# A true concurrency model of CCS semantics 

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#### Abstract

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Degano et al. (1989) introduced $\mathrm{AC} / \mathrm{E}$ systems (augmented C/E systems) to give a true concurrency semantics to CCS. But the true concurrency was not complete. There was no true concurrency for recursive agents (like $\langle x\rangle \cdot e_{1} \mid e_{2}$ ) and nondcterminant agents (like $e_{1}\left|e_{2}+e_{3}\right| e_{4}$ ). Also the concept of bisimulation has not been transplanted to $\mathrm{AC} / \mathrm{E}$ systems. This paper defines a complete true concurrency model of CCS by exploiting the potential concurrency of any CCS agent to its full strength. It introduces a kind of multilayered Petri nets, called NP/R nets, to define the processes on $A C / E$ systems. We also introduced the notion of bisimulation of groups of $N P / R$ nets and proved that this bisimulation relation can determine the CCS bisimulation uniquely.


## 1. Introduction

The interleaving semantics of CCS given by Milner [3] is well-known. This semantics allows the actions of concurrent agents to occur in different orders, but not "without orders". Therefore, the interleaving semantics is not considered as a true concurrent one. Degano et al. [1] used a new kind of net systems, the so-called contact-free augmented $\mathrm{C} / \mathrm{E}$ systems ( $\mathrm{AC} / \mathrm{E}$ systems), to give a true concurrent semantics to CCS. They decomposed a CCS agent into a set of grapes which can act concurrently. The derivation of a set of grapes corresponds to the firing of an event of the related $\mathrm{AC} / \mathrm{E}$ system. Therefore, the concurrency of event firings of $\mathrm{AC} / \mathrm{E}$ systems guarantees the concurrency of grapes derivations and thus the concurrency of CCS

[^0]agent derivations. But their solution was not perfect. According to their approach, the first step of the derivation of $e_{1}\left|e_{2}+e_{3}\right| e_{4}$ or $\langle x\rangle . e_{1} \mid e_{2}$ (recursive agent) can only be sequential, not concurrent. Another defect of their approach was the absence of bisimulation concepts for AC/E systems, the importance of which should not be underestimated. Without this concept one cannot compare the behaviors of two $\mathrm{AC} / \mathrm{E}$ systems and their relation to behaviors of CCS agents. The reason of this absence may be the fact that the $\mathrm{AC} / \mathrm{E}$ systems defined by Degano et al. are in general not contact-free in the usual net-theoretical sense. It lacks a tool (like the occurrence net) to define processes of such systems. In this paper, we introduce a new kind of Petri nets, called $N P / R$ nets, to define processes on $A C / E$ systems. We define also the bisimulation concept for groups of NP/R nets and prove that this bisimulation relation is necessary and sufficient for the existence of a bisimulation relation between corresponding CCS agents. We also solve the problem of completely decomposing CCS agents into sets of concurrent grapes, including those of form $e_{1}\left|e_{2}+e_{3}\right| e_{4}$ or $\langle x\rangle . e_{1} \mid e_{2}$. Thus, we give a new true concurrent semantics to CCS.

## 2. AC/E systems and NP/R nets

Definition 2.1. Let $N=(S, T, F)$ be a net, $M$ be a subset of $S$, called a marking. An event $e \in T$ is said to be $a$-enabled under the marking $M$, if the following condition is fulfilled:

$$
\begin{equation*}
e \subseteq M \& e^{\bullet} \subseteq \cdot e \cup(S-M) \tag{1}
\end{equation*}
$$

Definition 2.2. Let $N=(S, T, F)$ be a net, $M_{1}, M_{2} \subseteq S, B \subseteq T$, and suppose that the following conditions are fulfilled:
(a) $\forall e \in B, e$ is $a$-enabled under $M_{1}$,
(b) $\forall e_{1}, e_{2} \in B, e_{1} \neq e_{2} \rightarrow{ }^{\circ} e_{1} \cap^{\bullet} e_{2}=e_{1}^{*} \cap e_{2}^{*}=\emptyset$,
(c) $\quad M_{2}=\left(M_{1}-B\right) \cup B^{*}$.

Then the events in $B$ are said to be concurrently a-enabled under $M_{1}$.
Further we saly that the marking $M_{2}$ is reached after the concurrent firing of the events in $B$. We call this firing an $a$-step and denote it by

$$
\begin{equation*}
M_{1}\left[B>M_{2}\right. \tag{4}
\end{equation*}
$$

We also say that $B$ is a step forward from $M_{1}$ to $M_{2}$, and at the same time a step backward from $M_{2}$ to $M_{1}$.

It is called a maximal $a$-step if there is no $B^{\prime}$ with $B^{\prime} \supset B\left(B^{\prime}\right.$ contains $B$ properly) such that the events of $B^{\prime}$ can fire concurrently under $M_{1}$.

Definition 2.3. $\Sigma=(S, T, F, C)$ is called an extended $C / E$ system-an $A C / E$ system for short-if
(1) $(S, T, F)$ is a net;
(2) $C$ is a set of markings with the property that for any two different markings (called cases henceforth) $M_{1}$ and $M_{2}$, there exists a chain of forward and/or backward steps, which transforms $M_{1}$ into $M_{2}$; and
(3) For each $e \in T$, there exists a case $M \in C$, such that $e$ is a-enabled under $M$.

Here the concepts "a-enabled" and "a-steps" are used because some pre-conditions of an event may coincide with some postconditions of the same event, if the net is nonpure. In that case it is difficult to decide whether the event has already fired.

Example 2.4. The event in Fig. 1 is a-enabled. Its (only) pre-condition coincides with its post-condition.

Corollary 2.5. Any $C / E$ system is an $A C / E$ system.
Definition 2.6. Let $\Sigma=(S, T, F, C)$ be an $\Lambda \mathrm{C} / \mathrm{E}$ system. A triple $R=\{R[i]=$ $\left.\left(S_{i}, T_{i}, F_{i}\right) \mid i=1,2,3, \ldots\right\}$ is called an $N P / R$ net over $\Sigma$ (or a $N P / R$ net for short) if the following conditions are satisfied.
(a) $K=\left(\bigcup S_{i}, \bigcup T_{i}, \bigcup F_{i}\right)$ is an occurrence net.
(b) $\forall i, F_{i}=\bigcup_{i \leqslant j} F_{i j}$,

$$
\begin{equation*}
\forall i \leqslant j, \quad F_{i j} \subseteq S_{i} \times T_{j} \cup T_{i} \times S_{j} \tag{5}
\end{equation*}
$$

(c) $\forall x \in S_{i} \cup T_{i}$, let

$$
\begin{align*}
& \cdot x=\left\{y \mid \exists j \leqslant i,(y, x) \in F_{j i}\right\},  \tag{6}\\
& x^{\cdot}=\left\{y \mid \exists j \geqslant i,(x, y) \in F_{i j}\right\} .
\end{align*}
$$

(d) If $S^{\prime}=\bigcup S_{i}, T^{\prime}=\bigcup T_{i}, F^{\prime}=\bigcup F_{i}$, then there exists a mapping

$$
\begin{equation*}
p: S^{\prime} \rightarrow S, \quad T^{\prime} \rightarrow T, \quad F^{\prime} \rightarrow F, \tag{7}
\end{equation*}
$$

such that $\forall i, \forall x, y \in S_{i} \cup T_{i}$ :

$$
\begin{align*}
& (x, y) \in F^{\prime} \rightarrow p((x, y))=(p(x), p(y)) \in F,  \tag{8}\\
& x \neq y \rightarrow p(x) \neq p(y),
\end{align*}
$$



Fig. 1. An AC/E system.
and

$$
\begin{equation*}
\forall i, x \in T_{i}, \quad p\left({ }^{\bullet} x\right)=\bullet p(x) \wedge p\left(x^{\bullet}\right)=p(x)^{\bullet} \tag{9}
\end{equation*}
$$

We call $R[i]$ the $i$ th page of $R$, and $S_{i}, T_{i}, F_{i}$ the condition set, event set and arc set of $R[i]$, respectively. Finally, we call ${ }^{\circ} x$ and $x^{\bullet}$ the preset and postset of $x$, respectively.

Corollary 2.7. It follows from (8) that for any $x \in S_{i} \cup T_{i}$ such that $p(x)=y$ we may use the notation $y[i](=x)$.

Example 2.8. In Fig. 2, (a) and (b) are two AC/E systems, and (c) and (d) are two NP/R nets over them, where $c$ has infinitely many pages.

Definition 2.9. Given an $\mathrm{AC} / \mathrm{E}$ system $\Sigma$. The sequence $c_{i}\left[B_{i}\right\rangle c_{i+1}, 1 \leqslant i \leqslant n$, is called a step sequence of $\Sigma$, where each element of the sequence is an a-step (a step for short). In the following, we will not differentiate between the terminologies step sequence, firing sequence, or a run. A successive subsequence of a step sequence is called a subrun. We denote the set of all event occurrences of the run $A$ with $e v(A)$, and the $i$ th occurrence of the event $e$ in it with $e\langle i\rangle$.

Definition 2.10. Given a run $A$ of an $\mathrm{AC} / \mathrm{E}$ system $\Sigma$. Define the partial order of the event occurrences in $e v(A)$ as follows. Let $A$ be composed of the step sequence $c_{i}\left[B_{i}>c_{i+1}\right.$, then:
(1) $e_{1}$ is before $e_{2}$, or in other words, $e_{2}$ is after $e_{1}$, if $i<k, e_{1} \in B_{i}, e_{2} \in B_{k}$.
(2) there is no other order among the event occurrences besides the one mentioned above.

Corollary 2.11. The order given above is a partial order.
Definition 2.12. Let $R$ be an NP/R net. Define relations $<, r l i$ and $r c o$ as follows.
(a) If the elements $x[i], y[j]$ of $R$, when considered as elements of the corresponding occurrence net (see Definition 2.6(a)), satisfy

$$
x[i]<y[j],
$$

then the following is also true:

$$
\begin{equation*}
x[i] \prec y[j] . \tag{10}
\end{equation*}
$$

(b) $\quad \forall i<k, x[i]<y[k]$.
(c) $\forall i, j, k, x[i] \prec y[j] \wedge y[j] \prec z[k] \Rightarrow x[i] \prec z[k]$.
(d) $\forall i, j$, if $x\lceil i\rceil \prec y\lceil j\rceil$, then one of (a)-(c) must be valid.
(e) $\forall i, j, x[i]=y[j] \vee x[i] \prec y[j] \vee y[j] \prec x[i] \Leftrightarrow x[i] \operatorname{rliy} y[j]$

$$
\begin{equation*}
\forall i, j, \sim x[i] \prec y[j] \wedge \sim y[j] \prec x[i] \Leftrightarrow x[i] \operatorname{rco} y[j] \tag{14}
\end{equation*}
$$

Theorem 2.13. (1) $x[i]<y[i] \Rightarrow x[i]<y[i]$,
(2) relation $<$ is transitive,
(3) relation $<$ is anti-symmetric,
(4) therefore, $<$ is a partial order.

Definition 2.14. Let $R$ be a NP/R net, $Q \subseteq\left(\bigcup S_{i}\right) \cup\left(\bigcup T_{j}\right)$, then:
(1) $Q$ is called an $r$-line, if $\forall x, y \in Q$, there is always $x r l i y$, and $\forall z \notin Q, \exists t \in Q, \sim z r l i t$;
(2) $Q$ is called an $r$-slice, if $\forall x, y \in Q$, there is always $x \operatorname{rco} y$, and $\forall z \notin Q, \exists t \in Q$, $\sim z r c o t$.

Definition 2.15. Let $R=\left\{R[i]=\left(S_{i}, T_{i}, F_{i}\right) \mid i=1,2,3, \ldots\right\}$ be an NP/R net over the $\mathrm{AC} / \mathrm{E}$ system $\Sigma=(S, T, F, C)$. Let $A$ be a run of $\Sigma . R$ is called an exact description of $A$, if the following conditions are satisficd:
(1) There is a bi-unique mapping $\beta$ :

$$
\begin{equation*}
\beta: e v(A) \rightarrow \bigcup T_{i} \tag{16}
\end{equation*}
$$

(2) The mapping $p$ of Definition 2.6 has the following properties:
(2.1) $p$ is an internal mapping on each $r$-slice of $R$.
(2.2) Let $\alpha$ be a single-valued mapping which maps each event occurrence $a\langle i\rangle$ of $\operatorname{ev}(A)$ to the event a of $\Sigma$, then we have

$$
\begin{equation*}
\forall t \in e v(A), \quad \alpha(t)=p(\beta(t)) \tag{17}
\end{equation*}
$$

(3) For $t_{1}, t_{2} \in e v(A), t_{2}$ is behind $t_{1}$ if and only if $\beta\left(t_{1}\right)<\beta\left(t_{2}\right)$.

This mapping $p$ is called a process of $\Sigma$.
Theorem 2.16. Let $\Sigma=(S, T, F, C)$ be an AC/E system, then for each run $A$ of $\Sigma$, there must be an NP/R net $R$ over $\Sigma$, such that $R$ is an exact description of $A$.

Proof. Let $A$ be a step sequence $B_{1}, B_{2}, B_{3}, \ldots$. We construct the corresponding NP/R net, starting from $B_{1}$.

Step I. Assume that $\left\{e_{1}, \ldots, e_{l}\right\}$ is the set of events firing concurrently in $B_{1}$. Let

$$
\begin{equation*}
\cdot e_{i}=\left\{a_{i 1}, \ldots, a_{i n_{i}}\right\}, \quad e_{i}^{\bullet}=\left\{b_{i 1}, \ldots, b_{i m_{i}}\right\}, \quad 1 \leqslant i \leqslant l . \tag{18}
\end{equation*}
$$

Construct new objects $t_{1}, \ldots, t_{i}$. For each $i$, construct new objects $x_{i 1}, \ldots, x_{i n_{i}}$; $y_{i 1}, \ldots, y_{i m_{i}}$. Let

$$
\begin{equation*}
X_{i}=\left\{x_{i 1}, \ldots, x_{i n_{i}}\right\}, \quad Y_{i}=\left\{y_{i 1}, \ldots, y_{i m_{i}}\right\}, \quad 1 \leqslant i \leqslant l \tag{19}
\end{equation*}
$$

Define a mapping $p$ :

$$
\begin{align*}
& \forall i, j, \quad p\left(x_{i j}\right)=a_{i j}, \quad p\left(y_{i j}\right)=b_{i j} \\
& p\left(t_{i}\right)=e_{i}, \quad p((x, y))=(p(x), p(y)) \tag{20}
\end{align*}
$$

Call the $t_{i}$ 's, $x_{i j}$ 's and $y_{i j}$ 's separable objects, and their $p$-mappings $e_{i}$ 's, $a_{i j}$ 's, $b_{i j}$ 's original objects. Obviously, $p$ is single-valued. Further let

$$
\begin{align*}
& F_{11}=\bigcup_{i=1}^{l} \bigcup_{j=1}^{n_{i}}\left\{\left(x_{i j}, t_{i}\right)\right\}, \quad F_{12}=\bigcup_{i=1}^{l} \bigcup_{j=1}^{m_{i}}\left\{\left(t_{i}, y_{i j}\right)\right\} ;  \tag{21}\\
& S_{1}=\bar{X}_{1}=\bigcup_{i=1}^{l} X_{i}, \quad \bar{Y}_{1}=\bigcup_{i=1}^{l} Y_{i}, \quad T_{1}=\bigcup_{i=1}^{l}\left\{t_{i}\right\}, \quad F_{1}=F_{11} \cup F_{12} ;  \tag{22}\\
& R[1]-\left(S_{1}, T_{1}, F_{1}\right) .
\end{align*}
$$

Step II. Assume that we have already constructed $R[1], \ldots, R[k]$ for the steps $B_{1}, \ldots, B_{k}$. Differentiate between two different cases.

Case 1: The number of steps of $A$ is greater than $k$. Let

$$
R[i]=\left(S_{i}, T_{i}, F_{i}\right), \quad 1 \leqslant i \leqslant k .
$$

At first, we construct a new page. Let

$$
\begin{equation*}
Y^{(k)}=\bigcup_{i=1}^{k} \bar{Y}_{i}, \quad Y^{\prime}=p\left(Y^{(k)}\right) . \tag{23}
\end{equation*}
$$

Note that above we have extended the mapping $p$, in such a way that it maps also sets of objects to sets of objects.

Furthermore, let the events that fire concurrently in $B_{K+1}$ be $f_{1}, \ldots, f_{h}$.

$$
\begin{equation*}
\cdot f_{i}=\left(a_{i 1}, \ldots, a_{i n_{i}}\right), \quad f_{i}^{*}=\left(b_{i 1}, \ldots, b_{i m_{i}}\right), \quad 1 \leqslant i \leqslant h . \tag{24}
\end{equation*}
$$

Let

$$
\begin{equation*}
Y^{\prime \prime}=\left(\bigcup_{i=1}^{h} \cdot f_{i}\right) \cap Y^{\prime} . \tag{25}
\end{equation*}
$$

If $Y^{\prime \prime}=\emptyset$, then construct $\bar{X}_{k+1}, \bar{Y}_{k+1}, S_{k+1}, T_{k+1}, F_{k+1}$ and

$$
R[k+1]=\left(S_{k+1}, T_{k+1}, F_{k+1}\right)
$$

in the same way as we constructed $R[1]$.
If $Y^{\prime \prime} \neq \emptyset$, let $Y^{\prime \prime \prime}=\left\{y \mid p(y) \in Y^{\prime \prime}\right\}$. Then

$$
\begin{equation*}
\forall i, \quad \cdot f_{i}-Y^{\prime \prime}=\left\{a_{i 1}, \ldots, a_{i g_{i}}\right\}, \quad 0 \leqslant g_{i} \leqslant n_{i} . \tag{26}
\end{equation*}
$$

Generate new objects $u_{1}, \ldots, u_{h}$. For each $i$, generate new objects $x_{i 1}, \ldots, x_{i g}$; $y_{i 1}, \ldots, y_{i m_{i}}$. Let

$$
\begin{align*}
& X_{i}=\left\{x_{i 1}, \ldots, x_{i g_{i}}\right\}, \quad Y_{i}=\left\{y_{i 1}, \ldots, y_{i m}\right\}, \quad 1 \leqslant i \leqslant h ;  \tag{27}\\
& \bar{X}_{k+1}=\bigcup_{i=1}^{h} X_{i}, \quad \bar{Y}_{k+1}=\bigcup_{i=1}^{h} Y_{i}, \\
& S_{k+1}=\bar{X}_{k+1} \cup \bar{Y}_{k}, \quad T_{k+1}=\bigcup_{i=1}^{h}\left\{f_{i}\right\} ; \tag{28}
\end{align*}
$$

$$
\begin{align*}
& F_{11}=\bigcup_{i=1}^{h} \bigcup_{j=1}^{g_{i}}\left\{\left(x_{i j}, u_{i}\right)\right\}, \\
& F_{12}=\bigcup_{i=1}^{h}\left\{\left(y, u_{i}\right) \mid y \in \bar{Y}_{k}, p(y) \in \cdot f_{i}\right\},  \tag{29}\\
& F_{13}=\bigcup_{i=1}^{h} \bigcup_{j=1}^{m_{i}}\left\{\left(u_{i}, y_{i j}\right)\right\}, \\
& F_{k+1}=F_{11} \cup F_{12} \cup F_{13} ; \\
& R[k+1]=\left(S_{k+1}, T_{k+1}, F_{k+1}\right) .
\end{align*}
$$

Now, for $1 \leqslant i \leqslant k$, modify the sets of objects constructed above as follows:

$$
\begin{align*}
& F_{i}^{\prime}=\bigcup\left\{(x, y) \mid x \in \bar{Y}_{i-1} \cap Y^{\prime \prime \prime}, y \in T_{k+1}\right\}, \\
& F_{i}:=F_{i} \cup F_{i}^{\prime},  \tag{30}\\
& \bar{Y}_{i}:=\bar{Y}_{i}-Y^{\prime \prime \prime} . \tag{31}
\end{align*}
$$

Note that $:=$ is the assignment symbol. It just replaces the content of the left-hand side by the right-hand side.

Extend the mapping $p$ as follows:

$$
\begin{align*}
& \forall i, 1 \leqslant i \leqslant h: \quad p\left(x_{i j}\right)=a_{i j}, \quad 1 \leqslant j \leqslant g_{i}, \\
& p\left(y_{i j}\right)=b_{i j}, \quad 1 \leqslant j \leqslant m_{i},  \tag{32}\\
& p\left(u_{i}\right)=f_{i}, \\
& p((x, y))=(p(x), p(y)) .
\end{align*}
$$

Case 2: The number of steps of $A$ is $k$. Let

$$
\begin{equation*}
S_{k+1}=\bar{Y}_{k}, \quad R[k+1]=\left(S_{k+1}, \emptyset, \emptyset\right) . \tag{33}
\end{equation*}
$$

In this way, we get a (finitely or infinitely) multi-layered net on $\Sigma$.

$$
R=\left\{R[i]=\left(S_{i}, T_{i}, F_{i}\right) \mid i=1,2,3, \ldots\right\} .
$$

We prove that $R$ is an NP/R net over $\Sigma$.
(i) In order to prove that $K_{0}=\left(S_{0}, T_{0}, F_{0}\right)$ is an occurrence net, where

$$
\begin{equation*}
S_{0}=\bigcup S_{i}, \quad T_{0}=\bigcup T_{i}, \quad F_{0}=\bigcup F_{i}, \tag{34}
\end{equation*}
$$

we define the union of two occurrence nets as follows:

$$
\begin{array}{r}
\left(K^{\prime}=\left(S^{\prime}, T^{\prime}, F^{\prime}\right)\right) \cup\left(K^{\prime \prime}=\left(S^{\prime \prime}, T^{\prime \prime}, F^{\prime \prime}\right)\right) \\
=\left(K^{\prime \prime \prime}=\left(S^{\prime} \cup S^{\prime \prime}, T^{\prime} \cup T^{\prime \prime}, F^{\prime} \cup F^{\prime \prime}\right)\right) \tag{35}
\end{array}
$$

The proof proceeds inductively. It is easy to see that

$$
\begin{equation*}
\forall i, j, \quad\left|\cdot x_{i j}\right|=\left|y_{i j}\right|=0, \quad\left|x_{i j}\right|=\left|\cdot y_{i j}\right|=1 \tag{36}
\end{equation*}
$$

was valid in the first step when constructing $R[1]$. Therefore $R[1]$ is an occurrence net (see e.g. 「5, Section 3.2]).
Now assume that $R^{(k)}=R[1] \cup R[2] \cup \cdots \cup R[k]$ is an occurrence net. Our assertion is already proved if the run $A$ has only $k$ steps. Otherwise, construct $R[k+1]=\left(S_{k+1}, T_{k+1}, F_{k+1}\right)$ by using the method given above. From the way we constructed $R[k+1]$ we know that $R[k+1]$ remains an occurrence net before the assignment formulas of (30). It has no common elements with $R^{(k)}$, i.e.

$$
\begin{equation*}
\left(S^{(k)} \cup T^{(k)}\right) \cap\left(S_{k+1} \cup T_{k+1}\right)=\emptyset . \tag{37}
\end{equation*}
$$

In the assignment of (30) and thereafter, the modification to $R[k+1]$ is only the addition of some arcs from certain condition elements $x$ (satisfying $x^{\bullet}=\emptyset$ ) of $R^{(k)}$ to certain event elements $y$ (satisfying $y=\emptyset$ ) of $R[k+1]$. Therefore, if we construct

$$
\begin{equation*}
R^{(k+1)}=R[k+1] \cup R^{(k)} \tag{38}
\end{equation*}
$$

then all its condition elements $x$ still satisfy $|\cdot x| \leqslant 1,|x| \leqslant 1$, and there is no cycle in it. That means $R^{(k+1)}$ is still an occurrence net.
(ii) The validity of (b)-(d) of Definition 2.6 is easy to prove.
(iii) In order to see the existence of the mapping $p$ we need only to note that the mapping $p$ produced when constructing $R$ is precisely the mapping $p$ required in Definition 2.6. The validity of requirements (8) and (9) can be checked in a straightforward way.
Thus we have shown that $R$ is really a NP/R net over $\Sigma$. Now we prove that it is also an exact simulation of the run $A$ (see Definition 2.15) as follows:
(i) From the way we constructed $R$ we know, that there is an one-to-one correspondence between the objects of $\bigcup T_{i}$ and the event occurrences of $A=\left\{B_{j}\right\}$, where $B_{j}$ are the steps of $A$. This correspondence is the mapping $\beta$ required in Definition 2.15.
(ii) To prove that $p$ is injective on each $r$-slice of $R$ we assume that $Q$ is such a $r$-slice, $x[i], y[j] \in Q, x[i] \neq y[j]$. Then $i=j$ follows from the definition of partial order of NP/R nets.

From (8) of Definition 2.16 we know that

$$
\begin{equation*}
p(x[i]) \neq p(y[i]) . \tag{39}
\end{equation*}
$$

This shows that $p$ is injective on $Q$.
(iii) To prove (17) we assume that $e\langle j\rangle$ (the $j$ th occurrence of the cvent $e$ in $A$ ) is in the $i$ th step $B_{i}$ of $A$. Then there is a unique element $t=\beta(e\langle j\rangle)$ corresponding to it, which is generated as a new object when constructing $R[i]$. It is $p(t)=e$ according to the definition of $p$. This is consistent with the fact $\alpha(e\langle j\rangle)=e$.
(iv) To prove property (3) of Definition 2.15, assume that $t_{1}, t_{2} \in e v(A)$ and $t_{2}$ is behind $t_{1}$. From Definition 2.10 we know $\exists B_{i}, B_{j}, t_{1} \in B_{i}, t_{2} \in B_{j}, i<j$. We know also that $\beta\left(t_{1}\right)$ and $\beta\left(t_{2}\right)$ are objects of $R[i]$ and $R[j]$ from the way we constructed $R$. Thus $\beta\left(t_{1}\right)<\beta\left(t_{2}\right)$ by (11) of Definition 2.12.


Fig. 2. Two NP/R nets.

The second part of the proof (validation of the other direction of the assertion) is similar to the first part and thus omitted here.

Example 2.17. The NP/R net (c) given in Fig. 2 is an exact simulation of a run of the $\mathrm{AC} / \mathrm{E}$ system in (a). Note that (c) was constructed using the algorithm given in Theorem 2.16. The NP/R net ( d ) of the same figure is an exact simulation of a run of the $\mathrm{AC} / \mathrm{E}$ system in (b). But (d) was not constructed in the way (c) was.

Corollary 2.18. Different $N P / R$ nets may be exact simulations of the same run of the same $A C / E$ system.

## 3. The partial derivation semantics of CCS

In the following we reproduce briefly the results about CCS semantics given by Degano et al. based on AC/E systems.
$\Delta=\{\alpha, \beta, \gamma, \ldots\}$ is called the action set of $\operatorname{CCS}, \bar{A}=\{\bar{\alpha}, \alpha \in \Delta\}$ its anti-action set. $\Lambda$ ctions of $\Delta \cup \bar{\Delta}$ are called visible ones; $\tau$ is the (only) invisible action, $\tau \notin \Delta \cup \bar{\Delta}$. The agents of CCS are defined with the following syntax:

$$
\begin{equation*}
e::=x|n i l| \alpha . e|e \backslash \alpha| e[s]\left|e_{1}+e_{2}\right| e_{1}\left|e_{2}\right|\langle x\rangle . e \tag{40}
\end{equation*}
$$

and the following derivation rules:

$$
\begin{align*}
& \alpha . e-\alpha \rightarrow e,  \tag{44a}\\
& e_{1}-\alpha \rightarrow e_{2} \text { implies } e_{1} \backslash \beta-\alpha-e_{2} \backslash \beta, \text { where } \beta \notin\{\alpha, \bar{\alpha}\},  \tag{41b}\\
& e_{1}-\alpha \rightarrow e_{2} \text { implies } e_{1}[s]-s(\alpha) \rightarrow e_{2}[s],  \tag{41c}\\
& e_{1}-\alpha \rightarrow e_{2} \text { implies } e_{1}+e-\alpha \rightarrow e_{2} \text { and } e+e_{1}-\alpha \rightarrow e_{2},  \tag{41d}\\
& e_{1}-\alpha \rightarrow e_{2} \text { implies } e_{1}\left|e-\alpha-e_{2}\right| e \text { and } e\left|e_{1}-\alpha-e\right| e_{2},  \tag{41e}\\
& e_{1}-\alpha \rightarrow e_{2} \text { and } e_{1}^{\prime}-\bar{\alpha} \rightarrow e_{2}^{\prime} \text { imply } e_{1}\left|e_{1}^{\prime}-\tau \rightarrow e_{2}\right| e_{2}^{\prime},  \tag{41f}\\
& e_{1}\left[\langle x\rangle . e_{1} / x\right]-\alpha \rightarrow e_{2} \text { implies }\langle x\rangle . e_{1}-\alpha \rightarrow e_{2} . \tag{41g}
\end{align*}
$$

The grapes are defined by Degano et al. [1] with the following syntax:

$$
\begin{equation*}
g::=\text { nil }|\alpha . e| e+e|\langle x\rangle . e| i d|e| e|i d| e \backslash \alpha \mid e[s] \tag{42}
\end{equation*}
$$

and the following decomposition rules:

$$
\begin{align*}
& \operatorname{dec}(n i l)=\{n i l\},  \tag{43a}\\
& \operatorname{dec}(\alpha \cdot e)=\{\alpha \cdot e\},  \tag{43b}\\
& \operatorname{dec}(e \backslash \alpha)=\operatorname{dec}(e) \backslash \alpha,  \tag{43c}\\
& \operatorname{dec}(e[s])=\operatorname{dec}(e)[s],  \tag{43d}\\
& \operatorname{dec}\left(e_{1}+e_{2}\right)=\left\{e_{1}+e_{2}\right\},  \tag{43e}\\
& \operatorname{dec}\left(e_{1} \mid e_{2}\right)=\operatorname{dec}\left(e_{1}\right)|i d \cup i d| \operatorname{dec}\left(e_{2}\right),  \tag{43f}\\
& \operatorname{dec}(\langle x\rangle . e)=\{\langle x\rangle . e\} . \tag{43~g}
\end{align*}
$$

The partial order semantics of CCS is defined by the following derivation rules for grapes:

$$
\begin{equation*}
\{\alpha . e\}-\alpha \rightarrow \operatorname{dec}(e), \tag{44a}
\end{equation*}
$$

$G_{1}-\alpha \rightarrow G_{2}$ implies $G_{1} \backslash \beta-\alpha \rightarrow G_{2} \backslash \beta, \quad \beta \notin\{\alpha, \bar{\alpha}\}$,
$G_{1}-\alpha \rightarrow G_{2}$ implies $G_{1}[s]-s(\alpha) \rightarrow G_{2}[s]$,
$\left(\operatorname{dec}\left(e_{1}\right)-G_{3}\right)-\alpha \rightarrow G_{2}$ implies

$$
\begin{equation*}
\left\{e_{1}+e\right\}-\alpha \rightarrow G_{2} \cup G_{3} \text { and }\left\{e+e_{1}\right\}-\alpha \rightarrow G_{2} \cup G_{3}, \tag{44d}
\end{equation*}
$$

$G_{1}-\alpha \rightarrow G_{2}$ implies $G_{1}\left|i d-\alpha \rightarrow G_{2}\right| i d$ and $i d\left|G_{1}-\alpha \rightarrow i d\right| G_{2}$,
$G_{1}-\alpha \rightarrow G_{2}$ and $G_{3}-\bar{\alpha} \rightarrow G_{4}$ imply

$$
\begin{equation*}
G_{1}|i d \cup i d| G_{3}-\tau \rightarrow G_{2}|i d \cup i d| G_{4}, \tag{44f}
\end{equation*}
$$

$\left(\operatorname{dec}\left(e_{1}\left[\langle x\rangle . e_{1} / x\right]-G_{3}\right)-\alpha \rightarrow G_{2}\right.$ implies $\left\{\langle x\rangle . e_{1}\right\}-\alpha \rightarrow G_{2} \cup G_{3}$,
where $G_{1}, G_{2}, G_{3}, G_{4}$ are sets of grapes. A set $G$ of grapes is called complete, if there exists an agent $e$ such that $\operatorname{dec}(e)=G$. It was proved [1] that the function dec defines an one-to-one correspondence between agents and complete sets of grapes. It was also proved that if $G-\alpha \rightarrow G_{2}$ is a derivation of grapes, then there must be a set $G_{3}$ of grapes, such that $G_{1} \cap G_{3}=\emptyset$ and $G_{1} \cup G_{3}$ is a complete set of grapes. Furthermore, we must have $G_{2} \cap G_{3}=\emptyset$ and $G_{2} \cup G_{3}$ is also a complete set of grapes.
The system $\Sigma_{\mathrm{CCS}}=(S, T, F, C)$ is defined as follows:

- $S=$ the set of all grapes,
- $T=$ the set of all derivations of grapes,
- $F=\left\{\left(g_{1}, G_{1}-\alpha \rightarrow G_{2}\right),\left(G_{1}-\alpha \rightarrow G_{2}, g_{2}\right) \mid g_{1} \in G_{1}, g_{2} \in G_{2}, G_{1}-\alpha \rightarrow G_{2} \in T\right\}$,
- $C=$ the set of all complete sets of grapes.

It was proved that $\Sigma_{\mathrm{cCs}}$ is an AC/E system.

## 4. A true concurrency semantics for CCS

In order to solve the problems which have not been solved in [1], we extend the syntax of CCS a little bit and then give its operational semantics in the form of derivation rules.

Definition 4.1. The CCS syntax is extended as follows:

$$
\begin{equation*}
e::=x \mid \text { nil }|\alpha . e| e \backslash \alpha(a)|e[s]| e_{1}+e_{2}\left|e_{1}\right| e_{2} \mid e_{1} \text { where } x=e_{2}, \tag{45}
\end{equation*}
$$

where $a$ is an arbitrary identifier.
Let $H_{i}, H_{i}^{\prime}, H_{i}^{\prime \prime}, i=0,1, \ldots$ be multisets (i.e. bags) with the elements of $\Delta \cup \bar{\Delta} \cup\{\tau\}$ as their elements. $V\left(H_{i}\right)$ is the multiset of all visible actions in $H_{i}$, whereas $\operatorname{inv}\left(H_{i}\right)$ is the multiset of all invisible actions ( $\tau$ ) of $H_{i}$. Then we have the following derivation rules

$$
\begin{equation*}
\alpha \cdot e-\{\alpha\} \rightarrow e, \tag{46a}
\end{equation*}
$$

$e_{1}-H_{0} \rightarrow e_{2}$ implies

$$
\begin{aligned}
& e_{1} \backslash \alpha(a)-H_{0} \rightarrow e_{2} \backslash \alpha(a), \quad \alpha \notin H_{0} \cup \bar{H}_{0} \\
& e_{1} \backslash \alpha(a)-\left(H_{0}-\{\alpha, \bar{\alpha}\}\right) \rightarrow e_{2} \backslash \alpha(a), \quad \text { for all } \alpha .
\end{aligned}
$$

where $H_{0}-\{\alpha, \bar{\alpha}\}$ means "delete all occurrences of $\alpha$ and $\bar{\alpha}$ from $H_{0} "$,

$$
\begin{align*}
& e_{1}-H_{0} \rightarrow e_{2} \text { implies } e_{1}[s]-s\left(H_{0}\right) \rightarrow e_{2}[s]  \tag{46c}\\
& e_{1}-H_{0} \rightarrow e_{2} \text { implies } e_{1}+e-H_{0} \rightarrow e_{2} \text { and } e+e_{1}-H_{0} \rightarrow e_{2},  \tag{46d}\\
& e_{1}-H_{0} \rightarrow e_{2} \text { implies } e_{1}\left|e-H_{0} \rightarrow e_{2}\right| e \text { and } e\left|e_{1}-H_{0} \rightarrow e\right| e_{2},
\end{align*}
$$

$$
\begin{align*}
& e_{1}-H_{1} \rightarrow e_{2} \text { and } e_{3}-H_{2} \rightarrow e_{4}, \quad \alpha \in\{\beta, \bar{\beta}\} \quad \text { imply } \\
& e_{1}\left|e_{3}-H_{4} \rightarrow e_{2}\right| e_{4} \text { and } e_{1} \backslash \alpha(a)\left|e_{3} \backslash \beta(a)-H_{4}^{\prime} \rightarrow e_{2} \backslash \alpha(a)\right| e_{4} \backslash \beta(a),  \tag{46f}\\
& e_{1}\left[\left(e_{2} \text { where } x=e_{2}\right) / x\right]-H_{0} \rightarrow e_{3} \text { where } x=e_{2} \\
& \text { implies }\left(e_{1} \text { where } x=e_{2}\right)-H_{0} \rightarrow e_{3} \text { where } x=e_{2} . \tag{46~g}
\end{align*}
$$

Here we have used the following notations:

$$
\begin{aligned}
& H_{4}=H_{1}^{\prime} \cup H_{2}^{\prime} \cup \operatorname{inv}\left(H_{1}\right) \cup \operatorname{inv}\left(H_{2}\right) \cup \operatorname{inv}\left(\left|H_{3}\right|\right), \\
& H_{4}^{\prime}=H_{1}^{\prime \prime} \cup H_{2}^{\prime \prime} \cup \operatorname{inv}\left(H_{1}\right) \cup \operatorname{inv}\left(H_{2}\right) \cup \operatorname{inv}\left(\left|H_{3}\right|\right), \\
& H_{1}^{\prime}=v\left(H_{1}\right)-H_{3}, \quad H_{2}^{\prime}=v\left(H_{2}\right)-\bar{H}_{3}, \\
& H_{1}^{\prime \prime}=H_{1}^{\prime}-\{\alpha, \bar{\alpha}\}, \quad H_{2}^{\prime \prime}=H_{2}^{\prime}-\{\alpha, \bar{\alpha}\}, \\
& H_{3} \subseteq v\left(H_{1}\right) \cap \overline{v\left(H_{2}\right),}
\end{aligned}
$$

where the intersection of two multisets is defined as the maximal sub-multiset which is contained in both multisets. $\left|H_{i}\right|$ is the number of elements contained in multiset $H_{i}$, $\operatorname{inv}\left(\left|H_{i}\right|\right)$ is the multiset of $\left|H_{i}\right| \tau$ 's. $\bar{H}_{i}=\left\{\bar{\alpha} \mid \alpha \in H_{i}\right\}$.

Note that this concurrency semantics of CCS is different from both Milner's and that of Degano et al. It will contain the Milner semantics as its proper subset by adding the following two rules.
(a) Let $e_{1}$ where $x=e_{1}$ be equal to $\langle x\rangle . e_{1}$ in the original syntax.
(b) Let the agents in which the identifiers " $a$ " in operations $\backslash \alpha(a)$ are all different from each other equal to those agents in the original syntax, which have the same form except for the identifiers which do not exist.

As to the derivation rules, note that the rules (46b)-(46e) and (46g) will be the same as those in Milner's semantics if $\left|H_{0}\right|=1$. The derivation (46f) will be the same as that in Milner's semantics if $\left|H_{1}\right|=\left|H_{2}\right|=1, v\left(H_{1}\right)=\overline{v\left(H_{2}\right)} \neq \emptyset$. Rule (46a) as it stands is also valid for Milner's semantics.

## Example 4.2. Let

$$
\begin{aligned}
& e_{1}=(\alpha . n i l \mid \beta . n i l) \mid((\bar{\alpha} . n i l \mid \bar{\gamma} . n i l) \mid(\omega . n i l \mid \varphi . n i l)), \\
& e_{2}=((\delta . n i l \mid \bar{\beta} . n i l) \mid(\gamma . n i l \mid \bar{\delta} . n i l)) \mid(\bar{\omega} . n i l \mid \psi . n i l) .
\end{aligned}
$$

It follows from (46f) that

$$
\begin{aligned}
& e_{1}-\{\tau, \beta, \bar{\gamma}\} \rightarrow(\text { nil } \mid \text { nil }) \mid((\text { nil } \mid \text { nil }) \mid(\omega . n i l \mid \varphi . n i l)), \\
& e_{2}-\{\tau, \bar{\beta}, \gamma\} \rightarrow((\text { nil } \mid n i l) \mid(\text { nil } \mid n i l) \mid(\omega . n i l \mid \psi . n i l)
\end{aligned}
$$

implies

$$
\begin{aligned}
e_{1} \mid e_{2}-\{\tau, \tau, \beta, \bar{\beta}, \tau\} \rightarrow & ((\text { nil } \mid \text { nil }) \mid((\text { nil } \mid \text { nil }) \mid(\omega . n i l \mid \varphi . n i l))) \\
& \mid(((\text { nil } \mid \text { nil }) \mid(\text { nil } \mid \text { nil })) \mid(\bar{\omega} . n i l \mid \psi . n i l))
\end{aligned}
$$

where

$$
\begin{aligned}
& I_{3}=\{\bar{\gamma}\} \subseteq(\{\beta, \bar{\gamma}\} \cap\{\beta, \bar{\gamma}\})=\{\beta, \bar{\gamma}\}, \\
& H_{1}^{\prime}=\{\beta\}, \quad H_{2}^{\prime}=\{\bar{\beta}\}, \\
& \operatorname{inv}\left(H_{1}\right)=\operatorname{inv}\left(H_{2}\right)=\operatorname{inv}\left(\left|H_{3}\right|\right)=\{\tau\}, \\
& H_{4}=\{\tau, \tau, \beta, \bar{\beta}, \tau\} .
\end{aligned}
$$

Definition 4.3. A relation $S B \subseteq E \times E$, where $E$ is the set of all agents, is called a bisimulation if the following conditions are fulfilled:
(a) if $\left(e_{1}, e_{2}\right) \in S B, e_{1}-H \rightarrow e_{1}^{\prime}$, then there exists $e_{2}^{\prime}$, such that $e_{2}-H \rightarrow e_{2}^{\prime}$, and $\left(e_{1}^{\prime}, e_{2}^{\prime}\right) \in S B$,
(b) $\left(e_{1}, e_{2}\right) \in S B \Leftrightarrow\left(e_{2}, e_{1}\right) \in S B$ where $H$ is a multiset of actions.

Theorem 4.4. For each agent $e$ there exists another agent $N(e)$ such that

$$
\begin{equation*}
N(e)=\sum_{i=1}^{m} \prod_{j=1}^{n_{i}} e_{i j} \quad \text { and } \quad(N(e), e) \in S B \tag{49}
\end{equation*}
$$

where

$$
\begin{aligned}
& \sum_{i=1}^{n} e_{i}=e_{1}+e_{2}+\cdots+e_{n}, \\
& \prod_{i=1}^{n} e_{i}=\left[e_{1}\left|e_{2}\right| e_{3}|\cdots| e_{n}\right]
\end{aligned}
$$

(the $n$-ary product $\prod_{i=1}^{n} e_{i}$ is appropriately composed of binary products ( $e^{\prime} \mid e^{\prime \prime}$ ) by using parentheses. Each $e_{i j}$ takes one of the following forms:

$$
\sum_{i=1}^{k} \alpha_{i} \cdot e_{i}^{\prime} \backslash A_{i} \text { where } x_{i}=e_{i}^{\prime \prime} \quad \text { or nil, }
$$

where each $\alpha_{i}$ is a (visible or invisible) action. $e_{i}^{\prime}$ and $e_{i}^{\prime \prime}$ take the form (49). $A_{i}$ is a set of actions with identifier parameters $\left\{\alpha_{1}\left(a_{1}\right), \ldots, \alpha_{l}\left(a_{l}\right)\right\}, \forall i \neq j, \alpha_{i} \neq \alpha_{j} . A_{i}$ may be empty. To avoid details, the naming action $e[s]$ is not considered here.

Proof. We use the following transformation rules to prove this theorem:

$$
\begin{align*}
& \left(e_{11}+e_{12}\right)\left|\left(e_{21}+e_{22}\right)=e_{11}\right| e_{21}+e_{11}\left|e_{22}+e_{12}\right| e_{21}+e_{12} \mid e_{22},  \tag{50a}\\
& \left(\sum_{i=1}^{n} e_{i}^{\prime}\right) \text { where } x=e^{\prime \prime}=\sum_{i=1}^{n}\left(e_{i}^{\prime} \text { where } x=e^{\prime \prime}\right), \tag{50b}
\end{align*}
$$

$$
\begin{align*}
& \left(\prod_{i=1}^{n} e_{i}^{\prime}\right) \text { where } x_{i}^{\prime}=e_{i}^{\prime \prime}=\prod_{i=1}^{n}\left(e_{i}^{\prime} \text { where } x_{i}^{\prime}=e_{i}^{\prime \prime}\right),  \tag{50c}\\
& e_{i}^{\prime} \text { where } x_{i}^{\prime}=e_{i}^{\prime \prime}=e_{i}^{\prime} \quad \text { where } e_{i}^{\prime} \text { does not contain } x_{i}^{\prime},  \tag{50d}\\
& \left(e_{i}^{\prime} \text { where } x_{i}^{\prime}=e_{i}^{\prime \prime}\right) \backslash A_{i}=\left(e_{i}^{\prime} \backslash A_{i}\right) \text { where } x_{i}^{\prime}=e_{i}^{\prime \prime},  \tag{50e}\\
& e_{i} \backslash A_{i} \backslash A_{i}^{\prime}-e_{i} \backslash\left(A_{i} \cup A_{i}^{\prime \prime}\right), \quad \text { wherc } \\
& \quad A_{i}^{\prime \prime}=\left\{\alpha(a) \mid \alpha(a) \in A_{i}^{\prime}, \sim \exists b \neq a, \text { such that } \alpha(b) \in A_{i} \text { or } \bar{\alpha}(b) \in A_{i}\right\},  \tag{50f}\\
& \left(\sum e_{i}\right) \backslash A=\sum\left(e_{i} \backslash A\right),  \tag{50~g}\\
& \left(\prod e_{i}\right) \backslash A=\prod\left(e_{i} \backslash\{\alpha(c) \mid \alpha(a) \in A\}\right) \tag{50h}
\end{align*}
$$

where $c$ is a completely new identifier.

$$
\begin{equation*}
n i l \backslash A=n i l . \tag{50i}
\end{equation*}
$$

To avoid going too far into the details, we assume here that each recursive agent has only one agent variable. Different recursive agents use different identifiers to denote their agent variables. We assume also that there is no nested recursive agent.

Using induction it is easy to prove that each agent can be transformed into the form (49) by using the transformation rules given above.

Now we will prove that each of these transformations keeps the bisimulation relation unchanged.

Transformation (50a). Let

$$
\begin{aligned}
& e=\left(e_{11}+e_{12}\right) \mid\left(e_{21}+e_{22}\right), \\
& f=e_{11}\left|e_{21}+e_{11}\right| e_{22}+e_{12}\left|e_{21}+e_{12}\right| e_{22} .
\end{aligned}
$$

Given a derivation $e-H \rightarrow e^{\prime}$, let (see Definition 4.1):

$$
\begin{array}{ll}
H=H_{1} \cup H_{2}, & H_{1}=H_{11} \cup H_{12}, \\
H_{2}=H_{3} \cup H_{4}, & H_{4}=H_{41} \cup H_{42} ; \\
e_{1}=e_{11}+e_{12}, & e_{2}=e_{21}+e_{22}
\end{array}
$$

where $H_{11}$ and $H_{12}$ are the sets of visible actions executed by $e_{1}$ and $e_{2}$, respectively. $H_{41}$ and $H_{42}$ are the sets of invisible actions executed by $e_{1}$ and $e_{2}$, respectively. $H_{3}$ is the set of invisible actions produced during the communication between $e_{1}$ and $e_{2}$. All the sets mentioned above are multisets.
W.l.o.g., assume that $H_{11}$ and $H_{12}$ are the sets of visible actions produced by $e_{11}$ and $e_{21}$ respectively. $H_{41}$ and $H_{42}$ are the sets of invisible actions produced by $e_{11}$ and $e_{21}$ respectivcly. $H_{3}$ is the set of invisible actions produced during the communication between $e_{11}$ and $e_{21}$. That means

$$
e_{11}\left|e_{21}-H \rightarrow e_{11}^{\prime}\right| e_{21}^{\prime \prime}\left(=e^{\prime}\right) .
$$

From (46d) follows the existence of derivation $f-H \rightarrow e^{\prime}$. On the other hand, if any derivation $f-H \rightarrow f^{\prime}$ is given, we can also prove the existence of the corresponding derivation $e-H \rightarrow f^{\prime}$ in the same way. That means $(e, f) \in S B$.

Transformation (50b). Let

$$
e=\left(\sum_{i=1}^{n} e_{i}^{\prime}\right) \text { where } x=e^{\prime \prime}, \quad f=\sum_{i=1}^{n}\left(e_{i}^{\prime} \text { where } x=e^{\prime \prime}\right) .
$$

## Consider a derivation

$$
\begin{equation*}
e-H \rightarrow e^{\prime} \text { where } x=e^{\prime \prime} \tag{51}
\end{equation*}
$$

It follows from $(46 \mathrm{~g})$, that derivation (51) can only occur when there is another derivation of the following form:

$$
\begin{equation*}
\left(\sum_{i=1}^{n} e_{i}^{\prime}\right)\left[\left(e^{\prime \prime} \text { where } x=e^{\prime \prime}\right) / x\right]-H \rightarrow e^{\prime} \text { where } x=e^{\prime \prime} . \tag{52}
\end{equation*}
$$

This can be rewritten as follows:

$$
\sum_{i=1}^{n} e_{i}^{\prime}\left[\left(e^{\prime \prime} \text { where } x=e^{\prime \prime}\right) / x\right]-H \rightarrow e^{\prime} \text { where } x=e^{\prime \prime}
$$

Therefore there exists a $j$, such that

$$
e_{j}^{\prime}\left[\left(e^{\prime \prime} \text { where } x=e^{\prime \prime}\right) / x\right]-H \rightarrow e^{\prime} \text { where } x=e^{\prime \prime}
$$

It follows again from (46g) that

$$
\left(e_{j}^{\prime} \text { where } x=e^{\prime \prime}\right)-H \rightarrow e^{\prime} \text { where } x=e^{\prime \prime}
$$

Thus we have

$$
\sum_{i=1}^{n}\left(e_{i}^{\prime} \text { where } x=e^{\prime \prime}\right)-H \rightarrow e^{\prime} \text { where } x=e^{\prime \prime} .
$$

On the other hand, each derivation $f-H \rightarrow f^{\prime}$ where $x=f^{\prime \prime}$ implies also the existence of a derivation $e-H \rightarrow f^{\prime}$ where $x=f^{\prime \prime}$. This means $(e, f) \in S B$.

Transformation (50c). The proof is similar to that of Transformation (50b).
Transformation (50d). Proof is obvious.
Transformation (50e). Proof is obvious.
Transformation (50f). Let

$$
\begin{align*}
& e=e_{1} \backslash A_{1} \backslash A_{2},  \tag{53}\\
& f=e_{1} \backslash A_{1} \cup A_{3} \tag{54}
\end{align*}
$$

where

$$
A_{3}=\left\{\alpha(a) \mid \alpha(a) \in A_{2}, \sim \exists b \neq a \text {, such that } \alpha(b) \in A_{1} \text { or } \bar{\alpha}(b) \in A_{1}\right\} .
$$

Consider the derivation

$$
\begin{equation*}
e-H \rightarrow e^{\prime} \backslash A_{1} \backslash A_{2} \tag{55}
\end{equation*}
$$

It follows from (46f) that the following derivation is valid:

$$
e_{1}-H \rightarrow e^{\prime}, \quad \forall \alpha(a) \in A_{1} \cup A_{2}, \alpha \notin H \cup \bar{H} .
$$

Since $\left(A_{1} \cup A_{3}\right) \subseteq\left(A_{1} \cup A_{2}\right)$ we know that $\forall \alpha(a) \in A_{1} \cup A_{3}, \alpha \notin H \cup \bar{H}$. Thus the validity of the following derivation is assured by (46f):

$$
\begin{equation*}
f-H \rightarrow e^{\prime} \backslash\left(A_{1} \cup A_{3}\right) \tag{56}
\end{equation*}
$$

Note that the forms of (55) and (56) are similar to those of (53) and (54), respectively. Therefore we can repeat the reasoning described above and prove that for all $n$,

$$
e^{(n)}-H \rightarrow e_{1}^{(n)} \backslash A_{1} \backslash A_{2}
$$

implies

$$
f^{(n)}-H \rightarrow e_{1}^{(n)} \backslash\left(A_{1} \cup A_{3}\right)
$$

where $e^{(n)}, f^{(n)}, e_{1}^{(n)}$ are the $n$th derivations of $e, f$ and $e_{1}$ respectively.
On the other hand, any

$$
f^{(n)}-H \rightarrow e_{1}^{(n)} \backslash\left(A_{1} \cup A_{3}\right)
$$

implies

$$
e^{(n)}-H \rightarrow e_{1}^{(n)} \backslash A_{1} \backslash A_{2}
$$

because $\left\{\alpha \mid \exists a, \alpha(a) \in A_{2}\right.$ or $\left.\bar{\alpha}(a) \in A_{2}\right\}=\left\{\alpha \mid \exists a, \alpha(a) \in A_{3}\right.$ or $\left.\bar{\alpha}(a) \in A_{3}\right\}$. Hence $(e, f) \in S B$.

Transformation ( 50 g ). Proof is obvious.
Transformation (50h). To shorten the proof, we consider only the cases of binary products and $|A|=1$. Let

$$
\begin{align*}
& e=\left(e_{1} \mid e_{3}\right) \backslash \alpha(a),  \tag{57}\\
& f=\left(e_{1} \backslash \alpha(c)\right) \mid\left(e_{3} \backslash \alpha(c)\right) \tag{58}
\end{align*}
$$

where $c$ is a new identifier. Assume

$$
\begin{equation*}
e-H_{4} \rightarrow e^{\prime} \backslash \alpha(a) \tag{59}
\end{equation*}
$$

then the following must hold:

$$
e_{1} \mid e_{3}-H_{4} \rightarrow e^{\prime}, \quad \alpha \notin H_{4} \cup \bar{H}_{4} .
$$

This is only possible when

$$
e_{1}-H_{1} \rightarrow e_{2}, \quad e_{3}-H_{2} \rightarrow e_{4}, \quad e_{2} \mid e_{4}=e^{\prime}
$$

It then follows that

$$
\left(e_{1} \backslash \alpha(a)\right)\left|\left(e_{3} \backslash \alpha(a)\right)-H_{4}^{\prime} \rightarrow\left(e_{2} \backslash \alpha(a)\right)\right|\left(e_{4} \backslash \alpha(a)\right)
$$

For the meaning of $H_{1}, H_{2}, H_{4}$ see (46f). Note that the only difference between $H_{4}$ and $H_{4}^{\prime}$ is that $H_{4}$ may have $\alpha$ or $\bar{\alpha}$ which do not exist in $H_{4}^{\prime}$. But in our case we have $\alpha \notin H_{4} \cup \bar{H}_{4}$, therefore the derivation above can be rewritten as follows:

$$
\left(e_{1} \backslash \alpha(a)\right)\left|\left(e_{3} \backslash \alpha(a)\right)-H_{4} \rightarrow\left(e_{2} \backslash \alpha(a)\right)\right|\left(e_{4} \backslash \alpha(a)\right)
$$

This is valid and does not depend on the choice of a. Therefore we have

$$
\begin{equation*}
f-H_{4} \rightarrow f^{\prime}, \quad f^{\prime}=\left(e_{2} \backslash \alpha(c)\right) \mid\left(e_{4} \backslash \alpha(c)\right) \tag{60}
\end{equation*}
$$

By comparing (57), (58) with (59), (60) we know that the same way of reasoning can be applied to $e^{\prime}$ and $f^{\prime}$, and $e^{(n)}, f^{(n)}$ for arbitrary $n$. On the other hand, if

$$
f-H_{4}^{\prime} \rightarrow f^{\prime} \quad\left(=\left(e_{2} \backslash \alpha(c)\right) \mid\left(e_{4} \backslash \alpha(c)\right)\right)
$$

is given, then it follows from (46f) that

$$
e_{1}-H_{1} \rightarrow e_{2}, \quad e_{3}-H_{2} \rightarrow e_{4}, \quad e_{1}\left|e_{3}-H_{4} \rightarrow e_{2}\right| e_{4}
$$

This implies:

$$
\begin{aligned}
& \left(e_{1} \mid e_{3}\right) \backslash \alpha(a)-\left(H_{4}-\{\alpha, \bar{\alpha}\}\right) \rightarrow\left(e_{2} \mid e_{4}\right) \backslash \alpha(a), \\
& \left(e_{1} \mid e_{3}\right) \backslash \alpha(a)-H_{4}^{\prime} \rightarrow\left(e_{2} \mid e_{4}\right) \backslash \alpha(a) .
\end{aligned}
$$

This way of reasoning can be applied to any $e^{(n)}$ and $f^{(n)}$ for arbitrary $n$, thus $(e, f) \in S B$.

Discussion. The key point of transforming any agent $e$ into $N(e)$ (sometimes we call it the normal form of $e$, although $N(e)$ is not uniquely determined by $e$ ) is not to lose the global information of the agent, especially for recursive agents " $e$ where $x=e$ " and masked agents " $e \backslash A$ ". See (b), (c) and (h) of the following example.

## Example 4.5.

(a) $\quad\left(e_{1}\left|e_{2}+e_{3}\right| e_{4}\right)\left|\left(e_{5}\left|e_{6}+e_{7}\right| e_{8}\right)=\left(e_{1} \mid e_{2}\right)\right|\left(e_{5} \mid e_{6}\right)+\left(e_{1} \mid e_{2}\right) \mid\left(e_{7} \mid e_{8}\right)$

$$
+\left(e_{3} \mid e_{4}\right) \mid\left(e_{5} \mid e_{6}\right)+\left(e_{3} \mid e_{4}\right)\left(e_{7} \mid e_{8}\right)
$$

(b) $\quad(\alpha \cdot x+\beta \cdot x$ where $x=\alpha \cdot x+\beta \cdot x)=(\alpha \cdot x$ where $x=\alpha \cdot x+\beta \cdot x)$

$$
+(\beta \cdot x \text { where } x=\alpha \cdot x+\beta \cdot x)
$$

(c) $\quad(\alpha \cdot x \mid \beta \cdot x$ where $x=\alpha \cdot x+\beta \cdot x)$

$$
=(\alpha \cdot x \text { where } x=\alpha \cdot x+\beta \cdot x) \mid(\beta \cdot x \text { where } x=\alpha \cdot x+\beta \cdot x)
$$

(d) ( $\alpha . \beta$.nil where $x=\gamma, x)=\alpha . \beta$ nil
(e) $\quad(\alpha . x$ where $x=\beta . x) \backslash\{\beta(a)\}=(\alpha \cdot x \backslash \beta(a))$ where $x=\beta \cdot x$
(f) $\quad e \backslash\{\alpha(a), \beta(a)\} \backslash\{\alpha(b), \gamma(b)\}=e \backslash\{\alpha(a), \beta(a), \gamma(b)\}$
(g) $\quad(\alpha . n i l+\beta . n i l) \backslash\{\alpha(b)\}=\alpha . n i l \backslash\{\alpha(b)\}+\beta . n i l \backslash\{\alpha(b)\}$
(h) $\quad((\alpha . n i l \mid \bar{\alpha} . n i l) \backslash\{\alpha(b)\} \mid \alpha . n i l) \backslash\{\alpha(a)\}$

$$
=(\alpha . n i l \backslash\{\alpha(c)\})|(\bar{\alpha} . n i l \backslash\{\alpha(c)\})|(\alpha . n i l \backslash\{\alpha(a)\})
$$

Definition 4.6. All agents in normal form (or their grapes) can be decomposed into sets of grapes (or their sub-grapes) in the following way:

$$
\begin{align*}
& \operatorname{dec}(n i l)=\{n i l\},  \tag{61a}\\
& \operatorname{dec}(\alpha . e)=\{\alpha . e\},  \tag{61b}\\
& \operatorname{dec}(e \backslash \alpha(a))=\operatorname{dec}(e) \backslash \alpha(a),  \tag{61c}\\
& \operatorname{dec}(e[s])=\operatorname{dec}(e)[s],  \tag{61d}\\
& \operatorname{dec}\left(\sum e_{i}\right)=\sum \operatorname{dec}\left(e_{i}\right),  \tag{61e}\\
& \operatorname{dec}\left(\prod_{i=1}^{n} e_{i}\right)=\left\{\prod_{i=1}^{j} i d\left|\operatorname{dec}\left(e_{j+1}\right)\right| \prod_{i=j+2}^{n} i d \mid j=0, \ldots, n-1\right\},  \tag{61f}\\
& \operatorname{dec}\left(\prod_{i=l}^{m} i d|e| \prod_{j=k}^{m} i d\right)=\left\{\prod_{i=1}^{m} i d|\operatorname{dec}(e)| \prod_{j=k}^{m} i d\right\}, \tag{61~g}
\end{align*}
$$

where the products of $i d$ do not exist if $l>m$ or $k>m$ (but always $\min (l, k) \leqslant m$ ).

$$
\begin{equation*}
\operatorname{dec}\left(e_{1} \text { where } x=e_{2}\right)=\left\{\operatorname{dec}\left(e_{1}\right) \text { where } x=e_{2}\right\} \text {. } \tag{61h}
\end{equation*}
$$

Note that $e, e_{1}$ and $e_{2}$ can be any agents. In rule ( 61 h ), $e_{1}$ can be an agent or a grape. Here we allow the operands of the sum operator " + " and the product operator "|" to be sets of grapes, i.e.

$$
\sum_{i=1}^{n} G_{i}=\left\{\sum_{i=1}^{n} g_{i} \mid g_{i} \in G_{i}\right\} \quad \text { and } \quad \prod_{i=1}^{n} G_{i}=\left\{\prod_{i=1}^{n} g_{i} \mid g_{i} \in G_{i}\right\} .
$$

Remember that each product of agents and/or grapes must be combined into binary products appropriately. Further we define:
$\{G$ where $x=e\}=\{g$ where $x=e \mid g \in G\}$.
Definition 4.7. The concurrent derivation rules of grapes are the following:

$$
\begin{align*}
& \{\alpha . e\}-\alpha \rightarrow \operatorname{dec}(e),  \tag{62a}\\
& G_{1}-\alpha \rightarrow G_{2} \text { implies } G_{1} \backslash \beta(a)-\alpha \rightarrow G_{2} \backslash \beta(a), \quad \beta \notin\{\alpha, \bar{\alpha}\},  \tag{62b}\\
& G_{1}-\alpha \rightarrow G_{2} \text { implies } G_{1}[s]-s(\alpha) \rightarrow G_{2}[s]  \tag{62c}\\
& \left(\operatorname{dec}\left(e_{1}\right)-G_{1}\right)-\alpha \rightarrow G_{2} \text { implies }\left(\operatorname{dec}\left(e_{1}\right)-G_{1}\right)+\operatorname{dec}\left(e_{2}\right)-\alpha \rightarrow G_{2} \text { and } \\
& \qquad \operatorname{dec}\left(e_{2}\right)+\left(\operatorname{dec}\left(e_{1}\right)-G_{1}\right)-\alpha \rightarrow G_{2}, \tag{62d}
\end{align*}
$$

$$
\begin{gather*}
G_{1}-\alpha \rightarrow G_{2} \text { implies } G_{1}\left|i d-\alpha \rightarrow G_{2}\right| i d \text { and } \\
i d\left|G_{1}-\alpha \rightarrow i d\right| G_{2}, \tag{62e}
\end{gather*}
$$

$G_{1}-\alpha \rightarrow G_{2}$ and $G_{3}-\bar{\alpha} \rightarrow G_{4}$ imply
$G_{1}|i d \cup i d| G_{3}-\tau \rightarrow G_{2}|i d \cup i d| G_{4}$
$G_{1} \backslash \alpha(a)|i d \cup i d| G_{3} \backslash \beta(a)-\tau$
$\rightarrow G_{2} \backslash \alpha(a)|i d \cup i d| G_{4} \backslash \beta(a), \quad \alpha \in\{\beta, \bar{\beta}\}$,
$G_{1}-\alpha \rightarrow G_{2}$ implies
$G_{1}$ where $x=e-\alpha \rightarrow \operatorname{dec}\left(G_{2}[e / x]\right)$ where $x=e$,
provided that $G_{1}$ does not contain something like "where $x=e_{1}$ ".

## Example 4.8.

$$
\begin{aligned}
\operatorname{dec}\left(e_{1}\left|e_{2}+e_{3}\right| e_{4}\right) & =\operatorname{dec}\left(e_{1} \mid e_{2}\right)+\operatorname{dec}\left(e_{3} \mid e_{4}\right) \\
& =\left\{e_{1}|i d, i d| e_{2}\right\}+\left\{e_{3}|i d, i d| e_{4}\right\} \\
& =\left\{e_{1}\left|i d+e_{3}\right| i d, e_{1}|i d++i d| e_{4}, i d\left|e_{2}+e_{3}\right| i d, i d\left|e_{2}+i d\right| e_{4}\right\}
\end{aligned}
$$

provided that $\forall i, \operatorname{dec}\left(e_{i}\right)=e_{i}$.

## Example 4.9.

$$
\begin{aligned}
\operatorname{dec}( & (\alpha \cdot x|\beta \cdot x+\gamma \cdot x| \delta \cdot x) \text { where } x=\alpha \cdot x|\beta \cdot x+\gamma \cdot x| \delta \cdot x \\
= & \operatorname{dec}(\alpha \cdot x|\beta \cdot x+\gamma \cdot x| \delta \cdot x) \text { where } x=\alpha \cdot x|\beta \cdot x+\gamma \cdot x| \delta \cdot x \\
= & \{\alpha \cdot x|i d+\gamma \cdot x| i d, \alpha \cdot x|i d+i d| \delta \cdot x, i d|\beta \cdot x+\gamma \cdot x| i d, \\
& i d|\beta \cdot x+i d| \delta \cdot x\} \text { where } x=\alpha \cdot x|\beta \cdot x+\gamma \cdot x| \delta \cdot x \\
= & \{\alpha \cdot x|i d+\gamma \cdot x| i d \text { where } x=\alpha \cdot x|\beta \cdot x+\gamma \cdot x| \delta \cdot x, \\
& \alpha \cdot x|i d+i d| \delta \cdot x \text { where } x=\alpha \cdot x|\beta \cdot x+\gamma \cdot x| \delta \cdot x, \\
& i d|\beta \cdot x+\gamma \cdot x| i d \text { where } x=\alpha \cdot x|\beta \cdot x+\gamma \cdot x| \delta \cdot x, \\
& i d|\beta \cdot x+i d| \delta \cdot x \text { where } x=\alpha \cdot x|\beta \cdot x+\gamma \cdot x| \delta \cdot x\} .
\end{aligned}
$$

Example 4.10. It follows from rules (62d), (62e) and Example 4.8 that $e_{1}-\alpha \rightarrow e_{1}^{\prime}$ implies

$$
\left\{e_{1}\left|i d+e_{3}\right| i d, e_{1}|i d+i d| e_{4}\right\}-\alpha \rightarrow e_{1}^{\prime} \mid i d .
$$

Example 4.11. It follows from rules (62d), (62e), (62g) and Example 4.9 that:

$$
\begin{aligned}
& \{\alpha \cdot x|i d+\gamma \cdot x| i d \text { where } x=\alpha \cdot x|\beta \cdot x+\gamma \cdot x| \delta \cdot x, \\
& \quad \alpha \cdot x|i d+i d| \delta \cdot x \text { where } x=\alpha \cdot x|\beta \cdot x+\gamma \cdot x| \delta \cdot x\}-\alpha \\
& \quad \rightarrow \operatorname{dec}(\alpha \cdot x|\beta \cdot x+\gamma \cdot x| \delta \cdot x) \mid i d \text { where } x=\alpha \cdot x|\beta \cdot x+\gamma \cdot x| \delta \cdot x .
\end{aligned}
$$

The representation of a CCS agent by an $\mathrm{AC} / \mathrm{E}$ system is not perfect. In fact, the information contained in it is not complete, there is no initial case (marking) in an $\mathrm{AC} / \mathrm{E}$ system. In the following we give a more exact way of representing an agent.

Definition 4.12. If $\Sigma=(S, T, F, C)$ is an $\mathrm{AC} / E$ system, then $\Sigma_{1}=(S, T, F, C, M)$ is called an $A C / E N$ system, where $M \in C$ is called the initial marking of $\Sigma_{1}$. The firing rules of $\mathrm{AC} / \mathrm{EN}$ systems are the same as those of $\mathrm{AC} / \mathrm{E}$ systems.

Definition 4.13. An AC/EN system ( $S, T, F, C, M$ ) is called reachable, if any case of $C$ is reachable by foward firing, starting from the initial marking.

Definition 4.14. A set $G$ of grapes is called a direct unfolding of an agent $e$, if $G=\operatorname{dec}(e)$. $G$ is called a unfolding of $e$ if

- $G$ is a direct unfolding of $e$, or
- there exists a unfolding $G^{\prime}$ of $e$ and a derivation:

$$
\left(G^{\prime}-G^{\prime \prime}\right)-\alpha \rightarrow\left(G-G^{\prime \prime}\right)
$$

where $G^{\prime \prime}$ is a set of grapes, $\alpha$ is an action of CCS.
A grape $g$ is called a direct descendent of an agent $e$, if $g$ is an element of dec(e). $g$ is called a descendent of $e$, if $g$ is an element of some unfolding of $e$.

Definition 4.15. The net-representation of an agent $e$ is an $\mathrm{AC} / \mathrm{EN}$ system $\Sigma(e)=$ ( $S, T, F, C, M$ ), constructed as follows:

$$
\begin{align*}
& M=\operatorname{dec}(e),  \tag{63a}\\
& C=\{a \mid a \text { is an unfolding of } e\},  \tag{63b}\\
& S=\{b \mid b \text { is a descendent of } e\},  \tag{63c}\\
& T=\left\{\left(G^{\prime}-G^{\prime \prime}\right)-H \rightarrow\left(G-G^{\prime \prime}\right) \mid G^{\prime} \text { and } G \text { are both unfoldings of } e\right\},  \tag{63d}\\
& F=\left\{(x, y) \mid x \in\left(G^{\prime}-G^{\prime \prime}\right)\right\} \cup\left\{(y, z) \mid z \in\left(G-G^{\prime \prime}\right)\right\}, \tag{63e}
\end{align*}
$$

where $y \in T$, and $y$ takes the form $\left(G^{\prime}-G^{\prime \prime}\right)-H \rightarrow\left(G-G^{\prime \prime}\right)$.
It is easy to prove the following theorem.
Theorem 4.16. $\Sigma(e)=(S, T, F, C, M)$ as it is constructed in Definition 4.15 is really an AC/EN system.

Example 4.17. Reconsider Example 4.8 with $e_{1}=\alpha$.nil, $e_{2}=\beta$ nil, $e_{3}=\gamma$ nil, $e_{4}=\delta$.nil. Let $a, b, c, d$ denote the four grapes in $\operatorname{dec}\left(e_{1}\left|e_{2}+e_{3}\right| e_{4}\right)$ in the order as it was given there. Then $\Sigma(e)$ is shown in Fig. 3, where the simplified notations $\alpha, \beta, \gamma, \delta$ denote the four events $\{a, b\}-\alpha \rightarrow\{$ nil $\mid i d\}$, etc.


Fig. 3.

Example 4.18. Fig. 3 can also be understood as the net-representation of the agent $e$ in Example 4.9, if we give a new explanation to it. Namely, let $e=\alpha \cdot x|\beta \cdot x+\gamma \cdot x| \delta . x$. Let $a, b, c, d$ denote the four grapes of dec(e). Let $\alpha, \beta, \gamma, \delta$ denote the four grape derivations (one of which was shown in Example 4.11). Rename the elements nillid and $i d \mid n i l$ in Fig. 3 as $e \mid i d$ where $x=e$ and $i d \mid e$ where $x=e$. Then Fig. 3 contains all possible unfoldings of Example 4.9 for the "first step".

## 5. Bisimulation and semantical equivalence

Definition 5.1. Let $R$ and $R^{\prime}$ be NP/R nets. Their occurrence net representations (see Definition 2.6(a)) are:

$$
K=(S, T, F), \quad K^{\prime}=\left(S^{\prime}, T^{\prime}, F^{\prime}\right)
$$

We say that $R$ is $t$-isomorphic to $R^{\prime}$, if there is a mapping

$$
\Phi: T \rightarrow T^{\prime}
$$

such that
$\Phi$ is a bi-unique mapping,

$$
\begin{align*}
& \Phi(a[i])=b[j] \rightarrow \forall a[k], \exists m, \Phi(a[k])=b[m],  \tag{64b}\\
& a[i] \prec b[j] \leftrightarrow \Phi(a[i]) \prec \Phi(b[j]) .
\end{align*}
$$

Condition (64b) guarantees that if two elements $x, y$ of a NP/R net $R$ correspond to the same element of the underlying AC/EN system, and if $R$ is $t$-isomorphic to $R^{\prime}$, then the mappings $x^{\prime}, y^{\prime}$ of $x, y$ in $R^{\prime}$ correspond also to the same event of its underlying $\mathrm{AC} / \mathrm{EN}$ system. Condition ( 64 c ) keeps the partial order unchanged.

Definition 5.2. Let $e_{1}$ and $e_{2}$ be two agents. $R_{1}$ and $R_{2}$ are NP/R nets over $\Sigma\left(e_{1}\right)$ and $\Sigma\left(e_{2}\right)$, respectively. We say that $R_{1}$ is b-isomorphic to $R_{2}$, if we change (64b) as follows:
$\Phi$ maps the event $G_{1}-\alpha \rightarrow G_{2}$ of $R_{1}$ to an event $G_{3}-\alpha \rightarrow G_{4}$ of $R_{2}$.

Definition 5.3. Let $R=\left\{R[i]=\left(S_{i}, T_{i}, F_{i}\right) \mid i-1,2, \ldots\right\}$ be a NP/R net, then

$$
\begin{equation*}
R[i] \oplus n=(S, T, F) \tag{65}
\end{equation*}
$$

where

$$
\begin{aligned}
& S=\left\{x[i+n] \mid x[i] \in S_{i}\right\}, \quad T=\left\{x[i+n] \mid x[i] \in T_{i}\right\}, \\
& F=\left\{(x[i+n], y[j+n]) \mid(x[i], y[j]) \in F_{i}\right\}, \\
& R \oplus n=\{R[i] \oplus n \mid i=1,2, \ldots\} .
\end{aligned}
$$

Definition 5.4. Let $R=\{R[i] \mid i=1,2, \ldots, n\}$ and $R^{\prime}=\left\{R^{\prime}[i] \mid i=1,2,3, \ldots\right\}$ be two NP/R nets over the same AC/EN system $\Sigma$. We define the concatenation $R^{\prime \prime}$ of $R$ and $R^{\prime}$ as follows.

Let

$$
\begin{array}{ll}
\forall i \leqslant n, & R^{\prime \prime}[i]=R[i], \\
\forall i>n, & R^{\prime \prime}[i]=R^{\prime}[i-n] \oplus n . \tag{66}
\end{array}
$$

Modify $R^{\prime \prime}$ as follows. If

$$
K=(S, T, F), \quad K^{\prime}=\left(S^{\prime}, T^{\prime}, F^{\prime}\right)
$$

are the occurrence net representations of $R$ and $R^{\prime}$ (see Definition 2.6), respectively, then the following is true: Whenever there is $a[i] \in S, \mathrm{a}[j] \in S^{\prime}$, and there is no $k>i$ such that $a[k] \in S$, and there is no $m<j$, such that $a[m] \in S^{\prime}$, we can always (but not necessarily) delete $a[j+n]$ from $R^{\prime \prime}$, and replace the set $\{(a[j+n], y)\}$ by the set $\{(a[i], y)\}$.
$R^{\prime \prime}$, as modified above, is also a NP/R net over $\Sigma$. It is called the concatenation of $R$ and $R^{\prime}$. We call $R$ a predecessor of $R^{\prime}$, and $R^{\prime}$ a successor of $R$.

Definition 5.5. Let $R$ be a NP/R net. Denote the set of all predecessors of $R$ with $\operatorname{PRED}(R)$, and the set of all successors of $R$ with $\operatorname{SUC}(R)$. Note that either of these may be empty, and $\operatorname{SUC}(R)$ is only defined when $R$ is finite.

Let $P R S_{1}$ and $P R S_{2}$ be the sets of all NP/R nets over the two AC/EN systems $\Sigma_{1}$ and $\Sigma_{2}$, respectively. The relation

$$
B S \subseteq 2^{P R S_{1}} \times 2^{P R S_{2}}
$$

is called the $b$-equivalent relation, or bisimulation, if
(a) for $\left(P R_{1}, P R_{2}\right) \in B S$ the following holds

- $\forall R_{1} \in P R_{1}, R_{1}$ has finitely many pages,
- $\exists R_{2} \in P R_{2}, R_{2}$ has finitely many pages,
- $R_{1}$ is b-isomorphic to $R_{2}$, and
- $\left(\operatorname{SUC}\left(R_{1}\right), \operatorname{SUC}\left(R_{2}\right)\right) \in B S$; and
(b) $\left(P R_{1}, P R_{2}\right) \in B S$ implies $\left(P R_{2}, P R_{1}\right) \in B S$.

Definition 5.6. Iet $\Sigma$ he an AC/FN system with $M$ as its initial marking. The proper set of NP/R nets of $\Sigma$ consists of all those NP/R nets which are exact simulations of some runs starting from $M$.

Theorem 5.7. Let $e_{1}$ and $e_{2}$ be two CCS agents in normal form. Let $\Sigma\left(e_{1}\right)$ and $\Sigma\left(e_{2}\right)$ be the corresponding $A C / E N$ systems. Then $\left(e_{1}, e_{2}\right) \in S B$ if and only if $\left(P R_{1}, P R_{2}\right) \in B S$, where $P R_{1}$ and $P R_{2}$ are the proper sets of $N P / R$ nets of $\Sigma\left(e_{1}\right)$ and $\Sigma\left(e_{2}\right)$.

In order to prove this, we need the following lemma.
Lemma 5.8. Let e be an agent in normal form, $\Sigma(e)$ the corresponding $A C / E N$ system ( $S, T, F, C, M$ ). Then there is a one-to-one correspondence between the derivation sequences of $e$ :

$$
e_{i}-H_{i} \rightarrow e_{i+1}, \quad 1 \leqslant i \leqslant n, e=e_{1}
$$

and the firing sequences of $\Sigma(e)$ :

$$
M_{i}\left[B_{i}>M_{i+1}, \quad 1 \leqslant i \leqslant n, M=M_{1}\right.
$$

where $B_{i}$ is the step transforming $M_{i}$ into $M_{i+1}$.
Proof. First, we prove the one-to-one correspondence between the derivations of $e$ (one step derivation) and the firings of $\Sigma(e)$ (one step run). Let

$$
e=\sum_{i=1}^{n} \prod_{j=1}^{n_{i}} e_{i j}
$$

where each $e_{i j}$ takes one of the following two forms:

$$
\sum_{k=1}^{p} \alpha_{k} \cdot e_{k}^{\prime} \backslash A_{k} \text { where } x_{k}=e_{k}^{\prime \prime} \quad \text { or } \quad \text { nil. }
$$

Case 1. $n=1$, i.e.

$$
e=\prod_{j=1}^{n_{1}} e_{i j}
$$

Let $n_{1}=m$, we differentiate two subcases.
Case 1.1. $m=1$, i.e.

$$
e=\sum_{k=1}^{p} \alpha_{k} \cdot e_{k} \backslash A_{k} \text { where } x_{k}=e_{k}^{\prime \prime} .
$$

There is no need to consider the case where $e=$ nil, because in that case there will be no action at all.

Clearly, $\operatorname{dec}(e)=e$. From (61a) and (61d) in Definition 4.6 we know that the event of $\Sigma(e)$, which takes part in its first firing, must be one of the following:

$$
e-\alpha_{k} \rightarrow \operatorname{dec}\left(e_{k}\left[e_{k}^{\prime \prime} / x_{k}\right]\right) \text { where } x_{k}=e_{k}^{\prime \prime} \backslash A_{k} \quad \text { and } \alpha_{k} \notin A_{k}
$$

This shows its one-to-one correspondence to the derivations of $e$.
Case 1.2. $m>1$. Let

$$
e=\prod_{j-1}^{m} e_{j}-H \rightarrow e^{\prime},
$$

then each $e_{j}$ can take part in this derivation in one of the following three ways:

- $e_{j}$ produces no action at all,
- $e_{j}$ produces an action $\alpha \in H$,
- $e_{j}$ communicates with another $e_{k}$ and produces an action $\tau \in H$.

Now consider $\Sigma(e)$. Let

$$
\operatorname{dec}(e)=\left\{g_{k} \mid k=1, \ldots, m\right\}, \quad g_{k}=\prod_{j=1}^{k-1} i d\left|e_{k}\right| \prod_{j=k+1}^{m} i d .
$$

It follows from (62e) and (62f) in Definition 4.7, that each $g_{k}$ can take part in the firing of $\Sigma(e)$ in one of the following three ways:

- $g_{k}$ is not a condition of any firing event;
- for some $\alpha, g_{k}-\alpha \rightarrow g_{k}^{\prime}$ fires independently (we call it simply $\alpha^{k}$ );
- $g_{k}$ and some $g_{h}, h \neq k$, are both condition elements of the following firing event:

$$
\left\{g_{k}, g_{h}\right\}-\tau \rightarrow\left\{g_{k}^{\prime}, g_{h}^{\prime}\right\}
$$

(we call it simply $\tau^{k h}$ ).
These $g_{k}$ 's are different from each other. That means that in case $j \neq k, j \neq l, h \neq k$, $h \neq l$, the events $\alpha^{k}$ and $\alpha^{j}$ of $\Sigma(e)$ have no common condition elements. The same conclusion is true for $\alpha^{k}$ and $\tau^{j h}$, or $\tau^{j h}$ and $\tau^{k l}$.

It follows from ( 62 c ) and (62f) that

$$
g_{k}^{\prime}=\prod_{j=1}^{k-1} i d\left|e_{k}^{\prime}\right| \prod_{j=k+1}^{m} i d .
$$

Therefore, we have

$$
\forall h \neq k, \forall x \in g_{k}^{\prime}, y \in g_{h}^{\prime}, x \neq y
$$

because the numbers of id on the left and right sides of $e_{k}^{\prime}$ and $e_{h}^{\prime}$ are different.

Note that both $g_{k}$ and $g_{k}^{\prime}$ are combined appropriately into binary products using parentheses. This means that the events $\alpha^{k}, \tau^{h l}$, etc. can fire concurrently in the sense of Definition 2.2. Thus we have shown the one-to-one correspondence between the event firings of $\Sigma(e)$ and the derivation of $e$.

Case 2. $n>1$.
Case 2.1. $\forall i, n_{i}=1$. This case is equivalent to Case 1.1.
Case 2.2. $\exists i, n_{i}>1$. Let

$$
e=\sum_{i=1}^{n} e_{i}, \quad e_{i}=\prod_{j=1}^{n_{i}} e_{i j}
$$

Then any action of $e$ must be produced by some $e_{i}$. W.l.o.g. assume $n_{i}>1$. Let us recall Case 1.2. Let

$$
G_{i j}=\sum_{h=1}^{i-1} \operatorname{dec}\left(e_{h}\right)+\left\{g_{i j}\right\}+\sum_{h=i+1}^{n} \operatorname{dec}\left(e_{h}\right)
$$

where $g_{i j} \in \operatorname{dec}\left(e_{i}\right)$ :

$$
g_{i j}=\prod_{k=1}^{j-1} i d\left|e_{i j}\right| \prod_{k=j+1}^{n_{i}} i d .
$$

Note that $\operatorname{dec}\left(e_{i j}\right)=e_{i j}$ because $e$ is in normal form. $G_{i j}$ is the pre-condition of the event $G_{i j}-\alpha_{i j} \rightarrow G_{i j}^{\prime}\left(=g_{i j}^{\prime}\right)$ or part of the pre-condition of the event $\left\{G_{i j}, G_{i k}\right\}-\tau \rightarrow\left\{G_{i j}^{\prime}, G_{i k}^{\prime}\right\}$ in $\Sigma(e)$, where $\alpha_{i j}$ is the action produced by $e_{i j}$, and $\tau$ is the action produced by $e_{i j}$ and $e_{i k}$.
(i) $\forall j \neq k, g_{i j} \neq g_{i k}$. That means

$$
\forall i, \forall j \neq k, \quad G_{i j} \cap G_{i k}=\emptyset
$$

This shows that the events $\alpha^{i j}$ or $\tau^{i j k}$ in $\Sigma(e)$, which correspond to the actions $\alpha_{i j}$ or $\tau$ mentioned above, have no pre-condition elements in common.
(ii) We have

$$
g_{i j}^{\prime}=\prod_{k=1}^{j-1} i d\left|\operatorname{dec}\left(e_{i j}^{\prime}\right)\right| \prod_{k=j+1}^{n_{i}} i d
$$

where $e_{i j}-\alpha \rightarrow \operatorname{dec}\left(e_{i j}^{\prime}\right)$. Therefore

$$
\forall j \neq k, \forall x \in g_{i j}^{\prime}, \quad y \in g_{i k}^{\prime}, \quad x \neq y
$$

and

$$
G_{i j}^{\prime} \cap G_{i k}^{\prime}=\emptyset .
$$

This shows that the events $\alpha^{i j}$ or $r^{i j k}$ have no post-condition elements in common. It follows then that these events can fire concurrently in $\Sigma(e)$, by combining (i) and (ii).
(iii) $\forall l \neq j, \forall h, k$

$$
G_{l h} \cap G_{j k} \neq \emptyset
$$

This shows that the events of $\Sigma(e)$, which correspond to actions of different $e_{i}$ 's cannot fire concurrently.

Now we can conclude by combining (i)-(iii) that in Case 2.2 the event firings within a step in $\Sigma(e)$ are in a one-to-one correspondence to the one step derivations of $e$.

It is now easy to prove the conclusion by induction for a derivation sequence consisting of any number of steps.

Proof of Theorem 5.7. Let $\left(e_{1}, e_{2}\right) \in S B, R_{1} \in P R_{1}$, with finitely many pages. Then $R_{1}$ must be an exact simulation of a run $A_{1}$ of $\Sigma\left(e_{1}\right)$, starting from its initial marking $M_{1}$. Assume that $A_{1}$ consists of the steps $B_{11}, B_{12}, \ldots, B_{1 n}$. It follows from Lemma 5.8 that $A_{1}$ corresponds to a derivation sequence of $e_{1}$

$$
\begin{equation*}
\left(e_{1}=\right) e_{11} \rightarrow e_{12} \rightarrow e_{13} \rightarrow \cdots \rightarrow e_{1, n+1} . \tag{67}
\end{equation*}
$$

It corresponds by bisimulation to the following derivation sequence

$$
\begin{equation*}
\left(e_{2}=\right) e_{21} \rightarrow e_{22} \rightarrow e_{23} \rightarrow \cdots \rightarrow e_{2, n+1} . \tag{68}
\end{equation*}
$$

By Lemma 5.8, this corresponds again to a run $A_{2}$ of $\Sigma\left(e_{2}\right)$, which consists of steps $B_{21}, B_{22}, \ldots, B_{2 n}$. Let $R_{2}$ be a NP/R net which is an exact simulation of $A_{2}$ and is constructed according to the way of Theorem 2.16. Clearly $R_{2}$ is finite.

At first, we will show that $R_{1}$ is b-isomorph to $R_{2}$. Let ( $S^{1}, T^{1}, F^{1}$ ) and ( $S^{2}, T^{2}, F^{2}$ ) be occurrence representations of $R_{1}$ and $R_{2}$ as it is prescribed in Definition 2.6(a). Then it follows from Definition 2.15 and Theorem 2.16, that there exist two bi-unique mappings

$$
\beta_{1}: \operatorname{ev}\left(A_{1}\right) \rightarrow T^{1}, \quad \beta_{2}: \operatorname{ev}\left(A_{2}\right) \rightarrow T^{2} .
$$

From Lemma 5.8 and the bisimulation relation between $e_{1}$ and $e_{2}$ we know that there is also a onc-to-one correspondence between event occurrences of $\operatorname{ev}\left(A_{1}\right)$ and $\operatorname{ev}\left(A_{2}\right)$. Denote it by $\psi$, then

$$
\beta_{2} \circ \psi \circ \beta_{1}^{-1}: T^{1} \rightarrow T^{2}
$$

is a one-to-one correspondence between events of $R_{1}$ and $R_{2}$.
The event occurrences $x$ of $\operatorname{ev}\left(A_{1}\right)$ take the form of $\left(G-\alpha \rightarrow G^{\prime}\langle i\rangle\right)$. From Corollary 2.7 we know that the $\beta_{1}(x)$ 's take the form ( $G-\alpha \rightarrow G^{\prime}$ ) [j]. Similar conclusions are valid for $\operatorname{ev}\left(A_{2}\right)$ and $\beta_{2}$. Then, again based on Lemma 5.8 and bisimulation of $e_{1}, e_{2}$, we conclude

$$
\beta_{2} \circ \psi \circ \beta_{1}^{-1}\left(\left(G_{1}-\alpha \rightarrow G_{1}^{\prime}\right)[i]\right)=G_{2}-\alpha \rightarrow G_{2}^{\prime}[j]
$$

where $G_{u}-\alpha \rightarrow G_{u}^{\prime}$ is an event of $\Sigma\left(e_{u}\right)(u=1,2)$. By taking 3) of Definition 2.15 into consideration, we know that for arbitrary $t_{1}, t_{1}^{\prime} \in \operatorname{ev}\left(A_{1}\right)$ the following is true:

$$
\beta_{1}\left(t_{1}\right)<\beta_{1}\left(t_{1}^{\prime}\right) \Leftrightarrow \beta_{2} \circ \psi\left(t_{1}\right)<\beta_{2} \circ \psi\left(t_{1}^{\prime}\right),
$$

where $\Leftrightarrow$ means "if and only if".
This shows that $R_{1}$ is b-isomorph to $R_{2}$.

Now assume that $R_{1}^{\prime}$ is a successor of $R_{1}$ and has finitely many pages. Assume further that $R_{1}^{\prime \prime}$ is the concatenation of $R_{1}$ and $R_{1}^{\prime}$. From Definition 5.4 we know that $R_{1}^{\prime \prime}$ belongs to the proper set of NP/R nets over $\Sigma\left(e_{1}\right)$. It corresponds to a run $A_{1}^{\prime \prime}$ of $\Sigma\left(e_{1}\right)$, namely,

$$
B_{11}, B_{12}, \ldots, B_{1 n}, B_{1, n+1}, \ldots, B_{1, m}, \quad m>n
$$

and thus to a derivation sequence of $e_{1}$ :

$$
\left(e_{1}=\right) e_{11} \rightarrow e_{12} \rightarrow e_{13} \rightarrow \cdots \rightarrow e_{1, n+1} \rightarrow \cdots \rightarrow e_{1, m}
$$

and thus to a derivation sequence of $e_{2}$ :

$$
\left(e_{2}=\right) e_{21} \rightarrow e_{22} \rightarrow e_{23} \rightarrow \cdots \rightarrow e_{2, n+1} \rightarrow \cdots \rightarrow e_{2, m}
$$

and thus to a run $A_{2}^{\prime \prime}$ of $\Sigma\left(e_{2}\right)$ :

$$
B_{21}, B_{22}, \ldots, B_{2 n}, B_{2, n+1}, \ldots, B_{2, m}
$$

Note that $A_{2}$ is a subrun of $A_{2}^{\prime \prime}$.
Construct a NP/R net $R_{2}^{\prime}$ which is an exact simulation of the step sequence $B_{2, n+1}, \ldots, B_{2, m}$ by using the algorithm given in Theorem 2.16. $R_{2}^{\prime}$ has also finitely many pages. Based on the same way of reasoning we can show that $R_{2}^{\prime}$ is b-isomorph to $R_{1}^{\prime}$. Let

$$
\begin{aligned}
& \Sigma\left(e_{1}\right)=\left(S_{1}, T_{1}, F_{1}, C_{1}, M_{1}\right), \\
& \Sigma\left(e_{2}\right)=\left(S_{2}, T_{2}, F_{2}, C_{2}, M_{2}\right) ;
\end{aligned}
$$

where

$$
\begin{aligned}
& \left(M_{1}=\right) M_{11}\left[B_{11}>M_{12} \cdots M_{1 n}\left[B_{1 n}\right\rangle M_{1, n+1},\right. \\
& \left(M_{2}=\right) M_{21}\left[B_{21}\right\rangle M_{22} \cdots M_{2 n}\left[B_{2 n}\right\rangle M_{2, n+1}, \\
& \Sigma^{\prime}\left(e_{1}\right)=\left(S_{1}, T_{1}, F_{1}, C_{1}, M_{1, n+1}\right) \\
& \Sigma^{\prime}\left(e_{2}\right)=\left(S_{2}, T_{2}, F_{2}, C_{2}, M_{2, n+1}\right) .
\end{aligned}
$$

Apply the same proof procedure which has been applied to $e_{1}, e_{2}, \Sigma\left(e_{1}\right), \Sigma\left(e_{2}\right)$, to $e_{1, n+1}, e_{2, n+1}, \Sigma^{\prime}\left(e_{1}\right), \Sigma^{\prime}\left(e_{2}\right)$, we can obtain similar conclusions. Continuc this process for arbitrary $n$ and we complete the proof of the theorem in one direction. The proof of the other direction is similar and is thus omitted here.

Corollary 5.9. Let $e_{1}$ and $e_{2}$ be two arbitrary CCS agents, $N\left(e_{1}\right)$ and $N\left(e_{2}\right)$ be their normal forms (not necessary unique), $\Sigma\left(N\left(e_{1}\right)\right)$ and $\Sigma\left(N\left(e_{2}\right)\right)$ be the corresponding $A C / E N$ systems. Then $\left(e_{1}, e_{2}\right) \in S B$, if and only if $\left(P R_{1}, P R_{2}\right) \in B S$, where $P R_{1}$ and $P R_{2}$ are the proper sets of $N P / R$ nets over $\Sigma\left(N\left(e_{1}\right)\right)$ and $\Sigma\left(N\left(e_{2}\right)\right)$, respectively.

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