# Permanence of a delayed SIR epidemic model with density dependent birth rate 

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#### Abstract

In this paper, we consider the permanence of a modified delayed SIR epidemic model with density dependent birth rate which is proposed in [M. Song, W. Ma, Asymptotic properties of a revised SIR epidemic model with density dependent birth rate and time delay, Dynamic of Continuous, Discrete and Impulsive Systems, 13 (2006) 199-208]. It is shown that global dynamic property of the modified delayed SIR epidemic model is very similar as that of the model in [W. Ma, Y. Takeuchi, T. Hara, E. Beretta, Permanence of an SIR epidemic model with distributed time delays, Tohoku Math. J. 54 (2002) 581-591; W. Ma, M. Song, Y. Takeuchi, Global stability of an SIR epidemic model with time delay, Appl. Math. Lett. 17 (2004) 1141-1145].


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## 1. Introduction

Epidemic models with or without time delay are studied by many authors (see, for example, for the model with time delay $[1,2,11-13,15]$, for one without time delay $[7,9,10,14]$ ). They consider the stability or permanence of the models by applying the theory on delay differential equations [3-6,8]. In this paper, we consider the permanence of the following modified delayed SIR epidemic model with density dependent birth rate which is proposed in [13],

$$
\left\{\begin{array}{l}
\dot{S}(t)=-\beta S(t) I(t-h)-\mu_{1} S(t)+b\left(1-\beta_{1} \frac{N(t)}{1+N(t)}\right),  \tag{1.1}\\
\dot{I}(t)=\beta S(t) I(t-h)-\mu_{2} I(t)-\lambda I(t), \\
\dot{R}(t)=\lambda I(t)-\mu_{3} R(t),
\end{array}\right.
$$

where $S(t)+I(t)+R(t) \equiv N(t)$ denotes the number of a population at time $t ; S(t), I(t)$ and $R(t)$ denote the numbers of susceptible members to the disease, of infective members and of members who have been removed from the possibility

[^0]of infection through full immunity, respectively. It is assumed that all newborns are susceptible. The positive constants $\mu_{1}, \mu_{2}$ and $\mu_{3}$ represent the death rates of susceptibles, infectives and recovered, respectively. It is natural biologically to assume that $\mu_{1} \leqslant \min \left\{\mu_{2}, \mu_{3}\right\}$. The positive constants $b$ and $\lambda$ represent the birth rate of the population and the recovery rate of infectives, respectively. The constant $\beta_{1}\left(0 \leqslant \beta_{1}<1\right)$ reflects the relation between the birth rate and the density of population. The nonnegative constant $h$ is the time delay.

The initial condition of (1.1) is given as

$$
\begin{equation*}
S(\theta)=\varphi_{1}(\theta), \quad I(\theta)=\varphi_{2}(\theta), \quad R(\theta)=\varphi_{3}(\theta) \quad(-h \leqslant \theta \leqslant 0), \tag{1.2}
\end{equation*}
$$

where $\varphi=\left(\varphi_{1}, \varphi_{2}, \varphi_{3}\right)^{\mathrm{T}} \in C$, such that $\varphi_{i}(\theta) \geqslant 0(-h \leqslant \theta \leqslant 0, i=1,2,3) . C$ denotes the Banach space $C\left([-h, 0], \mathscr{R}^{3}\right)$ of continuous functions mapping the interval $[-h, 0]$ into $\mathscr{R}^{3}$. By a biological meaning, we further assume that $\varphi_{i}(0)>0$ for $i=1,2,3$. It is easily to show that the solution $(S(t), I(t), R(t))$ of (1.1) with the initial condition (1.2) exists for all $t \geqslant 0$ and is unique and positive for all $t \geqslant 0$.

With some simple computation, we see that (1.1) always has a disease free equilibrium (i.e., boundary equilibrium) $E_{0}=\left(S_{0}, 0,0\right)$, where

$$
S_{0}=\frac{1}{2 \mu_{1}}\left[b\left(1-\beta_{1}\right)-\mu_{1}+\sqrt{\left[b\left(1-\beta_{1}\right)-\mu_{1}\right]^{2}+4 \mu_{1} b}\right] .
$$

Furthermore, if

$$
\begin{equation*}
S_{0}>S^{*} \equiv \frac{\mu_{2}+\lambda}{\beta} \tag{1.3}
\end{equation*}
$$

then (1.1) also has an endemic equilibrium (i.e., interior equilibrium) $E_{+}=\left(S^{*}, I^{*}, R^{*}\right)$, where

$$
\begin{aligned}
& I^{*}=-P+\frac{\sqrt{P^{2}-4 \beta S^{*} W Q}}{2 \beta S^{*} W}, \quad R^{*}=\frac{\lambda I^{*}}{\mu_{3}}, \\
& W=1+\frac{\lambda}{\mu_{3}}>0, \\
& P=\left[\mu_{1} S^{*}-b\left(1-\beta_{1}\right)\right] W+\beta S^{*}\left(1+S^{*}\right), \\
& Q=\left[\mu_{1} S^{*}-b\left(1-\beta_{1}\right)\right]\left(1+S^{*}\right)-b \beta_{1}<0 .
\end{aligned}
$$

A detailed analysis on the local asymptotic stability of $E_{0}$ and $E_{+}$, and the global asymptotic stability of $E_{0}$ are given in [13]. The purpose of the paper is to consider the permanence of (1.1) with the initial condition (1.2).

## 2. Permanence of (1.1)

In this section, we always assume that $S_{0}>S^{*}$ which ensures the existence of the endemic equilibrium $E_{+}$of (1.1). The following lemma is proved in [13].

Lemma 2.1. For any solution $(S(t), I(t), R(t))$ of (1.1) with (1.2), we have that

$$
\begin{equation*}
\limsup _{t \rightarrow+\infty} N(t) \leqslant S_{0} . \tag{2.1}
\end{equation*}
$$

We also have the following
Lemma 2.2. For any solution $(S(t), I(t), R(t))$ of (1.1) with (1.2), it has that

$$
\begin{equation*}
\liminf _{t \rightarrow+\infty} S(t) \geqslant \frac{b\left(1-\beta_{1}\right)}{\beta S_{0}+\mu_{1}} \equiv v_{1} . \tag{2.2}
\end{equation*}
$$

Proof. For any sufficiently small $\varepsilon>0$, from Lemma 2.1, there exists a large $t_{1}>0$ such that for $t \geqslant t_{1}, I(t) \leqslant S_{0}+\varepsilon$. Hence, for $t \geqslant t_{1}+h$,

$$
\begin{aligned}
\dot{S}(t) & \geqslant-\beta S(t)\left(S_{0}+\varepsilon\right)-\mu_{1} S(t)+b\left(1-\beta_{1}\right) \\
& =-\left[\beta\left(S_{0}+\varepsilon\right)+\mu_{1}\right] S(t)+b\left(1-\beta_{1}\right),
\end{aligned}
$$

which clearly implies that

$$
\liminf _{t \rightarrow+\infty} S(t) \geqslant \frac{b\left(1-\beta_{1}\right)}{\beta\left(S_{0}+\varepsilon\right)+\mu_{1}}=v_{1} .
$$

Note that $\varepsilon$ may be arbitrarily small. It has that (2.2) holds. This completes the proof of Lemma 2.2.
The following Lemma 2.3 plays an important role for the permanence of (1.1).
Lemma 2.3. For any solution $(S(t), I(t), R(t))$ of (1.1) with (1.2), it has that

$$
\liminf _{t \rightarrow+\infty} I(t) \geqslant \rho I^{*} \mathrm{e}^{-\left(\mu_{2}+\lambda\right)(d+h)} \equiv v_{2}
$$

where $\rho>0$ and $d>0$ satisfy

$$
q \equiv \frac{1}{\rho \beta I^{*}+\mu_{1}}\left(b\left(1-\beta_{1}\right)+\frac{b \beta_{1}}{1+S_{0}+\varepsilon_{0}}\right)>S^{*}
$$

and

$$
S^{4} \equiv q\left(1-\mathrm{e}^{-\left(\rho \beta I^{*}+\mu_{1}\right) d}\right)>S^{*},
$$

respectively. $\varepsilon_{0}>0$ satisfies

$$
\begin{equation*}
\frac{1}{\mu_{1}}\left(b\left(1-\beta_{1}\right)+\frac{b \beta_{1}}{1+S_{0}+\varepsilon_{0}}\right)>S^{*} . \tag{2.3}
\end{equation*}
$$

Proof. First, note that since $S_{0}$ satisfies

$$
S_{0}=\frac{1}{\mu_{1}}\left(b-\frac{b \beta_{1} S_{0}}{1+S_{0}}\right)>S^{*},
$$

it is possible to choose $\varepsilon_{0}>0$ satisfying (2.3). Hence, there exist $\rho>0$ and $d>0$ such that $q>S^{*}$ and $S^{\Delta}>S^{*}$ hold.
Let us consider any solution $(S(t), I(t), R(t))$ of (1.1) with (1.2). For $t \geqslant 0$, we define a differentiable function $V(t)$ as follows:

$$
\begin{equation*}
V(t)=I(t)+\beta S^{*} \int_{t-h}^{t} I(u) \mathrm{d} u . \tag{2.4}
\end{equation*}
$$

Then, the derivative of $V(t)$ along the solution of (1.1) with (1.2) satisfies

$$
\begin{align*}
\dot{V}(t) & =\dot{I}(t)+\beta S^{*} I(t)-\beta S^{*} I(t-h) \\
& =\beta\left(S(t)-S^{*}\right) I(t-h)+\left[\beta S^{*}-\left(\mu_{2}+\lambda\right)\right] I(t) \\
& =\beta\left(S(t)-S^{*}\right) I(t-h) . \tag{2.5}
\end{align*}
$$

From Lemma 2.1, there is some $t_{0}>0$ such that for any $t \geqslant t_{0}$, it has that

$$
N(t) \leqslant S_{0}+\varepsilon_{0} .
$$

Claim. It is impossible that for all large t, it has that

$$
I(t) \leqslant \rho I^{*} .
$$

In fact, if the claim is not true, there exists $t^{*} \geqslant t_{0}$ such that for any $t \geqslant t^{*}$, it has that

$$
I(t) \leqslant \rho I^{*} .
$$

Hence, it follows from the first equation of (1.1) that, for any $t \geqslant t^{*}+h$,

$$
\begin{aligned}
\dot{S}(t) & =-\beta S(t) I(t-h)-\mu_{1} S(t)+b\left(1-\beta_{1}\right)+\frac{b \beta_{1}}{1+N(t)} \\
& \geqslant-\left(\beta \rho I^{*}+\mu_{1}\right) S(t)+b\left(1-\beta_{1}\right)+\frac{b \beta_{1}}{1+S_{0}+\varepsilon_{0}} .
\end{aligned}
$$

Thus, it has that, for any $t \geqslant t^{*}+h+d$,

$$
\begin{align*}
S(t) & \geqslant S\left(t^{*}+h\right) \mathrm{e}^{-\left(\beta \rho I^{*}+\mu_{1}\right)\left(t-t^{*}-h\right)}+\left(b\left(1-\beta_{1}\right)+\frac{b \beta_{1}}{1+S_{0}+\varepsilon_{0}}\right) \int_{t^{*}+h}^{t} \mathrm{e}^{-\left(\beta \rho I^{*}+\mu_{1}\right)(t-\theta)} \mathrm{d} \theta \\
& >\frac{1}{\beta \rho I^{*}+\mu_{1}}\left(b\left(1-\beta_{1}\right)+\frac{b \beta_{1}}{1+S_{0}+\varepsilon_{0}}\right)\left(1-\mathrm{e}^{-\left(\beta \rho I^{*}+\mu_{1}\right)\left(t-t^{*}-h\right)}\right) \\
& \geqslant \frac{1}{\beta \rho I^{*}+\mu_{1}}\left(b\left(1-\beta_{1}\right)+\frac{b \beta_{1}}{1+S_{0}+\varepsilon_{0}}\right)\left(1-\mathrm{e}^{-\left(\beta \rho I^{*}+\mu_{1}\right) d}\right) \\
& =q\left(1-\mathrm{e}^{-\left(\rho \beta I^{*}+\mu_{1}\right) d}\right) \\
& =S^{\Delta}>S^{*} . \tag{2.6}
\end{align*}
$$

Therefore, from (2.5) and (2.6), we have that, for any $t \geqslant t^{*}+d+h$,

$$
\begin{aligned}
\dot{V}(t) & =\beta\left(S(t)-S^{*}\right) I(t-h) \\
& >\beta\left(S^{4}-S^{*}\right) I(t-h) .
\end{aligned}
$$

Set

$$
\underline{i}=\min _{\theta \in[-h, 0]} I\left(t^{*}+d+2 h+\theta\right)>0
$$

Now, we show that $I(t) \geqslant \underline{i}$ for all $t \geqslant t^{*}+d+h$.
In fact, if there is a $T \geqslant 0$ such that $I(t) \geqslant \underline{i}$ for $t^{*}+d+h \leqslant t \leqslant t^{*}+d+2 h+T, I\left(t^{*}+d+2 h+T\right)=\underline{i}$ and $\dot{I}\left(t^{*}+d+2 h+T\right) \leqslant 0$, it has from the second equation of (1.1) and (2.6) that, for $t=t^{*}+d+2 h+T$,

$$
\begin{aligned}
\dot{I}(t) & \geqslant\left[\beta S(t)-\left(\mu_{2}+\lambda\right)\right] \underline{i} \\
& >\beta\left[S^{\Delta}-S^{*}\right] \underline{i} \\
& >0 .
\end{aligned}
$$

This is a contradiction to $\dot{I}\left(t^{*}+d+2 h+T\right) \leqslant 0$. Thus, $I(t) \geqslant \underline{i}$ for all $t \geqslant t^{*}+d+h$.
Therefore, for all $t \geqslant t^{*}+d+h$,

$$
\dot{V}(t)>\beta\left(S^{4}-S^{*}\right) \underline{i},
$$

which implies that $V(t) \rightarrow+\infty$ as $t \rightarrow+\infty$. On the other hand, from Lemma 2.1 and (2.4), there exists a sufficiently large $\bar{T}>0$ such that, for $t \geqslant \bar{T}$,

$$
V(t) \leqslant S_{0}+1+\beta S^{*} h\left(1+S_{0}\right) .
$$

This is a contradiction to $V(t) \rightarrow+\infty$ as $t \rightarrow+\infty$. Hence, the claim is proved.

In the rest, we are left to consider two cases.
(i) $I(t) \geqslant \rho I^{*}$ for all large $t$.
(ii) $I(t)$ oscillates about $\rho I^{*}$ for all large $t$.

We show that $I(t) \geqslant \rho I^{*} \mathrm{e}^{-\left(\mu_{2}+\lambda\right)(d+h)}=v_{2}$ for all large $t$. Clearly, we only need to consider the case (ii). Let $t_{1}$ and $t_{2}$ be sufficiently large such that $t^{*}<t_{1}<t_{2}$,

$$
\begin{aligned}
& I\left(t_{1}\right)=I\left(t_{2}\right)=\rho I^{*} \\
& I(t)<\rho I^{*} \quad\left(t_{1}<t<t_{2}\right) .
\end{aligned}
$$

If $t_{2}-t_{1} \leqslant d+h$, from the second equation of (1.1), we have that

$$
\dot{I}(t)>-\left(\mu_{2}+\lambda\right) I(t)
$$

which implies that, for $t \in\left(t_{1}, t_{2}\right)$,

$$
I(t)>I\left(t_{1}\right) \mathrm{e}^{-\left(\mu_{2}+\lambda\right)\left(t-t_{1}\right)} .
$$

It is obvious that, for $t_{1}<t<t_{2}$,

$$
I(t)>\rho I^{*} \mathrm{e}^{-\left(\mu_{2}+\lambda\right)(d+h)}=v_{2} .
$$

If $t_{2}-t_{1}>d+h$, we can easily obtain that $I(t) \geqslant v_{2}$ for $t \in\left[t_{1}, t_{1}+d+h\right]$. Then, proceeding exactly as the proof for the above claim, we can show that $I(t) \geqslant v_{2}$ for $t_{1}+d+h \leqslant t \leqslant t_{2}$.

In fact, if not, there exists a $T^{*} \geqslant 0$ such that $I(t) \geqslant v_{2}$ for $t_{1} \leqslant t \leqslant t_{1}+d+h+T^{*} \leqslant t_{2}, I\left(t_{1}+d+h+T^{*}\right)=v_{2}$ and $\dot{I}\left(t_{1}+d+h+T^{*}\right) \leqslant 0$. On the other hand, it has that, for $t_{1} \leqslant t \leqslant t_{1}+d+h+T^{*} \leqslant t_{2}$,

$$
I(t) \leqslant \rho I^{*} .
$$

Then, it has from the first equation of (1.1) that, for $t_{1}+h \leqslant t \leqslant t_{1}+d+h+T^{*} \leqslant t_{2}$,

$$
\begin{aligned}
\dot{S}(t) & =-\beta S(t) I(t-h)-\mu_{1} S(t)+b\left(1-\beta_{1}\right)+\frac{b \beta_{1}}{1+N(t)} \\
& \geqslant-\left(\beta \rho I^{*}+\mu_{1}\right) S(t)+b\left(1-\beta_{1}\right)+\frac{b \beta_{1}}{1+S_{0}+\varepsilon_{0}}
\end{aligned}
$$

which implies that, for $t_{1}+d+h \leqslant t \leqslant t_{1}+d+h+T^{*} \leqslant t_{2}$,

$$
\begin{align*}
S(t) & \geqslant S\left(t_{1}+h\right) \mathrm{e}^{-\left(\beta \rho I^{*}+\mu_{1}\right)\left(t-t_{1}-h\right)}+\left(b\left(1-\beta_{1}\right)+\frac{b \beta_{1}}{1+S_{0}+\varepsilon_{0}}\right) \int_{t_{1}+h}^{t} \mathrm{e}^{-\left(\beta \rho I^{*}+\mu_{1}\right)(t-\theta)} \mathrm{d} \theta \\
& >\frac{1}{\beta \rho I^{*}+\mu_{1}}\left(b\left(1-\beta_{1}\right)+\frac{b \beta_{1}}{1+S_{0}+\varepsilon_{0}}\right)\left(1-\mathrm{e}^{-\left(\beta \rho I^{*}+\mu_{1}\right)\left(t-t_{1}-h\right)}\right) \\
& \geqslant \frac{1}{\beta \rho I^{*}+\mu_{1}}\left(b\left(1-\beta_{1}\right)+\frac{b \beta_{1}}{1+S_{0}+\varepsilon_{0}}\right)\left(1-\mathrm{e}^{-\left(\beta \rho I^{*}+\mu_{1}\right) d}\right) \\
& =q\left(1-\mathrm{e}^{-\left(\beta \rho I^{*}+\mu_{1}\right) d}\right) \\
& =S^{4}>S^{*} . \tag{2.7}
\end{align*}
$$

Thus, it has from the second equation of (1.1) and (2.7) that, for $t=t_{1}+d+h+T^{*}$,

$$
\begin{aligned}
\dot{I}(t) & =\beta S(t) I(t-h)-\mu_{2} I(t)-\lambda I(t) \\
& \geqslant\left[\beta S(t)-\left(\mu_{2}+\lambda\right)\right] v_{2} \\
& >\beta\left[S^{4}-S^{*}\right] v_{2} \\
& >0 .
\end{aligned}
$$

This is a contradiction to $\dot{I}\left(t_{1}+d+h+T^{*}\right) \leqslant 0$. Therefore, we have that $I(t) \geqslant v_{2}$ for $t \in\left[t_{1}, t_{2}\right]$. Since this kind of interval $\left[t_{1}, t_{2}\right]$ is chosen in an arbitrary way, we conclude that $I(t) \geqslant v_{2}$ for all large $t$ in the case (ii). Hence, it has that

$$
\liminf _{t \rightarrow+\infty} I(t) \geqslant v_{2} .
$$

The proof of Lemma 2.3 is completed.
Theorem 2.4. If $S_{0}>S^{*}$, then, (1.1) is permanent for any time delay $h$.
Proof. Lemma 2.1 shows that the solution $(S(t), I(t), R(t))$ of (1.1) is uniformly ultimately bounded. Lemmas 2.2-2.3 show that $S(t)$ and $I(t)$ are ultimately strictly positive with some positive constants. Furthermore, it follows from the third equation of (1.1) and Lemma 2.3 that $\lim \inf _{t \rightarrow+\infty} R(t) \geqslant\left(\lambda v_{2}\right) / \mu_{3}$. Hence, (1.1) is permanent. This proves Theorem 2.4.

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