# The periodic unfolding method for perforated domains and Neumann sieve models 

D. Cioranescu ${ }^{\text {a }}$, A. Damlamian ${ }^{\text {b,* }}$, G. Griso ${ }^{\text {a }}$, D. Onofrei ${ }^{\text {c }}$<br>${ }^{\text {a }}$ Laboratoire Jacques-Louis Lions, Boite courier 187, Universite Pierre et Marie Curie, 4 place Jussieu, France<br>${ }^{\text {b }}$ Université Paris-Est, Laboratoire d'Analyse et de Mathématiques Appliquées, CNRS UMR 8050, CMC, 94010 Créteil Cedex, France<br>${ }^{\text {c }}$ Department of Mathematical Sciences, Worcester Polytechnic Institute, MA, USA

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#### Abstract

The periodic unfolding method, introduced in [D. Cioranescu, A. Damlamian, G. Griso, Periodic unfolding and homogenization, C. R. Acad. Sci. Paris, Ser. I 335 (2002) 99-104], was developed to study the limit behavior of periodic problems depending on a small parameter $\varepsilon$. The same philosophy applies to a range of periodic problems with small parameters and with a specific period (as well as to almost any combinations thereof). One example is the so-called Neumann sieve.

In this work, we present these extensions and show how they apply to known results and allow for generalizations (some in dimension $N \geqslant 3$ only). The case of the Neumann sieve is treated in details. This approach is significantly simpler than the original ones, both in spirit and in practice.


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## Résumé

La méthode de l'éclatement périodique, introduite dans [D. Cioranescu, A. Damlamian, G. Griso, Periodic unfolding and homogenization, C. R. Acad. Sci. Paris, Ser. I 335 (2002) 99-104], a pour but l'étude du comportement asymptotique de problèmes périodiques avec période tendant vers zéro. La même approche permet de traiter toute une famille de problèmes caractérisés par des périodicités de tailles tendant vers zéro. Un exemple est donné par le problème connu sous le nom de la passoire de Neumann.

Nous présentons ici divers prolongements et généralisations de l'éclatement périodique (certains nécéssitant que la dimension $N$ soit supérieure à 3 ) et nous l'appliquons à la passoire de Neumann. Pour ce type de problèmes, cette approche apparaît comme élémentaire, directe et plus efficace que les méthodes classiques.
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## 1. Introduction

The periodic unfolding method (see [8]), as a simpler alternative to the two-scale convergence, was developed to study the limit behavior of periodic problems depending on a small parameter $\varepsilon$. As it turns out, the same philosophy

[^0]applies to a whole range of periodic problems with small parameters, provided they have a specific period. The method is flexible enough to apply as well to almost any combinations of the preceding cases.

In this work, we present these various extensions and show how they apply to known results and allow for generalizations. This approach is significantly simpler than the original ones, both in spirit and in practice.

The plan of the paper is as follows.
Section 2 is devoted to the presentation of various unfolding operators and their main properties for domains in $\mathbb{R}^{N}, N \in \mathbb{N}^{*}$. More precisely, in Section 2.1, we recall the definition of the unfolding operator $\mathcal{T}_{\varepsilon}$ for the periodic case in fixed domains ([8] and [12]). In Section 2.2, we present the unfolding operator adapted to the case of holes of size $\varepsilon$ (with Neumann boundary condition) with period of same size (see [9] for details and applications). Section 2.3 introduces the unfolding operator $\mathcal{I}_{\varepsilon, \delta}$ depending of two small parameters $\varepsilon$ and $\delta$ (corresponding to the scales $\varepsilon$ and $\varepsilon \delta)$ and which was first introduced in a similar form in [6] and [7]. The following subsections deal again with an unfolding operator $\mathcal{T}_{\varepsilon, \delta}^{b l}$ depending on the scales $\varepsilon$ and $\varepsilon \delta$ when the latter occurs only on a layer. This approach never assumes the existence of an extension operator in the cells but is based on the Poincaré-Wirtinger inequality (Section 2.1) and Sobolev-Poincaré-Wirtinger inequality (Sections 2.2 and 2.3). The latter requires that the dimension $N$ be larger than 2.

The remainder of the paper is devoted to the application to various linear problems in perforated domains and with oscillating coefficients. For simplicity, we assume a homogeneous Dirichlet boundary condition on the outer boundary of the domain, but more general boundary conditions can be handled provided the outer boundary is Lipschitz and the perforations do not intersect it. In each case, we obtain both the unfolded and the classical (standard) form for the limit problem. The operator $\mathcal{T}_{\varepsilon}$ allows to homogenize the coefficients of the differential operators, whereas the operators $\mathcal{T}_{\varepsilon, \delta}\left(\right.$ or $\mathcal{T}_{\varepsilon, \delta}^{b l}, \ldots$ ) generates the "strange terms" in the limit.

Section 3 concerns the homogenization of elliptic problems with oscillating coefficients, for volume $\varepsilon$-periodically distributed small holes of size $\varepsilon \delta$ with Dirichlet condition. These results are well known for the Laplace operator, with the appearance of the "strange term" (see [10] and references therein). For the case of oscillating coefficients, we refer to [11] where $H$-convergence is used. It should be noted that for technical reasons, our method fails to apply in dimension $N=2$. See also [2] for the nonlinear case.

Section 4 considers small perforations of size $\varepsilon \delta$ which are distributed $\varepsilon$-periodically in a layer of thickness $\varepsilon$. It generalizes the results of $[21,17]$ and $[10]$ to the case of oscillating coefficients.

Section 5 deals with the Neumann sieve problem with zero thickness and oscillating coefficients. For the case of constant coefficients, we refer the reader to [4,12,16,20,1] and [19]. We also refer to the recent paper [3] for a different approach. In Section 6, the thick sieve is treated (for which we refer to [15] for the case of constant coefficients). The unfolding method was applied for the first time for sieve problems in [18], also in the case of constant coefficients.

To conclude this section, we would like to point out that using the various unfolding operators introduced in this paper, one can treat any combination of the previous problems, for instance, a medium with $\varepsilon$-size Neumann perforations and $\varepsilon \delta$-size Dirichlet holes in the bulk (see Fig. 10), or even a thick sieve in such a medium. This will be presented in a forthcoming paper which will also include the proof of convergence for the energies.

## 2. The periodic unfolding operator

In this section we recall the general properties of the periodic unfolding operator introduced in [8] and include variants and generalizations, all based on the technique of unfolding. In particular, we introduce the notion of unfolding criterion for integrals (in short u.c.i.), in order to simplify the proofs where unfolding is used.

For $N$ in $\mathbb{N}^{*}$, let $Y$ be the unit cube of $\mathbb{R}^{N}$ centered in the origin, $\left.Y \doteq\right]-\frac{1}{2}, \frac{1}{2}\left[{ }^{N}\right.$ (more general sets $Y$ having the paving property in $\mathbb{R}^{N}$ can also be used, cf. [14]). We consider the periodical net on $\mathbb{R}^{N}$ (i.e. the subgroup $\mathbb{Z}^{N}$ ) and all the corresponding translates of $Y$. By analogy with the one-dimensional case, to each $x \in \mathbb{R}^{N}$ we can associate its integer part, $[x]_{Y}$ belonging to the net, such that $x-[x]_{Y} \in Y$, the latter being its fractional part, respectively, i.e, $\{x\}_{Y}=x-[x]_{Y}$ (see Fig. 1). These definitions are ambiguous, but only on a set of measure zero, which is enough for our purpose.

Therefore we have:

$$
x=\varepsilon\left\{\frac{x}{\varepsilon}\right\}_{Y}+\varepsilon\left[\frac{x}{\varepsilon}\right]_{Y} \quad \text { for every } x \in \mathbb{R}^{N}
$$



Fig. 1. The basic decomposition.


Fig. 2. The sets $\Omega, \widehat{\Omega}_{\varepsilon}$ and $\Lambda_{\varepsilon}$.

Let $\Omega$ be open and bounded in $\mathbb{R}^{N}$. We use the following notations:

$$
\begin{equation*}
\widehat{\Omega}_{\varepsilon}=\left\{x \in \Omega,\left(\varepsilon\left[\frac{x}{\varepsilon}\right]+\varepsilon Y\right) \subset \Omega\right\}, \quad \Lambda_{\varepsilon}=\Omega \backslash \widehat{\Omega}_{\varepsilon} . \tag{2.1}
\end{equation*}
$$

The set $\widehat{\Omega}_{\varepsilon}$ is the largest union of $\varepsilon Y$ cells contained in $\Omega$, while $\Lambda_{\varepsilon}$ is the subset of $\Omega$ containing the parts from $\varepsilon Y$ cells intersecting the boundary $\partial \Omega$ (see Fig. 2).
2.1. The case of fixed domains: the operator $\mathcal{T}_{\varepsilon}$

We recall here the definition of the unfolding operator and its main properties (for details and proofs we refer the reader to [8] and [13]).

Definition 2.1. For $\phi \in L^{p}(\Omega)$, the unfolding operator $\mathcal{T}_{\varepsilon}: L^{p}(\Omega) \rightarrow L^{p}(\Omega \times Y)$ is defined as follows:

$$
\mathcal{T}_{\varepsilon}(\phi)(x, y)= \begin{cases}\phi\left(\varepsilon\left[\frac{x}{\varepsilon}\right]_{Y}+\varepsilon y\right) & \text { if }(x, y) \in \widehat{\Omega}_{\varepsilon} \times Y, \\ 0 & \text { if }(x, y) \in \Lambda_{\varepsilon} \times Y\end{cases}
$$

Theorem 2.2 (Properties of the operator $\mathcal{T}_{\varepsilon}$ ).

1. For any $v, w \in L^{p}(\Omega), \mathcal{T}_{\varepsilon}(v w)=\mathcal{T}_{\varepsilon}(v) \mathcal{T}_{\varepsilon}(w)$.
2. For any $w \in L^{p}(\Omega)$, one has the following "exact integration" formula:

$$
\int_{\Omega \times Y} \mathcal{T}_{\varepsilon}(w)(x, y) \mathrm{d} x \mathrm{~d} y=\int_{\Omega} w(x) \mathrm{d} x-\int_{\Lambda_{\varepsilon}} w(x) \mathrm{d} x=\int_{\widehat{\Omega}_{\varepsilon}} w(x) \mathrm{d} x .
$$

3. For any $u \in L^{1}(\Omega)$,

$$
\int_{\Omega \times Y}\left|\mathcal{F}_{\varepsilon}(u)\right| \mathrm{d} x \mathrm{~d} y \leqslant \int_{\Omega}|u| \mathrm{d} x .
$$

4. For any $u \in L^{1}(\Omega)$,

$$
\begin{equation*}
\left|\int_{\Omega} u \mathrm{~d} x-\int_{\Omega \times Y} \mathcal{T}_{\varepsilon}(u) \mathrm{d} x \mathrm{~d} y\right| \leqslant \int_{\Lambda_{\varepsilon}}|u| \mathrm{d} x . \tag{2.2}
\end{equation*}
$$

5. Let $\left\{w_{\varepsilon}\right\} \subset L^{2}(\Omega)$ such that $w_{\varepsilon} \rightarrow w$ strongly in $L^{2}(\Omega)$. Then

$$
\mathcal{T}_{\varepsilon}\left(w_{\varepsilon}\right) \rightarrow w \quad \text { strongly in } L^{2}(\Omega \times Y)
$$

6. Let $w_{\varepsilon} \rightharpoonup w$ weakly in $H^{1}(\Omega)$. Then, there exists a subsequence and $\widehat{w} \in L^{2}\left(\Omega ; H_{p e r}^{1}(Y)\right)$ such that

$$
\mathcal{T}_{\varepsilon}\left(\nabla w_{\varepsilon}\right) \rightharpoonup \nabla_{x} w+\nabla_{y} \widehat{w} \quad \text { weakly in } L^{2}(\Omega \times Y) .
$$

Property 4 shows that any integral of a function $w$ on $\Omega$, is "almost equivalent" to the integral of its unfolded on $\Omega \times Y$, the "integration defect" arises only from the cells intersecting the boundary $\partial \Omega$ and is controlled by the right-hand side integral in (2.2).

The next proposition, which we call unfolding criterion for integrals (u.c.i.), is a very useful tool when treating homogenization problems.

Proposition 2.3 (u.c.i.). If $\left\{w_{\varepsilon}\right\}$ is a sequence in $L^{1}(\Omega)$ satisfying

$$
\int_{\Lambda_{\varepsilon}}\left|w_{\varepsilon}\right| \mathrm{d} x \rightarrow 0
$$

then

$$
\int_{\Omega} w_{\varepsilon} \mathrm{d} x-\int_{\Omega \times Y} \mathcal{T}_{\varepsilon}\left(w_{\varepsilon}\right) \mathrm{d} x \mathrm{~d} y \rightarrow 0 .
$$

Based on this result, in order to simplify the proofs in the sequel, we introduce the following notation:

Notation 2.4. If $\left\{w_{\varepsilon}\right\}$ is a sequence satisfying u.c.i., we write:

$$
\int_{\Omega} w_{\varepsilon} \mathrm{d} x \stackrel{\mathcal{T}_{\varepsilon}}{=} \int_{\Omega \times Y} \mathcal{T}_{\varepsilon}\left(w_{\varepsilon}\right) \mathrm{d} x \mathrm{~d} y .
$$

Corollary 2.5. Let $\left\{u_{\varepsilon}\right\}$ be bounded in $L^{2}(\Omega)$ and $\left\{v_{\varepsilon}\right\}$ be bounded in $L^{p}(\Omega)$ with $p>2$. Then we have:

$$
\int_{\Omega} u_{\varepsilon} v_{\varepsilon} \mathrm{d} x \stackrel{\mathcal{T}_{\varepsilon}}{=} \int_{\Omega \times Y} \mathcal{T}_{\varepsilon}\left(u_{\varepsilon}\right) \mathcal{T}_{\varepsilon}\left(v_{\varepsilon}\right) \mathrm{d} x \mathrm{~d} y
$$

We end this subsection with the notion of local average of a function.
Definition 2.6. The local average $M_{Y}^{\varepsilon}: L^{p}(\Omega) \mapsto L^{p}(\Omega)$, is defined for any $\phi$ in $L^{p}(\Omega), 1 \leqslant p<\infty$, by

$$
M_{Y}^{\varepsilon}(\phi)(x) \doteq \int_{Y} \mathcal{T}_{\varepsilon}(\phi)(x, y) \mathrm{d} y
$$

Remark 2.7. The function $M_{Y}^{\varepsilon}(\phi)$ is indeed a local average, since

$$
M_{Y}^{\varepsilon}(\phi)(x)=\int_{Y} \mathcal{T}_{\varepsilon}(\phi)(x, y) \mathrm{d} y= \begin{cases}\frac{1}{\varepsilon^{N}} \int_{\varepsilon\left[\frac{x}{\varepsilon}\right]+\varepsilon Y} \phi(\zeta) \mathrm{d} \zeta & \text { if } x \in \widehat{\Omega}_{\varepsilon}, \\ 0 & \text { if } x \in \Lambda_{\varepsilon}\end{cases}
$$

Remark 2.8. Note that $\mathcal{T}_{\varepsilon}\left(M_{Y}^{\varepsilon}(\phi)\right)=M_{Y}^{\varepsilon}(\phi)$ on the set $\Omega \times Y$.
The next proposition, which will be frequently used as well, is classical:
Proposition 2.9. Let $\left\{w_{\varepsilon}\right\}$ be a sequence such that $w_{\varepsilon} \rightarrow w$ strongly in $L^{p}(\Omega)$ where $1 \leqslant p<\infty$. Then we have:

$$
M_{Y}^{\varepsilon}\left(w_{\varepsilon}\right) \rightarrow w \quad \text { strongly in } L^{p}(\Omega)
$$

### 2.2. Unfolding in domains with volume-distributed "small" holes: the operator $\mathcal{T}_{\varepsilon, \delta}$

In Section 4 below, we will consider domains with $\varepsilon Y$-periodically distributed holes of size $\varepsilon \delta(\delta \rightarrow 0$ with $\varepsilon)$. More precisely (see Fig. 3), for a given open $B \Subset Y$ we denote $Y_{\delta}^{*}=Y \backslash \delta \bar{B}$ and define the perforated domain $\Omega_{\varepsilon, \delta}^{*}$ as

$$
\begin{equation*}
\Omega_{\varepsilon, \delta}^{*}=\left\{x \in \Omega, \text { such that }\left\{\frac{x}{\varepsilon}\right\} \in Y_{\delta}^{*}\right\} . \tag{2.3}
\end{equation*}
$$

This geometry of domains with "small" holes requires another unfolding operator $\mathcal{T}_{\varepsilon, \delta}$ depending on both parameters $\varepsilon$ and $\delta$. In the next sections, we will consider functions $v_{\varepsilon, \delta}$ which vanish on the whole boundary of the perforated domain $\Omega_{\varepsilon, \delta}^{*}$, namely belonging to the space $H_{0}^{1}\left(\Omega_{\varepsilon, \delta}^{*}\right)$. These functions are naturally extended by zero to the whole of $\Omega$ and these extensions belong to $H_{0}^{1}(\Omega)$. Consequently, from now on, we will not distinguish elements of $H_{0}^{1}\left(\Omega_{\varepsilon, \delta}^{*}\right)$ and their extensions in $H_{0}^{1}(\Omega)$. This justifies the introduction of $\mathcal{T}_{\varepsilon, \delta}$ on the fix domain $\Omega$, while it may (and, in Section 4 , will) be applied to elements of $H_{0}^{1}\left(\Omega_{\varepsilon, \delta}^{*}\right)$.

Definition 2.10. For $\phi \in L^{p}(\Omega), p \in\left[1, \infty\left[\right.\right.$, the unfolding operator $\mathcal{T}_{\varepsilon, \delta}: L^{p}(\Omega) \rightarrow L^{p}\left(\Omega \times \mathbb{R}^{N}\right)$ is defined by:

$$
\mathcal{T}_{\varepsilon, \delta}(\phi)(x, z)= \begin{cases}\mathcal{T}_{\varepsilon}(x, \delta z) & \text { if }(x, z) \in \widehat{\Omega}_{\varepsilon} \times \frac{1}{\delta} Y, \\ 0 & \text { otherwise } .\end{cases}
$$

For $N \geqslant 3$, the Sobolev exponent $\frac{2 N}{N-2}$ associated to 2 is denoted $2^{*}$.
The next results follow from Theorem 2.2 by using the change of variable $z=(1 / \delta) y$.


Fig. 3. The sets $B$ and $Y_{\delta}^{*}$ and the corresponding $\Omega_{\varepsilon, \delta}^{*}$.
Theorem 2.11 (Properties of the operator $\mathcal{T}_{\varepsilon, \delta}$ ).

1. For any $v, w \in L^{p}(\Omega), \mathcal{T}_{\varepsilon, \delta}(v w)=\mathcal{T}_{\varepsilon, \delta}(v) \mathcal{T}_{\varepsilon, \delta}(w)$.
2. For any $u \in L^{1}(\Omega)$, one has

$$
\delta^{N} \int_{\Omega \times \mathbb{R}^{N}}\left|\mathcal{T}_{\varepsilon, \delta}(u)\right| \mathrm{d} x \mathrm{~d} z \leqslant \int_{\Omega}|u| \mathrm{d} x .
$$

3. For any $u \in L^{2}(\Omega)$,

$$
\left\|\mathcal{T}_{\varepsilon, \delta}(u)\right\|_{L^{2}\left(\Omega \times \mathbb{R}^{N}\right)}^{2} \leqslant \frac{1}{\delta^{N}}\|u\|_{L^{2}(\Omega)}^{2} .
$$

4. For any $u \in L^{1}(\Omega)$,

$$
\left|\int_{\Omega} u \mathrm{~d} x-\delta^{N} \int_{\Omega \times \mathbb{R}^{N}} \mathcal{T}_{\varepsilon, \delta}(u) \mathrm{d} x \mathrm{~d} z\right| \leqslant \int_{\Lambda_{\varepsilon}}|u| \mathrm{d} x .
$$

5. Let $u \in H^{1}(\Omega)$. Then

$$
\mathcal{T}_{\varepsilon, \delta}\left(\nabla_{x} u\right)=\frac{1}{\varepsilon \delta} \nabla_{z}\left(\mathcal{T}_{\varepsilon, \delta}(u)\right) \quad \text { in } \Omega \times \frac{1}{\delta} Y
$$

6. Suppose $N \geqslant 3$ and let $\omega$ be open and bounded in $\mathbb{R}^{N}$. Then the following estimates hold:

$$
\begin{gather*}
\left\|\nabla_{z}\left(\mathcal{I}_{\varepsilon, \delta}(u)\right)\right\|_{L^{2}\left(\Omega \times \frac{1}{\delta} Y\right)}^{2} \leqslant \frac{\varepsilon^{2}}{\delta^{N-2}}\|\nabla u\|_{L^{2}(\Omega)}^{2}  \tag{2.4}\\
\left\|\mathcal{T}_{\varepsilon, \delta}\left(u-M_{Y}^{\varepsilon}(u)\right)\right\|_{L^{2}\left(\Omega ; L^{2^{*}}\left(\mathbb{R}^{N}\right)\right)}^{2} \leqslant \frac{C \varepsilon^{2}}{\delta^{N-2}}\|\nabla u\|_{L^{2}(\Omega)}^{2} \tag{2.5}
\end{gather*}
$$

and

$$
\begin{equation*}
\left\|\mathcal{T}_{\varepsilon, \delta}(u)\right\|_{L^{2}(\Omega \times \omega)}^{2} \leqslant \frac{2 C \varepsilon^{2}}{\delta^{N-2}}|\omega|^{2 / N}\|\nabla u\|_{L^{2}(\Omega)}^{2}+2|\omega|\|u\|_{L^{2}(\Omega)}^{2} \tag{2.6}
\end{equation*}
$$

where C denotes the Sobolev-Poincaré-Wirtinger constant for $H^{1}(Y)$.
7. Suppose $N \geqslant 3$. Let $\left\{w_{\varepsilon, \delta}\right\}$ be a sequence in $H^{1}(\Omega)$ which is uniformly bounded when both $\varepsilon$ and $\delta$ go to zero. Then, up to a subsequence, there is $W$ in $L^{2}\left(\Omega ; L^{2^{*}}\left(\mathbb{R}^{N}\right)\right)$ with $\nabla_{z} W$ in $L^{2}\left(\Omega \times \mathbb{R}^{N}\right)$ such that

$$
\begin{gathered}
\frac{\delta^{\frac{N}{2}-1}}{\varepsilon}\left(\mathcal{T}_{\varepsilon, \delta}\left(w_{\varepsilon, \delta}\right)-M_{Y}^{\varepsilon}\left(w_{\varepsilon, \delta}\right) 1_{\frac{1}{\delta} Y}\right) \rightharpoonup W \\
\quad \begin{array}{cl}
\text { weakly in } L^{2}\left(\Omega ; L^{2^{*}}\left(\mathbb{R}^{N}\right)\right), \\
\varepsilon & \nabla_{z}\left(\mathcal{T}_{\varepsilon, \delta}\left(w_{\varepsilon, \delta}\right)\right) 1_{\frac{1}{\delta} Y} \rightharpoonup \nabla_{z} W
\end{array} \text { weakly in } L^{2}\left(\Omega \times \mathbb{R}^{N}\right) .
\end{gathered}
$$

Assuming furthermore that $\lim \sup _{(\varepsilon, \delta) \rightarrow\left(0^{+}, 0^{+}\right)} \frac{\delta^{N / 2-1}}{\varepsilon}<+\infty$, one can choose the subsequence above and some $U$ in $L^{2}\left(\Omega ; L_{\mathrm{loc}}^{2}\left(\mathbb{R}^{N}\right)\right)$ with

$$
\frac{\delta^{\frac{N}{2}-1}}{\varepsilon} \mathcal{T}_{\varepsilon, \delta}\left(w_{\varepsilon, \delta}\right) \rightharpoonup U \quad \text { weakly in } L^{2}\left(\Omega ; L_{\mathrm{loc}}^{2}\left(\mathbb{R}^{N}\right)\right)
$$

Remark 2.12. In order to establish (2.5)-(2.6) from (2.4), the Sobolev-Poincaré-Wirtinger inequality is used (because of its scale-invariance). The use of the standard Poincaré-Wirtinger inequality would give,

$$
\left\|\mathcal{T}_{\varepsilon, \delta}\left(u-M_{Y}^{\varepsilon}(u)\right)\right\|_{L^{2}\left(\Omega^{\prime} \times \mathbb{R}^{N}\right)}^{2} \leqslant \frac{1}{\delta^{2}} \frac{C^{\prime} \varepsilon^{2}}{\delta^{N-2}}\|\nabla u\|_{L^{2}(\Omega)}^{2}
$$

where $C^{\prime}$ is the Poincaré-Wirtinger constant of $Y$. This estimate is not compatible with (2.4).
Concerning the integral formulas, we have the following results, similar to those of the previous subsection.
Proposition 2.13 (u.c.i.). If $\left\{w_{\varepsilon}\right\}$ is a sequence in $L^{1}(\Omega)$ satisfying

$$
\int_{\Lambda_{\varepsilon}}\left|w_{\varepsilon}\right| \mathrm{d} x \rightarrow 0
$$

then

$$
\int_{\Omega} w_{\varepsilon} \mathrm{d} x \stackrel{\mathcal{T}_{\varepsilon, \delta}}{=} \delta^{N} \int_{\Omega \times \mathbb{R}^{N}} \mathcal{T}_{\varepsilon, \delta}\left(w_{\varepsilon}\right) \mathrm{d} x \mathrm{~d} z .
$$

Corollary 2.14. Let $\left\{u_{\varepsilon}\right\}$ be bounded in $L^{2}(\Omega)$ and $\left\{v_{\varepsilon}\right\}$ be bounded in $L^{p}(\Omega)$ with $p>2$. Then

$$
\int_{\Omega} u_{\varepsilon} v_{\mathcal{E}} \mathrm{d} x \stackrel{\mathcal{T}_{\varepsilon, \delta}}{=} \delta^{N} \int_{\Omega \times \mathbb{R}^{N}} \mathcal{T}_{\varepsilon, \delta}\left(u_{\varepsilon}\right) \mathcal{T}_{\varepsilon, \delta}\left(v_{\varepsilon}\right) \mathrm{d} x \mathrm{~d} z .
$$

### 2.3. The boundary-layer unfolding operator: the operator $\mathcal{T}_{\varepsilon, \delta}^{b l}$

For sieve-type problems (Sections 4 and 5 below), we consider the case of holes of size $\varepsilon \delta$, distributed in $\Sigma_{\varepsilon}^{\prime}$, a layer of thickness $\varepsilon$ parallel to a hyperplane in the open domain $\Omega$ in $\mathbb{R}^{N}$. We denote $x^{\prime} \doteq\left(x_{1}, \ldots, x_{N-1}\right), \Pi \doteq\left\{x_{N}=0\right\}$ and set $\Sigma=\Pi \cap \Omega$.

The layer $\Sigma_{\varepsilon}^{\prime}$ is defined as

$$
\Sigma_{\varepsilon}^{\prime}=\Omega \cap\left\{x ;\left|x_{N}\right|<\frac{\varepsilon}{2}\right\}
$$

and by analogy with (2.1), we introduce the corresponding sets,

$$
\widehat{\Sigma}_{\varepsilon}^{\prime}=\left\{x \in \Sigma_{\varepsilon}^{\prime},\left(\varepsilon\left[\frac{x}{\varepsilon}\right]+\varepsilon Y\right) \subset \Sigma_{\varepsilon}^{\prime}\right\}, \quad \Lambda_{\varepsilon}^{\prime}=\Sigma_{\varepsilon}^{\prime}, \backslash \widehat{\Sigma}_{\varepsilon}^{\prime}
$$

and denote $\widehat{\Sigma}_{\varepsilon}=\widehat{\Sigma}_{\varepsilon}^{\prime} \cap \Pi$.
The set $\widehat{\Sigma}_{\varepsilon}^{\prime}$ is the largest union of $\varepsilon Y$ cells contained in $\Sigma_{\varepsilon}^{\prime}$ (see Fig. 4).


Fig. 4. The sets $\Sigma_{\varepsilon}^{\prime}, \widehat{\Sigma}_{\varepsilon}$ and $\Lambda_{\varepsilon}^{\prime}$.
Definition 2.15. For $\phi \in L^{p}\left(\Sigma_{\varepsilon}^{\prime}\right), p \in\left[1, \infty\left[\right.\right.$ the unfolding operator $\mathcal{T}_{\varepsilon, \delta}^{b l}: L^{p}\left(\Sigma_{\varepsilon}^{\prime}\right) \rightarrow L^{p}\left(\Sigma \times \mathbb{R}^{N}\right)$ is defined by:

$$
\mathcal{T}_{\varepsilon, \delta}^{b l}(\phi)\left(x^{\prime}, z\right)= \begin{cases}\phi\left(\varepsilon\left[\frac{\left(x^{\prime}, 0\right)}{\varepsilon}\right]_{Y}+\varepsilon \delta z\right) & \text { if }\left(x^{\prime}, z\right) \in \widehat{\Sigma}_{\varepsilon} \times \frac{1}{\delta} Y, \\ 0 & \text { otherwise }\end{cases}
$$

This operation, designed to capture the contribution of the barriers in the limit process, was originally used in [18]. We also introduce the notion of local average related to the hyperplane $\Sigma$.

Definition 2.16. The local average $M_{Y}^{\varepsilon, b l}: L^{p}\left(\Sigma_{\varepsilon}^{\prime}\right) \mapsto L^{p}(\Sigma)$, is defined for every $\phi$ in $L^{p}\left(\Sigma_{\varepsilon}^{\prime}\right), 1 \leqslant p<\infty$, by

$$
M_{Y}^{\varepsilon, b l}(\phi)\left(x^{\prime}\right)=\delta^{N} \int_{\frac{1}{\delta} Y} \mathcal{T}_{\varepsilon, \delta}^{b l}(\phi)\left(x^{\prime}, z\right) \mathrm{d} z= \begin{cases}\frac{1}{\varepsilon^{N}} \int_{\varepsilon\left[\frac{x^{\prime}}{\varepsilon}\right]+\varepsilon Y} \phi(\zeta) \mathrm{d} \zeta & \text { if } x^{\prime} \in \widehat{\Sigma}_{\varepsilon} \\ 0 & \text { if } x^{\prime} \in \Sigma \backslash \widehat{\Sigma}_{\varepsilon}\end{cases}
$$

Remark 2.17. Since elements of $L^{p}(\Sigma)$ can be considered as functions of $L^{p}\left(\Sigma_{\varepsilon}^{\prime}\right), M_{Y}^{\varepsilon, b l}$ can be applied to them. With this convention, $\mathcal{T}_{\varepsilon, \delta}^{b l}\left(M_{Y}^{\varepsilon, b l}(\phi)\right)=M_{Y}^{\varepsilon, b l}(\phi)$ on the set $\Sigma$.

We also have an equivalent of Proposition 2.9.
Proposition 2.18. Let $\left\{w_{\varepsilon}\right\}$ be a sequence such that $w_{\varepsilon} \rightharpoonup w$ weakly in $H^{1}(\Omega)$. Then

$$
M_{Y}^{\varepsilon, b l}\left(w_{\varepsilon}\right) \rightarrow w_{\left.\right|_{\Sigma}} \quad \text { strongly in } L^{2}(\Sigma) .
$$

It is easy to check that most of the results stated in the previous subsection extend to $\mathcal{T}_{\varepsilon, \delta}^{b l}$.
Theorem 2.19 (Properties of the operator $\mathcal{T}_{\varepsilon, \delta}^{b l}$ ).

1. For any $v, w \in L^{p}\left(\Sigma_{\varepsilon}^{\prime}\right)$,

$$
\mathcal{T}_{\varepsilon, \delta}^{b l}(v w)=\mathcal{T}_{\varepsilon, \delta}^{b l}(v) \mathcal{T}_{\varepsilon, \delta}^{b l}(w) .
$$

2. For any $u \in L^{1}\left(\Sigma_{\varepsilon}^{\prime}\right)$,

$$
\varepsilon \delta^{N} \int_{\Sigma \times \mathbb{R}^{N}} \mathcal{T}_{\varepsilon, \delta}^{b l}(u) \mathrm{d} x^{\prime} \mathrm{d} z=\int_{\bar{\Sigma}_{\varepsilon}^{\prime}} u \mathrm{~d} x, \quad \text { and } \quad \varepsilon \delta^{N} \int_{\Sigma \times \mathbb{R}^{N}}\left|\mathcal{T}_{\varepsilon, \delta}^{b l}(u)\right| \mathrm{d} x^{\prime} \mathrm{d} z \leqslant \int_{\Sigma_{\varepsilon}^{\prime}}|u| \mathrm{d} x .
$$

3. For any $u \in L^{2}\left(\Sigma_{\varepsilon}^{\prime}\right)$,

$$
\left\|\mathcal{T}_{\varepsilon, \delta}^{b l}(u)\right\|_{L^{2}\left(\Sigma \times \mathbb{R}^{N}\right)}^{2} \leqslant \frac{1}{\varepsilon \delta^{N}}\|u\|_{L^{2}\left(\Sigma_{\varepsilon}^{\prime}\right)}^{2} .
$$

4. For any $u \in L^{1}\left(\Sigma_{\varepsilon}^{\prime}\right)$, one has

$$
\left|\int_{\Sigma_{\varepsilon}^{\prime}} u \mathrm{~d} x-\varepsilon \delta^{N} \int_{\Sigma \times \mathbb{R}^{N}} \mathcal{T}_{\varepsilon, \delta}^{b l}(u) \mathrm{d} x^{\prime} \mathrm{d} z\right| \leqslant \int_{\Lambda_{\varepsilon}^{\prime}}|u| \mathrm{d} x .
$$

5. Let u be in $H^{1}\left(\Sigma_{\varepsilon}^{\prime}\right)$. Then,

$$
\mathcal{T}_{\varepsilon, \delta}^{b l}\left(\nabla_{x} u\right)=\frac{1}{\varepsilon \delta} \nabla_{z}\left(\mathcal{T}_{\varepsilon, \delta}^{b l}(u)\right) \quad \text { in } \Sigma \times \frac{1}{\delta} Y .
$$

6. Suppose $N \geqslant 3$ and let $\omega$ be open and bounded in $\mathbb{R}^{N}$. Then the following estimates hold:

$$
\begin{gathered}
\left\|\nabla_{z}\left(\mathcal{T}_{\varepsilon, \delta}^{b l}(u)\right)\right\|_{L^{2}\left(\Sigma \times \frac{1}{\delta} Y\right)}^{2} \leqslant \frac{\varepsilon}{\delta^{N-2}}\|\nabla u\|_{L^{2}\left(\Sigma_{\varepsilon}^{\prime}\right)}^{2}, \\
\left\|\mathcal{T}_{\varepsilon, \delta}^{b l}\left(u-M_{Y}^{\varepsilon, b l}(u)\right)\right\|_{L^{2}\left(\Sigma ; L^{2^{*}}\left(\mathbb{R}^{N}\right)\right)}^{2} \leqslant \frac{C \varepsilon}{\delta^{N-2}}\|\nabla u\|_{L^{2}\left(\Sigma_{\varepsilon}^{\prime}\right)}^{2},
\end{gathered}
$$

and

$$
\left\|\mathcal{T}_{\varepsilon, \delta}^{b l}(u)\right\|_{L^{2}(\Sigma \times \omega)}^{2} \leqslant 2 \frac{C \varepsilon}{\delta^{N-2}}|\omega|^{2 / N}\|\nabla u\|_{L^{2}\left(\Sigma_{\varepsilon}^{\prime}\right)}^{2}+2|\omega|\|u\|_{L^{2}\left(\Sigma_{\varepsilon}^{\prime}\right)}^{2}
$$

where $C$ denotes the Sobolev-Poincaré-Wirtinger constant for $H^{1}(Y)$.
7. Suppose $N \geqslant 3$. Let $\left\{w_{\varepsilon, \delta}\right\}$ be a sequence in $H^{1}\left(\Sigma_{\varepsilon}^{\prime}\right)$ such that $\left\|\nabla w_{\varepsilon, \delta}\right\|_{L^{2}\left(\Sigma_{\varepsilon}^{\prime}\right)}$ is bounded. Then, up to a subsequence, there exist $W$ in $L^{2}\left(\Sigma ; L^{2^{*}}\left(\mathbb{R}^{N}\right)\right)$ with $\nabla_{z} W$ in $L^{2}\left(\Sigma \times \mathbb{R}^{N}\right)$ such that

$$
\begin{gathered}
\frac{\delta^{\frac{N}{2}-1}}{\sqrt{\varepsilon}}\left(\mathcal{T}_{\varepsilon, \delta}\left(w_{\varepsilon, \delta}\right)-M_{Y}^{\varepsilon}\left(w_{\varepsilon, \delta}\right) 1_{\frac{1}{\delta} Y}\right) \rightharpoonup W \\
\text { weakly in } L^{2}\left(\Sigma ; L^{2^{*}}\left(\mathbb{R}^{N}\right)\right), \\
\quad \frac{\delta^{\frac{N}{2}-1}}{\sqrt{\varepsilon}} \nabla_{z}\left(\mathcal{T}_{\varepsilon, \delta}\left(w_{\varepsilon, \delta}\right)\right) 1_{\frac{1}{\delta} Y} \rightharpoonup \nabla_{z} W \\
\text { weakly in } L^{2}\left(\Sigma \times \mathbb{R}^{N}\right)
\end{gathered}
$$

Assuming furthermore that $\lim \sup _{(\varepsilon, \delta) \rightarrow\left(0^{+}, 0^{+}\right)} \frac{\delta^{N / 2-1}}{\sqrt{\varepsilon}}<+\infty$, one can choose the subsequence above and some $U$ in $L^{2}\left(\Sigma ; L_{\text {loc }}^{2}\left(\mathbb{R}^{N}\right)\right)$ with

$$
\frac{\delta^{\frac{N}{2}-1}}{\sqrt{\varepsilon}} \mathcal{T}_{\varepsilon, \delta}\left(w_{\varepsilon, \delta}\right) \rightharpoonup U \quad \text { weakly in } L^{2}\left(\Sigma ; L_{\mathrm{loc}}^{2}\left(\mathbb{R}^{N}\right)\right)
$$

Proposition 2.20 (u.c.i.). If $\left\{w_{\varepsilon}\right\}$ is a sequence in $L^{1}\left(\Sigma_{\varepsilon}^{\prime}\right)$ satisfying,

$$
\int_{\Lambda_{\varepsilon}^{\prime}}\left|w_{\varepsilon}\right| \mathrm{d} x \rightarrow 0
$$

then

$$
\int_{\Sigma_{\varepsilon}^{\prime}} w_{\varepsilon} \mathrm{d} x \stackrel{\mathcal{T}_{\varepsilon, \delta}^{b l}}{\leftrightharpoons} \varepsilon \delta^{N} \int_{\Sigma \times \mathbb{R}^{N}} \mathcal{T}_{\varepsilon, \delta}^{b l}\left(w_{\varepsilon}\right) \mathrm{d} x^{\prime} \mathrm{d} z .
$$

Corollary 2.21. Let $\left\{u_{\varepsilon}\right\} \subset L^{2}\left(\Sigma_{\varepsilon}^{\prime}\right)$ and $\left\{v_{\varepsilon}\right\} \subset L^{p}\left(\Sigma_{\varepsilon}^{\prime}\right)$ with $p>2$, such that $\left\|u_{\varepsilon}\right\|_{L^{2}\left(\Sigma_{\varepsilon}^{\prime}\right)}$ and $\left\|v_{\varepsilon}\right\|_{L^{p}\left(\Sigma_{\varepsilon}^{\prime}\right)}$ are bounded independently of $\varepsilon$. Then

$$
\int_{\Sigma_{\varepsilon}^{\prime}} u_{\varepsilon} v_{\varepsilon} \mathrm{d} x \stackrel{\mathcal{T}_{\varepsilon, \delta}^{b l}}{=} \varepsilon \delta^{N} \int_{\Sigma \times \mathbb{R}^{N}} \mathcal{T}_{\varepsilon, \delta}^{b l}\left(u_{\varepsilon}\right) \mathcal{T}_{\varepsilon, \delta}^{b l}\left(v_{\varepsilon}\right) \mathrm{d} x^{\prime} \mathrm{d} z
$$

For sieve problems, there is a need to distinguish between the subdomains above and below $\Sigma$. Set

$$
\Omega_{+}=\mathbb{R}_{+}^{N} \cap \Omega, \quad \Omega_{-}=\mathbb{R}_{-}^{N} \cap \Omega, \quad Y_{+}=\mathbb{R}_{+}^{N} \cap Y, \quad Y_{-}=\mathbb{R}_{-}^{N} \cap Y .
$$

We suppose that the two domains $\Omega_{+}$and $\Omega_{-}$have a Lipschitz boundary.
For simplicity, we will make the convention that all the results stated for $\Omega_{+}$, are true also for $\Omega_{-}$unless specified otherwise. For any function $u$ defined in $\Omega$, we denote by $u^{+}$its restriction to the domain $\Omega_{+}$, i.e., $\left.u^{+} \equiv u\right|_{\Omega_{+}}$. Analogously, $\left.u^{-} \equiv u\right|_{\Omega_{-}}$.

The corresponding definitions and propositions are the following:
Definition 2.22. The local average $M_{Y_{ \pm}}^{\varepsilon, b l}: L^{p}\left(\Sigma_{\varepsilon \pm}^{\prime}\right) \mapsto L^{p}(\Sigma)$, is defined for every $\phi$ in $L^{p}\left(\Sigma_{\varepsilon \pm}^{\prime}\right), 1 \leqslant p<\infty$, by

$$
M_{Y_{ \pm}}^{\varepsilon, b l}(\phi)\left(x^{\prime}\right) \doteq \frac{\delta^{N}}{\left|Y_{ \pm}\right|} \int_{\frac{1}{\delta} Y_{ \pm}} \mathcal{T}_{\varepsilon, \delta}^{b l}(\phi)\left(x^{\prime}, z\right) \mathrm{d} z .
$$

Proposition 2.23. Let $\left\{w_{\varepsilon}\right\}$ be a sequence such that $w_{\varepsilon} \rightharpoonup w^{ \pm}$weakly in $H^{1}\left(\Omega_{ \pm}\right)$. Then

$$
\left.M_{Y_{ \pm}}^{\varepsilon, b l}\left(w_{\varepsilon}\right) \rightarrow w^{ \pm}\right|_{\Sigma} \quad \text { strongly in } L^{2}(\Sigma) .
$$

Theorem 2.24. 1. For all $\phi \in L^{2}\left(\Omega_{ \pm}\right)$,

$$
\left\|\mathcal{T}_{\varepsilon, \delta}^{b l}(u)\right\|_{L^{2}\left(\Sigma \times \mathbb{R}_{ \pm}^{N}\right)}^{2} \leqslant \frac{1}{\varepsilon \delta^{N}}\|u\|_{L^{2}\left(\Sigma_{\varepsilon \pm}^{\prime}\right)}^{2} .
$$

2. Suppose $N \geqslant 3$ and let $u$ belong to $H^{1}\left(\Omega_{ \pm}\right)$. For every $\omega$ open and bounded in $\mathbb{R}_{+}^{N}$ the following estimates hold:

$$
\begin{gathered}
\left\|\nabla_{z}\left(\mathcal{T}_{\varepsilon, \delta}^{b l}(u)\right)\right\|_{L^{2}\left(\Sigma \times \frac{1}{\delta} Y_{ \pm}\right)}^{2} \leqslant \frac{\varepsilon}{\delta^{N-2}}\|\nabla u\|_{L^{2}\left(\Sigma_{\varepsilon \pm}^{\prime}\right)}^{2}, \\
\left\|\mathcal{T}_{\varepsilon, \delta}^{b l}\left(u-M_{Y}^{\varepsilon, b l}(u)\right)\right\|_{L^{2}\left(\Sigma ; L^{2^{*}}\left(\mathbb{R}_{ \pm}^{N}\right)\right)}^{2} \leqslant \frac{C \varepsilon}{\delta^{N-2}}\|\nabla u\|_{L^{2}\left(\Sigma_{\varepsilon \pm}^{\prime}\right)}^{2},
\end{gathered}
$$

and

$$
\left\|\mathcal{T}_{\varepsilon, \delta}^{b l}(u)\right\|_{L^{2}(\Sigma \times \omega)}^{2} \leqslant 2 \frac{C \varepsilon}{\delta^{N-2}}|\omega|^{2 / N}\|\nabla u\|_{L^{2}\left(\Sigma_{\varepsilon+}^{\prime}\right)}^{2}+2|\omega|\|u\|_{L^{2}\left(\Sigma_{\varepsilon+}^{\prime}\right)}^{2},
$$

where C denotes the Sobolev-Poincaré-Wirtinger constant for $H^{1}\left(Y_{ \pm}\right)$.
A similar inequality is true for bounded open subsets of $\mathbb{R}_{-}^{N}$.
3. Suppose $N \geqslant 3$. Let $\left\{w_{\varepsilon, \delta}\right\}$ be a sequence in $H^{1}\left(\Sigma_{\varepsilon+}^{\prime}\right)$ such that $\left\|\nabla w_{\varepsilon, \delta}\right\|_{L^{2}\left(\Sigma_{\varepsilon+}^{\prime}\right)}$ is bounded. Then, up to a subsequence there exists $W^{+}$in $L^{2}\left(\Sigma ; L^{2^{*}}\left(\mathbb{R}_{ \pm}^{N}\right)\right)$ with $\nabla_{z} W^{+}$in $L^{2}\left(\Sigma \times \mathbb{R}_{+}^{N}\right)$ such that

$$
\begin{gathered}
\frac{\delta^{\frac{N}{2}-1}}{\sqrt{\varepsilon}}\left(\mathcal{T}_{\varepsilon, \delta}^{b l}\left(w_{\varepsilon, \delta}\right)-M_{Y_{+}}^{\varepsilon}\left(w_{\varepsilon, \delta}\right) 1_{\frac{1}{\delta} Y_{+}}\right) \rightharpoonup W^{+} \quad \text { weakly in } L^{2}\left(\Sigma ; L^{2^{*}}\left(\mathbb{R}_{+}^{N}\right)\right), \\
\frac{\delta^{\frac{N}{2}-1}}{\sqrt{\varepsilon}} \nabla_{z}\left(\mathcal{T}_{\varepsilon, \delta}^{b l}\left(w_{\varepsilon, \delta}\right)\right) 1_{\frac{1}{\delta} Y_{+}} \rightharpoonup \nabla_{z} W^{+} \quad \text { weakly in } L^{2}\left(\Sigma \times \mathbb{R}_{+}^{N}\right) .
\end{gathered}
$$

Assuming furthermore that $\lim \sup _{(\varepsilon, \delta) \rightarrow\left(0^{+}, 0^{+}\right)} \frac{\delta^{N / 2-1}}{\sqrt{\varepsilon}}<+\infty$, one can choose the subsequence above and some $U^{+}$in $L^{2}\left(\Sigma ; L_{\mathrm{loc}}^{2}\left(\mathbb{R}_{+}^{N}\right)\right)$ with

$$
\frac{\delta^{\frac{N}{2}-1}}{\sqrt{\varepsilon}} \mathcal{T}_{\varepsilon, \delta}^{b l}\left(w_{\varepsilon, \delta}\right) \rightharpoonup U^{+} \quad \text { weakly in } L^{2}\left(\Sigma ; L_{\mathrm{loc}}^{2}\left(\mathbb{R}_{+}^{N}\right)\right)
$$

The same result holds true for sequences in $H^{1}\left(\Sigma_{\varepsilon-}^{\prime}\right)$.
The equivalent of Proposition 2.20 (u.c.i.) also holds true in $\Omega_{ \pm}$.

## 3. Homogenization in domains with small holes which are periodically distributed in volume

### 3.1. Functional setting

Let $\alpha$ and $\beta$ be two real numbers such that $0<\alpha<\beta$. For any open set $\mathcal{O}$ in $\mathbb{R}^{N}$, denote by $M(\alpha, \beta, \mathcal{O})$ the set of the $N \times N$ matrix-fields $A=\left(a_{i j}\right)_{1 \leqslant i, j \leqslant N} \in\left(L^{\infty}(\mathcal{O})\right)^{N \times N}$ such that

$$
\alpha|\lambda|^{2} \leqslant(A(x) \lambda, \lambda) \quad \text { and } \quad|A(x) \lambda|^{2} \leqslant \beta(A(x) \lambda, \lambda),
$$

for any $\lambda \in \mathbb{R}^{N}$ and a.e. $x$ in $\mathcal{O}$.
The perforated domain $\Omega_{\varepsilon, \delta}^{*}$ is defined by (2.3). Assume that the matrix field $A^{\varepsilon}(x)=\left(a_{i j}^{\varepsilon}(x)\right)_{1 \leqslant i, j \leqslant N}$ belongs to $M(\alpha, \beta, \Omega)$. For $f \in L^{2}(\Omega)$, consider the following problem:

$$
\left\{\begin{array}{l}
\text { Find } u_{\varepsilon, \delta} \in H_{0}^{1}\left(\Omega_{\varepsilon, \delta}^{*}\right) \text { satisfying } \\
\int_{\Omega_{\varepsilon, \delta}^{*}} A^{\varepsilon} \nabla u_{\varepsilon, \delta} \nabla \phi=\int_{\Omega_{\varepsilon, \delta}^{*}} f \phi, \\
\forall \phi \in H_{0}^{1}\left(\Omega_{\varepsilon, \delta}^{*}\right) .
\end{array}\right.
$$

In this section we suppose that $N \geqslant 3$ and study the asymptotic behavior of problem ( $\mathcal{P}_{\varepsilon, \delta}$ ) as $\varepsilon$ and $\delta=\delta(\varepsilon)$ are such that there exists a positive constant $k_{1}$ satisfying,

$$
\begin{equation*}
k_{1}=\lim _{\varepsilon \rightarrow 0} \frac{\delta^{\frac{N}{2}-1}}{\varepsilon}, \quad \text { with } 0 \leqslant k_{1}<\infty \tag{3.1}
\end{equation*}
$$

### 3.2. Unfolded homogenization result

We now derive the unfolded formulation of the limit problem for $\mathcal{P}_{\varepsilon, \delta}$. In the limit we will observe the contribution of the periodic oscillations as well as the contribution of the perforations.

In order to state the result, we introduce the functional space $K_{B}$ defined as follows:

$$
\begin{equation*}
K_{B}=\left\{\Phi \in L^{2^{*}}\left(\mathbb{R}^{N}\right) ; \nabla \Phi \in L^{2}\left(\mathbb{R}^{N}\right), \Phi \text { constant on } B\right\} . \tag{3.2}
\end{equation*}
$$

Theorem 3.1. Let $A^{\varepsilon}$ belong to $M(\alpha, \beta, \Omega)$. Suppose that, as $\varepsilon$ goes to 0 , there exists a matrix $A$ such that

$$
\mathcal{T}_{\varepsilon}\left(A^{\varepsilon}\right)(x, y) \rightarrow A(x, y) \quad \text { a.e. in } \Omega \times Y .
$$

Furthermore, suppose that there exists a matrix field $A_{0}$ such that as $\varepsilon$ and $\delta \rightarrow 0$,

$$
\begin{equation*}
\mathcal{T}_{\varepsilon, \delta}\left(A^{\varepsilon}\right)(x, z) \rightarrow A_{0}(x, z) \quad \text { a.e. in } \Omega \times\left(\mathbb{R}^{N} \backslash B\right) . \tag{3.3}
\end{equation*}
$$

Let $u_{\varepsilon, \delta}$ be the solution of the problem $\left(\mathcal{P}_{\varepsilon, \delta}\right)$. Then

$$
\begin{equation*}
u_{\varepsilon, \delta} \rightharpoonup u_{0} \quad \text { weakly in } H_{0}^{1}(\Omega), \tag{3.4}
\end{equation*}
$$

and there exists $\hat{u}$ in $L^{2}\left(\Omega ; H_{p e r}^{1}(Y)\right)$, and $U$ vanishing on $\Omega \times B$ with $U-k_{1} u_{0}$ belonging to $L^{2}\left(\Omega ; K_{B}\right)$, such that the triplet $\left(u_{0}, \hat{u}, U\right)$ satisfies the following three conditions:

$$
\begin{equation*}
\int_{Y} A(x, y)\left(\nabla_{x} u_{0}(x)+\nabla_{y} \hat{u}(x, y)\right) \nabla_{y} \phi(y) \mathrm{d} y=0, \tag{3.5}
\end{equation*}
$$

for a.e. $x$ in $\Omega$ and all $\phi \in H_{p e r}^{1}(Y)$;

$$
\begin{equation*}
\int_{\mathbb{R}^{N} \backslash B} A_{0}(x, z) \nabla_{z} U(x, z) \nabla_{z} v(z) \mathrm{d} z=0, \tag{3.6}
\end{equation*}
$$

for a.e. $x$ in $\Omega$ and all $v \in K_{B}$ with $v(B)=0$;

$$
\begin{equation*}
\int_{\Omega \times Y} A\left(\nabla_{x} u_{0}+\nabla_{y} \hat{u}\right) \nabla \psi \mathrm{d} x \mathrm{~d} y-k_{1} \int_{\Omega \times \partial B} A_{0} \nabla_{z} U \nu_{B} \psi \mathrm{~d} \sigma_{z}=\int_{\Omega} f \psi \mathrm{~d} x, \tag{3.7}
\end{equation*}
$$

for all $\psi \in H_{0}^{1}(\Omega)$, where $\nu_{B}$ is the inward normal on $\partial B$ and $\mathrm{d} \sigma_{z}$ the surface measure.

The proof of this theorem, makes use of the next two elementary results.
Lemma 3.2. Let $N \geqslant 3$. Then, for every $\delta_{0}>0$, the set

$$
\bigcup_{0<\delta<\delta_{0}}\left\{\phi \in H_{p e r}^{1}(Y) ; \phi=0 \text { on } \delta B\right\}
$$

is dense in $H_{p e r}^{1}(Y)$.
Proof. Let $\psi \in C_{p e r}^{\infty}(\bar{Y})$ be fixed. For $\delta_{k} \xrightarrow{k \rightarrow \infty} 0$ consider $\phi_{k} \in H_{p e r}^{1}(Y)$ smooth with

$$
\phi_{k}= \begin{cases}0 & \text { on } \delta_{k} B \\ 1 & \text { on } Y \backslash 2 \delta_{k} B\end{cases}
$$

and such that $\left|\nabla \phi_{k}\right| \leqslant \frac{C}{\delta_{k}}$. Define $\Phi_{k}=\phi_{k} \psi$. We claim that $\Phi_{k}$ converges to $\psi$ strongly in $H_{p e r}^{1}(Y)$. To do so, observe that

$$
\left\|\Phi_{k}-\psi\right\|_{L^{2}(Y)}+\left\|\nabla \Phi_{k}-\nabla \psi\right\|_{L^{2}(Y)} \leqslant \int_{2 \delta_{k} B}|\psi|^{2} \mathrm{~d} y+\int_{2 \delta_{k} B}|\nabla \psi|^{2} \mathrm{~d} y+\int_{2 \delta_{k} B}\left|\nabla \phi_{k}\right|^{2}|\psi|^{2} \mathrm{~d} y
$$

For the last integral, using the definition of $\phi_{k}$, one gets:

$$
\int_{2 \delta_{k} B}\left|\nabla \phi_{k}\right|^{2}|\psi|^{2} \mathrm{~d} y \leqslant C^{2} \delta_{k}^{N-2}\|\psi\|_{L^{\infty}(Y)}^{2}
$$

Hence,

$$
\Phi_{k} \rightarrow \psi \quad \text { strongly in } H_{p e r}^{1}(Y)
$$

Since $H_{p e r}^{1}(Y)$ is the closure of $C_{p e r}^{\infty}(\bar{Y})$ in the $H^{1}$-norm, a density argument completes the proof.
Lemma 3.3. Let $v$ in $\mathcal{D}\left(\mathbb{R}^{N}\right) \cap K_{B}$ (i.e. $v=$ const. $=v(B)$ on $B$ ), and set

$$
w_{\varepsilon, \delta}(x)=v(B)-v\left(\frac{1}{\delta}\left\{\frac{x}{\varepsilon}\right\}_{Y}\right) \quad \text { for } x \in \mathbb{R}^{N}
$$

Then,

$$
\begin{equation*}
w_{\varepsilon, \delta} \rightharpoonup v(B) \quad \text { weakly in } H^{1}(\Omega) \tag{3.8}
\end{equation*}
$$

Proof. For $\delta$ small enough, the support of $v$ is compact in $\frac{1}{\delta} Y$ and consequently,

$$
\int_{\frac{1}{\delta} Y}|v(z)|^{2} \mathrm{~d} z=\|v\|_{L^{2}\left(\mathbb{R}^{n}\right)}^{2}
$$

Clearly, $w_{\varepsilon, \delta}$ is uniformly bounded on $\mathbb{R}^{N}$. Observe that the set where $w_{\varepsilon, \delta}$ differs from $v(B)$ is $\bigcup_{\xi \in \mathbb{Z}^{N}}(\varepsilon \xi+\varepsilon \delta\{\operatorname{Support}(v)\})$, so that the measure of its intersection with $\Omega$, is at most of order $\delta^{N}$. Thus, $w_{\varepsilon, \delta}$ converges to $v(B)$ in every $L^{q}(\Omega)$ for finite $q$.

Since $\mathcal{T}_{\varepsilon, \delta}\left(w_{\varepsilon}\right)(x, z)=v(B)-v(z)$, property (5) from Theorem 2.11 gives:

$$
\begin{equation*}
\mathcal{T}_{\varepsilon, \delta}\left(\nabla w_{\varepsilon, \delta}\right)=-\frac{1}{\varepsilon \delta} \nabla_{z} v \quad \text { in } \widehat{\Omega}_{\varepsilon} \times \frac{1}{\delta} Y \tag{3.9}
\end{equation*}
$$

hence (see Theorem 2.2(2)),

$$
\left\|\nabla w_{\varepsilon, \delta}\right\|_{L^{2}\left(\hat{\Omega}_{\varepsilon}\right)}^{2}=\delta^{N}\left\|T_{\varepsilon, \delta}\left(\nabla w_{\varepsilon, \delta}\right)\right\|_{L^{2}\left(\Omega \times \frac{1}{\delta} Y\right)}^{2} \leqslant \frac{\delta^{N-2}}{\varepsilon^{2}}|\Omega|\left\|\nabla_{z} v\right\|_{L^{2}\left(\mathbb{R}^{N}\right)}^{2}
$$

Due to (3.1), $\nabla w_{\varepsilon, \delta}$ is bounded in $L_{\text {loc }}^{2}(\Omega)$ which concludes the proof, since $w_{\varepsilon, \delta}$ is $\varepsilon Y$-periodic in $\mathbb{R}^{N}$.

Proof of Theorem 3.1 (for the case $k_{1}>0$ ). Observe first that by the Lax-Milgram theorem, there exists a unique solution $u_{\varepsilon, \delta}$ of $\left(\mathcal{P}_{\varepsilon, \delta}\right)$ and it satisfies

$$
\begin{equation*}
\left\|u_{\varepsilon, \delta}\right\|_{H_{0}^{1}\left(\Omega_{\varepsilon, \delta}^{*}\right)} \leqslant C\|f\|_{L^{2}(\Omega)}, \tag{3.10}
\end{equation*}
$$

which implies convergence (3.4), up to a subsequence. Next, by Theorem 2.2(6), there exists $\hat{u} \in L^{2}\left(\Omega ; H_{p e r}^{1}(Y)\right)$ such that

$$
\begin{equation*}
\mathcal{T}_{\varepsilon}\left(\nabla u_{\varepsilon, \delta}\right) \rightharpoonup \nabla_{x} u_{0}+\nabla_{y} \hat{u} \quad \text { weakly in } L^{2}(\Omega \times Y) . \tag{3.11}
\end{equation*}
$$

By Theorem 2.11(7), there exists some $U$ in $L^{2}\left(\Omega ; L_{\mathrm{loc}}^{2}\left(\mathbb{R}^{N}\right)\right)$ such that, up to a subsequence,

$$
\begin{equation*}
\frac{\delta^{\frac{N}{2}-1}}{\varepsilon} \mathcal{T}_{\varepsilon, \delta}\left(u_{\varepsilon, \delta}\right) \rightharpoonup U \quad \text { weakly in } L^{2}\left(\Omega ; L_{\mathrm{loc}}^{2}\left(\mathbb{R}^{N}\right)\right) \tag{3.12}
\end{equation*}
$$

By Proposition 2.9, one has

$$
\begin{equation*}
\frac{\delta^{\frac{N}{2}-1}}{\varepsilon} M_{Y}^{\varepsilon}\left(u_{\varepsilon, \delta}\right) 1_{\frac{1}{\delta} Y} \rightarrow k_{1} u_{0} \quad \text { strongly in } L^{2}\left(\Omega ; L_{\mathrm{loc}}^{2}\left(\mathbb{R}^{N}\right)\right) . \tag{3.13}
\end{equation*}
$$

On the other hand, by Theorem 2.11(7) there exists a $W$ in $L^{2}\left(\Omega ; L^{2^{*}}\left(\mathbb{R}^{N}\right)\right)$ with $\nabla_{z} W$ in $L^{2}\left(\Omega \times \mathbb{R}^{N}\right)$ such that

$$
\begin{equation*}
\frac{\delta^{\frac{N}{2}-1}}{\varepsilon}\left(\mathcal{T}_{\varepsilon, \delta}\left(u_{\varepsilon, \delta}\right)-M_{Y}^{\varepsilon}\left(u_{\varepsilon, \delta}\right) 1_{\frac{1}{\delta} Y}\right) \rightharpoonup W \quad \text { weakly in } L^{2}\left(\Omega ; L^{2^{*}}\left(\mathbb{R}^{N}\right)\right) . \tag{3.14}
\end{equation*}
$$

From (3.12), (3.13) and (3.14), one concludes:

$$
U=W+k_{1} u_{0}, \quad \text { and } \quad \nabla_{z} U=\nabla_{z} W
$$

and, by Theorem 2.11(5) and (7) again

$$
\begin{equation*}
\frac{\delta^{\frac{N}{2}-1}}{\varepsilon} \nabla_{z}\left(\mathcal{T}_{\varepsilon, \delta}\left(u_{\varepsilon, \delta}\right)\right) 1_{\frac{1}{\delta} Y}=\delta^{\frac{N}{2}} \mathcal{T}_{\varepsilon, \delta}\left(\nabla u_{\varepsilon, \delta}\right) \rightharpoonup \nabla_{z} U \quad \text { weakly in } L^{2}\left(\Omega \times \mathbb{R}^{N}\right) . \tag{3.15}
\end{equation*}
$$

From Definition 2.10, $\mathcal{T}_{\varepsilon, \delta}\left(u_{\varepsilon, \delta}\right)=0$ in $\Omega \times B$, so that by (3.12),

$$
\begin{equation*}
U=0 \quad \text { on } \Omega \times B . \tag{3.16}
\end{equation*}
$$

Due to (3.16), $W=U-k_{1} u_{0}$ actually belongs to $L^{2}\left(\Omega ; K_{B}\right)$.
Using $\Phi(\cdot)=\varepsilon \psi(\cdot) \phi(\dot{\bar{\varepsilon}})$ as a test function in $\left(\mathcal{P}_{\varepsilon, \delta}\right)$, with $\psi \in \mathcal{D}(\Omega)$ and $\phi \in C_{p e r}^{1}(Y)$ vanishing in a neighborhood of the origin, we have:

$$
\varepsilon \int_{\Omega_{\varepsilon, \delta}^{*}} A^{\varepsilon} \nabla u_{\varepsilon, \delta} \nabla \psi \phi\left(\frac{\cdot}{\varepsilon}\right)+\int_{\Omega_{\varepsilon, \delta}^{*}} A^{\varepsilon} \nabla u_{\varepsilon, \delta} \psi \nabla \phi\left(\frac{\cdot}{\varepsilon}\right)=\varepsilon \int_{\Omega_{\varepsilon, \delta}^{*}} f \psi \phi\left(\frac{\cdot}{\varepsilon}\right) .
$$

It is easy to see that the first integral as well as the right-hand side of the above equality converge to zero. The second integral above is unfolded with $\mathcal{T}_{\varepsilon}$ noting that $\mathcal{T}_{\varepsilon}(\nabla \phi(\cdot / \varepsilon))(x, y)=\nabla \phi(y)$. Applying Theorem 2.2(1) and (4), then Corollary 2.5 , one gets:

$$
\begin{equation*}
\int_{\Omega_{\varepsilon, \delta}^{*}} A^{\varepsilon} \nabla u_{\varepsilon, \delta} \psi \nabla \phi\left(\frac{\dot{\varepsilon}}{\varepsilon}\right) \stackrel{\mathcal{T}_{\varepsilon}}{=} \int_{\Omega \times Y} \mathcal{T}_{\varepsilon}\left(A^{\varepsilon}\right)(x, y) \mathcal{T}_{\varepsilon}\left(\nabla_{x} u_{\varepsilon, \delta}\right)(x, y) \nabla \phi(y) \mathcal{T}_{\varepsilon}(\psi)(x, y) \mathrm{d} x \mathrm{~d} y \tag{3.17}
\end{equation*}
$$

(the unfolding criterion of integrals (u.c.i.) is trivially satisfied since $\psi$ is compactly supported in $\Omega$ ). From (3.11), we can pass to the limit with respect to $\varepsilon$ in (3.17). Then, by Lemma 3.2, we obtain (3.5), the first equation of the unfolded formulation for the limit problem. This equation describes the effect of the periodic oscillations of the coefficients in ( $\mathcal{P}_{\varepsilon, \delta}$ ).

In order to describe the contribution of the perforations, we use the function $w_{\varepsilon, \delta}$ introduced in Lemma 3.3. For $\psi$ in $\mathcal{D}(\Omega)$, use $w_{\varepsilon, \delta} \psi$ as a test function in ( $\mathcal{P}_{\varepsilon, \delta}$ ). By the definition of $w_{\varepsilon, \delta}$ this function vanishes on the holes and by the choice of $\psi$, it vanishes near the boundary of $\Omega$. Thus, we obtain,

$$
\begin{equation*}
\int_{\Omega_{\varepsilon, \delta}^{*}} A^{\varepsilon} \nabla u_{\varepsilon, \delta} \nabla w_{\varepsilon, \delta} \psi+\int_{\Omega_{\varepsilon, \delta}^{*}} A^{\varepsilon} \nabla u_{\varepsilon, \delta} \nabla \psi w_{\varepsilon, \delta}=\int_{\Omega_{\varepsilon, \delta}^{*}} f w_{\varepsilon, \delta} \psi . \tag{3.18}
\end{equation*}
$$

The first term in (3.18) is unfolded with $\mathcal{T}_{\varepsilon, \delta}$. Again, the choice of the test function implies that the u.c.i. is satisfied, so by Theorem 2.11 and Corollary 2.14, we can write,

$$
\begin{equation*}
\int_{\Omega_{\varepsilon, \delta}^{*}} A^{\varepsilon} \nabla u_{\varepsilon, \delta} \nabla w_{\varepsilon, \delta} \psi \stackrel{\mathcal{T}_{\varepsilon, \delta}}{=} \delta^{N} \int_{\Omega \times \mathbb{R}^{N}} \mathcal{T}_{\varepsilon, \delta}\left(A^{\varepsilon}\right) \mathcal{T}_{\varepsilon, \delta}\left(\nabla u_{\varepsilon, \delta}\right) \mathcal{T}_{\varepsilon, \delta}\left(\nabla w_{\varepsilon, \delta}\right) \mathcal{T}_{\varepsilon, \delta}(\psi) . \tag{3.19}
\end{equation*}
$$

Therefore (3.19), together with (3.9), yields

$$
\begin{equation*}
\int_{\Omega_{\varepsilon, \delta}^{*}} A^{\varepsilon} \nabla u_{\varepsilon, \delta} \nabla w_{\varepsilon, \delta} \psi \stackrel{\mathcal{T}_{\varepsilon, \delta}}{=} \frac{\delta^{\frac{N}{2}-1}}{\varepsilon} \int_{\Omega \times \mathbb{R}^{N}} \mathcal{T}_{\varepsilon, \delta}\left(A^{\varepsilon}\right) \delta^{\frac{N}{2}} \mathcal{T}_{\varepsilon, \delta}\left(\nabla u_{\varepsilon, \delta}\right)\left(-\nabla_{z} v\right) \mathcal{T}_{\varepsilon, \delta}(\psi) . \tag{3.20}
\end{equation*}
$$

From the following obvious inequality,

$$
\left\|\mathcal{T}_{\varepsilon, \delta}(\psi)-\psi\right\|_{L^{\infty}\left(\widehat{\Omega}_{\varepsilon} \times \frac{1}{\delta} Y\right)} \leqslant C \varepsilon\|\nabla \psi\|_{L^{\infty}(\Omega)},
$$

we obtain:

$$
\begin{equation*}
\mathcal{T}_{\varepsilon, \delta}(\psi) \nabla_{z} v \rightarrow \psi \nabla_{z} v \quad \text { strongly in } L^{2}\left(\Omega \times \mathbb{R}^{N}\right) \tag{3.21}
\end{equation*}
$$

Convergences (3.15), (3.21), as well as hypothesis (3.3), allows us to pass to the limit in (3.20) to obtain:

$$
\begin{equation*}
\lim _{\varepsilon \rightarrow 0} \int_{\Omega_{\varepsilon, \delta}^{*}} A^{\varepsilon} \nabla u_{\varepsilon, \delta} \nabla w_{\varepsilon, \delta} \psi \mathrm{d} x=-k_{1} \int_{\Omega \times\left(\mathbb{R}^{N} \backslash B\right)} A_{0}(x, z) \nabla_{z} U(x, z) \nabla_{z} v(z) \psi(x) \mathrm{d} x \mathrm{~d} z, \tag{3.22}
\end{equation*}
$$

which by density, is true for every $v \in K_{B}$.
The second term in (3.18) is unfolded with $\mathcal{T}_{\varepsilon}$ and we have,

$$
\int_{\Omega_{\varepsilon, \delta}^{*}} A^{\varepsilon} \nabla u_{\varepsilon, \delta} w_{\varepsilon, \delta} \nabla \psi \stackrel{\mathcal{T}_{\varepsilon}}{\cong} \int_{\Omega \times Y} \mathcal{T}_{\varepsilon}\left(A^{\varepsilon}\right) \mathcal{T}_{\varepsilon}\left(\nabla u_{\varepsilon, \delta}\right) \mathcal{T}_{\varepsilon}\left(w_{\varepsilon, \delta}\right) \mathcal{T}_{\varepsilon}(\nabla \psi) .
$$

Using Theorem 2.2(5) and convergences (3.8) and (3.11), we can pass to the limit with respect to $\varepsilon$ in the above equality to get:

$$
\begin{equation*}
\lim _{\varepsilon \rightarrow 0} \int_{\Omega_{\varepsilon, \delta}^{*}} A^{\varepsilon} \nabla u_{\varepsilon, \delta} w_{\varepsilon, \delta} \nabla \psi=v(B) \int_{\Omega \times Y} A\left(\nabla_{x} u_{0}+\nabla_{y} \hat{u}\right) \nabla_{x} \psi, \tag{3.23}
\end{equation*}
$$

where we also used the fact that $\mathcal{T}_{\varepsilon}(\nabla \psi)$ converges uniformly to $\nabla \psi$ (hence strongly in every $L^{q}(\Omega \times Y)$ for $1 \leqslant q \leqslant \infty)$.

Passing to the limit with respect to $\varepsilon$ in (3.18) and using (3.22) and (3.23), we obtain,

$$
\begin{equation*}
v(B) \int_{\Omega \times Y} A\left(\nabla_{x} u_{0}+\nabla_{y} \hat{u}\right) \nabla \psi-k_{1} \int_{\Omega \times\left(\mathbb{R}^{N} \backslash B\right)} A_{0} \nabla_{z} U \nabla v \psi=v(B) \int_{\Omega} f \psi, \tag{3.24}
\end{equation*}
$$

which, by density, holds true for all $\psi \in H_{0}^{1}(\Omega)$ and $v \in K_{B}$. Choosing $v(B)=0$ in (3.24) yields Eq. (3.6), whereupon the Stokes formula transforms (3.24) into (3.7). This concludes the proof of the theorem.

### 3.3. Standard form for the limit problem

Here we show that the unfolded problem is well-posed and we give the formulation in terms of the macroscopic solution $u_{0}$ alone.

First, consider the classical correctors $\widehat{\chi}_{j}, j=1, \ldots, N$, defined by the cell problems (see [5]),

$$
\left\{\begin{array}{l}
\widehat{\chi}_{j} \in L^{\infty}\left(\Omega ; H_{p e r}^{1}(Y)\right),  \tag{3.25}\\
\int_{Y} A(x, y) \nabla\left(\widehat{\chi}_{j}-y_{j}\right) \nabla \phi \mathrm{d} y=0 \quad \text { a.e. } x \in \Omega, \\
\forall \phi \in H_{p e r}^{1}(Y)
\end{array}\right.
$$

Assuming $u_{0}$ is known and solving Eq. (3.5) for $\hat{u}$ as a function of $u_{0}$, gives:

$$
\hat{u}(x, y)=-\sum_{j=1}^{N} \frac{\partial u_{0}}{\partial x_{j}}(x) \widehat{\chi}_{j}(x, y),
$$

which used in Eq. (3.7) from Theorem 3.1 yields

$$
\begin{equation*}
\int_{\Omega} \mathcal{A}^{\mathrm{hom}} \nabla u_{0} \nabla \psi \mathrm{~d} x-k_{1} \int_{\Omega \times \partial B} A_{0} \nabla_{z} U v_{B} \psi \mathrm{~d} \sigma_{z}=\int_{\Omega} f \psi \mathrm{~d} x, \tag{3.26}
\end{equation*}
$$

where, for a.e. $x$ in $\Omega, \mathcal{A}^{\text {hom }}(x)$ is the homogenized matrix defined as

$$
\begin{equation*}
\mathcal{A}_{i j}^{\mathrm{hom}}(x)=\int_{Y}\left(a_{i j}(x, y)-\sum_{k=1}^{N} a_{i k}(x, y) \frac{\partial \widehat{\chi}_{j}}{\partial y_{k}}(x, y)\right) \mathrm{d} y . \tag{3.27}
\end{equation*}
$$

Eq. (3.26) is the variational formulation for

$$
\begin{equation*}
-\operatorname{div}\left(\mathcal{A}^{\text {hom }} \nabla u_{0}\right)-k_{1} \int_{\partial B} A_{0} \nabla_{z} U \nu_{B} \mathrm{~d} \sigma_{z}=f \tag{3.28}
\end{equation*}
$$

It remains to clarify the connection between the second term in (3.28) and $u_{0}$. In order to do so, let $\theta$ be the solution of the corresponding "cell problem":

$$
\left\{\begin{array}{l}
\theta \in L^{\infty}\left(\Omega ; K_{B}\right), \quad \theta(x, B) \equiv 1,  \tag{3.29}\\
\int_{\mathbb{R}^{N} \backslash B}^{t} A_{0}(x, z) \nabla_{z} \theta(x, z) \nabla_{z} \Psi(z) \mathrm{d} z=0 \quad \text { a.e. for } x \in \Omega, \\
\forall \Psi \in K_{B} \text { with } \Psi(B)=0 .
\end{array}\right.
$$

From (3.29), (3.16) and Green's formula together with Eq. (3.6), we get:

$$
\int_{\partial B} A_{0} \nabla_{z} U \nu_{B} \mathrm{~d} \sigma_{z}=\int_{\partial B} A_{0} \nabla_{z}\left(U-k_{1} u_{0}\right) v_{B} \mathrm{~d} \sigma_{z}=-k_{1} u_{0}\left(\int_{\partial B}{ }^{t} A_{0} \nabla_{z} \theta v_{B} \mathrm{~d} \sigma_{z}\right),
$$

so that Eq. (3.28) becomes

$$
-\operatorname{div}\left(\mathcal{A}^{\text {hom }} \nabla u_{0}\right)+k_{1}^{2} \boldsymbol{\Theta} u_{0}=f
$$

where

$$
\begin{equation*}
\boldsymbol{\Theta}(x) \doteq \int_{\partial B}^{t} A_{0}(x, z) \nabla_{z} \theta(x, z) \nu_{B} \mathrm{~d} \sigma_{z} . \tag{3.30}
\end{equation*}
$$

Remark 3.4. From definition (3.30) the function $\boldsymbol{\Theta}(x)$ equals,

$$
\boldsymbol{\Theta}(x)=\int_{\mathbb{R}^{N} \backslash B} A_{0}(x, z) \nabla_{z} \theta(x, z) \nabla_{z} \theta(x, z) \mathrm{d} z,
$$

which is non-negative and can be interpreted as the local capacity of the set $B$.
In conclusion, by Lax-Milgram's theorem, we have:
Theorem 3.5. The limit function $u_{0}$ given by Theorem 3.1 is the unique solution of the homogenized equation:

$$
\left\{\begin{array}{l}
u_{0} \in H_{0}^{1}(\Omega),  \tag{3.31}\\
\int_{\Omega} \mathcal{A}^{\text {hom }} \nabla u_{0} \nabla \psi+k_{1}^{2} \int_{\Omega} \boldsymbol{\Theta} u_{0} \psi=\int_{\Omega} f \psi, \\
\forall \psi \in H_{0}^{1}(\Omega)
\end{array}\right.
$$



Fig. 5. An example of set $\Omega_{\varepsilon, \delta}^{\prime}$ : an electrostatic screen.
Remark 3.6. The contribution of the oscillations of the matrix $A^{\varepsilon}$ in the homogenized problem are reflected by the first term of the left-hand side in (3.31). The contribution of the perforations is the zero order "strange term" $k_{1}^{2} \boldsymbol{\Theta}(x) u_{0}$.

## Remark 3.7.

1. The proof is actually simpler for the case $k_{1}=0$ and the statement is included in Theorem 3.5: the small holes have no influence at the limit.
2. The case of $\lim \frac{\delta^{\frac{N}{2}-1}}{\varepsilon}=\infty$ is easy to analyze: from Theorem 2.11(6),

$$
\mathcal{T}_{\varepsilon, \delta}\left(u_{\varepsilon, \delta}\right) \rightharpoonup u_{0} \quad \text { weakly in } L^{2}\left(\Omega ; L_{\mathrm{loc}}^{2}\left(\mathbb{R}^{N}\right)\right) .
$$

On the other hand, since $\mathcal{T}_{\varepsilon, \delta}\left(u_{\varepsilon, \delta}\right)=0$ in $\Omega \times B$, this implies that $u_{0}=0$.

## 4. Homogenization in domains with small holes which are periodically distributed in a layer

### 4.1. Functional setting

As in the preceding section, we suppose that $N \geqslant 3$. We use the notations introduced in Section 2.3 for domains with small holes contained in the layer $\Sigma_{\varepsilon}^{\prime}$. The corresponding perforated layer $\Sigma_{\varepsilon, \delta}^{\prime}$ is given by:

$$
\Sigma_{\varepsilon, \delta}^{\prime}=\left\{x \in \Sigma_{\varepsilon}^{\prime} \text { such that }\left\{\frac{x}{\varepsilon}\right\}_{Y} \in Y_{\delta}^{*}\right\} .
$$

The perforated domain is now (see Fig. 5 for an example),

$$
\Omega_{\varepsilon, \delta}^{\prime}=\Omega \backslash\left\{x \in \Sigma_{\varepsilon}^{\prime} \text { such that }\left\{\frac{x}{\varepsilon}\right\}_{Y} \in \delta B\right\} .
$$

The small perforations are of size $\varepsilon \delta$ with $\delta=\delta(\varepsilon)$ satisfying,

$$
\begin{equation*}
k_{2}=\lim _{\varepsilon \rightarrow 0} \frac{\delta^{\frac{N}{2}-1}}{\sqrt{\varepsilon}}, \quad \text { where } 0 \leqslant k_{2}<\infty \tag{4.1}
\end{equation*}
$$

We consider the asymptotic behavior for the following problem:

$$
\left\{\begin{array}{l}
\text { Find } u_{\varepsilon, \delta} \in H_{0}^{1}\left(\Omega_{\varepsilon, \delta}^{\prime}\right) \text { satisfying } \\
\int_{\Omega_{\varepsilon, \delta}^{\prime}} A^{\varepsilon} \nabla u_{\varepsilon, \delta} \nabla \phi=\int_{\Omega_{\varepsilon, \delta}^{\prime}} f \phi, \quad f \in L^{2}(\Omega), \\
\forall \phi \in H_{0}^{1}\left(\Omega_{\varepsilon, \delta}^{\prime} .\right.
\end{array}\right.
$$

### 4.2. Unfolded homogenization result

Theorem 4.1. Let $A^{\varepsilon}$ belong to $M(\alpha, \beta, \Omega)$. Suppose that, as $\varepsilon$ goes to 0 , there exists a matrix A such that

$$
\mathcal{T}_{\varepsilon}\left(A^{\varepsilon}\right)(x, y) \rightarrow A(x, y) \quad \text { a.e. in } \Omega \times Y .
$$

Furthermore, suppose that there exists a matrix field $A_{0}$ such that, as $\varepsilon$ and $\delta \rightarrow 0$,

$$
\begin{equation*}
\mathcal{T}_{\varepsilon, \delta}^{b l}\left(A^{\varepsilon}\right)\left(x^{\prime}, z\right) \rightarrow A_{0}\left(x^{\prime}, z\right) \quad \text { a.e. in } \Sigma \times\left(\mathbb{R}^{N} \backslash B\right) . \tag{4.2}
\end{equation*}
$$

Let $u_{\varepsilon, \delta}$ be the solution of the problem $\left(\mathcal{P}_{\varepsilon, \delta}\right)$. Then

$$
u_{\varepsilon, \delta} \rightharpoonup u_{0} \quad \text { weakly in } H_{0}^{1}(\Omega),
$$

and there exists $\hat{u} \in L^{2}\left(\Omega ; H_{p e r}^{1}(Y)\right)$, and $U$ satisfying (4.11) with $U-k_{2} u_{0}$ in $L^{2}\left(\Sigma ; K_{B}\right)$, such that $\left(u_{0}, \hat{u}, U\right)$ solves the equations

$$
\begin{equation*}
\int_{Y} A(x, y)\left(\nabla_{x} u_{0}(x)+\nabla_{y} \hat{u}(x, y)\right) \nabla_{y} \phi(y) \mathrm{d} y=0, \tag{4.3}
\end{equation*}
$$

for a.e. $x$ in $\Omega$ and all $\phi \in H_{p e r}^{1}(Y)$;

$$
\begin{equation*}
\int_{\mathbb{R}^{N} \backslash B} A_{0}\left(x^{\prime}, z\right) \nabla_{z} U\left(x^{\prime}, z\right) \nabla_{z} v(z) \mathrm{d} z=0, \tag{4.4}
\end{equation*}
$$

for a.e. $x^{\prime}$ in $\Sigma$ and all $v \in K_{B}$ with $v(B)=0$;

$$
\begin{equation*}
\int_{\Omega \times Y} A\left(\nabla_{x} u_{0}+\nabla_{y} \hat{u}\right) \nabla \psi-k_{2} \int_{\Sigma \times \partial B} A_{0} \nabla_{z} U \nu_{B} \psi \mathrm{~d} \sigma_{z}=\int_{\Omega} f \psi, \tag{4.5}
\end{equation*}
$$

for all $\psi \in H_{0}^{1}(\Omega)$, where $\nu_{B}$ and $\mathrm{d} \sigma_{z}$ are the inward normal and the surface measure on $\partial B$.
For the proof of this theorem, we need the equivalent of Lemma 3.3 with a similar proof (where $\mathcal{T}_{\varepsilon, \delta}$ is replaced by $\mathcal{T}_{\varepsilon, \delta}^{b l}$.

Lemma 4.2. Let $v$ in $\mathcal{D}\left(\mathbb{R}^{N}\right) \cap K_{B}$ and, for $\delta$ small enough, set

$$
w_{\varepsilon, \delta}^{b l}(x)=v(B)-v\left(\frac{1}{\delta}\left\{\frac{x^{\prime}}{\varepsilon}\right\}_{Y}, \frac{x_{N}}{\varepsilon \delta}\right) \quad \text { for } x \in \mathbb{R}^{N} .
$$

Then,

$$
\begin{equation*}
w_{\varepsilon, \delta}^{b l} \rightharpoonup v(B) \quad \text { weakly in } H^{1}(\Omega) . \tag{4.6}
\end{equation*}
$$

Proof of Theorem 4.1 (for the case $k_{2}>0$ ). We denote $u_{\varepsilon, \delta}$ the extension by zero to the whole of $\Omega$ of the solution of $\left(\mathcal{P}_{\varepsilon, \delta}^{\prime}\right)$. The reasoning is similar to that of the previous section. The following estimate is straightforward from $\left(\mathcal{P}_{\varepsilon, \delta}^{\prime}\right)$ :

$$
\left\|u_{\varepsilon, \delta}\right\|_{H_{0}^{1}(\Omega)} \leqslant C\|f\|_{L^{2}(\Omega)},
$$

so that, up to a subsequence,

$$
u_{\varepsilon, \delta} \rightharpoonup u_{0} \quad \text { weakly in } H_{0}^{1}(\Omega) .
$$

Eq. (4.3) is obtained exactly as in the proof of Theorem 3.1.
By Theorem 2.19(7), there exists some $U$ in $L^{2}\left(\Sigma ; L_{\mathrm{loc}}^{2}\left(\mathbb{R}^{N}\right)\right)$ such that, up to a subsequence

$$
\begin{equation*}
\frac{\delta^{\frac{N}{2}-1}}{\sqrt{\varepsilon}} \mathcal{T}_{\varepsilon, \delta}^{b l}\left(u_{\varepsilon, \delta}\right) \rightharpoonup U \quad \text { weakly in } L^{2}\left(\Sigma ; L_{\mathrm{loc}}^{2}\left(\mathbb{R}^{N}\right)\right) \tag{4.7}
\end{equation*}
$$

Since $\mathcal{T}_{\varepsilon, \delta}^{b l}\left(M_{Y}^{\varepsilon, b l}\left(u_{\varepsilon, \delta}\right)\right)=M_{Y}^{\varepsilon, b l}\left(u_{\varepsilon, \delta}\right) 1_{\frac{1}{\delta} Y}$, Proposition 2.18 implies:

$$
\begin{equation*}
\frac{\delta^{\frac{N}{2}-1}}{\sqrt{\varepsilon}} M_{Y}^{\varepsilon, b l}\left(u_{\varepsilon, \delta}\right) 1_{\frac{1}{\delta} Y} \rightarrow k_{2} u_{\left.0\right|_{\Sigma}} \quad \text { strongly in } L^{2}\left(\Sigma ; L_{\mathrm{loc}}^{2}\left(\mathbb{R}^{N}\right)\right) . \tag{4.8}
\end{equation*}
$$

On the other hand, Theorem 2.19(7) gives a $W$ in $L^{2}\left(\Sigma ; L^{2^{*}}\left(\mathbb{R}^{N}\right)\right)$ with $\nabla_{z} W$ in $L^{2}\left(\Sigma \times \mathbb{R}^{N}\right)$, such that

$$
\begin{equation*}
\frac{\delta^{\frac{N}{2}-1}}{\sqrt{\varepsilon}}\left(\mathcal{\tau}_{\varepsilon, \delta}^{b l}\left(u_{\varepsilon, \delta}\right)-M_{Y}^{\varepsilon, b l}\left(u_{\varepsilon, \delta}\right) 1_{\frac{1}{\delta} Y}\right) \rightharpoonup W \quad \text { weakly in } L^{2}\left(\Sigma ; L^{2^{*}}\left(\mathbb{R}^{N}\right)\right) \tag{4.9}
\end{equation*}
$$

From (4.7), (4.8) and (4.9), one concludes:

$$
U=W+k_{2} u_{0}, \quad \text { and } \quad \nabla_{z} U=\nabla_{z} W,
$$

and, by Theorem 2.19(5) and (7) again,

$$
\begin{equation*}
\sqrt{\varepsilon} \delta^{\frac{N}{2}} \mathcal{T}_{\varepsilon, \delta}^{b l}\left(\nabla u_{\varepsilon, \delta}\right)=\frac{\delta^{\frac{N}{2}-1}}{\sqrt{\varepsilon}} \nabla_{z}\left(\mathcal{T}_{\varepsilon, \delta}^{b l}\left(u_{\varepsilon, \delta}\right)\right) 1_{\frac{1}{\delta} Y} \rightharpoonup \nabla_{z} U \quad \text { weakly in } L^{2}\left(\Sigma \times \mathbb{R}^{N}\right) \tag{4.10}
\end{equation*}
$$

From Definition 2.15, $\mathcal{T}_{\varepsilon, \delta}^{b l}\left(u_{\varepsilon, \delta}\right)=0$ in $\Sigma \times B$, so (4.7) implies:

$$
\begin{equation*}
U=0 \quad \text { on } \Sigma \times B . \tag{4.11}
\end{equation*}
$$

Therefore, $W=U-k_{2} u_{0}$ belongs to $L^{2}\left(\Sigma ; K_{B}\right)$.
In order to capture the contribution of the perforations to the limit problem, we adapt the proof of Theorem 3.1 and use Lemma 4.2. For $\psi \in \mathcal{D}(\Omega)$, let $\Phi \doteq \psi w_{\varepsilon, \delta}^{b l}$, be a test function in problem $\left(\mathcal{P}_{\varepsilon, \delta}^{\prime}\right)$. Since $w_{\varepsilon, \delta}^{b l}$ is constant outside $\Sigma_{\varepsilon}^{\prime}$ for $\delta$ small enough, one obtains:

$$
\begin{equation*}
\int_{\Sigma_{\varepsilon, \delta}^{\prime}} A^{\varepsilon} \nabla u_{\varepsilon, \delta} \nabla w_{\varepsilon, \delta}^{b l} \psi+\int_{\Omega_{\varepsilon, \delta}^{\prime}} A^{\varepsilon} \nabla u_{\varepsilon, \delta} \nabla \psi w_{\varepsilon, \delta}^{b l}=\int_{\Omega_{\varepsilon, \delta}^{\prime}} f w_{\varepsilon, \delta}^{b l} \psi \tag{4.12}
\end{equation*}
$$

Observe that since $w_{\varepsilon, \delta}^{b l}$ vanishes in the holes, one actually has

$$
\int_{\Sigma_{\varepsilon, \delta}^{\prime}} A^{\varepsilon} \nabla u_{\varepsilon, \delta} \nabla w_{\varepsilon, \delta}^{b l} \psi=\int_{\Sigma_{\varepsilon}^{\prime}} A^{\varepsilon} \nabla u_{\varepsilon, \delta} \nabla w_{\varepsilon, \delta}^{b l} \psi,
$$

which unfolded with $\mathcal{T}_{\varepsilon, \delta}^{b l}$ gives:

$$
\begin{equation*}
\int_{\Sigma_{\varepsilon}^{\prime}} A^{\varepsilon} \nabla u_{\varepsilon, \delta} \nabla w_{\varepsilon, \delta}^{b l} \psi \stackrel{\mathcal{T}_{\varepsilon, \delta}^{b l}}{=} \varepsilon \delta^{N} \int_{\Sigma \times \mathbb{R}^{N}} \mathcal{I}_{\varepsilon, \delta}^{b l}\left(A^{\varepsilon}\right) \mathcal{T}_{\varepsilon, \delta}^{b l}\left(\nabla u_{\varepsilon, \delta}\right) \mathcal{T}_{\varepsilon, \delta}^{b l}\left(\nabla w_{\varepsilon, \delta}^{b l} \mathcal{I}_{\varepsilon, \delta}^{b l}(\psi) .\right. \tag{4.13}
\end{equation*}
$$

Properties (5) of Theorem 2.19 implies:

$$
\mathcal{T}_{\varepsilon, \delta}^{b l}\left(\nabla w_{\varepsilon, \delta}^{b l}\right)=-\frac{1}{\varepsilon \delta} \nabla_{z} v,
$$

so that (4.10) and (4.13) yield,

$$
\begin{equation*}
\int_{\Sigma_{\varepsilon, \delta}^{\prime}} A^{\varepsilon} \nabla u_{\varepsilon, \delta} \nabla w_{\varepsilon, \delta}^{b l} \psi \stackrel{\mathcal{T}_{\varepsilon, \delta}^{b l}}{=} \frac{\delta^{\frac{N}{2}-1}}{\sqrt{\varepsilon}} \int_{\Sigma \times \mathbb{R}^{N}} \mathcal{T}_{\varepsilon, \delta}^{b l}\left(A^{\varepsilon}\right) \frac{\delta^{\frac{N}{2}-1}}{\sqrt{\varepsilon}} \nabla_{z}\left(\mathcal{T}_{\varepsilon, \delta}^{b l}\left(u_{\varepsilon, \delta}\right)\right)\left(-\nabla_{z} v\right) \mathcal{T}_{\varepsilon, \delta}^{b l}(\psi) . \tag{4.14}
\end{equation*}
$$

From the compactness of the support of $v$ and the straightforward inequality,

$$
\left\|\mathcal{T}_{\varepsilon, \delta}^{b l}(\psi)-\psi\right\|_{L^{\infty}\left(\widehat{\Sigma}_{\varepsilon} \times \frac{1}{\delta} Y\right)} \leqslant c \varepsilon\left\|\nabla_{x} \psi\right\|_{L^{\infty}(\Omega)^{N}},
$$

we obtain:

$$
\begin{equation*}
\mathcal{T}_{\varepsilon, \delta}^{b l}(\psi) \nabla_{z} v \rightarrow \psi \nabla_{z} v \quad \text { strongly in } L^{2}\left(\Sigma \times \mathbb{R}^{N}\right) . \tag{4.15}
\end{equation*}
$$

This, together with convergences (4.1) and (4.10), as well as hypothesis (4.2), allows us to pass to the limit in (4.14) which now reads

$$
\begin{equation*}
\lim _{\varepsilon \rightarrow 0} \int_{\Sigma_{\varepsilon, \delta}^{\prime}} A^{\varepsilon} \nabla u_{\varepsilon, \delta} \nabla w_{\varepsilon, \delta}^{b l} \psi \mathrm{~d} x=-k_{2} \int_{\Sigma \times \mathbb{R}^{N}} A_{0}\left(x^{\prime}, z\right) \nabla_{z} U\left(x^{\prime}, z\right) \nabla_{z} v \psi \mathrm{~d} x^{\prime} \mathrm{d} z . \tag{4.16}
\end{equation*}
$$

By a density argument, (4.15) is true for every $v$ in $K_{B}$.
The second term in (4.12) is unfolded with $\mathcal{T}_{\varepsilon}$ and using Theorem 2.2 , we get at the limit

$$
\lim _{\varepsilon \rightarrow 0} \int_{\Omega_{\varepsilon, \delta}^{\prime}} A^{\varepsilon} \nabla u_{\varepsilon, \delta} w_{\varepsilon, \delta}^{b l} \nabla \psi \mathrm{~d} x=v(B) \int_{\Omega \times Y} A(x, y)\left(\nabla_{x} u_{0}+\nabla_{y} \hat{u}\right) \nabla_{x} \psi \mathrm{~d} x \mathrm{~d} y,
$$

which, with (4.16) gives Eq. (4.4). Eq. (4.5) is obtained similarly.

### 4.3. Standard form of the homogenized equation

Like in Section 3.4, one can rewrite system (4.3)-(4.5) in the standard form. The result is stated in the next theorem, the proof of which follows the same lines as that of Theorem 3.5.

Theorem 4.3. The limit function $u_{0}$ given by Theorem 4.1 is the solution of the homogenized equation:

$$
\left\{\begin{array}{l}
u_{0} \in H_{0}^{1}(\Omega),  \tag{4.17}\\
\int_{\Omega} \mathcal{A}^{\mathrm{hom}} \nabla u_{0} \nabla \psi+k_{2}^{2} \int_{\Sigma} \boldsymbol{\Theta}^{\prime} u_{0} \psi=\int_{\Omega} f \psi, \\
\forall \psi \in H_{0}^{1}(\Omega),
\end{array}\right.
$$

where $\boldsymbol{\Theta}^{\prime}$ is defined by (3.30) with $x^{\prime}$ in place of $x$.
Remark 4.4. The strong formulation for (4.17) is the following:

$$
\begin{cases}-\operatorname{div} \mathcal{A}^{\text {hom }} \nabla u_{0}=f & \text { in } \Omega \backslash \Sigma, \\ -\left[\mathcal{A}^{\text {hom }} \nabla u_{0}\right]=\left(k_{2}\right)^{2} \boldsymbol{\Theta}^{\prime} u_{0} & \text { on } \Sigma, \\ u_{0}=0 & \text { on } \partial \Omega,\end{cases}
$$

where $\left[\mathcal{A}^{\text {hom }} \nabla u_{0}\right]$ denotes the jump across $\Sigma$,

$$
\left[\mathcal{A}^{\text {hom }} \nabla u_{0}\right] \doteq \mathcal{A}^{\text {hom }} \nabla u_{0}^{-} n^{-}+\mathcal{A}^{\text {hom }} \nabla u_{0}^{+} n^{+} \quad \text { on } \Sigma,
$$

$n^{+}$and $n^{-}$denoting the respective exterior unit normal to $\Omega_{+}$and $\Omega_{-}$on $\Sigma$.
Remark 4.5. 1. The proof for the case $k_{2}=0$ is actually simpler, and the statement is included in Theorem 4.3: the small holes have no influence at the limit, i.e. the equation $-\operatorname{div} \mathcal{A}^{\text {hom }} \nabla u_{0}=f$ is satisfied in the whole of $\Omega$.
2. As in Remark 3.7, for the case of $\lim \frac{\delta^{\frac{N}{2}-1}}{\sqrt{\varepsilon}}=\infty$, Theorem 2.19(6) implies:

$$
\left.\mathcal{T}_{\varepsilon, \delta}^{b l}\left(u_{\varepsilon, \delta}\right) \rightharpoonup u_{0}\right|_{\Sigma} \quad \text { weakly in } L^{2}\left(\Sigma ; L_{\mathrm{loc}}^{2}\left(\mathbb{R}^{N}\right)\right)
$$

On the other hand, $\mathcal{T}_{\varepsilon, \delta}^{b l}\left(u_{\varepsilon, \delta}\right)=0$ in $\Sigma \times B$ implies that $\left.u_{0}\right|_{\Sigma}=0$. Therefore, the limit problem splits into two separate homogeneous Dirichlet problems in $\Omega_{+}$and $\Omega_{-}$,

$$
\begin{cases}-\operatorname{div} \mathcal{A}^{\text {hom }} \nabla u_{0}=f & \text { in } \Omega_{ \pm} \\ u_{0}=0 & \text { on } \partial \Omega_{ \pm}\end{cases}
$$

## 5. The thin Neumann sieve with variable coefficients

### 5.1. Functional setting

We use the same notations as in Sections 2 and 4. For an open subset $S$ of $Y \cap \Pi$ such that $\bar{S} \subset(Y \cap \Pi)$, set

$$
Y_{\delta}=Y_{+} \cup Y_{-} \cup \delta S,
$$



Fig. 6. The set $Y_{\delta}$ and the thin sieve $\Omega_{\varepsilon \delta}^{b l}$.
and

$$
S_{\varepsilon, \delta}=\left\{x \in \Sigma \text { such that }\left\{\frac{x}{\varepsilon}\right\}_{Y} \in \delta S\right\} .
$$

For $\Omega$ open and bounded in $\mathbb{R}^{N}(N \geqslant 3)$, define:

$$
\Omega_{\varepsilon \delta}^{b l}=\Omega_{+} \cup \Omega_{-} \cup S_{\varepsilon, \delta} \quad \text { and } \quad \Sigma_{\varepsilon, \delta}^{\prime} \doteq \Sigma_{\varepsilon}^{\prime} \cap \Omega_{\varepsilon \delta}^{b l} .
$$

The connection between $\Omega_{+}$and $\Omega_{-}$occurs through the "sieve" consisting of the set $S_{\varepsilon, \delta}$ (see Fig. 6). We assume that $\varepsilon$ and $\delta$ satisfy assumption (4.1) of Section 4:

$$
k_{2}=\lim _{\varepsilon \rightarrow 0} \frac{\delta^{\frac{N}{2}-1}}{\sqrt{\varepsilon}}, \quad \text { where } 0 \leqslant k_{2}<\infty .
$$

Consider the space

$$
V=\left\{v \in H^{1}\left(\Omega_{+} \cup \Omega_{-}\right) ; v=0 \text { on } \partial \Omega\right\},
$$

which is a Hilbert space for the scalar product,

$$
\langle u, v\rangle_{V}=\int_{\Omega_{+} \cup \Omega_{-}} \nabla u \nabla v \quad \text { for all } u, v \in V .
$$

For simplicity, when $v$ belongs to $V$, we denote $\nabla v$ the $L^{2}(\Omega)-$ function which equals the gradient of $v$ in $\Omega_{+} \cup \Omega_{-}$ (this is the restriction to $\Omega_{+} \cup \Omega_{-}$of the distributional gradient of $v$ ). We also denote by $[v]$ the jump of $v$ across $\Sigma,\left.[v] \doteq v^{+}\right|_{\Sigma}-\left.v^{-}\right|_{\Sigma}$, which belongs to $H^{1 / 2}(\Sigma)$. Finally set

$$
V_{\varepsilon, \delta}=\left\{v \in V,[v]=0 \text { on } S_{\varepsilon, \delta}\right\} .
$$

The thin Neumann sieve model is:

$$
\left\{\begin{array}{l}
\text { Find } u_{\varepsilon, \delta} \in V_{\varepsilon, \delta} \text { satisfying, }  \tag{bl}\\
\int_{\Omega_{\varepsilon, \delta}^{b l}} A^{\varepsilon} \nabla u_{\varepsilon, \delta} \nabla \phi=\int_{\Omega_{\varepsilon, \delta}^{b l}} f \phi, \quad f \in L^{2}(\Omega), \\
\forall \phi \in V_{\varepsilon, \delta} .
\end{array}\right.
$$

### 5.2. Unfolded homogenization result

In this problem, the equivalent of the space $K_{B}$ of Section 3 (see (3.2)), is

$$
\begin{equation*}
\widehat{K_{S}}=\left\{\Phi \in H_{\mathrm{loc}}^{1}\left(\mathbb{R}_{+}^{N} \cup \mathbb{R}_{-}^{N}\right) ; \nabla \Phi \in L^{2}\left(\mathbb{R}_{+}^{N} \cup \mathbb{R}_{-}^{N}\right),[\Phi]=0 \text { on } S\right\} . \tag{5.1}
\end{equation*}
$$

Proposition 5.1. There exist two linear forms $l^{ \pm}$on $\widehat{K_{S}}$ such that for every $\Phi$ in $\widehat{K_{S}}$, the functions $\Phi^{ \pm}-l^{ \pm}(\Phi)$ belong to $L^{2^{*}}\left(\mathbb{R}_{ \pm}^{N}\right)$.

The space $\widehat{K_{S}}$ is Hilbert space for the norm,

$$
\begin{equation*}
\|\Phi\|_{\widehat{K}_{S}}^{2} \doteq\|\nabla \Phi\|_{L^{2}\left(\mathbb{R}_{+}^{N} \cup \mathbb{R}_{-}^{N}\right)}^{2}+\left(\frac{l^{+}(\Phi)+l^{-}(\Phi)}{2}\right)^{2} \tag{5.2}
\end{equation*}
$$

Furthermore,

$$
\widehat{K_{S}}{ }^{\infty} \doteq\left\{\Phi \in \widehat{K_{S}}, \Phi^{ \pm} \in C^{\infty}\left(\mathbb{R}_{ \pm}^{N}\right), \operatorname{supp}\left(\nabla \Phi^{ \pm}\right) \text {bounded in } \mathbb{R}_{ \pm}^{N}\right\}
$$

is dense in $\widehat{K_{S}}$ for this norm.
Proof. Due to the Sobolev-Poincaré-Wirtinger inequality (applied in the sets $\frac{1}{\delta} Y_{ \pm}$with $\delta \rightarrow 0$ ), for every $\Phi$ in $\widehat{K_{S}}$, there exist two constants $l^{ \pm}(\Phi)$ such that $\left(\Phi^{ \pm}-l^{ \pm}(\Phi)\right)$ belong to $L^{2^{*}}\left(\mathbb{R}_{ \pm}^{N}\right)$.

It is well known that the first term in (5.2) is a Hilbert semi-norm on the space $\widehat{K_{S}}$, so that, with the second term, it defines a norm. The density of $\widehat{K_{S}}{ }^{\infty}$ in $\widehat{K_{S}}$ follows by a standard argument of truncation and regularization.

Theorem 5.2. Let $A^{\varepsilon}$ belong to $M(\alpha, \beta, \Omega)$. Suppose that, as $\varepsilon$ goes to 0 , there exists a matrix $A$ such that

$$
\mathcal{T}_{\mathcal{\varepsilon}}\left(A^{\varepsilon}\right)(x, y) \rightarrow A(x, y) \quad \text { a.e. in } \Omega \times Y
$$

Furthermore, suppose that there exists a matrix field $A_{0}$ such that, as $\varepsilon$ and $\delta \rightarrow 0$,

$$
\begin{equation*}
\mathcal{T}_{\varepsilon, \delta}^{b l}\left(A^{\varepsilon}\right)\left(x^{\prime}, z\right) \rightarrow A_{0}\left(x^{\prime}, z\right) \quad \text { a.e. in } \Sigma \times \mathbb{R}^{N} . \tag{5.3}
\end{equation*}
$$

Let $u_{\varepsilon, \delta}$ be the solution of the problem $\left(\mathcal{P}_{\varepsilon, \delta}^{b l}\right)$. Then

$$
u_{\varepsilon, \delta} \rightharpoonup u_{0} \quad \text { weakly in } V,
$$

and there exists $\hat{u} \in L^{2}\left(\Omega ; H_{p e r}^{1}(Y)\right), U \in L^{2}\left(\Sigma ; \widehat{K}_{S}\right)$ satisfying,

$$
\begin{equation*}
l^{ \pm}(U)=\left.k_{2} u_{0}^{ \pm}\right|_{\Sigma} \quad \text { for a.e. } x^{\prime} \in \Sigma, \tag{5.4}
\end{equation*}
$$

and such that $\left(u_{0}, \hat{u}, U\right)$ solves the following three equations:

$$
\begin{equation*}
\int_{Y} A(x, y)\left(\nabla_{x} u_{0}(x)+\nabla_{y} \hat{u}(x, y)\right) \nabla_{y} \phi(y) \mathrm{d} y=0, \tag{5.5}
\end{equation*}
$$

for a.e. $x$ in $\Omega$ and all $\phi \in H_{p e r}^{1}(Y)$,

$$
\begin{equation*}
\int_{\mathbb{R}^{N}} A_{0}\left(x^{\prime}, z\right) \nabla_{z} U\left(x^{\prime}, z\right) \nabla_{z} v(z) \mathrm{d} z=0 \tag{5.6}
\end{equation*}
$$

for a.e. $x^{\prime}$ in $\Sigma$ and all $v \in \widehat{K}_{S}$ with $l^{ \pm}(v)=0$, and

$$
\begin{equation*}
\int_{\Omega \times Y} A\left(\nabla_{x} u_{0}+\nabla_{y} \hat{u}\right) \nabla \phi-k_{2} \int_{\Sigma \times S} A_{0} \nabla_{z} U n^{+}[\phi]_{\Sigma}=\int_{\Omega} f \phi, \tag{5.7}
\end{equation*}
$$

for all $\phi \in V$.
Proof (for the case $k_{2}>0$ ). Let $u_{\varepsilon, \delta}$ be a test function in $\left(\mathcal{P}_{\varepsilon, \delta}^{b l}\right)$. Using the Poincaré inequality on $\Omega_{+}$and $\Omega_{-}$, there is a constant $C$ (independent of $\varepsilon, \delta$ ) such that,

$$
\left\|u_{\varepsilon, \delta}\right\|_{V} \leqslant C\|f\|_{L^{2}(\Omega)}
$$

Consequently, up to a subsequence, there exists $u_{0} \in V$ such that

$$
u_{\varepsilon, \delta} \rightharpoonup u_{0} \quad \text { weakly in } V .
$$

By Theorem 2.2, one can also assume that there exists $\hat{u} \in L^{2}\left(\Omega ; H_{p e r}^{1}(Y)\right)$ with,

$$
\mathcal{T}_{\varepsilon}\left(\nabla u_{\varepsilon, \delta}\right) \rightharpoonup \nabla_{x} u_{0}+\nabla_{y} \hat{u} \quad \text { weakly in } L^{2}(\Omega \times Y) .
$$

Using $\psi \in \mathcal{D}(\Omega)$ as a test function in $\left(\mathcal{P}_{\varepsilon, \delta}^{b l}\right)$, and unfolding with operator $\mathcal{T}_{\varepsilon}$, we get:

$$
\int_{\Omega_{\varepsilon, \delta}^{b l}} A^{\varepsilon} \nabla u_{\varepsilon, \delta} \nabla \psi \mathrm{d} x \stackrel{\mathcal{T}_{\varepsilon}}{=} \int_{\Omega \times Y} \mathcal{T}_{\varepsilon}\left(A^{\varepsilon}\right) \mathcal{T}_{\varepsilon}\left(\nabla u_{\varepsilon, \delta}\right) \mathcal{T}_{\varepsilon}(\nabla \psi) \mathrm{d} x \mathrm{~d} y .
$$

Applying properties (5) and (6) of Theorem 2.2 we can pass to the limit to obtain,

$$
\int_{\Omega \times Y} A(x, y)\left[\nabla_{x} u_{0}+\nabla_{y} \hat{u}\right] \nabla_{x} \psi \mathrm{~d} x \mathrm{~d} y=\int_{\Omega} f \psi \mathrm{~d} x .
$$

Next, consider $\phi \in H_{p e r}^{1}(Y)$ and $\psi \in \mathcal{D}\left(\Omega_{+}\right) \cup \mathcal{D}\left(\Omega_{-}\right)$. Using $\Phi(x)=\varepsilon \psi(x) \phi\left(\frac{x}{\varepsilon}\right)$ as a test function in $\left(\mathcal{P}_{\varepsilon, \delta}^{b l}\right)$ yields,

$$
\varepsilon \int_{\Omega_{\varepsilon, \delta}^{b l}} A^{\varepsilon} \nabla u_{\varepsilon, \delta} \nabla \psi \phi\left(\frac{\dot{\bar{q}}}{\bar{\varepsilon}}\right)+\int_{\Omega_{\varepsilon, \delta}^{b l}} A^{\varepsilon} \nabla u_{\varepsilon, \delta} \psi \nabla \phi\left(\frac{\dot{\bar{q}}}{\bar{\varepsilon}}\right)=\varepsilon \int_{\Omega_{\varepsilon, \delta}^{b l}} f \psi \phi\left(\frac{\dot{\bar{\varepsilon}}}{\bar{\varepsilon}}\right) .
$$

As in Section 3.3, passing to the limit gives (5.5).
By Theorem 2.24(3), there exists $U \in L^{2}\left(\Sigma ; L_{\mathrm{loc}}^{2}\left(\mathbb{R}_{ \pm}^{N}\right)\right)$ such that (up to a subsequence),

$$
\begin{equation*}
\frac{\delta^{\frac{N}{2}-1}}{\sqrt{\varepsilon}} \mathcal{T}_{\varepsilon, \delta}^{b l}\left(u_{\varepsilon, \delta}^{ \pm}\right) \rightharpoonup U^{ \pm} \quad \text { weakly in } L^{2}\left(\Sigma ; L_{\mathrm{loc}}^{2}\left(\mathbb{R}_{ \pm}^{N}\right)\right) \tag{5.8}
\end{equation*}
$$

By construction $\mathcal{T}_{\varepsilon, \delta}^{b l}\left(M_{Y_{ \pm}}^{\varepsilon, b l}\left(u_{\varepsilon, \delta}^{ \pm}\right)\right)=\left.M_{Y_{ \pm}}^{\varepsilon, b l}\left(u_{\varepsilon, \delta}^{ \pm}\right)\right|_{\frac{1}{\delta} Y_{ \pm}}$. By Proposition 2.23, one has:

$$
\begin{equation*}
\frac{\delta^{\frac{N}{2}-1}}{\sqrt{\varepsilon}} M_{Y_{ \pm}}^{\varepsilon, b l}\left(u_{\varepsilon, \delta}^{ \pm}\right) 1_{\frac{1}{\delta} Y} \rightarrow k_{2} u_{0}^{ \pm}{ }_{\mid \Sigma} \quad \text { strongly in } L^{2}\left(\Sigma ; L_{\mathrm{loc}}^{2}\left(\mathbb{R}_{ \pm}^{N}\right)\right) \tag{5.9}
\end{equation*}
$$

By Theorem $2.24(3)$ there exists a $W$ in $L^{2}\left(\Sigma ; L^{2^{*}}\left(\mathbb{R}^{N}\right)\right)$ with $\nabla_{z} W^{ \pm}$in $L^{2}\left(\Sigma \times \mathbb{R}_{ \pm}^{N}\right)$ such that

$$
\begin{equation*}
\frac{\delta^{\frac{N}{2}-1}}{\sqrt{\varepsilon}}\left(\mathcal{T}_{\varepsilon, \delta}^{b l}\left(u_{\varepsilon, \delta}^{ \pm}\right)-M_{Y_{ \pm}}^{\varepsilon, b l}\left(u_{\varepsilon, \delta}^{ \pm}\right) 1_{\frac{1}{\delta} Y}\right) \rightharpoonup W^{ \pm} \quad \text { weakly in } L^{2}\left(\Sigma ; L^{2^{*}}\left(\mathbb{R}_{ \pm}^{N}\right)\right) \tag{5.10}
\end{equation*}
$$

From (5.8), (5.9) and (5.10), one concludes:

$$
\begin{equation*}
U^{ \pm}=W^{ \pm}+\left.k_{2} u_{0}^{ \pm}\right|_{\Sigma}, \quad \text { and } \quad \nabla_{z} U^{ \pm}=\nabla_{z} W^{ \pm} . \tag{5.11}
\end{equation*}
$$

Again by Theorem 2.24(3), one has the convergence:

$$
\begin{equation*}
\frac{\delta^{\frac{N}{2}-1}}{\sqrt{\varepsilon}} \nabla_{z}\left(\mathcal{T}_{\varepsilon, \delta}^{b l}\left(u_{\varepsilon, \delta}^{ \pm}\right)\right)=\sqrt{\varepsilon} \delta^{\frac{N}{2}} \mathcal{T}_{\varepsilon, \delta}^{b l}\left(\nabla u_{\varepsilon, \delta}^{ \pm}\right) \rightharpoonup \nabla_{z} U^{ \pm} \quad \text { weakly in } L^{2}\left(\Sigma \times \mathbb{R}_{ \pm}^{N}\right) \tag{5.12}
\end{equation*}
$$

From Definition 2.15, $\mathcal{T}_{\varepsilon, \delta}^{b l}\left(u_{\varepsilon, \delta}^{+}\right)=\mathcal{T}_{\varepsilon, \delta}^{b l}\left(u_{\varepsilon, \delta}^{-}\right)$on $\Sigma \times S$, so that by convergences (5.8), (5.12) one has:

$$
\left[U\left(x^{\prime}, \cdot\right)\right]=0 \quad \text { on } S \text { for a.e. } x^{\prime} \in \Sigma
$$

Therefore, $U \in L^{2}\left(\Sigma ; \widehat{K_{S}}\right)$, and (5.11) implies (5.4).
In order to obtain equations (5.6) and (5.7), choose a function $v$ in ${\widehat{K_{S}}}^{\infty}$ and set:

$$
w_{\varepsilon, \delta}\left(x^{\prime}, x_{N}\right)=v\left(\frac{1}{\delta}\left\{\frac{x^{\prime}}{\varepsilon}\right\}_{Y}, \frac{x_{N}}{\varepsilon \delta}\right) .
$$

Clearly, $\left[w_{\varepsilon, \delta}\right]=0$ on $S_{\varepsilon, \delta}$ and $\nabla w_{\varepsilon, \delta}^{ \pm}$vanishes outside $\Sigma_{\varepsilon, \delta}^{\prime}$ for $\delta$ small enough. One easily shows (as in Lemma 4.2) that

$$
\begin{cases}\mathcal{T}_{\varepsilon}\left(w_{\varepsilon, \delta}^{ \pm}\right) \rightarrow l^{ \pm}(v) & \text { strongly in } L^{2}\left(\Omega_{ \pm}\right)  \tag{5.13}\\ w_{\varepsilon, \delta}^{ \pm} \rightarrow l^{ \pm}(v) & \text { weakly in } H^{1}\left(\Omega_{ \pm}\right)\end{cases}
$$

For $\psi \in \mathcal{D}(\Omega)$, using $\psi w_{\varepsilon, \delta}$ as a test function in problem $\left(\mathcal{P}_{\varepsilon, \delta}^{b l}\right)$ gives:

$$
\begin{equation*}
\int_{\Omega_{\varepsilon, \delta}^{b l}} A^{\varepsilon} \nabla u_{\varepsilon, \delta} \nabla \psi w_{\varepsilon, \delta}+\int_{\Sigma_{\varepsilon, \delta}^{\prime}} A^{\varepsilon} \nabla u_{\varepsilon, \delta} \nabla w_{\varepsilon, \delta} \psi=\int_{\Omega_{\varepsilon, \delta}^{b l}} f w_{\varepsilon, \delta} \psi \tag{5.14}
\end{equation*}
$$

The first term in (5.14) is unfolded with $\mathcal{T}_{\varepsilon}$ as usual. This yields

$$
\int_{\Omega_{\varepsilon, \delta}^{b l}} A^{\varepsilon} \nabla u_{\varepsilon, \delta} \nabla \psi w_{\varepsilon, \delta} \stackrel{\mathcal{T}_{\varepsilon}}{=} \int_{\Omega \times Y} \mathcal{T}_{\varepsilon}\left(A^{\varepsilon}\right) \mathcal{T}_{\varepsilon}\left(\nabla u_{\varepsilon, \delta}\right) \mathcal{T}_{\varepsilon}(\nabla \psi) \mathcal{T}_{\varepsilon}\left(w_{\varepsilon, \delta}\right) \mathrm{d} x \mathrm{~d} y .
$$

Applying (5.13) and properties (5) and (6) of Theorem 2.2, one obtains:

$$
\begin{aligned}
\lim _{\varepsilon \rightarrow 0} \int_{\Omega_{\varepsilon, \delta}^{b l}} A^{\varepsilon} \nabla u_{\varepsilon, \delta} \nabla \psi w_{\varepsilon, \delta}= & l^{+}(v) \int_{\Omega_{+} \times Y} A(x, y)\left(\nabla_{x} u_{0}+\nabla_{y} \hat{u}\right) \nabla_{x} \psi \mathrm{~d} x \mathrm{~d} y \\
& +l^{-}(v) \int_{\Omega_{-\times Y}} A(x, y)\left(\nabla_{x} u_{0}+\nabla_{y} \hat{u}\right) \nabla_{x} \psi \mathrm{~d} x \mathrm{~d} y
\end{aligned}
$$

The second term in (5.14) is unfolded with $\mathcal{T}_{\varepsilon, \delta}^{b l}$. The choice of the test function implies that u.c.i. is satisfied, so

$$
\begin{equation*}
\int_{\Sigma_{\varepsilon, \delta}^{\prime}} A^{\varepsilon} \nabla u_{\varepsilon, \delta} \nabla w_{\varepsilon, \delta} \psi \stackrel{\mathcal{T}_{\varepsilon, \delta}^{b l}}{=} \varepsilon \delta^{N} \int_{\Sigma \times \mathbb{R}^{N}} \mathcal{T}_{\varepsilon, \delta}^{b l}\left(A^{\varepsilon}\right) \mathcal{T}_{\varepsilon, \delta}^{b l}\left(\nabla u_{\varepsilon, \delta}\right) \mathcal{T}_{\varepsilon, \delta}^{b l}\left(\nabla w_{\varepsilon, \delta}\right) \mathcal{T}_{\varepsilon, \delta}^{b l}(\psi) . \tag{5.15}
\end{equation*}
$$

Property (5) from Theorem 2.19 gives:

$$
\mathcal{T}_{\varepsilon, \delta}^{b l}\left(\nabla w_{\varepsilon, \delta}\right)=\frac{1}{\varepsilon \delta} \nabla_{z} v
$$

which, together with (5.15), yields

$$
\begin{equation*}
\int_{\Sigma_{\varepsilon, \delta}^{\prime}} A^{\varepsilon} \nabla u_{\varepsilon, \delta} \nabla w_{\varepsilon, \delta} \psi \stackrel{\mathcal{T}_{\varepsilon, \delta}^{b l}}{=} \frac{\delta^{\frac{N}{2}-1}}{\sqrt{\varepsilon}} \int_{\Sigma \times \mathbb{R}^{N}} \mathcal{T}_{\varepsilon, \delta}^{b l}\left(A^{\varepsilon}\right) \sqrt{\varepsilon} \delta^{\frac{N}{2}} \mathcal{T}_{\varepsilon, \delta}^{b l}\left(\nabla u_{\varepsilon, \delta}\right) \nabla_{z} v \mathcal{T}_{\varepsilon, \delta}^{b l}(\psi) \tag{5.16}
\end{equation*}
$$

Convergences (5.3), (5.12), allow to pass to the limit in (5.16) to obtain:

$$
\lim _{\varepsilon \rightarrow 0} \int_{\Sigma_{\varepsilon, \delta}^{\prime}} A^{\varepsilon} \nabla u_{\varepsilon, \delta} \nabla w_{\varepsilon, \delta} \psi=k_{2} \int_{\Sigma \times \mathbb{R}^{N}} A_{0} \nabla_{z} U\left(x^{\prime}, z\right) \nabla_{z} v \psi \mathrm{~d} x^{\prime} \mathrm{d} z .
$$

Now, the limit in (5.14) becomes:

$$
\begin{align*}
& l^{+}(v) \int_{\Omega_{+} \times Y} A\left(\nabla_{x} u_{0}+\nabla_{y} \hat{u}\right) \nabla_{x} \psi+l^{-}(v) \int_{\Omega_{-\times Y}} A\left(\nabla_{x} u_{0}+\nabla_{y} \hat{u}\right) \nabla_{x} \psi \\
& \quad+k_{2} \int_{\Sigma \times \mathbb{R}^{N}} A_{0}\left(x^{\prime}, z\right) \nabla_{z} U\left(x^{\prime}, z\right) \nabla_{z} v \psi \mathrm{~d} x^{\prime} \mathrm{d} z \\
& =l^{+}(v) \int_{\Omega_{+}} f \psi+l^{-}(v) \int_{\Omega_{-}} f \psi, \tag{5.17}
\end{align*}
$$

which, by density, holds for every $v \in \widehat{K_{S}}$. Eq. (5.6) is then simply obtained by choosing $l^{+}(v)=l^{-}(v)=0$ in (5.17).
Using (5.6) with an arbitrary $v$ in ${\widehat{K_{S}}}^{\infty}$ one deduces by Green's formula that

$$
\begin{equation*}
\int_{\mathbb{R}_{ \pm}^{N}} A_{0} \nabla_{z} U \nabla_{z} v \mathrm{~d} z=\int_{S} A_{0} \nabla_{z} U n^{ \pm}\left(v\left(z^{\prime}\right)-l^{ \pm}(v)\right) \mathrm{d} z^{\prime} \tag{5.18}
\end{equation*}
$$

which still holds for every $v \in \widehat{K_{S}}$. Then, (5.18) together with (5.17) leads to,

$$
\begin{align*}
& l^{+}(v)\left(\int_{\Omega_{+} \times Y} A\left(\nabla_{x} u_{0}+\nabla_{y} \hat{u}\right) \nabla_{x} \psi-k_{2} \int_{\Sigma \times S} A_{0} \nabla_{z} U n^{+} \psi-\int_{\Omega_{+}} f \psi\right) \\
& \quad+l^{-}(v)\left(\int_{\Omega_{-\times Y}} A\left(\nabla_{x} u_{0}+\nabla_{y} \hat{u}\right) \nabla_{x} \psi-k_{2} \int_{\Sigma \times S} A_{0} \nabla_{z} U n^{-} \psi-\int_{\Omega_{-}} f \psi\right) \\
& \quad+k_{2} \int_{\Sigma \times S}\left(A_{0} \nabla_{z} U n^{+}+A_{0} \nabla_{z} U n^{-}\right) v \psi=0 . \tag{5.19}
\end{align*}
$$

Taking $l^{+}(v)=l^{-}(v)=0$ in (5.19), implies that

$$
\begin{equation*}
A_{0} \nabla_{z} U n^{+}+A_{0} \nabla_{z} U n^{-} \doteq\left[A_{0} \nabla_{z} U\right]_{S}=0 \quad \text { a.e. on } \Sigma \times S \tag{5.20}
\end{equation*}
$$

Since $l^{+}(v)$ and $l^{-}(v)$ are independent, (5.19) now gives the following two formulas:

$$
\begin{align*}
& \int_{\Omega_{+\times Y}} A\left(\nabla_{x} u_{0}+\nabla_{y} \hat{u}\right) \nabla_{x} \psi-k_{2} \int_{\Sigma \times S} A_{0} \nabla_{z} U n^{+} \psi=\int_{\Omega_{+}} f \psi, \\
& \int_{\Omega_{-\times Y}} A\left(\nabla_{x} u_{0}+\nabla_{y} \hat{u}\right) \nabla_{x} \psi-k_{2} \int_{\Sigma \times S} A_{0} \nabla_{z} U n^{-} \psi=\int_{\Omega_{-}} f \psi, \tag{5.21}
\end{align*}
$$

which, by density, hold for every $\psi$ in $H_{0}^{1}(\Omega)$. Let $\phi$ be arbitrary in $V$. Eq. (5.7) is obtained by choosing $\psi=\phi^{+}$, respectively $\psi=\phi^{-}$in (5.21), and adding the two corresponding equations.

### 5.3. Standard form of the homogenized equation

As in Section 4.4, one can write system (5.4)-(5.7) in a standard form, with only $u_{0}$ as unknown.
First, from (5.6), the first term in the left-hand side of (5.7), can be written in terms of the standard homogenized operator:

$$
\int_{\Omega \times Y} A\left(\nabla_{x} u_{0}+\nabla_{y} \hat{u}\right) \nabla \phi=\int_{\Omega} \mathcal{A}^{\mathrm{hom}} \nabla u_{0} \nabla \phi,
$$

for every $\phi$ in the space $V$, using the same cell-problems (3.25) and the same $\mathcal{A}^{\text {hom }}$ given by (3.27).

Next, observe that for a given $u_{0}$, problem (5.4)-(5.6) for $U$, has a unique solution by the Lax-Milgram theorem (applied on a closed affine subspace of $\widehat{K_{S}}$ ).

Now, we show how Eq. (5.7) can be brought to the standard form. More precisely, it remains to clarify the connection between the term $-k_{2} \int_{S} A_{0} \nabla_{z} U n^{+}$and $\left[u_{0}\right]_{\Sigma}$. In order to do so, let $\theta$ be the solution of the following "cell problem":

$$
\left\{\begin{array}{l}
\theta \in L^{\infty}\left(\Sigma ; \widehat{K_{S}}\right), \quad l^{ \pm}(\theta) \equiv \pm 1  \tag{5.22}\\
\int_{\mathbb{R}^{N}} A_{0}\left(x^{\prime}, z\right) \nabla_{z} \theta\left(x^{\prime}, z\right) \nabla_{z} \Psi(z) \mathrm{d} z=0 \quad \text { for a.e. } x^{\prime} \in \Sigma, \\
\forall \Psi \in \widehat{K_{S}} \text { with } l^{ \pm}(\Psi)=0
\end{array}\right.
$$

From (5.18) follows:

$$
\begin{equation*}
\int_{\substack{\mathbb{R}_{+}^{N} \cup \mathbb{R}_{-}^{N}}} A_{0} \nabla_{z} U \nabla_{z} v \mathrm{~d} z=\left(l^{+}(v)-l^{-}(v)\right) \int_{S} A_{0} \nabla_{z} U n^{-} \mathrm{d} z^{\prime} \tag{5.23}
\end{equation*}
$$

Similarly, the solution of (5.22) is unique and satisfies for a.e. $x^{\prime}$ in $\Sigma$,

$$
\begin{gather*}
{ }^{t} A_{0} \nabla_{z} \theta n^{+}+{ }^{t} A A_{0} \nabla_{z} \theta n^{-} \doteq\left[{ }^{t} A_{0} \nabla_{z} \theta\right]_{S}=0, \\
\int_{\mathbb{R}_{+}^{N} \cup \mathbb{R}_{-}^{N}}{ }^{t} A_{0} \nabla_{z} \theta \nabla_{z} v \mathrm{~d} z=\left(l^{+}(v)-l^{-}(v)\right) \int_{S}^{t} A_{0} \nabla_{z} \theta n^{-} \mathrm{d} z^{\prime} . \tag{5.24}
\end{gather*}
$$

Formula (5.23) holds for $v=\theta$, whereas (5.24) does for $v=U$, so that combining the two yields,

$$
\int_{S} A_{0} \nabla_{z} U n^{-} \mathrm{d} z^{\prime}=\frac{l^{+}(\theta)-l^{-}(\theta)}{2} \int_{S} A_{0} \nabla_{z} U n^{-} \mathrm{d} z^{\prime}=\frac{l^{+}(U)-l^{-}(U)}{2} \int_{S}^{t} A_{0} \nabla_{z} \theta n^{-} \mathrm{d} z^{\prime}
$$

Consequently, by (5.4),

$$
k_{2} \int_{S} A_{0}\left(x^{\prime}, z\right) \nabla_{z} U\left(x^{\prime}, z\right) n^{-} \mathrm{d} z^{\prime}=\frac{k_{2}^{2}}{2} \boldsymbol{\Theta}\left(x^{\prime}\right)\left[u_{0}\right]_{\Sigma}\left(x^{\prime}\right)
$$

where

$$
\boldsymbol{\Theta}\left(x^{\prime}\right) \doteq \int_{S}{ }^{t} A_{0} \nabla_{z} \theta n^{-} \mathrm{d} z^{\prime}=-\int_{S}{ }^{t} A_{0} \nabla_{z} \theta n^{+} \mathrm{d} z^{\prime}
$$

the latter equality deriving from (5.23). Thus, Eq. (5.7) becomes:

$$
\int_{\Omega} \mathcal{A}^{\mathrm{hom}} \nabla u_{0} \nabla \phi \mathrm{~d} x+\frac{k_{2}^{2}}{2} \int_{\Sigma} \boldsymbol{\Theta}\left(x^{\prime}\right)\left[u_{0}\right]_{\Sigma}\left(x^{\prime}\right)[\phi]_{\Sigma}\left(x^{\prime}\right) \mathrm{d} x^{\prime}=\int_{\Omega} f \phi \mathrm{~d} x
$$

We have proved the following theorem:
Theorem 5.3. The limit function $u_{0}$ given by Theorem 5.2 is the solution of the homogenized equation:

$$
\left\{\begin{array}{l}
u_{0} \in V,  \tag{5.25}\\
\int_{\Omega} \mathcal{A}^{\text {hom }} \nabla u_{0} \nabla \phi+\frac{k_{2}^{2}}{2} \int_{\Sigma} \boldsymbol{\Theta}\left[u_{0}\right]_{\Sigma}[\phi]_{\Sigma}=\int_{\Omega} f \phi, \\
\forall \phi \in V .
\end{array}\right.
$$

Remark 5.4. Taking $v=\theta$ in (5.24) shows that

$$
\boldsymbol{\Theta}\left(x^{\prime}\right)=\frac{1}{2} \int_{\mathbb{R}_{+}^{N} \cup \mathbb{R}_{-}^{N}} A_{0}\left(x^{\prime}, z\right) \nabla_{z} \theta\left(x^{\prime}, z\right) \nabla_{z} \theta\left(x^{\prime}, z\right) \mathrm{d} z
$$

is non-negative. This implies existence and uniqueness of the solution $u_{0}$ of (5.25).

Remark 5.5. The strong formulation for the solution $u_{0}$ of the limit problem is:

$$
\left\{\begin{array}{l}
-\operatorname{div} \mathcal{A}^{\text {hom }} \nabla u_{0}=f \quad \text { in } \Omega \backslash \Sigma, \\
\left.\mathcal{A}^{\text {hom }} \nabla u_{0} n^{-}\right|_{\Sigma}=-\left.\mathcal{A}^{\text {hom }} \nabla u_{0} n^{+}\right|_{\Sigma}=\frac{k_{2}^{2}}{2} \boldsymbol{\Theta}\left[u_{0}\right]_{\Sigma}, \\
u_{0}=0 \text { on } \partial \Omega
\end{array}\right.
$$

Remark 5.6. In the case where $A_{0}$ is even with respect to $z_{N}, \theta$ vanishes on $S$. Then, $\boldsymbol{\Theta}\left(x^{\prime}\right)$ can be interpreted as the local capacity of the set $S$, the capacitary potential being ( $1 \mp \theta^{ \pm}$).

Remark 5.7. 1. The proof for the case $k_{2}=0$ is actually simpler and the statement is included in Theorem 5.3: the holes are too small to keep any connection between $\Omega_{+}$and $\Omega_{-}$. The limit problem is split into two independent problems in each of these sets with mixed homogeneous boundary conditions,

$$
\begin{cases}-\operatorname{div} \mathcal{A}^{\text {hom }} \nabla u_{0}=f & \text { in } \Omega_{ \pm}, \\ \left.\mathcal{A}^{\text {hom }} \nabla u_{0} n^{ \pm}\right|_{\Sigma}=0 & \text { on } \Sigma, \\ u_{0}=0 & \text { on } \partial \Omega_{ \pm} \backslash \Sigma .\end{cases}
$$

2. For the case of $\lim \frac{\delta^{\frac{N}{2}-1}}{\sqrt{\varepsilon}}=\infty$, Theorem 2.24(2) implies:

$$
\left.\mathcal{T}_{\varepsilon, \delta}^{b l}\left(u_{\varepsilon, \delta}\right) \rightharpoonup u_{0}^{ \pm}\right|_{\Sigma} \quad \text { weakly in } L^{2}\left(\Sigma ; L_{\mathrm{loc}}^{2}\left(\mathbb{R}_{ \pm}^{N}\right)\right)
$$

On the other hand, $\left[\mathcal{T}_{\varepsilon, \delta}^{b l}\left(u_{\varepsilon, \delta}\right)\right]_{S}=0$ on $\Sigma \times S$ implies that $\left.\left[u_{0}\right]\right|_{\Sigma}=0$. Therefore, $u_{0}$ belongs to $H_{0}^{1}(\Omega)$ so that the limit problem is satisfied in the whole of $\Omega$.

## 6. The thick Neumann sieve with variable coefficients

In this section we extend the results of Section 5 to the case of a thick Neumann sieve of thickness of order $\varepsilon>0$. We will use the same notations, unless specified otherwise, and we only sketch the main modifications of setting and of the proof.

For an open subset $S$ of $Y \cap \Pi$ such that $S \Subset(Y \cap \Pi)$, we introduce the class $\mathcal{F}_{\mathcal{S}}$ of admissible sets, which we use to describe a thick sieve with holes shaped according to $S$.

Definition 6.1. The subset set $F$ of $\mathbb{R}^{N}$ is in $\mathcal{F}_{\mathcal{S}}$, if
(i) $F$ is closed with connected complement in $\mathbb{R}^{N}$,
(ii) $F$ is symmetric with respect to all the hyperplanes of equations $\left\{z_{j}=0, j \in 1, \ldots, N-1\right\}$ and $F=F_{+} \cup F_{-} \cup$ $\{\Pi \backslash S\}$,
(iii) $F$ is such that $F \cap \frac{1}{\delta} \bar{Y} \subset\left\{\left|z_{N}\right| \leqslant \frac{1}{2 \delta}\right\}$ for every $0<\delta \ll 1$,
(iv) $F_{+}$and $F_{-}$are unbounded with Lipschitz boundary,
(v) there exists some positive $R$ such that the boundaries $\partial F_{+}$and $\partial F_{-}$outside the ball of radius $R$, are Lipschitz graphs over $\mathbb{R}^{N-1}$.

For $F \in \mathcal{F}_{\mathcal{S}}$, set

$$
F_{\delta}=\delta F \cap Y, \quad \text { and } \quad F_{\varepsilon, \delta}=\left\{x \in \Sigma_{\varepsilon}^{\prime} \text { such that }\left\{\frac{x}{\varepsilon}\right\}_{Y} \in F_{\delta}\right\} .
$$

Define:

$$
\Omega_{\varepsilon \delta}^{n s}=\Omega \backslash F_{\varepsilon \delta} \quad \text { and } \quad S_{\varepsilon, \delta}=\Omega_{\varepsilon \delta}^{n s} \cap \Pi .
$$

Fig. 7 present an example of admissible set $F$ in dimension 3. Fig. 8 is the corresponding sieve. Fig. 9 is a two dimensional cross-section.

We use the same space $V$ as in Section 5, while the $V_{\varepsilon, \delta}$ is now:

$$
V_{\varepsilon, \delta}=\left\{v \in H^{1}\left(\Omega_{\varepsilon \delta+}^{n s} \cup \Omega_{\varepsilon \delta-}^{n s}\right),\left.v\right|_{\partial \Omega}=0,[v]_{S_{\varepsilon, \delta}}=0\right\} .
$$



Fig. 7. An example of set $F$ : the hole in the sieve.


Fig. 8. The 3D geometry of the thick Neumann sieve.


Fig. 9. A 2D cross-section of the set $F$ and the domain $\Omega_{\varepsilon, \delta}^{n s .}$.

The thick Neumann sieve problem can be stated as follows:

$$
\left\{\begin{array}{l}
\text { Find } u_{\varepsilon, \delta} \in V_{\varepsilon, \delta} \text { satisfying, }  \tag{ns}\\
\int_{\Omega_{\varepsilon, \delta}^{n s}} A^{\varepsilon} \nabla u_{\varepsilon, \delta} \nabla \phi=\int_{\Omega_{\varepsilon, \delta}^{n s}} f \phi, \quad f \in L^{2}(\Omega), \\
\forall \phi \in V_{\varepsilon, \delta} .
\end{array}\right.
$$

The equivalent of the space $\widehat{K_{S}}$ (see (5.1)) is the following, where $G$ denotes the complement of $F$ :

$$
\begin{equation*}
\widetilde{K_{G}}=\left\{\Phi \in H_{\mathrm{loc}}^{1}(G) ; \nabla \Phi \in L^{2}(G)\right\} . \tag{6.1}
\end{equation*}
$$

Proposition 6.2. There exist two linear forms $l^{ \pm}$on $\widetilde{K_{G}}$ such that for every $\Phi$ in $\widetilde{K_{G}}$, the functions $\Phi^{ \pm}-l^{ \pm}(\Phi)$ belong to $L^{2^{*}}\left(\left(\mathbb{R}^{N} \backslash F\right)_{ \pm}\right)$.

The space $\widetilde{K_{G}}$ is a Hilbert space for the norm given by:

$$
\|\Phi\|_{\widetilde{K_{G}}}^{2} \doteq\|\nabla \Phi\|_{L^{2}\left(\left(\mathbb{R}_{+}^{N} \cup \mathbb{R}_{-}^{N}\right) \backslash F\right)}^{2}+l^{+}(\Phi)^{2}+l^{-}(\Phi)^{2} .
$$

Furthermore, for this norm, $l^{+}$and $l^{-}$are continuous on $\widetilde{K_{G}}$, and

$$
\left.\widetilde{{K_{G}}} \dot{\doteq} \doteq \Phi \in \widetilde{K_{G}}, \Phi \in C^{\infty}(G), \text { supp }(\nabla \Phi) \text { bounded in } G\right\}
$$

is dense in $\widetilde{K_{G}}$.
Proof. The proof is the same as that of Proposition 5.1. The only modification concerns the sequence of sets on which the Sobolev-Poincaré-Wirtinger inequality (with a uniform constant) is applied. In view of Definition 6.1(iv), this can be achieved on the sets $\frac{1}{\delta} Y_{ \pm} \cap\left\{ \pm z_{N}>R\right\} \cap G$ (making use of [22]).

The unfolded limit problem and the standard homogenized equation are given in the next two theorems. Up to the modifications of notations indicated above, theirs proofs are the same as in Section 5.

Theorem 6.3. Let $\Omega$ be open and bounded in $\mathbb{R}^{N}, N \geqslant 3$, and $A^{\varepsilon}$ belong to $M(\alpha, \beta, \Omega)$. Suppose that, as $\varepsilon$ goes to 0 , there exists a matrix A such that

$$
\mathcal{T}_{\varepsilon}\left(A^{\varepsilon}\right)(x, y) \rightarrow A(x, y) \quad \text { a.e. in } \Omega \times Y
$$

Furthermore, suppose that there exists a matrix field $A_{0}$ such that, as $\varepsilon$ and $\delta \rightarrow 0$,

$$
\mathcal{T}_{\varepsilon, \delta}^{b l}\left(A^{\varepsilon}\right)\left(x^{\prime}, z\right) \rightarrow A_{0}\left(x^{\prime}, z\right) \quad \text { a.e. in } \Sigma \times\left(\mathbb{R}^{N} \backslash F\right)
$$

Let $u_{\varepsilon, \delta}$ be the solution of the problem $\left(\mathcal{P}_{\varepsilon, \delta}^{n s}\right)$. Then

$$
u_{\varepsilon, \delta} \rightharpoonup u_{0} \quad \text { weakly in } H_{\mathrm{loc}}^{1}(\Omega \backslash \Sigma),
$$

and there exist $\hat{u} \in L^{2}\left(\Omega ; H_{p e r}^{1}(Y)\right), U \in L^{2}\left(\Sigma ; \widetilde{K}_{G}\right)$ satisfying,

$$
l^{ \pm}(U)=k_{2}\left(u_{0}^{ \pm}\right)_{\mid \Sigma} \quad \text { for a.e. } x^{\prime} \in \Sigma
$$

and such that $\left(u_{0}, \hat{u}, U\right)$ solves the equations,

$$
\int_{Y} A(x, y)\left(\nabla_{x} u_{0}(x)+\nabla_{y} \hat{u}(x, y)\right) \nabla_{y} \phi(y) \mathrm{d} y=0,
$$

for a.e. $x$ in $\Omega$ and all $\phi \in H_{p e r}^{1}(Y)$;

$$
\int_{G} A_{0}\left(x^{\prime}, z\right) \nabla_{z} U\left(x^{\prime}, z\right) \nabla_{z} v(z) \mathrm{d} z=0
$$

for a.e. $x^{\prime}$ in $\Sigma$ and all $v \in \widetilde{K}_{G}$ with $l^{ \pm}(v)=0$,

$$
\int_{\Omega \times Y} A\left(\nabla_{x} u_{0}+\nabla_{y} \hat{u}\right) \nabla \phi-k_{2} \int_{\Sigma \times S} A_{0} \nabla_{z} U n^{+}[\phi]_{\Sigma}=\int_{\Omega} f \phi,
$$

for all $\phi \in V$.


Fig. 10. The combination of a Neumann hole $T$ and a Dirichlet hole $\delta$ B.
Theorem 6.4. The limit function $u_{0}$ given by Theorem 6.3 is the solution of the homogenized equation:

$$
\left\{\begin{array}{l}
u_{0} \in V, \\
\int_{\Omega} \mathcal{A}^{\text {hom }} \nabla u_{0} \nabla \phi+\frac{k_{2}^{2}}{2} \int_{\Sigma} \boldsymbol{\Theta}\left[u_{0}\right]_{\Sigma}[\phi]_{\Sigma}=\int_{\Omega} f \phi, \\
\forall \phi \in V,
\end{array}\right.
$$

where

$$
\boldsymbol{\Theta}\left(x^{\prime}\right)=\frac{1}{2} \int_{G} A_{0}\left(x^{\prime}, z\right) \nabla_{z} \theta\left(x^{\prime}, z\right) \nabla_{z} \theta\left(x^{\prime}, z\right) \mathrm{d} z,
$$

and $\theta$ is the solution of the cell-problem,

$$
\left\{\begin{array}{l}
\theta \in L^{\infty}\left(\Sigma ; \widetilde{K_{G}}\right), \quad l^{ \pm}\left(\theta\left(x^{\prime}, \cdot\right)\right) \equiv \pm 1, \\
\int_{G}{ }^{t} A_{0}\left(x^{\prime}, z\right) \nabla_{z} \theta\left(x^{\prime}, z\right) \nabla_{z} \Psi(z) \mathrm{d} z=0, \quad \text { a.e. for } x^{\prime} \in \Sigma, \\
\forall \Psi \in \widetilde{K_{G}} \text { with } l^{ \pm}(\Psi)=0 .
\end{array}\right.
$$

Remark 6.5. The function $\boldsymbol{\Theta}\left(x^{\prime}\right)$ can be interpreted as the local relative capacity (in $G$ ) of the set $\mathcal{C}\left(x^{\prime}\right)$ defined as the set where $\theta\left(x^{\prime}, \cdot\right)$ vanishes, the capacitary potential being $\left(1-\theta\left(x^{\prime}, \cdot\right)\right)$ "above $\mathcal{C}\left(x^{\prime}\right)$ " and $\left(1+\theta\left(x^{\prime}, \cdot\right)\right)$ "below $\mathcal{C}\left(x^{\prime}\right)$ ".

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[^0]:    * Corresponding author.

    E-mail address: damlamian@univ-paris12.fr (A. Damlamian).

