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# Positive solutions for three-point boundary value problems with dependence on the first order derivative ${ }^{\text {an }}$ 

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## Abstract

A new fixed point theorem in a cone is applied to obtain the existence of at least one positive solution for the second order three-point boundary value problem

$$
\left\{\begin{array}{l}
x^{\prime \prime}+f\left(t, x, x^{\prime}\right)=0, \quad 0<t<1, \\
x(0)=0, \quad x(1)=\alpha x(\eta),
\end{array}\right.
$$

where $f$ is a nonnegative continuous function, $\alpha>0, \eta \in(0,1), \alpha \eta<1$. The associated Green's function for the above problem is also used.
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## 1. Introduction

In the past few years, there has been much attention focused on questions of positive solutions of three-point boundary value problems for nonlinear ordinary differential equa-

[^0]tions; see, to name a few [1-7]. Recently, Ma [1] used the Krasnoselskii's fixed point theorem in a cone [8] to prove the existence of positive solutions for the second order three-point boundary value problem
\[

\left\{$$
\begin{array}{l}
u^{\prime \prime}+a(t) g(u)=0, \quad 0<t<1,  \tag{1}\\
u(0)=0, \quad u(1)=\alpha u(\eta),
\end{array}
$$\right.
\]

where $\alpha>0, \eta \in(0,1), \alpha \eta<1, a \in C([0,1],[0, \infty))$, and $g \in C([0, \infty),[0, \infty))$ is either superlinear or sublinear. Applying Leggett-Williams fixed point theorem [9], He and Ge [7] studied the existence of at least three positive solutions for the second order threepoint boundary value problem

$$
\left\{\begin{array}{l}
u^{\prime \prime}+f(t, u)=0, \quad 0<t<1  \tag{2}\\
u(0)=0, \quad u(1)=\alpha u(\eta)
\end{array}\right.
$$

All the above works were done under the assumption that the first order derivative $x^{\prime}$ is not involved explicitly in the nonlinear term $f$. In this paper, we are concerned with the existence of positive solutions for the second order three-point boundary value problem

$$
\left\{\begin{array}{l}
x^{\prime \prime}+f\left(t, x, x^{\prime}\right)=0, \quad 0<t<1,  \tag{3}\\
x(0)=0, \quad x(1)=\alpha x(\eta) .
\end{array}\right.
$$

The following conditions are satisfied throughout this paper:
$\left(H_{1}\right) \alpha>0,0<\eta<1$, and $1-\alpha \eta>0$;
$\left(H_{2}\right) f:[0,1] \times[0, \infty) \times R \rightarrow[0, \infty]$ is continuous.
In [11], Avery and Anderson extended Krasnoselskii’s fixed point theorem. In this paper, to show the existence of positive solutions to (3), a new fixed point theorem in a cone is proved at first, which can be also regarded as an extension of Krasnoselskii's fixed point theorem in a cone. Then some new criteria for the existence of positive solutions to (3) are given by applying the new theorem. This is the only work which allows $f$ to depend on the first derivative of $x$ to obtain positive solutions as far as we know.

## 2. Fixed point theorem in a cone

Let $X$ be a Banach space and $K \subset X$ a cone. Suppose $\alpha, \beta: X \rightarrow R^{+}$are two continuous convex functionals satisfying

$$
\begin{equation*}
\alpha(\lambda x)=|\lambda| \alpha(x), \quad \beta(\lambda x)=|\lambda| \beta(x), \quad \text { for } x \in X, \lambda \in R, \tag{4}
\end{equation*}
$$

and

$$
\begin{align*}
& \|x\| \leqslant M \max \{\alpha(x), \beta(x)\} \quad \text { for } x \in X \quad \text { and } \\
& \alpha(x) \leqslant \alpha(y) \quad \text { for } x, y \in K, x \leqslant y \tag{5}
\end{align*}
$$

where $M>0$ is a constant.
Lemma 2.1. Let $r, L>0$ be constants and

$$
\Omega=\{x \in X: \alpha(x)<r, \beta(x)<L\} .
$$

Set

$$
D=\{x \in X: \alpha(x)=r\}, \quad E=\{x \in X: \alpha(x) \leqslant r, \beta(x)=L\} .
$$

Assume $T: K \rightarrow K$ is a completely continuous operator satisfying
$\left(A_{1}\right) \alpha(T u)<r, u \in D \cap K$;
( $\left.A_{2}\right) \beta(T u)<L, u \in E \cap K$.
Then

$$
\operatorname{deg}\{I-T, \Omega \cap K, 0\}=1
$$

Proof. Obviously $\partial \Omega \cap K \subset(D \cap K) \cup(E \cap K)$. According to Dugundji's extension theorem [10], $\left.T\right|_{\bar{\Omega} \cap K}$ has a completely continuous extension $T^{*}: \bar{\Omega} \rightarrow K$ such that

$$
\left.T^{*}\right|_{\bar{\Omega} \cap K}=\left.T\right|_{\bar{\Omega} \cap K}, \quad T^{*}(\bar{\Omega}) \subset \overline{\operatorname{conv}} T(\bar{\Omega} \cap K) \subset K
$$

## Let

$$
h(x, \lambda)=x-\lambda T^{*} x, \quad x \in \bar{\Omega}, \lambda \in[0,1]
$$

$h(x, \lambda): \bar{\Omega} \times[0,1] \rightarrow K$ is completely continuous. We claim that $h(x, \lambda) \neq 0$ for $x \in \partial \Omega$ and $\lambda \in[0,1]$. Suppose there is $x_{0} \in \partial \Omega, \lambda_{0} \in[0,1]$ such that

$$
h\left(x_{0}, \lambda_{0}\right)=0 .
$$

Then $x_{0}=\lambda_{0} T^{*} x_{0} \in K .\left(A_{1}\right)$ and $\left(A_{2}\right)$ implies $\lambda_{0} \neq 1$.
If $x_{0} \in D \cap K$, then

$$
r=\alpha\left(x_{0}\right)=\alpha\left(\lambda_{0} T^{*} x_{0}\right)=\lambda_{0} \alpha\left(T x_{0}\right) \leqslant \lambda_{0} r<r
$$

a contradiction. On the other hand, if $x_{0} \in E \cap K$,

$$
L=\beta\left(x_{0}\right)=\beta\left(\lambda_{0} T^{*} x_{0}\right)=\beta\left(\lambda_{0} T x_{0}\right)=\lambda_{0} \beta\left(T x_{0}\right) \leqslant \lambda_{0} L<L
$$

a contradiction, too. It follows that

$$
\operatorname{deg}\{I-T, \Omega \cap K, 0\}=\operatorname{deg}\left\{I-T^{*}, \Omega, 0\right\}=\operatorname{deg}\{I, \Omega, 0\}=1
$$

Lemma 2.2. In Lemma 2.1, suppose $\left(A_{1}\right)$ and $\left(A_{2}\right)$ are replaced by
$\left(A_{3}\right) \alpha(T u)>r, u \in D \cap K$;
( $\left.A_{4}\right) \beta(T u)<L, u \in K$;
and there is a $p \in(\Omega \cap K) \backslash\{0\}$ such that $\alpha(p) \neq 0$ and $\alpha(x+\lambda p) \geqslant \alpha(x)$ for all $x \in K$ and $\lambda \geqslant 0$. Then

$$
\operatorname{deg}\{I-T, \Omega \cap K, 0\}=0
$$

Proof. Let $\eta=\max \left\{\alpha(u): u \in \overline{\operatorname{conv}} T\left(\bar{\Omega}^{*} \cap K\right)\right\}, s=1+(r+\eta) / \alpha(p)$ and $\Omega^{*}=\{x \in X: \alpha(x)<r, \beta(x)<1+L+s \beta(p)\}$.

According to Dugundji's extension theorem, $\left.T\right|_{\bar{\Omega}^{*} \cap K}$ has a completely continuous extension $T^{*}: \bar{\Omega}^{*} \rightarrow K$ such that

$$
\begin{equation*}
\left.T^{*}\right|_{\bar{\Omega}^{*} \cap K}=\left.T\right|_{\bar{\Omega}^{*} \cap K}, \quad T^{*}\left(\bar{\Omega}^{*}\right) \subset \overline{\operatorname{conv}} T\left(\bar{\Omega}^{*} \cap K\right) \subset K . \tag{6}
\end{equation*}
$$

Therefore

$$
\begin{equation*}
\alpha\left(x-T^{*} x\right) \leqslant \alpha(x)+\alpha\left(T^{*} x\right) \leqslant r+\eta, \quad \beta\left(T^{*} x\right) \leqslant L, \quad x \in \bar{\Omega}^{*} . \tag{7}
\end{equation*}
$$

Let $H(x, \lambda)=x-T^{*} x-\lambda p, 0 \leqslant \lambda \leqslant s$. We claim that $H(x, \lambda) \neq 0$ for $x \in \partial \Omega^{*}$, $\lambda \in[0, s]$. Otherwise there are $x_{0} \in \partial \Omega^{*}, \lambda_{0} \in[0, s]$ such that

$$
x_{0}-T^{*} x_{0}-\lambda_{0} p=0
$$

Then $x_{0}=T^{*} x_{0}+\lambda_{0} p \in K$. So $x_{0} \in \partial \Omega^{*} \cap K$.
(1) If $\alpha\left(x_{0}\right)=r$, then $x_{0} \in D \cap K$. From $\left(A_{3}\right)$, we have $\alpha\left(T^{*} x_{0}\right)=\alpha\left(T x_{0}\right)>r$. However,

$$
\alpha\left(T^{*} x_{0}\right) \leqslant \alpha\left(T^{*} x_{0}+\lambda_{0} p\right)=\alpha\left(x_{0}\right)=r,
$$

a contradiction.
(2) If $\beta\left(x_{0}\right)=1+L+s \beta(p)$, then

$$
1+L+s \beta(p)=\beta\left(x_{0}\right)=\beta\left(T^{*} x_{0}+\lambda_{0} p\right) \leqslant \beta\left(T^{*} x_{0}\right)+\lambda_{0} \beta(p) \leqslant L+s \beta(p)
$$

a contradiction. So

$$
\operatorname{deg}\left\{I-T^{*}, \Omega^{*}, 0\right\}=\operatorname{deg}\left\{I-T^{*}-s p, \Omega^{*}, 0\right\}=\operatorname{deg}\left\{I-T^{*}, \Omega^{*}, s p\right\}
$$

If there is $x \in \Omega^{*}$ such that $x-T^{*} x=s p$, then $\alpha\left(x-T^{*} x\right)=s \alpha(p)$ and

$$
s=\frac{\alpha\left(x-T^{*} x\right)}{\alpha(p)} \leqslant \frac{r+\eta}{\alpha(p)}<1+\frac{r+\eta}{\alpha(p)}=s,
$$

a contradiction. So $\operatorname{deg}\left\{I-T^{*}, \Omega^{*}, 0\right\}=0$.
In addition, if $x \in \Omega^{*}, x=T^{*} x,\left(A_{4}\right)$ implies

$$
\beta(x)=\beta\left(T^{*} x\right)<L,
$$

and then $x \in \Omega$. So

$$
\operatorname{deg}\{I-T, \Omega \cap K, 0\}=\operatorname{deg}\left\{I-T^{*}, \Omega, 0\right\}=\operatorname{deg}\left\{I-T^{*}, \Omega^{*}, 0\right\}=0
$$

Theorem 2.1. Let $r_{2}>r_{1}>0, L>0$ be constants and

$$
\Omega_{i}=\left\{x \in X: \alpha(x)<r_{i}, \beta(x)<L\right\}, \quad i=1,2,
$$

two bounded open sets in $X$. Set

$$
D_{i}=\left\{x \in X: \alpha(x)=r_{i}\right\} .
$$

Assume $T: K \rightarrow K$ is a completely continuous operator satisfying
(A5) $\alpha(T u)<r_{1}, u \in D_{1} \cap K ; \alpha(T u)>r_{2}, u \in D_{2} \cap K$;
( $\left.A_{6}\right) \beta(T u)<L, u \in K$;
( $A_{7}$ ) there is a $p \in(\Omega \cap K) \backslash\{0\}$ such that $\alpha(p) \neq 0$ and $\alpha(x+\lambda p) \geqslant \alpha(x)$ for all $x \in K$ and $\lambda \geqslant 0$.

Then $T$ has at least one fixed point in $\left(\Omega_{2} \backslash \bar{\Omega}_{1}\right) \cap K$.
Proof. Applying Lemmas 2.1 and 2.2,

$$
\operatorname{deg}\left\{I-T, \Omega_{1} \cap K, 0\right\}=1, \quad \operatorname{deg}\left\{I-T, \Omega_{2} \cap K, 0\right\}=0
$$

and then

$$
\begin{aligned}
\operatorname{deg}\left\{I-T,\left(\Omega_{2} \backslash \bar{\Omega}_{1}\right) \cap K, 0\right\} & =\operatorname{deg}\left\{I-T, \Omega_{2} \cap K, 0\right\}-\operatorname{deg}\left\{I-T, \Omega_{1} \cap K, 0\right\} \\
& =-1
\end{aligned}
$$

So $T$ has at least one fixed point in $\left(\Omega_{2} \backslash \bar{\Omega}_{1}\right) \cap K$.

## 3. The main results

Lemma 3.1 [1]. Let $\alpha \eta \neq 1$; then for $y \in C[0,1]$, the problem

$$
\left\{\begin{array}{l}
x^{\prime \prime}+y(t)=0, \quad 0<t<1,  \tag{8}\\
x(0)=0, \quad x(1)=\alpha x(\eta)
\end{array}\right.
$$

has a unique solution

$$
x(t)=-\int_{0}^{t}(t-s) y(s) d s+\frac{t}{1-\alpha \eta} \int_{0}^{1}(1-s) y(s) d s-\frac{\alpha t}{1-\alpha \eta} \int_{0}^{\eta}(\eta-s) y(s) d s
$$

Lemma 3.2 [1]. Let $0<\alpha<1 / \eta$. If $y \in C[0,1]$ and $y \geqslant 0$, then the unique solution $x$ of problem (8) satisfies

$$
\min _{t \in[\eta, 1]} x(t) \geqslant \gamma\|x\|
$$

where $\gamma=\min \{\alpha \eta, \alpha(1-\eta) /(1-\alpha \eta), \eta\}$.
Lemma 3.3. Let $(1-\alpha \eta) \neq 0$ and $y \in C[0,1]$. The Green function for the boundary value problem

$$
\begin{cases}-x^{\prime \prime}=0, & 0<t<1  \tag{9}\\ x(0)=0, & x(1)=\alpha x(\eta)\end{cases}
$$

is given by

$$
G(t, s)= \begin{cases}\frac{s[(1-t)-\alpha(\eta-t)]}{1-\alpha \eta}, & s \leqslant t, s \leqslant \eta, \\ \frac{s(1-t)+\alpha(t-s)}{1-\alpha \eta}, & \eta \leqslant s \leqslant t, \\ \frac{t[(1-s)-\alpha(\eta-s)]}{1-\alpha \eta}, & t \leqslant s \leqslant \eta, \\ \frac{t(1-s)}{1-\alpha \eta}, & t \leqslant s, s \geqslant \eta .\end{cases}
$$

Proof. For $t \leqslant \eta$, the unique solution of (8) can be expressed as

$$
\begin{aligned}
x(t)= & -\int_{0}^{t}(t-s) y(s) d s \\
& +\frac{t}{1-\alpha \eta}\left[\int_{0}^{t}(1-s) y(s) d s+\int_{t}^{\eta}(1-s) y(s) d s+\int_{\eta}^{1}(1-s) y(s) d s\right] \\
& -\frac{\alpha t}{1-\alpha \eta}\left[\int_{0}^{t}(\eta-s) y(s) d s+\int_{t}^{\eta}(\eta-s) y(s) d s\right] \\
= & \int_{0}^{t} \frac{s[(1-t)-\alpha(\eta-t)]}{1-\alpha \eta} y(s) d s+\int_{t}^{\eta} \frac{t[(1-s)-\alpha(\eta-s)]}{1-\alpha \eta} y(s) d s \\
& +\int_{\eta}^{1} \frac{t(1-s)}{1-\alpha \eta} y(s) d s \\
= & \int_{0}^{1} G(t, s) y(s) d s
\end{aligned}
$$

For $t \geqslant \eta$, the unique solution of (8) can be expressed as

$$
\begin{aligned}
x(t)= & -\left[\int_{0}^{\eta}(t-s) y(s) d s+\int_{\eta}^{t}(t-s) y(s) d s\right] \\
& +\frac{t}{1-\alpha \eta}\left[\int_{0}^{\eta}(1-s) y(s) d s+\int_{\eta}^{t}(1-s) y(s) d s+\int_{t}^{1}(1-s) y(s) d s\right] \\
& -\frac{\alpha t}{1-\alpha \eta} \int_{0}^{\eta}(\eta-s) y(s) d s \\
= & \int_{0}^{\eta} \frac{s[(1-t)-\alpha(\eta-t)]}{1-\alpha \eta} y(s) d s+\int_{\eta}^{t} \frac{s(1-t)+\alpha \eta(t-s)}{1-\alpha \eta} y(s) d s \\
& +\int_{t}^{1} \frac{t(1-s)}{1-\alpha \eta} y(s) d s \\
= & \int_{0}^{1} G(t, s) y(s) d s
\end{aligned}
$$

Therefore, the unique solution of (8) can be expressed as $x(t)=\int_{0}^{1} G(t, s) y(s) d s$. Lemma 3.3 is now proved.

Let $X=C^{1}([0,1], R)$ with $\|x\|=\max _{0 \leqslant t \leqslant 1}\left[x^{2}(t)+\left(x^{\prime}(t)\right)^{2}\right]^{1 / 2}$, and $K=\{x \in X$ : $x(t) \geqslant 0, x$ is concave on $[0,1]\}$. Define functionals $\alpha(x)=\max _{0 \leqslant t \leqslant 1}|x(t)|$ and $\beta(x)=$ $\max _{0 \leqslant t \leqslant 1}\left|x^{\prime}(t)\right|$ for each $x \in X$, then $\|x\| \leqslant \sqrt{2} \max \{\alpha(x), \beta(x)\}$ and

$$
\begin{aligned}
& \alpha(\lambda x)=|\lambda| \alpha(x), \quad \beta(\lambda x)=|\lambda| \beta(x), \quad x \in X, \quad \lambda \in R, \\
& \alpha(x) \leqslant \alpha(y) \quad \text { for } x, y \in K, \quad x \leqslant y .
\end{aligned}
$$

If $\left(H_{1}\right)$ holds, the Green function $G(t, s) \geqslant 0$ for the problem (9). Let $y(t)=1$, we have

$$
\int_{0}^{1} G(t, s) d s=-\frac{1}{2} t^{2}+\frac{t\left(1-\alpha \eta^{2}\right)}{2(1-\alpha \eta)}
$$

In the following, we denote

$$
M=\max _{t \in[0,1]} \int_{0}^{1} G(t, s) d s, \quad m=\max _{t \in[0,1]} \int_{\eta}^{1} G(t, s) d s, \quad Q=\frac{3-\alpha \eta+\alpha \eta^{2}}{2(1-\alpha \eta)} .
$$

We will suppose that there are $L>b>\gamma b>c>0$ such that $f(t, u, v)$ satisfies the following growth conditions:
$\left(H_{3}\right) f(t, u, v)<c / M$ for $(t, u, v) \in[0,1] \times[0, c] \times[-L, L] ;$
$\left(H_{4}\right) \quad f(t, u, v) \geqslant b / m$ for $(t, u, v) \in[0,1] \times[\gamma b, b] \times[-L, L]$;
$\left(H_{5}\right) f(t, u, v)<L / Q$ for $(t, u, v) \in[0,1] \times[0, b] \times[-L, L]$;
$\left(H_{6}\right) f(t, u, v)<L^{2} /(2 b)$ for $(t, u, v) \in[0,1] \times[0, b] \times[-L, L]$.
Let

$$
f^{*}(t, u, v)= \begin{cases}f(t, u, v), & (t, u, v) \in[0,1] \times[0, b] \times(-\infty, \infty)  \tag{10}\\ f(t, b, v), & (t, u, v) \in[0,1] \times(b, \infty) \times(-\infty, \infty)\end{cases}
$$

and

$$
f_{1}(t, u, v)= \begin{cases}f^{*}(t, u, v), & (t, u, v) \in[0,1] \times[0, \infty) \times[-L, L]  \tag{11}\\ f^{*}(t, u,-L), & (t, u, v) \in[0,1] \times[0, \infty) \times(-\infty,-L] \\ f^{*}(t, u, L), & (t, u, v) \in[0,1] \times[0, \infty) \times[L, \infty)\end{cases}
$$

Then $f_{1} \in C\left([0,1] \times[0, \infty) \times R, R^{+}\right)$. Define

$$
(T x)(t)=\int_{0}^{1} G(t, s) f_{1}\left(s, x(s), x^{\prime}(s)\right) d s
$$

Theorem 3.1. Suppose $\left(H_{1}\right)-\left(H_{5}\right)$ hold. Then BVP (3) has at least one positive solution $y(t)$ satisfying

$$
c<\alpha(x)<b, \quad\left|y^{\prime}(t)\right|<L .
$$

## Proof. Take

$$
\Omega_{1}=\left\{x \in X:|x(t)|<c,\left|x^{\prime}(t)\right|<L\right\}, \quad \Omega_{2}=\left\{x \in X:|x(t)|<b,\left|x^{\prime}(t)\right|<L\right\},
$$

two bounded open sets in $X$, and

$$
D_{1}=\{x \in X: \alpha(x)=c\}, \quad D_{2}=\{x \in X: \alpha(x)=b\} .
$$

Obviously, $T: K \rightarrow K$ is completely continuous, and there is a $p \in\left(\Omega_{2} \cap K\right) \backslash\{0\}$ such that $\alpha(x+\lambda p) \geqslant \alpha(x)$ for all $x \in K$ and $\lambda \geqslant 0$. For $x \in D_{1} \cap K, \alpha(x)=c$. From $\left(H_{3}\right)$, we get

$$
\begin{aligned}
\alpha(T x) & =\max _{t \in[0,1]}\left|\int_{0}^{1} G(t, s) f_{1}\left(s, x(s), x^{\prime}(s)\right) d s\right| \\
& <\max _{t \in[0,1]} \int_{0}^{1} G(t, s) \frac{c}{M} d s=\frac{c}{M} \max _{t \in[0,1]} \int_{0}^{1} G(t, s) d s=c
\end{aligned}
$$

Whereas for $x \in D_{2} \cap K, \alpha(x)=b$. From Lemma 3.2, we have $x(t) \geqslant \gamma \alpha(x)=\gamma b$ for $t \in[\eta, 1]$. So, from $\left(H_{4}\right)$, we get

$$
\begin{aligned}
\alpha(T x) & =\max _{t \in[0,1]}\left|\int_{0}^{1} G(t, s) f_{1}\left(s, x(s), x^{\prime}(s)\right) d s\right| \\
& >\max _{t \in[0,1]}\left|\int_{\eta}^{1} G(t, s) f_{1}\left(s, x(s), x^{\prime}(s)\right) d s\right| \\
& >\max _{t \in[0,1]} \int_{\eta}^{1} G(t, s) \frac{b}{m} d s=\frac{b}{m} \max _{t \in[0,1]} \int_{\eta}^{1} G(t, s) d s=b .
\end{aligned}
$$

For $x \in K$, from $\left(H_{5}\right)$, we get

$$
\begin{aligned}
\beta(T x)= & \max _{t \in[0,1]} \left\lvert\,-\int_{0}^{t} f_{1}\left(s, x(s), x^{\prime}(s)\right) d s+\frac{1}{1-\alpha \eta} \int_{0}^{1}(1-s) f_{1}\left(s, x(s) x^{\prime}(s)\right) d s\right. \\
& \left.-\frac{\alpha}{1-\alpha \eta} \int_{0}^{\eta}(\eta-s) f_{1}\left(s, x(s) x^{\prime}(s)\right) d s \right\rvert\, \\
< & {\left[1+\frac{1}{1-\alpha \eta} \int_{0}^{1}(1-s) d s+\frac{\alpha}{1-\alpha \eta} \int_{0}^{\eta}(\eta-s) d s\right] \frac{L}{Q} } \\
= & \frac{3-\alpha \eta+\alpha \eta^{2}}{2(1-\alpha \eta)} \frac{L}{Q}=L .
\end{aligned}
$$

Theorem 2.1 implies there is $y \in\left(\Omega_{2} \backslash \bar{\Omega}_{1}\right) \cap K$ such that $y=T y$. So, $y$ is a positive solution for BVP (3) satisfying

$$
c<\alpha(y)<b, \quad\left|y^{\prime}(t)\right|<L .
$$

Thus, Theorem 3.1 is completed.
If $\alpha \leqslant 1$, then $(T u)(1)=\alpha(T u)(\eta) \leqslant(T u)(\eta)$. Let $L_{1}>0$ such that $\max \{f(t, u, v)$, $(t, u, v) \in[0,1] \times[0, b] \times[-L, L]\}=L_{1}^{2} /(2 b)<L^{2} /(2 b)$. So, there is $\sigma \in(0,1)$ such that $\max _{0 \leqslant t \leqslant 1}(T x)(t)=(T x)(\sigma)$. For $b>a$, define

$$
\begin{aligned}
& {[A]_{a}^{b}= \begin{cases}b, & A>b, \\
A, & a \leqslant A \leqslant b, \\
a, & A<a,\end{cases} } \\
& \begin{aligned}
\left(T^{*} x\right)(t)= & \int_{0}^{t}\left[-\int_{0}^{s} f_{1}\left(r, x(r), x^{\prime}(r)\right) d r+\frac{1}{1-\alpha \eta} \int_{0}^{1}(1-r) f_{1}\left(r, x(r), x^{\prime}(r)\right) d r\right. \\
& \left.-\frac{\alpha}{1-\alpha \eta} \int_{0}^{\eta}(\eta-r) f_{1}\left(r, x(r), x^{\prime}(r)\right) d r\right]_{-L_{1}}^{L_{1}} d s+d_{x},
\end{aligned}
\end{aligned}
$$

where

$$
\begin{aligned}
d_{x}= & \int_{0}^{\sigma}\left\{\left[-\int_{0}^{s} f_{1}\left(r, x(r), x^{\prime}(r)\right) d r+\frac{1}{1-\alpha \eta} \int_{0}^{1}(1-r) f_{1}\left(r, x(r), x^{\prime}(r)\right) d r\right.\right. \\
& \left.\left.\left.-\frac{\alpha}{1-\alpha \eta} \int_{0}^{\eta}(\eta-r) f_{1}\left(r, x(r), x^{\prime}(r)\right) d r\right]_{0}^{s}\right]_{-L_{1}}^{s}\right\} \\
& -\left[-\int_{0} f_{1}\left(r, x(r), x^{\prime}(r)\right) d r+\frac{1}{1-\alpha \eta} \int_{0}^{1}(1-r) f_{1}\left(r, x(r), x^{\prime}(r)\right) d r\right. \\
& \left.\left.-\frac{\alpha}{1-\alpha \eta} \int_{0}^{\eta}(\eta-r) f_{1}\left(r, x(r), x^{\prime}(r)\right) d r\right]_{1}^{L_{1}}\right\} d s
\end{aligned}
$$

Obviously, $T^{*} x$ is well defined. It is easy to see that $T^{*}: K \rightarrow K$ is a completely continuous operator. And clearly

$$
\begin{aligned}
\alpha\left(T^{*} x\right)= & \alpha(T x) \\
= & \int_{0}^{\sigma}\left[-\int_{0}^{s} f_{1}\left(r, x(r), x^{\prime}(r)\right) d r+\frac{1}{1-\alpha \eta} \int_{0}^{1}(1-r) f_{1}\left(r, x(r), x^{\prime}(r)\right) d r\right. \\
& \left.\quad-\frac{\alpha}{1-\alpha \eta} \int_{0}^{\eta}(\eta-r) f_{1}\left(r, x(r), x^{\prime}(r)\right) d r\right] d s
\end{aligned}
$$

$$
\begin{aligned}
& =\int_{0}^{1} G(\sigma, r) f_{1}\left(r, x(r), x^{\prime}(r)\right) d r \\
\beta\left(T^{*} x\right) & \leqslant L_{1} \quad \text { for } x \in K, \quad\left(T^{*} x\right)(t) \geqslant(T x)(t), \quad t \in[0,1] .
\end{aligned}
$$

Theorem 3.2. Suppose $\left(H_{2}\right)-\left(H_{4}\right)$ and $\left(H_{6}\right)$ hold. If in addition $0<\alpha \leqslant 1, \eta \in(0,1)$, then $B V P$ (3) has at least one positive solution $y(t)$ satisfying

$$
c<\alpha(y)<b, \quad\left|y^{\prime}(t)\right|<L
$$

Proof. From $\left(H_{6}\right)$, we have $\beta\left(T^{*} x\right) \leqslant L_{1}<L$ for $x \in K$. Essentially using the same reasoning as in Theorem 3.1, we may obtain $T^{*}$ has a fixed point $y \in\left(\Omega_{2} \backslash \bar{\Omega}_{1}\right) \cap K$.

For all $x \in K$, clearly $(T x)^{\prime}(\sigma)=\left(T^{*} x\right)^{\prime}(\sigma)=0$. We now show

$$
\begin{equation*}
\left|\left(T^{*} y\right)^{\prime}(t)\right|<L_{1} \tag{12}
\end{equation*}
$$

If (12) fails to be true, from the concavity of $\left(T^{*} y\right)(t)$ there is a $t_{0} \in[0, \sigma) \cup(\sigma, 1]$, say, for example, $t_{0} \in[0, \sigma)$, such that

$$
\begin{align*}
& \left(T^{*} y\right)^{\prime}\left(t_{0}\right)=(T y)^{\prime}\left(t_{0}\right)=L_{1}, \\
& 0<\left(T^{*} y\right)^{\prime}(t)=(T y)^{\prime}(t)<L_{1}, \quad t \in\left(t_{0}, \sigma\right] \tag{13}
\end{align*}
$$

Then $\left(T^{*} y\right)(t)$ is a solution of the equation $x^{\prime \prime}+f_{1}\left(t, x, x^{\prime}\right)=0$ on the interval $\left[t_{0}, \sigma\right]$ with $0 \leqslant\left(T^{*} y\right)(t) \leqslant b$. From the definition of $L_{1}$, then

$$
\begin{equation*}
\left(T^{*} y\right)^{\prime \prime}(s) \geqslant-\frac{L_{1}^{2}}{2 b}, \quad s \in\left[t_{0}, \sigma\right] \tag{14}
\end{equation*}
$$

Multiplying $\left(T^{*} y\right)^{\prime}(s)$ on both sides of (14), one has

$$
\begin{equation*}
\left(T^{*} y\right)^{\prime \prime}(s)\left(T^{*} y\right)^{\prime}(s) \geqslant-\frac{L_{1}^{2}}{2 b}\left(T^{*} y\right)^{\prime}(s), \quad s \in\left[t_{0}, \sigma\right) \tag{15}
\end{equation*}
$$

Integrating (15) on $\left[t_{0}, \sigma\right]$, it follows that

$$
-\frac{1}{2}\left[\left(T^{*} y\right)^{\prime}\left(t_{0}\right)\right]^{2} \geqslant-\frac{L_{1}^{2}}{2 b}\left(\left(T^{*} y\right)(\sigma)-\left(T^{*} y\right)\left(t_{0}\right)\right)>-\frac{L_{1}^{2}}{2}
$$

and then $0<\left(T^{*} y\right)^{\prime}\left(t_{0}\right)<L_{1}$, a contradiction. Now it follows that

$$
\left(T^{*} y\right)(t)=(T y)(t), \quad 0 \leqslant t \leqslant 1,
$$

which implies in turn $y(t)=(T y)(t)$ and then $y(t)$ is a positive solution to BVP (3) satisfying

$$
c<\alpha(y)<b, \quad\left|y^{\prime}(t)\right|<L .
$$

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