomial theorem, ${ }_{1} F_{0}\left({ }_{a}^{a} ; z\right)=(1-z)^{-a}$, we apply (5.13) to (5.10) consecutively for $p=n-1, \ldots, 2$ and derive (5.12).

Theorem 5.3. The polynomials $f_{\lambda}(z)$ and $q_{\lambda}(z)$ are proportional

$$
\begin{equation*}
f_{\lambda}(z)=\beta_{\lambda} q_{\lambda}(z) \tag{5.14}
\end{equation*}
$$

where

$$
\begin{equation*}
\beta_{\lambda}=\prod_{i=1}^{n-1} \beta_{\lambda}^{(i)}, \quad \beta_{\lambda}^{(i)}=\frac{((n-i+1) g)_{\lambda_{i, n}}}{((n-i) g)_{\lambda_{i, n}}} \tag{5.15}
\end{equation*}
$$

Proof. We shall start with the expression (5.12) for $f_{\lambda}(z)$. After the change of the variable $z \mapsto 1-z$ we can rewrite (5.12) as

$$
\begin{equation*}
f_{\lambda}(1-z)=(1-z)^{\lambda_{n}} \varphi_{\lambda}^{(n-1)}(z) \tag{5.16}
\end{equation*}
$$

where $\varphi_{\lambda}^{(i)}\left(z ; k_{i+1}, \ldots, k_{n-1}\right)$ are defined recursively for $i=1, \ldots, n-1$ by $\varphi_{\lambda}^{(0)}(z$; $\left.k_{1}, \ldots, k_{n-1}\right) \equiv 1$ and

$$
\begin{align*}
& \varphi_{\lambda}^{(i)}\left(z ; k_{i+1}, \ldots, k_{n-1}\right)=z^{\lambda_{i, i+1}} \sum_{k_{i}=0}^{\lambda_{i, i+1}}\left(\frac{z-1}{z}\right)^{k_{i}} \frac{\left(-\lambda_{i, i+1}\right)_{k_{i}}}{k_{i}!}  \tag{5.17}\\
& \times \frac{\left(1-(n-i+1) g-\lambda_{i, n}\right)_{k_{i}+\ldots+k_{n-1}}^{\left(1-(n-i) g-\lambda_{i, n}\right)_{k_{i}+\ldots+k_{n-1}}^{(i-1)}} \varphi_{\lambda}\left(z ; k_{i}, \ldots, k_{n-1}\right) .}{} .
\end{align*}
$$

Lemma 5.2.

$$
\begin{align*}
& \varphi_{\lambda}^{(i)}\left(z ; k_{i+1}, \ldots, k_{n-1}\right)=\beta_{\lambda}^{(i)} \frac{I^{\prime}((n-i+1) g)}{\Gamma(g) \Gamma((n-i) g)}  \tag{5.18}\\
& \times \int_{0}^{1} d v v^{i g-1}(1-v)^{(n-i) g-1+\lambda_{i+1, n}-k_{i+1}-\ldots-k_{n-1}}(1-z v)^{\lambda_{i, i+1}} \Phi_{\lambda}^{(i-1)}(z v),
\end{align*}
$$

where $\Phi_{\lambda}^{(i)}(z)$ for $i=0, \ldots, n-2$ are defined recursively by $\Phi_{\lambda}^{(0)}(z) \equiv 1$ and

$$
\begin{equation*}
\Phi_{\lambda}^{(i)}(z)=\int_{0}^{1} d u u^{i g-1}(1-u)^{g-1}(1-z u)^{\lambda_{i, i+1}} \Phi_{\lambda}^{(i-1)}(z u) \tag{5.19}
\end{equation*}
$$

Proof is done by induction. For $i=1$, formula (5.17) gives

$$
\begin{align*}
& \varphi_{\lambda}^{(1)}\left(z ; k_{2}, \ldots, k_{n-1}\right)=z^{\lambda_{1,2}} \frac{\left(1-n g-\lambda_{1, n}\right)_{k_{2}+\ldots+k_{n-1}}}{\left(1-(n-1) g-\lambda_{1, n}\right)_{k_{2}+\ldots+k_{n-1}}}  \tag{5.20}\\
& \times{ }_{2} F_{1}\left(\begin{array}{c}
-\lambda_{1,2}, \theta_{1} \\
\theta_{1}+g
\end{array} ; \frac{z-1}{z}\right),
\end{align*}
$$

where $\theta_{1}=1-n g-\lambda_{1, n}+k_{2}+\ldots+k_{n-1}$. Using the well-known identity for the terminating Gauss hypergeometric function,

$$
{ }_{2} F_{1}\left(\begin{array}{c}
-p, b  \tag{5.21}\\
c
\end{array} ; z\right)=\frac{(b)_{p}}{(c)_{p}}(1-z)^{p}{ }_{2} F_{1}\left(\begin{array}{c}
-p, c-b \\
-p+1-b
\end{array} ; \frac{1}{1-z}\right),
$$

and then the integral representation (see, e.g. [9]),

$$
{ }_{2} F_{1}\left(\begin{array}{c}
a, b  \tag{5.22}\\
c
\end{array} ; z\right)=\frac{\Gamma(c)}{\Gamma(b) \Gamma(c-b)} \int_{0}^{1} d u u^{b-1}(1-u)^{c-b-1}(1-z u)^{-a}
$$

we arrive at the formula (5.18) for $i=1$.
Supposing that the statement is true for $i-1$, we substitute the expression (5.18) for $\varphi_{\lambda}^{(i-1)}$ in terms of $\Phi_{\lambda}^{(i-2)}$ into (5.17) and get the integral

$$
\begin{align*}
& \varphi_{\lambda}^{(i)}\left(z ; k_{i+1}, \ldots, k_{n-1}\right)=z^{\lambda_{i, i+1}} \\
& \times \int_{0}^{1} d v v^{i g \quad 1}(1-v)^{(n-i+1) g-1+\lambda_{i, n}-k_{i+1}-\ldots-k_{n-1}}(1-z v)^{\lambda_{i-1, j}} \Phi_{\lambda}^{(i-2)}(z v) S_{i} \tag{5.23}
\end{align*}
$$

where $S_{i}$ is the sum

$$
\begin{align*}
S_{i} & =\sum_{k_{i}=0}^{\lambda_{i, i+1}}\left(\frac{z-1}{z(1-v)}\right)^{k_{i}} \frac{\left(-\lambda_{i, i+1}\right)_{k_{i}}}{k_{i}!} \frac{\left(1-(n-i+1) g-\lambda_{i, n}\right)_{k_{i}+\ldots+k_{n-1}}}{\left(1-(n-i) g-\lambda_{i, n}\right)_{k_{i}+\ldots+k_{n-1}}}  \tag{5.24}\\
& \left.=\frac{\left(1-(n-i+1) g-\lambda_{i, n}\right)_{k_{i+1}+\ldots+k_{n-1}}{ }_{2} F_{1}\left(\begin{array}{c}
-\lambda_{i, i+1}, \theta_{i} \\
\theta_{i}+g
\end{array} ; \frac{(z-1)}{z\left(1-(n-i) g-\lambda_{i, n}\right)_{k_{i+1}+\ldots+k_{n-1}}}\right)}{(1-(n-v)}\right)
\end{align*}
$$

and $\theta_{i}=1-(n-i+1) g-\lambda_{i, n}+k_{i+1}+\ldots+k_{n-1}$. Using again the transformation (5.21) and then the integral representation (5.22), after some algebra we transform $S_{i}$ to the following form:

$$
\begin{align*}
S_{i} & =\beta_{\lambda}^{(i)} \frac{\Gamma((n-i+1) g)}{\Gamma(g) \Gamma((n-i) g)}(1-v)^{-\lambda_{i, i+1}}  \tag{5.25}\\
& \times \int_{0}^{1} d t t^{g-1}(1-t)^{(n-i) g-1+\lambda_{i+1, n}-k_{i+1} \cdots-k_{n-1}}[1-y(v+t(1-v))]^{\lambda_{i, i+1}}
\end{align*}
$$

Substituting $S_{i}$ from (5.25) into (5.23) we obtain an expression for $\varphi_{\lambda}^{(i)}$ as a double integral, in the variables $v$ and $t$. Making the change of variables $(v, t) \mapsto(v, u=v+t-v t)$ followed by $(u, v) \mapsto(u, w=v / u)$ we obtain for $\varphi_{\lambda}^{(i)}$ an expression as an integral in $u$ and $w$. The integration domains are changed respectively from $v, t \in[0,1]$ to $0 \leq v \leq u \leq 1$, and finally to $u, w \in[0,1]$. The result reads

$$
\begin{align*}
& \varphi_{\lambda}^{(i)}\left(z ; k_{i+1}, \ldots, k_{n-1}\right)=\beta_{\lambda}^{(i)} \frac{\Gamma((n-i+1) g)}{\Gamma(g) \Gamma((n-i) g)} \\
& \times \int_{0}^{1} d u u^{i g-1}(1-u)^{(n-i) g-1+\lambda_{i+1, n}-k_{i+1}-\ldots-k_{n-1}}(1-z u)^{\lambda_{i, i+1}}  \tag{5.26}\\
& \times \int_{0}^{1} d w w^{(i-1) g-1}(1-w)^{g-1}(1-z u w)^{\lambda_{i-1, i}} \Phi_{\lambda}^{(i-2)}(z u w)
\end{align*}
$$

The integral over $w$ is evaluated with the help of (5.19) producing $\Phi_{\lambda}^{(i-1)}(z u)$, and we recover formula (5.18), thus completing the induction step.

Iterating integrals (5.19) and using (5.16) we obtain the following representation for $f_{\lambda}(1-z)$ as a multiple integral:

$$
\begin{align*}
& f_{\lambda}(1-z)=(1-z)^{\lambda_{n}} \beta_{\lambda} \frac{\Gamma(n g)}{\Gamma(g)^{n}} \int_{0}^{1} d u_{1} \cdots \int_{0}^{1} d u_{n-1} \\
& \times \prod_{i=1}^{n-1} u_{i}^{i g-1}\left(1-u_{i}\right)^{g-1}\left(1-z u_{i} \cdots u_{n-1}\right)^{\lambda_{i, j+1}} \tag{5.27}
\end{align*}
$$

Expanding the binomials $\left(1-z u_{i} \cdots u_{n-1}\right)^{\lambda_{i l+1}}$ we get a sum of products of onedimensional beta-integrals in each $u_{i}$ and, after evaluating them, we recover the expression (5.3) for $q_{\lambda}(z)$, arriving thus at (5.14).

Remark 5.1. The eigenvalue $q_{\lambda}(z)$ of the $Q$-operator $Q_{z}$ is thus proportional to the function $f_{\lambda}(z)$ expressed by $(5.10)$ as a hypergeometric polynomial, hence its Baxter (or separation) equation has the form (cf, e.g., [9])

$$
\begin{equation*}
\left(z \frac{d}{d z} \prod_{i=1}^{n-1}\left(z \frac{d}{d z}+b_{i}-1\right)-z \prod_{i=1}^{n}\left(z \frac{d}{d z}+a_{i}\right)\right)\left[z^{-\lambda_{n}}(1-z)^{n g-1} f_{\lambda}(z)\right]=0 \tag{5.28}
\end{equation*}
$$

where $a_{i}=\lambda_{n, i}+1-(n-i+1) g$ and $b_{i}=a_{i}+g$.

## 6. FACTORISATION OF JACK POLYNOMIALS

In this section, the integral operator $Q_{z}$ is used to construct a factorisation of Jack polynomials $P_{\lambda}^{(1 / g)}\left(x_{1}, \ldots, x_{n}\right)$ in $n$ variables into a product of $n$ polynomials in one variable. The general construction of the separating (factorising) operator $\mathcal{S}_{n}^{(\rho)}$,

$$
\begin{equation*}
\mathcal{S}_{n}^{(\rho)}=\rho Q_{z_{1}} \cdots Q_{z_{n}} \tag{6.1}
\end{equation*}
$$

briefly described in the Introduction involves an arbitrary linear functional $\rho: \mathbb{C}[\mathbf{x}]^{S_{n}} \mapsto \mathbb{C}$. Our present task is to make the integral operator $\mathcal{S}_{n}^{(\rho)}$ as simple as possible by choosing $\rho=\rho_{0}$ in a special way. More specifically, we wish to factorise the integral operator $\mathcal{S}_{n}^{\left(\rho_{0}\right)}$ into a string of operators $\mathcal{A}_{k}$,

$$
\begin{equation*}
\mathcal{S}_{n}^{\left(\rho_{0}\right)}=\rho_{0} Q_{z_{1}} \cdots Q_{z_{n}}=\mathcal{A}_{1} \cdots \mathcal{A}_{n} \tag{6.2}
\end{equation*}
$$

possessing the property of dimension reduction in the sense that each operator
$\mathcal{A}_{k}$ acts only on $k$ variables. Any such factorisation will be called factorised separation chain or $\mathcal{A}$-chain.

Let us choose $\rho_{0}$ to be the evaluation homomorphism that returns the value of a polynomial at the point $\mathbf{x}=(1, \ldots, 1)$,

$$
\begin{equation*}
\rho_{0}: f \mapsto \rho_{0} f=f(1, \ldots, 1) \tag{6.3}
\end{equation*}
$$

or, equivalently, the integral operator whose kernel is the product of deltafunctions,

$$
\begin{equation*}
\rho_{0}(\mathbf{x})-\prod_{j=1}^{n} \delta\left(x_{j}-1\right), \quad \rho_{0} f \equiv \int d \mathbf{x} \rho_{0}(\mathbf{x}) f(\mathbf{x})-f(1, \ldots, 1) \tag{6.4}
\end{equation*}
$$

Having fixed the functional $\rho=\rho_{0}$, hereafter we shall omit $\rho$ (or $\rho_{0}$ ) from the operator notation, writing $\mathcal{S}_{n}$ to denote the corresponding separating operator. Two theorems below constitute the main result of this section and show how distinguished is the chosen $\rho_{0}$ (6.3).

Theorem 6.1. The operator $\mathcal{S}_{n}=\rho_{0} Q_{z_{1}} \cdots Q_{z_{n}}$ sends Jack polynomials into the product of separated polynomials $q_{\lambda}(z)$ defined in Section 5 ,

$$
\begin{equation*}
\mathcal{S}_{n}: P_{\lambda}^{(1 / g)}(\mathbf{x}) \mapsto c_{\lambda} \prod_{k=1}^{n} q_{\lambda}\left(z_{k}\right), \tag{6.5}
\end{equation*}
$$

the normalisation constant $c_{\lambda}$ being given by

$$
\begin{equation*}
c_{\lambda}=P_{\lambda}^{(1 / g)}(\mathbf{1}, \ldots, 1)=\prod_{1 \leq i<j \leq n} \frac{(g(j-i+1))_{\lambda_{i j}}}{(g(j-i))_{\lambda_{i j}}} . \tag{6.6}
\end{equation*}
$$

Proof. Apply the chain (6.5) of operators $Q_{z_{k}}$ to a Jack polynomial $P_{\lambda}^{(1 / g)}(\mathbf{x})$ and use the fact (4.17) that $P_{\lambda}^{(1 / g)}(\mathbf{x})$ is an eigenfunction of $Q_{z_{k}}$. Each factor $Q_{z_{k}}$ produces a desired factor $q_{\lambda}\left(z_{k}\right)$. Finally, the evaluation homomorphism $\rho_{0}(6.3)$ transforms $P_{\lambda}^{(1 / g)}(\mathbf{x})$ into the normalisation constant $c_{\lambda}(6.6)$. For the evaluation of a Jack polynomial at $\mathbf{x}=(1, \ldots, 1)$ see $[35],\left[25, \S 6,\left(6.11^{\prime}\right)\right]$ or [28].

Theorem 6.2. The operator $\mathcal{S}_{n}: \mathbb{C}[\mathbf{x}]^{S_{n}} \mapsto \mathbb{C}[\mathbf{z}]^{S_{n}}$, corresponding to the evaluation homomorphism (6.3), can be decomposed into the product of $n$ operators $\mathcal{A}_{k}$,

$$
\begin{align*}
& \mathcal{S}_{n}=\mathcal{A}_{1} \cdots \mathcal{A}_{n}  \tag{6.7}\\
& \mathcal{A}_{k}: \mathbb{C}\left[x_{1}, \ldots, x_{k}\right]^{S_{k} \mapsto \mathbb{C}\left[x_{1}, \ldots, x_{k-1}\right]^{S_{k-1}} \otimes \mathbb{C}\left[z_{k}\right], \quad k=1, \ldots, n} \tag{6.8}
\end{align*}
$$

In particular, $\mathcal{A}_{1}: \mathbb{C}\left[x_{1}\right] \mapsto \mathbb{C}\left[z_{1}\right]$. The operators $\mathcal{A}_{k}$ in (6.7) are assumed to act trivially (as unit operators) on the variables $\mathbf{z}$.

Furthermore, the operators $\mathcal{A}_{k}$ act on the restricted polynomials $P_{\lambda}^{(1 / g)}\left(x_{1}, \ldots\right.$, $\left.x_{k}, 1, \ldots, 1\right)$ as follows:

$$
\begin{equation*}
\mathcal{A}_{k}: P_{\lambda}^{(1 / g)}\left(x_{1}, \ldots, x_{k}, 1, \ldots, 1\right) \mapsto P_{\lambda}^{(1 / g)}\left(x_{1}, \ldots, x_{k-1}, 1, \ldots, 1\right) q_{\lambda}\left(z_{k}\right) \tag{6.9}
\end{equation*}
$$

The factorisation (6.7)-(6.9) possesses the property of dimension reduction
$k \mapsto k-1$. Such factorisations have been introduced in [17] when studying the inverse problem for integrable models of the $s l(2)$ class and have been given the general name factorised separation chains.

Note that the formula (6.9) is consistent with Theorem 6.1. Indeed, applying the chain (6.7) of operators $\mathcal{A}_{k}$ to the polynomial $P_{\lambda}^{(1 / g)}\left(x_{1}, \ldots, x_{n}\right)$ and using (6.9) we reproduce formula (6.5). The existence of a factorization of the form (6.7) is by no means trivial. One cannot simply define $\mathcal{A}_{k}$ by (6.9) because the restricted Jack polynomials $P_{\lambda}^{(1 / g)}\left(x_{1}, \ldots, x_{k}, 1, \ldots, 1\right)$, as polynomials of $k$ variables labelled by $n$-dimensional vector $\lambda$, are not linearly independent.

To prove Theorem 6.2 we shall describe a recursive procedure for constructing the operators $\mathcal{A}_{k}$ based on the defining formula $\mathcal{S}_{n}=\rho_{0} Q_{z_{1}} \cdots Q_{z_{n}}$. The idea is to pull the homomorphism $\rho_{0}$ through the sequence of $Q_{z_{k}}$ 's transforming at each step $Q_{z_{k}}$ into $\mathcal{A}_{k}$ and producing a new homomorphism $\rho_{k}$. Let $\mathrm{id}_{[j, k]}$ for $j \leq$ $k$ denote the identity operator in $\mathbb{C}\left[x_{j}, \ldots, x_{k}\right]^{S_{k j+1}}$.

Proposition 6.1. There exist a unique sequence of operators $\mathcal{A}_{k}$,

$$
\mathcal{A}_{k}: \mathbb{C}\left[x_{1}, \ldots, x_{k}\right]^{S_{k} \mapsto \mathbb{C}\left[x_{1}, \ldots, x_{k-1}\right]^{S_{k-1}} \otimes \mathbb{C}\left[z_{k}\right], \quad k=1, \ldots, n, ~}
$$

and a unique sequence of homomorphisms $\rho_{k}$,

$$
\rho_{k}: \mathbb{C}\left[x_{k+1}, \ldots, x_{n}\right]_{n-k_{\mapsto} \rightarrow \mathbb{C}}, \quad k=0, \ldots, n
$$

such that:
(a) $\rho_{0}: \mathbb{C}[\mathbf{x}]^{S_{n}} \mapsto \mathbb{C}$ coincides with the evaluation (6.3),
(b) the operators $\mathcal{A}_{k}$ are normalised by the condition $\mathcal{A}_{k}: 1 \mapsto 1$,
(c) the following relation holds for $k=0, \ldots, n-1$ :

$$
\begin{equation*}
\left(\mathrm{id}_{[1, k]} \otimes \rho_{k}\right) Q_{z_{k+1}}=\mathcal{A}_{k+1}\left(\mathrm{id}_{[1, k+1]} \otimes \rho_{k+1}\right) \tag{6.10}
\end{equation*}
$$

The homomorphisms $\rho_{k}$ defined in this way act on polynomials $f \in \mathbb{C}\left[x_{k+1}, \ldots\right.$, $\left.x_{n}\right]^{S_{n-k}}$ by restricting their $n-k$ arguments to 1 :

$$
\begin{equation*}
\rho_{k}: f\left(x_{k+1}, \ldots, x_{n}\right) \mapsto f(1, \ldots, 1), \quad k=0, \ldots, n-1 \tag{6.11}
\end{equation*}
$$

For $k=n$ we have simply $\rho_{n}=1$.

Proof of Theorem 6.2 follows then immediately. Applying recursively formula (6.10) to $\mathcal{S}_{n}=\rho_{0} Q_{z_{1}} Q_{z_{2}} \cdots Q_{z_{n}}$ we get $\mathcal{S}_{n}=\mathcal{A}_{1}\left(\operatorname{id}_{[1,1]} \otimes \rho_{1}\right) Q_{z_{2}} \cdots Q_{z_{n}}$ and so on, until we arrive at (6.7). Applying the identity (6.10) to a Jack polynomial $P_{\lambda}^{(1 / g)}(\mathbf{x})$ and using (6.11) we get (6.9).

Proof of Proposition 6.1 is given by induction. For $\rho_{0}$ the formula (6.11) holds by assumption. Assuming that for some $k \in[0, n-1]$ the operators $\mathcal{A}_{1}, \ldots, \mathcal{A}_{k}$ and homomorphisms $\rho_{0}, \ldots, \rho_{k}$ have been already constructed, let us consider the product $\left(\mathrm{id}_{[1, k]} \otimes \rho_{k}\right) Q_{z_{k+1}}$ and show that it factorises uniquely as $\mathcal{A}_{k+1}\left(\mathrm{id}_{[1, k+1]} \otimes \rho_{k+1}\right)$. Note that the operation $\left(\mathrm{id}_{[1, k]} \otimes \rho_{k}\right)$ produces from a polynomial $f(\mathbf{x})$ of $n$ variables the polynomial $f\left(x_{1}, \ldots, x_{k}, 1, \ldots, 1\right)$ of $k$ variables. As in Section 4, we will distinguish the variables $\mathbf{y}$ of the target space for
the operator $Q_{z_{k+1}}$ from the variables $\mathbf{x}$ of the source space. Given a polynomial $f \in \mathbb{C}[\mathbf{x}]^{S_{n}}$, we have thus to take $Q_{z_{k+1}} f \in \mathbb{C}[\mathbf{y}]^{S_{n}}$ and to set $y_{k+1}=\ldots=y_{n}=1$. We can analyse the resulting expression in two ways based on two descriptions of $Q_{z_{k+1}}$ given in Section 4: the one in terms of an integral operator and a pure algebraic one.

Let us apply first the combinatorial prescription for evaluating $Q_{z_{k+1}}$ on the elementary symmetric polynomials $e_{j}(\mathbf{x})$ given in Remark 4.1, formulae (4.10) and (4.11). Recalling formula (4.7), we introduce the generating functions $w_{x}(t)=\prod_{j=1}^{n}\left(t-x_{j}\right)$ for $e_{j}(\mathbf{x})$ and, respectively, $w_{y}(t)=\prod_{j=1}^{n}\left(t-y_{j}\right)$ for $e_{j}(\mathbf{y})$. Consider now the relation (4.8),

$$
\begin{equation*}
w_{x}(t)=w_{y}(t)-\sum_{i=1}^{n} \eta_{i} y_{i} \frac{w_{y}(t)}{t-y_{i}} \tag{6.12}
\end{equation*}
$$

and set $y_{k+1}=\ldots=y_{n}=1$. The right hand side of (6.12) is then divisible by $(t-1)^{n-k-1}$, so is the left hand side, therefore $n-k-1$ of the variables $x_{j}$ are forced to take value 1 . Due to the symmetry, the remaining free variables can be chosen as $x_{1}, \ldots, x_{k+1}$. Note that from the above the statement of the Proposition follows immediately: we have effectively transformed the operator expression $\left(\operatorname{id}_{[1, k]} \otimes \rho_{k}\right) Q_{z_{k+1}}$ to the desired form $\mathcal{A}_{k+1}\left(\operatorname{id}_{[1, k+1]} \otimes \rho_{k+1}\right)$ with some operator $\mathcal{A}_{k+1}$ acting on the variables $x_{1}, \ldots, x_{k+1}$.

We can go even further and find how $\mathcal{A}_{k+1}$ acts on polynomials in $x_{1}, \ldots, x_{k+1}$. Let

$$
w_{x}(t)=(t-1)^{n-k-1} \widetilde{w}_{x}(t), \quad \widetilde{w}_{x}(t) \equiv \prod_{j=1}^{k+1}\left(t-x_{j}\right)
$$

and, respectively,

$$
w_{y}(t)=(t-1)^{n-k-1} \widetilde{w}_{y}(t), \quad \widetilde{w}_{y}(t) \equiv \prod_{j=0}^{k}\left(t-y_{j}\right), \quad y_{0} \equiv 1
$$

The relation (6.12) transforms then into

$$
\begin{equation*}
\widetilde{w}_{x}(t)=\widetilde{w}_{y}(t)-\sum_{i=0}^{k} \eta_{i} y_{i} \frac{\widetilde{w}_{y}(t)}{t-y_{i}}, \quad \eta_{0} \equiv \eta_{k+1}+\ldots+\eta_{n} \tag{6.13}
\end{equation*}
$$

Expanding both sides of (6.13) in $t$ we get the following prescription for calculating $\mathcal{A}_{k+1} f$ :
(1) express $f \in \mathbb{C}\left[x_{1}, \ldots, x_{k+1}\right]^{S_{k+1}}$ as a polynomial in $\left\{e_{j}\left(x_{1}, \ldots, x_{k+1}\right)\right\}$, $j=1, \ldots, k+1$;
(2) substitute for $e_{j}\left(x_{1}, \ldots, x_{k+1}\right)$ the expressions

$$
\begin{equation*}
e_{j}\left(x_{1}, \ldots, x_{k+1}\right)=\left(1+\eta_{0}+\ldots+\eta_{j-1}\right) y_{0} \cdots y_{j-1}+\text { permutations } \tag{6.14}
\end{equation*}
$$

(the distinct permutations are taken simultaneously in $y_{j}$ and $\eta_{j}$ );
(3) expand the resulting polynomial in monomials $\eta_{0}^{m_{0}} \eta_{1}^{m_{1}} \cdots \eta_{k}^{m_{k}}$, $\mathbf{m}=\left(m_{0}, m_{1}, \ldots, m_{k}\right) \in \mathbb{N}^{k+1} ;$
(4) replace each monomial in $\eta_{j}$ according to the rule

$$
\begin{equation*}
\eta_{0}^{m_{0}} \eta_{1}^{m_{1}} \cdots \eta_{k}^{m_{k}} \mapsto \frac{\left(z_{k \cdot 1}-1\right)^{m_{0}+\ldots+m_{k}}((n-k) g)_{m n_{0}}}{(n g)_{m_{0}+\ldots+m_{k}}} \prod_{j=1}^{k}(g)_{m_{i}} \tag{6.15}
\end{equation*}
$$

The last formula is obtained by expanding $\left(\eta_{k+1}+\ldots+\eta_{n}\right)^{m_{0}}$ in the left hand side of (6.15), evaluating the result by formula (4.11) and using the following combinatorial identity for $s \equiv n-k, m \equiv m_{0}$ :

$$
\begin{equation*}
\sum_{j_{1}+\ldots+j_{s}=m} \frac{m!}{j_{1}!\cdots j_{s}!} \prod_{\alpha=1}^{s}(g)_{j_{\alpha}}=(s g)_{m} \tag{6.16}
\end{equation*}
$$

which is easily proved by expanding the identity $\left[(1-t)^{-g}\right]^{s}=(1-t)^{-s g}$ in powers of $t$.

An alternative proof of Proposition 6.1 is based on the formula (4.2), presenting $Q_{z_{k+1}}$ as an integral operator. Let us take the expression (4.2) for $\left[Q_{z_{k+1}} f\right](\mathbf{y})$ and restrict $n-k$ of the arguments $y_{j}$ to the value 1. Since $\left[Q_{z_{k+1}} f\right](\mathbf{y})$ is a symmetric polynomial, it does not matter which of $y_{j}$ we choose to fix. Because of the inequalities in the definition of the domain $\Omega_{\mathrm{x}}$ (3.4),

$$
0<y_{1}<x_{1}<y_{2}<\ldots<y_{n}<x_{n}
$$

the natural choice is to take the limit $y_{1}, y_{2}, \ldots, y_{n-k} \rightarrow \widetilde{y}_{0} \equiv 1$. The variables $x_{1}, \ldots, x_{n-k-1}$ are sandwiched between $y^{\prime}$ s and, therefore, forced to tend to 1 as well. As $y_{1}, \ldots, y_{n-k}$ tend to $y_{0} \equiv 1$, the right hand side of (4.2) exhibits an uncertainty $0 / 0$. To resolve the uncertainty, let us set $y_{j}=1+\varepsilon v_{j}, j=1, \ldots, n-k$, and $x_{j}=1+\varepsilon u_{j}, j-1, \ldots, n-k-1$, for some $\varepsilon>0$ and $u_{j}, v_{j}$ satisfying

$$
0<v_{1}<u_{1}<\ldots<u_{n-k-1}<v_{n-k},
$$

and take the limit $\varepsilon \rightarrow 0$. Let us also renumber the remaining arguments as $y_{n-k+j}=\widetilde{y}_{j}, j=1, \ldots, k$, and $x_{n-k+j-1}=\widetilde{x}_{j}, j=1, \ldots, k+1$.

The components of the integrand of (4.2) are then transformed as follows:

$$
\begin{aligned}
\xi_{i} & \rightarrow \hat{\xi}_{i} \widetilde{\xi}_{0}, \quad i=1, \ldots, n-k \\
\xi_{n-k+i} & \rightarrow \widetilde{\xi}_{i}, \quad i=1, \ldots k
\end{aligned}
$$

where

$$
\begin{aligned}
& \hat{\xi}_{i}=\frac{\prod_{j=1}^{n-k-1}\left(u_{j}-v_{i}\right)}{\prod_{\substack{j=1 \\
j \neq i}}^{n-k}\left(v_{j}-v_{i}\right)}, \quad i=1, \ldots, n-k \\
& \widetilde{\xi}_{i}=\frac{\prod_{j=1}^{k+1}\left(\widetilde{x}_{j}-\widetilde{y}_{i}\right)}{\prod_{\substack{j=0 \\
j \neq i}}^{k+1}\left(\widetilde{y}_{j}-\widetilde{y}_{i}\right)}, \quad i=0, \ldots, k \\
& \frac{\Delta_{n}(\mathbf{x})}{\Delta_{n}(\mathbf{y})} \sim \varepsilon^{-n+k+1} \widetilde{\xi}_{0}^{n-k-1} \frac{\Delta_{n-k-1}(\mathbf{u})}{\Delta_{n-k}(\mathbf{v})} \frac{\Delta_{k+1}(\widetilde{\mathbf{x}})}{\Delta_{k+1}(\widetilde{\mathbf{y}})}
\end{aligned}
$$

and $\widetilde{\mathbf{x}}=\left(\widetilde{x}_{1}, \ldots, \widetilde{x}_{k+1}\right), \widetilde{\mathbf{y}}=\left(\widetilde{y}_{0}, \ldots, \widetilde{y}_{k}\right)$.
Since $d x_{1} \cdots d x_{n-k-1} \sim \varepsilon^{n-k-1} d u_{1} \cdots d u_{n-k-1}$, the factors $\varepsilon$ cancel completely. Integration in the variables $u_{j}$ produces a constant factor which is evaluated with the help of Proposition 7.2:

$$
\begin{equation*}
\frac{1}{\Delta_{n-k}(\mathbf{v})} \int_{v_{1}}^{v_{2}} d u_{1} \cdots \int_{v_{n-k-1}}^{v_{n-k}} d u_{n-k-1} \Delta_{n-k-1}(\mathbf{u})\left[\prod_{j=1}^{n-k} \hat{\xi}_{j}^{g-1}\right]=\frac{\Gamma(g)^{n-k}}{\Gamma((n-k) g)} . \tag{6.17}
\end{equation*}
$$

The expression $\left(\mathrm{id}_{[1, k]} \otimes \rho_{k}\right) Q_{z_{k+1}}$ is presented in the desired form $\mathcal{A}_{k+1}\left(\mathrm{id}_{[1, k+1]}\right.$ $\otimes \rho_{k+1}$ ) with the operator $\mathcal{A}_{k+1}$ defined by the integral

$$
\begin{align*}
& {\left[\mathcal{A}_{k+1} f\right](\widetilde{\mathbf{y}})=\frac{\Gamma(n g)}{\Gamma((n-k) g) \Gamma(g)^{k}} \frac{\left(z_{k+1}-1\right)^{1-n g}}{\Delta_{k+1}(\widetilde{\mathbf{y}})}\left[\prod_{j=1}^{k} \widetilde{y}_{j}^{1-g}\right]}  \tag{6.18}\\
& \times \int_{\tilde{\Omega}_{\mathbf{x}}} d \widetilde{\mathbf{x}} \Delta_{k+1}(\widetilde{\mathbf{x}}) \delta\left(\widetilde{x}_{1} \ldots \widetilde{x}_{k+1}\right. \\
& \left.z_{k+1} \widetilde{y}_{1} \cdots \widetilde{y}_{k}\right) \tilde{\xi}_{0}^{n-k) g-1}\left[\prod_{j=1}^{k} \widetilde{\xi}_{j}^{\tilde{s}^{-1}}\right] f(\widetilde{\mathbf{x}}),
\end{align*}
$$

where the integration domain $\widetilde{\Omega}_{\mathrm{x}}$ is described by the inequalities

$$
0<1 \equiv \widetilde{y}_{0}<\widetilde{x}_{1}<\widetilde{y}_{1}<\ldots<\widetilde{y}_{k}<\widetilde{x}_{k+1}<\infty .
$$

Using the Dirichlet-Liouville integral (3.2), one can analyse the integral operator (6.18) in the same manner as the operator $Q_{z}$ has been analysed in section 4. In particular, one can prove an analogue of Proposition 4.1: $\mathcal{A}_{k+1}$ sends symmetric polynomials into symmetric polynomials (with the dimension reduced by one) and its action on the elementary symmetric polynomials $e_{j}$ is described by formulae (6.14) and (6.15).

Notice that, for $k=0$, the formula (6.18) produces $\mathcal{A}_{1}: f\left(x_{1}\right) \mapsto f\left(z_{1}\right)$, whereas setting $k=1$ in (6.9) we get

$$
\mathcal{A}_{1}: P_{\lambda}^{(1 / g)}\left(x_{1}, 1, \ldots, 1\right) \mapsto P_{\lambda}^{(1 / g)}(1, \ldots, 1) q_{\lambda}\left(z_{1}\right)=c_{\lambda} q_{\lambda}\left(z_{1}\right)
$$

Combining these two observations together, we arrive at the following remarkable expression for the separated polynomial $q_{\lambda}(z)$ in terms of a restricted Jack polynomial:

$$
\begin{equation*}
q_{\lambda}(z)=c_{\lambda}^{-1} P_{\lambda}^{(1 / g)}(z, 1, \ldots, 1) . \tag{6.19}
\end{equation*}
$$

## 7. INTEGRAL REPRESENTATION

In this section we shall apply our $Q$-operator to construct an integral representation for Jack polynomials. In principle, such representation could be obtained by inverting the separating operator $\mathcal{S}_{n}$, described in Theorem 6.2. However, the construction of $\mathcal{S}_{n}^{-1}$ is a difficult and yet unsolved problem. Fortunately, there is another, more direct approach using the operator $Q_{z}$ at $z=0$.

Applying Proposition 4.3 to the case $z=0$ we conclude that $Q_{0}$ nullifies the
ideal $e_{n}(\mathbf{x}) \mathbb{C}[\mathbf{x}]^{S_{n}}$ and therefore can be canonically defined on the factor space $\mathcal{F}=\mathbb{C}[\mathbf{x}]^{S_{n}} / e_{n}(\mathbf{x}) \mathbb{C}[\mathbf{x}]^{S_{n}}$. For the rest of this section we denote $\mathbf{x}=\left(x_{1}, \ldots, x_{n}\right)$, $\mathbf{y}=\left(y_{1}, \ldots, y_{n}\right)$ and $\mathbf{x}^{\prime}=\left(x_{1}, \ldots, x_{n-1}\right)$. Let $\mathcal{P}$ be the projection operator $\mathcal{P}$ : $\mathbb{C}[\mathbf{x}]^{S_{n}} \mapsto \mathbb{C}\left[\mathbf{x}^{\prime}\right]^{S_{n-1}}: p\left(x_{1}, \ldots, x_{n}\right) \mapsto p\left(x_{1}, \ldots, x_{n-1}, 0\right)$. Note that $\mathcal{P}: e_{i}(\mathbf{x}) \mapsto e_{i}\left(\mathbf{x}^{\prime}\right)$ for $i=1, \ldots, n-1$ and $\mathcal{P}: e_{n}(\mathbf{x}) \mapsto 0$. Since the products $e_{1}^{k_{1}} \cdots e_{n-1}^{k_{n-1}}$ form a basis in $\mathcal{F}$, the projector $\mathcal{P}$ provides a natural isomorphism $\mathcal{F} \simeq \mathbb{C}\left[\mathbf{x}^{\prime}\right]^{S_{n-1}}$. We have thus come to the following conclusion.

Proposition 7.1. There exists a unique operator $Q_{0}^{\prime}: \mathbb{C}\left[\mathbf{x}^{\prime}\right]^{S_{n-1}} \mapsto \mathbb{C}[y]^{S_{n}}$ such that

$$
\begin{equation*}
Q_{0}=Q_{0}^{\prime} \mathcal{P} \tag{7.1}
\end{equation*}
$$

Formula (7.1) provides a direct way to constructing a Jack polynomial in $n$ variables from a Jack polynomial in $n-1$ variables. For any partition $\lambda=$ $\left(\lambda_{1}, \ldots, \lambda_{n}\right)$ of length $n$ define two partitions: $\lambda^{b}=\left(\lambda_{1, n}, \lambda_{2, n}, \ldots, \lambda_{n-1, n}, 0\right)$ of length $n$ and $\lambda^{h}=\left(\lambda_{1, n}, \lambda_{2, n}, \ldots, \lambda_{n-1, n}\right)$ of length $n-1$. Recall two important properties of Jack polynomials (see [25]): homogeneity,

$$
\begin{equation*}
P_{\lambda_{1}, \ldots, \lambda_{n}}^{(1 / g)}\left(x_{1}, \ldots, x_{n}\right)=\left(x_{1} \cdots x_{n}\right)^{\lambda_{n}} P_{\lambda_{1, n}, \ldots, \lambda_{n-1, n}, 0}^{(1 / g)}\left(x_{1}, \ldots, x_{n}\right) \tag{7.2}
\end{equation*}
$$

and restriction to $x_{n}=0$,

$$
\begin{equation*}
P_{\lambda_{1, n}, \ldots, \lambda_{n-1, n}, 0}^{(1 / g)}\left(x_{1}, \ldots, x_{n-1}, 0\right)=P_{\lambda_{1, n}, \ldots, \lambda_{n-1, n}}^{(1 / g)}\left(x_{1}, \ldots, x_{n-1}\right) \tag{7.3}
\end{equation*}
$$

Note that the equations (7.2) and (7.3) can be abbreviated as $P_{\lambda}^{(1 / g)}(\mathbf{x})=$ $\left[e_{n}(\mathbf{x})\right]^{\lambda_{n}} P_{\lambda^{6}}^{(1 / g)}(\mathbf{x})$ and, respectively, $\mathcal{P}: P_{\lambda^{6}}^{(1 / g)}(\mathbf{x}) \mapsto P_{\lambda^{6}}^{(1 / g)}\left(\mathbf{x}^{\prime}\right)$.

By Theorem 4.1, the eigenvalue of $Q_{0}$ on $P_{\lambda}^{(1 / g)}(\mathbf{x})$ is given by $q_{\lambda}(0)$. It follows from Theorem 5.2 that, for small $z, f_{\lambda}(z)=z^{\lambda_{n}}+O\left(z^{\lambda_{n}+1}\right)$ and then from Theorem 5.3 that

$$
\begin{equation*}
q_{\lambda}(z)=\beta_{\lambda}^{-1} z^{\lambda_{n}}(1+O(z)), \quad z \rightarrow 0 \tag{7.4}
\end{equation*}
$$

where $\beta_{\lambda}$ is defined by (5.15). In particular, $q_{\lambda^{b}}(0)=\beta_{\lambda}^{-1}$.
Applying the operator equality (7.1) to the polynomial $P_{\lambda^{b}}^{(1 / g)}(\mathbf{x})$ and using (7.3) and $q_{\lambda^{b}}(0)=\beta_{\lambda}^{-1}$ we obtain $\beta_{\lambda}^{-1} P_{\lambda^{\prime}}^{(1 / g)}(\mathbf{x})=\left[Q_{0}^{\prime} P_{\lambda^{k}}^{(1 / g)}\right](\mathbf{x})$. Finally, we use (7.2) and arrive at the formula

$$
\begin{equation*}
P_{\lambda}^{(1 / g)}(\mathbf{x})=\beta_{\lambda}\left[e_{n}(\mathbf{x})\right]^{\lambda_{n}}\left[Q_{0}^{\prime} P_{\lambda^{5}}^{(1 / g)}\right](\mathbf{x}), \tag{7.5}
\end{equation*}
$$

expressing a Jack polynomial in $n$ variables in terms of a Jack polynomial in $n-1$ variables.

To give the formula (7.5) more flesh, we need to realise $Q_{0}$ as an integral opcrator. However, formula (4.2), which we used to define $Q_{z}$, is valid only for $z>1$, so that the case $z=0$ requires a special consideration.

Proposition 7.2. Given a set of real parameters $\mathbf{y}=\left(y_{1}, \ldots, y_{n}\right)$ satisfying inequalities (3.3), define the domain $\Omega_{\mathbf{x}}^{\prime} \subset \mathbb{R}^{n-1}$ by the inequalities

$$
\begin{equation*}
\Omega_{\mathbf{x}}^{\prime}=\left\{\mathbf{x}^{\prime} \in \mathbb{R}^{n-1} \mid 0<y_{1}<x_{1}<y_{2}<\ldots<x_{n-1}<y_{n}<\infty\right\} . \tag{7.6}
\end{equation*}
$$

Then for $\Re \alpha_{i}>0$

$$
\begin{equation*}
\int_{\Omega_{\mathbf{x}}^{\prime}} d \mathbf{x}^{\prime} \frac{\Delta_{n-1}\left(\mathbf{x}^{\prime}\right)}{\Delta_{n}(\mathbf{y})}\left[\prod_{i=1}^{n} \hat{\xi}_{i}^{\alpha_{i}-1}\right]=\frac{\Gamma\left(\alpha_{1}\right) \cdots \Gamma\left(\alpha_{n}\right)}{\Gamma(|\alpha|)} \tag{7.7}
\end{equation*}
$$

where $\hat{\xi}_{i}>0$ are defined as

$$
\begin{equation*}
\hat{\xi}_{i}=\frac{\prod_{k=1}^{n-1}\left(x_{k}-y_{i}\right)}{\prod_{\substack{k=1 \\ k \neq i}}^{n}\left(y_{k}-y_{i}\right)}, \quad i=1, \ldots, n, \quad \sum_{i=1}^{n} \hat{\xi}_{i}=1 \tag{7.8}
\end{equation*}
$$

The proof follows closely that of Theorem 3.2. Introducing functions $\hat{w}_{x}(t)=$ $\prod_{i=1}^{n-1}\left(t-x_{i}\right)$ and $w_{y}(t)=\prod_{i=1}^{n}\left(t-y_{i}\right)$ we construct the generating function $\hat{R}(t)=\hat{w}_{x}(t) / w_{y}(t)=\sum_{i=1}^{n} \hat{\xi}_{i} /\left(t-y_{i}\right)$ for the change of variables $\left(x_{1}, \ldots\right.$, $\left.x_{n-1}\right) \mapsto\left(\hat{\xi}_{1}, \ldots, \hat{\xi}_{n-1}\right)$. The argument, based on studying $\hat{R}(t)$, shows that the domain $\Omega_{\mathbf{x}}^{\prime}$ is mapped bijectively onto $V_{\xi}^{\prime}$,

$$
\begin{equation*}
V_{\xi}^{\prime}=\left\{\hat{\boldsymbol{\xi}}^{\prime} \in \mathbb{R}^{n-1} \mid \hat{\xi}_{i}>0, i=1, \ldots, n-1, \quad \hat{\xi}_{1}+\ldots+\hat{\xi}_{n-1}<1\right\} \tag{7.9}
\end{equation*}
$$

The corresponding Jacobian is given by $\operatorname{det}\left[\partial \hat{\xi}_{j} / \partial x_{k}\right]_{i, j=1}^{n}=\Delta_{n-1}\left(\mathbf{x}^{\prime}\right) / \Delta_{n}(\mathbf{y})$.
Making the change of variables $\mathbf{x}^{\prime} \mapsto \hat{\xi}^{\prime}$ in the integral (7.7) we come exactly to the Dirichlet-Liouville integral (3.2) with the only difference that the integration variable $\hat{\xi}_{n}$ is eliminated by resolving explicitly the constraint $|\hat{\xi}|=1$.

Theorem 7.1. The integral operator $\mathbb{Q}$ defined by

$$
\begin{equation*}
[\mathbb{Q} p](\mathbf{y})=\frac{\Gamma(n g)}{\Gamma(g)^{n}} \int_{\Omega_{\mathbf{x}}^{\prime}} d \mathbf{x}^{\prime} \frac{\Delta_{n-1}\left(\mathbf{x}^{\prime}\right)}{\Delta_{n}(\mathbf{y})}\left[\prod_{i=1}^{n} \hat{\xi}_{i}^{g-1}\right] p\left(\mathbf{x}^{\prime}\right) \tag{7.10}
\end{equation*}
$$

sends $\mathbb{C}\left[\mathbf{x}^{\prime}\right]^{S_{n-1}}$ into $\mathbb{C}[\mathbf{y}]^{S_{n}}$ and coincides with the operator $Q_{0}^{\prime}$ defined by (7.1).
Proof. Repeating almost word by word the proof of Proposition 4.1 and using formula (7.7), we find the analogue of the formula (4.5) $\forall \mathbf{k}=\left(k_{1}, \ldots, k_{n}\right) \in \mathbb{N}^{n}$,

$$
\begin{equation*}
\mathbb{Q}: \hat{\xi}^{\mathbf{k}} \mapsto \frac{(g)_{k_{1}} \cdots(g)_{k_{n}}}{(n g)_{|\mathbf{k}|}} \tag{7.11}
\end{equation*}
$$

The action of $\mathbb{Q}$ on the polynomials $e_{i}\left(\mathbf{x}^{\prime}\right)$ is obtained then from the analogue of the formula (4.9),

$$
\begin{equation*}
e_{i}\left(\mathbf{x}^{\prime}\right)=\sum_{j=1}^{n} \hat{\xi}_{j}\left[e_{i-1}(\mathbf{y})\right]_{y_{j}=0} \tag{7.12}
\end{equation*}
$$

which is obtained, in turn, by expanding the equality $\hat{w}_{x}(t)=\sum_{i=1}^{n} \hat{\xi}_{i} w_{y}(t) /(t-$ $y_{i}$ ) in powers of $t$.

It now remains to identify the action of $\mathbb{Q}$ and $Q_{0}^{\prime}$ on $\mathbb{C}\left[\mathbf{x}^{\prime}\right]^{S_{n-1}}$. Setting $x_{n}=0$ in the expressions (3.6) for $\xi_{i}$ and comparing the result with the expressions (7.8), we obtain

$$
\begin{equation*}
\mathcal{P} \xi_{i}=-y_{i} \hat{\xi}_{i} \tag{7.13}
\end{equation*}
$$

Setting $z=0$ in the right hand side of (4.5) and using (7.13) we obtain exactly the right hand side of (7.11), which proves that $Q_{0}=\mathbb{Q} \mathcal{P}$.

We can regard the formula (7.5) as an integral relation, which reduces a Jack polynomial in $n$ variables to a Jack polynomial in $n-1$ variables ${ }^{1}$. Starting with $P_{\lambda}^{(1 / g)}\left(x_{1}, \ldots, x_{n}\right)$ and having iterated the formula (7.5) $n-1$ times, we go down to the $P_{\lambda_{1}}^{(1 / g)}\left(x_{1}\right)=x_{1}^{\lambda_{1}}$ and, as a result, get an explicit integral representation for a Jack polynomial in $n$ variables. To describe it explicitly, we introduce a triangular matrix $x_{i, j}, 1 \leq i \leq j \leq n$ of variables. At the first step, the variables $x_{i, n}$, $i=1, \ldots, n$, are the external ones and $x_{i, n-1}, i=1, \ldots, n-1$, are the integration variables. Then the equation (7.5) takes the following form:

$$
\begin{aligned}
& P_{\lambda}^{(1 / g)}\left(x_{1, n}, \ldots, x_{n, n)}=\frac{\Gamma(n g)}{\Gamma(g)^{n}}\left[\prod_{i=1}^{n} x_{i, n}^{\lambda_{n}}\right]\left[\prod_{i=1}^{n-1} \frac{((n-i+1) g)_{\lambda_{i, n}}}{((n-i) g)_{\lambda_{i, n}}}\right]\right. \\
& \times \int_{x_{1, n}}^{x_{2, n}} d x_{1, n-1} \cdots \int_{x_{n-1, n}}^{x_{n, n}} d x_{n-1, n-1}
\end{aligned}
$$

$$
\begin{align*}
& \times \frac{\prod_{i<j}\left(x_{j, n-1}-x_{i, n-1}\right)}{\prod_{i<j}\left(x_{j, n}-x_{i, n}\right)}\left[\frac{\prod_{i=1}^{n} \prod_{k=1}^{n-1}\left(x_{i, n}-x_{k, n-1}\right)}{\prod_{k \neq i}\left(x_{i, n}-x_{k, n}\right)}\right]^{g-1}  \tag{7.14}\\
& \times P_{\lambda_{1, n}, \ldots, \lambda_{n-1, n}\left(x_{1, n-1}, \ldots, x_{n-1, n-1}\right) .}^{(1 / g)}
\end{align*}
$$

Iterating this formula, we obtain the integral representation for Jack polynomials

$$
\begin{align*}
& P_{\lambda}^{(1 / g)}\left(x_{1, n}, \ldots, x_{n, n}\right)=\frac{\prod_{i=1}^{n} x_{i, n}^{\lambda_{n}}}{\prod_{i<j}\left(x_{j, n}-x_{i, n}\right)}\left[\prod_{j=2}^{n} \prod_{i=1}^{j-1} \frac{((j+1-i) g)_{\lambda_{i, j}}}{((j-i) g)_{\lambda_{i, j}}}\right] \\
& \times\left(\prod_{j=n-1,1}\left(\prod_{i=1, j} \int_{x_{i, j+1}}^{x_{i+1, j+1}} d x_{i, j}\right)\right)\left\{\prod_{j=2}^{n} \prod_{i=1}^{j}\left[\frac{\prod_{k=1}^{j-1}\left(x_{i, j}-x_{k, j-1}\right)}{\prod_{l=k \neq i}^{j}\left(x_{i, j}-x_{k, j}\right)}\right]\right\}^{g-1}  \tag{7.15}\\
& \times\left(\prod_{j=1}^{n-1} \prod_{i=1}^{j} x_{i, j}^{\lambda_{j, j+1}}\right) \Gamma(g)^{-n(n+1) / 2} \prod_{j=1}^{n} \Gamma(j g) .
\end{align*}
$$

It is implied in (7.15) that the integrals $\int d x_{i, j}$ are ordered corresponding to the order of indices in the products.

[^1]As mentioned before, formula (7.14) first appeared in [28], where its proof was based on the fact that Jack polynomials can be obtained as a limit from the shifted Jack polynomials. One can regard the integral equation (4.17) in section 4 as the one-parameter generalisation of (7.14).

## 8. CONCLUDING REMARKS

Our construction of the $Q$-operator relies on the properties of Jack polynomials. Nevertheless, several of the obtained results are of importance for the general theory of quantum integrable models. It concerns, first of all, the factorised separation chain, constructed in Section 6. Similar factorisations of separating operators were already observed for other integrable models [17] and, apparently, they are manifestations of some general pattern, which is yet to be fully understood.

Notice also the intriguing role of the restricted Jack polynomials revealed in formulae like (6.9) or (6.19). It would be interesting to find analogous formulae for other integrable models. The properties of restricted Jack polynomials themselves deserve a further study.

Finally, we should mention another integral representation known for Jack polynomials [2].

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[^1]:    ${ }^{1}$ or, vice versa, builds up the number of variables, starting from the unit function

