An Intemational Joumal
computers \&
mathematics
with applications

# Nonoscillatory Solutions for Discrete Equations 

R. P. Agarwal<br>Department of Mathematical Sciences, Florida Institute of Technology Melbourne, FL 32901, U.S.A.<br>S. R. Grace<br>Department of Engineering Mathematics, Cairo University<br>Orman, Giza 12221, Egypt<br>D. O'Regan<br>Department of Mathematics, National University of Ireland<br>Galway, Ireland


#### Abstract

A nonoscillatory theory is presented for discrete equations. Our results rely on a nonlinear alternative of Leray-Schauder type for condensing operators. (c) 2003 Elsevier Science Ltd. All rights reserved.


Keywords-Nonoscillation, Nonlinear alternative, Leray-Schauder, Condensing operators.

## 1. INTRODUCTION

Section 2 presents nonoscillatory results for the discrete equation

$$
\begin{equation*}
\Delta(a(k) \Delta(y(k)+p y(k-\tau)))+F(k+1, y(k+1-\sigma))=0, \quad k \in \mathbf{N} ; \tag{1.1}
\end{equation*}
$$

here $\mathbf{N}=\{1,2, \ldots\}$. Recall a nontrivial solution of (1.1) is called oscillatory if it is neither eventually positive nor eventually negative. Otherwise, it is called nonoscillatory. Our results rely on a nonlinear alternative of Leray-Schauder type (to be found in [1]) and on a compactness criterion [2-4] in $B(\mathbf{N})$ (the Banach space of all continuous, bounded mappings from $\mathbf{N}$ (discrete topology) to $\mathbf{R}$, endowed with the usual supremum norm; i.e., $|u|_{\infty}=\sup _{i \in \mathbf{N}}|u(i)|$ for $u \in$ $B(\mathrm{~N})$ ).

Theorem 1.1. Let $C$ be a closed, convex subset of a Banach space $E$ and $U$ an open subset of $C$ with $p^{\star} \in U$. Also $N: \bar{U} \rightarrow C$ is a continuous, condensing map with $N(\bar{U})$ bounded. Then one of the following hold:
(A1) $N$ has a fixed point in $\bar{U}$; or
(A2) there is an $x \in \partial U$ and $\lambda \in(0,1)$ with $x=(1-\lambda) p^{\star}+\lambda N x$.
Theorem 1.2. Let $E$ be a uniformly bounded subset of the Banach space $B(\mathbf{N})$. If $E$ is equiconvergent at $\infty$, it is also relatively compact.

We finally remark here that the results in this paper could be established using Krasnosel'skii's fixed-point theorem instead of Theorem 1.1. Also, the results in this paper extend and correct the results in [5, Section 21].

## 2. DISCRETE EQUATIONS

In this section, we discuss the discrete equation

$$
\begin{equation*}
\Delta(a(k) \Delta(y(k)+p y(k-\tau)))+F(k+1, y(k+1-\sigma))=0, \quad k \in \mathbf{N} \tag{2.1}
\end{equation*}
$$

here $\mathbf{N}=\{1,2, \ldots\}$. Also, the following conditions are assumed throughout this section:

$$
\begin{equation*}
\tau \text { and } \sigma \text { are fixed nonnegative integers; } \tag{2.2}
\end{equation*}
$$

$F: \mathbf{N} \times(0, \infty) \rightarrow[0, \infty)$ is continuous; i.e., it is continuous as a map from the topological space $\mathbf{N} \times(0, \infty)$ into the topological space $[0, \infty)$; the topology on $\mathbf{N}$ is the discrete topology;
and

$$
\begin{equation*}
a: \mathbf{N} \rightarrow(0, \infty) \quad \text { and } \quad p \in \mathbf{R} . \tag{2.4}
\end{equation*}
$$

Theorem 2.1. Suppose (2.2)-(2.4) hold. Also assume the following two conditions are satisfied:

$$
\begin{equation*}
|p| \neq 1 \tag{2.5}
\end{equation*}
$$

and there exists $K>0$ and $k_{0} \in\{1,2, \ldots\}$ with

$$
\begin{equation*}
\sum_{k=k_{0}}^{\infty} \frac{1}{a(k)} \sum_{i=k}^{\infty} \sup _{w \in[K / 2, K]} F(i+1, w)<\infty . \tag{2.6}
\end{equation*}
$$

Then (2.1) has a bounded nonoscillatory solution.
Proof. Let $\nu=\max \{\tau, \sigma\}$. The proof will be broken into two cases, namely $|p|<1$ and $|p|>1$.
Case I. $|p|<1$.
Choose a positive integer $T>\max \left\{\nu, k_{0}\right\}$ sufficiently large so that

$$
\begin{equation*}
\sum_{k=T}^{\infty} \frac{1}{a(k)} \sum_{i=k}^{\infty} \sup _{w \in[K / 2, K]} F(i+1, w)<\frac{1}{4}(1-|p|) K . \tag{2.7}
\end{equation*}
$$

Then there exists $\epsilon>0$ with $\epsilon<K / 2$ and

$$
\begin{equation*}
\sum_{k=T}^{\infty} \frac{1}{a(k)} \sum_{i=k}^{\infty} \sup _{w \in[K / 2, K]} F(i+1, w) \leq \frac{1}{4}(1-|p|) K-\epsilon . \tag{2.8}
\end{equation*}
$$

We wish to apply Theorem 1.1. For notational purposes, let

$$
\mathbf{N}(T-\nu)=\{T-\nu, T-\nu+1, \ldots\} .
$$

We will apply Theorem 1.1 with $E=\left(B(\mathbf{N}(T-\nu)),|\cdot|_{\infty}\right)$,

$$
\begin{aligned}
& C=\left\{y \in B(\mathbf{N}(T-\nu)): y(i) \geq \frac{K}{2} \text { for } i \in \mathbf{N}(T-\nu)\right\}, \\
& U=\left\{y \in C:|y|_{\infty}<K\right\},
\end{aligned}
$$

and with $p^{\star}=K-\epsilon$,

$$
N_{1} y(i)= \begin{cases}\frac{3}{4}(1+p) K-p y(T-\tau), & i \in\{T-\nu, \ldots, T\}, \\ \frac{3}{4}(1+p) K-p y(i-\tau), & i \in\{T+1, T+2, \ldots\},\end{cases}
$$

and

$$
N_{2} y(i)= \begin{cases}0, & i \in\{T-\nu, \ldots, T\} \\ \sum_{k=T}^{i-1} \frac{1}{a(k)} \sum_{j=k}^{\infty} F(j+1, y(j+1-\sigma)), & i \in\{T+1, \ldots\}\end{cases}
$$

Notice $p^{\star} \in U$ since $0<\epsilon<K / 2$. First, we show

$$
\begin{equation*}
N=N_{1}+N_{2}: \bar{U} \rightarrow C . \tag{2.9}
\end{equation*}
$$

To see this take $y \in \bar{U}$, so in particular $K / 2 \leq y(i) \leq K$ for $i \in \mathbf{N}(T-\nu)$. Our discussion is broken into two subcases, namely $0 \leq p<1$ and $-1<p<0$.
Subcase I. $0 \leq p<1$.
If $i \in\{T+1, T+2, \ldots\}$ we have

$$
N_{1} y(i)+N_{2} y(i) \geq \frac{3}{4}(1+p) K-p y(i-\tau) \geq \frac{3}{4}(1+p) K-p K=\left(\frac{3}{4}-\frac{1}{4} p\right) K \geq \frac{K}{2},
$$

whereas, if $i \in\{T-\nu, \ldots, T\}$ we have

$$
N_{1} y(i)+N_{2} y(i)=\frac{3}{4}(1+p) K-p y(T-\tau) \geq \frac{3}{4}(1+p) K-p K \geq \frac{K}{2} .
$$

As a result, $K / 2 \leq N_{1} y(i)+N_{2} y(i)$ for $i \in \mathbf{N}(T-\nu)$ for every $y \in \bar{U}$. Thus, (2.9) holds in this case.

Subcase II. $-1<p<0$.
If $i \in\{T+1, T+2, \ldots\}$ we have

$$
N_{1} y(i)+N_{2}(i) \geq \frac{3}{4}(1+p) K-p \frac{K}{2}=\left(\frac{3}{4}+\frac{1}{4} p\right) K \geq \frac{K}{2},
$$

whereas if $i \in\{T-\nu, \ldots, T\}$ we have

$$
N_{1} y(i)+N_{2} y(i)=\frac{3}{4}(1+p) K-p y(T-\tau) \geq\left(\frac{3}{4}+\frac{1}{4} p\right) K \geq \frac{K}{2} .
$$

Thus, (2.9) holds in this case also.
Next, we show

$$
\begin{equation*}
N_{2}: \breve{U} \rightarrow E \text { is a continuous, compact map. } \tag{2.10}
\end{equation*}
$$

The continuity of $N_{2}$ is immediate from (2.3). To see that $N_{2} \bar{U}$ is relatively compact we will use Theorem 1.2. Clearly, $Y=\left\{N_{2} y: y \in \bar{U}\right\}$ is a uniformly bounded subset of $B(\mathbf{N}(T-\nu))$. Also, if $y \in \bar{U}$ and $i \in\{T+1, T+2, \ldots\}$ we have

$$
\left|N_{2} y(\infty)-N_{2} y(i)\right| \leq \sum_{k=i}^{\infty} \frac{1}{a(k)} \sum_{j=k}^{\infty} \sup _{w \in[K / 2, K]} F(j+1, w)
$$

so $Y$ is equiconvergent at $\infty$. Theorem 1.2 guarantees that $N_{2} \bar{U}$ is a relatively compact subset of $B(\mathbf{N}(T-\nu))$. Next, we claim that

$$
\begin{equation*}
N_{1}: \bar{U} \rightarrow E \text { is a contractive map. } \tag{2.11}
\end{equation*}
$$

To see this, notice if $y_{1}, y_{2} \in \bar{U}$ and $i \in\{T-\nu, \ldots, T\}$, then we have

$$
\left|N_{1} y(i)-N_{1} y_{2}(i)\right|=\left|p\left\{y_{1}(T-\tau)-y_{2}(T-\tau)\right\}\right| \leq|p|\left|y_{1}-y_{2}\right|_{\infty},
$$

whereas if $i \in\{T+1, T+2, \ldots\}$ we have

$$
\left|N_{1} y(i)-N_{1} y_{2}(i)\right|=\left|p\left\{y_{1}(i-\tau)-y_{2}(i-\tau)\right\}\right| \leq|p|\left|y_{1}-y_{2}\right|_{\infty} .
$$

Combining gives

$$
\left|N_{1} y_{1}-N_{1} y_{2}\right|_{\infty} \leq|p|\left|y_{1}-y_{2}\right|_{\infty},
$$

so (2.11) is true since $|p|<1$.
Now (2.10) and (2.11) guarantee that

$$
\begin{equation*}
N: \bar{U} \rightarrow C \text { is a continuous, condensing map. } \tag{2.12}
\end{equation*}
$$

Next, we show condition (A2) in Theorem 1.1 cannot occur. Suppose $y \in B(\mathbf{N}(T-\nu))$ is a solution of

$$
\begin{equation*}
y=(1-\lambda) p^{\star}+\lambda N y \tag{2.13}
\end{equation*}
$$

for some $\lambda \in(0,1)$ with $y \in \partial U$. Notice $K / 2 \leq y(i) \leq K$ for $i \in \mathbf{N}(T-\nu)$. Our discussion is broken into two subcases, namely $0 \leq p<1$ and $-1<p<0$.
Subcase I. $0 \leq p<1$.
If $i \in\{T+1, T+2, \ldots\}$ we have

$$
\begin{aligned}
y(i) & =(1-\lambda) p^{\star}+\lambda\left[N_{1} y(i)+N_{2} y(i)\right] \\
& \leq(1-\lambda)[K-\epsilon]+\lambda\left[\frac{3}{4}(1+p) K-p y(i-\tau)+\sum_{k=T}^{\infty} \frac{1}{a(k)} \sum_{j=k}^{\infty} \sup _{w \in[K / 2, K]} F(j+1, w)\right]
\end{aligned}
$$

and so (2.8) implies

$$
\begin{aligned}
\sup _{i \in\{T+1, T+2, \ldots\}} y(i) & \leq(1-\lambda)[K-\epsilon]+\lambda\left[\frac{3}{4}(1+p) K-p \frac{K}{2}+\left\{\frac{1}{4}(1-p) K-\epsilon\right\}\right] \\
& =(1-\lambda)[K-\epsilon]+\lambda[K-\epsilon]=K-\epsilon<K
\end{aligned}
$$

Thus,

$$
\begin{equation*}
\sup _{i \in\{T+1, T+2, \ldots\}} y(i)<K . \tag{2.14}
\end{equation*}
$$

Now if $i \in\{T-\nu, \ldots, T\}$, we have

$$
y(i)=(1-\lambda) p^{\star}+\lambda N_{1} y(i) \leq(1-\lambda)[K-\epsilon]+\lambda\left[\frac{3}{4}(1+p) K-p \frac{K}{2}\right],
$$

and so

$$
\sup _{i \in\{T-\nu, \ldots, T\}} y(i) \leq(1-\lambda)[K-\epsilon]+\lambda\left[\frac{3}{4}+\frac{1}{4} p\right] K<(1-\lambda)[K-\epsilon]+\lambda K=K .
$$

Thus,

$$
\begin{equation*}
\sup _{i \in\{T-\nu, \ldots, T\}} y(i)<K . \tag{2.15}
\end{equation*}
$$

Combining (2.14) and (2.15) gives

$$
\begin{equation*}
\sup _{i \in \mathbf{N}(T-\nu)} y(i)<K \tag{2.16}
\end{equation*}
$$

This is a contradiction since $K=|y|_{\infty}=\sup _{i \in \mathbf{N}(T-\nu)} y(i)$.

SUBCASE II. $-1<p<0$.
If $i \in\{T+1, T+2, \ldots\}$ we have

$$
y(i) \leq(1-\lambda)[K-\epsilon]+\lambda\left[\frac{3}{4}(1+p) K-p K+\sum_{k=T}^{\infty} \frac{1}{a(k)} \sum_{j=k}^{\infty} \sup _{w \in[K / 2, K]} F(j+1, w)\right] .
$$

As a result

$$
\begin{aligned}
\sup _{i \in\{T+1, T+2, \ldots\}} y(i) & \leq(1-\lambda)[K-\epsilon]+\lambda\left[\frac{3}{4}(1+p) K-p K+\left\{\frac{1}{4}(1+p) K-\epsilon\right\}\right] \\
& =(1-\lambda)[K-\epsilon]+\lambda[K-\epsilon]=K-\epsilon<K .
\end{aligned}
$$

Thus,

$$
\begin{equation*}
\sup _{i \in\{T+1, T+2, \ldots\}} y(i)<K . \tag{2.17}
\end{equation*}
$$

Now if $i \in\{T-\nu, \ldots, T\}$ we have

$$
y(i) \leq(1-\lambda)[K-\epsilon]+\lambda\left[\frac{3}{4}(1+p) K-p K\right],
$$

and so

$$
\sup _{i \in\{T-\nu, \ldots, T\}} y(i) \leq(1-\lambda)[K-\epsilon]+\lambda\left[\frac{3}{4}-\frac{1}{4} p\right] K<(1-\lambda)[K-\epsilon]+\lambda K=K .
$$

Thus,

$$
\begin{equation*}
\sup _{i \in\{T-\nu, \ldots, T\}} y(i)<K . \tag{2.18}
\end{equation*}
$$

Combining (2.17) and (2.18) gives

$$
\sup _{i \in \mathbf{N}(T-\nu)} y(i)<K
$$

a contradiction.
Theorem 1.1 implies that there exists $y \in \bar{U}$ with $y=N_{1} y+N_{2} y$. Hence, for $i \in\{T+1, T+$ $2, \ldots\}$ we have

$$
y(i)=\frac{3}{4}(1+p) K-p y(i-\tau)+\sum_{k=T}^{i-1} \frac{1}{a(k)} \sum_{j=k}^{\infty} F(j+1, y(j+1-\sigma)),
$$

so the proof is complete in this case.
Case II. $|p|>1$.
Choose a positive integer $T>\max \left\{\nu, k_{0}\right\}$ sufficiently large so that

$$
\sum_{k=T}^{\infty} \frac{1}{a(k)} \sum_{i=k}^{\infty} \sup _{w \in\lfloor K / 2, K]} F(i+1, w)<\frac{1}{4}(|p|-1) K .
$$

Then there exists $\epsilon>0$ with $\epsilon<K / 2$ and

$$
\sum_{k=T}^{\infty} \frac{1}{a(k)} \sum_{i=k}^{\infty} \sup _{w \in[K / 2, K]} F(i+1, w) \leq \frac{1}{4}(|p|-1) K-\epsilon .
$$

Let $E, C, U$, and $p^{*}$ be as in Case I with

$$
N_{1} y(i)= \begin{cases}\frac{3}{4}\left(\frac{1+p}{p}\right) K-\frac{1}{p} y(T+\tau), & i \in\{T-\nu, \ldots, T\}, \\ \frac{3}{4}\left(\frac{1+p}{p}\right) K-\frac{1}{p} y(i+\tau), & i \in\{T+1, \ldots\}\end{cases}
$$

and

$$
N_{2} y(i)= \begin{cases}0, & i \in\{T-\nu, \ldots, T\} \\ \frac{1}{p} \sum_{k=T}^{i+\tau-1} \frac{1}{a(k)} \sum_{j=k}^{\infty} F(j+1, y(j+1-\sigma)), & i \in\{T+1, \ldots\}\end{cases}
$$

A slight modification of the argument in Case I guarantees that $N=N_{1}+N_{2}: \bar{U} \rightarrow C$ is a continuous, condensing map, and any solution $y$ to (2.13) $)_{\lambda}$ satisfies $|y|_{\infty} \neq K$. Now apply Theorem 1.1.

In Theorem 2.1 it is possible to replace (2.6) with the less restrictive condition: there exists $K>0$ and $k_{0} \in\{1,2, \ldots\}$ with

$$
\begin{equation*}
\sum_{k=k_{0}}^{\infty} \frac{1}{a(k)} \sum_{i=k_{0}}^{k-1} \sup _{w \in[K / 2, K]} F(i+1, w)<\infty \tag{2.19}
\end{equation*}
$$

The proof is essentially the same as the proof in Theorem 2.1; the only difference is that we write $N_{2}$ in Case I as

$$
N_{2} y(i)= \begin{cases}0, & i \in\{T-\nu, \ldots, T\}, \\ \sum_{k=i}^{\infty} \frac{1}{a(k)} \sum_{j=T}^{k-1} F(j+1, y(j+1-\sigma)), & i \in\{T+1, \ldots\},\end{cases}
$$

and $N_{2}$ is Case II as

$$
N_{2} y(i)= \begin{cases}0, & i \in\{T-\nu, \ldots, T\}, \\ \frac{1}{p} \sum_{k=i+\tau}^{\infty} \frac{1}{a(k)} \sum_{j=T}^{k-1} F(j+1, y(j+1-\sigma)), & i \in\{T+1, \ldots\} .\end{cases}
$$

Thus, we have the following theorem.
Theorem 2.2. Suppose (2.2)-(2.5) are satisfied. Also, assume there exists $K>0$ and $k_{0} \in$ $\{1,2, \ldots\}$ with (2.19) holding. Then (2.1) has a bounded nonoscillatory solution.
Remark 2.1. It is possible to use the ideas in [5, Section 21] to discuss when the solution $y$ in Theorem 2.1 (or Theorem 2.2) lies in $M^{+}$, etc. (see [5] for the appropriate definitions). We leave the details to the reader.
Remark 2.2. Minor adjustments are only necessary to discuss higher-order equations. Again the details are left to the reader.

## REFERENCES

1. J. Dugundji and A. Granas, Fixed point theory, Monografie Mathematyczne 61, PWN, Warszawa, (1982).
2. R.P. Agarwal and D. O'Regan, Existence principles for continuous and discrete equations on infinite intervals in Banach spaces, Math. Nachr. 207, 5-19, (1999).
3. N. Dunford and J. Schwartz, Linear Operators, Interscience, New York, (1958).
4. B. Przeradzki, The existence of bounded solutions for differential equations in Hilbert spaces, Ann. Polon. Math. 56, 103-121, (1992).
5. R.P. Agarwal and P.J.Y. Wong, Advanced Topics in Difference Equations, Kluwer Academic, Dordrecht, (1997).
6. R.P. Agarwal, S.R. Grace and D. O'Regan, Oscillation Theory for Second Order Dynamic Equations, Taylor \& Francis, London, (2003).
7. L.H. Erbe, Q.K. Kong and B.G. Zhang, Oscillation Theory for Functional Differential Equations, Marcel Dekker, New York, (1995).
8. I. Győri and G. Ladas, Oscillation Theory of Delay Differential Equations with Applications, Clarendon Press, Oxford, (1991).
9. G.S. Ladde, V. Lakshmikantham and B.G. Zhang, Oscillation Theory of Differential Equations with Deviating Arguments, Marcel Dekker, New York, (1987).
